

GNSS-SDR

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Chapter 1

GNSS-SDR



Figure 1.1 GNSS-SDR logo

Welcome to GNSS-SDR!

GNSS-SDR is an open-source [GNSS software receiver](#) freely available to the research community. This project provides a common framework for GNSS signal processing which can operate in a variety of computer platforms. This tool is intended to foster collaboration, increase awareness, and reduce development costs in the field of GNSS receiver design and customized use of GNSS signals.

For details about GNSS-SDR and using it, please see the [main project page](#) or browse [the source code at GitHub](#). You could be also interested in [subscribing to the mailing list](#).

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- [Overview](#)
- [Building GNSS-SDR](#)
- [Using GNSS-SDR](#)
- [Control plane](#)
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More details on GNSS-SDR signal processing blocks:

- [Signal Source](#)
- [Signal Conditioner](#)

- Channel
 - Acquisition
 - Tracking
 - Decoding of the navigation message
- Observables
- Computation of Position, Velocity and Time

1.2 Overview

GNSS-SDR provides an interface to different suitable RF front-ends and implements all the receiver chain up to the navigation solution. Its design allows any kind of customization, including interchangeability of signal sources, signal processing algorithms, interoperability with other systems, output formats, and offers interfaces to all the intermediate signals, parameters and variables. The goal is to write efficient and truly reusable code, easy to read and maintain, with fewer bugs, and producing highly optimized executables in a variety of hardware platforms and operating systems. In that sense, the challenge consists of defining a gentle balance within level of abstraction and performance. GNSS-SDR runs in a personal computer and provides interfaces through USB and Ethernet buses to a variety of either commercially available or custom-made RF front-ends, adapting the processing algorithms to different sampling frequencies, intermediate frequencies and sample resolutions. This makes possible rapid prototyping of specific receivers intended, for instance, to geodetic applications, observation of the ionospheric impact on navigation signals, GNSS reflectometry, signal quality monitoring, or carrier-phase based navigation techniques.

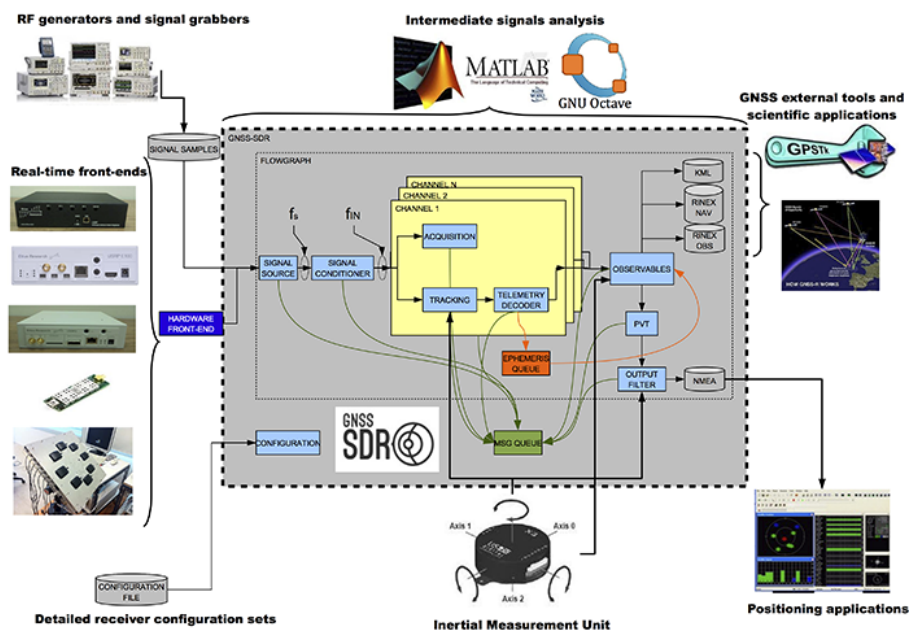


Figure 1.2 Overview

As signal inputs, it accepts:

- Raw data file captured with a data grabber (digitized at some intermediate frequency or directly at baseband).
- Any suitable RF configuration that can be driven by the Universal Software Radio Peripheral Hardware Driver (UHD). This includes all current and future Ettus Research products. The USRP1 + DBSRX 2.2 daughterboard is an example of working configuration for GPS L1 C/A and Galileo E1B and E1C signals.

- Experimentally, with some [USB DVB-T dongles based on the Realtek RTL2832U chipset](#).
- For mathematical representations of the targeted signals, check out the [Signal model](#) page.

As outputs, it provides:

- Dump of intermediate signals (configurable by the user)
- The processing is logged at a system temporary folder (usually, `/tmp`)
- Observables in form of RINEX file (experimental)
- Navigation message data in form of RINEX file
- Position, Velocity and Time solution in KML format and NMEA

1.3 Building GNSS-SDR

In principle, GNSS-SDR can be built in any Unix-like system. In practice, it depends on being able to install all the required dependencies. See the [building guide](#) page for details about the project's dependencies and build process. Mainly, it consists on installing [GNU Radio](#) plus some few more libraries:

- [Armadillo](#), a C++ linear algebra library,
- [Boost](#), a set of free peer-reviewed portable C++ source libraries,
- [Gflags](#), a library that implements commandline flags processing,
- [Glog](#), a library that implements application-level logging,
- [Googletest](#), Google's framework for writing C++ tests,
- [Mako](#), a template library written in Python,
- [Matio](#), a MATLAB MAT File I/O Library,
- [Protocol Buffers](#), a language-neutral, platform-neutral extensible mechanism for serializing structured data,
- [PugiXML](#), a light-weight, simple and fast XML parser for C++ with XPath support,
- [Volk](#), a Vector-Optimized Library of Kernels which provides an abstraction of optimized math routines targeting several SIMD processors,

and, optionally,

- GNU Radio modules for hardware interface ([gr-uhd](#), [gr-osmosdr](#), [gr-iio](#)),
- [Benchmark](#), a library to benchmark code snippets,
- [Gperftools](#), which provides fast, multi-threaded malloc() and performance analysis tools.

After all dependencies are installed, clone the GNSS-SDR repository:

```
$ git clone https://github.com/gnss-sdr/gnss-sdr
```

This will create a folder named `gnss-sdr` with the following structure:

```
|-gnss-sdr
|---cmake      <- CMake-related files
|---conf       <- Configuration files. Each file represents one receiver.
|---docs       <- Contains documentation-related files
|---install    <- Executables
|---src        <- Source code folder
|-----algorithms
|-----PVT
|-----acquisition
|-----channel
|-----conditioner
|-----data_type_adapter
|-----input_filter
|-----libs
|-----observables
|-----resampler
|-----signal_source
|-----telemetry_decoder
|-----tracking
|-----core
|-----interfaces
|-----libs
|-----receiver
|-----system_parameters
|-----main
|---tests
|---utils      <- some utilities (e.g. Matlab scripts)
```

You are now ready to build GNSS-SDR by using **CMake** as building tool:

```
$ cd gnss-sdr && mkdir build && cd build
$ cmake ..
$ make
```

If everything goes well, three new executables will be created at `gnss-sdr/install`, namely `gnss-sdr`, `volk_gnssdr_profile` and `run_tests`. You can run them from that folder, but if you prefer to install `gnss-sdr` on your system and have it available anywhere else, do:

```
$ sudo make install
```

This will make a copy of the `conf/` folder into `/usr/local/share/gnss-sdr/conf` for your reference. We suggest to create a working directory at your preferred location and store your own configuration and data files there.

You can create the documentation by doing:

```
$ make doc
```

from the building folder. In both cases, **Doxygen** will generate HTML documentation that can be retrieved pointing your browser of preference to `gnss-sdr/docs/html/index.html`.

There are two more extra targets available. In the building folder:

```
$ make doc-clean
```

will remove the content of previously-generated documentation and, if a LaTeX installation is detected in your system,

```
$ make pdfmanual
```

will create a PDF manual at `gnss-sdr/docs/GNSS-SDR_manual.pdf`. Please note that the PDF generation requires some fonts to be installed on the host system. In Ubuntu, those fonts do not come by default. You can install them by doing:

```
$ sudo apt install texlive-fonts-recommended
```

and then run `cmake ../` and `make pdfmanual` again.

1.3.1 Debug and Release builds

By default, CMake will build the Release version, meaning that the compiler will generate a faster, optimized executable. This is the recommended build type when using a RF front-end and you need to attain real time. If working with a file (and thus without real-time constraints), you may want to obtain more information about the internals of the receiver, as well as more fine-grained logging. This can be done by building the Debug version, by doing:

```
$ cd gnss-sdr && mkdir build-debug && cd build-debug
$ cmake -DCMAKE_BUILD_TYPE=Debug ..
$ make
```

1.3.2 Updating GNSS-SDR

If you checked out GNSS-SDR some days ago, it is possible that some developer had updated files at the Git repository. You can update your local copy by doing:

```
$ git checkout next
$ git pull https://github.com/gnss-sdr/gnss-sdr next
```

Before rebuilding the source code, it is safe (and recommended) to remove the remainders of old builds:

```
$ cd <building folder>
$ sudo make uninstall ; if you installed it before
$ rm -rf *
```

You can also check [The Git Book](#) for more information about Git usage.

1.4 Using GNSS-SDR

With GNSS-SDR, you can define your own receiver, work with captured raw data or from a RF front-end, dump into files intermediate signals, or tune every single algorithm used in the [Signal Processing plane](#). All the configuration is done in a single file. Those configuration files reside at the `gnss-sdr/conf` folder. By default, the executable `gnss-sdr` will read the configuration available at `gnss-sdr/conf/gnss-sdr.conf`. You can edit that file to fit your needs, or even better, define a new `my_receiver.conf` file with your own configuration. This new receiver can be done by invoking `gnss-sdr` with the `-config_file` flag pointing to your configuration file:

```
$ gnss-sdr --config_file=./conf/my_receiver.conf
```

You can see a guide of available implementations at [the online documentation](#). That folder contains other working examples as well. If you have a working configuration and want to share it with others, please email it to the [GNSS-SDR developers mailing list](#) and we will be happy to upload it to the server.

You can use a single configuration file for processing different data files, specifying the file to be processed with the `-signal_source` flag:

```
$ gnss-sdr --config_file=./conf/my_receiver.conf --signal_source=./my_captured_data.dat
```

This will override the `SignalSource.filename` specified in the configuration file.

You can get a complete list of available commandline flags by doing:

```
$ gnss-sdr --help
```

1.5 Control plane

GNSS-SDR's main method initializes the logging library, processes the command line flags, if any, provided by the user and instantiates a [ControlThread](#) object. Its constructor reads the configuration file, creates a control queue and creates a flowgraph according to the configuration. Then, the program's main method calls the `run()` method of the instantiated object, an action that connects the flowgraph and starts running it. After that, and until a stop message is received, it reads control messages sent by the receiver's modules through a safe-thread queue and processes them. Finally, when a stop message is received, the main method executes the destructor of the [ControlThread](#) object, which deallocates memory, does other cleanup and exits the program.

The [GNSSFlowgraph](#) class is responsible for preparing the graph of blocks according to the configuration, running it, modifying it during run-time and stopping it. Blocks are identified by its role. This class knows which roles it has to instantiate and how to connect them. It relies on the configuration to get the correct instances of the roles it needs and then it applies the connections between GNU Radio blocks to make the graph ready to be started. The complexity related to managing the blocks and the data stream is handled by GNU Radio's `gr::top_block` class. [GNSSFlowgraph](#) wraps the `gr::top_block` instance so we can take advantage of the [GNSS block factory](#), the configuration system and the processing blocks. This class is also responsible for applying changes to the configuration of the flowgraph during run-time, dynamically reconfiguring channels: it selects the strategy for selecting satellites. This can range from a sequential search over all the satellites' ID to smarter approaches that determine what are the satellites most likely in-view based on rough estimations of the receiver position in order to avoid searching satellites in the other side of the Earth.

The Control Plane is in charge of creating a flowgraph according to the configuration and then managing the modules. Configuration allows users to define in an easy way their own custom receiver by specifying the flowgraph (type of signal source, number of channels, algorithms to be used for each channel and each module, strategies for satellite selection, type of output format, etc.). Since it is difficult to foresee what future module implementations will be needed in terms of configuration, we used a very simple approach that can be extended without a major impact in the code. This can be achieved by simply mapping the names of the variables in the modules with the names of the parameters in the configuration.

1.5.1 Configuration

Properties are passed around within the program using the [ConfigurationInterface](#) class. There are two implementations of this interface: [FileConfiguration](#) and [InMemoryConfiguration](#). [FileConfiguration](#) reads the properties (pairs of property name and value) from a file and stores them internally. [InMemoryConfiguration](#) does not read from a file; it remains empty after instantiation and property values and names are set using the `set` property method. [FileConfiguration](#) is intended to be used in the actual GNSS-SDR application whereas [InMemoryConfiguration](#) is intended to be used in tests to avoid file-dependency in the file system. Classes that need to read configuration parameters will receive instances of [ConfigurationInterface](#) from where they will fetch the values. For instance, parameters related to `SignalSource` should look like this:

```
SignalSource.parameter1=value1
SignalSource.parameter2=value2
```

The name of these parameters can be anything but one reserved word: `implementation`. This parameter indicates in its value the name of the class that has to be instantiated by the factory for that role. For instance, if our signal source is providing data already at baseband and thus we want to use the implementation [Pass_Through](#) for module [SignalConditioner](#), the corresponding line in the configuration file would be

```
SignalConditioner.implementation=Pass_Through
```

Since the configuration is just a set of property names and values without any meaning or syntax, the system is very versatile and easily extendable. Adding new properties to the system only implies modifications in the classes that will make use of these properties. In addition, the configuration files are not checked against any strict syntax so it is always in a correct status (as long as it contains pairs of property names and values in [INI format](#)).

1.5.2 GNSS block factory

Hence, the application defines a simple accessor class to fetch the configuration pairs of values and passes them to a factory class called [GNSSBlockFactory](#). This factory decides, according to the configuration, which class needs to be instantiated and which parameters should be passed to the constructor. Hence, the factory encapsulates the complexity of blocks' instantiation. With that approach, adding a new block that requires new parameters will be as simple as adding the block class and modifying the factory to be able to instantiate it. This loose coupling between the blocks' implementations and the syntax of the configuration enables extending the application capacities in a high degree. It also allows to produce fully customized receivers, for instance a testbed for acquisition algorithms, and to place observers at any point of the receiver chain.

1.6 Signal Processing plane

GNU Radio's class `gr::basic_block` is the abstract base class for all signal processing blocks, a bare abstraction of an entity that has a name and a set of inputs and outputs. It is never instantiated directly; rather, this is the abstract parent class of both `gr::hier_block2`, which is a recursive container that adds or removes processing or hierarchical blocks to the internal graph, and `gr::block`, which is the abstract base class for all the processing blocks.

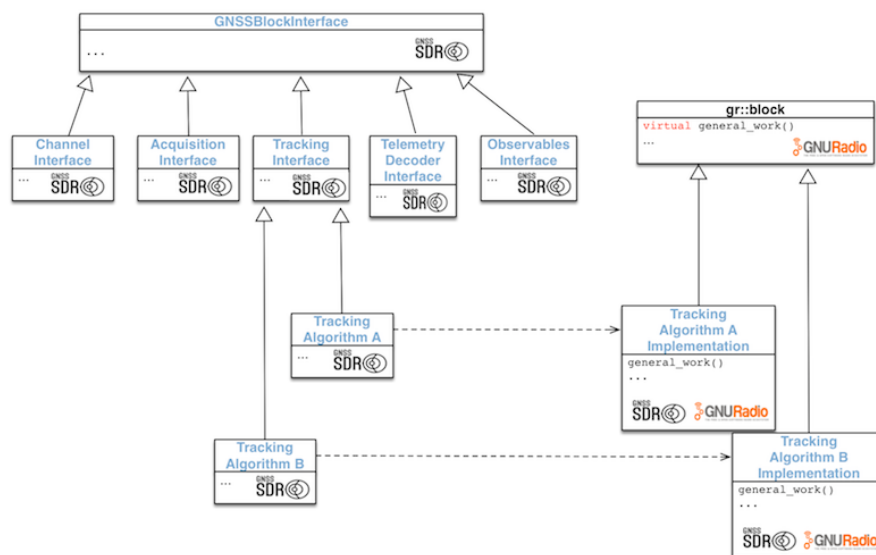


Figure 1.3 Class hierarchy of signal processing blocks

A signal processing flow is constructed by creating a tree of hierarchical blocks, which at any level may also contain terminal nodes that actually implement signal processing functions.

Class `gr::top_block` is the top-level hierarchical block representing a flowgraph. It defines GNU Radio run-time functions used during the execution of the program: `run()`, `start()`, `stop()`, `wait()`, etc. A subclass called [GNSSBlockInterface](#) is the common interface for all the GNSS-SDR modules. It defines pure virtual methods, that are required to be implemented by a derived class.

Subclassing [GNSSBlockInterface](#), we defined interfaces for the GNSS receiver blocks depicted in the figure above. This hierarchy provides the definition of different algorithms and different implementations, which will be instantiated according to the configuration. This strategy allows multiple implementations sharing a common interface, achieving the objective of decoupling interfaces from implementations: it defines a family of algorithms, encapsulates each one, and makes them interchangeable. Hence, we let the algorithm vary independently from the program that uses it.

1.6.1 Signal Source

The input of a software receiver are the raw bits that come out from the front-end's analog-to-digital converter (ADC). Those bits can be read from a file stored in the hard disk or directly in real-time from a hardware device through USB or Ethernet buses.

The Signal Source module is in charge of implementing the hardware driver, that is, the portion of the code that communicates with the RF front-end and receives the samples coming from the ADC. This communication is usually performed through USB or Ethernet buses. Since real-time processing requires a highly optimized implementation of the whole receiver, this module also allows to read samples from a file stored in a hard disk, and thus processing without time constraints. Relevant parameters of those samples are the intermediate frequency (or baseband I&Q components), the sampling rate and number of bits per sample, that must be specified by the user in the configuration file.

This module also performs bit-depth adaptation, since most of the existing RF front-ends provide samples quantized with 2 or 3 bits, while operations inside the processor are performed on 32- or 64-bit words, depending on its architecture. Although there are implementations of the most intensive computational processes (mainly correlation) that take advantage of specific data types and architectures for the sake of efficiency, the approach is processor-specific and hardly portable. We suggest to keep signal samples in standard data types and letting the compiler select the best library version (implemented using SIMD or any other processor-specific technology) of the required routines for a given processor.

Example: [FileSignalSource](#)

The user can configure the receiver for reading from a file, setting in the configuration file the data file location, sample format, and the sampling frequency and intermediate frequency at what the signal was originally captured.

```
;##### SIGNAL_SOURCE CONFIG #####
SignalSource.implementation=File_Signal_Source
SignalSource.filename=/home/user/gnss-sdr/data/my_capture.dat
SignalSource.item_type=gr_complex
SignalSource.sampling_frequency=4000000 ; Sampling frequency in [Hz]
SignalSource.freq=1575420000 ; RF front-end center frequency in [Hz]
```

Example: [UhdSignalSource](#)

The user may prefer to use a UHD-compatible RF front-end and try real-time processing. For instance, for a USRP1 + DBSRX daughterboard, use:

```
;##### SIGNAL_SOURCE CONFIG #####
SignalSource.implementation=UHD_Signal_Source
SignalSource.item_type=gr_complex
SignalSource.sampling_frequency=4000000 ; Sampling frequency in [Hz]
SignalSource.freq=1575420000 ; RF front-end center frequency in [Hz]
SignalSource.gain=60 ; Front-end gain in dB
SignalSource.subdevice=B:0 ; UHD subdevice specification (for USRP1 use A:0 or B:0)
```

Other examples are available at `gnss-sdr/conf`.

1.6.2 Signal Conditioner

The signal conditioner is in charge of resampling the signal and delivering a reference sample rate to the downstream processing blocks, acting as a facade between the signal source and the synchronization channels, providing a simplified interface to the input signal. In case of multiband front-ends, this module would be in charge of providing a separated data stream for each band.

1.6.3 Channel

A channel encapsulates all signal processing devoted to a single satellite. Thus, it is a large composite object which encapsulates the [Acquisition](#), [Tracking](#) and [Decoding of the navigation message](#) modules. As a composite object, it can be treated as a single entity, meaning that it can be easily replicated. Since the number of channels is selectable by the user in the configuration file, this approach helps improving the scalability and maintainability of the receiver.

This module is also in charge of managing the interplay between acquisition and tracking. Acquisition can be initialized in several ways, depending on the prior information available (called cold start when the receiver has no information about its position nor the satellites almanac; warm start when a rough location and the approximate time of day are available, and the receiver has a recently recorded almanac broadcast; or hot start when the receiver was tracking a satellite and the signal line of sight broke for a short period of time, but the ephemeris and almanac data is still valid, or this information is provided by other means), and an acquisition process can finish deciding that the satellite is not present, that longer integration is needed in order to confirm the presence of the satellite, or declaring the satellite present. In the latter case, acquisition process should stop and trigger the tracking module with coarse estimations of the synchronization parameters.

The abstract class [ChannelInterface](#) represents an interface to a channel GNSS block. Check [Channel](#) for an actual implementation.

1.6.3.1 Acquisition

The first task of a GNSS receiver is to detect the presence or absence of in-view satellites. This is done by the acquisition system process, which also provides a coarse estimation of two signal parameters: the frequency shift with respect to the nominal IF frequency, and a delay term which allows the receiver to create a local code aligned with the incoming code. [AcquisitionInterface](#) is the common interface for all the acquisition algorithms and their corresponding implementations. Algorithms' interface, that may vary depending on the use of information external to the receiver, such as in Assisted GNSS, is defined in classes referred to as *adapters*. These adapters wrap the GNU Radio blocks interface into a compatible interface expected by [AcquisitionInterface](#). This allows the use of existing GNU Radio blocks derived from `gr::block`, and ensures that newly developed implementations will also be reusable in other GNU Radio-based applications. Moreover, it adds still another layer of abstraction, since each given acquisition algorithm can have different implementations (for instance using different numerical libraries). In such a way, implementations can be continuously improved without having any impact neither on the algorithm interface nor the general acquisition interface.

Check [GpsL1CaPcpsAcquisition](#) and [GalileoE1PcpsAmbiguousAcquisition](#) for examples of adapters from a Parallel Code Phase Search (PCPS) acquisition block, and `pcps_acquisition_cc` for an example of a block implementation. The source code of all the available acquisition algorithms is located at:

```
| -gnss-sdr
| ---src
| ----algorithms
| -----acquisition
| -----adapters          <- Adapters of the processing blocks to an AcquisitionInterface
| -----gnuradio_blocks   <- Signal processing blocks implementation
```

The user can select a given implementation for the algorithm to be used in each receiver channel, as well as their parameters, in the configuration file:

```
##### ACQUISITION GLOBAL CONFIG #####

;#implementation: Acquisition algorithm selection for this channel:
Acquisition_1C.implementation=GPS_L1_CA_PCPS_Acquisition
;#dump: Enable or disable the acquisition internal data file logging [true] or [false]
Acquisition_1C.dump=false
;#filename: Log path and filename
Acquisition_1C.dump_filename=./acq_dump.dat
```

```
;#item_type: Type and resolution for each of the signal samples. Use only gr_complex in this version.
Acquisition_1C.item_type=gr_complex
;#coherent_integration_time_ms: Signal block duration for the acquisition signal detection [ms]
Acquisition_1C.coherent_integration_time_ms=1
;#threshold: Acquisition threshold
Acquisition_1C.threshold=2.5
;#pfa: Acquisition false alarm probability. This option overrides the threshold option.
Acquisition_1C.pfa=0.0001
;#doppler_max: Maximum expected Doppler shift [Hz]
Acquisition_1C.doppler_max=5000
;#doppler_step: Doppler step in the grid search [Hz]
Acquisition_1C.doppler_step=250
```

1.6.3.2 Tracking

When a satellite is declared present, the parameters estimated by the acquisition module are then fed to the receiver tracking module, which represents the second stage of the signal processing unit, aiming to perform a local search for accurate estimates of code delay and carrier phase, and following their eventual variations.

Again, a class hierarchy consisting of a [TrackingInterface](#) class and subclasses implementing algorithms provides a way of testing different approaches, with full access to their parameters. Check [GpsL1CaDlIPllTracking](#) or [GalileoE1DlIPllVemlTracking](#) for examples of adapters, and [Gps_L1_Ca_Dll_Pll_Tracking_cc](#) for an example of a signal processing block implementation. There are also available some useful classes and functions for signal tracking; take a look at Correlator, [lock_detectors.h](#), [tracking_discriminators.h](#) or [tracking_2nd_DLL_filter.h](#).

The source code of all the available tracking algorithms is located at:

```
| -gnss-sdr
| ---src
| ----algorithms
| -----tracking
| -----adapters          <- Adapters of the processing blocks to a TrackingInterface
| -----gnuradio_blocks    <- Signal processing blocks implementation
| -----libs               <- libraries of tracking objects (e.g. correlators, discriminators, and so on)
```

The user can select a given implementation for the algorithm to be used in all the tracking blocks, as well as its parameters, in the configuration file:

```
##### TRACKING GLOBAL CONFIG #####

;#implementation: Selected tracking algorithm
Tracking_1C.implementation=GPS_L1_CA_DLL_PLL_Tracking
;#item_type: Type and resolution for each of the signal samples.
Tracking_1C.item_type=gr_complex

;#dump: Enable or disable the Tracking internal binary data file logging [true] or [false]
Tracking_1C.dump=false

;#dump_filename: Log path and filename. Notice that the tracking channel will add "x.dat" where x is the channel
Tracking_1C.dump_filename=./tracking_ch_

;#pll_bw_hz: PLL loop filter bandwidth [Hz]
Tracking_1C.pll_bw_hz=50.0;

;#dll_bw_hz: DLL loop filter bandwidth [Hz]
Tracking_1C.dll_bw_hz=2.0;

;#fll_bw_hz: FLL loop filter bandwidth [Hz]
Tracking_1C.fll_bw_hz=10.0;

Tracking_1C.pll_filter_order=3 ; PLL loop filter order [2] or [3]
Tracking_1C.dll_filter_order=2 ; DLL loop filter order [1], [2] or [3]

;#early_late_space_chips: correlator early-late space [chips].
Tracking_1C.early_late_space_chips=0.5;
```

1.6.3.3 Decoding of the navigation message

Most of GNSS signal links are modulated by a navigation message containing the time the message was transmitted, orbital parameters of satellites (also known as ephemeris) and an almanac (information about the general system health, rough orbits of all satellites in the network as well as data related to error correction). Navigation data bits are structured in words, pages, subframes, frames and superframes. Sometimes, bits corresponding to a single parameter are spread over different words, and values extracted from different frames are required for proper decoding. Some words are for synchronization purposes, others for error control and others contain actual information. There are also error control mechanisms, from parity checks to forward error correction (FEC) encoding and interleaving, depending on the system.

The common interface is [TelemetryDecoderInterface](#). Check [GpsL1CaTelemetryDecoder](#) for an example of the GPS L1 NAV message decoding adapter, and `gps_l1_ca_telemetry_decoder_cc` for an actual implementation of a signal processing block. Configuration example:

```
##### TELEMETRY DECODER CONFIG #####
TelemetryDecoder_1C.implementation=Gps_L1_CA_Telemetry_Decoder
TelemetryDecoder_1C.dump=false
```

See the [Reference Documents](#) for more information about the signal format.

1.6.4 Observables

GNSS systems provide different kinds of observations. The most commonly used are the code observations, also called pseudoranges. The *pseudo* comes from the fact that on the receiver side the clock error is unknown and thus the measurement is not a pure range observation. High accuracy applications also use the carrier phase observations, which are based on measuring the difference between the carrier phase transmitted by the GNSS satellites and the phase of the carrier generated in the receiver. Both observables are computed from the outputs of the tracking module and the decoding of the navigation message. This module collects all the data provided by every tracked channel, aligns all received data into a coherent set, and computes the observables.

The common interface is [ObservablesInterface](#).

Configuration example:

```
##### OBSERVABLES CONFIG #####
Observables.implementation=Hybrid_Observables

#dump: Enable or disable the Observables internal binary data file logging [true] or [false]
Observables.dump=false

#dump_filename: Log path and filename.
Observables.dump_filename=./observables.dat
```

1.6.5 Computation of Position, Velocity and Time

Although data processing for obtaining high-accuracy PVT solutions is out of the scope of GNSS-SDR, we provide a module that can compute a simple least square solution and leaves room for more sophisticated positioning methods. The integration with libraries and software tools that are able to deal with multi-constellation data such as [GNSSTk](#) or [gLAB](#) appears as a viable solution for high performance, completely customizable GNSS receivers.

The common interface is [PvtInterface](#). For instance, in order to use the implementation `RTKLIB_PVT`, add to the configuration file:

```

;##### PVT CONFIG #####
PVT.implementation=RTKLIB_PVT

;#nmea_dump_filename: NMEA log path and filename
PVT.nmea_dump_filename=./gnss_sdr_pvt.nmea;

;#flag_nmea_tty_port: Enable or disable the NMEA log to a serial TTY port (Can be used with real hardware or v
PVT.flag_nmea_tty_port=true;

;#nmea_dump_devname: serial device descriptor for NMEA logging
PVT.nmea_dump_devname=/dev/pts/4

;#dump: Enable or disable the PVT internal binary data file logging [true] or [false]
PVT.dump=false

```

This implementation allows tuning of the following parameters:

```

PVT.implementation=RTKLIB_PVT
PVT.positioning_mode=Single      ; options: Single, Static, Kinematic, PPP_Static, PPP_Kinematic
PVT.iono_model=Broadcast        ; options: OFF, Broadcast
PVT.trop_model=Saastamoinen     ; options: OFF, Saastamoinen
PVT.rinex_version=2             ; options: 2 or 3
PVT.output_rate_ms=100         ; Period in [ms] between two PVT outputs
PVT.display_rate_ms=500        ; Position console print (std::out) interval [ms].
PVT.nmea_dump_filename=./gnss_sdr_pvt.nmea ; NMEA log path and filename
PVT.flag_nmea_tty_port=false    ; Enables the NMEA log to a serial TTY port
PVT.nmea_dump_devname=/dev/pts/4 ; serial device descriptor for NMEA logging
PVT.flag_rtcm_server=true       ; Enables or disables a TCP/IP server dispatching RTCM messages
PVT.flag_rtcm_tty_port=false    ; Enables the RTCM log to a serial TTY port
PVT.rtcm_dump_devname=/dev/pts/1 ; serial device descriptor for RTCM logging
PVT.rtcm_tcp_port=2101
PVT.rtcm_MT1019_rate_ms=5000
PVT.rtcm_MT1045_rate_ms=5000
PVT.rtcm_MT1097_rate_ms=1000
PVT.rtcm_MT1077_rate_ms=1000

```

1.7 About the software license

GNSS-SDR is released under the [General Public License \(GPL\) v3](#), thus securing practical usability, inspection, and continuous improvement by the research community, allowing the discussion based on tangible code and the analysis of results obtained with real signals. The GPL implies that:

- Copies may be distributed free of charge or for money, but the source code has to be shipped or provided free of charge (or at cost price) on demand. The receiver of the source code has the same rights meaning he can share copies free of charge or resell.
- The licensed material may be analyzed or modified.
- Modified material may be distributed under the same licensing terms but **do not** have to be distributed.

That means that modifications only have to be made available to the public if distribution happens. So it is perfectly fine to take the GNSS-SDR source code, modify it heavily and use it in a not distributed application / library. This is how companies like Google can run their own patched versions of Linux for example.

But what this also means is that non-GPL code cannot use GPL code. This means that you cannot modify / use GNSS-SDR, blend it with non-GPL code, and make money with the resulting software. You cannot distribute the resulting software under a non-disclosure agreement or contract. Distributors under the GPL also grant a license for any of their patents practiced by the software, to practice those patents in GPL software. You can sell a device that runs with GNSS-SDR, but if you distribute the code, it has to remain under GPL.

1.8 Publications and Credits

If you use GNSS-SDR to produce a research paper or Thesis, we would appreciate if you reference any of these articles to credit the GNSS-SDR project:

- C. Fernández-Prades, J. Arribas, L. Esteve, D. Pubill, P. Closas, *An Open Source Galileo E1 Software Receiver*, in Proc. of the 6th ESA Workshop on Satellite Navigation Technologies (NAVITEC 2012), ESTEC, Noordwijk, The Netherlands, Dec. 2012.
- J. Arribas, *GNSS Array-based Acquisition: Theory and Implementation*, PhD Thesis, Universitat Politècnica de Catalunya, Barcelona, Spain, June 2012.
- C. Fernández-Prades, J. Arribas, P. Closas, C. Avilés, and L. Esteve, *GNSS-SDR: an open source tool for researchers and developers*, in Proc. of the ION GNSS 2011 Conference, Portland, Oregon, Sept. 19-23, 2011.
- C. Fernández-Prades, C. Avilés, L. Esteve, J. Arribas, and P. Closas, *Design patterns for GNSS software receivers*, in Proc. of the 5th ESA Workshop on Satellite Navigation Technologies (NAVITEC'2010), ESTEC, Noordwijk, The Netherlands, Dec. 2010. DOI:10.1109/NAVITEC.2010.5707981

For LaTeX users, these are the BibTeX cites for your convenience:

```
@INPROCEEDINGS{GNSS-SDR12
  author = {C.~{Fern}\{a\}ndez--Prades} and J.~Arribas and L.~Esteve and D.~Pubill and P.~Closas},
  title = {An Open Source {G}alileo {E1} Software Receiver},
  booktitle = {Proc. of the 6th ESA Workshop on Satellite Navigation Technologies (NAVITEC'2012)},
  year = {2012},
  address = {ESTEC, Noordwijk, The Netherlands},
  month = {Dec.} }

@PHDTHESIS{Arribas12,
  author = {J.~Arribas},
  title = {{GNSS} Array-based Acquisition: Theory and Implementation},
  school = {Universitat Polit\`{e}cnica de Catalunya},
  year = {2012},
  address = {Barcelona, Spain},
  month = {June} }

@INPROCEEDINGS{GNSS-SDR11,
  AUTHOR = {C.~{Fern}\{a\}ndez--Prades} and J.~Arribas and P.~Closas and C.~Avil\{e\}s and L.~Esteve},
  TITLE = {{GNSS-SDR}: An Open Source Tool For Researchers and Developers},
  BOOKTITLE = {Proc. of the ION GNSS 2011 Conference},
  YEAR = {2011},
  address = {Portland, Oregon},
  month = {Sept.} }

@INPROCEEDINGS{GNSS-SDR10,
  AUTHOR = {C.~{Fern}\{a\}ndez--Prades} and C.~Avil\{e\}s and L.~Esteve and J.~Arribas and P.~Closas},
  TITLE = {Design patterns for {GNSS} software receivers},
  BOOKTITLE = {Proc. of the 5th ESA Workshop on Satellite Navigation Technologies (NAVITEC'2010)},
  YEAR = {2010},
  address = {ESTEC, Noordwijk, The Netherlands},
  month = {Dec.},
  note = {doi:10.1109/NAVITEC.2010.5707981} }
```

More papers related to GNSS-SDR are available at the [publications page](#).

1.9 Ok, now what?

In order to start using GNSS-SDR, you may want to populate `gnss-sdr/data` folder (or anywhere else on your system) with raw data files. By "raw data" we mean the output of a Radio Frequency front-end's Analog-to-Digital converter. GNSS-SDR needs signal samples already in baseband or in passband, at a suitable intermediate frequency (on the order of MHz). Prepare your configuration file, and then you are ready for going to the `gnss-sdr/install` folder, running `./gnss-sdr`, and see how the file is processed. Please ask the Developer Team for a signal sample if you need one, and they will do their best ;-)

Another interesting option is working in real-time with a RF front-end. We provide drivers for UHD-compatible hardware (see [Signal Source](#)) and for some DVB-T USB dongles. Start with a low number of channels and then increase it in order to test how many channels your processor can handle in real-time.

You can find more information at the [GNSS-SDR Documentation page](#) or directly asking to the [GNSS-SDR Developers mailing list](#).

You are also very welcome to contribute to the project, there are many ways to [participate in GNSS-SDR](#). If you need some special feature not yet implemented, the Developer Team would love to be hired for developing it. Please do not hesitate to [contact them](#).

Enjoy GNSS-SDR!

The Developer Team.

Chapter 2

Reference Documents

2.1 Interface Control Documents

2.1.1 GPS

All the current GPS Interface Control Documents can be downloaded from [GPS.gov](https://www.gps.gov), the official U.S. Government webpage for GPS.

- GPS L1 and L2C: Global Positioning System Directorate, [Interface Specification IS-GPS-200 Revision M](#). May, 2021.
- GPS L1C (available with first Block III launch): Global Positioning System Directorate, [Interface Specification IS-GPS-800 Revision H](#). May, 2021.
- GPS L5 (first Block IIF satellite launched on May, 2010): Global Positioning System Directorate, [Interface Specification IS-GPS-705 Revision H](#). May, 2021.

2.1.2 GLONASS

Official GLONASS webpage: [Information-analytical centre official website](#).

- Standard Accuracy (ST) signals at L1 and L2: Russian Institute of Space Device Engineering, Global Navigation Satellite System GLONASS. [Interface Control Document. Navigational radiosignal in bands L1, L2. Edition 5.1](#), Moscow, Russia, 2008
- [GLONASS Interface Control Document. Open CDMA navigational radio signal in L1 band. Edition 1.0 \(in Russian\)](#). Russian Space Systems OJSC. 2016.
- [GLONASS Interface Control Document. Open CDMA navigational radio signal in L2 band. Edition 1.0 \(in Russian\)](#). Russian Space Systems OJSC. 2016.
- [GLONASS Interface Control Document. Open CDMA navigational radio signal in L3 band. Edition 1.0 \(in Russian\)](#). Russian Space Systems OJSC. 2016.

2.1.3 Galileo

Check the [Galileo website](#) of the European Global Navigation Satellite Systems Agency (GSA) and the [Galileo website](#) of the European Space Agency. There is a website with [Galileo constellation status information](#) from the GSA.

- Galileo E5, E6, and E1: European GNSS (Galileo) Open Service. **Signal In Space Interface Control Document. Ref: OS SIS ICD, Issue 2.0**, European Union, Jan. 2021.

The European Commission is granting free access to the technical information on the future Galileo open service signal, i.e. the specifications manufacturers and developers need to process data received from satellites. This document informs receiver manufacturers, application developers and service providers on how to use the future Galileo system and what they can expect in terms of performance.

2.1.4 BeiDou

Official webpage at beidou.gov.cn

- **BeiDou Navigation Satellite System Signal In Space Interface Control Document Open Service Signal B1I (Version 3.0)**. China Satellite Navigation Office, Feb. 2019.
- **BeiDou Navigation Satellite System Signal In Space Interface Control Document Open Service Signal B1C (Version 1.0)**. China Satellite Navigation Office, Jun. 2018.
- **BeiDou Navigation Satellite System Signal In Space Interface Control Document Open Service Signal B3I (Version 1.0)**. China Satellite Navigation Office, Feb. 2018.
- **BeiDou Navigation Satellite System Signal In Space Interface Control Document Open Service Signal B2a (Version 1.0)**. China Satellite Navigation Office, Dec. 2017.
- **BeiDou Navigation Satellite System Signal In Space Interface Control Document Open Service Signal (Version 2.1)**. China Satellite Navigation Office, December 2016.

2.1.5 Satellite Based Augmentation Systems (SBAS)

- **Minimum Operational Performance Standards for Global Positioning System/Wide Area Augmentation System Airborne Equipment, DO-229D**, RTCA, Washington, DC, Dec. 13, 2006. The 'RTCA MOPS DO229D - appendix A' is the reference standard for WAAS/EGNOS application development. RTCA is an advisory committee of the US federal government, and issues standards for civil airborne equipment, among other duties. One such standard is MOPS 229D (Minimum Operational Performance Standards for Global Positioning System/Wide Area Augmentation System Airborne Equipment version D), which describes the implementation of satellite-based augmentation services (SBAS) for receivers designed for civil aviation use. An annex to DO229D contains the specifications for the SBAS signal and message. The RTCA provides regular updates to these standards. MOPS 229D is available for a fee from the [RTCA website](#).
- **Global Positioning System Wide Area Augmentation System (WAAS) Performance Standard, 1st Edition**, Department of Transportation and Federal Aviation Administration, Oct. 31, 2008. This document defines the levels of performance the U.S. Government makes available to users of the GPS SPS augmented by the Wide Area Augmentation System.
- **EGNOS Data Access Service (EDAS) Service Definition Document. Revision 2.2**, European GNSS Agency (GSA), June, 2019. This is a complementary document to the RTCA DO229D, mentioned above. It describes the scope of services provided by the EGNOS EDAS Service to be used by end-users or Application Specific Service Providers. It details the general conditions relating to the use of the EGNOS service, a technical description of the Signal-in-Space (SIS), the reference receiver, environmental conditions, the service performance achieved and aspects relating to service provision.
- **EGNOS Safety of Life Service Definition Document. Revision 3.3**, European GNSS Agency (GSA), Mar, 2019. The EGNOS Safety of Life (SoL) Service is provided openly and is freely accessible without any direct charge and is tailored to safety-critical transport applications in various domains, in particular for aviation applications. The service is thus compliant with the aviation APV-I (Approach with Vertical Guidance) requirements, as defined by ICAO in Annex 10, but may support also applications in other SoL domains.
- **EGNOS Open Service Service Definition Document. Revision 2.3**, European GNSS Agency (GSA), Sep., 2017.

More information about EGNOS can be found through the [EGNOS Portal](#).

2.2 Other Standards

2.2.1 RINEX

The final output of a navigation receiver is usually its position, speed or other related physical quantities. However, the calculation of those quantities are based on a series of measurements from one or more satellite constellations. Although receivers calculate positions in real time, in many cases it is interesting to store intermediate measures for later post-processing. RINEX is the standard format that allows the management and disposal of the measures generated by a receiver, as well as their off-line processing by a multitude of applications.

- The most common version at present is **RINEX: The Receiver Independent Exchange Format Version 2.12**, which enables storage of measurements from pseudorange, carrier-phase and Doppler systems for GPS, GLONASS, Galileo along with data from EGNOS and WAAS satellite based augmentation systems (SBAS).
- The most recent version is **RINEX: The Receiver Independent Exchange Format Version 3.03** published in July, 2015. It includes Galileo and improves the handling of multi-constellation data files.
- There is also available the **RINEX Extensions to Handle Clock Information**, published in September, 2010.

2.2.2 NMEA

The [National Marine Electronics Association](#) released the NMEA 0183 Interface Standard, which defines electrical signal requirements, data transmission protocol and time, and specific sentence formats for a 4800-baud serial data bus. The standard is [available for purchase](#).

2.2.3 KML

KML is an XML language focused on geographic visualization, including annotation of maps and images. Geographic visualization includes not only the presentation of graphical data on the globe, but also the control of the user's navigation in the sense of where to go and where to look. Google submitted KML (formerly Keyhole Markup Language) to the Open Geospatial Consortium (OGC) to be evolved within the OGC consensus process with the following goal: KML Version 2.2 has been adopted as an OGC implementation standard.

- Open Geospatial Consortium, Inc., [OGC KML Version 2.2.0](#), April 2008.

2.2.4 C++ Standards

The C++ programming language is standardized by the International Organization for Standardization (ISO), with the latest standard version ratified and published by ISO in December 2017 as ISO/IEC 14882:2017 (informally known as C++17). The list of supported C++ standards (the highest available is automatically selected by the CMake script):

- **Draft C++23:** Check the [C++ standard draft sources at GitHub](#).
- **C++20:** The current ISO C++ standard is officially known as *ISO International Standard ISO/IEC 14882:2020(E) – Programming languages – C++*. You can get it from [ISO](#), [IEC](#) or [ANSI](#). The closest free working document available is [N4868](#).
- **C++17:** A former ISO C++ standard was officially known as *ISO International Standard ISO/IEC 14882:2017 – Programming languages – C++*. You can get it from [ISO](#), [IEC](#) or [ANSI](#). The closest free working document available is [N4659](#).
- **C++14:** A former ISO C++ standard was officially known as *ISO International Standard ISO/IEC 14882:2014 – Programming languages – C++*. You can get it from [ISO](#) or [ANSI](#). The closest free working document available is [N4296](#).
- **C++11:** An older ISO C++ standard was ISO/IEC 14882:2011. You can get it from [ISO](#). The closest free working document available is [N3337](#).

2.2.5 Positioning protocols in wireless communication networks

Cellular industry location standards first appeared in the late 1990s, with the [3rd generation partnership project \(3GPP\)](#) radio resource location services protocol (RRLP) technical specification 44.031 positioning protocol for GSM networks. Today, RRLP is the de facto standardized protocol to carry GNSS assistance data to GNSS-enabled mobile devices, and the term "3GPP specification" now covers all GSM (including GPRS and EDGE), W-CDMA and LTE (including LTE-A) specifications. Precisely, the label "LTE-A" is applied to networks compliant with LTE Release 10 and beyond, which fulfill the requirements issued by the [International Telecommunication Union Radiocommunication Sector \(ITU-R\)](https://www.itu.int/en/ITU-R/Pages/default.aspx) in the global standard for international mobile telecommunications (IMT Advanced, also referred to as 4G) access technologies. Control plane protocols: \li Radio Resource LCS Protocol (RRLP): <https://www.3gpp.org/ftp/Specs/html-info/44031.htm> target="_blank">3GPP

Technical Specification 44.031

- LTE Positioning Protocol (LPP): [3GPP Technical Specification 36.355](https://www.3gpp.org/ftp/Specs/html-info/36355.htm). User plane protocols:
 - Open Mobile Alliance (OMA), [Secure User Plane Location Architecture Version 1 \(SUPL 1.0\)](http://member.openmobilealliance.org/ftp/Public_documents/LOC/Permanent_documents/OMA-AD-SUPL-V1_0-20070615-A.zip), June 2007.
 - Open Mobile Alliance (OMA), [Secure User Plane Location Architecture Version 2 \(SUPL 2.0\)](http://member.openmobilealliance.org/ftp/Public_documents/LOC/Permanent_documents/OMA-AD-SUPL-V2_0-20120417-A.zip), April 2012.
 LTE Release 9 introduced extension hooks in LPP messages, so that the bodies external to 3GPP could extend the LPP feature set. OMA LPP extensions (LPPe), supported in SUPL 3.0, build on top of the 3GPP LPP reusing its procedures and data types. Check the [OMA Specifications webpage](https://technical.openmobilealliance.org/index.html) for updated information about LPP Extensions (LPPe) Specification.
- The [OMA Mobile Location Protocol \(MLP\) V3.5](http://member.openmobilealliance.org/ftp/Public_documents/loc/Permanent_documents/OMA-TS-MLP-V3_5-20181119-D.zip) is an application-level protocol for getting the position of mobile stations (mobile phones, wireless personal digital assistants, etc.) independent of underlying network technology. The MLP serves as the interface between a Location Server and a Location Services (LCS) Client. This specification defines the core set of operations that a Location Server should be able to perform.

Chapter 3

Signal model

3.1 GNSS signal model

This page describes signals transmitted by GNSS space vehicles. Signal models are mathematical representations of the electromagnetic waves that are exciting the receiver's antenna. The current induced by those waves is then amplified, filtered and downconverted to a suitable frequency (can be at some intermediate frequency or directly to baseband), and then converted to 0s and 1s by the Analog-to-Digital Converter (ADC). That is the job of the Radio Frequency front-end, which at its output delivers a stream of digital samples. Those samples constitute the input of a software receiver, so for GNSS-SDR the signal models described below can be seen as *the rules of the game*.

GNSS' space vehicles are modern versions of lighthouses, but with better visibility. Each satellite is a reference point, and if we know our distance to several reference points, we can compute our location, just as mariners do when they see a couple of lighthouses. For each in-view satellite i of system s , we can write:

$$\rho_i = \sqrt{(x_i^{\text{Tx}} - x)^2 + (y_i^{\text{Tx}} - y)^2 + (z_i^{\text{Tx}} - z)^2} + c\Delta t^{(s)} + \sigma_e, \quad (3.1)$$

where $(x_i^{\text{Tx}}, y_i^{\text{Tx}}, z_i^{\text{Tx}})$ is the satellite's position (known from the navigation message), (x, y, z) the receiver's position, and σ_e gathers other sources of error. Since the receiver needs to estimate its own 3D position (three spatial unknowns) and its clock deviation with respect to the satellites' time basis, at least $3 + N_s$ satellites must be seen by the receiver at the same time, where N_s is the number of different navigation systems available (in-view) at a given time. Each received satellite signal, once synchronized and demodulated at the receiver, defines one equation such as the one defined above, forming a set of nonlinear equations that can be solved algebraically by means of the [Bancroft algorithm](#) or numerically, resorting to multidimensional Newton-Raphson and weighted least square methods. When *a priori* information is added we resort to Bayesian estimation, a problem that can be solved recursively by a Kalman filter or any of its variants. The problem can be further expanded by adding other unknowns (for instance, parameters of ionospheric and tropospheric models), sources of information from other systems, mapping information, and even motion models of the receiver. In the design of multi-constellation GNSS receivers, the vector of unknowns can also include the receiver clock offset with respect to each system in order to take advantage of a higher number of in-view satellites and using them jointly in the navigation solution, therefore increasing accuracy.

The [analytic representation](#) of a signal received from a GNSS satellite can be generically expressed as

$$r(t) = \alpha(t)s_T(t - \tau(t))e^{-j2\pi f_d(t)}e^{j2\pi f_c t} + n(t), \quad (3.2)$$

where $\alpha(t)$ is the amplitude, $s_T(t)$ is the complex baseband transmitted signal, $\tau(t)$ is the time-varying delay, $f_d(t) = f_c\tau(t)$ is the Doppler shift, f_c is the carrier frequency, and $n(t)$ is a noise term. These signals arrive to the Earth's surface at extremely low power (e.g. -158.5 dBW for GPS L1 C/A-code, -157 dBW for Galileo E1), well below the noise floor. In order to estimate its distances to satellites, the receiver must correlate time-aligned replicas of the corresponding pseudorandom code with the incoming signal, in a process called *despreading* that

provides processing gain only to the signal of interest. After a coarse and fine estimation stages of the synchronization parameters (usually known as acquisition and tracking, respectively), signal processing output is in form of *observables*:

i) the pseudorange (code) measurement, equivalent to the difference of the time of reception (expressed in the time frame of the receiver) and the time of transmission (expressed in the time frame of the satellite) of a distinct satellite signal; and optionally

ii) the carrier-phase measurement, actually being a measurement on the beat frequency between the received carrier of the satellite signal and a receiver-generated reference frequency. Carrier phase measurements are ambiguous, in the sense that the integer number of carrier wavelengths between satellite and the receiver's antenna is unknown. Techniques such as **Least-square AMBiguity Decorrelation Approach (LAMBDA)** or Multi Carrier Ambiguity Resolution (MCAR) can be applied to resolve such ambiguity and provide an accurate estimation of the distance between the satellite and the receiver.

Then, depending on the required accuracy, the navigation solution can range from pseudorange-only, computationally low demanding, and limited accuracy least squares methods to sophisticated combinations of code and phase observables at different frequencies for high demanding applications such as surveying, geodesy, and geophysics.

Next sections provide brief descriptions of the space segment of different GNSSs and their broadcast signal structures accessible by civilians.

3.1.1 Global Positioning System (GPS) signal in space

The Global Positioning System (GPS) is a space-based radio-navigation system owned by the United States Government (USG) and operated by the United States Air Force (USAF). GPS provides positioning and timing services to military and civilian users on a continuous, worldwide basis. Two GPS services are provided: the Precise Positioning Service (PPS), available primarily to the military of the United States and its allies, and the Standard Positioning Service (SPS) open to civilian users.

- **GPS L1.** Defined at **Interface Specification IS-GPS-200 Revision M**, this band is centered at $f_{\text{GPS L1}} = 1575.42$ MHz. The complex baseband transmitted signal can be written as

$$s_T^{(\text{GPS L1})}(t) = e_{L1I}(t) + je_{L1Q}(t), \quad (3.3)$$

with

$$e_{L1I}(t) = \sum_{l=-\infty}^{\infty} D_{\text{NAV}}[l]_{204600} \oplus C_{P(Y)}[l]_{L_{P(Y)}} p(t - lT_{c,P(Y)}), \quad (3.4)$$

$$e_{L1Q}(t) = \sum_{l=-\infty}^{\infty} D_{\text{NAV}}[l]_{20460} \oplus C_{C/A}[l]_{1023} p(t - lT_{c,C/A}), \quad (3.5)$$

where \oplus is the exclusive-or operation (modulo-2 addition), $|l|_L$ means l modulo L , $[l]_L$ means the integer part of $\frac{l}{L}$, D_{NAV} is the GPS navigation message bit sequence, transmitted at 50 bps, $T_{c,P(Y)} = \frac{1}{10.23} \mu\text{s}$, $T_{c,C/A} = \frac{1}{1.023} \mu\text{s}$, $L_{P(Y)} = 6.1871 \cdot 10^{12}$, and $p(t)$ is a rectangular pulse of a chip-period duration centered at $t = 0$ and filtered at the transmitter. According to the chip rate, the binary phase-shift keying modulations in the equations above are denoted as BPSK(10) and BPSK(1), respectively. The precision P codes (named Y codes whenever the anti-spoofing mode is activated, encrypting the code and thus denying non-U.S. military users) are sequences of 7 days in length. Regarding the modernization plans for GPS, it is worthwhile to mention that there is a new civilian-use signal planned, called L1C and defined at **Interface Specification IS-GPS-800 Revision H**, to be broadcast on the same L1 frequency that currently contains the C/A signal. The L1C is available with first Block III launch. The implementation provides C/A code to ensure backward compatibility.

- **GPS L2C.** Defined at **Interface Specification IS-GPS-200 Revision M**, is only available on Block IIR-M and subsequent satellite blocks. Centered at $f_{\text{GPS L2}} = 1227.60$ MHz, the signal structure is the same than in (eq:GPSL1}), with the precision code in the In-phase component, just as in (eq:L1CAI}) but with an optional presence of the navigation message D_{NAV} . For the Quadrature-phase component, three options are defined:

$$e_{L2CQ}(t) = \sum_{l=-\infty}^{\infty} D_{\text{CNAV}}[l]_{10230} \oplus \left(C_{\text{CL}}[l]_{L_{\text{CL}}} p_{1/2}(t - lT_{c,L2C}) + \right. \quad (3.6)$$

$$\left. + C_{\text{CM}}[l]_{L_{\text{CM}}} p_{1/2}\left(t - \left(l + \frac{3}{4}\right) T_{c,L2C}\right) \right), \quad (3.7)$$

$$e_{L2CQ}(t) = \sum_{l=-\infty}^{\infty} D_{\text{NAV}}[l]_{20460} \oplus C_{\text{C/A}}[l]_{1023} p(t - lT_{c,C/A}), \text{ or} \quad (3.8)$$

$$e_{L2CQ}(t) = \sum_{l=-\infty}^{\infty} C_{\text{C/A}}[l]_{1023} p(t - lT_{c,C/A}), \quad (3.9)$$

where $T_{c,L2C} = \frac{1}{511.5}$ ms and $p_{1/2}(t)$ is a rectangular pulse of half chip-period duration, thus time-multiplexing both codes. The civilian long code C_{CL} is $L_{\text{CL}} = 767250$ chips long, repeating every 1.5 s, while the civilian moderate code C_{CM} is $L_{\text{CL}} = 10230$ chips long and its repeats every 20 ms. The CNAV data is an upgraded version of the original NAV navigation message, containing higher precision representation and nominally more accurate data than the NAV data. It is transmitted at 25 bps with forward error correction (FEC) encoding, resulting in 50 sps.

- **GPS L5.** The GPS L5 link, defined at **Interface Specification IS-GPS-705 Revision H**, is only available in Block IIF (first satellite launched on May, 2010) and subsequent satellite blocks. Centered at $f_{\text{GPS L5}} = 1176.45$ MHz, this signal in space can be written as:

$$s_T^{(\text{GPS L5})}(t) = e_{L5I}(t) + je_{L5Q}(t), \quad (3.10)$$

$$e_{L5I}(t) = \sum_{m=-\infty}^{+\infty} C_{nh10}[m]_{10} \oplus D_{\text{CNAV}}[m]_{10} \oplus \sum_{l=1}^{102300} C_{L5I}[l]_{10230} p(t - mT_{c,nh} - lT_{c,L5}), \quad (3.11)$$

$$e_{L5Q}(t) = \sum_{m=-\infty}^{+\infty} C_{nh20}[m]_{20} \oplus \sum_{l=1}^{102300} C_{L5Q}[l]_{10230} \cdot p(t - mT_{c,nh} - lT_{c,L5}), \quad (3.12)$$

where $T_{c,nh} = 1$ ms and $T_{c,L5} = \frac{1}{10.23}$ μ s, thus defining a BPSK(10) modulation. Both L5I and L5Q contain synchronization sequences.

3.1.2 GLONASS signal in space

The nominal baseline constellation of the Russian Federation's Global Navigation Satellite System (GLONASS) comprises 24 GLONASS-M satellites that are uniformly deployed in three roughly circular orbital planes at an inclination of 64.8° to the equator. The altitude of the orbit is 19,100 km. The orbit period of each satellite is 11 hours, 15 minutes, and 45 seconds. The orbital planes are separated by 120° right ascension of the ascending node. Eight satellites are equally spaced in each plane with 45° argument of latitude. Moreover, the orbital planes have an argument of latitude displacement of 15° relative to each other.

GLONASS civil signal-in-space is defined at **Interface Control Document. Navigational radiosignal in bands L1, L2. Edition 5.1**. This system makes use of a frequency-division multiple access (FDMA) signal structure, transmitting in two bands: $f_{\text{GLOL1}}^{(k)} = 1602 + k \cdot 0.5625$ MHz and $f_{\text{GLOL2}}^{(k)} = 1246 + k \cdot 0.4375$ MHz, where $k \in \{-7, -6, \dots, 5, 6\}$ is the channel number. Satellites in opposite points of an orbit plane transmit signals on equal frequencies, as these satellites will never be in view simultaneously by a ground-based user.

- **GLONASS L1.** Two kind of signals are transmitted: a standard precision (SP) and an obfuscated high precision (HP) signal. The complex baseband transmitted signal can be written as

$$s_T^{(\text{GLO L1})}(t) = e_{L1I}(t) + je_{L1Q}(t), \quad (3.13)$$

with BPSK(5) and BPSK(0.5) modulations:

$$e_{L1I}(t) = \sum_{l=-\infty}^{\infty} D_{\text{GNAV}}[l]_{102200} \oplus C_{\text{HP}}[l]_{L_{\text{HP}}} p(t - lT_{c,\text{HP}}), \quad (3.14)$$

$$e_{L1Q}(t) = \sum_{l=-\infty}^{\infty} D_{\text{GNAV}}[l]_{10220} \oplus C_{\text{SP}}[l]_{511} p(t - lT_{c,\text{SP}}), \quad (3.15)$$

where $T_{c,\text{HP}} = \frac{1}{5.11} \mu\text{s}$, $T_{c,\text{SP}} = \frac{1}{0.511} \mu\text{s}$, and $L_{\text{HP}} = 3.3554 \cdot 10^7$. The navigation message D_{GNAV} is transmitted at 50 bps. Details of its content and structure, as well as the generation of the C_{SP} code, can be found at the [ICD](#). The usage of the HP signal should be agreed with the Russian Federation Defense Ministry, and no more details have been disclosed.

- **GLONASS L2.** Beginning with the second generation of satellites, called GLONASS-M and first launched in 2001, a second civil signal is available using the same SP code than the one in the L1 band.

The use of FDMA techniques, in which the same code is used to broadcast navigation signals on different frequencies, and the placement of civil GLONASS transmissions on frequencies close to 1600 MHz, well above the GPS L1 band, have complicated the design of combined GLONASS/GPS receivers, particularly low-cost equipment for mass-market applications. Future plans of modernization are intended to increase compatibility and interoperability with other GNSS, and include the addition of a code-division multiple access (CDMA) structure, and possibly binary offset carrier (BOC) modulation, beginning with the third civil signal in the L3 band (1197.648 – 1212.255 MHz). Russia is implementing the new signals on the next-generation GLONASS-K satellites, with a first prototype successfully launched into orbit on February 26, 2011.

3.1.3 Galileo signal in space

The nominal Galileo constellation comprises a total of 27 operational satellites (plus 3 active spares), that are evenly distributed among three orbital planes inclined at 56° relative to the equator. There are nine operational satellites per orbital plane, occupying evenly distributed orbital slots. Three additional spare satellites (one per orbital plane) complement the nominal constellation configuration. The Galileo satellites are placed in quasi-circular Earth orbits with a nominal semi-major axis of about 30,000 km and an approximate revolution period of 14 hours. The Control segment full infrastructure will be composed of 30 – 40 sensor stations, 3 control centers, 9 Mission Uplink stations, and 5 TT&C stations.

Galileo's Open Service is defined at [Signal In Space Interface Control Document](#). [Ref↔](#): [OS SIS ICD, Issue 2.0](#), where the following signal structures are specified:

- **Galileo E1.** This band, centered at $f_{\text{Gal E1}} = 1575.420$ MHz and with a reference bandwidth of 24.5520 MHz, uses the so-called composite binary offset carrier CBOC(6,1, $\frac{1}{11}$) modulation, defined in baseband as:

$$s_T^{(\text{Gal E1})}(t) = \frac{1}{\sqrt{2}} \left(e_{E1B}(t) (\alpha sc_A(t) + \beta sc_B(t)) + \right. \quad (3.16)$$

$$\left. - e_{E1C}(t) (\alpha sc_A(t) - \beta sc_B(t)) \right), \quad (3.17)$$

where the subcarriers $sc(t)$ are defined as

$$sc_A(t) = \text{sign}(\sin(2\pi f_{s,E1A}t)), \quad (3.18)$$

$$sc_B(t) = \text{sign}(\sin(2\pi f_{s,E1B}t)), \quad (3.19)$$

and $f_{s,E1A} = 1.023$ MHz, $f_{s,E1B} = 6.138$ MHz are the subcarrier rates, $\alpha = \sqrt{\frac{10}{11}}$, and $\beta = \sqrt{\frac{1}{11}}$. Channel B contains the I/NAV type of navigation message, $D_{I/NAV}$, intended for Safety-of-Life (SoL) services:

$$e_{E1B}(t) = \sum_{l=-\infty}^{+\infty} D_{I/NAV} \left[[l]_{4092} \right] \oplus C_{E1B} \left[[l]_{4092} \right] p(t - lT_{c,E1B}). \quad (3.20)$$

In case of channel C, it is a pilot (dataless) channel with a secondary code, forming a tiered code:

$$e_{E1C}(t) = \sum_{m=-\infty}^{+\infty} C_{E1Cs} \left[[m]_{25} \right] \oplus \sum_{l=1}^{4092} C_{E1Cp} \left[[l] \right] \cdot p(t - mT_{c,E1Cs} - lT_{c,E1Cp}), \quad (3.21)$$

with $T_{c,E1B} = T_{c,E1Cp} = \frac{1}{1.023} \mu\text{s}$ and $T_{c,E1Cs} = 4$ ms. The C_{E1B} and C_{E1Cp} primary codes are pseudorandom memory code sequences defined at Annex C of OS SIS ICD. The binary sequence of the secondary code C_{E1Cs} is 0011100000001010110110010. This band also contains another component, Galileo E1A, intended for the Public Regulated Service (PRS). It uses a BOC(15,2.5) modulation with cosine-shaped subcarrier $f_{s,E1A} = 15.345$ MHz and $T_{c,E1A} = \frac{1}{2.5575} \mu\text{s}$. The PRS spreading codes and the structure of the navigation message have not been made public.

- **Galileo E6.** Intended for the Commercial Service and centered at $f_{\text{Gal E6}} = 1278.750$ MHz, this band provides pilot and data components

$$s_T^{(\text{Gal E6})}(t) = \frac{1}{\sqrt{2}} (e_{E6B}(t) - e_{E6C}(t)), \quad (3.22)$$

$$e_{E6B}(t) = \sum_{m=-\infty}^{+\infty} D_{C/NAV} \left[[l]_{5115} \right] \oplus C_{E6B} \left[[l]_{L_{E6B}} \right] \cdot p(t - lT_{c,E6}), \quad (3.23)$$

$$e_{E6C}(t) = \sum_{m=-\infty}^{+\infty} C_{E6Cs} \left[[m]_{100} \right] \oplus \sum_{l=1}^{L_{E6C}} C_{E6Cp} \left[[l] \right] \cdot p(t - mT_{c,E6s} - lT_{c,E6p}), \quad (3.24)$$

where $D_{C/NAV}$ is the C/NAV navigation data stream, which is modulated with the encrypted ranging code C_{E6B} with chip period $T_{c,E6} = \frac{1}{5.115} \mu\text{s}$, thus being a BPSK(5) modulation. Codes C_{E6B} and primary codes C_{E6Cs} and their respective lengths, L_{E6B} and L_{E6C} , have not been published. The secondary codes for the pilot component, C_{E6Cp} , are available at the OS SIS ICD. The receiver reference bandwidth for this signal is 40.920 MHz. This band also contains another component, Galileo E6A, intended for PRS.

- **Galileo E5.** Centered at $f_{\text{Gal E5}} = 1191.795$ MHz and with a total bandwidth of 51.150 MHz, its signal structure deserves some analysis. The AltBOC modulation can be generically expressed as

$$s^{\text{AltBOC}}(t) = x_1(t)v^*(t) + x_2(t)v(t), \quad (3.25)$$

where $v(t) = \frac{1}{\sqrt{2}} (\text{sign}(\cos(2\pi f_s t)) + j \text{sign}(\sin(2\pi f_s t)))$ is the single side-band subcarrier, f_s is the subcarrier frequency, $(\cdot)^*$ stands for the conjugate operation, and $x_1(t)$ and $x_2(t)$ are QPSK signals. The resulting waveform does not exhibit constant envelope. In case of Galileo, the need for high efficiency of the satellites' onboard High Power Amplifier (HPA) has pushed a modification on the signal in order to make it envelope-constant and thus use the HPA at saturation. This can be done by adding some inter-modulation products to the expression above, coming up with the following definition:

$$s_T^{(\text{Gal E5})}(t) = e_{E5a}(t)ssc_s^*(t) + e_{E5b}(t)ssc_s(t) + \bar{e}_{E5a}(t)ssc_p^*(t) + \bar{e}_{E5b}(t)ssc_p(t), \quad (3.26)$$

where the single and product side-band signal subcarriers are

$$ssc_s(t) = sc_s(t) + jsc_s\left(t - \frac{T_s}{4}\right), \quad (3.27)$$

$$ssc_p(t) = sc_p(t) + jsc_p\left(t - \frac{T_s}{4}\right), \quad (3.28)$$

and

$$e_{E5a}(t) = e_{E5aI}(t) + je_{E5aQ}(t), \quad (3.29)$$

$$e_{E5b}(t) = e_{E5bI}(t) + je_{E5bQ}(t), \quad (3.30)$$

$$\bar{e}_{E5a}(t) = \bar{e}_{E5aI}(t) + j\bar{e}_{E5aQ}(t), \quad (3.31)$$

$$\bar{e}_{E5b}(t) = \bar{e}_{E5bI}(t) + j\bar{e}_{E5bQ}(t), \quad (3.32)$$

$$\bar{e}_{E5aI}(t) = e_{E5aQ}(t)e_{E5bI}(t)e_{E5bQ}(t), \quad (3.33)$$

$$\bar{e}_{E5aQ}(t) = e_{E5aI}(t)e_{E5bI}(t)e_{E5bQ}(t), \quad (3.34)$$

$$\bar{e}_{E5bI}(t) = e_{E5bQ}(t)e_{E5aI}(t)e_{E5aQ}(t), \quad (3.35)$$

$$\bar{e}_{E5bQ}(t) = e_{E5bI}(t)e_{E5aI}(t)e_{E5aQ}(t). \quad (3.36)$$

The signal components are defined as

$$e_{E5aI}(t) = \sum_{m=-\infty}^{+\infty} C_{E5aIs} \left[|m|_{20} \right] \oplus \sum_{l=1}^{10230} C_{E5aIp} \left[l \right] \oplus \quad (3.37)$$

$$\oplus D_{F/NAV} \left[[l]_{204600} \right] p(t - mT_{c,E5s} - lT_{c,E5p}), \quad (3.38)$$

$$e_{E5aQ}(t) = \sum_{m=-\infty}^{+\infty} C_{E5aQs} \left[|m|_{100} \right] \oplus \sum_{l=1}^{10230} C_{E5aQp} \left[l \right] \cdot \quad (3.39)$$

$$\cdot p(t - mT_{c,E5s} - lT_{c,E5p}), \quad (3.40)$$

$$e_{E5bI}(t) = \sum_{m=-\infty}^{+\infty} C_{E5bIs} \left[|m|_4 \right] \oplus \sum_{l=1}^{10230} C_{E5bIp} \left[l \right] \oplus \quad (3.41)$$

$$\oplus D_{I/NAV} \left[[l]_{40920} \right] p(t - mT_{c,E5s} - lT_{c,E5p}), \quad (3.42)$$

$$e_{E5bQ}(t) = \sum_{m=-\infty}^{+\infty} C_{E5bQs} \left[|m|_{100} \right] \oplus \sum_{l=1}^{10230} C_{E5bQp} \left[l \right] \cdot \quad (3.43)$$

$$\cdot p(t - mT_{c,E5s} - lT_{c,E5p}), \quad (3.44)$$

where $T_{c,E5s} = 1$ ms and $T_{c,E5p} = \frac{1}{10.23} \mu\text{s}$. **Channel A** contains the F/NAV type of navigation message, $D_{F/NAV}$, intended for the Open Service. The I/NAV message structures for the E5bI and E1B signals use the same page layout. Only page sequencing is different, with page swapping between both components in order to allow a fast reception of data by a dual frequency receiver. The single subcarrier $sc_s(t)$ and the product subcarrier $sc_p(t)$ are defined as:

$$sc_s(t) = \frac{\sqrt{2}}{4} \text{sign} \left(\cos \left(2\pi f_s t - \frac{\pi}{4} \right) \right) + \quad (3.45)$$

$$+ \frac{1}{2} \text{sign} \left(\cos (2\pi f_s t) \right) + \frac{\sqrt{2}}{4} \text{sign} \left(\cos \left(2\pi f_s t + \frac{\pi}{4} \right) \right), \quad (3.46)$$

$$sc_p(t) = -\frac{\sqrt{2}}{4} \text{sign} \left(\cos \left(2\pi f_s t - \frac{\pi}{4} \right) \right) + \quad (3.47)$$

$$+ \frac{1}{2} \text{sign} \left(\cos (2\pi f_s t) \right) - \frac{\sqrt{2}}{4} \text{sign} \left(\cos \left(2\pi f_s t + \frac{\pi}{4} \right) \right), \quad (3.48)$$

with a subcarrier frequency of $f_s = 15.345$ MHz, thus defining an AltBOC(15,10) modulation. The QPSK(10) signal $e_{E5a}(t)$ defined above is shifted to $f_{\text{Gal E5a}} \doteq f_{\text{Gal E5}} - f_s = 1176.450$ MHz, while $e_{E5b}(t)$ is shifted to $f_{\text{Gal E5b}} \doteq f_{\text{Gal E5}} + f_s = 1207.140$ MHz. Thus, we can bandpass filter around $f_{\text{Gal E5a}}$ and get a good approximation of a QPSK(10) signal, with very low energy components of $e_{E5b}(t)$, $\bar{e}_{E5a}(t)$, and $\bar{e}_{E5b}(t)$:

$$s_T^{(\text{Gal E5a})}(t) \simeq e_{E5aI}(t) + je_{E5aQ}(t). \quad (3.49)$$

The same applies to $e_{E5b}(t)$, allowing an independent reception of two QPSK(10) signals and thus requiring considerably less bandwidth than the processing of the whole E5 band.

3.1.4 Reference

This text is an except of the following paper:

- C. Fernández-Prades, L. Lo Presti, E. Falletti, *Satellite Radiolocalization From GPS to GNSS and Beyond: Novel Technologies and Applications for Civil Mass↔Market*. Proceedings of the IEEE. Vol 99, No. 11, pp. 1882-1904. November, 2011. doi: 10.1109/JPROC.2011.2158032

Chapter 4

Todo List

Member **ALPHA_0** ({{69, 8}})

read all pages of subframe 4

Member **T_OA** ({{69, 8}})

read all pages of subframe 5

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Chapter 9

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gps_l1_ca_dll_pll_tracking_gpu_cc.h	Implementation of a code DLL + carrier PLL tracking block, GPU ACCELERATED	1590
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gps_l1_ca_tcp_connector_tracking_cc.h	Interface of a TCP connector block based on code DLL + carrier PLL	1596
kf_tracking.h		1599
bayesian_estimation.h	Interface of a library with Bayesian noise statistic estimation	1601
bit_synchronizer.h	Histogram-based bit-edge synchronizer for GNSS prompt correlator outputs	1603
cpu_multicorrelator.h	High optimized CPU vector multiTAP correlator class	1607
cpu_multicorrelator_16sc.h	Highly optimized CPU vector multiTAP correlator class for lv_16sc_t (short int complex)	1609
cpu_multicorrelator_real_codes.h	Highly optimized CPU vector multiTAP correlator class using real-valued local codes	1610
cuda_multicorrelator.h	Highly optimized CUDA GPU vector multiTAP correlator class	1611
dll_pll_conf.h	Class that contains all the configuration parameters for generic tracking block based on a DLL and a PLL	1614
dll_pll_conf_fpga.h	Class that contains all the configuration parameters for generic tracking block based on a DLL and a PLL for the FPGA	1615
exponential_smoother.h	Class that implements an exponential smoother	1617
fpga_multicorrelator.h	FPGA vector correlator class	1618
kf_conf.h		1622
lock_detectors.h	Interface of a library with a set of code and carrier phase lock detectors	1623
nonlinear_tracking.h	Interface of a library for nonlinear tracking algorithms	1625
tcp_communication.h	Interface of the TCP communication class	1627
tcp_packet_data.h	Interface of the TCP data packet class	1629
tracking_2nd_DLL_filter.h	Interface of a 2nd order DLL filter for code tracking loop	1630
tracking_2nd_PLL_filter.h	Interface of a 2nd order PLL filter for carrier tracking loop	1631
tracking_discriminators.h	Interface of a library with a set of code tracking and carrier tracking discriminators	1632
tracking_FLL_PLL_filter.h	Interface of a hybrid FLL and PLL filter for tracking carrier loop	1636
tracking_loop_filter.h	Generic 1st to 3rd order loop filter implementation	1637
acquisition_interface.h	Header file of the interface to an acquisition GNSS block	1638
channel_interface.h	This class represents an interface to a channel GNSS block	1640

configuration_interface.h	This class represents an interface to configuration parameters	1641
gnss_block_interface.h	This interface represents a GNSS block	1642
observables_interface.h	This class represents an interface to an Observables block	1644
pvt_interface.h	This class represents an interface to a PVT block	1645
signal_source_interface.h	1647
telemetry_decoder_interface.h	This class represents an interface to a telemetry decoder block	1647
tracking_interface.h	This class represents an interface to a tracking block	1649
channel_event.h	Class that defines a channel event	1650
channel_status_msg_receiver.h	GNU Radio block that receives asynchronous channel messages from acquisition and tracking blocks	1651
command_event.h	Class that defines a receiver command event	1652
galileo_e6_has_msg_receiver.h	GNU Radio block that processes Galileo HAS message pages received from Galileo E6B telemetry blocks. After successful decoding, sends the content to the PVT block	1654
galileo_tow_map.h	GNU Radio block that stores TOW for Galileo channels	1656
gnss_crypto.h	Class for computing cryptographic functions	1657
gnss_sdr_fpga_sample_counter.h	Simple block to report the current receiver time based on the output of the tracking or telemetry blocks	1659
gnss_sdr_sample_counter.h	Simple block to report the current receiver time based on the output of the tracking or telemetry blocks	1661
gnss_sdr_supl_client.h	Class that implements a C++ interface to external Secure User Location Protocol (SUPL) client library	1663
gnss_sdr_time_counter.h	Simple block to report the current receiver time based on the output of the tracking or telemetry blocks	1667
ini.h	This function parses an INI file into easy-to-access name/value pairs	1668
INIReader.h	This class reads an INI file into easy-to-access name/value pairs	1670
nav_message_monitor.h	GNU Radio block that processes Nav_Message_Packet received from telemetry blocks and sends them via UDP	1671
nav_message_packet.h	Class for storage of decoded navigation messages	1673
nav_message_udp_sink.h	Interface of a class that sends serialized Nav_Message_Packet objects over UDP to one or multiple endpoints	1674
osnma_helper.h	Class for auxiliary osnma functions	1675
osnma_msg_receiver.h	GNU Radio block that processes Galileo OSNMA data received from Galileo E1B telemetry blocks. After successful decoding, sends the content to the PVT block	1676
osnma_nav_data_manager.h	Class for Galileo OSNMA navigation data management	1680

serdes_nav_message.h	Serialization / Deserialization of Nav_Message_Packet objects using Protocol Buffers	1681
string_converter.h	Interface of a class that interprets the contents of a string and converts it into different types . .	1683
uio_fpga.h	This library contains functions to determine the uio device driver file that corresponds to a hardware accelerator device name in the FPGA	1684
gnss_synchro_monitor.h	Interface of a receiver monitoring block which allows sending a data stream with the receiver internal parameters (Gnss_Synchro objects) to local or remote clients over UDP	1685
gnss_synchro_udp_sink.h	Interface of a class that sends serialized Gnss_Synchro objects over udp to one or multiple endpoints	1687
serdes_gnss_synchro.h	Serialization / Deserialization of Gnss_Synchro objects using Protocol Buffers	1688
concurrent_map.h	Interface of a thread-safe std::map	1691
concurrent_queue.h	Interface of a thread-safe std::queue	1692
control_thread.h	Interface of the receiver control plane	1694
file_configuration.h	A ConfigurationInterface that reads the configuration from a file	1698
gnss_block_factory.h	Interface of a factory that returns smart pointers to GNSS blocks	1699
gnss_flowgraph.h	Interface of a GNSS receiver flow graph	1701
in_memory_configuration.h	A ConfigurationInterface for testing purposes	1706
tcp_cmd_interface.h	Class that implements a TCP/IP telecommand command line interface for GNSS-SDR	1707
agnss_ref_location.h	Interface of an Assisted GNSS REFERENCE LOCATION storage	1709
agnss_ref_time.h	Interface of an Assisted GNSS REFERENCE TIME storage	1710
Beidou_B1I.h	Defines system parameters for BeiDou B1I signal and DNAV data	1711
Beidou_B3I.h	Defines system parameters for BeiDou B3I signal and DNAV data	1713
Beidou_DNAV.h	Defines system parameters for BeiDou DNAV data processing	1714
beidou_dnav_almanac.h	Interface of a Beidou DNAV Almanac storage	1722
beidou_dnav_ephemeris.h	Interface of a BEIDOU EPHEMERIS storage	1723
beidou_dnav_iono.h	Interface of a BEIDOU IONOSPHERIC MODEL storage	1725
beidou_dnav_navigation_message.h	Interface of a BeiDou DNAV Data message decoder	1726
beidou_dnav_utc_model.h	Interface of a BeiDou UTC MODEL storage	1731
display.h	Defines useful display constants	1732
galileo_almanac.h	Interface of a Galileo ALMANAC storage	1734
galileo_almanac_helper.h	Interface of a Galileo ALMANAC storage helper	1736

Galileo_CNAV.h	Galileo CNAV message constants. Data from: Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022	1737
galileo_cnav_message.h	Implementation of a Galileo CNAV Data message as described in Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022	1741
Galileo_E1.h	Defines system parameters for Galileo E1 signal and NAV data	1743
Galileo_E5a.h	Defines system parameters for Galileo E5a signal and NAV data	1761
Galileo_E5b.h	Defines system parameters for Galileo E5b signal and NAV data	1805
Galileo_E6.h	Defines system parameters for Galileo E6 B/C signal, as published at: European Union, E6-B/C Codes Technical Note, Issue 1, January 2019	1849
galileo_ephemeris.h	Interface of a Galileo EPHEMERIS storage	1872
Galileo_FNAV.h	Galileo FNAV message constants	1873
galileo_fnav_message.h	Implementation of a Galileo F/NAV Data message as described in Galileo OS SIS ICD Issue 1.2 (Nov. 2015)	1879
galileo_has_data.h	Class for Galileo HAS message type 1 data storage	1883
galileo_has_page.h	Class for Galileo HAS message page storage	1886
Galileo_INAV.h	Galileo INAV message constants	1887
galileo_inav_message.h	Implementation of a Galileo I/NAV Data message as described in Galileo OS SIS ICD Issue 2.0 (Jan. 2021)	1895
galileo_iono.h	Interface of a Galileo Ionospheric Model storage	1902
galileo_ism.h	Interface of a Galileo Integrity Support Message	1904
Galileo_OSNMA.h	Galileo OSNMA message constants	1907
galileo_reduced_ced.h	Galileo Reduced Clock and Ephemeris Data storage class	1910
galileo_utc_model.h	Interface of a Galileo UTC MODEL storage	1911
glonass_gnav_almanac.h	Interface of a GLONASS GNAV ALMANAC storage	1913
glonass_gnav_ephemeris.h	Interface of a GLONASS EPHEMERIS storage	1915
glonass_gnav_navigation_message.h	Interface of a GLONASS GNAV Data message decoder as described in GLONASS ICD (Edition 5.1)	1918
glonass_gnav_utc_model.h	Interface of a GLONASS GNAV UTC MODEL storage	1922
GLONASS_L1_L2_CA.h	Defines system parameters for GLONASS L1 C/A signal and NAV data	1923
gnss_almanac.h	Base class for GNSS almanac storage	1932
gnss_ephemeris.h	Base class for GNSS Ephemeris	1933
gnss_frequencies.h	GNSS Frequencies	1935

gnss_obs_codes.h	GNSS Observable codes	1937
gnss_satellite.h	Interface of the Gnss_Satellite class	1941
gnss_signal.h	Implementation of the Gnss_Signal class	1942
gnss_synchro.h	Interface of the Gnss_Synchro class	1944
gps_acq_assist.h	Interface of a GPS RRLL ACQUISITION ASSISTACE storage	1947
gps_almanac.h	Interface of a GPS ALMANAC storage	1948
GPS_CNAV.h	Defines parameters for GPS CNAV	1950
gps_cnav_ephemeris.h	Interface of a GPS CNAV EPHEMERIS storage	1954
gps_cnav_iono.h	Interface of a GPS CNAV IONOSPHERIC MODEL storage	1956
gps_cnav_navigation_message.h	Interface of a GPS CNAV Data message decoder	1957
gps_cnav_utc_model.h	Interface of a GPS CNAV UTC MODEL storage	1960
gps_ephemeris.h	Interface of a GPS EPHEMERIS storage	1960
gps_iono.h	Interface of a GPS IONOSPHERIC MODEL storage	1963
GPS_L1_CA.h	Defines system parameters for GPS L1 C/A signal and NAV data	1964
GPS_L2C.h	Defines system parameters for GPS L2C signal	1971
GPS_L5.h	Defines system parameters for GPS L5 signal	1974
gps_navigation_message.h	Interface of a GPS NAV Data message decoder	1977
gps_utc_model.h	Interface of a GPS UTC MODEL storage	1981
MATH_CONSTANTS.h	Defines useful mathematical constants and their scaled versions	1983
osnma_data.h	Class for Galileo OSNMA data storage	1988
osnma_dsm_reader.h	Class for reading OSNMA DSM messages	1991
qzss.h	Defines system parameters for QZSS signals	1993
reed_solomon.h	Class implementing a Reed-Solomon encoder/decoder for blocks of 255 symbols and symbols of 8 bits	1994
sbas_ephemeris.h	Interface of a SBAS REFERENCE LOCATION storage	1997
tow_to_trk.h	Class to inform about TOW from Telemetry to Tracking blocks	1998

Chapter 10

Topic Documentation

10.1 Acquisition

Topics

- [acquisition_adapters](#)
- [acquisition_gr_blocks](#)
- [acquisition_libs](#)

10.1.1 Detailed Description

Classes for GNSS signal acquisition

Classes for GNSS signal acquisition

Classes for GNSS signal acquisition

Classes for GNSS signal acquisition

Classes for GNSS signal acquisition

10.1.2 acquisition_adapters

Classes

- class [BasePcpsAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#).
- class [ThresholdComputeInterface](#)
- class [ThresholdComputeBasic](#)
- class [ThresholdComputeDoppler](#)
- class [ThresholdComputeQuickSync](#)
- class [BasePcpsAcquisitionCustom](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#).
- class [BasePcpsAcquisitionFpga](#)
Base class providing shared logic for FPGA-based GPS PCPS acquisition adapters.

- class [BeidouB1iPcpsAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.
- class [BeidouB3iPcpsAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for BeiDou B3I signals.
- class [GalileoE1Pcps8msAmbiguousAcquisition](#)
Adapts a PCPS 8ms acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.
- class [GalileoE1PcpsAmbiguousAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.
- class [GalileoE1PcpsAmbiguousAcquisitionFpga](#)
This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for Galileo E1 Signals.
- class [GalileoE1PcpsCccwsrAmbiguousAcquisition](#)
Adapts a PCPS CCCWSR acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.
- class [GalileoE1PcpsQuickSyncAmbiguousAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.
- class [GalileoE1PcpsTongAmbiguousAcquisition](#)
Adapts a PCPS Tong acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.
- class [GalileoE5aNoncoherentIQAcquisitionCaf](#)
- class [GalileoE5aPcpsAcquisition](#)
- class [GalileoE5aPcpsAcquisitionFpga](#)
This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for Galileo E5a signals.
- class [GalileoE5bPcpsAcquisition](#)
- class [GalileoE5bPcpsAcquisitionFpga](#)
This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for Galileo E5b signals.
- class [GalileoE6PcpsAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E6 Signals.
- class [GlonassL1CaPcpsAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.
- class [GlonassL2CaPcpsAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GLONASS L2 C/A signals.
- class [GpsL1CaPcpsAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.
- class [GpsL1CaPcpsAcquisitionFineDoppler](#)
This class Adapts a PCPS acquisition block with fine Doppler estimation to an [AcquisitionInterface](#) for GPS L1 C/A signals.
- class [GpsL1CaPcpsAcquisitionFpga](#)
This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for GPS L1 C/A signals.
- class [GpsL1CaPcpsAssistedAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.
- class [GpsL1CaPcpsOpenCLAcquisition](#)
This class adapts an OpenCL PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.
- class [GpsL1CaPcpsQuickSyncAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.
- class [GpsL1CaPcpsTongAcquisition](#)
This class adapts a PCPS Tong acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.
- class [GpsL2MPcpsAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L2 M signals.
- class [GpsL2MPcpsAcquisitionFpga](#)
This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for GPS L2 M signals.
- class [GpsL5iPcpsAcquisition](#)
This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L5i signals.
- class [GpsL5iPcpsAcquisitionFpga](#)

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for GPS L5i signals.

- class [QzssL1PcpsAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for QZSS L1 signals.

- class [QzssL5iPcpsAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for QZSS L5I signals.

10.1.2.1 Detailed Description

Wrap GNU Radio acquisition blocks with an [AcquisitionInterface](#)

Wrap GNU Radio acquisition blocks with an [AcquisitionInterface](#)

Wrap GNU Radio acquisition blocks with an [AcquisitionInterface](#)

Wrap GNU Radio acquisition blocks with an [AcquisitionInterface](#)

10.1.3 acquisition_gr_blocks

Classes

- class [galileo_e5a_noncoherentIQ_acquisition_caf_cc](#)

This class implements a Parallel Code Phase Search Acquisition.

- class [galileo_pcps_8ms_acquisition_cc](#)

This class implements a Parallel Code Phase Search Acquisition for Galileo E1 signals with coherent integration time = 8 ms (two codes)

- class [pcps_acquisition](#)

This class implements a Parallel Code Phase Search Acquisition.

- class [pcps_acquisition_fine_doppler_cc](#)

This class implements a Parallel Code Phase Search Acquisition.

- class [pcps_acquisition_fpga](#)

This class implements a Parallel Code Phase Search Acquisition that uses the FPGA.

- class [pcps_assisted_acquisition_cc](#)

This class implements a Parallel Code Phase Search Acquisition.

- class [pcps_cccwsr_acquisition_cc](#)

This class implements a Parallel Code Phase Search Acquisition with Coherent [Channel](#) Combining With Sign Recovery scheme.

- class [pcps_openc1_acquisition_cc](#)

This class implements a Parallel Code Phase Search Acquisition.

- class [pcps_quicksync_acquisition_cc](#)

This class implements a Parallel Code Phase Search Acquisition with the implementation of the Sparse QuickSync Algorithm.

- class [pcps_tong_acquisition_cc](#)

This class implements a Parallel Code Phase Search Acquisition with Tong algorithm.

Typedefs

- using [galileo_e5a_noncoherentIQ_acquisition_caf_cc_sptr](#) = gnss_shared_ptr<[galileo_e5a_noncoherentIQ_acquisition_caf_cc](#)>
- using [galileo_pcps_8ms_acquisition_cc_sptr](#) = gnss_shared_ptr<[galileo_pcps_8ms_acquisition_cc](#)>
- using [pcps_acquisition_sptr](#) = gnss_shared_ptr<[pcps_acquisition](#)>
- using [pcps_acquisition_fine_doppler_cc_sptr](#) = gnss_shared_ptr<[pcps_acquisition_fine_doppler_cc](#)>
- using [pcps_acquisition_fpga_sptr](#) = std::shared_ptr<[pcps_acquisition_fpga](#)>
- using [pcps_assisted_acquisition_cc_sptr](#) = gnss_shared_ptr<[pcps_assisted_acquisition_cc](#)>
- using [pcps_cccwsr_acquisition_cc_sptr](#) = gnss_shared_ptr<[pcps_cccwsr_acquisition_cc](#)>
- using [pcps_opencl_acquisition_cc_sptr](#) = gnss_shared_ptr<[pcps_opencl_acquisition_cc](#)>
- using [pcps_quicksync_acquisition_cc_sptr](#) = gnss_shared_ptr<[pcps_quicksync_acquisition_cc](#)>
- using [pcps_tong_acquisition_cc_sptr](#) = gnss_shared_ptr<[pcps_tong_acquisition_cc](#)>

Functions

- [galileo_e5a_noncoherentIQ_acquisition_caf_cc_sptr](#) **galileo_e5a_noncoherentIQ_make_acquisition_caf_cc** (const [Acq_Conf](#) &conf, bool both_signal_components, int CAF_window_hz, int Zero_padding)
- [galileo_pcps_8ms_acquisition_cc_sptr](#) **galileo_pcps_8ms_make_acquisition_cc** (const [Acq_Conf](#) &conf)
- [pcps_acquisition_sptr](#) **pcps_make_acquisition** (const [Acq_Conf](#) &conf_)
- [pcps_acquisition_fine_doppler_cc_sptr](#) **pcps_make_acquisition_fine_doppler_cc** (const [Acq_Conf](#) &conf_)
- [pcps_acquisition_fpga_sptr](#) **pcps_make_acquisition_fpga** ([Acq_Conf_Fpga](#) *conf_, uint32_t acq_buff_num, std::vector< std::pair< uint32_t, uint32_t > > &downsampling_filter_specs, uint32_t &max_FFT_size)
- [pcps_assisted_acquisition_cc_sptr](#) **pcps_make_assisted_acquisition_cc** (const [Acq_Conf](#) &conf)
- [pcps_cccwsr_acquisition_cc_sptr](#) **pcps_cccwsr_make_acquisition_cc** (const [Acq_Conf](#) &conf)
- [pcps_opencl_acquisition_cc_sptr](#) **pcps_make_opencl_acquisition_cc** (const [Acq_Conf](#) &conf, uint32_t max_dwells)
- [pcps_quicksync_acquisition_cc_sptr](#) **pcps_quicksync_make_acquisition_cc** (const [Acq_Conf](#) &conf, uint32_t folding_factor, uint32_t max_dwells)
- [pcps_tong_acquisition_cc_sptr](#) **pcps_tong_make_acquisition_cc** (const [Acq_Conf](#) &conf, uint32_t tong_init_val, uint32_t tong_max_val, uint32_t tong_max_dwells)

10.1.3.1 Detailed Description

GNU Radio processing blocks for GNSS signal acquisition

10.1.3.2 Typedef Documentation

10.1.3.2.1 [galileo_e5a_noncoherentIQ_acquisition_caf_cc_sptr](#)

```
using galileo_e5a_noncoherentIQ_acquisition_caf_cc_sptr = gnss_shared_ptr<galileo\_e5a\_noncoherentIQ\_acquisition\_caf\_cc>
```

Definition at line 48 of file [galileo_e5a_noncoherent_iq_acquisition_caf_cc.h](#).

10.1.3.2.2 [galileo_pcps_8ms_acquisition_cc_sptr](#)

```
using galileo_pcps_8ms_acquisition_cc_sptr = gnss_shared_ptr<galileo\_pcps\_8ms\_acquisition\_cc>
```

Definition at line 42 of file [galileo_pcps_8ms_acquisition_cc.h](#).

10.1.3.2.3 pcps_acquisition_fine_doppler_cc_sptr

```
using pcps_acquisition_fine_doppler_cc_sptr = gnss_shared_ptr<pcps_acquisition_fine_doppler_cc>
```

Definition at line 66 of file [pcps_acquisition_fine_doppler_cc.h](#).

10.1.3.2.4 pcps_acquisition_fpga_sptr

```
using pcps_acquisition_fpga_sptr = std::shared_ptr<pcps_acquisition_fpga>
```

Definition at line 48 of file [pcps_acquisition_fpga.h](#).

10.1.3.2.5 pcps_acquisition_sptr

```
using pcps_acquisition_sptr = gnss_shared_ptr<pcps_acquisition>
```

Definition at line 83 of file [pcps_acquisition.h](#).

10.1.3.2.6 pcps_assisted_acquisition_cc_sptr

```
using pcps_assisted_acquisition_cc_sptr = gnss_shared_ptr<pcps_assisted_acquisition_cc>
```

Definition at line 58 of file [pcps_assisted_acquisition_cc.h](#).

10.1.3.2.7 pcps_cccwsr_acquisition_cc_sptr

```
using pcps_cccwsr_acquisition_cc_sptr = gnss_shared_ptr<pcps_cccwsr_acquisition_cc>
```

Definition at line 47 of file [pcps_cccwsr_acquisition_cc.h](#).

10.1.3.2.8 pcps_opencl_acquisition_cc_sptr

```
using pcps_opencl_acquisition_cc_sptr = gnss_shared_ptr<pcps_opencl_acquisition_cc>
```

Definition at line 65 of file [pcps_opencl_acquisition_cc.h](#).

10.1.3.2.9 pcps_quicksync_acquisition_cc_sptr

```
using pcps_quicksync_acquisition_cc_sptr = gnss_shared_ptr<pcps_quicksync_acquisition_cc>
```

Definition at line 62 of file [pcps_quicksync_acquisition_cc.h](#).

10.1.3.2.10 pcps_tong_acquisition_cc_sptr

```
using pcps_tong_acquisition_cc_sptr = gnss_shared_ptr<pcps_tong_acquisition_cc>
```

Definition at line 61 of file [pcps_tong_acquisition_cc.h](#).

10.1.4 acquisition_libs

Classes

- class [Acq_Conf](#)
- class [Acq_Conf_Fpga](#)
- class [Fpga_Acquisition](#)

Class that implements carrier wipe-off and correlators.

10.1.4.1 Detailed Description

Library with utilities for GNSS signal acquisition

Library with utilities for GNSS signal acquisition

10.2 Core GNSS Receiver

Header file of the interface to a signal_source GNSS block.

Topics

- [GNSS block interfaces](#)
- [core_libs](#)
- [core_monitor](#)
- [core_receiver](#)
- [core_system_parameters](#)

10.2.1 Detailed Description

Header file of the interface to a signal_source GNSS block.

\signal_source_interface.h

Author

Jim Melton, 2020. [jim.melton\(at\)sncorp.com](mailto:jim.melton@sncorp.com)

This header file contains the interface to an abstract class for signal sources. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

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GNSS-SDR is a software defined Global Navigation Satellite Systems receiver

This file is part of GNSS-SDR.

SPDX-License-Identifier: GPL-3.0-or-later

Core GNSS Receiver.

10.2.2 GNSS block interfaces

Classes

- class [acquisition_impl_interface](#)
This abstract class represents an interface to an acquisition GNSS block.
- class [Concurrent_Queue< Data >](#)
This class implements a thread-safe std::queue.
- class [AcquisitionInterface](#)
This abstract class represents an interface to an acquisition GNSS block.
- class [ChannelInterface](#)
This abstract class represents an interface to a channel GNSS block.
- class [ConfigurationInterface](#)
This abstract class represents an interface to configuration parameters.
- class [GNSSBlockInterface](#)
This abstract class represents an interface to GNSS blocks.
- class [ObservablesInterface](#)
This abstract class represents an interface to an observables block.
- class [PvtInterface](#)
This class represents an interface to a PVT block.
- class [SignalSourceInterface](#)
This abstract class represents an interface to signal_source GNSS block.
- class [TelemetryDecoderInterface](#)
This abstract class represents an interface to a navigation GNSS block.
- class [TrackingInterface](#)
This abstract class represents an interface to a tracking block.

Typedefs

- using [acquisition_impl_interface_sptr](#) = gnss_shared_ptr<[acquisition_impl_interface](#)>
- template<typename T>
using [gnss_shared_ptr](#) = boost::shared_ptr<T>

Functions

- template<typename C, typename... Args>
gnss_shared_ptr< C > [gnss_make_shared](#) (Args &&... args)
- virtual size_t [SignalSourceInterface::getRfChannels](#) () const =0

10.2.2.1 Detailed Description

GNSS block interfaces.
GNSS block interfaces.
GNSS block interfaces.

10.2.2.2 Typedef Documentation

10.2.2.2.1 acquisition_impl_interface_sptr

using [acquisition_impl_interface_sptr](#) = gnss_shared_ptr<[acquisition_impl_interface](#)>
Definition at line 41 of file [acquisition_impl_interface.h](#).

10.2.2.2.2 gnss_shared_ptr

template<typename T>
using [gnss_shared_ptr](#) = boost::shared_ptr<T>
Definition at line 50 of file [gnss_block_interface.h](#).

10.2.2.3 Function Documentation

10.2.2.3.1 gnss_make_shared()

```
template<typename C, typename... Args>
gnss_shared_ptr< C > gnss_make_shared (
    Args &&... args)
```

Definition at line 52 of file [gnss_block_interface.h](#).

10.2.2.3.2 SignalSourceInterface()

```
SignalSourceInterface::SignalSourceInterface () [inline], [protected]
```

Definition at line 57 of file [signal_source_interface.h](#).

10.2.2.3.3 ~SignalSourceInterface()

```
SignalSourceInterface::~SignalSourceInterface () [inline]
```

Definition at line 63 of file [signal_source_interface.h](#).

10.2.3 core_libs

Classes

- class [Channel_Event](#)
- class [channel_status_msg_receiver](#)
 - GNU Radio block that receives asynchronous channel messages from tlm blocks.*
- class [Command_Event](#)
- class [galileo_e6_has_msg_receiver](#)
 - GNU Radio block that receives asynchronous Galileo HAS message pages from the telemetry blocks, stores them in memory, and decodes HAS messages when enough data have been received. The decoded HAS message is sent to the PVT block.*
- class [galileo_tow_map](#)
- class [Gnss_Crypto](#)
 - Class implementing cryptographic functions for Navigation Message Authentication.*
- class [gnss_sdr_fpga_sample_counter](#)
- class [gnss_sdr_sample_counter](#)
- class [Gnss_Sdr_Supl_Client](#)
 - class that implements a C++ interface to external Secure User Location Protocol (SUPL) client library..*
- class [gnss_sdr_time_counter](#)
- class [INIReader](#)
 - Read an INI file into easy-to-access name/value pairs. (Note that I've gone for simplicity here rather than speed, but it should be pretty decent.)*
- class [nav_message_monitor](#)
 - GNU Radio block that receives asynchronous [Nav_Message_Packet](#) objects from the telemetry blocks and sends them via UDP.*
- class [Nav_Message_Packet](#)
- class [Nav_Message_Udp_Sink](#)
- class [Osnma_Helper](#)
- class [osnma_msg_receiver](#)
 - GNU Radio block that receives asynchronous OSNMA messages from the telemetry blocks, stores them in memory, and decodes OSNMA info when enough data have been received. The decoded OSNMA data is sent to the PVT block.*
- class [OSNMA_NavDataManager](#)
 - Class for managing OSNMA navigation data.*
- class [StringConverter](#)
 - Class that interprets the contents of a string and converts it into different types.*

Macros

- `#define INI_ALLOW_MULTILINE 1`

Typedefs

- using `channel_event_sptr` = `std::shared_ptr<Channel_Event>`
- using `channel_status_msg_receiver_sptr` = `gnss_shared_ptr<channel_status_msg_receiver>`
- using `command_event_sptr` = `std::shared_ptr<Command_Event>`
- using `galileo_e6_has_msg_receiver_sptr` = `gnss_shared_ptr<galileo_e6_has_msg_receiver>`
- using `galileo_tow_map_sptr` = `gnss_shared_ptr<galileo_tow_map>`
- using `gnss_sdr_fpga_sample_counter_sptr` = `gnss_shared_ptr<gnss_sdr_fpga_sample_counter>`
- using `gnss_sdr_sample_counter_sptr` = `gnss_shared_ptr<gnss_sdr_sample_counter>`
- using `gnss_sdr_time_counter_sptr` = `std::shared_ptr<gnss_sdr_time_counter>`
- using `nav_message_monitor_sptr` = `gnss_shared_ptr<nav_message_monitor>`
- using `b_io_context` = `boost::asio::io_service`
- using `osnma_msg_receiver_sptr` = `gnss_shared_ptr<osnma_msg_receiver>`

Functions

- `channel_event_sptr channel_event_make` (int channel_id, int event_type)
- `channel_status_msg_receiver_sptr channel_status_msg_receiver_make` ()
- `command_event_sptr command_event_make` (int command_id, int event_type)
- `galileo_e6_has_msg_receiver_sptr galileo_e6_has_msg_receiver_make` ()
- `galileo_tow_map_sptr galileo_tow_map_make` ()
- `gnss_sdr_fpga_sample_counter_sptr gnss_sdr_make_fpga_sample_counter` (double fs, int32_t interval_ms)
- `gnss_sdr_sample_counter_sptr gnss_sdr_make_sample_counter` (double fs, int32_t interval_ms, size_t size)
- `gnss_sdr_time_counter_sptr gnss_sdr_make_time_counter` ()
- `int ini_parse` (const char *filename, int(*handler)(void *user, const char *section, const char *name, const char *value), void *user)
Parse given INI-style file. May have [section]s, name=value pairs (whitespace stripped), and comments starting with ';' (semicolon). Section is "" if name=value pair parsed before any section heading.
- `nav_message_monitor_sptr nav_message_monitor_make` (const std::vector< std::string > &addresses, uint16_t port)
- `osnma_msg_receiver_sptr osnma_msg_receiver_make` (const std::string &pemFilePath, const std::string &merkleFilePath, bool strict_mode=false)
- `const std::string uio_dir` ("/sys/class/uio/")
- `const std::string uio_filename` ("uio")
- `const std::string uio_subdir_name` ("/name")
- `int32_t find_uio_dev_file_name` (std::string &device_file_name, const std::string &device_name, uint32_t device_num)
This function finds the uio device driver device file name out of the device name and the device number.
- `uint32_t get_num_devices` (const std::string &device_name)
Returns the number of devices (tracking multicorrelators) of type device_name available in the FPGA.

10.2.3.1 Detailed Description

Utilities for the core GNSS receiver.

10.2.3.2 Macro Definition Documentation

10.2.3.2.1 INI_ALLOW_MULTILINE

```
#define INI_ALLOW_MULTILINE 1
```

Definition at line 65 of file `ini.h`.

10.2.3.3 Typedef Documentation

10.2.3.3.1 b_io_context

using b_io_context = boost::asio::io_service
Definition at line 36 of file [nav_message_udp_sink.h](#).

10.2.3.3.2 channel_event_sptr

using channel_event_sptr = std::shared_ptr<Channel_Event>
Definition at line 30 of file [channel_event.h](#).

10.2.3.3.3 channel_status_msg_receiver_sptr

using channel_status_msg_receiver_sptr = gnss_shared_ptr<channel_status_msg_receiver>
Definition at line 37 of file [channel_status_msg_receiver.h](#).

10.2.3.3.4 command_event_sptr

using command_event_sptr = std::shared_ptr<Command_Event>
Definition at line 30 of file [command_event.h](#).

10.2.3.3.5 galileo_e6_has_msg_receiver_sptr

using galileo_e6_has_msg_receiver_sptr = gnss_shared_ptr<galileo_e6_has_msg_receiver>
Definition at line 46 of file [galileo_e6_has_msg_receiver.h](#).

10.2.3.3.6 galileo_tow_map_sptr

using galileo_tow_map_sptr = gnss_shared_ptr<galileo_tow_map>
Definition at line 34 of file [galileo_tow_map.h](#).

10.2.3.3.7 gnss_sdr_fpga_sample_counter_sptr

using gnss_sdr_fpga_sample_counter_sptr = gnss_shared_ptr<gnss_sdr_fpga_sample_counter>
Definition at line 36 of file [gnss_sdr_fpga_sample_counter.h](#).

10.2.3.3.8 gnss_sdr_sample_counter_sptr

using gnss_sdr_sample_counter_sptr = gnss_shared_ptr<gnss_sdr_sample_counter>
Definition at line 36 of file [gnss_sdr_sample_counter.h](#).

10.2.3.3.9 gnss_sdr_time_counter_sptr

using gnss_sdr_time_counter_sptr = std::shared_ptr<gnss_sdr_time_counter>
Definition at line 34 of file [gnss_sdr_time_counter.h](#).

10.2.3.3.10 nav_message_monitor_sptr

using nav_message_monitor_sptr = gnss_shared_ptr<nav_message_monitor>
Definition at line 37 of file [nav_message_monitor.h](#).

10.2.3.3.11 osnma_msg_receiver_sptr

using osnma_msg_receiver_sptr = gnss_shared_ptr<osnma_msg_receiver>
Definition at line 51 of file [osnma_msg_receiver.h](#).

10.2.3.4 Function Documentation

10.2.3.4.1 find_uio_dev_file_name()

```
int32_t find_uio_dev_file_name (
    std::string & device_file_name,
    const std::string & device_name,
    uint32_t device_num)
```

This function finds the uio device driver device file name out of the device name and the device number.

10.2.3.4.2 get_num_devices()

```
uint32_t get_num_devices (
    const std::string & device_name)
```

Returns the number of devices (tracking multicorrelators) of type device_name available in the FPGA.

10.2.3.4.3 ini_parse()

```
int ini_parse (
    const char * filename,
    int(* handler ) (void *user, const char *section, const char *name, const char
    *value),
    void * user)
```

Parse given INI-style file. May have [section]s, name=value pairs (whitespace stripped), and comments starting with ';' (semicolon). Section is "" if name=value pair parsed before any section heading.

For each name=value pair parsed, call handler function with given user pointer as well as section, name, and value (data only valid for duration of handler call). Handler should return nonzero on success, zero on error.

Returns 0 on success, line number of first error on parse error, on -1 on file open error.

10.2.4 core_monitor

Classes

- class [gnss_synchro_monitor](#)

This class implements a monitoring block which allows sending a data stream with the receiver internal parameters ([Gnss_Synchro](#) objects) to local or remote clients over UDP.

- class [Gnss_Synchro_Udp_Sink](#)

This class sends serialized [Gnss_Synchro](#) objects over UDP to one or multiple endpoints.

Typedefs

- using [gnss_synchro_monitor_sptr](#) = [gnss_shared_ptr](#)<[gnss_synchro_monitor](#)>
- using [b_io_context](#) = [boost::asio::io_service](#)

Functions

- [gnss_synchro_monitor_sptr](#) **gnss_synchro_make_monitor** (int n_channels, int decimation_factor, const std::vector< std::string > &udp_ports, const std::vector< std::string > &udp_addresses, bool enable_↵ protobuf)

10.2.4.1 Detailed Description

Classes for the [Gnss_Synchro](#) monitor.

10.2.4.2 Typedef Documentation

10.2.4.2.1 b_io_context

```
using b_io_context = boost::asio::io_service
```

Definition at line 38 of file [gnss_synchro_udp_sink.h](#).

10.2.4.2.2 gnss_synchro_monitor_sptr

using gnss_synchro_monitor_sptr = gnss_shared_ptr<gnss_synchro_monitor>
 Definition at line 40 of file [gnss_synchro_monitor.h](#).

10.2.5 core_receiver

Classes

- class [Concurrent_Map< Data >](#)
This class implements a thread-safe std::map.
- class [Concurrent_Queue< Data >](#)
This class implements a thread-safe std::queue.
- class [ControlThread](#)
This class represents the main thread of the application, so the name is [ControlThread](#). This is the GNSS Receiver Control Plane: it connects the flowgraph, starts running it, and while it does not stop, reads the control messages generated by the blocks, processes them, and applies the corresponding actions.
- class [FileConfiguration](#)
This class is an implementation of the interface [ConfigurationInterface](#).
- class [GNSSBlockFactory](#)
Class that produces all kinds of GNSS blocks.
- class [GNSSFlowgraph](#)
This class represents a GNSS flow graph.
- class [InMemoryConfiguration](#)
This class is an implementation of the interface [ConfigurationInterface](#).
- class [TcpCmdInterface](#)

10.2.5.1 Detailed Description

Classes for the core GNSS receiver.

10.2.6 core_system_parameters

Classes

- class [Agnss_Ref_Location](#)
Interface of an Assisted GNSS REFERENCE LOCATION storage.
- class [Agnss_Ref_Time](#)
Interface of an Assisted GNSS REFERENCE TIME storage.
- class [Beidou_Dnav_Almanac](#)
This class is a storage for the BeiDou D1 almanac.
- class [Beidou_Dnav_Ephemeris](#)
This is a storage class for the Beidou SV ephemeris data as described in BeiDou Navigation Satellite System Signal In Space Interface Control Document Open Service Signal B1I (Version 3.0)
- class [Beidou_Dnav_Iono](#)
This class is a storage for the BEIDOU IONOSPHERIC data as described in ICD v2.1.
- class [Beidou_Dnav_Navigation_Message](#)
This class decodes a BeiDou D1 NAV Data message.
- class [Beidou_Dnav_Utc_Model](#)
This class is a storage for the BeiDou DNAV UTC Model.
- class [Galileo_Almanac](#)
This class is a storage for the Galileo SV ALMANAC data.
- class [Galileo_Almanac_Helper](#)
This class is a storage for the GALILEO ALMANAC data as described in GALILEO ICD.
- class [Galileo_Cnav_Message](#)

This class handles the Galileo CNAV Data message, as described in the Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022.

- class [Galileo_Ephemeris](#)

This class is a storage and orbital model functions for the Galileo SV ephemeris data as described in Galileo ICD paragraph 5.1.1.

- class [Galileo_Fnav_Message](#)

This class handles the Galileo F/NAV Data message, as described in the Galileo Open Service Signal in Space Interface Control Document (OS SIS ICD), Issue 2.0 (Jan. 2021). See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf.

- struct [mt1_header](#)

- class [Galileo_HAS_data](#)

This class is a storage for Galileo HAS message type 1, as defined in Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022. See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_HAS_SIS_ICD_v1.0.pdf.

- class [Galileo_HAS_page](#)

This class is a storage for Galileo HAS message page, as defined in Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022.

- class [OSNMA_msg](#)

This class fills the [OSNMA_msg](#) structure with the data received from the telemetry blocks.

- class [Galileo_Inav_Message](#)

This class handles the Galileo I/NAV Data message, as described in the Galileo Open Service Signal in Space Interface Control Document (OS SIS ICD), Issue 2.0 (Jan. 2021). See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf.

- class [Galileo_Iono](#)

This class is a storage for the GALILEO IONOSPHERIC data as described in Galileo ICD paragraph 5.1.6.

- class [Galileo_ISM](#)

This class is a storage for the GALILEO Integrity Support Message as described in Galileo ICD paragraph 5.2.

- class [Mack_lookup](#)

- class [Galileo_Reduced_CED](#)

This class manages the Galileo Reduced Clock and Ephemeris Data.

- class [Galileo_Utc_Model](#)

This class is a storage for the GALILEO UTC MODEL data as described in Galileo ICD https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf paragraph 5.1.7.

- class [Glonass_Gnav_Almanac](#)

This class is a storage for the GLONASS SV ALMANAC data as described GLONASS ICD (Edition 5.1)

- class [Glonass_Gnav_Ephemeris](#)

This class is a storage and orbital model functions for the GLONASS SV ephemeris data as described in GLONASS ICD (Edition 5.1)

- class [Glonass_Gnav_Navigation_Message](#)

This class decodes a GLONASS GNAV Data message as described in GLONASS ICD (Edition 5.1)

- class [Glonass_Gnav_Utc_Model](#)

This class is a storage for the GLONASS GNAV UTC MODEL data as described in GLONASS ICD (Edition 5.1)

- class [Gnss_Almanac](#)

Base class for GNSS almanac storage.

- class [Gnss_Satellite](#)

This class represents a GNSS satellite.

- class [Gnss_Signal](#)

This class represents a GNSS signal.

- class [Gnss_Synchro](#)

This is the class that contains the information that is shared by the processing blocks.

- class [Gps_Acq_Assist](#)

This class is a storage for the GPS GSM RRLP acquisition assistance data as described in Digital cellular telecommunications system (Phase 2+); Location Services (LCS); Mobile Station (MS) - Serving Mobile Location Centre (SMLC) Radio Resource LCS Protocol (RRLP) (3GPP TS 44.031 version 5.12.0 Release 5)

- class [Gps_Almanac](#)

This class is a storage for the GPS SV ALMANAC data as described in IS-GPS-200M.

- class [Gps_CNAV_Ephemeris](#)

This is a storage class for the GPS CNAV ephemeris data as described in IS-GPS-200M.

- class [Gps_CNAV_Iono](#)

This class is a storage for the GPS IONOSPHERIC data as described in IS-GPS-200M.

- class [Gps_CNAV_Navigation_Message](#)

This class decodes a GPS CNAV Data message as described in IS-GPS-200M.

- class [Gps_CNAV_Utc_Model](#)

This class is a storage for the GPS UTC MODEL data as described in in IS-GPS-200M.

- class [Gps_Ephemeris](#)

This class is a storage and orbital model functions for the GPS SV ephemeris data as described in IS-GPS-200M.

- class [Gps_Iono](#)

This class is a storage for the GPS IONOSPHERIC data as described in IS-GPS-200M.

- class [Gps_Navigation_Message](#)

This class decodes a GPS NAV Data message as described in IS-GPS-200M.

- class [Gps_Utc_Model](#)

This class is a storage for the GPS UTC MODEL data as described in IS-GPS-200M.

- class [DSM_nma_header](#)

- class [DSM_dsm_header](#)

- class [MACK_header](#)

- class [MACK_tag_info](#)

- class [MACK_tag_and_info](#)

- class [DSM_PKR_message](#)

- class [DSM_KROOT_message](#)

- class [MACK_message](#)

- class [OSNMA_NavData](#)

- class [OSNMA_data](#)

This class handles OSNMA data See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OSNMA_User_ICD_for_Test_Phase_v1.0.pdf.

- class [Tag](#)

- class [OSNMA_DSM_Reader](#)

- class [ReedSolomon](#)

Class implementing a Reed-Solomon encoder and decoder $RS(255,K,d)$ where $k=255-nroots$ is the information vector length and $d=nroots+1$ is the minimum Hamming distance, with symbols of 8 bits. It allows shortened RS codes.

- class [Sbas_Ephemeris](#)

This class stores SBAS SV ephemeris data.

- class [TOW_to_trk](#)

Macros

- `#define DISPLAY_COLORS 1`
- `#define GLONASS_GNAV_PREAMBLE`
- `#define GLONASS_GNAV_PREAMBLE_SAMPLES`

Enumerations

- enum class **CnavSystem** { **GPS** , **QZSS** }
- enum class **LnavSystem** { **GPS** , **QZSS** }

Functions

- `const std::vector< std::pair< int32_t, int32_t > > D1_PRE {{{1, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_FRAID {{{16, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_SOW {{{19, 8}, {31, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_PNUM {{{44, 7}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_SAT_H1 {{{43, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_AODC {{{44, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_URAI {{{49, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_WN {{{61, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TOC {{{74, 9}, {91, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TGD1 {{{99, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TGD2 {{{109, 4}, {121, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_ALPHA0 {{{127, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_ALPHA1 {{{135, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_ALPHA2 {{{151, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_ALPHA3 {{{159, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_BETA0 {{{167, 6}, {181, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_BETA1 {{{183, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_BETA2 {{{191, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_BETA3 {{{199, 4}, {211, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A2 {{{215, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A0 {{{226, 7}, {241, 17}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A1 {{{258, 5}, {271, 17}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_AODE {{{288, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_DELTA_N {{{43, 10}, {61, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_CUC {{{67, 16}, {91, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_M0 {{{93, 20}, {121, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_E {{{133, 10}, {151, 22}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_CUS {{{181, 18}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_CRC {{{199, 4}, {211, 14}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_CRS {{{225, 8}, {241, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_SQRT_A {{{251, 12}, {271, 20}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TOE_SF2 {{{291, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TOE_SF3 {{{43, 10}, {61, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_I0 {{{66, 17}, {91, 15}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_CIC {{{106, 7}, {121, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_OMEGA_DOT {{{132, 11}, {151, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_CIS {{{164, 9}, {181, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_IDOT {{{190, 13}, {211, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_OMEGA0 {{{212, 21}, {241, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_OMEGA {{{252, 11}, {271, 21}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_SQRT_A_ALMANAC {{{51, 2}, {61, 22}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A1_ALMANAC {{{91, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A0_ALMANAC {{{102, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_OMEGA0_ALMANAC {{{121, 22}, {151, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_E_ALMANAC {{{153, 17}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_DELTA_I {{{170, 3}, {181, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TOA {{{194, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_OMEGA_DOT_ALMANAC {{{202, 1}, {211, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_OMEGA_ALMANAC {{{227, 6}, {241, 18}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_M0_ALMANAC {{{259, 4}, {271, 20}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA1 {{{51, 2}, {61, 7}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA2 {{{68, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA3 {{{77, 6}, {91, 3}}}`

- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA4 {{{94, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA5 {{{103, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA6 {{{112, 1}, {121, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA7 {{{129, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA8 {{{138, 5}, {151, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA9 {{{155, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA10 {{{164, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA11 {{{181, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA12 {{{190, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA13 {{{199, 4}, {211, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA14 {{{216, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA15 {{{225, 8}, {241, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA16 {{{242, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA17 {{{251, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA18 {{{260, 3}, {271, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA19 {{{277, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA20 {{{51, 2}, {61, 7}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA21 {{{68, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA22 {{{77, 6}, {91, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA23 {{{94, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA24 {{{103, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA25 {{{112, 1}, {121, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA26 {{{129, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA27 {{{138, 5}, {151, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA28 {{{155, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA29 {{{164, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA30 {{{181, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_WNA {{{190, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TOA2 {{{198, 5}, {211, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A0GPS {{{97, 14}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A1GPS {{{111, 2}, {121, 14}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A0GAL {{{135, 8}, {151, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A1GAL {{{157, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A0GLO {{{181, 14}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A1GLO {{{195, 8}, {211, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_DELTA_T_LS {{{51, 2}, {61, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_DELTA_T_LSF {{{67, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_WN_LSF {{{75, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A0UTC {{{91, 22}, {121, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A1UTC {{{131, 12}, {151, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_DN {{{163, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_PRE {{{1, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_FRAID {{{16, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_SOW {{{19, 8}, {31, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_PNUM {{{43, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_SAT_H1 {{{47, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_AODC {{{48, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_URAI {{{61, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_WN {{{65, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_TOC {{{78, 5}, {91, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_TGD1 {{{103, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_TGD2 {{{121, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_ALPHA0 {{{47, 6}, {61, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_ALPHA1 {{{63, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_ALPHA2 {{{71, 8}}}`

- `const std::vector< std::pair< int32_t, int32_t > > D2_ALPHA3 ({79, 4}, {91, 4})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_BETA0 ({95, 8})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_BETA1 ({103, 8})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_BETA2 ({111, 2}, {121, 6})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_BETA3 ({127, 8})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_A0 ({101, 12}, {121, 12})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_A1_MSB ({133, 4})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_A1_LSB ({47, 6}, {61, 12})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_A1 ({279, 22})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_A2 ({73, 10}, {91, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_AODE ({92, 5})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_DELTA_N ({97, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_CUC_MSB ({121, 14})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_CUC_LSB ({47, 4})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_CUC ({283, 18})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_M0 ({51, 2}, {61, 22}, {91, 8})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_CUS ({99, 14}, {121, 4})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_E_MSB ({125, 10})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_E_LSB ({47, 6}, {61, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_SQRT_A ({77, 6}, {91, 22}, {121, 4})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_CIC_MSB ({125, 10})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_CIC_LSB ({47, 6}, {61, 2})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_CIC ({283, 18})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_CIS ({63, 18})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_TOE ({81, 2}, {91, 15})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_I0_MSB ({106, 7}, {121, 14})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_I0_LSB ({47, 6}, {61, 5})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_I0 ({269, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_CRC ({66, 17}, {91, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_CRS ({92, 18})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA_DOT_MSB ({110, 3}, {121, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA_DOT_LSB ({47, 5})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA_DOT ({277, 24})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA0 ({52, 1}, {61, 22}, {91, 9})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA_MSB ({100, 13}, {121, 14})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA_LSB ({47, 5})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA ({269, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > D2_IDOT ({52, 1}, {61, 13})`
- `const std::pair< int32_t, int32_t > GALILEO_HAS_STATUS ({1, 2})`
- `const std::pair< int32_t, int32_t > GALILEO_HAS_RESERVED ({3, 2})`
- `const std::pair< int32_t, int32_t > GALILEO_HAS_MESSAGE_TYPE ({5, 2})`
- `const std::pair< int32_t, int32_t > GALILEO_HAS_MESSAGE_ID ({7, 5})`
- `const std::pair< int32_t, int32_t > GALILEO_HAS_MESSAGE_SIZE ({12, 5})`
- `const std::pair< int32_t, int32_t > GALILEO_HAS_MESSAGE_PAGE_ID ({17, 8})`
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_TOH ({1, 12})`
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_MASK_FLAG ({13, 1})`
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_ORBIT_CORRECTION_FLAG ({14, 1})`
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_CLOCK_FULLSET_FLAG ({15, 1})`
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_CLOCK_SUBSET_FLAG ({16, 1})`
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_CODE_BIAS_FLAG ({17, 1})`
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_PHASE_BIAS_FLAG ({18, 1})`
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_RESERVED ({19, 4})`
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_MASK_ID ({23, 5})`
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_IOD_SET_ID ({28, 5})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_PAGE_TYPE_BIT ({1, 6})`

- `const std::vector< std::pair< int32_t, int32_t > > FNAV_SV_ID_PRN_1_BIT ({7, 6})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IO_DNAV_1_BIT ({13, 10})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_T0C_1_BIT ({23, 14})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF0_1_BIT ({37, 31})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF1_1_BIT ({68, 21})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF2_1_BIT ({89, 6})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_SISA_1_BIT ({95, 8})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AIO_1_BIT ({103, 11})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AI1_1_BIT ({114, 11})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AI2_1_BIT ({125, 14})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_REGION1_1_BIT ({139, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_REGION2_1_BIT ({140, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_REGION3_1_BIT ({141, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_REGION4_1_BIT ({142, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_REGION5_1_BIT ({143, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_BGD_1_BIT ({144, 10})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E5AHS_1_BIT ({154, 2})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_WN_1_BIT ({156, 12})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_TOW_1_BIT ({168, 20})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E5ADVS_1_BIT ({188, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IO_DNAV_2_BIT ({7, 10})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_M0_2_BIT ({17, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGADOT_2_BIT ({49, 24})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E_2_BIT ({73, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_A12_2_BIT ({105, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGA0_2_BIT ({137, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IDOT_2_BIT ({169, 14})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_WN_2_BIT ({183, 12})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_TOW_2_BIT ({195, 20})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IO_DNAV_3_BIT ({7, 10})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_I0_3_BIT ({17, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_3_BIT ({49, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTAN_3_BIT ({81, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_CUC_3_BIT ({97, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_CUS_3_BIT ({113, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_CRC_3_BIT ({129, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_CRS_3_BIT ({145, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_T0E_3_BIT ({161, 14})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_WN_3_BIT ({175, 12})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_TOW_3_BIT ({187, 20})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IO_DNAV_4_BIT ({7, 10})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_CIC_4_BIT ({17, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_CIS_4_BIT ({33, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_A0_4_BIT ({49, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_A1_4_BIT ({81, 24})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTATLS_4_BIT ({105, 8})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_T0T_4_BIT ({113, 8})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_NOT_4_BIT ({121, 8})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_NLSF_4_BIT ({129, 8})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DN_4_BIT ({137, 3})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTATLSF_4_BIT ({140, 8})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_T0G_4_BIT ({148, 8})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_A0G_4_BIT ({156, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_A1G_4_BIT ({172, 12})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_N0G_4_BIT ({184, 6})`

- `const std::vector< std::pair< int32_t, int32_t > > FNAV_TOW_4_BIT {{{190, 20}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IO_DA_5_BIT {{{7, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_NA_5_BIT {{{11, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_T0A_5_BIT {{{13, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_SVI_D1_5_BIT {{{23, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTA12_1_5_BIT {{{29, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E_1_5_BIT {{{42, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_1_5_BIT {{{53, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTAI_1_5_BIT {{{69, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGA0_1_5_BIT {{{80, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGADOT_1_5_BIT {{{96, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_M0_1_5_BIT {{{107, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF0_1_5_BIT {{{123, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF1_1_5_BIT {{{139, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E5AHS_1_5_BIT {{{152, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_SVI_D2_5_BIT {{{154, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTA12_2_5_BIT {{{160, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E_2_5_BIT {{{173, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_2_5_BIT {{{184, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTAI_2_5_BIT {{{200, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IO_DA_6_BIT {{{7, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGADOT_2_6_BIT {{{23, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_M0_2_6_BIT {{{34, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF0_2_6_BIT {{{50, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF1_2_6_BIT {{{66, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E5AHS_2_6_BIT {{{79, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_SVI_D3_6_BIT {{{81, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTA12_3_6_BIT {{{87, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E_3_6_BIT {{{100, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_3_6_BIT {{{111, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTAI_3_6_BIT {{{127, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGA0_3_6_BIT {{{138, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGADOT_3_6_BIT {{{154, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_M0_3_6_BIT {{{165, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF0_3_6_BIT {{{181, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF1_3_6_BIT {{{197, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E5AHS_3_6_BIT {{{210, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > TYPE {{{1, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > PAGE_TYPE_BIT {{{1, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > IOD_NAV_1_BIT {{{7, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > T0_E_1_BIT {{{17, 14}}}`
- `const std::vector< std::pair< int32_t, int32_t > > M0_1_BIT {{{31, 32}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E_1_BIT {{{63, 32}}}`
- `const std::vector< std::pair< int32_t, int32_t > > A_1_BIT {{{95, 32}}}`
- `const std::vector< std::pair< int32_t, int32_t > > IOD_NAV_2_BIT {{{7, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_0_2_BIT {{{17, 32}}}`
- `const std::vector< std::pair< int32_t, int32_t > > I_0_2_BIT {{{49, 32}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_2_BIT {{{81, 32}}}`
- `const std::vector< std::pair< int32_t, int32_t > > I_DOT_2_BIT {{{113, 14}}}`
- `const std::vector< std::pair< int32_t, int32_t > > IOD_NAV_3_BIT {{{7, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_DOT_3_BIT {{{17, 24}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_N_3_BIT {{{41, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > C_UC_3_BIT {{{57, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > C_US_3_BIT {{{73, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > C_RC_3_BIT {{{89, 16}}}`

- `const std::vector< std::pair< int32_t, int32_t > > C_RS_3_BIT {{{105, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > SISA_3_BIT {{{121, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > IOD_NAV_4_BIT {{{7, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > SV_ID_PRN_4_BIT {{{17, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > C_IC_4_BIT {{{23, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > C_IS_4_BIT {{{39, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > T0C_4_BIT {{{55, 14}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF0_4_BIT {{{69, 31}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF1_4_BIT {{{100, 21}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF2_4_BIT {{{121, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > SPARE_4_BIT {{{127, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AI0_5_BIT {{{7, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AI1_5_BIT {{{18, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AI2_5_BIT {{{29, 14}}}`
- `const std::vector< std::pair< int32_t, int32_t > > REGION1_5_BIT {{{43, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > REGION2_5_BIT {{{44, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > REGION3_5_BIT {{{45, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > REGION4_5_BIT {{{46, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > REGION5_5_BIT {{{47, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > BGD_E1_E5A_5_BIT {{{48, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > BGD_E1_E5B_5_BIT {{{58, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E5B_HS_5_BIT {{{68, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E1_B_HS_5_BIT {{{70, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E5B_DVS_5_BIT {{{72, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E1_B_DVS_5_BIT {{{73, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > WN_5_BIT {{{74, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > TOW_5_BIT {{{86, 20}}}`
- `const std::vector< std::pair< int32_t, int32_t > > SPARE_5_BIT {{{106, 23}}}`
- `const std::vector< std::pair< int32_t, int32_t > > A0_6_BIT {{{7, 32}}}`
- `const std::vector< std::pair< int32_t, int32_t > > A1_6_BIT {{{39, 24}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_T_LS_6_BIT {{{63, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > T0T_6_BIT {{{71, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > W_NOT_6_BIT {{{79, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > WN_LSF_6_BIT {{{87, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DN_6_BIT {{{95, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_T_LSF_6_BIT {{{98, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > TOW_6_BIT {{{106, 20}}}`
- `const std::vector< std::pair< int32_t, int32_t > > IOD_A_7_BIT {{{7, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > WN_A_7_BIT {{{11, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > T0A_7_BIT {{{13, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > SVI_D1_7_BIT {{{23, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_A_7_BIT {{{29, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E_7_BIT {{{42, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_7_BIT {{{53, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_I_7_BIT {{{69, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA0_7_BIT {{{80, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_DOT_7_BIT {{{96, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > M0_7_BIT {{{107, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > IOD_A_8_BIT {{{7, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF0_8_BIT {{{11, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF1_8_BIT {{{27, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E5B_HS_8_BIT {{{40, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E1_B_HS_8_BIT {{{42, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > SVI_D2_8_BIT {{{44, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_A_8_BIT {{{50, 13}}}`

- `const std::vector< std::pair< int32_t, int32_t > > E_8_BIT {{{63, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_8_BIT {{{74, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_I_8_BIT {{{90, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA0_8_BIT {{{101, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_DOT_8_BIT {{{117, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > IOD_A_9_BIT {{{7, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > WN_A_9_BIT {{{11, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > T0A_9_BIT {{{13, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > M0_9_BIT {{{23, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF0_9_BIT {{{39, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF1_9_BIT {{{55, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E5B_HS_9_BIT {{{68, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E1_B_HS_9_BIT {{{70, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > SVI_D3_9_BIT {{{72, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_A_9_BIT {{{78, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E_9_BIT {{{91, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_9_BIT {{{102, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_I_9_BIT {{{118, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > IOD_A_10_BIT {{{7, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA0_10_BIT {{{11, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_DOT_10_BIT {{{27, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > M0_10_BIT {{{38, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF0_10_BIT {{{54, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF1_10_BIT {{{70, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E5B_HS_10_BIT {{{83, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E1_B_HS_10_BIT {{{85, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > A_0_G_10_BIT {{{87, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > A_1_G_10_BIT {{{103, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > T_0_G_10_BIT {{{115, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > WN_0_G_10_BIT {{{123, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CED_DeltaAred_BIT {{{7, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CED_exred_BIT {{{12, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CED_eyred_BIT {{{25, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CED_DeltaI0red_BIT {{{38, 17}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CED_Omega0red_BIT {{{55, 23}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CED_lambda0red_BIT {{{78, 23}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CED_af0red_BIT {{{101, 22}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CED_af1red_BIT {{{123, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > RS_IODNAV_LSBS {{{15, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_CONSTELLATION_ID_BIT {{{7, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_SERVICE_LEVEL_ID_BIT {{{10, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_WN_BIT {{{13, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_T0_BIT {{{25, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_MASK_MSB_BIT {{{34, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_MASK_BIT {{{35, 32}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_PCONST_BIT {{{67, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_PSAT_BIT {{{71, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_URA_BIT {{{75, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_URE_BIT {{{79, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_BNOM_BIT {{{83, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_TVALIDITY_BIT {{{87, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ISM_CRC_BIT {{{97, 32}}}`
- `const std::vector< std::pair< int32_t, int32_t > > TIME_0_BIT {{{7, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > WN_0_BIT {{{97, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > TOW_0_BIT {{{109, 20}}}`

- const std::string **PEMFILE_DEFAULT** (".OSNMA_PublicKey.pem")
- const std::string **CRTFILE_DEFAULT** (".OSNMA_PublicKey_20240115100000_newPKID_1.crt")
- const std::string **MERKLEFILE_DEFAULT** (".OSNMA_MerkleTree_20240115100000_newPKID_1.xml")
- const std::string **KROOTFILE_DEFAULT** (".OSNMA_DSM_KROOT_NMAHeader.bin")
- const std::vector< std::pair< int32_t, int32_t > > **STRING_ID** ({{2, 4}})
- const std::vector< std::pair< int32_t, int32_t > > **KX** ({{78, 8}})
- const std::vector< std::pair< int32_t, int32_t > > **P1** ({{8, 2}})
- const std::vector< std::pair< int32_t, int32_t > > **T_K_HR** ({{10, 5}})
- const std::vector< std::pair< int32_t, int32_t > > **T_K_MIN** ({{15, 6}})
- const std::vector< std::pair< int32_t, int32_t > > **T_K_SEC** ({{21, 1}})
- const std::vector< std::pair< int32_t, int32_t > > **X_N_DOT** ({{22, 24}})
- const std::vector< std::pair< int32_t, int32_t > > **X_N_DOT_DOT** ({{46, 5}})
- const std::vector< std::pair< int32_t, int32_t > > **X_N** ({{51, 27}})
- const std::vector< std::pair< int32_t, int32_t > > **B_N** ({{6, 3}})
- const std::vector< std::pair< int32_t, int32_t > > **P2** ({{9, 1}})
- const std::vector< std::pair< int32_t, int32_t > > **T_B** ({{10, 7}})
- const std::vector< std::pair< int32_t, int32_t > > **Y_N_DOT** ({{22, 24}})
- const std::vector< std::pair< int32_t, int32_t > > **Y_N_DOT_DOT** ({{46, 5}})
- const std::vector< std::pair< int32_t, int32_t > > **Y_N** ({{51, 27}})
- const std::vector< std::pair< int32_t, int32_t > > **P3** ({{6, 1}})
- const std::vector< std::pair< int32_t, int32_t > > **GAMMA_N** ({{7, 11}})
- const std::vector< std::pair< int32_t, int32_t > > **P** ({{19, 2}})
- const std::vector< std::pair< int32_t, int32_t > > **EPH_L_N** ({{21, 1}})
- const std::vector< std::pair< int32_t, int32_t > > **Z_N_DOT** ({{22, 24}})
- const std::vector< std::pair< int32_t, int32_t > > **Z_N_DOT_DOT** ({{46, 5}})
- const std::vector< std::pair< int32_t, int32_t > > **Z_N** ({{51, 27}})
- const std::vector< std::pair< int32_t, int32_t > > **TAU_N** ({{6, 22}})
- const std::vector< std::pair< int32_t, int32_t > > **DELTA_TAU_N** ({{28, 5}})
- const std::vector< std::pair< int32_t, int32_t > > **E_N** ({{33, 5}})
- const std::vector< std::pair< int32_t, int32_t > > **P4** ({{52, 1}})
- const std::vector< std::pair< int32_t, int32_t > > **F_T** ({{53, 4}})
- const std::vector< std::pair< int32_t, int32_t > > **N_T** ({{60, 11}})
- const std::vector< std::pair< int32_t, int32_t > > **N** ({{71, 5}})
- const std::vector< std::pair< int32_t, int32_t > > **M** ({{76, 2}})
- const std::vector< std::pair< int32_t, int32_t > > **DAY_NUMBER_A** ({{6, 11}})
- const std::vector< std::pair< int32_t, int32_t > > **TAU_C** ({{17, 32}})
- const std::vector< std::pair< int32_t, int32_t > > **N_4** ({{50, 5}})
- const std::vector< std::pair< int32_t, int32_t > > **TAU_GPS** ({{55, 22}})
- const std::vector< std::pair< int32_t, int32_t > > **ALM_L_N** ({{77, 1}})
- const std::vector< std::pair< int32_t, int32_t > > **C_N** ({{6, 1}})
- const std::vector< std::pair< int32_t, int32_t > > **M_N_A** ({{7, 2}})
- const std::vector< std::pair< int32_t, int32_t > > **N_A** ({{9, 5}})
- const std::vector< std::pair< int32_t, int32_t > > **TAU_N_A** ({{14, 10}})
- const std::vector< std::pair< int32_t, int32_t > > **LAMBDA_N_A** ({{24, 21}})
- const std::vector< std::pair< int32_t, int32_t > > **DELTA_I_N_A** ({{45, 18}})
- const std::vector< std::pair< int32_t, int32_t > > **EPSILON_N_A** ({{63, 15}})
- const std::vector< std::pair< int32_t, int32_t > > **OMEGA_N_A** ({{6, 16}})
- const std::vector< std::pair< int32_t, int32_t > > **T_LAMBDA_N_A** ({{22, 21}})
- const std::vector< std::pair< int32_t, int32_t > > **DELTA_T_N_A** ({{43, 22}})
- const std::vector< std::pair< int32_t, int32_t > > **DELTA_T_DOT_N_A** ({{65, 7}})
- const std::vector< std::pair< int32_t, int32_t > > **H_N_A** ({{72, 5}})
- const std::vector< std::pair< int32_t, int32_t > > **B1** ({{6, 11}})
- const std::vector< std::pair< int32_t, int32_t > > **B2** ({{17, 10}})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_PRN** ({{9, 6}})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_MSG_TYPE** ({{15, 6}})

- `const std::vector< std::pair< int32_t, int32_t > > CNAV_TOW {{{21, 17}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ALERT_FLAG {{{38, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_WN {{{39, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_HEALTH {{{52, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_TOP1 {{{55, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_URA {{{66, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_TOE1 {{{71, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_DELTA_A {{{82, 26}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_A_DOT {{{108, 25}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_DELTA_N0 {{{133, 17}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_DELTA_N0_DOT {{{150, 23}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_M0 {{{173, 33}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_E_ECCENTRICITY {{{206, 33}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_OMEGA {{{239, 33}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_INTEGRITY_FLAG {{{272, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_L2_PHASING_FLAG {{{273, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_TOE2 {{{39, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_OMEGA0 {{{50, 33}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_I0 {{{83, 33}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_DELTA_OMEGA_DOT {{{116, 17}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_I0_DOT {{{133, 15}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_CIS {{{148, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_CIC {{{164, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_CRS {{{180, 24}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_CRC {{{204, 24}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_CUS {{{228, 21}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_CUC {{{249, 21}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_TOP2 {{{39, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_URA_NED0 {{{50, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_URA_NED1 {{{55, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_URA_NED2 {{{58, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_TOC {{{61, 11}}}`
- `const std::vector< std::pair< int, int > > CNAV_AF0 {{{72, 26}}}`
- `const std::vector< std::pair< int, int > > CNAV_AF1 {{{98, 20}}}`
- `const std::vector< std::pair< int, int > > CNAV_AF2 {{{118, 10}}}`
- `const std::vector< std::pair< int, int > > CNAV_TGD {{{128, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ISCL1 {{{141, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ISCL2 {{{154, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ISCL5I {{{167, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ISCL5Q {{{180, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ALPHA0 {{{193, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ALPHA1 {{{201, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ALPHA2 {{{209, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ALPHA3 {{{217, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_BETA0 {{{225, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_BETA1 {{{233, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_BETA2 {{{241, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_BETA3 {{{249, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_WNOP {{{257, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_A0 {{{128, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_A1 {{{144, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_A2 {{{157, 7}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_DELTA_TLS {{{164, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_TOT {{{172, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_WN_OT {{{188, 13}}}`

- `const std::vector< std::pair< int32_t, int32_t > > CNAV_WN_LSF` ({201, 13})
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_DN` ({214, 4})
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_DELTA_TLSF` ({218, 8})
- `const std::vector< std::pair< int32_t, int32_t > > TOW` ({31, 17})
- `const std::vector< std::pair< int32_t, int32_t > > INTEGRITY_STATUS_FLAG` ({23, 1})
- `const std::vector< std::pair< int32_t, int32_t > > ALERT_FLAG` ({48, 1})
- `const std::vector< std::pair< int32_t, int32_t > > ANTI_SPOOFING_FLAG` ({49, 1})
- `const std::vector< std::pair< int32_t, int32_t > > SUBFRAME_ID` ({50, 3})
- `const std::vector< std::pair< int32_t, int32_t > > GPS_WEEK` ({61, 10})
- `const std::vector< std::pair< int32_t, int32_t > > CA_OR_P_ON_L2` ({71, 2})
- `const std::vector< std::pair< int32_t, int32_t > > SV_ACCURACY` ({73, 4})
- `const std::vector< std::pair< int32_t, int32_t > > SV_HEALTH` ({77, 6})
- `const std::vector< std::pair< int32_t, int32_t > > L2_P_DATA_FLAG` ({91, 1})
- `const std::vector< std::pair< int32_t, int32_t > > T_GD` ({197, 8})
- `const std::vector< std::pair< int32_t, int32_t > > IODC` ({83, 2}, {211, 8})
- `const std::vector< std::pair< int32_t, int32_t > > T_OC` ({219, 16})
- `const std::vector< std::pair< int32_t, int32_t > > A_F2` ({241, 8})
- `const std::vector< std::pair< int32_t, int32_t > > A_F1` ({249, 16})
- `const std::vector< std::pair< int32_t, int32_t > > A_F0` ({271, 22})
- `const std::vector< std::pair< int32_t, int32_t > > IODE_SF2` ({61, 8})
- `const std::vector< std::pair< int32_t, int32_t > > C_RS` ({69, 16})
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_N` ({91, 16})
- `const std::vector< std::pair< int32_t, int32_t > > M_0` ({107, 8}, {121, 24})
- `const std::vector< std::pair< int32_t, int32_t > > C_UC` ({151, 16})
- `const std::vector< std::pair< int32_t, int32_t > > ECCENTRICITY` ({167, 8}, {181, 24})
- `const std::vector< std::pair< int32_t, int32_t > > C_US` ({211, 16})
- `const std::vector< std::pair< int32_t, int32_t > > SQRT_A` ({227, 8}, {241, 24})
- `const std::vector< std::pair< int32_t, int32_t > > T_OE` ({271, 16})
- `const std::vector< std::pair< int32_t, int32_t > > FIT_INTERVAL_FLAG` ({271, 1})
- `const std::vector< std::pair< int32_t, int32_t > > AODO` ({272, 5})
- `const std::vector< std::pair< int32_t, int32_t > > C_IC` ({61, 16})
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_0` ({77, 8}, {91, 24})
- `const std::vector< std::pair< int32_t, int32_t > > C_IS` ({121, 16})
- `const std::vector< std::pair< int32_t, int32_t > > I_0` ({137, 8}, {151, 24})
- `const std::vector< std::pair< int32_t, int32_t > > C_RC` ({181, 16})
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA` ({197, 8}, {211, 24})
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_DOT` ({241, 24})
- `const std::vector< std::pair< int32_t, int32_t > > IODE_SF3` ({271, 8})
- `const std::vector< std::pair< int32_t, int32_t > > I_DOT` ({279, 14})
- `const std::vector< std::pair< int32_t, int32_t > > SV_DATA_ID` ({61, 2})
- `const std::vector< std::pair< int32_t, int32_t > > SV_PAGE` ({63, 6})
- `const std::vector< std::pair< int32_t, int32_t > > ALPHA_0` ({69, 8})
- `const std::vector< std::pair< int32_t, int32_t > > ALPHA_1` ({77, 8})
- `const std::vector< std::pair< int32_t, int32_t > > ALPHA_2` ({91, 8})
- `const std::vector< std::pair< int32_t, int32_t > > ALPHA_3` ({99, 8})
- `const std::vector< std::pair< int32_t, int32_t > > BETA_0` ({107, 8})
- `const std::vector< std::pair< int32_t, int32_t > > BETA_1` ({121, 8})
- `const std::vector< std::pair< int32_t, int32_t > > BETA_2` ({129, 8})
- `const std::vector< std::pair< int32_t, int32_t > > BETA_3` ({137, 8})
- `const std::vector< std::pair< int32_t, int32_t > > A_1` ({151, 24})
- `const std::vector< std::pair< int32_t, int32_t > > A_0` ({181, 24}, {211, 8})
- `const std::vector< std::pair< int32_t, int32_t > > T_OT` ({219, 8})
- `const std::vector< std::pair< int32_t, int32_t > > WN_T` ({227, 8})
- `const std::vector< std::pair< int32_t, int32_t > > DELTAT_LS` ({241, 8})
- `const std::vector< std::pair< int32_t, int32_t > > WN_LSF` ({249, 8})

- `const std::vector< std::pair< int32_t, int32_t > > DN {{{257, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTAT_LSF {{{271, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV25 {{{229, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV26 {{{241, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV27 {{{247, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV28 {{{253, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV29 {{{259, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV30 {{{271, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV31 {{{277, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV32 {{{283, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > T_OA {{{69, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > WN_A {{{77, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV1 {{{91, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV2 {{{97, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV3 {{{103, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV4 {{{109, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV5 {{{121, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV6 {{{127, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV7 {{{133, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV8 {{{139, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV9 {{{151, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV10 {{{157, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV11 {{{163, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV12 {{{169, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV13 {{{181, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV14 {{{187, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV15 {{{193, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV16 {{{199, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV17 {{{211, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV18 {{{217, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV19 {{{223, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV20 {{{229, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV21 {{{241, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV22 {{{247, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV23 {{{253, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV24 {{{259, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ALM_ECC {{{69, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ALM_TOA {{{91, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ALM_DELTAI {{{99, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ALM_OMEGADOT {{{121, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ALM_SVHEALTH {{{137, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ALM_SQUAREA {{{151, 24}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ALM_OMEGAZERO {{{181, 24}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ALM_OMEGA {{{211, 24}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ALM_MZERO {{{241, 24}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ALM_AF0 {{{271, 8}, {290, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ALM_AF1 {{{279, 11}}}`

Variables

- constexpr double `BEIDOU_B1I_FREQ_HZ` = `FREQ1_BDS`
B1I [Hz].
- constexpr double `BEIDOU_B1I_CODE_RATE_CPS` = 2.046e6
Beidou B1I code rate [chips/s].
- constexpr double `BEIDOU_B1I_CODE_LENGTH_CHIPS` = 2046.0
Beidou B1I code length [chips].
- constexpr double `BEIDOU_B1I_CODE_PERIOD_S` = 0.001
Beidou B1I code period [seconds].
- constexpr double `BEIDOU_B1I_PREAMBLE_DURATION_S` = 0.220
- constexpr double `BEIDOU_B1I_OPT_ACQ_FS_SPS` = 10e6
- constexpr uint32_t `BEIDOU_B1I_CODE_PERIOD_MS` = 1
Beidou B1I code period [ms].
- constexpr uint32_t `BEIDOU_B1I_PREAMBLE_LENGTH_BITS` = 11
- constexpr uint32_t `BEIDOU_B1I_PREAMBLE_LENGTH_SYMBOLS` = 220
- constexpr int32_t `BEIDOU_B1I_SECONDARY_CODE_LENGTH` = 20
- constexpr int32_t `BEIDOU_B1I_GEO_PREAMBLE_LENGTH_SYMBOLS` = 22
- constexpr int32_t `BEIDOU_B1I_PREAMBLE_DURATION_MS` = 220
- constexpr int32_t `BEIDOU_B1I_TELEMETRY_RATE_BITS_SECOND` = 50
- constexpr int32_t `BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT` = 20
- constexpr int32_t `BEIDOU_B1I_GEO_TELEMETRY_SYMBOLS_PER_BIT` = 2
- constexpr int32_t `BEIDOU_B1I_TELEMETRY_SYMBOL_PERIOD_MS` = static_cast<int32_t>(static_cast<uint32_t>(BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT) * BEIDOU_B1I_CODE_PERIOD_MS)
- constexpr int32_t `BEIDOU_B1I_TELEMETRY_RATE_SYMBOLS_SECOND` = BEIDOU_B1I_TELEMETRY_RATE_BITS_SECOND * BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT
- constexpr char `BEIDOU_B1I_SECONDARY_CODE_STR` [21] = "00000100110101001110"
- constexpr char `BEIDOU_B1I_GEO_PREAMBLE_SYMBOLS_STR` [23] = "1111110000001100001100"
- constexpr char `BEIDOU_B1I_D2_SECONDARY_CODE_STR` [3] = "00"
- constexpr double `BEIDOU_B3I_FREQ_HZ` = `FREQ3_BDS`
BeiDou B3I [Hz].
- constexpr double `BEIDOU_B3I_CODE_RATE_CPS` = 10.23e6
BeiDou B3I code rate [chips/s].
- constexpr double `BEIDOU_B3I_CODE_LENGTH_CHIPS` = 10230.0
BeiDou B3I code length [chips].
- constexpr double `BEIDOU_B3I_CODE_PERIOD_S` = 0.001
BeiDou B3I code period [seconds].
- constexpr double `BEIDOU_B3I_PREAMBLE_DURATION_S` = 0.220
- constexpr double `BEIDOU_B3I_OPT_ACQ_FS_SPS` = 10e6
- constexpr uint32_t `BEIDOU_B3I_CODE_PERIOD_MS` = 1
BeiDou B3I code period [ms].
- constexpr uint32_t `BEIDOU_B3I_PREAMBLE_LENGTH_BITS` = 11
- constexpr uint32_t `BEIDOU_B3I_PREAMBLE_LENGTH_SYMBOLS` = 220
- constexpr int32_t `BEIDOU_B3I_SECONDARY_CODE_LENGTH` = 20
- constexpr int32_t `BEIDOU_B3I_GEO_PREAMBLE_LENGTH_SYMBOLS` = 22
- constexpr int32_t `BEIDOU_B3I_PREAMBLE_DURATION_MS` = 220
- constexpr int32_t `BEIDOU_B3I_TELEMETRY_RATE_BITS_SECOND` = 50
D1 NAV message bit rate [bits/s].
- constexpr int32_t `BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT` = 20
- constexpr int32_t `BEIDOU_B3I_GEO_TELEMETRY_SYMBOLS_PER_BIT` = 2
- constexpr int32_t `BEIDOU_B3I_TELEMETRY_SYMBOL_PERIOD_MS` = static_cast<int32_t>(static_cast<uint32_t>(BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT) * BEIDOU_B3I_CODE_PERIOD_MS)
- constexpr int32_t `BEIDOU_B3I_TELEMETRY_RATE_SYMBOLS_SECOND` = BEIDOU_B3I_TELEMETRY_RATE_BITS_SECOND * BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT

- constexpr char BEIDOU_B3I_SECONDARY_CODE_STR [21] = "00000100110101001110"
- constexpr char BEIDOU_B3I_GEO_PREAMBLE_SYMBOLS_STR [23] = "1111110000001100001100"
- constexpr char BEIDOU_B3I_D2_SECONDARY_CODE_STR [3] = "00"
- constexpr double D1_TOC_LSB = TWO_P3
- constexpr double D1_TGD1_LSB = 0.1e-9
- constexpr double D1_TGD2_LSB = 0.1e-9
- constexpr double D1_ALPHA0_LSB = TWO_N30
- constexpr double D1_ALPHA1_LSB = TWO_N27
- constexpr double D1_ALPHA2_LSB = TWO_N24
- constexpr double D1_ALPHA3_LSB = TWO_N24
- constexpr double D1_BETA0_LSB = TWO_P11
- constexpr double D1_BETA1_LSB = TWO_P14
- constexpr double D1_BETA2_LSB = TWO_P16
- constexpr double D1_BETA3_LSB = TWO_P16
- constexpr double D1_A2_LSB = TWO_N66
- constexpr double D1_A0_LSB = TWO_N33
- constexpr double D1_A1_LSB = TWO_N50
- constexpr double D1_DELTA_N_LSB = PI_TWO_N43
- constexpr double D1_CUC_LSB = TWO_N31
- constexpr double D1_M0_LSB = PI_TWO_N31
- constexpr double D1_E_LSB = TWO_N33
- constexpr double D1_CUS_LSB = TWO_N31
- constexpr double D1_CRC_LSB = TWO_N6
- constexpr double D1_CRS_LSB = TWO_N6
- constexpr double D1_SQRT_A_LSB = TWO_N19
- constexpr double D1_TOE_LSB = TWO_P3
- constexpr double D1_I0_LSB = PI_TWO_N31
- constexpr double D1_CIC_LSB = TWO_N31
- constexpr double D1_OMEGA_DOT_LSB = PI_TWO_N43
- constexpr double D1_CIS_LSB = TWO_N31
- constexpr double D1_IDOT_LSB = PI_TWO_N43
- constexpr double D1_OMEGA0_LSB = PI_TWO_N31
- constexpr double D1_OMEGA_LSB = PI_TWO_N31
- constexpr double D1_SQRT_A_ALMANAC_LSB = TWO_N11
- constexpr double D1_A1_ALMANAC_LSB = TWO_N38
- constexpr double D1_A0_ALMANAC_LSB = TWO_N20
- constexpr double D1_OMEGA0_ALMANAC_LSB = PI_TWO_N23
- constexpr double D1_E_ALMANAC_LSB = TWO_N21
- constexpr double D1_DELTA_I_LSB = PI_TWO_N19
- constexpr double D1_TOA_LSB = TWO_P12
- constexpr double D1_OMEGA_DOT_ALMANAC_LSB = PI_TWO_N38
- constexpr double D1_OMEGA_ALMANAC_LSB = PI_TWO_N23
- constexpr double D1_M0_ALMANAC_LSB = PI_TWO_N23
- constexpr double D1_A0GPS_LSB = 0.1e-9
- constexpr double D1_A1GPS_LSB = 0.1e-9
- constexpr double D1_A0GAL_LSB = 0.1e-9
- constexpr double D1_A1GAL_LSB = 0.1e-9
- constexpr double D1_A0GLO_LSB = 0.1e-9
- constexpr double D1_A1GLO_LSB = 0.1e-9
- constexpr double D1_A0UTC_LSB = TWO_N30
- constexpr double D1_A1UTC_LSB = TWO_N50
- constexpr int32_t BEIDOU_DNAV_PREAMBLE_LENGTH_BITS = 11
- constexpr int32_t BEIDOU_DNAV_PREAMBLE_LENGTH_SYMBOLS = 11
- constexpr int32_t BEIDOU_DNAV_PREAMBLE_PERIOD_SYMBOLS = 300
- constexpr int32_t BEIDOU_DNAV_SUBFRAME_DATA_BITS = 300

Number of bits per subframe in the NAV message [bits].

- constexpr int32_t BEIDOU_DNAV_BDT2GPST_LEAP_SEC_OFFSET = 14
- constexpr int32_t BEIDOU_DNAV_BDT2GPST_WEEK_NUM_OFFSET = 1356
- constexpr uint32_t BEIDOU_DNAV_SUBFRAME_SYMBOLS = 300
- constexpr uint32_t BEIDOU_DNAV_WORDS_SUBFRAME = 10
- constexpr uint32_t BEIDOU_DNAV_WORD_LENGTH_BITS = 30
- constexpr char BEIDOU_DNAV_PREAMBLE [12] = "11100010010"
- const std::string TEXT_RESET = "\033[0m"
- const std::string TEXT_BLACK = "\033[30m"
- const std::string TEXT_RED = "\033[31m"
- const std::string TEXT_GREEN = "\033[32m"
- const std::string TEXT_YELLOW = "\033[33m"
- const std::string TEXT_BLUE = "\033[34m"
- const std::string TEXT_MAGENTA = "\033[35m"
- const std::string TEXT_CYAN = "\033[36m"
- const std::string TEXT_WHITE = "\033[37m"
- const std::string TEXT_BOLD_BLACK = "\033[1m\033[30m"
- const std::string TEXT_BOLD_RED = "\033[1m\033[31m"
- const std::string TEXT_BOLD_GREEN = "\033[1m\033[32m"
- const std::string TEXT_BOLD_YELLOW = "\033[1m\033[33m"
- const std::string TEXT_BOLD_BLUE = "\033[1m\033[34m"
- const std::string TEXT_BOLD_MAGENTA = "\033[1m\033[35m"
- const std::string TEXT_BOLD_CYAN = "\033[1m\033[36m"
- const std::string TEXT_BOLD_WHITE = "\033[1m\033[37m"
- constexpr size_t HAS_MSG_NSYS_LENGTH = 4
- constexpr size_t HAS_MSG_ID_MASK_LENGTH = 4
- constexpr size_t HAS_MSG_SATELLITE_MASK_LENGTH = 40
- constexpr size_t HAS_MSG_SIGNAL_MASK_LENGTH = 16
- constexpr size_t HAS_MSG_NAV_MESSAGE_LENGTH = 3
- constexpr size_t HAS_MSG_MASK_RESERVED_LENGTH = 6
- constexpr size_t HAS_MSG_VALIDITY_INDEX_LENGTH = 4
- constexpr size_t HAS_MSG_IOD_GPS_LENGTH = 8
- constexpr size_t HAS_MSG_IOD_GAL_LENGTH = 10
- constexpr size_t HAS_MSG_DELTA_RADIAL_LENGTH = 13
- constexpr size_t HAS_MSG_DELTA_IN_TRACK_LENGTH = 12
- constexpr size_t HAS_MSG_DELTA_CROSS_TRACK_LENGTH = 12
- constexpr size_t HAS_MSG_DELTA_CLOCK_MULTIPLIER_LENGTH = 2
- constexpr size_t HAS_MSG_DELTA_CLOCK_CORRECTION_LENGTH = 13
- constexpr size_t HAS_MSG_NSYS_SUB_LENGTH = 4
- constexpr size_t HAS_MSG_ID_CLOCK_SUBSET_LENGTH = 4
- constexpr size_t HAS_MSG_DELTA_CLOCK_MULTIPLIER_SUBSET_LENGTH = 2
- constexpr size_t HAS_MSG_DELTA_CLOCK_CORRECTION_SUBSET_LENGTH = 13
- constexpr size_t HAS_MSG_CODE_BIAS_LENGTH = 11
- constexpr size_t HAS_MSG_PHASE_BIAS_LENGTH = 11
- constexpr size_t HAS_MSG_PHASE_DISCONTINUITY_INDICATOR_LENGTH = 2
- constexpr uint64_t MAX_SECONDS_REMEMBERING_MID = 150
- constexpr int32_t GALILEO_CNAV_SYMBOLS_PER_PAGE = 1000
- constexpr int32_t GALILEO_CNAV_PREAMBLE_PERIOD_SYMBOLS = 1000
- constexpr int32_t GALILEO_CNAV_PAGE_MS = 1
- constexpr int32_t GALILEO_CNAV_INTERLEAVER_ROWS = 8
- constexpr int32_t GALILEO_CNAV_INTERLEAVER_COLS = 123
- constexpr int32_t GALILEO_CNAV_TELEMETRY_RATE_BITS_SECOND = 1000
- constexpr int32_t GALILEO_CNAV_HAS_PAGE_DATA_BITS = 448
- constexpr int32_t GALILEO_CNAV_PAGE_RESERVED_BITS = 14
- constexpr int32_t GALILEO_CNAV_BYTES_FOR_CRC = 58

- constexpr int32_t GALILEO_CNAV_CRC_LENGTH = 24
- constexpr int32_t GALILEO_CNAV_MESSAGE_BITS_PER_PAGE = 424
- constexpr int32_t GALILEO_CNAV_PAGE_HEADER_BITS = 24
- constexpr int32_t GALILEO_CNAV_PREAMBLE_LENGTH_BITS = 16
- constexpr int32_t GALILEO_CNAV_MAX_NUMBER_SYMBOLS_ENCODED_BLOCK = 255
- constexpr int32_t GALILEO_CNAV_MT1_HEADER_BITS = 32
- constexpr int32_t GALILEO_CNAV_OCTETS_IN_SUBPAGE = 53
- constexpr int32_t GALILEO_CNAV_INFORMATION_VECTOR_LENGTH = 32
- constexpr int32_t GALILEO_CNAV_BITS_FOR_CRC = GALILEO_CNAV_HAS_PAGE_DATA_BITS + GALILEO_CNAV_PAGE_RESERVED_BITS
- constexpr int32_t HAS_MSG_NUMBER_MASK_IDS = 32
- constexpr int32_t HAS_MSG_NUMBER_GNSS_IDS = 16
- constexpr int32_t HAS_MSG_NUMBER_MESSAGE_IDS = 32
- constexpr int32_t HAS_MSG_NUMBER_SATELLITE_IDS = 40
- constexpr int32_t HAS_MSG_NUMBER_SIGNAL_MASKS = 16
- constexpr float HAS_MSG_DELTA_RADIAL_SCALE_FACTOR = 0.0025
- constexpr float HAS_MSG_DELTA_IN_TRACK_SCALE_FACTOR = 0.008
- constexpr float HAS_MSG_DELTA_CROSS_TRACK_SCALE_FACTOR = 0.008
- constexpr float HAS_MSG_DELTA_CLOCK_SCALE_FACTOR = 0.0025
- constexpr float HAS_MSG_CODE_BIAS_SCALE_FACTOR = 0.02
- constexpr float HAS_MSG_PHASE_BIAS_SCALE_FACTOR = 0.01
- constexpr uint16_t HAS_MSG_NUMBER_MAX_TOH = 3599
- constexpr uint8_t HAS_MSG_GPS_SYSTEM = 0
- constexpr uint8_t HAS_MSG_GALILEO_SYSTEM = 2
- constexpr uint8_t HAS_MSG_WRONG_SYSTEM = 255
- constexpr char GALILEO_CNAV_PREAMBLE [17] = "1011011101110000"
- const std::unordered_map< uint8_t, std::unordered_map< uint8_t, std::string > > HAS_SIGNAL_INDEX_TABLE
- const std::unordered_map< uint8_t, uint16_t > HAS_VALIDITY_INTERVALS
- constexpr double GALILEO_E1_FREQ_HZ = FREQ1
Galileo E1 carrier frequency [Hz].
- constexpr double GALILEO_E1_CODE_CHIP_RATE_CPS = 1.023e6
Galileo E1 code rate [chips/s].
- constexpr double GALILEO_E1_CODE_PERIOD_S = 0.004
Galileo E1 code period [s].
- constexpr double GALILEO_E1_SUB_CARRIER_A_RATE_HZ = 1.023e6
Galileo E1 sub-carrier 'a' rate [Hz].
- constexpr double GALILEO_E1_SUB_CARRIER_B_RATE_HZ = 6.138e6
Galileo E1 sub-carrier 'b' rate [Hz].
- constexpr double GALILEO_E1_B_CODE_LENGTH_CHIPS = 4092.0
Galileo E1-B code length [chips].
- constexpr double GALILEO_E1_B_SYMBOL_RATE_BPS = 250.0
Galileo E1-B symbol rate [bits/second].
- constexpr uint32_t GALILEO_E1_CODE_PERIOD_MS = 4
Galileo E1 code period [ms].
- constexpr int32_t GALILEO_E1_B_SAMPLES_PER_SYMBOL = 1
(Galileo_E1_CODE_CHIP_RATE_HZ / Galileo_E1_B_CODE_LENGTH_CHIPS) / Galileo_E1_B_SYMBOL_RATE_BPS
- constexpr int32_t GALILEO_E1_C_SECONDARY_CODE_LENGTH = 25
Galileo E1-C secondary code length [chips].
- constexpr int32_t GALILEO_E1_NUMBER_OF_CODES = 50
- constexpr uint32_t GALILEO_E1_OPT_ACQ_FS_SPS = 2000000
Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.
- constexpr int32_t GALILEO_E1_HISTORY_DEEP = 100

Observable history length for interpolation.

- `constexpr char GALILEO_E1_C_SECONDARY_CODE [26] = "0011100000001010110110010"`
- `constexpr size_t GALILEO_E1_B_PRIMARY_CODE_STR_LENGTH = 1023`
- `constexpr char GALILEO_E1_B_PRIMARY_CODE [GALILEO_E1_NUMBER_OF_CODES][1024]`
- `constexpr size_t GALILEO_E1_C_PRIMARY_CODE_STR_LENGTH = 1023`
- `constexpr char GALILEO_E1_C_PRIMARY_CODE [GALILEO_E1_NUMBER_OF_CODES][1024]`
- `constexpr double GALILEO_E5A_FREQ_HZ = FREQ5`

Galileo E5a carrier frequency [Hz].

- `constexpr double GALILEO_E5A_CODE_CHIP_RATE_CPS = 1.023e7`

Galileo E5a code rate [chips/s].

- `constexpr double GALILEO_E5A_I_TIERED_CODE_PERIOD_S = 0.020`

Galileo E5a-I tiered code period [s].

- `constexpr double GALILEO_E5A_Q_TIERED_CODE_PERIOD_S = 0.100`

Galileo E5a-Q tiered code period [s].

- `constexpr double GALILEO_E5A_CODE_PERIOD_S = 0.001`

Galileo E5a primary code period [s].

- `constexpr int32_t GALILEO_E5A_CODE_LENGTH_CHIPS = 10230`

Galileo E5a primary code length [chips].

- `constexpr int32_t GALILEO_E5A_I_SECONDARY_CODE_LENGTH = 20`

Galileo E5a-I secondary code length [chips].

- `constexpr int32_t GALILEO_E5A_Q_SECONDARY_CODE_LENGTH = 100`

Galileo E5a-Q secondary code length [chips].

- `constexpr int32_t GALILEO_E5A_CODE_PERIOD_MS = 1`

Galileo E5a primary code period [ms].

- `constexpr int32_t GALILEO_E5A_SYMBOL_RATE_BPS = 50`

Galileo E5a symbol rate [bits/second].

- `constexpr int32_t GALILEO_E5A_NUMBER_OF_CODES = 50`
- `constexpr int32_t GALILEO_E5A_HISTORY_DEEP = 20`
- `constexpr int32_t GALILEO_E5A_CRC_ERROR_LIMIT = 6`
- `constexpr uint32_t GALILEO_E5A_OPT_ACQ_FS_SPS = 10000000`

Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.

- `constexpr int32_t GALILEO_FNAV_PREAMBLE_LENGTH_BITS = 12`
- `constexpr int32_t GALILEO_FNAV_CODES_PER_SYMBOL = 20`
- `constexpr int32_t GALILEO_FNAV_CODES_PER_PREAMBLE = 240`
- `constexpr int32_t GALILEO_FNAV_SYMBOLS_PER_PAGE = 500`
- `constexpr int32_t GALILEO_FNAV_SECONDS_PER_PAGE = 10`
- `constexpr int32_t GALILEO_FNAV_CODES_PER_PAGE = 10000`
- `constexpr int32_t GALILEO_FNAV_INTERLEAVER_ROWS = 8`
- `constexpr int32_t GALILEO_FNAV_INTERLEAVER_COLS = 61`
- `constexpr int32_t GALILEO_FNAV_PAGE_TYPE_BITS = 6`
- `constexpr int32_t GALILEO_FNAV_DATA_FRAME_BITS = 214`
- `constexpr int32_t GALILEO_FNAV_DATA_FRAME_BYTES = 27`
- `constexpr char GALILEO_FNAV_PREAMBLE [13] = "101101110000"`
- `constexpr size_t GALILEO_E5A_I_PRIMARY_CODE_STR_LENGTH = 2558`
- `constexpr char GALILEO_E5A_I_PRIMARY_CODE [GALILEO_E5A_NUMBER_OF_CODES][2559]`
- `constexpr size_t GALILEO_E5A_Q_PRIMARY_CODE_STR_LENGTH = 2558`
- `constexpr char GALILEO_E5A_Q_PRIMARY_CODE [GALILEO_E5A_NUMBER_OF_CODES][2559]`
- `constexpr char GALILEO_E5A_I_SECONDARY_CODE [] = "10000100001011101001"`
- `constexpr size_t GALILEO_E5A_Q_SECONDARY_CODE_STR_LENGTH = 100`
- `constexpr char GALILEO_E5A_Q_SECONDARY_CODE [GALILEO_E5A_NUMBER_OF_CODES][101]`
- `constexpr double GALILEO_E5B_FREQ_HZ = FREQ7`

Galileo E5b carrier frequency [Hz].

- `constexpr double GALILEO_E5B_CODE_CHIP_RATE_CPS = 1.023e7`

- Galileo E5b code rate [chips/s].*
- constexpr double `GALILEO_E5B_I_TIERED_CODE_PERIOD_S` = 0.004
- Galileo E5b-I tiered code period [s].*
- constexpr double `GALILEO_E5B_Q_TIERED_CODE_PERIOD_S` = 0.100
- Galileo E5b-Q tiered code period [s].*
- constexpr double `GALILEO_E5B_CODE_PERIOD_S` = 0.001
- Galileo E5b primary code period [s].*
- constexpr int32_t `GALILEO_E5B_CODE_PERIOD_MS` = 1
- Galileo E5b primary code period [ms].*
- constexpr int32_t `GALILEO_E5B_CODE_LENGTH_CHIPS` = 10230
- Galileo E5b primary code length [chips].*
- constexpr int32_t `GALILEO_E5B_I_SECONDARY_CODE_LENGTH` = 4
- Galileo E5b-I secondary code length [chips].*
- constexpr int32_t `GALILEO_E5B_Q_SECONDARY_CODE_LENGTH` = 100
- Galileo E5b-Q secondary code length [chips].*
- constexpr int32_t `GALILEO_E5B_SYMBOL_RATE_BPS` = 250
- Galileo E5b symbol rate [bits/second].*
- constexpr int32_t `GALILEO_E5B_NUMBER_OF_CODES` = 50
- constexpr int32_t `GALILEO_E5B_HISTORY_DEEP` = 100
- constexpr uint32_t `GALILEO_E5B_OPT_ACQ_FS_SPS` = 10000000
- Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.*
- constexpr char `GALILEO_E5B_I_SECONDARY_CODE` [5] = "1110"
- constexpr size_t `GALILEO_E5B_I_PRIMARY_CODE_STR_LENGTH` = 2558
- constexpr char `GALILEO_E5B_I_PRIMARY_CODE` [GALILEO_E5B_NUMBER_OF_CODES][2559]
- constexpr size_t `GALILEO_E5B_Q_PRIMARY_CODE_STR_LENGTH` = 2558
- constexpr char `GALILEO_E5B_Q_PRIMARY_CODE` [GALILEO_E5B_NUMBER_OF_CODES][2559]
- constexpr size_t `GALILEO_E5B_Q_SECONDARY_CODE_STR_LENGTH` = 100
- constexpr char `GALILEO_E5B_Q_SECONDARY_CODE` [GALILEO_E5B_NUMBER_OF_CODES][101]
- constexpr double `GALILEO_E6_FREQ_HZ` = `FREQ6`
- Galileo E6 carrier frequency [Hz].*
- constexpr double `GALILEO_E6_B_CODE_CHIP_RATE_CPS` = 5.115e6
- Galileo E6 B code rate [chips/s].*
- constexpr double `GALILEO_E6_C_CODE_CHIP_RATE_CPS` = 5.115e6
- Galileo E6 C code rate [chips/s].*
- constexpr double `GALILEO_E6_CODE_PERIOD_S` = 0.001
- Galileo E6 code period [s].*
- constexpr double `GALILEO_E6_B_CODE_LENGTH_CHIPS` = 5115.0
- Galileo E6 B code length [chips].*
- constexpr double `GALILEO_E6_C_CODE_LENGTH_CHIPS` = 5115.0
- Galileo E6 C code length [chips].*
- constexpr double `GALILEO_E6_C_SECONDARY_CODE_LENGTH_CHIPS` = 100.0
- Galileo E6 C secondary code length [chips].*
- constexpr uint32_t `GALILEO_E6_CODE_PERIOD_MS` = 1
- Galileo E& B/C code period [ms].*
- constexpr int32_t `GALILEO_E6_NUMBER_OF_CODES` = 50
- constexpr uint32_t `GALILEO_E6_OPT_ACQ_FS_SPS` = 10000000
- constexpr size_t `GALILEO_E6_B_PRIMARY_CODE_STR_LENGTH` = 1279
- constexpr char `GALILEO_E6_B_PRIMARY_CODE` [GALILEO_E6_NUMBER_OF_CODES][1280]
- constexpr size_t `GALILEO_E6_C_PRIMARY_CODE_STR_LENGTH` = 1279
- constexpr char `GALILEO_E6_C_PRIMARY_CODE` [GALILEO_E6_NUMBER_OF_CODES][1280]
- constexpr size_t `GALILEO_E6_C_SECONDARY_CODE_STR_LENGTH` = 25
- constexpr char `GALILEO_E6_C_SECONDARY_CODE` [GALILEO_E6_NUMBER_OF_CODES][26]

- constexpr int32_t FNAV_T0C_1_LSB = 60
- constexpr double FNAV_AF0_1_LSB = TWO_N34
- constexpr double FNAV_AF1_1_LSB = TWO_N46
- constexpr double FNAV_AF2_1_LSB = TWO_N59
- constexpr double FNAV_AI0_1_LSB = TWO_N2
- constexpr double FNAV_AI1_1_LSB = TWO_N8
- constexpr double FNAV_AI2_1_LSB = TWO_N15
- constexpr double FNAV_BGD_1_LSB = TWO_N32
- constexpr double FNAV_M0_2_LSB = PI_TWO_N31
- constexpr double FNAV_OMEGADOT_2_LSB = PI_TWO_N43
- constexpr double FNAV_E_2_LSB = TWO_N33
- constexpr double FNAV_A12_2_LSB = TWO_N19
- constexpr double FNAV_OMEGA0_2_LSB = PI_TWO_N31
- constexpr double FNAV_IDOT_2_LSB = PI_TWO_N43
- constexpr double FNAV_I0_3_LSB = PI_TWO_N31
- constexpr double FNAV_W_3_LSB = PI_TWO_N31
- constexpr double FNAV_DELTAN_3_LSB = PI_TWO_N43
- constexpr double FNAV_CUC_3_LSB = TWO_N29
- constexpr double FNAV_CUS_3_LSB = TWO_N29
- constexpr double FNAV_CRC_3_LSB = TWO_N5
- constexpr double FNAV_CRS_3_LSB = TWO_N5
- constexpr int32_t FNAV_T0E_3_LSB = 60
- constexpr double FNAV_CIC_4_LSB = TWO_N29
- constexpr double FNAV_CIS_4_LSB = TWO_N29
- constexpr double FNAV_A0_4_LSB = TWO_N30
- constexpr double FNAV_A1_4_LSB = TWO_N50
- constexpr int32_t FNAV_T0T_4_LSB = 3600
- constexpr int32_t FNAV_T0G_4_LSB = 3600
- constexpr double FNAV_A0G_4_LSB = TWO_N35
- constexpr double FNAV_A1G_4_LSB = TWO_N51
- constexpr int32_t FNAV_T0A_5_LSB = 600
- constexpr double FNAV_DELTAA12_5_LSB = TWO_N9
- constexpr double FNAV_E_5_LSB = TWO_N16
- constexpr double FNAV_W_5_LSB = TWO_N15
- constexpr double FNAV_DELTAI_5_LSB = TWO_N14
- constexpr double FNAV_OMEGA0_5_LSB = TWO_N15
- constexpr double FNAV_OMEGADOT_5_LSB = TWO_N33
- constexpr double FNAV_M0_5_LSB = TWO_N15
- constexpr double FNAV_AF0_5_LSB = TWO_N19
- constexpr double FNAV_AF1_5_LSB = TWO_N38
- constexpr double GALILEO_INAV_PAGE_PART_WITH_PREABLE_SECONDS = 2.04

Page Duration + (Galileo I/NAV Preamble bits)(Galileo E5b-I tiered Code Period(seconds))*

- constexpr uint32_t GALILEO_INAV_PAGE_SYMBOLS = 500

The complete Galileo INAV page length.

- constexpr int32_t GALILEO_INAV_PREAMBLE_LENGTH_BITS = 10
- constexpr int32_t GALILEO_INAV_PREAMBLE_PERIOD_SYMBOLS = 250
- constexpr int32_t GALILEO_INAV_PAGE_PART_SYMBOLS = 250

Each Galileo INAV pages are composed of two parts (even and odd) each of 250 symbols, including preamble. See Galileo ICD 4.3.2.

- constexpr int32_t GALILEO_INAV_PAGE_PART_SECONDS = 1
- constexpr int32_t GALILEO_INAV_PAGE_PART_MS = 1000
- constexpr int32_t GALILEO_INAV_PAGE_SECONDS = 2
- constexpr int32_t GALILEO_INAV_INTERLEAVER_ROWS = 8
- constexpr int32_t GALILEO_INAV_INTERLEAVER_COLS = 30

- constexpr int32_t GALILEO_TELEMETRY_RATE_BITS_SECOND = 250
- constexpr int32_t GALILEO_PAGE_TYPE_BITS = 6
- constexpr int32_t GALILEO_DATA_JK_BITS = 128
- constexpr int32_t GALILEO_DATA_FRAME_BITS = 196
- constexpr int32_t GALILEO_DATA_FRAME_BYTES = 25
- constexpr char GALILEO_INAV_PREAMBLE [11] = "0101100000"
- constexpr int32_t T0E_1_LSB = 60
- constexpr double M0_1_LSB = PI_TWO_N31
- constexpr double E_1_LSB = TWO_N33
- constexpr double A_1_LSB_GAL = TWO_N19
- constexpr double OMEGA_0_2_LSB = PI_TWO_N31
- constexpr double I_0_2_LSB = PI_TWO_N31
- constexpr double OMEGA_2_LSB = PI_TWO_N31
- constexpr double I_DOT_2_LSB = PI_TWO_N43
- constexpr double OMEGA_DOT_3_LSB = PI_TWO_N43
- constexpr double DELTA_N_3_LSB = PI_TWO_N43
- constexpr double C_UC_3_LSB = TWO_N29
- constexpr double C_US_3_LSB = TWO_N29
- constexpr double C_RC_3_LSB = TWO_N5
- constexpr double C_RS_3_LSB = TWO_N5
- constexpr double C_IC_4_LSB = TWO_N29
- constexpr double C_IS_4_LSB = TWO_N29
- constexpr int32_t T0C_4_LSB = 60
- constexpr double AF0_4_LSB = TWO_N34
- constexpr double AF1_4_LSB = TWO_N46
- constexpr double AF2_4_LSB = TWO_N59
- constexpr double AI0_5_LSB = TWO_N2
- constexpr double AI1_5_LSB = TWO_N8
- constexpr double AI2_5_LSB = TWO_N15
- constexpr double BGD_E1_E5A_5_LSB = TWO_N32
- constexpr double BGD_E1_E5B_5_LSB = TWO_N32
- constexpr double A0_6_LSB = TWO_N30
- constexpr double A1_6_LSB = TWO_N50
- constexpr int32_t T0T_6_LSB = 3600
- constexpr int32_t T0A_7_LSB = 600
- constexpr double DELTA_A_7_LSB = TWO_N9
- constexpr double E_7_LSB = TWO_N16
- constexpr double OMEGA_7_LSB = TWO_N15
- constexpr double DELTA_I_7_LSB = TWO_N14
- constexpr double OMEGA0_7_LSB = TWO_N15
- constexpr double OMEGA_DOT_7_LSB = TWO_N33
- constexpr double M0_7_LSB = TWO_N15
- constexpr double AF0_8_LSB = TWO_N19
- constexpr double AF1_8_LSB = TWO_N38
- constexpr double DELTA_A_8_LSB = TWO_N9
- constexpr double E_8_LSB = TWO_N16
- constexpr double OMEGA_8_LSB = TWO_N15
- constexpr double DELTA_I_8_LSB = TWO_N14
- constexpr double OMEGA0_8_LSB = TWO_N15
- constexpr double OMEGA_DOT_8_LSB = TWO_N33
- constexpr int32_t T0A_9_LSB = 600
- constexpr double M0_9_LSB = TWO_N15
- constexpr double AF0_9_LSB = TWO_N19
- constexpr double AF1_9_LSB = TWO_N38
- constexpr double DELTA_A_9_LSB = TWO_N9

- constexpr double [E_9_LSB](#) = [TWO_N16](#)
- constexpr double [OMEGA_9_LSB](#) = [TWO_N15](#)
- constexpr double [DELTA_I_9_LSB](#) = [TWO_N14](#)
- constexpr double [OMEGA0_10_LSB](#) = [TWO_N15](#)
- constexpr double [OMEGA_DOT_10_LSB](#) = [TWO_N33](#)
- constexpr double [M0_10_LSB](#) = [TWO_N15](#)
- constexpr double [AF0_10_LSB](#) = [TWO_N19](#)
- constexpr double [AF1_10_LSB](#) = [TWO_N38](#)
- constexpr double [A_0G_10_LSB](#) = [TWO_N35](#)
- constexpr double [A_1G_10_LSB](#) = [TWO_N51](#)
- constexpr int32_t [T_0_G_10_LSB](#) = 3600
- constexpr double [CED_DeltaAred_LSB](#) = [TWO_P8](#)
- constexpr double [CED_exred_LSB](#) = [TWO_N22](#)
- constexpr double [CED_eyred_LSB](#) = [TWO_N22](#)
- constexpr double [CED_DeltaI0red_LSB](#) = [TWO_N22](#)
- constexpr double [CED_Omega0red_LSB](#) = [TWO_N22](#)
- constexpr double [CED_lambda0red_LSB](#) = [TWO_N22](#)
- constexpr double [CED_af0red_LSB](#) = [TWO_N26](#)
- constexpr double [CED_af1red_LSB](#) = [TWO_N35](#)
- constexpr size_t [INAV_RS_SUBVECTOR_LENGTH](#) = 15
- constexpr size_t [INAV_RS_PARITY_VECTOR_LENGTH](#) = 60
- constexpr size_t [INAV_RS_INFO_VECTOR_LENGTH](#) = 58
- constexpr size_t [INAV_RS_BUFFER_LENGTH](#) = 118
- constexpr int32_t [BITS_IN_OCTET](#) = 8
- constexpr int32_t [FIRST_RS_BIT](#) = 7
- constexpr int32_t [FIRST_RS_BIT_AFTER_IODNAV](#) = 17
- constexpr int32_t [GALILEO_ISM_CRC_DATA_BITS](#) = 96
- constexpr int32_t [GALILEO_ISM_CRC_DATA_BYTES](#) = 12
- constexpr char [GALILEO_INAV_PLAIN_SSP1](#) [9] = "00000100"
- constexpr char [GALILEO_INAV_PLAIN_SSP2](#) [9] = "00101011"
- constexpr char [GALILEO_INAV_PLAIN_SSP3](#) [9] = "00101111"
- constexpr char [GALILEO_INAV_ENCODED_SSP1](#) [17] = "1110100100100101"
- constexpr char [GALILEO_INAV_ENCODED_SSP2](#) [17] = "0110110001001110"
- constexpr char [GALILEO_INAV_ENCODED_SSP3](#) [17] = "1101000000111110"
- constexpr size_t [SIZE_DSM_BLOCKS_BYTES](#) = 13
- const std::unordered_map< uint8_t, std::string > [OSNMA_TABLE_1](#)
- const std::unordered_map< uint8_t, std::string > [OSNMA_TABLE_2](#)
- const std::unordered_map< uint8_t, std::pair< uint16_t, uint16_t > > [OSNMA_TABLE_3](#)
- const std::unordered_map< uint8_t, std::string > [OSNMA_TABLE_5](#)
- const std::unordered_map< std::string, uint16_t > [OSNMA_TABLE_6](#)
- const std::unordered_map< uint8_t, std::pair< uint16_t, uint16_t > > [OSNMA_TABLE_7](#)
- const std::unordered_map< uint8_t, std::string > [OSNMA_TABLE_8](#)
- const std::unordered_map< uint8_t, uint16_t > [OSNMA_TABLE_10](#)
- const std::unordered_map< uint8_t, uint8_t > [OSNMA_TABLE_11](#)
- const std::unordered_map< std::string, uint16_t > [OSNMA_TABLE_15](#)
- const std::unordered_map< uint8_t, [Mack_lookup](#) > [OSNMA_TABLE_16](#)
- constexpr double [GLONASS_F_M_A](#) = 0.35e9
- Gravitational constant of atmosphere [m^3/s^2].*
- constexpr double [GLONASS_SEMI_MAJOR_AXIS](#) = 6378136
- Semi-major axis of Earth [m].*
- constexpr double [GLONASS_FLATTENING](#) = 1.0 / 29825784.0
- Flattening parameter.*
- constexpr double [GLONASS_GRAVITY](#) = 97803284.0
- Equatorial acceleration of gravity [mGal].*

- constexpr double `GLONASS_GRAVITY_CORRECTION` = 0.87
Correction to acceleration of gravity at sea-level due to Atmosphere[uGal].
- constexpr double `GLONASS_J2` = 1082625.75e-9
Second zonal harmonic of the geopotential.
- constexpr double `GLONASS_J4` = -2370.89e-9
Fourth zonal harmonic of the geopotential.
- constexpr double `GLONASS_J6` = 6.08e-9
Sixth zonal harmonic of the geopotential.
- constexpr double `GLONASS_J8` = 1.40e-11
Eighth zonal harmonic of the geopotential.
- constexpr double `GLONASS_U0` = 62636861.4
Normal potential at surface of common terrestrial ellipsoid [m^2/s^2].
- constexpr double `GLONASS_C20` = -1082.63e-6
Second zonal coefficient of spherical harmonic expansion.
- constexpr double `GLONASS_EARTH_RADIUS` = 6378.136
Equatorial radius of Earth [km].
- constexpr double `GLONASS_EARTH_INCLINATION` = 0.000409148809899e3
Mean inclination of ecliptic to equator (23 deg 26 min 33 sec) [rad].
- constexpr double `GLONASS_TAU_0` = -0.005835151531174e3
(-334 deg 19 min 46.40 sec) [rad];
- constexpr double `GLONASS_TAU_1` = 0.071018041257371e3
(4069 deg 02 min 02.52 sec) [rad];
- constexpr double `GLONASS_MOON_Q0` = -0.001115184961435e3
(-63 deg 53 min 43.41 sec) [rad]
- constexpr double `GLONASS_MOON_Q1` = 8.328691103668023e3
(477198 deg 50 min 56.79 sec) [rad]
- constexpr double `GLONASS_MOON_OMEGA_0` = 0.004523601514852e3
(259 deg 10 min 59.79 sec) [rad]
- constexpr double `GLONASS_MOON_OMEGA_1` = -0.033757146246552e3
(-1934 deg 08 min 31.23 sec) [rad]
- constexpr double `GLONASS_MOON_GM` = 4902.835
Lunar gravitational constant [km^3/s^2].
- constexpr double `GLONASS_MOON_SEMI_MAJOR_AXIS` = 3.84385243e5
Semi-major axis of lunar orbit [km].;
- constexpr double `GLONASS_MOON_ECCENTRICITY` = 0.054900489
Eccentricity of lunar orbit.
- constexpr double `GLONASS_MOON_INCLINATION` = 0.000089803977407e3
Inclination of lunar orbit to ecliptic plane (5 deg 08 min 43.4 sec) [rad].
- constexpr double `GLONASS_SUN_OMEGA` = 0.004908229466869e3
TODO What is this operation in the seconds with T?(281 deg 13 min 15.0 + 6189.03 x T sec) [rad].
- constexpr double `GLONASS_SUN_Q0` = 0.006256583774423e3
(358 deg 28 min 33.04 sec) [rad]
- constexpr double `GLONASS_SUN_Q1` = 0e3
TODO Why is the value greater than 60?(129596579.10 sec) [rad].
- constexpr double `GLONASS_SUN_GM` = 0.1325263e12
Solar gravitational constant [km^3/s^2].
- constexpr double `GLONASS_SUN_SEMI_MAJOR_AXIS` = 1.49598e8
Semi-major axis of solar orbit [km].;
- constexpr double `GLONASS_SUN_ECCENTRICITY` = 0.016719
Eccentricity of solar orbit.
- constexpr double `GLONASS_L2_CA_FREQ_HZ` = `FREQ2_GLO`

Number of bits in hamming code sequence of GNAV message.

- constexpr int32_t [GLONASS_GNAV_DATA_SYMBOLS](#) = 1700
- constexpr double [GLONASS_LEAP_SECONDS](#) [19][7]

Record of leap seconds definition for GLOT to GPST conversion and vice versa.

- const std::map< uint32_t, int32_t > [GLONASS_PRN](#)
- const std::vector< int32_t > [GLONASS_GNAV_CRC_I_INDEX](#) {9, 10, 12, 13, 15, 17, 19, 20, 22, 24, 26, 28, 30, 32, 34, 35, 37, 39, 41, 43, 45, 47, 49, 51, 53, 55, 57, 59, 61, 63, 65, 66, 68, 70, 72, 74, 76, 78, 80, 82, 84}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_J_INDEX](#) {9, 11, 12, 14, 15, 18, 19, 21, 22, 25, 26, 29, 30, 33, 34, 36, 37, 40, 41, 44, 45, 48, 49, 52, 53, 56, 57, 60, 61, 64, 65, 67, 68, 71, 72, 75, 76, 79, 80, 83, 84}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_K_INDEX](#) {10, 11, 12, 16, 17, 18, 19, 23, 24, 25, 26, 31, 32, 33, 34, 38, 39, 40, 41, 46, 47, 48, 49, 54, 55, 56, 57, 62, 63, 64, 65, 69, 70, 71, 72, 77, 78, 79, 80, 85}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_L_INDEX](#) {13, 14, 15, 16, 17, 18, 19, 27, 28, 29, 30, 31, 32, 33, 34, 42, 43, 44, 45, 46, 47, 48, 49, 58, 59, 60, 61, 62, 63, 64, 65, 73, 74, 75, 76, 77, 78, 79, 80}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_M_INDEX](#) {20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 81, 82, 83, 84, 85}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_N_INDEX](#) {35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_P_INDEX](#) {66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_Q_INDEX](#) {9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85}
- const std::vector< int32_t > [GLONASS_GNAV_ECC_LOCATOR](#) {0, 0, 1, 8, 2, 9, 10, 11, 3, 12, 13, 14, 15, 16, 17, 18, 4, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 5, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 6, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84}
- constexpr double [FREQ1](#) = 1.57542e9

L1/E1 frequency (Hz)

- constexpr double [FREQ2](#) = 1.22760e9

L2 frequency (Hz)

- constexpr double [FREQ5](#) = 1.17645e9

L5/E5a frequency (Hz)

- constexpr double [FREQ6](#) = 1.27875e9

E6/LEX frequency (Hz)

- constexpr double [FREQ7](#) = 1.20714e9

E5b frequency (Hz)

- constexpr double [FREQ8](#) = 1.191795e9

E5a+b frequency (Hz)

- constexpr double [FREQ9](#) = 2.492028e9

S frequency (Hz)

- constexpr double [FREQ1_GLO](#) = 1.60200e9

GLONASS G1 base frequency (Hz)

- constexpr double [DFRQ1_GLO](#) = 0.56250e6

GLONASS G1 bias frequency (Hz/n)

- constexpr double [FREQ2_GLO](#) = 1.24600e9

GLONASS G2 base frequency (Hz)

- constexpr double [DFRQ2_GLO](#) = 0.43750e6

GLONASS G2 bias frequency (Hz/n)

- constexpr double [FREQ3_GLO](#) = 1.202025e9

GLONASS G3 frequency (Hz)

- constexpr double [FREQ1_BDS](#) = 1.561098e9

BeiDou B1 frequency (Hz)

- constexpr double [FREQ2_BDS](#) = 1.20714e9
BeiDou B2 frequency (Hz)
- constexpr double [FREQ3_BDS](#) = 1.26852e9
BeiDou B3 frequency (Hz)
- const std::unordered_map< std::string, double > [SIGNAL_FREQ_MAP](#)
- constexpr uint32_t [CODE_NONE](#) = 0
obs code: none or unknown
- constexpr uint32_t [CODE_L1C](#) = 1
obs code: L1C/A, G1C/A, E1C (GPS, GLO, GAL, QZS, SBS)
- constexpr uint32_t [CODE_L1P](#) = 2
obs code: L1P, G1P (GPS, GLO)
- constexpr uint32_t [CODE_L1W](#) = 3
obs code: L1 Z-track (GPS)
- constexpr uint32_t [CODE_L1Y](#) = 4
obs code: L1Y (GPS)
- constexpr uint32_t [CODE_L1M](#) = 5
obs code: L1M (GPS)
- constexpr uint32_t [CODE_L1N](#) = 6
obs code: L1codeless (GPS)
- constexpr uint32_t [CODE_L1S](#) = 7
obs code: L1C(D) (GPS, QZS)
- constexpr uint32_t [CODE_L1L](#) = 8
obs code: L1C(P) (GPS, QZS)
- constexpr uint32_t [CODE_L1E](#) = 9
(not used)
- constexpr uint32_t [CODE_L1A](#) = 10
obs code: E1A (GAL)
- constexpr uint32_t [CODE_L1B](#) = 11
obs code: E1B (GAL)
- constexpr uint32_t [CODE_L1X](#) = 12
obs code: E1B+C, L1C(D+P) (GAL, QZS)
- constexpr uint32_t [CODE_L1Z](#) = 13
obs code: E1A+B+C, L1SAIF (GAL, QZS)
- constexpr uint32_t [CODE_L2C](#) = 14
obs code: L2C/A, G1C/A (GPS, GLO)
- constexpr uint32_t [CODE_L2D](#) = 15
obs code: L2 L1C/A-(P2-P1) (GPS)
- constexpr uint32_t [CODE_L2S](#) = 16
obs code: L2C(M) (GPS, QZS)
- constexpr uint32_t [CODE_L2L](#) = 17
obs code: L2C(L) (GPS, QZS)
- constexpr uint32_t [CODE_L2X](#) = 18
obs code: L2C(M+L), B1I+Q (GPS, QZS, BDS)
- constexpr uint32_t [CODE_L2P](#) = 19
obs code: L2P, G2P (GPS, GLO)
- constexpr uint32_t [CODE_L2W](#) = 20
obs code: L2 Z-track (GPS)
- constexpr uint32_t [CODE_L2Y](#) = 21
obs code: L2Y (GPS)
- constexpr uint32_t [CODE_L2M](#) = 22
obs code: L2M (GPS)

- constexpr uint32_t `CODE_L2N` = 23
obs code: L2codeless (GPS)
- constexpr uint32_t `CODE_L5I` = 24
obs code: L5/E5aI (GPS,GAL,QZS,SBS)
- constexpr uint32_t `CODE_L5Q` = 25
obs code: L5/E5aQ (GPS,GAL,QZS,SBS)
- constexpr uint32_t `CODE_L5X` = 26
obs code: L5/E5aI+Q/L5B+C (GPS,GAL,QZS,IRN,SBS)
- constexpr uint32_t `CODE_L7I` = 27
obs code: E5bI,B2I (GAL,BDS)
- constexpr uint32_t `CODE_L7Q` = 28
obs code: E5bQ,B2Q (GAL,BDS)
- constexpr uint32_t `CODE_L7X` = 29
obs code: E5bI+Q,B2I+Q (GAL,BDS)
- constexpr uint32_t `CODE_L6A` = 30
obs code: E6A (GAL)
- constexpr uint32_t `CODE_L6B` = 31
obs code: E6B (GAL)
- constexpr uint32_t `CODE_L6C` = 32
obs code: E6C (GAL)
- constexpr uint32_t `CODE_L6X` = 33
obs code: E6B+C,LEXS+L,B3I+Q (GAL,QZS,BDS)
- constexpr uint32_t `CODE_L6Z` = 34
obs code: E6A+B+C (GAL)
- constexpr uint32_t `CODE_L6S` = 35
obs code: LEXS (QZS)
- constexpr uint32_t `CODE_L6L` = 36
obs code: LEXL (QZS)
- constexpr uint32_t `CODE_L8I` = 37
obs code: E5(a+b)I (GAL)
- constexpr uint32_t `CODE_L8Q` = 38
obs code: E5(a+b)Q (GAL)
- constexpr uint32_t `CODE_L8X` = 39
obs code: E5(a+b)I+Q (GAL)
- constexpr uint32_t `CODE_L2I` = 40
obs code: B1I (BDS)
- constexpr uint32_t `CODE_L2Q` = 41
obs code: B1Q (BDS)
- constexpr uint32_t `CODE_L6I` = 42
obs code: B3I (BDS)
- constexpr uint32_t `CODE_L6Q` = 43
obs code: B3Q (BDS)
- constexpr uint32_t `CODE_L3I` = 44
obs code: G3I (GLO)
- constexpr uint32_t `CODE_L3Q` = 45
obs code: G3Q (GLO)
- constexpr uint32_t `CODE_L3X` = 46
obs code: G3I+Q (GLO)
- constexpr uint32_t `CODE_L1I` = 47
obs code: B1I (BDS)
- constexpr uint32_t `CODE_L1Q` = 48

- obs code: B1Q (BDS)*
- constexpr uint32_t [CODE_L5A](#) = 49
- obs code: L5A SPS (IRN)*
- constexpr uint32_t [CODE_L5B](#) = 50
- obs code: L5B RS(D) (IRN)*
- constexpr uint32_t [CODE_L5C](#) = 51
- obs code: L5C RS(P) (IRN)*
- constexpr uint32_t [CODE_L9A](#) = 52
- obs code: SA SPS (IRN)*
- constexpr uint32_t [CODE_L9B](#) = 53
- obs code: SB RS(D) (IRN)*
- constexpr uint32_t [CODE_L9C](#) = 54
- obs code: SC RS(P) (IRN)*
- constexpr uint32_t [CODE_L9X](#) = 55
- obs code: SB+C (IRN)*
- constexpr int32_t [MAXCODE](#) = 55
- max number of obs code*
- constexpr int32_t [GPS_CNAV_DATA_PAGE_BITS](#) = 300
- constexpr int32_t [CNAV_TOW_LSB](#) = 6
- constexpr int32_t [CNAV_TOP1_LSB](#) = 300
- constexpr int32_t [CNAV_TOE1_LSB](#) = 300
- constexpr double [CNAV_DELTA_A_LSB](#) = [TWO_N9](#)
- constexpr double [CNAV_A_DOT_LSB](#) = [TWO_N21](#)
- constexpr double [CNAV_DELTA_N0_LSB](#) = [TWO_N44](#) * [GNSS_PI](#)
- constexpr double [CNAV_DELTA_N0_DOT_LSB](#) = [TWO_N57](#) * [GNSS_PI](#)
- constexpr double [CNAV_M0_LSB](#) = [TWO_N32](#) * [GNSS_PI](#)
- constexpr double [CNAV_E_ECCENTRICITY_LSB](#) = [TWO_N34](#)
- constexpr double [CNAV_OMEGA_LSB](#) = [TWO_N32](#) * [GNSS_PI](#)
- constexpr int32_t [CNAV_TOE2_LSB](#) = 300
- constexpr double [CNAV_OMEGA0_LSB](#) = [TWO_N32](#) * [GNSS_PI](#)
- constexpr double [CNAV_I0_LSB](#) = [TWO_N32](#) * [GNSS_PI](#)
- constexpr double [CNAV_DELTA_OMEGA_DOT_LSB](#) = [TWO_N44](#) * [GNSS_PI](#)
- constexpr double [CNAV_I0_DOT_LSB](#) = [TWO_N44](#) * [GNSS_PI](#)
- constexpr double [CNAV_CIS_LSB](#) = [TWO_N30](#)
- constexpr double [CNAV_CIC_LSB](#) = [TWO_N30](#)
- constexpr double [CNAV_CRS_LSB](#) = [TWO_N8](#)
- constexpr double [CNAV_CRC_LSB](#) = [TWO_N8](#)
- constexpr double [CNAV_CUS_LSB](#) = [TWO_N30](#)
- constexpr double [CNAV_CUC_LSB](#) = [TWO_N30](#)
- constexpr int32_t [CNAV_TOP2_LSB](#) = 300
- constexpr int32_t [CNAV_TOC_LSB](#) = 300
- constexpr double [CNAV_AF0_LSB](#) = [TWO_N35](#)
- constexpr double [CNAV_AF1_LSB](#) = [TWO_N48](#)
- constexpr double [CNAV_AF2_LSB](#) = [TWO_N60](#)
- constexpr double [CNAV_TGD_LSB](#) = [TWO_N35](#)
- constexpr double [CNAV_ISCL1_LSB](#) = [TWO_N35](#)
- constexpr double [CNAV_ISCL2_LSB](#) = [TWO_N35](#)
- constexpr double [CNAV_ISCL5I_LSB](#) = [TWO_N35](#)
- constexpr double [CNAV_ISCL5Q_LSB](#) = [TWO_N35](#)
- constexpr double [CNAV_ALPHA0_LSB](#) = [TWO_N30](#)
- constexpr double [CNAV_ALPHA1_LSB](#) = [TWO_N27](#)
- constexpr double [CNAV_ALPHA2_LSB](#) = [TWO_N24](#)
- constexpr double [CNAV_ALPHA3_LSB](#) = [TWO_N24](#)

- constexpr double CNAV_BETA0_LSB = TWO_P11
 - constexpr double CNAV_BETA1_LSB = TWO_P14
 - constexpr double CNAV_BETA2_LSB = TWO_P16
 - constexpr double CNAV_BETA3_LSB = TWO_P16
 - constexpr double CNAV_A0_LSB = TWO_N35
 - constexpr double CNAV_A1_LSB = TWO_N51
 - constexpr double CNAV_A2_LSB = TWO_N68
 - constexpr int32_t CNAV_DELTA_TLS_LSB = 1
 - constexpr int32_t CNAV_TOT_LSB = TWO_P4
 - constexpr int32_t CNAV_WN_OT_LSB = 1
 - constexpr int32_t CNAV_WN_LSF_LSB = 1
 - constexpr int32_t CNAV_DN_LSB = 1
 - constexpr int32_t CNAV_DELTA_TLSF_LSB = 1
 - constexpr double CNAV_A_REF = 26559710.0
 - constexpr double CNAV_OMEGA_DOT_REF = -2.6e-9
 - constexpr double CNAV_QZSS_A_REF = 42164200.0
 - constexpr double GPS_L1_FREQ_HZ = FREQ1
- L1 [Hz].*
- constexpr double GPS_L1_CA_CODE_RATE_CPS = 1.023e6
- GPS L1 C/A code rate [chips/s].*
- constexpr double GPS_L1_CA_CODE_LENGTH_CHIPS = 1023.0
- GPS L1 C/A code length [chips].*
- constexpr double GPS_L1_CA_CODE_PERIOD_S = 0.001
- GPS L1 C/A code period [seconds].*
- constexpr double GPS_L1_CA_CHIP_PERIOD_S = 9.7752e-07
- GPS L1 C/A chip period [seconds].*
- constexpr uint32_t GPS_L1_CA_CODE_PERIOD_MS = 1U
- GPS L1 C/A code period [ms].*
- constexpr uint32_t GPS_L1_CA_BIT_PERIOD_MS = 20U
- GPS L1 C/A bit period [ms].*
- constexpr double MAX_TOA_DELAY_MS = 20.0
- Maximum Time-Of-Arrival (TOA) difference between satellites for a receiver operated on Earth surface is 20 ms.*
- constexpr uint32_t GPS_L1_CA_OPT_ACQ_FS_SPS = 2000000
- Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.*
- constexpr int32_t GPS_L1_CA_HISTORY_DEEP = 100
 - constexpr double GPS_CA_PREAMBLE_DURATION_S = 0.160
 - constexpr int32_t GPS_CA_PREAMBLE_LENGTH_BITS = 8
 - constexpr int32_t GPS_CA_PREAMBLE_LENGTH_SYMBOLS = 160
 - constexpr int32_t GPS_CA_PREAMBLE_DURATION_MS = 160
 - constexpr int32_t GPS_CA_TELEMETRY_RATE_BITS_SECOND = 50
- NAV message bit rate [bits/s].*
- constexpr int32_t GPS_CA_TELEMETRY_SYMBOLS_PER_BIT = 20
 - constexpr int32_t GPS_CA_TELEMETRY_RATE_SYMBOLS_SECOND = GPS_CA_TELEMETRY_RATE_BITS_SECOND * GPS_CA_TELEMETRY_SYMBOLS_PER_BIT
- NAV message bit rate [symbols/s].*
- constexpr int32_t GPS_WORD_LENGTH = 4
- CRC + GPS WORD (-2 -1 0 ... 29) Bits = 4 bytes.*
- constexpr int32_t GPS_SUBFRAME_LENGTH = 40
- GPS_WORD_LENGTH x 10 = 40 bytes.*
- constexpr int32_t GPS_SUBFRAME_BITS = 300
- Number of bits per subframe in the NAV message [bits].*
- constexpr int32_t GPS_SUBFRAME_SECONDS = 6

- constexpr double `ALM_AF0_LSB` = `TWO_N20`
- constexpr double `ALM_AF1_LSB` = `TWO_N38`
- constexpr double `GPS_L2_FREQ_HZ` = `FREQ2`
L2 [Hz].
- constexpr double `GPS_L2_L_PERIOD_S` = 1.5
GPS L2 L code period [seconds].
- constexpr double `GPS_L2_M_CODE_RATE_CPS` = 0.5115e6
GPS L2 M code rate [chips/s].
- constexpr double `GPS_L2_M_CODE_RATE_L_ZEROED_CPS` = 1.023e6
GPS L2 M code rate with L2 M Zeroed [chips/s].
- constexpr double `GPS_L2_M_PERIOD_S` = 0.02
GPS L2 M code period [seconds].
- constexpr double `GPS_L2_L_CODE_RATE_CPS` = 0.5115e6
GPS L2 L code rate [chips/s].
- constexpr uint32_t `GPS_L2_M_CODE_PERIOD_MS` = 20
GPS L2 L code period [ms].
- constexpr int32_t `GPS_L2_M_CODE_LENGTH_CHIPS` = 10230
GPS L2 M code length [chips].
- constexpr int32_t `GPS_L2_M_CODE_LENGTH_CHIPS_L_ZEROED` = 2 * `GPS_L2_M_CODE_LENGTH_CHIPS`
GPS L2 M code length with L2 CL zeroed [chips].
- constexpr int32_t `GPS_L2_L_CODE_LENGTH_CHIPS` = 767250
GPS L2 L code length [chips].
- constexpr int32_t `GPS_L2_CNAV_DATA_PAGE_BITS` = 300
GPS L2 CNAV page length, including preamble and CRC [bits].
- constexpr int32_t `GPS_L2_SYMBOLS_PER_BIT` = 2
- constexpr int32_t `GPS_L2_SAMPLES_PER_SYMBOL` = 1
- constexpr int32_t `GPS_L2_CNAV_DATA_PAGE_SYMBOLS` = 600
- constexpr int32_t `GPS_L2_CNAV_DATA_PAGE_DURATION_S` = 12
- constexpr int32_t `GPS_L2C_HISTORY_DEEP` = 5
- constexpr uint32_t `GPS_L2C_OPT_ACQ_FS_SPS` = 2000000
Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.
- constexpr int32_t `GPS_L2C_M_INIT_REG` [115]
- constexpr double `GPS_L5_FREQ_HZ` = `FREQ5`
L5 [Hz].
- constexpr double `GPS_L5I_CODE_RATE_CPS` = 10.23e6
GPS L5I code rate [chips/s].
- constexpr double `GPS_L5I_PERIOD_S` = 0.001
GPS L5I code period [seconds].
- constexpr double `GPS_L5I_SYMBOL_PERIOD_S` = 0.01
GPS L5I symbol period [seconds].
- constexpr double `GPS_L5Q_CODE_RATE_CPS` = 10.23e6
GPS L5Q code rate [chips/s].
- constexpr double `GPS_L5Q_PERIOD_S` = 0.001
GPS L5Q code period [seconds].
- constexpr int32_t `GPS_L5Q_CODE_LENGTH_CHIPS` = 10230
GPS L5Q code length [chips].
- constexpr int32_t `GPS_L5I_CODE_LENGTH_CHIPS` = 10230
GPS L5I code length [chips].
- constexpr int32_t `GPS_L5I_PERIOD_MS` = 1
GPS L5I code period [ms].
- constexpr int32_t `GPS_L5I_SYMBOL_PERIOD_MS` = 10

GPS L5I symbol period [ms].

- constexpr int32_t `GPS_L5_HISTORY_DEEP` = 5
- constexpr uint32_t `GPS_L5_OPT_ACQ_FS_SPS` = 10000000

Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.

- constexpr int32_t `GPS_L5I_INIT_REG` [210]
- constexpr int32_t `GPS_L5Q_INIT_REG` [210]
- constexpr int32_t `GPS_L5_CNAV_DATA_PAGE_BITS` = 300

GPS L5 CNAV page length, including preamble and CRC [bits].

- constexpr int32_t `GPS_L5_SYMBOLS_PER_BIT` = 2
- constexpr int32_t `GPS_L5_SAMPLES_PER_SYMBOL` = 10
- constexpr int32_t `GPS_L5_CNAV_DATA_PAGE_SYMBOLS` = 600
- constexpr int32_t `GPS_L5_CNAV_DATA_PAGE_DURATION_S` = 6
- constexpr int32_t `GPS_L5I_NH_CODE_LENGTH` = 10
- constexpr int32_t `GPS_L5I_NH_CODE` [10] = {0, 0, 0, 0, 1, 1, 0, 1, 0, 1}
- constexpr int32_t `GPS_L5Q_NH_CODE_LENGTH` = 20
- constexpr int32_t `GPS_L5Q_NH_CODE` [20] = {0, 0, 0, 0, 0, 1, 0, 0, 1, 1, 0, 1, 0, 1, 0, 0, 1, 1, 1, 0}
- constexpr char `GPS_L5I_NH_CODE_STR` [11] = "0000110101"
- constexpr char `GPS_L5Q_NH_CODE_STR` [21] = "00000100110101001110"
- constexpr double `GNSS_OMEGA_EARTH_DOT` = 7.2921151467e-5

Default Earth rotation rate, [rad/s].

- constexpr double `SPEED_OF_LIGHT_M_S` = 299792458.0

Speed of light in vacuum [m/s].

- constexpr double `SPEED_OF_LIGHT_M_MS` = 299792.4580

Speed of light in vacuum [m/ms].

- constexpr double `GPS_GM` = 3.986005e14

Universal gravitational constant times the mass of the Earth, [m^3/s^2] IS-GPS-200M, 20.3.3.3.3.1.

- constexpr double `GPS_F` = -4.442807633e-10

Constant, [$s/(m)^{1/2}$], IS-GPS-200M, 20.3.3.3.3.1.

- constexpr double `GALILEO_GM` = 3.986004418e14

Geocentric gravitational constant [m^3/s^2], OS SIS ICD v2.0, pag. 44.

- constexpr double `GALILEO_F` = -4.442807309e-10

Constant, [$s/(m)^{1/2}$], OS SIS ICD v2.0, pag. 47.

- constexpr double `GLONASS_OMEGA_EARTH_DOT` = 7.292115e-5

Earth rotation rate, [rad/s] ICD L1, L2 GLONASS Edition 5.1 2008 pag. 55.

- constexpr double `GLONASS_GM` = 398600.44e9

Universal gravitational constant times the mass of the Earth, [m^3/s^2].

- constexpr double `BEIDOU_OMEGA_EARTH_DOT` = 7.2921150e-5

Earth rotation rate, [rad/s] as defined in BDS-SIS-ICD-B1I-3.0 2019-02, pag. 3.

- constexpr double `BEIDOU_GM` = 3.986004418e14

Universal gravitational constant times the mass of the Earth, [m^3/s^2] as defined in CGCS2000.

- constexpr double `BEIDOU_F` = -4.442807309e-10

Constant, [$s/(m)^{1/2}$] $F = -2(GM)^{.5}/C^2$.

- constexpr double `GNSS_PI` = 3.1415926535898

pi constant as defined for GNSS

- constexpr double `HALF_PI` = `GNSS_PI` / 2.0

pi/2

- constexpr double `TWO_PI` = 2.0 * `GNSS_PI`

*2 * pi*

- constexpr double `TWO_P3` = 8.0

2^3

- constexpr double `TWO_P4` = 16.0

2^4

- constexpr double TWO_P8 = 256.0
 2^8
- constexpr double TWO_P11 = 2048.0
 2^{11}
- constexpr double TWO_P12 = 4096.0
 2^{12}
- constexpr double TWO_P14 = 16384.0
 2^{14}
- constexpr double TWO_P16 = 65536.0
 2^{16}
- constexpr double TWO_P19 = 524288.0
 2^{19}
- constexpr double TWO_P31 = 2147483648.0
 2^{31}
- constexpr double TWO_P32 = 4294967296.0
 2^{32}
- constexpr double TWO_P56 = 7.205759403792794e+016
 2^{56}
- constexpr double TWO_P57 = 1.441151880758559e+017
 2^{57}
- constexpr double TWO_N2 = 0.25
 2^{-2}
- constexpr double TWO_N5 = 0.03125
 2^{-5}
- constexpr double TWO_N6 = 0.015625
 2^{-6}
- constexpr double TWO_N8 = 0.00390625
 2^{-8}
- constexpr double TWO_N9 = 0.001953125
 2^{-9}
- constexpr double TWO_N10 = 0.0009765625
 2^{-10}
- constexpr double TWO_N11 = 4.882812500000000e-004
 2^{-11}
- constexpr double TWO_N14 = 0.00006103515625
 2^{-14}
- constexpr double TWO_N15 = 3.051757812500000e-005
 2^{-15}
- constexpr double TWO_N16 = 1.525878906250000e-005
 2^{-16}
- constexpr double TWO_N17 = 7.629394531250000e-006
 2^{-17}
- constexpr double TWO_N18 = 3.814697265625000e-006
 2^{-18}
- constexpr double TWO_N19 = 1.907348632812500e-006
 2^{-19}
- constexpr double TWO_N20 = 9.536743164062500e-007
 2^{-20}
- constexpr double TWO_N21 = 4.768371582031250e-007
 2^{-21}
- constexpr double TWO_N22 = 2.384185791015625e-007

- 2^{-22}
- constexpr double [TWO_N23](#) = 1.192092895507810e-007
- 2^{-23}
- constexpr double [TWO_N24](#) = 5.960464477539063e-008
- 2^{-24}
- constexpr double [TWO_N25](#) = 2.980232238769531e-008
- 2^{-25}
- constexpr double [TWO_N26](#) = 1.490116119384765e-009
- 2^{-26}
- constexpr double [TWO_N27](#) = 7.450580596923828e-009
- 2^{-27}
- constexpr double [TWO_N29](#) = 1.862645149230957e-009
- 2^{-29}
- constexpr double [TWO_N30](#) = 9.313225746154785e-010
- 2^{-30}
- constexpr double [TWO_N31](#) = 4.656612873077393e-010
- 2^{-31}
- constexpr double [TWO_N32](#) = 2.328306436538696e-010
- 2^{-32}
- constexpr double [TWO_N33](#) = 1.164153218269348e-010
- 2^{-33}
- constexpr double [TWO_N34](#) = 5.82076609134674e-011
- 2^{-34}
- constexpr double [TWO_N35](#) = 2.91038304567337e-011
- 2^{-35}
- constexpr double [TWO_N38](#) = 3.637978807091713e-012
- 2^{-38}
- constexpr double [TWO_N39](#) = 1.818989403545856e-012
- 2^{-39}
- constexpr double [TWO_N40](#) = 9.094947017729280e-013
- 2^{-40}
- constexpr double [TWO_N43](#) = 1.136868377216160e-013
- 2^{-43}
- constexpr double [TWO_N44](#) = 5.684341886080802e-14
- 2^{-44}
- constexpr double [TWO_N46](#) = 1.4210854715202e-014
- 2^{-46}
- constexpr double [TWO_N48](#) = 3.552713678800501e-15
- 2^{-46}
- constexpr double [TWO_N50](#) = 8.881784197001252e-016
- 2^{-50}
- constexpr double [TWO_N51](#) = 4.44089209850063e-016
- 2^{-51}
- constexpr double [TWO_N55](#) = 2.775557561562891e-017
- 2^{-55}
- constexpr double [TWO_N57](#) = 6.938893903907228e-18
- 2^{-57}
- constexpr double [TWO_N59](#) = 1.73472347597681e-018
- 2^{-59}
- constexpr double [TWO_N60](#) = 8.673617379884036e-19
- 2^{-60}

- [illegible]

10.2.6.1 Detailed Description

Classes containing info about system parameters for the different GNSS.
GNSS parameters

10.2.6.2 Macro Definition Documentation

10.2.6.2.1 DISPLAY_COLORS

```
#define DISPLAY_COLORS 1
```

Definition at line 29 of file [display.h](#).

10.2.6.2.2 GLONASS_GNAV_PREAMBLE

```
#define GLONASS_GNAV_PREAMBLE
Value:
{
    1, 1, 1, 1, 1, 0, 0, 0, 1, 1, 0, 1, 1, 1, 0, 1, 0, 1, 0, 0, 0, 0, 1, 0, 0, 1, 0, 1, 1, 0 }
Definition at line 94 of file GLONASS_L1_L2_CA.h.
```

10.2.6.2.3 GLONASS GNAV PREAMBLE SAMPLES

```
#define GLONASS_GNAV_PREAMBLE_SAMPLES
Value:
    {
        1, 1, 1, 1, 1, -1, -1, -1, 1, 1, -1, 1, 1, 1, -1, 1, -1, 1, -1, -1, -1, -1, 1, -1, -1, 1, -1, 1, 1,
        -1}
Definition at line 98 of file GLONASS L1 L2 CA.h.
```

10.2.6.3 Enumeration Type Documentation

10.2.6.3.1 CnavSystem

enum class CnavSystem [strong]

Definition at line 39 of file [gps_cnav_navigation_message.h](#).

10.2.6.3.2 LnavSystem

enum class LnavSystem [strong]

Definition at line 40 of file [gps_navigation_message.h](#).

10.2.6.4 Function Documentation

10.2.6.4.1 ALPHA_0()

```
const std::vector< std::pair< int32_t, int32_t > > ALPHA_0 (
    {{69, 8}} )
```

Todo read all pages of subframe 4

10.2.6.4.2 T_OA()

```
const std::vector< std::pair< int32_t, int32_t > > T_OA (
    {{69, 8}} )
```

Todo read all pages of subframe 5

10.2.6.5 Variable Documentation

10.2.6.5.1 A0_6_LSB

double A0_6_LSB = [TWO_N30](#) [constexpr]

Definition at line 145 of file [Galileo_INAV.h](#).

10.2.6.5.2 A1_6_LSB

double A1_6_LSB = [TWO_N50](#) [constexpr]

Definition at line 147 of file [Galileo_INAV.h](#).

10.2.6.5.3 A_0_LSB

double A_0_LSB = [TWO_N30](#) [constexpr]

Definition at line 171 of file [GPS_L1_CA.h](#).

10.2.6.5.4 A_0G_10_LSB

double A_0G_10_LSB = [TWO_N35](#) [constexpr]

Definition at line 242 of file [Galileo_INAV.h](#).

10.2.6.5.5 A_1_LSB

double A_1_LSB = [TWO_N50](#) [constexpr]

Definition at line 169 of file [GPS_L1_CA.h](#).

10.2.6.5.6 A_1_LSB_GAL

double A_1_LSB_GAL = [TWO_N19](#) [constexpr]

Definition at line 63 of file [Galileo_INAV.h](#).

10.2.6.5.7 A_1G_10_LSB

double A_1G_10_LSB = TWO_N51 [constexpr]
Definition at line 244 of file [Galileo_INAV.h](#).

10.2.6.5.8 A_F0_LSB

double A_F0_LSB = TWO_N31 [constexpr]
Definition at line 102 of file [GPS_L1_CA.h](#).

10.2.6.5.9 A_F1_LSB

double A_F1_LSB = TWO_N43 [constexpr]
Definition at line 100 of file [GPS_L1_CA.h](#).

10.2.6.5.10 A_F2_LSB

double A_F2_LSB = TWO_N55 [constexpr]
Definition at line 98 of file [GPS_L1_CA.h](#).

10.2.6.5.11 AF0_10_LSB

double AF0_10_LSB = TWO_N19 [constexpr]
Definition at line 236 of file [Galileo_INAV.h](#).

10.2.6.5.12 AF0_4_LSB

double AF0_4_LSB = TWO_N34 [constexpr]
Definition at line 106 of file [Galileo_INAV.h](#).

10.2.6.5.13 AF0_8_LSB

double AF0_8_LSB = TWO_N19 [constexpr]
Definition at line 183 of file [Galileo_INAV.h](#).

10.2.6.5.14 AF0_9_LSB

double AF0_9_LSB = TWO_N19 [constexpr]
Definition at line 211 of file [Galileo_INAV.h](#).

10.2.6.5.15 AF1_10_LSB

double AF1_10_LSB = TWO_N38 [constexpr]
Definition at line 238 of file [Galileo_INAV.h](#).

10.2.6.5.16 AF1_4_LSB

double AF1_4_LSB = TWO_N46 [constexpr]
Definition at line 108 of file [Galileo_INAV.h](#).

10.2.6.5.17 AF1_8_LSB

double AF1_8_LSB = TWO_N38 [constexpr]
Definition at line 185 of file [Galileo_INAV.h](#).

10.2.6.5.18 AF1_9_LSB

double AF1_9_LSB = TWO_N38 [constexpr]
Definition at line 213 of file [Galileo_INAV.h](#).

10.2.6.5.19 AF2_4_LSB

double AF2_4_LSB = TWO_N59 [constexpr]
Definition at line 110 of file [Galileo_INAV.h](#).

10.2.6.5.20 AI0_5_LSB

double AI0_5_LSB = TWO_N2 [constexpr]
Definition at line 118 of file [Galileo_INAV.h](#).

10.2.6.5.21 AI1_5_LSB

double AI1_5_LSB = TWO_N8 [constexpr]
Definition at line 120 of file [Galileo_INAV.h](#).

10.2.6.5.22 AI2_5_LSB

double AI2_5_LSB = TWO_N15 [constexpr]
Definition at line 122 of file [Galileo_INAV.h](#).

10.2.6.5.23 ALM_AF0_LSB

double ALM_AF0_LSB = TWO_N20 [constexpr]
Definition at line 249 of file [GPS_L1_CA.h](#).

10.2.6.5.24 ALM_AF1_LSB

double ALM_AF1_LSB = TWO_N38 [constexpr]
Definition at line 251 of file [GPS_L1_CA.h](#).

10.2.6.5.25 ALM_DELTAI_LSB

double ALM_DELTAI_LSB = TWO_N19 [constexpr]
Definition at line 235 of file [GPS_L1_CA.h](#).

10.2.6.5.26 ALM_ECC_LSB

double ALM_ECC_LSB = TWO_N21 [constexpr]
Definition at line 231 of file [GPS_L1_CA.h](#).

10.2.6.5.27 ALM_MZERO_LSB

double ALM_MZERO_LSB = TWO_N23 [constexpr]
Definition at line 246 of file [GPS_L1_CA.h](#).

10.2.6.5.28 ALM_OMEGA_LSB

double ALM_OMEGA_LSB = TWO_N23 [constexpr]
Definition at line 244 of file [GPS_L1_CA.h](#).

10.2.6.5.29 ALM_OMEGADOT_LSB

double ALM_OMEGADOT_LSB = TWO_N38 [constexpr]
Definition at line 237 of file [GPS_L1_CA.h](#).

10.2.6.5.30 ALM_OMEGAZERO_LSB

double ALM_OMEGAZERO_LSB = TWO_N23 [constexpr]
Definition at line 242 of file [GPS_L1_CA.h](#).

10.2.6.5.31 ALM_SQUAREA_LSB

double ALM_SQUAREA_LSB = TWO_N11 [constexpr]
Definition at line 240 of file [GPS_L1_CA.h](#).

10.2.6.5.32 ALM_TOA_LSB

int32_t ALM_TOA_LSB = static_cast<int32_t>(TWO_P12) [constexpr]
Definition at line 233 of file [GPS_L1_CA.h](#).

10.2.6.5.33 ALPHA_0_LSB

double ALPHA_0_LSB = TWO_N30 [constexpr]
Definition at line 153 of file [GPS_L1_CA.h](#).

10.2.6.5.34 ALPHA_1_LSB

double ALPHA_1_LSB = TWO_N27 [constexpr]
Definition at line 155 of file [GPS_L1_CA.h](#).

10.2.6.5.35 ALPHA_2_LSB

double ALPHA_2_LSB = TWO_N24 [constexpr]
Definition at line 157 of file [GPS_L1_CA.h](#).

10.2.6.5.36 ALPHA_3_LSB

double ALPHA_3_LSB = TWO_N24 [constexpr]
Definition at line 159 of file [GPS_L1_CA.h](#).

10.2.6.5.37 AODO_LSB

int32_t AODO_LSB = 900 [constexpr]
Definition at line 124 of file [GPS_L1_CA.h](#).

10.2.6.5.38 AS2R

double AS2R = D2R / 3600.0 [constexpr]
arc sec to radian
Definition at line 126 of file [MATH_CONSTANTS.h](#).

10.2.6.5.39 AU

double AU = 149597870691.0 [constexpr]
1 Astronomical Unit AU (m) distance from Earth to the Sun.
Definition at line 128 of file [MATH_CONSTANTS.h](#).

10.2.6.5.40 BEIDOU_B1I_CODE_LENGTH_CHIPS

double BEIDOU_B1I_CODE_LENGTH_CHIPS = 2046.0 [constexpr]
Beidou B1I code length [chips].
Definition at line 34 of file [Beidou_B1I.h](#).

10.2.6.5.41 BEIDOU_B1I_CODE_PERIOD_MS

uint32_t BEIDOU_B1I_CODE_PERIOD_MS = 1 [constexpr]
Beidou B1I code period [ms].
Definition at line 38 of file [Beidou_B1I.h](#).

10.2.6.5.42 BEIDOU_B1I_CODE_PERIOD_S

```
double BEIDOU_B1I_CODE_PERIOD_S = 0.001 [constexpr]
```

Beidou B1I code period [seconds].

Definition at line 35 of file [Beidou_B1I.h](#).

10.2.6.5.43 BEIDOU_B1I_CODE_RATE_CPS

```
double BEIDOU_B1I_CODE_RATE_CPS = 2.046e6 [constexpr]
```

Beidou B1I code rate [chips/s].

Definition at line 33 of file [Beidou_B1I.h](#).

10.2.6.5.44 BEIDOU_B1I_D2_SECONDARY_CODE_STR

```
char BEIDOU_B1I_D2_SECONDARY_CODE_STR[3] = "00" [constexpr]
```

Definition at line 51 of file [Beidou_B1I.h](#).

10.2.6.5.45 BEIDOU_B1I_FREQ_HZ

```
double BEIDOU_B1I_FREQ_HZ = FREQ1\_BDS [constexpr]
```

B1I [Hz].

Definition at line 32 of file [Beidou_B1I.h](#).

10.2.6.5.46 BEIDOU_B1I_GEO_PREAMBLE_LENGTH_SYMBOLS

```
int32_t BEIDOU_B1I_GEO_PREAMBLE_LENGTH_SYMBOLS = 22 [constexpr]
```

Definition at line 42 of file [Beidou_B1I.h](#).

10.2.6.5.47 BEIDOU_B1I_GEO_PREAMBLE_SYMBOLS_STR

```
char BEIDOU_B1I_GEO_PREAMBLE_SYMBOLS_STR[23] = "1111110000001100001100" [constexpr]
```

Definition at line 50 of file [Beidou_B1I.h](#).

10.2.6.5.48 BEIDOU_B1I_GEO_TELEMETRY_SYMBOLS_PER_BIT

```
int32_t BEIDOU_B1I_GEO_TELEMETRY_SYMBOLS_PER_BIT = 2 [constexpr]
```

Definition at line 46 of file [Beidou_B1I.h](#).

10.2.6.5.49 BEIDOU_B1I_OPT_ACQ_FS_SPS

```
double BEIDOU_B1I_OPT_ACQ_FS_SPS = 10e6 [constexpr]
```

Definition at line 37 of file [Beidou_B1I.h](#).

10.2.6.5.50 BEIDOU_B1I_PREAMBLE_DURATION_MS

```
int32_t BEIDOU_B1I_PREAMBLE_DURATION_MS = 220 [constexpr]
```

Definition at line 43 of file [Beidou_B1I.h](#).

10.2.6.5.51 BEIDOU_B1I_PREAMBLE_DURATION_S

```
double BEIDOU_B1I_PREAMBLE_DURATION_S = 0.220 [constexpr]
```

Definition at line 36 of file [Beidou_B1I.h](#).

10.2.6.5.52 BEIDOU_B1I_PREAMBLE_LENGTH_BITS

```
uint32_t BEIDOU_B1I_PREAMBLE_LENGTH_BITS = 11 [constexpr]
```

Definition at line 39 of file [Beidou_B1I.h](#).

10.2.6.5.53 BEIDOU_B1I_PREAMBLE_LENGTH_SYMBOLS

`uint32_t BEIDOU_B1I_PREAMBLE_LENGTH_SYMBOLS = 220 [constexpr]`
 Definition at line 40 of file [Beidou_B1I.h](#).

10.2.6.5.54 BEIDOU_B1I_SECONDARY_CODE_LENGTH

`int32_t BEIDOU_B1I_SECONDARY_CODE_LENGTH = 20 [constexpr]`
 Definition at line 41 of file [Beidou_B1I.h](#).

10.2.6.5.55 BEIDOU_B1I_SECONDARY_CODE_STR

`char BEIDOU_B1I_SECONDARY_CODE_STR[21] = "00000100110101001110" [constexpr]`
 Definition at line 49 of file [Beidou_B1I.h](#).

10.2.6.5.56 BEIDOU_B1I_TELEMETRY_RATE_BITS_SECOND

`int32_t BEIDOU_B1I_TELEMETRY_RATE_BITS_SECOND = 50 [constexpr]`
 Definition at line 44 of file [Beidou_B1I.h](#).

10.2.6.5.57 BEIDOU_B1I_TELEMETRY_RATE_SYMBOLS_SECOND

`int32_t BEIDOU_B1I_TELEMETRY_RATE_SYMBOLS_SECOND = BEIDOU_B1I_TELEMETRY_RATE_BITS_SECOND *
 BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT [constexpr]`
 Definition at line 48 of file [Beidou_B1I.h](#).

10.2.6.5.58 BEIDOU_B1I_TELEMETRY_SYMBOL_PERIOD_MS

`int32_t BEIDOU_B1I_TELEMETRY_SYMBOL_PERIOD_MS = static_cast<int32_t>(static_cast<uint32_t>(
 t>(BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT) * BEIDOU_B1I_CODE_PERIOD_MS) [constexpr]`
 Definition at line 47 of file [Beidou_B1I.h](#).

10.2.6.5.59 BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT

`int32_t BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT = 20 [constexpr]`
 Definition at line 45 of file [Beidou_B1I.h](#).

10.2.6.5.60 BEIDOU_B3I_CODE_LENGTH_CHIPS

`double BEIDOU_B3I_CODE_LENGTH_CHIPS = 10230.0 [constexpr]`
 BeiDou B3I code length [chips].
 Definition at line 33 of file [Beidou_B3I.h](#).

10.2.6.5.61 BEIDOU_B3I_CODE_PERIOD_MS

`uint32_t BEIDOU_B3I_CODE_PERIOD_MS = 1 [constexpr]`
 BeiDou B3I code period [ms].
 Definition at line 37 of file [Beidou_B3I.h](#).

10.2.6.5.62 BEIDOU_B3I_CODE_PERIOD_S

`double BEIDOU_B3I_CODE_PERIOD_S = 0.001 [constexpr]`
 BeiDou B3I code period [seconds].
 Definition at line 34 of file [Beidou_B3I.h](#).

10.2.6.5.63 BEIDOU_B3I_CODE_RATE_CPS

`double BEIDOU_B3I_CODE_RATE_CPS = 10.23e6 [constexpr]`
 BeiDou B3I code rate [chips/s].
 Definition at line 32 of file [Beidou_B3I.h](#).

10.2.6.5.64 BEIDOU_B3I_D2_SECONDARY_CODE_STR

char BEIDOU_B3I_D2_SECONDARY_CODE_STR[3] = "00" [constexpr]
Definition at line 50 of file [Beidou_B3I.h](#).

10.2.6.5.65 BEIDOU_B3I_FREQ_HZ

double BEIDOU_B3I_FREQ_HZ = [FREQ3_BDS](#) [constexpr]
BeiDou B3I [Hz].
Definition at line 31 of file [Beidou_B3I.h](#).

10.2.6.5.66 BEIDOU_B3I_GEO_PREAMBLE_LENGTH_SYMBOLS

int32_t BEIDOU_B3I_GEO_PREAMBLE_LENGTH_SYMBOLS = 22 [constexpr]
Definition at line 41 of file [Beidou_B3I.h](#).

10.2.6.5.67 BEIDOU_B3I_GEO_PREAMBLE_SYMBOLS_STR

char BEIDOU_B3I_GEO_PREAMBLE_SYMBOLS_STR[23] = "1111110000001100001100" [constexpr]
Definition at line 49 of file [Beidou_B3I.h](#).

10.2.6.5.68 BEIDOU_B3I_GEO_TELEMETRY_SYMBOLS_PER_BIT

int32_t BEIDOU_B3I_GEO_TELEMETRY_SYMBOLS_PER_BIT = 2 [constexpr]
Definition at line 45 of file [Beidou_B3I.h](#).

10.2.6.5.69 BEIDOU_B3I_OPT_ACQ_FS_SPS

double BEIDOU_B3I_OPT_ACQ_FS_SPS = 10e6 [constexpr]
Definition at line 36 of file [Beidou_B3I.h](#).

10.2.6.5.70 BEIDOU_B3I_PREAMBLE_DURATION_MS

int32_t BEIDOU_B3I_PREAMBLE_DURATION_MS = 220 [constexpr]
Definition at line 42 of file [Beidou_B3I.h](#).

10.2.6.5.71 BEIDOU_B3I_PREAMBLE_DURATION_S

double BEIDOU_B3I_PREAMBLE_DURATION_S = 0.220 [constexpr]
Definition at line 35 of file [Beidou_B3I.h](#).

10.2.6.5.72 BEIDOU_B3I_PREAMBLE_LENGTH_BITS

uint32_t BEIDOU_B3I_PREAMBLE_LENGTH_BITS = 11 [constexpr]
Definition at line 38 of file [Beidou_B3I.h](#).

10.2.6.5.73 BEIDOU_B3I_PREAMBLE_LENGTH_SYMBOLS

uint32_t BEIDOU_B3I_PREAMBLE_LENGTH_SYMBOLS = 220 [constexpr]
Definition at line 39 of file [Beidou_B3I.h](#).

10.2.6.5.74 BEIDOU_B3I_SECONDARY_CODE_LENGTH

int32_t BEIDOU_B3I_SECONDARY_CODE_LENGTH = 20 [constexpr]
Definition at line 40 of file [Beidou_B3I.h](#).

10.2.6.5.75 BEIDOU_B3I_SECONDARY_CODE_STR

char BEIDOU_B3I_SECONDARY_CODE_STR[21] = "00000100110101001110" [constexpr]
Definition at line 48 of file [Beidou_B3I.h](#).

10.2.6.5.76 BEIDOU_B3I_TELEMETRY_RATE_BITS_SECOND

```
int32_t BEIDOU_B3I_TELEMETRY_RATE_BITS_SECOND = 50 [constexpr]
```

D1 NAV message bit rate [bits/s].

Definition at line 43 of file [Beidou_B3I.h](#).

10.2.6.5.77 BEIDOU_B3I_TELEMETRY_RATE_SYMBOLS_SECOND

```
int32_t BEIDOU_B3I_TELEMETRY_RATE_SYMBOLS_SECOND = BEIDOU_B3I_TELEMETRY_RATE_BITS_SECOND *
```

```
BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT [constexpr]
```

Definition at line 47 of file [Beidou_B3I.h](#).

10.2.6.5.78 BEIDOU_B3I_TELEMETRY_SYMBOL_PERIOD_MS

```
int32_t BEIDOU_B3I_TELEMETRY_SYMBOL_PERIOD_MS = static_cast<int32_t>(static_cast<uint32_t>↵
```

```
t>(BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT) * BEIDOU_B3I_CODE_PERIOD_MS) [constexpr]
```

Definition at line 46 of file [Beidou_B3I.h](#).

10.2.6.5.79 BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT

```
int32_t BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT = 20 [constexpr]
```

Definition at line 44 of file [Beidou_B3I.h](#).

10.2.6.5.80 BEIDOU_DNAV_BDT2GPST_LEAP_SEC_OFFSET

```
int32_t BEIDOU_DNAV_BDT2GPST_LEAP_SEC_OFFSET = 14 [constexpr]
```

Definition at line 89 of file [Beidou_DNAV.h](#).

10.2.6.5.81 BEIDOU_DNAV_BDT2GPST_WEEK_NUM_OFFSET

```
int32_t BEIDOU_DNAV_BDT2GPST_WEEK_NUM_OFFSET = 1356 [constexpr]
```

Definition at line 91 of file [Beidou_DNAV.h](#).

10.2.6.5.82 BEIDOU_DNAV_PREAMBLE

```
char BEIDOU_DNAV_PREAMBLE[12] = "11100010010" [constexpr]
```

Definition at line 96 of file [Beidou_DNAV.h](#).

10.2.6.5.83 BEIDOU_DNAV_PREAMBLE_LENGTH_BITS

```
int32_t BEIDOU_DNAV_PREAMBLE_LENGTH_BITS = 11 [constexpr]
```

Definition at line 84 of file [Beidou_DNAV.h](#).

10.2.6.5.84 BEIDOU_DNAV_PREAMBLE_LENGTH_SYMBOLS

```
int32_t BEIDOU_DNAV_PREAMBLE_LENGTH_SYMBOLS = 11 [constexpr]
```

Definition at line 85 of file [Beidou_DNAV.h](#).

10.2.6.5.85 BEIDOU_DNAV_PREAMBLE_PERIOD_SYMBOLS

```
int32_t BEIDOU_DNAV_PREAMBLE_PERIOD_SYMBOLS = 300 [constexpr]
```

Definition at line 86 of file [Beidou_DNAV.h](#).

10.2.6.5.86 BEIDOU_DNAV_SUBFRAME_DATA_BITS

```
int32_t BEIDOU_DNAV_SUBFRAME_DATA_BITS = 300 [constexpr]
```

Number of bits per subframe in the NAV message [bits].

Definition at line 87 of file [Beidou_DNAV.h](#).

10.2.6.5.87 BEIDOU_DNAV_SUBFRAME_SYMBOLS

`uint32_t BEIDOU_DNAV_SUBFRAME_SYMBOLS = 300 [constexpr]`
Definition at line 93 of file [Beidou_DNAV.h](#).

10.2.6.5.88 BEIDOU_DNAV_WORD_LENGTH_BITS

`uint32_t BEIDOU_DNAV_WORD_LENGTH_BITS = 30 [constexpr]`
Definition at line 95 of file [Beidou_DNAV.h](#).

10.2.6.5.89 BEIDOU_DNAV_WORDS_SUBFRAME

`uint32_t BEIDOU_DNAV_WORDS_SUBFRAME = 10 [constexpr]`
Definition at line 94 of file [Beidou_DNAV.h](#).

10.2.6.5.90 BEIDOU_F

`double BEIDOU_F = -4.442807309e-10 [constexpr]`
Constant, $[s/(m)^{(1/2)}] F = -2(GM)^{.5}/C^2$.
Definition at line 45 of file [MATH_CONSTANTS.h](#).

10.2.6.5.91 BEIDOU_GM

`double BEIDOU_GM = 3.986004418e14 [constexpr]`
Universal gravitational constant times the mass of the Earth, $[m^3/s^2]$ as defined in CGCS2000.
Definition at line 44 of file [MATH_CONSTANTS.h](#).

10.2.6.5.92 BEIDOU_OMEGA_EARTH_DOT

`double BEIDOU_OMEGA_EARTH_DOT = 7.2921150e-5 [constexpr]`
Earth rotation rate, $[rad/s]$ as defined in BDS-SIS-ICD-B1I-3.0 2019-02, pag. 3.
Definition at line 43 of file [MATH_CONSTANTS.h](#).

10.2.6.5.93 BETA_0_LSB

`double BETA_0_LSB = TWO_P11 [constexpr]`
Definition at line 161 of file [GPS_L1_CA.h](#).

10.2.6.5.94 BETA_1_LSB

`double BETA_1_LSB = TWO_P14 [constexpr]`
Definition at line 163 of file [GPS_L1_CA.h](#).

10.2.6.5.95 BETA_2_LSB

`double BETA_2_LSB = TWO_P16 [constexpr]`
Definition at line 165 of file [GPS_L1_CA.h](#).

10.2.6.5.96 BETA_3_LSB

`double BETA_3_LSB = TWO_P16 [constexpr]`
Definition at line 167 of file [GPS_L1_CA.h](#).

10.2.6.5.97 BGD_E1_E5A_5_LSB

`double BGD_E1_E5A_5_LSB = TWO_N32 [constexpr]`
Definition at line 130 of file [Galileo_INAV.h](#).

10.2.6.5.98 BGD_E1_E5B_5_LSB

```
double BGD_E1_E5B_5_LSB = TWO_N32 [constexpr]
```

Definition at line 132 of file [Galileo_INAV.h](#).

10.2.6.5.99 BITS_IN_OCTET

```
int32_t BITS_IN_OCTET = 8 [constexpr]
```

Definition at line 273 of file [Galileo_INAV.h](#).

10.2.6.5.100 C_IC_4_LSB

```
double C_IC_4_LSB = TWO_N29 [constexpr]
```

Definition at line 100 of file [Galileo_INAV.h](#).

10.2.6.5.101 C_IC_LSB

```
double C_IC_LSB = TWO_N29 [constexpr]
```

Definition at line 128 of file [GPS_L1_CA.h](#).

10.2.6.5.102 C_IS_4_LSB

```
double C_IS_4_LSB = TWO_N29 [constexpr]
```

Definition at line 102 of file [Galileo_INAV.h](#).

10.2.6.5.103 C_IS_LSB

```
double C_IS_LSB = TWO_N29 [constexpr]
```

Definition at line 132 of file [GPS_L1_CA.h](#).

10.2.6.5.104 C_RC_3_LSB

```
double C_RC_3_LSB = TWO_N5 [constexpr]
```

Definition at line 90 of file [Galileo_INAV.h](#).

10.2.6.5.105 C_RC_LSB

```
double C_RC_LSB = TWO_N5 [constexpr]
```

Definition at line 136 of file [GPS_L1_CA.h](#).

10.2.6.5.106 C_RS_3_LSB

```
double C_RS_3_LSB = TWO_N5 [constexpr]
```

Definition at line 92 of file [Galileo_INAV.h](#).

10.2.6.5.107 C_RS_LSB

```
double C_RS_LSB = TWO_N5 [constexpr]
```

Definition at line 107 of file [GPS_L1_CA.h](#).

10.2.6.5.108 C_UC_3_LSB

```
double C_UC_3_LSB = TWO_N29 [constexpr]
```

Definition at line 86 of file [Galileo_INAV.h](#).

10.2.6.5.109 C_UC_LSB

```
double C_UC_LSB = TWO_N29 [constexpr]
```

Definition at line 113 of file [GPS_L1_CA.h](#).

10.2.6.5.110 C_US_3_LSB

double C_US_3_LSB = TWO_N29 [constexpr]
Definition at line 88 of file [Galileo_INAV.h](#).

10.2.6.5.111 C_US_LSB

double C_US_LSB = TWO_N29 [constexpr]
Definition at line 117 of file [GPS_L1_CA.h](#).

10.2.6.5.112 CED_af0red_LSB

double CED_af0red_LSB = TWO_N26 [constexpr]
Definition at line 262 of file [Galileo_INAV.h](#).

10.2.6.5.113 CED_af1red_LSB

double CED_af1red_LSB = TWO_N35 [constexpr]
Definition at line 264 of file [Galileo_INAV.h](#).

10.2.6.5.114 CED_DeltaAred_LSB

double CED_DeltaAred_LSB = TWO_P8 [constexpr]
Definition at line 250 of file [Galileo_INAV.h](#).

10.2.6.5.115 CED_DeltaI0red_LSB

double CED_DeltaI0red_LSB = TWO_N22 [constexpr]
Definition at line 256 of file [Galileo_INAV.h](#).

10.2.6.5.116 CED_exred_LSB

double CED_exred_LSB = TWO_N22 [constexpr]
Definition at line 252 of file [Galileo_INAV.h](#).

10.2.6.5.117 CED_eyred_LSB

double CED_eyred_LSB = TWO_N22 [constexpr]
Definition at line 254 of file [Galileo_INAV.h](#).

10.2.6.5.118 CED_lambda0red_LSB

double CED_lambda0red_LSB = TWO_N22 [constexpr]
Definition at line 260 of file [Galileo_INAV.h](#).

10.2.6.5.119 CED_Omega0red_LSB

double CED_Omega0red_LSB = TWO_N22 [constexpr]
Definition at line 258 of file [Galileo_INAV.h](#).

10.2.6.5.120 CNAV_A0_LSB

double CNAV_A0_LSB = TWO_N35 [constexpr]
Definition at line 144 of file [GPS_CNAV.h](#).

10.2.6.5.121 CNAV_A1_LSB

double CNAV_A1_LSB = TWO_N51 [constexpr]
Definition at line 146 of file [GPS_CNAV.h](#).

10.2.6.5.122 CNAV_A2_LSB

```
double CNAV_A2_LSB = TWO_N68 [constexpr]
```

Definition at line 148 of file [GPS_CNAV.h](#).

10.2.6.5.123 CNAV_A_DOT_LSB

```
double CNAV_A_DOT_LSB = TWO_N21 [constexpr]
```

Definition at line 58 of file [GPS_CNAV.h](#).

10.2.6.5.124 CNAV_A_REF

```
double CNAV_A_REF = 26559710.0 [constexpr]
```

Definition at line 162 of file [GPS_CNAV.h](#).

10.2.6.5.125 CNAV_AF0_LSB

```
double CNAV_AF0_LSB = TWO_N35 [constexpr]
```

Definition at line 107 of file [GPS_CNAV.h](#).

10.2.6.5.126 CNAV_AF1_LSB

```
double CNAV_AF1_LSB = TWO_N48 [constexpr]
```

Definition at line 109 of file [GPS_CNAV.h](#).

10.2.6.5.127 CNAV_AF2_LSB

```
double CNAV_AF2_LSB = TWO_N60 [constexpr]
```

Definition at line 111 of file [GPS_CNAV.h](#).

10.2.6.5.128 CNAV_ALPHA0_LSB

```
double CNAV_ALPHA0_LSB = TWO_N30 [constexpr]
```

Definition at line 124 of file [GPS_CNAV.h](#).

10.2.6.5.129 CNAV_ALPHA1_LSB

```
double CNAV_ALPHA1_LSB = TWO_N27 [constexpr]
```

Definition at line 126 of file [GPS_CNAV.h](#).

10.2.6.5.130 CNAV_ALPHA2_LSB

```
double CNAV_ALPHA2_LSB = TWO_N24 [constexpr]
```

Definition at line 128 of file [GPS_CNAV.h](#).

10.2.6.5.131 CNAV_ALPHA3_LSB

```
double CNAV_ALPHA3_LSB = TWO_N24 [constexpr]
```

Definition at line 130 of file [GPS_CNAV.h](#).

10.2.6.5.132 CNAV_BETA0_LSB

```
double CNAV_BETA0_LSB = TWO_P11 [constexpr]
```

Definition at line 132 of file [GPS_CNAV.h](#).

10.2.6.5.133 CNAV_BETA1_LSB

```
double CNAV_BETA1_LSB = TWO_P14 [constexpr]
```

Definition at line 134 of file [GPS_CNAV.h](#).

10.2.6.5.134 CNAV_BETA2_LSB

double CNAV_BETA2_LSB = TWO_P16 [constexpr]
Definition at line 136 of file GPS_CNAV.h.

10.2.6.5.135 CNAV_BETA3_LSB

double CNAV_BETA3_LSB = TWO_P16 [constexpr]
Definition at line 138 of file GPS_CNAV.h.

10.2.6.5.136 CNAV_CIC_LSB

double CNAV_CIC_LSB = TWO_N30 [constexpr]
Definition at line 87 of file GPS_CNAV.h.

10.2.6.5.137 CNAV_CIS_LSB

double CNAV_CIS_LSB = TWO_N30 [constexpr]
Definition at line 85 of file GPS_CNAV.h.

10.2.6.5.138 CNAV_CRC_LSB

double CNAV_CRC_LSB = TWO_N8 [constexpr]
Definition at line 91 of file GPS_CNAV.h.

10.2.6.5.139 CNAV_CRS_LSB

double CNAV_CRS_LSB = TWO_N8 [constexpr]
Definition at line 89 of file GPS_CNAV.h.

10.2.6.5.140 CNAV_CUC_LSB

double CNAV_CUC_LSB = TWO_N30 [constexpr]
Definition at line 95 of file GPS_CNAV.h.

10.2.6.5.141 CNAV_CUS_LSB

double CNAV_CUS_LSB = TWO_N30 [constexpr]
Definition at line 93 of file GPS_CNAV.h.

10.2.6.5.142 CNAV_DELTA_A_LSB

double CNAV_DELTA_A_LSB = TWO_N9 [constexpr]
Definition at line 55 of file GPS_CNAV.h.

10.2.6.5.143 CNAV_DELTA_N0_DOT_LSB

double CNAV_DELTA_N0_DOT_LSB = TWO_N57 * GNSS_PI [constexpr]
Definition at line 63 of file GPS_CNAV.h.

10.2.6.5.144 CNAV_DELTA_N0_LSB

double CNAV_DELTA_N0_LSB = TWO_N44 * GNSS_PI [constexpr]
Definition at line 61 of file GPS_CNAV.h.

10.2.6.5.145 CNAV_DELTA_OMEGA_DOT_LSB

double CNAV_DELTA_OMEGA_DOT_LSB = TWO_N44 * GNSS_PI [constexpr]
Definition at line 81 of file GPS_CNAV.h.

10.2.6.5.146 CNAV_DELTA_TLS_LSB

```
int32_t CNAV_DELTA_TLS_LSB = 1 [constexpr]
```

Definition at line 150 of file [GPS_CNAV.h](#).

10.2.6.5.147 CNAV_DELTA_TLSF_LSB

```
int32_t CNAV_DELTA_TLSF_LSB = 1 [constexpr]
```

Definition at line 160 of file [GPS_CNAV.h](#).

10.2.6.5.148 CNAV_DN_LSB

```
int32_t CNAV_DN_LSB = 1 [constexpr]
```

Definition at line 158 of file [GPS_CNAV.h](#).

10.2.6.5.149 CNAV_E_ECCENTRICITY_LSB

```
double CNAV_E_ECCENTRICITY_LSB = TWO_N34 [constexpr]
```

Definition at line 67 of file [GPS_CNAV.h](#).

10.2.6.5.150 CNAV_I0_DOT_LSB

```
double CNAV_I0_DOT_LSB = TWO_N44 * GNSS_PI [constexpr]
```

Definition at line 83 of file [GPS_CNAV.h](#).

10.2.6.5.151 CNAV_I0_LSB

```
double CNAV_I0_LSB = TWO_N32 * GNSS_PI [constexpr]
```

Definition at line 79 of file [GPS_CNAV.h](#).

10.2.6.5.152 CNAV_ISCL1_LSB

```
double CNAV_ISCL1_LSB = TWO_N35 [constexpr]
```

Definition at line 115 of file [GPS_CNAV.h](#).

10.2.6.5.153 CNAV_ISCL2_LSB

```
double CNAV_ISCL2_LSB = TWO_N35 [constexpr]
```

Definition at line 117 of file [GPS_CNAV.h](#).

10.2.6.5.154 CNAV_ISCL5I_LSB

```
double CNAV_ISCL5I_LSB = TWO_N35 [constexpr]
```

Definition at line 119 of file [GPS_CNAV.h](#).

10.2.6.5.155 CNAV_ISCL5Q_LSB

```
double CNAV_ISCL5Q_LSB = TWO_N35 [constexpr]
```

Definition at line 121 of file [GPS_CNAV.h](#).

10.2.6.5.156 CNAV_M0_LSB

```
double CNAV_M0_LSB = TWO_N32 * GNSS_PI [constexpr]
```

Definition at line 65 of file [GPS_CNAV.h](#).

10.2.6.5.157 CNAV_OMEGA0_LSB

```
double CNAV_OMEGA0_LSB = TWO_N32 * GNSS_PI [constexpr]
```

Definition at line 77 of file [GPS_CNAV.h](#).

10.2.6.5.158 CNAV_OMEGA_DOT_REF

```
double CNAV_OMEGA_DOT_REF = -2.6e-9 [constexpr]
```

Definition at line 163 of file [GPS_CNAV.h](#).

10.2.6.5.159 CNAV_OMEGA_LSB

```
double CNAV_OMEGA_LSB = TWO_N32 * GNSS_PI [constexpr]
```

Definition at line 69 of file [GPS_CNAV.h](#).

10.2.6.5.160 CNAV_QZSS_A_REF

```
double CNAV_QZSS_A_REF = 42164200.0 [constexpr]
```

Definition at line 164 of file [GPS_CNAV.h](#).

10.2.6.5.161 CNAV_TGD_LSB

```
double CNAV_TGD_LSB = TWO_N35 [constexpr]
```

Definition at line 113 of file [GPS_CNAV.h](#).

10.2.6.5.162 CNAV_TOC_LSB

```
int32_t CNAV_TOC_LSB = 300 [constexpr]
```

Definition at line 105 of file [GPS_CNAV.h](#).

10.2.6.5.163 CNAV_TOE1_LSB

```
int32_t CNAV_TOE1_LSB = 300 [constexpr]
```

Definition at line 52 of file [GPS_CNAV.h](#).

10.2.6.5.164 CNAV_TOE2_LSB

```
int32_t CNAV_TOE2_LSB = 300 [constexpr]
```

Definition at line 75 of file [GPS_CNAV.h](#).

10.2.6.5.165 CNAV_TOP1_LSB

```
int32_t CNAV_TOP1_LSB = 300 [constexpr]
```

Definition at line 48 of file [GPS_CNAV.h](#).

10.2.6.5.166 CNAV_TOP2_LSB

```
int32_t CNAV_TOP2_LSB = 300 [constexpr]
```

Definition at line 100 of file [GPS_CNAV.h](#).

10.2.6.5.167 CNAV_TOT_LSB

```
int32_t CNAV_TOT_LSB = TWO_P4 [constexpr]
```

Definition at line 152 of file [GPS_CNAV.h](#).

10.2.6.5.168 CNAV_TOW_LSB

```
int32_t CNAV_TOW_LSB = 6 [constexpr]
```

Definition at line 41 of file [GPS_CNAV.h](#).

10.2.6.5.169 CNAV_WN_LSF_LSB

```
int32_t CNAV_WN_LSF_LSB = 1 [constexpr]
```

Definition at line 156 of file [GPS_CNAV.h](#).

10.2.6.5.170 CNAV_WN_OT_LSB

```
int32_t CNAV_WN_OT_LSB = 1 [constexpr]
```

Definition at line 154 of file [GPS_CNAV.h](#).

10.2.6.5.171 CODE_L1A

```
uint32_t CODE_L1A = 10 [constexpr]
```

obs code: E1A (GAL)
Definition at line 40 of file [gnss_obs_codes.h](#).

10.2.6.5.172 CODE_L1B

```
uint32_t CODE_L1B = 11 [constexpr]
```

obs code: E1B (GAL)
Definition at line 41 of file [gnss_obs_codes.h](#).

10.2.6.5.173 CODE_L1C

```
uint32_t CODE_L1C = 1 [constexpr]
```

obs code: L1C/A,G1C/A,E1C (GPS,GLO,GAL,QZS,SBS)
Definition at line 31 of file [gnss_obs_codes.h](#).

10.2.6.5.174 CODE_L1E

```
uint32_t CODE_L1E = 9 [constexpr]
```

(not used)
Definition at line 39 of file [gnss_obs_codes.h](#).

10.2.6.5.175 CODE_L1I

```
uint32_t CODE_L1I = 47 [constexpr]
```

obs code: B1I (BDS)
Definition at line 77 of file [gnss_obs_codes.h](#).

10.2.6.5.176 CODE_L1L

```
uint32_t CODE_L1L = 8 [constexpr]
```

obs code: L1C(P) (GPS,QZS)
Definition at line 38 of file [gnss_obs_codes.h](#).

10.2.6.5.177 CODE_L1M

```
uint32_t CODE_L1M = 5 [constexpr]
```

obs code: L1M (GPS)
Definition at line 35 of file [gnss_obs_codes.h](#).

10.2.6.5.178 CODE_L1N

```
uint32_t CODE_L1N = 6 [constexpr]
```

obs code: L1codeless (GPS)
Definition at line 36 of file [gnss_obs_codes.h](#).

10.2.6.5.179 CODE_L1P

```
uint32_t CODE_L1P = 2 [constexpr]
```

obs code: L1P,G1P (GPS,GLO)
Definition at line 32 of file [gnss_obs_codes.h](#).

10.2.6.5.180 CODE_L1Q

`uint32_t CODE_L1Q = 48 [constexpr]`
obs code: B1Q (BDS)
Definition at line 78 of file [gnss_obs_codes.h](#).

10.2.6.5.181 CODE_L1S

`uint32_t CODE_L1S = 7 [constexpr]`
obs code: L1C(D) (GPS,QZS)
Definition at line 37 of file [gnss_obs_codes.h](#).

10.2.6.5.182 CODE_L1W

`uint32_t CODE_L1W = 3 [constexpr]`
obs code: L1 Z-track (GPS)
Definition at line 33 of file [gnss_obs_codes.h](#).

10.2.6.5.183 CODE_L1X

`uint32_t CODE_L1X = 12 [constexpr]`
obs code: E1B+C,L1C(D+P) (GAL,QZS)
Definition at line 42 of file [gnss_obs_codes.h](#).

10.2.6.5.184 CODE_L1Y

`uint32_t CODE_L1Y = 4 [constexpr]`
obs code: L1Y (GPS)
Definition at line 34 of file [gnss_obs_codes.h](#).

10.2.6.5.185 CODE_L1Z

`uint32_t CODE_L1Z = 13 [constexpr]`
obs code: E1A+B+C,L1SAIF (GAL,QZS)
Definition at line 43 of file [gnss_obs_codes.h](#).

10.2.6.5.186 CODE_L2C

`uint32_t CODE_L2C = 14 [constexpr]`
obs code: L2C/A,G1C/A (GPS,GLO)
Definition at line 44 of file [gnss_obs_codes.h](#).

10.2.6.5.187 CODE_L2D

`uint32_t CODE_L2D = 15 [constexpr]`
obs code: L2 L1C/A-(P2-P1) (GPS)
Definition at line 45 of file [gnss_obs_codes.h](#).

10.2.6.5.188 CODE_L2I

`uint32_t CODE_L2I = 40 [constexpr]`
obs code: B1I (BDS)
Definition at line 70 of file [gnss_obs_codes.h](#).

10.2.6.5.189 CODE_L2L

`uint32_t CODE_L2L = 17 [constexpr]`
obs code: L2C(L) (GPS,QZS)
Definition at line 47 of file [gnss_obs_codes.h](#).

10.2.6.5.190 CODE_L2M

`uint32_t CODE_L2M = 22 [constexpr]`
obs code: L2M (GPS)
Definition at line 52 of file [gnss_obs_codes.h](#).

10.2.6.5.191 CODE_L2N

`uint32_t CODE_L2N = 23 [constexpr]`
obs code: L2codeless (GPS)
Definition at line 53 of file [gnss_obs_codes.h](#).

10.2.6.5.192 CODE_L2P

`uint32_t CODE_L2P = 19 [constexpr]`
obs code: L2P,G2P (GPS,GLO)
Definition at line 49 of file [gnss_obs_codes.h](#).

10.2.6.5.193 CODE_L2Q

`uint32_t CODE_L2Q = 41 [constexpr]`
obs code: B1Q (BDS)
Definition at line 71 of file [gnss_obs_codes.h](#).

10.2.6.5.194 CODE_L2S

`uint32_t CODE_L2S = 16 [constexpr]`
obs code: L2C(M) (GPS,QZS)
Definition at line 46 of file [gnss_obs_codes.h](#).

10.2.6.5.195 CODE_L2W

`uint32_t CODE_L2W = 20 [constexpr]`
obs code: L2 Z-track (GPS)
Definition at line 50 of file [gnss_obs_codes.h](#).

10.2.6.5.196 CODE_L2X

`uint32_t CODE_L2X = 18 [constexpr]`
obs code: L2C(M+L),B1I+Q (GPS,QZS,BDS)
Definition at line 48 of file [gnss_obs_codes.h](#).

10.2.6.5.197 CODE_L2Y

`uint32_t CODE_L2Y = 21 [constexpr]`
obs code: L2Y (GPS)
Definition at line 51 of file [gnss_obs_codes.h](#).

10.2.6.5.198 CODE_L3I

`uint32_t CODE_L3I = 44 [constexpr]`
obs code: G3I (GLO)
Definition at line 74 of file [gnss_obs_codes.h](#).

10.2.6.5.199 CODE_L3Q

`uint32_t CODE_L3Q = 45 [constexpr]`
obs code: G3Q (GLO)
Definition at line 75 of file [gnss_obs_codes.h](#).

10.2.6.5.200 CODE_L3X

`uint32_t CODE_L3X = 46 [constexpr]`
obs code: G3I+Q (GLO)
Definition at line 76 of file [gnss_obs_codes.h](#).

10.2.6.5.201 CODE_L5A

`uint32_t CODE_L5A = 49 [constexpr]`
obs code: L5A SPS (IRN)
Definition at line 79 of file [gnss_obs_codes.h](#).

10.2.6.5.202 CODE_L5B

`uint32_t CODE_L5B = 50 [constexpr]`
obs code: L5B RS(D) (IRN)
Definition at line 80 of file [gnss_obs_codes.h](#).

10.2.6.5.203 CODE_L5C

`uint32_t CODE_L5C = 51 [constexpr]`
obs code: L5C RS(P) (IRN)
Definition at line 81 of file [gnss_obs_codes.h](#).

10.2.6.5.204 CODE_L5I

`uint32_t CODE_L5I = 24 [constexpr]`
obs code: L5/E5aI (GPS,GAL,QZS,SBS)
Definition at line 54 of file [gnss_obs_codes.h](#).

10.2.6.5.205 CODE_L5Q

`uint32_t CODE_L5Q = 25 [constexpr]`
obs code: L5/E5aQ (GPS,GAL,QZS,SBS)
Definition at line 55 of file [gnss_obs_codes.h](#).

10.2.6.5.206 CODE_L5X

`uint32_t CODE_L5X = 26 [constexpr]`
obs code: L5/E5aI+Q/L5B+C (GPS,GAL,QZS,IRN,SBS)
Definition at line 56 of file [gnss_obs_codes.h](#).

10.2.6.5.207 CODE_L6A

`uint32_t CODE_L6A = 30 [constexpr]`
obs code: E6A (GAL)
Definition at line 60 of file [gnss_obs_codes.h](#).

10.2.6.5.208 CODE_L6B

`uint32_t CODE_L6B = 31 [constexpr]`
obs code: E6B (GAL)
Definition at line 61 of file [gnss_obs_codes.h](#).

10.2.6.5.209 CODE_L6C

`uint32_t CODE_L6C = 32 [constexpr]`
obs code: E6C (GAL)
Definition at line 62 of file [gnss_obs_codes.h](#).

10.2.6.5.210 CODE_L6I

uint32_t CODE_L6I = 42 [constexpr]
obs code: B3I (BDS)
Definition at line 72 of file [gnss_obs_codes.h](#).

10.2.6.5.211 CODE_L6L

uint32_t CODE_L6L = 36 [constexpr]
obs code: LEXL (QZS)
Definition at line 66 of file [gnss_obs_codes.h](#).

10.2.6.5.212 CODE_L6Q

uint32_t CODE_L6Q = 43 [constexpr]
obs code: B3Q (BDS)
Definition at line 73 of file [gnss_obs_codes.h](#).

10.2.6.5.213 CODE_L6S

uint32_t CODE_L6S = 35 [constexpr]
obs code: LEXS (QZS)
Definition at line 65 of file [gnss_obs_codes.h](#).

10.2.6.5.214 CODE_L6X

uint32_t CODE_L6X = 33 [constexpr]
obs code: E6B+C,LEXS+L,B3I+Q (GAL,QZS,BDS)
Definition at line 63 of file [gnss_obs_codes.h](#).

10.2.6.5.215 CODE_L6Z

uint32_t CODE_L6Z = 34 [constexpr]
obs code: E6A+B+C (GAL)
Definition at line 64 of file [gnss_obs_codes.h](#).

10.2.6.5.216 CODE_L7I

uint32_t CODE_L7I = 27 [constexpr]
obs code: E5bI,B2I (GAL,BDS)
Definition at line 57 of file [gnss_obs_codes.h](#).

10.2.6.5.217 CODE_L7Q

uint32_t CODE_L7Q = 28 [constexpr]
obs code: E5bQ,B2Q (GAL,BDS)
Definition at line 58 of file [gnss_obs_codes.h](#).

10.2.6.5.218 CODE_L7X

uint32_t CODE_L7X = 29 [constexpr]
obs code: E5bI+Q,B2I+Q (GAL,BDS)
Definition at line 59 of file [gnss_obs_codes.h](#).

10.2.6.5.219 CODE_L8I

uint32_t CODE_L8I = 37 [constexpr]
obs code: E5(a+b)I (GAL)
Definition at line 67 of file [gnss_obs_codes.h](#).

10.2.6.5.220 CODE_L8Q

uint32_t CODE_L8Q = 38 [constexpr]
obs code: E5(a+b)Q (GAL)
Definition at line 68 of file [gnss_obs_codes.h](#).

10.2.6.5.221 CODE_L8X

uint32_t CODE_L8X = 39 [constexpr]
obs code: E5(a+b)I+Q (GAL)
Definition at line 69 of file [gnss_obs_codes.h](#).

10.2.6.5.222 CODE_L9A

uint32_t CODE_L9A = 52 [constexpr]
obs code: SA SPS (IRN)
Definition at line 82 of file [gnss_obs_codes.h](#).

10.2.6.5.223 CODE_L9B

uint32_t CODE_L9B = 53 [constexpr]
obs code: SB RS(D) (IRN)
Definition at line 83 of file [gnss_obs_codes.h](#).

10.2.6.5.224 CODE_L9C

uint32_t CODE_L9C = 54 [constexpr]
obs code: SC RS(P) (IRN)
Definition at line 84 of file [gnss_obs_codes.h](#).

10.2.6.5.225 CODE_L9X

uint32_t CODE_L9X = 55 [constexpr]
obs code: SB+C (IRN)
Definition at line 85 of file [gnss_obs_codes.h](#).

10.2.6.5.226 CODE_NONE

uint32_t CODE_NONE = 0 [constexpr]
obs code: none or unknown
Definition at line 30 of file [gnss_obs_codes.h](#).

10.2.6.5.227 D1_A0_ALMANAC_LSB

double D1_A0_ALMANAC_LSB = TWO_N20 [constexpr]
Definition at line 67 of file [Beidou_DNAV.h](#).

10.2.6.5.228 D1_A0_LSB

double D1_A0_LSB = TWO_N33 [constexpr]
Definition at line 46 of file [Beidou_DNAV.h](#).

10.2.6.5.229 D1_A0GAL_LSB

double D1_A0GAL_LSB = 0.1e-9 [constexpr]
Definition at line 77 of file [Beidou_DNAV.h](#).

10.2.6.5.230 D1_A0GLO_LSB

double D1_A0GLO_LSB = 0.1e-9 [constexpr]
Definition at line 79 of file [Beidou_DNAV.h](#).

10.2.6.5.231 D1_A0GPS_LSB

double D1_A0GPS_LSB = 0.1e-9 [constexpr]
Definition at line 75 of file [Beidou_DNAV.h](#).

10.2.6.5.232 D1_A0UTC_LSB

double D1_A0UTC_LSB = TWO_N30 [constexpr]
Definition at line 81 of file [Beidou_DNAV.h](#).

10.2.6.5.233 D1_A1_ALMANAC_LSB

double D1_A1_ALMANAC_LSB = TWO_N38 [constexpr]
Definition at line 66 of file [Beidou_DNAV.h](#).

10.2.6.5.234 D1_A1_LSB

double D1_A1_LSB = TWO_N50 [constexpr]
Definition at line 47 of file [Beidou_DNAV.h](#).

10.2.6.5.235 D1_A1GAL_LSB

double D1_A1GAL_LSB = 0.1e-9 [constexpr]
Definition at line 78 of file [Beidou_DNAV.h](#).

10.2.6.5.236 D1_A1GLO_LSB

double D1_A1GLO_LSB = 0.1e-9 [constexpr]
Definition at line 80 of file [Beidou_DNAV.h](#).

10.2.6.5.237 D1_A1GPS_LSB

double D1_A1GPS_LSB = 0.1e-9 [constexpr]
Definition at line 76 of file [Beidou_DNAV.h](#).

10.2.6.5.238 D1_A1UTC_LSB

double D1_A1UTC_LSB = TWO_N50 [constexpr]
Definition at line 82 of file [Beidou_DNAV.h](#).

10.2.6.5.239 D1_A2_LSB

double D1_A2_LSB = TWO_N66 [constexpr]
Definition at line 45 of file [Beidou_DNAV.h](#).

10.2.6.5.240 D1_ALPHA0_LSB

double D1_ALPHA0_LSB = TWO_N30 [constexpr]
Definition at line 37 of file [Beidou_DNAV.h](#).

10.2.6.5.241 D1_ALPHA1_LSB

double D1_ALPHA1_LSB = TWO_N27 [constexpr]
Definition at line 38 of file [Beidou_DNAV.h](#).

10.2.6.5.242 D1_ALPHA2_LSB

double D1_ALPHA2_LSB = TWO_N24 [constexpr]
Definition at line 39 of file [Beidou_DNAV.h](#).

10.2.6.5.243 D1_ALPHA3_LSB

double D1_ALPHA3_LSB = TWO_N24 [constexpr]
Definition at line 40 of file [Beidou_DNAV.h](#).

10.2.6.5.244 D1_BETA0_LSB

double D1_BETA0_LSB = TWO_P11 [constexpr]
Definition at line 41 of file [Beidou_DNAV.h](#).

10.2.6.5.245 D1_BETA1_LSB

double D1_BETA1_LSB = TWO_P14 [constexpr]
Definition at line 42 of file [Beidou_DNAV.h](#).

10.2.6.5.246 D1_BETA2_LSB

double D1_BETA2_LSB = TWO_P16 [constexpr]
Definition at line 43 of file [Beidou_DNAV.h](#).

10.2.6.5.247 D1_BETA3_LSB

double D1_BETA3_LSB = TWO_P16 [constexpr]
Definition at line 44 of file [Beidou_DNAV.h](#).

10.2.6.5.248 D1_CIC_LSB

double D1_CIC_LSB = TWO_N31 [constexpr]
Definition at line 58 of file [Beidou_DNAV.h](#).

10.2.6.5.249 D1_CIS_LSB

double D1_CIS_LSB = TWO_N31 [constexpr]
Definition at line 60 of file [Beidou_DNAV.h](#).

10.2.6.5.250 D1_CRC_LSB

double D1_CRC_LSB = TWO_N6 [constexpr]
Definition at line 53 of file [Beidou_DNAV.h](#).

10.2.6.5.251 D1_CRS_LSB

double D1_CRS_LSB = TWO_N6 [constexpr]
Definition at line 54 of file [Beidou_DNAV.h](#).

10.2.6.5.252 D1_CUC_LSB

double D1_CUC_LSB = TWO_N31 [constexpr]
Definition at line 49 of file [Beidou_DNAV.h](#).

10.2.6.5.253 D1_CUS_LSB

double D1_CUS_LSB = TWO_N31 [constexpr]
Definition at line 52 of file [Beidou_DNAV.h](#).

10.2.6.5.254 D1_DELTA_I_LSB

double D1_DELTA_I_LSB = PI_TWO_N19 [constexpr]
Definition at line 70 of file [Beidou_DNAV.h](#).

10.2.6.5.255 D1_DELTA_N_LSB

double D1_DELTA_N_LSB = [PI_TWO_N43](#) [constexpr]
Definition at line [48](#) of file [Beidou_DNAV.h](#).

10.2.6.5.256 D1_E_ALMANAC_LSB

double D1_E_ALMANAC_LSB = [TWO_N21](#) [constexpr]
Definition at line [69](#) of file [Beidou_DNAV.h](#).

10.2.6.5.257 D1_E_LSB

double D1_E_LSB = [TWO_N33](#) [constexpr]
Definition at line [51](#) of file [Beidou_DNAV.h](#).

10.2.6.5.258 D1_I0_LSB

double D1_I0_LSB = [PI_TWO_N31](#) [constexpr]
Definition at line [57](#) of file [Beidou_DNAV.h](#).

10.2.6.5.259 D1_IDOT_LSB

double D1_IDOT_LSB = [PI_TWO_N43](#) [constexpr]
Definition at line [61](#) of file [Beidou_DNAV.h](#).

10.2.6.5.260 D1_M0_ALMANAC_LSB

double D1_M0_ALMANAC_LSB = [PI_TWO_N23](#) [constexpr]
Definition at line [74](#) of file [Beidou_DNAV.h](#).

10.2.6.5.261 D1_M0_LSB

double D1_M0_LSB = [PI_TWO_N31](#) [constexpr]
Definition at line [50](#) of file [Beidou_DNAV.h](#).

10.2.6.5.262 D1_OMEGA0_ALMANAC_LSB

double D1_OMEGA0_ALMANAC_LSB = [PI_TWO_N23](#) [constexpr]
Definition at line [68](#) of file [Beidou_DNAV.h](#).

10.2.6.5.263 D1_OMEGA0_LSB

double D1_OMEGA0_LSB = [PI_TWO_N31](#) [constexpr]
Definition at line [62](#) of file [Beidou_DNAV.h](#).

10.2.6.5.264 D1_OMEGA_ALMANAC_LSB

double D1_OMEGA_ALMANAC_LSB = [PI_TWO_N23](#) [constexpr]
Definition at line [73](#) of file [Beidou_DNAV.h](#).

10.2.6.5.265 D1_OMEGA_DOT_ALMANAC_LSB

double D1_OMEGA_DOT_ALMANAC_LSB = [PI_TWO_N38](#) [constexpr]
Definition at line [72](#) of file [Beidou_DNAV.h](#).

10.2.6.5.266 D1_OMEGA_DOT_LSB

double D1_OMEGA_DOT_LSB = [PI_TWO_N43](#) [constexpr]
Definition at line [59](#) of file [Beidou_DNAV.h](#).

10.2.6.5.267 D1_OMEGA_LSB

```
double D1_OMEGA_LSB = PI_TWO_N31 [constexpr]
```

Definition at line 63 of file [Beidou_DNAV.h](#).

10.2.6.5.268 D1_SQRT_A_ALMANAC_LSB

```
double D1_SQRT_A_ALMANAC_LSB = TWO_N11 [constexpr]
```

Definition at line 65 of file [Beidou_DNAV.h](#).

10.2.6.5.269 D1_SQRT_A_LSB

```
double D1_SQRT_A_LSB = TWO_N19 [constexpr]
```

Definition at line 55 of file [Beidou_DNAV.h](#).

10.2.6.5.270 D1_TGD1_LSB

```
double D1_TGD1_LSB = 0.1e-9 [constexpr]
```

Definition at line 35 of file [Beidou_DNAV.h](#).

10.2.6.5.271 D1_TGD2_LSB

```
double D1_TGD2_LSB = 0.1e-9 [constexpr]
```

Definition at line 36 of file [Beidou_DNAV.h](#).

10.2.6.5.272 D1_TOA_LSB

```
double D1_TOA_LSB = TWO_P12 [constexpr]
```

Definition at line 71 of file [Beidou_DNAV.h](#).

10.2.6.5.273 D1_TOC_LSB

```
double D1_TOC_LSB = TWO_P3 [constexpr]
```

Definition at line 34 of file [Beidou_DNAV.h](#).

10.2.6.5.274 D1_TOE_LSB

```
double D1_TOE_LSB = TWO_P3 [constexpr]
```

Definition at line 56 of file [Beidou_DNAV.h](#).

10.2.6.5.275 D2R

```
double D2R = GNSS_PI / 180.0 [constexpr]
```

deg to rad

Definition at line 123 of file [MATH_CONSTANTS.h](#).

10.2.6.5.276 DELTA_A_7_LSB

```
double DELTA_A_7_LSB = TWO_N9 [constexpr]
```

Definition at line 165 of file [Galileo_INAV.h](#).

10.2.6.5.277 DELTA_A_8_LSB

```
double DELTA_A_8_LSB = TWO_N9 [constexpr]
```

Definition at line 190 of file [Galileo_INAV.h](#).

10.2.6.5.278 DELTA_A_9_LSB

```
double DELTA_A_9_LSB = TWO_N9 [constexpr]
```

Definition at line 218 of file [Galileo_INAV.h](#).

10.2.6.5.279 DELTA_I_7_LSB

double DELTA_I_7_LSB = TWO_N14 [constexpr]
Definition at line 171 of file [Galileo_INAV.h](#).

10.2.6.5.280 DELTA_I_8_LSB

double DELTA_I_8_LSB = TWO_N14 [constexpr]
Definition at line 196 of file [Galileo_INAV.h](#).

10.2.6.5.281 DELTA_I_9_LSB

double DELTA_I_9_LSB = TWO_N14 [constexpr]
Definition at line 224 of file [Galileo_INAV.h](#).

10.2.6.5.282 DELTA_N_3_LSB

double DELTA_N_3_LSB = PI_TWO_N43 [constexpr]
Definition at line 84 of file [Galileo_INAV.h](#).

10.2.6.5.283 DELTA_N_LSB

double DELTA_N_LSB = PI_TWO_N43 [constexpr]
Definition at line 109 of file [GPS_L1_CA.h](#).

10.2.6.5.284 DELTAT_LS_LSB

double DELTAT_LS_LSB = 1 [constexpr]
Definition at line 177 of file [GPS_L1_CA.h](#).

10.2.6.5.285 DELTAT_LSF_LSB

double DELTAT_LSF_LSB = 1 [constexpr]
Definition at line 183 of file [GPS_L1_CA.h](#).

10.2.6.5.286 DFRQ1_GLO

double DFRQ1_GLO = 0.56250e6 [constexpr]
GLONASS G1 bias frequency (Hz/n)
Definition at line 39 of file [gnss_frequencies.h](#).

10.2.6.5.287 DFRQ2_GLO

double DFRQ2_GLO = 0.43750e6 [constexpr]
GLONASS G2 bias frequency (Hz/n)
Definition at line 41 of file [gnss_frequencies.h](#).

10.2.6.5.288 DN_LSB

double DN_LSB = 1 [constexpr]
Definition at line 181 of file [GPS_L1_CA.h](#).

10.2.6.5.289 E_1_LSB

double E_1_LSB = TWO_N33 [constexpr]
Definition at line 61 of file [Galileo_INAV.h](#).

10.2.6.5.290 E_7_LSB

double E_7_LSB = TWO_N16 [constexpr]
Definition at line 167 of file [Galileo_INAV.h](#).

10.2.6.5.291 E_8_LSB

double E_8_LSB = TWO_N16 [constexpr]
Definition at line 192 of file [Galileo_INAV.h](#).

10.2.6.5.292 E_9_LSB

double E_9_LSB = TWO_N16 [constexpr]
Definition at line 220 of file [Galileo_INAV.h](#).

10.2.6.5.293 ECCENTRICITY_LSB

double ECCENTRICITY_LSB = TWO_N33 [constexpr]
Definition at line 115 of file [GPS_L1_CA.h](#).

10.2.6.5.294 FIRST_RS_BIT

int32_t FIRST_RS_BIT = 7 [constexpr]
Definition at line 274 of file [Galileo_INAV.h](#).

10.2.6.5.295 FIRST_RS_BIT_AFTER_IODNAV

int32_t FIRST_RS_BIT_AFTER_IODNAV = 17 [constexpr]
Definition at line 275 of file [Galileo_INAV.h](#).

10.2.6.5.296 FNAV_A0_4_LSB

double FNAV_A0_4_LSB = TWO_N30 [constexpr]
Definition at line 109 of file [Galileo_FNAV.h](#).

10.2.6.5.297 FNAV_A0G_4_LSB

double FNAV_A0G_4_LSB = TWO_N35 [constexpr]
Definition at line 122 of file [Galileo_FNAV.h](#).

10.2.6.5.298 FNAV_A12_2_LSB

double FNAV_A12_2_LSB = TWO_N19 [constexpr]
Definition at line 73 of file [Galileo_FNAV.h](#).

10.2.6.5.299 FNAV_A1_4_LSB

double FNAV_A1_4_LSB = TWO_N50 [constexpr]
Definition at line 111 of file [Galileo_FNAV.h](#).

10.2.6.5.300 FNAV_A1G_4_LSB

double FNAV_A1G_4_LSB = TWO_N51 [constexpr]
Definition at line 124 of file [Galileo_FNAV.h](#).

10.2.6.5.301 FNAV_AF0_1_LSB

double FNAV_AF0_1_LSB = TWO_N34 [constexpr]
Definition at line 40 of file [Galileo_FNAV.h](#).

10.2.6.5.302 FNAV_AF0_5_LSB

double FNAV_AF0_5_LSB = TWO_N19 [constexpr]
Definition at line 149 of file [Galileo_FNAV.h](#).

10.2.6.5.303 FNAV_AF1_1_LSB

double FNAV_AF1_1_LSB = TWO_N46 [constexpr]
Definition at line 42 of file [Galileo_FNAV.h](#).

10.2.6.5.304 FNAV_AF1_5_LSB

double FNAV_AF1_5_LSB = TWO_N38 [constexpr]
Definition at line 151 of file [Galileo_FNAV.h](#).

10.2.6.5.305 FNAV_AF2_1_LSB

double FNAV_AF2_1_LSB = TWO_N59 [constexpr]
Definition at line 44 of file [Galileo_FNAV.h](#).

10.2.6.5.306 FNAV_AI0_1_LSB

double FNAV_AI0_1_LSB = TWO_N2 [constexpr]
Definition at line 47 of file [Galileo_FNAV.h](#).

10.2.6.5.307 FNAV_AI1_1_LSB

double FNAV_AI1_1_LSB = TWO_N8 [constexpr]
Definition at line 49 of file [Galileo_FNAV.h](#).

10.2.6.5.308 FNAV_AI2_1_LSB

double FNAV_AI2_1_LSB = TWO_N15 [constexpr]
Definition at line 51 of file [Galileo_FNAV.h](#).

10.2.6.5.309 FNAV_BGD_1_LSB

double FNAV_BGD_1_LSB = TWO_N32 [constexpr]
Definition at line 58 of file [Galileo_FNAV.h](#).

10.2.6.5.310 FNAV_CIC_4_LSB

double FNAV_CIC_4_LSB = TWO_N29 [constexpr]
Definition at line 105 of file [Galileo_FNAV.h](#).

10.2.6.5.311 FNAV_CIS_4_LSB

double FNAV_CIS_4_LSB = TWO_N29 [constexpr]
Definition at line 107 of file [Galileo_FNAV.h](#).

10.2.6.5.312 FNAV_CRC_3_LSB

double FNAV_CRC_3_LSB = TWO_N5 [constexpr]
Definition at line 94 of file [Galileo_FNAV.h](#).

10.2.6.5.313 FNAV_CRS_3_LSB

double FNAV_CRS_3_LSB = TWO_N5 [constexpr]
Definition at line 96 of file [Galileo_FNAV.h](#).

10.2.6.5.314 FNAV_CUC_3_LSB

double FNAV_CUC_3_LSB = TWO_N29 [constexpr]
Definition at line 90 of file [Galileo_FNAV.h](#).

10.2.6.5.315 FNAV_CUS_3_LSB

```
double FNAV_CUS_3_LSB = TWO_N29 [constexpr]
```

Definition at line 92 of file [Galileo_FNAV.h](#).

10.2.6.5.316 FNAV_DELTA12_5_LSB

```
double FNAV_DELTA12_5_LSB = TWO_N9 [constexpr]
```

Definition at line 135 of file [Galileo_FNAV.h](#).

10.2.6.5.317 FNAV_DELTAI_5_LSB

```
double FNAV_DELTAI_5_LSB = TWO_N14 [constexpr]
```

Definition at line 141 of file [Galileo_FNAV.h](#).

10.2.6.5.318 FNAV_DELTAN_3_LSB

```
double FNAV_DELTAN_3_LSB = PI_TWO_N43 [constexpr]
```

Definition at line 88 of file [Galileo_FNAV.h](#).

10.2.6.5.319 FNAV_E_2_LSB

```
double FNAV_E_2_LSB = TWO_N33 [constexpr]
```

Definition at line 71 of file [Galileo_FNAV.h](#).

10.2.6.5.320 FNAV_E_5_LSB

```
double FNAV_E_5_LSB = TWO_N16 [constexpr]
```

Definition at line 137 of file [Galileo_FNAV.h](#).

10.2.6.5.321 FNAV_I0_3_LSB

```
double FNAV_I0_3_LSB = PI_TWO_N31 [constexpr]
```

Definition at line 84 of file [Galileo_FNAV.h](#).

10.2.6.5.322 FNAV_IDOT_2_LSB

```
double FNAV_IDOT_2_LSB = PI_TWO_N43 [constexpr]
```

Definition at line 77 of file [Galileo_FNAV.h](#).

10.2.6.5.323 FNAV_M0_2_LSB

```
double FNAV_M0_2_LSB = PI_TWO_N31 [constexpr]
```

Definition at line 67 of file [Galileo_FNAV.h](#).

10.2.6.5.324 FNAV_M0_5_LSB

```
double FNAV_M0_5_LSB = TWO_N15 [constexpr]
```

Definition at line 147 of file [Galileo_FNAV.h](#).

10.2.6.5.325 FNAV_OMEGA0_2_LSB

```
double FNAV_OMEGA0_2_LSB = PI_TWO_N31 [constexpr]
```

Definition at line 75 of file [Galileo_FNAV.h](#).

10.2.6.5.326 FNAV_OMEGA0_5_LSB

```
double FNAV_OMEGA0_5_LSB = TWO_N15 [constexpr]
```

Definition at line 143 of file [Galileo_FNAV.h](#).

10.2.6.5.327 FNAV_OMEGADOT_2_LSB

double FNAV_OMEGADOT_2_LSB = [PI_TWO_N43](#) [constexpr]
Definition at line [69](#) of file [Galileo_FNAV.h](#).

10.2.6.5.328 FNAV_OMEGADOT_5_LSB

double FNAV_OMEGADOT_5_LSB = [TWO_N33](#) [constexpr]
Definition at line [145](#) of file [Galileo_FNAV.h](#).

10.2.6.5.329 FNAV_T0A_5_LSB

int32_t FNAV_T0A_5_LSB = [600](#) [constexpr]
Definition at line [132](#) of file [Galileo_FNAV.h](#).

10.2.6.5.330 FNAV_T0C_1_LSB

int32_t FNAV_T0C_1_LSB = [60](#) [constexpr]
Definition at line [38](#) of file [Galileo_FNAV.h](#).

10.2.6.5.331 FNAV_T0E_3_LSB

int32_t FNAV_T0E_3_LSB = [60](#) [constexpr]
Definition at line [98](#) of file [Galileo_FNAV.h](#).

10.2.6.5.332 FNAV_T0G_4_LSB

int32_t FNAV_T0G_4_LSB = [3600](#) [constexpr]
Definition at line [120](#) of file [Galileo_FNAV.h](#).

10.2.6.5.333 FNAV_T0T_4_LSB

int32_t FNAV_T0T_4_LSB = [3600](#) [constexpr]
Definition at line [114](#) of file [Galileo_FNAV.h](#).

10.2.6.5.334 FNAV_W_3_LSB

double FNAV_W_3_LSB = [PI_TWO_N31](#) [constexpr]
Definition at line [86](#) of file [Galileo_FNAV.h](#).

10.2.6.5.335 FNAV_W_5_LSB

double FNAV_W_5_LSB = [TWO_N15](#) [constexpr]
Definition at line [139](#) of file [Galileo_FNAV.h](#).

10.2.6.5.336 FREQ1

double FREQ1 = [1.57542e9](#) [constexpr]
L1/E1 frequency (Hz)
Definition at line [31](#) of file [gnss_frequencies.h](#).

10.2.6.5.337 FREQ1_BDS

double FREQ1_BDS = [1.561098e9](#) [constexpr]
BeiDou B1 frequency (Hz)
Definition at line [43](#) of file [gnss_frequencies.h](#).

10.2.6.5.338 FREQ1_GLO

`double FREQ1_GLO = 1.60200e9 [constexpr]`
GLONASS G1 base frequency (Hz)
Definition at line 38 of file [gnss_frequencies.h](#).

10.2.6.5.339 FREQ2

`double FREQ2 = 1.22760e9 [constexpr]`
L2 frequency (Hz)
Definition at line 32 of file [gnss_frequencies.h](#).

10.2.6.5.340 FREQ2_BDS

`double FREQ2_BDS = 1.20714e9 [constexpr]`
BeiDou B2 frequency (Hz)
Definition at line 44 of file [gnss_frequencies.h](#).

10.2.6.5.341 FREQ2_GLO

`double FREQ2_GLO = 1.24600e9 [constexpr]`
GLONASS G2 base frequency (Hz)
Definition at line 40 of file [gnss_frequencies.h](#).

10.2.6.5.342 FREQ3_BDS

`double FREQ3_BDS = 1.26852e9 [constexpr]`
BeiDou B3 frequency (Hz)
Definition at line 45 of file [gnss_frequencies.h](#).

10.2.6.5.343 FREQ3_GLO

`double FREQ3_GLO = 1.202025e9 [constexpr]`
GLONASS G3 frequency (Hz)
Definition at line 42 of file [gnss_frequencies.h](#).

10.2.6.5.344 FREQ5

`double FREQ5 = 1.17645e9 [constexpr]`
L5/E5a frequency (Hz)
Definition at line 33 of file [gnss_frequencies.h](#).

10.2.6.5.345 FREQ6

`double FREQ6 = 1.27875e9 [constexpr]`
E6/LEX frequency (Hz)
Definition at line 34 of file [gnss_frequencies.h](#).

10.2.6.5.346 FREQ7

`double FREQ7 = 1.20714e9 [constexpr]`
E5b frequency (Hz)
Definition at line 35 of file [gnss_frequencies.h](#).

10.2.6.5.347 FREQ8

`double FREQ8 = 1.191795e9 [constexpr]`
E5a+b frequency (Hz)
Definition at line 36 of file [gnss_frequencies.h](#).

10.2.6.5.348 FREQ9

double FREQ9 = 2.492028e9 [constexpr]
S frequency (Hz)
Definition at line 37 of file [gnss_frequencies.h](#).

10.2.6.5.349 GALILEO_CNAV_BITS_FOR_CRC

int32_t GALILEO_CNAV_BITS_FOR_CRC = GALILEO_CNAV_HAS_PAGE_DATA_BITS + GALILEO_CNAV_PAGE_←
RESERVED_BITS [constexpr]
Definition at line 78 of file [Galileo_CNAV.h](#).

10.2.6.5.350 GALILEO_CNAV_BYTES_FOR_CRC

int32_t GALILEO_CNAV_BYTES_FOR_CRC = 58 [constexpr]
Definition at line 68 of file [Galileo_CNAV.h](#).

10.2.6.5.351 GALILEO_CNAV_CRC_LENGTH

int32_t GALILEO_CNAV_CRC_LENGTH = 24 [constexpr]
Definition at line 69 of file [Galileo_CNAV.h](#).

10.2.6.5.352 GALILEO_CNAV_HAS_PAGE_DATA_BITS

int32_t GALILEO_CNAV_HAS_PAGE_DATA_BITS = 448 [constexpr]
Definition at line 66 of file [Galileo_CNAV.h](#).

10.2.6.5.353 GALILEO_CNAV_INFORMATION_VECTOR_LENGTH

int32_t GALILEO_CNAV_INFORMATION_VECTOR_LENGTH = 32 [constexpr]
Definition at line 76 of file [Galileo_CNAV.h](#).

10.2.6.5.354 GALILEO_CNAV_INTERLEAVER_COLS

int32_t GALILEO_CNAV_INTERLEAVER_COLS = 123 [constexpr]
Definition at line 64 of file [Galileo_CNAV.h](#).

10.2.6.5.355 GALILEO_CNAV_INTERLEAVER_ROWS

int32_t GALILEO_CNAV_INTERLEAVER_ROWS = 8 [constexpr]
Definition at line 63 of file [Galileo_CNAV.h](#).

10.2.6.5.356 GALILEO_CNAV_MAX_NUMBER_SYMBOLS_ENCODED_BLOCK

int32_t GALILEO_CNAV_MAX_NUMBER_SYMBOLS_ENCODED_BLOCK = 255 [constexpr]
Definition at line 73 of file [Galileo_CNAV.h](#).

10.2.6.5.357 GALILEO_CNAV_MESSAGE_BITS_PER_PAGE

int32_t GALILEO_CNAV_MESSAGE_BITS_PER_PAGE = 424 [constexpr]
Definition at line 70 of file [Galileo_CNAV.h](#).

10.2.6.5.358 GALILEO_CNAV_MT1_HEADER_BITS

int32_t GALILEO_CNAV_MT1_HEADER_BITS = 32 [constexpr]
Definition at line 74 of file [Galileo_CNAV.h](#).

10.2.6.5.359 GALILEO_CNAV_OCTETS_IN_SUBPAGE

int32_t GALILEO_CNAV_OCTETS_IN_SUBPAGE = 53 [constexpr]
Definition at line 75 of file [Galileo_CNAV.h](#).

10.2.6.5.360 GALILEO_CNAV_PAGE_HEADER_BITS

```
int32_t GALILEO_CNAV_PAGE_HEADER_BITS = 24 [constexpr]
```

Definition at line 71 of file [Galileo_CNAV.h](#).

10.2.6.5.361 GALILEO_CNAV_PAGE_MS

```
int32_t GALILEO_CNAV_PAGE_MS = 1 [constexpr]
```

Definition at line 62 of file [Galileo_CNAV.h](#).

10.2.6.5.362 GALILEO_CNAV_PAGE_RESERVED_BITS

```
int32_t GALILEO_CNAV_PAGE_RESERVED_BITS = 14 [constexpr]
```

Definition at line 67 of file [Galileo_CNAV.h](#).

10.2.6.5.363 GALILEO_CNAV_PREAMBLE

```
char GALILEO_CNAV_PREAMBLE[17] = "1011011101110000" [constexpr]
```

Definition at line 99 of file [Galileo_CNAV.h](#).

10.2.6.5.364 GALILEO_CNAV_PREAMBLE_LENGTH_BITS

```
int32_t GALILEO_CNAV_PREAMBLE_LENGTH_BITS = 16 [constexpr]
```

Definition at line 72 of file [Galileo_CNAV.h](#).

10.2.6.5.365 GALILEO_CNAV_PREAMBLE_PERIOD_SYMBOLS

```
int32_t GALILEO_CNAV_PREAMBLE_PERIOD_SYMBOLS = 1000 [constexpr]
```

Definition at line 61 of file [Galileo_CNAV.h](#).

10.2.6.5.366 GALILEO_CNAV_SYMBOLS_PER_PAGE

```
int32_t GALILEO_CNAV_SYMBOLS_PER_PAGE = 1000 [constexpr]
```

Definition at line 60 of file [Galileo_CNAV.h](#).

10.2.6.5.367 GALILEO_CNAV_TELEMETRY_RATE_BITS_SECOND

```
int32_t GALILEO_CNAV_TELEMETRY_RATE_BITS_SECOND = 1000 [constexpr]
```

Definition at line 65 of file [Galileo_CNAV.h](#).

10.2.6.5.368 GALILEO_DATA_FRAME_BITS

```
int32_t GALILEO_DATA_FRAME_BITS = 196 [constexpr]
```

Definition at line 47 of file [Galileo_INAV.h](#).

10.2.6.5.369 GALILEO_DATA_FRAME_BYTES

```
int32_t GALILEO_DATA_FRAME_BYTES = 25 [constexpr]
```

Definition at line 48 of file [Galileo_INAV.h](#).

10.2.6.5.370 GALILEO_DATA_JK_BITS

```
int32_t GALILEO_DATA_JK_BITS = 128 [constexpr]
```

Definition at line 46 of file [Galileo_INAV.h](#).

10.2.6.5.371 GALILEO_E1_B_CODE_LENGTH_CHIPS

```
double GALILEO_E1_B_CODE_LENGTH_CHIPS = 4092.0 [constexpr]
```

Galileo E1-B code length [chips].
Definition at line 39 of file [Galileo_E1.h](#).

10.2.6.5.372 GALILEO_E1_B_PRIMARY_CODE

```
char GALILEO_E1_B_PRIMARY_CODE[GALILEO_E1_NUMBER_OF_CODES][1024] [constexpr]
```

Definition at line 56 of file [Galileo_E1.h](#).

10.2.6.5.373 GALILEO_E1_B_PRIMARY_CODE_STR_LENGTH

```
size_t GALILEO_E1_B_PRIMARY_CODE_STR_LENGTH = 1023 [constexpr]
```

Definition at line 55 of file [Galileo_E1.h](#).

10.2.6.5.374 GALILEO_E1_B_SAMPLES_PER_SYMBOL

```
int32_t GALILEO_E1_B_SAMPLES_PER_SYMBOL = 1 [constexpr]
```

$(\text{Galileo_E1_CODE_CHIP_RATE_HZ} / \text{Galileo_E1_B_CODE_LENGTH_CHIPS}) / \text{Galileo_E1_B_SYMBOL_RATE_BPS}$

Definition at line 42 of file [Galileo_E1.h](#).

10.2.6.5.375 GALILEO_E1_B_SYMBOL_RATE_BPS

```
double GALILEO_E1_B_SYMBOL_RATE_BPS = 250.0 [constexpr]
```

Galileo E1-B symbol rate [bits/second].

Definition at line 40 of file [Galileo_E1.h](#).

10.2.6.5.376 GALILEO_E1_C_PRIMARY_CODE

```
char GALILEO_E1_C_PRIMARY_CODE[GALILEO_E1_NUMBER_OF_CODES][1024] [constexpr]
```

Definition at line 760 of file [Galileo_E1.h](#).

10.2.6.5.377 GALILEO_E1_C_PRIMARY_CODE_STR_LENGTH

```
size_t GALILEO_E1_C_PRIMARY_CODE_STR_LENGTH = 1023 [constexpr]
```

Definition at line 759 of file [Galileo_E1.h](#).

10.2.6.5.378 GALILEO_E1_C_SECONDARY_CODE

```
char GALILEO_E1_C_SECONDARY_CODE[26] = "0011100000001010110110010" [constexpr]
```

Definition at line 52 of file [Galileo_E1.h](#).

10.2.6.5.379 GALILEO_E1_C_SECONDARY_CODE_LENGTH

```
int32_t GALILEO_E1_C_SECONDARY_CODE_LENGTH = 25 [constexpr]
```

Galileo E1-C secondary code length [chips].

Definition at line 43 of file [Galileo_E1.h](#).

10.2.6.5.380 GALILEO_E1_CODE_CHIP_RATE_CPS

```
double GALILEO_E1_CODE_CHIP_RATE_CPS = 1.023e6 [constexpr]
```

Galileo E1 code rate [chips/s].

Definition at line 35 of file [Galileo_E1.h](#).

10.2.6.5.381 GALILEO_E1_CODE_PERIOD_MS

```
uint32_t GALILEO_E1_CODE_PERIOD_MS = 4 [constexpr]
```

Galileo E1 code period [ms].

Definition at line 41 of file [Galileo_E1.h](#).

10.2.6.5.382 GALILEO_E1_CODE_PERIOD_S

```
double GALILEO_E1_CODE_PERIOD_S = 0.004 [constexpr]
```

Galileo E1 code period [s].

Definition at line 36 of file [Galileo_E1.h](#).

10.2.6.5.383 GALILEO_E1_FREQ_HZ

```
double GALILEO_E1_FREQ_HZ = FREQ1 [constexpr]
```

Galileo E1 carrier frequency [Hz].

Definition at line [34](#) of file [Galileo_E1.h](#).

10.2.6.5.384 GALILEO_E1_HISTORY_DEEP

```
int32_t GALILEO_E1_HISTORY_DEEP = 100 [constexpr]
```

Observable history length for interpolation.

Definition at line [50](#) of file [Galileo_E1.h](#).

10.2.6.5.385 GALILEO_E1_NUMBER_OF_CODES

```
int32_t GALILEO_E1_NUMBER_OF_CODES = 50 [constexpr]
```

Definition at line [44](#) of file [Galileo_E1.h](#).

10.2.6.5.386 GALILEO_E1_OPT_ACQ_FS_SPS

```
uint32_t GALILEO_E1_OPT_ACQ_FS_SPS = 2000000 [constexpr]
```

Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.

Definition at line [48](#) of file [Galileo_E1.h](#).

10.2.6.5.387 GALILEO_E1_SUB_CARRIER_A_RATE_HZ

```
double GALILEO_E1_SUB_CARRIER_A_RATE_HZ = 1.023e6 [constexpr]
```

Galileo E1 sub-carrier 'a' rate [Hz].

Definition at line [37](#) of file [Galileo_E1.h](#).

10.2.6.5.388 GALILEO_E1_SUB_CARRIER_B_RATE_HZ

```
double GALILEO_E1_SUB_CARRIER_B_RATE_HZ = 6.138e6 [constexpr]
```

Galileo E1 sub-carrier 'b' rate [Hz].

Definition at line [38](#) of file [Galileo_E1.h](#).

10.2.6.5.389 GALILEO_E5A_CODE_CHIP_RATE_CPS

```
double GALILEO_E5A_CODE_CHIP_RATE_CPS = 1.023e7 [constexpr]
```

Galileo E5a code rate [chips/s].

Definition at line [33](#) of file [Galileo_E5a.h](#).

10.2.6.5.390 GALILEO_E5A_CODE_LENGTH_CHIPS

```
int32_t GALILEO_E5A_CODE_LENGTH_CHIPS = 10230 [constexpr]
```

Galileo E5a primary code length [chips].

Definition at line [37](#) of file [Galileo_E5a.h](#).

10.2.6.5.391 GALILEO_E5A_CODE_PERIOD_MS

```
int32_t GALILEO_E5A_CODE_PERIOD_MS = 1 [constexpr]
```

Galileo E5a primary code period [ms].

Definition at line [40](#) of file [Galileo_E5a.h](#).

10.2.6.5.392 GALILEO_E5A_CODE_PERIOD_S

```
double GALILEO_E5A_CODE_PERIOD_S = 0.001 [constexpr]
```

Galileo E5a primary code period [s].

Definition at line [36](#) of file [Galileo_E5a.h](#).

10.2.6.5.393 GALILEO_E5A_CRC_ERROR_LIMIT

```
int32_t GALILEO_E5A_CRC_ERROR_LIMIT = 6 [constexpr]
```

Definition at line 47 of file [Galileo_E5a.h](#).

10.2.6.5.394 GALILEO_E5A_FREQ_HZ

```
double GALILEO_E5A_FREQ_HZ = FREQ5 [constexpr]
```

Galileo E5a carrier frequency [Hz].

Definition at line 32 of file [Galileo_E5a.h](#).

10.2.6.5.395 GALILEO_E5A_HISTORY_DEEP

```
int32_t GALILEO_E5A_HISTORY_DEEP = 20 [constexpr]
```

Definition at line 46 of file [Galileo_E5a.h](#).

10.2.6.5.396 GALILEO_E5A_I_PRIMARY_CODE

```
char GALILEO_E5A_I_PRIMARY_CODE[GALILEO_E5A_NUMBER_OF_CODES][2559] [constexpr]
```

Definition at line 72 of file [Galileo_E5a.h](#).

10.2.6.5.397 GALILEO_E5A_I_PRIMARY_CODE_STR_LENGTH

```
size_t GALILEO_E5A_I_PRIMARY_CODE_STR_LENGTH = 2558 [constexpr]
```

Definition at line 71 of file [Galileo_E5a.h](#).

10.2.6.5.398 GALILEO_E5A_I_SECONDARY_CODE

```
char GALILEO_E5A_I_SECONDARY_CODE[] = "10000100001011101001" [constexpr]
```

Definition at line 3581 of file [Galileo_E5a.h](#).

10.2.6.5.399 GALILEO_E5A_I_SECONDARY_CODE_LENGTH

```
int32_t GALILEO_E5A_I_SECONDARY_CODE_LENGTH = 20 [constexpr]
```

Galileo E5a-I secondary code length [chips].

Definition at line 38 of file [Galileo_E5a.h](#).

10.2.6.5.400 GALILEO_E5A_I_TIERED_CODE_PERIOD_S

```
double GALILEO_E5A_I_TIERED_CODE_PERIOD_S = 0.020 [constexpr]
```

Galileo E5a-I tiered code period [s].

Definition at line 34 of file [Galileo_E5a.h](#).

10.2.6.5.401 GALILEO_E5A_NUMBER_OF_CODES

```
int32_t GALILEO_E5A_NUMBER_OF_CODES = 50 [constexpr]
```

Definition at line 42 of file [Galileo_E5a.h](#).

10.2.6.5.402 GALILEO_E5A_OPT_ACQ_FS_SPS

```
uint32_t GALILEO_E5A_OPT_ACQ_FS_SPS = 10000000 [constexpr]
```

Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.

Definition at line 50 of file [Galileo_E5a.h](#).

10.2.6.5.403 GALILEO_E5A_Q_PRIMARY_CODE

```
char GALILEO_E5A_Q_PRIMARY_CODE[GALILEO_E5A_NUMBER_OF_CODES][2559] [constexpr]
```

Definition at line 1827 of file [Galileo_E5a.h](#).

10.2.6.5.404 GALILEO_E5A_Q_PRIMARY_CODE_STR_LENGTH

```
size_t GALILEO_E5A_Q_PRIMARY_CODE_STR_LENGTH = 2558 [constexpr]
```

Definition at line 1826 of file [Galileo_E5a.h](#).

10.2.6.5.405 GALILEO_E5A_Q_SECONDARY_CODE

```
char GALILEO_E5A_Q_SECONDARY_CODE[GALILEO_E5A_NUMBER_OF_CODES][101] [constexpr]
```

Definition at line 3585 of file [Galileo_E5a.h](#).

10.2.6.5.406 GALILEO_E5A_Q_SECONDARY_CODE_LENGTH

```
int32_t GALILEO_E5A_Q_SECONDARY_CODE_LENGTH = 100 [constexpr]
```

Galileo E5a-Q secondary code length [chips].

Definition at line 39 of file [Galileo_E5a.h](#).

10.2.6.5.407 GALILEO_E5A_Q_SECONDARY_CODE_STR_LENGTH

```
size_t GALILEO_E5A_Q_SECONDARY_CODE_STR_LENGTH = 100 [constexpr]
```

Definition at line 3584 of file [Galileo_E5a.h](#).

10.2.6.5.408 GALILEO_E5A_Q_TIERED_CODE_PERIOD_S

```
double GALILEO_E5A_Q_TIERED_CODE_PERIOD_S = 0.100 [constexpr]
```

Galileo E5a-Q tiered code period [s].

Definition at line 35 of file [Galileo_E5a.h](#).

10.2.6.5.409 GALILEO_E5A_SYMBOL_RATE_BPS

```
int32_t GALILEO_E5A_SYMBOL_RATE_BPS = 50 [constexpr]
```

Galileo E5a symbol rate [bits/second].

Definition at line 41 of file [Galileo_E5a.h](#).

10.2.6.5.410 GALILEO_E5B_CODE_CHIP_RATE_CPS

```
double GALILEO_E5B_CODE_CHIP_RATE_CPS = 1.023e7 [constexpr]
```

Galileo E5b code rate [chips/s].

Definition at line 34 of file [Galileo_E5b.h](#).

10.2.6.5.411 GALILEO_E5B_CODE_LENGTH_CHIPS

```
int32_t GALILEO_E5B_CODE_LENGTH_CHIPS = 10230 [constexpr]
```

Galileo E5b primary code length [chips].

Definition at line 39 of file [Galileo_E5b.h](#).

10.2.6.5.412 GALILEO_E5B_CODE_PERIOD_MS

```
int32_t GALILEO_E5B_CODE_PERIOD_MS = 1 [constexpr]
```

Galileo E5b primary code period [ms].

Definition at line 38 of file [Galileo_E5b.h](#).

10.2.6.5.413 GALILEO_E5B_CODE_PERIOD_S

```
double GALILEO_E5B_CODE_PERIOD_S = 0.001 [constexpr]
```

Galileo E5b primary code period [s].

Definition at line 37 of file [Galileo_E5b.h](#).

10.2.6.5.414 GALILEO_E5B_FREQ_HZ

```
double GALILEO_E5B_FREQ_HZ = FREQ7 [constexpr]
```

Galileo E5b carrier frequency [Hz].

Definition at line 33 of file [Galileo_E5b.h](#).

10.2.6.5.415 GALILEO_E5B_HISTORY_DEEP

```
int32_t GALILEO_E5B_HISTORY_DEEP = 100 [constexpr]
```

Definition at line 47 of file [Galileo_E5b.h](#).

10.2.6.5.416 GALILEO_E5B_I_PRIMARY_CODE

```
char GALILEO_E5B_I_PRIMARY_CODE[GALILEO_E5B_NUMBER_OF_CODES][2559] [constexpr]
```

Definition at line 57 of file [Galileo_E5b.h](#).

10.2.6.5.417 GALILEO_E5B_I_PRIMARY_CODE_STR_LENGTH

```
size_t GALILEO_E5B_I_PRIMARY_CODE_STR_LENGTH = 2558 [constexpr]
```

Definition at line 56 of file [Galileo_E5b.h](#).

10.2.6.5.418 GALILEO_E5B_I_SECONDARY_CODE

```
char GALILEO_E5B_I_SECONDARY_CODE[5] = "1110" [constexpr]
```

Definition at line 53 of file [Galileo_E5b.h](#).

10.2.6.5.419 GALILEO_E5B_I_SECONDARY_CODE_LENGTH

```
int32_t GALILEO_E5B_I_SECONDARY_CODE_LENGTH = 4 [constexpr]
```

Galileo E5b-I secondary code length [chips].

Definition at line 40 of file [Galileo_E5b.h](#).

10.2.6.5.420 GALILEO_E5B_I_TIERED_CODE_PERIOD_S

```
double GALILEO_E5B_I_TIERED_CODE_PERIOD_S = 0.004 [constexpr]
```

Galileo E5b-I tiered code period [s].

Definition at line 35 of file [Galileo_E5b.h](#).

10.2.6.5.421 GALILEO_E5B_NUMBER_OF_CODES

```
int32_t GALILEO_E5B_NUMBER_OF_CODES = 50 [constexpr]
```

Definition at line 43 of file [Galileo_E5b.h](#).

10.2.6.5.422 GALILEO_E5B_OPT_ACQ_FS_SPS

```
uint32_t GALILEO_E5B_OPT_ACQ_FS_SPS = 10000000 [constexpr]
```

Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.

Definition at line 50 of file [Galileo_E5b.h](#).

10.2.6.5.423 GALILEO_E5B_Q_PRIMARY_CODE

```
char GALILEO_E5B_Q_PRIMARY_CODE[GALILEO_E5B_NUMBER_OF_CODES][2559] [constexpr]
```

Definition at line 1812 of file [Galileo_E5b.h](#).

10.2.6.5.424 GALILEO_E5B_Q_PRIMARY_CODE_STR_LENGTH

```
size_t GALILEO_E5B_Q_PRIMARY_CODE_STR_LENGTH = 2558 [constexpr]
```

Definition at line 1811 of file [Galileo_E5b.h](#).

10.2.6.5.425 GALILEO_E5B_Q_SECONDARY_CODE

char GALILEO_E5B_Q_SECONDARY_CODE[GALILEO_E5B_NUMBER_OF_CODES][101] [constexpr]
Definition at line 3568 of file [Galileo_E5b.h](#).

10.2.6.5.426 GALILEO_E5B_Q_SECONDARY_CODE_LENGTH

int32_t GALILEO_E5B_Q_SECONDARY_CODE_LENGTH = 100 [constexpr]
Galileo E5b-Q secondary code length [chips].
Definition at line 41 of file [Galileo_E5b.h](#).

10.2.6.5.427 GALILEO_E5B_Q_SECONDARY_CODE_STR_LENGTH

size_t GALILEO_E5B_Q_SECONDARY_CODE_STR_LENGTH = 100 [constexpr]
Definition at line 3567 of file [Galileo_E5b.h](#).

10.2.6.5.428 GALILEO_E5B_Q_TIERED_CODE_PERIOD_S

double GALILEO_E5B_Q_TIERED_CODE_PERIOD_S = 0.100 [constexpr]
Galileo E5b-Q tiered code period [s].
Definition at line 36 of file [Galileo_E5b.h](#).

10.2.6.5.429 GALILEO_E5B_SYMBOL_RATE_BPS

int32_t GALILEO_E5B_SYMBOL_RATE_BPS = 250 [constexpr]
Galileo E5b symbol rate [bits/second].
Definition at line 42 of file [Galileo_E5b.h](#).

10.2.6.5.430 GALILEO_E6_B_CODE_CHIP_RATE_CPS

double GALILEO_E6_B_CODE_CHIP_RATE_CPS = 5.115e6 [constexpr]
Galileo E6 B code rate [chips/s].
Definition at line 31 of file [Galileo_E6.h](#).

10.2.6.5.431 GALILEO_E6_B_CODE_LENGTH_CHIPS

double GALILEO_E6_B_CODE_LENGTH_CHIPS = 5115.0 [constexpr]
Galileo E6 B code length [chips].
Definition at line 35 of file [Galileo_E6.h](#).

10.2.6.5.432 GALILEO_E6_B_PRIMARY_CODE

char GALILEO_E6_B_PRIMARY_CODE[GALILEO_E6_NUMBER_OF_CODES][1280] [constexpr]
Definition at line 45 of file [Galileo_E6.h](#).

10.2.6.5.433 GALILEO_E6_B_PRIMARY_CODE_STR_LENGTH

size_t GALILEO_E6_B_PRIMARY_CODE_STR_LENGTH = 1279 [constexpr]
Definition at line 44 of file [Galileo_E6.h](#).

10.2.6.5.434 GALILEO_E6_C_CODE_CHIP_RATE_CPS

double GALILEO_E6_C_CODE_CHIP_RATE_CPS = 5.115e6 [constexpr]
Galileo E6 C code rate [chips/s].
Definition at line 32 of file [Galileo_E6.h](#).

10.2.6.5.435 GALILEO_E6_C_CODE_LENGTH_CHIPS

double GALILEO_E6_C_CODE_LENGTH_CHIPS = 5115.0 [constexpr]
Galileo E6 C code length [chips].
Definition at line 36 of file [Galileo_E6.h](#).

10.2.6.5.436 GALILEO_E6_C_PRIMARY_CODE

char GALILEO_E6_C_PRIMARY_CODE[GALILEO_E6_NUMBER_OF_CODES][1280] [constexpr]
Definition at line 950 of file [Galileo_E6.h](#).

10.2.6.5.437 GALILEO_E6_C_PRIMARY_CODE_STR_LENGTH

size_t GALILEO_E6_C_PRIMARY_CODE_STR_LENGTH = 1279 [constexpr]
Definition at line 949 of file [Galileo_E6.h](#).

10.2.6.5.438 GALILEO_E6_C_SECONDARY_CODE

char GALILEO_E6_C_SECONDARY_CODE[GALILEO_E6_NUMBER_OF_CODES][26] [constexpr]
Definition at line 1855 of file [Galileo_E6.h](#).

10.2.6.5.439 GALILEO_E6_C_SECONDARY_CODE_LENGTH_CHIPS

double GALILEO_E6_C_SECONDARY_CODE_LENGTH_CHIPS = 100.0 [constexpr]
Galileo E6 C secondary code length [chips].
Definition at line 37 of file [Galileo_E6.h](#).

10.2.6.5.440 GALILEO_E6_C_SECONDARY_CODE_STR_LENGTH

size_t GALILEO_E6_C_SECONDARY_CODE_STR_LENGTH = 25 [constexpr]
Definition at line 1854 of file [Galileo_E6.h](#).

10.2.6.5.441 GALILEO_E6_CODE_PERIOD_MS

uint32_t GALILEO_E6_CODE_PERIOD_MS = 1 [constexpr]
Galileo E& B/C code period [ms].
Definition at line 38 of file [Galileo_E6.h](#).

10.2.6.5.442 GALILEO_E6_CODE_PERIOD_S

double GALILEO_E6_CODE_PERIOD_S = 0.001 [constexpr]
Galileo E6 code period [s].
Definition at line 33 of file [Galileo_E6.h](#).

10.2.6.5.443 GALILEO_E6_FREQ_HZ

double GALILEO_E6_FREQ_HZ = [FREQ6](#) [constexpr]
Galileo E6 carrier frequency [Hz].
Definition at line 30 of file [Galileo_E6.h](#).

10.2.6.5.444 GALILEO_E6_NUMBER_OF_CODES

int32_t GALILEO_E6_NUMBER_OF_CODES = 50 [constexpr]
Definition at line 40 of file [Galileo_E6.h](#).

10.2.6.5.445 GALILEO_E6_OPT_ACQ_FS_SPS

uint32_t GALILEO_E6_OPT_ACQ_FS_SPS = 10000000 [constexpr]
Definition at line 42 of file [Galileo_E6.h](#).

10.2.6.5.446 GALILEO_F

double GALILEO_F = -4.442807309e-10 [constexpr]
Constant, $[s/(m)^{(1/2)}]$. OS SIS ICD v2.0, pag. 47.
Definition at line 36 of file [MATH_CONSTANTS.h](#).

10.2.6.5.447 GALILEO_FNAV_CODES_PER_PAGE

```
int32_t GALILEO_FNAV_CODES_PER_PAGE = 10000 [constexpr]
```

Definition at line 59 of file [Galileo_E5a.h](#).

10.2.6.5.448 GALILEO_FNAV_CODES_PER_PREAMBLE

```
int32_t GALILEO_FNAV_CODES_PER_PREAMBLE = 240 [constexpr]
```

Definition at line 56 of file [Galileo_E5a.h](#).

10.2.6.5.449 GALILEO_FNAV_CODES_PER_SYMBOL

```
int32_t GALILEO_FNAV_CODES_PER_SYMBOL = 20 [constexpr]
```

Definition at line 55 of file [Galileo_E5a.h](#).

10.2.6.5.450 GALILEO_FNAV_DATA_FRAME_BITS

```
int32_t GALILEO_FNAV_DATA_FRAME_BITS = 214 [constexpr]
```

Definition at line 65 of file [Galileo_E5a.h](#).

10.2.6.5.451 GALILEO_FNAV_DATA_FRAME_BYTES

```
int32_t GALILEO_FNAV_DATA_FRAME_BYTES = 27 [constexpr]
```

Definition at line 66 of file [Galileo_E5a.h](#).

10.2.6.5.452 GALILEO_FNAV_INTERLEAVER_COLS

```
int32_t GALILEO_FNAV_INTERLEAVER_COLS = 61 [constexpr]
```

Definition at line 62 of file [Galileo_E5a.h](#).

10.2.6.5.453 GALILEO_FNAV_INTERLEAVER_ROWS

```
int32_t GALILEO_FNAV_INTERLEAVER_ROWS = 8 [constexpr]
```

Definition at line 61 of file [Galileo_E5a.h](#).

10.2.6.5.454 GALILEO_FNAV_PAGE_TYPE_BITS

```
int32_t GALILEO_FNAV_PAGE_TYPE_BITS = 6 [constexpr]
```

Definition at line 63 of file [Galileo_E5a.h](#).

10.2.6.5.455 GALILEO_FNAV_PREAMBLE

```
char GALILEO_FNAV_PREAMBLE[13] = "101101110000" [constexpr]
```

Definition at line 68 of file [Galileo_E5a.h](#).

10.2.6.5.456 GALILEO_FNAV_PREAMBLE_LENGTH_BITS

```
int32_t GALILEO_FNAV_PREAMBLE_LENGTH_BITS = 12 [constexpr]
```

Definition at line 54 of file [Galileo_E5a.h](#).

10.2.6.5.457 GALILEO_FNAV_SECONDS_PER_PAGE

```
int32_t GALILEO_FNAV_SECONDS_PER_PAGE = 10 [constexpr]
```

Definition at line 58 of file [Galileo_E5a.h](#).

10.2.6.5.458 GALILEO_FNAV_SYMBOLS_PER_PAGE

```
int32_t GALILEO_FNAV_SYMBOLS_PER_PAGE = 500 [constexpr]
```

Definition at line 57 of file [Galileo_E5a.h](#).

10.2.6.5.459 GALILEO_GM

double GALILEO_GM = 3.986004418e14 [constexpr]
Geocentric gravitational constant[m³/s²], OS SIS ICD v2.0, pag. 44.
Definition at line 35 of file [MATH_CONSTANTS.h](#).

10.2.6.5.460 GALILEO_INAV_ENCODED_SSP1

char GALILEO_INAV_ENCODED_SSP1[17] = "1110100100100101" [constexpr]
Definition at line 303 of file [Galileo_INAV.h](#).

10.2.6.5.461 GALILEO_INAV_ENCODED_SSP2

char GALILEO_INAV_ENCODED_SSP2[17] = "0110110001001110" [constexpr]
Definition at line 304 of file [Galileo_INAV.h](#).

10.2.6.5.462 GALILEO_INAV_ENCODED_SSP3

char GALILEO_INAV_ENCODED_SSP3[17] = "1101000000111110" [constexpr]
Definition at line 305 of file [Galileo_INAV.h](#).

10.2.6.5.463 GALILEO_INAV_INTERLEAVER_COLS

int32_t GALILEO_INAV_INTERLEAVER_COLS = 30 [constexpr]
Definition at line 43 of file [Galileo_INAV.h](#).

10.2.6.5.464 GALILEO_INAV_INTERLEAVER_ROWS

int32_t GALILEO_INAV_INTERLEAVER_ROWS = 8 [constexpr]
Definition at line 42 of file [Galileo_INAV.h](#).

10.2.6.5.465 GALILEO_INAV_PAGE_PART_MS

int32_t GALILEO_INAV_PAGE_PART_MS = 1000 [constexpr]
Definition at line 40 of file [Galileo_INAV.h](#).

10.2.6.5.466 GALILEO_INAV_PAGE_PART_SECONDS

int32_t GALILEO_INAV_PAGE_PART_SECONDS = 1 [constexpr]
Definition at line 39 of file [Galileo_INAV.h](#).

10.2.6.5.467 GALILEO_INAV_PAGE_PART_SYMBOLS

int32_t GALILEO_INAV_PAGE_PART_SYMBOLS = 250 [constexpr]
Each Galileo INAV pages are composed of two parts (even and odd) each of 250 symbols, including preamble. See Galileo ICD 4.3.2.
Definition at line 38 of file [Galileo_INAV.h](#).

10.2.6.5.468 GALILEO_INAV_PAGE_PART_WITH_PREAMBLE_SECONDS

double GALILEO_INAV_PAGE_PART_WITH_PREAMBLE_SECONDS = 2.04 [constexpr]
Page Duration + (Galileo I/NAV Preamble bits)*(Galileo E5b-I tiered Code Period(seconds))
Definition at line 34 of file [Galileo_INAV.h](#).

10.2.6.5.469 GALILEO_INAV_PAGE_SECONDS

int32_t GALILEO_INAV_PAGE_SECONDS = 2 [constexpr]
Definition at line 41 of file [Galileo_INAV.h](#).

10.2.6.5.470 GALILEO_INAV_PAGE_SYMBOLS

```
uint32_t GALILEO_INAV_PAGE_SYMBOLS = 500 [constexpr]
```

The complete Galileo INAV page length.

Definition at line 35 of file [Galileo_INAV.h](#).

10.2.6.5.471 GALILEO_INAV_PLAIN_SSP1

```
char GALILEO_INAV_PLAIN_SSP1[9] = "00000100" [constexpr]
```

Definition at line 300 of file [Galileo_INAV.h](#).

10.2.6.5.472 GALILEO_INAV_PLAIN_SSP2

```
char GALILEO_INAV_PLAIN_SSP2[9] = "00101011" [constexpr]
```

Definition at line 301 of file [Galileo_INAV.h](#).

10.2.6.5.473 GALILEO_INAV_PLAIN_SSP3

```
char GALILEO_INAV_PLAIN_SSP3[9] = "00101111" [constexpr]
```

Definition at line 302 of file [Galileo_INAV.h](#).

10.2.6.5.474 GALILEO_INAV_PREAMBLE

```
char GALILEO_INAV_PREAMBLE[11] = "0101100000" [constexpr]
```

Definition at line 49 of file [Galileo_INAV.h](#).

10.2.6.5.475 GALILEO_INAV_PREAMBLE_LENGTH_BITS

```
int32_t GALILEO_INAV_PREAMBLE_LENGTH_BITS = 10 [constexpr]
```

Definition at line 36 of file [Galileo_INAV.h](#).

10.2.6.5.476 GALILEO_INAV_PREAMBLE_PERIOD_SYMBOLS

```
int32_t GALILEO_INAV_PREAMBLE_PERIOD_SYMBOLS = 250 [constexpr]
```

Definition at line 37 of file [Galileo_INAV.h](#).

10.2.6.5.477 GALILEO_ISM_CRC_DATA_BITS

```
int32_t GALILEO_ISM_CRC_DATA_BITS = 96 [constexpr]
```

Definition at line 291 of file [Galileo_INAV.h](#).

10.2.6.5.478 GALILEO_ISM_CRC_DATA_BYTES

```
int32_t GALILEO_ISM_CRC_DATA_BYTES = 12 [constexpr]
```

Definition at line 292 of file [Galileo_INAV.h](#).

10.2.6.5.479 GALILEO_PAGE_TYPE_BITS

```
int32_t GALILEO_PAGE_TYPE_BITS = 6 [constexpr]
```

Definition at line 45 of file [Galileo_INAV.h](#).

10.2.6.5.480 GALILEO_TELEMETRY_RATE_BITS_SECOND

```
int32_t GALILEO_TELEMETRY_RATE_BITS_SECOND = 250 [constexpr]
```

Definition at line 44 of file [Galileo_INAV.h](#).

10.2.6.5.481 GLONASS_C20

```
double GLONASS_C20 = -1082.63e-6 [constexpr]
```

Second zonal coefficient of spherical harmonic expansion.

Definition at line 45 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.482 GLONASS_CA_NBR_SATS

`int32_t GLONASS_CA_NBR_SATS = 24 [constexpr]`
 Definition at line 88 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.483 GLONASS_EARTH_INCLINATION

`double GLONASS_EARTH_INCLINATION = 0.000409148809899e3 [constexpr]`
 Mean inclination of ecliptic to equator (23 deg 26 min 33 sec) [rad].
 Definition at line 47 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.484 GLONASS_EARTH_RADIUS

`double GLONASS_EARTH_RADIUS = 6378.136 [constexpr]`
 Equatorial radius of Earth [km].
 Definition at line 46 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.485 GLONASS_F_M_A

`double GLONASS_F_M_A = 0.35e9 [constexpr]`
 Gravitational constant of atmosphere [m^3/s^2].
 Definition at line 35 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.486 GLONASS_FLATTENING

`double GLONASS_FLATTENING = 1.0 / 29825784.0 [constexpr]`
 Flattening parameter.
 Definition at line 37 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.487 GLONASS_GM

`double GLONASS_GM = 398600.44e9 [constexpr]`
 Universal gravitational constant times the mass of the Earth, [m^3/s^2].
 Definition at line 40 of file [MATH_CONSTANTS.h](#).

10.2.6.5.488 GLONASS_GNAV_CRC_I_INDEX

`const std::vector<int32_t> GLONASS_GNAV_CRC_I_INDEX {9, 10, 12, 13, 15, 17, 19, 20, 22, 24, 26, 28, 30, 32, 34, 35, 37, 39, 41, 43, 45, 47, 49, 51, 53, 55, 57, 59, 61, 63, 65, 66, 68, 70, 72, 74, 76, 78, 80, 82, 84}`
 Definition at line 244 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.489 GLONASS_GNAV_CRC_J_INDEX

`const std::vector<int32_t> GLONASS_GNAV_CRC_J_INDEX {9, 11, 12, 14, 15, 18, 19, 21, 22, 25, 26, 29, 30, 33, 34, 36, 37, 40, 41, 44, 45, 48, 49, 52, 53, 56, 57, 60, 61, 64, 65, 67, 68, 71, 72, 75, 76, 79, 80, 83, 84}`
 Definition at line 245 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.490 GLONASS_GNAV_CRC_K_INDEX

`const std::vector<int32_t> GLONASS_GNAV_CRC_K_INDEX {10, 11, 12, 16, 17, 18, 19, 23, 24, 25, 26, 31, 32, 33, 34, 38, 39, 40, 41, 46, 47, 48, 49, 54, 55, 56, 57, 62, 63, 64, 65, 69, 70, 71, 72, 77, 78, 79, 80, 85}`
 Definition at line 246 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.491 GLONASS_GNAV_CRC_L_INDEX

```
const std::vector<int32_t> GLONASS_GNAV_CRC_L_INDEX {13, 14, 15, 16, 17, 18, 19, 27, 28, 29,
30, 31, 32, 33, 34, 42, 43, 44, 45, 46, 47, 48, 49, 58, 59, 60, 61, 62, 63, 64, 65, 73, 74,
75, 76, 77, 78, 79, 80}
```

Definition at line 247 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.492 GLONASS_GNAV_CRC_M_INDEX

```
const std::vector<int32_t> GLONASS_GNAV_CRC_M_INDEX {20, 21, 22, 23, 24, 25, 26, 27, 28, 29,
30, 31, 32, 33, 34, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 81, 82,
83, 84, 85}
```

Definition at line 248 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.493 GLONASS_GNAV_CRC_N_INDEX

```
const std::vector<int32_t> GLONASS_GNAV_CRC_N_INDEX {35, 36, 37, 38, 39, 40, 41, 42, 43, 44,
45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65}
```

Definition at line 249 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.494 GLONASS_GNAV_CRC_P_INDEX

```
const std::vector<int32_t> GLONASS_GNAV_CRC_P_INDEX {66, 67, 68, 69, 70, 71, 72, 73, 74, 75,
76, 77, 78, 79, 80, 81, 82, 83, 84, 85}
```

Definition at line 250 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.495 GLONASS_GNAV_CRC_Q_INDEX

```
const std::vector<int32_t> GLONASS_GNAV_CRC_Q_INDEX {9, 10, 11, 12, 13, 14, 15, 16, 17, 18,
19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41,
42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64,
65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85}
```

Definition at line 251 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.496 GLONASS_GNAV_DATA_SYMBOLS

```
int32_t GLONASS_GNAV_DATA_SYMBOLS = 1700 [constexpr]
```

Definition at line 116 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.497 GLONASS_GNAV_ECC_LOCATOR

```
const std::vector<int32_t> GLONASS_GNAV_ECC_LOCATOR {0, 0, 1, 8, 2, 9, 10, 11, 3, 12, 13, 14,
15, 16, 17, 18, 4, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 5, 34, 35, 36,
37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59,
60, 61, 62, 63, 64, 6, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82,
83, 84}
```

Definition at line 252 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.498 GLONASS_GNAV_HAMMING_CODE_BITS

```
int32_t GLONASS_GNAV_HAMMING_CODE_BITS = 8 [constexpr]
```

Number of bits in hamming code sequence of GNAV message.

Definition at line 115 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.499 GLONASS_GNAV_PREAMBLE_DURATION_S

```
double GLONASS_GNAV_PREAMBLE_DURATION_S = 0.300 [constexpr]
```

Definition at line 103 of file [GLONASS_L1_L2_CA.h](#).

int32_t GLONASS_GNAV_PREAMBLE_LENGTH_BITS = 30 [constexpr]
Definition at line 104 of file [GLONASS_L1_L2_CA.h](#).

int32_t GLONASS_GNAV_PREAMBLE_LENGTH_SYMBOLS = 300 [constexpr]
Definition at line 105 of file [GLONASS_L1_L2_CA.h](#).

int32_t GLONASS_GNAV_PREAMBLE_PERIOD_BITS = 200 [constexpr]
Definition at line 107 of file [GLONASS_L1_L2_CA.h](#).

int32_t GLONASS_GNAV_PREAMBLE_PERIOD_SYMBOLS = 2000 [constexpr]
Definition at line 106 of file [GLONASS_L1_L2_CA.h](#).

[illegible]

int32_t GLONASS_GNAV_STRING_BIBINARY_WITH_PREAMBLE = 200 [constexpr]
Number of bits per string in the GNAV message (85 data bits + 30 time mark bits) [bits].
Definition at line 113 of file [GLONASS_L1_L2_CA.h](#).

int32_t GLONASS_GNAV_STRING_BITS = 85 [constexpr]
Number of bits per string in the GNAV message (85 data bits + 30 time mark bits) [bits].
Definition at line 114 of file [GLONASS_L1_L2_CA.h](#).

```
int32_t GLONASS_GNAV_STRING_SYMBOLS_WITH_PREAMBLE = 2000 [constexpr]
```

Definition at line 112 of file [GLONASS L1 L2 CA.h](#).

int32_t GLONASS_GNAV_TELEMETRY_RATE_BITS_SECOND = 50 [constexpr]
NAV message bit rate [bits/s].
Definition at line 108 of file [GLONASS_L1_L2_CA.h](#).

int32_t GLONASS_GNAV_TELEMETRY_RATE_SYMBOLS_SECOND = GLONASS_GNAV_TELEMETRY_RATE_BITS_SECOND *
GLONASS_GNAV_TELEMETRY_SYMBOLS_PER_BIT [constexpr]
NAV message bit rate [symbols/s].
Definition at line 111 of file [GLONASS_L1_L2_CA.h](#).

int32_t GLONASS_GNAV_TELEMETRY_SYMBOLS_PER_BIT = 10 [constexpr]
Definition at line 109 of file [GLONASS L1 L2 CA.h](#).

10.2.6.5.511 GLONASS_GNAV_TELEMETRY_SYMBOLS_PER_PREAMBLE_BIT

`int32_t GLONASS_GNAV_TELEMETRY_SYMBOLS_PER_PREAMBLE_BIT = 10 [constexpr]`
Definition at line 110 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.512 GLONASS_GRAVITY

`double GLONASS_GRAVITY = 97803284.0 [constexpr]`
Equatorial acceleration of gravity [mGal].
Definition at line 38 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.513 GLONASS_GRAVITY_CORRECTION

`double GLONASS_GRAVITY_CORRECTION = 0.87 [constexpr]`
Correction to acceleration of gravity at sea-level due to Atmosphere[uGal].
Definition at line 39 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.514 GLONASS_J2

`double GLONASS_J2 = 1082625.75e-9 [constexpr]`
Second zonal harmonic of the geopotential.
Definition at line 40 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.515 GLONASS_J4

`double GLONASS_J4 = -2370.89e-9 [constexpr]`
Fourth zonal harmonic of the geopotential.
Definition at line 41 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.516 GLONASS_J6

`double GLONASS_J6 = 6.08e-9 [constexpr]`
Sixth zonal harmonic of the geopotential.
Definition at line 42 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.517 GLONASS_J8

`double GLONASS_J8 = 1.40e-11 [constexpr]`
Eighth zonal harmonic of the geopotential.
Definition at line 43 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.518 GLONASS_L1_CA_CHIP_PERIOD_S

`double GLONASS_L1_CA_CHIP_PERIOD_S = 1.9569e-06 [constexpr]`
GLONASS L1 C/A chip period [seconds].
Definition at line 83 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.519 GLONASS_L1_CA_CODE_LENGTH_CHIPS

`double GLONASS_L1_CA_CODE_LENGTH_CHIPS = 511.0 [constexpr]`
GLONASS L1 C/A code length [chips].
Definition at line 80 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.520 GLONASS_L1_CA_CODE_PERIOD_MS

`uint32_t GLONASS_L1_CA_CODE_PERIOD_MS = 1 [constexpr]`
Definition at line 86 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.521 GLONASS_L1_CA_CODE_PERIOD_S

double GLONASS_L1_CA_CODE_PERIOD_S = 0.001 [constexpr]
GLONASS L1 C/A code period [seconds].
Definition at line 81 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.522 GLONASS_L1_CA_CODE_RATE_CPS

double GLONASS_L1_CA_CODE_RATE_CPS = 0.511e6 [constexpr]
GLONASS L1 C/A code rate [chips/s].
Definition at line 79 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.523 GLONASS_L1_CA_DFREQ_HZ

double GLONASS_L1_CA_DFREQ_HZ = DFRQ1_GLO [constexpr]
Freq Bias for GLONASS L1 [Hz].
Definition at line 78 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.524 GLONASS_L1_CA_FREQ_HZ

double GLONASS_L1_CA_FREQ_HZ = FREQ1_GLO [constexpr]
L1 [Hz].
Definition at line 77 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.525 GLONASS_L1_CA_HISTORY_DEEP

int32_t GLONASS_L1_CA_HISTORY_DEEP = 100 [constexpr]
Definition at line 91 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.526 GLONASS_L1_CA_SYMBOL_PERIOD_S

double GLONASS_L1_CA_SYMBOL_PERIOD_S = 0.01 [constexpr]
GLONASS L1 C/A symbol period [seconds].
Definition at line 82 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.527 GLONASS_L1_CA_SYMBOL_RATE_BPS

double GLONASS_L1_CA_SYMBOL_RATE_BPS = 1000.0 [constexpr]
Definition at line 84 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.528 GLONASS_L2_CA_CHIP_PERIOD_S

double GLONASS_L2_CA_CHIP_PERIOD_S = 1.9569e-06 [constexpr]
GLONASS L1 C/A chip period [seconds].
Definition at line 74 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.529 GLONASS_L2_CA_CODE_LENGTH_CHIPS

double GLONASS_L2_CA_CODE_LENGTH_CHIPS = 511.0 [constexpr]
GLONASS L1 C/A code length [chips].
Definition at line 71 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.530 GLONASS_L2_CA_CODE_PERIOD_MS

uint32_t GLONASS_L2_CA_CODE_PERIOD_MS = 1 [constexpr]
Definition at line 87 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.531 GLONASS_L2_CA_CODE_PERIOD_S

```
double GLONASS_L2_CA_CODE_PERIOD_S = 0.001 [constexpr]
```

GLONASS L1 C/A code period [seconds].

Definition at line 72 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.532 GLONASS_L2_CA_CODE_RATE_CPS

```
double GLONASS_L2_CA_CODE_RATE_CPS = 0.511e6 [constexpr]
```

GLONASS L1 C/A code rate [chips/s].

Definition at line 70 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.533 GLONASS_L2_CA_DFREQ_HZ

```
double GLONASS_L2_CA_DFREQ_HZ = DFRQ2_GLO [constexpr]
```

Freq Bias for GLONASS L1 [Hz].

Definition at line 69 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.534 GLONASS_L2_CA_FREQ_HZ

```
double GLONASS_L2_CA_FREQ_HZ = FREQ2_GLO [constexpr]
```

L2 [Hz].

Definition at line 68 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.535 GLONASS_L2_CA_SYMBOL_PERIOD_S

```
double GLONASS_L2_CA_SYMBOL_PERIOD_S = 0.01 [constexpr]
```

GLONASS L1 C/A symbol period [seconds].

Definition at line 73 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.536 GLONASS_L2_CA_SYMBOL_RATE_BPS

```
double GLONASS_L2_CA_SYMBOL_RATE_BPS = 1000.0 [constexpr]
```

Definition at line 75 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.537 GLONASS_LEAP_SECONDS

```
double GLONASS_LEAP_SECONDS[19][7] [constexpr]
```

Initial value:

```
= {
    {2017, 1, 1, 0, 0, 0, -18},
    {2015, 7, 1, 0, 0, 0, -17},
    {2012, 7, 1, 0, 0, 0, -16},
    {2009, 1, 1, 0, 0, 0, -15},
    {2006, 1, 1, 0, 0, 0, -14},
    {1999, 1, 1, 0, 0, 0, -13},
    {1997, 7, 1, 0, 0, 0, -12},
    {1996, 1, 1, 0, 0, 0, -11},
    {1994, 7, 1, 0, 0, 0, -10},
    {1993, 7, 1, 0, 0, 0, -9},
    {1992, 7, 1, 0, 0, 0, -8},
    {1991, 1, 1, 0, 0, 0, -7},
    {1990, 1, 1, 0, 0, 0, -6},
    {1988, 1, 1, 0, 0, 0, -5},
    {1985, 7, 1, 0, 0, 0, -4},
    {1983, 7, 1, 0, 0, 0, -3},
    {1982, 7, 1, 0, 0, 0, -2},
    {1981, 7, 1, 0, 0, 0, -1},
    {}
}
```

Record of leap seconds definition for GLOT to GPST conversion and vice versa.

Each entry is defined by an array of 7 elements consisting of yr,month,day,hr,min,sec,utc-gpst

Note

Ideally should use leap seconds definitions of rtklib GLONASS SV's orbital slots PRN = (orbital_slot - 1)

Definition at line 123 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.538 GLONASS_MOON_ECCENTRICITY

```
double GLONASS_MOON_ECCENTRICITY = 0.054900489 [constexpr]
```

Eccentricity of lunar orbit.

Definition at line 58 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.539 GLONASS_MOON_GM

```
double GLONASS_MOON_GM = 4902.835 [constexpr]
```

Lunar gravitational constant [km^3/s^2].

Definition at line 56 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.540 GLONASS_MOON_INCLINATION

```
double GLONASS_MOON_INCLINATION = 0.000089803977407e3 [constexpr]
```

Inclination of lunar orbit to ecliptic plane (5 deg 08 min 43.4 sec) [rad].

Definition at line 59 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.541 GLONASS_MOON_OMEGA_0

```
double GLONASS_MOON_OMEGA_0 = 0.004523601514852e3 [constexpr]
```

(259 deg 10 min 59.79 sec) [rad]

Definition at line 54 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.542 GLONASS_MOON_OMEGA_1

```
double GLONASS_MOON_OMEGA_1 = -0.033757146246552e3 [constexpr]
```

(-1934 deg 08 min 31.23 sec) [rad]

Definition at line 55 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.543 GLONASS_MOON_Q0

```
double GLONASS_MOON_Q0 = -0.001115184961435e3 [constexpr]
```

(-63 deg 53 min 43.41 sec) [rad]

Definition at line 52 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.544 GLONASS_MOON_Q1

```
double GLONASS_MOON_Q1 = 8.328691103668023e3 [constexpr]
```

(477198 deg 50 min 56.79 sec) [rad]

Definition at line 53 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.545 GLONASS_MOON_SEMI_MAJOR_AXIS

```
double GLONASS_MOON_SEMI_MAJOR_AXIS = 3.84385243e5 [constexpr]
```

Semi-major axis of lunar orbit [km];.

Definition at line 57 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.546 GLONASS_OMEGA_EARTH_DOT

```
double GLONASS_OMEGA_EARTH_DOT = 7.292115e-5 [constexpr]
```

Earth rotation rate, [rad/s] ICD L1, L2 GLONASS Edition 5.1 2008 pag. 55.

Definition at line 39 of file [MATH_CONSTANTS.h](#).

10.2.6.5.547 GLONASS_PRN

```
const std::map<uint32_t, int32_t> GLONASS_PRN
```

Definition at line 145 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.548 GLONASS_SEMI_MAJOR_AXIS

```
double GLONASS_SEMI_MAJOR_AXIS = 6378136 [constexpr]
```

Semi-major axis of Earth [m].

Definition at line 36 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.549 GLONASS_SUN_ECCENTRICITY

```
double GLONASS_SUN_ECCENTRICITY = 0.016719 [constexpr]
```

Eccentricity of solar orbit.

Definition at line 66 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.550 GLONASS_SUN_GM

```
double GLONASS_SUN_GM = 0.1325263e12 [constexpr]
```

Solar gravitational constant [km^3/s^2].

Definition at line 64 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.551 GLONASS_SUN_OMEGA

```
double GLONASS_SUN_OMEGA = 0.004908229466869e3 [constexpr]
```

TODO What is this operation in the seconds with T?(281 deg 13 min 15.0 + 6189.03 x T sec) [rad].

Definition at line 61 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.552 GLONASS_SUN_Q0

```
double GLONASS_SUN_Q0 = 0.006256583774423e3 [constexpr]
```

(358 deg 28 min 33.04 sec) [rad]

Definition at line 62 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.553 GLONASS_SUN_Q1

```
double GLONASS_SUN_Q1 = 0e3 [constexpr]
```

TODO Why is the value greater than 60?(129596579.10 sec) [rad].

Definition at line 63 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.554 GLONASS_SUN_SEMI_MAJOR_AXIS

```
double GLONASS_SUN_SEMI_MAJOR_AXIS = 1.49598e8 [constexpr]
```

Semi-major axis of solar orbit [km];.

Definition at line 65 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.555 GLONASS_TAU_0

```
double GLONASS_TAU_0 = -0.005835151531174e3 [constexpr]
```

(-334 deg 19 min 46.40 sec) [rad];

Definition at line 49 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.556 GLONASS_TAU_1

```
double GLONASS_TAU_1 = 0.071018041257371e3 [constexpr]
```

(4069 deg 02 min 02.52 sec) [rad];

Definition at line 50 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.557 GLONASS_U0

```
double GLONASS_U0 = 62636861.4 [constexpr]
```

Normal potential at surface of common terrestrial ellipsoid [m^2/s^2].

Definition at line 44 of file [GLONASS_L1_L2_CA.h](#).

10.2.6.5.569 GPS_CNAV_DATA_PAGE_BITS

`int32_t GPS_CNAV_DATA_PAGE_BITS = 300 [constexpr]`
Definition at line 35 of file [GPS_CNAV.h](#).

10.2.6.5.570 GPS_F

`double GPS_F = -4.442807633e-10 [constexpr]`
Constant, $[s/(m)^{(1/2)}]$, IS-GPS-200M, 20.3.3.3.3.1.
Definition at line 32 of file [MATH_CONSTANTS.h](#).

10.2.6.5.571 GPS_GM

`double GPS_GM = 3.986005e14 [constexpr]`
Universal gravitational constant times the mass of the Earth, $[m^3/s^2]$ IS-GPS-200M, 20.3.3.3.3.1.
Definition at line 31 of file [MATH_CONSTANTS.h](#).

10.2.6.5.572 GPS_L1_CA_BIT_PERIOD_MS

`uint32_t GPS_L1_CA_BIT_PERIOD_MS = 20U [constexpr]`
GPS L1 C/A bit period [ms].
Definition at line 40 of file [GPS_L1_CA.h](#).

10.2.6.5.573 GPS_L1_CA_CHIP_PERIOD_S

`double GPS_L1_CA_CHIP_PERIOD_S = 9.7752e-07 [constexpr]`
GPS L1 C/A chip period [seconds].
Definition at line 38 of file [GPS_L1_CA.h](#).

10.2.6.5.574 GPS_L1_CA_CODE_LENGTH_CHIPS

`double GPS_L1_CA_CODE_LENGTH_CHIPS = 1023.0 [constexpr]`
GPS L1 C/A code length [chips].
Definition at line 36 of file [GPS_L1_CA.h](#).

10.2.6.5.575 GPS_L1_CA_CODE_PERIOD_MS

`uint32_t GPS_L1_CA_CODE_PERIOD_MS = 1U [constexpr]`
GPS L1 C/A code period [ms].
Definition at line 39 of file [GPS_L1_CA.h](#).

10.2.6.5.576 GPS_L1_CA_CODE_PERIOD_S

`double GPS_L1_CA_CODE_PERIOD_S = 0.001 [constexpr]`
GPS L1 C/A code period [seconds].
Definition at line 37 of file [GPS_L1_CA.h](#).

10.2.6.5.577 GPS_L1_CA_CODE_RATE_CPS

`double GPS_L1_CA_CODE_RATE_CPS = 1.023e6 [constexpr]`
GPS L1 C/A code rate [chips/s].
Definition at line 35 of file [GPS_L1_CA.h](#).

10.2.6.5.578 GPS_L1_CA_HISTORY_DEEP

`int32_t GPS_L1_CA_HISTORY_DEEP = 100 [constexpr]`
Definition at line 56 of file [GPS_L1_CA.h](#).

10.2.6.5.579 GPS_L1_CA_OPT_ACQ_FS_SPS

```
uint32_t GPS_L1_CA_OPT_ACQ_FS_SPS = 2000000 [constexpr]
```

Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.

Definition at line 53 of file [GPS_L1_CA.h](#).

10.2.6.5.580 GPS_L1_FREQ_HZ

```
double GPS_L1_FREQ_HZ = FREQ1 [constexpr]
```

L1 [Hz].

Definition at line 34 of file [GPS_L1_CA.h](#).

10.2.6.5.581 GPS_L2_CNAV_DATA_PAGE_BITS

```
int32_t GPS_L2_CNAV_DATA_PAGE_BITS = 300 [constexpr]
```

GPS L2 CNAV page length, including preamble and CRC [bits].

Definition at line 45 of file [GPS_L2C.h](#).

10.2.6.5.582 GPS_L2_CNAV_DATA_PAGE_DURATION_S

```
int32_t GPS_L2_CNAV_DATA_PAGE_DURATION_S = 12 [constexpr]
```

Definition at line 49 of file [GPS_L2C.h](#).

10.2.6.5.583 GPS_L2_CNAV_DATA_PAGE_SYMBOLS

```
int32_t GPS_L2_CNAV_DATA_PAGE_SYMBOLS = 600 [constexpr]
```

Definition at line 48 of file [GPS_L2C.h](#).

10.2.6.5.584 GPS_L2_FREQ_HZ

```
double GPS_L2_FREQ_HZ = FREQ2 [constexpr]
```

L2 [Hz].

Definition at line 35 of file [GPS_L2C.h](#).

10.2.6.5.585 GPS_L2_L_CODE_LENGTH_CHIPS

```
int32_t GPS_L2_L_CODE_LENGTH_CHIPS = 767250 [constexpr]
```

GPS L2 L code length [chips].

Definition at line 44 of file [GPS_L2C.h](#).

10.2.6.5.586 GPS_L2_L_CODE_RATE_CPS

```
double GPS_L2_L_CODE_RATE_CPS = 0.5115e6 [constexpr]
```

GPS L2 L code rate [chips/s].

Definition at line 40 of file [GPS_L2C.h](#).

10.2.6.5.587 GPS_L2_L_PERIOD_S

```
double GPS_L2_L_PERIOD_S = 1.5 [constexpr]
```

GPS L2 L code period [seconds].

Definition at line 36 of file [GPS_L2C.h](#).

10.2.6.5.588 GPS_L2_M_CODE_LENGTH_CHIPS

```
int32_t GPS_L2_M_CODE_LENGTH_CHIPS = 10230 [constexpr]
```

GPS L2 M code length [chips].

Definition at line 42 of file [GPS_L2C.h](#).

10.2.6.5.589 GPS_L2_M_CODE_LENGTH_CHIPS_L_ZEROED

```
int32_t GPS_L2_M_CODE_LENGTH_CHIPS_L_ZEROED = 2 * GPS_L2_M_CODE_LENGTH_CHIPS [constexpr]
```

GPS L2 M code length with L2 CL zeroed [chips].

Definition at line 43 of file [GPS_L2C.h](#).

10.2.6.5.590 GPS_L2_M_CODE_PERIOD_MS

```
uint32_t GPS_L2_M_CODE_PERIOD_MS = 20 [constexpr]
```

GPS L2 L code period [ms].

Definition at line 41 of file [GPS_L2C.h](#).

10.2.6.5.591 GPS_L2_M_CODE_RATE_CPS

```
double GPS_L2_M_CODE_RATE_CPS = 0.5115e6 [constexpr]
```

GPS L2 M code rate [chips/s].

Definition at line 37 of file [GPS_L2C.h](#).

10.2.6.5.592 GPS_L2_M_CODE_RATE_L_ZEROED_CPS

```
double GPS_L2_M_CODE_RATE_L_ZEROED_CPS = 1.023e6 [constexpr]
```

GPS L2 M code rate with L2 M Zeroed [chips/s].

Definition at line 38 of file [GPS_L2C.h](#).

10.2.6.5.593 GPS_L2_M_PERIOD_S

```
double GPS_L2_M_PERIOD_S = 0.02 [constexpr]
```

GPS L2 M code period [seconds].

Definition at line 39 of file [GPS_L2C.h](#).

10.2.6.5.594 GPS_L2_SAMPLES_PER_SYMBOL

```
int32_t GPS_L2_SAMPLES_PER_SYMBOL = 1 [constexpr]
```

Definition at line 47 of file [GPS_L2C.h](#).

10.2.6.5.595 GPS_L2_SYMBOLS_PER_BIT

```
int32_t GPS_L2_SYMBOLS_PER_BIT = 2 [constexpr]
```

Definition at line 46 of file [GPS_L2C.h](#).

10.2.6.5.596 GPS_L2C_HISTORY_DEEP

```
int32_t GPS_L2C_HISTORY_DEEP = 5 [constexpr]
```

Definition at line 51 of file [GPS_L2C.h](#).

10.2.6.5.597 GPS_L2C_M_INIT_REG

```
int32_t GPS_L2C_M_INIT_REG[115] [constexpr]
```

Initial value:

=

```
{0742417664, 0756014035, 0002747144, 0066265724,
 0601403471, 0703232733, 0124510070, 0617316361,
 0047541621, 0733031046, 0713512145, 0024437606,
 0021264003, 0230655351, 0001314400, 0222021506,
 0540264026, 0205521705, 0064022144, 0120161274,
 0044023533, 0724744327, 0045743577, 0741201660,
 0700274134, 0010247261, 0713433445, 0737324162,
 0311627434, 0710452007, 0722462133, 0050172213,
 0500653703, 0755077436, 0136717361, 0756675453,
 0435506112, 0771353753, 0226107701, 0022025110,
 0402466344, 0752566114, 0702011164, 0041216771,
 0047457275, 0266333164, 0713167356, 0060546335,
 0355173035, 0617201036, 0157465571, 0767360553,
 0023127030, 0431343777, 0747317317, 0045706125,
 0002744276, 0060036467, 0217744147, 0603340174,
```



```
0326616775, 0063240065, 0111460621,
0604055104, 0157065232, 0013305707, 0603552017,
0230461355, 0603653437, 0652346475, 0743107103,
0401521277, 0167335110, 0014013575, 0362051132,
0617753265, 0216363634, 0755561123, 0365304033,
0625025543, 0054420334, 0415473671, 0662364360,
0373446602, 0417564100, 0000526452, 0226631300,
0113752074, 0706134401, 0041352546, 0664630154,
0276524255, 0714720530, 0714051771, 0044526647,
0207164322, 0262120161, 0204244652, 0202133131,
0714351204, 0657127260, 0130567507, 0670517677,
0607275514, 0045413633, 0212645405, 0613700455,
0706202440, 0705056276, 0020373522, 0746013617,
0132720621, 0434015513, 0566721727, 0140633660}
```

Definition at line 56 of file [GPS_L2C.h](#).

10.2.6.5.598 GPS_L2C_OPT_ACQ_FS_SPS

```
uint32_t GPS_L2C_OPT_ACQ_FS_SPS = 2000000 [constexpr]
```

Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.

Definition at line 54 of file [GPS_L2C.h](#).

10.2.6.5.599 GPS_L5_CNAV_DATA_PAGE_BITS

```
int32_t GPS_L5_CNAV_DATA_PAGE_BITS = 300 [constexpr]
```

GPS L5 CNAV page length, including preamble and CRC [bits].

Definition at line 162 of file [GPS_L5.h](#).

10.2.6.5.600 GPS_L5_CNAV_DATA_PAGE_DURATION_S

```
int32_t GPS_L5_CNAV_DATA_PAGE_DURATION_S = 6 [constexpr]
```

Definition at line 166 of file [GPS_L5.h](#).

10.2.6.5.601 GPS_L5_CNAV_DATA_PAGE_SYMBOLS

```
int32_t GPS_L5_CNAV_DATA_PAGE_SYMBOLS = 600 [constexpr]
```

Definition at line 165 of file [GPS_L5.h](#).

10.2.6.5.602 GPS_L5_FREQ_HZ

```
double GPS_L5_FREQ_HZ = FREQ5 [constexpr]
```

L5 [Hz].

Definition at line 32 of file [GPS_L5.h](#).

10.2.6.5.603 GPS_L5_HISTORY_DEEP

```
int32_t GPS_L5_HISTORY_DEEP = 5 [constexpr]
```

Definition at line 43 of file [GPS_L5.h](#).

10.2.6.5.604 GPS_L5_OPT_ACQ_FS_SPS

```
uint32_t GPS_L5_OPT_ACQ_FS_SPS = 10000000 [constexpr]
```

Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.

Definition at line 46 of file [GPS_L5.h](#).

10.2.6.5.605 GPS_L5_SAMPLES_PER_SYMBOL

```
int32_t GPS_L5_SAMPLES_PER_SYMBOL = 10 [constexpr]
```

Definition at line 164 of file [GPS_L5.h](#).

10.2.6.5.606 GPS_L5_SYMBOLS_PER_BIT

```
int32_t GPS_L5_SYMBOLS_PER_BIT = 2 [constexpr]
```

Definition at line 163 of file [GPS_L5.h](#).

10.2.6.5.607 GPS_L5I_CODE_LENGTH_CHIPS

```
int32_t GPS_L5I_CODE_LENGTH_CHIPS = 10230 [constexpr]
```

GPS L5I code length [chips].

Definition at line 39 of file [GPS_L5.h](#).

10.2.6.5.608 GPS_L5I_CODE_RATE_CPS

```
double GPS_L5I_CODE_RATE_CPS = 10.23e6 [constexpr]
```

GPS L5I code rate [chips/s].

Definition at line 33 of file [GPS_L5.h](#).

10.2.6.5.609 GPS_L5I_INIT_REG

```
int32_t GPS_L5I_INIT_REG[210] [constexpr]
```

Definition at line 48 of file [GPS_L5.h](#).

10.2.6.5.610 GPS_L5I_NH_CODE

```
int32_t GPS_L5I_NH_CODE[10] = {0, 0, 0, 0, 1, 1, 0, 1, 0, 1} [constexpr]
```

Definition at line 168 of file [GPS_L5.h](#).

10.2.6.5.611 GPS_L5I_NH_CODE_LENGTH

```
int32_t GPS_L5I_NH_CODE_LENGTH = 10 [constexpr]
```

Definition at line 167 of file [GPS_L5.h](#).

10.2.6.5.612 GPS_L5I_NH_CODE_STR

```
char GPS_L5I_NH_CODE_STR[11] = "0000110101" [constexpr]
```

Definition at line 171 of file [GPS_L5.h](#).

10.2.6.5.613 GPS_L5I_PERIOD_MS

```
int32_t GPS_L5I_PERIOD_MS = 1 [constexpr]
```

GPS L5I code period [ms].

Definition at line 40 of file [GPS_L5.h](#).

10.2.6.5.614 GPS_L5I_PERIOD_S

```
double GPS_L5I_PERIOD_S = 0.001 [constexpr]
```

GPS L5I code period [seconds].

Definition at line 34 of file [GPS_L5.h](#).

10.2.6.5.615 GPS_L5I_SYMBOL_PERIOD_MS

```
int32_t GPS_L5I_SYMBOL_PERIOD_MS = 10 [constexpr]
```

GPS L5I symbol period [ms].

Definition at line 41 of file [GPS_L5.h](#).

10.2.6.5.616 GPS_L5I_SYMBOL_PERIOD_S

```
double GPS_L5I_SYMBOL_PERIOD_S = 0.01 [constexpr]
```

GPS L5I symbol period [seconds].

Definition at line 35 of file [GPS_L5.h](#).

10.2.6.5.617 GPS_L5Q_CODE_LENGTH_CHIPS

```
int32_t GPS_L5Q_CODE_LENGTH_CHIPS = 10230 [constexpr]
```

GPS L5Q code length [chips].

Definition at line 38 of file [GPS_L5.h](#).

10.2.6.5.618 GPS_L5Q_CODE_RATE_CPS

```
double GPS_L5Q_CODE_RATE_CPS = 10.23e6 [constexpr]
```

GPS L5Q code rate [chips/s].

Definition at line 36 of file [GPS_L5.h](#).

10.2.6.5.619 GPS_L5Q_INIT_REG

```
int32_t GPS_L5Q_INIT_REG[210] [constexpr]
```

Definition at line 105 of file [GPS_L5.h](#).

10.2.6.5.620 GPS_L5Q_NH_CODE

```
int32_t GPS_L5Q_NH_CODE[20] = {0, 0, 0, 0, 0, 1, 0, 0, 1, 1, 0, 1, 0, 1, 0, 0, 1, 1, 1, 0}  
[constexpr]
```

Definition at line 170 of file [GPS_L5.h](#).

10.2.6.5.621 GPS_L5Q_NH_CODE_LENGTH

```
int32_t GPS_L5Q_NH_CODE_LENGTH = 20 [constexpr]
```

Definition at line 169 of file [GPS_L5.h](#).

10.2.6.5.622 GPS_L5Q_NH_CODE_STR

```
char GPS_L5Q_NH_CODE_STR[21] = "00000100110101001110" [constexpr]
```

Definition at line 172 of file [GPS_L5.h](#).

10.2.6.5.623 GPS_L5Q_PERIOD_S

```
double GPS_L5Q_PERIOD_S = 0.001 [constexpr]
```

GPS L5Q code period [seconds].

Definition at line 37 of file [GPS_L5.h](#).

10.2.6.5.624 GPS_SUBFRAME_BITS

```
int32_t GPS_SUBFRAME_BITS = 300 [constexpr]
```

Number of bits per subframe in the NAV message [bits].

Definition at line 68 of file [GPS_L1_CA.h](#).

10.2.6.5.625 GPS_SUBFRAME_LENGTH

```
int32_t GPS_SUBFRAME_LENGTH = 40 [constexpr]
```

GPS_WORD_LENGTH x 10 = 40 bytes.

Definition at line 67 of file [GPS_L1_CA.h](#).

10.2.6.5.626 GPS_SUBFRAME_MS

```
int32_t GPS_SUBFRAME_MS = 6000 [constexpr]
```

Subframe duration [seconds].

Definition at line 70 of file [GPS_L1_CA.h](#).

10.2.6.5.627 GPS_SUBFRAME_SECONDS

```
int32_t GPS_SUBFRAME_SECONDS = 6 [constexpr]
```

Subframe duration [seconds].

Definition at line 69 of file [GPS_L1_CA.h](#).

10.2.6.5.628 GPS_WORD_BITS

```
int32_t GPS_WORD_BITS = 30 [constexpr]
```

Number of bits per word in the NAV message [bits].
Definition at line 71 of file [GPS_L1_CA.h](#).

10.2.6.5.629 GPS_WORD_LENGTH

```
int32_t GPS_WORD_LENGTH = 4 [constexpr]
```

CRC + GPS WORD (-2 -1 0 ... 29) Bits = 4 bytes.
Definition at line 66 of file [GPS_L1_CA.h](#).

10.2.6.5.630 HALF_PI

```
double HALF_PI = GNSS_PI / 2.0 [constexpr]
```

$\pi/2$
Definition at line 48 of file [MATH_CONSTANTS.h](#).

10.2.6.5.631 HAS_MSG_CODE_BIAS_LENGTH

```
size_t HAS_MSG_CODE_BIAS_LENGTH = 11 [constexpr]
```

Definition at line 53 of file [Galileo_CNAV.h](#).

10.2.6.5.632 HAS_MSG_CODE_BIAS_SCALE_FACTOR

```
float HAS_MSG_CODE_BIAS_SCALE_FACTOR = 0.02 [constexpr]
```

Definition at line 90 of file [Galileo_CNAV.h](#).

10.2.6.5.633 HAS_MSG_DELTA_CLOCK_CORRECTION_LENGTH

```
size_t HAS_MSG_DELTA_CLOCK_CORRECTION_LENGTH = 13 [constexpr]
```

Definition at line 48 of file [Galileo_CNAV.h](#).

10.2.6.5.634 HAS_MSG_DELTA_CLOCK_CORRECTION_SUBSET_LENGTH

```
size_t HAS_MSG_DELTA_CLOCK_CORRECTION_SUBSET_LENGTH = 13 [constexpr]
```

Definition at line 52 of file [Galileo_CNAV.h](#).

10.2.6.5.635 HAS_MSG_DELTA_CLOCK_MULTIPLIER_LENGTH

```
size_t HAS_MSG_DELTA_CLOCK_MULTIPLIER_LENGTH = 2 [constexpr]
```

Definition at line 47 of file [Galileo_CNAV.h](#).

10.2.6.5.636 HAS_MSG_DELTA_CLOCK_MULTIPLIER_SUBSET_LENGTH

```
size_t HAS_MSG_DELTA_CLOCK_MULTIPLIER_SUBSET_LENGTH = 2 [constexpr]
```

Definition at line 51 of file [Galileo_CNAV.h](#).

10.2.6.5.637 HAS_MSG_DELTA_CLOCK_SCALE_FACTOR

```
float HAS_MSG_DELTA_CLOCK_SCALE_FACTOR = 0.0025 [constexpr]
```

Definition at line 89 of file [Galileo_CNAV.h](#).

10.2.6.5.638 HAS_MSG_DELTA_CROSS_TRACK_LENGTH

```
size_t HAS_MSG_DELTA_CROSS_TRACK_LENGTH = 12 [constexpr]
```

Definition at line 46 of file [Galileo_CNAV.h](#).

10.2.6.5.639 HAS_MSG_DELTA_CROSS_TRACK_SCALE_FACTOR

float HAS_MSG_DELTA_CROSS_TRACK_SCALE_FACTOR = 0.008 [constexpr]
Definition at line 88 of file [Galileo_CNAV.h](#).

10.2.6.5.640 HAS_MSG_DELTA_IN_TRACK_LENGTH

size_t HAS_MSG_DELTA_IN_TRACK_LENGTH = 12 [constexpr]
Definition at line 45 of file [Galileo_CNAV.h](#).

10.2.6.5.641 HAS_MSG_DELTA_IN_TRACK_SCALE_FACTOR

float HAS_MSG_DELTA_IN_TRACK_SCALE_FACTOR = 0.008 [constexpr]
Definition at line 87 of file [Galileo_CNAV.h](#).

10.2.6.5.642 HAS_MSG_DELTA_RADIAL_LENGTH

size_t HAS_MSG_DELTA_RADIAL_LENGTH = 13 [constexpr]
Definition at line 44 of file [Galileo_CNAV.h](#).

10.2.6.5.643 HAS_MSG_DELTA_RADIAL_SCALE_FACTOR

float HAS_MSG_DELTA_RADIAL_SCALE_FACTOR = 0.0025 [constexpr]
Definition at line 86 of file [Galileo_CNAV.h](#).

10.2.6.5.644 HAS_MSG_GALILEO_SYSTEM

uint8_t HAS_MSG_GALILEO_SYSTEM = 2 [constexpr]
Definition at line 96 of file [Galileo_CNAV.h](#).

10.2.6.5.645 HAS_MSG_GPS_SYSTEM

uint8_t HAS_MSG_GPS_SYSTEM = 0 [constexpr]
Definition at line 95 of file [Galileo_CNAV.h](#).

10.2.6.5.646 HAS_MSG_ID_CLOCK_SUBSET_LENGTH

size_t HAS_MSG_ID_CLOCK_SUBSET_LENGTH = 4 [constexpr]
Definition at line 50 of file [Galileo_CNAV.h](#).

10.2.6.5.647 HAS_MSG_ID_MASK_LENGTH

size_t HAS_MSG_ID_MASK_LENGTH = 4 [constexpr]
Definition at line 36 of file [Galileo_CNAV.h](#).

10.2.6.5.648 HAS_MSG_IOD_GAL_LENGTH

size_t HAS_MSG_IOD_GAL_LENGTH = 10 [constexpr]
Definition at line 43 of file [Galileo_CNAV.h](#).

10.2.6.5.649 HAS_MSG_IOD_GPS_LENGTH

size_t HAS_MSG_IOD_GPS_LENGTH = 8 [constexpr]
Definition at line 42 of file [Galileo_CNAV.h](#).

10.2.6.5.650 HAS_MSG_MASK_RESERVED_LENGTH

size_t HAS_MSG_MASK_RESERVED_LENGTH = 6 [constexpr]
Definition at line 40 of file [Galileo_CNAV.h](#).

10.2.6.5.651 HAS_MSG_NAV_MESSAGE_LENGTH

size_t HAS_MSG_NAV_MESSAGE_LENGTH = 3 [constexpr]
Definition at line 39 of file [Galileo_CNAV.h](#).

10.2.6.5.652 HAS_MSG_NSYS_LENGTH

size_t HAS_MSG_NSYS_LENGTH = 4 [constexpr]
Definition at line 35 of file [Galileo_CNAV.h](#).

10.2.6.5.653 HAS_MSG_NSYS_SUB_LENGTH

size_t HAS_MSG_NSYS_SUB_LENGTH = 4 [constexpr]
Definition at line 49 of file [Galileo_CNAV.h](#).

10.2.6.5.654 HAS_MSG_NUMBER_GNSS_IDS

int32_t HAS_MSG_NUMBER_GNSS_IDS = 16 [constexpr]
Definition at line 81 of file [Galileo_CNAV.h](#).

10.2.6.5.655 HAS_MSG_NUMBER_MASK_IDS

int32_t HAS_MSG_NUMBER_MASK_IDS = 32 [constexpr]
Definition at line 80 of file [Galileo_CNAV.h](#).

10.2.6.5.656 HAS_MSG_NUMBER_MAX_TOH

uint16_t HAS_MSG_NUMBER_MAX_TOH = 3599 [constexpr]
Definition at line 93 of file [Galileo_CNAV.h](#).

10.2.6.5.657 HAS_MSG_NUMBER_MESSAGE_IDS

int32_t HAS_MSG_NUMBER_MESSAGE_IDS = 32 [constexpr]
Definition at line 82 of file [Galileo_CNAV.h](#).

10.2.6.5.658 HAS_MSG_NUMBER_SATELLITE_IDS

int32_t HAS_MSG_NUMBER_SATELLITE_IDS = 40 [constexpr]
Definition at line 83 of file [Galileo_CNAV.h](#).

10.2.6.5.659 HAS_MSG_NUMBER_SIGNAL_MASKS

int32_t HAS_MSG_NUMBER_SIGNAL_MASKS = 16 [constexpr]
Definition at line 84 of file [Galileo_CNAV.h](#).

10.2.6.5.660 HAS_MSG_PHASE_BIAS_LENGTH

size_t HAS_MSG_PHASE_BIAS_LENGTH = 11 [constexpr]
Definition at line 54 of file [Galileo_CNAV.h](#).

10.2.6.5.661 HAS_MSG_PHASE_BIAS_SCALE_FACTOR

float HAS_MSG_PHASE_BIAS_SCALE_FACTOR = 0.01 [constexpr]
Definition at line 91 of file [Galileo_CNAV.h](#).

10.2.6.5.662 HAS_MSG_PHASE_DISCONTINUITY_INDICATOR_LENGTH

size_t HAS_MSG_PHASE_DISCONTINUITY_INDICATOR_LENGTH = 2 [constexpr]
Definition at line 55 of file [Galileo_CNAV.h](#).

10.2.6.5.663 HAS_MSG_SATELLITE_MASK_LENGTH

`size_t HAS_MSG_SATELLITE_MASK_LENGTH = 40 [constexpr]`
 Definition at line 37 of file [Galileo_CNAV.h](#).

10.2.6.5.664 HAS_MSG_SIGNAL_MASK_LENGTH

`size_t HAS_MSG_SIGNAL_MASK_LENGTH = 16 [constexpr]`
 Definition at line 38 of file [Galileo_CNAV.h](#).

10.2.6.5.665 HAS_MSG_VALIDITY_INDEX_LENGTH

`size_t HAS_MSG_VALIDITY_INDEX_LENGTH = 4 [constexpr]`
 Definition at line 41 of file [Galileo_CNAV.h](#).

10.2.6.5.666 HAS_MSG_WRONG_SYSTEM

`uint8_t HAS_MSG_WRONG_SYSTEM = 255 [constexpr]`
 Definition at line 97 of file [Galileo_CNAV.h](#).

10.2.6.5.667 HAS_SIGNAL_INDEX_TABLE

`const std::unordered_map<uint8_t, std::unordered_map<uint8_t, std::string> > HAS_SIGNAL_INDEX_TABLE`
 Definition at line 122 of file [Galileo_CNAV.h](#).

10.2.6.5.668 HAS_VALIDITY_INTERVALS

`const std::unordered_map<uint8_t, uint16_t> HAS_VALIDITY_INTERVALS`

Initial value:

```
= {
    {0, 5},
    {1, 10},
    {2, 15},
    {3, 20},
    {4, 30},
    {5, 60},
    {6, 90},
    {7, 120},
    {8, 180},
    {9, 240},
    {10, 300},
    {11, 600},
    {12, 900},
    {13, 1800},
    {14, 3600}}
```

Definition at line 161 of file [Galileo_CNAV.h](#).

10.2.6.5.669 I_0_2_LSB

`double I_0_2_LSB = PI_TWO_N31 [constexpr]`
 Definition at line 72 of file [Galileo_INAV.h](#).

10.2.6.5.670 I_0_LSB

`double I_0_LSB = PI_TWO_N31 [constexpr]`
 Definition at line 134 of file [GPS_L1_CA.h](#).

10.2.6.5.671 I_DOT_2_LSB

`double I_DOT_2_LSB = PI_TWO_N43 [constexpr]`
 Definition at line 76 of file [Galileo_INAV.h](#).

10.2.6.5.672 I_DOT_LSB

double I_DOT_LSB = [PI_TWO_N43](#) [constexpr]
Definition at line [143](#) of file [GPS_L1_CA.h](#).

10.2.6.5.673 INAV_RS_BUFFER_LENGTH

size_t INAV_RS_BUFFER_LENGTH = 118 [constexpr]
Definition at line [272](#) of file [Galileo_INAV.h](#).

10.2.6.5.674 INAV_RS_INFO_VECTOR_LENGTH

size_t INAV_RS_INFO_VECTOR_LENGTH = 58 [constexpr]
Definition at line [271](#) of file [Galileo_INAV.h](#).

10.2.6.5.675 INAV_RS_PARITY_VECTOR_LENGTH

size_t INAV_RS_PARITY_VECTOR_LENGTH = 60 [constexpr]
Definition at line [270](#) of file [Galileo_INAV.h](#).

10.2.6.5.676 INAV_RS_SUBVECTOR_LENGTH

size_t INAV_RS_SUBVECTOR_LENGTH = 15 [constexpr]
Definition at line [269](#) of file [Galileo_INAV.h](#).

10.2.6.5.677 M0_10_LSB

double M0_10_LSB = [TWO_N15](#) [constexpr]
Definition at line [234](#) of file [Galileo_INAV.h](#).

10.2.6.5.678 M0_1_LSB

double M0_1_LSB = [PI_TWO_N31](#) [constexpr]
Definition at line [59](#) of file [Galileo_INAV.h](#).

10.2.6.5.679 M0_7_LSB

double M0_7_LSB = [TWO_N15](#) [constexpr]
Definition at line [177](#) of file [Galileo_INAV.h](#).

10.2.6.5.680 M0_9_LSB

double M0_9_LSB = [TWO_N15](#) [constexpr]
Definition at line [209](#) of file [Galileo_INAV.h](#).

10.2.6.5.681 M_0_LSB

double M_0_LSB = [PI_TWO_N31](#) [constexpr]
Definition at line [111](#) of file [GPS_L1_CA.h](#).

10.2.6.5.682 MAX_SECONDS_REMEMBERING_MID

uint64_t MAX_SECONDS_REMEMBERING_MID = 150 [constexpr]
Definition at line [57](#) of file [Galileo_CNAV.h](#).

10.2.6.5.683 MAX_TOA_DELAY_MS

```
double MAX_TOA_DELAY_MS = 20.0 [constexpr]
```

Maximum Time-Of-Arrival (TOA) difference between satellites for a receiver operated on Earth surface is 20 ms. According to the GPS orbit model described in [1] Pag. 32. It should be taken into account to set the buffer size for the PRN start timestamp in the pseudoranges block. [1] J. Bao-Yen Tsui, Fundamentals of Global Positioning System Receivers. A Software Approach, John Wiley & Sons, Inc., Hoboken, NJ, 2nd edition, 2005. Definition at line 50 of file [GPS_L1_CA.h](#).

10.2.6.5.684 MAXCODE

```
int32_t MAXCODE = 55 [constexpr]
```

max number of obs code

Definition at line 86 of file [gnss_obs_codes.h](#).

10.2.6.5.685 OMEGA0_10_LSB

```
double OMEGA0_10_LSB = TWO_N15 [constexpr]
```

Definition at line 230 of file [Galileo_INAV.h](#).

10.2.6.5.686 OMEGA0_7_LSB

```
double OMEGA0_7_LSB = TWO_N15 [constexpr]
```

Definition at line 173 of file [Galileo_INAV.h](#).

10.2.6.5.687 OMEGA0_8_LSB

```
double OMEGA0_8_LSB = TWO_N15 [constexpr]
```

Definition at line 198 of file [Galileo_INAV.h](#).

10.2.6.5.688 OMEGA_0_2_LSB

```
double OMEGA_0_2_LSB = PI_TWO_N31 [constexpr]
```

Definition at line 70 of file [Galileo_INAV.h](#).

10.2.6.5.689 OMEGA_0_LSB

```
double OMEGA_0_LSB = PI_TWO_N31 [constexpr]
```

Definition at line 130 of file [GPS_L1_CA.h](#).

10.2.6.5.690 OMEGA_2_LSB

```
double OMEGA_2_LSB = PI_TWO_N31 [constexpr]
```

Definition at line 74 of file [Galileo_INAV.h](#).

10.2.6.5.691 OMEGA_7_LSB

```
double OMEGA_7_LSB = TWO_N15 [constexpr]
```

Definition at line 169 of file [Galileo_INAV.h](#).

10.2.6.5.692 OMEGA_8_LSB

```
double OMEGA_8_LSB = TWO_N15 [constexpr]
```

Definition at line 194 of file [Galileo_INAV.h](#).

10.2.6.5.693 OMEGA_9_LSB

```
double OMEGA_9_LSB = TWO_N15 [constexpr]
```

Definition at line 222 of file [Galileo_INAV.h](#).

10.2.6.5.694 OMEGA_DOT_10_LSB

double OMEGA_DOT_10_LSB = TWO_N33 [constexpr]
 Definition at line 232 of file [Galileo_INAV.h](#).

10.2.6.5.695 OMEGA_DOT_3_LSB

double OMEGA_DOT_3_LSB = PI_TWO_N43 [constexpr]
 Definition at line 82 of file [Galileo_INAV.h](#).

10.2.6.5.696 OMEGA_DOT_7_LSB

double OMEGA_DOT_7_LSB = TWO_N33 [constexpr]
 Definition at line 175 of file [Galileo_INAV.h](#).

10.2.6.5.697 OMEGA_DOT_8_LSB

double OMEGA_DOT_8_LSB = TWO_N33 [constexpr]
 Definition at line 200 of file [Galileo_INAV.h](#).

10.2.6.5.698 OMEGA_DOT_LSB

double OMEGA_DOT_LSB = PI_TWO_N43 [constexpr]
 Definition at line 140 of file [GPS_L1_CA.h](#).

10.2.6.5.699 OMEGA_LSB

double OMEGA_LSB = PI_TWO_N31 [constexpr]
 Definition at line 138 of file [GPS_L1_CA.h](#).

10.2.6.5.700 OSNMA_TABLE_1

const std::unordered_map<uint8_t, std::string> OSNMA_TABLE_1

Initial value:

```
= {
    {0, std::string("Reserved")},
    {1, std::string("Test")},
    {2, std::string("Operational")},
    {3, std::string("Don't use")}
```

Definition at line 36 of file [Galileo_OSNMA.h](#).

10.2.6.5.701 OSNMA_TABLE_10

const std::unordered_map<uint8_t, uint16_t> OSNMA_TABLE_10

Initial value:

```
= {
    {0, 96},
    {1, 104},
    {2, 112},
    {3, 120},
    {4, 128},
    {5, 160},
    {6, 192},
    {7, 224},
    {8, 256},
    {9, 0},
    {10, 0},
    {11, 0},
    {12, 0},
    {13, 0},
    {15, 0},
    {15, 0}}
```

Definition at line 120 of file [Galileo_OSNMA.h](#).

10.2.6.5.702 OSNMA_TABLE_11

```
const std::unordered_map<uint8_t, uint8_t> OSNMA_TABLE_11
```

Initial value:

```
= {
    {0, 0},
    {1, 0},
    {2, 0},
    {3, 0},
    {4, 0},
    {5, 20},
    {6, 24},
    {7, 28},
    {8, 32},
    {9, 40},
    {10, 0},
    {11, 0},
    {12, 0},
    {13, 0},
    {14, 0},
    {15, 0},
}
```

Definition at line 138 of file [Galileo_OSNMA.h](#).**10.2.6.5.703 OSNMA_TABLE_15**

```
const std::unordered_map<std::string, uint16_t> OSNMA_TABLE_15
```

Initial value:

```
= {
    {std::string("ECDSA P-256"), 512},
    {std::string("ECDSA P-521"), 1056}}

```

Definition at line 157 of file [Galileo_OSNMA.h](#).**10.2.6.5.704 OSNMA_TABLE_16**

```
const std::unordered_map<uint8_t, Mack_lookup> OSNMA_TABLE_16
```

Initial value:

```
= {
    {27, {2, 6, {"00S", "00E", "00E", "00E", "12S", "00E"}, {"00S ", "00E", "00E", "04S", "12S", "00E"}}},
    {28, {2, 10, {"00S", "00E", "00E", "00E", "00S", "00E", "00E", "12S", "00E", "00E"}, {"00S", "00E", "00E", "00S", "00E", "04S", "12S", "00E", "00E"}}},
    {31, {2, 5, {"00S", "00E", "00E", "12S", "00E"}, {"00S", "00E", "12S", "04S"}}},
    {33, {2, 6, {"00S", "00E", "04S", "00E", "12S", "00E"}, {"00S", "00E", "00E", "12S", "00E", "12E"}}},
    {34, {2, 6, {"00S", "FLX", "04S", "FLX", "12S", "00E"}, {"00S", "FLX", "00E", "12S", "00E", "12E"}}},
    {35, {2, 6, {"00S", "FLX", "04S", "FLX", "12S", "FLX"}, {"00S", "FLX", "FLX", "12S", "FLX", "FLX"}}},
    {36, {2, 5, {"00S", "FLX", "04S", "FLX", "12S"}, {"00S", "FLX", "00E", "12S", "12E"}}},
    {37, {2, 5, {"00S", "00E", "04S", "00E", "12S"}, {"00S", "00E", "00E", "12S", "12E"}}},
    {38, {2, 5, {"00S", "FLX", "04S", "FLX", "12S"}, {"00S", "FLX", "FLX", "12S", "FLX"}}},
    {39, {2, 4, {"00S", "FLX", "04S", "FLX"}, {"00S", "FLX", "00E", "12S"}}},
    {40, {2, 4, {"00S", "00E", "04S", "12S"}, {"00S", "00E", "00E", "12E"}}},
    {41, {2, 4, {"00S", "FLX", "04S", "FLX"}, {"00S", "FLX", "FLX", "12S"}}}
}
```

Definition at line 183 of file [Galileo_OSNMA.h](#).**10.2.6.5.705 OSNMA_TABLE_2**

```
const std::unordered_map<uint8_t, std::string> OSNMA_TABLE_2
```

Initial value:

```
= {
    {0, std::string("Reserved")},
    {1, std::string("Nominal")},
    {2, std::string("End of Chain (EOC)")},
    {3, std::string("Chain Revoked (CREV)")},
    {4, std::string("New Public Key (NPK)")},
    {5, std::string("Public Key Revoked (PKREV)")},
    {6, std::string("New Merkle Tree (NMT)")},
    {7, std::string("Alert Message (AM)")}
}
```

Definition at line 44 of file [Galileo_OSNMA.h](#).**10.2.6.5.706 OSNMA_TABLE_3**

```
const std::unordered_map<uint8_t, std::pair<uint16_t, uint16_t> > OSNMA_TABLE_3
```

Initial value:

```
= {
```

```

{0, {0, 0}},
{1, {0, 0}},
{2, {0, 0}},
{3, {0, 0}},
{4, {0, 0}},
{5, {0, 0}},
{6, {0, 0}},
{7, {13, 1352}},
{8, {14, 1456}},
{9, {15, 1560}},
{10, {16, 1664}},
{11, {0, 0}},
{12, {0, 0}},
{13, {0, 0}},
{14, {0, 0}},
{15, {0, 0}}

```

Definition at line 55 of file [Galileo_OSNMA.h](#).

10.2.6.5.707 OSNMA_TABLE_5

```
const std::unordered_map<uint8_t, std::string> OSNMA_TABLE_5
```

Initial value:

```

= {
    {0, std::string("Reserved")},
    {1, std::string("ECDSA P-256")},
    {2, std::string("Reserved")},
    {3, std::string("ECDSA P-521")},
    {4, std::string("OAM")},
    {5, std::string("Reserved")},
    {6, std::string("Reserved")},
    {7, std::string("Reserved")},
    {8, std::string("Reserved")},
    {9, std::string("Reserved")},
    {10, std::string("Reserved")},
    {11, std::string("Reserved")},
    {12, std::string("Reserved")},
    {13, std::string("Reserved")},
    {14, std::string("Reserved")},
    {15, std::string("Reserved")}
}

```

Definition at line 73 of file [Galileo_OSNMA.h](#).

10.2.6.5.708 OSNMA_TABLE_6

```
const std::unordered_map<std::string, uint16_t> OSNMA_TABLE_6
```

Initial value:

```

= {
    {std::string("ECDSA P-256"), 264},
    {std::string("ECDSA P-521"), 536}
}

```

Definition at line 91 of file [Galileo_OSNMA.h](#).

10.2.6.5.709 OSNMA_TABLE_7

```
const std::unordered_map<uint8_t, std::pair<uint16_t, uint16_t> > OSNMA_TABLE_7
```

Initial value:

```

= {
    {0, {0, 0}},
    {1, {7, 728}},
    {2, {8, 832}},
    {3, {9, 936}},
    {4, {10, 1040}},
    {5, {11, 1144}},
    {6, {12, 1248}},
    {7, {13, 1352}},
    {8, {14, 1456}},
    {9, {0, 0}},
    {10, {0, 0}},
    {11, {0, 0}},
    {12, {0, 0}},
    {13, {0, 0}},
    {14, {0, 0}},
    {15, {0, 0}}
}

```

Definition at line 96 of file [Galileo_OSNMA.h](#).

Definition at line 114 of file Galileo_OSNMA.h.

Definition at line 117 of file MATH_CONSTANTS.h.

Definition at line 121 of file MATH_CONSTANTS.h.

Definition at line 119 of file MATH_CONSTANTS.h.

Definition at line 120 of file MATH_CONSTANTS.h.

Definition at line 118 of file MATH_CONSTANTS.h.

Definition at line 51 of file qzss.h.

```
const char QZSS_L5I_NH_CODE_STR[11] = "0000110101"  [constexpr]
```

Definition at line 53 of file [qzss.h](#).

```
const char QZSS_L5Q_NH_CODE_STR[21] = "00000100110101001110" [constexpr]
Definition at line 52 of file qzss.h.
```

```
double R2D = 180.0 / GNSS_PI [constexpr]
rad to deg
Definition at line 124 of file MATH CONSTANTS.h.
```

10.2.6.5.720 SC2RAD

double SC2RAD = GNSS_PI [constexpr]
 semi-circle to radian (IS-GPS)
 Definition at line 125 of file [MATH_CONSTANTS.h](#).

10.2.6.5.721 SIGNAL_FREQ_MAP

const std::unordered_map<std::string, double> SIGNAL_FREQ_MAP
 Initial value:

```
= {
    {"1C", FREQ1},
    {"2S", FREQ2},
    {"L5", FREQ5},
    {"1B", FREQ1},
    {"5X", FREQ5},
    {"E6", FREQ6},
    {"7X", FREQ7},
    {"1G", FREQ1_GLO},
    {"2G", FREQ2_GLO},
    {"B1", FREQ1_BDS},
    {"B2", FREQ2_BDS},
    {"B3", FREQ3_BDS},
    {"J1", FREQ1},
    {"J5", FREQ5},
}
```

Definition at line 47 of file [gnss_frequencies.h](#).

10.2.6.5.722 SIZE_DSM_BLOCKS_BYTES

size_t SIZE_DSM_BLOCKS_BYTES = 13 [constexpr]
 Definition at line 33 of file [Galileo_OSNMA.h](#).

10.2.6.5.723 SPEED_OF_LIGHT_M_MS

double SPEED_OF_LIGHT_M_MS = 299792.4580 [constexpr]
 Speed of light in vacuum [m/ms].
 Definition at line 28 of file [MATH_CONSTANTS.h](#).

10.2.6.5.724 SPEED_OF_LIGHT_M_S

double SPEED_OF_LIGHT_M_S = 299792458.0 [constexpr]
 Speed of light in vacuum [m/s].
 Definition at line 27 of file [MATH_CONSTANTS.h](#).

10.2.6.5.725 SQRT_A_LSB

double SQRT_A_LSB = TWO_N19 [constexpr]
 Definition at line 119 of file [GPS_L1_CA.h](#).

10.2.6.5.726 T0A_7_LSB

int32_t T0A_7_LSB = 600 [constexpr]
 Definition at line 162 of file [Galileo_INAV.h](#).

10.2.6.5.727 T0A_9_LSB

int32_t T0A_9_LSB = 600 [constexpr]
 Definition at line 207 of file [Galileo_INAV.h](#).

10.2.6.5.728 T0C_4_LSB

int32_t T0C_4_LSB = 60 [constexpr]
 Definition at line 104 of file [Galileo_INAV.h](#).

10.2.6.5.729 T0E_1_LSB

```
int32_t T0E_1_LSB = 60 [constexpr]
```

Definition at line 57 of file [Galileo_INAV.h](#).

10.2.6.5.730 T0T_6_LSB

```
int32_t T0T_6_LSB = 3600 [constexpr]
```

Definition at line 150 of file [Galileo_INAV.h](#).

10.2.6.5.731 T_0_G_10_LSB

```
int32_t T_0_G_10_LSB = 3600 [constexpr]
```

Definition at line 246 of file [Galileo_INAV.h](#).

10.2.6.5.732 T_GD_LSB

```
double T_GD_LSB = TWO_N31 [constexpr]
```

Definition at line 93 of file [GPS_L1_CA.h](#).

10.2.6.5.733 T_OA_LSB

```
int32_t T_OA_LSB = TWO_P12 [constexpr]
```

Definition at line 201 of file [GPS_L1_CA.h](#).

10.2.6.5.734 T_OC_LSB

```
int32_t T_OC_LSB = static_cast<int32_t>(TWO_P4) [constexpr]
```

Definition at line 96 of file [GPS_L1_CA.h](#).

10.2.6.5.735 T_OE_LSB

```
int32_t T_OE_LSB = static_cast<int32_t>(TWO_P4) [constexpr]
```

Definition at line 121 of file [GPS_L1_CA.h](#).

10.2.6.5.736 T_OT_LSB

```
double T_OT_LSB = TWO_P12 [constexpr]
```

Definition at line 173 of file [GPS_L1_CA.h](#).

10.2.6.5.737 TEXT_BLACK

```
const std::string TEXT_BLACK = "\033[30m"
```

Definition at line 36 of file [display.h](#).

10.2.6.5.738 TEXT_BLUE

```
const std::string TEXT_BLUE = "\033[34m"
```

Definition at line 40 of file [display.h](#).

10.2.6.5.739 TEXT_BOLD_BLACK

```
const std::string TEXT_BOLD_BLACK = "\033[1m\033[30m"
```

Definition at line 44 of file [display.h](#).

10.2.6.5.740 TEXT_BOLD_BLUE

```
const std::string TEXT_BOLD_BLUE = "\033[1m\033[34m"
```

Definition at line 48 of file [display.h](#).

10.2.6.5.741 TEXT_BOLD_CYAN

```
const std::string TEXT_BOLD_CYAN = "\033[1m\033[36m"
```

Definition at line 50 of file [display.h](#).

10.2.6.5.742 TEXT_BOLD_GREEN

```
const std::string TEXT_BOLD_GREEN = "\033[1m\033[32m"
```

Definition at line 46 of file [display.h](#).

10.2.6.5.743 TEXT_BOLD_MAGENTA

```
const std::string TEXT_BOLD_MAGENTA = "\033[1m\033[35m"
```

Definition at line 49 of file [display.h](#).

10.2.6.5.744 TEXT_BOLD_RED

```
const std::string TEXT_BOLD_RED = "\033[1m\033[31m"
```

Definition at line 45 of file [display.h](#).

10.2.6.5.745 TEXT_BOLD_WHITE

```
const std::string TEXT_BOLD_WHITE = "\033[1m\033[37m"
```

Definition at line 51 of file [display.h](#).

10.2.6.5.746 TEXT_BOLD_YELLOW

```
const std::string TEXT_BOLD_YELLOW = "\033[1m\033[33m"
```

Definition at line 47 of file [display.h](#).

10.2.6.5.747 TEXT_CYAN

```
const std::string TEXT_CYAN = "\033[36m"
```

Definition at line 42 of file [display.h](#).

10.2.6.5.748 TEXT_GREEN

```
const std::string TEXT_GREEN = "\033[32m"
```

Definition at line 38 of file [display.h](#).

10.2.6.5.749 TEXT_MAGENTA

```
const std::string TEXT_MAGENTA = "\033[35m"
```

Definition at line 41 of file [display.h](#).

10.2.6.5.750 TEXT_RED

```
const std::string TEXT_RED = "\033[31m"
```

Definition at line 37 of file [display.h](#).

10.2.6.5.751 TEXT_RESET

```
const std::string TEXT_RESET = "\033[0m"
```

Definition at line 35 of file [display.h](#).

10.2.6.5.752 TEXT_WHITE

```
const std::string TEXT_WHITE = "\033[37m"
```

Definition at line 43 of file [display.h](#).

10.2.6.5.753 TEXT_YELLOW

```
const std::string TEXT_YELLOW = "\033[33m"
```

Definition at line 39 of file [display.h](#).

10.2.6.5.754 TWO_N10

```
double TWO_N10 = 0.0009765625 [constexpr]  
2^-10
```

Definition at line 77 of file [MATH_CONSTANTS.h](#).

10.2.6.5.755 TWO_N11

```
double TWO_N11 = 4.882812500000000e-004 [constexpr]  
2^-11
```

Definition at line 78 of file [MATH_CONSTANTS.h](#).

10.2.6.5.756 TWO_N14

```
double TWO_N14 = 0.00006103515625 [constexpr]  
2^-14
```

Definition at line 79 of file [MATH_CONSTANTS.h](#).

10.2.6.5.757 TWO_N15

```
double TWO_N15 = 3.051757812500000e-005 [constexpr]  
2^-15
```

Definition at line 80 of file [MATH_CONSTANTS.h](#).

10.2.6.5.758 TWO_N16

```
double TWO_N16 = 1.525878906250000e-005 [constexpr]  
2^-16
```

Definition at line 81 of file [MATH_CONSTANTS.h](#).

10.2.6.5.759 TWO_N17

```
double TWO_N17 = 7.629394531250000e-006 [constexpr]  
2^-17
```

Definition at line 82 of file [MATH_CONSTANTS.h](#).

10.2.6.5.760 TWO_N18

```
double TWO_N18 = 3.814697265625000e-006 [constexpr]  
2^-18
```

Definition at line 83 of file [MATH_CONSTANTS.h](#).

10.2.6.5.761 TWO_N19

```
double TWO_N19 = 1.907348632812500e-006 [constexpr]  
2^-19
```

Definition at line 84 of file [MATH_CONSTANTS.h](#).

10.2.6.5.762 TWO_N2

```
double TWO_N2 = 0.25 [constexpr]  
2^-2
```

Definition at line 72 of file [MATH_CONSTANTS.h](#).

10.2.6.5.763 TWO_N20

```
double TWO_N20 = 9.536743164062500e-007 [constexpr]  
2^-20
```

Definition at line 85 of file [MATH_CONSTANTS.h](#).

10.2.6.5.764 TWO_N21

```
double TWO_N21 = 4.768371582031250e-007 [constexpr]  
2^-21
```

Definition at line 86 of file [MATH_CONSTANTS.h](#).

10.2.6.5.765 TWO_N22

```
double TWO_N22 = 2.384185791015625e-007 [constexpr]  
2^-22
```

Definition at line 87 of file [MATH_CONSTANTS.h](#).

10.2.6.5.766 TWO_N23

```
double TWO_N23 = 1.192092895507810e-007 [constexpr]  
2^-23
```

Definition at line 88 of file [MATH_CONSTANTS.h](#).

10.2.6.5.767 TWO_N24

```
double TWO_N24 = 5.960464477539063e-008 [constexpr]  
2^-24
```

Definition at line 89 of file [MATH_CONSTANTS.h](#).

10.2.6.5.768 TWO_N25

```
double TWO_N25 = 2.980232238769531e-008 [constexpr]  
2^-25
```

Definition at line 90 of file [MATH_CONSTANTS.h](#).

10.2.6.5.769 TWO_N26

```
double TWO_N26 = 1.490116119384765e-009 [constexpr]  
2^-26
```

Definition at line 91 of file [MATH_CONSTANTS.h](#).

10.2.6.5.770 TWO_N27

```
double TWO_N27 = 7.450580596923828e-009 [constexpr]  
2^-27
```

Definition at line 92 of file [MATH_CONSTANTS.h](#).

10.2.6.5.771 TWO_N29

```
double TWO_N29 = 1.862645149230957e-009 [constexpr]  
2^-29
```

Definition at line 93 of file [MATH_CONSTANTS.h](#).

10.2.6.5.772 TWO_N30

```
double TWO_N30 = 9.313225746154785e-010 [constexpr]  
2^-30
```

Definition at line 94 of file [MATH_CONSTANTS.h](#).

10.2.6.5.773 TWO_N31

```
double TWO_N31 = 4.656612873077393e-010 [constexpr]  
2^-31
```

Definition at line 95 of file [MATH_CONSTANTS.h](#).

10.2.6.5.774 TWO_N32

```
double TWO_N32 = 2.328306436538696e-010 [constexpr]  
2^-32
```

Definition at line 96 of file [MATH_CONSTANTS.h](#).

10.2.6.5.775 TWO_N33

```
double TWO_N33 = 1.164153218269348e-010 [constexpr]  
2^-33
```

Definition at line 97 of file [MATH_CONSTANTS.h](#).

10.2.6.5.776 TWO_N34

```
double TWO_N34 = 5.82076609134674e-011 [constexpr]  
2^-34
```

Definition at line 98 of file [MATH_CONSTANTS.h](#).

10.2.6.5.777 TWO_N35

```
double TWO_N35 = 2.91038304567337e-011 [constexpr]  
2^-35
```

Definition at line 99 of file [MATH_CONSTANTS.h](#).

10.2.6.5.778 TWO_N38

```
double TWO_N38 = 3.637978807091713e-012 [constexpr]  
2^-38
```

Definition at line 100 of file [MATH_CONSTANTS.h](#).

10.2.6.5.779 TWO_N39

```
double TWO_N39 = 1.818989403545856e-012 [constexpr]  
2^-39
```

Definition at line 101 of file [MATH_CONSTANTS.h](#).

10.2.6.5.780 TWO_N40

```
double TWO_N40 = 9.094947017729280e-013 [constexpr]  
2^-40
```

Definition at line 102 of file [MATH_CONSTANTS.h](#).

10.2.6.5.781 TWO_N43

```
double TWO_N43 = 1.136868377216160e-013 [constexpr]  
2^-43
```

Definition at line 103 of file [MATH_CONSTANTS.h](#).

10.2.6.5.782 TWO_N44

```
double TWO_N44 = 5.684341886080802e-14 [constexpr]  
2^-44
```

Definition at line 104 of file [MATH_CONSTANTS.h](#).

10.2.6.5.783 TWO_N46

```
double TWO_N46 = 1.4210854715202e-014 [constexpr]  
2^-46
```

Definition at line 105 of file [MATH_CONSTANTS.h](#).

10.2.6.5.784 TWO_N48

```
double TWO_N48 = 3.552713678800501e-15 [constexpr]  
2^-46
```

Definition at line 106 of file [MATH_CONSTANTS.h](#).

10.2.6.5.785 TWO_N5

```
double TWO_N5 = 0.03125 [constexpr]  
2^-5
```

Definition at line 73 of file [MATH_CONSTANTS.h](#).

10.2.6.5.786 TWO_N50

```
double TWO_N50 = 8.881784197001252e-016 [constexpr]  
2^-50
```

Definition at line 108 of file [MATH_CONSTANTS.h](#).

10.2.6.5.787 TWO_N51

```
double TWO_N51 = 4.44089209850063e-016 [constexpr]  
2^-51
```

Definition at line 109 of file [MATH_CONSTANTS.h](#).

10.2.6.5.788 TWO_N55

```
double TWO_N55 = 2.775557561562891e-017 [constexpr]  
2^-55
```

Definition at line 110 of file [MATH_CONSTANTS.h](#).

10.2.6.5.789 TWO_N57

```
double TWO_N57 = 6.938893903907228e-18 [constexpr]  
2^-57
```

Definition at line 111 of file [MATH_CONSTANTS.h](#).

10.2.6.5.790 TWO_N59

```
double TWO_N59 = 1.73472347597681e-018 [constexpr]  
2^-59
```

Definition at line 112 of file [MATH_CONSTANTS.h](#).

10.2.6.5.791 TWO_N6

```
double TWO_N6 = 0.015625 [constexpr]  
2^-6
```

Definition at line 74 of file [MATH_CONSTANTS.h](#).

10.2.6.5.792 TWO_N60

```
double TWO_N60 = 8.673617379884036e-19 [constexpr]  
2^-60
```

Definition at line 113 of file [MATH_CONSTANTS.h](#).

10.2.6.5.793 TWO_N66

```
double TWO_N66 = 1.3552527156068805425093160010874271392822265625e-20 [constexpr]  
2^-66
```

Definition at line 114 of file [MATH_CONSTANTS.h](#).

10.2.6.5.794 TWO_N68

```
double TWO_N68 = 3.388131789017201e-21 [constexpr]  
2^-68
```

Definition at line 115 of file [MATH_CONSTANTS.h](#).

10.2.6.5.795 TWO_N8

```
double TWO_N8 = 0.00390625 [constexpr]  
2^-8
```

Definition at line 75 of file [MATH_CONSTANTS.h](#).

10.2.6.5.796 TWO_N9

```
double TWO_N9 = 0.001953125 [constexpr]  
2^-9
```

Definition at line 76 of file [MATH_CONSTANTS.h](#).

10.2.6.5.797 TWO_P11

```
double TWO_P11 = 2048.0 [constexpr]  
2^11
```

Definition at line 62 of file [MATH_CONSTANTS.h](#).

10.2.6.5.798 TWO_P12

```
double TWO_P12 = 4096.0 [constexpr]  
2^12
```

Definition at line 63 of file [MATH_CONSTANTS.h](#).

10.2.6.5.799 TWO_P14

```
double TWO_P14 = 16384.0 [constexpr]  
2^14
```

Definition at line 64 of file [MATH_CONSTANTS.h](#).

10.2.6.5.800 TWO_P16

```
double TWO_P16 = 65536.0 [constexpr]  
2^16
```

Definition at line 65 of file [MATH_CONSTANTS.h](#).

10.2.6.5.801 TWO_P19

```
double TWO_P19 = 524288.0 [constexpr]  
2^19
```

Definition at line 66 of file [MATH_CONSTANTS.h](#).

10.2.6.5.802 TWO_P3

```
double TWO_P3 = 8.0 [constexpr]  
2^3
```

Definition at line 59 of file [MATH_CONSTANTS.h](#).

10.2.6.5.803 TWO_P31

```
double TWO_P31 = 2147483648.0 [constexpr]  
2^31
```

Definition at line 67 of file [MATH_CONSTANTS.h](#).

10.2.6.5.804 TWO_P32

```
double TWO_P32 = 4294967296.0 [constexpr]  
2^32
```

Definition at line 68 of file [MATH_CONSTANTS.h](#).

10.2.6.5.805 TWO_P4

```
double TWO_P4 = 16.0 [constexpr]  
2^4
```

Definition at line 60 of file [MATH_CONSTANTS.h](#).

10.2.6.5.806 TWO_P56

```
double TWO_P56 = 7.205759403792794e+016 [constexpr]  
2^56
```

Definition at line 69 of file [MATH_CONSTANTS.h](#).

10.2.6.5.807 TWO_P57

```
double TWO_P57 = 1.441151880758559e+017 [constexpr]  
2^57
```

Definition at line 70 of file [MATH_CONSTANTS.h](#).

10.2.6.5.808 TWO_P8

```
double TWO_P8 = 256.0 [constexpr]  
2^8
```

Definition at line 61 of file [MATH_CONSTANTS.h](#).

10.2.6.5.809 TWO_PI

```
double TWO_PI = 2.0 * GNSS_PI [constexpr]  
2 * pi
```

Definition at line 49 of file [MATH_CONSTANTS.h](#).

10.2.6.5.810 WN_LSF_LSB

```
double WN_LSF_LSB = 1 [constexpr]
```

Definition at line 179 of file [GPS_L1_CA.h](#).

10.2.6.5.811 WN_T_LSB

```
double WN_T_LSB = 1 [constexpr]
```

Definition at line 175 of file [GPS_L1_CA.h](#).

10.3 Channel

Topics

- [channel_adapters](#)
- [channel_libs](#)

10.3.1 Detailed Description

Classes containing a GNSS channel.

10.3.2 channel_adapters

Classes

- class [Channel](#)

This class represents a GNSS channel. It wraps an [AcquisitionInterface](#), a [TrackingInterface](#) and a [TelemetryDecoderInterface](#), and handles their interaction through a Finite State Machine.

10.3.2.1 Detailed Description

Classes that wrap an [AcquisitionInterface](#), a [TrackingInterface](#) and a [TelemetryDecoderInterface](#), and handles their interaction.

10.3.3 channel_libs

Classes

- class [ChannelFsm](#)

This class implements a State Machine for channel.

- class [channel_msg_receiver_cc](#)

GNU Radio block that receives asynchronous channel messages from acquisition and tracking blocks.

Typedefs

- using [channel_msg_receiver_cc_sptr](#) = `gnss_shared_ptr<channel_msg_receiver_cc>`

Functions

- `channel_msg_receiver_cc_sptr channel_msg_receiver_make_cc (std::shared_ptr< ChannelFsm > channel_fsm, bool repeat)`

10.3.3.1 Detailed Description

Library with utilities for a GNSS [Channel](#).

10.3.3.2 Typedef Documentation

10.3.3.2.1 channel_msg_receiver_cc_sptr

`using channel_msg_receiver_cc_sptr = gnss_shared_ptr<channel_msg_receiver_cc>`

Definition at line 33 of file [channel_msg_receiver_cc.h](#).

10.4 Signal Conditioner

Topics

- [conditioner_adapters](#)

10.4.1 Detailed Description

Signal Conditioner wrapper block

10.4.2 conditioner_adapters

Classes

- class [ArraySignalConditioner](#)
This class wraps blocks to change data_type_adapter, input_filter and resampler to be applied to the input flow of sampled signal.
- class [SignalConditioner](#)
This class wraps blocks to change data_type_adapter, input_filter and resampler to be applied to the input flow of sampled signal.

10.4.2.1 Detailed Description

Wrap a Signal Conditioner with a [GNSSBlockInterface](#)

10.5 Data Type Adapters

Topics

- [data_type_adapters](#)
- [data_type_gr_blocks](#)

10.5.1 Detailed Description

Classes for data type conversion

Classes for data type conversion

10.5.2 data_type_adapters

Classes

- class [ByteToShort](#)
Adapts an 8-bits sample stream (IF) to a short int stream (IF)
- class [CshortToGrComplex](#)
Adapts an 16-bits complex sample stream to a float complex stream.
- class [lbyteToCbyte](#)
- class [lbyteToComplex](#)
Adapts an I/Q interleaved byte integer sample stream to a gr_complex (float) stream.
- class [lbyteToCshort](#)
Adapts a short integer (16 bits) interleaved sample stream into a std::complex<short> stream.
- class [lshortToComplex](#)
Adapts an I/Q interleaved short integer sample stream to a gr_complex (float) stream.
- class [lshortToCshort](#)
Adapts a short integer (16 bits) interleaved sample stream into a std::complex<short> stream.

10.5.2.1 Detailed Description

Wrap GNU Radio data type adapter blocks with a [GNSSBlockInterface](#)

Wrap GNU Radio data type adapter blocks with a [GNSSBlockInterface](#)

10.5.3 data_type_gr_blocks

Classes

- class [cshort_to_gr_complex](#)
This class adapts a short (16-bits) interleaved sample stream into a std::complex<float> stream.
- class [interleaved_byte_to_complex_byte](#)

This class adapts an 8-bits interleaved sample stream into a 16-bits complex stream (`std::complex<unsigned char>`)

- class [interleaved_byte_to_complex_short](#)

This class adapts a short (16-bits) interleaved sample stream into a `std::complex<short>` stream.

- class [interleaved_short_to_complex_short](#)

This class adapts a short (16-bits) interleaved sample stream into a `std::complex<short>` stream.

Typedefs

- using [cshort_to_gr_complex_sptr](#) = `gnss_shared_ptr<cshort_to_gr_complex>`
- using [interleaved_byte_to_complex_byte_sptr](#) = `gnss_shared_ptr<interleaved_byte_to_complex_byte>`
- using [interleaved_byte_to_complex_short_sptr](#) = `gnss_shared_ptr<interleaved_byte_to_complex_short>`
- using [interleaved_short_to_complex_short_sptr](#) = `gnss_shared_ptr<interleaved_short_to_complex_short>`

Functions

- `cshort_to_gr_complex_sptr` **make_cshort_to_gr_complex** ()
- `interleaved_byte_to_complex_byte_sptr` **make_interleaved_byte_to_complex_byte** ()
- `interleaved_byte_to_complex_short_sptr` **make_interleaved_byte_to_complex_short** ()
- `interleaved_short_to_complex_short_sptr` **make_interleaved_short_to_complex_short** ()

10.5.3.1 Detailed Description

GNU Radio Blocks for data type conversion

10.5.3.2 Typedef Documentation

10.5.3.2.1 cshort_to_gr_complex_sptr

using `cshort_to_gr_complex_sptr` = `gnss_shared_ptr<cshort_to_gr_complex>`

Definition at line 32 of file [cshort_to_gr_complex.h](#).

10.5.3.2.2 interleaved_byte_to_complex_byte_sptr

using `interleaved_byte_to_complex_byte_sptr` = `gnss_shared_ptr<interleaved_byte_to_complex_byte>`

Definition at line 32 of file [interleaved_byte_to_complex_byte.h](#).

10.5.3.2.3 interleaved_byte_to_complex_short_sptr

using `interleaved_byte_to_complex_short_sptr` = `gnss_shared_ptr<interleaved_byte_to_complex_short>`

Definition at line 32 of file [interleaved_byte_to_complex_short.h](#).

10.5.3.2.4 interleaved_short_to_complex_short_sptr

using `interleaved_short_to_complex_short_sptr` = `gnss_shared_ptr<interleaved_short_to_complex_short>`

Definition at line 31 of file [interleaved_short_to_complex_short.h](#).

10.6 Input Filter

Topics

- [input_filter_adapters](#)
- [input_filter_gr_blocks](#)

10.6.1 Detailed Description

Classes for input signal filtering

10.6.2 input_filter_adapters

Classes

- class [BeamformerFilter](#)
Interface of an adapter of a digital beamformer block to a [GNSSBlockInterface](#).
- class [FirFilter](#)
This class adapts a GNU Radio `gr_fir_filter` designed with `pm_remez`.
- class [FreqXlatingFirFilter](#)
This class adapts a `gnuradio gr_freq_xlating_fir_filter` designed with `pm_remez`.
- class [NotchFilter](#)
- class [NotchFilterLite](#)
- class [PulseBlankingFilter](#)

10.6.2.1 Detailed Description

Classes that wrap GNU Radio input filters with a [GNSSBlockInterface](#)

10.6.3 input_filter_gr_blocks

Classes

- class [beamformer](#)
This class implements a real-time software-defined spatial filter using the CTTC GNSS experimental antenna array input and a set of dynamically reloadable weights.
- class [Notch](#)
This class implements a real-time software-defined multi state notch filter.
- class [NotchLite](#)
This class implements a real-time software-defined multi state notch filter light version.
- class [pulse_blanking_cc](#)

Typedefs

- using [beamformer_sptr](#) = `gnss_shared_ptr<beamformer>`
- using [notch_sptr](#) = `gnss_shared_ptr<Notch>`
- using [notch_lite_sptr](#) = `gnss_shared_ptr<NotchLite>`
- using [pulse_blanking_cc_sptr](#) = `gnss_shared_ptr<pulse_blanking_cc>`

Functions

- `beamformer_sptr` **make_beamformer_sptr** ()
- `notch_sptr` **make_notch_filter** (float pfa, float p_c_factor, int32_t length, int32_t n_segments_est, int32_t n_segments_reset)
- `notch_lite_sptr` **make_notch_filter_lite** (float p_c_factor, float pfa, int32_t length, int32_t n_segments_est, int32_t n_segments_reset, int32_t n_segments_coeff)
- `pulse_blanking_cc_sptr` **make_pulse_blanking_cc** (float pfa, int32_t length, int32_t n_segments_est, int32_t n_segments_reset)

Variables

- const int [GNSS_SDR_BEAMFORMER_CHANNELS](#) = 8

10.6.3.1 Detailed Description

GNU Radio blocks implementing input filters,

10.6.3.2 Typedef Documentation

10.6.3.2.1 beamformer_sptr

using beamformer_sptr = gnss_shared_ptr<beamformer>

Definition at line 33 of file [beamformer.h](#).

10.6.3.2.2 notch_lite_sptr

using notch_lite_sptr = gnss_shared_ptr<NotchLite>

Definition at line 36 of file [notch_lite_cc.h](#).

10.6.3.2.3 notch_sptr

using notch_sptr = gnss_shared_ptr<Notch>

Definition at line 36 of file [notch_cc.h](#).

10.6.3.2.4 pulse_blanking_cc_sptr

using pulse_blanking_cc_sptr = gnss_shared_ptr<pulse_blanking_cc>

Definition at line 36 of file [pulse_blanking_cc.h](#).

10.6.3.3 Variable Documentation

10.6.3.3.1 GNSS_SDR_BEAMFORMER_CHANNELS

const int GNSS_SDR_BEAMFORMER_CHANNELS = 8

Definition at line 37 of file [beamformer.h](#).

10.7 Algorithms Common Library

Topics

- [algorithms_libs](#)
- [gnss_sdr_flags](#)

10.7.1 Detailed Description

Common utilities for the GNSS receiver.

10.7.2 algorithms_libs

Namespaces

- namespace [std](#)
STL namespace.

Classes

- class [byte_x2_to_complex_byte](#)
This class adapts two signed char streams into a std::complex<signed char> stream.
- class [complex_byte_to_float_x2](#)
This class adapts a std::complex<signed char> stream into two 16-bits (short) streams.
- class [complex_float_to_complex_byte](#)
This class adapts a gr_complex stream into a std::complex<signed char> stream.
- class [conjugate_cc](#)
This class adapts a std::complex<short> stream into two 32-bits (float) streams.
- class [conjugate_ic](#)

This class adapts a `std::complex<short>` stream into two 32-bits (float) streams.

- class [conjugate_sc](#)

This class adapts a `std::complex<short>` stream into two 32-bits (float) streams.

- class [cshort_to_float_x2](#)

This class adapts a `std::complex<short>` stream into two 32-bits (float) streams.

- class [Gnss_circular_deque< T >](#)
- class [Pass_Through](#)

This class implements a block that connects input and output (does nothing)

- struct [SensorDataSample< DataType >](#)
- class [SensorDataAggregator](#)
- class [SensorDataFile](#)
- class [SensorDataSource](#)
- struct [SensorDataFileConfiguration](#)
- struct [SensorDataConfiguration](#)
- class [SensorDataSourceConfiguration](#)
- struct [SensorDataType](#)
- struct [SensorIdentifier](#)
- class [short_x2_to_cshort](#)

This class adapts two short streams into a `std::complex<short>` stream.

- class [TrackingCmd](#)

Typedefs

- using [byte_x2_to_complex_byte_sptr](#) = `gnss_shared_ptr<byte_x2_to_complex_byte>`
- using [complex_byte_to_float_x2_sptr](#) = `gnss_shared_ptr<complex_byte_to_float_x2>`
- using [complex_float_to_complex_byte_sptr](#) = `gnss_shared_ptr<complex_float_to_complex_byte>`
- using [conjugate_cc_sptr](#) = `gnss_shared_ptr<conjugate_cc>`
- using [conjugate_ic_sptr](#) = `gnss_shared_ptr<conjugate_ic>`
- using [conjugate_sc_sptr](#) = `gnss_shared_ptr<conjugate_sc>`
- using [cshort_to_float_x2_sptr](#) = `gnss_shared_ptr<cshort_to_float_x2>`
- using [item_type_converter_t](#) = `std::function<void(void *, const void *, uint32_t)>`
- using [short_x2_to_cshort_sptr](#) = `gnss_shared_ptr<short_x2_to_cshort>`

Functions

- void [beidou_b1i_code_gen_int](#) (`own::span< int32_t > dest`, `int32_t prn`, `uint32_t chip_shift`)
Generates int32_t GPS L1 C/A code for the desired SV ID and code shift.
- void [beidou_b1i_code_gen_float](#) (`own::span< float > dest`, `int32_t prn`, `uint32_t chip_shift`)
Generates float GPS L1 C/A code for the desired SV ID and code shift.
- void [beidou_b1i_code_gen_complex](#) (`own::span< std::complex< float > > dest`, `int32_t prn`, `uint32_t chip_shift`)
Generates complex GPS L1 C/A code for the desired SV ID and code shift.
- void [beidou_b1i_code_gen_complex_sampled](#) (`own::span< std::complex< float > > dest`, `uint32_t prn`, `int32_t sampling_freq`, `uint32_t chip_shift`)
Generates complex GPS L1 C/A code for the desired SV ID and code shift, and sampled to specific sampling frequency.
- void [beidou_b3i_code_gen_int](#) (`own::span< int > dest`, `int32_t prn`, `uint32_t chip_shift`)
Generates int BeiDou B3I code for the desired SV ID and code shift.
- void [beidou_b3i_code_gen_float](#) (`own::span< float > dest`, `int32_t prn`, `uint32_t chip_shift`)
Generates float BeiDou B3I code for the desired SV ID and code shift.
- void [beidou_b3i_code_gen_complex](#) (`own::span< std::complex< float > > dest`, `int32_t prn`, `uint32_t chip_shift`)
Generates complex BeiDou B3I code for the desired SV ID and code shift.

- void `beidou_b3i_code_gen_complex_sampled` (own::span< std::complex< float > > dest, uint32_t prn, int sampling_freq, uint32_t chip_shift)
Generates complex BeiDou B3I code for the desired SV ID and code shift, and sampled to specific sampling frequency.
- byte_x2_to_complex_byte_sptr `make_byte_x2_to_complex_byte` ()
- complex_byte_to_float_x2_sptr `make_complex_byte_to_float_x2` ()
- complex_float_to_complex_byte_sptr `make_complex_float_to_complex_byte` ()
- conjugate_cc_sptr `make_conjugate_cc` ()
- conjugate_ic_sptr `make_conjugate_ic` ()
- conjugate_sc_sptr `make_conjugate_sc` ()
- cshort_to_float_x2_sptr `make_cshort_to_float_x2` ()
- void `galileo_e1_code_gen_sinboc11_float` (own::span< float > dest, const std::array< char, 3 > &signal_id, uint32_t prn)
This function generates Galileo E1 code (can select E1B or E1C sinboc).
- void `galileo_e1_code_gen_float_sampled` (own::span< float > dest, const std::array< char, 3 > &signal_id, bool cboc, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift, bool secondary_flag)
This function generates Galileo E1 code (can select E1B or E1C, cboc or sinboc and the sample frequency sampling_freq).
- void `galileo_e1_code_gen_float_sampled` (own::span< float > dest, const std::array< char, 3 > &signal_id, bool cboc, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift)
This function generates Galileo E1 code (can select E1B or E1C, cboc or sinboc and the sample frequency sampling_freq).
- void `galileo_e1_code_gen_complex_sampled` (own::span< std::complex< float > > dest, const std::array< char, 3 > &signal_id, bool cboc, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift, bool secondary_flag)
This function generates Galileo E1 code (can select E1B or E1C, cboc or sinboc and the sample frequency sampling_freq).
- void `galileo_e1_code_gen_complex_sampled` (own::span< std::complex< float > > dest, const std::array< char, 3 > &signal_id, bool cboc, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift)
galileo_e1_code_gen_complex_sampled without secondary_flag for backward compatibility.
- void `galileo_e5_a_code_gen_complex_primary` (own::span< std::complex< float > > dest, int32_t prn, const std::array< char, 3 > &signal_id)
Generates Galileo E5a code at 1 sample/chip.
- void `galileo_e5_a_code_gen_complex_sampled` (own::span< std::complex< float > > dest, uint32_t prn, const std::array< char, 3 > &signal_id, int32_t sampling_freq, uint32_t chip_shift)
Generates Galileo E5a complex code, shifted to the desired chip and sampled at a frequency sampling_freq.
- void `galileo_e5_b_code_gen_complex_primary` (own::span< std::complex< float > > dest, int32_t prn, const std::array< char, 3 > &signal_id)
Generates Galileo E5b code at 1 sample/chip.
- void `galileo_e5_b_code_gen_complex_sampled` (own::span< std::complex< float > > dest, uint32_t prn, const std::array< char, 3 > &signal_id, int32_t sampling_freq, uint32_t chip_shift)
Generates Galileo E5b complex code, shifted to the desired chip and sampled at a frequency sampling_freq.
- void `galileo_e6_b_code_gen_complex_primary` (own::span< std::complex< float > > dest, int32_t prn)
Generates Galileo E6B code at 1 sample/chip.
- void `galileo_e6_b_code_gen_float_primary` (own::span< float > dest, int32_t prn)
Generates Galileo E6B code at 1 sample/chip.
- void `galileo_e6_b_code_gen_complex_sampled` (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift)
Generates Galileo E6B complex code, shifted to the desired chip and sampled at a frequency sampling_freq.
- void `galileo_e6_c_code_gen_complex_primary` (own::span< std::complex< float > > dest, int32_t prn)
Generates Galileo E6C codes at 1 sample/chip.
- void `galileo_e6_c_code_gen_float_primary` (own::span< float > dest, int32_t prn)
Generates Galileo E6C codes at 1 sample/chip.
- void `galileo_e6_c_code_gen_complex_sampled` (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift)

- Generates Galileo E6C complex codes, shifted to the desired chip and sampled at a frequency sampling_freq.*

 - void [galileo_e6_c_secondary_code_gen_complex](#) (own::span< std::complex< float > > dest, int32_t prn)

Generates Galileo E6C secondary codes at 1 sample/chip.

 - void [galileo_e6_c_secondary_code_gen_float](#) (own::span< float > dest, int32_t prn)

Generates Galileo E6C secondary codes at 1 sample/chip.

 - std::string [galileo_e6_c_secondary_code](#) (int32_t prn)

Generates a string with Galileo E6C secondary codes at 1 sample/chip.

 - arma::mat [Skew_symmetric](#) (const arma::vec &a)

Calculates skew-symmetric matrix.

 - double **WGS84_g0** (double Lat_rad)
 - double **WGS84_geocentric_radius** (double Lat_geodetic_rad)
 - int [topocent](#) (double *Az, double *El, double *D, const arma::vec &x, const arma::vec &dx)

Transformation of vector dx into topocentric coordinate system with origin at x Inputs: x - vector origin coordinates (in ECEF system [X; Y; Z;]) dx - vector ([dX; dY; dZ;]).

 - int [togeod](#) (double *dphi, double *dlambda, double *h, double a, double finv, double X, double Y, double Z)

Subroutine to calculate geodetic coordinates latitude, longitude, height given Cartesian coordinates X,Y,Z, and reference ellipsoid values semi-major axis (a) and the inverse of flattening (finv).

 - arma::vec [Gravity_ECEF](#) (const arma::vec &r_eb_e)

Calculates acceleration due to gravity resolved about ECEF-frame.

 - arma::vec [cart2geo](#) (const arma::vec &XYZ, int ellipsoid_selection)

Conversion of Cartesian coordinates (X,Y,Z) to geographical coordinates (latitude, longitude, h) on a selected reference ellipsoid.

 - arma::vec **LLH_to_deg** (const arma::vec &LLH)
 - double **degtorad** (double angleInDegrees)
 - double **radtodeg** (double angleInRadians)
 - double **mstoknotsh** (double MetersPerSeconds)
 - double **mstokph** (double MetersPerSeconds)
 - arma::vec **CTM_to_Euler** (const arma::mat &C)
 - arma::mat **Euler_to_CTM** (const arma::vec &eul)
 - void **ECEF_to_Geo** (const arma::vec &r_eb_e, const arma::vec &v_eb_e, const arma::mat &C_b_e, arma::vec &LLH, arma::vec &v_eb_n, arma::mat &C_b_n)
 - void [Geo_to_ECEF](#) (const arma::vec &LLH, const arma::vec &v_eb_n, const arma::mat &C_b_n, arma::vec &r_eb_e, arma::vec &v_eb_e, arma::mat &C_b_e)

From Geographic to ECEF coordinates.

 - void [pv_Geo_to_ECEF](#) (double L_b, double lambda_b, double h_b, const arma::vec &v_eb_n, arma::vec &r_eb_e, arma::vec &v_eb_e)

Converts curvilinear to Cartesian position and velocity resolving axes from NED to ECEF This function created 11/4/2012 by Paul Groves.

 - double [great_circle_distance](#) (double lat1, double lon1, double lat2, double lon2)

The Haversine formula determines the great-circle distance between two points on a sphere given their longitudes and latitudes.

 - void [cart2utm](#) (const arma::vec &r_eb_e, int zone, arma::vec &r_enu)

Transformation of ECEF (X,Y,Z) to (E,N,U) in UTM, zone 'zone'.

 - int [findUtmZone](#) (double latitude_deg, double longitude_deg)

Function finds the UTM zone number for given longitude and latitude.

 - double [clsin](#) (const arma::colvec &ar, int degree, double argument)

Clenshaw summation of sinus of argument.

 - void [clksin](#) (const arma::colvec &ar, int degree, double arg_real, double arg_imag, double *re, double *im)

Clenshaw summation of sinus with complex argument.

 - void [glonass_l1_ca_code_gen_complex](#) (own::span< std::complex< float > > dest, uint32_t chip_shift)

Generates complex GLONASS L1 C/A code for the desired SV ID and code shift.

 - void [glonass_l1_ca_code_gen_float](#) (own::span< float > dest, uint32_t chip_shift)

Generates float GLONASS L1 C/A code for the desired SV ID and code shift.

- void [glonass_l1_ca_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, int32_t sampling_freq, uint32_t chip_shift)
Generates complex GLONASS L1 C/A code for the desired SV ID and code shift, and sampled to specific sampling frequency.
- void [glonass_l2_ca_code_gen_complex](#) (own::span< std::complex< float > > dest, uint32_t chip_shift)
Generates complex GLONASS L2 C/A code for the desired SV ID and code shift.
- void [glonass_l2_ca_code_gen_float](#) (own::span< float > dest, uint32_t chip_shift)
Generates float GLONASS L2 C/A code for the desired SV ID and code shift.
- void [glonass_l2_ca_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, int32_t sampling_freq, uint32_t chip_shift)
Generates complex GLONASS L2 C/A code for the desired SV ID and code shift, and sampled to specific sampling frequency.
- bool [gnss_sdr_create_directory](#) (const std::string &foldername)
- void [complex_exp_gen](#) (own::span< std::complex< float > > dest, double freq, double sampling_freq)
This function generates a complex exponential in dest.
- void [complex_exp_gen_conj](#) (own::span< std::complex< float > > dest, double freq, double sampling_freq)
This function generates a conjugate complex exponential in dest.
- void [hex_to_binary_converter](#) (own::span< int32_t > dest, char from)
This function makes a conversion from hex (the input is a char) to binary (the output are 4 ints with +1 or -1 values).
- std::string [hex_to_binary_string](#) (char from)
This function makes a conversion from hex (the input is a char) to binary (the output is a string of 4 char with 0 or 1 values).
- void [resampler](#) (const own::span< float > from, own::span< float > dest, float fs_in, float fs_out)
This function resamples a sequence of float values.
- void [resampler](#) (own::span< const std::complex< float > > from, own::span< std::complex< float > > dest, float fs_in, float fs_out)
This function resamples a sequence of complex values.
- void [gps_l2c_m_code_gen_complex](#) (own::span< std::complex< float > > dest, uint32_t prn)
Generates complex GPS L2C M code for the desired SV ID.
- void [gps_l2c_m_code_gen_float](#) (own::span< float > dest, uint32_t prn)
Generates float GPS L2C M code for the desired SV ID.
- void [gps_l2c_m_code_gen_float_cl_zeroed](#) (own::span< float > dest, uint32_t prn)
Generates float GPS L2C M code with double chip rate and L component zeroed for the desired SV ID.
- void [gps_l2c_m_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq)
Generates complex GPS L2C M code for the desired SV ID, and sampled to specific sampling frequency.
- void [gps_l2c_m_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq, bool cl_zeroed)
Generates complex GPS L2C M code for the desired SV ID, and sampled to specific sampling frequency, optionally zeroing CL slots.
- void [gps_l5i_code_gen_complex](#) (own::span< std::complex< float > > dest, uint32_t prn)
Generates complex GPS L5I code for the desired SV ID.
- void [gps_l5i_code_gen_float](#) (own::span< float > dest, uint32_t prn)
Generates real GPS L5I code for the desired SV ID.
- void [gps_l5q_code_gen_complex](#) (own::span< std::complex< float > > dest, uint32_t prn)
Generates complex GPS L5Q code for the desired SV ID.
- void [gps_l5q_code_gen_float](#) (own::span< float > dest, uint32_t prn)
Generates real GPS L5Q code for the desired SV ID.
- void [gps_l5i_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq)
Generates complex GPS L5I code for the desired SV ID, and sampled to specific sampling frequency.
- void [gps_l5q_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq)

- Generates complex GPS L5Q code for the desired SV ID, and sampled to specific sampling frequency.*

 - void [gps_l1_ca_code_gen_int](#) (own::span< int32_t > dest, int32_t prn, uint32_t chip_shift)
- Generates int GPS L1 C/A code for the desired SV ID and code shift.*

 - void [gps_l1_ca_code_gen_float](#) (own::span< float > dest, int32_t prn, uint32_t chip_shift)
- Generates float GPS L1 C/A code for the desired SV ID and code shift.*

 - void [gps_l1_ca_code_gen_complex](#) (own::span< std::complex< float > > dest, int32_t prn, uint32_t chip_shift)
- Generates complex GPS L1 C/A code for the desired SV ID and code shift.*

 - void [gps_l1_ca_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift)
- Generates complex GPS L1 C/A code for the desired SV ID and code shift, and sampled to specific sampling frequency.*

 - bool [item_type_valid](#) (const std::string &item_type)
- Check if a string is a valid item type.*

 - size_t [item_type_size](#) (const std::string &item_type)
- Return the size of the given item type, or zero if unknown.*

 - bool [item_type_is_complex](#) (const std::string &item_type)
- Determine if an item_type is complex.*

 - item_type_converter_t [make_vector_converter](#) (const std::string &input_type, const std::string &output_type)
- Create a function to convert an array of input_type to an array of output_type.*

 - void [qzss_l1_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq)
- Generates complex QZSS L1 C/A code for the desired SV ID, and sampled to specific sampling frequency.*

 - void [qzss_l1_code_gen_float](#) (own::span< float > dest, uint32_t prn)
- Generates real QZSS L1 C/A code for the desired SV ID.*

 - void [qzss_l5i_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq)
- Generates complex QZSS L5I code for the desired SV ID, and sampled to specific sampling frequency.*

 - void [qzss_l5i_code_gen_float](#) (own::span< float > dest, uint32_t prn)
- Generates real QZSS L5I code for the desired SV ID.*

 - void [qzss_l5q_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq)
- Generates complex QZSS L5Q code for the desired SV ID, and sampled to specific sampling frequency.*

 - void [qzss_l5q_code_gen_float](#) (own::span< float > dest, uint32_t prn)
- Generates real QZSS L5I code for the desired SV ID.*

 - std::vector< gr::tag_t > [resample_sensor_data_tags](#) (const std::vector< gr::tag_t > &tags, double freq_in, double freq_out)
- Updates timestamp within sensor data tags. To be used in resampler blocks.*

 - short_x2_to_cshort_sptr [make_short_x2_to_cshort](#) ()
- [Gnss_circular_deque< T >::Gnss_circular_deque](#) ()

Default constructor.

 - [Gnss_circular_deque< T >::Gnss_circular_deque](#) (unsigned int max_size, unsigned int nchann)
- nchann = number of channels; max_size = channel capacity*

 - unsigned int [Gnss_circular_deque< T >::size](#) (unsigned int ch) const
- Returns the number of available elements in a channel.*

 - T & [Gnss_circular_deque< T >::back](#) (unsigned int ch)
- Returns a reference to the last element in the deque.*

 - T & [Gnss_circular_deque< T >::front](#) (unsigned int ch)
- Returns a reference to the first element in the deque.*

 - T & [Gnss_circular_deque< T >::at](#) (unsigned int ch, unsigned int pos)
- Returns a reference to an element with bound checking.*

 - const T & [Gnss_circular_deque< T >::get](#) (unsigned int ch, unsigned int pos) const

- Returns a const reference to an element without bound checking.*
- void [Gnss_circular_deque< T >::clear](#) (unsigned int ch)
Removes all the elements of the deque (Sets size to 0). Capacity is not modified.
- void [Gnss_circular_deque< T >::reset](#) (unsigned int max_size, unsigned int nchann)
Removes all the elements in all the channels. Re-sets the number of channels and their capacity.
- void [Gnss_circular_deque< T >::reset](#) ()
Removes all the channels (Sets nchann to 0)
- void [Gnss_circular_deque< T >::pop_front](#) (unsigned int ch)
Removes the first element of the deque.
- void [Gnss_circular_deque< T >::push_back](#) (unsigned int ch, const T &new_data)
Inserts an element at the end of the deque.

10.7.2.1 Detailed Description

Common utilities for GNSS algorithms.

10.7.2.2 Typedef Documentation

10.7.2.2.1 [byte_x2_to_complex_byte_sptr](#)

using [byte_x2_to_complex_byte_sptr](#) = [gnss_shared_ptr<byte_x2_to_complex_byte>](#)
Definition at line 33 of file [byte_x2_to_complex_byte.h](#).

10.7.2.2.2 [complex_byte_to_float_x2_sptr](#)

using [complex_byte_to_float_x2_sptr](#) = [gnss_shared_ptr<complex_byte_to_float_x2>](#)
Definition at line 33 of file [complex_byte_to_float_x2.h](#).

10.7.2.2.3 [complex_float_to_complex_byte_sptr](#)

using [complex_float_to_complex_byte_sptr](#) = [gnss_shared_ptr<complex_float_to_complex_byte>](#)
Definition at line 33 of file [complex_float_to_complex_byte.h](#).

10.7.2.2.4 [conjugate_cc_sptr](#)

using [conjugate_cc_sptr](#) = [gnss_shared_ptr<conjugate_cc>](#)
Definition at line 33 of file [conjugate_cc.h](#).

10.7.2.2.5 [conjugate_ic_sptr](#)

using [conjugate_ic_sptr](#) = [gnss_shared_ptr<conjugate_ic>](#)
Definition at line 33 of file [conjugate_ic.h](#).

10.7.2.2.6 [conjugate_sc_sptr](#)

using [conjugate_sc_sptr](#) = [gnss_shared_ptr<conjugate_sc>](#)
Definition at line 33 of file [conjugate_sc.h](#).

10.7.2.2.7 [cshort_to_float_x2_sptr](#)

using [cshort_to_float_x2_sptr](#) = [gnss_shared_ptr<cshort_to_float_x2>](#)
Definition at line 33 of file [cshort_to_float_x2.h](#).

10.7.2.2.8 [item_type_converter_t](#)

using [item_type_converter_t](#) = [std::function<void\(void *, const void *, uint32_t\)>](#)
Definition at line 34 of file [item_type_helpers.h](#).

10.7.2.2.9 short_x2_to_cshort_sptr

using short_x2_to_cshort_sptr = gnss_shared_ptr<short_x2_to_cshort>
 Definition at line 33 of file [short_x2_to_cshort.h](#).

10.7.2.3 Function Documentation

10.7.2.3.1 at()

```
template<class T>
T & Gnss_circular_deque< T >::at (
    unsigned int ch,
    unsigned int pos)
```

Returns a reference to an element with bound checking.
 Definition at line 88 of file [gnss_circular_deque.h](#).

10.7.2.3.2 back()

```
template<class T>
T & Gnss_circular_deque< T >::back (
    unsigned int ch)
```

Returns a reference to the last element in the deque.
 Definition at line 74 of file [gnss_circular_deque.h](#).

10.7.2.3.3 beidou_b1i_code_gen_complex()

```
void beidou_b1i_code_gen_complex (
    own::span< std::complex< float > > dest,
    int32_t prn,
    uint32_t chip_shift)
```

Generates complex GPS L1 C/A code for the desired SV ID and code shift.

10.7.2.3.4 beidou_b1i_code_gen_complex_sampled()

```
void beidou_b1i_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    int32_t sampling_freq,
    uint32_t chip_shift)
```

Generates complex GPS L1 C/A code for the desired SV ID and code shift, and sampled to specific sampling frequency.

10.7.2.3.5 beidou_b1i_code_gen_float()

```
void beidou_b1i_code_gen_float (
    own::span< float > dest,
    int32_t prn,
    uint32_t chip_shift)
```

Generates float GPS L1 C/A code for the desired SV ID and code shift.

10.7.2.3.6 beidou_b1i_code_gen_int()

```
void beidou_b1i_code_gen_int (
    own::span< int32_t > dest,
    int32_t prn,
    uint32_t chip_shift)
```

Generates int32_t GPS L1 C/A code for the desired SV ID and code shift.

10.7.2.3.7 beidou_b3i_code_gen_complex()

```
void beidou_b3i_code_gen_complex (
    own::span< std::complex< float > > dest,
    int32_t prn,
    uint32_t chip_shift)
```

Generates complex BeiDou B3I code for the desired SV ID and code shift.

10.7.2.3.8 beidou_b3i_code_gen_complex_sampled()

```
void beidou_b3i_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    int sampling_freq,
    uint32_t chip_shift)
```

Generates complex BeiDou B3I code for the desired SV ID and code shift, and sampled to specific sampling frequency.

10.7.2.3.9 beidou_b3i_code_gen_float()

```
void beidou_b3i_code_gen_float (
    own::span< float > dest,
    int32_t prn,
    uint32_t chip_shift)
```

Generates float BeiDou B3I code for the desired SV ID and code shift.

10.7.2.3.10 beidou_b3i_code_gen_int()

```
void beidou_b3i_code_gen_int (
    own::span< int > dest,
    int32_t prn,
    uint32_t chip_shift)
```

Generates int BeiDou B3I code for the desired SV ID and code shift.

10.7.2.3.11 cart2geo()

```
arma::vec cart2geo (
    const arma::vec & XYZ,
    int ellipsoid_selection)
```

Conversion of Cartesian coordinates (X,Y,Z) to geographical coordinates (latitude, longitude, h) on a selected reference ellipsoid.

Choices of Reference Ellipsoid for Geographical Coordinates

1. International Ellipsoid 1924
2. International Ellipsoid 1967
3. World Geodetic System 1972
4. Geodetic Reference System 1980
5. World Geodetic System 1984

10.7.2.3.12 cart2utm()

```
void cart2utm (
    const arma::vec & r_eb_e,
    int zone,
    arma::vec & r_enu)
```

Transformation of ECEF (X,Y,Z) to (E,N,U) in UTM, zone 'zone'.

10.7.2.3.13 clear()

```
template<class T>
void Gnss_circular_deque< T >::clear (
    unsigned int ch)
```

Removes all the elements of the deque (Sets size to 0). Capacity is not modified.

Definition at line 102 of file [gnss_circular_deque.h](#).

10.7.2.3.14 clkisin()

```
void clkisin (
    const arma::colvec & ar,
    int degree,
    double arg_real,
    double arg_imag,
    double * re,
    double * im)
```

Clenshaw summation of sinus with complex argument.

10.7.2.3.15 clsin()

```
double clsin (
    const arma::colvec & ar,
    int degree,
    double argument)
```

Clenshaw summation of sinus of argument.

10.7.2.3.16 complex_exp_gen()

```
void complex_exp_gen (
    own::span< std::complex< float > > dest,
    double freq,
    double sampling_freq)
```

This function generates a complex exponential in dest.

10.7.2.3.17 complex_exp_gen_conj()

```
void complex_exp_gen_conj (
    own::span< std::complex< float > > dest,
    double freq,
    double sampling_freq)
```

This function generates a conjugate complex exponential in dest.

10.7.2.3.18 findUtmZone()

```
int findUtmZone (
    double latitude_deg,
    double longitude_deg)
```

Function finds the UTM zone number for given longitude and latitude.

10.7.2.3.19 front()

```
template<class T>
T & Gnss_circular_deque< T >::front (
    unsigned int ch)
```

Returns a reference to the first element in the deque.

Definition at line 81 of file [gnss_circular_deque.h](#).

10.7.2.3.20 galileo_e1_code_gen_complex_sampled() [1/2]

```
void galileo_e1_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    const std::array< char, 3 > & signal_id,
    bool cboc,
    uint32_t prn,
    int32_t sampling_freq,
    uint32_t chip_shift)
```

galileo_e1_code_gen_complex_sampled without secondary_flag for backward compatibility.

10.7.2.3.21 galileo_e1_code_gen_complex_sampled() [2/2]

```
void galileo_e1_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    const std::array< char, 3 > & signal_id,
    bool cboc,
    uint32_t prn,
    int32_t sampling_freq,
    uint32_t chip_shift,
    bool secondary_flag)
```

This function generates Galileo E1 code (can select E1B or E1C, cboc or sinboc and the sample frequency sampling_freq).

10.7.2.3.22 galileo_e1_code_gen_float_sampled() [1/2]

```
void galileo_e1_code_gen_float_sampled (
    own::span< float > dest,
    const std::array< char, 3 > & signal_id,
    bool cboc,
    uint32_t prn,
    int32_t sampling_freq,
    uint32_t chip_shift)
```

This function generates Galileo E1 code (can select E1B or E1C, cboc or sinboc and the sample frequency sampling_freq).

10.7.2.3.23 galileo_e1_code_gen_float_sampled() [2/2]

```
void galileo_e1_code_gen_float_sampled (
    own::span< float > dest,
    const std::array< char, 3 > & signal_id,
    bool cboc,
    uint32_t prn,
    int32_t sampling_freq,
    uint32_t chip_shift,
    bool secondary_flag)
```

This function generates Galileo E1 code (can select E1B or E1C, cboc or sinboc and the sample frequency sampling_freq).

10.7.2.3.24 galileo_e1_code_gen_sinboc11_float()

```
void galileo_e1_code_gen_sinboc11_float (
    own::span< float > dest,
    const std::array< char, 3 > & signal_id,
    uint32_t prn)
```

This function generates Galileo E1 code (can select E1B or E1C sinboc).

10.7.2.3.25 galileo_e5_a_code_gen_complex_primary()

```
void galileo_e5_a_code_gen_complex_primary (
```

```

    own::span< std::complex< float > > dest,
    int32_t prn,
    const std::array< char, 3 > & signal_id)

```

Generates Galileo E5a code at 1 sample/chip.

10.7.2.3.26 galileo_e5_a_code_gen_complex_sampled()

```

void galileo_e5_a_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    const std::array< char, 3 > & signal_id,
    int32_t sampling_freq,
    uint32_t chip_shift)

```

Generates Galileo E5a complex code, shifted to the desired chip and sampled at a frequency sampling_freq.

10.7.2.3.27 galileo_e5_b_code_gen_complex_primary()

```

void galileo_e5_b_code_gen_complex_primary (
    own::span< std::complex< float > > dest,
    int32_t prn,
    const std::array< char, 3 > & signal_id)

```

Generates Galileo E5b code at 1 sample/chip.

10.7.2.3.28 galileo_e5_b_code_gen_complex_sampled()

```

void galileo_e5_b_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    const std::array< char, 3 > & signal_id,
    int32_t sampling_freq,
    uint32_t chip_shift)

```

Generates Galileo E5b complex code, shifted to the desired chip and sampled at a frequency sampling_freq.

10.7.2.3.29 galileo_e6_b_code_gen_complex_primary()

```

void galileo_e6_b_code_gen_complex_primary (
    own::span< std::complex< float > > dest,
    int32_t prn)

```

Generates Galileo E6B code at 1 sample/chip.

10.7.2.3.30 galileo_e6_b_code_gen_complex_sampled()

```

void galileo_e6_b_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    int32_t sampling_freq,
    uint32_t chip_shift)

```

Generates Galileo E6B complex code, shifted to the desired chip and sampled at a frequency sampling_freq.

10.7.2.3.31 galileo_e6_b_code_gen_float_primary()

```

void galileo_e6_b_code_gen_float_primary (
    own::span< float > dest,
    int32_t prn)

```

Generates Galileo E6B code at 1 sample/chip.

10.7.2.3.32 galileo_e6_c_code_gen_complex_primary()

```
void galileo_e6_c_code_gen_complex_primary (
    own::span< std::complex< float > > dest,
    int32_t prn)

```

Generates Galileo E6C codes at 1 sample/chip.

10.7.2.3.33 galileo_e6_c_code_gen_complex_sampled()

```
void galileo_e6_c_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    int32_t sampling_freq,
    uint32_t chip_shift)

```

Generates Galileo E6C complex codes, shifted to the desired chip and sampled at a frequency `sampling_freq`.

10.7.2.3.34 galileo_e6_c_code_gen_float_primary()

```
void galileo_e6_c_code_gen_float_primary (
    own::span< float > dest,
    int32_t prn)

```

Generates Galileo E6C codes at 1 sample/chip.

10.7.2.3.35 galileo_e6_c_secondary_code()

```
std::string galileo_e6_c_secondary_code (
    int32_t prn)

```

Generates a string with Galileo E6C secondary codes at 1 sample/chip.

10.7.2.3.36 galileo_e6_c_secondary_code_gen_complex()

```
void galileo_e6_c_secondary_code_gen_complex (
    own::span< std::complex< float > > dest,
    int32_t prn)

```

Generates Galileo E6C secondary codes at 1 sample/chip.

10.7.2.3.37 galileo_e6_c_secondary_code_gen_float()

```
void galileo_e6_c_secondary_code_gen_float (
    own::span< float > dest,
    int32_t prn)

```

Generates Galileo E6C secondary codes at 1 sample/chip.

10.7.2.3.38 Geo_to_ECEF()

```
void Geo_to_ECEF (
    const arma::vec & LLH,
    const arma::vec & v_eb_n,
    const arma::mat & C_b_n,
    arma::vec & r_eb_e,
    arma::vec & v_eb_e,
    arma::mat & C_b_e)

```

From Geographic to ECEF coordinates.

Inputs: LLH latitude (rad), longitude (rad), height (m) `v_eb_n` velocity of body frame w.r.t. ECEF frame, resolved along north, east, and down (m/s) `C_b_n` body-to-NED coordinate transformation matrix

Outputs: `r_eb_e` Cartesian position of body frame w.r.t. ECEF frame, resolved along ECEF-frame axes (m) `v_eb_e` velocity of body frame w.r.t. ECEF frame, resolved along ECEF-frame axes (m/s) `C_b_e` body-to-ECEF-frame coordinate transformation matrix

10.7.2.3.39 get()

```
template<class T>
const T & Gnss_circular_deque< T >::get (
    unsigned int ch,
    unsigned int pos) const
```

Returns a const reference to an element without bound checking.

Definition at line 95 of file [gnss_circular_deque.h](#).

10.7.2.3.40 glonass_l1_ca_code_gen_complex()

```
void glonass_l1_ca_code_gen_complex (
    own::span< std::complex< float > > dest,
    uint32_t chip_shift)
```

Generates complex GLONASS L1 C/A code for the desired SV ID and code shift.

10.7.2.3.41 glonass_l1_ca_code_gen_complex_sampled()

```
void glonass_l1_ca_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    int32_t sampling_freq,
    uint32_t chip_shift)
```

Generates complex GLONASS L1 C/A code for the desired SV ID and code shift, and sampled to specific sampling frequency.

10.7.2.3.42 glonass_l1_ca_code_gen_float()

```
void glonass_l1_ca_code_gen_float (
    own::span< float > dest,
    uint32_t chip_shift)
```

Generates float GLONASS L1 C/A code for the desired SV ID and code shift.

10.7.2.3.43 glonass_l2_ca_code_gen_complex()

```
void glonass_l2_ca_code_gen_complex (
    own::span< std::complex< float > > dest,
    uint32_t chip_shift)
```

Generates complex GLONASS L2 C/A code for the desired SV ID and code shift.

10.7.2.3.44 glonass_l2_ca_code_gen_complex_sampled()

```
void glonass_l2_ca_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    int32_t sampling_freq,
    uint32_t chip_shift)
```

Generates complex GLONASS L2 C/A code for the desired SV ID and code shift, and sampled to specific sampling frequency.

10.7.2.3.45 glonass_l2_ca_code_gen_float()

```
void glonass_l2_ca_code_gen_float (
    own::span< float > dest,
    uint32_t chip_shift)
```

Generates float GLONASS L2 C/A code for the desired SV ID and code shift.

10.7.2.3.46 Gnss_circular_deque() [1/2]

```
template<class T>
Gnss_circular_deque< T >::Gnss_circular_deque ()
```

Default constructor.

Definition at line 53 of file [gnss_circular_deque.h](#).
References [reset\(\)](#).

10.7.2.3.47 Gnss_circular_deque() [2/2]

```
template<class T>
Gnss_circular_deque< T >::Gnss_circular_deque (
    unsigned int max_size,
    unsigned int nchann)
nchann = number of channels; max_size = channel capacity
```

Definition at line 60 of file [gnss_circular_deque.h](#).
References [reset\(\)](#).

10.7.2.3.48 gps_l1_ca_code_gen_complex()

```
void gps_l1_ca_code_gen_complex (
    own::span< std::complex< float > > dest,
    int32_t prn,
    uint32_t chip_shift)
```

Generates complex GPS L1 C/A code for the desired SV ID and code shift.

10.7.2.3.49 gps_l1_ca_code_gen_complex_sampled()

```
void gps_l1_ca_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    int32_t sampling_freq,
    uint32_t chip_shift)
```

Generates complex GPS L1 C/A code for the desired SV ID and code shift, and sampled to specific sampling frequency.

10.7.2.3.50 gps_l1_ca_code_gen_float()

```
void gps_l1_ca_code_gen_float (
    own::span< float > dest,
    int32_t prn,
    uint32_t chip_shift)
```

Generates float GPS L1 C/A code for the desired SV ID and code shift.

10.7.2.3.51 gps_l1_ca_code_gen_int()

```
void gps_l1_ca_code_gen_int (
    own::span< int32_t > dest,
    int32_t prn,
    uint32_t chip_shift)
```

Generates int GPS L1 C/A code for the desired SV ID and code shift.

10.7.2.3.52 gps_l2c_m_code_gen_complex()

```
void gps_l2c_m_code_gen_complex (
    own::span< std::complex< float > > dest,
    uint32_t prn)
```

Generates complex GPS L2C M code for the desired SV ID.

10.7.2.3.53 gps_l2c_m_code_gen_complex_sampled() [1/2]

```
void gps_l2c_m_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
```

```
uint32_t prn,
int32_t sampling_freq)
```

Generates complex GPS L2C M code for the desired SV ID, and sampled to specific sampling frequency.

10.7.2.3.54 `gps_l2c_m_code_gen_complex_sampled()` [2/2]

```
void gps_l2c_m_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    int32_t sampling_freq,
    bool cl_zeroed)
```

Generates complex GPS L2C M code for the desired SV ID, and sampled to specific sampling frequency, optionally zeroing CL slots.

10.7.2.3.55 `gps_l2c_m_code_gen_float()`

```
void gps_l2c_m_code_gen_float (
    own::span< float > dest,
    uint32_t prn)
```

Generates float GPS L2C M code for the desired SV ID.

10.7.2.3.56 `gps_l2c_m_code_gen_float_cl_zeroed()`

```
void gps_l2c_m_code_gen_float_cl_zeroed (
    own::span< float > dest,
    uint32_t prn)
```

Generates float GPS L2C M code with double chip rate and L component zeroed for the desired SV ID.

10.7.2.3.57 `gps_l5i_code_gen_complex()`

```
void gps_l5i_code_gen_complex (
    own::span< std::complex< float > > dest,
    uint32_t prn)
```

Generates complex GPS L5I code for the desired SV ID.

10.7.2.3.58 `gps_l5i_code_gen_complex_sampled()`

```
void gps_l5i_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    int32_t sampling_freq)
```

Generates complex GPS L5I code for the desired SV ID, and sampled to specific sampling frequency.

10.7.2.3.59 `gps_l5i_code_gen_float()`

```
void gps_l5i_code_gen_float (
    own::span< float > dest,
    uint32_t prn)
```

Generates real GPS L5I code for the desired SV ID.

10.7.2.3.60 `gps_l5q_code_gen_complex()`

```
void gps_l5q_code_gen_complex (
    own::span< std::complex< float > > dest,
    uint32_t prn)
```

Generates complex GPS L5Q code for the desired SV ID.

10.7.2.3.61 gps_l5q_code_gen_complex_sampled()

```
void gps_l5q_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    int32_t sampling_freq)
```

Generates complex GPS L5Q code for the desired SV ID, and sampled to specific sampling frequency.

10.7.2.3.62 gps_l5q_code_gen_float()

```
void gps_l5q_code_gen_float (
    own::span< float > dest,
    uint32_t prn)
```

Generates real GPS L5Q code for the desired SV ID.

10.7.2.3.63 Gravity_ECEF()

```
arma::vec Gravity_ECEF (
    const arma::vec & r_eb_e)
```

Calculates acceleration due to gravity resolved about ECEF-frame.

10.7.2.3.64 great_circle_distance()

```
double great_circle_distance (
    double lat1,
    double lon1,
    double lat2,
    double lon2)
```

The Haversine formula determines the great-circle distance between two points on a sphere given their longitudes and latitudes.

10.7.2.3.65 hex_to_binary_converter()

```
void hex_to_binary_converter (
    own::span< int32_t > dest,
    char from)
```

This function makes a conversion from hex (the input is a char) to binary (the output are 4 ints with +1 or -1 values).

10.7.2.3.66 hex_to_binary_string()

```
std::string hex_to_binary_string (
    char from)
```

This function makes a conversion from hex (the input is a char) to binary (the output is a string of 4 char with 0 or 1 values).

10.7.2.3.67 item_type_is_complex()

```
bool item_type_is_complex (
    const std::string & item_type)
```

Determine if an item_type is complex.

10.7.2.3.68 item_type_size()

```
size_t item_type_size (
    const std::string & item_type)
```

Return the size of the given item type, or zero if unknown.

10.7.2.3.69 item_type_valid()

```
bool item_type_valid (
    const std::string & item_type)
```

Check if a string is a valid item type.

\description Valid item types include: "byte", "short", "float", "ibyte", "ishort", "cbyte", "cshort", "gr_complex"

10.7.2.3.70 make_vector_converter()

```
item_type_converter_t make_vector_converter (
    const std::string & input_type,
    const std::string & output_type)
```

Create a function to convert an array of input_type to an array of output_type.

\description Provides a generic interface to generate conversion functions for mapping arrays of items.

Parameters

<i>input_type</i>	- String representation of the input item type
<i>output_type</i>	- String representation of the output item type

The item types accepted are:

1. "byte" for 8 bit integers
2. "cbyte" for complex (interleaved) 8 bit integers
3. "ibyte" for complex (interleaved) 8 bit integers
1. "short" for 16 bit integers
2. "cshort" for complex (interleaved) 16 bit integers
3. "ishort" for complex (interleaved) 16 bit integers
4. "float" for 32 bit floating point values
5. "gr_complex" for complex (interleaved) 32 bit floating point values

Returns

A function object with the following prototype: void convert_fun(void *dest, void *src, int num_items);

10.7.2.3.71 pop_front()

```
template<class T>
void Gnss_circular_deque< T >::pop_front (
    unsigned int ch)
```

Removes the first element of the deque.

Definition at line 130 of file [gnss_circular_deque.h](#).

10.7.2.3.72 push_back()

```
template<class T>
void Gnss_circular_deque< T >::push_back (
    unsigned int ch,
    const T & new_data)
```

Inserts an element at the end of the deque.

Definition at line 137 of file [gnss_circular_deque.h](#).

10.7.2.3.73 pv_Geo_to_ECEF()

```
void pv_Geo_to_ECEF (
    double L_b,
    double lambda_b,
    double h_b,
    const arma::vec & v_eb_n,
    arma::vec & r_eb_e,
    arma::vec & v_eb_e)
```

Converts curvilinear to Cartesian position and velocity resolving axes from NED to ECEF This function created 11/4/2012 by Paul Groves.

Inputs: L_b latitude (rad) lambda_b longitude (rad) h_b height (m) v_eb_n velocity of body frame w.r.t. ECEF frame, resolved along north, east, and down (m/s)

Outputs: r_eb_e Cartesian position of body frame w.r.t. ECEF frame, resolved along ECEF-frame axes (m) v_eb_e velocity of body frame w.r.t. ECEF frame, resolved along ECEF-frame axes (m/s)

10.7.2.3.74 qzss_l1_code_gen_complex_sampled()

```
void qzss_l1_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    int32_t sampling_freq)
```

Generates complex QZSS L1 C/A code for the desired SV ID, and sampled to specific sampling frequency.

10.7.2.3.75 qzss_l1_code_gen_float()

```
void qzss_l1_code_gen_float (
    own::span< float > dest,
    uint32_t prn)
```

Generates real QZSS L1 C/A code for the desired SV ID.

10.7.2.3.76 qzss_l5i_code_gen_complex_sampled()

```
void qzss_l5i_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    int32_t sampling_freq)
```

Generates complex QZSS L5I code for the desired SV ID, and sampled to specific sampling frequency.

10.7.2.3.77 qzss_l5i_code_gen_float()

```
void qzss_l5i_code_gen_float (
    own::span< float > dest,
    uint32_t prn)
```

Generates real QZSS L5I code for the desired SV ID.

10.7.2.3.78 qzss_l5q_code_gen_complex_sampled()

```
void qzss_l5q_code_gen_complex_sampled (
    own::span< std::complex< float > > dest,
    uint32_t prn,
    int32_t sampling_freq)
```

Generates complex QZSS L5Q code for the desired SV ID, and sampled to specific sampling frequency.

10.7.2.3.79 qzss_l5q_code_gen_float()

```
void qzss_l5q_code_gen_float (
    own::span< float > dest,
    uint32_t prn)
```

Generates real QZSS L5I code for the desired SV ID.

10.7.2.3.80 resample_sensor_data_tags()

```
std::vector< gr::tag_t > resample_sensor_data_tags (
    const std::vector< gr::tag_t > & tags,
    double freq_in,
    double freq_out)
```

Updates timestamp within sensor data tags. To be used in resampler blocks.

Parameters

<i>tags</i>	Stream tags as retrieved by <code>get_tags_in_window</code> or <code>get_tags_in_range</code> .
<i>freq_in</i>	Input RF sample rate.
<i>freq_out</i>	Output RF sample rate.

Returns

Stream tags to be added with `add_item_tag`.

10.7.2.3.81 resampler() [1/2]

```
void resampler (
    const own::span< float > from,
    own::span< float > dest,
    float fs_in,
    float fs_out)
```

This function resamples a sequence of float values.

10.7.2.3.82 resampler() [2/2]

```
void resampler (
    own::span< const std::complex< float > > from,
    own::span< std::complex< float > > dest,
    float fs_in,
    float fs_out)
```

This function resamples a sequence of complex values.

10.7.2.3.83 reset() [1/2]

```
template<class T>
void Gnss_circular_deque< T >::reset ()
```

Removes all the channels (Sets `nchann` to 0)
Definition at line 123 of file [gnss_circular_deque.h](#).

10.7.2.3.84 reset() [2/2]

```
template<class T>
void Gnss_circular_deque< T >::reset (
    unsigned int max_size,
    unsigned int nchann)
```

Removes all the elements in all the channels. Re-sets the number of channels and their capacity.

Definition at line 109 of file [gnss_circular_deque.h](#).

Referenced by [Gnss_circular_deque\(\)](#), and [Gnss_circular_deque\(\)](#).

10.7.2.3.85 size()

```
template<class T>
unsigned int Gnss_circular_deque< T >::size (
    unsigned int ch) const
```

Returns the number of available elements in a channel.

Definition at line 67 of file [gnss_circular_deque.h](#).

10.7.2.3.86 Skew_symmetric()

```
arma::mat Skew_symmetric (
    const arma::vec & a)
```

Calculates skew-symmetric matrix.

10.7.2.3.87 togeod()

```
int togeod (
    double * dphi,
    double * dlambd,
    double * h,
    double a,
    double finv,
    double X,
    double Y,
    double Z)
```

Subroutine to calculate geodetic coordinates latitude, longitude, height given Cartesian coordinates X,Y,Z, and reference ellipsoid values semi-major axis (a) and the inverse of flattening (finv).

The output units of angular quantities will be in decimal degrees (15.5 degrees not 15 deg 30 min). The output units of h will be the same as the units of X,Y,Z,a.

Inputs:

a	- semi-major axis of the reference ellipsoid
finv	- inverse of flattening of the reference ellipsoid
X,Y,Z	- Cartesian coordinates

Outputs:

dphi	- latitude
dlambd	- longitude
h	- height above reference ellipsoid

Based in a Matlab function by Kai Borre

10.7.2.3.88 topocent()

```
int topocent (
    double * Az,
    double * El,
    double * D,
    const arma::vec & x,
    const arma::vec & dx)
```

Transformation of vector dx into topocentric coordinate system with origin at x Inputs: x - vector origin coordinates (in ECEF system [X; Y; Z;]) dx - vector ([dX; dY; dZ;]).

Outputs: D - vector length. Units like the input Az - azimuth from north positive clockwise, degrees El - elevation angle, degrees

Based on a Matlab function by Kai Borre

10.7.3 gnss_sdr_flags**Functions**

- [ABSL_DECLARE_FLAG](#) (std::string, c)
Path to the configuration file.
- [ABSL_DECLARE_FLAG](#) (std::string, config_file)
Path to the configuration file.
- [ABSL_DECLARE_FLAG](#) (std::string, log_dir)
Path to the folder in which logging will be stored.
- [ABSL_DECLARE_FLAG](#) (std::string, s)
Path to the file containing the signal samples.

- `ABSL_DECLARE_FLAG` (std::string, signal_source)
Path to the file containing the signal samples.
- `ABSL_DECLARE_FLAG` (std::string, timestamp_source)
Path to the file containing the signal samples.
- `ABSL_DECLARE_FLAG` (bool, rf_shutdown)
Shutdown RF when program exits.
- `ABSL_DECLARE_FLAG` (int32_t, doppler_max)
If defined, maximum Doppler value in the search grid, in Hz (overrides the configuration file).
- `ABSL_DECLARE_FLAG` (int32_t, doppler_step)
If defined, sets the frequency step in the search grid, in Hz, in Hz (overrides the configuration file).
- `ABSL_DECLARE_FLAG` (int32_t, cn0_samples)
Number of correlator outputs used for CN0 estimation.
- `ABSL_DECLARE_FLAG` (int32_t, cn0_min)
Minimum valid CN0 (in dB-Hz).
- `ABSL_DECLARE_FLAG` (int32_t, max_lock_fail)
Maximum number of code lock failures before dropping a satellite.
- `ABSL_DECLARE_FLAG` (int32_t, max_carrier_lock_fail)
Maximum number of carrier lock failures before dropping a satellite.
- `ABSL_DECLARE_FLAG` (double, carrier_lock_th)
Carrier lock threshold (in rad).
- `ABSL_DECLARE_FLAG` (double, dll_bw_hz)
Bandwidth of the DLL low pass filter, in Hz (overrides the configuration file).
- `ABSL_DECLARE_FLAG` (double, pll_bw_hz)
Bandwidth of the PLL low pass filter, in Hz (overrides the configuration file).
- `ABSL_DECLARE_FLAG` (int32_t, carrier_smoothing_factor)
Sets carrier smoothing factor M (overrides the configuration file).
- `ABSL_DECLARE_FLAG` (std::string, RINEX_version)
If defined, specifies the RINEX version (2.11 or 3.02). Overrides the configuration file.
- `ABSL_DECLARE_FLAG` (std::string, RINEX_name)
If defined, specifies the RINEX files base name.
- `ABSL_DECLARE_FLAG` (bool, keyboard)
If set to false, disables the keyboard listener. Only for debug purposes (e.g. ASAN mode termination)
- bool `ValidateFlags` ()

Variables

- const int32_t `DEFAULT_CARRIER_SMOOTHING_FACTOR` = 200

10.7.3.1 Detailed Description

Library for command-line handling.

10.7.3.2 Function Documentation

10.7.3.2.1 `ABSL_DECLARE_FLAG()` [1/20]

```
ABSL_DECLARE_FLAG (
    bool ,
    keyboard )
```

If set to false, disables the keyboard listener. Only for debug purposes (e.g. ASAN mode termination)

10.7.3.2.2 ABSL_DECLARE_FLAG() [2/20]

```
ABSL_DECLARE_FLAG (
    bool ,
    rf_shutdown )
```

Shutdown RF when program exits.

10.7.3.2.3 ABSL_DECLARE_FLAG() [3/20]

```
ABSL_DECLARE_FLAG (
    double ,
    carrier_lock_th )
```

Carrier lock threshold (in rad).

10.7.3.2.4 ABSL_DECLARE_FLAG() [4/20]

```
ABSL_DECLARE_FLAG (
    double ,
    dll_bw_hz )
```

Bandwidth of the DLL low pass filter, in Hz (overrides the configuration file).

10.7.3.2.5 ABSL_DECLARE_FLAG() [5/20]

```
ABSL_DECLARE_FLAG (
    double ,
    pll_bw_hz )
```

Bandwidth of the PLL low pass filter, in Hz (overrides the configuration file).

10.7.3.2.6 ABSL_DECLARE_FLAG() [6/20]

```
ABSL_DECLARE_FLAG (
    int32_t ,
    carrier_smoothing_factor )
```

Sets carrier smoothing factor M (overrides the configuration file).

10.7.3.2.7 ABSL_DECLARE_FLAG() [7/20]

```
ABSL_DECLARE_FLAG (
    int32_t ,
    cn0_min )
```

Minimum valid CN0 (in dB-Hz).

10.7.3.2.8 ABSL_DECLARE_FLAG() [8/20]

```
ABSL_DECLARE_FLAG (
    int32_t ,
    cn0_samples )
```

Number of correlator outputs used for CN0 estimation.

10.7.3.2.9 ABSL_DECLARE_FLAG() [9/20]

```
ABSL_DECLARE_FLAG (
    int32_t ,
    doppler_max )
```

If defined, maximum Doppler value in the search grid, in Hz (overrides the configuration file).

10.7.3.2.10 ABSL_DECLARE_FLAG() [10/20]

```
ABSL_DECLARE_FLAG (
    int32_t ,
    doppler_step )
```

If defined, sets the frequency step in the search grid, in Hz, in Hz (overrides the configuration file).

10.7.3.2.11 ABSL_DECLARE_FLAG() [11/20]

```
ABSL_DECLARE_FLAG (
    int32_t ,
    max_carrier_lock_fail )
```

Maximum number of carrier lock failures before dropping a satellite.

10.7.3.2.12 ABSL_DECLARE_FLAG() [12/20]

```
ABSL_DECLARE_FLAG (
    int32_t ,
    max_lock_fail )
```

Maximum number of code lock failures before dropping a satellite.

10.7.3.2.13 ABSL_DECLARE_FLAG() [13/20]

```
ABSL_DECLARE_FLAG (
    std::string ,
    c )
```

Path to the configuration file.

10.7.3.2.14 ABSL_DECLARE_FLAG() [14/20]

```
ABSL_DECLARE_FLAG (
    std::string ,
    config_file )
```

Path to the configuration file.

10.7.3.2.15 ABSL_DECLARE_FLAG() [15/20]

```
ABSL_DECLARE_FLAG (
    std::string ,
    log_dir )
```

Path to the folder in which logging will be stored.

10.7.3.2.16 ABSL_DECLARE_FLAG() [16/20]

```
ABSL_DECLARE_FLAG (
    std::string ,
    RINEX_name )
```

If defined, specifies the RINEX files base name.

10.7.3.2.17 ABSL_DECLARE_FLAG() [17/20]

```
ABSL_DECLARE_FLAG (
    std::string ,
    RINEX_version )
```

If defined, specifies the RINEX version (2.11 or 3.02). Overrides the configuration file.

10.7.3.2.18 ABSL_DECLARE_FLAG() [18/20]

```
ABSL_DECLARE_FLAG (
    std::string ,
    s )
```

Path to the file containing the signal samples.

10.7.3.2.19 ABSL_DECLARE_FLAG() [19/20]

```
ABSL_DECLARE_FLAG (
    std::string ,
    signal_source )
```

Path to the file containing the signal samples.

10.7.3.2.20 ABSL_DECLARE_FLAG() [20/20]

```
ABSL_DECLARE_FLAG (
    std::string ,
    timestamp_source )
```

Path to the file containing the signal samples.

10.7.3.3 Variable Documentation**10.7.3.3.1 DEFAULT_CARRIER_SMOOTHING_FACTOR**

```
const int32_t DEFAULT_CARRIER_SMOOTHING_FACTOR = 200
```

Definition at line 103 of file [gnss_sdr_flags.h](#).

10.8 PVT**Topics**

- [algorithms_libs_rtklib](#)
- [pvt_adapters](#)
- [pvt_gr_blocks](#)
- [pvt_libs](#)

10.8.1 Detailed Description

Computation of Position, Velocity and Time from GNSS observables.

10.8.2 algorithms_libs_rtklib**Classes**

- struct [gtime_t](#)
- struct [obsd_t](#)
- struct [obs_t](#)
- struct [erpd_t](#)
- struct [erp_t](#)
- struct [pcv_t](#)
- struct [pcvs_t](#)
- struct [alm_t](#)
- struct [eph_t](#)
- struct [geph_t](#)
- struct [peph_t](#)
- struct [pclk_t](#)
- struct [seph_t](#)

- struct [tled_t](#)
- struct [tle_t](#)
- struct [tec_t](#)
- struct [fcbd_t](#)
- struct [sbsmsg_t](#)
- struct [sbs_t](#)
- struct [sbsfcrr_t](#)
- struct [sbslcorr_t](#)
- struct [sbssatp_t](#)
- struct [sbssat_t](#)
- struct [sbsigp_t](#)
- struct [sbsigpband_t](#)
- struct [sbsion_t](#)
- struct [dgps_t](#)
- struct [ssr_t](#)
- struct [lexmsg_t](#)
- struct [lex_t](#)
- struct [lexeph_t](#)
- struct [lexion_t](#)
- struct [stec_t](#)
- struct [trop_t](#)
- struct [pppcorr_t](#)
- struct [nav_t](#)
- struct [sta_t](#)
- struct [sol_t](#)
- struct [solbuf_t](#)
- struct [solstat_t](#)
- struct [solstatbuf_t](#)
- struct [rtcm_t](#)
- struct [url_t](#)
- struct [opt_t](#)
- struct [exterr_t](#)
- struct [snrmask_t](#)
- struct [prcopt_t](#)
- struct [solopt_t](#)
- struct [ssat_t](#)
- struct [ambc_t](#)
- struct [rtk_t](#)
- struct [half_cyc_tag](#)
- struct [stream_t](#)
- struct [serial_t](#)
- struct [file_t](#)
- struct [tcp_t](#)
- struct [tcpsvr_t](#)
- struct [tcpcli_t](#)
- struct [ntrip_t](#)
- struct [ftp_t](#)
- struct [raw_t](#)
- struct [rtksvr_t](#)
- struct [msm_h_t](#)
- class [HAS_clock_corrections](#)
- class [HAS_orbit_corrections](#)
- class [HAS_obs_corrections](#)

Macros

- #define `dev_t` int
- #define `socket_t` int
- #define `closesocket` close
- #define `lock_t` pthread_mutex_t
- #define `initlock(f)`
- #define `rtk_lock(f)`
- #define `rtk_unlock(f)`
- #define `VER_RTKLIB` "2.4.2"
- #define `NTRIP_AGENT` "RTKLIB/" VER_RTKLIB
- #define `NTRIP_CLI_PORT` 2101 /* default ntrip-client connection port */
- #define `NTRIP_SVR_PORT` 80 /* default ntrip-server connection port */
- #define `NTRIP_MAXRSP` 32768 /* max size of ntrip response */
- #define `NTRIP_MAXSTR` 256 /* max length of mountpoint string */
- #define `NTRIP_RSP_OK_CLI` "ICY 200 OK\r\n" /* ntrip response: client */
- #define `NTRIP_RSP_OK_SVR` "OK\r\n" /* ntrip response: server */
- #define `NTRIP_RSP_SRCTBL` "SOURCETABLE 200 OK\r\n" /* ntrip response: source table */
- #define `NTRIP_RSP_TBLEND` "ENDSOURCETABLE"
- #define `NTRIP_RSP_HTTP` "HTTP/" /* ntrip response: http */
- #define `NTRIP_RSP_ERROR` "ERROR" /* ntrip response: error */
- #define `FTP_CMD` "wget" /* ftp/http command */
- #define `ENAGLO`
- #define `ENAZQS`
- #define `ENABDS`
- #define `STR_MODE_R` 0x1 /* stream mode: read */
- #define `STR_MODE_W` 0x2 /* stream mode: write */
- #define `STR_MODE_RW` 0x3 /* stream mode: read/write */
- #define `STR_NONE` 0 /* stream type: none */
- #define `STR_SERIAL` 1 /* stream type: serial */
- #define `STR_FILE` 2 /* stream type: file */
- #define `STR_TCPSVR` 3 /* stream type: TCP server */
- #define `STR_TCPCLI` 4 /* stream type: TCP client */
- #define `STR_UDP` 5 /* stream type: UDP stream */
- #define `STR_NTRIPSVR` 6 /* stream type: NTRIP server */
- #define `STR_NTRIPCLI` 7 /* stream type: NTRIP client */
- #define `STR_FTP` 8 /* stream type: ftp */
- #define `STR_HTTP` 9 /* stream type: http */
- #define `NP_PPP`(opt)
- #define `IC_PPP`(s, opt)
- #define `IT_PPP`(opt)
- #define `NR_PPP`(opt)
- #define `IB_PPP`(s, opt)
- #define `NX_PPP`(opt)
- #define `NF_RTK`(opt)
- #define `NP_RTK`(opt)
- #define `NI_RTK`(opt)
- #define `NT_RTK`(opt)
- #define `NL_RTK`(opt)
- #define `NB_RTK`(opt)
- #define `NR_RTK`(opt)
- #define `NX_RTK`(opt)
- #define `II_RTK`(s, opt)
- #define `IT_RTK`(r, opt)
- #define `IL_RTK`(f, opt)
- #define `IB_RTK`(s, f, opt)
- #define `COMMENTH` "%" /* comment line indicator for solution */
- #define `MSG_DISCONNECT` "\$_DISCONNECT\r\n" /* disconnect message */

Typedefs

- using [fatalfunc_t](#) = void(const char *)
fatal callback function type
- typedef struct [half_cyc_tag](#) [half_cyc_t](#)

Functions

- [eph_t eph_to_rtklib](#) (const [Galileo_Ephemeris](#) &gal_eph)
- [eph_t eph_to_rtklib](#) (const [Galileo_Ephemeris](#) &gal_eph, const std::map< int, [HAS_orbit_corrections](#) > &orbit_correction_map, const std::map< int, [HAS_clock_corrections](#) > &clock_correction_map)
- [eph_t eph_to_rtklib](#) (const [Gps_Ephemeris](#) &gps_eph, bool pre_2009_file=false)
- [eph_t eph_to_rtklib](#) (const [Gps_Ephemeris](#) &gps_eph, const std::map< int, [HAS_orbit_corrections](#) > &orbit_correction_map, const std::map< int, [HAS_clock_corrections](#) > &clock_correction_map, bool pre_2009_file=false)
- [eph_t eph_to_rtklib](#) (const [Gps_CNAV_Ephemeris](#) &gps_cnav_eph)
- [eph_t eph_to_rtklib](#) (const [Beidou_Dnav_Ephemeris](#) &bei_eph)
- [alm_t alm_to_rtklib](#) (const [Gps_Almanac](#) &gps_alm)
- [alm_t alm_to_rtklib](#) (const [Galileo_Almanac](#) &gal_alm)
- [geph_t eph_to_rtklib](#) (const [Glonass_Gnav_Ephemeris](#) &glonass_gnav_eph, const [Glonass_Gnav_Utc_Model](#) &gnav_clock_model)
Transforms a [Glonass_Gnav_Ephemeris](#) to its RTKLIB counterpart.
- [obsd_t insert_obs_to_rtklib](#) ([obsd_t](#) &rtklib_obs, const [Gnss_Synchro](#) &gnss_synchro, const std::map< std::string, std::map< int, [HAS_obs_corrections](#) > > &has_obs_corr, int week, int band, bool pre_2009_file=false)
- [obsd_t insert_obs_to_rtklib](#) ([obsd_t](#) &rtklib_obs, const [Gnss_Synchro](#) &gnss_synchro, int week, int band, bool pre_2009_file=false)
- int [rtkopenstat](#) (const char *file, int level)
- void [rtkclosestat](#) ()
- void [rtkoutstat](#) ([rtk_t](#) *rtk)
- void [swapsolstat](#) ()
- void [outsolstat](#) ([rtk_t](#) *rtk)
- void [errmsg](#) ([rtk_t](#) *rtk, const char *format,...)
- double [sdoobs](#) (const [obsd_t](#) *obs, int i, int j, int f)
- double [gfoobs_L1L2](#) (const [obsd_t](#) *obs, int i, int j, const double *lam)
- double [gfoobs_L1L5](#) (const [obsd_t](#) *obs, int i, int j, const double *lam)
- double [varerr](#) (int sat, int sys, double el, double bl, double dt, int f, const [prcopt_t](#) *opt)
- double [baseline](#) (const double *ru, const double *rb, double *dr)
- void [initx_rtk](#) ([rtk_t](#) *rtk, double xi, double var, int i)
- int [selsat](#) (const [obsd_t](#) *obs, const double *azel, int nu, int nr, const [prcopt_t](#) *opt, int *sat, int *iu, int *ir)
- void [udpos](#) ([rtk_t](#) *rtk, double tt)
- void [udion](#) ([rtk_t](#) *rtk, double tt, double bl, const int *sat, int ns)
- void [udtrop](#) ([rtk_t](#) *rtk, double tt, double bl)
- void [udrcvbias](#) ([rtk_t](#) *rtk, double tt)
- void [detslp_II](#) ([rtk_t](#) *rtk, const [obsd_t](#) *obs, int i, int rcv)
- void [detslp_gf_L1L2](#) ([rtk_t](#) *rtk, const [obsd_t](#) *obs, int i, int j, const [nav_t](#) *nav)
- void [detslp_gf_L1L5](#) ([rtk_t](#) *rtk, const [obsd_t](#) *obs, int i, int j, const [nav_t](#) *nav)
- void [detslp_dop](#) ([rtk_t](#) *rtk, const [obsd_t](#) *obs, int i, int rcv, const [nav_t](#) *nav)
- void [udbias](#) ([rtk_t](#) *rtk, double tt, const [obsd_t](#) *obs, const int *sat, const int *iu, const int *ir, int ns, const [nav_t](#) *nav)
- void [udstate](#) ([rtk_t](#) *rtk, const [obsd_t](#) *obs, const int *sat, const int *iu, const int *ir, int ns, const [nav_t](#) *nav)
- void [zdres_sat](#) (int base, double r, const [obsd_t](#) *obs, const [nav_t](#) *nav, const double *azel, const double *dant, const [prcopt_t](#) *opt, double *y)
- int [zdres](#) (int base, const [obsd_t](#) *obs, int n, const double *rs, const double *dts, const int *svh, const [nav_t](#) *nav, const double *rr, const [prcopt_t](#) *opt, int index, double *y, double *e, double *azel)
- int [validobs](#) (int i, int j, int f, int nf, const double *y)

- void **ddcov** (const int *nb, int n, const double *Ri, const double *Rj, int nv, double *R)
- int **constbl** (rtk_t *rtk, const double *x, const double *P, double *v, double *H, double *Ri, double *Rj, int index)
- double **prectrop** (gtime_t time, const double *pos, int r, const double *azel, const prcopt_t *opt, const double *x, double *dtdx)
- double **gloicbcorr** (int sat1, int sat2, const prcopt_t *opt, double lam1, double lam2, int f)
- int **test_sys** (int sys, int m)
- int **ddres** (rtk_t *rtk, const nav_t *nav, double dt, const double *x, const double *P, const int *sat, double *y, const double *e, double *azel, const int *iu, const int *ir, int ns, double *v, double *H, double *R, int *vflg)
- double **intpres** (gtime_t time, const obsd_t *obs, int n, const nav_t *nav, rtk_t *rtk, double *y)
- int **ddmat** (rtk_t *rtk, double *D)
- void **restamb** (rtk_t *rtk, const double *bias, int nb, double *xa)
- void **holdamb** (rtk_t *rtk, const double *xa)
- int **resamb_LAMBDA** (rtk_t *rtk, double *bias, double *xa)
- int **valpos** (rtk_t *rtk, const double *v, const double *R, const int *vflg, int nv, double thres)
- int **relpos** (rtk_t *rtk, const obsd_t *obs, int nu, int nr, const nav_t *nav)
- void **rtkinit** (rtk_t *rtk, const prcopt_t *opt)
- void **rtkfree** (rtk_t *rtk)
- int **rtkpos** (rtk_t *rtk, const obsd_t *obs, int n, const nav_t *nav)
- const char * **opt2sep** (const solopt_t *opt)
- int **tonum** (char *buff, const char *sep, double *v)
- double **sqvar** (double covar)
- double **dmm2deg** (double dmm)
- void **septime** (double t, double *t1, double *t2, double *t3)
- void **soltocov** (const sol_t *sol, double *P)
- void **covtosol** (const double *P, sol_t *sol)
- int **decode_nmearmc** (char **val, int n, sol_t *sol)
- int **decode_nmeagga** (char **val, int n, sol_t *sol)
- int **decode_nmea** (char *buff, sol_t *sol)
- char * **decode_soltime** (char *buff, const solopt_t *opt, gtime_t *time)
- int **decode_solxyz** (char *buff, const solopt_t *opt, sol_t *sol)
- int **decode_solllh** (char *buff, const solopt_t *opt, sol_t *sol)
- int **decode_solenu** (char *buff, const solopt_t *opt, sol_t *sol)
- int **decode_solgsi** (char *buff, const solopt_t *opt, sol_t *sol)
- int **decode_solpos** (char *buff, const solopt_t *opt, sol_t *sol)
- void **decode_refpos** (char *buff, const solopt_t *opt, double *rb)
- int **decode_sol** (char *buff, const solopt_t *opt, sol_t *sol, double *rb)
- void **decode_solo** (char *buff, solopt_t *opt)
- void **readsolo** (FILE *fp, solopt_t *opt)
- int **inputsol** (unsigned char data, gtime_t ts, gtime_t te, double tint, int qflag, const solopt_t *opt, solbuf_t *solbuf)
- int **readsoldata** (FILE *fp, gtime_t ts, gtime_t te, double tint, int qflag, const solopt_t *opt, solbuf_t *solbuf)
- int **cmpsol** (const void *p1, const void *p2)
- int **sort_solbuf** (solbuf_t *solbuf)
- int **readsolt** (char *files[], int nfile, gtime_t ts, gtime_t te, double tint, int qflag, solbuf_t *solbuf)
- int **readsol** (char *files[], int nfile, solbuf_t *sol)
- int **addsol** (solbuf_t *solbuf, const sol_t *sol)
- sol_t * **getsol** (solbuf_t *solbuf, int index)
- void **initsolbuf** (solbuf_t *solbuf, int cyclic, int nmax)
- void **freesolbuf** (solbuf_t *solbuf)
- void **freesolstatbuf** (solstatbuf_t *solstatbuf)
- int **cmpsolstat** (const void *p1, const void *p2)
- int **sort_solstat** (solstatbuf_t *statbuf)
- int **decode_solstat** (char *buff, solstat_t *stat)
- void **addsolstat** (solstatbuf_t *statbuf, const solstat_t *stat)

- int **readsolstatdata** (FILE *fp, [gtime_t](#) ts, [gtime_t](#) te, double tint, [solstatbuf_t](#) *statbuf)
- int **readsolstatt** (char *files[], int nfile, [gtime_t](#) ts, [gtime_t](#) te, double tint, [solstatbuf_t](#) *statbuf)
- int **readsolstat** (char *files[], int nfile, [solstatbuf_t](#) *statbuf)
- int **outecef** (unsigned char *buff, const char *s, const [sol_t](#) *sol, const [solopt_t](#) *opt)
- int **outpos** (unsigned char *buff, const char *s, const [sol_t](#) *sol, const [solopt_t](#) *opt)
- int **outenu** (unsigned char *buff, const char *s, const [sol_t](#) *sol, const double *rb, const [solopt_t](#) *opt)
- int **outnmea_rmc** (unsigned char *buff, const [sol_t](#) *sol)
- int **outnmea_gga** (unsigned char *buff, const [sol_t](#) *sol)
- int **outnmea_gsa** (unsigned char *buff, const [sol_t](#) *sol, const [ssat_t](#) *ssat)
- int **outnmea_gsv** (unsigned char *buff, const [sol_t](#) *sol, const [ssat_t](#) *ssat)
- int **outprcopts** (unsigned char *buff, const [prcopt_t](#) *opt)
- int **outsolheads** (unsigned char *buff, const [solopt_t](#) *opt)
- int **outsols** (unsigned char *buff, const [sol_t](#) *sol, const double *rb, const [solopt_t](#) *opt)
- int **outsollexs** (unsigned char *buff, const [sol_t](#) *sol, const [ssat_t](#) *ssat, const [solopt_t](#) *opt)
- void **outprcopt** (FILE *fp, const [prcopt_t](#) *opt)
- void **outsolhead** (FILE *fp, const [solopt_t](#) *opt)
- void **outsol** (FILE *fp, const [sol_t](#) *sol, const double *rb, const [solopt_t](#) *opt)
- void **outsollex** (FILE *fp, const [sol_t](#) *sol, const [ssat_t](#) *ssat, const [solopt_t](#) *opt)

Variables

- const int **TINTACT** = 200
period for stream active (ms)
- const int **SERIBUFFSIZE** = 4096
serial buffer size (bytes)
- const int **TIMETAGH_LEN** = 64
time tag file header length
- const int **MAXCLI** = 32
max client connection for tcp svr
- const int **MAXSTATMSG** = 32
max length of status message
- const int **FTP_TIMEOUT** = 30
ftp/http timeout (s)
- const int **MAXRAWLEN** = 4096
max length of receiver raw message
- const int **MAXSOLBUF** = 256
max number of solution buffer
- const int **MAXSBMSG** = 32
max number of SBAS msg in RTK server
- const int **MAXOBSBUF** = 128
max number of observation data buffer
- const int **FILEPATHSEP** = '/'
- const double **RE_WGS84** = 6378137.0
earth semimajor axis (WGS84) (m)
- const double **FE_WGS84** = (1.0 / 298.257223563)
earth flattening (WGS84)
- const double **HION** = 350000.0
ionosphere height (m)
- const double **PRN_HWBIAS** = 1e-6
process noise of h/w bias (m/MHz/sqrt(s))
- const double **INT_SWAP_STAT** = 86400.0
swap interval of solution status file (s)
- const double **INT_SWAP_TRAC** = 86400.0

- swap interval of trace file (s)*
- const unsigned int POLYCRC32 = 0xEDB88320u
CRC32 polynomial.
- const unsigned int POLYCRC24Q = 0x1864CFBu
CRC24Q polynomial.
- const int PMODE_SINGLE = 0
positioning mode: single
- const int PMODE_DGPS = 1
positioning mode: DGPS/DGNSS
- const int PMODE_KINEMA = 2
positioning mode: kinematic
- const int PMODE_STATIC = 3
positioning mode: static
- const int PMODE_MOVEB = 4
positioning mode: moving-base
- const int PMODE_FIXED = 5
positioning mode: fixed
- const int PMODE_PPP_KINEMA = 6
positioning mode: PPP-kinematic
- const int PMODE_PPP_STATIC = 7
positioning mode: PPP-static
- const int PMODE_PPP_FIXED = 8
positioning mode: PPP-fixed
- const int SOLF_LLH = 0
solution format: lat/lon/height
- const int SOLF_XYZ = 1
solution format: x/y/z-ecef
- const int SOLF_ENU = 2
solution format: e/n/u-baseline
- const int SOLF_NMEA = 3
solution format: NMEA-183
- const int SOLF_STAT = 4
solution format: solution status
- const int SOLF_GSIF = 5
solution format: GSI F1/F2
- const int SOLQ_NONE = 0
solution status: no solution
- const int SOLQ_FIX = 1
solution status: fix
- const int SOLQ_FLOAT = 2
solution status: float
- const int SOLQ_SBAS = 3
solution status: SBAS
- const int SOLQ_DGPS = 4
solution status: DGPS/DGNSS
- const int SOLQ_SINGLE = 5
solution status: single
- const int SOLQ_PPP = 6
solution status: PPP
- const int SOLQ_DR = 7
solution status: dead reckoning

- const int `MAXSOLQ` = 7
max number of solution status
- const int `TIMES_GPST` = 0
time system: gps time
- const int `TIMES_UTC` = 1
time system: utc
- const int `TIMES_JST` = 2
time system: jst
- const double `ERR_SAAS` = 0.3
saastamoinen model error std (m)
- const double `ERR_BRDCI` = 0.5
broadcast iono model error factor
- const double `ERR_CBIAS` = 0.3
code bias error std (m)
- const double `REL_HUMI` = 0.7
relative humidity for saastamoinen model
- const double `GAP_RESION` = 120
default gap to reset ionos parameters (ep)
- const int `MAXFREQ` = 7
max NFREQ
- const int `MAXLEAPS` = 64
max number of leap seconds table
- const double `DTTOL` = 0.005
tolerance of time difference (s)
- const int `NFREQ` = 3
number of carrier frequencies
- const int `NFREQGLO` = 2
number of carrier frequencies of GLONASS
- const int `NEXOBS` = 0
number of extended obs codes
- const int `MAXANT` = 64
max length of station name/antenna type
- const int `MINPRNGPS` = 1
min satellite PRN number of GPS
- const int `MAXPRNGPS` = 32
max satellite PRN number of GPS
- const int `NSATGPS` = (`MAXPRNGPS` - `MINPRNGPS` + 1)
number of GPS satellites
- const int `NSYSGPS` = 1
- const int `SYS_NONE` = 0x00
navigation system: none
- const int `SYS_GPS` = 0x01
navigation system: GPS
- const int `SYS_SBS` = 0x02
navigation system: SBAS
- const int `SYS_GLO` = 0x04
navigation system: GLONASS
- const int `SYS_GAL` = 0x08
navigation system: Galileo
- const int `SYS_QZS` = 0x10
navigation system: QZSS

- const int **SYS_BDS** = 0x20
navigation system: BeiDou
- const int **SYS_IRN** = 0x40
navigation system: IRNS
- const int **SYS_LEO** = 0x80
navigation system: LEO
- const int **SYS_ALL** = 0xFF
navigation system: all
- const int **MINPRNGLO** = 1
min satellite slot number of GLONASS
- const int **MAXPRNGLO** = 27
max satellite slot number of GLONASS
- const int **NSATGLO** = (**MAXPRNGLO** - **MINPRNGLO** + 1)
number of GLONASS satellites
- const int **NSYSGLO** = 1
- const int **MINPRNGAL** = 1
min satellite PRN number of Galileo
- const int **MAXPRNGAL** = 36
max satellite PRN number of Galileo
- const int **NSATGAL** = (**MAXPRNGAL** - **MINPRNGAL** + 1)
number of Galileo satellites
- const int **NSYSGAL** = 1
- const int **MAXPRNQZS** = 202
max satellite PRN number of QZSS
- const int **MINPRNQZS** = 193
min satellite PRN number of QZSS
- const int **MINPRNQZS_S** = 183
min satellite PRN number of QZSS SAIF
- const int **MAXPRNQZS_S** = 191
max satellite PRN number of QZSS SAIF
- const int **NSATQZS** = (**MAXPRNQZS** - **MINPRNQZS** + 1)
number of QZSS satellites
- const int **NSYSQZS** = 1
- const int **MINPRNBDS** = 1
min satellite sat number of BeiDou
- const int **MAXPRNBDS** = 63
max satellite sat number of BeiDou
- const int **NSATBDS** = (**MAXPRNBDS** - **MINPRNBDS** + 1)
number of BeiDou satellites
- const int **NSYSBDS** = 1
- const int **MINPRNIRN** = 1
min satellite sat number of IRNSS
- const int **MAXPRNIRN** = 7
max satellite sat number of IRNSS
- const int **NSATIRN** = 0
- const int **NSYSIRN** = 0
- const int **MINPRNLEO** = 1
min satellite sat number of LEO
- const int **MAXPRNLEO** = 10
*max satellite sat number of LEO */*
- const int **NSATLEO** = 0

- const int **NSYSLEO** = 0
- const int **NSYS** = (NSYSGPS + NSYSGLO + NSYSGAL + NSYSQZS + NSYSBDS + NSYSIRN + NSYSLEO)
number of systems
- const int **MINPRNSBS** = 120
min satellite PRN number of SBAS
- const int **MAXPRNSBS** = 142
max satellite PRN number of SBAS
- const int **NSATSBS** = (**MAXPRNSBS** - **MINPRNSBS** + 1)
number of SBAS satellites
- const int **MAXSAT** = (**NSATGPS** + **NSATGLO** + **NSATGAL** + **NSATQZS** + **NSATBDS** + **NSATIRN** + **NSATSBS** + **NSATLEO**)
- const int **MAXSTA** = 255
- const int **MAXOBS** = 64
max number of obs in an epoch
- const int **MAXRCV** = 64
max receiver number (1 to MAXRCV)
- const int **MAXOBS** = 64
max number of obs type in RINEX
- const double **MAXD** = 7200.0
max time difference to GPS Toe (s)
- const double **MAXD_QZS** = 7200.0
max time difference to QZSS Toe (s)
- const double **MAXD_GAL** = 10800.0
max time difference to Galileo Toe (s)
- const double **MAXD_BDS** = 21600.0
max time difference to BeiDou Toe (s)
- const double **MAXD_GLO** = 1800.0
max time difference to GLONASS Toe (s)
- const double **MAXD_SBS** = 360.0
max time difference to SBAS Toe (s)
- const double **MAXD_S** = 86400.0
max time difference to ephemeris toe (s) for other
- const double **MAXGDOP** = 300.0
max GDOP
- const int **MAXSBSURA** = 8
max URA of SBAS satellite
- const int **MAXBAND** = 10
max SBAS band of IGP
- const int **MAXNIGP** = 201
max number of IGP in SBAS band
- const int **MAXNGEO** = 4
max number of GEO satellites
- const int **MAXSOLMSG** = 8191
max length of solution message
- const int **MAXERRMSG** = 4096
max length of error/warning message
- const int **IONOOPT_OFF** = 0
ionosphere option: correction off
- const int **IONOOPT_BRDC** = 1
ionosphere option: broadcast model
- const int **IONOOPT_SBAS** = 2

- ionosphere option: SBAS model*
 - const int `IONOOPT_IFLC` = 3
- ionosphere option: L1/L2 or L1/L5 iono-free LC*
 - const int `IONOOPT_EST` = 4
- ionosphere option: estimation*
 - const int `IONOOPT_TEC` = 5
- ionosphere option: IONEX TEC model*
 - const int `IONOOPT_QZS` = 6
- ionosphere option: QZSS broadcast model*
 - const int `IONOOPT_LEX` = 7
- ionosphere option: QZSS LEX ionosphere*
 - const int `IONOOPT_STEC` = 8
- ionosphere option: SLANT TEC model*
 - const int `TROPOPT_OFF` = 0
- troposphere option: correction off*
 - const int `TROPOPT_SAAS` = 1
- troposphere option: Saastamoinen model*
 - const int `TROPOPT_SBAS` = 2
- troposphere option: SBAS model*
 - const int `TROPOPT_EST` = 3
- troposphere option: ZTD estimation*
 - const int `TROPOPT_ESTG` = 4
- troposphere option: ZTD+grad estimation*
 - const int `TROPOPT_COR` = 5
- troposphere option: ZTD correction*
 - const int `TROPOPT_CORG` = 6
- troposphere option: ZTD+grad correction*
 - const int `EPHOPT_BRDC` = 0
- ephemeris option: broadcast ephemeris*
 - const int `EPHOPT_PREC` = 1
- ephemeris option: precise ephemeris*
 - const int `EPHOPT_SBAS` = 2
- ephemeris option: broadcast + SBAS*
 - const int `EPHOPT_SSRAPC` = 3
- ephemeris option: broadcast + SSR_APC*
 - const int `EPHOPT_SSRCOM` = 4
- ephemeris option: broadcast + SSR_COM*
 - const int `EPHOPT_LEX` = 5
- ephemeris option: QZSS LEX ephemeris*
 - const double `EFACT_GPS` = 1.0
- error factor: GPS*
 - const double `EFACT_GLO` = 1.5
- error factor: GLONASS*
 - const double `EFACT_GAL` = 1.0
- error factor: Galileo*
 - const double `EFACT_QZS` = 1.0
- error factor: QZSS*
 - const double `EFACT_BDS` = 1.0
- error factor: BeiDou*
 - const double `EFACT_IRN` = 1.5
- error factor: IRNSS*

- const double `EFACT_SBS` = 3.0
error factor: SBAS
- const int `MAXEXFILE` = 1024
max number of expanded files
- const double `MAXSBSAGEF` = 30.0
max age of SBAS fast correction (s)
- const double `MAXSBSAGEL` = 1800.0
max age of SBAS long term corr (s)
- const int `ARMODE_OFF` = 0
AR mode: off.
- const int `ARMODE_CONT` = 1
AR mode: continuous.
- const int `ARMODE_INST` = 2
AR mode: instantaneous.
- const int `ARMODE_FIXHOLD` = 3
AR mode: fix and hold.
- const int `ARMODE_PPPAR` = 4
AR mode: PPP-AR.
- const int `ARMODE_PPPAR_ILS` = 5
AR mode: AR mode: PPP-AR ILS.
- const int `ARMODE_WLNL` = 6
- const int `ARMODE_TCAR` = 7
- const int `POSOPT_RINEX` = 3
pos option: rinex header pos
- const int `MAXSTRPATH` = 1024
max length of stream path
- const int `MAXSTRMSG` = 1024
max length of stream message
- const double `CHISQR` [100]
- const double `LAM_CARR` [MAXFREQ]
- const int `STRFMT_RTCM2` = 0
- const int `STRFMT_RTCM3` = 1
- const int `STRFMT_SP3` = 16
- const int `STRFMT_RNXCLK` = 17
- const int `STRFMT_SBAS` = 18
- const int `STRFMT_NMEA` = 19
- const int `MAXSTRRTK` = 8
- const double `VAR_POS` = std::pow(30.0, 2.0)
- const double `VAR_VEL` = std::pow(10.0, 2.0)
- const double `VAR_ACC` = std::pow(10.0, 2.0)
- const double `VAR_HWBIAS` = std::pow(1.0, 2.0)
- const double `VAR_GRA` = std::pow(0.001, 2.0)
- const double `INIT_ZWD` = 0.15
- const double `PRN_HWBIA` = 1E-6
- const double `MAXAC` = 30.0
- const double `VAR_HOLDAMB` = 0.001
- const double `TTOL_MOVEB` = (1.0 + 2 * `DTTOL`)

10.8.2.1 Detailed Description

Our version of the RTKLIB core library (see <http://www.rtklib.com/>)

10.8.2.2 Macro Definition Documentation

10.8.2.2.1 closesocket

```
#define closesocket close
```

Definition at line 59 of file [rtklib.h](#).

10.8.2.2.2 COMMENTH

```
#define COMMENTH "%" /* comment line indicator for solution */
```

Definition at line 43 of file [rtklib_solution.h](#).

10.8.2.2.3 dev_t

```
#define dev_t int
```

Definition at line 57 of file [rtklib.h](#).

10.8.2.2.4 ENABDS

```
#define ENABDS
```

Definition at line 203 of file [rtklib.h](#).

10.8.2.2.5 ENAGLO

```
#define ENAGLO
```

Definition at line 170 of file [rtklib.h](#).

10.8.2.2.6 ENAQZS

```
#define ENAQZS
```

Definition at line 191 of file [rtklib.h](#).

10.8.2.2.7 FTP_CMD

```
#define FTP_CMD "wget" /* ftp/http command */
```

Definition at line 78 of file [rtklib.h](#).

10.8.2.2.8 IB_PPP

```
#define IB_PPP(  
    s,  
    opt)
```

Value:

```
(NR_PPP(opt) + (s)-1) /* state index of  
    phase bias */
```

Definition at line 343 of file [rtklib.h](#).

10.8.2.2.9 IB_RTK

```
#define IB_RTK(  
    s,  
    f,  
    opt)
```

Value:

```
(NR_RTK(opt) + MAXSAT * (f) + (s)-1) /* phase bias (s:satno,f:freq) */
```

Definition at line 68 of file [rtklib_rtkpos.h](#).

10.8.2.2.10 IC_PPP

```
#define IC_PPP(
    s,
    opt)
```

Value:

```
(NP_PPP(opt) + (s)) /* state index of
    clocks (s=0:gps,1:glo) */
```

Definition at line 340 of file [rtklib.h](#).

10.8.2.2.11 II_RTK

```
#define II_RTK(
    s,
    opt)
```

Value:

```
(NP_RTK(opt) + (s)-1) /* ionos (s:satellite no) */
```

Definition at line 65 of file [rtklib_rtkpos.h](#).

10.8.2.2.12 IL_RTK

```
#define IL_RTK(
    f,
    opt)
```

Value:

```
(NP_RTK(opt) + NI_RTK(opt) + NT_RTK(opt) + (f)) /* receiver h/w bias */
```

Definition at line 67 of file [rtklib_rtkpos.h](#).

10.8.2.2.13 initlock

```
#define initlock(
    f)
```

Value:

```
pthread_mutex_init(f, NULL)
```

Definition at line 61 of file [rtklib.h](#).

10.8.2.2.14 IT_PPP

```
#define IT_PPP(
    opt)
```

Value:

```
(IC_PPP(0, opt) + NSYS) /* state index
    of tropos */
```

Definition at line 341 of file [rtklib.h](#).

10.8.2.2.15 IT_RTK

```
#define IT_RTK(
    r,
    opt)
```

Value:

```
(NP_RTK(opt) + NI_RTK(opt) + NT_RTK(opt) / 2 * (r)) /* tropos (r:0=rov,1:ref) */
```

Definition at line 66 of file [rtklib_rtkpos.h](#).

10.8.2.2.16 lock_t

```
#define lock_t pthread_mutex_t
```

Definition at line 60 of file [rtklib.h](#).

10.8.2.2.17 MSG_DISCONN

```
#define MSG_DISCONN "$_DISCONNECT\r\n" /* disconnect message */
```

Definition at line 44 of file [rtklib_solution.h](#).

10.8.2.2.18 NB_RTK

```
#define NB_RTK(  
    opt)
```

Value:

```
((opt)->mode <= PMODE_DGPS ? 0 : MAXSAT * NB_RTK(opt))
```

Definition at line 352 of file [rtklib.h](#).

10.8.2.2.19 NF_RTK

```
#define NF_RTK(  
    opt)
```

Value:

```
((opt)->ionoopt == IONOOPT_IFLC ? 1 : (opt)->nf)
```

Definition at line 347 of file [rtklib.h](#).

10.8.2.2.20 NI_RTK

```
#define NI_RTK(  
    opt)
```

Value:

```
((opt)->ionoopt != IONOOPT_EST ? 0 : MAXSAT)
```

Definition at line 349 of file [rtklib.h](#).

10.8.2.2.21 NL_RTK

```
#define NL_RTK(  
    opt)
```

Value:

```
((opt)->glomodear != 2 ? 0 : NFREQGLO)
```

Definition at line 351 of file [rtklib.h](#).

10.8.2.2.22 NP_PPP

```
#define NP_PPP(  
    opt)
```

Value:

```
((opt)->dynamics ? 9 : 3) /* number of  
    pos solution */
```

Definition at line 339 of file [rtklib.h](#).

10.8.2.2.23 NP_RTK

```
#define NP_RTK(  
    opt)
```

Value:

```
((opt)->dynamics == 0 ? 3 : 9)
```

Definition at line 348 of file [rtklib.h](#).

10.8.2.2.24 NR_PPP

```
#define NR_PPP(  
    opt)
```

Value:

```
(IT_PPP(opt) + ((opt)->tropopt < TROPOPT_EST ? 0 : ((opt)->tropopt == TROPOPT_EST ? 1 : 3))) /* number of  
    solutions */
```

Definition at line 342 of file [rtklib.h](#).

10.8.2.2.25 NR_RTK

```
#define NR_RTK(  
    opt)
```

Value:

```
(NP_RTK(opt) + NI_RTK(opt) + NT_RTK(opt) + NL_RTK(opt))
```

Definition at line 353 of file [rtklib.h](#).

10.8.2.2.26 NT_RTK

```
#define NT_RTK(  
    opt)
```

Value:

```
((opt)->tropopt < TROPOPT_EST ? 0 : ((opt)->tropopt < TROPOPT_ESTG ? 2 : 6))
```

Definition at line 350 of file [rtklib.h](#).

10.8.2.2.27 NTRIP_AGENT

```
#define NTRIP_AGENT "RTKLIB/" VER_RTKLIB
```

Definition at line 66 of file [rtklib.h](#).

10.8.2.2.28 NTRIP_CLI_PORT

```
#define NTRIP_CLI_PORT 2101 /* default ntrip-client connection port */
```

Definition at line 67 of file [rtklib.h](#).

10.8.2.2.29 NTRIP_MAXRSP

```
#define NTRIP_MAXRSP 32768 /* max size of ntrip response */
```

Definition at line 69 of file [rtklib.h](#).

10.8.2.2.30 NTRIP_MAXSTR

```
#define NTRIP_MAXSTR 256 /* max length of mountpoint string */
```

Definition at line 70 of file [rtklib.h](#).

10.8.2.2.31 NTRIP_RSP_ERROR

```
#define NTRIP_RSP_ERROR "ERROR" /* ntrip response: error */
```

Definition at line 76 of file [rtklib.h](#).

10.8.2.2.32 NTRIP_RSP_HTTP

```
#define NTRIP_RSP_HTTP "HTTP/" /* ntrip response: http */
```

Definition at line 75 of file [rtklib.h](#).

10.8.2.2.33 NTRIP_RSP_OK_CLI

```
#define NTRIP_RSP_OK_CLI "ICY 200 OK\r\n" /* ntrip response: client */
```

Definition at line 71 of file [rtklib.h](#).

10.8.2.2.34 NTRIP_RSP_OK_SVR

```
#define NTRIP_RSP_OK_SVR "OK\r\n" /* ntrip response: server */
```

Definition at line 72 of file [rtklib.h](#).

10.8.2.2.35 NTRIP_RSP_SRCTBL

```
#define NTRIP_RSP_SRCTBL "SOURCETABLE 200 OK\r\n" /* ntrip response: source table */
```

Definition at line 73 of file [rtklib.h](#).

10.8.2.2.36 NTRIP_RSP_TBLEND

```
#define NTRIP_RSP_TBLEND "ENDSOURCETABLE"
```

Definition at line 74 of file [rtklib.h](#).

10.8.2.2.37 NTRIP_SVR_PORT

```
#define NTRIP_SVR_PORT 80 /* default ntrip-server connection port */
```

Definition at line 68 of file [rtklib.h](#).

10.8.2.2.38 NX_PPP

```
#define NX_PPP(  
    opt)
```

Value:

```
(IB_PPP(MAXSAT, opt) + 1) /* number of  
    estimated states */
```

Definition at line 344 of file [rtklib.h](#).

10.8.2.2.39 NX_RTK

```
#define NX_RTK(  
    opt)
```

Value:

```
(NR_RTK(opt) + NB_RTK(opt))
```

Definition at line 354 of file [rtklib.h](#).

10.8.2.2.40 rtk_lock

```
#define rtk_lock(  
    f)
```

Value:

```
pthread_mutex_lock(f)
```

Definition at line 62 of file [rtklib.h](#).

10.8.2.2.41 rtk_unlock

```
#define rtk_unlock(  
    f)
```

Value:

```
pthread_mutex_unlock(f)
```

Definition at line 63 of file [rtklib.h](#).

10.8.2.2.42 socket_t

```
#define socket_t int
```

Definition at line 58 of file [rtklib.h](#).

10.8.2.2.43 STR_FILE

```
#define STR_FILE 2 /* stream type: file */
```

Definition at line 330 of file [rtklib.h](#).

10.8.2.2.44 STR_FTP

```
#define STR_FTP 8 /* stream type:  ftp */
```

Definition at line 336 of file [rtklib.h](#).

10.8.2.2.45 STR_HTTP

```
#define STR_HTTP 9 /* stream type:  http */
```

Definition at line 337 of file [rtklib.h](#).

10.8.2.2.46 STR_MODE_R

```
#define STR_MODE_R 0x1 /* stream mode:  read */
```

Definition at line 324 of file [rtklib.h](#).

10.8.2.2.47 STR_MODE_RW

```
#define STR_MODE_RW 0x3 /* stream mode:  read/write */
```

Definition at line 326 of file [rtklib.h](#).

10.8.2.2.48 STR_MODE_W

```
#define STR_MODE_W 0x2 /* stream mode:  write */
```

Definition at line 325 of file [rtklib.h](#).

10.8.2.2.49 STR_NONE

```
#define STR_NONE 0 /* stream type:  none */
```

Definition at line 328 of file [rtklib.h](#).

10.8.2.2.50 STR_NTRIPCLI

```
#define STR_NTRIPCLI 7 /* stream type:  NTRIP client */
```

Definition at line 335 of file [rtklib.h](#).

10.8.2.2.51 STR_NTRIPSVR

```
#define STR_NTRIPSVR 6 /* stream type:  NTRIP server */
```

Definition at line 334 of file [rtklib.h](#).

10.8.2.2.52 STR_SERIAL

```
#define STR_SERIAL 1 /* stream type:  serial */
```

Definition at line 329 of file [rtklib.h](#).

10.8.2.2.53 STR_TCPCLI

```
#define STR_TCPCLI 4 /* stream type:  TCP client */
```

Definition at line 332 of file [rtklib.h](#).

10.8.2.2.54 STR_TCPSVR

```
#define STR_TCPSVR 3 /* stream type:  TCP server */
```

Definition at line 331 of file [rtklib.h](#).

10.8.2.2.55 STR_UDP

```
#define STR_UDP 5 /* stream type:  UDP stream */
```

Definition at line 333 of file [rtklib.h](#).

10.8.2.2.56 VER_RTKLIB

#define VER_RTKLIB "2.4.2"
Definition at line 65 of file [rtklib.h](#).

10.8.2.3 Typedef Documentation

10.8.2.3.1 fatalfunc_t

using fatalfunc_t = void(const char *)
fatal callback function type
Definition at line 321 of file [rtklib.h](#).

10.8.2.4 Function Documentation

10.8.2.4.1 eph_to_rtklib()

```
geph_t eph_to_rtklib (
    const Glonass_Gnav_Ephemeris & glonass_gnav_eph,
    const Glonass_Gnav_Utc_Model & gnav_clock_model)
```

Transforms a [Glonass_Gnav_Ephemeris](#) to its RTKLIB counterpart.

Parameters

<i>glonass_gnav_eph</i>	GLONASS GNAV Ephemeris structure
-------------------------	----------------------------------

Returns

Ephemeris structure for RTKLIB parsing

10.8.2.5 Variable Documentation

10.8.2.5.1 ARMODE_CONT

const int ARMODE_CONT = 1
AR mode: continuous.
Definition at line 308 of file [rtklib.h](#).

10.8.2.5.2 ARMODE_FIXHOLD

const int ARMODE_FIXHOLD = 3
AR mode: fix and hold.
Definition at line 310 of file [rtklib.h](#).

10.8.2.5.3 ARMODE_INST

const int ARMODE_INST = 2
AR mode: instantaneous.
Definition at line 309 of file [rtklib.h](#).

10.8.2.5.4 ARMODE_OFF

const int ARMODE_OFF = 0
AR mode: off.
Definition at line 307 of file [rtklib.h](#).

10.8.2.5.5 ARMODE_PPPAR

const int ARMODE_PPPAR = 4
AR mode: PPP-AR.
Definition at line 311 of file [rtklib.h](#).

10.8.2.5.6 ARMODE_PPPAR_ILS

```
const int ARMODE_PPPAR_ILS = 5
```

AR mode: AR mode: PPP-AR ILS.

Definition at line 312 of file [rtklib.h](#).

10.8.2.5.7 ARMODE_TCAR

```
const int ARMODE_TCAR = 7
```

Definition at line 314 of file [rtklib.h](#).

10.8.2.5.8 ARMODE_WLNL

```
const int ARMODE_WLNL = 6
```

Definition at line 313 of file [rtklib.h](#).

10.8.2.5.9 CHISQR

```
const double CHISQR[100]
```

Initial value:

```
= {  
    10.8, 13.8, 16.3, 18.5, 20.5, 22.5, 24.3, 26.1, 27.9, 29.6,  
    31.3, 32.9, 34.5, 36.1, 37.7, 39.3, 40.8, 42.3, 43.8, 45.3,  
    46.8, 48.3, 49.7, 51.2, 52.6, 54.1, 55.5, 56.9, 58.3, 59.7,  
    61.1, 62.5, 63.9, 65.2, 66.6, 68.0, 69.3, 70.7, 72.1, 73.4,  
    74.7, 76.0, 77.3, 78.6, 80.0, 81.3, 82.6, 84.0, 85.4, 86.7,  
    88.0, 89.3, 90.6, 91.9, 93.3, 94.7, 96.0, 97.4, 98.7, 100,  
    101, 102, 103, 104, 105, 107, 108, 109, 110, 112,  
    113, 114, 115, 116, 118, 119, 120, 122, 123, 125,  
    126, 127, 128, 129, 131, 132, 133, 134, 135, 137,  
    138, 139, 140, 142, 143, 144, 145, 147, 148, 149}
```

Definition at line 1292 of file [rtklib.h](#).

10.8.2.5.10 DTTOL

```
const double DTTOL = 0.005
```

tolerance of time difference (s)

Definition at line 146 of file [rtklib.h](#).

10.8.2.5.11 EFACT_BDS

```
const double EFACT_BDS = 1.0
```

error factor: BeiDou

Definition at line 299 of file [rtklib.h](#).

10.8.2.5.12 EFACT_GAL

```
const double EFACT_GAL = 1.0
```

error factor: Galileo

Definition at line 297 of file [rtklib.h](#).

10.8.2.5.13 EFACT_GLO

```
const double EFACT_GLO = 1.5
```

error factor: GLONASS

Definition at line 296 of file [rtklib.h](#).

10.8.2.5.14 EFACT_GPS

```
const double EFACT_GPS = 1.0
```

error factor: GPS

Definition at line 295 of file [rtklib.h](#).

10.8.2.5.15 EFACT_IRN

`const double EFACT_IRN = 1.5`
error factor: IRNSS
Definition at line 300 of file [rtklib.h](#).

10.8.2.5.16 EFACT_QZS

`const double EFACT_QZS = 1.0`
error factor: QZSS
Definition at line 298 of file [rtklib.h](#).

10.8.2.5.17 EFACT_SBS

`const double EFACT_SBS = 3.0`
error factor: SBAS
Definition at line 301 of file [rtklib.h](#).

10.8.2.5.18 EPHOPT_BRDC

`const int EPHOPT_BRDC = 0`
ephemeris option: broadcast ephemeris
Definition at line 288 of file [rtklib.h](#).

10.8.2.5.19 EPHOPT_LEX

`const int EPHOPT_LEX = 5`
ephemeris option: QZSS LEX ephemeris
Definition at line 293 of file [rtklib.h](#).

10.8.2.5.20 EPHOPT_PREC

`const int EPHOPT_PREC = 1`
ephemeris option: precise ephemeris
Definition at line 289 of file [rtklib.h](#).

10.8.2.5.21 EPHOPT_SBAS

`const int EPHOPT_SBAS = 2`
ephemeris option: broadcast + SBAS
Definition at line 290 of file [rtklib.h](#).

10.8.2.5.22 EPHOPT_SSRAPC

`const int EPHOPT_SSRAPC = 3`
ephemeris option: broadcast + SSR_APC
Definition at line 291 of file [rtklib.h](#).

10.8.2.5.23 EPHOPT_SSRCOM

`const int EPHOPT_SSRCOM = 4`
ephemeris option: broadcast + SSR_COM
Definition at line 292 of file [rtklib.h](#).

10.8.2.5.24 ERR_BRDCI

`const double ERR_BRDCI = 0.5`
broadcast iono model error factor
Definition at line 138 of file [rtklib.h](#).

10.8.2.5.25 ERR_CBIAS

```
const double ERR_CBIAS = 0.3
```

code bias error std (m)
Definition at line 139 of file [rtklib.h](#).

10.8.2.5.26 ERR_SAAS

```
const double ERR_SAAS = 0.3
```

saastamoinen model error std (m)
Definition at line 137 of file [rtklib.h](#).

10.8.2.5.27 FE_WGS84

```
const double FE_WGS84 = (1.0 / 298.257223563)
```

earth flattening (WGS84)
Definition at line 94 of file [rtklib.h](#).

10.8.2.5.28 FILEPATHSEP

```
const int FILEPATHSEP = '/'
```

Definition at line 92 of file [rtklib.h](#).

10.8.2.5.29 FTP_TIMEOUT

```
const int FTP_TIMEOUT = 30
```

ftp/http timeout (s)
Definition at line 86 of file [rtklib.h](#).

10.8.2.5.30 GAP_RESION

```
const double GAP_RESION = 120
```

default gap to reset ionos parameters (ep)
Definition at line 141 of file [rtklib.h](#).

10.8.2.5.31 HION

```
const double HION = 350000.0
```

ionosphere height (m)
Definition at line 96 of file [rtklib.h](#).

10.8.2.5.32 INIT_ZWD

```
const double INIT_ZWD = 0.15
```

Definition at line 50 of file [rtklib_rtkpos.h](#).

10.8.2.5.33 INT_SWAP_STAT

```
const double INT_SWAP_STAT = 86400.0
```

swap interval of solution status file (s)
Definition at line 99 of file [rtklib.h](#).

10.8.2.5.34 INT_SWAP_TRAC

```
const double INT_SWAP_TRAC = 86400.0
```

swap interval of trace file (s)
Definition at line 100 of file [rtklib.h](#).

10.8.2.5.35 IONOOPT_BRDC

`const int IONOOPT_BRDC = 1`
 ionosphere option: broadcast model
 Definition at line 270 of file [rtklib.h](#).

10.8.2.5.36 IONOOPT_EST

`const int IONOOPT_EST = 4`
 ionosphere option: estimation
 Definition at line 273 of file [rtklib.h](#).

10.8.2.5.37 IONOOPT_IFLC

`const int IONOOPT_IFLC = 3`
 ionosphere option: L1/L2 or L1/L5 iono-free LC
 Definition at line 272 of file [rtklib.h](#).

10.8.2.5.38 IONOOPT_LEX

`const int IONOOPT_LEX = 7`
 ionosphere option: QZSS LEX ionosphere
 Definition at line 276 of file [rtklib.h](#).

10.8.2.5.39 IONOOPT_OFF

`const int IONOOPT_OFF = 0`
 ionosphere option: correction off
 Definition at line 269 of file [rtklib.h](#).

10.8.2.5.40 IONOOPT_QZS

`const int IONOOPT_QZS = 6`
 ionosphere option: QZSS broadcast model
 Definition at line 275 of file [rtklib.h](#).

10.8.2.5.41 IONOOPT_SBAS

`const int IONOOPT_SBAS = 2`
 ionosphere option: SBAS model
 Definition at line 271 of file [rtklib.h](#).

10.8.2.5.42 IONOOPT_STEC

`const int IONOOPT_STEC = 8`
 ionosphere option: SLANT TEC model
 Definition at line 277 of file [rtklib.h](#).

10.8.2.5.43 IONOOPT_TEC

`const int IONOOPT_TEC = 5`
 ionosphere option: IONEX TEC model
 Definition at line 274 of file [rtklib.h](#).

10.8.2.5.44 LAM_CARR

`const double LAM_CARR[MAXFREQ]`

Initial value:

```
= {
    SPEED_OF_LIGHT_M_S / FREQ1, SPEED_OF_LIGHT_M_S / FREQ2, SPEED_OF_LIGHT_M_S / FREQ5, SPEED_OF_LIGHT_M_S /
    FREQ6, SPEED_OF_LIGHT_M_S / FREQ7,
```

```
SPEED_OF_LIGHT_M_S / FREQ8, SPEED_OF_LIGHT_M_S / FREQ9}
```

Definition at line 1305 of file [rtklib.h](#).

10.8.2.5.45 MAXAC

```
const double MAXAC = 30.0
```

Definition at line 53 of file [rtklib_rtkpos.h](#).

10.8.2.5.46 MAXANT

```
const int MAXANT = 64
```

max length of station name/antenna type

Definition at line 151 of file [rtklib.h](#).

10.8.2.5.47 MAXBAND

```
const int MAXBAND = 10
```

max SBAS band of IGP

Definition at line 262 of file [rtklib.h](#).

10.8.2.5.48 MAXCLI

```
const int MAXCLI = 32
```

max client connection for tcp svr

Definition at line 83 of file [rtklib.h](#).

10.8.2.5.49 MAXDTOE

```
const double MAXDTOE = 7200.0
```

max time difference to GPS Toe (s)

Definition at line 252 of file [rtklib.h](#).

10.8.2.5.50 MAXDTOE_BDS

```
const double MAXDTOE_BDS = 21600.0
```

max time difference to BeiDou Toe (s)

Definition at line 255 of file [rtklib.h](#).

10.8.2.5.51 MAXDTOE_GAL

```
const double MAXDTOE_GAL = 10800.0
```

max time difference to Galileo Toe (s)

Definition at line 254 of file [rtklib.h](#).

10.8.2.5.52 MAXDTOE_GLO

```
const double MAXDTOE_GLO = 1800.0
```

max time difference to GLONASS Toe (s)

Definition at line 256 of file [rtklib.h](#).

10.8.2.5.53 MAXDTOE_QZS

```
const double MAXDTOE_QZS = 7200.0
```

max time difference to QZSS Toe (s)

Definition at line 253 of file [rtklib.h](#).

10.8.2.5.54 MAXDToe_S

`const double MAXDToe_S = 86400.0`
max time difference to ephemeris toe (s) for other
Definition at line 258 of file [rtklib.h](#).

10.8.2.5.55 MAXDToe_SBS

`const double MAXDToe_SBS = 360.0`
max time difference to SBAS Toe (s)
Definition at line 257 of file [rtklib.h](#).

10.8.2.5.56 MAXERRMSG

`const int MAXERRMSG = 4096`
max length of error/warning message
Definition at line 267 of file [rtklib.h](#).

10.8.2.5.57 MAXEXFILE

`const int MAXEXFILE = 1024`
max number of expanded files
Definition at line 303 of file [rtklib.h](#).

10.8.2.5.58 MAXFREQ

`const int MAXFREQ = 7`
max NFREQ
Definition at line 143 of file [rtklib.h](#).

10.8.2.5.59 MAXGDOP

`const double MAXGDOP = 300.0`
max GDOP
Definition at line 259 of file [rtklib.h](#).

10.8.2.5.60 MAXLEAPS

`const int MAXLEAPS = 64`
max number of leap seconds table
Definition at line 145 of file [rtklib.h](#).

10.8.2.5.61 MAXNGEO

`const int MAXNGEO = 4`
max number of GEO satellites
Definition at line 264 of file [rtklib.h](#).

10.8.2.5.62 MAXNIGP

`const int MAXNIGP = 201`
max number of IGP in SBAS band
Definition at line 263 of file [rtklib.h](#).

10.8.2.5.63 MAXOBS

`const int MAXOBS = 64`
max number of obs in an epoch
Definition at line 247 of file [rtklib.h](#).

10.8.2.5.64 MAXOBSBUF

`const int MAXOBSBUF = 128`
max number of observation data buffer
Definition at line 90 of file [rtklib.h](#).

10.8.2.5.65 MAXOBSTYPE

`const int MAXOBSTYPE = 64`
max number of obs type in RINEX
Definition at line 251 of file [rtklib.h](#).

10.8.2.5.66 MAXPRNBDS

`const int MAXPRNBDS = 63`
max satellite sat number of BeiDou
Definition at line 206 of file [rtklib.h](#).

10.8.2.5.67 MAXPRNGAL

`const int MAXPRNGAL = 36`
max satellite PRN number of Galileo
Definition at line 185 of file [rtklib.h](#).

10.8.2.5.68 MAXPRNGLO

`const int MAXPRNGLO = 27`
max satellite slot number of GLONASS
Definition at line 173 of file [rtklib.h](#).

10.8.2.5.69 MAXPRNGPS

`const int MAXPRNGPS = 32`
max satellite PRN number of GPS
Definition at line 154 of file [rtklib.h](#).

10.8.2.5.70 MAXPRNIRN

`const int MAXPRNIRN = 7`
max satellite sat number of IRNSS
Definition at line 217 of file [rtklib.h](#).

10.8.2.5.71 MAXPRNLEO

`const int MAXPRNLEO = 10`
max satellite sat number of LEO */
Definition at line 227 of file [rtklib.h](#).

10.8.2.5.72 MAXPRNQZS

`const int MAXPRNQZS = 202`
max satellite PRN number of QZSS
Definition at line 189 of file [rtklib.h](#).

10.8.2.5.73 MAXPRNQZS_S

`const int MAXPRNQZS_S = 191`
max satellite PRN number of QZSS SAIF
Definition at line 194 of file [rtklib.h](#).

10.8.2.5.74 MAXPRNSBS

`const int MAXPRNSBS = 142`
max satellite PRN number of SBAS
Definition at line 239 of file [rtklib.h](#).

10.8.2.5.75 MAXRAWLEN

`const int MAXRAWLEN = 4096`
max length of receiver raw message
Definition at line 87 of file [rtklib.h](#).

10.8.2.5.76 MAXRCV

`const int MAXRCV = 64`
max receiver number (1 to MAXRCV)
Definition at line 250 of file [rtklib.h](#).

10.8.2.5.77 MAXSAT

`const int MAXSAT = (NSATGPS + NSATGLO + NSATGAL + NSATQZS + NSATBDS + NSATIRN + NSATSBS + NSATLEO)`
Definition at line 242 of file [rtklib.h](#).

10.8.2.5.78 MAXSBSAGEF

`const double MAXSBSAGEF = 30.0`
max age of SBAS fast correction (s)
Definition at line 304 of file [rtklib.h](#).

10.8.2.5.79 MAXSBSAGEL

`const double MAXSBSAGEL = 1800.0`
max age of SBAS long term corr (s)
Definition at line 305 of file [rtklib.h](#).

10.8.2.5.80 MAXSBSMSG

`const int MAXSBSMSG = 32`
max number of SBAS msg in RTK server
Definition at line 89 of file [rtklib.h](#).

10.8.2.5.81 MAXSBSURA

`const int MAXSBSURA = 8`
max URA of SBAS satellite
Definition at line 261 of file [rtklib.h](#).

10.8.2.5.82 MAXSOLBUF

`const int MAXSOLBUF = 256`
max number of solution buffer
Definition at line 88 of file [rtklib.h](#).

10.8.2.5.83 MAXSOLMSG

`const int MAXSOLMSG = 8191`
max length of solution message
Definition at line 266 of file [rtklib.h](#).

10.8.2.5.84 MAXSOLQ

`const int MAXSOLQ = 7`
max number of solution status
Definition at line 130 of file [rtklib.h](#).

10.8.2.5.85 MAXSTA

`const int MAXSTA = 255`
Definition at line 244 of file [rtklib.h](#).

10.8.2.5.86 MAXSTATMSG

`const int MAXSTATMSG = 32`
max length of status message
Definition at line 84 of file [rtklib.h](#).

10.8.2.5.87 MAXSTRMSG

`const int MAXSTRMSG = 1024`
max length of stream message
Definition at line 319 of file [rtklib.h](#).

10.8.2.5.88 MAXSTRPATH

`const int MAXSTRPATH = 1024`
max length of stream path
Definition at line 318 of file [rtklib.h](#).

10.8.2.5.89 MAXSTRRTK

`const int MAXSTRRTK = 8`
Definition at line 1317 of file [rtklib.h](#).

10.8.2.5.90 MINPRNBDS

`const int MINPRNBDS = 1`
min satellite sat number of BeiDou
Definition at line 205 of file [rtklib.h](#).

10.8.2.5.91 MINPRNGAL

`const int MINPRNGAL = 1`
min satellite PRN number of Galileo
Definition at line 184 of file [rtklib.h](#).

10.8.2.5.92 MINPRNGLO

`const int MINPRNGLO = 1`
min satellite slot number of GLONASS
Definition at line 172 of file [rtklib.h](#).

10.8.2.5.93 MINPRNGPS

`const int MINPRNGPS = 1`
min satellite PRN number of GPS
Definition at line 153 of file [rtklib.h](#).

10.8.2.5.94 MINPRNIRN

`const int MINPRNIRN = 1`
min satellite sat number of IRNSS
Definition at line 216 of file [rtklib.h](#).

10.8.2.5.95 MINPRNLEO

`const int MINPRNLEO = 1`
min satellite sat number of LEO
Definition at line 226 of file [rtklib.h](#).

10.8.2.5.96 MINPRNQZS

`const int MINPRNQZS = 193`
min satellite PRN number of QZSS
Definition at line 190 of file [rtklib.h](#).

10.8.2.5.97 MINPRNQZS_S

`const int MINPRNQZS_S = 183`
min satellite PRN number of QZSS SAIF
Definition at line 193 of file [rtklib.h](#).

10.8.2.5.98 MINPRNSBS

`const int MINPRNSBS = 120`
min satellite PRN number of SBAS
Definition at line 238 of file [rtklib.h](#).

10.8.2.5.99 NEXOBS

`const int NEXOBS = 0`
number of extended obs codes
Definition at line 150 of file [rtklib.h](#).

10.8.2.5.100 NFREQ

`const int NFREQ = 3`
number of carrier frequencies
Definition at line 148 of file [rtklib.h](#).

10.8.2.5.101 NFREQGLO

`const int NFREQGLO = 2`
number of carrier frequencies of GLONASS
Definition at line 149 of file [rtklib.h](#).

10.8.2.5.102 NSATBDS

`const int NSATBDS = (MAXPRNBDS - MINPRNBDS + 1)`
number of BeiDou satellites
Definition at line 207 of file [rtklib.h](#).

10.8.2.5.103 NSATGAL

`const int NSATGAL = (MAXPRNGAL - MINPRNGAL + 1)`
number of Galileo satellites
Definition at line 186 of file [rtklib.h](#).

10.8.2.5.104 NSATGLO

```
const int NSATGLO = (MAXPRNGLO - MINPRNGLO + 1)
```

number of GLONASS satellites

Definition at line 174 of file [rtklib.h](#).

10.8.2.5.105 NSATGPS

```
const int NSATGPS = (MAXPRNGPS - MINPRNGPS + 1)
```

number of GPS satellites

Definition at line 155 of file [rtklib.h](#).

10.8.2.5.106 NSATIRN

```
const int NSATIRN = 0
```

Definition at line 222 of file [rtklib.h](#).

10.8.2.5.107 NSATLEO

```
const int NSATLEO = 0
```

Definition at line 232 of file [rtklib.h](#).

10.8.2.5.108 NSATQZS

```
const int NSATQZS = (MAXPRNQZS - MINPRNQZS + 1)
```

number of QZSS satellites

Definition at line 195 of file [rtklib.h](#).

10.8.2.5.109 NSATSBS

```
const int NSATSBS = (MAXPRNSBS - MINPRNSBS + 1)
```

number of SBAS satellites

Definition at line 240 of file [rtklib.h](#).

10.8.2.5.110 NSYS

```
const int NSYS = (NSYSGPS + NSYSGLO + NSYSGAL + NSYSQZS + NSYSBDS + NSYSIRN + NSYSLEO)
```

number of systems

Definition at line 236 of file [rtklib.h](#).

10.8.2.5.111 NSYSBDS

```
const int NSYSBDS = 1
```

Definition at line 208 of file [rtklib.h](#).

10.8.2.5.112 NSYSGAL

```
const int NSYSGAL = 1
```

Definition at line 187 of file [rtklib.h](#).

10.8.2.5.113 NSYSGLO

```
const int NSYSGLO = 1
```

Definition at line 175 of file [rtklib.h](#).

10.8.2.5.114 NSYSGPS

```
const int NSYSGPS = 1
```

Definition at line 156 of file [rtklib.h](#).

10.8.2.5.115 NSYSIRN

```
const int NSYSIRN = 0
```

Definition at line 223 of file [rtklib.h](#).

10.8.2.5.116 NSYSLEO

```
const int NSYSLEO = 0
```

Definition at line 233 of file [rtklib.h](#).

10.8.2.5.117 NSYSQZS

```
const int NSYSQZS = 1
```

Definition at line 196 of file [rtklib.h](#).

10.8.2.5.118 PMODE_DGPS

```
const int PMODE_DGPS = 1
```

positioning mode: DGPS/DGNSS

Definition at line 106 of file [rtklib.h](#).

10.8.2.5.119 PMODE_FIXED

```
const int PMODE_FIXED = 5
```

positioning mode: fixed

Definition at line 110 of file [rtklib.h](#).

10.8.2.5.120 PMODE_KINEMA

```
const int PMODE_KINEMA = 2
```

positioning mode: kinematic

Definition at line 107 of file [rtklib.h](#).

10.8.2.5.121 PMODE_MOVEB

```
const int PMODE_MOVEB = 4
```

positioning mode: moving-base

Definition at line 109 of file [rtklib.h](#).

10.8.2.5.122 PMODE_PPP_FIXED

```
const int PMODE_PPP_FIXED = 8
```

positioning mode: PPP-fixed

Definition at line 113 of file [rtklib.h](#).

10.8.2.5.123 PMODE_PPP_KINEMA

```
const int PMODE_PPP_KINEMA = 6
```

positioning mode: PPP-kinematic

Definition at line 111 of file [rtklib.h](#).

10.8.2.5.124 PMODE_PPP_STATIC

```
const int PMODE_PPP_STATIC = 7
```

positioning mode: PPP-static

Definition at line 112 of file [rtklib.h](#).

10.8.2.5.125 PMODE_SINGLE

`const int PMODE_SINGLE = 0`
positioning mode: single
Definition at line 105 of file [rtklib.h](#).

10.8.2.5.126 PMODE_STATIC

`const int PMODE_STATIC = 3`
positioning mode: static
Definition at line 108 of file [rtklib.h](#).

10.8.2.5.127 POLYCRC24Q

`const unsigned int POLYCRC24Q = 0x1864CFBu`
CRC24Q polynomial.
Definition at line 103 of file [rtklib.h](#).

10.8.2.5.128 POLYCRC32

`const unsigned int POLYCRC32 = 0xEDB88320u`
CRC32 polynomial.
Definition at line 102 of file [rtklib.h](#).

10.8.2.5.129 POSOPT_RINEX

`const int POSOPT_RINEX = 3`
pos option: rinex header pos
Definition at line 317 of file [rtklib.h](#).

10.8.2.5.130 PRN_HWBIA

`const double PRN_HWBIA = 1E-6`
Definition at line 52 of file [rtklib_rtkpos.h](#).

10.8.2.5.131 PRN_HWBIAS

`const double PRN_HWBIAS = 1e-6`
process noise of h/w bias (m/MHz/sqrt(s))
Definition at line 97 of file [rtklib.h](#).

10.8.2.5.132 RE_WGS84

`const double RE_WGS84 = 6378137.0`
earth semimajor axis (WGS84) (m)
Definition at line 93 of file [rtklib.h](#).

10.8.2.5.133 REL_HUMI

`const double REL_HUMI = 0.7`
relative humidity for saastamoinen model
Definition at line 140 of file [rtklib.h](#).

10.8.2.5.134 SERIBUFFSIZE

`const int SERIBUFFSIZE = 4096`
serial buffer size (bytes)
Definition at line 81 of file [rtklib.h](#).

10.8.2.5.135 SOLF_ENU

`const int SOLF_ENU = 2`
solution format: e/n/u-baseline
Definition at line 117 of file [rtklib.h](#).

10.8.2.5.136 SOLF_GSIF

`const int SOLF_GSIF = 5`
solution format: GSI F1/F2
Definition at line 120 of file [rtklib.h](#).

10.8.2.5.137 SOLF_LLH

`const int SOLF_LLH = 0`
solution format: lat/lon/height
Definition at line 115 of file [rtklib.h](#).

10.8.2.5.138 SOLF_NMEA

`const int SOLF_NMEA = 3`
solution format: NMEA-183
Definition at line 118 of file [rtklib.h](#).

10.8.2.5.139 SOLF_STAT

`const int SOLF_STAT = 4`
solution format: solution status
Definition at line 119 of file [rtklib.h](#).

10.8.2.5.140 SOLF_XYZ

`const int SOLF_XYZ = 1`
solution format: x/y/z-ecef
Definition at line 116 of file [rtklib.h](#).

10.8.2.5.141 SOLQ_DGPS

`const int SOLQ_DGPS = 4`
solution status: DGPS/DGNSS
Definition at line 126 of file [rtklib.h](#).

10.8.2.5.142 SOLQ_DR

`const int SOLQ_DR = 7`
solution status: dead reckoning
Definition at line 129 of file [rtklib.h](#).

10.8.2.5.143 SOLQ_FIX

`const int SOLQ_FIX = 1`
solution status: fix
Definition at line 123 of file [rtklib.h](#).

10.8.2.5.144 SOLQ_FLOAT

`const int SOLQ_FLOAT = 2`
solution status: float
Definition at line 124 of file [rtklib.h](#).

10.8.2.5.145 SOLQ_NONE

`const int SOLQ_NONE = 0`
solution status: no solution
Definition at line 122 of file [rtklib.h](#).

10.8.2.5.146 SOLQ_PPP

`const int SOLQ_PPP = 6`
solution status: PPP
Definition at line 128 of file [rtklib.h](#).

10.8.2.5.147 SOLQ_SBAS

`const int SOLQ_SBAS = 3`
solution status: SBAS
Definition at line 125 of file [rtklib.h](#).

10.8.2.5.148 SOLQ_SINGLE

`const int SOLQ_SINGLE = 5`
solution status: single
Definition at line 127 of file [rtklib.h](#).

10.8.2.5.149 STRFMT_NMEA

`const int STRFMT_NMEA = 19`
Definition at line 1314 of file [rtklib.h](#).

10.8.2.5.150 STRFMT_RNXCLK

`const int STRFMT_RNXCLK = 17`
Definition at line 1312 of file [rtklib.h](#).

10.8.2.5.151 STRFMT_RTCM2

`const int STRFMT_RTCM2 = 0`
Definition at line 1309 of file [rtklib.h](#).

10.8.2.5.152 STRFMT_RTCM3

`const int STRFMT_RTCM3 = 1`
Definition at line 1310 of file [rtklib.h](#).

10.8.2.5.153 STRFMT_SBAS

`const int STRFMT_SBAS = 18`
Definition at line 1313 of file [rtklib.h](#).

10.8.2.5.154 STRFMT_SP3

`const int STRFMT_SP3 = 16`
Definition at line 1311 of file [rtklib.h](#).

10.8.2.5.155 SYS_ALL

`const int SYS_ALL = 0xFF`
navigation system: all
Definition at line 167 of file [rtklib.h](#).

10.8.2.5.156 SYS_BDS

`const int SYS_BDS = 0x20`
navigation system: BeiDou
Definition at line 164 of file [rtklib.h](#).

10.8.2.5.157 SYS_GAL

`const int SYS_GAL = 0x08`
navigation system: Galileo
Definition at line 162 of file [rtklib.h](#).

10.8.2.5.158 SYS_GLO

`const int SYS_GLO = 0x04`
navigation system: GLONASS
Definition at line 161 of file [rtklib.h](#).

10.8.2.5.159 SYS_GPS

`const int SYS_GPS = 0x01`
navigation system: GPS
Definition at line 159 of file [rtklib.h](#).

10.8.2.5.160 SYS_IRN

`const int SYS_IRN = 0x40`
navigation system: IRNS
Definition at line 165 of file [rtklib.h](#).

10.8.2.5.161 SYS_LEO

`const int SYS_LEO = 0x80`
navigation system: LEO
Definition at line 166 of file [rtklib.h](#).

10.8.2.5.162 SYS_NONE

`const int SYS_NONE = 0x00`
navigation system: none
Definition at line 158 of file [rtklib.h](#).

10.8.2.5.163 SYS_QZS

`const int SYS_QZS = 0x10`
navigation system: QZSS
Definition at line 163 of file [rtklib.h](#).

10.8.2.5.164 SYS_SBS

`const int SYS_SBS = 0x02`
navigation system: SBAS
Definition at line 160 of file [rtklib.h](#).

10.8.2.5.165 TIMES_GPST

`const int TIMES_GPST = 0`
time system: gps time
Definition at line 132 of file [rtklib.h](#).

10.8.2.5.166 TIMES_JST

`const int TIMES_JST = 2`
time system: jst
Definition at line 134 of file [rtklib.h](#).

10.8.2.5.167 TIMES_UTC

`const int TIMES_UTC = 1`
time system: utc
Definition at line 133 of file [rtklib.h](#).

10.8.2.5.168 TIMETAGH_LEN

`const int TIMETAGH_LEN = 64`
time tag file header length
Definition at line 82 of file [rtklib.h](#).

10.8.2.5.169 TINTACT

`const int TINTACT = 200`
period for stream active (ms)
Definition at line 80 of file [rtklib.h](#).

10.8.2.5.170 TROPOPT_COR

`const int TROPOPT_COR = 5`
troposphere option: ZTD correction
Definition at line 284 of file [rtklib.h](#).

10.8.2.5.171 TROPOPT_CORG

`const int TROPOPT_CORG = 6`
troposphere option: ZTD+grad correction
Definition at line 285 of file [rtklib.h](#).

10.8.2.5.172 TROPOPT_EST

`const int TROPOPT_EST = 3`
troposphere option: ZTD estimation
Definition at line 282 of file [rtklib.h](#).

10.8.2.5.173 TROPOPT_ESTG

`const int TROPOPT_ESTG = 4`
troposphere option: ZTD+grad estimation
Definition at line 283 of file [rtklib.h](#).

10.8.2.5.174 TROPOPT_OFF

`const int TROPOPT_OFF = 0`
troposphere option: correction off
Definition at line 279 of file [rtklib.h](#).

10.8.2.5.175 TROPOPT_SAAS

`const int TROPOPT_SAAS = 1`
troposphere option: Saastamoinen model
Definition at line 280 of file [rtklib.h](#).

10.8.2.5.176 TROPOPT_SBAS

`const int TROPOPT_SBAS = 2`
 troposphere option: SBAS model
 Definition at line 281 of file [rtklib.h](#).

10.8.2.5.177 TTOL_MOVEB

`const double TTOL_MOVEB = (1.0 + 2 * DTTOL)`
 Definition at line 57 of file [rtklib_rtkpos.h](#).

10.8.2.5.178 VAR_ACC

`const double VAR_ACC = std::pow(10.0, 2.0)`
 Definition at line 47 of file [rtklib_rtkpos.h](#).

10.8.2.5.179 VAR_GRA

`const double VAR_GRA = std::pow(0.001, 2.0)`
 Definition at line 49 of file [rtklib_rtkpos.h](#).

10.8.2.5.180 VAR_HOLDAMB

`const double VAR_HOLDAMB = 0.001`
 Definition at line 55 of file [rtklib_rtkpos.h](#).

10.8.2.5.181 VAR_HWBIAS

`const double VAR_HWBIAS = std::pow(1.0, 2.0)`
 Definition at line 48 of file [rtklib_rtkpos.h](#).

10.8.2.5.182 VAR_POS

`const double VAR_POS = std::pow(30.0, 2.0)`
 Definition at line 45 of file [rtklib_rtkpos.h](#).

10.8.2.5.183 VAR_VEL

`const double VAR_VEL = std::pow(10.0, 2.0)`
 Definition at line 46 of file [rtklib_rtkpos.h](#).

10.8.3 pvt_adapters**Classes**

- class [Rtklib_Pvt](#)
This class implements a [PvtInterface](#) for the RTKLIB PVT block.

10.8.3.1 Detailed Description

Wrap GNU Radio PVT solvers with a [PvtInterface](#)

10.8.4 pvt_gr_blocks**Classes**

- class [rtklib_pvt_gs](#)
This class implements a block that computes the PVT solution using the RTKLIB integrated library.

Typedefs

- using [rtklib_pvt_gs_sptr](#) = gnss_shared_ptr<[rtklib_pvt_gs](#)>

Functions

- [rtklib_pvt_gs_sptr](#) **rtklib_make_pvt_gs** (uint32_t nchannels, const [Pvt_Conf](#) &conf_, const [rtk_t](#) &rtk, const [SensorDataSourceConfiguration](#) &sensor_data_configuration)

10.8.4.1 Detailed Description

GNU Radio blocks for the computation of PVT solutions.

10.8.4.2 Typedef Documentation

10.8.4.2.1 rtklib_pvt_gs_sptr

using [rtklib_pvt_gs_sptr](#) = gnss_shared_ptr<[rtklib_pvt_gs](#)>

Definition at line 75 of file [rtklib_pvt_gs.h](#).

10.8.5 pvt_libs

Classes

- struct [sdr_gnss_packet_t](#)
- struct [an_packet_t](#)
- class [An_Packet_Printer](#)
class that prints PVT solutions in a serial device following a custom version of the Advanced Navigation Packet Protocol.
- class [Geohash](#)
Class for geohash encoding / decoding See <https://en.wikipedia.org/wiki/Geohash>.
- class [GeoJSON_Printer](#)
Prints PVT solutions in GeoJSON format file.
- class [Gpx_Printer](#)
Prints PVT information to GPX format file.
- class [Has_Simple_Printer](#)
Prints HAS messages content in a txt file. See HAS-SIS-ICD for a message description.
- class [Kml_Printer](#)
Prints PVT information to OGC KML format file (can be viewed with Google Earth)
- class [Monitor_Ephemeris_Udp_Sink](#)
- class [Monitor_Pvt](#)
This class contains parameters and outputs of the PVT block.
- class [Monitor_Pvt_Udp_Sink](#)
- class [Nmea_Printer](#)
This class provides a implementation of a subset of the NMEA-0183 standard for interfacing marine electronic devices as defined by the National Marine Electronics Association (NMEA).
- class [Pvt_Conf](#)
- class [Pvt_Kf](#)
Kalman Filter for Position and Velocity.
- class [Pvt_Solution](#)
Base class for a PVT solution.
- class [Rinex_Printer](#)
Class that handles the generation of Receiver INdependent EXchange format (RINEX) files.
- class [Rtcm](#)
This class implements the generation and reading of some Message Types defined in the RTCM 3.2 Standard, plus some utilities to handle messages.

- class [Rtcm_Printer](#)

This class provides a implementation of a subset of the RTCM Standard 10403.2 messages.

- class [Rtklib_Solver](#)

This class implements a PVT solution based on RTKLIB.

- class [Serdes_Galileo_Eph](#)

This class implements serialization and deserialization of [Galileo_Ephemeris](#) using Protocol Buffers.

- class [Serdes_Gps_Eph](#)

This class implements serialization and deserialization of [Gps_Ephemeris](#) objects using Protocol Buffers.

- class [Serdes_Monitor_Pvt](#)

This class implements serialization and deserialization of [Monitor_Pvt](#) objects using Protocol Buffers.

Typedefs

- using [b_io_context](#) = boost::asio::io_service
- using [b_io_context](#) = boost::asio::io_service
- using [b_io_context](#) = boost::asio::io_service

10.8.5.1 Detailed Description

Library for the computation of PVT solutions.

10.8.5.2 Typedef Documentation

10.8.5.2.1 [b_io_context](#) [1/3]

```
using b_io_context = boost::asio::io_service
```

Definition at line 39 of file [monitor_ephemeris_udp_sink.h](#).

10.8.5.2.2 [b_io_context](#) [2/3]

```
using b_io_context = boost::asio::io_service
```

Definition at line 37 of file [monitor_pvt_udp_sink.h](#).

10.8.5.2.3 [b_io_context](#) [3/3]

```
using b_io_context = boost::asio::io_service
```

Definition at line 64 of file [rtcm.h](#).

10.9 Observables

Topics

- [obs_adapters](#)
- [obs_gr_blocks](#)
- [observables_libs](#)

10.9.1 Detailed Description

Classes for the computation of GNSS observables

10.9.2 [obs_adapters](#)

Classes

- class [HybridObservables](#)

This class implements an [ObservablesInterface](#) for observables of all kind of GNSS signals.

10.9.2.1 Detailed Description

Wrap GNU Radio observables blocks with an [ObservablesInterface](#)

10.9.3 obs_gr_blocks

Classes

- class [Gnss_circular_deque< T >](#)
- class [hybrid_observables_gs](#)

This class implements a block that computes observables.

Typedefs

- using [hybrid_observables_gs_sptr](#) = `gnss_shared_ptr<hybrid_observables_gs>`

Functions

- `hybrid_observables_gs_sptr hybrid_observables_gs_make (const Obs_Conf &conf_)`

10.9.3.1 Detailed Description

GNU Radio blocks for the computation of GNSS observables

10.9.3.2 Typedef Documentation

10.9.3.2.1 hybrid_observables_gs_sptr

`using hybrid_observables_gs_sptr = gnss_shared_ptr<hybrid_observables_gs>`

Definition at line 51 of file [hybrid_observables_gs.h](#).

10.9.4 observables_libs

Classes

- class [Obs_Conf](#)

10.9.4.1 Detailed Description

Utilities for GNSS observables configuration.

10.10 Resampler

Topics

- [resampler_adapters](#)
- [resampler_gr_blocks](#)

10.10.1 Detailed Description

Classes for input signal resampling

10.10.2 resampler_adapters

Classes

- class [DirectResamplerConditioner](#)
Interface of an adapter of a direct resampler conditioner block to a [SignalConditionerInterface](#).
- class [MmseResamplerConditioner](#)
Interface of a MMSE resampler block adapter to a [SignalConditionerInterface](#).

10.10.2.1 Detailed Description

Classes that wrap GNU Radio resampler blocks with a [GNSSBlockInterface](#)

10.10.3 resampler_gr_blocks

Classes

- class [direct_resampler_conditioner_cb](#)
This class implements a direct resampler conditioner for `std::complex<signed char>`
- class [direct_resampler_conditioner_cc](#)
This class implements a direct resampler conditioner for complex data.
- class [direct_resampler_conditioner_cs](#)
This class implements a direct resampler conditioner for `std::complex<short>`

Typedefs

- using [direct_resampler_conditioner_cb_sptr](#) = `gnss_shared_ptr<direct_resampler_conditioner_cb>`
- using [direct_resampler_conditioner_cc_sptr](#) = `gnss_shared_ptr<direct_resampler_conditioner_cc>`
- using [direct_resampler_conditioner_cs_sptr](#) = `gnss_shared_ptr<direct_resampler_conditioner_cs>`

Functions

- `direct_resampler_conditioner_cb_sptr` **direct_resampler_make_conditioner_cb** (double sample_freq_in, double sample_freq_out)
- `direct_resampler_conditioner_cc_sptr` **direct_resampler_make_conditioner_cc** (double sample_freq_in, double sample_freq_out)
- `direct_resampler_conditioner_cs_sptr` **direct_resampler_make_conditioner_cs** (double sample_freq_in, double sample_freq_out)

10.10.3.1 Detailed Description

GNU Radio blocks for input signal resampling

10.10.3.2 Typedef Documentation

10.10.3.2.1 direct_resampler_conditioner_cb_sptr

using `direct_resampler_conditioner_cb_sptr` = `gnss_shared_ptr<direct_resampler_conditioner_cb>`
Definition at line 35 of file [direct_resampler_conditioner_cb.h](#).

10.10.3.2.2 direct_resampler_conditioner_cc_sptr

using `direct_resampler_conditioner_cc_sptr` = `gnss_shared_ptr<direct_resampler_conditioner_cc>`
Definition at line 40 of file [direct_resampler_conditioner_cc.h](#).

10.10.3.2.3 direct_resampler_conditioner_cs_sptr

using `direct_resampler_conditioner_cs_sptr` = `gnss_shared_ptr<direct_resampler_conditioner_cs>`
Definition at line 34 of file [direct_resampler_conditioner_cs.h](#).

10.11 Signal Source

Topics

- [signal_source_adapters](#)
- [signal_source_gr_blocks](#)
- [signal_source_libs](#)

10.11.1 Detailed Description

Classes for Signal Source management.

10.11.2 signal_source_adapters

Classes

- class [Ad936xCustomSignalSource](#)
This class instantiates the Ad936xCustom gnuradio signal source. It has support also for a customized Ad936xCustom firmware and signal source to support PPS samplestamp reading.
- class [Adrv9361z7035SignalSourceFPGA](#)
- class [CustomUDPSignalSource](#)
This class reads from UDP packets, which streams interleaved I/Q samples over a network.
- class [DMASignalSourceFPGA](#)
- class [FifoSignalSource](#)
Class that reads a sample stream from a Unix FIFO.
- class [FileSignalSource](#)
Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
- class [FileSourceBase](#)
Base class to file-oriented [SignalSourceBase](#) GNSS blocks.
- class [FileTimestampSignalSource](#)
Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
- class [FlexibandSignalSource](#)
This class configures and reads samples from Teorbit Flexiband front-end. This software requires a Flexiband GNU Radio driver installed (not included with GNSS-SDR).
- class [Fmcomms2SignalSource](#)
- class [Fmcomms5SignalSourceFPGA](#)
- class [FourBitCpxFileSignalSource](#)
Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
- class [GenSignalSource](#)
This class wraps blocks that generates synthesized GNSS signal and filters the signal.
- class [GnMaxSignalSource](#)
This class reads samples from a gnMAX2769 USB dongle, a RF front-end signal sampler.
- class [IONGSMSSignalSource](#)
Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
- class [LabsatSignalSource](#)
This class reads samples stored in LabSat version 2, 3, and 3 Wideband format.
- class [LimesdrSignalSource](#)
This class instantiates the LimeSDR gnuradio signal source. It has support also for a customized LimeSDR firmware and signal source to support PPS samplestamp reading.
- class [MAX2771EVKITSignalSourceFPGA](#)
- class [MultichannelFileSignalSource](#)
Class that reads signals samples from files at different frequency bands and adapts it to a [SignalSourceInterface](#).
- class [NsrFileSignalSource](#)
Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
- class [NTLabFileSignalSource](#)
Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
- class [OsmosdrSignalSource](#)
This class reads samples OmoSDR-compatible front-ends, such as HackRF or Realtek's RTL2832U-based USB dongle DVB-T receivers (see <https://osmocom.org/projects/rtl-sdr/wiki>)
- class [PlutosdrSignalSource](#)
- class [RawArraySignalSource](#)
This class reads samples from an antenna array RF front-end signal sampler.

- class [RtlTcpSignalSource](#)
This class reads from rtl_tcp, which streams interleaved I/Q samples over TCP. (see <https://osmocom.org/projects/rtl-sdr/wiki>)
- class [SpirFileSignalSource](#)
Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
- class [SpirGSS6450FileSignalSource](#)
Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
- class [TwoBitCpxFileSignalSource](#)
Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
- class [TwoBitPackedFileSignalSource](#)
Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
- class [UhdSignalSource](#)
This class reads samples from a UHD device (see <http://code.ettus.com/redmine/ettus/projects/uhd/wiki>)
- class [ZmqSignalSource](#)
This class supports the following properties:

10.11.2.1 Detailed Description

Classes that wrap GNU Radio signal sources with a [GNSSBlockInterface](#)

10.11.3 signal_source_gr_blocks

Classes

- class [ad936x_iio_source](#)
This class implements conversion between Labsat 2, 3 and 3 Wideband formats to gr_complex.
- class [FifoReader](#)
- class [Gr_Complex_Ip_Packet_Source](#)
- class [IONGSMSFileSource](#)
- class [labsat23_source](#)
This class implements conversion between Labsat 2, 3 and 3 Wideband formats to gr_complex.
- class [rtl_tcp_signal_source_c](#)
This class reads interleaved I/Q samples from an rtl_tcp server and outputs complex types.
- class [unpack_2bit_samples](#)
This class takes 2 bit samples that have been packed into bytes or shorts as input and generates a byte for each sample. It generates eight times as much data as is input (every two bits become 16 bits)
- class [unpack_byte_2bit_cpx_samples](#)
This class implements conversion between byte packet samples to 2bit_cpx samples 1 byte = 2 x complex 2bit I, + 2bit Q samples.
- class [unpack_byte_2bit_samples](#)
This class implements conversion between byte packet samples to 2bit samples 1 byte = 4 2bit samples.
- class [unpack_byte_4bit_samples](#)
This class implements conversion between byte packet samples to 4bit_cpx samples 1 byte = 1 x complex 4bit I, + 4bit Q samples.
- class [unpack_intspir_1bit_samples](#)
This class implements conversion between byte packet samples to 2bit samples 1 byte = 4 2bit samples.
- class [unpack_ntlab_2bit_samples](#)
This class implements conversion between byte packet multichannel samples to 2bit samples 1 byte = 4 2bit samples.
- class [unpack_short_byte_samples](#)
This class implements conversion between short packet samples to byte samples 1 short = 2 byte samples.
- class [unpack_spir_gss6450_samples](#)

Typedefs

- using [ad936x_iio_source_sptr](#) = gnss_shared_ptr<[ad936x_iio_source](#)>
- using [labsat23_source_sptr](#) = gnss_shared_ptr<[labsat23_source](#)>
- using [rtl_tcp_signal_source_c_sptr](#) = gnss_shared_ptr<[rtl_tcp_signal_source_c](#)>
- using [b_io_context](#) = boost::asio::io_service
- using [unpack_2bit_samples_sptr](#) = gnss_shared_ptr<[unpack_2bit_samples](#)>
- using [unpack_byte_2bit_cpx_samples_sptr](#) = gnss_shared_ptr<[unpack_byte_2bit_cpx_samples](#)>
- using [unpack_byte_2bit_samples_sptr](#) = gnss_shared_ptr<[unpack_byte_2bit_samples](#)>
- using [unpack_byte_4bit_samples_sptr](#) = gnss_shared_ptr<[unpack_byte_4bit_samples](#)>
- using [unpack_intspir_1bit_samples_sptr](#) = gnss_shared_ptr<[unpack_intspir_1bit_samples](#)>
- using [unpack_ntlab_2bit_samples_sptr](#) = gnss_shared_ptr<[unpack_ntlab_2bit_samples](#)>
- using [unpack_short_byte_samples_sptr](#) = gnss_shared_ptr<[unpack_short_byte_samples](#)>
- using [unpack_spir_gss6450_samples_sptr](#) = gnss_shared_ptr<[unpack_spir_gss6450_samples](#)>

Functions

- [ad936x_iio_source_sptr](#) **ad936x_iio_make_source_sptr** (const std::string &pluto_uri_, const std::string &board_type_, int64_t bandwidth_, int64_t sample_rate_, int64_t freq_, const std::string &rf_port_select_↵_, const std::string &rf_filter, const std::string &gain_mode_rx0_, const std::string &gain_mode_rx1_, double rf_gain_rx0_, double rf_gain_rx1_, bool enable_ch0, bool enable_ch1, int64_t freq_2ch, bool ppsmode_↵_, bool customsamplesize_, const std::string &fe_ip_, int fe_ctlport_, int ssize_, int bshift_, bool spattern_, double lo_attenuation_db_, bool high_side_lo_, int tx_lo_channel_)
- [labsat23_source_sptr](#) **labsat23_make_source_sptr** (const char *signal_file_basename, const std::vector<int> &channel_selector, [Concurrent_Queue](#)<pmt::pmt_t> *queue, bool digital_io_enabled, double seconds_to_skip)
- [rtl_tcp_signal_source_c_sptr](#) **rtl_tcp_make_signal_source_c** (const std::string &address, int16_t port, bool flip_iq=false)
- [unpack_2bit_samples_sptr](#) **make_unpack_2bit_samples** (bool big_endian_bytes, size_t item_size, bool big_endian_items, bool reverse_interleaving=false)
- [unpack_byte_2bit_cpx_samples_sptr](#) **make_unpack_byte_2bit_cpx_samples** ()
- [unpack_byte_2bit_samples_sptr](#) **make_unpack_byte_2bit_samples** ()
- [unpack_byte_4bit_samples_sptr](#) **make_unpack_byte_4bit_samples** ()
- [unpack_intspir_1bit_samples_sptr](#) **make_unpack_intspir_1bit_samples** ()
- [unpack_ntlab_2bit_samples_sptr](#) **make_unpack_ntlab_2bit_samples** (size_t item_size, int nchannels=4)
- [unpack_short_byte_samples_sptr](#) **make_unpack_short_byte_samples** ()
- [unpack_spir_gss6450_samples_sptr](#) **make_unpack_spir_gss6450_samples** (int adc_nbit_)

10.11.3.1 Detailed Description

GNU Radio blocks for signal sources.

10.11.3.2 Typedef Documentation

10.11.3.2.1 ad936x_iio_source_sptr

```
using ad936x_iio_source_sptr = gnss_shared_ptr<ad936x_iio_source>
```

Definition at line 45 of file [ad936x_iio_source.h](#).

10.11.3.2.2 b_io_context

```
using b_io_context = boost::asio::io_service
```

Definition at line 53 of file [rtl_tcp_signal_source_c.h](#).

10.11.3.2.3 labsat23_source_sptr

```
using labsat23_source_sptr = gnss_shared_ptr<labsat23_source>
```

Definition at line 43 of file [labsat23_source.h](#).

10.11.3.2.4 rtl_tcp_signal_source_c_sptr

using rtl_tcp_signal_source_c_sptr = gnss_shared_ptr<rtl_tcp_signal_source_c>
 Definition at line 48 of file [rtl_tcp_signal_source_c.h](#).

10.11.3.2.5 unpack_2bit_samples_sptr

using unpack_2bit_samples_sptr = gnss_shared_ptr<unpack_2bit_samples>
 Definition at line 71 of file [unpack_2bit_samples.h](#).

10.11.3.2.6 unpack_byte_2bit_cpx_samples_sptr

using unpack_byte_2bit_cpx_samples_sptr = gnss_shared_ptr<unpack_byte_2bit_cpx_samples>
 Definition at line 36 of file [unpack_byte_2bit_cpx_samples.h](#).

10.11.3.2.7 unpack_byte_2bit_samples_sptr

using unpack_byte_2bit_samples_sptr = gnss_shared_ptr<unpack_byte_2bit_samples>
 Definition at line 32 of file [unpack_byte_2bit_samples.h](#).

10.11.3.2.8 unpack_byte_4bit_samples_sptr

using unpack_byte_4bit_samples_sptr = gnss_shared_ptr<unpack_byte_4bit_samples>
 Definition at line 34 of file [unpack_byte_4bit_samples.h](#).

10.11.3.2.9 unpack_intspir_1bit_samples_sptr

using unpack_intspir_1bit_samples_sptr = gnss_shared_ptr<unpack_intspir_1bit_samples>
 Definition at line 33 of file [unpack_intspir_1bit_samples.h](#).

10.11.3.2.10 unpack_ntlab_2bit_samples_sptr

using unpack_ntlab_2bit_samples_sptr = gnss_shared_ptr<unpack_ntlab_2bit_samples>
 Definition at line 35 of file [unpack_ntlab_2bit_samples.h](#).

10.11.3.2.11 unpack_short_byte_samples_sptr

using unpack_short_byte_samples_sptr = gnss_shared_ptr<unpack_short_byte_samples>
 Definition at line 33 of file [unpack_short_byte_samples.h](#).

10.11.3.2.12 unpack_spir_gss6450_samples_sptr

using unpack_spir_gss6450_samples_sptr = gnss_shared_ptr<unpack_spir_gss6450_samples>
 Definition at line 32 of file [unpack_spir_gss6450_samples.h](#).

10.11.4 signal_source_libs**Classes**

- struct [stream_cfg](#)
- class [ad936x_iio_custom](#)
- class [ad936x_iio_samples](#)
- class [Fpga_buffer_monitor](#)

Class that checks the receiver buffer overflow flags and monitors the status of the receiver buffers.

- class [Fpga_dynamic_bit_selection](#)

Class that controls the switch in the FPGA, which connects the FPGA acquisition and multicorrelator modules to either the DMA or the Analog Front-End.

- class [Fpga_Switch](#)

Class that controls the switch in the FPGA, which connects the FPGA acquisition and multicorrelator modules to either the DMA or the Analog Front-End.

- class [Gnss_Sdr_Timestamp](#)
- class [Gnss_Sdr_Valve](#)

Implementation of a GNU Radio block that sends a STOP message to the control queue right after a specific number of samples have passed through it.

- struct [IONGSMSChunkUnpackingCtx](#)< WT >
- class [Rtl_Tcp_Dongle_Info](#)

This class represents the dongle information which is sent by rtl_tcp.

Macros

- #define [FIR_BUF_SIZE](#) 8192

Enumerations

- enum [iodev](#) { RX , TX }
- enum [RTL_TCP_COMMAND](#) {
RTL_TCP_SET_FREQUENCY = 1 , **RTL_TCP_SET_SAMPLE_RATE** = 2 , **RTL_TCP_SET_GAIN_MODE**
= 3 , **RTL_TCP_SET_GAIN** = 4 ,
RTL_TCP_SET_IF_GAIN = 6 , **RTL_TCP_SET_AGC_MODE** = 8 }

Command IDs for configuration rtl_tcp.

Functions

- void **errchk** (int v, const char *what)
- void **wr_ch_lli** (struct iio_channel *chn, const char *what, int64_t val)
- void **wr_ch_str** (struct iio_channel *chn, const char *what, const char *str)
- struct iio_device * **get_ad9361_phy** (struct iio_context *ctx)
- bool **get_ad9361_stream_dev** (struct iio_context *ctx, enum iodev d, struct iio_device **dev)
- bool **get_ad9361_stream_ch** (struct iio_context *ctx, enum iodev d, struct iio_device *dev, int chid, struct iio_channel **chn)
- bool **get_phy_chan** (struct iio_context *ctx, enum iodev d, int chid, struct iio_channel **chn)
- bool **get_lo_chan** (struct iio_context *ctx, enum iodev d, struct iio_channel **chn)
- bool **cfg_ad9361_streaming_ch** (struct iio_context *ctx, struct [stream_cfg](#) *cfg, enum iodev type, int chid)
- bool **config_ad9361_rx_local** (uint64_t bandwidth_, uint64_t sample_rate_, uint64_t freq0_, uint64_t freq1_↵
_, const std::string &rf_port_select_, bool rx1_enable_, bool rx2_enable_, const std::string &gain_mode_↵
rx1_, const std::string &gain_mode_rx2_, double rf_gain_rx1_, double rf_gain_rx2_, bool quadrature_, bool
rfdc_, bool bbdc_, std::string filter_source_, std::string filter_filename_, float Fpass_, float Fstop_)
- bool **config_ad9361_rx_remote** (const std::string &remote_host, uint64_t bandwidth_, uint64_t sample_↵
rate, uint64_t freq_, const std::string &rf_port_select_, bool rx1_enable_, bool rx2_enable_, const std_↵
::string &gain_mode_rx1_, const std::string &gain_mode_rx2_, double rf_gain_rx1_, double rf_gain_rx2_,
bool quadrature_, bool rfdc_, bool bbdc_, std::string filter_source_, std::string filter_filename_, float Fpass_,
float Fstop_)
- bool **config_ad9361_lo_local** (uint64_t bandwidth_, uint64_t sample_rate_, uint64_t freq_rf_tx_hz_, double
tx_attenuation_db_, int64_t freq_dds_tx_hz_, double scale_dds_dbfs_, double phase_dds_deg_)
- bool **config_ad9361_lo_remote** (const std::string &remote_host, uint64_t bandwidth_, uint64_t sample_↵
rate, uint64_t freq_rf_tx_hz_, double tx_attenuation_db_, int64_t freq_dds_tx_hz_, double scale_dds_↵
dbfs_, double phase_dds_deg_)
- bool **ad9361_disable_lo_remote** (const std::string &remote_host)
- bool **ad9361_disable_lo_local** ()
- bool **load_fir_filter** (std::string &filter, struct iio_device *phy)
- bool **disable_ad9361_rx_local** ()
- bool **disable_ad9361_rx_remote** (const std::string &remote_host)
- gnss_shared_ptr< [Gnss_Sdr_Timestamp](#) > **gnss_sdr_make_timestamp** (size_t sizeof_stream_item,
std::string timestamp_file, double clock_offset_ms, int items_to_samples)
- gnss_shared_ptr< [Gnss_Sdr_Valve](#) > **gnss_sdr_make_valve** (size_t sizeof_stream_item, uint64_t nitems,
[Concurrent_Queue](#)< pmt::pmt_t > *queue)

- `gnss_shared_ptr< Gnss_Sdr_Valve > gnss_sdr_make_valve` (`size_t sizeof_stream_item`, `uint64_t nitems`, `Concurrent_Queue< pmt::pmt_t > *queue`, `bool stop_flowgraph`)
- `boost::system::error_code rtl_tcp_command` (`RTL_TCP_COMMAND id`, `unsigned param`, `boost::asio::ip::tcp::socket &socket`)

Send a command to rtl_tcp over the given socket.

10.11.4.1 Detailed Description

Library with utilities for signal sources.

10.11.4.2 Macro Definition Documentation

10.11.4.2.1 FIR_BUF_SIZE

```
#define FIR_BUF_SIZE 8192
```

Definition at line 33 of file [ad9361_manager.h](#).

10.11.4.3 Enumeration Type Documentation

10.11.4.3.1 iodev

```
enum iodev
```

Definition at line 43 of file [ad9361_manager.h](#).

10.11.4.3.2 RTL_TCP_COMMAND

```
enum RTL_TCP_COMMAND
```

Command IDs for configuration rtl_tcp.

Definition at line 32 of file [rtl_tcp_commands.h](#).

10.11.4.4 Function Documentation

10.11.4.4.1 rtl_tcp_command()

```
boost::system::error_code rtl_tcp_command (
    RTL_TCP_COMMAND id,
    unsigned param,
    boost::asio::ip::tcp::socket & socket)
```

Send a command to rtl_tcp over the given socket.

10.12 Telemetry Decoder

Topics

- [telemetry_decoder_adapters](#)
- [telemetry_decoder_gr_blocks](#)
- [telemetry_decoder_libswiftcnv](#)
- [telemetry_decoder_libs](#)

10.12.1 Detailed Description

Classes for the decoding of GNSS Navigation messages.

Classes for the decoding of GNSS Navigation messages.

Classes for the decoding of GNSS Navigation messages.

10.12.2 telemetry_decoder_adapters

Classes

- class [BeidouB1iTelemetryDecoder](#)
This class implements a NAV data decoder for BEIDOU B1I.
- class [BeidouB3iTelemetryDecoder](#)
This class implements a NAV data decoder for BEIDOU B1I.
- class [GalileoE1BTelemetryDecoder](#)
This class implements a NAV data decoder for Galileo INAV frames in E1B radio link.
- class [GalileoE5aTelemetryDecoder](#)
This class implements a NAV data decoder for Galileo INAV frames in E1B radio link.
- class [GalileoE5bTelemetryDecoder](#)
This class implements a NAV data decoder for Galileo INAV frames in E5b radio link.
- class [GalileoE6TelemetryDecoder](#)
This class implements a NAV data decoder for Galileo CNAV frames in E6 radio link.
- class [GlonassL1CaTelemetryDecoder](#)
This class implements a NAV data decoder for GLONASS L1 C/A.
- class [GlonassL2CaTelemetryDecoder](#)
This class implements a NAV data decoder for GLONASS L2 C/A.
- class [GpsL1CaTelemetryDecoder](#)
This class implements a NAV data decoder for GPS L1 C/A.
- class [GpsL2CTelemetryDecoder](#)
This class implements a NAV data decoder for GPS L2 M.
- class [GpsL5TelemetryDecoder](#)
This class implements a NAV data decoder for GPS L5.
- class [QzssL1TelemetryDecoder](#)
This class implements a NAV data decoder for QZSS L1.
- class [QzssL5TelemetryDecoder](#)
This class implements a NAV data decoder for QZSS L5.
- class [SbasL1TelemetryDecoder](#)
This class implements a NAV data decoder for SBAS frames in L1 radio link.
- class [TelemetryDecoderAdapterBase](#)
Base class for Telemetry Decoder adapters.

10.12.2.1 Detailed Description

Wrap GNU Radio blocks for the decoding of GNSS Navigation messages with a [TelemetryDecoderInterface](#)
 Wrap GNU Radio blocks for the decoding of GNSS Navigation messages with a [TelemetryDecoderInterface](#)
 Wrap GNU Radio blocks for the decoding of GNSS Navigation messages with a [TelemetryDecoderInterface](#)

10.12.3 telemetry_decoder_gr_blocks

Classes

- class [beidou_b1i_telemetry_decoder_gs](#)
This class implements a block that decodes the BeiDou DNAV data.
- class [beidou_b3i_telemetry_decoder_gs](#)
This class implements a block that decodes the BeiDou DNAV data.
- class [galileo_telemetry_decoder_gs](#)
This class implements a block that decodes the INAV and FNAV data defined in Galileo ICD.
- class [glonass_l1_ca_telemetry_decoder_gs](#)
This class implements a block that decodes the GNAV data defined in GLONASS ICD v5.1.
- class [glonass_l2_ca_telemetry_decoder_gs](#)

This class implements a block that decodes the GNAV data defined in GLONASS ICD v5.1.

- class [gps_l1_ca_telemetry_decoder_gs](#)

This class implements a block that decodes the NAV data defined in IS-GPS-200M.

- class [gps_l2c_telemetry_decoder_gs](#)

This class implements a block that decodes CNAV data defined in IS-GPS-200M.

- class [gps_l5_telemetry_decoder_gs](#)

This class implements a GPS L5 Telemetry decoder.

- class [sbas_l1_telemetry_decoder_gs](#)

This class implements a block that decodes the SBAS integrity and corrections data defined in RTCA MOPS DO-229.

- class [telemetry_impl_interface](#)

Common base class for telemetry decoder GNU Radio implementations.

Typedefs

- using [beidou_b1i_telemetry_decoder_gs_sptr](#) = gnss_shared_ptr<[beidou_b1i_telemetry_decoder_gs](#)>
- using [beidou_b3i_telemetry_decoder_gs_sptr](#)
- using [galileo_telemetry_decoder_gs_sptr](#) = gnss_shared_ptr<[galileo_telemetry_decoder_gs](#)>
- using [glonass_l1_ca_telemetry_decoder_gs_sptr](#) = gnss_shared_ptr<[glonass_l1_ca_telemetry_decoder_gs](#)>
- using [glonass_l2_ca_telemetry_decoder_gs_sptr](#) = gnss_shared_ptr<[glonass_l2_ca_telemetry_decoder_gs](#)>
- using [gps_l1_ca_telemetry_decoder_gs_sptr](#) = gnss_shared_ptr<[gps_l1_ca_telemetry_decoder_gs](#)>
- using [gps_l2c_telemetry_decoder_gs_sptr](#) = gnss_shared_ptr<[gps_l2c_telemetry_decoder_gs](#)>
- using [gps_l5_telemetry_decoder_gs_sptr](#) = gnss_shared_ptr<[gps_l5_telemetry_decoder_gs](#)>
- using [sbas_l1_telemetry_decoder_gs_sptr](#) = gnss_shared_ptr<[sbas_l1_telemetry_decoder_gs](#)>
- using [telemetry_impl_interface_sptr](#) = gnss_shared_ptr<[telemetry_impl_interface](#)>

Enumerations

- enum class **L1LnavSystem** { **GPS** , **QZSS** }

Functions

- [beidou_b1i_telemetry_decoder_gs_sptr](#) **beidou_b1i_make_telemetry_decoder_gs** (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf)
- [beidou_b3i_telemetry_decoder_gs_sptr](#) **beidou_b3i_make_telemetry_decoder_gs** (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf)
- [galileo_telemetry_decoder_gs_sptr](#) **galileo_make_telemetry_decoder_gs** (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf, int frame_type)
- [glonass_l1_ca_telemetry_decoder_gs_sptr](#) **glonass_l1_ca_make_telemetry_decoder_gs** (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf)
- [glonass_l2_ca_telemetry_decoder_gs_sptr](#) **glonass_l2_ca_make_telemetry_decoder_gs** (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf)
- [gps_l1_ca_telemetry_decoder_gs_sptr](#) **gps_l1_ca_make_telemetry_decoder_gs** (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf, L1LnavSystem system=L1LnavSystem::GPS)
- [gps_l2c_telemetry_decoder_gs_sptr](#) **gps_l2c_make_telemetry_decoder_gs** (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf)
- [gps_l5_telemetry_decoder_gs_sptr](#) **gps_l5_make_telemetry_decoder_gs** (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf, CnavSystem system=CnavSystem::GPS)
- [sbas_l1_telemetry_decoder_gs_sptr](#) **sbas_l1_make_telemetry_decoder_gs** (const [Gnss_Satellite](#) &satellite, bool dump)

10.12.3.1 Detailed Description

GNU Radio blocks for the demodulation of GNSS navigation messages.

10.12.3.2 Typedef Documentation

10.12.3.2.1 beidou_b1i_telemetry_decoder_gs_sptr

using beidou_b1i_telemetry_decoder_gs_sptr = gnss_shared_ptr<beidou_b1i_telemetry_decoder_gs>

Definition at line 40 of file [beidou_b1i_telemetry_decoder_gs.h](#).

10.12.3.2.2 beidou_b3i_telemetry_decoder_gs_sptr

using beidou_b3i_telemetry_decoder_gs_sptr

Initial value:

```
gnss_shared_ptr<beidou_b3i_telemetry_decoder_gs>
```

Definition at line 37 of file [beidou_b3i_telemetry_decoder_gs.h](#).

10.12.3.2.3 galileo_telemetry_decoder_gs_sptr

using galileo_telemetry_decoder_gs_sptr = gnss_shared_ptr<galileo_telemetry_decoder_gs>

Definition at line 44 of file [galileo_telemetry_decoder_gs.h](#).

10.12.3.2.4 glonass_l1_ca_telemetry_decoder_gs_sptr

using glonass_l1_ca_telemetry_decoder_gs_sptr = gnss_shared_ptr<glonass_l1_ca_telemetry_decoder_gs>

Definition at line 40 of file [glonass_l1_ca_telemetry_decoder_gs.h](#).

10.12.3.2.5 glonass_l2_ca_telemetry_decoder_gs_sptr

using glonass_l2_ca_telemetry_decoder_gs_sptr = gnss_shared_ptr<glonass_l2_ca_telemetry_decoder_gs>

Definition at line 39 of file [glonass_l2_ca_telemetry_decoder_gs.h](#).

10.12.3.2.6 gps_l1_ca_telemetry_decoder_gs_sptr

using gps_l1_ca_telemetry_decoder_gs_sptr = gnss_shared_ptr<gps_l1_ca_telemetry_decoder_gs>

Definition at line 48 of file [gps_l1_ca_telemetry_decoder_gs.h](#).

10.12.3.2.7 gps_l2c_telemetry_decoder_gs_sptr

using gps_l2c_telemetry_decoder_gs_sptr = gnss_shared_ptr<gps_l2c_telemetry_decoder_gs>

Definition at line 40 of file [gps_l2c_telemetry_decoder_gs.h](#).

10.12.3.2.8 gps_l5_telemetry_decoder_gs_sptr

using gps_l5_telemetry_decoder_gs_sptr = gnss_shared_ptr<gps_l5_telemetry_decoder_gs>

Definition at line 42 of file [gps_l5_telemetry_decoder_gs.h](#).

10.12.3.2.9 sbas_l1_telemetry_decoder_gs_sptr

using sbas_l1_telemetry_decoder_gs_sptr = gnss_shared_ptr<sbas_l1_telemetry_decoder_gs>

Definition at line 37 of file [sbas_l1_telemetry_decoder_gs.h](#).

10.12.3.2.10 telemetry_impl_interface_sptr

using telemetry_impl_interface_sptr = gnss_shared_ptr<telemetry_impl_interface>

Definition at line 40 of file [telemetry_impl_interface.h](#).

10.12.3.3 Enumeration Type Documentation

10.12.3.3.1 L1LnavSystem

```
enum class L1LnavSystem [strong]
```

Definition at line 40 of file [gps_l1_ca_telemetry_decoder_gs.h](#).

10.12.4 telemetry_decoder_libswiftcnv

Classes

- struct [cnv_msg_t](#)
- struct [cnv_v27_part_t](#)
- struct [cnv_msg_decoder_t](#)

Macros

- #define [GPS_L2_V27_HISTORY_LENGTH_BITS](#) 64
- #define [GPS_L2C_V27_INIT_BITS](#) (32)
- #define [GPS_L2C_V27_DECODE_BITS](#) (32)
- #define [GPS_L2C_V27_DELAY_BITS](#) (32)
- #define [ABS](#)(x)
- #define [MIN](#)(x, y)
- #define [MAX](#)(x, y)
- #define [CLAMP_DIFF](#)(a, b)

Functions

- uint8_t [parity](#) (uint32_t x)
- uint32_t [getbitu](#) (const uint8_t *buff, uint32_t pos, uint8_t len)
- int32_t [getbits](#) (const uint8_t *buff, uint32_t pos, uint8_t len)
- void [setbitu](#) (uint8_t *buff, uint32_t pos, uint32_t len, uint32_t data)
- void [setbits](#) (uint8_t *buff, uint32_t pos, uint32_t len, int32_t data)
- void [bitcopy](#) (void *dst, uint32_t dst_index, const void *src, uint32_t src_index, uint32_t count)
- void [bitshl](#) (void *buf, uint32_t size, uint32_t shift)
- uint8_t [count_bits_u64](#) (uint64_t v, uint8_t bv)
- uint8_t [count_bits_u32](#) (uint32_t v, uint8_t bv)
- uint8_t [count_bits_u16](#) (uint16_t v, uint8_t bv)
- uint8_t [count_bits_u8](#) (uint8_t v, uint8_t bv)
- const [v27_poly_t](#) * [cnv_msg_decoder_get_poly](#) (void)
- void [cnv_msg_decoder_init](#) ([cnv_msg_decoder_t](#) *dec)
- bool [cnv_msg_decoder_add_symbol](#) ([cnv_msg_decoder_t](#) *dec, unsigned char symbol, [cnv_msg_t](#) *msg, uint32_t *delay)
- uint32_t [crc24q](#) (const uint8_t *buf, uint32_t len, uint32_t crc)
- uint32_t [crc24q_bits](#) (uint32_t crc, const uint8_t *buf, uint32_t n_bits, bool invert)

10.12.4.1 Detailed Description

Utilities for CNAV message decoding by Swift Navigation Inc.

10.12.4.2 Macro Definition Documentation

10.12.4.2.1 ABS

```
#define ABS(  
    x)
```

Value:

```
((x) < 0 ? -(x) : (x))
```

Definition at line 34 of file [swift_common.h](#).

10.12.4.2.2 CLAMP_DIFF

```
#define CLAMP_DIFF(  
    a,  
    b)
```

Value:

```
(MAX((a), (b)) - (b))
```

Definition at line 37 of file [swift_common.h](#).

10.12.4.2.3 GPS_L2_V27_HISTORY_LENGTH_BITS

```
#define GPS_L2_V27_HISTORY_LENGTH_BITS 64
```

Size of the Viterbi decoder history.

Definition at line 40 of file [cnav_msg.h](#).

10.12.4.2.4 GPS_L2C_V27_DECODE_BITS

```
#define GPS_L2C_V27_DECODE_BITS (32)
```

Bits to decode at a time.

Definition at line 44 of file [cnav_msg.h](#).

10.12.4.2.5 GPS_L2C_V27_DELAY_BITS

```
#define GPS_L2C_V27_DELAY_BITS (32)
```

Bits in decoder tail. We ignore them.

Definition at line 46 of file [cnav_msg.h](#).

10.12.4.2.6 GPS_L2C_V27_INIT_BITS

```
#define GPS_L2C_V27_INIT_BITS (32)
```

Bits to accumulate before decoding starts.

Definition at line 42 of file [cnav_msg.h](#).

10.12.4.2.7 MAX

```
#define MAX(  
    x,  
    y)
```

Value:

```
((x) > (y)) ? (x) : (y)
```

Definition at line 36 of file [swift_common.h](#).

10.12.4.2.8 MIN

```
#define MIN(  
    x,  
    y)
```

Value:

```
((x) < (y)) ? (x) : (y)
```

Definition at line 35 of file [swift_common.h](#).

10.12.5 telemetry_decoder_libs

Classes

- class [Tlm_Conf](#)
- class [Tlm_CRC_Stats](#)
Class that computes the telemetry CRC statistics.
- class [Viterbi_Decoder](#)
Class that implements a Viterbi decoder.
- class [Viterbi_Decoder_Sbas](#)
Class that implements a Viterbi decoder.
- class [Serdes_Nav_Message](#)
This class implements serialization and deserialization of [Nav_Message_Packet](#) objects using Protocol Buffers.

Functions

- int **save_tlm_matfile** (const std::string &dumpfile)
- bool **tlm_remove_file** (const std::string &file_to_remove)

10.12.5.1 Detailed Description

Utilities for the decoding of GNSS navigation messages.

10.13 Tracking

Topics

- [tracking_adapters](#)
- [tracking_gr_blocks](#)
- [tracking_libs](#)

10.13.1 Detailed Description

Classes for GNSS signal tracking.
 Classes for GNSS signal tracking.
 Classes for GNSS signal tracking.
 Classes for GNSS signal tracking.
 Classes for GNSS signal tracking.
 Classes for GNSS signal tracking.
 Classes for GNSS signal tracking.
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 Classes for GNSS signal tracking.
 Classes for GNSS signal tracking.
 Classes for GNSS signal tracking.
 Classes for GNSS signal tracking.
 Classes for GNSS signal tracking.

10.13.2 tracking_adapters

Classes

- class [BaseDIIPITracking](#)
Base class providing shared logic for DLL+PLL tracking loop adapters for GNSS signals.
- class [BaseDIIPITrackingFpga](#)
- class [BeidouB1iDIIPITracking](#)
This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for BeiDou B1I signals.
- class [BeidouB3iDIIPITracking](#)
This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for BeiDou B3I signals.
- class [GalileoE1DIPIIVemITracking](#)
This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E1 signals.
- class [GalileoE1DIPIIVemITrackingFpga](#)
Adapter for a Galileo E1 DLL+PLL VEML tracking loop block in FPGA.
- class [GalileoE1TcpConnectorTracking](#)
This class implements a code DLL + carrier PLL tracking loop.
- class [GalileoE5aDIIPITracking](#)
This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E5a signals.
- class [GalileoE5aDIIPITrackingFpga](#)
Adapter for a Galileo E5a DLL+PLL tracking loop implemented in FPGA.
- class [GalileoE5bDIIPITracking](#)
This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E5b signals.

- class [GalileoE6DIPIITracking](#)
This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E5a signals.
- class [GlonassL1CaDIPIITracking](#)
This class implements a code DLL + carrier PLL tracking loop block adapter for GLONASS L1 signals.
- class [GlonassL2CaDIPIITracking](#)
This class implements a code DLL + carrier PLL tracking loop block adapter for GLONASS L2 signals.
- class [GpsL1CaDIPIITracking](#)
This class implements a code DLL + carrier PLL tracking loop block adapter for GPS L1 C/A signals.
- class [GpsL1CaDIPIITrackingFpga](#)
Adapter for a GPS L1 C/A DLL+PLL tracking loop for FPGA.
- class [GpsL1CaDIPIITrackingGPU](#)
This class implements a code DLL + carrier PLL tracking loop using GPU accelerated functions.
- class [GpsL1CaGaussianTracking](#)
This class implements a code DLL + carrier PLL tracking loop.
- class [GpsL1CaTcpConnectorTracking](#)
This class implements a code DLL + carrier PLL tracking loop.
- class [GpsL2MDIPIITracking](#)
This class implements a code DLL + carrier PLL tracking loop block adapter for GPS L2C(M) signals.
- class [GpsL2MDIPIITrackingFpga](#)
Adapter for a GPS L2M DLL+PLL tracking loop implemented in FPGA.
- class [GpsL5DIPIITracking](#)
This class implements a code DLL + carrier PLL tracking loop block adapter for GPS L5 signals.
- class [GpsL5DIPIITrackingFpga](#)
Adapter for a GPS L5 DLL+PLL tracking loop for FPGA devices.
- class [QzssL1DIPIITracking](#)
This class implements a code DLL + carrier PLL tracking loop block adapter for QZSS L1 signals.
- class [QzssL5DIPIITracking](#)
This class implements a code DLL + carrier PLL tracking loop block adapter for QZSS L5 signals.

10.13.2.1 Detailed Description

Wrap GNU Radio blocks for GNSS signal tracking with a [TrackingInterface](#)
 Wrap GNU Radio blocks for GNSS signal tracking with a [TrackingInterface](#)
 Wrap GNU Radio blocks for GNSS signal tracking with a [TrackingInterface](#)
 Wrap GNU Radio blocks for GNSS signal tracking with a [TrackingInterface](#)
 Wrap GNU Radio blocks for GNSS signal tracking with a [TrackingInterface](#)
 Wrap GNU Radio blocks for GNSS signal tracking with a [TrackingInterface](#)
 Wrap GNU Radio blocks for GNSS signal tracking with a [TrackingInterface](#)
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 Wrap GNU Radio blocks for GNSS signal tracking with a [TrackingInterface](#)
 Wrap GNU Radio blocks for GNSS signal tracking with a [TrackingInterface](#)
 Wrap GNU Radio blocks for GNSS signal tracking with a [TrackingInterface](#)
 Wrap GNU Radio blocks for GNSS signal tracking with a [TrackingInterface](#)

10.13.3 tracking_gr_blocks

Classes

- class [dll_pll_veml_tracking](#)
This class implements a code DLL + carrier PLL tracking block.
- class [dll_pll_veml_tracking_fpga](#)

This class implements a code DLL + carrier PLL tracking block.

- class [Galileo_E1_Tcp_Connector_Tracking_cc](#)

This class implements a code DLL + carrier PLL VEML (Very Early Minus Late) tracking block for Galileo E1 signals.

- class [Gps_L1_Ca_Dll_Pll_Tracking_GPU_cc](#)

This class implements a DLL + PLL tracking loop block.

- class [Gps_L1_Ca_Gaussian_Tracking_cc](#)

This class implements a DLL + PLL tracking loop block.

- class [Gps_L1_Ca_Tcp_Connector_Tracking_cc](#)

This class implements a DLL + PLL tracking loop block.

Typedefs

- using [dll_pll_veml_tracking_sptr](#) = gnss_shared_ptr<[dll_pll_veml_tracking](#)>
- using [dll_pll_veml_tracking_fpga_sptr](#) = gnss_shared_ptr<[dll_pll_veml_tracking_fpga](#)>
- using [galileo_e1_tcp_connector_tracking_cc_sptr](#) = gnss_shared_ptr<[Galileo_E1_Tcp_Connector_Tracking_cc](#)>
- using [gps_l1_ca_dll_pll_tracking_gpu_cc_sptr](#) = gnss_shared_ptr<[Gps_L1_Ca_Dll_Pll_Tracking_GPU_cc](#)>
- using [gps_l1_ca_gaussian_tracking_cc_sptr](#) = gnss_shared_ptr<[Gps_L1_Ca_Gaussian_Tracking_cc](#)>
- using [gps_l1_ca_tcp_connector_tracking_cc_sptr](#) = gnss_shared_ptr<[Gps_L1_Ca_Tcp_Connector_Tracking_cc](#)>

Functions

- [dll_pll_veml_tracking_sptr](#) **[dll_pll_veml_make_tracking](#)** (const [Dll_Pll_Conf](#) &conf_)
- [dll_pll_veml_tracking_fpga_sptr](#) **[dll_pll_veml_make_tracking_fpga](#)** (const [Dll_Pll_Conf_Fpga](#) &conf_)
- [galileo_e1_tcp_connector_tracking_cc_sptr](#) **[galileo_e1_tcp_connector_make_tracking_cc](#)** (int64_t fs_in, uint32_t vector_length, bool dump, const std::string &dump_filename, float pll_bw_hz, float dll_bw_hz, float early_late_space_chips, float very_early_late_space_chips, size_t port_ch0)
- [gps_l1_ca_dll_pll_tracking_gpu_cc_sptr](#) **[gps_l1_ca_dll_pll_make_tracking_gpu_cc](#)** (int64_t fs_in, uint32_t vector_length, bool dump, std::string dump_filename, float pll_bw_hz, float dll_bw_hz, float early_late_space_chips)
- [gps_l1_ca_gaussian_tracking_cc_sptr](#) **[gps_l1_ca_gaussian_make_tracking_cc](#)** (uint32_t order, int64_t fs_in, uint32_t vector_length, bool dump, const std::string &dump_filename, float dll_bw_hz, float early_late_space_chips, bool bce_run, uint32_t bce_ptrans, uint32_t bce_strans, int32_t bce_nu, int32_t bce_kappa)
- [gps_l1_ca_tcp_connector_tracking_cc_sptr](#) **[gps_l1_ca_tcp_connector_make_tracking_cc](#)** (int64_t fs_in, uint32_t vector_length, bool dump, const std::string &dump_filename, float early_late_space_chips, size_t port_ch0)

10.13.3.1 Detailed Description

GNU Radio blocks for GNSS signal tracking.

10.13.3.2 Typedef Documentation

10.13.3.2.1 [dll_pll_veml_tracking_fpga_sptr](#)

```
using dll\_pll\_veml\_tracking\_fpga\_sptr = gnss_shared_ptr<dll\_pll\_veml\_tracking\_fpga>
```

Definition at line 51 of file [dll_pll_veml_tracking_fpga.h](#).

10.13.3.2.2 [dll_pll_veml_tracking_sptr](#)

```
using dll\_pll\_veml\_tracking\_sptr = gnss_shared_ptr<dll\_pll\_veml\_tracking>
```

Definition at line 54 of file [dll_pll_veml_tracking.h](#).

10.13.3.2.3 [galileo_e1_tcp_connector_tracking_cc_sptr](#)

```
using galileo\_e1\_tcp\_connector\_tracking\_cc\_sptr = gnss_shared_ptr<Galileo\_E1\_Tcp\_Connector\_Tracking\_cc>
```

Definition at line 46 of file [galileo_e1_tcp_connector_tracking_cc.h](#).

10.13.3.2.4 `gps_l1_ca_dll_pll_tracking_gpu_cc_sptr`

using `gps_l1_ca_dll_pll_tracking_gpu_cc_sptr = gnss_shared_ptr<Gps_L1_Ca_Dll_Pll_Tracking_GPU_cc>`
 Definition at line 44 of file `gps_l1_ca_dll_pll_tracking_gpu_cc.h`.

10.13.3.2.5 `gps_l1_ca_gaussian_tracking_cc_sptr`

using `gps_l1_ca_gaussian_tracking_cc_sptr = gnss_shared_ptr<Gps_L1_Ca_Gaussian_Tracking_cc>`
 Definition at line 54 of file `gps_l1_ca_gaussian_tracking_cc.h`.

10.13.3.2.6 `gps_l1_ca_tcp_connector_tracking_cc_sptr`

using `gps_l1_ca_tcp_connector_tracking_cc_sptr = gnss_shared_ptr<Gps_L1_Ca_Tcp_Connector_Tracking_cc>`
 Definition at line 44 of file `gps_l1_ca_tcp_connector_tracking_cc.h`.

10.13.4 `tracking_libs`

Classes

- class `Bayesian_estimator`
Bayesian_estimator is an estimator of noise characteristics (i.e. mean, covariance)
- class `HistogramBitSynchronizer`
Histogram-based navigation data bit synchronizer.
- class `Cpu_Multicorrelator`
Class that implements carrier wipe-off and correlators.
- class `Cpu_Multicorrelator_16sc`
Class that implements carrier wipe-off and correlators.
- class `Cpu_Multicorrelator_Real_Codes`
Class that implements carrier wipe-off and correlators.
- struct `GPU_Complex`
- struct `GPU_Complex_Short`
- class `cuda_multicorrelator`
Class that implements carrier wipe-off and correlators using NVIDIA CUDA GPU accelerators.
- class `Dll_Pll_Conf`
- class `Dll_Pll_Conf_Fpga`
- class `Exponential_Smoother`
Class that implements a first-order exponential smoother.
- class `Fpga_Multicorrelator_8sc`
Class that implements carrier wipe-off and correlators.
- class `ModelFunction`
- class `CubatureFilter`
- class `UnscentedFilter`
- class `Tcp_Communication`
TCP communication class.
- class `Tcp_Packet_Data`
Class that implements a TCP data packet.
- class `Tracking_2nd_DLL_filter`
This class implements a 2nd order DLL filter for code tracking loop.
- class `Tracking_2nd_PLL_filter`
This class implements a 2nd order PLL filter for carrier tracking loop.
- class `Tracking_FLL_PLL_filter`
This class implements a hybrid FLL and PLL filter for tracking carrier loop.
- class `Tracking_loop_filter`
This class implements a generic 1st, 2nd or 3rd order loop filter.

Macros

- `#define NUM_TX_VARIABLES_GALILEO_E1` 13
- `#define NUM_TX_VARIABLES_GPS_L1_CA` 9
- `#define NUM_RX_VARIABLES` 4

Typedefs

- using `b_io_context` = `boost::asio::io_service`

Functions

- float `cn0_svn_estimator` (const gr_complex *Prompt_buffer, int length, float coh_integration_time_s)
cn0_svn_estimator is a Carrier-to-Noise (CN0) estimator based on the Signal-to-Noise Variance (SNV) estimator
- float `cn0_m2m4_estimator` (const gr_complex *Prompt_buffer, int length, float coh_integration_time_s)
cn0_m2m4_estimator is a Carrier-to-Noise (CN0) estimator based on the Second- and Fourth-Order Moments Method (M2M4)
- float `carrier_lock_detector` (const gr_complex *Prompt_buffer, int length)
A carrier lock detector.
- double `fil_four_quadrant_atan` (gr_complex prompt_s1, gr_complex prompt_s2, double t1, double t2)
- double `fil_diff_atan` (gr_complex prompt_s1, gr_complex prompt_s2, double t1, double t2)
- double `phase_unwrap` (double phase_rad)
Phase unwrapping function, input is [rad].
- double `pll_four_quadrant_atan` (gr_complex prompt_s1)
PLL four quadrant arctan discriminator.
- double `pll_cloop_two_quadrant_atan` (gr_complex prompt_s1)
PLL Costas loop two quadrant arctan discriminator.
- double `dll_nc_e_minus_l_normalized` (gr_complex early_s1, gr_complex late_s1, float spc=0.5, float slope=1.0, float y_intercept=1.0)
DLL Noncoherent Early minus Late envelope normalized discriminator.
- double `dll_nc_vemlp_normalized` (gr_complex very_early_s1, gr_complex early_s1, gr_complex late_s1, gr_complex very_late_s1)
DLL Noncoherent Very Early Minus Late Power (VEMLP) normalized discriminator.
- template<typename Fun>
double `CalculateSlope` (Fun &&f, double x)
- template<typename Fun>
double `CalculateSlopeAbs` (Fun &&f, double x)
- template<typename Fun>
double `GetYIntercept` (Fun &&f, double x)
- template<typename Fun>
double `GetYInterceptAbs` (Fun &&f, double x)
- template<int M = 1, int N = M>
double `SinBocCorrelationFunction` (double offset_in_chips)
- template<int M = 1, int N = M>
double `CosBocCorrelationFunction` (double offset_in_chips)

10.13.4.1 Detailed Description

Utilities for GNSS signal tracking.

10.13.4.2 Macro Definition Documentation

10.13.4.2.1 NUM_RX_VARIABLES

```
#define NUM_RX_VARIABLES 4
```

Definition at line 39 of file [tcp_communication.h](#).

10.13.4.2.2 NUM_TX_VARIABLES_GALILEO_E1

```
#define NUM_TX_VARIABLES_GALILEO_E1 13
```

Definition at line 37 of file [tcp_communication.h](#).

10.13.4.2.3 NUM_TX_VARIABLES_GPS_L1_CA

```
#define NUM_TX_VARIABLES_GPS_L1_CA 9
```

Definition at line 38 of file [tcp_communication.h](#).

10.13.4.3 Typedef Documentation

10.13.4.3.1 b_io_context

```
using b_io_context = boost::asio::io_service
```

Definition at line 34 of file [tcp_communication.h](#).

10.13.4.4 Function Documentation

10.13.4.4.1 CalculateSlope()

```
template<typename Fun>
double CalculateSlope (
    Fun && f,
    double x)
```

Definition at line 112 of file [tracking_discriminators.h](#).

10.13.4.4.2 CalculateSlopeAbs()

```
template<typename Fun>
double CalculateSlopeAbs (
    Fun && f,
    double x)
```

Definition at line 120 of file [tracking_discriminators.h](#).

10.13.4.4.3 carrier_lock_detector()

```
float carrier_lock_detector (
    const gr_complex * Prompt_buffer,
    int length)
```

A carrier lock detector.

The Carrier Phase Lock Detector block uses the estimate of the cosine of twice the carrier phase error is given by

$$C2\phi = \frac{NBD}{NBP}, \quad (10.1)$$

where $NBD = (\sum_{i=0}^{N-1} |Im(Pc(i))|)^2 + (\sum_{i=0}^{N-1} |Re(Pc(i))|)^2$, $NBP = \sum_{i=0}^{N-1} Im(Pc(i))^2 - \sum_{i=0}^{N-1} Re(Pc(i))^2$, and $Pc(i)$ is the prompt correlator output for the sample index i . Ref: Van Dierendonck, A.J. (1996), Global Positioning System: Theory and Applications, Volume I, Chapter 8: GPS Receivers, AJ Systems, Los Altos, CA 94024. Inc.: 329-407.

10.13.4.4.4 cn0_m2m4_estimator()

```
float cn0_m2m4_estimator (
    const gr_complex * Prompt_buffer,
    int length,
    float coh_integration_time_s)
```

cn0_m2m4_estimator is a Carrier-to-Noise (CN0) estimator based on the Second- and Fourth-Order Moments Method (M2M4)

Signal-to-Noise (SNR) (ρ) estimator using the Moments Method:

$$\hat{\rho} = \frac{\sqrt{2\hat{M}_2^2 - \hat{M}_4}}{\hat{M}_2 - \sqrt{2\hat{M}_2^2 - \hat{M}_4}}, \quad (10.2)$$

where $\hat{M}_2 = \frac{1}{N} \sum_{k=0}^{K-1} |P[k]|^2$, $\hat{M}_4 = \frac{1}{K} \sum_{k=0}^{K-1} |P[k]|^4$, $|\cdot|$ is the absolute value, and $P[k]$ is the prompt correlator output for the sample index k .

The SNR value is converted to CN0 [dB-Hz] taking into account the coherent integration time, using the following formula:

$$CN0_{dB} = 10 * \log(\hat{\rho}) - 10 * \log(T_{int}), \quad (10.3)$$

where T_{int} is the coherent integration time, in seconds.

Ref: D. R. Pauluzzi, N. C. Beaulieu, "A comparison of SNR estimation techniques for the AWGN channel," IEEE Trans. on Comm., vol. 48, no. 10, pp. 1681–1691, Oct. 2000.

10.13.4.4.5 cn0_svn_estimator()

```
float cn0_svn_estimator (
    const gr_complex * Prompt_buffer,
    int length,
    float coh_integration_time_s)
```

cn0_svn_estimator is a Carrier-to-Noise (CN0) estimator based on the Signal-to-Noise Variance (SNV) estimator Signal-to-Noise (SNR) (ρ) estimator using the Signal-to-Noise Variance (SNV) estimator:

$$\hat{\rho} = \frac{\hat{P}_s}{\hat{P}_n} = \frac{\hat{P}_s}{\hat{P}_{tot} - \hat{P}_s}, \quad (10.4)$$

where $\hat{P}_s = \left(\frac{1}{N} \sum_{i=0}^{N-1} |Re(Pc(i))| \right)^2$ is the estimation of the signal power, $\hat{P}_{tot} = \frac{1}{N} \sum_{i=0}^{N-1} |Pc(i)|^2$ is the estimator of the total power, $|\cdot|$ is the absolute value, $Re(\cdot)$ stands for the real part of the value, and $Pc(i)$ is the prompt correlator output for the sample index i .

The SNR value is converted to CN0 [dB-Hz], taking into account the coherent integration time, using the following formula:

$$CN0_{dB} = 10 * \log(\hat{\rho}) - 10 * \log(T_{int}), \quad (10.5)$$

where T_{int} is the coherent integration time, in seconds.

Ref: Marco Pini, Emanuela Falletti and Maurizio Fantino, "Performance Evaluation of C/N0 Estimators using a Real Time GNSS Software Receiver," IEEE 10th International Symposium on Spread Spectrum Techniques and Applications, pp.28-30, August 2008.

10.13.4.4.6 CosBocCorrelationFunction()

```
template<int M = 1, int N = M>
double CosBocCorrelationFunction (
    double offset_in_chips)
```

Definition at line 171 of file [tracking_discriminators.h](#).

10.13.4.4.7 dll_nc_e_minus_l_normalized()

```
double dll_nc_e_minus_l_normalized (
    gr_complex early_s1,
    gr_complex late_s1,
    float spc = 0.5,
    float slope = 1.0,
    float y_intercept = 1.0)
```

DLL Noncoherent Early minus Late envelope normalized discriminator.

DLL Noncoherent Early minus Late envelope normalized discriminator:

$$error = \frac{y_{intercept} - slope * \epsilon}{slope} \frac{E - L}{E + L}, \quad (10.6)$$

where $E = \sqrt{I_{ES}^2 + Q_{ES}^2}$ is the Early correlator output absolute value and $L = \sqrt{I_{LS}^2 + Q_{LS}^2}$ is the Late correlator output absolute value. The output is in [chips].

10.13.4.4.8 dll_nc_vemlp_normalized()

```
double dll_nc_vemlp_normalized (
    gr_complex very_early_s1,
    gr_complex early_s1,
    gr_complex late_s1,
    gr_complex very_late_s1)
```

DLL Noncoherent Very Early Minus Late Power (VEMLP) normalized discriminator.

DLL Noncoherent Very Early Minus Late Power (VEMLP) normalized discriminator, using the outputs of four correlators, Very Early (VE), Early (E), Late (L) and Very Late (VL):

$$error = \frac{E - L}{E + L}, \quad (10.7)$$

where $E = \sqrt{I_{VE}^2 + Q_{VE}^2 + I_E^2 + Q_E^2}$ and $L = \sqrt{I_{VL}^2 + Q_{VL}^2 + I_L^2 + Q_L^2}$. The output is in [chips].

10.13.4.4.9 flf_four_quadrant_atan()

```
double flf_four_quadrant_atan (
    gr_complex prompt_s1,
    gr_complex prompt_s2,
    double t1,
    double t2)
```

brief FLL four quadrant arctan discriminator

FLL four quadrant arctan discriminator:

$$\frac{\phi_2 - \phi_1}{t_2 - t_1} = \frac{ATAN2(cross, dot)}{t_1 - t_2}, \quad (10.8)$$

where $cross = I_{PS1}Q_{PS2} - I_{PS2}Q_{PS1}$ and $dot = I_{PS1}I_{PS2} + Q_{PS1}Q_{PS2}$, I_{PS1}, Q_{PS1} are the inphase and quadrature prompt correlator outputs respectively at sample time t_1 , and I_{PS2}, Q_{PS2} are the inphase and quadrature prompt correlator outputs respectively at sample time t_2 . The output is in [radians/second].

10.13.4.4.10 GetYIntercept()

```
template<typename Fun>
double GetYIntercept (
    Fun && f,
    double x)
```

Definition at line 128 of file [tracking_discriminators.h](#).

10.13.4.4.11 GetYInterceptAbs()

```
template<typename Fun>
double GetYInterceptAbs (
    Fun && f,
    double x)
```

Definition at line 137 of file [tracking_discriminators.h](#).

10.13.4.4.12 phase_unwrap()

```
double phase_unwrap (
    double phase_rad)
```

Phase unwrapping function, input is [rad].

10.13.4.4.13 pll_cloop_two_quadrant_atan()

```
double pll_cloop_two_quadrant_atan (
    gr_complex prompt_s1)
```

PLL Costas loop two quadrant arctan discriminator.

PLL Costas loop two quadrant arctan discriminator:

$$\phi = ATAN\left(\frac{Q_{PS}}{I_{PS}}\right), \quad (10.9)$$

where I_{PS1} , Q_{PS1} are the inphase and quadrature prompt correlator outputs respectively. The output is in [radians].

10.13.4.4.14 pll_four_quadrant_atan()

```
double pll_four_quadrant_atan (
    gr_complex prompt_sl)
```

PLL four quadrant arctan discriminator.

PLL four quadrant arctan discriminator:

$$\phi = ATAN2(Q_{PS}, I_{PS}), \quad (10.10)$$

where I_{PS1} , Q_{PS1} are the inphase and quadrature prompt correlator outputs respectively. The output is in [radians].

10.13.4.4.15 SinBocCorrelationFunction()

```
template<int M = 1, int N = M>
double SinBocCorrelationFunction (
    double offset_in_chips)
```

Definition at line 150 of file [tracking_discriminators.h](#).

Chapter 11

Namespace Documentation

11.1 std Namespace Reference

STL namespace.

Classes

- class **allocator**
STL class.
- class **array**
STL class.
- class **atomic**
STL class.
- class **atomic_ref**
STL class.
- class **auto_ptr**
STL class.
- class **bad_alloc**
STL class.
- class **bad_cast**
STL class.
- class **bad_exception**
STL class.
- class **bad_typeid**
STL class.
- class **basic_fstream**
STL class.
- class **basic_ifstream**
STL class.
- class **basic_ios**
STL class.
- class **basic_iostream**
STL class.
- class **basic_istream**
STL class.
- class **basic_istreamstream**
STL class.
- class **basic_ofstream**
STL class.

- class **basic_ostream**
STL class.
- class **basic_ostringstream**
STL class.
- class **basic_string**
STL class.
- class **basic_string_view**
STL class.
- class **basic_stringstream**
STL class.
- class **bitset**
STL class.
- class **complex**
STL class.
- class **deque**
STL class.
- class **domain_error**
STL class.
- class **error_category**
STL class.
- class **error_code**
STL class.
- class **error_condition**
STL class.
- class **exception**
STL class.
- class **forward_list**
STL class.
- class **fstream**
STL class.
- struct [hash< SensorIdentifier::value_type >](#)
- class **ifstream**
STL class.
- class **invalid_argument**
STL class.
- class **ios**
STL class.
- class **ios_base**
STL class.
- class **istream**
STL class.
- class **istringstream**
STL class.
- class **jthread**
STL class.
- class **length_error**
STL class.
- class **list**
STL class.
- class **lock_guard**
STL class.

- class **logic_error**
STL class.
- class **map**
STL class.
- class **multimap**
STL class.
- class **multiset**
STL class.
- class **mutex**
STL class.
- class **ofstream**
STL class.
- class **ostream**
STL class.
- class **ostringstream**
STL class.
- class **out_of_range**
STL class.
- class **overflow_error**
STL class.
- class **pair**
STL class.
- class **priority_queue**
STL class.
- class **queue**
STL class.
- class **range_error**
STL class.
- class **recursive_mutex**
STL class.
- class **recursive_timed_mutex**
STL class.
- class **runtime_error**
STL class.
- class **set**
STL class.
- class **shared_lock**
STL class.
- class **shared_mutex**
STL class.
- class **shared_ptr**
STL class.
- class **shared_timed_mutex**
STL class.
- class **smart_ptr**
STL class.
- class **span**
STL class.
- class **stack**
STL class.
- class **string**

- STL class.*
- class **string_view**
 - STL class.*
- class **stringstream**
 - STL class.*
- class **system_error**
 - STL class.*
- class **thread**
 - STL class.*
- class **timed_mutex**
 - STL class.*
- class **u16string**
 - STL class.*
- class **u16string_view**
 - STL class.*
- class **u32string**
 - STL class.*
- class **u32string_view**
 - STL class.*
- class **u8string**
 - STL class.*
- class **u8string_view**
 - STL class.*
- class **underflow_error**
 - STL class.*
- class **unique_lock**
 - STL class.*
- class **unique_ptr**
 - STL class.*
- class **unordered_map**
 - STL class.*
- class **unordered_multimap**
 - STL class.*
- class **unordered_multiset**
 - STL class.*
- class **unordered_set**
 - STL class.*
- class **valarray**
 - STL class.*
- class **vector**
 - STL class.*
- class **weak_ptr**
 - STL class.*
- class **wfstream**
 - STL class.*
- class **wifstream**
 - STL class.*
- class **wios**
 - STL class.*
- class **wistream**
 - STL class.*

- class **wistringstream**
STL class.
- class **wofstream**
STL class.
- class **wostream**
STL class.
- class **wostringstream**
STL class.
- class **wstring**
STL class.
- class **wstring_view**
STL class.
- class **wstringstream**
STL class.

11.1.1 Detailed Description

STL namespace.

Chapter 12

Class Documentation

12.1 Acq_Conf Class Reference

Public Member Functions

- void **SetFromConfiguration** (const [ConfigurationInterface](#) *configuration, const std::string &role, double chip_rate, double opt_freq)

Public Attributes

- std::string [item_type](#) {"gr_complex"}
- std::string [dump_filename](#)
- int64_t [fs_in](#) {4000000LL}
- int64_t [resampled_fs](#) {0LL}
- size_t [it_size](#) {sizeof(gr_complex)}
- float [samples_per_ms](#) {0.0}
- float [doppler_step2](#) {125.0}
- float [threshold](#) {0.0}
- float [pfa](#) {0.0}
- float [pfa2](#) {0.0}
- float [samples_per_code](#) {0.0}
- float [resampler_ratio](#) {1.0}
- uint32_t [sampled_ms](#) {1U}
- uint32_t [ms_per_code](#) {1U}
- uint32_t [samples_per_chip](#) {2U}
- uint32_t [chips_per_second](#) {1023000U}
- uint32_t [max_dwells](#) {1U}
- uint32_t [num_doppler_bins_step2](#) {4U}
- uint32_t [resampler_latency_samples](#) {0U}
- uint32_t [dump_channel](#) {0U}
- int32_t [doppler_max](#) {5000}
- int32_t [doppler_min](#) {-5000}
- int32_t [doppler_step](#) {500}
- bool [bit_transition_flag](#) {false}
- bool [use_CFAR_algorithm_flag](#) {true}
- bool [dump](#) {false}
- bool [blocking](#) {true}
- bool [blocking_on_standby](#) {false}
- bool [make_2_steps](#) {false}
- bool [use_automatic_resampler](#) {false}
- bool [enable_monitor_output](#) {false}
- uint32_t [num_codes](#) {0}
- uint32_t [code_length](#) {0}
- uint32_t [vector_length](#) {0}

12.1.1 Detailed Description

Definition at line 33 of file [acq_conf.h](#).

12.1.2 Member Data Documentation

12.1.2.1 bit_transition_flag

```
bool Acq_Conf::bit_transition_flag {false}
```

Definition at line 69 of file [acq_conf.h](#).

12.1.2.2 blocking

```
bool Acq_Conf::blocking {true}
```

Definition at line 72 of file [acq_conf.h](#).

12.1.2.3 blocking_on_standby

```
bool Acq_Conf::blocking_on_standby {false}
```

Definition at line 73 of file [acq_conf.h](#).

12.1.2.4 chips_per_second

```
uint32_t Acq_Conf::chips_per_second {1023000U}
```

Definition at line 60 of file [acq_conf.h](#).

12.1.2.5 code_length

```
uint32_t Acq_Conf::code_length {0}
```

Definition at line 80 of file [acq_conf.h](#).

12.1.2.6 doppler_max

```
int32_t Acq_Conf::doppler_max {5000}
```

Definition at line 65 of file [acq_conf.h](#).

12.1.2.7 doppler_min

```
int32_t Acq_Conf::doppler_min {-5000}
```

Definition at line 66 of file [acq_conf.h](#).

12.1.2.8 doppler_step

```
int32_t Acq_Conf::doppler_step {500}
```

Definition at line 67 of file [acq_conf.h](#).

12.1.2.9 doppler_step2

```
float Acq_Conf::doppler_step2 {125.0}
```

Definition at line 50 of file [acq_conf.h](#).

12.1.2.10 dump

```
bool Acq_Conf::dump {false}
```

Definition at line 71 of file [acq_conf.h](#).

12.1.2.11 dump_channel

```
uint32_t Acq_Conf::dump_channel {0U}
```

Definition at line 64 of file [acq_conf.h](#).

12.1.2.12 dump_filename

std::string Acq_Conf::dump_filename
Definition at line 42 of file [acq_conf.h](#).

12.1.2.13 enable_monitor_output

bool Acq_Conf::enable_monitor_output {false}
Definition at line 76 of file [acq_conf.h](#).

12.1.2.14 fs_in

int64_t Acq_Conf::fs_in {4000000LL}
Definition at line 44 of file [acq_conf.h](#).

12.1.2.15 it_size

size_t Acq_Conf::it_size {sizeof(gr_complex)}
Definition at line 47 of file [acq_conf.h](#).

12.1.2.16 item_type

std::string Acq_Conf::item_type {"gr_complex"}
Definition at line 41 of file [acq_conf.h](#).

12.1.2.17 make_2_steps

bool Acq_Conf::make_2_steps {false}
Definition at line 74 of file [acq_conf.h](#).

12.1.2.18 max_dwells

uint32_t Acq_Conf::max_dwells {1U}
Definition at line 61 of file [acq_conf.h](#).

12.1.2.19 ms_per_code

uint32_t Acq_Conf::ms_per_code {1U}
Definition at line 58 of file [acq_conf.h](#).

12.1.2.20 num_codes

uint32_t Acq_Conf::num_codes {0}
Definition at line 79 of file [acq_conf.h](#).

12.1.2.21 num_doppler_bins_step2

uint32_t Acq_Conf::num_doppler_bins_step2 {4U}
Definition at line 62 of file [acq_conf.h](#).

12.1.2.22 pfa

float Acq_Conf::pfa {0.0}
Definition at line 52 of file [acq_conf.h](#).

12.1.2.23 pfa2

float Acq_Conf::pfa2 {0.0}
Definition at line 53 of file [acq_conf.h](#).

12.1.2.24 resampled_fs

```
int64_t Acq_Conf::resampled_fs {0LL}
```

Definition at line 45 of file [acq_conf.h](#).

12.1.2.25 resampler_latency_samples

```
uint32_t Acq_Conf::resampler_latency_samples {0U}
```

Definition at line 63 of file [acq_conf.h](#).

12.1.2.26 resampler_ratio

```
float Acq_Conf::resampler_ratio {1.0}
```

Definition at line 55 of file [acq_conf.h](#).

12.1.2.27 sampled_ms

```
uint32_t Acq_Conf::sampled_ms {1U}
```

Definition at line 57 of file [acq_conf.h](#).

12.1.2.28 samples_per_chip

```
uint32_t Acq_Conf::samples_per_chip {2U}
```

Definition at line 59 of file [acq_conf.h](#).

12.1.2.29 samples_per_code

```
float Acq_Conf::samples_per_code {0.0}
```

Definition at line 54 of file [acq_conf.h](#).

12.1.2.30 samples_per_ms

```
float Acq_Conf::samples_per_ms {0.0}
```

Definition at line 49 of file [acq_conf.h](#).

12.1.2.31 threshold

```
float Acq_Conf::threshold {0.0}
```

Definition at line 51 of file [acq_conf.h](#).

12.1.2.32 use_automatic_resampler

```
bool Acq_Conf::use_automatic_resampler {false}
```

Definition at line 75 of file [acq_conf.h](#).

12.1.2.33 use_CFAR_algorithm_flag

```
bool Acq_Conf::use_CFAR_algorithm_flag {true}
```

Definition at line 70 of file [acq_conf.h](#).

12.1.2.34 vector_length

```
uint32_t Acq_Conf::vector_length {0}
```

Definition at line 81 of file [acq_conf.h](#).

The documentation for this class was generated from the following file:

- [acq_conf.h](#)

12.2 Acq_Conf_Fpga Class Reference

Public Member Functions

- void **SetFromConfiguration** (const [ConfigurationInterface](#) *configuration, const std::string &role, uint32_t blk_exp, double code_chips_per_sec, double num_chips_per_code)
- bool **ConfigureAutomaticResampler** (std::vector< std::pair< uint32_t, uint32_t > > downsampling_filter_specs, uint32_t max_FFT_size, double opt_freq)
- bool **Is_acq_config_valid** (uint32_t max_FFT_size) const

Public Attributes

- std::string [device_name](#) = "uio0"
- double [code_rate_cps](#)
- double [code_length_chips](#)
- float [doppler_step](#) {250.0}
- float [doppler_step2](#) {125.0}
- float [threshold](#) {0.0}
- int64_t [fs_in](#) {4000000LL}
- int64_t [resampled_fs](#) {4000000LL}
- uint32_t * [all_fft_codes](#) = nullptr
- uint32_t [num_doppler_bins_step2](#) {4U}
- uint32_t [downsampling_filter_num](#) {0U}
- uint32_t [downsampling_factor](#) {1U}
- uint32_t [downsampling_filter_delay](#) {0U}
- uint32_t [total_block_exp](#) {13U}
- uint32_t [excludelimit](#) {5U}
- uint32_t [max_num_acqs](#) {2U}
- uint32_t [fft_size](#) {1U}
- uint32_t [code_length](#) {16000U}
- int32_t [doppler_max](#) {5000}
- bool [make_2_steps](#) {false}
- bool [enable_zero_padding](#) {false}
- bool [repeat_satellite](#) {false}

12.2.1 Detailed Description

Definition at line 35 of file [acq_conf_fpga.h](#).

12.2.2 Member Data Documentation

12.2.2.1 all_fft_codes

```
uint32_t* Acq_Conf_Fpga::all_fft_codes = nullptr
```

Definition at line 57 of file [acq_conf_fpga.h](#).

12.2.2.2 code_length

```
uint32_t Acq_Conf_Fpga::code_length {16000U}
```

Definition at line 66 of file [acq_conf_fpga.h](#).

12.2.2.3 code_length_chips

```
double Acq_Conf_Fpga::code_length_chips
```

Definition at line 49 of file [acq_conf_fpga.h](#).

12.2.2.4 code_rate_cps

double Acq_Conf_Fpga::code_rate_cps
Definition at line 48 of file [acq_conf_fpga.h](#).

12.2.2.5 device_name

std::string Acq_Conf_Fpga::device_name = "uio0"
Definition at line 47 of file [acq_conf_fpga.h](#).

12.2.2.6 doppler_max

int32_t Acq_Conf_Fpga::doppler_max {5000}
Definition at line 67 of file [acq_conf_fpga.h](#).

12.2.2.7 doppler_step

float Acq_Conf_Fpga::doppler_step {250.0}
Definition at line 50 of file [acq_conf_fpga.h](#).

12.2.2.8 doppler_step2

float Acq_Conf_Fpga::doppler_step2 {125.0}
Definition at line 51 of file [acq_conf_fpga.h](#).

12.2.2.9 downsampling_factor

uint32_t Acq_Conf_Fpga::downsampling_factor {1U}
Definition at line 60 of file [acq_conf_fpga.h](#).

12.2.2.10 downsampling_filter_delay

uint32_t Acq_Conf_Fpga::downsampling_filter_delay {0U}
Definition at line 61 of file [acq_conf_fpga.h](#).

12.2.2.11 downsampling_filter_num

uint32_t Acq_Conf_Fpga::downsampling_filter_num {0U}
Definition at line 59 of file [acq_conf_fpga.h](#).

12.2.2.12 enable_zero_padding

bool Acq_Conf_Fpga::enable_zero_padding {false}
Definition at line 70 of file [acq_conf_fpga.h](#).

12.2.2.13 excludelimit

uint32_t Acq_Conf_Fpga::excludelimit {5U}
Definition at line 63 of file [acq_conf_fpga.h](#).

12.2.2.14 fft_size

uint32_t Acq_Conf_Fpga::fft_size {1U}
Definition at line 65 of file [acq_conf_fpga.h](#).

12.2.2.15 fs_in

int64_t Acq_Conf_Fpga::fs_in {4000000LL}
Definition at line 54 of file [acq_conf_fpga.h](#).

12.2.2.16 make_2_steps

```
bool Acq_Conf_Fpga::make_2_steps {false}
```

Definition at line 69 of file [acq_conf_fpga.h](#).

12.2.2.17 max_num_acqs

```
uint32_t Acq_Conf_Fpga::max_num_acqs {2U}
```

Definition at line 64 of file [acq_conf_fpga.h](#).

12.2.2.18 num_doppler_bins_step2

```
uint32_t Acq_Conf_Fpga::num_doppler_bins_step2 {4U}
```

Definition at line 58 of file [acq_conf_fpga.h](#).

12.2.2.19 repeat_satellite

```
bool Acq_Conf_Fpga::repeat_satellite {false}
```

Definition at line 71 of file [acq_conf_fpga.h](#).

12.2.2.20 resampled_fs

```
int64_t Acq_Conf_Fpga::resampled_fs {4000000LL}
```

Definition at line 55 of file [acq_conf_fpga.h](#).

12.2.2.21 threshold

```
float Acq_Conf_Fpga::threshold {0.0}
```

Definition at line 52 of file [acq_conf_fpga.h](#).

12.2.2.22 total_block_exp

```
uint32_t Acq_Conf_Fpga::total_block_exp {13U}
```

Definition at line 62 of file [acq_conf_fpga.h](#).

The documentation for this class was generated from the following file:

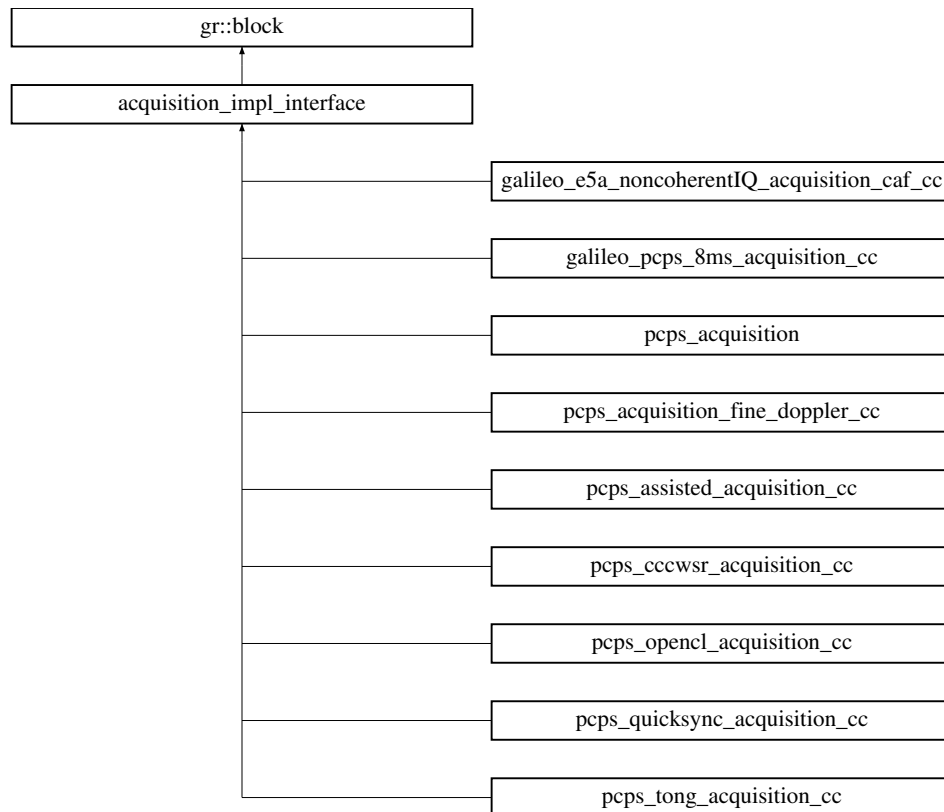
- [acq_conf_fpga.h](#)

12.3 acquisition_impl_interface Class Reference

This abstract class represents an interface to an acquisition GNSS block.

```
#include <acquisition_impl_interface.h>
```

Inheritance diagram for `acquisition_impl_interface`:



Public Member Functions

- [acquisition_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_gnss_synchro](#) (Gnss_Synchro *gnss_synchro)=0
- virtual void [set_channel](#) (uint32_t channel_id)=0
- virtual void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm)=0
- virtual void [set_local_code](#) (std::complex< float > *)
- virtual void [set_local_code](#) (std::complex< float > *, std::complex< float > *)
- virtual uint32_t [mag](#) () const =0
- virtual void [set_active](#) (bool active)=0

12.3.1 Detailed Description

This abstract class represents an interface to an acquisition GNSS block.

Abstract class for acquisition algorithms. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

Definition at line 50 of file [acquisition_impl_interface.h](#).

12.3.2 Constructor & Destructor Documentation

12.3.2.1 acquisition_impl_interface()

```

acquisition_impl_interface::acquisition_impl_interface (
    const std::string & name,
    gr::io_signature::sptr input_signature,
    gr::io_signature::sptr output_signature) [inline]

```

Definition at line 53 of file [acquisition_impl_interface.h](#).

12.3.3 Member Function Documentation

12.3.3.1 mag()

```
virtual uint32_t acquisition_impl_interface::mag () const [pure virtual]
```

Implemented in [galileo_e5a_noncoherentIQ_acquisition_caf_cc](#), [galileo_pcps_8ms_acquisition_cc](#), [pcps_acquisition](#), [pcps_acquisition_fine_doppler_cc](#), [pcps_assisted_acquisition_cc](#), [pcps_cccwsr_acquisition_cc](#), [pcps_openc1_acquisition_cc](#), [pcps_quicksync_acquisition_cc](#), and [pcps_tong_acquisition_cc](#).

12.3.3.2 set_active()

```
virtual void acquisition_impl_interface::set_active (
    bool active) [pure virtual]
```

Implemented in [galileo_e5a_noncoherentIQ_acquisition_caf_cc](#), [galileo_pcps_8ms_acquisition_cc](#), [pcps_acquisition](#), [pcps_acquisition_fine_doppler_cc](#), [pcps_assisted_acquisition_cc](#), [pcps_cccwsr_acquisition_cc](#), [pcps_openc1_acquisition_cc](#), [pcps_quicksync_acquisition_cc](#), and [pcps_tong_acquisition_cc](#).

12.3.3.3 set_channel()

```
virtual void acquisition_impl_interface::set_channel (
    uint32_t channel_id) [pure virtual]
```

Implemented in [galileo_pcps_8ms_acquisition_cc](#), [pcps_acquisition](#), [pcps_assisted_acquisition_cc](#), [pcps_cccwsr_acquisition_cc](#), [pcps_openc1_acquisition_cc](#), [pcps_quicksync_acquisition_cc](#), and [pcps_tong_acquisition_cc](#).

12.3.3.4 set_channel_fsm()

```
virtual void acquisition_impl_interface::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [pure virtual]
```

Implemented in [galileo_e5a_noncoherentIQ_acquisition_caf_cc](#), [galileo_pcps_8ms_acquisition_cc](#), [pcps_acquisition](#), [pcps_acquisition_fine_doppler_cc](#), [pcps_assisted_acquisition_cc](#), [pcps_cccwsr_acquisition_cc](#), [pcps_openc1_acquisition_cc](#), [pcps_quicksync_acquisition_cc](#), and [pcps_tong_acquisition_cc](#).

12.3.3.5 set_gnss_synchro()

```
virtual void acquisition_impl_interface::set_gnss_synchro (
    Gnss_Synchro * gnss_synchro) [pure virtual]
```

Implemented in [galileo_e5a_noncoherentIQ_acquisition_caf_cc](#), [galileo_pcps_8ms_acquisition_cc](#), [pcps_acquisition](#), [pcps_acquisition_fine_doppler_cc](#), [pcps_assisted_acquisition_cc](#), [pcps_cccwsr_acquisition_cc](#), [pcps_openc1_acquisition_cc](#), [pcps_quicksync_acquisition_cc](#), and [pcps_tong_acquisition_cc](#).

12.3.3.6 set_local_code() [1/2]

```
virtual void acquisition_impl_interface::set_local_code (
    std::complex< float > * ) [inline], [virtual]
```

Reimplemented in [galileo_pcps_8ms_acquisition_cc](#), [pcps_acquisition](#), [pcps_acquisition_fine_doppler_cc](#), [pcps_assisted_acquisition_cc](#), [pcps_openc1_acquisition_cc](#), [pcps_quicksync_acquisition_cc](#), and [pcps_tong_acquisition_cc](#).
Definition at line 60 of file [acquisition_impl_interface.h](#).

12.3.3.7 set_local_code() [2/2]

```
virtual void acquisition_impl_interface::set_local_code (
    std::complex< float > * ,
    std::complex< float > * ) [inline], [virtual]
```

Reimplemented in [galileo_e5a_noncoherentIQ_acquisition_caf_cc](#), and [pcps_cccwsr_acquisition_cc](#).
Definition at line 61 of file [acquisition_impl_interface.h](#).

The documentation for this class was generated from the following file:

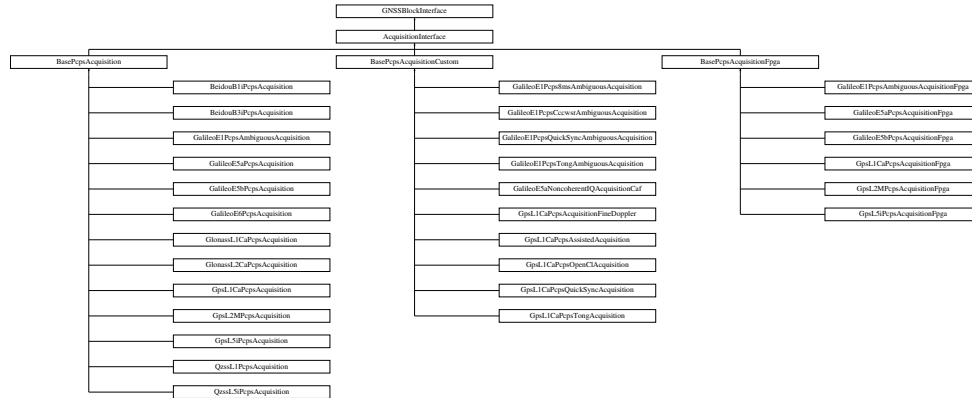
- [acquisition_impl_interface.h](#)

12.4 AcquisitionInterface Class Reference

This abstract class represents an interface to an acquisition GNSS block.

```
#include <acquisition_interface.h>
```

Inheritance diagram for AcquisitionInterface:



Public Member Functions

- virtual void [set_gnss_synchro](#) (Gnss_Synchro *gnss_synchro)=0
- virtual void [set_channel](#) (unsigned int channel_id)=0
- virtual void [set_channel_fsm](#) (std::weak_ptr< ChannelFsm > channel_fsm)=0
- virtual void [set_doppler_center](#) (int)
- virtual void [set_local_code](#) ()=0
- virtual signed int [mag](#) ()=0
- virtual void [reset](#) ()=0
- virtual void [stop_acquisition](#) ()=0
- virtual void [set_resampler_latency](#) (uint32_t latency_samples)=0

Public Member Functions inherited from GNSSBlockInterface

- virtual std::string [role](#) ()=0
- virtual std::string [implementation](#) ()=0
- virtual size_t [item_size](#) ()=0
- virtual void [connect](#) (gr::top_block_sptr top_block)=0
- virtual void [disconnect](#) (gr::top_block_sptr top_block)=0
- virtual gr::basic_block_sptr [get_left_block](#) ()=0
- virtual gr::basic_block_sptr [get_right_block](#) ()=0
- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.4.1 Detailed Description

This abstract class represents an interface to an acquisition GNSS block.

Abstract class for acquisition algorithms. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

Definition at line 50 of file [acquisition_interface.h](#).

12.4.2 Member Function Documentation

12.4.2.1 mag()

virtual signed int AcquisitionInterface::mag () [pure virtual]

Implemented in [BasePcpsAcquisition](#), and [BasePcpsAcquisitionCustom](#).

12.4.2.2 reset()

virtual void AcquisitionInterface::reset () [pure virtual]

Implemented in [BasePcpsAcquisition](#), and [BasePcpsAcquisitionCustom](#).

12.4.2.3 set_channel()

virtual void AcquisitionInterface::set_channel (
 unsigned int *channel_id*) [pure virtual]

Implemented in [BasePcpsAcquisition](#), and [BasePcpsAcquisitionCustom](#).

12.4.2.4 set_channel_fsm()

virtual void AcquisitionInterface::set_channel_fsm (
 std::weak_ptr< [ChannelFsm](#) > *channel_fsm*) [pure virtual]

Implemented in [BasePcpsAcquisition](#), and [BasePcpsAcquisitionCustom](#).

12.4.2.5 set_doppler_center()

virtual void AcquisitionInterface::set_doppler_center (
 int) [inline], [virtual]

Reimplemented in [BasePcpsAcquisition](#).

Definition at line 56 of file [acquisition_interface.h](#).

12.4.2.6 set_gnss_synchro()

virtual void AcquisitionInterface::set_gnss_synchro (
 [Gnss_Synchro](#) * *gnss_synchro*) [pure virtual]

Implemented in [BasePcpsAcquisition](#), [BasePcpsAcquisitionCustom](#), and [GalileoE1PcpsAmbiguousAcquisition](#).

12.4.2.7 set_local_code()

virtual void AcquisitionInterface::set_local_code () [pure virtual]

Implemented in [BasePcpsAcquisition](#), [BasePcpsAcquisitionCustom](#), [GalileoE1PcpsCccwsrAmbiguousAcquisition](#), and [GalileoE5aNoncoherentIQAcquisitionCaf](#).

12.4.2.8 set_resampler_latency()

virtual void AcquisitionInterface::set_resampler_latency (
 uint32_t *latency_samples*) [pure virtual]

Implemented in [BasePcpsAcquisition](#).

12.4.2.9 stop_acquisition()

virtual void AcquisitionInterface::stop_acquisition () [pure virtual]

Implemented in [BasePcpsAcquisition](#), and [BasePcpsAcquisitionCustom](#).

The documentation for this class was generated from the following file:

- [acquisition_interface.h](#)

12.5 ad936x_iio_custom Class Reference

Public Member Functions

- **ad936x_iio_custom** (int debug_level_, int log_level_)
- bool **initialize_device** (const std::string &pluto_device_uri, const std::string &board_type)
- bool **init_config_ad9361_rx** (long long bandwidth_, long long sample_rate_, long long freq_, const std::string &rf_port_select_, const std::string &rf_filter, const std::string &gain_mode_rx0_, const std::string &gain_mode_rx1_, double rf_gain_rx0_, double rf_gain_rx1_, bool enable_ch0, bool enable_ch1, long long freq_2ch, double lo_attenuation_db_, bool high_side_lo_, int tx_lo_channel_)
- bool **calibrate** (int ch, double bw_hz)
- double **get_rx_gain** (int ch_num)
- bool **setRXGain** (int ch_num, const std::string &gain_mode, double gain_dB)
- bool **set_antenna_port** (int ch, int antenna_idx)
- double **get_frequency** (int ch)
- bool **set_frequency** (int ch, double freq_hz)
- bool **start_sample_rx** (bool ppsmode)
- void **stop_record** ()
- void **set_gnss_time_queue** (std::shared_ptr< [Concurrent_Queue](#)< [GnssTime](#) > > queue)
- void **set_pps_samplestamp_queue** (std::shared_ptr< [Concurrent_Queue](#)< [PpsSamplestamp](#) > > queue)
- bool **get_rx_frequency** (long long &freq_hz)
- bool **set_rx_frequency** (long long freq_hz)
- bool **read_die_temp** (double &temp_c)
- void **pop_sample_buffer** (std::shared_ptr< [ad936x_iio_samples](#) > ¤t_buffer)
- void **push_sample_buffer** (std::shared_ptr< [ad936x_iio_samples](#) > ¤t_buffer)

Public Attributes

- int [n_channels](#)

12.5.1 Detailed Description

Definition at line 39 of file [ad936x_iio_custom.h](#).

12.5.2 Member Data Documentation

12.5.2.1 n_channels

```
int ad936x_iio_custom::n_channels
```

Definition at line 84 of file [ad936x_iio_custom.h](#).

The documentation for this class was generated from the following file:

- [ad936x_iio_custom.h](#)

12.6 ad936x_iio_samples Class Reference

Public Attributes

- uint32_t [n_bytes](#) {0}
- uint32_t [n_interleaved_iq_samples](#) {0}
- uint16_t [n_channels](#) {0}
- uint16_t [step_bytes](#) {0}
- char [buffer](#) [IIO_DEFAULTAD936XAPIFIFOSIZE_SAMPLES *4 *4]

12.6.1 Detailed Description

Definition at line 33 of file [ad936x_iio_samples.h](#).

12.6.2 Member Data Documentation

12.6.2.1 buffer

char ad936x_iio_samples::buffer[IIO_DEFAULTAD936XAPIFIFO_SIZE_SAMPLES *4 *4]

Definition at line 41 of file [ad936x_iio_samples.h](#).

12.6.2.2 n_bytes

uint32_t ad936x_iio_samples::n_bytes {0}

Definition at line 37 of file [ad936x_iio_samples.h](#).

12.6.2.3 n_channels

uint16_t ad936x_iio_samples::n_channels {0}

Definition at line 39 of file [ad936x_iio_samples.h](#).

12.6.2.4 n_interleaved_iq_samples

uint32_t ad936x_iio_samples::n_interleaved_iq_samples {0}

Definition at line 38 of file [ad936x_iio_samples.h](#).

12.6.2.5 step_bytes

uint16_t ad936x_iio_samples::step_bytes {0}

Definition at line 40 of file [ad936x_iio_samples.h](#).

The documentation for this class was generated from the following file:

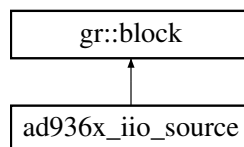
- [ad936x_iio_samples.h](#)

12.7 ad936x_iio_source Class Reference

This class implements conversion between Labsat 2, 3 and 3 Wideband formats to gr_complex.

```
#include <ad936x_iio_source.h>
```

Inheritance diagram for ad936x_iio_source:



Public Member Functions

- bool [start](#) ()
start the sample transmission
- bool [stop](#) ()
stop the sample transmission
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- ad936x_iio_source_sptr **ad936x_iio_make_source_sptr** (const std::string &pluto_uri_, const std::string &board_type_, int64_t bandwidth_, int64_t sample_rate_, int64_t freq_, const std::string &rf_port_select_, const std::string &rf_filter, const std::string &gain_mode_rx0_, const std::string &gain_mode_rx1_, double rf_gain_rx0_, double rf_gain_rx1_, bool enable_ch0, bool enable_ch1, int64_t freq_2ch, bool ppsmode_, bool customsamplesize_, const std::string &fe_ip_, int fe_ctlport_, int ssize_, int bshift_, bool spattern_, double lo_attenuation_db_, bool high_side_lo_, int tx_lo_channel_)

12.7.1 Detailed Description

This class implements conversion between Labsat 2, 3 and 3 Wideband formats to `gr_complex`.
Definition at line 77 of file [ad936x_iio_source.h](#).

12.7.2 Member Function Documentation

12.7.2.1 start()

```
bool ad936x_iio_source::start ()
start the sample transmission
```

12.7.2.2 stop()

```
bool ad936x_iio_source::stop ()
stop the sample transmission
```

The documentation for this class was generated from the following file:

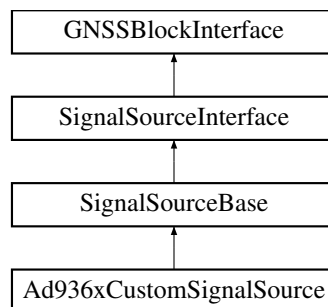
- [ad936x_iio_source.h](#)

12.8 Ad936xCustomSignalSource Class Reference

This class instantiates the Ad936xCustom gnuradio signal source. It has support also for a customized Ad936x↔ Custom firmware and signal source to support PPS samplestamp reading.

```
#include <ad936x_custom_signal_source.h>
```

Inheritance diagram for Ad936xCustomSignalSource:



Public Member Functions

- **Ad936xCustomSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- `size_t item_size ()` override
- void `connect` (gr::top_block_sptr top_block) override
- void `disconnect` (gr::top_block_sptr top_block) override
- gr::basic_block_sptr `get_left_block ()` override
- gr::basic_block_sptr `get_right_block ()` override
- gr::basic_block_sptr `get_right_block` (int RF_channel) override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string `role ()` final
- std::string `implementation ()` final
- `size_t getRfChannels ()` const override
- gr::basic_block_sptr `get_left_block ()` override

Public Member Functions inherited from GNSSBlockInterface

- virtual `gr::basic_block_sptr` [get_left_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from SignalSourceBase

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- `size_t` [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↵
error=false)

utility for decoding passed ".item_type" values

12.8.1 Detailed Description

This class instantiates the Ad936xCustom gnuradio signal source. It has support also for a customized Ad936x↵ Custom firmware and signal source to support PPS samplestamp reading.

Definition at line 51 of file [ad936x_custom_signal_source.h](#).

12.8.2 Member Function Documentation

12.8.2.1 connect()

```
void Ad936xCustomSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.8.2.2 disconnect()

```
void Ad936xCustomSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.8.2.3 get_left_block()

```
gr::basic_block_sptr Ad936xCustomSignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.8.2.4 get_right_block() [1/2]

```
gr::basic_block_sptr Ad936xCustomSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.8.2.5 get_right_block() [2/2]

```
gr::basic_block_sptr Ad936xCustomSignalSource::get_right_block (
    int RF_channel) [override], [virtual]
```

Reimplemented from [GNSSBlockInterface](#).

12.8.2.6 item_size()

```
size_t Ad936xCustomSignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

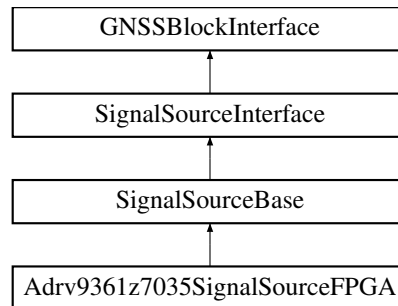
Definition at line 60 of file [ad936x_custom_signal_source.h](#).

The documentation for this class was generated from the following file:

- [ad936x_custom_signal_source.h](#)

12.9 Adrv9361z7035SignalSourceFPGA Class Reference

Inheritance diagram for Adrv9361z7035SignalSourceFPGA:



Public Member Functions

- **Adrv9361z7035SignalSourceFPGA** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_error=false)
utility for decoding passed ".item_type" values

12.9.1 Detailed Description

Definition at line 46 of file [adv9361_z7035_signal_source_fpga.h](#).

12.9.2 Member Function Documentation

12.9.2.1 connect()

```
void Adrv9361z7035SignalSourceFPGA::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.9.2.2 disconnect()

```
void Adrv9361z7035SignalSourceFPGA::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.9.2.3 get_left_block()

```
gr::basic_block_sptr Adrv9361z7035SignalSourceFPGA::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.9.2.4 get_right_block()

```
gr::basic_block_sptr Adrv9361z7035SignalSourceFPGA::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.9.2.5 item_size()

```
size_t Adrv9361z7035SignalSourceFPGA::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 55 of file [adv9361_z7035_signal_source_fpga.h](#).

The documentation for this class was generated from the following file:

- [adv9361_z7035_signal_source_fpga.h](#)

12.10 Agnss_Ref_Location Class Reference

Interface of an Assisted GNSS REFERENCE LOCATION storage.

```
#include <agnss_ref_location.h>
```

Public Member Functions

- [Agnss_Ref_Location](#) ()=default
- `template<class Archive>`
void [serialize](#) (Archive &archive, const unsigned int version)

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the Ref location on disk file.

Public Attributes

- double [lat](#) {}
- double [lon](#) {}
- double [uncertainty](#) {}
- bool [valid](#) {}

12.10.1 Detailed Description

Interface of an Assisted GNSS REFERENCE LOCATION storage.

Definition at line 33 of file [agnss_ref_location.h](#).

12.10.2 Constructor & Destructor Documentation

12.10.2.1 Agnss_Ref_Location()

```
Agnss_Ref_Location::Agnss_Ref_Location () [default]
```

Default constructor

12.10.3 Member Function Documentation

12.10.3.1 serialize()

```
template<class Archive>
void Agnss_Ref_Location::serialize (
    Archive & archive,
    const unsigned int version) [inline]
```

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the Ref location on disk file.

Definition at line 52 of file [agnss_ref_location.h](#).

12.10.4 Member Data Documentation

12.10.4.1 lat

```
double Agnss_Ref_Location::lat {}
```

Definition at line 41 of file [agnss_ref_location.h](#).

12.10.4.2 lon

```
double Agnss_Ref_Location::lon {}
```

Definition at line 42 of file [agnss_ref_location.h](#).

12.10.4.3 uncertainty

```
double Agnss_Ref_Location::uncertainty {}
```

Definition at line 43 of file [agnss_ref_location.h](#).

12.10.4.4 valid

```
bool Agnss_Ref_Location::valid {}
```

Definition at line 44 of file [agnss_ref_location.h](#).

The documentation for this class was generated from the following file:

- [agnss_ref_location.h](#)

12.11 Agnss_Ref_Time Class Reference

Interface of an Assisted GNSS REFERENCE TIME storage.

```
#include <agnss_ref_time.h>
```

Public Member Functions

- [Agnss_Ref_Time](#) ()=default
- template<class Archive>
void [serialize](#) (Archive &archive, const unsigned int version)

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ref time data on disk file.

Public Attributes

- double [tow](#) {}
- double [week](#) {}
- double [seconds](#) {}
- double [microseconds](#) {}
- bool [valid](#) {}

12.11.1 Detailed Description

Interface of an Assisted GNSS REFERENCE TIME storage.
Definition at line 33 of file [agnss_ref_time.h](#).

12.11.2 Constructor & Destructor Documentation

12.11.2.1 Agnss_Ref_Time()

`Agnss_Ref_Time::Agnss_Ref_Time () [default]`
Default constructor

12.11.3 Member Function Documentation

12.11.3.1 serialize()

```
template<class Archive>
void Agnss_Ref_Time::serialize (
    Archive & archive,
    const unsigned int version) [inline]
```

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ref time data on disk file.

Definition at line 53 of file [agnss_ref_time.h](#).

12.11.4 Member Data Documentation

12.11.4.1 microseconds

```
double Agnss_Ref_Time::microseconds {}
```

Definition at line 44 of file [agnss_ref_time.h](#).

12.11.4.2 seconds

```
double Agnss_Ref_Time::seconds {}
```

Definition at line 43 of file [agnss_ref_time.h](#).

12.11.4.3 tow

```
double Agnss_Ref_Time::tow {}
```

Definition at line 41 of file [agnss_ref_time.h](#).

12.11.4.4 valid

```
bool Agnss_Ref_Time::valid {}
```

Definition at line 45 of file [agnss_ref_time.h](#).

12.11.4.5 week

```
double Agnss_Ref_Time::week {}
```

Definition at line 42 of file [agnss_ref_time.h](#).

The documentation for this class was generated from the following file:

- [agnss_ref_time.h](#)

12.12 Allocator Struct Reference

Public Member Functions

- [Allocator](#) (size_t countwords, void *&buffer)
- `template<typename WordType>`
`void operator() () const`

Public Attributes

- size_t [countwords_](#)
- void *& [buffer_](#)

12.12.1 Detailed Description

Definition at line 57 of file [ion_gsms_chunk_data.h](#).

12.12.2 Constructor & Destructor Documentation

12.12.2.1 Allocator()

```
Allocator::Allocator (  
    size_t countwords,  
    void *& buffer) [inline]
```

Definition at line 62 of file [ion_gsms_chunk_data.h](#).

12.12.3 Member Function Documentation

12.12.3.1 operator>()

```
template<typename WordType>  
void Allocator::operator() () const [inline]
```

Definition at line 66 of file [ion_gsms_chunk_data.h](#).

12.12.4 Member Data Documentation

12.12.4.1 buffer_

```
void*& Allocator::buffer_
```

Definition at line 60 of file [ion_gsms_chunk_data.h](#).

12.12.4.2 countwords_

```
size_t Allocator::countwords_
```

Definition at line 59 of file [ion_gsms_chunk_data.h](#).

The documentation for this struct was generated from the following file:

- [ion_gsms_chunk_data.h](#)

12.13 alm_t Struct Reference

Public Attributes

- int [sat](#)
- int [svh](#)
- int [svconf](#)
- int [week](#)
- [gtime_t](#) [toa](#)
- double [A](#)
- double [e](#)

- double [i0](#)
- double [OMG0](#)
- double [omg](#)
- double [M0](#)
- double [OMGd](#)
- double [toas](#)
- double [f0](#)
- double [f1](#)

12.13.1 Detailed Description

Definition at line [419](#) of file [rtklib.h](#).

12.13.2 Member Data Documentation

12.13.2.1 A

double alm_t::A

Definition at line [427](#) of file [rtklib.h](#).

12.13.2.2 e

double alm_t::e

Definition at line [427](#) of file [rtklib.h](#).

12.13.2.3 f0

double alm_t::f0

Definition at line [429](#) of file [rtklib.h](#).

12.13.2.4 f1

double alm_t::f1

Definition at line [429](#) of file [rtklib.h](#).

12.13.2.5 i0

double alm_t::i0

Definition at line [427](#) of file [rtklib.h](#).

12.13.2.6 M0

double alm_t::M0

Definition at line [427](#) of file [rtklib.h](#).

12.13.2.7 omg

double alm_t::omg

Definition at line [427](#) of file [rtklib.h](#).

12.13.2.8 OMG0

double alm_t::OMG0

Definition at line [427](#) of file [rtklib.h](#).

12.13.2.9 OMGd

double alm_t::OMGd

Definition at line [427](#) of file [rtklib.h](#).

12.13.2.10 sat

```
int alm_t::sat
```

Definition at line 421 of file [rtklib.h](#).

12.13.2.11 svconf

```
int alm_t::svconf
```

Definition at line 423 of file [rtklib.h](#).

12.13.2.12 svh

```
int alm_t::svh
```

Definition at line 422 of file [rtklib.h](#).

12.13.2.13 toa

```
gtime_t alm_t::toa
```

Definition at line 425 of file [rtklib.h](#).

12.13.2.14 toas

```
double alm_t::toas
```

Definition at line 428 of file [rtklib.h](#).

12.13.2.15 week

```
int alm_t::week
```

Definition at line 424 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.14 ambc_t Struct Reference

Public Attributes

- [gtime_t](#) epoch [4]
- int n [4]
- double LC [4]
- double LCv [4]
- int fixcnt
- char flags [MAXSAT]

12.14.1 Detailed Description

Definition at line 1056 of file [rtklib.h](#).

12.14.2 Member Data Documentation

12.14.2.1 epoch

```
gtime_t ambc_t::epoch[4]
```

Definition at line 1058 of file [rtklib.h](#).

12.14.2.2 fixcnt

```
int ambc_t::fixcnt
```

Definition at line 1062 of file [rtklib.h](#).

12.14.2.3 flags

```
char ambc_t::flags[MAXSAT]
```

Definition at line 1063 of file [rtklib.h](#).

12.14.2.4 LC

```
double ambc_t::LC[4]
```

Definition at line 1060 of file [rtklib.h](#).

12.14.2.5 LCv

```
double ambc_t::LCv[4]
```

Definition at line 1061 of file [rtklib.h](#).

12.14.2.6 n

```
int ambc_t::n[4]
```

Definition at line 1059 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.15 An_Packet_Printer Class Reference

class that prints PVT solutions in a serial device following a custom version of the Advanced Navigation Packet Protocol.

```
#include <an_packet_printer.h>
```

Public Member Functions

- [An_Packet_Printer](#) (const std::string &an_dump_devname)
Default constructor.
- [~An_Packet_Printer](#) ()
Default destructor.
- bool [print_packet](#) (const [Rtklib_Solver](#) *const pvt_data, const std::map< int, [Gnss_Synchro](#) > &gnss_↔
observables_map)
Print AN packet to the initialized device.
- void [close_serial](#) () const
Close serial port. Also done in the destructor, this is only for testing.

12.15.1 Detailed Description

class that prints PVT solutions in a serial device following a custom version of the Advanced Navigation Packet Protocol.

Definition at line 73 of file [an_packet_printer.h](#).

12.15.2 Constructor & Destructor Documentation

12.15.2.1 An_Packet_Printer()

```
An_Packet_Printer::An_Packet_Printer (
    const std::string & an_dump_devname) [explicit]
```

Default constructor.

12.15.2.2 ~An_Packet_Printer()

```
An_Packet_Printer::~An_Packet_Printer ()
```

Default destructor.

12.15.3 Member Function Documentation

12.15.3.1 close_serial()

```
void An_Packet_Printer::close_serial () const
```

Close serial port. Also done in the destructor, this is only for testing.

12.15.3.2 print_packet()

```
bool An_Packet_Printer::print_packet (
    const Rtklib_Solver *const pvt_data,
    const std::map< int, Gnss_Synchro > & gnss_observables_map)
```

Print AN packet to the initialized device.

The documentation for this class was generated from the following file:

- [an_packet_printer.h](#)

12.16 an_packet_t Struct Reference

Public Attributes

- `uint8_t header` [4]
- `uint8_t data` [113]

12.16.1 Detailed Description

Definition at line 62 of file [an_packet_printer.h](#).

12.16.2 Member Data Documentation

12.16.2.1 data

```
uint8_t an_packet_t::data[113]
```

Definition at line 65 of file [an_packet_printer.h](#).

12.16.2.2 header

```
uint8_t an_packet_t::header[4]
```

Definition at line 64 of file [an_packet_printer.h](#).

The documentation for this struct was generated from the following file:

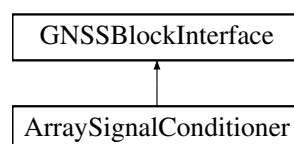
- [an_packet_printer.h](#)

12.17 ArraySignalConditioner Class Reference

This class wraps blocks to change `data_type_adapter`, `input_filter` and `resampler` to be applied to the input flow of sampled signal.

```
#include <array_signal_conditioner.h>
```

Inheritance diagram for ArraySignalConditioner:



Public Member Functions

- [ArraySignalConditioner](#) (std::shared_ptr< [GNSSBlockInterface](#) > data_type_adapt, std::shared_ptr< [GNSSBlockInterface](#) > in_filt, std::shared_ptr< [GNSSBlockInterface](#) > res, std::string role)

Constructor.

- [~ArraySignalConditioner](#) ()=default

Destructor.

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- std::string [role](#) () override
- std::string [implementation](#) () override

Returns "Array_Signal_Conditioner".

- size_t [item_size](#) () override
- std::shared_ptr< [GNSSBlockInterface](#) > [data_type_adapter](#) ()
- std::shared_ptr< [GNSSBlockInterface](#) > [input_filter](#) ()
- std::shared_ptr< [GNSSBlockInterface](#) > [resampler](#) ()

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.17.1 Detailed Description

This class wraps blocks to change data_type_adapter, input_filter and resampler to be applied to the input flow of sampled signal.

Definition at line 41 of file [array_signal_conditioner.h](#).

12.17.2 Constructor & Destructor Documentation**12.17.2.1 ArraySignalConditioner()**

```
ArraySignalConditioner::ArraySignalConditioner (
    std::shared_ptr< GNSSBlockInterface > data_type_adapt,
    std::shared_ptr< GNSSBlockInterface > in_filt,
    std::shared_ptr< GNSSBlockInterface > res,
    std::string role)
```

Constructor.

12.17.2.2 ~ArraySignalConditioner()

```
ArraySignalConditioner::~ArraySignalConditioner () [default]
```

Destructor.

12.17.3 Member Function Documentation**12.17.3.1 connect()**

```
void ArraySignalConditioner::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.17.3.2 data_type_adapter()

`std::shared_ptr< GNSSBlockInterface > ArraySignalConditioner::data_type_adapter () [inline]`
 Definition at line 63 of file [array_signal_conditioner.h](#).

12.17.3.3 disconnect()

`void ArraySignalConditioner::disconnect (gr::top_block_sptr top_block) [override], [virtual]`
 Implements [GNSSBlockInterface](#).

12.17.3.4 get_left_block()

`gr::basic_block_sptr ArraySignalConditioner::get_left_block () [override], [virtual]`
 Implements [GNSSBlockInterface](#).

12.17.3.5 get_right_block()

`gr::basic_block_sptr ArraySignalConditioner::get_right_block () [override], [virtual]`
 Implements [GNSSBlockInterface](#).

12.17.3.6 implementation()

`std::string ArraySignalConditioner::implementation () [inline], [override], [virtual]`
 Returns "Array_Signal_Conditioner".
 Implements [GNSSBlockInterface](#).
 Definition at line 60 of file [array_signal_conditioner.h](#).

12.17.3.7 input_filter()

`std::shared_ptr< GNSSBlockInterface > ArraySignalConditioner::input_filter () [inline]`
 Definition at line 64 of file [array_signal_conditioner.h](#).

12.17.3.8 item_size()

`size_t ArraySignalConditioner::item_size () [inline], [override], [virtual]`
 Implements [GNSSBlockInterface](#).
 Definition at line 61 of file [array_signal_conditioner.h](#).

12.17.3.9 resampler()

`std::shared_ptr< GNSSBlockInterface > ArraySignalConditioner::resampler () [inline]`
 Definition at line 65 of file [array_signal_conditioner.h](#).

12.17.3.10 role()

`std::string ArraySignalConditioner::role () [inline], [override], [virtual]`
 Implements [GNSSBlockInterface](#).
 Definition at line 58 of file [array_signal_conditioner.h](#).
 The documentation for this class was generated from the following file:

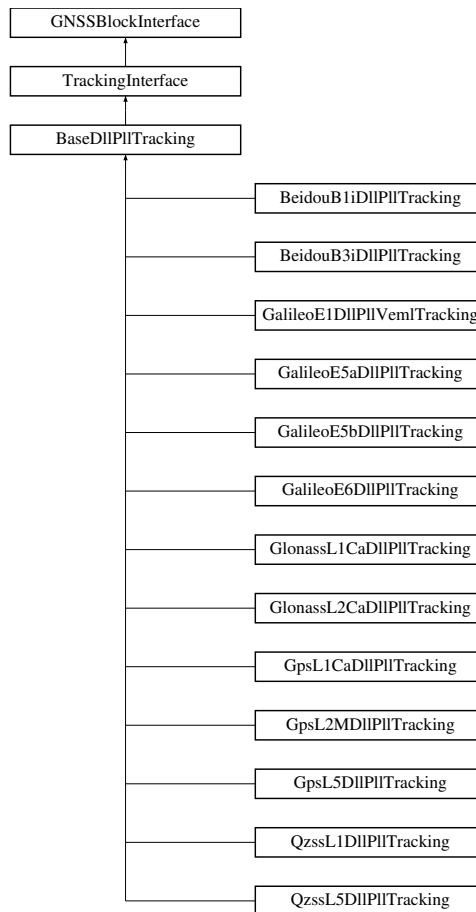
- [array_signal_conditioner.h](#)

12.18 BaseDIIPIITracking Class Reference

Base class providing shared logic for DLL+PLL tracking loop adapters for GNSS signals.

`#include <base_dll_pll_tracking.h>`

Inheritance diagram for BaseDIIPIITracking:



Public Member Functions

- [BaseDIIPIITracking](#) (const [ConfigurationInterface](#) *configuration, std::string [role](#), unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDIIPIITracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override final
Get left block from the Tracking block adapter.
- gr::basic_block_sptr [get_right_block](#) () override final
Get right block from the Tracking block adapter.
- void [set_channel](#) (unsigned int channel) override final
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final

Start the Tracking block.

- void [stop_tracking](#) () override final

Stop the Tracking block.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual std::string [implementation](#) ()=0
- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Protected Member Functions

- [Dll_Pll_Conf](#) & [config_params](#) ()
- const [Dll_Pll_Conf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t item_size)
- virtual void [configure_tracking_parameters](#) (const [ConfigurationInterface](#) *configuration)=0
- virtual void [create_tracking_block](#) ()=0

Protected Attributes

- dll_pll_veml_tracking_sptr [tracking_sptr_](#)

12.18.1 Detailed Description

Base class providing shared logic for DLL+PLL tracking loop adapters for GNSS signals.
Definition at line 39 of file [base_dll_pll_tracking.h](#).

12.18.2 Constructor & Destructor Documentation

12.18.2.1 BaseDllPllTracking()

```
BaseDllPllTracking::BaseDllPllTracking (
    const ConfigurationInterface * configuration,
    std::string role,
    unsigned int in_streams,
    unsigned int out_streams) [explicit]
```

Base constructor of a Tracking block adapter.

References [role\(\)](#).

12.18.2.2 ~BaseDllPllTracking()

```
BaseDllPllTracking::~BaseDllPllTracking () [override], [default]
```

Default destructor of the Tracking block adapter.

12.18.3 Member Function Documentation

12.18.3.1 config_params() [1/2]

```
Dll\_Pll\_Conf & BaseDllPllTracking::config_params () [inline], [protected]
```

Definition at line 108 of file [base_dll_pll_tracking.h](#).

12.18.3.2 config_params() [2/2]

```
const Dll\_Pll\_Conf & BaseDllPllTracking::config_params () const [inline], [protected]
```

Definition at line 109 of file [base_dll_pll_tracking.h](#).

12.18.3.3 connect()

```
void BaseDllPllTracking::connect (
    gr::top_block_sptr top_block) [final], [override], [virtual]
```

Connect the Tracking block adapter.

Implements [GNSSBlockInterface](#).

12.18.3.4 disconnect()

```
void BaseDllPllTracking::disconnect (
    gr::top_block_sptr top_block) [final], [override], [virtual]
```

Disconnect the sTracking block adapter.

Implements [GNSSBlockInterface](#).

12.18.3.5 get_left_block()

```
gr::basic_block_sptr BaseDllPllTracking::get_left_block () [final], [override], [virtual]
```

Get left block from the Tracking block adapter.

Implements [GNSSBlockInterface](#).

12.18.3.6 get_right_block()

```
gr::basic_block_sptr BaseDllPllTracking::get_right_block () [final], [override], [virtual]
```

Get right block from the Tracking block adapter.

Implements [GNSSBlockInterface](#).

References [get_right_block\(\)](#).

Referenced by [get_right_block\(\)](#).

12.18.3.7 item_size()

```
size_t BaseDllPllTracking::item_size () [inline], [final], [override], [virtual]
```

Get item_size from the Tracking block adapter.

Implements [GNSSBlockInterface](#).

Definition at line 63 of file [base_dll_pll_tracking.h](#).

12.18.3.8 role()

```
std::string BaseDllPllTracking::role () [inline], [final], [override], [virtual]
```

Get role from the Tracking block adapter.

Implements [GNSSBlockInterface](#).

Definition at line 58 of file [base_dll_pll_tracking.h](#).

Referenced by [BaseDllPllTracking\(\)](#), [BeidouB1iDllPllTracking::BeidouB1iDllPllTracking\(\)](#), [BeidouB3iDllPllTracking::BeidouB3iDllPllTracking\(\)](#), [GalileoE1iDllPllTracking::GalileoE1iDllPllTracking\(\)](#), [GalileoE5aDllPllTracking::GalileoE5aDllPllTracking\(\)](#), [GalileoE5bDllPllTracking::GalileoE5bDllPllTracking\(\)](#), [GalileoE6DllPllTracking::GalileoE6DllPllTracking\(\)](#), [GlonassL1CaDllPllTracking::GlonassL1CaDllPllTracking\(\)](#), [GlonassL2CaDllPllTracking::GlonassL2CaDllPllTracking\(\)](#), [GpsL1CaDllPllTracking::GpsL1CaDllPllTracking\(\)](#), [GpsL2MDiDllPllTracking::GpsL2MDiDllPllTracking\(\)](#), [GpsL5DllPllTracking::GpsL5DllPllTracking\(\)](#), [QzssL1DiDllPllTracking::QzssL1DiDllPllTracking\(\)](#) and [QzssL5DiDllPllTracking::QzssL5DiDllPllTracking\(\)](#).

12.18.3.9 set_channel()

```
void BaseDllPllTracking::set_channel (
    unsigned int channel) [final], [override], [virtual]
```

Set tracking channel unique ID.

Implements [TrackingInterface](#).

References [set_channel\(\)](#).

Referenced by [set_channel\(\)](#).

12.18.3.10 set_gnss_synchro()

```
void BaseDllPllTracking::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [final], [override], [virtual]
```

Set acquisition [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.

Implements [TrackingInterface](#).

References [set_gnss_synchro\(\)](#).

Referenced by [set_gnss_synchro\(\)](#).

12.18.3.11 set_item_size()

```
void BaseDllPllTracking::set_item_size (
    size_t item_size) [inline], [protected]
```

Definition at line 110 of file [base_dll_pll_tracking.h](#).

12.18.3.12 start_tracking()

```
void BaseDllPllTracking::start_tracking () [final], [override], [virtual]
```

Start the Tracking block.

Implements [TrackingInterface](#).

References [start_tracking\(\)](#).

Referenced by [start_tracking\(\)](#).

12.18.3.13 stop_tracking()

```
void BaseDllPllTracking::stop_tracking () [final], [override], [virtual]
```

Stop the Tracking block.

Implements [TrackingInterface](#).

References [stop_tracking\(\)](#).

Referenced by [stop_tracking\(\)](#).

12.18.4 Member Data Documentation

12.18.4.1 tracking_sptr_

```
dll_pll_veml_tracking_sptr BaseDllPllTracking::tracking_sptr_ [protected]
```

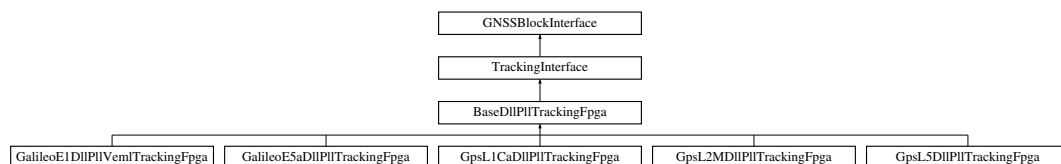
Definition at line 115 of file [base_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

- [base_dll_pll_tracking.h](#)

12.19 BaseDIIPllTrackingFpga Class Reference

Inheritance diagram for BaseDIIPllTrackingFpga:



Public Member Functions

- [BaseDIIPllTrackingFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Base constructor of FPGA-based Tracking block adapters.
- virtual [~BaseDIIPllTrackingFpga](#) ()=default

Base destructor of FPGA-based Tracking block adapters.

- `std::string role ()` override
Get role from the Tracking block adapter.
- `size_t item_size ()` override
Get item_size from the Tracking block adapter.
- `void connect (gr::top_block_sptr top_block)` override
Connect the Tracking block adapter.
- `void disconnect (gr::top_block_sptr top_block)` override
Disconnect the Tracking block adapter.
- `gr::basic_block_sptr get_left_block ()` override
Get left block from the Tracking block adapter.
- `gr::basic_block_sptr get_right_block ()` override
Get right block from the Tracking block adapter.
- `void start_tracking ()` override
Start the tracking process in the FPGA.
- `void stop_tracking ()` override
Stop the tracking process in the FPGA.
- `void configure_fpga_tracking_channel_mapping (std::string signal)`
configure FPGA tracking channel mapping
- `void set_channel (unsigned int channel)` override
Set tracking channel unique ID.
- `void set_gnss_synchro (Gnss_Synchro *p_gnss_synchro)` override
Set acquisition/tracking common Gnss_Synchro object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

Public Member Functions inherited from GNSSBlockInterface

- `virtual std::string implementation ()=0`
- `virtual gr::basic_block_sptr get_left_block (int RF_channel)`
- `virtual gr::basic_block_sptr get_right_block (int RF_channel)`
- `virtual void start ()`
Start the flow of samples if needed.

Protected Member Functions

- `DII_PII_Conf_Fpga & config_params_fpga ()`
- `const DII_PII_Conf_Fpga & config_params_fpga () const`

Protected Attributes

- `dll_pll_veml_tracking_fpga_sptr tracking_fpga_sc_sptr_`

Static Protected Attributes

- `static const int32_t LOCAL_CODE_FPGA_ENABLE_WRITE_MEMORY = 0x0C000000`
- `static const int32_t LOCAL_CODE_FPGA_CORRELATOR_SELECT_COUNT = 0x20000000`

12.19.1 Detailed Description

Definition at line 37 of file `base_dll_pll_tracking_fpga.h`.

12.19.2 Constructor & Destructor Documentation

12.19.2.1 BaseDllPllTrackingFpga()

```
BaseDllPllTrackingFpga::BaseDllPllTrackingFpga (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Base constructor of FPGA-based Tracking block adapters.

References [role\(\)](#).

12.19.2.2 ~BaseDllPllTrackingFpga()

```
virtual BaseDllPllTrackingFpga::~~BaseDllPllTrackingFpga () [virtual], [default]
```

Base destructor of FPGA-based Tracking block adapters.

12.19.3 Member Function Documentation

12.19.3.1 config_params_fpga() [1/2]

```
Dll\_Pll\_Conf\_Fpga & BaseDllPllTrackingFpga::config_params_fpga () [inline], [protected]
```

Definition at line 115 of file [base_dll_pll_tracking_fpga.h](#).

12.19.3.2 config_params_fpga() [2/2]

```
const Dll\_Pll\_Conf\_Fpga & BaseDllPllTrackingFpga::config_params_fpga () const [inline], [protected]
```

Definition at line 116 of file [base_dll_pll_tracking_fpga.h](#).

12.19.3.3 configure_fpga_tracking_channel_mapping()

```
void BaseDllPllTrackingFpga::configure_fpga_tracking_channel_mapping (
    std::string signal)
```

configure FPGA tracking channel mapping

12.19.3.4 connect()

```
void BaseDllPllTrackingFpga::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Connect the Tracking block adapter.

Implements [GNSSBlockInterface](#).

12.19.3.5 disconnect()

```
void BaseDllPllTrackingFpga::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Disconnect the Tracking block adapter.

Implements [GNSSBlockInterface](#).

12.19.3.6 get_left_block()

```
gr::basic_block_sptr BaseDllPllTrackingFpga::get_left_block () [override], [virtual]
```

Get left block from the Tracking block adapter.

Implements [GNSSBlockInterface](#).

12.19.3.7 get_right_block()

```
gr::basic_block_sptr BaseDllPllTrackingFpga::get_right_block () [override], [virtual]
```

Get right block from the Tracking block adapter.

Implements [GNSSBlockInterface](#).

12.19.3.8 item_size()

```
size_t BaseDllPllTrackingFpga::item_size () [inline], [override], [virtual]
```

Get item_size from the Tracking block adapter.

Implements [GNSSBlockInterface](#).

Definition at line 62 of file [base_dll_pll_tracking_fpga.h](#).

12.19.3.9 role()

```
std::string BaseDllPllTrackingFpga::role () [inline], [override], [virtual]
```

Get role from the Tracking block adapter.

Implements [GNSSBlockInterface](#).

Definition at line 57 of file [base_dll_pll_tracking_fpga.h](#).

Referenced by [BaseDllPllTrackingFpga\(\)](#), [GalileoE5aDllPllTrackingFpga::GalileoE5aDllPllTrackingFpga\(\)](#), [GpsL2MDllPllTrackingFpga::GpsL2MDllPllTrackingFpga\(\)](#) and [GpsL5DllPllTrackingFpga::GpsL5DllPllTrackingFpga\(\)](#).

12.19.3.10 set_channel()

```
void BaseDllPllTrackingFpga::set_channel (
    unsigned int channel) [override], [virtual]
```

Set tracking channel unique ID.

Implements [TrackingInterface](#).

12.19.3.11 set_gnss_synchro()

```
void BaseDllPllTrackingFpga::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

Implements [TrackingInterface](#).

12.19.3.12 start_tracking()

```
void BaseDllPllTrackingFpga::start_tracking () [override], [virtual]
```

Start the tracking process in the FPGA.

Implements [TrackingInterface](#).

12.19.3.13 stop_tracking()

```
void BaseDllPllTrackingFpga::stop_tracking () [override], [virtual]
```

Stop the tracking process in the FPGA.

Implements [TrackingInterface](#).

12.19.4 Member Data Documentation

12.19.4.1 LOCAL_CODE_FPGA_CORRELATOR_SELECT_COUNT

```
const int32_t BaseDllPllTrackingFpga::LOCAL_CODE_FPGA_CORRELATOR_SELECT_COUNT = 0x20000000
[static], [protected]
```

Definition at line 113 of file [base_dll_pll_tracking_fpga.h](#).

12.19.4.2 LOCAL_CODE_FPGA_ENABLE_WRITE_MEMORY

```
const int32_t BaseDllPllTrackingFpga::LOCAL_CODE_FPGA_ENABLE_WRITE_MEMORY = 0x0C000000 [static],
[protected]
```

Definition at line 112 of file [base_dll_pll_tracking_fpga.h](#).

12.19.4.3 tracking_fpga_sc_sptr_

dll_pll_veml_tracking_fpga_sptr BaseDllPllTrackingFpga::tracking_fpga_sc_sptr_ [protected]

Definition at line 119 of file [base_dll_pll_tracking_fpga.h](#).

The documentation for this class was generated from the following file:

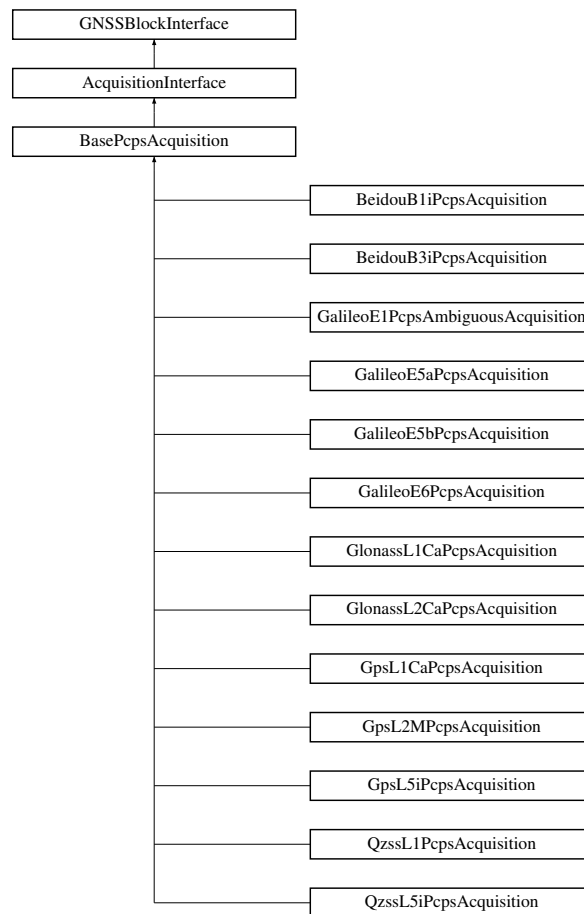
- [base_dll_pll_tracking_fpga.h](#)

12.20 BasePcpsAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#).

#include <base_pcps_acquisition.h>

Inheritance diagram for BasePcpsAcquisition:



Public Member Functions

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int doppler_center) override
Set Doppler center for the grid search.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t latency_samples) override
Sets the resampler latency to account it in the acquisition code delay estimation.
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual std::string [implementation](#) ()=0
- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

12.20.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#).
Definition at line 43 of file [base_pcps_acquisition.h](#).

12.20.2 Member Function Documentation

12.20.2.1 connect()

```
void BasePcpsAcquisition::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.20.2.2 disconnect()

```
void BasePcpsAcquisition::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.20.2.3 get_left_block()

```
gr::basic_block_sptr BasePcpsAcquisition::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.20.2.4 get_right_block()

```
gr::basic_block_sptr BasePcpsAcquisition::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.20.2.5 item_size()

```
size_t BasePcpsAcquisition::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 63 of file [base_pcps_acquisition.h](#).

12.20.2.6 mag()

```
signed int BasePcpsAcquisition::mag () [override], [virtual]
```

Returns the maximum peak of grid search.

Implements [AcquisitionInterface](#).

12.20.2.7 reset()

```
void BasePcpsAcquisition::reset () [override], [virtual]
```

Restart acquisition algorithm.

Implements [AcquisitionInterface](#).

12.20.2.8 role()

```
std::string BasePcpsAcquisition::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 58 of file [base_pcps_acquisition.h](#).

12.20.2.9 set_channel()

```
void BasePcpsAcquisition::set_channel (
    unsigned int channel) [inline], [override], [virtual]
```

Set acquisition channel unique ID.

Implements [AcquisitionInterface](#).

Definition at line 83 of file [base_pcps_acquisition.h](#).

12.20.2.10 set_channel_fsm()

```
void BasePcpsAcquisition::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [inline], [override], [virtual]
```

Set channel fsm associated to this acquisition instance.

Implements [AcquisitionInterface](#).

Definition at line 91 of file [base_pcps_acquisition.h](#).

12.20.2.11 set_doppler_center()

```
void BasePcpsAcquisition::set_doppler_center (
    int doppler_center) [override], [virtual]
```

Set Doppler center for the grid search.

Reimplemented from [AcquisitionInterface](#).

12.20.2.12 set_gnss_synchro()

```
void BasePcpsAcquisition::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

Implements [AcquisitionInterface](#).

Reimplemented in [GalileoE1PcpsAmbiguousAcquisition](#).

12.20.2.13 set_local_code()

```
void BasePcpsAcquisition::set_local_code () [override], [virtual]
```

Sets local code.

Implements [AcquisitionInterface](#).

12.20.2.14 set_resampler_latency()

```
void BasePcpsAcquisition::set_resampler_latency (
    uint32_t latency_samples) [override], [virtual]
```

Sets the resampler latency to account it in the acquisition code delay estimation.

Implements [AcquisitionInterface](#).

12.20.2.15 stop_acquisition()

```
void BasePcpsAcquisition::stop_acquisition () [override], [virtual]
```

Stop running acquisition.

Implements [AcquisitionInterface](#).

The documentation for this class was generated from the following file:

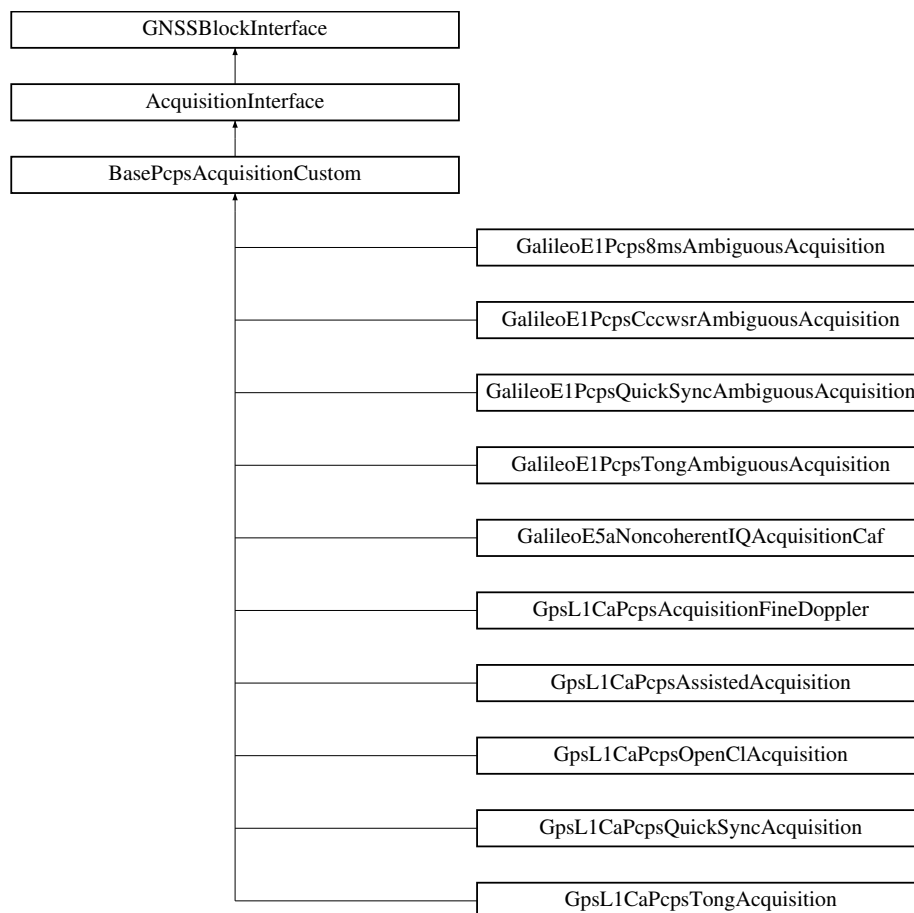
- base_pcps_acquisition.h

12.21 BasePcpsAcquisitionCustom Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#).

```
#include <base_pcps_acquisition_custom.h>
```

Inheritance diagram for BasePcpsAcquisitionCustom:



Public Member Functions

- **BasePcpsAcquisitionCustom** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double code_length_chips, unsigned int

- ms_per_code, bool use_stream_to_vector, const [ThresholdComputeInterface](#) &threshold_compute, uint32_t max_sampled_ms=std::numeric_limits< uint32_t >::max())
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
 - Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.*
- void [set_channel](#) (unsigned int channel) override
 - Set acquisition channel unique ID.*
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
 - Set channel fsm associated to this acquisition instance.*
- signed int [mag](#) () override
 - Returns the maximum peak of grid search.*
- void [reset](#) () override
 - Restart acquisition algorithm.*
- void [stop_acquisition](#) () override
 - Stop running acquisition.*
- void [set_resampler_latency](#) (uint32_t) override
- void [set_local_code](#) () override
 - Sets local code.*

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_doppler_center](#) (int)

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual std::string [implementation](#) ()=0
- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
 - Start the flow of samples if needed.*

Protected Member Functions

- bool [is_type_gr_complex](#) () const

Protected Attributes

- const [Acq_Conf](#) [acq_parameters_](#)
- acquisition_impl_interface_sptr [acquisition_cc_](#)
- [Gnss_Synchro](#) * [gnss_synchro_](#)
- unsigned int [channel_](#)
- volk_gnss_sdr::vector< std::complex< float > > [code_](#)

12.21.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#).
Definition at line 72 of file [base_pcps_acquisition_custom.h](#).

12.21.2 Member Function Documentation

12.21.2.1 connect()

```
void BasePcpsAcquisitionCustom::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.21.2.2 disconnect()

```
void BasePcpsAcquisitionCustom::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.21.2.3 get_left_block()

```
gr::basic_block_sptr BasePcpsAcquisitionCustom::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.21.2.4 get_right_block()

```
gr::basic_block_sptr BasePcpsAcquisitionCustom::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.21.2.5 is_type_gr_complex()

```
bool BasePcpsAcquisitionCustom::is_type_gr_complex () const [inline], [protected]
```

Definition at line 138 of file [base_pcps_acquisition_custom.h](#).

12.21.2.6 item_size()

```
size_t BasePcpsAcquisitionCustom::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 90 of file [base_pcps_acquisition_custom.h](#).

12.21.2.7 mag()

```
signed int BasePcpsAcquisitionCustom::mag () [override], [virtual]
```

Returns the maximum peak of grid search.

Implements [AcquisitionInterface](#).

12.21.2.8 reset()

```
void BasePcpsAcquisitionCustom::reset () [override], [virtual]
```

Restart acquisition algorithm.

Implements [AcquisitionInterface](#).

12.21.2.9 role()

```
std::string BasePcpsAcquisitionCustom::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 88 of file [base_pcps_acquisition_custom.h](#).

12.21.2.10 set_channel()

```
void BasePcpsAcquisitionCustom::set_channel (
    unsigned int channel) [override], [virtual]
```

Set acquisition channel unique ID.

Implements [AcquisitionInterface](#).

12.21.2.11 set_channel_fsm()

```
void BasePcpsAcquisitionCustom::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [override], [virtual]
```

Set channel fsm associated to this acquisition instance.

Implements [AcquisitionInterface](#).

12.21.2.12 set_gnss_synchro()

```
void BasePcpsAcquisitionCustom::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

Implements [AcquisitionInterface](#).

12.21.2.13 set_local_code()

```
void BasePcpsAcquisitionCustom::set_local_code () [override], [virtual]
```

Sets local code.

Implements [AcquisitionInterface](#).

Reimplemented in [GalileoE1PcpsCccwsrAmbiguousAcquisition](#), and [GalileoE5aNoncoherentIQAcquisitionCaf](#).

12.21.2.14 set_resampler_latency()

```
void BasePcpsAcquisitionCustom::set_resampler_latency (
    uint32_t ) [inline], [override], [virtual]
```

Implements [AcquisitionInterface](#).

Definition at line 129 of file [base_pcps_acquisition_custom.h](#).

12.21.2.15 stop_acquisition()

```
void BasePcpsAcquisitionCustom::stop_acquisition () [override], [virtual]
```

Stop running acquisition.

Implements [AcquisitionInterface](#).

12.21.3 Member Data Documentation**12.21.3.1 acq_parameters_**

```
const Acq_Conf BasePcpsAcquisitionCustom::acq_parameters_ [protected]
```

Definition at line 140 of file [base_pcps_acquisition_custom.h](#).

12.21.3.2 acquisition_cc_

```
acquisition_impl_interface_sptr BasePcpsAcquisitionCustom::acquisition_cc_ [protected]
```

Definition at line 141 of file [base_pcps_acquisition_custom.h](#).

12.21.3.3 channel_

```
unsigned int BasePcpsAcquisitionCustom::channel_ [protected]
```

Definition at line 143 of file [base_pcps_acquisition_custom.h](#).

12.21.3.4 code_

```
volk_gnssssdr::vector<std::complex<float> > BasePcpsAcquisitionCustom::code_ [protected]
```

Definition at line 144 of file [base_pcps_acquisition_custom.h](#).

12.21.3.5 gnss_synchro_

`Gnss_Synchro*` BasePcpsAcquisitionCustom::gnss_synchro_ [protected]

Definition at line 142 of file `base_pcps_acquisition_custom.h`.

The documentation for this class was generated from the following file:

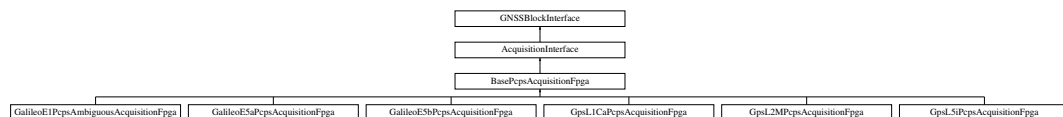
- `base_pcps_acquisition_custom.h`

12.22 BasePcpsAcquisitionFpga Class Reference

Base class providing shared logic for FPGA-based GPS PCPS acquisition adapters.

`#include <base_pcps_acquisition_fpga.h>`

Inheritance diagram for BasePcpsAcquisitionFpga:



Public Member Functions

- **BasePcpsAcquisitionFpga** (const [ConfigurationInterface](#) *configuration, std::string role, double code_rate_cps, double code_length_chips, uint32_t opt_acq_fs_sps, uint32_t default_fpga_blk_exp, uint32_t acq_buff, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override final
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- signed int [mag](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
- void [set_channel](#) (unsigned int channel) override
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
- void [set_doppler_center](#) (int doppler_center) override
- void [reset](#) () override
- void [stop_acquisition](#) () override
- void [set_resampler_latency](#) (uint32_t latency_samples __attribute__((unused))) override
- void [set_local_code](#) () override

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_resampler_latency](#) (uint32_t latency_samples)=0

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual std::string [implementation](#) ()=0
- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Protected Member Functions

- void [init](#) ()

Protected Attributes

- `volk_gnssssdr::vector< uint32_t > d_all_fft_codes_`
- [Acq_Conf_Fpga acq_parameters_](#)

Static Protected Attributes

- `static const uint32_t QUANT_BITS_LOCAL_CODE = 16`
- `static const uint32_t SELECT_LSBITS = 0x0000FFFF`
- `static const uint32_t SELECT_MSBITS = 0xFFFF0000`
- `static const uint32_t SELECT_ALL_CODE_BITS = 0xFFFFFFFF`
- `static const uint32_t SHL_CODE_BITS = 65536`
- `static const uint32_t ACQ_BUFF_0 = 0`
- `static const uint32_t ACQ_BUFF_1 = 1`

12.22.1 Detailed Description

Base class providing shared logic for FPGA-based GPS PCPS acquisition adapters.
Definition at line 44 of file [base_pcps_acquisition_fpga.h](#).

12.22.2 Member Function Documentation

12.22.2.1 connect()

```
void BasePcpsAcquisitionFpga::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.22.2.2 disconnect()

```
void BasePcpsAcquisitionFpga::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.22.2.3 get_left_block()

```
gr::basic_block_sptr BasePcpsAcquisitionFpga::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.22.2.4 get_right_block()

```
gr::basic_block_sptr BasePcpsAcquisitionFpga::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.22.2.5 item_size()

```
size_t BasePcpsAcquisitionFpga::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).
Definition at line 61 of file [base_pcps_acquisition_fpga.h](#).

12.22.2.6 mag()

```
signed int BasePcpsAcquisitionFpga::mag () [override], [virtual]
```

Implements [AcquisitionInterface](#).

12.22.2.7 reset()

```
void BasePcpsAcquisitionFpga::reset () [override], [virtual]
```

Implements [AcquisitionInterface](#).

12.22.2.8 role()

```
std::string BasePcpsAcquisitionFpga::role () [inline], [final], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 59 of file [base_pcps_acquisition_fpga.h](#).

12.22.2.9 set_channel()

```
void BasePcpsAcquisitionFpga::set_channel (
    unsigned int channel) [override], [virtual]
```

Implements [AcquisitionInterface](#).

12.22.2.10 set_channel_fsm()

```
void BasePcpsAcquisitionFpga::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [override], [virtual]
```

Implements [AcquisitionInterface](#).

12.22.2.11 set_doppler_center()

```
void BasePcpsAcquisitionFpga::set_doppler_center (
    int doppler_center) [override], [virtual]
```

Reimplemented from [AcquisitionInterface](#).

12.22.2.12 set_gnss_synchro()

```
void BasePcpsAcquisitionFpga::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [override], [virtual]
```

Implements [AcquisitionInterface](#).

12.22.2.13 set_local_code()

```
void BasePcpsAcquisitionFpga::set_local_code () [override], [virtual]
```

Implements [AcquisitionInterface](#).

12.22.2.14 set_resampler_latency()

```
void BasePcpsAcquisitionFpga::set_resampler_latency (
    uint32_t latency_samples __attribute__((unused))) [inline], [override]
```

Definition at line 76 of file [base_pcps_acquisition_fpga.h](#).

12.22.2.15 stop_acquisition()

```
void BasePcpsAcquisitionFpga::stop_acquisition () [override], [virtual]
```

Implements [AcquisitionInterface](#).

12.22.3 Member Data Documentation**12.22.3.1 ACQ_BUFF_0**

```
const uint32_t BasePcpsAcquisitionFpga::ACQ_BUFF_0 = 0 [static], [protected]
```

Definition at line 86 of file [base_pcps_acquisition_fpga.h](#).

12.22.3.2 ACQ_BUFF_1

```
const uint32_t BasePcpsAcquisitionFpga::ACQ_BUFF_1 = 1 [static], [protected]
```

Definition at line 87 of file [base_pcps_acquisition_fpga.h](#).

12.22.3.3 acq_parameters_

[Acq_Conf_Fpga](#) BasePcpsAcquisitionFpga::acq_parameters_ [protected]

Definition at line 94 of file [base_pcps_acquisition_fpga.h](#).

12.22.3.4 d_all_fft_codes_

volk_gnssdr::vector<uint32_t> BasePcpsAcquisitionFpga::d_all_fft_codes_ [protected]

Definition at line 93 of file [base_pcps_acquisition_fpga.h](#).

12.22.3.5 QUANT_BITS_LOCAL_CODE

const uint32_t BasePcpsAcquisitionFpga::QUANT_BITS_LOCAL_CODE = 16 [static], [protected]

Definition at line 81 of file [base_pcps_acquisition_fpga.h](#).

12.22.3.6 SELECT_ALL_CODE_BITS

const uint32_t BasePcpsAcquisitionFpga::SELECT_ALL_CODE_BITS = 0xFFFFFFFF [static], [protected]

Definition at line 84 of file [base_pcps_acquisition_fpga.h](#).

12.22.3.7 SELECT_LSBITS

const uint32_t BasePcpsAcquisitionFpga::SELECT_LSBITS = 0x0000FFFF [static], [protected]

Definition at line 82 of file [base_pcps_acquisition_fpga.h](#).

12.22.3.8 SELECT_MSBITS

const uint32_t BasePcpsAcquisitionFpga::SELECT_MSBITS = 0xFFFF0000 [static], [protected]

Definition at line 83 of file [base_pcps_acquisition_fpga.h](#).

12.22.3.9 SHL_CODE_BITS

const uint32_t BasePcpsAcquisitionFpga::SHL_CODE_BITS = 65536 [static], [protected]

Definition at line 85 of file [base_pcps_acquisition_fpga.h](#).

The documentation for this class was generated from the following file:

- [base_pcps_acquisition_fpga.h](#)

12.23 Bayesian_estimator Class Reference

[Bayesian_estimator](#) is an estimator of noise characteristics (i.e. mean, covariance)

```
#include <bayesian_estimation.h>
```

Public Member Functions

- **Bayesian_estimator** (int ny)
- **Bayesian_estimator** (const arma::vec &mu_prior_0, int kappa_prior_0, int nu_prior_0, const arma::mat &Psi_prior_0)
- void **init** (const arma::mat &mu_prior_0, int kappa_prior_0, int nu_prior_0, const arma::mat &Psi_prior_0)
- void **update_sequential** (const arma::vec &data)
- void **update_sequential** (const arma::vec &data, const arma::vec &mu_prior_0, int kappa_prior_0, int nu_↵prior_0, const arma::mat &Psi_prior_0)
- arma::mat **get_mu_est** () const
- arma::mat **get_Psi_est** () const

12.23.1 Detailed Description

[Bayesian_estimator](#) is an estimator of noise characteristics (i.e. mean, covariance)

[Bayesian_estimator](#) is an estimator which performs estimation of noise characteristics from a sequence of identically and independently distributed (IID) samples of a stationary stochastic process by way of Bayesian inference using conjugate priors. The posterior distribution is assumed to be Gaussian with mean $\mathbf{\mu}$ and covariance $\hat{\mathbf{C}}$, which has a conjugate prior given by a normal-inverse-Wishart distribution with parameters $\mathbf{\mu}_0$, $\mathbf{\kappa}_0$, $\mathbf{\nu}_0$, and $\mathbf{\Psi}$.

[1] TODO: Ref1

Definition at line 60 of file [bayesian_estimation.h](#).

The documentation for this class was generated from the following file:

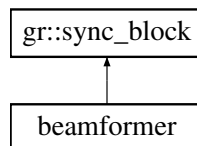
- [bayesian_estimation.h](#)

12.24 beamformer Class Reference

This class implements a real-time software-defined spatial filter using the CTTC GNSS experimental antenna array input and a set of dynamically reloadable weights.

```
#include <beamformer.h>
```

Inheritance diagram for beamformer:



Public Member Functions

- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- beamformer_sptr **make_beamformer_sptr** ()

12.24.1 Detailed Description

This class implements a real-time software-defined spatial filter using the CTTC GNSS experimental antenna array input and a set of dynamically reloadable weights.

Definition at line 42 of file [beamformer.h](#).

The documentation for this class was generated from the following file:

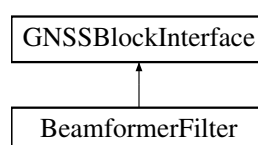
- [beamformer.h](#)

12.25 BeamformerFilter Class Reference

Interface of an adapter of a digital beamformer block to a [GNSSBlockInterface](#).

```
#include <beamformer_filter.h>
```

Inheritance diagram for BeamformerFilter:



Public Member Functions

- **BeamformerFilter** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream)
- std::string [role](#) () override
- std::string [implementation](#) () override
returns "Beamformer_Filte"
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.25.1 Detailed Description

Interface of an adapter of a digital beamformer block to a [GNSSBlockInterface](#).
Definition at line 38 of file [beamformer_filter.h](#).

12.25.2 Member Function Documentation

12.25.2.1 connect()

```
void BeamformerFilter::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.25.2.2 disconnect()

```
void BeamformerFilter::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.25.2.3 get_left_block()

```
gr::basic_block_sptr BeamformerFilter::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.25.2.4 get_right_block()

```
gr::basic_block_sptr BeamformerFilter::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.25.2.5 implementation()

```
std::string BeamformerFilter::implementation () [inline], [override], [virtual]
```

returns "Beamformer_Filte"
Implements [GNSSBlockInterface](#).
Definition at line 53 of file [beamformer_filter.h](#).

12.25.2.6 item_size()

size_t BeamformerFilter::item_size () [inline], [override], [virtual]

Implements [GNSSBlockInterface](#).

Definition at line 58 of file [beamformer_filter.h](#).

12.25.2.7 role()

std::string BeamformerFilter::role () [inline], [override], [virtual]

Implements [GNSSBlockInterface](#).

Definition at line 47 of file [beamformer_filter.h](#).

The documentation for this class was generated from the following file:

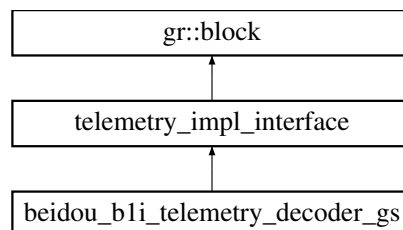
- [beamformer_filter.h](#)

12.26 beidou_b1i_telemetry_decoder_gs Class Reference

This class implements a block that decodes the BeiDou DNAV data.

#include <beidou_b1i_telemetry_decoder_gs.h>

Inheritance diagram for beidou_b1i_telemetry_decoder_gs:



Public Member Functions

- [~beidou_b1i_telemetry_decoder_gs](#) () override
Class destructor.
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
Set satellite PRN.
- void [set_channel](#) (int channel) override
Set receiver's channel.
- void [reset](#) () override
- int [general_work](#) (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
This is where all signal processing takes place.

Public Member Functions inherited from [telemetry_impl_interface](#)

- [telemetry_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)

Friends

- beidou_b1i_telemetry_decoder_gs_sptr [beidou_b1i_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, const [TIm_Conf](#) &conf)

Additional Inherited Members

Protected Member Functions inherited from [telemetry_impl_interface](#)

- void **configure_basic_outputs** ()
- void **configure_dump_file** (int32_t channel, bool enable_dump, std::string &dump_filename, std::ofstream &dump_file) const
- void **configure_crc_stats_channel** (int32_t channel, bool &dump_crc_stats, std::unique_ptr< [Tlm_CRC_Stats](#) > &crc_stats) const

12.26.1 Detailed Description

This class implements a block that decodes the BeiDou DNAV data.

Note

Code added as part of GSoC 2018 program

Definition at line 51 of file [beidou_b1i_telemetry_decoder_gs.h](#).

12.26.2 Constructor & Destructor Documentation

12.26.2.1 ~beidou_b1i_telemetry_decoder_gs()

```
beidou_b1i_telemetry_decoder_gs::~beidou_b1i_telemetry_decoder_gs () [override]
```

Class destructor.

12.26.3 Member Function Documentation

12.26.3.1 general_work()

```
int beidou_b1i_telemetry_decoder_gs::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

This is where all signal processing takes place.

12.26.3.2 reset()

```
void beidou_b1i_telemetry_decoder_gs::reset () [override], [virtual]
```

Implements [telemetry_impl_interface](#).

12.26.3.3 set_channel()

```
void beidou_b1i_telemetry_decoder_gs::set_channel (
    int channel) [override], [virtual]
```

Set receiver's channel.

Implements [telemetry_impl_interface](#).

12.26.3.4 set_satellite()

```
void beidou_b1i_telemetry_decoder_gs::set_satellite (
    const Gnss\_Satellite & satellite) [override], [virtual]
```

Set satellite PRN.

Implements [telemetry_impl_interface](#).

The documentation for this class was generated from the following file:

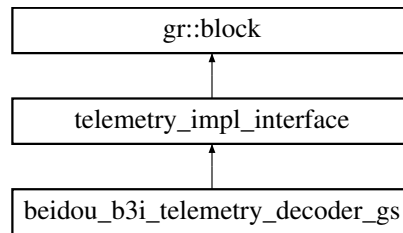
- [beidou_b1i_telemetry_decoder_gs.h](#)

12.27 beidou_b3i_telemetry_decoder_gs Class Reference

This class implements a block that decodes the BeiDou DNAV data.

```
#include <beidou_b3i_telemetry_decoder_gs.h>
```

Inheritance diagram for beidou_b3i_telemetry_decoder_gs:



Public Member Functions

- [~beidou_b3i_telemetry_decoder_gs](#) () override
Class destructor.
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
Set satellite PRN.
- void [set_channel](#) (int channel) override
Set receiver's channel.
- void [reset](#) () override
- int [general_work](#) (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
This is where all signal processing takes place.

Public Member Functions inherited from [telemetry_impl_interface](#)

- [telemetry_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)

Friends

- beidou_b3i_telemetry_decoder_gs_sptr [beidou_b3i_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf)

Additional Inherited Members

Protected Member Functions inherited from [telemetry_impl_interface](#)

- void [configure_basic_outputs](#) ()
- void [configure_dump_file](#) (int32_t channel, bool enable_dump, std::string &dump_filename, std::ofstream &dump_file) const
- void [configure_crc_stats_channel](#) (int32_t channel, bool &dump_crc_stats, std::unique_ptr< [Tlm_CRC_Stats](#) > &crc_stats) const

12.27.1 Detailed Description

This class implements a block that decodes the BeiDou DNAV data.

Definition at line 47 of file [beidou_b3i_telemetry_decoder_gs.h](#).

12.27.2 Constructor & Destructor Documentation

12.27.2.1 ~beidou_b3i_telemetry_decoder_gs()

```
beidou_b3i_telemetry_decoder_gs::~beidou_b3i_telemetry_decoder_gs () [override]
```

Class destructor.

12.27.3 Member Function Documentation

12.27.3.1 `general_work()`

```
int beidou_b3i_telemetry_decoder_gs::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

This is where all signal processing takes place.

12.27.3.2 `reset()`

```
void beidou_b3i_telemetry_decoder_gs::reset () [override], [virtual]
```

Implements [telemetry_impl_interface](#).

12.27.3.3 `set_channel()`

```
void beidou_b3i_telemetry_decoder_gs::set_channel (
    int channel) [override], [virtual]
```

Set receiver's channel.

Implements [telemetry_impl_interface](#).

12.27.3.4 `set_satellite()`

```
void beidou_b3i_telemetry_decoder_gs::set_satellite (
    const Gnss_Satellite & satellite) [override], [virtual]
```

Set satellite PRN.

Implements [telemetry_impl_interface](#).

The documentation for this class was generated from the following file:

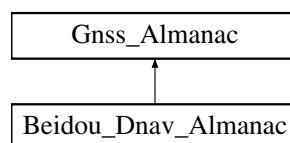
- [beidou_b3i_telemetry_decoder_gs.h](#)

12.28 Beidou_Dnav_Almanac Class Reference

This class is a storage for the BeiDou D1 almanac.

```
#include <beidou_dnav_almanac.h>
```

Inheritance diagram for Beidou_Dnav_Almanac:



Public Member Functions

- [Beidou_Dnav_Almanac](#) ()
- `template<class Archive>`
void [serialize](#) (Archive &ar, const unsigned int version)

Public Member Functions inherited from [Gnss_Almanac](#)

- [Gnss_Almanac](#) ()=default
- double [predicted_doppler](#) (double rx_time_s, double lat, double lon, double h, double ve, double vn, double vu, int band) const
Computes prediction of the Doppler shift for a given time and receiver's position and velocity.
- void [satellitePosVelComputation](#) (double transmitTime, std::array< double, 7 > &pos_vel_dtr) const
Computes satellite Position and Velocity, in ECEF, for a given time (expressed in seconds of week)

Public Attributes

- int [SV_health](#) {}
SV Health.

Public Attributes inherited from [Gnss_Almanac](#)

- uint32_t [PRN](#) {}
SV PRN NUMBER.
- double [delta_i](#) {}
Inclination Angle at Reference Time (relative to $i_0 = 0.30$ semi-circles)
- int32_t [toa](#) {}
Almanac data reference time of week [s].
- int32_t [WNa](#) {}
Almanac week number.
- double [M_0](#) {}
Mean Anomaly at Reference Time [semi-circles].
- double [ecc](#) {}
Eccentricity [dimensionless].
- double [sqrtA](#) {}
Square Root of the Semi-Major Axis [sqrt(m)].
- double [OMEGA_0](#) {}
Longitude of Ascending Node of Orbit Plane at Weekly Epoch [semi-circles].
- double [omega](#) {}
Argument of Perigee [semi-circles].
- double [OMEGAdot](#) {}
Rate of Right Ascension [semi-circles/s].
- double [af0](#) {}
Coefficient 0 of code phase offset model [s].
- double [af1](#) {}
Coefficient 1 of code phase offset model [s/s].

Additional Inherited Members**Protected Attributes inherited from [Gnss_Almanac](#)**

- char [System](#) {}
Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou.

12.28.1 Detailed Description

This class is a storage for the BeiDou D1 almanac.
Definition at line 33 of file [beidou_dnav_almanac.h](#).

12.28.2 Constructor & Destructor Documentation**12.28.2.1 Beidou_Dnav_Almanac()**

```
Beidou_Dnav_Almanac::Beidou_Dnav_Almanac () [inline]
```

Default constructor

Definition at line 39 of file [beidou_dnav_almanac.h](#).

References [Gnss_Almanac::System](#).

12.28.3 Member Function Documentation

12.28.3.1 serialize()

```
template<class Archive>
void Beidou_Dnav_Almanac::serialize (
    Archive & ar,
    const unsigned int version) [inline]
```

Definition at line 48 of file [beidou_dnav_almanac.h](#).

12.28.4 Member Data Documentation

12.28.4.1 SV_health

```
int Beidou_Dnav_Almanac::SV_health {}
```

SV Health.

Definition at line 44 of file [beidou_dnav_almanac.h](#).

The documentation for this class was generated from the following file:

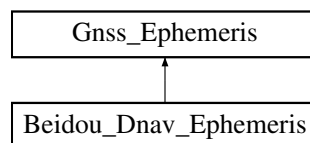
- [beidou_dnav_almanac.h](#)

12.29 Beidou_Dnav_Ephemeris Class Reference

This is a storage class for the Beidou SV ephemeris data as described in BeiDou Navigation Satellite System Signal In Space Interface Control Document Open Service Signal B1I (Version 3.0)

```
#include <beidou_dnav_ephemeris.h>
```

Inheritance diagram for Beidou_Dnav_Ephemeris:



Public Member Functions

- [Beidou_Dnav_Ephemeris](#) ()
- `template<class Archive>`
void [serialize](#) (Archive &archive, const unsigned int version)

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Public Member Functions inherited from [Gnss_Ephemeris](#)

- double [sv_clock_drift](#) (double transmitTime)
Sets (satClkDrift) and (dtr), and returns the clock drift in seconds according to the User Algorithm for SV Clock Correction (IS-GPS-200M, 20.3.3.3.1, and Galileo OS SIS ICD, 5.1.4).
- double [predicted_doppler](#) (double rx_time_s, double lat, double lon, double h, double ve, double vn, double vu, int band) const
Computes prediction of the Doppler shift for a given time and receiver's position and velocity.
- void [satellitePosition](#) (double transmitTime)
Computes the ECEF SV coordinates and ECEF velocity.

Public Attributes

- int [SV_accuracy](#) {}
User Range Accuracy (URA) index of the SV (reference paragraph 5.2.4.5) for the standard positioning service user.

- int [SV_health](#) {}
- double [TGD1](#) {}
Estimated Group Delay Differential on B1I [s].
- double [TGD2](#) {}
Estimated Group Delay Differential on B2I [s].
- double [AODC](#) {}
Age of Data, Clock.
- double [AODE](#) {}
Age of Data, Ephemeris.
- int [AODO](#) {}
Age of Data Offset (AODO) term for the navigation message correction table (NMCT) contained in subframe 4 (reference paragraph 20.3.3.5.1.9) [s].
- int [sig_type](#) {}
*BDS: data source (0:unknown,1:B1I,2:B1Q,3:B2I,4:B2Q,5:B3I,6:B3Q) */.*
- int [nav_type](#) {}
*BDS: nav type (0:unknown,1:IGSO/MEO,2:GEO) */.*
- bool [fit_interval_flag](#) {}
Curve-fit interval used by the CS (Block II/IIA/IIR/IIR-M/IIF) and SS (Block IIIA) in determining the ephemeris parameters, as follows: 0 = 4 hours, 1 = greater than 4 hours.
- double [spare1](#) {}
- double [spare2](#) {}
- bool [integrity_status_flag](#) {}
If true, enhanced level of integrity assurance.
- bool [alert_flag](#) {}
If true, indicates that the SV URA may be worse than indicated in d_SV_accuracy, use that SV at our own risk.
- bool [antispoofing_flag](#) {}
If true, the AntiSpoofing mode is ON in that SV.
- std::map< int, std::string > [satelliteBlock](#)
Map that stores to which block the PRN belongs.

Public Attributes inherited from [Gnss_Ephemeris](#)

- uint32_t [PRN](#) {}
SV ID.
- double [M_0](#) {}
Mean anomaly at reference time [rad].
- double [delta_n](#) {}
Mean motion difference from computed value [rad/sec].
- double [ecc](#) {}
Eccentricity.
- double [sqrtA](#) {}
Square root of the semi-major axis [meters^{1/2}].
- double [OMEGA_0](#) {}
Longitude of ascending node of orbital plane at weekly epoch [rad].
- double [i_0](#) {}
Inclination angle at reference time [rad].
- double [omega](#) {}
Argument of perigee [rad].
- double [OMEGAdot](#) {}
Rate of right ascension [rad/sec].
- double [idot](#) {}
Rate of inclination angle [rad/sec].

- double [Cuc](#) {}
Amplitude of the cosine harmonic correction term to the argument of latitude [rad].
- double [Cus](#) {}
Amplitude of the sine harmonic correction term to the argument of latitude [rad].
- double [Crc](#) {}
Amplitude of the cosine harmonic correction term to the orbit radius [meters].
- double [Crs](#) {}
Amplitude of the sine harmonic correction term to the orbit radius [meters].
- double [Cic](#) {}
Amplitude of the cosine harmonic correction term to the angle of inclination [rad].
- double [Cis](#) {}
Amplitude of the sine harmonic correction term to the angle of inclination [rad].
- int32_t [toe](#) {}
Ephemeris reference time [s].
- int32_t [toc](#) {}
Clock correction data reference Time of Week [sec].
- double [af0](#) {}
SV clock bias correction coefficient [s].
- double [af1](#) {}
SV clock drift correction coefficient [s/s].
- double [af2](#) {}
SV clock drift rate correction coefficient [s/s²].
- double [satClkDrift](#) {}
SV clock drift.
- double [dtr](#) {}
Relativistic clock correction term.
- int32_t [WN](#) {}
Week number.
- int32_t [tow](#) {}
Time of Week.
- double [satpos_X](#) {}
Earth-fixed coordinate x of the satellite [m]. Intersection of the IERS Reference Meridian (IRM) and the plane passing through the origin and normal to the Z-axis.
- double [satpos_Y](#) {}
Earth-fixed coordinate y of the satellite [m]. Completes a right-handed, Earth-Centered, Earth-Fixed orthogonal coordinate system.
- double [satpos_Z](#) {}
Earth-fixed coordinate z of the satellite [m]. The direction of the IERS (International Earth Rotation and Reference Systems Service) Reference Pole (IRP).
- double [satvel_X](#) {}
Earth-fixed velocity coordinate x of the satellite [m].
- double [satvel_Y](#) {}
Earth-fixed velocity coordinate y of the satellite [m].
- double [satvel_Z](#) {}
Earth-fixed velocity coordinate z of the satellite [m].

Additional Inherited Members

Protected Attributes inherited from [Gnss_Ephemeris](#)

- char [System](#) {}
Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou.

12.29.1 Detailed Description

This is a storage class for the Beidou SV ephemeris data as described in BeiDou Navigation Satellite System Signal In Space Interface Control Document Open Service Signal B1I (Version 3.0)

See <http://en.beidou.gov.cn/SYSTEMS/Officialdocument/201902/P020190227601370045731.pdf>

Definition at line 39 of file [beidou_dnav_ephemeris.h](#).

12.29.2 Constructor & Destructor Documentation

12.29.2.1 Beidou_Dnav_Ephemeris()

```
Beidou_Dnav_Ephemeris::Beidou_Dnav_Ephemeris ()
```

Default constructor

12.29.3 Member Function Documentation

12.29.3.1 serialize()

```
template<class Archive>
void Beidou_Dnav_Ephemeris::serialize (
    Archive & archive,
    const unsigned int version) [inline]
```

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Definition at line 87 of file [beidou_dnav_ephemeris.h](#).

References [Gnss_Ephemeris::af0](#), [Gnss_Ephemeris::af1](#), [Gnss_Ephemeris::af2](#), [alert_flag](#), [antispoofing_flag](#), [AODC](#), [AODE](#), [AODO](#), [Gnss_Ephemeris::Cic](#), [Gnss_Ephemeris::Cis](#), [Gnss_Ephemeris::Crc](#), [Gnss_Ephemeris::Crs](#), [Gnss_Ephemeris::Cuc](#), [Gnss_Ephemeris::Cus](#), [Gnss_Ephemeris::delta_n](#), [Gnss_Ephemeris::dtr](#), [Gnss_Ephemeris::ecc](#), [fit_interval_flag](#), [Gnss_Ephemeris::i_0](#), [Gnss_Ephemeris::idot](#), [integrity_status_flag](#), [Gnss_Ephemeris::M_0](#), [nav_type](#), [Gnss_Ephemeris::omega](#), [Gnss_Ephemeris::OMEGA_0](#), [Gnss_Ephemeris::OMEGAdot](#), [Gnss_Ephemeris::PRN](#), [Gnss_Ephemeris::satClkDrift](#), [sig_type](#), [Gnss_Ephemeris::sqrtA](#), [SV_accuracy](#), [TGD1](#), [TGD2](#), [Gnss_Ephemeris::toc](#), [Gnss_Ephemeris::toe](#), [Gnss_Ephemeris::tow](#), and [Gnss_Ephemeris::WN](#).

12.29.4 Member Data Documentation

12.29.4.1 alert_flag

```
bool Beidou_Dnav_Ephemeris::alert_flag {}
```

If true, indicates that the SV URA may be worse than indicated in `d_SV_accuracy`, use that SV at our own risk.

Definition at line 76 of file [beidou_dnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.29.4.2 antispoofing_flag

```
bool Beidou_Dnav_Ephemeris::antispoofing_flag {}
```

If true, the AntiSpoofing mode is ON in that SV.

Definition at line 77 of file [beidou_dnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.29.4.3 AODC

```
double Beidou_Dnav_Ephemeris::AODC {}
```

Age of Data, Clock.

Definition at line 51 of file [beidou_dnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.29.4.4 AODE

```
double Beidou_Dnav_Ephemeris::AODE {}
```

Age of Data, Ephemeris.

Definition at line 52 of file [beidou_dnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.29.4.5 AODO

```
int Beidou_Dnav_Ephemeris::AODO {}
```

Age of Data Offset (AODO) term for the navigation message correction table (NMCT) contained in subframe 4 (reference paragraph 20.3.3.5.1.9) [s].

Definition at line 53 of file [beidou_dnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.29.4.6 fit_interval_flag

```
bool Beidou_Dnav_Ephemeris::fit_interval_flag {}
```

Curve-fit interval used by the CS (Block II/IIA/IIR/IIR-M/IIF) and SS (Block IIIA) in determining the ephemeris parameters, as follows: 0 = 4 hours, 1 = greater than 4 hours.

Definition at line 58 of file [beidou_dnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.29.4.7 integrity_status_flag

```
bool Beidou_Dnav_Ephemeris::integrity_status_flag {}
```

If true, enhanced level of integrity assurance.

If false, indicates that the conveying signal is provided with the legacy level of integrity assurance. That is, the probability that the instantaneous URE of the conveying signal exceeds 4.42 times the upper bound value of the current broadcast URA index, for more than 5.2 seconds, without an accompanying alert, is less than 1E-5 per hour.

If true, indicates that the conveying signal is provided with an enhanced level of integrity assurance. That is, the probability that the instantaneous URE of the conveying signal exceeds 5.73 times the upper bound value of the current broadcast URA index, for more than 5.2 seconds, without an accompanying alert, is less than 1E-8 per hour.

Definition at line 75 of file [beidou_dnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.29.4.8 nav_type

```
int Beidou_Dnav_Ephemeris::nav_type {}
```

BDS: nav type (0:unknown,1:IGSO/MEO,2:GEO) */.

Definition at line 56 of file [beidou_dnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.29.4.9 satelliteBlock

```
std::map<int, std::string> Beidou_Dnav_Ephemeris::satelliteBlock
```

Map that stores to which block the PRN belongs.

Definition at line 79 of file [beidou_dnav_ephemeris.h](#).

12.29.4.10 sig_type

```
int Beidou_Dnav_Ephemeris::sig_type {}
```

BDS: data source (0:unknown,1:B1I,2:B1Q,3:B2I,4:B2Q,5:B3I,6:B3Q) */.

Definition at line 55 of file [beidou_dnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.29.4.11 spare1

```
double Beidou_Dnav_Ephemeris::spare1 {}
```

Definition at line 59 of file [beidou_dnav_ephemeris.h](#).

12.29.4.12 spare2

```
double Beidou_Dnav_Ephemeris::spare2 {}
```

Definition at line 60 of file [beidou_dnav_ephemeris.h](#).

12.29.4.13 SV_accuracy

```
int Beidou_Dnav_Ephemeris::SV_accuracy {}
```

User Range Accuracy (URA) index of the SV (reference paragraph 5.2.4.5) for the standard positioning service user.

Definition at line 47 of file [beidou_dnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.29.4.14 SV_health

```
int Beidou_Dnav_Ephemeris::SV_health {}
```

Definition at line 48 of file [beidou_dnav_ephemeris.h](#).

12.29.4.15 TGD1

```
double Beidou_Dnav_Ephemeris::TGD1 {}
```

Estimated Group Delay Differential on B1I [s].

Definition at line 49 of file [beidou_dnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.29.4.16 TGD2

```
double Beidou_Dnav_Ephemeris::TGD2 {}
```

Estimated Group Delay Differential on B2I [s].

Definition at line 50 of file [beidou_dnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

The documentation for this class was generated from the following file:

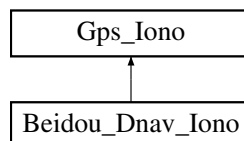
- [beidou_dnav_ephemeris.h](#)

12.30 Beidou_Dnav_Iono Class Reference

This class is a storage for the BEIDOU IONOSPHERIC data as described in ICD v2.1.

```
#include <beidou_dnav_iono.h>
```

Inheritance diagram for Beidou_Dnav_Iono:

**Public Member Functions**

- [Beidou_Dnav_Iono](#) ()=default
Default constructor.

Public Member Functions inherited from [Gps_Iono](#)

- [Gps_Iono](#) ()=default
Default constructor.
- `template<class Archive>`
void [serialize](#) (Archive &archive, const unsigned int version)
Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Additional Inherited Members

Public Attributes inherited from [Gps_Iono](#)

- double [alpha0](#) {}
Coefficient 0 of a cubic equation representing the amplitude of the vertical delay [s].
- double [alpha1](#) {}
Coefficient 1 of a cubic equation representing the amplitude of the vertical delay [s/semi-circle].
- double [alpha2](#) {}
Coefficient 2 of a cubic equation representing the amplitude of the vertical delay [s(semi-circle)²].
- double [alpha3](#) {}
Coefficient 3 of a cubic equation representing the amplitude of the vertical delay [s(semi-circle)³].
- double [beta0](#) {}
Coefficient 0 of a cubic equation representing the period of the model [s].
- double [beta1](#) {}
Coefficient 1 of a cubic equation representing the period of the model [s/semi-circle].
- double [beta2](#) {}
Coefficient 2 of a cubic equation representing the period of the model [s(semi-circle)²].
- double [beta3](#) {}
Coefficient 3 of a cubic equation representing the period of the model [s(semi-circle)³].
- bool [valid](#) {}
Valid flag.

12.30.1 Detailed Description

This class is a storage for the BEIDOU IONOSPHERIC data as described in ICD v2.1.

Definition at line 33 of file [beidou_dnav_iono.h](#).

12.30.2 Constructor & Destructor Documentation

12.30.2.1 Beidou_Dnav_Iono()

```
Beidou_Dnav_Iono::Beidou_Dnav_Iono () [default]
```

Default constructor.

The documentation for this class was generated from the following file:

- [beidou_dnav_iono.h](#)

12.31 Beidou_Dnav_Navigation_Message Class Reference

This class decodes a BeiDou D1 NAV Data message.

```
#include <beidou_dnav_navigation_message.h>
```

Public Member Functions

- [Beidou_Dnav_Navigation_Message](#) ()
- [Beidou_Dnav_Ephemeris](#) [get_ephemeris](#) () const
Obtain a BDS SV Ephemeris class filled with current SV data.
- [Beidou_Dnav_Iono](#) [get_iono](#) ()
Obtain a BDS ionospheric correction parameters class filled with current SV data.
- [Beidou_Dnav_Utc_Model](#) [get_utc_model](#) ()
Obtain a BDS UTC model parameters class filled with current SV data.
- int32_t [d1_subframe_decoder](#) (std::string const &subframe)
Decodes the BDS D1 NAV message.
- int32_t [d2_subframe_decoder](#) (std::string const &subframe)

- Decodes the BDS D2 NAV message.*
- double `utc_time` (double beidoutime_corrected) const
Computes the Coordinated Universal Time (UTC) and returns it in [s].
- bool `satellite_validation` ()
- bool `have_new_ephemeris` ()
Returns true if new Ephemeris has arrived. The flag is set to false when the function is executed.
- bool `have_new_iono` () const
Returns true if new Iono model has arrived. The flag is set to false when the function is executed.
- bool `have_new_utc_model` ()
Returns true if new UTC model has arrived. The flag is set to false when the function is executed.
- bool `have_new_almanac` ()
Returns true if new UTC model has arrived. The flag is set to false when the function is executed.
- void `set_satellite_PRN` (uint32_t prn)
Sets satellite PRN number.
- void `set_signal_type` (int32_t signal_type)
- bool `get_flag_CRC_test` () const
- bool `get_flag_new_SOW_available` () const
- void `set_flag_new_SOW_available` (bool new_SOW_available)
- double `get_SOW` () const

12.31.1 Detailed Description

This class decodes a BeiDou D1 NAV Data message.

Definition at line 46 of file [beidou_dnav_navigation_message.h](#).

12.31.2 Constructor & Destructor Documentation

12.31.2.1 Beidou_Dnav_Navigation_Message()

```
Beidou_Dnav_Navigation_Message::Beidou_Dnav_Navigation_Message ()
```

Default constructor

12.31.3 Member Function Documentation

12.31.3.1 d1_subframe_decoder()

```
int32_t Beidou_Dnav_Navigation_Message::d1_subframe_decoder (
    std::string const & subframe)
```

Decodes the BDS D1 NAV message.

12.31.3.2 d2_subframe_decoder()

```
int32_t Beidou_Dnav_Navigation_Message::d2_subframe_decoder (
    std::string const & subframe)
```

Decodes the BDS D2 NAV message.

12.31.3.3 get_ephemeris()

```
Beidou\_Dnav\_Ephemeris Beidou_Dnav_Navigation_Message::get_ephemeris () const
```

Obtain a BDS SV Ephemeris class filled with current SV data.

12.31.3.4 get_flag_CRC_test()

```
bool Beidou_Dnav_Navigation_Message::get_flag_CRC_test () const [inline]
```

Definition at line 120 of file [beidou_dnav_navigation_message.h](#).

12.31.3.5 get_flag_new_SOW_available()

`bool Beidou_Dnav_Navigation_Message::get_flag_new_SOW_available () const [inline]`
 Definition at line 125 of file [beidou_dnav_navigation_message.h](#).

12.31.3.6 get_iono()

[Beidou_Dnav_Iono](#) `Beidou_Dnav_Navigation_Message::get_iono ()`
 Obtain a BDS ionospheric correction parameters class filled with current SV data.

12.31.3.7 get_SOW()

`double Beidou_Dnav_Navigation_Message::get_SOW () const [inline]`
 Definition at line 135 of file [beidou_dnav_navigation_message.h](#).

12.31.3.8 get_utc_model()

[Beidou_Dnav_Utc_Model](#) `Beidou_Dnav_Navigation_Message::get_utc_model ()`
 Obtain a BDS UTC model parameters class filled with current SV data.

12.31.3.9 have_new_almanac()

`bool Beidou_Dnav_Navigation_Message::have_new_almanac ()`
 Returns true if new UTC model has arrived. The flag is set to false when the function is executed.

12.31.3.10 have_new_ephemeris()

`bool Beidou_Dnav_Navigation_Message::have_new_ephemeris ()`
 Returns true if new Ephemeris has arrived. The flag is set to false when the function is executed.

12.31.3.11 have_new_iono()

`bool Beidou_Dnav_Navigation_Message::have_new_iono () const`
 Returns true if new Iono model has arrived. The flag is set to false when the function is executed.

12.31.3.12 have_new_utc_model()

`bool Beidou_Dnav_Navigation_Message::have_new_utc_model ()`
 Returns true if new UTC model has arrived. The flag is set to false when the function is executed.

12.31.3.13 set_flag_new_SOW_available()

`void Beidou_Dnav_Navigation_Message::set_flag_new_SOW_available (`
 `bool new_SOW_available) [inline]`
 Definition at line 130 of file [beidou_dnav_navigation_message.h](#).

12.31.3.14 set_satellite_PRN()

`void Beidou_Dnav_Navigation_Message::set_satellite_PRN (`
 `uint32_t prn) [inline]`
 Sets satellite PRN number.
 Definition at line 110 of file [beidou_dnav_navigation_message.h](#).

12.31.3.15 set_signal_type()

`void Beidou_Dnav_Navigation_Message::set_signal_type (`
 `int32_t signal_type) [inline]`
 Definition at line 115 of file [beidou_dnav_navigation_message.h](#).

12.31.3.16 utc_time()

```
double Beidou_Dnav_Navigation_Message::utc_time (
    double beidou_time_corrected) const
```

Computes the Coordinated Universal Time (UTC) and returns it in [s].
The documentation for this class was generated from the following file:

- [beidou_dnav_navigation_message.h](#)

12.32 Beidou_Dnav_Utc_Model Class Reference

This class is a storage for the BeiDou DNAV UTC Model.

```
#include <beidou_dnav_utc_model.h>
```

Public Member Functions

- `template<class Archive>`
void [serialize](#) (Archive &archive, const unsigned int version)

Public Attributes

- double [A0_UTC](#) {}
BDT clock bias relative to UTC [s].
- double [A1_UTC](#) {}
BDT clock rate relative to UTC [s/s].
- int [DeltaT_LS](#) {}
Delta time due to leap seconds before the new leap second effective.
- int [WN_LSF](#) {}
Week number of the new leap second.
- int [DN](#) {}
Day number of week of the new leap second.
- double [DeltaT_LSF](#) {}
Delta time due to leap seconds after the new leap second effective [s].
- double [A0_GPS](#) {}
BDT clock bias relative to GPS time [s].
- double [A1_GPS](#) {}
BDT clock rate relative to GPS time [s/s].
- double [A0_GAL](#) {}
BDT clock bias relative to GAL time [s].
- double [A1_GAL](#) {}
BDT clock rate relative to GAL time [s/s].
- double [A0_GLO](#) {}
BDT clock bias relative to GLO time [s].
- double [A1_GLO](#) {}
BDT clock rate relative to GLO time [s/s].
- bool [valid](#) {}

12.32.1 Detailed Description

This class is a storage for the BeiDou DNAV UTC Model.

Implementation follows the interface described in the Open Service Signal (Version 2.1)

Definition at line 35 of file [beidou_dnav_utc_model.h](#).

12.32.2 Member Function Documentation

12.32.2.1 serialize()

```
template<class Archive>
void Beidou_Dnav_Utc_Model::serialize (
    Archive & archive,
    const unsigned int version) [inline]
```

Definition at line 67 of file [beidou_dnav_utc_model.h](#).

12.32.3 Member Data Documentation

12.32.3.1 A0_GAL

```
double Beidou_Dnav_Utc_Model::A0_GAL {}
```

BDT clock bias relative to GAL time [s].

Definition at line 53 of file [beidou_dnav_utc_model.h](#).

12.32.3.2 A0_GLO

```
double Beidou_Dnav_Utc_Model::A0_GLO {}
```

BDT clock bias relative to GLO time [s].

Definition at line 57 of file [beidou_dnav_utc_model.h](#).

12.32.3.3 A0_GPS

```
double Beidou_Dnav_Utc_Model::A0_GPS {}
```

BDT clock bias relative to GPS time [s].

Definition at line 49 of file [beidou_dnav_utc_model.h](#).

12.32.3.4 A0_UTC

```
double Beidou_Dnav_Utc_Model::A0_UTC {}
```

BDT clock bias relative to UTC [s].

Definition at line 41 of file [beidou_dnav_utc_model.h](#).

12.32.3.5 A1_GAL

```
double Beidou_Dnav_Utc_Model::A1_GAL {}
```

BDT clock rate relative to GAL time [s/s].

Definition at line 54 of file [beidou_dnav_utc_model.h](#).

12.32.3.6 A1_GLO

```
double Beidou_Dnav_Utc_Model::A1_GLO {}
```

BDT clock rate relative to GLO time [s/s].

Definition at line 58 of file [beidou_dnav_utc_model.h](#).

12.32.3.7 A1_GPS

```
double Beidou_Dnav_Utc_Model::A1_GPS {}
```

BDT clock rate relative to GPS time [s/s].

Definition at line 50 of file [beidou_dnav_utc_model.h](#).

12.32.3.8 A1_UTC

```
double Beidou_Dnav_Utc_Model::A1_UTC {}
```

BDT clock rate relative to UTC [s/s].

Definition at line 42 of file [beidou_dnav_utc_model.h](#).

12.32.3.9 DeltaT_LS

```
int Beidou_Dnav_Utc_Model::DeltaT_LS {}
```

Delta time due to leap seconds before the new leap second effective.

Definition at line 43 of file [beidou_dnav_utc_model.h](#).

12.32.3.10 DeltaT_LSF

```
double Beidou_Dnav_Utc_Model::DeltaT_LSF {}
```

Delta time due to leap seconds after the new leap second effective [s].

Definition at line 46 of file [beidou_dnav_utc_model.h](#).

12.32.3.11 DN

```
int Beidou_Dnav_Utc_Model::DN {}
```

Day number of week of the new leap second.

Definition at line 45 of file [beidou_dnav_utc_model.h](#).

12.32.3.12 valid

```
bool Beidou_Dnav_Utc_Model::valid {}
```

Definition at line 60 of file [beidou_dnav_utc_model.h](#).

12.32.3.13 WN_LSF

```
int Beidou_Dnav_Utc_Model::WN_LSF {}
```

Week number of the new leap second.

Definition at line 44 of file [beidou_dnav_utc_model.h](#).

The documentation for this class was generated from the following file:

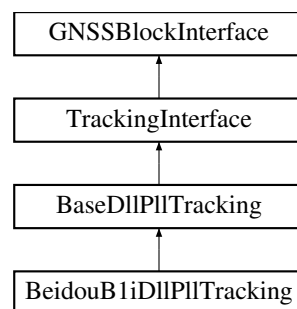
- [beidou_dnav_utc_model.h](#)

12.33 BeidouB1iDIIPITracking Class Reference

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for BeiDou B1I signals.

```
#include <beidou_b1i_dll_pll_tracking.h>
```

Inheritance diagram for BeidouB1iDIIPITracking:

**Public Member Functions**

- [BeidouB1iDIIPITracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "BEIDOU_B1I_DLL_PLL_Tracking".

Public Member Functions inherited from [BaseDIIPITracking](#)

- [BaseDIIPITracking](#) (const [ConfigurationInterface](#) *configuration, std::string [role](#), unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDIIPITracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override final
Get left block from the Tracking block adapter.
- gr::basic_block_sptr [get_right_block](#) () override final
Get right block from the Tracking block adapter.
- void [set_channel](#) (unsigned int channel) override final
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final
Start the Tracking block.
- void [stop_tracking](#) () override final
Stop the Tracking block.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BaseDIIPITracking](#)

- [DII_PII_Conf](#) & [config_params](#) ()
- const [DII_PII_Conf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t [item_size](#))

Protected Attributes inherited from [BaseDIIPITracking](#)

- dll_pll_veml_tracking_sptr [tracking_sptr_](#)

12.33.1 Detailed Description

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for BeiDou B1I signals.

Definition at line 41 of file [beidou_b1i_dll_pll_tracking.h](#).

12.33.2 Constructor & Destructor Documentation

12.33.2.1 BeidouB1iDllPllTracking()

```
BeidouB1iDllPllTracking::BeidouB1iDllPllTracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDllPllTracking::role\(\)](#).

12.33.3 Member Function Documentation

12.33.3.1 implementation()

```
std::string BeidouB1iDllPllTracking::implementation () [inline], [override], [virtual]
```

Returns "BEIDOU_B1I_DLL_PLL_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 51 of file [beidou_b1i_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

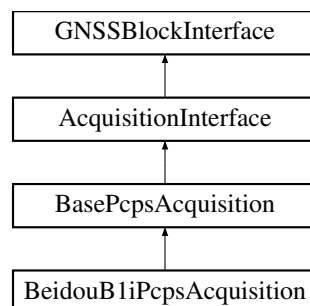
- [beidou_b1i_dll_pll_tracking.h](#)

12.34 BeidouB1iPcpsAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

```
#include <beidou_b1i_pcps_acquisition.h>
```

Inheritance diagram for BeidouB1iPcpsAcquisition:



Public Member Functions

- **BeidouB1iPcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "BEIDOU_B1I_PCPS_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override

- `gr::basic_block_sptr` [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int doppler_center) override
Set Doppler center for the grid search.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t latency_samples) override
Sets the resampler latency to account it in the acquisition code delay estimation.
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual `gr::basic_block_sptr` [get_left_block](#) (int RF_channel)
- virtual `gr::basic_block_sptr` [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

12.34.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.
Definition at line 34 of file [beidou_b1i_pcps_acquisition.h](#).

12.34.2 Member Function Documentation

12.34.2.1 implementation()

```
std::string BeidouB1iPcpsAcquisition::implementation () [inline], [override], [virtual]
```

Returns "BEIDOU_B1I_PCPS_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 46 of file [beidou_b1i_pcps_acquisition.h](#).

The documentation for this class was generated from the following file:

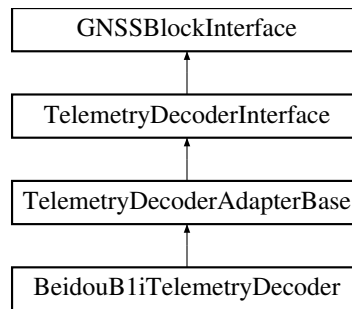
- [beidou_b1i_pcps_acquisition.h](#)

12.35 BeidouB1iTelemetryDecoder Class Reference

This class implements a NAV data decoder for BEIDOU B1I.

```
#include <beidou_b1i_telemetry_decoder.h>
```

Inheritance diagram for BeidouB1iTelemetryDecoder:



Public Member Functions

- **BeidouB1iTelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "BEIDOU_B1I_Telemetry_Decoder".

Public Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- void **InitializeDecoder** (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & **satellite** () const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- [Tlm_Conf](#) tlm_parameters_

12.35.1 Detailed Description

This class implements a NAV data decoder for BEIDOU B1I.
Definition at line 36 of file [beidou_b1i_telemetry_decoder.h](#).

12.35.2 Member Function Documentation

12.35.2.1 implementation()

```
std::string BeidouB1iTelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "BEIDOU_B1i_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 46 of file [beidou_b1i_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

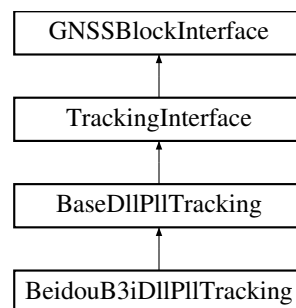
- [beidou_b1i_telemetry_decoder.h](#)

12.36 BeidouB3iDIIPITracking Class Reference

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for BeiDou B3I signals.

```
#include <beidou_b3i_dll_pll_tracking.h>
```

Inheritance diagram for BeidouB3iDIIPITracking:



Public Member Functions

- [BeidouB3iDIIPITracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "BEIDOU_B3I_DLL_PLL_Tracking".

Public Member Functions inherited from [BaseDIIPITracking](#)

- [BaseDIIPITracking](#) (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDIIPITracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override final
Get left block from the Tracking block adapter.
- gr::basic_block_sptr [get_right_block](#) () override final

- *Get right block from the Tracking block adapter.*
void [set_channel](#) (unsigned int channel) override final
- *Set tracking channel unique ID.*
void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final
Start the Tracking block.
- void [stop_tracking](#) () override final
Stop the Tracking block.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BaseDlIPllTracking](#)

- [DlI_Pll_Conf](#) & [config_params](#) ()
- const [DlI_Pll_Conf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t item_size)

Protected Attributes inherited from [BaseDlIPllTracking](#)

- dll_pll_veml_tracking_sptr [tracking_sptr_](#)

12.36.1 Detailed Description

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for BeiDou B3I signals.

Definition at line 41 of file [beidou_b3i_dll_pll_tracking.h](#).

12.36.2 Constructor & Destructor Documentation

12.36.2.1 BeidouB3iDlIPllTracking()

```
BeidouB3iDlIPllTracking::BeidouB3iDlIPllTracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDlIPllTracking::role\(\)](#).

12.36.3 Member Function Documentation

12.36.3.1 implementation()

```
std::string BeidouB3iDlIPllTracking::implementation () [inline], [override], [virtual]
```

Returns "BEIDOU_B3I_DLL_PLL_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 51 of file [beidou_b3i_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

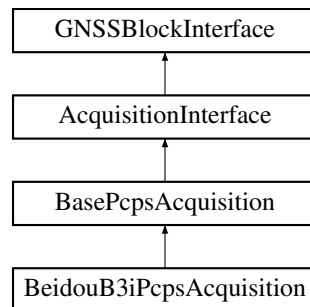
- [beidou_b3i_dll_pll_tracking.h](#)

12.37 BeidouB3iPcpsAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for BeiDou B3I signals.

```
#include <beidou_b3i_pcps_acquisition.h>
```

Inheritance diagram for BeidouB3iPcpsAcquisition:



Public Member Functions

- **BeidouB3iPcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "BEIDOU_B1I_PCPS_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int doppler_center) override
Set Doppler center for the grid search.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t latency_samples) override
Sets the resampler latency to account it in the acquisition code delay estimation.
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.37.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for BeiDou B3I signals.
Definition at line 32 of file [beidou_b3i_pcps_acquisition.h](#).

12.37.2 Member Function Documentation

12.37.2.1 implementation()

```
std::string BeidouB3iPcpsAcquisition::implementation () [inline], [override], [virtual]
```

Returns "BEIDOU_B1I_PCPS_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 44 of file [beidou_b3i_pcps_acquisition.h](#).

The documentation for this class was generated from the following file:

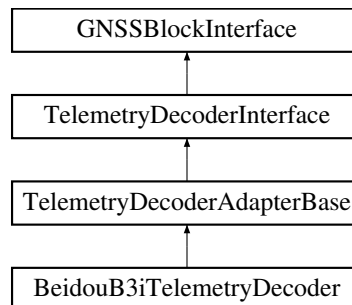
- [beidou_b3i_pcps_acquisition.h](#)

12.38 BeidouB3iTelemetryDecoder Class Reference

This class implements a NAV data decoder for BEIDOU B1I.

```
#include <beidou_b3i_telemetry_decoder.h>
```

Inheritance diagram for BeidouB3iTelemetryDecoder:



Public Member Functions

- **BeidouB3iTelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override

Returns "BEIDOU_B3I_Telemetry_Decoder".

Public Member Functions inherited from TelemetryDecoderAdapterBase

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override

- `std::string` [role](#) () override
- `void` [set_channel](#) (int channel) override
- `void` [reset](#) () override
- `size_t` [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- `virtual` `gr::basic_block_sptr` [get_left_block](#) (int RF_channel)
- `virtual` `gr::basic_block_sptr` [get_right_block](#) (int RF_channel)
- `virtual` `void` [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- `void` [InitializeDecoder](#) (telemetry_impl_interface_sptr decoder)
- `const` [Gnss_Satellite](#) & [satellite](#) () const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- [Tlm_Conf](#) [tlm_parameters_](#)

12.38.1 Detailed Description

This class implements a NAV data decoder for BEIDOU B1I.
Definition at line 35 of file [beidou_b3i_telemetry_decoder.h](#).

12.38.2 Member Function Documentation

12.38.2.1 implementation()

```
std::string BeidouB3iTelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "BEIDOU_B3I_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 44 of file [beidou_b3i_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

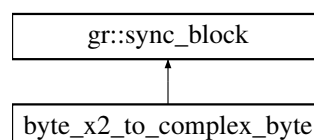
- [beidou_b3i_telemetry_decoder.h](#)

12.39 byte_x2_to_complex_byte Class Reference

This class adapts two signed char streams into a `std::complex<signed char>` stream.

```
#include <byte_x2_to_complex_byte.h>
```

Inheritance diagram for `byte_x2_to_complex_byte`:



Public Member Functions

- `int` [work](#) (int noutput_items, `gr_vector_const_void_star` &input_items, `gr_vector_void_star` &output_items)

Friends

- `byte_x2_to_complex_byte_sptr make_byte_x2_to_complex_byte ()`

12.39.1 Detailed Description

This class adapts two signed char streams into a `std::complex<signed char>` stream.

Definition at line 41 of file [byte_x2_to_complex_byte.h](#).

The documentation for this class was generated from the following file:

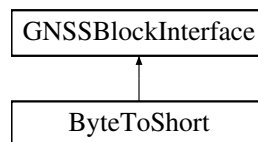
- [byte_x2_to_complex_byte.h](#)

12.40 ByteToShort Class Reference

Adapts an 8-bits sample stream (IF) to a short int stream (IF)

```
#include <byte_to_short.h>
```

Inheritance diagram for ByteToShort:

**Public Member Functions**

- **ByteToShort** (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override
- *Returns "Byte_To_Short".*
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.40.1 Detailed Description

Adapts an 8-bits sample stream (IF) to a short int stream (IF)

Definition at line 40 of file [byte_to_short.h](#).

12.40.2 Member Function Documentation**12.40.2.1 connect()**

```
void ByteToShort::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.40.2.2 disconnect()

```
void ByteToShort::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.40.2.3 get_left_block()

```
gr::basic_block_sptr ByteToShort::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.40.2.4 get_right_block()

```
gr::basic_block_sptr ByteToShort::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.40.2.5 implementation()

```
std::string ByteToShort::implementation () [inline], [override], [virtual]
```

Returns "Byte_To_Short".

Implements [GNSSBlockInterface](#).

Definition at line 55 of file [byte_to_short.h](#).

12.40.2.6 item_size()

```
size_t ByteToShort::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 60 of file [byte_to_short.h](#).

12.40.2.7 role()

```
std::string ByteToShort::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 49 of file [byte_to_short.h](#).

The documentation for this class was generated from the following file:

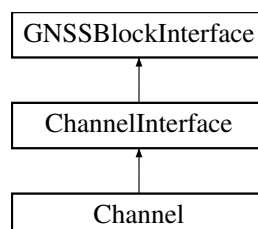
- [byte_to_short.h](#)

12.41 Channel Class Reference

This class represents a GNSS channel. It wraps an [AcquisitionInterface](#), a [TrackingInterface](#) and a [TelemetryDecoderInterface](#), and handles their interaction through a Finite State Machine.

```
#include <channel.h>
```

Inheritance diagram for Channel:



Public Member Functions

- [Channel](#) (const [ConfigurationInterface](#) *configuration, uint32_t channel, std::shared_ptr< [AcquisitionInterface](#) > acq, std::shared_ptr< [TrackingInterface](#) > trk, std::shared_ptr< [TelemetryDecoderInterface](#) > nav, const std::string &role, const std::string &signal_str, [Concurrent_Queue](#)< pmt::pmt_t > *queue)

Constructor.

- `~Channel()`=default

Destructor.

- void `connect` (gr::top_block_sptr top_block) override

Connects the tracking block to the top_block and to the telemetry.

- void `disconnect` (gr::top_block_sptr top_block) override
- gr::basic_block_sptr `get_left_block` () override
- gr::basic_block_sptr `get_left_block_trk` () override

Gets the GNU Radio tracking block input pointer.

- gr::basic_block_sptr `get_right_block_trk` () override

Gets the GNU Radio tracking block output pointer.

- gr::basic_block_sptr `get_left_block_acq` () override
- gr::basic_block_sptr `get_right_block_acq` () override

Gets the GNU Radio acquisition block input pointer.

- gr::basic_block_sptr `get_right_block_acq` () override

Gets the GNU Radio acquisition block output pointer.

- std::string `role` () override
- std::string `implementation` () override

Returns "Channel".

- size_t `item_size` () override
- Gnss_Signal `get_signal` () override
- void `start_acquisition` () override

Start the State Machine.

- void `stop_channel` () override

Stop the State Machine.

- void `set_signal` (const Gnss_Signal &gnss_signal_) override

Sets the channel GNSS signal.

- void `assist_acquisition_doppler` (double Carrier_Doppler_hz) override
- std::shared_ptr< AcquisitionInterface > `acquisition` () const
- std::shared_ptr< TrackingInterface > `tracking` () const
- std::shared_ptr< TelemetryDecoderInterface > `telemetry` () const

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr `get_left_block` (int RF_channel)
- virtual gr::basic_block_sptr `get_right_block` (int RF_channel)
- virtual void `start` ()

Start the flow of samples if needed.

12.41.1 Detailed Description

This class represents a GNSS channel. It wraps an [AcquisitionInterface](#), a [TrackingInterface](#) and a [TelemetryDecoderInterface](#), and handles their interaction through a Finite State Machine. Definition at line 60 of file [channel.h](#).

12.41.2 Constructor & Destructor Documentation

12.41.2.1 Channel()

```
Channel::Channel (
    const ConfigurationInterface * configuration,
    uint32_t channel,
    std::shared_ptr< AcquisitionInterface > acq,
    std::shared_ptr< TrackingInterface > trk,
    std::shared_ptr< TelemetryDecoderInterface > nav,
    const std::string & role,
    const std::string & signal_str,
    Concurrent\_Queue< pmt::pmt_t > * queue)
```

Constructor.

12.41.2.2 ~Channel()

```
Channel::~~Channel () [default]
```

Destructor.

12.41.3 Member Function Documentation

12.41.3.1 acquisition()

```
std::shared_ptr< AcquisitionInterface > Channel::acquisition () const [inline]
```

Definition at line 94 of file [channel.h](#).

12.41.3.2 assist_acquisition_doppler()

```
void Channel::assist_acquisition_doppler (
    double Carrier_Doppler_hz) [override], [virtual]
```

Implements [ChannelInterface](#).

12.41.3.3 connect()

```
void Channel::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Connects the tracking block to the top_block and to the telemetry.

Implements [GNSSBlockInterface](#).

12.41.3.4 disconnect()

```
void Channel::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.41.3.5 get_left_block()

```
gr::basic_block_sptr Channel::get_left_block () [override], [virtual]
```

Implements [ChannelInterface](#).

12.41.3.6 get_left_block_acq()

```
gr::basic_block_sptr Channel::get_left_block_acq () [override], [virtual]
```

Gets the GNU Radio acquisition block input pointer.

Implements [ChannelInterface](#).

12.41.3.7 get_left_block_trk()

```
gr::basic_block_sptr Channel::get_left_block_trk () [override], [virtual]
```

Gets the GNU Radio tracking block input pointer.

Implements [ChannelInterface](#).

12.41.3.8 get_right_block()

```
gr::basic_block_sptr Channel::get_right_block () [override], [virtual]
```

Gets the GNU Radio channel block output pointer.

Implements [ChannelInterface](#).

12.41.3.9 get_right_block_acq()

```
gr::basic_block_sptr Channel::get_right_block_acq () [override], [virtual]
```

Gets the GNU Radio acquisition block output pointer.

Implements [ChannelInterface](#).

12.41.3.10 get_right_block_trk()

```
gr::basic_block_sptr Channel::get_right_block_trk () [override], [virtual]
```

Gets the GNU Radio tracking block output pointer.

Implements [ChannelInterface](#).

12.41.3.11 get_signal()

```
Gnss_Signal Channel::get_signal () [override], [virtual]
```

Implements [ChannelInterface](#).

12.41.3.12 implementation()

```
std::string Channel::implementation () [inline], [override], [virtual]
```

Returns "Channel".

Implements [GNSSBlockInterface](#).

Definition at line 85 of file [channel.h](#).

12.41.3.13 item_size()

```
size_t Channel::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 86 of file [channel.h](#).

12.41.3.14 role()

```
std::string Channel::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 84 of file [channel.h](#).

12.41.3.15 set_signal()

```
void Channel::set_signal (  
    const Gnss_Signal & gnss_signal_) [override], [virtual]
```

Sets the channel GNSS signal.

Implements [ChannelInterface](#).

12.41.3.16 start_acquisition()

```
void Channel::start_acquisition () [override], [virtual]
```

Start the State Machine.

Implements [ChannelInterface](#).

12.41.3.17 stop_channel()

```
void Channel::stop_channel () [override], [virtual]
```

Stop the State Machine.

Implements [ChannelInterface](#).

12.41.3.18 telemetry()

```
std::shared_ptr< TelemetryDecoderInterface > Channel::telemetry () const [inline]
```

Definition at line 96 of file [channel.h](#).

12.41.3.19 tracking()

```
std::shared_ptr< TrackingInterface > Channel::tracking () const [inline]
```

Definition at line 95 of file [channel.h](#).

The documentation for this class was generated from the following file:

- [channel.h](#)

12.42 Channel_Event Class Reference**Public Attributes**

- int [channel_id](#)
- int [event_type](#)

Friends

- [channel_event_sptr](#) **channel_event_make** (int channel_id, int event_type)

12.42.1 Detailed Description

Definition at line 34 of file [channel_event.h](#).

12.42.2 Member Data Documentation**12.42.2.1 channel_id**

```
int Channel_Event::channel_id
```

Definition at line 37 of file [channel_event.h](#).

12.42.2.2 event_type

```
int Channel_Event::event_type
```

Definition at line 38 of file [channel_event.h](#).

The documentation for this class was generated from the following file:

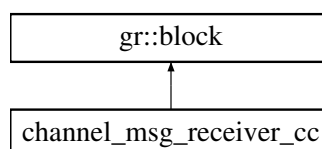
- [channel_event.h](#)

12.43 channel_msg_receiver_cc Class Reference

GNU Radio block that receives asynchronous channel messages from acquisition and tracking blocks.

```
#include <channel_msg_receiver_cc.h>
```

Inheritance diagram for [channel_msg_receiver_cc](#):



Public Member Functions

- [~channel_msg_receiver_cc](#) ()=default

Default destructor.

Friends

- `channel_msg_receiver_cc_sptr` [channel_msg_receiver_make_cc](#) (std::shared_ptr< [ChannelFsm](#) > channel_fsm, bool repeat)

12.43.1 Detailed Description

GNU Radio block that receives asynchronous channel messages from acquisition and tracking blocks.

Definition at line 40 of file [channel_msg_receiver_cc.h](#).

12.43.2 Constructor & Destructor Documentation

12.43.2.1 ~channel_msg_receiver_cc()

```
channel_msg_receiver_cc::~channel_msg_receiver_cc () [default]
```

Default destructor.

The documentation for this class was generated from the following file:

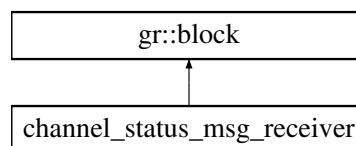
- [channel_msg_receiver_cc.h](#)

12.44 channel_status_msg_receiver Class Reference

GNU Radio block that receives asynchronous channel messages from tlm blocks.

```
#include <channel_status_msg_receiver.h>
```

Inheritance diagram for channel_status_msg_receiver:



Public Member Functions

- [~channel_status_msg_receiver](#) ()=default
Default destructor.
- std::map< int, std::shared_ptr< [Gnss_Synchro](#) > > [get_current_status_map](#) ()
return the current status map of all channels with valid telemetry
- [Monitor_Pvt](#) [get_current_status_pvt](#) ()
return the current receiver PVT

Friends

- `channel_status_msg_receiver_sptr` [channel_status_msg_receiver_make](#) ()

12.44.1 Detailed Description

GNU Radio block that receives asynchronous channel messages from tlm blocks.

Definition at line 44 of file [channel_status_msg_receiver.h](#).

12.44.2 Constructor & Destructor Documentation

12.44.2.1 ~channel_status_msg_receiver()

channel_status_msg_receiver::~~channel_status_msg_receiver () [default]
Default destructor.

12.44.3 Member Function Documentation

12.44.3.1 get_current_status_map()

std::map< int, std::shared_ptr< Gnss_Synchro > > channel_status_msg_receiver::get_current_status_map ()
return the current status map of all channels with valid telemetry

12.44.3.2 get_current_status_pvt()

Monitor_Pvt channel_status_msg_receiver::get_current_status_pvt ()
return the current receiver PVT
The documentation for this class was generated from the following file:

- [channel_status_msg_receiver.h](#)

12.45 ChannelFsm Class Reference

This class implements a State Machine for channel.
#include <channel_fsm.h>

Public Member Functions

- **ChannelFsm** (std::shared_ptr< [AcquisitionInterface](#) > acquisition)
- void **set_acquisition** (std::shared_ptr< [AcquisitionInterface](#) > acquisition)
- void **set_tracking** (std::shared_ptr< [TrackingInterface](#) > tracking)
- void **set_telemetry** (std::shared_ptr< [TelemetryDecoderInterface](#) > telemetry)
- void **set_queue** ([Concurrent_Queue](#)< pmt::pmt_t > *queue)
- void **set_channel** (uint32_t channel)
- void **start_acquisition** ()
- bool **Event_start_acquisition** ()
- bool **Event_start_acquisition_fpga** ()
- bool **Event_stop_channel** ()
- bool **Event_failed_tracking_standby** ()
- virtual bool **Event_valid_acquisition** ()
- virtual bool **Event_failed_acquisition_repeat** ()
- virtual bool **Event_failed_acquisition_no_repeat** ()

12.45.1 Detailed Description

This class implements a State Machine for channel.
Definition at line 41 of file [channel_fsm.h](#).
The documentation for this class was generated from the following file:

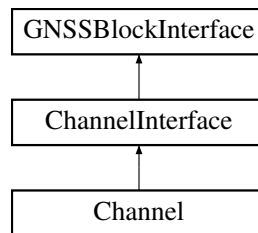
- [channel_fsm.h](#)

12.46 ChannelInterface Class Reference

This abstract class represents an interface to a channel GNSS block.

```
#include <channel_interface.h>
```

Inheritance diagram for ChannelInterface:



Public Member Functions

- virtual gr::basic_block_sptr [get_left_block_trk](#) ()=0
- virtual gr::basic_block_sptr [get_right_block_trk](#) ()=0
- virtual gr::basic_block_sptr [get_left_block_acq](#) ()=0
- virtual gr::basic_block_sptr [get_right_block_acq](#) ()=0
- virtual gr::basic_block_sptr [get_left_block](#) ()=0
- virtual gr::basic_block_sptr [get_right_block](#) ()=0
- virtual [Gnss_Signal](#) [get_signal](#) ()=0
- virtual void [start_acquisition](#) ()=0
- virtual void [assist_acquisition_doppler](#) (double Carrier_Doppler_hz)=0
- virtual void [stop_channel](#) ()=0
- virtual void [set_signal](#) (const [Gnss_Signal](#) &)=0

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual std::string [role](#) ()=0
- virtual std::string [implementation](#) ()=0
- virtual size_t [item_size](#) ()=0
- virtual void [connect](#) (gr::top_block_sptr top_block)=0
- virtual void [disconnect](#) (gr::top_block_sptr top_block)=0
- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.46.1 Detailed Description

This abstract class represents an interface to a channel GNSS block.

Abstract class for channel blocks. Since all its methods are pure virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

Definition at line 43 of file [channel_interface.h](#).

12.46.2 Member Function Documentation

12.46.2.1 [get_left_block\(\)](#)

```
virtual gr::basic_block_sptr ChannelInterface::get_left_block () [pure virtual]
```

Implements [GNSSBlockInterface](#).

12.46.2.2 get_left_block_acq()

virtual gr::basic_block_sptr ChannelInterface::get_left_block_acq () [pure virtual]
 Implemented in [Channel](#).

12.46.2.3 get_left_block_trk()

virtual gr::basic_block_sptr ChannelInterface::get_left_block_trk () [pure virtual]
 Implemented in [Channel](#).

12.46.2.4 get_right_block()

virtual gr::basic_block_sptr ChannelInterface::get_right_block () [pure virtual]
 Implements [GNSSBlockInterface](#).
 Implemented in [Channel](#).

12.46.2.5 get_right_block_acq()

virtual gr::basic_block_sptr ChannelInterface::get_right_block_acq () [pure virtual]
 Implemented in [Channel](#).

12.46.2.6 get_right_block_trk()

virtual gr::basic_block_sptr ChannelInterface::get_right_block_trk () [pure virtual]
 Implemented in [Channel](#).

12.46.2.7 set_signal()

virtual void ChannelInterface::set_signal (
 const [Gnss_Signal](#) &) [pure virtual]
 Implemented in [Channel](#).

12.46.2.8 start_acquisition()

virtual void ChannelInterface::start_acquisition () [pure virtual]
 Implemented in [Channel](#).

12.46.2.9 stop_channel()

virtual void ChannelInterface::stop_channel () [pure virtual]
 Implemented in [Channel](#).

The documentation for this class was generated from the following file:

- [channel_interface.h](#)

12.47 cl_fft_plan Struct Reference**Public Attributes**

- cl_context [context](#)
- clFFT_Dim3 [n](#)
- clFFT_Dimension [dim](#)
- clFFT_DataFormat [format](#)
- string * [kernel_string](#)
- cl_program [program](#)
- [cl_fft_kernel_info](#) * [kernel_info](#)
- int [num_kernels](#)
- cl_kernel [twist_kernel](#)
- cl_int [temp_buffer_needed](#)

- unsigned [last_batch_size](#)
- cl_mem [tempmemobj](#)
- cl_mem [tempmemobj_real](#)
- cl_mem [tempmemobj_imag](#)
- unsigned [max_localmem_fft_size](#)
- unsigned [max_work_item_per_workgroup](#)
- unsigned [max_radix](#)
- unsigned [min_mem_coalesce_width](#)
- unsigned [num_local_mem_banks](#)

12.47.1 Detailed Description

Definition at line 45 of file [fft_internal.h](#).

12.47.2 Member Data Documentation

12.47.2.1 context

`cl_context cl_fft_plan::context`

Definition at line 48 of file [fft_internal.h](#).

12.47.2.2 dim

`clFFT_Dimension cl_fft_plan::dim`

Definition at line 54 of file [fft_internal.h](#).

12.47.2.3 format

`clFFT_DataFormat cl_fft_plan::format`

Definition at line 57 of file [fft_internal.h](#).

12.47.2.4 kernel_info

`cl_fft_kernel_info* cl_fft_plan::kernel_info`

Definition at line 68 of file [fft_internal.h](#).

12.47.2.5 kernel_string

`string* cl_fft_plan::kernel_string`

Definition at line 61 of file [fft_internal.h](#).

12.47.2.6 last_batch_size

`unsigned cl_fft_plan::last_batch_size`

Definition at line 93 of file [fft_internal.h](#).

12.47.2.7 max_localmem_fft_size

`unsigned cl_fft_plan::max_localmem_fft_size`

Definition at line 106 of file [fft_internal.h](#).

12.47.2.8 max_radix

`unsigned cl_fft_plan::max_radix`

Definition at line 114 of file [fft_internal.h](#).

12.47.2.9 max_work_item_per_workgroup

`unsigned cl_fft_plan::max_work_item_per_workgroup`

Definition at line 110 of file [fft_internal.h](#).

12.47.2.10 min_mem_coalesce_width

unsigned cl_fft_plan::min_mem_coalesce_width
Definition at line 119 of file [fft_internal.h](#).

12.47.2.11 n

clFFT_Dim3 cl_fft_plan::n
Definition at line 51 of file [fft_internal.h](#).

12.47.2.12 num_kernels

int cl_fft_plan::num_kernels
Definition at line 71 of file [fft_internal.h](#).

12.47.2.13 num_local_mem_banks

unsigned cl_fft_plan::num_local_mem_banks
Definition at line 124 of file [fft_internal.h](#).

12.47.2.14 program

cl_program cl_fft_plan::program
Definition at line 65 of file [fft_internal.h](#).

12.47.2.15 temp_buffer_needed

cl_int cl_fft_plan::temp_buffer_needed
Definition at line 84 of file [fft_internal.h](#).

12.47.2.16 tempmemobj

cl_mem cl_fft_plan::tempmemobj
Definition at line 96 of file [fft_internal.h](#).

12.47.2.17 tempmemobj_imag

cl_mem cl_fft_plan::tempmemobj_imag
Definition at line 101 of file [fft_internal.h](#).

12.47.2.18 tempmemobj_real

cl_mem cl_fft_plan::tempmemobj_real
Definition at line 101 of file [fft_internal.h](#).

12.47.2.19 twist_kernel

cl_kernel cl_fft_plan::twist_kernel
Definition at line 75 of file [fft_internal.h](#).
The documentation for this struct was generated from the following file:

- [fft_internal.h](#)

12.48 clFFT_Complex Struct Reference

Public Attributes

- float [real](#)
- float [imag](#)

12.48.1 Detailed Description

Definition at line 65 of file [cIFFT.h](#).

12.48.2 Member Data Documentation

12.48.2.1 imag

```
float cIFFT_Complex::imag
```

Definition at line 68 of file [cIFFT.h](#).

12.48.2.2 real

```
float cIFFT_Complex::real
```

Definition at line 67 of file [cIFFT.h](#).

The documentation for this struct was generated from the following file:

- [cIFFT.h](#)

12.49 cIFFT_Dim3 Struct Reference

Public Attributes

- unsigned int [x](#)
- unsigned int [y](#)
- unsigned int [z](#)

12.49.1 Detailed Description

Definition at line 52 of file [cIFFT.h](#).

12.49.2 Member Data Documentation

12.49.2.1 x

```
unsigned int cIFFT_Dim3::x
```

Definition at line 54 of file [cIFFT.h](#).

12.49.2.2 y

```
unsigned int cIFFT_Dim3::y
```

Definition at line 55 of file [cIFFT.h](#).

12.49.2.3 z

```
unsigned int cIFFT_Dim3::z
```

Definition at line 56 of file [cIFFT.h](#).

The documentation for this struct was generated from the following file:

- [cIFFT.h](#)

12.50 cIFFT_SplitComplex Struct Reference

Public Attributes

- float * [real](#)
- float * [imag](#)

12.50.1 Detailed Description

Definition at line 59 of file [clFFT.h](#).

12.50.2 Member Data Documentation

12.50.2.1 `imag`

`float* clFFT_SplitComplex::imag`

Definition at line 62 of file [clFFT.h](#).

12.50.2.2 `real`

`float* clFFT_SplitComplex::real`

Definition at line 61 of file [clFFT.h](#).

The documentation for this struct was generated from the following file:

- [clFFT.h](#)

12.51 `cnav_msg_decoder_t` Struct Reference

```
#include <cnav_msg.h>
```

Public Attributes

- [cnav_v27_part_t](#) `part1`
- [cnav_v27_part_t](#) `part2`

12.51.1 Detailed Description

GPS CNAV message lock and decoder object.

Decoder uses two Viterbi decoder objects to ensure the lock is acquired when the input symbol phase is not known.

Definition at line 95 of file [cnav_msg.h](#).

12.51.2 Member Data Documentation

12.51.2.1 `part1`

[cnav_v27_part_t](#) `cnav_msg_decoder_t::part1`

Decoder for odd symbol pairs

Definition at line 97 of file [cnav_msg.h](#).

12.51.2.2 `part2`

[cnav_v27_part_t](#) `cnav_msg_decoder_t::part2`

Decoder for even symbol pairs

Definition at line 98 of file [cnav_msg.h](#).

The documentation for this struct was generated from the following file:

- [cnav_msg.h](#)

12.52 `cnav_msg_t` Struct Reference

```
#include <cnav_msg.h>
```

Public Attributes

- uint8_t [prn](#)
- uint8_t [msg_id](#)
- uint32_t [tow](#)
- bool [alert](#)
- uint8_t [raw_msg](#) [[GPS_L2C_V27_DECODE_BITS](#)+[GPS_L2C_V27_DELAY_BITS](#)]

12.52.1 Detailed Description

GPS CNAV message container.

See also

[cnav_msg_decoder_add_symbol](#)

Definition at line [52](#) of file [cnav_msg.h](#).

12.52.2 Member Data Documentation

12.52.2.1 alert

`bool cnav_msg_t::alert`
CNAV message alert flag
Definition at line [57](#) of file [cnav_msg.h](#).

12.52.2.2 msg_id

`uint8_t cnav_msg_t::msg_id`
Message id. 0..31
Definition at line [55](#) of file [cnav_msg.h](#).

12.52.2.3 prn

`uint8_t cnav_msg_t::prn`
SV PRN. 0..31
Definition at line [54](#) of file [cnav_msg.h](#).

12.52.2.4 raw_msg

`uint8_t cnav_msg_t::raw_msg` [[GPS_L2C_V27_DECODE_BITS](#)+[GPS_L2C_V27_DELAY_BITS](#)]
RAW MSG for GNSS-SDR
Definition at line [58](#) of file [cnav_msg.h](#).

12.52.2.5 tow

`uint32_t cnav_msg_t::tow`
GPS ToW in 6-second units. Multiply to 6 to get seconds.
Definition at line [56](#) of file [cnav_msg.h](#).
The documentation for this struct was generated from the following file:

- [cnav_msg.h](#)

12.53 cnav_v27_part_t Struct Reference

```
#include <cnav_msg.h>
```

Public Attributes

- [v27_t dec](#)
- [v27_decision_t decisions](#) [[GPS_L2_V27_HISTORY_LENGTH_BITS](#)]
- unsigned char [symbols](#) [([GPS_L2C_V27_INIT_BITS](#)+[GPS_L2C_V27_DECODE_BITS](#)) *2]
- size_t [n_symbols](#)
- unsigned char [decoded](#) [[GPS_L2C_V27_DECODE_BITS](#)+[GPS_L2C_V27_DELAY_BITS](#)]
- size_t [n_decoded](#)
- bool [preamble_seen](#)
- bool [invert](#)
- bool [message_lock](#)
- bool [crc_ok](#)
- size_t [n_crc_fail](#)
- bool [init](#)

12.53.1 Detailed Description

GPS CNAV decoder component. This component controls symbol decoding string.

See also

[cnav_msg_decoder_t](#)

Definition at line 67 of file [cnav_msg.h](#).

12.53.2 Member Data Documentation

12.53.2.1 `crc_ok`

```
bool cnav_v27_part_t::crc_ok
```

Flag that the last message had good CRC

Definition at line 83 of file [cnav_msg.h](#).

12.53.2.2 `dec`

```
v27_t cnav_v27_part_t::dec
```

Viterbi block decoder object

Definition at line 69 of file [cnav_msg.h](#).

12.53.2.3 `decisions`

```
v27_decision_t cnav_v27_part_t::decisions[GPS_L2_V27_HISTORY_LENGTH_BITS]
```

Decision graph

Definition at line 70 of file [cnav_msg.h](#).

12.53.2.4 `decoded`

```
unsigned char cnav_v27_part_t::decoded[GPS_L2C_V27_DECODE_BITS+GPS_L2C_V27_DELAY_BITS]
```

Decode buffer

Definition at line 75 of file [cnav_msg.h](#).

12.53.2.5 `init`

```
bool cnav_v27_part_t::init
```

Initial state flag. When true, initial bits do not produce output.

Definition at line 85 of file [cnav_msg.h](#).

12.53.2.6 `invert`

```
bool cnav_v27_part_t::invert
```

When true, indicates the bits are inverted

Definition at line 80 of file [cnav_msg.h](#).

12.53.2.7 message_lock

```
bool cnav_v27_part_t::message_lock
```

When true, indicates the message boundary is found.

Definition at line 81 of file [cnav_msg.h](#).

12.53.2.8 n_crc_fail

```
size_t cnav_v27_part_t::n_crc_fail
```

Counter for CRC failures

Definition at line 84 of file [cnav_msg.h](#).

12.53.2.9 n_decoded

```
size_t cnav_v27_part_t::n_decoded
```

Number of bits in the decode buffer

Definition at line 77 of file [cnav_msg.h](#).

12.53.2.10 n_symbols

```
size_t cnav_v27_part_t::n_symbols
```

Count of symbols in the symbol buffer

Definition at line 74 of file [cnav_msg.h](#).

12.53.2.11 preamble_seen

```
bool cnav_v27_part_t::preamble_seen
```

When true, the decode buffer is aligned on preamble.

Definition at line 78 of file [cnav_msg.h](#).

12.53.2.12 symbols

```
unsigned char cnav_v27_part_t::symbols[(GPS_L2C_V27_INIT_BITS+GPS_L2C_V27_DECODE_BITS) *2]
```

Symbol buffer

Definition at line 72 of file [cnav_msg.h](#).

The documentation for this struct was generated from the following file:

- [cnav_msg.h](#)

12.54 Command_Event Class Reference

Public Attributes

- int [command_id](#)
- int [event_type](#)

Friends

- [command_event_sptr](#) **command_event_make** (int command_id, int event_type)

12.54.1 Detailed Description

Definition at line 34 of file [command_event.h](#).

12.54.2 Member Data Documentation

12.54.2.1 command_id

```
int Command_Event::command_id
```

Definition at line 37 of file [command_event.h](#).

12.54.2.2 event_type

`int Command_Event::event_type`

Definition at line 38 of file [command_event.h](#).

The documentation for this class was generated from the following file:

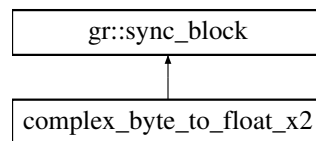
- [command_event.h](#)

12.55 complex_byte_to_float_x2 Class Reference

This class adapts a `std::complex<signed char>` stream into two 16-bits (short) streams.

`#include <complex_byte_to_float_x2.h>`

Inheritance diagram for `complex_byte_to_float_x2`:



Public Member Functions

- `int work` (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- `complex_byte_to_float_x2_sptr make_complex_byte_to_float_x2` ()

12.55.1 Detailed Description

This class adapts a `std::complex<signed char>` stream into two 16-bits (short) streams.

Definition at line 41 of file [complex_byte_to_float_x2.h](#).

The documentation for this class was generated from the following file:

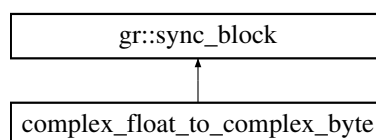
- [complex_byte_to_float_x2.h](#)

12.56 complex_float_to_complex_byte Class Reference

This class adapts a `gr_complex` stream into a `std::complex<signed char>` stream.

`#include <complex_float_to_complex_byte.h>`

Inheritance diagram for `complex_float_to_complex_byte`:



Public Member Functions

- `int work` (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- `complex_float_to_complex_byte_sptr make_complex_float_to_complex_byte` ()

12.56.1 Detailed Description

This class adapts a `gr_complex` stream into a `std::complex<signed char>` stream.

Definition at line 40 of file [complex_float_to_complex_byte.h](#).

The documentation for this class was generated from the following file:

- [complex_float_to_complex_byte.h](#)

12.57 Concurrent_Map< Data > Class Template Reference

This class implements a thread-safe `std::map`.

#include <concurrent_map.h>

Public Member Functions

- void [write](#) (int key, Data const &data)
- `std::map< int, Data >` [get_map_copy](#) () const &
- `std::map< int, Data >` [get_map_copy](#) () &&
- `size_t` [size](#) () const
- bool [read](#) (int key, Data &p_data) const

12.57.1 Detailed Description

template<typename Data>

class Concurrent_Map< Data >

This class implements a thread-safe `std::map`.

Definition at line 37 of file [concurrent_map.h](#).

12.57.2 Member Function Documentation

12.57.2.1 [get_map_copy\(\)](#) [1/2]

template<typename Data>

`std::map< int, Data >` [Concurrent_Map< Data >::get_map_copy](#) () && [inline]

Definition at line 60 of file [concurrent_map.h](#).

12.57.2.2 [get_map_copy\(\)](#) [2/2]

template<typename Data>

`std::map< int, Data >` [Concurrent_Map< Data >::get_map_copy](#) () const & [inline]

Definition at line 54 of file [concurrent_map.h](#).

12.57.2.3 [read\(\)](#)

template<typename Data>

```
bool Concurrent\_Map< Data >::read (
    int key,
    Data & p_data) const [inline]
```

Definition at line 72 of file [concurrent_map.h](#).

12.57.2.4 [size\(\)](#)

template<typename Data>

`size_t` [Concurrent_Map< Data >::size](#) () const [inline]

Definition at line 66 of file [concurrent_map.h](#).

12.57.2.5 write()

```
template<typename Data>
void Concurrent_Map< Data >::write (
    int key,
    Data const & data) [inline]
```

Definition at line 40 of file [concurrent_map.h](#).

The documentation for this class was generated from the following file:

- [concurrent_map.h](#)

12.58 Concurrent_Queue< Data > Class Template Reference

This class implements a thread-safe `std::queue`.

```
#include <concurrent_queue.h>
```

Public Member Functions

- void [push](#) (const Data &data)
- void [push](#) (Data &&data)
- bool [empty](#) () const noexcept
- size_t [size](#) () const noexcept
- void [clear](#) ()
- bool [try_pop](#) (Data &popped_value)
- void [wait_and_pop](#) (Data &popped_value)
- bool [timed_wait_and_pop](#) (Data &popped_value, int wait_ms)

12.58.1 Detailed Description

```
template<typename Data>
class Concurrent_Queue< Data >
```

This class implements a thread-safe `std::queue`.

Definition at line 38 of file [concurrent_queue.h](#).

12.58.2 Member Function Documentation

12.58.2.1 clear()

```
template<typename Data>
void Concurrent_Queue< Data >::clear () [inline]
```

Definition at line 70 of file [concurrent_queue.h](#).

12.58.2.2 empty()

```
template<typename Data>
bool Concurrent_Queue< Data >::empty () const [inline], [noexcept]
```

Definition at line 59 of file [concurrent_queue.h](#).

12.58.2.3 push() [1/2]

```
template<typename Data>
void Concurrent_Queue< Data >::push (
    const Data & data) [inline]
```

Definition at line 41 of file [concurrent_queue.h](#).

12.58.2.4 push() [2/2]

```
template<typename Data>
void Concurrent_Queue< Data >::push (
    Data && data) [inline]
```

Definition at line 50 of file [concurrent_queue.h](#).

12.58.2.5 size()

```
template<typename Data>
size_t Concurrent_Queue< Data >::size () const [inline], [noexcept]
```

Definition at line 64 of file [concurrent_queue.h](#).

12.58.2.6 timed_wait_and_pop()

```
template<typename Data>
bool Concurrent_Queue< Data >::timed_wait_and_pop (
    Data & popped_value,
    int wait_ms) [inline]
```

Definition at line 96 of file [concurrent_queue.h](#).

12.58.2.7 try_pop()

```
template<typename Data>
bool Concurrent_Queue< Data >::try_pop (
    Data & popped_value) [inline]
```

Definition at line 76 of file [concurrent_queue.h](#).

12.58.2.8 wait_and_pop()

```
template<typename Data>
void Concurrent_Queue< Data >::wait_and_pop (
    Data & popped_value) [inline]
```

Definition at line 88 of file [concurrent_queue.h](#).

The documentation for this class was generated from the following files:

- [acquisition_interface.h](#)
- [concurrent_queue.h](#)

12.59 HistogramBitSynchronizer::Config Struct Reference

Configuration parameters for [HistogramBitSynchronizer](#).

```
#include <bit_synchronizer.h>
```

Public Attributes

- int [bit_period_ms](#)
Navigation data bit period in milliseconds.
- int [epoch_ms](#)
Time interval between successive calls to [update\(\)](#), in milliseconds.
- int [min_events_for_lock](#)
Minimum number of detected transition events required before lock evaluation.
- double [dominance_ratio](#)
Required dominance ratio of the winning histogram bin.
- int [stable_best_required](#)
Required stability of the dominant histogram bin (consecutive evaluations).
- float [min_prompt_mag](#)

Minimum magnitude of the prompt correlator output.

- bool [use_phase_dot_detector](#)

Select the transition detection method.

12.59.1 Detailed Description

Configuration parameters for [HistogramBitSynchronizer](#).

These parameters define the bit period, the update cadence, the lock criteria, and the transition detection method. Definition at line 43 of file [bit_synchronizer.h](#).

12.59.2 Constructor & Destructor Documentation

12.59.2.1 Config()

```
HistogramBitSynchronizer::Config::Config () [inline]
```

Definition at line 128 of file [bit_synchronizer.h](#).

12.59.3 Member Data Documentation

12.59.3.1 bit_period_ms

```
int HistogramBitSynchronizer::Config::bit_period_ms
```

Navigation data bit period in milliseconds.

This is the nominal duration of one navigation data bit.

Definition at line 50 of file [bit_synchronizer.h](#).

12.59.3.2 dominance_ratio

```
double HistogramBitSynchronizer::Config::dominance_ratio
```

Required dominance ratio of the winning histogram bin.

Lock requires the most frequent histogram bin to be sufficiently dominant:

$$\text{dominance_ratio} = \frac{\text{best_bin_count}}{\text{total_detected_events}}$$

Guidance:

- Values near 0.5 may lock faster but increase false-lock probability.
- Values closer to 1.0 are conservative and require a clearly dominant phase.

Definition at line 84 of file [bit_synchronizer.h](#).

12.59.3.3 epoch_ms

```
int HistogramBitSynchronizer::Config::epoch_ms
```

Time interval between successive calls to [update\(\)](#), in milliseconds.

This should match the minimum integration interval (epoch) produced by the tracking loop and used to generate the provided prompt correlator output.

Definition at line 58 of file [bit_synchronizer.h](#).

12.59.3.4 min_events_for_lock

```
int HistogramBitSynchronizer::Config::min_events_for_lock
```

Minimum number of detected transition events required before lock evaluation.

The histogram is built from detected candidate transitions. Lock decisions are not attempted until at least this many events have been accumulated.

Trade-offs:

- Larger values increase robustness against false locks but increase time-to-lock.
- Smaller values reduce time-to-lock but increase sensitivity to noise/spurious transitions.

Definition at line 70 of file [bit_synchronizer.h](#).

12.59.3.5 min_prompt_mag

```
float HistogramBitSynchronizer::Config::min_prompt_mag
```

Minimum magnitude of the prompt correlator output.

Candidate transition detection is suppressed when $|P| < \text{min_prompt_mag}$, where P is the prompt correlator output.

Use this to avoid counting unreliable transitions when tracking quality is poor or the prompt output is dominated by noise.

Definition at line 105 of file [bit_synchronizer.h](#).

12.59.3.6 stable_best_required

```
int HistogramBitSynchronizer::Config::stable_best_required
```

Required stability of the dominant histogram bin (consecutive evaluations).

Even if the dominance ratio is met, the algorithm requires that the same histogram bin remains dominant for this many consecutive lock evaluations before declaring lock.

This helps prevent locking on transient peaks caused by noise or short-lived disturbances.

Definition at line 94 of file [bit_synchronizer.h](#).

12.59.3.7 use_phase_dot_detector

```
bool HistogramBitSynchronizer::Config::use_phase_dot_detector
```

Select the transition detection method.

If true (recommended), uses a “phase-dot” detector:

- A candidate transition is detected when:

$$\Re\{P_k \cdot P_{k-1}^*\} < 0$$

where P_k is the current prompt and P_{k-1}^* the conjugate of the previous.

This method is largely insensitive to constant carrier phase rotations and is often more robust during early tracking / imperfect carrier phase alignment.

If false, uses a simpler sign-change detector on the real part:

- A candidate transition is detected when $\text{sign}(\text{Re}(P_k)) \neq \text{sign}(\text{Re}(P_{k-1}))$.

This assumes the prompt output is already aligned with the data bit polarity (i.e., stable PLL lock and correct navigation bit polarity mapping).

Definition at line 126 of file [bit_synchronizer.h](#).

The documentation for this struct was generated from the following file:

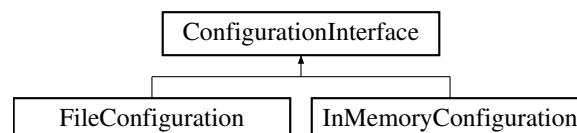
- [bit_synchronizer.h](#)

12.60 ConfigurationInterface Class Reference

This abstract class represents an interface to configuration parameters.

```
#include <configuration_interface.h>
```

Inheritance diagram for ConfigurationInterface:



Public Member Functions

- virtual std::string **property** (std::string property_name, std::string default_value) const =0
- virtual bool **property** (std::string property_name, bool default_value) const =0
- virtual int64_t **property** (std::string property_name, int64_t default_value) const =0

- virtual uint64_t **property** (std::string property_name, uint64_t default_value) const =0
- virtual int32_t **property** (std::string property_name, int32_t default_value) const =0
- virtual uint32_t **property** (std::string property_name, uint32_t default_value) const =0
- virtual int16_t **property** (std::string property_name, int16_t default_value) const =0
- virtual uint16_t **property** (std::string property_name, uint16_t default_value) const =0
- virtual float **property** (std::string property_name, float default_value) const =0
- virtual double **property** (std::string property_name, double default_value) const =0
- virtual void **set_property** (std::string property_name, std::string value)=0
- virtual bool **is_present** (const std::string &property_name) const =0

12.60.1 Detailed Description

This abstract class represents an interface to configuration parameters.

The interface defines an accessor method that gets a parameter name as input and returns the value of this parameter, a string, as output. Property names are defined here. This is an abstract class for interfaces. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

Definition at line 44 of file [configuration_interface.h](#).

The documentation for this class was generated from the following file:

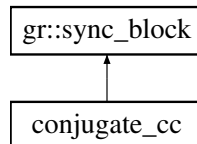
- [configuration_interface.h](#)

12.61 conjugate_cc Class Reference

This class adapts a std::complex<short> stream into two 32-bits (float) streams.

```
#include <conjugate_cc.h>
```

Inheritance diagram for conjugate_cc:



Public Member Functions

- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- conjugate_cc_sptr **make_conjugate_cc** ()

12.61.1 Detailed Description

This class adapts a std::complex<short> stream into two 32-bits (float) streams.

Definition at line 41 of file [conjugate_cc.h](#).

The documentation for this class was generated from the following file:

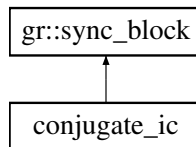
- [conjugate_cc.h](#)

12.62 conjugate_ic Class Reference

This class adapts a std::complex<short> stream into two 32-bits (float) streams.

```
#include <conjugate_ic.h>
```

Inheritance diagram for conjugate_ic:



Public Member Functions

- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- conjugate_ic_sptr **make_conjugate_ic** ()

12.62.1 Detailed Description

This class adapts a `std::complex<short>` stream into two 32-bits (float) streams.

Definition at line 41 of file [conjugate_ic.h](#).

The documentation for this class was generated from the following file:

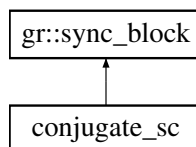
- [conjugate_ic.h](#)

12.63 conjugate_sc Class Reference

This class adapts a `std::complex<short>` stream into two 32-bits (float) streams.

`#include <conjugate_sc.h>`

Inheritance diagram for conjugate_sc:



Public Member Functions

- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- conjugate_sc_sptr **make_conjugate_sc** ()

12.63.1 Detailed Description

This class adapts a `std::complex<short>` stream into two 32-bits (float) streams.

Definition at line 41 of file [conjugate_sc.h](#).

The documentation for this class was generated from the following file:

- [conjugate_sc.h](#)

12.64 ControlThread Class Reference

This class represents the main thread of the application, so the name is [ControlThread](#). This is the GNSS Receiver Control Plane: it connects the flowgraph, starts running it, and while it does not stop, reads the control messages generated by the blocks, processes them, and applies the corresponding actions.

`#include <control_thread.h>`

Public Member Functions

- [ControlThread](#) ()
Default constructor.
- [ControlThread](#) (std::shared_ptr< [ConfigurationInterface](#) > configuration)
Constructor that initializes the class with parameters.
- [~ControlThread](#) ()
Destructor.
- int [run](#) ()
Runs the control thread.
- void [set_control_queue](#) (std::shared_ptr< [Concurrent_Queue](#)< pmt::pmt_t > > control_queue)
Sets the control_queue.
- unsigned int [processed_control_messages](#) () const
- unsigned int [applied_actions](#) () const
- std::shared_ptr< [GNSSFlowgraph](#) > [flowgraph](#) ()
Instantiates a flowgraph.

Static Public Attributes

- static [ControlThread](#) * [me](#)

12.64.1 Detailed Description

This class represents the main thread of the application, so the name is [ControlThread](#). This is the GNSS Receiver Control Plane: it connects the flowgraph, starts running it, and while it does not stop, reads the control messages generated by the blocks, processes them, and applies the corresponding actions.

Definition at line 64 of file [control_thread.h](#).

12.64.2 Constructor & Destructor Documentation

12.64.2.1 [ControlThread\(\)](#) [1/2]

```
ControlThread::ControlThread ()
```

Default constructor.

12.64.2.2 [ControlThread\(\)](#) [2/2]

```
ControlThread::ControlThread (
    std::shared_ptr< ConfigurationInterface > configuration) [explicit]
```

Constructor that initializes the class with parameters.

Parameters

in	<i>configuration</i>	Pointer to a ConfigurationInterface
----	----------------------	---

12.64.2.3 [~ControlThread\(\)](#)

```
ControlThread::~ControlThread ()
```

Destructor.

12.64.3 Member Function Documentation

12.64.3.1 [applied_actions\(\)](#)

```
unsigned int ControlThread::applied_actions () const [inline]
```

Definition at line 111 of file [control_thread.h](#).

12.64.3.2 flowgraph()

`std::shared_ptr< GNSSFlowgraph > ControlThread::flowgraph () [inline]`
 Instantiates a flowgraph.

Returns

Returns a smart pointer to a flowgraph object

Definition at line 121 of file [control_thread.h](#).

12.64.3.3 processed_control_messages()

`unsigned int ControlThread::processed_control_messages () const [inline]`
 Definition at line 106 of file [control_thread.h](#).

12.64.3.4 run()

`int ControlThread::run ()`

Runs the control thread.

This is the main loop that reads and process the control messages:

- Connect the GNSS receiver flowgraph;
- Start the GNSS receiver flowgraph;

while (flowgraph_->running() && !stop_){

- Read control messages and process them; }

12.64.3.5 set_control_queue()

`void ControlThread::set_control_queue (`
 `std::shared_ptr< Concurrent_Queue< pmt::pmt_t > > control_queue)`

Sets the control_queue.

Parameters

in	<code>std::shared_ptr<Concurrent_Queue<pmt::pmt_t>></code>	<code>control_queue</code>
----	--	----------------------------

12.64.4 Member Data Documentation

12.64.4.1 me

`ControlThread* ControlThread::me [static]`

Definition at line 67 of file [control_thread.h](#).

The documentation for this class was generated from the following file:

- [control_thread.h](#)

12.65 Cpu_Multicorrelator Class Reference

Class that implements carrier wipe-off and correlators.

`#include <cpu_multicorrelator.h>`

Public Member Functions

- bool **init** (int max_signal_length_samples, int n_correlators)
- bool **set_local_code_and_taps** (int code_length_chips, const std::complex< float > *local_code_in, float *shifts_chips)
- bool **set_input_output_vectors** (std::complex< float > *corr_out, const std::complex< float > *sig_in)
- void **update_local_code** (int correlator_length_samples, float rem_code_phase_chips, float code_phase_step_chips)
- bool **Carrier_wipeoff_multicorrelator_resampler** (float rem_carrier_phase_in_rad, float phase_step_rad, float rem_code_phase_chips, float code_phase_step_chips, int signal_length_samples)
- bool **free** ()

12.65.1 Detailed Description

Class that implements carrier wipe-off and correlators.

Definition at line 37 of file [cpu_multicorrelator.h](#).

The documentation for this class was generated from the following file:

- [cpu_multicorrelator.h](#)

12.66 Cpu_Multicorrelator_16sc Class Reference

Class that implements carrier wipe-off and correlators.

#include <cpu_multicorrelator_16sc.h>

Public Member Functions

- bool **init** (int max_signal_length_samples, int n_correlators)
- bool **set_local_code_and_taps** (int code_length_chips, const lv_16sc_t *local_code_in, float *shifts_chips)
- bool **set_input_output_vectors** (lv_16sc_t *corr_out, const lv_16sc_t *sig_in)
- void **update_local_code** (int correlator_length_samples, float rem_code_phase_chips, float code_phase_step_chips)
- bool **Carrier_wipeoff_multicorrelator_resampler** (float rem_carrier_phase_in_rad, float phase_step_rad, float rem_code_phase_chips, float code_phase_step_chips, int signal_length_samples)
- bool **free** ()

12.66.1 Detailed Description

Class that implements carrier wipe-off and correlators.

Definition at line 35 of file [cpu_multicorrelator_16sc.h](#).

The documentation for this class was generated from the following file:

- [cpu_multicorrelator_16sc.h](#)

12.67 Cpu_Multicorrelator_Real_Codes Class Reference

Class that implements carrier wipe-off and correlators.

#include <cpu_multicorrelator_real_codes.h>

Public Member Functions

- void **set_high_dynamics_resampler** (bool use_high_dynamics_resampler)
- bool **init** (int max_signal_length_samples, int n_correlators)
- bool **set_local_code_and_taps** (int code_length_chips, const float *local_code_in, float *shifts_chips)
- bool **set_input_output_vectors** (std::complex< float > *corr_out, const std::complex< float > *sig_in)
- void **update_local_code** (int correlator_length_samples, float rem_code_phase_chips, float code_phase_step_chips, float code_phase_rate_step_chips=0.0)

- bool **Carrier_wipeoff_multicorrelator_resampler** (float rem_carrier_phase_in_rad, float phase_step_rad, float phase_rate_step_rad, float rem_code_phase_chips, float code_phase_step_chips, float code_phase_rate_step_chips, int signal_length_samples)
- bool **Carrier_wipeoff_multicorrelator_resampler** (float rem_carrier_phase_in_rad, float phase_step_rad, float rem_code_phase_chips, float code_phase_step_chips, float code_phase_rate_step_chips, int signal_length_samples)
- bool **free** ()

12.67.1 Detailed Description

Class that implements carrier wipe-off and correlators.

Definition at line 37 of file [cpu_multicorrelator_real_codes.h](#).

The documentation for this class was generated from the following file:

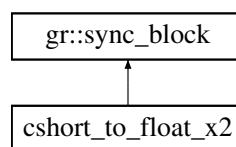
- [cpu_multicorrelator_real_codes.h](#)

12.68 cshort_to_float_x2 Class Reference

This class adapts a `std::complex<short>` stream into two 32-bits (float) streams.

```
#include <csort_to_float_x2.h>
```

Inheritance diagram for `csort_to_float_x2`:



Public Member Functions

- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- `csort_to_float_x2_sptr` **make_csort_to_float_x2** ()

12.68.1 Detailed Description

This class adapts a `std::complex<short>` stream into two 32-bits (float) streams.

Definition at line 41 of file [csort_to_float_x2.h](#).

The documentation for this class was generated from the following file:

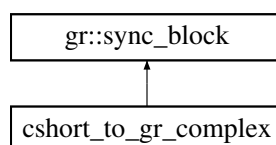
- [csort_to_float_x2.h](#)

12.69 cshort_to_gr_complex Class Reference

This class adapts a short (16-bits) interleaved sample stream into a `std::complex<float>` stream.

```
#include <csort_to_gr_complex.h>
```

Inheritance diagram for `csort_to_gr_complex`:



Public Member Functions

- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- cshort_to_gr_complex_sptr **make_cshort_to_gr_complex** ()

12.69.1 Detailed Description

This class adapts a short (16-bits) interleaved sample stream into a `std::complex<float>` stream.

Definition at line 40 of file [csshort_to_gr_complex.h](#).

The documentation for this class was generated from the following file:

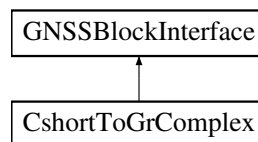
- [csshort_to_gr_complex.h](#)

12.70 CshortToGrComplex Class Reference

Adapts an 16-bits complex sample stream to a float complex stream.

`#include <csshort_to_grcomplex.h>`

Inheritance diagram for CshortToGrComplex:



Public Member Functions

- **CshortToGrComplex** (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override
 - Returns "Cshort_To_Gr_Complex".*
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.70.1 Detailed Description

Adapts an 16-bits complex sample stream to a float complex stream.

Definition at line 40 of file [csshort_to_grcomplex.h](#).

12.70.2 Member Function Documentation

12.70.2.1 connect()

```
void CshortToGrComplex::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.70.2.2 disconnect()

```
void CshortToGrComplex::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.70.2.3 get_left_block()

```
gr::basic_block_sptr CshortToGrComplex::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.70.2.4 get_right_block()

```
gr::basic_block_sptr CshortToGrComplex::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.70.2.5 implementation()

```
std::string CshortToGrComplex::implementation () [inline], [override], [virtual]
```

Returns "Cshort_To_Gr_Complex".

Implements [GNSSBlockInterface](#).

Definition at line 55 of file [cshort_to_grcomplex.h](#).

12.70.2.6 item_size()

```
size_t CshortToGrComplex::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 60 of file [cshort_to_grcomplex.h](#).

12.70.2.7 role()

```
std::string CshortToGrComplex::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 49 of file [cshort_to_grcomplex.h](#).

The documentation for this class was generated from the following file:

- [cshort_to_grcomplex.h](#)

12.71 CubatureFilter Class Reference

Public Member Functions

- **CubatureFilter** (int nx)
- **CubatureFilter** (const arma::vec &x_pred_0, const arma::mat &P_x_pred_0)
- void **initialize** (const arma::mat &x_pred_0, const arma::mat &P_x_pred_0)
- void **predict_sequential** (const arma::vec &x_post, const arma::mat &P_x_post, [ModelFunction](#) *transition←_fcn, const arma::mat &noise_covariance)
- void **update_sequential** (const arma::vec &z_upd, const arma::vec &x_pred, const arma::mat &P_x_pred, [ModelFunction](#) *measurement_fcn, const arma::mat &noise_covariance)
- arma::mat **get_x_pred** () const
- arma::mat **get_P_x_pred** () const
- arma::mat **get_x_est** () const
- arma::mat **get_P_x_est** () const

12.71.1 Detailed Description

Definition at line 54 of file [nonlinear_tracking.h](#).

The documentation for this class was generated from the following file:

- [nonlinear_tracking.h](#)

12.72 cuda_multicorrelator Class Reference

Class that implements carrier wipe-off and correlators using NVIDIA CUDA GPU accelerators.

#include <cuda_multicorrelator.h>

Public Member Functions

- bool **init_cuda_integrated_resampler** (int signal_length_samples, int code_length_chips, int n_correlators)
- bool **set_local_code_and_taps** (int code_length_chips, const std::complex< float > *local_codes_in, float *shifts_chips, int n_correlators)
- bool **set_input_output_vectors** (std::complex< float > *corr_out, std::complex< float > *sig_in)
- bool **free_cuda** ()
- bool **Carrier_wipeoff_multicorrelator_resampler_cuda** (float rem_carrier_phase_in_rad, float phase_step_rad, float code_phase_step_chips, float rem_code_phase_chips, int signal_length_samples, int n_correlators)

12.72.1 Detailed Description

Class that implements carrier wipe-off and correlators using NVIDIA CUDA GPU accelerators.

Definition at line 111 of file [cuda_multicorrelator.h](#).

The documentation for this class was generated from the following file:

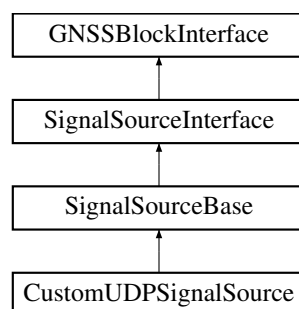
- [cuda_multicorrelator.h](#)

12.73 CustomUDPSignalSource Class Reference

This class reads from UDP packets, which streams interleaved I/Q samples over a network.

#include <custom_udp_signal_source.h>

Inheritance diagram for CustomUDPSignalSource:



Public Member Functions

- **CustomUDPSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t **item_size** () override
- void **connect** (gr::top_block_sptr top_block) override
- void **disconnect** (gr::top_block_sptr top_block) override
- gr::basic_block_sptr **get_left_block** () override
- gr::basic_block_sptr **get_right_block** () override
- gr::basic_block_sptr **get_right_block** (int RF_channel) override

Public Member Functions inherited from [SignalSourceBase](#)

- `std::string` [role](#) () final
- `std::string` [implementation](#) () final
- `size_t` [getRfChannels](#) () const override
- `gr::basic_block_sptr` [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual `gr::basic_block_sptr` [get_left_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, `std::string` role, `std::string` impl)
Constructor.
- `size_t` [decode_item_type](#) (`std::string` const &item_type, `bool` *is_interleaved=nullptr, `bool` throw_on_↔ error=false)
utility for decoding passed ".item_type" values

12.73.1 Detailed Description

This class reads from UDP packets, which streams interleaved I/Q samples over a network.
Definition at line 43 of file [custom_udp_signal_source.h](#).

12.73.2 Member Function Documentation

12.73.2.1 connect()

```
void CustomUDPSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.73.2.2 disconnect()

```
void CustomUDPSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.73.2.3 get_left_block()

```
gr::basic_block_sptr CustomUDPSignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.73.2.4 get_right_block() [1/2]

```
gr::basic_block_sptr CustomUDPSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.73.2.5 get_right_block() [2/2]

```
gr::basic_block_sptr CustomUDPSignalSource::get_right_block (
    int RF_channel) [override], [virtual]
```

Reimplemented from [GNSSBlockInterface](#).

12.73.2.6 item_size()

size_t CustomUDPSignalSource::item_size () [inline], [override], [virtual]

Implements [GNSSBlockInterface](#).

Definition at line 52 of file [custom_udp_signal_source.h](#).

The documentation for this class was generated from the following file:

- [custom_udp_signal_source.h](#)

12.74 Deleter Struct Reference

Public Member Functions

- [Deleter](#) (void *buffer)
- template<typename WordType>
void [operator](#)() () const

Public Attributes

- void * [buffer_](#)

12.74.1 Detailed Description

Definition at line 74 of file [ion_gsms_chunk_data.h](#).

12.74.2 Constructor & Destructor Documentation

12.74.2.1 Deleter()

```
Deleter::Deleter (
    void * buffer) [inline], [explicit]
```

Definition at line 78 of file [ion_gsms_chunk_data.h](#).

12.74.3 Member Function Documentation

12.74.3.1 operator>()()

```
template<typename WordType>
void Deleter::operator() () const [inline]
```

Definition at line 82 of file [ion_gsms_chunk_data.h](#).

12.74.4 Member Data Documentation

12.74.4.1 buffer_

```
void* Deleter::buffer_
```

Definition at line 76 of file [ion_gsms_chunk_data.h](#).

The documentation for this struct was generated from the following file:

- [ion_gsms_chunk_data.h](#)

12.75 dgps_t Struct Reference

Public Attributes

- [gtime_t](#) t0
- double [prc](#)
- double [rrc](#)
- int [iod](#)
- double [udre](#)

12.75.1 Detailed Description

Definition at line 646 of file [rtklib.h](#).

12.75.2 Member Data Documentation

12.75.2.1 iod

```
int dgps_t::iod
```

Definition at line 651 of file [rtklib.h](#).

12.75.2.2 prc

```
double dgps_t::prc
```

Definition at line 649 of file [rtklib.h](#).

12.75.2.3 rrc

```
double dgps_t::rrc
```

Definition at line 650 of file [rtklib.h](#).

12.75.2.4 t0

```
ptime_t dgps_t::t0
```

Definition at line 648 of file [rtklib.h](#).

12.75.2.5 udre

```
double dgps_t::udre
```

Definition at line 652 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

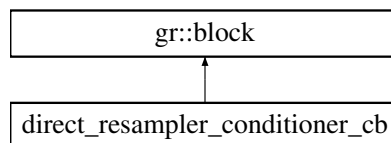
- [rtklib.h](#)

12.76 direct_resampler_conditioner_cb Class Reference

This class implements a direct resampler conditioner for `std::complex<signed char>`

```
#include <direct_resampler_conditioner_cb.h>
```

Inheritance diagram for `direct_resampler_conditioner_cb`:



Public Member Functions

- unsigned int [sample_freq_in](#) () const
- unsigned int [sample_freq_out](#) () const
- void **forecast** (int noutput_items, gr_vector_int &ninput_items_required)
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- `direct_resampler_conditioner_cb_sptr` **direct_resampler_make_conditioner_cb** (double sample_freq_in, double sample_freq_out)

12.76.1 Detailed Description

This class implements a direct resampler conditioner for `std::complex<signed char>`

Direct resampling without interpolation

Definition at line 46 of file [direct_resampler_conditioner_cb.h](#).

12.76.2 Member Function Documentation

12.76.2.1 `sample_freq_in()`

```
unsigned int direct_resampler_conditioner_cb::sample_freq_in () const [inline]
```

Definition at line 51 of file [direct_resampler_conditioner_cb.h](#).

12.76.2.2 `sample_freq_out()`

```
unsigned int direct_resampler_conditioner_cb::sample_freq_out () const [inline]
```

Definition at line 56 of file [direct_resampler_conditioner_cb.h](#).

The documentation for this class was generated from the following file:

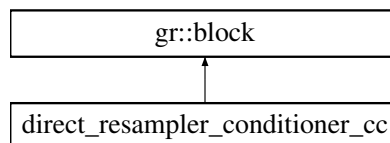
- [direct_resampler_conditioner_cb.h](#)

12.77 `direct_resampler_conditioner_cc` Class Reference

This class implements a direct resampler conditioner for complex data.

```
#include <direct_resampler_conditioner_cc.h>
```

Inheritance diagram for `direct_resampler_conditioner_cc`:



Public Member Functions

- unsigned int [sample_freq_in](#) () const
- unsigned int [sample_freq_out](#) () const
- void **forecast** (int noutput_items, gr_vector_int &ninput_items_required)
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- `direct_resampler_conditioner_cc_sptr` **direct_resampler_make_conditioner_cc** (double sample_freq_in, double sample_freq_out)

12.77.1 Detailed Description

This class implements a direct resampler conditioner for complex data.

Direct resampling without interpolation

Definition at line 51 of file [direct_resampler_conditioner_cc.h](#).

12.77.2 Member Function Documentation

12.77.2.1 `sample_freq_in()`

```
unsigned int direct_resampler_conditioner_cc::sample_freq_in () const [inline]
```

Definition at line 55 of file [direct_resampler_conditioner_cc.h](#).

12.77.2.2 sample_freq_out()

unsigned int direct_resampler_conditioner_cc::sample_freq_out () const [inline]

Definition at line 60 of file [direct_resampler_conditioner_cc.h](#).

The documentation for this class was generated from the following file:

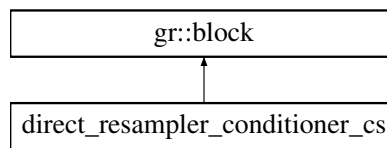
- [direct_resampler_conditioner_cc.h](#)

12.78 direct_resampler_conditioner_cs Class Reference

This class implements a direct resampler conditioner for `std::complex<short>`

#include <direct_resampler_conditioner_cs.h>

Inheritance diagram for direct_resampler_conditioner_cs:



Public Member Functions

- unsigned int [sample_freq_in](#) () const
- unsigned int [sample_freq_out](#) () const
- void **forecast** (int noutput_items, gr_vector_int &ninput_items_required)
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- direct_resampler_conditioner_cs_sptr **direct_resampler_make_conditioner_cs** (double sample_freq_in, double sample_freq_out)

12.78.1 Detailed Description

This class implements a direct resampler conditioner for `std::complex<short>`

Direct resampling without interpolation

Definition at line 45 of file [direct_resampler_conditioner_cs.h](#).

12.78.2 Member Function Documentation

12.78.2.1 sample_freq_in()

unsigned int direct_resampler_conditioner_cs::sample_freq_in () const [inline]

Definition at line 50 of file [direct_resampler_conditioner_cs.h](#).

12.78.2.2 sample_freq_out()

unsigned int direct_resampler_conditioner_cs::sample_freq_out () const [inline]

Definition at line 55 of file [direct_resampler_conditioner_cs.h](#).

The documentation for this class was generated from the following file:

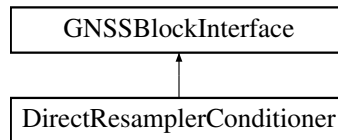
- [direct_resampler_conditioner_cs.h](#)

12.79 DirectResamplerConditioner Class Reference

Interface of an adapter of a direct resampler conditioner block to a SignalConditionerInterface.

#include <direct_resampler_conditioner.h>

Inheritance diagram for DirectResamplerConditioner:



Public Member Functions

- **DirectResamplerConditioner** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream)
- std::string [role](#) () override
- std::string [implementation](#) () override
Returns "Direct_Resampler".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.79.1 Detailed Description

Interface of an adapter of a direct resampler conditioner block to a SignalConditionerInterface.

Definition at line 38 of file [direct_resampler_conditioner.h](#).

12.79.2 Member Function Documentation

12.79.2.1 connect()

```
void DirectResamplerConditioner::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.79.2.2 disconnect()

```
void DirectResamplerConditioner::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.79.2.3 get_left_block()

```
gr::basic_block_sptr DirectResamplerConditioner::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.79.2.4 get_right_block()

`gr::basic_block_sptr DirectResamplerConditioner::get_right_block () [override], [virtual]`
 Implements [GNSSBlockInterface](#).

12.79.2.5 implementation()

`std::string DirectResamplerConditioner::implementation () [inline], [override], [virtual]`
 Returns "Direct_Resampler".
 Implements [GNSSBlockInterface](#).
 Definition at line 53 of file [direct_resampler_conditioner.h](#).

12.79.2.6 item_size()

`size_t DirectResamplerConditioner::item_size () [inline], [override], [virtual]`
 Implements [GNSSBlockInterface](#).
 Definition at line 58 of file [direct_resampler_conditioner.h](#).

12.79.2.7 role()

`std::string DirectResamplerConditioner::role () [inline], [override], [virtual]`
 Implements [GNSSBlockInterface](#).
 Definition at line 47 of file [direct_resampler_conditioner.h](#).
 The documentation for this class was generated from the following file:

- [direct_resampler_conditioner.h](#)

12.80 Dll_Pll_Conf Class Reference

Public Member Functions

- void **SetFromConfiguration** (const [ConfigurationInterface](#) *configuration, const std::string &role)

Public Attributes

- std::string [item_type](#) {"gr_complex"}
- std::string [dump_filename](#) {"./dll_pll_dump.dat"}
- double [fs_in](#) {2000000.0}
- double [carrier_lock_th](#) {0.0}
- double [bs_dominance_ratio](#) {0.6}
- float [pll_pull_in_bw_hz](#) {50.0}
- float [dll_pull_in_bw_hz](#) {3.0}
- float [fll_bw_hz](#) {35.0}
- float [pll_bw_hz](#) {35.0}
- float [dll_bw_hz](#) {2.0}
- float [pll_bw_narrow_hz](#) {5.0}
- float [dll_bw_narrow_hz](#) {0.75}
- float [early_late_space_chips](#) {0.25}
- float [very_early_late_space_chips](#) {0.5}
- float [early_late_space_narrow_chips](#) {0.15}
- float [very_early_late_space_narrow_chips](#) {0.5}
- float [slope](#) {1.0}
- float [spc](#) {0.5}
- float [y_intercept](#) {1.0}
- float [cn0_smoother_alpha](#) {0.002}
- float [carrier_lock_test_smoother_alpha](#) {0.002}
- float [bs_min_prompt_mag](#) {0.0}
- uint32_t [pull_in_time_s](#) {5U}

- uint32_t [bit_synchronization_time_limit_s](#) {20U}
- uint32_t [vector_length](#) {0U}
- uint32_t [smoother_length](#) {10U}
- int32_t [fill_filter_order](#) {1}
- int32_t [pll_filter_order](#) {3}
- int32_t [dll_filter_order](#) {2}
- int32_t [extend_correlation_symbols](#) {1}
- int32_t [cn0_samples](#) {0}
- int32_t [cn0_smoother_samples](#) {200}
- int32_t [carrier_lock_test_smoother_samples](#) {25}
- int32_t [cn0_min](#) {0}
- int32_t [max_code_lock_fail](#) {0}
- int32_t [max_carrier_lock_fail](#) {0}
- int32_t [bs_stable_best_required](#) {3}
- int32_t [bs_min_events_for_lock](#) {10}
- char [signal](#) [3] {}
- char [system](#) {'G'}
- bool [enable_fill_pull_in](#) {false}
- bool [enable_fill_steady_state](#) {false}
- bool [track_pilot](#) {true}
- bool [enable_doppler_correction](#) {false}
- bool [carrier_aiding](#) {true}
- bool [high_dyn](#) {false}
- bool [dump](#) {false}
- bool [dump_mat](#) {true}
- bool [tow_to_trk](#) {false}
- bool [bs_use_phase_dot_detector](#) {true}

12.80.1 Detailed Description

Definition at line 32 of file [dll_pll_conf.h](#).

12.80.2 Member Data Documentation

12.80.2.1 [bit_synchronization_time_limit_s](#)

```
uint32_t Dll_Pll_Conf::bit_synchronization_time_limit_s {20U}
```

Definition at line 62 of file [dll_pll_conf.h](#).

12.80.2.2 [bs_dominance_ratio](#)

```
double Dll_Pll_Conf::bs_dominance_ratio {0.6}
```

Definition at line 43 of file [dll_pll_conf.h](#).

12.80.2.3 [bs_min_events_for_lock](#)

```
int32_t Dll_Pll_Conf::bs_min_events_for_lock {10}
```

Definition at line 76 of file [dll_pll_conf.h](#).

12.80.2.4 [bs_min_prompt_mag](#)

```
float Dll_Pll_Conf::bs_min_prompt_mag {0.0}
```

Definition at line 60 of file [dll_pll_conf.h](#).

12.80.2.5 [bs_stable_best_required](#)

```
int32_t Dll_Pll_Conf::bs_stable_best_required {3}
```

Definition at line 75 of file [dll_pll_conf.h](#).

12.80.2.6 bs_use_phase_dot_detector

```
bool Dll_Pll_Conf::bs_use_phase_dot_detector {true}
```

Definition at line 88 of file [dll_pll_conf.h](#).

12.80.2.7 carrier_aiding

```
bool Dll_Pll_Conf::carrier_aiding {true}
```

Definition at line 83 of file [dll_pll_conf.h](#).

12.80.2.8 carrier_lock_test_smoother_alpha

```
float Dll_Pll_Conf::carrier_lock_test_smoother_alpha {0.002}
```

Definition at line 59 of file [dll_pll_conf.h](#).

12.80.2.9 carrier_lock_test_smoother_samples

```
int32_t Dll_Pll_Conf::carrier_lock_test_smoother_samples {25}
```

Definition at line 71 of file [dll_pll_conf.h](#).

12.80.2.10 carrier_lock_th

```
double Dll_Pll_Conf::carrier_lock_th {0.0}
```

Definition at line 42 of file [dll_pll_conf.h](#).

12.80.2.11 cn0_min

```
int32_t Dll_Pll_Conf::cn0_min {0}
```

Definition at line 72 of file [dll_pll_conf.h](#).

12.80.2.12 cn0_samples

```
int32_t Dll_Pll_Conf::cn0_samples {0}
```

Definition at line 69 of file [dll_pll_conf.h](#).

12.80.2.13 cn0_smoother_alpha

```
float Dll_Pll_Conf::cn0_smoother_alpha {0.002}
```

Definition at line 58 of file [dll_pll_conf.h](#).

12.80.2.14 cn0_smoother_samples

```
int32_t Dll_Pll_Conf::cn0_smoother_samples {200}
```

Definition at line 70 of file [dll_pll_conf.h](#).

12.80.2.15 dll_bw_hz

```
float Dll_Pll_Conf::dll_bw_hz {2.0}
```

Definition at line 48 of file [dll_pll_conf.h](#).

12.80.2.16 dll_bw_narrow_hz

```
float Dll_Pll_Conf::dll_bw_narrow_hz {0.75}
```

Definition at line 50 of file [dll_pll_conf.h](#).

12.80.2.17 dll_filter_order

```
int32_t Dll_Pll_Conf::dll_filter_order {2}
```

Definition at line 67 of file [dll_pll_conf.h](#).

12.80.2.18 dll_pull_in_bw_hz

```
float Dll_Pll_Conf::dll_pull_in_bw_hz {3.0}
```

Definition at line 45 of file [dll_pll_conf.h](#).

12.80.2.19 dump

```
bool Dll_Pll_Conf::dump {false}
```

Definition at line 85 of file [dll_pll_conf.h](#).

12.80.2.20 dump_filename

```
std::string Dll_Pll_Conf::dump_filename {"/dll_pll_dump.dat"}
```

Definition at line 40 of file [dll_pll_conf.h](#).

12.80.2.21 dump_mat

```
bool Dll_Pll_Conf::dump_mat {true}
```

Definition at line 86 of file [dll_pll_conf.h](#).

12.80.2.22 early_late_space_chips

```
float Dll_Pll_Conf::early_late_space_chips {0.25}
```

Definition at line 51 of file [dll_pll_conf.h](#).

12.80.2.23 early_late_space_narrow_chips

```
float Dll_Pll_Conf::early_late_space_narrow_chips {0.15}
```

Definition at line 53 of file [dll_pll_conf.h](#).

12.80.2.24 enable_doppler_correction

```
bool Dll_Pll_Conf::enable_doppler_correction {false}
```

Definition at line 82 of file [dll_pll_conf.h](#).

12.80.2.25 enable_fll_pull_in

```
bool Dll_Pll_Conf::enable_fll_pull_in {false}
```

Definition at line 79 of file [dll_pll_conf.h](#).

12.80.2.26 enable_fll_steady_state

```
bool Dll_Pll_Conf::enable_fll_steady_state {false}
```

Definition at line 80 of file [dll_pll_conf.h](#).

12.80.2.27 extend_correlation_symbols

```
int32_t Dll_Pll_Conf::extend_correlation_symbols {1}
```

Definition at line 68 of file [dll_pll_conf.h](#).

12.80.2.28 fll_bw_hz

```
float Dll_Pll_Conf::fll_bw_hz {35.0}
```

Definition at line 46 of file [dll_pll_conf.h](#).

12.80.2.29 fll_filter_order

```
int32_t Dll_Pll_Conf::fll_filter_order {1}
```

Definition at line 65 of file [dll_pll_conf.h](#).

12.80.2.30 fs_in

```
double Dll_Pll_Conf::fs_in {2000000.0}
```

Definition at line 41 of file [dll_pll_conf.h](#).

12.80.2.31 high_dyn

```
bool Dll_Pll_Conf::high_dyn {false}
```

Definition at line 84 of file [dll_pll_conf.h](#).

12.80.2.32 item_type

```
std::string Dll_Pll_Conf::item_type {"gr_complex"}
```

Definition at line 39 of file [dll_pll_conf.h](#).

12.80.2.33 max_carrier_lock_fail

```
int32_t Dll_Pll_Conf::max_carrier_lock_fail {0}
```

Definition at line 74 of file [dll_pll_conf.h](#).

12.80.2.34 max_code_lock_fail

```
int32_t Dll_Pll_Conf::max_code_lock_fail {0}
```

Definition at line 73 of file [dll_pll_conf.h](#).

12.80.2.35 pll_bw_hz

```
float Dll_Pll_Conf::pll_bw_hz {35.0}
```

Definition at line 47 of file [dll_pll_conf.h](#).

12.80.2.36 pll_bw_narrow_hz

```
float Dll_Pll_Conf::pll_bw_narrow_hz {5.0}
```

Definition at line 49 of file [dll_pll_conf.h](#).

12.80.2.37 pll_filter_order

```
int32_t Dll_Pll_Conf::pll_filter_order {3}
```

Definition at line 66 of file [dll_pll_conf.h](#).

12.80.2.38 pll_pull_in_bw_hz

```
float Dll_Pll_Conf::pll_pull_in_bw_hz {50.0}
```

Definition at line 44 of file [dll_pll_conf.h](#).

12.80.2.39 pull_in_time_s

```
uint32_t Dll_Pll_Conf::pull_in_time_s {5U}
```

Definition at line 61 of file [dll_pll_conf.h](#).

12.80.2.40 signal

```
char Dll_Pll_Conf::signal[3] {}
```

Definition at line 77 of file [dll_pll_conf.h](#).

12.80.2.41 slope

```
float Dll_Pll_Conf::slope {1.0}
```

Definition at line 55 of file [dll_pll_conf.h](#).

12.80.2.42 smoother_length

uint32_t Dll_Pll_Conf::smoother_length {10U}
 Definition at line 64 of file [dll_pll_conf.h](#).

12.80.2.43 spc

float Dll_Pll_Conf::spc {0.5}
 Definition at line 56 of file [dll_pll_conf.h](#).

12.80.2.44 system

char Dll_Pll_Conf::system {'G'}
 Definition at line 78 of file [dll_pll_conf.h](#).

12.80.2.45 tow_to_trk

bool Dll_Pll_Conf::tow_to_trk {false}
 Definition at line 87 of file [dll_pll_conf.h](#).

12.80.2.46 track_pilot

bool Dll_Pll_Conf::track_pilot {true}
 Definition at line 81 of file [dll_pll_conf.h](#).

12.80.2.47 vector_length

uint32_t Dll_Pll_Conf::vector_length {0U}
 Definition at line 63 of file [dll_pll_conf.h](#).

12.80.2.48 very_early_late_space_chips

float Dll_Pll_Conf::very_early_late_space_chips {0.5}
 Definition at line 52 of file [dll_pll_conf.h](#).

12.80.2.49 very_early_late_space_narrow_chips

float Dll_Pll_Conf::very_early_late_space_narrow_chips {0.5}
 Definition at line 54 of file [dll_pll_conf.h](#).

12.80.2.50 y_intercept

float Dll_Pll_Conf::y_intercept {1.0}
 Definition at line 57 of file [dll_pll_conf.h](#).

The documentation for this class was generated from the following file:

- [dll_pll_conf.h](#)

12.81 Dll_Pll_Conf_Fpga Class Reference**Public Member Functions**

- void **SetFromConfiguration** (const [ConfigurationInterface](#) *configuration, const std::string &role)

Public Attributes

- std::string **device_name** {"/dev/uio"}
- std::string **dump_filename** {"/dll_pll_dump.dat"}
- double **fs_in** {12500000.0}
- double **carrier_lock_th** {0.0}

- double `bs_dominance_ratio` {0.6}
- float `pll_pull_in_bw_hz` {50.0}
- float `dll_pull_in_bw_hz` {3.0}
- float `fill_bw_hz` {35.0}
- float `pll_bw_hz` {5.0}
- float `dll_bw_hz` {0.5}
- float `pll_bw_narrow_hz` {2.0}
- float `dll_bw_narrow_hz` {0.25}
- float `early_late_space_chips` {0.25}
- float `very_early_late_space_chips` {0.5}
- float `early_late_space_narrow_chips` {0.15}
- float `very_early_late_space_narrow_chips` {0.5}
- float `slope` {1.0}
- float `spc` {0.5}
- float `y_intercept` {1.0}
- float `cn0_smoother_alpha` {0.002}
- float `carrier_lock_test_smoother_alpha` {0.002}
- float `bs_min_prompt_mag` {0.0}
- uint32_t `pull_in_time_s` {5U}
- uint32_t `bit_synchronization_time_limit_s` {70U}
- uint32_t `vector_length` {0U}
- uint32_t `smoother_length` {10U}
- uint32_t `code_length_chips` {0U}
- uint32_t `code_samples_per_chip` {0U}
- uint32_t `extend_fpga_integration_periods` {1}
- uint32_t `fpga_integration_period` {0}
- int32_t `fill_filter_order` {1}
- int32_t `pll_filter_order` {3}
- int32_t `dll_filter_order` {2}
- int32_t `extend_correlation_symbols` {1}
- int32_t `cn0_samples` {0}
- int32_t `cn0_min` {0}
- int32_t `max_code_lock_fail` {0}
- int32_t `max_carrier_lock_fail` {0}
- int32_t `cn0_smoother_samples` {200}
- int32_t `carrier_lock_test_smoother_samples` {25}
- int32_t `bs_stable_best_required` {3}
- int32_t `bs_min_events_for_lock` {10}
- int32_t * `ca_codes` {nullptr}
- int32_t * `data_codes` {nullptr}
- char `signal` [3] {}
- char `system` {'G'}
- bool `extended_correlation_in_fpga` {false}
- bool `track_pilot` {true}
- bool `enable_doppler_correction` {false}
- bool `enable_fill_pull_in` {false}
- bool `enable_fill_steady_state` {false}
- bool `carrier_aiding` {true}
- bool `high_dyn` {false}
- bool `dump` {false}
- bool `dump_mat` {true}
- bool `bs_use_phase_dot_detector` {true}

12.81.1 Detailed Description

Definition at line 34 of file [dll_pll_conf_fpga.h](#).

12.81.2 Member Data Documentation

12.81.2.1 bit_synchronization_time_limit_s

```
uint32_t Dll_Pll_Conf_Fpga::bit_synchronization_time_limit_s {70U}
```

Definition at line 67 of file [dll_pll_conf_fpga.h](#).

12.81.2.2 bs_dominance_ratio

```
double Dll_Pll_Conf_Fpga::bs_dominance_ratio {0.6}
```

Definition at line 46 of file [dll_pll_conf_fpga.h](#).

12.81.2.3 bs_min_events_for_lock

```
int32_t Dll_Pll_Conf_Fpga::bs_min_events_for_lock {10}
```

Definition at line 87 of file [dll_pll_conf_fpga.h](#).

12.81.2.4 bs_min_prompt_mag

```
float Dll_Pll_Conf_Fpga::bs_min_prompt_mag {0.0}
```

Definition at line 64 of file [dll_pll_conf_fpga.h](#).

12.81.2.5 bs_stable_best_required

```
int32_t Dll_Pll_Conf_Fpga::bs_stable_best_required {3}
```

Definition at line 86 of file [dll_pll_conf_fpga.h](#).

12.81.2.6 bs_use_phase_dot_detector

```
bool Dll_Pll_Conf_Fpga::bs_use_phase_dot_detector {true}
```

Definition at line 104 of file [dll_pll_conf_fpga.h](#).

12.81.2.7 ca_codes

```
int32_t* Dll_Pll_Conf_Fpga::ca_codes {nullptr}
```

Definition at line 89 of file [dll_pll_conf_fpga.h](#).

12.81.2.8 carrier_aiding

```
bool Dll_Pll_Conf_Fpga::carrier_aiding {true}
```

Definition at line 100 of file [dll_pll_conf_fpga.h](#).

12.81.2.9 carrier_lock_test_smoother_alpha

```
float Dll_Pll_Conf_Fpga::carrier_lock_test_smoother_alpha {0.002}
```

Definition at line 63 of file [dll_pll_conf_fpga.h](#).

12.81.2.10 carrier_lock_test_smoother_samples

```
int32_t Dll_Pll_Conf_Fpga::carrier_lock_test_smoother_samples {25}
```

Definition at line 84 of file [dll_pll_conf_fpga.h](#).

12.81.2.11 carrier_lock_th

```
double Dll_Pll_Conf_Fpga::carrier_lock_th {0.0}
```

Definition at line 45 of file [dll_pll_conf_fpga.h](#).

12.81.2.12 cn0_min

```
int32_t Dll_Pll_Conf_Fpga::cn0_min {0}
```

Definition at line 80 of file [dll_pll_conf_fpga.h](#).

12.81.2.13 cn0_samples

```
int32_t Dll_Pll_Conf_Fpga::cn0_samples {0}
```

Definition at line 79 of file [dll_pll_conf_fpga.h](#).

12.81.2.14 cn0_smoother_alpha

```
float Dll_Pll_Conf_Fpga::cn0_smoother_alpha {0.002}
```

Definition at line 62 of file [dll_pll_conf_fpga.h](#).

12.81.2.15 cn0_smoother_samples

```
int32_t Dll_Pll_Conf_Fpga::cn0_smoother_samples {200}
```

Definition at line 83 of file [dll_pll_conf_fpga.h](#).

12.81.2.16 code_length_chips

```
uint32_t Dll_Pll_Conf_Fpga::code_length_chips {0U}
```

Definition at line 70 of file [dll_pll_conf_fpga.h](#).

12.81.2.17 code_samples_per_chip

```
uint32_t Dll_Pll_Conf_Fpga::code_samples_per_chip {0U}
```

Definition at line 71 of file [dll_pll_conf_fpga.h](#).

12.81.2.18 data_codes

```
int32_t* Dll_Pll_Conf_Fpga::data_codes {nullptr}
```

Definition at line 90 of file [dll_pll_conf_fpga.h](#).

12.81.2.19 device_name

```
std::string Dll_Pll_Conf_Fpga::device_name {"/dev/uio"}
```

Definition at line 41 of file [dll_pll_conf_fpga.h](#).

12.81.2.20 dll_bw_hz

```
float Dll_Pll_Conf_Fpga::dll_bw_hz {0.5}
```

Definition at line 52 of file [dll_pll_conf_fpga.h](#).

12.81.2.21 dll_bw_narrow_hz

```
float Dll_Pll_Conf_Fpga::dll_bw_narrow_hz {0.25}
```

Definition at line 54 of file [dll_pll_conf_fpga.h](#).

12.81.2.22 dll_filter_order

```
int32_t Dll_Pll_Conf_Fpga::dll_filter_order {2}
```

Definition at line 77 of file [dll_pll_conf_fpga.h](#).

12.81.2.23 dll_pull_in_bw_hz

```
float Dll_Pll_Conf_Fpga::dll_pull_in_bw_hz {3.0}
```

Definition at line 49 of file [dll_pll_conf_fpga.h](#).

12.81.2.24 dump

```
bool Dll_Pll_Conf_Fpga::dump {false}
```

Definition at line 102 of file [dll_pll_conf_fpga.h](#).

12.81.2.25 dump_filename

```
std::string Dll_Pll_Conf_Fpga::dump_filename {"/dll_pll_dump.dat"}
```

Definition at line 42 of file [dll_pll_conf_fpga.h](#).

12.81.2.26 dump_mat

```
bool Dll_Pll_Conf_Fpga::dump_mat {true}
```

Definition at line 103 of file [dll_pll_conf_fpga.h](#).

12.81.2.27 early_late_space_chips

```
float Dll_Pll_Conf_Fpga::early_late_space_chips {0.25}
```

Definition at line 55 of file [dll_pll_conf_fpga.h](#).

12.81.2.28 early_late_space_narrow_chips

```
float Dll_Pll_Conf_Fpga::early_late_space_narrow_chips {0.15}
```

Definition at line 57 of file [dll_pll_conf_fpga.h](#).

12.81.2.29 enable_doppler_correction

```
bool Dll_Pll_Conf_Fpga::enable_doppler_correction {false}
```

Definition at line 97 of file [dll_pll_conf_fpga.h](#).

12.81.2.30 enable_fll_pull_in

```
bool Dll_Pll_Conf_Fpga::enable_fll_pull_in {false}
```

Definition at line 98 of file [dll_pll_conf_fpga.h](#).

12.81.2.31 enable_fll_steady_state

```
bool Dll_Pll_Conf_Fpga::enable_fll_steady_state {false}
```

Definition at line 99 of file [dll_pll_conf_fpga.h](#).

12.81.2.32 extend_correlation_symbols

```
int32_t Dll_Pll_Conf_Fpga::extend_correlation_symbols {1}
```

Definition at line 78 of file [dll_pll_conf_fpga.h](#).

12.81.2.33 extend_fpga_integration_periods

```
uint32_t Dll_Pll_Conf_Fpga::extend_fpga_integration_periods {1}
```

Definition at line 72 of file [dll_pll_conf_fpga.h](#).

12.81.2.34 extended_correlation_in_fpga

```
bool Dll_Pll_Conf_Fpga::extended_correlation_in_fpga {false}
```

Definition at line 95 of file [dll_pll_conf_fpga.h](#).

12.81.2.35 fll_bw_hz

```
float Dll_Pll_Conf_Fpga::fll_bw_hz {35.0}
```

Definition at line 50 of file [dll_pll_conf_fpga.h](#).

12.81.2.36 fll_filter_order

```
int32_t Dll_Pll_Conf_Fpga::fll_filter_order {1}
```

Definition at line 75 of file [dll_pll_conf_fpga.h](#).

12.81.2.37 fpga_integration_period

```
uint32_t Dll_Pll_Conf_Fpga::fpga_integration_period {0}
```

Definition at line 73 of file [dll_pll_conf_fpga.h](#).

12.81.2.38 fs_in

```
double Dll_Pll_Conf_Fpga::fs_in {12500000.0}
```

Definition at line 44 of file [dll_pll_conf_fpga.h](#).

12.81.2.39 high_dyn

```
bool Dll_Pll_Conf_Fpga::high_dyn {false}
```

Definition at line 101 of file [dll_pll_conf_fpga.h](#).

12.81.2.40 max_carrier_lock_fail

```
int32_t Dll_Pll_Conf_Fpga::max_carrier_lock_fail {0}
```

Definition at line 82 of file [dll_pll_conf_fpga.h](#).

12.81.2.41 max_code_lock_fail

```
int32_t Dll_Pll_Conf_Fpga::max_code_lock_fail {0}
```

Definition at line 81 of file [dll_pll_conf_fpga.h](#).

12.81.2.42 pll_bw_hz

```
float Dll_Pll_Conf_Fpga::pll_bw_hz {5.0}
```

Definition at line 51 of file [dll_pll_conf_fpga.h](#).

12.81.2.43 pll_bw_narrow_hz

```
float Dll_Pll_Conf_Fpga::pll_bw_narrow_hz {2.0}
```

Definition at line 53 of file [dll_pll_conf_fpga.h](#).

12.81.2.44 pll_filter_order

```
int32_t Dll_Pll_Conf_Fpga::pll_filter_order {3}
```

Definition at line 76 of file [dll_pll_conf_fpga.h](#).

12.81.2.45 pll_pull_in_bw_hz

```
float Dll_Pll_Conf_Fpga::pll_pull_in_bw_hz {50.0}
```

Definition at line 48 of file [dll_pll_conf_fpga.h](#).

12.81.2.46 pull_in_time_s

```
uint32_t Dll_Pll_Conf_Fpga::pull_in_time_s {5U}
```

Definition at line 66 of file [dll_pll_conf_fpga.h](#).

12.81.2.47 signal

```
char Dll_Pll_Conf_Fpga::signal[3] {}
```

Definition at line 92 of file [dll_pll_conf_fpga.h](#).

12.81.2.48 slope

```
float Dll_Pll_Conf_Fpga::slope {1.0}
```

Definition at line 59 of file [dll_pll_conf_fpga.h](#).

12.81.2.49 smoother_length

```
uint32_t Dll_Pll_Conf_Fpga::smoother_length {10U}
```

Definition at line 69 of file [dll_pll_conf_fpga.h](#).

12.81.2.50 spc

```
float Dll_Pll_Conf_Fpga::spc {0.5}
```

Definition at line 60 of file [dll_pll_conf_fpga.h](#).

12.81.2.51 system

```
char Dll_Pll_Conf_Fpga::system {'G'}
```

Definition at line 93 of file [dll_pll_conf_fpga.h](#).

12.81.2.52 track_pilot

```
bool Dll_Pll_Conf_Fpga::track_pilot {true}
```

Definition at line 96 of file [dll_pll_conf_fpga.h](#).

12.81.2.53 vector_length

```
uint32_t Dll_Pll_Conf_Fpga::vector_length {0U}
```

Definition at line 68 of file [dll_pll_conf_fpga.h](#).

12.81.2.54 very_early_late_space_chips

```
float Dll_Pll_Conf_Fpga::very_early_late_space_chips {0.5}
```

Definition at line 56 of file [dll_pll_conf_fpga.h](#).

12.81.2.55 very_early_late_space_narrow_chips

```
float Dll_Pll_Conf_Fpga::very_early_late_space_narrow_chips {0.5}
```

Definition at line 58 of file [dll_pll_conf_fpga.h](#).

12.81.2.56 y_intercept

```
float Dll_Pll_Conf_Fpga::y_intercept {1.0}
```

Definition at line 61 of file [dll_pll_conf_fpga.h](#).

The documentation for this class was generated from the following file:

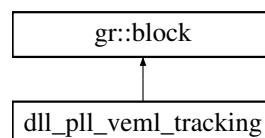
- [dll_pll_conf_fpga.h](#)

12.82 dll_pll_veml_tracking Class Reference

This class implements a code DLL + carrier PLL tracking block.

```
#include <dll_pll_veml_tracking.h>
```

Inheritance diagram for `dll_pll_veml_tracking`:



Public Member Functions

- void **set_channel** (uint32_t channel)
- void **set_gnss_synchro** ([Gnss_Synchro](#) *p_gnss_synchro)
- void **start_tracking** ()
- void **stop_tracking** ()
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
- void **forecast** (int noutput_items, gr_vector_int &ninput_items_required) override

Friends

- [dll_pll_veml_tracking_sptr](#) **dll_pll_veml_make_tracking** (const [Dll_Pll_Conf](#) &conf_)

12.82.1 Detailed Description

This class implements a code DLL + carrier PLL tracking block.

Definition at line 61 of file [dll_pll_veml_tracking.h](#).

The documentation for this class was generated from the following file:

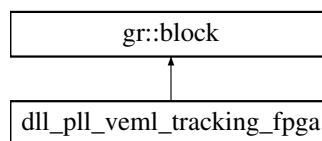
- [dll_pll_veml_tracking.h](#)

12.83 dll_pll_veml_tracking_fpga Class Reference

This class implements a code DLL + carrier PLL tracking block.

#include <dll_pll_veml_tracking_fpga.h>

Inheritance diagram for `dll_pll_veml_tracking_fpga`:



Public Member Functions

- [~dll_pll_veml_tracking_fpga](#) ()
Destructor.
- void **set_channel** (uint32_t channel, const std::string &device_io_name)
Set the channel number and configure some multicorrelator parameters.
- void **set_gnss_synchro** ([Gnss_Synchro](#) *p_gnss_synchro)
This function is used with two purposes: 1 -> To set the gnss_synchro 2 -> A set_gnss_synchro command with a valid PRN is received when the system is going to run acquisition with that PRN. We can use this command to pre-initialize tracking parameters and variables before the actual acquisition process takes place. In this way we minimize the latency between acquisition and tracking once the acquisition has been made.
- void **start_tracking** ()
This function starts the tracking process.
- void **stop_tracking** ()
This function sets a flag that makes general_work to stop in order to finish the tracking process.
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)
General Work.
- void **reset** ()
This function disables the HW multicorrelator in the FPGA in order to stop the tracking process.

Friends

- `dll_pll_veml_tracking_fpga_sptr dll_pll_veml_make_tracking_fpga` (const [Dll_Pll_Conf_Fpga](#) &conf_)

12.83.1 Detailed Description

This class implements a code DLL + carrier PLL tracking block.
Definition at line 59 of file [dll_pll_veml_tracking_fpga.h](#).

12.83.2 Constructor & Destructor Documentation

12.83.2.1 ~dll_pll_veml_tracking_fpga()

```
dll_pll_veml_tracking_fpga::~dll_pll_veml_tracking_fpga ()
```

Destructor.

12.83.3 Member Function Documentation

12.83.3.1 general_work()

```
int dll_pll_veml_tracking_fpga::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items)
```

General Work.

12.83.3.2 reset()

```
void dll_pll_veml_tracking_fpga::reset ()
```

This function disables the HW multicorrelator in the FPGA in order to stop the tracking process.

12.83.3.3 set_channel()

```
void dll_pll_veml_tracking_fpga::set_channel (
    uint32_t channel,
    const std::string & device_io_name)
```

Set the channel number and configure some multicorrelator parameters.

12.83.3.4 set_gnss_synchro()

```
void dll_pll_veml_tracking_fpga::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro)
```

This function is used with two purposes: 1 -> To set the gnss_synchro 2 -> A set_gnss_synchro command with a valid PRN is received when the system is going to run acquisition with that PRN. We can use this command to pre-initialize tracking parameters and variables before the actual acquisition process takes place. In this way we minimize the latency between acquisition and tracking once the acquisition has been made.

12.83.3.5 start_tracking()

```
void dll_pll_veml_tracking_fpga::start_tracking ()
```

This function starts the tracking process.

12.83.3.6 stop_tracking()

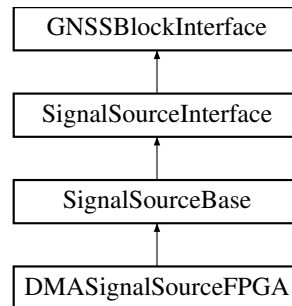
```
void dll_pll_veml_tracking_fpga::stop_tracking ()
```

This function sets a flag that makes general_work to stop in order to finish the tracking process.
The documentation for this class was generated from the following file:

- [dll_pll_veml_tracking_fpga.h](#)

12.84 DMASignalSourceFPGA Class Reference

Inheritance diagram for DMASignalSourceFPGA:



Public Member Functions

- **DMASignalSourceFPGA** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- void [start](#) () override
Start the flow of samples if needed.
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↔ error=false)
utility for decoding passed ".item_type" values

12.84.1 Detailed Description

Definition at line 44 of file [dma_signal_source_fpga.h](#).

12.84.2 Member Function Documentation

12.84.2.1 connect()

```
void DMASignalSourceFPGA::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.84.2.2 disconnect()

```
void DMASignalSourceFPGA::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.84.2.3 get_left_block()

```
gr::basic_block_sptr DMASignalSourceFPGA::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.84.2.4 get_right_block()

```
gr::basic_block_sptr DMASignalSourceFPGA::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.84.2.5 item_size()

```
size_t DMASignalSourceFPGA::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 55 of file [dma_signal_source_fpga.h](#).

12.84.2.6 start()

```
void DMASignalSourceFPGA::start () [override], [virtual]
```

Start the flow of samples if needed.

Reimplemented from [GNSSBlockInterface](#).

The documentation for this class was generated from the following file:

- [dma_signal_source_fpga.h](#)

12.85 DSM_dsm_header Class Reference

Public Attributes

- uint8_t [dsm_id](#) {}
- uint8_t [dsm_block_id](#) {}

12.85.1 Detailed Description

Definition at line 44 of file [osnma_data.h](#).

12.85.2 Member Data Documentation

12.85.2.1 dsm_block_id

```
uint8_t DSM_dsm_header::dsm_block_id {}
```

Definition at line 49 of file [osnma_data.h](#).

12.85.2.2 dsm_id

uint8_t DSM_dsm_header::dsm_id {}

Definition at line 48 of file [osnma_data.h](#).

The documentation for this class was generated from the following file:

- [osnma_data.h](#)

12.86 DSM_KROOT_message Class Reference

Public Attributes

- std::vector< uint8_t > [kroot](#)
- std::vector< uint8_t > [ds](#)
- std::vector< uint8_t > [p_dk](#)
- uint64_t [alpha](#) {}
- uint16_t [wn_k](#) {}
- uint8_t [nb_dk](#) {}
- uint8_t [pkid](#) {}
- uint8_t [cidkr](#) {}
- uint8_t [reserved1](#) {}
- uint8_t [hf](#) {}
- uint8_t [mf](#) {}
- uint8_t [ks](#) {}
- uint8_t [ts](#) {}
- uint8_t [maclt](#) {}
- uint8_t [reserved](#) {}
- uint8_t [towh_k](#) {}
- bool [verified](#) {false}

12.86.1 Detailed Description

Definition at line 98 of file [osnma_data.h](#).

12.86.2 Member Data Documentation

12.86.2.1 alpha

uint64_t DSM_KROOT_message::alpha {}

Definition at line 106 of file [osnma_data.h](#).

12.86.2.2 cidkr

uint8_t DSM_KROOT_message::cidkr {}

Definition at line 110 of file [osnma_data.h](#).

12.86.2.3 ds

std::vector<uint8_t> DSM_KROOT_message::ds

Definition at line 104 of file [osnma_data.h](#).

12.86.2.4 hf

uint8_t DSM_KROOT_message::hf {}

Definition at line 112 of file [osnma_data.h](#).

12.86.2.5 kroot

std::vector<uint8_t> DSM_KROOT_message::kroot

Definition at line 103 of file [osnma_data.h](#).

12.86.2.6 ks

```
uint8_t DSM_KROOT_message::ks {}
```

Definition at line 114 of file [osnma_data.h](#).

12.86.2.7 macIt

```
uint8_t DSM_KROOT_message::macIt {}
```

Definition at line 116 of file [osnma_data.h](#).

12.86.2.8 mf

```
uint8_t DSM_KROOT_message::mf {}
```

Definition at line 113 of file [osnma_data.h](#).

12.86.2.9 nb_dk

```
uint8_t DSM_KROOT_message::nb_dk {}
```

Definition at line 108 of file [osnma_data.h](#).

12.86.2.10 p_dk

```
std::vector<uint8_t> DSM_KROOT_message::p_dk
```

Definition at line 105 of file [osnma_data.h](#).

12.86.2.11 pkid

```
uint8_t DSM_KROOT_message::pkid {}
```

Definition at line 109 of file [osnma_data.h](#).

12.86.2.12 reserved

```
uint8_t DSM_KROOT_message::reserved {}
```

Definition at line 117 of file [osnma_data.h](#).

12.86.2.13 reserved1

```
uint8_t DSM_KROOT_message::reserved1 {}
```

Definition at line 111 of file [osnma_data.h](#).

12.86.2.14 towh_k

```
uint8_t DSM_KROOT_message::towh_k {}
```

Definition at line 118 of file [osnma_data.h](#).

12.86.2.15 ts

```
uint8_t DSM_KROOT_message::ts {}
```

Definition at line 115 of file [osnma_data.h](#).

12.86.2.16 verified

```
bool DSM_KROOT_message::verified {false}
```

Definition at line 119 of file [osnma_data.h](#).

12.86.2.17 wn_k

```
uint16_t DSM_KROOT_message::wn_k {}
```

Definition at line 107 of file [osnma_data.h](#).

The documentation for this class was generated from the following file:

- [osnma_data.h](#)

12.87 DSM_nma_header Class Reference

Public Attributes

- uint8_t [nmas](#) {}
- uint8_t [cid](#) {}
- uint8_t [cpks](#) {}
- bool [reserved](#) {}

12.87.1 Detailed Description

Definition at line 33 of file [osnma_data.h](#).

12.87.2 Member Data Documentation

12.87.2.1 cid

```
uint8_t DSM_nma_header::cid {}
```

Definition at line 38 of file [osnma_data.h](#).

12.87.2.2 cpks

```
uint8_t DSM_nma_header::cpks {}
```

Definition at line 39 of file [osnma_data.h](#).

12.87.2.3 nmas

```
uint8_t DSM_nma_header::nmas {}
```

Definition at line 37 of file [osnma_data.h](#).

12.87.2.4 reserved

```
bool DSM_nma_header::reserved {}
```

Definition at line 40 of file [osnma_data.h](#).

The documentation for this class was generated from the following file:

- [osnma_data.h](#)

12.88 DSM_PKR_message Class Reference

Public Attributes

- std::array< uint8_t, 128 > [itn](#) {}
- std::vector< uint8_t > [npk](#)
- std::vector< uint8_t > [p_dp](#)
- uint8_t [nb_dp](#) {}
- uint8_t [mid](#) {}
- uint8_t [npkt](#) {}
- uint8_t [npktid](#) {}

12.88.1 Detailed Description

Definition at line 83 of file [osnma_data.h](#).

12.88.2 Member Data Documentation

12.88.2.1 itn

```
std::array<uint8_t, 128> DSM_PKR_message::itn {}
```

Definition at line 88 of file [osnma_data.h](#).

12.88.2.2 mid

```
uint8_t DSM_PKR_message::mid {}
```

Definition at line 92 of file [osnma_data.h](#).

12.88.2.3 nb_dp

```
uint8_t DSM_PKR_message::nb_dp {}
```

Definition at line 91 of file [osnma_data.h](#).

12.88.2.4 npk

```
std::vector<uint8_t> DSM_PKR_message::npk
```

Definition at line 89 of file [osnma_data.h](#).

12.88.2.5 npkt

```
uint8_t DSM_PKR_message::npkt {}
```

Definition at line 93 of file [osnma_data.h](#).

12.88.2.6 npktid

```
uint8_t DSM_PKR_message::npktid {}
```

Definition at line 94 of file [osnma_data.h](#).

12.88.2.7 p_dp

```
std::vector<uint8_t> DSM_PKR_message::p_dp
```

Definition at line 90 of file [osnma_data.h](#).

The documentation for this class was generated from the following file:

- [osnma_data.h](#)

12.89 eph_t Struct Reference

Public Attributes

- int [sat](#)
- int [iode](#)
- int [iodc](#)
- int [sva](#)
- int [svh](#)
- int [week](#)
- int [code](#)
- int [flag](#)
- [gtime_t](#) [toe](#)
- [gtime_t](#) [toc](#)
- [gtime_t](#) [ttr](#)
- double [A](#)
- double [e](#)
- double [i0](#)
- double [OMG0](#)
- double [omg](#)
- double [M0](#)
- double [deln](#)
- double [OMGd](#)
- double [idot](#)
- double [crc](#)

- double [crs](#)
- double [cuc](#)
- double [cus](#)
- double [cic](#)
- double [cis](#)
- double [toes](#)
- double [fit](#)
- double [f0](#)
- double [f1](#)
- double [f2](#)
- double [tgd](#) [4]
- double [isc](#) [4]
- double [Adot](#)
- double [ndot](#)
- float [has_clock_correction_m](#)
- float [has_orbit_radial_correction_m](#)
- float [has_orbit_in_track_correction_m](#)
- float [has_orbit_cross_track_correction_m](#)
- bool [apply_has_corrections](#)

12.89.1 Detailed Description

Definition at line 433 of file [rtklib.h](#).

12.89.2 Member Data Documentation

12.89.2.1 A

double [eph_t::A](#)

Definition at line 444 of file [rtklib.h](#).

12.89.2.2 Adot

double [eph_t::Adot](#)

Definition at line 454 of file [rtklib.h](#).

12.89.2.3 apply_has_corrections

bool [eph_t::apply_has_corrections](#)

Definition at line 459 of file [rtklib.h](#).

12.89.2.4 cic

double [eph_t::cic](#)

Definition at line 445 of file [rtklib.h](#).

12.89.2.5 cis

double [eph_t::cis](#)

Definition at line 445 of file [rtklib.h](#).

12.89.2.6 code

int [eph_t::code](#)

Definition at line 440 of file [rtklib.h](#).

12.89.2.7 crc

```
double eph_t::crc
```

Definition at line 445 of file [rtklib.h](#).

12.89.2.8 crs

```
double eph_t::crs
```

Definition at line 445 of file [rtklib.h](#).

12.89.2.9 cuc

```
double eph_t::cuc
```

Definition at line 445 of file [rtklib.h](#).

12.89.2.10 cus

```
double eph_t::cus
```

Definition at line 445 of file [rtklib.h](#).

12.89.2.11 deln

```
double eph_t::deln
```

Definition at line 444 of file [rtklib.h](#).

12.89.2.12 e

```
double eph_t::e
```

Definition at line 444 of file [rtklib.h](#).

12.89.2.13 f0

```
double eph_t::f0
```

Definition at line 448 of file [rtklib.h](#).

12.89.2.14 f1

```
double eph_t::f1
```

Definition at line 448 of file [rtklib.h](#).

12.89.2.15 f2

```
double eph_t::f2
```

Definition at line 448 of file [rtklib.h](#).

12.89.2.16 fit

```
double eph_t::fit
```

Definition at line 447 of file [rtklib.h](#).

12.89.2.17 flag

```
int eph_t::flag
```

Definition at line 441 of file [rtklib.h](#).

12.89.2.18 has_clock_correction_m

```
float eph_t::has_clock_correction_m
```

Definition at line 455 of file [rtklib.h](#).

12.89.2.19 has_orbit_cross_track_correction_m

float eph_t::has_orbit_cross_track_correction_m
Definition at line 458 of file [rtklib.h](#).

12.89.2.20 has_orbit_in_track_correction_m

float eph_t::has_orbit_in_track_correction_m
Definition at line 457 of file [rtklib.h](#).

12.89.2.21 has_orbit_radial_correction_m

float eph_t::has_orbit_radial_correction_m
Definition at line 456 of file [rtklib.h](#).

12.89.2.22 i0

double eph_t::i0
Definition at line 444 of file [rtklib.h](#).

12.89.2.23 idot

double eph_t::idot
Definition at line 444 of file [rtklib.h](#).

12.89.2.24 iodic

int eph_t::iodic
Definition at line 436 of file [rtklib.h](#).

12.89.2.25 iode

int eph_t::iode
Definition at line 436 of file [rtklib.h](#).

12.89.2.26 isc

double eph_t::isc[4]
Definition at line 453 of file [rtklib.h](#).

12.89.2.27 M0

double eph_t::M0
Definition at line 444 of file [rtklib.h](#).

12.89.2.28 ndot

double eph_t::ndot
Definition at line 454 of file [rtklib.h](#).

12.89.2.29 omg

double eph_t::omg
Definition at line 444 of file [rtklib.h](#).

12.89.2.30 OMG0

double eph_t::OMG0
Definition at line 444 of file [rtklib.h](#).

12.89.2.31 OMGd

```
double eph_t::OMGd
```

Definition at line 444 of file [rtklib.h](#).

12.89.2.32 sat

```
int eph_t::sat
```

Definition at line 435 of file [rtklib.h](#).

12.89.2.33 sva

```
int eph_t::sva
```

Definition at line 437 of file [rtklib.h](#).

12.89.2.34 svh

```
int eph_t::svh
```

Definition at line 438 of file [rtklib.h](#).

12.89.2.35 tgd

```
double eph_t::tgd[4]
```

Definition at line 449 of file [rtklib.h](#).

12.89.2.36 toc

```
gtime_t eph_t::toc
```

Definition at line 442 of file [rtklib.h](#).

12.89.2.37 toe

```
gtime_t eph_t::toe
```

Definition at line 442 of file [rtklib.h](#).

12.89.2.38 toes

```
double eph_t::toes
```

Definition at line 446 of file [rtklib.h](#).

12.89.2.39 ttr

```
gtime_t eph_t::ttr
```

Definition at line 442 of file [rtklib.h](#).

12.89.2.40 week

```
int eph_t::week
```

Definition at line 439 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.90 erp_t Struct Reference

Public Attributes

- int [n](#)
- int [nmax](#)
- [erpd_t](#) * [data](#)

12.90.1 Detailed Description

Definition at line 393 of file [rtklib.h](#).

12.90.2 Member Data Documentation

12.90.2.1 data

`erpd_t* erpd_t::data`

Definition at line 396 of file [rtklib.h](#).

12.90.2.2 n

`int erpd_t::n`

Definition at line 395 of file [rtklib.h](#).

12.90.2.3 nmax

`int erpd_t::nmax`

Definition at line 395 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.91 erpd_t Struct Reference

Public Attributes

- double [mjd](#)
- double [xp](#)
- double [yp](#)
- double [xpr](#)
- double [ypr](#)
- double [ut1_utc](#)
- double [lod](#)

12.91.1 Detailed Description

Definition at line 383 of file [rtklib.h](#).

12.91.2 Member Data Documentation

12.91.2.1 lod

`double erpd_t::lod`

Definition at line 389 of file [rtklib.h](#).

12.91.2.2 mjd

`double erpd_t::mjd`

Definition at line 385 of file [rtklib.h](#).

12.91.2.3 ut1_utc

`double erpd_t::ut1_utc`

Definition at line 388 of file [rtklib.h](#).

12.91.2.4 xp

`double erpd_t::xp`

Definition at line 386 of file [rtklib.h](#).

12.91.2.5 xpr

double erpd_t::xpr

Definition at line 387 of file [rtklib.h](#).

12.91.2.6 yp

double erpd_t::yp

Definition at line 386 of file [rtklib.h](#).

12.91.2.7 ypr

double erpd_t::ypr

Definition at line 387 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.92 Exponential_Smoother Class Reference

Class that implements a first-order exponential smoother.

```
#include <exponential_smoother.h>
```

Public Member Functions

- [Exponential_Smoother](#) ()
Constructor.
- [~Exponential_Smoother](#) ()=default
Destructor.
- [Exponential_Smoother](#) ([Exponential_Smoother](#) &&)=default
Move operator.
- [Exponential_Smoother](#) & [operator=](#) ([Exponential_Smoother](#) &&)=default
Move assignment operator.
- void [set_alpha](#) (float alpha)
 $0 < \alpha < 1$. The higher, the most responsive, but more variance. Default value: 0.001
- void [set_samples_for_initialization](#) (int num_samples)
Number of samples averaged for initialization. Default value: 200.
- void [reset](#) ()
- void [set_min_value](#) (float value)
- void [set_offset](#) (float offset)
- float [smooth](#) (float raw)
- double [smooth](#) (double raw)

12.92.1 Detailed Description

Class that implements a first-order exponential smoother.

```
smoothed_value[k] = alpha * raw + (1-alpha) * smoothed_value[k-1]
```

The length of the initialization can be controlled with [set_samples_for_initialization\(int num_samples\)](#)

Definition at line 39 of file [exponential_smoother.h](#).

12.92.2 Constructor & Destructor Documentation

12.92.2.1 Exponential_Smoother() [1/2]

```
Exponential_Smoother::Exponential_Smoother ()
```

Constructor.

Referenced by [Exponential_Smoother\(\)](#), and [operator=\(\)](#).

12.92.2.2 ~Exponential_Smoother()

`Exponential_Smoother::~~Exponential_Smoother () [default]`
 Destructor.

12.92.2.3 Exponential_Smoother() [2/2]

`Exponential_Smoother::Exponential_Smoother (`
 `Exponential_Smoother &&) [default]`

Move operator.

References [Exponential_Smoother\(\)](#).

12.92.3 Member Function Documentation

12.92.3.1 operator=()

`Exponential_Smoother & Exponential_Smoother::operator= (`
 `Exponential_Smoother &&) [default]`

Move assignment operator.

References [Exponential_Smoother\(\)](#).

12.92.3.2 set_alpha()

`void Exponential_Smoother::set_alpha (`
 `float alpha)`

0 < alpha < 1. The higher, the most responsive, but more variance. Default value: 0.001

12.92.3.3 set_samples_for_initialization()

`void Exponential_Smoother::set_samples_for_initialization (`
 `int num_samples)`

Number of samples averaged for initialization. Default value: 200.

The documentation for this class was generated from the following file:

- [exponential_smoother.h](#)

12.93 exterr_t Struct Reference

Public Attributes

- int [ena](#) [4]
- double [cerr](#) [4][NFREQ *2]
- double [perr](#) [4][NFREQ *2]
- double [gpsglob](#) [NFREQ]
- double [gloicb](#) [NFREQ]

12.93.1 Detailed Description

Definition at line 926 of file [rtklib.h](#).

12.93.2 Member Data Documentation

12.93.2.1 cerr

`double exterr_t::cerr[4][NFREQ *2]`

Definition at line 929 of file [rtklib.h](#).

12.93.2.2 ena

`int exterr_t::ena[4]`

Definition at line 928 of file [rtklib.h](#).

12.93.2.3 gloicb

double exterr_t::gloicb[NFREQ]
Definition at line 932 of file [rtklib.h](#).

12.93.2.4 gpsglob

double exterr_t::gpsglob[NFREQ]
Definition at line 931 of file [rtklib.h](#).

12.93.2.5 perr

double exterr_t::perr[4][NFREQ *2]
Definition at line 930 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.94 fcbd_t Struct Reference

Public Attributes

- [gtime_t](#) ts
- [gtime_t](#) te
- double [bias](#) [MAXSAT][3]
- double [std](#) [MAXSAT][3]

12.94.1 Detailed Description

Definition at line 558 of file [rtklib.h](#).

12.94.2 Member Data Documentation

12.94.2.1 bias

double fcbd_t::bias[MAXSAT][3]
Definition at line 561 of file [rtklib.h](#).

12.94.2.2 std

double fcbd_t::std[MAXSAT][3]
Definition at line 562 of file [rtklib.h](#).

12.94.2.3 te

[gtime_t](#) fcbd_t::te
Definition at line 560 of file [rtklib.h](#).

12.94.2.4 ts

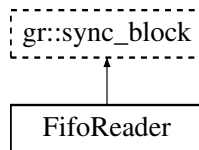
[gtime_t](#) fcbd_t::ts
Definition at line 560 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.95 FifoReader Class Reference

Inheritance diagram for FifoReader:



Public Types

- using `sptr` = `gnss_shared_ptr<FifoReader>`
static function to create a class instance

Public Member Functions

- bool `start` ()
initialize istream resource for FIFO
- int `work` (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Static Public Member Functions

- static `sptr make` (const std::string &file_name, const std::string &sample_type)

12.95.1 Detailed Description

Definition at line 31 of file `fifo_reader.h`.

12.95.2 Member Typedef Documentation

12.95.2.1 `sptr`

using `FifoReader::sptr` = `gnss_shared_ptr<FifoReader>`
static function to create a class instance
Definition at line 35 of file `fifo_reader.h`.

12.95.3 Member Function Documentation

12.95.3.1 `start()`

```
bool FifoReader::start ()
```

initialize istream resource for FIFO

The documentation for this class was generated from the following file:

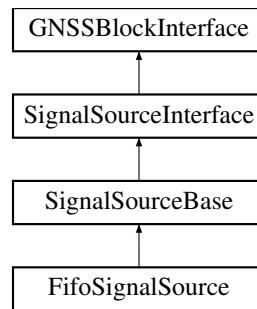
- `fifo_reader.h`

12.96 FifoSignalSource Class Reference

Class that reads a sample stream from a Unix FIFO.

```
#include <fifo_signal_source.h>
```

Inheritance diagram for FifoSignalSource:



Public Member Functions

- **FifoSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- void [connect](#) (gr::top_block_sptr top_block) override
override methods from [GnssBlockInterface](#)
- void [disconnect](#) (gr::top_block_sptr top_block) override
- size_t [item_size](#) () override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GnssBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_error=false)
utility for decoding passed ".item_type" values

12.96.1 Detailed Description

Class that reads a sample stream from a Unix FIFO.

This class supports the following properties:

.filename - the path to the input file

- may be overridden by the -signal_source or -s command-line arguments

.sample_type - data type read out from the FIFO. default is short ;

- note: not output format. that is always gr_complex

.dump - whether to archive input data

.dump_filename - if dumping, path to file for output

Definition at line 50 of file [fifo_signal_source.h](#).

12.96.2 Member Function Documentation

12.96.2.1 connect()

```
void FifoSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

override methods from [GNSSBlockInterface](#)
Implements [GNSSBlockInterface](#).

12.96.2.2 disconnect()

```
void FifoSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.96.2.3 get_left_block()

```
gr::basic_block_sptr FifoSignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.96.2.4 get_right_block()

```
gr::basic_block_sptr FifoSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.96.2.5 item_size()

```
size_t FifoSignalSource::item_size () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

The documentation for this class was generated from the following file:

- [fifo_signal_source.h](#)

12.97 file_t Struct Reference

Public Attributes

- FILE * [fp](#) = nullptr
- FILE * [fp_tag](#) = nullptr
- FILE * [fp_tmp](#) = nullptr
- FILE * [fp_tag_tmp](#) = nullptr
- std::string [path](#)
- std::string [openpath](#)
- int [mode](#) = 0
- int [timetag](#)
- int [repmode](#) = 0
- int [offset](#) = 0
- [gtime_t](#) [time](#) = {}
- [gtime_t](#) [wtime](#) = {}
- unsigned int [tick](#) = 0
- unsigned int [tick_f](#) = 0
- unsigned int [fpos](#) = 0
- double [start](#) = 0
- double [speed](#) = 0
- double [swapintv](#) = 0
- lock_t [lock](#)

12.97.1 Detailed Description

Definition at line 1118 of file [rtklib.h](#).

12.97.2 Member Data Documentation

12.97.2.1 fp

```
FILE* file_t::fp = nullptr
```

Definition at line 1120 of file [rtklib.h](#).

12.97.2.2 fp_tag

```
FILE* file_t::fp_tag = nullptr
```

Definition at line 1121 of file [rtklib.h](#).

12.97.2.3 fp_tag_tmp

```
FILE* file_t::fp_tag_tmp = nullptr
```

Definition at line 1123 of file [rtklib.h](#).

12.97.2.4 fp_tmp

```
FILE* file_t::fp_tmp = nullptr
```

Definition at line 1122 of file [rtklib.h](#).

12.97.2.5 fpos

```
unsigned int file_t::fpos = 0
```

Definition at line 1134 of file [rtklib.h](#).

12.97.2.6 lock

```
lock_t file_t::lock
```

Definition at line 1138 of file [rtklib.h](#).

12.97.2.7 mode

```
int file_t::mode = 0
```

Definition at line 1126 of file [rtklib.h](#).

12.97.2.8 offset

```
int file_t::offset = 0
```

Definition at line 1129 of file [rtklib.h](#).

12.97.2.9 openpath

```
std::string file_t::openpath
```

Definition at line 1125 of file [rtklib.h](#).

12.97.2.10 path

```
std::string file_t::path
```

Definition at line 1124 of file [rtklib.h](#).

12.97.2.11 repmode

```
int file_t::repmode = 0
```

Definition at line 1128 of file [rtklib.h](#).

12.97.2.12 speed

```
double file_t::speed = 0
```

Definition at line 1136 of file [rtklib.h](#).

12.97.2.13 start

```
double file_t::start = 0
```

Definition at line 1135 of file [rtklib.h](#).

12.97.2.14 swapintv

```
double file_t::swapintv = 0
```

Definition at line 1137 of file [rtklib.h](#).

12.97.2.15 tick

```
unsigned int file_t::tick = 0
```

Definition at line 1132 of file [rtklib.h](#).

12.97.2.16 tick_f

```
unsigned int file_t::tick_f = 0
```

Definition at line 1133 of file [rtklib.h](#).

12.97.2.17 time

```
gtime_t file_t::time = {}
```

Definition at line 1130 of file [rtklib.h](#).

12.97.2.18 timetag

```
int file_t::timetag
```

Definition at line 1127 of file [rtklib.h](#).

12.97.2.19 wtime

```
gtime_t file_t::wtime = {}
```

Definition at line 1131 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

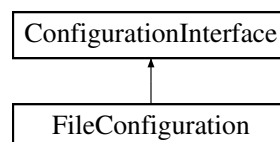
- [rtklib.h](#)

12.98 FileConfiguration Class Reference

This class is an implementation of the interface [ConfigurationInterface](#).

```
#include <file_configuration.h>
```

Inheritance diagram for FileConfiguration:



Public Member Functions

- **FileConfiguration** (std::string filename)
- std::string **property** (std::string property_name, std::string default_value) const override
- bool **property** (std::string property_name, bool default_value) const override
- int64_t **property** (std::string property_name, int64_t default_value) const override
- uint64_t **property** (std::string property_name, uint64_t default_value) const override
- int32_t **property** (std::string property_name, int32_t default_value) const override
- uint32_t **property** (std::string property_name, uint32_t default_value) const override
- int16_t **property** (std::string property_name, int16_t default_value) const override
- uint16_t **property** (std::string property_name, uint16_t default_value) const override
- float **property** (std::string property_name, float default_value) const override
- double **property** (std::string property_name, double default_value) const override
- void **set_property** (std::string property_name, std::string value) override
- bool **is_present** (const std::string &property_name) const override
- bool **has_section** () const

12.98.1 Detailed Description

This class is an implementation of the interface [ConfigurationInterface](#).

Derived from [ConfigurationInterface](#), this class implements an interface to a configuration file. This implementation has a text file as the source for the values of the parameters. The file is in the INI format, containing sections and pairs of names and values. For more information about the INI format, see https://en.wikipedia.org/wiki/INI_file

Definition at line 48 of file [file_configuration.h](#).

12.98.2 Member Function Documentation

12.98.2.1 is_present()

```
bool FileConfiguration::is_present (
    const std::string & property_name) const    [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.98.2.2 property() [1/10]

```
bool FileConfiguration::property (
    std::string property_name,
    bool default_value) const    [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.98.2.3 property() [2/10]

```
double FileConfiguration::property (
    std::string property_name,
    double default_value) const    [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.98.2.4 property() [3/10]

```
float FileConfiguration::property (
    std::string property_name,
    float default_value) const    [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.98.2.5 property() [4/10]

```
int16_t FileConfiguration::property (
    std::string property_name,
    int16_t default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.98.2.6 property() [5/10]

```
int32_t FileConfiguration::property (
    std::string property_name,
    int32_t default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.98.2.7 property() [6/10]

```
int64_t FileConfiguration::property (
    std::string property_name,
    int64_t default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.98.2.8 property() [7/10]

```
std::string FileConfiguration::property (
    std::string property_name,
    std::string default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.98.2.9 property() [8/10]

```
uint16_t FileConfiguration::property (
    std::string property_name,
    uint16_t default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.98.2.10 property() [9/10]

```
uint32_t FileConfiguration::property (
    std::string property_name,
    uint32_t default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.98.2.11 property() [10/10]

```
uint64_t FileConfiguration::property (
    std::string property_name,
    uint64_t default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.98.2.12 set_property()

```
void FileConfiguration::set_property (
    std::string property_name,
    std::string value) [override], [virtual]
```

Implements [ConfigurationInterface](#).

The documentation for this class was generated from the following file:

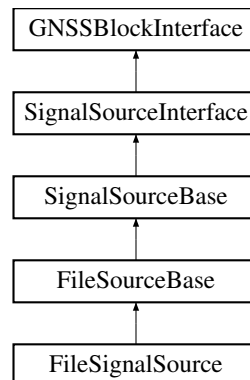
- [file_configuration.h](#)

12.99 FileSignalSource Class Reference

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

```
#include <file_signal_source.h>
```

Inheritance diagram for FileSignalSource:



Public Member Functions

- **FileSignalSource** ([ConfigurationInterface](#) const *configuration, std::string const &role, unsigned int in_streams, unsigned int out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue)

Public Member Functions inherited from [FileSourceBase](#)

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- std::string [filename](#) () const
The file to read.
- std::string [item_type](#) () const
The item type.
- size_t [item_size](#) () override
The configured size of each item.
- virtual size_t [item_size](#) () const
- bool [repeat](#) () const
Whether to repeat reading after end-of-file.
- int64_t [sampling_frequency](#) () const
The sampling frequency of the source file.
- uint64_t [samples](#) () const
The number of samples in the file.

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [FileSourceBase](#)

- [FileSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string const &role, std::string impl, [Concurrent_Queue](#)< pmt::pmt_t > *queue, std::string default_item_type="short")
Constructor.
- void [init](#) ()
Perform post-construction initialization.
- virtual std::tuple< size_t, bool > [itemTypeToSize](#) ()
Compute the item size, from the [item_type](#)(). Subclasses may constrain types that don't make.
- virtual double [packetsPerSample](#) () const
The number of (possibly unpacked) samples in a (raw) file sample (default=1)
- virtual uint64_t [samplesToSkip](#) () const
Compute the number of samples to skip.
- uint64_t [computeSamplesInFile](#) () const
Compute the number of samples in the file.
- virtual gnss_shared_ptr< gr::block > [source](#) () const
Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.
- virtual size_t [source_item_size](#) () const
For complex source chains, the size of the file item may not be the same as the size of the.
- bool [is_complex](#) () const
- gnss_shared_ptr< gr::block > [file_source](#) () const
- gnss_shared_ptr< gr::block > [valve](#) () const
- gnss_shared_ptr< gr::block > [throttle](#) () const
- gnss_shared_ptr< gr::block > [sink](#) () const
- SensorDataSource::sptr [sensor_data_source](#) () const
- gr::blocks::file_source::sptr [create_file_source](#) ()
- gr::blocks::throttle::sptr [create_throttle](#) ()
- gnss_shared_ptr< gr::block > [create_valve](#) ()
- gr::blocks::file_sink::sptr [create_sink](#) ()
- SensorDataSource::sptr [create_sensor_data_source](#) ()
- virtual void [create_file_source_hook](#) ()
- virtual void [create_throttle_hook](#) ()
- virtual void [create_valve_hook](#) ()
- virtual void [create_sink_hook](#) ()
- virtual void [pre_connect_hook](#) (gr::top_block_sptr top_block)
- virtual void [post_connect_hook](#) (gr::top_block_sptr top_block)
- virtual void [pre_disconnect_hook](#) (gr::top_block_sptr top_block)
- virtual void [post_disconnect_hook](#) (gr::top_block_sptr top_block)

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↵ error=false)
utility for decoding passed ".item_type" values

12.99.1 Detailed Description

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

Definition at line 41 of file [file_signal_source.h](#).

The documentation for this class was generated from the following file:

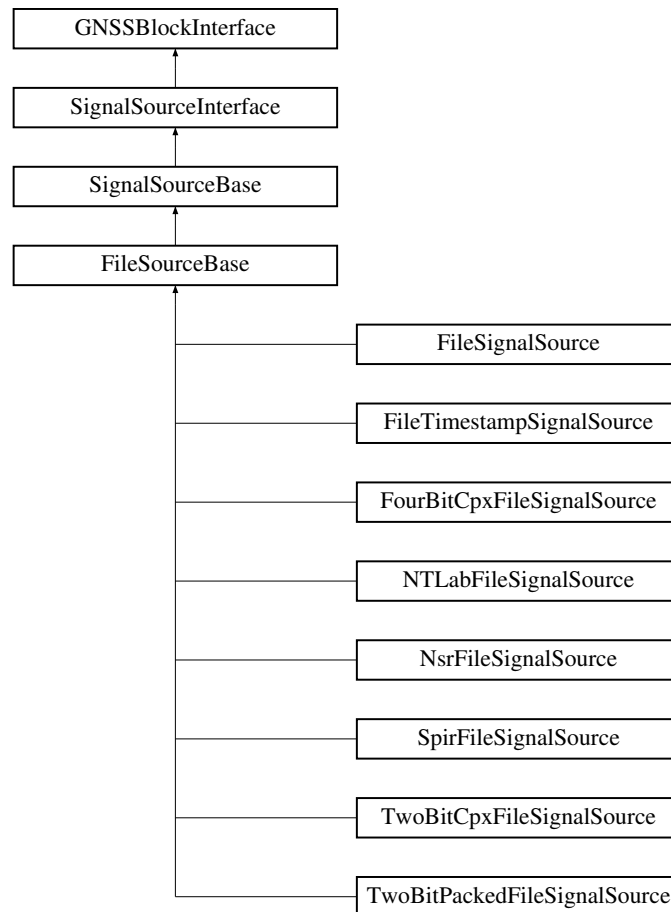
- [file_signal_source.h](#)

12.100 FileSourceBase Class Reference

Base class to file-oriented [SignalSourceBase](#) GNSS blocks.

```
#include <file_source_base.h>
```

Inheritance diagram for FileSourceBase:



Public Member Functions

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- std::string [filename](#) () const
The file to read.
- std::string [item_type](#) () const
The item type.
- size_t [item_size](#) () override
The configured size of each item.
- virtual size_t [item_size](#) () const
- bool [repeat](#) () const
Whether to repeat reading after end-of-file.
- int64_t [sampling_frequency](#) () const
The sampling frequency of the source file.
- uint64_t [samples](#) () const
The number of samples in the file.

Public Member Functions inherited from [SignalSourceBase](#)

- `std::string role ()` final
- `std::string implementation ()` final
- `size_t getRfChannels ()` const override
- `gr::basic_block_sptr get_left_block ()` override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual `gr::basic_block_sptr get_left_block (int RF_channel)`
- virtual `gr::basic_block_sptr get_right_block (int RF_channel)`
- virtual void `start ()`

Start the flow of samples if needed.

Protected Member Functions

- [FileSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string const &role, std::string impl, [Concurrent_Queue](#)< pmt::pmt_t > *queue, std::string default_item_type="short")

Constructor.

- void `init ()`

Perform post-construction initialization.

- virtual `std::tuple< size_t, bool > itemTypeToSize ()`

Compute the item size, from the [item_type\(\)](#). Subclasses may constrain types that don't make.

- virtual double `packetsPerSample ()` const

The number of (possibly unpacked) samples in a (raw) file sample (default=1)

- virtual `uint64_t samplesToSkip ()` const

Compute the number of samples to skip.

- `uint64_t computeSamplesInFile ()` const

Compute the number of samples in the file.

- virtual `gnss_shared_ptr< gr::block > source ()` const

Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.

- virtual `size_t source_item_size ()` const

For complex source chains, the size of the file item may not be the same as the size of the.

- bool `is_complex ()` const
- `gnss_shared_ptr< gr::block > file_source ()` const
- `gnss_shared_ptr< gr::block > valve ()` const
- `gnss_shared_ptr< gr::block > throttle ()` const
- `gnss_shared_ptr< gr::block > sink ()` const
- `SensorDataSource::sptr sensor_data_source ()` const
- `gr::blocks::file_source::sptr create_file_source ()`
- `gr::blocks::throttle::sptr create_throttle ()`
- `gnss_shared_ptr< gr::block > create_valve ()`
- `gr::blocks::file_sink::sptr create_sink ()`
- `SensorDataSource::sptr create_sensor_data_source ()`
- virtual void `create_file_source_hook ()`
- virtual void `create_throttle_hook ()`
- virtual void `create_valve_hook ()`
- virtual void `create_sink_hook ()`
- virtual void `pre_connect_hook (gr::top_block_sptr top_block)`
- virtual void `post_connect_hook (gr::top_block_sptr top_block)`
- virtual void `pre_disconnect_hook (gr::top_block_sptr top_block)`
- virtual void `post_disconnect_hook (gr::top_block_sptr top_block)`

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↵ error=false)
utility for decoding passed ".item_type" values

12.100.1 Detailed Description

Base class to file-oriented [SignalSourceBase](#) GNSS blocks.

This class supports the following properties:

.filename - the path to the input file

- may be overridden by the -signal_source or -s command-line arguments

.samples - number of samples to process (default 0)

- if not specified or 0, read the entire file; otherwise stop after that many samples

.sampling_frequency - the frequency of the sampled data (samples/second)

.item_type - data type of the samples (default "short")

.header_size - the size of a prefixed header to skip in "samples" (default 0)

.seconds_to_skip - number of seconds of lead-in data to skip over (default 0)

.enable_throttle_control - whether to stop reading if the upstream buffer is full (default false)

.repeat - whether to rewind and continue at end of file (default false)

(probably abstracted to the base class)

.dump - whether to archive input data

.dump_filename - if dumping, path to file for output

Definition at line 68 of file [file_source_base.h](#).

12.100.2 Constructor & Destructor Documentation

12.100.2.1 FileSourceBase()

```
FileSourceBase::FileSourceBase (
    ConfigurationInterface const * configuration,
    std::string const & role,
    std::string impl,
    Concurrent_Queue< pmt::pmt_t > * queue,
    std::string default_item_type = "short") [protected]
```

Constructor.

Subclasses may want to assert default item types that are appropriate to the specific file type supported. Rather than require the item type to be specified in the config file, allow sub-classes to impose their will

12.100.3 Member Function Documentation

12.100.3.1 computeSamplesInFile()

```
uint64_t FileSourceBase::computeSamplesInFile () const [protected]
```

Compute the number of samples in the file.

12.100.3.2 connect()

```
void FileSourceBase::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.100.3.3 disconnect()

```
void FileSourceBase::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.100.3.4 filename()

```
std::string FileSourceBase::filename () const
```

The file to read.

12.100.3.5 get_left_block()

```
gr::basic_block_sptr FileSourceBase::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.100.3.6 get_right_block()

```
gr::basic_block_sptr FileSourceBase::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.100.3.7 init()

```
void FileSourceBase::init () [protected]
```

Perform post-construction initialization.

12.100.3.8 item_size()

```
size_t FileSourceBase::item_size () [override], [virtual]
```

The configured size of each item.

Implements [GNSSBlockInterface](#).

12.100.3.9 item_type()

```
std::string FileSourceBase::item_type () const
```

The item type.

12.100.3.10 itemTypeToSize()

```
virtual std::tuple< size_t, bool > FileSourceBase::itemTypeToSize () [protected], [virtual]
```

Compute the item size, from the [item_type\(\)](#). Subclasses may constrain types that don't make.

Reimplemented in [FourBitCpxFileSignalSource](#), [NsrFileSignalSource](#), [NTLabFileSignalSource](#), [SpirFileSignalSource](#), [TwoBitCpxFileSignalSource](#), and [TwoBitPackedFileSignalSource](#).

12.100.3.11 packetsPerSample()

```
virtual double FileSourceBase::packetsPerSample () const [protected], [virtual]
```

The number of (possibly unpacked) samples in a (raw) file sample (default=1)

Reimplemented in [FourBitCpxFileSignalSource](#), [NsrFileSignalSource](#), [NTLabFileSignalSource](#), [TwoBitCpxFileSignalSource](#), and [TwoBitPackedFileSignalSource](#).

12.100.3.12 repeat()

```
bool FileSourceBase::repeat () const
```

Whether to repeat reading after end-of-file.

12.100.3.13 samples()

```
uint64_t FileSourceBase::samples () const
```

The number of samples in the file.

12.100.3.14 samplesToSkip()

```
virtual uint64_t FileSourceBase::samplesToSkip () const [protected], [virtual]
```

Compute the number of samples to skip.

12.100.3.15 sampling_frequency()

```
int64_t FileSourceBase::sampling_frequency () const
```

The sampling frequency of the source file.

12.100.3.16 source()

```
virtual gnss_shared_ptr< gr::block > FileSourceBase::source () const [protected], [virtual]
```

Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.

Reimplemented in [FileTimestampSignalSource](#), [FourBitCpxFileSignalSource](#), [NsrFileSignalSource](#), [NTLabFileSignalSource](#), [SpirFileSignalSource](#), [TwoBitCpxFileSignalSource](#), and [TwoBitPackedFileSignalSource](#).

12.100.3.17 source_item_size()

```
virtual size_t FileSourceBase::source_item_size () const [protected], [virtual]
```

For complex source chains, the size of the file item may not be the same as the size of the.

The documentation for this class was generated from the following file:

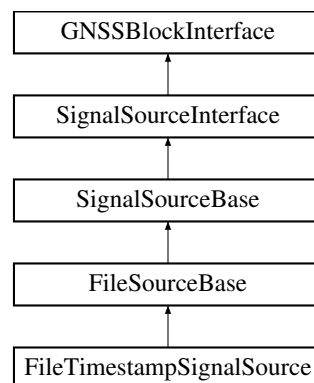
- [file_source_base.h](#)

12.101 FileTimestampSignalSource Class Reference

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

```
#include <file_timestamp_signal_source.h>
```

Inheritance diagram for FileTimestampSignalSource:



Public Member Functions

- **FileTimestampSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue)

Public Member Functions inherited from [FileSourceBase](#)

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- std::string [filename](#) () const

The file to read.

- std::string [item_type](#) () const
The item type.
- size_t [item_size](#) () override
The configured size of each item.
- virtual size_t [item_size](#) () const
- bool [repeat](#) () const
Whether to repeat reading after end-of-file.
- int64_t [sampling_frequency](#) () const
The sampling frequency of the source file.
- uint64_t [samples](#) () const
The number of samples in the file.

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Protected Member Functions

- gnss_shared_ptr< gr::block > [source](#) () const override
Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.
- void [create_file_source_hook](#) () override
- void [pre_connect_hook](#) (gr::top_block_sptr top_block) override
- void [pre_disconnect_hook](#) (gr::top_block_sptr top_block) override

Protected Member Functions inherited from [FileSourceBase](#)

- [FileSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string const &role, std::string impl, [Concurrent_Queue](#)< pmt::pmt_t > *queue, std::string default_item_type="short")
Constructor.
- void [init](#) ()
Perform post-construction initialization.
- virtual std::tuple< size_t, bool > [itemTypeToSize](#) ()
Compute the item size, from the [item_type](#)().* Subclasses may constrain types that don't make.*
- virtual double [packetsPerSample](#) () const
The number of (possibly unpacked) samples in a (raw) file sample (default=1)
- virtual uint64_t [samplesToSkip](#) () const
Compute the number of samples to skip.
- uint64_t [computeSamplesInFile](#) () const
Compute the number of samples in the file.
- virtual size_t [source_item_size](#) () const
For complex source chains, the size of the file item may not be the same as the size of the.
- bool [is_complex](#) () const
- gnss_shared_ptr< gr::block > [file_source](#) () const

- gnss_shared_ptr< gr::block > **valve** () const
- gnss_shared_ptr< gr::block > **throttle** () const
- gnss_shared_ptr< gr::block > **sink** () const
- SensorDataSource::sptr **sensor_data_source** () const
- gr::blocks::file_source::sptr **create_file_source** ()
- gr::blocks::throttle::sptr **create_throttle** ()
- gnss_shared_ptr< gr::block > **create_valve** ()
- gr::blocks::file_sink::sptr **create_sink** ()
- SensorDataSource::sptr **create_sensor_data_source** ()
- virtual void **create_throttle_hook** ()
- virtual void **create_valve_hook** ()
- virtual void **create_sink_hook** ()
- virtual void **post_connect_hook** (gr::top_block_sptr top_block)
- virtual void **post_disconnect_hook** (gr::top_block_sptr top_block)

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↵ error=false)
utility for decoding passed ".item_type" values

12.101.1 Detailed Description

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
Definition at line 37 of file [file_timestamp_signal_source.h](#).

12.101.2 Member Function Documentation

12.101.2.1 create_file_source_hook()

```
void FileTimestampSignalSource::create_file_source_hook () [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.101.2.2 pre_connect_hook()

```
void FileTimestampSignalSource::pre_connect_hook (
    gr::top_block_sptr top_block) [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.101.2.3 pre_disconnect_hook()

```
void FileTimestampSignalSource::pre_disconnect_hook (
    gr::top_block_sptr top_block) [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.101.2.4 source()

```
gnss_shared_ptr< gr::block > FileTimestampSignalSource::source () const [override], [protected], [virtual]
```

Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.

Reimplemented from [FileSourceBase](#).

The documentation for this class was generated from the following file:

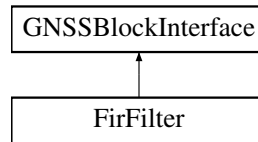
- [file_timestamp_signal_source.h](#)

12.102 FirFilter Class Reference

This class adapts a GNU Radio `gr_fir_filter` designed with `pm_remez`.

```
#include <fir_filter.h>
```

Inheritance diagram for FirFilter:



Public Member Functions

- `FirFilter` (const `ConfigurationInterface` *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- `~FirFilter` ()=default
Destructor.
- std::string `role` () override
- std::string `implementation` () override
Returns "Fir_Filter".
- size_t `item_size` () override
- void `connect` (gr::top_block_sptr top_block) override
- void `disconnect` (gr::top_block_sptr top_block) override
- gr::basic_block_sptr `get_left_block` () override
- gr::basic_block_sptr `get_right_block` () override

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr `get_left_block` (int RF_channel)
- virtual gr::basic_block_sptr `get_right_block` (int RF_channel)
- virtual void `start` ()

Start the flow of samples if needed.

12.102.1 Detailed Description

This class adapts a GNU Radio `gr_fir_filter` designed with `pm_remez`.

See Parks-McClellan FIR filter design, https://en.wikipedia.org/wiki/Parks-McClellan_filter_design_algorithm Calculates the optimal (in the Chebyshev/minimax sense) FIR filter impulse response given a set of band edges, the desired response on those bands, and the weight given to the error in those bands.

Definition at line 59 of file `fir_filter.h`.

12.102.2 Constructor & Destructor Documentation

12.102.2.1 FirFilter()

```

FirFilter::FirFilter (
    const ConfigurationInterface * configuration,
    std::string role,
    unsigned int in_streams,
    unsigned int out_streams)

```

Constructor.

12.102.2.2 ~FirFilter()

`FirFilter::~~FirFilter () [default]`
Destructor.

12.102.3 Member Function Documentation

12.102.3.1 connect()

`void FirFilter::connect (`
`gr::top_block_sptr top_block) [override], [virtual]`
Implements [GNSSBlockInterface](#).

12.102.3.2 disconnect()

`void FirFilter::disconnect (`
`gr::top_block_sptr top_block) [override], [virtual]`
Implements [GNSSBlockInterface](#).

12.102.3.3 get_left_block()

`gr::basic_block_sptr FirFilter::get_left_block () [override], [virtual]`
Implements [GNSSBlockInterface](#).

12.102.3.4 get_right_block()

`gr::basic_block_sptr FirFilter::get_right_block () [override], [virtual]`
Implements [GNSSBlockInterface](#).

12.102.3.5 implementation()

`std::string FirFilter::implementation () [inline], [override], [virtual]`
Returns "Fir_Filter".
Implements [GNSSBlockInterface](#).
Definition at line 77 of file [fir_filter.h](#).

12.102.3.6 item_size()

`size_t FirFilter::item_size () [inline], [override], [virtual]`
Implements [GNSSBlockInterface](#).
Definition at line 82 of file [fir_filter.h](#).

12.102.3.7 role()

`std::string FirFilter::role () [inline], [override], [virtual]`
Implements [GNSSBlockInterface](#).
Definition at line 71 of file [fir_filter.h](#).

The documentation for this class was generated from the following file:

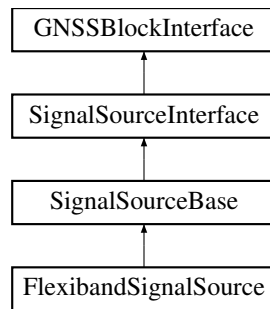
- [fir_filter.h](#)

12.103 FlexibandSignalSource Class Reference

This class configures and reads samples from Teleorbit Flexiband front-end. This software requires a Flexiband GNU Radio driver installed (not included with GNSS-SDR).

```
#include <flexiband_signal_source.h>
```

Inheritance diagram for FlexibandSignalSource:



Public Member Functions

- **FlexibandSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- gr::basic_block_sptr [get_right_block](#) (int RF_channel) override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↔ error=false)
utility for decoding passed ".item_type" values

12.103.1 Detailed Description

This class configures and reads samples from Teleorbit Flexiband front-end. This software requires a Flexiband GNU Radio driver installed (not included with GNSS-SDR).

Definition at line 48 of file [flexiband_signal_source.h](#).

12.103.2 Member Function Documentation

12.103.2.1 connect()

```
void FlexibandSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.103.2.2 disconnect()

```
void FlexibandSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.103.2.3 get_left_block()

```
gr::basic_block_sptr FlexibandSignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.103.2.4 get_right_block() [1/2]

```
gr::basic_block_sptr FlexibandSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.103.2.5 get_right_block() [2/2]

```
gr::basic_block_sptr FlexibandSignalSource::get_right_block (
    int RF_channel) [override], [virtual]
```

Reimplemented from [GNSSBlockInterface](#).

12.103.2.6 item_size()

```
size_t FlexibandSignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

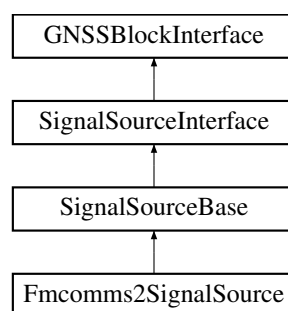
Definition at line 57 of file [flexiband_signal_source.h](#).

The documentation for this class was generated from the following file:

- [flexiband_signal_source.h](#)

12.104 Fmcomms2SignalSource Class Reference

Inheritance diagram for Fmcomms2SignalSource:



Public Member Functions

- **Fmcomms2SignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [SignalSourceBase](#)

- `std::string` [role](#) () final
- `std::string` [implementation](#) () final
- `size_t` [getRfChannels](#) () const override
- `gr::basic_block_sptr` [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual `gr::basic_block_sptr` [get_left_block](#) (int RF_channel)
- virtual `gr::basic_block_sptr` [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, `std::string` role, `std::string` impl)
Constructor.
- `size_t` [decode_item_type](#) (`std::string` const &item_type, `bool` *is_interleaved=nullptr, `bool` throw_on_↵
error=false)
utility for decoding passed ".item_type" values

12.104.1 Detailed Description

Definition at line 44 of file [fmcomms2_signal_source.h](#).

12.104.2 Member Function Documentation

12.104.2.1 connect()

```
void Fmcomms2SignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.104.2.2 disconnect()

```
void Fmcomms2SignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.104.2.3 get_left_block()

```
gr::basic_block_sptr Fmcomms2SignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.104.2.4 get_right_block()

```
gr::basic_block_sptr Fmcomms2SignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.104.2.5 item_size()

```
size_t Fmcomms2SignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

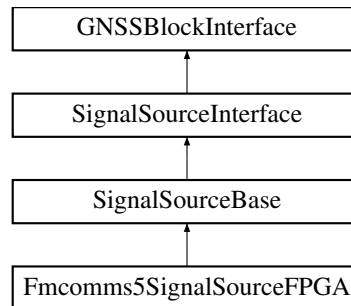
Definition at line 53 of file [fmcomms2_signal_source.h](#).

The documentation for this class was generated from the following file:

- [fmcomms2_signal_source.h](#)

12.105 Fmcomms5SignalSourceFPGA Class Reference

Inheritance diagram for Fmcomms5SignalSourceFPGA:



Public Member Functions

- **Fmcomms5SignalSourceFPGA** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↔ error=false)
utility for decoding passed ".item_type" values

12.105.1 Detailed Description

Definition at line 46 of file [fmcomms5_signal_source_fpga.h](#).

12.105.2 Member Function Documentation

12.105.2.1 connect()

```
void Fmcomms5SignalSourceFPGA::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.105.2.2 disconnect()

```
void Fmcomms5SignalSourceFPGA::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.105.2.3 get_left_block()

```
gr::basic_block_sptr Fmcomms5SignalSourceFPGA::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.105.2.4 get_right_block()

```
gr::basic_block_sptr Fmcomms5SignalSourceFPGA::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.105.2.5 item_size()

```
size_t Fmcomms5SignalSourceFPGA::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 55 of file [fmcomms5_signal_source_fpga.h](#).

The documentation for this class was generated from the following file:

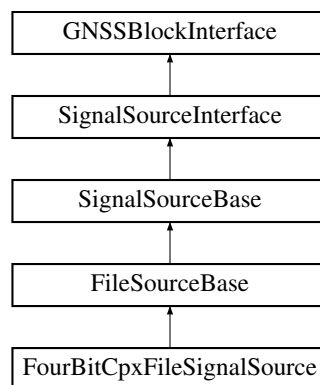
- [fmcomms5_signal_source_fpga.h](#)

12.106 FourBitCpxFileSignalSource Class Reference

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

```
#include <four_bit_cpx_file_signal_source.h>
```

Inheritance diagram for FourBitCpxFileSignalSource:



Public Member Functions

- **FourBitCpxFileSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue)

Public Member Functions inherited from [FileSourceBase](#)

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- std::string [filename](#) () const
The file to read.
- std::string [item_type](#) () const
The item type.
- size_t [item_size](#) () override
The configured size of each item.
- virtual size_t [item_size](#) () const
- bool [repeat](#) () const
Whether to repeat reading after end-of-file.
- int64_t [sampling_frequency](#) () const
The sampling frequency of the source file.
- uint64_t [samples](#) () const
The number of samples in the file.

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Protected Member Functions

- std::tuple< size_t, bool > [itemTypeToSize](#) () override
Compute the item size, from the [item_type](#)(). Subclasses may constrain types that don't make.
- double [packetsPerSample](#) () const override
The number of (possibly unpacked) samples in a (raw) file sample (default=1)
- gnss_shared_ptr< gr::block > [source](#) () const override
Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.
- void [create_file_source_hook](#) () override
- void [pre_connect_hook](#) (gr::top_block_sptr top_block) override
- void [pre_disconnect_hook](#) (gr::top_block_sptr top_block) override

Protected Member Functions inherited from [FileSourceBase](#)

- [FileSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string const &role, std::string impl, [Concurrent_Queue](#)< pmt::pmt_t > *queue, std::string default_item_type="short")
Constructor.
- void [init](#) ()
Perform post-construction initialization.

- virtual uint64_t [samplesToSkip](#) () const
Compute the number of samples to skip.
- uint64_t [computeSamplesInFile](#) () const
Compute the number of samples in the file.
- virtual size_t [source_item_size](#) () const
For complex source chains, the size of the file item may not be the same as the size of the.
- bool [is_complex](#) () const
- gnss_shared_ptr< gr::block > [file_source](#) () const
- gnss_shared_ptr< gr::block > [valve](#) () const
- gnss_shared_ptr< gr::block > [throttle](#) () const
- gnss_shared_ptr< gr::block > [sink](#) () const
- SensorDataSource::sptr [sensor_data_source](#) () const
- gr::blocks::file_source::sptr [create_file_source](#) ()
- gr::blocks::throttle::sptr [create_throttle](#) ()
- gnss_shared_ptr< gr::block > [create_valve](#) ()
- gr::blocks::file_sink::sptr [create_sink](#) ()
- SensorDataSource::sptr [create_sensor_data_source](#) ()
- virtual void [create_throttle_hook](#) ()
- virtual void [create_valve_hook](#) ()
- virtual void [create_sink_hook](#) ()
- virtual void [post_connect_hook](#) (gr::top_block_sptr top_block)
- virtual void [post_disconnect_hook](#) (gr::top_block_sptr top_block)

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_error=false)
utility for decoding passed ".item_type" values

12.106.1 Detailed Description

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
Definition at line 43 of file [four_bit_cpx_file_signal_source.h](#).

12.106.2 Member Function Documentation

12.106.2.1 [create_file_source_hook\(\)](#)

void FourBitCpxFileSignalSource::create_file_source_hook () [override], [protected], [virtual]
Reimplemented from [FileSourceBase](#).

12.106.2.2 [itemTypeToSize\(\)](#)

std::tuple< size_t, bool > FourBitCpxFileSignalSource::itemTypeToSize () [override], [protected], [virtual]
Compute the item size, from the [item_type\(\)](#). Subclasses may constrain types that don't make.
Reimplemented from [FileSourceBase](#).

12.106.2.3 [packetsPerSample\(\)](#)

double FourBitCpxFileSignalSource::packetsPerSample () const [override], [protected], [virtual]
The number of (possibly unpacked) samples in a (raw) file sample (default=1)
Reimplemented from [FileSourceBase](#).

12.106.2.4 pre_connect_hook()

```
void FourBitCpxFileSignalSource::pre_connect_hook (
    gr::top_block_sptr top_block) [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.106.2.5 pre_disconnect_hook()

```
void FourBitCpxFileSignalSource::pre_disconnect_hook (
    gr::top_block_sptr top_block) [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.106.2.6 source()

```
gnss_shared_ptr< gr::block > FourBitCpxFileSignalSource::source () const [override], [protected],
[virtual]
```

Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.

Reimplemented from [FileSourceBase](#).

The documentation for this class was generated from the following file:

- [four_bit_cpx_file_signal_source.h](#)

12.107 Fpga_Acquisition Class Reference

Class that implements carrier wipe-off and correlators.

```
#include <fpga_acquisition.h>
```

Public Member Functions

- [Fpga_Acquisition](#) (std::string device_name, uint32_t select_queue, std::vector< std::pair< uint32_t, uint32_t > > &downsampling_filter_specs, uint32_t &max_FFT_size)
Constructor.
- [~Fpga_Acquisition](#) ()=default
Destructor.
- void [init](#) (uint32_t nsamples, uint32_t d_fft_size, int64_t resampled_fs, uint32_t downsampling_filter_num, uint32_t excludelimit, uint32_t *all_fft_codes)
Initialize acquisition parameters.
- bool [set_local_code](#) (uint32_t PRN)
Select the code with the chosen PRN.
- void [set_doppler_sweep](#) (uint32_t num_sweeps, uint32_t doppler_step, int32_t doppler_min)
Configure the doppler sweep parameters in the FPGA.
- void [run_acquisition](#) ()
Run the acquisition process in the FPGA.
- void [read_acquisition_results](#) (uint32_t *max_index, float *firstpeak, float *secondpeak, uint64_t *initial_sample, float *power_sum, uint32_t *doppler_index, uint32_t *total_blk_exp)
Read the results of the acquisition process.
- void [reset_acquisition](#) ()
Reset the FPGA PL.
- void [stop_acquisition](#) ()
stop the acquisition and the FPGA modules.
- void [set_block_exp](#) (uint32_t total_block_exp)
Set the block exponent of the FFT in the FPGA.
- void [write_local_code](#) (void)
Write the PRN code in the FPGA.

- void [configure_acquisition](#) (void)
Write the acquisition parameters into the FPGA.
- void [open_device](#) ()
Open the device driver.
- void [close_device](#) ()
Close the device driver.

12.107.1 Detailed Description

Class that implements carrier wipe-off and correlators.
Definition at line 39 of file [fpga_acquisition.h](#).

12.107.2 Constructor & Destructor Documentation

12.107.2.1 Fpga_Acquisition()

```
Fpga_Acquisition::Fpga_Acquisition (
    std::string device_name,
    uint32_t select_queue,
    std::vector< std::pair< uint32_t, uint32_t > > & downsampling_filter_specs,
    uint32_t & max_FFT_size)
```

Constructor.

12.107.2.2 ~Fpga_Acquisition()

```
Fpga_Acquisition::~~Fpga_Acquisition () [default]
```

Destructor.

12.107.3 Member Function Documentation

12.107.3.1 close_device()

```
void Fpga_Acquisition::close_device ()
```

Close the device driver.

12.107.3.2 configure_acquisition()

```
void Fpga_Acquisition::configure_acquisition (
    void )
```

Write the acquisition parameters into the FPGA.

12.107.3.3 init()

```
void Fpga_Acquisition::init (
    uint32_t nsamples,
    uint32_t d_fft_size,
    int64_t resampled_fs,
    uint32_t downsampling_filter_num,
    uint32_t excludelimit,
    uint32_t * all_fft_codes)
```

Initialize acquisition parameters.

12.107.3.4 open_device()

```
void Fpga_Acquisition::open_device ()
```

Open the device driver.

12.107.3.5 read_acquisition_results()

```
void Fpga_Acquisition::read_acquisition_results (
    uint32_t * max_index,
    float * firstpeak,
    float * secondpeak,
    uint64_t * initial_sample,
    float * power_sum,
    uint32_t * doppler_index,
    uint32_t * total_blk_exp)
```

Read the results of the acquisition process.

12.107.3.6 reset_acquisition()

```
void Fpga_Acquisition::reset_acquisition ()
```

Reset the FPGA PL.

12.107.3.7 run_acquisition()

```
void Fpga_Acquisition::run_acquisition ()
```

Run the acquisition process in the FPGA.

12.107.3.8 set_block_exp()

```
void Fpga_Acquisition::set_block_exp (
    uint32_t total_block_exp)
```

Set the block exponent of the FFT in the FPGA.

12.107.3.9 set_doppler_sweep()

```
void Fpga_Acquisition::set_doppler_sweep (
    uint32_t num_sweeps,
    uint32_t doppler_step,
    int32_t doppler_min)
```

Configure the doppler sweep parameters in the FPGA.

12.107.3.10 set_local_code()

```
bool Fpga_Acquisition::set_local_code (
    uint32_t PRN)
```

Select the code with the chosen PRN.

12.107.3.11 stop_acquisition()

```
void Fpga_Acquisition::stop_acquisition ()
```

stop the acquisition and the FPGA modules.

12.107.3.12 write_local_code()

```
void Fpga_Acquisition::write_local_code (
    void )
```

Write the PRN code in the FPGA.

The documentation for this class was generated from the following file:

- [fpga_acquisition.h](#)

12.108 Fpga_buffer_monitor Class Reference

Class that checks the receiver buffer overflow flags and monitors the status of the receiver buffers.

```
#include <fpga_buffer_monitor.h>
```

Public Member Functions

- [Fpga_buffer_monitor](#) (uint32_t num_freq_bands, bool dump, std::string dump_filename)
Constructor.
- [~Fpga_buffer_monitor](#) ()
Destructor.
- bool [check_buffer_overflow_and_monitor_buffer_status](#) ()
This function checks buffer overflow and monitors the FPGA buffer status.

12.108.1 Detailed Description

Class that checks the receiver buffer overflow flags and monitors the status of the receiver buffers.
Definition at line 42 of file [fpga_buffer_monitor.h](#).

12.108.2 Constructor & Destructor Documentation**12.108.2.1 Fpga_buffer_monitor()**

```
Fpga_buffer_monitor::Fpga_buffer_monitor (
    uint32_t num_freq_bands,
    bool dump,
    std::string dump_filename) [explicit]
```

Constructor.

12.108.2.2 ~Fpga_buffer_monitor()

```
Fpga_buffer_monitor::~~Fpga_buffer_monitor ()
```

Destructor.

12.108.3 Member Function Documentation**12.108.3.1 check_buffer_overflow_and_monitor_buffer_status()**

```
bool Fpga_buffer_monitor::check_buffer_overflow_and_monitor_buffer_status ()
```

This function checks buffer overflow and monitors the FPGA buffer status.

The documentation for this class was generated from the following file:

- [fpga_buffer_monitor.h](#)

12.109 Fpga_DMA Class Reference

Class that controls the switch DMA in the FPGA.

```
#include <fpga_dma-proxy.h>
```

Public Member Functions

- [Fpga_DMA](#) ()=default
Default constructor.
- [~Fpga_DMA](#) ()=default
Default destructor.
- int [DMA_open](#) (void)
Open the DMA device driver.
- int8_t * [get_buffer_address](#) (void)
Obtain DMA buffer address.
- int [DMA_write](#) (int nbytes) const
Transfer DMA data.
- int [DMA_close](#) (void) const
Close the DMA device driver.

12.109.1 Detailed Description

Class that controls the switch DMA in the FPGA.

Definition at line 26 of file [fpga_dma-proxy.h](#).

12.109.2 Constructor & Destructor Documentation

12.109.2.1 Fpga_DMA()

```
Fpga_DMA::Fpga_DMA () [default]
```

Default constructor.

12.109.2.2 ~Fpga_DMA()

```
Fpga_DMA::~~Fpga_DMA () [default]
```

Default destructor.

12.109.3 Member Function Documentation

12.109.3.1 DMA_close()

```
int Fpga_DMA::DMA_close (
    void ) const
```

Close the DMA device driver.

12.109.3.2 DMA_open()

```
int Fpga_DMA::DMA_open (
    void )
```

Open the DMA device driver.

12.109.3.3 DMA_write()

```
int Fpga_DMA::DMA_write (
    int nbytes) const
```

Transfer DMA data.

12.109.3.4 get_buffer_address()

```
int8_t * Fpga_DMA::get_buffer_address (
    void )
```

Obtain DMA buffer address.

The documentation for this class was generated from the following file:

- [fpga_dma-proxy.h](#)

12.110 Fpga_dynamic_bit_selection Class Reference

Class that controls the switch in the FPGA, which connects the FPGA acquisition and multicorrelator modules to either the DMA or the Analog Front-End.

```
#include <fpga_dynamic_bit_selection.h>
```

Public Member Functions

- [Fpga_dynamic_bit_selection](#) (bool enable_rx1_band, bool enable_rx2_band)
Constructor.
- [~Fpga_dynamic_bit_selection](#) ()
Destructor.
- void [bit_selection](#) (void)
This function configures the switch in the FPGA.

12.110.1 Detailed Description

Class that controls the switch in the FPGA, which connects the FPGA acquisition and multicorrelator modules to either the DMA or the Analog Front-End.

Definition at line 40 of file [fpga_dynamic_bit_selection.h](#).

12.110.2 Constructor & Destructor Documentation

12.110.2.1 Fpga_dynamic_bit_selection()

```
Fpga_dynamic_bit_selection::Fpga_dynamic_bit_selection (
    bool enable_rx1_band,
    bool enable_rx2_band) [explicit]
```

Constructor.

12.110.2.2 ~Fpga_dynamic_bit_selection()

```
Fpga_dynamic_bit_selection::~~Fpga_dynamic_bit_selection ()
```

Destructor.

12.110.3 Member Function Documentation

12.110.3.1 bit_selection()

```
void Fpga_dynamic_bit_selection::bit_selection (
    void )
```

This function configures the switch in the FPGA.

The documentation for this class was generated from the following file:

- [fpga_dynamic_bit_selection.h](#)

12.111 Fpga_Multicorrelator_8sc Class Reference

Class that implements carrier wipe-off and correlators.

```
#include <fpga_multicorrelator.h>
```

Public Member Functions

- [Fpga_Multicorrelator_8sc](#) (int32_t n_correlators, int32_t *ca_codes, int32_t *data_codes, uint32_t code_length_chips, bool track_pilot, uint32_t code_samples_per_chip)
Constructor.
- [~Fpga_Multicorrelator_8sc](#) ()
Destructor.
- void [set_output_vectors](#) (gr_complex *corr_out, gr_complex *Prompt_Data)
Configure pointers to the FPGA multicorrelator results.
- void [set_local_code_and_taps](#) (float *shifts_chips, float *prompt_data_shift, int32_t PRN)
Configure the local code in the FPGA multicorrelator.
- void [update_local_code](#) ()
Configure code phase and code rate parameters in the FPGA.
- void [Carrier_wipeoff_multicorrelator_resampler](#) (float rem_carrier_phase_in_rad, float phase_step_rad, float carrier_phase_rate_step_rad, float rem_code_phase_chips, float code_phase_step_chips, float code_phase_rate_step_chips, int32_t signal_length_samples)
Perform a multicorrelation.
- bool [free](#) ()
Stop the correlation process in the FPGA and free code phase and code rate parameters.
- void [open_channel](#) (const std::string &device_io_name, uint32_t channel)
Open the FPGA device driver.

- void [set_initial_sample](#) (uint64_t samples_offset)
Set the initial sample number where the tracking process begins.
- uint64_t [read_sample_counter](#) ()
Read the sample counter in the FPGA.
- void [lock_channel](#) ()
Start the tracking process in the FPGA.
- void [unlock_channel](#) ()
finish the tracking process in the FPGA
- void [set_secondary_code_lengths](#) (uint32_t secondary_code_0_length, uint32_t secondary_code_1_length)
Set the secondary code length in the FPGA. This is only used when extended coherent integration is enabled in the FPGA. If tracking the pilot is enabled then secondary_code_0_length is the length of the pilot secondary code and secondary_code_1_length is the length of the data secondary code. If tracking the pilot is disabled then secondary_code_0_length is the length of the data secondary code, and secondary_code_1_length must be set to zero.
- void [initialize_secondary_code](#) (uint32_t secondary_code, std::string *secondary_code_string)
Initialize the secondary code in the FPGA. If tracking the pilot is enabled then the pilot secondary code is configured when secondary_code = 0 and the data secondary code is configured when secondary_code = 1. If tracking the pilot is disabled then the data secondary code is configured when secondary_code = 0.
- void [update_prn_code_length](#) (uint32_t first_prn_length, uint32_t next_prn_length)
Set the PRN length in the FPGA in number of samples. This function is only used then extended coherent integration is enabled in the FPGA. The FPGA allows for the configuration of two PRN lengths. When the length of the extended coherent integration is bigger than the length of the PRN code, the FPGA uses the first_length_secondary_code as the length of the PRN code immediately following the beginning of the extended coherent integration, and the next_length_secondary_code as the length of the remaining PRN codes. The purpose of this is to have the option to allow the FPGA to compensate for a possible deviation between the nominal value of the PRN code length and the measured PRN code length in the PRN immediately following the start of the coherent integration only. If this option is not used then write the same value to first_length_secondary_code and next_length_secondary_code.
- void [enable_secondary_codes](#) ()
Enable the use of secondary codes in the FPGA.
- void [disable_secondary_codes](#) ()
Disable the use of secondary codes in the FPGA.

12.111.1 Detailed Description

Class that implements carrier wipe-off and correlators.

Definition at line 40 of file [fpga_multicorrelator.h](#).

12.111.2 Constructor & Destructor Documentation

12.111.2.1 Fpga_Multicorrelator_8sc()

```
Fpga_Multicorrelator_8sc::Fpga_Multicorrelator_8sc (
    int32_t n_correlators,
    int32_t * ca_codes,
    int32_t * data_codes,
    uint32_t code_length_chips,
    bool track_pilot,
    uint32_t code_samples_per_chip)
```

Constructor.

12.111.2.2 ~Fpga_Multicorrelator_8sc()

```
Fpga_Multicorrelator_8sc::~Fpga_Multicorrelator_8sc ()
```

Destructor.

12.111.3 Member Function Documentation

12.111.3.1 Carrier_wipeoff_multicorrelator_resampler()

```
void Fpga_Multicorrelator_8sc::Carrier_wipeoff_multicorrelator_resampler (
    float rem_carrier_phase_in_rad,
    float phase_step_rad,
    float carrier_phase_rate_step_rad,
    float rem_code_phase_chips,
    float code_phase_step_chips,
    float code_phase_rate_step_chips,
    int32_t signal_length_samples)
```

Perform a multicorrelation.

12.111.3.2 disable_secondary_codes()

```
void Fpga_Multicorrelator_8sc::disable_secondary_codes ()
```

Disable the use of secondary codes in the FPGA.

12.111.3.3 enable_secondary_codes()

```
void Fpga_Multicorrelator_8sc::enable_secondary_codes ()
```

Enable the use of secondary codes in the FPGA.

12.111.3.4 free()

```
bool Fpga_Multicorrelator_8sc::free ()
```

Stop the correlation process in the FPGA and free code phase and code rate parameters.

12.111.3.5 initialize_secondary_code()

```
void Fpga_Multicorrelator_8sc::initialize_secondary_code (
    uint32_t secondary_code,
    std::string * secondary_code_string)
```

Initialize the secondary code in the FPGA. If tracking the pilot is enabled then the pilot secondary code is configured when `secondary_code = 0` and the data secondary code is configured when `secondary_code = 1`. If tracking the pilot is disabled then the data secondary code is configured when `secondary_code = 0`.

12.111.3.6 lock_channel()

```
void Fpga_Multicorrelator_8sc::lock_channel ()
```

Start the tracking process in the FPGA.

12.111.3.7 open_channel()

```
void Fpga_Multicorrelator_8sc::open_channel (
    const std::string & device_io_name,
    uint32_t channel)
```

Open the FPGA device driver.

12.111.3.8 read_sample_counter()

```
uint64_t Fpga_Multicorrelator_8sc::read_sample_counter ()
```

Read the sample counter in the FPGA.

12.111.3.9 set_initial_sample()

```
void Fpga_Multicorrelator_8sc::set_initial_sample (
    uint64_t samples_offset)
```

Set the initial sample number where the tracking process begins.

12.111.3.10 set_local_code_and_taps()

```
void Fpga_Multicorrelator_8sc::set_local_code_and_taps (
    float * shifts_chips,
    float * prompt_data_shift,
    int32_t PRN)
```

Configure the local code in the FPGA multicorrelator.

12.111.3.11 set_output_vectors()

```
void Fpga_Multicorrelator_8sc::set_output_vectors (
    gr_complex * corr_out,
    gr_complex * Prompt_Data)
```

Configure pointers to the FPGA multicorrelator results.

12.111.3.12 set_secondary_code_lengths()

```
void Fpga_Multicorrelator_8sc::set_secondary_code_lengths (
    uint32_t secondary_code_0_length,
    uint32_t secondary_code_1_length)
```

Set the secondary code length in the FPGA. This is only used when extended coherent integration is enabled in the FPGA. If tracking the pilot is enabled then `secondary_code_0_length` is the length of the pilot secondary code and `secondary_code_1_length` is the length of the data secondary code. If tracking the pilot is disabled then `secondary_code_0_length` is the length of the data secondary code, and `secondary_code_1_length` must be set to zero.

12.111.3.13 unlock_channel()

```
void Fpga_Multicorrelator_8sc::unlock_channel ()
```

finish the tracking process in the FPGA

12.111.3.14 update_local_code()

```
void Fpga_Multicorrelator_8sc::update_local_code ()
```

Configure code phase and code rate parameters in the FPGA.

12.111.3.15 update_prn_code_length()

```
void Fpga_Multicorrelator_8sc::update_prn_code_length (
    uint32_t first_prn_length,
    uint32_t next_prn_length)
```

Set the PRN length in the FPGA in number of samples. This function is only used then extended coherent integration is enabled in the FPGA. The FPGA allows for the configuration of two PRN lengths. When the length of the extended coherent integration is bigger than the length of the PRN code, the FPGA uses the `first_length_secondary_code` as the length of the PRN code immediately following the beginning of the extended coherent integration, and the `next_length_secondary_code` as the length of the remaining PRN codes. The purpose of this is to have the option to allow the FPGA to compensate for a possible deviation between the nominal value of the PRN code length and the measured PRN code length in the PRN immediately following the start of the coherent integration only. If this option is not used then write the same value to `first_length_secondary_code` and `next_length_secondary_code`.

The documentation for this class was generated from the following file:

- [fpga_multicorrelator.h](#)

12.112 Fpga_spidev Class Reference**Public Member Functions**

- [Fpga_spidev](#) ()=default

Default constructor.

- [~Fpga_spidev](#) ()=default
Default destructor.
- int [write_reg32](#) (char addr, uint32_t data)
write a register through the SPI.
- int [read_reg32](#) (uint8_t addr, uint32_t *copy_to)
read a register through the SPI.
- int [SPI_open](#) (std::string spi_device_name)
Open the SPI device driver.
- int [SPI_close](#) (void) const
Close the SPI device driver.

12.112.1 Detailed Description

Definition at line 22 of file [fpga_spidev.h](#).

12.112.2 Constructor & Destructor Documentation

12.112.2.1 Fpga_spidev()

```
Fpga_spidev::Fpga_spidev () [default]
```

Default constructor.

12.112.2.2 ~Fpga_spidev()

```
Fpga_spidev::~~Fpga_spidev () [default]
```

Default destructor.

12.112.3 Member Function Documentation

12.112.3.1 read_reg32()

```
int Fpga_spidev::read_reg32 (
    uint8_t addr,
    uint32_t * copy_to)
```

read a register through the SPI.

12.112.3.2 SPI_close()

```
int Fpga_spidev::SPI_close (
    void ) const
```

Close the SPI device driver.

12.112.3.3 SPI_open()

```
int Fpga_spidev::SPI_open (
    std::string spi_device_name)
```

Open the SPI device driver.

12.112.3.4 write_reg32()

```
int Fpga_spidev::write_reg32 (
    char addr,
    uint32_t data)
```

write a register through the SPI.

The documentation for this class was generated from the following file:

- [fpga_spidev.h](#)

12.113 Fpga_Switch Class Reference

Class that controls the switch in the FPGA, which connects the FPGA acquisition and multicorrelator modules to either the DMA or the Analog Front-End.

```
#include <fpga_switch.h>
```

Public Member Functions

- [Fpga_Switch](#) (void)
Constructor.
- [~Fpga_Switch](#) ()
Destructor.
- void [set_switch_position](#) (int32_t switch_position)
This function configures the switch in the eFPGA.

12.113.1 Detailed Description

Class that controls the switch in the FPGA, which connects the FPGA acquisition and multicorrelator modules to either the DMA or the Analog Front-End.

Definition at line 39 of file [fpga_switch.h](#).

12.113.2 Constructor & Destructor Documentation

12.113.2.1 Fpga_Switch()

```
Fpga_Switch::Fpga_Switch (
    void )
```

Constructor.

12.113.2.2 ~Fpga_Switch()

```
Fpga_Switch::~~Fpga_Switch ()
```

Destructor.

12.113.3 Member Function Documentation

12.113.3.1 set_switch_position()

```
void Fpga_Switch::set_switch_position (
    int32_t switch_position)
```

This function configures the switch in the eFPGA.

The documentation for this class was generated from the following file:

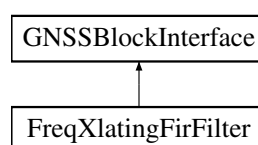
- [fpga_switch.h](#)

12.114 FreqXlatingFirFilter Class Reference

This class adapts a gnuradio gr_freq_xlating_fir_filter designed with pm_remez.

```
#include <freq_xlating_fir_filter.h>
```

Inheritance diagram for FreqXlatingFirFilter:



Public Member Functions

- **FreqXlatingFirFilter** (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override
Returns "Freq_Xlating_Fir_Filter".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.114.1 Detailed Description

This class adapts a gnuradio gr_freq_xlating_fir_filter designed with pm_remez.

Construct a FIR filter with the given taps and a composite frequency translation that shifts intermediate_freq_down to zero Hz. The frequency translation logically comes before the filtering operation.

See Parks-McClellan FIR filter design, https://en.wikipedia.org/wiki/Parks-McClellan_filter_design_algorithm Calculates the optimal (in the Chebyshev/minimax sense) FIR filter impulse response given a set of band edges, the desired response on those bands, and the weight given to the error in those bands.

Definition at line 58 of file [freq_xlating_fir_filter.h](#).

12.114.2 Member Function Documentation

12.114.2.1 connect()

```
void FreqXlatingFirFilter::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.114.2.2 disconnect()

```
void FreqXlatingFirFilter::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.114.2.3 get_left_block()

```
gr::basic_block_sptr FreqXlatingFirFilter::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.114.2.4 get_right_block()

```
gr::basic_block_sptr FreqXlatingFirFilter::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.114.2.5 implementation()

`std::string FreqXlatingFirFilter::implementation () [inline], [override], [virtual]`

Returns "Freq_Xlating_Fir_Filter".

Implements [GNSSBlockInterface](#).

Definition at line 73 of file [freq_xlating_fir_filter.h](#).

12.114.2.6 item_size()

`size_t FreqXlatingFirFilter::item_size () [inline], [override], [virtual]`

Implements [GNSSBlockInterface](#).

Definition at line 78 of file [freq_xlating_fir_filter.h](#).

12.114.2.7 role()

`std::string FreqXlatingFirFilter::role () [inline], [override], [virtual]`

Implements [GNSSBlockInterface](#).

Definition at line 67 of file [freq_xlating_fir_filter.h](#).

The documentation for this class was generated from the following file:

- [freq_xlating_fir_filter.h](#)

12.115 ftp_t Struct Reference

Public Attributes

- int [state](#)
- int [proto](#)
- int [error](#)
- char [addr](#) [1024]
- char [file](#) [1024]
- char [user](#) [256]
- char [passwd](#) [256]
- char [local](#) [1024]
- int [topts](#) [4]
- [gtime_t](#) [tnext](#)
- [pthread_t](#) [thread](#)

12.115.1 Detailed Description

Definition at line 1185 of file [rtklib.h](#).

12.115.2 Member Data Documentation

12.115.2.1 addr

`char ftp_t::addr[1024]`

Definition at line 1191 of file [rtklib.h](#).

12.115.2.2 error

`int ftp_t::error`

Definition at line 1189 of file [rtklib.h](#).

12.115.2.3 file

`char ftp_t::file[1024]`

Definition at line 1192 of file [rtklib.h](#).

12.115.2.4 local

```
char ftp_t::local[1024]
```

Definition at line 1195 of file [rtklib.h](#).

12.115.2.5 passwd

```
char ftp_t::passwd[256]
```

Definition at line 1194 of file [rtklib.h](#).

12.115.2.6 proto

```
int ftp_t::proto
```

Definition at line 1188 of file [rtklib.h](#).

12.115.2.7 state

```
int ftp_t::state
```

Definition at line 1187 of file [rtklib.h](#).

12.115.2.8 thread

```
pthread_t ftp_t::thread
```

Definition at line 1198 of file [rtklib.h](#).

12.115.2.9 tnext

```
gtime_t ftp_t::tnext
```

Definition at line 1197 of file [rtklib.h](#).

12.115.2.10 topts

```
int ftp_t::topts[4]
```

Definition at line 1196 of file [rtklib.h](#).

12.115.2.11 user

```
char ftp_t::user[256]
```

Definition at line 1193 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

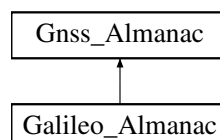
- [rtklib.h](#)

12.116 Galileo_Almanac Class Reference

This class is a storage for the Galileo SV ALMANAC data.

```
#include <galileo_almanac.h>
```

Inheritance diagram for Galileo_Almanac:

**Public Member Functions**

- [Galileo_Almanac](#) ()
- [template<class Archive>](#)
void [serialize](#) (Archive &ar, const unsigned int version)

Public Member Functions inherited from [Gnss_Almanac](#)

- [Gnss_Almanac](#) ()=default
- double [predicted_doppler](#) (double rx_time_s, double lat, double lon, double h, double ve, double vn, double vu, int band) const
Computes prediction of the Doppler shift for a given time and receiver's position and velocity.
- void [satellitePosVelComputation](#) (double transmitTime, std::array< double, 7 > &pos_vel_dtr) const
Computes satellite Position and Velocity, in ECEF, for a given time (expressed in seconds of week)

Public Attributes

- int32_t [IODa](#) {}
- int32_t [E5b_HS](#) {}
- int32_t [E1B_HS](#) {}
- int32_t [E5a_HS](#) {}

Public Attributes inherited from [Gnss_Almanac](#)

- uint32_t [PRN](#) {}
SV PRN NUMBER.
- double [delta_i](#) {}
Inclination Angle at Reference Time (relative to $i_0 = 0.30$ semi-circles)
- int32_t [toa](#) {}
Almanac data reference time of week [s].
- int32_t [WNa](#) {}
Almanac week number.
- double [M_0](#) {}
Mean Anomaly at Reference Time [semi-circles].
- double [ecc](#) {}
Eccentricity [dimensionless].
- double [sqrtA](#) {}
Square Root of the Semi-Major Axis [sqrt(m)].
- double [OMEGA_0](#) {}
Longitude of Ascending Node of Orbit Plane at Weekly Epoch [semi-circles].
- double [omega](#) {}
Argument of Perigee [semi-circles].
- double [OMEGAdot](#) {}
Rate of Right Ascension [semi-circles/s].
- double [af0](#) {}
Coefficient 0 of code phase offset model [s].
- double [af1](#) {}
Coefficient 1 of code phase offset model [s/s].

Additional Inherited Members

Protected Attributes inherited from [Gnss_Almanac](#)

- char [System](#) {}
Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou.

12.116.1 Detailed Description

This class is a storage for the Galileo SV ALMANAC data.
Definition at line 33 of file [galileo_almanac.h](#).

12.116.2 Constructor & Destructor Documentation

12.116.2.1 Galileo_Almanac()

Galileo_Almanac::Galileo_Almanac () [inline]

Default constructor

Definition at line 39 of file [galileo_almanac.h](#).

References [Gnss_Almanac::System](#).

12.116.3 Member Function Documentation

12.116.3.1 serialize()

```
template<class Archive>
void Galileo_Almanac::serialize (
    Archive & ar,
    const unsigned int version) [inline]
```

Definition at line 51 of file [galileo_almanac.h](#).

12.116.4 Member Data Documentation

12.116.4.1 E1B_HS

int32_t Galileo_Almanac::E1B_HS {}

Definition at line 46 of file [galileo_almanac.h](#).

12.116.4.2 E5a_HS

int32_t Galileo_Almanac::E5a_HS {}

Definition at line 47 of file [galileo_almanac.h](#).

12.116.4.3 E5b_HS

int32_t Galileo_Almanac::E5b_HS {}

Definition at line 45 of file [galileo_almanac.h](#).

12.116.4.4 IODa

int32_t Galileo_Almanac::IODa {}

Definition at line 44 of file [galileo_almanac.h](#).

The documentation for this class was generated from the following file:

- [galileo_almanac.h](#)

12.117 Galileo_Almanac_Helper Class Reference

This class is a storage for the GALILEO ALMANAC data as described in GALILEO ICD.

```
#include <galileo_almanac_helper.h>
```

Public Member Functions

- [Galileo_Almanac_Helper](#) ()=default
Default constructor.
- [Galileo_Almanac](#) get_almanac (int i) const

Public Attributes

- int32_t [IOD_a_7](#) {}
- int32_t [WN_a_7](#) {}
- int32_t [t0a_7](#) {}

- int32_t SVID1_7 {}
- double DELTA_A_7 {}
- double e_7 {}
- double omega_7 {}
- double delta_i_7 {}
- double Omega0_7 {}
- double Omega_dot_7 {}
- double M0_7 {}
- int32_t IOD_a_8 {}
- double af0_8 {}
- double af1_8 {}
- int32_t E5b_HS_8 {}
- int32_t E1B_HS_8 {}
- int32_t E5a_HS_8 {}
- int32_t SVID2_8 {}
- double DELTA_A_8 {}
- double e_8 {}
- double omega_8 {}
- double delta_i_8 {}
- double Omega0_8 {}
- double Omega_dot_8 {}
- int32_t IOD_a_9 {}
- int32_t WN_a_9 {}
- int32_t t0a_9 {}
- double M0_9 {}
- double af0_9 {}
- double af1_9 {}
- int32_t E5b_HS_9 {}
- int32_t E1B_HS_9 {}
- int32_t E5a_HS_9 {}
- int32_t SVID3_9 {}
- double DELTA_A_9 {}
- double e_9 {}
- double omega_9 {}
- double delta_i_9 {}
- int32_t IOD_a_10 {}
- double Omega0_10 {}
- double Omega_dot_10 {}
- double M0_10 {}
- double af0_10 {}
- double af1_10 {}
- int32_t E5b_HS_10 {}
- int32_t E1B_HS_10 {}
- int32_t E5a_HS_10 {}

12.117.1 Detailed Description

This class is a storage for the GALILEO ALMANAC data as described in GALILEO ICD.

See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf paragraph 5.1.10

Definition at line 34 of file [galileo_almanac_helper.h](#).

12.117.2 Constructor & Destructor Documentation

12.117.2.1 Galileo_Almanac_Helper()

Galileo_Almanac_Helper::Galileo_Almanac_Helper () [default]
Default constructor.

12.117.3 Member Data Documentation

12.117.3.1 af0_10

double Galileo_Almanac_Helper::af0_10 {}
Definition at line 90 of file [galileo_almanac_helper.h](#).

12.117.3.2 af0_8

double Galileo_Almanac_Helper::af0_8 {}
Definition at line 56 of file [galileo_almanac_helper.h](#).

12.117.3.3 af0_9

double Galileo_Almanac_Helper::af0_9 {}
Definition at line 74 of file [galileo_almanac_helper.h](#).

12.117.3.4 af1_10

double Galileo_Almanac_Helper::af1_10 {}
Definition at line 91 of file [galileo_almanac_helper.h](#).

12.117.3.5 af1_8

double Galileo_Almanac_Helper::af1_8 {}
Definition at line 57 of file [galileo_almanac_helper.h](#).

12.117.3.6 af1_9

double Galileo_Almanac_Helper::af1_9 {}
Definition at line 75 of file [galileo_almanac_helper.h](#).

12.117.3.7 DELTA_A_7

double Galileo_Almanac_Helper::DELTA_A_7 {}
Definition at line 46 of file [galileo_almanac_helper.h](#).

12.117.3.8 DELTA_A_8

double Galileo_Almanac_Helper::DELTA_A_8 {}
Definition at line 62 of file [galileo_almanac_helper.h](#).

12.117.3.9 DELTA_A_9

double Galileo_Almanac_Helper::DELTA_A_9 {}
Definition at line 80 of file [galileo_almanac_helper.h](#).

12.117.3.10 delta_i_7

double Galileo_Almanac_Helper::delta_i_7 {}
Definition at line 49 of file [galileo_almanac_helper.h](#).

12.117.3.11 delta_i_8

```
double Galileo_Almanac_Helper::delta_i_8 {}
```

Definition at line 65 of file [galileo_almanac_helper.h](#).

12.117.3.12 delta_i_9

```
double Galileo_Almanac_Helper::delta_i_9 {}
```

Definition at line 83 of file [galileo_almanac_helper.h](#).

12.117.3.13 E1B_HS_10

```
int32_t Galileo_Almanac_Helper::E1B_HS_10 {}
```

Definition at line 93 of file [galileo_almanac_helper.h](#).

12.117.3.14 E1B_HS_8

```
int32_t Galileo_Almanac_Helper::E1B_HS_8 {}
```

Definition at line 59 of file [galileo_almanac_helper.h](#).

12.117.3.15 E1B_HS_9

```
int32_t Galileo_Almanac_Helper::E1B_HS_9 {}
```

Definition at line 77 of file [galileo_almanac_helper.h](#).

12.117.3.16 E5a_HS_10

```
int32_t Galileo_Almanac_Helper::E5a_HS_10 {}
```

Definition at line 94 of file [galileo_almanac_helper.h](#).

12.117.3.17 E5a_HS_8

```
int32_t Galileo_Almanac_Helper::E5a_HS_8 {}
```

Definition at line 60 of file [galileo_almanac_helper.h](#).

12.117.3.18 E5a_HS_9

```
int32_t Galileo_Almanac_Helper::E5a_HS_9 {}
```

Definition at line 78 of file [galileo_almanac_helper.h](#).

12.117.3.19 E5b_HS_10

```
int32_t Galileo_Almanac_Helper::E5b_HS_10 {}
```

Definition at line 92 of file [galileo_almanac_helper.h](#).

12.117.3.20 E5b_HS_8

```
int32_t Galileo_Almanac_Helper::E5b_HS_8 {}
```

Definition at line 58 of file [galileo_almanac_helper.h](#).

12.117.3.21 E5b_HS_9

```
int32_t Galileo_Almanac_Helper::E5b_HS_9 {}
```

Definition at line 76 of file [galileo_almanac_helper.h](#).

12.117.3.22 e_7

```
double Galileo_Almanac_Helper::e_7 {}
```

Definition at line 47 of file [galileo_almanac_helper.h](#).

12.117.3.23 e_8

```
double Galileo_Almanac_Helper::e_8 {}
```

Definition at line 63 of file [galileo_almanac_helper.h](#).

12.117.3.24 e_9

```
double Galileo_Almanac_Helper::e_9 {}
```

Definition at line 81 of file [galileo_almanac_helper.h](#).

12.117.3.25 IOD_a_10

```
int32_t Galileo_Almanac_Helper::IOD_a_10 {}
```

Definition at line 86 of file [galileo_almanac_helper.h](#).

12.117.3.26 IOD_a_7

```
int32_t Galileo_Almanac_Helper::IOD_a_7 {}
```

Definition at line 42 of file [galileo_almanac_helper.h](#).

12.117.3.27 IOD_a_8

```
int32_t Galileo_Almanac_Helper::IOD_a_8 {}
```

Definition at line 55 of file [galileo_almanac_helper.h](#).

12.117.3.28 IOD_a_9

```
int32_t Galileo_Almanac_Helper::IOD_a_9 {}
```

Definition at line 70 of file [galileo_almanac_helper.h](#).

12.117.3.29 M0_10

```
double Galileo_Almanac_Helper::M0_10 {}
```

Definition at line 89 of file [galileo_almanac_helper.h](#).

12.117.3.30 M0_7

```
double Galileo_Almanac_Helper::M0_7 {}
```

Definition at line 52 of file [galileo_almanac_helper.h](#).

12.117.3.31 M0_9

```
double Galileo_Almanac_Helper::M0_9 {}
```

Definition at line 73 of file [galileo_almanac_helper.h](#).

12.117.3.32 Omega0_10

```
double Galileo_Almanac_Helper::Omega0_10 {}
```

Definition at line 87 of file [galileo_almanac_helper.h](#).

12.117.3.33 Omega0_7

```
double Galileo_Almanac_Helper::Omega0_7 {}
```

Definition at line 50 of file [galileo_almanac_helper.h](#).

12.117.3.34 Omega0_8

```
double Galileo_Almanac_Helper::Omega0_8 {}
```

Definition at line 66 of file [galileo_almanac_helper.h](#).

12.117.3.35 omega_7

```
double Galileo_Almanac_Helper::omega_7 {}
```

Definition at line 48 of file [galileo_almanac_helper.h](#).

12.117.3.36 omega_8

```
double Galileo_Almanac_Helper::omega_8 {}
```

Definition at line 64 of file [galileo_almanac_helper.h](#).

12.117.3.37 omega_9

```
double Galileo_Almanac_Helper::omega_9 {}
```

Definition at line 82 of file [galileo_almanac_helper.h](#).

12.117.3.38 Omega_dot_10

```
double Galileo_Almanac_Helper::Omega_dot_10 {}
```

Definition at line 88 of file [galileo_almanac_helper.h](#).

12.117.3.39 Omega_dot_7

```
double Galileo_Almanac_Helper::Omega_dot_7 {}
```

Definition at line 51 of file [galileo_almanac_helper.h](#).

12.117.3.40 Omega_dot_8

```
double Galileo_Almanac_Helper::Omega_dot_8 {}
```

Definition at line 67 of file [galileo_almanac_helper.h](#).

12.117.3.41 SVID1_7

```
int32_t Galileo_Almanac_Helper::SVID1_7 {}
```

Definition at line 45 of file [galileo_almanac_helper.h](#).

12.117.3.42 SVID2_8

```
int32_t Galileo_Almanac_Helper::SVID2_8 {}
```

Definition at line 61 of file [galileo_almanac_helper.h](#).

12.117.3.43 SVID3_9

```
int32_t Galileo_Almanac_Helper::SVID3_9 {}
```

Definition at line 79 of file [galileo_almanac_helper.h](#).

12.117.3.44 t0a_7

```
int32_t Galileo_Almanac_Helper::t0a_7 {}
```

Definition at line 44 of file [galileo_almanac_helper.h](#).

12.117.3.45 t0a_9

```
int32_t Galileo_Almanac_Helper::t0a_9 {}
```

Definition at line 72 of file [galileo_almanac_helper.h](#).

12.117.3.46 WN_a_7

```
int32_t Galileo_Almanac_Helper::WN_a_7 {}
```

Definition at line 43 of file [galileo_almanac_helper.h](#).

12.117.3.47 WN_a_9

```
int32_t Galileo_Almanac_Helper::WN_a_9 {}
```

Definition at line 71 of file [galileo_almanac_helper.h](#).

The documentation for this class was generated from the following file:

- [galileo_almanac_helper.h](#)

12.118 Galileo_Cnav_Message Class Reference

This class handles the Galileo CNAV Data message, as described in the Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022.

```
#include <galileo_cnav_message.h>
```

Public Member Functions

- void **read_HAS_page** (const std::string &page_string)
- bool **is_HAS_in_test_mode** () const
- bool **is_HAS_page_dummy** () const
- bool **have_new_HAS_page** () const
- [Galileo_HAS_page](#) **get_HAS_encoded_page** () const
- bool **get_flag_CRC_test** () const
- void **set_time_stamp** (uint64_t time_stamp)
- void **set_tow** (uint32_t tow)

12.118.1 Detailed Description

This class handles the Galileo CNAV Data message, as described in the Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022.

Definition at line 40 of file [galileo_cnav_message.h](#).

12.118.2 Member Function Documentation

12.118.2.1 get_flag_CRC_test()

```
bool Galileo_Cnav_Message::get_flag_CRC_test () const [inline]
```

Definition at line 67 of file [galileo_cnav_message.h](#).

12.118.2.2 get_HAS_encoded_page()

```
Galileo\_HAS\_page Galileo_Cnav_Message::get_HAS_encoded_page () const [inline]
```

Definition at line 62 of file [galileo_cnav_message.h](#).

12.118.2.3 have_new_HAS_page()

```
bool Galileo_Cnav_Message::have_new_HAS_page () const [inline]
```

Definition at line 57 of file [galileo_cnav_message.h](#).

12.118.2.4 is_HAS_in_test_mode()

```
bool Galileo_Cnav_Message::is_HAS_in_test_mode () const [inline]
```

Definition at line 47 of file [galileo_cnav_message.h](#).

12.118.2.5 is_HAS_page_dummy()

```
bool Galileo_Cnav_Message::is_HAS_page_dummy () const [inline]
```

Definition at line 52 of file [galileo_cnav_message.h](#).

12.118.2.6 set_time_stamp()

```
void Galileo_Cnav_Message::set_time_stamp (
    uint64_t time_stamp) [inline]
```

Definition at line 72 of file [galileo_cnav_message.h](#).

12.118.2.7 set_tow()

```
void Galileo_Cnav_Message::set_tow (
    uint32_t tow) [inline]
```

Definition at line 77 of file [galileo_cnav_message.h](#).

The documentation for this class was generated from the following file:

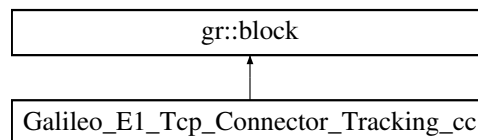
- [galileo_cnav_message.h](#)

12.119 Galileo_E1_Tcp_Connector_Tracking_cc Class Reference

This class implements a code DLL + carrier PLL VEML (Very Early Minus Late) tracking block for Galileo E1 signals.

```
#include <galileo_e1_tcp_connector_tracking_cc.h>
```

Inheritance diagram for Galileo_E1_Tcp_Connector_Tracking_cc:



Public Member Functions

- void **set_channel** (uint32_t channel)
- void **set_gnss_synchro** ([Gnss_Synchro](#) *p_gnss_synchro)
- void **start_tracking** ()
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)
- void **forecast** (int noutput_items, gr_vector_int &ninput_items_required)

Friends

- galileo_e1_tcp_connector_tracking_cc_sptr **galileo_e1_tcp_connector_make_tracking_cc** (int64_t fs_in, uint32_t vector_length, bool dump, const std::string &dump_filename, float pll_bw_hz, float dll_bw_hz, float early_late_space_chips, float very_early_late_space_chips, size_t port_ch0)

12.119.1 Detailed Description

This class implements a code DLL + carrier PLL VEML (Very Early Minus Late) tracking block for Galileo E1 signals.

Definition at line 63 of file [galileo_e1_tcp_connector_tracking_cc.h](#).

The documentation for this class was generated from the following file:

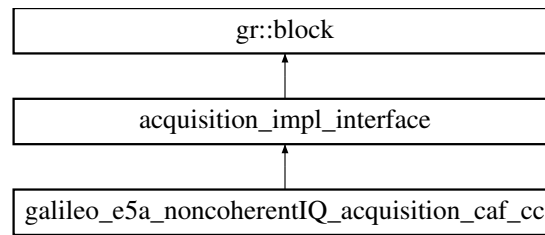
- [galileo_e1_tcp_connector_tracking_cc.h](#)

12.120 galileo_e5a_noncoherentIQ_acquisition_caf_cc Class Reference

This class implements a Parallel Code Phase Search Acquisition.

```
#include <galileo_e5a_noncoherent_iq_acquisition_caf_cc.h>
```

Inheritance diagram for galileo_e5a_noncoherentIQ_acquisition_caf_cc:



Public Member Functions

- [~galileo_e5a_noncoherentIQ_acquisition_caf_cc](#) ()
Default destructor.
- void [set_gnss_synchro](#) (Gnss_Synchro *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- unsigned int [mag](#) () const override
Returns the maximum peak of grid search.
- void [set_local_code](#) (std::complex< float > *code, std::complex< float > *codeQ) override
Sets local code for PCPS acquisition algorithm.
- void [set_active](#) (bool active) override
Starts acquisition algorithm, turning from standby mode to active mode.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- int [general_work](#) (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
Parallel Code Phase Search Acquisition signal processing.

Public Member Functions inherited from [acquisition_impl_interface](#)

- [acquisition_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_channel](#) (uint32_t channel_id)=0
- virtual void [set_local_code](#) (std::complex< float > *)

Friends

- galileo_e5a_noncoherentIQ_acquisition_caf_cc_sptr [galileo_e5a_noncoherentIQ_make_acquisition_caf_cc](#) (const [Acq_Conf](#) &conf, bool both_signal_components, int CAF_window_hz, int Zero_padding)

12.120.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition.

Check [An Open Source Galileo E1 Software Receiver](#), Algorithm 1, for a pseudocode description of this implementation.

Definition at line 62 of file [galileo_e5a_noncoherent_iq_acquisition_caf_cc.h](#).

12.120.2 Constructor & Destructor Documentation

12.120.2.1 ~galileo_e5a_noncoherentIQ_acquisition_caf_cc()

[galileo_e5a_noncoherentIQ_acquisition_caf_cc::~galileo_e5a_noncoherentIQ_acquisition_caf_cc](#) ()
Default destructor.

12.120.3 Member Function Documentation

12.120.3.1 `general_work()`

```
int galileo_e5a_noncoherentIQ_acquisition_caf_cc::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

Parallel Code Phase Search Acquisition signal processing.

12.120.3.2 `mag()`

```
unsigned int galileo_e5a_noncoherentIQ_acquisition_caf_cc::mag () const [inline], [override],
[virtual]
```

Returns the maximum peak of grid search.

Implements [acquisition_impl_interface](#).

Definition at line 83 of file [galileo_e5a_noncoherent_iq_acquisition_caf_cc.h](#).

12.120.3.3 `set_active()`

```
void galileo_e5a_noncoherentIQ_acquisition_caf_cc::set_active (
    bool active) [inline], [override], [virtual]
```

Starts acquisition algorithm, turning from standby mode to active mode.

Parameters

<i>active</i>	- bool that activates/deactivates the block.
---------------	--

Implements [acquisition_impl_interface](#).

Definition at line 99 of file [galileo_e5a_noncoherent_iq_acquisition_caf_cc.h](#).

12.120.3.4 `set_channel()`

```
void galileo_e5a_noncoherentIQ_acquisition_caf_cc::set_channel (
    unsigned int channel) [inline], [override]
```

Set acquisition channel unique ID.

Parameters

<i>channel</i>	- receiver channel.
----------------	---------------------

Definition at line 113 of file [galileo_e5a_noncoherent_iq_acquisition_caf_cc.h](#).

12.120.3.5 `set_channel_fsm()`

```
void galileo_e5a_noncoherentIQ_acquisition_caf_cc::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [inline], [override], [virtual]
```

Set channel fsm associated to this acquisition instance.

Implements [acquisition_impl_interface](#).

Definition at line 121 of file [galileo_e5a_noncoherent_iq_acquisition_caf_cc.h](#).

12.120.3.6 `set_gnss_synchro()`

```
void galileo_e5a_noncoherentIQ_acquisition_caf_cc::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [inline], [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.

Parameters

<code>p_gnss_synchro</code>	Satellite information shared by the processing blocks.
-----------------------------	--

Implements [acquisition_impl_interface](#).

Definition at line 75 of file [galileo_e5a_noncoherent_iq_acquisition_caf_cc.h](#).

12.120.3.7 set_local_code()

```
void galileo_e5a_noncoherentIQ_acquisition_caf_cc::set_local_code (
    std::complex< float > * code,
    std::complex< float > * codeQ) [override], [virtual]
```

Sets local code for PCPS acquisition algorithm.

Parameters

<code>code</code>	- Pointer to the PRN code.
-------------------	----------------------------

Reimplemented from [acquisition_impl_interface](#).

The documentation for this class was generated from the following file:

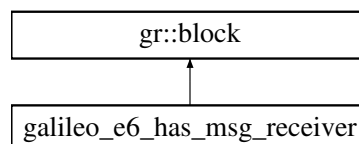
- [galileo_e5a_noncoherent_iq_acquisition_caf_cc.h](#)

12.121 galileo_e6_has_msg_receiver Class Reference

GNU Radio block that receives asynchronous Galileo HAS message pages from the telemetry blocks, stores them in memory, and decodes HAS messages when enough data have been received. The decoded HAS message is sent to the PVT block.

```
#include <galileo_e6_has_msg_receiver.h>
```

Inheritance diagram for `galileo_e6_has_msg_receiver`:

**Public Member Functions**

- `~galileo_e6_has_msg_receiver()`=default
Default destructor.
- void **set_enable_navdata_monitor** (bool enable)
- `std::shared_ptr< Galileo_HAS_data > process_test_page` (const pmt::pmt_t &msg)
For testing purposes only.

Friends

- `galileo_e6_has_msg_receiver_sptr galileo_e6_has_msg_receiver_make` ()

12.121.1 Detailed Description

GNU Radio block that receives asynchronous Galileo HAS message pages from the telemetry blocks, stores them in memory, and decodes HAS messages when enough data have been received. The decoded HAS message is sent to the PVT block.

Definition at line 56 of file [galileo_e6_has_msg_receiver.h](#).

12.121.2 Constructor & Destructor Documentation

12.121.2.1 ~galileo_e6_has_msg_receiver()

```
galileo_e6_has_msg_receiver::~~galileo_e6_has_msg_receiver () [default]
```

Default destructor.

12.121.3 Member Function Documentation

12.121.3.1 process_test_page()

```
std::shared_ptr< Galileo_HAS_data > galileo_e6_has_msg_receiver::process_test_page (
    const pmt::pmt_t & msg)
```

For testing purposes only.

The documentation for this class was generated from the following file:

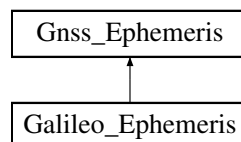
- [galileo_e6_has_msg_receiver.h](#)

12.122 Galileo_Ephemeris Class Reference

This class is a storage and orbital model functions for the Galileo SV ephemeris data as described in Galileo ICD paragraph 5.1.1.

```
#include <galileo_ephemeris.h>
```

Inheritance diagram for Galileo_Ephemeris:



Public Member Functions

- double [Galileo_System_Time](#) (double week_number, double TOW)
Galileo System Time (GST), ICD paragraph 5.1.2.
- template<class Archive>
void [serialize](#) (Archive &archive, const uint32_t version)
Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Public Member Functions inherited from [Gnss_Ephemeris](#)

- double [sv_clock_drift](#) (double transmitTime)
Sets (satClkDrift) and (dtr), and returns the clock drift in seconds according to the User Algorithm for SV Clock Correction (IS-GPS-200M, 20.3.3.3.3.1, and Galileo OS SIS ICD, 5.1.4).
- double [predicted_doppler](#) (double rx_time_s, double lat, double lon, double h, double ve, double vn, double vu, int band) const
Computes prediction of the Doppler shift for a given time and receiver's position and velocity.
- void [satellitePosition](#) (double transmitTime)
Computes the ECEF SV coordinates and ECEF velocity.

Public Attributes

- int32_t [IOD_ephemeris](#) {}
- int32_t [IOD_nav](#) {}
- int32_t [SISA](#) {}
Signal in space accuracy index.

- int32_t [E5a_HS](#) {}
E5a Signal Health Status.
- int32_t [E5b_HS](#) {}
E5b Signal Health Status.
- int32_t [E1B_HS](#) {}
E1B Signal Health Status.
- bool [E5a_DVS](#) {}
E5a Data Validity Status.
- bool [E5b_DVS](#) {}
E5b Data Validity Status.
- bool [E1B_DVS](#) {}
E1B Data Validity Status.
- double [BGD_E1E5a](#) {}
E1-E5a Broadcast Group Delay [s].
- double [BGD_E1E5b](#) {}
E1-E5b Broadcast Group Delay [s].
- bool [flag_all_ephemeris](#) {}

Public Attributes inherited from [Gnss_Ephemeris](#)

- uint32_t [PRN](#) {}
SV ID.
- double [M_0](#) {}
Mean anomaly at reference time [rad].
- double [delta_n](#) {}
Mean motion difference from computed value [rad/sec].
- double [ecc](#) {}
Eccentricity.
- double [sqrtA](#) {}
Square root of the semi-major axis [meters^{1/2}].
- double [OMEGA_0](#) {}
Longitude of ascending node of orbital plane at weekly epoch [rad].
- double [i_0](#) {}
Inclination angle at reference time [rad].
- double [omega](#) {}
Argument of perigee [rad].
- double [OMEGAdot](#) {}
Rate of right ascension [rad/sec].
- double [idot](#) {}
Rate of inclination angle [rad/sec].
- double [Cuc](#) {}
Amplitude of the cosine harmonic correction term to the argument of latitude [rad].
- double [Cus](#) {}
Amplitude of the sine harmonic correction term to the argument of latitude [rad].
- double [Crc](#) {}
Amplitude of the cosine harmonic correction term to the orbit radius [meters].
- double [Crs](#) {}
Amplitude of the sine harmonic correction term to the orbit radius [meters].
- double [Cic](#) {}
Amplitude of the cosine harmonic correction term to the angle of inclination [rad].
- double [Cis](#) {}

- *Amplitude of the sine harmonic correction term to the angle of inclination [rad].*
- `int32_t toe {}`
Ephemeris reference time [s].
- `int32_t toc {}`
Clock correction data reference Time of Week [sec].
- `double af0 {}`
SV clock bias correction coefficient [s].
- `double af1 {}`
SV clock drift correction coefficient [s/s].
- `double af2 {}`
SV clock drift rate correction coefficient [s/s²].
- `double satClkDrift {}`
SV clock drift.
- `double dtr {}`
Relativistic clock correction term.
- `int32_t WN {}`
Week number.
- `int32_t tow {}`
Time of Week.
- `double satpos_X {}`
Earth-fixed coordinate x of the satellite [m]. Intersection of the IERS Reference Meridian (IRM) and the plane passing through the origin and normal to the Z-axis.
- `double satpos_Y {}`
Earth-fixed coordinate y of the satellite [m]. Completes a right-handed, Earth-Centered, Earth-Fixed orthogonal coordinate system.
- `double satpos_Z {}`
Earth-fixed coordinate z of the satellite [m]. The direction of the IERS (International Earth Rotation and Reference Systems Service) Reference Pole (IRP).
- `double satvel_X {}`
Earth-fixed velocity coordinate x of the satellite [m].
- `double satvel_Y {}`
Earth-fixed velocity coordinate y of the satellite [m].
- `double satvel_Z {}`
Earth-fixed velocity coordinate z of the satellite [m].

Additional Inherited Members

Protected Attributes inherited from [Gnss_Ephemeris](#)

- `char System {}`
Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou.

12.122.1 Detailed Description

This class is a storage and orbital model functions for the Galileo SV ephemeris data as described in Galileo ICD paragraph 5.1.1.

(See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf)

Definition at line 39 of file [galileo_ephemeris.h](#).

12.122.2 Constructor & Destructor Documentation

12.122.2.1 Galileo_Ephemeris()

`Galileo_Ephemeris::Galileo_Ephemeris () [inline]`

Definition at line 42 of file [galileo_ephemeris.h](#).

12.122.3 Member Function Documentation

12.122.3.1 Galileo_System_Time()

```
double Galileo_Ephemeris::Galileo_System_Time (
    double week_number,
    double TOW)
```

Galileo System Time (GST), ICD paragraph 5.1.2.

12.122.3.2 serialize()

```
template<class Archive>
void Galileo_Ephemeris::serialize (
    Archive & archive,
    const uint32_t version) [inline]
```

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Definition at line 71 of file [galileo_ephemeris.h](#).

References [Gnss_Ephemeris::af0](#), [Gnss_Ephemeris::af1](#), [Gnss_Ephemeris::af2](#), [BGD_E1E5a](#), [BGD_E1E5b](#), [Gnss_Ephemeris::Cic](#), [Gnss_Ephemeris::Cis](#), [Gnss_Ephemeris::Crc](#), [Gnss_Ephemeris::Crs](#), [Gnss_Ephemeris::Cuc](#), [Gnss_Ephemeris::Cus](#), [Gnss_Ephemeris::delta_n](#), [Gnss_Ephemeris::dtr](#), [E1B_DVS](#), [E1B_HS](#), [E5a_DVS](#), [E5a_HS](#), [E5b_DVS](#), [E5b_HS](#), [Gnss_Ephemeris::ecc](#), [Gnss_Ephemeris::i_0](#), [Gnss_Ephemeris::idot](#), [Gnss_Ephemeris::M_0](#), [Gnss_Ephemeris::omega](#), [Gnss_Ephemeris::OMEGA_0](#), [Gnss_Ephemeris::OMEGAdot](#), [Gnss_Ephemeris::PRN](#), [Gnss_Ephemeris::satCikDrift](#), [SISA](#), [Gnss_Ephemeris::sqrtA](#), [Gnss_Ephemeris::toc](#), [Gnss_Ephemeris::toe](#), [Gnss_Ephemeris::tow](#), and [Gnss_Ephemeris::WN](#).

12.122.4 Member Data Documentation

12.122.4.1 BGD_E1E5a

```
double Galileo_Ephemeris::BGD_E1E5a {}
```

E1-E5a Broadcast Group Delay [s].

Definition at line 60 of file [galileo_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.122.4.2 BGD_E1E5b

```
double Galileo_Ephemeris::BGD_E1E5b {}
```

E1-E5b Broadcast Group Delay [s].

Definition at line 61 of file [galileo_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.122.4.3 E1B_DVS

```
bool Galileo_Ephemeris::E1B_DVS {}
```

E1B Data Validity Status.

Definition at line 59 of file [galileo_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.122.4.4 E1B_HS

```
int32_t Galileo_Ephemeris::E1B_HS {}
```

E1B Signal Health Status.

Definition at line 56 of file [galileo_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.122.4.5 E5a_DVS

```
bool Galileo_Ephemeris::E5a_DVS {}
```

E5a Data Validity Status.

Definition at line 57 of file [galileo_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.122.4.6 E5a_HS

```
int32_t Galileo_Ephemeris::E5a_HS {}
```

E5a Signal Health Status.

Definition at line 54 of file [galileo_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.122.4.7 E5b_DVS

```
bool Galileo_Ephemeris::E5b_DVS {}
```

E5b Data Validity Status.

Definition at line 58 of file [galileo_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.122.4.8 E5b_HS

```
int32_t Galileo_Ephemeris::E5b_HS {}
```

E5b Signal Health Status.

Definition at line 55 of file [galileo_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.122.4.9 flag_all_ephemeris

```
bool Galileo_Ephemeris::flag_all_ephemeris {}
```

Definition at line 63 of file [galileo_ephemeris.h](#).

12.122.4.10 IOD_ephemeris

```
int32_t Galileo_Ephemeris::IOD_ephemeris {}
```

Definition at line 49 of file [galileo_ephemeris.h](#).

12.122.4.11 IOD_nav

```
int32_t Galileo_Ephemeris::IOD_nav {}
```

Definition at line 50 of file [galileo_ephemeris.h](#).

12.122.4.12 SISA

```
int32_t Galileo_Ephemeris::SISA {}
```

Signal in space accuracy index.

Definition at line 53 of file [galileo_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

The documentation for this class was generated from the following file:

- [galileo_ephemeris.h](#)

12.123 Galileo_Fnav_Message Class Reference

This class handles the Galileo F/NAV Data message, as described in the Galileo Open Service Signal in Space Interface Control Document (OS SIS ICD), Issue 2.0 (Jan. 2021). See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf.

```
#include <galileo_fnav_message.h>
```


Public Member Functions

- void **split_page** (const std::string &page_string)
- bool **have_new_ephemeris** ()
- bool **have_new_iono_and_GST** ()
- bool **have_new_utc_model** ()
- bool **have_new_almanac** ()
- [Galileo_Ephemeris](#) **get_ephemeris** () const
- [Galileo_Iono](#) **get_iono** () const
- [Galileo_Utc_Model](#) **get_utc_model** () const
- [Galileo_Almanac_Helper](#) **get_almanac** () const
- int32_t **get_TOW1** () const
- int32_t **get_TOW2** () const
- int32_t **get_TOW3** () const
- int32_t **get_TOW4** () const
- bool **get_flag_CRC_test** () const
- bool **get_flag_TOW_set** () const
- void **set_flag_TOW_set** (bool flag_tow)
- bool **is_TOW1_set** () const
- void **set_TOW1_flag** (bool flag_tow1)
- bool **is_TOW2_set** () const
- void **set_TOW2_flag** (bool flag_tow2)
- bool **is_TOW3_set** () const
- void **set_TOW3_flag** (bool flag_tow3)
- bool **is_TOW4_set** () const
- void **set_TOW4_flag** (bool flag_tow4)

12.123.1 Detailed Description

This class handles the Galileo F/NAV Data message, as described in the Galileo Open Service Signal in Space Interface Control Document (OS SIS ICD), Issue 2.0 (Jan. 2021). See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf.

Definition at line 50 of file [galileo_fnav_message.h](#).

12.123.2 Member Function Documentation

12.123.2.1 get_flag_CRC_test()

```
bool Galileo_Fnav_Message::get_flag_CRC_test () const [inline]
```

Definition at line 85 of file [galileo_fnav_message.h](#).

12.123.2.2 get_flag_TOW_set()

```
bool Galileo_Fnav_Message::get_flag_TOW_set () const [inline]
```

Definition at line 90 of file [galileo_fnav_message.h](#).

12.123.2.3 get_TOW1()

```
int32_t Galileo_Fnav_Message::get_TOW1 () const [inline]
```

Definition at line 65 of file [galileo_fnav_message.h](#).

12.123.2.4 get_TOW2()

```
int32_t Galileo_Fnav_Message::get_TOW2 () const [inline]
```

Definition at line 70 of file [galileo_fnav_message.h](#).

12.123.2.5 get_TOW3()

`int32_t Galileo_Fnav_Message::get_TOW3 () const [inline]`
Definition at line 75 of file [galileo_fnav_message.h](#).

12.123.2.6 get_TOW4()

`int32_t Galileo_Fnav_Message::get_TOW4 () const [inline]`
Definition at line 80 of file [galileo_fnav_message.h](#).

12.123.2.7 is_TOW1_set()

`bool Galileo_Fnav_Message::is_TOW1_set () const [inline]`
Definition at line 100 of file [galileo_fnav_message.h](#).

12.123.2.8 is_TOW2_set()

`bool Galileo_Fnav_Message::is_TOW2_set () const [inline]`
Definition at line 110 of file [galileo_fnav_message.h](#).

12.123.2.9 is_TOW3_set()

`bool Galileo_Fnav_Message::is_TOW3_set () const [inline]`
Definition at line 120 of file [galileo_fnav_message.h](#).

12.123.2.10 is_TOW4_set()

`bool Galileo_Fnav_Message::is_TOW4_set () const [inline]`
Definition at line 130 of file [galileo_fnav_message.h](#).

12.123.2.11 set_flag_TOW_set()

`void Galileo_Fnav_Message::set_flag_TOW_set (
 bool flag_tow) [inline]`
Definition at line 95 of file [galileo_fnav_message.h](#).

12.123.2.12 set_TOW1_flag()

`void Galileo_Fnav_Message::set_TOW1_flag (
 bool flag_tow1) [inline]`
Definition at line 105 of file [galileo_fnav_message.h](#).

12.123.2.13 set_TOW2_flag()

`void Galileo_Fnav_Message::set_TOW2_flag (
 bool flag_tow2) [inline]`
Definition at line 115 of file [galileo_fnav_message.h](#).

12.123.2.14 set_TOW3_flag()

`void Galileo_Fnav_Message::set_TOW3_flag (
 bool flag_tow3) [inline]`
Definition at line 125 of file [galileo_fnav_message.h](#).

12.123.2.15 set_TOW4_flag()

`void Galileo_Fnav_Message::set_TOW4_flag (
 bool flag_tow4) [inline]`
Definition at line 135 of file [galileo_fnav_message.h](#).

The documentation for this class was generated from the following file:

- [galileo_fnav_message.h](#)

12.124 Galileo_HAS_data Class Reference

This class is a storage for Galileo HAS message type 1, as defined in Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022. See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_HAS_SIS_ICD_v1.0.pdf.

```
#include <galileo_has_data.h>
```

Public Member Functions

- `std::vector< std::string > get_signals_in_mask (uint8_t nsys) const`
Get a vector of Nsys std::string with signals in mask for system nsys, with $0 \leq nsys < Nsys$.
- `std::vector< std::string > get_signals_in_mask (const std::string &system) const`
Get a vector of Nsys std::string with signals in mask for system ("GPS"/"Galileo")
- `std::vector< std::string > get_systems_string () const`
Get Nsys system name strings.
- `std::vector< std::string > get_systems_subset_string () const`
Get Nsat system name strings present in clock corrections subset.
- `std::vector< std::vector< float > > get_code_bias_m () const`
Get Nsat x Ncodes code biases in [m].
- `std::vector< std::vector< float > > get_phase_bias_cycle () const`
Get Nsat x Nphases phase biases in [cycles].
- `std::vector< std::vector< float > > get_delta_clock_subset_correction_m () const`
Get Nsys_sub vectors with Nsat_sub delta clock C0 corrections in [m].
- `std::vector< float > get_delta_radial_m () const`
Get Nsat delta radial corrections in [m].
- `std::vector< float > get_delta_radial_m (uint8_t nsys) const`
Get delta radial corrections in [m] for system nsys, with $0 \leq nsys < Nsys$.
- `std::vector< float > get_delta_in_track_m () const`
Get Nsat delta in-track corrections in [m].
- `std::vector< float > get_delta_in_track_m (uint8_t nsys) const`
Get delta in-track corrections in [m] for system nsys, with $0 \leq nsys < Nsys$.
- `std::vector< float > get_delta_cross_track_m () const`
Get Nsat delta cross-track corrections in [m].
- `std::vector< float > get_delta_cross_track_m (uint8_t nsys) const`
Get delta cross-track corrections in [m] for system nsys, with $0 \leq nsys < Nsys$.
- `std::vector< float > get_delta_clock_correction_m () const`
Get Nsat delta clock C0 corrections in [m].
- `std::vector< float > get_delta_clock_correction_m (uint8_t nsys) const`
Get delta clock C0 corrections in [m] for system nsys, with $0 \leq nsys < Nsys$.
- `std::vector< float > get_delta_clock_subset_correction_m (uint8_t nsys) const`
Get delta clock C0 subset corrections in [m] for system nsys, with $0 \leq nsys < Nsys$.
- `std::vector< int > get_PRNs_in_mask (uint8_t nsys) const`
Get PRNs in mask for system nsys, with $0 \leq nsys < Nsys$.
- `std::vector< int > get_PRNs_in_mask (const std::string &system) const`
Get PRNs in mask for system ("GPS"/"Galileo")
- `std::vector< int > get_PRNs_in_submask (uint8_t nsys) const`
Get PRNs in submask for system nsys, with $0 \leq nsys < Nsys$.
- `std::vector< uint16_t > get_gnss_iod (uint8_t nsys) const`
Get GNSS IODs for for system nsys, with $0 \leq nsys < Nsys$.
- `std::vector< uint8_t > get_num_satellites () const`

- *Get Nsys number of satellites.*
- `std::vector< uint8_t > get_num_subset_satellites ()` const
- *Get Nsys_sub number of satellites.*
- `float get_code_bias_m (const std::string &signal, int PRN)` const
- *Get code bias in [m] for a given signal and PRN satellite.*
- `float get_phase_bias_cycle (const std::string &signal, int PRN)` const
- *Get phase bias in [cycles] for a given signal and PRN satellite.*
- `float get_delta_radial_m (const std::string &system, int prn)` const
- *Get orbital radial correction in [m] for a given system ("GPS"/"Galileo") and PRN.*
- `float get_delta_in_track_m (const std::string &system, int prn)` const
- *Get orbital in_track correction in [m] for a given system ("GPS"/"Galileo") and PRN.*
- `float get_delta_cross_track_m (const std::string &system, int prn)` const
- *Get orbital cross_track correction in [m] for a given system ("GPS"/"Galileo") and PRN.*
- `float get_clock_correction_mult_m (const std::string &system, int prn)` const
- *Get clock correction in [m], already multiplied by its Delta Clock Multiplier, for a given system ("GPS"/"Galileo") and PRN.*
- `float get_clock_subset_correction_mult_m (const std::string &system, int prn)` const
- *Get clock correction subset in [m], already multiplied by its Delta Clock Multiplier.*
- `uint16_t get_nsat ()` const
- *Get total number of satellites with corrections.*
- `uint16_t get_nsat_sub ()` const
- *Get number of satellites in clock subset corrections.*
- `uint16_t get_validity_interval_s (uint8_t validity_interval_index)` const
- *Get validity interval in [s] from the validity_interval_index.*
- `uint16_t get_gnss_iod (const std::string &system, int prn)` const
- *Get GNSS IOD from a given system ("GPS"/"Galileo") and PRN.*
- `uint8_t get_gnss_id (int nsat)` const
- *Get GNSS ID from the nsat satellite.*

Public Attributes

- `std::vector< uint8_t > gnss_id_mask`
- *GNSS ID. See HAS SIS ICD 1.0 Section 5.2.1.1.*
- `std::vector< uint64_t > satellite_mask`
- *SatM - Satellite Mask. See HAS SIS ICD 1.0 Section 5.2.1.2.*
- `std::vector< uint16_t > signal_mask`
- *SigM - Signal Mask. See HAS SIS ICD 1.0 Section 5.2.1.3.*
- `std::vector< bool > cell_mask_availability_flag`
- *CMAF - Cell Mask Availability Flag. See HAS SIS ICD 1.0 Section 5.2.1.4.*
- `std::vector< std::vector< std::vector< bool > > > cell_mask`
- *CM - Cell Mask. See HAS SIS ICD 1.0 Section 5.2.1.5.*
- `std::vector< uint8_t > nav_message`
- *NM - Navigation Message Index. See HAS SIS ICD 1.0 Section 5.2.1.6.*
- `std::vector< uint16_t > gnss_iod`
- *IODref - Reference Issue of Data. See HAS SIS ICD 1.0 Table 26.*
- `std::vector< int16_t > delta_radial`
- *DR - Delta Radial Correction. See HAS SIS ICD 1.0 Table 25.*
- `std::vector< int16_t > delta_in_track`
- *DIT - Delta In-Track Correction. See HAS SIS ICD 1.0 Table 25.*
- `std::vector< int16_t > delta_cross_track`
- *DCT - Delta Cross Correction. See HAS SIS ICD 1.0 Table 25.*

- `std::vector< uint8_t > delta_clock_multiplier`
DCM - Delta Clock Multipliers. See HAS SIS ICD 1.0 Section 5.2.3.1.
- `std::vector< int16_t > delta_clock_correction`
DCC - Delta Clock Corrections. See HAS SIS ICD 1.0 Section 5.2.3.2.
- `std::vector< uint8_t > gnss_id_clock_subset`
GNSS ID. Specific GNSS to which the corrections refer. See HAS SIS ICD 1.0 Section 5.2.1.1.
- `std::vector< uint8_t > delta_clock_multiplier_clock_subset`
DCM. Multiplier for all Delta Clock corrections. See HAS SIS ICD 1.0 Section 5.2.3.1.
- `std::vector< uint64_t > satellite_submask`
SatMsub - Satellite Subset Mask. See HAS SIS ICD 1.0 Section 5.2.4.1.
- `std::vector< std::vector< int16_t > > delta_clock_correction_clock_subset`
DCCsub - Delta Clock Subset Corrections. See HAS SIS ICD 1.0 Section 5.2.4.1.
- `std::vector< std::vector< int16_t > > code_bias`
CB - Code bias for the m -th signal of the n -th SV. See HAS SIS ICD 1.0 Section 5.2.5.
- `std::vector< std::vector< int16_t > > phase_bias`
PB - Phase bias for the m -th signal of the n -th SV. See HAS SIS ICD 1.0 Section 5.2.6.
- `std::vector< std::vector< uint8_t > > phase_discontinuity_indicator`
PDI - Phase Discontinuity Indicator. See HAS SIS ICD 1.0 Section 5.2.6.
- `uint32_t tow`
Time of Week.
- `mt1_header header`
MT1 Header parameters. See HAS SIS ICD 1.0 Section 5.1.1.
- `uint8_t has_status`
HASS - HAS Status (from HAS page header). See HAS SIS ICD 1.0 Section 3.1.1.
- `uint8_t message_id`
MID - Message ID (from HAS page header). See HAS SIS ICD 1.0 Section 3.1.
- `uint8_t Nsys`
Number of GNSS for which corrections are provided. See HAS SIS ICD 1.0 Section 5.2.1.
- `uint8_t Nsys_sub`
Number of GNSS for which corrections are provided in clock subset corrections. See HAS SIS ICD 1.0 Section 5.2.2.1.
- `uint8_t validity_interval_index_orbit_corrections`
VI - Validity Interval Index for Orbit corrections. See HAS SIS ICD 1.0 Section 5.2.2.1.
- `uint8_t validity_interval_index_clock_fullset_corrections`
VI - Validity Interval Index for Clock full-set corrections. See HAS SIS ICD 1.0 Section 5.2.2.1.
- `uint8_t validity_interval_index_clock_subset_corrections`
VI - Validity Interval Index for Clock subset corrections. See HAS SIS ICD 1.0 Section 5.2.2.1.
- `uint8_t validity_interval_index_code_bias_corrections`
VI - Validity Interval Index for Code bias. See HAS SIS ICD 1.0 Section 5.2.2.1.
- `uint8_t validity_interval_index_phase_bias_corrections`
VI - Validity Interval Index for Phase bias. See HAS SIS ICD 1.0 Section 5.2.2.1.

12.124.1 Detailed Description

This class is a storage for Galileo HAS message type 1, as defined in Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022. See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_HAS_SIS_ICD_v1.0.pdf.

Definition at line 50 of file `galileo_has_data.h`.

12.124.2 Member Function Documentation

12.124.2.1 `get_clock_correction_mult_m()`

```
float Galileo_HAS_data::get_clock_correction_mult_m (
    const std::string & system,
    int prn) const
```

Get clock correction in [m], already multiplied by its Delta Clock Multiplier, for a given system ("GPS"/"Galileo") and PRN.

12.124.2.2 `get_clock_subset_correction_mult_m()`

```
float Galileo_HAS_data::get_clock_subset_correction_mult_m (
    const std::string & system,
    int prn) const
```

Get clock correction subset in [m], already multiplied by its Delta Clock Multiplier.

12.124.2.3 `get_code_bias_m()` [1/2]

```
std::vector< std::vector< float > > Galileo_HAS_data::get_code_bias_m () const
```

Get Nsat x Ncodes code biases in [m].

12.124.2.4 `get_code_bias_m()` [2/2]

```
float Galileo_HAS_data::get_code_bias_m (
    const std::string & signal,
    int PRN) const
```

Get code bias in [m] for a given signal and PRN satellite.

12.124.2.5 `get_delta_clock_correction_m()` [1/2]

```
std::vector< float > Galileo_HAS_data::get_delta_clock_correction_m () const
```

Get Nsat delta clock C0 corrections in [m].

12.124.2.6 `get_delta_clock_correction_m()` [2/2]

```
std::vector< float > Galileo_HAS_data::get_delta_clock_correction_m (
    uint8_t nsys) const
```

Get delta clock C0 corrections in [m] for system nsys, with 0 <= nsys < Nsys.

12.124.2.7 `get_delta_clock_subset_correction_m()` [1/2]

```
std::vector< std::vector< float > > Galileo_HAS_data::get_delta_clock_subset_correction_m ()
const
```

Get Nsys_sub vectors with Nsat_sub delta clock C0 corrections in [m].

12.124.2.8 `get_delta_clock_subset_correction_m()` [2/2]

```
std::vector< float > Galileo_HAS_data::get_delta_clock_subset_correction_m (
    uint8_t nsys) const
```

Get delta clock C0 subset corrections in [m] for system nsys, with 0 <= nsys < Nsys.

12.124.2.9 `get_delta_cross_track_m()` [1/3]

```
std::vector< float > Galileo_HAS_data::get_delta_cross_track_m () const
```

Get Nsat delta cross-track corrections in [m].

12.124.2.10 get_delta_cross_track_m() [2/3]

```
float Galileo_HAS_data::get_delta_cross_track_m (
    const std::string & system,
    int prn) const
```

Get orbital cross_track correction in [m] for a given system ("GPS"/"Galileo") and PRN.

12.124.2.11 get_delta_cross_track_m() [3/3]

```
std::vector< float > Galileo_HAS_data::get_delta_cross_track_m (
    uint8_t nsys) const
```

Get delta cross-track corrections in [m] for system nsys, with $0 \leq nsys < Nsys$.

12.124.2.12 get_delta_in_track_m() [1/3]

```
std::vector< float > Galileo_HAS_data::get_delta_in_track_m () const
```

Get Nsat delta in-track corrections in [m].

12.124.2.13 get_delta_in_track_m() [2/3]

```
float Galileo_HAS_data::get_delta_in_track_m (
    const std::string & system,
    int prn) const
```

Get orbital in_track correction in [m] for a given system ("GPS"/"Galileo") and PRN.

12.124.2.14 get_delta_in_track_m() [3/3]

```
std::vector< float > Galileo_HAS_data::get_delta_in_track_m (
    uint8_t nsys) const
```

Get delta in-track corrections in [m] for system nsys, with $0 \leq nsys < Nsys$.

12.124.2.15 get_delta_radial_m() [1/3]

```
std::vector< float > Galileo_HAS_data::get_delta_radial_m () const
```

Get Nsat delta radial corrections in [m].

12.124.2.16 get_delta_radial_m() [2/3]

```
float Galileo_HAS_data::get_delta_radial_m (
    const std::string & system,
    int prn) const
```

Get orbital radial correction in [m] for a given system ("GPS"/"Galileo") and PRN.

12.124.2.17 get_delta_radial_m() [3/3]

```
std::vector< float > Galileo_HAS_data::get_delta_radial_m (
    uint8_t nsys) const
```

Get delta radial corrections in [m] for system nsys, with $0 \leq nsys < Nsys$.

12.124.2.18 get_gnss_id()

```
uint8_t Galileo_HAS_data::get_gnss_id (
    int nsat) const
```

Get GNSS ID from the nsat satellite.

12.124.2.19 get_gnss_iod() [1/2]

```
uint16_t Galileo_HAS_data::get_gnss_iod (
    const std::string & system,
    int prn) const
```

Get GNSS IOD from a given system ("GPS"/"Galileo") and PRN.

12.124.2.20 get_gnss_iod() [2/2]

```
std::vector< uint16_t > Galileo_HAS_data::get_gnss_iod (
    uint8_t nsys) const
```

Get GNSS IODs for for system nsys, with $0 \leq nsys < Nsys$.

12.124.2.21 get_nsat()

```
uint16_t Galileo_HAS_data::get_nsat () const
```

Get total number of satellites with corrections.

12.124.2.22 get_nsat_sub()

```
uint16_t Galileo_HAS_data::get_nsat_sub () const
```

Get number of satellites in clock subset corrections.

12.124.2.23 get_num_satellites()

```
std::vector< uint8_t > Galileo_HAS_data::get_num_satellites () const
```

Get Nsys number of satellites.

12.124.2.24 get_num_subset_satellites()

```
std::vector< uint8_t > Galileo_HAS_data::get_num_subset_satellites () const
```

Get Nsys_sub number of satellites.

12.124.2.25 get_phase_bias_cycle() [1/2]

```
std::vector< std::vector< float > > Galileo_HAS_data::get_phase_bias_cycle () const
```

Get Nsat x Nphases phase biases in [cycles].

12.124.2.26 get_phase_bias_cycle() [2/2]

```
float Galileo_HAS_data::get_phase_bias_cycle (
    const std::string & signal,
    int PRN) const
```

Get phase bias in [cycles] for a given signal and PRN satellite.

12.124.2.27 get_PRNs_in_mask() [1/2]

```
std::vector< int > Galileo_HAS_data::get_PRNs_in_mask (
    const std::string & system) const
```

Get PRNs in mask for system ("GPS"/"Galileo")

12.124.2.28 get_PRNs_in_mask() [2/2]

```
std::vector< int > Galileo_HAS_data::get_PRNs_in_mask (
    uint8_t nsys) const
```

Get PRNs in mask for system nsys, with $0 \leq nsys < Nsys$.

12.124.2.29 get_PRNs_in_submask()

```
std::vector< int > Galileo_HAS_data::get_PRNs_in_submask (
    uint8_t nsys) const
```

Get PRNs in submask for system nsys, with $0 \leq nsys < Nsys$.

12.124.2.30 get_signals_in_mask() [1/2]

```
std::vector< std::string > Galileo_HAS_data::get_signals_in_mask (
    const std::string & system) const
```

Get a vector of Nsys std::string with signals in mask for system ("GPS"/"Galileo")

12.124.2.31 get_signals_in_mask() [2/2]

```
std::vector< std::string > Galileo_HAS_data::get_signals_in_mask (
    uint8_t nsys) const
```

Get a vector of Nsys std::string with signals in mask for system nsys, with $0 \leq nsys < Nsys$.

12.124.2.32 get_systems_string()

```
std::vector< std::string > Galileo_HAS_data::get_systems_string () const
```

Get Nsys system name strings.

12.124.2.33 get_systems_subset_string()

```
std::vector< std::string > Galileo_HAS_data::get_systems_subset_string () const
```

Get Nsat system name strings present in clock corrections subset.

12.124.2.34 get_validity_interval_s()

```
uint16_t Galileo_HAS_data::get_validity_interval_s (
    uint8_t validity_interval_index) const
```

Get validity interval in [s] from the validity_interval_index.

12.124.3 Member Data Documentation**12.124.3.1 cell_mask**

```
std::vector<std::vector<std::vector<bool> > > Galileo_HAS_data::cell_mask
```

CM - Cell Mask. See HAS SIS ICD 1.0 Section 5.2.1.5.

Definition at line 95 of file [galileo_has_data.h](#).

12.124.3.2 cell_mask_availability_flag

```
std::vector<bool> Galileo_HAS_data::cell_mask_availability_flag
```

CMAF - Cell Mask Availability Flag. See HAS SIS ICD 1.0 Section 5.2.1.4.

Definition at line 94 of file [galileo_has_data.h](#).

12.124.3.3 code_bias

```
std::vector<std::vector<int16_t> > Galileo_HAS_data::code_bias
```

CB - Code bias for the m-th signal of the n-th SV. See HAS SIS ICD 1.0 Section 5.2.5.

Definition at line 115 of file [galileo_has_data.h](#).

12.124.3.4 delta_clock_correction

```
std::vector<int16_t> Galileo_HAS_data::delta_clock_correction
```

DCC - Delta Clock Corrections. See HAS SIS ICD 1.0 Section 5.2.3.2.

Definition at line 106 of file [galileo_has_data.h](#).

12.124.3.5 delta_clock_correction_clock_subset

```
std::vector<std::vector<int16_t> > Galileo_HAS_data::delta_clock_correction_clock_subset
```

DCCsub - Delta Clock Subset Corrections. See HAS SIS ICD 1.0 Section 5.2.4.1.

Definition at line 112 of file [galileo_has_data.h](#).

12.124.3.6 delta_clock_multiplier

```
std::vector<uint8_t> Galileo_HAS_data::delta_clock_multiplier
```

DCM - Delta Clock Multipliers. See HAS SIS ICD 1.0 Section 5.2.3.1.

Definition at line 105 of file [galileo_has_data.h](#).

12.124.3.7 delta_clock_multiplier_clock_subset

`std::vector<uint8_t> Galileo_HAS_data::delta_clock_multiplier_clock_subset`

DCM. Multiplier for all Delta Clock corrections. See HAS SIS ICD 1.0 Section 5.2.3.1.

Definition at line 110 of file [galileo_has_data.h](#).

12.124.3.8 delta_cross_track

`std::vector<int16_t> Galileo_HAS_data::delta_cross_track`

DCT - Delta Cross Correction. See HAS SIS ICD 1.0 Table 25.

Definition at line 102 of file [galileo_has_data.h](#).

12.124.3.9 delta_in_track

`std::vector<int16_t> Galileo_HAS_data::delta_in_track`

DIT - Delta In-Track Correction. See HAS SIS ICD 1.0 Table 25.

Definition at line 101 of file [galileo_has_data.h](#).

12.124.3.10 delta_radial

`std::vector<int16_t> Galileo_HAS_data::delta_radial`

DR - Delta Radial Correction. See HAS SIS ICD 1.0 Table 25.

Definition at line 100 of file [galileo_has_data.h](#).

12.124.3.11 gnss_id_clock_subset

`std::vector<uint8_t> Galileo_HAS_data::gnss_id_clock_subset`

GNSS ID. Specific GNSS to which the corrections refer. See HAS SIS ICD 1.0 Section 5.2.1.1.

Definition at line 109 of file [galileo_has_data.h](#).

12.124.3.12 gnss_id_mask

`std::vector<uint8_t> Galileo_HAS_data::gnss_id_mask`

GNSS ID. See HAS SIS ICD 1.0 Section 5.2.1.1.

Definition at line 91 of file [galileo_has_data.h](#).

12.124.3.13 gnss_iod

`std::vector<uint16_t> Galileo_HAS_data::gnss_iod`

IODref - Reference Issue of Data. See HAS SIS ICD 1.0 Table 26.

Definition at line 99 of file [galileo_has_data.h](#).

12.124.3.14 has_status

`uint8_t Galileo_HAS_data::has_status`

HASS - HAS Status (from HAS page header). See HAS SIS ICD 1.0 Section 3.1.1.

Definition at line 124 of file [galileo_has_data.h](#).

12.124.3.15 header

`mt1_header Galileo_HAS_data::header`

MT1 Header parameters. See HAS SIS ICD 1.0 Section 5.1.1.

Definition at line 123 of file [galileo_has_data.h](#).

12.124.3.16 message_id

`uint8_t Galileo_HAS_data::message_id`

MID - Message ID (from HAS page header). See HAS SIS ICD 1.0 Section 3.1.

Definition at line 125 of file [galileo_has_data.h](#).

12.124.3.17 nav_message

`std::vector<uint8_t> Galileo_HAS_data::nav_message`

NM - Navigation Message Index. See HAS SIS ICD 1.0 Section 5.2.1.6.

Definition at line 96 of file [galileo_has_data.h](#).

12.124.3.18 Nsys

`uint8_t Galileo_HAS_data::Nsys`

Number of GNSS for which corrections are provided. See HAS SIS ICD 1.0 Section 5.2.1.

Definition at line 127 of file [galileo_has_data.h](#).

12.124.3.19 Nsys_sub

`uint8_t Galileo_HAS_data::Nsys_sub`

Number of GNSS for which corrections are provided in clock subset corrections. See HAS SIS ICD 1.0 Section 5.2.2.1.

Definition at line 128 of file [galileo_has_data.h](#).

12.124.3.20 phase_bias

`std::vector<std::vector<int16_t> > Galileo_HAS_data::phase_bias`

PB - Phase bias for the m-th signal of the n-th SV. See HAS SIS ICD 1.0 Section 5.2.6.

Definition at line 118 of file [galileo_has_data.h](#).

12.124.3.21 phase_discontinuity_indicator

`std::vector<std::vector<uint8_t> > Galileo_HAS_data::phase_discontinuity_indicator`

PDI - Phase Discontinuity Indicator. See HAS SIS ICD 1.0 Section 5.2.6.

Definition at line 119 of file [galileo_has_data.h](#).

12.124.3.22 satellite_mask

`std::vector<uint64_t> Galileo_HAS_data::satellite_mask`

SatM - Satellite Mask. See HAS SIS ICD 1.0 Section 5.2.1.2.

Definition at line 92 of file [galileo_has_data.h](#).

12.124.3.23 satellite_submask

`std::vector<uint64_t> Galileo_HAS_data::satellite_submask`

SatMsub - Satellite Subset Mask. See HAS SIS ICD 1.0 Section 5.2.4.1.

Definition at line 111 of file [galileo_has_data.h](#).

12.124.3.24 signal_mask

`std::vector<uint16_t> Galileo_HAS_data::signal_mask`

SigM - Signal Mask. See HAS SIS ICD 1.0 Section 5.2.1.3.

Definition at line 93 of file [galileo_has_data.h](#).

12.124.3.25 tow

`uint32_t Galileo_HAS_data::tow`

Time of Week.

Definition at line 121 of file [galileo_has_data.h](#).

12.124.3.26 validity_interval_index_clock_fullset_corrections

`uint8_t Galileo_HAS_data::validity_interval_index_clock_fullset_corrections`

VI - Validity Interval Index for Clock full-set corrections. See HAS SIS ICD 1.0 Section 5.2.2.1.

Definition at line 131 of file [galileo_has_data.h](#).

12.124.3.27 validity_interval_index_clock_subset_corrections

uint8_t Galileo_HAS_data::validity_interval_index_clock_subset_corrections

VI - Validity Interval Index for Clock subset corrections. See HAS SIS ICD 1.0 Section 5.2.2.1.

Definition at line 132 of file [galileo_has_data.h](#).

12.124.3.28 validity_interval_index_code_bias_corrections

uint8_t Galileo_HAS_data::validity_interval_index_code_bias_corrections

VI - Validity Interval Index for Code bias. See HAS SIS ICD 1.0 Section 5.2.2.1.

Definition at line 133 of file [galileo_has_data.h](#).

12.124.3.29 validity_interval_index_orbit_corrections

uint8_t Galileo_HAS_data::validity_interval_index_orbit_corrections

VI - Validity Interval Index for Orbit corrections. See HAS SIS ICD 1.0 Section 5.2.2.1.

Definition at line 130 of file [galileo_has_data.h](#).

12.124.3.30 validity_interval_index_phase_bias_corrections

uint8_t Galileo_HAS_data::validity_interval_index_phase_bias_corrections

VI - Validity Interval Index for Phase bias. See HAS SIS ICD 1.0 Section 5.2.2.1.

Definition at line 134 of file [galileo_has_data.h](#).

The documentation for this class was generated from the following file:

- [galileo_has_data.h](#)

12.125 Galileo_HAS_page Class Reference

This class is a storage for Galileo HAS message page, as defined in Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022.

```
#include <galileo_has_page.h>
```

Public Attributes

- std::string [has_message_string](#)
HAS message content.
- uint64_t [time_stamp](#) {}
HAS page time stamp, in [s].
- uint32_t [tow](#) {}
HAS page time of week, in [s].
- uint8_t [has_status](#) {}
HAS status.
- uint8_t [reserved](#) {}
HAS reserved field.
- uint8_t [message_type](#) {}
HAS message type (MT)
- uint8_t [message_id](#) {}
HAS message ID (MID)
- uint8_t [message_size](#) {}
HAS message size (MS)
- uint8_t [message_page_id](#) {}
HAS message page ID (PID)

12.125.1 Detailed Description

This class is a storage for Galileo HAS message page, as defined in Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022.

Definition at line 35 of file [galileo_has_page.h](#).

12.125.2 Member Data Documentation

12.125.2.1 has_message_string

```
std::string Galileo_HAS_page::has_message_string
```

HAS message content.

Definition at line 40 of file [galileo_has_page.h](#).

12.125.2.2 has_status

```
uint8_t Galileo_HAS_page::has_status {}
```

HAS status.

Definition at line 45 of file [galileo_has_page.h](#).

12.125.2.3 message_id

```
uint8_t Galileo_HAS_page::message_id {}
```

HAS message ID (MID)

Definition at line 48 of file [galileo_has_page.h](#).

12.125.2.4 message_page_id

```
uint8_t Galileo_HAS_page::message_page_id {}
```

HAS message page ID (PID)

Definition at line 50 of file [galileo_has_page.h](#).

12.125.2.5 message_size

```
uint8_t Galileo_HAS_page::message_size {}
```

HAS message size (MS)

Definition at line 49 of file [galileo_has_page.h](#).

12.125.2.6 message_type

```
uint8_t Galileo_HAS_page::message_type {}
```

HAS message type (MT)

Definition at line 47 of file [galileo_has_page.h](#).

12.125.2.7 reserved

```
uint8_t Galileo_HAS_page::reserved {}
```

HAS reserved field.

Definition at line 46 of file [galileo_has_page.h](#).

12.125.2.8 time_stamp

```
uint64_t Galileo_HAS_page::time_stamp {}
```

HAS page time stamp, in [s].

Definition at line 41 of file [galileo_has_page.h](#).

12.125.2.9 tow

```
uint32_t Galileo_HAS_page::tow {}
```

HAS page time of week, in [s].

Definition at line 42 of file [galileo_has_page.h](#).

The documentation for this class was generated from the following file:

- [galileo_has_page.h](#)

12.126 Galileo_Inav_Message Class Reference

This class handles the Galileo I/NAV Data message, as described in the Galileo Open Service Signal in Space Interface Control Document (OS SIS ICD), Issue 2.0 (Jan. 2021). See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf.

```
#include <galileo_inav_message.h>
```

Public Member Functions

- void **split_page** (std::string page_string, int32_t flag_even_word)
- bool **have_new_ephemeris** ()
- bool **have_new_iono_and_GST** ()
- bool **have_new_utc_model** ()
- bool **have_new_almanac** ()
- bool **have_new_reduced_ced** ()
- bool **have_new_ism** ()
- bool **have_new_nma** ()
- [Galileo_Ephemeris](#) **get_ephemeris** () const
- [Galileo_Iono](#) **get_iono** () const
- [Galileo_Utc_Model](#) **get_utc_model** () const
- [Galileo_Almanac_Helper](#) **get_almanac** () const
- [Galileo_Ephemeris](#) **get_reduced_ced** () const
- [Galileo_ISM](#) **get_galileo_ism** () const
- [OSNMA_msg](#) **get_osnma_msg** ()
- std::string **get_osnma_adkd_4_nav_bits** ()
- void **reset_osnma_nav_bits_adkd4** ()
- std::string **get_osnma_adkd_0_12_nav_bits** ()
- void **reset_osnma_nav_bits_adkd0_12** ()
- bool **get_flag_CRC_test** () const
- bool **get_flag_TOW_set** () const
- void **set_flag_TOW_set** (bool flag_tow)
- int32_t **get_Galileo_week** () const
- int32_t **get_TOW5** () const
- int32_t **get_TOW6** () const
- bool **is_TOW5_set** () const
- void **set_TOW5_flag** (bool flag_tow5)
- bool **is_TOW6_set** () const
- void **set_TOW6_flag** (bool flag_tow6)
- int32_t **get_TOW0** () const
- bool **is_TOW0_set** () const
- void **set_TOW0_flag** (bool flag_tow0)
- bool **get_flag_GGTO** () const
- double **get_A0G** () const
- double **get_A1G** () const
- double **get_t0G** () const
- double **get_WN0G** () const
- void **init_PRN** (uint32_t prn)
- void **enable_reed_solomon** ()

12.126.1 Detailed Description

This class handles the Galileo I/NAV Data message, as described in the Galileo Open Service Signal in Space Interface Control Document (OS SIS ICD), Issue 2.0 (Jan. 2021). See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf.

Definition at line 62 of file [galileo_inav_message.h](#).

12.126.2 Member Function Documentation

12.126.2.1 enable_reed_solomon()

```
void Galileo_Inav_Message::enable_reed_solomon () [inline]
```

Definition at line 270 of file [galileo_inav_message.h](#).

12.126.2.2 get_A0G()

```
double Galileo_Inav_Message::get_A0G () const [inline]
```

Definition at line 234 of file [galileo_inav_message.h](#).

12.126.2.3 get_A1G()

```
double Galileo_Inav_Message::get_A1G () const [inline]
```

Definition at line 239 of file [galileo_inav_message.h](#).

12.126.2.4 get_flag_CRC_test()

```
bool Galileo_Inav_Message::get_flag_CRC_test () const [inline]
```

Definition at line 164 of file [galileo_inav_message.h](#).

12.126.2.5 get_flag_GGTO()

```
bool Galileo_Inav_Message::get_flag_GGTO () const [inline]
```

Definition at line 229 of file [galileo_inav_message.h](#).

12.126.2.6 get_flag_TOW_set()

```
bool Galileo_Inav_Message::get_flag_TOW_set () const [inline]
```

Definition at line 169 of file [galileo_inav_message.h](#).

12.126.2.7 get_Galileo_week()

```
int32_t Galileo_Inav_Message::get_Galileo_week () const [inline]
```

Definition at line 179 of file [galileo_inav_message.h](#).

12.126.2.8 get_t0G()

```
double Galileo_Inav_Message::get_t0G () const [inline]
```

Definition at line 244 of file [galileo_inav_message.h](#).

12.126.2.9 get_TOW0()

```
int32_t Galileo_Inav_Message::get_TOW0 () const [inline]
```

Definition at line 214 of file [galileo_inav_message.h](#).

12.126.2.10 get_TOW5()

```
int32_t Galileo_Inav_Message::get_TOW5 () const [inline]
```

Definition at line 184 of file [galileo_inav_message.h](#).

12.126.2.11 get_TOW6()

`int32_t Galileo_Inav_Message::get_TOW6 () const [inline]`
Definition at line 189 of file [galileo_inav_message.h](#).

12.126.2.12 get_WN0G()

`double Galileo_Inav_Message::get_WN0G () const [inline]`
Definition at line 249 of file [galileo_inav_message.h](#).

12.126.2.13 init_PRN()

`void Galileo_Inav_Message::init_PRN (`
 `uint32_t prn) [inline]`
Definition at line 257 of file [galileo_inav_message.h](#).

12.126.2.14 is_TOW0_set()

`bool Galileo_Inav_Message::is_TOW0_set () const [inline]`
Definition at line 219 of file [galileo_inav_message.h](#).

12.126.2.15 is_TOW5_set()

`bool Galileo_Inav_Message::is_TOW5_set () const [inline]`
Definition at line 194 of file [galileo_inav_message.h](#).

12.126.2.16 is_TOW6_set()

`bool Galileo_Inav_Message::is_TOW6_set () const [inline]`
Definition at line 204 of file [galileo_inav_message.h](#).

12.126.2.17 set_flag_TOW_set()

`void Galileo_Inav_Message::set_flag_TOW_set (`
 `bool flag_tow) [inline]`
Definition at line 174 of file [galileo_inav_message.h](#).

12.126.2.18 set_TOW0_flag()

`void Galileo_Inav_Message::set_TOW0_flag (`
 `bool flag_tow0) [inline]`
Definition at line 224 of file [galileo_inav_message.h](#).

12.126.2.19 set_TOW5_flag()

`void Galileo_Inav_Message::set_TOW5_flag (`
 `bool flag_tow5) [inline]`
Definition at line 199 of file [galileo_inav_message.h](#).

12.126.2.20 set_TOW6_flag()

`void Galileo_Inav_Message::set_TOW6_flag (`
 `bool flag_tow6) [inline]`
Definition at line 209 of file [galileo_inav_message.h](#).

The documentation for this class was generated from the following file:

- [galileo_inav_message.h](#)

12.127 Galileo_Iono Class Reference

This class is a storage for the GALILEO IONOSPHERIC data as described in Galileo ICD paragraph 5.1.6.

```
#include <galileo_iono.h>
```

Public Member Functions

- [Galileo_Iono](#) ()=default
- template<class Archive>
void [serialize](#) (Archive &archive, const unsigned int version)
Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the iono data on disk file.

Public Attributes

- double [ai0](#) {}
Effective Ionisation Level 1st order parameter [sfu].
- double [ai1](#) {}
Effective Ionisation Level 2st order parameter [sfu/degree].
- double [ai2](#) {}
Effective Ionisation Level 3st order parameter [sfu/degree].
- int32_t [tow](#) {}
UTC data reference Time of Week [s].
- int32_t [WN](#) {}
UTC data reference Week number [week].
- bool [Region1_flag](#) {}
Ionospheric Disturbance Flag for region 1.
- bool [Region2_flag](#) {}
Ionospheric Disturbance Flag for region 2.
- bool [Region3_flag](#) {}
Ionospheric Disturbance Flag for region 3.
- bool [Region4_flag](#) {}
Ionospheric Disturbance Flag for region 4.
- bool [Region5_flag](#) {}
Ionospheric Disturbance Flag for region 5.

12.127.1 Detailed Description

This class is a storage for the GALILEO IONOSPHERIC data as described in Galileo ICD paragraph 5.1.6.

See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf

Definition at line 37 of file [galileo_iono.h](#).

12.127.2 Constructor & Destructor Documentation

12.127.2.1 Galileo_Iono()

```
Galileo_Iono::Galileo_Iono () [default]
```

Default constructor

12.127.3 Member Function Documentation

12.127.3.1 `serialize()`

```
template<class Archive>
void Galileo_Iono::serialize (
    Archive & archive,
    const unsigned int version) [inline]
```

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the iono data on disk file.

Definition at line 67 of file [galileo_iono.h](#).

References [ai0](#), [ai1](#), [ai2](#), [Region1_flag](#), [Region2_flag](#), [Region3_flag](#), [Region4_flag](#), [Region5_flag](#), [tow](#), and [WN](#).

12.127.4 Member Data Documentation

12.127.4.1 `ai0`

```
double Galileo_Iono::ai0 {}
```

Effective Ionisation Level 1st order parameter [sfu].

Definition at line 46 of file [galileo_iono.h](#).

Referenced by [serialize\(\)](#).

12.127.4.2 `ai1`

```
double Galileo_Iono::ai1 {}
```

Effective Ionisation Level 2st order parameter [sfu/degree].

Definition at line 47 of file [galileo_iono.h](#).

Referenced by [serialize\(\)](#).

12.127.4.3 `ai2`

```
double Galileo_Iono::ai2 {}
```

Effective Ionisation Level 3st order parameter [sfu/degree].

Definition at line 48 of file [galileo_iono.h](#).

Referenced by [serialize\(\)](#).

12.127.4.4 `Region1_flag`

```
bool Galileo_Iono::Region1_flag {}
```

Ionospheric Disturbance Flag for region 1.

Definition at line 55 of file [galileo_iono.h](#).

Referenced by [serialize\(\)](#).

12.127.4.5 `Region2_flag`

```
bool Galileo_Iono::Region2_flag {}
```

Ionospheric Disturbance Flag for region 2.

Definition at line 56 of file [galileo_iono.h](#).

Referenced by [serialize\(\)](#).

12.127.4.6 `Region3_flag`

```
bool Galileo_Iono::Region3_flag {}
```

Ionospheric Disturbance Flag for region 3.

Definition at line 57 of file [galileo_iono.h](#).

Referenced by [serialize\(\)](#).

12.127.4.7 `Region4_flag`

```
bool Galileo_Iono::Region4_flag {}
```

Ionospheric Disturbance Flag for region 4.
 Definition at line 58 of file [galileo_iono.h](#).
 Referenced by [serialize\(\)](#).

12.127.4.8 Region5_flag

```
bool Galileo_Iono::Region5_flag {}
```

Ionospheric Disturbance Flag for region 5.
 Definition at line 59 of file [galileo_iono.h](#).
 Referenced by [serialize\(\)](#).

12.127.4.9 tow

```
int32_t Galileo_Iono::tow {}
```

UTC data reference Time of Week [s].
 Definition at line 51 of file [galileo_iono.h](#).
 Referenced by [serialize\(\)](#).

12.127.4.10 WN

```
int32_t Galileo_Iono::WN {}
```

UTC data reference Week number [week].
 Definition at line 52 of file [galileo_iono.h](#).
 Referenced by [serialize\(\)](#).
 The documentation for this class was generated from the following file:

- [galileo_iono.h](#)

12.128 Galileo_ISM Class Reference

This class is a storage for the GALILEO Integrity Support Message as described in Galileo ICD paragraph 5.2.

```
#include <galileo_ism.h>
```

Public Member Functions

- [Galileo_ISM](#) ()=default
- void **set_ism_constellation_id** (uint8_t const_id)
- void **set_ism_service_level_id** (uint8_t sl_id)
- void **set_ism_wn** (uint16_t wn_ism)
- void **set_ism_t0** (uint16_t t0)
- void **set_ism_mask_msb** (bool mask_msb)
- void **set_ism_mask** (uint32_t mask)
- void **set_ism_pconst** (uint8_t pconst)
- void **set_ism_psat** (uint8_t psat)
- void **set_ism_ura** (uint8_t ura)
- void **set_ism_ure** (uint8_t ure)
- void **set_ism_bnom** (uint8_t bnom)
- void **set_ism_Tvalidity** (uint8_t tvalidity)
- bool **check_ism_crc** (const std::bitset< GALILEO_DATA_JK_BITS > &bits)
- double **get_pconst_value** () const
- double **get_psat_value** () const
- float **get_ura_m** () const
- float **get_ure_m** () const
- float **get_bnom_m** () const
- uint32_t **get_mask_ISM** () const
- uint16_t **get_WN_ISM** () const
- uint16_t **get_t0_ISM** () const

- `uint16_t get_Tvalidity_hours ()` const
- `bool get_ism_mask_msb ()` const
- `bool ism_parameters_apply (uint32_t prn)` const

12.128.1 Detailed Description

This class is a storage for the GALILEO Integrity Support Message as described in Galileo ICD paragraph 5.2.

See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.1.pdf

Definition at line 40 of file [galileo_ism.h](#).

12.128.2 Constructor & Destructor Documentation

12.128.2.1 Galileo_ISM()

`Galileo_ISM::Galileo_ISM ()` [default]

Default constructor

The documentation for this class was generated from the following file:

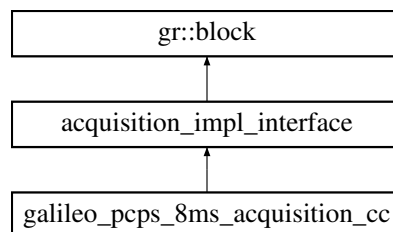
- [galileo_ism.h](#)

12.129 galileo_pcps_8ms_acquisition_cc Class Reference

This class implements a Parallel Code Phase Search Acquisition for Galileo E1 signals with coherent integration time = 8 ms (two codes)

`#include <galileo_pcps_8ms_acquisition_cc.h>`

Inheritance diagram for `galileo_pcps_8ms_acquisition_cc`:



Public Member Functions

- `~galileo_pcps_8ms_acquisition_cc ()`
Default destructor.
- `void set_gnss_synchro (Gnss_Synchro *p_gnss_synchro)` override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- `uint32_t mag ()` const override
Returns the maximum peak of grid search.
- `void set_local_code (std::complex< float > *code)` override
Sets local code for PCPS acquisition algorithm.
- `void set_active (bool active)` override
Starts acquisition algorithm, turning from standby mode to active mode.
- `void set_channel (uint32_t channel)` override
Set acquisition channel unique ID.
- `void set_channel_fsm (std::weak_ptr< ChannelFsm > channel_fsm)` override
Set channel fsm associated to this acquisition instance.
- `int general_work (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)` override
Parallel Code Phase Search Acquisition signal processing.

Public Member Functions inherited from [acquisition_impl_interface](#)

- [acquisition_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_local_code](#) (std::complex< float > *, std::complex< float > *)

Friends

- galileo_pcps_8ms_acquisition_cc_sptr [galileo_pcps_8ms_make_acquisition_cc](#) (const [Acq_Conf](#) &conf)

12.129.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition for Galileo E1 signals with coherent integration time = 8 ms (two codes)

Definition at line 51 of file [galileo_pcps_8ms_acquisition_cc.h](#).

12.129.2 Constructor & Destructor Documentation

12.129.2.1 ~galileo_pcps_8ms_acquisition_cc()

```
galileo_pcps_8ms_acquisition_cc::~galileo_pcps_8ms_acquisition_cc ()
```

Default destructor.

12.129.3 Member Function Documentation

12.129.3.1 general_work()

```
int galileo_pcps_8ms_acquisition_cc::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

Parallel Code Phase Search Acquisition signal processing.

12.129.3.2 mag()

```
uint32_t galileo_pcps_8ms_acquisition_cc::mag () const [inline], [override], [virtual]
```

Returns the maximum peak of grid search.

Implements [acquisition_impl_interface](#).

Definition at line 72 of file [galileo_pcps_8ms_acquisition_cc.h](#).

12.129.3.3 set_active()

```
void galileo_pcps_8ms_acquisition_cc::set_active (
    bool active) [inline], [override], [virtual]
```

Starts acquisition algorithm, turning from standby mode to active mode.

Parameters

<i>active</i>	- bool that activates/deactivates the block.
---------------	--

Implements [acquisition_impl_interface](#).

Definition at line 88 of file [galileo_pcps_8ms_acquisition_cc.h](#).

12.129.3.4 set_channel()

```
void galileo_pcps_8ms_acquisition_cc::set_channel (
    uint32_t channel) [inline], [override], [virtual]
```

Set acquisition channel unique ID.

Parameters

<i>channel</i>	- receiver channel.
----------------	---------------------

Implements [acquisition_impl_interface](#).

Definition at line 102 of file [galileo_pcps_8ms_acquisition_cc.h](#).

12.129.3.5 set_channel_fsm()

```
void galileo_pcps_8ms_acquisition_cc::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [inline], [override], [virtual]
```

Set channel fsm associated to this acquisition instance.

Implements [acquisition_impl_interface](#).

Definition at line 110 of file [galileo_pcps_8ms_acquisition_cc.h](#).

12.129.3.6 set_gnss_synchro()

```
void galileo_pcps_8ms_acquisition_cc::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [inline], [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.

Parameters

<i>p_gnss_synchro</i>	Satellite information shared by the processing blocks.
-----------------------	--

Implements [acquisition_impl_interface](#).

Definition at line 64 of file [galileo_pcps_8ms_acquisition_cc.h](#).

12.129.3.7 set_local_code()

```
void galileo_pcps_8ms_acquisition_cc::set_local_code (
    std::complex< float > * code) [override], [virtual]
```

Sets local code for PCPS acquisition algorithm.

Parameters

<i>code</i>	- Pointer to the PRN code.
-------------	----------------------------

Reimplemented from [acquisition_impl_interface](#).

The documentation for this class was generated from the following file:

- [galileo_pcps_8ms_acquisition_cc.h](#)

12.130 Galileo_Reduced_CED Class Reference

This class manages the Galileo Reduced Clock and Ephemeris Data.

```
#include <galileo_reduced_ced.h>
```

Public Member Functions

- [Galileo_Reduced_CED](#) ()=default
- [Galileo_Ephemeris compute_eph](#) () const

Public Attributes

- uint32_t [PRN](#) {}
Satellite ID.
- int32_t [TOTRedCED](#) {}
Start time of transmission of the Reduced CED word in GST.
- int32_t [IODnav](#) {}
Issue of Data.
- double [DeltaAred](#) {}
Difference between the Reduced CED semi-major axis and the nominal semi-major axis [meters].
- double [exred](#) {}
Reduced CED eccentricity vector component x.
- double [eyred](#) {}
Reduced CED eccentricity vector component y.
- double [Deltai0red](#) {}
Difference between the Reduced CED inclination angle at reference time and the nominal inclination [rad].
- double [Omega0red](#) {}
Reduced CED longitude of ascending node at weekly epoch [rad].
- double [lambda0red](#) {}
Reduced CED mean argument of latitude [rad].
- double [af0red](#) {}
Reduced CED satellite clock bias correction coefficient [seconds].
- double [af1red](#) {}
Reduced CED satellite clock drift correction coefficient [seconds/seconds].

12.130.1 Detailed Description

This class manages the Galileo Reduced Clock and Ephemeris Data.
Definition at line 33 of file [galileo_reduced_ced.h](#).

12.130.2 Constructor & Destructor Documentation

12.130.2.1 Galileo_Reduced_CED()

`Galileo_Reduced_CED::Galileo_Reduced_CED () [default]`
Default constructor

12.130.3 Member Function Documentation

12.130.3.1 compute_eph()

`Galileo_Ephemeris Galileo_Reduced_CED::compute_eph () const`
Convert to [Galileo_Ephemeris](#)

12.130.4 Member Data Documentation

12.130.4.1 af0red

`double Galileo_Reduced_CED::af0red {}`
Reduced CED satellite clock bias correction coefficient [seconds].
Definition at line 55 of file [galileo_reduced_ced.h](#).

12.130.4.2 af1red

`double Galileo_Reduced_CED::af1red {}`
Reduced CED satellite clock drift correction coefficient [seconds/seconds].
Definition at line 56 of file [galileo_reduced_ced.h](#).

12.130.4.3 DeltaAred

```
double Galileo_Reduced_CED::DeltaAred {}
```

Difference between the Reduced CED semi-major axis and the nominal semi-major axis [meters].

Definition at line 49 of file [galileo_reduced_ced.h](#).

12.130.4.4 Deltai0red

```
double Galileo_Reduced_CED::Deltai0red {}
```

Difference between the Reduced CED inclination angle at reference time and the nominal inclination [rad].

Definition at line 52 of file [galileo_reduced_ced.h](#).

12.130.4.5 exred

```
double Galileo_Reduced_CED::exred {}
```

Reduced CED eccentricity vector component x.

Definition at line 50 of file [galileo_reduced_ced.h](#).

12.130.4.6 eyred

```
double Galileo_Reduced_CED::eyred {}
```

Reduced CED eccentricity vector component y.

Definition at line 51 of file [galileo_reduced_ced.h](#).

12.130.4.7 IODnav

```
int32_t Galileo_Reduced_CED::IODnav {}
```

Issue of Data.

Definition at line 48 of file [galileo_reduced_ced.h](#).

12.130.4.8 lambda0red

```
double Galileo_Reduced_CED::lambda0red {}
```

Reduced CED mean argument of latitude [rad].

Definition at line 54 of file [galileo_reduced_ced.h](#).

12.130.4.9 Omega0red

```
double Galileo_Reduced_CED::Omega0red {}
```

Reduced CED longitude of ascending node at weekly epoch [rad].

Definition at line 53 of file [galileo_reduced_ced.h](#).

12.130.4.10 PRN

```
uint32_t Galileo_Reduced_CED::PRN {}
```

Satellite ID.

Definition at line 46 of file [galileo_reduced_ced.h](#).

12.130.4.11 TOTRedCED

```
int32_t Galileo_Reduced_CED::TOTRedCED {}
```

Start time of transmission of the Reduced CED word in GST.

Definition at line 47 of file [galileo_reduced_ced.h](#).

The documentation for this class was generated from the following file:

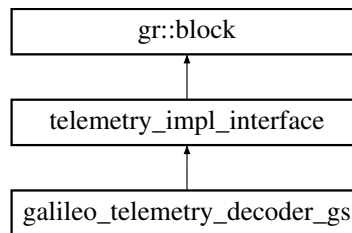
- [galileo_reduced_ced.h](#)

12.131 galileo_telemetry_decoder_gs Class Reference

This class implements a block that decodes the INAV and FNAV data defined in Galileo ICD.

```
#include <galileo_telemetry_decoder_gs.h>
```

Inheritance diagram for galileo_telemetry_decoder_gs:



Public Member Functions

- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
Set satellite PRN.
- void [set_channel](#) (int32_t channel) override
Set receiver's channel.
- void [reset](#) () override
- int [general_work](#) (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
This is where all signal processing takes place.

Public Member Functions inherited from [telemetry_impl_interface](#)

- [telemetry_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_channel](#) (int channel)=0

Friends

- galileo_telemetry_decoder_gs_sptr [galileo_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf, int frame_type)

Additional Inherited Members

Protected Member Functions inherited from [telemetry_impl_interface](#)

- void [configure_basic_outputs](#) ()
- void [configure_dump_file](#) (int32_t channel, bool enable_dump, std::string &dump_filename, std::ofstream &dump_file) const
- void [configure_crc_stats_channel](#) (int32_t channel, bool &dump_crc_stats, std::unique_ptr< [Tlm_CRC_Stats](#) > &crc_stats) const

12.131.1 Detailed Description

This class implements a block that decodes the INAV and FNAV data defined in Galileo ICD.

Definition at line 54 of file [galileo_telemetry_decoder_gs.h](#).

12.131.2 Member Function Documentation

12.131.2.1 [general_work\(\)](#)

```
int galileo_telemetry_decoder_gs::general_work (
    int noutput_items,
```

```

        gr_vector_int & ninput_items,
        gr_vector_const_void_star & input_items,
        gr_vector_void_star & output_items) [override]

```

This is where all signal processing takes place.

12.131.2.2 reset()

```
void galileo_telemetry_decoder_gs::reset () [override], [virtual]
```

Implements [telemetry_impl_interface](#).

12.131.2.3 set_channel()

```
void galileo_telemetry_decoder_gs::set_channel (
    int32_t channel) [override]
```

Set receiver's channel.

12.131.2.4 set_satellite()

```
void galileo_telemetry_decoder_gs::set_satellite (
    const Gnss_Satellite & satellite) [override], [virtual]
```

Set satellite PRN.

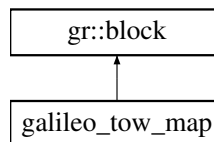
Implements [telemetry_impl_interface](#).

The documentation for this class was generated from the following file:

- [galileo_telemetry_decoder_gs.h](#)

12.132 galileo_tow_map Class Reference

Inheritance diagram for galileo_tow_map:



Public Member Functions

- [~galileo_tow_map](#) ()=default
Default destructor.

Friends

- [galileo_tow_map_sptr](#) [galileo_tow_map_make](#) ()

12.132.1 Detailed Description

Definition at line 38 of file [galileo_tow_map.h](#).

12.132.2 Constructor & Destructor Documentation

12.132.2.1 ~galileo_tow_map()

```
galileo_tow_map::~~galileo_tow_map () [default]
```

Default destructor.

The documentation for this class was generated from the following file:

- [galileo_tow_map.h](#)

12.133 Galileo_Utc_Model Class Reference

This class is a storage for the GALILEO UTC MODEL data as described in Galileo ICD https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf paragraph 5.1.7.

```
#include <galileo_utc_model.h>
```

Public Member Functions

- [Galileo_Utc_Model](#) ()=default
- double [GST_to_UTC_time](#) (double t_e, int32_t WN) const
GST-UTC Conversion Algorithm and Parameters.
- template<class Archive>
void [serialize](#) (Archive &archive, const unsigned int version)
Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the UTC data on disk file.

Public Attributes

- double [A0](#) {}
- double [A1](#) {}
- int32_t [Delta_tLS](#) {}
- int32_t [tot](#) {}
UTC data reference Time of Week [s].
- int32_t [WNNot](#) {}
UTC data reference Week number [week].
- int32_t [WN_LSF](#) {}
- int32_t [DN](#) {}
- int32_t [Delta_tLSF](#) {}
- double [A_0G](#) {}
- double [A_1G](#) {}
- int32_t [t_0G](#) {}
- int32_t [WN_0G](#) {}
- bool [flag_utc_model](#) {}

12.133.1 Detailed Description

This class is a storage for the GALILEO UTC MODEL data as described in Galileo ICD https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf paragraph 5.1.7.

Definition at line 36 of file [galileo_utc_model.h](#).

12.133.2 Constructor & Destructor Documentation

12.133.2.1 Galileo_Utc_Model()

```
Galileo_Utc_Model::Galileo_Utc_Model () [default]
```

Default constructor

12.133.3 Member Function Documentation

12.133.3.1 GST_to_UTC_time()

```
double Galileo_Utc_Model::GST_to_UTC_time (
    double t_e,
    int32_t WN) const
```

GST-UTC Conversion Algorithm and Parameters.

12.133.3.2 serialize()

```
template<class Archive>
void Galileo_Utc_Model::serialize (
    Archive & archive,
    const unsigned int version) [inline]
```

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the UTC data on disk file.

Definition at line 71 of file [galileo_utc_model.h](#).

References [tot](#), and [WNot](#).

12.133.4 Member Data Documentation

12.133.4.1 A0

```
double Galileo_Utc_Model::A0 {}
```

Definition at line 48 of file [galileo_utc_model.h](#).

12.133.4.2 A1

```
double Galileo_Utc_Model::A1 {}
```

Definition at line 49 of file [galileo_utc_model.h](#).

12.133.4.3 A_0G

```
double Galileo_Utc_Model::A_0G {}
```

Definition at line 58 of file [galileo_utc_model.h](#).

12.133.4.4 A_1G

```
double Galileo_Utc_Model::A_1G {}
```

Definition at line 59 of file [galileo_utc_model.h](#).

12.133.4.5 Delta_tLS

```
int32_t Galileo_Utc_Model::Delta_tLS {}
```

Definition at line 50 of file [galileo_utc_model.h](#).

12.133.4.6 Delta_tLSF

```
int32_t Galileo_Utc_Model::Delta_tLSF {}
```

Definition at line 55 of file [galileo_utc_model.h](#).

12.133.4.7 DN

```
int32_t Galileo_Utc_Model::DN {}
```

Definition at line 54 of file [galileo_utc_model.h](#).

12.133.4.8 flag_utc_model

```
bool Galileo_Utc_Model::flag_utc_model {}
```

Definition at line 63 of file [galileo_utc_model.h](#).

12.133.4.9 t_0G

```
int32_t Galileo_Utc_Model::t_0G {}
```

Definition at line 60 of file [galileo_utc_model.h](#).

12.133.4.10 tot

```
int32_t Galileo_Utc_Model::tot {}
```

UTC data reference Time of Week [s].

Definition at line 51 of file [galileo_utc_model.h](#).

Referenced by [serialize\(\)](#).

12.133.4.11 WN_0G

```
int32_t Galileo_Utc_Model::WN_0G {}
```

Definition at line 61 of file [galileo_utc_model.h](#).

12.133.4.12 WN_LSF

```
int32_t Galileo_Utc_Model::WN_LSF {}
```

Definition at line 53 of file [galileo_utc_model.h](#).

12.133.4.13 WNot

```
int32_t Galileo_Utc_Model::WNot {}
```

UTC data reference Week number [week].

Definition at line 52 of file [galileo_utc_model.h](#).

Referenced by [serialize\(\)](#).

The documentation for this class was generated from the following file:

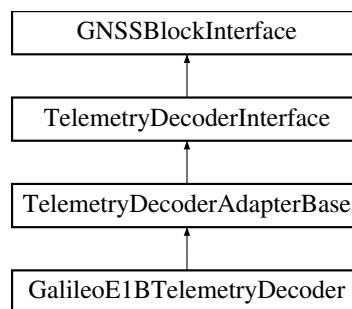
- [galileo_utc_model.h](#)

12.134 GalileoE1BTelemetryDecoder Class Reference

This class implements a NAV data decoder for Galileo INAV frames in E1B radio link.

```
#include <galileo_e1b_telemetry_decoder.h>
```

Inheritance diagram for GalileoE1BTelemetryDecoder:

**Public Member Functions**

- **GalileoE1BTelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override

Returns "Galileo_E1B_Telemetry_Decoder".

Public Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override

- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- void [InitializeDecoder](#) (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & [satellite](#) () const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- [Tlm_Conf](#) [tlm_parameters_](#)

12.134.1 Detailed Description

This class implements a NAV data decoder for Galileo INAV frames in E1B radio link.
Definition at line 36 of file [galileo_e1b_telemetry_decoder.h](#).

12.134.2 Member Function Documentation

12.134.2.1 implementation()

```
std::string GalileoE1BTelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E1B_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [galileo_e1b_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

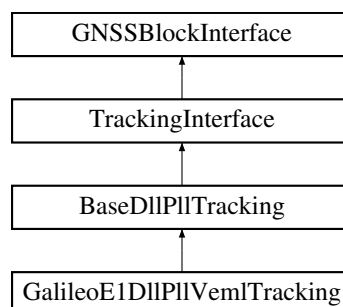
- [galileo_e1b_telemetry_decoder.h](#)

12.135 GalileoE1DIIPllVemlTracking Class Reference

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E1 signals.

```
#include <galileo_e1_dll_pll_veml_tracking.h>
```

Inheritance diagram for GalileoE1DIIPllVemlTracking:



Public Member Functions

- [GalileoE1DIIPIIVemlTracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "Galileo_E1_DLL_PLL_VEML_Tracking".

Public Member Functions inherited from [BaseDIIPIITracking](#)

- [BaseDIIPIITracking](#) (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDIIPIITracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override final
Get left block from the Tracking block adapter.
- gr::basic_block_sptr [get_right_block](#) () override final
Get right block from the Tracking block adapter.
- void [set_channel](#) (unsigned int channel) override final
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final
Start the Tracking block.
- void [stop_tracking](#) () override final
Stop the Tracking block.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BaseDIIPIITracking](#)

- [DII_PII_Conf](#) & [config_params](#) ()
- const [DII_PII_Conf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t item_size)

Protected Attributes inherited from [BaseDIIPIITracking](#)

- dll_pll_veml_tracking_sptr [tracking_sptr_](#)

12.135.1 Detailed Description

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E1 signals.

Definition at line 41 of file [galileo_e1_dll_pll_veml_tracking.h](#).

12.135.2 Constructor & Destructor Documentation

12.135.2.1 GalileoE1DllPllVemlTracking()

```
GalileoE1DllPllVemlTracking::GalileoE1DllPllVemlTracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDllPllTracking::role\(\)](#).

12.135.3 Member Function Documentation

12.135.3.1 implementation()

```
std::string GalileoE1DllPllVemlTracking::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E1_DLL_PLL_VEML_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 51 of file [galileo_e1_dll_pll_veml_tracking.h](#).

The documentation for this class was generated from the following file:

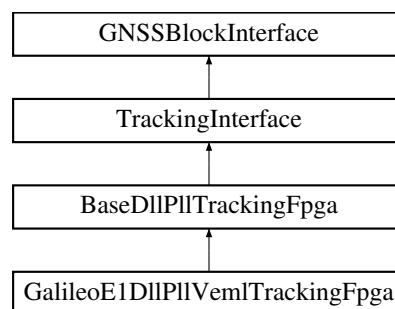
- [galileo_e1_dll_pll_veml_tracking.h](#)

12.136 GalileoE1DllPllVemlTrackingFpga Class Reference

Adapter for a Galileo E1 DLL+PLL VEML tracking loop block in FPGA.

```
#include <galileo_e1_dll_pll_veml_tracking_fpga.h>
```

Inheritance diagram for GalileoE1DllPllVemlTrackingFpga:



Public Member Functions

- **GalileoE1DllPllVemlTrackingFpga** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override

Public Member Functions inherited from [BaseDllPllTrackingFpga](#)

- [BaseDllPllTrackingFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)

Base constructor of FPGA-based Tracking block adapters.

- virtual `~BaseDIIPIITrackingFpga()` = default
Base destructor of FPGA-based Tracking block adapters.
- `std::string role()` override
Get role from the Tracking block adapter.
- `size_t item_size()` override
Get item_size from the Tracking block adapter.
- `void connect(gr::top_block_sptr top_block)` override
Connect the Tracking block adapter.
- `void disconnect(gr::top_block_sptr top_block)` override
Disconnect the Tracking block adapter.
- `gr::basic_block_sptr get_left_block()` override
Get left block from the Tracking block adapter.
- `gr::basic_block_sptr get_right_block()` override
Get right block from the Tracking block adapter.
- `void start_tracking()` override
Start the tracking process in the FPGA.
- `void stop_tracking()` override
Stop the tracking process in the FPGA.
- `void configure_fpga_tracking_channel_mapping(std::string signal)`
configure FPGA tracking channel mapping
- `void set_channel(unsigned int channel)` override
Set tracking channel unique ID.
- `void set_gnss_synchro(Gnss_Synchro *p_gnss_synchro)` override
Set acquisition/tracking common Gnss_Synchro object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

Public Member Functions inherited from GNSSBlockInterface

- virtual `gr::basic_block_sptr get_left_block(int RF_channel)`
- virtual `gr::basic_block_sptr get_right_block(int RF_channel)`
- virtual `void start()`
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from BaseDIIPIITrackingFpga

- `DII_PII_Conf_Fpga & config_params_fpga()`
- `const DII_PII_Conf_Fpga & config_params_fpga() const`

Protected Attributes inherited from BaseDIIPIITrackingFpga

- `dll_pll_veml_tracking_fpga_sptr tracking_fpga_sc_sptr_`

Static Protected Attributes inherited from BaseDIIPIITrackingFpga

- `static const int32_t LOCAL_CODE_FPGA_ENABLE_WRITE_MEMORY = 0x0C000000`
- `static const int32_t LOCAL_CODE_FPGA_CORRELATOR_SELECT_COUNT = 0x20000000`

12.136.1 Detailed Description

Adapter for a Galileo E1 DLL+PLL VEML tracking loop block in FPGA.
Definition at line 36 of file `galileo_e1_dll_pll_veml_tracking_fpga.h`.

12.136.2 Member Function Documentation

12.136.2.1 implementation()

`std::string GalileoE1DllPllVemlTrackingFpga::implementation () [inline], [override], [virtual]`

Implements [GNSSBlockInterface](#).

Definition at line 46 of file [galileo_e1_dll_pll_veml_tracking_fpga.h](#).

The documentation for this class was generated from the following file:

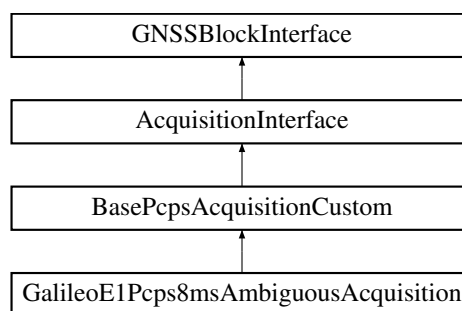
- [galileo_e1_dll_pll_veml_tracking_fpga.h](#)

12.137 GalileoE1Pcps8msAmbiguousAcquisition Class Reference

Adapts a PCPS 8ms acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

`#include <galileo_e1_pcps_8ms_ambiguous_acquisition.h>`

Inheritance diagram for GalileoE1Pcps8msAmbiguousAcquisition:



Public Member Functions

- **GalileoE1Pcps8msAmbiguousAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "Galileo_E1_PCPS_8ms_Ambiguous_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- **BasePcpsAcquisitionCustom** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double code_length_chips, unsigned int ms_per_code, bool use_stream_to_vector, const [ThresholdComputeInterface](#) &threshold_compute, uint32_t max_sampled_ms=std::numeric_limits< uint32_t >::max())
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- signed int [mag](#) () override
Returns the maximum peak of grid search.

- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t) override
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_doppler_center](#) (int)

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- bool [is_type_gr_complex](#) () const

Protected Attributes inherited from [BasePcpsAcquisitionCustom](#)

- const [Acq_Conf](#) [acq_parameters_](#)
- acquisition_impl_interface_sptr [acquisition_cc_](#)
- [Gnss_Synchro](#) * [gnss_synchro_](#)
- unsigned int [channel_](#)
- volk_gnssdr::vector< std::complex< float > > [code_](#)

12.137.1 Detailed Description

Adapts a PCPS 8ms acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.
Definition at line 32 of file [galileo_e1_pcps_8ms_ambiguous_acquisition.h](#).

12.137.2 Member Function Documentation

12.137.2.1 [implementation\(\)](#)

```
std::string GalileoE1Pcps8msAmbiguousAcquisition::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E1_PCPS_8ms_Ambiguous_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 45 of file [galileo_e1_pcps_8ms_ambiguous_acquisition.h](#).

The documentation for this class was generated from the following file:

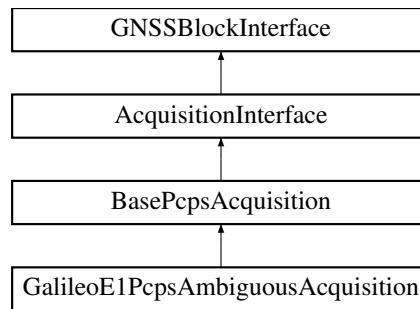
- [galileo_e1_pcps_8ms_ambiguous_acquisition.h](#)

12.138 GalileoE1PcpsAmbiguousAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

```
#include <galileo_e1_pcps_ambiguous_acquisition.h>
```

Inheritance diagram for GalileoE1PcpsAmbiguousAcquisition:



Public Member Functions

- **GalileoE1PcpsAmbiguousAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "Galileo_E1_PCPS_Ambiguous_Acquisition".
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition channel unique ID.

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int doppler_center) override
Set Doppler center for the grid search.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t latency_samples) override
Sets the resampler latency to account it in the acquisition code delay estimation.
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

12.138.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.
Definition at line 33 of file [galileo_e1_pcps_ambiguous_acquisition.h](#).

12.138.2 Member Function Documentation

12.138.2.1 implementation()

```
std::string GalileoE1PcpsAmbiguousAcquisition::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E1_PCPS_Ambiguous_Acquisition".
Implements [GNSSBlockInterface](#).
Definition at line 47 of file [galileo_e1_pcps_ambiguous_acquisition.h](#).

12.138.2.2 set_gnss_synchro()

```
void GalileoE1PcpsAmbiguousAcquisition::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [override], [virtual]
```

Set acquisition channel unique ID.

Reimplemented from [BasePcpsAcquisition](#).

The documentation for this class was generated from the following file:

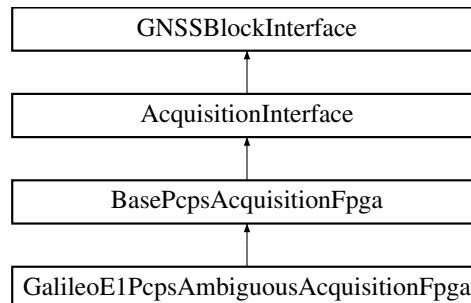
- [galileo_e1_pcps_ambiguous_acquisition.h](#)

12.139 GalileoE1PcpsAmbiguousAcquisitionFpga Class Reference

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for Galileo E1 Signals.

```
#include <galileo_e1_pcps_ambiguous_acquisition_fpga.h>
```

Inheritance diagram for GalileoE1PcpsAmbiguousAcquisitionFpga:



Public Member Functions

- [GalileoE1PcpsAmbiguousAcquisitionFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "Galileo_E1_PCPS_Ambiguous_Acquisition_FPGA".

Public Member Functions inherited from [BasePcpsAcquisitionFpga](#)

- [BasePcpsAcquisitionFpga](#) (const [ConfigurationInterface](#) *configuration, std::string role, double code_rate_cps, double code_length_chips, uint32_t opt_acq_fs_sps, uint32_t default_fpga_blk_exp, uint32_t acq_buff, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override final
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override

- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- signed int [mag](#) () override
- void [set_gnss_synchro](#) (Gnss_Synchro *p_gnss_synchro) override
- void [set_channel](#) (unsigned int channel) override
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
- void [set_doppler_center](#) (int doppler_center) override
- void [reset](#) () override
- void [stop_acquisition](#) () override
- void [set_resampler_latency](#) (uint32_t latency_samples __attribute__((unused))) override
- void [set_local_code](#) () override

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_resampler_latency](#) (uint32_t latency_samples)=0

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionFpga](#)

- void [init](#) ()

Protected Attributes inherited from [BasePcpsAcquisitionFpga](#)

- volk_gnssdr::vector< uint32_t > [d_all_fft_codes_](#)
- [Acq_Conf_Fpga](#) [acq_parameters_](#)

Static Protected Attributes inherited from [BasePcpsAcquisitionFpga](#)

- static const uint32_t [QUANT_BITS_LOCAL_CODE](#) = 16
- static const uint32_t [SELECT_LSBITS](#) = 0x0000FFFF
- static const uint32_t [SELECT_MSBITS](#) = 0xFFFF0000
- static const uint32_t [SELECT_ALL_CODE_BITS](#) = 0xFFFFFFFF
- static const uint32_t [SHL_CODE_BITS](#) = 65536
- static const uint32_t [ACQ_BUFF_0](#) = 0
- static const uint32_t [ACQ_BUFF_1](#) = 1

12.139.1 Detailed Description

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for Galileo E1 Signals. Definition at line 33 of file [galileo_e1_pcps_ambiguous_acquisition_fpga.h](#).

12.139.2 Constructor & Destructor Documentation

12.139.2.1 GalileoE1PcpsAmbiguousAcquisitionFpga()

```
GalileoE1PcpsAmbiguousAcquisitionFpga::GalileoE1PcpsAmbiguousAcquisitionFpga (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

12.139.3 Member Function Documentation

12.139.3.1 implementation()

```
std::string GalileoE1PcpsAmbiguousAcquisitionFpga::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E1_PCPS_Ambiguous_Acquisition_FPGA".

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [galileo_e1_pcps_ambiguous_acquisition_fpga.h](#).

The documentation for this class was generated from the following file:

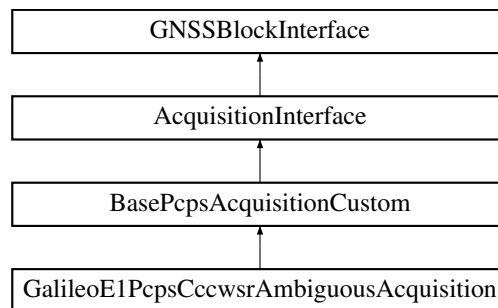
- [galileo_e1_pcps_ambiguous_acquisition_fpga.h](#)

12.140 GalileoE1PcpsCccwsrAmbiguousAcquisition Class Reference

Adapts a PCPS CCCWSR acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

```
#include <galileo_e1_pcps_cccwsr_ambiguous_acquisition.h>
```

Inheritance diagram for GalileoE1PcpsCccwsrAmbiguousAcquisition:



Public Member Functions

- **GalileoE1PcpsCccwsrAmbiguousAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "Galileo_E1_PCPS_CCCWSR_Ambiguous_Acquisition".
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- **BasePcpsAcquisitionCustom** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double code_length_chips, unsigned int ms_per_code, bool use_stream_to_vector, const [ThresholdComputeInterface](#) &threshold_compute, uint32_t max_sampled_ms=std::numeric_limits< uint32_t >::max())
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override

Set channel fsm associated to this acquisition instance.

- signed int [mag](#) () override

Returns the maximum peak of grid search.

- void [reset](#) () override

Restart acquisition algorithm.

- void [stop_acquisition](#) () override

Stop running acquisition.

- void [set_resampler_latency](#) (uint32_t) override

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_doppler_center](#) (int)

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- bool [is_type_gr_complex](#) () const

Protected Attributes inherited from [BasePcpsAcquisitionCustom](#)

- const [Acq_Conf](#) [acq_parameters_](#)
- acquisition_impl_interface_sptr [acquisition_cc_](#)
- [Gnss_Synchro](#) * [gnss_synchro_](#)
- unsigned int [channel_](#)
- volk_gnssdr::vector< std::complex< float > > [code_](#)

12.140.1 Detailed Description

Adapts a PCPS CCCWSR acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.
Definition at line 32 of file [galileo_e1_pcps_cccwsr_ambiguous_acquisition.h](#).

12.140.2 Member Function Documentation

12.140.2.1 implementation()

```
std::string GalileoE1PcpsCccwsrAmbiguousAcquisition::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E1_PCPS_CCCWSR_Ambiguous_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 46 of file [galileo_e1_pcps_cccwsr_ambiguous_acquisition.h](#).

12.140.2.2 set_local_code()

```
void GalileoE1PcpsCccwsrAmbiguousAcquisition::set_local_code () [override], [virtual]
```

Sets local code.

Reimplemented from [BasePcpsAcquisitionCustom](#).

The documentation for this class was generated from the following file:

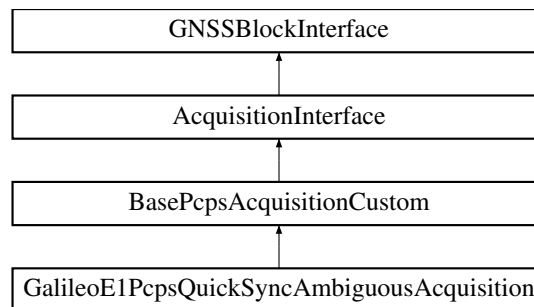
- [galileo_e1_pcps_cccwsr_ambiguous_acquisition.h](#)

12.141 GalileoE1PcpsQuickSyncAmbiguousAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

```
#include <galileo_e1_pcps_quicksync_ambiguous_acquisition.h>
```

Inheritance diagram for GalileoE1PcpsQuickSyncAmbiguousAcquisition:



Public Member Functions

- **GalileoE1PcpsQuickSyncAmbiguousAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "Galileo_E1_PCPS_Ambiguous_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- **BasePcpsAcquisitionCustom** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double code_length_chips, unsigned int ms_per_code, bool use_stream_to_vector, const [ThresholdComputeInterface](#) &threshold_compute, uint32_t max_sampled_ms=std::numeric_limits< uint32_t >::max())
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t) override
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_doppler_center](#) (int)

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from BasePcpsAcquisitionCustom

- bool [is_type_gr_complex](#) () const

Protected Attributes inherited from BasePcpsAcquisitionCustom

- const [Acq_Conf](#) [acq_parameters_](#)
- acquisition_impl_interface_sptr [acquisition_cc_](#)
- [Gnss_Synchro](#) * [gnss_synchro_](#)
- unsigned int [channel_](#)
- volk_gnssdr::vector< std::complex< float > > [code_](#)

12.141.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

Definition at line 32 of file [galileo_e1_pcps_quicksync_ambiguous_acquisition.h](#).

12.141.2 Member Function Documentation

12.141.2.1 implementation()

```
std::string GalileoE1PcpsQuickSyncAmbiguousAcquisition::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E1_PCPS_Ambiguous_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 46 of file [galileo_e1_pcps_quicksync_ambiguous_acquisition.h](#).

The documentation for this class was generated from the following file:

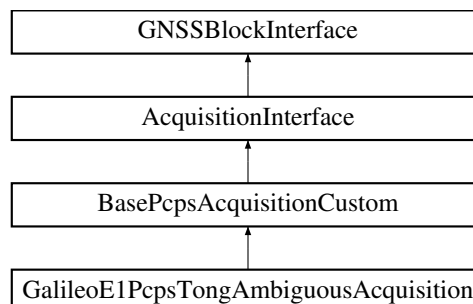
- [galileo_e1_pcps_quicksync_ambiguous_acquisition.h](#)

12.142 GalileoE1PcpsTongAmbiguousAcquisition Class Reference

Adapts a PCPS Tong acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

```
#include <galileo_e1_pcps_tong_ambiguous_acquisition.h>
```

Inheritance diagram for GalileoE1PcpsTongAmbiguousAcquisition:



Public Member Functions

- **GalileoE1PcpsTongAmbiguousAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "Galileo_E1_PCPS_Tong_Ambiguous_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- **BasePcpsAcquisitionCustom** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double code_length_chips, unsigned int ms_per_code, bool use_stream_to_vector, const [ThresholdComputeInterface](#) &threshold_compute, uint32_t max_sampled_ms=std::numeric_limits< uint32_t >::max())
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t) override
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_doppler_center](#) (int)

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- bool [is_type_gr_complex](#) () const

Protected Attributes inherited from [BasePcpsAcquisitionCustom](#)

- const [Acq_Conf](#) [acq_parameters_](#)
- [acquisition_impl_interface_sptr](#) [acquisition_cc_](#)
- [Gnss_Synchro](#) * [gnss_synchro_](#)
- unsigned int [channel_](#)
- [volk_gnss_sdr::vector](#)< [std::complex](#)< float > > [code_](#)

12.142.1 Detailed Description

Adapts a PCPS Tong acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.
Definition at line 32 of file [galileo_e1_pcps_tong_ambiguous_acquisition.h](#).

12.142.2 Member Function Documentation

12.142.2.1 implementation()

```
std::string GalileoE1PcpsTongAmbiguousAcquisition::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E1_PCPS_Tong_Ambiguous_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 46 of file [galileo_e1_pcps_tong_ambiguous_acquisition.h](#).

The documentation for this class was generated from the following file:

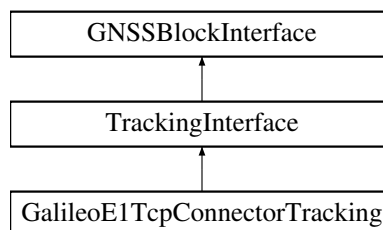
- [galileo_e1_pcps_tong_ambiguous_acquisition.h](#)

12.143 GalileoE1TcpConnectorTracking Class Reference

This class implements a code DLL + carrier PLL tracking loop.

```
#include <galileo_e1_tcp_connector_tracking.h>
```

Inheritance diagram for GalileoE1TcpConnectorTracking:



Public Member Functions

- **GalileoE1TcpConnectorTracking** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override
Returns "Galileo_E1_TCP_CONNECTOR_Tracking".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_channel](#) (unsigned int channel) override
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

- void [start_tracking](#) () override
- void [stop_tracking](#) () override

Stop running tracking.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.143.1 Detailed Description

This class implements a code DLL + carrier PLL tracking loop.

Definition at line 43 of file [galileo_e1_tcp_connector_tracking.h](#).

12.143.2 Member Function Documentation

12.143.2.1 connect()

```
void GalileoE1TcpConnectorTracking::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.143.2.2 disconnect()

```
void GalileoE1TcpConnectorTracking::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.143.2.3 get_left_block()

```
gr::basic_block_sptr GalileoE1TcpConnectorTracking::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.143.2.4 get_right_block()

```
gr::basic_block_sptr GalileoE1TcpConnectorTracking::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.143.2.5 implementation()

```
std::string GalileoE1TcpConnectorTracking::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E1_TCP_CONNECTOR_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 60 of file [galileo_e1_tcp_connector_tracking.h](#).

12.143.2.6 item_size()

```
size_t GalileoE1TcpConnectorTracking::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 65 of file [galileo_e1_tcp_connector_tracking.h](#).

12.143.2.7 role()

```
std::string GalileoE1TcpConnectorTracking::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 54 of file [galileo_e1_tcp_connector_tracking.h](#).

12.143.2.8 set_channel()

```
void GalileoE1TcpConnectorTracking::set_channel (
    unsigned int channel) [override], [virtual]
```

Set tracking channel unique ID.

Implements [TrackingInterface](#).

12.143.2.9 set_gnss_synchro()

```
void GalileoE1TcpConnectorTracking::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

Implements [TrackingInterface](#).

12.143.2.10 start_tracking()

```
void GalileoE1TcpConnectorTracking::start_tracking () [override], [virtual]
```

Implements [TrackingInterface](#).

12.143.2.11 stop_tracking()

```
void GalileoE1TcpConnectorTracking::stop_tracking () [override], [virtual]
```

Stop running tracking.

Implements [TrackingInterface](#).

The documentation for this class was generated from the following file:

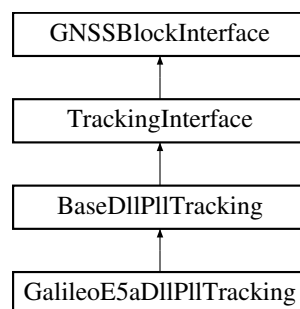
- [galileo_e1_tcp_connector_tracking.h](#)

12.144 GalileoE5aDlIPllTracking Class Reference

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E5a signals.

```
#include <galileo_e5a_dll_pll_tracking.h>
```

Inheritance diagram for GalileoE5aDlIPllTracking:



Public Member Functions

- [GalileoE5aDlIPllTracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)

Constructor.

- std::string [implementation](#) () override

Returns "Galileo_E5a_DLL_PLL_Tracking".

Public Member Functions inherited from BaseDIIPIITracking

- [BaseDIIPIITracking](#) (const [ConfigurationInterface](#) *configuration, std::string [role](#), unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDIIPIITracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override final
Get left block from the Tracking block adapter.
- gr::basic_block_sptr [get_right_block](#) () override final
Get right block from the Tracking block adapter.
- void [set_channel](#) (unsigned int channel) override final
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition Gnss_Synchro object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final
Start the Tracking block.
- void [stop_tracking](#) () override final
Stop the Tracking block.

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from BaseDIIPIITracking

- [DII_PII_Conf](#) & [config_params](#) ()
- const [DII_PII_Conf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t [item_size](#))

Protected Attributes inherited from BaseDIIPIITracking

- dll_pll_veml_tracking_sptr [tracking_sptr_](#)

12.144.1 Detailed Description

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E5a signals.

Definition at line 41 of file [galileo_e5a_dll_pll_tracking.h](#).

12.144.2 Constructor & Destructor Documentation

12.144.2.1 GalileoE5aDllPllTracking()

```
GalileoE5aDllPllTracking::GalileoE5aDllPllTracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDIIPllTracking::role\(\)](#).

12.144.3 Member Function Documentation

12.144.3.1 implementation()

```
std::string GalileoE5aDllPllTracking::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E5a_DLL_PLL_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 51 of file [galileo_e5a_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

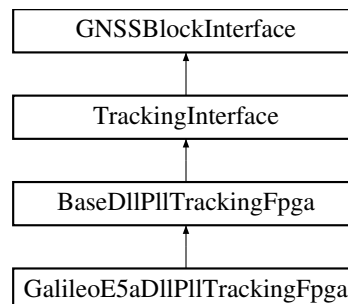
- [galileo_e5a_dll_pll_tracking.h](#)

12.145 GalileoE5aDIIPllTrackingFpga Class Reference

Adapter for a Galileo E5a DLL+PLL tracking loop implemented in FPGA.

```
#include <galileo_e5a_dll_pll_tracking_fpga.h>
```

Inheritance diagram for GalileoE5aDIIPllTrackingFpga:



Public Member Functions

- [GalileoE5aDIIPllTrackingFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- [~GalileoE5aDIIPllTrackingFpga](#) () override
Destructor.
- std::string [implementation](#) () override
Returns "Galileo_E5a_DLL_PLL_Tracking_FPGA".

Public Member Functions inherited from [BaseDIIPllTrackingFpga](#)

- [BaseDIIPllTrackingFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Base constructor of FPGA-based Tracking block adapters.
- virtual [~BaseDIIPllTrackingFpga](#) ()=default

- *Base destructor of FPGA-based Tracking block adapters.*
- `std::string role ()` override
Get role from the Tracking block adapter.
- `size_t item_size ()` override
Get item_size from the Tracking block adapter.
- `void connect (gr::top_block_sptr top_block)` override
Connect the Tracking block adapter.
- `void disconnect (gr::top_block_sptr top_block)` override
Disconnect the Tracking block adapter.
- `gr::basic_block_sptr get_left_block ()` override
Get left block from the Tracking block adapter.
- `gr::basic_block_sptr get_right_block ()` override
Get right block from the Tracking block adapter.
- `void start_tracking ()` override
Start the tracking process in the FPGA.
- `void stop_tracking ()` override
Stop the tracking process in the FPGA.
- `void configure_fpga_tracking_channel_mapping (std::string signal)`
configure FPGA tracking channel mapping
- `void set_channel (unsigned int channel)` override
Set tracking channel unique ID.
- `void set_gnss_synchro (Gnss_Synchro *p_gnss_synchro)` override
Set acquisition/tracking common Gnss_Synchro object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

Public Member Functions inherited from GNSSBlockInterface

- virtual `gr::basic_block_sptr get_left_block (int RF_channel)`
- virtual `gr::basic_block_sptr get_right_block (int RF_channel)`
- virtual `void start ()`
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from BaseDIIPIITrackingFpga

- `DII_PII_Conf_Fpga & config_params_fpga ()`
- `const DII_PII_Conf_Fpga & config_params_fpga () const`

Protected Attributes inherited from BaseDIIPIITrackingFpga

- `dll_pll_veml_tracking_fpga_sptr tracking_fpga_sc_sptr_`

Static Protected Attributes inherited from BaseDIIPIITrackingFpga

- `static const int32_t LOCAL_CODE_FPGA_ENABLE_WRITE_MEMORY = 0x0C000000`
- `static const int32_t LOCAL_CODE_FPGA_CORRELATOR_SELECT_COUNT = 0x20000000`

12.145.1 Detailed Description

Adapter for a Galileo E5a DLL+PLL tracking loop implemented in FPGA.

Definition at line 31 of file `galileo_e5a_dll_pll_tracking_fpga.h`.

12.145.2 Constructor & Destructor Documentation

12.145.2.1 GalileoE5aDllPllTrackingFpga()

```
GalileoE5aDllPllTrackingFpga::GalileoE5aDllPllTrackingFpga (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDllPllTrackingFpga::role\(\)](#).

12.145.2.2 ~GalileoE5aDllPllTrackingFpga()

```
GalileoE5aDllPllTrackingFpga::~GalileoE5aDllPllTrackingFpga () [override]
```

Destructor.

12.145.3 Member Function Documentation

12.145.3.1 implementation()

```
std::string GalileoE5aDllPllTrackingFpga::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E5a_DLL_PLL_Tracking_FPGA".

Implements [GNSSBlockInterface](#).

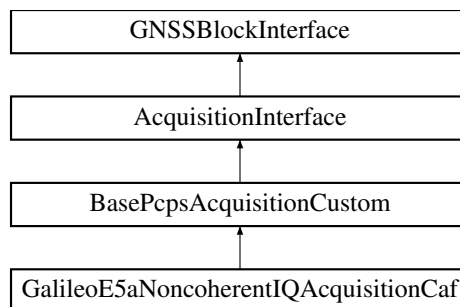
Definition at line 50 of file [galileo_e5a_dll_pll_tracking_fpga.h](#).

The documentation for this class was generated from the following file:

- [galileo_e5a_dll_pll_tracking_fpga.h](#)

12.146 GalileoE5aNoncoherentIQAcquisitionCaf Class Reference

Inheritance diagram for GalileoE5aNoncoherentIQAcquisitionCaf:



Public Member Functions

- **GalileoE5aNoncoherentIQAcquisitionCaf** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "Galileo_E5a_Noncoherent_IQ_Acquisition_CAF".
- void [set_local_code](#) () override
Sets local Galileo E5a code for PCPS acquisition algorithm.

Public Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- **BasePcpsAcquisitionCustom** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double code_length_chips, unsigned int ms_per_code, bool use_stream_to_vector, const [ThresholdComputeInterface](#) &threshold_compute, uint32_t max_sampled_ms=std::numeric_limits< uint32_t >::max())

- `std::string role ()` override
- `size_t item_size ()` override
- `void connect (gr::top_block_sptr top_block)` override
- `void disconnect (gr::top_block_sptr top_block)` override
- `gr::basic_block_sptr get_left_block ()` override
- `gr::basic_block_sptr get_right_block ()` override
- `void set_gnss_synchro (Gnss_Synchro *p_gnss_synchro)` override
Set acquisition/tracking common Gnss_Synchro object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- `void set_channel (unsigned int channel)` override
Set acquisition channel unique ID.
- `void set_channel_fsm (std::weak_ptr< ChannelFsm > channel_fsm)` override
Set channel fsm associated to this acquisition instance.
- `signed int mag ()` override
Returns the maximum peak of grid search.
- `void reset ()` override
Restart acquisition algorithm.
- `void stop_acquisition ()` override
Stop running acquisition.
- `void set_resampler_latency (uint32_t)` override

Public Member Functions inherited from AcquisitionInterface

- virtual `void set_doppler_center (int)`

Public Member Functions inherited from GNSSBlockInterface

- virtual `gr::basic_block_sptr get_left_block (int RF_channel)`
- virtual `gr::basic_block_sptr get_right_block (int RF_channel)`
- virtual `void start ()`
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from BasePcpsAcquisitionCustom

- `bool is_type_gr_complex ()` const

Protected Attributes inherited from BasePcpsAcquisitionCustom

- const `Acq_Conf acq_parameters_`
- `acquisition_impl_interface_sptr acquisition_cc_`
- `Gnss_Synchro * gnss_synchro_`
- unsigned int `channel_`
- `volk_gnss_sdr::vector< std::complex< float > > code_`

12.146.1 Detailed Description

Definition at line 34 of file `galileo_e5a_noncoherent_iq_acquisition_caf.h`.

12.146.2 Member Function Documentation

12.146.2.1 implementation()

```
std::string GalileoE5aNoncoherentIQAcquisitionCaf::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E5a_Noncoherent_IQ_Acquisition_CAF".

Implements [GNSSBlockInterface](#).

Definition at line 47 of file [galileo_e5a_noncoherent_iq_acquisition_caf.h](#).

12.146.2.2 set_local_code()

```
void GalileoE5aNoncoherentIQAcquisitionCaf::set_local_code () [override], [virtual]
```

Sets local Galileo E5a code for PCPS acquisition algorithm.

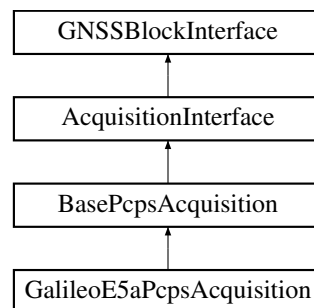
Reimplemented from [BasePcpsAcquisitionCustom](#).

The documentation for this class was generated from the following file:

- [galileo_e5a_noncoherent_iq_acquisition_caf.h](#)

12.147 GalileoE5aPcpsAcquisition Class Reference

Inheritance diagram for GalileoE5aPcpsAcquisition:



Public Member Functions

- **GalileoE5aPcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override

Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override

- Set channel fsm associated to this acquisition instance.*

 - void [set_doppler_center](#) (int doppler_center) override

Set Doppler center for the grid search.
- signed int [mag](#) () override

Returns the maximum peak of grid search.
- void [reset](#) () override

Restart acquisition algorithm.
- void [stop_acquisition](#) () override

Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t latency_samples) override

Sets the resampler latency to account it in the acquisition code delay estimation.
- void [set_local_code](#) () override

Sets local code.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
 - virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
 - virtual void [start](#) ()
- Start the flow of samples if needed.*

12.147.1 Detailed Description

Definition at line 30 of file [galileo_e5a_pcps_acquisition.h](#).

12.147.2 Member Function Documentation

12.147.2.1 implementation()

```
std::string GalileoE5aPcpsAcquisition::implementation () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 41 of file [galileo_e5a_pcps_acquisition.h](#).

The documentation for this class was generated from the following file:

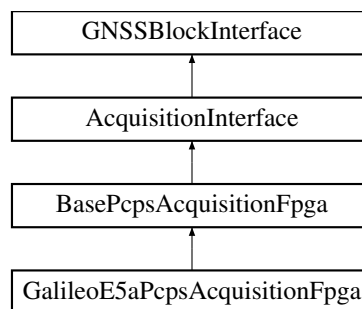
- [galileo_e5a_pcps_acquisition.h](#)

12.148 GalileoE5aPcpsAcquisitionFpga Class Reference

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for Galileo E5a signals.

```
#include <galileo_e5a_pcps_acquisition_fpga.h>
```

Inheritance diagram for GalileoE5aPcpsAcquisitionFpga:



Public Member Functions

- [GalileoE5aPcpsAcquisitionFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "Galileo_E5a_Pcps_Acquisition_FPGA".

Public Member Functions inherited from [BasePcpsAcquisitionFpga](#)

- **[BasePcpsAcquisitionFpga](#)** (const [ConfigurationInterface](#) *configuration, std::string role, double code_rate_cps, double code_length_chips, uint32_t opt_acq_fs_sps, uint32_t default_fpga_blk_exp, uint32_t acq_buff, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override final
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- signed int [mag](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
- void [set_channel](#) (unsigned int channel) override
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
- void [set_doppler_center](#) (int doppler_center) override
- void [reset](#) () override
- void [stop_acquisition](#) () override
- void [set_resampler_latency](#) (uint32_t latency_samples __attribute__((unused))) override
- void [set_local_code](#) () override

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_resampler_latency](#) (uint32_t latency_samples)=0

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionFpga](#)

- void [init](#) ()

Protected Attributes inherited from [BasePcpsAcquisitionFpga](#)

- volk_gnssdr::vector< uint32_t > [d_all_fft_codes_](#)
- [Acq_Conf_Fpga](#) [acq_parameters_](#)

Static Protected Attributes inherited from [BasePcpsAcquisitionFpga](#)

- static const uint32_t [QUANT_BITS_LOCAL_CODE](#) = 16
- static const uint32_t [SELECT_LSBITS](#) = 0x0000FFFF
- static const uint32_t [SELECT_MSBITS](#) = 0xFFFF0000
- static const uint32_t [SELECT_ALL_CODE_BITS](#) = 0xFFFFFFFF
- static const uint32_t [SHL_CODE_BITS](#) = 65536
- static const uint32_t [ACQ_BUFF_0](#) = 0
- static const uint32_t [ACQ_BUFF_1](#) = 1

12.148.1 Detailed Description

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for Galileo E5a signals. Definition at line 33 of file [galileo_e5a_pcps_acquisition_fpga.h](#).

12.148.2 Constructor & Destructor Documentation

12.148.2.1 GalileoE5aPcpsAcquisitionFpga()

```
GalileoE5aPcpsAcquisitionFpga::GalileoE5aPcpsAcquisitionFpga (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

12.148.3 Member Function Documentation

12.148.3.1 implementation()

```
std::string GalileoE5aPcpsAcquisitionFpga::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E5a_Pcps_Acquisition_FPGA".

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [galileo_e5a_pcps_acquisition_fpga.h](#).

The documentation for this class was generated from the following file:

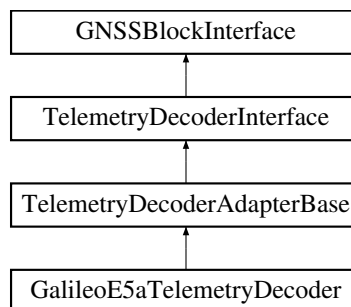
- [galileo_e5a_pcps_acquisition_fpga.h](#)

12.149 GalileoE5aTelemetryDecoder Class Reference

This class implements a NAV data decoder for Galileo INAV frames in E1B radio link.

```
#include <galileo_e5a_telemetry_decoder.h>
```

Inheritance diagram for GalileoE5aTelemetryDecoder:



Public Member Functions

- **GalileoE5aTelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "Galileo_E5a_Telemetry_Decoder".

Public Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- void **InitializeDecoder** (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & **satellite** () const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- [Tlm_Conf](#) tlm_parameters_

12.149.1 Detailed Description

This class implements a NAV data decoder for Galileo INAV frames in E1B radio link.
Definition at line 38 of file [galileo_e5a_telemetry_decoder.h](#).

12.149.2 Member Function Documentation

12.149.2.1 [implementation\(\)](#)

```
std::string GalileoE5aTelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E5a_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 50 of file [galileo_e5a_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

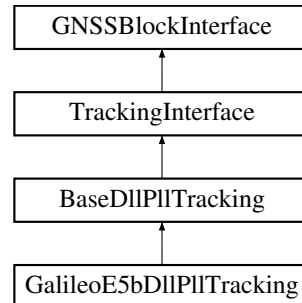
- [galileo_e5a_telemetry_decoder.h](#)

12.150 GalileoE5bDIIPITracking Class Reference

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E5b signals.

```
#include <galileo_e5b_dll_pll_tracking.h>
```

Inheritance diagram for GalileoE5bDIIPITracking:



Public Member Functions

- [GalileoE5bDIIPITracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "Galileo_E5b_DLL_PLL_Tracking".

Public Member Functions inherited from [BaseDIIPITracking](#)

- [BaseDIIPITracking](#) (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDIIPITracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override final
Get left block from the Tracking block adapter.
- gr::basic_block_sptr [get_right_block](#) () override final
Get right block from the Tracking block adapter.
- void [set_channel](#) (unsigned int channel) override final
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition Gnss_Synchro object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final
Start the Tracking block.
- void [stop_tracking](#) () override final
Stop the Tracking block.

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from BaseDIPIITracking

- [Dll_Pll_Conf](#) & [config_params](#) ()
- const [Dll_Pll_Conf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t item_size)

Protected Attributes inherited from BaseDIPIITracking

- dll_pll_veml_tracking_sptr [tracking_sptr_](#)

12.150.1 Detailed Description

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E5b signals.

Definition at line 42 of file [galileo_e5b_dll_pll_tracking.h](#).

12.150.2 Constructor & Destructor Documentation

12.150.2.1 GalileoE5bDIPIITracking()

```
GalileoE5bDllPllTracking::GalileoE5bDllPllTracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDIPIITracking::role\(\)](#).

12.150.3 Member Function Documentation

12.150.3.1 implementation()

```
std::string GalileoE5bDllPllTracking::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E5b_DLL_PLL_Tracking".

Implements [GNSSBlockInterface](#).

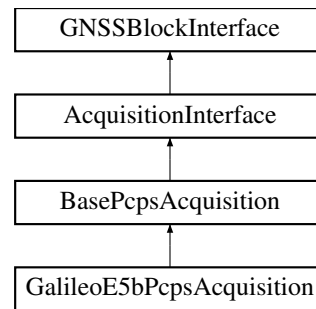
Definition at line 52 of file [galileo_e5b_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

- [galileo_e5b_dll_pll_tracking.h](#)

12.151 GalileoE5bPcpsAcquisition Class Reference

Inheritance diagram for GalileoE5bPcpsAcquisition:



Public Member Functions

- [GalileoE5bPcpsAcquisition](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- [~GalileoE5bPcpsAcquisition](#) ()=default
Destructor.
- std::string [implementation](#) () override
Returns "GALILEO_E5b_PCPS_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int doppler_center) override
Set Doppler center for the grid search.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t latency_samples) override
Sets the resampler latency to account it in the acquisition code delay estimation.
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.151.1 Detailed Description

Definition at line 30 of file [galileo_e5b_pcps_acquisition.h](#).

12.151.2 Constructor & Destructor Documentation

12.151.2.1 GalileoE5bPcpsAcquisition()

```
GalileoE5bPcpsAcquisition::GalileoE5bPcpsAcquisition (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

12.151.2.2 ~GalileoE5bPcpsAcquisition()

```
GalileoE5bPcpsAcquisition::~~GalileoE5bPcpsAcquisition () [default]
```

Destructor.

12.151.3 Member Function Documentation

12.151.3.1 implementation()

```
std::string GalileoE5bPcpsAcquisition::implementation () [inline], [override], [virtual]
```

Returns "GALILEO_E5b_PCPS_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 50 of file [galileo_e5b_pcps_acquisition.h](#).

The documentation for this class was generated from the following file:

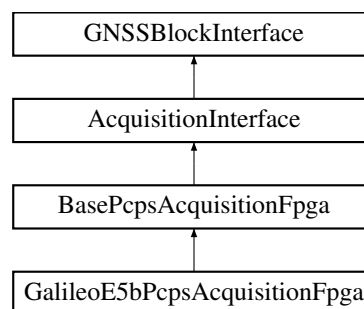
- [galileo_e5b_pcps_acquisition.h](#)

12.152 GalileoE5bPcpsAcquisitionFpga Class Reference

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for Galileo E5b signals.

```
#include <galileo_e5b_pcps_acquisition_fpga.h>
```

Inheritance diagram for GalileoE5bPcpsAcquisitionFpga:



Public Member Functions

- [GalileoE5bPcpsAcquisitionFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "Galileo_E5b_Pcps_Acquisition_FPGA".

Public Member Functions inherited from [BasePcpsAcquisitionFpga](#)

- **[BasePcpsAcquisitionFpga](#)** (const [ConfigurationInterface](#) *configuration, std::string role, double code_rate_cps, double code_length_chips, uint32_t opt_acq_fs_sps, uint32_t default_fpga_blk_exp, uint32_t acq_buff, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override final
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- signed int [mag](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
- void [set_channel](#) (unsigned int channel) override
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
- void [set_doppler_center](#) (int doppler_center) override
- void [reset](#) () override
- void [stop_acquisition](#) () override
- void [set_resampler_latency](#) (uint32_t latency_samples __attribute__((unused))) override
- void [set_local_code](#) () override

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_resampler_latency](#) (uint32_t latency_samples)=0

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionFpga](#)

- void [init](#) ()

Protected Attributes inherited from [BasePcpsAcquisitionFpga](#)

- volk_gnssdr::vector< uint32_t > [d_all_fft_codes_](#)
- [Acq_Conf_Fpga](#) [acq_parameters_](#)

Static Protected Attributes inherited from [BasePcpsAcquisitionFpga](#)

- static const uint32_t [QUANT_BITS_LOCAL_CODE](#) = 16
- static const uint32_t [SELECT_LSBITS](#) = 0x0000FFFF
- static const uint32_t [SELECT_MSBITS](#) = 0xFFFF0000
- static const uint32_t [SELECT_ALL_CODE_BITS](#) = 0xFFFFFFFF
- static const uint32_t [SHL_CODE_BITS](#) = 65536
- static const uint32_t [ACQ_BUFF_0](#) = 0
- static const uint32_t [ACQ_BUFF_1](#) = 1

12.152.1 Detailed Description

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for Galileo E5b signals. Definition at line 34 of file [galileo_e5b_pcps_acquisition_fpga.h](#).

12.152.2 Constructor & Destructor Documentation

12.152.2.1 GalileoE5bPcpsAcquisitionFpga()

```
GalileoE5bPcpsAcquisitionFpga::GalileoE5bPcpsAcquisitionFpga (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

12.152.3 Member Function Documentation

12.152.3.1 implementation()

```
std::string GalileoE5bPcpsAcquisitionFpga::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E5b_Pcps_Acquisition_FPGA".

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [galileo_e5b_pcps_acquisition_fpga.h](#).

The documentation for this class was generated from the following file:

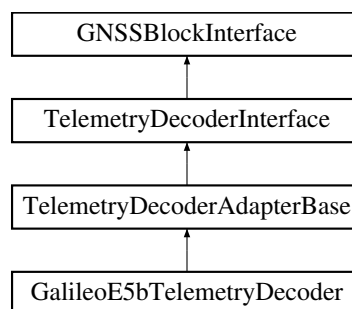
- [galileo_e5b_pcps_acquisition_fpga.h](#)

12.153 GalileoE5bTelemetryDecoder Class Reference

This class implements a NAV data decoder for Galileo INAV frames in E5b radio link.

```
#include <galileo_e5b_telemetry_decoder.h>
```

Inheritance diagram for GalileoE5bTelemetryDecoder:



Public Member Functions

- **GalileoE5bTelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "Galileo_E5b_Telemetry_Decoder".

Public Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- void **InitializeDecoder** (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & **satellite** () const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- [Tlm_Conf](#) tlm_parameters_

12.153.1 Detailed Description

This class implements a NAV data decoder for Galileo INAV frames in E5b radio link.
Definition at line 36 of file [galileo_e5b_telemetry_decoder.h](#).

12.153.2 Member Function Documentation

12.153.2.1 [implementation\(\)](#)

```
std::string GalileoE5bTelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E5b_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [galileo_e5b_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

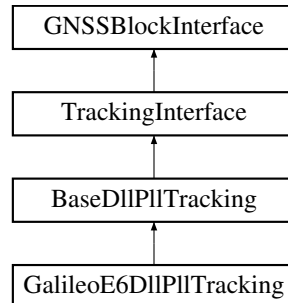
- [galileo_e5b_telemetry_decoder.h](#)

12.154 GalileoE6DIPIITracking Class Reference

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E5a signals.

```
#include <galileo_e6_dll_pll_tracking.h>
```

Inheritance diagram for GalileoE6DIPIITracking:



Public Member Functions

- [GalileoE6DIPIITracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "Galileo_E6_DLL_PLL_Tracking".

Public Member Functions inherited from [BaseDIPIITracking](#)

- [BaseDIPIITracking](#) (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDIPIITracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override final
Get left block from the Tracking block adapter.
- gr::basic_block_sptr [get_right_block](#) () override final
Get right block from the Tracking block adapter.
- void [set_channel](#) (unsigned int channel) override final
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition Gnss_Synchro object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final
Start the Tracking block.
- void [stop_tracking](#) () override final
Stop the Tracking block.

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from BaseDIPIITracking

- [Dll_Pll_Conf](#) & [config_params](#) ()
- const [Dll_Pll_Conf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t item_size)

Protected Attributes inherited from BaseDIPIITracking

- [dll_pll_veml_tracking_sptr](#) [tracking_sptr_](#)

12.154.1 Detailed Description

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E5a signals.

Definition at line 37 of file [galileo_e6_dll_pll_tracking.h](#).

12.154.2 Constructor & Destructor Documentation

12.154.2.1 GalileoE6DIPIITracking()

```
GalileoE6D11P11Tracking::GalileoE6D11P11Tracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDIPIITracking::role\(\)](#).

12.154.3 Member Function Documentation

12.154.3.1 implementation()

```
std::string GalileoE6D11P11Tracking::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E6_DLL_PLL_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 47 of file [galileo_e6_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

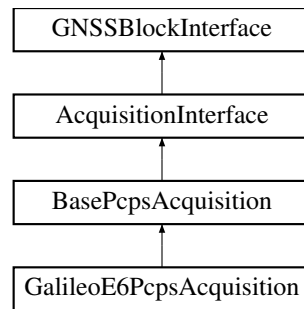
- [galileo_e6_dll_pll_tracking.h](#)

12.155 GalileoE6PcpsAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E6 Signals.

```
#include <galileo_e6_pcps_acquisition.h>
```

Inheritance diagram for GalileoE6PcpsAcquisition:



Public Member Functions

- **GalileoE6PcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "Galileo_E6_PCPS_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int doppler_center) override
Set Doppler center for the grid search.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t latency_samples) override
Sets the resampler latency to account it in the acquisition code delay estimation.
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

12.155.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E6 Signals.
Definition at line 33 of file [galileo_e6_pcps_acquisition.h](#).

12.155.2 Member Function Documentation

12.155.2.1 implementation()

```
std::string GalileoE6PcpsAcquisition::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E6_PCPS_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 47 of file [galileo_e6_pcps_acquisition.h](#).

The documentation for this class was generated from the following file:

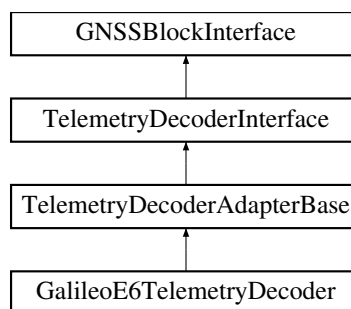
- [galileo_e6_pcps_acquisition.h](#)

12.156 GalileoE6TelemetryDecoder Class Reference

This class implements a NAV data decoder for Galileo CNAV frames in E6 radio link.

```
#include <galileo_e6_telemetry_decoder.h>
```

Inheritance diagram for GalileoE6TelemetryDecoder:



Public Member Functions

- **GalileoE6TelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "Galileo_E6_Telemetry_Decoder".

Public Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from TelemetryDecoderAdapterBase

- void **InitializeDecoder** (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & **satellite** () const

Protected Attributes inherited from TelemetryDecoderAdapterBase

- [Tlm_Conf](#) tlm_parameters_

12.156.1 Detailed Description

This class implements a NAV data decoder for Galileo CNAV frames in E6 radio link.
Definition at line 35 of file [galileo_e6_telemetry_decoder.h](#).

12.156.2 Member Function Documentation

12.156.2.1 implementation()

```
std::string GalileoE6TelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "Galileo_E6_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 47 of file [galileo_e6_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

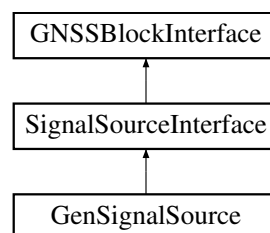
- [galileo_e6_telemetry_decoder.h](#)

12.157 GenSignalSource Class Reference

This class wraps blocks that generates synthesized GNSS signal and filters the signal.

```
#include <gen_signal_source.h>
```

Inheritance diagram for GenSignalSource:



Public Member Functions

- [GenSignalSource](#) (std::shared_ptr< [GNSSBlockInterface](#) > signal_generator, std::shared_ptr< [GNSSBlockInterface](#) > filter, std::string role, [Concurrent_Queue](#)< pmt::pmt_t > *queue)

Constructor.

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override

- `gr::basic_block_sptr` [get_right_block](#) () override
- `std::string` [role](#) () override
- `std::string` [implementation](#) () override
- *Returns "Signal Source".*
- `size_t` [item_size](#) () override
- `size_t` [getRfChannels](#) () const final
- `std::shared_ptr< GNSSBlockInterface >` [signal_generator](#) () const

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual `gr::basic_block_sptr` [get_left_block](#) (int RF_channel)
- virtual `gr::basic_block_sptr` [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.157.1 Detailed Description

This class wraps blocks that generates synthesized GNSS signal and filters the signal.
Definition at line 41 of file [gen_signal_source.h](#).

12.157.2 Constructor & Destructor Documentation

12.157.2.1 GenSignalSource()

```
GenSignalSource::GenSignalSource (
    std::shared_ptr< GNSSBlockInterface > signal_generator,
    std::shared_ptr< GNSSBlockInterface > filter,
    std::string role,
    Concurrent_Queue< pmt::pmt_t > * queue)
```

Constructor.

12.157.3 Member Function Documentation

12.157.3.1 connect()

```
void GenSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.157.3.2 disconnect()

```
void GenSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.157.3.3 get_left_block()

```
gr::basic_block_sptr GenSignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.157.3.4 get_right_block()

```
gr::basic_block_sptr GenSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.157.3.5 getRfChannels()

```
size_t GenSignalSource::getRfChannels () const [inline], [final], [virtual]
```

Implements [SignalSourceInterface](#).

Definition at line 57 of file [gen_signal_source.h](#).

12.157.3.6 implementation()

```
std::string GenSignalSource::implementation () [inline], [override], [virtual]
```

Returns "Signal Source".

Implements [GNSSBlockInterface](#).

Definition at line 55 of file [gen_signal_source.h](#).

12.157.3.7 item_size()

```
size_t GenSignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 56 of file [gen_signal_source.h](#).

12.157.3.8 role()

```
std::string GenSignalSource::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 53 of file [gen_signal_source.h](#).

12.157.3.9 signal_generator()

```
std::shared_ptr< GNSSBlockInterface > GenSignalSource::signal_generator () const [inline]
```

Definition at line 59 of file [gen_signal_source.h](#).

The documentation for this class was generated from the following file:

- [gen_signal_source.h](#)

12.158 Geohash Class Reference

Class for geohash encoding / decoding See <https://en.wikipedia.org/wiki/Geohash>.

```
#include <geohash.h>
```

Public Member Functions

- std::string [encode](#) (double lat, double lon, int precision=-1) const
- std::array< double, 2 > [decode](#) (std::string geohash) const

12.158.1 Detailed Description

Class for geohash encoding / decoding See <https://en.wikipedia.org/wiki/Geohash>.

Definition at line 34 of file [geohash.h](#).

12.158.2 Member Function Documentation

12.158.2.1 decode()

```
std::array< double, 2 > Geohash::decode (
    std::string geohash) const
```

Decode geohash to latitude/longitude (location is approximate centre of geohash cell, to reasonable precision).

Parameters

<i>{string}</i>	geohash - Geohash string to be converted to latitude/longitude.
-----------------	---

Returns

{lat, lon} (Center of) geohashed location.

Exceptions

<i>Invalid</i>	geohash.
----------------	----------

12.158.2.2 encode()

```
std::string Geohash::encode (
    double lat,
    double lon,
    int precision = -1) const
```

Encodes latitude/longitude to geohash, either to specified precision or to automatically evaluated precision.

Parameters

<i>{double}</i>	lat - Latitude in degrees.
<i>{double}</i>	lon - Longitude in degrees.
<i>{int}</i>	[precision] - Number of characters in resulting geohash.

Returns

{string} [Geohash](#) of supplied latitude/longitude.

Exceptions

<i>Invalid</i>	geohash.
----------------	----------

The documentation for this class was generated from the following file:

- [geohash.h](#)

12.159 GeoJSON_Printer Class Reference

Prints PVT solutions in GeoJSON format file.

```
#include <geojson_printer.h>
```

Public Member Functions

- **GeoJSON_Printer** (const std::string &base_path=".")
- bool **set_headers** (const std::string &filename, bool time_tag_name=true)
- bool **print_position** (const [Pvt_Solution](#) *const position)
- bool **close_file** ()

12.159.1 Detailed Description

Prints PVT solutions in GeoJSON format file.

See <https://tools.ietf.org/html/rfc7946>

Definition at line 39 of file [geojson_printer.h](#).

The documentation for this class was generated from the following file:

- [geojson_printer.h](#)

12.160 `geph_t` Struct Reference

Public Attributes

- int `sat`
- int `iode`
- int `frq`
- int `svh`
- int `sva`
- int `age`
- `gtime_t` `toe`
- `gtime_t` `tof`
- double `pos` [3]
- double `vel` [3]
- double `acc` [3]
- double `taun`
- double `gamn`
- double `dtaun`

12.160.1 Detailed Description

Definition at line 463 of file `rtklib.h`.

12.160.2 Member Data Documentation

12.160.2.1 `acc`

```
double geph_t::acc[3]
```

Definition at line 473 of file `rtklib.h`.

12.160.2.2 `age`

```
int geph_t::age
```

Definition at line 468 of file `rtklib.h`.

12.160.2.3 `dtaun`

```
double geph_t::dtaun
```

Definition at line 475 of file `rtklib.h`.

12.160.2.4 `frq`

```
int geph_t::frq
```

Definition at line 467 of file `rtklib.h`.

12.160.2.5 `gamn`

```
double geph_t::gamn
```

Definition at line 474 of file `rtklib.h`.

12.160.2.6 `iode`

```
int geph_t::iode
```

Definition at line 466 of file `rtklib.h`.

12.160.2.7 `pos`

```
double geph_t::pos[3]
```

Definition at line 471 of file `rtklib.h`.

12.160.2.8 sat

```
int geph_t::sat
```

Definition at line 465 of file [rtklib.h](#).

12.160.2.9 sva

```
int geph_t::sva
```

Definition at line 468 of file [rtklib.h](#).

12.160.2.10 svh

```
int geph_t::svh
```

Definition at line 468 of file [rtklib.h](#).

12.160.2.11 taun

```
double geph_t::taun
```

Definition at line 474 of file [rtklib.h](#).

12.160.2.12 toe

```
gtime_t geph_t::toe
```

Definition at line 469 of file [rtklib.h](#).

12.160.2.13 tof

```
gtime_t geph_t::tof
```

Definition at line 470 of file [rtklib.h](#).

12.160.2.14 vel

```
double geph_t::vel[3]
```

Definition at line 472 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.161 Glonass_Gnav_Almanac Class Reference

This class is a storage for the GLONASS SV ALMANAC data as described GLONASS ICD (Edition 5.1)

```
#include <glonass_gnav_almanac.h>
```

Public Member Functions

- [Glonass_Gnav_Almanac](#) ()=default
- `template<class Archive>`
void [serialize](#) (Archive &archive, const uint32_t version)

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the almanac data on disk file.

Public Attributes

- double [d_n_A](#) {}
Conventional number of satellite within GLONASS space segment [dimensionless].
- double [d_H_n_A](#) {}
Carrier frequency number of navigation RF signal transmitted by d_nA satellite as table 4.10 (0-31) [dimensionless].
- double [d_lambda_n_A](#) {}

- Longitude of the first (within the d_nA day) ascending node of d_nA [radians].*
- double [d_t_lambda_n_A](#) {}
Time of first ascending node passage [s].
- double [d_Delta_i_n_A](#) {}
Correction of the mean value of inclination of d_n_A satellite at instant t_lambda_n_A [radians].
- double [d_Delta_T_n_A](#) {}
Correction to the mean value of Draconian period of d_n_A satellite at instant t_lambda_n_A [s / orbital period].
- double [d_Delta_T_n_A_dot](#) {}
Rate of change of Draconian period of d_n_A satellite at instant t_lambda_n_A [s / orbital period²].
- double [d_epsilon_n_A](#) {}
Eccentricity of d_n_A satellite at instant t_lambda_n_A [dimensionless].
- double [d_omega_n_A](#) {}
Argument of perigee of d_n_A satellite at instant t_lambda_n_A [radians].
- double [d_M_n_A](#) {}
Type of satellite n_A [dimensionless].
- double [d_KP](#) {}
Notification on forthcoming leap second correction of UTC [dimensionless].
- double [d_tau_n_A](#) {}
Coarse value of d_n_A satellite time correction to GLONASS time at instant t_lambda_n_A[s].
- bool [d_C_n](#) {}
Generalized "unhealthy flag" of n_A satellite at instant of almanac upload [dimensionless].
- bool [d_I_n](#) {}
Health flag for nth satellite; In = 0 indicates the n-th satellite is healthy, In = 1 indicates malfunction of this nth satellite [dimensionless].
- int32_t [i_satellite_freq_channel](#) {}
SV Frequency Channel Number.
- uint32_t [PRN](#) {}
SV PRN Number, equivalent to slot number for compatibility with GPS.
- uint32_t [i_satellite_slot_number](#) {}
SV Slot Number.

12.161.1 Detailed Description

This class is a storage for the GLONASS SV ALMANAC data as described GLONASS ICD (Edition 5.1)

Note

Code added as part of GSoC 2017 program

See also

[GLONASS ICD](#)

Definition at line 37 of file [glonass_gnav_almanac.h](#).

12.161.2 Constructor & Destructor Documentation

12.161.2.1 Glonass_Gnav_Almanac()

```
Glonass_Gnav_Almanac::Glonass_Gnav_Almanac () [default]
```

Default constructor

12.161.3 Member Function Documentation

12.161.3.1 serialize()

```
template<class Archive>
void Glonass_Gnav_Almanac::serialize (
    Archive & archive,
    const uint32_t version) [inline]
```

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the almanac data on disk file.

Definition at line 70 of file [glonass_gnav_almanac.h](#).

References [d_C_n](#), [d_Delta_i_n_A](#), [d_Delta_T_n_A](#), [d_Delta_T_n_A_dot](#), [d_epsilon_n_A](#), [d_H_n_A](#), [d_KP](#), [d_I_n](#), [d_lambda_n_A](#), [d_M_n_A](#), [d_n_A](#), [d_omega_n_A](#), [d_t_lambda_n_A](#), [d_tau_n_A](#), [i_satellite_freq_channel](#), [i_satellite_slot_number](#), and [PRN](#).

12.161.4 Member Data Documentation

12.161.4.1 d_C_n

```
bool Glonass_Gnav_Almanac::d_C_n {}
```

Generalized “unhealthy flag” of n_A satellite at instant of almanac upload [dimensionless].

Definition at line 57 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.2 d_Delta_i_n_A

```
double Glonass_Gnav_Almanac::d_Delta_i_n_A {}
```

Correction of the mean value of inclination of d_n_A satellite at instant $t_{\lambda n_A}$ [radians].

Definition at line 49 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.3 d_Delta_T_n_A

```
double Glonass_Gnav_Almanac::d_Delta_T_n_A {}
```

Correction to the mean value of Draconian period of d_n_A satellite at instant $t_{\lambda n_A}$ [s / orbital period].

Definition at line 50 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.4 d_Delta_T_n_A_dot

```
double Glonass_Gnav_Almanac::d_Delta_T_n_A_dot {}
```

Rate of change of Draconian period of d_n_A satellite at instant $t_{\lambda n_A}$ [s / orbital period²].

Definition at line 51 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.5 d_epsilon_n_A

```
double Glonass_Gnav_Almanac::d_epsilon_n_A {}
```

Eccentricity of d_n_A satellite at instant $t_{\lambda n_A}$ [dimensionless].

Definition at line 52 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.6 d_H_n_A

```
double Glonass_Gnav_Almanac::d_H_n_A {}
```

Carrier frequency number of navigation RF signal transmitted by d_n_A satellite as table 4.10 (0-31) [dimensionless].

Definition at line 46 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.7 d_KP

```
double Glonass_Gnav_Almanac::d_KP {}
```

Notification on forthcoming leap second correction of UTC [dimensionless].

Definition at line 55 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.8 d_l_n

```
bool Glonass_Gnav_Almanac::d_l_n {}
```

Health flag for nth satellite; l_n = 0 indicates the n-th satellite is healthy, l_n = 1 indicates malfunction of this nth satellite [dimensionless].

Definition at line 58 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.9 d_lambda_n_A

```
double Glonass_Gnav_Almanac::d_lambda_n_A {}
```

Longitude of the first (within the d_n_A day) ascending node of d_n_A [radians].

Definition at line 47 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.10 d_M_n_A

```
double Glonass_Gnav_Almanac::d_M_n_A {}
```

Type of satellite n_A [dimensionless].

Definition at line 54 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.11 d_n_A

```
double Glonass_Gnav_Almanac::d_n_A {}
```

Conventional number of satellite within GLONASS space segment [dimensionless].

Definition at line 45 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.12 d_omega_n_A

```
double Glonass_Gnav_Almanac::d_omega_n_A {}
```

Argument of perigee of d_n_A satellite at instant t_lambda_n_A [radians].

Definition at line 53 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.13 d_t_lambda_n_A

```
double Glonass_Gnav_Almanac::d_t_lambda_n_A {}
```

Time of first ascending node passage [s].

Definition at line 48 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.14 d_tau_n_A

```
double Glonass_Gnav_Almanac::d_tau_n_A {}
```

Coarse value of d_n_A satellite time correction to GLONASS time at instant t_lambda_n_A[s].

Definition at line 56 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.15 i_satellite_freq_channel

```
int32_t Glonass_Gnav_Almanac::i_satellite_freq_channel {}
```

SV Frequency [Channel](#) Number.

Definition at line 61 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.16 i_satellite_slot_number

```
uint32_t Glonass_Gnav_Almanac::i_satellite_slot_number {}
```

SV Slot Number.

Definition at line 63 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

12.161.4.17 PRN

```
uint32_t Glonass_Gnav_Almanac::PRN {}
```

SV PRN Number, equivalent to slot number for compatibility with GPS.

Definition at line 62 of file [glonass_gnav_almanac.h](#).

Referenced by [serialize\(\)](#).

The documentation for this class was generated from the following file:

- [glonass_gnav_almanac.h](#)

12.162 Glonass_Gnav_Ephemeris Class Reference

This class is a storage and orbital model functions for the GLONASS SV ephemeris data as described in GLONASS ICD (Edition 5.1)

```
#include <glonass_gnav_ephemeris.h>
```

Public Member Functions

- [Glonass_Gnav_Ephemeris](#) ()=default
- double [sv_clock_drift](#) (double transmitTime, double timeCorrUTC)
Sets (d_satCikDrift) and returns the clock drift in seconds according to the User Algorithm for SV Clock Correction.
- boost::posix_time::ptime [compute_GLONASS_time](#) (double offset_time) const
Computes the GLONASS System Time and returns a boost::posix_time::ptime object \ param offset_time Is the start of day offset to compute the time.
- boost::posix_time::ptime [glot_to_utc](#) (double offset_time, double glot2utc_corr) const
Converts from GLONASST to UTC.
- void [glot_to_gpst](#) (double tod_offset, double glot2utc_corr, double glot2gpst_corr, int32_t *WN, double *TOW) const
Converts from GLONASST to GPST.
- template<class Archive>
void [serialize](#) (Archive &archive, const uint32_t version)
Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Public Attributes

- double [d_m](#) {}
String number within frame [dimensionless].
- double [d_t_k](#) {}
GLONASS Time (UTC(SU) + 3 h) referenced to the beginning of the frame within the current day [s].
- double [d_t_b](#) {}
Reference ephemeris relative time in GLONASS Time (UTC(SU) + 3 h). Index of a time interval within current day according to UTC(SU) + 03 hours 00 min. [s].

- double [d_M](#) {}
Type of satellite transmitting navigation signal [dimensionless].
- double [d_gamma_n](#) {}
Relative deviation of predicted carrier frequency value of n- satellite from nominal value at the instant t_b [dimensionless].
- double [d_tau_n](#) {}
Correction to the nth satellite time (t_n) relative to GLONASS time (t_e),.
- double [d_Xn](#) {}
Earth-fixed coordinate x of the satellite in PZ-90.02 coordinate system [km].
- double [d_Yn](#) {}
Earth-fixed coordinate y of the satellite in PZ-90.02 coordinate system [km].
- double [d_Zn](#) {}
Earth-fixed coordinate z of the satellite in PZ-90.02 coordinate system [km].
- double [d_VXn](#) {}
Earth-fixed velocity coordinate x of the satellite in PZ-90.02 coordinate system [km/s].
- double [d_VYn](#) {}
Earth-fixed velocity coordinate y of the satellite in PZ-90.02 coordinate system [km/s].
- double [d_VZn](#) {}
Earth-fixed velocity coordinate z of the satellite in PZ-90.02 coordinate system [km/s].
- double [d_AXn](#) {}
Earth-fixed acceleration coordinate x of the satellite in PZ-90.02 coordinate system [km/s^2].
- double [d_AYn](#) {}
Earth-fixed acceleration coordinate y of the satellite in PZ-90.02 coordinate system [km/s^2].
- double [d_AZn](#) {}
Earth-fixed acceleration coordinate z of the satellite in PZ-90.02 coordinate system [km/s^2].
- double [d_B_n](#) {}
Health flag [dimensionless].
- double [d_P](#) {}
Technological parameter of control segment, indication the satellite operation mode in respect of time parameters [dimensionless].
- double [d_N_T](#) {}
Current date, calendar number of day within four-year interval starting from the 1-st of January in a leap year [days].
- double [d_F_T](#) {}
Parameter that provides the predicted satellite user range accuracy at time t_b [dimensionless].
- double [d_n](#) {}
Index of the satellite transmitting given navigation signal. It corresponds to a slot number within GLONASS constellation.
- double [d_Delta_tau_n](#) {}
Time difference between navigation RF signal transmitted in L2 sub- band and aviation RF signal transmitted in L1 sub-band by nth satellite. [dimensionless].
- double [d_E_n](#) {}
Characterises "age" of a current information [days].
- double [d_P_1](#) {}
Flag of the immediate data updating [minutes].
- bool [d_P_2](#) {}
Flag of oddness ("1") or evenness ("0") of the value of (t_b) [dimensionless].
- bool [d_P_3](#) {}
Flag indicating a number of satellites for which almanac is transmitted within given frame: "1" corresponds to 5 satellites and "0" corresponds to 4 satellites [dimensionless].
- bool [d_P_4](#) {}
Flag to show that ephemeris parameters are present. "1" indicates that updated ephemeris or frequency/time parameters have been uploaded by the control segment [dimensionless].

- bool [d_l3rd_n](#) {}
Health flag for nth satellite; In = 0 indicates the n-th satellite is healthy, In = 1 indicates malfunction of this nth satellite [dimensionless].
- bool [d_l5th_n](#) {}
Health flag for nth satellite; In = 0 indicates the n-th satellite is healthy, In = 1 indicates malfunction of this nth satellite [dimensionless].
- int32_t [i_satellite_freq_channel](#) {}
SV Frequency [Channel](#) Number.
- uint32_t [PRN](#) {}
SV PRN Number, equivalent to slot number for compatibility with GPS.
- uint32_t [i_satellite_slot_number](#) {}
SV Slot Number.
- double [d_yr](#) = 1972.0
Current year.
- double [d_satClkDrift](#) {}
GLONASS clock error.
- double [d_dtr](#) {}
relativistic clock correction term
- double [d_iode](#) {}
Issue of data, ephemeris (Bit 0-6 of tb)
- double [d_tau_c](#) {}
GLONASS 2 UTC correction (todo) may be eliminated.
- double [d_TOW](#) {}
GLONASS IN GPST seconds of week.
- int32_t [d_WN](#) {}
GLONASS IN GPST week number of the start of frame.
- double [d_tod](#) {}
Time of Day since ephemeris where decoded.

12.162.1 Detailed Description

This class is a storage and orbital model functions for the GLONASS SV ephemeris data as described in GLONASS ICD (Edition 5.1)

Note

Code added as part of GSoC 2017 program

See also

[GLONASS ICD](#)

Definition at line 40 of file [glonass_gnav_ephemeris.h](#).

12.162.2 Constructor & Destructor Documentation

12.162.2.1 Glonass_Gnav_Ephemeris()

```
Glonass_Gnav_Ephemeris::Glonass_Gnav_Ephemeris () [default]
```

Default constructor

12.162.3 Member Function Documentation

12.162.3.1 compute_GLONASS_time()

```
boost::posix_time::ptime Glonass_Gnav_Ephemeris::compute_GLONASS_time (
    double offset_time) const
```

Computes the GLONASS System Time and returns a boost::posix_time::ptime object \ param offset_time Is the start of day offset to compute the time.

12.162.3.2 glot_to_gpst()

```
void Glonass_Gnav_Ephemeris::glot_to_gpst (
    double tod_offset,
    double glot2utc_corr,
    double glot2gpst_corr,
    int32_t * WN,
    double * TOW) const
```

Converts from GLONASST to GPST.

Converts from GLONASST to GPST in time of week (TOW) and week number (WN) format

Parameters

in	<i>tod_offset</i>	Is the start of day offset
in	<i>glot2utc_corr</i>	Correction from GLONASST to UTC
in	<i>glot2gpst_corr</i>	Correction from GLONASST to GPST
out	<i>WN</i>	Week Number, not in mod(1024) format
out	<i>TOW</i>	Time of Week in seconds of week

12.162.3.3 glot_to_utc()

```
boost::posix_time::ptime Glonass_Gnav_Ephemeris::glot_to_utc (
    double offset_time,
    double glot2utc_corr) const
```

Converts from GLONASST to UTC.

The function simply adjust for the 6 hrs offset between GLONASST and UTC

Parameters

in	<i>offset_time</i>	Is the start of day offset
in	<i>glot2utc_corr</i>	Correction from GLONASST to UTC

Returns

UTC time as a boost::posix_time::ptime object

12.162.3.4 serialize()

```
template<class Archive>
void Glonass_Gnav_Ephemeris::serialize (
    Archive & archive,
    const uint32_t version) [inline]
```

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

- < SV PRN frequency channel number
- < String number within frame [dimensionless]
- < Time referenced to the beginning of the frame within the current day [hours, minutes, seconds]
- < Index of a time interval within current day according to UTC(SU) + 03 hours 00 min. [minutes]
- < Type of satellite transmitting navigation signal [dimensionless]
- < Relative deviation of predicted carrier frequency value of n- satellite from nominal value at the instant tb [dimensionless]
- < Correction to the nth satellite time (tn) relative to GLONASS time (te)
- < Earth-fixed coordinate x of the satellite in PZ-90.02 coordinate system [km].
- < Earth-fixed coordinate y of the satellite in PZ-90.02 coordinate system [km]
- < Earth-fixed coordinate z of the satellite in PZ-90.02 coordinate system [km]
- < Earth-fixed velocity coordinate x of the satellite in PZ-90.02 coordinate system [km/s]

- < Earth-fixed velocity coordinate y of the satellite in PZ-90.02 coordinate system [km/s]
- < Earth-fixed velocity coordinate z of the satellite in PZ-90.02 coordinate system [km/s]
- < Earth-fixed acceleration coordinate x of the satellite in PZ-90.02 coordinate system [km/s²]
- < Earth-fixed acceleration coordinate y of the satellite in PZ-90.02 coordinate system [km/s²]
- < Earth-fixed acceleration coordinate z of the satellite in PZ-90.02 coordinate system [km/s²]
- < Health flag [dimensionless]
- < Technological parameter of control segment, indication the satellite operation mode in respect of time parameters [dimensionless]
- < Current date, calendar number of day within four-year interval starting from the 1-st of January in a leap year [days]
- < Parameter that provides the predicted satellite user range accuracy at time tb [dimensionless]
- < Index of the satellite transmitting given navigation signal. It corresponds to a slot number within GLONASS constellation
- < Time difference between navigation RF signal transmitted in L2 sub- band and aviation RF signal transmitted in L1 sub-band by nth satellite. [dimensionless]
- < Characterises "age" of a current information [days]
- < Flag of the immediate data updating.
- < Flag of oddness ("1") or evenness ("0") of the value of (tb) [dimensionless]
- < Flag indicating a number of satellites for which almanac is transmitted within given frame: "1" corresponds to 5 satellites and "0" corresponds to 4 satellites [dimensionless]
- < Flag to show that ephemeris parameters are present. "1" indicates that updated ephemeris or frequency/time parameters have been uploaded by the control segment [dimensionless]
- < Health flag for nth satellite; In = 0 indicates the n-th satellite is helthy, In = 1 indicates malfunction of this nth satellite [dimensionless]
- < Health flag for nth satellite; In = 0 indicates the n-th satellite is helthy, In = 1 indicates malfunction of this nth satellite [dimensionless]

Definition at line 128 of file [glonass_gnav_ephemeris.h](#).

References [d_AXn](#), [d_AYn](#), [d_AZn](#), [d_B_n](#), [d_Delta_tau_n](#), [d_E_n](#), [d_F_T](#), [d_gamma_n](#), [d_l3rd_n](#), [d_l5th_n](#), [d_M](#), [d_m](#), [d_n](#), [d_N_T](#), [d_P](#), [d_P_1](#), [d_P_2](#), [d_P_3](#), [d_P_4](#), [d_t_b](#), [d_t_k](#), [d_tau_n](#), [d_VXn](#), [d_VYn](#), [d_VZn](#), [d_Xn](#), [d_Yn](#), [d_Zn](#), [i_satellite_freq_channel](#), [i_satellite_slot_number](#), and [PRN](#).

12.162.3.5 sv_clock_drift()

```
double Glonass_Gnav_Ephemeris::sv_clock_drift (
    double transmitTime,
    double timeCorrUTC)
```

Sets (*d_satClkDrift*) and returns the clock drift in seconds according to the User Algorithm for SV Clock Correction.

12.162.4 Member Data Documentation

12.162.4.1 d_AXn

```
double Glonass_Gnav_Ephemeris::d_AXn {}
```

Earth-fixed acceleration coordinate x of the satellite in PZ-90.02 coordinate system [km/s²].

Definition at line 60 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.2 d_AYn

```
double Glonass_Gnav_Ephemeris::d_AYn {}
```

Earth-fixed acceleration coordinate y of the satellite in PZ-90.02 coordinate system [km/s²].

Definition at line 61 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.3 d_AZn

```
double Glonass_Gnav_Ephemeris::d_AZn {}
```

Earth-fixed acceleration coordinate z of the satellite in PZ-90.02 coordinate system [km/s²].

Definition at line 62 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.4 d_B_n

```
double Glonass_Gnav_Ephemeris::d_B_n {}
```

Health flag [dimensionless].

Definition at line 63 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.5 d_Delta_tau_n

```
double Glonass_Gnav_Ephemeris::d_Delta_tau_n {}
```

Time difference between navigation RF signal transmitted in L2 sub- band and aviation RF signal transmitted in L1 sub-band by nth satellite. [dimensionless].

Definition at line 68 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.6 d_dtr

```
double Glonass_Gnav_Ephemeris::d_dtr {}
```

relativistic clock correction term

Definition at line 84 of file [glonass_gnav_ephemeris.h](#).

12.162.4.7 d_E_n

```
double Glonass_Gnav_Ephemeris::d_E_n {}
```

Characterises "age" of a current information [days].

Definition at line 69 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.8 d_F_T

```
double Glonass_Gnav_Ephemeris::d_F_T {}
```

Parameter that provides the predicted satellite user range accuracy at time tb [dimensionless].

Definition at line 66 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.9 d_gamma_n

```
double Glonass_Gnav_Ephemeris::d_gamma_n {}
```

Relative deviation of predicted carrier frequency value of n- satellite from nominal value at the instant tb [dimensionless].

Definition at line 52 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.10 d_iode

```
double Glonass_Gnav_Ephemeris::d_iode {}
```

Issue of data, ephemeris (Bit 0-6 of tb)

Definition at line 85 of file [glonass_gnav_ephemeris.h](#).

12.162.4.11 d_l3rd_n

```
bool Glonass_Gnav_Ephemeris::d_l3rd_n {}
```

Health flag for nth satellite; ln = 0 indicates the n-th satellite is healthy, ln = 1 indicates malfunction of this nth satellite [dimensionless].

Definition at line 74 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.12 d_l5th_n

```
bool Glonass_Gnav_Ephemeris::d_l5th_n {}
```

Health flag for nth satellite; ln = 0 indicates the n-th satellite is healthy, ln = 1 indicates malfunction of this nth satellite [dimensionless].

Definition at line 75 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.13 d_M

```
double Glonass_Gnav_Ephemeris::d_M {}
```

Type of satellite transmitting navigation signal [dimensionless].

Definition at line 51 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.14 d_m

```
double Glonass_Gnav_Ephemeris::d_m {}
```

String number within frame [dimensionless].

Definition at line 48 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.15 d_n

```
double Glonass_Gnav_Ephemeris::d_n {}
```

Index of the satellite transmitting given navigation signal. It corresponds to a slot number within GLONASS constellation.

Definition at line 67 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.16 d_N_T

```
double Glonass_Gnav_Ephemeris::d_N_T {}
```

Current date, calendar number of day within four-year interval starting from the 1-st of January in a leap year [days].

Definition at line 65 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.17 d_P

```
double Glonass_Gnav_Ephemeris::d_P {}
```

Technological parameter of control segment, indication the satellite operation mode in respect of time parameters [dimensionless].

Definition at line 64 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.18 d_P_1

```
double Glonass_Gnav_Ephemeris::d_P_1 {}
```

Flag of the immediate data updating [minutes].

Definition at line 70 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.19 d_P_2

```
bool Glonass_Gnav_Ephemeris::d_P_2 {}
```

Flag of oddness ("1") or evenness ("0") of the value of (tb) [dimensionless].

Definition at line 71 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.20 d_P_3

```
bool Glonass_Gnav_Ephemeris::d_P_3 {}
```

Flag indicating a number of satellites for which almanac is transmitted within given frame: "1" corresponds to 5 satellites and "0" corresponds to 4 satellites [dimensionless].

Definition at line 72 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.21 d_P_4

```
bool Glonass_Gnav_Ephemeris::d_P_4 {}
```

Flag to show that ephemeris parameters are present. "1" indicates that updated ephemeris or frequency/time parameters have been uploaded by the control segment [dimensionless].

Definition at line 73 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.22 d_satClkDrift

```
double Glonass_Gnav_Ephemeris::d_satClkDrift {}
```

GLONASS clock error.

Definition at line 83 of file [glonass_gnav_ephemeris.h](#).

12.162.4.23 d_t_b

```
double Glonass_Gnav_Ephemeris::d_t_b {}
```

Reference ephemeris relative time in GLONASS Time (UTC(SU) + 3 h). Index of a time interval within current day according to UTC(SU) + 03 hours 00 min. [s].

Definition at line 50 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.24 d_t_k

```
double Glonass_Gnav_Ephemeris::d_t_k {}
```

GLONASS Time (UTC(SU) + 3 h) referenced to the beginning of the frame within the current day [s].

Definition at line 49 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.25 d_tau_c

```
double Glonass_Gnav_Ephemeris::d_tau_c {}
```

GLONASST 2 UTC correction (todo) may be eliminated.

Definition at line 86 of file [glonass_gnav_ephemeris.h](#).

12.162.4.26 d_tau_n

```
double Glonass_Gnav_Ephemeris::d_tau_n {}
```

Correction to the nth satellite time (tn) relative to GLONASS time (te),.

Definition at line 53 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.27 d_tod

```
double Glonass_Gnav_Ephemeris::d_tod {}
```

Time of Day since ephemeris where decoded.

Definition at line 89 of file [glonass_gnav_ephemeris.h](#).

12.162.4.28 d_TOW

```
double Glonass_Gnav_Ephemeris::d_TOW {}
```

GLONASST IN GPST seconds of week.

Definition at line 87 of file [glonass_gnav_ephemeris.h](#).

12.162.4.29 d_VXn

```
double Glonass_Gnav_Ephemeris::d_VXn {}
```

Earth-fixed velocity coordinate x of the satellite in PZ-90.02 coordinate system [km/s].

Definition at line 57 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.30 d_VYn

```
double Glonass_Gnav_Ephemeris::d_VYn {}
```

Earth-fixed velocity coordinate y of the satellite in PZ-90.02 coordinate system [km/s].

Definition at line 58 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.31 d_VZn

```
double Glonass_Gnav_Ephemeris::d_VZn {}
```

Earth-fixed velocity coordinate z of the satellite in PZ-90.02 coordinate system [km/s].

Definition at line 59 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.32 d_WN

```
int32_t Glonass_Gnav_Ephemeris::d_WN {}
```

GLONASST IN GPST week number of the start of frame.

Definition at line 88 of file [glonass_gnav_ephemeris.h](#).

12.162.4.33 d_Xn

```
double Glonass_Gnav_Ephemeris::d_Xn {}
```

Earth-fixed coordinate x of the satellite in PZ-90.02 coordinate system [km].

Definition at line 54 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.34 d_Yn

```
double Glonass_Gnav_Ephemeris::d_Yn {}
```

Earth-fixed coordinate y of the satellite in PZ-90.02 coordinate system [km].

Definition at line 55 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.35 d_yr

```
double Glonass_Gnav_Ephemeris::d_yr = 1972.0
```

Current year.

Definition at line 82 of file [glonass_gnav_ephemeris.h](#).

12.162.4.36 d_Zn

```
double Glonass_Gnav_Ephemeris::d_Zn {}
```

Earth-fixed coordinate z of the satellite in PZ-90.02 coordinate system [km].

Definition at line 56 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.37 i_satellite_freq_channel

`int32_t Glonass_Gnav_Ephemeris::i_satellite_freq_channel {}`

SV Frequency Channel Number.

Definition at line 79 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.38 i_satellite_slot_number

`uint32_t Glonass_Gnav_Ephemeris::i_satellite_slot_number {}`

SV Slot Number.

Definition at line 81 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.162.4.39 PRN

`uint32_t Glonass_Gnav_Ephemeris::PRN {}`

SV PRN Number, equivalent to slot number for compatibility with GPS.

Definition at line 80 of file [glonass_gnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

The documentation for this class was generated from the following file:

- [glonass_gnav_ephemeris.h](#)

12.163 Glonass_Gnav_Navigation_Message Class Reference

This class decodes a GLONASS GNAV Data message as described in GLONASS ICD (Edition 5.1)

```
#include <glonass_gnav_navigation_message.h>
```

Public Member Functions

- [Glonass_Gnav_Navigation_Message](#) ()=default
- `bool CRC_test (std::bitset< GLONASS_GNAV_STRING_BITS > &bits) const`
Compute CRC for GLONASS GNAV strings.
- `uint32_t get_frame_number (uint32_t satellite_slot_number)`
Computes the frame number being decoded given the satellite slot number.
- [Glonass_Gnav_Ephemeris get_ephemeris](#) () const
Obtain a GLONASS GNAV SV Ephemeris class filled with current SV data.
- [Glonass_Gnav_Utc_Model get_utc_model](#) () const
Obtain a GLONASS GNAV UTC model parameters class filled with current SV data.
- [Glonass_Gnav_Almanac get_almanac](#) (uint32_t satellite_slot_number) const
Returns a [Glonass_Gnav_Almanac](#) object filled with the latest navigation data received.
- `bool have_new_ephemeris ()`
Returns true if a new [Glonass_Gnav_Ephemeris](#) object has arrived.
- `bool have_new_utc_model ()`
Returns true if new [Glonass_Gnav_Utc_Model](#) object has arrived.
- `bool have_new_almanac ()`
Returns true if new [Glonass_Gnav_Almanac](#) object has arrived.
- `int32_t string_decoder (const std::string &frame_string)`
Decodes the GLONASS GNAV string.
- `bool get_flag_CRC_test` () const
- `void set_rf_link` (int32_t rf_link)
- `uint32_t get_alm_satellite_slot_number` () const
- `bool get_flag_update_slot_number` () const
- `void set_flag_update_slot_number` (bool flag_slot)
- `bool get_flag_TOW_new` () const

- void [set_flag_TOW_new](#) (bool tow_new)
- bool [is_flag_TOW_set](#) () const
- void [set_flag_ephemeris_str_1](#) (bool ephemeris_str_1)
- void [set_flag_ephemeris_str_2](#) (bool ephemeris_str_2)
- void [set_flag_ephemeris_str_3](#) (bool ephemeris_str_3)
- void [set_flag_ephemeris_str_4](#) (bool ephemeris_str_4)

12.163.1 Detailed Description

This class decodes a GLONASS GNAV Data message as described in GLONASS ICD (Edition 5.1)

Note

Code added as part of GSoC 2017 program

See also

[GLONASS ICD](#)

Definition at line 45 of file [glonass_gnav_navigation_message.h](#).

12.163.2 Constructor & Destructor Documentation

12.163.2.1 Glonass_Gnav_Navigation_Message()

```
Glonass_Gnav_Navigation_Message::Glonass_Gnav_Navigation_Message () [default]
```

Default constructor

12.163.3 Member Function Documentation

12.163.3.1 CRC_test()

```
bool Glonass_Gnav_Navigation_Message::CRC_test (
    std::bitset< GLONASS\_GNAV\_STRING\_BITS > & bits) const
```

Compute CRC for GLONASS GNAV strings.

Parameters

<i>bits</i>	Bits of the string message where to compute CRC
-------------	---

12.163.3.2 get_alm_satellite_slot_number()

```
uint32_t Glonass_Gnav_Navigation_Message::get_alm_satellite_slot_number () const [inline]
```

Definition at line 121 of file [glonass_gnav_navigation_message.h](#).

12.163.3.3 get_almanac()

```
Glonass\_Gnav\_Almanac Glonass_Gnav_Navigation_Message::get_almanac (
    uint32_t satellite_slot_number) const
```

Returns a [Glonass_Gnav_Almanac](#) object filled with the latest navigation data received.

Parameters

<i>satellite_slot_number</i>	Slot number identifier for the satellite
------------------------------	--

Returns

Returns the [Glonass_Gnav_Almanac](#) object for the input slot number

12.163.3.4 get_ephemeris()

[Glonass_Gnav_Ephemeris](#) `Glonass_Gnav_Navigation_Message::get_ephemeris () const [inline]`

Obtain a GLONASS GNAV SV Ephemeris class filled with current SV data.

Definition at line 69 of file [glonass_gnav_navigation_message.h](#).

12.163.3.5 get_flag_CRC_test()

`bool Glonass_Gnav_Navigation_Message::get_flag_CRC_test () const [inline]`

Definition at line 111 of file [glonass_gnav_navigation_message.h](#).

12.163.3.6 get_flag_TOW_new()

`bool Glonass_Gnav_Navigation_Message::get_flag_TOW_new () const [inline]`

Definition at line 136 of file [glonass_gnav_navigation_message.h](#).

12.163.3.7 get_flag_update_slot_number()

`bool Glonass_Gnav_Navigation_Message::get_flag_update_slot_number () const [inline]`

Definition at line 126 of file [glonass_gnav_navigation_message.h](#).

12.163.3.8 get_frame_number()

`uint32_t Glonass_Gnav_Navigation_Message::get_frame_number (`
 `uint32_t satellite_slot_number)`

Computes the frame number being decoded given the satellite slot number.

Parameters

<i>satellite_slot_number</i>	[in] Satellite slot number identifier
------------------------------	---------------------------------------

Returns

Frame number being decoded, 0 if operation was not successful.

12.163.3.9 get_utc_model()

[Glonass_Gnav_Utc_Model](#) `Glonass_Gnav_Navigation_Message::get_utc_model () const [inline]`

Obtain a GLONASS GNAV UTC model parameters class filled with current SV data.

Definition at line 77 of file [glonass_gnav_navigation_message.h](#).

12.163.3.10 have_new_almanac()

`bool Glonass_Gnav_Navigation_Message::have_new_almanac ()`

Returns true if new [Glonass_Gnav_Almanac](#) object has arrived.

12.163.3.11 have_new_ephemeris()

`bool Glonass_Gnav_Navigation_Message::have_new_ephemeris ()`

Returns true if a new [Glonass_Gnav_Ephemeris](#) object has arrived.

12.163.3.12 have_new_utc_model()

`bool Glonass_Gnav_Navigation_Message::have_new_utc_model ()`

Returns true if new [Glonass_Gnav_Utc_Model](#) object has arrived.

12.163.3.13 is_flag_TOW_set()

`bool Glonass_Gnav_Navigation_Message::is_flag_TOW_set () const [inline]`

Definition at line 146 of file [glonass_gnav_navigation_message.h](#).

12.163.3.14 set_flag_ephemeris_str_1()

```
void Glonass_Gnav_Navigation_Message::set_flag_ephemeris_str_1 (
    bool ephemeris_str_1) [inline]
```

Definition at line 151 of file [glonass_gnav_navigation_message.h](#).

12.163.3.15 set_flag_ephemeris_str_2()

```
void Glonass_Gnav_Navigation_Message::set_flag_ephemeris_str_2 (
    bool ephemeris_str_2) [inline]
```

Definition at line 156 of file [glonass_gnav_navigation_message.h](#).

12.163.3.16 set_flag_ephemeris_str_3()

```
void Glonass_Gnav_Navigation_Message::set_flag_ephemeris_str_3 (
    bool ephemeris_str_3) [inline]
```

Definition at line 161 of file [glonass_gnav_navigation_message.h](#).

12.163.3.17 set_flag_ephemeris_str_4()

```
void Glonass_Gnav_Navigation_Message::set_flag_ephemeris_str_4 (
    bool ephemeris_str_4) [inline]
```

Definition at line 166 of file [glonass_gnav_navigation_message.h](#).

12.163.3.18 set_flag_TOW_new()

```
void Glonass_Gnav_Navigation_Message::set_flag_TOW_new (
    bool tow_new) [inline]
```

Definition at line 141 of file [glonass_gnav_navigation_message.h](#).

12.163.3.19 set_flag_update_slot_number()

```
void Glonass_Gnav_Navigation_Message::set_flag_update_slot_number (
    bool flag_slot) [inline]
```

Definition at line 131 of file [glonass_gnav_navigation_message.h](#).

12.163.3.20 set_rf_link()

```
void Glonass_Gnav_Navigation_Message::set_rf_link (
    int32_t rf_link) [inline]
```

Definition at line 116 of file [glonass_gnav_navigation_message.h](#).

12.163.3.21 string_decoder()

```
int32_t Glonass_Gnav_Navigation_Message::string_decoder (
    const std::string & frame_string)
```

Decodes the GLONASS GNAV string.

Parameters

<i>frame_string</i>	[in] is the string message within the parsed frame
---------------------	--

Returns

Returns the ID of the decoded string

The documentation for this class was generated from the following file:

- [glonass_gnav_navigation_message.h](#)

12.164 Glonass_Gnav_Utc_Model Class Reference

This class is a storage for the GLONASS GNAV UTC MODEL data as described in GLONASS ICD (Edition 5.1)

```
#include <glonass_gnav_utc_model.h>
```

Public Member Functions

- [Glonass_Gnav_Utc_Model](#) ()=default
- double [utc_time](#) (double glonass_time_corrected) const
Computes the Coordinated Universal Time (UTC) and returns it in [s] (GLONASS ICD (Edition 5.1) Section 3.3.3 GLONASS Time)
- template<class Archive>
void [serialize](#) (Archive &archive, const uint32_t version)
Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the almanac data on disk file.

Public Attributes

- bool [valid](#) {}
- double [d_tau_c](#) {}
GLONASS time scale correction to UTC(SU) time. [s].
- double [d_tau_gps](#) {}
Correction to GPS time to GLONASS time [day].
- double [d_N_4](#) {}
Four year interval number starting from 1996 [4 year interval].
- double [d_N_A](#) {}
Calendar day number within the four-year period beginning since the leap year for Almanac data [days].
- double [d_B1](#) {}
Coefficient to determine DeltaUT1 [s].
- double [d_B2](#) {}
Coefficient to determine DeltaUT1 [s/msd].

12.164.1 Detailed Description

This class is a storage for the GLONASS GNAV UTC MODEL data as described in GLONASS ICD (Edition 5.1)

Note

Code added as part of GSoC 2017 program

See also

[GLONASS ICD](#)

Definition at line 37 of file [glonass_gnav_utc_model.h](#).

12.164.2 Constructor & Destructor Documentation

12.164.2.1 Glonass_Gnav_Utc_Model()

```
Glonass_Gnav_Utc_Model::Glonass_Gnav_Utc_Model () [default]
```

Default constructor

12.164.3 Member Function Documentation

12.164.3.1 `serialize()`

```
template<class Archive>
void Glonass_Gnav_Utc_Model::serialize (
    Archive & archive,
    const uint32_t version) [inline]
```

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the almanac data on disk file.

Definition at line 65 of file [glonass_gnav_utc_model.h](#).

References [d_B1](#), [d_B2](#), [d_N_4](#), [d_N_A](#), [d_tau_c](#), and [d_tau_gps](#).

12.164.3.2 `utc_time()`

```
double Glonass_Gnav_Utc_Model::utc_time (
    double glonass_time_corrected) const
```

Computes the Coordinated Universal Time (UTC) and returns it in [s] (GLONASS ICD (Edition 5.1) Section 3.3.3 GLONASS Time)

12.164.4 Member Data Documentation

12.164.4.1 `d_B1`

```
double Glonass_Gnav_Utc_Model::d_B1 {}
```

Coefficient to determine DeltaUT1 [s].

Definition at line 51 of file [glonass_gnav_utc_model.h](#).

Referenced by [serialize\(\)](#).

12.164.4.2 `d_B2`

```
double Glonass_Gnav_Utc_Model::d_B2 {}
```

Coefficient to determine DeltaUT1 [s/msd].

Definition at line 52 of file [glonass_gnav_utc_model.h](#).

Referenced by [serialize\(\)](#).

12.164.4.3 `d_N_4`

```
double Glonass_Gnav_Utc_Model::d_N_4 {}
```

Four year interval number starting from 1996 [4 year interval].

Definition at line 49 of file [glonass_gnav_utc_model.h](#).

Referenced by [serialize\(\)](#).

12.164.4.4 `d_N_A`

```
double Glonass_Gnav_Utc_Model::d_N_A {}
```

Calendar day number within the four-year period beginning since the leap year for Almanac data [days].

Definition at line 50 of file [glonass_gnav_utc_model.h](#).

Referenced by [serialize\(\)](#).

12.164.4.5 `d_tau_c`

```
double Glonass_Gnav_Utc_Model::d_tau_c {}
```

GLONASS time scale correction to UTC(SU) time. [s].

Definition at line 47 of file [glonass_gnav_utc_model.h](#).

Referenced by [serialize\(\)](#).

12.164.4.6 `d_tau_gps`

```
double Glonass_Gnav_Utc_Model::d_tau_gps {}
```

Correction to GPS time to GLONASS time [day].
 Definition at line 48 of file [glonass_gnav_utc_model.h](#).
 Referenced by [serialize\(\)](#).

12.164.4.7 valid

`bool Glonass_Gnav_Utc_Model::valid {}`
 Definition at line 45 of file [glonass_gnav_utc_model.h](#).
 The documentation for this class was generated from the following file:

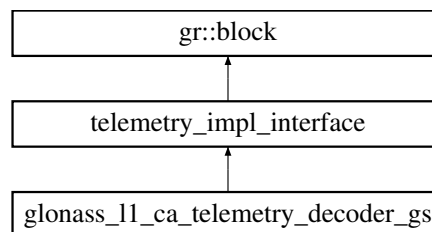
- [glonass_gnav_utc_model.h](#)

12.165 glonass_l1_ca_telemetry_decoder_gs Class Reference

This class implements a block that decodes the GNAV data defined in GLONASS ICD v5.1.

`#include <glonass_l1_ca_telemetry_decoder_gs.h>`

Inheritance diagram for `glonass_l1_ca_telemetry_decoder_gs`:



Public Member Functions

- `~glonass_l1_ca_telemetry_decoder_gs ()` override
Class destructor.
- `void set_satellite (const Gnss_Satellite &satellite)` override
Set satellite PRN.
- `void set_channel (int32_t channel)` override
Set receiver's channel.
- `void reset ()` override
- `int general_work (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)` override
This is where all signal processing takes place.

Public Member Functions inherited from [telemetry_impl_interface](#)

- `telemetry_impl_interface (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)`
- `virtual void set_channel (int channel)=0`

Friends

- `glonass_l1_ca_telemetry_decoder_gs_sptr glonass_l1_ca_make_telemetry_decoder_gs (const Gnss_Satellite &satellite, const TIm_Conf &conf)`

Additional Inherited Members

Protected Member Functions inherited from [telemetry_impl_interface](#)

- `void configure_basic_outputs ()`

- void **configure_dump_file** (int32_t channel, bool enable_dump, std::string &dump_filename, std::ofstream &dump_file) const
- void **configure_crc_stats_channel** (int32_t channel, bool &dump_crc_stats, std::unique_ptr< [Tlm_CRC_Stats](#) > &crc_stats) const

12.165.1 Detailed Description

This class implements a block that decodes the GNAV data defined in GLONASS ICD v5.1.

Note

Code added as part of GSoC 2017 program

See also

[GLONASS ICD](#)

Definition at line 52 of file [glonass_l1_ca_telemetry_decoder_gs.h](#).

12.165.2 Constructor & Destructor Documentation

12.165.2.1 ~glonass_l1_ca_telemetry_decoder_gs()

```
glonass_l1_ca_telemetry_decoder_gs::~glonass_l1_ca_telemetry_decoder_gs () [override]
Class destructor.
```

12.165.3 Member Function Documentation

12.165.3.1 general_work()

```
int glonass_l1_ca_telemetry_decoder_gs::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

This is where all signal processing takes place.

12.165.3.2 reset()

```
void glonass_l1_ca_telemetry_decoder_gs::reset () [inline], [override], [virtual]
```

Implements [telemetry_impl_interface](#).

Definition at line 58 of file [glonass_l1_ca_telemetry_decoder_gs.h](#).

12.165.3.3 set_channel()

```
void glonass_l1_ca_telemetry_decoder_gs::set_channel (
    int32_t channel) [override]
```

Set receiver's channel.

12.165.3.4 set_satellite()

```
void glonass_l1_ca_telemetry_decoder_gs::set_satellite (
    const Gnss\_Satellite & satellite) [override], [virtual]
```

Set satellite PRN.

Implements [telemetry_impl_interface](#).

The documentation for this class was generated from the following file:

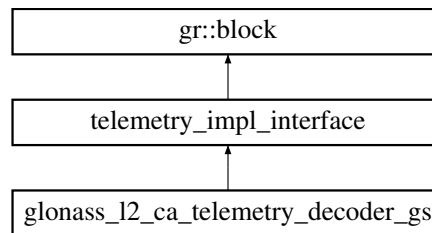
- [glonass_l1_ca_telemetry_decoder_gs.h](#)

12.166 glonass_l2_ca_telemetry_decoder_gs Class Reference

This class implements a block that decodes the GNAV data defined in GLONASS ICD v5.1.

```
#include <glonass_l2_ca_telemetry_decoder_gs.h>
```

Inheritance diagram for `glonass_l2_ca_telemetry_decoder_gs`:



Public Member Functions

- `~glonass_l2_ca_telemetry_decoder_gs` () override
Class destructor.
- void `set_satellite` (const `Gnss_Satellite` &satellite) override
Set satellite PRN.
- void `set_channel` (int32_t channel) override
Set receiver's channel.
- void `reset` () override
- int `general_work` (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
This is where all signal processing takes place.

Public Member Functions inherited from `telemetry_impl_interface`

- `telemetry_impl_interface` (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void `set_channel` (int channel)=0

Friends

- `glonass_l2_ca_telemetry_decoder_gs_sptr glonass_l2_ca_make_telemetry_decoder_gs` (const `Gnss_Satellite` &satellite, const `Tlm_Conf` &conf)

Additional Inherited Members

Protected Member Functions inherited from `telemetry_impl_interface`

- void `configure_basic_outputs` ()
- void `configure_dump_file` (int32_t channel, bool enable_dump, std::string &dump_filename, std::ofstream &dump_file) const
- void `configure_crc_stats_channel` (int32_t channel, bool &dump_crc_stats, std::unique_ptr< `Tlm_CRC_Stats` > &crc_stats) const

12.166.1 Detailed Description

This class implements a block that decodes the GNAV data defined in GLONASS ICD v5.1.

See also

[GLONASS ICD](#)

Definition at line 50 of file `glonass_l2_ca_telemetry_decoder_gs.h`.

12.166.2 Constructor & Destructor Documentation

12.166.2.1 ~glonass_l2_ca_telemetry_decoder_gs()

`glonass_l2_ca_telemetry_decoder_gs::~glonass_l2_ca_telemetry_decoder_gs () [override]`
 Class destructor.

12.166.3 Member Function Documentation

12.166.3.1 general_work()

```
int glonass_l2_ca_telemetry_decoder_gs::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

This is where all signal processing takes place.

12.166.3.2 reset()

```
void glonass_l2_ca_telemetry_decoder_gs::reset () [inline], [override], [virtual]
```

Implements [telemetry_impl_interface](#).

Definition at line 56 of file [glonass_l2_ca_telemetry_decoder_gs.h](#).

12.166.3.3 set_channel()

```
void glonass_l2_ca_telemetry_decoder_gs::set_channel (
    int32_t channel) [override]
```

Set receiver's channel.

12.166.3.4 set_satellite()

```
void glonass_l2_ca_telemetry_decoder_gs::set_satellite (
    const Gnss_Satellite & satellite) [override], [virtual]
```

Set satellite PRN.

Implements [telemetry_impl_interface](#).

The documentation for this class was generated from the following file:

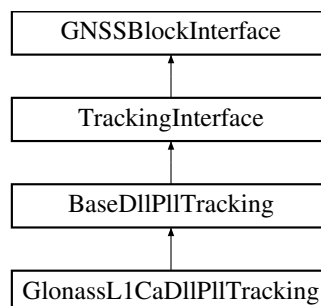
- [glonass_l2_ca_telemetry_decoder_gs.h](#)

12.167 GlonassL1CaDIIPIITracking Class Reference

This class implements a code DLL + carrier PLL tracking loop adapter for GLONASS L1 signals.

```
#include <glonass_l1_ca_dll_pll_tracking.h>
```

Inheritance diagram for GlonassL1CaDIIPIITracking:



Public Member Functions

- [GlonassL1CaDIIPITracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "GLONASS_L1_CA_DLL_PLL_Tracking".

Public Member Functions inherited from [BaseDIIPITracking](#)

- [BaseDIIPITracking](#) (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDIIPITracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override final
Get left block from the Tracking block adapter.
- gr::basic_block_sptr [get_right_block](#) () override final
Get right block from the Tracking block adapter.
- void [set_channel](#) (unsigned int channel) override final
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final
Start the Tracking block.
- void [stop_tracking](#) () override final
Stop the Tracking block.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BaseDIIPITracking](#)

- [DIIPITrackingConf](#) & [config_params](#) ()
- const [DIIPITrackingConf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t item_size)

Protected Attributes inherited from [BaseDIIPITracking](#)

- dll_pll_veml_tracking_sptr [tracking_sptr_](#)

12.167.1 Detailed Description

This class implements a code DLL + carrier PLL tracking loop block adapter for GLONASS L1 signals.
Definition at line 44 of file [glonass_l1_ca_dll_pll_tracking.h](#).

12.167.2 Constructor & Destructor Documentation

12.167.2.1 GlonassL1CaDllPllTracking()

```
GlonassL1CaDllPllTracking::GlonassL1CaDllPllTracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDllPllTracking::role\(\)](#).

12.167.3 Member Function Documentation

12.167.3.1 implementation()

```
std::string GlonassL1CaDllPllTracking::implementation () [inline], [override], [virtual]
```

Returns "GLONASS_L1_CA_DLL_PLL_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 54 of file [glonass_l1_ca_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

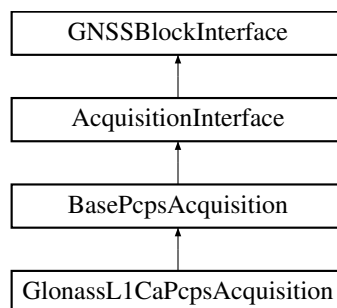
- [glonass_l1_ca_dll_pll_tracking.h](#)

12.168 GlonassL1CaPcpsAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

```
#include <glonass_l1_ca_pcps_acquisition.h>
```

Inheritance diagram for GlonassL1CaPcpsAcquisition:



Public Member Functions

- **GlonassL1CaPcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GLONASS_L1_CA_PCPS_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)

- `std::string role ()` override
- `size_t item_size ()` override
- `void connect (gr::top_block_sptr top_block)` override
- `void disconnect (gr::top_block_sptr top_block)` override
- `gr::basic_block_sptr get_left_block ()` override
- `gr::basic_block_sptr get_right_block ()` override
- `void set_gnss_synchro (Gnss_Synchro *p_gnss_synchro)` override
Set acquisition/tracking common Gnss_Synchro object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- `void set_channel (unsigned int channel)` override
Set acquisition channel unique ID.
- `void set_channel_fsm (std::weak_ptr< ChannelFsm > channel_fsm)` override
Set channel fsm associated to this acquisition instance.
- `void set_doppler_center (int doppler_center)` override
Set Doppler center for the grid search.
- `signed int mag ()` override
Returns the maximum peak of grid search.
- `void reset ()` override
Restart acquisition algorithm.
- `void stop_acquisition ()` override
Stop running acquisition.
- `void set_resampler_latency (uint32_t latency_samples)` override
Sets the resampler latency to account it in the acquisition code delay estimation.
- `void set_local_code ()` override
Sets local code.

Public Member Functions inherited from GNSSBlockInterface

- virtual `gr::basic_block_sptr get_left_block (int RF_channel)`
- virtual `gr::basic_block_sptr get_right_block (int RF_channel)`
- virtual `void start ()`
Start the flow of samples if needed.

12.168.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.
 Definition at line 34 of file [glonass_l1_ca_pcps_acquisition.h](#).

12.168.2 Member Function Documentation

12.168.2.1 implementation()

```
std::string GlonassL1CaPcpsAcquisition::implementation () [inline], [override], [virtual]
```

Returns "GLONASS_L1_CA_PCPS_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [glonass_l1_ca_pcps_acquisition.h](#).

The documentation for this class was generated from the following file:

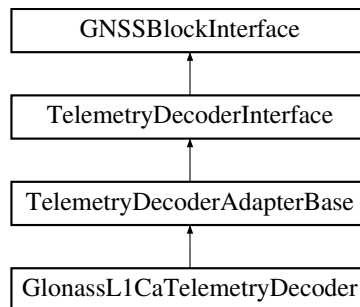
- [glonass_l1_ca_pcps_acquisition.h](#)

12.169 GlonassL1CaTelemetryDecoder Class Reference

This class implements a NAV data decoder for GLONASS L1 C/A.

```
#include <glonass_l1_ca_telemetry_decoder.h>
```

Inheritance diagram for GlonassL1CaTelemetryDecoder:



Public Member Functions

- **GlonassL1CaTelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GLONASS_L1_CA_Telemetry_Decoder".

Public Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- void **InitializeDecoder** (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & **satellite** () const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- [Tlm_Conf](#) tlm_parameters_

12.169.1 Detailed Description

This class implements a NAV data decoder for GLONASS L1 C/A.
Definition at line 35 of file [glonass_l1_ca_telemetry_decoder.h](#).

12.169.2 Member Function Documentation

12.169.2.1 implementation()

```
std::string GlonassL1CaTelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "GLONASS_L1_CA_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 45 of file [glonass_l1_ca_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

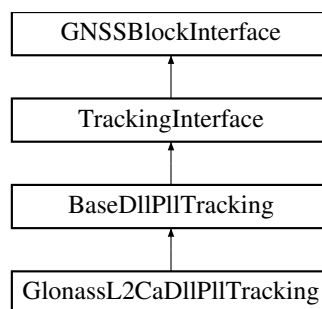
- [glonass_l1_ca_telemetry_decoder.h](#)

12.170 GlonassL2CaDllPllTracking Class Reference

This class implements a code DLL + carrier PLL tracking loop block adapter for GLONASS L2 signals.

```
#include <glonass_l2_ca_dll_pll_tracking.h>
```

Inheritance diagram for GlonassL2CaDllPllTracking:



Public Member Functions

- [GlonassL2CaDllPllTracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "GLONASS_L2_CA_DLL_PLL_Tracking".

Public Member Functions inherited from [BaseDllPllTracking](#)

- [BaseDllPllTracking](#) (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDllPllTracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final

Disconnect the sTracking block adapter.

- gr::basic_block_sptr [get_left_block](#) () override final
Get left block from the Tracking block adapter.
- gr::basic_block_sptr [get_right_block](#) () override final
Get right block from the Tracking block adapter.
- void [set_channel](#) (unsigned int channel) override final
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final
Start the Tracking block.
- void [stop_tracking](#) () override final
Stop the Tracking block.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BaseDIPIITracking](#)

- [Dll_Pll_Conf](#) & [config_params](#) ()
- const [Dll_Pll_Conf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t item_size)

Protected Attributes inherited from [BaseDIPIITracking](#)

- dll_pll_veml_tracking_sptr [tracking_sptr_](#)

12.170.1 Detailed Description

This class implements a code DLL + carrier PLL tracking loop block adapter for GLONASS L2 signals. Definition at line 43 of file [glonass_l2_ca_dll_pll_tracking.h](#).

12.170.2 Constructor & Destructor Documentation

12.170.2.1 GlonassL2CaDIPIITracking()

```
GlonassL2CaDllPllTracking::GlonassL2CaDllPllTracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDIPIITracking::role\(\)](#).

12.170.3 Member Function Documentation

12.170.3.1 implementation()

```
std::string GlonassL2CaDllPllTracking::implementation () [inline], [override], [virtual]
```

Returns "GLONASS_L2_CA_DLL_PLL_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 53 of file [glonass_l2_ca_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

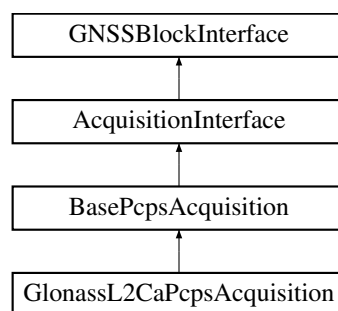
- [glonass_l2_ca_dll_pll_tracking.h](#)

12.171 GlonassL2CaPcpsAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GLONASS L2 C/A signals.

```
#include <glonass_l2_ca_pcps_acquisition.h>
```

Inheritance diagram for GlonassL2CaPcpsAcquisition:



Public Member Functions

- **GlonassL2CaPcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Returns "GLONASS_L2_CA_PCPS_Acquisition".
- std::string [implementation](#) () override

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)
ms_per_code)
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int doppler_center) override
Set Doppler center for the grid search.

- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t latency_samples) override
Sets the resampler latency to account it in the acquisition code delay estimation.
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

12.171.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GLONASS L2 C/A signals.
Definition at line 33 of file [glonass_l2_ca_pcps_acquisition.h](#).

12.171.2 Member Function Documentation

12.171.2.1 implementation()

```
std::string GlonassL2CaPcpsAcquisition::implementation () [inline], [override], [virtual]
```

Returns "GLONASS_L2_CA_PCPS_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 47 of file [glonass_l2_ca_pcps_acquisition.h](#).

The documentation for this class was generated from the following file:

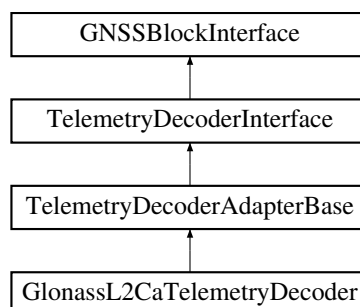
- [glonass_l2_ca_pcps_acquisition.h](#)

12.172 GlonassL2CaTelemetryDecoder Class Reference

This class implements a NAV data decoder for GLONASS L2 C/A.

```
#include <glonass_l2_ca_telemetry_decoder.h>
```

Inheritance diagram for GlonassL2CaTelemetryDecoder:



Public Member Functions

- **GlonassL2CaTelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GLONASS_L2_CA_Telemetry_Decoder".

Public Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- void **InitializeDecoder** (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & **satellite** () const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- [Tlm_Conf](#) tlm_parameters_

12.172.1 Detailed Description

This class implements a NAV data decoder for GLONASS L2 C/A.
Definition at line 34 of file [glonass_l2_ca_telemetry_decoder.h](#).

12.172.2 Member Function Documentation

12.172.2.1 [implementation\(\)](#)

```
std::string GlonassL2CaTelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "GLONASS_L2_CA_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 44 of file [glonass_l2_ca_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

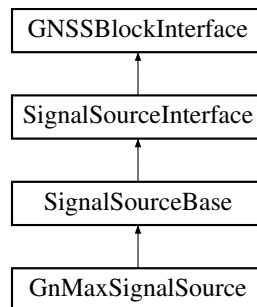
- [glonass_l2_ca_telemetry_decoder.h](#)

12.173 GnMaxSignalSource Class Reference

This class reads samples from a gnMAX2769 USB dongle, a RF front-end signal sampler.

```
#include <gnmax_signal_source.h>
```

Inheritance diagram for GnMaxSignalSource:



Public Member Functions

- **GnMaxSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_error=false)
utility for decoding passed ".item_type" values

12.173.1 Detailed Description

This class reads samples from a gnMAX2769 USB dongle, a RF front-end signal sampler.

Definition at line 44 of file [gnmax_signal_source.h](#).

12.173.2 Member Function Documentation

12.173.2.1 connect()

```
void GnMaxSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.173.2.2 disconnect()

```
void GnMaxSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.173.2.3 get_left_block()

```
gr::basic_block_sptr GnMaxSignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.173.2.4 get_right_block()

```
gr::basic_block_sptr GnMaxSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.173.2.5 item_size()

```
size_t GnMaxSignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 53 of file [gnmax_signal_source.h](#).

The documentation for this class was generated from the following file:

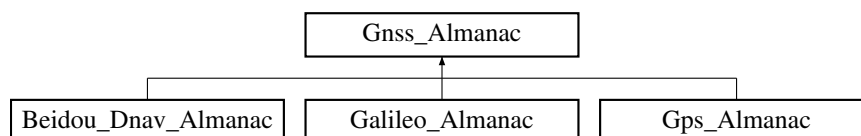
- [gnmax_signal_source.h](#)

12.174 Gnss_Almanac Class Reference

Base class for GNSS almanac storage.

```
#include <gnss_almanac.h>
```

Inheritance diagram for Gnss_Almanac:



Public Member Functions

- [Gnss_Almanac](#) ()=default
- double [predicted_doppler](#) (double rx_time_s, double lat, double lon, double h, double ve, double vn, double vu, int band) const
Computes prediction of the Doppler shift for a given time and receiver's position and velocity.
- void [satellitePosVelComputation](#) (double transmitTime, std::array< double, 7 > &pos_vel_dtr) const
Computes satellite Position and Velocity, in ECEF, for a given time (expressed in seconds of week)

Public Attributes

- uint32_t [PRN](#) {}
SV PRN NUMBER.
- double [delta_i](#) {}
Inclination Angle at Reference Time (relative to $i_0 = 0.30$ semi-circles)
- int32_t [toa](#) {}
Almanac data reference time of week [s].
- int32_t [WNa](#) {}
Almanac week number.
- double [M_0](#) {}
Mean Anomaly at Reference Time [semi-circles].
- double [ecc](#) {}
Eccentricity [dimensionless].
- double [sqrtA](#) {}
Square Root of the Semi-Major Axis [sqrt(m)].
- double [OMEGA_0](#) {}
Longitude of Ascending Node of Orbit Plane at Weekly Epoch [semi-circles].
- double [omega](#) {}
Argument of Perigee [semi-circles].
- double [OMEGAdot](#) {}
Rate of Right Ascension [semi-circles/s].
- double [af0](#) {}
Coefficient 0 of code phase offset model [s].
- double [af1](#) {}
Coefficient 1 of code phase offset model [s/s].

Protected Attributes

- char [System](#) {}
Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou.

12.174.1 Detailed Description

Base class for GNSS almanac storage.

Definition at line 33 of file [gnss_almanac.h](#).

12.174.2 Constructor & Destructor Documentation

12.174.2.1 Gnss_Almanac()

```
Gnss_Almanac::Gnss_Almanac () [default]
```

Default constructor

12.174.3 Member Function Documentation

12.174.3.1 predicted_doppler()

```
double Gnss_Almanac::predicted_doppler (
    double rx_time_s,
    double lat,
    double lon,
    double h,
    double ve,
    double vn,
```

```
double vu,
int band) const
```

Computes prediction of the Doppler shift for a given time and receiver's position and velocity.

$$f_d = -\mathbf{v} \frac{\mathbf{x}^T}{|\mathbf{x}|} \frac{f_L}{c}$$

where:

$$\mathbf{v} = \mathbf{v}_{sat} - \mathbf{v}_{rx}$$

$$\mathbf{x} = \mathbf{x}_{sat} - \mathbf{x}_{rx}$$

$$|\mathbf{x}| = \sqrt{\mathbf{x}\mathbf{x}^T}$$

Parameters

in	<i>rx_time</i> _s	Time of Week in seconds
in	<i>lat</i>	Receiver's latitude in degrees
in	<i>lon</i>	Receiver's longitude in degrees
in	<i>h</i>	Receiver's height in meters
in	<i>ve</i>	Receiver's velocity in the East direction [m/s]
in	<i>vn</i>	Receiver's velocity in the North direction [m/s]
in	<i>vu</i>	Receiver's velocity in the Up direction [m/s]
in	<i>band</i>	Signal band for which the Doppler will be computed (1: L1 C/A, E1B, BI1; 2: L2C, BI2; 3: BI3; 5: L5/E5a; 6: E6B; 7: E5b; 8: E5a+E5b)

12.174.3.2 satellitePosVelComputation()

```
void Gnss_Almanac::satellitePosVelComputation (
    double transmitTime,
    std::array< double, 7 > & pos_vel_dtr) const
```

Computes satellite Position and Velocity, in ECEF, for a given time (expressed in seconds of week)

12.174.4 Member Data Documentation

12.174.4.1 af0

```
double Gnss_Almanac::af0 {}
```

Coefficient 0 of code phase offset model [s].
Definition at line 91 of file [gnss_almanac.h](#).

12.174.4.2 af1

```
double Gnss_Almanac::af1 {}
```

Coefficient 1 of code phase offset model [s/s].
Definition at line 92 of file [gnss_almanac.h](#).

12.174.4.3 delta_i

```
double Gnss_Almanac::delta_i {}
```

Inclination Angle at Reference Time (relative to i_0 = 0.30 semi-circles)
Definition at line 82 of file [gnss_almanac.h](#).

12.174.4.4 ecc

```
double Gnss_Almanac::ecc {}
```

Eccentricity [dimensionless].
Definition at line 86 of file [gnss_almanac.h](#).

12.174.4.5 M_0

```
double Gnss_Almanac::M_0 {}
```

Mean Anomaly at Reference Time [semi-circles].

Definition at line 85 of file [gnss_almanac.h](#).

12.174.4.6 omega

```
double Gnss_Almanac::omega {}
```

Argument of Perigee [semi-circles].

Definition at line 89 of file [gnss_almanac.h](#).

12.174.4.7 OMEGA_0

```
double Gnss_Almanac::OMEGA_0 {}
```

Longitude of Ascending Node of Orbit Plane at Weekly Epoch [semi-circles].

Definition at line 88 of file [gnss_almanac.h](#).

12.174.4.8 OMEGAdot

```
double Gnss_Almanac::OMEGAdot {}
```

Rate of Right Ascension [semi-circles/s].

Definition at line 90 of file [gnss_almanac.h](#).

12.174.4.9 PRN

```
uint32_t Gnss_Almanac::PRN {}
```

SV PRN NUMBER.

Definition at line 81 of file [gnss_almanac.h](#).

12.174.4.10 sqrtA

```
double Gnss_Almanac::sqrtA {}
```

Square Root of the Semi-Major Axis [sqrt(m)].

Definition at line 87 of file [gnss_almanac.h](#).

12.174.4.11 System

```
char Gnss_Almanac::System {} [protected]
```

Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou.

Definition at line 95 of file [gnss_almanac.h](#).

Referenced by [Beidou_Dnav_Almanac::Beidou_Dnav_Almanac\(\)](#), [Galileo_Almanac::Galileo_Almanac\(\)](#), and [Gps_Almanac::Gps_Almanac\(\)](#).

12.174.4.12 toa

```
int32_t Gnss_Almanac::toa {}
```

Almanac data reference time of week [s].

Definition at line 83 of file [gnss_almanac.h](#).

12.174.4.13 WNa

```
int32_t Gnss_Almanac::WNa {}
```

Almanac week number.

Definition at line 84 of file [gnss_almanac.h](#).

The documentation for this class was generated from the following file:

- [gnss_almanac.h](#)

12.175 Gnss_circular_deque< T > Class Template Reference

Public Member Functions

- [Gnss_circular_deque](#) ()
Default constructor.
- [Gnss_circular_deque](#) (unsigned int max_size, unsigned int nchann)
nchann = number of channels; max_size = channel capacity
- unsigned int [size](#) (unsigned int ch) const
Returns the number of available elements in a channel.
- T & [at](#) (unsigned int ch, unsigned int pos)
Returns a reference to an element with bound checking.
- const T & [get](#) (unsigned int ch, unsigned int pos) const
Returns a const reference to an element without bound checking.
- T & [front](#) (unsigned int ch)
Returns a reference to the first element in the deque.
- T & [back](#) (unsigned int ch)
Returns a reference to the last element in the deque.
- void [push_back](#) (unsigned int ch, const T &new_data)
Inserts an element at the end of the deque.
- void [pop_front](#) (unsigned int ch)
Removes the first element of the deque.
- void [clear](#) (unsigned int ch)
Removes all the elements of the deque (Sets size to 0). Capacity is not modified.
- void [reset](#) (unsigned int max_size, unsigned int nchann)
Removes all the elements in all the channels. Re-sets the number of channels and their capacity.
- void [reset](#) ()
Removes all the channels (Sets nchann to 0)

12.175.1 Detailed Description

template<class T>

class Gnss_circular_deque< T >

Definition at line 31 of file [gnss_circular_deque.h](#).

The documentation for this class was generated from the following file:

- [gnss_circular_deque.h](#)

12.176 Gnss_Crypto Class Reference

Class implementing cryptographic functions for Navigation Message Authentication.

```
#include <gnss_crypto.h>
```

Public Member Functions

- [Gnss_Crypto](#) ()
Default constructor.
- [Gnss_Crypto](#) (const std::string &certFilePath, const std::string &merkleTreePath)
- [~Gnss_Crypto](#) ()
Default destructor.
- bool [have_public_key](#) () const
Returns true if the ECDSA Public Key is already loaded.
- bool [store_public_key](#) (const std::string &pubKeyFilePath) const

- bool [verify_signature_ecdsa_p256](#) (const std::vector< uint8_t > &message, const std::vector< uint8_t > &signature) const
Verify ECDSA-P256 signature (message in plain hex, signature in raw format)
- bool [verify_signature_ecdsa_p521](#) (const std::vector< uint8_t > &message, const std::vector< uint8_t > &signature) const
Verify ECDSA-P521 signature (message in plain hex, signature in raw format)
- std::vector< uint8_t > [compute_SHA_256](#) (const std::vector< uint8_t > &input) const
Computes SHA-256 hash.
- std::vector< uint8_t > [compute_SHA3_256](#) (const std::vector< uint8_t > &input) const
Computes SHA3-256 hash.
- std::vector< uint8_t > [compute_HMAC_SHA_256](#) (const std::vector< uint8_t > &key, const std::vector< uint8_t > &input) const
Computes HMAC-SHA-256 message authentication code.
- std::vector< uint8_t > [compute_CMAC_AES](#) (const std::vector< uint8_t > &key, const std::vector< uint8_t > &input) const
Computes CMAC-AES message authentication code.
- std::vector< uint8_t > [get_merkle_root](#) () const
Gets the Merkle Tree root node ($x_{4,0}$)
- std::string [get_public_key_type](#) () const
Gets the ECDSA Public Key type (ECDSA P-256 / ECDSA P-521 / Unknown)
- void [set_public_key](#) (const std::vector< uint8_t > &publickey)
Sets the ECDSA Public Key (publickey compressed format)
- void [set_public_key_type](#) (const std::string &public_key_type)
Sets the ECDSA Public Key type (ECDSA P-256 / ECDSA P-521)
- void [set_merkle_root](#) (const std::vector< uint8_t > &v)
Sets the Merkle Tree root node $x(x_{4,0})$
- void [read_merkle_xml](#) (const std::string &merkleFilePath)

12.176.1 Detailed Description

Class implementing cryptographic functions for Navigation Message Authentication.
Definition at line 41 of file [gnss_crypto.h](#).

12.176.2 Constructor & Destructor Documentation

12.176.2.1 Gnss_Crypto() [1/2]

Gnss_Crypto::Gnss_Crypto ()
Default constructor.

12.176.2.2 Gnss_Crypto() [2/2]

Gnss_Crypto::Gnss_Crypto (
 const std::string & certFilePath,
 const std::string & merkleTreePath)

Constructor with a .crt or .pem file for the ECDSA Public Key and a XML file for the Merkle Tree root. Files can be downloaded by registering at <https://www.gsc-europa.eu/>

12.176.2.3 ~Gnss_Crypto()

Gnss_Crypto::~Gnss_Crypto ()
Default destructor.

12.176.3 Member Function Documentation

12.176.3.1 compute_CMAC_AES()

```
std::vector< uint8_t > Gnss_Crypto::compute_CMAC_AES (
    const std::vector< uint8_t > & key,
    const std::vector< uint8_t > & input) const
```

Computes CMAC-AES message authentication code.

12.176.3.2 compute_HMAC_SHA_256()

```
std::vector< uint8_t > Gnss_Crypto::compute_HMAC_SHA_256 (
    const std::vector< uint8_t > & key,
    const std::vector< uint8_t > & input) const
```

Computes HMAC-SHA-256 message authentication code.

12.176.3.3 compute_SHA3_256()

```
std::vector< uint8_t > Gnss_Crypto::compute_SHA3_256 (
    const std::vector< uint8_t > & input) const
```

Computes SHA3-256 hash.

12.176.3.4 compute_SHA_256()

```
std::vector< uint8_t > Gnss_Crypto::compute_SHA_256 (
    const std::vector< uint8_t > & input) const
```

Computes SHA-256 hash.

12.176.3.5 get_merkle_root()

```
std::vector< uint8_t > Gnss_Crypto::get_merkle_root () const
```

Gets the Merkle Tree root node ($x_{4,0}$)

12.176.3.6 get_public_key_type()

```
std::string Gnss_Crypto::get_public_key_type () const
```

Gets the ECDSA Public Key type (ECDSA P-256 / ECDSA P-521 / Unknown)

12.176.3.7 have_public_key()

```
bool Gnss_Crypto::have_public_key () const
```

Returns true if the ECDSA Public Key is already loaded.

12.176.3.8 set_merkle_root()

```
void Gnss_Crypto::set_merkle_root (
    const std::vector< uint8_t > & v)
```

Sets the Merkle Tree root node $x_{4,0}$

12.176.3.9 set_public_key()

```
void Gnss_Crypto::set_public_key (
    const std::vector< uint8_t > & publickey)
```

Sets the ECDSA Public Key (publickey compressed format)

12.176.3.10 set_public_key_type()

```
void Gnss_Crypto::set_public_key_type (
    const std::string & public_key_type)
```

Sets the ECDSA Public Key type (ECDSA P-256 / ECDSA P-521)

12.176.3.11 store_public_key()

```
bool Gnss_Crypto::store_public_key (
    const std::string & pubKeyFilePath) const
```

Stores the ECDSA Public Key in a .pem file, which is read in a following run if the .crt file is not found

12.176.3.12 verify_signature_ecdsa_p256()

```
bool Gnss_Crypto::verify_signature_ecdsa_p256 (
    const std::vector< uint8_t > & message,
    const std::vector< uint8_t > & signature) const
```

Verify ECDSA-P256 signature (message in plain hex, signature in raw format)

12.176.3.13 verify_signature_ecdsa_p521()

```
bool Gnss_Crypto::verify_signature_ecdsa_p521 (
    const std::vector< uint8_t > & message,
    const std::vector< uint8_t > & signature) const
```

Verify ECDSA-P521 signature (message in plain hex, signature in raw format)

The documentation for this class was generated from the following file:

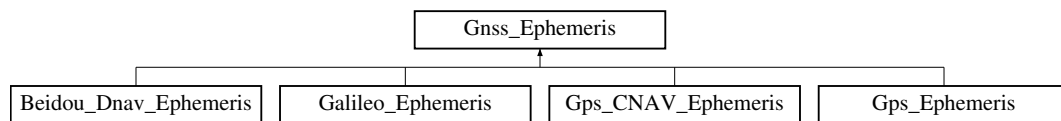
- [gnss_crypto.h](#)

12.177 Gnss_Ephemeris Class Reference

Base class for GNSS ephemeris storage.

```
#include <gnss_ephemeris.h>
```

Inheritance diagram for Gnss_Ephemeris:

**Public Member Functions**

- double [sv_clock_drift](#) (double transmitTime)
Sets (satClkDrift) and (dtr), and returns the clock drift in seconds according to the User Algorithm for SV Clock Correction (IS-GPS-200M, 20.3.3.3.3.1, and Galileo OS SIS ICD, 5.1.4).
- double [predicted_doppler](#) (double rx_time_s, double lat, double lon, double h, double ve, double vn, double vu, int band) const
Computes prediction of the Doppler shift for a given time and receiver's position and velocity.
- void [satellitePosition](#) (double transmitTime)
Computes the ECEF SV coordinates and ECEF velocity.

Public Attributes

- uint32_t [PRN](#) {}
SV ID.
- double [M_0](#) {}
Mean anomaly at reference time [rad].
- double [delta_n](#) {}
Mean motion difference from computed value [rad/sec].
- double [ecc](#) {}
Eccentricity.
- double [sqrtA](#) {}

- *Square root of the semi-major axis [meters^{1/2}].*
- double [OMEGA_0](#) {}
Longitude of ascending node of orbital plane at weekly epoch [rad].
- double [i_0](#) {}
Inclination angle at reference time [rad].
- double [omega](#) {}
Argument of perigee [rad].
- double [OMEGAdot](#) {}
Rate of right ascension [rad/sec].
- double [idot](#) {}
Rate of inclination angle [rad/sec].
- double [Cuc](#) {}
Amplitude of the cosine harmonic correction term to the argument of latitude [rad].
- double [Cus](#) {}
Amplitude of the sine harmonic correction term to the argument of latitude [rad].
- double [Crc](#) {}
Amplitude of the cosine harmonic correction term to the orbit radius [meters].
- double [Crs](#) {}
Amplitude of the sine harmonic correction term to the orbit radius [meters].
- double [Cic](#) {}
Amplitude of the cosine harmonic correction term to the angle of inclination [rad].
- double [Cis](#) {}
Amplitude of the sine harmonic correction term to the angle of inclination [rad].
- int32_t [toe](#) {}
Ephemeris reference time [s].
- int32_t [toc](#) {}
Clock correction data reference Time of Week [sec].
- double [af0](#) {}
SV clock bias correction coefficient [s].
- double [af1](#) {}
SV clock drift correction coefficient [s/s].
- double [af2](#) {}
SV clock drift rate correction coefficient [s/s²].
- double [satClkDrift](#) {}
SV clock drift.
- double [dtr](#) {}
Relativistic clock correction term.
- int32_t [WN](#) {}
Week number.
- int32_t [tow](#) {}
Time of Week.
- double [satpos_X](#) {}
Earth-fixed coordinate x of the satellite [m]. Intersection of the IERS Reference Meridian (IRM) and the plane passing through the origin and normal to the Z-axis.
- double [satpos_Y](#) {}
Earth-fixed coordinate y of the satellite [m]. Completes a right-handed, Earth-Centered, Earth-Fixed orthogonal coordinate system.
- double [satpos_Z](#) {}
Earth-fixed coordinate z of the satellite [m]. The direction of the IERS (International Earth Rotation and Reference Systems Service) Reference Pole (IRP).
- double [satvel_X](#) {}

Earth-fixed velocity coordinate x of the satellite [m].

- double [satvel_Y](#) {}

Earth-fixed velocity coordinate y of the satellite [m].

- double [satvel_Z](#) {}

Earth-fixed velocity coordinate z of the satellite [m].

Protected Attributes

- char [System](#) {}

Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou.

12.177.1 Detailed Description

Base class for GNSS ephemeris storage.

Definition at line 28 of file [gnss_ephemeris.h](#).

12.177.2 Member Function Documentation

12.177.2.1 predicted_doppler()

```
double Gnss_Ephemeris::predicted_doppler (
    double rx_time_s,
    double lat,
    double lon,
    double h,
    double ve,
    double vn,
    double vu,
    int band) const
```

Computes prediction of the Doppler shift for a given time and receiver's position and velocity.

$$f_d = -\mathbf{v} \frac{\mathbf{x}^T}{|\mathbf{x}|} \frac{f_L}{c}$$

where:

$$\mathbf{v} = \mathbf{v}_{sat} - \mathbf{v}_{rx}$$

$$\mathbf{x} = \mathbf{x}_{sat} - \mathbf{x}_{rx}$$

$$|\mathbf{x}| = \sqrt{\mathbf{x}\mathbf{x}^T}$$

Parameters

in	rx_time_s	Time of Week in seconds
in	lat	Receiver's latitude in degrees
in	lon	Receiver's longitude in degrees
in	h	Receiver's height in meters
in	ve	Receiver's velocity in the East direction [m/s]
in	vn	Receiver's velocity in the North direction [m/s]
in	vu	Receiver's velocity in the Up direction [m/s]
in	band	Signal band for which the Doppler will be computed (1: L1 C/A, E1B, B1I; 2: L2C, B1I2; 3: B1I3; 5: L5/E5a; 6: E6B; 7: E5b; 8: E5a+E5b)

12.177.2.2 `satellitePosition()`

```
void Gnss_Ephemeris::satellitePosition (
    double transmitTime)
```

Computes the ECEF SV coordinates and ECEF velocity.

12.177.2.3 `sv_clock_drift()`

```
double Gnss_Ephemeris::sv_clock_drift (
    double transmitTime)
```

Sets (*satClkDrift*) and (*dtr*), and returns the clock drift in seconds according to the User Algorithm for SV Clock Correction (IS-GPS-200M, 20.3.3.3.3.1, and Galileo OS SIS ICD, 5.1.4).

12.177.3 Member Data Documentation

12.177.3.1 `af0`

```
double Gnss_Ephemeris::af0 {}
```

SV clock bias correction coefficient [s].

Definition at line 90 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.2 `af1`

```
double Gnss_Ephemeris::af1 {}
```

SV clock drift correction coefficient [s/s].

Definition at line 91 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.3 `af2`

```
double Gnss_Ephemeris::af2 {}
```

SV clock drift rate correction coefficient [s/s²].

Definition at line 92 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.4 `Cic`

```
double Gnss_Ephemeris::Cic {}
```

Amplitude of the cosine harmonic correction term to the angle of inclination [rad].

Definition at line 84 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.5 `Cis`

```
double Gnss_Ephemeris::Cis {}
```

Amplitude of the sine harmonic correction term to the angle of inclination [rad].

Definition at line 85 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.6 `Crc`

```
double Gnss_Ephemeris::Crc {}
```

Amplitude of the cosine harmonic correction term to the orbit radius [meters].

Definition at line 82 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.7 Crs

```
double Gnss_Ephemeris::Crs {}
```

Amplitude of the sine harmonic correction term to the orbit radius [meters].

Definition at line 83 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.8 Cuc

```
double Gnss_Ephemeris::Cuc {}
```

Amplitude of the cosine harmonic correction term to the argument of latitude [rad].

Definition at line 80 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.9 Cus

```
double Gnss_Ephemeris::Cus {}
```

Amplitude of the sine harmonic correction term to the argument of latitude [rad].

Definition at line 81 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.10 delta_n

```
double Gnss_Ephemeris::delta_n {}
```

Mean motion difference from computed value [rad/sec].

Definition at line 72 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.11 dtr

```
double Gnss_Ephemeris::dtr {}
```

Relativistic clock correction term.

Definition at line 95 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.12 ecc

```
double Gnss_Ephemeris::ecc {}
```

Eccentricity.

Definition at line 73 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.13 i_0

```
double Gnss_Ephemeris::i_0 {}
```

Inclination angle at reference time [rad].

Definition at line 76 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.14 idot

```
double Gnss_Ephemeris::idot {}
```

Rate of inclination angle [rad/sec].

Definition at line 79 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.15 M_0

```
double Gnss_Ephemeris::M_0 {}
```

Mean anomaly at reference time [rad].

Definition at line 71 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.16 omega

```
double Gnss_Ephemeris::omega {}
```

Argument of perigee [rad].

Definition at line 77 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.17 OMEGA_0

```
double Gnss_Ephemeris::OMEGA_0 {}
```

Longitude of ascending node of orbital plane at weekly epoch [rad].

Definition at line 75 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.18 OMEGAdot

```
double Gnss_Ephemeris::OMEGAdot {}
```

Rate of right ascension [rad/sec].

Definition at line 78 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.19 PRN

```
uint32_t Gnss_Ephemeris::PRN {}
```

SV ID.

Definition at line 70 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.20 satClkDrift

```
double Gnss_Ephemeris::satClkDrift {}
```

SV clock drift.

Definition at line 94 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.21 satpos_X

```
double Gnss_Ephemeris::satpos_X {}
```

Earth-fixed coordinate x of the satellite [m]. Intersection of the IERS Reference Meridian (IRM) and the plane passing through the origin and normal to the Z-axis.

Definition at line 102 of file [gnss_ephemeris.h](#).

12.177.3.22 satpos_Y

```
double Gnss_Ephemeris::satpos_Y {}
```

Earth-fixed coordinate y of the satellite [m]. Completes a right-handed, Earth-Centered, Earth-Fixed orthogonal coordinate system.

Definition at line 103 of file [gnss_ephemeris.h](#).

12.177.3.23 satpos_Z

```
double Gnss_Ephemeris::satpos_Z {}
```

Earth-fixed coordinate z of the satellite [m]. The direction of the IERS (International Earth Rotation and Reference Systems Service) Reference Pole (IRP).

Definition at line 104 of file [gnss_ephemeris.h](#).

12.177.3.24 satvel_X

```
double Gnss_Ephemeris::satvel_X {}
```

Earth-fixed velocity coordinate x of the satellite [m].

Definition at line 107 of file [gnss_ephemeris.h](#).

12.177.3.25 satvel_Y

```
double Gnss_Ephemeris::satvel_Y {}
```

Earth-fixed velocity coordinate y of the satellite [m].

Definition at line 108 of file [gnss_ephemeris.h](#).

12.177.3.26 satvel_Z

```
double Gnss_Ephemeris::satvel_Z {}
```

Earth-fixed velocity coordinate z of the satellite [m].

Definition at line 109 of file [gnss_ephemeris.h](#).

12.177.3.27 sqrtA

```
double Gnss_Ephemeris::sqrtA {}
```

Square root of the semi-major axis [meters^{1/2}].

Definition at line 74 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.28 System

```
char Gnss_Ephemeris::System {} [protected]
```

Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou.

Definition at line 112 of file [gnss_ephemeris.h](#).

Referenced by [Gps_CNAV_Ephemeris::Gps_CNAV_Ephemeris\(\)](#).

12.177.3.29 toc

```
int32_t Gnss_Ephemeris::toc {}
```

Clock correction data reference Time of Week [sec].

Definition at line 89 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.30 toe

```
int32_t Gnss_Ephemeris::toe {}
```

Ephemeris reference time [s].

Definition at line 86 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.31 tow

```
int32_t Gnss_Ephemeris::tow {}
```

Time of Week.

Definition at line 99 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

12.177.3.32 WN

```
int32_t Gnss_Ephemeris::WN {}
```

Week number.

Definition at line 98 of file [gnss_ephemeris.h](#).

Referenced by [Serdes_Galileo_Eph::readProtobuffer\(\)](#), [Serdes_Gps_Eph::readProtobuffer\(\)](#), [Beidou_Dnav_Ephemeris::serialize\(\)](#), [Galileo_Ephemeris::serialize\(\)](#), [Gps_CNAV_Ephemeris::serialize\(\)](#), and [Gps_Ephemeris::serialize\(\)](#).

The documentation for this class was generated from the following file:

- [gnss_ephemeris.h](#)

12.178 Gnss_Satellite Class Reference

This class represents a GNSS satellite.

```
#include <gnss_satellite.h>
```

Public Member Functions

- [Gnss_Satellite](#) ()=default
Default Constructor.
- [Gnss_Satellite](#) (const std::string &system_, uint32_t PRN_)
Concrete GNSS satellite Constructor.
- [~Gnss_Satellite](#) ()=default
Default Destructor.
- [Gnss_Satellite](#) (const [Gnss_Satellite](#) &other) noexcept
Copy constructor.
- [Gnss_Satellite](#) & operator= (const [Gnss_Satellite](#) &) noexcept
Copy assignment operator.
- [Gnss_Satellite](#) ([Gnss_Satellite](#) &&other) noexcept
Move constructor.
- [Gnss_Satellite](#) & operator= ([Gnss_Satellite](#) &&other) noexcept
Move assignment operator.
- void [update_PRN](#) (uint32_t PRN)
Updates the PRN Number when information is decoded, only applies to GLONASS GNAV messages.
- uint32_t [get_PRN](#) () const
Gets satellite's PRN.
- int32_t [get_rf_link](#) () const
Gets the satellite's rf link.
- std::string [get_system](#) () const

- Gets the satellite system {"GPS", "Glonass", "SBAS", "Galileo", "Beidou", "QZSS"}.*
- `std::string get_system_short () const`
Gets the satellite system {"G", "R", "SBAS", "E", "C", "J"}.
- `std::string get_block () const`
Gets the satellite block. If GPS, returns {"IIA", "IIR", "IIR-M", "IIF"}.
- `std::string what_block (const std::string &system_, uint32_t PRN_)`
Gets the block of a given satellite.

Friends

- `bool operator== (const Gnss_Satellite &, const Gnss_Satellite &)`
operator== for comparison
- `std::ostream & operator<< (std::ostream &, const Gnss_Satellite &)`
operator<< for pretty printing

12.178.1 Detailed Description

This class represents a GNSS satellite.

It contains information about the space vehicles currently operational of GPS, Glonass, SBAS and Galileo constellations.

Definition at line 39 of file [gnss_satellite.h](#).

12.178.2 Constructor & Destructor Documentation

12.178.2.1 Gnss_Satellite() [1/4]

```
Gnss_Satellite::Gnss_Satellite () [default]
```

Default Constructor.

Referenced by [Gnss_Satellite\(\)](#), [Gnss_Satellite\(\)](#), [operator<<](#), [operator=\(\)](#), [operator=\(\)](#), and [operator==](#).

12.178.2.2 Gnss_Satellite() [2/4]

```
Gnss_Satellite::Gnss_Satellite (
    const std::string & system_,
    uint32_t PRN_)
```

Concrete GNSS satellite Constructor.

12.178.2.3 ~Gnss_Satellite()

```
Gnss_Satellite::~Gnss_Satellite () [default]
```

Default Destructor.

12.178.2.4 Gnss_Satellite() [3/4]

```
Gnss_Satellite::Gnss_Satellite (
    const Gnss_Satellite & other) [noexcept]
```

Copy constructor.

References [Gnss_Satellite\(\)](#).

12.178.2.5 Gnss_Satellite() [4/4]

```
Gnss_Satellite::Gnss_Satellite (
    Gnss_Satellite && other) [noexcept]
```

Move constructor.

References [Gnss_Satellite\(\)](#).

12.178.3 Member Function Documentation

12.178.3.1 `get_block()`

`std::string Gnss_Satellite::get_block () const`
 Gets the satellite block. If GPS, returns {"IIA", "IIR", "IIR-M", "IIF"}.

12.178.3.2 `get_PRN()`

`uint32_t Gnss_Satellite::get_PRN () const`
 Gets satellite's PRN.

12.178.3.3 `get_rf_link()`

`int32_t Gnss_Satellite::get_rf_link () const`
 Gets the satellite's rf link.

12.178.3.4 `get_system()`

`std::string Gnss_Satellite::get_system () const`
 Gets the satellite system {"GPS", "Glonass", "SBAS", "Galileo", "Beidou", "QZSS"}.

12.178.3.5 `get_system_short()`

`std::string Gnss_Satellite::get_system_short () const`
 Gets the satellite system {"G", "R", "SBAS", "E", "C", "J"}.

12.178.3.6 `operator=()` [1/2]

`Gnss_Satellite & Gnss_Satellite::operator= (`
 `const Gnss_Satellite &) [noexcept]`
 Copy assignment operator.
 References [Gnss_Satellite\(\)](#).

12.178.3.7 `operator=()` [2/2]

`Gnss_Satellite & Gnss_Satellite::operator= (`
 `Gnss_Satellite && other) [noexcept]`
 Move assignment operator.
 References [Gnss_Satellite\(\)](#).

12.178.3.8 `update_PRN()`

`void Gnss_Satellite::update_PRN (`
 `uint32_t PRN)`
 Updates the PRN Number when information is decoded, only applies to GLONASS GNAV messages.

12.178.3.9 `what_block()`

`std::string Gnss_Satellite::what_block (`
 `const std::string & system_,`
 `uint32_t PRN_)`
 Gets the block of a given satellite.

12.178.4 Friends And Related Symbol Documentation

12.178.4.1 `operator<<`

`std::ostream & operator<< (`
 `std::ostream & ,`
 `const Gnss_Satellite &) [friend]`

operator<< for pretty printing
References [Gnss_Satellite\(\)](#).

12.178.4.2 operator==

```
bool operator== (
    const Gnss\_Satellite & ,
    const Gnss\_Satellite & ) [friend]
```

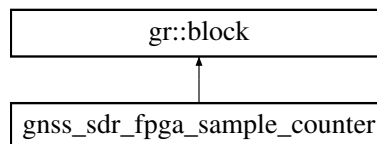
operator== for comparison
References [Gnss_Satellite\(\)](#).

The documentation for this class was generated from the following file:

- [gnss_satellite.h](#)

12.179 gnss_sdr_fpga_sample_counter Class Reference

Inheritance diagram for gnss_sdr_fpga_sample_counter:



Public Member Functions

- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- gnss_sdr_fpga_sample_counter_sptr **gnss_sdr_make_fpga_sample_counter** (double _fs, int32_t _↔ interval_ms)

12.179.1 Detailed Description

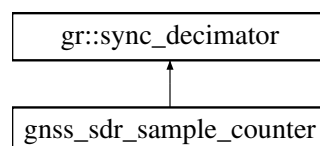
Definition at line 40 of file [gnss_sdr_fpga_sample_counter.h](#).

The documentation for this class was generated from the following file:

- [gnss_sdr_fpga_sample_counter.h](#)

12.180 gnss_sdr_sample_counter Class Reference

Inheritance diagram for gnss_sdr_sample_counter:



Public Member Functions

- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- gnss_sdr_sample_counter_sptr **gnss_sdr_make_sample_counter** (double _fs, int32_t _interval_ms, size_t _size)

12.180.1 Detailed Description

Definition at line 43 of file [gnss_sdr_sample_counter.h](#).

The documentation for this class was generated from the following file:

- [gnss_sdr_sample_counter.h](#)

12.181 Gnss_Sdr_Supl_Client Class Reference

class that implements a C++ interface to external Secure User Location Protocol (SUPL) client library..

```
#include <gnss_sdr_supl_client.h>
```

Public Member Functions

- int **get_assistance** (int i_mcc, int i_mns, int i_lac, int i_ci)
- void **read_supl_data** ()
- bool **load_ephemeris_xml** (const std::string &file_name)
Read GPS NAV ephemeris map from XML file.
- bool **save_ephemeris_map_xml** (const std::string &file_name, std::map< int, [Gps_Ephemeris](#) > eph_map)
Save ephemeris map to XML file.
- bool **load_cnav_ephemeris_xml** (const std::string &file_name)
Read GPS CNAV ephemeris map from XML file.
- bool **save_cnav_ephemeris_map_xml** (const std::string &file_name, std::map< int, [Gps_CNAV_Ephemeris](#) > eph_map)
Save GPS CNAV ephemeris map to XML file.
- bool **load_gal_ephemeris_xml** (const std::string &file_name)
Read Galileo ephemeris map from XML file.
- bool **save_gal_ephemeris_map_xml** (const std::string &file_name, std::map< int, [Galileo_Ephemeris](#) > eph_map)
Save Galileo ephemeris map to XML file.
- bool **load_gnav_ephemeris_xml** (const std::string &file_name)
Read GLONASS GNAV ephemeris map from XML file.
- bool **save_gnav_ephemeris_map_xml** (const std::string &file_name, std::map< int, [Glonass_Gnav_Ephemeris](#) > eph_map)
Save GLONASS GNAV ephemeris map to XML file.
- bool **load_utc_xml** (const std::string &file_name)
Read GPS utc model from XML file.
- bool **save_utc_xml** (const std::string &file_name, [Gps_Utc_Model](#) &utc)
Save UTC model map to XML file.
- bool **load_cnav_utc_xml** (const std::string &file_name)
Read CNAV GPS utc model from XML file.
- bool **save_cnav_utc_xml** (const std::string &file_name, [Gps_CNAV_Utc_Model](#) &utc)
Save CNAV UTC model map to XML file.
- bool **load_gal_utc_xml** (const std::string &file_name)
Read Galileo utc model from XML file.
- bool **save_gal_utc_xml** (const std::string &file_name, [Galileo_Utc_Model](#) &utc)
Save Galileo UTC model map to XML file.
- bool **load_gal_almanac_xml** (const std::string &file_name)
Read Galileo almanac map from XML file.

- bool [save_gal_almanac_xml](#) (const std::string &file_name, std::map< int, [Galileo_Almanac](#) > galileo_almanac_map_to_save)
Save Galileo almanac map to XML file.
- bool [load_gps_almanac_xml](#) (const std::string &file_name)
Read GPS almanac map from XML file.
- bool [save_gps_almanac_xml](#) (const std::string &file_name, std::map< int, [Gps_Almanac](#) > gps_almanac_map_to_save)
Save GPS almanac map to XML file.
- bool [load_iono_xml](#) (const std::string &file_name)
Read iono from XML file.
- bool [save_iono_xml](#) (const std::string &file_name, [Gps_Iono](#) &iono)
Save iono map to XML file.
- bool [load_gal_iono_xml](#) (const std::string &file_name)
Read Galileo iono from XML file.
- bool [save_gal_iono_xml](#) (const std::string &file_name, [Galileo_Iono](#) &iono)
Save Galileo iono map to XML file.
- bool [load_glo_utc_xml](#) (const std::string &file_name)
Read Glonass utc model from XML file.
- bool [save_glo_utc_xml](#) (const std::string &file_name, [Glonass_Gnav_Utc_Model](#) &utc)
Save Glonass UTC model map to XML file.
- bool [load_ref_time_xml](#) (const std::string &file_name)
Read ref time from XML file.
- bool [save_ref_time_xml](#) (const std::string &file_name, [Agnss_Ref_Time](#) &ref_time_map)
Save ref time map to XML file.
- bool [load_ref_location_xml](#) (const std::string &file_name)
Read ref location from XML file.
- bool [save_ref_location_xml](#) (const std::string &file_name, [Agnss_Ref_Location](#) &ref_location)
Save ref location map to XML file.
- void [print_assistance](#) ()

Public Attributes

- std::string [server_name](#)
- int [server_port](#)
- int [request](#)
- std::map< int, [Gps_Ephemeris](#) > [gps_ephemeris_map](#)
- std::map< int, [Galileo_Ephemeris](#) > [gal_ephemeris_map](#)
- std::map< int, [Gps_CNAV_Ephemeris](#) > [gps_cnav_ephemeris_map](#)
- std::map< int, [Glonass_Gnav_Ephemeris](#) > [glonass_gnav_ephemeris_map](#)
- std::map< int, [Gps_Almanac](#) > [gps_almanac_map](#)
- std::map< int, [Galileo_Almanac](#) > [gal_almanac_map](#)
- [Gps_Iono](#) [gps_iono](#)
- [Galileo_Iono](#) [gal_iono](#)
- [Agnss_Ref_Time](#) [gps_time](#)
- [Gps_Utc_Model](#) [gps_utc](#)
- [Galileo_Utc_Model](#) [gal_utc](#)
- [Gps_CNAV_Utc_Model](#) [gps_cnav_utc](#)
- [Glonass_Gnav_Utc_Model](#) [glo_gnav_utc](#)
- [Agnss_Ref_Location](#) [gps_ref_loc](#)
- std::map< int, [Gps_Acq_Assist](#) > [gps_acq_map](#)

12.181.1 Detailed Description

class that implements a C++ interface to external Secure User Location Protocol (SUPL) client library..
Definition at line 55 of file [gnss_sdr_supl_client.h](#).

12.181.2 Member Function Documentation

12.181.2.1 load_cnav_ephemeris_xml()

```
bool Gnss_Sdr_Supl_Client::load_cnav_ephemeris_xml (
    const std::string & file_name)
```

Read GPS CNAV ephemeris map from XML file.

12.181.2.2 load_cnav_utc_xml()

```
bool Gnss_Sdr_Supl_Client::load_cnav_utc_xml (
    const std::string & file_name)
```

Read CNAV GPS utc model from XML file.

12.181.2.3 load_ephemeris_xml()

```
bool Gnss_Sdr_Supl_Client::load_ephemeris_xml (
    const std::string & file_name)
```

Read GPS NAV ephemeris map from XML file.

12.181.2.4 load_gal_almanac_xml()

```
bool Gnss_Sdr_Supl_Client::load_gal_almanac_xml (
    const std::string & file_name)
```

Read Galileo almanac map from XML file.

12.181.2.5 load_gal_ephemeris_xml()

```
bool Gnss_Sdr_Supl_Client::load_gal_ephemeris_xml (
    const std::string & file_name)
```

Read Galileo ephemeris map from XML file.

12.181.2.6 load_gal_iono_xml()

```
bool Gnss_Sdr_Supl_Client::load_gal_iono_xml (
    const std::string & file_name)
```

Read Galileo iono from XML file.

12.181.2.7 load_gal_utc_xml()

```
bool Gnss_Sdr_Supl_Client::load_gal_utc_xml (
    const std::string & file_name)
```

Read Galileo utc model from XML file.

12.181.2.8 load_glo_utc_xml()

```
bool Gnss_Sdr_Supl_Client::load_glo_utc_xml (
    const std::string & file_name)
```

Read Glonass utc model from XML file.

12.181.2.9 load_gnav_ephemeris_xml()

```
bool Gnss_Sdr_Supl_Client::load_gnav_ephemeris_xml (
    const std::string & file_name)
```

Read GLONASS GNAV ephemeris map from XML file.

12.181.2.10 load_gps_almanac_xml()

```
bool Gnss_Sdr_Supl_Client::load_gps_almanac_xml (
    const std::string & file_name)
```

Read GPS almanac map from XML file.

12.181.2.11 load_iono_xml()

```
bool Gnss_Sdr_Supl_Client::load_iono_xml (
    const std::string & file_name)
```

Read iono from XML file.

12.181.2.12 load_ref_location_xml()

```
bool Gnss_Sdr_Supl_Client::load_ref_location_xml (
    const std::string & file_name)
```

Read ref location from XML file.

12.181.2.13 load_ref_time_xml()

```
bool Gnss_Sdr_Supl_Client::load_ref_time_xml (
    const std::string & file_name)
```

Read ref time from XML file.

12.181.2.14 load_utc_xml()

```
bool Gnss_Sdr_Supl_Client::load_utc_xml (
    const std::string & file_name)
```

Read GPS utc model from XML file.

12.181.2.15 save_cnav_ephemeris_map_xml()

```
bool Gnss_Sdr_Supl_Client::save_cnav_ephemeris_map_xml (
    const std::string & file_name,
    std::map< int, Gps_CNAV_Ephemeris > eph_map)
```

Save GPS CNAV ephemeris map to XML file.

12.181.2.16 save_cnav_utc_xml()

```
bool Gnss_Sdr_Supl_Client::save_cnav_utc_xml (
    const std::string & file_name,
    Gps_CNAV_Utc_Model & utc)
```

Save CNAV UTC model map to XML file.

12.181.2.17 save_ephemeris_map_xml()

```
bool Gnss_Sdr_Supl_Client::save_ephemeris_map_xml (
    const std::string & file_name,
    std::map< int, Gps_Ephemeris > eph_map)
```

Save ephemeris map to XML file.

12.181.2.18 save_gal_almanac_xml()

```
bool Gnss_Sdr_Supl_Client::save_gal_almanac_xml (
    const std::string & file_name,
    std::map< int, Galileo_Almanac > galileo_almanac_map_to_save)
```

Save Galileo almanac map to XML file.

12.181.2.19 save_gal_ephemeris_map_xml()

```
bool Gnss_Sdr_Supl_Client::save_gal_ephemeris_map_xml (
    const std::string & file_name,
    std::map< int, Galileo_Ephemeris > eph_map)
```

Save Galileo ephemeris map to XML file.

12.181.2.20 save_gal_iono_xml()

```
bool Gnss_Sdr_Supl_Client::save_gal_iono_xml (
    const std::string & file_name,
    Galileo_Iono & iono)
```

Save Galileo iono map to XML file.

12.181.2.21 save_gal_utc_xml()

```
bool Gnss_Sdr_Supl_Client::save_gal_utc_xml (
    const std::string & file_name,
    Galileo_Utc_Model & utc)
```

Save Galileo UTC model map to XML file.

12.181.2.22 save_glo_utc_xml()

```
bool Gnss_Sdr_Supl_Client::save_glo_utc_xml (
    const std::string & file_name,
    Glonass_Gnav_Utc_Model & utc)
```

Save Glonass UTC model map to XML file.

12.181.2.23 save_gnav_ephemeris_map_xml()

```
bool Gnss_Sdr_Supl_Client::save_gnav_ephemeris_map_xml (
    const std::string & file_name,
    std::map< int, Glonass_Gnav_Ephemeris > eph_map)
```

Save GLONASS GNAV ephemeris map to XML file.

12.181.2.24 save_gps_almanac_xml()

```
bool Gnss_Sdr_Supl_Client::save_gps_almanac_xml (
    const std::string & file_name,
    std::map< int, Gps_Almanac > gps_almanac_map_to_save)
```

Save GPS almanac map to XML file.

12.181.2.25 save_iono_xml()

```
bool Gnss_Sdr_Supl_Client::save_iono_xml (
    const std::string & file_name,
    Gps_Iono & iono)
```

Save iono map to XML file.

12.181.2.26 save_ref_location_xml()

```
bool Gnss_Sdr_Supl_Client::save_ref_location_xml (
    const std::string & file_name,
    Agnss_Ref_Location & ref_location)
```

Save ref location map to XML file.

12.181.2.27 save_ref_time_xml()

```
bool Gnss_Sdr_Supl_Client::save_ref_time_xml (
    const std::string & file_name,
    Agnss_Ref_Time & ref_time_map)
```

Save ref time map to XML file.

12.181.2.28 save_utc_xml()

```
bool Gnss_Sdr_Supl_Client::save_utc_xml (
    const std::string & file_name,
    Gps_Utc_Model & utc)
```

Save UTC model map to XML file.

12.181.3 Member Data Documentation

12.181.3.1 gal_almanac_map

```
std::map<int, Galileo_Almanac> Gnss_Sdr_Supl_Client::gal_almanac_map
```

Definition at line 73 of file [gnss_sdr_supl_client.h](#).

12.181.3.2 gal_ephemeris_map

```
std::map<int, Galileo_Ephemeris> Gnss_Sdr_Supl_Client::gal_ephemeris_map
```

Definition at line 67 of file [gnss_sdr_supl_client.h](#).

12.181.3.3 gal_iono

```
Galileo_Iono Gnss_Sdr_Supl_Client::gal_iono
```

Definition at line 77 of file [gnss_sdr_supl_client.h](#).

12.181.3.4 gal_utc

```
Galileo_Utc_Model Gnss_Sdr_Supl_Client::gal_utc
```

Definition at line 82 of file [gnss_sdr_supl_client.h](#).

12.181.3.5 glo_gnav_utc

```
Glonass_Gnav_Utc_Model Gnss_Sdr_Supl_Client::glo_gnav_utc
```

Definition at line 84 of file [gnss_sdr_supl_client.h](#).

12.181.3.6 glonass_gnav_ephemeris_map

```
std::map<int, Glonass_Gnav_Ephemeris> Gnss_Sdr_Supl_Client::glonass_gnav_ephemeris_map
```

Definition at line 69 of file [gnss_sdr_supl_client.h](#).

12.181.3.7 gps_acq_map

```
std::map<int, Gps_Acq_Assist> Gnss_Sdr_Supl_Client::gps_acq_map
```

Definition at line 88 of file [gnss_sdr_supl_client.h](#).

12.181.3.8 gps_almanac_map

```
std::map<int, Gps_Almanac> Gnss_Sdr_Supl_Client::gps_almanac_map
```

Definition at line 72 of file [gnss_sdr_supl_client.h](#).

12.181.3.9 gps_cnav_ephemeris_map

```
std::map<int, Gps_CNAV_Ephemeris> Gnss_Sdr_Supl_Client::gps_cnav_ephemeris_map
```

Definition at line 68 of file [gnss_sdr_supl_client.h](#).

12.181.3.10 gps_cnav_utc

[Gps_CNAV_Utc_Model](#) Gnss_Sdr_Supl_Client::gps_cnav_utc
 Definition at line 83 of file [gnss_sdr_supl_client.h](#).

12.181.3.11 gps_ephemeris_map

`std::map<int, Gps_Ephemeris>` Gnss_Sdr_Supl_Client::gps_ephemeris_map
 Definition at line 66 of file [gnss_sdr_supl_client.h](#).

12.181.3.12 gps_iono

[Gps_Iono](#) Gnss_Sdr_Supl_Client::gps_iono
 Definition at line 76 of file [gnss_sdr_supl_client.h](#).

12.181.3.13 gps_ref_loc

[Agnss_Ref_Location](#) Gnss_Sdr_Supl_Client::gps_ref_loc
 Definition at line 86 of file [gnss_sdr_supl_client.h](#).

12.181.3.14 gps_time

[Agnss_Ref_Time](#) Gnss_Sdr_Supl_Client::gps_time
 Definition at line 79 of file [gnss_sdr_supl_client.h](#).

12.181.3.15 gps_utc

[Gps_Utc_Model](#) Gnss_Sdr_Supl_Client::gps_utc
 Definition at line 81 of file [gnss_sdr_supl_client.h](#).

12.181.3.16 request

`int` Gnss_Sdr_Supl_Client::request
 Definition at line 64 of file [gnss_sdr_supl_client.h](#).

12.181.3.17 server_name

`std::string` Gnss_Sdr_Supl_Client::server_name
 Definition at line 62 of file [gnss_sdr_supl_client.h](#).

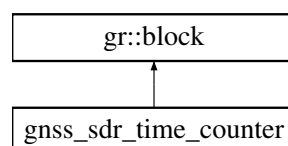
12.181.3.18 server_port

`int` Gnss_Sdr_Supl_Client::server_port
 Definition at line 63 of file [gnss_sdr_supl_client.h](#).
 The documentation for this class was generated from the following file:

- [gnss_sdr_supl_client.h](#)

12.182 gnss_sdr_time_counter Class Reference

Inheritance diagram for `gnss_sdr_time_counter`:



Public Member Functions

- int **general_work** (int noutput_items __attribute__((unused)), gr_vector_int &ninput_items __attribute__((unused)), gr_vector_const_void_star &input_items __attribute__((unused)), gr_vector_void_star &output_items)

Friends

- gnss_sdr_time_counter_sptr **gnss_sdr_make_time_counter** ()

12.182.1 Detailed Description

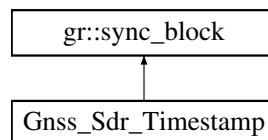
Definition at line 38 of file [gnss_sdr_time_counter.h](#).

The documentation for this class was generated from the following file:

- [gnss_sdr_time_counter.h](#)

12.183 Gnss_Sdr_Timestamp Class Reference

Inheritance diagram for Gnss_Sdr_Timestamp:

**Public Member Functions**

- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)
- bool **start** ()

Friends

- gnss_shared_ptr< [Gnss_Sdr_Timestamp](#) > **gnss_sdr_make_Timestamp** (size_t sizeof_stream_item, std::string timestamp_file, double clock_offset_ms, int items_to_samples)

12.183.1 Detailed Description

Definition at line 46 of file [gnss_sdr_timestamp.h](#).

The documentation for this class was generated from the following file:

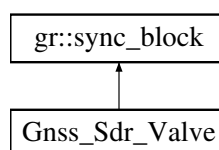
- [gnss_sdr_timestamp.h](#)

12.184 Gnss_Sdr_Valve Class Reference

Implementation of a GNU Radio block that sends a STOP message to the control queue right after a specific number of samples have passed through it.

```
#include <gnss_sdr_valve.h>
```

Inheritance diagram for Gnss_Sdr_Valve:



Public Member Functions

- void **open_valve** ()
- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- gnss_shared_ptr< [Gnss_Sdr_Valve](#) > **gnss_sdr_make_valve** (size_t sizeof_stream_item, uint64_t nitems, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- gnss_shared_ptr< [Gnss_Sdr_Valve](#) > **gnss_sdr_make_valve** (size_t sizeof_stream_item, uint64_t nitems, [Concurrent_Queue](#)< pmt::pmt_t > *queue, bool stop_flowgraph)

12.184.1 Detailed Description

Implementation of a GNU Radio block that sends a STOP message to the control queue right after a specific number of samples have passed through it.

Definition at line 54 of file [gnss_sdr_valve.h](#).

The documentation for this class was generated from the following file:

- [gnss_sdr_valve.h](#)

12.185 Gnss_Signal Class Reference

This class represents a GNSS signal.

```
#include <gnss_signal.h>
```

Public Member Functions

- **Gnss_Signal** (const std::string &signal_)
- **Gnss_Signal** (const [Gnss_Satellite](#) &satellite_, const std::string &signal_)
- std::string **get_signal_str** () const
Return the signal identifier string.
- [Gnss_Satellite](#) **get_satellite** () const
Get the [Gnss_Satellite](#) associated to the signal.

Friends

- bool **operator==** (const [Gnss_Signal](#) &, const [Gnss_Signal](#) &)
operator== for comparison
- std::ostream & **operator<<** (std::ostream &, const [Gnss_Signal](#) &)
operator<< for pretty printing

12.185.1 Detailed Description

This class represents a GNSS signal.

Encapsulates a specific GNSS signal (e.g., GPS L1 C/A, Galileo E1B) and its associated satellite.

Definition at line 38 of file [gnss_signal.h](#).

12.185.2 Member Function Documentation

12.185.2.1 get_satellite()

```
Gnss\_Satellite Gnss_Signal::get_satellite () const
```

Get the [Gnss_Satellite](#) associated to the signal.

12.185.2.2 get_signal_str()

```
std::string Gnss_Signal::get_signal_str () const
```

Return the signal identifier string.

- GPS: "1C" (L1 C/A), "2S" (L2C), "L5"
- GLONASS: "1G" (L1 C/A), "2G" (L2 C/A)
- Galileo: "1B" (E1B), "5X" (E5a), "7X" (E5b), "6C" (E6C)
- BeiDou: "B1" (B1I), "B3" (B3I)

12.185.3 Friends And Related Symbol Documentation

12.185.3.1 operator<<

```
std::ostream & operator<< (
    std::ostream & ,
    const Gnss_Signal & ) [friend]
```

operator<< for pretty printing

12.185.3.2 operator==

```
bool operator== (
    const Gnss_Signal & ,
    const Gnss_Signal & ) [friend]
```

operator== for comparison

The documentation for this class was generated from the following file:

- [gnss_signal.h](#)

12.186 Gnss_Synchro Class Reference

This is the class that contains the information that is shared by the processing blocks.

```
#include <gnss_synchro.h>
```

Public Member Functions

- [Gnss_Synchro](#) ()=default
Default constructor.
- [~Gnss_Synchro](#) ()=default
Default destructor.
- [Gnss_Synchro](#) (const [Gnss_Synchro](#) &other) noexcept=default
Copy constructor.
- [Gnss_Synchro](#) & [operator=](#) (const [Gnss_Synchro](#) &rhs) noexcept
Copy assignment operator.
- [Gnss_Synchro](#) ([Gnss_Synchro](#) &&other) noexcept=default
Move constructor.
- [Gnss_Synchro](#) & [operator=](#) ([Gnss_Synchro](#) &&other) noexcept
Move assignment operator.
- `template<class Archive>`
void [serialize](#) (Archive &ar, const unsigned int version)
This member function serializes and restores [Gnss_Synchro](#) objects from a byte stream.

Public Attributes

- char [System](#) {}
Set by Channel::set_signal(Gnss_Signal gnss_signal)
- char [Signal](#) [3] {}
Set by Channel::set_signal(Gnss_Signal gnss_signal)
- uint32_t [PRN](#) {}
Set by Channel::set_signal(Gnss_Signal gnss_signal)
- int32_t [Channel_ID](#) {}
Set by Channel constructor.
- double [Acq_delay_samples](#) {}
Set by Acquisition processing block.
- double [Acq_doppler_hz](#) {}
Set by Acquisition processing block.
- uint64_t [Acq_samplestamp_samples](#) {}
Set by Acquisition processing block.
- uint32_t [Acq_doppler_step](#) {}
Set by Acquisition processing block.
- int64_t [fs](#) {}
Set by Tracking processing block.
- double [Prompt_I](#) {}
Set by Tracking processing block.
- double [Prompt_Q](#) {}
Set by Tracking processing block.
- double [CN0_dB_hz](#) {}
Set by Tracking processing block.
- double [Carrier_Doppler_hz](#) {}
Set by Tracking processing block.
- double [Carrier_phase_rads](#) {}
Set by Tracking processing block.
- double [Code_phase_samples](#) {}
Set by Tracking processing block.
- uint64_t [Tracking_sample_counter](#) {}
Set by Tracking processing block.
- int32_t [correlation_length_ms](#) {}
Set by Tracking processing block.
- uint32_t [TOW_at_current_symbol_ms](#) {}
Set by Telemetry Decoder processing block.
- double [Pseudorange_m](#) {}
Set by Observables processing block.
- double [RX_time](#) {}
Set by Observables processing block.
- double [interp_TOW_ms](#) {}
Set by Observables processing block.
- bool [Flag_valid_acquisition](#) {}
Set by Acquisition processing block.
- bool [Flag_valid_symbol_output](#) {}
Set by Tracking processing block.
- bool [Flag_valid_word](#) {}
Set by Telemetry Decoder processing block.
- bool [Flag_valid_pseudorange](#) {}

Set by Observables processing block.

- bool [Flag_PLL_180_deg_phase_locked](#) {}

Set by Telemetry Decoder processing block.

- bool [Flag_cycle_slip](#) {}

Set by Observables processing block.

12.186.1 Detailed Description

This is the class that contains the information that is shared by the processing blocks.

Definition at line 38 of file [gnss_synchro.h](#).

12.186.2 Constructor & Destructor Documentation

12.186.2.1 Gnss_Synchro() [1/3]

```
Gnss_Synchro::Gnss_Synchro () [default]
```

Default constructor.

Referenced by [Gnss_Synchro\(\)](#), [Gnss_Synchro\(\)](#), [operator=\(\)](#), and [operator=\(\)](#).

12.186.2.2 ~Gnss_Synchro()

```
Gnss_Synchro::~Gnss_Synchro () [default]
```

Default destructor.

12.186.2.3 Gnss_Synchro() [2/3]

```
Gnss_Synchro::Gnss_Synchro (
    const Gnss_Synchro & other) [default], [noexcept]
```

Copy constructor.

References [Gnss_Synchro\(\)](#).

12.186.2.4 Gnss_Synchro() [3/3]

```
Gnss_Synchro::Gnss_Synchro (
    Gnss_Synchro && other) [default], [noexcept]
```

Move constructor.

References [Gnss_Synchro\(\)](#).

12.186.3 Member Function Documentation

12.186.3.1 operator=() [1/2]

```
Gnss_Synchro & Gnss_Synchro::operator= (
    const Gnss_Synchro & rhs) [inline], [noexcept]
```

Copy assignment operator.

Definition at line 88 of file [gnss_synchro.h](#).

References [Gnss_Synchro\(\)](#).

12.186.3.2 operator=() [2/2]

```
Gnss_Synchro & Gnss_Synchro::operator= (
    Gnss_Synchro && other) [inline], [noexcept]
```

Move assignment operator.

Definition at line 130 of file [gnss_synchro.h](#).

References [Gnss_Synchro\(\)](#).

12.186.3.3 serialize()

```
template<class Archive>
void Gnss_Synchro::serialize (
    Archive & ar,
    const unsigned int version) [inline]
```

This member function serializes and restores [Gnss_Synchro](#) objects from a byte stream.

Definition at line 203 of file [gnss_synchro.h](#).

References [Acq_delay_samples](#), [Acq_doppler_hz](#), [Acq_doppler_step](#), [Acq_samplestamp_samples](#), [Carrier_Doppler_hz](#), [Carrier_phase_rads](#), [Channel_ID](#), [CN0_dB_hz](#), [Code_phase_samples](#), [correlation_length_ms](#), [Flag_cycle_slip](#), [Flag_PLL_180_deg_phase_locked](#), [Flag_valid_acquisition](#), [Flag_valid_pseudorange](#), [Flag_valid_symbol_output](#), [Flag_valid_word](#), [fs](#), [interp_TOW_ms](#), [PRN](#), [Prompt_I](#), [Prompt_Q](#), [Pseudorange_m](#), [RX_time](#), [Signal](#), [System](#), [TOW_at_current_symbol_ms](#), and [Tracking_sample_counter](#).

12.186.4 Member Data Documentation

12.186.4.1 Acq_delay_samples

```
double Gnss_Synchro::Acq_delay_samples {}
```

Set by Acquisition processing block.

Definition at line 52 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.2 Acq_doppler_hz

```
double Gnss_Synchro::Acq_doppler_hz {}
```

Set by Acquisition processing block.

Definition at line 53 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.3 Acq_doppler_step

```
uint32_t Gnss_Synchro::Acq_doppler_step {}
```

Set by Acquisition processing block.

Definition at line 55 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.4 Acq_samplestamp_samples

```
uint64_t Gnss_Synchro::Acq_samplestamp_samples {}
```

Set by Acquisition processing block.

Definition at line 54 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.5 Carrier_Doppler_hz

```
double Gnss_Synchro::Carrier_Doppler_hz {}
```

Set by Tracking processing block.

Definition at line 62 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.6 Carrier_phase_rads

```
double Gnss_Synchro::Carrier_phase_rads {}
```

Set by Tracking processing block.

Definition at line 63 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.7 Channel_ID

```
int32_t Gnss_Synchro::Channel_ID {}
```

Set by [Channel](#) constructor.

Definition at line 49 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.8 CN0_dB_hz

```
double Gnss_Synchro::CN0_dB_hz {}
```

Set by Tracking processing block.

Definition at line 61 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.9 Code_phase_samples

```
double Gnss_Synchro::Code_phase_samples {}
```

Set by Tracking processing block.

Definition at line 64 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.10 correlation_length_ms

```
int32_t Gnss_Synchro::correlation_length_ms {}
```

Set by Tracking processing block.

Definition at line 66 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.11 Flag_cycle_slip

```
bool Gnss_Synchro::Flag_cycle_slip {}
```

Set by Observables processing block.

Definition at line 82 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.12 Flag_PLL_180_deg_phase_locked

```
bool Gnss_Synchro::Flag_PLL_180_deg_phase_locked {}
```

Set by Telemetry Decoder processing block.

Definition at line 81 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.13 Flag_valid_acquisition

```
bool Gnss_Synchro::Flag_valid_acquisition {}
```

Set by Acquisition processing block.

Definition at line 77 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.14 Flag_valid_pseudorange

```
bool Gnss_Synchro::Flag_valid_pseudorange {}
```

Set by Observables processing block.

Definition at line 80 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.15 Flag_valid_symbol_output

```
bool Gnss_Synchro::Flag_valid_symbol_output {}
```

Set by Tracking processing block.

Definition at line 78 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.16 Flag_valid_word

```
bool Gnss_Synchro::Flag_valid_word {}
```

Set by Telemetry Decoder processing block.

Definition at line 79 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.17 fs

```
int64_t Gnss_Synchro::fs {}
```

Set by Tracking processing block.

Definition at line 58 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.18 interp_TOW_ms

```
double Gnss_Synchro::interp_TOW_ms {}
```

Set by Observables processing block.

Definition at line 74 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.19 PRN

```
uint32_t Gnss_Synchro::PRN {}
```

Set by Channel::set_signal(Gnss_Signal gnss_signal)

Definition at line 48 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.20 Prompt_I

```
double Gnss_Synchro::Prompt_I {}
```

Set by Tracking processing block.

Definition at line 59 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.21 Prompt_Q

```
double Gnss_Synchro::Prompt_Q {}
```

Set by Tracking processing block.

Definition at line 60 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.22 Pseudorange_m

```
double Gnss_Synchro::Pseudorange_m {}
```

Set by Observables processing block.

Definition at line 72 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.23 RX_time

```
double Gnss_Synchro::RX_time {}
```

Set by Observables processing block.

Definition at line 73 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.24 Signal

```
char Gnss_Synchro::Signal[3] {}
```

Set by Channel::set_signal(Gnss_Signal gnss_signal)

Definition at line 47 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.25 System

```
char Gnss_Synchro::System {}
```

Set by Channel::set_signal(Gnss_Signal gnss_signal)

Definition at line 46 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.26 TOW_at_current_symbol_ms

```
uint32_t Gnss_Synchro::TOW_at_current_symbol_ms {}
```

Set by Telemetry Decoder processing block.

Definition at line 69 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.186.4.27 Tracking_sample_counter

```
uint64_t Gnss_Synchro::Tracking_sample_counter {}
```

Set by Tracking processing block.

Definition at line 65 of file [gnss_synchro.h](#).

Referenced by [Serdes_Gnss_Synchro::readProtobuffer\(\)](#), and [serialize\(\)](#).

The documentation for this class was generated from the following file:

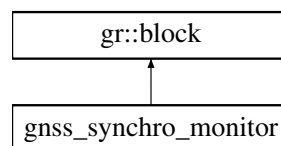
- [gnss_synchro.h](#)

12.187 gnss_synchro_monitor Class Reference

This class implements a monitoring block which allows sending a data stream with the receiver internal parameters ([Gnss_Synchro](#) objects) to local or remote clients over UDP.

```
#include <gnss_synchro_monitor.h>
```

Inheritance diagram for gnss_synchro_monitor:



Public Member Functions

- [~gnss_synchro_monitor](#) ()=default
Default destructor.
- void **forecast** (int noutput_items, gr_vector_int &ninput_items_required)
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- gnss_synchro_monitor_sptr **gnss_synchro_make_monitor** (int n_channels, int decimation_factor, const std::vector< std::string > &udp_ports, const std::vector< std::string > &udp_addresses, bool enable_protobuf)

12.187.1 Detailed Description

This class implements a monitoring block which allows sending a data stream with the receiver internal parameters ([Gnss_Synchro](#) objects) to local or remote clients over UDP.

Definition at line 53 of file [gnss_synchro_monitor.h](#).

12.187.2 Constructor & Destructor Documentation

12.187.2.1 ~gnss_synchro_monitor()

```
gnss_synchro_monitor::~gnss_synchro_monitor () [default]
```

Default destructor.

The documentation for this class was generated from the following file:

- [gnss_synchro_monitor.h](#)

12.188 Gnss_Synchro_Udp_Sink Class Reference

This class sends serialized [Gnss_Synchro](#) objects over UDP to one or multiple endpoints.

```
#include <gnss_synchro_udp_sink.h>
```

Public Member Functions

- **Gnss_Synchro_Udp_Sink** (const std::vector< std::string > &addresses, const std::vector< std::string > &ports, bool enable_protobuf)
- bool **write_gnss_synchro** (const std::vector< [Gnss_Synchro](#) > &stocks)

12.188.1 Detailed Description

This class sends serialized [Gnss_Synchro](#) objects over UDP to one or multiple endpoints.

Definition at line 45 of file [gnss_synchro_udp_sink.h](#).

The documentation for this class was generated from the following file:

- [gnss_synchro_udp_sink.h](#)

12.189 GNSSBlockFactory Class Reference

Class that produces all kinds of GNSS blocks.

```
#include <gnss_block_factory.h>
```

Public Member Functions

- std::unique_ptr< [SignalSourceInterface](#) > **GetSignalSource** (const [ConfigurationInterface](#) *configuration, [Concurrent_Queue](#)< pmt::pmt_t > *queue, int ID=-1) const
- std::unique_ptr< [GNSSBlockInterface](#) > **GetSignalConditioner** (const [ConfigurationInterface](#) *configuration, int ID=-1) const
- std::vector< std::unique_ptr< [GNSSBlockInterface](#) > > **GetChannels** (const [ConfigurationInterface](#) *configuration, [Concurrent_Queue](#)< pmt::pmt_t > *queue) const
- std::unique_ptr< [GNSSBlockInterface](#) > **GetObservables** (const [ConfigurationInterface](#) *configuration) const
- std::unique_ptr< [GNSSBlockInterface](#) > **GetPVT** (const [ConfigurationInterface](#) *configuration) const
- std::unique_ptr< [GNSSBlockInterface](#) > **GetBlock** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue=nullptr) const

Returns the block with the required role implementation and its configuration parameters.

12.189.1 Detailed Description

Class that produces all kinds of GNSS blocks.

Definition at line 49 of file [gnss_block_factory.h](#).

12.189.2 Member Function Documentation

12.189.2.1 GetBlock()

```
std::unique_ptr< GNSSBlockInterface > GNSSBlockFactory::GetBlock (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams,
    Concurrent_Queue< pmt::pmt_t > * queue = nullptr) const
```

Returns the block with the required role implementation and its configuration parameters.

The documentation for this class was generated from the following file:

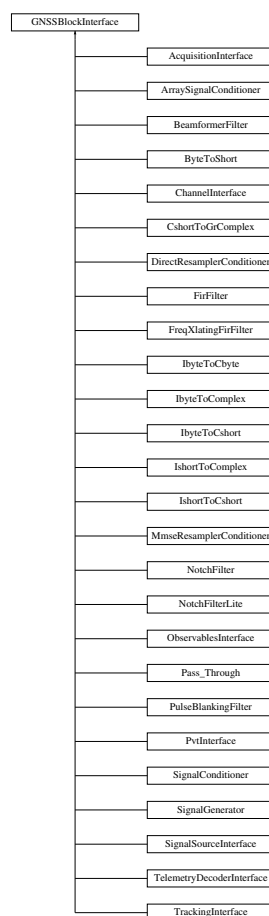
- [gnss_block_factory.h](#)

12.190 GNSSBlockInterface Class Reference

This abstract class represents an interface to GNSS blocks.

```
#include <gnss_block_interface.h>
```

Inheritance diagram for GNSSBlockInterface:



Public Member Functions

- virtual std::string [role](#) ()=0

- virtual std::string [implementation](#) ()=0
- virtual size_t [item_size](#) ()=0
- virtual void [connect](#) (gr::top_block_sptr top_block)=0
- virtual void [disconnect](#) (gr::top_block_sptr top_block)=0
- virtual gr::basic_block_sptr [get_left_block](#) ()=0
- virtual gr::basic_block_sptr [get_right_block](#) ()=0
- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.190.1 Detailed Description

This abstract class represents an interface to GNSS blocks.

Abstract class for GNSS block interfaces. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

Definition at line 68 of file [gnss_block_interface.h](#).

12.190.2 Member Function Documentation

12.190.2.1 connect()

```
virtual void GNSSBlockInterface::connect (
    gr::top_block_sptr top_block) [pure virtual]
```

Implemented in [BaseDIIPITracking](#), [BaseDIIPITrackingFpga](#), [Channel](#), and [FifoSignalSource](#).

12.190.2.2 disconnect()

```
virtual void GNSSBlockInterface::disconnect (
    gr::top_block_sptr top_block) [pure virtual]
```

Implemented in [BaseDIIPITracking](#), and [BaseDIIPITrackingFpga](#).

12.190.2.3 get_left_block() [1/2]

```
virtual gr::basic_block_sptr GNSSBlockInterface::get_left_block () [pure virtual]
```

Implemented in [BaseDIIPITracking](#), and [BaseDIIPITrackingFpga](#).

12.190.2.4 get_left_block() [2/2]

```
virtual gr::basic_block_sptr GNSSBlockInterface::get_left_block (
    int RF_channel) [inline], [virtual]
```

Definition at line 81 of file [gnss_block_interface.h](#).

12.190.2.5 get_right_block() [1/2]

```
virtual gr::basic_block_sptr GNSSBlockInterface::get_right_block () [pure virtual]
```

Implemented in [BaseDIIPITracking](#), [BaseDIIPITrackingFpga](#), and [Channel](#).

12.190.2.6 get_right_block() [2/2]

```
virtual gr::basic_block_sptr GNSSBlockInterface::get_right_block (
    int RF_channel) [inline], [virtual]
```

Definition at line 89 of file [gnss_block_interface.h](#).

12.190.2.7 implementation()

```
virtual std::string GNSSBlockInterface::implementation () [pure virtual]
```

Implemented in [ArraySignalConditioner](#), [BeamformerFilter](#), [BeidouB1iDIIPIITracking](#), [BeidouB1iPcpsAcquisition](#), [BeidouB1iTelemetryDecoder](#), [BeidouB3iDIIPIITracking](#), [BeidouB3iPcpsAcquisition](#), [BeidouB3iTelemetryDecoder](#), [ByteToShort](#), [Channel](#), [CshortToGrComplex](#), [DirectResamplerConditioner](#), [FirFilter](#), [FreqXlatingFirFilter](#), [GalileoE1BTelemetryDecoder](#), [GalileoE1DIIPIIVemlTracking](#), [GalileoE1Pcps8msAmbiguousAcquisition](#), [GalileoE1PcpsAmbiguousAcquisition](#), [GalileoE1PcpsAmbiguousAcquisitionFpga](#), [GalileoE1PcpsCccwsrAmbiguousAcquisition](#), [GalileoE1PcpsQuickSyncAmbiguousAcquisition](#), [GalileoE1PcpsTongAmbiguousAcquisition](#), [GalileoE1TcpConnectorTracking](#), [GalileoE5aDIIPIITracking](#), [GalileoE5aDIIPIITrackingFpga](#), [GalileoE5aNoncoherentIQAcquisitionCaf](#), [GalileoE5aPcpsAcquisitionFpga](#), [GalileoE5aTelemetryDecoder](#), [GalileoE5bDIIPIITracking](#), [GalileoE5bPcpsAcquisition](#), [GalileoE5bPcpsAcquisitionFpga](#), [GalileoE5bTelemetryDecoder](#), [GalileoE6DIIPIITracking](#), [GalileoE6PcpsAcquisition](#), [GalileoE6TelemetryDecoder](#), [GenSignalSource](#), [GlonassL1CaDIIPIITracking](#), [GlonassL1CaPcpsAcquisition](#), [GlonassL1CaTelemetryDecoder](#), [GlonassL2CaDIIPIITracking](#), [GlonassL2CaPcpsAcquisition](#), [GlonassL2CaTelemetryDecoder](#), [GpsL1CaDIIPIITracking](#), [GpsL1CaDIIPIITrackingFpga](#), [GpsL1CaDIIPIITrackingGPU](#), [GpsL1CaGaussianTracking](#), [GpsL1CaKfTracking](#), [GpsL1CaPcpsAcquisition](#), [GpsL1CaPcpsAcquisitionFineDoppler](#), [GpsL1CaPcpsAcquisitionFpga](#), [GpsL1CaPcpsAssistedAcquisition](#), [GpsL1CaPcpsOpenCIAcquisition](#), [GpsL1CaPcpsQuickSyncAcquisition](#), [GpsL1CaPcpsTongAcquisition](#), [GpsL1CaTcpConnectorTracking](#), [GpsL1CaTelemetryDecoder](#), [GpsL2CTelemetryDecoder](#), [GpsL2MDIIPIITracking](#), [GpsL2MDIIPIITrackingFpga](#), [GpsL2MPcpsAcquisition](#), [GpsL2MPcpsAcquisitionFpga](#), [GpsL5DIIPIITracking](#), [GpsL5DIIPIITrackingFpga](#), [GpsL5iPcpsAcquisition](#), [GpsL5iPcpsAcquisitionFpga](#), [GpsL5TelemetryDecoder](#), [HybridObservables](#), [lbyteToCbyte](#), [lbyteToComplex](#), [lbyteToCshort](#), [lshortToComplex](#), [lshortToCshort](#), [NotchFilter](#), [NotchFilterLite](#), [Pass_Through](#), [PulseBlankingFilter](#), [QzssL1DIIPIITracking](#), [QzssL1PcpsAcquisition](#), [QzssL1TelemetryDecoder](#), [QzssL5DIIPIITracking](#), [QzssL5iPcpsAcquisition](#), [QzssL5TelemetryDecoder](#), [Rtklib_Pvt](#), [SbasL1TelemetryDecoder](#), [SignalConditioner](#), and [SignalGenerator](#).

12.190.2.8 item_size()

```
virtual size_t GNSSBlockInterface::item_size () [pure virtual]
```

Implemented in [BaseDIIPIITracking](#), [BaseDIIPIITrackingFpga](#), [FileSourceBase](#), [HybridObservables](#), and [Rtklib_Pvt](#).

12.190.2.9 role()

```
virtual std::string GNSSBlockInterface::role () [pure virtual]
```

Implemented in [BaseDIIPIITracking](#), and [BaseDIIPIITrackingFpga](#).

12.190.2.10 start()

```
virtual void GNSSBlockInterface::start () [inline], [virtual]
```

Start the flow of samples if needed.

Reimplemented in [DMASignalSourceFPGA](#).

Definition at line 101 of file [gnss_block_interface.h](#).

The documentation for this class was generated from the following file:

- [gnss_block_interface.h](#)

12.191 GNSSFlowgraph Class Reference

This class represents a GNSS flow graph.

```
#include <gnss_flowgraph.h>
```

Public Member Functions

- [GNSSFlowgraph](#) (std::shared_ptr< [ConfigurationInterface](#) > configuration, std::shared_ptr< [Concurrent_Queue](#)< pmt::pmt_t > > queue)
Constructor that initializes the receiver flow graph.
- [~GNSSFlowgraph](#) ()
Destructor.
- void [start](#) ()
Start the flow graph.

- void [stop](#) ()
Stop the flow graph.
- void [connect](#) ()
Connects the defined blocks in the flow graph.
- void [disconnect](#) ()
Disconnect the blocks in the flow graph.
- void [wait](#) ()
Wait for a flowgraph to complete.
- void [acquisition_manager](#) (unsigned int who)
Manage satellite acquisition.
- void [apply_action](#) (unsigned int who, unsigned int what)
Applies an action to the flow graph.
- void [set_configuration](#) (const std::shared_ptr< [ConfigurationInterface](#) > &configuration)
Set flow graph configuration.
- bool [connected](#) () const
- bool [running](#) () const
- bool [send_telemetry_msg](#) (const pmt::pmt_t &msg)
Sends a GNU Radio asynchronous message from telemetry to PVT.
- std::shared_ptr< [PvtInterface](#) > [get_pvt](#) ()
Returns a smart pointer to the PVT object.
- void [prioritize_satellites](#) (const std::vector< std::pair< int, [Gnss_Satellite](#) > > &visible_satellites)
Prioritize visible satellites in the specified vector.

12.191.1 Detailed Description

This class represents a GNSS flow graph.
It contains a signal source, a signal conditioner, a set of channels, a PVT and an output filter.
Definition at line 67 of file [gnss_flowgraph.h](#).

12.191.2 Constructor & Destructor Documentation

12.191.2.1 GNSSFlowgraph()

```
GNSSFlowgraph::GNSSFlowgraph (
    std::shared_ptr< ConfigurationInterface > configuration,
    std::shared_ptr< Concurrent\_Queue< pmt::pmt_t > > queue)
```

Constructor that initializes the receiver flow graph.

12.191.2.2 ~GNSSFlowgraph()

```
GNSSFlowgraph::~GNSSFlowgraph ()
```

Destructor.

12.191.3 Member Function Documentation

12.191.3.1 acquisition_manager()

```
void GNSSFlowgraph::acquisition_manager (
    unsigned int who)
```

Manage satellite acquisition.

Parameters

in	who	Channel ID
--------------------	---------------------	----------------------------

12.191.3.2 apply_action()

```
void GNSSFlowgraph::apply_action (
    unsigned int who,
    unsigned int what)
```

Applies an action to the flow graph.

Parameters

in	<i>who</i>	Who generated the action
in	<i>what</i>	What is the action. 0: acquisition failed; 1: acquisition success; 2: tracking lost

12.191.3.3 connect()

```
void GNSSFlowgraph::connect ()
```

Connects the defined blocks in the flow graph.

Signal Source > Signal conditioner > Channels >> Observables >> PVT > Output filter

12.191.3.4 connected()

```
bool GNSSFlowgraph::connected () const [inline]
```

Definition at line 131 of file [gnss_flowgraph.h](#).

12.191.3.5 disconnect()

```
void GNSSFlowgraph::disconnect ()
```

Disconnect the blocks in the flow graph.

12.191.3.6 get_pvt()

```
std::shared_ptr< PvtInterface > GNSSFlowgraph::get_pvt () [inline]
```

Returns a smart pointer to the PVT object.

Definition at line 151 of file [gnss_flowgraph.h](#).

12.191.3.7 prioritize_satellites()

```
void GNSSFlowgraph::prioritize_satellites (
    const std::vector< std::pair< int, Gnss_Satellite > > & visible_satellites)
```

Prioritize visible satellites in the specified vector.

12.191.3.8 running()

```
bool GNSSFlowgraph::running () const [inline]
```

Definition at line 136 of file [gnss_flowgraph.h](#).

12.191.3.9 send_telemetry_msg()

```
bool GNSSFlowgraph::send_telemetry_msg (
    const pmt::pmt_t & msg)
```

Sends a GNU Radio asynchronous message from telemetry to PVT.

It is used to assist the receiver with external ephemeris data

12.191.3.10 set_configuration()

```
void GNSSFlowgraph::set_configuration (
    const std::shared_ptr< ConfigurationInterface > & configuration)
```

Set flow graph configuration.

12.191.3.11 start()

```
void GNSSFlowgraph::start ()
```

Start the flow graph.

12.191.3.12 stop()

```
void GNSSFlowgraph::stop ()
```

Stop the flow graph.

12.191.3.13 wait()

```
void GNSSFlowgraph::wait ()
```

Wait for a flowgraph to complete.

Flowgraphs complete when either (1) all blocks indicate that they are done, or (2) after [stop\(\)](#) has been called to request shutdown.

The documentation for this class was generated from the following file:

- [gnss_flowgraph.h](#)

12.192 GnssTime Class Reference

Public Attributes

- double [rx_time](#)
- int [week](#)
- int [tow_ms](#)
- double [tow_ms_fraction](#)

12.192.1 Detailed Description

Definition at line 23 of file [gnss_time.h](#).

12.192.2 Member Data Documentation

12.192.2.1 rx_time

```
double GnssTime::rx_time
```

Definition at line 26 of file [gnss_time.h](#).

12.192.2.2 tow_ms

```
int GnssTime::tow_ms
```

Definition at line 28 of file [gnss_time.h](#).

12.192.2.3 tow_ms_fraction

```
double GnssTime::tow_ms_fraction
```

Definition at line 29 of file [gnss_time.h](#).

12.192.2.4 week

```
int GnssTime::week
```

GPS week number (since January 1980)

Definition at line 27 of file [gnss_time.h](#).

The documentation for this class was generated from the following file:

- [gnss_time.h](#)

12.193 Gps_Acq_Assist Class Reference

This class is a storage for the GPS GSM RRLP acquisition assistance data as described in Digital cellular telecommunications system (Phase 2+); Location Services (LCS); Mobile Station (MS) - Serving Mobile Location Centre (SMLC) Radio Resource LCS Protocol (RRLP) (3GPP TS 44.031 version 5.12.0 Release 5)

```
#include <gps_acq_assist.h>
```

Public Member Functions

- [Gps_Acq_Assist](#) ()=default

Public Attributes

- uint32_t [PRN](#) {}
SV PRN NUMBER.
- double [tow](#) {}
Time Of Week assigned to the acquisition data.
- double [Doppler0](#) {}
Doppler (0 order term) [Hz].
- double [Doppler1](#) {}
Doppler (1 order term) [Hz].
- double [dopplerUncertainty](#) {}
Doppler Uncertainty [Hz].
- double [Code_Phase](#) {}
Code phase [chips].
- double [Code_Phase_int](#) {}
Integer Code Phase [1 C/A code period].
- double [GPS_Bit_Number](#) {}
GPS Bit Number.
- double [Code_Phase_window](#) {}
Code Phase search window [chips].
- double [Azimuth](#) {}
Satellite Azimuth [deg].
- double [Elevation](#) {}
Satellite Elevation [deg].

12.193.1 Detailed Description

This class is a storage for the GPS GSM RRLP acquisition assistance data as described in Digital cellular telecommunications system (Phase 2+); Location Services (LCS); Mobile Station (MS) - Serving Mobile Location Centre (SMLC) Radio Resource LCS Protocol (RRLP) (3GPP TS 44.031 version 5.12.0 Release 5)

Definition at line 37 of file [gps_acq_assist.h](#).

12.193.2 Constructor & Destructor Documentation

12.193.2.1 Gps_Acq_Assist()

```
Gps_Acq_Assist::Gps_Acq_Assist () [default]
```

Default constructor

12.193.3 Member Data Documentation

12.193.3.1 Azimuth

```
double Gps_Acq_Assist::Azimuth {}
```

Satellite Azimuth [deg].

Definition at line 54 of file [gps_acq_assist.h](#).

12.193.3.2 Code_Phase

double Gps_Acq_Assist::Code_Phase {}
Code phase [chips].
Definition at line 50 of file [gps_acq_assist.h](#).

12.193.3.3 Code_Phase_int

double Gps_Acq_Assist::Code_Phase_int {}
Integer Code Phase [1 C/A code period].
Definition at line 51 of file [gps_acq_assist.h](#).

12.193.3.4 Code_Phase_window

double Gps_Acq_Assist::Code_Phase_window {}
Code Phase search window [chips].
Definition at line 53 of file [gps_acq_assist.h](#).

12.193.3.5 Doppler0

double Gps_Acq_Assist::Doppler0 {}
Doppler (0 order term) [Hz].
Definition at line 47 of file [gps_acq_assist.h](#).

12.193.3.6 Doppler1

double Gps_Acq_Assist::Doppler1 {}
Doppler (1 order term) [Hz].
Definition at line 48 of file [gps_acq_assist.h](#).

12.193.3.7 dopplerUncertainty

double Gps_Acq_Assist::dopplerUncertainty {}
Doppler Uncertainty [Hz].
Definition at line 49 of file [gps_acq_assist.h](#).

12.193.3.8 Elevation

double Gps_Acq_Assist::Elevation {}
Satellite Elevation [deg].
Definition at line 55 of file [gps_acq_assist.h](#).

12.193.3.9 GPS_Bit_Number

double Gps_Acq_Assist::GPS_Bit_Number {}
GPS Bit Number.
Definition at line 52 of file [gps_acq_assist.h](#).

12.193.3.10 PRN

uint32_t Gps_Acq_Assist::PRN {}
SV PRN NUMBER.
Definition at line 45 of file [gps_acq_assist.h](#).

12.193.3.11 tow

double Gps_Acq_Assist::tow {}
Time Of Week assigned to the acquisition data.
Definition at line 46 of file [gps_acq_assist.h](#).
The documentation for this class was generated from the following file:

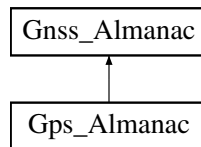
- [gps_acq_assist.h](#)

12.194 Gps_Almanac Class Reference

This class is a storage for the GPS SV ALMANAC data as described in IS-GPS-200M.

```
#include <gps_almanac.h>
```

Inheritance diagram for Gps_Almanac:



Public Member Functions

- [Gps_Almanac](#) ()
- `template<class Archive>`
void [serialize](#) (Archive &ar, const unsigned int version)

Public Member Functions inherited from [Gnss_Almanac](#)

- [Gnss_Almanac](#) ()=default
- double [predicted_doppler](#) (double rx_time_s, double lat, double lon, double h, double ve, double vn, double vu, int band) const
Computes prediction of the Doppler shift for a given time and receiver's position and velocity.
- void [satellitePosVelComputation](#) (double transmitTime, std::array< double, 7 > &pos_vel_dtr) const
Computes satellite Position and Velocity, in ECEF, for a given time (expressed in seconds of week)

Public Attributes

- int32_t [SV_health](#) {}
SV Health.
- int32_t [AS_status](#) {}
Anti-Spoofing Flags and SV Configuration.

Public Attributes inherited from [Gnss_Almanac](#)

- uint32_t [PRN](#) {}
SV PRN NUMBER.
- double [delta_i](#) {}
Inclination Angle at Reference Time (relative to $i_0 = 0.30$ semi-circles)
- int32_t [toa](#) {}
Almanac data reference time of week [s].
- int32_t [WNa](#) {}
Almanac week number.
- double [M_0](#) {}
Mean Anomaly at Reference Time [semi-circles].
- double [ecc](#) {}
Eccentricity [dimensionless].
- double [sqrtA](#) {}
Square Root of the Semi-Major Axis [sqrt(m)].
- double [OMEGA_0](#) {}

- Longitude of Ascending Node of Orbit Plane at Weekly Epoch [semi-circles].*
- double `omega` {}
- Argument of Perigee [semi-circles].*
- double `OMEGAdot` {}
- Rate of Right Ascension [semi-circles/s].*
- double `af0` {}
- Coefficient 0 of code phase offset model [s].*
- double `af1` {}
- Coefficient 1 of code phase offset model [s/s].*

Additional Inherited Members

Protected Attributes inherited from `Gnss_Almanac`

- char `System` {}
- Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou.*

12.194.1 Detailed Description

This class is a storage for the GPS SV ALMANAC data as described in IS-GPS-200M.

See <https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf> Appendix II
Definition at line 35 of file `gps_almanac.h`.

12.194.2 Constructor & Destructor Documentation

12.194.2.1 `Gps_Almanac()`

`Gps_Almanac::Gps_Almanac () [inline]`
Default constructor
Definition at line 41 of file `gps_almanac.h`.
References `Gnss_Almanac::System`.

12.194.3 Member Function Documentation

12.194.3.1 `serialize()`

```
template<class Archive>
void Gps_Almanac::serialize (
    Archive & ar,
    const unsigned int version) [inline]
```

Definition at line 51 of file `gps_almanac.h`.

12.194.4 Member Data Documentation

12.194.4.1 `AS_status`

`int32_t Gps_Almanac::AS_status {}`
Anti-Spoofing Flags and SV Configuration.
Definition at line 47 of file `gps_almanac.h`.

12.194.4.2 `SV_health`

`int32_t Gps_Almanac::SV_health {}`
SV Health.
Definition at line 46 of file `gps_almanac.h`.
The documentation for this class was generated from the following file:

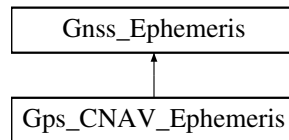
- `gps_almanac.h`

12.195 Gps_CNAV_Ephemeris Class Reference

This is a storage class for the GPS CNAV ephemeris data as described in IS-GPS-200M.

```
#include <gps_cnav_ephemeris.h>
```

Inheritance diagram for Gps_CNAV_Ephemeris:



Public Member Functions

- [Gps_CNAV_Ephemeris](#) ()
- `template<class Archive>`
void [serialize](#) (Archive &archive, const uint32_t version)
Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Public Member Functions inherited from [Gnss_Ephemeris](#)

- double [sv_clock_drift](#) (double transmitTime)
Sets (satClkDrift) and (dtr), and returns the clock drift in seconds according to the User Algorithm for SV Clock Correction (IS-GPS-200M, 20.3.3.3.3.1, and Galileo OS SIS ICD, 5.1.4).
- double [predicted_doppler](#) (double rx_time_s, double lat, double lon, double h, double ve, double vn, double vu, int band) const
Computes prediction of the Doppler shift for a given time and receiver's position and velocity.
- void [satellitePosition](#) (double transmitTime)
Computes the ECEF SV coordinates and ECEF velocity.

Public Attributes

- double [delta_A](#) {}
Semi-major axis difference at reference time.
- double [Adot](#) {}
Change rate in semi-major axis.
- double [delta_ndot](#) {}
Rate of mean motion difference from computed value.
- double [delta_OMEGAdot](#) {}
Rate of Right Ascension difference [semi-circles/s].
- int32_t [toe1](#) {}
Ephemeris data reference time of week (Ref. 20.3.3.4.3 IS-GPS-200M) [s].
- int32_t [toe2](#) {}
Ephemeris data reference time of week (Ref. 20.3.3.4.3 IS-GPS-200M) [s].
- int32_t [signal_health](#) {}
Signal health (L1/L2/L5)
- int32_t [top](#) {}
Data predict time of week.
- int32_t [URA](#) {}
ED Accuracy Index.
- double [URA0](#) {}
NED Accuracy Index.
- double [URA1](#) {}

- *NED Accuracy Change Index.*
- double [URA2](#) {}
- *NED Accuracy Change Rate Index.*
- double [TGD](#) {}
- *Estimated Group Delay Differential: L1-L2 correction term only for the benefit of "L1 P(Y)" or "L2 P(Y)" s users [s].*
- double [ISCL1](#) {}
- double [ISCL2](#) {}
- double [ISCL5I](#) {}
- double [ISCL5Q](#) {}
- bool [integrity_status_flag](#) {}
- *If true, enhanced level of integrity assurance.*
- bool [l2c_phasing_flag](#) {}
- bool [alert_flag](#) {}
- *If true, indicates that the SV URA may be worse than indicated in d_SV_accuracy, use that SV at our own risk.*
- bool [antispoofing_flag](#) {}
- *If true, the AntiSpoofing mode is ON in that SV.*

Public Attributes inherited from [Gnss_Ephemeris](#)

- uint32_t [PRN](#) {}
- *SV ID.*
- double [M_0](#) {}
- *Mean anomaly at reference time [rad].*
- double [delta_n](#) {}
- *Mean motion difference from computed value [rad/sec].*
- double [ecc](#) {}
- *Eccentricity.*
- double [sqrtA](#) {}
- *Square root of the semi-major axis [meters^{1/2}].*
- double [OMEGA_0](#) {}
- *Longitude of ascending node of orbital plane at weekly epoch [rad].*
- double [i_0](#) {}
- *Inclination angle at reference time [rad].*
- double [omega](#) {}
- *Argument of perigee [rad].*
- double [OMEGAdot](#) {}
- *Rate of right ascension [rad/sec].*
- double [idot](#) {}
- *Rate of inclination angle [rad/sec].*
- double [Cuc](#) {}
- *Amplitude of the cosine harmonic correction term to the argument of latitude [rad].*
- double [Cus](#) {}
- *Amplitude of the sine harmonic correction term to the argument of latitude [rad].*
- double [Crc](#) {}
- *Amplitude of the cosine harmonic correction term to the orbit radius [meters].*
- double [Crs](#) {}
- *Amplitude of the sine harmonic correction term to the orbit radius [meters].*
- double [Cic](#) {}
- *Amplitude of the cosine harmonic correction term to the angle of inclination [rad].*
- double [Cis](#) {}
- *Amplitude of the sine harmonic correction term to the angle of inclination [rad].*

- `int32_t toe {}`
Ephemeris reference time [s].
- `int32_t toc {}`
Clock correction data reference Time of Week [sec].
- `double af0 {}`
SV clock bias correction coefficient [s].
- `double af1 {}`
SV clock drift correction coefficient [s/s].
- `double af2 {}`
SV clock drift rate correction coefficient [s/s²].
- `double satClkDrift {}`
SV clock drift.
- `double dtr {}`
Relativistic clock correction term.
- `int32_t WN {}`
Week number.
- `int32_t tow {}`
Time of Week.
- `double satpos_X {}`
Earth-fixed coordinate x of the satellite [m]. Intersection of the IERS Reference Meridian (IRM) and the plane passing through the origin and normal to the Z-axis.
- `double satpos_Y {}`
Earth-fixed coordinate y of the satellite [m]. Completes a right-handed, Earth-Centered, Earth-Fixed orthogonal coordinate system.
- `double satpos_Z {}`
Earth-fixed coordinate z of the satellite [m]. The direction of the IERS (International Earth Rotation and Reference Systems Service) Reference Pole (IRP).
- `double satvel_X {}`
Earth-fixed velocity coordinate x of the satellite [m].
- `double satvel_Y {}`
Earth-fixed velocity coordinate y of the satellite [m].
- `double satvel_Z {}`
Earth-fixed velocity coordinate z of the satellite [m].

Additional Inherited Members

Protected Attributes inherited from [Gnss_Ephemeris](#)

- `char System {}`
Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou.

12.195.1 Detailed Description

This is a storage class for the GPS CNAV ephemeris data as described in IS-GPS-200M.

See <https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf> Appendix III Definition at line 37 of file [gps_cnav_ephemeris.h](#).

12.195.2 Constructor & Destructor Documentation

12.195.2.1 Gps_CNAV_Ephemeris()

```
Gps_CNAV_Ephemeris::Gps_CNAV_Ephemeris () [inline]
```

Constructor

Definition at line 43 of file [gps_cnav_ephemeris.h](#).

References [Gnss_Ephemeris::System](#).

12.195.3 Member Function Documentation

12.195.3.1 serialize()

```
template<class Archive>
void Gps_CNAV_Ephemeris::serialize (
    Archive & archive,
    const uint32_t version) [inline]
```

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Definition at line 93 of file [gps_cnav_ephemeris.h](#).

References [Adot](#), [Gnss_Ephemeris::af0](#), [Gnss_Ephemeris::af1](#), [Gnss_Ephemeris::af2](#), [alert_flag](#), [antispoofing_flag](#), [Gnss_Ephemeris::Cic](#), [Gnss_Ephemeris::Cis](#), [Gnss_Ephemeris::Crc](#), [Gnss_Ephemeris::Crs](#), [Gnss_Ephemeris::Cuc](#), [Gnss_Ephemeris::Cus](#), [delta_A](#), [Gnss_Ephemeris::delta_n](#), [delta_OMEGAdot](#), [Gnss_Ephemeris::dtr](#), [Gnss_Ephemeris::ecc](#), [Gnss_Ephemeris::i_0](#), [Gnss_Ephemeris::idot](#), [integrity_status_flag](#), [Gnss_Ephemeris::M_0](#), [Gnss_Ephemeris::omega](#), [Gnss_Ephemeris::OMEGA_0](#), [Gnss_Ephemeris::OMEGAdot](#), [Gnss_Ephemeris::PRN](#), [Gnss_Ephemeris::satClkDrift](#), [Gnss_Ephemeris::sqrtA](#), [TGD](#), [Gnss_Ephemeris::toc](#), [Gnss_Ephemeris::toe](#), [toe1](#), [toe2](#), [Gnss_Ephemeris::tow](#), and [Gnss_Ephemeris::WN](#).

12.195.4 Member Data Documentation

12.195.4.1 Adot

```
double Gps_CNAV_Ephemeris::Adot {}
```

Change rate in semi-major axis.

Definition at line 49 of file [gps_cnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.195.4.2 alert_flag

```
bool Gps_CNAV_Ephemeris::alert_flag {}
```

If true, indicates that the SV URA may be worse than indicated in d_SV_accuracy, use that SV at our own risk.

Definition at line 84 of file [gps_cnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.195.4.3 antispoofing_flag

```
bool Gps_CNAV_Ephemeris::antispoofing_flag {}
```

If true, the AntiSpoofing mode is ON in that SV.

Definition at line 85 of file [gps_cnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.195.4.4 delta_A

```
double Gps_CNAV_Ephemeris::delta_A {}
```

Semi-major axis difference at reference time.

Definition at line 48 of file [gps_cnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.195.4.5 delta_ndot

```
double Gps_CNAV_Ephemeris::delta_ndot {}
```

Rate of mean motion difference from computed value.

Definition at line 50 of file [gps_cnav_ephemeris.h](#).

12.195.4.6 delta_OMEGAdot

```
double Gps_CNAV_Ephemeris::delta_OMEGAdot {}
```

Rate of Right Ascension difference [semi-circles/s].

Definition at line 51 of file [gps_cnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.195.4.7 integrity_status_flag

```
bool Gps_CNAV_Ephemeris::integrity_status_flag {}
```

If true, enhanced level of integrity assurance.

If false, indicates that the conveying signal is provided with the legacy level of integrity assurance. That is, the probability that the instantaneous URE of the conveying signal exceeds 4.42 times the upper bound value of the current broadcast URA index, for more than 5.2 seconds, without an accompanying alert, is less than 1E-5 per hour.

If true, indicates that the conveying signal is provided with an enhanced level of integrity assurance. That is, the probability that the instantaneous URE of the conveying signal exceeds 5.73 times the upper bound value of the current broadcast URA index, for more than 5.2 seconds, without an accompanying alert, is less than 1E-8 per hour.

Definition at line 82 of file [gps_cnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.195.4.8 ISCL1

```
double Gps_CNAV_Ephemeris::ISCL1 {}
```

Definition at line 64 of file [gps_cnav_ephemeris.h](#).

12.195.4.9 ISCL2

```
double Gps_CNAV_Ephemeris::ISCL2 {}
```

Definition at line 65 of file [gps_cnav_ephemeris.h](#).

12.195.4.10 ISCL5I

```
double Gps_CNAV_Ephemeris::ISCL5I {}
```

Definition at line 66 of file [gps_cnav_ephemeris.h](#).

12.195.4.11 ISCL5Q

```
double Gps_CNAV_Ephemeris::ISCL5Q {}
```

Definition at line 67 of file [gps_cnav_ephemeris.h](#).

12.195.4.12 l2c_phasing_flag

```
bool Gps_CNAV_Ephemeris::l2c_phasing_flag {}
```

Definition at line 83 of file [gps_cnav_ephemeris.h](#).

12.195.4.13 signal_health

```
int32_t Gps_CNAV_Ephemeris::signal_health {}
```

Signal health (L1/L2/L5)

Definition at line 54 of file [gps_cnav_ephemeris.h](#).

12.195.4.14 TGD

```
double Gps_CNAV_Ephemeris::TGD {}
```

Estimated Group Delay Differential: L1-L2 correction term only for the benefit of "L1 P(Y)" or "L2 P(Y)" s users [s].

Definition at line 63 of file [gps_cnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.195.4.15 toe1

```
int32_t Gps_CNAV_Ephemeris::toe1 {}
```

Ephemeris data reference time of week (Ref. 20.3.3.4.3 IS-GPS-200M) [s].

Definition at line 52 of file [gps_cnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.195.4.16 toe2

```
int32_t Gps_CNAV_Ephemeris::toe2 {}
```

Ephemeris data reference time of week (Ref. 20.3.3.4.3 IS-GPS-200M) [s].

Definition at line 53 of file [gps_cnav_ephemeris.h](#).

Referenced by [serialize\(\)](#).

12.195.4.17 top

```
int32_t Gps_CNAV_Ephemeris::top {}
```

Data predict time of week.

Definition at line 55 of file [gps_cnav_ephemeris.h](#).

12.195.4.18 URA

```
int32_t Gps_CNAV_Ephemeris::URA {}
```

ED Accuracy Index.

Definition at line 56 of file [gps_cnav_ephemeris.h](#).

12.195.4.19 URA0

```
double Gps_CNAV_Ephemeris::URA0 {}
```

NED Accuracy Index.

Definition at line 58 of file [gps_cnav_ephemeris.h](#).

12.195.4.20 URA1

```
double Gps_CNAV_Ephemeris::URA1 {}
```

NED Accuracy Change Index.

Definition at line 59 of file [gps_cnav_ephemeris.h](#).

12.195.4.21 URA2

```
double Gps_CNAV_Ephemeris::URA2 {}
```

NED Accuracy Change Rate Index.

Definition at line 60 of file [gps_cnav_ephemeris.h](#).

The documentation for this class was generated from the following file:

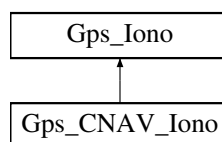
- [gps_cnav_ephemeris.h](#)

12.196 Gps_CNAV_Iono Class Reference

This class is a storage for the GPS IONOSPHERIC data as described in IS-GPS-200M.

```
#include <gps_cnav_iono.h>
```

Inheritance diagram for Gps_CNAV_Iono:

**Public Member Functions**

- [Gps_CNAV_Iono\(\)](#)=default

Default constructor.

Public Member Functions inherited from Gps_Iono

- `Gps_Iono()` = default
Default constructor.
- `template<class Archive>`
`void serialize` (Archive &archive, const unsigned int version)
Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Additional Inherited Members

Public Attributes inherited from Gps_Iono

- `double alpha0` {}
Coefficient 0 of a cubic equation representing the amplitude of the vertical delay [s].
- `double alpha1` {}
Coefficient 1 of a cubic equation representing the amplitude of the vertical delay [s/semi-circle].
- `double alpha2` {}
Coefficient 2 of a cubic equation representing the amplitude of the vertical delay [s(semi-circle)²].
- `double alpha3` {}
Coefficient 3 of a cubic equation representing the amplitude of the vertical delay [s(semi-circle)³].
- `double beta0` {}
Coefficient 0 of a cubic equation representing the period of the model [s].
- `double beta1` {}
Coefficient 1 of a cubic equation representing the period of the model [s/semi-circle].
- `double beta2` {}
Coefficient 2 of a cubic equation representing the period of the model [s(semi-circle)²].
- `double beta3` {}
Coefficient 3 of a cubic equation representing the period of the model [s(semi-circle)³].
- `bool valid` {}
Valid flag.

12.196.1 Detailed Description

This class is a storage for the GPS IONOSPHERIC data as described in IS-GPS-200M.

See <https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf> Appendix III
Definition at line 34 of file [gps_cnav_iono.h](#).

12.196.2 Constructor & Destructor Documentation

12.196.2.1 Gps_CNAV_Iono()

```
Gps_CNAV_Iono::Gps_CNAV_Iono () [default]
```

Default constructor.

The documentation for this class was generated from the following file:

- [gps_cnav_iono.h](#)

12.197 Gps_CNAV_Navigation_Message Class Reference

This class decodes a GPS CNAV Data message as described in IS-GPS-200M.

```
#include <gps_cnav_navigation_message.h>
```

Public Member Functions

- [Gps_CNAV_Navigation_Message](#) (CnavSystem system=CnavSystem::GPS)
- void **decode_page** (const std::bitset< GPS_CNAV_DATA_PAGE_BITS > &data_bits)
- [Gps_CNAV_Ephemeris](#) **get_ephemeris** () const
Obtain a GPS SV Ephemeris class filled with current SV data.
- bool **have_new_iono** ()
Check if we have a new iono record stored in the GPS ephemeris class.
- [Gps_CNAV_Iono](#) **get_iono** () const
Obtain a GPS ionospheric correction parameters class filled with current SV data.
- [Gps_CNAV_Utc_Model](#) **get_utc_model** ()
Obtain a GPS UTC model parameters class filled with current SV data.
- bool **have_new_utc_model** ()
- bool **have_new_ephemeris** ()
Check if we have a new ephemeris stored in the GPS ephemeris class.

12.197.1 Detailed Description

This class decodes a GPS CNAV Data message as described in IS-GPS-200M.

See <https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf> Appendix III Definition at line 50 of file [gps_cnav_navigation_message.h](#).

12.197.2 Constructor & Destructor Documentation

12.197.2.1 Gps_CNAV_Navigation_Message()

```
Gps_CNAV_Navigation_Message::Gps_CNAV_Navigation_Message (
    CnavSystem system = CnavSystem::GPS) [explicit]
```

Default constructor

12.197.3 Member Function Documentation

12.197.3.1 get_ephemeris()

```
Gps\_CNAV\_Ephemeris Gps_CNAV_Navigation_Message::get_ephemeris () const
```

Obtain a GPS SV Ephemeris class filled with current SV data.

12.197.3.2 get_iono()

```
Gps\_CNAV\_Iono Gps_CNAV_Navigation_Message::get_iono () const
```

Obtain a GPS ionospheric correction parameters class filled with current SV data.

12.197.3.3 get_utc_model()

```
Gps\_CNAV\_Utc\_Model Gps_CNAV_Navigation_Message::get_utc_model ()
```

Obtain a GPS UTC model parameters class filled with current SV data.

12.197.3.4 have_new_ephemeris()

```
bool Gps_CNAV_Navigation_Message::have_new_ephemeris ()
```

Check if we have a new ephemeris stored in the GPS ephemeris class.

12.197.3.5 have_new_iono()

```
bool Gps_CNAV_Navigation_Message::have_new_iono ()
```

Check if we have a new iono record stored in the GPS ephemeris class.

12.197.3.6 have_new_utc_model()

```
bool Gps_CNAV_Navigation_Message::have_new_utc_model ()
```

\brief Check if we have a new GPS UTC model record stored in the GPS ephemeris class

The documentation for this class was generated from the following file:

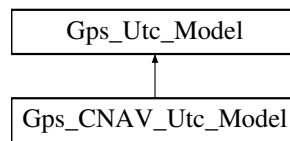
- [gps_cnav_navigation_message.h](#)

12.198 Gps_CNAV_Utc_Model Class Reference

This class is a storage for the GPS UTC MODEL data as described in in IS-GPS-200M.

```
#include <gps_cnav_utc_model.h>
```

Inheritance diagram for Gps_CNAV_Utc_Model:



Public Member Functions

- [Gps_CNAV_Utc_Model](#) ()=default

Default constructor.

Public Member Functions inherited from [Gps_Utc_Model](#)

- [Gps_Utc_Model](#) ()=default
- `template<class Archive>`
void [serialize](#) (Archive &archive, const uint32_t version)

Additional Inherited Members

Public Attributes inherited from [Gps_Utc_Model](#)

- double [A0](#) {}
Constant of a model that relates GPS and UTC time (ref. 20.3.3.5.2.4 IS-GPS-200M) [s].
- double [A1](#) {}
1st order term of a model that relates GPS and UTC time (ref. 20.3.3.5.2.4 IS-GPS-200M) [s/s]
- double [A2](#) {}
2nd order term of a model that relates GPS and UTC time (ref. 20.3.3.5.2.4 IS-GPS-200M) [s/s]
- int32_t [tot](#) {}
Reference time for UTC data (reference 20.3.4.5 and 20.3.3.5.2.4 IS-GPS-200M) [s].
- int32_t [WN_T](#) {}
UTC reference week number [weeks].
- int32_t [DeltaT_LS](#) {}
Delta time due to leap seconds [s]. Number of leap seconds since 6-Jan-1980 as transmitted by the GPS almanac.
- int32_t [WN_LSF](#) {}
Week number at the end of which the leap second becomes effective [weeks].
- int32_t [DN](#) {}
Day number (DN) at the end of which the leap second becomes effective [days].
- int32_t [DeltaT_LSF](#) {}
Scheduled future or recent past (relative to NAV message upload) value of the delta time due to leap seconds [s].
- bool [valid](#) {}

12.198.1 Detailed Description

This class is a storage for the GPS UTC MODEL data as described in in IS-GPS-200M.

See <https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf> Appendix III Definition at line 34 of file [gps_cnav_utc_model.h](#).

12.198.2 Constructor & Destructor Documentation

12.198.2.1 Gps_CNAV_Utc_Model()

```
Gps_CNAV_Utc_Model::Gps_CNAV_Utc_Model () [default]
```

Default constructor.

The documentation for this class was generated from the following file:

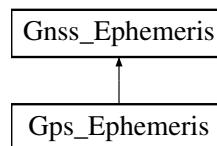
- [gps_cnav_utc_model.h](#)

12.199 Gps_Ephemeris Class Reference

This class is a storage and orbital model functions for the GPS SV ephemeris data as described in IS-GPS-200M.

```
#include <gps_ephemeris.h>
```

Inheritance diagram for Gps_Ephemeris:



Public Member Functions

- [Gps_Ephemeris](#) ()
- `template<class Archive>`
void [serialize](#) (Archive &archive, const uint32_t version)

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Public Member Functions inherited from [Gnss_Ephemeris](#)

- double [sv_clock_drift](#) (double transmitTime)
Sets (satClkDrift) and (dtr), and returns the clock drift in seconds according to the User Algorithm for SV Clock Correction (IS-GPS-200M, 20.3.3.3.3.1, and Galileo OS SIS ICD, 5.1.4).
- double [predicted_doppler](#) (double rx_time_s, double lat, double lon, double h, double ve, double vn, double vu, int band) const
Computes prediction of the Doppler shift for a given time and receiver's position and velocity.
- void [satellitePosition](#) (double transmitTime)
Computes the ECEF SV coordinates and ECEF velocity.

Public Attributes

- int32_t [code_on_L2](#) {}
If 1, P code ON in L2; if 2, C/A code ON in L2;.
- bool [L2_P_data_flag](#) {}
When true, indicates that the NAV data stream was commanded OFF on the P-code of the L2 channel.
- int32_t [SV_accuracy](#) {}
User Range Accuracy (URA) index of the SV (reference paragraph 6.2.1) for the standard positioning service user (Ref 20.3.3.3.1.3 IS-GPS-200M)

- `int32_t SV_health {}`
Satellite health status.
- `double TGD {}`
Estimated Group Delay Differential: L1-L2 correction term only for the benefit of "L1 P(Y)" or "L2 P(Y)" s users [s].
- `int32_t IODC {}`
Issue of Data, Clock.
- `int32_t IODE_SF2 {}`
Issue of Data, Ephemeris (IODE), subframe 2.
- `int32_t IODE_SF3 {}`
Issue of Data, Ephemeris (IODE), subframe 3.
- `int32_t AODO {}`
Age of Data Offset (AODO) term for the navigation message correction table (NMCT) contained in subframe 4 (reference paragraph 20.3.3.5.1.9) [s].
- `bool fit_interval_flag {}`
indicates the curve-fit interval used by the CS (Block II/IIA/IIR/IIR-M/IIF) and SS (Block IIIA) in determining the ephemeris parameters, as follows: 0 = 4 hours, 1 = greater than 4 hours.
- `double spare1 {}`
- `double spare2 {}`
- `bool integrity_status_flag {}`
If true, enhanced level of integrity assurance.
- `bool alert_flag {}`
If true, indicates that the SV URA may be worse than indicated in d_SV_accuracy, use that SV at our own risk.
- `bool antispoofing_flag {}`
If true, the AntiSpoofing mode is ON in that SV.
- `std::map< int, std::string > satelliteBlock`
Map that stores to which block the PRN belongs <https://www.navcen.uscg.gov/?Do=constellation&Status>.

Public Attributes inherited from Gnss_Ephemeris

- `uint32_t PRN {}`
SV ID.
- `double M_0 {}`
Mean anomaly at reference time [rad].
- `double delta_n {}`
Mean motion difference from computed value [rad/sec].
- `double ecc {}`
Eccentricity.
- `double sqrtA {}`
Square root of the semi-major axis [meters^{1/2}].
- `double OMEGA_0 {}`
Longitude of ascending node of orbital plane at weekly epoch [rad].
- `double i_0 {}`
Inclination angle at reference time [rad].
- `double omega {}`
Argument of perigee [rad].
- `double OMEGAdot {}`
Rate of right ascension [rad/sec].
- `double idot {}`
Rate of inclination angle [rad/sec].
- `double Cuc {}`
Amplitude of the cosine harmonic correction term to the argument of latitude [rad].

- double [Cus](#) {}
Amplitude of the sine harmonic correction term to the argument of latitude [rad].
- double [Crc](#) {}
Amplitude of the cosine harmonic correction term to the orbit radius [meters].
- double [Crs](#) {}
Amplitude of the sine harmonic correction term to the orbit radius [meters].
- double [Cic](#) {}
Amplitude of the cosine harmonic correction term to the angle of inclination [rad].
- double [Cis](#) {}
Amplitude of the sine harmonic correction term to the angle of inclination [rad].
- int32_t [toe](#) {}
Ephemeris reference time [s].
- int32_t [toc](#) {}
Clock correction data reference Time of Week [sec].
- double [af0](#) {}
SV clock bias correction coefficient [s].
- double [af1](#) {}
SV clock drift correction coefficient [s/s].
- double [af2](#) {}
SV clock drift rate correction coefficient [s/s²].
- double [satClkDrift](#) {}
SV clock drift.
- double [dtr](#) {}
Relativistic clock correction term.
- int32_t [WN](#) {}
Week number.
- int32_t [tow](#) {}
Time of Week.
- double [satpos_X](#) {}
Earth-fixed coordinate x of the satellite [m]. Intersection of the IERS Reference Meridian (IRM) and the plane passing through the origin and normal to the Z-axis.
- double [satpos_Y](#) {}
Earth-fixed coordinate y of the satellite [m]. Completes a right-handed, Earth-Centered, Earth-Fixed orthogonal coordinate system.
- double [satpos_Z](#) {}
Earth-fixed coordinate z of the satellite [m]. The direction of the IERS (International Earth Rotation and Reference Systems Service) Reference Pole (IRP).
- double [satvel_X](#) {}
Earth-fixed velocity coordinate x of the satellite [m].
- double [satvel_Y](#) {}
Earth-fixed velocity coordinate y of the satellite [m].
- double [satvel_Z](#) {}
Earth-fixed velocity coordinate z of the satellite [m].

Additional Inherited Members

Protected Attributes inherited from [Gnss_Ephemeris](#)

- char [System](#) {}
Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou.

12.199.1 Detailed Description

This class is a storage and orbital model functions for the GPS SV ephemeris data as described in IS-GPS-200M. See <https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf> Appendix II Definition at line 40 of file [gps_ephemeris.h](#).

12.199.2 Constructor & Destructor Documentation

12.199.2.1 Gps_Ephemeris()

```
Gps_Ephemeris::Gps_Ephemeris ()
```

Default constructor

12.199.3 Member Function Documentation

12.199.3.1 serialize()

```
template<class Archive>
void Gps_Ephemeris::serialize (
    Archive & archive,
    const uint32_t version) [inline]
```

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Definition at line 86 of file [gps_ephemeris.h](#).

References [Gnss_Ephemeris::af0](#), [Gnss_Ephemeris::af1](#), [Gnss_Ephemeris::af2](#), [alert_flag](#), [antispoofing_flag](#), [AODO](#), [Gnss_Ephemeris::Cic](#), [Gnss_Ephemeris::Cis](#), [code_on_L2](#), [Gnss_Ephemeris::Crc](#), [Gnss_Ephemeris::Crs](#), [Gnss_Ephemeris::Cuc](#), [Gnss_Ephemeris::Cus](#), [Gnss_Ephemeris::delta_n](#), [Gnss_Ephemeris::dtr](#), [Gnss_Ephemeris::ecc](#), [fit_interval_flag](#), [Gnss_Ephemeris::i_0](#), [Gnss_Ephemeris::idot](#), [integrity_status_flag](#), [IODC](#), [IODE_SF2](#), [IODE_SF3](#), [L2_P_data_flag](#), [Gnss_Ephemeris::M_0](#), [Gnss_Ephemeris::omega](#), [Gnss_Ephemeris::OMEGA_0](#), [Gnss_Ephemeris::OMEGAdot](#), [Gnss_Ephemeris::PRN](#), [Gnss_Ephemeris::satClkDrift](#), [Gnss_Ephemeris::sqrtA](#), [SV_accuracy](#), [SV_health](#), [TGD](#), [Gnss_Ephemeris::toc](#), [Gnss_Ephemeris::toe](#), [Gnss_Ephemeris::tow](#), and [Gnss_Ephemeris::WN](#).

12.199.4 Member Data Documentation

12.199.4.1 alert_flag

```
bool Gps_Ephemeris::alert_flag {}
```

If true, indicates that the SV URA may be worse than indicated in `d_SV_accuracy`, use that SV at our own risk.

Definition at line 75 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.199.4.2 antispoofing_flag

```
bool Gps_Ephemeris::antispoofing_flag {}
```

If true, the AntiSpoofing mode is ON in that SV.

Definition at line 76 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.199.4.3 AODO

```
int32_t Gps_Ephemeris::AODO {}
```

Age of Data Offset (AODO) term for the navigation message correction table (NMCT) contained in subframe 4 (reference paragraph 20.3.3.5.1.9) [s].

Definition at line 56 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.199.4.4 code_on_L2

```
int32_t Gps_Ephemeris::code_on_L2 {}
```

If 1, P code ON in L2; if 2, C/A code ON in L2;

Definition at line 48 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.199.4.5 fit_interval_flag

```
bool Gps_Ephemeris::fit_interval_flag {}
```

indicates the curve-fit interval used by the CS (Block II/IIA/IIR/IIR-M/IIF) and SS (Block IIIA) in determining the ephemeris parameters, as follows: 0 = 4 hours, 1 = greater than 4 hours.

Definition at line 58 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.199.4.6 integrity_status_flag

```
bool Gps_Ephemeris::integrity_status_flag {}
```

If true, enhanced level of integrity assurance.

If false, indicates that the conveying signal is provided with the legacy level of integrity assurance. That is, the probability that the instantaneous URE of the conveying signal exceeds 4.42 times the upper bound value of the current broadcast URA index, for more than 5.2 seconds, without an accompanying alert, is less than 1E-5 per hour.

If true, indicates that the conveying signal is provided with an enhanced level of integrity assurance. That is, the probability that the instantaneous URE of the conveying signal exceeds 5.73 times the upper bound value of the current broadcast URA index, for more than 5.2 seconds, without an accompanying alert, is less than 1E-8 per hour.

Definition at line 74 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.199.4.7 IODC

```
int32_t Gps_Ephemeris::IODC {}
```

Issue of Data, Clock.

Definition at line 53 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.199.4.8 IODE_SF2

```
int32_t Gps_Ephemeris::IODC_SF2 {}
```

Issue of Data, Ephemeris (IODC), subframe 2.

Definition at line 54 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.199.4.9 IODE_SF3

```
int32_t Gps_Ephemeris::IODC_SF3 {}
```

Issue of Data, Ephemeris (IODC), subframe 3.

Definition at line 55 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.199.4.10 L2_P_data_flag

```
bool Gps_Ephemeris::L2_P_data_flag {}
```

When true, indicates that the NAV data stream was commanded OFF on the P-code of the L2 channel.

Definition at line 49 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.199.4.11 satelliteBlock

```
std::map<int, std::string> Gps_Ephemeris::satelliteBlock
```

Map that stores to which block the PRN belongs <https://www.navcen.uscg.gov/?Do=constellation&Status>.

Definition at line 78 of file [gps_ephemeris.h](#).

12.199.4.12 spare1

```
double Gps_Ephemeris::spare1 {}
```

Definition at line 59 of file [gps_ephemeris.h](#).

12.199.4.13 spare2

```
double Gps_Ephemeris::spare2 {}
```

Definition at line 60 of file [gps_ephemeris.h](#).

12.199.4.14 SV_accuracy

```
int32_t Gps_Ephemeris::SV_accuracy {}
```

User Range Accuracy (URA) index of the SV (reference paragraph 6.2.1) for the standard positioning service user (Ref 20.3.3.3.1.3 IS-GPS-200M)

Definition at line 50 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.199.4.15 SV_health

```
int32_t Gps_Ephemeris::SV_health {}
```

Satellite health status.

Definition at line 51 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

12.199.4.16 TGD

```
double Gps_Ephemeris::TGD {}
```

Estimated Group Delay Differential: L1-L2 correction term only for the benefit of "L1 P(Y)" or "L2 P(Y)" s users [s].

Definition at line 52 of file [gps_ephemeris.h](#).

Referenced by [Serdes_Gps_Eph::readProtobuffer\(\)](#), and [serialize\(\)](#).

The documentation for this class was generated from the following file:

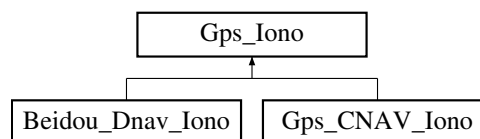
- [gps_ephemeris.h](#)

12.200 Gps_Iono Class Reference

This class is a storage for the GPS IONOSPHERIC data as described in IS-GPS-200M.

```
#include <gps_iono.h>
```

Inheritance diagram for Gps_Iono:

**Public Member Functions**

- [Gps_Iono](#) ()=default

Default constructor.

- `template<class Archive>`

`void serialize (Archive &archive, const unsigned int version)`

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Public Attributes

- double [alpha0](#) {}
Coefficient 0 of a cubic equation representing the amplitude of the vertical delay [s].
- double [alpha1](#) {}
Coefficient 1 of a cubic equation representing the amplitude of the vertical delay [s/semi-circle].
- double [alpha2](#) {}
Coefficient 2 of a cubic equation representing the amplitude of the vertical delay [s(semi-circle)^2].
- double [alpha3](#) {}
Coefficient 3 of a cubic equation representing the amplitude of the vertical delay [s(semi-circle)^3].
- double [beta0](#) {}
Coefficient 0 of a cubic equation representing the period of the model [s].
- double [beta1](#) {}
Coefficient 1 of a cubic equation representing the period of the model [s/semi-circle].
- double [beta2](#) {}
Coefficient 2 of a cubic equation representing the period of the model [s(semi-circle)^2].
- double [beta3](#) {}
Coefficient 3 of a cubic equation representing the period of the model [s(semi-circle)^3].
- bool [valid](#) {}
Valid flag.

12.200.1 Detailed Description

This class is a storage for the GPS IONOSPHERIC data as described in IS-GPS-200M.

See <https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf> Appendix II

Definition at line 35 of file [gps_iono.h](#).

12.200.2 Constructor & Destructor Documentation

12.200.2.1 Gps_Iono()

```
Gps_Iono::Gps_Iono () [default]
```

Default constructor.

12.200.3 Member Function Documentation

12.200.3.1 serialize()

```
template<class Archive>
void Gps_Iono::serialize (
    Archive & archive,
    const unsigned int version) [inline]
```

Serialize is a boost standard method to be called by the boost XML serialization. Here is used to save the ephemeris data on disk file.

Definition at line 58 of file [gps_iono.h](#).

References [alpha0](#), [alpha1](#), [alpha2](#), [alpha3](#), [beta0](#), [beta1](#), [beta2](#), and [beta3](#).

12.200.4 Member Data Documentation

12.200.4.1 alpha0

```
double Gps_Iono::alpha0 {}
```

Coefficient 0 of a cubic equation representing the amplitude of the vertical delay [s].

Definition at line 41 of file [gps_iono.h](#).

Referenced by [serialize\(\)](#).

12.200.4.2 alpha1

```
double Gps_Iono::alpha1 {}
```

Coefficient 1 of a cubic equation representing the amplitude of the vertical delay [s/semi-circle].

Definition at line 42 of file [gps_iono.h](#).

Referenced by [serialize\(\)](#).

12.200.4.3 alpha2

```
double Gps_Iono::alpha2 {}
```

Coefficient 2 of a cubic equation representing the amplitude of the vertical delay [s(semi-circle)²].

Definition at line 43 of file [gps_iono.h](#).

Referenced by [serialize\(\)](#).

12.200.4.4 alpha3

```
double Gps_Iono::alpha3 {}
```

Coefficient 3 of a cubic equation representing the amplitude of the vertical delay [s(semi-circle)³].

Definition at line 44 of file [gps_iono.h](#).

Referenced by [serialize\(\)](#).

12.200.4.5 beta0

```
double Gps_Iono::beta0 {}
```

Coefficient 0 of a cubic equation representing the period of the model [s].

Definition at line 45 of file [gps_iono.h](#).

Referenced by [serialize\(\)](#).

12.200.4.6 beta1

```
double Gps_Iono::beta1 {}
```

Coefficient 1 of a cubic equation representing the period of the model [s/semi-circle].

Definition at line 46 of file [gps_iono.h](#).

Referenced by [serialize\(\)](#).

12.200.4.7 beta2

```
double Gps_Iono::beta2 {}
```

Coefficient 2 of a cubic equation representing the period of the model [s(semi-circle)²].

Definition at line 47 of file [gps_iono.h](#).

Referenced by [serialize\(\)](#).

12.200.4.8 beta3

```
double Gps_Iono::beta3 {}
```

Coefficient 3 of a cubic equation representing the period of the model [s(semi-circle)³].

Definition at line 48 of file [gps_iono.h](#).

Referenced by [serialize\(\)](#).

12.200.4.9 valid

```
bool Gps_Iono::valid {}
```

Valid flag.

Definition at line 50 of file [gps_iono.h](#).

The documentation for this class was generated from the following file:

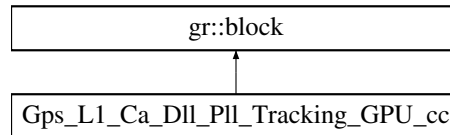
- [gps_iono.h](#)

12.201 Gps_L1_Ca_DLL_Pll_Tracking_GPU_cc Class Reference

This class implements a DLL + PLL tracking loop block.

```
#include <gps_l1_ca_dll_pll_tracking_gpu_cc.h>
```

Inheritance diagram for Gps_L1_Ca_DLL_Pll_Tracking_GPU_cc:



Public Member Functions

- void **set_channel** (uint32_t channel)
- void **set_gnss_synchro** ([Gnss_Synchro](#) *p_gnss_synchro)
- void **start_tracking** ()
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)
- void **forecast** (int noutput_items, gr_vector_int &ninput_items_required)

Friends

- [gps_l1_ca_dll_pll_tracking_gpu_cc_sptr](#) **gps_l1_ca_dll_pll_make_tracking_gpu_cc** (int64_t fs_in, uint32_t vector_length, bool dump, std::string dump_filename, float pll_bw_hz, float dll_bw_hz, float early_↵late_space_chips)

12.201.1 Detailed Description

This class implements a DLL + PLL tracking loop block.

Definition at line 60 of file [gps_l1_ca_dll_pll_tracking_gpu_cc.h](#).

The documentation for this class was generated from the following file:

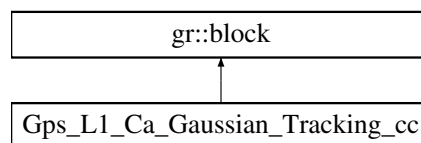
- [gps_l1_ca_dll_pll_tracking_gpu_cc.h](#)

12.202 Gps_L1_Ca_Gaussian_Tracking_cc Class Reference

This class implements a DLL + PLL tracking loop block.

```
#include <gps_l1_ca_gaussian_tracking_cc.h>
```

Inheritance diagram for Gps_L1_Ca_Gaussian_Tracking_cc:



Public Member Functions

- void **set_channel** (uint32_t channel)
- void **set_gnss_synchro** ([Gnss_Synchro](#) *p_gnss_synchro)
- void **start_tracking** ()
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)
- void **forecast** (int noutput_items, gr_vector_int &ninput_items_required)

Friends

- `gps_l1_ca_gaussian_tracking_cc_sptr` **gps_l1_ca_gaussian_make_tracking_cc** (uint32_t order, int64_t fs_in, uint32_t vector_length, bool dump, const std::string &dump_filename, float dll_bw_hz, float early_late_space_chips, bool bce_run, uint32_t bce_pttrans, uint32_t bce_strans, int32_t bce_nu, int32_t bce_kappa)

12.202.1 Detailed Description

This class implements a DLL + PLL tracking loop block.

Definition at line 74 of file [gps_l1_ca_gaussian_tracking_cc.h](#).

The documentation for this class was generated from the following file:

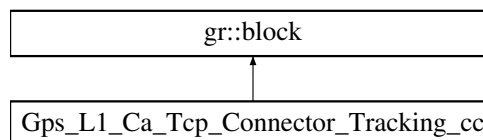
- [gps_l1_ca_gaussian_tracking_cc.h](#)

12.203 Gps_L1_Ca_Tcp_Connector_Tracking_cc Class Reference

This class implements a DLL + PLL tracking loop block.

#include <gps_l1_ca_tcp_connector_tracking_cc.h>

Inheritance diagram for Gps_L1_Ca_Tcp_Connector_Tracking_cc:

**Public Member Functions**

- void **set_channel** (uint32_t channel)
- void **set_gnss_synchro** ([Gnss_Synchro](#) *p_gnss_synchro)
- void **start_tracking** ()
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)
- void **forecast** (int noutput_items, gr_vector_int &ninput_items_required)

Friends

- `gps_l1_ca_tcp_connector_tracking_cc_sptr` **gps_l1_ca_tcp_connector_make_tracking_cc** (int64_t fs_in, uint32_t vector_length, bool dump, const std::string &dump_filename, float early_late_space_chips, size_t port_ch0)

12.203.1 Detailed Description

This class implements a DLL + PLL tracking loop block.

Definition at line 58 of file [gps_l1_ca_tcp_connector_tracking_cc.h](#).

The documentation for this class was generated from the following file:

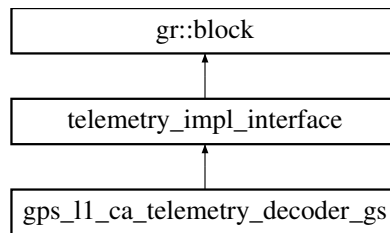
- [gps_l1_ca_tcp_connector_tracking_cc.h](#)

12.204 gps_l1_ca_telemetry_decoder_gs Class Reference

This class implements a block that decodes the NAV data defined in IS-GPS-200M.

#include <gps_l1_ca_telemetry_decoder_gs.h>

Inheritance diagram for gps_l1_ca_telemetry_decoder_gs:



Public Member Functions

- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
Set satellite PRN.
- void [set_channel](#) (int channel) override
Set receiver's channel.
- void [reset](#) () override
- int [general_work](#) (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
This is where all signal processing takes place.

Public Member Functions inherited from [telemetry_impl_interface](#)

- [telemetry_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)

Friends

- [gps_l1_ca_telemetry_decoder_gs_sptr](#) [gps_l1_ca_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf, L1LnavSystem system=L1LnavSystem::GPS)

Additional Inherited Members

Protected Member Functions inherited from [telemetry_impl_interface](#)

- void [configure_basic_outputs](#) ()
- void [configure_dump_file](#) (int32_t channel, bool enable_dump, std::string &dump_filename, std::ofstream &dump_file) const
- void [configure_crc_stats_channel](#) (int32_t channel, bool &dump_crc_stats, std::unique_ptr< [Tlm_CRC_Stats](#) > &crc_stats) const

12.204.1 Detailed Description

This class implements a block that decodes the NAV data defined in IS-GPS-200M.
Definition at line 58 of file [gps_l1_ca_telemetry_decoder_gs.h](#).

12.204.2 Member Function Documentation

12.204.2.1 [general_work\(\)](#)

```

int gps_l1_ca_telemetry_decoder_gs::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]

```

This is where all signal processing takes place.

12.204.2.2 reset()

void gps_l1_ca_telemetry_decoder_gs::reset () [override], [virtual]
 Implements [telemetry_impl_interface](#).

12.204.2.3 set_channel()

void gps_l1_ca_telemetry_decoder_gs::set_channel (
 int channel) [override], [virtual]

Set receiver's channel.

Implements [telemetry_impl_interface](#).

12.204.2.4 set_satellite()

void gps_l1_ca_telemetry_decoder_gs::set_satellite (
 const [Gnss_Satellite](#) & satellite) [override], [virtual]

Set satellite PRN.

Implements [telemetry_impl_interface](#).

The documentation for this class was generated from the following file:

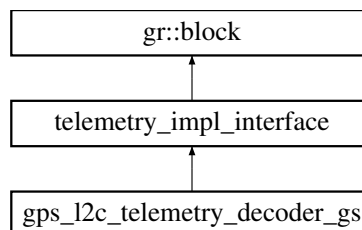
- [gps_l1_ca_telemetry_decoder_gs.h](#)

12.205 gps_l2c_telemetry_decoder_gs Class Reference

This class implements a block that decodes CNAV data defined in IS-GPS-200M.

```
#include <gps_l2c_telemetry_decoder_gs.h>
```

Inheritance diagram for `gps_l2c_telemetry_decoder_gs`:



Public Member Functions

- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
Set satellite PRN.
- void [set_channel](#) (int32_t channel) override
Set receiver's channel.
- void [reset](#) () override
- int [general_work](#) (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
This is where all signal processing takes place.

Public Member Functions inherited from [telemetry_impl_interface](#)

- [telemetry_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_channel](#) (int channel)=0

Friends

- `gps_l2c_telemetry_decoder_gs_sptr` [gps_l2c_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, const [Tim_Conf](#) &conf)

Additional Inherited Members

Protected Member Functions inherited from [telemetry_impl_interface](#)

- void **configure_basic_outputs** ()
- void **configure_dump_file** (int32_t channel, bool enable_dump, std::string &dump_filename, std::ofstream &dump_file) const
- void **configure_crc_stats_channel** (int32_t channel, bool &dump_crc_stats, std::unique_ptr< [Tlm_CRC_Stats](#) > &crc_stats) const

12.205.1 Detailed Description

This class implements a block that decodes CNAV data defined in IS-GPS-200M.

Definition at line 49 of file [gps_l2c_telemetry_decoder_gs.h](#).

12.205.2 Member Function Documentation

12.205.2.1 general_work()

```
int gps_l2c_telemetry_decoder_gs::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

This is where all signal processing takes place.

12.205.2.2 reset()

```
void gps_l2c_telemetry_decoder_gs::reset () [override], [virtual]
```

Implements [telemetry_impl_interface](#).

12.205.2.3 set_channel()

```
void gps_l2c_telemetry_decoder_gs::set_channel (
    int32_t channel) [override]
```

Set receiver's channel.

12.205.2.4 set_satellite()

```
void gps_l2c_telemetry_decoder_gs::set_satellite (
    const Gnss\_Satellite & satellite) [override], [virtual]
```

Set satellite PRN.

Implements [telemetry_impl_interface](#).

The documentation for this class was generated from the following file:

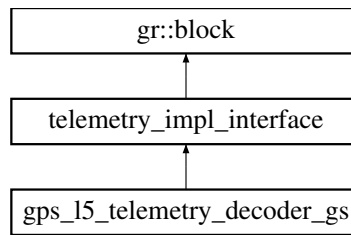
- [gps_l2c_telemetry_decoder_gs.h](#)

12.206 gps_l5_telemetry_decoder_gs Class Reference

This class implements a GPS L5 Telemetry decoder.

```
#include <gps_l5_telemetry_decoder_gs.h>
```

Inheritance diagram for [gps_l5_telemetry_decoder_gs](#):



Public Member Functions

- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
Set satellite PRN.
- void [set_channel](#) (int32_t channel) override
Set receiver's channel.
- void [reset](#) () override
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override

Public Member Functions inherited from [telemetry_impl_interface](#)

- [telemetry_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_channel](#) (int channel)=0

Friends

- [gps_l5_telemetry_decoder_gs_sptr](#) **gps_l5_make_telemetry_decoder_gs** (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf, CnavSystem system=CnavSystem::GPS)

Additional Inherited Members

Protected Member Functions inherited from [telemetry_impl_interface](#)

- void **configure_basic_outputs** ()
- void **configure_dump_file** (int32_t channel, bool enable_dump, std::string &dump_filename, std::ofstream &dump_file) const
- void **configure_crc_stats_channel** (int32_t channel, bool &dump_crc_stats, std::unique_ptr< [Tlm_CRC_Stats](#) > &crc_stats) const

12.206.1 Detailed Description

This class implements a GPS L5 Telemetry decoder.
Definition at line 53 of file [gps_l5_telemetry_decoder_gs.h](#).

12.206.2 Member Function Documentation

12.206.2.1 reset()

void [gps_l5_telemetry_decoder_gs::reset](#) () [override], [virtual]
Implements [telemetry_impl_interface](#).

12.206.2.2 set_channel()

void [gps_l5_telemetry_decoder_gs::set_channel](#) (
 int32_t channel) [override]
Set receiver's channel.

12.206.2.3 set_satellite()

```
void gps_l5_telemetry_decoder_gs::set_satellite (
    const Gnss_Satellite & satellite) [override], [virtual]
```

Set satellite PRN.

Implements [telemetry_impl_interface](#).

The documentation for this class was generated from the following file:

- [gps_l5_telemetry_decoder_gs.h](#)

12.207 Gps_Navigation_Message Class Reference

This class decodes a GPS NAV Data message as described in IS-GPS-200M.

```
#include <gps_navigation_message.h>
```

Public Member Functions

- [Gps_Navigation_Message](#) (LnavSystem system=LnavSystem::GPS)
- [Gps_Ephemeris get_ephemeris](#) () const
Obtain a GPS SV Ephemeris class filled with current SV data.
- [Gps_Iono get_iono](#) ()
Obtain a GPS ionospheric correction parameters class filled with current SV data.
- [Gps_Almanac get_almanac](#) ()
Obtain a GPS almanac class filled with current SV data.
- [Gps_Utc_Model get_utc_model](#) ()
Obtain a GPS Almanac model parameters class filled with current SV data.
- [int32_t subframe_decoder](#) (const char *subframe)
Decodes the GPS NAV message.
- [double utc_time](#) (double gpstime_corrected) const
Computes the Coordinated Universal Time (UTC) and returns it in [s] (IS-GPS-200M, 20.3.3.5.2.4)
- [int32_t get_TOW](#) () const
Gets Time of Week, in seconds.
- [int32_t get_GPS_week](#) () const
Gets GPS Week Number.
- [void set_satellite_PRN](#) (uint32_t prn)
Sets satellite PRN number.
- [uint32_t get_satellite_PRN](#) () const
Gets satellite PRN number.
- [void set_channel](#) (int32_t channel_id)
Sets channel ID.
- [bool get_flag_iono_valid](#) () const
Gets flag_iono_valid.
- [bool get_flag_utc_model_valid](#) () const
Gets flag_utc_model_valid.
- [bool satellite_validation](#) ()
- [bool almanac_validation](#) () const

12.207.1 Detailed Description

This class decodes a GPS NAV Data message as described in IS-GPS-200M.

See <https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf> Appendix II Definition at line 51 of file [gps_navigation_message.h](#).

12.207.2 Constructor & Destructor Documentation

12.207.2.1 Gps_Navigation_Message()

```
Gps_Navigation_Message::Gps_Navigation_Message (
    LnavSystem system = LnavSystem::GPS) [explicit]
```

Default constructor

12.207.3 Member Function Documentation

12.207.3.1 get_almanac()

```
Gps_Almanac Gps_Navigation_Message::get_almanac ()
```

Obtain a GPS almanac class filled with current SV data.

12.207.3.2 get_ephemeris()

```
Gps_Ephemeris Gps_Navigation_Message::get_ephemeris () const
```

Obtain a GPS SV Ephemeris class filled with current SV data.

12.207.3.3 get_flag_iono_valid()

```
bool Gps_Navigation_Message::get_flag_iono_valid () const [inline]
```

Gets flag_iono_valid.

Definition at line 133 of file [gps_navigation_message.h](#).

12.207.3.4 get_flag_utc_model_valid()

```
bool Gps_Navigation_Message::get_flag_utc_model_valid () const [inline]
```

Gets flag_utc_model_valid.

Definition at line 141 of file [gps_navigation_message.h](#).

12.207.3.5 get_GPS_week()

```
int32_t Gps_Navigation_Message::get_GPS_week () const [inline]
```

Gets GPS Week Number.

Definition at line 101 of file [gps_navigation_message.h](#).

12.207.3.6 get_iono()

```
Gps_Iono Gps_Navigation_Message::get_iono ()
```

Obtain a GPS ionospheric correction parameters class filled with current SV data.

12.207.3.7 get_satellite_PRN()

```
uint32_t Gps_Navigation_Message::get_satellite_PRN () const [inline]
```

Gets satellite PRN number.

Definition at line 117 of file [gps_navigation_message.h](#).

12.207.3.8 get_TOW()

```
int32_t Gps_Navigation_Message::get_TOW () const [inline]
```

Gets Time of Week, in seconds.

Definition at line 93 of file [gps_navigation_message.h](#).

12.207.3.9 get_utc_model()

```
Gps_Utc_Model Gps_Navigation_Message::get_utc_model ()
```

Obtain a GPS Almanac model parameters class filled with current SV data.

12.207.3.10 set_channel()

```
void Gps_Navigation_Message::set_channel (
    int32_t channel_id) [inline]
```

Sets channel ID.

Definition at line 125 of file [gps_navigation_message.h](#).

12.207.3.11 set_satellite_PRN()

```
void Gps_Navigation_Message::set_satellite_PRN (
    uint32_t prn) [inline]
```

Sets satellite PRN number.

Definition at line 109 of file [gps_navigation_message.h](#).

12.207.3.12 subframe_decoder()

```
int32_t Gps_Navigation_Message::subframe_decoder (
    const char * subframe)
```

Decodes the GPS NAV message.

12.207.3.13 utc_time()

```
double Gps_Navigation_Message::utc_time (
    double gpstime_corrected) const
```

Computes the Coordinated Universal Time (UTC) and returns it in [s] (IS-GPS-200M, 20.3.3.5.2.4)

The documentation for this class was generated from the following file:

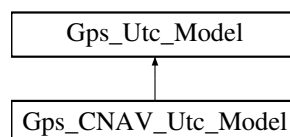
- [gps_navigation_message.h](#)

12.208 Gps_Utc_Model Class Reference

This class is a storage for the GPS UTC MODEL data as described in IS-GPS-200M.

```
#include <gps_utc_model.h>
```

Inheritance diagram for Gps_Utc_Model:

**Public Member Functions**

- [Gps_Utc_Model](#) ()=default
- `template<class Archive>`
void [serialize](#) (Archive &archive, const uint32_t version)

Public Attributes

- double [A0](#) {}
Constant of a model that relates GPS and UTC time (ref. 20.3.3.5.2.4 IS-GPS-200M) [s].
- double [A1](#) {}
1st order term of a model that relates GPS and UTC time (ref. 20.3.3.5.2.4 IS-GPS-200M) [s/s]
- double [A2](#) {}
2nd order term of a model that relates GPS and UTC time (ref. 20.3.3.5.2.4 IS-GPS-200M) [s/s]
- int32_t [tot](#) {}
Reference time for UTC data (reference 20.3.4.5 and 20.3.3.5.2.4 IS-GPS-200M) [s].

- int32_t [WN_T](#) {}
UTC reference week number [weeks].
- int32_t [DeltaT_LS](#) {}
Delta time due to leap seconds [s]. Number of leap seconds since 6-Jan-1980 as transmitted by the GPS almanac.
- int32_t [WN_LSF](#) {}
Week number at the end of which the leap second becomes effective [weeks].
- int32_t [DN](#) {}
Day number (DN) at the end of which the leap second becomes effective [days].
- int32_t [DeltaT_LSF](#) {}
Scheduled future or recent past (relative to NAV message upload) value of the delta time due to leap seconds [s].
- bool [valid](#) {}

12.208.1 Detailed Description

This class is a storage for the GPS UTC MODEL data as described in IS-GPS-200M.

See <https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf> Appendix II Definition at line 35 of file [gps_utc_model.h](#).

12.208.2 Constructor & Destructor Documentation

12.208.2.1 Gps_Utc_Model()

```
Gps_Utc_Model::Gps_Utc_Model () [default]
```

Default constructor

12.208.3 Member Function Documentation

12.208.3.1 serialize()

```
template<class Archive>
void Gps_Utc_Model::serialize (
    Archive & archive,
    const uint32_t version) [inline]
```

Definition at line 61 of file [gps_utc_model.h](#).

12.208.4 Member Data Documentation

12.208.4.1 A0

```
double Gps_Utc_Model::A0 {}
```

Constant of a model that relates GPS and UTC time (ref. 20.3.3.5.2.4 IS-GPS-200M) [s].

Definition at line 44 of file [gps_utc_model.h](#).

12.208.4.2 A1

```
double Gps_Utc_Model::A1 {}
```

1st order term of a model that relates GPS and UTC time (ref. 20.3.3.5.2.4 IS-GPS-200M) [s/s]

Definition at line 45 of file [gps_utc_model.h](#).

12.208.4.3 A2

```
double Gps_Utc_Model::A2 {}
```

2nd order term of a model that relates GPS and UTC time (ref. 20.3.3.5.2.4 IS-GPS-200M) [s/s]

Definition at line 46 of file [gps_utc_model.h](#).

12.208.4.4 DeltaT_LS

```
int32_t Gps_Utc_Model::DeltaT_LS {}
```

Delta time due to leap seconds [s]. Number of leap seconds since 6-Jan-1980 as transmitted by the GPS almanac.

Definition at line 49 of file [gps_utc_model.h](#).

12.208.4.5 DeltaT_LSF

```
int32_t Gps_Utc_Model::DeltaT_LSF {}
```

Scheduled future or recent past (relative to NAV message upload) value of the delta time due to leap seconds [s].

Definition at line 52 of file [gps_utc_model.h](#).

12.208.4.6 DN

```
int32_t Gps_Utc_Model::DN {}
```

Day number (DN) at the end of which the leap second becomes effective [days].

Definition at line 51 of file [gps_utc_model.h](#).

12.208.4.7 tot

```
int32_t Gps_Utc_Model::tot {}
```

Reference time for UTC data (reference 20.3.4.5 and 20.3.3.5.2.4 IS-GPS-200M) [s].

Definition at line 47 of file [gps_utc_model.h](#).

12.208.4.8 valid

```
bool Gps_Utc_Model::valid {}
```

Definition at line 54 of file [gps_utc_model.h](#).

12.208.4.9 WN_LSF

```
int32_t Gps_Utc_Model::WN_LSF {}
```

Week number at the end of which the leap second becomes effective [weeks].

Definition at line 50 of file [gps_utc_model.h](#).

12.208.4.10 WN_T

```
int32_t Gps_Utc_Model::WN_T {}
```

UTC reference week number [weeks].

Definition at line 48 of file [gps_utc_model.h](#).

The documentation for this class was generated from the following file:

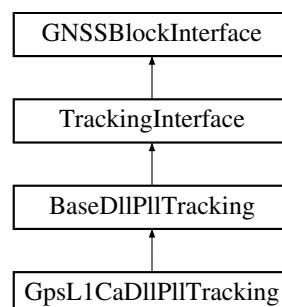
- [gps_utc_model.h](#)

12.209 GpsL1CaDllPllTracking Class Reference

This class implements a code DLL + carrier PLL tracking loop block adapter for GPS L1 C/A signals.

```
#include <gps_l1_ca_dll_pll_tracking.h>
```

Inheritance diagram for GpsL1CaDllPllTracking:



Public Member Functions

- [GpsL1CaDIIPIITracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "GPS_L1_CA_DLL_PLL_Tracking".

Public Member Functions inherited from [BaseDIIPIITracking](#)

- [BaseDIIPIITracking](#) (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDIIPIITracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override final
Get left block from the Tracking block adapter.
- gr::basic_block_sptr [get_right_block](#) () override final
Get right block from the Tracking block adapter.
- void [set_channel](#) (unsigned int channel) override final
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final
Start the Tracking block.
- void [stop_tracking](#) () override final
Stop the Tracking block.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BaseDIIPIITracking](#)

- [DII_PII_Conf](#) & [config_params](#) ()
- const [DII_PII_Conf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t item_size)

Protected Attributes inherited from [BaseDIIPIITracking](#)

- dll_pll_veml_tracking_sptr [tracking_sptr_](#)

12.209.1 Detailed Description

This class implements a code DLL + carrier PLL tracking loop block adapter for GPS L1 C/A signals.
Definition at line 41 of file [gps_l1_ca_dll_pll_tracking.h](#).

12.209.2 Constructor & Destructor Documentation

12.209.2.1 GpsL1CaDllPllTracking()

```
GpsL1CaDllPllTracking::GpsL1CaDllPllTracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDIPIITracking::role\(\)](#).

12.209.3 Member Function Documentation

12.209.3.1 implementation()

```
std::string GpsL1CaDllPllTracking::implementation () [inline], [override], [virtual]
```

Returns "GPS_L1_CA_DLL_PLL_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 51 of file [gps_l1_ca_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

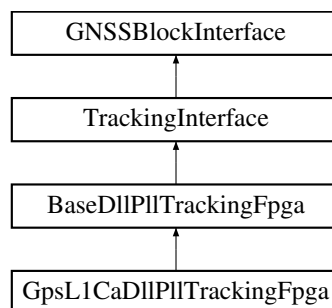
- [gps_l1_ca_dll_pll_tracking.h](#)

12.210 GpsL1CaDIPIITrackingFpga Class Reference

Adapter for a GPS L1 C/A DLL+PLL tracking loop for FPGA.

```
#include <gps_l1_ca_dll_pll_tracking_fpga.h>
```

Inheritance diagram for GpsL1CaDIPIITrackingFpga:



Public Member Functions

- **GpsL1CaDIPIITrackingFpga** (const [ConfigurationInterface](#) *configuration, const std::string &[role](#), unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GPS_L1_CA_DLL_PLL_Tracking_FPGA".

Public Member Functions inherited from [BaseDIPIITrackingFpga](#)

- [BaseDIPIITrackingFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &[role](#), unsigned int in_streams, unsigned int out_streams)
Base constructor of FPGA-based Tracking block adapters.

- virtual `~BaseDllPllTrackingFpga()` = default
Base destructor of FPGA-based Tracking block adapters.
- `std::string role()` override
Get role from the Tracking block adapter.
- `size_t item_size()` override
Get item_size from the Tracking block adapter.
- `void connect(gr::top_block_sptr top_block)` override
Connect the Tracking block adapter.
- `void disconnect(gr::top_block_sptr top_block)` override
Disconnect the Tracking block adapter.
- `gr::basic_block_sptr get_left_block()` override
Get left block from the Tracking block adapter.
- `gr::basic_block_sptr get_right_block()` override
Get right block from the Tracking block adapter.
- `void start_tracking()` override
Start the tracking process in the FPGA.
- `void stop_tracking()` override
Stop the tracking process in the FPGA.
- `void configure_fpga_tracking_channel_mapping(std::string signal)`
configure FPGA tracking channel mapping
- `void set_channel(unsigned int channel)` override
Set tracking channel unique ID.
- `void set_gnss_synchro(Gnss_Synchro *p_gnss_synchro)` override
Set acquisition/tracking common Gnss_Synchro object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

Public Member Functions inherited from GNSSBlockInterface

- virtual `gr::basic_block_sptr get_left_block(int RF_channel)`
- virtual `gr::basic_block_sptr get_right_block(int RF_channel)`
- virtual `void start()`
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from BaseDllPllTrackingFpga

- `Dll_Pll_Conf_Fpga & config_params_fpga()`
- `const Dll_Pll_Conf_Fpga & config_params_fpga() const`

Protected Attributes inherited from BaseDllPllTrackingFpga

- `dll_pll_veml_tracking_fpga_sptr tracking_fpga_sc_sptr_`

Static Protected Attributes inherited from BaseDllPllTrackingFpga

- `static const int32_t LOCAL_CODE_FPGA_ENABLE_WRITE_MEMORY = 0x0C000000`
- `static const int32_t LOCAL_CODE_FPGA_CORRELATOR_SELECT_COUNT = 0x20000000`

12.210.1 Detailed Description

Adapter for a GPS L1 C/A DLL+PLL tracking loop for FPGA.
Definition at line 39 of file `gps_l1_ca_dll_pll_tracking_fpga.h`.

12.210.2 Member Function Documentation

12.210.2.1 implementation()

`std::string GpsL1CaDllPllTrackingFpga::implementation () [inline], [override], [virtual]`

Returns "GPS_L1_CA_DLL_PLL_Tracking_FPGA".

Implements [GNSSBlockInterface](#).

Definition at line 52 of file [gps_l1_ca_dll_pll_tracking_fpga.h](#).

The documentation for this class was generated from the following file:

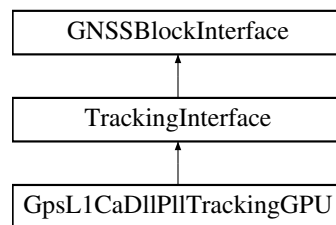
- [gps_l1_ca_dll_pll_tracking_fpga.h](#)

12.211 GpsL1CaDllPllTrackingGPU Class Reference

This class implements a code DLL + carrier PLL tracking loop using GPU accelerated functions.

`#include <gps_l1_ca_dll_pll_tracking_gpu.h>`

Inheritance diagram for GpsL1CaDllPllTrackingGPU:



Public Member Functions

- **GpsL1CaDllPllTrackingGPU** (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override

Returns "GPS_L1_CA_DLL_PLL_Tracking_GPU".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_channel](#) (unsigned int channel) override

Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override
- void [stop_tracking](#) () override

Stop running tracking.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.211.1 Detailed Description

This class implements a code DLL + carrier PLL tracking loop using GPU accelerated functions.
Definition at line 41 of file [gps_l1_ca_dll_pll_tracking_gpu.h](#).

12.211.2 Member Function Documentation

12.211.2.1 connect()

```
void GpsL1CaDllPllTrackingGPU::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.211.2.2 disconnect()

```
void GpsL1CaDllPllTrackingGPU::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.211.2.3 get_left_block()

```
gr::basic_block_sptr GpsL1CaDllPllTrackingGPU::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.211.2.4 get_right_block()

```
gr::basic_block_sptr GpsL1CaDllPllTrackingGPU::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.211.2.5 implementation()

```
std::string GpsL1CaDllPllTrackingGPU::implementation () [inline], [override], [virtual]
```

Returns "GPS_L1_CA_DLL_PLL_Tracking_GPU".
Implements [GNSSBlockInterface](#).
Definition at line 58 of file [gps_l1_ca_dll_pll_tracking_gpu.h](#).

12.211.2.6 item_size()

```
size_t GpsL1CaDllPllTrackingGPU::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).
Definition at line 63 of file [gps_l1_ca_dll_pll_tracking_gpu.h](#).

12.211.2.7 role()

```
std::string GpsL1CaDllPllTrackingGPU::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).
Definition at line 52 of file [gps_l1_ca_dll_pll_tracking_gpu.h](#).

12.211.2.8 set_channel()

```
void GpsL1CaDllPllTrackingGPU::set_channel (
    unsigned int channel) [override], [virtual]
```

Set tracking channel unique ID.
Implements [TrackingInterface](#).

12.211.2.9 set_gnss_synchro()

```
void GpsL1CaDllPllTrackingGPU::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

Implements [TrackingInterface](#).

12.211.2.10 start_tracking()

```
void GpsL1CaDllPllTrackingGPU::start_tracking () [override], [virtual]
```

Implements [TrackingInterface](#).

12.211.2.11 stop_tracking()

```
void GpsL1CaDllPllTrackingGPU::stop_tracking () [override], [virtual]
```

Stop running tracking.

Implements [TrackingInterface](#).

The documentation for this class was generated from the following file:

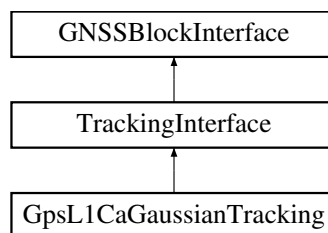
- [gps_l1_ca_dll_pll_tracking_gpu.h](#)

12.212 GpsL1CaGaussianTracking Class Reference

This class implements a code DLL + carrier PLL tracking loop.

```
#include <gps_l1_ca_gaussian_tracking.h>
```

Inheritance diagram for GpsL1CaGaussianTracking:



Public Member Functions

- **GpsL1CaGaussianTracking** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override

Returns "GPS_L1_CA_Gaussian_Tracking".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_channel](#) (unsigned int channel) override

Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override
- void [stop_tracking](#) () override

Stop running tracking.

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.212.1 Detailed Description

This class implements a code DLL + carrier PLL tracking loop.
Definition at line 44 of file [gps_l1_ca_gaussian_tracking.h](#).

12.212.2 Member Function Documentation

12.212.2.1 connect()

```
void GpsL1CaGaussianTracking::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.212.2.2 disconnect()

```
void GpsL1CaGaussianTracking::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.212.2.3 get_left_block()

```
gr::basic_block_sptr GpsL1CaGaussianTracking::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.212.2.4 get_right_block()

```
gr::basic_block_sptr GpsL1CaGaussianTracking::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.212.2.5 implementation()

```
std::string GpsL1CaGaussianTracking::implementation () [inline], [override], [virtual]
```

Returns "GPS_L1_CA_Gaussian_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 61 of file [gps_l1_ca_gaussian_tracking.h](#).

12.212.2.6 item_size()

```
size_t GpsL1CaGaussianTracking::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 66 of file [gps_l1_ca_gaussian_tracking.h](#).

12.212.2.7 role()

```
std::string GpsL1CaGaussianTracking::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 55 of file [gps_l1_ca_gaussian_tracking.h](#).

12.212.2.8 set_channel()

```
void GpsL1CaGaussianTracking::set_channel (
    unsigned int channel) [override], [virtual]
```

Set tracking channel unique ID.

Implements [TrackingInterface](#).

12.212.2.9 set_gnss_synchro()

```
void GpsL1CaGaussianTracking::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

Implements [TrackingInterface](#).

12.212.2.10 start_tracking()

```
void GpsL1CaGaussianTracking::start_tracking () [override], [virtual]
```

Implements [TrackingInterface](#).

12.212.2.11 stop_tracking()

```
void GpsL1CaGaussianTracking::stop_tracking () [override], [virtual]
```

Stop running tracking.

Implements [TrackingInterface](#).

The documentation for this class was generated from the following file:

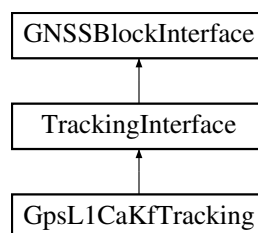
- [gps_l1_ca_gaussian_tracking.h](#)

12.213 GpsL1CaKfTracking Class Reference

This class implements a code + carrier Kalman Filter tracking loop with VTL capabilities.

```
#include <gps_l1_ca_kf_tracking.h>
```

Inheritance diagram for GpsL1CaKfTracking:

**Public Member Functions**

- **GpsL1CaKfTracking** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override
Returns "GPS_L1_CA_KF_Tracking".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_channel](#) (unsigned int channel) override
Set tracking channel unique ID.

- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override
- void [stop_tracking](#) () override
Stop running tracking.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

12.213.1 Detailed Description

This class implements a code + carrier Kalman Filter tracking loop with VTL capabilities.
Definition at line 36 of file [gps_l1_ca_kf_tracking.h](#).

12.213.2 Member Function Documentation

12.213.2.1 connect()

```
void GpsL1CaKfTracking::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.213.2.2 disconnect()

```
void GpsL1CaKfTracking::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.213.2.3 get_left_block()

```
gr::basic_block_sptr GpsL1CaKfTracking::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.213.2.4 get_right_block()

```
gr::basic_block_sptr GpsL1CaKfTracking::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.213.2.5 implementation()

```
std::string GpsL1CaKfTracking::implementation () [inline], [override], [virtual]
```

Returns "GPS_L1_CA_KF_Tracking".
Implements [GNSSBlockInterface](#).
Definition at line 53 of file [gps_l1_ca_kf_tracking.h](#).

12.213.2.6 item_size()

```
size_t GpsL1CaKfTracking::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).
Definition at line 58 of file [gps_l1_ca_kf_tracking.h](#).

12.213.2.7 role()

std::string GpsL1CaKfTracking::role () [inline], [override], [virtual]

Implements [GNSSBlockInterface](#).

Definition at line 47 of file [gps_l1_ca_kf_tracking.h](#).

12.213.2.8 set_channel()

void GpsL1CaKfTracking::set_channel (
 unsigned int channel) [override], [virtual]

Set tracking channel unique ID.

Implements [TrackingInterface](#).

12.213.2.9 set_gnss_synchro()

void GpsL1CaKfTracking::set_gnss_synchro (
 Gnss_Synchro * p_gnss_synchro) [override], [virtual]

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

Implements [TrackingInterface](#).

12.213.2.10 start_tracking()

void GpsL1CaKfTracking::start_tracking () [override], [virtual]

Implements [TrackingInterface](#).

12.213.2.11 stop_tracking()

void GpsL1CaKfTracking::stop_tracking () [override], [virtual]

Stop running tracking.

Implements [TrackingInterface](#).

The documentation for this class was generated from the following file:

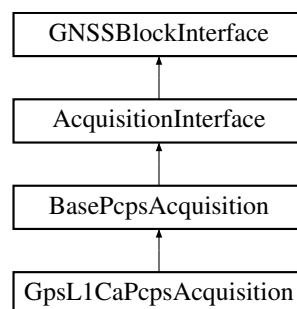
- [gps_l1_ca_kf_tracking.h](#)

12.214 GpsL1CaPcpsAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

#include <gps_l1_ca_pcps_acquisition.h>

Inheritance diagram for GpsL1CaPcpsAcquisition:



Public Member Functions

- **GpsL1CaPcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GPS_L1_CA_PCPS_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override

Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override

Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int doppler_center) override

Set Doppler center for the grid search.
- signed int [mag](#) () override

Returns the maximum peak of grid search.
- void [reset](#) () override

Restart acquisition algorithm.
- void [stop_acquisition](#) () override

Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t latency_samples) override

Sets the resampler latency to account it in the acquisition code delay estimation.
- void [set_local_code](#) () override

Sets local code.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.214.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

Definition at line 38 of file [gps_l1_ca_pcps_acquisition.h](#).

12.214.2 Member Function Documentation

12.214.2.1 [implementation\(\)](#)

```
std::string GpsL1CaPcpsAcquisition::implementation () [inline], [override], [virtual]
```

Returns "GPS_L1_CA_PCPS_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 52 of file [gps_l1_ca_pcps_acquisition.h](#).

The documentation for this class was generated from the following file:

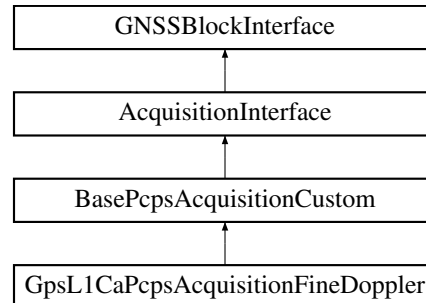
- [gps_l1_ca_pcps_acquisition.h](#)

12.215 GpsL1CaPcpsAcquisitionFineDoppler Class Reference

This class Adapts a PCPS acquisition block with fine Doppler estimation to an [AcquisitionInterface](#) for GPS L1 C/A signals.

```
#include <gps_l1_ca_pcps_acquisition_fine_doppler.h>
```

Inheritance diagram for GpsL1CaPcpsAcquisitionFineDoppler:



Public Member Functions

- **GpsL1CaPcpsAcquisitionFineDoppler** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GPS_L1_CA_PCPS_Acquisition_Fine_Doppler".

Public Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- **BasePcpsAcquisitionCustom** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double code_length_chips, unsigned int ms_per_code, bool use_stream_to_vector, const [ThresholdComputeInterface](#) &threshold_compute, uint32_t max_sampled_ms=std::numeric_limits< uint32_t >::max())
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t) override
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_doppler_center](#) (int)

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- bool [is_type_gr_complex](#) () const

Protected Attributes inherited from [BasePcpsAcquisitionCustom](#)

- const [Acq_Conf](#) [acq_parameters_](#)
- acquisition_impl_interface_sptr [acquisition_cc_](#)
- [Gnss_Synchro](#) * [gnss_synchro_](#)
- unsigned int [channel_](#)
- volk_gnss_sdr::vector< std::complex< float > > [code_](#)

12.215.1 Detailed Description

This class Adapts a PCPS acquisition block with fine Doppler estimation to an [AcquisitionInterface](#) for GPS L1 C/A signals.

Definition at line 35 of file [gps_l1_ca_pcps_acquisition_fine_doppler.h](#).

12.215.2 Member Function Documentation

12.215.2.1 implementation()

```
std::string GpsL1CaPcpsAcquisitionFineDoppler::implementation () [inline], [override], [virtual]
```

Returns "GPS_L1_CA_PCPS_Acquisition_Fine_Doppler".

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [gps_l1_ca_pcps_acquisition_fine_doppler.h](#).

The documentation for this class was generated from the following file:

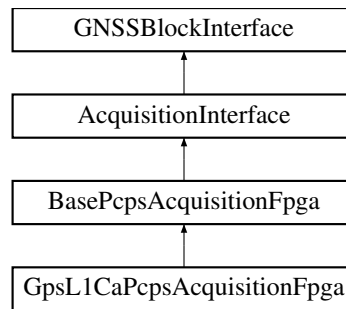
- [gps_l1_ca_pcps_acquisition_fine_doppler.h](#)

12.216 GpsL1CaPcpsAcquisitionFpga Class Reference

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for GPS L1 C/A signals.

```
#include <gps_l1_ca_pcps_acquisition_fpga.h>
```

Inheritance diagram for GpsL1CaPcpsAcquisitionFpga:



Public Member Functions

- **GpsL1CaPcpsAcquisitionFpga** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "GPS_L1_CA_PCPS_Acquisition_FPGA".

Public Member Functions inherited from [BasePcpsAcquisitionFpga](#)

- **BasePcpsAcquisitionFpga** (const [ConfigurationInterface](#) *configuration, std::string role, double code_rate_cps, double code_length_chips, uint32_t opt_acq_fs_sps, uint32_t default_fpga_blk_exp, uint32_t acq_buff, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override final
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- signed int [mag](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
- void [set_channel](#) (unsigned int channel) override
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
- void [set_doppler_center](#) (int doppler_center) override
- void [reset](#) () override
- void [stop_acquisition](#) () override
- void [set_resampler_latency](#) (uint32_t latency_samples __attribute__((unused))) override
- void [set_local_code](#) () override

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_resampler_latency](#) (uint32_t latency_samples)=0

Public Member Functions inherited from [GnssBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionFpga](#)

- void [init](#) ()

Protected Attributes inherited from [BasePcpsAcquisitionFpga](#)

- `volk_gnssdr::vector< uint32_t > d_all_fft_codes_`
- `Acq_Conf_Fpga acq_parameters_`

Static Protected Attributes inherited from [BasePcpsAcquisitionFpga](#)

- `static const uint32_t QUANT_BITS_LOCAL_CODE = 16`
- `static const uint32_t SELECT_LSBITS = 0x0000FFFF`
- `static const uint32_t SELECT_MSBITS = 0xFFFF0000`
- `static const uint32_t SELECT_ALL_CODE_BITS = 0xFFFFFFFF`
- `static const uint32_t SHL_CODE_BITS = 65536`
- `static const uint32_t ACQ_BUFF_0 = 0`
- `static const uint32_t ACQ_BUFF_1 = 1`

12.216.1 Detailed Description

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for GPS L1 C/A signals.

Definition at line 35 of file [gps_l1_ca_pcps_acquisition_fpga.h](#).

12.216.2 Constructor & Destructor Documentation

12.216.2.1 GpsL1CaPcpsAcquisitionFpga()

```
GpsL1CaPcpsAcquisitionFpga::GpsL1CaPcpsAcquisitionFpga (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

12.216.3 Member Function Documentation

12.216.3.1 implementation()

```
std::string GpsL1CaPcpsAcquisitionFpga::implementation () [inline], [override], [virtual]
```

Returns "GPS_L1_CA_PCPS_Acquisition_FPGA".

Implements [GNSSBlockInterface](#).

Definition at line 49 of file [gps_l1_ca_pcps_acquisition_fpga.h](#).

The documentation for this class was generated from the following file:

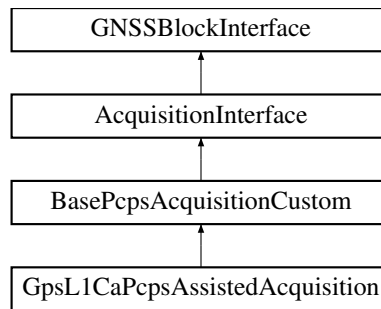
- [gps_l1_ca_pcps_acquisition_fpga.h](#)

12.217 GpsL1CaPcpsAssistedAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

```
#include <gps_l1_ca_pcps_assisted_acquisition.h>
```

Inheritance diagram for GpsL1CaPcpsAssistedAcquisition:



Public Member Functions

- **GpsL1CaPcpsAssistedAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GPS_L1_CA_PCPS_Assisted_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- **BasePcpsAcquisitionCustom** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double code_length_chips, unsigned int ms_per_code, bool use_stream_to_vector, const [ThresholdComputeInterface](#) &threshold_compute, uint32_t max_sampled_ms=std::numeric_limits< uint32_t >::max())
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t) override
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_doppler_center](#) (int)

Public Member Functions inherited from [GnssBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- bool [is_type_gr_complex](#) () const

Protected Attributes inherited from [BasePcpsAcquisitionCustom](#)

- const [Acq_Conf](#) [acq_parameters_](#)
- acquisition_impl_interface_sptr [acquisition_cc_](#)
- [Gnss_Synchro](#) * [gnss_synchro_](#)
- unsigned int [channel_](#)
- [volk_gnssssdr::vector< std::complex< float > >](#) [code_](#)

12.217.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.
Definition at line 35 of file [gps_l1_ca_pcps_assisted_acquisition.h](#).

12.217.2 Member Function Documentation

12.217.2.1 implementation()

```
std::string GpsL1CaPcpsAssistedAcquisition::implementation () [inline], [override], [virtual]
```

Returns "GPS_L1_CA_PCPS_Assisted_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 49 of file [gps_l1_ca_pcps_assisted_acquisition.h](#).

The documentation for this class was generated from the following file:

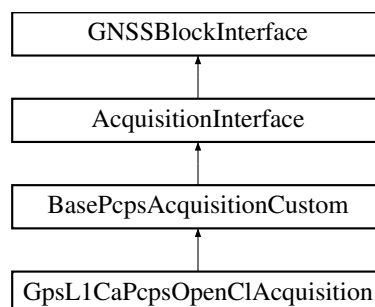
- [gps_l1_ca_pcps_assisted_acquisition.h](#)

12.218 GpsL1CaPcpsOpenCIAcquisition Class Reference

This class adapts an OpenCL PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

```
#include <gps_l1_ca_pcps_openc1_acquisition.h>
```

Inheritance diagram for GpsL1CaPcpsOpenCIAcquisition:



Public Member Functions

- **GpsL1CaPcpsOpenCIAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GPS_L1_CA_PCPS_OpenCL_Acquisition".
- bool [openc1_ready](#) () const

Public Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- **BasePcpsAcquisitionCustom** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double code_length_chips, unsigned int ms_per_code, bool use_stream_to_vector, const [ThresholdComputeInterface](#) &threshold_compute, uint32_t max_sampled_ms=std::numeric_limits< uint32_t >::max())
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override

Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override

Set channel fsm associated to this acquisition instance.
- signed int [mag](#) () override

Returns the maximum peak of grid search.
- void [reset](#) () override

Restart acquisition algorithm.
- void [stop_acquisition](#) () override

Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t) override
- void [set_local_code](#) () override

Sets local code.

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_doppler_center](#) (int)

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- bool [is_type_gr_complex](#) () const

Protected Attributes inherited from [BasePcpsAcquisitionCustom](#)

- const [Acq_Conf](#) [acq_parameters_](#)
- acquisition_impl_interface_sptr [acquisition_cc_](#)
- [Gnss_Synchro](#) * [gnss_synchro_](#)
- unsigned int [channel_](#)
- volk_gnss_sdr::vector< std::complex< float > > [code_](#)

12.218.1 Detailed Description

This class adapts an OpenCL PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.
Definition at line 32 of file [gps_l1_ca_pcps_openc1_acquisition.h](#).

12.218.2 Member Function Documentation

12.218.2.1 implementation()

```
std::string GpsL1CaPcpsOpenClAcquisition::implementation () [inline], [override], [virtual]
```

Returns "GPS_L1_CA_PCPS_OpenCl_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 45 of file [gps_l1_ca_pcps_openc1_acquisition.h](#).

12.218.2.2 openc1_ready()

```
bool GpsL1CaPcpsOpenClAcquisition::openc1_ready () const [inline]
```

Definition at line 50 of file [gps_l1_ca_pcps_openc1_acquisition.h](#).

The documentation for this class was generated from the following file:

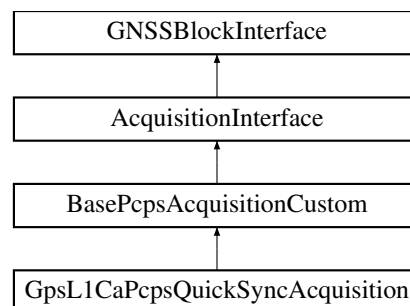
- [gps_l1_ca_pcps_openc1_acquisition.h](#)

12.219 GpsL1CaPcpsQuickSyncAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

```
#include <gps_l1_ca_pcps_quicksync_acquisition.h>
```

Inheritance diagram for GpsL1CaPcpsQuickSyncAcquisition:



Public Member Functions

- **GpsL1CaPcpsQuickSyncAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GPS_L1_CA_PCPS_QuickSync_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- **BasePcpsAcquisitionCustom** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double code_length_chips, unsigned int ms_per_code, bool use_stream_to_vector, const [ThresholdComputeInterface](#) &threshold_compute, uint32_t max_sampled_ms=std::numeric_limits< uint32_t >::max())
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t) override
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_doppler_center](#) (int)

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- bool [is_type_gr_complex](#) () const

Protected Attributes inherited from [BasePcpsAcquisitionCustom](#)

- const [Acq_Conf](#) [acq_parameters_](#)
- acquisition_impl_interface_sptr [acquisition_cc_](#)
- [Gnss_Synchro](#) * [gnss_synchro_](#)
- unsigned int [channel_](#)
- volk_gnssdr::vector< std::complex< float > > [code_](#)

12.219.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.
Definition at line 33 of file [gps_l1_ca_pcps_quicksync_acquisition.h](#).

12.219.2 Member Function Documentation

12.219.2.1 implementation()

`std::string GpsL1CaPcpsQuickSyncAcquisition::implementation () [inline], [override], [virtual]`
Returns "GPS_L1_CA_PCPS_QuickSync_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 47 of file [gps_l1_ca_pcps_quicksync_acquisition.h](#).

The documentation for this class was generated from the following file:

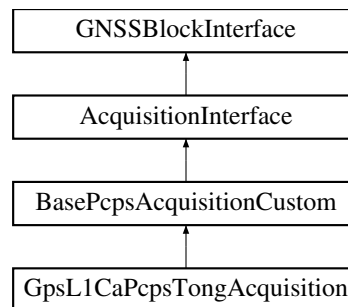
- [gps_l1_ca_pcps_quicksync_acquisition.h](#)

12.220 GpsL1CaPcpsTongAcquisition Class Reference

This class adapts a PCPS Tong acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

```
#include <gps_l1_ca_pcps_tong_acquisition.h>
```

Inheritance diagram for GpsL1CaPcpsTongAcquisition:



Public Member Functions

- **GpsL1CaPcpsTongAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GPS_L1_CA_PCPS_Tong_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisitionCustom](#)

- **BasePcpsAcquisitionCustom** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double code_length_chips, unsigned int ms_per_code, bool use_stream_to_vector, const [ThresholdComputeInterface](#) &threshold_compute, uint32_t max_sampled_ms=std::numeric_limits< uint32_t >::max())
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t) override
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_doppler_center](#) (int)

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from BasePcpsAcquisitionCustom

- bool [is_type_gr_complex](#) () const

Protected Attributes inherited from BasePcpsAcquisitionCustom

- const [Acq_Conf](#) [acq_parameters_](#)
- acquisition_impl_interface_sptr [acquisition_cc_](#)
- [Gnss_Synchro](#) * [gnss_synchro_](#)
- unsigned int [channel_](#)
- volk_gnssdr::vector< std::complex< float > > [code_](#)

12.220.1 Detailed Description

This class adapts a PCPS Tong acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

Definition at line 32 of file [gps_l1_ca_pcps_tong_acquisition.h](#).

12.220.2 Member Function Documentation

12.220.2.1 implementation()

```
std::string GpsL1CaPcpsTongAcquisition::implementation () [inline], [override], [virtual]
```

Returns "GPS_L1_CA_PCPS_Tong_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 45 of file [gps_l1_ca_pcps_tong_acquisition.h](#).

The documentation for this class was generated from the following file:

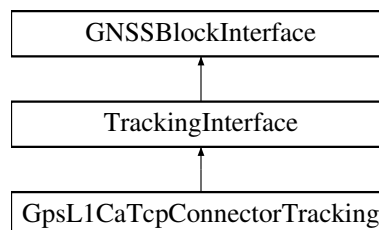
- [gps_l1_ca_pcps_tong_acquisition.h](#)

12.221 GpsL1CaTcpConnectorTracking Class Reference

This class implements a code DLL + carrier PLL tracking loop.

```
#include <gps_l1_ca_tcp_connector_tracking.h>
```

Inheritance diagram for GpsL1CaTcpConnectorTracking:



Public Member Functions

- **GpsL1CaTcpConnectorTracking** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override

- `std::string implementation ()` override
Returns "GPS_L1_CA_TCP_CONNECTOR_Tracking".
- `size_t item_size ()` override
- `void connect (gr::top_block_sptr top_block)` override
- `void disconnect (gr::top_block_sptr top_block)` override
- `gr::basic_block_sptr get_left_block ()` override
- `gr::basic_block_sptr get_right_block ()` override
- `void set_channel (unsigned int channel)` override
Set tracking channel unique ID.
- `void set_gnss_synchro (Gnss_Synchro *p_gnss_synchro)` override
Set acquisition/tracking common Gnss_Synchro object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- `void start_tracking ()` override
- `void stop_tracking ()` override
Stop running tracking.

Public Member Functions inherited from GNSSBlockInterface

- virtual `gr::basic_block_sptr get_left_block (int RF_channel)`
- virtual `gr::basic_block_sptr get_right_block (int RF_channel)`
- virtual `void start ()`

Start the flow of samples if needed.

12.221.1 Detailed Description

This class implements a code DLL + carrier PLL tracking loop.
Definition at line 42 of file [gps_l1_ca_tcp_connector_tracking.h](#).

12.221.2 Member Function Documentation

12.221.2.1 connect()

```
void GpsL1CaTcpConnectorTracking::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.221.2.2 disconnect()

```
void GpsL1CaTcpConnectorTracking::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.221.2.3 get_left_block()

```
gr::basic_block_sptr GpsL1CaTcpConnectorTracking::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.221.2.4 get_right_block()

```
gr::basic_block_sptr GpsL1CaTcpConnectorTracking::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.221.2.5 implementation()

```
std::string GpsL1CaTcpConnectorTracking::implementation () [inline], [override], [virtual]
```

Returns "GPS_L1_CA_TCP_CONNECTOR_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 59 of file [gps_l1_ca_tcp_connector_tracking.h](#).

12.221.2.6 item_size()

```
size_t GpsL1CaTcpConnectorTracking::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 64 of file [gps_l1_ca_tcp_connector_tracking.h](#).

12.221.2.7 role()

```
std::string GpsL1CaTcpConnectorTracking::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 53 of file [gps_l1_ca_tcp_connector_tracking.h](#).

12.221.2.8 set_channel()

```
void GpsL1CaTcpConnectorTracking::set_channel (
    unsigned int channel) [override], [virtual]
```

Set tracking channel unique ID.

Implements [TrackingInterface](#).

12.221.2.9 set_gnss_synchro()

```
void GpsL1CaTcpConnectorTracking::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.

Implements [TrackingInterface](#).

12.221.2.10 start_tracking()

```
void GpsL1CaTcpConnectorTracking::start_tracking () [override], [virtual]
```

Implements [TrackingInterface](#).

12.221.2.11 stop_tracking()

```
void GpsL1CaTcpConnectorTracking::stop_tracking () [override], [virtual]
```

Stop running tracking.

Implements [TrackingInterface](#).

The documentation for this class was generated from the following file:

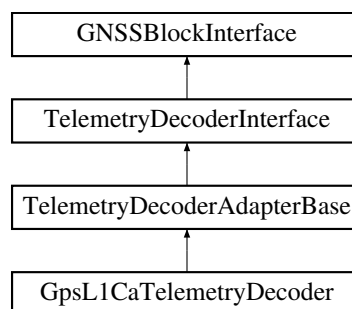
- [gps_l1_ca_tcp_connector_tracking.h](#)

12.222 GpsL1CaTelemetryDecoder Class Reference

This class implements a NAV data decoder for GPS L1 C/A.

```
#include <gps_l1_ca_telemetry_decoder.h>
```

Inheritance diagram for GpsL1CaTelemetryDecoder:



Public Member Functions

- **GpsL1CaTelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GPS_L1_CA_Telemetry_Decoder".

Public Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- void **InitializeDecoder** (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & **satellite** () const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- [Tlm_Conf](#) tlm_parameters_

12.222.1 Detailed Description

This class implements a NAV data decoder for GPS L1 C/A.
Definition at line 37 of file [gps_l1_ca_telemetry_decoder.h](#).

12.222.2 Member Function Documentation

12.222.2.1 [implementation\(\)](#)

```
std::string GpsL1CaTelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "GPS_L1_CA_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 47 of file [gps_l1_ca_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

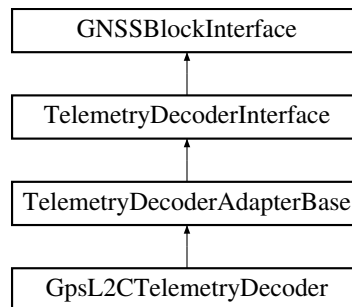
- [gps_l1_ca_telemetry_decoder.h](#)

12.223 GpsL2CTelemetryDecoder Class Reference

This class implements a NAV data decoder for GPS L2 M.

```
#include <gps_l2c_telemetry_decoder.h>
```

Inheritance diagram for GpsL2CTelemetryDecoder:



Public Member Functions

- **GpsL2CTelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GPS_L2C_Telemetry_Decoder".

Public Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- void **InitializeDecoder** (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & **satellite** () const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- [Tlm_Conf](#) tlm_parameters_

12.223.1 Detailed Description

This class implements a NAV data decoder for GPS L2 M.
Definition at line 35 of file [gps_l2c_telemetry_decoder.h](#).

12.223.2 Member Function Documentation

12.223.2.1 implementation()

```
std::string GpsL2CTelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "GPS_L2C_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 45 of file [gps_l2c_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

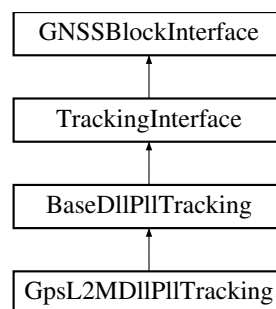
- [gps_l2c_telemetry_decoder.h](#)

12.224 GpsL2MDIIPITracking Class Reference

This class implements a code DLL + carrier PLL tracking loop block adapter for GPS L2C(M) signals.

```
#include <gps_l2_m_dll_pll_tracking.h>
```

Inheritance diagram for GpsL2MDIIPITracking:



Public Member Functions

- [GpsL2MDIIPITracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "GPS_L2_M_DLL_PLL_Tracking".

Public Member Functions inherited from [BaseDIIPITracking](#)

- [BaseDIIPITracking](#) (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDIIPITracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final

- Disconnect the *sTracking* block adapter.
- `gr::basic_block_sptr` [get_left_block](#) () override final
Get left block from the *Tracking* block adapter.
- `gr::basic_block_sptr` [get_right_block](#) () override final
Get right block from the *Tracking* block adapter.
- void [set_channel](#) (unsigned int channel) override final
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final
Start the *Tracking* block.
- void [stop_tracking](#) () override final
Stop the *Tracking* block.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual `gr::basic_block_sptr` [get_left_block](#) (int RF_channel)
- virtual `gr::basic_block_sptr` [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BaseDIIPITracking](#)

- [Dll_Pll_Conf](#) & [config_params](#) ()
- const [Dll_Pll_Conf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t item_size)

Protected Attributes inherited from [BaseDIIPITracking](#)

- `dll_pll_veml_tracking_sptr` [tracking_sptr_](#)

12.224.1 Detailed Description

This class implements a code DLL + carrier PLL tracking loop block adapter for GPS L2C(M) signals.
Definition at line 40 of file [gps_l2_m_dll_pll_tracking.h](#).

12.224.2 Constructor & Destructor Documentation

12.224.2.1 GpsL2MDIIPITracking()

```
GpsL2MDIIPITracking::GpsL2MDIIPITracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDIIPITracking::role\(\)](#).

12.224.3 Member Function Documentation

12.224.3.1 implementation()

`std::string GpsL2MD11P11Tracking::implementation () [inline], [override], [virtual]`

Returns "GPS_L2_M_DLL_PLL_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 50 of file [gps_l2_m_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

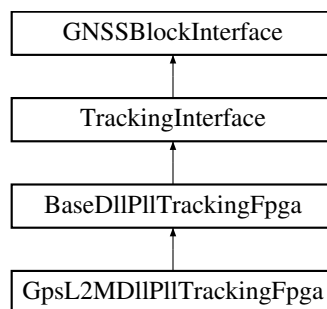
- [gps_l2_m_dll_pll_tracking.h](#)

12.225 GpsL2MDIIPITrackingFpga Class Reference

Adapter for a GPS L2M DLL+PLL tracking loop implemented in FPGA.

`#include <gps_l2_m_dll_pll_tracking_fpga.h>`

Inheritance diagram for GpsL2MDIIPITrackingFpga:



Public Member Functions

- [GpsL2MDIIPITrackingFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- [~GpsL2MDIIPITrackingFpga](#) () override
Destructor.
- std::string [implementation](#) () override
Returns "GPS_L2_M_DLL_PLL_Tracking_FPGA".

Public Member Functions inherited from [BaseDIIPITrackingFpga](#)

- [BaseDIIPITrackingFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Base constructor of FPGA-based Tracking block adapters.
- virtual [~BaseDIIPITrackingFpga](#) ()=default
Base destructor of FPGA-based Tracking block adapters.
- std::string [role](#) () override
Get role from the Tracking block adapter.
- size_t [item_size](#) () override
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override

- Get left block from the Tracking block adapter.*
- `gr::basic_block_sptr` [get_right_block](#) () override
- Get right block from the Tracking block adapter.*
- void [start_tracking](#) () override
- Start the tracking process in the FPGA.*
- void [stop_tracking](#) () override
- Stop the tracking process in the FPGA.*
- void [configure_fpga_tracking_channel_mapping](#) (std::string signal)
- configure FPGA tracking channel mapping*
- void [set_channel](#) (unsigned int channel) override
- Set tracking channel unique ID.*
- void [set_gnss_synchro](#) (Gnss_Synchro *p_gnss_synchro) override
- Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.*

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual `gr::basic_block_sptr` [get_left_block](#) (int RF_channel)
- virtual `gr::basic_block_sptr` [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
- Start the flow of samples if needed.*

Additional Inherited Members

Protected Member Functions inherited from [BaseDIIPITrackingFpga](#)

- `Dll_Pll_Conf_Fpga` & [config_params_fpga](#) ()
- const `Dll_Pll_Conf_Fpga` & [config_params_fpga](#) () const

Protected Attributes inherited from [BaseDIIPITrackingFpga](#)

- `dll_pll_veml_tracking_fpga_sptr` [tracking_fpga_sc_sptr](#)

Static Protected Attributes inherited from [BaseDIIPITrackingFpga](#)

- static const int32_t [LOCAL_CODE_FPGA_ENABLE_WRITE_MEMORY](#) = 0x0C000000
- static const int32_t [LOCAL_CODE_FPGA_CORRELATOR_SELECT_COUNT](#) = 0x20000000

12.225.1 Detailed Description

Adapter for a GPS L2M DLL+PLL tracking loop implemented in FPGA.
Definition at line 36 of file [gps_l2_m_dll_pll_tracking_fpga.h](#).

12.225.2 Constructor & Destructor Documentation

12.225.2.1 GpsL2MDIIPITrackingFpga()

```
GpsL2MDIIPITrackingFpga::GpsL2MDIIPITrackingFpga (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDIIPITrackingFpga::role\(\)](#).

12.225.2.2 ~GpsL2MDllPllTrackingFpga()

GpsL2MDllPllTrackingFpga::~~GpsL2MDllPllTrackingFpga () [override]
Destructor.

12.225.3 Member Function Documentation

12.225.3.1 implementation()

std::string GpsL2MDllPllTrackingFpga::implementation () [inline], [override], [virtual]

Returns "GPS_L2_M_DLL_PLL_Tracking_FPGA".

Implements [GNSSBlockInterface](#).

Definition at line 55 of file [gps_l2_m_dll_pll_tracking_fpga.h](#).

The documentation for this class was generated from the following file:

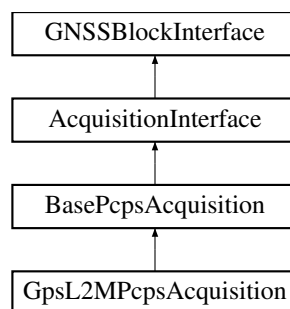
- [gps_l2_m_dll_pll_tracking_fpga.h](#)

12.226 GpsL2MPcpsAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L2 M signals.

#include <gps_l2_m_pcps_acquisition.h>

Inheritance diagram for GpsL2MPcpsAcquisition:



Public Member Functions

- **GpsL2MPcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
std::string [implementation](#) () override
Returns "GPS_L2_M_PCPS_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)
std::string [role](#) () override
size_t [item_size](#) () override
void [connect](#) (gr::top_block_sptr top_block) override
void [disconnect](#) (gr::top_block_sptr top_block) override
gr::basic_block_sptr [get_left_block](#) () override
gr::basic_block_sptr [get_right_block](#) () override
void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.

- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int doppler_center) override
Set Doppler center for the grid search.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t latency_samples) override
Sets the resampler latency to account it in the acquisition code delay estimation.
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

12.226.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L2 M signals.
Definition at line 34 of file [gps_l2_m_pcps_acquisition.h](#).

12.226.2 Member Function Documentation

12.226.2.1 implementation()

```
std::string GpsL2MPcpsAcquisition::implementation () [inline], [override], [virtual]
```

Returns "GPS_L2_M_PCPS_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [gps_l2_m_pcps_acquisition.h](#).

The documentation for this class was generated from the following file:

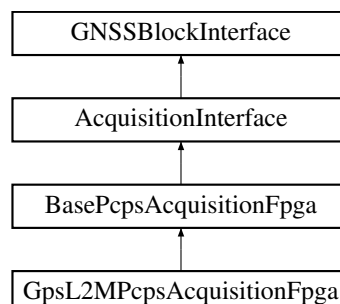
- [gps_l2_m_pcps_acquisition.h](#)

12.227 GpsL2MPcpsAcquisitionFpga Class Reference

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for GPS L2 M signals.

```
#include <gps_l2_m_pcps_acquisition_fpga.h>
```

Inheritance diagram for GpsL2MPcpsAcquisitionFpga:



Public Member Functions

- **GpsL2MPcpsAcquisitionFpga** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GPS_L2_M_PCPS_Acquisition_FPGA".

Public Member Functions inherited from [BasePcpsAcquisitionFpga](#)

- **BasePcpsAcquisitionFpga** (const [ConfigurationInterface](#) *configuration, std::string role, double code_rate_cps, double code_length_chips, uint32_t opt_acq_fs_sps, uint32_t default_fpga_blk_exp, uint32_t acq_buff, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override final
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- signed int [mag](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
- void [set_channel](#) (unsigned int channel) override
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
- void [set_doppler_center](#) (int doppler_center) override
- void [reset](#) () override
- void [stop_acquisition](#) () override
- void [set_resampler_latency](#) (uint32_t latency_samples __attribute__((unused))) override
- void [set_local_code](#) () override

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_resampler_latency](#) (uint32_t latency_samples)=0

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionFpga](#)

- void [init](#) ()

Protected Attributes inherited from [BasePcpsAcquisitionFpga](#)

- volk_gnssdr::vector< uint32_t > [d_all_fft_codes_](#)
- [Acq_Conf_Fpga](#) [acq_parameters_](#)

Static Protected Attributes inherited from [BasePcpsAcquisitionFpga](#)

- static const uint32_t [QUANT_BITS_LOCAL_CODE](#) = 16
- static const uint32_t [SELECT_LSBITS](#) = 0x0000FFFF
- static const uint32_t [SELECT_MSBITS](#) = 0xFFFF0000
- static const uint32_t [SELECT_ALL_CODE_BITS](#) = 0xFFFFFFFF
- static const uint32_t [SHL_CODE_BITS](#) = 65536
- static const uint32_t [ACQ_BUFF_0](#) = 0
- static const uint32_t [ACQ_BUFF_1](#) = 1

12.227.1 Detailed Description

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for GPS L2 M signals. Definition at line 34 of file [gps_l2_m_pcps_acquisition_fpga.h](#).

12.227.2 Member Function Documentation

12.227.2.1 implementation()

```
std::string GpsL2MPcpsAcquisitionFpga::implementation () [inline], [override], [virtual]
```

Returns "GPS_L2_M_PCPS_Acquisition_FPGA".

Implements [GNSSBlockInterface](#).

Definition at line 46 of file [gps_l2_m_pcps_acquisition_fpga.h](#).

The documentation for this class was generated from the following file:

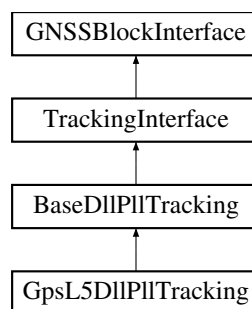
- [gps_l2_m_pcps_acquisition_fpga.h](#)

12.228 GpsL5DlIPllTracking Class Reference

This class implements a code DLL + carrier PLL tracking loop block adapter for GPS L5 signals.

```
#include <gps_l5_dll_pll_tracking.h>
```

Inheritance diagram for GpsL5DlIPllTracking:



Public Member Functions

- [GpsL5DlIPllTracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "GPS_L5_DLL_PLL_Tracking".

Public Member Functions inherited from [BaseDlIPllTracking](#)

- [BaseDlIPllTracking](#) (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDlIPllTracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final

- *Disconnect the sTracking block adapter.*
- gr::basic_block_sptr [get_left_block](#) () override final
Get left block from the Tracking block adapter.
- gr::basic_block_sptr [get_right_block](#) () override final
Get right block from the Tracking block adapter.
- void [set_channel](#) (unsigned int channel) override final
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final
Start the Tracking block.
- void [stop_tracking](#) () override final
Stop the Tracking block.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BaseDIIPIITracking](#)

- [DII_PII_Conf](#) & [config_params](#) ()
- const [DII_PII_Conf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t item_size)

Protected Attributes inherited from [BaseDIIPIITracking](#)

- dll_pll_veml_tracking_sptr [tracking_sptr_](#)

12.228.1 Detailed Description

This class implements a code DLL + carrier PLL tracking loop block adapter for GPS L5 signals. Definition at line 40 of file [gps_l5_dll_pll_tracking.h](#).

12.228.2 Constructor & Destructor Documentation

12.228.2.1 GpsL5DIIPIITracking()

```
GpsL5DllPl1Tracking::GpsL5DllPl1Tracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDIIPIITracking::role\(\)](#).

12.228.3 Member Function Documentation

12.228.3.1 implementation()

`std::string GpsL5DllPllTracking::implementation () [inline], [override], [virtual]`

Returns "GPS_L5_DLL_PLL_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 50 of file [gps_l5_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

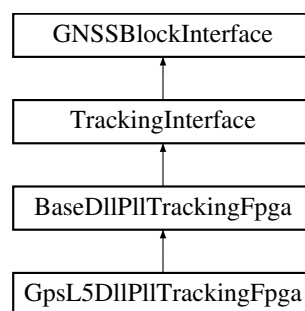
- [gps_l5_dll_pll_tracking.h](#)

12.229 GpsL5DllPllTrackingFpga Class Reference

Adapter for a GPS L5 DLL+PLL tracking loop for FPGA devices.

`#include <gps_l5_dll_pll_tracking_fpga.h>`

Inheritance diagram for GpsL5DllPllTrackingFpga:



Public Member Functions

- [GpsL5DllPllTrackingFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- [~GpsL5DllPllTrackingFpga](#) () override
Destructor.
- std::string [implementation](#) () override
Returns "GPS_L5_DLL_PLL_Tracking_FPGA".

Public Member Functions inherited from [BaseDllPllTrackingFpga](#)

- [BaseDllPllTrackingFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Base constructor of FPGA-based Tracking block adapters.
- virtual [~BaseDllPllTrackingFpga](#) ()=default
Base destructor of FPGA-based Tracking block adapters.
- std::string [role](#) () override
Get role from the Tracking block adapter.
- size_t [item_size](#) () override
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override

- Get left block from the Tracking block adapter.*
- `gr::basic_block_sptr` [get_right_block](#) () override
- Get right block from the Tracking block adapter.*
- `void` [start_tracking](#) () override
- Start the tracking process in the FPGA.*
- `void` [stop_tracking](#) () override
- Stop the tracking process in the FPGA.*
- `void` [configure_fpga_tracking_channel_mapping](#) (std::string signal)
- configure FPGA tracking channel mapping*
- `void` [set_channel](#) (unsigned int channel) override
- Set tracking channel unique ID.*
- `void` [set_gnss_synchro](#) (Gnss_Synchro *p_gnss_synchro) override
- Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.*

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual `gr::basic_block_sptr` [get_left_block](#) (int RF_channel)
- virtual `gr::basic_block_sptr` [get_right_block](#) (int RF_channel)
- virtual `void` [start](#) ()
- Start the flow of samples if needed.*

Additional Inherited Members

Protected Member Functions inherited from [BaseDlIPllTrackingFpga](#)

- `Dll_Pll_Conf_Fpga` & [config_params_fpga](#) ()
- `const Dll_Pll_Conf_Fpga` & [config_params_fpga](#) () const

Protected Attributes inherited from [BaseDlIPllTrackingFpga](#)

- `dll_pll_veml_tracking_fpga_sptr` [tracking_fpga_sc_sptr](#)

Static Protected Attributes inherited from [BaseDlIPllTrackingFpga](#)

- `static const int32_t` [LOCAL_CODE_FPGA_ENABLE_WRITE_MEMORY](#) = 0x0C000000
- `static const int32_t` [LOCAL_CODE_FPGA_CORRELATOR_SELECT_COUNT](#) = 0x20000000

12.229.1 Detailed Description

Adapter for a GPS L5 DLL+PLL tracking loop for FPGA devices.

Definition at line 37 of file [gps_l5_dll_pll_tracking_fpga.h](#).

12.229.2 Constructor & Destructor Documentation

12.229.2.1 GpsL5DlIPllTrackingFpga()

```
GpsL5DlIPllTrackingFpga::GpsL5DlIPllTrackingFpga (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDlIPllTrackingFpga::role\(\)](#).

12.229.2.2 ~GpsL5DlIPllTrackingFpga()

GpsL5DlIPllTrackingFpga::~~GpsL5DlIPllTrackingFpga () [override]
Destructor.

12.229.3 Member Function Documentation

12.229.3.1 implementation()

std::string GpsL5DlIPllTrackingFpga::implementation () [inline], [override], [virtual]

Returns "GPS_L5_DLL_PLL_Tracking_FPGA".

Implements [GNSSBlockInterface](#).

Definition at line 56 of file [gps_l5_dll_pll_tracking_fpga.h](#).

The documentation for this class was generated from the following file:

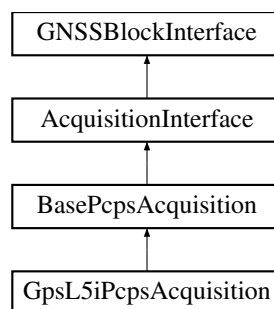
- [gps_l5_dll_pll_tracking_fpga.h](#)

12.230 GpsL5iPcpsAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L5i signals.

#include <gps_l5i_pcps_acquisition.h>

Inheritance diagram for GpsL5iPcpsAcquisition:



Public Member Functions

- **GpsL5iPcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
std::string [implementation](#) () override
Returns "GPS_L5i_PCPS_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)
std::string [role](#) () override
size_t [item_size](#) () override
void [connect](#) (gr::top_block_sptr top_block) override
void [disconnect](#) (gr::top_block_sptr top_block) override
gr::basic_block_sptr [get_left_block](#) () override
gr::basic_block_sptr [get_right_block](#) () override
void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.

- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int doppler_center) override
Set Doppler center for the grid search.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t latency_samples) override
Sets the resampler latency to account it in the acquisition code delay estimation.
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

12.230.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L5i signals.
Definition at line 34 of file [gps_l5i_pcps_acquisition.h](#).

12.230.2 Member Function Documentation

12.230.2.1 implementation()

```
std::string GpsL5iPcpsAcquisition::implementation () [inline], [override], [virtual]
```

Returns "GPS_L5i_PCPS_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [gps_l5i_pcps_acquisition.h](#).

The documentation for this class was generated from the following file:

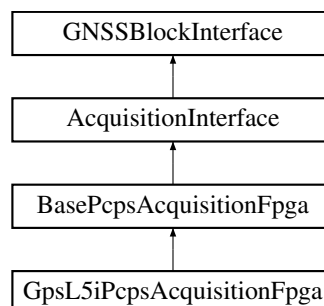
- [gps_l5i_pcps_acquisition.h](#)

12.231 GpsL5iPcpsAcquisitionFpga Class Reference

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for GPS L5i signals.

```
#include <gps_l5i_pcps_acquisition_fpga.h>
```

Inheritance diagram for GpsL5iPcpsAcquisitionFpga:



Public Member Functions

- [GpsL5iPcpsAcquisitionFpga](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "GPS_L5i_PCPS_Acquisition_FPGA".

Public Member Functions inherited from [BasePcpsAcquisitionFpga](#)

- **[BasePcpsAcquisitionFpga](#)** (const [ConfigurationInterface](#) *configuration, std::string role, double code_rate_cps, double code_length_chips, uint32_t opt_acq_fs_sps, uint32_t default_fpga_blk_exp, uint32_t acq_buff, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override final
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- signed int [mag](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
- void [set_channel](#) (unsigned int channel) override
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
- void [set_doppler_center](#) (int doppler_center) override
- void [reset](#) () override
- void [stop_acquisition](#) () override
- void [set_resampler_latency](#) (uint32_t latency_samples __attribute__((unused))) override
- void [set_local_code](#) () override

Public Member Functions inherited from [AcquisitionInterface](#)

- virtual void [set_resampler_latency](#) (uint32_t latency_samples)=0

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BasePcpsAcquisitionFpga](#)

- void [init](#) ()

Protected Attributes inherited from [BasePcpsAcquisitionFpga](#)

- volk_gnssdr::vector< uint32_t > [d_all_fft_codes_](#)
- [Acq_Conf_Fpga](#) [acq_parameters_](#)

Static Protected Attributes inherited from [BasePcpsAcquisitionFpga](#)

- static const uint32_t [QUANT_BITS_LOCAL_CODE](#) = 16
- static const uint32_t [SELECT_LSBITS](#) = 0x0000FFFF
- static const uint32_t [SELECT_MSBITS](#) = 0xFFFF0000
- static const uint32_t [SELECT_ALL_CODE_BITS](#) = 0xFFFFFFFF
- static const uint32_t [SHL_CODE_BITS](#) = 65536
- static const uint32_t [ACQ_BUFF_0](#) = 0
- static const uint32_t [ACQ_BUFF_1](#) = 1

12.231.1 Detailed Description

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for GPS L5i signals. Definition at line 35 of file [gps_l5i_pcps_acquisition_fpga.h](#).

12.231.2 Constructor & Destructor Documentation

12.231.2.1 GpsL5iPcpsAcquisitionFpga()

```
GpsL5iPcpsAcquisitionFpga::GpsL5iPcpsAcquisitionFpga (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

12.231.3 Member Function Documentation

12.231.3.1 implementation()

```
std::string GpsL5iPcpsAcquisitionFpga::implementation () [inline], [override], [virtual]
```

Returns "GPS_L5i_PCPS_Acquisition_FPGA".

Implements [GNSSBlockInterface](#).

Definition at line 50 of file [gps_l5i_pcps_acquisition_fpga.h](#).

The documentation for this class was generated from the following file:

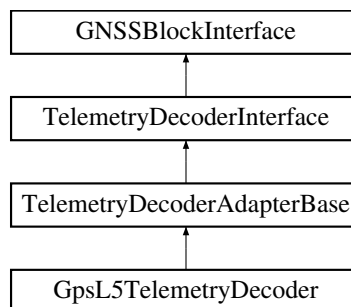
- [gps_l5i_pcps_acquisition_fpga.h](#)

12.232 GpsL5TelemetryDecoder Class Reference

This class implements a NAV data decoder for GPS L5.

```
#include <gps_l5_telemetry_decoder.h>
```

Inheritance diagram for GpsL5TelemetryDecoder:



Public Member Functions

- **GpsL5TelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "GPS_L5_Telemetry_Decoder".

Public Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- void **InitializeDecoder** (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & **satellite** () const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- [Tlm_Conf](#) tlm_parameters_

12.232.1 Detailed Description

This class implements a NAV data decoder for GPS L5.
Definition at line 34 of file [gps_l5_telemetry_decoder.h](#).

12.232.2 Member Function Documentation

12.232.2.1 [implementation\(\)](#)

```
std::string GpsL5TelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "GPS_L5_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 44 of file [gps_l5_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

- [gps_l5_telemetry_decoder.h](#)

12.233 GPU_Complex Struct Reference

Public Member Functions

- CUDA_CALLABLE_MEMBER_DEVICE [GPU_Complex](#) (float a, float b)
- CUDA_CALLABLE_MEMBER_DEVICE float [magnitude2](#) (void)
- CUDA_CALLABLE_MEMBER_DEVICE [GPU_Complex operator*](#) (const [GPU_Complex](#) &a)
- CUDA_CALLABLE_MEMBER_DEVICE [GPU_Complex operator+](#) (const [GPU_Complex](#) &a)
- CUDA_CALLABLE_MEMBER_DEVICE void [operator+=](#) (const [GPU_Complex](#) &a)
- CUDA_CALLABLE_MEMBER_DEVICE void [multiply_acc](#) (const [GPU_Complex](#) &a, const [GPU_Complex](#) &b)

Public Attributes

- float [r](#)
- float [i](#)

12.233.1 Detailed Description

Definition at line 45 of file [cuda_multicorrelator.h](#).

12.233.2 Constructor & Destructor Documentation

12.233.2.1 GPU_Complex() [1/2]

```
CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex::GPU_Complex () [inline]
```

Definition at line 49 of file [cuda_multicorrelator.h](#).

12.233.2.2 GPU_Complex() [2/2]

```
CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex::GPU_Complex (
    float a,
    float b) [inline]
```

Definition at line 50 of file [cuda_multicorrelator.h](#).

12.233.3 Member Function Documentation

12.233.3.1 magnitude2()

```
CUDA_CALLABLE_MEMBER_DEVICE float GPU_Complex::magnitude2 (
    void ) [inline]
```

Definition at line 51 of file [cuda_multicorrelator.h](#).

12.233.3.2 multiply_acc()

```
CUDA_CALLABLE_MEMBER_DEVICE void GPU_Complex::multiply_acc (
    const GPU_Complex & a,
    const GPU_Complex & b) [inline]
```

Definition at line 69 of file [cuda_multicorrelator.h](#).

12.233.3.3 operator*()

```
CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex GPU_Complex::operator* (
    const GPU_Complex & a) [inline]
```

Definition at line 52 of file [cuda_multicorrelator.h](#).

12.233.3.4 operator+()

```
CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex GPU_Complex::operator+ (
    const GPU_Complex & a) [inline]
```

Definition at line 60 of file [cuda_multicorrelator.h](#).

12.233.3.5 operator+=()

```
CUDA_CALLABLE_MEMBER_DEVICE void GPU_Complex::operator+= (
    const GPU_Complex & a) [inline]
```

Definition at line 64 of file [cuda_multicorrelator.h](#).

12.233.4 Member Data Documentation

12.233.4.1 i

```
float GPU_Complex::i
```

Definition at line 48 of file [cuda_multicorrelator.h](#).

12.233.4.2 r

```
float GPU_Complex::r
```

Definition at line 47 of file [cuda_multicorrelator.h](#).

The documentation for this struct was generated from the following file:

- [cuda_multicorrelator.h](#)

12.234 GPU_Complex_Short Struct Reference

Public Member Functions

- CUDA_CALLABLE_MEMBER_DEVICE [GPU_Complex_Short](#) (short int a, short int b)
- CUDA_CALLABLE_MEMBER_DEVICE float [magnitude2](#) (void)
- CUDA_CALLABLE_MEMBER_DEVICE [GPU_Complex_Short operator*](#) (const [GPU_Complex_Short](#) &a)
- CUDA_CALLABLE_MEMBER_DEVICE [GPU_Complex_Short operator+](#) (const [GPU_Complex_Short](#) &a)

Public Attributes

- float [r](#)
- float [i](#)

12.234.1 Detailed Description

Definition at line 88 of file [cuda_multicorrelator.h](#).

12.234.2 Constructor & Destructor Documentation

12.234.2.1 GPU_Complex_Short()

```
CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex_Short::GPU_Complex_Short (
    short int a,
    short int b) [inline]
```

Definition at line 92 of file [cuda_multicorrelator.h](#).

12.234.3 Member Function Documentation

12.234.3.1 magnitude2()

```
CUDA_CALLABLE_MEMBER_DEVICE float GPU_Complex_Short::magnitude2 (
    void ) [inline]
```

Definition at line 93 of file [cuda_multicorrelator.h](#).

12.234.3.2 operator*()

```
CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex_Short GPU_Complex_Short::operator* (
    const GPU_Complex_Short & a) [inline]
```

Definition at line 97 of file [cuda_multicorrelator.h](#).

12.234.3.3 operator+()

```
CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex_Short GPU_Complex_Short::operator+ (
    const GPU_Complex_Short & a) [inline]
```

Definition at line 101 of file [cuda_multicorrelator.h](#).

12.234.4 Member Data Documentation

12.234.4.1 i

```
float GPU_Complex_Short::i
```

Definition at line 91 of file [cuda_multicorrelator.h](#).

12.234.4.2 r

```
float GPU_Complex_Short::r
```

Definition at line 90 of file [cuda_multicorrelator.h](#).

The documentation for this struct was generated from the following file:

- [cuda_multicorrelator.h](#)

12.235 Gpx_Printer Class Reference

Prints PVT information to GPX format file.

```
#include <gpx_printer.h>
```

Public Member Functions

- **Gpx_Printer** (const std::string &base_path=".")
- bool **set_headers** (const std::string &filename, bool time_tag_name=true)
- bool **print_position** (const [Pvt_Solution](#) *const position)
- bool **close_file** ()

12.235.1 Detailed Description

Prints PVT information to GPX format file.

See <https://www.topografix.com/gpx.asp>

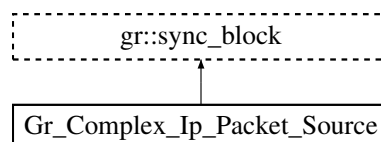
Definition at line 39 of file [gpx_printer.h](#).

The documentation for this class was generated from the following file:

- [gpx_printer.h](#)

12.236 Gr_Complex_Ip_Packet_Source Class Reference

Inheritance diagram for Gr_Complex_Ip_Packet_Source:



Public Types

- using **sptr** = gnss_shared_ptr<[Gr_Complex_Ip_Packet_Source](#)>

Public Member Functions

- **Gr_Complex_Ip_Packet_Source** (std::string src_device, const std::string &origin_address, int udp_port, int udp_packet_size, int n_baseband_channels, const std::string &wire_sample_type, size_t item_size, bool IQ_swap_)
- bool **start** ()
- bool **stop** ()
- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Static Public Member Functions

- static sptr **make** (std::string src_device, const std::string &origin_address, int udp_port, int udp_packet_size, int n_baseband_channels, const std::string &wire_sample_type, size_t item_size, bool IQ_swap_)

12.236.1 Detailed Description

Definition at line 41 of file [gr_complex_ip_packet_source.h](#).

12.236.2 Member Typedef Documentation

12.236.2.1 sptr

```
using Gr_Complex_Ip_Packet_Source::sptr = gnss_shared_ptr<Gr_Complex_Ip_Packet_Source>
```

Definition at line 44 of file [gr_complex_ip_packet_source.h](#).

The documentation for this class was generated from the following file:

- [gr_complex_ip_packet_source.h](#)

12.237 gtime_t Struct Reference

Public Attributes

- time_t [time](#)
- double [sec](#)

12.237.1 Detailed Description

Definition at line 356 of file [rtklib.h](#).

12.237.2 Member Data Documentation

12.237.2.1 sec

```
double gtime_t::sec
```

Definition at line 359 of file [rtklib.h](#).

12.237.2.2 time

```
time_t gtime_t::time
```

Definition at line 358 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.238 half_cyc_tag Struct Reference

Public Attributes

- unsigned char [sat](#)

- unsigned char [freq](#)
- unsigned char [valid](#)
- char [corr](#)
- [gtime_t](#) [ts](#)
- [gtime_t](#) [te](#)
- struct [half_cyc_tag](#) * [next](#)

12.238.1 Detailed Description

Definition at line [1084](#) of file [rtklib.h](#).

12.238.2 Member Data Documentation

12.238.2.1 corr

```
char half_cyc_tag::corr
```

Definition at line [1089](#) of file [rtklib.h](#).

12.238.2.2 freq

```
unsigned char half_cyc_tag::freq
```

Definition at line [1087](#) of file [rtklib.h](#).

12.238.2.3 next

```
struct half_cyc_tag* half_cyc_tag::next
```

Definition at line [1091](#) of file [rtklib.h](#).

12.238.2.4 sat

```
unsigned char half_cyc_tag::sat
```

Definition at line [1086](#) of file [rtklib.h](#).

12.238.2.5 te

```
gtime\_t half_cyc_tag::te
```

Definition at line [1090](#) of file [rtklib.h](#).

12.238.2.6 ts

```
gtime\_t half_cyc_tag::ts
```

Definition at line [1090](#) of file [rtklib.h](#).

12.238.2.7 valid

```
unsigned char half_cyc_tag::valid
```

Definition at line [1088](#) of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.239 HAS_clock_corrections Class Reference

Public Attributes

- float [clock_correction_m](#) {}
- uint32_t [valid_until](#) {}

12.239.1 Detailed Description

Definition at line 41 of file [rtklib_conversions.h](#).

12.239.2 Member Data Documentation

12.239.2.1 clock_correction_m

```
float HAS_clock_corrections::clock_correction_m {}
```

Definition at line 45 of file [rtklib_conversions.h](#).

12.239.2.2 valid_until

```
uint32_t HAS_clock_corrections::valid_until {}
```

Definition at line 46 of file [rtklib_conversions.h](#).

The documentation for this class was generated from the following file:

- [rtklib_conversions.h](#)

12.240 HAS_obs_corrections Class Reference

Public Attributes

- float [code_bias_m](#) {}
- float [phase_bias_cycle](#) {}

12.240.1 Detailed Description

Definition at line 60 of file [rtklib_conversions.h](#).

12.240.2 Member Data Documentation

12.240.2.1 code_bias_m

```
float HAS_obs_corrections::code_bias_m {}
```

Definition at line 64 of file [rtklib_conversions.h](#).

12.240.2.2 phase_bias_cycle

```
float HAS_obs_corrections::phase_bias_cycle {}
```

Definition at line 65 of file [rtklib_conversions.h](#).

The documentation for this class was generated from the following file:

- [rtklib_conversions.h](#)

12.241 HAS_orbit_corrections Class Reference

Public Attributes

- float [radial_m](#) {}
- float [in_track_m](#) {}
- float [cross_track_m](#) {}
- uint32_t [valid_until](#) {}
- uint16_t [iod](#) {}

12.241.1 Detailed Description

Definition at line 49 of file [rtklib_conversions.h](#).

12.241.2 Member Data Documentation

12.241.2.1 cross_track_m

float HAS_orbit_corrections::cross_track_m {}

Definition at line 55 of file [rtklib_conversions.h](#).

12.241.2.2 in_track_m

float HAS_orbit_corrections::in_track_m {}

Definition at line 54 of file [rtklib_conversions.h](#).

12.241.2.3 iod

uint16_t HAS_orbit_corrections::iod {}

Definition at line 57 of file [rtklib_conversions.h](#).

12.241.2.4 radial_m

float HAS_orbit_corrections::radial_m {}

Definition at line 53 of file [rtklib_conversions.h](#).

12.241.2.5 valid_until

uint32_t HAS_orbit_corrections::valid_until {}

Definition at line 56 of file [rtklib_conversions.h](#).

The documentation for this class was generated from the following file:

- [rtklib_conversions.h](#)

12.242 Has_Simple_Printer Class Reference

Prints HAS messages content in a txt file. See HAS-SIS-ICD for a message description.

#include <has_simple_printer.h>

Public Member Functions

- **Has_Simple_Printer** (const std::string &base_path=std::string("."), const std::string &filename=std::string("HAS_Messages"), bool time_tag_name=true)
- bool **print_message** (const [Galileo_HAS_data](#) *const has_data)

12.242.1 Detailed Description

Prints HAS messages content in a txt file. See HAS-SIS-ICD for a message description.

Definition at line 37 of file [has_simple_printer.h](#).

The documentation for this class was generated from the following file:

- [has_simple_printer.h](#)

12.243 std::hash< SensorIdentifier::value_type > Struct Reference

Public Member Functions

- std::size_t **operator()** (const SensorIdentifier::value_type &key) const noexcept

12.243.1 Detailed Description

Definition at line 67 of file [sensor_identifier.h](#).

12.243.2 Member Function Documentation

12.243.2.1 operator>()

```
std::size_t std::hash< SensorIdentifier::value_type >::operator() (
    const SensorIdentifier::value_type & key) const [inline], [noexcept]
```

Definition at line 69 of file [sensor_identifier.h](#).

The documentation for this struct was generated from the following file:

- [sensor_identifier.h](#)

12.244 HistogramBitSynchronizer Class Reference

Histogram-based navigation data bit synchronizer.

```
#include <bit_synchronizer.h>
```

Classes

- struct [Config](#)
Configuration parameters for [HistogramBitSynchronizer](#).

Public Member Functions

- [HistogramBitSynchronizer](#) (const [Config](#) &cfg)
Construct a histogram bit synchronizer with the provided configuration.
- void [reset](#) ()
Reset the synchronizer state.
- bool [update](#) (const std::complex< float > &prompt, bool tracking_quality_ok)
Update the synchronizer once per epoch.
- bool [locked](#) () const
Query whether the synchronizer has achieved lock.
- int [edge_phase](#) () const
Get the estimated bit edge phase bin.
- bool [is_edge_epoch](#) (std::int64_t k) const
Predict whether a given epoch index corresponds to a bit edge.
- int [bins](#) () const
Return the number of histogram bins.
- const std::vector< int > & [get_histogram](#) () const
Access the internal histogram (read-only).
- std::int64_t [get_total_events](#) () const
Total number of detected transition events accumulated into the histogram.
- std::int64_t [get_epoch_count](#) () const
Total number of epochs processed by [update\(\)](#).
- int [epochs_until_next_edge](#) () const
Return the number of epochs until the next predicted navigation bit edge.

12.244.1 Detailed Description

Histogram-based navigation data bit synchronizer.

Definition at line 34 of file [bit_synchronizer.h](#).

12.244.2 Constructor & Destructor Documentation

12.244.2.1 HistogramBitSynchronizer()

```
HistogramBitSynchronizer::HistogramBitSynchronizer (
    const Config & cfg) [inline], [explicit]
```

Construct a histogram bit synchronizer with the provided configuration.

Initializes internal counters and allocates the histogram with [bins\(\)](#) entries, all set to zero.

Parameters

<i>cfg</i>	Configuration parameters.
------------	---------------------------

Definition at line 148 of file [bit_synchronizer.h](#).

References [bins\(\)](#).

12.244.3 Member Function Documentation

12.244.3.1 bins()

```
int HistogramBitSynchronizer::bins () const
```

Return the number of histogram bins.

Derived from the bit period and epoch duration, e.g.: $\text{bins} = \text{bit_period_ms} / \text{epoch_ms}$

Returns

Number of histogram bins.

Referenced by [HistogramBitSynchronizer\(\)](#).

12.244.3.2 edge_phase()

```
int HistogramBitSynchronizer::edge_phase () const [inline]
```

Get the estimated bit edge phase bin.

The edge phase is expressed as an integer histogram bin index in the range $[0, \text{bins}()-1]$ when locked. The interpretation is “which epoch phase within the bit period is most likely to contain a navigation bit transition.”

Returns

Estimated edge phase bin index, or -1 if not locked.

Definition at line 213 of file [bit_synchronizer.h](#).

12.244.3.3 epochs_until_next_edge()

```
int HistogramBitSynchronizer::epochs_until_next_edge () const
```

Return the number of epochs until the next predicted navigation bit edge.

When the synchronizer is locked, this function computes the forward distance (in epochs) from the most recently processed epoch to the next epoch that is aligned with the estimated bit-edge phase.

The result is expressed modulo the bit period and has the following meaning:

- 0 : the current epoch corresponds to the predicted start of a new navigation bit
- >0 : number of epochs remaining until the next bit boundary

The computation is based on the internal epoch counter advanced by [update\(\)](#), assuming that [update\(\)](#) is called once per epoch with a constant cadence equal to [Config::epoch_ms](#).

If the synchronizer is not locked, or if the configuration yields an invalid number of bins, this function returns -1.

Returns

Number of epochs until the next predicted bit edge, or -1 if not locked or if the bit period configuration is invalid.

12.244.3.4 get_epoch_count()

```
std::int64_t HistogramBitSynchronizer::get_epoch_count () const [inline]
```

Total number of epochs processed by [update\(\)](#).

This counter increments once per call to [update\(\)](#), regardless of whether a transition is detected or whether `tracking_quality_ok` is true.

Returns

Total processed epochs.

Definition at line 264 of file [bit_synchronizer.h](#).

12.244.3.5 get_histogram()

```
const std::vector< int > & HistogramBitSynchronizer::get_histogram () const [inline]
```

Access the internal histogram (read-only).

Each entry counts how many detected candidate transitions occurred at the corresponding phase bin within the bit period.

Returns

Reference to the histogram vector.

Definition at line 247 of file [bit_synchronizer.h](#).

12.244.3.6 get_total_events()

```
std::int64_t HistogramBitSynchronizer::get_total_events () const [inline]
```

Total number of detected transition events accumulated into the histogram.

Returns

Total detected events.

Definition at line 254 of file [bit_synchronizer.h](#).

12.244.3.7 is_edge_epoch()

```
bool HistogramBitSynchronizer::is_edge_epoch (
    std::int64_t k) const
```

Predict whether a given epoch index corresponds to a bit edge.

For a given epoch index `k` (0-based), this function returns true when `k` is aligned with the currently estimated edge phase (i.e., the predicted transition epoch), and false otherwise.

If not locked, this always returns false.

Parameters

<code>k</code>	Epoch index (0-based, consistent with the caller's epoch counting).
----------------	---

Returns

True if `k` is the predicted edge epoch; false otherwise.

12.244.3.8 locked()

```
bool HistogramBitSynchronizer::locked () const [inline]
```

Query whether the synchronizer has achieved lock.

Returns

True if lock has been declared, false otherwise.

Definition at line 202 of file [bit_synchronizer.h](#).

12.244.3.9 reset()

```
void HistogramBitSynchronizer::reset ()
```

Reset the synchronizer state.

Clears the histogram and all internal counters/flags, returning the instance to the pre-lock state:

- `locked()` becomes false
- `edge_phase()` becomes -1
- `total_events` and `epoch_count` are reset to zero

12.244.3.10 update()

```
bool HistogramBitSynchronizer::update (
    const std::complex< float > & prompt,
    bool tracking_quality_ok)
```

Update the synchronizer once per epoch.

This method should be called at a fixed cadence defined by `Config::epoch_ms`

The method:

- Advances the internal epoch counter,
- Optionally performs candidate transition detection if tracking quality is acceptable,
- Updates the phase histogram on detected transitions,
- Evaluates lock once enough events have been gathered.

Parameters

<i>prompt</i>	Prompt correlator output for the current epoch.
<i>tracking_quality_ok</i>	Indicates whether tracking quality is sufficient to trust the prompt sample for transition detection (e.g., code/carrier lock metrics).

Returns

True only on the epoch when lock is first declared; false otherwise (including subsequent epochs after lock has been achieved).

The documentation for this class was generated from the following file:

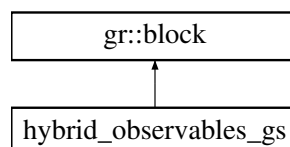
- [bit_synchronizer.h](#)

12.245 hybrid_observables_gs Class Reference

This class implements a block that computes observables.

```
#include <hybrid_observables_gs.h>
```

Inheritance diagram for `hybrid_observables_gs`:



Public Member Functions

- void **forecast** (int noutput_items, gr_vector_int &ninput_items_required)
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- `hybrid_observables_gs_sptr` **hybrid_observables_gs_make** (const [Obs_Conf](#) &conf_)

12.245.1 Detailed Description

This class implements a block that computes observables.

Definition at line 58 of file [hybrid_observables_gs.h](#).

The documentation for this class was generated from the following file:

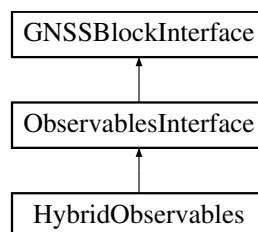
- [hybrid_observables_gs.h](#)

12.246 HybridObservables Class Reference

This class implements an [ObservablesInterface](#) for observables of all kind of GNSS signals.

`#include <hybrid_observables.h>`

Inheritance diagram for HybridObservables:



Public Member Functions

- **HybridObservables** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override
- *Returns "Hybrid_Observables".*
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [reset](#) () override
- size_t [item_size](#) () override

All blocks must have an [item_size\(\)](#) function implementation.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.246.1 Detailed Description

This class implements an [ObservablesInterface](#) for observables of all kind of GNSS signals.

Definition at line 43 of file [hybrid_observables.h](#).

12.246.2 Member Function Documentation

12.246.2.1 connect()

```
void HybridObservables::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.246.2.2 disconnect()

```
void HybridObservables::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.246.2.3 get_left_block()

```
gr::basic_block_sptr HybridObservables::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.246.2.4 get_right_block()

```
gr::basic_block_sptr HybridObservables::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.246.2.5 implementation()

```
std::string HybridObservables::implementation () [inline], [override], [virtual]
```

Returns "Hybrid_Observables".

Implements [GNSSBlockInterface](#).

Definition at line 59 of file [hybrid_observables.h](#).

12.246.2.6 item_size()

```
size_t HybridObservables::item_size () [inline], [override], [virtual]
```

All blocks must have an [item_size\(\)](#) function implementation.

Implements [GNSSBlockInterface](#).

Definition at line 75 of file [hybrid_observables.h](#).

12.246.2.7 reset()

```
void HybridObservables::reset () [inline], [override], [virtual]
```

Implements [ObservablesInterface](#).

Definition at line 69 of file [hybrid_observables.h](#).

12.246.2.8 role()

```
std::string HybridObservables::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 53 of file [hybrid_observables.h](#).

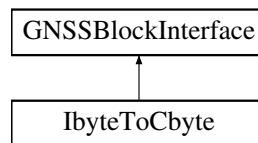
The documentation for this class was generated from the following file:

- [hybrid_observables.h](#)

12.247 lbyteToCbyte Class Reference

```
#include <lbyte_to_cbyte.h>
```

Inheritance diagram for lbyteToCbyte:



Public Member Functions

- **IbyteToCbyte** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override
Returns "Ibyte_To_Cbyte".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.247.1 Detailed Description

\brief Adapts an I/Q interleaved byte (unsigned char) sample stream into a std::complex<unsigned char> stream
Definition at line 40 of file [ibyte_to_cbyte.h](#).

12.247.2 Member Function Documentation

12.247.2.1 connect()

```
void IbyteToCbyte::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.247.2.2 disconnect()

```
void IbyteToCbyte::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.247.2.3 get_left_block()

```
gr::basic_block_sptr IbyteToCbyte::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.247.2.4 get_right_block()

```
gr::basic_block_sptr IbyteToCbyte::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.247.2.5 implementation()

```
std::string IbyteToCbyte::implementation () [inline], [override], [virtual]
```

Returns "Ibyte_To_Cbyte".

Implements [GNSSBlockInterface](#).

Definition at line 55 of file [ibyte_to_cbyte.h](#).

12.247.2.6 item_size()

```
size_t IbyteToCbyte::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 60 of file [ibyte_to_cbyte.h](#).

12.247.2.7 role()

```
std::string IbyteToCbyte::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 49 of file [ibyte_to_cbyte.h](#).

The documentation for this class was generated from the following file:

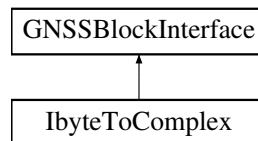
- [ibyte_to_cbyte.h](#)

12.248 IbyteToComplex Class Reference

Adapts an I/Q interleaved byte integer sample stream to a gr_complex (float) stream.

```
#include <ibyte_to_complex.h>
```

Inheritance diagram for IbyteToComplex:



Public Member Functions

- **IbyteToComplex** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override

Returns "Ibyte_To_Complex".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.248.1 Detailed Description

Adapts an I/Q interleaved byte integer sample stream to a gr_complex (float) stream.

Definition at line 39 of file [ibyte_to_complex.h](#).

12.248.2 Member Function Documentation

12.248.2.1 connect()

```
void IbyteToComplex::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.248.2.2 disconnect()

```
void IbyteToComplex::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.248.2.3 get_left_block()

```
gr::basic_block_sptr IbyteToComplex::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.248.2.4 get_right_block()

```
gr::basic_block_sptr IbyteToComplex::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.248.2.5 implementation()

```
std::string IbyteToComplex::implementation () [inline], [override], [virtual]
```

Returns "Ibyte_To_Complex".

Implements [GNSSBlockInterface](#).

Definition at line 54 of file [ibyte_to_complex.h](#).

12.248.2.6 item_size()

```
size_t IbyteToComplex::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 59 of file [ibyte_to_complex.h](#).

12.248.2.7 role()

```
std::string IbyteToComplex::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [ibyte_to_complex.h](#).

The documentation for this class was generated from the following file:

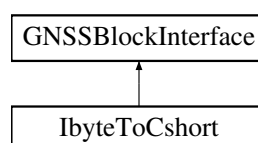
- [ibyte_to_complex.h](#)

12.249 IbyteToCshort Class Reference

Adapts a short integer (16 bits) interleaved sample stream into a `std::complex<short>` stream.

```
#include <ibyte_to_cshort.h>
```

Inheritance diagram for IbyteToCshort:



Public Member Functions

- **IbyteToCshort** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override
Returns "Ibyte_To_Cshort".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.249.1 Detailed Description

Adapts a short integer (16 bits) interleaved sample stream into a std::complex<short> stream.
Definition at line 39 of file [ibyte_to_cshort.h](#).

12.249.2 Member Function Documentation

12.249.2.1 connect()

```
void IbyteToCshort::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.249.2.2 disconnect()

```
void IbyteToCshort::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.249.2.3 get_left_block()

```
gr::basic_block_sptr IbyteToCshort::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.249.2.4 get_right_block()

```
gr::basic_block_sptr IbyteToCshort::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.249.2.5 implementation()

```
std::string IbyteToCshort::implementation () [inline], [override], [virtual]
```

Returns "Ibyte_To_Cshort".
Implements [GNSSBlockInterface](#).
Definition at line 54 of file [ibyte_to_cshort.h](#).

12.249.2.6 item_size()

```
size_t IbyteToCshort::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 59 of file [ibyte_to_cshort.h](#).

12.249.2.7 role()

```
std::string IbyteToCshort::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [ibyte_to_cshort.h](#).

The documentation for this class was generated from the following file:

- [ibyte_to_cshort.h](#)

12.250 INIReader Class Reference

Read an INI file into easy-to-access name/value pairs. (Note that I've gone for simplicity here rather than speed, but it should be pretty decent.)

```
#include <INIReader.h>
```

Public Member Functions

- [INIReader](#) (const std::string &filename)
Construct [INIReader](#) and parse given filename. See [ini.h](#) for more info about the parsing.
- int [ParseError](#) () const
Return the result of [ini_parse\(\)](#), i.e., 0 on success, line number of first error on parse error, or -1 on file open error.
- std::string [Get](#) (const std::string §ion, const std::string &name, const std::string &default_value)
Get a string value from INI file, returning default_value if not found.
- int64_t [GetInteger](#) (const std::string §ion, const std::string &name, int64_t default_value)
Get an integer (long) value from INI file, returning default_value if not found.
- bool [HasSection](#) (const std::string §ion) const
Return true if the given section exists (section must contain at least one name=value pair).
- bool [HasValue](#) (const std::string §ion, const std::string &name) const
Return true if a value exists with the given section and field names.

12.250.1 Detailed Description

Read an INI file into easy-to-access name/value pairs. (Note that I've gone for simplicity here rather than speed, but it should be pretty decent.)

Definition at line 45 of file [INIReader.h](#).

12.250.2 Constructor & Destructor Documentation

12.250.2.1 INIReader()

```
INIReader::INIReader (
    const std::string & filename) [explicit]
```

Construct [INIReader](#) and parse given filename. See [ini.h](#) for more info about the parsing.

12.250.3 Member Function Documentation

12.250.3.1 Get()

```
std::string INIReader::Get (
    const std::string & section,
    const std::string & name,
    const std::string & default_value)
```

Get a string value from INI file, returning default_value if not found.

12.250.3.2 GetInteger()

```
int64_t INIReader::GetInteger (
    const std::string & section,
    const std::string & name,
    int64_t default_value)
```

Get an integer (long) value from INI file, returning default_value if not found.

12.250.3.3 HasSection()

```
bool INIReader::HasSection (
    const std::string & section) const
```

Return true if the given section exists (section must contain at least one name=value pair).

12.250.3.4 HasValue()

```
bool INIReader::HasValue (
    const std::string & section,
    const std::string & name) const
```

Return true if a value exists with the given section and field names.

12.250.3.5 ParseError()

```
int INIReader::ParseError () const
```

Return the result of `ini_parse()`, i.e., 0 on success, line number of first error on parse error, or -1 on file open error.

The documentation for this class was generated from the following file:

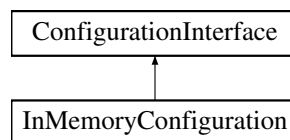
- [INIReader.h](#)

12.251 InMemoryConfiguration Class Reference

This class is an implementation of the interface [ConfigurationInterface](#).

```
#include <in_memory_configuration.h>
```

Inheritance diagram for InMemoryConfiguration:



Public Member Functions

- `std::string property (std::string property_name, std::string default_value) const` override
- `bool property (std::string property_name, bool default_value) const` override
- `int64_t property (std::string property_name, int64_t default_value) const` override
- `uint64_t property (std::string property_name, uint64_t default_value) const` override
- `int32_t property (std::string property_name, int32_t default_value) const` override
- `uint32_t property (std::string property_name, uint32_t default_value) const` override
- `int16_t property (std::string property_name, int16_t default_value) const` override
- `uint16_t property (std::string property_name, uint16_t default_value) const` override
- `float property (std::string property_name, float default_value) const` override
- `double property (std::string property_name, double default_value) const` override
- `void set_property (std::string property_name, std::string value) override`
- `void supersede_property (const std::string &property_name, const std::string &value)`
- `bool is_present (const std::string &property_name) const` override

12.251.1 Detailed Description

This class is an implementation of the interface [ConfigurationInterface](#).

This implementation accepts configuration parameters upon instantiation and it is intended to be used in unit testing.

Definition at line 43 of file [in_memory_configuration.h](#).

12.251.2 Member Function Documentation

12.251.2.1 `is_present()`

```
bool InMemoryConfiguration::is_present (
    const std::string & property_name) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.251.2.2 `property()` [1/10]

```
bool InMemoryConfiguration::property (
    std::string property_name,
    bool default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.251.2.3 `property()` [2/10]

```
double InMemoryConfiguration::property (
    std::string property_name,
    double default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.251.2.4 `property()` [3/10]

```
float InMemoryConfiguration::property (
    std::string property_name,
    float default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.251.2.5 `property()` [4/10]

```
int16_t InMemoryConfiguration::property (
    std::string property_name,
    int16_t default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.251.2.6 `property()` [5/10]

```
int32_t InMemoryConfiguration::property (
    std::string property_name,
    int32_t default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.251.2.7 `property()` [6/10]

```
int64_t InMemoryConfiguration::property (
    std::string property_name,
    int64_t default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.251.2.8 `property()` [7/10]

```
std::string InMemoryConfiguration::property (
    std::string property_name,
    std::string default_value) const [override], [virtual]
```


Implements [ConfigurationInterface](#).

12.251.2.9 property() [8/10]

```
uint16_t InMemoryConfiguration::property (
    std::string property_name,
    uint16_t default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.251.2.10 property() [9/10]

```
uint32_t InMemoryConfiguration::property (
    std::string property_name,
    uint32_t default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.251.2.11 property() [10/10]

```
uint64_t InMemoryConfiguration::property (
    std::string property_name,
    uint64_t default_value) const [override], [virtual]
```

Implements [ConfigurationInterface](#).

12.251.2.12 set_property()

```
void InMemoryConfiguration::set_property (
    std::string property_name,
    std::string value) [override], [virtual]
```

Implements [ConfigurationInterface](#).

The documentation for this class was generated from the following file:

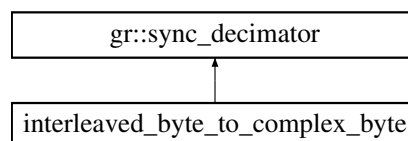
- [in_memory_configuration.h](#)

12.252 interleaved_byte_to_complex_byte Class Reference

This class adapts an 8-bits interleaved sample stream into a 16-bits complex stream (`std::complex<unsigned char>`)

```
#include <interleaved_byte_to_complex_byte.h>
```

Inheritance diagram for `interleaved_byte_to_complex_byte`:



Public Member Functions

- `int work` (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- `interleaved_byte_to_complex_byte_sptr make_interleaved_byte_to_complex_byte ()`

12.252.1 Detailed Description

This class adapts an 8-bits interleaved sample stream into a 16-bits complex stream (`std::complex<unsigned char>`)

Definition at line 40 of file [interleaved_byte_to_complex_byte.h](#).

The documentation for this class was generated from the following file:

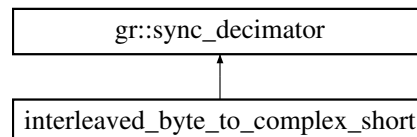
- [interleaved_byte_to_complex_byte.h](#)

12.253 interleaved_byte_to_complex_short Class Reference

This class adapts a short (16-bits) interleaved sample stream into a `std::complex<short>` stream.

`#include <interleaved_byte_to_complex_short.h>`

Inheritance diagram for `interleaved_byte_to_complex_short`:



Public Member Functions

- `int work (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)`

Friends

- `interleaved_byte_to_complex_short_sptr make_interleaved_byte_to_complex_short ()`

12.253.1 Detailed Description

This class adapts a short (16-bits) interleaved sample stream into a `std::complex<short>` stream.

Definition at line 40 of file [interleaved_byte_to_complex_short.h](#).

The documentation for this class was generated from the following file:

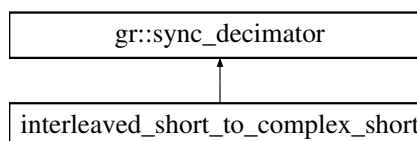
- [interleaved_byte_to_complex_short.h](#)

12.254 interleaved_short_to_complex_short Class Reference

This class adapts a short (16-bits) interleaved sample stream into a `std::complex<short>` stream.

`#include <interleaved_short_to_complex_short.h>`

Inheritance diagram for `interleaved_short_to_complex_short`:



Public Member Functions

- `int work (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)`

Friends

- `interleaved_short_to_complex_short_sptr make_interleaved_short_to_complex_short ()`

12.254.1 Detailed Description

This class adapts a short (16-bits) interleaved sample stream into a `std::complex<short>` stream.

Definition at line 39 of file [interleaved_short_to_complex_short.h](#).

The documentation for this class was generated from the following file:

- [interleaved_short_to_complex_short.h](#)

12.255 IONGSMSChunkData Class Reference

Public Member Functions

- **IONGSMSChunkData** (const GnssMetadata::Chunk &chunk, const std::vector< std::string > &stream_ids, std::size_t output_stream_offset)
- **IONGSMSChunkData** (const [IONGSMSChunkData](#) &rh1)=delete
- **IONGSMSChunkData** & **operator=** (const [IONGSMSChunkData](#) &rh1)=delete
- **IONGSMSChunkData** ([IONGSMSChunkData](#) &&rh1)=delete
- **IONGSMSChunkData** & **operator=** ([IONGSMSChunkData](#) &&rh1)=delete
- std::size_t **read_from_buffer** (uint8_t *buffer, std::size_t offset)
- void **write_to_output** (gr_vector_void_star &outputs, std::vector< int > &output_items)
- std::size_t **output_stream_count** () const
- std::size_t **output_stream_item_size** (std::size_t stream_index) const
- std::size_t **output_stream_item_rate** (std::size_t stream_index) const

12.255.1 Detailed Description

Definition at line 112 of file [ion_gsms_chunk_data.h](#).

The documentation for this class was generated from the following file:

- [ion_gsms_chunk_data.h](#)

12.256 IONGSMSChunkUnpackingCtx< WT > Struct Template Reference

Public Member Functions

- [IONGSMSChunkUnpackingCtx](#) (const GnssMetadata::Chunk::WordShift word_shift, WT *data_buffer, uint8_t data_buffer_word_count)
- void [advance_word](#) ()
- void [shift_current_word](#) (uint8_t n)
- void [shift_padding](#) (uint8_t n_bits)
- template<typename OT>
void [shift_sample](#) (uint8_t sample_bitsize, OT *output, uint8_t output_bit_offset=0)

Public Attributes

- const GnssMetadata::Chunk::WordShift [word_shift_direction_](#)
- WT * [iterator_](#) = nullptr
- WT [current_word_](#) {}
- uint8_t [bitshift_](#) = 0

Static Public Attributes

- static constexpr uint8_t [word_bitsize_](#) = sizeof(WT) * 8

12.256.1 Detailed Description

```
template<typename WT>
struct IONGSMSChunkUnpackingCtx< WT >
```

Definition at line 32 of file [ion_gsms_chunk_unpacking_ctx.h](#).

12.256.2 Constructor & Destructor Documentation

12.256.2.1 IONGSMSChunkUnpackingCtx()

```
template<typename WT>
IONGSMSChunkUnpackingCtx< WT >::IONGSMSChunkUnpackingCtx (
    const GnssMetadata::Chunk::WordShift word_shift,
    WT * data_buffer,
    uint8_t data_buffer_word_count) [inline]
```

Definition at line 41 of file [ion_gsms_chunk_unpacking_ctx.h](#).

12.256.3 Member Function Documentation

12.256.3.1 advance_word()

```
template<typename WT>
void IONGSMSChunkUnpackingCtx< WT >::advance_word () [inline]
```

Definition at line 60 of file [ion_gsms_chunk_unpacking_ctx.h](#).

12.256.3.2 shift_current_word()

```
template<typename WT>
void IONGSMSChunkUnpackingCtx< WT >::shift_current_word (
    uint8_t n) [inline]
```

Definition at line 75 of file [ion_gsms_chunk_unpacking_ctx.h](#).

12.256.3.3 shift_padding()

```
template<typename WT>
void IONGSMSChunkUnpackingCtx< WT >::shift_padding (
    uint8_t n_bits) [inline]
```

Definition at line 103 of file [ion_gsms_chunk_unpacking_ctx.h](#).

12.256.3.4 shift_sample()

```
template<typename WT>
template<typename OT>
void IONGSMSChunkUnpackingCtx< WT >::shift_sample (
    uint8_t sample_bitsize,
    OT * output,
    uint8_t output_bit_offset = 0) [inline]
```

Definition at line 124 of file [ion_gsms_chunk_unpacking_ctx.h](#).

12.256.4 Member Data Documentation

12.256.4.1 bitshift_

```
template<typename WT>
uint8_t IONGSMSChunkUnpackingCtx< WT >::bitshift_ = 0
```

Definition at line 39 of file [ion_gsms_chunk_unpacking_ctx.h](#).

12.256.4.2 current_word_

```
template<typename WT>
WT IONGSMSChunkUnpackingCtx< WT >::current_word_ {}
```

Definition at line 38 of file [ion_gsms_chunk_unpacking_ctx.h](#).

12.256.4.3 iterator_

```
template<typename WT>
WT* IONGSMSChunkUnpackingCtx< WT >::iterator_ = nullptr
```

Definition at line 37 of file [ion_gsms_chunk_unpacking_ctx.h](#).

12.256.4.4 word_bitsize_

```
template<typename WT>
uint8_t IONGSMSChunkUnpackingCtx< WT >::word_bitsize_ = sizeof(WT) * 8 [static], [constexpr]
```

Definition at line 34 of file [ion_gsms_chunk_unpacking_ctx.h](#).

12.256.4.5 word_shift_direction_

```
template<typename WT>
const GnssMetadata::Chunk::WordShift IONGSMSChunkUnpackingCtx< WT >::word_shift_direction_
```

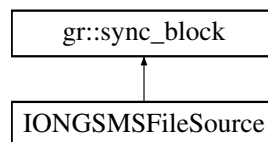
Definition at line 36 of file [ion_gsms_chunk_unpacking_ctx.h](#).

The documentation for this struct was generated from the following file:

- [ion_gsms_chunk_unpacking_ctx.h](#)

12.257 IONGSMSFileSource Class Reference

Inheritance diagram for IONGSMSFileSource:



Public Types

- using [sptr](#) = gnss_shared_ptr<[IONGSMSFileSource](#)>

Public Member Functions

- **IONGSMSFileSource** (const fs::path &metadata_filepath, const GnssMetadata::File &file, const GnssMetadata::Block &block, const std::vector< std::string > &stream_ids)
- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
- std::size_t **output_stream_count** () const
- std::size_t **output_stream_item_size** (std::size_t stream_index) const
- std::size_t **output_stream_total_sample_count** (std::size_t stream_index) const

12.257.1 Detailed Description

Definition at line 36 of file [ion_gsms.h](#).

12.257.2 Member Typedef Documentation

12.257.2.1 sptr

using IONGSMSFileSource::sptr = gnss_shared_ptr<IONGSMSFileSource>

Definition at line 39 of file [ion_gsms.h](#).

The documentation for this class was generated from the following file:

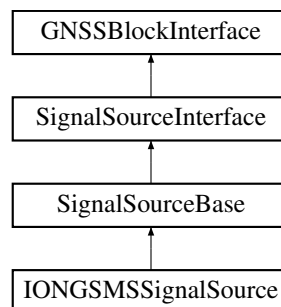
- [ion_gsms.h](#)

12.258 IONGSMSSignalSource Class Reference

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

```
#include <ion_gsms_signal_source.h>
```

Inheritance diagram for IONGSMSSignalSource:



Public Member Functions

- **IONGSMSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue)

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Protected Member Functions

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- gr::basic_block_sptr [get_right_block](#) (int RF_channel) override
- size_t [item_size](#) () override

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↵ error=false)
utility for decoding passed ".item_type" values

12.258.1 Detailed Description

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

Definition at line 40 of file [ion_gsms_signal_source.h](#).

12.258.2 Member Function Documentation

12.258.2.1 connect()

```
void IONGSMSSignalSource::connect (
    gr::top_block_sptr top_block) [override], [protected], [virtual]
```

Implements [GNSSBlockInterface](#).

12.258.2.2 disconnect()

```
void IONGSMSSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [protected], [virtual]
```

Implements [GNSSBlockInterface](#).

12.258.2.3 get_left_block()

```
gr::basic_block_sptr IONGSMSSignalSource::get_left_block () [override], [protected], [virtual]
```

Implements [GNSSBlockInterface](#).

12.258.2.4 get_right_block() [1/2]

```
gr::basic_block_sptr IONGSMSSignalSource::get_right_block () [override], [protected], [virtual]
```

Implements [GNSSBlockInterface](#).

12.258.2.5 get_right_block() [2/2]

```
gr::basic_block_sptr IONGSMSSignalSource::get_right_block (
    int RF_channel) [override], [protected], [virtual]
```

Reimplemented from [GNSSBlockInterface](#).

12.258.2.6 item_size()

```
size_t IONGSMSSignalSource::item_size () [inline], [override], [protected], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 57 of file [ion_gsms_signal_source.h](#).

The documentation for this class was generated from the following file:

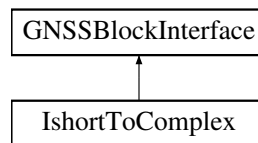
- [ion_gsms_signal_source.h](#)

12.259 IshortToComplex Class Reference

Adapts an I/Q interleaved short integer sample stream to a gr_complex (float) stream.

```
#include <ishort_to_complex.h>
```

Inheritance diagram for IshortToComplex:



Public Member Functions

- **IshortToComplex** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override
Returns "Ishort_To_Complex".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.259.1 Detailed Description

Adapts an I/Q interleaved short integer sample stream to a gr_complex (float) stream.
Definition at line 39 of file [ishort_to_complex.h](#).

12.259.2 Member Function Documentation

12.259.2.1 connect()

```
void IshortToComplex::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.259.2.2 disconnect()

```
void IshortToComplex::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.259.2.3 get_left_block()

```
gr::basic_block_sptr IshortToComplex::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.259.2.4 get_right_block()

```
gr::basic_block_sptr IshortToComplex::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.259.2.5 implementation()

```
std::string IshortToComplex::implementation () [inline], [override], [virtual]
```

Returns "Ishort_To_Complex".

Implements [GNSSBlockInterface](#).

Definition at line 54 of file [ishort_to_complex.h](#).

12.259.2.6 item_size()

```
size_t IshortToComplex::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 59 of file [ishort_to_complex.h](#).

12.259.2.7 role()

```
std::string IshortToComplex::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [ishort_to_complex.h](#).

The documentation for this class was generated from the following file:

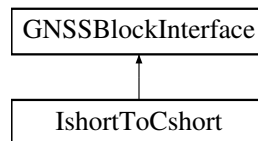
- [ishort_to_complex.h](#)

12.260 IshortToCshort Class Reference

Adapts a short integer (16 bits) interleaved sample stream into a `std::complex<short>` stream.

```
#include <ishort_to_cshort.h>
```

Inheritance diagram for IshortToCshort:



Public Member Functions

- **IshortToCshort** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override

Returns "Ishort_To_Cshort".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.260.1 Detailed Description

Adapts a short integer (16 bits) interleaved sample stream into a `std::complex<short>` stream.

Definition at line 39 of file [ishort_to_cshort.h](#).

12.260.2 Member Function Documentation

12.260.2.1 connect()

```
void IshortToCshort::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.260.2.2 disconnect()

```
void IshortToCshort::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.260.2.3 get_left_block()

```
gr::basic_block_sptr IshortToCshort::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.260.2.4 get_right_block()

```
gr::basic_block_sptr IshortToCshort::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.260.2.5 implementation()

```
std::string IshortToCshort::implementation () [inline], [override], [virtual]
```

Returns "Ishort_To_Cshort".

Implements [GNSSBlockInterface](#).

Definition at line 54 of file [ishort_to_cshort.h](#).

12.260.2.6 item_size()

```
size_t IshortToCshort::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 59 of file [ishort_to_cshort.h](#).

12.260.2.7 role()

```
std::string IshortToCshort::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [ishort_to_cshort.h](#).

The documentation for this class was generated from the following file:

- [ishort_to_cshort.h](#)

12.261 kernel_info_t Struct Reference

Public Attributes

- cl_kernel [kernel](#)
- char * [kernel_name](#)
- unsigned [lmem_size](#)
- unsigned [num_workgroups](#)
- unsigned [num_xforms_per_workgroup](#)
- unsigned [num_workitems_per_workgroup](#)
- cl_fft_kernel_dir [dir](#)
- int [in_place_possible](#)
- [kernel_info_t](#) * [next](#)

12.261.1 Detailed Description

Definition at line 32 of file [fft_internal.h](#).

12.261.2 Member Data Documentation

12.261.2.1 dir

```
cl_fft_kernel_dir kernel_info_t::dir
```

Definition at line 40 of file [fft_internal.h](#).

12.261.2.2 in_place_possible

```
int kernel_info_t::in_place_possible
```

Definition at line 41 of file [fft_internal.h](#).

12.261.2.3 kernel

```
cl_kernel kernel_info_t::kernel
```

Definition at line 34 of file [fft_internal.h](#).

12.261.2.4 kernel_name

```
char* kernel_info_t::kernel_name
```

Definition at line 35 of file [fft_internal.h](#).

12.261.2.5 lmem_size

```
unsigned kernel_info_t::lmem_size
```

Definition at line 36 of file [fft_internal.h](#).

12.261.2.6 next

```
kernel_info_t* kernel_info_t::next
```

Definition at line 42 of file [fft_internal.h](#).

12.261.2.7 num_workgroups

```
unsigned kernel_info_t::num_workgroups
```

Definition at line 37 of file [fft_internal.h](#).

12.261.2.8 num_workitems_per_workgroup

```
unsigned kernel_info_t::num_workitems_per_workgroup
```

Definition at line 39 of file [fft_internal.h](#).

12.261.2.9 num_xforms_per_workgroup

```
unsigned kernel_info_t::num_xforms_per_workgroup
```

Definition at line 38 of file [fft_internal.h](#).

The documentation for this struct was generated from the following file:

- [fft_internal.h](#)

12.262 Kf_Conf Class Reference

Public Member Functions

- void **SetFromConfiguration** (const [ConfigurationInterface](#) *configuration, const std::string &role)

Public Attributes

- `std::string item_type`
- `std::string dump_filename`
- `double fs_in`
- `double carrier_lock_th`
- `double code_disc_sd_chips`
- `double carrier_disc_sd_rads`
- `double code_phase_sd_chips`
- `double carrier_phase_sd_rad`
- `double carrier_freq_sd_hz`
- `double carrier_freq_rate_sd_hz_s`
- `double init_code_phase_sd_chips`
- `double init_carrier_phase_sd_rad`
- `double init_carrier_freq_sd_hz`
- `double init_carrier_freq_rate_sd_hz_s`
- `float early_late_space_chips`
- `float very_early_late_space_chips`
- `float early_late_space_narrow_chips`
- `float very_early_late_space_narrow_chips`
- `float slope`
- `float spc`
- `float y_intercept`
- `float cn0_smoother_alpha`
- `float carrier_lock_test_smoother_alpha`
- `uint32_t pull_in_time_s`
- `uint32_t bit_synchronization_time_limit_s`
- `uint32_t vector_length`
- `uint32_t smoother_length`
- `int32_t extend_correlation_symbols`
- `int32_t cn0_samples`
- `int32_t cn0_smoother_samples`
- `int32_t carrier_lock_test_smoother_samples`
- `int32_t cn0_min`
- `int32_t max_code_lock_fail`
- `int32_t max_carrier_lock_fail`
- `char signal [3] {}`
- `char system`
- `bool track_pilot`
- `bool enable_doppler_correction`
- `bool high_dyn`
- `bool dump`
- `bool dump_mat`

12.262.1 Detailed Description

Definition at line 29 of file `kf_conf.h`.

12.262.2 Member Data Documentation

12.262.2.1 bit_synchronization_time_limit_s

`uint32_t Kf_Conf::bit_synchronization_time_limit_s`

Definition at line 67 of file `kf_conf.h`.

12.262.2.2 carrier_disc_sd_rads

double Kf_Conf::carrier_disc_sd_rads
Definition at line 43 of file [kf_conf.h](#).

12.262.2.3 carrier_freq_rate_sd_hz_s

double Kf_Conf::carrier_freq_rate_sd_hz_s
Definition at line 49 of file [kf_conf.h](#).

12.262.2.4 carrier_freq_sd_hz

double Kf_Conf::carrier_freq_sd_hz
Definition at line 48 of file [kf_conf.h](#).

12.262.2.5 carrier_lock_test_smoother_alpha

float Kf_Conf::carrier_lock_test_smoother_alpha
Definition at line 65 of file [kf_conf.h](#).

12.262.2.6 carrier_lock_test_smoother_samples

int32_t Kf_Conf::carrier_lock_test_smoother_samples
Definition at line 73 of file [kf_conf.h](#).

12.262.2.7 carrier_lock_th

double Kf_Conf::carrier_lock_th
Definition at line 38 of file [kf_conf.h](#).

12.262.2.8 carrier_phase_sd_rad

double Kf_Conf::carrier_phase_sd_rad
Definition at line 47 of file [kf_conf.h](#).

12.262.2.9 cn0_min

int32_t Kf_Conf::cn0_min
Definition at line 74 of file [kf_conf.h](#).

12.262.2.10 cn0_samples

int32_t Kf_Conf::cn0_samples
Definition at line 71 of file [kf_conf.h](#).

12.262.2.11 cn0_smoother_alpha

float Kf_Conf::cn0_smoother_alpha
Definition at line 64 of file [kf_conf.h](#).

12.262.2.12 cn0_smoother_samples

int32_t Kf_Conf::cn0_smoother_samples
Definition at line 72 of file [kf_conf.h](#).

12.262.2.13 code_disc_sd_chips

double Kf_Conf::code_disc_sd_chips
Definition at line 42 of file [kf_conf.h](#).

12.262.2.14 code_phase_sd_chips

double Kf_Conf::code_phase_sd_chips
Definition at line 46 of file [kf_conf.h](#).

12.262.2.15 dump

bool Kf_Conf::dump
Definition at line 82 of file [kf_conf.h](#).

12.262.2.16 dump_filename

std::string Kf_Conf::dump_filename
Definition at line 36 of file [kf_conf.h](#).

12.262.2.17 dump_mat

bool Kf_Conf::dump_mat
Definition at line 83 of file [kf_conf.h](#).

12.262.2.18 early_late_space_chips

float Kf_Conf::early_late_space_chips
Definition at line 57 of file [kf_conf.h](#).

12.262.2.19 early_late_space_narrow_chips

float Kf_Conf::early_late_space_narrow_chips
Definition at line 59 of file [kf_conf.h](#).

12.262.2.20 enable_doppler_correction

bool Kf_Conf::enable_doppler_correction
Definition at line 80 of file [kf_conf.h](#).

12.262.2.21 extend_correlation_symbols

int32_t Kf_Conf::extend_correlation_symbols
Definition at line 70 of file [kf_conf.h](#).

12.262.2.22 fs_in

double Kf_Conf::fs_in
Definition at line 37 of file [kf_conf.h](#).

12.262.2.23 high_dyn

bool Kf_Conf::high_dyn
Definition at line 81 of file [kf_conf.h](#).

12.262.2.24 init_carrier_freq_rate_sd_hz_s

double Kf_Conf::init_carrier_freq_rate_sd_hz_s
Definition at line 55 of file [kf_conf.h](#).

12.262.2.25 init_carrier_freq_sd_hz

double Kf_Conf::init_carrier_freq_sd_hz
Definition at line 54 of file [kf_conf.h](#).

12.262.2.26 init_carrier_phase_sd_rad

double Kf_Conf::init_carrier_phase_sd_rad
Definition at line 53 of file [kf_conf.h](#).

12.262.2.27 init_code_phase_sd_chips

double Kf_Conf::init_code_phase_sd_chips
Definition at line 52 of file [kf_conf.h](#).

12.262.2.28 item_type

std::string Kf_Conf::item_type
Definition at line 35 of file [kf_conf.h](#).

12.262.2.29 max_carrier_lock_fail

int32_t Kf_Conf::max_carrier_lock_fail
Definition at line 76 of file [kf_conf.h](#).

12.262.2.30 max_code_lock_fail

int32_t Kf_Conf::max_code_lock_fail
Definition at line 75 of file [kf_conf.h](#).

12.262.2.31 pull_in_time_s

uint32_t Kf_Conf::pull_in_time_s
Definition at line 66 of file [kf_conf.h](#).

12.262.2.32 signal

char Kf_Conf::signal[3] {}
Definition at line 77 of file [kf_conf.h](#).

12.262.2.33 slope

float Kf_Conf::slope
Definition at line 61 of file [kf_conf.h](#).

12.262.2.34 smoother_length

uint32_t Kf_Conf::smoother_length
Definition at line 69 of file [kf_conf.h](#).

12.262.2.35 spc

float Kf_Conf::spc
Definition at line 62 of file [kf_conf.h](#).

12.262.2.36 system

char Kf_Conf::system
Definition at line 78 of file [kf_conf.h](#).

12.262.2.37 track_pilot

bool Kf_Conf::track_pilot
Definition at line 79 of file [kf_conf.h](#).

12.262.2.38 vector_length

uint32_t Kf_Conf::vector_length
 Definition at line 68 of file [kf_conf.h](#).

12.262.2.39 very_early_late_space_chips

float Kf_Conf::very_early_late_space_chips
 Definition at line 58 of file [kf_conf.h](#).

12.262.2.40 very_early_late_space_narrow_chips

float Kf_Conf::very_early_late_space_narrow_chips
 Definition at line 60 of file [kf_conf.h](#).

12.262.2.41 y_intercept

float Kf_Conf::y_intercept
 Definition at line 63 of file [kf_conf.h](#).

The documentation for this class was generated from the following file:

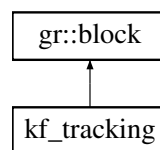
- [kf_conf.h](#)

12.263 kf_tracking Class Reference

This class implements a code DLL + carrier PLL tracking block.

`#include <kf_tracking.h>`

Inheritance diagram for `kf_tracking`:

**Public Member Functions**

- void **set_channel** (uint32_t channel)
- void **set_gnss_synchro** ([Gnss_Synchro](#) *p_gnss_synchro)
- void **start_tracking** ()
- void **stop_tracking** ()
- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)
- void **forecast** (int noutput_items, gr_vector_int &ninput_items_required)

Friends

- `kf_tracking_sptr` **kf_make_tracking** (const [Kf_Conf](#) &conf_)

12.263.1 Detailed Description

This class implements a code DLL + carrier PLL tracking block.

Definition at line 60 of file [kf_tracking.h](#).

The documentation for this class was generated from the following file:

- [kf_tracking.h](#)

12.264 Kml_Printer Class Reference

Prints PVT information to OGC KML format file (can be viewed with Google Earth)

```
#include <kml_printer.h>
```

Public Member Functions

- **Kml_Printer** (const std::string &base_path=std::string("."))
- bool **set_headers** (const std::string &filename, bool time_tag_name=true)
- bool **print_position** (const [Pvt_Solution](#) *const position)
- bool **close_file** ()

12.264.1 Detailed Description

Prints PVT information to OGC KML format file (can be viewed with Google Earth)

See <https://www.opengeospatial.org/standards/kml>

Definition at line 38 of file [kml_printer.h](#).

The documentation for this class was generated from the following file:

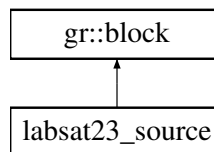
- [kml_printer.h](#)

12.265 labsat23_source Class Reference

This class implements conversion between Labsat 2, 3 and 3 Wideband formats to gr_complex.

```
#include <labsat23_source.h>
```

Inheritance diagram for labsat23_source:



Public Member Functions

- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- labsat23_source_sptr **labsat23_make_source_sptr** (const char *signal_file_basename, const std::vector<int > &channel_selector, [Concurrent_Queue](#)< pmt::pmt_t > *queue, bool digital_io_enabled, double seconds_to_skip)

12.265.1 Detailed Description

This class implements conversion between Labsat 2, 3 and 3 Wideband formats to gr_complex.

Definition at line 56 of file [labsat23_source.h](#).

The documentation for this class was generated from the following file:

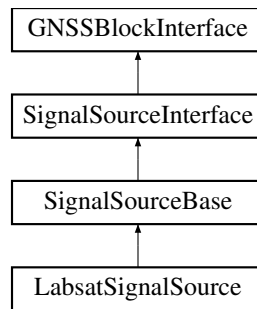
- [labsat23_source.h](#)

12.266 LabsatSignalSource Class Reference

This class reads samples stored in LabSat version 2, 3, and 3 Wideband format.

```
#include <labsat_signal_source.h>
```

Inheritance diagram for LabsatSignalSource:



Public Member Functions

- **LabsatSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- size_t [getRfChannels](#) () const override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- gr::basic_block_sptr [get_right_block](#) (int i) override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_error=false)
utility for decoding passed ".item_type" values

12.266.1 Detailed Description

This class reads samples stored in LabSat version 2, 3, and 3 Wideband format.
Definition at line 44 of file [labsat_signal_source.h](#).

12.266.2 Member Function Documentation

12.266.2.1 connect()

```
void LabsatSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.266.2.2 disconnect()

```
void LabsatSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.266.2.3 get_left_block()

```
gr::basic_block_sptr LabsatSignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.266.2.4 get_right_block() [1/2]

```
gr::basic_block_sptr LabsatSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.266.2.5 get_right_block() [2/2]

```
gr::basic_block_sptr LabsatSignalSource::get_right_block (
    int i) [override], [virtual]
```

Reimplemented from [GNSSBlockInterface](#).

12.266.2.6 getRfChannels()

```
size_t LabsatSignalSource::getRfChannels () const [override], [virtual]
```

Implements [SignalSourceInterface](#).

12.266.2.7 item_size()

```
size_t LabsatSignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 53 of file [labsat_signal_source.h](#).

The documentation for this class was generated from the following file:

- [labsat_signal_source.h](#)

12.267 lex_t Struct Reference**Public Attributes**

- int [n](#)
- int [nmax](#)
- [lexmsg_t](#) * [msgs](#)

12.267.1 Detailed Description

Definition at line 689 of file [rtklib.h](#).

12.267.2 Member Data Documentation**12.267.2.1 msgs**

```
lexmsg\_t* lex\_t::msgs
```

Definition at line 692 of file [rtklib.h](#).

12.267.2.2 n

```
int lex\_t::n
```

Definition at line 691 of file [rtklib.h](#).

12.267.2.3 nmax

`int lex_t::nmax`

Definition at line 691 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.268 lexeph_t Struct Reference

Public Attributes

- [gtime_t](#) toe
- [gtime_t](#) tof
- int sat
- unsigned char health
- unsigned char ura
- double pos [3]
- double vel [3]
- double acc [3]
- double jerk [3]
- double af0
- double af1
- double tgd
- double isc [8]

12.268.1 Detailed Description

Definition at line 696 of file [rtklib.h](#).

12.268.2 Member Data Documentation

12.268.2.1 acc

`double lexeph_t::acc[3]`

Definition at line 705 of file [rtklib.h](#).

12.268.2.2 af0

`double lexeph_t::af0`

Definition at line 707 of file [rtklib.h](#).

12.268.2.3 af1

`double lexeph_t::af1`

Definition at line 707 of file [rtklib.h](#).

12.268.2.4 health

`unsigned char lexeph_t::health`

Definition at line 701 of file [rtklib.h](#).

12.268.2.5 isc

`double lexeph_t::isc[8]`

Definition at line 709 of file [rtklib.h](#).

12.268.2.6 jerk

```
double lexeph_t::jerk[3]
```

Definition at line 706 of file [rtklib.h](#).

12.268.2.7 pos

```
double lexeph_t::pos[3]
```

Definition at line 703 of file [rtklib.h](#).

12.268.2.8 sat

```
int lexeph_t::sat
```

Definition at line 700 of file [rtklib.h](#).

12.268.2.9 tgd

```
double lexeph_t::tgd
```

Definition at line 708 of file [rtklib.h](#).

12.268.2.10 toe

```
gtime_t lexeph_t::toe
```

Definition at line 698 of file [rtklib.h](#).

12.268.2.11 tof

```
gtime_t lexeph_t::tof
```

Definition at line 699 of file [rtklib.h](#).

12.268.2.12 ura

```
unsigned char lexeph_t::ura
```

Definition at line 702 of file [rtklib.h](#).

12.268.2.13 vel

```
double lexeph_t::vel[3]
```

Definition at line 704 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.269 lexion_t Struct Reference

Public Attributes

- [gtime_t](#) t0
- double [tspan](#)
- double [pos0](#) [2]
- double [coef](#) [3][2]

12.269.1 Detailed Description

Definition at line 713 of file [rtklib.h](#).

12.269.2 Member Data Documentation

12.269.2.1 coef

```
double lexion_t::coef[3][2]
```

Definition at line 718 of file [rtklib.h](#).

12.269.2.2 pos0

```
double lexion_t::pos0[2]
```

Definition at line 717 of file [rtklib.h](#).

12.269.2.3 t0

```
gtime_t lexion_t::t0
```

Definition at line 715 of file [rtklib.h](#).

12.269.2.4 tspan

```
double lexion_t::tspan
```

Definition at line 716 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.270 lexmsg_t Struct Reference

Public Attributes

- int [prn](#)
- int [type](#)
- int [alert](#)
- unsigned char [stat](#)
- unsigned char [snr](#)
- unsigned int [ttt](#)
- unsigned char [msg](#) [212]

12.270.1 Detailed Description

Definition at line 677 of file [rtklib.h](#).

12.270.2 Member Data Documentation

12.270.2.1 alert

```
int lexmsg_t::alert
```

Definition at line 681 of file [rtklib.h](#).

12.270.2.2 msg

```
unsigned char lexmsg_t::msg[212]
```

Definition at line 685 of file [rtklib.h](#).

12.270.2.3 prn

```
int lexmsg_t::prn
```

Definition at line 679 of file [rtklib.h](#).

12.270.2.4 snr

unsigned char lexmsg_t::snr
 Definition at line 683 of file [rtklib.h](#).

12.270.2.5 stat

unsigned char lexmsg_t::stat
 Definition at line 682 of file [rtklib.h](#).

12.270.2.6 ttt

unsigned int lexmsg_t::ttt
 Definition at line 684 of file [rtklib.h](#).

12.270.2.7 type

int lexmsg_t::type
 Definition at line 680 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

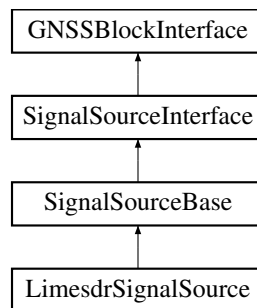
- [rtklib.h](#)

12.271 LimesdrSignalSource Class Reference

This class instantiates the LimeSDR gnuradio signal source. It has support also for a customized LimeSDR firmware and signal source to support PPS samplestamp reading.

```
#include <limesdr_signal_source.h>
```

Inheritance diagram for LimesdrSignalSource:

**Public Member Functions**

- **LimesdrSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from SignalSourceBase

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↵ error=false)
utility for decoding passed ".item_type" values

12.271.1 Detailed Description

This class instantiates the LimeSDR gnuradio signal source. It has support also for a customized LimeSDR firmware and signal source to support PPS samplestamp reading.

Definition at line 42 of file [limesdr_signal_source.h](#).

12.271.2 Member Function Documentation

12.271.2.1 connect()

```
void LimesdrSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.271.2.2 disconnect()

```
void LimesdrSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.271.2.3 get_left_block()

```
gr::basic_block_sptr LimesdrSignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.271.2.4 get_right_block()

```
gr::basic_block_sptr LimesdrSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.271.2.5 item_size()

```
size_t LimesdrSignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 51 of file [limesdr_signal_source.h](#).

The documentation for this class was generated from the following file:

- [limesdr_signal_source.h](#)

12.272 MACK_header Class Reference

Public Attributes

- uint64_t [tag0](#) {}
- uint16_t [macseq](#) {}
- uint8_t [cop](#) {}

12.272.1 Detailed Description

Definition at line 53 of file [osnma_data.h](#).

12.272.2 Member Data Documentation

12.272.2.1 cop

```
uint8_t MACK_header::cop {}
```

Definition at line 59 of file [osnma_data.h](#).

12.272.2.2 macseq

```
uint16_t MACK_header::macseq {}
```

Definition at line 58 of file [osnma_data.h](#).

12.272.2.3 tag0

```
uint64_t MACK_header::tag0 {}
```

Definition at line 57 of file [osnma_data.h](#).

The documentation for this class was generated from the following file:

- [osnma_data.h](#)

12.273 Mack_lookup Class Reference

Public Member Functions

- [Mack_lookup](#) (uint8_t msg_, uint8_t nt_, const std::vector< std::string > &s1_, const std::vector< std::string > &s2_)

Public Attributes

- uint8_t [msg](#) {}
- uint8_t [nt](#) {}
- std::vector< std::string > [sequence1](#)
- std::vector< std::string > [sequence2](#)

12.273.1 Detailed Description

Definition at line 166 of file [Galileo_OSNMA.h](#).

12.273.2 Constructor & Destructor Documentation

12.273.2.1 Mack_lookup()

```
Mack_lookup::Mack_lookup (
    uint8_t msg_,
    uint8_t nt_,
    const std::vector< std::string > & s1_,
    const std::vector< std::string > & s2_) [inline]
```

Definition at line 170 of file [Galileo_OSNMA.h](#).

12.273.3 Member Data Documentation

12.273.3.1 msg

```
uint8_t Mack_lookup::msg {}
```

Definition at line 177 of file [Galileo_OSNMA.h](#).

12.273.3.2 nt

```
uint8_t Mack_lookup::nt {}
```

Definition at line 178 of file [Galileo_OSNMA.h](#).

12.273.3.3 sequence1

```
std::vector<std::string> Mack_lookup::sequence1
```

Definition at line 179 of file [Galileo_OSNMA.h](#).

12.273.3.4 sequence2

```
std::vector<std::string> Mack_lookup::sequence2
```

Definition at line 180 of file [Galileo_OSNMA.h](#).

The documentation for this class was generated from the following file:

- [Galileo_OSNMA.h](#)

12.274 MACK_message Class Reference

Public Attributes

- [MACK_header](#) header
- std::vector< [MACK_tag_and_info](#) > tag_and_info
- std::vector< uint8_t > key
- uint32_t TOW
- uint32_t WN
- uint32_t PRNa

12.274.1 Detailed Description

Definition at line 123 of file [osnma_data.h](#).

12.274.2 Member Data Documentation

12.274.2.1 header

```
MACK\_header MACK_message::header
```

Definition at line 127 of file [osnma_data.h](#).

12.274.2.2 key

```
std::vector<uint8_t> MACK_message::key
```

Definition at line 129 of file [osnma_data.h](#).

12.274.2.3 PRNa

```
uint32_t MACK_message::PRNa
```

Definition at line 132 of file [osnma_data.h](#).

12.274.2.4 tag_and_info

```
std::vector<MACK\_tag\_and\_info> MACK_message::tag_and_info
```

Definition at line 128 of file [osnma_data.h](#).

12.274.2.5 TOW

`uint32_t MACK_message::TOW`

Definition at line 130 of file [osnma_data.h](#).

12.274.2.6 WN

`uint32_t MACK_message::WN`

Definition at line 131 of file [osnma_data.h](#).

The documentation for this class was generated from the following file:

- [osnma_data.h](#)

12.275 MACK_tag_and_info Class Reference

Public Attributes

- `uint64_t` [tag](#)
- [MACK_tag_info](#) [tag_info](#)
- `uint32_t` [counter](#)

12.275.1 Detailed Description

Definition at line 73 of file [osnma_data.h](#).

12.275.2 Member Data Documentation

12.275.2.1 counter

`uint32_t MACK_tag_and_info::counter`

Definition at line 79 of file [osnma_data.h](#).

12.275.2.2 tag

`uint64_t MACK_tag_and_info::tag`

Definition at line 77 of file [osnma_data.h](#).

12.275.2.3 tag_info

[MACK_tag_info](#) `MACK_tag_and_info::tag_info`

Definition at line 78 of file [osnma_data.h](#).

The documentation for this class was generated from the following file:

- [osnma_data.h](#)

12.276 MACK_tag_info Class Reference

Public Attributes

- `uint8_t` [PRN_d](#) {}
- `uint8_t` [ADKD](#) {}
- `uint8_t` [cop](#) {}

12.276.1 Detailed Description

Definition at line 63 of file [osnma_data.h](#).

12.276.2 Member Data Documentation

12.276.2.1 ADKD

`uint8_t MACK_tag_info::ADKD {}`

Definition at line 68 of file [osnma_data.h](#).

12.276.2.2 cop

`uint8_t MACK_tag_info::cop {}`

Definition at line 69 of file [osnma_data.h](#).

12.276.2.3 PRN_d

`uint8_t MACK_tag_info::PRN_d {}`

Definition at line 67 of file [osnma_data.h](#).

The documentation for this class was generated from the following file:

- [osnma_data.h](#)

12.277 matlab_type_traits< T > Struct Template Reference

12.277.1 Detailed Description

`template<typename T>`
`struct matlab_type_traits< T >`

Definition at line 26 of file [matlab_writer_helper.h](#).

The documentation for this struct was generated from the following file:

- [matlab_writer_helper.h](#)

12.278 matlab_type_traits< double > Struct Reference

Static Public Attributes

- static constexpr `matio_classes` [class_type](#) = `MAT_C_DOUBLE`
- static constexpr `matio_types` [data_type](#) = `MAT_T_DOUBLE`

12.278.1 Detailed Description

Definition at line 71 of file [matlab_writer_helper.h](#).

12.278.2 Member Data Documentation

12.278.2.1 class_type

`matio_classes matlab_type_traits< double >::class_type = MAT_C_DOUBLE [static], [constexpr]`

Definition at line 73 of file [matlab_writer_helper.h](#).

12.278.2.2 data_type

`matio_types matlab_type_traits< double >::data_type = MAT_T_DOUBLE [static], [constexpr]`

Definition at line 74 of file [matlab_writer_helper.h](#).

The documentation for this struct was generated from the following file:

- [matlab_writer_helper.h](#)

12.279 matlab_type_traits< float > Struct Reference

Static Public Attributes

- static constexpr matio_classes [class_type](#) = MAT_C_SINGLE
- static constexpr matio_types [data_type](#) = MAT_T_SINGLE

12.279.1 Detailed Description

Definition at line 64 of file [matlab_writer_helper.h](#).

12.279.2 Member Data Documentation

12.279.2.1 class_type

matio_classes [matlab_type_traits](#)< float >::class_type = MAT_C_SINGLE [static], [constexpr]

Definition at line 66 of file [matlab_writer_helper.h](#).

12.279.2.2 data_type

matio_types [matlab_type_traits](#)< float >::data_type = MAT_T_SINGLE [static], [constexpr]

Definition at line 67 of file [matlab_writer_helper.h](#).

The documentation for this struct was generated from the following file:

- [matlab_writer_helper.h](#)

12.280 matlab_type_traits< int32_t > Struct Reference

Static Public Attributes

- static constexpr matio_classes [class_type](#) = MAT_C_INT32
- static constexpr matio_types [data_type](#) = MAT_T_INT32

12.280.1 Detailed Description

Definition at line 29 of file [matlab_writer_helper.h](#).

12.280.2 Member Data Documentation

12.280.2.1 class_type

matio_classes [matlab_type_traits](#)< int32_t >::class_type = MAT_C_INT32 [static], [constexpr]

Definition at line 31 of file [matlab_writer_helper.h](#).

12.280.2.2 data_type

matio_types [matlab_type_traits](#)< int32_t >::data_type = MAT_T_INT32 [static], [constexpr]

Definition at line 32 of file [matlab_writer_helper.h](#).

The documentation for this struct was generated from the following file:

- [matlab_writer_helper.h](#)

12.281 matlab_type_traits< int64_t > Struct Reference

Static Public Attributes

- static constexpr matio_classes [class_type](#) = MAT_C_INT64
- static constexpr matio_types [data_type](#) = MAT_T_INT64

12.281.1 Detailed Description

Definition at line 50 of file [matlab_writer_helper.h](#).

12.281.2 Member Data Documentation

12.281.2.1 class_type

```
matio_classes matlab_type_traits< int64_t >::class_type = MAT_C_INT64 [static], [constexpr]
```

Definition at line 52 of file [matlab_writer_helper.h](#).

12.281.2.2 data_type

```
matio_types matlab_type_traits< int64_t >::data_type = MAT_T_INT64 [static], [constexpr]
```

Definition at line 53 of file [matlab_writer_helper.h](#).

The documentation for this struct was generated from the following file:

- [matlab_writer_helper.h](#)

12.282 matlab_type_traits< uint32_t > Struct Reference

Static Public Attributes

- static constexpr matio_classes [class_type](#) = MAT_C_UINT32
- static constexpr matio_types [data_type](#) = MAT_T_UINT32

12.282.1 Detailed Description

Definition at line 36 of file [matlab_writer_helper.h](#).

12.282.2 Member Data Documentation

12.282.2.1 class_type

```
matio_classes matlab_type_traits< uint32_t >::class_type = MAT_C_UINT32 [static], [constexpr]
```

Definition at line 38 of file [matlab_writer_helper.h](#).

12.282.2.2 data_type

```
matio_types matlab_type_traits< uint32_t >::data_type = MAT_T_UINT32 [static], [constexpr]
```

Definition at line 39 of file [matlab_writer_helper.h](#).

The documentation for this struct was generated from the following file:

- [matlab_writer_helper.h](#)

12.283 matlab_type_traits< uint64_t > Struct Reference

Static Public Attributes

- static constexpr matio_classes [class_type](#) = MAT_C_UINT64
- static constexpr matio_types [data_type](#) = MAT_T_UINT64

12.283.1 Detailed Description

Definition at line 57 of file [matlab_writer_helper.h](#).

12.283.2 Member Data Documentation

12.283.2.1 class_type

matio_classes [matlab_type_traits](#)< uint64_t >::class_type = MAT_C_UINT64 [static], [constexpr]
Definition at line 59 of file [matlab_writer_helper.h](#).

12.283.2.2 data_type

matio_types [matlab_type_traits](#)< uint64_t >::data_type = MAT_T_UINT64 [static], [constexpr]
Definition at line 60 of file [matlab_writer_helper.h](#).

The documentation for this struct was generated from the following file:

- [matlab_writer_helper.h](#)

12.284 matlab_type_traits< uint8_t > Struct Reference

Static Public Attributes

- static constexpr matio_classes [class_type](#) = MAT_C_UINT8
- static constexpr matio_types [data_type](#) = MAT_T_UINT8

12.284.1 Detailed Description

Definition at line 43 of file [matlab_writer_helper.h](#).

12.284.2 Member Data Documentation

12.284.2.1 class_type

matio_classes [matlab_type_traits](#)< uint8_t >::class_type = MAT_C_UINT8 [static], [constexpr]
Definition at line 45 of file [matlab_writer_helper.h](#).

12.284.2.2 data_type

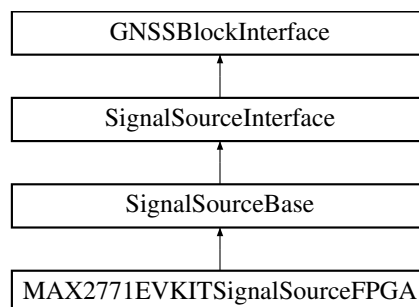
matio_types [matlab_type_traits](#)< uint8_t >::data_type = MAT_T_UINT8 [static], [constexpr]
Definition at line 46 of file [matlab_writer_helper.h](#).

The documentation for this struct was generated from the following file:

- [matlab_writer_helper.h](#)

12.285 MAX2771EVKITSignalSourceFPGA Class Reference

Inheritance diagram for MAX2771EVKITSignalSourceFPGA:



Public Member Functions

- **MAX2771EVKITSignalSourceFPGA** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- std::vector< uint32_t > **setup_regs** (uint64_t freq)
- size_t **item_size** () override
- void **connect** (gr::top_block_sptr top_block) override
- void **disconnect** (gr::top_block_sptr top_block) override
- gr::basic_block_sptr **get_left_block** () override
- gr::basic_block_sptr **get_right_block** () override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string **role** () final
- std::string **implementation** () final
- size_t **getRfChannels** () const override
- gr::basic_block_sptr **get_left_block** () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr **get_left_block** (int RF_channel)
- virtual gr::basic_block_sptr **get_right_block** (int RF_channel)
- virtual void **start** ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t **decode_item_type** (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↔ error=false)
utility for decoding passed ".item_type" values

12.285.1 Detailed Description

Definition at line 45 of file [max2771_evkit_signal_source_fpga.h](#).

12.285.2 Member Function Documentation

12.285.2.1 connect()

```
void MAX2771EVKITSignalSourceFPGA::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.285.2.2 disconnect()

```
void MAX2771EVKITSignalSourceFPGA::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.285.2.3 get_left_block()

```
gr::basic_block_sptr MAX2771EVKITSignalSourceFPGA::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.285.2.4 get_right_block()

gr::basic_block_sptr MAX2771EVKITSignalSourceFPGA::get_right_block () [override], [virtual]
Implements [GNSSBlockInterface](#).

12.285.2.5 item_size()

size_t MAX2771EVKITSignalSourceFPGA::item_size () [inline], [override], [virtual]
Implements [GNSSBlockInterface](#).

Definition at line 56 of file [max2771_evkit_signal_source_fpga.h](#).

The documentation for this class was generated from the following file:

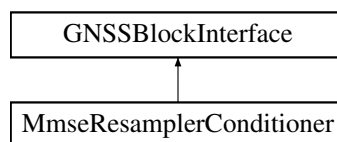
- [max2771_evkit_signal_source_fpga.h](#)

12.286 MmseResamplerConditioner Class Reference

Interface of a MMSE resampler block adapter to a SignalConditionerInterface.

#include <mmse_resampler_conditioner.h>

Inheritance diagram for MmseResamplerConditioner:



Public Member Functions

- **MmseResamplerConditioner** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream)
- std::string [role](#) () override
- std::string [implementation](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.286.1 Detailed Description

Interface of a MMSE resampler block adapter to a SignalConditionerInterface.

Definition at line 48 of file [mmse_resampler_conditioner.h](#).

12.286.2 Member Function Documentation

12.286.2.1 connect()

void MmseResamplerConditioner::connect (
gr::top_block_sptr top_block) [override], [virtual]

Implements [GNSSBlockInterface](#).

12.286.2.2 disconnect()

```
void MmseResamplerConditioner::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.286.2.3 get_left_block()

```
gr::basic_block_sptr MmseResamplerConditioner::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.286.2.4 get_right_block()

```
gr::basic_block_sptr MmseResamplerConditioner::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.286.2.5 implementation()

```
std::string MmseResamplerConditioner::implementation () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 62 of file [mmse_resampler_conditioner.h](#).

12.286.2.6 item_size()

```
size_t MmseResamplerConditioner::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 67 of file [mmse_resampler_conditioner.h](#).

12.286.2.7 role()

```
std::string MmseResamplerConditioner::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 57 of file [mmse_resampler_conditioner.h](#).

The documentation for this class was generated from the following file:

- [mmse_resampler_conditioner.h](#)

12.287 ModelFunction Class Reference**Public Member Functions**

- virtual arma::vec **operator()** (const arma::vec &input)=0

12.287.1 Detailed Description

Definition at line 46 of file [nonlinear_tracking.h](#).

12.287.2 Constructor & Destructor Documentation**12.287.2.1 ModelFunction()**

```
ModelFunction::ModelFunction () [inline]
```

Definition at line 49 of file [nonlinear_tracking.h](#).

The documentation for this class was generated from the following file:

- [nonlinear_tracking.h](#)

12.288 Monitor_Ephemeris_Udp_Sink Class Reference

Public Member Functions

- **Monitor_Ephemeris_Udp_Sink** (const std::vector< std::string > &addresses, const uint16_t &port, bool protobuf_enabled)
- bool **write_gps_ephemeris** (const std::shared_ptr< [Gps_Ephemeris](#) > &monitor_gps_eph)
- bool **write_galileo_ephemeris** (const std::shared_ptr< [Galileo_Ephemeris](#) > &monitor_gal_eph)

12.288.1 Detailed Description

Definition at line 42 of file [monitor_ephemeris_udp_sink.h](#).

The documentation for this class was generated from the following file:

- [monitor_ephemeris_udp_sink.h](#)

12.289 Monitor_Pvt Class Reference

This class contains parameters and outputs of the PVT block.

```
#include <monitor_pvt.h>
```

Public Member Functions

- template<class Archive>
void [serialize](#) (Archive &ar, const unsigned int version)
This member function serializes and restores [Monitor_Pvt](#) objects from a byte stream.

Public Attributes

- uint32_t [TOW_at_current_symbol_ms](#)
- uint32_t [week](#)
- double [RX_time](#)
- double [user_clk_offset](#)
- double [pos_x](#)
- double [pos_y](#)
- double [pos_z](#)
- double [vel_x](#)
- double [vel_y](#)
- double [vel_z](#)
- double [cov_xx](#)
- double [cov_yy](#)
- double [cov_zz](#)
- double [cov_xy](#)
- double [cov_yz](#)
- double [cov_zx](#)
- double [latitude](#)
- double [longitude](#)
- double [height](#)
- double [vel_e](#)
- double [vel_n](#)
- double [vel_u](#)
- double [cog](#)
- uint32_t [galhas_status](#)
- uint8_t [valid_sats](#)
- uint8_t [solution_status](#)
- uint8_t [solution_type](#)

- float [AR_ratio_factor](#)
- float [AR_ratio_threshold](#)
- double [gdop](#)
- double [pdop](#)
- double [hdop](#)
- double [vdop](#)
- double [user_clk_drift_ppm](#)
- std::string [utc_time](#)
- std::string [geohash](#)

12.289.1 Detailed Description

This class contains parameters and outputs of the PVT block.
Definition at line 33 of file [monitor_pvt.h](#).

12.289.2 Member Function Documentation

12.289.2.1 `serialize()`

```
template<class Archive>
void Monitor_Pvt::serialize (
    Archive & ar,
    const unsigned int version) [inline]
```

This member function serializes and restores [Monitor_Pvt](#) objects from a byte stream.
Definition at line 109 of file [monitor_pvt.h](#).

12.289.3 Member Data Documentation

12.289.3.1 `AR_ratio_factor`

```
float Monitor_Pvt::AR_ratio_factor
```

Definition at line 85 of file [monitor_pvt.h](#).

12.289.3.2 `AR_ratio_threshold`

```
float Monitor_Pvt::AR_ratio_threshold
```

Definition at line 87 of file [monitor_pvt.h](#).

12.289.3.3 `cog`

```
double Monitor_Pvt::cog
```

Definition at line 73 of file [monitor_pvt.h](#).

12.289.3.4 `cov_xx`

```
double Monitor_Pvt::cov_xx
```

Definition at line 54 of file [monitor_pvt.h](#).

12.289.3.5 `cov_xy`

```
double Monitor_Pvt::cov_xy
```

Definition at line 57 of file [monitor_pvt.h](#).

12.289.3.6 `cov_yy`

```
double Monitor_Pvt::cov_yy
```

Definition at line 55 of file [monitor_pvt.h](#).

12.289.3.7 cov_yz

double Monitor_Pvt::cov_yz
Definition at line 58 of file [monitor_pvt.h](#).

12.289.3.8 cov_zx

double Monitor_Pvt::cov_zx
Definition at line 59 of file [monitor_pvt.h](#).

12.289.3.9 cov_zz

double Monitor_Pvt::cov_zz
Definition at line 56 of file [monitor_pvt.h](#).

12.289.3.10 galhas_status

uint32_t Monitor_Pvt::galhas_status
Definition at line 76 of file [monitor_pvt.h](#).

12.289.3.11 gdop

double Monitor_Pvt::gdop
Definition at line 90 of file [monitor_pvt.h](#).

12.289.3.12 geohash

std::string Monitor_Pvt::geohash
Definition at line 101 of file [monitor_pvt.h](#).

12.289.3.13 hdop

double Monitor_Pvt::hdop
Definition at line 92 of file [monitor_pvt.h](#).

12.289.3.14 height

double Monitor_Pvt::height
Definition at line 66 of file [monitor_pvt.h](#).

12.289.3.15 latitude

double Monitor_Pvt::latitude
Definition at line 62 of file [monitor_pvt.h](#).

12.289.3.16 longitude

double Monitor_Pvt::longitude
Definition at line 64 of file [monitor_pvt.h](#).

12.289.3.17 pdop

double Monitor_Pvt::pdop
Definition at line 91 of file [monitor_pvt.h](#).

12.289.3.18 pos_x

double Monitor_Pvt::pos_x
Definition at line 46 of file [monitor_pvt.h](#).

12.289.3.19 pos_y

double Monitor_Pvt::pos_y
Definition at line 47 of file [monitor_pvt.h](#).

12.289.3.20 pos_z

double Monitor_Pvt::pos_z
Definition at line 48 of file [monitor_pvt.h](#).

12.289.3.21 RX_time

double Monitor_Pvt::RX_time
Definition at line 41 of file [monitor_pvt.h](#).

12.289.3.22 solution_status

uint8_t Monitor_Pvt::solution_status
Definition at line 81 of file [monitor_pvt.h](#).

12.289.3.23 solution_type

uint8_t Monitor_Pvt::solution_type
Definition at line 83 of file [monitor_pvt.h](#).

12.289.3.24 TOW_at_current_symbol_ms

uint32_t Monitor_Pvt::TOW_at_current_symbol_ms
Definition at line 37 of file [monitor_pvt.h](#).

12.289.3.25 user_clk_drift_ppm

double Monitor_Pvt::user_clk_drift_ppm
Definition at line 96 of file [monitor_pvt.h](#).

12.289.3.26 user_clk_offset

double Monitor_Pvt::user_clk_offset
Definition at line 43 of file [monitor_pvt.h](#).

12.289.3.27 utc_time

std::string Monitor_Pvt::utc_time
Definition at line 99 of file [monitor_pvt.h](#).

12.289.3.28 valid_sats

uint8_t Monitor_Pvt::valid_sats
Definition at line 79 of file [monitor_pvt.h](#).

12.289.3.29 vdop

double Monitor_Pvt::vdop
Definition at line 93 of file [monitor_pvt.h](#).

12.289.3.30 vel_e

double Monitor_Pvt::vel_e
Definition at line 68 of file [monitor_pvt.h](#).

12.289.3.31 vel_n

double Monitor_Pvt::vel_n

Definition at line 69 of file [monitor_pvt.h](#).

12.289.3.32 vel_u

double Monitor_Pvt::vel_u

Definition at line 70 of file [monitor_pvt.h](#).

12.289.3.33 vel_x

double Monitor_Pvt::vel_x

Definition at line 49 of file [monitor_pvt.h](#).

12.289.3.34 vel_y

double Monitor_Pvt::vel_y

Definition at line 50 of file [monitor_pvt.h](#).

12.289.3.35 vel_z

double Monitor_Pvt::vel_z

Definition at line 51 of file [monitor_pvt.h](#).

12.289.3.36 week

uint32_t Monitor_Pvt::week

Definition at line 39 of file [monitor_pvt.h](#).

The documentation for this class was generated from the following file:

- [monitor_pvt.h](#)

12.290 Monitor_Pvt_Udp_Sink Class Reference

Public Member Functions

- **Monitor_Pvt_Udp_Sink** (const std::vector< std::string > &addresses, const std::vector< std::string > &ports, bool protobuf_enabled)
- bool **write_monitor_pvt** (const [Monitor_Pvt](#) *const monitor_pvt)

12.290.1 Detailed Description

Definition at line 40 of file [monitor_pvt_udp_sink.h](#).

The documentation for this class was generated from the following file:

- [monitor_pvt_udp_sink.h](#)

12.291 msm_h_t Struct Reference

Public Attributes

- unsigned char [iod](#)
- unsigned char [time_s](#)
- unsigned char [clk_str](#)
- unsigned char [clk_ext](#)
- unsigned char [smooth](#)
- unsigned char [tint_s](#)
- unsigned char [nsat](#)

- unsigned char [nsig](#)
- unsigned char [sats](#) [64]
- unsigned char [sigs](#) [32]
- unsigned char [cellmask](#) [64]

12.291.1 Detailed Description

Definition at line [1277](#) of file [rtklib.h](#).

12.291.2 Member Data Documentation

12.291.2.1 cellmask

```
unsigned char msm_h_t::cellmask[64]
```

Definition at line [1288](#) of file [rtklib.h](#).

12.291.2.2 clk_ext

```
unsigned char msm_h_t::clk_ext
```

Definition at line [1282](#) of file [rtklib.h](#).

12.291.2.3 clk_str

```
unsigned char msm_h_t::clk_str
```

Definition at line [1281](#) of file [rtklib.h](#).

12.291.2.4 iod

```
unsigned char msm_h_t::iod
```

Definition at line [1279](#) of file [rtklib.h](#).

12.291.2.5 nsat

```
unsigned char msm_h_t::nsat
```

Definition at line [1285](#) of file [rtklib.h](#).

12.291.2.6 nsig

```
unsigned char msm_h_t::nsig
```

Definition at line [1285](#) of file [rtklib.h](#).

12.291.2.7 sats

```
unsigned char msm_h_t::sats[64]
```

Definition at line [1286](#) of file [rtklib.h](#).

12.291.2.8 sigs

```
unsigned char msm_h_t::sigs[32]
```

Definition at line [1287](#) of file [rtklib.h](#).

12.291.2.9 smooth

```
unsigned char msm_h_t::smooth
```

Definition at line [1283](#) of file [rtklib.h](#).

12.291.2.10 time_s

```
unsigned char msm_h_t::time_s
```

Definition at line [1280](#) of file [rtklib.h](#).

12.291.2.11 tint_s

unsigned char msm_h_t::tint_s

Definition at line 1284 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.292 mt1_header Struct Reference

Public Attributes

- uint16_t [toh](#)
- uint8_t [mask_id](#)
- uint8_t [iod_set_id](#)
- uint8_t [reserved](#)
- bool [mask_flag](#)
- bool [orbit_correction_flag](#)
- bool [clock_fullset_flag](#)
- bool [clock_subset_flag](#)
- bool [code_bias_flag](#)
- bool [phase_bias_flag](#)

12.292.1 Detailed Description

Definition at line 30 of file [galileo_has_data.h](#).

12.292.2 Member Data Documentation

12.292.2.1 clock_fullset_flag

bool mt1_header::clock_fullset_flag

Definition at line 38 of file [galileo_has_data.h](#).

12.292.2.2 clock_subset_flag

bool mt1_header::clock_subset_flag

Definition at line 39 of file [galileo_has_data.h](#).

12.292.2.3 code_bias_flag

bool mt1_header::code_bias_flag

Definition at line 40 of file [galileo_has_data.h](#).

12.292.2.4 iod_set_id

uint8_t mt1_header::iod_set_id

Definition at line 34 of file [galileo_has_data.h](#).

12.292.2.5 mask_flag

bool mt1_header::mask_flag

Definition at line 36 of file [galileo_has_data.h](#).

12.292.2.6 mask_id

uint8_t mt1_header::mask_id

Definition at line 33 of file [galileo_has_data.h](#).

12.292.2.7 orbit_correction_flag

bool mtl_header::orbit_correction_flag
 Definition at line 37 of file [galileo_has_data.h](#).

12.292.2.8 phase_bias_flag

bool mtl_header::phase_bias_flag
 Definition at line 41 of file [galileo_has_data.h](#).

12.292.2.9 reserved

uint8_t mtl_header::reserved
 Definition at line 35 of file [galileo_has_data.h](#).

12.292.2.10 toh

uint16_t mtl_header::toh
 Definition at line 32 of file [galileo_has_data.h](#).
 The documentation for this struct was generated from the following file:

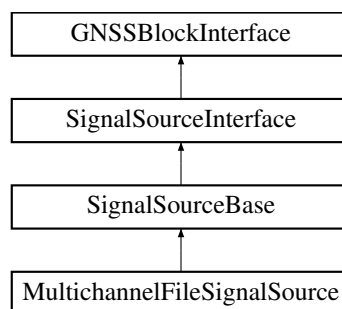
- [galileo_has_data.h](#)

12.293 MultichannelFileSignalSource Class Reference

Class that reads signals samples from files at different frequency bands and adapts it to a [SignalSourceInterface](#).

#include <multichannel_file_signal_source.h>

Inheritance diagram for MultichannelFileSignalSource:



Public Member Functions

- **MultichannelFileSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- std::string [filename](#) () const
- std::string [item_type](#) () const
- bool [repeat](#) () const
- int64_t [sampling_frequency](#) () const
- uint64_t [samples](#) () const

Public Member Functions inherited from [SignalSourceBase](#)

- `std::string` [role](#) () final
- `std::string` [implementation](#) () final
- `size_t` [getRfChannels](#) () const override
- `gr::basic_block_sptr` [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual `gr::basic_block_sptr` [get_left_block](#) (int RF_channel)
- virtual `gr::basic_block_sptr` [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, `std::string` role, `std::string` impl)
Constructor.
- `size_t` [decode_item_type](#) (`std::string` const &item_type, `bool` *is_interleaved=nullptr, `bool` throw_on_↔ error=false)
utility for decoding passed ".item_type" values

12.293.1 Detailed Description

Class that reads signals samples from files at different frequency bands and adapts it to a [SignalSourceInterface](#).
Definition at line 49 of file [multichannel_file_signal_source.h](#).

12.293.2 Member Function Documentation

12.293.2.1 connect()

```
void MultichannelFileSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.293.2.2 disconnect()

```
void MultichannelFileSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.293.2.3 filename()

```
std::string MultichannelFileSignalSource::filename () const [inline]
```

Definition at line 68 of file [multichannel_file_signal_source.h](#).

12.293.2.4 get_left_block()

```
gr::basic_block_sptr MultichannelFileSignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.293.2.5 get_right_block()

```
gr::basic_block_sptr MultichannelFileSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.293.2.6 item_size()

```
size_t MultichannelFileSignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 58 of file [multichannel_file_signal_source.h](#).

12.293.2.7 item_type()

```
std::string MultichannelFileSignalSource::item_type () const [inline]
```

Definition at line 73 of file [multichannel_file_signal_source.h](#).

12.293.2.8 repeat()

```
bool MultichannelFileSignalSource::repeat () const [inline]
```

Definition at line 78 of file [multichannel_file_signal_source.h](#).

12.293.2.9 samples()

```
uint64_t MultichannelFileSignalSource::samples () const [inline]
```

Definition at line 88 of file [multichannel_file_signal_source.h](#).

12.293.2.10 sampling_frequency()

```
int64_t MultichannelFileSignalSource::sampling_frequency () const [inline]
```

Definition at line 83 of file [multichannel_file_signal_source.h](#).

The documentation for this class was generated from the following file:

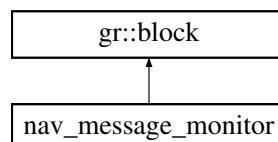
- [multichannel_file_signal_source.h](#)

12.294 nav_message_monitor Class Reference

GNU Radio block that receives asynchronous [Nav_Message_Packet](#) objects from the telemetry blocks and sends them via UDP.

```
#include <nav_message_monitor.h>
```

Inheritance diagram for nav_message_monitor:

**Public Member Functions**

- [~nav_message_monitor](#) ()=default
Default destructor.

Friends

- nav_message_monitor_sptr **nav_message_monitor_make** (const std::vector< std::string > &addresses, uint16_t port)

12.294.1 Detailed Description

GNU Radio block that receives asynchronous [Nav_Message_Packet](#) objects from the telemetry blocks and sends them via UDP.

Definition at line 45 of file [nav_message_monitor.h](#).

12.294.2 Constructor & Destructor Documentation

12.294.2.1 ~nav_message_monitor()

nav_message_monitor::~nav_message_monitor () [default]

Default destructor.

The documentation for this class was generated from the following file:

- [nav_message_monitor.h](#)

12.295 Nav_Message_Packet Class Reference

Public Member Functions

- [Nav_Message_Packet](#) ()=default
Default constructor.
- [~Nav_Message_Packet](#) ()=default
Default destructor.
- [Nav_Message_Packet](#) (const [Nav_Message_Packet](#) &other) noexcept
Copy constructor.
- [Nav_Message_Packet](#) & [operator=](#) (const [Nav_Message_Packet](#) &rhs) noexcept
Copy assignment operator.
- [Nav_Message_Packet](#) ([Nav_Message_Packet](#) &&other) noexcept
Move constructor.
- [Nav_Message_Packet](#) & [operator=](#) ([Nav_Message_Packet](#) &&other) noexcept
Move assignment operator.

Public Attributes

- std::string [system](#)
GNSS constellation: "G" for GPS, "R" for Glonass, "S" for SBAS, "E" for Galileo and "C" for Beidou.
- std::string [signal](#)
GNSS signal: "1C" for GPS L1 C/A, "1B" for Galileo E1b/c, "1G" for Glonass L1 C/A, "2S" for GPS L2 L2C(M), "2G" for Glonass L2 C/A, "L5" for GPS L5 and "5X" for Galileo E5a.
- int32_t [prn](#)
SV ID.
- int32_t [tow_at_current_symbol_ms](#)
Time of week of the current symbol, in ms.
- std::string [nav_message](#)
Content of the navigation page.

12.295.1 Detailed Description

Definition at line 29 of file [nav_message_packet.h](#).

12.295.2 Constructor & Destructor Documentation

12.295.2.1 Nav_Message_Packet() [1/3]

Nav_Message_Packet::Nav_Message_Packet () [default]

Default constructor.

Referenced by [Nav_Message_Packet\(\)](#), [Nav_Message_Packet\(\)](#), [operator=\(\)](#), and [operator=\(\)](#).

12.295.2.2 ~Nav_Message_Packet()

Nav_Message_Packet::~Nav_Message_Packet () [default]

Default destructor.

12.295.2.3 Nav_Message_Packet() [2/3]

```
Nav_Message_Packet::Nav_Message_Packet (
    const Nav_Message_Packet & other) [inline], [noexcept]
```

Copy constructor.

Definition at line 43 of file [nav_message_packet.h](#).

References [Nav_Message_Packet\(\)](#).

12.295.2.4 Nav_Message_Packet() [3/3]

```
Nav_Message_Packet::Nav_Message_Packet (
    Nav_Message_Packet && other) [inline], [noexcept]
```

Move constructor.

Definition at line 64 of file [nav_message_packet.h](#).

References [Nav_Message_Packet\(\)](#).

12.295.3 Member Function Documentation**12.295.3.1 operator=() [1/2]**

```
Nav_Message_Packet & Nav_Message_Packet::operator= (
    const Nav_Message_Packet & rhs) [inline], [noexcept]
```

Copy assignment operator.

Definition at line 49 of file [nav_message_packet.h](#).

References [Nav_Message_Packet\(\)](#).

12.295.3.2 operator=() [2/2]

```
Nav_Message_Packet & Nav_Message_Packet::operator= (
    Nav_Message_Packet && other) [inline], [noexcept]
```

Move assignment operator.

Definition at line 70 of file [nav_message_packet.h](#).

References [Nav_Message_Packet\(\)](#).

12.295.4 Member Data Documentation**12.295.4.1 nav_message**

```
std::string Nav_Message_Packet::nav_message
```

Content of the navigation page.

Definition at line 40 of file [nav_message_packet.h](#).

Referenced by [Serdes_Nav_Message::readProtobuffer\(\)](#).

12.295.4.2 prn

```
int32_t Nav_Message_Packet::prn
```

SV ID.

Definition at line 38 of file [nav_message_packet.h](#).

Referenced by [Serdes_Nav_Message::readProtobuffer\(\)](#).

12.295.4.3 signal

```
std::string Nav_Message_Packet::signal
```

GNSS signal: "1C" for GPS L1 C/A, "1B" for Galileo E1b/c, "1G" for Glonass L1 C/A, "2S" for GPS L2 L2C(M), "2G" for Glonass L2 C/A, "L5" for GPS L5 and "5X" for Galileo E5a.

Definition at line 37 of file [nav_message_packet.h](#).

Referenced by [Serdes_Nav_Message::readProtobuffer\(\)](#).

12.295.4.4 system

`std::string Nav_Message_Packet::system`

GNSS constellation: "G" for GPS, "R" for Glonass, "S" for SBAS, "E" for Galileo and "C" for Beidou.

Definition at line 36 of file [nav_message_packet.h](#).

Referenced by [Serdes_Nav_Message::readProtobuffer\(\)](#).

12.295.4.5 tow_at_current_symbol_ms

`int32_t Nav_Message_Packet::tow_at_current_symbol_ms`

Time of week of the current symbol, in ms.

Definition at line 39 of file [nav_message_packet.h](#).

Referenced by [Serdes_Nav_Message::readProtobuffer\(\)](#).

The documentation for this class was generated from the following file:

- [nav_message_packet.h](#)

12.296 Nav_Message_Udp_Sink Class Reference

Public Member Functions

- **Nav_Message_Udp_Sink** (const std::vector< std::string > &addresses, const uint16_t &port)
- **bool write_nav_message** (const std::shared_ptr< [Nav_Message_Packet](#) > &nav_meg_packet)

12.296.1 Detailed Description

Definition at line 39 of file [nav_message_udp_sink.h](#).

The documentation for this class was generated from the following file:

- [nav_message_udp_sink.h](#)

12.297 nav_t Struct Reference

Public Attributes

- int [n](#)
- int [nmax](#)
- int [ng](#)
- int [ngmax](#)
- int [ns](#)
- int [nsmax](#)
- int [ne](#)
- int [nemax](#)
- int [nc](#)
- int [ncmax](#)
- int [na](#)
- int [namax](#)
- int [nt](#)
- int [ntmax](#)
- int [nf](#)
- int [nfmax](#)
- [eph_t](#) * [eph](#)
- [geph_t](#) * [geph](#)
- [seph_t](#) * [seph](#)
- [peph_t](#) * [peph](#)
- [pclk_t](#) * [pclk](#)
- [alm_t](#) * [alm](#)

- [tec_t](#) * [tec](#)
- [fcbd_t](#) * [fcb](#)
- [erp_t](#) [erp](#)
- double [utc_gps](#) [4]
- double [utc_glo](#) [4]
- double [utc_gal](#) [4]
- double [utc_qzs](#) [4]
- double [utc_cmp](#) [4]
- double [utc_irn](#) [4]
- double [utc_sbs](#) [4]
- double [ion_gps](#) [8]
- double [ion_gal](#) [4]
- double [ion_qzs](#) [8]
- double [ion_cmp](#) [8]
- double [ion_irn](#) [8]
- int [leaps](#)
- double [lam](#) [MAXSAT][NFREQ]
- double [cbias](#) [MAXSAT][3]
- double [rbias](#) [MAXRCV][2][3]
- double [wlbias](#) [MAXSAT]
- double [glo_cpbias](#) [4]
- char [glo_fcn](#) [MAXPRNGLO+1]
- [pcv_t](#) [pcvs](#) [MAXSAT]
- [sbssat_t](#) [sbssat](#)
- [sbsion_t](#) [sbsion](#) [MAXBAND+1]
- [dgps_t](#) [dgps](#) [MAXSAT]
- [ssr_t](#) [ssr](#) [MAXSAT]
- [lexeph_t](#) [lexeph](#) [MAXSAT]
- [lexion_t](#) [lexion](#)
- [pppcorr_t](#) [pppcorr](#)

12.297.1 Detailed Description

Definition at line 753 of file [rtklib.h](#).

12.297.2 Member Data Documentation

12.297.2.1 alm

[alm_t](#)* [nav_t::alm](#)

Definition at line 768 of file [rtklib.h](#).

12.297.2.2 cbias

double [nav_t::cbias](#) [MAXSAT] [3]

Definition at line 786 of file [rtklib.h](#).

12.297.2.3 dgps

[dgps_t](#) [nav_t::dgps](#) [MAXSAT]

Definition at line 794 of file [rtklib.h](#).

12.297.2.4 eph

[eph_t](#)* [nav_t::eph](#)

Definition at line 763 of file [rtklib.h](#).

12.297.2.5 erp

`erp_t` `nav_t::erp`

Definition at line 771 of file `rtklib.h`.

12.297.2.6 fcb

`fcbd_t*` `nav_t::fcb`

Definition at line 770 of file `rtklib.h`.

12.297.2.7 geph

`geph_t*` `nav_t::geph`

Definition at line 764 of file `rtklib.h`.

12.297.2.8 glo_cpbias

`double` `nav_t::glo_cpbias`[4]

Definition at line 789 of file `rtklib.h`.

12.297.2.9 glo_fcn

`char` `nav_t::glo_fcn`[`MAXPRNGLO`+1]

Definition at line 790 of file `rtklib.h`.

12.297.2.10 ion_cmp

`double` `nav_t::ion_cmp`[8]

Definition at line 782 of file `rtklib.h`.

12.297.2.11 ion_gal

`double` `nav_t::ion_gal`[4]

Definition at line 780 of file `rtklib.h`.

12.297.2.12 ion_gps

`double` `nav_t::ion_gps`[8]

Definition at line 779 of file `rtklib.h`.

12.297.2.13 ion_irn

`double` `nav_t::ion_irn`[8]

Definition at line 783 of file `rtklib.h`.

12.297.2.14 ion_qzs

`double` `nav_t::ion_qzs`[8]

Definition at line 781 of file `rtklib.h`.

12.297.2.15 lam

`double` `nav_t::lam`[`MAXSAT`][`NFREQ`]

Definition at line 785 of file `rtklib.h`.

12.297.2.16 leaps

`int` `nav_t::leaps`

Definition at line 784 of file `rtklib.h`.

12.297.2.17 lexeph

`lexeph_t nav_t::lexeph[MAXSAT]`
Definition at line 796 of file [rtklib.h](#).

12.297.2.18 lexion

`lexion_t nav_t::lexion`
Definition at line 797 of file [rtklib.h](#).

12.297.2.19 n

`int nav_t::n`
Definition at line 755 of file [rtklib.h](#).

12.297.2.20 na

`int nav_t::na`
Definition at line 760 of file [rtklib.h](#).

12.297.2.21 namax

`int nav_t::namax`
Definition at line 760 of file [rtklib.h](#).

12.297.2.22 nc

`int nav_t::nc`
Definition at line 759 of file [rtklib.h](#).

12.297.2.23 ncmax

`int nav_t::ncmax`
Definition at line 759 of file [rtklib.h](#).

12.297.2.24 ne

`int nav_t::ne`
Definition at line 758 of file [rtklib.h](#).

12.297.2.25 nemax

`int nav_t::nemax`
Definition at line 758 of file [rtklib.h](#).

12.297.2.26 nf

`int nav_t::nf`
Definition at line 762 of file [rtklib.h](#).

12.297.2.27 nfmax

`int nav_t::nfmax`
Definition at line 762 of file [rtklib.h](#).

12.297.2.28 ng

`int nav_t::ng`
Definition at line 756 of file [rtklib.h](#).

12.297.2.29 ngmax

```
int nav_t::ngmax
```

Definition at line 756 of file [rtklib.h](#).

12.297.2.30 nmax

```
int nav_t::nmax
```

Definition at line 755 of file [rtklib.h](#).

12.297.2.31 ns

```
int nav_t::ns
```

Definition at line 757 of file [rtklib.h](#).

12.297.2.32 nsmax

```
int nav_t::nsmax
```

Definition at line 757 of file [rtklib.h](#).

12.297.2.33 nt

```
int nav_t::nt
```

Definition at line 761 of file [rtklib.h](#).

12.297.2.34 ntmax

```
int nav_t::ntmax
```

Definition at line 761 of file [rtklib.h](#).

12.297.2.35 pclk

```
pclk_t* nav_t::pclk
```

Definition at line 767 of file [rtklib.h](#).

12.297.2.36 pcvs

```
pcv_t nav_t::pcvs[MAXSAT]
```

Definition at line 791 of file [rtklib.h](#).

12.297.2.37 peph

```
peph_t* nav_t::peph
```

Definition at line 766 of file [rtklib.h](#).

12.297.2.38 pppcorr

```
pppcorr_t nav_t::pppcorr
```

Definition at line 798 of file [rtklib.h](#).

12.297.2.39 rbias

```
double nav_t::rbias[MAXRCV][2][3]
```

Definition at line 787 of file [rtklib.h](#).

12.297.2.40 sbsion

```
sbsion_t nav_t::sbsion[MAXBAND+1]
```

Definition at line 793 of file [rtklib.h](#).

12.297.2.41 sbssat

```
sbssat_t nav_t::sbssat
```

Definition at line 792 of file [rtklib.h](#).

12.297.2.42 seph

```
seph_t* nav_t::seph
```

Definition at line 765 of file [rtklib.h](#).

12.297.2.43 ssr

```
ssr_t nav_t::ssr[MAXSAT]
```

Definition at line 795 of file [rtklib.h](#).

12.297.2.44 tec

```
tec_t* nav_t::tec
```

Definition at line 769 of file [rtklib.h](#).

12.297.2.45 utc_cmp

```
double nav_t::utc_cmp[4]
```

Definition at line 776 of file [rtklib.h](#).

12.297.2.46 utc_gal

```
double nav_t::utc_gal[4]
```

Definition at line 774 of file [rtklib.h](#).

12.297.2.47 utc_glo

```
double nav_t::utc_glo[4]
```

Definition at line 773 of file [rtklib.h](#).

12.297.2.48 utc_gps

```
double nav_t::utc_gps[4]
```

Definition at line 772 of file [rtklib.h](#).

12.297.2.49 utc_irn

```
double nav_t::utc_irn[4]
```

Definition at line 777 of file [rtklib.h](#).

12.297.2.50 utc_qzs

```
double nav_t::utc_qzs[4]
```

Definition at line 775 of file [rtklib.h](#).

12.297.2.51 utc_sbs

```
double nav_t::utc_sbs[4]
```

Definition at line 778 of file [rtklib.h](#).

12.297.2.52 wlbias

```
double nav_t::wlbias[MAXSAT]
```

Definition at line 788 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.298 Nmea_Printer Class Reference

This class provides a implementation of a subset of the NMEA-0183 standard for interfacing marine electronic devices as defined by the National Marine Electronics Association (NMEA).

```
#include <nmea_printer.h>
```

Public Member Functions

- [Nmea_Printer](#) (const std::string &filename, bool flag_nmea_output_file, bool flag_nmea_tty_port, std::string nmea_dump_devname, const std::string &base_path=".")
Default constructor.
- [~Nmea_Printer](#) ()
Default destructor.
- bool [Print_Nmea_Line](#) (const [Rtklib_Solver](#) *const pvt_data)
Print NMEA PVT and satellite info to the initialized device.
- std::string [get_GPGGA](#) (const [Rtklib_Solver](#) *const pvt_data) const
Returns GPGGA message (fix data)
- std::string [get_GPGSA](#) (const [Rtklib_Solver](#) *const pvt_data) const
Returns GPGSA message (overall satellite reception data)

12.298.1 Detailed Description

This class provides a implementation of a subset of the NMEA-0183 standard for interfacing marine electronic devices as defined by the National Marine Electronics Association (NMEA).

See https://en.wikipedia.org/wiki/NMEA_0183

Definition at line 44 of file [nmea_printer.h](#).

12.298.2 Constructor & Destructor Documentation

12.298.2.1 Nmea_Printer()

```
Nmea_Printer::Nmea_Printer (
    const std::string & filename,
    bool flag_nmea_output_file,
    bool flag_nmea_tty_port,
    std::string nmea_dump_devname,
    const std::string & base_path = ".")
```

Default constructor.

12.298.2.2 ~Nmea_Printer()

```
Nmea_Printer::~Nmea_Printer ()
```

Default destructor.

12.298.3 Member Function Documentation

12.298.3.1 get_GPGGA()

```
std::string Nmea_Printer::get_GPGGA (
    const Rtklib\_Solver *const pvt_data) const
```

Returns GPGGA message (fix data)

12.298.3.2 get_GPGSA()

```
std::string Nmea_Printer::get_GPGSA (
    const Rtklib\_Solver *const pvt_data) const
```

Returns GPGSA message (overall satellite reception data)

12.298.3.3 Print_Nmea_Line()

```
bool Nmea_Printer::Print_Nmea_Line (
    const Rtklib\_Solver *const pvt_data)
```

Print NMEA PVT and satellite info to the initialized device.

The documentation for this class was generated from the following file:

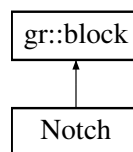
- [nmea_printer.h](#)

12.299 Notch Class Reference

This class implements a real-time software-defined multi state notch filter.

```
#include <notch_cc.h>
```

Inheritance diagram for Notch:



Public Member Functions

- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- notch_sptr **make_notch_filter** (float pfa, float p_c_factor, int32_t length, int32_t n_segments_est, int32_t n_segments_reset)

12.299.1 Detailed Description

This class implements a real-time software-defined multi state notch filter.

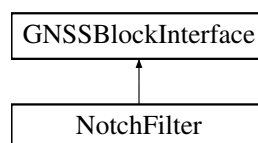
Definition at line 48 of file [notch_cc.h](#).

The documentation for this class was generated from the following file:

- [notch_cc.h](#)

12.300 NotchFilter Class Reference

Inheritance diagram for NotchFilter:



Public Member Functions

- **NotchFilter** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) ()
- std::string [implementation](#) ()

Returns "Notch_Filter".

- `size_t item_size ()`
- `void connect (gr::top_block_sptr top_block)`
- `void disconnect (gr::top_block_sptr top_block)`
- `gr::basic_block_sptr get_left_block ()`
- `gr::basic_block_sptr get_right_block ()`

Public Member Functions inherited from GNSSBlockInterface

- `virtual gr::basic_block_sptr get_left_block (int RF_channel)`
- `virtual gr::basic_block_sptr get_right_block (int RF_channel)`
- `virtual void start ()`

Start the flow of samples if needed.

12.300.1 Detailed Description

Definition at line 35 of file [notch_filter.h](#).

12.300.2 Member Function Documentation

12.300.2.1 connect()

```
void NotchFilter::connect (
    gr::top_block_sptr top_block) [virtual]
```

Implements [GNSSBlockInterface](#).

12.300.2.2 disconnect()

```
void NotchFilter::disconnect (
    gr::top_block_sptr top_block) [virtual]
```

Implements [GNSSBlockInterface](#).

12.300.2.3 get_left_block()

```
gr::basic_block_sptr NotchFilter::get_left_block () [virtual]
```

Implements [GNSSBlockInterface](#).

12.300.2.4 get_right_block()

```
gr::basic_block_sptr NotchFilter::get_right_block () [virtual]
```

Implements [GNSSBlockInterface](#).

12.300.2.5 implementation()

```
std::string NotchFilter::implementation () [inline], [virtual]
```

Returns "Notch_Filter".

Implements [GNSSBlockInterface](#).

Definition at line 50 of file [notch_filter.h](#).

12.300.2.6 item_size()

```
size_t NotchFilter::item_size () [inline], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 55 of file [notch_filter.h](#).

12.300.2.7 role()

`std::string NotchFilter::role () [inline], [virtual]`

Implements [GNSSBlockInterface](#).

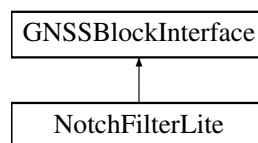
Definition at line 44 of file [notch_filter.h](#).

The documentation for this class was generated from the following file:

- [notch_filter.h](#)

12.301 NotchFilterLite Class Reference

Inheritance diagram for NotchFilterLite:



Public Member Functions

- **NotchFilterLite** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) ()
- std::string [implementation](#) ()
Returns "Notch_Filter_Lite".
- size_t [item_size](#) ()
- void [connect](#) (gr::top_block_sptr top_block)
- void [disconnect](#) (gr::top_block_sptr top_block)
- gr::basic_block_sptr [get_left_block](#) ()
- gr::basic_block_sptr [get_right_block](#) ()

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.301.1 Detailed Description

Definition at line 35 of file [notch_filter_lite.h](#).

12.301.2 Member Function Documentation

12.301.2.1 connect()

`void NotchFilterLite::connect (`
 `gr::top_block_sptr top_block) [virtual]`

Implements [GNSSBlockInterface](#).

12.301.2.2 disconnect()

`void NotchFilterLite::disconnect (`
 `gr::top_block_sptr top_block) [virtual]`

Implements [GNSSBlockInterface](#).

12.301.2.3 get_left_block()

gr::basic_block_sptr NotchFilterLite::get_left_block () [virtual]
 Implements [GNSSBlockInterface](#).

12.301.2.4 get_right_block()

gr::basic_block_sptr NotchFilterLite::get_right_block () [virtual]
 Implements [GNSSBlockInterface](#).

12.301.2.5 implementation()

std::string NotchFilterLite::implementation () [inline], [virtual]
 Returns "Notch_Filter_Lite".
 Implements [GNSSBlockInterface](#).
 Definition at line 50 of file [notch_filter_lite.h](#).

12.301.2.6 item_size()

size_t NotchFilterLite::item_size () [inline], [virtual]
 Implements [GNSSBlockInterface](#).
 Definition at line 55 of file [notch_filter_lite.h](#).

12.301.2.7 role()

std::string NotchFilterLite::role () [inline], [virtual]
 Implements [GNSSBlockInterface](#).
 Definition at line 44 of file [notch_filter_lite.h](#).
 The documentation for this class was generated from the following file:

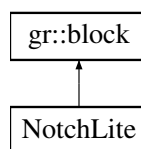
- [notch_filter_lite.h](#)

12.302 NotchLite Class Reference

This class implements a real-time software-defined multi state notch filter light version.

```
#include <notch_lite_cc.h>
```

Inheritance diagram for NotchLite:



Public Member Functions

- int **general_work** (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- notch_lite_sptr **make_notch_filter_lite** (float p_c_factor, float pfa, int32_t length, int32_t n_segments_est, int32_t n_segments_reset, int32_t n_segments_coeff)

12.302.1 Detailed Description

This class implements a real-time software-defined multi state notch filter light version.

Definition at line 49 of file [notch_lite_cc.h](#).

The documentation for this class was generated from the following file:

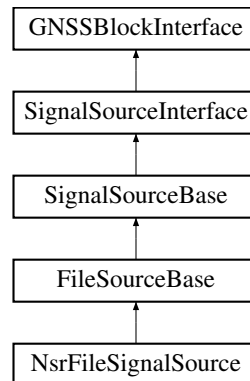
- [notch_lite_cc.h](#)

12.303 NsrFileSignalSource Class Reference

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

```
#include <nsr_file_signal_source.h>
```

Inheritance diagram for NsrFileSignalSource:



Public Member Functions

- **NsrFileSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in←_streams, unsigned int out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue)

Public Member Functions inherited from [FileSourceBase](#)

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- std::string [filename](#) () const
The file to read.
- std::string [item_type](#) () const
The item type.
- size_t [item_size](#) () override
The configured size of each item.
- virtual size_t [item_size](#) () const
- bool [repeat](#) () const
Whether to repeat reading after end-of-file.
- int64_t [sampling_frequency](#) () const
The sampling frequency of the source file.
- uint64_t [samples](#) () const
The number of samples in the file.

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Protected Member Functions

- std::tuple< size_t, bool > [itemTypeToSize](#) () override
Compute the item size, from the [item_type\(\)](#). Subclasses may constrain types that don't make.
- double [packetsPerSample](#) () const override
The number of (possibly unpacked) samples in a (raw) file sample (default=1)
- gnss_shared_ptr< gr::block > [source](#) () const override
Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.
- void [create_file_source_hook](#) () override
- void [pre_connect_hook](#) (gr::top_block_sptr top_block) override
- void [pre_disconnect_hook](#) (gr::top_block_sptr top_block) override

Protected Member Functions inherited from FileSourceBase

- [FileSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string const &role, std::string impl, [Concurrent_Queue](#)< pmt::pmt_t > *queue, std::string default_item_type="short")
Constructor.
- void [init](#) ()
Perform post-construction initialization.
- virtual uint64_t [samplesToSkip](#) () const
Compute the number of samples to skip.
- uint64_t [computeSamplesInFile](#) () const
Compute the number of samples in the file.
- virtual size_t [source_item_size](#) () const
For complex source chains, the size of the file item may not be the same as the size of the.
- bool [is_complex](#) () const
- gnss_shared_ptr< gr::block > [file_source](#) () const
- gnss_shared_ptr< gr::block > [valve](#) () const
- gnss_shared_ptr< gr::block > [throttle](#) () const
- gnss_shared_ptr< gr::block > [sink](#) () const
- SensorDataSource::sptr [sensor_data_source](#) () const
- gr::blocks::file_source::sptr [create_file_source](#) ()
- gr::blocks::throttle::sptr [create_throttle](#) ()
- gnss_shared_ptr< gr::block > [create_valve](#) ()
- gr::blocks::file_sink::sptr [create_sink](#) ()
- SensorDataSource::sptr [create_sensor_data_source](#) ()
- virtual void [create_throttle_hook](#) ()
- virtual void [create_valve_hook](#) ()
- virtual void [create_sink_hook](#) ()
- virtual void [post_connect_hook](#) (gr::top_block_sptr top_block)
- virtual void [post_disconnect_hook](#) (gr::top_block_sptr top_block)

Protected Member Functions inherited from SignalSourceBase

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↔ error=false)
utility for decoding passed ".item_type" values

12.303.1 Detailed Description

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
Definition at line 41 of file [nsr_file_signal_source.h](#).

12.303.2 Member Function Documentation

12.303.2.1 create_file_source_hook()

```
void NsrFileSignalSource::create_file_source_hook () [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.303.2.2 itemTypeToSize()

```
std::tuple< size_t, bool > NsrFileSignalSource::itemTypeToSize () [override], [protected], [virtual]
```

Compute the item size, from the [item_type\(\)](#). Subclasses may constrain types that don't make.
Reimplemented from [FileSourceBase](#).

12.303.2.3 packetsPerSample()

```
double NsrFileSignalSource::packetsPerSample () const [override], [protected], [virtual]
```

The number of (possibly unpacked) samples in a (raw) file sample (default=1)
Reimplemented from [FileSourceBase](#).

12.303.2.4 pre_connect_hook()

```
void NsrFileSignalSource::pre_connect_hook (
    gr::top_block_sptr top_block) [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.303.2.5 pre_disconnect_hook()

```
void NsrFileSignalSource::pre_disconnect_hook (
    gr::top_block_sptr top_block) [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.303.2.6 source()

```
gnss_shared_ptr< gr::block > NsrFileSignalSource::source () const [override], [protected], [virtual]
```

Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.

Reimplemented from [FileSourceBase](#).

The documentation for this class was generated from the following file:

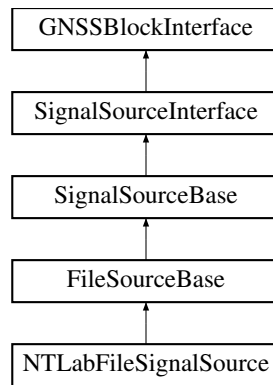
- [nsr_file_signal_source.h](#)

12.304 NTLabFileSignalSource Class Reference

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

```
#include <ntlab_file_signal_source.h>
```

Inheritance diagram for NTLabFileSignalSource:



Public Member Functions

- **NTLabFileSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [FileSourceBase](#)

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- std::string [filename](#) () const
The file to read.
- std::string [item_type](#) () const
The item type.
- size_t [item_size](#) () override
The configured size of each item.
- virtual size_t [item_size](#) () const
- bool [repeat](#) () const
Whether to repeat reading after end-of-file.
- int64_t [sampling_frequency](#) () const
The sampling frequency of the source file.
- uint64_t [samples](#) () const
The number of samples in the file.

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Protected Member Functions

- `std::tuple< size_t, bool > itemTypeToSize ()` override
Compute the item size, from the `item_type()`. Subclasses may constrain types that don't make.
- `double packetsPerSample ()` const override
The number of (possibly unpacked) samples in a (raw) file sample (default=1)
- `gnss_shared_ptr< gr::block > source ()` const override
Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.
- `void create_file_source_hook ()` override
- `void pre_connect_hook (gr::top_block_sptr top_block)` override
- `void pre_disconnect_hook (gr::top_block_sptr top_block)` override

Protected Member Functions inherited from `FileSourceBase`

- `FileSourceBase (ConfigurationInterface const *configuration, std::string const &role, std::string impl, Concurrent_Queue< pmt::pmt_t > *queue, std::string default_item_type="short")`
Constructor.
- `void init ()`
Perform post-construction initialization.
- `virtual uint64_t samplesToSkip ()` const
Compute the number of samples to skip.
- `uint64_t computeSamplesInFile ()` const
Compute the number of samples in the file.
- `virtual size_t source_item_size ()` const
For complex source chains, the size of the file item may not be the same as the size of the.
- `bool is_complex ()` const
- `gnss_shared_ptr< gr::block > file_source ()` const
- `gnss_shared_ptr< gr::block > valve ()` const
- `gnss_shared_ptr< gr::block > throttle ()` const
- `gnss_shared_ptr< gr::block > sink ()` const
- `SensorDataSource::sptr sensor_data_source ()` const
- `gr::blocks::file_source::sptr create_file_source ()`
- `gr::blocks::throttle::sptr create_throttle ()`
- `gnss_shared_ptr< gr::block > create_valve ()`
- `gr::blocks::file_sink::sptr create_sink ()`
- `SensorDataSource::sptr create_sensor_data_source ()`
- `virtual void create_throttle_hook ()`
- `virtual void create_valve_hook ()`
- `virtual void create_sink_hook ()`
- `virtual void post_connect_hook (gr::top_block_sptr top_block)`
- `virtual void post_disconnect_hook (gr::top_block_sptr top_block)`

Protected Member Functions inherited from `SignalSourceBase`

- `SignalSourceBase (ConfigurationInterface const *configuration, std::string role, std::string impl)`
Constructor.
- `size_t decode_item_type (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_error=false)`
utility for decoding passed ".item_type" values

12.304.1 Detailed Description

Class that reads signals samples from a file and adapts it to a `SignalSourceInterface`.
Definition at line 43 of file `ntlab_file_signal_source.h`.

12.304.2 Member Function Documentation

12.304.2.1 create_file_source_hook()

void NTLabFileSignalSource::create_file_source_hook () [override], [protected], [virtual]
Reimplemented from [FileSourceBase](#).

12.304.2.2 get_left_block()

gr::basic_block_sptr NTLabFileSignalSource::get_left_block () [override], [virtual]
Reimplemented from [FileSourceBase](#).

12.304.2.3 get_right_block()

gr::basic_block_sptr NTLabFileSignalSource::get_right_block () [override], [virtual]
Reimplemented from [FileSourceBase](#).

12.304.2.4 itemTypeToSize()

std::tuple< size_t, bool > NTLabFileSignalSource::itemTypeToSize () [override], [protected], [virtual]
Compute the item size, from the [item_type\(\)](#). Subclasses may constrain types that don't make.
Reimplemented from [FileSourceBase](#).

12.304.2.5 packetsPerSample()

double NTLabFileSignalSource::packetsPerSample () const [override], [protected], [virtual]
The number of (possibly unpacked) samples in a (raw) file sample (default=1)
Reimplemented from [FileSourceBase](#).

12.304.2.6 pre_connect_hook()

void NTLabFileSignalSource::pre_connect_hook (
gr::top_block_sptr top_block) [override], [protected], [virtual]
Reimplemented from [FileSourceBase](#).

12.304.2.7 pre_disconnect_hook()

void NTLabFileSignalSource::pre_disconnect_hook (
gr::top_block_sptr top_block) [override], [protected], [virtual]
Reimplemented from [FileSourceBase](#).

12.304.2.8 source()

gnss_shared_ptr< gr::block > NTLabFileSignalSource::source () const [override], [protected], [virtual]
Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.
Reimplemented from [FileSourceBase](#).
The documentation for this class was generated from the following file:

- [ntlab_file_signal_source.h](#)

12.305 ntrip_t Struct Reference

Public Attributes

- int [state](#)
- int [type](#)
- int [nb](#)

- char [url](#) [256]
- char [mntpnt](#) [256]
- char [user](#) [256]
- char [passwd](#) [256]
- char [str](#) [NTRIP_MAXSTR]
- unsigned char [buff](#) [NTRIP_MAXRSP]
- [tcpcli_t](#) * [tcp](#)

12.305.1 Detailed Description

Definition at line [1170](#) of file [rtklib.h](#).

12.305.2 Member Data Documentation

12.305.2.1 buff

```
unsigned char ntrip_t::buff[NTRIP_MAXRSP]
```

Definition at line [1180](#) of file [rtklib.h](#).

12.305.2.2 mntpnt

```
char ntrip_t::mntpnt[256]
```

Definition at line [1176](#) of file [rtklib.h](#).

12.305.2.3 nb

```
int ntrip_t::nb
```

Definition at line [1174](#) of file [rtklib.h](#).

12.305.2.4 passwd

```
char ntrip_t::passwd[256]
```

Definition at line [1178](#) of file [rtklib.h](#).

12.305.2.5 state

```
int ntrip_t::state
```

Definition at line [1172](#) of file [rtklib.h](#).

12.305.2.6 str

```
char ntrip_t::str[NTRIP_MAXSTR]
```

Definition at line [1179](#) of file [rtklib.h](#).

12.305.2.7 tcp

```
tcpcli\_t* ntrip_t::tcp
```

Definition at line [1181](#) of file [rtklib.h](#).

12.305.2.8 type

```
int ntrip_t::type
```

Definition at line [1173](#) of file [rtklib.h](#).

12.305.2.9 url

```
char ntrip_t::url[256]
```

Definition at line [1175](#) of file [rtklib.h](#).

12.305.2.10 user

```
char ntrip_t::user[256]
```

Definition at line 1177 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.306 Obs_Conf Class Reference

Public Attributes

- std::string [dump_filename](#) {"obs_dump.dat"}
- int32_t [smoothing_factor](#) {0}
- uint32_t [nchannels_in](#) {0U}
- uint32_t [nchannels_out](#) {0U}
- uint32_t [observable_interval_ms](#) {20U}
- bool [enable_carrier_smoothing](#) {false}
- bool [always_output_gs](#) {false}
- bool [dump](#) {false}
- bool [dump_mat](#) {false}
- bool [enable_E6](#) {false}

12.306.1 Detailed Description

Definition at line 30 of file [obs_conf.h](#).

12.306.2 Member Data Documentation

12.306.2.1 always_output_gs

```
bool Obs_Conf::always_output_gs {false}
```

Definition at line 41 of file [obs_conf.h](#).

12.306.2.2 dump

```
bool Obs_Conf::dump {false}
```

Definition at line 42 of file [obs_conf.h](#).

12.306.2.3 dump_filename

```
std::string Obs_Conf::dump_filename {"obs_dump.dat"}
```

Definition at line 35 of file [obs_conf.h](#).

12.306.2.4 dump_mat

```
bool Obs_Conf::dump_mat {false}
```

Definition at line 43 of file [obs_conf.h](#).

12.306.2.5 enable_carrier_smoothing

```
bool Obs_Conf::enable_carrier_smoothing {false}
```

Definition at line 40 of file [obs_conf.h](#).

12.306.2.6 enable_E6

```
bool Obs_Conf::enable_E6 {false}
```

Definition at line 44 of file [obs_conf.h](#).

12.306.2.7 nchannels_in

```
uint32_t Obs_Conf::nchannels_in {0U}
```

Definition at line 37 of file [obs_conf.h](#).

12.306.2.8 nchannels_out

```
uint32_t Obs_Conf::nchannels_out {0U}
```

Definition at line 38 of file [obs_conf.h](#).

12.306.2.9 observable_interval_ms

```
uint32_t Obs_Conf::observable_interval_ms {20U}
```

Definition at line 39 of file [obs_conf.h](#).

12.306.2.10 smoothing_factor

```
int32_t Obs_Conf::smoothing_factor {0}
```

Definition at line 36 of file [obs_conf.h](#).

The documentation for this class was generated from the following file:

- [obs_conf.h](#)

12.307 obs_t Struct Reference

Public Attributes

- int [n](#)
- int [nmax](#)
- [obsd_t](#) * [data](#)

12.307.1 Detailed Description

Definition at line 376 of file [rtklib.h](#).

12.307.2 Member Data Documentation

12.307.2.1 data

```
obsd\_t* obs\_t::data
```

Definition at line 379 of file [rtklib.h](#).

12.307.2.2 n

```
int obs\_t::n
```

Definition at line 378 of file [rtklib.h](#).

12.307.2.3 nmax

```
int obs\_t::nmax
```

Definition at line 378 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.308 obsd_t Struct Reference

Public Attributes

- [gtime_t](#) `time`
- unsigned char `sat`
- unsigned char `rcv`
- unsigned char `SNR` [[NFREQ+NEXOBS](#)]
- unsigned char `LLI` [[NFREQ+NEXOBS](#)]
- unsigned char `code` [[NFREQ+NEXOBS](#)]
- double `L` [[NFREQ+NEXOBS](#)]
- double `P` [[NFREQ+NEXOBS](#)]
- float `D` [[NFREQ+NEXOBS](#)]

12.308.1 Detailed Description

Definition at line 363 of file [rtklib.h](#).

12.308.2 Member Data Documentation

12.308.2.1 code

```
unsigned char obsd_t::code[NFREQ+NEXOBS]
```

Definition at line 369 of file [rtklib.h](#).

12.308.2.2 D

```
float obsd_t::D[NFREQ+NEXOBS]
```

Definition at line 372 of file [rtklib.h](#).

12.308.2.3 L

```
double obsd_t::L[NFREQ+NEXOBS]
```

Definition at line 370 of file [rtklib.h](#).

12.308.2.4 LLI

```
unsigned char obsd_t::LLI[NFREQ+NEXOBS]
```

Definition at line 368 of file [rtklib.h](#).

12.308.2.5 P

```
double obsd_t::P[NFREQ+NEXOBS]
```

Definition at line 371 of file [rtklib.h](#).

12.308.2.6 rcv

```
unsigned char obsd_t::rcv
```

Definition at line 366 of file [rtklib.h](#).

12.308.2.7 sat

```
unsigned char obsd_t::sat
```

Definition at line 366 of file [rtklib.h](#).

12.308.2.8 SNR

```
unsigned char obsd_t::SNR[NFREQ+NEXOBS]
```

Definition at line 367 of file [rtklib.h](#).

12.308.2.9 time

`ptime_t obsd_t::time`

Definition at line 365 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

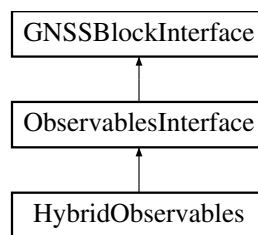
- [rtklib.h](#)

12.309 ObservablesInterface Class Reference

This abstract class represents an interface to an observables block.

`#include <observables_interface.h>`

Inheritance diagram for ObservablesInterface:



Public Member Functions

- virtual void **reset** ()=0

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual std::string **role** ()=0
- virtual std::string **implementation** ()=0
- virtual size_t **item_size** ()=0
- virtual void **connect** (gr::top_block_sptr top_block)=0
- virtual void **disconnect** (gr::top_block_sptr top_block)=0
- virtual gr::basic_block_sptr **get_left_block** ()=0
- virtual gr::basic_block_sptr **get_right_block** ()=0
- virtual gr::basic_block_sptr **get_left_block** (int RF_channel)
- virtual gr::basic_block_sptr **get_right_block** (int RF_channel)
- virtual void **start** ()

Start the flow of samples if needed.

12.309.1 Detailed Description

This abstract class represents an interface to an observables block.

Abstract class for pseudorange_interfaces, derived from [GNSSBlockInterface](#). Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

Definition at line 43 of file [observables_interface.h](#).

The documentation for this class was generated from the following file:

- [observables_interface.h](#)

12.310 opt_t Struct Reference

Public Attributes

- const char * **name**

- int [format](#)
- void * [var](#)
- const char * [comment](#)

12.310.1 Detailed Description

Definition at line 917 of file [rtklib.h](#).

12.310.2 Member Data Documentation

12.310.2.1 comment

```
const char* opt_t::comment
```

Definition at line 922 of file [rtklib.h](#).

12.310.2.2 format

```
int opt_t::format
```

Definition at line 920 of file [rtklib.h](#).

12.310.2.3 name

```
const char* opt_t::name
```

Definition at line 919 of file [rtklib.h](#).

12.310.2.4 var

```
void* opt_t::var
```

Definition at line 921 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

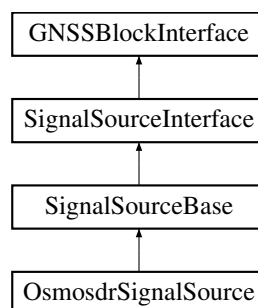
- [rtklib.h](#)

12.311 OsmosdrSignalSource Class Reference

This class reads samples OsmoSDR-compatible front-ends, such as HackRF or Realtek's RTL2832U-based USB dongle DVB-T receivers (see <https://osmocom.org/projects/rtl-sdr/wiki>)

```
#include <osmosdr_signal_source.h>
```

Inheritance diagram for OsmosdrSignalSource:



Public Member Functions

- **OsmosdrSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override

- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↔ error=false)
utility for decoding passed ".item_type" values

12.311.1 Detailed Description

This class reads samples OsmoSDR-compatible front-ends, such as HackRF or Realtek's RTL2832U-based USB dongle DVB-T receivers (see <https://osmocom.org/projects/rtl-sdr/wiki>)
Definition at line 45 of file [osmosdr_signal_source.h](#).

12.311.2 Member Function Documentation

12.311.2.1 connect()

```
void OsmosdrSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.311.2.2 disconnect()

```
void OsmosdrSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.311.2.3 get_left_block()

```
gr::basic_block_sptr OsmosdrSignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.311.2.4 get_right_block()

```
gr::basic_block_sptr OsmosdrSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.311.2.5 item_size()

size_t OsmosdrSignalSource::item_size () [inline], [override], [virtual]

Implements [GNSSBlockInterface](#).

Definition at line 54 of file [osmosdr_signal_source.h](#).

The documentation for this class was generated from the following file:

- [osmosdr_signal_source.h](#)

12.312 OSNMA_data Class Reference

This class handles OSNMA data See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OSNMA_User_ICD_for_Test_Phase_v1.0.pdf.

#include <osnma_data.h>

Public Attributes

- [DSM_nma_header](#) d_nma_header
- [DSM_dsm_header](#) d_dsm_header
- [DSM_PKR_message](#) d_dsm_pkr_message
- [DSM_KROOT_message](#) d_dsm_kroot_message
- [DSM_KROOT_message](#) d_dsm_kroot_new_message
- [MACK_message](#) d_mack_message
- [OSNMA_NavData](#) d_nav_data

12.312.1 Detailed Description

This class handles OSNMA data See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OSNMA_User_ICD_for_Test_Phase_v1.0.pdf.

Definition at line 178 of file [osnma_data.h](#).

12.312.2 Member Data Documentation

12.312.2.1 d_dsm_header

[DSM_dsm_header](#) OSNMA_data::d_dsm_header

Definition at line 183 of file [osnma_data.h](#).

12.312.2.2 d_dsm_kroot_message

[DSM_KROOT_message](#) OSNMA_data::d_dsm_kroot_message

Definition at line 185 of file [osnma_data.h](#).

12.312.2.3 d_dsm_kroot_new_message

[DSM_KROOT_message](#) OSNMA_data::d_dsm_kroot_new_message

Definition at line 186 of file [osnma_data.h](#).

12.312.2.4 d_dsm_pkr_message

[DSM_PKR_message](#) OSNMA_data::d_dsm_pkr_message

Definition at line 184 of file [osnma_data.h](#).

12.312.2.5 d_mack_message

[MACK_message](#) OSNMA_data::d_mack_message

Definition at line 187 of file [osnma_data.h](#).

12.312.2.6 d_nav_data

[OSNMA_NavData](#) OSNMA_data::d_nav_data

Definition at line 188 of file [osnma_data.h](#).

12.312.2.7 d_nma_header

[DSM_nma_header](#) OSNMA_data::d_nma_header

Definition at line 182 of file [osnma_data.h](#).

The documentation for this class was generated from the following file:

- [osnma_data.h](#)

12.313 OSNMA_DSM_Reader Class Reference

Public Member Functions

- `uint8_t get_nmas (uint8_t nma_header) const`
- `uint8_t get_cid (uint8_t nma_header) const`
- `uint8_t get_cpks (uint8_t nma_header) const`
- `bool get_nma_header_reserved (uint8_t nma_header) const`
- `uint8_t get_dsm_id (uint8_t dsm_header) const`
- `uint8_t get_dsm_block_id (uint8_t dsm_header) const`
- `uint8_t get_number_blocks_index (uint8_t dsm_msg_0) const`
- `uint8_t get_pkid (const std::vector< uint8_t > &dsm_msg) const`
- `uint8_t get_cidkr (const std::vector< uint8_t > &dsm_msg) const`
- `uint8_t get_dsm_reserved1 (const std::vector< uint8_t > &dsm_msg) const`
- `uint8_t get_hf (const std::vector< uint8_t > &dsm_msg) const`
- `uint8_t get_mf (const std::vector< uint8_t > &dsm_msg) const`
- `uint8_t get_ks (const std::vector< uint8_t > &dsm_msg) const`
- `uint8_t get_ts (const std::vector< uint8_t > &dsm_msg) const`
- `uint8_t get_mac1t (const std::vector< uint8_t > &dsm_msg) const`
- `uint8_t get_dsm_reserved (const std::vector< uint8_t > &dsm_msg) const`
- `uint16_t get_wn_k (const std::vector< uint8_t > &dsm_msg) const`
- `uint8_t get_towh_k (const std::vector< uint8_t > &dsm_msg) const`
- `uint64_t get_alpha (const std::vector< uint8_t > &dsm_msg) const`
- `uint16_t get_l_dk_bits (uint8_t nb_dk) const`
- `uint16_t get_lk_bits (uint8_t ks) const`
- `std::vector< uint8_t > get_kroot (const std::vector< uint8_t > &dsm_msg, uint16_t bytes_lk) const`
- `std::string get_hash_function (uint8_t hf) const`
- `std::string get_nmas_status (uint8_t nmas) const`
- `std::string get_cpks_status (uint8_t cpks) const`
- `uint8_t get_mid (const std::vector< uint8_t > &dsm_msg) const`
- `uint8_t get_npkt (const std::vector< uint8_t > &dsm_msg) const`
- `uint8_t get_npktid (const std::vector< uint8_t > &dsm_msg) const`

12.313.1 Detailed Description

Definition at line 29 of file [osnma_dsm_reader.h](#).

The documentation for this class was generated from the following file:

- [osnma_dsm_reader.h](#)

12.314 Osnma_Helper Class Reference

Public Member Functions

- uint32_t **compute_gst** (uint32_t WN, uint32_t TOW) const
- uint32_t **compute_gst** (std::tm &input)
- uint32_t **compute_gst_now** ()
- uint32_t **get_WN** (uint32_t GST) const
- uint32_t **get_TOW** (uint32_t GST) const
- std::vector< uint8_t > **gst_to_uint8** (uint32_t GST) const
- std::vector< uint8_t > **bytes** (const std::string &binaryString) const
- std::string **verification_status_str** (int status) const
- std::string **convert_to_hex_string** (const std::vector< uint8_t > &vector) const
- std::vector< uint8_t > **convert_from_hex_string** (const std::string &hex_string) const

Public Attributes

- std::tm [GST_START_EPOCH](#) {}

12.314.1 Detailed Description

Definition at line 31 of file [osnma_helper.h](#).

12.314.2 Member Data Documentation

12.314.2.1 GST_START_EPOCH

std::tm Osnma_Helper::GST_START_EPOCH {}

Definition at line 46 of file [osnma_helper.h](#).

The documentation for this class was generated from the following file:

- [osnma_helper.h](#)

12.315 OSNMA_msg Class Reference

This class fills the [OSNMA_msg](#) structure with the data received from the telemetry blocks.

#include <galileo_inav_message.h>

Public Attributes

- std::array< uint32_t, 15 > [mack](#) {}
- std::array< uint8_t, 15 > [hkroot](#) {}
- uint32_t [PRN](#) {}
- uint32_t [WN_sf0](#) {}
- uint32_t [TOW_sf0](#) {}

12.315.1 Detailed Description

This class fills the [OSNMA_msg](#) structure with the data received from the telemetry blocks.

Definition at line 46 of file [galileo_inav_message.h](#).

12.315.2 Member Data Documentation

12.315.2.1 hkroot

std::array<uint8_t, 15> OSNMA_msg::hkroot {}

Definition at line 51 of file [galileo_inav_message.h](#).

12.315.2.2 mack

```
std::array<uint32_t, 15> OSNMA_msg::mack {}
```

Definition at line 50 of file [galileo_inav_message.h](#).

12.315.2.3 PRN

```
uint32_t OSNMA_msg::PRN {}
```

Definition at line 52 of file [galileo_inav_message.h](#).

12.315.2.4 TOW_sf0

```
uint32_t OSNMA_msg::TOW_sf0 {}
```

Definition at line 54 of file [galileo_inav_message.h](#).

12.315.2.5 WN_sf0

```
uint32_t OSNMA_msg::WN_sf0 {}
```

Definition at line 53 of file [galileo_inav_message.h](#).

The documentation for this class was generated from the following file:

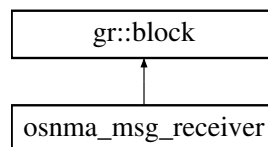
- [galileo_inav_message.h](#)

12.316 osnma_msg_receiver Class Reference

GNU Radio block that receives asynchronous OSNMA messages from the telemetry blocks, stores them in memory, and decodes OSNMA info when enough data have been received. The decoded OSNMA data is sent to the PVT block.

```
#include <osnma_msg_receiver.h>
```

Inheritance diagram for `osnma_msg_receiver`:

**Public Member Functions**

- `~osnma_msg_receiver()` = default
Default destructor.
- `bool verify_dsm_pkr(const DSM_PKR_message &message) const`
Public for benchmarking purposes.
- `void msg_handler_osnma(const pmt::pmt_t &msg)`
For testing purposes.
- `void read_merkle_xml(const std::string &merklepath)`
Public for testing purposes.
- `void set_merkle_root(const std::vector< uint8_t > &v)`
Public for benchmarking purposes.

Friends

- `osnma_msg_receiver_sptr osnma_msg_receiver_make(const std::string &pemFilePath, const std::string &merkleFilePath, bool strict_mode=false)`

12.316.1 Detailed Description

GNU Radio block that receives asynchronous OSNMA messages from the telemetry blocks, stores them in memory, and decodes OSNMA info when enough data have been received. The decoded OSNMA data is sent to the PVT block.

Definition at line 61 of file [osnma_msg_receiver.h](#).

12.316.2 Constructor & Destructor Documentation

12.316.2.1 ~osnma_msg_receiver()

```
osnma_msg_receiver::~osnma_msg_receiver () [default]
```

Default destructor.

12.316.3 Member Function Documentation

12.316.3.1 msg_handler_osnma()

```
void osnma_msg_receiver::msg_handler_osnma (
    const pmt::pmt_t & msg)
```

For testing purposes.

12.316.3.2 read_merkle_xml()

```
void osnma_msg_receiver::read_merkle_xml (
    const std::string & merklepath)
```

Public for testing purposes.

12.316.3.3 set_merkle_root()

```
void osnma_msg_receiver::set_merkle_root (
    const std::vector< uint8_t > & v)
```

Public for benchmarking purposes.

12.316.3.4 verify_dsm_pkr()

```
bool osnma_msg_receiver::verify_dsm_pkr (
    const DSM\_PKR\_message & message) const
```

Public for benchmarking purposes.

The documentation for this class was generated from the following file:

- [osnma_msg_receiver.h](#)

12.317 OSNMA_NavData Class Reference

Public Member Functions

- std::string [get_utc_data](#) () const
- std::string [get_ephemeris_data](#) () const
- uint32_t [get_verified_bits](#) () const
- uint32_t [get_prn_d](#) () const
- uint32_t [get_IOD_nav](#) () const
- uint32_t [get_last_received_TOW](#) () const
- uint32_t [get_tow_sf0](#) () const
- bool [have_this_bits](#) (std::string nav_data)
- bool [get_verified_status](#) () const
- bool [add_nav_data](#) (const std::string &nav_data)
- void [set_tow_sf0](#) (int value)
- void [set_ephemeris_data](#) (std::string value)

- void [set_utc_data](#) (std::string value)
- void **update_last_received_timestamp** (uint32_t TOW)
- void [set_prn_d](#) (uint32_t value)
- void [set_last_received_TOW](#) (uint32_t TOW)
- void [set_update_verified_bits](#) (uint32_t morebits)
- void [set_verified_status](#) (bool value)
- void [set_IOD_nav](#) (uint32_t value)

Public Attributes

- const uint32_t [nav_data_id](#)

12.317.1 Detailed Description

Definition at line 136 of file [osnma_data.h](#).

12.317.2 Constructor & Destructor Documentation

12.317.2.1 OSNMA_NavData()

```
OSNMA_NavData::OSNMA_NavData () [inline]
```

Definition at line 139 of file [osnma_data.h](#).

12.317.3 Member Function Documentation

12.317.3.1 get_IOD_nav()

```
uint32_t OSNMA_NavData::get_IOD_nav () const [inline]
```

Definition at line 145 of file [osnma_data.h](#).

12.317.3.2 get_last_received_TOW()

```
uint32_t OSNMA_NavData::get_last_received_TOW () const [inline]
```

Definition at line 146 of file [osnma_data.h](#).

12.317.3.3 get_prn_d()

```
uint32_t OSNMA_NavData::get_prn_d () const [inline]
```

Definition at line 144 of file [osnma_data.h](#).

12.317.3.4 get_tow_sf0()

```
uint32_t OSNMA_NavData::get_tow_sf0 () const [inline]
```

Definition at line 147 of file [osnma_data.h](#).

12.317.3.5 get_verified_bits()

```
uint32_t OSNMA_NavData::get_verified_bits () const [inline]
```

Definition at line 143 of file [osnma_data.h](#).

12.317.3.6 get_verified_status()

```
bool OSNMA_NavData::get_verified_status () const [inline]
```

Definition at line 149 of file [osnma_data.h](#).

12.317.3.7 set_ephemeris_data()

```
void OSNMA_NavData::set_ephemeris_data (
    std::string value) [inline]
```

Definition at line 152 of file [osnma_data.h](#).

12.317.3.8 set_IOD_nav()

```
void OSNMA_NavData::set_IOD_nav (
    uint32_t value) [inline]
```

Definition at line 159 of file [osnma_data.h](#).

12.317.3.9 set_last_received_TOW()

```
void OSNMA_NavData::set_last_received_TOW (
    uint32_t TOW) [inline]
```

Definition at line 156 of file [osnma_data.h](#).

12.317.3.10 set_prn_d()

```
void OSNMA_NavData::set_prn_d (
    uint32_t value) [inline]
```

Definition at line 155 of file [osnma_data.h](#).

12.317.3.11 set_tow_sf0()

```
void OSNMA_NavData::set_tow_sf0 (
    int value) [inline]
```

Definition at line 151 of file [osnma_data.h](#).

12.317.3.12 set_update_verified_bits()

```
void OSNMA_NavData::set_update_verified_bits (
    uint32_t morebits) [inline]
```

Definition at line 157 of file [osnma_data.h](#).

12.317.3.13 set_utc_data()

```
void OSNMA_NavData::set_utc_data (
    std::string value) [inline]
```

Definition at line 153 of file [osnma_data.h](#).

12.317.3.14 set_verified_status()

```
void OSNMA_NavData::set_verified_status (
    bool value) [inline]
```

Definition at line 158 of file [osnma_data.h](#).

12.317.4 Member Data Documentation

12.317.4.1 nav_data_id

```
const uint32_t OSNMA_NavData::nav_data_id
```

Definition at line 140 of file [osnma_data.h](#).

The documentation for this class was generated from the following file:

- [osnma_data.h](#)

12.318 OSNMA_NavDataManager Class Reference

Class for managing OSNMA navigation data.

```
#include <osnma_nav_data_manager.h>
```

Public Member Functions

- void **log_status** () const
- bool **have_nav_data** (const [Tag](#) &t) const
- bool **have_nav_data** (uint32_t PRNd, uint32_t TOW, uint8_t ADKD) const
- std::string **get_navigation_data** (const [Tag](#) &t) const
- void **add_navigation_data** (const std::string &nav_bits, uint32_t PRNd, uint32_t TOW)
- void **update_nav_data** (const std::multimap< uint32_t, [Tag](#) > &tags_verified, uint8_t tag_size)
- bool **have_nav_data** (const std::string &nav_bits, uint32_t PRNd, uint32_t TOW)
- std::vector< [OSNMA_NavData](#) > **get_verified_data** ()

12.318.1 Detailed Description

Class for managing OSNMA navigation data.

Definition at line 35 of file [osnma_nav_data_manager.h](#).

The documentation for this class was generated from the following file:

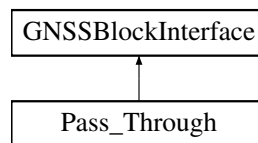
- [osnma_nav_data_manager.h](#)

12.319 Pass_Through Class Reference

This class implements a block that connects input and output (does nothing)

```
#include <pass_through.h>
```

Inheritance diagram for Pass_Through:



Public Member Functions

- **Pass_Through** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream)
- std::string [role](#) () override
- std::string [implementation](#) () override
Returns "Pass_Through".
- std::string [item_type](#) () const
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.319.1 Detailed Description

This class implements a block that connects input and output (does nothing)

Definition at line 42 of file [pass_through.h](#).

12.319.2 Member Function Documentation

12.319.2.1 connect()

```
void Pass_Through::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.319.2.2 disconnect()

```
void Pass_Through::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.319.2.3 get_left_block()

```
gr::basic_block_sptr Pass_Through::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.319.2.4 get_right_block()

```
gr::basic_block_sptr Pass_Through::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.319.2.5 implementation()

```
std::string Pass_Through::implementation () [inline], [override], [virtual]
```

Returns "Pass_Through".
Implements [GNSSBlockInterface](#).
Definition at line 58 of file [pass_through.h](#).

12.319.2.6 item_size()

```
size_t Pass_Through::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).
Definition at line 68 of file [pass_through.h](#).

12.319.2.7 item_type()

```
std::string Pass_Through::item_type () const [inline]
```

Definition at line 63 of file [pass_through.h](#).

12.319.2.8 role()

```
std::string Pass_Through::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).
Definition at line 52 of file [pass_through.h](#).

The documentation for this class was generated from the following file:

- [pass_through.h](#)

12.320 pclk_t Struct Reference

Public Attributes

- [gtime_t](#) time
- int [index](#)
- double [clk](#) [MAXSAT][1]
- float [std](#) [MAXSAT][1]

12.320.1 Detailed Description

Definition at line 492 of file [rtklib.h](#).

12.320.2 Member Data Documentation

12.320.2.1 clk

```
double pclk_t::clk[MAXSAT][1]
```

Definition at line 496 of file [rtklib.h](#).

12.320.2.2 index

```
int pclk_t::index
```

Definition at line 495 of file [rtklib.h](#).

12.320.2.3 std

```
float pclk_t::std[MAXSAT][1]
```

Definition at line 497 of file [rtklib.h](#).

12.320.2.4 time

```
ptime_t pclk_t::time
```

Definition at line 494 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

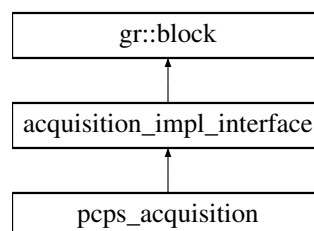
- [rtklib.h](#)

12.321 pcps_acquisition Class Reference

This class implements a Parallel Code Phase Search Acquisition.

```
#include <pcps_acquisition.h>
```

Inheritance diagram for pcps_acquisition:



Public Member Functions

- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [set_local_code](#) (std::complex< float > *code) override
Sets local code for PCPS acquisition algorithm.
- void [set_resampler_latency](#) (uint32_t latency_samples)
- uint32_t [mag](#) () const override
Returns the maximum peak of grid search.
- void [set_active](#) (bool active) override
Starts acquisition algorithm, turning from standby mode to active mode.
- void [set_channel](#) (uint32_t channel) override
Set acquisition channel unique ID.

- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int32_t doppler_center)
Set Doppler center frequency for the grid search. It will refresh the Doppler grid.
- int [general_work](#) (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
Parallel Code Phase Search Acquisition signal processing.

Public Member Functions inherited from [acquisition_impl_interface](#)

- [acquisition_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_local_code](#) (std::complex< float > *, std::complex< float > *)

Friends

- pcps_acquisition_sptr [pcps_make_acquisition](#) (const [Acq_Conf](#) &conf_)

12.321.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition.

Check [An Open Source Galileo E1 Software Receiver](#), Algorithm 1, for a pseudocode description of this implementation.

Definition at line 93 of file [pcps_acquisition.h](#).

12.321.2 Member Function Documentation

12.321.2.1 [general_work\(\)](#)

```
int pcps_acquisition::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

Parallel Code Phase Search Acquisition signal processing.

12.321.2.2 [mag\(\)](#)

```
uint32_t pcps_acquisition::mag () const [inline], [override], [virtual]
```

Returns the maximum peak of grid search.

Implements [acquisition_impl_interface](#).

Definition at line 120 of file [pcps_acquisition.h](#).

12.321.2.3 [set_active\(\)](#)

```
void pcps_acquisition::set_active (
    bool active) [override], [virtual]
```

Starts acquisition algorithm, turning from standby mode to active mode.

Parameters

<i>active</i>	- bool that activates/deactivates the block.
---------------	--

Implements [acquisition_impl_interface](#).

12.321.2.4 set_channel()

```
void pcps_acquisition::set_channel (  
    uint32_t channel) [inline], [override], [virtual]
```

Set acquisition channel unique ID.

Parameters

<i>channel</i>	- receiver channel.
----------------	---------------------

Implements [acquisition_impl_interface](#).

Definition at line 136 of file [pcps_acquisition.h](#).

12.321.2.5 set_channel_fsm()

```
void pcps_acquisition::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [inline], [override], [virtual]
```

Set channel fsm associated to this acquisition instance.

Implements [acquisition_impl_interface](#).

Definition at line 144 of file [pcps_acquisition.h](#).

12.321.2.6 set_doppler_center()

```
void pcps_acquisition::set_doppler_center (
    int32_t doppler_center)
```

Set Doppler center frequency for the grid search. It will refresh the Doppler grid.

Parameters

<i>doppler_center</i>	- Frequency center of the search grid [Hz].
-----------------------	---

12.321.2.7 set_gnss_synchro()

```
void pcps_acquisition::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [inline], [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.

Parameters

<i>p_gnss_synchro</i>	Satellite information shared by the processing blocks.
-----------------------	--

Implements [acquisition_impl_interface](#).

Definition at line 103 of file [pcps_acquisition.h](#).

12.321.2.8 set_local_code()

```
void pcps_acquisition::set_local_code (
    std::complex< float > * code) [override], [virtual]
```

Sets local code for PCPS acquisition algorithm.

Parameters

<i>code</i>	- Pointer to the PRN code.
-------------	----------------------------

Reimplemented from [acquisition_impl_interface](#).

The documentation for this class was generated from the following file:

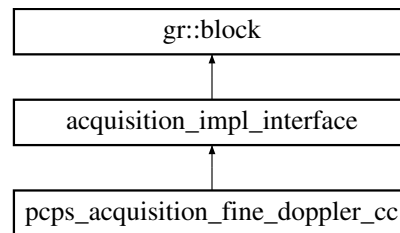
- [pcps_acquisition.h](#)

12.322 pcps_acquisition_fine_doppler_cc Class Reference

This class implements a Parallel Code Phase Search Acquisition.

```
#include <pcps_acquisition_fine_doppler_cc.h>
```

Inheritance diagram for pcps_acquisition_fine_doppler_cc:



Public Member Functions

- `~pcps_acquisition_fine_doppler_cc()`=default
Default destructor.
- void `set_gnss_synchro` (`Gnss_Synchro` *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- unsigned int `mag` () const override
Returns the maximum peak of grid search.
- void `set_local_code` (`std::complex< float >` *code) override
Sets local code for PCPS acquisition algorithm.
- void `set_active` (bool active) override
Starts acquisition algorithm, turning from standby mode to active mode.
- void `set_channel` (unsigned int channel) override
Set acquisition channel unique ID.
- void `set_channel_fsm` (`std::weak_ptr< ChannelFsm >` channel_fsm) override
Set channel fsm associated to this acquisition instance.
- int `general_work` (int noutput_items, `gr_vector_int` &ninput_items, `gr_vector_const_void_star` &input_items, `gr_vector_void_star` &output_items) override
Parallel Code Phase Search Acquisition signal processing.

Public Member Functions inherited from [acquisition_impl_interface](#)

- `acquisition_impl_interface` (const `std::string` &name, `gr::io_signature::sptr` input_signature, `gr::io_signature::sptr` output_signature)
- virtual void `set_channel` (uint32_t channel_id)=0
- virtual void `set_local_code` (`std::complex< float >` *, `std::complex< float >` *)

Friends

- `pcps_acquisition_fine_doppler_cc_sptr` `pcps_make_acquisition_fine_doppler_cc` (const [Acq_Conf](#) &conf_)

12.322.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition.

Definition at line 74 of file [pcps_acquisition_fine_doppler_cc.h](#).

12.322.2 Constructor & Destructor Documentation

12.322.2.1 ~pcps_acquisition_fine_doppler_cc()

`pcps_acquisition_fine_doppler_cc::~pcps_acquisition_fine_doppler_cc ()` [default]
Default destructor.

12.322.3 Member Function Documentation

12.322.3.1 general_work()

```
int pcps_acquisition_fine_doppler_cc::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

Parallel Code Phase Search Acquisition signal processing.

12.322.3.2 mag()

```
unsigned int pcps_acquisition_fine_doppler_cc::mag () const [inline], [override], [virtual]
```

Returns the maximum peak of grid search.

Implements [acquisition_impl_interface](#).

Definition at line 95 of file [pcps_acquisition_fine_doppler_cc.h](#).

12.322.3.3 set_active()

```
void pcps_acquisition_fine_doppler_cc::set_active (
    bool active) [inline], [override], [virtual]
```

Starts acquisition algorithm, turning from standby mode to active mode.

Parameters

<i>active</i>	- bool that activates/deactivates the block.
---------------	--

Implements [acquisition_impl_interface](#).

Definition at line 111 of file [pcps_acquisition_fine_doppler_cc.h](#).

12.322.3.4 set_channel()

```
void pcps_acquisition_fine_doppler_cc::set_channel (
    unsigned int channel) [inline], [override]
```

Set acquisition channel unique ID.

Parameters

<i>channel</i>	- receiver channel.
----------------	---------------------

Definition at line 125 of file [pcps_acquisition_fine_doppler_cc.h](#).

12.322.3.5 set_channel_fsm()

```
void pcps_acquisition_fine_doppler_cc::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [inline], [override], [virtual]
```

Set channel fsm associated to this acquisition instance.

Implements [acquisition_impl_interface](#).

Definition at line 134 of file [pcps_acquisition_fine_doppler_cc.h](#).

12.322.3.6 set_gnss_synchro()

```
void pcps_acquisition_fine_doppler_cc::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [inline], [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.

Parameters

<code>p_gnss_synchro</code>	Satellite information shared by the processing blocks.
-----------------------------	--

Implements [acquisition_impl_interface](#).

Definition at line 87 of file [pcps_acquisition_fine_doppler_cc.h](#).

12.322.3.7 set_local_code()

```
void pcps_acquisition_fine_doppler_cc::set_local_code (
    std::complex< float > * code) [override], [virtual]
```

Sets local code for PCPS acquisition algorithm.

Parameters

<code>code</code>	- Pointer to the PRN code.
-------------------	----------------------------

Reimplemented from [acquisition_impl_interface](#).

The documentation for this class was generated from the following file:

- [pcps_acquisition_fine_doppler_cc.h](#)

12.323 pcps_acquisition_fpga Class Reference

This class implements a Parallel Code Phase Search Acquisition that uses the FPGA.

```
#include <pcps_acquisition_fpga.h>
```

Public Member Functions

- [~pcps_acquisition_fpga](#) ()=default
Destructor.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro)
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- uint32_t [mag](#) () const
Returns the maximum peak of grid search.
- void [init](#) ()
Initializes acquisition algorithm.
- void [set_local_code](#) ()
Sets local code for PCPS acquisition algorithm.
- void [set_active](#) (bool active)
Starts acquisition algorithm, turning from standby mode to active mode.
- void [set_channel](#) (uint32_t channel)
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm)
Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int32_t doppler_center)
Set Doppler center frequency for the grid search. It will refresh the Doppler grid.

- void [reset_acquisition](#) ()
This function triggers a HW reset of the FPGA PL.
- void [stop_acquisition](#) ()
stop the acquisition and the other FPGA modules.

Friends

- pcps_acquisition_fpga_sptr **pcps_make_acquisition_fpga** ([Acq_Conf_Fpga](#) *conf, uint32_t acq_buff_num, std::vector< std::pair< uint32_t, uint32_t > > &downsampling_filter_specs, uint32_t &max_FFT_size)

12.323.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition that uses the FPGA.

Check [An Open Source Galileo E1 Software Receiver](#), Algorithm 1, for a pseudocode description of this implementation.

Definition at line 58 of file [pcps_acquisition_fpga.h](#).

12.323.2 Constructor & Destructor Documentation

12.323.2.1 ~pcps_acquisition_fpga()

```
pcps_acquisition_fpga::~pcps_acquisition_fpga () [default]
```

Destructor.

12.323.3 Member Function Documentation

12.323.3.1 init()

```
void pcps_acquisition_fpga::init ()
```

Initializes acquisition algorithm.

12.323.3.2 mag()

```
uint32_t pcps_acquisition_fpga::mag () const [inline]
```

Returns the maximum peak of grid search.
Definition at line 79 of file [pcps_acquisition_fpga.h](#).

12.323.3.3 reset_acquisition()

```
void pcps_acquisition_fpga::reset_acquisition ()
```

This function triggers a HW reset of the FPGA PL.

12.323.3.4 set_active()

```
void pcps_acquisition_fpga::set_active (
    bool active)
```

Starts acquisition algorithm, turning from standby mode to active mode.

Parameters

<i>active</i>	- bool that activates/deactivates the block.
---------------	--

12.323.3.5 set_channel()

```
void pcps_acquisition_fpga::set_channel (
    uint32_t channel) [inline]
```

Set acquisition channel unique ID.

Parameters

<i>channel</i>	- receiver channel.
----------------	---------------------

Definition at line 105 of file [pcps_acquisition_fpga.h](#).

12.323.3.6 set_channel_fsm()

```
void pcps_acquisition_fpga::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [inline]
```

Set channel fsm associated to this acquisition instance.

Definition at line 113 of file [pcps_acquisition_fpga.h](#).

12.323.3.7 set_doppler_center()

```
void pcps_acquisition_fpga::set_doppler_center (
    int32_t doppler_center)
```

Set Doppler center frequency for the grid search. It will refresh the Doppler grid.

Parameters

<i>doppler_center</i>	- Frequency center of the search grid [Hz].
-----------------------	---

12.323.3.8 set_gnss_synchro()

```
void pcps_acquisition_fpga::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [inline]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.

Parameters

<i>p_gnss_synchro</i>	Satellite information shared by the processing blocks.
-----------------------	--

Definition at line 71 of file [pcps_acquisition_fpga.h](#).

12.323.3.9 set_local_code()

```
void pcps_acquisition_fpga::set_local_code ()
```

Sets local code for PCPS acquisition algorithm.

12.323.3.10 stop_acquisition()

```
void pcps_acquisition_fpga::stop_acquisition ()
```

stop the acquisition and the other FPGA modules.

The documentation for this class was generated from the following file:

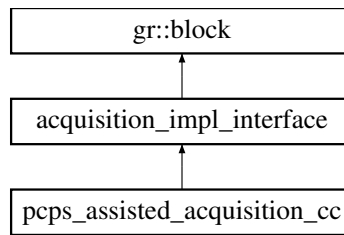
- [pcps_acquisition_fpga.h](#)

12.324 pcps_assisted_acquisition_cc Class Reference

This class implements a Parallel Code Phase Search Acquisition.

```
#include <pcps_assisted_acquisition_cc.h>
```

Inheritance diagram for [pcps_assisted_acquisition_cc](#):



Public Member Functions

- [~pcps_assisted_acquisition_cc](#) ()
Default destructor.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- uint32_t [mag](#) () const override
Returns the maximum peak of grid search.
- void [set_local_code](#) (std::complex< float > *code) override
Sets local code for PCPS acquisition algorithm.
- void [set_active](#) (bool active) override
Starts acquisition algorithm, turning from standby mode to active mode.
- void [set_channel](#) (uint32_t channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- int [general_work](#) (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
Parallel Code Phase Search Acquisition signal processing.

Public Member Functions inherited from [acquisition_impl_interface](#)

- [acquisition_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_local_code](#) (std::complex< float > *, std::complex< float > *)

Friends

- pcps_assisted_acquisition_cc_sptr [pcps_make_assisted_acquisition_cc](#) (const [Acq_Conf](#) &conf)

12.324.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition.

Check [An Open Source Galileo E1 Software Receiver](#), Algorithm 1, for a pseudocode description of this implementation.

Definition at line 68 of file [pcps_assisted_acquisition_cc.h](#).

12.324.2 Constructor & Destructor Documentation

12.324.2.1 ~pcps_assisted_acquisition_cc()

```
pcps_assisted_acquisition_cc::~pcps_assisted_acquisition_cc ()
```

Default destructor.

12.324.3 Member Function Documentation

12.324.3.1 `general_work()`

```
int pcps_assisted_acquisition_cc::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

Parallel Code Phase Search Acquisition signal processing.

12.324.3.2 `mag()`

```
uint32_t pcps_assisted_acquisition_cc::mag () const [inline], [override], [virtual]
```

Returns the maximum peak of grid search.

Implements [acquisition_impl_interface](#).

Definition at line 89 of file [pcps_assisted_acquisition_cc.h](#).

12.324.3.3 `set_active()`

```
void pcps_assisted_acquisition_cc::set_active (
    bool active) [inline], [override], [virtual]
```

Starts acquisition algorithm, turning from standby mode to active mode.

Parameters

<i>active</i>	- bool that activates/deactivates the block.
---------------	--

Implements [acquisition_impl_interface](#).

Definition at line 105 of file [pcps_assisted_acquisition_cc.h](#).

12.324.3.4 `set_channel()`

```
void pcps_assisted_acquisition_cc::set_channel (
    uint32_t channel) [inline], [override], [virtual]
```

Set acquisition channel unique ID.

Parameters

<i>channel</i>	- receiver channel.
----------------	---------------------

Implements [acquisition_impl_interface](#).

Definition at line 119 of file [pcps_assisted_acquisition_cc.h](#).

12.324.3.5 `set_channel_fsm()`

```
void pcps_assisted_acquisition_cc::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [inline], [override], [virtual]
```

Set channel fsm associated to this acquisition instance.

Implements [acquisition_impl_interface](#).

Definition at line 127 of file [pcps_assisted_acquisition_cc.h](#).

12.324.3.6 `set_gnss_synchro()`

```
void pcps_assisted_acquisition_cc::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [inline], [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.

Parameters

<code>p_gnss_synchro</code>	Satellite information shared by the processing blocks.
-----------------------------	--

Implements [acquisition_impl_interface](#).

Definition at line 81 of file [pcps_assisted_acquisition_cc.h](#).

12.324.3.7 set_local_code()

```
void pcps_assisted_acquisition_cc::set_local_code (
    std::complex< float > * code) [override], [virtual]
```

Sets local code for PCPS acquisition algorithm.

Parameters

<code>code</code>	- Pointer to the PRN code.
-------------------	----------------------------

Reimplemented from [acquisition_impl_interface](#).

The documentation for this class was generated from the following file:

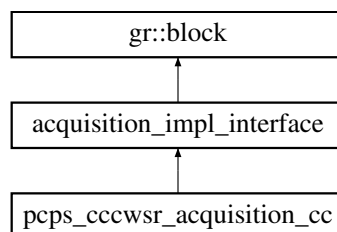
- [pcps_assisted_acquisition_cc.h](#)

12.325 pcps_cccwsr_acquisition_cc Class Reference

This class implements a Parallel Code Phase Search Acquisition with Coherent [Channel](#) Combining With Sign Recovery scheme.

```
#include <pcps_cccwsr_acquisition_cc.h>
```

Inheritance diagram for `pcps_cccwsr_acquisition_cc`:



Public Member Functions

- [~pcps_cccwsr_acquisition_cc](#) ()
Default destructor.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- uint32_t [mag](#) () const override
Returns the maximum peak of grid search.
- void [set_local_code](#) (std::complex< float > *code_data, std::complex< float > *code_pilot) override
Sets local code for CCCWSR acquisition algorithm.
- void [set_active](#) (bool active) override
Starts acquisition algorithm, turning from standby mode to active mode.
- void [set_channel](#) (uint32_t channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- int [general_work](#) (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
Coherent [Channel](#) Combining With Sign Recovery Acquisition signal processing.

Public Member Functions inherited from [acquisition_impl_interface](#)

- [acquisition_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_local_code](#) (std::complex< float > *)

Friends

- pcps_cccwsr_acquisition_cc_sptr [pcps_cccwsr_make_acquisition_cc](#) (const [Acq_Conf](#) &conf)

12.325.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition with Coherent [Channel](#) Combining With Sign Recovery scheme.

Definition at line 55 of file [pcps_cccwsr_acquisition_cc.h](#).

12.325.2 Constructor & Destructor Documentation

12.325.2.1 ~pcps_cccwsr_acquisition_cc()

```
pcps_cccwsr_acquisition_cc::~pcps_cccwsr_acquisition_cc ()
```

Default destructor.

12.325.3 Member Function Documentation

12.325.3.1 general_work()

```
int pcps_cccwsr_acquisition_cc::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

Coherent [Channel](#) Combining With Sign Recovery Acquisition signal processing.

12.325.3.2 mag()

```
uint32_t pcps_cccwsr_acquisition_cc::mag () const [inline], [override], [virtual]
```

Returns the maximum peak of grid search.

Implements [acquisition_impl_interface](#).

Definition at line 76 of file [pcps_cccwsr_acquisition_cc.h](#).

12.325.3.3 set_active()

```
void pcps_cccwsr_acquisition_cc::set_active (
    bool active) [inline], [override], [virtual]
```

Starts acquisition algorithm, turning from standby mode to active mode.

Parameters

<i>active</i>	- bool that activates/deactivates the block.
---------------	--

Implements [acquisition_impl_interface](#).

Definition at line 93 of file [pcps_cccwsr_acquisition_cc.h](#).

12.325.3.4 set_channel()

```
void pcps_cccwsr_acquisition_cc::set_channel (
    uint32_t channel) [inline], [override], [virtual]
```

Set acquisition channel unique ID.

Parameters

<i>channel</i>	- receiver channel.
----------------	---------------------

Implements [acquisition_impl_interface](#).

Definition at line 107 of file [pcps_cccwsr_acquisition_cc.h](#).

12.325.3.5 set_channel_fsm()

```
void pcps_cccwsr_acquisition_cc::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [inline], [override], [virtual]
```

Set channel fsm associated to this acquisition instance.

Implements [acquisition_impl_interface](#).

Definition at line 115 of file [pcps_cccwsr_acquisition_cc.h](#).

12.325.3.6 set_gnss_synchro()

```
void pcps_cccwsr_acquisition_cc::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [inline], [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.

Parameters

<i>p_gnss_synchro</i>	Satellite information shared by the processing blocks.
-----------------------	--

Implements [acquisition_impl_interface](#).

Definition at line 68 of file [pcps_cccwsr_acquisition_cc.h](#).

12.325.3.7 set_local_code()

```
void pcps_cccwsr_acquisition_cc::set_local_code (
    std::complex< float > * code_data,
    std::complex< float > * code_pilot) [override], [virtual]
```

Sets local code for CCCWSR acquisition algorithm.

Parameters

<i>data_code</i>	- Pointer to the data PRN code.
<i>pilot_code</i>	- Pointer to the pilot PRN code.

Reimplemented from [acquisition_impl_interface](#).

The documentation for this class was generated from the following file:

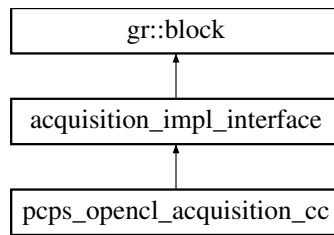
- [pcps_cccwsr_acquisition_cc.h](#)

12.326 pcps_openc1_acquisition_cc Class Reference

This class implements a Parallel Code Phase Search Acquisition.

```
#include <pcps_openc1_acquisition_cc.h>
```

Inheritance diagram for [pcps_openc1_acquisition_cc](#):



Public Member Functions

- `~pcps_openc1_acquisition_cc ()`
Default destructor.
- void `set_gnss_synchro (Gnss_Synchro *p_gnss_synchro)` override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- `uint32_t mag ()` const override
Returns the maximum peak of grid search.
- void `set_local_code (std::complex< float > *code)` override
Sets local code for PCPS acquisition algorithm.
- void `set_active (bool active)` override
Starts acquisition algorithm, turning from standby mode to active mode.
- void `set_channel (uint32_t channel)` override
Set acquisition channel unique ID.
- void `set_channel_fsm (std::weak_ptr< ChannelFsm > channel_fsm)` override
Set channel fsm associated to this acquisition instance.
- bool `openc1_ready ()` const
- void `acquisition_core_volk ()`
- void `acquisition_core_openc1 ()`
- int `general_work (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)` override
Parallel Code Phase Search Acquisition signal processing.

Public Member Functions inherited from [acquisition_impl_interface](#)

- `acquisition_impl_interface (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)`
- virtual void `set_local_code (std::complex< float > *, std::complex< float > *)`

Friends

- `pcps_openc1_acquisition_cc_sptr pcps_make_openc1_acquisition_cc (const Acq_Conf &conf, uint32_t max_dwells)`

12.326.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition.

Check [An Open Source Galileo E1 Software Receiver](#), Algorithm 1, for a pseudocode description of this implementation.

Definition at line 75 of file [pcps_openc1_acquisition_cc.h](#).

12.326.2 Constructor & Destructor Documentation

12.326.2.1 `~pcps_openc1_acquisition_cc()`

`pcps_openc1_acquisition_cc::~~pcps_openc1_acquisition_cc ()`
Default destructor.

12.326.3 Member Function Documentation

12.326.3.1 general_work()

```
int pcps_opencl_acquisition_cc::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

Parallel Code Phase Search Acquisition signal processing.

12.326.3.2 mag()

```
uint32_t pcps_opencl_acquisition_cc::mag () const [inline], [override], [virtual]
```

Returns the maximum peak of grid search.

Implements [acquisition_impl_interface](#).

Definition at line 96 of file [pcps_opencl_acquisition_cc.h](#).

12.326.3.3 opencl_ready()

```
bool pcps_opencl_acquisition_cc::opencl_ready () const [inline]
```

Definition at line 139 of file [pcps_opencl_acquisition_cc.h](#).

12.326.3.4 set_active()

```
void pcps_opencl_acquisition_cc::set_active (
    bool active) [inline], [override], [virtual]
```

Starts acquisition algorithm, turning from standby mode to active mode.

Parameters

<i>active</i>	- bool that activates/deactivates the block.
---------------	--

Implements [acquisition_impl_interface](#).

Definition at line 112 of file [pcps_opencl_acquisition_cc.h](#).

12.326.3.5 set_channel()

```
void pcps_opencl_acquisition_cc::set_channel (
    uint32_t channel) [inline], [override], [virtual]
```

Set acquisition channel unique ID.

Parameters

<i>channel</i>	- receiver channel.
----------------	---------------------

Implements [acquisition_impl_interface](#).

Definition at line 126 of file [pcps_opencl_acquisition_cc.h](#).

12.326.3.6 set_channel_fsm()

```
void pcps_opencl_acquisition_cc::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [inline], [override], [virtual]
```

Set channel fsm associated to this acquisition instance.

Implements [acquisition_impl_interface](#).

Definition at line 134 of file [pcps_opencl_acquisition_cc.h](#).

12.326.3.7 set_gnss_synchro()

```
void pcps_openc1_acquisition_cc::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [inline], [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.

Parameters

<code>p_gnss_synchro</code>	Satellite information shared by the processing blocks.
-----------------------------	--

Implements [acquisition_impl_interface](#).

Definition at line 88 of file [pcps_openc1_acquisition_cc.h](#).

12.326.3.8 set_local_code()

```
void pcps_openc1_acquisition_cc::set_local_code (
    std::complex< float > * code) [override], [virtual]
```

Sets local code for PCPS acquisition algorithm.

Parameters

<code>code</code>	- Pointer to the PRN code.
-------------------	----------------------------

Reimplemented from [acquisition_impl_interface](#).

The documentation for this class was generated from the following file:

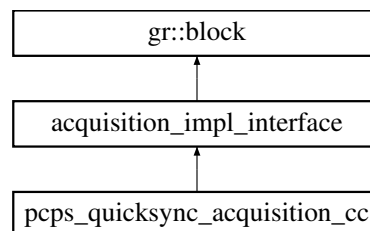
- [pcps_openc1_acquisition_cc.h](#)

12.327 pcps_quicksync_acquisition_cc Class Reference

This class implements a Parallel Code Phase Search Acquisition with the implementation of the Sparse QuickSync Algorithm.

```
#include <pcps_quicksync_acquisition_cc.h>
```

Inheritance diagram for `pcps_quicksync_acquisition_cc`:



Public Member Functions

- `~pcps_quicksync_acquisition_cc ()`
Default destructor.
- `void set_gnss_synchro (Gnss_Synchro *p_gnss_synchro) override`
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- `uint32_t mag () const override`
Returns the maximum peak of grid search.
- `void set_local_code (std::complex< float > *code) override`
Sets local code for PCPS acquisition algorithm.
- `void set_active (bool active) override`

- Starts acquisition algorithm, turning from standby mode to active mode.
- void [set_channel](#) (uint32_t channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- int [general_work](#) (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
Parallel Code Phase Search Acquisition signal processing.

Public Member Functions inherited from [acquisition_impl_interface](#)

- [acquisition_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_local_code](#) (std::complex< float > *, std::complex< float > *)

Friends

- pcps_quicksync_acquisition_cc_sptr [pcps_quicksync_make_acquisition_cc](#) (const [Acq_Conf](#) &conf, uint32_t folding_factor, uint32_t max_dwells)

12.327.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition with the implementation of the Sparse QuickSync Algorithm.

Check [Faster GPS via the Sparse Fourier Transform](#), for details of its implementation and functionality.

Definition at line 73 of file [pcps_quicksync_acquisition_cc.h](#).

12.327.2 Constructor & Destructor Documentation

12.327.2.1 ~pcps_quicksync_acquisition_cc()

```
pcps_quicksync_acquisition_cc::~pcps_quicksync_acquisition_cc ()
```

Default destructor.

12.327.3 Member Function Documentation

12.327.3.1 general_work()

```
int pcps_quicksync_acquisition_cc::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

Parallel Code Phase Search Acquisition signal processing.

12.327.3.2 mag()

```
uint32_t pcps_quicksync_acquisition_cc::mag () const [inline], [override], [virtual]
```

Returns the maximum peak of grid search.

Implements [acquisition_impl_interface](#).

Definition at line 94 of file [pcps_quicksync_acquisition_cc.h](#).

12.327.3.3 set_active()

```
void pcps_quicksync_acquisition_cc::set_active (
    bool active) [inline], [override], [virtual]
```

Starts acquisition algorithm, turning from standby mode to active mode.

Parameters

<i>active</i>	- bool that activates/deactivates the block.
---------------	--

Implements [acquisition_impl_interface](#).

Definition at line 110 of file [pcps_quicksync_acquisition_cc.h](#).

12.327.3.4 set_channel()

```
void pcps_quicksync_acquisition_cc::set_channel (
    uint32_t channel) [inline], [override], [virtual]
```

Set acquisition channel unique ID.

Parameters

<i>channel</i>	- receiver channel.
----------------	---------------------

Implements [acquisition_impl_interface](#).

Definition at line 124 of file [pcps_quicksync_acquisition_cc.h](#).

12.327.3.5 set_channel_fsm()

```
void pcps_quicksync_acquisition_cc::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [inline], [override], [virtual]
```

Set channel fsm associated to this acquisition instance.

Implements [acquisition_impl_interface](#).

Definition at line 132 of file [pcps_quicksync_acquisition_cc.h](#).

12.327.3.6 set_gnss_synchro()

```
void pcps_quicksync_acquisition_cc::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [inline], [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.

Parameters

<i>p_gnss_synchro</i>	Satellite information shared by the processing blocks.
-----------------------	--

Implements [acquisition_impl_interface](#).

Definition at line 86 of file [pcps_quicksync_acquisition_cc.h](#).

12.327.3.7 set_local_code()

```
void pcps_quicksync_acquisition_cc::set_local_code (
    std::complex< float > * code) [override], [virtual]
```

Sets local code for PCPS acquisition algorithm.

Parameters

<i>code</i>	- Pointer to the PRN code.
-------------	----------------------------

Reimplemented from [acquisition_impl_interface](#).

The documentation for this class was generated from the following file:

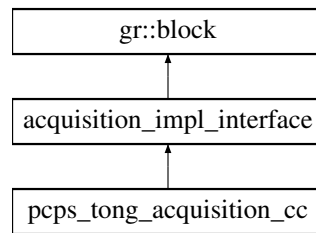
- [pcps_quicksync_acquisition_cc.h](#)

12.328 pcps_tong_acquisition_cc Class Reference

This class implements a Parallel Code Phase Search Acquisition with Tong algorithm.

```
#include <pcps_tong_acquisition_cc.h>
```

Inheritance diagram for pcps_tong_acquisition_cc:



Public Member Functions

- [~pcps_tong_acquisition_cc](#) ()
Default destructor.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- uint32_t [mag](#) () const override
Returns the maximum peak of grid search.
- void [set_local_code](#) (std::complex< float > *code) override
Sets local code for TONG acquisition algorithm.
- void [set_active](#) (bool active) override
Starts acquisition algorithm, turning from standby mode to active mode.
- void [set_channel](#) (uint32_t channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- int [general_work](#) (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
Parallel Code Phase Search Acquisition signal processing.

Public Member Functions inherited from [acquisition_impl_interface](#)

- [acquisition_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_local_code](#) (std::complex< float > *, std::complex< float > *)

Friends

- pcps_tong_acquisition_cc_sptr [pcps_tong_make_acquisition_cc](#) (const [Acq_Conf](#) &conf, uint32_t tong_init_val, uint32_t tong_max_val, uint32_t tong_max_dwells)

12.328.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition with Tong algorithm.

Definition at line 73 of file [pcps_tong_acquisition_cc.h](#).

12.328.2 Constructor & Destructor Documentation

12.328.2.1 ~pcps_tong_acquisition_cc()

```
pcps_tong_acquisition_cc::~pcps_tong_acquisition_cc ()
```

Default destructor.

12.328.3 Member Function Documentation

12.328.3.1 `general_work()`

```
int pcps_tong_acquisition_cc::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

Parallel Code Phase Search Acquisition signal processing.

12.328.3.2 `mag()`

```
uint32_t pcps_tong_acquisition_cc::mag () const [inline], [override], [virtual]
```

Returns the maximum peak of grid search.

Implements [acquisition_impl_interface](#).

Definition at line 94 of file [pcps_tong_acquisition_cc.h](#).

12.328.3.3 `set_active()`

```
void pcps_tong_acquisition_cc::set_active (
    bool active) [inline], [override], [virtual]
```

Starts acquisition algorithm, turning from standby mode to active mode.

Parameters

<i>active</i>	- bool that activates/deactivates the block.
---------------	--

Implements [acquisition_impl_interface](#).

Definition at line 110 of file [pcps_tong_acquisition_cc.h](#).

12.328.3.4 `set_channel()`

```
void pcps_tong_acquisition_cc::set_channel (
    uint32_t channel) [inline], [override], [virtual]
```

Set acquisition channel unique ID.

Parameters

<i>channel</i>	- receiver channel.
----------------	---------------------

Implements [acquisition_impl_interface](#).

Definition at line 124 of file [pcps_tong_acquisition_cc.h](#).

12.328.3.5 `set_channel_fsm()`

```
void pcps_tong_acquisition_cc::set_channel_fsm (
    std::weak_ptr< ChannelFsm > channel_fsm) [inline], [override], [virtual]
```

Set channel fsm associated to this acquisition instance.

Implements [acquisition_impl_interface](#).

Definition at line 132 of file [pcps_tong_acquisition_cc.h](#).

12.328.3.6 `set_gnss_synchro()`

```
void pcps_tong_acquisition_cc::set_gnss_synchro (
    Gnss_Synchro * p_gnss_synchro) [inline], [override], [virtual]
```

Set acquisition/tracking common [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.

Parameters

<code>p_gnss_synchro</code>	Satellite information shared by the processing blocks.
-----------------------------	--

Implements [acquisition_impl_interface](#).

Definition at line 86 of file [pcps_tong_acquisition_cc.h](#).

12.328.3.7 set_local_code()

```
void pcps_tong_acquisition_cc::set_local_code (
    std::complex< float > * code) [override], [virtual]
```

Sets local code for TONG acquisition algorithm.

Parameters

<code>code</code>	- Pointer to the PRN code.
-------------------	----------------------------

Reimplemented from [acquisition_impl_interface](#).

The documentation for this class was generated from the following file:

- [pcps_tong_acquisition_cc.h](#)

12.329 pcv_t Struct Reference**Public Attributes**

- int [sat](#)
- char [type](#) [[MAXANT](#)]
- char [code](#) [[MAXANT](#)]
- [gtime_t](#) [ts](#)
- [gtime_t](#) [te](#)
- double [off](#) [[NFREQ](#)][3]
- double [var](#) [[NFREQ](#)][19]

12.329.1 Detailed Description

Definition at line 400 of file [rtklib.h](#).

12.329.2 Member Data Documentation**12.329.2.1 code**

```
char pcv_t::code[MAXANT]
```

Definition at line 404 of file [rtklib.h](#).

12.329.2.2 off

```
double pcv_t::off[NFREQ][3]
```

Definition at line 406 of file [rtklib.h](#).

12.329.2.3 sat

```
int pcv_t::sat
```

Definition at line 402 of file [rtklib.h](#).

12.329.2.4 te

```
gtime\_t pcv_t::te
```

Definition at line 405 of file [rtklib.h](#).

12.329.2.5 ts

`ptime_t pcv_t::ts`

Definition at line 405 of file [rtklib.h](#).

12.329.2.6 type

`char pcv_t::type[MAXANT]`

Definition at line 403 of file [rtklib.h](#).

12.329.2.7 var

`double pcv_t::var[NFREQ][19]`

Definition at line 407 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.330 pcvs_t Struct Reference

Public Attributes

- `int n`
- `int nmax`
- `pcv_t * pcv`

12.330.1 Detailed Description

Definition at line 412 of file [rtklib.h](#).

12.330.2 Member Data Documentation

12.330.2.1 n

`int pcvs_t::n`

Definition at line 414 of file [rtklib.h](#).

12.330.2.2 nmax

`int pcvs_t::nmax`

Definition at line 414 of file [rtklib.h](#).

12.330.2.3 pcv

`pcv_t* pcvs_t::pcv`

Definition at line 415 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.331 pep_h Struct Reference

Public Attributes

- `ptime_t time`
- `int index`
- `double pos [MAXSAT][4]`
- `float std [MAXSAT][4]`
- `double vel [MAXSAT][4]`

- float [vst](#) [MAXSAT][4]
- float [cov](#) [MAXSAT][3]
- float [vco](#) [MAXSAT][3]

12.331.1 Detailed Description

Definition at line [479](#) of file [rtklib.h](#).

12.331.2 Member Data Documentation

12.331.2.1 cov

```
float pep_h_t::cov[MAXSAT][3]
```

Definition at line [487](#) of file [rtklib.h](#).

12.331.2.2 index

```
int pep_h_t::index
```

Definition at line [482](#) of file [rtklib.h](#).

12.331.2.3 pos

```
double pep_h_t::pos[MAXSAT][4]
```

Definition at line [483](#) of file [rtklib.h](#).

12.331.2.4 std

```
float pep_h_t::std[MAXSAT][4]
```

Definition at line [484](#) of file [rtklib.h](#).

12.331.2.5 time

```
gtime_t pep_h_t::time
```

Definition at line [481](#) of file [rtklib.h](#).

12.331.2.6 vco

```
float pep_h_t::vco[MAXSAT][3]
```

Definition at line [488](#) of file [rtklib.h](#).

12.331.2.7 vel

```
double pep_h_t::vel[MAXSAT][4]
```

Definition at line [485](#) of file [rtklib.h](#).

12.331.2.8 vst

```
float pep_h_t::vst[MAXSAT][4]
```

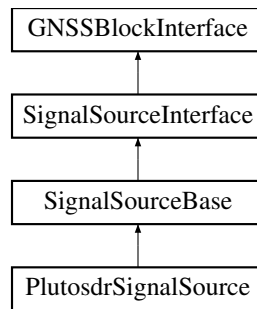
Definition at line [486](#) of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.332 PlutosdrSignalSource Class Reference

Inheritance diagram for PlutosdrSignalSource:



Public Member Functions

- **PlutosdrSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_error=false)
utility for decoding passed ".item_type" values

12.332.1 Detailed Description

Definition at line 49 of file [plutosdr_signal_source.h](#).

12.332.2 Member Function Documentation

12.332.2.1 [connect](#)()

```
void PlutosdrSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.332.2.2 disconnect()

```
void PlutosdrSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.332.2.3 get_left_block()

```
gr::basic_block_sptr PlutosdrSignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.332.2.4 get_right_block()

```
gr::basic_block_sptr PlutosdrSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.332.2.5 item_size()

```
size_t PlutosdrSignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 58 of file [plutosdr_signal_source.h](#).

The documentation for this class was generated from the following file:

- [plutosdr_signal_source.h](#)

12.333 pppcorr_t Struct Reference**Public Attributes**

- int [nsta](#)
- char [stas](#) [MAXSTA][8]
- double [rr](#) [MAXSTA][3]
- int [ns](#) [MAXSTA]
- int [nsmax](#) [MAXSTA]
- int [nt](#) [MAXSTA]
- int [ntmax](#) [MAXSTA]
- [stec_t](#) * [stec](#) [MAXSTA]
- [trop_t](#) * [trop](#) [MAXSTA]

12.333.1 Detailed Description

Definition at line 741 of file [rtklib.h](#).

12.333.2 Member Data Documentation**12.333.2.1 ns**

```
int pppcorr_t::ns[MAXSTA]
```

Definition at line 746 of file [rtklib.h](#).

12.333.2.2 nsmax

```
int pppcorr_t::nsmax[MAXSTA]
```

Definition at line 746 of file [rtklib.h](#).

12.333.2.3 nsta

```
int pppcorr_t::nsta
```

Definition at line 743 of file [rtklib.h](#).

12.333.2.4 nt

```
int pppcorr_t::nt[MAXSTA]
```

Definition at line 747 of file [rtklib.h](#).

12.333.2.5 ntmax

```
int pppcorr_t::ntmax[MAXSTA]
```

Definition at line 747 of file [rtklib.h](#).

12.333.2.6 rr

```
double pppcorr_t::rr[MAXSTA][3]
```

Definition at line 745 of file [rtklib.h](#).

12.333.2.7 stas

```
char pppcorr_t::stas[MAXSTA][8]
```

Definition at line 744 of file [rtklib.h](#).

12.333.2.8 stec

```
stec_t* pppcorr_t::stec[MAXSTA]
```

Definition at line 748 of file [rtklib.h](#).

12.333.2.9 trop

```
trop_t* pppcorr_t::trop[MAXSTA]
```

Definition at line 749 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.334 pps_tcp_rx Class Reference

Public Member Functions

- void **receive_pps** (const std::string &ip_address, int port)
- bool **send_cmd** (std::string cmd) const
- void **set_pps_samplestamp_queue** (std::shared_ptr< [Concurrent_Queue](#)< [PpsSamplestamp](#) > > queue)

Public Attributes

- volatile bool [is_connected](#) {false}

12.334.1 Detailed Description

Definition at line 27 of file [ppstcprx.h](#).

12.334.2 Member Data Documentation

12.334.2.1 is_connected

```
volatile bool pps_tcp_rx::is_connected {false}
```

Definition at line 34 of file [ppstcprx.h](#).

The documentation for this class was generated from the following file:

- [ppstcprx.h](#)

12.335 PpsSamplestamp Class Reference

Public Attributes

- uint64_t [samplestamp](#) = 0
- uint32_t [overflow_reg](#) = 0

12.335.1 Detailed Description

Definition at line 21 of file [pps_samplestamp.h](#).

12.335.2 Member Data Documentation

12.335.2.1 overflow_reg

uint32_t PpsSamplestamp::overflow_reg = 0

Definition at line 25 of file [pps_samplestamp.h](#).

12.335.2.2 samplestamp

uint64_t PpsSamplestamp::samplestamp = 0

Definition at line 24 of file [pps_samplestamp.h](#).

The documentation for this class was generated from the following file:

- [pps_samplestamp.h](#)

12.336 prcopt_t Struct Reference

Public Attributes

- int [mode](#)
- int [soltype](#)
- int [nf](#)
- int [navsys](#)
- double [elmin](#)
- [snrmask_t](#) [snrmask](#)
- int [sateph](#)
- int [modear](#)
- int [glomodear](#)
- int [bdsmodear](#)
- int [maxout](#)
- int [minlock](#)
- int [minfix](#)
- int [armaxiter](#)
- int [ionoopt](#)
- int [tropopt](#)
- int [dynamics](#)
- int [tidecorr](#)
- int [niter](#)
- int [codesmooth](#)
- int [intpref](#)
- int [sbascorr](#)
- int [sbassatsel](#)
- int [rovpos](#)
- int [refpos](#)
- double [eratio](#) [NFREQ]
- double [err](#) [5]

- double `std` [3]
- double `prn` [6]
- double `sclkstab`
- double `thresar` [8]
- double `elmaskar`
- double `elmaskhold`
- double `thresslip`
- double `maxtdiff`
- double `maxinno`
- double `maxgdop`
- double `baseline` [2]
- double `ru` [3]
- double `rb` [3]
- char `anttype` [2][MAXANT]
- double `antdel` [2][3]
- `pcv_t` `pcvr` [2]
- unsigned char `exsats` [MAXSAT]
- int `maxaveep`
- int `initrst`
- int `outsingle`
- char `rnxopt` [2][256]
- int `posopt` [6]
- int `syncsol`
- double `odisp` [2][6 * 11]
- `exterr_t` `exterr`
- int `freqopt`
- char `pppopt` [256]
- bool `bancroft_init`

12.336.1 Detailed Description

Definition at line 943 of file `rtklib.h`.

12.336.2 Member Data Documentation

12.336.2.1 antdel

```
double prcopt_t::antdel[2][3]
```

Definition at line 991 of file `rtklib.h`.

12.336.2.2 anttype

```
char prcopt_t::anttype[2][MAXANT]
```

Definition at line 990 of file `rtklib.h`.

12.336.2.3 armaxiter

```
int prcopt_t::armaxiter
```

Definition at line 958 of file `rtklib.h`.

12.336.2.4 bancroft_init

```
bool prcopt_t::bancroft_init
```

Definition at line 1004 of file `rtklib.h`.

12.336.2.5 baseline

double prcopt_t::baseline[2]

Definition at line 987 of file [rtklib.h](#).

12.336.2.6 bdsmodear

int prcopt_t::bdsmodear

Definition at line 954 of file [rtklib.h](#).

12.336.2.7 codesmooth

int prcopt_t::codesmooth

Definition at line 964 of file [rtklib.h](#).

12.336.2.8 dynamics

int prcopt_t::dynamics

Definition at line 961 of file [rtklib.h](#).

12.336.2.9 elmaskar

double prcopt_t::elmaskar

Definition at line 981 of file [rtklib.h](#).

12.336.2.10 elmaskhold

double prcopt_t::elmaskhold

Definition at line 982 of file [rtklib.h](#).

12.336.2.11 elmin

double prcopt_t::elmin

Definition at line 949 of file [rtklib.h](#).

12.336.2.12 eratio

double prcopt_t::eratio[NFREQ]

Definition at line 972 of file [rtklib.h](#).

12.336.2.13 err

double prcopt_t::err[5]

Definition at line 973 of file [rtklib.h](#).

12.336.2.14 exsats

unsigned char prcopt_t::exsats[MAXSAT]

Definition at line 993 of file [rtklib.h](#).

12.336.2.15 exterr

[exterr_t](#) prcopt_t::exterr

Definition at line 1001 of file [rtklib.h](#).

12.336.2.16 freqopt

int prcopt_t::freqopt

Definition at line 1002 of file [rtklib.h](#).

12.336.2.17 glomodear

```
int prcopt_t::glomodear
```

Definition at line 953 of file [rtklib.h](#).

12.336.2.18 initrst

```
int prcopt_t::initrst
```

Definition at line 995 of file [rtklib.h](#).

12.336.2.19 intpref

```
int prcopt_t::intpref
```

Definition at line 965 of file [rtklib.h](#).

12.336.2.20 ionoopt

```
int prcopt_t::ionoopt
```

Definition at line 959 of file [rtklib.h](#).

12.336.2.21 maxaveep

```
int prcopt_t::maxaveep
```

Definition at line 994 of file [rtklib.h](#).

12.336.2.22 maxgdop

```
double prcopt_t::maxgdop
```

Definition at line 986 of file [rtklib.h](#).

12.336.2.23 maxinno

```
double prcopt_t::maxinno
```

Definition at line 985 of file [rtklib.h](#).

12.336.2.24 maxout

```
int prcopt_t::maxout
```

Definition at line 955 of file [rtklib.h](#).

12.336.2.25 maxtdiff

```
double prcopt_t::maxtdiff
```

Definition at line 984 of file [rtklib.h](#).

12.336.2.26 minfix

```
int prcopt_t::minfix
```

Definition at line 957 of file [rtklib.h](#).

12.336.2.27 minlock

```
int prcopt_t::minlock
```

Definition at line 956 of file [rtklib.h](#).

12.336.2.28 mode

```
int prcopt_t::mode
```

Definition at line 945 of file [rtklib.h](#).

12.336.2.29 modear

```
int prcopt_t::modear
```

Definition at line 952 of file [rtklib.h](#).

12.336.2.30 navsys

```
int prcopt_t::navsys
```

Definition at line 948 of file [rtklib.h](#).

12.336.2.31 nf

```
int prcopt_t::nf
```

Definition at line 947 of file [rtklib.h](#).

12.336.2.32 niter

```
int prcopt_t::niter
```

Definition at line 963 of file [rtklib.h](#).

12.336.2.33 odisp

```
double prcopt_t::odisp[2][6 * 11]
```

Definition at line 1000 of file [rtklib.h](#).

12.336.2.34 outsingle

```
int prcopt_t::outsingle
```

Definition at line 996 of file [rtklib.h](#).

12.336.2.35 pcvr

```
pcv_t prcopt_t::pcvr[2]
```

Definition at line 992 of file [rtklib.h](#).

12.336.2.36 posopt

```
int prcopt_t::posopt[6]
```

Definition at line 998 of file [rtklib.h](#).

12.336.2.37 pppopt

```
char prcopt_t::pppopt[256]
```

Definition at line 1003 of file [rtklib.h](#).

12.336.2.38 prn

```
double prcopt_t::prn[6]
```

Definition at line 978 of file [rtklib.h](#).

12.336.2.39 rb

```
double prcopt_t::rb[3]
```

Definition at line 989 of file [rtklib.h](#).

12.336.2.40 refpos

```
int prcopt_t::refpos
```

Definition at line 969 of file [rtklib.h](#).

12.336.2.41 rnxopt

char prcopt_t::rnxopt[2][256]
Definition at line 997 of file [rtklib.h](#).

12.336.2.42 rovpos

int prcopt_t::rovpos
Definition at line 968 of file [rtklib.h](#).

12.336.2.43 ru

double prcopt_t::ru[3]
Definition at line 988 of file [rtklib.h](#).

12.336.2.44 sateph

int prcopt_t::sateph
Definition at line 951 of file [rtklib.h](#).

12.336.2.45 sbascorr

int prcopt_t::sbascorr
Definition at line 966 of file [rtklib.h](#).

12.336.2.46 sbassatsel

int prcopt_t::sbassatsel
Definition at line 967 of file [rtklib.h](#).

12.336.2.47 sclkstab

double prcopt_t::sclkstab
Definition at line 979 of file [rtklib.h](#).

12.336.2.48 snrmask

[snrmask_t](#) prcopt_t::snrmask
Definition at line 950 of file [rtklib.h](#).

12.336.2.49 soltype

int prcopt_t::soltype
Definition at line 946 of file [rtklib.h](#).

12.336.2.50 std

double prcopt_t::std[3]
Definition at line 977 of file [rtklib.h](#).

12.336.2.51 syncsol

int prcopt_t::syncsol
Definition at line 999 of file [rtklib.h](#).

12.336.2.52 thresar

double prcopt_t::thresar[8]
Definition at line 980 of file [rtklib.h](#).

12.336.2.53 thresslip

double prcopt_t::thresslip
 Definition at line 983 of file [rtklib.h](#).

12.336.2.54 tidecorr

int prcopt_t::tidecorr
 Definition at line 962 of file [rtklib.h](#).

12.336.2.55 tropopt

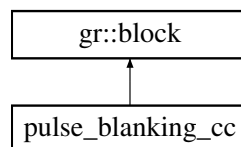
int prcopt_t::tropopt
 Definition at line 960 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.337 pulse_blanking_cc Class Reference

Inheritance diagram for pulse_blanking_cc:

**Public Member Functions**

- int **general_work** (int noutput_items __attribute__((unused)), gr_vector_int &ninput_items __attribute__((unused)), gr_vector_const_void_star &ninput_items, gr_vector_void_star &output_items)

Friends

- pulse_blanking_cc_sptr **make_pulse_blanking_cc** (float pfa, int32_t length, int32_t n_segments_est, int32_t n_segments_reset)

12.337.1 Detailed Description

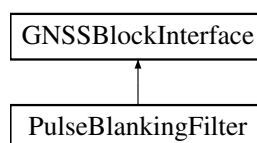
Definition at line 44 of file [pulse_blanking_cc.h](#).

The documentation for this class was generated from the following file:

- [pulse_blanking_cc.h](#)

12.338 PulseBlankingFilter Class Reference

Inheritance diagram for PulseBlankingFilter:



Public Member Functions

- **PulseBlankingFilter** (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override
Returns "Pulse_Blanking_Filter".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.338.1 Detailed Description

Definition at line 39 of file [pulse_blanking_filter.h](#).

12.338.2 Member Function Documentation

12.338.2.1 connect()

```
void PulseBlankingFilter::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.338.2.2 disconnect()

```
void PulseBlankingFilter::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.338.2.3 get_left_block()

```
gr::basic_block_sptr PulseBlankingFilter::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.338.2.4 get_right_block()

```
gr::basic_block_sptr PulseBlankingFilter::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.338.2.5 implementation()

```
std::string PulseBlankingFilter::implementation () [inline], [override], [virtual]
```

Returns "Pulse_Blanking_Filter".

Implements [GNSSBlockInterface](#).

Definition at line 54 of file [pulse_blanking_filter.h](#).

12.338.2.6 item_size()

```
size_t PulseBlankingFilter::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 59 of file [pulse_blanking_filter.h](#).

12.338.2.7 role()

std::string PulseBlankingFilter::role () [inline], [override], [virtual]

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [pulse_blanking_filter.h](#).

The documentation for this class was generated from the following file:

- [pulse_blanking_filter.h](#)

12.339 Pvt_Conf Class Reference

Public Attributes

- std::map< int, int > [rtcm_msg_rate_ms](#)
- std::string [rinex_name](#) = std::string("-")
- std::string [dump_filename](#)
- std::string [nmea_dump_filename](#)
- std::string [nmea_dump_devname](#)
- std::string [rtcm_dump_devname](#)
- std::string [an_dump_devname](#)
- std::string [output_path](#) = std::string(".")
- std::string [rinex_output_path](#) = std::string(".")
- std::string [gpx_output_path](#) = std::string(".")
- std::string [geojson_output_path](#) = std::string(".")
- std::string [nmea_output_file_path](#) = std::string(".")
- std::string [kml_output_path](#) = std::string(".")
- std::string [xml_output_path](#) = std::string(".")
- std::string [rtcm_output_file_path](#) = std::string(".")
- std::string [has_output_file_path](#) = std::string(".")
- std::string [udp_addresses](#)
- std::string [udp_ports](#)
- std::string [udp_eph_addresses](#)
- std::string [log_source_timetag_file](#)
- uint32_t [signal_enabled_flags](#) = 0
- uint32_t [observable_interval_ms](#) = 20
- int32_t [output_rate_ms](#) = 0
- int32_t [display_rate_ms](#) = 0
- int32_t [kml_rate_ms](#) = 20
- int32_t [gpx_rate_ms](#) = 20
- int32_t [geojson_rate_ms](#) = 20
- int32_t [nmea_rate_ms](#) = 20
- int32_t [rinex_version](#) = 0
- int32_t [rinexobs_rate_ms](#) = 0
- int32_t [an_rate_ms](#) = 20
- int32_t [max_obs_block_rx_clock_offset_ms](#) = 40
- int [udp_eph_port](#) = 0
- int [rtk_trace_level](#) = 0
- uint16_t [rtcm_tcp_port](#) = 0
- uint16_t [rtcm_station_id](#) = 0
- bool [flag_nmea_tty_port](#) = false
- bool [flag_rtcm_server](#) = false
- bool [flag_rtcm_tty_port](#) = false
- bool [output_enabled](#) = true
- bool [rinex_output_enabled](#) = true
- bool [gpx_output_enabled](#) = true
- bool [geojson_output_enabled](#) = true

- bool [nmea_output_file_enabled](#) = true
- bool [an_output_enabled](#) = false
- bool [kml_output_enabled](#) = true
- bool [xml_output_enabled](#) = true
- bool [rtcm_output_file_enabled](#) = true
- bool [monitor_enabled](#) = false
- bool [monitor_ephemeris_enabled](#) = false
- bool [protobuf_enabled](#) = true
- bool [enable_rx_clock_correction](#) = true
- bool [show_local_time_zone](#) = false
- bool [pre_2009_file](#) = false
- bool [dump](#) = false
- bool [dump_mat](#) = true
- bool [log_source_timetag](#) = false
- bool [use_e6_for_pvt](#) = true
- bool [use_has_corrections](#) = true
- bool [use_unhealthy_sats](#) = false
- bool [osnma_strict](#) = false
- bool [enable_pvt_kf](#) = false
- double [measures_ecef_pos_sd_m](#) = 1.0
- double [measures_ecef_vel_sd_ms](#) = 0.1
- double [system_ecef_pos_sd_m](#) = 0.01
- double [system_ecef_vel_sd_ms](#) = 0.001
- bool [kf_use_imu_vel](#) = false

12.339.1 Detailed Description

Definition at line 30 of file [pvt_conf.h](#).

12.339.2 Member Data Documentation

12.339.2.1 an_dump_devname

`std::string Pvt_Conf::an_dump_devname`

Definition at line 40 of file [pvt_conf.h](#).

12.339.2.2 an_output_enabled

`bool Pvt_Conf::an_output_enabled = false`

Definition at line 82 of file [pvt_conf.h](#).

12.339.2.3 an_rate_ms

`int32_t Pvt_Conf::an_rate_ms = 20`

Definition at line 66 of file [pvt_conf.h](#).

12.339.2.4 display_rate_ms

`int32_t Pvt_Conf::display_rate_ms = 0`

Definition at line 59 of file [pvt_conf.h](#).

12.339.2.5 dump

`bool Pvt_Conf::dump = false`

Definition at line 92 of file [pvt_conf.h](#).

12.339.2.6 dump_filename

std::string Pvt_Conf::dump_filename
Definition at line 36 of file [pvt_conf.h](#).

12.339.2.7 dump_mat

bool Pvt_Conf::dump_mat = true
Definition at line 93 of file [pvt_conf.h](#).

12.339.2.8 enable_pvt_kf

bool Pvt_Conf::enable_pvt_kf = false
Definition at line 101 of file [pvt_conf.h](#).

12.339.2.9 enable_rx_clock_correction

bool Pvt_Conf::enable_rx_clock_correction = true
Definition at line 89 of file [pvt_conf.h](#).

12.339.2.10 flag_nmea_tty_port

bool Pvt_Conf::flag_nmea_tty_port = false
Definition at line 74 of file [pvt_conf.h](#).

12.339.2.11 flag_rtcn_server

bool Pvt_Conf::flag_rtcn_server = false
Definition at line 75 of file [pvt_conf.h](#).

12.339.2.12 flag_rtcn_tty_port

bool Pvt_Conf::flag_rtcn_tty_port = false
Definition at line 76 of file [pvt_conf.h](#).

12.339.2.13 geojson_output_enabled

bool Pvt_Conf::geojson_output_enabled = true
Definition at line 80 of file [pvt_conf.h](#).

12.339.2.14 geojson_output_path

std::string Pvt_Conf::geojson_output_path = std::string(".")
Definition at line 44 of file [pvt_conf.h](#).

12.339.2.15 geojson_rate_ms

int32_t Pvt_Conf::geojson_rate_ms = 20
Definition at line 62 of file [pvt_conf.h](#).

12.339.2.16 gpx_output_enabled

bool Pvt_Conf::gpx_output_enabled = true
Definition at line 79 of file [pvt_conf.h](#).

12.339.2.17 gpx_output_path

std::string Pvt_Conf::gpx_output_path = std::string(".")
Definition at line 43 of file [pvt_conf.h](#).

12.339.2.18 gpx_rate_ms

int32_t Pvt_Conf::gpx_rate_ms = 20
Definition at line 61 of file [pvt_conf.h](#).

12.339.2.19 has_output_file_path

std::string Pvt_Conf::has_output_file_path = std::string(".")
Definition at line 49 of file [pvt_conf.h](#).

12.339.2.20 kf_use_imu_vel

bool Pvt_Conf::kf_use_imu_vel = false
Definition at line 108 of file [pvt_conf.h](#).

12.339.2.21 kml_output_enabled

bool Pvt_Conf::kml_output_enabled = true
Definition at line 83 of file [pvt_conf.h](#).

12.339.2.22 kml_output_path

std::string Pvt_Conf::kml_output_path = std::string(".")
Definition at line 46 of file [pvt_conf.h](#).

12.339.2.23 kml_rate_ms

int32_t Pvt_Conf::kml_rate_ms = 20
Definition at line 60 of file [pvt_conf.h](#).

12.339.2.24 log_source_timetag

bool Pvt_Conf::log_source_timetag = false
Definition at line 94 of file [pvt_conf.h](#).

12.339.2.25 log_source_timetag_file

std::string Pvt_Conf::log_source_timetag_file
Definition at line 53 of file [pvt_conf.h](#).

12.339.2.26 max_obs_block_rx_clock_offset_ms

int32_t Pvt_Conf::max_obs_block_rx_clock_offset_ms = 40
Definition at line 67 of file [pvt_conf.h](#).

12.339.2.27 measures_ecef_pos_sd_m

double Pvt_Conf::measures_ecef_pos_sd_m = 1.0
Definition at line 102 of file [pvt_conf.h](#).

12.339.2.28 measures_ecef_vel_sd_ms

double Pvt_Conf::measures_ecef_vel_sd_ms = 0.1
Definition at line 103 of file [pvt_conf.h](#).

12.339.2.29 monitor_enabled

bool Pvt_Conf::monitor_enabled = false
Definition at line 86 of file [pvt_conf.h](#).

12.339.2.30 monitor_ephemeris_enabled

```
bool Pvt_Conf::monitor_ephemeris_enabled = false
```

Definition at line 87 of file [pvt_conf.h](#).

12.339.2.31 nmea_dump_devname

```
std::string Pvt_Conf::nmea_dump_devname
```

Definition at line 38 of file [pvt_conf.h](#).

12.339.2.32 nmea_dump_filename

```
std::string Pvt_Conf::nmea_dump_filename
```

Definition at line 37 of file [pvt_conf.h](#).

12.339.2.33 nmea_output_file_enabled

```
bool Pvt_Conf::nmea_output_file_enabled = true
```

Definition at line 81 of file [pvt_conf.h](#).

12.339.2.34 nmea_output_file_path

```
std::string Pvt_Conf::nmea_output_file_path = std::string(".")
```

Definition at line 45 of file [pvt_conf.h](#).

12.339.2.35 nmea_rate_ms

```
int32_t Pvt_Conf::nmea_rate_ms = 20
```

Definition at line 63 of file [pvt_conf.h](#).

12.339.2.36 observable_interval_ms

```
uint32_t Pvt_Conf::observable_interval_ms = 20
```

Definition at line 56 of file [pvt_conf.h](#).

12.339.2.37 osnma_strict

```
bool Pvt_Conf::osnma_strict = false
```

Definition at line 98 of file [pvt_conf.h](#).

12.339.2.38 output_enabled

```
bool Pvt_Conf::output_enabled = true
```

Definition at line 77 of file [pvt_conf.h](#).

12.339.2.39 output_path

```
std::string Pvt_Conf::output_path = std::string(".")
```

Definition at line 41 of file [pvt_conf.h](#).

12.339.2.40 output_rate_ms

```
int32_t Pvt_Conf::output_rate_ms = 0
```

Definition at line 58 of file [pvt_conf.h](#).

12.339.2.41 pre_2009_file

```
bool Pvt_Conf::pre_2009_file = false
```

Definition at line 91 of file [pvt_conf.h](#).

12.339.2.42 `protobuf_enabled`

`bool Pvt_Conf::protobuf_enabled = true`
Definition at line 88 of file [pvt_conf.h](#).

12.339.2.43 `rinex_name`

`std::string Pvt_Conf::rinex_name = std::string("-")`
Definition at line 35 of file [pvt_conf.h](#).

12.339.2.44 `rinex_output_enabled`

`bool Pvt_Conf::rinex_output_enabled = true`
Definition at line 78 of file [pvt_conf.h](#).

12.339.2.45 `rinex_output_path`

`std::string Pvt_Conf::rinex_output_path = std::string(".")`
Definition at line 42 of file [pvt_conf.h](#).

12.339.2.46 `rinex_version`

`int32_t Pvt_Conf::rinex_version = 0`
Definition at line 64 of file [pvt_conf.h](#).

12.339.2.47 `rinexobs_rate_ms`

`int32_t Pvt_Conf::rinexobs_rate_ms = 0`
Definition at line 65 of file [pvt_conf.h](#).

12.339.2.48 `rtcm_dump_devname`

`std::string Pvt_Conf::rtcm_dump_devname`
Definition at line 39 of file [pvt_conf.h](#).

12.339.2.49 `rtcm_msg_rate_ms`

`std::map<int, int> Pvt_Conf::rtcm_msg_rate_ms`
Definition at line 33 of file [pvt_conf.h](#).

12.339.2.50 `rtcm_output_file_enabled`

`bool Pvt_Conf::rtcm_output_file_enabled = true`
Definition at line 85 of file [pvt_conf.h](#).

12.339.2.51 `rtcm_output_file_path`

`std::string Pvt_Conf::rtcm_output_file_path = std::string(".")`
Definition at line 48 of file [pvt_conf.h](#).

12.339.2.52 `rtcm_station_id`

`uint16_t Pvt_Conf::rtcm_station_id = 0`
Definition at line 72 of file [pvt_conf.h](#).

12.339.2.53 `rtcm_tcp_port`

`uint16_t Pvt_Conf::rtcm_tcp_port = 0`
Definition at line 71 of file [pvt_conf.h](#).

12.339.2.54 rtk_trace_level

```
int Pvt_Conf::rtk_trace_level = 0
```

Definition at line 69 of file [pvt_conf.h](#).

12.339.2.55 show_local_time_zone

```
bool Pvt_Conf::show_local_time_zone = false
```

Definition at line 90 of file [pvt_conf.h](#).

12.339.2.56 signal_enabled_flags

```
uint32_t Pvt_Conf::signal_enabled_flags = 0
```

Definition at line 55 of file [pvt_conf.h](#).

12.339.2.57 system_ecef_pos_sd_m

```
double Pvt_Conf::system_ecef_pos_sd_m = 0.01
```

Definition at line 104 of file [pvt_conf.h](#).

12.339.2.58 system_ecef_vel_sd_ms

```
double Pvt_Conf::system_ecef_vel_sd_ms = 0.001
```

Definition at line 105 of file [pvt_conf.h](#).

12.339.2.59 udp_addresses

```
std::string Pvt_Conf::udp_addresses
```

Definition at line 50 of file [pvt_conf.h](#).

12.339.2.60 udp_eph_addresses

```
std::string Pvt_Conf::udp_eph_addresses
```

Definition at line 52 of file [pvt_conf.h](#).

12.339.2.61 udp_eph_port

```
int Pvt_Conf::udp_eph_port = 0
```

Definition at line 68 of file [pvt_conf.h](#).

12.339.2.62 udp_ports

```
std::string Pvt_Conf::udp_ports
```

Definition at line 51 of file [pvt_conf.h](#).

12.339.2.63 use_e6_for_pvt

```
bool Pvt_Conf::use_e6_for_pvt = true
```

Definition at line 95 of file [pvt_conf.h](#).

12.339.2.64 use_has_corrections

```
bool Pvt_Conf::use_has_corrections = true
```

Definition at line 96 of file [pvt_conf.h](#).

12.339.2.65 use_unhealthy_sats

```
bool Pvt_Conf::use_unhealthy_sats = false
```

Definition at line 97 of file [pvt_conf.h](#).

12.339.2.66 xml_output_enabled

bool Pvt_Conf::xml_output_enabled = true
 Definition at line 84 of file [pvt_conf.h](#).

12.339.2.67 xml_output_path

std::string Pvt_Conf::xml_output_path = std::string(".")
 Definition at line 47 of file [pvt_conf.h](#).
 The documentation for this class was generated from the following file:

- [pvt_conf.h](#)

12.340 Pvt_Kf Class Reference

Kalman Filter for Position and Velocity.
 #include <pvt_kf.h>

Public Member Functions

- void **init_Kf** (const arma::vec &p, const arma::vec &v, double update_interval_s, double measures_ecef_pos_sd_m, double measures_ecef_vel_sd_ms, double system_ecef_pos_sd_m, double system_ecef_vel_sd_ms)
- bool **is_initialized** () const
- void **run_Kf** (const arma::vec &p, const arma::vec &v)
- void **get_pv_Kf** (arma::vec &p, arma::vec &v) const
- void **reset_Kf** ()

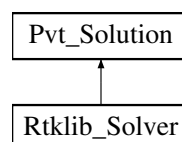
12.340.1 Detailed Description

Kalman Filter for Position and Velocity.
 Definition at line 33 of file [pvt_kf.h](#).
 The documentation for this class was generated from the following file:

- [pvt_kf.h](#)

12.341 Pvt_Solution Class Reference

Base class for a PVT solution.
 #include <pvt_solution.h>
 Inheritance diagram for Pvt_Solution:



Public Member Functions

- virtual double **get_hdop** () const =0
- virtual double **get_vdop** () const =0
- virtual double **get_pdop** () const =0
- virtual double **get_gdop** () const =0
- std::array< double, 3 > **get_rx_pos** () const
- std::array< double, 3 > **get_rx_vel** () const
- boost::posix_time::ptime **get_position.UTC_time** () const

- double [get_latitude](#) () const
Get RX position Latitude WGS84 [deg].
- double [get_longitude](#) () const
Get RX position Longitude WGS84 [deg].
- double [get_height](#) () const
Get RX position height WGS84 [m].
- double [get_time_offset_s](#) () const
Get RX time offset [s].
- double [get_clock_drift_ppm](#) () const
Get the Rx clock drift [ppm].
- double [get_speed_over_ground](#) () const
Get RX speed over ground [m/s].
- double [get_course_over_ground](#) () const
Get RX course over ground [deg].
- int [get_num_valid_observations](#) () const
Get the number of valid pseudorange observations (valid satellites)
- bool [is_pre_2009](#) () const
- bool [is_valid_position](#) () const
- void [set_rx_pos](#) (const std::array< double, 3 > &pos)
Set position: X, Y, Z in Cartesian ECEF coordinates [m].
- void [set_rx_vel](#) (const std::array< double, 3 > &vel)
Set velocity: East [m/s], North [m/s], Up [m/s].
- void [set_position.UTC_time](#) (const boost::posix_time::ptime &pt)
- void [set_time_offset_s](#) (double offset)
Set RX time offset [s].
- void [set_clock_drift_ppm](#) (double clock_drift_ppm)
Set the Rx clock drift [ppm].
- void [set_speed_over_ground](#) (double speed_m_s)
Set RX speed over ground [m/s].
- void [set_course_over_ground](#) (double cog_deg)
Set RX course over ground [deg].
- void [set_valid_position](#) (bool is_valid)
- void [set_num_valid_observations](#) (int num)
Set the number of valid pseudorange observations (valid satellites)
- void [set_pre_2009_file](#) (bool pre_2009_file)
Flag for the week rollover computation in post processing mode for signals older than 2009.

12.341.1 Detailed Description

Base class for a PVT solution.

Definition at line 34 of file [pvt_solution.h](#).

12.341.2 Member Function Documentation

12.341.2.1 [get_clock_drift_ppm](#)()

```
double Pvt_Solution::get_clock_drift_ppm () const
```

Get the Rx clock drift [ppm].

12.341.2.2 [get_course_over_ground](#)()

```
double Pvt_Solution::get_course_over_ground () const
```

Get RX course over ground [deg].

12.341.2.3 `get_height()`

```
double Pvt_Solution::get_height () const
```

Get RX position height WGS84 [m].

12.341.2.4 `get_latitude()`

```
double Pvt_Solution::get_latitude () const
```

Get RX position Latitude WGS84 [deg].

12.341.2.5 `get_longitude()`

```
double Pvt_Solution::get_longitude () const
```

Get RX position Longitude WGS84 [deg].

12.341.2.6 `get_num_valid_observations()`

```
int Pvt_Solution::get_num_valid_observations () const
```

Get the number of valid pseudorange observations (valid satellites)

12.341.2.7 `get_speed_over_ground()`

```
double Pvt_Solution::get_speed_over_ground () const
```

Get RX speed over ground [m/s].

12.341.2.8 `get_time_offset_s()`

```
double Pvt_Solution::get_time_offset_s () const
```

Get RX time offset [s].

12.341.2.9 `set_clock_drift_ppm()`

```
void Pvt_Solution::set_clock_drift_ppm (
    double clock_drift_ppm)
```

Set the Rx clock drift [ppm].

12.341.2.10 `set_course_over_ground()`

```
void Pvt_Solution::set_course_over_ground (
    double cog_deg)
```

Set RX course over ground [deg].

12.341.2.11 `set_num_valid_observations()`

```
void Pvt_Solution::set_num_valid_observations (
    int num)
```

Set the number of valid pseudorange observations (valid satellites)

12.341.2.12 `set_pre_2009_file()`

```
void Pvt_Solution::set_pre_2009_file (
    bool pre_2009_file)
```

Flag for the week rollover computation in post processing mode for signals older than 2009.

12.341.2.13 `set_rx_pos()`

```
void Pvt_Solution::set_rx_pos (
    const std::array< double, 3 > & pos)
```

Set position: X, Y, Z in Cartesian ECEF coordinates [m].

12.341.2.14 set_rx_vel()

```
void Pvt_Solution::set_rx_vel (
    const std::array< double, 3 > & vel)
```

Set velocity: East [m/s], North [m/s], Up [m/s].

12.341.2.15 set_speed_over_ground()

```
void Pvt_Solution::set_speed_over_ground (
    double speed_m_s)
```

Set RX speed over ground [m/s].

12.341.2.16 set_time_offset_s()

```
void Pvt_Solution::set_time_offset_s (
    double offset)
```

Set RX time offset [s].

The documentation for this class was generated from the following file:

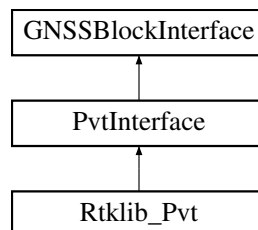
- [pvt_solution.h](#)

12.342 PvtInterface Class Reference

This class represents an interface to a PVT block.

```
#include <pvt_interface.h>
```

Inheritance diagram for PvtInterface:

**Public Member Functions**

- virtual void **reset** ()=0
- virtual void **clear_ephemeris** ()=0
- virtual std::map< int, [Gps_Ephemeris](#) > **get_gps_ephemeris** () const =0
- virtual std::map< int, [Galileo_Ephemeris](#) > **get_galileo_ephemeris** () const =0
- virtual std::map< int, [Gps_Almanac](#) > **get_gps_almanac** () const =0
- virtual std::map< int, [Galileo_Almanac](#) > **get_galileo_almanac** () const =0
- virtual bool **get_latest_PVT** (double *longitude_deg, double *latitude_deg, double *height_m, double *ground_speed_kmh, double *course_over_ground_deg, time_t *UTC_time)=0

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual std::string [role](#) ()=0
- virtual std::string [implementation](#) ()=0
- virtual size_t [item_size](#) ()=0
- virtual void [connect](#) (gr::top_block_sptr top_block)=0
- virtual void [disconnect](#) (gr::top_block_sptr top_block)=0
- virtual gr::basic_block_sptr [get_left_block](#) ()=0
- virtual gr::basic_block_sptr [get_right_block](#) ()=0
- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)

- virtual void [start](#) ()
Start the flow of samples if needed.

12.342.1 Detailed Description

This class represents an interface to a PVT block.

Abstract class for PVT interfaces, derived from [GNSSBlockInterface](#). Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

Definition at line 48 of file [pvt_interface.h](#).

The documentation for this class was generated from the following file:

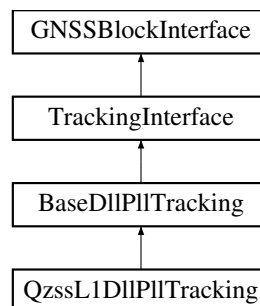
- [pvt_interface.h](#)

12.343 QzssL1DIIPITracking Class Reference

This class implements a code DLL + carrier PLL tracking loop block adapter for QZSS L1 signals.

```
#include <qzss_l1_dll_pll_tracking.h>
```

Inheritance diagram for QzssL1DIIPITracking:



Public Member Functions

- [QzssL1DIIPITracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &[role](#), unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "QZSS_L1_CA_DLL_PLL_Tracking".

Public Member Functions inherited from [BaseDIIPITracking](#)

- [BaseDIIPITracking](#) (const [ConfigurationInterface](#) *configuration, std::string [role](#), unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDIIPITracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override final

- *Get left block from the Tracking block adapter.*
gr::basic_block_sptr [get_right_block](#) () override final
- *Get right block from the Tracking block adapter.*
void [set_channel](#) (unsigned int channel) override final
- *Set tracking channel unique ID.*
void [set_gnss_synchro](#) (Gnss_Synchro *p_gnss_synchro) override final
- *Set acquisition Gnss_Synchro object pointer to exchange synchronization data between acquisition and tracking blocks.*
void [start_tracking](#) () override final
- *Start the Tracking block.*
void [stop_tracking](#) () override final
- *Stop the Tracking block.*

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
 - virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
 - virtual void [start](#) ()
- Start the flow of samples if needed.*

Additional Inherited Members

Protected Member Functions inherited from BaseDlIPllTracking

- [DlI_Pll_Conf](#) & [config_params](#) ()
- const [DlI_Pll_Conf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t item_size)

Protected Attributes inherited from BaseDlIPllTracking

- dll_pll_veml_tracking_sptr [tracking_sptr](#)

12.343.1 Detailed Description

This class implements a code DLL + carrier PLL tracking loop block adapter for QZSS L1 signals.

Definition at line 40 of file [qzss_l1_dll_pll_tracking.h](#).

12.343.2 Constructor & Destructor Documentation

12.343.2.1 QzssL1DlIPllTracking()

```
QzssL1DlIPllTracking::QzssL1DlIPllTracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDlIPllTracking::role\(\)](#).

12.343.3 Member Function Documentation

12.343.3.1 implementation()

```
std::string QzssL1DlIPllTracking::implementation () [inline], [override], [virtual]
```

Returns "QZSS_L1_CA_DLL_PLL_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 50 of file [qzss_l1_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

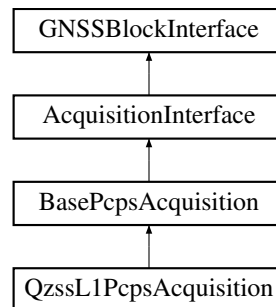
- [qzss_l1_dll_pll_tracking.h](#)

12.344 QzssL1PcpsAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for QZSS L1 signals.

```
#include <qzss_l1_pcps_acquisition.h>
```

Inheritance diagram for QzssL1PcpsAcquisition:



Public Member Functions

- **QzssL1PcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "QZSS_L1_PCPS_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)
- std::string [role](#) () override
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override
Set acquisition/tracking common [Gnss_Synchro](#) object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- void [set_channel](#) (unsigned int channel) override
Set acquisition channel unique ID.
- void [set_channel_fsm](#) (std::weak_ptr< [ChannelFsm](#) > channel_fsm) override
Set channel fsm associated to this acquisition instance.
- void [set_doppler_center](#) (int doppler_center) override
Set Doppler center for the grid search.
- signed int [mag](#) () override
Returns the maximum peak of grid search.
- void [reset](#) () override
Restart acquisition algorithm.
- void [stop_acquisition](#) () override
Stop running acquisition.
- void [set_resampler_latency](#) (uint32_t latency_samples) override
Sets the resampler latency to account it in the acquisition code delay estimation.
- void [set_local_code](#) () override
Sets local code.

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.344.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for QZSS L1 signals.
Definition at line 34 of file [qzss_l1_pcps_acquisition.h](#).

12.344.2 Member Function Documentation

12.344.2.1 implementation()

```
std::string QzssL1PcpsAcquisition::implementation () [inline], [override], [virtual]
```

Returns "QZSS_L1_PCPS_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [qzss_l1_pcps_acquisition.h](#).

The documentation for this class was generated from the following file:

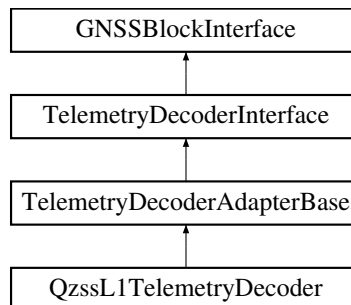
- [qzss_l1_pcps_acquisition.h](#)

12.345 QzssL1TelemetryDecoder Class Reference

This class implements a NAV data decoder for QZSS L1.

```
#include <qzss_l1_telemetry_decoder.h>
```

Inheritance diagram for QzssL1TelemetryDecoder:



Public Member Functions

- **QzssL1TelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override

Returns "QZSS_L1_Telemetry_Decoder".

Public Member Functions inherited from TelemetryDecoderAdapterBase

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override

- `std::string role ()` override
- `void set_channel (int channel)` override
- `void reset ()` override
- `size_t item_size ()` override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual `gr::basic_block_sptr get_left_block (int RF_channel)`
- virtual `gr::basic_block_sptr get_right_block (int RF_channel)`
- virtual `void start ()`

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- `void InitializeDecoder (telemetry_impl_interface_sptr decoder)`
- `const Gnss_Satellite & satellite ()` const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- `Tlm_Conf tlm_parameters_`

12.345.1 Detailed Description

This class implements a NAV data decoder for QZSS L1.
Definition at line 37 of file [qzss_l1_telemetry_decoder.h](#).

12.345.2 Member Function Documentation

12.345.2.1 implementation()

```
std::string QzssL1TelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "QZSS_L1_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 47 of file [qzss_l1_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

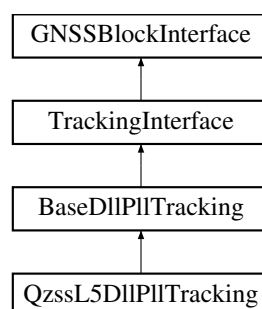
- [qzss_l1_telemetry_decoder.h](#)

12.346 QzssL5DIIPITracking Class Reference

This class implements a code DLL + carrier PLL tracking loop block adapter for QZSS L5 signals.

```
#include <qzss_l5_dll_pll_tracking.h>
```

Inheritance diagram for QzssL5DIIPITracking:



Public Member Functions

- [QzssL5DIIPITracking](#) (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
Constructor.
- std::string [implementation](#) () override
Returns "QZSS_L5_DLL_PLL_Tracking".

Public Member Functions inherited from [BaseDIIPITracking](#)

- [BaseDIIPITracking](#) (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_streams, unsigned int out_streams)
Base constructor of a Tracking block adapter.
- [~BaseDIIPITracking](#) () override=default
Default destructor of the Tracking block adapter.
- std::string [role](#) () override final
Get role from the Tracking block adapter.
- size_t [item_size](#) () override final
Get item_size from the Tracking block adapter.
- void [connect](#) (gr::top_block_sptr top_block) override final
Connect the Tracking block adapter.
- void [disconnect](#) (gr::top_block_sptr top_block) override final
Disconnect the Tracking block adapter.
- gr::basic_block_sptr [get_left_block](#) () override final
Get left block from the Tracking block adapter.
- gr::basic_block_sptr [get_right_block](#) () override final
Get right block from the Tracking block adapter.
- void [set_channel](#) (unsigned int channel) override final
Set tracking channel unique ID.
- void [set_gnss_synchro](#) ([Gnss_Synchro](#) *p_gnss_synchro) override final
Set acquisition [Gnss_Synchro](#) object pointer to exchange synchronization data between acquisition and tracking blocks.
- void [start_tracking](#) () override final
Start the Tracking block.
- void [stop_tracking](#) () override final
Stop the Tracking block.

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [BaseDIIPITracking](#)

- [DIIPITrackingConf](#) & [config_params](#) ()
- const [DIIPITrackingConf](#) & [config_params](#) () const
- void [set_item_size](#) (size_t item_size)

Protected Attributes inherited from [BaseDIIPITracking](#)

- dll_pll_veml_tracking_sptr [tracking_sptr](#)

12.346.1 Detailed Description

This class implements a code DLL + carrier PLL tracking loop block adapter for QZSS L5 signals.
Definition at line 40 of file [qzss_l5_dll_pll_tracking.h](#).

12.346.2 Constructor & Destructor Documentation

12.346.2.1 QzssL5DllPllTracking()

```
QzssL5DllPllTracking::QzssL5DllPllTracking (
    const ConfigurationInterface * configuration,
    const std::string & role,
    unsigned int in_streams,
    unsigned int out_streams)
```

Constructor.

References [BaseDllPllTracking::role\(\)](#).

12.346.3 Member Function Documentation

12.346.3.1 implementation()

```
std::string QzssL5DllPllTracking::implementation () [inline], [override], [virtual]
```

Returns "QZSS_L5_DLL_PLL_Tracking".

Implements [GNSSBlockInterface](#).

Definition at line 50 of file [qzss_l5_dll_pll_tracking.h](#).

The documentation for this class was generated from the following file:

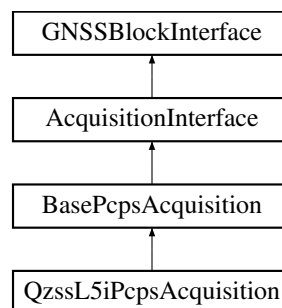
- [qzss_l5_dll_pll_tracking.h](#)

12.347 QzssL5iPcpsAcquisition Class Reference

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for QZSS L5I signals.

```
#include <qzss_l5i_pcps_acquisition.h>
```

Inheritance diagram for QzssL5iPcpsAcquisition:



Public Member Functions

- **QzssL5iPcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "QZSS_L5I_PCPS_Acquisition".

Public Member Functions inherited from [BasePcpsAcquisition](#)

- **BasePcpsAcquisition** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, double chip_rate, double opt_freq, double code_length_chips, uint32_t ms_per_code)

- `std::string role ()` override
- `size_t item_size ()` override
- `void connect (gr::top_block_sptr top_block)` override
- `void disconnect (gr::top_block_sptr top_block)` override
- `gr::basic_block_sptr get_left_block ()` override
- `gr::basic_block_sptr get_right_block ()` override
- `void set_gnss_synchro (Gnss_Synchro *p_gnss_synchro)` override
Set acquisition/tracking common Gnss_Synchro object pointer to efficiently exchange synchronization data between acquisition and tracking blocks.
- `void set_channel (unsigned int channel)` override
Set acquisition channel unique ID.
- `void set_channel_fsm (std::weak_ptr< ChannelFsm > channel_fsm)` override
Set channel fsm associated to this acquisition instance.
- `void set_doppler_center (int doppler_center)` override
Set Doppler center for the grid search.
- `signed int mag ()` override
Returns the maximum peak of grid search.
- `void reset ()` override
Restart acquisition algorithm.
- `void stop_acquisition ()` override
Stop running acquisition.
- `void set_resampler_latency (uint32_t latency_samples)` override
Sets the resampler latency to account it in the acquisition code delay estimation.
- `void set_local_code ()` override
Sets local code.

Public Member Functions inherited from GNSSBlockInterface

- virtual `gr::basic_block_sptr get_left_block (int RF_channel)`
- virtual `gr::basic_block_sptr get_right_block (int RF_channel)`
- virtual `void start ()`
Start the flow of samples if needed.

12.347.1 Detailed Description

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for QZSS L5I signals.
 Definition at line 34 of file [qzss_l5i_pcps_acquisition.h](#).

12.347.2 Member Function Documentation

12.347.2.1 implementation()

```
std::string QzssL5iPcpsAcquisition::implementation () [inline], [override], [virtual]
```

Returns "QZSS_L5I_PCPS_Acquisition".

Implements [GNSSBlockInterface](#).

Definition at line 48 of file [qzss_l5i_pcps_acquisition.h](#).

The documentation for this class was generated from the following file:

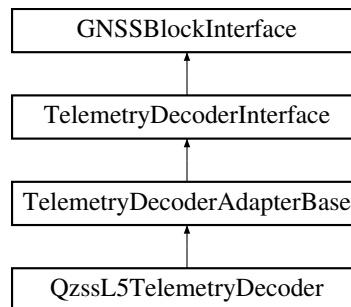
- [qzss_l5i_pcps_acquisition.h](#)

12.348 QzssL5TelemetryDecoder Class Reference

This class implements a NAV data decoder for QZSS L5.

```
#include <qzss_l5_telemetry_decoder.h>
```

Inheritance diagram for QzssL5TelemetryDecoder:



Public Member Functions

- **QzssL5TelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "QZSS_L5_Telemetry_Decoder".

Public Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- void **InitializeDecoder** (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & **satellite** () const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- [Tlm_Conf](#) tlm_parameters_

12.348.1 Detailed Description

This class implements a NAV data decoder for QZSS L5.
Definition at line 37 of file [qzss_l5_telemetry_decoder.h](#).

12.348.2 Member Function Documentation

12.348.2.1 implementation()

```
std::string QzssL5TelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "QZSS_L5_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 47 of file [qzss_l5_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

- [qzss_l5_telemetry_decoder.h](#)

12.349 raw_t Struct Reference

Public Attributes

- [gtime_t](#) time
- [gtime_t](#) tobs
- [obs_t](#) obs
- [obs_t](#) obuf
- [nav_t](#) nav
- [sta_t](#) sta
- int ephsat
- [sbsmsg_t](#) sbsmsg
- char msgtype [256]
- unsigned char subfrm [MAXSAT][380]
- [lexmsg_t](#) lexmsg
- double lockt [MAXSAT][NFREQ+NEXOBS]
- double icpp [MAXSAT]
- double off [MAXSAT]
- double icpc
- double prCA [MAXSAT]
- double dpCA [MAXSAT]
- unsigned char halfc [MAXSAT][NFREQ+NEXOBS]
- char freqn [MAXOBS]
- int nbyte
- int len
- int iod
- int tod
- int tbase
- int flag
- int outtype
- unsigned char buff [MAXRAWLEN]
- char opt [256]
- double receive_time
- unsigned int plen
- unsigned int pbyte
- unsigned int page
- unsigned int reply
- int week
- unsigned char pbuff [255+4+2]

12.349.1 Detailed Description

Definition at line 1202 of file [rtklib.h](#).

12.349.2 Member Data Documentation

12.349.2.1 buff

```
unsigned char raw_t::buff[MAXRAWLEN]
```

Definition at line 1227 of file [rtklib.h](#).

12.349.2.2 dpCA

```
double raw_t::dpCA[MAXSAT]
```

Definition at line 1217 of file [rtklib.h](#).

12.349.2.3 ephsat

```
int raw_t::ephsat
```

Definition at line 1210 of file [rtklib.h](#).

12.349.2.4 flag

```
int raw_t::flag
```

Definition at line 1225 of file [rtklib.h](#).

12.349.2.5 freqn

```
char raw_t::freqn[MAXOBS]
```

Definition at line 1219 of file [rtklib.h](#).

12.349.2.6 halfc

```
unsigned char raw_t::halfc[MAXSAT][NFREQ+NEXOBS]
```

Definition at line 1218 of file [rtklib.h](#).

12.349.2.7 icpc

```
double raw_t::icpc
```

Definition at line 1216 of file [rtklib.h](#).

12.349.2.8 icpp

```
double raw_t::icpp[MAXSAT]
```

Definition at line 1216 of file [rtklib.h](#).

12.349.2.9 iod

```
int raw_t::iod
```

Definition at line 1222 of file [rtklib.h](#).

12.349.2.10 len

```
int raw_t::len
```

Definition at line 1221 of file [rtklib.h](#).

12.349.2.11 lexmsg

```
lexmsg_t raw_t::lexmsg
```

Definition at line 1214 of file [rtklib.h](#).

12.349.2.12 lockt

```
double raw_t::lockt[MAXSAT] [NFREQ+NEXOBS]
```

Definition at line 1215 of file [rtklib.h](#).

12.349.2.13 msgtype

```
char raw_t::msgtype[256]
```

Definition at line 1212 of file [rtklib.h](#).

12.349.2.14 nav

```
nav_t raw_t::nav
```

Definition at line 1208 of file [rtklib.h](#).

12.349.2.15 nbyte

```
int raw_t::nbyte
```

Definition at line 1220 of file [rtklib.h](#).

12.349.2.16 obs

```
obs_t raw_t::obs
```

Definition at line 1206 of file [rtklib.h](#).

12.349.2.17 obuf

```
obs_t raw_t::obuf
```

Definition at line 1207 of file [rtklib.h](#).

12.349.2.18 off

```
double raw_t::off[MAXSAT]
```

Definition at line 1216 of file [rtklib.h](#).

12.349.2.19 opt

```
char raw_t::opt[256]
```

Definition at line 1228 of file [rtklib.h](#).

12.349.2.20 outtype

```
int raw_t::outtype
```

Definition at line 1226 of file [rtklib.h](#).

12.349.2.21 page

```
unsigned int raw_t::page
```

Definition at line 1232 of file [rtklib.h](#).

12.349.2.22 pbuff

```
unsigned char raw_t::pbuff[255+4+2]
```

Definition at line 1235 of file [rtklib.h](#).

12.349.2.23 pbyte

```
unsigned int raw_t::pbyte
```

Definition at line 1231 of file [rtklib.h](#).

12.349.2.24 plen

unsigned int raw_t::plen

Definition at line 1230 of file [rtklib.h](#).

12.349.2.25 prCA

double raw_t::prCA[MAXSAT]

Definition at line 1217 of file [rtklib.h](#).

12.349.2.26 receive_time

double raw_t::receive_time

Definition at line 1229 of file [rtklib.h](#).

12.349.2.27 reply

unsigned int raw_t::reply

Definition at line 1233 of file [rtklib.h](#).

12.349.2.28 sbsmsg

[sbsmsg_t](#) raw_t::sbsmsg

Definition at line 1211 of file [rtklib.h](#).

12.349.2.29 sta

[sta_t](#) raw_t::sta

Definition at line 1209 of file [rtklib.h](#).

12.349.2.30 subfrm

unsigned char raw_t::subfrm[MAXSAT][380]

Definition at line 1213 of file [rtklib.h](#).

12.349.2.31 tbase

int raw_t::tbase

Definition at line 1224 of file [rtklib.h](#).

12.349.2.32 time

[gtime_t](#) raw_t::time

Definition at line 1204 of file [rtklib.h](#).

12.349.2.33 tobs

[gtime_t](#) raw_t::tobs

Definition at line 1205 of file [rtklib.h](#).

12.349.2.34 tod

int raw_t::tod

Definition at line 1223 of file [rtklib.h](#).

12.349.2.35 week

int raw_t::week

Definition at line 1234 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

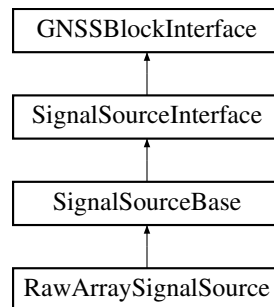
- [rtklib.h](#)

12.350 RawArraySignalSource Class Reference

This class reads samples from an antenna array RF front-end signal sampler.

```
#include <raw_array_signal_source.h>
```

Inheritance diagram for RawArraySignalSource:



Public Member Functions

- **RawArraySignalSource** (const [ConfigurationInterface](#) *configuration, std::string role, unsigned int in_↔ stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↔ error=false)
utility for decoding passed ".item_type" values

12.350.1 Detailed Description

This class reads samples from an antenna array RF front-end signal sampler.

Definition at line 42 of file [raw_array_signal_source.h](#).

12.350.2 Member Function Documentation

12.350.2.1 connect()

```
void RawArraySignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.350.2.2 disconnect()

```
void RawArraySignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.350.2.3 get_left_block()

```
gr::basic_block_sptr RawArraySignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.350.2.4 get_right_block()

```
gr::basic_block_sptr RawArraySignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.350.2.5 item_size()

```
size_t RawArraySignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 51 of file [raw_array_signal_source.h](#).

The documentation for this class was generated from the following file:

- [raw_array_signal_source.h](#)

12.351 ReedSolomon Class Reference

Class implementing a Reed-Solomon encoder and decoder RS(255,K,d) where k=255-nroots is the information vector length and d=nroots+1 is the minimum Hamming distance, with symbols of 8 bits. It allows shortened RS codes.

```
#include <reed_solomon.h>
```

Public Member Functions

- [ReedSolomon](#) (const std::string &gnss_signal=std::string())
Default constructor. Constructs a Reed Solomon object. The encode_with_generator_poly and encode_with_generator_matrix methods are available for testing purposes.
- [ReedSolomon](#) (int nroots, int minpoly, int prim, int fcr, int pad=0, int shortening=0, const std::vector< uint8_t > &genpoly_coeff=std::vector< uint8_t > {}, const std::vector< std::vector< uint8_t > > &gen_matrix=std::vector< std::vector< uint8_t > > {})
Custom constructor for RS(255, 255-nroots, nroots+1). Parameters:
- int [decode](#) (std::vector< uint8_t > &data_to_decode, const std::vector< int > &erasure_positions=std::vector< int > {}) const
Decode an encoded block.
- std::vector< uint8_t > [encode_with_generator_matrix](#) (const std::vector< uint8_t > &data_to_encode) const
Encode data with the generator matrix (for testing purposes)
- std::vector< uint8_t > [encode_with_generator_poly](#) (const std::vector< uint8_t > &data_to_encode) const
Encode data with the generator polynomial (for testing purposes)

12.351.1 Detailed Description

Class implementing a Reed-Solomon encoder and decoder RS(255,K,d) where $k=255-nroots$ is the information vector length and $d=nroots+1$ is the minimum Hamming distance, with symbols of 8 bits. It allows shortened RS codes.

Definition at line 40 of file [reed_solomon.h](#).

12.351.2 Constructor & Destructor Documentation

12.351.2.1 ReedSolomon() [1/2]

```
ReedSolomon::ReedSolomon (
```

```
    const std::string & gnss_signal = std::string()) [explicit]
```

Default constructor. Constructs a Reed Solomon object. The `encode_with_generator_poly` and `encode_with_generator_matrix` methods are available for testing purposes.

`gnss_signal`: empty or "E6B" sets the Galileo E6B RS parameters. "E1B" sets the Galileo E1B (INAV) RS parameters.

12.351.2.2 ReedSolomon() [2/2]

```
ReedSolomon::ReedSolomon (
```

```
    int nroots,
```

```
    int minpoly,
```

```
    int prim,
```

```
    int fcr,
```

```
    int pad = 0,
```

```
    int shortening = 0,
```

```
    const std::vector< uint8_t > & genpoly_coeff = std::vector< uint8_t > {},
```

```
    const std::vector< std::vector< uint8_t > > & gen_matrix = std::vector< std::vector< uint8_t > > {})
```

Custom constructor for RS(255, 255-nroots, nroots+1). Parameters:

`nroots` - the number of roots in the RS code generator polynomial, which is the same as the number of parity symbols in a block.

`minpoly` - primitive polynomial.

`prim` - the primitive root of the generator polynomial.

`fcr` - first consecutive root of the Reed-Solomon generator polynomial.

`pad` - the number of pad symbols in a block. If not defined, it defaults to 0.

`shortening` - value of the shortening parameter. Defaults to 0. If different to 0, it defines a shortened RS encoder/decoder.

`genpoly_coeff` - a vector of (nroots+1) elements containing the generator polynomial coefficients. Only used for encoding. Defaults to empty. If defined, the `encode_with_generator_poly` method can be used.

`gen_matrix` - a (255-shortening)x(255-nroots-shortening) matrix containing the elements of the generator matrix. Only used for encoding. Defaults to empty. If defined, the `encode_with_generator_matrix` method can be used.

12.351.3 Member Function Documentation

12.351.3.1 decode()

```
int ReedSolomon::decode (
```

```
    std::vector< uint8_t > & data_to_decode,
```

```
    const std::vector< int > & erasure_positions = std::vector< int > {} ) const
```

Decode an encoded block.

The decoded symbols are at the first 255-nroots-shortening elements of the `data_to_decode` vector.

The second parameter is optional, and contains a vector of erasure positions to be passed to the decoding algorithm. Defaults to empty.

Returns the number of corrected errors, or -1 if decoding failed.

12.351.3.2 encode_with_generator_matrix()

```
std::vector< uint8_t > ReedSolomon::encode_with_generator_matrix (
```

```
const std::vector< uint8_t > & data_to_encode) const
```

Encode data with the generator matrix (for testing purposes)

Returns the encoded vector. It is set to all zeros if the generator matrix is not defined.

12.351.3.3 encode_with_generator_poly()

```
std::vector< uint8_t > ReedSolomon::encode_with_generator_poly (
```

```
const std::vector< uint8_t > & data_to_encode) const
```

Encode data with the generator polynomial (for testing purposes)

Returns the encoded vector. It is set to all zeros if the generator polynomial is not defined.

The documentation for this class was generated from the following file:

- [reed_solomon.h](#)

12.352 Rinex_Printer Class Reference

Class that handles the generation of Receiver INdependent EXchange format (RINEX) files.

```
#include <rinex_printer.h>
```

Public Member Functions

- [Rinex_Printer](#) (uint32_t signal_enabled_flags, int version=3, const std::string &base_path=".", const std::string &base_name="-", bool pre_2009_file=false)
Constructor. Creates GNSS Navigation and Observables RINEX files.
- [~Rinex_Printer](#) ()
Destructor. Removes created files if empty.
- void [print_rinex_annotation](#) (const [Rtklib_Solver](#) *pvt_solver, const std::map< int, [Gnss_Synchro](#) > &gnss_observables_map, double rx_time, bool flag_write_RINEX_obs_output)
Print RINEX annotation. If it is the first annotation, it also prints the RINEX headers for navigation and observation files. If it is not the first annotation, it only annotates the observation, and updates the navigation header if UTC data was not available when writing it for the first time.
- void [log_rinex_nav_gps_nav](#) (const std::map< int32_t, [Gps_Ephemeris](#) > &new_eph)
Print RINEX annotation for GPS NAV message.
- void [log_rinex_nav_gps_cnav](#) (const std::map< int32_t, [Gps_CNAV_Ephemeris](#) > &new_cnav_eph)
Print RINEX annotation for GPS CNAV message.
- void [log_rinex_nav_gal_nav](#) (const std::map< int32_t, [Galileo_Ephemeris](#) > &new_gal_eph)
Print RINEX annotation for Galileo NAV message.
- void [log_rinex_nav_glo_gnav](#) (const std::map< int32_t, [Glonass_Gnav_Ephemeris](#) > &new_glo_eph)
Print RINEX annotation for Glonass GNAV message.
- void [log_rinex_nav_bds_dnav](#) (const std::map< int32_t, [Beidou_Dnav_Ephemeris](#) > &new_bds_eph)
Print RINEX annotation for BeiDou DNAV message.
- bool [is_rinex_header_written](#) () const
Returns true is the RINEX file headers are already written.
- std::vector< std::string > [get_navfilename](#) () const
Returns name of RINEX navigation file(s)
- std::string [get_obsfilename](#) () const
Returns name of RINEX observation file.

12.352.1 Detailed Description

Class that handles the generation of Receiver INdependent EXchange format (RINEX) files.

Definition at line 82 of file [rinex_printer.h](#).

12.352.2 Constructor & Destructor Documentation

12.352.2.1 Rinex_Printer()

```
Rinex_Printer::Rinex_Printer (
    uint32_t signal_enabled_flags,
    int version = 3,
    const std::string & base_path = ".",
    const std::string & base_name = "-",
    bool pre_2009_file = false) [explicit]
```

Constructor. Creates GNSS Navigation and Observables RINEX files.

12.352.2.2 ~Rinex_Printer()

```
Rinex_Printer::~~Rinex_Printer ()
```

Destructor. Removes created files if empty.

12.352.3 Member Function Documentation

12.352.3.1 get_navfilename()

```
std::vector< std::string > Rinex_Printer::get_navfilename () const [inline]
```

Returns name of RINEX navigation file(s)

Definition at line 148 of file [rinex_printer.h](#).

12.352.3.2 get_obsfilename()

```
std::string Rinex_Printer::get_obsfilename () const [inline]
```

Returns name of RINEX observation file.

Definition at line 156 of file [rinex_printer.h](#).

12.352.3.3 is_rinex_header_written()

```
bool Rinex_Printer::is_rinex_header_written () const [inline]
```

Returns true is the RINEX file headers are already written.

Definition at line 140 of file [rinex_printer.h](#).

12.352.3.4 log_rinex_nav_bds_dnav()

```
void Rinex_Printer::log_rinex_nav_bds_dnav (
    const std::map< int32_t, Beidou_Dnav_Ephemeris > & new_bds_eph)
```

Print RINEX annotation for BeiDou DNAV message.

12.352.3.5 log_rinex_nav_gal_nav()

```
void Rinex_Printer::log_rinex_nav_gal_nav (
    const std::map< int32_t, Galileo_Ephemeris > & new_gal_eph)
```

Print RINEX annotation for Galileo NAV message.

12.352.3.6 log_rinex_nav_glo_gnav()

```
void Rinex_Printer::log_rinex_nav_glo_gnav (
    const std::map< int32_t, Glonass_Gnav_Ephemeris > & new_glo_eph)
```

Print RINEX annotation for Glonass GNAV message.

12.352.3.7 log_rinex_nav_gps_cnav()

```
void Rinex_Printer::log_rinex_nav_gps_cnav (
    const std::map< int32_t, Gps_CNAV_Ephemeris > & new_cnav_eph)
```

Print RINEX annotation for GPS CNAV message.

12.352.3.8 log_rinex_nav_gps_nav()

```
void Rinex_Printer::log_rinex_nav_gps_nav (
    const std::map< int32_t, Gps_Ephemeris > & new_eph)
```

Print RINEX annotation for GPS NAV message.

12.352.3.9 print_rinex_annotation()

```
void Rinex_Printer::print_rinex_annotation (
    const Rtklib_Solver * pvt_solver,
    const std::map< int, Gnss_Synchro > & gnss_observables_map,
    double rx_time,
    bool flag_write_RINEX_obs_output)
```

Print RINEX annotation. If it is the first annotation, it also prints the RINEX headers for navigation and observation files. If it is not the first annotation, it only annotates the observation, and updates the navigation header if UTC data was not available when writing it for the first time.

The documentation for this class was generated from the following file:

- [rinex_printer.h](#)

12.353 RtcM Class Reference

This class implements the generation and reading of some Message Types defined in the RTCM 3.2 Standard, plus some utilities to handle messages.

```
#include <rtcm.h>
```

Public Member Functions

- [RtcM](#) (uint16_t port=2101)
Default constructor that sets TCP port of the RTCM message server and RTCM Station ID. 2101 is the standard RTCM port according to the Internet Assigned Numbers Authority (IANA). See <https://www.iana.org/assignments/service-names-port-numbers/service-names-port-numbers.xml>.
- std::string [print_MT1001](#) (const [Gps_Ephemeris](#) &gps_eph, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint16_t station_id)
Prints message type 1001 (L1-Only GPS RTK Observables)
- std::string [print_MT1002](#) (const [Gps_Ephemeris](#) &gps_eph, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint16_t station_id)
Prints message type 1002 (Extended L1-Only GPS RTK Observables)
- std::string [print_MT1003](#) (const [Gps_Ephemeris](#) &ephL1, const [Gps_CNAV_Ephemeris](#) &ephL2, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint16_t station_id)
Prints message type 1003 (L1 & L2 GPS RTK Observables)
- std::string [print_MT1004](#) (const [Gps_Ephemeris](#) &ephL1, const [Gps_CNAV_Ephemeris](#) &ephL2, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint16_t station_id)
Prints message type 1004 (Extended L1 & L2 GPS RTK Observables)
- std::string [print_MT1005](#) (uint32_t ref_id, double ecef_x, double ecef_y, double ecef_z, bool gps, bool glonass, bool galileo, bool non_physical, bool single_oscillator, uint32_t quarter_cycle_indicator)
Prints message type 1005 (Stationary Antenna Reference Point)
- int32_t [read_MT1005](#) (const std::string &message, uint32_t &ref_id, double &ecef_x, double &ecef_y, double &ecef_z, bool &gps, bool &glonass, bool &galileo)
Verifies and reads messages of type 1005 (Stationary Antenna Reference Point). Returns 1 if anything goes wrong, 0 otherwise.
- std::string [print_MT1006](#) (uint32_t ref_id, double ecef_x, double ecef_y, double ecef_z, bool gps, bool glonass, bool galileo, bool non_physical, bool single_oscillator, uint32_t quarter_cycle_indicator, double height)
Prints message type 1006 (Stationary Antenna Reference Point, with Height Information)
- std::string [print_MT1005_test](#) ()

For testing purposes.

- `std::string print_MT1008` (uint32_t ref_id, const std::string &antenna_descriptor, uint32_t antenna_setup_id, const std::string &antenna_serial_number)

Prints message type 1008 (Antenna Descriptor & Serial Number)

- `std::string print_MT1009` (const [Glonass_Gnav_Ephemeris](#) &glonass_gnav_eph, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint16_t station_id)

Prints L1-Only GLONASS RTK Observables.

- `std::string print_MT1010` (const [Glonass_Gnav_Ephemeris](#) &glonass_gnav_eph, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint16_t station_id)

Prints Extended L1-Only GLONASS RTK Observables.

- `std::string print_MT1011` (const [Glonass_Gnav_Ephemeris](#) &glonass_gnav_ephL1, const [Glonass_Gnav_Ephemeris](#) &glonass_gnav_ephL2, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint16_t station_id)

Prints L1&L2 GLONASS RTK Observables.

- `std::string print_MT1012` (const [Glonass_Gnav_Ephemeris](#) &glonass_gnav_ephL1, const [Glonass_Gnav_Ephemeris](#) &glonass_gnav_ephL2, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint16_t station_id)

Prints Extended L1&L2 GLONASS RTK Observables.

- `std::string print_MT1019` (const [Gps_Ephemeris](#) &gps_eph)

Prints message type 1019 (GPS Ephemeris), should be broadcast in the event that the IODC does not match the IODE, and every 2 minutes.

- `int32_t read_MT1019` (const std::string &message, [Gps_Ephemeris](#) &gps_eph) const

Verifies and reads messages of type 1019 (GPS Ephemeris). Returns 1 if anything goes wrong, 0 otherwise.

- `std::string print_MT1020` (const [Glonass_Gnav_Ephemeris](#) &glonass_gnav_eph, const [Glonass_Gnav_Utc_Model](#) &glonass_gnav_utc_model)

Prints message type 1020 (GLONASS Ephemeris).

- `int32_t read_MT1020` (const std::string &message, [Glonass_Gnav_Ephemeris](#) &glonass_gnav_eph, [Glonass_Gnav_Utc_Model](#) &glonass_gnav_utc_model) const

Verifies and reads messages of type 1020 (GLONASS Ephemeris).

- `std::string print_MT1029` (uint32_t ref_id, const [Gps_Ephemeris](#) &gps_eph, double obs_time, const std::string &message)

Prints message type 1029 (Unicode Text String)

- `std::string print_MT1045` (const [Galileo_Ephemeris](#) &gal_eph)

Prints message type 1045 (Galileo Ephemeris), should be broadcast every 2 minutes.

- `int32_t read_MT1045` (const std::string &message, [Galileo_Ephemeris](#) &gal_eph) const

Verifies and reads messages of type 1045 (Galileo Ephemeris). Returns 1 if anything goes wrong, 0 otherwise.

- `std::string print_MSM_1` (const [Gps_Ephemeris](#) &gps_eph, const [Gps_CNAV_Ephemeris](#) &gps_cnav_eph, const [Galileo_Ephemeris](#) &gal_eph, const [Glonass_Gnav_Ephemeris](#) &glo_gnav_eph, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint32_t ref_id, uint32_t clock_steering_indicator, uint32_t external_clock_indicator, int32_t smooth_int, bool divergence_free, bool more_messages)

Prints messages of type MSM1 (Compact GNSS observables)

- `std::string print_MSM_2` (const [Gps_Ephemeris](#) &gps_eph, const [Gps_CNAV_Ephemeris](#) &gps_cnav_eph, const [Galileo_Ephemeris](#) &gal_eph, const [Glonass_Gnav_Ephemeris](#) &glo_gnav_eph, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint32_t ref_id, uint32_t clock_steering_indicator, uint32_t external_clock_indicator, int32_t smooth_int, bool divergence_free, bool more_messages)

Prints messages of type MSM2 (Compact GNSS phaseranges)

- `std::string print_MSM_3` (const [Gps_Ephemeris](#) &gps_eph, const [Gps_CNAV_Ephemeris](#) &gps_cnav_eph, const [Galileo_Ephemeris](#) &gal_eph, const [Glonass_Gnav_Ephemeris](#) &glo_gnav_eph, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint32_t ref_id, uint32_t clock_steering_indicator, uint32_t external_clock_indicator, int32_t smooth_int, bool divergence_free, bool more_messages)

Prints messages of type MSM3 (Compact GNSS pseudoranges and phaseranges)

- `std::string print_MSM_4` (const [Gps_Ephemeris](#) &gps_eph, const [Gps_CNAV_Ephemeris](#) &gps_cnav_eph, const [Galileo_Ephemeris](#) &gal_eph, const [Glonass_Gnav_Ephemeris](#) &glo_gnav_eph, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint32_t ref_id, uint32_t clock_steering_indicator, uint32_t external_clock_indicator, int32_t smooth_int, bool divergence_free, bool more_messages)

Prints messages of type MSM4 (Full GNSS pseudoranges and phaseranges plus CNR)

- `std::string print_MSM_5` (const [Gps_Ephemeris](#) &gps_eph, const [Gps_CNAV_Ephemeris](#) &gps_cnav_eph, const [Galileo_Ephemeris](#) &gal_eph, const [Glonass_Gnav_Ephemeris](#) &glo_gnav_eph, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint32_t ref_id, uint32_t clock_steering_indicator, uint32_t external_clock_indicator, int32_t smooth_int, bool divergence_free, bool more_messages)

Prints messages of type MSM5 (Full GNSS pseudoranges, phaseranges, phaserange rate and CNR)

- `std::string print_MSM_6` (const [Gps_Ephemeris](#) &gps_eph, const [Gps_CNAV_Ephemeris](#) &gps_cnav_eph, const [Galileo_Ephemeris](#) &gal_eph, const [Glonass_Gnav_Ephemeris](#) &glo_gnav_eph, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint32_t ref_id, uint32_t clock_steering_indicator, uint32_t external_clock_indicator, int32_t smooth_int, bool divergence_free, bool more_messages)

Prints messages of type MSM6 (Full GNSS pseudoranges and phaseranges plus CNR, high resolution)

- `std::string print_MSM_7` (const [Gps_Ephemeris](#) &gps_eph, const [Gps_CNAV_Ephemeris](#) &gps_cnav_eph, const [Galileo_Ephemeris](#) &gal_eph, const [Glonass_Gnav_Ephemeris](#) &glo_gnav_eph, double obs_time, const std::map< int32_t, [Gnss_Synchro](#) > &observables, uint32_t ref_id, uint32_t clock_steering_indicator, uint32_t external_clock_indicator, int32_t smooth_int, bool divergence_free, bool more_messages)

Prints messages of type MSM7 (Full GNSS pseudoranges, phaseranges, phaserange rate and CNR, high resolution)

- `std::vector< std::string > print_IGM01` (const [Galileo_HAS_data](#) &has_data)

Prints messages of type IGM01 (SSR Orbit Correction)

- `std::vector< std::string > print_IGM02` (const [Galileo_HAS_data](#) &has_data)

Prints messages of type IGM02 (SSR Clock Correction)

- `std::vector< std::string > print_IGM03` (const [Galileo_HAS_data](#) &has_data)

Prints messages of type IGM03 (SSR Combined Orbit and Clock Correction)

- `std::vector< std::string > print_IGM05` (const [Galileo_HAS_data](#) &has_data)

Prints messages of type IGM05 (SSR Bias Correction)

- `uint32_t lock_time` (const [Gps_Ephemeris](#) &eph, double obs_time, const [Gnss_Synchro](#) &gnss_synchro)

Returns the time period in which GPS L1 signals have been continually tracked.

- `uint32_t lock_time` (const [Gps_CNAV_Ephemeris](#) &eph, double obs_time, const [Gnss_Synchro](#) &gnss_synchro)

Returns the time period in which GPS L2 signals have been continually tracked.

- `uint32_t lock_time` (const [Galileo_Ephemeris](#) &eph, double obs_time, const [Gnss_Synchro](#) &gnss_synchro)

Returns the time period in which Galileo signals have been continually tracked.

- `uint32_t lock_time` (const [Glonass_Gnav_Ephemeris](#) &eph, double obs_time, const [Gnss_Synchro](#) &gnss_synchro)

Locks time period in which GLONASS signals have been continually tracked.

- `std::string bin_to_hex` (const std::string &s) const

Returns a string of hexadecimal symbols from a string of binary symbols.

- `std::string hex_to_bin` (const std::string &s) const

Returns a string of binary symbols from a string of hexadecimal symbols.

- `std::string bin_to_binary_data` (const std::string &s) const

Returns a string of binary data from a string of binary symbols.

- `std::string binary_data_to_bin` (const std::string &s) const

Returns a string of binary symbols from a string of binary data.

- `uint32_t bin_to_uint` (const std::string &s) const

Returns an uint32_t from a string of binary symbols.

- `int32_t bin_to_int` (const std::string &s) const

- `double bin_to_double` (const std::string &s) const

Returns double from a string of binary symbols.

- `int32_t bin_to_sint` (const std::string &s) const

- `uint64_t hex_to_uint` (const std::string &s) const

Returns an uint64_t from a string of hexadecimal symbols.

- `int64_t hex_to_int` (const std::string &s) const

Returns a int64_t from a string of hexadecimal symbols.

- bool `check_CRC` (const std::string &message) const
Checks that the CRC of a RTCM package is correct.
- void `run_server` ()
Starts running the server.
- void `stop_server` ()
Stops the server.
- void `send_message` (const std::string &msg)
Sends a message through the server to all connected clients.
- bool `is_server_running` () const
Returns true if the server is running, false otherwise.

12.353.1 Detailed Description

This class implements the generation and reading of some Message Types defined in the RTCM 3.2 Standard, plus some utilities to handle messages.

Generation of the following Message Types: 1001, 1002, 1003, 1004, 1005, 1006, 1008, 1019, 1020, 1029, 1045

Decoding of the following Message Types: 1019, 1045

Generation of the following Multiple Signal Messages: MSM1 (message types 1071, 1091) MSM2 (message types 1072, 1092) MSM3 (message types 1073, 1093) MSM4 (message types 1074, 1094) MSM5 (message types 1075, 1095) MSM6 (message types 1076, 1096) MSM7 (message types 1077, 1097)

RTCM 3 message format (size in bits): +-----+-----+-----+-----+-----+ | preamble | 000000
| length | data message | parity | +-----+-----+-----+-----+-----+ | <- 8 ---> | <- 6 --> | <- 10
---> | <- length x 8 ---> | <- 24 --> | +-----+-----+-----+-----+-----+ |

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Definition at line 97 of file [rtcm.h](#).

12.353.2 Constructor & Destructor Documentation

12.353.2.1 RtcM()

```
RtcM::RtcM (
    uint16_t port = 2101) [explicit]
```

Default constructor that sets TCP port of the RTCM message server and RTCM Station ID. 2101 is the standard RTCM port according to the Internet Assigned Numbers Authority (IANA). See <https://www.iana.org/assignments/service-names-port-numbers/service-names-port-numbers.xml>.

References [RtcM\(\)](#).

Referenced by [RtcM\(\)](#).

12.353.3 Member Function Documentation

12.353.3.1 bin_to_binary_data()

```
std::string RtcM::bin_to_binary_data (
    const std::string & s) const
```

Returns a string of binary data from a string of binary symbols.

12.353.3.2 bin_to_double()

```
double RtcM::bin_to_double (
    const std::string & s) const
```

Returns double from a string of binary symbols.

12.353.3.3 bin_to_hex()

```
std::string RtcM::bin_to_hex (
    const std::string & s) const
```

Returns a string of hexadecimal symbols from a string of binary symbols.

12.353.3.4 bin_to_uint()

```
uint32_t RtcM::bin_to_uint (
    const std::string & s) const
```

Returns an uint32_t from a string of binary symbols.

12.353.3.5 binary_data_to_bin()

```
std::string RtcM::binary_data_to_bin (
    const std::string & s) const
```

Returns a string of binary symbols from a string of binary data.

12.353.3.6 check_CRC()

```
bool RtcM::check_CRC (
    const std::string & message) const
```

Checks that the CRC of a RTCM package is correct.

12.353.3.7 hex_to_bin()

```
std::string RtcM::hex_to_bin (
    const std::string & s) const
```

Returns a string of binary symbols from a string of hexadecimal symbols.

12.353.3.8 hex_to_int()

```
int64_t RtcM::hex_to_int (
    const std::string & s) const
```

Returns a int64_t from a string of hexadecimal symbols.

12.353.3.9 hex_to_uint()

```
uint64_t RtcM::hex_to_uint (
    const std::string & s) const
```

Returns an uint64_t from a string of hexadecimal symbols.

12.353.3.10 is_server_running()

```
bool RtcM::is_server_running () const
```

Returns true if the server is running, false otherwise.

12.353.3.11 lock_time() [1/4]

```
uint32_t RtcM::lock_time (
    const Galileo_Ephemeris & eph,
    double obs_time,
    const Gnss_Synchro & gnss_synchro)
```

Returns the time period in which Galileo signals have been continually tracked.

12.353.3.12 lock_time() [2/4]

```
uint32_t RtcM::lock_time (
    const Glonass_Gnav_Ephemeris & eph,
    double obs_time,
    const Gnss_Synchro & gnss_synchro)
```

Locks time period in which GLONASS signals have been continually tracked.

Note

Code added as part of GSoC 2017 program

Parameters

<i>eph</i>	GLONASS GNAV Broadcast Ephemeris
<i>obs_time</i>	Time of observation at the moment of printing
<i>observables</i>	Set of observables as defined by the platform

Returns

Returns the time period in which GLONASS signals have been continually tracked.

12.353.3.13 lock_time() [3/4]

```
uint32_t RtcM::lock_time (
    const Gps_CNAV_Ephemeris & eph,
    double obs_time,
    const Gnss_Synchro & gnss_synchro)
```

Returns the time period in which GPS L2 signals have been continually tracked.

12.353.3.14 lock_time() [4/4]

```
uint32_t RtcM::lock_time (
    const Gps_Ephemeris & eph,
    double obs_time,
    const Gnss_Synchro & gnss_synchro)
```

Returns the time period in which GPS L1 signals have been continually tracked.

12.353.3.15 print_IGM01()

```
std::vector< std::string > RtcM::print_IGM01 (
    const Galileo_HAS_data & has_data)
```

Prints messages of type IGM01 (SSR Orbit Correction)

12.353.3.16 print_IGM02()

```
std::vector< std::string > RtcM::print_IGM02 (
    const Galileo_HAS_data & has_data)
```

Prints messages of type IGM02 (SSR Clock Correction)

12.353.3.17 print_IGM03()

```
std::vector< std::string > RtcM::print_IGM03 (
    const Galileo_HAS_data & has_data)
```

Prints messages of type IGM03 (SSR Combined Orbit and Clock Correction)

12.353.3.18 print_IGM05()

```
std::vector< std::string > RtcM::print_IGM05 (
    const Galileo_HAS_data & has_data)
```

Prints messages of type IGM05 (SSR Bias Correction)

12.353.3.19 print_MSM_1()

```
std::string RtcM::print_MSM_1 (
    const Gps_Ephemeris & gps_eph,
    const Gps_CNAV_Ephemeris & gps_cnav_eph,
    const Galileo_Ephemeris & gal_eph,
    const Glonass_Gnav_Ephemeris & glo_gnav_eph,
    double obs_time,
```

```

    const std::map< int32_t, Gnss_Synchro > & observables,
    uint32_t ref_id,
    uint32_t clock_steering_indicator,
    uint32_t external_clock_indicator,
    int32_t smooth_int,
    bool divergence_free,
    bool more_messages)

```

Prints messages of type MSM1 (Compact GNSS observables)

12.353.3.20 print_MSM_2()

```

std::string RtcM::print_MSM_2 (
    const Gps_Ephemeris & gps_eph,
    const Gps_CNAV_Ephemeris & gps_cnav_eph,
    const Galileo_Ephemeris & gal_eph,
    const Glonass_Gnav_Ephemeris & glo_gnav_eph,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint32_t ref_id,
    uint32_t clock_steering_indicator,
    uint32_t external_clock_indicator,
    int32_t smooth_int,
    bool divergence_free,
    bool more_messages)

```

Prints messages of type MSM2 (Compact GNSS phaseranges)

12.353.3.21 print_MSM_3()

```

std::string RtcM::print_MSM_3 (
    const Gps_Ephemeris & gps_eph,
    const Gps_CNAV_Ephemeris & gps_cnav_eph,
    const Galileo_Ephemeris & gal_eph,
    const Glonass_Gnav_Ephemeris & glo_gnav_eph,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint32_t ref_id,
    uint32_t clock_steering_indicator,
    uint32_t external_clock_indicator,
    int32_t smooth_int,
    bool divergence_free,
    bool more_messages)

```

Prints messages of type MSM3 (Compact GNSS pseudoranges and phaseranges)

12.353.3.22 print_MSM_4()

```

std::string RtcM::print_MSM_4 (
    const Gps_Ephemeris & gps_eph,
    const Gps_CNAV_Ephemeris & gps_cnav_eph,
    const Galileo_Ephemeris & gal_eph,
    const Glonass_Gnav_Ephemeris & glo_gnav_eph,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint32_t ref_id,
    uint32_t clock_steering_indicator,
    uint32_t external_clock_indicator,
    int32_t smooth_int,
    bool divergence_free,
    bool more_messages)

```

Prints messages of type MSM4 (Full GNSS pseudoranges and phaseranges plus CNR)

12.353.3.23 print_MSM_5()

```
std::string RtcM::print_MSM_5 (
    const Gps_Ephemeris & gps_eph,
    const Gps_CNAV_Ephemeris & gps_cnav_eph,
    const Galileo_Ephemeris & gal_eph,
    const Glonass_Gnav_Ephemeris & glo_gnav_eph,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint32_t ref_id,
    uint32_t clock_steering_indicator,
    uint32_t external_clock_indicator,
    int32_t smooth_int,
    bool divergence_free,
    bool more_messages)
```

Prints messages of type MSM5 (Full GNSS pseudoranges, phaseranges, phaserange rate and CNR)

12.353.3.24 print_MSM_6()

```
std::string RtcM::print_MSM_6 (
    const Gps_Ephemeris & gps_eph,
    const Gps_CNAV_Ephemeris & gps_cnav_eph,
    const Galileo_Ephemeris & gal_eph,
    const Glonass_Gnav_Ephemeris & glo_gnav_eph,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint32_t ref_id,
    uint32_t clock_steering_indicator,
    uint32_t external_clock_indicator,
    int32_t smooth_int,
    bool divergence_free,
    bool more_messages)
```

Prints messages of type MSM6 (Full GNSS pseudoranges and phaseranges plus CNR, high resolution)

12.353.3.25 print_MSM_7()

```
std::string RtcM::print_MSM_7 (
    const Gps_Ephemeris & gps_eph,
    const Gps_CNAV_Ephemeris & gps_cnav_eph,
    const Galileo_Ephemeris & gal_eph,
    const Glonass_Gnav_Ephemeris & glo_gnav_eph,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint32_t ref_id,
    uint32_t clock_steering_indicator,
    uint32_t external_clock_indicator,
    int32_t smooth_int,
    bool divergence_free,
    bool more_messages)
```

Prints messages of type MSM7 (Full GNSS pseudoranges, phaseranges, phaserange rate and CNR, high resolution)

12.353.3.26 print_MT1001()

```
std::string RtcM::print_MT1001 (
    const Gps_Ephemeris & gps_eph,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint16_t station_id)
```

Prints message type 1001 (L1-Only GPS RTK Observables)

12.353.3.27 print_MT1002()

```
std::string RtcM::print_MT1002 (
    const Gps_Ephemeris & gps_eph,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint16_t station_id)
```

Prints message type 1002 (Extended L1-Only GPS RTK Observables)

12.353.3.28 print_MT1003()

```
std::string RtcM::print_MT1003 (
    const Gps_Ephemeris & ephL1,
    const Gps_CNAV_Ephemeris & ephL2,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint16_t station_id)
```

Prints message type 1003 (L1 & L2 GPS RTK Observables)

12.353.3.29 print_MT1004()

```
std::string RtcM::print_MT1004 (
    const Gps_Ephemeris & ephL1,
    const Gps_CNAV_Ephemeris & ephL2,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint16_t station_id)
```

Prints message type 1004 (Extended L1 & L2 GPS RTK Observables)

12.353.3.30 print_MT1005()

```
std::string RtcM::print_MT1005 (
    uint32_t ref_id,
    double ecef_x,
    double ecef_y,
    double ecef_z,
    bool gps,
    bool glonass,
    bool galileo,
    bool non_physical,
    bool single_oscillator,
    uint32_t quarter_cycle_indicator)
```

Prints message type 1005 (Stationary Antenna Reference Point)

12.353.3.31 print_MT1005_test()

```
std::string RtcM::print_MT1005_test ()
```

For testing purposes.

12.353.3.32 print_MT1006()

```
std::string RtcM::print_MT1006 (
    uint32_t ref_id,
    double ecef_x,
    double ecef_y,
    double ecef_z,
    bool gps,
```



```

    bool glonass,
    bool galileo,
    bool non_physical,
    bool single_oscillator,
    uint32_t quarter_cycle_indicator,
    double height)

```

Prints message type 1006 (Stationary Antenna Reference Point, with Height Information)

12.353.3.33 print_MT1008()

```

std::string RtcM::print_MT1008 (
    uint32_t ref_id,
    const std::string & antenna_descriptor,
    uint32_t antenna_setup_id,
    const std::string & antenna_serial_number)

```

Prints message type 1008 (Antenna Descriptor & Serial Number)

12.353.3.34 print_MT1009()

```

std::string RtcM::print_MT1009 (
    const Glonass_Gnav_Ephemeris & glonass_gnav_eph,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint16_t station_id)

```

Prints L1-Only GLONASS RTK Observables.

This GLONASS message type is not generally used or supported; type 1012 is to be preferred.

Note

Code added as part of GSoC 2017 program

Parameters

<i>glonass_gnav_eph</i>	GLONASS GNAV Broadcast Ephemeris
<i>obs_time</i>	Time of observation at the moment of printing
<i>observables</i>	Set of observables as defined by the platform

Returns

string with message contents

12.353.3.35 print_MT1010()

```

std::string RtcM::print_MT1010 (
    const Glonass_Gnav_Ephemeris & glonass_gnav_eph,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint16_t station_id)

```

Prints Extended L1-Only GLONASS RTK Observables.

This GLONASS message type is used when only L1 data is present and bandwidth is very tight, often 1012 is used in such cases.

Note

Code added as part of GSoC 2017 program

Parameters

<i>glonass_gnav_eph</i>	GLONASS GNAV Broadcast Ephemeris
<i>obs_time</i>	Time of observation at the moment of printing
<i>observables</i>	Set of observables as defined by the platform

Returns

string with message contents

12.353.3.36 print_MT1011()

```
std::string RtcM::print_MT1011 (
    const Glonass_Gnav_Ephemeris & glonass_gnav_ephL1,
    const Glonass_Gnav_Ephemeris & glonass_gnav_ephL2,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint16_t station_id)
```

Prints L1&L2 GLONASS RTK Observables.

This GLONASS message type is not generally used or supported; type 1012 is to be preferred

Note

Code added as part of GSoC 2017 program

Parameters

<i>glonass_gnav_eph</i>	GLONASS GNAV Broadcast Ephemeris
<i>obs_time</i>	Time of observation at the moment of printing
<i>observables</i>	Set of observables as defined by the platform

Returns

string with message contents

12.353.3.37 print_MT1012()

```
std::string RtcM::print_MT1012 (
    const Glonass_Gnav_Ephemeris & glonass_gnav_ephL1,
    const Glonass_Gnav_Ephemeris & glonass_gnav_ephL2,
    double obs_time,
    const std::map< int32_t, Gnss_Synchro > & observables,
    uint16_t station_id)
```

Prints Extended L1&L2 GLONASS RTK Observables.

This GLONASS message type is the most common observational message type, with L1/L2/SNR content. This is one of the most common messages found.

Note

Code added as part of GSoC 2017 program

Parameters

<i>glonass_gnav_eph</i>	GLONASS GNAV Broadcast Ephemeris
<i>obs_time</i>	Time of observation at the moment of printing
<i>observables</i>	Set of observables as defined by the platform

Returns

string with message contents

12.353.3.38 print_MT1019()

```
std::string RtcM::print_MT1019 (
    const Gps\_Ephemeris & gps_eph)
```

Prints message type 1019 (GPS Ephemeris), should be broadcast in the event that the IODC does not match the IODE, and every 2 minutes.

12.353.3.39 print_MT1020()

```
std::string RtcM::print_MT1020 (
    const Glonass\_Gnav\_Ephemeris & glonass_gnav_eph,
    const Glonass\_Gnav\_Utc\_Model & glonass_gnav_utc_model)
```

Prints message type 1020 (GLONASS Ephemeris).

Note

Code added as part of GSoC 2017 program

Parameters

<i>glonass_gnav_eph</i>	GLONASS GNAV Broadcast Ephemeris
<i>glonass_gnav_utc_model</i>	GLONASS GNAV Clock Information

Returns

Returns message type as a string type

12.353.3.40 print_MT1029()

```
std::string RtcM::print_MT1029 (
    uint32_t ref_id,
    const Gps\_Ephemeris & gps_eph,
    double obs_time,
    const std::string & message)
```

Prints message type 1029 (Unicode Text String)

12.353.3.41 print_MT1045()

```
std::string RtcM::print_MT1045 (
    const Galileo\_Ephemeris & gal_eph)
```

Prints message type 1045 (Galileo Ephemeris), should be broadcast every 2 minutes.

12.353.3.42 read_MT1005()

```
int32_t RtcM::read_MT1005 (
    const std::string & message,
    uint32_t & ref_id,
    double & ecef_x,
    double & ecef_y,
    double & ecef_z,
    bool & gps,
    bool & glonass,
    bool & galileo)
```

Verifies and reads messages of type 1005 (Stationary Antenna Reference Point). Returns 1 if anything goes wrong, 0 otherwise.

12.353.3.43 read_MT1019()

```
int32_t RtcM::read_MT1019 (
    const std::string & message,
    Gps_Ephemeris & gps_eph) const
```

Verifies and reads messages of type 1019 (GPS Ephemeris). Returns 1 if anything goes wrong, 0 otherwise.

12.353.3.44 read_MT1020()

```
int32_t RtcM::read_MT1020 (
    const std::string & message,
    Glonass_Gnav_Ephemeris & glonass_gnav_eph,
    Glonass_Gnav_Utc_Model & glonass_gnav_utc_model) const
```

Verifies and reads messages of type 1020 (GLONASS Ephemeris).

Note

Code added as part of GSoC 2017 program

Parameters

<i>message</i>	Message to read as a string type
<i>glonass_gnav_eph</i>	GLONASS GNAV Broadcast Ephemeris
<i>glonass_gnav_utc_model</i>	GLONASS GNAV Clock Information

Returns

Returns 1 if anything goes wrong, 0 otherwise.

12.353.3.45 read_MT1045()

```
int32_t RtcM::read_MT1045 (
    const std::string & message,
    Galileo_Ephemeris & gal_eph) const
```

Verifies and reads messages of type 1045 (Galileo Ephemeris). Returns 1 if anything goes wrong, 0 otherwise.

12.353.3.46 run_server()

```
void RtcM::run_server ()
```

Starts running the server.

12.353.3.47 send_message()

```
void RtcM::send_message (
    const std::string & msg)
```

Sends a message through the server to all connected clients.

12.353.3.48 stop_server()

```
void RtcM::stop_server ()
```

Stops the server.

The documentation for this class was generated from the following file:

- [rtcM.h](#)

12.354 RtcM_Printer Class Reference

This class provides a implementation of a subset of the RTCM Standard 10403.2 messages.

```
#include <rtcM_printer.h>
```

Public Member Functions

- [Rtcn_Printer](#) (const std::string &filename, bool flag_rtcn_file_dump, bool flag_rtcn_server, bool flag_rtcn_tty_port, uint16_t rtcn_tcp_port, uint16_t rtcn_station_id, const std::string &rtcn_dump_devname, uint32_t signal_enabled_flags, bool time_tag_name=true, const std::string &base_path=".")
Default constructor.
- [~Rtcn_Printer](#) ()
Default destructor.
- void [Print_Rtcn_Messages](#) (const [Rtklib_Solver](#) *pvt_solver, const std::map< int, [Gnss_Synchro](#) > &gnss_observables_map, double rx_time, bool rtcn_MSM_enabled, bool rtcn_MT1019_enabled, bool rtcn_MT1020_enabled, bool rtcn_MT1045_enabled, bool rtcn_MT1077_enabled, bool rtcn_MT1087_enabled, bool rtcn_MT1097_enabled, bool flag_write_RTCM_MSM_output, bool flag_write_RTCM_1019_output, bool flag_write_RTCM_1020_output, bool flag_write_RTCM_1045_output, bool enable_rx_clock_correction)
Print RTCM messages.
- uint32_t [lock_time](#) (const [Gps_Ephemeris](#) &eph, double obs_time, const [Gnss_Synchro](#) &gnss_synchro)
- uint32_t [lock_time](#) (const [Gps_CNAV_Ephemeris](#) &eph, double obs_time, const [Gnss_Synchro](#) &gnss_synchro)
- uint32_t [lock_time](#) (const [Galileo_Ephemeris](#) &eph, double obs_time, const [Gnss_Synchro](#) &gnss_synchro)
- uint32_t [lock_time](#) (const [Glonass_Gnav_Ephemeris](#) &eph, double obs_time, const [Gnss_Synchro](#) &gnss_synchro)
Locks time for logging given GLONASS GNAV Broadcast Ephemeris.
- void [Print_IGM_Messages](#) (const [Galileo_HAS_data](#) &has_data)
- std::string [print_MT1005_test](#) ()
For testing purposes.

12.354.1 Detailed Description

This class provides a implementation of a subset of the RTCM Standard 10403.2 messages.
Definition at line 49 of file [rtcn_printer.h](#).

12.354.2 Constructor & Destructor Documentation

12.354.2.1 Rtcn_Printer()

```
Rtcn_Printer::Rtcn_Printer (
    const std::string & filename,
    bool flag_rtcn_file_dump,
    bool flag_rtcn_server,
    bool flag_rtcn_tty_port,
    uint16_t rtcn_tcp_port,
    uint16_t rtcn_station_id,
    const std::string & rtcn_dump_devname,
    uint32_t signal_enabled_flags,
    bool time_tag_name = true,
    const std::string & base_path = ".")
```

Default constructor.

12.354.2.2 ~Rtcn_Printer()

```
Rtcn_Printer::~~Rtcn_Printer ()
```

Default destructor.

12.354.3 Member Function Documentation

12.354.3.1 lock_time()

```
uint32_t Rtcn_Printer::lock_time (
    const Glonass\_Gnav\_Ephemeris & eph,
```

```
double obs_time,
const Gnss_Synchro & gnss_synchro)
```

Locks time for logging given GLONASS GNAV Broadcast Ephemeris.

Note

Code added as part of GSoC 2017 program \params glonass_gnav_eph GLONASS GNAV Broadcast Ephemeris \params obs_time Time of observation at the moment of printing \params observables Set of observables as defined by the platform

Returns

locked time during logging process

12.354.3.2 print_MT1005_test()

```
std::string RtcM_Printer::print_MT1005_test ()
```

For testing purposes.

12.354.3.3 Print_RtcM_Messages()

```
void RtcM_Printer::Print_RtcM_Messages (
    const Rtklib_Solver * pvt_solver,
    const std::map< int, Gnss_Synchro > & gnss_observables_map,
    double rx_time,
    bool rtcM_MSM_enabled,
    bool rtcM_MT1019_enabled,
    bool rtcM_MT1020_enabled,
    bool rtcM_MT1045_enabled,
    bool rtcM_MT1077_enabled,
    bool rtcM_MT1087_enabled,
    bool rtcM_MT1097_enabled,
    bool flag_write_RTCM_MSM_output,
    bool flag_write_RTCM_1019_output,
    bool flag_write_RTCM_1020_output,
    bool flag_write_RTCM_1045_output,
    bool enable_rx_clock_correction)
```

Print RTCM messages.

The documentation for this class was generated from the following file:

- [rtcM_printer.h](#)

12.355 rtcM_t Struct Reference

Public Attributes

- int [staid](#)
- int [stah](#)
- int [seqno](#)
- int [outtype](#)
- [gtime_t](#) [time](#)
- [gtime_t](#) [time_s](#)
- [obs_t](#) [obs](#)
- [nav_t](#) [nav](#)
- [sta_t](#) [sta](#)
- [dgps_t](#) * [dgps](#)
- [ssr_t](#) [ssr](#) [MAXSAT]
- char [msg](#) [128]

- char [msgtype](#) [256]
- char [msmtype](#) [6][128]
- int [obsflag](#)
- int [ephsat](#)
- double [cp](#) [MAXSAT][NFREQ+NEXOBS]
- unsigned short [lock](#) [MAXSAT][NFREQ+NEXOBS]
- unsigned short [loss](#) [MAXSAT][NFREQ+NEXOBS]
- [gtime_t](#) [lltime](#) [MAXSAT][NFREQ+NEXOBS]
- int [nbyte](#)
- int [nbit](#)
- int [len](#)
- unsigned char [buff](#) [1200]
- unsigned int [word](#)
- unsigned int [nmsg2](#) [100]
- unsigned int [nmsg3](#) [400]
- char [opt](#) [256]

12.355.1 Detailed Description

Definition at line 875 of file [rtklib.h](#).

12.355.2 Member Data Documentation

12.355.2.1 buff

```
unsigned char rtm_t::buff[1200]
```

Definition at line 900 of file [rtklib.h](#).

12.355.2.2 cp

```
double rtm_t::cp[MAXSAT][NFREQ+NEXOBS]
```

Definition at line 893 of file [rtklib.h](#).

12.355.2.3 dgps

```
dgps\_t* rtm_t::dgps
```

Definition at line 886 of file [rtklib.h](#).

12.355.2.4 ephsat

```
int rtm_t::ephsat
```

Definition at line 892 of file [rtklib.h](#).

12.355.2.5 len

```
int rtm_t::len
```

Definition at line 899 of file [rtklib.h](#).

12.355.2.6 lltime

```
gtime\_t rtm_t::lltime[MAXSAT][NFREQ+NEXOBS]
```

Definition at line 896 of file [rtklib.h](#).

12.355.2.7 lock

```
unsigned short rtm_t::lock[MAXSAT][NFREQ+NEXOBS]
```

Definition at line 894 of file [rtklib.h](#).

12.355.2.8 loss

unsigned short rtcmt::loss[MAXSAT] [NFREQ+NEXOBS]
Definition at line 895 of file [rtklib.h](#).

12.355.2.9 msg

char rtcmt::msg[128]
Definition at line 888 of file [rtklib.h](#).

12.355.2.10 msgtype

char rtcmt::msgtype[256]
Definition at line 889 of file [rtklib.h](#).

12.355.2.11 msmttype

char rtcmt::msmttype[6][128]
Definition at line 890 of file [rtklib.h](#).

12.355.2.12 nav

[nav_t](#) rtcmt::nav
Definition at line 884 of file [rtklib.h](#).

12.355.2.13 nbit

int rtcmt::nbit
Definition at line 898 of file [rtklib.h](#).

12.355.2.14 nbyte

int rtcmt::nbyte
Definition at line 897 of file [rtklib.h](#).

12.355.2.15 nmsg2

unsigned int rtcmt::nmsg2[100]
Definition at line 902 of file [rtklib.h](#).

12.355.2.16 nmsg3

unsigned int rtcmt::nmsg3[400]
Definition at line 903 of file [rtklib.h](#).

12.355.2.17 obs

[obs_t](#) rtcmt::obs
Definition at line 883 of file [rtklib.h](#).

12.355.2.18 obsflag

int rtcmt::obsflag
Definition at line 891 of file [rtklib.h](#).

12.355.2.19 opt

char rtcmt::opt[256]
Definition at line 904 of file [rtklib.h](#).

12.355.2.20 outtype

```
int rtkm_t::outtype
```

Definition at line 880 of file [rtklib.h](#).

12.355.2.21 seqno

```
int rtkm_t::seqno
```

Definition at line 879 of file [rtklib.h](#).

12.355.2.22 ssr

```
ssr_t rtkm_t::ssr[MAXSAT]
```

Definition at line 887 of file [rtklib.h](#).

12.355.2.23 sta

```
sta_t rtkm_t::sta
```

Definition at line 885 of file [rtklib.h](#).

12.355.2.24 stah

```
int rtkm_t::stah
```

Definition at line 878 of file [rtklib.h](#).

12.355.2.25 staid

```
int rtkm_t::staid
```

Definition at line 877 of file [rtklib.h](#).

12.355.2.26 time

```
gtime_t rtkm_t::time
```

Definition at line 881 of file [rtklib.h](#).

12.355.2.27 time_s

```
gtime_t rtkm_t::time_s
```

Definition at line 882 of file [rtklib.h](#).

12.355.2.28 word

```
unsigned int rtkm_t::word
```

Definition at line 901 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.356 rtk_t Struct Reference

Public Attributes

- [sol_t](#) [sol](#)
- double [rb](#) [6]
- int [nx](#)
- int [na](#)
- double [tt](#)
- double * [x](#)
- double * [P](#)

- double * [xa](#)
- double * [Pa](#)
- int [nfix](#)
- [ambc_t](#) [ambc](#) [MAXSAT]
- [ssat_t](#) [ssat](#) [MAXSAT]
- int [neb](#)
- char [errbuf](#) [MAXERRMSG]
- [prcopt_t](#) [opt](#)

12.356.1 Detailed Description

Definition at line [1067](#) of file [rtklib.h](#).

12.356.2 Member Data Documentation

12.356.2.1 [ambc](#)

[ambc_t](#) [rtk_t::ambc](#) [MAXSAT]

Definition at line [1076](#) of file [rtklib.h](#).

12.356.2.2 [errbuf](#)

char [rtk_t::errbuf](#) [MAXERRMSG]

Definition at line [1079](#) of file [rtklib.h](#).

12.356.2.3 [na](#)

int [rtk_t::na](#)

Definition at line [1071](#) of file [rtklib.h](#).

12.356.2.4 [neb](#)

int [rtk_t::neb](#)

Definition at line [1078](#) of file [rtklib.h](#).

12.356.2.5 [nfix](#)

int [rtk_t::nfix](#)

Definition at line [1075](#) of file [rtklib.h](#).

12.356.2.6 [nx](#)

int [rtk_t::nx](#)

Definition at line [1071](#) of file [rtklib.h](#).

12.356.2.7 [opt](#)

[prcopt_t](#) [rtk_t::opt](#)

Definition at line [1080](#) of file [rtklib.h](#).

12.356.2.8 [P](#)

double * [rtk_t::P](#)

Definition at line [1073](#) of file [rtklib.h](#).

12.356.2.9 [Pa](#)

double * [rtk_t::Pa](#)

Definition at line [1074](#) of file [rtklib.h](#).

12.356.2.10 rb

```
double rtk_t::rb[6]
```

Definition at line 1070 of file [rtklib.h](#).

12.356.2.11 sol

```
sol_t rtk_t::sol
```

Definition at line 1069 of file [rtklib.h](#).

12.356.2.12 ssat

```
ssat_t rtk_t::ssat [MAXSAT]
```

Definition at line 1077 of file [rtklib.h](#).

12.356.2.13 tt

```
double rtk_t::tt
```

Definition at line 1072 of file [rtklib.h](#).

12.356.2.14 x

```
double* rtk_t::x
```

Definition at line 1073 of file [rtklib.h](#).

12.356.2.15 xa

```
double* rtk_t::xa
```

Definition at line 1074 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

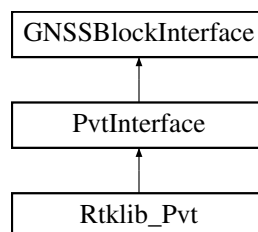
- [rtklib.h](#)

12.357 Rtklib_Pvt Class Reference

This class implements a [PvtInterface](#) for the RTKLIB PVT block.

```
#include <rtklib_pvt.h>
```

Inheritance diagram for Rtklib_Pvt:

**Public Member Functions**

- **Rtklib_Pvt** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [role](#) () override
- std::string [implementation](#) () override

Returns "RTKLIB_PVT".
- void [clear_ephemeris](#) () override
- std::map< int, [Gps_Ephemeris](#) > [get_gps_ephemeris](#) () const override
- std::map< int, [Galileo_Ephemeris](#) > [get_galileo_ephemeris](#) () const override

- `std::map< int, Gps_Almanac > get_gps_almanac ()` const override
 - `std::map< int, Galileo_Almanac > get_galileo_almanac ()` const override
 - `void connect (gr::top_block_sptr top_block)` override
 - `void disconnect (gr::top_block_sptr top_block)` override
 - `gr::basic_block_sptr get_left_block ()` override
 - `gr::basic_block_sptr get_right_block ()` override
 - `void reset ()` override
 - `size_t item_size ()` override
- All blocks must have an [item_size\(\)](#) function implementation.*
- `bool get_latest_PVT (double *longitude_deg, double *latitude_deg, double *height_m, double *ground_↵
speed_kmh, double *course_over_ground_deg, time_t *UTC_time)` override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual `gr::basic_block_sptr get_left_block (int RF_channel)`
- virtual `gr::basic_block_sptr get_right_block (int RF_channel)`
- virtual `void start ()`

Start the flow of samples if needed.

12.357.1 Detailed Description

This class implements a [PvtInterface](#) for the RTKLIB PVT block.

Global configuration options used:

`GNSS-SDR.pre_2009_file` - flag indicating a file older than 2009 rollover should be processed (false) `GNSS-SDR.↵
observable_interval_ms` - (20)

It supports the following configuration options:

`.dump` - (false) `.dump_filename` - ("/pvt.dat") `.dump_mat` - (true) `.rtk_trace_level` - debug level for the RTKLIB meth-
ods (0)

`.output_rate_ms` - (500) Note that the actual rate is the least common multiple of this value and `GNSS-SDR.↵
observable_interval_ms` `.display_rate_ms` - (500)

`.flag_nmea_tty_port` - (false) `.nmea_dump_filename` - ("/nmea_pvt.nmea") `.nmea_dump_devname` - ("/dev/tty1")

`.rinex_version` - (3) overridden by `-RINEX_version=n.nn` command line argument `.rinexobs_rate_ms` - rate at which
RINEX observations are written (1000). Note that the actual rate is the least common multiple of this value and
`.output_rate_ms` `.rinex_name` - (-RINEX_name command-line argument)

`.flag_rtcn_tty_port` - (false) `.rtcm_dump_devname` - ("/dev/pts/1") `.flag_rtcn_server` - (false) `.rtcm_tcp_port` - (2101)

`.rtcm_station_id` - (1234) Output rates ... all values are LCM with the computed output rate (above) `.rtcm_↵
MT1019_rate_ms` - (5000) `.rtcm_MT1020_rate_ms` - (5000) `.rtcm_MT1045_rate_ms` - (5000) `.rtcm_MSM_rate_ms`
- (1000) `.rtcm_MT1077_rate_ms` - (.rtcm_MSM_rate_ms) `.rtcm_MT1087_rate_ms` - (.rtcm_MSM_rate_ms) `.rtcm_↵
_MT1097_rate_ms` - (.rtcm_MSM_rate_ms)

`.kml_rate_ms` - (1000) `.gpx_rate_ms` - (1000) `.geojson_rate_ms` - (1000) `.nmea_rate_ms` - (1000)

`.positioning_mode` - The RTKLIB positioning mode. ("Single") Supported values are "Single", "Static", "Kinematic",
"PPP_Static" and "PPP_Kinematic". Unsupported modes include DGPS/DGNSS, Moving Baseline, Fixed, and
PPP-fixed `.num_bands` - number of frequencies to use, between 1 and 3. Default is based on the channels con-
figured `.elevation_mask` - (15.0). Value must be in the range [0,90.0] `.dynamics_model` - (0) 0:none, 1:velocity,
2:acceleration

`.iono_model` - ("OFF"). Supported values are "OFF", "Broadcast", "SBAS", "Iono-Free-LC", "Estimate_STEC", "↵
IONEX". Unsupported values include QZSS broadcast, QZSS LEX, and SLANT TEC. `.trop_model` - ("OFF"). Sup-
ported values are "OFF", "Saastamoinen", "SBAS", "Estimate_ZTD", and "Estimate_ZTD_Grad". Unsupported
values include ZTD correction and ZTD+grad correction `.phwindup` - phase windup correction for PPP modes (0)

`.reject_GPS_IIA` - whether the GPS Block IIA satellites in eclipse are excluded (0). Only applies in PPP-* modes

`.raim_fde` - whether RAIM (receiver autonomous integrity monitoring) FDE (fault detection and exclusion) is enabled
(0) `.earth_tide` - (0) `.navigation_system` - mask of navigation systems to use. Default based on configured channels
0x01:GPS, 0x02:SBAS, 0x04:GLONASS, 0x08:Galileo, 0x10:QZSS, 0x20:BeiDou, 0x40:IRNS, 0x80:LEO

`.AR_GPS` - Ambiguity Resolution mode for GPS ("Continuous"). Supported values are "OFF", "Continuous", "↵
Instantaneous", "Fix-and-Hold", "PPP-AR". Unsupported values include PPP-AR ILS, WLNL, and TCAR. `.AR_GLO`
- Ambiguity Resolution mode for GLONASS (1). Value must be in the range [0,3]. (0:off,1:on,2:auto cal,3:ext cal)

.AR_DBS - Ambiguity Resolution Mode for BeiDou (1). Value must be in the range [0,1]. (0:off,1:on) .min_ratio_↵
to_fix_ambiguity - (3.0) .min_lock_to_fix_ambiguity - (0) .min_elevation_to_fix_ambiguity - minimum elevation (deg)
to fix integer ambiguity (0.0) .outage_reset_ambiguity - (5) .slip_threshold - (0.05) .threshold_reject_gdop - if GDOP
is over this value, the observable is excluded (30.0) .threshold_reject_innovation - if innovation is over this value, the
observable is excluded (30.0) .number_filter_iter - number of iterations for the estimation filter (1) .bias_0 - (30.0)
.iono_0 - (0.03) .trop_0 - (0.3) .sigma_bias - process noise stddev of carrier-phase bias(ambiguity)(cycle/sqrt(s)) (1e-
4) .sigma_iono - process noise stddev of vertical ionospheric delay per 10km baseline (m/sqrt(s)) (1e-3) .sigma_↵
_trop - process noise stddev of zenith tropospheric delay (m/sqrt(s)) (1e-4) .sigma_acch - process noise stddev of
the receiver acceleration horizontal component (m/s2/sqrt(s)) (1e-1) .sigma_accv - process noise stddev of the re-
ceiver acceleration vertical component (m/s2/sqrt(s)) (1e-2) .sigma_pos - (0.0) .code_phase_error_ratio_l1 - (100.0)
.code_phase_error_ratio_l2 - (100.0) .code_phase_error_ratio_l5 - (100.0) .carrier_phase_error_factor_a - (0.003)
.carrier_phase_error_factor_b - (0.003)
.output_enabled - (true) .rinex_output_enabled - (.output_enabled) .gpx_output_enabled - (.output_enabled)
.geojson_output_enabled - (.output_enabled) .kml_output_enabled - (.output_enabled) .xml_output_enabled -
(.output_enabled) .nmea_output_enabled - (.output_enabled) .rtcm_output_enabled - (false)
.output_path - directory to which output files are written (".") .rinex_output_path - (.output_path) .gpx_output_↵
_path - (.output_path) .geojson_output_path - (.output_path) .kml_output_path - (.output_path) .xml_output_path -
(.output_path) .nmea_output_path - (.output_path) .rtcm_output_path - (.output_path)
.enable_monitor - enable the PVT monitor (false) .monitor_client_addresses - ("127.0.0.1") .monitor_udp_port - DO
NOT USE THE DEFAULT (1234) .enable_protobuf - serialize using protocol buffers (true). Monitor.enable_protobuf
if true, sets this to true
.enable_monitor_ephemeris - enable the ephemeris monitor (false) .monitor_ephemeris_client_addresses -
("127.0.0.1") .monitor_ephemeris_udp_port - DO NOT USE THE DEFAULT (1234)
.show_local_time_zone - (false) .enable_rx_clock_correction - (false) .max_clock_offset_ms - (40)
Definition at line 173 of file [rtklib_pvt.h](#).

12.357.2 Member Function Documentation

12.357.2.1 clear_ephemeris()

```
void Rtklib_Pvt::clear_ephemeris () [override], [virtual]
```

Implements [PvtInterface](#).

12.357.2.2 connect()

```
void Rtklib_Pvt::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.357.2.3 disconnect()

```
void Rtklib_Pvt::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.357.2.4 get_galileo_almanac()

```
std::map< int, Galileo_Almanac > Rtklib_Pvt::get_galileo_almanac () const [override], [virtual]
```

Implements [PvtInterface](#).

12.357.2.5 get_galileo_ephemeris()

```
std::map< int, Galileo_Ephemeris > Rtklib_Pvt::get_galileo_ephemeris () const [override],
[virtual]
```

Implements [PvtInterface](#).

12.357.2.6 get_gps_almanac()

```
std::map< int, Gps_Almanac > Rtklib_Pvt::get_gps_almanac () const [override], [virtual]
```

Implements [PvtInterface](#).

12.357.2.7 get_gps_ephemeris()

`std::map< int, Gps_Ephemeris > Rtklib_Pvt::get_gps_ephemeris () const` [override], [virtual]
 Implements [PvtInterface](#).

12.357.2.8 get_latest_PVT()

```
bool Rtklib_Pvt::get_latest_PVT (
    double * longitude_deg,
    double * latitude_deg,
    double * height_m,
    double * ground_speed_kmh,
    double * course_over_ground_deg,
    time_t * UTC_time) [override], [virtual]
```

Implements [PvtInterface](#).

12.357.2.9 get_left_block()

`gr::basic_block_sptr Rtklib_Pvt::get_left_block ()` [override], [virtual]
 Implements [GNSSBlockInterface](#).

12.357.2.10 get_right_block()

`gr::basic_block_sptr Rtklib_Pvt::get_right_block ()` [override], [virtual]
 Implements [GNSSBlockInterface](#).

12.357.2.11 implementation()

`std::string Rtklib_Pvt::implementation ()` [inline], [override], [virtual]
 Returns "RTKLIB_PVT".
 Implements [GNSSBlockInterface](#).
 Definition at line 189 of file [rtklib_pvt.h](#).

12.357.2.12 item_size()

`size_t Rtklib_Pvt::item_size ()` [inline], [override], [virtual]
 All blocks must have an [item_size\(\)](#) function implementation.
 Implements [GNSSBlockInterface](#).
 Definition at line 211 of file [rtklib_pvt.h](#).

12.357.2.13 reset()

`void Rtklib_Pvt::reset ()` [inline], [override], [virtual]
 Implements [PvtInterface](#).
 Definition at line 205 of file [rtklib_pvt.h](#).

12.357.2.14 role()

`std::string Rtklib_Pvt::role ()` [inline], [override], [virtual]
 Implements [GNSSBlockInterface](#).
 Definition at line 183 of file [rtklib_pvt.h](#).

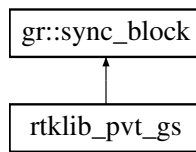
The documentation for this class was generated from the following file:

- [rtklib_pvt.h](#)

12.358 rtklib_pvt_gs Class Reference

This class implements a block that computes the PVT solution using the RTKLIB integrated library.
`#include <rtklib_pvt_gs.h>`

Inheritance diagram for rtklib_pvt_gs:



Public Member Functions

- [~rtklib_pvt_gs](#) ()
Default destructor.
- `std::map< int, Gps_Ephemeris > get_gps_ephemeris_map () const
Get latest set of GPS ephemeris from PVT block.`
- `std::map< int, Gps_Almanac > get_gps_almanac_map () const
Get latest set of GPS almanac from PVT block.`
- `std::map< int, Galileo_Ephemeris > get_galileo_ephemeris_map () const
Get latest set of Galileo ephemeris from PVT block.`
- `std::map< int, Galileo_Almanac > get_galileo_almanac_map () const
Get latest set of Galileo almanac from PVT block.`
- `std::map< int, Beidou_Dnav_Ephemeris > get_beidou_dnav_ephemeris_map () const
Get latest set of BeiDou DNAV ephemeris from PVT block.`
- `std::map< int, Beidou_Dnav_Almanac > get_beidou_dnav_almanac_map () const
Get latest set of BeiDou DNAV almanac from PVT block.`
- `void clear_ephemeris ()`
Clear all ephemeris information and the almanacs for GPS and Galileo.
- `bool get_latest_PVT (double *longitude_deg, double *latitude_deg, double *height_m, double *ground_speed_kmh, double *course_over_ground_deg, time_t *UTC_time) const`
Get the latest Position WGS84 [deg], Ground Velocity, Course over Ground, and UTC Time, if available.
- `int work (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)`
PVT Signal Processing.

Friends

- `rtklib_pvt_gs_sptr rtklib_make_pvt_gs (uint32_t nchannels, const Pvt_Conf &conf_, const rtk_t &rtk, const SensorDataSourceConfiguration &sensor_data_configuration)`

12.358.1 Detailed Description

This class implements a block that computes the PVT solution using the RTKLIB integrated library. Definition at line 85 of file [rtklib_pvt_gs.h](#).

12.358.2 Constructor & Destructor Documentation

12.358.2.1 ~rtklib_pvt_gs()

`rtklib_pvt_gs::~~rtklib_pvt_gs ()`
Default destructor.

12.358.3 Member Function Documentation

12.358.3.1 clear_ephemeris()

`void rtklib_pvt_gs::clear_ephemeris ()`
Clear all ephemeris information and the almanacs for GPS and Galileo.

12.358.3.2 get_beidou_dnav_almanac_map()

```
std::map< int, Beidou_Dnav_Almanac > rtklib_pvt_gs::get_beidou_dnav_almanac_map () const
```

Get latest set of BeiDou DNAV almanac from PVT block.

12.358.3.3 get_beidou_dnav_ephemeris_map()

```
std::map< int, Beidou_Dnav_Ephemeris > rtklib_pvt_gs::get_beidou_dnav_ephemeris_map () const
```

Get latest set of BeiDou DNAV ephemeris from PVT block.

12.358.3.4 get_galileo_almanac_map()

```
std::map< int, Galileo_Almanac > rtklib_pvt_gs::get_galileo_almanac_map () const
```

Get latest set of Galileo almanac from PVT block.

12.358.3.5 get_galileo_ephemeris_map()

```
std::map< int, Galileo_Ephemeris > rtklib_pvt_gs::get_galileo_ephemeris_map () const
```

Get latest set of Galileo ephemeris from PVT block.

12.358.3.6 get_gps_almanac_map()

```
std::map< int, Gps_Almanac > rtklib_pvt_gs::get_gps_almanac_map () const
```

Get latest set of GPS almanac from PVT block.

12.358.3.7 get_gps_ephemeris_map()

```
std::map< int, Gps_Ephemeris > rtklib_pvt_gs::get_gps_ephemeris_map () const
```

Get latest set of GPS ephemeris from PVT block.

12.358.3.8 get_latest_PVT()

```
bool rtklib_pvt_gs::get_latest_PVT (
    double * longitude_deg,
    double * latitude_deg,
    double * height_m,
    double * ground_speed_kmh,
    double * course_over_ground_deg,
    time_t * UTC_time) const
```

Get the latest Position WGS84 [deg], Ground Velocity, Course over Ground, and UTC Time, if available.

12.358.3.9 work()

```
int rtklib_pvt_gs::work (
    int noutput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items)
```

PVT Signal Processing.

The documentation for this class was generated from the following file:

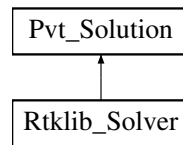
- [rtklib_pvt_gs.h](#)

12.359 Rtklib_Solver Class Reference

This class implements a PVT solution based on RTKLIB.

```
#include <rtklib_solver.h>
```

Inheritance diagram for Rtklib_Solver:



Public Member Functions

- **Rtklib_Solver** (const [rtk_t](#) &rtk, const [Pvt_Conf](#) &conf, const std::string &dump_filename, uint32_t signal_↔ enabled_flags, bool flag_dump_to_file, bool flag_dump_to_mat)
- bool **get_PVT** (const std::map< int, [Gnss_Synchro](#) > &gnss_observables_map, double kf_update_interval_↔ _s, const [SensorDataAggregator](#) &sensor_data_aggregator)
- double **get_hdop** () const override
- double **get_vdop** () const override
- double **get_pdop** () const override
- double **get_gdop** () const override
- [Monitor_Pvt](#) **get_monitor_pvt** () const
- void **store_has_data** (const [Galileo_HAS_data](#) &new_has_data)
- void **update_has_corrections** (const std::map< int, [Gnss_Synchro](#) > &obs_map)

Public Member Functions inherited from [Pvt_Solution](#)

- std::array< double, 3 > **get_rx_pos** () const
- std::array< double, 3 > **get_rx_vel** () const
- boost::posix_time::ptime **get_position_UTC_time** () const
- double **get_latitude** () const
Get RX position Latitude WGS84 [deg].
- double **get_longitude** () const
Get RX position Longitude WGS84 [deg].
- double **get_height** () const
Get RX position height WGS84 [m].
- double **get_time_offset_s** () const
Get RX time offset [s].
- double **get_clock_drift_ppm** () const
Get the Rx clock drift [ppm].
- double **get_speed_over_ground** () const
Get RX speed over ground [m/s].
- double **get_course_over_ground** () const
Get RX course over ground [deg].
- int **get_num_valid_observations** () const
Get the number of valid pseudorange observations (valid satellites)
- bool **is_pre_2009** () const
- bool **is_valid_position** () const
- void **set_rx_pos** (const std::array< double, 3 > &pos)
Set position: X, Y, Z in Cartesian ECEF coordinates [m].
- void **set_rx_vel** (const std::array< double, 3 > &vel)
Set velocity: East [m/s], North [m/s], Up [m/s].
- void **set_position_UTC_time** (const boost::posix_time::ptime &pt)
- void **set_time_offset_s** (double offset)
Set RX time offset [s].
- void **set_clock_drift_ppm** (double clock_drift_ppm)
Set the Rx clock drift [ppm].
- void **set_speed_over_ground** (double speed_m_s)

- *Set RX speed over ground [m/s].*
- void [set_course_over_ground](#) (double cog_deg)
- *Set RX course over ground [deg].*
- void [set_valid_position](#) (bool is_valid)
- void [set_num_valid_observations](#) (int num)
- *Set the number of valid pseudorange observations (valid satellites)*
- void [set_pre_2009_file](#) (bool pre_2009_file)
- *Flag for the week rollover computation in post processing mode for signals older than 2009.*

Public Attributes

- [sol_t pvt_sol](#) {}
- std::array< [ssat_t](#), MAXSAT > [pvt_ssat](#) {}
- std::map< int, [Galileo_Ephemeris](#) > [galileo_ephemeris_map](#)
- *Map storing new [Galileo_Ephemeris](#).*
- std::map< int, [Gps_Ephemeris](#) > [gps_ephemeris_map](#)
- *Map storing new [GPS_Ephemeris](#).*
- std::map< int, [Gps_CNAV_Ephemeris](#) > [gps_cnav_ephemeris_map](#)
- *Map storing new [GPS_CNAV_Ephemeris](#).*
- std::map< int, [Glonass_Gnav_Ephemeris](#) > [glonass_gnav_ephemeris_map](#)
- *Map storing new [GLONASS GNAV Ephemeris](#).*
- std::map< int, [Beidou_Dnav_Ephemeris](#) > [beidou_dnav_ephemeris_map](#)
- *Map storing new [BeiDou DNAV Ephemeris](#).*
- [Galileo_Utc_Model](#) [galileo_utc_model](#)
- [Galileo_Iono](#) [galileo_iono](#)
- std::map< int, [Galileo_Almanac](#) > [galileo_almanac_map](#)
- [Gps_Utc_Model](#) [gps_utc_model](#)
- [Gps_Iono](#) [gps_iono](#)
- std::map< int, [Gps_Almanac](#) > [gps_almanac_map](#)
- [Gps_CNAV_Iono](#) [gps_cnav_iono](#)
- [Gps_CNAV_Utc_Model](#) [gps_cnav_utc_model](#)
- [Glonass_Gnav_Utc_Model](#) [glonass_gnav_utc_model](#)
- *Map storing [GLONASS GNAV UTC Model](#).*
- [Glonass_Gnav_Almanac](#) [glonass_gnav_almanac](#)
- *Map storing [GLONASS GNAV Almanac Model](#).*
- [Beidou_Dnav_Utc_Model](#) [beidou_dnav_utc_model](#)
- [Beidou_Dnav_Iono](#) [beidou_dnav_iono](#)
- std::map< int, [Beidou_Dnav_Almanac](#) > [beidou_dnav_almanac_map](#)

12.359.1 Detailed Description

This class implements a PVT solution based on RTKLIB.
Definition at line 82 of file [rtklib_solver.h](#).

12.359.2 Member Function Documentation

12.359.2.1 [get_gdop\(\)](#)

double [Rtklib_Solver::get_gdop](#) () const [override], [virtual]
Implements [Pvt_Solution](#).

12.359.2.2 [get_hdop\(\)](#)

double [Rtklib_Solver::get_hdop](#) () const [override], [virtual]
Implements [Pvt_Solution](#).

12.359.2.3 get_pdop()

double Rtklib_Solver::get_pdop () const [override], [virtual]
Implements [Pvt_Solution](#).

12.359.2.4 get_vdop()

double Rtklib_Solver::get_vdop () const [override], [virtual]
Implements [Pvt_Solution](#).

12.359.3 Member Data Documentation

12.359.3.1 beidou_dnav_almanac_map

std::map<int, [Beidou_Dnav_Almanac](#)> Rtklib_Solver::beidou_dnav_almanac_map
Definition at line 129 of file [rtklib_solver.h](#).

12.359.3.2 beidou_dnav_ephemeris_map

std::map<int, [Beidou_Dnav_Ephemeris](#)> Rtklib_Solver::beidou_dnav_ephemeris_map
Map storing new BeiDou DNAV Ephemeris.
Definition at line 111 of file [rtklib_solver.h](#).

12.359.3.3 beidou_dnav_iono

[Beidou_Dnav_Iono](#) Rtklib_Solver::beidou_dnav_iono
Definition at line 128 of file [rtklib_solver.h](#).

12.359.3.4 beidou_dnav_utc_model

[Beidou_Dnav_Utc_Model](#) Rtklib_Solver::beidou_dnav_utc_model
Definition at line 127 of file [rtklib_solver.h](#).

12.359.3.5 galileo_almanac_map

std::map<int, [Galileo_Almanac](#)> Rtklib_Solver::galileo_almanac_map
Definition at line 115 of file [rtklib_solver.h](#).

12.359.3.6 galileo_ephemeris_map

std::map<int, [Galileo_Ephemeris](#)> Rtklib_Solver::galileo_ephemeris_map
Map storing new [Galileo_Ephemeris](#).
Definition at line 107 of file [rtklib_solver.h](#).

12.359.3.7 galileo_iono

[Galileo_Iono](#) Rtklib_Solver::galileo_iono
Definition at line 114 of file [rtklib_solver.h](#).

12.359.3.8 galileo_utc_model

[Galileo_Utc_Model](#) Rtklib_Solver::galileo_utc_model
Definition at line 113 of file [rtklib_solver.h](#).

12.359.3.9 glonass_gnav_almanac

[Glonass_Gnav_Almanac](#) Rtklib_Solver::glonass_gnav_almanac
Map storing GLONASS GNAV Almanac Model.
Definition at line 125 of file [rtklib_solver.h](#).

12.359.3.10 glonass_gnav_ephemeris_map

`std::map<int, Glonass_Gnav_Ephemeris> Rtklib_Solver::glonass_gnav_ephemeris_map`

Map storing new GLONASS GNAV Ephemeris.

Definition at line 110 of file [rtklib_solver.h](#).

12.359.3.11 glonass_gnav_utc_model

`Glonass_Gnav_Utc_Model Rtklib_Solver::glonass_gnav_utc_model`

Map storing GLONASS GNAV UTC Model.

Definition at line 124 of file [rtklib_solver.h](#).

12.359.3.12 gps_almanac_map

`std::map<int, Gps_Almanac> Rtklib_Solver::gps_almanac_map`

Definition at line 119 of file [rtklib_solver.h](#).

12.359.3.13 gps_cnav_ephemeris_map

`std::map<int, Gps_CNAV_Ephemeris> Rtklib_Solver::gps_cnav_ephemeris_map`

Map storing new GPS_CNAV_Ephemeris.

Definition at line 109 of file [rtklib_solver.h](#).

12.359.3.14 gps_cnav_iono

`Gps_CNAV_Iono Rtklib_Solver::gps_cnav_iono`

Definition at line 121 of file [rtklib_solver.h](#).

12.359.3.15 gps_cnav_utc_model

`Gps_CNAV_Utc_Model Rtklib_Solver::gps_cnav_utc_model`

Definition at line 122 of file [rtklib_solver.h](#).

12.359.3.16 gps_ephemeris_map

`std::map<int, Gps_Ephemeris> Rtklib_Solver::gps_ephemeris_map`

Map storing new GPS_Ephemeris.

Definition at line 108 of file [rtklib_solver.h](#).

12.359.3.17 gps_iono

`Gps_Iono Rtklib_Solver::gps_iono`

Definition at line 118 of file [rtklib_solver.h](#).

12.359.3.18 gps_utc_model

`Gps_Utc_Model Rtklib_Solver::gps_utc_model`

Definition at line 117 of file [rtklib_solver.h](#).

12.359.3.19 pvt_sol

`sol_t Rtklib_Solver::pvt_sol {}`

Definition at line 104 of file [rtklib_solver.h](#).

12.359.3.20 pvt_ssatt

`std::array<ssatt_t, MAXSAT> Rtklib_Solver::pvt_ssatt {}`

Definition at line 105 of file [rtklib_solver.h](#).

The documentation for this class was generated from the following file:

- [rtklib_solver.h](#)

12.360 rtksvr_t Struct Reference

Public Attributes

- int [state](#)
- int [cycle](#)
- int [nmeacycle](#)
- int [nmeareq](#)
- double [nmeapos](#) [3]
- int [buffsize](#)
- int [format](#) [3]
- [solopt_t](#) [solopt](#) [2]
- int [navsel](#)
- int [nsbs](#)
- int [nsol](#)
- [rtk_t](#) [rtk](#)
- int [nb](#) [3]
- int [nsb](#) [2]
- int [npb](#) [3]
- unsigned char * [buff](#) [3]
- unsigned char * [sbuf](#) [2]
- unsigned char * [pbuf](#) [3]
- [sol_t](#) [solbuf](#) [MAXSOLBUF]
- unsigned int [nmsg](#) [3][10]
- [raw_t](#) [raw](#) [3]
- [rtcm_t](#) [rtcm](#) [3]
- [gtime_t](#) [ftime](#) [3]
- char [files](#) [3][MAXSTRPATH]
- [obs_t](#) [obs](#) [3][MAXOBSBUF]
- [nav_t](#) [nav](#)
- [sbsmsg_t](#) [sbsmsg](#) [MAXSBSMSG]
- [stream_t](#) [stream](#) [8]
- [stream_t](#) * [moni](#)
- unsigned int [tick](#)
- [pthread_t](#) [thread](#)
- int [cputime](#)
- int [prcout](#)
- [lock_t](#) [lock](#)

12.360.1 Detailed Description

Definition at line [1239](#) of file [rtklib.h](#).

12.360.2 Member Data Documentation

12.360.2.1 buff

```
unsigned char* rtksvr_t::buff[3]
```

Definition at line [1256](#) of file [rtklib.h](#).

12.360.2.2 buffsize

```
int rtksvr_t::buffsize
```

Definition at line [1246](#) of file [rtklib.h](#).

12.360.2.3 cputime

```
int rtksvr_t::cputime
```

Definition at line 1272 of file [rtklib.h](#).

12.360.2.4 cycle

```
int rtksvr_t::cycle
```

Definition at line 1242 of file [rtklib.h](#).

12.360.2.5 files

```
char rtksvr_t::files[3][MAXSTRPATH]
```

Definition at line 1264 of file [rtklib.h](#).

12.360.2.6 format

```
int rtksvr_t::format[3]
```

Definition at line 1247 of file [rtklib.h](#).

12.360.2.7 ftime

```
gtime_t rtksvr_t::ftime[3]
```

Definition at line 1263 of file [rtklib.h](#).

12.360.2.8 lock

```
lock_t rtksvr_t::lock
```

Definition at line 1274 of file [rtklib.h](#).

12.360.2.9 moni

```
stream_t* rtksvr_t::moni
```

Definition at line 1269 of file [rtklib.h](#).

12.360.2.10 nav

```
nav_t rtksvr_t::nav
```

Definition at line 1266 of file [rtklib.h](#).

12.360.2.11 navsel

```
int rtksvr_t::navsel
```

Definition at line 1249 of file [rtklib.h](#).

12.360.2.12 nb

```
int rtksvr_t::nb[3]
```

Definition at line 1253 of file [rtklib.h](#).

12.360.2.13 nmeacycle

```
int rtksvr_t::nmeacycle
```

Definition at line 1243 of file [rtklib.h](#).

12.360.2.14 nmeapos

```
double rtksvr_t::nmeapos[3]
```

Definition at line 1245 of file [rtklib.h](#).

12.360.2.15 nmeareq

```
int rtksvr_t::nmeareq
```

Definition at line 1244 of file [rtklib.h](#).

12.360.2.16 nmsg

```
unsigned int rtksvr_t::nmsg[3][10]
```

Definition at line 1260 of file [rtklib.h](#).

12.360.2.17 npb

```
int rtksvr_t::npb[3]
```

Definition at line 1255 of file [rtklib.h](#).

12.360.2.18 nsb

```
int rtksvr_t::nsb[2]
```

Definition at line 1254 of file [rtklib.h](#).

12.360.2.19 nsbs

```
int rtksvr_t::nsbs
```

Definition at line 1250 of file [rtklib.h](#).

12.360.2.20 nsol

```
int rtksvr_t::nsol
```

Definition at line 1251 of file [rtklib.h](#).

12.360.2.21 obs

```
obs_t rtksvr_t::obs[3][MAXOBSBUF]
```

Definition at line 1265 of file [rtklib.h](#).

12.360.2.22 pbuf

```
unsigned char* rtksvr_t::pbuf[3]
```

Definition at line 1258 of file [rtklib.h](#).

12.360.2.23 prcout

```
int rtksvr_t::prcout
```

Definition at line 1273 of file [rtklib.h](#).

12.360.2.24 raw

```
raw_t rtksvr_t::raw[3]
```

Definition at line 1261 of file [rtklib.h](#).

12.360.2.25 rtcm

```
rtcm_t rtksvr_t::rtcm[3]
```

Definition at line 1262 of file [rtklib.h](#).

12.360.2.26 rtk

```
rtk_t rtksvr_t::rtk
```

Definition at line 1252 of file [rtklib.h](#).

12.360.2.27 sbsmsg

`sbsmsg_t rtksvr_t::sbsmsg[MAXSBSMSG]`
 Definition at line 1267 of file [rtklib.h](#).

12.360.2.28 sbuf

`unsigned char* rtksvr_t::sbuf[2]`
 Definition at line 1257 of file [rtklib.h](#).

12.360.2.29 solbuf

`sol_t rtksvr_t::solbuf[MAXSOLBUF]`
 Definition at line 1259 of file [rtklib.h](#).

12.360.2.30 solopt

`solopt_t rtksvr_t::solut[2]`
 Definition at line 1248 of file [rtklib.h](#).

12.360.2.31 state

`int rtksvr_t::state`
 Definition at line 1241 of file [rtklib.h](#).

12.360.2.32 stream

`stream_t rtksvr_t::stream[8]`
 Definition at line 1268 of file [rtklib.h](#).

12.360.2.33 thread

`pthread_t rtksvr_t::thread`
 Definition at line 1271 of file [rtklib.h](#).

12.360.2.34 tick

`unsigned int rtksvr_t::tick`
 Definition at line 1270 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.361 Rtl_Tcp_Dongle_Info Class Reference

This class represents the dongle information which is sent by rtl_tcp.

`#include <rtl_tcp_dongle_info.h>`

Public Types

- enum {
 TUNER_UNKNOWN = 0 , **TUNER_E4000** , **TUNER_FC0012** , **TUNER_FC0013** ,
 TUNER_FC2580 , **TUNER_R820T** , **TUNER_R828D** }

Public Member Functions

- `boost::system::error_code read (boost::asio::ip::tcp::socket &socket)`
- `bool is_valid () const`
- `const char * get_type_name () const`

- double **clip_gain** (int gain) const
- uint32_t **get_tuner_type** () const
- uint32_t **get_tuner_gain_count** () const

12.361.1 Detailed Description

This class represents the dongle information which is sent by rtl_tcp.

Definition at line 35 of file [rtl_tcp_dongle_info.h](#).

12.361.2 Member Enumeration Documentation

12.361.2.1 anonymous enum

anonymous enum

Definition at line 38 of file [rtl_tcp_dongle_info.h](#).

12.361.3 Member Function Documentation

12.361.3.1 get_tuner_gain_count()

```
uint32_t Rtl_Tcp_Dongle_Info::get_tuner_gain_count () const [inline]
```

Definition at line 64 of file [rtl_tcp_dongle_info.h](#).

12.361.3.2 get_tuner_type()

```
uint32_t Rtl_Tcp_Dongle_Info::get_tuner_type () const [inline]
```

Definition at line 59 of file [rtl_tcp_dongle_info.h](#).

The documentation for this class was generated from the following file:

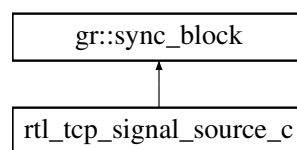
- [rtl_tcp_dongle_info.h](#)

12.362 rtl_tcp_signal_source_c Class Reference

This class reads interleaved I/Q samples from an rtl_tcp server and outputs complex types.

```
#include <rtl_tcp_signal_source_c.h>
```

Inheritance diagram for rtl_tcp_signal_source_c:



Public Member Functions

- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)
- void **set_frequency** (int frequency)
- void **set_sample_rate** (int sample_rate)
- void **set_agc_mode** (bool agc)
- void **set_gain** (int gain)
- void **set_if_gain** (int gain)

Friends

- rtl_tcp_signal_source_c_sptr **rtl_tcp_make_signal_source_c** (const std::string &address, int16_t port, bool flip_iq=false)

12.362.1 Detailed Description

This class reads interleaved I/Q samples from an rtl_tcp server and outputs complex types.

Definition at line 65 of file [rtl_tcp_signal_source_c.h](#).

The documentation for this class was generated from the following file:

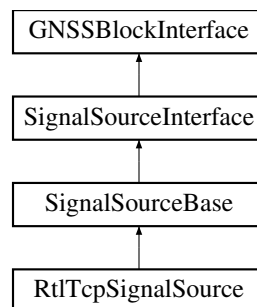
- [rtl_tcp_signal_source_c.h](#)

12.363 RtlTcpSignalSource Class Reference

This class reads from rtl_tcp, which streams interleaved I/Q samples over TCP. (see <https://osmocom.org/projects/rtl-sdr/wiki>)

```
#include <rtl_tcp_signal_source.h>
```

Inheritance diagram for RtlTcpSignalSource:



Public Member Functions

- **RtlTcpSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)

Constructor.

- `size_t decode_item_type` (`std::string const &item_type`, `bool *is_interleaved=nullptr`, `bool throw_on_error=false`)

utility for decoding passed ".item_type" values

12.363.1 Detailed Description

This class reads from `rtl_tcp`, which streams interleaved I/Q samples over TCP. (see <https://osmocom.org/projects/rtl-sdr/wiki>)

Definition at line 45 of file `rtl_tcp_signal_source.h`.

12.363.2 Member Function Documentation

12.363.2.1 connect()

```
void RtlTcpSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.363.2.2 disconnect()

```
void RtlTcpSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.363.2.3 get_left_block()

```
gr::basic_block_sptr RtlTcpSignalSource::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.363.2.4 get_right_block()

```
gr::basic_block_sptr RtlTcpSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.363.2.5 item_size()

```
size_t RtlTcpSignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 56 of file `rtl_tcp_signal_source.h`.

The documentation for this class was generated from the following file:

- [rtl_tcp_signal_source.h](#)

12.364 Sbas_Ephemeris Class Reference

This class stores SBAS SV ephemeris data.

```
#include <sbas_ephemeris.h>
```

Public Member Functions

- `void print` (`std::ostream &out`)

Public Attributes

- `int i_prn` {}
PRN number.
- `int i_t0` {}
Reference epoch time (GPST)

- double `d_tof` {}
Time of message frame (GPST)
- int `i_sv_ura` {}
SV accuracy (URA index), not standardized.
- bool `b_sv_do_not_use` {}
Health status (false:do not use / true:usable)
- double `d_pos` [3] {}
Satellite position (m) (ECEF)
- double `d_vel` [3] {}
Satellite velocity (m/s) (ECEF)
- double `d_acc` [3] {}
Satellite acceleration (m/s²) (ECEF)
- double `d_af0` {}
Satellite clock-offset (s)
- double `d_af1` {}
Satellite drift (s/s)

12.364.1 Detailed Description

This class stores SBAS SV ephemeris data.
Definition at line 33 of file [sbas_ephemeris.h](#).

12.364.2 Member Data Documentation

12.364.2.1 `b_sv_do_not_use`

```
bool Sbas_Ephemeris::b_sv_do_not_use {}
```

Health status (false:do not use / true:usable)
Definition at line 42 of file [sbas_ephemeris.h](#).

12.364.2.2 `d_acc`

```
double Sbas_Ephemeris::d_acc[3] {}
```

Satellite acceleration (m/s²) (ECEF)
Definition at line 45 of file [sbas_ephemeris.h](#).

12.364.2.3 `d_af0`

```
double Sbas_Ephemeris::d_af0 {}
```

Satellite clock-offset (s)
Definition at line 46 of file [sbas_ephemeris.h](#).

12.364.2.4 `d_af1`

```
double Sbas_Ephemeris::d_af1 {}
```

Satellite drift (s/s)
Definition at line 47 of file [sbas_ephemeris.h](#).

12.364.2.5 `d_pos`

```
double Sbas_Ephemeris::d_pos[3] {}
```

Satellite position (m) (ECEF)
Definition at line 43 of file [sbas_ephemeris.h](#).

12.364.2.6 d_tof

```
double Sbas_Ephemeris::d_tof {}
```

Time of message frame (GPST)

Definition at line 40 of file [sbas_ephemeris.h](#).

12.364.2.7 d_vel

```
double Sbas_Ephemeris::d_vel[3] {}
```

Satellite velocity (m/s) (ECEF)

Definition at line 44 of file [sbas_ephemeris.h](#).

12.364.2.8 i_prn

```
int Sbas_Ephemeris::i_prn {}
```

PRN number.

Definition at line 38 of file [sbas_ephemeris.h](#).

12.364.2.9 i_sv_ura

```
int Sbas_Ephemeris::i_sv_ura {}
```

SV accuracy (URA index), not standardized.

Definition at line 41 of file [sbas_ephemeris.h](#).

12.364.2.10 i_t0

```
int Sbas_Ephemeris::i_t0 {}
```

Reference epoch time (GPST)

Definition at line 39 of file [sbas_ephemeris.h](#).

The documentation for this class was generated from the following file:

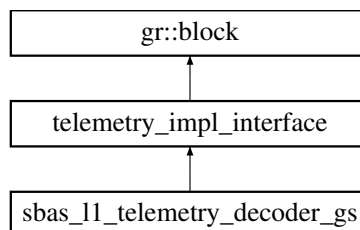
- [sbas_ephemeris.h](#)

12.365 sbas_l1_telemetry_decoder_gs Class Reference

This class implements a block that decodes the SBAS integrity and corrections data defined in RTCA MOPS DO-229.

```
#include <sbas_l1_telemetry_decoder_gs.h>
```

Inheritance diagram for `sbas_l1_telemetry_decoder_gs`:

**Public Member Functions**

- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
Set satellite PRN.
- void [set_channel](#) (int32_t channel) override
Set receiver's channel.
- void [reset](#) () override
- int [general_work](#) (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override
This is where all signal processing takes place.

Public Member Functions inherited from [telemetry_impl_interface](#)

- [telemetry_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_channel](#) (int channel)=0

Friends

- sbas_l1_telemetry_decoder_gs_sptr [sbas_l1_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, bool dump)

Additional Inherited Members

Protected Member Functions inherited from [telemetry_impl_interface](#)

- void [configure_basic_outputs](#) ()
- void [configure_dump_file](#) (int32_t channel, bool enable_dump, std::string &dump_filename, std::ofstream &dump_file) const
- void [configure_crc_stats_channel](#) (int32_t channel, bool &dump_crc_stats, std::unique_ptr< [Tlm_CRC_Stats](#) > &crc_stats) const

12.365.1 Detailed Description

This class implements a block that decodes the SBAS integrity and corrections data defined in RTCA MOPS DO-229.

Definition at line 47 of file [sbas_l1_telemetry_decoder_gs.h](#).

12.365.2 Member Function Documentation

12.365.2.1 [general_work\(\)](#)

```
int sbas_l1_telemetry_decoder_gs::general_work (
    int noutput_items,
    gr_vector_int & ninput_items,
    gr_vector_const_void_star & input_items,
    gr_vector_void_star & output_items) [override]
```

This is where all signal processing takes place.

12.365.2.2 [reset\(\)](#)

```
void sbas_l1_telemetry_decoder_gs::reset () [inline], [override], [virtual]
```

Implements [telemetry_impl_interface](#).

Definition at line 53 of file [sbas_l1_telemetry_decoder_gs.h](#).

12.365.2.3 [set_channel\(\)](#)

```
void sbas_l1_telemetry_decoder_gs::set_channel (
    int32_t channel) [override]
```

Set receiver's channel.

12.365.2.4 [set_satellite\(\)](#)

```
void sbas_l1_telemetry_decoder_gs::set_satellite (
    const Gnss\_Satellite & satellite) [override], [virtual]
```

Set satellite PRN.

Implements [telemetry_impl_interface](#).

The documentation for this class was generated from the following file:

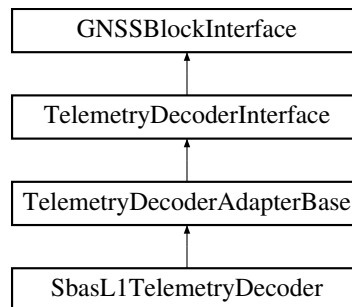
- [sbas_l1_telemetry_decoder_gs.h](#)

12.366 SbasL1TelemetryDecoder Class Reference

This class implements a NAV data decoder for SBAS frames in L1 radio link.

```
#include <sbas_l1_telemetry_decoder.h>
```

Inheritance diagram for SbasL1TelemetryDecoder:



Public Member Functions

- **SbasL1TelemetryDecoder** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- std::string [implementation](#) () override
Returns "SBAS_L1_Telemetry_Decoder".

Public Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [TelemetryDecoderAdapterBase](#)

- void **InitializeDecoder** (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & **satellite** () const

Protected Attributes inherited from [TelemetryDecoderAdapterBase](#)

- [Tlm_Conf](#) tlm_parameters_

12.366.1 Detailed Description

This class implements a NAV data decoder for SBAS frames in L1 radio link.
Definition at line 35 of file [sbas_l1_telemetry_decoder.h](#).

12.366.2 Member Function Documentation

12.366.2.1 implementation()

```
std::string SbasL1TelemetryDecoder::implementation () [inline], [override], [virtual]
```

Returns "SBAS_L1_Telemetry_Decoder".

Implements [GNSSBlockInterface](#).

Definition at line 47 of file [sbas_l1_telemetry_decoder.h](#).

The documentation for this class was generated from the following file:

- [sbas_l1_telemetry_decoder.h](#)

12.367 sbs_t Struct Reference

Public Attributes

- int [n](#)
- int [nmax](#)
- [sbsmsg_t](#) * [msgs](#)

12.367.1 Detailed Description

Definition at line 574 of file [rtklib.h](#).

12.367.2 Member Data Documentation

12.367.2.1 msgs

```
sbsmsg\_t* sbs_t::msgs
```

Definition at line 577 of file [rtklib.h](#).

12.367.2.2 n

```
int sbs_t::n
```

Definition at line 576 of file [rtklib.h](#).

12.367.2.3 nmax

```
int sbs_t::nmax
```

Definition at line 576 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.368 sbsfcrr_t Struct Reference

Public Attributes

- [gtime_t](#) [t0](#)
- double [prc](#)
- double [rrc](#)
- double [dt](#)
- int [iodf](#)
- short [udre](#)
- short [ai](#)

12.368.1 Detailed Description

Definition at line 581 of file [rtklib.h](#).

12.368.2 Member Data Documentation

12.368.2.1 ai

```
short sbsfcorr_t::ai
```

Definition at line 589 of file [rtklib.h](#).

12.368.2.2 dt

```
double sbsfcorr_t::dt
```

Definition at line 586 of file [rtklib.h](#).

12.368.2.3 iodf

```
int sbsfcorr_t::iodf
```

Definition at line 587 of file [rtklib.h](#).

12.368.2.4 prc

```
double sbsfcorr_t::prc
```

Definition at line 584 of file [rtklib.h](#).

12.368.2.5 rrc

```
double sbsfcorr_t::rrc
```

Definition at line 585 of file [rtklib.h](#).

12.368.2.6 t0

```
gtime_t sbsfcorr_t::t0
```

Definition at line 583 of file [rtklib.h](#).

12.368.2.7 udre

```
short sbsfcorr_t::udre
```

Definition at line 588 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.369 sbsign_t Struct Reference

Public Attributes

- [gtime_t](#) t0
- short [lat](#)
- short [lon](#)
- short [give](#)
- float [delay](#)

12.369.1 Detailed Description

Definition at line 620 of file [rtklib.h](#).

12.369.2 Member Data Documentation

12.369.2.1 delay

`float sbsigp_t::delay`

Definition at line 625 of file [rtklib.h](#).

12.369.2.2 give

`short sbsigp_t::give`

Definition at line 624 of file [rtklib.h](#).

12.369.2.3 lat

`short sbsigp_t::lat`

Definition at line 623 of file [rtklib.h](#).

12.369.2.4 lon

`short sbsigp_t::lon`

Definition at line 623 of file [rtklib.h](#).

12.369.2.5 t0

`gtime_t sbsigp_t::t0`

Definition at line 622 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.370 sbsigpband_t Struct Reference

Public Attributes

- short [x](#)
- const short * [y](#)
- unsigned char [bits](#)
- unsigned char [bite](#)

12.370.1 Detailed Description

Definition at line 629 of file [rtklib.h](#).

12.370.2 Member Data Documentation

12.370.2.1 bite

`unsigned char sbsigpband_t::bite`

Definition at line 634 of file [rtklib.h](#).

12.370.2.2 bits

`unsigned char sbsigpband_t::bits`

Definition at line 633 of file [rtklib.h](#).

12.370.2.3 x

`short sbsigpband_t::x`

Definition at line 631 of file [rtklib.h](#).

12.370.2.4 y

```
const short* sbsigpband_t::y
```

Definition at line 632 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.371 sbsion_t Struct Reference

Public Attributes

- int [iodi](#)
- int [nigp](#)
- [sbsigp_t igp](#) [MAXNIGP]

12.371.1 Detailed Description

Definition at line 638 of file [rtklib.h](#).

12.371.2 Member Data Documentation

12.371.2.1 igp

```
sbsigp_t sbsion_t::igp [MAXNIGP]
```

Definition at line 642 of file [rtklib.h](#).

12.371.2.2 iodi

```
int sbsion_t::iodi
```

Definition at line 640 of file [rtklib.h](#).

12.371.2.3 nigp

```
int sbsion_t::nigp
```

Definition at line 641 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.372 sbslcorr_t Struct Reference

Public Attributes

- [gtime_t t0](#)
- int [iode](#)
- double [dpos](#) [3]
- double [dvel](#) [3]
- double [daf0](#)
- double [daf1](#)

12.372.1 Detailed Description

Definition at line 593 of file [rtklib.h](#).

12.372.2 Member Data Documentation

12.372.2.1 daf0

```
double sbslcorr_t::daf0
```

Definition at line 599 of file [rtklib.h](#).

12.372.2.2 daf1

```
double sbslcorr_t::daf1
```

Definition at line 599 of file [rtklib.h](#).

12.372.2.3 dpos

```
double sbslcorr_t::dpos[3]
```

Definition at line 597 of file [rtklib.h](#).

12.372.2.4 dvel

```
double sbslcorr_t::dvel[3]
```

Definition at line 598 of file [rtklib.h](#).

12.372.2.5 iode

```
int sbslcorr_t::iode
```

Definition at line 596 of file [rtklib.h](#).

12.372.2.6 t0

```
ptime_t sbslcorr_t::t0
```

Definition at line 595 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.373 sbsmsg_t Struct Reference

Public Attributes

- int [week](#)
- int [tow](#)
- int [prn](#)
- unsigned char [msg](#) [29]

12.373.1 Detailed Description

Definition at line 566 of file [rtklib.h](#).

12.373.2 Member Data Documentation

12.373.2.1 msg

```
unsigned char sbsmsg_t::msg[29]
```

Definition at line 570 of file [rtklib.h](#).

12.373.2.2 prn

```
int sbsmsg_t::prn
```

Definition at line 569 of file [rtklib.h](#).

12.373.2.3 tow

```
int sbsmsg_t::tow
```

Definition at line 568 of file [rtklib.h](#).

12.373.2.4 week

```
int sbmsg_t::week
```

Definition at line 568 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.374 sbssat_t Struct Reference

Public Attributes

- int [iodp](#)
- int [nsat](#)
- int [tlat](#)
- [sbssatp_t](#) [sat](#) [MAXSAT]

12.374.1 Detailed Description

Definition at line 611 of file [rtklib.h](#).

12.374.2 Member Data Documentation

12.374.2.1 iodp

```
int sbssat_t::iodp
```

Definition at line 613 of file [rtklib.h](#).

12.374.2.2 nsat

```
int sbssat_t::nsat
```

Definition at line 614 of file [rtklib.h](#).

12.374.2.3 sat

```
sbssatp\_t sbssat_t::sat [MAXSAT]
```

Definition at line 616 of file [rtklib.h](#).

12.374.2.4 tlat

```
int sbssat_t::tlat
```

Definition at line 615 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.375 sbssatp_t Struct Reference

Public Attributes

- int [sat](#)
- [sbsfcrr_t](#) [fcorr](#)
- [sbslcorr_t](#) [lcorr](#)

12.375.1 Detailed Description

Definition at line 603 of file [rtklib.h](#).

12.375.2 Member Data Documentation

12.375.2.1 fcorr

`sbsfcorr_t sbssatp_t::fcorr`

Definition at line 606 of file [rtklib.h](#).

12.375.2.2 lcorr

`sbslcorr_t sbssatp_t::lcorr`

Definition at line 607 of file [rtklib.h](#).

12.375.2.3 sat

`int sbssatp_t::sat`

Definition at line 605 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.376 sdr_gnss_packet_t Struct Reference

Public Attributes

- `uint8_t` [nsvfix](#)
- `uint8_t` [gps_satellites](#)
- `uint8_t` [galileo_satellites](#)
- `uint32_t` [microseconds](#)
- `double` [latitude](#)
- `double` [longitude](#)
- `double` [height](#)
- `float` [velocity](#) [3]
- `struct` {
 - `uint8_t` [prn](#)
 - `uint8_t` [snr](#)
 - `int16_t` [doppler](#)
- `sats` [16]
- `uint32_t` [reserved](#)
- `uint16_t` [status](#)

12.376.1 Detailed Description

Definition at line 39 of file [an_packet_printer.h](#).

12.376.2 Member Data Documentation

12.376.2.1 doppler

`int16_t sdr_gnss_packet_t::doppler`

Definition at line 54 of file [an_packet_printer.h](#).

12.376.2.2 galileo_satellites

`uint8_t sdr_gnss_packet_t::galileo_satellites`

Definition at line 43 of file [an_packet_printer.h](#).

12.376.2.3 gps_satellites

uint8_t sdr_gnss_packet_t::gps_satellites
Definition at line 42 of file [an_packet_printer.h](#).

12.376.2.4 height

double sdr_gnss_packet_t::height
Definition at line 47 of file [an_packet_printer.h](#).

12.376.2.5 latitude

double sdr_gnss_packet_t::latitude
Definition at line 45 of file [an_packet_printer.h](#).

12.376.2.6 longitude

double sdr_gnss_packet_t::longitude
Definition at line 46 of file [an_packet_printer.h](#).

12.376.2.7 microseconds

uint32_t sdr_gnss_packet_t::microseconds
Definition at line 44 of file [an_packet_printer.h](#).

12.376.2.8 nsuffix

uint8_t sdr_gnss_packet_t::nsuffix
Definition at line 41 of file [an_packet_printer.h](#).

12.376.2.9 prn

uint8_t sdr_gnss_packet_t::prn
Definition at line 52 of file [an_packet_printer.h](#).

12.376.2.10 reserved

uint32_t sdr_gnss_packet_t::reserved
Definition at line 57 of file [an_packet_printer.h](#).

12.376.2.11 snr

uint8_t sdr_gnss_packet_t::snr
Definition at line 53 of file [an_packet_printer.h](#).

12.376.2.12 status

uint16_t sdr_gnss_packet_t::status
Definition at line 58 of file [an_packet_printer.h](#).

12.376.2.13 velocity

float sdr_gnss_packet_t::velocity[3]
Definition at line 48 of file [an_packet_printer.h](#).

The documentation for this struct was generated from the following file:

- [an_packet_printer.h](#)

12.377 SensorDataAggregator Class Reference

Public Member Functions

- **SensorDataAggregator** (const [SensorDataSourceConfiguration](#) &configuration, const std::vector< [SensorIdentifier::value_type](#) > &required_sensors)
- void **update** (const std::vector< [gr::tag_t](#) > &tags)
- const std::vector< [SensorDataSample](#)< float > > & **get_f32** ([SensorIdentifier::value_type](#) sensor_id) const
- [SensorDataSample](#)< float > **get_last_f32** ([SensorIdentifier::value_type](#) sensor_id) const
- [SensorDataSample](#)< float > **get_average_f32** ([SensorIdentifier::value_type](#) sensor_id) const
- const std::vector< [SensorDataSample](#)< double > > & **get_f64** ([SensorIdentifier::value_type](#) sensor_id) const
- [SensorDataSample](#)< double > **get_last_f64** ([SensorIdentifier::value_type](#) sensor_id) const
- [SensorDataSample](#)< double > **get_average_f64** ([SensorIdentifier::value_type](#) sensor_id) const

Public Attributes

- const pmt::pmt_t [SENSOR_DATA_TAG](#) = pmt::mp("sensor_data")

12.377.1 Detailed Description

Definition at line 45 of file [sensor_data_aggregator.h](#).

12.377.2 Member Data Documentation

12.377.2.1 SENSOR_DATA_TAG

```
const pmt::pmt_t SensorDataAggregator::SENSOR_DATA_TAG = pmt::mp("sensor_data")
```

Definition at line 48 of file [sensor_data_aggregator.h](#).

The documentation for this class was generated from the following file:

- [sensor_data_aggregator.h](#)

12.378 SensorDataConfiguration Struct Reference

Public Attributes

- uint64_t [id](#)
- uint64_t [file_id](#)
- uint64_t [offset](#)
- [SensorIdentifier::value_type](#) [identifier](#)
- [SensorDataType::value_type](#) [type](#)
- pmt::pmt_t [tag_key](#)

12.378.1 Detailed Description

Definition at line 46 of file [sensor_data_source_configuration.h](#).

12.378.2 Member Data Documentation

12.378.2.1 file_id

```
uint64_t SensorDataConfiguration::file_id
```

Definition at line 49 of file [sensor_data_source_configuration.h](#).

12.378.2.2 id

```
uint64_t SensorDataConfiguration::id
```

Definition at line 48 of file [sensor_data_source_configuration.h](#).

12.378.2.3 identifier

`SensorIdentifier::value_type SensorDataConfiguration::identifier`
 Definition at line 51 of file [sensor_data_source_configuration.h](#).

12.378.2.4 offset

`uint64_t SensorDataConfiguration::offset`
 Definition at line 50 of file [sensor_data_source_configuration.h](#).

12.378.2.5 tag_key

`pmt::pmt_t SensorDataConfiguration::tag_key`
 Definition at line 53 of file [sensor_data_source_configuration.h](#).

12.378.2.6 type

`SensorDataType::value_type SensorDataConfiguration::type`
 Definition at line 52 of file [sensor_data_source_configuration.h](#).
 The documentation for this struct was generated from the following file:

- [sensor_data_source_configuration.h](#)

12.379 SensorDataFile Class Reference

Public Types

- using `sptr` = `gnss_shared_ptr<SensorDataFile>`
- using `id_type` = `std::size_t`

Public Member Functions

- **SensorDataFile** (const std::string &path, const std::size_t &sample_delay, const std::size_t &sample_period, const std::size_t &offset_in_file, const std::size_t &item_size, const bool &repeat)
- void **reset** ()
- bool **read_until_sample** (std::size_t end_sample, std::size_t &sample_stamp, std::vector< uint8_t > &buffer)
- std::size_t **get_chunks_read** () const

12.379.1 Detailed Description

Definition at line 35 of file [sensor_data_file.h](#).

12.379.2 Member Typedef Documentation

12.379.2.1 id_type

`using SensorDataFile::id_type = std::size_t`
 Definition at line 39 of file [sensor_data_file.h](#).

12.379.2.2 sptr

`using SensorDataFile::sptr = gnss_shared_ptr<SensorDataFile>`
 Definition at line 38 of file [sensor_data_file.h](#).
 The documentation for this class was generated from the following file:

- [sensor_data_file.h](#)

12.380 SensorDataFileConfiguration Struct Reference

Public Attributes

- uint64_t [id](#)
- uint64_t [chunk_size](#)
- uint64_t [file_offset](#)
- uint64_t [sample_offset](#)
- uint64_t [sample_period](#)
- std::string [filename](#)
- bool [repeat](#)

12.380.1 Detailed Description

Definition at line 34 of file [sensor_data_source_configuration.h](#).

12.380.2 Member Data Documentation

12.380.2.1 chunk_size

uint64_t SensorDataFileConfiguration::chunk_size

Definition at line 37 of file [sensor_data_source_configuration.h](#).

12.380.2.2 file_offset

uint64_t SensorDataFileConfiguration::file_offset

Definition at line 38 of file [sensor_data_source_configuration.h](#).

12.380.2.3 filename

std::string SensorDataFileConfiguration::filename

Definition at line 41 of file [sensor_data_source_configuration.h](#).

12.380.2.4 id

uint64_t SensorDataFileConfiguration::id

Definition at line 36 of file [sensor_data_source_configuration.h](#).

12.380.2.5 repeat

bool SensorDataFileConfiguration::repeat

Definition at line 42 of file [sensor_data_source_configuration.h](#).

12.380.2.6 sample_offset

uint64_t SensorDataFileConfiguration::sample_offset

Definition at line 39 of file [sensor_data_source_configuration.h](#).

12.380.2.7 sample_period

uint64_t SensorDataFileConfiguration::sample_period

Definition at line 40 of file [sensor_data_source_configuration.h](#).

The documentation for this struct was generated from the following file:

- [sensor_data_source_configuration.h](#)

12.381 SensorDataSample< DataType > Struct Template Reference

Public Member Functions

- constexpr [SensorDataSample](#) (uint64_t t, DataType v)

Public Attributes

- uint64_t [timestamp](#)
- DataType [value](#)

12.381.1 Detailed Description

```
template<typename DataType>
struct SensorDataSample< DataType >
```

Definition at line 35 of file [sensor_data_aggregator.h](#).

12.381.2 Constructor & Destructor Documentation**12.381.2.1 SensorDataSample()**

```
template<typename DataType>
SensorDataSample< DataType >::SensorDataSample (
    uint64_t t,
    DataType v) [inline], [constexpr]
```

Definition at line 40 of file [sensor_data_aggregator.h](#).

12.381.3 Member Data Documentation**12.381.3.1 timestamp**

```
template<typename DataType>
uint64_t SensorDataSample< DataType >::timestamp
```

Definition at line 37 of file [sensor_data_aggregator.h](#).

12.381.3.2 value

```
template<typename DataType>
DataType SensorDataSample< DataType >::value
```

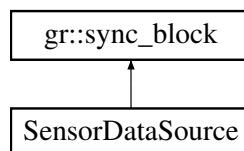
Definition at line 38 of file [sensor_data_aggregator.h](#).

The documentation for this struct was generated from the following file:

- [sensor_data_aggregator.h](#)

12.382 SensorDataSource Class Reference

Inheritance diagram for SensorDataSource:

**Public Types**

- using [sptr](#) = gnss_shared_ptr<[SensorDataSource](#)>

Public Member Functions

- **SensorDataSource** (const [SensorDataSourceConfiguration](#) &configuration, const gr::io_signature::sptr &io_signature)
- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override

12.382.1 Detailed Description

Definition at line 33 of file [sensor_data_source.h](#).

12.382.2 Member Typedef Documentation

12.382.2.1 `sptr`

```
using SensorDataSource::sptr = gnss_shared_ptr<SensorDataSource>
```

Definition at line 36 of file [sensor_data_source.h](#).

The documentation for this class was generated from the following file:

- [sensor_data_source.h](#)

12.383 SensorDataSourceConfiguration Class Reference

Public Member Functions

- **SensorDataSourceConfiguration** (const [ConfigurationInterface](#) *configuration)
- bool **validate** () const
- bool **is_enabled** () const
- bool **is_sensor_provided** (SensorIdentifier::value_type sensor_id) const
- const std::unordered_map< uint64_t, [SensorDataFileConfiguration](#) > & **files** () const
- const std::vector< [SensorDataConfiguration](#) > & **sensors** () const
- void **set_items_per_sample** (uint64_t items_per_sample)
- uint64_t **get_items_per_sample** () const

12.383.1 Detailed Description

Definition at line 57 of file [sensor_data_source_configuration.h](#).

The documentation for this class was generated from the following file:

- [sensor_data_source_configuration.h](#)

12.384 SensorDataType Struct Reference

Public Types

- enum **value_type** {
 UINT64 , **F32** , **F64** , **I32** ,
 I64 }

Static Public Member Functions

- static value_type **from_string** (const std::string &s)
- static std::string **to_string** (const value_type &v)
- static uint64_t **get_size** (const value_type &v)
- static pmt::pmt_t **make_value** (const value_type &v, void *value)

12.384.1 Detailed Description

Definition at line 29 of file [sensor_data_type.h](#).

12.384.2 Member Enumeration Documentation

12.384.2.1 value_type

enum SensorDataType::value_type

Definition at line 32 of file [sensor_data_type.h](#).

The documentation for this struct was generated from the following file:

- [sensor_data_type.h](#)

12.385 SensorIdentifier Struct Reference

Public Types

- enum **value_type** : unsigned short {
SAMPLE_STAMP = 0 , **CHUNK_COUNT** , **IMU_VEL_X** , **IMU_VEL_Y** ,
IMU_VEL_Z , **IMU_ACC_X** , **IMU_ACC_Y** , **IMU_ACC_Z** ,
IMU_ANG_VEL_X , **IMU_ANG_VEL_Y** , **IMU_ANG_VEL_Z** , **IMU_ANG_ACC_X** ,
IMU_ANG_ACC_Y , **IMU_ANG_ACC_Z** }

Static Public Member Functions

- static value_type **from_string** (const std::string &s)
- static std::string **to_string** (value_type v)
- static bool **is_valid_type** (value_type sensor_id, SensorDataType::value_type type)
- static SensorDataType::value_type **get_internal_type** (value_type sensor_id)
- static pmt::pmt_t **convert_to_internal_type** (value_type sensor_id, SensorDataType::value_type original_type, const pmt::pmt_t &value)

12.385.1 Detailed Description

Definition at line 30 of file [sensor_identifier.h](#).

12.385.2 Member Enumeration Documentation

12.385.2.1 value_type

enum SensorIdentifier::value_type : unsigned short

Definition at line 33 of file [sensor_identifier.h](#).

The documentation for this struct was generated from the following file:

- [sensor_identifier.h](#)

12.386 seph_t Struct Reference

Public Attributes

- int [sat](#)
- [gtime_t](#) [t0](#)
- [gtime_t](#) [tof](#)
- int [sva](#)
- int [svh](#)
- double [pos](#) [3]
- double [vel](#) [3]
- double [acc](#) [3]
- double [af0](#)
- double [af1](#)

12.386.1 Detailed Description

Definition at line 501 of file [rtklib.h](#).

12.386.2 Member Data Documentation

12.386.2.1 acc

```
double seph_t::acc[3]
```

Definition at line 510 of file [rtklib.h](#).

12.386.2.2 af0

```
double seph_t::af0
```

Definition at line 511 of file [rtklib.h](#).

12.386.2.3 af1

```
double seph_t::af1
```

Definition at line 511 of file [rtklib.h](#).

12.386.2.4 pos

```
double seph_t::pos[3]
```

Definition at line 508 of file [rtklib.h](#).

12.386.2.5 sat

```
int seph_t::sat
```

Definition at line 503 of file [rtklib.h](#).

12.386.2.6 sva

```
int seph_t::sva
```

Definition at line 506 of file [rtklib.h](#).

12.386.2.7 svh

```
int seph_t::svh
```

Definition at line 507 of file [rtklib.h](#).

12.386.2.8 t0

```
gtime_t seph_t::t0
```

Definition at line 504 of file [rtklib.h](#).

12.386.2.9 tof

```
gtime_t seph_t::tof
```

Definition at line 505 of file [rtklib.h](#).

12.386.2.10 vel

```
double seph_t::vel[3]
```

Definition at line 509 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.387 Serdes_Galileo_Eph Class Reference

This class implements serialization and deserialization of [Galileo_Ephemeris](#) using Protocol Buffers.

```
#include <serdes_galileo_eph.h>
```

Public Member Functions

- [Serdes_Galileo_Eph](#) (const [Serdes_Galileo_Eph](#) &other) noexcept
- [Serdes_Galileo_Eph](#) & operator= (const [Serdes_Galileo_Eph](#) &rhs) noexcept
< Copy assignment operator
- [Serdes_Galileo_Eph](#) ([Serdes_Galileo_Eph](#) &&other) noexcept
- [Serdes_Galileo_Eph](#) & operator= ([Serdes_Galileo_Eph](#) &&other) noexcept
< Move assignment operator
- std::string [createProtobuffer](#) (const std::shared_ptr< [Galileo_Ephemeris](#) > monitor)
- [Galileo_Ephemeris](#) [readProtobuffer](#) (const gnss_sdr::GalileoEphemeris &mon) const
< Deserialization

12.387.1 Detailed Description

This class implements serialization and deserialization of [Galileo_Ephemeris](#) using Protocol Buffers.

Definition at line 37 of file [serdes_galileo_eph.h](#).

12.387.2 Constructor & Destructor Documentation

12.387.2.1 Serdes_Galileo_Eph() [1/3]

```
Serdes_Galileo_Eph::Serdes_Galileo_Eph () [inline]
```

Definition at line 40 of file [serdes_galileo_eph.h](#).

12.387.2.2 ~Serdes_Galileo_Eph()

```
Serdes_Galileo_Eph::~~Serdes_Galileo_Eph () [inline]
```

Definition at line 47 of file [serdes_galileo_eph.h](#).

12.387.2.3 Serdes_Galileo_Eph() [2/3]

```
Serdes_Galileo_Eph::Serdes_Galileo_Eph (
    const Serdes\_Galileo\_Eph & other) [inline], [noexcept]
```

Definition at line 52 of file [serdes_galileo_eph.h](#).

12.387.2.4 Serdes_Galileo_Eph() [3/3]

```
Serdes_Galileo_Eph::Serdes_Galileo_Eph (
    Serdes\_Galileo\_Eph && other) [inline], [noexcept]
```

Definition at line 63 of file [serdes_galileo_eph.h](#).

12.387.3 Member Function Documentation

12.387.3.1 createProtobuffer()

```
std::string Serdes_Galileo_Eph::createProtobuffer (
    const std::shared_ptr< Galileo\_Ephemeris > monitor) [inline]
```

Parameters

<i>monitor</i>	Serialization into a string
----------------	-----------------------------

Definition at line 73 of file [serdes_galileo_eph.h](#).

12.387.3.2 operator=() [1/2]

```
Serdes_Galileo_Eph & Serdes_Galileo_Eph::operator= (
    const Serdes_Galileo_Eph & rhs) [inline], [noexcept]
```

< Copy assignment operator

Definition at line 56 of file [serdes_galileo_eph.h](#).**12.387.3.3 operator=()** [2/2]

```
Serdes_Galileo_Eph & Serdes_Galileo_Eph::operator= (
    Serdes_Galileo_Eph && other) [inline], [noexcept]
```

< Move assignment operator

Definition at line 67 of file [serdes_galileo_eph.h](#).**12.387.3.4 readProtobuffer()**

```
Galileo_Ephemeris Serdes_Galileo_Eph::readProtobuffer (
    const gnss_sdr::GalileoEphemeris & mon) const [inline]
```

< Deserialization

Definition at line 122 of file [serdes_galileo_eph.h](#).

References [Gnss_Ephemeris::af0](#), [Gnss_Ephemeris::af1](#), [Gnss_Ephemeris::af2](#), [Galileo_Ephemeris::BGD_E1E5a](#), [Galileo_Ephemeris::BGD_E1E5b](#), [Gnss_Ephemeris::Cic](#), [Gnss_Ephemeris::Cis](#), [Gnss_Ephemeris::Crc](#), [Gnss_Ephemeris::Crs](#), [Gnss_Ephemeris::Cuc](#), [Gnss_Ephemeris::Cus](#), [Gnss_Ephemeris::delta_n](#), [Gnss_Ephemeris::dtr](#), [Galileo_Ephemeris::E1B_DVS](#), [Galileo_Ephemeris::E1B_HS](#), [Galileo_Ephemeris::E5a_DVS](#), [Galileo_Ephemeris::E5a_HS](#), [Galileo_Ephemeris::E5b_DVS](#), [Galileo_Ephemeris::E5b_HS](#), [Gnss_Ephemeris::ecc](#), [Gnss_Ephemeris::i_0](#), [Gnss_Ephemeris::idot](#), [Gnss_Ephemeris::M_0](#), [Gnss_Ephemeris::omega](#), [Gnss_Ephemeris::OMEGA_0](#), [Gnss_Ephemeris::OMEGAdot](#), [Gnss_Ephemeris::PRN](#), [Gnss_Ephemeris::satClkDrift](#), [Galileo_Ephemeris::SISA](#), [Gnss_Ephemeris::sqrtA](#), [Gnss_Ephemeris::toc](#), [Gnss_Ephemeris::toe](#), [Gnss_Ephemeris::tow](#), and [Gnss_Ephemeris::WN](#).

The documentation for this class was generated from the following file:

- [serdes_galileo_eph.h](#)

12.388 Serdes_Gnss_Synchro Class ReferenceThis class implements serialization and deserialization of [Gnss_Synchro](#) objects using Protocol Buffers.

#include <serdes_gnss_synchro.h>

Public Member Functions

- [Serdes_Gnss_Synchro](#) (const [Serdes_Gnss_Synchro](#) &other) noexcept
< Copy constructor
- [Serdes_Gnss_Synchro](#) & operator= (const [Serdes_Gnss_Synchro](#) &rhs) noexcept
< Copy assignment operator
- [Serdes_Gnss_Synchro](#) ([Serdes_Gnss_Synchro](#) &&other) noexcept
< Move constructor
- [Serdes_Gnss_Synchro](#) & operator= ([Serdes_Gnss_Synchro](#) &&other) noexcept
< Move assignment operator
- std::string [createProtobuffer](#) (const std::vector< [Gnss_Synchro](#) > &vgs)
- std::vector< [Gnss_Synchro](#) > [readProtobuffer](#) (const gnss_sdr::Observables &obs) const
< Deserialization

12.388.1 Detailed DescriptionThis class implements serialization and deserialization of [Gnss_Synchro](#) objects using Protocol Buffers.Definition at line 32 of file [serdes_gnss_synchro.h](#).

12.388.2 Constructor & Destructor Documentation

12.388.2.1 Serdes_Gnss_Synchro() [1/3]

`Serdes_Gnss_Synchro::Serdes_Gnss_Synchro () [inline]`

Definition at line 35 of file [serdes_gnss_synchro.h](#).

12.388.2.2 ~Serdes_Gnss_Synchro()

`Serdes_Gnss_Synchro::~~Serdes_Gnss_Synchro () [inline]`

Definition at line 42 of file [serdes_gnss_synchro.h](#).

12.388.2.3 Serdes_Gnss_Synchro() [2/3]

`Serdes_Gnss_Synchro::Serdes_Gnss_Synchro (const Serdes_Gnss_Synchro & other) [inline], [noexcept]`

< Copy constructor

Definition at line 47 of file [serdes_gnss_synchro.h](#).

12.388.2.4 Serdes_Gnss_Synchro() [3/3]

`Serdes_Gnss_Synchro::Serdes_Gnss_Synchro (Serdes_Gnss_Synchro && other) [inline], [noexcept]`

< Move constructor

Definition at line 58 of file [serdes_gnss_synchro.h](#).

12.388.3 Member Function Documentation

12.388.3.1 createProtobuffer()

`std::string Serdes_Gnss_Synchro::createProtobuffer (const std::vector< Gnss_Synchro > & vgs) [inline]`

Parameters

<code>vgs</code>	Serialization into a string
------------------	-----------------------------

Definition at line 72 of file [serdes_gnss_synchro.h](#).

12.388.3.2 operator=() [1/2]

`Serdes_Gnss_Synchro & Serdes_Gnss_Synchro::operator= (const Serdes_Gnss_Synchro & rhs) [inline], [noexcept]`

< Copy assignment operator

Definition at line 52 of file [serdes_gnss_synchro.h](#).

12.388.3.3 operator=() [2/2]

`Serdes_Gnss_Synchro & Serdes_Gnss_Synchro::operator= (Serdes_Gnss_Synchro && other) [inline], [noexcept]`

< Move assignment operator

Definition at line 63 of file [serdes_gnss_synchro.h](#).

12.388.3.4 readProtobuffer()

`std::vector< Gnss_Synchro > Serdes_Gnss_Synchro::readProtobuffer (const gnss_sdr::Observables & obs) const [inline]`

< Deserialization

Definition at line 123 of file [serdes_gnss_synchro.h](#).

References [Gnss_Synchro::Acq_delay_samples](#), [Gnss_Synchro::Acq_doppler_hz](#), [Gnss_Synchro::Acq_doppler_step](#), [Gnss_Synchro::Acq_samplestamp_samples](#), [Gnss_Synchro::Carrier_Doppler_hz](#), [Gnss_Synchro::Carrier_phase_rads](#), [Gnss_Synchro::Channel_ID](#), [Gnss_Synchro::CN0_dB_hz](#), [Gnss_Synchro::Code_phase_samples](#), [Gnss_Synchro::correlation_length](#), [Gnss_Synchro::Flag_cycle_slip](#), [Gnss_Synchro::Flag_PLL_180_deg_phase_locked](#), [Gnss_Synchro::Flag_valid_acquisition](#), [Gnss_Synchro::Flag_valid_pseudorange](#), [Gnss_Synchro::Flag_valid_symbol_output](#), [Gnss_Synchro::Flag_valid_word](#), [Gnss_Synchro::fs](#), [Gnss_Synchro::interp_TOW_ms](#), [Gnss_Synchro::PRN](#), [Gnss_Synchro::Prompt_I](#), [Gnss_Synchro::Prompt_Q](#), [Gnss_Synchro::Pseudorange_m](#), [Gnss_Synchro::RX_time](#), [Gnss_Synchro::Signal](#), [Gnss_Synchro::System](#), [Gnss_Synchro::TOW_at_current_symbol_ms](#), and [Gnss_Synchro::Tracking_sample_counter](#).

The documentation for this class was generated from the following file:

- [serdes_gnss_synchro.h](#)

12.389 Serdes_Gps_Eph Class Reference

This class implements serialization and deserialization of [Gps_Ephemeris](#) objects using Protocol Buffers.

```
#include <serdes_gps_eph.h>
```

Public Member Functions

- [Serdes_Gps_Eph](#) (const [Serdes_Gps_Eph](#) &other) noexcept
- [Serdes_Gps_Eph](#) & operator= (const [Serdes_Gps_Eph](#) &rhs) noexcept
< Copy assignment operator
- [Serdes_Gps_Eph](#) ([Serdes_Gps_Eph](#) &&other) noexcept
- [Serdes_Gps_Eph](#) & operator= ([Serdes_Gps_Eph](#) &&other) noexcept
< Move assignment operator
- std::string [createProtobuffer](#) (const std::shared_ptr< [Gps_Ephemeris](#) > monitor)
- [Gps_Ephemeris](#) [readProtobuffer](#) (const gnss_sdr::GpsEphemeris &mon) const
< Deserialization

12.389.1 Detailed Description

This class implements serialization and deserialization of [Gps_Ephemeris](#) objects using Protocol Buffers.

Definition at line 36 of file [serdes_gps_eph.h](#).

12.389.2 Constructor & Destructor Documentation

12.389.2.1 Serdes_Gps_Eph() [1/3]

```
Serdes_Gps_Eph::Serdes_Gps_Eph () [inline]
```

Definition at line 39 of file [serdes_gps_eph.h](#).

12.389.2.2 ~Serdes_Gps_Eph()

```
Serdes_Gps_Eph::~Serdes_Gps_Eph () [inline]
```

Definition at line 46 of file [serdes_gps_eph.h](#).

12.389.2.3 Serdes_Gps_Eph() [2/3]

```
Serdes_Gps_Eph::Serdes_Gps_Eph (
    const Serdes\_Gps\_Eph & other) [inline], [noexcept]
```

Definition at line 51 of file [serdes_gps_eph.h](#).

12.389.2.4 Serdes_Gps_Eph() [3/3]

```
Serdes_Gps_Eph::Serdes_Gps_Eph (
    Serdes\_Gps\_Eph && other) [inline], [noexcept]
```

Definition at line 62 of file [serdes_gps_eph.h](#).

12.389.3 Member Function Documentation

12.389.3.1 createProtobuffer()

```
std::string Serdes_Gps_Eph::createProtobuffer (
    const std::shared_ptr< Gps_Ephemeris > monitor) [inline]
```

Parameters

<i>monitor</i>	Serialization into a string
----------------	-----------------------------

Definition at line 72 of file [serdes_gps_eph.h](#).

12.389.3.2 operator=() [1/2]

```
Serdes_Gps_Eph & Serdes_Gps_Eph::operator= (
    const Serdes_Gps_Eph & rhs) [inline], [noexcept]
```

< Copy assignment operator

Definition at line 55 of file [serdes_gps_eph.h](#).

12.389.3.3 operator=() [2/2]

```
Serdes_Gps_Eph & Serdes_Gps_Eph::operator= (
    Serdes_Gps_Eph && other) [inline], [noexcept]
```

< Move assignment operator

Definition at line 66 of file [serdes_gps_eph.h](#).

12.389.3.4 readProtobuffer()

```
Gps_Ephemeris Serdes_Gps_Eph::readProtobuffer (
    const gnss_sdr::GpsEphemeris & mon) const [inline]
```

< Deserialization

Definition at line 124 of file [serdes_gps_eph.h](#).

References [Gnss_Ephemeris::af0](#), [Gnss_Ephemeris::af1](#), [Gnss_Ephemeris::af2](#), [Gps_Ephemeris::alert_flag](#), [Gps_Ephemeris::antispoofing_flag](#), [Gps_Ephemeris::AODO](#), [Gnss_Ephemeris::Cic](#), [Gnss_Ephemeris::Cis](#), [Gps_Ephemeris::code_on_L2](#), [Gnss_Ephemeris::Crc](#), [Gnss_Ephemeris::Crs](#), [Gnss_Ephemeris::Cuc](#), [Gnss_Ephemeris::Cus](#), [Gnss_Ephemeris::delta_n](#), [Gnss_Ephemeris::dtr](#), [Gnss_Ephemeris::ecc](#), [Gps_Ephemeris::fit_interval_flag](#), [Gnss_Ephemeris::i_0](#), [Gnss_Ephemeris::idot](#), [Gps_Ephemeris::integrity_status_flag](#), [Gps_Ephemeris::IODC](#), [Gps_Ephemeris::IODE_SF2](#), [Gps_Ephemeris::IODE_SF3](#), [Gps_Ephemeris::L2_P_data_flag](#), [Gnss_Ephemeris::M_0](#), [Gnss_Ephemeris::omega](#), [Gnss_Ephemeris::OMEGA_0](#), [Gnss_Ephemeris::OMEGAdot](#), [Gnss_Ephemeris::PRN](#), [Gnss_Ephemeris::satClkDrift](#), [Gnss_Ephemeris::sqrtA](#), [Gps_Ephemeris::SV_accuracy](#), [Gps_Ephemeris::SV_health](#), [Gps_Ephemeris::TGD](#), [Gnss_Ephemeris::toc](#), [Gnss_Ephemeris::toe](#), [Gnss_Ephemeris::tow](#), and [Gnss_Ephemeris::WN](#).

The documentation for this class was generated from the following file:

- [serdes_gps_eph.h](#)

12.390 Serdes_Monitor_Pvt Class Reference

This class implements serialization and deserialization of [Monitor_Pvt](#) objects using Protocol Buffers.

```
#include <serdes_monitor_pvt.h>
```

Public Member Functions

- [Serdes_Monitor_Pvt](#) (const [Serdes_Monitor_Pvt](#) &other) noexcept
- [Serdes_Monitor_Pvt](#) & operator= (const [Serdes_Monitor_Pvt](#) &rhs) noexcept
< Copy assignment operator
- [Serdes_Monitor_Pvt](#) ([Serdes_Monitor_Pvt](#) &&other) noexcept
- [Serdes_Monitor_Pvt](#) & operator= ([Serdes_Monitor_Pvt](#) &&other) noexcept
< Move assignment operator

- `std::string createProtobuffer` (const [Monitor_Pvt](#) *const monitor)
- [Monitor_Pvt readProtobuffer](#) (const gnss_sdr::MonitorPvt &mon) const

< *Deserialization*

12.390.1 Detailed Description

This class implements serialization and deserialization of [Monitor_Pvt](#) objects using Protocol Buffers.
Definition at line 37 of file [serdes_monitor_pvt.h](#).

12.390.2 Constructor & Destructor Documentation

12.390.2.1 Serdes_Monitor_Pvt() [1/3]

```
Serdes_Monitor_Pvt::Serdes_Monitor_Pvt () [inline]
```

Definition at line 40 of file [serdes_monitor_pvt.h](#).

12.390.2.2 ~Serdes_Monitor_Pvt()

```
Serdes_Monitor_Pvt::~~Serdes_Monitor_Pvt () [inline]
```

Definition at line 47 of file [serdes_monitor_pvt.h](#).

12.390.2.3 Serdes_Monitor_Pvt() [2/3]

```
Serdes_Monitor_Pvt::Serdes_Monitor_Pvt (
    const Serdes\_Monitor\_Pvt & other) [inline], [noexcept]
```

Definition at line 52 of file [serdes_monitor_pvt.h](#).

12.390.2.4 Serdes_Monitor_Pvt() [3/3]

```
Serdes_Monitor_Pvt::Serdes_Monitor_Pvt (
    Serdes\_Monitor\_Pvt && other) [inline], [noexcept]
```

Definition at line 65 of file [serdes_monitor_pvt.h](#).

12.390.3 Member Function Documentation

12.390.3.1 createProtobuffer()

```
std::string Serdes_Monitor_Pvt::createProtobuffer (
    const Monitor\_Pvt *const monitor) [inline]
```

Parameters

<i>monitor</i>	Serialization into a string
----------------	-----------------------------

Definition at line 80 of file [serdes_monitor_pvt.h](#).

12.390.3.2 operator=() [1/2]

```
Serdes\_Monitor\_Pvt & Serdes_Monitor_Pvt::operator= (
    const Serdes\_Monitor\_Pvt & rhs) [inline], [noexcept]
```

< Copy assignment operator

Definition at line 56 of file [serdes_monitor_pvt.h](#).

12.390.3.3 operator=() [2/2]

```
Serdes\_Monitor\_Pvt & Serdes_Monitor_Pvt::operator= (
    Serdes\_Monitor\_Pvt && other) [inline], [noexcept]
```

< Move assignment operator

Definition at line 71 of file [serdes_monitor_pvt.h](#).

12.390.3.4 readProtobuffer()

```
Monitor_Pvt Serdes_Monitor_Pvt::readProtobuffer (
    const gnss_sdr::MonitorPvt & mon) const [inline]
```

< Deserialization

Definition at line 127 of file [serdes_monitor_pvt.h](#).

The documentation for this class was generated from the following file:

- [serdes_monitor_pvt.h](#)

12.391 Serdes_Nav_Message Class Reference

This class implements serialization and deserialization of [Nav_Message_Packet](#) objects using Protocol Buffers.

```
#include <serdes_nav_message.h>
```

Public Member Functions

- [Serdes_Nav_Message](#) (const [Serdes_Nav_Message](#) &other) noexcept
- [Serdes_Nav_Message](#) & operator= (const [Serdes_Nav_Message](#) &rhs) noexcept
 < Copy assignment operator
- [Serdes_Nav_Message](#) ([Serdes_Nav_Message](#) &&other) noexcept
- [Serdes_Nav_Message](#) & operator= ([Serdes_Nav_Message](#) &&other) noexcept
 < Move assignment operator
- std::string [createProtobuffer](#) (const std::shared_ptr< [Nav_Message_Packet](#) > nav_msg_packet)
- [Nav_Message_Packet](#) [readProtobuffer](#) (const gnss_sdr::navMsg &msg) const
 < Deserialization

12.391.1 Detailed Description

This class implements serialization and deserialization of [Nav_Message_Packet](#) objects using Protocol Buffers.

Definition at line 38 of file [serdes_nav_message.h](#).

12.391.2 Constructor & Destructor Documentation

12.391.2.1 Serdes_Nav_Message() [1/3]

```
Serdes_Nav_Message::Serdes_Nav_Message () [inline]
```

Definition at line 41 of file [serdes_nav_message.h](#).

12.391.2.2 ~Serdes_Nav_Message()

```
Serdes_Nav_Message::~~Serdes_Nav_Message () [inline]
```

Definition at line 48 of file [serdes_nav_message.h](#).

12.391.2.3 Serdes_Nav_Message() [2/3]

```
Serdes_Nav_Message::Serdes_Nav_Message (
    const Serdes\_Nav\_Message & other) [inline], [noexcept]
```

Definition at line 53 of file [serdes_nav_message.h](#).

12.391.2.4 Serdes_Nav_Message() [3/3]

```
Serdes_Nav_Message::Serdes_Nav_Message (
    Serdes\_Nav\_Message && other) [inline], [noexcept]
```

Definition at line 66 of file [serdes_nav_message.h](#).

12.391.3 Member Function Documentation

12.391.3.1 createProtobuffer()

```
std::string Serdes_Nav_Message::createProtobuffer (
    const std::shared_ptr< Nav_Message_Packet > nav_msg_packet) [inline]
```

Parameters

<i>nav_msg_packet</i>	Serialization into a string
-----------------------	-----------------------------

Definition at line 82 of file [serdes_nav_message.h](#).

12.391.3.2 operator=() [1/2]

```
Serdes_Nav_Message & Serdes_Nav_Message::operator= (
    const Serdes_Nav_Message & rhs) [inline], [noexcept]
```

< Copy assignment operator

Definition at line 57 of file [serdes_nav_message.h](#).

12.391.3.3 operator=() [2/2]

```
Serdes_Nav_Message & Serdes_Nav_Message::operator= (
    Serdes_Nav_Message && other) [inline], [noexcept]
```

< Move assignment operator

Definition at line 72 of file [serdes_nav_message.h](#).

12.391.3.4 readProtobuffer()

```
Nav_Message_Packet Serdes_Nav_Message::readProtobuffer (
    const gnss_sdr::navMsg & msg) const [inline]
```

< Deserialization

Definition at line 98 of file [serdes_nav_message.h](#).

References [Nav_Message_Packet::nav_message](#), [Nav_Message_Packet::prn](#), [Nav_Message_Packet::signal](#), [Nav_Message_Packet::system](#), and [Nav_Message_Packet::tow_at_current_symbol_ms](#).

The documentation for this class was generated from the following file:

- [serdes_nav_message.h](#)

12.392 serial_t Struct Reference

Public Attributes

- dev_t [dev](#)
- int [error](#)

12.392.1 Detailed Description

Definition at line 1111 of file [rtklib.h](#).

12.392.2 Member Data Documentation

12.392.2.1 dev

```
dev_t serial_t::dev
```

Definition at line 1113 of file [rtklib.h](#).

12.392.2.2 error

```
int serial_t::error
```

Definition at line 1114 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

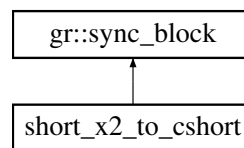
- [rtklib.h](#)

12.393 short_x2_to_cshort Class Reference

This class adapts two short streams into a `std::complex<short>` stream.

```
#include <short_x2_to_cshort.h>
```

Inheritance diagram for `short_x2_to_cshort`:



Public Member Functions

- `int work` (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- `short_x2_to_cshort_sptr make_short_x2_to_cshort()`

12.393.1 Detailed Description

This class adapts two short streams into a `std::complex<short>` stream.

Definition at line 40 of file [short_x2_to_cshort.h](#).

The documentation for this class was generated from the following file:

- [short_x2_to_cshort.h](#)

12.394 Signal_Enabled_Flags Class Reference

Public Member Functions

- `Signal_Enabled_Flags` (const [ConfigurationInterface](#) *configuration)
- `Signal_Enabled_Flags` (uint32_t flags_)
- `template<typename T>`
`uint32_t or_all` (const T &value) const
- `template<typename T, typename... Args>`
`uint32_t or_all` (const T &first, const Args &... rest) const
- `template<typename... Args>`
`bool check_only_enabled` (const Args &... args) const
- `template<typename... Args>`
`bool check_any_enabled` (const Args &... args) const

Public Attributes

- const uint32_t [flags](#)
- const bool [has_gps](#)
- const bool [has_galileo](#)
- const bool [has_glonass](#)

- const bool [has_beidou](#)
- const bool [has_qzss](#)
- const bool [only_gps](#)
- const bool [only_galileo](#)
- const bool [only_glonass](#)
- const bool [only_beidou](#)
- const bool [only_qzss](#)

12.394.1 Detailed Description

Definition at line 41 of file [signal_enabled_flags.h](#).

12.394.2 Member Function Documentation

12.394.2.1 [check_any_enabled\(\)](#)

```
template<typename... Args>
bool Signal_Enabled_Flags::check_any_enabled (
    const Args &... args) const [inline]
```

Definition at line 66 of file [signal_enabled_flags.h](#).

12.394.2.2 [check_only_enabled\(\)](#)

```
template<typename... Args>
bool Signal_Enabled_Flags::check_only_enabled (
    const Args &... args) const [inline]
```

Definition at line 60 of file [signal_enabled_flags.h](#).

12.394.2.3 [or_all\(\)](#) [1/2]

```
template<typename T, typename... Args>
uint32_t Signal_Enabled_Flags::or_all (
    const T & first,
    const Args &... rest) const [inline]
```

Definition at line 54 of file [signal_enabled_flags.h](#).

12.394.2.4 [or_all\(\)](#) [2/2]

```
template<typename T>
uint32_t Signal_Enabled_Flags::or_all (
    const T & value) const [inline]
```

Definition at line 48 of file [signal_enabled_flags.h](#).

12.394.3 Member Data Documentation

12.394.3.1 [flags](#)

```
const uint32_t Signal_Enabled_Flags::flags
```

Definition at line 71 of file [signal_enabled_flags.h](#).

12.394.3.2 [has_beidou](#)

```
const bool Signal_Enabled_Flags::has_beidou
```

Definition at line 76 of file [signal_enabled_flags.h](#).

12.394.3.3 [has_galileo](#)

```
const bool Signal_Enabled_Flags::has_galileo
```

Definition at line 74 of file [signal_enabled_flags.h](#).

12.394.3.4 has_glonass

`const bool Signal_Enabled_Flags::has_glonass`
 Definition at line 75 of file [signal_enabled_flags.h](#).

12.394.3.5 has_gps

`const bool Signal_Enabled_Flags::has_gps`
 Definition at line 73 of file [signal_enabled_flags.h](#).

12.394.3.6 has_qzss

`const bool Signal_Enabled_Flags::has_qzss`
 Definition at line 77 of file [signal_enabled_flags.h](#).

12.394.3.7 only_beidou

`const bool Signal_Enabled_Flags::only_beidou`
 Definition at line 82 of file [signal_enabled_flags.h](#).

12.394.3.8 only_galileo

`const bool Signal_Enabled_Flags::only_galileo`
 Definition at line 80 of file [signal_enabled_flags.h](#).

12.394.3.9 only_glonass

`const bool Signal_Enabled_Flags::only_glonass`
 Definition at line 81 of file [signal_enabled_flags.h](#).

12.394.3.10 only_gps

`const bool Signal_Enabled_Flags::only_gps`
 Definition at line 79 of file [signal_enabled_flags.h](#).

12.394.3.11 only_qzss

`const bool Signal_Enabled_Flags::only_qzss`
 Definition at line 83 of file [signal_enabled_flags.h](#).
 The documentation for this class was generated from the following file:

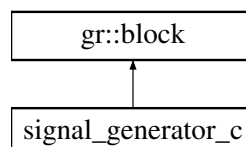
- [signal_enabled_flags.h](#)

12.395 signal_generator_c Class Reference

This class generates synthesized GNSS signal.

`#include <signal_generator_c.h>`

Inheritance diagram for `signal_generator_c`:

**Public Member Functions**

- `int general_work (int noutput_items, gr_vector_int &ninput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)`

Friends

- `signal_generator_c_sptr` [signal_make_generator_c](#) (const std::vector< std::string > &signal1, const std::vector< std::string > &system, const std::vector< unsigned int > &PRN, const std::vector< float > &CNO_dB, const std::vector< float > &doppler_Hz, const std::vector< unsigned int > &delay_chips, const std::vector< unsigned int > &delay_sec, bool data_flag, bool noise_flag, unsigned int fs_in, unsigned int vector_length, float BW_BB)

Return a shared_ptr to a new instance of gen_source.

12.395.1 Detailed Description

This class generates synthesized GNSS signal.

See also

`gen_source` for a version that subclasses `gr_block`.

Definition at line 58 of file [signal_generator_c.h](#).

12.395.2 Friends And Related Symbol Documentation

12.395.2.1 signal_make_generator_c

```
signal_generator_c_sptr signal_make_generator_c (
    const std::vector< std::string > & signal1,
    const std::vector< std::string > & system,
    const std::vector< unsigned int > & PRN,
    const std::vector< float > & CNO_dB,
    const std::vector< float > & doppler_Hz,
    const std::vector< unsigned int > & delay_chips,
    const std::vector< unsigned int > & delay_sec,
    bool data_flag,
    bool noise_flag,
    unsigned int fs_in,
    unsigned int vector_length,
    float BW_BB) [friend]
```

Return a shared_ptr to a new instance of `gen_source`.

To avoid accidental use of raw pointers, `gen_source`'s constructor is private. `signal_make_generator_c` is the public interface for creating new instances.

The documentation for this class was generated from the following file:

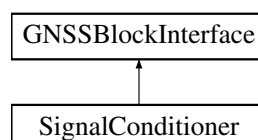
- [signal_generator_c.h](#)

12.396 SignalConditioner Class Reference

This class wraps blocks to change `data_type_adapter`, `input_filter` and `resampler` to be applied to the input flow of sampled signal.

```
#include <signal_conditioner.h>
```

Inheritance diagram for `SignalConditioner`:



Public Member Functions

- `SignalConditioner` (std::shared_ptr< [GNSSBlockInterface](#) > data_type_adapt, std::shared_ptr< [GNSSBlockInterface](#) > in_filt, std::shared_ptr< [GNSSBlockInterface](#) > res, std::string role)

Constructor.

- [~SignalConditioner](#) ()=default

Destructor.

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- std::string [role](#) () override
- std::string [implementation](#) () override

Returns "Signal_Conditioner".

- size_t [item_size](#) () override
- std::shared_ptr< [GNSSBlockInterface](#) > [data_type_adapter](#) ()
- std::shared_ptr< [GNSSBlockInterface](#) > [input_filter](#) ()
- std::shared_ptr< [GNSSBlockInterface](#) > [resampler](#) ()

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.396.1 Detailed Description

This class wraps blocks to change `data_type_adapter`, `input_filter` and `resampler` to be applied to the input flow of sampled signal.

Definition at line 39 of file [signal_conditioner.h](#).

12.396.2 Constructor & Destructor Documentation

12.396.2.1 SignalConditioner()

```
SignalConditioner::SignalConditioner (
    std::shared_ptr< GNSSBlockInterface > data_type_adapt,
    std::shared_ptr< GNSSBlockInterface > in_filt,
    std::shared_ptr< GNSSBlockInterface > res,
    std::string role)
```

Constructor.

12.396.2.2 ~SignalConditioner()

```
SignalConditioner::~SignalConditioner () [default]
```

Destructor.

12.396.3 Member Function Documentation

12.396.3.1 connect()

```
void SignalConditioner::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.396.3.2 data_type_adapter()

```
std::shared_ptr< GNSSBlockInterface > SignalConditioner::data_type_adapter () [inline]
```

Definition at line 62 of file [signal_conditioner.h](#).

12.396.3.3 disconnect()

```
void SignalConditioner::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.396.3.4 get_left_block()

```
gr::basic_block_sptr SignalConditioner::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.396.3.5 get_right_block()

```
gr::basic_block_sptr SignalConditioner::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.396.3.6 implementation()

```
std::string SignalConditioner::implementation () [inline], [override], [virtual]
```

Returns "Signal_Conditioner".

Implements [GNSSBlockInterface](#).

Definition at line 58 of file [signal_conditioner.h](#).

12.396.3.7 input_filter()

```
std::shared_ptr< GNSSBlockInterface > SignalConditioner::input_filter () [inline]
```

Definition at line 63 of file [signal_conditioner.h](#).

12.396.3.8 item_size()

```
size_t SignalConditioner::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 60 of file [signal_conditioner.h](#).

12.396.3.9 resampler()

```
std::shared_ptr< GNSSBlockInterface > SignalConditioner::resampler () [inline]
```

Definition at line 64 of file [signal_conditioner.h](#).

12.396.3.10 role()

```
std::string SignalConditioner::role () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 56 of file [signal_conditioner.h](#).

The documentation for this class was generated from the following file:

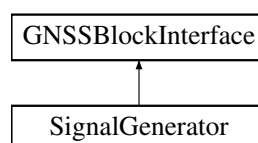
- [signal_conditioner.h](#)

12.397 SignalGenerator Class Reference

This class generates synthesized GNSS signal.

```
#include <signal_generator.h>
```

Inheritance diagram for SignalGenerator:



Public Member Functions

- **SignalGenerator** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- std::string [role](#) () override
- std::string [implementation](#) () override
Returns "GNSSSignalGenerator".
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.397.1 Detailed Description

This class generates synthesized GNSS signal.

Definition at line 39 of file [signal_generator.h](#).

12.397.2 Member Function Documentation

12.397.2.1 connect()

```
void SignalGenerator::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.397.2.2 disconnect()

```
void SignalGenerator::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.397.2.3 get_left_block()

```
gr::basic_block_sptr SignalGenerator::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.397.2.4 get_right_block()

```
gr::basic_block_sptr SignalGenerator::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.397.2.5 implementation()

```
std::string SignalGenerator::implementation () [inline], [override], [virtual]
```

Returns "GNSSSignalGenerator".

Implements [GNSSBlockInterface](#).

Definition at line 56 of file [signal_generator.h](#).

12.397.2.6 item_size()

size_t SignalGenerator::item_size () [inline], [override], [virtual]

Implements [GNSSBlockInterface](#).

Definition at line 61 of file [signal_generator.h](#).

12.397.2.7 role()

std::string SignalGenerator::role () [inline], [override], [virtual]

Implements [GNSSBlockInterface](#).

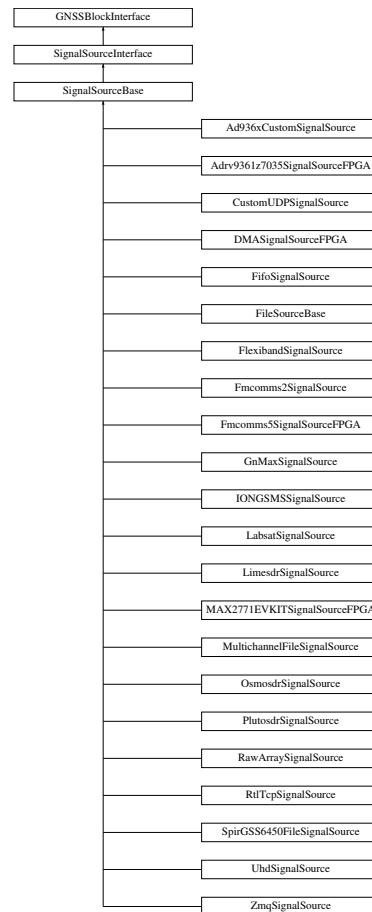
Definition at line 48 of file [signal_generator.h](#).

The documentation for this class was generated from the following file:

- [signal_generator.h](#)

12.398 SignalSourceBase Class Reference

Inheritance diagram for SignalSourceBase:



Public Member Functions

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from GNSSBlockInterface

- virtual `size_t` `item_size` ()=0
- virtual void `connect` (gr::top_block_sptr top_block)=0
- virtual void `disconnect` (gr::top_block_sptr top_block)=0
- virtual gr::basic_block_sptr `get_right_block` ()=0
- virtual gr::basic_block_sptr `get_left_block` (int RF_channel)
- virtual gr::basic_block_sptr `get_right_block` (int RF_channel)
- virtual void `start` ()

Start the flow of samples if needed.

Protected Member Functions

- `SignalSourceBase` (`ConfigurationInterface` const *configuration, std::string role, std::string impl)
Constructor.
- `size_t` `decode_item_type` (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_error=false)
utility for decoding passed ".item_type" values

12.398.1 Detailed Description

Definition at line 28 of file `signal_source_base.h`.

12.398.2 Constructor & Destructor Documentation

12.398.2.1 SignalSourceBase()

```
SignalSourceBase::SignalSourceBase (
    ConfigurationInterface const * configuration,
    std::string role,
    std::string impl) [protected]
```

Constructor.

12.398.3 Member Function Documentation

12.398.3.1 decode_item_type()

```
size_t SignalSourceBase::decode_item_type (
    std::string const & item_type,
    bool * is_interleaved = nullptr,
    bool throw_on_error = false) [protected]
```

utility for decoding passed ".item_type" values

Parameters

in	<i>item_type</i>	- user provided string, should be one of the known types
out	<i>is_interleaved</i>	- if non-null, the pointed to memory is updated with whether the data is interleaved I/Q (e.g., ishort)
in	<i>throw_on_error</i>	- if true, throw an exception if the string does not represent a known type

Returns

the size in bytes of the passed type

12.398.3.2 get_left_block()

```
gr::basic_block_sptr SignalSourceBase::get_left_block () [override], [virtual]
```

Implements `GNSSBlockInterface`.

12.398.3.3 getRfChannels()

size_t SignalSourceBase::getRfChannels () const [override], [virtual]
Implements [SignalSourceInterface](#).

12.398.3.4 implementation()

std::string SignalSourceBase::implementation () [final], [virtual]
Implements [GNSSBlockInterface](#).

12.398.3.5 role()

std::string SignalSourceBase::role () [final], [virtual]
Implements [GNSSBlockInterface](#).

The documentation for this class was generated from the following file:

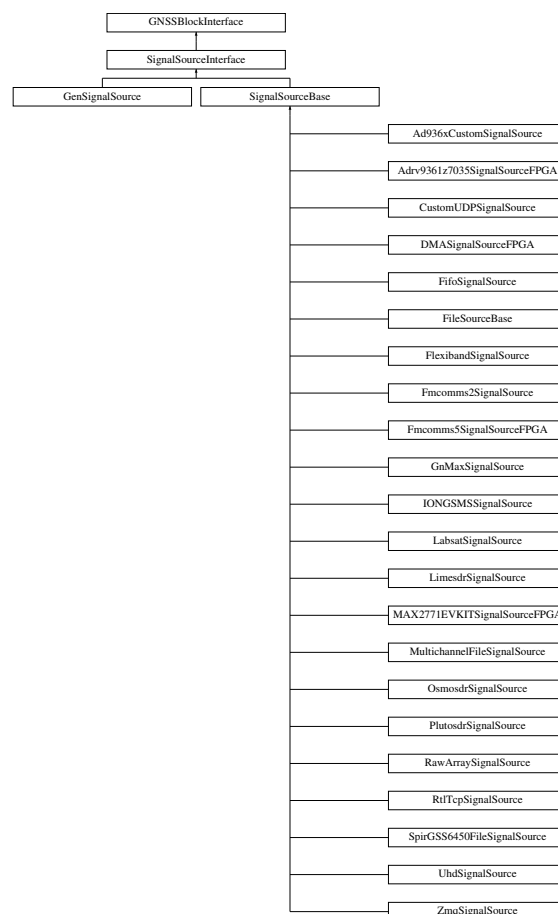
- [signal_source_base.h](#)

12.399 SignalSourceInterface Class Reference

This abstract class represents an interface to signal_source GNSS block.

```
#include <signal_source_interface.h>
```

Inheritance diagram for SignalSourceInterface:



Public Member Functions

- virtual size_t **getRfChannels** () const =0

Public Member Functions inherited from GNSSBlockInterface

- virtual std::string [role](#) ()=0
- virtual std::string [implementation](#) ()=0
- virtual size_t [item_size](#) ()=0
- virtual void [connect](#) (gr::top_block_sptr top_block)=0
- virtual void [disconnect](#) (gr::top_block_sptr top_block)=0
- virtual gr::basic_block_sptr [get_left_block](#) ()=0
- virtual gr::basic_block_sptr [get_right_block](#) ()=0
- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.399.1 Detailed Description

This abstract class represents an interface to signal_source GNSS block.

Abstract class for signal sources. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

Definition at line 51 of file [signal_source_interface.h](#).

The documentation for this class was generated from the following file:

- [signal_source_interface.h](#)

12.400 snrmask_t Struct Reference

Public Attributes

- int [ena](#) [2]
- double [mask](#) [[NFREQ](#)][9]

12.400.1 Detailed Description

Definition at line 936 of file [rtklib.h](#).

12.400.2 Member Data Documentation

12.400.2.1 ena

```
int snrmask_t::ena[2]
```

Definition at line 938 of file [rtklib.h](#).

12.400.2.2 mask

```
double snrmask_t::mask[NFREQ][9]
```

Definition at line 939 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.401 sol_t Struct Reference

Public Attributes

- [gtime_t](#) [time](#)
- double [rr](#) [6]
- float [qr](#) [6]

- double [dtr](#) [6]
- unsigned char [type](#)
- unsigned char [stat](#)
- unsigned char [ns](#)
- float [age](#)
- float [ratio](#)
- float [thres](#)

12.401.1 Detailed Description

Definition at line [820](#) of file [rtklib.h](#).

12.401.2 Member Data Documentation

12.401.2.1 age

```
float sol_t::age
```

Definition at line [832](#) of file [rtklib.h](#).

12.401.2.2 dtr

```
double sol_t::dtr[6]
```

Definition at line [828](#) of file [rtklib.h](#).

12.401.2.3 ns

```
unsigned char sol_t::ns
```

Definition at line [831](#) of file [rtklib.h](#).

12.401.2.4 qr

```
float sol_t::qr[6]
```

Definition at line [825](#) of file [rtklib.h](#).

12.401.2.5 ratio

```
float sol_t::ratio
```

Definition at line [833](#) of file [rtklib.h](#).

12.401.2.6 rr

```
double sol_t::rr[6]
```

Definition at line [823](#) of file [rtklib.h](#).

12.401.2.7 stat

```
unsigned char sol_t::stat
```

Definition at line [830](#) of file [rtklib.h](#).

12.401.2.8 thres

```
float sol_t::thres
```

Definition at line [834](#) of file [rtklib.h](#).

12.401.2.9 time

```
gtime_t sol_t::time
```

Definition at line [822](#) of file [rtklib.h](#).

12.401.2.10 type

`unsigned char sol_t::type`

Definition at line 829 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.402 solbuf_t Struct Reference

Public Attributes

- `int n`
- `int nmax`
- `int cyclic`
- `int start`
- `int end`
- `gtime_t time`
- `sol_t * data`
- `double rb [3]`
- `unsigned char buff [MAXSOLMSG+1]`
- `int nb`

12.402.1 Detailed Description

Definition at line 838 of file [rtklib.h](#).

12.402.2 Member Data Documentation

12.402.2.1 buff

`unsigned char solbuf_t::buff [MAXSOLMSG+1]`

Definition at line 846 of file [rtklib.h](#).

12.402.2.2 cyclic

`int solbuf_t::cyclic`

Definition at line 841 of file [rtklib.h](#).

12.402.2.3 data

`sol_t* solbuf_t::data`

Definition at line 844 of file [rtklib.h](#).

12.402.2.4 end

`int solbuf_t::end`

Definition at line 842 of file [rtklib.h](#).

12.402.2.5 n

`int solbuf_t::n`

Definition at line 840 of file [rtklib.h](#).

12.402.2.6 nb

`int solbuf_t::nb`

Definition at line 847 of file [rtklib.h](#).

12.402.2.7 nmax

```
int solbuf_t::nmax
```

Definition at line 840 of file [rtklib.h](#).

12.402.2.8 rb

```
double solbuf_t::rb[3]
```

Definition at line 845 of file [rtklib.h](#).

12.402.2.9 start

```
int solbuf_t::start
```

Definition at line 842 of file [rtklib.h](#).

12.402.2.10 time

```
gtime_t solbuf_t::time
```

Definition at line 843 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.403 solopt_t Struct Reference

Public Attributes

- int [posf](#)
- int [times](#)
- int [timef](#)
- int [timeu](#)
- int [degf](#)
- int [outhead](#)
- int [outopt](#)
- int [datum](#)
- int [height](#)
- int [geoid](#)
- int [solstatic](#)
- int [sstat](#)
- int [trace](#)
- double [nmeaintv](#) [2]
- char [sep](#) [64]
- char [prog](#) [64]
- double [maxsolstd](#)

12.403.1 Detailed Description

Definition at line 1008 of file [rtklib.h](#).

12.403.2 Member Data Documentation

12.403.2.1 datum

```
int solopt_t::datum
```

Definition at line 1017 of file [rtklib.h](#).

12.403.2.2 degf

```
int solopt_t::degf
```

Definition at line 1014 of file [rtklib.h](#).

12.403.2.3 geoid

`int solopt_t::geoid`

Definition at line 1019 of file [rtklib.h](#).

12.403.2.4 height

`int solopt_t::height`

Definition at line 1018 of file [rtklib.h](#).

12.403.2.5 maxsolstd

`double solopt_t::maxsolstd`

Definition at line 1027 of file [rtklib.h](#).

12.403.2.6 nmeaintv

`double solopt_t::nmeaintv[2]`

Definition at line 1023 of file [rtklib.h](#).

12.403.2.7 outhead

`int solopt_t::outhead`

Definition at line 1015 of file [rtklib.h](#).

12.403.2.8 outopt

`int solopt_t::outopt`

Definition at line 1016 of file [rtklib.h](#).

12.403.2.9 posf

`int solopt_t::posf`

Definition at line 1010 of file [rtklib.h](#).

12.403.2.10 prog

`char solopt_t::prog[64]`

Definition at line 1026 of file [rtklib.h](#).

12.403.2.11 sep

`char solopt_t::sep[64]`

Definition at line 1025 of file [rtklib.h](#).

12.403.2.12 solstatic

`int solopt_t::solstatic`

Definition at line 1020 of file [rtklib.h](#).

12.403.2.13 sstat

`int solopt_t::sstat`

Definition at line 1021 of file [rtklib.h](#).

12.403.2.14 timef

`int solopt_t::timef`

Definition at line 1012 of file [rtklib.h](#).

12.403.2.15 times

```
int solopt_t::times
```

Definition at line 1011 of file [rtklib.h](#).

12.403.2.16 timeu

```
int solopt_t::timeu
```

Definition at line 1013 of file [rtklib.h](#).

12.403.2.17 trace

```
int solopt_t::trace
```

Definition at line 1022 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.404 solstat_t Struct Reference

Public Attributes

- [gtime_t](#) time
- unsigned char sat
- unsigned char frq
- float az
- float el
- float resp
- float resc
- unsigned char flag
- unsigned char snr
- unsigned short lock
- unsigned short outc
- unsigned short slipc
- unsigned short rejc

12.404.1 Detailed Description

Definition at line 851 of file [rtklib.h](#).

12.404.2 Member Data Documentation

12.404.2.1 az

```
float solstat_t::az
```

Definition at line 856 of file [rtklib.h](#).

12.404.2.2 el

```
float solstat_t::el
```

Definition at line 856 of file [rtklib.h](#).

12.404.2.3 flag

```
unsigned char solstat_t::flag
```

Definition at line 859 of file [rtklib.h](#).

12.404.2.4 frq

unsigned char solstat_t::frq
Definition at line 855 of file [rtklib.h](#).

12.404.2.5 lock

unsigned short solstat_t::lock
Definition at line 861 of file [rtklib.h](#).

12.404.2.6 outc

unsigned short solstat_t::outc
Definition at line 862 of file [rtklib.h](#).

12.404.2.7 rejc

unsigned short solstat_t::rejc
Definition at line 864 of file [rtklib.h](#).

12.404.2.8 resc

float solstat_t::resc
Definition at line 858 of file [rtklib.h](#).

12.404.2.9 resp

float solstat_t::resp
Definition at line 857 of file [rtklib.h](#).

12.404.2.10 sat

unsigned char solstat_t::sat
Definition at line 854 of file [rtklib.h](#).

12.404.2.11 slipc

unsigned short solstat_t::slipc
Definition at line 863 of file [rtklib.h](#).

12.404.2.12 snr

unsigned char solstat_t::snr
Definition at line 860 of file [rtklib.h](#).

12.404.2.13 time

[gtime_t](#) solstat_t::time
Definition at line 853 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.405 solstatbuf_t Struct Reference

Public Attributes

- int [n](#)
- int [nmax](#)
- [solstat_t](#) * [data](#)

12.405.1 Detailed Description

Definition at line 868 of file [rtklib.h](#).

12.405.2 Member Data Documentation

12.405.2.1 data

```
solstat_t* solstatbuf_t::data
```

Definition at line 871 of file [rtklib.h](#).

12.405.2.2 n

```
int solstatbuf_t::n
```

Definition at line 870 of file [rtklib.h](#).

12.405.2.3 nmax

```
int solstatbuf_t::nmax
```

Definition at line 870 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

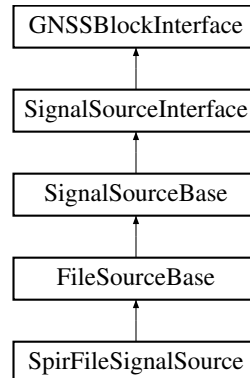
- [rtklib.h](#)

12.406 SpirFileSignalSource Class Reference

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

```
#include <spir_file_signal_source.h>
```

Inheritance diagram for SpirFileSignalSource:



Public Member Functions

- **SpirFileSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue)

Public Member Functions inherited from [FileSourceBase](#)

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- std::string [filename](#) () const
The file to read.
- std::string [item_type](#) () const

The item type.

- `size_t item_size ()` override

The configured size of each item.

- `virtual size_t item_size () const`
- `bool repeat () const`

Whether to repeat reading after end-of-file.

- `int64_t sampling_frequency () const`

The sampling frequency of the source file.

- `uint64_t samples () const`

The number of samples in the file.

Public Member Functions inherited from [SignalSourceBase](#)

- `std::string role ()` final
- `std::string implementation ()` final
- `size_t getRfChannels ()` const override
- `gr::basic_block_sptr get_left_block ()` override

Public Member Functions inherited from [GNSSBlockInterface](#)

- `virtual gr::basic_block_sptr get_left_block (int RF_channel)`
- `virtual gr::basic_block_sptr get_right_block (int RF_channel)`
- `virtual void start ()`

Start the flow of samples if needed.

Protected Member Functions

- `std::tuple< size_t, bool > itemTypeToSize ()` override
- Compute the item size, from the [item_type\(\)](#). Subclasses may constrain types that don't make.*
- `gnss_shared_ptr< gr::block > source ()` const override
- Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.*
- `void create_file_source_hook ()` override
 - `void pre_connect_hook (gr::top_block_sptr top_block)` override
 - `void post_disconnect_hook (gr::top_block_sptr top_block)` override

Protected Member Functions inherited from [FileSourceBase](#)

- [FileSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string const &role, std::string impl, [Concurrent_Queue](#)< pmt::pmt_t > *queue, std::string default_item_type="short")
- Constructor.*
- `void init ()`
- Perform post-construction initialization.*
- `virtual double packetsPerSample () const`
- The number of (possibly unpacked) samples in a (raw) file sample (default=1)*
- `virtual uint64_t samplesToSkip () const`
- Compute the number of samples to skip.*
- `uint64_t computeSamplesInFile () const`
- Compute the number of samples in the file.*
- `virtual size_t source_item_size () const`
- For complex source chains, the size of the file item may not be the same as the size of the.*
- `bool is_complex () const`
 - `gnss_shared_ptr< gr::block > file_source () const`
 - `gnss_shared_ptr< gr::block > valve () const`

- gnss_shared_ptr< gr::block > **throttle** () const
- gnss_shared_ptr< gr::block > **sink** () const
- SensorDataSource::sptr **sensor_data_source** () const
- gr::blocks::file_source::sptr **create_file_source** ()
- gr::blocks::throttle::sptr **create_throttle** ()
- gnss_shared_ptr< gr::block > **create_valve** ()
- gr::blocks::file_sink::sptr **create_sink** ()
- SensorDataSource::sptr **create_sensor_data_source** ()
- virtual void **create_throttle_hook** ()
- virtual void **create_valve_hook** ()
- virtual void **create_sink_hook** ()
- virtual void **post_connect_hook** (gr::top_block_sptr top_block)
- virtual void **pre_disconnect_hook** (gr::top_block_sptr top_block)

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_error=false)
utility for decoding passed ".item_type" values

12.406.1 Detailed Description

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
Definition at line 40 of file [spir_file_signal_source.h](#).

12.406.2 Member Function Documentation

12.406.2.1 create_file_source_hook()

```
void SpirFileSignalSource::create_file_source_hook () [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.406.2.2 itemTypeToSize()

```
std::tuple< size_t, bool > SpirFileSignalSource::itemTypeToSize () [override], [protected], [virtual]
```

Compute the item size, from the [item_type\(\)](#). Subclasses may constrain types that don't make.
Reimplemented from [FileSourceBase](#).

12.406.2.3 post_disconnect_hook()

```
void SpirFileSignalSource::post_disconnect_hook (
    gr::top_block_sptr top_block) [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.406.2.4 pre_connect_hook()

```
void SpirFileSignalSource::pre_connect_hook (
    gr::top_block_sptr top_block) [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.406.2.5 source()

```
gnss_shared_ptr< gr::block > SpirFileSignalSource::source () const [override], [protected], [virtual]
```

Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.

Reimplemented from [FileSourceBase](#).

The documentation for this class was generated from the following file:

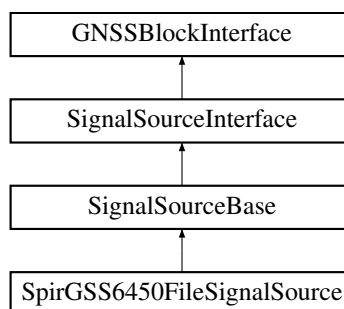
- [spir_file_signal_source.h](#)

12.407 SpirGSS6450FileSignalSource Class Reference

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

```
#include <spir_gss6450_file_signal_source.h>
```

Inheritance diagram for SpirGSS6450FileSignalSource:



Public Member Functions

- **SpirGSS6450FileSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, uint32_t in_streams, uint32_t out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) (int RF_channel) override
- gr::basic_block_sptr [get_right_block](#) () override
- std::string [filename](#) () const
- std::string [item_type](#) () const
- bool [repeat](#) () const
- int64_t [sampling_frequency](#) () const
- uint64_t [samples](#) () const

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_error=false)
utility for decoding passed ".item_type" values

12.407.1 Detailed Description

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
Definition at line 53 of file [spir_gss6450_file_signal_source.h](#).

12.407.2 Member Function Documentation

12.407.2.1 connect()

```
void SpirGSS6450FileSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.407.2.2 disconnect()

```
void SpirGSS6450FileSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.407.2.3 filename()

```
std::string SpirGSS6450FileSignalSource::filename () const [inline]
```

Definition at line 70 of file [spir_gss6450_file_signal_source.h](#).

12.407.2.4 get_left_block()

```
gr::basic_block_sptr SpirGSS6450FileSignalSource::get_left_block () [override], [virtual]
```

Reimplemented from [SignalSourceBase](#).

12.407.2.5 get_right_block() [1/2]

```
gr::basic_block_sptr SpirGSS6450FileSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.407.2.6 get_right_block() [2/2]

```
gr::basic_block_sptr SpirGSS6450FileSignalSource::get_right_block (
    int RF_channel) [override], [virtual]
```

Reimplemented from [GNSSBlockInterface](#).

12.407.2.7 item_size()

```
size_t SpirGSS6450FileSignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).
Definition at line 59 of file [spir_gss6450_file_signal_source.h](#).

12.407.2.8 item_type()

```
std::string SpirGSS6450FileSignalSource::item_type () const [inline]
```

Definition at line 75 of file [spir_gss6450_file_signal_source.h](#).

12.407.2.9 repeat()

`bool SpirGSS6450FileSignalSource::repeat () const [inline]`
 Definition at line 80 of file [spir_gss6450_file_signal_source.h](#).

12.407.2.10 samples()

`uint64_t SpirGSS6450FileSignalSource::samples () const [inline]`
 Definition at line 90 of file [spir_gss6450_file_signal_source.h](#).

12.407.2.11 sampling_frequency()

`int64_t SpirGSS6450FileSignalSource::sampling_frequency () const [inline]`
 Definition at line 85 of file [spir_gss6450_file_signal_source.h](#).

The documentation for this class was generated from the following file:

- [spir_gss6450_file_signal_source.h](#)

12.408 ssat_t Struct Reference**Public Attributes**

- unsigned char [sys](#)
- unsigned char [vs](#)
- double [azel](#) [2]
- double [resp](#) [NFREQ]
- double [resc](#) [NFREQ]
- unsigned char [vsat](#) [NFREQ]
- unsigned char [snr](#) [NFREQ]
- unsigned char [fix](#) [NFREQ]
- unsigned char [slip](#) [NFREQ]
- unsigned char [half](#) [NFREQ]
- int [lock](#) [NFREQ]
- unsigned int [outc](#) [NFREQ]
- unsigned int [slipc](#) [NFREQ]
- unsigned int [rejc](#) [NFREQ]
- double [gf](#)
- double [gf2](#)
- double [mw](#)
- double [phw](#)
- [gtime_t](#) [pt](#) [2][NFREQ]
- double [ph](#) [2][NFREQ]

12.408.1 Detailed Description

Definition at line 1031 of file [rtklib.h](#).

12.408.2 Member Data Documentation**12.408.2.1 azel**

`double ssat_t::azel[2]`
 Definition at line 1035 of file [rtklib.h](#).

12.408.2.2 fix

`unsigned char ssat_t::fix[NFREQ]`
 Definition at line 1040 of file [rtklib.h](#).

12.408.2.3 gf

double ssat_t::gf

Definition at line 1047 of file [rtklib.h](#).

12.408.2.4 gf2

double ssat_t::gf2

Definition at line 1048 of file [rtklib.h](#).

12.408.2.5 half

unsigned char ssat_t::half[NFREQ]

Definition at line 1042 of file [rtklib.h](#).

12.408.2.6 lock

int ssat_t::lock[NFREQ]

Definition at line 1043 of file [rtklib.h](#).

12.408.2.7 mw

double ssat_t::mw

Definition at line 1049 of file [rtklib.h](#).

12.408.2.8 outc

unsigned int ssat_t::outc[NFREQ]

Definition at line 1044 of file [rtklib.h](#).

12.408.2.9 ph

double ssat_t::ph[2][NFREQ]

Definition at line 1052 of file [rtklib.h](#).

12.408.2.10 phw

double ssat_t::phw

Definition at line 1050 of file [rtklib.h](#).

12.408.2.11 pt

gtime_t ssat_t::pt[2][NFREQ]

Definition at line 1051 of file [rtklib.h](#).

12.408.2.12 rejc

unsigned int ssat_t::rejc[NFREQ]

Definition at line 1046 of file [rtklib.h](#).

12.408.2.13 resc

double ssat_t::resc[NFREQ]

Definition at line 1037 of file [rtklib.h](#).

12.408.2.14 resp

double ssat_t::resp[NFREQ]

Definition at line 1036 of file [rtklib.h](#).

12.408.2.15 `slip`

`unsigned char ssat_t::slip[NFREQ]`
Definition at line 1041 of file [rtklib.h](#).

12.408.2.16 `slipc`

`unsigned int ssat_t::slipc[NFREQ]`
Definition at line 1045 of file [rtklib.h](#).

12.408.2.17 `snr`

`unsigned char ssat_t::snr[NFREQ]`
Definition at line 1039 of file [rtklib.h](#).

12.408.2.18 `sys`

`unsigned char ssat_t::sys`
Definition at line 1033 of file [rtklib.h](#).

12.408.2.19 `vs`

`unsigned char ssat_t::vs`
Definition at line 1034 of file [rtklib.h](#).

12.408.2.20 `vsat`

`unsigned char ssat_t::vsat[NFREQ]`
Definition at line 1038 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.409 `ssr_t` Struct Reference

Public Attributes

- [gtime_t](#) `t0` [6]
- double `udi` [6]
- int `iod` [6]
- int `iode`
- int `iodcrc`
- int `ura`
- int `refd`
- double `deph` [3]
- double `ddeph` [3]
- double `dclk` [3]
- double `hrcclk`
- float `cbias` [MAXCODE]
- double `pbias` [MAXCODE]
- float `stdpb` [MAXCODE]
- double `yaw_ang`
- double `yaw_rate`
- unsigned char `update`

12.409.1 Detailed Description

Definition at line 656 of file [rtklib.h](#).

12.409.2 Member Data Documentation

12.409.2.1 cbias

```
float ssr_t::cbias[MAXCODE]
```

Definition at line 669 of file [rtklib.h](#).

12.409.2.2 dclk

```
double ssr_t::dclk[3]
```

Definition at line 667 of file [rtklib.h](#).

12.409.2.3 ddeph

```
double ssr_t::ddeph[3]
```

Definition at line 666 of file [rtklib.h](#).

12.409.2.4 deph

```
double ssr_t::deph[3]
```

Definition at line 665 of file [rtklib.h](#).

12.409.2.5 hrclk

```
double ssr_t::hrclk
```

Definition at line 668 of file [rtklib.h](#).

12.409.2.6 iod

```
int ssr_t::iod[6]
```

Definition at line 660 of file [rtklib.h](#).

12.409.2.7 iodcrc

```
int ssr_t::iodcrc
```

Definition at line 662 of file [rtklib.h](#).

12.409.2.8 iode

```
int ssr_t::iode
```

Definition at line 661 of file [rtklib.h](#).

12.409.2.9 pbias

```
double ssr_t::pbias[MAXCODE]
```

Definition at line 670 of file [rtklib.h](#).

12.409.2.10 refd

```
int ssr_t::refd
```

Definition at line 664 of file [rtklib.h](#).

12.409.2.11 stdpb

```
float ssr_t::stdpb[MAXCODE]
```

Definition at line 671 of file [rtklib.h](#).

12.409.2.12 t0

```
gtime_t ssr_t::t0[6]
```

Definition at line 658 of file [rtklib.h](#).

12.409.2.13 udi

```
double ssr_t::udi[6]
```

Definition at line 659 of file [rtklib.h](#).

12.409.2.14 update

```
unsigned char ssr_t::update
```

Definition at line 673 of file [rtklib.h](#).

12.409.2.15 ura

```
int ssr_t::ura
```

Definition at line 663 of file [rtklib.h](#).

12.409.2.16 yaw_ang

```
double ssr_t::yaw_ang
```

Definition at line 672 of file [rtklib.h](#).

12.409.2.17 yaw_rate

```
double ssr_t::yaw_rate
```

Definition at line 672 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.410 sta_t Struct Reference

Public Attributes

- char [name](#) [[MAXANT](#)]
- char [marker](#) [[MAXANT](#)]
- char [antdes](#) [[MAXANT](#)]
- char [antsno](#) [[MAXANT](#)]
- char [rectype](#) [[MAXANT](#)]
- char [recver](#) [[MAXANT](#)]
- char [recsno](#) [[MAXANT](#)]
- int [antsetup](#)
- int [itr](#)
- int [deltype](#)
- double [pos](#) [3]
- double [del](#) [3]
- double [hgt](#)

12.410.1 Detailed Description

Definition at line 802 of file [rtklib.h](#).

12.410.2 Member Data Documentation

12.410.2.1 antdes

```
char sta_t::antdes [MAXANT]
```

Definition at line 806 of file [rtklib.h](#).

12.410.2.2 antsetup

```
int sta_t::antsetup
```

Definition at line 811 of file [rtklib.h](#).

12.410.2.3 antsno

```
char sta_t::antsno[MAXANT]
```

Definition at line 807 of file [rtklib.h](#).

12.410.2.4 del

```
double sta_t::del[3]
```

Definition at line 815 of file [rtklib.h](#).

12.410.2.5 deltype

```
int sta_t::deltype
```

Definition at line 813 of file [rtklib.h](#).

12.410.2.6 hgt

```
double sta_t::hgt
```

Definition at line 816 of file [rtklib.h](#).

12.410.2.7 itrfr

```
int sta_t::itrfr
```

Definition at line 812 of file [rtklib.h](#).

12.410.2.8 marker

```
char sta_t::marker[MAXANT]
```

Definition at line 805 of file [rtklib.h](#).

12.410.2.9 name

```
char sta_t::name[MAXANT]
```

Definition at line 804 of file [rtklib.h](#).

12.410.2.10 pos

```
double sta_t::pos[3]
```

Definition at line 814 of file [rtklib.h](#).

12.410.2.11 recsno

```
char sta_t::recsno[MAXANT]
```

Definition at line 810 of file [rtklib.h](#).

12.410.2.12 rectype

```
char sta_t::rectype[MAXANT]
```

Definition at line 808 of file [rtklib.h](#).

12.410.2.13 recver

```
char sta_t::recver[MAXANT]
```

Definition at line 809 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.411 stec_t Struct Reference

Public Attributes

- [gtime_t](#) `time`
- unsigned char `sat`
- double `ion`
- float `std`
- float `azel` [2]
- unsigned char `flag`

12.411.1 Detailed Description

Definition at line 722 of file [rtklib.h](#).

12.411.2 Member Data Documentation

12.411.2.1 azel

```
float stec_t::azel[2]
```

Definition at line 728 of file [rtklib.h](#).

12.411.2.2 flag

```
unsigned char stec_t::flag
```

Definition at line 729 of file [rtklib.h](#).

12.411.2.3 ion

```
double stec_t::ion
```

Definition at line 726 of file [rtklib.h](#).

12.411.2.4 sat

```
unsigned char stec_t::sat
```

Definition at line 725 of file [rtklib.h](#).

12.411.2.5 std

```
float stec_t::std
```

Definition at line 727 of file [rtklib.h](#).

12.411.2.6 time

```
gtime\_t stec_t::time
```

Definition at line 724 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.412 stream_cfg Struct Reference

Public Attributes

- int64_t `bw_hz`
- int64_t `fs_hz`
- int64_t `lo_hz`
- const char * `rfport`

12.412.1 Detailed Description

Definition at line 50 of file [ad9361_manager.h](#).

12.412.2 Member Data Documentation

12.412.2.1 bw_hz

```
int64_t stream_cfg::bw_hz
```

Definition at line 52 of file [ad9361_manager.h](#).

12.412.2.2 fs_hz

```
int64_t stream_cfg::fs_hz
```

Definition at line 53 of file [ad9361_manager.h](#).

12.412.2.3 lo_hz

```
int64_t stream_cfg::lo_hz
```

Definition at line 54 of file [ad9361_manager.h](#).

12.412.2.4 rfport

```
const char* stream_cfg::rfport
```

Definition at line 55 of file [ad9361_manager.h](#).

The documentation for this struct was generated from the following file:

- [ad9361_manager.h](#)

12.413 stream_t Struct Reference

Public Attributes

- int [type](#)
- int [mode](#)
- int [state](#)
- unsigned int [inb](#)
- unsigned int [inr](#)
- unsigned int [outb](#)
- unsigned int [outr](#)
- unsigned int [tick](#)
- unsigned int [tact](#)
- unsigned int [inbt](#)
- unsigned int [outbt](#)
- lock_t [lock](#)
- void * [port](#)
- char [path](#) [MAXSTRPATH]
- char [msg](#) [MAXSTRMSG]

12.413.1 Detailed Description

Definition at line 1095 of file [rtklib.h](#).

12.413.2 Member Data Documentation

12.413.2.1 inb

```
unsigned int stream_t::inb
```

Definition at line 1100 of file [rtklib.h](#).

12.413.2.2 inbt

unsigned int stream_t::inbt
Definition at line 1103 of file [rtklib.h](#).

12.413.2.3 inr

unsigned int stream_t::inr
Definition at line 1100 of file [rtklib.h](#).

12.413.2.4 lock

lock_t stream_t::lock
Definition at line 1104 of file [rtklib.h](#).

12.413.2.5 mode

int stream_t::mode
Definition at line 1098 of file [rtklib.h](#).

12.413.2.6 msg

char stream_t::msg[MAXSTRMSG]
Definition at line 1107 of file [rtklib.h](#).

12.413.2.7 outb

unsigned int stream_t::outb
Definition at line 1101 of file [rtklib.h](#).

12.413.2.8 outbt

unsigned int stream_t::outbt
Definition at line 1103 of file [rtklib.h](#).

12.413.2.9 outr

unsigned int stream_t::outr
Definition at line 1101 of file [rtklib.h](#).

12.413.2.10 path

char stream_t::path[MAXSTRPATH]
Definition at line 1106 of file [rtklib.h](#).

12.413.2.11 port

void* stream_t::port
Definition at line 1105 of file [rtklib.h](#).

12.413.2.12 state

int stream_t::state
Definition at line 1099 of file [rtklib.h](#).

12.413.2.13 tact

unsigned int stream_t::tact
Definition at line 1102 of file [rtklib.h](#).

12.413.2.14 tick

unsigned int stream_t::tick
 Definition at line 1102 of file [rtklib.h](#).

12.413.2.15 type

int stream_t::type
 Definition at line 1097 of file [rtklib.h](#).
 The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.414 StringConverter Class Reference

Class that interprets the contents of a string and converts it into different types.
 #include <string_converter.h>

Public Member Functions

- bool **convert** (const std::string &value, bool default_value)
- int64_t **convert** (const std::string &value, int64_t default_value)
- uint64_t **convert** (const std::string &value, uint64_t default_value)
- int32_t **convert** (const std::string &value, int32_t default_value)
- uint32_t **convert** (const std::string &value, uint32_t default_value)
- int16_t **convert** (const std::string &value, int16_t default_value)
- uint16_t **convert** (const std::string &value, uint16_t default_value)
- float **convert** (const std::string &value, float default_value)
- double **convert** (const std::string &value, double default_value)

12.414.1 Detailed Description

Class that interprets the contents of a string and converts it into different types.
 Definition at line 35 of file [string_converter.h](#).
 The documentation for this class was generated from the following file:

- [string_converter.h](#)

12.415 Tag Class Reference**Public Types**

- enum **e_verification_status** { **SUCCESS** , **FAIL** , **UNVERIFIED** }

Public Member Functions

- [Tag](#) (const [MACK_tag_and_info](#) &MTI, uint32_t TOW, uint32_t WN, uint32_t PRNa, uint8_t CTR)
- [Tag](#) (const [MACK_message](#) &mack)

Public Attributes

- const uint32_t [tag_id](#)
- uint32_t [TOW](#)
- uint32_t [WN](#)
- uint32_t [PRNa](#)
- uint8_t [CTR](#)
- e_verification_status [status](#)
- uint64_t [received_tag](#)

- uint64_t [computed_tag](#)
- uint8_t [PRN_d](#)
- uint8_t [ADKD](#)
- uint8_t [cop](#)
- uint32_t [skipped](#)
- std::string [nav_data](#)

Static Public Attributes

- static uint32_t [id_counter](#)

12.415.1 Detailed Description

Definition at line 192 of file [osnma_data.h](#).

12.415.2 Member Enumeration Documentation

12.415.2.1 e_verification_status

enum Tag::e_verification_status

Definition at line 195 of file [osnma_data.h](#).

12.415.3 Constructor & Destructor Documentation

12.415.3.1 Tag() [1/2]

```
Tag::Tag (
    const MACK_tag_and_info & MTI,
    uint32_t TOW,
    uint32_t WN,
    uint32_t PRNa,
    uint8_t CTR) [inline]
```

Definition at line 201 of file [osnma_data.h](#).

12.415.3.2 Tag() [2/2]

```
Tag::Tag (
    const MACK_message & mack) [inline], [explicit]
```

Definition at line 216 of file [osnma_data.h](#).

12.415.4 Member Data Documentation

12.415.4.1 ADKD

uint8_t Tag::ADKD

Definition at line 241 of file [osnma_data.h](#).

12.415.4.2 computed_tag

uint64_t Tag::computed_tag

Definition at line 239 of file [osnma_data.h](#).

12.415.4.3 cop

uint8_t Tag::cop

Definition at line 242 of file [osnma_data.h](#).

12.415.4.4 CTR

uint8_t Tag::CTR

Definition at line 236 of file [osnma_data.h](#).

12.415.4.5 id_counter

```
uint32_t Tag::id_counter [static]
```

Definition at line 232 of file [osnma_data.h](#).

12.415.4.6 nav_data

```
std::string Tag::nav_data
```

Definition at line 244 of file [osnma_data.h](#).

12.415.4.7 PRN_d

```
uint8_t Tag::PRN_d
```

Definition at line 240 of file [osnma_data.h](#).

12.415.4.8 PRNa

```
uint32_t Tag::PRNa
```

Definition at line 235 of file [osnma_data.h](#).

12.415.4.9 received_tag

```
uint64_t Tag::received_tag
```

Definition at line 238 of file [osnma_data.h](#).

12.415.4.10 skipped

```
uint32_t Tag::skipped
```

Definition at line 243 of file [osnma_data.h](#).

12.415.4.11 status

```
e_verification_status Tag::status
```

Definition at line 237 of file [osnma_data.h](#).

12.415.4.12 tag_id

```
const uint32_t Tag::tag_id
```

Definition at line 231 of file [osnma_data.h](#).

12.415.4.13 TOW

```
uint32_t Tag::TOW
```

Definition at line 233 of file [osnma_data.h](#).

12.415.4.14 WN

```
uint32_t Tag::WN
```

Definition at line 234 of file [osnma_data.h](#).

The documentation for this class was generated from the following file:

- [osnma_data.h](#)

12.416 Tcp_Communication Class Reference

TCP communication class.

```
#include <tcp_communication.h>
```


Public Member Functions

- int **listen_tcp_connection** (size_t d_port_, size_t d_port_ch0_)
- void **send_receive_tcp_packet_galileo_e1** (boost::array< float, NUM_TX_VARIABLES_GALILEO_E1 > buf, [Tcp_Packet_Data](#) *tcp_data_)
- void **send_receive_tcp_packet_gps_l1_ca** (boost::array< float, NUM_TX_VARIABLES_GPS_L1_CA > buf, [Tcp_Packet_Data](#) *tcp_data_)
- void **close_tcp_connection** (size_t d_port_)

12.416.1 Detailed Description

TCP communication class.

Definition at line 44 of file [tcp_communication.h](#).

The documentation for this class was generated from the following file:

- [tcp_communication.h](#)

12.417 Tcp_Packet_Data Class Reference

Class that implements a TCP data packet.

#include <tcp_packet_data.h>

Public Attributes

- float [proc_pack_code_error](#) = 0.0
- float [proc_pack_carr_error](#) = 0.0
- float [proc_pack_carrier_doppler_hz](#) = 0.0

12.417.1 Detailed Description

Class that implements a TCP data packet.

Definition at line 30 of file [tcp_packet_data.h](#).

12.417.2 Member Data Documentation**12.417.2.1 proc_pack_carr_error**

float Tcp_Packet_Data::proc_pack_carr_error = 0.0

Definition at line 36 of file [tcp_packet_data.h](#).

12.417.2.2 proc_pack_carrier_doppler_hz

float Tcp_Packet_Data::proc_pack_carrier_doppler_hz = 0.0

Definition at line 37 of file [tcp_packet_data.h](#).

12.417.2.3 proc_pack_code_error

float Tcp_Packet_Data::proc_pack_code_error = 0.0

Definition at line 35 of file [tcp_packet_data.h](#).

The documentation for this class was generated from the following file:

- [tcp_packet_data.h](#)

12.418 tcp_t Struct Reference**Public Attributes**

- int [state](#)
- char [saddr](#) [256]

- int [port](#)
- struct sockaddr_in [addr](#)
- socket_t [sock](#)
- int [tcon](#)
- unsigned int [tact](#)
- unsigned int [tdis](#)

12.418.1 Detailed Description

Definition at line [1142](#) of file [rtklib.h](#).

12.418.2 Member Data Documentation

12.418.2.1 addr

```
struct sockaddr_in tcp_t::addr
```

Definition at line [1147](#) of file [rtklib.h](#).

12.418.2.2 port

```
int tcp_t::port
```

Definition at line [1146](#) of file [rtklib.h](#).

12.418.2.3 saddr

```
char tcp_t::saddr[256]
```

Definition at line [1145](#) of file [rtklib.h](#).

12.418.2.4 sock

```
socket_t tcp_t::sock
```

Definition at line [1148](#) of file [rtklib.h](#).

12.418.2.5 state

```
int tcp_t::state
```

Definition at line [1144](#) of file [rtklib.h](#).

12.418.2.6 tact

```
unsigned int tcp_t::tact
```

Definition at line [1150](#) of file [rtklib.h](#).

12.418.2.7 tcon

```
int tcp_t::tcon
```

Definition at line [1149](#) of file [rtklib.h](#).

12.418.2.8 tdis

```
unsigned int tcp_t::tdis
```

Definition at line [1151](#) of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.419 tcpcli_t Struct Reference

Public Attributes

- [tcp_t](#) `svr`
- `int` [toinact](#)
- `int` [tirecon](#)

12.419.1 Detailed Description

Definition at line 1162 of file [rtklib.h](#).

12.419.2 Member Data Documentation

12.419.2.1 svr

[tcp_t](#) `tcpcli_t::svr`

Definition at line 1164 of file [rtklib.h](#).

12.419.2.2 tirecon

`int` `tcpcli_t::tirecon`

Definition at line 1166 of file [rtklib.h](#).

12.419.2.3 toinact

`int` `tcpcli_t::toinact`

Definition at line 1165 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.420 TcpCmdInterface Class Reference

Public Member Functions

- `void` `run_cmd_server` (`int` `tcp_port`)
- `void` `set_msg_queue` (`std::shared_ptr`< [Concurrent_Queue](#)< `pmt::pmt_t` > > `control_queue`)
- `time_t` `get_utc_time` () `const`
gets the UTC time parsed from the last TC command issued
- `std::array`< `float`, 3 > `get_LLH` () `const`
gets the Latitude, Longitude and Altitude vector from the last TC command issued
- `void` `set_pvt` (`std::shared_ptr`< [PvtInterface](#) > `PVT_sptr`)

12.420.1 Detailed Description

Definition at line 41 of file [tcp_cmd_interface.h](#).

12.420.2 Member Function Documentation

12.420.2.1 get_LLH()

`std::array`< `float`, 3 > `TcpCmdInterface::get_LLH` () `const`

gets the Latitude, Longitude and Altitude vector from the last TC command issued

12.420.2.2 `get_utc_time()`

```
time_t TcpCmdInterface::get_utc_time () const
```

gets the UTC time parsed from the last TC command issued

The documentation for this class was generated from the following file:

- [tcp_cmd_interface.h](#)

12.421 `tcpsvr_t` Struct Reference

Public Attributes

- [tcp_t](#) `svr`
- [tcp_t](#) `cli` [`MAXCLI`]

12.421.1 Detailed Description

Definition at line 1155 of file [rtklib.h](#).

12.421.2 Member Data Documentation

12.421.2.1 `cli`

```
tcp_t tcpsvr_t::cli[MAXCLI]
```

Definition at line 1158 of file [rtklib.h](#).

12.421.2.2 `svr`

```
tcp_t tcpsvr_t::svr
```

Definition at line 1157 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.422 `tec_t` Struct Reference

Public Attributes

- [gtime_t](#) `time`
- int `ndata` [3]
- double `rb`
- double `lats` [3]
- double `lons` [3]
- double `hgts` [3]
- double * `data`
- float * `rms`

12.422.1 Detailed Description

Definition at line 545 of file [rtklib.h](#).

12.422.2 Member Data Documentation

12.422.2.1 `data`

```
double* tec_t::data
```

Definition at line 553 of file [rtklib.h](#).

12.422.2.2 hgts

```
double tec_t::hgts[3]
```

Definition at line 552 of file [rtklib.h](#).

12.422.2.3 lats

```
double tec_t::lats[3]
```

Definition at line 550 of file [rtklib.h](#).

12.422.2.4 lons

```
double tec_t::lons[3]
```

Definition at line 551 of file [rtklib.h](#).

12.422.2.5 ndata

```
int tec_t::ndata[3]
```

Definition at line 548 of file [rtklib.h](#).

12.422.2.6 rb

```
double tec_t::rb
```

Definition at line 549 of file [rtklib.h](#).

12.422.2.7 rms

```
float* tec_t::rms
```

Definition at line 554 of file [rtklib.h](#).

12.422.2.8 time

```
gtime_t tec_t::time
```

Definition at line 547 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

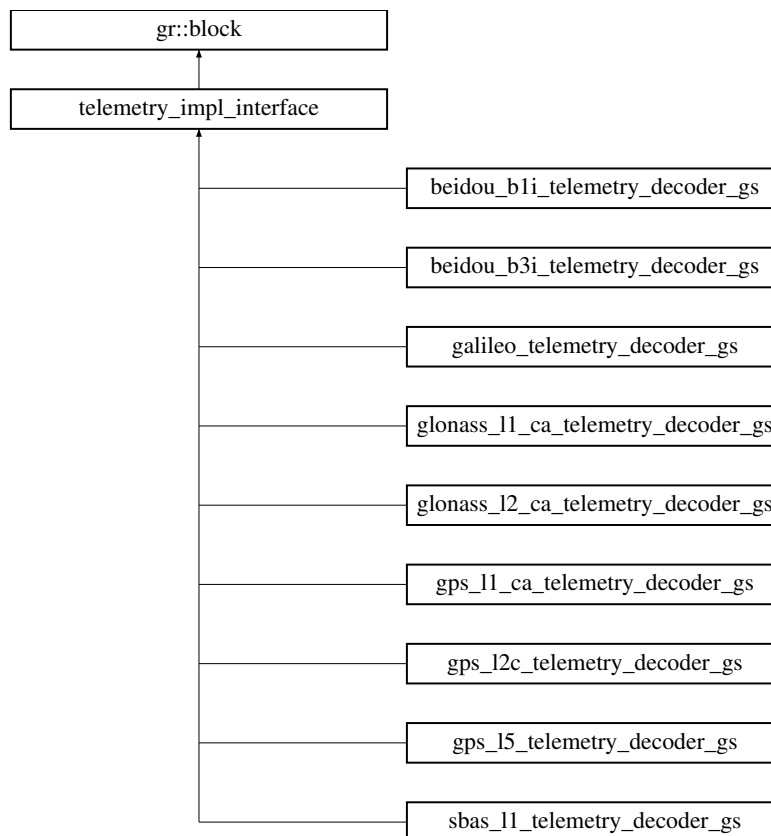
- [rtklib.h](#)

12.423 telemetry_impl_interface Class Reference

Common base class for telemetry decoder GNU Radio implementations.

```
#include <telemetry_impl_interface.h>
```

Inheritance diagram for telemetry_impl_interface:



Public Member Functions

- [telemetry_impl_interface](#) (const std::string &name, gr::io_signature::sptr input_signature, gr::io_signature::sptr output_signature)
- virtual void [set_satellite](#) (const [Gnss_Satellite](#) &satellite)=0
- virtual void [set_channel](#) (int channel)=0
- virtual void [reset](#) ()=0

Protected Member Functions

- void [configure_basic_outputs](#) ()
- void [configure_dump_file](#) (int32_t channel, bool enable_dump, std::string &dump_filename, std::ofstream &dump_file) const
- void [configure_crc_stats_channel](#) (int32_t channel, bool &dump_crc_stats, std::unique_ptr< [Tlm_CRC_Stats](#) > &crc_stats) const

12.423.1 Detailed Description

Common base class for telemetry decoder GNU Radio implementations.

Definition at line 45 of file [telemetry_impl_interface.h](#).

12.423.2 Constructor & Destructor Documentation

12.423.2.1 telemetry_impl_interface()

```

telemetry_impl_interface::telemetry_impl_interface (
    const std::string & name,
    gr::io_signature::sptr input_signature,
    gr::io_signature::sptr output_signature) [inline]

```

Definition at line 48 of file [telemetry_impl_interface.h](#).

12.423.3 Member Function Documentation

12.423.3.1 set_channel()

```
virtual void telemetry_impl_interface::set_channel (
    int channel) [pure virtual]
```

Implemented in [beidou_b1i_telemetry_decoder_gs](#), [beidou_b3i_telemetry_decoder_gs](#), and [gps_l1_ca_telemetry_decoder_gs](#).

12.423.3.2 set_satellite()

```
virtual void telemetry_impl_interface::set_satellite (
    const Gnss_Satellite & satellite) [pure virtual]
```

Implemented in [beidou_b1i_telemetry_decoder_gs](#), [beidou_b3i_telemetry_decoder_gs](#), [galileo_telemetry_decoder_gs](#), [glonass_l1_ca_telemetry_decoder_gs](#), [glonass_l2_ca_telemetry_decoder_gs](#), [gps_l1_ca_telemetry_decoder_gs](#), [gps_l2c_telemetry_decoder_gs](#), [gps_l5_telemetry_decoder_gs](#), and [sbas_l1_telemetry_decoder_gs](#).

The documentation for this class was generated from the following file:

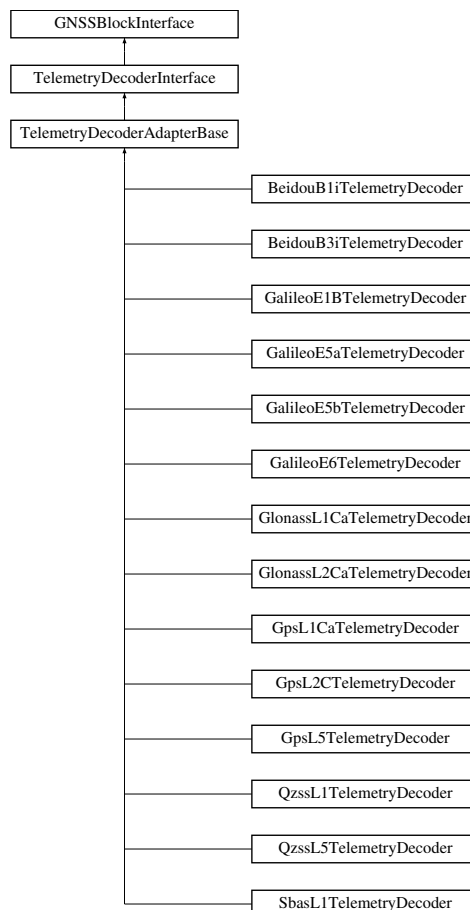
- [telemetry_impl_interface.h](#)

12.424 TelemetryDecoderAdapterBase Class Reference

Base class for Telemetry Decoder adapters.

```
#include <telemetry_decoder_adapter_base.h>
```

Inheritance diagram for TelemetryDecoderAdapterBase:



Public Member Functions

- **TelemetryDecoderAdapterBase** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams)

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- void [set_satellite](#) (const [Gnss_Satellite](#) &satellite) override
- std::string [role](#) () override
- void [set_channel](#) (int channel) override
- void [reset](#) () override
- size_t [item_size](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual std::string [implementation](#) ()=0
- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Protected Member Functions

- void **InitializeDecoder** (telemetry_impl_interface_sptr decoder)
- const [Gnss_Satellite](#) & **satellite** () const

Protected Attributes

- [Tlm_Conf](#) tlm_parameters_

12.424.1 Detailed Description

Base class for Telemetry Decoder adapters.

Definition at line 42 of file [telemetry_decoder_adapter_base.h](#).

12.424.2 Member Function Documentation

12.424.2.1 connect()

```
void TelemetryDecoderAdapterBase::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.424.2.2 disconnect()

```
void TelemetryDecoderAdapterBase::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.424.2.3 get_left_block()

```
gr::basic_block_sptr TelemetryDecoderAdapterBase::get_left_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.424.2.4 get_right_block()

```
gr::basic_block_sptr TelemetryDecoderAdapterBase::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.424.2.5 item_size()

size_t TelemetryDecoderAdapterBase::item_size () [override], [virtual]
Implements [GNSSBlockInterface](#).

12.424.2.6 reset()

void TelemetryDecoderAdapterBase::reset () [override], [virtual]
Implements [TelemetryDecoderInterface](#).

12.424.2.7 role()

std::string TelemetryDecoderAdapterBase::role () [override], [virtual]
Implements [GNSSBlockInterface](#).

12.424.2.8 set_channel()

void TelemetryDecoderAdapterBase::set_channel (
int channel) [override], [virtual]
Implements [TelemetryDecoderInterface](#).

12.424.2.9 set_satellite()

void TelemetryDecoderAdapterBase::set_satellite (
const [Gnss_Satellite](#) & satellite) [override], [virtual]
Implements [TelemetryDecoderInterface](#).

12.424.3 Member Data Documentation

12.424.3.1 tlm_parameters_

[Tlm_Conf](#) TelemetryDecoderAdapterBase::tlm_parameters_ [protected]
Definition at line 75 of file [telemetry_decoder_adapter_base.h](#).

The documentation for this class was generated from the following file:

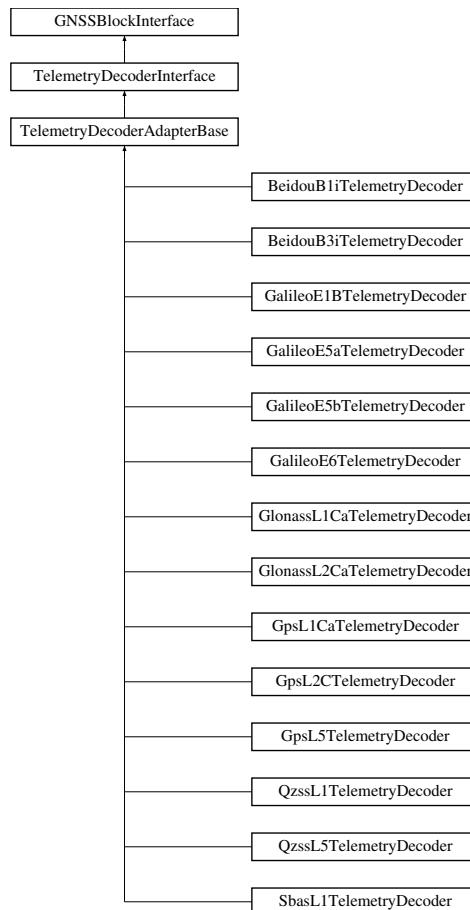
- [telemetry_decoder_adapter_base.h](#)

12.425 TelemetryDecoderInterface Class Reference

This abstract class represents an interface to a navigation GNSS block.

```
#include <telemetry_decoder_interface.h>
```

Inheritance diagram for TelemetryDecoderInterface:



Public Member Functions

- virtual void **reset** ()=0
- virtual void **set_satellite** (const [Gnss_Satellite](#) &sat)=0
- virtual void **set_channel** (int channel)=0

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual std::string **role** ()=0
- virtual std::string **implementation** ()=0
- virtual size_t **item_size** ()=0
- virtual void **connect** (gr::top_block_sptr top_block)=0
- virtual void **disconnect** (gr::top_block_sptr top_block)=0
- virtual gr::basic_block_sptr **get_left_block** ()=0
- virtual gr::basic_block_sptr **get_right_block** ()=0
- virtual gr::basic_block_sptr **get_left_block** (int RF_channel)
- virtual gr::basic_block_sptr **get_right_block** (int RF_channel)
- virtual void **start** ()

Start the flow of samples if needed.

12.425.1 Detailed Description

This abstract class represents an interface to a navigation GNSS block.

Abstract class for navigation interfaces. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

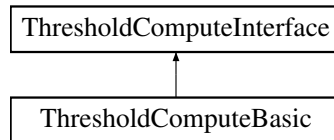
Definition at line 43 of file [telemetry_decoder_interface.h](#).

The documentation for this class was generated from the following file:

- [telemetry_decoder_interface.h](#)

12.426 ThresholdComputeBasic Class Reference

Inheritance diagram for ThresholdComputeBasic:



Public Member Functions

- float [calculate_threshold](#) (const [Acq_Conf](#) &acq_parameters) const override

12.426.1 Detailed Description

Definition at line 46 of file [base_pcps_acquisition_custom.h](#).

12.426.2 Member Function Documentation

12.426.2.1 calculate_threshold()

```
float ThresholdComputeBasic::calculate_threshold (
    const Acq\_Conf & acq_parameters) const [override], [virtual]
```

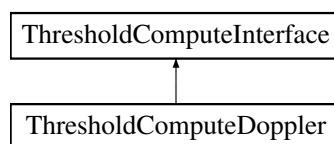
Implements [ThresholdComputeInterface](#).

The documentation for this class was generated from the following file:

- [base_pcps_acquisition_custom.h](#)

12.427 ThresholdComputeDoppler Class Reference

Inheritance diagram for ThresholdComputeDoppler:



Public Member Functions

- float [calculate_threshold](#) (const [Acq_Conf](#) &acq_parameters) const override

12.427.1 Detailed Description

Definition at line 52 of file [base_pcps_acquisition_custom.h](#).

12.427.2 Member Function Documentation

12.427.2.1 calculate_threshold()

```
float ThresholdComputeDoppler::calculate_threshold (
    const Acq\_Conf & acq_parameters) const [override], [virtual]
```

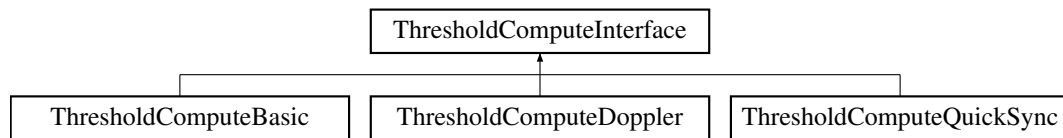
Implements [ThresholdComputeInterface](#).

The documentation for this class was generated from the following file:

- [base_pcps_acquisition_custom.h](#)

12.428 ThresholdComputeInterface Class Reference

Inheritance diagram for ThresholdComputeInterface:



Public Member Functions

- virtual float **calculate_threshold** (const [Acq_Conf](#) &acq_parameters) const =0

12.428.1 Detailed Description

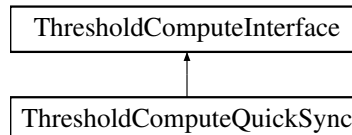
Definition at line 40 of file [base_pcps_acquisition_custom.h](#).

The documentation for this class was generated from the following file:

- [base_pcps_acquisition_custom.h](#)

12.429 ThresholdComputeQuickSync Class Reference

Inheritance diagram for ThresholdComputeQuickSync:



Public Member Functions

- **ThresholdComputeQuickSync** (uint32_t folding_factor)
- float **calculate_threshold** (const [Acq_Conf](#) &acq_parameters) const override

12.429.1 Detailed Description

Definition at line 58 of file [base_pcps_acquisition_custom.h](#).

12.429.2 Member Function Documentation

12.429.2.1 calculate_threshold()

```
float ThresholdComputeQuickSync::calculate_threshold (
    const Acq\_Conf & acq_parameters) const [override], [virtual]
```

Implements [ThresholdComputeInterface](#).

The documentation for this class was generated from the following file:

- [base_pcps_acquisition_custom.h](#)

12.430 tle_t Struct Reference

Public Attributes

- int [n](#)
- int [nmax](#)
- [tled_t](#) * [data](#)

12.430.1 Detailed Description

Definition at line [538](#) of file [rtklib.h](#).

12.430.2 Member Data Documentation

12.430.2.1 data

```
tled\_t* tle_t::data
```

Definition at line [541](#) of file [rtklib.h](#).

12.430.2.2 n

```
int tle_t::n
```

Definition at line [540](#) of file [rtklib.h](#).

12.430.2.3 nmax

```
int tle_t::nmax
```

Definition at line [540](#) of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.431 tled_t Struct Reference

Public Attributes

- char [name](#) [32]
- char [alias](#) [32]
- char [satno](#) [16]
- char [satclass](#)
- char [desig](#) [16]
- [gtime_t](#) [epoch](#)
- double [ndot](#)
- double [nddot](#)
- double [bstar](#)
- int [etype](#)
- int [eleno](#)
- double [inc](#)
- double [OMG](#)
- double [ecc](#)
- double [omg](#)
- double [M](#)
- double [n](#)
- int [rev](#)

12.431.1 Detailed Description

Definition at line [515](#) of file [rtklib.h](#).

12.431.2 Member Data Documentation

12.431.2.1 alias

```
char tled_t::alias[32]
```

Definition at line 518 of file [rtklib.h](#).

12.431.2.2 bstar

```
double tled_t::bstar
```

Definition at line 525 of file [rtklib.h](#).

12.431.2.3 desig

```
char tled_t::desig[16]
```

Definition at line 521 of file [rtklib.h](#).

12.431.2.4 ecc

```
double tled_t::ecc
```

Definition at line 530 of file [rtklib.h](#).

12.431.2.5 eleno

```
int tled_t::eleno
```

Definition at line 527 of file [rtklib.h](#).

12.431.2.6 epoch

```
gtime_t tled_t::epoch
```

Definition at line 522 of file [rtklib.h](#).

12.431.2.7 etype

```
int tled_t::etype
```

Definition at line 526 of file [rtklib.h](#).

12.431.2.8 inc

```
double tled_t::inc
```

Definition at line 528 of file [rtklib.h](#).

12.431.2.9 M

```
double tled_t::M
```

Definition at line 532 of file [rtklib.h](#).

12.431.2.10 n

```
double tled_t::n
```

Definition at line 533 of file [rtklib.h](#).

12.431.2.11 name

```
char tled_t::name[32]
```

Definition at line 517 of file [rtklib.h](#).

12.431.2.12 nddot

```
double tled_t::nddot
```

Definition at line 524 of file [rtklib.h](#).

12.431.2.13 ndot

```
double tled_t::ndot
```

Definition at line 523 of file [rtklib.h](#).

12.431.2.14 OMG

```
double tled_t::OMG
```

Definition at line 529 of file [rtklib.h](#).

12.431.2.15 omg

```
double tled_t::omg
```

Definition at line 531 of file [rtklib.h](#).

12.431.2.16 rev

```
int tled_t::rev
```

Definition at line 534 of file [rtklib.h](#).

12.431.2.17 satclass

```
char tled_t::satclass
```

Definition at line 520 of file [rtklib.h](#).

12.431.2.18 satno

```
char tled_t::satno[16]
```

Definition at line 519 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.432 Tlm_Conf Class Reference

Public Member Functions

- void **SetFromConfiguration** (const [ConfigurationInterface](#) *configuration, const std::string &role)

Public Attributes

- std::string [dump_filename](#)
- std::string [dump_crc_stats_filename](#)
- bool [dump](#) {false}
- bool [dump_mat](#) {false}
- bool [remove_dat](#) {false}
- bool [enable_reed_solomon](#) {false}
- bool [dump_crc_stats](#) {false}
- bool [enable_navdata_monitor](#) {false}
- bool [there_are_e1_channels](#) {false}
- bool [there_are_e6_channels](#) {false}
- bool [use_ced](#) {false}
- bool [tow_to_trk](#) {false}

12.432.1 Detailed Description

Definition at line 30 of file [tlm_conf.h](#).

12.432.2 Member Data Documentation

12.432.2.1 dump

```
bool Tlm_Conf::dump {false}
```

Definition at line 39 of file [tlm_conf.h](#).

12.432.2.2 dump_crc_stats

```
bool Tlm_Conf::dump_crc_stats {false}
```

Definition at line 43 of file [tlm_conf.h](#).

12.432.2.3 dump_crc_stats_filename

```
std::string Tlm_Conf::dump_crc_stats_filename
```

Definition at line 38 of file [tlm_conf.h](#).

12.432.2.4 dump_filename

```
std::string Tlm_Conf::dump_filename
```

Definition at line 37 of file [tlm_conf.h](#).

12.432.2.5 dump_mat

```
bool Tlm_Conf::dump_mat {false}
```

Definition at line 40 of file [tlm_conf.h](#).

12.432.2.6 enable_navdata_monitor

```
bool Tlm_Conf::enable_navdata_monitor {false}
```

Definition at line 44 of file [tlm_conf.h](#).

12.432.2.7 enable_reed_solomon

```
bool Tlm_Conf::enable_reed_solomon {false}
```

Definition at line 42 of file [tlm_conf.h](#).

12.432.2.8 remove_dat

```
bool Tlm_Conf::remove_dat {false}
```

Definition at line 41 of file [tlm_conf.h](#).

12.432.2.9 there_are_e1_channels

```
bool Tlm_Conf::there_are_e1_channels {false}
```

Definition at line 45 of file [tlm_conf.h](#).

12.432.2.10 there_are_e6_channels

```
bool Tlm_Conf::there_are_e6_channels {false}
```

Definition at line 46 of file [tlm_conf.h](#).

12.432.2.11 tow_to_trk

```
bool Tlm_Conf::tow_to_trk {false}
```

Definition at line 48 of file [tlm_conf.h](#).

12.432.2.12 use_ced

```
bool Tlm_Conf::use_ced {false}
```

Definition at line 47 of file [tlm_conf.h](#).

The documentation for this class was generated from the following file:

- [tlm_conf.h](#)

12.433 Tlm_CRC_Stats Class Reference

Class that computes the telemetry CRC statistics.

```
#include <tlm_crc_stats.h>
```

Public Member Functions

- void [initialize](#) (std::string dump_crc_stats_filename)
Initialize the telemetry CRC statistics.
- bool [set_channel](#) (int32_t channel)
Initialize the channel number and output file.
- void [update_CRC_stats](#) (bool CRC)
Update the CRC statistics.

12.433.1 Detailed Description

Class that computes the telemetry CRC statistics.

Definition at line 32 of file [tlm_crc_stats.h](#).

12.433.2 Member Function Documentation

12.433.2.1 initialize()

```
void Tlm_CRC_Stats::initialize (  
    std::string dump_crc_stats_filename)
```

Initialize the telemetry CRC statistics.

12.433.2.2 set_channel()

```
bool Tlm_CRC_Stats::set_channel (  
    int32_t channel)
```

Initialize the channel number and output file.

12.433.2.3 update_CRC_stats()

```
void Tlm_CRC_Stats::update_CRC_stats (  
    bool CRC)
```

Update the CRC statistics.

The documentation for this class was generated from the following file:

- [tlm_crc_stats.h](#)

12.434 TOW_to_trk Class Reference

Public Member Functions

- [TOW_to_trk](#) (const std::string &sig, int32_t ch, uint32_t t, uint64_t stamp, int32_t w, uint32_t p)

Public Attributes

- `std::string` [signal](#)
- `int32_t` [channel](#) {0}
- `uint32_t` [tow](#) {0}
- `uint64_t` [sample_stamp](#) {0}
- `int32_t` [wn](#) {0}
- `uint32_t` [prn](#) {0}

12.434.1 Detailed Description

Definition at line 29 of file [tow_to_trk.h](#).

12.434.2 Constructor & Destructor Documentation

12.434.2.1 TOW_to_trk()

```
TOW_to_trk::TOW_to_trk (  
    const std::string & sig,  
    int32_t ch,  
    uint32_t t,  
    uint64_t stamp,  
    int32_t w,  
    uint32_t p) [inline]
```

Definition at line 35 of file [tow_to_trk.h](#).

12.434.3 Member Data Documentation

12.434.3.1 channel

```
int32_t TOW_to_trk::channel {0}
```

Definition at line 39 of file [tow_to_trk.h](#).

12.434.3.2 prn

```
uint32_t TOW_to_trk::prn {0}
```

Definition at line 43 of file [tow_to_trk.h](#).

12.434.3.3 sample_stamp

```
uint64_t TOW_to_trk::sample_stamp {0}
```

Definition at line 41 of file [tow_to_trk.h](#).

12.434.3.4 signal

```
std::string TOW_to_trk::signal
```

Definition at line 38 of file [tow_to_trk.h](#).

12.434.3.5 tow

```
uint32_t TOW_to_trk::tow {0}
```

Definition at line 40 of file [tow_to_trk.h](#).

12.434.3.6 wn

```
int32_t TOW_to_trk::wn {0}
```

Definition at line 42 of file [tow_to_trk.h](#).

The documentation for this class was generated from the following file:

- [tow_to_trk.h](#)

12.435 Tracking_2nd_DLL_filter Class Reference

This class implements a 2nd order DLL filter for code tracking loop.

```
#include <tracking_2nd_DLL_filter.h>
```

Public Member Functions

- **Tracking_2nd_DLL_filter** (float pdi_code)
- void **set_DLL_BW** (float dll_bw_hz)
Set DLL filter bandwidth [Hz].
- void **set_pdi** (float pdi_code)
Set Summation interval for code [s].
- void **initialize** ()
Start tracking with acquisition information.
- float **get_code_nco** (float DLL_discriminator)
Numerically controlled oscillator.

12.435.1 Detailed Description

This class implements a 2nd order DLL filter for code tracking loop.

The algorithm is described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S. H. Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007, Applied and Numerical Harmonic Analysis.

Definition at line 40 of file [tracking_2nd_DLL_filter.h](#).

12.435.2 Member Function Documentation

12.435.2.1 get_code_nco()

```
float Tracking_2nd_DLL_filter::get_code_nco (
    float DLL_discriminator)
```

Numerically controlled oscillator.

12.435.2.2 initialize()

```
void Tracking_2nd_DLL_filter::initialize ()
```

Start tracking with acquisition information.

12.435.2.3 set_DLL_BW()

```
void Tracking_2nd_DLL_filter::set_DLL_BW (
    float dll_bw_hz)
```

Set DLL filter bandwidth [Hz].

12.435.2.4 set_pdi()

```
void Tracking_2nd_DLL_filter::set_pdi (
    float pdi_code)
```

Set Summation interval for code [s].

The documentation for this class was generated from the following file:

- [tracking_2nd_DLL_filter.h](#)

12.436 Tracking_2nd_PLL_filter Class Reference

This class implements a 2nd order PLL filter for carrier tracking loop.

```
#include <tracking_2nd_PLL_filter.h>
```

Public Member Functions

- **Tracking_2nd_PLL_filter** (float pdi_carr)
- void **set_PLL_BW** (float pll_bw_hz)
Set PLL loop bandwidth [Hz].
- void **set_pdi** (float pdi_carr)
Set Summation interval for code [s].
- void **initialize** ()
- float **get_carrier_nco** (float PLL_discriminator)

12.436.1 Detailed Description

This class implements a 2nd order PLL filter for carrier tracking loop.

The algorithm is described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S. H. Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007, Applied and Numerical Harmonic Analysis.

Definition at line 39 of file [tracking_2nd_PLL_filter.h](#).

12.436.2 Member Function Documentation

12.436.2.1 set_pdi()

```
void Tracking_2nd_PLL_filter::set_pdi (
    float pdi_carr)
```

Set Summation interval for code [s].

12.436.2.2 set_PLL_BW()

```
void Tracking_2nd_PLL_filter::set_PLL_BW (
    float pll_bw_hz)
```

Set PLL loop bandwidth [Hz].

The documentation for this class was generated from the following file:

- [tracking_2nd_PLL_filter.h](#)

12.437 Tracking_FLL_PLL_filter Class Reference

This class implements a hybrid FLL and PLL filter for tracking carrier loop.

```
#include <tracking_FLL_PLL_filter.h>
```

Public Member Functions

- void **set_params** (float fll_bw_hz, float pll_bw_hz, int order)
- void **initialize** (float d_acq_carrier_doppler_hz)
- float **get_carrier_error** (float FLL_discriminator, float PLL_discriminator, float correlation_time_s)

12.437.1 Detailed Description

This class implements a hybrid FLL and PLL filter for tracking carrier loop.

Definition at line 29 of file [tracking_FLL_PLL_filter.h](#).

The documentation for this class was generated from the following file:

- [tracking_FLL_PLL_filter.h](#)

12.438 Tracking_loop_filter Class Reference

This class implements a generic 1st, 2nd or 3rd order loop filter.

```
#include <tracking_loop_filter.h>
```

Public Member Functions

- **Tracking_loop_filter** (float update_interval, float noise_bandwidth, int loop_order=2, bool include_last_integrator=false)
- **Tracking_loop_filter** (**Tracking_loop_filter** &&)=default
Move operator.
- **Tracking_loop_filter** & **operator=** (**Tracking_loop_filter** &&)=default
Move assignment operator.
- float **get_noise_bandwidth** () const
- float **get_update_interval** () const
- bool **get_include_last_integrator** () const
- int **get_order** () const
- void **set_noise_bandwidth** (float noise_bandwidth)
- void **set_update_interval** (float update_interval)
- void **set_include_last_integrator** (bool include_last_integrator)
- void **set_order** (int loop_order)
- void **initialize** (float initial_output=0.0)
- float **apply** (float current_input)

12.438.1 Detailed Description

This class implements a generic 1st, 2nd or 3rd order loop filter.
Definition at line 35 of file [tracking_loop_filter.h](#).

12.438.2 Constructor & Destructor Documentation

12.438.2.1 Tracking_loop_filter()

```
Tracking_loop_filter::Tracking_loop_filter (
    Tracking_loop_filter && ) [default]
```

Move operator.

12.438.3 Member Function Documentation

12.438.3.1 operator=()

```
Tracking_loop_filter & Tracking_loop_filter::operator= (
    Tracking_loop_filter && ) [default]
```

Move assignment operator.

The documentation for this class was generated from the following file:

- [tracking_loop_filter.h](#)

12.439 TrackingCmd Class Reference

Public Attributes

- bool [enable_carrier_nco_cmd](#) = false
- bool [enable_code_nco_cmd](#) = false
- double [code_freq_chips](#) = 0.0
- double [carrier_freq_hz](#) = 0.0
- double [carrier_freq_rate_hz_s](#) = 0.0
- uint64_t [sample_counter](#) = 0UL

12.439.1 Detailed Description

Definition at line 28 of file [trackingcmd.h](#).

- virtual void [set_gnss_synchro](#) ([Gnss_Synchro](#) *gnss_synchro)=0
- virtual void [set_channel](#) (unsigned int channel)=0

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual std::string [role](#) ()=0
- virtual std::string [implementation](#) ()=0
- virtual size_t [item_size](#) ()=0
- virtual void [connect](#) (gr::top_block_sptr top_block)=0
- virtual void [disconnect](#) (gr::top_block_sptr top_block)=0
- virtual gr::basic_block_sptr [get_left_block](#) ()=0
- virtual gr::basic_block_sptr [get_right_block](#) ()=0
- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

12.440.1 Detailed Description

This abstract class represents an interface to a tracking block.

Abstract class for tracking interfaces. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

Definition at line 47 of file [tracking_interface.h](#).

12.440.2 Member Function Documentation

12.440.2.1 [set_channel\(\)](#)

```
virtual void TrackingInterface::set_channel (
    unsigned int channel) [pure virtual]
```

Implemented in [BaseDIIPITracking](#), [BaseDIIPITrackingFpga](#), [GalileoE1TcpConnectorTracking](#), [GpsL1CaDIIPITrackingGPU](#), [GpsL1CaGaussianTracking](#), [GpsL1CaKfTracking](#), and [GpsL1CaTcpConnectorTracking](#).

12.440.2.2 [set_gnss_synchro\(\)](#)

```
virtual void TrackingInterface::set_gnss_synchro (
    Gnss_Synchro * gnss_synchro) [pure virtual]
```

Implemented in [BaseDIIPITracking](#), [BaseDIIPITrackingFpga](#), [GalileoE1TcpConnectorTracking](#), [GpsL1CaDIIPITrackingGPU](#), [GpsL1CaGaussianTracking](#), [GpsL1CaKfTracking](#), and [GpsL1CaTcpConnectorTracking](#).

12.440.2.3 [start_tracking\(\)](#)

```
virtual void TrackingInterface::start_tracking () [pure virtual]
```

Implemented in [BaseDIIPITracking](#), and [BaseDIIPITrackingFpga](#).

12.440.2.4 [stop_tracking\(\)](#)

```
virtual void TrackingInterface::stop_tracking () [pure virtual]
```

Implemented in [BaseDIIPITracking](#), [BaseDIIPITrackingFpga](#), [GalileoE1TcpConnectorTracking](#), [GpsL1CaDIIPITrackingGPU](#), [GpsL1CaGaussianTracking](#), [GpsL1CaKfTracking](#), and [GpsL1CaTcpConnectorTracking](#).

The documentation for this class was generated from the following file:

- [tracking_interface.h](#)

12.441 trop_t Struct Reference

Public Attributes

- [gtime_t](#) `time`
- double `trp` [3]
- float `std` [3]

12.441.1 Detailed Description

Definition at line 733 of file [rtklib.h](#).

12.441.2 Member Data Documentation

12.441.2.1 std

```
float trop_t::std[3]
```

Definition at line 737 of file [rtklib.h](#).

12.441.2.2 time

```
gtime_t trop_t::time
```

Definition at line 735 of file [rtklib.h](#).

12.441.2.3 trp

```
double trop_t::trp[3]
```

Definition at line 736 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

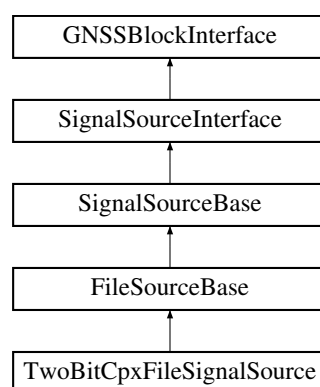
- [rtklib.h](#)

12.442 TwoBitCpxFileSignalSource Class Reference

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

```
#include <two_bit_cpx_file_signal_source.h>
```

Inheritance diagram for TwoBitCpxFileSignalSource:



Public Member Functions

- **TwoBitCpxFileSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue)

Public Member Functions inherited from FileSourceBase

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- std::string [filename](#) () const
The file to read.
- std::string [item_type](#) () const
The item type.
- size_t [item_size](#) () override
The configured size of each item.
- virtual size_t [item_size](#) () const
- bool [repeat](#) () const
Whether to repeat reading after end-of-file.
- int64_t [sampling_frequency](#) () const
The sampling frequency of the source file.
- uint64_t [samples](#) () const
The number of samples in the file.

Public Member Functions inherited from SignalSourceBase

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from GNSSBlockInterface

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()
Start the flow of samples if needed.

Protected Member Functions

- std::tuple< size_t, bool > [itemTypeToSize](#) () override
Compute the item size, from the [item_type](#)(). Subclasses may constrain types that don't make.
- double [packetsPerSample](#) () const override
The number of (possibly unpacked) samples in a (raw) file sample (default=1)
- gnss_shared_ptr< gr::block > [source](#) () const override
Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.
- void [create_file_source_hook](#) () override
- void [pre_connect_hook](#) (gr::top_block_sptr top_block) override
- void [pre_disconnect_hook](#) (gr::top_block_sptr top_block) override

Protected Member Functions inherited from FileSourceBase

- [FileSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string const &role, std::string impl, [Concurrent_Queue](#)< pmt::pmt_t > *queue, std::string default_item_type="short")
Constructor.
- void [init](#) ()
Perform post-construction initialization.

- virtual uint64_t [samplesToSkip](#) () const
Compute the number of samples to skip.
- uint64_t [computeSamplesInFile](#) () const
Compute the number of samples in the file.
- virtual size_t [source_item_size](#) () const
For complex source chains, the size of the file item may not be the same as the size of the.
- bool [is_complex](#) () const
- gnss_shared_ptr< gr::block > [file_source](#) () const
- gnss_shared_ptr< gr::block > [valve](#) () const
- gnss_shared_ptr< gr::block > [throttle](#) () const
- gnss_shared_ptr< gr::block > [sink](#) () const
- SensorDataSource::sptr [sensor_data_source](#) () const
- gr::blocks::file_source::sptr [create_file_source](#) ()
- gr::blocks::throttle::sptr [create_throttle](#) ()
- gnss_shared_ptr< gr::block > [create_valve](#) ()
- gr::blocks::file_sink::sptr [create_sink](#) ()
- SensorDataSource::sptr [create_sensor_data_source](#) ()
- virtual void [create_throttle_hook](#) ()
- virtual void [create_valve_hook](#) ()
- virtual void [create_sink_hook](#) ()
- virtual void [post_connect_hook](#) (gr::top_block_sptr top_block)
- virtual void [post_disconnect_hook](#) (gr::top_block_sptr top_block)

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↵ error=false)
utility for decoding passed ".item_type" values

12.442.1 Detailed Description

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
Definition at line 42 of file [two_bit_cpx_file_signal_source.h](#).

12.442.2 Member Function Documentation

12.442.2.1 [create_file_source_hook\(\)](#)

void TwoBitCpxFileSignalSource::create_file_source_hook () [override], [protected], [virtual]
Reimplemented from [FileSourceBase](#).

12.442.2.2 [itemTypeToSize\(\)](#)

std::tuple< size_t, bool > TwoBitCpxFileSignalSource::itemTypeToSize () [override], [protected], [virtual]
Compute the item size, from the [item_type\(\)](#). Subclasses may constrain types that don't make.
Reimplemented from [FileSourceBase](#).

12.442.2.3 [packetsPerSample\(\)](#)

double TwoBitCpxFileSignalSource::packetsPerSample () const [override], [protected], [virtual]
The number of (possibly unpacked) samples in a (raw) file sample (default=1)
Reimplemented from [FileSourceBase](#).

12.442.2.4 pre_connect_hook()

```
void TwoBitCpxFileSignalSource::pre_connect_hook (
    gr::top_block_sptr top_block) [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.442.2.5 pre_disconnect_hook()

```
void TwoBitCpxFileSignalSource::pre_disconnect_hook (
    gr::top_block_sptr top_block) [override], [protected], [virtual]
```

Reimplemented from [FileSourceBase](#).

12.442.2.6 source()

```
gnss_shared_ptr< gr::block > TwoBitCpxFileSignalSource::source () const [override], [protected],
[virtual]
```

Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.

Reimplemented from [FileSourceBase](#).

The documentation for this class was generated from the following file:

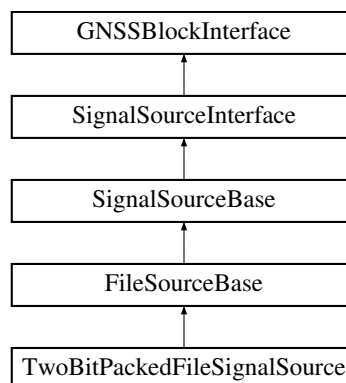
- [two_bit_cpx_file_signal_source.h](#)

12.443 TwoBitPackedFileSignalSource Class Reference

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

```
#include <two_bit_packed_file_signal_source.h>
```

Inheritance diagram for TwoBitPackedFileSignalSource:

**Public Member Functions**

- **TwoBitPackedFileSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_streams, unsigned int out_streams, [Concurrent_Queue](#)< pmt::pmt_t > *queue)

Public Member Functions inherited from [FileSourceBase](#)

- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- std::string [filename](#) () const
The file to read.
- std::string [item_type](#) () const
The item type.

- `size_t item_size ()` override
The configured size of each item.
- virtual `size_t item_size () const`
- bool `repeat () const`
Whether to repeat reading after end-of-file.
- `int64_t sampling_frequency () const`
The sampling frequency of the source file.
- `uint64_t samples () const`
The number of samples in the file.

Public Member Functions inherited from [SignalSourceBase](#)

- `std::string role () final`
- `std::string implementation () final`
- `size_t getRfChannels () const override`
- `gr::basic_block_sptr get_left_block () override`

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual `gr::basic_block_sptr get_left_block (int RF_channel)`
- virtual `gr::basic_block_sptr get_right_block (int RF_channel)`
- virtual void `start ()`
Start the flow of samples if needed.

Protected Member Functions

- `std::tuple< size_t, bool > itemTypeToSize () override`
Compute the item size, from the [item_type\(\)](#). Subclasses may constrain types that don't make.
- double `packetsPerSample () const override`
The number of (possibly unpacked) samples in a (raw) file sample (default=1)
- `gnss_shared_ptr< gr::block > source () const override`
Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.
- void `create_file_source_hook () override`
- void `pre_connect_hook (gr::top_block_sptr top_block) override`
- void `pre_disconnect_hook (gr::top_block_sptr top_block) override`

Protected Member Functions inherited from [FileSourceBase](#)

- [FileSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string const &role, std::string impl, [Concurrent_Queue](#)< pmt::pmt_t > *queue, std::string default_item_type="short")
Constructor.
- void `init ()`
Perform post-construction initialization.
- virtual `uint64_t samplesToSkip () const`
Compute the number of samples to skip.
- `uint64_t computeSamplesInFile () const`
Compute the number of samples in the file.
- virtual `size_t source_item_size () const`
For complex source chains, the size of the file item may not be the same as the size of the.
- bool `is_complex () const`
- `gnss_shared_ptr< gr::block > file_source () const`
- `gnss_shared_ptr< gr::block > valve () const`
- `gnss_shared_ptr< gr::block > throttle () const`

- gnss_shared_ptr< gr::block > **sink** () const
- SensorDataSource::sptr **sensor_data_source** () const
- gr::blocks::file_source::sptr **create_file_source** ()
- gr::blocks::throttle::sptr **create_throttle** ()
- gnss_shared_ptr< gr::block > **create_valve** ()
- gr::blocks::file_sink::sptr **create_sink** ()
- SensorDataSource::sptr **create_sensor_data_source** ()
- virtual void **create_throttle_hook** ()
- virtual void **create_valve_hook** ()
- virtual void **create_sink_hook** ()
- virtual void **post_connect_hook** (gr::top_block_sptr top_block)
- virtual void **post_disconnect_hook** (gr::top_block_sptr top_block)

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_error=false)
utility for decoding passed ".item_type" values

12.443.1 Detailed Description

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).
Definition at line 44 of file [two_bit_packed_file_signal_source.h](#).

12.443.2 Member Function Documentation

12.443.2.1 create_file_source_hook()

void TwoBitPackedFileSignalSource::create_file_source_hook () [override], [protected], [virtual]
Reimplemented from [FileSourceBase](#).

12.443.2.2 itemTypeToSize()

std::tuple< size_t, bool > TwoBitPackedFileSignalSource::itemTypeToSize () [override], [protected], [virtual]
Compute the item size, from the [item_type\(\)](#). Subclasses may constrain types that don't make.
Reimplemented from [FileSourceBase](#).

12.443.2.3 packetsPerSample()

double TwoBitPackedFileSignalSource::packetsPerSample () const [override], [protected], [virtual]
The number of (possibly unpacked) samples in a (raw) file sample (default=1)
Reimplemented from [FileSourceBase](#).

12.443.2.4 pre_connect_hook()

void TwoBitPackedFileSignalSource::pre_connect_hook (gr::top_block_sptr top_block) [override], [protected], [virtual]
Reimplemented from [FileSourceBase](#).

12.443.2.5 pre_disconnect_hook()

void TwoBitPackedFileSignalSource::pre_disconnect_hook (gr::top_block_sptr top_block) [override], [protected], [virtual]
Reimplemented from [FileSourceBase](#).

12.443.2.6 source()

```
gnss_shared_ptr< gr::block > TwoBitPackedFileSignalSource::source () const [override], [protected], [virtual]
```

Abstracted front-end source. Sub-classes may override if they create specialized chains to decode source files into a usable format.

Reimplemented from [FileSourceBase](#).

The documentation for this class was generated from the following file:

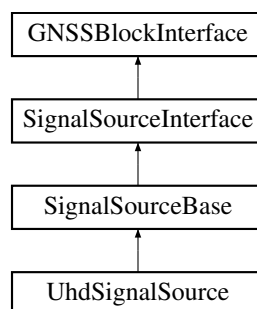
- [two_bit_packed_file_signal_source.h](#)

12.444 UhdSignalSource Class Reference

This class reads samples from a UHD device (see <http://code.ettus.com/redmine/ettus/projects/uhd/wiki>)

```
#include <uhd_signal_source.h>
```

Inheritance diagram for UhdSignalSource:



Public Member Functions

- **UhdSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- void [connect](#) (gr::top_block_sptr top_block) override
- void [disconnect](#) (gr::top_block_sptr top_block) override
- gr::basic_block_sptr [get_left_block](#) () override
- gr::basic_block_sptr [get_right_block](#) () override
- gr::basic_block_sptr [get_right_block](#) (int RF_channel) override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.

- `size_t decode_item_type` (`std::string const &item_type`, `bool *is_interleaved=nullptr`, `bool throw_on_error=false`)

utility for decoding passed ".item_type" values

12.444.1 Detailed Description

This class reads samples from a UHD device (see <http://code.ettus.com/redmine/ettus/projects/uhd/wiki>)
Definition at line 41 of file `uhd_signal_source.h`.

12.444.2 Member Function Documentation

12.444.2.1 connect()

```
void UhdSignalSource::connect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.444.2.2 disconnect()

```
void UhdSignalSource::disconnect (
    gr::top_block_sptr top_block) [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.444.2.3 get_left_block()

```
gr::basic_block_sptr UhdSignalSource::get_left_block () [override], [virtual]
```

Reimplemented from [SignalSourceBase](#).

12.444.2.4 get_right_block() [1/2]

```
gr::basic_block_sptr UhdSignalSource::get_right_block () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.444.2.5 get_right_block() [2/2]

```
gr::basic_block_sptr UhdSignalSource::get_right_block (
    int RF_channel) [override], [virtual]
```

Reimplemented from [GNSSBlockInterface](#).

12.444.2.6 item_size()

```
size_t UhdSignalSource::item_size () [inline], [override], [virtual]
```

Implements [GNSSBlockInterface](#).

Definition at line 50 of file `uhd_signal_source.h`.

The documentation for this class was generated from the following file:

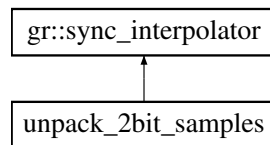
- [uhd_signal_source.h](#)

12.445 unpack_2bit_samples Class Reference

This class takes 2 bit samples that have been packed into bytes or shorts as input and generates a byte for each sample. It generates eight times as much data as is input (every two bits become 16 bits)

```
#include <unpack_2bit_samples.h>
```

Inheritance diagram for `unpack_2bit_samples`:



Public Member Functions

- **unpack_2bit_samples** (bool big_endian_bytes, size_t item_size, bool big_endian_items, bool reverse_interleaving)
- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- unpack_2bit_samples_sptr **make_unpack_2bit_samples_sptr** (bool big_endian_bytes, size_t item_size, bool big_endian_items, bool reverse_interleaving)

12.445.1 Detailed Description

This class takes 2 bit samples that have been packed into bytes or shorts as input and generates a byte for each sample. It generates eight times as much data as is input (every two bits become 16 bits)

Definition at line 84 of file [unpack_2bit_samples.h](#).

The documentation for this class was generated from the following file:

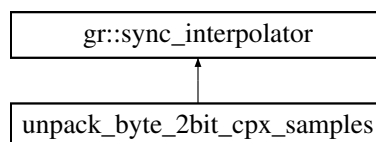
- [unpack_2bit_samples.h](#)

12.446 unpack_byte_2bit_cpx_samples Class Reference

This class implements conversion between byte packet samples to 2bit_cpx samples 1 byte = 2 x complex 2bit I, + 2bit Q samples.

#include <unpack_byte_2bit_cpx_samples.h>

Inheritance diagram for unpack_byte_2bit_cpx_samples:



Public Member Functions

- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- unpack_byte_2bit_cpx_samples_sptr **make_unpack_byte_2bit_cpx_samples_sptr** ()

12.446.1 Detailed Description

This class implements conversion between byte packet samples to 2bit_cpx samples 1 byte = 2 x complex 2bit I, + 2bit Q samples.

Definition at line 44 of file [unpack_byte_2bit_cpx_samples.h](#).

The documentation for this class was generated from the following file:

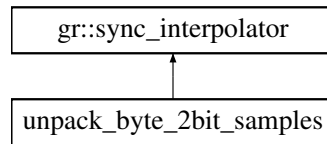
- [unpack_byte_2bit_cpx_samples.h](#)

12.447 unpack_byte_2bit_samples Class Reference

This class implements conversion between byte packet samples to 2bit samples 1 byte = 4 2bit samples.

#include <unpack_byte_2bit_samples.h>

Inheritance diagram for unpack_byte_2bit_samples:



Public Member Functions

- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- unpack_byte_2bit_samples_sptr **make_unpack_byte_2bit_samples_sptr** ()

12.447.1 Detailed Description

This class implements conversion between byte packet samples to 2bit samples 1 byte = 4 2bit samples.

Definition at line 40 of file [unpack_byte_2bit_samples.h](#).

The documentation for this class was generated from the following file:

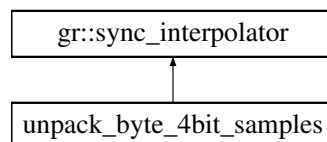
- [unpack_byte_2bit_samples.h](#)

12.448 unpack_byte_4bit_samples Class Reference

This class implements conversion between byte packet samples to 4bit_cpx samples 1 byte = 1 x complex 4bit I, + 4bit Q samples.

#include <unpack_byte_4bit_samples.h>

Inheritance diagram for unpack_byte_4bit_samples:



Public Member Functions

- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- unpack_byte_4bit_samples_sptr **make_unpack_byte_4bit_samples_sptr** ()

12.448.1 Detailed Description

This class implements conversion between byte packet samples to 4bit_cpx samples 1 byte = 1 x complex 4bit I, + 4bit Q samples.

Definition at line 42 of file [unpack_byte_4bit_samples.h](#).

The documentation for this class was generated from the following file:

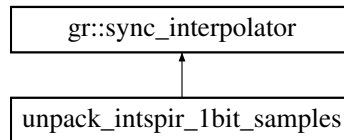
- [unpack_byte_4bit_samples.h](#)

12.449 unpack_intspir_1bit_samples Class Reference

This class implements conversion between byte packet samples to 2bit samples 1 byte = 4 2bit samples.

```
#include <unpack_intspir_1bit_samples.h>
```

Inheritance diagram for `unpack_intspir_1bit_samples`:



Public Member Functions

- `int work` (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- `unpack_intspir_1bit_samples_sptr make_unpack_intspir_1bit_samples_sptr` ()

12.449.1 Detailed Description

This class implements conversion between byte packet samples to 2bit samples 1 byte = 4 2bit samples.

Definition at line 41 of file [unpack_intspir_1bit_samples.h](#).

The documentation for this class was generated from the following file:

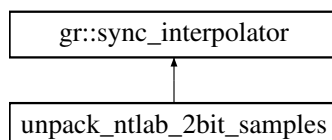
- [unpack_intspir_1bit_samples.h](#)

12.450 unpack_ntlab_2bit_samples Class Reference

This class implements conversion between byte packet multichannel samples to 2bit samples 1 byte = 4 2bit samples.

```
#include <unpack_ntlab_2bit_samples.h>
```

Inheritance diagram for `unpack_ntlab_2bit_samples`:



Public Member Functions

- `unpack_ntlab_2bit_samples` (size_t item_size, int nchannels)
- `int work` (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- `unpack_ntlab_2bit_samples_sptr make_unpack_ntlab_2bit_samples_sptr` (size_t item_size, int nchannels)

12.450.1 Detailed Description

This class implements conversion between byte packet multichannel samples to 2bit samples 1 byte = 4 2bit samples.

Unpack each of the four 2-bit samples in the byte 'b' into four real-valued outputs.

The NTLAB format encodes samples as sign+magnitude pairs in each byte: bits 7-6 = [M0 S0] -> sample 0 bits 5-4 = [M1 S1] -> sample 1 bits 3-2 = [M2 S2] -> sample 2 bits 1-0 = [M3 S3] -> sample 3
M = magnitude bit (1->|sample|=3, 0->|sample|=1) S = sign bit (1->positive, 0->negative)
Definition at line 56 of file [unpack_ntlab_2bit_samples.h](#).

The documentation for this class was generated from the following file:

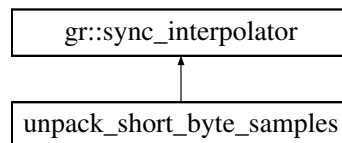
- [unpack_ntlab_2bit_samples.h](#)

12.451 unpack_short_byte_samples Class Reference

This class implements conversion between short packet samples to byte samples 1 short = 2 byte samples.

#include <unpack_short_byte_samples.h>

Inheritance diagram for unpack_short_byte_samples:



Public Member Functions

- void **forecast** (int noutput_items, gr_vector_int &ninput_items_required)
- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- unpack_short_byte_samples_sptr **make_unpack_short_byte_samples_sptr** ()

12.451.1 Detailed Description

This class implements conversion between short packet samples to byte samples 1 short = 2 byte samples.

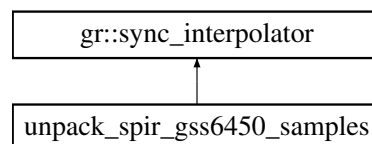
Definition at line 41 of file [unpack_short_byte_samples.h](#).

The documentation for this class was generated from the following file:

- [unpack_short_byte_samples.h](#)

12.452 unpack_spir_gss6450_samples Class Reference

Inheritance diagram for unpack_spir_gss6450_samples:



Public Member Functions

- **unpack_spir_gss6450_samples** (int adc_nbit)
- void **decode_4bits_word** (uint32_t input_uint32, gr_complex *out, int adc_bits_)
- int **work** (int noutput_items, gr_vector_const_void_star &input_items, gr_vector_void_star &output_items)

Friends

- unpack_spir_gss6450_samples_sptr **make_unpack_spir_gss6450_samples_sptr** (int adc_nbit)

12.452.1 Detailed Description

Definition at line 37 of file [unpack_spir_gss6450_samples.h](#).

The documentation for this class was generated from the following file:

- [unpack_spir_gss6450_samples.h](#)

12.453 UnscentedFilter Class Reference

Public Member Functions

- **UnscentedFilter** (int nx)
- **UnscentedFilter** (const arma::vec &x_pred_0, const arma::mat &P_x_pred_0)
- void **initialize** (const arma::mat &x_pred_0, const arma::mat &P_x_pred_0)
- void **predict_sequential** (const arma::vec &x_post, const arma::mat &P_x_post, [ModelFunction](#) *transition←_fcn, const arma::mat &noise_covariance)
- void **update_sequential** (const arma::vec &z_upd, const arma::vec &x_pred, const arma::mat &P_x_pred, [ModelFunction](#) *measurement_fcn, const arma::mat &noise_covariance)
- arma::mat **get_x_pred** () const
- arma::mat **get_P_x_pred** () const
- arma::mat **get_x_est** () const
- arma::mat **get_P_x_est** () const

12.453.1 Detailed Description

Definition at line 83 of file [nonlinear_tracking.h](#).

The documentation for this class was generated from the following file:

- [nonlinear_tracking.h](#)

12.454 url_t Struct Reference

Public Attributes

- char [type](#) [32]
- char [path](#) [1024]
- char [dir](#) [1024]
- double [tint](#)

12.454.1 Detailed Description

Definition at line 908 of file [rtklib.h](#).

12.454.2 Member Data Documentation

12.454.2.1 dir

```
char url_t::dir[1024]
```

Definition at line 912 of file [rtklib.h](#).

12.454.2.2 path

```
char url_t::path[1024]
```

Definition at line 911 of file [rtklib.h](#).

12.454.2.3 tint

```
double url_t::tint
```

Definition at line 913 of file [rtklib.h](#).

12.454.2.4 type

```
char url_t::type[32]
```

Definition at line 910 of file [rtklib.h](#).

The documentation for this struct was generated from the following file:

- [rtklib.h](#)

12.455 v27_decision_t Struct Reference

Public Attributes

- unsigned int [w](#) [2]

12.455.1 Detailed Description

Definition at line 38 of file [fec.h](#).

12.455.2 Member Data Documentation

12.455.2.1 w

```
unsigned int v27_decision_t::w[2]
```

Definition at line 40 of file [fec.h](#).

The documentation for this struct was generated from the following file:

- [fec.h](#)

12.456 v27_poly_t Struct Reference

Public Attributes

- unsigned char [c0](#) [32]
- unsigned char [c1](#) [32]

12.456.1 Detailed Description

Definition at line 32 of file [fec.h](#).

12.456.2 Member Data Documentation

12.456.2.1 c0

```
unsigned char v27_poly_t::c0[32]
```

Definition at line 34 of file [fec.h](#).

12.456.2.2 c1

```
unsigned char v27_poly_t::c1[32]
```

Definition at line 35 of file [fec.h](#).

The documentation for this struct was generated from the following file:

- [fec.h](#)

12.457 v27_t Struct Reference

Public Attributes

- unsigned int [metrics1](#) [64]
- unsigned int [metrics2](#) [64]

- unsigned int * [old_metrics](#)
- unsigned int * [new_metrics](#)
- const [v27_poly_t](#) * [poly](#)
- [v27_decision_t](#) * [decisions](#)
- unsigned int [decisions_index](#)
- unsigned int [decisions_count](#)

12.457.1 Detailed Description

Definition at line [45](#) of file [fec.h](#).

12.457.2 Member Data Documentation

12.457.2.1 decisions

```
v27\_decision\_t* v27_t::decisions
```

Definition at line [52](#) of file [fec.h](#).

12.457.2.2 decisions_count

```
unsigned int v27_t::decisions_count
```

Definition at line [54](#) of file [fec.h](#).

12.457.2.3 decisions_index

```
unsigned int v27_t::decisions_index
```

Definition at line [53](#) of file [fec.h](#).

12.457.2.4 metrics1

```
unsigned int v27_t::metrics1[64]
```

Definition at line [47](#) of file [fec.h](#).

12.457.2.5 metrics2

```
unsigned int v27_t::metrics2[64]
```

Definition at line [48](#) of file [fec.h](#).

12.457.2.6 new_metrics

```
unsigned int * v27_t::new_metrics
```

Definition at line [50](#) of file [fec.h](#).

12.457.2.7 old_metrics

```
unsigned int* v27_t::old_metrics
```

Definition at line [50](#) of file [fec.h](#).

12.457.2.8 poly

```
const v27\_poly\_t* v27_t::poly
```

Definition at line [51](#) of file [fec.h](#).

The documentation for this struct was generated from the following file:

- [fec.h](#)

12.458 Viterbi_Decoder Class Reference

Class that implements a Viterbi decoder.

```
#include <viterbi_decoder.h>
```

Public Member Functions

- [Viterbi_Decoder](#) (int32_t KK, int32_t nn, int32_t LL, const std::array< int32_t, 2 > &g)
Constructor of a Viterbi decoder.
- void [decode](#) (std::vector< int32_t > &output_u_int, const std::vector< float > &input_c)
Uses the Viterbi algorithm to perform hard-decision decoding of a convolutional code.
- void [reset](#) ()
Reset internal status.

12.458.1 Detailed Description

Class that implements a Viterbi decoder.

Definition at line 34 of file [viterbi_decoder.h](#).

12.458.2 Constructor & Destructor Documentation

12.458.2.1 Viterbi_Decoder()

```
Viterbi_Decoder::Viterbi_Decoder (
    int32_t KK,
    int32_t nn,
    int32_t LL,
    const std::array< int32_t, 2 > & g)
```

Constructor of a Viterbi decoder.

Parameters

in	<i>KK</i>	Constraint length
in	<i>nn</i>	Coding rate 1/n
in	<i>LL</i>	Data length
in	<i>g</i>	Polynomial G1 and G2

12.458.3 Member Function Documentation

12.458.3.1 decode()

```
void Viterbi_Decoder::decode (
    std::vector< int32_t > & output_u_int,
    const std::vector< float > & input_c)
```

Uses the Viterbi algorithm to perform hard-decision decoding of a convolutional code.

Parameters

out	<i>output_u_int</i>	Hard decisions on the data bits
in	<i>input_c</i>	The received signal in LLR-form. For BPSK, must be in form $r = 2*a*y/(\sigma^2)$.

12.458.3.2 reset()

```
void Viterbi_Decoder::reset ()
```

Reset internal status.

The documentation for this class was generated from the following file:

- [viterbi_decoder.h](#)

12.459 Viterbi_Decoder_Sbas Class Reference

Class that implements a Viterbi decoder.

```
#include <viterbi_decoder_sbas.h>
```

Public Member Functions

- **Viterbi_Decoder_Sbas** (const int g_encoder[], int KK, int nn)
- void **reset** ()
- float **decode_block** (const double input_c[], int *output_u_int, int LL)
Uses the Viterbi algorithm to perform hard-decision decoding of a convolutional code.
- float **decode_continuous** (const double sym[], int traceback_depth, int bits[], int nbits_requested, int &nbits_decoded)

12.459.1 Detailed Description

Class that implements a Viterbi decoder.

Definition at line 34 of file [viterbi_decoder_sbas.h](#).

12.459.2 Member Function Documentation

12.459.2.1 decode_block()

```
float Viterbi_Decoder_Sbas::decode_block (
    const double input_c[],
    int * output_u_int,
    int LL)
```

Uses the Viterbi algorithm to perform hard-decision decoding of a convolutional code.

Parameters

in	<i>input_c[]</i>	The received signal in LLR-form. For BPSK, must be in form $r = 2*a*y/(\sigma^2)$.
in	<i>LL</i>	The number of data bits to be decoded (does not include the mm zero-tail-bits)

Returns

output_u_int[] Hard decisions on the data bits (without the mm zero-tail-bits)

The documentation for this class was generated from the following file:

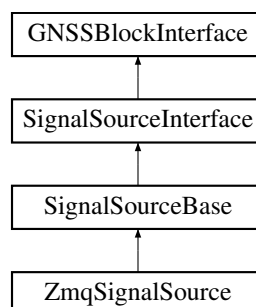
- [viterbi_decoder_sbas.h](#)

12.460 ZmqSignalSource Class Reference

This class supports the following properties:

```
#include <zmq_signal_source.h>
```

Inheritance diagram for ZmqSignalSource:



Public Member Functions

- **ZmqSignalSource** (const [ConfigurationInterface](#) *configuration, const std::string &role, unsigned int in_↔ stream, unsigned int out_stream, [Concurrent_Queue](#)< pmt::pmt_t > *queue)
- size_t [item_size](#) () override
- auto [connect](#) (gr::top_block_sptr top_block) -> void override
- auto [disconnect](#) (gr::top_block_sptr top_block) -> void override
- auto [get_right_block](#) () -> gr::basic_block_sptr override

Public Member Functions inherited from [SignalSourceBase](#)

- std::string [role](#) () final
- std::string [implementation](#) () final
- size_t [getRfChannels](#) () const override
- gr::basic_block_sptr [get_left_block](#) () override

Public Member Functions inherited from [GNSSBlockInterface](#)

- virtual gr::basic_block_sptr [get_left_block](#) (int RF_channel)
- virtual gr::basic_block_sptr [get_right_block](#) (int RF_channel)
- virtual void [start](#) ()

Start the flow of samples if needed.

Additional Inherited Members

Protected Member Functions inherited from [SignalSourceBase](#)

- [SignalSourceBase](#) ([ConfigurationInterface](#) const *configuration, std::string role, std::string impl)
Constructor.
- size_t [decode_item_type](#) (std::string const &item_type, bool *is_interleaved=nullptr, bool throw_on_↔ error=false)
utility for decoding passed ".item_type" values

12.460.1 Detailed Description

This class supports the following properties:

.endpoint - the ZMQ endpoint to be connected to .vlen - vector length of the input items (default 1, one item) this must match the size of the publisher! .pass_tags - boolean flag if tags should be propagated (default false) .timeout_ms - receive timeout, in milliseconds (default 100) .hwm - ZMQ high water mark (default -1, ZMQ default)

.item_type - data type of the samples (default "gr_complex")

(probably should be abstracted to the base class)

.dump - whether to archive input data .dump_filename - if dumping, path to file for output

Definition at line 51 of file [zmq_signal_source.h](#).

12.460.2 Member Function Documentation

12.460.2.1 connect()

```
auto ZmqSignalSource::connect (
    gr::top_block_sptr top_block) -> void [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.460.2.2 disconnect()

```
auto ZmqSignalSource::disconnect (
    gr::top_block_sptr top_block) -> void [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.460.2.3 get_right_block()

```
auto ZmqSignalSource::get_right_block () -> gr::basic_block_sptr [override], [virtual]
```

Implements [GNSSBlockInterface](#).

12.460.2.4 item_size()

```
size_t ZmqSignalSource::item_size () [override], [virtual]
```

Implements [GNSSBlockInterface](#).

The documentation for this class was generated from the following file:

- [zmq_signal_source.h](#)

Chapter 13

File Documentation

13.1 base_pcps_acquisition.h

```
00001 /*!
00002  * \file base_ca_pcps_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface
00004  * \authors <ul>
00005  *         <li> Mathieu Favreau, 2025. favreau.mathieu(at)hotmail.com
00006  *         </ul>
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2025 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_BASE_PCPS_ACQUISITION_H
00020 #define GNSS_SDR_BASE_PCPS_ACQUISITION_H
00021
00022 #include "acq_conf.h"
00023 #include "channel_fsm.h"
00024 #include "complex_byte_to_float_x2.h"
00025 #include "gnss_synchro.h"
00026 #include "pcps_acquisition.h"
00027 #include <gnuradio/blocks/float_to_complex.h>
00028 #include <volk_gnssdr/volk_gnssdr_alloc.h>
00029
00030 /** \addtogroup Acquisition
00031  * Classes for GNSS signal acquisition
00032  * \{ */
00033 /** \addtogroup Acq_adapters acquisition_adapters
00034  * Wrap GNU Radio acquisition blocks with an AcquisitionInterface
00035  * \{ */
00036
00037
00038 class ConfigurationInterface;
00039
00040 /*!
00041  * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00042  */
00043 class BasePcpsAcquisition : public AcquisitionInterface
00044 {
00045 public:
00046     BasePcpsAcquisition(
00047         const ConfigurationInterface* configuration,
00048         const std::string& role,
00049         unsigned int in_streams,
00050         unsigned int out_streams,
00051         double chip_rate,
00052         double opt_freq,
00053         double code_length_chips,
00054         uint32_t ms_per_code);
00055
00056     ~BasePcpsAcquisition() = default;
00057
00058     inline std::string role() override
00059     {
00060         return role_;
00061     }
```

```

00062
00063     inline size_t item_size() override
00064     {
00065         return acq_parameters_.it_size;
00066     }
00067
00068     void connect(gr::top_block_sptr top_block) override;
00069     void disconnect(gr::top_block_sptr top_block) override;
00070     gr::basic_block_sptr get_left_block() override;
00071     gr::basic_block_sptr get_right_block() override;
00072
00073     /*!
00074      * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00075      * to efficiently exchange synchronization data between acquisition and
00076      * tracking blocks
00077      */
00078     void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override;
00079
00080     /*!
00081      * \brief Set acquisition channel unique ID
00082      */
00083     inline void set_channel(unsigned int channel) override
00084     {
00085         acquisition_>set_channel(channel);
00086     }
00087
00088     /*!
00089      * \brief Set channel fsm associated to this acquisition instance
00090      */
00091     inline void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) override
00092     {
00093         acquisition_>set_channel_fsm(std::move(channel_fsm));
00094     }
00095
00096     /*!
00097      * \brief Set Doppler center for the grid search
00098      */
00099     void set_doppler_center(int doppler_center) override;
00100
00101     /*!
00102      * \brief Returns the maximum peak of grid search
00103      */
00104     signed int mag() override;
00105
00106     /*!
00107      * \brief Restart acquisition algorithm
00108      */
00109     void reset() override;
00110
00111     /*!
00112      * \brief Stop running acquisition
00113      */
00114     void stop_acquisition() override;
00115
00116     /*!
00117      * \brief Sets the resampler latency to account it in the acquisition code delay estimation
00118      */
00119     void set_resampler_latency(uint32_t latency_samples) override;
00120
00121     /*!
00122      * \brief Sets local code
00123      */
00124     void set_local_code() override;
00125
00126 private:
00127     /*!
00128      * \brief Generate code
00129      */
00130     virtual void code_gen_complex_sampled(own::span<std::complex<float>> dest, uint32_t prn, int32_t
sampling_freq) = 0;
00131
00132     const Acq_Conf acq_parameters_;
00133     gr::blocks::float_to_complex::sptr float_to_complex_;
00134     complex_byte_to_float_x2_sptr cbyte_to_float_x2_;
00135     Gnss_Synchro* gnss_synchro_;
00136     const std::string role_;
00137     const unsigned int vector_length_;
00138     const unsigned int code_length_;
00139     volk_gnssdr::vector<std::complex<float>> code_;
00140     pcps_acquisition_sptr acquisition_;
00141 };
00142
00143
00144 /** \} */
00145 /** \} */
00146 #endif // GNSS_SDR_BASE_PCPS_ACQUISITION_H

```

13.2 base_pcps_acquisition_custom.h

```

00001  /*!
00002  * \file base_ca_pcps_acquisition_custom.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface
00004  * \authors <ul>
00005  *         <li> Mathieu Favreau, 2025. favreau.mathieu(at)hotmail.com
00006  *         </li>
00007  *         </ul>
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2025 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_BASE_PCPS_ACQUISITION_CUSTOM_H
00020 #define GNSS_SDR_BASE_PCPS_ACQUISITION_CUSTOM_H
00021
00022 #include "acquisition_impl_interface.h"
00023 #include "channel_fsm.h"
00024 #include "gnss_synchro.h"
00025 #include "pcps_acquisition.h"
00026 #include <gnuradio/blocks/stream_to_vector.h>
00027 #include <volk_gnssssdr/volk_gnssssdr_alloc.h>
00028 #include <limits>
00029
00030 /** \addtogroup Acquisition
00031  * Classes for GNSS signal acquisition
00032  * \{ */
00033 /** \addtogroup Acq_adapters acquisition_adapters
00034  * Wrap GNU Radio acquisition blocks with an AcquisitionInterface
00035  * \{ */
00036
00037
00038 class ConfigurationInterface;
00039
00040 class ThresholdComputeInterface
00041 {
00042 public:
00043     virtual float calculate_threshold(const Acq_Conf& acq_parameters) const = 0;
00044 };
00045
00046 class ThresholdComputeBasic : public ThresholdComputeInterface
00047 {
00048 public:
00049     float calculate_threshold(const Acq_Conf& acq_parameters) const override;
00050 };
00051
00052 class ThresholdComputeDoppler : public ThresholdComputeInterface
00053 {
00054 public:
00055     float calculate_threshold(const Acq_Conf& acq_parameters) const override;
00056 };
00057
00058 class ThresholdComputeQuickSync : public ThresholdComputeInterface
00059 {
00060 public:
00061     explicit ThresholdComputeQuickSync(uint32_t folding_factor);
00062
00063     float calculate_threshold(const Acq_Conf& acq_parameters) const override;
00064
00065 private:
00066     const uint32_t folding_factor_;
00067 };
00068
00069 /*!
00070 * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00071 */
00072 class BasePcpsAcquisitionCustom : public AcquisitionInterface
00073 {
00074 public:
00075     BasePcpsAcquisitionCustom(const ConfigurationInterface* configuration,
00076                               const std::string& role,
00077                               unsigned int in_streams,
00078                               unsigned int out_streams,
00079                               double chip_rate,
00080                               double code_length_chips,
00081                               unsigned int ms_per_code,
00082                               bool use_stream_to_vector,
00083                               const ThresholdComputeInterface& threshold_compute,
00084                               uint32_t max_sampled_ms = std::numeric_limits<uint32_t>::max());

```

```

00085
00086     ~BasePcpsAcquisitionCustom() = default;
00087
00088     inline std::string role() override { return role_; }
00089
00090     inline size_t item_size() override { return item_size_; }
00091
00092     void connect(gr::top_block_sptr top_block) override;
00093     void disconnect(gr::top_block_sptr top_block) override;
00094     gr::basic_block_sptr get_left_block() override;
00095     gr::basic_block_sptr get_right_block() override;
00096
00097     /*!
00098      * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00099      * to efficiently exchange synchronization data between acquisition and
00100      * tracking blocks
00101      */
00102     void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override;
00103
00104     /*!
00105      * \brief Set acquisition channel unique ID
00106      */
00107     void set_channel(unsigned int channel) override;
00108
00109     /*!
00110      * \brief Set channel fsm associated to this acquisition instance
00111      */
00112     void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) override;
00113
00114     /*!
00115      * \brief Returns the maximum peak of grid search
00116      */
00117     signed int mag() override;
00118
00119     /*!
00120      * \brief Restart acquisition algorithm
00121      */
00122     void reset() override;
00123
00124     /*!
00125      * \brief Stop running acquisition
00126      */
00127     void stop_acquisition() override;
00128
00129     void set_resampler_latency(uint32_t /*latency_samples*/) override {};
00130
00131     /*!
00132      * \brief Sets local code
00133      */
00134     void set_local_code() override;
00135
00136
00137 protected:
00138     bool is_type_gr_complex() const { return is_type_gr_complex_; }
00139
00140     const Acq_Conf acq_parameters_;
00141     acquisition_impl_interface_sptr acquisition_cc_;
00142     Gnss_Synchro* gnss_synchro_;
00143     unsigned int channel_;
00144     volk_gnssdr::vector<std::complex<float>> code_;
00145
00146 private:
00147     /*!
00148      * \brief Generate code
00149      */
00150     virtual void code_gen_complex_sampled(own::span<std::complex<float>> dest, uint32_t prn, int32_t
sampling_freq) = 0;
00151
00152     gr::blocks::stream_to_vector::sptr stream_to_vector_;
00153     const std::string role_;
00154     const bool is_type_gr_complex_;
00155     const size_t item_size_;
00156     const bool use_stream_to_vector_;
00157 };
00158
00159
00160 /** \} */
00161 /** \} */
00162 #endif // GNSS_SDR_BASE_PCPS_ACQUISITION_H

```

13.3 base_pcps_acquisition_fpga.h File Reference

Shared implementation for FPGA-based PCPS acquisition adapters.

```
#include "acq_conf_fpga.h"
#include "channel_fsm.h"
#include "gnss_synchro.h"
#include "pcps_acquisition_fpga.h"
#include <gnuradio/runtime_types.h>
#include <volk_gnssssdr/volk_gnssssdr_alloc.h>
#include <cstdlib>
#include <stdint>
#include <memory>
#include <string>
```

Classes

- class [BasePcpsAcquisitionFpga](#)

Base class providing shared logic for FPGA-based GPS PCPS acquisition adapters.

13.3.1 Detailed Description

Shared implementation for FPGA-based PCPS acquisition adapters.

Authors

Carles Fernandez, 2025. carles.fernandez(at)cttc.cat

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 Definition in file [base_pcps_acquisition_fpga.h](#).

13.4 base_pcps_acquisition_fpga.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file base_pcps_acquisition_fpga.h
00003  * \brief Shared implementation for FPGA-based PCPS acquisition adapters
00004  * \authors Carles Fernandez, 2025. carles.fernandez(at)cttc.cat
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2025 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_BASE_PCPS_ACQUISITION_FPGA_H
00019 #define GNSS_SDR_BASE_PCPS_ACQUISITION_FPGA_H
00020
00021 #include "acq_conf_fpga.h"
00022 #include "channel_fsm.h"
00023 #include "gnss_synchro.h"
00024 #include "pcps_acquisition_fpga.h"
00025 #include <gnuradio/runtime_types.h> // for basic_block_sptr, top_block_sptr
00026 #include <volk_gnssssdr/volk_gnssssdr_alloc.h>
00027 #include <cstdlib>
00028 #include <stdint>
00029 #include <memory>
00030 #include <string>
00031
00032 /** \addtogroup Acquisition
00033  * Classes for GNSS signal acquisition
00034  * \{ */
00035 /** \addtogroup Acq_adapters acquisition_adapters
00036  * Wrap GNU Radio acquisition blocks with an AcquisitionInterface
00037  * \{ */
00038
00039 class ConfigurationInterface;
00040
```

```

00041  /*!
00042  * \brief Base class providing shared logic for FPGA-based GPS PCPS acquisition adapters.
00043  */
00044  class BasePcpsAcquisitionFpga : public AcquisitionInterface
00045  {
00046  public:
00047      BasePcpsAcquisitionFpga(const ConfigurationInterface* configuration,
00048          std::string role,
00049          double code_rate_cps,
00050          double code_length_chips,
00051          uint32_t opt_acq_fs_sps,
00052          uint32_t default_fpga_blk_exp,
00053          uint32_t acq_buff,
00054          unsigned int in_streams,
00055          unsigned int out_streams);
00056
00057      ~BasePcpsAcquisitionFpga() override = default;
00058
00059      inline std::string role() override final { return role_; }
00060
00061      inline size_t item_size() override { return sizeof(int16_t); }
00062
00063      // Common AcquisitionInterface overrides
00064      void connect(gr::top_block_sptr top_block) override;
00065      void disconnect(gr::top_block_sptr top_block) override;
00066      gr::basic_block_sptr get_left_block() override;
00067      gr::basic_block_sptr get_right_block() override;
00068
00069      signed int mag() override;
00070      void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override;
00071      void set_channel(unsigned int channel) override;
00072      void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) override;
00073      void set_doppler_center(int doppler_center) override;
00074      void reset() override;
00075      void stop_acquisition() override;
00076      void set_resampler_latency(uint32_t latency_samples __attribute__((unused))) override {}
00077      void set_local_code() override;
00078
00079  protected:
00080      // Members subclasses can use
00081      static const uint32_t QUANT_BITS_LOCAL_CODE = 16;
00082      static const uint32_t SELECT_LSBITS = 0x0000FFFF; // Select the 10 LSbits out of a 20-bit
00083      static const uint32_t SELECT_MSBITS = 0xFFFF0000; // Select the 10 MSbits out of a 20-bit
00084      static const uint32_t SELECT_ALL_CODE_BITS = 0xFFFFFFFF; // Select a 20 bit word
00085      static const uint32_t SHL_CODE_BITS = 65536; // shift left by 10 bits
00086      static const uint32_t ACQ_BUFF_0 = 0; // FPGA Acquisition IP buffer containing
00087      // L1/E1 frequency band samples by default.
00088      static const uint32_t ACQ_BUFF_1 = 1; // FPGA Acquisition IP buffer containing
00089      // L2 or L5/E5 frequency band samples by default.
00090
00091      // parameter initialization
00092      void init();
00093
00094      // Members subclasses must set
00095      volk_gnssdr::vector<uint32_t> d_all_fft_codes_;
00096      Acq_Conf_Fpga acq_parameters_;
00097
00098  private:
00099      // Managed entirely by the base class
00100      pcps_acquisition_fpga_sptr acquisition_fpga_;
00101      const std::string role_;
00102  };
00103  /** \} */
00104  /** \} */
00105  #endif // GNSS_SDR_BASE_PCPS_ACQUISITION_FPGA_H

```

13.5 beidou_b1i_pcps_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Beidou B1I signals.

```
#include "base_pcps_acquisition.h"
```

Classes

- class [BeidouB1iPcpsAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

13.5.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Beidou B1I signals.

Authors

- Sergi Segura, 2018. sergi.segura.munoz(at)gmail.com

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 Definition in file [beidou_b1i_pcps_acquisition.h](#).

13.6 beidou_b1i_pcps_acquisition.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file beidou_b1i_pcps_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * Beidou B1I signals
00005  * \authors <ul>
00006  * <li> Sergi Segura, 2018. sergi.segura.munoz(at)gmail.com
00007  * </li>
00008  * </ul>
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  *
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00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_BEIDOU_B1I_PCPS_ACQUISITION_H
00021 #define GNSS_SDR_BEIDOU_B1I_PCPS_ACQUISITION_H
00022
00023 #include "base_pcps_acquisition.h"
00024
00025 /** \addtogroup Acquisition
00026  * \{ */
00027 /** \addtogroup Acq_adapters
00028  * \{ */
00029
00030 /*!
00031 * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00032 * for GPS L1 C/A signals
00033 */
00034 class BeidouB1iPcpsAcquisition : public BasePcpsAcquisition
00035 {
00036 public:
00037     BeidouB1iPcpsAcquisition(const ConfigurationInterface* configuration,
00038                             const std::string& role, unsigned int in_streams,
00039                             unsigned int out_streams);
00040
00041     ~BeidouB1iPcpsAcquisition() = default;
00042
00043     /*!
00044     * \brief Returns "BEIDOU_B1I_PCPS_Acquisition"
00045     */
00046     inline std::string implementation() override
00047     {
00048         return "BEIDOU_B1I_PCPS_Acquisition";
00049     }
00050
00051 private:
00052     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
00053     sampling_freq) override;
00054 };
00055
00056 /** \} */
00057 /** \} */
00058 #endif // GNSS_SDR_BEIDOU_B1I_PCPS_ACQUISITION_H

```

13.7 beidou_b3i_pcps_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Beidou B3I signals.

```
#include "base_pcps_acquisition.h"
```

Classes

- class [BeidouB3iPcpsAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for BeiDou B3I signals.

13.7.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for BeiDou B3I signals.

Author

Damian Miralles, 2019. dmiralles2009@gmail.com

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 Definition in file [beidou_b3i_pcps_acquisition.h](#).

13.8 beidou_b3i_pcps_acquisition.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file beidou_b3i_pcps_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  *        Beidou B3I signals
00005  * \author Damian Miralles, 2019. dmiralles2009@gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_BEIDOU_B3I_PCPS_ACQUISITION_H
00019 #define GNSS_SDR_BEIDOU_B3I_PCPS_ACQUISITION_H
00020
00021 #include "base_pcps_acquisition.h"
00022
00023 /** \addtogroup Acquisition
00024  *  \{ */
00025 /** \addtogroup Acq_adapters
00026  *  \{ */
00027
00028 /*!
00029  * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00030  *        for BeiDou B3I signals
00031  */
00032 class BeidouB3iPcpsAcquisition : public BasePcpsAcquisition
00033 {
00034 public:
00035     BeidouB3iPcpsAcquisition(const ConfigurationInterface* configuration,
00036                             const std::string& role, unsigned int in_streams,
00037                             unsigned int out_streams);
00038
00039     ~BeidouB3iPcpsAcquisition() = default;
00040
00041     /*!
00042     * \brief Returns "BEIDOU_B3I_PCPS_Acquisition"
00043     */
00044     inline std::string implementation() override
00045     {
00046         return "BEIDOU_B3I_PCPS_Acquisition";
00047     }
00048
00049 private:
00050     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
00051                                sampling_freq) override;
00052 };
00053
```

```

00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_BEIDOU_B3I_PCPS_ACQUISITION_H

```

13.9 galileo_e1_pcps_8ms_ambiguous_acquisition.h File Reference

Adapts a PCPS 8ms acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

```
#include "base_pcps_acquisition_custom.h"
```

Classes

- class [GalileoE1Pcps8msAmbiguousAcquisition](#)

Adapts a PCPS 8ms acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

13.9.1 Detailed Description

Adapts a PCPS 8ms acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

Author

Marc Molina, 2013. marc.molina.pena(at)gmail.com

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 Definition in file [galileo_e1_pcps_8ms_ambiguous_acquisition.h](#).

13.10 galileo_e1_pcps_8ms_ambiguous_acquisition.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_e1_pcps_8ms_ambiguous_acquisition.h
00003  * \brief Adapts a PCPS 8ms acquisition block to an
00004  * \brief AcquisitionInterface for Galileo E1 Signals
00005  * \author Marc Molina, 2013. marc.molina.pena(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GALILEO_E1_PCPS_8MS_AMBIGUOUS_ACQUISITION_H
00019 #define GNSS_SDR_GALILEO_E1_PCPS_8MS_AMBIGUOUS_ACQUISITION_H
00020
00021 #include "base_pcps_acquisition_custom.h"
00022
00023 /** \addtogroup Acquisition
00024  * \{ */
00025 /** \addtogroup Acq_adapters
00026  * \{ */
00027
00028 /*!
00029  * \brief Adapts a PCPS 8ms acquisition block to an
00030  * \brief AcquisitionInterface for Galileo E1 Signals
00031  */
00032 class GalileoE1Pcps8msAmbiguousAcquisition : public BasePcpsAcquisitionCustom
00033 {
00034 public:
00035     GalileoE1Pcps8msAmbiguousAcquisition(const ConfigurationInterface* configuration,
00036     const std::string& role,
00037     unsigned int in_streams,
00038     unsigned int out_streams);
00039
00040     ~GalileoE1Pcps8msAmbiguousAcquisition() = default;
00041
00042     /*!
00043     * \brief Returns "Galileo_E1_PCPS_8ms_Ambiguous_Acquisition"

```

```

00044     */
00045     inline std::string implementation() override
00046     {
00047         return "Galileo_E1_PCPS_8ms_Ambiguous_Acquisition";
00048     }
00049
00050 private:
00051     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
sampling_freq) override;
00052
00053     const bool cboc_;
00054 };
00055
00056
00057 /** @} */
00058 /** @} */
00059 #endif // GNSS_SDR_GALILEO_E1_PCPS_8MS_AMBIGUOUS_ACQUISITION_H

```

13.11 galileo_e1_pcps_ambiguous_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

```
#include "base_pcps_acquisition.h"
```

Classes

- class [GalileoE1PcpsAmbiguousAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

13.11.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

Author

Luis Esteve, 2012. luis(at)epsilon-formacion.com

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Definition in file [galileo_e1_pcps_ambiguous_acquisition.h](#).

13.12 galileo_e1_pcps_ambiguous_acquisition.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file galileo_e1_pcps_ambiguous_acquisition.h
00003 * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004 * Galileo E1 Signals
00005 * \author Luis Esteve, 2012. luis(at)epsilon-formacion.com
00006 *
00007 * -----
00008 *
00009 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010 * This file is part of GNSS-SDR.
00011 *
00012 * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013 * SPDX-License-Identifier: GPL-3.0-or-later
00014 *
00015 * -----
00016 */
00017
00018 #ifndef GNSS_SDR_GALILEO_E1_PCPS_AMBIGUOUS_ACQUISITION_H
00019 #define GNSS_SDR_GALILEO_E1_PCPS_AMBIGUOUS_ACQUISITION_H
00020
00021 #include "base_pcps_acquisition.h"
00022
00023 /** \addtogroup Acquisition
00024 * \{ */
00025 /** \addtogroup Acq_adapters
00026 * \{ */
00027
00028
00029 /*!

```

```

00030  * \brief This class adapts a PCPS acquisition block to an
00031  * AcquisitionInterface for Galileo E1 Signals
00032  */
00033 class GalileoE1PcpsAmbiguousAcquisition : public BasePcpsAcquisition
00034 {
00035 public:
00036     GalileoE1PcpsAmbiguousAcquisition(
00037         const ConfigurationInterface* configuration,
00038         const std::string& role,
00039         unsigned int in_streams,
00040         unsigned int out_streams);
00041
00042     ~GalileoE1PcpsAmbiguousAcquisition() = default;
00043
00044     /*!
00045     * \brief Returns "Galileo_E1_PCPS_Ambiguous_Acquisition"
00046     */
00047     inline std::string implementation() override
00048     {
00049         return "Galileo_E1_PCPS_Ambiguous_Acquisition";
00050     }
00051
00052     /*!
00053     * \brief Set acquisition channel unique ID
00054     */
00055     void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override;
00056
00057 private:
00058     void code_gen_complex_sampled(own::span<std::complex<float>> dest, uint32_t prn, int32_t
        sampling_freq) override;
00059
00060     const bool acquire_pilot_;
00061     const bool cboc_;
00062     Gnss_Synchro* gnss_synchro_;
00063 };
00064
00065 /** \} */
00066 /** \} */
00067 /** \} */
00068 #endif // GNSS_SDR_GALILEO_E1_PCPS_AMBIGUOUS_ACQUISITION_H

```

13.13 galileo_e1_pcps_ambiguous_acquisition_fpga.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals for the FPGA.

```
#include "base_pcps_acquisition_fpga.h"
```

Classes

- class [GalileoE1PcpsAmbiguousAcquisitionFpga](#)

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for Galileo E1 Signals.

13.13.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals for the FPGA.

Author

Marc Majoral, 2019. mmajoral(at)cttc.es

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Definition in file [galileo_e1_pcps_ambiguous_acquisition_fpga.h](#).

13.14 galileo_e1_pcps_ambiguous_acquisition_fpga.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_e1_pcps_ambiguous_acquisition_fpga.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * Galileo E1 Signals for the FPGA
00005  * \author Marc Majoral, 2019. mmajoral(at)cttc.es
00006  */

```

```

00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GALILEO_E1_PCPS_AMBIGUOUS_ACQUISITION_FPGA_H
00019 #define GNSS_SDR_GALILEO_E1_PCPS_AMBIGUOUS_ACQUISITION_FPGA_H
00020
00021 #include "base_pcps_acquisition_fpga.h"
00022
00023 /** \addtogroup Acquisition
00024  * \{ */
00025 /** \addtogroup Acq_adapters
00026  * \{ */
00027
00028
00029 /*!
00030  * \brief This class adapts a PCPS acquisition block off-loaded on an FPGA
00031  * to an AcquisitionInterface for Galileo E1 Signals
00032  */
00033 class GalileoE1PcpsAmbiguousAcquisitionFpga : public BasePcpsAcquisitionFpga
00034 {
00035 public:
00036     /*!
00037      * \brief Constructor
00038      */
00039     GalileoE1PcpsAmbiguousAcquisitionFpga(
00040         const ConfigurationInterface* configuration,
00041         const std::string& role,
00042         unsigned int in_streams,
00043         unsigned int out_streams);
00044
00045     /*!
00046      * \brief Returns "Galileo_E1_PCPS_Ambiguous_Acquisition_FPGA"
00047      */
00048     inline std::string implementation() override
00049     {
00050         return "Galileo_E1_PCPS_Ambiguous_Acquisition_FPGA";
00051     }
00052
00053 private:
00054     static const uint32_t DEFAULT_FPGA_BLK_EXP = 13; // default block exponent
00055     void generate_galileo_e1_prn_codes();
00056     const bool acquire_pilot_;
00057 };
00058
00059
00060 /** \} */
00061 /** \} */
00062 #endif // GNSS_SDR_GALILEO_E1_PCPS_AMBIGUOUS_ACQUISITION_FPGA_H

```

13.15 galileo_e1_pcps_cccwsr_ambiguous_acquisition.h File Reference

Adapts a PCPS CCCWSR acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

```
#include "base_pcps_acquisition_custom.h"
```

Classes

- class [GalileoE1PcpsCccwsrAmbiguousAcquisition](#)
Adapts a PCPS CCCWSR acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

13.15.1 Detailed Description

Adapts a PCPS CCCWSR acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

Author

Marc Molina, 2013. marc.molina.pena(at)gmail.com

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Definition in file [galileo_e1_pcps_cccwsr_ambiguous_acquisition.h](#).

13.16 galileo_e1_pcps_cccwsr_ambiguous_acquisition.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_e1_pcps_cccwsr_ambiguous_acquisition.h
00003  * \brief Adapts a PCPS CCCWSR acquisition block to an AcquisitionInterface for
00004  * Galileo E1 Signals
00005  * \author Marc Molina, 2013. marc.molina.pena(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GALILEO_E1_PCPS_CCCWSR_AMBIGUOUS_ACQUISITION_H
00019 #define GNSS_SDR_GALILEO_E1_PCPS_CCCWSR_AMBIGUOUS_ACQUISITION_H
00020
00021 #include "base_pcps_acquisition_custom.h"
00022
00023 /** \addtogroup Acquisition
00024  * \{ */
00025 /** \addtogroup Acq_adapters
00026  * \{ */
00027
00028 /*!
00029  * \brief Adapts a PCPS CCCWSR acquisition block to an AcquisitionInterface
00030  * for Galileo E1 Signals
00031  */
00032 class GalileoE1PcpsCccwsrAmbiguousAcquisition : public BasePcpsAcquisitionCustom
00033 {
00034 public:
00035     GalileoE1PcpsCccwsrAmbiguousAcquisition(
00036         const ConfigurationInterface* configuration,
00037         const std::string& role,
00038         unsigned int in_streams,
00039         unsigned int out_streams);
00040
00041     ~GalileoE1PcpsCccwsrAmbiguousAcquisition() = default;
00042
00043     /*!
00044     * \brief Returns "Galileo_E1_PCPS_CCCWSR_Ambiguous_Acquisition"
00045     */
00046     inline std::string implementation() override
00047     {
00048         return "Galileo_E1_PCPS_CCCWSR_Ambiguous_Acquisition";
00049     }
00050
00051     void set_local_code() override;
00052
00053 private:
00054     // We don't implement this function since we override set_local_code
00055     void code_gen_complex_sampled(own::span<std::complex<float> /*dest*/, uint32_t /*prn*/, int32_t
/*sampling_freq*/) override {}
00056
00057     std::vector<std::complex<float> > code_pilot_;
00058     const bool cboc_;
00059 };
00060
00061
00062 /** \} */
00063 /** \} */
00064 #endif // GNSS_SDR_GALILEO_E1_PCPS_CCCWSR_AMBIGUOUS_ACQUISITION_H

```

13.17 galileo_e1_pcps_quicksync_ambiguous_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

```
#include "base_pcps_acquisition_custom.h"
```

Classes

- class [GalileoE1PcpsQuickSyncAmbiguousAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

13.17.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

Date

June, 2014

Author

Damian Miralles Sanchez. dmiralles2009@gmail.com

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Definition in file [galileo_e1_pcps_quicksync_ambiguous_acquisition.h](#).

13.18 galileo_e1_pcps_quicksync_ambiguous_acquisition.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file galileo_e1_pcps_quicksync_ambiguous_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for Galileo E1 Signals
00004  * \date June, 2014
00005  * \author Damian Miralles Sanchez. dmiralles2009@gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GALILEO_E1_PCPS_QUICKSYNC_AMBIGUOUS_ACQUISITION_H
00019 #define GNSS_SDR_GALILEO_E1_PCPS_QUICKSYNC_AMBIGUOUS_ACQUISITION_H
00020
00021 #include "base_pcps_acquisition_custom.h"
00022
00023 /** \addtogroup Acquisition
00024  * \{ */
00025 /** \addtogroup Acq_adapters
00026  * \{ */
00027
00028 /*!
00029  * \brief This class adapts a PCPS acquisition block to an
00030  * \brief AcquisitionInterface for Galileo E1 Signals
00031  */
00032 class GalileoE1PcpsQuickSyncAmbiguousAcquisition : public BasePcpsAcquisitionCustom
00033 {
00034 public:
00035     GalileoE1PcpsQuickSyncAmbiguousAcquisition(
00036         const ConfigurationInterface* configuration,
00037         const std::string& role,
00038         unsigned int in_streams,
00039         unsigned int out_streams);
00040
00041     ~GalileoE1PcpsQuickSyncAmbiguousAcquisition() = default;
00042
```



```

00043     /*!
00044     * \brief Returns "Galileo_E1_PCPS_Ambiguous_Acquisition"
00045     */
00046     inline std::string implementation() override
00047     {
00048         return "Galileo_E1_PCPS_QuickSync_Ambiguous_Acquisition";
00049     }
00050
00051 private:
00052     GalileoE1PcpsQuickSyncAmbiguousAcquisition(
00053         const ConfigurationInterface* configuration,
00054         const std::string& role,
00055         unsigned int in_streams,
00056         unsigned int out_streams,
00057         uint32_t folding_factor);
00058
00059     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
sampling_freq) override;
00060
00061     const bool cboc_;
00062 };
00063
00064
00065 /** \} */
00066 /** \} */
00067 #endif // GNSS_SDR_GALILEO_E1_PCPS_QUICKSYNC_AMBIGUOUS_ACQUISITION_H

```

13.19 galileo_e1_pcps_tong_ambiguous_acquisition.h File Reference

Adapts a PCPS Tong acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

```
#include "base_pcps_acquisition_custom.h"
```

Classes

- class [GalileoE1PcpsTongAmbiguousAcquisition](#)

Adapts a PCPS Tong acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

13.19.1 Detailed Description

Adapts a PCPS Tong acquisition block to an [AcquisitionInterface](#) for Galileo E1 Signals.

Author

Marc Molina, 2013. marc.molina.pena(at)gmail.com

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Definition in file [galileo_e1_pcps_tong_ambiguous_acquisition.h](#).

13.20 galileo_e1_pcps_tong_ambiguous_acquisition.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file galileo_e1_pcps_tong_ambiguous_acquisition.h
00003 * \brief Adapts a PCPS Tong acquisition block to an AcquisitionInterface for
00004 * Galileo E1 Signals
00005 * \author Marc Molina, 2013. marc.molina.pena(at)gmail.com
00006 *
00007 * -----
00008 *
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00014 *
00015 * -----
00016 */
00017
00018 #ifndef GNSS_SDR_GALILEO_E1_PCPS_TONG_AMBIGUOUS_ACQUISITION_H
00019 #define GNSS_SDR_GALILEO_E1_PCPS_TONG_AMBIGUOUS_ACQUISITION_H
00020

```

```

00021 #include "base_pcps_acquisition_custom.h"
00022
00023 /** \addtogroup Acquisition
00024 * \{ */
00025 /** \addtogroup Acq_adapters
00026 * \{ */
00027
00028 /*!
00029 * \brief Adapts a PCPS Tong acquisition block to an AcquisitionInterface
00030 * for Galileo E1 Signals
00031 */
00032 class GalileoE1PcpsTongAmbiguousAcquisition : public BasePcpsAcquisitionCustom
00033 {
00034 public:
00035     GalileoE1PcpsTongAmbiguousAcquisition(
00036         const ConfigurationInterface* configuration,
00037         const std::string& role,
00038         unsigned int in_streams,
00039         unsigned int out_streams);
00040
00041     ~GalileoE1PcpsTongAmbiguousAcquisition() = default;
00042
00043     /*!
00044     * \brief Returns "Galileo_E1_PCPS_Tong_Ambiguous_Acquisition"
00045     */
00046     inline std::string implementation() override
00047     {
00048         return "Galileo_E1_PCPS_Tong_Ambiguous_Acquisition";
00049     }
00050
00051 private:
00052     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
sampling_freq) override;
00053
00054     const bool cboc_;
00055 };
00056
00057
00058 /** \} */
00059 /** \} */
00060 #endif // GNSS_SDR_GALILEO_E1_PCPS_TONG_AMBIGUOUS_ACQUISITION_H

```

13.21 galileo_e5a_noncoherent_iq_acquisition_caf.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E5a data and pilot Signals.

```
#include "base_pcps_acquisition_custom.h"
```

Classes

- class [GalileoE5aNoncoherentIQAcquisitionCaf](#)

13.21.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E5a data and pilot Signals.

Author

Marc Sales, 2014. [marcsales92\(at\)gmail.com](mailto:marcsales92(at)gmail.com) \based on work from:

- Javier Arribas, 2011. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)
- Luis Esteve, 2012. [luis\(at\)epsilon-formacion.com](mailto:luis(at)epsilon-formacion.com)
- Marc Molina, 2013. marc.molina.pena@gmail.com

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 Definition in file [galileo_e5a_noncoherent_iq_acquisition_caf.h](#).

13.22 galileo_e5a_noncoherent_iq_acquisition_caf.h

[Go to the documentation of this file.](#)

```
00001 /*!
```

```

00002  * \file galileo_e5a_noncoherent_iq_acquisition_caf.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * Galileo E5a data and pilot Signals
00005  * \author Marc Sales, 2014. marcsales92(at)gmail.com
00006  * \based on work from:
00007  *     <ul>
00008  *         <li> Javier Arribas, 2011. jarribas(at)cttc.es
00009  *         <li> Luis Esteve, 2012. luis(at)epsilon-formacion.com
00010  *         <li> Marc Molina, 2013. marc.molina.pena@gmail.com
00011  *     </ul>
00012  *
00013  * -----
00014  *
00015  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00016  * This file is part of GNSS-SDR.
00017  *
00018  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00019  * SPDX-License-Identifier: GPL-3.0-or-later
00020  *
00021  * -----
00022  */
00023
00024 #ifndef GNSS_SDR_GALILEO_E5A_NONCOHERENT_IQ_ACQUISITION_CAF_H
00025 #define GNSS_SDR_GALILEO_E5A_NONCOHERENT_IQ_ACQUISITION_CAF_H
00026
00027 #include "base_pcps_acquisition_custom.h"
00028
00029 /** \addtogroup Acquisition
00030  * \{ */
00031 /** \addtogroup Acq_adapters
00032  * \{ */
00033
00034 class GalileoE5aNoncoherentIQAcquisitionCaf : public BasePcpsAcquisitionCustom
00035 {
00036 public:
00037     GalileoE5aNoncoherentIQAcquisitionCaf(const ConfigurationInterface* configuration,
00038         const std::string& role,
00039         unsigned int in_streams,
00040         unsigned int out_streams);
00041
00042     ~GalileoE5aNoncoherentIQAcquisitionCaf() = default;
00043
00044     /*!
00045      * \brief Returns "Galileo_E5a_Noncoherent_IQ_Acquisition_CAF"
00046      */
00047     inline std::string implementation() override
00048     {
00049         return "Galileo_E5a_Noncoherent_IQ_Acquisition_CAF";
00050     }
00051
00052     /*!
00053      * \brief Sets local Galileo E5a code for PCPS acquisition algorithm.
00054      */
00055     void set_local_code() override;
00056
00057 private:
00058     // We don't implement this function since we override set_local_code
00059     void code_gen_complex_sampled(own::span<std::complex<float> > /*dest*/, uint32_t /*prn*/, int32_t
/*sampling_freq*/) override {}
00060
00061     const int zero_padding_;
00062     const int caf_window_hz_;
00063
00064     std::vector<std::complex<float> > codeQ_;
00065 };
00066
00067
00068 /** \} */
00069 /** \} */
00070 #endif // GNSS_SDR_GALILEO_E5A_NONCOHERENT_IQ_ACQUISITION_CAF_H

```

13.23 galileo_e5a_pcps_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E5a data and pilot Signals.

#include "base_pcps_acquisition.h"

Classes

- class [GalileoE5aPcpsAcquisition](#)

13.23.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E5a data and pilot Signals.

Author

Antonio Ramos, 2018. antonio.ramos(at)cttc.es

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 Definition in file [galileo_e5a_pcps_acquisition.h](#).

13.24 galileo_e5a_pcps_acquisition.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_e5a_pcps_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * \brief Galileo E5a data and pilot Signals
00005  * \author Antonio Ramos, 2018. antonio.ramos(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GALILEO_E5A_PCPS_ACQUISITION_H
00019 #define GNSS_SDR_GALILEO_E5A_PCPS_ACQUISITION_H
00020
00021
00022 #include "base_pcps_acquisition.h"
00023
00024 /** \addtogroup Acquisition
00025  * \{ */
00026 /** \addtogroup Acq_adapters
00027  * \{ */
00028
00029
00030 class GalileoE5aPcpsAcquisition : public BasePcpsAcquisition
00031 {
00032 public:
00033     GalileoE5aPcpsAcquisition(
00034         const ConfigurationInterface* configuration,
00035         const std::string& role,
00036         unsigned int in_streams,
00037         unsigned int out_streams);
00038
00039     ~GalileoE5aPcpsAcquisition() = default;
00040
00041     inline std::string implementation() override
00042     {
00043         return "Galileo_E5a_Pcps_Acquisition";
00044     }
00045
00046 private:
00047     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
00048         sampling_freq) override;
00049
00049     bool acq_pilot_;
00050     const bool acq_iq_;
00051 };
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_GALILEO_E5A_PCPS_ACQUISITION_H

```

13.25 galileo_e5a_pcps_acquisition_fpga.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E5a data and pilot Signals for the FPGA.

```
#include "base_pcps_acquisition_fpga.h"
```

Classes

- class [GalileoE5aPcpsAcquisitionFpga](#)

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for Galileo E5a signals.

13.25.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E5a data and pilot Signals for the FPGA.

Author

Marc Majoral, 2019. mmajoral(at)cttc.es

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Definition in file [galileo_e5a_pcps_acquisition_fpga.h](#).

13.26 galileo_e5a_pcps_acquisition_fpga.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_e5a_pcps_acquisition_fpga.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * Galileo E5a data and pilot Signals for the FPGA
00005  * \author Marc Majoral, 2019. mmajoral(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GALILEO_E5A_PCPS_ACQUISITION_FPGA_H
00019 #define GNSS_SDR_GALILEO_E5A_PCPS_ACQUISITION_FPGA_H
00020
00021 #include "base_pcps_acquisition_fpga.h"
00022
00023 /** \addtogroup Acquisition
00024  * \{ */
00025 /** \addtogroup Acq_adapters
00026  * \{ */
00027
00028
00029 /*!
00030 * \brief This class adapts a PCPS acquisition block off-loaded on an FPGA
00031 * to an AcquisitionInterface for Galileo E5a signals
00032 */
00033 class GalileoE5aPcpsAcquisitionFpga : public BasePcpsAcquisitionFpga
00034 {
00035 public:
00036     /*!
00037     * \brief Constructor
00038     */
00039     GalileoE5aPcpsAcquisitionFpga(
00040         const ConfigurationInterface* configuration,
00041         const std::string& role,
00042         unsigned int in_streams,
00043         unsigned int out_streams);
00044
00045     /*!
00046     * \brief Returns "Galileo_E5a_Pcps_Acquisition_FPGA"
00047     */
00048     inline std::string implementation() override
00049     {
00050         return "Galileo_E5a_Pcps_Acquisition_FPGA";
00051     }
00052
00053 private:
00054     static const uint32_t DEFAULT_FPGA_BLK_EXP = 13; // default block exponent
00055     void generate_galileo_e5a_prn_codes();
00056     bool acq_pilot_;
00057     bool acq_iq_;
00058 };
00059

```

```

00060
00061 /** \} */
00062 /** \} */
00063 #endif // GNSS_SDR_GALILEO_E5A_PCPS_ACQUISITION_FPGA_H

```

13.27 galileo_e5b_pcps_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E5b data and pilot Signals.

```
#include "base_pcps_acquisition.h"
```

Classes

- class [GalileoE5bPcpsAcquisition](#)

13.27.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E5b data and pilot Signals.

Author

Piyush Gupta, 2020. piyush04111999@gmail.com

Note

Code added as part of GSoC 2020 program.

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Definition in file [galileo_e5b_pcps_acquisition.h](#).

13.28 galileo_e5b_pcps_acquisition.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_e5b_pcps_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * Galileo E5b data and pilot Signals
00005  * \author Piyush Gupta, 2020. piyush04111999@gmail.com
00006  * \note Code added as part of GSoC 2020 program.
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GALILEO_E5B_PCPS_ACQUISITION_H
00020 #define GNSS_SDR_GALILEO_E5B_PCPS_ACQUISITION_H
00021
00022
00023 #include "base_pcps_acquisition.h"
00024
00025 /** \addtogroup Acquisition
00026  * \{ */
00027 /** \addtogroup Acq_adapters
00028  * \{ */
00029
00030 class GalileoE5bPcpsAcquisition : public BasePcpsAcquisition
00031 {
00032 public:
00033     /*!
00034     * \brief Constructor
00035     */
00036     GalileoE5bPcpsAcquisition(const ConfigurationInterface* configuration,
00037                               const std::string& role,
00038                               unsigned int in_streams,

```

```

00039         unsigned int out_streams);
00040
00041     /*!
00042     * \brief Destructor
00043     */
00044     ~GalileoE5bPcpsAcquisition() = default;
00045
00046     /*!
00047     * \brief Returns "GALILEO_E5b_PCPS_Acquisition"
00048     */
00049
00050     inline std::string implementation() override
00051     {
00052         return "Galileo_E5b_PCPS_Acquisition";
00053     }
00054
00055 private:
00056     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
sampling_freq) override;
00057
00058     bool acq_pilot_;
00059     const bool acq_iq_;
00060 };
00061
00062
00063 /** \} */
00064 /** \} */
00065 #endif // GNSS_SDR_GALILEO_E5B_PCPS_ACQUISITION_H

```

13.29 galileo_e5b_pcps_acquisition_fpga.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E5b data and pilot Signals for the FPGA.

```
#include "base_pcps_acquisition_fpga.h"
```

Classes

- class [GalileoE5bPcpsAcquisitionFpga](#)

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for Galileo E5b signals.

13.29.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E5b data and pilot Signals for the FPGA.

Author

Piyush Gupta, 2020. piyush04111999@gmail.com

Note

Code added as part of GSoC 2020 Program.

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Definition in file [galileo_e5b_pcps_acquisition_fpga.h](#).

13.30 galileo_e5b_pcps_acquisition_fpga.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file galileo_e5b_pcps_acquisition_fpga.h
00003 * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004 * Galileo E5b data and pilot Signals for the FPGA
00005 * \author Piyush Gupta, 2020. piyush04111999@gmail.com
00006 * \note Code added as part of GSoC 2020 Program.
00007 *
00008 * -----
00009 *
00010 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00012 *

```

```

00013  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
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00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GALILEO_E5B_PCPS_ACQUISITION_FPGA_H
00020 #define GNSS_SDR_GALILEO_E5B_PCPS_ACQUISITION_FPGA_H
00021
00022 #include "base_pcps_acquisition_fpga.h"
00023
00024 /** \addtogroup Acquisition
00025  * \{ */
00026 /** \addtogroup Acq_adapters
00027  * \{ */
00028
00029
00030 /*!
00031  * \brief This class adapts a PCPS acquisition block off-loaded on an FPGA
00032  * to an AcquisitionInterface for Galileo E5b signals
00033  */
00034 class GalileoE5bPcpsAcquisitionFpga : public BasePcpsAcquisitionFpga
00035 {
00036 public:
00037     /*!
00038     * \brief Constructor
00039     */
00040     GalileoE5bPcpsAcquisitionFpga(const ConfigurationInterface* configuration,
00041         const std::string& role,
00042         unsigned int in_streams,
00043         unsigned int out_streams);
00044
00045     /*!
00046     * \brief Returns "Galileo_E5b_Pcps_Acquisition_FPGA"
00047     */
00048     inline std::string implementation() override
00049     {
00050         return "Galileo_E5b_PCPS_Acquisition_FPGA";
00051     }
00052
00053 private:
00054     static const uint32_t DEFAULT_FPGA_BLK_EXP = 13; // default block exponent
00055     void generate_galileo_e5b_prn_codes();
00056     bool acq_pilot_;
00057     const bool acq_iq_;
00058 };
00059
00060
00061 /** \} */
00062 /** \} */
00063 #endif // GNSS_SDR_GALILEO_E5B_PCPS_ACQUISITION_FPGA_H

```

13.31 galileo_e6_pcps_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E6 B/C Signals.

```
#include "base_pcps_acquisition.h"
```

Classes

- class [GalileoE6PcpsAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E6 Signals.

13.31.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E6 B/C Signals.

Author

Carles Fernandez-Prades, 2020. cfernandez(at)cttc.es

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 Definition in file [galileo_e6_pcps_acquisition.h](#).

13.32 galileo_e6_pcps_acquisition.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_e6_pcps_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * Galileo E6 B/C Signals
00005  * \author Carles Fernandez-Prades, 2020. cfernandez(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GALILEO_E6_PCPS_ACQUISITION_H
00019 #define GNSS_SDR_GALILEO_E6_PCPS_ACQUISITION_H
00020
00021 #include "base_pcps_acquisition.h"
00022
00023 /** \addtogroup Acquisition
00024  * \{ */
00025 /** \addtogroup Acq_adapters
00026  * \{ */
00027
00028
00029 /*!
00030 * \brief This class adapts a PCPS acquisition block to an
00031 * AcquisitionInterface for Galileo E6 Signals
00032 */
00033 class GalileoE6PcpsAcquisition : public BasePcpsAcquisition
00034 {
00035 public:
00036     GalileoE6PcpsAcquisition(
00037         const ConfigurationInterface* configuration,
00038         const std::string& role,
00039         unsigned int in_streams,
00040         unsigned int out_streams);
00041
00042     ~GalileoE6PcpsAcquisition() = default;
00043
00044     /*!
00045     * \brief Returns "Galileo_E6_PCPS_Acquisition"
00046     */
00047     inline std::string implementation() override
00048     {
00049         return "Galileo_E6_PCPS_Acquisition";
00050     }
00051
00052 private:
00053     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
sampling_freq) override;
00054 };
00055
00056
00057 /** \} */
00058 /** \} */
00059 #endif // GNSS_SDR_GALILEO_E6_PCPS_ACQUISITION_H

```

13.33 glonass_l1_ca_pcps_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Glonass L1 C/A signals.

```
#include "base_pcps_acquisition.h"
```

Classes

- class [GlonassL1CaPcpsAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

13.33.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Glonass L1 C/A signals.

Author

Gabriel Araujo, 2017. gabriel.araujo.5000(at)gmail.com

Luis Esteve, 2017. luis(at)epsilon-formacion.com

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 Definition in file [glonass_l1_ca_pcps_acquisition.h](#).

13.34 glonass_l1_ca_pcps_acquisition.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file glonass_l1_ca_pcps_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * Glonass L1 C/A signals
00005  * \author Gabriel Araujo, 2017. gabriel.araujo.5000(at)gmail.com
00006  * \author Luis Esteve, 2017. luis(at)epsilon-formacion.com
00007  *
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_GLOMSS_L1_CA_PCPS_ACQUISITION_H
00021 #define GNSS_SDR_GLOMSS_L1_CA_PCPS_ACQUISITION_H
00022
00023 #include "base_pcps_acquisition.h"
00024
00025 /** \addtogroup Acquisition
00026  * \{ */
00027 /** \addtogroup Acq_adapters
00028  * \{ */
00029
00030 /*!
00031 * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00032 * for GPS L1 C/A signals
00033 */
00034 class GlonassL1CaPcpsAcquisition : public BasePcpsAcquisition
00035 {
00036 public:
00037     GlonassL1CaPcpsAcquisition(
00038         const ConfigurationInterface* configuration,
00039         const std::string& role,
00040         unsigned int in_streams,
00041         unsigned int out_streams);
00042
00043     ~GlonassL1CaPcpsAcquisition() = default;
00044
00045     /*!
00046     * \brief Returns "GLONASS_L1_CA_PCPS_Acquisition"
00047     */
00048     inline std::string implementation() override
00049     {
00050         return "GLONASS_L1_CA_PCPS_Acquisition";
00051     }
00052
00053 private:
00054     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
00055         sampling_freq) override;
00056 };
00057
00058 /** \} */
00059 /** \} */
00060 #endif // GNSS_SDR_GLOMSS_L1_CA_PCPS_ACQUISITION_H

```

13.35 glonass_l2_ca_pcps_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Glonass L2 C/A signals.

```
#include "base_pcps_acquisition.h"
```

Classes

- class [GlonassL2CaPcpsAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GLONASS L2 C/A signals.

13.35.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Glonass L2 C/A signals.

Author

Damian Miralles, 2018, dmiralles2009@gmail.com

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Definition in file [glonass_l2_ca_pcps_acquisition.h](#).

13.36 glonass_l2_ca_pcps_acquisition.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file glonass_l2_ca_pcps_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * Glonass L2 C/A signals
00005  * \author Damian Miralles, 2018, dmiralles2009@gmail.com
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GLOMSS_L2_CA_PCPS_ACQUISITION_H
00020 #define GNSS_SDR_GLOMSS_L2_CA_PCPS_ACQUISITION_H
00021
00022 #include "base_pcps_acquisition.h"
00023
00024 /** \addtogroup Acquisition
00025  * \{ */
00026 /** \addtogroup Acq_adapters
00027  * \{ */
00028
00029 /*!
00030  * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00031  * for GLONASS L2 C/A signals
00032  */
00033 class GlonassL2CaPcpsAcquisition : public BasePcpsAcquisition
00034 {
00035 public:
00036     GlonassL2CaPcpsAcquisition(
00037         const ConfigurationInterface* configuration,
00038         const std::string& role,
00039         unsigned int in_streams,
00040         unsigned int out_streams);
00041
00042     ~GlonassL2CaPcpsAcquisition() = default;
00043
00044     /*!
00045     * \brief Returns "GLONASS_L2_CA_PCPS_Acquisition"
00046     */
00047     inline std::string implementation() override
00048     {
00049         return "GLONASS_L2_CA_PCPS_Acquisition";
00050     }
00051 }
```

```

00051
00052 private:
00053     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
        sampling_freq) override;
00054 };
00055
00056
00057 /** @} */
00058 /** @} */
00059 #endif // GNSS_SDR_GLO_NASS_L2_CA_PCPS_ACQUISITION_H

```

13.37 gps_l1_ca_pcps_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

```
#include "base_pcps_acquisition.h"
```

Classes

- class [GpsL1CaPcpsAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

13.37.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

Authors

- Javier Arribas, 2011. jarribas(at)cttc.es
- Luis Esteve, 2012. luis(at)epsilon-formacion.com
- Marc Molina, 2013. marc.molina.pena(at)gmail.com

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Definition in file [gps_l1_ca_pcps_acquisition.h](#).

13.38 gps_l1_ca_pcps_acquisition.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gps_l1_ca_pcps_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * \brief GPS L1 C/A signals
00005  * \authors <ul>
00006  *     <li> Javier Arribas, 2011. jarribas(at)cttc.es
00007  *     <li> Luis Esteve, 2012. luis(at)epsilon-formacion.com
00008  *     <li> Marc Molina, 2013. marc.molina.pena(at)gmail.com
00009  *     </ul>
00010  *
00011  * -----
00012  *
00013  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014  * This file is part of GNSS-SDR.
00015  *
00016  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022 #ifndef GNSS_SDR_GPS_L1_CA_PCPS_ACQUISITION_H
00023 #define GNSS_SDR_GPS_L1_CA_PCPS_ACQUISITION_H
00024
00025 #include "base_pcps_acquisition.h"
00026
00027 /** \addtogroup Acquisition
00028  * \brief Classes for GNSS signal acquisition
00029  * \{ */
00030 /** \addtogroup Acq_adapters acquisition_adapters
00031  * \brief Wrap GNU Radio acquisition blocks with an AcquisitionInterface
00032  * \{ */

```

```

00033
00034 /*!
00035  * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00036  * for GPS L1 C/A signals
00037  */
00038 class GpsL1CaPcpsAcquisition : public BasePcpsAcquisition
00039 {
00040 public:
00041     GpsL1CaPcpsAcquisition(
00042         const ConfigurationInterface* configuration,
00043         const std::string& role,
00044         unsigned int in_streams,
00045         unsigned int out_streams);
00046
00047     ~GpsL1CaPcpsAcquisition() = default;
00048
00049     /*!
00050      * \brief Returns "GPS_L1_CA_PCPS_Acquisition"
00051      */
00052     inline std::string implementation() override
00053     {
00054         return "GPS_L1_CA_PCPS_Acquisition";
00055     }
00056
00057 private:
00058     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
00059         sampling_freq) override;
00060 };
00061
00062 /** \} */
00063 /** \} */
00064 #endif // GNSS_SDR_GPS_L1_CA_PCPS_ACQUISITION_H

```

13.39 gps_l1_ca_pcps_acquisition_fine_doppler.h File Reference

Adapts a PCPS acquisition block with fine Doppler estimation to an [AcquisitionInterface](#) for GPS L1 C/A signals.
`#include "base_pcps_acquisition_custom.h"`

Classes

- class [GpsL1CaPcpsAcquisitionFineDoppler](#)

This class Adapts a PCPS acquisition block with fine Doppler estimation to an [AcquisitionInterface](#) for GPS L1 C/A signals.

13.39.1 Detailed Description

Adapts a PCPS acquisition block with fine Doppler estimation to an [AcquisitionInterface](#) for GPS L1 C/A signals.

Authors

- Javier Arribas, 2013. jarribas(at)cttc.es

*

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 Definition in file [gps_l1_ca_pcps_acquisition_fine_doppler.h](#).

13.40 gps_l1_ca_pcps_acquisition_fine_doppler.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gps_l1_ca_pcps_acquisition_fine_doppler.h
00003  * \brief Adapts a PCPS acquisition block with fine Doppler estimation to an AcquisitionInterface for
00004  * GPS L1 C/A signals
00005  * \authors <ul>
00006  * <li> Javier Arribas, 2013. jarribas(at)cttc.es
00007  * </ul> *
00008  *
00009  * -----
00010  *

```

```

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00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
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00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_GPS_L1_CA_PCPS_ACQUISITION_FINE_DOPPLER_H
00021 #define GNSS_SDR_GPS_L1_CA_PCPS_ACQUISITION_FINE_DOPPLER_H
00022
00023 #include "base_pcps_acquisition_custom.h"
00024
00025 /** \addtogroup Acquisition
00026  * \{ */
00027 /** \addtogroup Acq_adapters
00028  * \{ */
00029
00030
00031 /*!
00032  * \brief This class Adapts a PCPS acquisition block with fine Doppler estimation to an
00033  * AcquisitionInterface for
00034  * GPS L1 C/A signals
00035 */
00036 class GpsL1CaPcpsAcquisitionFineDoppler : public BasePcpsAcquisitionCustom
00037 {
00038 public:
00039     GpsL1CaPcpsAcquisitionFineDoppler(const ConfigurationInterface* configuration,
00040         const std::string& role,
00041         unsigned int in_streams,
00042         unsigned int out_streams);
00043
00044     ~GpsL1CaPcpsAcquisitionFineDoppler() = default;
00045
00046     /*!
00047     * \brief Returns "GPS_L1_CA_PCPS_Acquisition_Fine_Doppler"
00048     */
00049     inline std::string implementation() override
00050     {
00051         return "GPS_L1_CA_PCPS_Acquisition_Fine_Doppler";
00052     }
00053 private:
00054     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
00055         sampling_freq) override;
00056 };
00057
00058 /** \} */
00059 /** \} */
00060 #endif // GNSS_SDR_GPS_L1_CA_PCPS_ACQUISITION_FINE_DOPPLER_H

```

13.41 gps_l1_ca_pcps_acquisition_fpga.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals for the FPGA.

```
#include "base_pcps_acquisition_fpga.h"
```

Classes

- class [GpsL1CaPcpsAcquisitionFpga](#)

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for GPS L1 C/A signals.

13.41.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals for the FPGA.

Authors

- Marc Majoral, 2019. mmajoral(at)cttc.es
- Javier Arribas, 2019. jarribas(at)cttc.es

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 Definition in file [gps_l1_ca_pcps_acquisition_fpga.h](#).

13.42 gps_l1_ca_pcps_acquisition_fpga.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gps_l1_ca_pcps_acquisition_fpga.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface
00004  * for GPS L1 C/A signals for the FPGA
00005  * \authors <ul>
00006  *         <li> Marc Majoral, 2019. mmajoral(at)cttc.es
00007  *         <li> Javier Arribas, 2019. jarribas(at)cttc.es
00008  *         </li>
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_GPS_L1_CA_PCPS_ACQUISITION_FPGA_H
00022 #define GNSS_SDR_GPS_L1_CA_PCPS_ACQUISITION_FPGA_H
00023
00024 #include "base_pcps_acquisition_fpga.h"
00025
00026 /** \addtogroup Acquisition
00027  * \{ */
00028 /** \addtogroup Acq_adapters
00029  * \{ */
00030
00031  /*!
00032  * \brief This class adapts a PCPS acquisition block off-loaded on an FPGA
00033  * to an AcquisitionInterface for GPS L1 C/A signals
00034  */
00035  class GpsL1CaPcpsAcquisitionFpga : public BasePcpsAcquisitionFpga
00036  {
00037  public:
00038      /*!
00039      * \brief Constructor
00040      */
00041      GpsL1CaPcpsAcquisitionFpga(const ConfigurationInterface* configuration,
00042                                  const std::string& role,
00043                                  unsigned int in_streams,
00044                                  unsigned int out_streams);
00045
00046      /*!
00047      * \brief Returns "GPS_L1_CA_PCPS_Acquisition_FPGA"
00048      */
00049      inline std::string implementation() override
00050      {
00051          return "GPS_L1_CA_PCPS_Acquisition_FPGA";
00052      }
00053
00054  private:
00055      static const uint32_t DEFAULT_FPGA_BLK_EXP = 10; // default block exponent
00056      void generate_gps_l1_ca_prn_codes();
00057  };
00058
00059
00060 /** \} */
00061 /** \} */
00062 #endif // GNSS_SDR_GPS_L1_CA_PCPS_ACQUISITION_FPGA_H

```

13.43 gps_l1_ca_pcps_assisted_acquisition.h File Reference

Adapts a PCPS Assisted acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

```
#include "base_pcps_acquisition_custom.h"
```

Classes

- class [GpsL1CaPcpsAssistedAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

13.43.1 Detailed Description

Adapts a PCPS Assisted acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

Authors

- Javier Arribas, 2011. jarribas(at)cttc.es

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 Definition in file [gps_l1_ca_pcps_assisted_acquisition.h](#).

13.44 gps_l1_ca_pcps_assisted_acquisition.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gps_l1_ca_pcps_assisted_acquisition.h
00003  * \brief Adapts a PCPS Assisted acquisition block to an AcquisitionInterface for
00004  * GPS L1 C/A signals
00005  * \authors <ul>
00006  * <li> Javier Arribas, 2011. jarribas(at)cttc.es
00007  * </ul>
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_GPS_L1_CA_PCPS_ASSISTED_ACQUISITION_H
00021 #define GNSS_SDR_GPS_L1_CA_PCPS_ASSISTED_ACQUISITION_H
00022
00023 #include "base_pcps_acquisition_custom.h"
00024
00025 /** \addtogroup Acquisition
00026  * \{ */
00027 /** \addtogroup Acq_adapters
00028  * \{ */
00029
00030
00031 /*!
00032  * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00033  * for GPS L1 C/A signals
00034  */
00035 class GpsL1CaPcpsAssistedAcquisition : public BasePcpsAcquisitionCustom
00036 {
00037 public:
00038     GpsL1CaPcpsAssistedAcquisition(
00039         const ConfigurationInterface* configuration,
00040         const std::string& role,
00041         unsigned int in_streams,
00042         unsigned int out_streams);
00043
00044     ~GpsL1CaPcpsAssistedAcquisition() = default;
00045
00046     /*!
00047     * \brief Returns "GPS_L1_CA_PCPS_Assisted_Acquisition"
00048     */
00049     inline std::string implementation() override
00050     {
00051         return "GPS_L1_CA_PCPS_Assisted_Acquisition";
00052     }
00053
00054 private:
00055     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
00056         sampling_freq) override;
00057 };
00058
00059 /** \} */
00060 /** \} */
00061 #endif // GNSS_SDR_GPS_L1_CA_PCPS_ASSISTED_ACQUISITION_H

```


13.45 gps_l1_ca_pcps_openc1_acquisition.h File Reference

Adapts an OpenCL PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

```
#include "base_pcps_acquisition_custom.h"
```

Classes

- class [GpsL1CaPcpsOpenClAcquisition](#)

This class adapts an OpenCL PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

13.45.1 Detailed Description

Adapts an OpenCL PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

Author

Marc Molina, 2013. marc.molina.pena(at)gmail.com

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Definition in file [gps_l1_ca_pcps_openc1_acquisition.h](#).

13.46 gps_l1_ca_pcps_openc1_acquisition.h

[Go to the documentation of this file.](#)

```
00001  /*!
00002  * \file gps_l1_ca_pcps_openc1_acquisition.h
00003  * \brief Adapts an OpenCL PCPS acquisition block to an
00004  * \brief AcquisitionInterface for GPS L1 C/A signals
00005  * \author Marc Molina, 2013. marc.molina.pena(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GPS_L1_CA_PCPS_OPENC1_ACQUISITION_H
00019 #define GNSS_SDR_GPS_L1_CA_PCPS_OPENC1_ACQUISITION_H
00020
00021 #include "base_pcps_acquisition_custom.h"
00022
00023 /** \addtogroup Acquisition
00024  * \{ */
00025 /** \addtogroup Acq_adapters
00026  * \{ */
00027
00028 /*!
00029 * \brief This class adapts an OpenCL PCPS acquisition block to an
00030 * \brief AcquisitionInterface for GPS L1 C/A signals
00031 */
00032 class GpsL1CaPcpsOpenClAcquisition : public BasePcpsAcquisitionCustom
00033 {
00034 public:
00035     GpsL1CaPcpsOpenClAcquisition(const ConfigurationInterface* configuration,
00036                                   const std::string& role,
00037                                   unsigned int in_streams,
00038                                   unsigned int out_streams);
00039
00040     ~GpsL1CaPcpsOpenClAcquisition() = default;
00041
00042     /*!
00043     * \brief Returns "GPS_L1_CA_PCPS_OpenCl_Acquisition"
00044     */
00045     inline std::string implementation() override
00046     {
00047         return "GPS_L1_CA_PCPS_OpenCl_Acquisition";
00048     }
00049
00050     inline bool openc1_ready() const
```

```

00051     {
00052         return openc1_ready_;
00053     }
00054
00055 private:
00056     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
sampling_freq) override;
00057
00058     bool openc1_ready_;
00059 };
00060
00061
00062 /** \} */
00063 /** \} */
00064 #endif // GNSS_SDR_GPS_L1_CA_PCPS_OPENC1_ACQUISITION_H

```

13.47 gps_l1_ca_pcps_quicksync_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals implementing the QuickSync Algorithm.

```
#include "base_pcps_acquisition_custom.h"
```

Classes

- class [GpsL1CaPcpsQuickSyncAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

13.47.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals implementing the QuickSync Algorithm.

Date

June, 2014

Author

Damian Miralles Sanchez. dmiralles2009@gmail.com

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Definition in file [gps_l1_ca_pcps_quicksync_acquisition.h](#).

13.48 gps_l1_ca_pcps_quicksync_acquisition.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gps_l1_ca_pcps_quicksync_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for GPS L1 C/A signals
implementing the QuickSync Algorithm.
00004  * \date June, 2014
00005  * \author Damian Miralles Sanchez. dmiralles2009@gmail.com
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GPS_L1_CA_PCPS_QUICKSYNC_ACQUISITION_H
00020 #define GNSS_SDR_GPS_L1_CA_PCPS_QUICKSYNC_ACQUISITION_H
00021
00022 #include "base_pcps_acquisition_custom.h"

```

```

00023
00024 /** \addtogroup Acquisition
00025 * \{ */
00026 /** \addtogroup Acq_adapters
00027 * \{ */
00028
00029 /*!
00030 * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00031 * for GPS L1 C/A signals
00032 */
00033 class GpsL1CaPcpsQuickSyncAcquisition : public BasePcpsAcquisitionCustom
00034 {
00035 public:
00036     GpsL1CaPcpsQuickSyncAcquisition(
00037         const ConfigurationInterface* configuration,
00038         const std::string& role,
00039         unsigned int in_streams,
00040         unsigned int out_streams);
00041
00042     ~GpsL1CaPcpsQuickSyncAcquisition() = default;
00043
00044     /*!
00045     * \brief Returns "GPS_L1_CA_PCPS_QuickSync_Acquisition"
00046     */
00047     inline std::string implementation() override
00048     {
00049         return "GPS_L1_CA_PCPS_QuickSync_Acquisition";
00050     }
00051
00052 private:
00053     GpsL1CaPcpsQuickSyncAcquisition(
00054         const ConfigurationInterface* configuration,
00055         const std::string& role,
00056         unsigned int in_streams,
00057         unsigned int out_streams,
00058         uint32_t folding_factor);
00059
00060     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
sampling_freq) override;
00061 };
00062
00063
00064 /** \} */
00065 /** \} */
00066 #endif // GNSS_SDR_GPS_L1_CA_PCPS_QUICKSYNC_ACQUISITION_H

```

13.49 gps_l1_ca_pcps_tong_acquisition.h File Reference

Adapts a PCPS Tong acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

```
#include "base_pcps_acquisition_custom.h"
```

Classes

- class [GpsL1CaPcpsTongAcquisition](#)

This class adapts a PCPS Tong acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

13.49.1 Detailed Description

Adapts a PCPS Tong acquisition block to an [AcquisitionInterface](#) for GPS L1 C/A signals.

Author

Marc Molina, 2013. marc.molina.pena(at)gmail.com

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 Definition in file [gps_l1_ca_pcps_tong_acquisition.h](#).

13.50 gps_l1_ca_pcps_tong_acquisition.h

[Go to the documentation of this file.](#)

```
00001 /*!
```

```

00002  * \file gps_ll_ca_pcps_tong_acquisition.h
00003  * \brief Adapts a PCPS Tong acquisition block to an AcquisitionInterface for
00004  * GPS L1 C/A signals
00005  * \author Marc Molina, 2013. marc.molina.pena(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GPS_L1_CA_TONG_ACQUISITION_H
00019 #define GNSS_SDR_GPS_L1_CA_TONG_ACQUISITION_H
00020
00021 #include "base_pcps_acquisition_custom.h"
00022
00023 /** \addtogroup Acquisition
00024  * \{ */
00025 /** \addtogroup Acq_adapters
00026  * \{ */
00027
00028 /*!
00029  * \brief This class adapts a PCPS Tong acquisition block to an
00030  * AcquisitionInterface for GPS L1 C/A signals
00031  */
00032 class GpsL1CaPcpsTongAcquisition : public BasePcpsAcquisitionCustom
00033 {
00034 public:
00035     GpsL1CaPcpsTongAcquisition(const ConfigurationInterface* configuration,
00036                                const std::string& role,
00037                                unsigned int in_streams,
00038                                unsigned int out_streams);
00039
00040     ~GpsL1CaPcpsTongAcquisition() = default;
00041
00042     /*!
00043     * \brief Returns "GPS_L1_CA_PCPS_Tong_Acquisition"
00044     */
00045     inline std::string implementation() override
00046     {
00047         return "GPS_L1_CA_PCPS_Tong_Acquisition";
00048     }
00049
00050 private:
00051     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
00052                                   sampling_freq) override;
00053 };
00054
00055 /** \} */
00056 /** \} */
00057 #endif // GNSS_SDR_GPS_L1_CA_TONG_ACQUISITION_H

```

13.51 gps_l2_m_pcps_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L2 M signals.

```
#include "base_pcps_acquisition.h"
```

Classes

- class [GpsL2MPcpsAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L2 M signals.

13.51.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L2 M signals.

Authors

- Javier Arribas, 2015. jarribas(at)cttc.es

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 Definition in file [gps_l2_m_pcps_acquisition.h](#).

13.52 gps_l2_m_pcps_acquisition.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gps_l2_m_pcps_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  *        GPS L2 M signals
00005  * \authors <ul>
00006  *         <li> Javier Arribas, 2015. jarribas(at)cttc.es
00007  *         </li>
00008  *         </ul>
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
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00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_GPS_L2_M_PCPS_ACQUISITION_H
00021 #define GNSS_SDR_GPS_L2_M_PCPS_ACQUISITION_H
00022
00023 #include "base_pcps_acquisition.h"
00024
00025 /** \addtogroup Acquisition
00026  *  \{ */
00027 /** \addtogroup Acq_adapters
00028  *  \{ */
00029
00030 /*!
00031 * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00032 *        for GPS L2 M signals
00033 */
00034 class GpsL2MPcpsAcquisition : public BasePcpsAcquisition
00035 {
00036 public:
00037     GpsL2MPcpsAcquisition(
00038         const ConfigurationInterface* configuration,
00039         const std::string& role,
00040         unsigned int in_streams,
00041         unsigned int out_streams);
00042
00043     ~GpsL2MPcpsAcquisition() = default;
00044
00045     /*!
00046     * \brief Returns "GPS_L2_M_PCPS_Acquisition"
00047     */
00048     inline std::string implementation() override
00049     {
00050         return "GPS_L2_M_PCPS_Acquisition";
00051     }
00052
00053 private:
00054     void code_gen_complex_sampled(own::span<std::complex<float>> dest, uint32_t prn, int32_t
00055         sampling_freq) override;
00056 };
00057
00058 /** \} */
00059 /** \} */
00060 #endif // GNSS_SDR_GPS_L2_M_PCPS_ACQUISITION_H

```

13.53 gps_l2_m_pcps_acquisition_fpga.h File Reference

Adapts an FPGA-offloaded PCPS acquisition block to an [AcquisitionInterface](#) for GPS L2 M signals.
 #include "base_pcps_acquisition_fpga.h"

Classes

- class [GpsL2MPcpsAcquisitionFpga](#)

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for GPS L2 M signals.

13.53.1 Detailed Description

Adapts an FPGA-offloaded PCPS acquisition block to an [AcquisitionInterface](#) for GPS L2 M signals.

Authors

- Javier Arribas, 2019. jarribas(at)cttc.es

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Definition in file [gps_l2_m_pcps_acquisition_fpga.h](#).

13.54 gps_l2_m_pcps_acquisition_fpga.h

[Go to the documentation of this file.](#)

```
00001  /*!
00002  * \file gps_l2_m_pcps_acquisition_fpga.h
00003  * \brief Adapts an FPGA-offloaded PCPS acquisition block
00004  * to an AcquisitionInterface for GPS L2 M signals
00005  * \authors <ul>
00006  *         <li> Javier Arribas, 2019. jarribas(at)cttc.es
00007  *         </li>
00008  *         </ul>
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  * -----
00017  */
00018  */
00019
00020 #ifndef GNSS_SDR_GPS_L2_M_PCPS_ACQUISITION_FPGA_H
00021 #define GNSS_SDR_GPS_L2_M_PCPS_ACQUISITION_FPGA_H
00022
00023 #include "base_pcps_acquisition_fpga.h"
00024
00025 /** \addtogroup Acquisition
00026  * \{ */
00027 /** \addtogroup Acq_adapters
00028  * \{ */
00029
00030 /*!
00031 * \brief This class adapts a PCPS acquisition block off-loaded on an FPGA
00032 * to an AcquisitionInterface for GPS L2 M signals
00033 */
00034 class GpsL2MPcpsAcquisitionFpga : public BasePcpsAcquisitionFpga
00035 {
00036 public:
00037     GpsL2MPcpsAcquisitionFpga(
00038         const ConfigurationInterface* configuration,
00039         const std::string& role,
00040         unsigned int in_streams,
00041         unsigned int out_streams);
00042
00043     /*!
00044     * \brief Returns "GPS_L2_M_PCPS_Acquisition_FPGA"
00045     */
00046     inline std::string implementation() override
00047     {
00048         return "GPS_L2_M_PCPS_Acquisition_FPGA";
00049     }
00050
00051 private:
00052     static const uint32_t DEFAULT_FPGA_BLK_EXP = 13; // default block exponent
00053     void generate_gps_l2c_m_prn_codes();
00054 };
00055
00056
00057 /** \} */
00058 /** \} */
00059 #endif // GNSS_SDR_GPS_L2_M_PCPS_ACQUISITION_FPGA_H
```

13.55 gps_l5i_pcps_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L5i signals.

```
#include "base_pcps_acquisition.h"
```

Classes

- class [GpsL5iPcpsAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L5i signals.

13.55.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L5i signals.

Authors

- Javier Arribas, 2017. jarribas(at)cttc.es

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Definition in file [gps_l5i_pcps_acquisition.h](#).

13.56 gps_l5i_pcps_acquisition.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gps_l5i_pcps_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * GPS L5i signals
00005  * \authors <ul>
00006  * <li> Javier Arribas, 2017. jarribas(at)cttc.es
00007  * </li>
00008  * </ul>
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  * -----
00017  */
00018 */
00019
00020 #ifndef GNSS_SDR_GPS_L5I_PCPS_ACQUISITION_H
00021 #define GNSS_SDR_GPS_L5I_PCPS_ACQUISITION_H
00022
00023 #include "base_pcps_acquisition.h"
00024
00025 /** \addtogroup Acquisition
00026  * \{ */
00027 /** \addtogroup Acq_adapters
00028  * \{ */
00029
00030 /*!
00031  * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00032  * for GPS L5i signals
00033  */
00034 class GpsL5iPcpsAcquisition : public BasePcpsAcquisition
00035 {
00036 public:
00037     GpsL5iPcpsAcquisition(
00038         const ConfigurationInterface* configuration,
00039         const std::string& role,
00040         unsigned int in_streams,
00041         unsigned int out_streams);
00042
00043     ~GpsL5iPcpsAcquisition() = default;
00044
00045     /*!
00046     * \brief Returns "GPS_L5i_PCPS_Acquisition"
00047     */
00048     inline std::string implementation() override
00049     {
00050         return "GPS_L5i_PCPS_Acquisition";
00051     }
00052 }
```

```

00051     }
00052
00053 private:
00054     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
        sampling_freq) override;
00055 };
00056
00057
00058 /** \} */
00059 /** \} */
00060 #endif // GNSS_SDR_GPS_L5I_PCPS_ACQUISITION_H

```

13.57 gps_l5i_pcps_acquisition_fpga.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L5i signals for the FPGA.

```
#include "base_pcps_acquisition_fpga.h"
```

Classes

- class [GpsL5iPcpsAcquisitionFpga](#)

This class adapts a PCPS acquisition block off-loaded on an FPGA to an [AcquisitionInterface](#) for GPS L5i signals.

13.57.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for GPS L5i signals for the FPGA.

Authors

- Marc Majoral, 2019. mmajoral(at)cttc.es
- Javier Arribas, 2019. jarribas(at)cttc.es

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 Definition in file [gps_l5i_pcps_acquisition_fpga.h](#).

13.58 gps_l5i_pcps_acquisition_fpga.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gps_l5i_pcps_acquisition_fpga.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * GPS L5i signals for the FPGA
00005  * \authors <ul>
00006  * <li> Marc Majoral, 2019. mmajoral(at)cttc.es
00007  * <li> Javier Arribas, 2019. jarribas(at)cttc.es
00008  * </ul>
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  *
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00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_GPS_L5I_PCPS_ACQUISITION_FPGA_H
00022 #define GNSS_SDR_GPS_L5I_PCPS_ACQUISITION_FPGA_H
00023
00024 #include "base_pcps_acquisition_fpga.h"
00025
00026 /** \addtogroup Acquisition
00027  * \{ */
00028 /** \addtogroup Acq_adapters
00029  * \{ */
00030
00031 /*!
00032  * \brief This class adapts a PCPS acquisition block off-loaded on an FPGA
00033  * to an AcquisitionInterface for GPS L5i signals

```



```

00034  */
00035  class GpsL5iPcpsAcquisitionFpga : public BasePcpsAcquisitionFpga
00036  {
00037  public:
00038      /*!
00039       * \brief Constructor
00040       */
00041      GpsL5iPcpsAcquisitionFpga(
00042          const ConfigurationInterface* configuration,
00043          const std::string& role,
00044          unsigned int in_streams,
00045          unsigned int out_streams);
00046
00047      /*!
00048       * \brief Returns "GPS_L5i_PCPS_Acquisition_FPGA"
00049       */
00050      inline std::string implementation() override
00051      {
00052          return "GPS_L5i_PCPS_Acquisition_FPGA";
00053      }
00054
00055  private:
00056      static const uint32_t DEFAULT_FPGA_BLK_EXP = 13; // default block exponent
00057      void generate_gps_l5i_prn_codes();
00058  };
00059
00060
00061  /** \} */
00062  /** \} */
00063  #endif // GNSS_SDR_GPS_L5I_PCPS_ACQUISITION_FPGA_H

```

13.59 qzss_l1_pcps_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for QZSS L1 signals.

#include "base_pcps_acquisition.h"

Classes

- class [QzssL1PcpsAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for QZSS L1 signals.

13.59.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for QZSS L1 signals.

Authors

- Carles Fernandez, 2026. cfernandez(at)cttc.es

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 Definition in file [qzss_l1_pcps_acquisition.h](#).

13.60 qzss_l1_pcps_acquisition.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002   * \file qzss_l1_pcps_acquisition.h
00003   * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004   * QZSS L1 signals
00005   * \authors <ul>
00006   * <li> Carles Fernandez, 2026. cfernandez(at)cttc.es
00007   * </ul>
00008   *
00009   * -----
00010   *
00011   * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012   * This file is part of GNSS-SDR.
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00016   *

```

```

00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_QZSS_L1_PCPS_ACQUISITION_H
00021 #define GNSS_SDR_QZSS_L1_PCPS_ACQUISITION_H
00022
00023 #include "base_pcps_acquisition.h"
00024
00025 /** \addtogroup Acquisition
00026  * \{ */
00027 /** \addtogroup Acq_adapters
00028  * \{ */
00029
00030 /*!
00031 * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00032 * for QZSS L1 signals
00033 */
00034 class QzssL1PcpsAcquisition : public BasePcpsAcquisition
00035 {
00036 public:
00037     QzssL1PcpsAcquisition(
00038         const ConfigurationInterface* configuration,
00039         const std::string& role,
00040         unsigned int in_streams,
00041         unsigned int out_streams);
00042
00043     ~QzssL1PcpsAcquisition() = default;
00044
00045     /*!
00046     * \brief Returns "QZSS_L1_PCPS_Acquisition"
00047     */
00048     inline std::string implementation() override
00049     {
00050         return "QZSS_L1_PCPS_Acquisition";
00051     }
00052
00053 private:
00054     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
sampling_freq) override;
00055 };
00056
00057
00058 /** \} */
00059 /** \} */
00060
00061
00062 #endif // GNSS_SDR_QZSS_L1_PCPS_ACQUISITION_H

```

13.61 qzss_l5i_pcps_acquisition.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for QZSS L5I signals.

```
#include "base_pcps_acquisition.h"
```

Classes

- class [QzssL5iPcpsAcquisition](#)

This class adapts a PCPS acquisition block to an [AcquisitionInterface](#) for QZSS L5I signals.

13.61.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for QZSS L5I signals.

Authors

- Carles Fernandez, 2026. cfernandez(at)cttc.es

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 Definition in file [qzss_l5i_pcps_acquisition.h](#).

13.62 qzss_l5i_pcps_acquisition.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file qzss_l5i_pcps_acquisition.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  *        QZSS L5I signals
00005  * \authors <ul>
00006  *         <li> Carles Fernandez, 2026. cfernandez(at)cttc.es
00007  *         </li>
00008  *         </ul>
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2026 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  * -----
00017  */
00018  */
00019
00020 #ifndef GNSS_SDR_QZSS_L5I_PCPS_ACQUISITION_H
00021 #define GNSS_SDR_QZSS_L5I_PCPS_ACQUISITION_H
00022
00023 #include "base_pcps_acquisition.h"
00024
00025 /** \addtogroup Acquisition
00026  * \{ */
00027 /** \addtogroup Acq_adapters
00028  * \{ */
00029
00030 /*!
00031 * \brief This class adapts a PCPS acquisition block to an AcquisitionInterface
00032 *        for QZSS L5I signals
00033 */
00034 class QzssL5iPcpsAcquisition : public BasePcpsAcquisition
00035 {
00036 public:
00037     QzssL5iPcpsAcquisition(
00038         const ConfigurationInterface* configuration,
00039         const std::string& role,
00040         unsigned int in_streams,
00041         unsigned int out_streams);
00042
00043     ~QzssL5iPcpsAcquisition() = default;
00044
00045     /*!
00046     * \brief Returns "QZSS_L5I_PCPS_Acquisition"
00047     */
00048     inline std::string implementation() override
00049     {
00050         return "QZSS_L5I_PCPS_Acquisition";
00051     }
00052
00053 private:
00054     void code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
00055         sampling_freq) override;
00056 };
00057
00058 /** \} */
00059 /** \} */
00060
00061
00062 #endif // GNSS_SDR_QZSS_L5I_PCPS_ACQUISITION_H

```

13.63 acquisition_impl_interface.h File Reference

Header file of the interface to an acquisition implementation GNSS block.

```

#include "gnss_block_interface.h"
#include "gnss_synchro.h"
#include <gnuradio/block.h>
#include <complex>
#include <memory>

```

Classes

- class [acquisition_impl_interface](#)

This abstract class represents an interface to an acquisition GNSS block.

Typedefs

- using [acquisition_impl_interface_sptr](#) = gnss_shared_ptr<[acquisition_impl_interface](#)>

13.63.1 Detailed Description

Header file of the interface to an acquisition implementation GNSS block.

Author

Mathieu Favreau, 2025. [favreau.mathieu\(at\)hotmail.com](mailto:favreau.mathieu(at)hotmail.com)

This header file contains the interface to an abstract class for acquisition algorithms. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

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Definition in file [acquisition_impl_interface.h](#).

13.64 acquisition_impl_interface.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file acquisition_impl_interface.h
00003  * \brief Header file of the interface to an acquisition implementation GNSS block.
00004  * \author Mathieu Favreau, 2025. favreau.mathieu(at)hotmail.com
00005  *
00006  * This header file contains the interface to an abstract class
00007  * for acquisition algorithms. Since all its methods are virtual,
00008  * this class cannot be instantiated directly, and a subclass can only be
00009  * instantiated directly if all inherited pure virtual methods have been
00010  * implemented by that class or a parent class.
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_ACQUISITION_IMPL_INTERFACE_H
00024 #define GNSS_SDR_ACQUISITION_IMPL_INTERFACE_H
00025
00026 #include "gnss_block_interface.h"
00027 #include "gnss_synchro.h"
00028 #include <gnuradio/block.h>
00029 #include <complex>
00030 #include <memory>
00031
00032 /** \addtogroup Core
00033  * \{ */
00034 /** \addtogroup GNSS_Block_Interfaces GNSS block interfaces
00035  * GNSS block interfaces.
00036  * \{ */
00037
00038 class ChannelFsm;
00039 class acquisition_impl_interface;
00040
00041 using acquisition_impl_interface_sptr = gnss_shared_ptr<acquisition_impl_interface>;
00042
00043 /*! \brief This abstract class represents an interface to an acquisition GNSS block.
00044  *
00045  * Abstract class for acquisition algorithms. Since all its methods are virtual,
00046  * this class cannot be instantiated directly, and a subclass can only be
00047  * instantiated directly if all inherited pure virtual methods have been
00048  * implemented by that class or a parent class.
00049  */
00050 class acquisition_impl_interface : public gr::block
00051 {
00052 public:
00053     acquisition_impl_interface(const std::string& name,
00054                               gr::io_signature::sptr input_signature,
00055                               gr::io_signature::sptr output_signature) : gr::block(name, std::move(input_signature),
00056                                         std::move(output_signature)) {}

```

```

00056
00057     virtual void set_gnss_synchro(Gnss_Synchro* gnss_synchro) = 0;
00058     virtual void set_channel(uint32_t channel_id) = 0;
00059     virtual void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) = 0;
00060     virtual void set_local_code(std::complex<float>* /*code*/) {};
00061     virtual void set_local_code(std::complex<float>* /*code_data*/, std::complex<float>*
/*code_pilot*/) {};
00062     virtual uint32_t mag() const = 0;
00063     virtual void set_active(bool active) = 0;
00064 };
00065
00066
00067 /** \} */
00068 /** \} */
00069 #endif // GNSS_SDR_ACQUISITION_INTERFACE */

```

13.65 galileo_e5a_noncoherent_iq_acquisition_caf_cc.h File Reference

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E5a data and pilot Signals.

```

#include "acq_conf.h"
#include "acquisition_impl_interface.h"
#include "channel_fsm.h"
#include "gnss_sdr_fft.h"
#include "gnss_synchro.h"
#include <gnuradio/block.h>
#include <gnuradio/gr_complex.h>
#include <fstream>
#include <memory>
#include <string>
#include <utility>
#include <vector>

```

Classes

- class [galileo_e5a_noncoherentIQ_acquisition_caf_cc](#)
This class implements a Parallel Code Phase Search Acquisition.

Typedefs

- using [galileo_e5a_noncoherentIQ_acquisition_caf_cc_sptr](#) = gnss_shared_ptr<[galileo_e5a_noncoherentIQ_acquisition_caf_cc](#)>

Functions

- [galileo_e5a_noncoherentIQ_acquisition_caf_cc_sptr](#) [galileo_e5a_noncoherentIQ_make_acquisition](#) ↵
[caf_cc](#) (const [Acq_Conf](#) &conf, bool both_signal_components, int CAF_window_hz, int Zero_padding)

13.65.1 Detailed Description

Adapts a PCPS acquisition block to an [AcquisitionInterface](#) for Galileo E5a data and pilot Signals.

Author

Marc Sales, 2014. [marcsales92\(at\)gmail.com](mailto:marcsales92(at)gmail.com) \based on work from:

- Javier Arribas, 2011. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)
- Luis Esteve, 2012. [luis\(at\)epsilon-formacion.com](mailto:luis(at)epsilon-formacion.com)
- Marc Molina, 2013. marc.molina.pena@gmail.com

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Definition in file [galileo_e5a_noncoherent_iq_acquisition_caf_cc.h](#).

13.66 galileo_e5a_noncoherent_iq_acquisition_caf_cc.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_e5a_noncoherent_iq_acquisition_caf_cc.h
00003  * \brief Adapts a PCPS acquisition block to an AcquisitionInterface for
00004  * Galileo E5a data and pilot Signals
00005  * \author Marc Sales, 2014. marcsales92(at)gmail.com
00006  * \based on work from:
00007  *      <ul>
00008  *          <li> Javier Arribas, 2011. jarribas(at)cttc.es
00009  *          <li> Luis Esteve, 2012. luis(at)epsilon-formacion.com
00010  *          <li> Marc Molina, 2013. marc.molina.pena@gmail.com
00011  *      </ul>
00012  *
00013  * -----
00014  *
00015  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00017  *
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00019  * SPDX-License-Identifier: GPL-3.0-or-later
00020  *
00021  * -----
00022  */
00023
00024 #ifndef GNSS_SDR_GALILEO_E5A_NONCOHERENT_IQ_ACQUISITION_CAF_CC_H
00025 #define GNSS_SDR_GALILEO_E5A_NONCOHERENT_IQ_ACQUISITION_CAF_CC_H
00026
00027 #include "acq_conf.h"
00028 #include "acquisition_impl_interface.h"
00029 #include "channel_fsm.h"
00030 #include "gnss_sdr_fft.h"
00031 #include "gnss_synchro.h"
00032 #include <gnuradio/block.h>
00033 #include <gnuradio/gr_complex.h>
00034 #include <fstream>
00035 #include <memory>
00036 #include <string>
00037 #include <utility>
00038 #include <vector>
00039
00040 /** \addtogroup Acquisition
00041  * \{ */
00042 /** \addtogroup Acq_gnuradio_blocks
00043  * \{ */
00044
00045
00046 class galileo_e5a_noncoherentIQ_acquisition_caf_cc;
00047
00048 using galileo_e5a_noncoherentIQ_acquisition_caf_cc_sptr =
    gnss_shared_ptr<galileo_e5a_noncoherentIQ_acquisition_caf_cc>;
00049
00050 galileo_e5a_noncoherentIQ_acquisition_caf_cc_sptr galileo_e5a_noncoherentIQ_make_acquisition_caf_cc(
00051     const Acq_Conf& conf,
00052     bool both_signal_components,
00053     int CAF_window_hz,
00054     int Zero_padding);
00055
00056 /*!
00057  * \brief This class implements a Parallel Code Phase Search Acquisition.
00058  *
00059  * Check \ref Navitec2012 "An Open Source Galileo E1 Software Receiver",
00060  * Algorithm 1, for a pseudocode description of this implementation.
00061  */
00062 class galileo_e5a_noncoherentIQ_acquisition_caf_cc : public acquisition_impl_interface
00063 {
00064 public:
00065     /*!
00066      * \brief Default destructor.
00067      */
00068     ~galileo_e5a_noncoherentIQ_acquisition_caf_cc();
00069
00070     /*!
00071      * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00072      * to exchange synchronization data between acquisition and tracking blocks.
00073      * \param p_gnss_synchro Satellite information shared by the processing blocks.
00074      */
00075     inline void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override
00076     {
00077         d_gnss_synchro = p_gnss_synchro;
00078     }
00079
00080     /*!
00081      * \brief Returns the maximum peak of grid search.
00082      */

```

```

00083     inline unsigned int mag() const override
00084     {
00085         return d_mag;
00086     }
00087
00088     /*!
00089     * \brief Sets local code for PCPS acquisition algorithm.
00090     * \param code - Pointer to the PRN code.
00091     */
00092     void set_local_code(std::complex<float>* code, std::complex<float>* codeQ) override;
00093
00094     /*!
00095     * \brief Starts acquisition algorithm, turning from standby mode to
00096     * active mode
00097     * \param active - bool that activates/deactivates the block.
00098     */
00099     inline void set_active(bool active) override
00100     {
00101         if (!active)
00102         {
00103             d_state = 0;
00104         }
00105
00106         d_active = active;
00107     }
00108
00109     /*!
00110     * \brief Set acquisition channel unique ID
00111     * \param channel - receiver channel.
00112     */
00113     inline void set_channel(unsigned int channel) override
00114     {
00115         d_channel = channel;
00116     }
00117
00118     /*!
00119     * \brief Set channel fsm associated to this acquisition instance
00120     */
00121     inline void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) override
00122     {
00123         d_channel_fsm = std::move(channel_fsm);
00124     }
00125
00126     /*!
00127     * \brief Parallel Code Phase Search Acquisition signal processing.
00128     */
00129     int general_work(int noutput_items, gr_vector_int& ninput_items,
00130                     gr_vector_const_void_star& input_items,
00131                     gr_vector_void_star& output_items) override;
00132
00133 private:
00134     friend galileo_e5a_noncoherentIQ_acquisition_caf_cc_sptr
00135     galileo_e5a_noncoherentIQ_make_acquisition_caf_cc(
00136         const Acq_Conf& conf,
00137         bool both_signal_components,
00138         int CAF_window_hz,
00139         int Zero_padding);
00140
00141     galileo_e5a_noncoherentIQ_acquisition_caf_cc(
00142         const Acq_Conf& conf,
00143         bool both_signal_components,
00144         int CAF_window_hz,
00145         int Zero_padding);
00146
00147     void calculate_magnitudes(gr_complex* fft_begin, int doppler_shift,
00148                             int doppler_offset);
00149
00150     float estimate_input_power(gr_complex* in);
00151
00152     std::string d_satellite_str;
00153
00154     const Acq_Conf d_acq_params;
00155     std::ofstream d_dump_file;
00156
00157     Gnss_Synchro* d_gnss_synchro;
00158
00159     uint64_t d_sample_counter;
00160
00161     float d_mag;
00162     float d_input_power;
00163     float d_test_statistics;
00164
00165     int d_state;
00166     const int d_CAF_window_hz;
00167     int d_buffer_count;
00168     int d_doppler_resolution;
00169     const int d_fft_size;

```

```

00170     int d_num_doppler_bins;
00171     unsigned int d_gr_stream_buffer;
00172     unsigned int d_channel;
00173     unsigned int d_well_count;
00174     unsigned int d_sampled_ms;
00175     unsigned int d_code_phase;
00176
00177     bool d_active;
00178     const bool d_both_signal_components;
00179
00180     std::weak_ptr<ChannelFsm> d_channel_fsm;
00181     std::unique_ptr<gnss_fft_complex_fwd> d_fft_if;
00182     std::unique_ptr<gnss_fft_complex_rev> d_ifft;
00183
00184     std::vector<std::vector<gr_complex>> d_grid_doppler_wipeoffs;
00185     std::vector<gr_complex> d_fft_code_I_A;
00186     std::vector<gr_complex> d_fft_code_I_B;
00187     std::vector<gr_complex> d_fft_code_Q_A;
00188     std::vector<gr_complex> d_fft_code_Q_B;
00189     std::vector<gr_complex> d_inbuffer;
00190     std::vector<float> d_magnitudeIA;
00191     std::vector<float> d_magnitudeIB;
00192     std::vector<float> d_magnitudeQA;
00193     std::vector<float> d_magnitudeQB;
00194     std::vector<float> d_CAF_vector;
00195     std::vector<float> d_CAF_vector_I;
00196     std::vector<float> d_CAF_vector_Q;
00197 };
00198
00199
00200 /** \} */
00201 /** \} */
00202 #endif // GNSS_SDR_GALILEO_E5A_NONCOHERENT_IQ_ACQUISITION_CAF_CC_H

```

13.67 galileo_pcps_8ms_acquisition_cc.h File Reference

This class implements a Parallel Code Phase Search Acquisition for Galileo E1 signals with coherent integration time = 8 ms (two codes)

```

#include "acq_conf.h"
#include "acquisition_impl_interface.h"
#include "channel_fsm.h"
#include "gnss_sdr_fft.h"
#include "gnss_synchro.h"
#include <gnuradio/block.h>
#include <gnuradio/gr_complex.h>
#include <fstream>
#include <memory>
#include <string>
#include <utility>
#include <vector>

```

Classes

- class [galileo_pcps_8ms_acquisition_cc](#)

This class implements a Parallel Code Phase Search Acquisition for Galileo E1 signals with coherent integration time = 8 ms (two codes)

Typedefs

- using [galileo_pcps_8ms_acquisition_cc_sptr](#) = gnss_shared_ptr<[galileo_pcps_8ms_acquisition_cc](#)>

Functions

- [galileo_pcps_8ms_acquisition_cc_sptr](#) [galileo_pcps_8ms_make_acquisition_cc](#) (const [Acq_Conf](#) &conf)

13.67.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition for Galileo E1 signals with coherent integration time = 8 ms (two codes)

Author

Marc Molina, 2013. marc.molina.pena(at)gmail.com

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Definition in file [galileo_pcps_8ms_acquisition_cc.h](#).

13.68 galileo_pcps_8ms_acquisition_cc.h

[Go to the documentation of this file.](#)

```
00001  /*!
00002  * \file galileo_pcps_8ms_acquisition_cc.h
00003  * \brief This class implements a Parallel Code Phase Search Acquisition for
00004  * Galileo E1 signals with coherent integration time = 8 ms (two codes)
00005  * \author Marc Molina, 2013. marc.molina.pena(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_PCPS_8MS_ACQUISITION_CC_H
00019 #define GNSS_SDR_PCPS_8MS_ACQUISITION_CC_H
00020
00021 #include "acq_conf.h"
00022 #include "acquisition_impl_interface.h"
00023 #include "channel_fsm.h"
00024 #include "gnss_sdr_fft.h"
00025 #include "gnss_synchro.h"
00026 #include <gnuradio/block.h>
00027 #include <gnuradio/gr_complex.h>
00028 #include <fstream>
00029 #include <memory>
00030 #include <string>
00031 #include <utility>
00032 #include <vector>
00033
00034 /** \addtogroup Acquisition
00035  * \{ */
00036 /** \addtogroup Acq_gnuradio_blocks
00037  * \{ */
00038
00039
00040 class galileo_pcps_8ms_acquisition_cc;
00041
00042 using galileo_pcps_8ms_acquisition_cc_sptr = gnss_shared_ptr<galileo_pcps_8ms_acquisition_cc>;
00043
00044 galileo_pcps_8ms_acquisition_cc_sptr
00045 galileo_pcps_8ms_make_acquisition_cc(const Acq_Conf& conf);
00046
00047 /*!
00048 * \brief This class implements a Parallel Code Phase Search Acquisition for
00049 * Galileo E1 signals with coherent integration time = 8 ms (two codes)
00050 */
00051 class galileo_pcps_8ms_acquisition_cc : public acquisition_impl_interface
00052 {
00053 public:
00054     /*!
00055     * \brief Default destructor.
00056     */
00057     ~galileo_pcps_8ms_acquisition_cc();
00058
00059     /*!
00060     * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00061     * to exchange synchronization data between acquisition and tracking blocks.
00062     * \param p_gnss_synchro Satellite information shared by the processing blocks.
00063     */
00064     inline void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override
00065     {
```

```

00066         d_gnss_synchro = p_gnss_synchro;
00067     }
00068
00069     /*!
00070      * \brief Returns the maximum peak of grid search.
00071      */
00072     inline uint32_t mag() const override
00073     {
00074         return d_mag;
00075     }
00076
00077     /*!
00078      * \brief Sets local code for PCPS acquisition algorithm.
00079      * \param code - Pointer to the PRN code.
00080      */
00081     void set_local_code(std::complex<float>* code) override;
00082
00083     /*!
00084      * \brief Starts acquisition algorithm, turning from standby mode to
00085      * active mode
00086      * \param active - bool that activates/deactivates the block.
00087      */
00088     inline void set_active(bool active) override
00089     {
00090         if (!active)
00091         {
00092             d_state = 0;
00093         }
00094
00095         d_active = active;
00096     }
00097
00098     /*!
00099      * \brief Set acquisition channel unique ID
00100      * \param channel - receiver channel.
00101      */
00102     inline void set_channel(uint32_t channel) override
00103     {
00104         d_channel = channel;
00105     }
00106
00107     /*!
00108      * \brief Set channel fsm associated to this acquisition instance
00109      */
00110     inline void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) override
00111     {
00112         d_channel_fsm = std::move(channel_fsm);
00113     }
00114
00115     /*!
00116      * \brief Parallel Code Phase Search Acquisition signal processing.
00117      */
00118     int general_work(int noutput_items, gr_vector_int& ninput_items,
00119                     gr_vector_const_void_star& input_items,
00120                     gr_vector_void_star& output_items) override;
00121
00122 private:
00123     friend galileo_pcps_8ms_acquisition_cc_sptr
00124     galileo_pcps_8ms_make_acquisition_cc(const Acq_Conf& conf);
00125
00126     explicit galileo_pcps_8ms_acquisition_cc(const Acq_Conf& conf);
00127
00128     void calculate_magnitudes(
00129         gr_complex* fft_begin,
00130         int32_t doppler_shift,
00131         int32_t doppler_offset);
00132
00133     std::string d_satellite_str;
00134     const Acq_Conf d_acq_params;
00135     std::ofstream d_dump_file;
00136
00137     Gnss_Synchro* d_gnss_synchro;
00138
00139     uint64_t d_sample_counter;
00140
00141     float d_mag;
00142     float d_input_power;
00143     float d_test_statistics;
00144     int32_t d_state;
00145     uint32_t d_channel;
00146     uint32_t d_well_count;
00147     const uint32_t d_fft_size;
00148     uint32_t d_num_doppler_bins;
00149     uint32_t d_code_phase;
00150
00151     bool d_active;
00152

```

```

00153     std::weak_ptr<ChannelFsm> d_channel_fsm;
00154     std::unique_ptr<gnss_fft_complex_fwd> d_fft_if;
00155     std::unique_ptr<gnss_fft_complex_rev> d_ifft;
00156
00157     std::vector<std::vector<gr_complex>> d_grid_doppler_wipeoffs;
00158     std::vector<gr_complex> d_fft_code_A;
00159     std::vector<gr_complex> d_fft_code_B;
00160     std::vector<float> d_magnitude;
00161 };
00162
00163
00164 /** \} */
00165 /** \} */
00166 #endif // GNSS_SDR_PCPS_8MS_ACQUISITION_CC_H

```

13.69 pcps_acquisition.h File Reference

This class implements a Parallel Code Phase Search Acquisition.

```

#include "acquisition_impl_interface.h"
#include "acq_conf.h"
#include "channel_fsm.h"
#include "gnss_sdr_fft.h"
#include <armadillo>
#include <gnuradio/block.h>
#include <gnuradio/gr_complex.h>
#include <gnuradio/thread/thread.h>
#include <gnuradio/types.h>
#include <volk/volk_complex.h>
#include <volk_gnssssdr/volk_gnssssdr_alloc.h>
#include <complex>
#include <cstdint>
#include <memory>
#include <queue>
#include <string>
#include <utility>
#include <gsl-lite/gsl-lite.hpp>

```

Classes

- class [pcps_acquisition](#)

This class implements a Parallel Code Phase Search Acquisition.

Typedefs

- using [pcps_acquisition_sptr](#) = [gnss_shared_ptr](#)<[pcps_acquisition](#)>

Functions

- [pcps_acquisition_sptr pcps_make_acquisition](#) (const [Acq_Conf](#) &conf_)

13.69.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition.

Acquisition strategy (Kay Borre book + CFAR threshold).

1. Compute the input signal power estimation
2. Doppler serial search loop
3. Perform the FFT-based circular convolution (parallel time search)
4. Record the maximum peak and the associated synchronization parameters

5. Compute the test statistics and compare to the threshold
6. Declare positive or negative acquisition using a message queue

Kay Borre book: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, "A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach", Birkhauser, 2007. pp 81-84

Authors

- Javier Arribas, 2011. jarribas(at)cttc.es
- Luis Esteve, 2012. luis(at)epsilon-formacion.com
- Marc Molina, 2013. marc.molina.pena@gmail.com
- Cillian O'Driscoll, 2017. cillian(at)ieee.org
- Antonio Ramos, 2017. antonio.ramos@cttc.es

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 Definition in file [pcps_acquisition.h](#).

13.70 pcps_acquisition.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file pcps_acquisition.h
00003  * \brief This class implements a Parallel Code Phase Search Acquisition
00004  *
00005  * Acquisition strategy (Kay Borre book + CFAR threshold).
00006  * <ol>
00007  * <li> Compute the input signal power estimation
00008  * <li> Doppler serial search loop
00009  * <li> Perform the FFT-based circular convolution (parallel time search)
00010  * <li> Record the maximum peak and the associated synchronization parameters
00011  * <li> Compute the test statistics and compare to the threshold
00012  * <li> Declare positive or negative acquisition using a message queue
00013  * </ol>
00014  *
00015  * Kay Borre book: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00016  * "A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00017  * Approach", Birkhauser, 2007. pp 81-84
00018  *
00019  * \authors <ul>
00020  * <li> Javier Arribas, 2011. jarribas(at)cttc.es
00021  * <li> Luis Esteve, 2012. luis(at)epsilon-formacion.com
00022  * <li> Marc Molina, 2013. marc.molina.pena@gmail.com
00023  * <li> Cillian O'Driscoll, 2017. cillian(at)ieee.org
00024  * <li> Antonio Ramos, 2017. antonio.ramos@cttc.es
00025  * </ul>
00026  *
00027  * -----
00028  *
00029  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00030  * This file is part of GNSS-SDR.
00031  *
00032  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00033  * SPDX-License-Identifier: GPL-3.0-or-later
00034  *
00035  * -----
00036  */
00037
00038 #ifndef GNSS_SDR_PCPS_ACQUISITION_H
00039 #define GNSS_SDR_PCPS_ACQUISITION_H
00040
00041 #include "acquisition_impl_interface.h"
00042 #if ARMA_NO_BOUND_CHECKING
00043 #define ARMA_NO_DEBUG 1
00044 #endif
00045
00046 #include "acq_conf.h"
00047 #include "channel_fsm.h"
00048 #include "gnss_sdr_fft.h"
00049 #include <armadillo>
00050 #include <gnuradio/block.h>
00051 #include <gnuradio/gr_complex.h> // for gr_complex
00052 #include <gnuradio/thread/thread.h> // for scoped_lock
00053 #include <gnuradio/types.h> // for gr_vector_const_void_star
00054 #include <volk/volk_complex.h> // for lv_16sc_t
00055 #include <volk_gnssdr/volk_gnssdr_alloc.h> // for volk_gnssdr::vector

```

```

00056 #include <complex>
00057 #include <cstdint>
00058 #include <memory>
00059 #include <queue>
00060 #include <string>
00061 #include <utility>
00062
00063
00064 #if HAS_STD_SPAN
00065 #include <span>
00066 namespace own = std;
00067 #else
00068 #include <gsl-lite/gsl-lite.hpp>
00069 namespace own = gsl_lite;
00070 #endif
00071
00072 /** \addtogroup Acquisition
00073  * Classes for GNSS signal acquisition
00074  * \{ */
00075 /** \addtogroup Acq_gnuradio_blocks acquisition_gr_blocks
00076  * GNU Radio processing blocks for GNSS signal acquisition
00077  * \{ */
00078
00079
00080 class Gnss_Synchro;
00081 class pcps_acquisition;
00082
00083 using pcps_acquisition_sptr = gnss_shared_ptr<pcps_acquisition>;
00084
00085 pcps_acquisition_sptr pcps_make_acquisition(const Acq_Conf& conf_);
00086
00087 /*!
00088  * \brief This class implements a Parallel Code Phase Search Acquisition.
00089  *
00090  * Check \ref Navitec2012 "An Open Source Galileo E1 Software Receiver",
00091  * Algorithm 1, for a pseudocode description of this implementation.
00092  */
00093 class pcps_acquisition : public acquisition_impl_interface
00094 {
00095 public:
00096     ~pcps_acquisition() override;
00097
00098     /*!
00099     * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00100     * to exchange synchronization data between acquisition and tracking blocks.
00101     * \param p_gnss_synchro Satellite information shared by the processing blocks.
00102     */
00103     inline void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override
00104     {
00105         gr::thread::scoped_lock lock(d_setlock); // require mutex with work function called by the
scheduler
00106         d_gnss_synchro = p_gnss_synchro;
00107     }
00108
00109     /*!
00110     * \brief Sets local code for PCPS acquisition algorithm.
00111     * \param code - Pointer to the PRN code.
00112     */
00113     void set_local_code(std::complex<float>* code) override;
00114
00115     void set_resampler_latency(uint32_t latency_samples);
00116
00117     /*!
00118     * \brief Returns the maximum peak of grid search.
00119     */
00120     inline uint32_t mag() const override
00121     {
00122         return 0; // Not implemented
00123     }
00124
00125     /*!
00126     * \brief Starts acquisition algorithm, turning from standby mode to
00127     * active mode
00128     * \param active - bool that activates/deactivates the block.
00129     */
00130     void set_active(bool active) override;
00131
00132     /*!
00133     * \brief Set acquisition channel unique ID
00134     * \param channel - receiver channel.
00135     */
00136     inline void set_channel(uint32_t channel) override
00137     {
00138         d_channel = channel;
00139     }
00140
00141     /*!

```

```

00142     * \brief Set channel fsm associated to this acquisition instance
00143     */
00144     inline void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) override
00145     {
00146         d_channel_fsm = std::move(channel_fsm);
00147     }
00148
00149     /*!
00150     * \brief Set Doppler center frequency for the grid search. It will refresh the Doppler grid.
00151     * \param doppler_center - Frequency center of the search grid [Hz].
00152     */
00153     void set_doppler_center(int32_t doppler_center);
00154
00155     /*!
00156     * \brief Parallel Code Phase Search Acquisition signal processing.
00157     */
00158     int general_work(int noutput_items, gr_vector_int& ninput_items,
00159                     gr_vector_const_void_star& input_items,
00160                     gr_vector_void_star& output_items) override;
00161
00162 private:
00163     friend pcps_acquisition_sptr pcps_make_acquisition(const Acq_Conf& conf_);
00164     explicit pcps_acquisition(const Acq_Conf& conf_);
00165
00166     struct AcquisitionResult
00167     {
00168         int32_t doppler{0};
00169         uint32_t index_time{0};
00170         uint64_t sample_count{0};
00171         float test_statistics{0};
00172         bool positive_acq{false};
00173     };
00174
00175     void update_local_carrier(own::span<gr_complex> carrier_vector, float freq) const;
00176     void update_grid_doppler_wipeoffs();
00177     void update_grid_doppler_wipeoffs_step2();
00178     void doppler_grid(const gr_complex* in);
00179     AcquisitionResult compute_statistics();
00180     void update_synchro(const AcquisitionResult& result);
00181     void handle_threshold_reached(AcquisitionResult& result);
00182     void handle_integration_done(const AcquisitionResult& result);
00183     void acquisition_core(uint64_t sample_count);
00184     void log_acquisition(const AcquisitionResult& result) const;
00185     void send_negative_acquisition(const AcquisitionResult& result);
00186     void send_positive_acquisition(const AcquisitionResult& result);
00187     void dump_results(const AcquisitionResult& result);
00188     bool is_fdma();
00189     float get_threshold() const;
00190     AcquisitionResult first_vs_second_peak_statistic(uint32_t num_doppler_bins, int32_t doppler_max,
00191 int32_t doppler_step);
00192     AcquisitionResult max_to_input_power_statistic(uint32_t num_doppler_bins, int32_t doppler_max,
00193 int32_t doppler_step);
00194     void wait_if_active();
00195
00196     const Acq_Conf d_acq_parameters;
00197     const std::string d_dump_filename;
00198     const float d_doppler_max;
00199     const uint32_t d_samplesPerChip;
00200     const uint32_t d_doppler_step;
00201     const uint32_t d_consumed_samples;
00202     const uint32_t d_fft_size;
00203     const uint32_t d_effective_fft_size;
00204     const uint32_t d_num_doppler_bins;
00205     const uint32_t d_num_doppler_bins_step2;
00206     const uint32_t d_dump_channel;
00207     const float d_threshold;
00208     const float d_threshold_step_two;
00209     const bool d_cshort;
00210     const bool d_use_CFAR_algorithm_flag;
00211     const bool d_dump;
00212
00213     // Need lock to access these
00214     std::weak_ptr<ChannelFsm> d_channel_fsm;
00215     std::unique_ptr<gr::thread::thread> d_worker;
00216     Gnss_Synchro* d_gnss_synchro;
00217     std::queue<Gnss_Synchro> d_monitor_queue;
00218     int32_t d_state;
00219     int32_t d_doppler_center;
00220     int32_t d_doppler_bias;
00221     uint32_t d_buffer_count;
00222     uint32_t d_channel;
00223     uint32_t d_resampler_latency_samples;
00224     uint64_t d_sample_count;
00225     bool d_step_two;
00226     bool d_active;
00227     bool d_worker_active;

```

```

00227 // Only access these in acquisition_core and functions strictly called from acquisition_core
00228 uint32_t d_num_noncoherent_integrations_counter;
00229 int64_t d_dump_number;
00230 float d_input_power;
00231 float d_doppler_center_step_two;
00232 volk_gnssssdr::vector<volk_gnssssdr::vector<float> d_magnitude_grid;
00233 volk_gnssssdr::vector<float> d_tmp_buffer;
00234 volk_gnssssdr::vector<std::complex<float> d_input_signal;
00235 volk_gnssssdr::vector<volk_gnssssdr::vector<std::complex<float>> d_grid_doppler_wipeoffs_step_two;
00236 std::unique_ptr<gnss_fft_complex_rev> d_ifft;
00237 arma::fmat d_grid;
00238 arma::fmat d_narrow_grid;
00239
00240 // These are never accessed outside acquisition_core while acquisition is active
00241 volk_gnssssdr::vector<volk_gnssssdr::vector<std::complex<float>> d_grid_doppler_wipeoffs;
00242 volk_gnssssdr::vector<std::complex<float> d_fft_codes;
00243 volk_gnssssdr::vector<std::complex<float> d_data_buffer;
00244 volk_gnssssdr::vector<lv_l6sc_t> d_data_buffer_sc;
00245 std::unique_ptr<gnss_fft_complex_fwd> d_fft_if;
00246 };
00247
00248
00249 /** \} */
00250 /** \} */
00251 #endif // GNSS_SDR_PCPS_ACQUISITION_H

```

13.71 pcps_acquisition_fine_doppler_cc.h File Reference

This class implements a Parallel Code Phase Search Acquisition with multi-dwells and fine Doppler estimation for GPS L1 C/A signal.

```

#include "acquisition_impl_interface.h"
#include "acq_conf.h"
#include "channel_fsm.h"
#include "gnss_sdr_fft.h"
#include "gnss_synchro.h"
#include <armadillo>
#include <gnuradio/block.h>
#include <gnuradio/gr_complex.h>
#include <volk_gnssssdr/volk_gnssssdr_alloc.h>
#include <stdint>
#include <fstream>
#include <memory>
#include <string>
#include <utility>

```

Classes

- class [pcps_acquisition_fine_doppler_cc](#)
This class implements a Parallel Code Phase Search Acquisition.

Typedefs

- using [pcps_acquisition_fine_doppler_cc_sptr](#) = [gnss_shared_ptr](#)<[pcps_acquisition_fine_doppler_cc](#)>

Functions

- [pcps_acquisition_fine_doppler_cc_sptr](#) [pcps_make_acquisition_fine_doppler_cc](#) (const [Acq_Conf](#) &conf_)

13.71.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition with multi-dwells and fine Doppler estimation for GPS L1 C/A signal.

Acquisition strategy (Kay Borre book).

1. Compute the input signal power estimation
2. Doppler serial search loop
3. Perform the FFT-based circular convolution (parallel time search)
4. Record the maximum peak and the associated synchronization parameters
5. Compute the test statistics and compare to the threshold
6. Declare positive or negative acquisition using a message port

Kay Borre book: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, "A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach", Birkhauser, 2007. pp 81-84

Authors

- Javier Arribas, 2013. jarribas(at)cttc.es

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 Definition in file [pcps_acquisition_fine_doppler_cc.h](#).

13.72 pcps_acquisition_fine_doppler_cc.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file pcps_acquisition_fine_doppler_cc.h
00003  * \brief This class implements a Parallel Code Phase Search Acquisition with multi-dwells and fine
00004  *       Doppler estimation
00005  *       for GPS L1 C/A signal
00006  *
00007  * Acquisition strategy (Kay Borre book).
00008  * <ol>
00009  * <li> Compute the input signal power estimation
00010  * <li> Doppler serial search loop
00011  * <li> Perform the FFT-based circular convolution (parallel time search)
00012  * <li> Record the maximum peak and the associated synchronization parameters
00013  * <li> Compute the test statistics and compare to the threshold
00014  * <li> Declare positive or negative acquisition using a message port
00015  * </ol>
00016  *
00017  * Kay Borre book: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00018  * "A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00019  * Approach", Birkhauser, 2007. pp 81-84
00020  *
00021  * \authors <ul>
00022  * <li> Javier Arribas, 2013. jarribas(at)cttc.es
00023  * </ul>
00024  *
00025  * -----
00026  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00027  * This file is part of GNSS-SDR.
00028  *
00029  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00030  * SPDX-License-Identifier: GPL-3.0-or-later
00031  *
00032  * -----
00033  */
00034
00035 #ifndef GNSS_SDR_PCPS_ACQUISITION_FINE_DOPPLER_CC_H
00036 #define GNSS_SDR_PCPS_ACQUISITION_FINE_DOPPLER_CC_H
00037
00038 #include "acquisition_impl_interface.h"
00039 #if ARMA_NO_BOUND_CHECKING
00040 #define ARMA_NO_DEBUG 1
00041 #endif
00042
00043 #include "acq_conf.h"
00044 #include "channel_fsm.h"
00045 #include "gnss_sdr_fft.h"
00046 #include "gnss_synchro.h"
00047 #include <armadillo>
00048 #include <gnuradio/block.h>
00049 #include <gnuradio/gr_complex.h>
00050 #include <volk_gnssssdr/volk_gnssssdr_alloc.h> // for volk_gnssssdr::vector
00051 #include <cstdlib>
00052 #include <fstream>

```



```

00053 #include <memory>
00054 #include <string>
00055 #include <utility>
00056
00057
00058 /** \addtogroup Acquisition
00059  * \{ */
00060 /** \addtogroup Acq_gnuradio_blocks
00061  * \{ */
00062
00063
00064 class pcps_acquisition_fine_doppler_cc;
00065
00066 using pcps_acquisition_fine_doppler_cc_sptr = gnss_shared_ptr<pcps_acquisition_fine_doppler_cc>;
00067
00068 pcps_acquisition_fine_doppler_cc_sptr pcps_make_acquisition_fine_doppler_cc(const Acq_Conf& conf_);
00069
00070 /*!
00071  * \brief This class implements a Parallel Code Phase Search Acquisition.
00072  *
00073  */
00074 class pcps_acquisition_fine_doppler_cc : public acquisition_impl_interface
00075 {
00076 public:
00077     /*!
00078      * \brief Default destructor.
00079      */
00080     ~pcps_acquisition_fine_doppler_cc() = default;
00081
00082     /*!
00083      * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00084      * to exchange synchronization data between acquisition and tracking blocks.
00085      * \param p_gnss_synchro Satellite information shared by the processing blocks.
00086      */
00087     inline void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override
00088     {
00089         d_gnss_synchro = p_gnss_synchro;
00090     }
00091
00092     /*!
00093      * \brief Returns the maximum peak of grid search.
00094      */
00095     inline unsigned int mag() const override
00096     {
00097         return d_test_statistics;
00098     }
00099
00100     /*!
00101      * \brief Sets local code for PCPS acquisition algorithm.
00102      * \param code - Pointer to the PRN code.
00103      */
00104     void set_local_code(std::complex<float>* code) override;
00105
00106     /*!
00107      * \brief Starts acquisition algorithm, turning from standby mode to
00108      * active mode
00109      * \param active - bool that activates/deactivates the block.
00110      */
00111     inline void set_active(bool active) override
00112     {
00113         if (!active)
00114         {
00115             d_state = 0;
00116         }
00117
00118         d_active = active;
00119     }
00120
00121     /*!
00122      * \brief Set acquisition channel unique ID
00123      * \param channel - receiver channel.
00124      */
00125     inline void set_channel(unsigned int channel) override
00126     {
00127         d_channel = channel;
00128         d_dump_channel = d_channel;
00129     }
00130
00131     /*!
00132      * \brief Set channel fsm associated to this acquisition instance
00133      */
00134     inline void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) override
00135     {
00136         d_channel_fsm = std::move(channel_fsm);
00137     }
00138
00139     /*!

```

```

00140     * \brief Parallel Code Phase Search Acquisition signal processing.
00141     */
00142 int general_work(int noutput_items, gr_vector_int& ninput_items,
00143     gr_vector_const_void_star& input_items,
00144     gr_vector_void_star& output_items) override;
00145
00146 private:
00147     /*!
00148     * \brief Obtains the next power of 2 greater or equal to the input parameter
00149     * \param n - Integer value to obtain the next power of 2.
00150     */
00151     unsigned int nextPowerOf2(unsigned int n);
00152
00153     void dump_results(int effective_fft_size);
00154
00155     void forecast(int noutput_items, gr_vector_int& ninput_items_required) override;
00156
00157     friend pcps_acquisition_fine_doppler_cc_sptr pcps_make_acquisition_fine_doppler_cc(const Acq_Conf&
conf_);
00158     explicit pcps_acquisition_fine_doppler_cc(const Acq_Conf& conf_);
00159
00160     int compute_and_accumulate_grid(gr_vector_const_void_star& input_items);
00161     int estimate_Doppler();
00162     float estimate_input_power(gr_vector_const_void_star& input_items);
00163     float compute_CAF();
00164     void reset_grid();
00165     void update_carrier_wipeoff();
00166     bool start() override;
00167
00168     arma::fmat grid_;
00169
00170     std::string d_satellite_str;
00171
00172     const Acq_Conf d_acq_params;
00173     std::string d_dump_filename;
00174
00175     Gnss_Synchro* d_gnss_synchro;
00176
00177     int64_t d_dump_number;
00178     uint64_t d_sample_counter;
00179
00180     float d_test_statistics;
00181
00182     int d_positive_acq;
00183     int d_state;
00184     const int d_num_doppler_points;
00185     int d_well_count;
00186     int d_n_samples_in_buffer;
00187     const int d_fft_size;
00188     int d_gnuradio_forecast_samples;
00189     unsigned int d_channel;
00190     unsigned int d_dump_channel;
00191
00192     bool d_active;
00193     bool d_dump;
00194
00195     std::weak_ptr<ChannelFsm> d_channel_fsm;
00196     std::unique_ptr<gnss_fft_complex_fwd> d_fft_if;
00197     std::unique_ptr<gnss_fft_complex_rev> d_ifft;
00198
00199     volk_gnssssdr::vector<volk_gnssssdr::vector<std::complex<float>>> d_grid_doppler_wipeoffs;
00200     volk_gnssssdr::vector<volk_gnssssdr::vector<float>> d_grid_data;
00201     volk_gnssssdr::vector<gr_complex> d_fft_codes;
00202     volk_gnssssdr::vector<gr_complex> d_10_ms_buffer;
00203     volk_gnssssdr::vector<float> d_magnitude;
00204 };
00205
00206
00207 /** \} */
00208 /** \} */
00209 #endif // GNSS_SDR_PCPS_ACQUISITION_FINE_DOPPLER_CC_H

```

13.73 pcps_acquisition_fpga.h File Reference

This class implements a Parallel Code Phase Search Acquisition for the FPGA.

```

#include "acq_conf_fpga.h"
#include "channel_fsm.h"
#include "fpga_acquisition.h"
#include <stdint>
#include <memory>
#include <string>

```

```
#include <utility>
#include <vector>
```

Classes

- class [pcps_acquisition_fpga](#)

This class implements a Parallel Code Phase Search Acquisition that uses the FPGA.

Typedefs

- using [pcps_acquisition_fpga_sptr](#) = std::shared_ptr<[pcps_acquisition_fpga](#)>

Functions

- [pcps_acquisition_fpga_sptr pcps_make_acquisition_fpga](#) ([Acq_Conf_Fpga](#) *conf_, uint32_t acq_buff_↔ num, std::vector< std::pair< uint32_t, uint32_t > > &downsampling_filter_specs, uint32_t &max_FFT_size)

13.73.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition for the FPGA.

Kay Borre book: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, "A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach", Birkhauser, 2007. pp 81-84

Authors

- Marc Majoral, 2019. mmajoral(at)cttc.es
- Javier Arribas, 2019. jarribas(at)cttc.es

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 Definition in file [pcps_acquisition_fpga.h](#).

13.74 pcps_acquisition_fpga.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file pcps_acquisition_fpga.h
00003  * \brief This class implements a Parallel Code Phase Search Acquisition for the FPGA
00004  *
00005  *
00006  * Kay Borre book: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00007  * "A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00008  * Approach", Birkhauser, 2007. pp 81-84
00009  *
00010  * \authors <ul>
00011  *         <li> Marc Majoral, 2019. mmajoral(at)cttc.es
00012  *         <li> Javier Arribas, 2019. jarribas(at)cttc.es
00013  *         </li>
00014  * </ul>
00015  * -----
00016  *
00017  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00018  * This file is part of GNSS-SDR.
00019  *
00020  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00021  * SPDX-License-Identifier: GPL-3.0-or-later
00022  *
00023  * -----
00024  */
00025
00026 #ifndef GNSS_SDR_PCPS_ACQUISITION_FPGA_H
00027 #define GNSS_SDR_PCPS_ACQUISITION_FPGA_H
00028
00029 #include "acq_conf_fpga.h"
00030 #include "channel_fsm.h"
00031 #include "fpga_acquisition.h"
00032 #include <cstdint> // for uint32_t
00033 #include <memory> // for shared_ptr
00034 #include <string> // for string
```

```

00035 #include <utility> // for for std::move, std::pair
00036 #include <vector>    // for std::vector
00037
00038 /** \addtogroup Acquisition
00039  * \{ */
00040 /** \addtogroup Acq_gnuradio_blocks
00041  * \{ */
00042
00043
00044 class Gnss_Synchro;
00045
00046 class pcps_acquisition_fpga;
00047
00048 using pcps_acquisition_fpga_sptr = std::shared_ptr<pcps_acquisition_fpga>;
00049
00050 pcps_acquisition_fpga_sptr pcps_make_acquisition_fpga(Acq_Conf_Fpga* conf_, uint32_t acq_buff_num,
00051 std::vector<std::pair<uint32_t, uint32_t>& downsampling_filter_specs, uint32_t& max_FFT_size);
00052
00053 /*!
00054  * \brief This class implements a Parallel Code Phase Search Acquisition that uses the FPGA.
00055  *
00056  * Check \ref Navitec2012 "An Open Source Galileo E1 Software Receiver",
00057  * Algorithm 1, for a pseudocode description of this implementation.
00058  */
00059 class pcps_acquisition_fpga
00060 {
00061 public:
00062     /*!
00063      * \brief Destructor
00064      */
00065     ~pcps_acquisition_fpga() = default;
00066
00067     /*!
00068      * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00069      * to exchange synchronization data between acquisition and tracking blocks.
00070      * \param p_gnss_synchro Satellite information shared by the processing blocks.
00071      */
00072     inline void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro)
00073     {
00074         d_gnss_synchro = p_gnss_synchro;
00075     }
00076
00077     /*!
00078      * \brief Returns the maximum peak of grid search.
00079      */
00080     inline uint32_t mag() const
00081     {
00082         return d_mag;
00083     }
00084
00085     /*!
00086      * \brief Initializes acquisition algorithm.
00087      */
00088     void init();
00089
00090     /*!
00091      * \brief Sets local code for PCPS acquisition algorithm.
00092      */
00093     void set_local_code();
00094
00095     /*!
00096      * \brief Starts acquisition algorithm, turning from standby mode to
00097      * active mode
00098      * \param active - bool that activates/deactivates the block.
00099      */
00100     void set_active(bool active);
00101
00102     /*!
00103      * \brief Set acquisition channel unique ID
00104      * \param channel - receiver channel.
00105      */
00106     inline void set_channel(uint32_t channel)
00107     {
00108         d_channel = channel;
00109     }
00110
00111     /*!
00112      * \brief Set channel fsm associated to this acquisition instance
00113      */
00114     inline void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm)
00115     {
00116         d_channel_fsm = std::move(channel_fsm);
00117     }
00118
00119     /*!
00120      * \brief Set Doppler center frequency for the grid search. It will refresh the Doppler grid.
00121      * \param doppler_center - Frequency center of the search grid [Hz].

```

```

00121     */
00122 void set_doppler_center(int32_t doppler_center);
00123
00124     /*!
00125     * \brief This function triggers a HW reset of the FPGA PL.
00126     */
00127 void reset_acquisition();
00128
00129     /*!
00130     * \brief stop the acquisition and the other FPGA modules.
00131     */
00132 void stop_acquisition();
00133
00134 private:
00135     friend pcps_acquisition_fpga_sptr pcps_make_acquisition_fpga(Acq_Conf_Fpga* conf, uint32_t
acq_buff_num, std::vector<std::pair<uint32_t, uint32_t>& downsampling_filter_specs, uint32_t&
max_FFT_size);
00136     explicit pcps_acquisition_fpga(Acq_Conf_Fpga* conf, uint32_t acq_buff_num,
std::vector<std::pair<uint32_t, uint32_t>& downsampling_filter_specs, uint32_t& max_FFT_size);
00137
00138     void send_negative_acquisition();
00139     void send_positive_acquisition();
00140     void acquisition_core(uint32_t num_doppler_bins, uint32_t doppler_step, int32_t doppler_min);
00141     float first_vs_second_peak_statistic(uint32_t& index, int32_t& doppler, uint32_t
num_doppler_bins, int32_t doppler_max, int32_t doppler_step);
00142
00143     std::shared_ptr<Fpga_Acquisition> d_acquisition_fpga;
00144     std::weak_ptr<ChannelFsm> d_channel_fsm;
00145
00146     Acq_Conf_Fpga* d_acq_parameters;
00147
00148     Gnss_Synchro* d_gnss_synchro;
00149
00150     uint64_t d_sample_counter;
00151
00152     const float d_threshold;
00153     float d_mag;
00154     float d_input_power;
00155     float d_test_statistics;
00156     float d_doppler_step2;
00157     float d_doppler_center_step_two;
00158
00159     int32_t d_doppler_center;
00160     int32_t d_state;
00161
00162     uint32_t d_doppler_index;
00163     uint32_t d_channel;
00164     const uint32_t d_doppler_step;
00165     const uint32_t d_doppler_max;
00166     const uint32_t d_num_doppler_bins;
00167     uint32_t d_total_block_exp;
00168     uint32_t d_num_doppler_bins_step2;
00169     uint32_t d_max_num_acqs;
00170
00171     bool d_active;
00172     bool d_make_2_steps;
00173 };
00174
00175
00176 /** @} */
00177 /** @} */
00178 #endif // GNSS_SDR_PCPS_ACQUISITION_FPGA_H

```

13.75 pcps_assisted_acquisition_cc.h File Reference

This class implements a Parallel Code Phase Search Acquisition with assistance and multi-dwells.

```

#include "acq_conf.h"
#include "acquisition_impl_interface.h"
#include "channel_fsm.h"
#include "gnss_sdr_fft.h"
#include "gnss_synchro.h"
#include <gnuradio/block.h>
#include <gnuradio/gr_complex.h>
#include <fstream>
#include <memory>
#include <string>
#include <utility>
#include <vector>

```

Classes

- class [pcps_assisted_acquisition_cc](#)
This class implements a Parallel Code Phase Search Acquisition.

Typedefs

- using [pcps_assisted_acquisition_cc_sptr](#) = gnss_shared_ptr<[pcps_assisted_acquisition_cc](#)>

Functions

- [pcps_assisted_acquisition_cc_sptr pcps_make_assisted_acquisition_cc](#) (const [Acq_Conf](#) &conf)

13.75.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition with assistance and multi-dwells. Acquisition strategy (Kay Borre book + CFAR threshold).

1. Compute the input signal power estimation
2. Doppler serial search loop
3. Perform the FFT-based circular convolution (parallel time search)
4. Record the maximum peak and the associated synchronization parameters
5. Compute the test statistics and compare to the threshold
6. Declare positive or negative acquisition using a message queue

Kay Borre book: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, "A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach", Birkhauser, 2007. pp 81-84

Authors

- Javier Arribas, 2013. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)

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Definition in file [pcps_assisted_acquisition_cc.h](#).

13.76 pcps_assisted_acquisition_cc.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file pcps_assisted_acquisition_cc.h
00003  * \brief This class implements a Parallel Code Phase Search Acquisition with assistance and
00004  * multi-dwells
00005  * Acquisition strategy (Kay Borre book + CFAR threshold).
00006  * <ol>
00007  * <li> Compute the input signal power estimation
00008  * <li> Doppler serial search loop
00009  * <li> Perform the FFT-based circular convolution (parallel time search)
00010  * <li> Record the maximum peak and the associated synchronization parameters
00011  * <li> Compute the test statistics and compare to the threshold
00012  * <li> Declare positive or negative acquisition using a message queue
00013  * </ol>
00014  *
00015  * Kay Borre book: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00016  * "A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00017  * Approach", Birkhauser, 2007. pp 81-84
00018  *
00019  * \authors <ul>
00020  * <li> Javier Arribas, 2013. jarribas\(at\)cttc.es
00021  * </ul>
00022  *
00023  * -----
```

```

00024  *
00025  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00026  * This file is part of GNSS-SDR.
00027  *
00028  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00029  * SPDX-License-Identifier: GPL-3.0-or-later
00030  *
00031  * -----
00032  */
00033
00034 #ifndef GNSS_SDR_PCPS_ASSISTED_ACQUISITION_CC_H
00035 #define GNSS_SDR_PCPS_ASSISTED_ACQUISITION_CC_H
00036
00037 #include "acq_conf.h"
00038 #include "acquisition_impl_interface.h"
00039 #include "channel_fsm.h"
00040 #include "gnss_sdr_fft.h"
00041 #include "gnss_synchro.h"
00042 #include <gnuradio/block.h>
00043 #include <gnuradio/gr_complex.h>
00044 #include <fstream>
00045 #include <memory>
00046 #include <string>
00047 #include <utility>
00048 #include <vector>
00049
00050 /** \addtogroup Acquisition
00051  * \{ */
00052 /** \addtogroup Acq_gnuradio_blocks
00053  * \{ */
00054
00055
00056 class pcps_assisted_acquisition_cc;
00057
00058 using pcps_assisted_acquisition_cc_sptr = gnss_shared_ptr<pcps_assisted_acquisition_cc>;
00059
00060 pcps_assisted_acquisition_cc_sptr pcps_make_assisted_acquisition_cc(const Acq_Conf& conf);
00061
00062 /*!
00063  * \brief This class implements a Parallel Code Phase Search Acquisition.
00064  *
00065  * Check \ref Navitec2012 "An Open Source Galileo E1 Software Receiver",
00066  * Algorithm 1, for a pseudocode description of this implementation.
00067  */
00068 class pcps_assisted_acquisition_cc : public acquisition_impl_interface
00069 {
00070 public:
00071     /*!
00072      * \brief Default destructor.
00073      */
00074     ~pcps_assisted_acquisition_cc();
00075
00076     /*!
00077      * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00078      * to exchange synchronization data between acquisition and tracking blocks.
00079      * \param p_gnss_synchro Satellite information shared by the processing blocks.
00080      */
00081     inline void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override
00082     {
00083         d_gnss_synchro = p_gnss_synchro;
00084     }
00085
00086     /*!
00087      * \brief Returns the maximum peak of grid search.
00088      */
00089     inline uint32_t mag() const override
00090     {
00091         return d_test_statistics;
00092     }
00093
00094     /*!
00095      * \brief Sets local code for PCPS acquisition algorithm.
00096      * \param code - Pointer to the PRN code.
00097      */
00098     void set_local_code(std::complex<float>* code) override;
00099
00100     /*!
00101      * \brief Starts acquisition algorithm, turning from standby mode to
00102      * active mode
00103      * \param active - bool that activates/deactivates the block.
00104      */
00105     inline void set_active(bool active) override
00106     {
00107         if (!active)
00108         {
00109             d_state = 0;
00110         }
00111     }

```

```

00111
00112     d_active = active;
00113 }
00114
00115 /*!
00116  * \brief Set acquisition channel unique ID
00117  * \param channel - receiver channel.
00118  */
00119 inline void set_channel(uint32_t channel) override
00120 {
00121     d_channel = channel;
00122 }
00123
00124 /*!
00125  * \brief Set channel fsm associated to this acquisition instance
00126  */
00127 inline void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) override
00128 {
00129     d_channel_fsm = std::move(channel_fsm);
00130 }
00131
00132 /*!
00133  * \brief Parallel Code Phase Search Acquisition signal processing.
00134  */
00135 int general_work(int noutput_items, gr_vector_int& ninput_items,
00136                 gr_vector_const_void_star& input_items,
00137                 gr_vector_void_star& output_items) override;
00138
00139 private:
00140     void forecast(int noutput_items, gr_vector_int& ninput_items_required) override;
00141
00142     friend pcps_assisted_acquisition_cc_sptr
00143     pcps_make_assisted_acquisition_cc(const Acq_Conf& conf);
00144
00145     explicit pcps_assisted_acquisition_cc(const Acq_Conf& conf);
00146
00147     void calculate_magnitudes(gr_complex* fft_begin, int32_t doppler_shift, int32_t doppler_offset);
00148
00149     int32_t compute_and_accumulate_grid(gr_vector_const_void_star& input_items);
00150     float estimate_input_power(gr_vector_const_void_star& input_items) const;
00151     float search_maximum();
00152     void get_assistance();
00153     void reset_grid();
00154     void redefine_grid();
00155
00156     std::string d_satellite_str;
00157     const Acq_Conf d_acq_params;
00158
00159     std::ofstream d_dump_file;
00160
00161     Gnss_Synchro* d_gnss_synchro;
00162
00163     uint64_t d_sample_counter;
00164
00165     float d_input_power;
00166     float d_test_statistics;
00167
00168     uint32_t d_channel;
00169     uint32_t d_code_phase;
00170     const uint32_t d_fft_size;
00171
00172     const int32_t d_gnuradio_forecast_samples;
00173     int32_t d_doppler_max;
00174     int32_t d_doppler_min;
00175     int32_t d_num_doppler_points;
00176     int32_t d_state;
00177     int32_t d_well_count;
00178
00179     bool d_active;
00180     bool d_disable_assist;
00181
00182     std::weak_ptr<ChannelFsm> d_channel_fsm;
00183     std::unique_ptr<gnss_fft_complex_fwd> d_fft_if;
00184     std::unique_ptr<gnss_fft_complex_rev> d_ifft;
00185
00186     std::vector<std::vector<std::complex<float>>> d_grid_doppler_wipeoffs;
00187     std::vector<std::vector<float>> d_grid_data;
00188     std::vector<gr_complex> d_fft_codes;
00189 };
00190
00191
00192
00193 /** \} */
00194 /** \} */
00195 #endif // GNSS_SDR_PCPS_ASSISTED_ACQUISITION_CC_H

```


13.77 pcps_cccwsr_acquisition_cc.h File Reference

This class implements a Parallel Code Phase Search acquisition with Coherent [Channel](#) Combining With Sign Recovery scheme.

```
#include "acq_conf.h"
#include "acquisition_impl_interface.h"
#include "channel_fsm.h"
#include "gnss_sdr_fft.h"
#include "gnss_synchro.h"
#include <gnuradio/block.h>
#include <gnuradio/gr_complex.h>
#include <fstream>
#include <memory>
#include <string>
#include <utility>
#include <vector>
```

Classes

- class [pcps_cccwsr_acquisition_cc](#)

This class implements a Parallel Code Phase Search Acquisition with Coherent [Channel](#) Combining With Sign Recovery scheme.

Typedefs

- using [pcps_cccwsr_acquisition_cc_sptr](#) = gnss_shared_ptr<[pcps_cccwsr_acquisition_cc](#)>

Functions

- pcps_cccwsr_acquisition_cc_sptr [pcps_cccwsr_make_acquisition_cc](#) (const [Acq_Conf](#) &conf)

13.77.1 Detailed Description

This class implements a Parallel Code Phase Search acquisition with Coherent [Channel](#) Combining With Sign Recovery scheme.

Author

Marc Molina, 2013. marc.molina.pena(at)gmail.com

D.Borio, C.O'Driscoll, G.Lachapelle, "Coherent, Noncoherent and Differentially Coherent Combining Techniques for Acquisition of New Composite GNSS Signals", IEEE Transactions On Aerospace and Electronic Systems vol. 45 no. 3, July 2009, section IV

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Definition in file [pcps_cccwsr_acquisition_cc.h](#).

13.78 pcps_cccwsr_acquisition_cc.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file pcps_cccwsr_acquisition_cc.h
00003  * \brief This class implements a Parallel Code Phase Search acquisition
00004  * with Coherent Channel Combining With Sign Recovery scheme.
00005  * \author Marc Molina, 2013. marc.molina.pena(at)gmail.com
00006  *
00007  * D.Borio, C.O'Driscoll, G.Lachapelle, "Coherent, Noncoherent and
00008  * Differentially Coherent Combining Techniques for Acquisition of
00009  * New Composite GNSS Signals", IEEE Transactions On Aerospace and
00010  * Electronic Systems vol. 45 no. 3, July 2009, section IV
00011  *
00012  * -----
00013  *
```

```

00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.
00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_PCPS_CCCWSR_ACQUISITION_CC_H
00024 #define GNSS_SDR_PCPS_CCCWSR_ACQUISITION_CC_H
00025
00026 #include "acq_conf.h"
00027 #include "acquisition_impl_interface.h"
00028 #include "channel_fsm.h"
00029 #include "gnss_sdr_fft.h"
00030 #include "gnss_synchro.h"
00031 #include <gnuradio/block.h>
00032 #include <gnuradio/gr_complex.h>
00033 #include <fstream>
00034 #include <memory>
00035 #include <string>
00036 #include <utility>
00037 #include <vector>
00038
00039 /** \addtogroup Acquisition
00040  * \{ */
00041 /** \addtogroup Acq_gnuradio_blocks
00042  * \{ */
00043
00044
00045 class pcps_cccwsr_acquisition_cc;
00046
00047 using pcps_cccwsr_acquisition_cc_sptr = gnss_shared_ptr<pcps_cccwsr_acquisition_cc>;
00048
00049 pcps_cccwsr_acquisition_cc_sptr pcps_cccwsr_make_acquisition_cc(const Acq_Conf& conf);
00050
00051 /*!
00052  * \brief This class implements a Parallel Code Phase Search Acquisition with
00053  * Coherent Channel Combining With Sign Recovery scheme.
00054  */
00055 class pcps_cccwsr_acquisition_cc : public acquisition_impl_interface
00056 {
00057 public:
00058     /*!
00059      * \brief Default destructor.
00060      */
00061     ~pcps_cccwsr_acquisition_cc();
00062
00063     /*!
00064      * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00065      * to exchange synchronization data between acquisition and tracking blocks.
00066      * \param p_gnss_synchro Satellite information shared by the processing blocks.
00067      */
00068     inline void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override
00069     {
00070         d_gnss_synchro = p_gnss_synchro;
00071     }
00072
00073     /*!
00074      * \brief Returns the maximum peak of grid search.
00075      */
00076     inline uint32_t mag() const override
00077     {
00078         return d_mag;
00079     }
00080
00081     /*!
00082      * \brief Sets local code for CCCWSR acquisition algorithm.
00083      * \param data_code - Pointer to the data PRN code.
00084      * \param pilot_code - Pointer to the pilot PRN code.
00085      */
00086     void set_local_code(std::complex<float>* code_data, std::complex<float>* code_pilot) override;
00087
00088     /*!
00089      * \brief Starts acquisition algorithm, turning from standby mode to
00090      * active mode
00091      * \param active - bool that activates/deactivates the block.
00092      */
00093     inline void set_active(bool active) override
00094     {
00095         if (!active)
00096         {
00097             d_state = 0;
00098         }
00099
00100         d_active = active;

```

```

00101     }
00102
00103     /*!
00104     * \brief Set acquisition channel unique ID
00105     * \param channel - receiver channel.
00106     */
00107     inline void set_channel(uint32_t channel) override
00108     {
00109         d_channel = channel;
00110     }
00111
00112     /*!
00113     * \brief Set channel fsm associated to this acquisition instance
00114     */
00115     inline void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) override
00116     {
00117         d_channel_fsm = std::move(channel_fsm);
00118     }
00119
00120     /*!
00121     * \brief Coherent Channel Combining With Sign Recovery Acquisition signal processing.
00122     */
00123     int general_work(int noutput_items, gr_vector_int& ninput_items,
00124                     gr_vector_const_void_star& input_items,
00125                     gr_vector_void_star& output_items) override;
00126
00127 private:
00128     friend pcps_cccwsr_acquisition_cc_sptr
00129     pcps_cccwsr_make_acquisition_cc(const Acq_Conf& conf);
00130
00131     explicit pcps_cccwsr_acquisition_cc(const Acq_Conf& conf);
00132
00133     void calculate_magnitudes(gr_complex* fft_begin, int32_t doppler_shift, int32_t doppler_offset);
00134
00135     std::ofstream d_dump_file;
00136     std::string d_satellite_str;
00137     const Acq_Conf d_acq_params;
00138
00139     Gnss_Synchro* d_gnss_synchro;
00140
00141     int64_t d_fs_in;
00142     uint64_t d_sample_counter;
00143
00144     float d_mag;
00145     float d_input_power;
00146     float d_test_statistics;
00147
00148     int32_t d_state;
00149     uint32_t d_doppler_resolution;
00150     uint32_t d_well_count;
00151     const uint32_t d_fft_size;
00152     uint32_t d_num_doppler_bins;
00153     uint32_t d_code_phase;
00154     uint32_t d_channel;
00155
00156     bool d_active;
00157
00158     std::weak_ptr<ChannelFsm> d_channel_fsm;
00159
00160     std::unique_ptr<gnss_fft_complex_fwd> d_fft_if;
00161     std::unique_ptr<gnss_fft_complex_rev> d_ifft;
00162
00163     std::vector<std::vector<gr_complex>> d_grid_doppler_wipeoffs;
00164     std::vector<gr_complex> d_fft_code_data;
00165     std::vector<gr_complex> d_fft_code_pilot;
00166     std::vector<gr_complex> d_data_correlation;
00167     std::vector<gr_complex> d_pilot_correlation;
00168     std::vector<gr_complex> d_correlation_plus;
00169     std::vector<gr_complex> d_correlation_minus;
00170     std::vector<float> d_magnitude;
00171 };
00172
00173
00174 /** \} */
00175 /** \} */
00176 #endif // GNSS_SDR_PCPS_CCCWSR_ACQUISITION_CC_H

```

13.79 pcps_opengl_acquisition_cc.h File Reference

This class implements a Parallel Code Phase Search Acquisition using OpenGL to offload some functions to the GPU.

```

#include "acq_conf.h"
#include "acquisition_impl_interface.h"

```

```
#include "channel_fsm.h"
#include "gnss_block_interface.h"
#include "gnss_sdr_fft.h"
#include "gnss_synchro.h"
#include "opencl/fft_internal.h"
#include <gnuradio/block.h>
#include <gnuradio/gr_complex.h>
#include "opencl/cl.hpp"
#include <stdint>
#include <fstream>
#include <memory>
#include <string>
#include <vector>
```

Classes

- class [pcps_opencl_acquisition_cc](#)
This class implements a Parallel Code Phase Search Acquisition.

Typedefs

- using [pcps_opencl_acquisition_cc_sptr](#) = gnss_shared_ptr<[pcps_opencl_acquisition_cc](#)>

Functions

- [pcps_opencl_acquisition_cc_sptr](#) **pcps_make_opencl_acquisition_cc** (const [Acq_Conf](#) &conf, uint32_t max_dwells)

13.79.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition using OpenCL to offload some functions to the GPU.

Acquisition strategy (Kay Borre book + CFAR threshold).

1. Compute the input signal power estimation
2. Doppler serial search loop
3. Perform the FFT-based circular convolution (parallel time search)
4. Record the maximum peak and the associated synchronization parameters
5. Compute the test statistics and compare to the threshold
6. Declare positive or negative acquisition using a message port

Kay Borre book: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, "A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach", Birkhauser, 2007. pp 81-84

Authors

- Javier Arribas, 2011. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)
- Luis Esteve, 2012. [luis\(at\)epsilon-formacion.com](mailto:luis(at)epsilon-formacion.com)
- Marc Molina, 2013. marc.molina.pena@gmail.com

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 Definition in file [pcps_opencl_acquisition_cc.h](#).

13.79.2 Macro Definition Documentation

13.79.2.1 CL_SILENCE_DEPRECATED

#define CL_SILENCE_DEPRECATED

Definition at line 40 of file [pcps_opengl_acquisition_cc.h](#).

13.80 pcps_opengl_acquisition_cc.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file pcps_opengl_acquisition_cc.h
00003  * \brief This class implements a Parallel Code Phase Search Acquisition
00004  * using OpenCL to offload some functions to the GPU.
00005  *
00006  * Acquisition strategy (Kay Borre book + CFAR threshold).
00007  * <ol>
00008  * <li> Compute the input signal power estimation
00009  * <li> Doppler serial search loop
00010  * <li> Perform the FFT-based circular convolution (parallel time search)
00011  * <li> Record the maximum peak and the associated synchronization parameters
00012  * <li> Compute the test statistics and compare to the threshold
00013  * <li> Declare positive or negative acquisition using a message port
00014  * </ol>
00015  *
00016  * Kay Borre book: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00017  * "A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00018  * Approach", Birkhauser, 2007. pp 81-84
00019  *
00020  * \authors <ul>
00021  * <li> Javier Arribas, 2011. jarribas(at)cttc.es
00022  * <li> Luis Esteve, 2012. luis(at)epsilon-formacion.com
00023  * <li> Marc Molina, 2013. marc.molina.pena@gmail.com
00024  * </ul>
00025  *
00026  * -----
00027  *
00028  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00029  * This file is part of GNSS-SDR.
00030  *
00031  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00032  * SPDX-License-Identifier: GPL-3.0-or-later
00033  *
00034  * -----
00035  */
00036
00037 #ifndef GNSS_SDR_PCPS_OPENCL_ACQUISITION_CC_H
00038 #define GNSS_SDR_PCPS_OPENCL_ACQUISITION_CC_H
00039
00040 #define CL_SILENCE_DEPRECATED
00041 #include "acq_conf.h"
00042 #include "acquisition_impl_interface.h"
00043 #include "channel_fsm.h"
00044 #include "gnss_block_interface.h"
00045 #include "gnss_sdr_fft.h"
00046 #include "gnss_synchro.h"
00047 #include "opengl/fft_internal.h"
00048 #include <gnuradio/block.h>
00049 #include <gnuradio/gr_complex.h>
00050 #include "opengl/cl.hpp"
00051 #include <cstdint>
00052 #include <fstream>
00053 #include <memory> // for weak_ptr
00054 #include <string>
00055 #include <vector>
00056
00057 /** \addtogroup Acquisition
00058  * \{ */
00059 /** \addtogroup Acq_gnuradio_blocks
00060  * \{ */
00061
00062
00063 class pcps_opengl_acquisition_cc;
00064
00065 using pcps_opengl_acquisition_cc_sptr = gnss_shared_ptr<pcps_opengl_acquisition_cc>;
00066
00067 pcps_opengl_acquisition_cc_sptr pcps_make_opengl_acquisition_cc(const Acq_Conf& conf, uint32_t
max_dwells);
00068
00069 /*!
00070 * \brief This class implements a Parallel Code Phase Search Acquisition.
00071 */

```

```

00072  * Check \ref Navitec2012 "An Open Source Galileo E1 Software Receiver",
00073  * Algorithm 1, for a pseudocode description of this implementation.
00074  */
00075  class pcps_openc1_acquisition_cc : public acquisition_impl_interface
00076  {
00077  public:
00078      /*!
00079       * \brief Default destructor.
00080       */
00081      ~pcps_openc1_acquisition_cc();
00082
00083      /*!
00084       * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00085       * to exchange synchronization data between acquisition and tracking blocks.
00086       * \param p_gnss_synchro Satellite information shared by the processing blocks.
00087       */
00088      inline void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override
00089      {
00090          d_gnss_synchro = p_gnss_synchro;
00091      }
00092
00093      /*!
00094       * \brief Returns the maximum peak of grid search.
00095       */
00096      inline uint32_t mag() const override
00097      {
00098          return d_mag;
00099      }
00100
00101      /*!
00102       * \brief Sets local code for PCPS acquisition algorithm.
00103       * \param code - Pointer to the PRN code.
00104       */
00105      void set_local_code(std::complex<float>* code) override;
00106
00107      /*!
00108       * \brief Starts acquisition algorithm, turning from standby mode to
00109       * active mode
00110       * \param active - bool that activates/deactivates the block.
00111       */
00112      inline void set_active(bool active) override
00113      {
00114          if (!active)
00115          {
00116              d_state = 0;
00117          }
00118
00119          d_active = active;
00120      }
00121
00122      /*!
00123       * \brief Set acquisition channel unique ID
00124       * \param channel - receiver channel.
00125       */
00126      inline void set_channel(uint32_t channel) override
00127      {
00128          d_channel = channel;
00129      }
00130
00131      /*!
00132       * \brief Set channel fsm associated to this acquisition instance
00133       */
00134      inline void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) override
00135      {
00136          d_channel_fsm = channel_fsm;
00137      }
00138
00139      inline bool openc1_ready() const
00140      {
00141          bool ready = false;
00142          if (d_openc1 == 0)
00143          {
00144              ready = true;
00145          }
00146          return ready;
00147      }
00148
00149      void acquisition_core_volk();
00150
00151      void acquisition_core_openc1();
00152
00153      /*!
00154       * \brief Parallel Code Phase Search Acquisition signal processing.
00155       */
00156      int general_work(int noutput_items, gr_vector_int& ninput_items,
00157                      gr_vector_const_void_star& input_items,
00158                      gr_vector_void_star& output_items) override;

```

```

00159
00160 private:
00161     friend pcps_openccl_acquisition_cc_sptr
00162     pcps_make_openccl_acquisition_cc(const Acq_Conf& conf, uint32_t max_dwells);
00163
00164     explicit pcps_openccl_acquisition_cc(const Acq_Conf& conf, uint32_t max_dwells);
00165
00166     void calculate_magnitudes(gr_complex* fft_begin, int doppler_shift, int doppler_offset);
00167
00168     int init_openccl_environment(const std::string& kernel_filename);
00169
00170     cl::Platform d_cl_platform;
00171     cl::Device d_cl_device;
00172     cl::Context d_cl_context;
00173     cl::Program d_cl_program;
00174     cl::Buffer* d_cl_buffer_in;
00175     cl::Buffer* d_cl_buffer_fft_codes;
00176     cl::Buffer* d_cl_buffer_1;
00177     cl::Buffer* d_cl_buffer_2;
00178     cl::Buffer* d_cl_buffer_magnitude;
00179     cl::Buffer** d_cl_buffer_grid_doppler_wipeoffs;
00180     cl::CommandQueue* d_cl_queue;
00181     clFFT_Plan d_cl_fft_plan;
00182     cl_int d_cl_fft_batch_size;
00183
00184     std::string d_satellite_str;
00185     const Acq_Conf d_acq_params;
00186
00187     std::ofstream d_dump_file;
00188
00189     Gnss_Synchro* d_gnss_synchro;
00190
00191     uint64_t d_sample_counter;
00192
00193     int* d_max_doppler_indexes;
00194
00195     float d_mag;
00196     float d_input_power;
00197     float d_test_statistics;
00198
00199     int d_state;
00200     int d_openccl;
00201
00202     uint32_t d_max_dwells;
00203     uint32_t d_well_count;
00204     const uint32_t d_fft_size;
00205     uint32_t d_fft_size_pow2;
00206     uint32_t d_num_doppler_bins;
00207     uint32_t d_code_phase;
00208     uint32_t d_channel;
00209     uint32_t d_in_dwell_count;
00210
00211     bool d_active;
00212     bool d_core_working;
00213
00214     std::weak_ptr<ChannelFsm> d_channel_fsm;
00215
00216     std::unique_ptr<gnss_fft_complex_fwd> d_fft_if;
00217     std::unique_ptr<gnss_fft_complex_rev> d_ifft;
00218
00219     std::vector<std::vector<gr_complex>> d_grid_doppler_wipeoffs;
00220     std::vector<std::vector<gr_complex>> d_in_buffer;
00221     std::vector<gr_complex> d_fft_codes;
00222     std::vector<gr_complex> d_zero_vector;
00223     std::vector<uint64_t> d_sample_counter_buffer;
00224     std::vector<float> d_magnitude;
00225 };
00226
00227
00228 /** \} */
00229 /** \} */
00230 #endif // GNSS_SDR_PCPS_OPENCL_ACQUISITION_CC_H

```

13.81 pcps_quicksync_acquisition_cc.h File Reference

This class implements a Parallel Code Phase Search Acquisition with the QuickSync Algorithm.

```

#include "acq_conf.h"
#include "acquisition_impl_interface.h"
#include "channel_fsm.h"
#include "gnss_sdr_fft.h"
#include "gnss_synchro.h"

```

```
#include <gnuradio/block.h>
#include <gnuradio/gr_complex.h>
#include <cassert>
#include <fstream>
#include <memory>
#include <string>
#include <utility>
#include <vector>
```

Classes

- class [pcps_quicksync_acquisition_cc](#)

This class implements a Parallel Code Phase Search Acquisition with the implementation of the Sparse QuickSync Algorithm.

Typedefs

- using [pcps_quicksync_acquisition_cc_sptr](#) = gnss_shared_ptr<[pcps_quicksync_acquisition_cc](#)>

Functions

- [pcps_quicksync_acquisition_cc_sptr](#) **pcps_quicksync_make_acquisition_cc** (const [Acq_Conf](#) &conf, uint32_t folding_factor, uint32_t max_dwells)

13.81.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition with the QuickSync Algorithm. Acquisition strategy (Kay Borre book CFAR + threshold).

1. Compute the input signal power estimation
2. Doppler serial search loop
3. Perform folding of the incoming signal and local generated code
4. Perform the FFT-based circular convolution (parallel time search)
5. Record the maximum peak and the associated synchronization parameters
6. Compute the test statistics and compare to the threshold
7. Declare positive or negative acquisition using a message port
8. Obtain the adequate acquisition parameters by correlating the incoming signal shifted by the possible folded delays

Kay Borre book: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, "A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach", Birkha user, 2007. pp 81-84

Date

Jun2 2014

Author

Damian Miralles Sanchez, dmiralles2009@gmail.com

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 Definition in file [pcps_quicksync_acquisition_cc.h](#).

13.82 pcps_quicksync_acquisition_cc.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file pcps_quicksync_acquisition_cc.h
00003  * \brief This class implements a Parallel Code Phase Search Acquisition with the
00004  * QuickSync Algorithm
00005  *
00006  * Acquisition strategy (Kay Borre book CFAR + threshold).
00007  * <ol>
00008  * <li> Compute the input signal power estimation
00009  * <li> Doppler serial search loop
00010  * <li> Perform folding of the incoming signal and local generated code
00011  * <li> Perform the FFT-based circular convolution (parallel time search)
00012  * <li> Record the maximum peak and the associated synchronization parameters
00013  * <li> Compute the test statistics and compare to the threshold
00014  * <li> Declare positive or negative acquisition using a message port
00015  * <li> Obtain the adequate acquisition parameters by correlating the incoming
00016  * signal shifted by the possible folded delays
00017  * </ol>
00018  *
00019  * Kay Borre book: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00020  * "A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00021  * Approach", Birkha user, 2007. pp 81-84
00022  *
00023  * \date Jun2 2014
00024  * \author Damian Miralles Sanchez, dmiralles2009@gmail.com
00025  *
00026  * -----
00027  *
00028  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00029  * This file is part of GNSS-SDR.
00030  *
00031  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00032  * SPDX-License-Identifier: GPL-3.0-or-later
00033  *
00034  * -----
00035  */
00036
00037 #ifndef GNSS_SDR_PCPS_QUICKSYNC_ACQUISITION_CC_H
00038 #define GNSS_SDR_PCPS_QUICKSYNC_ACQUISITION_CC_H
00039
00040 #include "acq_conf.h"
00041 #include "acquisition_impl_interface.h"
00042 #include "channel_fsm.h"
00043 #include "gnss_sdr_fft.h"
00044 #include "gnss_synchro.h"
00045 #include <gnuradio/block.h>
00046 #include <gnuradio/gr_complex.h>
00047 #include <cassert>
00048 #include <fstream>
00049 #include <memory> // for weak_ptr
00050 #include <string>
00051 #include <utility>
00052 #include <vector>
00053
00054 /** \addtogroup Acquisition
00055  * \{ */
00056 /** \addtogroup Acq_gnuradio_blocks
00057  * \{ */
00058
00059
00060 class pcps_quicksync_acquisition_cc;
00061
00062 using pcps_quicksync_acquisition_cc_sptr = gnss_shared_ptr<pcps_quicksync_acquisition_cc>;
00063
00064 pcps_quicksync_acquisition_cc_sptr pcps_quicksync_make_acquisition_cc(const Acq_Conf& conf, uint32_t
folding_factor, uint32_t max_dwells);
00065
00066 /*!
00067 * \brief This class implements a Parallel Code Phase Search Acquisition with
00068 * the implementation of the Sparse QuickSync Algorithm.
00069 *
00070 * Check \ref Navitec2012 "Faster GPS via the Sparse Fourier Transform",
00071 * for details of its implementation and functionality.
00072 */
00073 class pcps_quicksync_acquisition_cc : public acquisition_impl_interface
00074 {
00075 public:
00076     /*!
00077     * \brief Default destructor.
00078     */
00079     ~pcps_quicksync_acquisition_cc();
00080
00081     /*!
00082     * \brief Set acquisition/tracking common Gnss_Synchro object pointer

```

```

00083     * to exchange synchronization data between acquisition and tracking blocks.
00084     * \param p_gnss_synchro Satellite information shared by the processing blocks.
00085     */
00086 inline void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override
00087 {
00088     d_gnss_synchro = p_gnss_synchro;
00089 }
00090
00091 /*!
00092  * \brief Returns the maximum peak of grid search.
00093  */
00094 inline uint32_t mag() const override
00095 {
00096     return d_mag;
00097 }
00098
00099 /*!
00100  * \brief Sets local code for PCPS acquisition algorithm.
00101  * \param code - Pointer to the PRN code.
00102  */
00103 void set_local_code(std::complex<float>* code) override;
00104
00105 /*!
00106  * \brief Starts acquisition algorithm, turning from standby mode to
00107  * active mode
00108  * \param active - bool that activates/deactivates the block.
00109  */
00110 inline void set_active(bool active) override
00111 {
00112     if (!active)
00113     {
00114         d_state = 0;
00115     }
00116
00117     d_active = active;
00118 }
00119
00120 /*!
00121  * \brief Set acquisition channel unique ID
00122  * \param channel - receiver channel.
00123  */
00124 inline void set_channel(uint32_t channel) override
00125 {
00126     d_channel = channel;
00127 }
00128
00129 /*!
00130  * \brief Set channel fsm associated to this acquisition instance
00131  */
00132 inline void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) override
00133 {
00134     d_channel_fsm = std::move(channel_fsm);
00135 }
00136
00137 /*!
00138  * \brief Parallel Code Phase Search Acquisition signal processing.
00139  */
00140 int general_work(int noutput_items, gr_vector_int& ninput_items,
00141     gr_vector_const_void_star& input_items,
00142     gr_vector_void_star& output_items) override;
00143
00144 private:
00145     friend pcps_quicksync_acquisition_cc_sptr
00146     pcps_quicksync_make_acquisition_cc(const Acq_Conf& conf, uint32_t folding_factor, uint32_t
00147     max_dwells);
00148     explicit pcps_quicksync_acquisition_cc(const Acq_Conf& conf, uint32_t folding_factor, uint32_t
00149     max_dwells);
00150
00151     void calculate_magnitudes(gr_complex* fft_begin, int32_t doppler_shift, int32_t doppler_offset);
00152
00153     std::string d_satellite_str;
00154     const Acq_Conf d_acq_params;
00155
00156     std::ofstream d_dump_file;
00157
00158     Gnss_Synchro* d_gnss_synchro;
00159
00160     uint64_t d_sample_counter;
00161
00162     float d_noise_floor_power;
00163     float d_mag;
00164     float d_input_power;
00165     float d_test_statistics;
00166     const int32_t d_vector_length;
00167     const int32_t d_samples_per_code;
00168     int32_t d_state;

```

```

00168     uint32_t d_channel;
00169     const uint32_t d_folding_factor; // also referred in the paper as 'p'
00170     const uint32_t d_max_dwells;
00171     uint32_t d_well_count;
00172     const uint32_t d_fft_size;
00173     uint32_t d_num_doppler_bins;
00174     uint32_t d_code_phase;
00175
00176     bool d_active;
00177
00178     std::weak_ptr<ChannelFsm> d_channel_fsm;
00179
00180     std::unique_ptr<gnss_fft_complex_fwd> d_fft_if;
00181     std::unique_ptr<gnss_fft_complex_rev> d_ifft;
00182
00183     std::vector<std::vector<gr_complex>> d_grid_doppler_wipeoffs;
00184     std::vector<gr_complex> d_code;
00185     std::vector<gr_complex> d_fft_codes;
00186     std::vector<gr_complex> d_signal_folded;
00187     std::vector<gr_complex> d_code_folded;
00188     std::vector<float> d_magnitude;
00189     std::vector<float> d_corr_output_f;
00190     std::vector<float> d_magnitude_folded;
00191     std::vector<uint32_t> d_possible_delay;
00192 };
00193
00194
00195 /** \} */
00196 /** \} */
00197 #endif // GNSS_SDR_PCPS_QUICKSYNC_ACQUISITION_CC_H

```

13.83 pcps_tong_acquisition_cc.h File Reference

This class implements a Parallel Code Phase Search Acquisition with Tong algorithm.

```

#include "acq_conf.h"
#include "acquisition_impl_interface.h"
#include "channel_fsm.h"
#include "gnss_sdr_fft.h"
#include "gnss_synchro.h"
#include <gnuradio/block.h>
#include <gnuradio/gr_complex.h>
#include <fstream>
#include <memory>
#include <string>
#include <utility>
#include <vector>

```

Classes

- class [pcps_tong_acquisition_cc](#)

This class implements a Parallel Code Phase Search Acquisition with Tong algorithm.

Typedefs

- using [pcps_tong_acquisition_cc_sptr](#) = [gnss_shared_ptr](#)<[pcps_tong_acquisition_cc](#)>

Functions

- [pcps_tong_acquisition_cc_sptr pcps_tong_make_acquisition_cc](#) (const [Acq_Conf](#) &conf, uint32_t tong←_init_val, uint32_t tong_max_val, uint32_t tong_max_dwells)

13.83.1 Detailed Description

This class implements a Parallel Code Phase Search Acquisition with Tong algorithm.

Author

Marc Molina, 2013. marc.molina.pena(at)gmail.com

Acquisition strategy (Kaplan book + CFAR threshold).

1. Compute the input signal power estimation.
2. Doppler serial search loop.
3. Perform the FFT-based circular convolution (parallel time search).
4. Compute the tests statistics for all the cells.
5. Accumulate the grid of tests statistics with the previous grids.
6. Record the maximum peak and the associated synchronization parameters.
7. Compare the maximum averaged test statistics with a threshold.
8. If the test statistics exceeds the threshold, increment the Tong counter.
9. Otherwise, decrement the Tong counter.
10. If the Tong counter is equal to a given maximum value, declare positive
11. acquisition. If the Tong counter is equa to zero, declare negative
12. acquisition. Otherwise, process the next block.

Kaplan book: D.Kaplan, J.Hegarty, "Understanding GPS. Principles and Applications", Artech House, 2006, pp 223-227

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Definition in file [pcps_tong_acquisition_cc.h](#).

13.84 pcps_tong_acquisition_cc.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file pcps_tong_acquisition_cc.h
00003  * \brief This class implements a Parallel Code Phase Search Acquisition with
00004  * Tong algorithm.
00005  * \author Marc Molina, 2013. marc.molina.pena(at)gmail.com
00006  *
00007  * Acquisition strategy (Kaplan book + CFAR threshold).
00008  * <ol>
00009  * <li> Compute the input signal power estimation.
00010  * <li> Doppler serial search loop.
00011  * <li> Perform the FFT-based circular convolution (parallel time search).
00012  * <li> Compute the tests statistics for all the cells.
00013  * <li> Accumulate the grid of tests statistics with the previous grids.
00014  * <li> Record the maximum peak and the associated synchronization parameters.
00015  * <li> Compare the maximum averaged test statistics with a threshold.
00016  * <li> If the test statistics exceeds the threshold, increment the Tong counter.
00017  * <li> Otherwise, decrement the Tong counter.
00018  * <li> If the Tong counter is equal to a given maximum value, declare positive
00019  * <li> acquisition. If the Tong counter is equa to zero, declare negative
00020  * <li> acquisition. Otherwise, process the next block.
00021  * </ol>
00022  *
00023  * Kaplan book: D.Kaplan, J.Hegarty, "Understanding GPS. Principles
00024  * and Applications", Artech House, 2006, pp 223-227
00025  *
00026  * -----
00027  *
00028  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00029  * This file is part of GNSS-SDR.
00030  *
00031  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00032  * SPDX-License-Identifier: GPL-3.0-or-later
00033  *
00034  * -----
00035  */
00036
00037 #ifndef GNSS_SDR_PCPS_TONG_ACQUISITION_CC_H
```

```

00038 #define GNSS_SDR_PCPS_TONG_ACQUISITION_CC_H
00039
00040 #include "acq_conf.h"
00041 #include "acquisition_impl_interface.h"
00042 #include "channel_fsm.h"
00043 #include "gnss_sdr_fft.h"
00044 #include "gnss_synchro.h"
00045 #include <gnuradio/block.h>
00046 #include <gnuradio/gr_complex.h>
00047 #include <fstream>
00048 #include <memory> // for weak_ptr
00049 #include <string>
00050 #include <utility>
00051 #include <vector>
00052
00053 /** \addtogroup Acquisition
00054  * \{ */
00055 /** \addtogroup Acq_gnuradio_blocks
00056  * \{ */
00057
00058
00059 class pcps_tong_acquisition_cc;
00060
00061 using pcps_tong_acquisition_cc_sptr = gnss_shared_ptr<pcps_tong_acquisition_cc>;
00062
00063 pcps_tong_acquisition_cc_sptr pcps_tong_make_acquisition_cc(
00064     const Acq_Conf& conf,
00065     uint32_t tong_init_val,
00066     uint32_t tong_max_val,
00067     uint32_t tong_max_dwells);
00068
00069 /*!
00070  * \brief This class implements a Parallel Code Phase Search Acquisition with
00071  * Tong algorithm.
00072  */
00073 class pcps_tong_acquisition_cc : public acquisition_impl_interface
00074 {
00075 public:
00076     /*!
00077      * \brief Default destructor.
00078      */
00079     ~pcps_tong_acquisition_cc();
00080
00081     /*!
00082      * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00083      * to exchange synchronization data between acquisition and tracking blocks.
00084      * \param p_gnss_synchro Satellite information shared by the processing blocks.
00085      */
00086     inline void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override
00087     {
00088         d_gnss_synchro = p_gnss_synchro;
00089     }
00090
00091     /*!
00092      * \brief Returns the maximum peak of grid search.
00093      */
00094     inline uint32_t mag() const override
00095     {
00096         return d_mag;
00097     }
00098
00099     /*!
00100      * \brief Sets local code for TONG acquisition algorithm.
00101      * \param code - Pointer to the PRN code.
00102      */
00103     void set_local_code(std::complex<float>* code) override;
00104
00105     /*!
00106      * \brief Starts acquisition algorithm, turning from standby mode to
00107      * active mode
00108      * \param active - bool that activates/deactivates the block.
00109      */
00110     inline void set_active(bool active) override
00111     {
00112         if (!active)
00113         {
00114             d_state = 0;
00115         }
00116
00117         d_active = active;
00118     }
00119
00120     /*!
00121      * \brief Set acquisition channel unique ID
00122      * \param channel - receiver channel.
00123      */
00124     inline void set_channel(uint32_t channel) override

```

```

00125     {
00126         d_channel = channel;
00127     }
00128
00129     /*!
00130     * \brief Set channel fsm associated to this acquisition instance
00131     */
00132     inline void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) override
00133     {
00134         d_channel_fsm = std::move(channel_fsm);
00135     }
00136
00137     /*!
00138     * \brief Parallel Code Phase Search Acquisition signal processing.
00139     */
00140     int general_work(int noutput_items, gr_vector_int& ninput_items,
00141         gr_vector_const_void_star& input_items,
00142         gr_vector_void_star& output_items) override;
00143
00144 private:
00145     friend pcps_tong_acquisition_cc_sptr
00146     pcps_tong_make_acquisition_cc(
00147         const Acq_Conf& conf,
00148         uint32_t tong_init_val,
00149         uint32_t tong_max_val,
00150         uint32_t tong_max_dwells);
00151
00152     pcps_tong_acquisition_cc(
00153         const Acq_Conf& conf,
00154         uint32_t tong_init_val,
00155         uint32_t tong_max_val,
00156         uint32_t tong_max_dwells);
00157
00158     void calculate_magnitudes(gr_complex* fft_begin, int32_t doppler_shift, int32_t doppler_offset);
00159
00160     std::string d_satellite_str;
00161     const Acq_Conf d_acq_params;
00162
00163     std::ofstream d_dump_file;
00164
00165     Gnss_Synchro* d_gnss_synchro;
00166
00167     uint64_t d_sample_counter;
00168
00169     float d_mag;
00170     float d_input_power;
00171     float d_test_statistics;
00172     int32_t d_state;
00173     uint32_t d_channel;
00174     uint32_t d_dwell_count;
00175     const uint32_t d_tong_init_val;
00176     const uint32_t d_tong_max_val;
00177     const uint32_t d_tong_max_dwells;
00178     uint32_t d_tong_count;
00179     const uint32_t d_fft_size;
00180     uint32_t d_num_doppler_bins;
00181     uint32_t d_code_phase;
00182
00183     bool d_active;
00184
00185     std::weak_ptr<ChannelFsm> d_channel_fsm;
00186     std::unique_ptr<gnss_fft_complex_fwd> d_fft_if;
00187     std::unique_ptr<gnss_fft_complex_rev> d_ifft;
00188
00189     std::vector<std::vector<gr_complex>> d_grid_doppler_wipeoffs;
00190     std::vector<std::vector<float>> d_grid_data;
00191     std::vector<gr_complex> d_fft_codes;
00192     std::vector<float> d_magnitude;
00193 };
00194
00195
00196 /** \} */
00197 /** \} */
00198 #endif // GNSS_SDR_PCPS_TONG_ACQUISITION_CC_H

```

13.85 acq_conf.h File Reference

Class that contains all the configuration parameters for generic acquisition block based on the PCPS algorithm.

```

#include "configuration_interface.h"
#include <gnuradio/gr_complex.h>
#include <stdint>
#include <string>

```

Classes

- class [Acq_Conf](#)

13.85.1 Detailed Description

Class that contains all the configuration parameters for generic acquisition block based on the PCPS algorithm.

Author

Carles Fernandez, 2018. cfernandez(at)cttc.es

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 Definition in file [acq_conf.h](#).

13.86 acq_conf.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file acq_conf.h
00003  * \brief Class that contains all the configuration parameters for generic
00004  * acquisition block based on the PCPS algorithm.
00005  * \author Carles Fernandez, 2018. cfernandez(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_ACQ_CONF_H
00019 #define GNSS_SDR_ACQ_CONF_H
00020
00021 #include "configuration_interface.h"
00022 #include <gnuradio/gr_complex.h>
00023 #include <stdint>
00024 #include <string>
00025
00026 /** \addtogroup Acquisition
00027  * \{ */
00028 /** \addtogroup acquisition_libs acquisition_libs
00029  * Library with utilities for GNSS signal acquisition
00030  * \{ */
00031
00032
00033 class Acq_Conf
00034 {
00035 public:
00036     Acq_Conf() = default;
00037
00038     void SetFromConfiguration(const ConfigurationInterface *configuration, const std::string &role,
00039                             double chip_rate, double opt_freq);
00039
00040     /** PCPS Acquisition configuration */
00041     std::string item_type{"gr_complex"};
00042     std::string dump_filename;
00043
00044     int64_t fs_in{4000000LL};
00045     int64_t resampled_fs{0LL};
00046
00047     size_t it_size{sizeof(gr_complex)};
00048
00049     float samples_per_ms{0.0};
00050     float doppler_step2{125.0};
00051     float threshold{0.0};
00052     float pfa{0.0};
00053     float pfa2{0.0};
00054     float samples_per_code{0.0};
00055     float resampler_ratio{1.0};
00056

```

```

00057     uint32_t sampled_ms{1U};
00058     uint32_t ms_per_code{1U};
00059     uint32_t samples_per_chip{2U};
00060     uint32_t chips_per_second{1023000U};
00061     uint32_t max_dwells{1U};
00062     uint32_t num_doppler_bins_step2{4U};
00063     uint32_t resampler_latency_samples{0U};
00064     uint32_t dump_channel{0U};
00065     int32_t doppler_max{5000};
00066     int32_t doppler_min{-5000};
00067     int32_t doppler_step{500};
00068
00069     bool bit_transition_flag{false};
00070     bool use_CFAR_algorithm_flag{true};
00071     bool dump{false};
00072     bool blocking{true};
00073     bool blocking_on_standby{false}; // enable it only for unit testing to avoid sample consume on
idle status
00074     bool make_2_steps{false};
00075     bool use_automatic_resampler{false};
00076     bool enable_monitor_output{false};
00077
00078     // Not part of the configuration interface
00079     uint32_t num_codes{0};
00080     uint32_t code_length{0};
00081     uint32_t vector_length{0};
00082
00083 private:
00084     void SetDerivedParams();
00085
00086     void ConfigureAutomaticResampler(double opt_freq);
00087 };
00088
00089
00090 /** \} */
00091 /** \} */
00092 #endif // GNSS_SDR_ACQ_CONF_H

```

13.87 acq_conf_fpga.h File Reference

Class that contains all the configuration parameters for generic acquisition block based on the PCPS algorithm running in the FPGA.

```

#include "configuration_interface.h"
#include <gnuradio/gr_complex.h>
#include <stdint>
#include <string>
#include <utility>
#include <vector>

```

Classes

- class [Acq_Conf_Fpga](#)

13.87.1 Detailed Description

Class that contains all the configuration parameters for generic acquisition block based on the PCPS algorithm running in the FPGA.

Author

Marc Majoral, 2022. mmajoral(at)cttc.es

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 Definition in file [acq_conf_fpga.h](#).

13.88 acq_conf_fpga.h

[Go to the documentation of this file.](#)

```
00001 /*!
```



```

00002  * \file acq_conf_fpga.h
00003  * \brief Class that contains all the configuration parameters for generic
00004  * acquisition block based on the PCPS algorithm running in the FPGA.
00005  * \author Marc Majoral, 2022. mmajoral(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_ACQ_CONF_FPGA_H
00019 #define GNSS_SDR_ACQ_CONF_FPGA_H
00020
00021 #include "configuration_interface.h"
00022 #include <gnuradio/gr_complex.h>
00023 #include <cstdint>
00024 #include <string>
00025 #include <utility> // for std::move, std::pair
00026 #include <vector> // for std::vector
00027
00028 /** \addtogroup Acquisition
00029  * \{ */
00030 /** \addtogroup acquisition_libs acquisition_libs
00031  * Library with utilities for GNSS signal acquisition
00032  * \{ */
00033
00034
00035 class Acq_Conf_Fpga
00036 {
00037 public:
00038     Acq_Conf_Fpga() = default;
00039
00040     void SetFromConfiguration(const ConfigurationInterface *configuration, const std::string &role,
00041                             uint32_t blk_exp, double code_chips_per_sec, double num_chips_per_code);
00042
00043     bool ConfigureAutomaticResampler(std::vector<std::pair<uint32_t, uint32_t>
00044                                     downsampling_filter_specs, uint32_t max_FFT_size, double opt_freq);
00045
00046     bool Is_acq_config_valid(uint32_t max_FFT_size) const;
00047
00048     /* PCPS Acquisition configuration */
00049     std::string device_name = "uio0";
00050     double code_rate_cps;
00051     double code_length_chips;
00052     float doppler_step{250.0};
00053     float doppler_step2{125.0};
00054     float threshold{0.0};
00055
00056     int64_t fs_in{4000000LL};
00057     int64_t resampled_fs{4000000LL};
00058
00059     uint32_t *all_fft_codes = nullptr; // pointer to memory that contains all the code ffts
00060     uint32_t num_doppler_bins_step2{4U};
00061     uint32_t downsampling_filter_num{0U};
00062     uint32_t downsampling_factor{1U};
00063     uint32_t downsampling_filter_delay{0U};
00064     uint32_t total_block_exp{13U};
00065     uint32_t excludelimit{5U};
00066     uint32_t max_num_acqs{2U};
00067     uint32_t fft_size{1U};
00068     uint32_t code_length{16000U};
00069     int32_t doppler_max{5000};
00070
00071     bool make_2_steps{false};
00072     bool enable_zero_padding{false};
00073     bool repeat_satellite{false};
00074
00075 private:
00076     const std::string acquisition_device_name = "acquisition_S00_AXI"; // UIO device name
00077 };
00078
00079 /** \} */
00080 /** \} */
00081 #endif // GNSS_SDR_ACQ_CONF_FPGA_H

```

13.89 fpga_acquisition.h File Reference

Highly optimized FPGA vector correlator class.

```
#include <cstdint>
#include <string>
#include <utility>
#include <vector>
```

Classes

- class [Fpga_Acquisition](#)
Class that implements carrier wipe-off and correlators.

13.89.1 Detailed Description

Highly optimized FPGA vector correlator class.

Authors

- Marc Majoral, 2019. mmajoral(at)cttc.cat

Class that controls and executes a highly optimized acquisition HW accelerator in the FPGA
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Definition in file [fpga_acquisition.h](#).

13.90 fpga_acquisition.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file fpga_acquisition.h
00003  * \brief Highly optimized FPGA vector correlator class
00004  * \authors <ul>
00005  *         <li> Marc Majoral, 2019. mmajoral(at)cttc.cat
00006  *         </li>
00007  *         </ul>
00008  * Class that controls and executes a highly optimized acquisition HW
00009  * accelerator in the FPGA
00010  *
00011  * -----
00012  *
00013  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014  * This file is part of GNSS-SDR.
00015  *
00016  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022 #ifndef GNSS_SDR_FPGA_ACQUISITION_H
00023 #define GNSS_SDR_FPGA_ACQUISITION_H
00024
00025 #include <cstdint>
00026 #include <string>
00027 #include <utility> // for std::move, std::pair
00028 #include <vector>  // for std::vector
00029
00030 /** \addtogroup Acquisition
00031  * \{ */
00032 /** \addtogroup acquisition_libs
00033  * \{ */
00034
00035
00036 /*!
00037  * \brief Class that implements carrier wipe-off and correlators.
00038  */
00039 class Fpga_Acquisition
00040 {
00041 public:
00042     /*!
00043     * \brief Constructor
00044     */
```

```

00045     Fpga_Acquisition(
00046         std::string device_name,
00047         uint32_t select_queue,
00048         std::vector<std::pair<uint32_t, uint32_t>> &downsampling_filter_specs,
00049         uint32_t &max_FFT_size);
00050
00051     /*!
00052     * \brief Destructor
00053     */
00054     ~Fpga_Acquisition() = default;
00055
00056     /*!
00057     * \brief Initialize acquisition parameters
00058     */
00059     // void init(uint32_t samples_per_code, uint32_t code_length, int64_t resampled_fs, uint32_t
*all_fft_codes);
00060     void init(uint32_t nsamples, uint32_t d_fft_size,
00061         int64_t resampled_fs, uint32_t downsampling_filter_num, uint32_t excludelimit, uint32_t
*all_fft_codes);
00062
00063     /*!
00064     * \brief Select the code with the chosen PRN
00065     */
00066     bool set_local_code(uint32_t PRN);
00067
00068     /*!
00069     * \brief Configure the doppler sweep parameters in the FPGA
00070     */
00071     void set_doppler_sweep(uint32_t num_sweeps, uint32_t doppler_step, int32_t doppler_min);
00072
00073     /*!
00074     * \brief Run the acquisition process in the FPGA
00075     */
00076     void run_acquisition();
00077
00078     /*!
00079     * \brief Read the results of the acquisition process
00080     */
00081     void read_acquisition_results(
00082         uint32_t *max_index,
00083         float *firstpeak,
00084         float *secondpeak,
00085         uint64_t *initial_sample,
00086         float *power_sum,
00087         uint32_t *doppler_index,
00088         uint32_t *total_blk_exp);
00089
00090     /*!
00091     * \brief Reset the FPGA PL.
00092     */
00093     void reset_acquisition();
00094
00095     /*!
00096     * \brief stop the acquisition and the FPGA modules.
00097     */
00098     void stop_acquisition();
00099
00100     /*!
00101     * \brief Set the block exponent of the FFT in the FPGA.
00102     */
00103     void set_block_exp(uint32_t total_block_exp);
00104
00105     /*!
00106     * \brief Write the PRN code in the FPGA
00107     */
00108     void write_local_code(void);
00109
00110     /*!
00111     * \brief Write the acquisition parameters into the FPGA
00112     */
00113     void configure_acquisition(void);
00114
00115     /*!
00116     * \brief Open the device driver
00117     */
00118     void open_device();
00119
00120     /*!
00121     * \brief Close the device driver
00122     */
00123     void close_device();
00124
00125 private:
00126     // FPGA IP Core version
00127     static const uint32_t FPGA_ACQ_IP_VERSION_1 = 0x0001; // FPGA IP core version
00128
00129     // FPGA register addresses

```

```

00130
00131 // write-only registers
00132 static const uint32_t FREQ_BAND_DOWNSAMPLE_REG_ADDR = 0; // Select frequency band and
downsampling filter
00133 static const uint32_t FFT_LENGTH_REG_ADDR = 1; // Length of the FFT
00134 static const uint32_t CORR_NSAMPLES_REG_ADDR = 2; // Correlation length
00135 static const uint32_t DOPPLER_MIN_REG_ADDR = 3; // Doppler min
00136 static const uint32_t DOPPLER_STEP_REG_ADDR = 4; // Doppler step
00137 static const uint32_t NUM_DOPPLER_SEARCH_STEPS_REG_ADDR = 5; // Number of Doppler search steps
00138 static const uint32_t PROG_MEM_ADDR = 6; // Access to the memory storing the
PRN code of the target satellite.
00139 static const uint32_t LOG2_FFT_LENGTH_REG_ADDR = 7; // Log2(FFT_LENGTH)
00140 static const uint32_t ACQ_COMMAND_FLAGS_REG_ADDR = 8; // Flags that reset, start, and stop
the acquisition process.
00141 static const uint32_t CLEAR_MEM_REG_ADDR = 9; // Flag that resets the write
address of the PRN code memory.
00142 static const uint32_t MAX_FFT_SCALING_FACTOR_REG_ADDR = 11; // Reference FFT scaling factor
00143 static const uint32_t EXCL_LIM_REG_ADDR = 12; // Exclude Limit value for the
second FFT peak search process
00144
00145 // read-write registers
00146 static const uint32_t TEST_REG_ADDR = 15;
00147
00148 // read-only registers
00149 static const uint32_t RESULT_VALID_REG_ADDR = 0; // Flag that indicates a
valid result
00150 static const uint32_t SAMPLESTAMP_LSW_REG_ADDR = 1; // Sample stamp LSW
00151 static const uint32_t SAMPLESTAMP_MSW_REG_ADDR = 2; // Sample stamp MSW
00152 static const uint32_t MAG_SQ_FIRST_PEAK_REG_ADDR = 3; // magnitude squared of the
first peak
00153 static const uint32_t MAG_SQ_SECOND_PEAK_REG_ADDR = 4; // magnitude squared of the
second peak
00154 static const uint32_t ACQ_DELAY_SAMPLES_REG_ADDR = 5; // acquisition delay in
samples
00155 static const uint32_t DOPPLER_INDEX_REG_ADDR = 7; // Doppler index
00156 static const uint32_t FFT_SCALING_FACTOR_REG_ADDR = 8; // Scaling factor applied by
the FFT
00157 static const uint32_t MAX_FFT_SIZE_REG_ADDR = 9; // Maximum FFT size
supported by the FPGA
00158 static const uint32_t DOWNSAMPLING_FILTER_DEC_FACTORS_REG_ADDR = 10; // Available decimation
factors
00159 static const uint32_t DOWNSAMPLING_FILTER_LATENCIES_REG_ADDR = 11; // Available downsampling
filter latencies
00160 static const uint32_t FPGA_IP_CORE_VERSION_REG_ADDR = 14; // FPGA acquisition IP core
version
00161
00162 // FPGA register parameters
00163 static const uint32_t FPGA_PAGE_SIZE = 0x1000; // default page size for the
multicorrelator memory map
00164 static const uint32_t LAUNCH_ACQUISITION = 1; // command to launch the acquisition
process
00165 static const uint32_t RESET_ACQUISITION = 2; // command to reset the acquisition
and the FPGA Modules
00166 static const uint32_t STOP_ACQUISITION = 4; // command to stop the acquisition
and the FPGA modules
00167 static const uint32_t TEST_REG_SANITY_CHECK = 0x55AA; // value to check the presence of
the test register (to detect the hw)
00168 static const uint32_t LOCAL_CODE_CLEAR_MEM = 0x10000000; // command to clear the internal
memory of the multicorrelator
00169 static const uint32_t MEM_LOCAL_CODE_WR_ENABLE = 0x0C000000; // command to enable the ENA and WR
pins of the internal memory of the multicorrelator
00170 static const uint32_t POW_2_2 = 4; // 2^2 (used for the conversion of
floating point numbers to integers)
00171 static const uint32_t POW_2_31 = 2147483648; // 2^31 (used for the conversion of
floating point numbers to integers)
00172 static const uint32_t MAX_FILTERS_AVAILABLE = 2; // maximum number of downsampling
filters available in the FPGA by default
00173 static const uint32_t DEFAULT_MAX_FFT_SIZE = 32768; // default maximum FFT size
supported by the FPGA
00174 static const uint32_t ACQ_BUFF_0 = 0; // FPGA Acquisition IP buffer
containing L1/E1 frequency band samples by default.
00175 static const uint32_t ACQ_BUFF_1 = 0; // FPGA Acquisition IP buffer
containing L2 or L5/E5a frequency band samples by default.
00176
00177 // bit manipulation
00178 static const uint32_t RSHIFT_4_BITS = 0x4;
00179 static const uint32_t RSHIFT_8_BITS = 0x8;
00180 static const uint32_t BIT_MASK_4 = 0xF;
00181 static const uint32_t BIT_MASK_8 = 0xFF;
00182
00183 // Downsampling default constants
00184 const uint32_t DEFAULT_DOWNSAMPLING_FILTER_DELAY = 40; // default downsampling filter delay (for
FPGA Acquisition IP core versions earlier than FPGA_ACQ_IP_VERSION_1)
00185 const uint32_t DEFAULT_DOWNSAMPLING_FACTOR = 4; // default downsampling factor (for FPGA
Acquisition IP core versions earlier than FPGA_ACQ_IP_VERSION_1)
00186
00187 // private methods

```

```

00188     void fpga_acquisition_test_register(void);
00189     void read_ipcore_info(std::vector<std::pair<uint32_t, uint32_t> &downsampling_filter_specs,
00190                          uint32_t &max_FFT_size);
00191
00191     std::vector<std::pair<uint32_t, uint32_t> > d_downsampling_filter_specs;
00192     std::string d_device_name;           // HW device name
00193     int64_t d_resampled_fs;             // sampling frequency
00194     volatile uint32_t *d_map_base;      // driver memory map
00195     uint32_t *d_all_fft_codes;         // memory that contains all the code ffts
00196     int32_t d_fd;                      // driver descriptor
00197     uint32_t d_fft_size;               // number of samples including padding
00198     uint32_t d_excludelimit;
00199     uint32_t d_nsamples;               // number of samples not including padding
00200     uint32_t d_filter_num;             // Selected downsampling filter
00201     uint32_t d_downsampling_factor;    // downsampling_factor
00202     uint32_t d_downsampling_filter_delay; // Impulse response delay of the downsampling filter
00203     uint32_t d_select_queue;          // queue selection
00204     uint32_t d_PRN;                  // PRN
00205     uint32_t d_IP_core_version;       // FPGA acquisition IP core version
00206 };
00207
00208
00209 /** \} */
00210 /** \} */
00211 #endif // GNSS_SDR_FPGA_ACQUISITION_H

```

13.91 channel.h File Reference

Interface of a GNSS channel.

```

#include "channel_fsm.h"
#include "channel_interface.h"
#include "channel_msg_receiver_cc.h"
#include "concurrent_queue.h"
#include "gnss_signal.h"
#include "gnss_synchro.h"
#include <gnuradio/block.h>
#include <pmt/pmt.h>
#include <cstdint>
#include <memory>
#include <mutex>
#include <string>

```

Classes

- class [Channel](#)

This class represents a GNSS channel. It wraps an [AcquisitionInterface](#), a [TrackingInterface](#) and a [TelemetryDecoderInterface](#), and handles their interaction through a Finite State Machine.

13.91.1 Detailed Description

Interface of a GNSS channel.

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com Luis Esteve, 2011. luis(at)epsilon-formacion.com

It holds blocks for acquisition, tracking, navigation data extraction and pseudorange calculation.

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Definition in file [channel.h](#).

13.92 channel.h

[Go to the documentation of this file.](#)

```
00001 /*!
```

```

00002  * \file channel.h
00003  * \brief Interface of a GNSS channel.
00004  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00005  *         Luis Esteve, 2011. luis(at)epsilon-formacion.com
00006  *
00007  * It holds blocks for acquisition, tracking,
00008  * navigation data extraction and pseudorange calculation.
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_CHANNEL_H
00022 #define GNSS_SDR_CHANNEL_H
00023
00024 #include "channel_fsm.h"
00025 #include "channel_interface.h"
00026 #include "channel_msg_receiver_cc.h"
00027 #include "concurrent_queue.h"
00028 #include "gnss_signal.h"
00029 #include "gnss_synchro.h"
00030 #include <gnuradio/block.h>
00031 #include <pmt/pmt.h>
00032 #include <stdint.h>
00033 #include <string>
00034 #include <memory>
00035 #include <mutex>
00036 #include <string>
00037
00038 /** \addtogroup Channel
00039  * Classes containing a GNSS channel.
00040  * \{ */
00041 /** \addtogroup Channel_adapters channel_adapters
00042  * Classes that wrap an AcquisitionInterface,
00043  * a TrackingInterface and a TelemetryDecoderInterface, and handles
00044  * their interaction.
00045  * \{ */
00046
00047
00048 class ConfigurationInterface;
00049 class AcquisitionInterface;
00050 class TrackingInterface;
00051 class TelemetryDecoderInterface;
00052
00053
00054 /*!
00055  * \brief This class represents a GNSS channel. It wraps an AcquisitionInterface,
00056  * a TrackingInterface and a TelemetryDecoderInterface, and handles
00057  * their interaction through a Finite State Machine
00058  *
00059  */
00060 class Channel : public ChannelInterface
00061 {
00062 public:
00063     /** Constructor
00064     Channel(const ConfigurationInterface* configuration,
00065             uint32_t channel,
00066             std::shared_ptr<AcquisitionInterface> acq,
00067             std::shared_ptr<TrackingInterface> trk,
00068             std::shared_ptr<TelemetryDecoderInterface> nav,
00069             const std::string& role,
00070             const std::string& signal_str,
00071             Concurrent_Queue<pmt::pmt_t>* queue);
00072
00073     ~Channel() = default;    //!< Destructor
00074
00075     void connect(gr::top_block_sptr top_block) override;    //!< Connects the tracking block to the
00076     void disconnect(gr::top_block_sptr top_block) override;
00077     gr::basic_block_sptr get_left_block() override;
00078     gr::basic_block_sptr get_left_block_trk() override;    //!< Gets the GNU Radio tracking block input
00079     pointer get_right_block_trk() override;    //!< Gets the GNU Radio tracking block
00080     output_pointer get_left_block_acq() override;    //!< Gets the GNU Radio acquisition block
00081     input_pointer get_right_block_acq() override;    //!< Gets the GNU Radio acquisition block
00082     output_pointer get_right_block() override;    //!< Gets the GNU Radio channel block output
00083     pointer

```

```

00083
00084     inline std::string role() override { return role_; }
00085     inline std::string implementation() override { return std::string("Channel"); } //!< Returns
"Channel"
00086     inline size_t item_size() override { return 2 * sizeof(float); }
00087     Gnss_Signal get_signal() override;
00088     void start_acquisition() override;                //!< Start the State Machine
00089     void stop_channel() override;                    //!< Stop the State Machine
00090     void set_signal(const Gnss_Signal& gnss_signal_) override; //!< Sets the channel GNSS signal
00091
00092     void assist_acquisition_doppler(double Carrier_Doppler_hz) override;
00093
00094     inline std::shared_ptr<AcquisitionInterface> acquisition() const { return acq_; }
00095     inline std::shared_ptr<TrackingInterface> tracking() const { return trk_; }
00096     inline std::shared_ptr<TelemetryDecoderInterface> telemetry() const { return nav_; }
00097
00098 private:
00099     std::shared_ptr<ChannelFsm> channel_fsm_;
00100     std::shared_ptr<AcquisitionInterface> acq_;
00101     std::shared_ptr<TrackingInterface> trk_;
00102     std::shared_ptr<TelemetryDecoderInterface> nav_;
00103     channel_msg_receiver_cc_sptr channel_msg_rx_;
00104     Gnss_Synchro gnss_synchro_{};
00105     Gnss_Signal gnss_signal_;
00106     std::string role_;
00107     std::mutex mx_;
00108     uint32_t channel_;
00109     int glonass_extend_correlation_ms_;
00110     bool connected_;
00111     bool repeat_;
00112     bool flag_enable_fpga_;
00113 };
00114
00115
00116 /** \} */
00117 /** \} */
00118 #endif // GNSS_SDR_CHANNEL_H

```

13.93 channel_fsm.h File Reference

Interface of the State Machine for channel.

```

#include "acquisition_interface.h"
#include "concurrent_queue.h"
#include "telemetry_decoder_interface.h"
#include "tracking_interface.h"
#include <pmt/pmt.h>
#include <stdint>
#include <memory>
#include <mutex>

```

Classes

- class [ChannelFsm](#)

This class implements a State Machine for channel.

13.93.1 Detailed Description

Interface of the State Machine for channel.

Authors

Javier Arribas, 2019. javiarribas@gmail.com Antonio Ramos, 2017. [antonio.ramos\(at\)cttc.es](mailto:antonio.ramos(at)cttc.es) Luis Esteve, 2011. [luis\(at\)epsilon-formacion.com](mailto:luis(at)epsilon-formacion.com)

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Definition in file [channel_fsm.h](#).

13.94 channel_fsm.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file channel_fsm.h
00003  * \brief Interface of the State Machine for channel
00004  * \authors Javier Arribas, 2019. javiarribas@gmail.com
00005  *          Antonio Ramos, 2017. antonio.ramos(at)cttc.es
00006  *          Luis Esteve, 2011. luis(at)epsilon-formacion.com
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_CHANNEL_FSM_H
00020 #define GNSS_SDR_CHANNEL_FSM_H
00021
00022 #include "acquisition_interface.h"
00023 #include "concurrent_queue.h"
00024 #include "telemetry_decoder_interface.h"
00025 #include "tracking_interface.h"
00026 #include <pmt/pmt.h>
00027 #include <stdint>
00028 #include <memory>
00029 #include <mutex>
00030
00031 /** \addtogroup Channel
00032  * \{ */
00033 /** \addtogroup Channel_libs channel_libs
00034  * Library with utilities for a GNSS Channel.
00035  * \{ */
00036
00037
00038  /*!
00039  * \brief This class implements a State Machine for channel
00040  */
00041  class ChannelFsm
00042  {
00043  public:
00044      ChannelFsm();
00045      virtual ~ChannelFsm() = default;
00046      explicit ChannelFsm(std::shared_ptr<AcquisitionInterface> acquisition);
00047
00048      void set_acquisition(std::shared_ptr<AcquisitionInterface> acquisition);
00049      void set_tracking(std::shared_ptr<TrackingInterface> tracking);
00050      void set_telemetry(std::shared_ptr<TelemetryDecoderInterface> telemetry);
00051      void set_queue(Concurrent_Queue<pmt::pmt_t>* queue);
00052      void set_channel(uint32_t channel);
00053      void start_acquisition();
00054
00055      // FSM EVENTS
00056      bool Event_start_acquisition();
00057      bool Event_start_acquisition_fpga();
00058      bool Event_stop_channel();
00059      bool Event_failed_tracking_standby();
00060      virtual bool Event_valid_acquisition();
00061      virtual bool Event_failed_acquisition_repeat();
00062      virtual bool Event_failed_acquisition_no_repeat();
00063
00064  private:
00065      void start_tracking();
00066      void stop_acquisition();
00067      void stop_tracking();
00068      void request_satellite();
00069      void notify_stop_tracking();
00070
00071      std::shared_ptr<AcquisitionInterface> acq_;
00072      std::shared_ptr<TrackingInterface> trk_;
00073      std::shared_ptr<TelemetryDecoderInterface> nav_;
00074
00075      std::mutex mx_;
00076
00077      Concurrent_Queue<pmt::pmt_t>* queue_;
00078
00079      uint32_t channel_;
00080      uint32_t state_;
00081  };
00082
00083

```



```

00084 /** \} */
00085 /** \} */
00086 #endif // GNSS_SDR_CHANNEL_FSM_H

```

13.95 channel_msg_receiver_cc.h File Reference

GNU Radio block that receives asynchronous channel messages from acquisition and tracking blocks.

```

#include "channel_fsm.h"
#include <gnuradio/block.h>
#include <pmt/pmt.h>
#include <memory>

```

Classes

- class [channel_msg_receiver_cc](#)

GNU Radio block that receives asynchronous channel messages from acquisition and tracking blocks.

Typedefs

- using [channel_msg_receiver_cc_sptr](#) = `gnss_shared_ptr<channel_msg_receiver_cc>`

Functions

- `channel_msg_receiver_cc_sptr channel_msg_receiver_make_cc (std::shared_ptr< ChannelFsm > channel_fsm, bool repeat)`

13.95.1 Detailed Description

GNU Radio block that receives asynchronous channel messages from acquisition and tracking blocks.

Author

Javier Arribas, 2016. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)

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 Definition in file [channel_msg_receiver_cc.h](#).

13.96 channel_msg_receiver_cc.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file channel_msg_receiver_cc.h
00003  * \brief GNU Radio block that receives asynchronous channel messages from acquisition and tracking
00004  * \author Javier Arribas, 2016. jarribas\(at\)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_CHANNEL_MSG_RECEIVER_CC_H
00018 #define GNSS_SDR_CHANNEL_MSG_RECEIVER_CC_H
00019
00020 #include "channel_fsm.h"
00021 #include <gnuradio/block.h>
00022 #include <pmt/pmt.h>
00023 #include <memory>
00024
00025 /** \addtogroup Channel

```

```

00026  * \{ */
00027  /** \addtogroup Channel_libs
00028  * \{ */
00029
00030
00031  class channel_msg_receiver_cc;
00032
00033  using channel_msg_receiver_cc_sptr = gnss_shared_ptr<channel_msg_receiver_cc>;
00034
00035  channel_msg_receiver_cc_sptr channel_msg_receiver_make_cc(std::shared_ptr<ChannelFsm> channel_fsm,
00036    bool repeat);
00037  /*!
00038  * \brief GNU Radio block that receives asynchronous channel messages from acquisition and tracking
00039  blocks
00040  */
00041  class channel_msg_receiver_cc : public gr::block
00042  {
00043  public:
00044    ~channel_msg_receiver_cc() = default; //!< Default destructor
00045  private:
00046    friend channel_msg_receiver_cc_sptr channel_msg_receiver_make_cc(std::shared_ptr<ChannelFsm>
00047      channel_fsm, bool repeat);
00048    channel_msg_receiver_cc(std::shared_ptr<ChannelFsm> channel_fsm, bool repeat);
00049    void msg_handler_channel_events(const pmt::pmt_t& msg);
00050    std::shared_ptr<ChannelFsm> d_channel_fsm;
00051    bool d_repeat; // todo: change FSM to include repeat value
00052  };
00053
00054  /** \} */
00055  /** \} */
00056  #endif // GNSS_SDR_CHANNEL_MSG_RECEIVER_CC_H

```

13.97 array_signal_conditioner.h File Reference

It wraps blocks to change data type, filter and resample input data, adapted to array receiver.

```

#include "gnss_block_interface.h"
#include <gnuradio/block.h>
#include <cstdint>
#include <memory>
#include <string>

```

Classes

- class [ArraySignalConditioner](#)

This class wraps blocks to change data_type_adapter, input_filter and resampler to be applied to the input flow of sampled signal.

13.97.1 Detailed Description

It wraps blocks to change data type, filter and resample input data, adapted to array receiver.

Author

Javier Arribas jarribas (at) cttc.es

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 Definition in file [array_signal_conditioner.h](#).

13.98 array_signal_conditioner.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file array_signal_conditioner.h
00003  * \brief It wraps blocks to change data type, filter and resample input data, adapted to array
00004  receiver
00005  * \author Javier Arribas jarribas (at) cttc.es

```

```

00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_ARRAY_SIGNAL_CONDITIONER_H
00019 #define GNSS_SDR_ARRAY_SIGNAL_CONDITIONER_H
00020
00021
00022 #include "gnss_block_interface.h"
00023 #include <gnuradio/block.h>
00024 #include <cstdint>
00025 #include <memory>
00026 #include <string>
00027
00028 /** \addtogroup Signal_Conditioner
00029  * \{ */
00030 /** \addtogroup Signal_Conditioner_adapters
00031  * \{ */
00032
00033
00034 class ConfigurationInterface;
00035
00036
00037 /*!
00038  * \brief This class wraps blocks to change data_type_adapter, input_filter and resampler
00039  * to be applied to the input flow of sampled signal.
00040  */
00041 class ArraySignalConditioner : public GNSSBlockInterface
00042 {
00043 public:
00044     /** Constructor
00045      * \param data_type_adapt std::shared_ptr<GNSSBlockInterface> data_type_adapt,
00046      * \param in_filt std::shared_ptr<GNSSBlockInterface> in_filt,
00047      * \param res std::shared_ptr<GNSSBlockInterface> res,
00048      * \param role std::string role);
00049
00050     /** Destructor
00051      * \param default;
00052
00053     void connect(gr::top_block_sptr top_block) override;
00054     void disconnect(gr::top_block_sptr top_block) override;
00055     gr::basic_block_sptr get_left_block() override;
00056     gr::basic_block_sptr get_right_block() override;
00057
00058     inline std::string role() override { return role_; }
00059     /** Returns "Array_Signal_Conditioner"
00060     inline std::string implementation() override { return "Array_Signal_Conditioner"; }
00061     inline size_t item_size() override { return data_type_adapt->item_size(); }
00062
00063     inline std::shared_ptr<GNSSBlockInterface> data_type_adapter() { return data_type_adapt_; }
00064     inline std::shared_ptr<GNSSBlockInterface> input_filter() { return in_filt_; }
00065     inline std::shared_ptr<GNSSBlockInterface> resampler() { return res_; }
00066
00067 private:
00068     std::shared_ptr<GNSSBlockInterface> data_type_adapt_;
00069     std::shared_ptr<GNSSBlockInterface> in_filt_;
00070     std::shared_ptr<GNSSBlockInterface> res_;
00071     std::string role_;
00072     bool connected_;
00073 };
00074
00075
00076 /** \} */
00077 /** \} */
00078 #endif // GNSS_SDR_SIGNAL_CONDITIONER_H

```

13.99 signal_conditioner.h File Reference

It wraps blocks to change data type, filter and resample input data.

```

#include "gnss_block_interface.h"
#include <gnuradio/block.h>
#include <cstdint>
#include <memory>

```

```
#include <string>
```

Classes

- class [SignalConditioner](#)

This class wraps blocks to change data_type_adapter, input_filter and resampler to be applied to the input flow of sampled signal.

13.99.1 Detailed Description

It wraps blocks to change data type, filter and resample input data.

Author

Luis Esteve, 2012. [luis\(at\)epsilon-formacion.com](mailto:luis(at)epsilon-formacion.com)

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Definition in file [signal_conditioner.h](#).

13.100 signal_conditioner.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file signal_conditioner.h
00003  * \brief It wraps blocks to change data type, filter and resample input data.
00004  * \author Luis Esteve, 2012. luis\(at\)epsilon-formacion.com
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_SIGNAL_CONDITIONER_H
00019 #define GNSS_SDR_SIGNAL_CONDITIONER_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/block.h>
00023 #include <cstdlib>
00024 #include <memory>
00025 #include <string>
00026
00027 /** \addtogroup SignalConditioner Signal Conditioner
00028  * Signal Conditioner wrapper block
00029  * \{ */
00030 /** \addtogroup SignalConditioner_adapters conditioner_adapters
00031  * Wrap a Signal Conditioner with a GNSSBlockInterface
00032  * \{ */
00033
00034
00035 /*!
00036  * \brief This class wraps blocks to change data_type_adapter, input_filter and resampler
00037  * to be applied to the input flow of sampled signal.
00038  */
00039 class SignalConditioner : public GNSSBlockInterface
00040 {
00041 public:
00042     /** Constructor
00043     SignalConditioner(std::shared_ptr<GNSSBlockInterface> data_type_adapt,
00044                     std::shared_ptr<GNSSBlockInterface> in_filt,
00045                     std::shared_ptr<GNSSBlockInterface> res,
00046                     std::string role);
00047
00048     /** Destructor
00049     ~SignalConditioner() = default;
00050
00051     void connect(gr::top_block_sptr top_block) override;
00052     void disconnect(gr::top_block_sptr top_block) override;
00053     gr::basic_block_sptr get_left_block() override;
```

```

00054     gr::basic_block_sptr get_right_block() override;
00055
00056     inline std::string role() override { return role_; }
00057
00058     inline std::string implementation() override { return "Signal_Conditioner"; } //!< Returns
    "Signal_Conditioner"
00059
00060     inline size_t item_size() override { return data_type_adapt_>item_size(); }
00061
00062     inline std::shared_ptr<GNSSBlockInterface> data_type_adapter() { return data_type_adapt_; }
00063     inline std::shared_ptr<GNSSBlockInterface> input_filter() { return in_filt_; }
00064     inline std::shared_ptr<GNSSBlockInterface> resampler() { return res_; }
00065
00066 private:
00067     std::shared_ptr<GNSSBlockInterface> data_type_adapt_;
00068     std::shared_ptr<GNSSBlockInterface> in_filt_;
00069     std::shared_ptr<GNSSBlockInterface> res_;
00070     std::string role_;
00071     bool connected_;
00072 };
00073
00074
00075 /** \} */
00076 /** \} */
00077 #endif // GNSS_SDR_SIGNAL_CONDITIONER_H

```

13.101 byte_to_short.h File Reference

Adapts an 8-bits sample stream (IF) to a short int stream (IF)

```

#include "gnss_block_interface.h"
#include <gnuradio/blocks/char_to_short.h>
#include <gnuradio/blocks/file_sink.h>
#include <cstdint>
#include <string>

```

Classes

- class [ByteToShort](#)

Adapts an 8-bits sample stream (IF) to a short int stream (IF)

13.101.1 Detailed Description

Adapts an 8-bits sample stream (IF) to a short int stream (IF)

Author

Carles Fernandez Prades, cfernandez(at)cttc.es

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Definition in file [byte_to_short.h](#).

13.102 byte_to_short.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file byte_to_short.h
00003  * \brief Adapts an 8-bits sample stream (IF) to a short int stream (IF)
00004  * \author Carles Fernandez Prades, cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */

```

```

00016
00017 #ifndef GNSS_SDR_BYTE_TO_SHORT_H
00018 #define GNSS_SDR_BYTE_TO_SHORT_H
00019
00020 #include "gnss_block_interface.h"
00021 #include <gnuradio/blocks/char_to_short.h>
00022 #include <gnuradio/blocks/file_sink.h>
00023 #include <stdint>
00024 #include <string>
00025
00026 /** \addtogroup Data_Type Data Type Adapters
00027  * Classes for data type conversion
00028  * \{ */
00029 /** \addtogroup Data_type_adapters data_type_adapters
00030  * Wrap GNU Radio data type adapter blocks with a GNSSBlockInterface
00031  * \{ */
00032
00033
00034 class ConfigurationInterface;
00035
00036 /*!
00037  * \brief Adapts an 8-bits sample stream (IF) to a short int stream (IF)
00038  *
00039  */
00040 class ByteToShort : public GNSSBlockInterface
00041 {
00042 public:
00043     ByteToShort(const ConfigurationInterface* configuration,
00044                 std::string role, unsigned int in_streams,
00045                 unsigned int out_streams);
00046
00047     ~ByteToShort() = default;
00048
00049     inline std::string role() override
00050     {
00051         return role_;
00052     }
00053
00054     /*! Returns "Byte_To_Short"
00055     inline std::string implementation() override
00056     {
00057         return "Byte_To_Short";
00058     }
00059
00060     inline size_t item_size() override
00061     {
00062         return sizeof(int8_t);
00063     }
00064
00065     void connect(gr::top_block_sptr top_block) override;
00066     void disconnect(gr::top_block_sptr top_block) override;
00067     gr::basic_block_sptr get_left_block() override;
00068     gr::basic_block_sptr get_right_block() override;
00069 private:
00070     gr::blocks::char_to_short::sptr gr_char_to_short_;
00071     gr::blocks::file_sink::sptr file_sink_;
00072     std::string dump_filename_;
00073     std::string input_item_type_;
00074     std::string output_item_type_;
00075     std::string role_;
00076     unsigned int in_streams_;
00077     unsigned int out_streams_;
00078     bool dump_;
00079 };
00080
00081
00082
00083 /** \} */
00084 /** \} */
00085 #endif // GNSS_SDR_BYTE_TO_SHORT_H

```

13.103 cshort_to_grcomplex.h File Reference

Adapts an 16-bits complex sample stream to a float complex stream.

```

#include "cshort_to_gr_complex.h"
#include "gnss_block_interface.h"
#include <gnuradio/blocks/file_sink.h>
#include <stdint>
#include <string>

```

Classes

- class [CshortToGrComplex](#)

Adapts an 16-bits complex sample stream to a float complex stream.

13.103.1 Detailed Description

Adapts an 16-bits complex sample stream to a float complex stream.

Author

Carles Fernandez Prades, 2014 cfernandez(at)cttc.es

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Definition in file [cshort_to_grcomplex.h](#).

13.104 cshort_to_grcomplex.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file cshort_to_grcomplex.h
00003  * \brief Adapts an 16-bits complex sample stream to a float complex stream
00004  * \author Carles Fernandez Prades, 2014 cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_CSHORT_TO_GRCOMPLEX_H
00018 #define GNSS_SDR_CSHORT_TO_GRCOMPLEX_H
00019
00020 #include "cshort_to_gr_complex.h"
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/blocks/file_sink.h>
00023 #include <cstdlib>
00024 #include <string>
00025
00026 /** \addtogroup Data_Type Data Type Adapters
00027  * Classes for data type conversion
00028  * \{ */
00029 /** \addtogroup Data_type_adapters data_type_adapters
00030  * Wrap GNU Radio data type adapter blocks with a GNSSBlockInterface
00031  * \{ */
00032
00033
00034 class ConfigurationInterface;
00035
00036 /*!
00037 * \brief Adapts an 16-bits complex sample stream to a float complex stream
00038 *
00039 */
00040 class CshortToGrComplex : public GNSSBlockInterface
00041 {
00042 public:
00043     CshortToGrComplex(const ConfigurationInterface* configuration,
00044         std::string role, unsigned int in_streams,
00045         unsigned int out_streams);
00046
00047     ~CshortToGrComplex() = default;
00048
00049     inline std::string role() override
00050     {
00051         return role_;
00052     }
00053
00054     /*! Returns "Cshort_To_Gr_Complex"
00055     inline std::string implementation() override
00056     {
00057         return "Cshort_To_Gr_Complex";
00058     }
00059 
```

```

00060     inline size_t item_size() override
00061     {
00062         return 2 * sizeof(float);
00063     }
00064
00065     void connect(gr::top_block_sptr top_block) override;
00066     void disconnect(gr::top_block_sptr top_block) override;
00067     gr::basic_block_sptr get_left_block() override;
00068     gr::basic_block_sptr get_right_block() override;
00069
00070 private:
00071     cshort_to_gr_complex_sptr cshort_to_gr_complex_;
00072     gr::blocks::file_sink::sptr file_sink_;
00073     std::string dump_filename_;
00074     std::string role_;
00075     unsigned int in_streams_;
00076     unsigned int out_streams_;
00077     bool dump_;
00078 };
00079
00080
00081 /** \} */
00082 /** \} */
00083 #endif // GNSS_SDR_CSHORT_TO_GRCOMPLEX_H

```

13.105 ibyte_to_cbyte.h File Reference

Adapts an I/Q interleaved byte (unsigned char) sample stream into a `std::complex<unsigned char>` stream.

```

#include "conjugate_ic.h"
#include "gnss_block_interface.h"
#include "interleaved_byte_to_complex_byte.h"
#include <gnuradio/blocks/file_sink.h>
#include <stdint>
#include <string>

```

Classes

- class [IByteToCByte](#)

13.105.1 Detailed Description

Adapts an I/Q interleaved byte (unsigned char) sample stream into a `std::complex<unsigned char>` stream.

Author

Carles Fernandez Prades, [cfernandez\(at\)cttc.es](mailto:cfernandez(at)cttc.es)

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Definition in file [ibyte_to_cbyte.h](#).

13.106 ibyte_to_cbyte.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file ibyte_to_cbyte.h
00003  * \brief \brief Adapts an I/Q interleaved byte (unsigned char) sample stream
00004  * into a std::complex<unsigned char> stream
00005  * \author Carles Fernandez Prades, cfernandez\(at\)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
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00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
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00014  *
00015  * -----
00016  */
00017

```



```

00018 #ifndef GNSS_SDR_IBYTE_TO_CBYTE_H
00019 #define GNSS_SDR_IBYTE_TO_CBYTE_H
00020
00021 #include "conjugate_ic.h"
00022 #include "gnss_block_interface.h"
00023 #include "interleaved_byte_to_complex_byte.h"
00024 #include <gnuradio/blocks/file_sink.h>
00025 #include <stdint>
00026 #include <string>
00027
00028 /** \addtogroup Data_Type
00029 * \{ */
00030 /** \addtogroup Data_type_adapters
00031 * \{ */
00032
00033
00034 class ConfigurationInterface;
00035
00036 /*!
00037 * \brief Adapts an I/Q interleaved byte (unsigned char) sample stream
00038 * into a std::complex<unsigned char> stream
00039 */
00040 class IbyteToCbyte : public GNSSBlockInterface
00041 {
00042 public:
00043     IbyteToCbyte(const ConfigurationInterface* configuration,
00044                 const std::string& role, unsigned int in_streams,
00045                 unsigned int out_streams);
00046
00047     ~IbyteToCbyte() = default;
00048
00049     inline std::string role() override
00050     {
00051         return role_;
00052     }
00053
00054     /*! Returns "Ibyte_To_Cbyte"
00055     inline std::string implementation() override
00056     {
00057         return "Ibyte_To_Cbyte";
00058     }
00059
00060     inline size_t item_size() override
00061     {
00062         return 2 * sizeof(int8_t);
00063     }
00064
00065     void connect(gr::top_block_sptr top_block) override;
00066     void disconnect(gr::top_block_sptr top_block) override;
00067     gr::basic_block_sptr get_left_block() override;
00068     gr::basic_block_sptr get_right_block() override;
00069
00070 private:
00071     interleaved_byte_to_complex_byte_sptr ibyte_to_cbyte_;
00072     conjugate_ic_sptr conjugate_ic_;
00073     gr::blocks::file_sink::sptr file_sink_;
00074     std::string dump_filename_;
00075     std::string input_item_type_;
00076     std::string output_item_type_;
00077     std::string role_;
00078     unsigned int in_streams_;
00079     unsigned int out_streams_;
00080     bool inverted_spectrum;
00081     bool dump_;
00082 };
00083
00084
00085 /** \} */
00086 /** \} */
00087 #endif // GNSS_SDR_IBYTE_TO_CBYTE_H

```

13.107 ibyte_to_complex.h File Reference

Adapts an I/Q interleaved byte integer sample stream to a gr_complex (float) stream.

```

#include "conjugate_cc.h"
#include "gnss_block_interface.h"
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/interleaved_char_to_complex.h>
#include <stdint>
#include <string>

```

Classes

- class [IbyteToComplex](#)

Adapts an I/Q interleaved byte integer sample stream to a gr_complex (float) stream.

13.107.1 Detailed Description

Adapts an I/Q interleaved byte integer sample stream to a gr_complex (float) stream.

Author

Javier Arribas, jarribas(at)cttc.es

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Definition in file [ibyte_to_complex.h](#).

13.108 ibyte_to_complex.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file ibyte_to_complex.h
00003  * \brief Adapts an I/Q interleaved byte integer sample stream to a gr_complex (float) stream
00004  * \author Javier Arribas, jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
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00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_IBYTE_TO_COMPLEX_H
00018 #define GNSS_SDR_IBYTE_TO_COMPLEX_H
00019
00020 #include "conjugate_cc.h"
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/blocks/file_sink.h>
00023 #include <gnuradio/blocks/interleaved_char_to_complex.h>
00024 #include <stdint>
00025 #include <string>
00026
00027 /** \addtogroup Data_Type
00028  * \{ */
00029 /** \addtogroup Data_type_adapters
00030  * \{ */
00031
00032
00033 class ConfigurationInterface;
00034
00035 /*!
00036 * \brief Adapts an I/Q interleaved byte integer sample stream to a gr_complex (float) stream
00037 *
00038 */
00039 class IbyteToComplex : public GNSSBlockInterface
00040 {
00041 public:
00042     IbyteToComplex(const ConfigurationInterface* configuration,
00043                   const std::string& role, unsigned int in_streams,
00044                   unsigned int out_streams);
00045
00046     ~IbyteToComplex() = default;
00047
00048     inline std::string role() override
00049     {
00050         return role_;
00051     }
00052
00053     //! Returns "Ibyte_To_Complex"
00054     inline std::string implementation() override
00055     {
00056         return "Ibyte_To_Complex";
00057     }
00058
00059     inline size_t item_size() override

```

```

00060     {
00061         return 2 * sizeof(int8_t);
00062     }
00063
00064     void connect(gr::top_block_sptr top_block) override;
00065     void disconnect(gr::top_block_sptr top_block) override;
00066     gr::basic_block_sptr get_left_block() override;
00067     gr::basic_block_sptr get_right_block() override;
00068
00069 private:
00070     gr::blocks::interleaved_char_to_complex::sptr gr_interleaved_char_to_complex_;
00071     conjugate_cc_sptr conjugate_cc_;
00072     gr::blocks::file_sink::sptr file_sink_;
00073     std::string dump_filename_;
00074     std::string input_item_type_;
00075     std::string output_item_type_;
00076     std::string role_;
00077     unsigned int in_streams_;
00078     unsigned int out_streams_;
00079     bool inverted_spectrum;
00080     bool dump_;
00081 };
00082
00083
00084 /** \} */
00085 /** \} */
00086 #endif // GNSS_SDR_IBYTE_TO_COMPLEX_H

```

13.109 ibyte_to_cshort.h File Reference

Adapts a short interleaved sample stream into a `std::complex<short>` stream.

```

#include "conjugate_sc.h"
#include "gnss_block_interface.h"
#include "interleaved_byte_to_complex_short.h"
#include <gnuradio/blocks/file_sink.h>
#include <cstdint>
#include <string>

```

Classes

- class [IbyteToCshort](#)

Adapts a short integer (16 bits) interleaved sample stream into a `std::complex<short>` stream.

13.109.1 Detailed Description

Adapts a short interleaved sample stream into a `std::complex<short>` stream.

Author

Carles Fernandez-Prades, [cfernandez\(at\)cttc.es](mailto:cfernandez(at)cttc.es)

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 Definition in file [ibyte_to_cshort.h](#).

13.110 ibyte_to_cshort.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file ibyte_to_cshort.h
00003  * \brief Adapts a short interleaved sample stream into a std::complex<short> stream
00004  * \author Carles Fernandez-Prades, cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
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00012  * SPDX-License-Identifier: GPL-3.0-or-later

```

```

00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_IBYTE_TO_CSHORT_H
00018 #define GNSS_SDR_IBYTE_TO_CSHORT_H
00019
00020 #include "conjugate_sc.h"
00021 #include "gnss_block_interface.h"
00022 #include "interleaved_byte_to_complex_short.h"
00023 #include <gnuradio/blocks/file_sink.h>
00024 #include <stdint>
00025 #include <string>
00026
00027 /** \addtogroup Data_Type
00028  * \{ */
00029 /** \addtogroup Data_type_adapters
00030  * \{ */
00031
00032
00033 class ConfigurationInterface;
00034
00035 /*!
00036  * \brief Adapts a short integer (16 bits) interleaved sample stream into a std::complex<short> stream
00037  *
00038  */
00039 class IbyteToCshort : public GNSSBlockInterface
00040 {
00041 public:
00042     IbyteToCshort(const ConfigurationInterface* configuration,
00043                  const std::string& role, unsigned int in_streams,
00044                  unsigned int out_streams);
00045
00046     ~IbyteToCshort() = default;
00047
00048     inline std::string role() override
00049     {
00050         return role_;
00051     }
00052
00053     /*! Returns "Ibyte_To_Cshort"
00054     inline std::string implementation() override
00055     {
00056         return "Ibyte_To_Cshort";
00057     }
00058
00059     inline size_t item_size() override
00060     {
00061         return 2 * sizeof(int8_t);
00062     }
00063
00064     void connect(gr::top_block_sptr top_block) override;
00065     void disconnect(gr::top_block_sptr top_block) override;
00066     gr::basic_block_sptr get_left_block() override;
00067     gr::basic_block_sptr get_right_block() override;
00068
00069 private:
00070     interleaved_byte_to_complex_short_sptr interleaved_byte_to_complex_short_;
00071     conjugate_sc_sptr conjugate_sc_;
00072     gr::blocks::file_sink::sptr file_sink_;
00073     std::string dump_filename_;
00074     std::string input_item_type_;
00075     std::string output_item_type_;
00076     std::string role_;
00077     unsigned int in_streams_;
00078     unsigned int out_streams_;
00079     bool inverted_spectrum;
00080     bool dump_;
00081 };
00082
00083
00084 /** \} */
00085 /** \} */
00086 #endif // GNSS_SDR_IBYTE_TO_CSHORT_H

```

13.111 ishort_to_complex.h File Reference

Adapts an I/Q interleaved short integer sample stream to a gr_complex (float) stream.

```

#include "conjugate_cc.h"
#include "gnss_block_interface.h"
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/interleaved_short_to_complex.h>

```

```
#include <cstdint>
#include <string>
```

Classes

- class [IshortToComplex](#)

Adapts an I/Q interleaved short integer sample stream to a gr_complex (float) stream.

13.111.1 Detailed Description

Adapts an I/Q interleaved short integer sample stream to a gr_complex (float) stream.

Author

Javier Arribas, jarribas(at)cttc.es

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 Definition in file [ishort_to_complex.h](#).

13.112 ishort_to_complex.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file ishort_to_complex.h
00003  * \brief Adapts an I/Q interleaved short integer sample stream to a gr_complex (float) stream
00004  * \author Javier Arribas, jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_ISHORT_TO_COMPLEX_H
00018 #define GNSS_SDR_ISHORT_TO_COMPLEX_H
00019
00020 #include "conjugate_cc.h"
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/blocks/file_sink.h>
00023 #include <gnuradio/blocks/interleaved_short_to_complex.h>
00024 #include <cstdint>
00025 #include <string>
00026
00027 /** \addtogroup Data_Type
00028  * \{ */
00029 /** \addtogroup Data_type_adapters
00030  * \{ */
00031
00032
00033 class ConfigurationInterface;
00034
00035 /*!
00036  * \brief Adapts an I/Q interleaved short integer sample stream to a gr_complex (float) stream
00037  *
00038  */
00039 class IshortToComplex : public GNSSBlockInterface
00040 {
00041 public:
00042     IshortToComplex(const ConfigurationInterface* configuration,
00043                     const std::string& role, unsigned int in_streams,
00044                     unsigned int out_streams);
00045
00046     ~IshortToComplex() = default;
00047
00048     inline std::string role() override
00049     {
00050         return role_;
00051     }
00052 }
```

```

00053     //!< Returns "Ishort_To_Complex"
00054     inline std::string implementation() override
00055     {
00056         return "Ishort_To_Complex";
00057     }
00058
00059     inline size_t item_size() override
00060     {
00061         return 2 * sizeof(int16_t);
00062     }
00063
00064     void connect(gr::top_block_sptr top_block) override;
00065     void disconnect(gr::top_block_sptr top_block) override;
00066     gr::basic_block_sptr get_left_block() override;
00067     gr::basic_block_sptr get_right_block() override;
00068
00069 private:
00070     gr::blocks::interleaved_short_to_complex::sptr gr_interleaved_short_to_complex_;
00071     conjugate_cc_sptr conjugate_cc_;
00072     gr::blocks::file_sink::sptr file_sink_;
00073     std::string dump_filename_;
00074     std::string input_item_type_;
00075     std::string output_item_type_;
00076     std::string role_;
00077     unsigned int in_streams_;
00078     unsigned int out_streams_;
00079     bool inverted_spectrum;
00080     bool dump_;
00081 };
00082
00083
00084 /** @} */
00085 /** @} */
00086 #endif // GNSS_SDR_ISHORT_TO_COMPLEX_H

```

13.113 ishort_to_cshort.h File Reference

Adapts a short interleaved sample stream into a `std::complex<short>` stream.

```

#include "conjugate_sc.h"
#include "gnss_block_interface.h"
#include "interleaved_short_to_complex_short.h"
#include <gnuradio/blocks/file_sink.h>
#include <stdint>
#include <string>

```

Classes

- class [IshortToCshort](#)

Adapts a short integer (16 bits) interleaved sample stream into a `std::complex<short>` stream.

13.113.1 Detailed Description

Adapts a short interleaved sample stream into a `std::complex<short>` stream.

Author

Carles Fernandez-Prades, cfernandez(at)cttc.es

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Definition in file [ishort_to_cshort.h](#).

13.114 ishort_to_cshort.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file ishort_to_cshort.h
00003  * \brief Adapts a short interleaved sample stream into a std::complex<short> stream
00004  * \author Carles Fernandez-Prades, cfernandez(at)cttc.es
00005  *

```

```

00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_ISHORT_TO_CSHORT_H
00018 #define GNSS_SDR_ISHORT_TO_CSHORT_H
00019
00020 #include "conjugate_sc.h"
00021 #include "gnss_block_interface.h"
00022 #include "interleaved_short_to_complex_short.h"
00023 #include <gnuradio/blocks/file_sink.h>
00024 #include <stdint>
00025 #include <string>
00026
00027 /** \addtogroup Data_Type
00028  * \{ */
00029 /** \addtogroup Data_type_adapters
00030  * \{ */
00031
00032
00033 class ConfigurationInterface;
00034
00035 /*!
00036  * \brief Adapts a short integer (16 bits) interleaved sample stream into a std::complex<short> stream
00037  *
00038  */
00039 class IshortToCshort : public GNSSBlockInterface
00040 {
00041 public:
00042     IshortToCshort(const ConfigurationInterface* configuration,
00043                   const std::string& role, unsigned int in_streams,
00044                   unsigned int out_streams);
00045
00046     ~IshortToCshort() = default;
00047
00048     inline std::string role() override
00049     {
00050         return role_;
00051     }
00052
00053     /*! Returns "Ishort_To_Cshort"
00054     inline std::string implementation() override
00055     {
00056         return "Ishort_To_Cshort";
00057     }
00058
00059     inline size_t item_size() override
00060     {
00061         return 2 * sizeof(int16_t);
00062     }
00063
00064     void connect(gr::top_block_sptr top_block) override;
00065     void disconnect(gr::top_block_sptr top_block) override;
00066     gr::basic_block_sptr get_left_block() override;
00067     gr::basic_block_sptr get_right_block() override;
00068
00069 private:
00070     interleaved_short_to_complex_short_sptr interleaved_short_to_complex_short_;
00071     conjugate_sc_sptr conjugate_sc_;
00072     gr::blocks::file_sink::sptr file_sink_;
00073     std::string dump_filename_;
00074     std::string input_item_type_;
00075     std::string output_item_type_;
00076     std::string role_;
00077     unsigned int in_streams_;
00078     unsigned int out_streams_;
00079     bool inverted_spectrum;
00080     bool dump_;
00081 };
00082
00083
00084 /** \} */
00085 /** \} */
00086 #endif // GNSS_SDR_ISHORT_TO_CSHORT_H

```

13.115 cshort_to_gr_complex.h File Reference

Adapts a complex short (16 + 16 bits) sample stream into a `std::complex<float>` stream (32 + 32 bits)

```
#include "gnss_block_interface.h"
#include <gnuradio/sync_block.h>
```

Classes

- class [csshort_to_gr_complex](#)

This class adapts a short (16-bits) interleaved sample stream into a `std::complex<float>` stream.

Typedefs

- using [csshort_to_gr_complex_sptr](#) = `gnss_shared_ptr<csshort_to_gr_complex>`

Functions

- `csshort_to_gr_complex_sptr make_cshort_to_gr_complex ()`

13.115.1 Detailed Description

Adapts a complex short (16 + 16 bits) sample stream into a `std::complex<float>` stream (32 + 32 bits)

Author

Carles Fernandez Prades, 2014 cfernandez(at)cttc.es

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Definition in file [csshort_to_gr_complex.h](#).

13.116 cshort_to_gr_complex.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file cshort_to_gr_complex.h
00003  * \brief Adapts a complex short (16 + 16 bits) sample stream into a
00004  *       std::complex<float> stream (32 + 32 bits)
00005  * \author Carles Fernandez Prades, 2014 cfernandez(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_CSHORT_TO_GR_COMPLEX_H
00019 #define GNSS_SDR_CSHORT_TO_GR_COMPLEX_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_block.h>
00023
00024 /** \addtogroup Data_Type
00025  *  \{ */
00026 /** \addtogroup data_type_gnuradio_blocks
00027  *  \{ */
00028
00029
00030 class cshort_to_gr_complex;
00031
00032 using cshort_to_gr_complex_sptr = gnss_shared_ptr<csshort_to_gr_complex>;
00033
00034 cshort_to_gr_complex_sptr make_cshort_to_gr_complex();
00035
00036 /*!
```



```

00037  * \brief This class adapts a short (16-bits) interleaved sample stream
00038  * into a std::complex<float> stream
00039  */
00040  class cshort_to_gr_complex : public gr::sync_block
00041  {
00042  public:
00043      int work(int noutput_items,
00044              gr_vector_const_void_star &input_items,
00045              gr_vector_void_star &output_items);
00046  private:
00047      friend cshort_to_gr_complex_sptr make_cshort_to_gr_complex();
00048      cshort_to_gr_complex();
00049  };
00050  };
00051
00052
00053  /** \} */
00054  /** \} */
00055  #endif // GNSS_SDR_CSHORT_TO_GR_COMPLEX_H

```

13.117 interleaved_byte_to_complex_byte.h File Reference

Adapts an 8-bits interleaved sample stream into a 16-bits complex stream.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_decimator.h>

```

Classes

- class [interleaved_byte_to_complex_byte](#)
This class adapts an 8-bits interleaved sample stream into a 16-bits complex stream (std::complex<unsigned char>)

Typedefs

- using [interleaved_byte_to_complex_byte_sptr](#) = [gnss_shared_ptr](#)<[interleaved_byte_to_complex_byte](#)>

Functions

- [interleaved_byte_to_complex_byte_sptr](#) [make_interleaved_byte_to_complex_byte](#) ()

13.117.1 Detailed Description

Adapts an 8-bits interleaved sample stream into a 16-bits complex stream.

Author

Carles Fernandez Prades, cfernandez(at)cttc.es

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 Definition in file [interleaved_byte_to_complex_byte.h](#).

13.118 interleaved_byte_to_complex_byte.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file interleaved_byte_to_complex_byte.h
00003  * \brief Adapts an 8-bits interleaved sample stream into a 16-bits complex stream
00004  * \author Carles Fernandez Prades, cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  *
00014  * -----

```

```

00015  */
00016
00017 #ifndef GNSS_SDR_INTERLEAVED_BYTE_TO_COMPLEX_BYTE_H
00018 #define GNSS_SDR_INTERLEAVED_BYTE_TO_COMPLEX_BYTE_H
00019
00020 #include "gnss_block_interface.h"
00021 #include <gnuradio/sync_decimator.h>
00022
00023 /** \addtogroup Data_Type
00024  * \{ */
00025 /** \addtogroup data_type_gnuradio_blocks data_type_gr_blocks
00026  * GNU Radio Blocks for data type conversion
00027  * \{ */
00028
00029
00030 class interleaved_byte_to_complex_byte;
00031
00032 using interleaved_byte_to_complex_byte_sptr = gnss_shared_ptr<interleaved_byte_to_complex_byte>;
00033
00034 interleaved_byte_to_complex_byte_sptr make_interleaved_byte_to_complex_byte();
00035
00036 /*!
00037  * \brief This class adapts an 8-bits interleaved sample stream
00038  * into a 16-bits complex stream (std::complex<unsigned char>)
00039  */
00040 class interleaved_byte_to_complex_byte : public gr::sync_decimator
00041 {
00042 public:
00043     int work(int noutput_items,
00044             gr_vector_const_void_star &input_items,
00045             gr_vector_void_star &output_items);
00046 private:
00047     friend interleaved_byte_to_complex_byte_sptr make_interleaved_byte_to_complex_byte();
00048     interleaved_byte_to_complex_byte();
00049 };
00050
00051
00052
00053 /** \} */
00054 /** \} */
00055 #endif // GNSS_SDR_INTERLEAVED_BYTE_TO_COMPLEX_BYTE_H

```

13.119 interleaved_byte_to_complex_short.h File Reference

Adapts a byte (8-bits) interleaved sample stream into a `std::complex<short>` stream.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_decimator.h>

```

Classes

- class [interleaved_byte_to_complex_short](#)

This class adapts a short (16-bits) interleaved sample stream into a `std::complex<short>` stream.

Typedefs

- using [interleaved_byte_to_complex_short_sptr](#) = `gnss_shared_ptr<interleaved_byte_to_complex_short>`

Functions

- `interleaved_byte_to_complex_short_sptr` [make_interleaved_byte_to_complex_short](#) ()

13.119.1 Detailed Description

Adapts a byte (8-bits) interleaved sample stream into a `std::complex<short>` stream.

Author

Javier Arribas (jarribas(at)cttc.es)

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 Definition in file [interleaved_byte_to_complex_short.h](#).

13.120 interleaved_byte_to_complex_short.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file interleaved_byte_to_complex_short.h
00003  * \brief Adapts a byte (8-bits) interleaved sample stream into a std::complex<short> stream
00004  * \author Javier Arribas (jarribas(at)cttc.es)
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_INTERLEAVED_BYTE_TO_COMPLEX_SHORT_H
00018 #define GNSS_SDR_INTERLEAVED_BYTE_TO_COMPLEX_SHORT_H
00019
00020 #include "gnss_block_interface.h"
00021 #include <gnuradio/sync_decimator.h>
00022
00023
00024 /** \addtogroup Data_Type
00025  * \{ */
00026 /** \addtogroup data_type_gnuradio_blocks
00027  * \{ */
00028
00029
00030 class interleaved_byte_to_complex_short;
00031
00032 using interleaved_byte_to_complex_short_sptr = gnss_shared_ptr<interleaved_byte_to_complex_short>;
00033
00034 interleaved_byte_to_complex_short_sptr make_interleaved_byte_to_complex_short();
00035
00036 /*!
00037 * \brief This class adapts a short (16-bits) interleaved sample stream
00038 * into a std::complex<short> stream
00039 */
00040 class interleaved_byte_to_complex_short : public gr::sync_decimator
00041 {
00042 public:
00043     int work(int noutput_items,
00044             gr_vector_const_void_star &input_items,
00045             gr_vector_void_star &output_items);
00046
00047 private:
00048     friend interleaved_byte_to_complex_short_sptr make_interleaved_byte_to_complex_short();
00049     interleaved_byte_to_complex_short();
00050 };
00051
00052
00053 /** \} */
00054 /** \} */
00055 #endif // GNSS_SDR_INTERLEAVED_BYTE_TO_COMPLEX_SHORT_H

```

13.121 interleaved_short_to_complex_short.h File Reference

Adapts a short (16-bits) interleaved sample stream into a std::complex<short> stream.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_decimator.h>

```

Classes

- class [interleaved_short_to_complex_short](#)

This class adapts a short (16-bits) interleaved sample stream into a std::complex<short> stream.

Typedefs

- using [interleaved_short_to_complex_short_sptr](#) = gnss_shared_ptr<interleaved_short_to_complex_short>

Functions

- `interleaved_short_to_complex_short_sptr make_interleaved_short_to_complex_short ()`

13.121.1 Detailed Description

Adapts a short (16-bits) interleaved sample stream into a `std::complex<short>` stream.

Author

Carles Fernandez Prades, [cfernandez\(at\)cttc.es](mailto:cfernandez(at)cttc.es)

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 Definition in file [interleaved_short_to_complex_short.h](#).

13.122 interleaved_short_to_complex_short.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file interleaved_short_to_complex_short.h
00003  * \brief Adapts a short (16-bits) interleaved sample stream into a std::complex<short> stream
00004  * \author Carles Fernandez Prades, cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_INTERLEAVED_SHORT_TO_COMPLEX_SHORT_H
00018 #define GNSS_SDR_INTERLEAVED_SHORT_TO_COMPLEX_SHORT_H
00019
00020 #include "gnss_block_interface.h"
00021 #include <gnuradio/sync_decimator.h>
00022
00023 /** \addtogroup Data_Type
00024  * \{ */
00025 /** \addtogroup data_type_gnuradio_blocks
00026  * \{ */
00027
00028
00029 class interleaved_short_to_complex_short;
00030
00031 using interleaved_short_to_complex_short_sptr = gnss_shared_ptr<interleaved_short_to_complex_short>;
00032
00033 interleaved_short_to_complex_short_sptr make_interleaved_short_to_complex_short();
00034
00035 /*!
00036  * \brief This class adapts a short (16-bits) interleaved sample stream
00037  * into a std::complex<short> stream
00038  */
00039 class interleaved_short_to_complex_short : public gr::sync_decimator
00040 {
00041 public:
00042     int work(int noutput_items,
00043             gr_vector_const_void_star &input_items,
00044             gr_vector_void_star &output_items);
00045 private:
00046     friend interleaved_short_to_complex_short_sptr make_interleaved_short_to_complex_short();
00047     interleaved_short_to_complex_short();
00048 };
00049
00050
00051
00052 /** \} */
00053 /** \} */
00054 #endif // GNSS_SDR_INTERLEAVED_SHORT_TO_COMPLEX_SHORT_H
```

13.123 beamformer_filter.h File Reference

Interface of an adapter of a digital beamformer.

```
#include "gnss_block_interface.h"
#include <gnuradio/hier_block2.h>
#include <stdint>
#include <string>
```

Classes

- class [BeamformerFilter](#)

Interface of an adapter of a digital beamformer block to a [GNSSBlockInterface](#).

13.123.1 Detailed Description

Interface of an adapter of a digital beamformer.

Author

Javier Arribas jarribas (at) cttc.es

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 Definition in file [beamformer_filter.h](#).

13.124 beamformer_filter.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file beamformer_filter.h
00003  * \brief Interface of an adapter of a digital beamformer
00004  * \author Javier Arribas jarribas (at) cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_BEAMFORMER_FILTER_H
00019 #define GNSS_SDR_BEAMFORMER_FILTER_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/hier_block2.h>
00023 #include <stdint>
00024 #include <string>
00025
00026 /** \addtogroup Input_Filter
00027  * \{ */
00028 /** \addtogroup Input_filter_adapters
00029  * \{ */
00030
00031
00032 class ConfigurationInterface;
00033
00034 /*!
00035  * \brief Interface of an adapter of a digital beamformer block
00036  * to a GNSSBlockInterface
00037  */
00038 class BeamformerFilter : public GNSSBlockInterface
00039 {
00040 public:
00041     BeamformerFilter(const ConfigurationInterface* configuration,
00042                     const std::string& role, unsigned int in_stream,
00043                     unsigned int out_stream);
00044
00045     ~BeamformerFilter() = default;
00046
00047     inline std::string role() override
00048     {
00049         return role_;
```

```

00050     }
00051
00052     ///! returns "Beamformer_Filte"
00053     inline std::string implementation() override
00054     {
00055         return "Beamformer_Filter";
00056     }
00057
00058     inline size_t item_size() override
00059     {
00060         return item_size_;
00061     }
00062
00063     void connect(gr::top_block_sptr top_block) override;
00064     void disconnect(gr::top_block_sptr top_block) override;
00065     gr::basic_block_sptr get_left_block() override;
00066     gr::basic_block_sptr get_right_block() override;
00067
00068 private:
00069     gr::block_sptr beamformer_;
00070     gr::block_sptr file_sink_;
00071     std::string role_;
00072     std::string item_type_;
00073     std::string dump_filename_;
00074     size_t item_size_;
00075     unsigned int in_stream_;
00076     unsigned int out_stream_;
00077     bool dump_;
00078 };
00079
00080
00081 /** \} */
00082 /** \} */
00083 #endif // GNSS_SDR_BEAMFORMER_FILTER_H

```

13.125 fir_filter.h File Reference

Adapts a gnuradio gr_fir_filter designed with pm_remez.

```

#include "byte_x2_to_complex_byte.h"
#include "complex_byte_to_float_x2.h"
#include "cshort_to_float_x2.h"
#include "gnss_block_interface.h"
#include "short_x2_to_cshort.h"
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/float_to_char.h>
#include <gnuradio/blocks/float_to_complex.h>
#include <gnuradio/blocks/float_to_short.h>
#include <gnuradio/gr_complex.h>
#include <gnuradio/filter/fir_filter_ccf.h>
#include <gnuradio/filter/fir_filter_fff.h>
#include <cmath>
#include <string>
#include <vector>

```

Classes

- class [FirFilter](#)

This class adapts a GNU Radio gr_fir_filter designed with pm_remez.

13.125.1 Detailed Description

Adapts a gnuradio gr_fir_filter designed with pm_remez.

Author

Luis Esteve, 2012. luis(at)epsilon-formacion.com

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Definition in file [fir_filter.h](#).

13.126 fir_filter.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file fir_filter.h
00003  * \brief Adapts a gnuradio gr_fir_filter designed with pm_remez
00004  * \author Luis Esteve, 2012. luis(at)epsilon-formacion.com
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_FIR_FILTER_H
00019 #define GNSS_SDR_FIR_FILTER_H
00020
00021 #include "byte_x2_to_complex_byte.h"
00022 #include "complex_byte_to_float_x2.h"
00023 #include "cshort_to_float_x2.h"
00024 #include "gnss_block_interface.h"
00025 #include "short_x2_to_cshort.h"
00026 #include <gnuradio/blocks/file_sink.h>
00027 #include <gnuradio/blocks/float_to_char.h>
00028 #include <gnuradio/blocks/float_to_complex.h>
00029 #include <gnuradio/blocks/float_to_short.h>
00030 #include <gnuradio/gr_complex.h>
00031 #ifdef GR_GREATER_38
00032 #include <gnuradio/filter/fir_filter_blk.h>
00033 #else
00034 #include <gnuradio/filter/fir_filter_ccf.h>
00035 #include <gnuradio/filter/fir_filter_fff.h>
00036 #endif
00037 #include <cmath>
00038 #include <string>
00039 #include <vector>
00040
00041 /** \addtogroup Input_Filter Input Filter
00042  * Classes for input signal filtering
00043  * \{ */
00044 /** \addtogroup Input_filter_adapters input_filter_adapters
00045  * Classes that wrap GNU Radio input filters with a GNSSBlockInterface
00046  * \{ */
00047
00048
00049 class ConfigurationInterface;
00050
00051 /*!
00052  * \brief This class adapts a GNU Radio gr_fir_filter designed with pm_remez
00053  *
00054  * See Parks-McClellan FIR filter design,
00055  * https://en.wikipedia.org/wiki/Parks-McClellan\_filter\_design\_algorithm
00056  * Calculates the optimal (in the Chebyshev/minimax sense) FIR filter impulse response
00057  * given a set of band edges, the desired response on those bands, and the weight given
00058  * to the error in those bands.
00059  */
00059 class FirFilter : public GNSSBlockInterface
00060 {
00061 public:
00062     ///! Constructor
00063     FirFilter(const ConfigurationInterface* configuration,
00064              std::string role,
00065              unsigned int in_streams,
00066              unsigned int out_streams);
00067
00068     ///! Destructor
00069     ~FirFilter() = default;
00070
00071     inline std::string role() override
00072     {
00073         return role_;
00074     }
00075
00076     ///! Returns "Fir_Filter"
00077     inline std::string implementation() override
00078     {
00079         return "Fir_Filter";
00080     }
00081
00082     inline size_t item_size() override

```

```

00083     {
00084         return item_size_;
00085     }
00086
00087     void connect(gr::top_block_sptr top_block) override;
00088     void disconnect(gr::top_block_sptr top_block) override;
00089     gr::basic_block_sptr get_left_block() override;
00090     gr::basic_block_sptr get_right_block() override;
00091
00092 private:
00093     void init();
00094
00095     gr::filter::fir_filter_ccf::sptr fir_filter_ccf_;
00096     gr::filter::fir_filter_fff::sptr fir_filter_fff_1_;
00097     gr::filter::fir_filter_fff::sptr fir_filter_fff_2_;
00098     gr::blocks::float_to_complex::sptr float_to_complex_;
00099     gr::blocks::float_to_short::sptr float_to_short_1_;
00100     gr::blocks::float_to_short::sptr float_to_short_2_;
00101     short_x2_to_cshort_sptr short_x2_to_cshort_;
00102     complex_byte_to_float_x2_sptr cbyte_to_float_x2_;
00103     byte_x2_to_complex_byte_sptr char_x2_cbyte_;
00104     cshort_to_float_x2_sptr cshort_to_float_x2_;
00105     gr::blocks::float_to_char::sptr float_to_char_1_;
00106     gr::blocks::float_to_char::sptr float_to_char_2_;
00107     gr::blocks::file_sink::sptr file_sink_;
00108     const ConfigurationInterface* config_;
00109     std::vector<float> taps_;
00110     std::string dump_filename_;
00111     std::string input_item_type_;
00112     std::string output_item_type_;
00113     std::string taps_item_type_;
00114     std::string role_;
00115     size_t item_size_;
00116     unsigned int in_streams_;
00117     unsigned int out_streams_;
00118     bool dump_;
00119 };
00120
00121
00122 /** \} */
00123 /** \} */
00124 #endif // GNSS_SDR_FIR_FILTER_H

```

13.127 freq_xlating_fir_filter.h File Reference

Adapts a gnuradio gr_freq_xlating_fir_filter designed with gr_remez.

```

#include "complex_float_to_complex_byte.h"
#include "gnss_block_interface.h"
#include "short_x2_to_cshort.h"
#include <gnuradio/filter/freq_xlating_fir_filter_ccf.h>
#include <gnuradio/filter/freq_xlating_fir_filter_fcf.h>
#include <gnuradio/filter/freq_xlating_fir_filter_scf.h>
#include <gnuradio/blocks/char_to_short.h>
#include <gnuradio/blocks/complex_to_float.h>
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/float_to_short.h>
#include <string>
#include <vector>

```

Classes

- class [FreqXlatingFirFilter](#)

This class adapts a gnuradio gr_freq_xlating_fir_filter designed with pm_remez.

13.127.1 Detailed Description

Adapts a gnuradio gr_freq_xlating_fir_filter designed with gr_remez.

Author

Luis Esteve, 2012. luis(at)epsilon-formacion.com

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Definition in file [freq_xlating_fir_filter.h](#).

13.128 freq_xlating_fir_filter.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file freq_xlating_fir_filter.h
00003  * \brief Adapts a gnuradio gr_freq_xlating_fir_filter designed with gr_remez
00004  * \author Luis Esteve, 2012. luis(at)epsilon-formacion.com
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_FREQ_XLATING_FIR_FILTER_H
00019 #define GNSS_SDR_FREQ_XLATING_FIR_FILTER_H
00020
00021 #include "complex_float_to_complex_byte.h"
00022 #include "gnss_block_interface.h"
00023 #include "short_x2_to_cshort.h"
00024 #ifdef GR_GREATER_38
00025 #include <gnuradio/filter/freq_xlating_fir_filter.h>
00026 #else
00027 #include <gnuradio/filter/freq_xlating_fir_filter_ccf.h>
00028 #include <gnuradio/filter/freq_xlating_fir_filter_fcf.h>
00029 #include <gnuradio/filter/freq_xlating_fir_filter_scf.h>
00030 #endif
00031 #include <gnuradio/blocks/char_to_short.h>
00032 #include <gnuradio/blocks/complex_to_float.h>
00033 #include <gnuradio/blocks/file_sink.h>
00034 #include <gnuradio/blocks/float_to_short.h>
00035 #include <string>
00036 #include <vector>
00037
00038 /** \addtogroup Input_Filter
00039  * \{ */
00040 /** \addtogroup Input_filter_adapters
00041  * \{ */
00042
00043
00044 class ConfigurationInterface;
00045
00046 /*!
00047  * \brief This class adapts a gnuradio gr_freq_xlating_fir_filter designed with pm_remez
00048  *
00049  * Construct a FIR filter with the given taps and a composite frequency
00050  * translation that shifts intermediate_freq_ down to zero Hz. The frequency
00051  * translation logically comes before the filtering operation.
00052  *
00053  * See Parks-McClellan FIR filter design,
00054  * https://en.wikipedia.org/wiki/Parks-McClellan_filter_design_algorithm
00055  * Calculates the optimal (in the Chebyshev/minimax sense) FIR filter impulse response
00056  * given a set of band edges, the desired response on those bands, and the weight given
00057  * to the error in those bands.
00058  */
00058 class FreqXlatingFirFilter : public GNSSBlockInterface
00059 {
00060 public:
00061     FreqXlatingFirFilter(const ConfigurationInterface* configuration,
00062         std::string role, unsigned int in_streams,
00063         unsigned int out_streams);
00064
00065     ~FreqXlatingFirFilter() = default;
00066
00067     inline std::string role() override
00068     {
00069         return role_;
00070     }
00071

```

```

00072     //!< Returns "Freq_Xlating_Fir_Filter"
00073     inline std::string implementation() override
00074     {
00075         return "Freq_Xlating_Fir_Filter";
00076     }
00077
00078     inline size_t item_size() override
00079     {
00080         return input_size_;
00081     }
00082
00083     void connect(gr::top_block_sptr top_block) override;
00084     void disconnect(gr::top_block_sptr top_block) override;
00085     gr::basic_block_sptr get_left_block() override;
00086     gr::basic_block_sptr get_right_block() override;
00087
00088 private:
00089     gr::filter::freq_xlating_fir_filter_ccf::sptr freq_xlating_fir_filter_ccf_;
00090     gr::filter::freq_xlating_fir_filter_fcf::sptr freq_xlating_fir_filter_fcf_;
00091     gr::filter::freq_xlating_fir_filter_scf::sptr freq_xlating_fir_filter_scf_;
00092     gr::blocks::complex_to_float::sptr complex_to_float_;
00093     gr::blocks::char_to_short::sptr gr_char_to_short_;
00094     gr::blocks::float_to_short::sptr float_to_short_1_;
00095     gr::blocks::float_to_short::sptr float_to_short_2_;
00096     short_x2_to_cshort_sptr short_x2_to_cshort_;
00097     complex_float_to_complex_byte_sptr complex_to_complex_byte_;
00098     gr::blocks::file_sink::sptr file_sink_;
00099     std::vector<float> taps_;
00100     std::string dump_filename_;
00101     std::string input_item_type_;
00102     std::string output_item_type_;
00103     std::string taps_item_type_;
00104     std::string role_;
00105     size_t input_size_;
00106     double intermediate_freq_;
00107     double sampling_freq_;
00108     int decimation_factor_;
00109     unsigned int in_streams_;
00110     unsigned int out_streams_;
00111     bool dump_;
00112 };
00113
00114
00115 /** \} */
00116 /** \} */
00117 #endif // GNSS_SDR_FREQ_XLATING_FIR_FILTER_H

```

13.129 notch_filter.h File Reference

Adapter of a multistate [Notch](#) filter.

```

#include "gnss_block_interface.h"
#include "notch_cc.h"
#include <gnuradio/blocks/file_sink.h>
#include <string>
#include <vector>

```

Classes

- class [NotchFilter](#)

13.129.1 Detailed Description

Adapter of a multistate [Notch](#) filter.

Author

Antonio Ramos, 2017. antonio.ramosdet(at)gmail.com

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 Definition in file [notch_filter.h](#).

13.130 notch_filter.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file notch_filter.h
00003  * \brief Adapter of a multistate Notch filter
00004  * \author Antonio Ramos, 2017. antonio.ramosdet(at)gmail.com
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_NOTCH_FILTER_H
00019 #define GNSS_SDR_NOTCH_FILTER_H
00020
00021 #include "gnss_block_interface.h"
00022 #include "notch_cc.h"
00023 #include <gnuradio/blocks/file_sink.h>
00024 #include <string>
00025 #include <vector>
00026
00027 /** \addtogroup Input_Filter
00028  * \{ */
00029 /** \addtogroup Input_filter_adapters
00030  * \{ */
00031
00032
00033 class ConfigurationInterface;
00034
00035 class NotchFilter : public GNSSBlockInterface
00036 {
00037 public:
00038     NotchFilter(const ConfigurationInterface* configuration,
00039                 const std::string& role, unsigned int in_streams,
00040                 unsigned int out_streams);
00041
00042     ~NotchFilter() = default;
00043
00044     std::string role()
00045     {
00046         return role_;
00047     }
00048
00049     //! Returns "Notch_Filter"
00050     std::string implementation()
00051     {
00052         return "Notch_Filter";
00053     }
00054
00055     size_t item_size()
00056     {
00057         return item_size_;
00058     }
00059
00060     void connect(gr::top_block_sptr top_block);
00061     void disconnect(gr::top_block_sptr top_block);
00062     gr::basic_block_sptr get_left_block();
00063     gr::basic_block_sptr get_right_block();
00064
00065 private:
00066     notch_sptr notch_filter_;
00067     gr::blocks::file_sink::sptr file_sink_;
00068     std::string dump_filename_;
00069     std::string role_;
00070     std::string item_type_;
00071     size_t item_size_;
00072     unsigned int in_streams_;
00073     unsigned int out_streams_;
00074     bool dump_;
00075 };
00076
00077
00078 /** \} */
00079 /** \} */
00080 #endif // GNSS_SDR_NOTCH_FILTER_H

```

13.131 notch_filter_lite.h File Reference

Adapts a light version of a multistate notch filter.

```
#include "gnss_block_interface.h"
#include "notch_lite_cc.h"
#include <gnuradio/blocks/file_sink.h>
#include <string>
#include <vector>
```

Classes

- class [NotchFilterLite](#)

13.131.1 Detailed Description

Adapts a light version of a multistate notch filter.

Author

Antonio Ramos, 2017. antonio.ramosdet(at)gmail.com

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 Definition in file [notch_filter_lite.h](#).

13.132 notch_filter_lite.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file notch_filter_lite.h
00003  * \brief Adapts a light version of a multistate notch filter
00004  * \author Antonio Ramos, 2017. antonio.ramosdet(at)gmail.com
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_NOTCH_FILTER_LITE_H
00019 #define GNSS_SDR_NOTCH_FILTER_LITE_H
00020
00021 #include "gnss_block_interface.h"
00022 #include "notch_lite_cc.h"
00023 #include <gnuradio/blocks/file_sink.h>
00024 #include <string>
00025 #include <vector>
00026
00027 /** \addtogroup Input_Filter
00028  * \{ */
00029 /** \addtogroup Input_filter_adapters
00030  * \{ */
00031
00032
00033 class ConfigurationInterface;
00034
00035 class NotchFilterLite : public GNSSBlockInterface
00036 {
00037 public:
00038     NotchFilterLite(const ConfigurationInterface* configuration,
00039                     const std::string& role, unsigned int in_streams,
00040                     unsigned int out_streams);
00041
00042     ~NotchFilterLite() = default;
00043
00044     std::string role()
00045     {
```

```

00046         return role_;
00047     }
00048
00049     //!< Returns "Notch_Filter_Lite"
00050     std::string implementation()
00051     {
00052         return "Notch_Filter_Lite";
00053     }
00054
00055     size_t item_size()
00056     {
00057         return item_size_;
00058     }
00059
00060     void connect(gr::top_block_sptr top_block);
00061     void disconnect(gr::top_block_sptr top_block);
00062     gr::basic_block_sptr get_left_block();
00063     gr::basic_block_sptr get_right_block();
00064
00065 private:
00066     notch_lite_sptr notch_filter_lite_;
00067     gr::blocks::file_sink::sptr file_sink_;
00068     std::string dump_filename_;
00069     std::string role_;
00070     std::string item_type_;
00071     size_t item_size_;
00072     unsigned int in_streams_;
00073     unsigned int out_streams_;
00074     bool dump_;
00075 };
00076
00077
00078 /** \} */
00079 /** \} */
00080 #endif // GNSS_SDR_NOTCH_FILTER_LITE_H

```

13.133 pulse_blanking_filter.h File Reference

Instantiates the GNSS-SDR pulse blanking filter.

```

#include "gnss_block_interface.h"
#include "pulse_blanking_cc.h"
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/filter/freq_xlating_fir_filter_ccf.h>
#include <string>

```

Classes

- class [PulseBlankingFilter](#)

13.133.1 Detailed Description

Instantiates the GNSS-SDR pulse blanking filter.

Author

Javier Arribas 2017 Antonio Ramos 2017

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 Definition in file [pulse_blanking_filter.h](#).

13.134 pulse_blanking_filter.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file pulse_blanking_filter.h
00003  * \brief Instantiates the GNSS-SDR pulse blanking filter
00004  * \author Javier Arribas 2017
00005  *          Antonio Ramos 2017
00006  *
00007  * -----

```

```

00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_PULSE_BLANKING_FILTER_H
00019 #define GNSS_SDR_PULSE_BLANKING_FILTER_H
00020
00021 #include "gnss_block_interface.h"
00022 #include "pulse_blanking_cc.h"
00023 #include <gnuradio/blocks/file_sink.h>
00024 #ifdef GR_GREATER_38
00025 #include <gnuradio/filter/freq_xlating_fir_filter.h>
00026 #else
00027 #include <gnuradio/filter/freq_xlating_fir_filter_ccf.h>
00028 #endif
00029 #include <string>
00030
00031 /** \addtogroup Input_Filter
00032  * \{ */
00033 /** \addtogroup Input_filter_adapters
00034  * \{ */
00035
00036
00037 class ConfigurationInterface;
00038
00039 class PulseBlankingFilter : public GNSSBlockInterface
00040 {
00041 public:
00042     PulseBlankingFilter(const ConfigurationInterface* configuration,
00043         std::string role, unsigned int in_streams,
00044         unsigned int out_streams);
00045
00046     ~PulseBlankingFilter() = default;
00047
00048     inline std::string role() override
00049     {
00050         return role_;
00051     }
00052
00053     //! Returns "Pulse_Blanking_Filter"
00054     inline std::string implementation() override
00055     {
00056         return "Pulse_Blanking_Filter";
00057     }
00058
00059     inline size_t item_size() override
00060     {
00061         return input_size_;
00062     }
00063
00064     void connect(gr::top_block_sptr top_block) override;
00065     void disconnect(gr::top_block_sptr top_block) override;
00066     gr::basic_block_sptr get_left_block() override;
00067     gr::basic_block_sptr get_right_block() override;
00068
00069 private:
00070     pulse_blanking_cc_sptr pulse_blanking_cc_;
00071     gr::filter::freq_xlating_fir_filter_ccf::sptr freq_xlating_;
00072     gr::blocks::file_sink_sptr file_sink_;
00073     std::string dump_filename_;
00074     std::string item_type_;
00075     std::string role_;
00076     size_t input_size_;
00077     unsigned int in_streams_;
00078     unsigned int out_streams_;
00079     bool dump_;
00080     bool xlat_;
00081 };
00082
00083
00084 /** \} */
00085 /** \} */
00086 #endif // GNSS_SDR_PULSE_BLANKING_FILTER_H

```

13.135 beamformer.h File Reference

Simple spatial filter using RAW array input and beamforming coefficients.

```
#include "gnss_block_interface.h"
#include <gnuradio/sync_block.h>
#include <vector>
```

Classes

- class [beamformer](#)

This class implements a real-time software-defined spatial filter using the CTTC GNSS experimental antenna array input and a set of dynamically reloadable weights.

Typedefs

- using [beamformer_sptr](#) = [gnss_shared_ptr](#)<[beamformer](#)>

Functions

- [beamformer_sptr make_beamformer_sptr](#) ()

Variables

- const int [GNSS_SDR_BEAMFORMER_CHANNELS](#) = 8

13.135.1 Detailed Description

Simple spatial filter using RAW array input and beamforming coefficients.

Author

Javier Arribas jarribas (at) cttc.es

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 Definition in file [beamformer.h](#).

13.136 beamformer.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file beamformer.h
00003  *
00004  * \brief Simple spatial filter using RAW array input and beamforming coefficients
00005  * \author Javier Arribas jarribas (at) cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
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00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_BEAMFORMER_H
00019 #define GNSS_SDR_BEAMFORMER_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_block.h>
00023 #include <vector>
00024
00025 /** \addtogroup Input_Filter
00026  * \{ */
00027 /** \addtogroup Input_filter_gnuradio_blocks
00028  * \{ */
00029
00030
00031 class beamformer;
00032
```

```

00033 using beamformer_sptr = gnss_shared_ptr<beamformer>;
00034 beamformer_sptr make_beamformer_sptr();
00036
00037 const int GNSS_SDR_BEAMFORMER_CHANNELS = 8;
00038
00039 /*!
00040 * \brief This class implements a real-time software-defined spatial filter using the CTTC GNSS
00041 * experimental antenna array input and a set of dynamically reloadable weights
00042 */
00042 class beamformer : public gr::sync_block
00043 {
00044 public:
00045     ~beamformer() = default;
00046     int work(int noutput_items, gr_vector_const_void_star &input_items,
00047             gr_vector_void_star &output_items);
00048 private:
00049     friend beamformer_sptr make_beamformer_sptr();
00050     beamformer();
00051     std::vector<gr_complex> weight_vector = std::vector<gr_complex>(GNSS_SDR_BEAMFORMER_CHANNELS,
00052                             gr_complex(1.0, 0.0));
00053 };
00054
00055
00056 /** \} */
00057 /** \} */
00058 #endif // GNSS_SDR_BEAMFORMER_H

```

13.137 notch_cc.h File Reference

Implements a notch filter algorithm.

```

#include "gnss_block_interface.h"
#include "gnss_sdr_fft.h"
#include <gnuradio/block.h>
#include <volk_gnssssdr/volk_gnssssdr_alloc.h>
#include <cstdint>
#include <memory>

```

Classes

- class [Notch](#)

This class implements a real-time software-defined multi state notch filter.

Typedefs

- using [notch_sptr](#) = gnss_shared_ptr<[Notch](#)>

Functions

- notch_sptr **make_notch_filter** (float pfa, float p_c_factor, int32_t length, int32_t n_segments_est, int32_t n_segments_reset)

13.137.1 Detailed Description

Implements a notch filter algorithm.

Author

Antonio Ramos (antonio.ramosdet(at)gmail.com)

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Definition in file [notch_cc.h](#).

13.138 notch_cc.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file notch_cc.h
00003  * \brief Implements a notch filter algorithm
00004  * \author Antonio Ramos (antonio.amosdet(at)gmail.com)
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  *
00014  * -----
00015  *
00016  */
00017
00018 #ifndef GNSS_SDR_NOTCH_CC_H
00019 #define GNSS_SDR_NOTCH_CC_H
00020
00021 #include "gnss_block_interface.h"
00022 #include "gnss_sdr_fft.h"
00023 #include <gnuradio/block.h>
00024 #include <volk_gnssssdr/volk_gnssssdr_alloc.h> // for volk_gnssssdr::vector
00025 #include <stdint>
00026 #include <memory>
00027
00028 /** \addtogroup Input_Filter
00029  * \{ */
00030 /** \addtogroup Input_filter_gnuradio_blocks
00031  * \{ */
00032
00033
00034 class Notch;
00035
00036 using notch_sptr = gnss_shared_ptr<Notch>;
00037
00038 notch_sptr make_notch_filter(
00039     float pfa,
00040     float p_c_factor,
00041     int32_t length,
00042     int32_t n_segments_est,
00043     int32_t n_segments_reset);
00044
00045 /*!
00046  * \brief This class implements a real-time software-defined multi state notch filter
00047  */
00048 class Notch : public gr::block
00049 {
00050 public:
00051     ~Notch() = default;
00052
00053     int general_work(int noutput_items, gr_vector_int &ninput_items,
00054         gr_vector_const_void_star &input_items,
00055         gr_vector_void_star &output_items);
00056
00057 private:
00058     friend notch_sptr make_notch_filter(float pfa, float p_c_factor, int32_t length, int32_t
00059         n_segments_est, int32_t n_segments_reset);
00059     Notch(float pfa, float p_c_factor, int32_t length, int32_t n_segments_est, int32_t
00060         n_segments_reset);
00061
00062     std::unique_ptr<gnss_fft_complex_fwd> d_fft_;
00063     volk_gnssssdr::vector<gr_complex> c_samples_;
00064     volk_gnssssdr::vector<float> angle_;
00065     volk_gnssssdr::vector<float> power_spect_;
00066     gr_complex last_out_;
00067     gr_complex z_0_;
00068     gr_complex p_c_factor_;
00069     float pfa_;
00070     float noise_pow_est_;
00071     float thres_;
00072     int32_t length_;
00073     int32_t n_deg_fred_;
00074     uint32_t n_segments_;
00075     uint32_t n_segments_est_;
00076     uint32_t n_segments_reset_;
00077     bool filter_state_;
00078 };
00079
00080 /** \} */
00081 /** \} */

```

```
00082 #endif // GNSS_SDR_NOTCH_CC_H
```

13.139 notch_lite_cc.h File Reference

Implements a notch filter light algorithm.

```
#include "gnss_block_interface.h"
#include "gnss_sdr_fft.h"
#include <gnuradio/block.h>
#include <volk_gnssssdr/volk_gnssssdr_alloc.h>
#include <cstdint>
#include <memory>
```

Classes

- class [NotchLite](#)

This class implements a real-time software-defined multi state notch filter light version.

Typedefs

- using [notch_lite_sptr](#) = [gnss_shared_ptr](#)<[NotchLite](#)>

Functions

- [notch_lite_sptr](#) **make_notch_filter_lite** (float p_c_factor, float pfa, int32_t length, int32_t n_segments_est, int32_t n_segments_reset, int32_t n_segments_coeff)

13.139.1 Detailed Description

Implements a notch filter light algorithm.

Author

Antonio Ramos (antonio.ramosdet(at)gmail.com)

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 Definition in file [notch_lite_cc.h](#).

13.140 notch_lite_cc.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file notch_lite_cc.h
00003  * \brief Implements a notch filter light algorithm
00004  * \author Antonio Ramos (antonio.ramosdet(at)gmail.com)
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  *
00014  * -----
00015  *
00016  */
00017
00018 #ifndef GNSS_SDR_NOTCH_LITE_CC_H
00019 #define GNSS_SDR_NOTCH_LITE_CC_H
00020
00021 #include "gnss_block_interface.h"
00022 #include "gnss_sdr_fft.h"
00023 #include <gnuradio/block.h>
00024 #include <volk_gnssssdr/volk_gnssssdr_alloc.h> // for volk_gnssssdr::vector
00025 #include <cstdint>
```

```

00026 #include <memory>
00027
00028 /** \addtogroup Input_Filter
00029 * \{ */
00030 /** \addtogroup Input_filter_gnuradio_blocks
00031 * \{ */
00032
00033
00034 class NotchLite;
00035
00036 using notch_lite_sptr = gnss_shared_ptr<NotchLite>;
00037
00038 notch_lite_sptr make_notch_filter_lite(
00039     float p_c_factor,
00040     float pfa,
00041     int32_t length,
00042     int32_t n_segments_est,
00043     int32_t n_segments_reset,
00044     int32_t n_segments_coeff);
00045
00046 /*!
00047 * \brief This class implements a real-time software-defined multi state notch filter light version
00048 */
00049 class NotchLite : public gr::block
00050 {
00051 public:
00052     ~NotchLite() = default;
00053
00054     int general_work(int noutput_items, gr_vector_int &ninput_items,
00055                     gr_vector_const_void_star &input_items,
00056                     gr_vector_void_star &output_items);
00057 private:
00058     friend notch_lite_sptr make_notch_filter_lite(float p_c_factor, float pfa, int32_t length, int32_t
00059 n_segments_est, int32_t n_segments_reset, int32_t n_segments_coeff);
00060     NotchLite(float p_c_factor, float pfa, int32_t length, int32_t n_segments_est, int32_t
00061 n_segments_reset, int32_t n_segments_coeff);
00062
00063     std::unique_ptr<gnss_fft_complex_fwd> d_fft_;
00064     volk_gnss_sdr::vector<float> power_spect_;
00065     gr_complex last_out_;
00066     gr_complex z_0_;
00067     gr_complex p_c_factor_;
00068     gr_complex c_samples1_;
00069     gr_complex c_samples2_;
00070     float pfa_;
00071     float thres_;
00072     float noise_pow_est_;
00073     float angle1_;
00074     float angle2_;
00075     int32_t length_;
00076     int32_t n_segments_;
00077     int32_t n_segments_est_;
00078     int32_t n_segments_reset_;
00079     int32_t n_segments_coeff_reset_;
00080     int32_t n_segments_coeff_;
00081     int32_t n_deg_fred_;
00082     bool filter_state_;
00083 };
00084
00085 /** \} */
00086 /** \} */
00087 #endif // GNSS_SDR_NOTCH_LITE_CC_H

```

13.141 pulse_blanking_cc.h File Reference

Implements a pulse blanking algorithm.

```

#include "gnss_block_interface.h"
#include <gnuradio/block.h>
#include <volk_gnss_sdr/volk_gnss_sdr_alloc.h>
#include <stdint>

```

Classes

- class [pulse_blanking_cc](#)

Typedefs

- using [pulse_blanking_cc_sptr](#) = gnss_shared_ptr<[pulse_blanking_cc](#)>

Functions

- [pulse_blanking_cc_sptr](#) **make_pulse_blanking_cc** (float pfa, int32_t length, int32_t n_segments_est, int32_t n_segments_reset)

13.141.1 Detailed Description

Implements a pulse blanking algorithm.

Author

Javier Arribas (jarribas(at)cttc.es) Antonio Ramos (antonio.ramosdet(at)gmail.com)

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 Definition in file [pulse_blanking_cc.h](#).

13.142 pulse_blanking_cc.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file pulse_blanking_cc.h
00003  * \brief Implements a pulse blanking algorithm
00004  * \author Javier Arribas (jarribas(at)cttc.es)
00005  *         Antonio Ramos (antonio.ramosdet(at)gmail.com)
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00011  *
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00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  *
00017  */
00018
00019 #ifndef GNSS_SDR_PULSE_BLANKING_CC_H
00020 #define GNSS_SDR_PULSE_BLANKING_CC_H
00021
00022 #include "gnss_block_interface.h"
00023 #include <gnuradio/block.h>
00024 #include <volk_gnssdr/volk_gnssdr_alloc.h> // for volk_gnssdr::vector
00025 #include <cstdint>
00026
00027 /** \addtogroup Input_Filter
00028  * \{ */
00029 /** \addtogroup Input_filter_gnuradio_blocks input_filter_gr_blocks
00030  * GNU Radio blocks implementing input filters,
00031  * \{ */
00032
00033
00034 class pulse_blanking_cc;
00035
00036 using pulse_blanking_cc_sptr = gnss_shared_ptr<pulse_blanking_cc>;
00037
00038 pulse_blanking_cc_sptr make_pulse_blanking_cc(
00039     float pfa,
00040     int32_t length,
00041     int32_t n_segments_est,
00042     int32_t n_segments_reset);
00043
00044 class pulse_blanking_cc : public gr::block
00045 {
00046 public:
00047     ~pulse_blanking_cc() = default;
00048
00049     int general_work(int noutput_items __attribute__((unused)), gr_vector_int &ninput_items
00050         __attribute__((unused)),
00051         gr_vector_const_void_star &input_items, gr_vector_void_star &output_items);
00052 private:

```

```

00053     friend pulse_blanking_cc_sptr make_pulse_blanking_cc(float pfa, int32_t length, int32_t
n_segments_est, int32_t n_segments_reset);
00054     pulse_blanking_cc(float pfa, int32_t length, int32_t n_segments_est, int32_t n_segments_reset);
00055     volk_gnssdr::vector<gr_complex> zeros_;
00056     float noise_power_estimation_;
00057     float thres_;
00058     float pfa_;
00059     int32_t length_;
00060     int32_t n_segments_;
00061     int32_t n_segments_est_;
00062     int32_t n_segments_reset_;
00063     int32_t n_deg_fred_;
00064     bool last_filtered_;
00065 };
00066
00067
00068 /** \} */
00069 /** \} */
00070 #endif // GNSS_SDR_PULSE_BLANKING_CC_H

```

13.143 beidou_b1i_signal_replica.h File Reference

This file implements various functions for BeiDou B1I signal replica generation.

```

#include <complex>
#include <cstdint>
#include <gsl-lite/gsl-lite.hpp>

```

Functions

- void [beidou_b1i_code_gen_int](#) (own::span< int32_t > dest, int32_t prn, uint32_t chip_shift)
Generates int32_t GPS L1 C/A code for the desired SV ID and code shift.
- void [beidou_b1i_code_gen_float](#) (own::span< float > dest, int32_t prn, uint32_t chip_shift)
Generates float GPS L1 C/A code for the desired SV ID and code shift.
- void [beidou_b1i_code_gen_complex](#) (own::span< std::complex< float > > dest, int32_t prn, uint32_t chip_shift)
Generates complex GPS L1 C/A code for the desired SV ID and code shift.
- void [beidou_b1i_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift)
Generates complex GPS L1 C/A code for the desired SV ID and code shift, and sampled to specific sampling frequency.

13.143.1 Detailed Description

This file implements various functions for BeiDou B1I signal replica generation.

Author

Sergi Segura, 2018. [sergi.segura.munoz\(at\)gmail.com](mailto:sergi.segura.munoz(at)gmail.com)

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Definition in file [beidou_b1i_signal_replica.h](#).

13.144 beidou_b1i_signal_replica.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file beidou_b1i_signal_replica.h
00003  * \brief This file implements various functions for BeiDou B1I signal replica
00004  * generation
00005  * \author Sergi Segura, 2018. sergi.segura.munoz\(at\)gmail.com
00006  *
00007  *
00008  * -----
00009  *

```

```

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00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_BEIDOU_B1I_SIGNAL_REPLICA_H
00020 #define GNSS_SDR_BEIDOU_B1I_SIGNAL_REPLICA_H
00021
00022 #include <complex>
00023 #include <stdint>
00024 #if HAS_STD_SPAN
00025 #include <span>
00026 namespace own = std;
00027 #else
00028 #include <gsl-lite/gsl-lite.hpp>
00029 namespace own = gsl_lite;
00030 #endif
00031
00032 /** \addtogroup Algorithms_Library Algorithms Common Library
00033  * Common utilities for the GNSS receiver.
00034  * \{ */
00035 /** \addtogroup Algorithm_libs algorithms_libs
00036  * Common utilities for GNSS algorithms.
00037  * \{ */
00038
00039
00040 //! Generates int32_t GPS L1 C/A code for the desired SV ID and code shift
00041 void beidou_b1i_code_gen_int(own::span<int32_t> dest, int32_t prn, uint32_t chip_shift);
00042
00043 //! Generates float GPS L1 C/A code for the desired SV ID and code shift
00044 void beidou_b1i_code_gen_float(own::span<float> dest, int32_t prn, uint32_t chip_shift);
00045
00046 //! Generates complex GPS L1 C/A code for the desired SV ID and code shift
00047 void beidou_b1i_code_gen_complex(own::span<std::complex<float>> dest, int32_t prn, uint32_t
chip_shift);
00048
00049 //! Generates complex GPS L1 C/A code for the desired SV ID and code shift, and sampled to specific
sampling frequency
00050 void beidou_b1i_code_gen_complex_sampled(own::span<std::complex<float>> dest, uint32_t prn, int32_t
sampling_freq, uint32_t chip_shift);
00051
00052
00053 /** \} */
00054 /** \} */
00055 #endif // GNSS_SDR_BEIDOU_B1I_SIGNAL_REPLICA_H

```

13.145 beidou_b3i_signal_replica.h File Reference

This file implements various functions for BeiDou B3I signal replica generation.

```

#include <complex>
#include <stdint>
#include <gsl-lite/gsl-lite.hpp>

```

Functions

- void `beidou_b3i_code_gen_int` (own::span< int > dest, int32_t prn, uint32_t chip_shift)
Generates int BeiDou B3I code for the desired SV ID and code shift.
- void `beidou_b3i_code_gen_float` (own::span< float > dest, int32_t prn, uint32_t chip_shift)
Generates float BeiDou B3I code for the desired SV ID and code shift.
- void `beidou_b3i_code_gen_complex` (own::span< std::complex< float > > dest, int32_t prn, uint32_t chip↵_shift)
Generates complex BeiDou B3I code for the desired SV ID and code shift.
- void `beidou_b3i_code_gen_complex_sampled` (own::span< std::complex< float > > dest, uint32_t prn, int sampling_freq, uint32_t chip_shift)
Generates complex BeiDou B3I code for the desired SV ID and code shift, and sampled to specific sampling frequency.

13.145.1 Detailed Description

This file implements various functions for BeiDou B3I signal replica generation.

Author

Damian Miralles, 2019. dmiralles2009@gmail.com

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Definition in file [beidou_b3i_signal_replica.h](#).

13.146 beidou_b3i_signal_replica.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file beidou_b3i_signal_replica.h
00003  * \brief This file implements various functions for BeiDou B3I signal replica
00004  * generation
00005  * \author Damian Miralles, 2019. dmiralles2009@gmail.com
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_BEIDOU_B3I_SIGNAL_REPLICA_H
00020 #define GNSS_SDR_BEIDOU_B3I_SIGNAL_REPLICA_H
00021
00022 #include <complex>
00023 #include <stdint>
00024 #if HAS_STD_SPAN
00025 #include <span>
00026 namespace own = std;
00027 #else
00028 #include <gsl-lite/gsl-lite.hpp>
00029 namespace own = gsl_lite;
00030 #endif
00031
00032 /** \addtogroup Algorithms_Library
00033  * \{ */
00034 /** \addtogroup Algorithm_libs algorithms_libs
00035  * \{ */
00036
00037
00038 /*! Generates int BeiDou B3I code for the desired SV ID and code shift
00039 void beidou_b3i_code_gen_int(own::span<int> dest, int32_t prn, uint32_t chip_shift);
00040
00041 /*! Generates float BeiDou B3I code for the desired SV ID and code shift
00042 void beidou_b3i_code_gen_float(own::span<float> dest, int32_t prn, uint32_t chip_shift);
00043
00044 /*! Generates complex BeiDou B3I code for the desired SV ID and code shift
00045 void beidou_b3i_code_gen_complex(own::span<std::complex<float> dest, int32_t prn, uint32_t
chip_shift);
00046
00047 /*! Generates complex BeiDou B3I code for the desired SV ID and code shift, and sampled to specific
sampling frequency
00048 void beidou_b3i_code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int
sampling_freq, uint32_t chip_shift);
00049
00050
00051 /** \} */
00052 /** \} */
00053 #endif // GNSS_SDR_BEIDOU_B3I_SIGNAL_REPLICA_H
```

13.147 byte_x2_to_complex_byte.h File Reference

Adapts two signed char streams into a std::complex<signed char> stream.

```
#include "gnss_block_interface.h"
#include <gnuradio/sync_block.h>
```

```
#include <gnuradio/types.h>
```

Classes

- class [byte_x2_to_complex_byte](#)

This class adapts two signed char streams into a `std::complex<signed char>` stream.

Typedefs

- using [byte_x2_to_complex_byte_sptr](#) = `gnss_shared_ptr<byte_x2_to_complex_byte>`

Functions

- `byte_x2_to_complex_byte_sptr` [make_byte_x2_to_complex_byte](#) ()

13.147.1 Detailed Description

Adapts two signed char streams into a `std::complex<signed char>` stream.

Author

Carles Fernandez Prades, [cfernandez\(at\)cttc.es](mailto:cfernandez(at)cttc.es)

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 Definition in file [byte_x2_to_complex_byte.h](#).

13.148 [byte_x2_to_complex_byte.h](#)

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file byte_x2_to_complex_byte.h
00003  * \brief Adapts two signed char streams into a std::complex<signed char> stream
00004  * \author Carles Fernandez Prades, cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_BYTE_X2_TO_COMPLEX_BYTE_H
00019 #define GNSS_SDR_BYTE_X2_TO_COMPLEX_BYTE_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_block.h>
00023 #include <gnuradio/types.h> // for gr_vector_const_void_star
00024
00025 /** \addtogroup Algorithms_Library
00026  * \{ */
00027 /** \addtogroup Algorithm_libs algorithms_libs
00028  * \{ */
00029
00030
00031 class byte_x2_to_complex_byte;
00032
00033 using byte_x2_to_complex_byte_sptr = gnss_shared_ptr<byte_x2_to_complex_byte>;
00034
00035 byte_x2_to_complex_byte_sptr make_byte_x2_to_complex_byte();
00036
00037 /*!
00038  * \brief This class adapts two signed char streams
00039  * into a std::complex<signed char> stream
00040  */
00041 class byte_x2_to_complex_byte : public gr::sync_block
00042 {
```



```

00043 public:
00044     int work(int noutput_items,
00045             gr_vector_const_void_star &input_items,
00046             gr_vector_void_star &output_items);
00047 private:
00048     friend byte_x2_to_complex_byte_sptr make_byte_x2_to_complex_byte();
00049     byte_x2_to_complex_byte();
00050 };
00051
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_BYTE_X2_TO_COMPLEX_BYTE_Hs

```

13.149 complex_byte_to_float_x2.h File Reference

Adapts a `std::complex<signed char>` stream into two 16-bits (short) streams.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_block.h>
#include <gnuradio/types.h>

```

Classes

- class [complex_byte_to_float_x2](#)

This class adapts a `std::complex<signed char>` stream into two 16-bits (short) streams.

Typedefs

- using [complex_byte_to_float_x2_sptr](#) = `gnss_shared_ptr<complex_byte_to_float_x2>`

Functions

- `complex_byte_to_float_x2_sptr make_complex_byte_to_float_x2 ()`

13.149.1 Detailed Description

Adapts a `std::complex<signed char>` stream into two 16-bits (short) streams.

Author

Carles Fernandez Prades, [cfernandez\(at\)cttc.es](mailto:cfernandez(at)cttc.es)

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 Definition in file [complex_byte_to_float_x2.h](#).

13.150 complex_byte_to_float_x2.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file complex_byte_to_float_x2.h
00003  * \brief Adapts a std::complex<signed char> stream into two 16-bits (short) streams
00004  * \author Carles Fernandez Prades, cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_COMPLEX_BYTE_TO_FLOAT_X2_H

```

```

00019 #define GNSS_SDR_COMPLEX_BYTE_TO_FLOAT_X2_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_block.h>
00023 #include <gnuradio/types.h> // for gr_vector_const_void_star
00024
00025 /** \addtogroup Algorithms_Library
00026  * \{ */
00027 /** \addtogroup Algorithm_libs algorithms_libs
00028  * \{ */
00029
00030
00031 class complex_byte_to_float_x2;
00032
00033 using complex_byte_to_float_x2_sptr = gnss_shared_ptr<complex_byte_to_float_x2>;
00034
00035 complex_byte_to_float_x2_sptr make_complex_byte_to_float_x2();
00036
00037 /*!
00038  * \brief This class adapts a std::complex<signed char> stream
00039  * into two 16-bits (short) streams
00040  */
00041 class complex_byte_to_float_x2 : public gr::sync_block
00042 {
00043 public:
00044     int work(int noutput_items,
00045             gr_vector_const_void_star &input_items,
00046             gr_vector_void_star &output_items);
00047 private:
00048     friend complex_byte_to_float_x2_sptr make_complex_byte_to_float_x2();
00049     complex_byte_to_float_x2();
00050 };
00051
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_COMPLEX_BYTE_TO_FLOAT_X2_H

```

13.151 complex_float_to_complex_byte.h File Reference

Adapts a `gr_complex` stream into a `std::complex<signed char>` stream.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_block.h>
#include <gnuradio/types.h>

```

Classes

- class [complex_float_to_complex_byte](#)

This class adapts a `gr_complex` stream into a `std::complex<signed char>` stream.

Typedefs

- using [complex_float_to_complex_byte_sptr](#) = `gnss_shared_ptr<complex_float_to_complex_byte>`

Functions

- `complex_float_to_complex_byte_sptr make_complex_float_to_complex_byte ()`

13.151.1 Detailed Description

Adapts a `gr_complex` stream into a `std::complex<signed char>` stream.

Author

Carles Fernandez Prades, cfernandez(at)cttc.es

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 Definition in file [complex_float_to_complex_byte.h](#).

13.152 complex_float_to_complex_byte.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file complex_float_to_complex_byte.h
00003  * \brief Adapts a gr_complex stream into a std::complex<signed char> stream
00004  * \author Carles Fernandez Prades, cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_COMPLEX_FLOAT_TO_COMPLEX_BYTE_H
00019 #define GNSS_SDR_COMPLEX_FLOAT_TO_COMPLEX_BYTE_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_block.h>
00023 #include <gnuradio/types.h> // for gr_vector_const_void_star
00024
00025 /** \addtogroup Algorithms_Library
00026  * \{ */
00027 /** \addtogroup Algorithm_libs algorithms_libs
00028  * \{ */
00029
00030
00031 class complex_float_to_complex_byte;
00032
00033 using complex_float_to_complex_byte_sptr = gnss_shared_ptr<complex_float_to_complex_byte>;
00034
00035 complex_float_to_complex_byte_sptr make_complex_float_to_complex_byte();
00036
00037 /*!
00038  * \brief This class adapts a gr_complex stream into a std::complex<signed char> stream
00039  */
00040 class complex_float_to_complex_byte : public gr::sync_block
00041 {
00042 public:
00043     int work(int noutput_items,
00044             gr_vector_const_void_star &input_items,
00045             gr_vector_void_star &output_items);
00046 private:
00047     friend complex_float_to_complex_byte_sptr make_complex_float_to_complex_byte();
00048     complex_float_to_complex_byte();
00049 };
00050
00051
00052
00053 /** \} */
00054 /** \} */
00055 #endif // GNSS_SDR_COMPLEX_FLOAT_TO_COMPLEX_BYTE_H

```

13.153 conjugate_cc.h File Reference

Conjugate a stream of gr_complex.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_block.h>
#include <gnuradio/types.h>

```

Classes

- class [conjugate_cc](#)

This class adapts a std::complex<short> stream into two 32-bits (float) streams.

Typedefs

- using [conjugate_cc_sptr](#) = gnss_shared_ptr<[conjugate_cc](#)>

Functions

- `conjugate_cc_sptr make_conjugate_cc ()`

13.153.1 Detailed Description

Conjugate a stream of `gr_complex`.

Author

Carles Fernandez Prades, `cfernandez(at)cttc.es`

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 Definition in file [conjugate_cc.h](#).

13.154 conjugate_cc.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file conjugate_cc.h
00003  * \brief Conjugate a stream of gr_complex
00004  * \author Carles Fernandez Prades, cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_CONJUGATE_CC_H
00019 #define GNSS_SDR_CONJUGATE_CC_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_block.h>
00023 #include <gnuradio/types.h> // for gr_vector_const_void_star
00024
00025 /** \addtogroup Algorithms_Library
00026  * \{ */
00027 /** \addtogroup Algorithm_libs algorithms_libs
00028  * \{ */
00029
00030
00031 class conjugate_cc;
00032
00033 using conjugate_cc_sptr = gnss_shared_ptr<conjugate_cc>;
00034
00035 conjugate_cc_sptr make_conjugate_cc();
00036
00037 /*!
00038  * \brief This class adapts a std::complex<short> stream
00039  * into two 32-bits (float) streams
00040  */
00041 class conjugate_cc : public gr::sync_block
00042 {
00043 public:
00044     int work(int noutput_items,
00045             gr_vector_const_void_star &input_items,
00046             gr_vector_void_star &output_items);
00047
00048 private:
00049     friend conjugate_cc_sptr make_conjugate_cc();
00050     conjugate_cc();
00051 };
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_CONJUGATE_CC_H

```

13.155 conjugate_ic.h File Reference

Conjugate a stream of `lv_8sc_t (std::complex<char>)`

```
#include "gnss_block_interface.h"
#include <gnuradio/sync_block.h>
#include <gnuradio/types.h>
```

Classes

- class [conjugate_ic](#)

This class adapts a `std::complex<short>` stream into two 32-bits (float) streams.

Typedefs

- using [conjugate_ic_sptr](#) = `gnss_shared_ptr<conjugate_ic>`

Functions

- `conjugate_ic_sptr make_conjugate_ic ()`

13.155.1 Detailed Description

Conjugate a stream of `lv_8sc_t (std::complex<char>)`

Author

Carles Fernandez Prades, [cfernandez\(at\)cttc.es](mailto:cfernandez(at)cttc.es)

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 Definition in file [conjugate_ic.h](#).

13.156 conjugate_ic.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file conjugate_ic.h
00003  * \brief Conjugate a stream of lv_8sc_t ( std::complex<char> )
00004  * \author Carles Fernandez Prades, cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_CONJUGATE_IC_H
00019 #define GNSS_SDR_CONJUGATE_IC_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_block.h>
00023 #include <gnuradio/types.h> // for gr_vector_const_void_star
00024
00025 /** \addtogroup Algorithms_Library
00026  * \{ */
00027 /** \addtogroup Algorithm_libs algorithms_libs
00028  * \{ */
00029
00030
00031 class conjugate_ic;
00032
00033 using conjugate_ic_sptr = gnss_shared_ptr<conjugate_ic>;
00034
00035 conjugate_ic_sptr make_conjugate_ic();
```

```

00036
00037 /*!
00038 * \brief This class adapts a std::complex<short> stream
00039 * into two 32-bits (float) streams
00040 */
00041 class conjugate_ic : public gr::sync_block
00042 {
00043 public:
00044     int work(int noutput_items,
00045             gr_vector_const_void_star &input_items,
00046             gr_vector_void_star &output_items);
00047
00048 private:
00049     friend conjugate_ic_sptr make_conjugate_ic();
00050     conjugate_ic();
00051 };
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_CONJUGATE_IC_H

```

13.157 conjugate_sc.h File Reference

Conjugate a stream of lv_16sc_t (std::complex<short>)

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_block.h>
#include <gnuradio/types.h>

```

Classes

- class [conjugate_sc](#)

This class adapts a std::complex<short> stream into two 32-bits (float) streams.

Typedefs

- using [conjugate_sc_sptr](#) = gnss_shared_ptr<[conjugate_sc](#)>

Functions

- [conjugate_sc_sptr make_conjugate_sc \(\)](#)

13.157.1 Detailed Description

Conjugate a stream of lv_16sc_t (std::complex<short>)

Author

Carles Fernandez Prades, cfernandez(at)cttc.es

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 Definition in file [conjugate_sc.h](#).

13.158 conjugate_sc.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file conjugate_sc.h
00003 * \brief Conjugate a stream of lv_16sc_t ( std::complex<short> )
00004 * \author Carles Fernandez Prades, cfernandez(at)cttc.es
00005 *
00006 *
00007 * -----
00008 *
00009 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010 * This file is part of GNSS-SDR.
00011 *

```

```

00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_CONJUGATE_SC_H
00019 #define GNSS_SDR_CONJUGATE_SC_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_block.h>
00023 #include <gnuradio/types.h> // for gr_vector_const_void_star
00024
00025 /** \addtogroup Algorithms_Library
00026  * \{ */
00027 /** \addtogroup Algorithm_libs algorithms_libs
00028  * \{ */
00029
00030
00031 class conjugate_sc;
00032
00033 using conjugate_sc_sptr = gnss_shared_ptr<conjugate_sc>;
00034
00035 conjugate_sc_sptr make_conjugate_sc();
00036
00037 /*!
00038  * \brief This class adapts a std::complex<short> stream
00039  * into two 32-bits (float) streams
00040  */
00041 class conjugate_sc : public gr::sync_block
00042 {
00043 public:
00044     int work(int noutput_items,
00045             gr_vector_const_void_star &input_items,
00046             gr_vector_void_star &output_items);
00047
00048 private:
00049     friend conjugate_sc_sptr make_conjugate_sc();
00050     conjugate_sc();
00051 };
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_CONJUGATE_SC_H

```

13.159 cshort_to_float_x2.h File Reference

Adapts a `std::complex<short>` stream into two float streams.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_block.h>
#include <gnuradio/types.h>

```

Classes

- class [cshort_to_float_x2](#)

This class adapts a `std::complex<short>` stream into two 32-bits (float) streams.

Typedefs

- using [cshort_to_float_x2_sptr](#) = `gnss_shared_ptr<cshort_to_float_x2>`

Functions

- `cshort_to_float_x2_sptr make_cshort_to_float_x2 ()`

13.159.1 Detailed Description

Adapts a `std::complex<short>` stream into two float streams.

Author

Carles Fernandez Prades, cfernandez(at)cttc.es

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 Definition in file [cshort_to_float_x2.h](#).

13.160 cshort_to_float_x2.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file cshort_to_float_x2.h
00003  * \brief Adapts a std::complex<short> stream into two float streams
00004  * \author Carles Fernandez Prades, cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_CSHORT_TO_FLOAT_X2_H
00019 #define GNSS_SDR_CSHORT_TO_FLOAT_X2_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_block.h>
00023 #include <gnuradio/types.h> // for gr_vector_const_void_star
00024
00025 /** \addtogroup Algorithms_Library
00026  * \{ */
00027 /** \addtogroup Algorithm_libs algorithms_libs
00028  * \{ */
00029
00030
00031 class cshort_to_float_x2;
00032
00033 using cshort_to_float_x2_sptr = gnss_shared_ptr<csshort_to_float_x2>;
00034
00035 cshort_to_float_x2_sptr make_cshort_to_float_x2();
00036
00037 /*!
00038 * \brief This class adapts a std::complex<short> stream
00039 * into two 32-bits (float) streams
00040 */
00041 class cshort_to_float_x2 : public gr::sync_block
00042 {
00043 public:
00044     int work(int noutput_items,
00045             gr_vector_const_void_star &input_items,
00046             gr_vector_void_star &output_items);
00047 private:
00048     friend cshort_to_float_x2_sptr make_cshort_to_float_x2();
00049     cshort_to_float_x2();
00050 };
00051
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_CSHORT_TO_FLOAT_X2_H

```

13.161 galileo_e1_signal_replica.h File Reference

This library implements various functions for Galileo E1 signal replica generation.

```

#include <array>
#include <complex>
#include <cstdint>
#include <gsl-lite/gsl-lite.hpp>

```


Functions

- void [galileo_e1_code_gen_sinboc11_float](#) (own::span< float > dest, const std::array< char, 3 > &signal_id, uint32_t prn)
This function generates Galileo E1 code (can select E1B or E1C sinboc).
- void [galileo_e1_code_gen_float_sampled](#) (own::span< float > dest, const std::array< char, 3 > &signal_id, bool cboc, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift, bool secondary_flag)
This function generates Galileo E1 code (can select E1B or E1C, cboc or sinboc and the sample frequency sampling←_freq).
- void [galileo_e1_code_gen_float_sampled](#) (own::span< float > dest, const std::array< char, 3 > &signal_id, bool cboc, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift)
This function generates Galileo E1 code (can select E1B or E1C, cboc or sinboc and the sample frequency sampling←_freq).
- void [galileo_e1_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, const std::array< char, 3 > &signal_id, bool cboc, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift, bool secondary_flag)
This function generates Galileo E1 code (can select E1B or E1C, cboc or sinboc and the sample frequency sampling←_freq).
- void [galileo_e1_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, const std::array< char, 3 > &signal_id, bool cboc, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift)
galileo_e1_code_gen_complex_sampled without secondary_flag for backward compatibility.

13.161.1 Detailed Description

This library implements various functions for Galileo E1 signal replica generation.

Author

Luis Esteve, 2012. luis(at)epsilon-formacion.com

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Definition in file [galileo_e1_signal_replica.h](#).

13.162 galileo_e1_signal_replica.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file galileo_e1_signal_replica.h
00003  * \brief This library implements various functions for Galileo E1 signal
00004  * replica generation
00005  * \author Luis Esteve, 2012. luis(at)epsilon-formacion.com
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GALILEO_E1_SIGNAL_REPLICA_H
00020 #define GNSS_SDR_GALILEO_E1_SIGNAL_REPLICA_H
00021
00022 #include <array>
00023 #include <complex>
00024 #include <stdint>
00025 #if HAS_STD_SPAN
00026 #include <span>
00027 namespace own = std;
00028 #else
00029 #include <gsl-lite/gsl-lite.hpp>
00030 namespace own = gsl_lite;
00031 #endif
00032
00033 /** \addtogroup Algorithms_Library
```

```

00034  * \{ */
00035  /** \addtogroup Algorithm_libs algorithms_libs
00036  * \{ */
00037
00038
00039  /*!
00040  * \brief This function generates Galileo E1 code (can select E1B or E1C sinboc).
00041  *
00042  */
00043 void galileo_e1_code_gen_sinboc11_float(own::span<float> dest, const std::array<char, 3>& signal_id,
uint32_t prn);
00044
00045 /*!
00046  * \brief This function generates Galileo E1 code (can select E1B or E1C, cboc or sinboc
00047  * and the sample frequency sampling_freq).
00048  *
00049  */
00050 void galileo_e1_code_gen_float_sampled(own::span<float> dest, const std::array<char, 3>& signal_id,
00051     bool cboc, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift,
00052     bool secondary_flag);
00053
00054 /*!
00055  * \brief This function generates Galileo E1 code (can select E1B or E1C, cboc or sinboc
00056  * and the sample frequency sampling_freq).
00057  *
00058  */
00059 void galileo_e1_code_gen_float_sampled(own::span<float> dest, const std::array<char, 3>& signal_id,
00060     bool cboc, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift);
00061
00062 /*!
00063  * \brief This function generates Galileo E1 code (can select E1B or E1C, cboc or sinboc
00064  * and the sample frequency sampling_freq).
00065  *
00066  */
00067 void galileo_e1_code_gen_complex_sampled(own::span<std::complex<float> dest, const std::array<char,
3>& signal_id,
00068     bool cboc, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift,
00069     bool secondary_flag);
00070
00071 /*!
00072  * \brief galileo_e1_code_gen_complex_sampled without secondary_flag for backward compatibility.
00073  */
00074 void galileo_e1_code_gen_complex_sampled(own::span<std::complex<float> dest, const std::array<char,
3>& signal_id,
00075     bool cboc, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift);
00076
00077
00078 /** \} */
00079 /** \} */
00080 #endif // GNSS_SDR_GALILEO_E1_SIGNAL_REPLICA_H

```

13.163 galileo_e5_signal_replica.h File Reference

This library implements various functions for Galileo E5 signal replica generation.

```

#include <array>
#include <complex>
#include <cstdint>
#include <gsl-lite/gsl-lite.hpp>

```

Functions

- void [galileo_e5_a_code_gen_complex_primary](#) (own::span< std::complex< float > > dest, int32_t prn, const std::array< char, 3 > &signal_id)
Generates Galileo E5a code at 1 sample/chip.
- void [galileo_e5_a_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, const std::array< char, 3 > &signal_id, int32_t sampling_freq, uint32_t chip_shift)
Generates Galileo E5a complex code, shifted to the desired chip and sampled at a frequency sampling_freq.
- void [galileo_e5_b_code_gen_complex_primary](#) (own::span< std::complex< float > > dest, int32_t prn, const std::array< char, 3 > &signal_id)
Generates Galileo E5b code at 1 sample/chip.
- void [galileo_e5_b_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, const std::array< char, 3 > &signal_id, int32_t sampling_freq, uint32_t chip_shift)

Generates Galileo E5b complex code, shifted to the desired chip and sampled at a frequency sampling_freq.

13.163.1 Detailed Description

This library implements various functions for Galileo E5 signal replica generation.

Author

Marc Sales, 2014. marcsales92(at)gmail.com

Piyush Gupta, 2020. piyush04111999@gmail.com

Note

Code added as part of GSoC 2020 Program.

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 Definition in file [galileo_e5_signal_replica.h](#).

13.164 galileo_e5_signal_replica.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_e5_signal_replica.h
00003  * \brief This library implements various functions for Galileo E5 signal
00004  * replica generation
00005  * \author Marc Sales, 2014. marcsales92(at)gmail.com
00006  * \author Piyush Gupta, 2020. piyush04111999@gmail.com
00007  * \note Code added as part of GSoC 2020 Program.
00008  *
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
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00015  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_GALILEO_E5_SIGNAL_REPLICA_H
00022 #define GNSS_SDR_GALILEO_E5_SIGNAL_REPLICA_H
00023
00024 #include <array>
00025 #include <complex>
00026 #include <stdint>
00027 #if HAS_STD_SPAN
00028 #include <span>
00029 namespace own = std;
00030 #else
00031 #include <gsl-lite/gsl-lite.hpp>
00032 namespace own = gsl_lite;
00033 #endif
00034
00035 /** \addtogroup Algorithms_Library
00036  * \{ */
00037 /** \addtogroup Algorithm_libs algorithms_libs
00038  * \{ */
00039
00040
00041 /*!
00042  * \brief Generates Galileo E5a code at 1 sample/chip
00043  */
00044 void galileo_e5_a_code_gen_complex_primary(own::span<std::complex<float>> dest,
00045      int32_t prn,
00046      const std::array<char, 3>& signal_id);
00047
00048
00049 /*!
00050  * \brief Generates Galileo E5a complex code, shifted to the desired chip and
00051  * sampled at a frequency sampling_freq
00052  */
00053 void galileo_e5_a_code_gen_complex_sampled(own::span<std::complex<float>> dest,
00054      uint32_t prn,
00055      const std::array<char, 3>& signal_id,
```

```

00056     int32_t sampling_freq,
00057     uint32_t chip_shift);
00058
00059
00060 /*!
00061  * \brief Generates Galileo E5b code at 1 sample/chip
00062  */
00063 void galileo_e5_b_code_gen_complex_primary(own::span<std::complex<float>> dest,
00064     int32_t prn,
00065     const std::array<char, 3>& signal_id);
00066
00067
00068 /*!
00069  * \brief Generates Galileo E5b complex code, shifted to the desired chip and
00070  * sampled at a frequency sampling_freq
00071  */
00072 void galileo_e5_b_code_gen_complex_sampled(own::span<std::complex<float>> dest,
00073     uint32_t prn,
00074     const std::array<char, 3>& signal_id,
00075     int32_t sampling_freq,
00076     uint32_t chip_shift);
00077
00078
00079 /** \} */
00080 /** \} */
00081 #endif // GNSS_SDR_GALILEO_E5_SIGNAL_REPLICA_H

```

13.165 galileo_e6_signal_replica.h File Reference

This library implements various functions for Galileo E6 signal replica generation.

```

#include <array>
#include <complex>
#include <cstdint>
#include <string>
#include <gsl-lite/gsl-lite.hpp>

```

Functions

- void [galileo_e6_b_code_gen_complex_primary](#) (own::span< std::complex< float > > dest, int32_t prn)
Generates Galileo E6B code at 1 sample/chip.
- void [galileo_e6_b_code_gen_float_primary](#) (own::span< float > dest, int32_t prn)
Generates Galileo E6B code at 1 sample/chip.
- void [galileo_e6_b_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift)
Generates Galileo E6B complex code, shifted to the desired chip and sampled at a frequency sampling_freq.
- void [galileo_e6_c_code_gen_complex_primary](#) (own::span< std::complex< float > > dest, int32_t prn)
Generates Galileo E6C codes at 1 sample/chip.
- void [galileo_e6_c_code_gen_float_primary](#) (own::span< float > dest, int32_t prn)
Generates Galileo E6C codes at 1 sample/chip.
- void [galileo_e6_c_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift)
Generates Galileo E6C complex codes, shifted to the desired chip and sampled at a frequency sampling_freq.
- void [galileo_e6_c_secondary_code_gen_complex](#) (own::span< std::complex< float > > dest, int32_t prn)
Generates Galileo E6C secondary codes at 1 sample/chip.
- void [galileo_e6_c_secondary_code_gen_float](#) (own::span< float > dest, int32_t prn)
Generates Galileo E6C secondary codes at 1 sample/chip.
- std::string [galileo_e6_c_secondary_code](#) (int32_t prn)
Generates a string with Galileo E6C secondary codes at 1 sample/chip.

13.165.1 Detailed Description

This library implements various functions for Galileo E6 signal replica generation.

Author

Carles Fernandez-Prades, 2020. cfernandez(at)cttc.es

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 Definition in file [galileo_e6_signal_replica.h](#).

13.166 galileo_e6_signal_replica.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_e6_signal_replica.h
00003  * \brief This library implements various functions for Galileo E6 signal
00004  * replica generation
00005  * \author Carles Fernandez-Prades, 2020. cfernandez(at)cttc.es
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GALILEO_E6_SIGNAL_REPLICA_H
00020 #define GNSS_SDR_GALILEO_E6_SIGNAL_REPLICA_H
00021
00022 #include <array>
00023 #include <complex>
00024 #include <cstdint>
00025 #include <string>
00026 #if HAS_STD_SPAN
00027 #include <span>
00028 namespace own = std;
00029 #else
00030 #include <gsl-lite/gsl-lite.hpp>
00031 namespace own = gsl_lite;
00032 #endif
00033
00034 /** \addtogroup Algorithms_Library
00035  * \{ */
00036 /** \addtogroup Algorithm_libs algorithms_libs
00037  * \{ */
00038
00039
00040  /*!
00041  * \brief Generates Galileo E6B code at 1 sample/chip
00042  */
00043  void galileo_e6_b_code_gen_complex_primary(own::span<std::complex<float>> dest,
00044      int32_t prn);
00045
00046
00047  /*!
00048  * \brief Generates Galileo E6B code at 1 sample/chip
00049  */
00050  void galileo_e6_b_code_gen_float_primary(own::span<float> dest, int32_t prn);
00051
00052
00053  /*!
00054  * \brief Generates Galileo E6B complex code, shifted to the desired chip and
00055  * sampled at a frequency sampling_freq
00056  */
00057  void galileo_e6_b_code_gen_complex_sampled(own::span<std::complex<float>> dest,
00058      uint32_t prn,
00059      int32_t sampling_freq,
00060      uint32_t chip_shift);
00061
00062
00063  /*!
00064  * \brief Generates Galileo E6C codes at 1 sample/chip
00065  */
00066  void galileo_e6_c_code_gen_complex_primary(own::span<std::complex<float>> dest,
00067      int32_t prn);

```

```

00068
00069
00070 /*!
00071  * \brief Generates Galileo E6C codes at 1 sample/chip
00072  */
00073 void galileo_e6_c_code_gen_float_primary(own::span<float> dest, int32_t prn);
00074
00075
00076 /*!
00077  * \brief Generates Galileo E6C complex codes, shifted to the desired chip and
00078  * sampled at a frequency sampling_freq
00079  */
00080 void galileo_e6_c_code_gen_complex_sampled(own::span<std::complex<float> dest,
00081      uint32_t prn,
00082      int32_t sampling_freq,
00083      uint32_t chip_shift);
00084
00085
00086 /*!
00087  * \brief Generates Galileo E6C secondary codes at 1 sample/chip
00088  */
00089 void galileo_e6_c_secondary_code_gen_complex(own::span<std::complex<float> dest,
00090      int32_t prn);
00091
00092
00093 /*!
00094  * \brief Generates Galileo E6C secondary codes at 1 sample/chip
00095  */
00096 void galileo_e6_c_secondary_code_gen_float(own::span<float> dest,
00097      int32_t prn);
00098
00099
00100 /*!
00101  * \brief Generates a string with Galileo E6C secondary codes at 1 sample/chip
00102  */
00103 std::string galileo_e6_c_secondary_code(int32_t prn);
00104
00105
00106 /** \} */
00107 /** \} */
00108 #endif // GNSS_SDR_GALILEO_E6_SIGNAL_REPLICA_H

```

13.167 geofunctions.h File Reference

A set of coordinate transformations functions and helpers, some of them migrated from MATLAB, for geographic information systems.

```
#include <armadillo>
```

Functions

- arma::mat [Skew_symmetric](#) (const arma::vec &a)
Calculates skew-symmetric matrix.
- double [WGS84_g0](#) (double Lat_rad)
- double [WGS84_geocentric_radius](#) (double Lat_geodetic_rad)
- int [topocent](#) (double *Az, double *El, double *D, const arma::vec &x, const arma::vec &dx)
Transformation of vector dx into topocentric coordinate system with origin at x Inputs: x - vector origin coordinates (in ECEF system [X; Y; Z;]) dx - vector ([dX; dY; dZ;]).
- int [togeod](#) (double *dphi, double *dlambda, double *h, double a, double finv, double X, double Y, double Z)
Subroutine to calculate geodetic coordinates latitude, longitude, height given Cartesian coordinates X,Y,Z, and reference ellipsoid values semi-major axis (a) and the inverse of flattening (finv).
- arma::vec [Gravity_ECEF](#) (const arma::vec &r_eb_e)
Calculates acceleration due to gravity resolved about ECEF-frame.
- arma::vec [cart2geo](#) (const arma::vec &XYZ, int ellipsoid_selection)
Conversion of Cartesian coordinates (X,Y,Z) to geographical coordinates (latitude, longitude, h) on a selected reference ellipsoid.
- arma::vec [LLH_to_deg](#) (const arma::vec &LLH)
- double [degtorad](#) (double angleInDegrees)
- double [radtodeg](#) (double angleInRadians)

- double **mstoknotsh** (double MetersPerSeconds)
- double **mstokph** (double MetersPerSeconds)
- arma::vec **CTM_to_Euler** (const arma::mat &C)
- arma::mat **Euler_to_CTM** (const arma::vec &eul)
- void **ECEF_to_Geo** (const arma::vec &r_eb_e, const arma::vec &v_eb_e, const arma::mat &C_b_e, arma::vec &LLH, arma::vec &v_eb_n, arma::mat &C_b_n)
- void **Geo_to_ECEF** (const arma::vec &LLH, const arma::vec &v_eb_n, const arma::mat &C_b_n, arma::vec &r_eb_e, arma::vec &v_eb_e, arma::mat &C_b_e)
From Geographic to ECEF coordinates.
- void **pv_Geo_to_ECEF** (double L_b, double lambda_b, double h_b, const arma::vec &v_eb_n, arma::vec &r_eb_e, arma::vec &v_eb_e)
Converts curvilinear to Cartesian position and velocity resolving axes from NED to ECEF This function created 11/4/2012 by Paul Groves.
- double **great_circle_distance** (double lat1, double lon1, double lat2, double lon2)
The Haversine formula determines the great-circle distance between two points on a sphere given their longitudes and latitudes.
- void **cart2utm** (const arma::vec &r_eb_e, int zone, arma::vec &r_enu)
Transformation of ECEF (X,Y,Z) to (E,N,U) in UTM, zone 'zone'.
- int **findUtmZone** (double latitude_deg, double longitude_deg)
Function finds the UTM zone number for given longitude and latitude.
- double **clsin** (const arma::colvec &ar, int degree, double argument)
Clenshaw summation of sinus of argument.
- void **clksin** (const arma::colvec &ar, int degree, double arg_real, double arg_imag, double *re, double *im)
Clenshaw summation of sinus with complex argument.

13.167.1 Detailed Description

A set of coordinate transformations functions and helpers, some of them migrated from MATLAB, for geographic information systems.

Author

Javier Arribas, 2018. jarribas(at)cttc.es

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 Definition in file [geofunctions.h](#).

13.168 geofunctions.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file geofunctions.h
00003  * \brief A set of coordinate transformations functions and helpers,
00004  * some of them migrated from MATLAB, for geographic information systems.
00005  * \author Javier Arribas, 2018. jarribas(at)cttc.es
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GEOFUNCTIONS_H
00020 #define GNSS_SDR_GEOFUNCTIONS_H
00021
00022 #if ARMA_NO_BOUND_CHECKING
00023 #define ARMA_NO_DEBUG 1
00024 #endif

```

```

00025
00026 #include <armadillo>
00027
00028 /** \addtogroup Algorithms_Library
00029 * \{ */
00030 /** \addtogroup Algorithm_libs algorithms_libs
00031 * \{ */
00032
00033
00034 arma::mat Skew_symmetric(const arma::vec &a); //!< Calculates skew-symmetric matrix
00035
00036 double WGS84_g0(double Lat_rad);
00037
00038 double WGS84_geocentric_radius(double Lat_geodetic_rad);
00039
00040 /*!
00041 * \brief Transformation of vector dx into topocentric coordinate
00042 * system with origin at x
00043 * Inputs:
00044 * x - vector origin coordinates (in ECEF system [X; Y; Z])
00045 * dx - vector ([dX; dY; dZ]).
00046 *
00047 * Outputs:
00048 * D - vector length. Units like the input
00049 * Az - azimuth from north positive clockwise, degrees
00050 * El - elevation angle, degrees
00051 *
00052 * Based on a Matlab function by Kai Borre
00053 */
00054 int topocent(double *Az, double *El, double *D, const arma::vec &x, const arma::vec &dx);
00055
00056 /*!
00057 * \brief Subroutine to calculate geodetic coordinates latitude, longitude,
00058 * height given Cartesian coordinates X,Y,Z, and reference ellipsoid
00059 * values semi-major axis (a) and the inverse of flattening (finv).
00060 *
00061 * The output units of angular quantities will be in decimal degrees
00062 * (15.5 degrees not 15 deg 30 min). The output units of h will be the
00063 * same as the units of X,Y,Z,a.
00064 *
00065 * Inputs:
00066 * a - semi-major axis of the reference ellipsoid
00067 * finv - inverse of flattening of the reference ellipsoid
00068 * X,Y,Z - Cartesian coordinates
00069 *
00070 * Outputs:
00071 * dphi - latitude
00072 * dlambd - longitude
00073 * h - height above reference ellipsoid
00074 *
00075 * Based in a Matlab function by Kai Borre
00076 */
00077 int togeod(double *dphi, double *dlambda, double *h, double a, double finv, double X, double Y, double
Z);
00078
00079 arma::vec Gravity_ECEF(const arma::vec &r_eb_e); //!< Calculates acceleration due to gravity resolved
about ECEF-frame
00080
00081 /*!
00082 * \brief Conversion of Cartesian coordinates (X,Y,Z) to geographical
00083 * coordinates (latitude, longitude, h) on a selected reference ellipsoid.
00084 *
00085 * Choices of Reference Ellipsoid for Geographical Coordinates
00086 * 0. International Ellipsoid 1924
00087 * 1. International Ellipsoid 1967
00088 * 2. World Geodetic System 1972
00089 * 3. Geodetic Reference System 1980
00090 * 4. World Geodetic System 1984
00091 */
00092 arma::vec cart2geo(const arma::vec &XYZ, int ellipsoid_selection);
00093
00094 arma::vec LLH_to_deg(const arma::vec &LLH);
00095
00096 double degtorad(double angleInDegrees);
00097
00098 double radtodeg(double angleInRadians);
00099
00100 double mstoknotsh(double MetersPerSeconds);
00101
00102 double mstokph(double MetersPerSeconds);
00103
00104 arma::vec CTM_to_Euler(const arma::mat &C);
00105
00106 arma::mat Euler_to_CTM(const arma::vec &eul);
00107
00108 void ECEF_to_Geo(const arma::vec &r_eb_e, const arma::vec &v_eb_e, const arma::mat &C_b_e, arma::vec
&LLH, arma::vec &v_eb_n, arma::mat &C_b_n);

```



```

00109
00110
00111 /*!
00112 * \brief From Geographic to ECEF coordinates
00113 *
00114 * Inputs:
00115 *   LLH           latitude (rad), longitude (rad), height (m)
00116 *   v_eb_n        velocity of body frame w.r.t. ECEF frame, resolved along
00117 *                 north, east, and down (m/s)
00118 *   C_b_n         body-to-NED coordinate transformation matrix
00119 *
00120 * Outputs:
00121 *   r_eb_e        Cartesian position of body frame w.r.t. ECEF frame, resolved
00122 *                 along ECEF-frame axes (m)
00123 *   v_eb_e        velocity of body frame w.r.t. ECEF frame, resolved along
00124 *                 ECEF-frame axes (m/s)
00125 *   C_b_e         body-to-ECEF-frame coordinate transformation matrix
00126 *
00127 */
00128 void Geo_to_ECEF(const arma::vec &LLH, const arma::vec &v_eb_n, const arma::mat &C_b_n, arma::vec
&r_eb_e, arma::vec &v_eb_e, arma::mat &C_b_e);
00129
00130
00131 /*!
00132 * \brief Converts curvilinear to Cartesian position and velocity
00133 * resolving axes from NED to ECEF
00134 * This function created 11/4/2012 by Paul Groves
00135 *
00136 * Inputs:
00137 *   L_b           latitude (rad)
00138 *   lambda_b      longitude (rad)
00139 *   h_b           height (m)
00140 *   v_eb_n        velocity of body frame w.r.t. ECEF frame, resolved along
00141 *                 north, east, and down (m/s)
00142 *
00143 * Outputs:
00144 *   r_eb_e        Cartesian position of body frame w.r.t. ECEF frame, resolved
00145 *                 along ECEF-frame axes (m)
00146 *   v_eb_e        velocity of body frame w.r.t. ECEF frame, resolved along
00147 *                 ECEF-frame axes (m/s)
00148 */
00149 void pv_Geo_to_ECEF(double L_b, double lambda_b, double h_b, const arma::vec &v_eb_n, arma::vec
&r_eb_e, arma::vec &v_eb_e);
00150
00151
00152 /*!
00153 * \brief The Haversine formula determines the great-circle distance between two points on a sphere
00154 * given their longitudes and latitudes.
00155 */
00155 double great_circle_distance(double lat1, double lon1, double lat2, double lon2);
00156
00157
00158 /*!
00159 * \brief Transformation of ECEF (X,Y,Z) to (E,N,U) in UTM, zone 'zone'.
00160 */
00161 void cart2utm(const arma::vec &r_eb_e, int zone, arma::vec &r_enu);
00162
00163
00164 /*!
00165 * \brief Function finds the UTM zone number for given longitude and latitude.
00166 */
00167 int findUtmZone(double latitude_deg, double longitude_deg);
00168
00169
00170 /*!
00171 * \brief Clenshaw summation of sinus of argument.
00172 */
00173 double clsin(const arma::colvec &ar, int degree, double argument);
00174
00175
00176 /*!
00177 * \brief Clenshaw summation of sinus with complex argument.
00178 */
00179 void clkasin(const arma::colvec &ar, int degree, double arg_real, double arg_imag, double *re, double
*im);
00180
00181
00182 /** \} */
00183 /** \} */
00184 #endif // GNSS_SDR_GEOFUNCTIONS_H

```

13.169 glonass_l1_signal_replica.h

```
00001 /*!
```

```

00002  * \file glonass_l1_signal_processing.h
00003  * \brief This file implements various functions for GLONASS L1 CA signal
00004  * replica generation
00005  * \author Gabriel Araujo, 2017. gabriel.araujo(at)ieee.org
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GLOMSS_L1_SIGNAL_REPLICA_H
00020 #define GNSS_SDR_GLOMSS_L1_SIGNAL_REPLICA_H
00021
00022 #include <complex>
00023 #include <cstdint>
00024 #if HAS_STD_SPAN
00025 #include <span>
00026 namespace own = std;
00027 #else
00028 #include <gsl-lite/gsl-lite.hpp>
00029 namespace own = gsl_lite;
00030 #endif
00031
00032 /** \addtogroup Algorithms_Library
00033  * \{ */
00034 /** \addtogroup Algorithm_libs algorithms_libs
00035  * \{ */
00036
00037
00038 //! Generates complex GLONASS L1 C/A code for the desired SV ID and code shift
00039 void glonass_l1_ca_code_gen_complex(own::span<std::complex<float>> dest, uint32_t chip_shift);
00040
00041 //! Generates float GLONASS L1 C/A code for the desired SV ID and code shift
00042 void glonass_l1_ca_code_gen_float(own::span<float> dest, uint32_t chip_shift);
00043
00044 //! Generates complex GLONASS L1 C/A code for the desired SV ID and code shift, and sampled to
    specific sampling frequency
00045 void glonass_l1_ca_code_gen_complex_sampled(own::span<std::complex<float>> dest, int32_t sampling_freq,
    uint32_t chip_shift);
00046
00047
00048 /** \} */
00049 /** \} */
00050 #endif // GNSS_SDR_GLOMSS_L1_SIGNAL_REPLICA_H

```

13.170 glonass_l2_signal_replica.h File Reference

This file implements various functions for GLONASS L2 CA signal replica generation.

```

#include <complex>
#include <cstdint>
#include <gsl-lite/gsl-lite.hpp>

```

Functions

- void [glonass_l2_ca_code_gen_complex](#) (own::span< std::complex< float > > dest, uint32_t chip_shift)
Generates complex GLONASS L2 C/A code for the desired SV ID and code shift.
- void [glonass_l2_ca_code_gen_float](#) (own::span< float > dest, uint32_t chip_shift)
Generates float GLONASS L2 C/A code for the desired SV ID and code shift.
- void [glonass_l2_ca_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, int32_t sampling_freq, uint32_t chip_shift)
Generates complex GLONASS L2 C/A code for the desired SV ID and code shift, and sampled to specific sampling frequency.

13.170.1 Detailed Description

This file implements various functions for GLONASS L2 CA signal replica generation.

Author

Damian Miralles, 2018, dmiralles2009(at)gmail.com

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Definition in file [glonass_l2_signal_replica.h](#).

13.171 glonass_l2_signal_replica.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file glonass_l2_signal_replica.h
00003  * \brief This file implements various functions for GLONASS L2 CA signal
00004  * replica generation
00005  * \author Damian Miralles, 2018, dmiralles2009(at)gmail.com
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GLOPASS_L2_SIGNAL_REPLICA_H
00020 #define GNSS_SDR_GLOPASS_L2_SIGNAL_REPLICA_H
00021
00022 #include <complex>
00023 #include <cstdint>
00024 #if HAS_STD_SPAN
00025 #include <span>
00026 namespace own = std;
00027 #else
00028 #include <gsl-lite/gsl-lite.hpp>
00029 namespace own = gsl_lite;
00030 #endif
00031
00032 /** \addtogroup Algorithms_Library
00033  * \{ */
00034 /** \addtogroup Algorithm_libs algorithms_libs
00035  * \{ */
00036
00037
00038 //! Generates complex GLONASS L2 C/A code for the desired SV ID and code shift
00039 void glonass_l2_ca_code_gen_complex(own::span<std::complex<float>> dest, uint32_t chip_shift);
00040
00041 //! Generates float GLONASS L2 C/A code for the desired SV ID and code shift
00042 void glonass_l2_ca_code_gen_float(own::span<float> dest, uint32_t chip_shift);
00043
00044 //! Generates complex GLONASS L2 C/A code for the desired SV ID and code shift, and sampled to
00045 void glonass_l2_ca_code_gen_complex_sampled(own::span<std::complex<float>> dest, int32_t sampling_freq,
00046 uint32_t chip_shift);
00047
00048 /** \} */
00049 /** \} */
00050 #endif // GNSS_SDR_GLOPASS_L2_SIGNAL_REPLICA_H
```

13.172 gnss_circular_deque.h File Reference

This class implements a circular deque for [Gnss_Synchro](#).

```
#include <boost/circular_buffer.hpp>
#include <vector>
```

Classes

- class [Gnss_circular_deque< T >](#)

13.172.1 Detailed Description

This class implements a circular deque for [Gnss_Synchro](#).

Author

Antonio Ramos, 2018. antonio.ramosdet(at)gmail.com

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 Definition in file [gnss_circular_deque.h](#).

13.173 gnss_circular_deque.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gnss_circular_deque.h
00003  * \brief This class implements a circular deque for Gnss_Synchro
00004  * \author Antonio Ramos, 2018. antonio.ramosdet(at)gmail.com
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_CIRCULAR_DEQUE_H
00019 #define GNSS_SDR_CIRCULAR_DEQUE_H
00020
00021 #include <boost/circular_buffer.hpp>
00022 #include <vector>
00023
00024 /** \addtogroup Algorithms_Library
00025  * \{ */
00026 /** \addtogroup Algorithm_libs algorithms_libs
00027  * \{ */
00028
00029
00030 template <class T>
00031 class Gnss_circular_deque
00032 {
00033 public:
00034     Gnss_circular_deque();                //!< Default constructor
00035     Gnss_circular_deque(unsigned int max_size, unsigned int nchann);    //!< nchann = number of
00036     channels; max_size = channel capacity
00037     unsigned int size(unsigned int ch) const;    //!< Returns the number of
00038     available elements in a channel
00039     T& at(unsigned int ch, unsigned int pos);    //!< Returns a reference to an
00040     element with bound checking
00041     const T& get(unsigned int ch, unsigned int pos) const;    //!< Returns a const reference
00042     to an element without bound checking
00043     T& front(unsigned int ch);                //!< Returns a reference to the
00044     first element in the deque
00045     T& back(unsigned int ch);                //!< Returns a reference to the
00046     last element in the deque
00047     void push_back(unsigned int ch, const T& new_data);    //!< Inserts an element at the
00048     end of the deque
00049     void pop_front(unsigned int ch);    //!< Removes the first element
00050     of the deque
00051     void clear(unsigned int ch);                //!< Removes all the elements of
00052     the deque (Sets size to 0). Capacity is not modified
00053     void reset(unsigned int max_size, unsigned int nchann);    //!< Removes all the elements in
00054     all the channels. Re-sets the number of channels and their capacity
00055     void reset();    //!< Removes all the channels
00056     (Sets nchann to 0)
00057
00058 private:
00059     std::vector<boost::circular_buffer<T>> d_data;
00060 };
00061
00062 template <class T>
00063 Gnss_circular_deque<T>::Gnss_circular_deque()
00064 {
00065     reset();
00066 }

```

```

00057
00058
00059 template <class T>
00060 Gnss_circular_deque<T>::Gnss_circular_deque(unsigned int max_size, unsigned int nchann)
00061 {
00062     reset(max_size, nchann);
00063 }
00064
00065
00066 template <class T>
00067 unsigned int Gnss_circular_deque<T>::size(unsigned int ch) const
00068 {
00069     return d_data[ch].size();
00070 }
00071
00072
00073 template <class T>
00074 T& Gnss_circular_deque<T>::back(unsigned int ch)
00075 {
00076     return d_data[ch].back();
00077 }
00078
00079
00080 template <class T>
00081 T& Gnss_circular_deque<T>::front(unsigned int ch)
00082 {
00083     return d_data[ch].front();
00084 }
00085
00086
00087 template <class T>
00088 T& Gnss_circular_deque<T>::at(unsigned int ch, unsigned int pos)
00089 {
00090     return d_data.at(ch).at(pos);
00091 }
00092
00093
00094 template <class T>
00095 const T& Gnss_circular_deque<T>::get(unsigned int ch, unsigned int pos) const
00096 {
00097     return d_data[ch][pos];
00098 }
00099
00100
00101 template <class T>
00102 void Gnss_circular_deque<T>::clear(unsigned int ch)
00103 {
00104     d_data[ch].clear();
00105 }
00106
00107
00108 template <class T>
00109 void Gnss_circular_deque<T>::reset(unsigned int max_size, unsigned int nchann)
00110 {
00111     d_data.clear();
00112     if (max_size > 0 and nchann > 0)
00113     {
00114         for (unsigned int i = 0; i < nchann; i++)
00115         {
00116             d_data.push_back(boost::circular_buffer<T>(max_size));
00117         }
00118     }
00119 }
00120
00121
00122 template <class T>
00123 void Gnss_circular_deque<T>::reset()
00124 {
00125     d_data.clear();
00126 }
00127
00128
00129 template <class T>
00130 void Gnss_circular_deque<T>::pop_front(unsigned int ch)
00131 {
00132     d_data[ch].pop_front();
00133 }
00134
00135
00136 template <class T>
00137 void Gnss_circular_deque<T>::push_back(unsigned int ch, const T& new_data)
00138 {
00139     d_data[ch].push_back(new_data);
00140 }
00141
00142
00143 /** \} */

```

```
00144 /** \} */
00145 #endif // GNSS_SDR_CIRCULAR_DEQUE_H
```

13.174 gnss_sdr_create_directory.h File Reference

Create a directory.

```
#include <string>
```

Functions

- `bool gnss_sdr_create_directory` (const std::string &foldername)

13.174.1 Detailed Description

Create a directory.

Author

Carles Fernandez-Prades, 2018. cfernandez(at)cttc.es

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 Definition in file [gnss_sdr_create_directory.h](#).

13.175 gnss_sdr_create_directory.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gnss_sdr_create_directory.h
00003  * \brief Create a directory
00004  * \author Carles Fernandez-Prades, 2018. cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GNSS_SDR_CREATE_DIRECTORY_H
00019 #define GNSS_SDR_GNSS_SDR_CREATE_DIRECTORY_H
00020
00021 #include <string>
00022
00023 /** \addtogroup Algorithms_Library
00024  * \{ */
00025 /** \addtogroup Algorithm_libs algorithms_libs
00026  * \{ */
00027
00028
00029 bool gnss_sdr_create_directory(const std::string& foldername);
00030
00031
00032 /** \} */
00033 /** \} */
00034 #endif // GNSS_SDR_GNSS_SDR_CREATE_DIRECTORY_H
```

13.176 gnss_sdr_fft.h File Reference

Helper file for FFT interface.

```
#include "gnss_sdr_make_unique.h"
#include <gnuradio/fft/fft.h>
#include <memory>
```

```
#include <utility>
```

Typedefs

- using [gnss_fft_complex_fwd](#) = `gr::fft::fft_complex`
- using [gnss_fft_complex_rev](#) = `gr::fft::fft_complex`
- template<typename T>
using [gnss_fft_fwd_unique_ptr](#) = `std::unique_ptr<T>`
- template<typename T>
using [gnss_fft_rev_unique_ptr](#) = `std::unique_ptr<T>`

Functions

- template<typename... Args>
`gnss_fft_fwd_unique_ptr< gr::fft::fft_complex >` [gnss_fft_fwd_make_unique](#) (Args &&... args)
- template<typename... Args>
`gnss_fft_rev_unique_ptr< gr::fft::fft_complex >` [gnss_fft_rev_make_unique](#) (Args &&... args)

13.176.1 Detailed Description

Helper file for FFT interface.

Author

Carles Fernandez Prades, 2021. [cfernandez\(at\)cttc.es](mailto:cfernandez(at)cttc.es)

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Definition in file [gnss_sdr_fft.h](#).

13.176.2 Typedef Documentation

13.176.2.1 [gnss_fft_complex_fwd](#)

using [gnss_fft_complex_fwd](#) = `gr::fft::fft_complex`
Definition at line 46 of file [gnss_sdr_fft.h](#).

13.176.2.2 [gnss_fft_complex_rev](#)

using [gnss_fft_complex_rev](#) = `gr::fft::fft_complex`
Definition at line 47 of file [gnss_sdr_fft.h](#).

13.176.2.3 [gnss_fft_fwd_unique_ptr](#)

template<typename T>
using [gnss_fft_fwd_unique_ptr](#) = `std::unique_ptr<T>`
Definition at line 49 of file [gnss_sdr_fft.h](#).

13.176.2.4 [gnss_fft_rev_unique_ptr](#)

template<typename T>
using [gnss_fft_rev_unique_ptr](#) = `std::unique_ptr<T>`
Definition at line 56 of file [gnss_sdr_fft.h](#).

13.176.3 Function Documentation

13.176.3.1 [gnss_fft_fwd_make_unique\(\)](#)

template<typename... Args>
`gnss_fft_fwd_unique_ptr< gr::fft::fft_complex >` [gnss_fft_fwd_make_unique](#) (
Args &&... args)
Definition at line 51 of file [gnss_sdr_fft.h](#).

13.176.3.2 gnss_fft_rev_make_unique()

```
template<typename... Args>
gnss_fft_rev_unique_ptr< gr::fft::fft_complex > gnss_fft_rev_make_unique (
    Args &&... args)
```

Definition at line 58 of file [gnss_sdr_fft.h](#).

13.177 gnss_sdr_fft.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gnss_sdr_fft.h
00003  * \brief Helper file for FFT interface
00004  * \author Carles Fernandez Prades, 2021. cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GNSS_SDR_FFT_H
00019 #define GNSS_SDR_GNSS_SDR_FFT_H
00020
00021 #include "gnss_sdr_make_unique.h"
00022 #include <gnuradio/fft/fft.h>
00023 #include <memory>
00024 #include <utility>
00025
00026 #if GNURADIO_FFT_USES_TEMPLATES
00027 using gnss_fft_complex_fwd = gr::fft::fft_complex_fwd;
00028 using gnss_fft_complex_rev = gr::fft::fft_complex_rev;
00029 template <typename T>
00030 using gnss_fft_fwd_unique_ptr = std::unique_ptr<T>;
00031 template <typename... Args>
00032 gnss_fft_fwd_unique_ptr<gr::fft::fft_complex_fwd> gnss_fft_fwd_make_unique(Args&&... args)
00033 {
00034     return std::make_unique<gr::fft::fft_complex_fwd>(std::forward<Args>(args)...);
00035 }
00036 template <typename T>
00037 using gnss_fft_rev_unique_ptr = std::unique_ptr<T>;
00038 template <typename... Args>
00039 gnss_fft_rev_unique_ptr<gr::fft::fft_complex_rev> gnss_fft_rev_make_unique(Args&&... args)
00040 {
00041     return std::make_unique<gr::fft::fft_complex_rev>(std::forward<Args>(args)...);
00042 }
00043
00044 #else
00045
00046 using gnss_fft_complex_fwd = gr::fft::fft_complex;
00047 using gnss_fft_complex_rev = gr::fft::fft_complex;
00048 template <typename T>
00049 using gnss_fft_fwd_unique_ptr = std::unique_ptr<T>;
00050 template <typename... Args>
00051 gnss_fft_fwd_unique_ptr<gr::fft::fft_complex> gnss_fft_fwd_make_unique(Args&&... args)
00052 {
00053     return std::make_unique<gr::fft::fft_complex>(std::forward<Args>(args)..., true);
00054 }
00055 template <typename T>
00056 using gnss_fft_rev_unique_ptr = std::unique_ptr<T>;
00057 template <typename... Args>
00058 gnss_fft_rev_unique_ptr<gr::fft::fft_complex> gnss_fft_rev_make_unique(Args&&... args)
00059 {
00060     return std::make_unique<gr::fft::fft_complex>(std::forward<Args>(args)..., false);
00061 }
00062
00063 #endif
00064
00065 #endif // GNSS_SDR_GNSS_SDR_FFT_H
```

13.178 gnss_sdr_filesystem.h File Reference

Helper file for filesystem library interface.


```
#include <boost/filesystem/operations.hpp>
#include <boost/filesystem/path.hpp>
#include <boost/filesystem/path_traits.hpp>
#include <boost/system/error_code.hpp>
```

13.178.1 Detailed Description

Helper file for filesystem library interface.

Author

Carles Fernandez Prades, 2021. cfernandez(at)cttc.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [gnss_sdr_filesystem.h](#).

13.179 gnss_sdr_filesystem.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gnss_sdr_filesystem.h
00003  * \brief Helper file for filesystem library interface
00004  * \author Carles Fernandez Prades, 2021. cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GNSS_SDR_FILESYSTEM_H
00019 #define GNSS_SDR_GNSS_SDR_FILESYSTEM_H
00020
00021 // clang-format off
00022 #if HAS_STD_FILESYSTEM
00023 #include <system_error>
00024 namespace errorlib = std;
00025 #if HAS_STD_FILESYSTEM_EXPERIMENTAL
00026 #include <experimental/filesystem>
00027 namespace fs = std::experimental::filesystem;
00028 #else
00029 #include <filesystem>
00030 namespace fs = std::filesystem;
00031 #endif
00032 #else
00033 #include <boost/filesystem/operations.hpp> // for create_directories, exists
00034 #include <boost/filesystem/path.hpp> // for path, operator<
00035 #include <boost/filesystem/path_traits.hpp> // for filesystem
00036 #include <boost/system/error_code.hpp> // for error_code
00037 namespace fs = boost::filesystem;
00038 namespace errorlib = boost::system;
00039 #endif
00040 // clang-format on
00041
00042
00043 #endif // GNSS_SDR_GNSS_SDR_FILESYSTEM_H
```

13.180 gnss_sdr_flags.h File Reference

Helper file for gnss-sdr cmdline flags.

```
#include <cstdint>
#include <string>
#include <absl/flags/declare.h>
#include <absl/flags/flag.h>
#include <cstdlib>
```

```
#include <iostream>
#include <sys/stat.h>
#include <vector>
```

Functions

- [ABSL_DECLARE_FLAG](#) (std::string, c)
Path to the configuration file.
- [ABSL_DECLARE_FLAG](#) (std::string, config_file)
Path to the configuration file.
- [ABSL_DECLARE_FLAG](#) (std::string, log_dir)
Path to the folder in which logging will be stored.
- [ABSL_DECLARE_FLAG](#) (std::string, s)
Path to the file containing the signal samples.
- [ABSL_DECLARE_FLAG](#) (std::string, signal_source)
Path to the file containing the signal samples.
- [ABSL_DECLARE_FLAG](#) (std::string, timestamp_source)
Path to the file containing the signal samples.
- [ABSL_DECLARE_FLAG](#) (bool, rf_shutdown)
Shutdown RF when program exits.
- [ABSL_DECLARE_FLAG](#) (int32_t, doppler_max)
If defined, maximum Doppler value in the search grid, in Hz (overrides the configuration file).
- [ABSL_DECLARE_FLAG](#) (int32_t, doppler_step)
If defined, sets the frequency step in the search grid, in Hz, in Hz (overrides the configuration file).
- [ABSL_DECLARE_FLAG](#) (int32_t, cn0_samples)
Number of correlator outputs used for CN0 estimation.
- [ABSL_DECLARE_FLAG](#) (int32_t, cn0_min)
Minimum valid CN0 (in dB-Hz).
- [ABSL_DECLARE_FLAG](#) (int32_t, max_lock_fail)
Maximum number of code lock failures before dropping a satellite.
- [ABSL_DECLARE_FLAG](#) (int32_t, max_carrier_lock_fail)
Maximum number of carrier lock failures before dropping a satellite.
- [ABSL_DECLARE_FLAG](#) (double, carrier_lock_th)
Carrier lock threshold (in rad).
- [ABSL_DECLARE_FLAG](#) (double, dll_bw_hz)
Bandwidth of the DLL low pass filter, in Hz (overrides the configuration file).
- [ABSL_DECLARE_FLAG](#) (double, pll_bw_hz)
Bandwidth of the PLL low pass filter, in Hz (overrides the configuration file).
- [ABSL_DECLARE_FLAG](#) (int32_t, carrier_smoothing_factor)
Sets carrier smoothing factor M (overrides the configuration file).
- [ABSL_DECLARE_FLAG](#) (std::string, RINEX_version)
If defined, specifies the RINEX version (2.11 or 3.02). Overrides the configuration file.
- [ABSL_DECLARE_FLAG](#) (std::string, RINEX_name)
If defined, specifies the RINEX files base name.
- [ABSL_DECLARE_FLAG](#) (bool, keyboard)
If set to false, disables the keyboard listener. Only for debug purposes (e.g. ASAN mode termination)
- bool **ValidateFlags** ()

Variables

- const int32_t **DEFAULT_CARRIER_SMOOTHING_FACTOR** = 200

13.180.1 Detailed Description

Helper file for gnss-sdr commandline flags.

Author

Carles Fernandez-Prades, 2018-2024. cfernandez(at)cttc.es

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 Definition in file [gnss_sdr_flags.h](#).

13.181 gnss_sdr_flags.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gnss_sdr_flags.h
00003  * \brief Helper file for gnss-sdr commandline flags
00004  * \author Carles Fernandez-Prades, 2018-2024. cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GNSS_SDR_FLAGS_H
00019 #define GNSS_SDR_GNSS_SDR_FLAGS_H
00020
00021 #include <cstdint>
00022 #include <string>
00023
00024 #if USE_GLOG_AND_GFLAGS
00025 #include <gflags/gflags.h>
00026 #else
00027 #include <absl/flags/declare.h>
00028 #include <absl/flags/flag.h>
00029 #include <cstdlib>
00030 #include <iostream>
00031 #include <sys/stat.h>
00032 #include <vector>
00033 #endif
00034
00035
00036 /** \addtogroup Algorithms_Library
00037  * \{ */
00038 /** \addtogroup Gflags gnss_sdr_flags
00039  * Library for command-line handling.
00040  * \{ */
00041
00042 #if USE_GLOG_AND_GFLAGS
00043 DECLARE_string(c);          //!< Path to the configuration file.
00044 DECLARE_string(config_file); //!< Path to the configuration file.
00045
00046 DECLARE_string(log_dir);    //!< Path to the folder in which logging will be stored.
00047
00048 // Declare flags for signal sources
00049 DECLARE_string(s);          //!< Path to the file containing the signal samples.
00050 DECLARE_string(signal_source); //!< Path to the file containing the signal samples.
00051 DECLARE_string(timestamp_source); //!< Path to the file containing the signal samples.
00052 DECLARE_bool(rf_shutdown);   //!< Shutdown RF when program exits.
00053
00054 // Declare flags for acquisition blocks
00055 DECLARE_int32(doppler_max);  //!< If defined, maximum Doppler value in the search grid, in Hz
                                (overrides the configuration file).
00056 DECLARE_int32(doppler_step); //!< If defined, sets the frequency step in the search grid, in Hz, in
                                Hz (overrides the configuration file).
00057
00058 // Declare flags for tracking blocks
00059 DECLARE_int32(cn0_samples);  //!< Number of correlator outputs used for CN0 estimation.
00060 DECLARE_int32(cn0_min);      //!< Minimum valid CN0 (in dB-Hz).
00061 DECLARE_int32(max_lock_fail); //!< Maximum number of code lock failures before dropping a
                                satellite.
00062 DECLARE_int32(max_carrier_lock_fail); //!< Maximum number of carrier lock failures before dropping a
                                satellite.
00063 DECLARE_double(carrier_lock_th); //!< Carrier lock threshold (in rad).

```

```

00064 DECLARE_double(dll_bw_hz);          //!< Bandwidth of the DLL low pass filter, in Hz (overrides the
configuration file).
00065 DECLARE_double pll_bw_hz;            //!< Bandwidth of the PLL low pass filter, in Hz (overrides the
configuration file).
00066
00067 // Declare flags for observables block
00068 DECLARE_int32(carrier_smoothing_factor); //!< Sets carrier smoothing factor M (overrides the
configuration file).
00069 const int32_t DEFAULT_CARRIER_SMOOTHING_FACTOR = 200;
00070
00071 // Declare flags for PVT
00072 DECLARE_string(RINEX_version); //!< If defined, specifies the RINEX version (2.11 or 3.02). Overrides
the configuration file.
00073 DECLARE_string(RINEX_name);          //!< If defined, specifies the RINEX files base name
00074 DECLARE_bool(keyboard);              //!< If set to false, disables the keyboard listener. Only for debug
purposes (e.g. ASAN mode termination)
00075
00076 #else
00077 ABSL_DECLARE_FLAG(std::string, c);          //!< Path to the configuration file.
00078 ABSL_DECLARE_FLAG(std::string, config_file); //!< Path to the configuration file.
00079
00080 ABSL_DECLARE_FLAG(std::string, log_dir);    //!< Path to the folder in which logging will be stored.
00081
00082 // Declare flags for signal sources
00083 ABSL_DECLARE_FLAG(std::string, s);          //!< Path to the file containing the signal
samples.
00084 ABSL_DECLARE_FLAG(std::string, signal_source); //!< Path to the file containing the signal
samples.
00085 ABSL_DECLARE_FLAG(std::string, timestamp_source); //!< Path to the file containing the signal
samples.
00086 ABSL_DECLARE_FLAG(bool, rf_shutdown);      //!< Shutdown RF when program exits.
00087
00088 // Declare flags for acquisition blocks
00089 ABSL_DECLARE_FLAG(int32_t, doppler_max);    //!< If defined, maximum Doppler value in the search grid,
in Hz (overrides the configuration file).
00090 ABSL_DECLARE_FLAG(int32_t, doppler_step);  //!< If defined, sets the frequency step in the search
grid, in Hz, in Hz (overrides the configuration file).
00091
00092 // Declare flags for tracking blocks
00093 ABSL_DECLARE_FLAG(int32_t, cn0_samples);    //!< Number of correlator outputs used for CN0
estimation.
00094 ABSL_DECLARE_FLAG(int32_t, cn0_min);        //!< Minimum valid CN0 (in dB-Hz).
00095 ABSL_DECLARE_FLAG(int32_t, max_lock_fail);  //!< Maximum number of code lock failures before
dropping a satellite.
00096 ABSL_DECLARE_FLAG(int32_t, max_carrier_lock_fail); //!< Maximum number of carrier lock failures
before dropping a satellite.
00097 ABSL_DECLARE_FLAG(double, carrier_lock_th); //!< Carrier lock threshold (in rad).
00098 ABSL_DECLARE_FLAG(double, dll_bw_hz);      //!< Bandwidth of the DLL low pass filter, in Hz
(overrides the configuration file).
00099 ABSL_DECLARE_FLAG(double, pll_bw_hz);      //!< Bandwidth of the PLL low pass filter, in Hz
(overrides the configuration file).
00100
00101 // Declare flags for observables block
00102 ABSL_DECLARE_FLAG(int32_t, carrier_smoothing_factor); //!< Sets carrier smoothing factor M (overrides
the configuration file).
00103 const int32_t DEFAULT_CARRIER_SMOOTHING_FACTOR = 200;
00104
00105 // Declare flags for PVT
00106 ABSL_DECLARE_FLAG(std::string, RINEX_version); //!< If defined, specifies the RINEX version (2.11 or
3.02). Overrides the configuration file.
00107 ABSL_DECLARE_FLAG(std::string, RINEX_name);    //!< If defined, specifies the RINEX files base name
00108 ABSL_DECLARE_FLAG(bool, keyboard);             //!< If set to false, disables the keyboard listener.
Only for debug purposes (e.g. ASAN mode termination)
00109
00110 static inline void GetTempDirectories(std::vector<std::string>& list)
00111 {
00112     list.clear();
00113     // Directories, in order of preference. If we find a dir that
00114     // exists, we stop adding other less-preferred dirs
00115     const char* candidates[] = {
00116         // Non-null only during unittest/regtest
00117         std::getenv("TEST_TMPDIR"),
00118
00119         // Explicitly-supplied temp dirs
00120         std::getenv("TMPDIR"),
00121         std::getenv("TMP"),
00122
00123         // If all else fails
00124         "/tmp",
00125     };
00126     for (auto d : candidates)
00127     {
00128         if (!d) continue; // Empty env var
00129
00130         // Make sure we don't surprise anyone who's expecting a '/'
00131         std::string dstr = d;
00132         if (dstr[dstr.size() - 1] != '/')

```

```

00133         {
00134             dstr += "/";
00135         }
00136         list.push_back(dstr);
00137
00138         struct stat statbuf;
00139         if (!stat(d, &statbuf) && S_ISDIR(statbuf.st_mode))
00140         {
00141             // We found a dir that exists - we're done.
00142             return;
00143         }
00144     }
00145 }
00146
00147
00148 static inline void GetExistingTempDirectories(std::vector<std::string>& list)
00149 {
00150     GetTempDirectories(list);
00151     auto i_dir = list.begin();
00152     while (i_dir != list.end())
00153     {
00154         if (access(i_dir->c_str(), 0))
00155         {
00156             i_dir = list.erase(i_dir);
00157         }
00158         else
00159         {
00160             ++i_dir;
00161         }
00162     };
00163 }
00164
00165
00166 static inline std::string GetTempDir()
00167 {
00168     std::vector<std::string> temp_directories_list;
00169     GetExistingTempDirectories(temp_directories_list);
00170
00171     if (temp_directories_list.empty())
00172     {
00173         std::cerr << "No temporary directory found\n";
00174         exit(EXIT_FAILURE);
00175     }
00176
00177     // Use first directory from list of existing temporary directories.
00178     return temp_directories_list.front();
00179 }
00180
00181 bool ValidateFlags();
00182
00183 #endif
00184
00185 /** \} */
00186 /** \} */
00187 #endif // GNSS_SDR_GNSS_SDR_FLAGS_H

```

13.182 gnss_sdr_make_unique.h File Reference

This file implements std::make_unique for C++11.

13.182.1 Detailed Description

This file implements std::make_unique for C++11.

Author

Carles Fernandez-Prades, 2020. cfernandez(at)cttc.es

Based on <https://stackoverflow.com/a/17902439>

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Definition in file [gnss_sdr_make_unique.h](#).

13.183 gnss_sdr_make_unique.h

[Go to the documentation of this file.](#)

```
00001 /*!
```

```

00002  * \file gnss_sdr_make_unique.h
00003  * \brief This file implements std::make_unique for C++11
00004  *
00005  * \author Carles Fernandez-Prades, 2020. cfernandez(at)cttc.es
00006  *
00007  * Based on https://stackoverflow.com/a/17902439
00008  *
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_GNSS_SDR_MAKE_UNIQUE_H
00022 #define GNSS_SDR_GNSS_SDR_MAKE_UNIQUE_H
00023
00024 #if __cplusplus == 201103L
00025
00026 #include <cstdint>
00027 #include <memory>
00028 #include <type_traits>
00029 #include <utility>
00030
00031 /** \addtogroup Algorithms_Library
00032  * \{ */
00033 /** \addtogroup Algorithm_libs algorithms_libs
00034  * \{ */
00035
00036 namespace std
00037 {
00038     template <class T>
00039     struct _Unique_if
00040     {
00041         typedef unique_ptr<T> _Single_object;
00042     };
00043
00044     template <class T>
00045     struct _Unique_if<T[]>
00046     {
00047         typedef unique_ptr<T[]> _Unknown_bound;
00048     };
00049
00050     template <class T, size_t N>
00051     struct _Unique_if<T[N]>
00052     {
00053         typedef void _Known_bound;
00054     };
00055
00056     template <class T, class... Args>
00057     typename _Unique_if<T>::_Single_object
00058     make_unique(Args&&... args)
00059     {
00060         return unique_ptr<T>(new T(std::forward<Args>(args)...));
00061     }
00062
00063     template <class T>
00064     typename _Unique_if<T>::_Unknown_bound
00065     make_unique(size_t n)
00066     {
00067         typedef typename remove_extent<T>::type U;
00068         return unique_ptr<T>(new U[n]());
00069     }
00070
00071     template <class T, class... Args>
00072     typename _Unique_if<T>::_Known_bound
00073     make_unique(Args&&...) = delete;
00074 } // namespace std
00075
00076 #endif // __cplusplus == 201103L
00077
00078 /** \} */
00079 /** \} */
00080 #endif // GNSS_SDR_GNSS_SDR_MAKE_UNIQUE_H

```

13.184 gnss_sdr_string_literals.h File Reference

This file implements the `""s` operator for `std::string` in C++11, and puts it into the `std::string_literals` namespace. This is already implemented in C++14, so this is only compiled when using C++11. The `.cc` file is required for avoiding the duplication of symbols.

13.184.1 Detailed Description

This file implements the `""s` operator for `std::string` in C++11, and puts it into the `std::string_literals` namespace. This is already implemented in C++14, so this is only compiled when using C++11. The `.cc` file is required for avoiding the duplication of symbols.

Author

Carles Fernandez-Prades, 2021. [cfernandez\(at\)cttc.es](mailto:cfernandez(at)cttc.es)

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [gnss_sdr_string_literals.h](#).

13.185 gnss_sdr_string_literals.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gnss_sdr_string_literals.h
00003  * \brief This file implements the ""s operator for std::string in C++11, and
00004  * puts it into the std::string_literals namespace. This is already implemented
00005  * in C++14, so this is only compiled when using C++11. The .cc file is required
00006  * for avoiding the duplication of symbols.
00007  *
00008  * \author Carles Fernandez-Prades, 2021. cfernandez(at)cttc.es
00009  *
00010  *
00011  * -----
00012  *
00013  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014  * This file is part of GNSS-SDR.
00015  *
00016  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022 #ifndef GNSS_SDR_STRING_LITERALS_H
00023 #define GNSS_SDR_STRING_LITERALS_H
00024
00025 /** \addtogroup Algorithms_Library
00026  * \{ */
00027 /** \addtogroup Algorithm_libs algorithms_libs
00028  * \{ */
00029
00030 #if __cplusplus == 201103L
00031
00032 #include <cstdint>
00033 #include <string>
00034
00035 namespace std
00036 {
00037     namespace string_literals
00038     {
00039         std::string operator"" s(const char* str, std::size_t len);
00040     } // namespace string_literals
00041 } // namespace std
00042
00043 #endif // __cplusplus == 201103L
00044
00045 /** \} */
00046 /** \} */
00047
00048 #endif // GNSS_SDR_STRING_LITERALS_H
```

13.186 gnss_signal_replica.h File Reference

This library gathers a few functions used for GNSS signal replica generation regardless of system used.

```
#include <complex>
#include <cstdint>
#include <string>
#include <gsl-lite/gsl-lite.hpp>
```

Functions

- void [complex_exp_gen](#) (own::span< std::complex< float > > dest, double freq, double sampling_freq)
This function generates a complex exponential in dest.
- void [complex_exp_gen_conj](#) (own::span< std::complex< float > > dest, double freq, double sampling_freq)
This function generates a conjugate complex exponential in dest.
- void [hex_to_binary_converter](#) (own::span< int32_t > dest, char from)
This function makes a conversion from hex (the input is a char) to binary (the output are 4 ints with +1 or -1 values).
- std::string [hex_to_binary_string](#) (char from)
This function makes a conversion from hex (the input is a char) to binary (the output is a string of 4 char with 0 or 1 values).
- void [resampler](#) (const own::span< float > from, own::span< float > dest, float fs_in, float fs_out)
This function resamples a sequence of float values.
- void [resampler](#) (own::span< const std::complex< float > > from, own::span< std::complex< float > > dest, float fs_in, float fs_out)
This function resamples a sequence of complex values.

13.186.1 Detailed Description

This library gathers a few functions used for GNSS signal replica generation regardless of system used.

Author

Luis Esteve, 2012. [luis\(at\)epsilon-formacion.com](mailto:luis(at)epsilon-formacion.com)

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Definition in file [gnss_signal_replica.h](#).

13.187 gnss_signal_replica.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gnss_signal_replica.h
00003  * \brief This library gathers a few functions used for GNSS signal replica
00004  * generation regardless of system used
00005  * \author Luis Esteve, 2012. luis\(at\)epsilon-formacion.com
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GNSS_SIGNAL_REPLICA_H
00020 #define GNSS_SDR_GNSS_SIGNAL_REPLICA_H
00021
00022 #include <complex>
00023 #include <cstdint>
00024 #include <string>
00025 #if HAS_STD_SPAN
00026 #include <span>
00027 namespace own = std;
00028 #else
00029 #include <gsl-lite/gsl-lite.hpp>
```



```

00030 namespace own = gsl_lite;
00031 #endif
00032
00033 /** \addtogroup Algorithms_Library
00034  * \{ */
00035 /** \addtogroup Algorithm_libs algorithms_libs
00036  * \{ */
00037
00038
00039 /*!
00040  * \brief This function generates a complex exponential in dest.
00041  *
00042  */
00043 void complex_exp_gen(own::span<std::complex<float> dest, double freq, double sampling_freq);
00044
00045 /*!
00046  * \brief This function generates a conjugate complex exponential in dest.
00047  *
00048  */
00049 void complex_exp_gen_conj(own::span<std::complex<float> dest, double freq, double sampling_freq);
00050
00051 /*!
00052  * \brief This function makes a conversion from hex (the input is a char)
00053  * to binary (the output are 4 ints with +1 or -1 values).
00054  *
00055  */
00056 void hex_to_binary_converter(own::span<int32_t> dest, char from);
00057
00058 /*!
00059  * \brief This function makes a conversion from hex (the input is a char)
00060  * to binary (the output is a string of 4 char with 0 or 1 values).
00061  *
00062  */
00063 std::string hex_to_binary_string(char from);
00064
00065 /*!
00066  * \brief This function resamples a sequence of float values.
00067  *
00068  */
00069 void resampler(const own::span<float> from, own::span<float> dest,
00070               float fs_in, float fs_out);
00071
00072 /*!
00073  * \brief This function resamples a sequence of complex values.
00074  *
00075  */
00076 void resampler(own::span<const std::complex<float> from, own::span<std::complex<float> dest,
00077               float fs_in, float fs_out);
00078
00079
00080 /** \} */
00081 /** \} */
00082 #endif // GNSS_SDR_GNSS_SIGNAL_REPLICA_H

```

13.188 gnss_time.h File Reference

class that stores both the receiver time, relative to the receiver start and the GNSS time (absolute)
#include <cstdint>

Classes

- class [GnssTime](#)

13.188.1 Detailed Description

class that stores both the receiver time, relative to the receiver start and the GNSS time (absolute)

Author

Javier Arribas 2022. jarribas(at)cttc.es

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Definition in file [gnss_time.h](#).

13.189 gnss_time.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gnss_time.h
00003  * \brief class that stores both the receiver time, relative to the receiver start and the GNSS time
00004  * \author Javier Arribas 2022. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GNSS_TIME_H
00019 #define GNSS_SDR_GNSS_TIME_H
00020
00021 #include <stdint>
00022
00023 class GnssTime
00024 {
00025 public:
00026     double rx_time;
00027     int week;           /*!< GPS week number (since January 1980) */
00028     int tow_ms;         /* time of week [ms]*/
00029     double tow_ms_fraction; /* tow ms fractional part [ms]*/
00030 };
00031
00032 #endif

```

13.190 gps_l2c_signal_replica.h File Reference

This file implements signal generators for GPS L2C signals.

```

#include <complex>
#include <stdint>
#include <gsl-lite/gsl-lite.hpp>

```

Functions

- void [gps_l2c_m_code_gen_complex](#) (own::span< std::complex< float > > dest, uint32_t prn)
Generates complex GPS L2C M code for the desired SV ID.
- void [gps_l2c_m_code_gen_float](#) (own::span< float > dest, uint32_t prn)
Generates float GPS L2C M code for the desired SV ID.
- void [gps_l2c_m_code_gen_float_cl_zeroed](#) (own::span< float > dest, uint32_t prn)
Generates float GPS L2C M code with double chip rate and L component zeroed for the desired SV ID.
- void [gps_l2c_m_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq)
Generates complex GPS L2C M code for the desired SV ID, and sampled to specific sampling frequency.
- void [gps_l2c_m_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq, bool cl_zeroed)
Generates complex GPS L2C M code for the desired SV ID, and sampled to specific sampling frequency, optionally zeroing CL slots.

13.190.1 Detailed Description

This file implements signal generators for GPS L2C signals.

Author

Javier Arribas, 2015. jarribas(at)cttc.es

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 Definition in file [gps_l2c_signal_replica.h](#).

13.191 gps_l2c_signal_replica.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gps_l2c_signal_replica.h
00003  * \brief This file implements signal generators for GPS L2C signals
00004  * \author Javier Arribas, 2015. jarribas(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GPS_L2C_SIGNAL_REPLICA_H
00019 #define GNSS_SDR_GPS_L2C_SIGNAL_REPLICA_H
00020
00021 #include <complex>
00022 #include <cstdint>
00023 #if HAS_STD_SPAN
00024 #include <span>
00025 namespace own = std;
00026 #else
00027 #include <gsl-lite/gsl-lite.hpp>
00028 namespace own = gsl_lite;
00029 #endif
00030
00031 /** \addtogroup Algorithms_Library
00032  * \{ */
00033 /** \addtogroup Algorithm_libs algorithms_libs
00034  * \{ */
00035
00036
00037 /*! Generates complex GPS L2C M code for the desired SV ID
00038 void gps_l2c_m_code_gen_complex(own::span<std::complex<float>> dest, uint32_t prn);
00039
00040 /*! Generates float GPS L2C M code for the desired SV ID
00041 void gps_l2c_m_code_gen_float(own::span<float> dest, uint32_t prn);
00042
00043 /*! Generates float GPS L2C M code with double chip rate and L component zeroed for the desired SV ID
00044 void gps_l2c_m_code_gen_float_cl_zeroed(own::span<float> dest, uint32_t prn);
00045
00046
00047 /*! Generates complex GPS L2C M code for the desired SV ID, and sampled to specific sampling frequency
00048 void gps_l2c_m_code_gen_complex_sampled(own::span<std::complex<float>> dest, uint32_t prn, int32_t
    sampling_freq);
00049
00050 /*! Generates complex GPS L2C M code for the desired SV ID, and sampled to specific sampling
    frequency, optionally zeroing CL slots
00051 void gps_l2c_m_code_gen_complex_sampled(own::span<std::complex<float>> dest, uint32_t prn, int32_t
    sampling_freq, bool cl_zeroed);
00052
00053 /** \} */
00054 /** \} */
00055 #endif // GNSS_SDR_GPS_L2C_SIGNAL_REPLICA_H

```

13.192 gps_l5_signal_replica.h File Reference

This file implements signal generators for GPS L5 signals.

```

#include <complex>
#include <cstdint>
#include <gsl-lite/gsl-lite.hpp>

```

Functions

- void [gps_l5i_code_gen_complex](#) (own::span< std::complex< float > > dest, uint32_t prn)
Generates complex GPS L5I code for the desired SV ID.
- void [gps_l5i_code_gen_float](#) (own::span< float > dest, uint32_t prn)
Generates real GPS L5I code for the desired SV ID.
- void [gps_l5q_code_gen_complex](#) (own::span< std::complex< float > > dest, uint32_t prn)
Generates complex GPS L5Q code for the desired SV ID.
- void [gps_l5q_code_gen_float](#) (own::span< float > dest, uint32_t prn)
Generates real GPS L5Q code for the desired SV ID.
- void [gps_l5i_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq)
Generates complex GPS L5I code for the desired SV ID, and sampled to specific sampling frequency.
- void [gps_l5q_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq)
Generates complex GPS L5Q code for the desired SV ID, and sampled to specific sampling frequency.

13.192.1 Detailed Description

This file implements signal generators for GPS L5 signals.

Author

Javier Arribas, 2017. jarribas(at)cttc.es

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Definition in file [gps_l5_signal_replica.h](#).

13.193 gps_l5_signal_replica.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gps_l5_signal_replica.h
00003  * \brief This file implements signal generators for GPS L5 signals
00004  * \author Javier Arribas, 2017. jarribas(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GPS_L5_SIGNAL_REPLICA_H
00019 #define GNSS_SDR_GPS_L5_SIGNAL_REPLICA_H
00020
00021 #include <complex>
00022 #include <cstdint>
00023 #if HAS_STD_SPAN
00024 #include <span>
00025 namespace own = std;
00026 #else
00027 #include <gsl-lite/gsl-lite.hpp>
00028 namespace own = gsl_lite;
00029 #endif
00030
00031 /** \addtogroup Algorithms_Library
00032  * \{ */
00033 /** \addtogroup Algorithm_libs algorithms_libs
00034  * \{ */
00035
00036
00037 /*! Generates complex GPS L5I code for the desired SV ID
00038 void gps\_l5i\_code\_gen\_complex (own::span<std::complex<float> dest, uint32_t prn);
```

```

00039
00040 ///! Generates real GPS L5I code for the desired SV ID
00041 void gps_l5i_code_gen_float(own::span<float> dest, uint32_t prn);
00042
00043 ///! Generates complex GPS L5Q code for the desired SV ID
00044 void gps_l5q_code_gen_complex(own::span<std::complex<float>> dest, uint32_t prn);
00045
00046 ///! Generates real GPS L5Q code for the desired SV ID
00047 void gps_l5q_code_gen_float(own::span<float> dest, uint32_t prn);
00048
00049 ///! Generates complex GPS L5I code for the desired SV ID, and sampled to specific sampling frequency
00050 void gps_l5i_code_gen_complex_sampled(own::span<std::complex<float>> dest, uint32_t prn, int32_t
    sampling_freq);
00051
00052 ///! Generates complex GPS L5Q code for the desired SV ID, and sampled to specific sampling frequency
00053 void gps_l5q_code_gen_complex_sampled(own::span<std::complex<float>> dest, uint32_t prn, int32_t
    sampling_freq);
00054
00055
00056 /** \} */
00057 /** \} */
00058 #endif // GNSS_SDR_GPS_L5_SIGNAL_REPLICA_H

```

13.194 gps_sdr_signal_replica.h File Reference

This file implements functions for GPS L1 C/A signal replica generation.

```

#include <complex>
#include <cstdint>
#include <gsl-lite/gsl-lite.hpp>

```

Functions

- void `gps_l1_ca_code_gen_int` (own::span< int32_t > dest, int32_t prn, uint32_t chip_shift)
Generates int GPS L1 C/A code for the desired SV ID and code shift.
- void `gps_l1_ca_code_gen_float` (own::span< float > dest, int32_t prn, uint32_t chip_shift)
Generates float GPS L1 C/A code for the desired SV ID and code shift.
- void `gps_l1_ca_code_gen_complex` (own::span< std::complex< float > > dest, int32_t prn, uint32_t chip_↵_shift)
Generates complex GPS L1 C/A code for the desired SV ID and code shift.
- void `gps_l1_ca_code_gen_complex_sampled` (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq, uint32_t chip_shift)
Generates complex GPS L1 C/A code for the desired SV ID and code shift, and sampled to specific sampling frequency.

13.194.1 Detailed Description

This file implements functions for GPS L1 C/A signal replica generation.

Author

Javier Arribas, 2011. jarribas(at)cttc.es

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 Definition in file [gps_sdr_signal_replica.h](#).

13.195 gps_sdr_signal_replica.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gps_sdr_signal_replica.h
00003  * \brief This file implements functions for GPS L1 C/A signal replica
00004  * generation
00005  * \author Javier Arribas, 2011. jarribas(at)cttc.es
00006  *

```

```

00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GPS_SDR_SIGNAL_REPLICA_H
00020 #define GNSS_SDR_GPS_SDR_SIGNAL_REPLICA_H
00021
00022 #include <complex>
00023 #include <stdint>
00024 #if HAS_STD_SPAN
00025 #include <span>
00026 namespace own = std;
00027 #else
00028 #include <gsl-lite/gsl-lite.hpp>
00029 namespace own = gsl_lite;
00030 #endif
00031
00032 /** \addtogroup Algorithms_Library
00033  * \{ */
00034 /** \addtogroup Algorithm_libs algorithms_libs
00035  * \{ */
00036
00037
00038 /** Generates int GPS L1 C/A code for the desired SV ID and code shift
00039 void gps_l1_ca_code_gen_int(own::span<int32_t> dest, int32_t prn, uint32_t chip_shift);
00040
00041 /** Generates float GPS L1 C/A code for the desired SV ID and code shift
00042 void gps_l1_ca_code_gen_float(own::span<float> dest, int32_t prn, uint32_t chip_shift);
00043
00044 /** Generates complex GPS L1 C/A code for the desired SV ID and code shift
00045 void gps_l1_ca_code_gen_complex(own::span<std::complex<float>> dest, int32_t prn, uint32_t chip_shift);
00046
00047 /** Generates complex GPS L1 C/A code for the desired SV ID and code shift, and sampled to specific
    sampling frequency
00048 void gps_l1_ca_code_gen_complex_sampled(own::span<std::complex<float>> dest, uint32_t prn, int32_t
    sampling_freq, uint32_t chip_shift);
00049
00050
00051 /** \} */
00052 /** \} */
00053 #endif // GNSS_SDR_GPS_SDR_SIGNAL_REPLICA_H

```

13.196 item_type_helpers.h File Reference

Utility functions for converting between item types.

```

#include <stdint>
#include <functional>
#include <string>

```

Typedefs

- using [item_type_converter_t](#) = std::function<void(void *, const void *, uint32_t)>

Functions

- bool [item_type_valid](#) (const std::string &item_type)
Check if a string is a valid item type.
- size_t [item_type_size](#) (const std::string &item_type)
Return the size of the given item type, or zero if unknown.
- bool [item_type_is_complex](#) (const std::string &item_type)
Determine if an item_type is complex.
- item_type_converter_t [make_vector_converter](#) (const std::string &input_type, const std::string &output_type)
Create a function to convert an array of input_type to an array of output_type.

13.196.1 Detailed Description

Utility functions for converting between item types.

Authors

- Cillian O'Driscoll, 2019. cillian.odriscoll(at)gmail.com

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 Definition in file [item_type_helpers.h](#).

13.197 item_type_helpers.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file item_type_helpers.h
00003  * \brief Utility functions for converting between item types
00004  * \authors <ul>
00005  *         <li> Cillian O'Driscoll, 2019. cillian.odriscoll(at)gmail.com
00006  *         </li>
00007  *
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_ITEM_TYPE_HELPERS_H
00021 #define GNSS_SDR_ITEM_TYPE_HELPERS_H
00022
00023
00024 #include <cstdint>
00025 #include <functional>
00026 #include <string>
00027
00028 /** \addtogroup Algorithms_Library
00029  * \{ */
00030 /** \addtogroup Algorithm_libs algorithms_libs
00031  * \{ */
00032
00033
00034 using item_type_converter_t = std::function<void(void *, const void *, uint32_t)>;
00035
00036 /*!
00037  * \brief Check if a string is a valid item type
00038  *
00039  * \description Valid item types include:
00040  *         "byte", "short", "float", "ibyte", "ishort", "cbyte", "cshort", "gr_complex"
00041  *
00042  */
00043 bool item_type_valid(const std::string &item_type);
00044
00045 /*!
00046  * \brief Return the size of the given item type, or zero if unknown
00047  */
00048 size_t item_type_size(const std::string &item_type);
00049
00050 /*!
00051  * \brief Determine if an item_type is complex
00052  */
00053 bool item_type_is_complex(const std::string &item_type);
00054
00055 /*!
00056  * \brief Create a function to convert an array of input_type to an array of output_type
00057  *
00058  * \description Provides a generic interface to generate conversion functions for mapping
00059  *         arrays of items.
00060  *
00061  * \param input_type - String representation of the input item type
00062  * \param output_type - String representation of the output item type
00063  *
00064  * The item types accepted are:
00065  *
00066  * 1. "byte" for 8 bit integers
00067  * 2. "cbyte" for complex (interleaved) 8 bit integers

```

```

00068 * 4. "ibyte" for complex (interleaved) 8 bit integers
00069 * 4. "short" for 16 bit integers
00070 * 5. "cshort" for complex (interleaved) 16 bit integers
00071 * 6. "ishort" for complex (interleaved) 16 bit integers
00072 * 7. "float" for 32 bit floating point values
00073 * 8. "gr_complex" for complex (interleaved) 32 bit floating point values
00074 *
00075 * \returns A function object with the following prototype:
00076 * void convert_fun( void *dest, void *src, int num_items );
00077 *
00078 */
00079 item_type_converter_t make_vector_converter(const std::string &input_type,
00080 const std::string &output_type);
00081
00082
00083 /** \} */
00084 /** \} */
00085 #endif // GNSS_SDR_ITEM_TYPE_HELPERS_H

```

13.198 matlab_writer_helper.h File Reference

Utility functions for logging to a matlab file.

```

#include <matio.h>
#include <array>

```

Classes

- struct [matlab_type_traits< int32_t >](#)
- struct [matlab_type_traits< uint32_t >](#)
- struct [matlab_type_traits< uint8_t >](#)
- struct [matlab_type_traits< int64_t >](#)
- struct [matlab_type_traits< uint64_t >](#)
- struct [matlab_type_traits< float >](#)
- struct [matlab_type_traits< double >](#)

Functions

- template<size_t Rank, typename T>
void [write_matlab_var](#) (const char *name, T data, mat_t *matfp, std::array< size_t, 2 > &dims)
- template<size_t Rank, typename T>
void [write_matlab_var](#) (const char *name, T *data, mat_t *matfp, std::array< size_t, 2 > &dims)

13.198.1 Detailed Description

Utility functions for logging to a matlab file.

Authors

- Mathieu Favreau, 2025. [favreau.mathieu\(at\)hotmail.com](mailto:favreau.mathieu(at)hotmail.com)

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Definition in file [matlab_writer_helper.h](#).

13.198.2 Function Documentation

13.198.2.1 write_matlab_var() [1/2]

```

template<size_t Rank, typename T>
void write_matlab_var (
    const char * name,
    T * data,
    mat_t * matfp,
    std::array< size_t, 2 > & dims)

```

Definition at line 89 of file [matlab_writer_helper.h](#).

13.198.2.2 write_matlab_var() [2/2]

```
template<size_t Rank, typename T>
void write_matlab_var (
    const char * name,
    T data,
    mat_t * matfp,
    std::array< size_t, 2 > & dims)
```

Definition at line 79 of file [matlab_writer_helper.h](#).

13.199 matlab_writer_helper.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file matlab_writer_helper.h
00003  * \brief Utility functions for logging to a matlab file
00004  * \authors <ul>
00005  *         <li> Mathieu Favreau, 2025. favreau.mathieu(at)hotmail.com
00006  *         </ul>
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2025 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_MATLAB_WRITTER_HELPER_H
00020 #define GNSS_SDR_MATLAB_WRITTER_HELPER_H
00021
00022 #include <matio.h>
00023 #include <array>
00024
00025 template <typename T>
00026 struct matlab_type_traits;
00027
00028 template <>
00029 struct matlab_type_traits<int32_t>
00030 {
00031     static constexpr matio_classes class_type = MAT_C_INT32;
00032     static constexpr matio_types data_type = MAT_T_INT32;
00033 };
00034
00035 template <>
00036 struct matlab_type_traits<uint32_t>
00037 {
00038     static constexpr matio_classes class_type = MAT_C_UINT32;
00039     static constexpr matio_types data_type = MAT_T_UINT32;
00040 };
00041
00042 template <>
00043 struct matlab_type_traits<uint8_t>
00044 {
00045     static constexpr matio_classes class_type = MAT_C_UINT8;
00046     static constexpr matio_types data_type = MAT_T_UINT8;
00047 };
00048
00049 template <>
00050 struct matlab_type_traits<int64_t>
00051 {
00052     static constexpr matio_classes class_type = MAT_C_INT64;
00053     static constexpr matio_types data_type = MAT_T_INT64;
00054 };
00055
00056 template <>
00057 struct matlab_type_traits<uint64_t>
00058 {
00059     static constexpr matio_classes class_type = MAT_C_UINT64;
00060     static constexpr matio_types data_type = MAT_T_UINT64;
00061 };
00062
00063 template <>
00064 struct matlab_type_traits<float>
00065 {
00066     static constexpr matio_classes class_type = MAT_C_SINGLE;
00067     static constexpr matio_types data_type = MAT_T_SINGLE;
```

```

00068 };
00069
00070 template <>
00071 struct matlab_type_traits<double>
00072 {
00073     static constexpr matio_classes class_type = MAT_C_DOUBLE;
00074     static constexpr matio_types data_type = MAT_T_DOUBLE;
00075 };
00076
00077
00078 template <size_t Rank, typename T>
00079 void write_matlab_var(const char* name, T data, mat_t* matfp, std::array<size_t, 2>& dims)
00080 {
00081     using traits = matlab_type_traits<T>;
00082     matvar_t* matvar = Mat_VarCreate(name, traits::class_type, traits::data_type, Rank, dims.data(),
&data, 0);
00083     Mat_VarWrite(matfp, matvar, MAT_COMPRESSION_ZLIB);
00084     Mat_VarFree(matvar);
00085 }
00086
00087
00088 template <size_t Rank, typename T>
00089 void write_matlab_var(const char* name, T* data, mat_t* matfp, std::array<size_t, 2>& dims)
00090 {
00091     using traits = matlab_type_traits<T>;
00092     matvar_t* matvar = Mat_VarCreate(name, traits::class_type, traits::data_type, Rank, dims.data(),
data, 0);
00093     Mat_VarWrite(matfp, matvar, MAT_COMPRESSION_ZLIB);
00094     Mat_VarFree(matvar);
00095 }
00096
00097 #endif // GNSS_SDR_NAV_MESSAGE_MONITOR_H

```

13.200 cIFFT.h File Reference

FFT in OpenCL.

```
#include <stdio.h>
```

```
#include <CL/cl.h>
```

Classes

- struct [cIFFT_Dim3](#)
- struct [cIFFT_SplitComplex](#)
- struct [cIFFT_Complex](#)

Typedefs

- typedef void * [cIFFT_Plan](#)

Enumerations

- enum [cIFFT_Direction](#) { [cIFFT_Forward](#) = -1 , [cIFFT_Inverse](#) = 1 }
- enum [cIFFT_Dimension](#) { [cIFFT_1D](#) = 0 , [cIFFT_2D](#) = 1 , [cIFFT_3D](#) = 3 }
- enum [cIFFT_DataFormat](#) { [cIFFT_SplitComplexFormat](#) = 0 , [cIFFT_InterleavedComplexFormat](#) = 1 }

Functions

- [cIFFT_Plan](#) [cIFFT_CreatePlan](#) (cl_context context, [cIFFT_Dim3](#) n, [cIFFT_Dimension](#) dim, [cIFFT_DataFormat](#) dataFormat, cl_int *error_code)
- void [cIFFT_DestroyPlan](#) ([cIFFT_Plan](#) plan)
- cl_int [cIFFT_ExecuteInterleaved](#) (cl_command_queue queue, [cIFFT_Plan](#) plan, cl_int batchSize, [cIFFT_Direction](#) dir, cl_mem data_in, cl_mem data_out, cl_int num_events, cl_event *event_list, cl_event *event)
- cl_int [cIFFT_ExecutePlannar](#) (cl_command_queue queue, [cIFFT_Plan](#) plan, cl_int batchSize, [cIFFT_Direction](#) dir, cl_mem data_in_real, cl_mem data_in_imag, cl_mem data_out_real, cl_mem data_out_imag, cl_int num_events, cl_event *event_list, cl_event *event)
- cl_int [cIFFT_1DTwistInterleaved](#) ([cIFFT_Plan](#) Plan, cl_command_queue queue, cl_mem array, size_t numRows, size_t numCols, size_t startRow, size_t rowsToProcess, [cIFFT_Direction](#) dir)

- `cl_int clFFT_1DTwistPlannar` (`clFFT_Plan Plan`, `cl_command_queue queue`, `cl_mem array_real`, `cl_mem array_imag`, `size_t numRows`, `size_t numCols`, `size_t startRow`, `size_t rowsToProcess`, `clFFT_Direction dir`)
- `void clFFT_DumpPlan` (`clFFT_Plan plan`, `FILE *file`)

13.200.1 Detailed Description

FFT in OpenCL.

Version: <1.0>

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Definition in file [clFFT.h](#).

13.200.2 Typedef Documentation

13.200.2.1 clFFT_Plan

```
typedef void* clFFT_Plan
```

Definition at line 71 of file [clFFT.h](#).

13.200.3 Enumeration Type Documentation

13.200.3.1 clFFT_DataFormat

```
enum clFFT_DataFormat
```

Definition at line 46 of file [clFFT.h](#).

13.200.3.2 clFFT_Dimension

```
enum clFFT_Dimension
```

Definition at line 38 of file [clFFT.h](#).

13.200.3.3 clFFT_Direction

```
enum clFFT_Direction
```

Definition at line 31 of file [clFFT.h](#).

13.201 clFFT.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file clFFT.h
00003  * \brief FFT in OpenCL
00004  *
00005  *
00006  * Version:    <1.0>
00007  *
00008  * Copyright ( C ) 2008 Apple Inc. All Rights Reserved.
00009  * SPDX-License-Identifier: LicenseRef-Apple-Permissive
00010  *
00011  */
00012
00013 #ifndef __CLFFT_H
00014 #define __CLFFT_H
00015
00016 #ifdef __cplusplus
00017 extern "C"
00018 {
00019 #endif
00020
00021 #include <stdio.h>
00022
00023 #ifdef __APPLE__
00024 #define CL_SILENCE_DEPRECATION
00025 #include <OpenCL/opencl.h>
00026 #else
00027 #include <CL/cl.h>
00028 #endif
00029
00030 // XForm type
00031 typedef enum
```

```

00032     {
00033         clFFT_Forward = -1,
00034         clFFT_Inverse = 1
00035     } clFFT_Direction;
00036
00037     // XForm dimension
00038     typedef enum
00039     {
00040         clFFT_1D = 0,
00041         clFFT_2D = 1,
00042         clFFT_3D = 3
00043     } clFFT_Dimension;
00044
00045     // XForm Data type
00046     typedef enum
00047     {
00048         clFFT_SplitComplexFormat = 0,
00049         clFFT_InterleavedComplexFormat = 1
00050     } clFFT_DataFormat;
00051
00052     typedef struct
00053     {
00054         unsigned int x;
00055         unsigned int y;
00056         unsigned int z;
00057     } clFFT_Dim3;
00058
00059     typedef struct
00060     {
00061         float *real;
00062         float *imag;
00063     } clFFT_SplitComplex;
00064
00065     typedef struct
00066     {
00067         float real;
00068         float imag;
00069     } clFFT_Complex;
00070
00071     typedef void *clFFT_Plan;
00072
00073     clFFT_Plan clFFT_CreatePlan(cl_context context, clFFT_Dim3 n, clFFT_Dimension dim,
clFFT_DataFormat dataFormat, cl_int *error_code);
00074
00075     void clFFT_DestroyPlan(clFFT_Plan plan);
00076
00077     cl_int clFFT_ExecuteInterleaved(cl_command_queue queue, clFFT_Plan plan, cl_int batchSize,
clFFT_Direction dir,
00078         cl_mem data_in, cl_mem data_out,
00079         cl_int num_events, cl_event *event_list, cl_event *event);
00080
00081     cl_int clFFT_ExecutePlannar(cl_command_queue queue, clFFT_Plan plan, cl_int batchSize,
clFFT_Direction dir,
00082         cl_mem data_in_real, cl_mem data_in_imag, cl_mem data_out_real, cl_mem data_out_imag,
00083         cl_int num_events, cl_event *event_list, cl_event *event);
00084
00085     cl_int clFFT_1DTwistInterleaved(clFFT_Plan Plan, cl_command_queue queue, cl_mem array,
size_t numRows, size_t numCols, size_t startRow, size_t rowsToProcess, clFFT_Direction dir);
00086
00087
00088     cl_int clFFT_1DTwistPlannar(clFFT_Plan Plan, cl_command_queue queue, cl_mem array_real, cl_mem
array_imag,
00089         size_t numRows, size_t numCols, size_t startRow, size_t rowsToProcess, clFFT_Direction dir);
00090
00091     void clFFT_DumpPlan(clFFT_Plan plan, FILE *file);
00092
00093 #ifdef __cplusplus
00094 }
00095 #endif
00096 #endif
00097
00098 #endif

```

13.202 fft_base_kernels.h File Reference

FFT base kernels for OpenCL.

```
#include <string>
```

13.202.1 Detailed Description

FFT base kernels for OpenCL.

Version: <1.0>

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Definition in file [fft_base_kernels.h](#).

13.203 fft_base_kernels.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file fft_base_kernels.h
00003  * \brief FFT base kernels for OpenCL
00004  *
00005  *
00006  * Version:    <1.0>
00007  *
00008  * Copyright ( C ) 2008 Apple Inc. All Rights Reserved.
00009  * SPDX-License-Identifier: LicenseRef-Apple-Permissive
00010  *
00011  */
00012
00013
00014 #ifndef __CL_FFT_BASE_KERNELS_
00015 #define __CL_FFT_BASE_KERNELS_
00016
00017 #include <string>
00018
00019 using namespace std;
00020
00021 static string baseKernels = string(
00022     "#ifndef M_PI\n"
00023     "#define M_PI 0x1.921fb54442d18p+1\n"
00024     "#endif\n"
00025     "#define complexMul(a,b) ((float2) (mad(-(a).y, (b).y, (a).x * (b).x), mad((a).y, (b).x, (a).x * (b).y))\n"
00026     "#define conj(a) ((float2) ((a).x, -(a).y))\n"
00027     "#define conjTransp(a) ((float2) (-(a).y, (a).x))\n"
00028     "\n"
00029     "#define fftKernel2(a,dir) \\\n"
00030     "{ \\\n"
00031     "    float2 c = (a)[0];    \\\n"
00032     "    (a)[0] = c + (a)[1];  \\\n"
00033     "    (a)[1] = c - (a)[1];  \\\n"
00034     "}\n"
00035     "\n"
00036     "#define fftKernel2S(d1,d2,dir) \\\n"
00037     "{ \\\n"
00038     "    float2 c = (d1);    \\\n"
00039     "    (d1) = c + (d2);    \\\n"
00040     "    (d2) = c - (d2);    \\\n"
00041     "}\n"
00042     "\n"
00043     "#define fftKernel4(a,dir) \\\n"
00044     "{ \\\n"
00045     "    fftKernel2S((a)[0], (a)[2], dir); \\\n"
00046     "    fftKernel2S((a)[1], (a)[3], dir); \\\n"
00047     "    fftKernel2S((a)[0], (a)[1], dir); \\\n"
00048     "    (a)[3] = (float2) (dir)*(conjTransp((a)[3])); \\\n"
00049     "    fftKernel2S((a)[2], (a)[3], dir); \\\n"
00050     "    float2 c = (a)[1]; \\\n"
00051     "    (a)[1] = (a)[2]; \\\n"
00052     "    (a)[2] = c; \\\n"
00053     "}\n"
00054     "\n"
00055     "#define fftKernel4s(a0,a1,a2,a3,dir) \\\n"
00056     "{ \\\n"
00057     "    fftKernel2S((a0), (a2), dir); \\\n"
00058     "    fftKernel2S((a1), (a3), dir); \\\n"
00059     "    fftKernel2S((a0), (a1), dir); \\\n"
00060     "    (a3) = (float2) (dir)*(conjTransp((a3))); \\\n"
00061     "    fftKernel2S((a2), (a3), dir); \\\n"
00062     "    float2 c = (a1); \\\n"
00063     "    (a1) = (a2); \\\n"
00064     "    (a2) = c; \\\n"
00065     "}\n"
00066     "\n"
00067     "#define bitreverse8(a) \\\n"
00068     "{ \\\n"
00069     "    float2 c; \\\n"
00070     "    c = (a)[1]; \\\n"
00071     "    (a)[1] = (a)[4]; \\\n"
00072     "    (a)[4] = c; \\\n"
00073     "    c = (a)[3]; \\\n"
00074     "    (a)[3] = (a)[6]; \\\n"
00075     "    (a)[6] = c; \\\n"

```

```

00076     "}\n"
00077     "\n"
00078     "#define fftKernel8(a,dir) \\\n"
00079     "{ \\\n"
00080     "    const float2 w1 = (float2)(0x1.6a09e6p-1f, dir*0x1.6a09e6p-1f); \\\n"
00081     "    const float2 w3 = (float2)(-0x1.6a09e6p-1f, dir*0x1.6a09e6p-1f); \\\n"
00082     "    float2 c; \\\n"
00083     "    fftKernel2S((a)[0], (a)[4], dir); \\\n"
00084     "    fftKernel2S((a)[1], (a)[5], dir); \\\n"
00085     "    fftKernel2S((a)[2], (a)[6], dir); \\\n"
00086     "    fftKernel2S((a)[3], (a)[7], dir); \\\n"
00087     "    (a)[5] = complexMul(w1, (a)[5]); \\\n"
00088     "    (a)[6] = (float2)(dir)*(conjTransp((a)[6])); \\\n"
00089     "    (a)[7] = complexMul(w3, (a)[7]); \\\n"
00090     "    fftKernel2S((a)[0], (a)[2], dir); \\\n"
00091     "    fftKernel2S((a)[1], (a)[3], dir); \\\n"
00092     "    fftKernel2S((a)[4], (a)[6], dir); \\\n"
00093     "    fftKernel2S((a)[5], (a)[7], dir); \\\n"
00094     "    (a)[3] = (float2)(dir)*(conjTransp((a)[3])); \\\n"
00095     "    (a)[7] = (float2)(dir)*(conjTransp((a)[7])); \\\n"
00096     "    fftKernel2S((a)[0], (a)[1], dir); \\\n"
00097     "    fftKernel2S((a)[2], (a)[3], dir); \\\n"
00098     "    fftKernel2S((a)[4], (a)[5], dir); \\\n"
00099     "    fftKernel2S((a)[6], (a)[7], dir); \\\n"
00100     "    bitreverse8((a)); \\\n"
00101     "}\n"
00102     "\n"
00103     "#define bitreverse4x4(a) \\\n"
00104     "{ \\\n"
00105     "    float2 c; \\\n"
00106     "    c = (a)[1]; (a)[1] = (a)[4]; (a)[4] = c; \\\n"
00107     "    c = (a)[2]; (a)[2] = (a)[8]; (a)[8] = c; \\\n"
00108     "    c = (a)[3]; (a)[3] = (a)[12]; (a)[12] = c; \\\n"
00109     "    c = (a)[6]; (a)[6] = (a)[9]; (a)[9] = c; \\\n"
00110     "    c = (a)[7]; (a)[7] = (a)[13]; (a)[13] = c; \\\n"
00111     "    c = (a)[11]; (a)[11] = (a)[14]; (a)[14] = c; \\\n"
00112     "}\n"
00113     "\n"
00114     "#define fftKernel16(a,dir) \\\n"
00115     "{ \\\n"
00116     "    const float w0 = 0x1.d906bcp-1f; \\\n"
00117     "    const float w1 = 0x1.87de2ap-2f; \\\n"
00118     "    const float w2 = 0x1.6a09e6p-1f; \\\n"
00119     "    fftKernel4s((a)[0], (a)[4], (a)[8], (a)[12], dir); \\\n"
00120     "    fftKernel4s((a)[1], (a)[5], (a)[9], (a)[13], dir); \\\n"
00121     "    fftKernel4s((a)[2], (a)[6], (a)[10], (a)[14], dir); \\\n"
00122     "    fftKernel4s((a)[3], (a)[7], (a)[11], (a)[15], dir); \\\n"
00123     "    (a)[5] = complexMul((a)[5], (float2)(w0, dir*w1)); \\\n"
00124     "    (a)[6] = complexMul((a)[6], (float2)(w2, dir*w2)); \\\n"
00125     "    (a)[7] = complexMul((a)[7], (float2)(w1, dir*w0)); \\\n"
00126     "    (a)[9] = complexMul((a)[9], (float2)(w2, dir*w2)); \\\n"
00127     "    (a)[10] = (float2)(dir)*(conjTransp((a)[10])); \\\n"
00128     "    (a)[11] = complexMul((a)[11], (float2)(-w2, dir*w2)); \\\n"
00129     "    (a)[13] = complexMul((a)[13], (float2)(w1, dir*w0)); \\\n"
00130     "    (a)[14] = complexMul((a)[14], (float2)(-w2, dir*w2)); \\\n"
00131     "    (a)[15] = complexMul((a)[15], (float2)(-w0, dir*-w1)); \\\n"
00132     "    fftKernel4((a), dir); \\\n"
00133     "    fftKernel4((a) + 4, dir); \\\n"
00134     "    fftKernel4((a) + 8, dir); \\\n"
00135     "    fftKernel4((a) + 12, dir); \\\n"
00136     "    bitreverse4x4((a)); \\\n"
00137     "}\n"
00138     "\n"
00139     "#define bitreverse32(a) \\\n"
00140     "{ \\\n"
00141     "    float2 c1, c2; \\\n"
00142     "    c1 = (a)[2]; (a)[2] = (a)[1]; c2 = (a)[4]; (a)[4] = c1; c1 = (a)[8]; (a)[8] = c2;
c2 = (a)[16]; (a)[16] = c1; (a)[1] = c2; \\\n"
00143     "    c1 = (a)[6]; (a)[6] = (a)[3]; c2 = (a)[12]; (a)[12] = c1; c1 = (a)[24]; (a)[24] = c2;
c2 = (a)[17]; (a)[17] = c1; (a)[3] = c2; \\\n"
00144     "    c1 = (a)[10]; (a)[10] = (a)[5]; c2 = (a)[20]; (a)[20] = c1; c1 = (a)[9]; (a)[9] = c2;
c2 = (a)[18]; (a)[18] = c1; (a)[5] = c2; \\\n"
00145     "    c1 = (a)[14]; (a)[14] = (a)[7]; c2 = (a)[28]; (a)[28] = c1; c1 = (a)[25]; (a)[25] = c2;
c2 = (a)[19]; (a)[19] = c1; (a)[7] = c2; \\\n"
00146     "    c1 = (a)[22]; (a)[22] = (a)[11]; c2 = (a)[13]; (a)[13] = c1; c1 = (a)[26]; (a)[26] = c2;
c2 = (a)[21]; (a)[21] = c1; (a)[11] = c2; \\\n"
00147     "    c1 = (a)[30]; (a)[30] = (a)[15]; c2 = (a)[29]; (a)[29] = c1; c1 = (a)[27]; (a)[27] = c2;
c2 = (a)[23]; (a)[23] = c1; (a)[15] = c2; \\\n"
00148     "}\n"
00149     "\n"
00150     "#define fftKernel32(a,dir) \\\n"
00151     "{ \\\n"
00152     "    fftKernel2S((a)[0], (a)[16], dir); \\\n"
00153     "    fftKernel2S((a)[1], (a)[17], dir); \\\n"
00154     "    fftKernel2S((a)[2], (a)[18], dir); \\\n"
00155     "    fftKernel2S((a)[3], (a)[19], dir); \\\n"
00156     "    fftKernel2S((a)[4], (a)[20], dir); \\\n"

```

```

00157     "    fftKernel2S((a)[5], (a)[21], dir); \\n"
00158     "    fftKernel2S((a)[6], (a)[22], dir); \\n"
00159     "    fftKernel2S((a)[7], (a)[23], dir); \\n"
00160     "    fftKernel2S((a)[8], (a)[24], dir); \\n"
00161     "    fftKernel2S((a)[9], (a)[25], dir); \\n"
00162     "    fftKernel2S((a)[10], (a)[26], dir); \\n"
00163     "    fftKernel2S((a)[11], (a)[27], dir); \\n"
00164     "    fftKernel2S((a)[12], (a)[28], dir); \\n"
00165     "    fftKernel2S((a)[13], (a)[29], dir); \\n"
00166     "    fftKernel2S((a)[14], (a)[30], dir); \\n"
00167     "    fftKernel2S((a)[15], (a)[31], dir); \\n"
00168     "    (a)[17] = complexMul((a)[17], (float2)(0x1.f6297cp-1f, dir*0x1.8f8b84p-3f)); \\n"
00169     "    (a)[18] = complexMul((a)[18], (float2)(0x1.d906bcp-1f, dir*0x1.87de2ap-2f)); \\n"
00170     "    (a)[19] = complexMul((a)[19], (float2)(0x1.a9b662p-1f, dir*0x1.1c73b4p-1f)); \\n"
00171     "    (a)[20] = complexMul((a)[20], (float2)(0x1.6a09e6p-1f, dir*0x1.6a09e6p-1f)); \\n"
00172     "    (a)[21] = complexMul((a)[21], (float2)(0x1.1c73b4p-1f, dir*0x1.a9b662p-1f)); \\n"
00173     "    (a)[22] = complexMul((a)[22], (float2)(0x1.87de2ap-2f, dir*0x1.d906bcp-1f)); \\n"
00174     "    (a)[23] = complexMul((a)[23], (float2)(0x1.8f8b84p-3f, dir*0x1.f6297cp-1f)); \\n"
00175     "    (a)[24] = complexMul((a)[24], (float2)(0x0p+0f, dir*0x1p+0f)); \\n"
00176     "    (a)[25] = complexMul((a)[25], (float2)(-0x1.8f8b84p-3f, dir*0x1.f6297cp-1f)); \\n"
00177     "    (a)[26] = complexMul((a)[26], (float2)(-0x1.87de2ap-2f, dir*0x1.d906bcp-1f)); \\n"
00178     "    (a)[27] = complexMul((a)[27], (float2)(-0x1.1c73b4p-1f, dir*0x1.a9b662p-1f)); \\n"
00179     "    (a)[28] = complexMul((a)[28], (float2)(-0x1.6a09e6p-1f, dir*0x1.6a09e6p-1f)); \\n"
00180     "    (a)[29] = complexMul((a)[29], (float2)(-0x1.a9b662p-1f, dir*0x1.1c73b4p-1f)); \\n"
00181     "    (a)[30] = complexMul((a)[30], (float2)(-0x1.d906bcp-1f, dir*0x1.87de2ap-2f)); \\n"
00182     "    (a)[31] = complexMul((a)[31], (float2)(-0x1.f6297cp-1f, dir*0x1.8f8b84p-3f)); \\n"
00183     "    fftKernel16((a), dir); \\n"
00184     "    fftKernel16((a) + 16, dir); \\n"
00185     "    bitreverse32((a)); \\n"
00186     "j\\n\\n");
00187
00188 static string twistKernelInterleaved = string(
00189     "__kernel void \\n"
00190     "c1FFT_1DTwistInterleaved(__global float2 *in, unsigned int startRow, unsigned int numCols,
00191     unsigned int N, unsigned int numRowsToProcess, int dir) \\n"
00192     "{ \\n"
00193     "    float2 a, w; \\n"
00194     "    float ang; \\n"
00195     "    unsigned int j; \\n"
00196     "    unsigned int i = get_global_id(0); \\n"
00197     "    unsigned int startIndex = i; \\n"
00198     "    \\n"
00199     "    if(i < numCols) \\n"
00200     "    { \\n"
00201     "        for(j = 0; j < numRowsToProcess; j++) \\n"
00202     "        { \\n"
00203     "            a = in[startIndex]; \\n"
00204     "            ang = 2.0f * M_PI * dir * i * (startRow + j) / N; \\n"
00205     "            w = (float2)(native_cos(ang), native_sin(ang)); \\n"
00206     "            a = complexMul(a, w); \\n"
00207     "            in[startIndex] = a; \\n"
00208     "            startIndex += numCols; \\n"
00209     "        } \\n"
00210     "    } \\n"
00211     "} \\n\\n");
00212
00213 static string twistKernelPlannar = string(
00214     "__kernel void \\n"
00215     "c1FFT_1DTwistSplit(__global float *in_real, __global float *in_imag, unsigned int startRow,
00216     unsigned int numCols, unsigned int N, unsigned int numRowsToProcess, int dir) \\n"
00217     "{ \\n"
00218     "    float2 a, w; \\n"
00219     "    float ang; \\n"
00220     "    unsigned int j; \\n"
00221     "    unsigned int i = get_global_id(0); \\n"
00222     "    unsigned int startIndex = i; \\n"
00223     "    \\n"
00224     "    if(i < numCols) \\n"
00225     "    { \\n"
00226     "        for(j = 0; j < numRowsToProcess; j++) \\n"
00227     "        { \\n"
00228     "            a = (float2)(in_real[startIndex], in_imag[startIndex]); \\n"
00229     "            ang = 2.0f * M_PI * dir * i * (startRow + j) / N; \\n"
00230     "            w = (float2)(native_cos(ang), native_sin(ang)); \\n"
00231     "            a = complexMul(a, w); \\n"
00232     "            in_real[startIndex] = a.x; \\n"
00233     "            in_imag[startIndex] = a.y; \\n"
00234     "            startIndex += numCols; \\n"
00235     "        } \\n"
00236     "    } \\n"
00237     "} \\n\\n");
00238 #endif

```

13.204 fft_internal.h File Reference

Internals of FFT for OpenCL.

```
#include "clFFT.h"
#include <iostream>
#include <sstream>
#include <string>
```

Classes

- struct [kernel_info_t](#)
- struct [cl_fft_plan](#)

Typedefs

- typedef enum kernel_dir_t [cl_fft_kernel_dir](#)
- typedef struct [kernel_info_t](#) [cl_fft_kernel_info](#)

Enumerations

- enum [kernel_dir_t](#) { [cl_fft_kernel_x](#) , [cl_fft_kernel_y](#) , [cl_fft_kernel_z](#) }

Functions

- void [FFT1D](#) ([cl_fft_plan](#) *plan, [cl_fft_kernel_dir](#) dir)

13.204.1 Detailed Description

Internals of FFT for OpenCL.

Version: <1.0>

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Definition in file [fft_internal.h](#).

13.204.2 Enumeration Type Documentation

13.204.2.1 kernel_dir_t

enum kernel_dir_t

Definition at line 25 of file [fft_internal.h](#).

13.205 fft_internal.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file fft_internal.h
00003  * \brief Internals of FFT for OpenCL
00004  *
00005  *
00006  * Version:    <1.0>
00007  *
00008  * Copyright ( C ) 2008 Apple Inc. All Rights Reserved.
00009  * SPDX-License-Identifier: LicenseRef-Apple-Permissive
00010  *
00011  *
00012  */
00013
00014
00015 #ifndef __CLFFT_INTERNAL_H
00016 #define __CLFFT_INTERNAL_H
00017
00018 #include "clFFT.h"
00019 #include <iostream>
00020 #include <sstream>
00021 #include <string>
```



```

00022
00023 using namespace std;
00024
00025 typedef enum kernel_dir_t
00026 {
00027     cl_fft_kernel_x,
00028     cl_fft_kernel_y,
00029     cl_fft_kernel_z
00030 } cl_fft_kernel_dir;
00031
00032 typedef struct kernel_info_t
00033 {
00034     cl_kernel kernel;
00035     char *kernel_name;
00036     unsigned lmem_size;
00037     unsigned num_workgroups;
00038     unsigned num_xforms_per_workgroup;
00039     unsigned num_workitems_per_workgroup;
00040     cl_fft_kernel_dir dir;
00041     int in_place_possible;
00042     kernel_info_t *next;
00043 } cl_fft_kernel_info;
00044
00045 typedef struct
00046 {
00047     // context in which fft resources are created and kernels are executed
00048     cl_context context;
00049
00050     // size of signal
00051     clFFT_Dim3 n;
00052
00053     // dimension of transform ... must be either 1D, 2D or 3D
00054     clFFT_Dimension dim;
00055
00056     // data format ... must be either interleaved or plannar
00057     clFFT_DataFormat format;
00058
00059     // string containing kernel source. Generated at runtime based on
00060     // n, dim, format and other parameters
00061     string *kernel_string;
00062
00063     // CL program containing source and kernel this particular
00064     // n, dim, data format
00065     cl_program program;
00066
00067     // linked list of kernels which needs to be executed for this fft
00068     cl_fft_kernel_info *kernel_info;
00069
00070     // number of kernels
00071     int num_kernels;
00072
00073     // twist kernel for virtualizing fft of very large sizes that do not
00074     // fit in GPU global memory
00075     cl_kernel twist_kernel;
00076
00077     // flag indicating if temporary intermediate buffer is needed or not.
00078     // this depends on fft kernels being executed and if transform is
00079     // in-place or out-of-place. e.g. Local memory fft (say 1D 1024 ...
00080     // one that does not require global transpose do not need temporary buffer)
00081     // 2D 1024x1024 out-of-place fft however do require intermediate buffer.
00082     // If temp buffer is needed, its allocation is lazy i.e. its not allocated
00083     // until its needed
00084     cl_int temp_buffer_needed;
00085
00086     // Batch size is runtime parameter and size of temporary buffer (if needed)
00087     // depends on batch size. Allocation of temporary buffer is lazy i.e. its
00088     // only created when needed. Once its created at first call of clFFT_Executexxx
00089     // it is not allocated next time if next time clFFT_Executexxx is called with
00090     // batch size different than the first call. last_batch_size caches the last
00091     // batch size with which this plan is used so that we dont keep allocating/deallocating
00092     // temp buffer if same batch size is used again and again.
00093     unsigned last_batch_size;
00094
00095     // temporary buffer for interleaved plan
00096     cl_mem tempmemobj;
00097
00098     // temporary buffer for planner plan. Only one of tempmemobj or
00099     // (tempmemobj_real, tempmemobj_imag) pair is valid (allocated) depending
00100     // data format of plan (plannar or interleaved)
00101     cl_mem tempmemobj_real, tempmemobj_imag;
00102
00103     // Maximum size of signal for which local memory transposed based
00104     // fft is sufficient i.e. no global mem transpose (communication)
00105     // is needed
00106     unsigned max_localmem_fft_size;
00107
00108     // Maximum work items per work group allowed. This, along with max_radix below controls

```

```

00109 // maximum local memory being used by fft kernels of this plan. Set to 256 by default
00110 unsigned max_work_item_per_workgroup;
00111
00112 // Maximum base radix for local memory fft ... this controls the maximum register
00113 // space used by work items. Currently defaults to 16
00114 unsigned max_radix;
00115
00116 // Device depended parameter that tells how many work-items need to be read consecutive
00117 // values to make sure global memory access by work-items of a work-group result in
00118 // coalesced memory access to utilize full bandwidth e.g. on NVidia tesla, this is 16
00119 unsigned min_mem_coalesce_width;
00120
00121 // Number of local memory banks. This is used to geneate kernel with local memory
00122 // transposes with appropriate padding to avoid bank conflicts to local memory
00123 // e.g. on NVidia it is 16.
00124 unsigned num_local_mem_banks;
00125 } cl_fft_plan;
00126
00127 void FFT1D(cl_fft_plan *plan, cl_fft_kernel_dir dir);
00128
00129 #endif

```

13.206 pass_through.h File Reference

Interface of a block that just puts its input in its output.

```

#include "conjugate_cc.h"
#include "conjugate_ic.h"
#include "conjugate_sc.h"
#include "gnss_block_interface.h"
#include <gnuradio/blocks/copy.h>
#include <gnuradio/runtime_types.h>
#include <cstdio>
#include <string>

```

Classes

- class [Pass_Through](#)

This class implements a block that connects input and output (does nothing)

13.206.1 Detailed Description

Interface of a block that just puts its input in its output.

Author

Carlos Aviles, 2010. carlos.avilesr(at)googlemail.com

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 Definition in file [pass_through.h](#).

13.207 pass_through.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file pass_through.h
00003 * \brief Interface of a block that just puts its input in its
00004 *       output.
00005 * \author Carlos Aviles, 2010. carlos.avilesr(at)googlemail.com
00006 *
00007 *
00008 * -----
00009 *
00010 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011 * This file is part of GNSS-SDR.
00012 *
00013 * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014 * SPDX-License-Identifier: GPL-3.0-or-later
00015 *

```

```

00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_PASS_THROUGH_H
00020 #define GNSS_SDR_PASS_THROUGH_H
00021
00022 #include "conjugate_cc.h"
00023 #include "conjugate_ic.h"
00024 #include "conjugate_sc.h"
00025 #include "gnss_block_interface.h"
00026 #include <gnuradio/blocks/copy.h>
00027 #include <gnuradio/runtime_types.h>
00028 #include <cstdint>
00029 #include <string>
00030
00031 /** \addtogroup Algorithms_Library
00032  * \{ */
00033 /** \addtogroup Algorithm_libs algorithms_libs
00034  * \{ */
00035
00036
00037 class ConfigurationInterface;
00038
00039 /*!
00040  * \brief This class implements a block that connects input and output (does nothing)
00041  */
00042 class Pass_Through : public GNSSBlockInterface
00043 {
00044 public:
00045     Pass_Through(const ConfigurationInterface* configuration,
00046                 const std::string& role,
00047                 unsigned int in_stream,
00048                 unsigned int out_stream);
00049
00050     ~Pass_Through() = default;
00051
00052     inline std::string role() override
00053     {
00054         return role_;
00055     }
00056
00057     /*! Returns "Pass_Through"
00058     inline std::string implementation() override
00059     {
00060         return "Pass_Through";
00061     }
00062
00063     inline std::string item_type() const
00064     {
00065         return item_type_;
00066     }
00067
00068     inline size_t item_size() override
00069     {
00070         return item_size_;
00071     }
00072
00073     void connect(gr::top_block_sptr top_block) override;
00074     void disconnect(gr::top_block_sptr top_block) override;
00075     gr::basic_block_sptr get_left_block() override;
00076     gr::basic_block_sptr get_right_block() override;
00077
00078 private:
00079     gr::blocks::copy::sptr kludge_copy_;
00080     conjugate_cc_sptr conjugate_cc_;
00081     conjugate_sc_sptr conjugate_sc_;
00082     conjugate_ic_sptr conjugate_ic_;
00083     std::string item_type_;
00084     std::string role_;
00085     size_t item_size_;
00086     unsigned int in_streams_;
00087     unsigned int out_streams_;
00088     bool inverted_spectrum;
00089 };
00090
00091
00092 /** \} */
00093 /** \} */
00094 #endif // GNSS_SDR_PASS_THROUGH_H

```

13.208 qzss_signal_replica.h File Reference

This file implements signal generators for QZSS signals.

```
#include <complex>
#include <cstdint>
#include <gsl-lite/gsl-lite.hpp>
```

Functions

- void [qzss_l1_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq)
Generates complex QZSS L1 C/A code for the desired SV ID, and sampled to specific sampling frequency.
- void [qzss_l1_code_gen_float](#) (own::span< float > dest, uint32_t prn)
Generates real QZSS L1 C/A code for the desired SV ID.
- void [qzss_l5i_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq)
Generates complex QZSS L5I code for the desired SV ID, and sampled to specific sampling frequency.
- void [qzss_l5i_code_gen_float](#) (own::span< float > dest, uint32_t prn)
Generates real QZSS L5I code for the desired SV ID.
- void [qzss_l5q_code_gen_complex_sampled](#) (own::span< std::complex< float > > dest, uint32_t prn, int32_t sampling_freq)
Generates complex QZSS L5Q code for the desired SV ID, and sampled to specific sampling frequency.
- void [qzss_l5q_code_gen_float](#) (own::span< float > dest, uint32_t prn)
Generates real QZSS L5I code for the desired SV ID.

13.208.1 Detailed Description

This file implements signal generators for QZSS signals.

Author

Carles Fernández-Prades, 2026. cfernandez (at) ctcc.es

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Definition in file [qzss_signal_replica.h](#).

13.209 qzss_signal_replica.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file qzss_signal_replica.h
00003  * \brief This file implements signal generators for QZSS signals
00004  * \author Carles Fernández-Prades, 2026. cfernandez (at) ctcc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2026 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_QZSS_SIGNAL_REPLICA_H
00018 #define GNSS_SDR_QZSS_SIGNAL_REPLICA_H
00019
00020 #include <complex>
00021 #include <cstdint>
00022 #if HAS_STD_SPAN
00023 #include <span>
00024 namespace own = std;
00025 #else
00026 #include <gsl-lite/gsl-lite.hpp>
00027 namespace own = gsl_lite;
00028 #endif
00029
```

```

00030 /** \addtogroup Algorithms_Library
00031 * \{ */
00032 /** \addtogroup Algorithm_libs algorithms_libs
00033 * \{ */
00034
00035 /*! Generates complex QZSS L1 C/A code for the desired SV ID, and sampled to specific sampling
frequency
00036 void qzss_l1_code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
sampling_freq);
00037
00038 /*! Generates real QZSS L1 C/A code for the desired SV ID
00039 void qzss_l1_code_gen_float(own::span<float> dest, uint32_t prn);
00040
00041 /*! Generates complex QZSS L5I code for the desired SV ID, and sampled to specific sampling frequency
00042 void qzss_l5i_code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
sampling_freq);
00043
00044 /*! Generates real QZSS L5I code for the desired SV ID
00045 void qzss_l5i_code_gen_float(own::span<float> dest, uint32_t prn);
00046
00047 /*! Generates complex QZSS L5Q code for the desired SV ID, and sampled to specific sampling frequency
00048 void qzss_l5q_code_gen_complex_sampled(own::span<std::complex<float> dest, uint32_t prn, int32_t
sampling_freq);
00049
00050 /*! Generates real QZSS L5I code for the desired SV ID
00051 void qzss_l5q_code_gen_float(own::span<float> dest, uint32_t prn);
00052
00053 /** \} */
00054 /** \} */
00055 #endif // GNSS_SDR_QZSS_SIGNAL_REPLICA_H

```

13.210 rtklib.h File Reference

main header file for the rtklib library

```

#include "MATH_CONSTANTS.h"
#include "gnss_frequencies.h"
#include "gnss_obs_codes.h"
#include <cctype>
#include <cmath>
#include <cstdarg>
#include <cstdint>
#include <cstdlib>
#include <netinet/in.h>
#include <pthread.h>
#include <string>

```

Classes

- struct [gtime_t](#)
- struct [obsd_t](#)
- struct [obs_t](#)
- struct [erpd_t](#)
- struct [erp_t](#)
- struct [pcv_t](#)
- struct [pcvs_t](#)
- struct [alm_t](#)
- struct [eph_t](#)
- struct [geph_t](#)
- struct [peph_t](#)
- struct [pclk_t](#)
- struct [seph_t](#)
- struct [tled_t](#)
- struct [tle_t](#)
- struct [tec_t](#)
- struct [fcbd_t](#)

- struct [sbsmsg_t](#)
- struct [sbs_t](#)
- struct [sbsfcorr_t](#)
- struct [sbslcorr_t](#)
- struct [sbssatp_t](#)
- struct [sbssat_t](#)
- struct [sbsigp_t](#)
- struct [sbsigpband_t](#)
- struct [sbsion_t](#)
- struct [dgps_t](#)
- struct [ssr_t](#)
- struct [lexmsg_t](#)
- struct [lex_t](#)
- struct [lexeph_t](#)
- struct [lexion_t](#)
- struct [stec_t](#)
- struct [trop_t](#)
- struct [pppcorr_t](#)
- struct [nav_t](#)
- struct [sta_t](#)
- struct [sol_t](#)
- struct [solbuf_t](#)
- struct [solstat_t](#)
- struct [solstatbuf_t](#)
- struct [rtcm_t](#)
- struct [url_t](#)
- struct [opt_t](#)
- struct [exterr_t](#)
- struct [snrmask_t](#)
- struct [prcopt_t](#)
- struct [solopt_t](#)
- struct [ssat_t](#)
- struct [ambc_t](#)
- struct [rtk_t](#)
- struct [half_cyc_tag](#)
- struct [stream_t](#)
- struct [serial_t](#)
- struct [file_t](#)
- struct [tcp_t](#)
- struct [tcpsvr_t](#)
- struct [tcpcli_t](#)
- struct [ntrip_t](#)
- struct [ftp_t](#)
- struct [raw_t](#)
- struct [rtksvr_t](#)
- struct [msm_h_t](#)

Macros

- #define `dev_t` int
- #define `socket_t` int
- #define `closesocket` close
- #define `lock_t` pthread_mutex_t
- #define `initlock(f)`
- #define `rtk_lock(f)`
- #define `rtk_unlock(f)`
- #define `VER_RTKLIB` "2.4.2"
- #define `NTRIP_AGENT` "RTKLIB/" VER_RTKLIB
- #define `NTRIP_CLI_PORT` 2101 /* default ntrip-client connection port */
- #define `NTRIP_SVR_PORT` 80 /* default ntrip-server connection port */
- #define `NTRIP_MAXRSP` 32768 /* max size of ntrip response */
- #define `NTRIP_MAXSTR` 256 /* max length of mountpoint string */
- #define `NTRIP_RSP_OK_CLI` "ICY 200 OK\r\n" /* ntrip response: client */
- #define `NTRIP_RSP_OK_SVR` "OK\r\n" /* ntrip response: server */
- #define `NTRIP_RSP_SRCTBL` "SOURCETABLE 200 OK\r\n" /* ntrip response: source table */
- #define `NTRIP_RSP_TBLEND` "ENDSOURCETABLE"
- #define `NTRIP_RSP_HTTP` "HTTP/" /* ntrip response: http */
- #define `NTRIP_RSP_ERROR` "ERROR" /* ntrip response: error */
- #define `FTP_CMD` "wget" /* ftp/http command */
- #define `ENAGLO`
- #define `ENAZQS`
- #define `ENABDS`
- #define `STR_MODE_R` 0x1 /* stream mode: read */
- #define `STR_MODE_W` 0x2 /* stream mode: write */
- #define `STR_MODE_RW` 0x3 /* stream mode: read/write */
- #define `STR_NONE` 0 /* stream type: none */
- #define `STR_SERIAL` 1 /* stream type: serial */
- #define `STR_FILE` 2 /* stream type: file */
- #define `STR_TCPSVR` 3 /* stream type: TCP server */
- #define `STR_TCPCLI` 4 /* stream type: TCP client */
- #define `STR_UDP` 5 /* stream type: UDP stream */
- #define `STR_NTRIPSVR` 6 /* stream type: NTRIP server */
- #define `STR_NTRIPCLI` 7 /* stream type: NTRIP client */
- #define `STR_FTP` 8 /* stream type: ftp */
- #define `STR_HTTP` 9 /* stream type: http */
- #define `NP_PPP`(opt)
- #define `IC_PPP`(s, opt)
- #define `IT_PPP`(opt)
- #define `NR_PPP`(opt)
- #define `IB_PPP`(s, opt)
- #define `NX_PPP`(opt)
- #define `NF_RTK`(opt)
- #define `NP_RTK`(opt)
- #define `NI_RTK`(opt)
- #define `NT_RTK`(opt)
- #define `NL_RTK`(opt)
- #define `NB_RTK`(opt)
- #define `NR_RTK`(opt)
- #define `NX_RTK`(opt)

Typedefs

- using `fatalfunc_t` = void(const char *)
fatal callback function type
- typedef struct `half_cyc_tag` `half_cyc_t`

Variables

- const int `TINTACT` = 200
period for stream active (ms)
- const int `SERIBUFFSIZE` = 4096
serial buffer size (bytes)
- const int `TIMETAGH_LEN` = 64
time tag file header length
- const int `MAXCLI` = 32
max client connection for tcp svr
- const int `MAXSTATMSG` = 32
max length of status message
- const int `FTP_TIMEOUT` = 30
ftp/http timeout (s)
- const int `MAXRAWLEN` = 4096
max length of receiver raw message
- const int `MAXSOLBUF` = 256
max number of solution buffer
- const int `MAXSBMSG` = 32
max number of SBAS msg in RTK server
- const int `MAXOBSBUF` = 128
max number of observation data buffer
- const int `FILEPATHSEP` = '/'
- const double `RE_WGS84` = 6378137.0
earth semimajor axis (WGS84) (m)
- const double `FE_WGS84` = (1.0 / 298.257223563)
earth flattening (WGS84)
- const double `HION` = 350000.0
ionosphere height (m)
- const double `PRN_HWBIAS` = 1e-6
process noise of h/w bias (m/MHz/sqrt(s))
- const double `INT_SWAP_STAT` = 86400.0
swap interval of solution status file (s)
- const double `INT_SWAP_TRAC` = 86400.0
swap interval of trace file (s)
- const unsigned int `POLYCRC32` = 0xEDB88320u
CRC32 polynomial.
- const unsigned int `POLYCRC24Q` = 0x1864CFBu
CRC24Q polynomial.
- const int `PMODE_SINGLE` = 0
positioning mode: single
- const int `PMODE_DGPS` = 1
positioning mode: DGPS/DGNSS
- const int `PMODE_KINEMA` = 2
positioning mode: kinematic
- const int `PMODE_STATIC` = 3

- positioning mode: static*
- const int [PMODE_MOVEB](#) = 4
- positioning mode: moving-base*
- const int [PMODE_FIXED](#) = 5
- positioning mode: fixed*
- const int [PMODE_PPP_KINEMA](#) = 6
- positioning mode: PPP-kinematic*
- const int [PMODE_PPP_STATIC](#) = 7
- positioning mode: PPP-static*
- const int [PMODE_PPP_FIXED](#) = 8
- positioning mode: PPP-fixed*
- const int [SOLF_LLH](#) = 0
- solution format: lat/lon/height*
- const int [SOLF_XYZ](#) = 1
- solution format: x/y/z-ecef*
- const int [SOLF_ENU](#) = 2
- solution format: e/n/u-baseline*
- const int [SOLF_NMEA](#) = 3
- solution format: NMEA-183*
- const int [SOLF_STAT](#) = 4
- solution format: solution status*
- const int [SOLF_GSIF](#) = 5
- solution format: GSI F1/F2*
- const int [SOLQ_NONE](#) = 0
- solution status: no solution*
- const int [SOLQ_FIX](#) = 1
- solution status: fix*
- const int [SOLQ_FLOAT](#) = 2
- solution status: float*
- const int [SOLQ_SBAS](#) = 3
- solution status: SBAS*
- const int [SOLQ_DGPS](#) = 4
- solution status: DGPS/DGNSS*
- const int [SOLQ_SINGLE](#) = 5
- solution status: single*
- const int [SOLQ_PPP](#) = 6
- solution status: PPP*
- const int [SOLQ_DR](#) = 7
- solution status: dead reckoning*
- const int [MAXSOLQ](#) = 7
- max number of solution status*
- const int [TIMES_GPST](#) = 0
- time system: gps time*
- const int [TIMES_UTC](#) = 1
- time system: utc*
- const int [TIMES_JST](#) = 2
- time system: jst*
- const double [ERR_SAAS](#) = 0.3
- saastamoinen model error std (m)*
- const double [ERR_BRDCI](#) = 0.5
- broadcast iono model error factor*

- const double `ERR_CBIAS` = 0.3
code bias error std (m)
- const double `REL_HUMI` = 0.7
relative humidity for saastamoinen model
- const double `GAP_RESION` = 120
default gap to reset ionos parameters (ep)
- const int `MAXFREQ` = 7
max NFREQ
- const int `MAXLEAPS` = 64
max number of leap seconds table
- const double `DTTOL` = 0.005
tolerance of time difference (s)
- const int `NFREQ` = 3
number of carrier frequencies
- const int `NFREQGLO` = 2
number of carrier frequencies of GLONASS
- const int `NEXOBS` = 0
number of extended obs codes
- const int `MAXANT` = 64
max length of station name/antenna type
- const int `MINPRNGPS` = 1
min satellite PRN number of GPS
- const int `MAXPRNGPS` = 32
max satellite PRN number of GPS
- const int `NSATGPS` = (`MAXPRNGPS` - `MINPRNGPS` + 1)
number of GPS satellites
- const int `NSYSGPS` = 1
- const int `SYS_NONE` = 0x00
navigation system: none
- const int `SYS_GPS` = 0x01
navigation system: GPS
- const int `SYS_SBS` = 0x02
navigation system: SBAS
- const int `SYS_GLO` = 0x04
navigation system: GLONASS
- const int `SYS_GAL` = 0x08
navigation system: Galileo
- const int `SYS_QZS` = 0x10
navigation system: QZSS
- const int `SYS_BDS` = 0x20
navigation system: BeiDou
- const int `SYS_IRN` = 0x40
navigation system: IRNS
- const int `SYS_LEO` = 0x80
navigation system: LEO
- const int `SYS_ALL` = 0xFF
navigation system: all
- const int `MINPRNGLO` = 1
min satellite slot number of GLONASS
- const int `MAXPRNGLO` = 27
max satellite slot number of GLONASS

- const int `NSATGLO` = (`MAXPRNGLO` - `MINPRNGLO` + 1)
number of GLONASS satellites
- const int `NSYSGLO` = 1
- const int `MINPRNGAL` = 1
min satellite PRN number of Galileo
- const int `MAXPRNGAL` = 36
max satellite PRN number of Galileo
- const int `NSATGAL` = (`MAXPRNGAL` - `MINPRNGAL` + 1)
number of Galileo satellites
- const int `NSYSGAL` = 1
- const int `MAXPRNQZS` = 202
max satellite PRN number of QZSS
- const int `MINPRNQZS` = 193
min satellite PRN number of QZSS
- const int `MINPRNQZS_S` = 183
min satellite PRN number of QZSS SAIF
- const int `MAXPRNQZS_S` = 191
max satellite PRN number of QZSS SAIF
- const int `NSATQZS` = (`MAXPRNQZS` - `MINPRNQZS` + 1)
number of QZSS satellites
- const int `NSYSQZS` = 1
- const int `MINPRNBDS` = 1
min satellite sat number of BeiDou
- const int `MAXPRNBDS` = 63
max satellite sat number of BeiDou
- const int `NSATBDS` = (`MAXPRNBDS` - `MINPRNBDS` + 1)
number of BeiDou satellites
- const int `NSYSBDS` = 1
- const int `MINPRNIRN` = 1
min satellite sat number of IRNSS
- const int `MAXPRNIRN` = 7
max satellite sat number of IRNSS
- const int `NSATIRN` = 0
- const int `NSYSIRN` = 0
- const int `MINPRNLEO` = 1
min satellite sat number of LEO
- const int `MAXPRNLEO` = 10
*max satellite sat number of LEO */*
- const int `NSATLEO` = 0
- const int `NSYSLEO` = 0
- const int `NSYS` = (`NSYSGPS` + `NSYSGLO` + `NSYSGAL` + `NSYSQZS` + `NSYSBDS` + `NSYSIRN` + `NSYSLEO`)
number of systems
- const int `MINPRNSBS` = 120
min satellite PRN number of SBAS
- const int `MAXPRNSBS` = 142
max satellite PRN number of SBAS
- const int `NSATSBBS` = (`MAXPRNSBS` - `MINPRNSBS` + 1)
number of SBAS satellites
- const int `MAXSAT` = (`NSATGPS` + `NSATGLO` + `NSATGAL` + `NSATQZS` + `NSATBDS` + `NSATIRN` + `NSATSBBS` + `NSATLEO`)
- const int `MAXSTA` = 255

- const int [MAXOBS](#) = 64
max number of obs in an epoch
- const int [MAXRCV](#) = 64
max receiver number (1 to MAXRCV)
- const int [MAXOBS](#)TYPE = 64
max number of obs type in RINEX
- const double [MAXD](#)TOE = 7200.0
max time difference to GPS Toe (s)
- const double [MAXD](#)TOE_QZS = 7200.0
max time difference to QZSS Toe (s)
- const double [MAXD](#)TOE_GAL = 10800.0
max time difference to Galileo Toe (s)
- const double [MAXD](#)TOE_BDS = 21600.0
max time difference to BeiDou Toe (s)
- const double [MAXD](#)TOE_GLO = 1800.0
max time difference to GLONASS Toe (s)
- const double [MAXD](#)TOE_SBS = 360.0
max time difference to SBAS Toe (s)
- const double [MAXD](#)TOE_S = 86400.0
max time difference to ephemeris toe (s) for other
- const double [MAX](#)GDOP = 300.0
max GDOP
- const int [MAX](#)SBSURA = 8
max URA of SBAS satellite
- const int [MAX](#)BAND = 10
max SBAS band of IGP
- const int [MAX](#)NIGP = 201
max number of IGP in SBAS band
- const int [MAX](#)NGEO = 4
max number of GEO satellites
- const int [MAX](#)SOLMSG = 8191
max length of solution message
- const int [MAX](#)ERRMSG = 4096
max length of error/warning message
- const int [ION](#)OPT_OFF = 0
ionosphere option: correction off
- const int [ION](#)OPT_BRDC = 1
ionosphere option: broadcast model
- const int [ION](#)OPT_SBAS = 2
ionosphere option: SBAS model
- const int [ION](#)OPT_IFLC = 3
ionosphere option: L1/L2 or L1/L5 iono-free LC
- const int [ION](#)OPT_EST = 4
ionosphere option: estimation
- const int [ION](#)OPT_TEC = 5
ionosphere option: IONEX TEC model
- const int [ION](#)OPT_QZS = 6
ionosphere option: QZSS broadcast model
- const int [ION](#)OPT_LEX = 7
ionosphere option: QZSS LEX ionosphere
- const int [ION](#)OPT_STEC = 8

- ionosphere option: SLANT TEC model*
- const int [TROPOPT_OFF](#) = 0
- troposphere option: correction off*
- const int [TROPOPT_SAAS](#) = 1
- troposphere option: Saastamoinen model*
- const int [TROPOPT_SBAS](#) = 2
- troposphere option: SBAS model*
- const int [TROPOPT_EST](#) = 3
- troposphere option: ZTD estimation*
- const int [TROPOPT_ESTG](#) = 4
- troposphere option: ZTD+grad estimation*
- const int [TROPOPT_COR](#) = 5
- troposphere option: ZTD correction*
- const int [TROPOPT_CORG](#) = 6
- troposphere option: ZTD+grad correction*
- const int [EPHOPT_BRDC](#) = 0
- ephemeris option: broadcast ephemeris*
- const int [EPHOPT_PREC](#) = 1
- ephemeris option: precise ephemeris*
- const int [EPHOPT_SBAS](#) = 2
- ephemeris option: broadcast + SBAS*
- const int [EPHOPT_SSRAPC](#) = 3
- ephemeris option: broadcast + SSR_APC*
- const int [EPHOPT_SSRCOM](#) = 4
- ephemeris option: broadcast + SSR_COM*
- const int [EPHOPT_LEX](#) = 5
- ephemeris option: QZSS LEX ephemeris*
- const double [EFACT_GPS](#) = 1.0
- error factor: GPS*
- const double [EFACT_GLO](#) = 1.5
- error factor: GLONASS*
- const double [EFACT_GAL](#) = 1.0
- error factor: Galileo*
- const double [EFACT_QZS](#) = 1.0
- error factor: QZSS*
- const double [EFACT_BDS](#) = 1.0
- error factor: BeiDou*
- const double [EFACT_IRN](#) = 1.5
- error factor: IRNSS*
- const double [EFACT_SBS](#) = 3.0
- error factor: SBAS*
- const int [MAXEXFILE](#) = 1024
- max number of expanded files*
- const double [MAXSBSAGEF](#) = 30.0
- max age of SBAS fast correction (s)*
- const double [MAXSBSAGEL](#) = 1800.0
- max age of SBAS long term corr (s)*
- const int [ARMODE_OFF](#) = 0
- AR mode: off.*
- const int [ARMODE_CONT](#) = 1
- AR mode: continuous.*

- const int [ARMODE_INST](#) = 2
AR mode: instantaneous.
- const int [ARMODE_FIXHOLD](#) = 3
AR mode: fix and hold.
- const int [ARMODE_PPPAR](#) = 4
AR mode: PPP-AR.
- const int [ARMODE_PPPAR_ILS](#) = 5
AR mode: AR mode: PPP-AR ILS.
- const int [ARMODE_WLNL](#) = 6
- const int [ARMODE_TCAR](#) = 7
- const int [POSOPT_RINEX](#) = 3
pos option: rinex header pos
- const int [MAXSTRPATH](#) = 1024
max length of stream path
- const int [MAXSTRMSG](#) = 1024
max length of stream message
- const double [CHISQR](#) [100]
- const double [LAM_CARR](#) [[MAXFREQ](#)]
- const int [STRFMT_RTCM2](#) = 0
- const int [STRFMT_RTCM3](#) = 1
- const int [STRFMT_SP3](#) = 16
- const int [STRFMT_RNXCLK](#) = 17
- const int [STRFMT_SBAS](#) = 18
- const int [STRFMT_NMEA](#) = 19
- const int [MAXSTRRTK](#) = 8

13.210.1 Detailed Description

main header file for the rtklib library

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017-2023, Carles Fernandez

This is a derived work from RTKLIB <http://www.rtklib.com/> The original source code at <https://github.com/tomojitakasu/RTKLIB> is released under the BSD 2-clause license with an additional exclusive clause that does not apply here. This additional clause is reproduced below:

" The software package includes some companion executive binaries or shared libraries necessary to execute APs on Windows. These licenses succeed to the original ones of these software. "

Neither the executive binaries nor the shared libraries are required by, used or included in GNSS-SDR.

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Definition in file [rtklib.h](#).

13.211 rtklib.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib.h
00003  * \brief main header file for the rtklib library
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017-2023, Carles Fernandez
00008  *         </ul>
00009  *
```

```

00010  * This is a derived work from RTKLIB http://www.rtklib.com/
00011  * The original source code at https://github.com/tomojitakasu/RTKLIB is
00012  * released under the BSD 2-clause license with an additional exclusive clause
00013  * that does not apply here. This additional clause is reproduced below:
00014  *
00015  * " The software package includes some companion executive binaries or shared
00016  * libraries necessary to execute APS on Windows. These licenses succeed to the
00017  * original ones of these software. "
00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
00020  * or included in GNSS-SDR.
00021  *
00022  * -----
00023  * Copyright (C) 2007-2013, T. Takasu
00024  * Copyright (C) 2017, Javier Arribas
00025  * Copyright (C) 2017-2023, Carles Fernandez
00026  * All rights reserved.
00027  *
00028  * SPDX-License-Identifier: BSD-2-Clause
00029  *
00030  * -----
00031  */
00032
00033 #ifndef GNSS_SDR_RTKLIB_H
00034 #define GNSS_SDR_RTKLIB_H
00035
00036 #include "MATH_CONSTANTS.h"
00037 #include "gnss_frequencies.h"
00038 #include "gnss_obs_codes.h"
00039 #include <cctype>
00040 #include <cmath>
00041 #include <cstdarg>
00042 #include <stdint>
00043 #include <stdlib>
00044 #include <netinet/in.h>
00045 #include <pthread.h>
00046 #include <string>
00047
00048 /** \addtogroup PVT
00049  * \{ */
00050 /** \addtogroup RTKLIB_Library algorithms_libs_rtklib
00051  * Our version of the RTKLIB core library (see http://www.rtklib.com/)
00052  * \{ */
00053
00054
00055 /* macros -----*/
00056
00057 #define dev_t int
00058 #define socket_t int
00059 #define closesocket close
00060 #define lock_t pthread_mutex_t
00061 #define initlock(f) pthread_mutex_init(f, NULL)
00062 #define rtk_lock(f) pthread_mutex_lock(f)
00063 #define rtk_unlock(f) pthread_mutex_unlock(f)
00064
00065 #define VER_RTKLIB "2.4.2"
00066 #define NTRIP_AGENT "RTKLIB/" VER_RTKLIB
00067 #define NTRIP_CLI_PORT 2101 /* default ntrip-client connection port */
00068 #define NTRIP_SVR_PORT 80 /* default ntrip-server connection port */
00069 #define NTRIP_MAXRSP 32768 /* max size of ntrip response */
00070 #define NTRIP_MAXSTR 256 /* max length of mountpoint string */
00071 #define NTRIP_RSP_OK_CLI "ICY 200 OK\r\n" /* ntrip response: client */
00072 #define NTRIP_RSP_OK_SVR "OK\r\n" /* ntrip response: server */
00073 #define NTRIP_RSP_SRCTBL "SOURCETABLE 200 OK\r\n" /* ntrip response: source table */
00074 #define NTRIP_RSP_TBLEN "ENDSOURCETABLE"
00075 #define NTRIP_RSP_HTTP "HTTP/" /* ntrip response: http */
00076 #define NTRIP_RSP_ERROR "ERROR" /* ntrip response: error */
00077
00078 #define FTP_CMD "wget" /* ftp/http command */
00079
00080 const int TINTACT = 200; /*!< period for stream active (ms)
00081 const int SERIBUFFSIZE = 4096; /*!< serial buffer size (bytes)
00082 const int TIMETAGH_LEN = 64; /*!< time tag file header length
00083 const int MAXCLI = 32; /*!< max client connection for tcp svr
00084 const int MAXSTATMSG = 32; /*!< max length of status message
00085
00086 const int FTP_TIMEOUT = 30; /*!< ftp/http timeout (s)
00087 const int MAXRAWLEN = 4096; /*!< max length of receiver raw message
00088 const int MAXSOLBUF = 256; /*!< max number of solution buffer
00089 const int MAXSBMSG = 32; /*!< max number of SBAS msg in RTK server
00090 const int MAXOBSBUF = 128; /*!< max number of observation data buffer
00091
00092 const int FILEPATHSEP = '/';
00093 const double RE_WGS84 = 6378137.0; /*!< earth semimajor axis (WGS84) (m)
00094 const double FE_WGS84 = (1.0 / 298.257223563); /*!< earth flattening (WGS84)
00095
00096 const double HION = 350000.0; /*!< ionosphere height (m)

```

```

00097 const double PRN_HWBIAS = 1e-6; //!< process noise of h/w bias (m/MHz/sqrt(s))
00098
00099 const double INT_SWAP_STAT = 86400.0; //!< swap interval of solution status file (s)
00100 const double INT_SWAP_TRAC = 86400.0; //!< swap interval of trace file (s)
00101
00102 const unsigned int POLYCRC32 = 0xEDB88320u; //!< CRC32 polynomial
00103 const unsigned int POLYCRC24Q = 0x1864CFBu; //!< CRC24Q polynomial
00104
00105 const int PMODE_SINGLE = 0; //!< positioning mode: single
00106 const int PMODE_DGPS = 1; //!< positioning mode: DGPS/DGNSS
00107 const int PMODE_KINEMA = 2; //!< positioning mode: kinematic
00108 const int PMODE_STATIC = 3; //!< positioning mode: static
00109 const int PMODE_MOVEB = 4; //!< positioning mode: moving-base
00110 const int PMODE_FIXED = 5; //!< positioning mode: fixed
00111 const int PMODE_PPP_KINEMA = 6; //!< positioning mode: PPP-kinematic
00112 const int PMODE_PPP_STATIC = 7; //!< positioning mode: PPP-static
00113 const int PMODE_PPP_FIXED = 8; //!< positioning mode: PPP-fixed
00114
00115 const int SOLF_LLH = 0; //!< solution format: lat/lon/height
00116 const int SOLF_XYZ = 1; //!< solution format: x/y/z-ecef
00117 const int SOLF_ENU = 2; //!< solution format: e/n/u-baseline
00118 const int SOLF_NMEA = 3; //!< solution format: NMEA-183
00119 const int SOLF_STAT = 4; //!< solution format: solution status
00120 const int SOLF_GSIF = 5; //!< solution format: GSI F1/F2
00121
00122 const int SOLQ_NONE = 0; //!< solution status: no solution
00123 const int SOLQ_FIX = 1; //!< solution status: fix
00124 const int SOLQ_FLOAT = 2; //!< solution status: float
00125 const int SOLQ_SBAS = 3; //!< solution status: SBAS
00126 const int SOLQ_DGPS = 4; //!< solution status: DGPS/DGNSS
00127 const int SOLQ_SINGLE = 5; //!< solution status: single
00128 const int SOLQ_PPP = 6; //!< solution status: PPP
00129 const int SOLQ_DR = 7; //!< solution status: dead reckoning
00130 const int MAXSOLQ = 7; //!< max number of solution status
00131
00132 const int TIMES_GPST = 0; //!< time system: gps time
00133 const int TIMES_UTC = 1; //!< time system: utc
00134 const int TIMES_JST = 2; //!< time system: jst
00135
00136
00137 const double ERR_SAAS = 0.3; //!< saastamoinen model error std (m)
00138 const double ERR_BRDCI = 0.5; //!< broadcast iono model error factor
00139 const double ERR_CBIAS = 0.3; //!< code bias error std (m)
00140 const double REL_HUMI = 0.7; //!< relative humidity for saastamoinen model
00141 const double GAP_RESION = 120; //!< default gap to reset ionos parameters (ep)
00142
00143 const int MAXFREQ = 7; //!< max NFREQ
00144
00145 const int MAXLEAPS = 64; //!< max number of leap seconds table
00146 const double DTTOL = 0.005; //!< tolerance of time difference (s)
00147
00148 const int NFREQ = 3; //!< number of carrier frequencies
00149 const int NFREQGLO = 2; //!< number of carrier frequencies of GLONASS
00150 const int NEXOBS = 0; //!< number of extended obs codes
00151 const int MAXANT = 64; //!< max length of station name/antenna type
00152
00153 const int MINPRNGPS = 1; //!< min satellite PRN number of GPS
00154 const int MAXPRNGPS = 32; //!< max satellite PRN number of GPS
00155 const int NSATGPS = (MAXPRNGPS - MINPRNGPS + 1); //!< number of GPS satellites
00156 const int NSYSGPS = 1;
00157
00158 const int SYS_NONE = 0x00; //!< navigation system: none
00159 const int SYS_GPS = 0x01; //!< navigation system: GPS
00160 const int SYS_SBS = 0x02; //!< navigation system: SBAS
00161 const int SYS_GLO = 0x04; //!< navigation system: GLONASS
00162 const int SYS_GAL = 0x08; //!< navigation system: Galileo
00163 const int SYS_QZS = 0x10; //!< navigation system: QZSS
00164 const int SYS_BDS = 0x20; //!< navigation system: BeiDou
00165 const int SYS_IRN = 0x40; //!< navigation system: IRNS
00166 const int SYS_LEO = 0x80; //!< navigation system: LEO
00167 const int SYS_ALL = 0xFF; //!< navigation system: all
00168
00169
00170 #define ENAGLO
00171 #ifdef ENAGLO
00172 const int MINPRNGLO = 1; //!< min satellite slot number of GLONASS
00173 const int MAXPRNGLO = 27; //!< max satellite slot number of GLONASS
00174 const int NSATGLO = (MAXPRNGLO - MINPRNGLO + 1); //!< number of GLONASS satellites
00175 const int NSYSGLO = 1;
00176 #else
00177 const int MINPRNGLO = 0;
00178 const int MAXPRNGLO = 0;
00179 const int NSATGLO = 0;
00180 const int NSYSGLO = 0;
00181 #endif
00182
00183

```



```

00184 const int MINPRNGAL = 1; //!< min satellite PRN number of Galileo
00185 const int MAXPRNGAL = 36; //!< max satellite PRN number of Galileo
00186 const int NSATGAL = (MAXPRNGAL - MINPRNGAL + 1); //!< number of Galileo satellites
00187 const int NSYSGAL = 1;
00188
00189 const int MAXPRNQZS = 202; //!< max satellite PRN number of QZSS
00190 const int MINPRNQZS = 193; //!< min satellite PRN number of QZSS
00191 #define ENAQZS
00192 #ifdef ENAQZS
00193 const int MINPRNQZS_S = 183; //!< min satellite PRN number of QZSS SAIF
00194 const int MAXPRNQZS_S = 191; //!< max satellite PRN number of QZSS SAIF
00195 const int NSATQZS = (MAXPRNQZS - MINPRNQZS + 1); //!< number of QZSS satellites
00196 const int NSYSQZS = 1;
00197 #else
00198 const int MINPRNQZS_S = 0;
00199 const int NSATQZS = 0;
00200 const int NSYSQZS = 0;
00201 #endif
00202
00203 #define ENABDS
00204 #ifdef ENABDS
00205 const int MINPRNBDS = 1; //!< min satellite sat number of BeiDou
00206 const int MAXPRNBDS = 63; //!< max satellite sat number of BeiDou
00207 const int NSATBDS = (MAXPRNBDS - MINPRNBDS + 1); //!< number of BeiDou satellites
00208 const int NSYSBDS = 1;
00209 #else
00210 const int MINPRNBDS = 0;
00211 const int MAXPRNBDS = 0;
00212 const int NSATBDS = 0;
00213 const int NSYSBDS = 0;
00214 #endif
00215
00216 const int MINPRNIRN = 1; //!< min satellite sat number of IRNSS
00217 const int MAXPRNIRN = 7; //!< max satellite sat number of IRNSS
00218 #ifdef ENAIRN
00219 const int NSATIRN = (MAXPRNIRN - MINPRNIRN + 1); //!< number of IRNSS satellites
00220 const int NSYSIRN = 1;
00221 #else
00222 const int NSATIRN = 0;
00223 const int NSYSIRN = 0;
00224 #endif
00225
00226 const int MINPRNLEO = 1; //!< min satellite sat number of LEO
00227 const int MAXPRNLEO = 10; //!< max satellite sat number of LEO */
00228 #ifdef ENALEO
00229 const int NSATLEO = (MAXPRNLEO - MINPRNLEO + 1); //!< number of LEO satellites
00230 const int NSYSLEO = 1;
00231 #else
00232 const int NSATLEO = 0;
00233 const int NSYSLEO = 0;
00234 #endif
00235
00236 const int NSYS = (NSYSGPS + NSYSGLO + NSYSGAL + NSYSQZS + NSYSBDS + NSYSIRN + NSYSLEO); //!< number
of systems
00237
00238 const int MINPRNSBS = 120; //!< min satellite PRN number of SBAS
00239 const int MAXPRNSBS = 142; //!< max satellite PRN number of SBAS
00240 const int NSATSBS = (MAXPRNSBS - MINPRNSBS + 1); //!< number of SBAS satellites
00241
00242 const int MAXSAT = (NSATGPS + NSATGLO + NSATGAL + NSATQZS + NSATBDS + NSATIRN + NSATSBS + NSATLEO);
00243
00244 const int MAXSTA = 255;
00245
00246 #ifndef MAXOBS
00247 const int MAXOBS = 64; //!< max number of obs in an epoch
00248 #endif
00249
00250 const int MAXRCV = 64; //!< max receiver number (1 to MAXRCV)
00251 const int MAXOBSSTYPE = 64; //!< max number of obs type in RINEX
00252 const double MAXDTOE = 7200.0; //!< max time difference to GPS Toe (s)
00253 const double MAXDTOE_QZS = 7200.0; //!< max time difference to QZSS Toe (s)
00254 const double MAXDTOE_GAL = 10800.0; //!< max time difference to Galileo Toe (s)
00255 const double MAXDTOE_BDS = 21600.0; //!< max time difference to BeiDou Toe (s)
00256 const double MAXDTOE_GLO = 1800.0; //!< max time difference to GLONASS Toe (s)
00257 const double MAXDTOE_SBS = 360.0; //!< max time difference to SBAS Toe (s)
00258 const double MAXDTOE_S = 86400.0; //!< max time difference to ephemeris toe (s) for other
00259 const double MAXGDOP = 300.0; //!< max GDOP
00260
00261 const int MAXSBSURA = 8; //!< max URA of SBAS satellite
00262 const int MAXBAND = 10; //!< max SBAS band of IGP
00263 const int MAXNIGP = 201; //!< max number of IGP in SBAS band
00264 const int MAXNGEO = 4; //!< max number of GEO satellites
00265
00266 const int MAXSOLMSG = 8191; //!< max length of solution message
00267 const int MAXERRMSG = 4096; //!< max length of error/warning message
00268
00269 const int IONOPT_OFF = 0; //!< ionosphere option: correction off

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00270 const int IONOOPT_BRDC = 1; //!< ionosphere option: broadcast model
00271 const int IONOOPT_SBAS = 2; //!< ionosphere option: SBAS model
00272 const int IONOOPT_IFLC = 3; //!< ionosphere option: L1/L2 or L1/L5 iono-free LC
00273 const int IONOOPT_EST = 4; //!< ionosphere option: estimation
00274 const int IONOOPT_TEC = 5; //!< ionosphere option: IONEX TEC model
00275 const int IONOOPT_QZS = 6; //!< ionosphere option: QZSS broadcast model
00276 const int IONOOPT_LEX = 7; //!< ionosphere option: QZSS LEX ionosphere
00277 const int IONOOPT_STEC = 8; //!< ionosphere option: SLANT TEC model
00278
00279 const int TROPOPT_OFF = 0; //!< troposphere option: correction off
00280 const int TROPOPT_SAAS = 1; //!< troposphere option: Saastamoinen model
00281 const int TROPOPT_SBAS = 2; //!< troposphere option: SBAS model
00282 const int TROPOPT_EST = 3; //!< troposphere option: ZTD estimation
00283 const int TROPOPT_ESTG = 4; //!< troposphere option: ZTD+grad estimation
00284 const int TROPOPT_COR = 5; //!< troposphere option: ZTD correction
00285 const int TROPOPT_CORG = 6; //!< troposphere option: ZTD+grad correction
00286
00287
00288 const int EPHOPT_BRDC = 0; //!< ephemeris option: broadcast ephemeris
00289 const int EPHOPT_PREC = 1; //!< ephemeris option: precise ephemeris
00290 const int EPHOPT_SBAS = 2; //!< ephemeris option: broadcast + SBAS
00291 const int EPHOPT_SSRAPC = 3; //!< ephemeris option: broadcast + SSR_APC
00292 const int EPHOPT_SSRCOM = 4; //!< ephemeris option: broadcast + SSR_COM
00293 const int EPHOPT_LEX = 5; //!< ephemeris option: QZSS LEX ephemeris
00294
00295 const double EFACT_GPS = 1.0; //!< error factor: GPS
00296 const double EFACT_GLO = 1.5; //!< error factor: GLONASS
00297 const double EFACT_GAL = 1.0; //!< error factor: Galileo
00298 const double EFACT_QZS = 1.0; //!< error factor: QZSS
00299 const double EFACT_BDS = 1.0; //!< error factor: BeiDou
00300 const double EFACT_IRN = 1.5; //!< error factor: IRNSS
00301 const double EFACT_SBS = 3.0; //!< error factor: SBAS
00302
00303 const int MAXEXFILE = 1024; //!< max number of expanded files
00304 const double MAXSBSAGEF = 30.0; //!< max age of SBAS fast correction (s)
00305 const double MAXSBSAGEL = 1800.0; //!< max age of SBAS long term corr (s)
00306
00307 const int ARMODE_OFF = 0; //!< AR mode: off
00308 const int ARMODE_CONT = 1; //!< AR mode: continuous
00309 const int ARMODE_INST = 2; //!< AR mode: instantaneous
00310 const int ARMODE_FIXHOLD = 3; //!< AR mode: fix and hold
00311 const int ARMODE_PPPAR = 4; //!< AR mode: PPP-AR
00312 const int ARMODE_PPPAR_ILS = 5; //!< AR mode: AR mode: PPP-AR ILS
00313 const int ARMODE_WLNL = 6;
00314 const int ARMODE_TCAR = 7;
00315
00316
00317 const int POSOPT_RINEX = 3; //!< pos option: rinex header pos
00318 const int MAXSTRPATH = 1024; //!< max length of stream path
00319 const int MAXSTRMSG = 1024; //!< max length of stream message
00320
00321 using fatalfunc_t = void(const char *); //!< fatal callback function type
00322
00323 // clang-format off
00324 #define STR_MODE_R 0x1 /* stream mode: read */
00325 #define STR_MODE_W 0x2 /* stream mode: write */
00326 #define STR_MODE_RW 0x3 /* stream mode: read/write */
00327
00328 #define STR_NONE 0 /* stream type: none */
00329 #define STR_SERIAL 1 /* stream type: serial */
00330 #define STR_FILE 2 /* stream type: file */
00331 #define STR_TCPSVR 3 /* stream type: TCP server */
00332 #define STR_TCPCLI 4 /* stream type: TCP client */
00333 #define STR_UDP 5 /* stream type: UDP stream */
00334 #define STR_NTRIPSVR 6 /* stream type: NTRIP server */
00335 #define STR_NTRIPCLI 7 /* stream type: NTRIP client */
00336 #define STR_FTP 8 /* stream type: ftp */
00337 #define STR_HTTP 9 /* stream type: http */
00338
00339 #define NP_PPP(opt) ((opt)->dynamics ? 9 : 3)
/* number of pos solution */
00340 #define IC_PPP(s, opt) (NP_PPP(opt) + (s))
/* state index of clocks (s=0:gps,1:glo) */
00341 #define IT_PPP(opt) (IC_PPP(0, opt) + NSYS)
/* state index of tropo */
00342 #define NR_PPP(opt) (IT_PPP(opt) + ((opt)->tropopt < TROPOPT_EST ? 0 : ((opt)->tropopt == TROPOPT_EST
? 1 : 3))) /* number of solutions */
00343 #define IB_PPP(s, opt) (NR_PPP(opt) + (s)-1)
/* state index of phase bias */
00344 #define NX_PPP(opt) (IB_PPP(MAXSAT, opt) + 1)
/* number of estimated states */
00345 // clang-format on
00346
00347 #define NF_RTK(opt) ((opt)->ionoopt == IONOOPT_IFLC ? 1 : (opt)->nf)
00348 #define NP_RTK(opt) ((opt)->dynamics == 0 ? 3 : 9)
00349 #define NI_RTK(opt) ((opt)->ionoopt != IONOOPT_EST ? 0 : MAXSAT)
00350 #define NT_RTK(opt) ((opt)->tropopt < TROPOPT_EST ? 0 : ((opt)->tropopt < TROPOPT_ESTG ? 2 : 6))

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00351 #define NL_RTK(opt) ((opt)->glomodear != 2 ? 0 : NFREQGLO)
00352 #define NB_RTK(opt) ((opt)->mode <= PMODE_DGPS ? 0 : MAXSAT * NF_RTK(opt))
00353 #define NR_RTK(opt) (NP_RTK(opt) + NI_RTK(opt) + NT_RTK(opt) + NL_RTK(opt))
00354 #define NX_RTK(opt) (NR_RTK(opt) + NB_RTK(opt))
00355
00356 typedef struct
00357 {
00358     time_t time; /* time (s) expressed by standard time_t */
00359     double sec; /* fraction of second under 1 s */
00360 } gtime_t;
00361
00362
00363 typedef struct
00364 {
00365     gtime_t time; /* observation data record */
00366     /* receiver sampling time (GPST) */
00367     unsigned char sat, rcv; /* satellite/receiver number */
00368     unsigned char SNR[NFREQ + NEXOBS]; /* signal strength (0.25 dBHz) */
00369     unsigned char LLI[NFREQ + NEXOBS]; /* loss of lock indicator */
00370     unsigned char code[NFREQ + NEXOBS]; /* code indicator (CODE_???) */
00371     double L[NFREQ + NEXOBS]; /* observation data carrier-phase (cycle) */
00372     double P[NFREQ + NEXOBS]; /* observation data pseudorange (m) */
00373     float D[NFREQ + NEXOBS]; /* observation data doppler frequency (Hz) */
00374 } obsd_t;
00375
00376 typedef struct
00377 {
00378     int n, nmax; /* number of observation data/allocated */
00379     obsd_t *data; /* observation data records */
00380 } obs_t;
00381
00382
00383 typedef struct
00384 {
00385     /* earth rotation parameter data type */
00386     double mjd; /* mjd (days) */
00387     double xp, yp; /* pole offset (rad) */
00388     double xpr, ypr; /* pole offset rate (rad/day) */
00389     double utl_utc; /* utl-utc (s) */
00390     double lod; /* length of day (s/day) */
00391 } erpd_t;
00392
00393 typedef struct
00394 {
00395     /* earth rotation parameter type */
00396     int n, nmax; /* number and max number of data */
00397     erpd_t *data; /* earth rotation parameter data */
00398 } erp_t;
00399
00400 typedef struct
00401 {
00402     /* antenna parameter type */
00403     int sat; /* satellite number (0:receiver) */
00404     char type[MAXANT]; /* antenna type */
00405     char code[MAXANT]; /* serial number or satellite code */
00406     gtime_t ts, te; /* valid time start and end */
00407     double off[NFREQ][3]; /* phase center offset e/n/u or x/y/z (m) */
00408     double var[NFREQ][19]; /* phase center variation (m) */
00409     /* el=90,85,...,0 or nadir=0,1,2,3,... (deg) */
00410 } pcv_t;
00411
00412 typedef struct
00413 {
00414     /* antenna parameters type */
00415     int n, nmax; /* number of data/allocated */
00416     pcv_t *pcv; /* antenna parameters data */
00417 } pcvs_t;
00418
00419 typedef struct
00420 {
00421     /* almanac type */
00422     int sat; /* satellite number */
00423     int svh; /* sv health (0:ok) */
00424     int svconf; /* as and sv config */
00425     int week; /* GPS/QZS: gps week, GAL: galileo week */
00426     gtime_t toa; /* Toa */
00427     /* SV orbit parameters */
00428     double A, e, i0, OMG0, omg, M0, OMGd;
00429     double toas; /* Toa (s) in week */
00430     double f0, f1; /* SV clock parameters (af0,af1) */
00431 } alm_t;
00432
00433 typedef struct
00434 {
00435     /* GPS/QZS/GAL broadcast ephemeris type */
00436     int sat; /* satellite number */
00437     int iode, iodec; /* IODE, IODC */
00438     int sva; /* SV accuracy (URA index) */

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00438     int svh;                /* SV health (0:ok) */
00439     int week;               /* GPS/QZS: gps week, GAL: galileo week */
00440     int code;              /* GPS/QZS: code on L2, GAL/BDS: data sources */
00441     int flag;              /* GPS/QZS: L2 P data flag, BDS: nav type */
00442     gtime_t toe, toc, ttr; /* Toe,Toc,T_trans */
00443     /* SV orbit parameters */
00444     double A, e, i0, OMG0, omg, M0, deln, OMGd, idot;
00445     double crc, crs, cuc, cus, cic, cis;
00446     double toes;           /* Toe (s) in week */
00447     double fit;            /* fit interval (h) */
00448     double f0, f1, f2;     /* SV clock parameters (af0,af1,af2) */
00449     double tgd[4];         /* group delay parameters */
00450     /* GPS/QZS:tgd[0]=TGD */
00451     /* GAL      :tgd[0]=BGD E5a/E1,tgd[1]=BGD E5b/E1 */
00452     /* BDS      :tgd[0]=BGD1,tgd[1]=BGD2 */
00453     double isc[4];         /* GPS      :isc[0]=ISCL1, isc[1]=ISCL2, isc[2]=ISCL5I,
isc[3]=ISCL5Q */
00454     double Adot, ndot;     /* Adot,ndot for CNAV */
00455     float has_clock_correction_m; /* Galileo High Accuracy Service clock correction, in
[m] */
00456     float has_orbit_radial_correction_m; /* Galileo High Accuracy Service orbit radial
correction, in [m] */
00457     float has_orbit_in_track_correction_m; /* Galileo High Accuracy Service orbit in-track
correction, in [m] */
00458     float has_orbit_cross_track_correction_m; /* Galileo High Accuracy Service orbit cross-track
correction, in [m] */
00459     bool apply_has_corrections;
00460 } eph_t;
00461
00462
00463 typedef struct
00464 {
00465     /* GLONASS broadcast ephemeris type */
00466     int sat;                /* satellite number */
00467     int iode;              /* IODE (0-6 bit of tb field) */
00468     int frq;              /* satellite frequency number */
00469     int svh, sva, age;     /* satellite health, accuracy, age of operation */
00470     gtime_t toe;          /* epoch of epherides (gpst) */
00471     gtime_t tof;          /* message frame time (gpst) */
00472     double pos[3];        /* satellite position (ecef) (m) */
00473     double vel[3];        /* satellite velocity (ecef) (m/s) */
00474     double acc[3];        /* satellite acceleration (ecef) (m/s^2) */
00475     double taun, gamn;     /* SV clock bias (s)/relative freq bias */
00476     double dtaun;         /* delay between L1 and L2 (s) */
00477 } gepht_t;
00478
00479 typedef struct
00480 {
00481     /* precise ephemeris type */
00482     gtime_t time;          /* time (GPST) */
00483     int index;            /* ephemeris index for multiple files */
00484     double pos[MAXSAT][4]; /* satellite position/clock (ecef) (m|s) */
00485     float std[MAXSAT][4];  /* satellite position/clock std (m|s) */
00486     double vel[MAXSAT][4]; /* satellite velocity/clock-rate (m/s|s/s) */
00487     float vst[MAXSAT][4];  /* satellite velocity/clock-rate std (m/s|s/s) */
00488     float cov[MAXSAT][3];  /* satellite position covariance (m^2) */
00489     float vco[MAXSAT][3];  /* satellite velocity covariance (m^2) */
00490 } pepht_t;
00491
00492 typedef struct
00493 {
00494     /* precise clock type */
00495     gtime_t time;          /* time (GPST) */
00496     int index;            /* clock index for multiple files */
00497     double clk[MAXSAT][1]; /* satellite clock (s) */
00498     float std[MAXSAT][1];  /* satellite clock std (s) */
00499 } pclk_t;
00500
00501 typedef struct
00502 {
00503     /* SBAS ephemeris type */
00504     int sat;                /* satellite number */
00505     gtime_t t0;            /* reference epoch time (GPST) */
00506     gtime_t tof;          /* time of message frame (GPST) */
00507     int sva;              /* SV accuracy (URA index) */
00508     int svh;              /* SV health (0:ok) */
00509     double pos[3];        /* satellite position (m) (ecef) */
00510     double vel[3];        /* satellite velocity (m/s) (ecef) */
00511     double acc[3];        /* satellite acceleration (m/s^2) (ecef) */
00512     double af0, af1;      /* satellite clock-offset/drift (s,s/s) */
00513 } seph_t;
00514
00515 typedef struct
00516 {
00517     /* norad two line element data type */
00518     char name[32];        /* common name */
00519     char alias[32];       /* alias name */
00520     char satno[16];       /* satellite catalog number */

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00520     char satclass; /* classification */
00521     char desig[16]; /* international designator */
00522     gtime_t epoch; /* element set epoch (UTC) */
00523     double ndot; /* 1st derivative of mean motion */
00524     double nddot; /* 2st derivative of mean motion */
00525     double bstar; /* B* drag term */
00526     int etype; /* element set type */
00527     int eleno; /* element number */
00528     double inc; /* orbit inclination (deg) */
00529     double OMG; /* right ascension of ascending node (deg) */
00530     double ecc; /* eccentricity */
00531     double omg; /* argument of perigee (deg) */
00532     double M; /* mean anomaly (deg) */
00533     double n; /* mean motion (rev/day) */
00534     int rev; /* revolution number at epoch */
00535 } tled_t;
00536
00537
00538 typedef struct
00539 {
00540     int n, nmax; /* norad two line element type */
00541     tled_t *data; /* number/max number of two line element data */
00542 } tle_t;
00543
00544
00545 typedef struct
00546 {
00547     gtime_t time; /* TEC grid type */
00548     int ndata[3]; /* epoch time (GPST) */
00549     double rb; /* TEC grid data size {nlat,nlon,nhgt} */
00550     double lats[3]; /* earth radius (km) */
00551     double lons[3]; /* latitude start/interval (deg) */
00552     double hgts[3]; /* longitude start/interval (deg) */
00553     double *data; /* heights start/interval (km) */
00554     float *rms; /* TEC grid data (tecu) */
00555     /* RMS values (tecu) */
00556 } tec_t;
00557
00558 typedef struct
00559 {
00560     gtime_t ts, te; /* satellite fcb data type */
00561     double bias[MAXSAT][3]; /* start/end time (GPST) */
00562     double std[MAXSAT][3]; /* fcb value (cyc) */
00563     /* fcb std-dev (cyc) */
00564 } fcbdt_t;
00565
00566 typedef struct
00567 {
00568     int week, tow; /* SBAS message type */
00569     int prn; /* reception time */
00570     unsigned char msg[29]; /* SBAS satellite PRN number */
00571     /* SBAS message (226bit) padded by 0 */
00572 } sbmsg_t;
00573
00574 typedef struct
00575 {
00576     int n, nmax; /* SBAS messages type */
00577     sbmsg_t *msgs; /* number of SBAS messages/allocated */
00578 } sbs_t;
00579
00580
00581 typedef struct
00582 {
00583     gtime_t t0; /* SBAS fast correction type */
00584     double prc; /* time of applicability (TOF) */
00585     double rrc; /* pseudorange correction (PRC) (m) */
00586     double dt; /* range-rate correction (RRC) (m/s) */
00587     int iodef; /* range-rate correction delta-time (s) */
00588     short udre; /* IODE (issue of date fast corr) */
00589     short ai; /* UDRE+1 */
00590     /* degradation factor indicator */
00591 } sbsfcrr_t;
00592
00593 typedef struct
00594 {
00595     gtime_t t0; /* SBAS long term satellite error correction type */
00596     int iode; /* correction time */
00597     double dpos[3]; /* IODE (issue of date ephemeris) */
00598     double dvel[3]; /* delta position (m) (ecef) */
00599     double daf0, daf1; /* delta velocity (m/s) (ecef) */
00600     /* delta clock-offset/drift (s,s/s) */
00601 } sbslcorr_t;
00602
00603 typedef struct
00604 {
00605     int sat; /* SBAS satellite correction type */
00606     sbsfcrr_t fcorr; /* satellite number */
00607     /* fast correction */

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00607     sbsslcorr_t lcorr; /* long term correction */
00608 } sbssatp_t;
00609
00610
00611 typedef struct
00612 {
00613     /* SBAS satellite corrections type */
00614     int iodp; /* IODP (issue of date mask) */
00615     int nsat; /* number of satellites */
00616     int tlat; /* system latency (s) */
00617     sbssatp_t sat[MAXSAT]; /* satellite correction */
00618 } sbssat_t;
00619
00620 typedef struct
00621 {
00622     /* SBAS ionospheric correction type */
00623     gtime_t t0; /* correction time */
00624     short lat, lon; /* latitude/longitude (deg) */
00625     short give; /* GIVI+1 */
00626     float delay; /* vertical delay estimate (m) */
00627 } sbsigp_t;
00628
00629 typedef struct
00630 {
00631     /* IGP band type */
00632     short x; /* longitude/latitude (deg) */
00633     const short *y; /* latitudes/longitudes (deg) */
00634     unsigned char bits; /* IGP mask start bit */
00635     unsigned char bite; /* IGP mask end bit */
00636 } sbsigpband_t;
00637
00638 typedef struct
00639 {
00640     /* SBAS ionospheric corrections type */
00641     int iodi; /* IODI (issue of date ionos corr) */
00642     int nigp; /* number of igps */
00643     sbsigp_t igp[MAXNIGP]; /* ionospheric correction */
00644 } sbsion_t;
00645
00646 typedef struct
00647 {
00648     /* DGPS/GNSS correction type */
00649     gtime_t t0; /* correction time */
00650     double prc; /* pseudorange correction (PRC) (m) */
00651     double rrc; /* range rate correction (RRC) (m/s) */
00652     int iod; /* issue of data (IOD) */
00653     double udre; /* UDRE */
00654 } dgps_t;
00655
00656 typedef struct
00657 {
00658     /* SSR correction type */
00659     gtime_t t0[6]; /* epoch time (GPST) {eph,clk,hrcclk,ura,bias,pbias} */
00660     double udi[6]; /* SSR update interval (s) */
00661     int iod[6]; /* iod ssr {eph,clk,hrcclk,ura,bias,pbias} */
00662     int iode; /* issue of data */
00663     int iodicrc; /* issue of data crc for beidou/sbas */
00664     int ura; /* URA indicator */
00665     int refd; /* sat ref datum (0:ITRF,1:regional) */
00666     double ddep[3]; /* delta orbit {radial,along,cross} (m) */
00667     double ddepd[3]; /* dot delta orbit {radial,along,cross} (m/s) */
00668     double dcl[3]; /* delta clock {c0,c1,c2} (m,m/s,m/s^2) */
00669     double hrcclk; /* high-rate clock correction (m) */
00670     float cbias[MAXCODE]; /* code biases (m) */
00671     double pbias[MAXCODE]; /* phase biases (m) */
00672     float stdpb[MAXCODE]; /* std-dev of phase biases (m) */
00673     double yaw_ang, yaw_rate; /* yaw angle and yaw rate (deg,deg/s) */
00674     unsigned char update; /* update flag (0:no update,1:update) */
00675 } ssr_t;
00676
00677 typedef struct
00678 {
00679     /* QZSS LEX message type */
00680     int prn; /* satellite PRN number */
00681     int type; /* message type */
00682     int alert; /* alert flag */
00683     unsigned char stat; /* signal tracking status */
00684     unsigned char snr; /* signal C/N0 (0.25 dBHz) */
00685     unsigned int tt; /* tracking time (ms) */
00686     unsigned char msg[212]; /* LEX message data part 1695 bits */
00687 } lexmsg_t;
00688
00689 typedef struct
00690 {
00691     /* QZSS LEX messages type */
00692     int n, nmax; /* number of LEX messages and allocated */
00693     lexmsg_t *msgs; /* LEX messages */
00694 } lex_t;

```

```

00694
00695
00696 typedef struct
00697 {
00698     /* QZSS LEX ephemeris type */
00699     gtime_t toe; /* epoch time (GPST) */
00700     gtime_t tof; /* message frame time (GPST) */
00701     int sat; /* satellite number */
00702     unsigned char health; /* signal health (L1,L2,L1C,L5,LEX) */
00703     unsigned char ura; /* URA index */
00704     double pos[3]; /* satellite position (m) */
00705     double vel[3]; /* satellite velocity (m/s) */
00706     double acc[3]; /* satellite acceleration (m/s2) */
00707     double jerk[3]; /* satellite jerk (m/s3) */
00708     double af0, af1; /* satellite clock bias and drift (s,s/s) */
00709     double tgd; /* TGD */
00710     double isc[8]; /* ISC */
00711 } lexeph_t;
00712
00713 typedef struct
00714 {
00715     /* QZSS LEX ionosphere correction type */
00716     gtime_t t0; /* epoch time (GPST) */
00717     double tspan; /* valid time span (s) */
00718     double pos0[2]; /* reference position {lat,lon} (rad) */
00719     double coef[3][2]; /* coefficients lat x lon (3 x 2) */
00720 } lexion_t;
00721
00722 typedef struct
00723 {
00724     /* stec data type */
00725     gtime_t time; /* time (GPST) */
00726     unsigned char sat; /* satellite number */
00727     double ion; /* slant ionos delay (m) */
00728     float std; /* std-dev (m) */
00729     float azel[2]; /* azimuth/elevation (rad) */
00730     unsigned char flag; /* fix flag */
00731 } stec_t;
00732
00733 typedef struct
00734 {
00735     /* trop data type */
00736     gtime_t time; /* time (GPST) */
00737     double trp[3]; /* zenith tropos delay/gradient (m) */
00738     float std[3]; /* std-dev (m) */
00739 } trop_t;
00740
00741 typedef struct
00742 {
00743     /* ppp corrections type */
00744     int nsta; /* number of stations */
00745     char stas[MAXSTA][8]; /* station names */
00746     double rr[MAXSTA][3]; /* station ecef positions (m) */
00747     int ns[MAXSTA], nsmax[MAXSTA]; /* number of stec data */
00748     int nt[MAXSTA], ntmax[MAXSTA]; /* number of trop data */
00749     stec_t *stec[MAXSTA]; /* stec data */
00750     trop_t *trop[MAXSTA]; /* trop data */
00751 } pppcorr_t;
00752
00753 typedef struct
00754 {
00755     /* navigation data type */
00756     int n, nmax; /* number of broadcast ephemeris */
00757     int ng, ngmax; /* number of glonass ephemeris */
00758     int ns, nsmax; /* number of sbas ephemeris */
00759     int ne, nemax; /* number of precise ephemeris */
00760     int nc, ncmax; /* number of precise clock */
00761     int na, namax; /* number of almanac data */
00762     int nt, ntmax; /* number of tec grid data */
00763     int nf, nfmax; /* number of satellite fcb data */
00764     eph_t *eph; /* GPS/QZS/GAL ephemeris */
00765     geph_t *geph; /* GLONASS ephemeris */
00766     seph_t *seph; /* SBAS ephemeris */
00767     peph_t *peph; /* precise ephemeris */
00768     pclk_t *pclk; /* precise clock */
00769     alm_t *alm; /* almanac data */
00770     tec_t *tec; /* tec grid data */
00771     fcbd_t *fcbd; /* satellite fcb data */
00772     erp_t *erp; /* earth rotation parameters */
00773     double utc_gps[4]; /* GPS delta-UTC parameters {A0,A1,T,W} */
00774     double utc_glo[4]; /* GLONASS UTC GPS time parameters */
00775     double utc_gal[4]; /* Galileo UTC GPS time parameters */
00776     double utc_gzs[4]; /* QZS UTC GPS time parameters */
00777     double utc_cmp[4]; /* BeiDou UTC parameters */
00778     double utc_irn[4]; /* IRNSS UTC parameters */
00779     double utc_sbs[4]; /* SBAS UTC parameters */
00780     double ion_gps[8]; /* GPS iono model parameters {a0,a1,a2,a3,b0,b1,b2,b3} */
00781     double ion_gal[4]; /* Galileo iono model parameters {ai0,ai1,ai2,0} */

```



```

00781     double ion_qzs[8];           /* QZSS iono model parameters {a0,a1,a2,a3,b0,b1,b2,b3} */
00782     double ion_cmp[8];           /* BeiDou iono model parameters {a0,a1,a2,a3,b0,b1,b2,b3} */
00783     double ion_irn[8];           /* IRNSS iono model parameters {a0,a1,a2,a3,b0,b1,b2,b3} */
00784     int leaps;                   /* leap seconds (s) */
00785     double lam[MAXSAT][NFREQ];   /* carrier wave lengths (m) */
00786     double cbias[MAXSAT][3];     /* satellite dcb (0:p1-p2,1:p1-c1,2:p2-c2) (m) */
00787     double rbias[MAXRCV][2][3];  /* receiver dcb (0:p1-p2,1:p1-c1,2:p2-c2) (m) */
00788     double wlbias[MAXSAT];       /* wide-lane bias (cycle) */
00789     double glo_cpbias[4];        /* glonass code-phase bias {1C,1P,2C,2P} (m) */
00790     char glo_fcn[MAXPRNGLO + 1]; /* glonass frequency channel number + 8 */
00791     pcv_t pcvs[MAXSAT];          /* satellite antenna pcv */
00792     sbssat_t sbssat;             /* SBAS satellite corrections */
00793     sbsion_t sbsion[MAXBAND + 1]; /* SBAS ionosphere corrections */
00794     dgps_t dgps[MAXSAT];         /* DGPS corrections */
00795     ssr_t ssr[MAXSAT];           /* SSR corrections */
00796     lexeph_t lexeph[MAXSAT];     /* LEX ephemeris */
00797     lexion_t lexion;             /* LEX ionosphere correction */
00798     pppcorr_t pppcorr;           /* ppp corrections */
00799 } nav_t;
00800
00801
00802 typedef struct
00803 {
00804     char name[MAXANT];           /* station parameter type */
00805     char marker[MAXANT];         /* marker name */
00806     char antdes[MAXANT];         /* marker number */
00807     char antsno[MAXANT];         /* antenna descriptor */
00808     char anttype[MAXANT];        /* antenna serial number */
00809     char rectype[MAXANT];        /* receiver type descriptor */
00810     char recver[MAXANT];         /* receiver firmware version */
00811     char recsno[MAXANT];         /* receiver serial number */
00812     int antsetup;                /* antenna setup id */
00813     int itrfr;                   /* ITRF realization year */
00814     int deltype;                 /* antenna delta type (0:enu,1:xyz) */
00815     double pos[3];               /* station position (ecef) (m) */
00816     double del[3];               /* antenna position delta (e/n/u or x/y/z) (m) */
00817     double hgt;                  /* antenna height (m) */
00818 } sta_t;
00819
00820 typedef struct
00821 {
00822     /* solution type */
00823     gtime_t time;                /* time (GPST) */
00824     double rr[6];                /* position/velocity (m|m/s) */
00825     float qr[6];                 /* {x,y,z,vx,vy,vz} or {e,n,u,ve,vn,vu} */
00826     /* position variance/covariance (m^2) */
00827     /* {c_xx,c_yy,c_zz,c_xy,c_yz,c_zx} or */
00828     /* {c_ee,c_nn,c_uu,c_en,c_nu,c_ue} */
00829     double dtr[6];               /* receiver clock bias to time systems (s) */
00830     unsigned char type;          /* type (0:xyz-ecef,1:enu-baseline) */
00831     unsigned char stat;          /* solution status (SOLQ_???) */
00832     unsigned char ns;            /* number of valid satellites */
00833     float age;                   /* age of differential (s) */
00834     float ratio;                 /* AR ratio factor for validation */
00835     float thres;                 /* AR ratio threshold for validation */
00836 } sol_t;
00837
00838 typedef struct
00839 {
00840     /* solution buffer type */
00841     int n, nmax;                 /* number of solution/max number of buffer */
00842     int cyclic;                  /* cyclic buffer flag */
00843     int start, end;              /* start/end index */
00844     gtime_t time;                /* current solution time */
00845     sol_t *data;                 /* solution data */
00846     double rb[3];                /* reference position {x,y,z} (ecef) (m) */
00847     unsigned char buff[MAXSOLMSG + 1]; /* message buffer */
00848     int nb;                      /* number of byte in message buffer */
00849 } solbuf_t;
00850
00851 typedef struct
00852 {
00853     /* solution status type */
00854     gtime_t time;                /* time (GPST) */
00855     unsigned char sat;            /* satellite number */
00856     unsigned char frq;            /* frequency (1:L1,2:L2,...) */
00857     float az, el;                /* azimuth/elevation angle (rad) */
00858     float resp;                  /* pseudorange residual (m) */
00859     float resc;                  /* carrier-phase residual (m) */
00860     unsigned char flag;           /* flags: (vsat<5)+(slip<3)+fix */
00861     unsigned char snr;            /* signal strength (0.25 dBHz) */
00862     unsigned short lock;          /* lock counter */
00863     unsigned short outc;          /* outage counter */
00864     unsigned short slipc;         /* slip counter */
00865     unsigned short rejcc;         /* reject counter */
00866 } solstat_t;
00867

```



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00868 typedef struct
00869 {
00870     int n, nmax;          /* solution status buffer type */
00871     solstat_t *data;      /* number of solution/max number of buffer */
00872 } solstatbuf_t;
00873
00874
00875 typedef struct
00876 {
00877     int staid;             /* RTCM control struct type */
00878     int stah;             /* station id */
00879     int seqno;            /* station health */
00880     int outtype;          /* sequence number for rtcm 2 or iods msm */
00881     gtime_t time;         /* output message type */
00882     gtime_t time_s;      /* message time */
00883     obs_t obs;           /* message start time */
00884     nav_t nav;           /* observation data (uncorrected) */
00885     sta_t sta;           /* satellite ephemerides */
00886     dgps_t *dgps;        /* station parameters */
00887     ssr_t ssr[MAXSAT];   /* output of dgps corrections */
00888     char msg[128];        /* output of ssr corrections */
00889     char msgtype[256];    /* special message */
00890     char msmttype[6][128]; /* last message type */
00891     int obsflag;         /* msm signal types */
00892     int ephsat;          /* obs data complete flag (1:ok,0:not complete) */
00893     double cp[MAXSAT][NFREQ + NEXOBS]; /* update satellite of ephemeris */
00894     unsigned short lock[MAXSAT][NFREQ + NEXOBS]; /* carrier-phase measurement */
00895     unsigned short loss[MAXSAT][NFREQ + NEXOBS]; /* lock time */
00896     gtime_t lltime[MAXSAT][NFREQ + NEXOBS]; /* loss of lock count */
00897     int nbyte;           /* last lock time */
00898     int nbit;            /* number of bytes in message buffer */
00899     int len;             /* number of bits in word buffer */
00900     unsigned char buff[1200]; /* message length (bytes) */
00901     unsigned int word;    /* message buffer */
00902     unsigned int nmsg2[100]; /* word buffer for rtcm 2 */
00903     unsigned int nmsg3[400]; /* message count of RTCM 2 (1-99:1-99,0:other) */
00904     /* (1-299:1001-1299,300-399:2000-2099,0:other) */
00905     char opt[256];        /* message count of RTCM 3 */
00906     /* RTCM dependent options */
00907 } rtcm_t;
00908
00909 typedef struct
00910 {
00911     char type[32];        /* download url type */
00912     char path[1024];      /* data type */
00913     char dir[1024];       /* url path */
00914     double tint;         /* local directory */
00915     /* time interval (s) */
00916 } url_t;
00917
00918 typedef struct
00919 {
00920     const char *name;     /* option type */
00921     int format;           /* option name */
00922     void *var;            /* option format (0:int,1:double,2:string,3:enum) */
00923     const char *comment;  /* pointer to option variable */
00924     /* option comment/enum labels/unit */
00925 } opt_t;
00926
00927 typedef struct
00928 {
00929     int ena[4];           /* extended receiver error model */
00930     double cerr[4][NFREQ * 2]; /* model enabled */
00931     double perr[4][NFREQ * 2]; /* code errors (m) */
00932     double gpsglob[NFREQ]; /* carrier-phase errors (m) */
00933     double gloicb[NFREQ]; /* gps-glonass h/w bias (m) */
00934     /* glonass interchannel bias (m/fn) */
00935 } exterr_t;
00936
00937 typedef struct
00938 {
00939     int ena[2];           /* SNR mask type */
00940     double mask[NFREQ][9]; /* enable flag {rover,base} */
00941     /* mask (dBHz) at 5,10,...85 deg */
00942 } snrmask_t;
00943
00944 typedef struct
00945 {
00946     int mode;             /* processing options type */
00947     int soltype;          /* positioning mode (PMODE_???) */
00948     int nf;               /* solution type (0:forward,1:backward,2:combined) */
00949     int navsys;           /* number of frequencies (1:L1,2:L1+L2,3:L1+L2+L5) */
00950     double elmin;         /* navigation system */
00951     snrmask_t snrmask;    /* elevation mask angle (rad) */
00952     int sateph;           /* SNR mask */
00953     int modear;           /* satellite ephemeris/clock (EPHOPT_???) */
00954     /* AR mode (0:off,1:continuous,2:instantaneous,3:fix and hold,4:ppp-ar) */

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```

00953     int glomodear;          /* GLONASS AR mode (0:off,1:on,2:auto cal,3:ext cal) */
00954     int bdsmodear;          /* BeiDou AR mode (0:off,1:on) */
00955     int maxout;             /* obs outage count to reset bias */
00956     int minlock;            /* min lock count to fix ambiguity */
00957     int minfix;             /* min fix count to hold ambiguity */
00958     int armaxiter;          /* max iteration to resolve ambiguity */
00959     int ionoopt;            /* ionosphere option (IONOOPT_???) */
00960     int tropopt;            /* troposphere option (TROPOPT_???) */
00961     int dynamics;           /* dynamics model (0:none,1:velocity,2:accel) */
00962     int tidecorr;           /* earth tide correction (0:off,1:solid,2:solid+otl+pole) */
00963     int niter;              /* number of filter iteration */
00964     int codesmooth;         /* code smoothing window size (0:none) */
00965     int intpref;            /* interpolate reference obs (for post mission) */
00966     int sbascorr;           /* SBAS correction options */
00967     int sbassatsel;         /* SBAS satellite selection (0:all) */
00968     int rovpos;             /* rover position for fixed mode */
00969     int refpos;             /* base position for relative mode */
00970                             /* (0:pos in prcpt, 1:average of single pos, */
00971                             /* 2:read from file, 3:rinex header, 4:rtcm pos) */
00972     double eratio[NFREQ];   /* code/phase error ratio */
00973     double err[5];          /* measurement error factor */
00974                             /* [0]:reserved */
00975                             /* [1-3]:error factor a/b/c of phase (m) */
00976                             /* [4]:doppler frequency (hz) */
00977     double std[3];          /* initial-state std [0]bias,[1]iono [2]trop */
00978     double prn[6];          /* process-noise std [0]bias,[1]iono [2]trop [3]acch [4]accv [5] pos
*/
00979     double sclkstab;        /* satellite clock stability (sec/sec) */
00980     double thresar[8];      /* AR validation threshold */
00981     double elmaskar;        /* elevation mask of AR for rising satellite (deg) */
00982     double elmaskhold;      /* elevation mask to hold ambiguity (deg) */
00983     double thresslip;       /* slip threshold of geometry-free phase (m) */
00984     double maxtdiff;         /* max difference of time (sec) */
00985     double maxinno;         /* reject threshold of innovation (m) */
00986     double maxgdp;          /* reject threshold of gdop */
00987     double baseline[2];     /* baseline length constraint {const,sigma} (m) */
00988     double ru[3];           /* rover position for fixed mode {x,y,z} (ecef) (m) */
00989     double rb[3];           /* base position for relative mode {x,y,z} (ecef) (m) */
00990     char anttype[2][MAXANT]; /* antenna types {rover,base} */
00991     double antdel[2][3];    /* antenna delta {{rov_e,rov_n,rov_u},{ref_e,ref_n,ref_u}} */
00992     pcvt_t pcvr[2];         /* receiver antenna parameters {rov,base} */
00993     unsigned char exsats[MAXSAT]; /* excluded satellites (1:excluded,2:included) */
00994     int maxaveep;           /* max averaging epoches */
00995     int initrst;            /* initialize by restart */
00996     int outsingle;          /* output single by dgps/float/fix/ppp outage */
00997     char rxnopt[2][256];    /* rinex options {rover,base} */
00998     int posopt[6];          /* positioning options */
00999     int syncsol;            /* solution sync mode (0:off,1:on) */
01000     double odis[2][6 * 11]; /* ocean tide loading parameters {rov,base} */
01001     exterr_t exterr;        /* extended receiver error model */
01002     int freqopt;            /* disable L2-AR */
01003     char pppopt[256];       /* ppp option */
01004     bool bancroft_init;     /* enable Bancroft initialization for the first iteration of the PVT
computation */
01005 } prcpt_t;
01006
01007
01008 typedef struct
01009 {
01010     int posf;               /* solution options type */
01011     int times;              /* solution format (SOLF_???) */
01012     int timef;              /* time system (TIMES_???) */
01013     int timeu;              /* time format (0:sssss.s,1:yyyy/mm/dd hh:mm:ss.s) */
01014     int degf;               /* time digits under decimal point */
01015     int outdeg;             /* latitude/longitude format (0:ddd.ddd,1:ddd mm ss) */
01016     int outhead;            /* output header (0:no,1:yes) */
01017     int datum;              /* output processing options (0:no,1:yes) */
01018     int height;             /* datum (0:WGS84,1:Tokyo) */
01019     int geoid;              /* height (0:ellipsoidal,1:geodetic) */
01020     int solstatic;          /* geoid model (0:EGM96,1:JGD2000) */
01021     int sstat;              /* solution of static mode (0:all,1:single) */
01022     int trace;              /* solution statistics level (0:off,1:states,2:residuals) */
01023     double nmeaintv[2];     /* debug trace level (0:off,1-5:debug) */
01024                             /* nmea output interval (s) (<0:no,0:all) */
01025     char sep[64];           /* nmeaintv[0]:gprmc,pggga,nmeaintv[1]:pggsv */
01026     char prog[64];          /* field separator */
01027     double maxsolstd;       /* program name */
01028 } solopt_t;                /* max std-dev for solution output (m) (0:all) */
01029
01030
01031 typedef struct
01032 {
01033     unsigned char sys;       /* satellite status type */
01034     unsigned char vs;        /* navigation system */
01035     double azel[2];          /* valid satellite flag single */
01036     double resp[NFREQ];      /* azimuth/elevation angles {az,el} (rad) */
01037     double resc[NFREQ];      /* residuals of pseudorange (m) */
01038                             /* residuals of carrier-phase (m) */

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01038     unsigned char vsat[NFREQ]; /* valid satellite flag */
01039     unsigned char snr[NFREQ]; /* signal strength (0.25 dBHz) */
01040     unsigned char fix[NFREQ]; /* ambiguity fix flag (1:fix,2:float,3:hold) */
01041     unsigned char slip[NFREQ]; /* cycle-slip flag */
01042     unsigned char half[NFREQ]; /* half-cycle valid flag */
01043     int lock[NFREQ]; /* lock counter of phase */
01044     unsigned int outc[NFREQ]; /* obs outage counter of phase */
01045     unsigned int slipc[NFREQ]; /* cycle-slip counter */
01046     unsigned int rejc[NFREQ]; /* reject counter */
01047     double gf; /* geometry-free phase L1-L2 (m) */
01048     double gf2; /* geometry-free phase L1-L5 (m) */
01049     double mw; /* MW-LC (m) */
01050     double phw; /* phase windup (cycle) */
01051     gtime_t pt[2][NFREQ]; /* previous carrier-phase time */
01052     double ph[2][NFREQ]; /* previous carrier-phase observable (cycle) */
01053 } ssat_t;
01054
01055
01056 typedef struct
01057 {
01058     /* ambiguity control type */
01059     gtime_t epoch[4]; /* last epoch */
01060     int n[4]; /* number of epochs */
01061     double LC[4]; /* linear combination average */
01062     double LCv[4]; /* linear combination variance */
01063     int fixcnt; /* fix count */
01064     char flags[MAXSAT]; /* fix flags */
01065 } ambc_t;
01066
01067 typedef struct
01068 {
01069     /* RTK control/result type */
01070     sol_t sol; /* RTK solution */
01071     double rb[6]; /* base position/velocity (ecef) (m|m/s) */
01072     int nx, na; /* number of float states/fixed states */
01073     double tt; /* time difference between current and previous (s) */
01074     double *x, *P; /* float states and their covariance */
01075     double *xa, *Pa; /* fixed states and their covariance */
01076     int nfix; /* number of continuous fixes of ambiguity */
01077     ambc_t ambc[MAXSAT]; /* ambiguity control */
01078     ssat_t ssat[MAXSAT]; /* satellite status */
01079     int neb; /* bytes in error message buffer */
01080     char errbuf[MAXERRMSG]; /* error message buffer */
01081     prcopt_t opt; /* processing options */
01082 } rtk_t;
01083
01084 typedef struct half_cyc_tag
01085 {
01086     /* half-cycle correction list type */
01087     unsigned char sat; /* satellite number */
01088     unsigned char freq; /* frequency number (0:L1,1:L2,2:L5) */
01089     unsigned char valid; /* half-cycle valid flag */
01090     char corr; /* half-cycle corrected (x 0.5 cyc) */
01091     gtime_t ts, te; /* time start, time end */
01092     struct half_cyc_tag *next; /* pointer to next correction */
01093 } half_cyc_t;
01094
01095 typedef struct
01096 {
01097     /* stream type */
01098     int type; /* type (STR_???) */
01099     int mode; /* mode (STR_MODE_?) */
01100     int state; /* state (-1:error,0:close,1:open) */
01101     unsigned int inb, inr; /* input bytes/rate */
01102     unsigned int outb, outr; /* output bytes/rate */
01103     unsigned int tick, tact; /* tick/active tick */
01104     unsigned int inbt, outbt; /* input/output bytes at tick */
01105     lock_t lock; /* lock flag */
01106     void *port; /* type dependent port control struct */
01107     char path[MAXSTRPATH]; /* stream path */
01108     char msg[MAXSTRMSG]; /* stream message */
01109 } stream_t;
01110
01111 typedef struct
01112 {
01113     /* serial control type */
01114     dev_t dev; /* serial device */
01115     int error; /* error state */
01116 } serial_t;
01117
01118 struct file_t
01119 {
01120     /* file control type */
01121     FILE *fp = nullptr; /* file pointer */
01122     FILE *fp_tag = nullptr; /* file pointer of tag file */
01123     FILE *fp_tmp = nullptr; /* temporary file pointer for swap */
01124     FILE *fp_tag_tmp = nullptr; /* temporary file pointer of tag file for swap */
01125     std::string path; /* file path */

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01125     std::string openpath;          /* open file path */
01126     int mode = 0;                  /* file mode */
01127     int timetag;                  /* time tag flag (0:off,1:on) */
01128     int repmode = 0;              /* replay mode (0:master,1:slave) */
01129     int offset = 0;               /* time offset (ms) for slave */
01130     gtime_t time = {};            /* start time */
01131     gtime_t wtime = {};           /* write time */
01132     unsigned int tick = 0;        /* start tick */
01133     unsigned int tick_f = 0;      /* start tick in file */
01134     unsigned int fpos = 0;        /* current file position */
01135     double start = 0;             /* start offset (s) */
01136     double speed = 0;             /* replay speed (time factor) */
01137     double swapintv = 0;          /* swap interval (hr) (0: no swap) */
01138     lock_t lock;                  /* lock flag */
01139 };
01140
01141
01142 typedef struct
01143 {
01144     int state;                    /* tcp control type */
01145     char saddr[256];             /* address string */
01146     int port;                    /* port */
01147     struct sockaddr_in addr;      /* address resolved */
01148     socket_t sock;               /* socket descriptor */
01149     int tcon;                    /* reconnect time (ms) (-1:never,0:now) */
01150     unsigned int tact;           /* data active tick */
01151     unsigned int tdis;           /* disconnect tick */
01152 } tcp_t;
01153
01154
01155 typedef struct
01156 {
01157     tcp_t svr;                   /* tcp server type */
01158     tcp_t cli[MAXCLI];          /* tcp client controls */
01159 } tcpsvr_t;
01160
01161
01162 typedef struct
01163 {
01164     tcp_t svr;                   /* tcp server control */
01165     int toinact;                 /* inactive timeout (ms) (0:no timeout) */
01166     int tirecon;                 /* reconnect interval (ms) (0:no reconnect) */
01167 } tcpcli_t;
01168
01169
01170 typedef struct
01171 {
01172     int state;                   /* ntrip control type */
01173     int type;                    /* state (0:close,1:wait,2:connect) */
01174     int nb;                      /* type (0:server,1:client) */
01175     char url[256];               /* response buffer size */
01176     char mntpnt[256];            /* url for proxy */
01177     char user[256];              /* mountpoint */
01178     char passwd[256];            /* user */
01179     char str[NTRIP_MAXSTR];       /* password */
01180     unsigned char buff[NTRIP_MAXRSP]; /* mountpoint string for server */
01181     tcpcli_t *tcp;               /* response buffer */
01182 } ntrip_t;
01183
01184
01185 typedef struct
01186 {
01187     int state;                   /* ftp download control type */
01188     int proto;                   /* state (0:close,1:download,2:complete,3:error) */
01189     int error;                   /* protocol (0:ftp,1:http) */
01190     /* error code (0:no error,1-10:wget error, */
01191     /* 11:no temp dir,12:uncompact error) */
01192     char addr[1024];             /* download address */
01193     char file[1024];             /* download file path */
01194     char user[256];              /* user for ftp */
01195     char passwd[256];            /* password for ftp */
01196     char local[1024];            /* local file path */
01197     int topts[4];                /* time options {poff,tint,toff,tretry} (s) */
01198     gtime_t tnext;               /* next retry time (gpst) */
01199     pthread_t thread;            /* download thread */
01200 } ftp_t;
01201
01202 typedef struct
01203 {
01204     gtime_t time;                /* receiver raw data control type */
01205     gtime_t tobs;                /* message time */
01206     obs_t obs;                   /* observation data time */
01207     obs_t obuf;                  /* observation data */
01208     nav_t nav;                   /* observation data buffer */
01209     sta_t sta;                   /* satellite ephemerides */
01210     int ephsat;                  /* station parameters */
01211     sbsmsg_t sbsmsg;             /* sat number of update ephemeris (0:no satellite) */
01212     /* SBAS message */

```

```

01212     char msgtype[256];                /* last message type */
01213     unsigned char subfrm[MAXSAT][380]; /* subframe buffer */
01214     lexmsg_t lexmsg;                  /* LEX message */
01215     double lockt[MAXSAT][NFREQ + NEXOBS]; /* lock time (s) */
01216     double icpp[MAXSAT], off[MAXSAT], icpc; /* carrier params for ss2 */
01217     double prCA[MAXSAT], dpCA[MAXSAT]; /* L1/CA pseudorange/doppler for javad */
01218     unsigned char halfc[MAXSAT][NFREQ + NEXOBS]; /* half-cycle add flag */
01219     char freqn[MAXOBS];                /* frequency number for javad */
01220     int nbyte;                          /* number of bytes in message buffer */
01221     int len;                            /* message length (bytes) */
01222     int iod;                            /* issue of data */
01223     int tod;                            /* time of day (ms) */
01224     int tbase;                          /* time base (0:gpst,1:utc(usno),2:glonass,3:utc(su)
*/
01225     int flag;                          /* general purpose flag */
01226     int outtype;                       /* output message type */
01227     unsigned char buff[MAXRAWLEN];     /* message buffer */
01228     char opt[256];                     /* receiver dependent options */
01229     double receive_time;                /* RT17: Reiceve time of week for week rollover
detection */
01230     unsigned int plen;                  /* RT17: Total size of packet to be read */
01231     unsigned int pbyte;                 /* RT17: How many packet bytes have been read so far
*/
01232     unsigned int page;                  /* RT17: Last page number */
01233     unsigned int reply;                 /* RT17: Current reply number */
01234     int week;                           /* RT17: week number */
01235     unsigned char pbuff[255 + 4 + 2];  /* RT17: Packet buffer */
01236 } raw_t;
01237
01238
01239 typedef struct
01240 {
01241     int state;                          /* RTK server type */
01242     int cycle;                          /* server state (0:stop,1:running) */
01243     int nmeacycle;                      /* processing cycle (ms) */
01244     int nmeareq;                        /* NMEA request cycle (ms) (0:no req) */
01245     double nmeapos[3];                 /* NMEA request (0:no,1:nmeapos,2:single sol) */
01246     int buffsize;                      /* NMEA request position (ecef) (m) */
01247     int format[3];                     /* input buffer size (bytes) */
01248     solopt_t solopt[2];                 /* input format {rov,base,corr} */
01249     int navsel;                        /* output solution options {sol1,sol2} */
01250     int nsbs;                          /* ephemeris select (0:all,1:rover,2:base,3:corr) */
01251     int nsol;                          /* number of sbas message */
01252     rtk_t rtk;                         /* number of solution buffer */
01253     int nb[3];                         /* RTK control/result struct */
01254     int nsb[2];                        /* bytes in input buffers {rov,base} */
01255     int npb[3];                        /* bytes in solution buffers */
01256     unsigned char *buff[3];            /* bytes in input peek buffers */
01257     unsigned char *sbuf[2];            /* input buffers {rov,base,corr} */
01258     unsigned char *pbuf[3];            /* output buffers {sol1,sol2} */
01259     sol_t solbuf[MAXSOLBUF];           /* peek buffers {rov,base,corr} */
01260     unsigned int nmsg[3][10];          /* solution buffer */
01261     raw_t raw[3];                      /* input message counts */
01262     rtkcm_t rtkcm[3];                  /* receiver raw control {rov,base,corr} */
01263     gtime_t ftime[3];                  /* RTCM control {rov,base,corr} */
01264     char files[3][MAXSTRPATH];         /* download time {rov,base,corr} */
01265     obs_t obs[3][MAXOBSBUF];           /* download paths {rov,base,corr} */
01266     nav_t nav;                         /* observation data {rov,base,corr} */
01267     sbmsg_t sbmsg[MAXSBMSG];           /* navigation data */
01268     stream_t stream[8];                /* SBAS message buffer */
01269     stream_t *moni;                   /* streams {rov,base,corr,sol1,sol2,logr,logb,logc} */
01270     unsigned int tick;                 /* monitor stream */
01271     pthread_t thread;                  /* start tick */
01272     int cputime;                       /* server thread */
01273     int prcout;                        /* CPU time (ms) for a processing cycle */
01274     lock_t lock;                       /* missing observation data count */
01275 } rtksvr_t;
01276
01277 typedef struct
01278 {
01279     unsigned char iod;                  /* multi-signal-message header type */
01280     unsigned char time_s;               /* issue of data station */
01281     unsigned char clk_str;              /* cumulative session transmitting time */
01282     unsigned char clk_ext;              /* clock steering indicator */
01283     unsigned char smooth;               /* external clock indicator */
01284     unsigned char tint_s;               /* divergence free smoothing indicator */
01285     unsigned char nsat, nsig;           /* soothing interval */
01286     unsigned char sats[64];             /* number of satellites/signals */
01287     unsigned char sigs[32];             /* satellites */
01288     unsigned char cellmask[64];         /* signals */
01289 } msm_h_t;
01290
01291
01292 const double CHISQR[100] = { /* chi-sqr(n) (alpha=0.001) */
01293     10.8, 13.8, 16.3, 18.5, 20.5, 22.5, 24.3, 26.1, 27.9, 29.6,
01294     31.3, 32.9, 34.5, 36.1, 37.7, 39.3, 40.8, 42.3, 43.8, 45.3,
01295     46.8, 48.3, 49.7, 51.2, 52.6, 54.1, 55.5, 56.9, 58.3, 59.7,

```

```

01296      61.1, 62.5, 63.9, 65.2, 66.6, 68.0, 69.3, 70.7, 72.1, 73.4,
01297      74.7, 76.0, 77.3, 78.6, 80.0, 81.3, 82.6, 84.0, 85.4, 86.7,
01298      88.0, 89.3, 90.6, 91.9, 93.3, 94.7, 96.0, 97.4, 98.7, 100,
01299      101, 102, 103, 104, 105, 107, 108, 109, 110, 112,
01300      113, 114, 115, 116, 118, 119, 120, 122, 123, 125,
01301      126, 127, 128, 129, 131, 132, 133, 134, 135, 137,
01302      138, 139, 140, 142, 143, 144, 145, 147, 148, 149};
01303
01304
01305 const double LAM_CARR[MAXFREQ] = { /* carrier wave length (m) */
01306     SPEED_OF_LIGHT_M_S / FREQ1, SPEED_OF_LIGHT_M_S / FREQ2, SPEED_OF_LIGHT_M_S / FREQ5,
01307     SPEED_OF_LIGHT_M_S / FREQ6, SPEED_OF_LIGHT_M_S / FREQ7,
01308     SPEED_OF_LIGHT_M_S / FREQ8, SPEED_OF_LIGHT_M_S / FREQ9};
01309
01309 const int STRFMT_RTCM2 = 0; /* stream format: RTCM 2 */
01310 const int STRFMT_RTCM3 = 1; /* stream format: RTCM 3 */
01311 const int STRFMT_SP3 = 16; /* stream format: SP3 */
01312 const int STRFMT_RNXCLK = 17; /* stream format: RINEX CLK */
01313 const int STRFMT_SBAS = 18; /* stream format: SBAS messages */
01314 const int STRFMT_NMEA = 19; /* stream format: NMEA 0183 */
01315 // const solopt_t solopt_default; /* default solution output options */
01316
01317 const int MAXSTRRTK = 8; /* max number of stream in RTK server */
01318
01319 /** \} */
01320 /** \} */
01321 #endif // GNSS_SDR_RTKLIB_H

```

13.212 rtklib_conversions.h File Reference

GNSS-SDR to RTKLIB data structures conversion functions.

```

#include "rtklib.h"
#include <stdint>
#include <map>
#include <string>

```

Classes

- class [HAS_clock_corrections](#)
- class [HAS_orbit_corrections](#)
- class [HAS_obs_corrections](#)

Functions

- [eph_t eph_to_rtklib](#) (const [Galileo_Ephemeris](#) &gal_eph)
 - [eph_t eph_to_rtklib](#) (const [Galileo_Ephemeris](#) &gal_eph, const std::map< int, [HAS_orbit_corrections](#) > &orbit_correction_map, const std::map< int, [HAS_clock_corrections](#) > &clock_correction_map)
 - [eph_t eph_to_rtklib](#) (const [Gps_Ephemeris](#) &gps_eph, bool pre_2009_file=false)
 - [eph_t eph_to_rtklib](#) (const [Gps_Ephemeris](#) &gps_eph, const std::map< int, [HAS_orbit_corrections](#) > &orbit_correction_map, const std::map< int, [HAS_clock_corrections](#) > &clock_correction_map, bool pre_2009_file=false)
 - [eph_t eph_to_rtklib](#) (const [Gps_CNAV_Ephemeris](#) &gps_cnav_eph)
 - [eph_t eph_to_rtklib](#) (const [Beidou_Dnav_Ephemeris](#) &bei_eph)
 - [alm_t alm_to_rtklib](#) (const [Gps_Almanac](#) &gps_alm)
 - [alm_t alm_to_rtklib](#) (const [Galileo_Almanac](#) &gal_alm)
 - [geph_t eph_to_rtklib](#) (const [Glonass_Gnav_Ephemeris](#) &glonass_gnav_eph, const [Glonass_Gnav_Utc_Model](#) &gnav_clock_model)
- Transforms a [Glonass_Gnav_Ephemeris](#) to its RTKLIB counterpart.*
- [obsd_t insert_obs_to_rtklib](#) ([obsd_t](#) &rtklib_obs, const [Gnss_Synchro](#) &gnss_synchro, const std::map< std::string, std::map< int, [HAS_obs_corrections](#) > > &has_obs_corr, int week, int band, bool pre_2009_file=false)
 - [obsd_t insert_obs_to_rtklib](#) ([obsd_t](#) &rtklib_obs, const [Gnss_Synchro](#) &gnss_synchro, int week, int band, bool pre_2009_file=false)

13.212.1 Detailed Description

GNSS-SDR to RTKLIB data structures conversion functions.

Author

2017, Javier Arribas

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors) SPDX-License-Identifier: GPL-3.0-or-later
 Definition in file [rtklib_conversions.h](#).

13.213 rtklib_conversions.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file rtklib_conversions.h
00003  * \brief GNSS-SDR to RTKLIB data structures conversion functions
00004  * \author 2017, Javier Arribas
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_RTKLIB_CONVERSIONS_H
00018 #define GNSS_SDR_RTKLIB_CONVERSIONS_H
00019
00020 #include "rtklib.h"
00021 #include <cstdint>
00022 #include <map>
00023 #include <string>
00024
00025 /** \addtogroup PVT
00026  * \{ */
00027 /** \addtogroup RTKLIB_Library
00028  * \{ */
00029
00030
00031 class Beidou_Dnav_Ephemeris;
00032 class Galileo_Almanac;
00033 class Galileo_Ephemeris;
00034 class Glonass_Gnav_Ephemeris;
00035 class Glonass_Gnav_Utc_Model;
00036 class Gnss_Synchro;
00037 class Gps_Almanac;
00038 class Gps_CNAV_Ephemeris;
00039 class Gps_Ephemeris;
00040
00041 class HAS_clock_corrections
00042 {
00043 public:
00044     HAS_clock_corrections() = default;
00045     float clock_correction_m{};
00046     uint32_t valid_until{};
00047 };
00048
00049 class HAS_orbit_corrections
00050 {
00051 public:
00052     HAS_orbit_corrections() = default;
00053     float radial_m{};
00054     float in_track_m{};
00055     float cross_track_m{};
00056     uint32_t valid_until{};
00057     uint16_t iod{};
00058 };
00059
00060 class HAS_obs_corrections
00061 {
00062 public:
00063     HAS_obs_corrections() = default;
00064     float code_bias_m{};
00065     float phase_bias_cycle{};
00066 };
00067

```



```

00068
00069 eph_t eph_to_rtklib(const Galileo_Ephemeris& gal_eph);
00070
00071 eph_t eph_to_rtklib(const Galileo_Ephemeris& gal_eph,
00072     const std::map<int, HAS_orbit_corrections>& orbit_correction_map,
00073     const std::map<int, HAS_clock_corrections>& clock_correction_map);
00074
00075 eph_t eph_to_rtklib(const Gps_Ephemeris& gps_eph,
00076     bool pre_2009_file = false);
00077
00078 eph_t eph_to_rtklib(const Gps_Ephemeris& gps_eph,
00079     const std::map<int, HAS_orbit_corrections>& orbit_correction_map,
00080     const std::map<int, HAS_clock_corrections>& clock_correction_map,
00081     bool pre_2009_file = false);
00082
00083 eph_t eph_to_rtklib(const Gps_CNAV_Ephemeris& gps_cnav_eph);
00084 eph_t eph_to_rtklib(const Beidou_Dnav_Ephemeris& bei_eph);
00085
00086 alm_t alm_to_rtklib(const Gps_Almanac& gps_alm);
00087 alm_t alm_to_rtklib(const Galileo_Almanac& gal_alm);
00088
00089 /*!
00090 * \brief Transforms a Glonass_Gnav_Ephemeris to its RTKLIB counterpart
00091 * \param glonass_gnav_eph GLONASS GNAV Ephemeris structure
00092 * \return Ephemeris structure for RTKLIB parsing
00093 */
00094 gep_t eph_to_rtklib(const Glonass_Gnav_Ephemeris& glonass_gnav_eph, const Glonass_Gnav_Utc_Model&
    gnav_clock_model);
00095
00096 obsd_t insert_obs_to_rtklib(obsd_t& rtklib_obs,
00097     const Gnss_Synchro& gnss_synchro,
00098     const std::map<std::string, std::map<int, HAS_obs_corrections>& has_obs_corr,
00099     int week,
00100     int band,
00101     bool pre_2009_file = false);
00102
00103 obsd_t insert_obs_to_rtklib(obsd_t& rtklib_obs, const Gnss_Synchro& gnss_synchro, int week, int band,
    bool pre_2009_file = false);
00104
00105
00106 /** \} */
00107 /** \} */
00108 #endif // GNSS_SDR_RTKLIB_CONVERSIONS_H

```

13.214 rtklib_ephemeris.h File Reference

satellite ephemeris and clock functions

```
#include "rtklib.h"
```

Functions

- double **var_uraeph** (int ura)
- double **var_urassr** (int ura)
- void **alm2pos** (gtime_t time, const alm_t *alm, double *rs, double *dts)
- double **eph2clk** (gtime_t time, const eph_t *eph)
- void **eph2pos** (gtime_t time, const eph_t *eph, double *rs, double *dts, double *var)
- void **deq** (const double *x, double *xdot, const double *acc)
- void **glorbit** (double t, double *x, const double *acc)
- double **geph2clk** (gtime_t time, const gep_t *geph)
- void **geph2pos** (gtime_t time, const gep_t *geph, double *rs, double *dts, double *var)
- double **seph2clk** (gtime_t time, const seph_t *seph)
- void **seph2pos** (gtime_t time, const seph_t *seph, double *rs, double *dts, double *var)
- eph_t * **seleph** (gtime_t time, int sat, int iode, const nav_t *nav)
- gep_t * **selgeph** (gtime_t time, int sat, int iode, const nav_t *nav)
- seph_t * **selseph** (gtime_t time, int sat, const nav_t *nav)
- int **ephclk** (gtime_t time, gtime_t teph, int sat, const nav_t *nav, double *dts)
- int **ephpos** (gtime_t time, gtime_t teph, int sat, const nav_t *nav, int iode, double *rs, double *dts, double *var, int *svh)
- int **satpos_sbass** (gtime_t time, gtime_t teph, int sat, const nav_t *nav, double *rs, double *dts, double *var, int *svh)

- int **satpos_ssr** (gtime_t time, gtime_t teph, int sat, const nav_t *nav, int opt, double *rs, double *dts, double *var, int *svh)
- int **satpos** (gtime_t time, gtime_t teph, int sat, int ephopt, const nav_t *nav, double *rs, double *dts, double *var, int *svh)
- void **satposs** (gtime_t teph, const obsd_t *obs, int n, const nav_t *nav, int ephopt, double *rs, double *dts, double *var, int *svh)

13.214.1 Detailed Description

satellite ephemeris and clock functions

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

This is a derived work from RTKLIB <http://www.rtklib.com/> The original source code at <https://github.com/tomojitakasu/RTKLIB> is released under the BSD 2-clause license with an additional exclusive clause that does not apply here. This additional clause is reproduced below:

" The software package includes some companion executive binaries or shared libraries necessary to execute APs on Windows. These licenses succeed to the original ones of these software. "

Neither the executive binaries nor the shared libraries are required by, used or included in GNSS-SDR.

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Definition in file [rtklib_ephemeris.h](#).

13.215 rtklib_ephemeris.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib_ephemeris.h
00003  * \brief satellite ephemeris and clock functions
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
00011  * The original source code at https://github.com/tomojitakasu/RTKLIB is
00012  * released under the BSD 2-clause license with an additional exclusive clause
00013  * that does not apply here. This additional clause is reproduced below:
00014  *
00015  * " The software package includes some companion executive binaries or shared
00016  * libraries necessary to execute APs on Windows. These licenses succeed to the
00017  * original ones of these software. "
00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
00020  * or included in GNSS-SDR.
00021  *
00022  * -----
00023  * Copyright (C) 2007-2013, T. Takasu
00024  * Copyright (C) 2017, Javier Arribas
00025  * Copyright (C) 2017, Carles Fernandez
00026  * All rights reserved.
00027  *
00028  * SPDX-License-Identifier: BSD-2-Clause
00029  *
00030  * -----
00031  */
00032
00033
00034 #ifndef GNSS_SDR_RTKLIB_EPHEMERIS_H
00035 #define GNSS_SDR_RTKLIB_EPHEMERIS_H
00036
00037 #include "rtklib.h"
00038
00039
00040 double var_uraeph(int ura);
00041 double var_urassr(int ura);
```

```

00042 void alm2pos(gtime_t time, const alm_t *alm, double *rs, double *dts);
00043 double eph2clk(gtime_t time, const eph_t *eph);
00044 void eph2pos(gtime_t time, const eph_t *eph, double *rs, double *dts,
00045             double *var);
00046 void deq(const double *x, double *xdot, const double *acc);
00047 void glorbit(double t, double *x, const double *acc);
00048 double geph2clk(gtime_t time, const geph_t *geph);
00049
00050 void geph2pos(gtime_t time, const geph_t *geph, double *rs, double *dts,
00051             double *var);
00052 double seph2clk(gtime_t time, const seph_t *seph);
00053 void seph2pos(gtime_t time, const seph_t *seph, double *rs, double *dts,
00054             double *var);
00055 eph_t *seleph(gtime_t time, int sat, int iode, const nav_t *nav);
00056 geph_t *selgeph(gtime_t time, int sat, int iode, const nav_t *nav);
00057 seph_t *selseph(gtime_t time, int sat, const nav_t *nav);
00058 int ephclk(gtime_t time, gtime_t teph, int sat, const nav_t *nav,
00059           double *dts);
00060 // satellite position and clock by broadcast ephemeris
00061 int ephpos(gtime_t time, gtime_t teph, int sat, const nav_t *nav,
00062           int iode, double *rs, double *dts, double *var, int *svh);
00063 int satpos_sbas(gtime_t time, gtime_t teph, int sat, const nav_t *nav,
00064               double *rs, double *dts, double *var, int *svh);
00065 int satpos_ssr(gtime_t time, gtime_t teph, int sat, const nav_t *nav,
00066               int opt, double *rs, double *dts, double *var, int *svh);
00067
00068 int satpos(gtime_t time, gtime_t teph, int sat, int ephopt,
00069           const nav_t *nav, double *rs, double *dts, double *var,
00070           int *svh);
00071 void satpos(gtime_t teph, const obsd_t *obs, int n, const nav_t *nav,
00072           int ephopt, double *rs, double *dts, double *var, int *svh);
00073
00074
00075 #endif // GNSS_SDR_RTCLIB_EPHEMERIS_H

```

13.216 rtklib_ionex.h File Reference

ionex functions

```
#include "rtklib.h"
```

Functions

- int **getindex** (double value, const double *range)
- int **nitem** (const double *range)
- int **dataindex** (int i, int j, int k, const int *ndata)
- **tec_t** * **addtec** (const double *lats, const double *lons, const double *hgts, double rb, **nav_t** *nav)
- void **readionexdcb** (FILE *fp, double *dcb, double *rms)
- double **readionexh** (FILE *fp, double *lats, double *lons, double *hgts, double *rb, double *nexp, double *dcb, double *rms)
- int **readionexb** (FILE *fp, const double *lats, const double *lons, const double *hgts, double rb, double nexp, **nav_t** *nav)
- void **combtec** (**nav_t** *nav)
- void **readtec** (const char *file, **nav_t** *nav, int opt)
- int **interptec** (const **tec_t** *tec, int k, const double *posp, double *value, double *rms)
- int **iondelay** (**gtime_t** time, const **tec_t** *tec, const double *pos, const double *azel, int opt, double *delay, double *var)
- int **iontec** (**gtime_t** time, const **nav_t** *nav, const double *pos, const double *azel, int opt, double *delay, double *var)

Variables

- const double **VAR_NOTEC** = 30.0 * 30.0
- const double **MIN_EL** = 0.0
- const double **MIN_HGT** = -1000.0

13.216.1 Detailed Description

ionex functions

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

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Definition in file [rtklib_ionex.h](#).

13.216.2 Variable Documentation

13.216.2.1 MIN_EL

```
const double MIN_EL = 0.0
```

Definition at line 46 of file [rtklib_ionex.h](#).

13.216.2.2 MIN_HGT

```
const double MIN_HGT = -1000.0
```

Definition at line 47 of file [rtklib_ionex.h](#).

13.216.2.3 VAR_NOTEC

```
const double VAR_NOTEC = 30.0 * 30.0
```

Definition at line 45 of file [rtklib_ionex.h](#).

13.217 rtklib_ionex.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib_ionex.h
00003  * \brief ionex functions
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
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00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
00020  * or included in GNSS-SDR.
00021  *
00022  * -----
```

```

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00026 * All rights reserved.
00027 *
00028 * SPDX-License-Identifier: BSD-2-Clause
00029 *
00030 * References:
00031 * [1] S.Schear, W.Gurtner and J.Feltens, IONEX: The IONosphere Map EXchange
00032 *      Format Version 1, February 25, 1998
00033 * [2] S.Schaer, R.Markus, B.Gerhard and A.S.Timon, Daily Global Ionosphere
00034 *      Maps based on GPS Carrier Phase Data Routinely produced by CODE
00035 *      Analysis Center, Proceeding of the IGS Analysis Center Workshop, 1996
00036 *
00037 * -----
00038 */
00039
00040 #ifndef GNSS_SDR_RTKLIB_IONEX_H
00041 #define GNSS_SDR_RTKLIB_IONEX_H
00042
00043 #include "rtklib.h"
00044
00045 const double VAR_NOTEC = 30.0 * 30.0; /* variance of no tec */
00046 const double MIN_EL = 0.0; /* min elevation angle (rad) */
00047 const double MIN_HGT = -1000.0; /* min user height (m) */
00048
00049 int getindex(double value, const double *range);
00050
00051 int nitem(const double *range);
00052 int dataindex(int i, int j, int k, const int *ndata);
00053 tec_t *addtec(const double *lats, const double *lons, const double *hgts,
00054              double rb, nav_t *nav);
00055 void readionexdcb(FILE *fp, double *dcb, double *rms);
00056 double readionexh(FILE *fp, double *lats, double *lons, double *hgts,
00057                  double *rb, double *nexp, double *dcb, double *rms);
00058 int readionexb(FILE *fp, const double *lats, const double *lons,
00059               const double *hgts, double rb, double nexp, nav_t *nav);
00060 void combtec(nav_t *nav);
00061 void readtec(const char *file, nav_t *nav, int opt);
00062 int interptec(const tec_t *tec, int k, const double *posp, double *value,
00063              double *rms);
00064
00065 int iondelay(gtime_t time, const tec_t *tec, const double *pos,
00066              const double *azel, int opt, double *delay, double *var);
00067 int iontec(gtime_t time, const nav_t *nav, const double *pos,
00068            const double *azel, int opt, double *delay, double *var);
00069
00070 #endif // GNSS_SDR_RTKLIB_IONEX_H

```

13.218 rtklib_lambda.h File Reference

Integer ambiguity resolution.

```
#include "rtklib.h"
```

Macros

- #define [SGN_LAMBDA](#)(x)
- #define [ROUND_LAMBDA](#)(x)
- #define [SWAP_LAMBDA](#)(x, y)

Functions

- int **LD** (int n, const double *Q, double *L, double *D)
- void **gauss** (int n, double *L, double *Z, int i, int j)
- void **perm** (int n, double *L, double *D, int j, double del, double *Z)
- void **reduction** (int n, double *L, double *D, double *Z)
- int **search** (int n, int m, const double *L, const double *D, const double *zs, double *zn, double *s)
- int **lambda** (int n, int m, const double *a, const double *Q, double *F, double *s)
- int **lambda_reduction** (int n, const double *Q, double *Z)
- int **lambda_search** (int n, int m, const double *a, const double *Q, double *F, double *s)

Variables

- const int `LOOPMAX` = 10000

13.218.1 Detailed Description

Integer ambiguity resolution.

Authors

- 2007-2008, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

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References: [1] P.J.G.Teunissen, The least-square ambiguity decorrelation adjustment: a method for fast GPS ambiguity estimation, J.Geodesy, Vol.70, 65-82, 1995 [2] X.-W.Chang, X.Yang, T.Zhou, MLAMBDA: A modified LAMBDA method for integer least-squares estimation, J.Geodesy, Vol.79, 552-565, 2005

Definition in file [rtklib_lambda.h](#).

13.218.2 Macro Definition Documentation

13.218.2.1 ROUND_LAMBDA

```
#define ROUND_LAMBDA(  
    x)
```

Value:

```
(floor((x) + 0.5))
```

Definition at line 49 of file [rtklib_lambda.h](#).

13.218.2.2 SGN_LAMBDA

```
#define SGN_LAMBDA(  
    x)
```

Value:

```
((x) <= 0.0 ? -1.0 : 1.0)
```

Definition at line 48 of file [rtklib_lambda.h](#).

13.218.2.3 SWAP_LAMBDA

```
#define SWAP_LAMBDA(  
    x,  
    y)
```

Value:

```
do  
{  
    double tmp_;  
    tmp_ = x;  
    x = y;  
    y = tmp_;  
}  
while (0)
```

Definition at line 50 of file [rtklib_lambda.h](#).

13.218.3 Variable Documentation

13.218.3.1 LOOPMAX

const int LOOPMAX = 10000

Definition at line 47 of file `rtklib_lambda.h`.

13.219 rtklib_lambda.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file rtklib_lambda.h
00003  * \brief Integer ambiguity resolution
00004  * \authors <ul>
00005  *         <li> 2007-2008, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
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00030  * References:
00031  * [1] P.J.G.Teunissen, The least-square ambiguity decorrelation adjustment:
00032  *      a method for fast GPS ambiguity estimation, J.Geodesy, Vol.70, 65-82,
00033  *      1995
00034  * [2] X.-W.Chang, X.Yang, T.Zhou, MLAMBDA: A modified LAMBDA method for
00035  *      integer least-squares estimation, J.Geodesy, Vol.79, 552-565, 2005
00036  *
00037  * -----
00038  */
00039
00040 #ifndef GNSS_SDR_RTKLIB_LAMBDA_H
00041 #define GNSS_SDR_RTKLIB_LAMBDA_H
00042
00043
00044 #include "rtklib.h"
00045
00046 /* constants/macros -----*/
00047 const int LOOPMAX = 10000; /* maximum count of search loop */
00048 #define SGN_LAMBDA(x) ((x) <= 0.0 ? -1.0 : 1.0)
00049 #define ROUND_LAMBDA(x) (floor((x) + 0.5))
00050 #define SWAP_LAMBDA(x, y) \
00051     do \
00052     { \
00053         double tmp_; \
00054         tmp_ = x; \
00055         x = y; \
00056         y = tmp_; \
00057     } \
00058     while (0)
00059
00060 int LD(int n, const double *Q, double *L, double *D);
00061 void gauss(int n, double *L, double *Z, int i, int j);
00062 void perm(int n, double *L, double *D, int j, double del, double *Z);
00063 void reduction(int n, double *L, double *D, double *Z);
00064 int search(int n, int m, const double *L, const double *D,
00065           const double *zs, double *zn, double *s);
00066
00067 int lambda(int n, int m, const double *a, const double *Q, double *F, double *s);
00068
00069 int lambda_reduction(int n, const double *Q, double *Z);
00070
00071 int lambda_search(int n, int m, const double *a, const double *Q,
00072                 double *F, double *s);

```

```
00073
00074
00075 #endif
```

13.220 rtklib_pntpos.h File Reference

standard code-based positioning

```
#include "rtklib.h"
#include "rtklib_rtkcmn.h"
```

Functions

- double **varerr** (const [prcopt_t](#) *opt, double el, int sys)
- double **gettgd** (int sat, const [nav_t](#) *nav)
- double **getiscl1** (int sat, const [nav_t](#) *nav)
- double **getiscl2** (int sat, const [nav_t](#) *nav)
- double **getiscl5i** (int sat, const [nav_t](#) *nav)
- double **getiscl5q** (int sat, const [nav_t](#) *nav)
- double **prange** (const [obsd_t](#) *obs, const [nav_t](#) *nav, const double *azel, int iter, const [prcopt_t](#) *opt, double *var)
- int **ionocorr** ([gtime_t](#) time, const [nav_t](#) *nav, int sat, const double *pos, const double *azel, int ionoopt, double *ion, double *var)
- int **tropcorr** ([gtime_t](#) time, const [nav_t](#) *nav, const double *pos, const double *azel, int tropopt, double *trp, double *var)
- int **rescode** (int iter, const [obsd_t](#) *obs, int n, const double *rs, const double *dts, const double *vare, const int *svh, const [nav_t](#) *nav, const double *x, const [prcopt_t](#) *opt, double *v, double *H, double *var, double *azel, int *vsat, double *resp, int *ns)
- int **valsol** (const double *azel, const int *vsat, int n, const [prcopt_t](#) *opt, const double *v, int nv, int nx, char *msg)
- int **estpos** (const [obsd_t](#) *obs, int n, const double *rs, const double *dts, const double *vare, const int *svh, const [nav_t](#) *nav, const [prcopt_t](#) *opt, [sol_t](#) *sol, double *azel, int *vsat, double *resp, char *msg)
- int **raim_fde** (const [obsd_t](#) *obs, int n, const double *rs, const double *dts, const double *vare, const int *svh, const [nav_t](#) *nav, const [prcopt_t](#) *opt, [sol_t](#) *sol, double *azel, int *vsat, double *resp, char *msg)
- int **resdop** (const [obsd_t](#) *obs, int n, const double *rs, const double *dts, const [nav_t](#) *nav, const double *rr, const double *x, const double *azel, const int *vsat, double *v, double *H)
- void **estvel** (const [obsd_t](#) *obs, int n, const double *rs, const double *dts, const [nav_t](#) *nav, const [prcopt_t](#) *opt, [sol_t](#) *sol, const double *azel, const int *vsat)
- int **pntpos** (const [obsd_t](#) *obs, int n, const [nav_t](#) *nav, const [prcopt_t](#) *opt, [sol_t](#) *sol, double *azel, [ssat_t](#) *ssat, char *msg)

single-point positioning compute receiver position, velocity, clock bias by single-point positioning with pseudorange and doppler observables args : [obsd_t](#) *obs I observation data int n I number of observation data [nav_t](#) *nav I navigation data [prcopt_t](#) *opt I processing options [sol_t](#) *sol IO solution double *azel IO azimuth/elevation angle (rad) (NULL: no output) [ssat_t](#) *ssat IO satellite status (NULL: no output) char *msg O error message for error exit return : status(1:ok,0:error) notes : assuming sbas-gps, galileo-gps, qzss-gps, compass-gps time offset and receiver bias are negligible (only involving glonass-gps time offset and receiver bias)

Variables

- const int **NX** = 4 + 3
- const int **MAXITR** = 10
max number of iteration for point pos
- const double **ERR_ION** = 5.0
ionospheric delay std (m)
- const double **ERR_TROP** = 3.0
tropospheric delay std (m)

13.220.1 Detailed Description

standard code-based positioning

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

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Definition in file [rtklib_pntpos.h](#).

13.220.2 Function Documentation

13.220.2.1 pntpos()

```
int pntpos (
    const obsd_t * obs,
    int n,
    const nav_t * nav,
    const prcopt_t * opt,
    sol_t * sol,
    double * azel,
    ssat_t * ssat,
    char * msg)
```

single-point positioning compute receiver position, velocity, clock bias by single-point positioning with pseudorange and doppler observables args : [obsd_t](#) *obs I observation data [int](#) n I number of observation data [nav_t](#) *nav I navigation data [prcopt_t](#) *opt I processing options [sol_t](#) *sol IO solution double *azel IO azimuth/elevation angle (rad) (NULL: no output) [ssat_t](#) *ssat IO satellite status (NULL: no output) [char](#) *msg O error message for error exit return : status(1:ok,0:error) notes : assuming sbas-gps, galileo-gps, qzss-gps, compass-gps time offset and receiver bias are negligible (only involving glonass-gps time offset and receiver bias)

13.220.3 Variable Documentation

13.220.3.1 ERR_ION

```
const double ERR_ION = 5.0
```

ionospheric delay std (m)
Definition at line [42](#) of file [rtklib_pntpos.h](#).

13.220.3.2 ERR_TROP

```
const double ERR_TROP = 3.0
```

tropspheric delay std (m)
Definition at line [43](#) of file [rtklib_pntpos.h](#).

13.220.3.3 MAXITR

```
const int MAXITR = 10
```

max number of iteration for point pos
Definition at line [41](#) of file [rtklib_pntpos.h](#).

13.220.3.4 NX

```
const int NX = 4 + 3
```

13.220.4 of estimated parameters

Definition at line 40 of file [rtklib_pntpos.h](#).

13.221 rtklib_pntpos.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib_pntpos.h
00003  * \brief standard code-based positioning
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
00011  * The original source code at https://github.com/tomokitaku/RTKLIB is
00012  * released under the BSD 2-clause license with an additional exclusive clause
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00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
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00027  *
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00029  *
00030  * -----
00031  */
00032
00033 #ifndef GNSS_SDR_RTKLIB_PNTPOS_H
00034 #define GNSS_SDR_RTKLIB_PNTPOS_H
00035
00036 #include "rtklib.h"
00037 #include "rtklib_rtkcmn.h"
00038
00039 /* constants -----*/
00040 const int NX = 4 + 3;          //!< # of estimated parameters
00041 const int MAXITR = 10;        //!< max number of iteration for point pos
00042 const double ERR_ION = 5.0;    //!< ionospheric delay std (m)
00043 const double ERR_TROP = 3.0;  //!< tropospheric delay std (m)
00044
00045
00046 /* pseudorange measurement error variance -----*/
00047 double varerr(const prcopt_t *opt, double el, int sys);
00048
00049 /* get tgd parameter (m) -----*/
00050 double gettgd(int sat, const nav_t *nav);
00051
00052 /* get isc parameter (m) -----*/
00053 double getisc11(int sat, const nav_t *nav);
00054 double getisc12(int sat, const nav_t *nav);
00055 double getisc15i(int sat, const nav_t *nav);
00056 double getisc15q(int sat, const nav_t *nav);
00057
00058 /* pseudorange with code bias correction -----*/
00059 double prange(const obsd_t *obs, const nav_t *nav, const double *azel,
00060              int iter, const prcopt_t *opt, double *var);
00061
00062 /* ionospheric correction -----
00063  * compute ionospheric correction
00064  * args : gtime_t time      I   time
00065  *       nav_t *nav        I   navigation data
00066  *       int sat           I   satellite number
00067  *       double *pos       I   receiver position {lat,lon,h} (rad|m)
00068  *       double *azel      I   azimuth/elevation angle {az,el} (rad)
00069  *       int ionoopt       I   ionospheric correction option (IONOOPT_???)
00070  *       double *ion       O   ionospheric delay (L1) (m)
```

```

00071 *          double *var      0   ionospheric delay (L1) variance (m^2)
00072 * return : status(1:ok,0:error)
00073 *-----*/
00074 int ionocorr(gtime_t time, const nav_t *nav, int sat, const double *pos,
00075             const double *azel, int ionoopt, double *ion, double *var);
00076 /* tropospheric correction -----*/
00077 * compute tropospheric correction
00078 * args   : gtime_t time      I   time
00079 *          nav_t *nav         I   navigation data
00080 *          double *pos        I   receiver position {lat,lon,h} (rad|m)
00081 *          double *azel        I   azimuth/elevation angle {az,el} (rad)
00082 *          int tropopt         I   tropospheric correction option (TROPOPT_???)
00083 *          double *trp         0   tropospheric delay (m)
00084 *          double *var         0   tropospheric delay variance (m^2)
00085 * return : status(1:ok,0:error)
00086 *-----*/
00087 int tropcorr(gtime_t time, const nav_t *nav, const double *pos,
00088             const double *azel, int tropopt, double *trp, double *var);
00089
00090 /* pseudorange residuals -----*/
00091 int rescode(int iter, const obsd_t *obs, int n, const double *rs,
00092            const double *dts, const double *vare, const int *svh,
00093            const nav_t *nav, const double *x, const prcopt_t *opt,
00094            double *v, double *H, double *var, double *azel, int *vsat,
00095            double *resp, int *ns);
00096
00097 /* validate solution -----*/
00098 int valsol(const double *azel, const int *vsat, int n,
00099           const prcopt_t *opt, const double *v, int nv, int nx,
00100           char *msg);
00101
00102 /* estimate receiver position -----*/
00103 int estpos(const obsd_t *obs, int n, const double *rs, const double *dts,
00104           const double *vare, const int *svh, const nav_t *nav,
00105           const prcopt_t *opt, sol_t *sol, double *azel, int *vsat,
00106           double *resp, char *msg);
00107
00108 /* raim fde (failure detection and exclusion) -----*/
00109 int raim_fde(const obsd_t *obs, int n, const double *rs,
00110            const double *dts, const double *vare, const int *svh,
00111            const nav_t *nav, const prcopt_t *opt, sol_t *sol,
00112            double *azel, int *vsat, double *resp, char *msg);
00113
00114 /* doppler residuals -----*/
00115 int resdop(const obsd_t *obs, int n, const double *rs, const double *dts,
00116           const nav_t *nav, const double *rr, const double *x,
00117           const double *azel, const int *vsat, double *v, double *H);
00118
00119 /* estimate receiver velocity -----*/
00120 void estvel(const obsd_t *obs, int n, const double *rs, const double *dts,
00121           const nav_t *nav, const prcopt_t *opt, sol_t *sol,
00122           const double *azel, const int *vsat);
00123
00124 /*!
00125 * \brief single-point positioning
00126 * compute receiver position, velocity, clock bias by single-point positioning
00127 * with pseudorange and doppler observables
00128 * args   : obsd_t *obs      I   observation data
00129 *          int n             I   number of observation data
00130 *          nav_t *nav         I   navigation data
00131 *          prcopt_t *opt      I   processing options
00132 *          sol_t *sol         IO  solution
00133 *          double *azel        IO  azimuth/elevation angle (rad) (NULL: no output)
00134 *          ssat_t *ssat       IO  satellite status (NULL: no output)
00135 *          char *msg          0   error message for error exit
00136 * return : status(1:ok,0:error)
00137 * notes   : assuming sbas-gps, galileo-gps, qzss-gps, compass-gps time offset and
00138 *           receiver bias are negligible (only involving glonass-gps time offset
00139 *           and receiver bias)
00140 */
00141 int pntpos(const obsd_t *obs, int n, const nav_t *nav,
00142           const prcopt_t *opt, sol_t *sol, double *azel, ssat_t *ssat,
00143           char *msg);
00144
00145 #endif // GNSS_SDR_RTKLIB_PNTPOS_H

```

13.222 rtklib_ppp.h File Reference

Precise Point Positioning.

```
#include "rtklib.h"
```

Macros

- #define [MIN_PPP](#)(x, y)
- #define [ROUND_PPP](#)(x)
- #define [SWAP_I](#)(x, y)
- #define [SWAP_D](#)(x, y)

Functions

- double [lam_LC](#) (int i, int j, int k)
- double [L_LC](#) (int i, int j, int k, const double *L)
- double [P_LC](#) (int i, int j, int k, const double *P)
- double [var_LC](#) (int i, int j, int k, double sig)
- double [q_gamma](#) (double a, double x, double log_gamma_a)
- double [p_gamma](#) (double a, double x, double log_gamma_a)
- double [f_erfc](#) (double x)
- double [conffunc](#) (int N, double B, double sig)
- void [average_LC](#) ([rtk_t](#) *rtk, const [obsd_t](#) *obs, int n, const [nav_t](#) *nav, const double *azel)
- int [fix_amb_WL](#) ([rtk_t](#) *rtk, const [nav_t](#) *nav, int sat1, int sat2, int *NW)
- int [is_depend](#) (int sat1, int sat2, int *flgs, int *max_flg)
- int [sel_amb](#) (int *sat1, int *sat2, double *N, double *var, int n)
- int [fix_sol](#) ([rtk_t](#) *rtk, const int *sat1, const int *sat2, const double *NC, int n)
- int [fix_amb_ROUND](#) ([rtk_t](#) *rtk, int *sat1, int *sat2, const int *NW, int n)
- int [fix_amb_ILS](#) ([rtk_t](#) *rtk, int *sat1, int *sat2, int *NW, int n)
- int [pppamb](#) ([rtk_t](#) *rtk, const [obsd_t](#) *obs, int n, const [nav_t](#) *nav, const double *azel)
- void [pppoutsolstat](#) ([rtk_t](#) *rtk, int level, FILE *fp)
- void [testeclipse](#) (const [obsd_t](#) *obs, int n, const [nav_t](#) *nav, double *rs)
- double [varerr](#) (int sat, int sys, double el, int type, const [prcopt_t](#) *opt)
- void [initx](#) ([rtk_t](#) *rtk, double xi, double var, int i)
- int [ifmeas](#) (const [obsd_t](#) *obs, const [nav_t](#) *nav, const double *azel, const [prcopt_t](#) *opt, const double *dantr, const double *dants, double phw, double *meas, double *var)
- double [gettgd_ppp](#) (int sat, const [nav_t](#) *nav)
- int [corr_ion](#) ([gtime_t](#) time, const [nav_t](#) *nav, int sat, const double *pos, const double *azel, int ionoopt, double *ion, double *var, int *brk)
- int [corrmeas](#) (const [obsd_t](#) *obs, const [nav_t](#) *nav, const double *pos, const double *azel, const [prcopt_t](#) *opt, const double *dantr, const double *dants, double phw, double *meas, double *var, int *brk)
- double [gfmeas](#) (const [obsd_t](#) *obs, const [nav_t](#) *nav)
- void [udpos_ppp](#) ([rtk_t](#) *rtk)
- void [udclk_ppp](#) ([rtk_t](#) *rtk)
- void [udtrop_ppp](#) ([rtk_t](#) *rtk)
- void [detslp_ll](#) ([rtk_t](#) *rtk, const [obsd_t](#) *obs, int n)
- void [detslp_gf](#) ([rtk_t](#) *rtk, const [obsd_t](#) *obs, int n, const [nav_t](#) *nav)
- void [udbias_ppp](#) ([rtk_t](#) *rtk, const [obsd_t](#) *obs, int n, const [nav_t](#) *nav)
- void [udstate_ppp](#) ([rtk_t](#) *rtk, const [obsd_t](#) *obs, int n, const [nav_t](#) *nav)
- void [satantpcv](#) (const double *rs, const double *rr, const [pcv_t](#) *pcv, double *dant)
- double [prectrop](#) ([gtime_t](#) time, const double *pos, const double *azel, const [prcopt_t](#) *opt, const double *x, double *dtdx, double *var)
- int [res_ppp](#) (int iter, const [obsd_t](#) *obs, int n, const double *rs, const double *dts, const double *vare, const int *svh, const [nav_t](#) *nav, const double *x, [rtk_t](#) *rtk, double *v, double *H, double *R, double *azel)
- int [pppnx](#) (const [prcopt_t](#) *opt)
- void [pppos](#) ([rtk_t](#) *rtk, const [obsd_t](#) *obs, int n, const [nav_t](#) *nav)

Variables

- const double `MIN_ARC_GAP` = 300.0
- const double `CONST_AMB` = 0.001
- const double `THRES_RES` = 0.3
- const double `LOG_PI` = 1.14472988584940017
- const double `SQRT2` = 1.41421356237309510
- const double `VAR_POS_PPP` = `std::pow(100.0, 2.0)`
- const double `VAR_CLK` = `std::pow(100.0, 2.0)`
- const double `VAR_ZTD` = `std::pow(0.3, 2.0)`
- const double `VAR_GRA_PPP` = `std::pow(0.001, 2.0)`
- const double `VAR_BIAS` = `std::pow(100.0, 2.0)`
- const double `VAR_IONO_OFF` = `std::pow(10.0, 2.0)`

13.222.1 Detailed Description

Precise Point Positioning.

Authors

- 2007-2008, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

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Definition in file [rtklib_ppp.h](#).

13.222.2 Macro Definition Documentation

13.222.2.1 MIN_PPP

```
#define MIN_PPP(  
    x,  
    y)
```

Value:

```
((x) <= (y) ? (x) : (y))
```

Definition at line 40 of file [rtklib_ppp.h](#).

13.222.2.2 ROUND_PPP

```
#define ROUND_PPP(  
    x)
```

Value:

```
static_cast<int>(floor((x) + 0.5))
```

Definition at line 41 of file [rtklib_ppp.h](#).

13.222.2.3 SWAP_D

```
#define SWAP_D(  
    x,  
    y)
```

Value:

```

do
{
    double _z = x;
    x = y;
    y = _z;
}
while (0)

```

Definition at line 51 of file [rtklib_ppp.h](#).

13.222.2.4 SWAP_I

```

#define SWAP_I(
    x,
    y)

```

Value:

```

do
{
    int _z = x;
    x = y;
    y = _z;
}
while (0)

```

Definition at line 43 of file [rtklib_ppp.h](#).

13.222.3 Variable Documentation

13.222.3.1 CONST_AMB

```
const double CONST_AMB = 0.001
```

Definition at line 61 of file [rtklib_ppp.h](#).

13.222.3.2 LOG_PI

```
const double LOG_PI = 1.14472988584940017
```

Definition at line 63 of file [rtklib_ppp.h](#).

13.222.3.3 MIN_ARC_GAP

```
const double MIN_ARC_GAP = 300.0
```

Definition at line 60 of file [rtklib_ppp.h](#).

13.222.3.4 SQRT2

```
const double SQRT2 = 1.41421356237309510
```

Definition at line 64 of file [rtklib_ppp.h](#).

13.222.3.5 THRES_RES

```
const double THRES_RES = 0.3
```

Definition at line 62 of file [rtklib_ppp.h](#).

13.222.3.6 VAR_BIAS

```
const double VAR_BIAS = std::pow(100.0, 2.0)
```

Definition at line 70 of file [rtklib_ppp.h](#).

13.222.3.7 VAR_CLK

```
const double VAR_CLK = std::pow(100.0, 2.0)
```

Definition at line 67 of file [rtklib_ppp.h](#).

13.222.3.8 VAR_GRA_PPP

```
const double VAR_GRA_PPP = std::pow(0.001, 2.0)
```

Definition at line 69 of file [rtklib_ppp.h](#).

13.222.3.9 VAR_IONO_OFF

```
const double VAR_IONO_OFF = std::pow(10.0, 2.0)
```

Definition at line 72 of file [rtklib_ppp.h](#).

13.222.3.10 VAR_POS_PPP

```
const double VAR_POS_PPP = std::pow(100.0, 2.0)
```

Definition at line 66 of file [rtklib_ppp.h](#).

13.222.3.11 VAR_ZTD

```
const double VAR_ZTD = std::pow(0.3, 2.0)
```

Definition at line 68 of file [rtklib_ppp.h](#).

13.223 rtklib_ppp.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib_ppp.h
00003  * \brief Precise Point Positioning
00004  * \authors <ul>
00005  *         <li> 2007-2008, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
00011  * The original source code at https://github.com/tomojitakasu/RTKLIB is
00012  * released under the BSD 2-clause license with an additional exclusive clause
00013  * that does not apply here. This additional clause is reproduced below:
00014  *
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00017  * original ones of these software. "
00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
00020  * or included in GNSS-SDR.
00021  *
00022  * -----
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00025  * Copyright (C) 2017, Carles Fernandez
00026  * All rights reserved.
00027  *
00028  * SPDX-License-Identifier: BSD-2-Clause
00029  *
00030  * -----
00031  */
00032
00033
00034 #ifndef GNSS_SDR_RTKLIB_PPP_H
00035 #define GNSS_SDR_RTKLIB_PPP_H
00036
00037 #include "rtklib.h"
00038
00039
00040 #define MIN_PPP(x, y) ((x) <= (y) ? (x) : (y))
00041 #define ROUND_PPP(x) static_cast<int>(floor((x) + 0.5))
00042
00043 #define SWAP_I(x, y) \
00044     do \
00045     { \
00046         int _z = x; \
00047         x = y; \
00048         y = _z; \
00049     } \
00050     while (0)
00051 #define SWAP_D(x, y) \
00052     do \
00053     { \
```

```

00054         double _z = x; \
00055         x = y;           \
00056         y = _z;         \
00057     }                   \
00058     while (0)
00059
00060     const double MIN_ARC_GAP = 300.0; /* min arc gap (s) */
00061     const double CONST_AMB = 0.001; /* constraint to fixed ambiguity */
00062     const double THRES_RES = 0.3; /* threshold of residuals test (m) */
00063     const double LOG_PI = 1.14472988584940017; /* log(pi) */
00064     const double Sqrt2 = 1.41421356237309510; /* sqrt(2) */
00065
00066     const double VAR_POS_PPP = std::pow(100.0, 2.0); /* init variance receiver position (m^2) */
00067     const double VAR_CLK = std::pow(100.0, 2.0); /* init variance receiver clock (m^2) */
00068     const double VAR_ZTD = std::pow(0.3, 2.0); /* init variance ztd (m^2) */
00069     const double VAR_GRA_PPP = std::pow(0.001, 2.0); /* init variance gradient (m^2) */
00070     const double VAR_BIAS = std::pow(100.0, 2.0); /* init variance phase-bias (m^2) */
00071
00072     const double VAR_IONO_OFF = std::pow(10.0, 2.0); /* variance of iono-model-off */
00073
00074
00075     /* functions originally included in RTKLIB/src/ppp_ar.c v2.4.2 */
00076     double lam_LC(int i, int j, int k);
00077
00078     double L_LC(int i, int j, int k, const double *L);
00079
00080     double P_LC(int i, int j, int k, const double *P);
00081
00082     double var_LC(int i, int j, int k, double sig);
00083
00084     double q_gamma(double a, double x, double log_gamma_a);
00085
00086     double p_gamma(double a, double x, double log_gamma_a);
00087
00088     double f_erfc(double x);
00089
00090     double conffunc(int N, double B, double sig);
00091
00092     void average_LC(rtk_t *rtk, const obsd_t *obs, int n, const nav_t *nav, const double *azel);
00093
00094     int fix_amb_WL(rtk_t *rtk, const nav_t *nav, int sat1, int sat2, int *NW);
00095
00096     int is_depend(int sat1, int sat2, int *flgs, int *max_flg);
00097
00098     int sel_amb(int *sat1, int *sat2, double *N, double *var, int n);
00099
00100     int fix_sol(rtk_t *rtk, const int *sat1, const int *sat2, const double *NC, int n);
00101
00102     int fix_amb_ROUND(rtk_t *rtk, int *sat1, int *sat2, const int *NW, int n);
00103
00104     int fix_amb_ILS(rtk_t *rtk, int *sat1, int *sat2, int *NW, int n);
00105
00106     int pppamb(rtk_t *rtk, const obsd_t *obs, int n, const nav_t *nav, const double *azel);
00107
00108
00109     /* functions originally included in RTKLIB/src/ppp.c v2.4.2 */
00110     void pppoutsolstat(rtk_t *rtk, int level, FILE *fp);
00111
00112     void testeclipse(const obsd_t *obs, int n, const nav_t *nav, double *rs);
00113
00114     double varerr(int sat, int sys, double el, int type, const prcopt_t *opt);
00115
00116     void initx(rtk_t *rtk, double xi, double var, int i);
00117
00118     int ifmeas(const obsd_t *obs, const nav_t *nav, const double *azel,
00119               const prcopt_t *opt, const double *dantr, const double *dants,
00120               double phw, double *meas, double *var);
00121
00122     double gettgd_ppp(int sat, const nav_t *nav);
00123
00124     int corr_ion(gtime_t time, const nav_t *nav, int sat, const double *pos,
00125                 const double *azel, int ionoopt, double *ion, double *var,
00126                 int *brk);
00127
00128     int corrmeas(const obsd_t *obs, const nav_t *nav, const double *pos,
00129                 const double *azel, const prcopt_t *opt,
00130                 const double *dantr, const double *dants, double phw,
00131                 double *meas, double *var, int *brk);
00132
00133     double gfmeas(const obsd_t *obs, const nav_t *nav);
00134
00135     void udpos_ppp(rtk_t *rtk);
00136
00137     void udclk_ppp(rtk_t *rtk);
00138
00139     void udtrop_ppp(rtk_t *rtk);
00140

```

```

00141 void detslp_ll(rtk_t *rtk, const obsd_t *obs, int n);
00142
00143 void detslp_gf(rtk_t *rtk, const obsd_t *obs, int n, const nav_t *nav);
00144
00145 void udbias_ppp(rtk_t *rtk, const obsd_t *obs, int n, const nav_t *nav);
00146
00147 void udstaate_ppp(rtk_t *rtk, const obsd_t *obs, int n, const nav_t *nav);
00148
00149 void satantpcv(const double *rs, const double *rr, const pcv_t *pcv, double *dant);
00150
00151 double prectrop(gtime_t time, const double *pos, const double *azel,
00152               const prcopt_t *opt, const double *x, double *dtdx,
00153               double *var);
00154
00155 int res_ppp(int iter, const obsd_t *obs, int n, const double *rs,
00156            const double *dts, const double *vare, const int *svh,
00157            const nav_t *nav, const double *x, rtk_t *rtk, double *v,
00158            double *H, double *R, double *azel);
00159
00160 int pppnx(const prcopt_t *opt);
00161
00162 void pppos(rtk_t *rtk, const obsd_t *obs, int n, const nav_t *nav);
00163
00164 #endif

```

13.224 rtklib_preceph.h File Reference

precise ephemeris and clock functions

```
#include "rtklib.h"
```

Functions

- int **code2sys** (char code)
- int **readsp3h** (FILE *fp, gtime_t *time, char *type, int *sats, double *bfact, char *tsys)
- int **addpeph** (nav_t *nav, peph_t *peph)
- void **readsp3b** (FILE *fp, char type, int *sats, int ns, const double *bfact, char *tsys, int index, int opt, nav_t *nav)
- int **cmppeph** (const void *p1, const void *p2)
- void **combpeph** (nav_t *nav, int opt)
- void **readsp3** (const char *file, nav_t *nav, int opt)
- int **readsap** (const char *file, gtime_t time, nav_t *nav)
- int **readdcbf** (const char *file, nav_t *nav, const sta_t *sta)
- int **readdcb** (const char *file, nav_t *nav, const sta_t *sta)
- double **interppl** (const double *x, double *y, int n)
- int **pephpos** (gtime_t time, int sat, const nav_t *nav, double *rs, double *dts, double *vare, double *varc)
- int **pephclk** (gtime_t time, int sat, const nav_t *nav, double *dts, double *varc)
- void **satantoff** (gtime_t time, const double *rs, int sat, const nav_t *nav, double *dant)
- int **peph2pos** (gtime_t time, int sat, const nav_t *nav, int opt, double *rs, double *dts, double *var)

Variables

- const int **NMAX** = 10
- const double **MAXDTE** = 900.0
- const double **EXTERR_CLK** = 1e-3
- const double **EXTERR_EPH** = 5e-7

13.224.1 Detailed Description

precise ephemeris and clock functions

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

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References : [1] S.Hilla, The Extended Standard Product 3 Orbit Format (SP3-c), 12 February, 2007 [2] J.Ray, W. Gurtner, RINEX Extensions to Handle Clock Information, 27 August, 1998 [3] D.D.McCarthy, IERS Technical Note 21, IERS Conventions 1996, July 1996 [4] D.A.Vallado, Fundamentals of Astrodynamics and Applications 2nd ed, Space Technology Library, 2004

Definition in file [rtklib_preceph.h](#).

13.224.2 Variable Documentation

13.224.2.1 EXTERR_CLK

```
const double EXTERR_CLK = 1e-3
```

Definition at line 51 of file [rtklib_preceph.h](#).

13.224.2.2 EXTERR_EPH

```
const double EXTERR_EPH = 5e-7
```

Definition at line 52 of file [rtklib_preceph.h](#).

13.224.2.3 MAXDTE

```
const double MAXDTE = 900.0
```

Definition at line 50 of file [rtklib_preceph.h](#).

13.224.2.4 NMAX

```
const int NMAX = 10
```

Definition at line 49 of file [rtklib_preceph.h](#).

13.225 rtklib_preceph.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib_preceph.h
00003  * \brief precise ephemeris and clock functions
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
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00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
00020  * or included in GNSS-SDR.
```

```

00021 *
00022 * -----
00023 * Copyright (C) 2007-2013, T. Takasu
00024 * Copyright (C) 2017, Javier Arribas
00025 * Copyright (C) 2017, Carles Fernandez
00026 * All rights reserved.
00027 *
00028 * SPDX-License-Identifier: BSD-2-Clause
00029 *
00030 *
00031 * References :
00032 * [1] S.Hilla, The Extended Standard Product 3 Orbit Format (SP3-c),
00033 * 12 February, 2007
00034 * [2] J.Ray, W.Gurtner, RINEX Extensions to Handle Clock Information,
00035 * 27 August, 1998
00036 * [3] D.D.McCarthy, IERS Technical Note 21, IERS Conventions 1996, July 1996
00037 * [4] D.A.Vallado, Fundamentals of Astrodynamics and Applications 2nd ed,
00038 * Space Technology Library, 2004
00039 *
00040 * -----
00041 */
00042
00043 #ifndef GNSS_SDR_RTKLIB_PRECEPH_H
00044 #define GNSS_SDR_RTKLIB_PRECEPH_H
00045
00046 #include "rtklib.h"
00047
00048
00049 const int NMAX = 10; /* order of polynomial interpolation */
00050 const double MAXDTE = 900.0; /* max time difference to ephem time (s) */
00051 const double EXTERR_CLK = 1e-3; /* extrapolation error for clock (m/s) */
00052 const double EXTERR_EPH = 5e-7; /* extrapolation error for ephem (m/s^2) */
00053
00054 int code2sys(char code);
00055
00056 int readsp3h(FILE *fp, gtime_t *time, char *type, int *sats,
00057 double *bfact, char *tsys);
00058
00059 int addpeph(nav_t *nav, peph_t *peph);
00060
00061 void readsp3b(FILE *fp, char type, int *sats, int ns, const double *bfact,
00062 char *tsys, int index, int opt, nav_t *nav);
00063
00064 int cmppeph(const void *p1, const void *p2);
00065
00066 void combpeph(nav_t *nav, int opt);
00067
00068 void readsp3(const char *file, nav_t *nav, int opt);
00069
00070 int readsap(const char *file, gtime_t time, nav_t *nav);
00071
00072 int readdcbf(const char *file, nav_t *nav, const sta_t *sta);
00073
00074 int readdcb(const char *file, nav_t *nav, const sta_t *sta);
00075
00076 double interppol(const double *x, double *y, int n);
00077
00078 int pephpos(gtime_t time, int sat, const nav_t *nav, double *rs,
00079 double *dts, double *vare, double *varc);
00080
00081 int pephclk(gtime_t time, int sat, const nav_t *nav, double *dts,
00082 double *varc);
00083
00084 void satantoff(gtime_t time, const double *rs, int sat, const nav_t *nav,
00085 double *dant);
00086
00087 int peph2pos(gtime_t time, int sat, const nav_t *nav, int opt,
00088 double *rs, double *dts, double *var);
00089
00090 #endif // GNSS_SDR_RTKLIB_PRECEPH_H

```

13.226 rtklib_rtcn.h File Reference

RTCM functions headers.

```

#include "rtklib.h"
#include "rtklib_rtcn2.h"
#include "rtklib_rtcn3.h"

```

Macros

- `#define RTCM2PREAMB 0x66 /* rtcn ver.2 frame preamble */`
- `#define RTCM3PREAMB 0xD3 /* rtcn ver.3 frame preamble */`

Functions

- `int init_rtcn (rtcn_t *rtcn)`
- `void free_rtcn (rtcn_t *rtcn)`
- `int input_rtcn2 (rtcn_t *rtcn, unsigned char data)`
- `int input_rtcn3 (rtcn_t *rtcn, unsigned char data)`
- `int input_rtcn2f (rtcn_t *rtcn, FILE *fp)`
- `int input_rtcn3f (rtcn_t *rtcn, FILE *fp)`
- `int gen_rtcn2 (rtcn_t *rtcn, int type, int sync)`

13.226.1 Detailed Description

RTCM functions headers.

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

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Definition in file [rtklib_rtcn.h](#).

13.226.2 Macro Definition Documentation

13.226.2.1 RTCM2PREAMB

`#define RTCM2PREAMB 0x66 /* rtcn ver.2 frame preamble */`

Definition at line 42 of file [rtklib_rtcn.h](#).

13.226.2.2 RTCM3PREAMB

`#define RTCM3PREAMB 0xD3 /* rtcn ver.3 frame preamble */`

Definition at line 43 of file [rtklib_rtcn.h](#).

13.227 rtklib_rtcn.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib_rtcn.h
00003  * \brief RTCM functions headers
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
00011  * The original source code at https://github.com/tomojitakasu/RTKLIB is
00012  * released under the BSD 2-clause license with an additional exclusive clause
```

```

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00020  * or included in GNSS-SDR.
00021  *
00022  * -----
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00025  * Copyright (C) 2017, Carles Fernandez
00026  * All rights reserved.
00027  *
00028  * SPDX-License-Identifier: BSD-2-Clause
00029  *
00030  *
00031  * -----
00032  */
00033
00034
00035 #ifndef GNSS_SDR_RTKLIB_RTCM_H
00036 #define GNSS_SDR_RTKLIB_RTCM_H
00037
00038 #include "rtklib.h"
00039 #include "rtklib_rtc2.h"
00040 #include "rtklib_rtc3.h"
00041
00042 #define RTCM2PREAMB 0x66 /* rtcm ver.2 frame preamble */
00043 #define RTCM3PREAMB 0xD3 /* rtcm ver.3 frame preamble */
00044
00045
00046 int init_rtc(rtc_t *rtc);
00047 void free_rtc(rtc_t *rtc);
00048 int input_rtc2(rtc_t *rtc, unsigned char data);
00049 int input_rtc3(rtc_t *rtc, unsigned char data);
00050 int input_rtc2f(rtc_t *rtc, FILE *fp);
00051 int input_rtc3f(rtc_t *rtc, FILE *fp);
00052 int gen_rtc2(rtc_t *rtc, int type, int sync);
00053 // int gen_rtc3(rtc_t *rtc, int type, int sync);
00054
00055
00056 #endif // GNSS_SDR_RTKLIB_RTCM_H

```

13.228 rtklib_rtc2.h File Reference

RTCM v2 functions headers.

```
#include "rtklib.h"
```

Functions

- void **adjhour** ([rtc_t](#) *rtc, double zcnt)
- int **obsindex** ([obs_t](#) *obs, [gtime_t](#) time, int sat)
- int **decode_type1** ([rtc_t](#) *rtc)
- int **decode_type3** ([rtc_t](#) *rtc)
- int **decode_type14** ([rtc_t](#) *rtc, bool pre_2009_file=false)
- int **decode_type16** ([rtc_t](#) *rtc)
- int **decode_type17** ([rtc_t](#) *rtc, bool pre_2009_file=false)
- int **decode_type18** ([rtc_t](#) *rtc)
- int **decode_type19** ([rtc_t](#) *rtc)
- int **decode_type22** ([rtc_t](#) *rtc)
- int **decode_type23** ([rtc_t](#) *rtc)
- int **decode_type24** ([rtc_t](#) *rtc)
- int **decode_type31** ([rtc_t](#) *rtc)
- int **decode_type32** ([rtc_t](#) *rtc)
- int **decode_type34** ([rtc_t](#) *rtc)
- int **decode_type36** ([rtc_t](#) *rtc)
- int **decode_type37** ([rtc_t](#) *rtc)
- int **decode_type59** ([rtc_t](#) *rtc)
- int **decode_rtc2** ([rtc_t](#) *rtc)

13.228.1 Detailed Description

RTCM v2 functions headers.

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

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Definition in file [rtklib_rtc2.h](#).

13.229 rtklib_rtc2.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib_rtc2.h
00003  * \brief RTCM v2 functions headers
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
00011  * The original source code at https://github.com/tomojitakasu/RTKLIB is
00012  * released under the BSD 2-clause license with an additional exclusive clause
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00017  * original ones of these software. "
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00019  * Neither the executive binaries nor the shared libraries are required by, used
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00022  * -----
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00025  * Copyright (C) 2017, Carles Fernandez
00026  * All rights reserved.
00027  *
00028  * SPDX-License-Identifier: BSD-2-Clause
00029  *
00030  * -----
00031  */
00032 */
00033
00034 #ifndef GNSS_SDR_RTKLIB_RTC2_H
00035 #define GNSS_SDR_RTKLIB_RTC2_H
00036
00037 #include "rtklib.h"
00038
00039
00040 void adjhour(rtc2_t *rtc2, double zcnt);
00041 int obsindex(obs_t *obs, gtime_t time, int sat);
00042 int decode_type1(rtc2_t *rtc2);
00043 int decode_type3(rtc2_t *rtc2);
00044 int decode_type14(rtc2_t *rtc2, bool pre_2009_file = false);
00045 int decode_type16(rtc2_t *rtc2);
00046 int decode_type17(rtc2_t *rtc2, bool pre_2009_file = false);
00047 int decode_type18(rtc2_t *rtc2);
00048 int decode_type19(rtc2_t *rtc2);
00049 int decode_type22(rtc2_t *rtc2);
00050 int decode_type23(rtc2_t *rtc2);
00051 int decode_type24(rtc2_t *rtc2);
00052 int decode_type31(rtc2_t *rtc2);
00053 int decode_type32(rtc2_t *rtc2);
```

```

00054 int decode_type34(rtcm_t *rtcm);
00055 int decode_type36(rtcm_t *rtcm);
00056 int decode_type37(rtcm_t *rtcm);
00057 int decode_type59(rtcm_t *rtcm);
00058 int decode_rtcm2(rtcm_t *rtcm);
00059
00060 #endif

```

13.230 rtklib_rtcm3.h File Reference

RTCM v3 functions headers.

```
#include "rtklib.h"
```

Functions

- double **getbitg** (const unsigned char *buff, int pos, int len)
- void **adjweek** (*rtcm_t* *rtcm, double tow)
- int **adjbdtweek** (int week)
- void **adjday_glot** (*rtcm_t* *rtcm, double tod)
- double **adjcp** (*rtcm_t* *rtcm, int sat, int freq, double cp)
- int **lossoflock** (*rtcm_t* *rtcm, int sat, int freq, int lock)
- unsigned char **snratio** (double snr)
- int **obsindex3** (*obs_t* *obs, *gtime_t* time, int sat)
- int **test_staid** (*rtcm_t* *rtcm, int staid)
- int **decode_head1001** (*rtcm_t* *rtcm, int *sync)
- int **decode_type1001** (*rtcm_t* *rtcm)
- int **decode_type1002** (*rtcm_t* *rtcm)
- int **decode_type1003** (*rtcm_t* *rtcm)
- int **decode_type1004** (*rtcm_t* *rtcm)
- double **getbits_38** (const unsigned char *buff, int pos)
- int **decode_type1005** (*rtcm_t* *rtcm)
- int **decode_type1006** (*rtcm_t* *rtcm)
- int **decode_type1007** (*rtcm_t* *rtcm)
- int **decode_type1008** (*rtcm_t* *rtcm)
- int **decode_head1009** (*rtcm_t* *rtcm, int *sync)
- int **decode_type1009** (*rtcm_t* *rtcm)
- int **decode_type1010** (*rtcm_t* *rtcm)
- int **decode_type1011** (*rtcm_t* *rtcm)
- int **decode_type1012** (*rtcm_t* *rtcm)
- int **decode_type1013** (*rtcm_t* *rtcm)
- int **decode_type1019** (*rtcm_t* *rtcm, bool pre_2009_file=false)
- int **decode_type1020** (*rtcm_t* *rtcm)
- int **decode_type1021** (*rtcm_t* *rtcm)
- int **decode_type1022** (*rtcm_t* *rtcm)
- int **decode_type1023** (*rtcm_t* *rtcm)
- int **decode_type1024** (*rtcm_t* *rtcm)
- int **decode_type1025** (*rtcm_t* *rtcm)
- int **decode_type1026** (*rtcm_t* *rtcm)
- int **decode_type1027** (*rtcm_t* *rtcm)
- int **decode_type1029** (*rtcm_t* *rtcm)
- int **decode_type1030** (*rtcm_t* *rtcm)
- int **decode_type1031** (*rtcm_t* *rtcm)
- int **decode_type1032** (*rtcm_t* *rtcm)
- int **decode_type1033** (*rtcm_t* *rtcm)
- int **decode_type1034** (*rtcm_t* *rtcm)
- int **decode_type1035** (*rtcm_t* *rtcm)

- int **decode_type1037** ([rtcm_t](#) *rtcm)
- int **decode_type1038** ([rtcm_t](#) *rtcm)
- int **decode_type1039** ([rtcm_t](#) *rtcm)
- int **decode_type1044** ([rtcm_t](#) *rtcm, bool pre_2009_file=false)
- int **decode_type1045** ([rtcm_t](#) *rtcm)
- int **decode_type1046** ([rtcm_t](#) *rtcm)
- int **decode_type1047** ([rtcm_t](#) *rtcm)
- int **decode_type1063** ([rtcm_t](#) *rtcm)
- int **decode_ssr1_head** ([rtcm_t](#) *rtcm, int sys, int *sync, int *iod, double *udint, int *refd, int *hsize)
- int **decode_ssr2_head** ([rtcm_t](#) *rtcm, int sys, int *sync, int *iod, double *udint, int *hsize)
- int **decode_ssr7_head** ([rtcm_t](#) *rtcm, int sys, int *sync, int *iod, double *udint, int *dispe, int *mw, int *hsize)
- int **decode_ssr1** ([rtcm_t](#) *rtcm, int sys)
- int **decode_ssr2** ([rtcm_t](#) *rtcm, int sys)
- int **decode_ssr3** ([rtcm_t](#) *rtcm, int sys)
- int **decode_ssr4** ([rtcm_t](#) *rtcm, int sys)
- int **decode_ssr5** ([rtcm_t](#) *rtcm, int sys)
- int **decode_ssr6** ([rtcm_t](#) *rtcm, int sys)
- int **decode_ssr7** ([rtcm_t](#) *rtcm, int sys)
- void **sigindex** (int sys, const unsigned char *code, const int *freq, int n, const char *opt, int *ind)
- void **save_msm_obs** ([rtcm_t](#) *rtcm, int sys, [msm_h_t](#) *h, const double *r, const double *pr, const double *cp, const double *rr, const double *rrf, const double *cnr, const int *lock, const int *ex, const int *half)
- int **decode_msm_head** ([rtcm_t](#) *rtcm, int sys, int *sync, int *iod, [msm_h_t](#) *h, int *hsize)
- int **decode_msm0** ([rtcm_t](#) *rtcm, int sys)
- int **decode_msm4** ([rtcm_t](#) *rtcm, int sys)
- int **decode_msm5** ([rtcm_t](#) *rtcm, int sys)
- int **decode_msm6** ([rtcm_t](#) *rtcm, int sys)
- int **decode_msm7** ([rtcm_t](#) *rtcm, int sys)
- int **decode_type1230** ([rtcm_t](#) *rtcm)
- int **decode_rtc3** ([rtcm_t](#) *rtcm)

Variables

- const double [PRUNIT_GPS](#) = 299792.458
- const double [PRUNIT_GLO](#) = 599584.916
- const double [RANGE_MS](#) = [SPEED_OF_LIGHT_M_S](#) * 0.001
- const double [SSRUDINT](#) [16]
- const int [CODES_GPS](#) []
- const int [CODES_GLO](#) []
- const int [CODES_GAL](#) []
- const int [CODES_QZS](#) []
- const int [CODES_BDS](#) []
- const int [CODES_SBS](#) []

13.230.1 Detailed Description

RTCM v3 functions headers.

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

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Definition in file [rtklib_rtc3.h](#).

13.230.2 Variable Documentation

13.230.2.1 CODES_BDS

```
const int CODES_BDS[]
```

Initial value:

```
= {
    CODE_L1I, CODE_L1Q, CODE_L1X, CODE_L7I, CODE_L7Q, CODE_L7X, CODE_L6I, CODE_L6Q,
    CODE_L6X}
```

Definition at line 73 of file [rtklib_rtc3.h](#).

13.230.2.2 CODES_GAL

```
const int CODES_GAL[]
```

Initial value:

```
= {
    CODE_L1A, CODE_L1B, CODE_L1C, CODE_L1X, CODE_L1Z, CODE_L5I, CODE_L5Q, CODE_L5X,
    CODE_L7I, CODE_L7Q, CODE_L7X, CODE_L8I, CODE_L8Q, CODE_L8X, CODE_L6A, CODE_L6B,
    CODE_L6C, CODE_L6X, CODE_L6Z}
```

Definition at line 62 of file [rtklib_rtc3.h](#).

13.230.2.3 CODES_GLO

```
const int CODES_GLO[]
```

Initial value:

```
= {
    CODE_L1C, CODE_L1P, CODE_L2C, CODE_L2P}
```

Definition at line 58 of file [rtklib_rtc3.h](#).

13.230.2.4 CODES_GPS

```
const int CODES_GPS[]
```

Initial value:

```
= {
    CODE_L1C, CODE_L1P, CODE_L1W, CODE_L1Y, CODE_L1M, CODE_L2C, CODE_L2D, CODE_L2S,
    CODE_L2L, CODE_L2X, CODE_L2P, CODE_L2W, CODE_L2Y, CODE_L2M, CODE_L5I, CODE_L5Q,
    CODE_L5X}
```

Definition at line 52 of file [rtklib_rtc3.h](#).

13.230.2.5 CODES_QZS

```
const int CODES_QZS[]
```

Initial value:

```
= {
    CODE_L1C, CODE_L1S, CODE_L1L, CODE_L2S, CODE_L2L, CODE_L2X, CODE_L5I, CODE_L5Q,
    CODE_L5X, CODE_L6S, CODE_L6L, CODE_L6X, CODE_L1X}
```

Definition at line 68 of file [rtklib_rtc3.h](#).

13.230.2.6 CODES_SBS

```
const int CODES_SBS[]
```

Initial value:

```
= {
```



```
CODE_L1C, CODE_L5I, CODE_L5Q, CODE_L5X}
```

Definition at line 78 of file rtklib_rtc3.h.

13.230.2.7 PRUNIT_GLO

```
const double PRUNIT_GLO = 599584.916
```

Definition at line 42 of file rtklib_rtc3.h.

13.230.2.8 PRUNIT_GPS

```
const double PRUNIT_GPS = 299792.458
```

Definition at line 41 of file rtklib_rtc3.h.

13.230.2.9 RANGE_MS

```
const double RANGE_MS = SPEED_OF_LIGHT_M_S * 0.001
```

Definition at line 43 of file rtklib_rtc3.h.

13.230.2.10 SSRUDINT

```
const double SSRUDINT[16]
```

Initial value:

```
= {
    1, 2, 5, 10, 15, 30, 60, 120, 240, 300, 600, 900, 1800, 3600, 7200, 10800}
```

Definition at line 47 of file rtklib_rtc3.h.

13.231 rtklib_rtc3.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib_rtc3.h
00003  * \brief RTCM v3 functions headers
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
00011  * The original source code at https://github.com/tomajitakasu/RTKLIB is
00012  * released under the BSD 2-clause license with an additional exclusive clause
00013  * that does not apply here. This additional clause is reproduced below:
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00015  * " The software package includes some companion executive binaries or shared
00016  * libraries necessary to execute APs on Windows. These licenses succeed to the
00017  * original ones of these software. "
00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
00020  * or included in GNSS-SDR.
00021  *
00022  * -----
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00024  * Copyright (C) 2017, Javier Arribas
00025  * Copyright (C) 2017, Carles Fernandez
00026  * All rights reserved.
00027  *
00028  * SPDX-License-Identifier: BSD-2-Clause
00029  *
00030  *
00031  * -----
00032  */
00033
00034 #ifndef GNSS_SDR_RTKLIB_RTCM3_H
00035 #define GNSS_SDR_RTKLIB_RTCM3_H
00036
00037 #include "rtklib.h"
00038
00039 /* constants -----*/
00040
00041 const double PRUNIT_GPS = 299792.458; /* rtkcm ver.3 unit of gps pseudorange (m) */
00042 const double PRUNIT_GLO = 599584.916; /* rtkcm ver.3 unit of glonass pseudorange (m) */
00043 const double RANGE_MS = SPEED_OF_LIGHT_M_S * 0.001; /* range in 1 ms */
00044
```

```
00045
00046 /* ssr update intervals -----*/
00047 const double SSRUDINT[16] = {
00048     1, 2, 5, 10, 15, 30, 60, 120, 240, 300, 600, 900, 1800, 3600, 7200, 10800};
00049
00050
00051 /* ssr 3 and 7 signal and tracking mode ids -----*/
00052 const int CODES_GPS[] = {
00053     CODE_L1C, CODE_L1P, CODE_L1W, CODE_L1Y, CODE_L1M, CODE_L2C, CODE_L2D, CODE_L2S,
00054     CODE_L2L, CODE_L2X, CODE_L2P, CODE_L2W, CODE_L2Y, CODE_L2M, CODE_L5I, CODE_L5Q,
00055     CODE_L5X};
00056
00057
00058 const int CODES_GLO[] = {
00059     CODE_L1C, CODE_L1P, CODE_L2C, CODE_L2P};
00060
00061
00062 const int CODES_GAL[] = {
00063     CODE_L1A, CODE_L1B, CODE_L1C, CODE_L1X, CODE_L1Z, CODE_L5I, CODE_L5Q, CODE_L5X,
00064     CODE_L7I, CODE_L7Q, CODE_L7X, CODE_L8I, CODE_L8Q, CODE_L8X, CODE_L6A, CODE_L6B,
00065     CODE_L6C, CODE_L6X, CODE_L6Z};
00066
00067
00068 const int CODES_QZS[] = {
00069     CODE_L1C, CODE_L1S, CODE_L1L, CODE_L2S, CODE_L2L, CODE_L2X, CODE_L5I, CODE_L5Q,
00070     CODE_L5X, CODE_L6S, CODE_L6L, CODE_L6X, CODE_L1X};
00071
00072
00073 const int CODES_BDS[] = {
00074     CODE_L1I, CODE_L1Q, CODE_L1X, CODE_L7I, CODE_L7Q, CODE_L7X, CODE_L6I, CODE_L6Q,
00075     CODE_L6X};
00076
00077
00078 const int CODES_SBS[] = {
00079     CODE_L1C, CODE_L5I, CODE_L5Q, CODE_L5X};
00080
00081
00082 double getbitg(const unsigned char *buff, int pos, int len);
00083
00084 void adjweek(rtc_t *rtc, double tow);
00085
00086 int adjbdtweek(int week);
00087
00088 void adjday_glot(rtc_t *rtc, double tod);
00089
00090 double adjcp(rtc_t *rtc, int sat, int freq, double cp);
00091
00092 int lossoflock(rtc_t *rtc, int sat, int freq, int lock);
00093
00094 unsigned char snratio(double snr);
00095
00096 int obsindex3(obs_t *obs, gtime_t time, int sat);
00097
00098 int test_staid(rtc_t *rtc, int staid);
00099
00100 int decode_head1001(rtc_t *rtc, int *sync);
00101
00102 int decode_type1001(rtc_t *rtc);
00103
00104 int decode_type1002(rtc_t *rtc);
00105
00106 int decode_type1003(rtc_t *rtc);
00107
00108 int decode_type1004(rtc_t *rtc);
00109
00110 double getbits_38(const unsigned char *buff, int pos);
00111
00112 int decode_type1005(rtc_t *rtc);
00113
00114 int decode_type1006(rtc_t *rtc);
00115
00116 int decode_type1007(rtc_t *rtc);
00117
00118 int decode_type1008(rtc_t *rtc);
00119
00120 int decode_head1009(rtc_t *rtc, int *sync);
00121
00122 int decode_type1009(rtc_t *rtc);
00123
00124 int decode_type1010(rtc_t *rtc);
00125
00126 int decode_type1011(rtc_t *rtc);
00127
00128 int decode_type1012(rtc_t *rtc);
00129
00130 int decode_type1013(rtc_t *rtc);
00131
```

```
00132 int decode_type1019(rtc_t *rtc, bool pre_2009_file = false);
00133
00134 int decode_type1020(rtc_t *rtc);
00135
00136 int decode_type1021(rtc_t *rtc);
00137
00138 int decode_type1022(rtc_t *rtc);
00139
00140 int decode_type1023(rtc_t *rtc);
00141
00142 int decode_type1024(rtc_t *rtc);
00143
00144 int decode_type1025(rtc_t *rtc);
00145
00146 int decode_type1026(rtc_t *rtc);
00147
00148 int decode_type1027(rtc_t *rtc);
00149
00150 int decode_type1029(rtc_t *rtc);
00151
00152 int decode_type1030(rtc_t *rtc);
00153
00154 int decode_type1031(rtc_t *rtc);
00155
00156 int decode_type1032(rtc_t *rtc);
00157
00158 int decode_type1033(rtc_t *rtc);
00159
00160 int decode_type1034(rtc_t *rtc);
00161
00162 int decode_type1035(rtc_t *rtc);
00163
00164 int decode_type1037(rtc_t *rtc);
00165
00166 int decode_type1038(rtc_t *rtc);
00167
00168 int decode_type1039(rtc_t *rtc);
00169
00170 int decode_type1044(rtc_t *rtc, bool pre_2009_file = false);
00171
00172 int decode_type1045(rtc_t *rtc);
00173
00174 int decode_type1046(rtc_t *rtc);
00175
00176 int decode_type1047(rtc_t *rtc);
00177
00178 int decode_type1063(rtc_t *rtc);
00179
00180 int decode_ssr1_head(rtc_t *rtc, int sys, int *sync, int *iod,
00181     double *udint, int *refd, int *hsize);
00182
00183 int decode_ssr2_head(rtc_t *rtc, int sys, int *sync, int *iod,
00184     double *udint, int *hsize);
00185
00186 int decode_ssr7_head(rtc_t *rtc, int sys, int *sync, int *iod,
00187     double *udint, int *dispe, int *mw, int *hsize);
00188
00189 int decode_ssr1(rtc_t *rtc, int sys);
00190
00191 int decode_ssr2(rtc_t *rtc, int sys);
00192
00193 int decode_ssr3(rtc_t *rtc, int sys);
00194
00195 int decode_ssr4(rtc_t *rtc, int sys);
00196
00197 int decode_ssr5(rtc_t *rtc, int sys);
00198
00199 int decode_ssr6(rtc_t *rtc, int sys);
00200
00201 int decode_ssr7(rtc_t *rtc, int sys);
00202
00203 void sigindex(int sys, const unsigned char *code, const int *freq, int n,
00204     const char *opt, int *ind);
00205
00206 void save_msm_obs(rtc_t *rtc, int sys, msm_h_t *h, const double *r,
00207     const double *pr, const double *cp, const double *rr,
00208     const double *rrf, const double *cnr, const int *lock,
00209     const int *ex, const int *half);
00210
00211 int decode_msm_head(rtc_t *rtc, int sys, int *sync, int *iod,
00212     msm_h_t *h, int *hsize);
00213
00214 int decode_msm0(rtc_t *rtc, int sys);
00215
00216 int decode_msm4(rtc_t *rtc, int sys);
00217
00218 int decode_msm5(rtc_t *rtc, int sys);
```

```

00219
00220 int decode_msm6(rtc_t *rtc, int sys);
00221
00222 int decode_msm7(rtc_t *rtc, int sys);
00223
00224 int decode_type1230(rtc_t *rtc);
00225
00226 int decode_rtc3(rtc_t *rtc);
00227
00228
00229 #endif

```

13.232 rtklib_rtkcmn.h File Reference

rtklib common functions

```

#include "rtklib.h"
#include <stddef>
#include <string>
#include <boost/filesystem/operations.hpp>
#include <boost/filesystem/path.hpp>
#include <boost/filesystem/path_traits.hpp>
#include <boost/system/error_code.hpp>

```

Macros

- #define **Rx**(t, X)
- #define **Ry**(t, X)
- #define **Rz**(t, X)

Functions

- char * **strncpy_no_trunc** (char *out, size_t outsz, const char *in, size_t insz)
- void **fatalerr** (const char *format,...)
- int **satno** (int sys, int prn)
- int **satsys** (int sat, int *prn)
- int **satid2no** (const char *id)
- std::string **satno2id** (int sat)
- int **satexclude** (int sat, int svh, const **prcopt_t** *opt)
- int **testsnr** (int base, int freq, double el, double snr, const **snrmask_t** *mask)
- unsigned char **obs2code** (const char *obs, int *freq)
- char * **code2obs** (unsigned char code, int *freq)
- void **setcodepri** (int sys, int freq, const char *pri)
- int **getcodepri** (int sys, unsigned char code, const char *opt)
- unsigned int **getbitu** (const unsigned char *buff, int pos, int len)
- int **getbits** (const unsigned char *buff, int pos, int len)
- void **setbitu** (unsigned char *buff, int pos, int len, unsigned int data)
- void **setbits** (unsigned char *buff, int pos, int len, int data)
- unsigned int **rtk_crc32** (const unsigned char *buff, int len)
- unsigned int **rtk_crc24q** (const unsigned char *buff, int len)
- unsigned short **rtk_crc16** (const unsigned char *buff, int len)
- int **decode_word** (unsigned int word, unsigned char *data)
- double * **mat** (int n, int m)
- int * **imat** (int n, int m)
- double * **zeros** (int n, int m)
- double * **eye** (int n)
- double **dot** (const double *a, const double *b, int n)
- double **norm_rtk** (const double *a, int n)
- void **cross3** (const double *a, const double *b, double *c)

- int **normv3** (const double *a, double *b)
- void **matcpy** (double *A, const double *B, int n, int m)
- void **matmul** (const char *tr, int n, int k, int m, double alpha, const double *A, const double *B, double beta, double *C)
- int **matinv** (double *A, int n)
- int **solve** (const char *tr, const double *A, const double *Y, int n, int m, double *X)
- int **lsq** (const double *A, const double *y, int n, int m, double *x, double *Q)
- int **filter_** (const double *x, const double *P, const double *H, const double *v, const double *R, int n, int m, double *xp, double *Pp)
- int **filter** (double *x, double *P, const double *H, const double *v, const double *R, int n, int m)
- int **smoother** (const double *xf, const double *Qf, const double *xb, const double *Qb, int n, double *xs, double *Qs)
- void **matfprint** (const double A[], int n, int m, int p, int q, FILE *fp)
- void **matsprint** (const double A[], int n, int m, int p, int q, std::string &buffer)
- void **matprint** (const double A[], int n, int m, int p, int q)
- double **str2num** (const char *s, int i, int n)
- int **str2time** (const char *s, int i, int n, [gtime_t](#) *t)
- [gtime_t](#) **epoch2time** (const double *ep)
- void **time2epoch** ([gtime_t](#) t, double *ep)
- [gtime_t](#) **gpst2time** (int week, double sec)
- double **time2gpst** ([gtime_t](#) t, int *week)
- [gtime_t](#) **gst2time** (int week, double sec)
- double **time2gst** ([gtime_t](#) t, int *week)
- [gtime_t](#) **bdt2time** (int week, double sec)
- double **time2bdt** ([gtime_t](#) t, int *week)
- [gtime_t](#) **timeadd** ([gtime_t](#) t, double sec)
- double **timediff** ([gtime_t](#) t1, [gtime_t](#) t2)
- double **timediffweekcrossover** ([gtime_t](#) t1, [gtime_t](#) t2)
- [gtime_t](#) **timeget** ()
- void **timeset** ([gtime_t](#) t)
- int **read_leaps_text** (FILE *fp)
- int **read_leaps_usno** (FILE *fp)
- int **read_leaps** (const char *file)
- [gtime_t](#) **gpst2utc** ([gtime_t](#) t)
- [gtime_t](#) **utc2gpst** ([gtime_t](#) t)
- [gtime_t](#) **gpst2bdt** ([gtime_t](#) t)
- [gtime_t](#) **bdt2gpst** ([gtime_t](#) t)
- double **time2sec** ([gtime_t](#) time, [gtime_t](#) *day)
- double **utc2gmst** ([gtime_t](#) t, double ut1_utc)
- void **time2str** ([gtime_t](#) t, char *s, int n)
- char * **time_str** ([gtime_t](#) t, int n)
- double **time2doy** ([gtime_t](#) t)
- int **adjgpsweek** (int week, bool pre_2009_file=false)
- unsigned int **tickget** ()
- void **sleepms** (int ms)
- void **deg2dms** (double deg, double *dms, int ndec)
- void **deg2dms** (double deg, double *dms)
- double **dms2deg** (const double *dms)
- void **ecf2pos** (const double *r, double *pos)
- void **pos2ecf** (const double *pos, double *r)
- void **xyz2enu** (const double *pos, double *E)
- void **ecf2enu** (const double *pos, const double *r, double *e)
- void **enu2ecf** (const double *pos, const double *e, double *r)
- void **covenu** (const double *pos, const double *P, double *Q)
- void **covecef** (const double *pos, const double *Q, double *P)

- void **ast_args** (double t, double *f)
- void **nut_iau1980** (double t, const double *f, double *dpsi, double *deps)
- void **eci2ecf** (gtime_t tutc, const double *erpv, double *U, double *gmst)
- int **decodef** (char *p, int n, double *v)
- void **addpcv** (const pcv_t *pcv, pcvs_t *pcvs)
- int **readngspcv** (const char *file, pcvs_t *pcvs)
- int **readantex** (const char *file, pcvs_t *pcvs)
- int **readpcv** (const char *file, pcvs_t *pcvs)
- pcv_t * **searchpcv** (int sat, const char *type, gtime_t time, const pcvs_t *pcvs)
- void **readpos** (const char *file, const char *rcv, double *pos)
- int **readblqrecord** (FILE *fp, double *odisp)
- int **readblq** (const char *file, const char *sta, double *odisp)
- int **readerp** (const char *file, erp_t *erp)
- int **geterp** (const erp_t *erp, gtime_t time, double *erpv)
- int **cmpeph** (const void *p1, const void *p2)
- void **uniqueph** (nav_t *nav)
- int **cmpgeph** (const void *p1, const void *p2)
- void **uniggeph** (nav_t *nav)
- int **cmpseph** (const void *p1, const void *p2)
- void **uniqseph** (nav_t *nav)
- void **uniqnav** (nav_t *nav)
- int **cmpobs** (const void *p1, const void *p2)
- int **sortobs** (obs_t *obs)
- int **screent** (gtime_t time, gtime_t ts, gtime_t te, double tint)
- int **readnav** (const char *file, nav_t *nav)
- int **savenav** (const char *file, const nav_t *nav)
- void **freeobs** (obs_t *obs)
- void **freenav** (nav_t *nav, int opt)
- void **traceopen** (const char *file)
- void **traceclose** ()
- void **tracelevel** (int level)
- void **traceswap** ()
- void **trace** (int level, const char *format,...)
- void **tracet** (int level, const char *format,...)
- void **tracemat** (int level, const double *A, int n, int m, int p, int q)
- void **traceobs** (int level, const obsd_t *obs, int n)
- int **execcmd** (const char *cmd)
- void **createdir** (fs::path const &path)
- int **reppath** (std::string const &path, std::string &spath, gtime_t time, const char *rov, const char *base)
- double **satwavelen** (int sat, int frq, const nav_t *nav)
- double **geodist** (const double *rs, const double *rr, double *e)
- double **satazel** (const double *pos, const double *e, double *azel)
- void **dops** (int ns, const double *azel, double elmin, double *dop)
- double **ionmodel** (gtime_t t, const double *ion, const double *pos, const double *azel)
- double **ionmapf** (const double *pos, const double *azel)
- double **ionppp** (const double *pos, const double *azel, double re, double hion, double *posp)
- double **tropmodel** (gtime_t time, const double *pos, const double *azel, double humi)
- double **interp** (const double coeff[], double lat)
- double **mapf** (double el, double a, double b, double c)
- double **nmf** (gtime_t time, const double pos[], const double azel[], double *mapfw)
- double **tropmapf** (gtime_t time, const double pos[], const double azel[], double *mapfw)
- double **interpvar** (double ang, const double *var)
- void **antmodel** (const pcv_t *pcv, const double *del, const double *azel, int opt, double *dant)
- void **antmodel_s** (const pcv_t *pcv, double nadir, double *dant)
- void **sunmoonpos_eci** (gtime_t tut, double *rsun, double *rmoon)

- void **sunmoonpos** ([gtime_t](#) tutc, const double *erpv, double *rsun, double *rmoon, double *gmst)
- void **csmooth** ([obs_t](#) *obs, int ns)
- int **rtk_uncompress** (const char *file, char *uncfile)
- int **expath** (const char *path, char *paths[], int nmax)
- void **windupcorr** ([gtime_t](#) time, const double *rs, const double *rr, double *phw)

13.232.1 Detailed Description

rtklib common functions

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

This is a derived work from RTKLIB <http://www.rtklib.com/> The original source code at <https://github.com/tomohitakasu/RTKLIB> is released under the BSD 2-clause license with an additional exclusive clause that does not apply here. This additional clause is reproduced below:

" The software package includes some companion executive binaries or shared libraries necessary to execute APs on Windows. These licenses succeed to the original ones of these software. "

Neither the executive binaries nor the shared libraries are required by, used or included in GNSS-SDR.

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SPDX-License-Identifier: BSD-2-Clause

References : [1] IS-GPS-200M, Navstar GPS Space Segment/Navigation User Interfaces, May, 2021 [2] RTCA/DO-229C, Minimum operational performance standards for global positioning system/wide area augmentation system airborne equipment, RTCA inc, November 28, 2001 [3] M.Rothacher, R.Schmid, ANTEX: The Antenna Exchange Format Version 1.4, 15 September, 2010 [4] A.Gelb ed., Applied Optimal Estimation, The M.I.T Press, 1974 [5] A.↵ E.Niell, Global mapping functions for the atmosphere delay at radio wavelengths, Journal of geophysical research, 1996 [6] W.Gurtner and L.Estey, RINEX The Receiver Independent Exchange Format Version 3.00, November 28, 2007 [7] J.Kouba, A Guide to using International GNSS Service (IGS) products, May 2009 [8] China Satellite Navigation Office, BeiDou navigation satellite system signal in space interface control document, open service signal B1I (version 1.0), Dec 2012 [9] J.Boehm, A.Niell, P.Tregoning and H.Shuh, Global Mapping Function (GMF): A new empirical mapping function base on numerical weather model data, Geophysical Research Letters, 33, L07304, 2006 [10] GLONASS/GPS/Galileo/Compass/SBAS NV08C receiver series BINR interface protocol specification ver.1.3, August, 2012

Definition in file [rtklib_rtkcmn.h](#).

13.232.2 Macro Definition Documentation

13.232.2.1 Rx

```
#define Rx(
```

```
    t,
    X)
```

Value:

```
do
{
    (X)[0] = 1.0;
    (X)[1] = (X)[2] = (X)[3] = (X)[6] = 0.0;
    (X)[4] = (X)[8] = cos(t);
    (X)[7] = sin(t);
    (X)[5] = -(X)[7];
}
while (0)
```

Definition at line 85 of file [rtklib_rtkcmn.h](#).

13.232.2.2 Ry

```
#define Ry(
```

```
    t,
    X)
```

Value:

```

do
{
    (X)[4] = 1.0;
    (X)[1] = (X)[3] = (X)[5] = (X)[7] = 0.0;
    (X)[0] = (X)[8] = cos(t);
    (X)[2] = sin(t);
    (X)[6] = -(X)[2];
}
while (0)

```

Definition at line 96 of file `rtklib_rtkcmn.h`.

13.232.2.3 Rz

```
#define Rz(
```

```

    t,
    X)

```

Value:

```

do
{
    (X)[8] = 1.0;
    (X)[2] = (X)[5] = (X)[6] = (X)[7] = 0.0;
    (X)[0] = (X)[4] = cos(t);
    (X)[3] = sin(t);
    (X)[1] = -(X)[3];
}
while (0)

```

Definition at line 107 of file `rtklib_rtkcmn.h`.

13.233 rtklib_rtkcmn.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file rtklib_rtkcmn.h
00003  * \brief rtklib common functions
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
00011  * The original source code at https://github.com/tomojitakasu/RTKLIB is
00012  * released under the BSD 2-clause license with an additional exclusive clause
00013  * that does not apply here. This additional clause is reproduced below:
00014  *
00015  * " The software package includes some companion executive binaries or shared
00016  * libraries necessary to execute APs on Windows. These licenses succeed to the
00017  * original ones of these software. "
00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
00020  * or included in GNSS-SDR.
00021  *
00022  * -----
00023  * Copyright (C) 2007-2013, T. Takasu
00024  * Copyright (C) 2017, Javier Arribas
00025  * Copyright (C) 2017, Carles Fernandez
00026  * All rights reserved.
00027  *
00028  * SPDX-License-Identifier: BSD-2-Clause
00029  *
00030  *
00031  * References :
00032  * [1] IS-GPS-200M, Navstar GPS Space Segment/Navigation User Interfaces,
00033  *     May, 2021
00034  * [2] RTCA/DO-229C, Minimum operational performance standards for global
00035  *     positioning system/wide area augmentation system airborne equipment,
00036  *     RTCA inc, November 28, 2001
00037  * [3] M.Rothacher, R.Schmid, ANTEX: The Antenna Exchange Format Version 1.4,
00038  *     15 September, 2010
00039  * [4] A.Gelb ed., Applied Optimal Estimation, The M.I.T Press, 1974
00040  * [5] A.E.Niell, Global mapping functions for the atmosphere delay at radio
00041  *     wavelengths, Journal of geophysical research, 1996
00042  * [6] W.Gurtner and L.Estey, RINEX The Receiver Independent Exchange Format
00043  *     Version 3.00, November 28, 2007
00044  * [7] J.Kouba, A Guide to using International GNSS Service (IGS) products,
00045  *     May 2009
00046  * [8] China Satellite Navigation Office, BeiDou navigation satellite system

```



```

00047 *          signal in space interface control document, open service signal B1I
00048 *          (version 1.0), Dec 2012
00049 *          [9] J.Boehm, A.Niell, P.Tregoning and H.Shuh, Global Mapping Function
00050 *          (GMF): A new empirical mapping function base on numerical weather
00051 *          model data, Geophysical Research Letters, 33, L07304, 2006
00052 *          [10] GLONASS/GPS/Galileo/Compass/SBAS NV08C receiver series BINR interface
00053 *          protocol specification ver.1.3, August, 2012
00054 *
00055 * -----
00056 */
00057
00058 #ifndef GNSS_SDR_RTKLIB_RTKCMN_H
00059 #define GNSS_SDR_RTKLIB_RTKCMN_H
00060
00061 #include "rtklib.h"
00062 #include <stddef>
00063 #include <string>
00064
00065 #if HAS_STD_FILESYSTEM
00066 #include <system_error>
00067 namespace errorlib = std;
00068 #if HAS_STD_FILESYSTEM_EXPERIMENTAL
00069 #include <experimental/filesystem>
00070 namespace fs = std::experimental::filesystem;
00071 #else
00072 #include <filesystem>
00073 namespace fs = std::filesystem;
00074 #endif
00075 #else
00076 #include <boost/filesystem/operations.hpp> // for create_directories, exists
00077 #include <boost/filesystem/path.hpp> // for path, operator«
00078 #include <boost/filesystem/path_traits.hpp> // for filesystem
00079 #include <boost/system/error_code.hpp> // for error_code
00080 namespace fs = boost::filesystem;
00081 namespace errorlib = boost::system;
00082 #endif
00083
00084 /* coordinate rotation matrix -----*/
00085 #define Rx(t, X) \
00086     do \
00087     { \
00088         (X)[0] = 1.0; \
00089         (X)[1] = (X)[2] = (X)[3] = (X)[6] = 0.0; \
00090         (X)[4] = (X)[8] = cos(t); \
00091         (X)[7] = sin(t); \
00092         (X)[5] = -(X)[7]; \
00093     } \
00094     while (0)
00095
00096 #define Ry(t, X) \
00097     do \
00098     { \
00099         (X)[4] = 1.0; \
00100         (X)[1] = (X)[3] = (X)[5] = (X)[7] = 0.0; \
00101         (X)[0] = (X)[8] = cos(t); \
00102         (X)[2] = sin(t); \
00103         (X)[6] = -(X)[2]; \
00104     } \
00105     while (0)
00106
00107 #define Rz(t, X) \
00108     do \
00109     { \
00110         (X)[8] = 1.0; \
00111         (X)[2] = (X)[5] = (X)[6] = (X)[7] = 0.0; \
00112         (X)[0] = (X)[4] = cos(t); \
00113         (X)[3] = sin(t); \
00114         (X)[1] = -(X)[3]; \
00115     } \
00116     while (0)
00117
00118 char *strncpy_no_trunc(char *out, size_t outsz, const char *in, size_t insz);
00119 void fatalerr(const char *format, ...);
00120 int satno(int sys, int prn);
00121 int satsys(int sat, int *prn);
00122 int satid2no(const char *id);
00123 std::string satno2id(int sat);
00124 int satexclude(int sat, int svh, const prcopt_t *opt);
00125 int testsnr(int base, int freq, double el, double snr, const snrmask_t *mask);
00126 unsigned char obs2code(const char *obs, int *freq);
00127 char *code2obs(unsigned char code, int *freq);
00128 void setcodepri(int sys, int freq, const char *pri);
00129 int getcodepri(int sys, unsigned char code, const char *opt);
00130 unsigned int getbitu(const unsigned char *buff, int pos, int len);
00131 int getbits(const unsigned char *buff, int pos, int len);
00132 void setbitu(unsigned char *buff, int pos, int len, unsigned int data);
00133 void setbits(unsigned char *buff, int pos, int len, int data);

```

```
00134 unsigned int rtk_crc32(const unsigned char *buff, int len);
00135 unsigned int rtk_crc24q(const unsigned char *buff, int len);
00136 unsigned short rtk_crc16(const unsigned char *buff, int len);
00137 int decode_word(unsigned int word, unsigned char *data);
00138 double *mat(int n, int m);
00139 int *imat(int n, int m);
00140 double *zeros(int n, int m);
00141 double *eye(int n);
00142 double dot(const double *a, const double *b, int n);
00143 double norm_rtk(const double *a, int n);
00144 void cross3(const double *a, const double *b, double *c);
00145 int normv3(const double *a, double *b);
00146 void matcpy(double *A, const double *B, int n, int m);
00147 void matmul(const char *tr, int n, int k, int m, double alpha,
00148             const double *A, const double *B, double beta, double *C);
00149 int matinv(double *A, int n);
00150 int solve(const char *tr, const double *A, const double *Y, int n,
00151           int m, double *X);
00152 int lsq(const double *A, const double *y, int n, int m, double *x,
00153         double *Q);
00154 int filter_(const double *x, const double *P, const double *H,
00155            const double *v, const double *R, int n, int m,
00156            double *xp, double *Pp);
00157 int filter(const double *x, double *P, const double *H, const double *v,
00158           const double *R, int n, int m);
00159 int smoother(const double *xf, const double *Qf, const double *xb,
00160             const double *Qb, int n, double *xs, double *Qs);
00161 void matfprintf(const double A[], int n, int m, int p, int q, FILE *fp);
00162 void matsprintf(const double A[], int n, int m, int p, int q, std::string &buffer);
00163 void matprint(const double A[], int n, int m, int p, int q);
00164 double str2num(const char *s, int i, int n);
00165 int str2time(const char *s, int i, int n, gtime_t *t);
00166 gtime_t epoch2time(const double *ep);
00167 void time2epoch(gtime_t t, double *ep);
00168 gtime_t gpst2time(int week, double sec);
00169 double time2gpst(gtime_t t, int *week);
00170 gtime_t gst2time(int week, double sec);
00171 double time2gst(gtime_t t, int *week);
00172 gtime_t bdt2time(int week, double sec);
00173 double time2bdt(gtime_t t, int *week);
00174 gtime_t timeadd(gtime_t t, double sec);
00175 double timediff(gtime_t t1, gtime_t t2);
00176 double timediffweekcrossover(gtime_t t1, gtime_t t2);
00177 gtime_t timeget();
00178 void timeset(gtime_t t);
00179 int read_leaps_text(FILE *fp);
00180 int read_leaps_usno(FILE *fp);
00181 int read_leaps(const char *file);
00182 gtime_t gpst2utc(gtime_t t);
00183 gtime_t utc2gpst(gtime_t t);
00184 gtime_t gpst2bdt(gtime_t t);
00185 gtime_t bdt2gpst(gtime_t t);
00186 double time2sec(gtime_t time, gtime_t *day);
00187 double utc2gmst(gtime_t t, double ut1_utc);
00188 void time2str(gtime_t t, char *s, int n);
00189 char *time_str(gtime_t t, int n);
00190 double time2doy(gtime_t t);
00191 int adjgpsweek(int week, bool pre_2009_file = false);
00192 unsigned int tickget();
00193 void sleepms(int ms);
00194 void deg2dms(double deg, double *dms, int ndec);
00195 void dms2deg(double deg, double *dms);
00196 double dms2deg(const double *dms);
00197 void ecef2pos(const double *r, double *pos);
00198 void pos2ecef(const double *pos, double *r);
00199 void xyz2enu(const double *pos, double *E);
00200 void ecef2enu(const double *pos, const double *r, double *e);
00201 void enu2ecef(const double *pos, const double *e, double *r);
00202 void covenu(const double *pos, const double *P, double *Q);
00203 void covecef(const double *pos, const double *Q, double *P);
00204 void ast_args(double t, double *f);
00205 void nut_iau1980(double t, const double *f, double *dpsi, double *deps);
00206 void eci2ecef(gtime_t tutc, const double *erpv, double *U, double *gmst);
00207 int decodef(char *p, int n, double *v);
00208 void addpcv(const pcv_t *pcv, pcvs_t *pcvs);
00209 int readngpcv(const char *file, pcvs_t *pcvs);
00210 int readantex(const char *file, pcvs_t *pcvs);
00211 int readpcv(const char *file, pcvs_t *pcvs);
00212 pcv_t *searchpcv(int sat, const char *type, gtime_t time,
00213                 const pcvs_t *pcvs);
00214 void readpos(const char *file, const char *rcv, double *pos);
00215 int readblqrecord(FILE *fp, double *odisp);
00216 int readblq(const char *file, const char *sta, double *odisp);
00217 int readerp(const char *file, erp_t *erp);
00218 int geterp(const erp_t *erp, gtime_t time, double *erpv);
00219 int cmppeph(const void *p1, const void *p2);
00220 void uniqeph(nav_t *nav);
```

```

00221 int cmpgeph(const void *p1, const void *p2);
00222 void uniqgeph(nav_t *nav);
00223 int cmpseph(const void *p1, const void *p2);
00224 void uniqseph(nav_t *nav);
00225 void unignav(nav_t *nav);
00226 int cmpobs(const void *p1, const void *p2);
00227 int sortobs(obs_t *obs);
00228 int screent(gtime_t time, gtime_t ts, gtime_t te, double tint);
00229 int readnav(const char *file, nav_t *nav);
00230 int savenav(const char *file, const nav_t *nav);
00231 void freeobs(obs_t *obs);
00232 void freenav(nav_t *nav, int opt);
00233
00234 void traceopen(const char *file);
00235 void traceclose();
00236 void tracelevel(int level);
00237 void traceswap();
00238 void trace(int level, const char *format, ...);
00239 void tracet(int level, const char *format, ...);
00240 void tracemat(int level, const double *A, int n, int m, int p, int q);
00241 void traceobs(int level, const obsd_t *obs, int n);
00242 // void tracenav(int level, const nav_t *nav);
00243 // void tracegnav(int level, const nav_t *nav);
00244 // void tracehnav(int level, const nav_t *nav);
00245 // void tracepeph(int level, const nav_t *nav);
00246 // void tracepclk(int level, const nav_t *nav);
00247 // void traceb (int level, const unsigned char *p, int n);
00248
00249 int execcmd(const char *cmd);
00250 void createdir(fs::path const &path);
00251 int reppath(std::string const &path, std::string &rp, gtime_t time, const char *rov,
00252            const char *base);
00253 double satwavelen(int sat, int frq, const nav_t *nav);
00254 double geodist(const double *rs, const double *rr, double *e);
00255 double satazel(const double *pos, const double *e, double *azel);
00256
00257 void dops(int ns, const double *azel, double elmin, double *dop);
00258 double ionmodel(gtime_t t, const double *ion, const double *pos,
00259                const double *azel);
00260 double ionmapf(const double *pos, const double *azel);
00261 double ionppp(const double *pos, const double *azel, double re,
00262               double hion, double *posp);
00263 double tropmodel(gtime_t time, const double *pos, const double *azel,
00264                  double humi);
00265 double interpc(const double coef[], double lat);
00266 double mapf(double el, double a, double b, double c);
00267 double nmf(gtime_t time, const double pos[], const double azel[],
00268            double *mapfw);
00269 double tropmapf(gtime_t time, const double pos[], const double azel[],
00270                 double *mapfw);
00271 double interpvar(double ang, const double *var);
00272
00273 void antmodel(const pcv_t *pcv, const double *del, const double *azel,
00274               int opt, double *dant);
00275
00276 void antmodel_s(const pcv_t *pcv, double nadir, double *dant);
00277 void sunmoonpos_eci(gtime_t tut, double *rsun, double *rmoon);
00278 void sunmoonpos(gtime_t tutc, const double *erpv, double *rsun,
00279                 double *rmoon, double *gmst);
00280 void csmooth(obs_t *obs, int ns);
00281 int rtk_uncompress(const char *file, char *uncfile);
00282 int expath(const char *path, char *paths[], int nmax);
00283 void windupcorr(gtime_t time, const double *rs, const double *rr, double *phw);
00284
00285 #endif // GNSS_SDR_RTKLIB_RTKCMN_H

```

13.234 rtklib_rtkpos.h File Reference

rtklib ppp-related functions

```
#include "rtklib.h"
```

```
#include "rtklib_rtkcmn.h"
```

Macros

- `#define IL_RTK(s, opt)`
- `#define IT_RTK(r, opt)`
- `#define IL_RTK(f, opt)`
- `#define IB_RTK(s, f, opt)`

Functions

- int **rtkopenstat** (const char *file, int level)
- void **rtkclosestat** ()
- void **rtkoutstat** (rtk_t *rtk)
- void **swapsolstat** ()
- void **outsolstat** (rtk_t *rtk)
- void **errmsg** (rtk_t *rtk, const char *format,...)
- double **sdoobs** (const obsd_t *obs, int i, int j, int f)
- double **gfobs_L1L2** (const obsd_t *obs, int i, int j, const double *lam)
- double **gfobs_L1L5** (const obsd_t *obs, int i, int j, const double *lam)
- double **varerr** (int sat, int sys, double el, double bl, double dt, int f, const prcopt_t *opt)
- double **baseline** (const double *ru, const double *rb, double *dr)
- void **initx_rtk** (rtk_t *rtk, double xi, double var, int i)
- int **selsat** (const obsd_t *obs, const double *azel, int nu, int nr, const prcopt_t *opt, int *sat, int *iu, int *ir)
- void **udpos** (rtk_t *rtk, double tt)
- void **udion** (rtk_t *rtk, double tt, double bl, const int *sat, int ns)
- void **udtrop** (rtk_t *rtk, double tt, double bl)
- void **udrcvbias** (rtk_t *rtk, double tt)
- void **detslp_ll** (rtk_t *rtk, const obsd_t *obs, int i, int rcv)
- void **detslp_gf_L1L2** (rtk_t *rtk, const obsd_t *obs, int i, int j, const nav_t *nav)
- void **detslp_gf_L1L5** (rtk_t *rtk, const obsd_t *obs, int i, int j, const nav_t *nav)
- void **detslp_dop** (rtk_t *rtk, const obsd_t *obs, int i, int rcv, const nav_t *nav)
- void **udbias** (rtk_t *rtk, double tt, const obsd_t *obs, const int *sat, const int *iu, const int *ir, int ns, const nav_t *nav)
- void **udstate** (rtk_t *rtk, const obsd_t *obs, const int *sat, const int *iu, const int *ir, int ns, const nav_t *nav)
- void **zdres_sat** (int base, double r, const obsd_t *obs, const nav_t *nav, const double *azel, const double *dant, const prcopt_t *opt, double *y)
- int **zdres** (int base, const obsd_t *obs, int n, const double *rs, const double *dts, const int *svh, const nav_t *nav, const double *rr, const prcopt_t *opt, int index, double *y, double *e, double *azel)
- int **validobs** (int i, int j, int f, int nf, const double *y)
- void **ddcov** (const int *nb, int n, const double *Ri, const double *Rj, int nv, double *R)
- int **constbl** (rtk_t *rtk, const double *x, const double *P, double *v, double *H, double *Ri, double *Rj, int index)
- double **prectrop** (gtime_t time, const double *pos, int r, const double *azel, const prcopt_t *opt, const double *x, double *dtdx)
- double **gloicbcorr** (int sat1, int sat2, const prcopt_t *opt, double lam1, double lam2, int f)
- int **test_sys** (int sys, int m)
- int **ddres** (rtk_t *rtk, const nav_t *nav, double dt, const double *x, const double *P, const int *sat, double *y, const double *e, double *azel, const int *iu, const int *ir, int ns, double *v, double *H, double *R, int *vflg)
- double **intpres** (gtime_t time, const obsd_t *obs, int n, const nav_t *nav, rtk_t *rtk, double *y)
- int **ddmat** (rtk_t *rtk, double *D)
- void **restamb** (rtk_t *rtk, const double *bias, int nb, double *xa)
- void **holdamb** (rtk_t *rtk, const double *xa)
- int **resamb_LAMBDA** (rtk_t *rtk, double *bias, double *xa)
- int **valpos** (rtk_t *rtk, const double *v, const double *R, const int *vflg, int nv, double thres)
- int **relpos** (rtk_t *rtk, const obsd_t *obs, int nu, int nr, const nav_t *nav)
- void **rtkinit** (rtk_t *rtk, const prcopt_t *opt)
- void **rtkfree** (rtk_t *rtk)
- int **rtkpos** (rtk_t *rtk, const obsd_t *obs, int n, const nav_t *nav)

Variables

- const double `VAR_POS` = std::pow(30.0, 2.0)
- const double `VAR_VEL` = std::pow(10.0, 2.0)
- const double `VAR_ACC` = std::pow(10.0, 2.0)
- const double `VAR_HWBIAS` = std::pow(1.0, 2.0)
- const double `VAR_GRA` = std::pow(0.001, 2.0)
- const double `INIT_ZWD` = 0.15
- const double `PRN_HWBIA` = 1E-6
- const double `MAXAC` = 30.0
- const double `VAR_HOLDAMB` = 0.001
- const double `TTOL_MOVEB` = (1.0 + 2 * `DTTOL`)

13.234.1 Detailed Description

rtklib ppp-related functions

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

This is a derived work from RTKLIB <http://www.rtklib.com/> The original source code at <https://github.com/tomojitakasu/RTKLIB> is released under the BSD 2-clause license with an additional exclusive clause that does not apply here. This additional clause is reproduced below:

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Neither the executive binaries nor the shared libraries are required by, used or included in GNSS-SDR.

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Definition in file [rtklib_rtkpos.h](#).

13.235 rtklib_rtkpos.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib_rtkpos.h
00003  * \brief rtklib ppp-related functions
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
00011  * The original source code at https://github.com/tomojitakasu/RTKLIB is
00012  * released under the BSD 2-clause license with an additional exclusive clause
00013  * that does not apply here. This additional clause is reproduced below:
00014  *
00015  * " The software package includes some companion executive binaries or shared
00016  * libraries necessary to execute APs on Windows. These licenses succeed to the
00017  * original ones of these software. "
00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
00020  * or included in GNSS-SDR.
00021  *
00022  * -----
00023  * Copyright (C) 2007-2013, T. Takasu
00024  * Copyright (C) 2017, Javier Arribas
00025  * Copyright (C) 2017, Carles Fernandez
00026  * All rights reserved.
00027  *
00028  * SPDX-License-Identifier: BSD-2-Clause
00029  * -----
```

```

00030  */
00031
00032 #ifndef GNSS_SDR_RTKLIB_RKTPOS_H
00033 #define GNSS_SDR_RTKLIB_RKTPOS_H
00034
00035 #include "rtklib.h"
00036 #include "rtklib_rtkcmn.h"
00037
00038 /** \addtogroup PVT
00039  * \{ */
00040 /** \addtogroup RTKLIB_Library
00041  * \{ */
00042
00043
00044 /* constants/macros -----*/
00045 const double VAR_POS = std::pow(30.0, 2.0); /* initial variance of receiver pos (m^2) */
00046 const double VAR_VEL = std::pow(10.0, 2.0); /* initial variance of receiver vel ((m/s)^2) */
00047 const double VAR_ACC = std::pow(10.0, 2.0); /* initial variance of receiver acc ((m/ss)^2) */
00048 const double VAR_HWBIAS = std::pow(1.0, 2.0); /* initial variance of h/w bias ((m/MHz)^2) */
00049 const double VAR_GRA = std::pow(0.001, 2.0); /* initial variance of gradient (m^2) */
00050 const double INIT_ZWD = 0.15; /* initial zwd (m) */
00051
00052 const double PRN_HWBIA = 1E-6; /* process noise of h/w bias (m/MHz/sqrt(s)) */
00053 const double MAXAC = 30.0; /* max accel for doppler slip detection (m/s^2) */
00054
00055 const double VAR_HOLDAMB = 0.001; /* constraint to hold ambiguity (cycle^2) */
00056
00057 const double TTOL_MOVEB = (1.0 + 2 * DTTOL);
00058 /* time sync tolerance for moving-baseline (s) */
00059
00060 /* number of parameters (pos,ionos,tropos,hw-bias,phase-bias,real,estimated) */
00061
00062
00063 /* state variable index */
00064 // clang-format off
00065 #define II_RTK(s, opt) (NP_RTK(opt) + (s)-1) /* ionos (s:satellite no)
00066 */
00067 #define IT_RTK(r, opt) (NP_RTK(opt) + NI_RTK(opt) + NT_RTK(opt) / 2 * (r)) /* tropos (r:0=rov,1:ref)
00068 */
00069 #define IL_RTK(f, opt) (NP_RTK(opt) + NI_RTK(opt) + NT_RTK(opt) + (f)) /* receiver h/w bias */
00070 #define IB_RTK(s, f, opt) (NR_RTK(opt) + MAXSAT * (f) + (s)-1) /* phase bias
00071 (s:satno,f:freq) */
00072 // clang-format on
00073
00074 int rtkopenstat(const char *file, int level);
00075
00076 void rtkclosestat();
00077
00078 void rtkoutstat(rtk_t *rtk);
00079
00080 void swapsolstat();
00081
00082 void outsolstat(rtk_t *rtk);
00083
00084 void errmsg(rtk_t *rtk, const char *format, ...);
00085
00086 double sdots(const obsd_t *obs, int i, int j, int f);
00087
00088 double gdots_L1L2(const obsd_t *obs, int i, int j, const double *lam);
00089
00090 double gdots_L1L5(const obsd_t *obs, int i, int j, const double *lam);
00091
00092 double varerr(int sat, int sys, double el, double bl, double dt, int f,
00093 const prcopt_t *opt);
00094
00095 double baseline(const double *ru, const double *rb, double *dr);
00096
00097 void initx_rtk(rtk_t *rtk, double xi, double var, int i);
00098
00099 int selsat(const obsd_t *obs, const double *azel, int nu, int nr,
00100 const prcopt_t *opt, int *sat, int *iu, int *ir);
00101
00102 void udpos(rtk_t *rtk, double tt);
00103
00104 void udion(rtk_t *rtk, double tt, double bl, const int *sat, int ns);
00105
00106 void udtrop(rtk_t *rtk, double tt, double bl);
00107
00108 void udrcvbias(rtk_t *rtk, double tt);
00109
00110 void detslp_ll(rtk_t *rtk, const obsd_t *obs, int i, int rcv);
00111
00112 void detslp_gf_L1L2(rtk_t *rtk, const obsd_t *obs, int i, int j,
00113 const nav_t *nav);
00114
00115 void detslp_gf_L1L5(rtk_t *rtk, const obsd_t *obs, int i, int j,
00116 const nav_t *nav);

```

```

00114
00115 void detslp_dop(rtk_t *rtk, const obsd_t *obs, int i, int rcv,
00116               const nav_t *nav);
00117
00118 void udbias(rtk_t *rtk, double tt, const obsd_t *obs, const int *sat,
00119            const int *iu, const int *ir, int ns, const nav_t *nav);
00120
00121 void udstate(rtk_t *rtk, const obsd_t *obs, const int *sat,
00122            const int *iu, const int *ir, int ns, const nav_t *nav);
00123
00124 void zdres_sat(int base, double r, const obsd_t *obs, const nav_t *nav,
00125              const double *azel, const double *dant,
00126              const prcopt_t *opt, double *y);
00127
00128 int zdres(int base, const obsd_t *obs, int n, const double *rs,
00129          const double *dts, const int *svh, const nav_t *nav,
00130          const double *rr, const prcopt_t *opt, int index, double *y,
00131          double *e, double *azel);
00132
00133 int validobs(int i, int j, int f, int nf, const double *y);
00134
00135 void ddcov(const int *nb, int n, const double *Ri, const double *Rj,
00136           int nv, double *R);
00137
00138 int constbl(rtk_t *rtk, const double *x, const double *P, double *v,
00139            double *H, double *Ri, double *Rj, int index);
00140
00141 double prectrop(gtime_t time, const double *pos, int r,
00142               const double *azel, const prcopt_t *opt, const double *x,
00143               double *dtdx);
00144
00145 double gloicbcorr(int sat1, int sat2, const prcopt_t *opt, double lam1,
00146                 double lam2, int f);
00147
00148 int test_sys(int sys, int m);
00149
00150 int ddres(rtk_t *rtk, const nav_t *nav, double dt, const double *x,
00151          const double *P, const int *sat, double *y, const double *e,
00152          double *azel, const int *iu, const int *ir, int ns, double *v,
00153          double *H, double *R, int *vflg);
00154
00155 double intpres(gtime_t time, const obsd_t *obs, int n, const nav_t *nav,
00156              rtk_t *rtk, double *y);
00157
00158
00159 int ddmatrix(rtk_t *rtk, double *D);
00160
00161 void restamb(rtk_t *rtk, const double *bias, int nb, double *xa);
00162
00163 void holdamb(rtk_t *rtk, const double *xa);
00164
00165 int resamb_IAMBDA(rtk_t *rtk, double *bias, double *xa);
00166
00167 int valpos(rtk_t *rtk, const double *v, const double *R, const int *vflg,
00168           int nv, double thres);
00169
00170 int relpos(rtk_t *rtk, const obsd_t *obs, int nu, int nr,
00171          const nav_t *nav);
00172
00173 void rtkinit(rtk_t *rtk, const prcopt_t *opt);
00174
00175 void rtkfree(rtk_t *rtk);
00176
00177 int rtkpos(rtk_t *rtk, const obsd_t *obs, int n, const nav_t *nav);
00178
00179
00180 /** \} */
00181 /** \} */
00182 #endif // GNSS_SDR_RTKLIB_RKTIPOS_H

```

13.236 rtklib_rtksvr.h File Reference

rtk server functions

```
#include "rtklib.h"
```

Functions

- void **writesolhead** (stream_t *stream, const solopt_t *solopt)
- void **saveoutbuf** (rtksvr_t *svr, unsigned char *buff, int n, int index)

- void **writesol** ([rtksvr_t](#) *svr, int index)
- void **updatenav** ([nav_t](#) *nav)
- void **updatefcfn** ([rtksvr_t](#) *svr)
- void **updatesvr** ([rtksvr_t](#) *svr, int ret, [obs_t](#) *obs, [nav_t](#) *nav, int sat, [sbsmsg_t](#) *sbsmsg, int index, int iobs)
- int **decoderaw** ([rtksvr_t](#) *svr, int index)
- void **decodefile** ([rtksvr_t](#) *svr, int index)
- void * **rtksvrthread** (void *arg)
- int **rtksvrinit** ([rtksvr_t](#) *svr)
- void **rtksvrfree** ([rtksvr_t](#) *svr)
- void **rtksvrlock** ([rtksvr_t](#) *svr)
- void **rtksvrunlock** ([rtksvr_t](#) *svr)
- int **rtksvrstart** ([rtksvr_t](#) *svr, int cycle, int buffsize, int *strs, char **paths, const int *formats, int navsel, char **cmds, char **rcvopts, int nmeacycle, int nmeareq, const double *nmeapos, [prcopt_t](#) *prcopt, [solopt_t](#) *solopt, [stream_t](#) *moni)
- void **rtksvrstop** ([rtksvr_t](#) *svr, char **cmds)
- int **rtksvropenstr** ([rtksvr_t](#) *svr, int index, int str, const char *path, const [solopt_t](#) *solopt)
- void **rtksvrclosestr** ([rtksvr_t](#) *svr, int index)
- int **rtksvrostat** ([rtksvr_t](#) *svr, int rcv, [gtime_t](#) *time, int *sat, double *az, double *el, int **snr, int *vsat)
- void **rtksvrsstat** ([rtksvr_t](#) *svr, int *sstat, char *msg)

Variables

- const [solopt_t](#) SOLOPT_DEFAULT
- const [prcopt_t](#) PRCOPT_DEFAULT

13.236.1 Detailed Description

rtk server functions

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

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Definition in file [rtklib_rtksvr.h](#).

13.236.2 Variable Documentation

13.236.2.1 PRCOPT_DEFAULT

const [prcopt_t](#) PRCOPT_DEFAULT

Initial value:

```
= {
    PMODE_SINGLE, 0, 2, SYS_GPS,
    15.0 * D2R, {{}}, {{}}, {{}},
    0, 1, 1, 1,
    5, 0, 10, 1,
    0, 0, 0, 0,
    1, 0, 0, 0, 0,
    0, 0,
    {100.0, 100.0, 100.0},
    {100.0, 0.003, 0.003, 0.0, 1.0},
}
```



```

{30.0, 0.03, 0.3},
{1e-4, 1e-3, 1e-4, 1e-1, 1e-2, 0.0},
5E-12,
{3.0, 0.9999, 0.25, 0.1, 0.05, 0, 0, 0},
0.0, 0.0, 0.05,
30.0, 30.0, 30.0,
{}, {}, {},
{"", ""},
{}, {}, {},
0, 0, 0, {"", ""}, {}, 0, {}, {}, {}, {}, {}, {}, {}, {}, {}, 0, {}, true}

```

Definition at line 49 of file `rtklib_rtksvr.h`.

13.236.2.2 SOLOPT_DEFAULT

const `solo_t` SOLOPT_DEFAULT

Initial value:

```

= {
    SOLF_LLH, TIMES_GPST, 1, 3,
    0, 1, 0, 0, 0, 0,
    0, 0, 0,
    {0.0, 0.0},
    " ", " ", 0
}

```

Definition at line 40 of file `rtklib_rtksvr.h`.

13.237 rtklib_rtksvr.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file rtklib_rtksvr.h
00003  * \brief rtk server functions
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
00011  * The original source code at https://github.com/tomojitakasu/RTKLIB is
00012  * released under the BSD 2-clause license with an additional exclusive clause
00013  * that does not apply here. This additional clause is reproduced below:
00014  *
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00016  * libraries necessary to execute APs on Windows. These licenses succeed to the
00017  * original ones of these software. "
00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
00020  * or included in GNSS-SDR.
00021  *
00022  * -----
00023  * Copyright (C) 2007-2013, T. Takasu
00024  * Copyright (C) 2017, Javier Arribas
00025  * Copyright (C) 2017, Carles Fernandez
00026  * All rights reserved.
00027  *
00028  * SPDX-License-Identifier: BSD-2-Clause
00029  *
00030  * -----
00031  */
00032
00033 #ifndef GNSS_SDR_RTKLIB_RKTSVR_H
00034 #define GNSS_SDR_RTKLIB_RKTSVR_H
00035
00036 #include "rtklib.h"
00037
00038
00039 const solo_t SOLOPT_DEFAULT = {
00040     /* defaults solution output options */
00041     SOLF_LLH, TIMES_GPST, 1, 3, /* posf, times, timef, timeu */
00042     0, 1, 0, 0, 0, 0, /* degf, outthead, outopt, datum, height, geoid */
00043     0, 0, 0, /* solstatic, sstat, trace */
00044     {0.0, 0.0}, /* nmeaintv */
00045     " ", " ", 0 /* separator/program name */
00046 };
00047
00048 const prcopt_t PRCOPT_DEFAULT = { /* defaults processing options */
00049     PMODE_SINGLE, 0, 2, SYS_GPS, /* mode, soltype, nf, navsys */
00050     15.0 * D2R, {}, {}, {} /* elmin, snrmask */
00051 }

```

```

00052      0, 1, 1, 1, /* sateph, modear, glomodear, bdsmodear */
00053      5, 0, 10, 1, /* maxout, minlock, minfix, armaxiter */
00054      0, 0, 0, 0, /* estion, esttrop, dynamics, tidecorr */
00055      1, 0, 0, 0, 0, /* niter, codesmooth, intpref, sbascorr, sbassatsel */
00056      0, 0, /* rovpos, refpos */
00057      {100.0, 100.0, 100.0}, /* eratio[] */
00058      {100.0, 0.003, 0.003, 0.0, 1.0}, /* err[] */
00059      {30.0, 0.03, 0.3}, /* std[] */
00060      {1e-4, 1e-3, 1e-4, 1e-1, 1e-2, 0.0}, /* prn[] */
00061      5E-12, /* sclkstab */
00062      {3.0, 0.9999, 0.25, 0.1, 0.05, 0, 0, 0}, /* thresar */
00063      0.0, 0.0, 0.05, /* elmaskar, almaskhold, thresslip */
00064      30.0, 30.0, 30.0, /* maxtdif, maxinno, maxgdop */
00065      {}, {}, {}, /* baseline, ru, rb */
00066      {"", ""}, /* anttype */
00067      {}, {}, {}, /* antdel, pcv, exsats */
00068      0, 0, 0, {"", ""}, {}, 0, {}, {}, {}, {}, {}, {}, {}, {}, {}, 0, {}, true};
00069
00070
00071 void writesolhead(stream_t *stream, const solopt_t *solopt);
00072
00073 void saveoutbuf(rtksvr_t *svr, unsigned char *buff, int n, int index);
00074
00075 void writesol(rtksvr_t *svr, int index);
00076
00077 void updatenav(nav_t *nav);
00078
00079 void updatefcfn(rtksvr_t *svr);
00080
00081 void updatesvr(rtksvr_t *svr, int ret, obs_t *obs, nav_t *nav, int sat,
00082      sbsmsg_t *sbsmsg, int index, int iobs);
00083
00084 int decoderaw(rtksvr_t *svr, int index);
00085
00086 void decodefile(rtksvr_t *svr, int index);
00087
00088 void *rtksvrthread(void *arg);
00089
00090 int rtksvrinit(rtksvr_t *svr);
00091
00092 void rtksvrfree(rtksvr_t *svr);
00093
00094 void rtksvrlock(rtksvr_t *svr);
00095
00096 void rtksvrunlock(rtksvr_t *svr);
00097
00098 int rtksvrstart(rtksvr_t *svr, int cycle, int buffsize, int *strs,
00099      char **paths, const int *formats, int navsel, char **cmds,
00100      char **rcvopts, int nmeacycle, int nmeareq,
00101      const double *nmeapos, prcopt_t *prcopt,
00102      solopt_t *solopt, stream_t *moni);
00103
00104 void rtksvrstop(rtksvr_t *svr, char **cmds);
00105
00106 int rtksvropenstr(rtksvr_t *svr, int index, int str, const char *path,
00107      const solopt_t *solopt);
00108
00109 void rtksvrclosestr(rtksvr_t *svr, int index);
00110
00111 int rtksvrostat(rtksvr_t *svr, int rcv, gtime_t *time, int *sat,
00112      double *az, double *el, int **snr, int *vsat);
00113
00114 void rtksvrsstat(rtksvr_t *svr, int *sstat, char *msg);
00115
00116
00117 #endif

```

13.238 rtklib_sbas.h File Reference

sbas functions

```
#include "rtklib.h"
```

Functions

- char * **getfield** (char *p, int pos)
- double **varfcorr** (int udre)
- double **varicorr** (int give)
- double **degfcorr** (int ai)

- int **decode_sbstype1** (const [sbmsg_t](#) *msg, [sbssat_t](#) *sbssat)
- int **decode_sbstype2** (const [sbmsg_t](#) *msg, [sbssat_t](#) *sbssat)
- int **decode_sbstype6** (const [sbmsg_t](#) *msg, [sbssat_t](#) *sbssat)
- int **decode_sbstype7** (const [sbmsg_t](#) *msg, [sbssat_t](#) *sbssat)
- int **decode_sbstype9** (const [sbmsg_t](#) *msg, [nav_t](#) *nav)
- int **decode_sbstype18** (const [sbmsg_t](#) *msg, [sbsion_t](#) *sbsion)
- int **decode_longcorr0** (const [sbmsg_t](#) *msg, int p, [sbssat_t](#) *sbssat)
- int **decode_longcorr1** (const [sbmsg_t](#) *msg, int p, [sbssat_t](#) *sbssat)
- int **decode_longcorrh** (const [sbmsg_t](#) *msg, int p, [sbssat_t](#) *sbssat)
- int **decode_sbstype24** (const [sbmsg_t](#) *msg, [sbssat_t](#) *sbssat)
- int **decode_sbstype25** (const [sbmsg_t](#) *msg, [sbssat_t](#) *sbssat)
- int **decode_sbstype26** (const [sbmsg_t](#) *msg, [sbsion_t](#) *sbsion)
- int **sbsupdatecorr** (const [sbmsg_t](#) *msg, [nav_t](#) *nav)
- void **readmsgs** (const char *file, int sel, [gtime_t](#) ts, [gtime_t](#) te, [sbs_t](#) *sbs)
- int **cmpmsgs** (const void *p1, const void *p2)
- int **sbsreadmsgt** (const char *file, int sel, [gtime_t](#) ts, [gtime_t](#) te, [sbs_t](#) *sbs)
- int **sbsreadmsg** (const char *file, int sel, [sbs_t](#) *sbs)
- void **sbsoutmsg** (FILE *fp, [sbmsg_t](#) *sbmsg)
- void **searchigp** ([gtime_t](#) time, const double *pos, const [sbsion_t](#) *ion, const [sbsigp_t](#) **igp, double *x, double *y)
- int **sbsioncorr** ([gtime_t](#) time, const [nav_t](#) *nav, const double *pos, const double *azel, double *delay, double *var)
- void **getmet** (double lat, double *met)
- double **sbstropcorr** ([gtime_t](#) time, const double *pos, const double *azel, double *var)
- int **sbslongcorr** ([gtime_t](#) time, int sat, const [sbssat_t](#) *sbssat, double *drs, double *ddts)
- int **sbsfastcorr** ([gtime_t](#) time, int sat, const [sbssat_t](#) *sbssat, double *prc, double *var)
- int **sbssatcorr** ([gtime_t](#) time, int sat, const [nav_t](#) *nav, double *rs, double *dts, double *var)
- int **sbsdecodemsg** ([gtime_t](#) time, int prn, const unsigned int *words, [sbmsg_t](#) *sbmsg)

Variables

- const int **WEEKOFFSET** = 1024
- const [sbsigpband_t](#) **IGPBAND1** [9][8]
- const [sbsigpband_t](#) **IGPBAND2** [2][5]

13.238.1 Detailed Description

sbas functions

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

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References : [1] RTCA/DO-229C, Minimum operational performance standards for global positioning system/wide area augmentation system airborne equipment, RTCA inc, November 28, 2001 [2] IS-QZSS v.1.1, Quasi-Zenith Satellite System Navigation Service Interface Specification for QZSS, Japan Aerospace Exploration Agency, July 31, 2009

Definition in file [rtklib_sbas.h](#).

13.238.2 Variable Documentation

13.238.2.1 IGPBAND1

const [sbsigpbband_t](#) IGPBAND1[9][8]

Initial value:

```
= {
    {{-180, X1, 1, 28}, {-175, X2, 29, 51}, {-170, X3, 52, 78}, {-165, X2, 79, 101},
     {-160, X3, 102, 128}, {-155, X2, 129, 151}, {-150, X3, 152, 178}, {-145, X2, 179, 201}},
    {{-140, X4, 1, 28}, {-135, X2, 29, 51}, {-130, X3, 52, 78}, {-125, X2, 79, 101},
     {-120, X3, 102, 128}, {-115, X2, 129, 151}, {-110, X3, 152, 178}, {-105, X2, 179, 201}},
    {{-100, X3, 1, 27}, {-95, X2, 28, 50}, {-90, X1, 51, 78}, {-85, X2, 79, 101},
     {-80, X3, 102, 128}, {-75, X2, 129, 151}, {-70, X3, 152, 178}, {-65, X2, 179, 201}},
    {{-60, X3, 1, 27}, {-55, X2, 28, 50}, {-50, X4, 51, 78}, {-45, X2, 79, 101},
     {-40, X3, 102, 128}, {-35, X2, 129, 151}, {-30, X3, 152, 178}, {-25, X2, 179, 201}},
    {{-20, X3, 1, 27}, {-15, X2, 28, 50}, {-10, X3, 51, 77}, {-5, X2, 78, 100},
     {0, X1, 101, 128}, {5, X2, 129, 151}, {10, X3, 152, 178}, {15, X2, 179, 201}},
    {{20, X3, 1, 27}, {25, X2, 28, 50}, {30, X3, 51, 77}, {35, X2, 78, 100},
     {40, X4, 101, 128}, {45, X2, 129, 151}, {50, X3, 152, 178}, {55, X2, 179, 201}},
    {{60, X3, 1, 27}, {65, X2, 28, 50}, {70, X3, 51, 77}, {75, X2, 78, 100},
     {80, X3, 101, 127}, {85, X2, 128, 150}, {90, X1, 151, 178}, {95, X2, 179, 201}},
    {{100, X3, 1, 27}, {105, X2, 28, 50}, {110, X3, 51, 77}, {115, X2, 78, 100},
     {120, X3, 101, 127}, {125, X2, 128, 150}, {130, X4, 151, 178}, {135, X2, 179, 201}},
    {{140, X3, 1, 27}, {145, X2, 28, 50}, {150, X3, 51, 77}, {155, X2, 78, 100},
     {160, X3, 101, 127}, {165, X2, 128, 150}, {170, X3, 151, 177}, {175, X2, 178, 200}}}
```

Definition at line 73 of file [rtklib_sbas.h](#).

13.238.2.2 IGPBAND2

const [sbsigpbband_t](#) IGPBAND2[2][5]

Initial value:

```
= {
    {{60, X5, 1, 72}, {65, X6, 73, 108}, {70, X6, 109, 144}, {75, X6, 145, 180},
     {85, X7, 181, 192}},
    {{-60, X5, 1, 72}, {-65, X6, 73, 108}, {-70, X6, 109, 144}, {-75, X6, 145, 180},
     {-85, X8, 181, 192}}}
```

Definition at line 92 of file [rtklib_sbas.h](#).

13.238.2.3 WEEKOFFSET

const int WEEKOFFSET = 1024

Definition at line 49 of file [rtklib_sbas.h](#).

13.239 rtklib_sbas.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib_sbas.h
00003  * \brief sbas functions
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *     </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
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00027  *
00028  * SPDX-License-Identifier: BSD-2-Clause
00029  *
00030  *
```

```

00031  * References :
00032  *      [1] RTCA/DO-229C, Minimum operational performance standards for global
00033  *      positioning system/wide area augmentation system airborne equipment,
00034  *      RTCA inc, November 28, 2001
00035  *      [2] IS-QZSS v.1.1, Quasi-Zenith Satellite System Navigation Service
00036  *      Interface Specification for QZSS, Japan Aerospace Exploration Agency,
00037  *      July 31, 2009
00038  *
00039  * -----
00040  */
00041
00042 #ifndef GNSS_SDR_RTKLIB_SBAS_H
00043 #define GNSS_SDR_RTKLIB_SBAS_H
00044
00045 #include "rtklib.h"
00046
00047 /* constants -----*/
00048
00049 const int WEEKOFFSET = 1024; /* gps week offset for NovAtel OEM-3 */
00050
00051 /* sbas igpp definition -----*/
00052 static const short
00053     X1[] = {-75, -65, -55, -50, -45, -40, -35, -30, -25, -20, -15, -10, -5, 0, 5, 10, 15, 20,
00054             25, 30, 35, 40, 45, 50, 55, 65, 75, 85},
00055     X2[] = {-55, -50, -45, -40, -35, -30, -25, -20, -15, -10, -5, 0, 5, 10, 15, 20, 25, 30,
00056             35, 40, 45, 50, 55},
00057     X3[] = {-75, -65, -55, -50, -45, -40, -35, -30, -25, -20, -15, -10, -5, 0, 5, 10, 15, 20,
00058             25, 30, 35, 40, 45, 50, 55, 65, 75},
00059     X4[] = {-85, -75, -65, -55, -50, -45, -40, -35, -30, -25, -20, -15, -10, -5, 0, 5, 10, 15,
00060             20, 25, 30, 35, 40, 45, 50, 55, 65, 75},
00061     X5[] = {-180, -175, -170, -165, -160, -155, -150, -145, -140, -135, -130, -125, -120, -115,
00062             -110, -105, -100, -95, -90, -85, -80, -75, -70, -65, -60, -55, -50, -45,
00063             -40, -35, -30, -25, -20, -15, -10, -5, 0, 5, 10, 15, 20, 25,
00064             30, 35, 40, 45, 50, 55, 60, 65, 70, 75, 80, 85, 90, 95,
00065             100, 105, 110, 115, 120, 125, 130, 135, 140, 145, 150, 155, 160, 165,
00066             170, 175},
00067     X6[] = {-180, -170, -160, -150, -140, -130, -120, -110, -100, -90, -80, -70, -60, -50,
00068             -40, -30, -20, -10, 0, 10, 20, 30, 40, 50, 60, 70, 80, 90,
00069             100, 110, 120, 130, 140, 150, 160, 170},
00070     X7[] = {-180, -150, -120, -90, -60, -30, 0, 30, 60, 90, 120, 150},
00071     X8[] = {-170, -140, -110, -80, -50, -20, 10, 40, 70, 100, 130, 160};
00072
00073 const sbssigband_t IGPBAND1[9][8] = { /* band 0-8 */
00074     {{-180, X1, 1, 28}, {-175, X2, 29, 51}, {-170, X3, 52, 78}, {-165, X2, 79, 101},
00075      {-160, X3, 102, 128}, {-155, X2, 129, 151}, {-150, X3, 152, 178}, {-145, X2, 179, 201}},
00076     {{-140, X4, 1, 28}, {-135, X2, 29, 51}, {-130, X3, 52, 78}, {-125, X2, 79, 101},
00077      {-120, X3, 102, 128}, {-115, X2, 129, 151}, {-110, X3, 152, 178}, {-105, X2, 179, 201}},
00078     {{-100, X3, 1, 27}, {-95, X2, 28, 50}, {-90, X1, 51, 78}, {-85, X2, 79, 101},
00079      {-80, X3, 102, 128}, {-75, X2, 129, 151}, {-70, X3, 152, 178}, {-65, X2, 179, 201}},
00080     {{-60, X3, 1, 27}, {-55, X2, 28, 50}, {-50, X4, 51, 78}, {-45, X2, 79, 101},
00081      {-40, X3, 102, 128}, {-35, X2, 129, 151}, {-30, X3, 152, 178}, {-25, X2, 179, 201}},
00082     {{-20, X3, 1, 27}, {-15, X2, 28, 50}, {-10, X3, 51, 77}, {-5, X2, 78, 100},
00083      {0, X1, 101, 128}, {5, X2, 129, 151}, {10, X3, 152, 178}, {15, X2, 179, 201}},
00084     {{20, X3, 1, 27}, {25, X2, 28, 50}, {30, X3, 51, 77}, {35, X2, 78, 100},
00085      {40, X4, 101, 128}, {45, X2, 129, 151}, {50, X3, 152, 178}, {55, X2, 179, 201}},
00086     {{60, X3, 1, 27}, {65, X2, 28, 50}, {70, X3, 51, 77}, {75, X2, 78, 100},
00087      {80, X3, 101, 127}, {85, X2, 128, 150}, {90, X1, 151, 178}, {95, X2, 179, 201}},
00088     {{100, X3, 1, 27}, {105, X2, 28, 50}, {110, X3, 51, 77}, {115, X2, 78, 100},
00089      {120, X3, 101, 127}, {125, X2, 128, 150}, {130, X4, 151, 178}, {135, X2, 179, 201}},
00090     {{140, X3, 1, 27}, {145, X2, 28, 50}, {150, X3, 51, 77}, {155, X2, 78, 100},
00091      {160, X3, 101, 127}, {165, X2, 128, 150}, {170, X3, 151, 177}, {175, X2, 178, 200}}};
00092 const sbssigband_t IGPBAND2[2][5] = { /* band 9-10 */
00093     {{60, X5, 1, 72}, {65, X6, 73, 108}, {70, X6, 109, 144}, {75, X6, 145, 180},
00094      {85, X7, 181, 192}},
00095     {{-60, X5, 1, 72}, {-65, X6, 73, 108}, {-70, X6, 109, 144}, {-75, X6, 145, 180},
00096      {-85, X8, 181, 192}}};
00097
00098
00099 char *getfield(char *p, int pos);
00100 double varfcorr(int udre);
00101 double varicorr(int give);
00102 double degfcorr(int ai);
00103
00104 int decode_sbstype1(const sbssmsg_t *msg, sbssat_t *sbssat);
00105 int decode_sbstype2(const sbssmsg_t *msg, sbssat_t *sbssat);
00106 int decode_sbstype6(const sbssmsg_t *msg, sbssat_t *sbssat);
00107 int decode_sbstype7(const sbssmsg_t *msg, sbssat_t *sbssat);
00108 int decode_sbstype9(const sbssmsg_t *msg, nav_t *nav);
00109 int decode_sbstype18(const sbssmsg_t *msg, sbssion_t *sbssion);
00110 int decode_longcorr0(const sbssmsg_t *msg, int p, sbssat_t *sbssat);
00111 int decode_longcorr1(const sbssmsg_t *msg, int p, sbssat_t *sbssat);
00112 int decode_longcorr2(const sbssmsg_t *msg, int p, sbssat_t *sbssat);
00113 int decode_sbstype24(const sbssmsg_t *msg, sbssat_t *sbssat);
00114 int decode_sbstype25(const sbssmsg_t *msg, sbssat_t *sbssat);
00115 int decode_sbstype26(const sbssmsg_t *msg, sbssion_t *sbssion);
00116
00117 int sbssupdatecorr(const sbssmsg_t *msg, nav_t *nav);

```

```

00118 void readmsgsg(const char *file, int sel, gtime_t ts, gtime_t te, sbs_t *sbs);
00119 int cmpmsgsg(const void *p1, const void *p2);
00120 int sbsreadmsgt(const char *file, int sel, gtime_t ts, gtime_t te,
00121 sbs_t *sbs);
00122 int sbsreadmsg(const char *file, int sel, sbs_t *sbs);
00123 void sbsoutmsg(FILE *fp, sbsmsg_t *sbsmsg);
00124 void searchigpp(gtime_t time, const double *pos, const sbsion_t *ion,
00125 const sbsigp_t **igp, double *x, double *y);
00126 int sbsioncorr(gtime_t time, const nav_t *nav, const double *pos,
00127 const double *azel, double *delay, double *var);
00128
00129 void getmet(double lat, double *met);
00130 double sbstropcorr(gtime_t time, const double *pos, const double *azel,
00131 double *var);
00132 int sbslongcorr(gtime_t time, int sat, const sbssat_t *sbssat,
00133 double *drs, double *ddts);
00134 int sbsfastcorr(gtime_t time, int sat, const sbssat_t *sbssat,
00135 double *prc, double *var);
00136
00137 int sbssatcorr(gtime_t time, int sat, const nav_t *nav, double *rs,
00138 double *dts, double *var);
00139 int sbsdecodemsg(gtime_t time, int prn, const unsigned int *words,
00140 sbsmsg_t *sbsmsg);
00141
00142
00143 #endif // GNSS_SDR_RTKLIB_SBAS_H

```

13.240 rtklib_solution.h File Reference

solution functions headers

```
#include "rtklib.h"
```

Macros

- #define **COMMENTH** "%" /* comment line indicator for solution */
- #define **MSG_DISCONN** "\$_DISCONNECT\r\n" /* disconnect message */

Functions

- const char * **opt2sep** (const [solopt_t](#) *opt)
- int **tonum** (char *buff, const char *sep, double *v)
- double **sqvar** (double covar)
- double **dmm2deg** (double dmm)
- void **septime** (double t, double *t1, double *t2, double *t3)
- void **soltocov** (const [sol_t](#) *sol, double *P)
- void **covtosol** (const double *P, [sol_t](#) *sol)
- int **decode_nmearmc** (char **val, int n, [sol_t](#) *sol)
- int **decode_nmeagga** (char **val, int n, [sol_t](#) *sol)
- int **decode_nmea** (char *buff, [sol_t](#) *sol)
- char * **decode_soltime** (char *buff, const [solopt_t](#) *opt, [gtime_t](#) *time)
- int **decode_solxyz** (char *buff, const [solopt_t](#) *opt, [sol_t](#) *sol)
- int **decode_solllh** (char *buff, const [solopt_t](#) *opt, [sol_t](#) *sol)
- int **decode_solenu** (char *buff, const [solopt_t](#) *opt, [sol_t](#) *sol)
- int **decode_solgsi** (char *buff, const [solopt_t](#) *opt, [sol_t](#) *sol)
- int **decode_solpos** (char *buff, const [solopt_t](#) *opt, [sol_t](#) *sol)
- void **decode_refpos** (char *buff, const [solopt_t](#) *opt, double *rb)
- int **decode_sol** (char *buff, const [solopt_t](#) *opt, [sol_t](#) *sol, double *rb)
- void **decode_solopt** (char *buff, [solopt_t](#) *opt)
- void **readsolopt** (FILE *fp, [solopt_t](#) *opt)
- int **inputsol** (unsigned char data, [gtime_t](#) ts, [gtime_t](#) te, double tint, int qflag, const [solopt_t](#) *opt, [solbuf_t](#) *solbuf)
- int **readsoldata** (FILE *fp, [gtime_t](#) ts, [gtime_t](#) te, double tint, int qflag, const [solopt_t](#) *opt, [solbuf_t](#) *solbuf)
- int **cmpsol** (const void *p1, const void *p2)

- int **sort_solbuf** (solbuf_t *solbuf)
- int **readsolt** (char *files[], int nfile, gtime_t ts, gtime_t te, double tint, int qflag, solbuf_t *solbuf)
- int **readsol** (char *files[], int nfile, solbuf_t *sol)
- int **addsolt** (solbuf_t *solbuf, const sol_t *sol)
- sol_t * **getsol** (solbuf_t *solbuf, int index)
- void **initsolbuf** (solbuf_t *solbuf, int cyclic, int nmax)
- void **freesolbuf** (solbuf_t *solbuf)
- void **freesolstatbuf** (solstatbuf_t *solstatbuf)
- int **cmpsolstat** (const void *p1, const void *p2)
- int **sort_solstat** (solstatbuf_t *statbuf)
- int **decode_solstat** (char *buff, solstat_t *stat)
- void **addsoltstat** (solstatbuf_t *statbuf, const solstat_t *stat)
- int **readsoltatdata** (FILE *fp, gtime_t ts, gtime_t te, double tint, solstatbuf_t *statbuf)
- int **readsoltatt** (char *files[], int nfile, gtime_t ts, gtime_t te, double tint, solstatbuf_t *statbuf)
- int **readsoltat** (char *files[], int nfile, solstatbuf_t *statbuf)
- int **outecef** (unsigned char *buff, const char *s, const sol_t *sol, const solopt_t *opt)
- int **outpos** (unsigned char *buff, const char *s, const sol_t *sol, const solopt_t *opt)
- int **outenu** (unsigned char *buff, const char *s, const sol_t *sol, const double *rb, const solopt_t *opt)
- int **outnmea_rmc** (unsigned char *buff, const sol_t *sol)
- int **outnmea_gga** (unsigned char *buff, const sol_t *sol)
- int **outnmea_gsa** (unsigned char *buff, const sol_t *sol, const ssat_t *ssat)
- int **outnmea_gsv** (unsigned char *buff, const sol_t *sol, const ssat_t *ssat)
- int **outprcopts** (unsigned char *buff, const prcopt_t *opt)
- int **outsolheads** (unsigned char *buff, const solopt_t *opt)
- int **outsols** (unsigned char *buff, const sol_t *sol, const double *rb, const solopt_t *opt)
- int **outsolsexs** (unsigned char *buff, const sol_t *sol, const ssat_t *ssat, const solopt_t *opt)
- void **outprcopt** (FILE *fp, const prcopt_t *opt)
- void **outsolhead** (FILE *fp, const solopt_t *opt)
- void **outsol** (FILE *fp, const sol_t *sol, const double *rb, const solopt_t *opt)
- void **outsolsex** (FILE *fp, const sol_t *sol, const ssat_t *ssat, const solopt_t *opt)

13.240.1 Detailed Description

solution functions headers

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

This is a derived work from RTKLIB <http://www.rtklib.com/> The original source code at <https://github.com/tomojitakasu/RTKLIB> is released under the BSD 2-clause license with an additional exclusive clause that does not apply here. This additional clause is reproduced below:

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Definition in file [rtklib_solution.h](#).

13.241 rtklib_solution.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file rtklib_solution.h
00003  * \brief solution functions headers
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
00011  * The original source code at https://github.com/tomojitakasu/RTKLIB is
00012  * released under the BSD 2-clause license with an additional exclusive clause
00013  * that does not apply here. This additional clause is reproduced below:
00014  *
00015  * " The software package includes some companion executive binaries or shared
00016  * libraries necessary to execute APs on Windows. These licenses succeed to the
00017  * original ones of these software. "
00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
00020  * or included in GNSS-SDR.
00021  *
00022  * -----
00023  * Copyright (C) 2007-2013, T. Takasu
00024  * Copyright (C) 2017, Javier Arribas
00025  * Copyright (C) 2017, Carles Fernandez
00026  * All rights reserved.
00027  *
00028  * SPDX-License-Identifier: BSD-2-Clause
00029  * -----
00030  */
00031
00032 #ifndef GNSS_SDR_RTKLIB_SOLUTION_H
00033 #define GNSS_SDR_RTKLIB_SOLUTION_H
00034
00035 #include "rtklib.h"
00036
00037 /** \addtogroup PVT
00038  * \{ */
00039 /** \addtogroup RTKLIB_Library
00040  * \{ */
00041
00042 #define COMMENTH "%" /* comment line indicator for solution */
00043 #define MSG_DISCONNECT "$_DISCONNECT\r\n" /* disconnect message */
00044
00045 const char *opt2sep(const solopt_t *opt);
00046
00047 int tonum(char *buff, const char *sep, double *v);
00048
00049 double sqvar(double covar);
00050
00051 double dmm2deg(double dmm);
00052
00053 void septime(double t, double *t1, double *t2, double *t3);
00054
00055 void soltocov(const sol_t *sol, double *P);
00056
00057 void covtosol(const double *P, sol_t *sol);
00058
00059 int decode_nmearmc(char **val, int n, sol_t *sol);
00060
00061 int decode_nmeagga(char **val, int n, sol_t *sol);
00062
00063 int decode_nmea(char *buff, sol_t *sol);
00064
00065 char *decode_soltime(char *buff, const solopt_t *opt, gtime_t *time);
00066
00067 int decode_solxyz(char *buff, const solopt_t *opt, sol_t *sol);
00068
00069 int decode_solllh(char *buff, const solopt_t *opt, sol_t *sol);
00070
00071 int decode_solenu(char *buff, const solopt_t *opt, sol_t *sol);
00072
00073 int decode_solgsi(char *buff, const solopt_t *opt, sol_t *sol);
00074
00075 int decode_solpos(char *buff, const solopt_t *opt, sol_t *sol);
00076
00077 void decode_refpos(char *buff, const solopt_t *opt, double *rb);
00078
00079 int decode_sol(char *buff, const solopt_t *opt, sol_t *sol, double *rb);
00080
00081 void decode_solopt(char *buff, solopt_t *opt);
00082
00083

```



```
00084 void readsolopt(FILE *fp, solopt_t *opt);
00085
00086 int inputsol(unsigned char data, gtime_t ts, gtime_t te, double tint,
00087             int qflag, const solopt_t *opt, solbuf_t *solbuf);
00088
00089 int readsoldata(FILE *fp, gtime_t ts, gtime_t te, double tint, int qflag,
00090                const solopt_t *opt, solbuf_t *solbuf);
00091
00092 int cmpsol(const void *p1, const void *p2);
00093
00094 int sort_solbuf(solbuf_t *solbuf);
00095
00096 int readsolt(char *files[], int nfile, gtime_t ts, gtime_t te,
00097             double tint, int qflag, solbuf_t *solbuf);
00098
00099 int readsol(char *files[], int nfile, solbuf_t *sol);
00100
00101 int addsol(solbuf_t *solbuf, const sol_t *sol);
00102
00103 sol_t *getsol(solbuf_t *solbuf, int index);
00104
00105 void initsolbuf(solbuf_t *solbuf, int cyclic, int nmax);
00106
00107 void freesolbuf(solbuf_t *solbuf);
00108
00109 void freesolstatbuf(solstatbuf_t *solstatbuf);
00110
00111 int cmpsolstat(const void *p1, const void *p2);
00112
00113 int sort_solstat(solstatbuf_t *statbuf);
00114
00115 int decode_solstat(char *buff, solstat_t *stat);
00116
00117 void addsolstat(solstatbuf_t *statbuf, const solstat_t *stat);
00118
00119 int readsolstatdata(FILE *fp, gtime_t ts, gtime_t te, double tint,
00120                    solstatbuf_t *statbuf);
00121
00122 int readsolstatt(char *files[], int nfile, gtime_t ts, gtime_t te,
00123                 double tint, solstatbuf_t *statbuf);
00124
00125 int readsolstat(char *files[], int nfile, solstatbuf_t *statbuf);
00126
00127 int outecef(unsigned char *buff, const char *s, const sol_t *sol,
00128            const solopt_t *opt);
00129
00130 int outpos(unsigned char *buff, const char *s, const sol_t *sol, const solopt_t *opt);
00131
00132 int outenu(unsigned char *buff, const char *s, const sol_t *sol,
00133            const double *rb, const solopt_t *opt);
00134
00135 int outnmea_rmc(unsigned char *buff, const sol_t *sol);
00136
00137 int outnmea_gga(unsigned char *buff, const sol_t *sol);
00138
00139 int outnmea_gsa(unsigned char *buff, const sol_t *sol,
00140                const ssat_t *ssat);
00141
00142 int outnmea_gsv(unsigned char *buff, const sol_t *sol,
00143                const ssat_t *ssat);
00144
00145 int outprcopts(unsigned char *buff, const prcopt_t *opt);
00146
00147 int outsolheads(unsigned char *buff, const solopt_t *opt);
00148
00149 int outsols(unsigned char *buff, const sol_t *sol, const double *rb,
00150            const solopt_t *opt);
00151
00152 int outsolexs(unsigned char *buff, const sol_t *sol, const ssat_t *ssat,
00153            const solopt_t *opt);
00154
00155 void outprcopt(FILE *fp, const prcopt_t *opt);
00156
00157 void outsolhead(FILE *fp, const solopt_t *opt);
00158
00159 void outsol(FILE *fp, const sol_t *sol, const double *rb,
00160            const solopt_t *opt);
00161
00162 void outsolex(FILE *fp, const sol_t *sol, const ssat_t *ssat,
00163            const solopt_t *opt);
00164
00165
00166 /** \} */
00167 /** \} */
00168 #endif // GNSS_SDR_RTKLIB_SOLUTION_H
```

13.242 rtklib_stream.h File Reference

streaming functions

```
#include "rtklib.h"
```

Macros

- #define [TINTACT](#) 200 /* period for stream active (ms) */
- #define [SERIBUFFSIZE](#) 4096 /* serial buffer size (bytes) */
- #define [TIMETAGH_LEN](#) 64 /* time tag file header length */
- #define [MAXCLI](#) 32 /* max client connection for tcp svr */
- #define [MAXSTATMSG](#) 32 /* max length of status message */
- #define [VER_RTKLIB](#) "2.4.2"
- #define [NTRIP_AGENT](#) "RTKLIB/" VER_RTKLIB
- #define [NTRIP_CLI_PORT](#) 2101 /* default ntrip-client connection port */
- #define [NTRIP_SVR_PORT](#) 80 /* default ntrip-server connection port */
- #define [NTRIP_MAXRSP](#) 32768 /* max size of ntrip response */
- #define [NTRIP_MAXSTR](#) 256 /* max length of mountpoint string */
- #define [NTRIP_RSP_OK_CLI](#) "ICY 200 OK\r\n" /* ntrip response: client */
- #define [NTRIP_RSP_OK_SVR](#) "OK\r\n" /* ntrip response: server */
- #define [NTRIP_RSP_SRCTBL](#) "SOURCETABLE 200 OK\r\n" /* ntrip response: source table */
- #define [NTRIP_RSP_TBLEND](#) "ENDSOURCETABLE"
- #define [NTRIP_RSP_HTTP](#) "HTTP/" /* ntrip response: http */
- #define [NTRIP_RSP_ERROR](#) "ERROR" /* ntrip response: error */
- #define [FTP_CMD](#) "wget" /* ftp/http command */
- #define [FTP_TIMEOUT](#) 30 /* ftp/http timeout (s) */

Functions

- [serial_t](#) * [openserial](#) (const char *path, int mode, char *msg)
- void [closeserial](#) ([serial_t](#) *serial)
- int [readserial](#) ([serial_t](#) *serial, unsigned char *buff, int n, char *msg)
- int [writeserial](#) ([serial_t](#) *serial, unsigned char *buff, int n, char *msg)
- int [stateserial](#) ([serial_t](#) *serial)
- int [openfile_](#) ([file_t](#) *file, [gtime_t](#) time, char *msg)
- void [closefile_](#) ([file_t](#) *file)
- [file_t](#) * [openfile](#) (const char *path, int mode, char *msg)
- void [closefile](#) ([file_t](#) *file)
- void [swapfile](#) ([file_t](#) *file, [gtime_t](#) time, char *msg)
- void [swapclose](#) ([file_t](#) *file)
- int [statefile](#) ([file_t](#) *file)
- int [readfile](#) ([file_t](#) *file, unsigned char *buff, int nmax, char *msg)
- int [writefile](#) ([file_t](#) *file, unsigned char *buff, int n, char *msg)
- void [syncfile](#) ([file_t](#) *file1, [file_t](#) *file2)
- void [decodetcp](#) (const char *path, char *addr, char *port, char *user, char *passwd, char *mntpnt, char *str)
- int [errsock](#) ()
- int [setsock](#) (socket_t sock, char *msg)
- socket_t [accept_nb](#) (socket_t sock, struct sockaddr *addr, socklen_t *len)
- int [connect_nb](#) (socket_t sock, struct sockaddr *addr, socklen_t len)
- int [recv_nb](#) (socket_t sock, unsigned char *buff, int n)
- int [send_nb](#) (socket_t sock, unsigned char *buff, int n)
- int [gentcp](#) ([tcp_t](#) *tcp, int type, char *msg)
- void [discontcp](#) ([tcp_t](#) *tcp, int tcon)
- [tcpsvr_t](#) * [opentcpsvr](#) (const char *path, char *msg)

- void **closetcpsvr** ([tcpsvr_t](#) *tcpsvr)
- void **updatetcpsvr** ([tcpsvr_t](#) *tcpsvr, char *msg)
- int **accsock** ([tcpsvr_t](#) *tcpsvr, char *msg)
- int **waittcpsvr** ([tcpsvr_t](#) *tcpsvr, char *msg)
- int **readtcpsvr** ([tcpsvr_t](#) *tcpsvr, unsigned char *buff, int n, char *msg)
- int **writetcpsvr** ([tcpsvr_t](#) *tcpsvr, unsigned char *buff, int n, char *msg)
- int **statetcpsvr** ([tcpsvr_t](#) *tcpsvr)
- int **consock** ([tcpcli_t](#) *tcpcli, char *msg)
- [tcpcli_t](#) * **opentcpcli** (const char *path, char *msg)
- void **closetcpcli** ([tcpcli_t](#) *tcpcli)
- int **waittcpcli** ([tcpcli_t](#) *tcpcli, char *msg)
- int **readtcpcli** ([tcpcli_t](#) *tcpcli, unsigned char *buff, int n, char *msg)
- int **writetcpcli** ([tcpcli_t](#) *tcpcli, unsigned char *buff, int n, char *msg)
- int **statetcpcli** ([tcpcli_t](#) *tcpcli)
- int **encbase64** (char *str, const unsigned char *byte, int n)
- int **reqntrip_s** ([ntrip_t](#) *ntrip, char *msg)
- int **reqntrip_c** ([ntrip_t](#) *ntrip, char *msg)
- int **rspntrip_s** ([ntrip_t](#) *ntrip, char *msg)
- int **rspntrip_c** ([ntrip_t](#) *ntrip, char *msg)
- int **waitntrip** ([ntrip_t](#) *ntrip, char *msg)
- [ntrip_t](#) * **openntrip** (const char *path, int type, char *msg)
- void **closentrip** ([ntrip_t](#) *ntrip)
- int **readntrip** ([ntrip_t](#) *ntrip, unsigned char *buff, int n, char *msg)
- int **writentrip** ([ntrip_t](#) *ntrip, unsigned char *buff, int n, char *msg)
- int **statentrip** ([ntrip_t](#) *ntrip)
- void **decodeftppath** (const char *path, char *addr, char *file, char *user, char *passwd, int *topts)
- [gtime_t](#) **nextdlttime** (const int *topts, int stat)
- void * **ftpthread** (void *arg)
- [ftp_t](#) * **openftp** (const char *path, int type, char *msg)
- void **closeftp** ([ftp_t](#) *ftp)
- int **readftp** ([ftp_t](#) *ftp, unsigned char *buff, int n, char *msg)
- int **stateftp** ([ftp_t](#) *ftp)
- void **strinitcom** ()
- void **strinit** ([stream_t](#) *stream)
- int **stropen** ([stream_t](#) *stream, int type, int mode, const char *path)
- void **strclose** ([stream_t](#) *stream)
- void **strsync** ([stream_t](#) *stream1, [stream_t](#) *stream2)
- void **strlock** ([stream_t](#) *stream)
- void **strunlock** ([stream_t](#) *stream)
- int **strread** ([stream_t](#) *stream, unsigned char *buff, int n)
- int **strwrite** ([stream_t](#) *stream, unsigned char *buff, int n)
- int **strstat** ([stream_t](#) *stream, char *msg)
- void **strsum** ([stream_t](#) *stream, int *inb, int *inr, int *outb, int *outr)
- void **strsetopt** (const int *opt)
- void **strsettimeout** ([stream_t](#) *stream, int inactive_timeout, int tirecon)
- void **strsetdir** (const char *dir)
- void **strsetproxy** (const char *addr)
- [gtime_t](#) **strgettime** ([stream_t](#) *stream)
- void **strsendnmea** ([stream_t](#) *stream, const double *pos)
- int **gen_hex** (const char *msg, unsigned char *buff)
- void **strsendcmd** ([stream_t](#) *str, const char *cmd)

13.242.1 Detailed Description

streaming functions

Authors

- 2007-2013, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

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Definition in file [rtklib_stream.h](#).

13.242.2 Macro Definition Documentation

13.242.2.1 FTP_CMD

```
#define FTP_CMD "wget" /* ftp/http command */
```

Definition at line 58 of file [rtklib_stream.h](#).

13.242.2.2 FTP_TIMEOUT

```
#define FTP_TIMEOUT 30 /* ftp/http timeout (s) */
```

Definition at line 59 of file [rtklib_stream.h](#).

13.242.2.3 MAXCLI

```
#define MAXCLI 32 /* max client connection for tcp svr */
```

Definition at line 42 of file [rtklib_stream.h](#).

13.242.2.4 MAXSTATMSG

```
#define MAXSTATMSG 32 /* max length of status message */
```

Definition at line 43 of file [rtklib_stream.h](#).

13.242.2.5 NTRIP_AGENT

```
#define NTRIP_AGENT "RTKLIB/" VER_RTKLIB
```

Definition at line 46 of file [rtklib_stream.h](#).

13.242.2.6 NTRIP_CLI_PORT

```
#define NTRIP_CLI_PORT 2101 /* default ntrip-client connection port */
```

Definition at line 47 of file [rtklib_stream.h](#).

13.242.2.7 NTRIP_MAXRSP

```
#define NTRIP_MAXRSP 32768 /* max size of ntrip response */
```

Definition at line 49 of file [rtklib_stream.h](#).

13.242.2.8 NTRIP_MAXSTR

```
#define NTRIP_MAXSTR 256 /* max length of mountpoint string */
```

Definition at line 50 of file [rtklib_stream.h](#).

13.242.2.9 NTRIP_RSP_ERROR

```
#define NTRIP_RSP_ERROR "ERROR" /* ntrip response: error */
```

Definition at line 56 of file [rtklib_stream.h](#).

13.242.2.10 NTRIP_RSP_HTTP

```
#define NTRIP_RSP_HTTP "HTTP/" /* ntrip response: http */
```

Definition at line 55 of file [rtklib_stream.h](#).

13.242.2.11 NTRIP_RSP_OK_CLI

```
#define NTRIP_RSP_OK_CLI "ICY 200 OK\r\n" /* ntrip response: client */
```

Definition at line 51 of file [rtklib_stream.h](#).

13.242.2.12 NTRIP_RSP_OK_SVR

```
#define NTRIP_RSP_OK_SVR "OK\r\n" /* ntrip response: server */
```

Definition at line 52 of file [rtklib_stream.h](#).

13.242.2.13 NTRIP_RSP_SRCTBL

```
#define NTRIP_RSP_SRCTBL "SOURCETABLE 200 OK\r\n" /* ntrip response: source table */
```

Definition at line 53 of file [rtklib_stream.h](#).

13.242.2.14 NTRIP_RSP_TBLEND

```
#define NTRIP_RSP_TBLEND "ENDSOURCETABLE"
```

Definition at line 54 of file [rtklib_stream.h](#).

13.242.2.15 NTRIP_SVR_PORT

```
#define NTRIP_SVR_PORT 80 /* default ntrip-server connection port */
```

Definition at line 48 of file [rtklib_stream.h](#).

13.242.2.16 SERIBUFFSIZE

```
#define SERIBUFFSIZE 4096 /* serial buffer size (bytes) */
```

Definition at line 40 of file [rtklib_stream.h](#).

13.242.2.17 TIMETAGH_LEN

```
#define TIMETAGH_LEN 64 /* time tag file header length */
```

Definition at line 41 of file [rtklib_stream.h](#).

13.242.2.18 TINTACT

```
#define TINTACT 200 /* period for stream active (ms) */
```

Definition at line 39 of file [rtklib_stream.h](#).

13.242.2.19 VER_RTKLIB

```
#define VER_RTKLIB "2.4.2"
```

Definition at line 45 of file [rtklib_stream.h](#).

13.243 rtklib_stream.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file rtklib_stream.h
00003  * \brief streaming functions
00004  * \authors <ul>
00005  *         <li> 2007-2013, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
00011  * The original source code at https://github.com/tomojitakasu/RTKLIB is
00012  * released under the BSD 2-clause license with an additional exclusive clause
00013  * that does not apply here. This additional clause is reproduced below:
00014  *
00015  * " The software package includes some companion executive binaries or shared
00016  * libraries necessary to execute APs on Windows. These licenses succeed to the
00017  * original ones of these software. "
00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
00020  * or included in GNSS-SDR.
00021  *
00022  * -----
00023  * Copyright (C) 2007-2013, T. Takasu
00024  * Copyright (C) 2017, Javier Arribas
00025  * Copyright (C) 2017, Carles Fernandez
00026  * All rights reserved.
00027  *
00028  * SPDX-License-Identifier: BSD-2-Clause
00029  *
00030  *-----*/
00031
00032 #ifndef GNSS_SDR_RTKLIB_STREAM_H
00033 #define GNSS_SDR_RTKLIB_STREAM_H
00034
00035 #include "rtklib.h"
00036
00037 /* constants -----*/
00038
00039 #define TINTACT 200 /* period for stream active (ms) */
00040 #define SERIBUFFSIZE 4096 /* serial buffer size (bytes) */
00041 #define TIMETAGH_LEN 64 /* time tag file header length */
00042 #define MAXCLI 32 /* max client connection for tcp svr */
00043 #define MAXSTATMSG 32 /* max length of status message */
00044
00045 #define VER_RTKLIB "2.4.2"
00046 #define NTRIP_AGENT "RTKLIB/" VER_RTKLIB
00047 #define NTRIP_CLI_PORT 2101 /* default ntrip-client connection port */
00048 #define NTRIP_SVR_PORT 80 /* default ntrip-server connection port */
00049 #define NTRIP_MAXRSP 32768 /* max size of ntrip response */
00050 #define NTRIP_MAXSTR 256 /* max length of mountpoint string */
00051 #define NTRIP_RSP_OK_CLI "ICY 200 OK\r\n" /* ntrip response: client */
00052 #define NTRIP_RSP_OK_SVR "OK\r\n" /* ntrip response: server */
00053 #define NTRIP_RSP_SRCTBL "SOURCETABLE 200 OK\r\n" /* ntrip response: source table */
00054 #define NTRIP_RSP_TBLEND "ENDSOURCETABLE"
00055 #define NTRIP_RSP_HTTP "HTTP/" /* ntrip response: http */
00056 #define NTRIP_RSP_ERROR "ERROR" /* ntrip response: error */
00057
00058 #define FTP_CMD "wget" /* ftp/http command */
00059 #define FTP_TIMEOUT 30 /* ftp/http timeout (s) */
00060
00061 serial_t *openserial(const char *path, int mode, char *msg);
00062
00063 void closeserial(serial_t *serial);
00064
00065 int readserial(serial_t *serial, unsigned char *buff, int n, char *msg);
00066
00067 int writeserial(serial_t *serial, unsigned char *buff, int n, char *msg);
00068
00069 int stateserial(serial_t *serial);
00070
00071 int openfile_(file_t *file, gtime_t time, char *msg);
00072
00073 void closefile_(file_t *file);
00074
00075 file_t *openfile(const char *path, int mode, char *msg);
00076
00077 void closefile(file_t *file);
00078
00079 void swapfile(file_t *file, gtime_t time, char *msg);
00080
00081 void swapclose(file_t *file);
00082
00083

```

```
00084 int statefile(file_t *file);
00085
00086 int readfile(file_t *file, unsigned char *buff, int nmax, char *msg);
00087
00088 int writefile(file_t *file, unsigned char *buff, int n, char *msg);
00089
00090 void syncfile(file_t *file1, file_t *file2);
00091
00092 void decodetcppath(const char *path, char *addr, char *port, char *user,
00093     char *passwd, char *mntpnt, char *str);
00094
00095 int errsock();
00096
00097 int setsock(socket_t sock, char *msg);
00098
00099 socket_t accept_nb(socket_t sock, struct sockaddr *addr, socklen_t *len);
00100
00101 int connect_nb(socket_t sock, struct sockaddr *addr, socklen_t len);
00102
00103 int recv_nb(socket_t sock, unsigned char *buff, int n);
00104
00105 int send_nb(socket_t sock, unsigned char *buff, int n);
00106
00107 int gentcp(tcp_t *tcp, int type, char *msg);
00108
00109 void discontcp(tcp_t *tcp, int tcon);
00110
00111 tcpsvr_t *opentcpsvr(const char *path, char *msg);
00112
00113 void closetcpsvr(tcpsvr_t *tcpsvr);
00114
00115 void updatetcpsvr(tcpsvr_t *tcpsvr, char *msg);
00116
00117 int accsock(tcpsvr_t *tcpsvr, char *msg);
00118
00119 int waittcpsvr(tcpsvr_t *tcpsvr, char *msg);
00120
00121 int readtcpsvr(tcpsvr_t *tcpsvr, unsigned char *buff, int n, char *msg);
00122
00123 int writetcpsvr(tcpsvr_t *tcpsvr, unsigned char *buff, int n, char *msg);
00124
00125 int statetcpsvr(tcpsvr_t *tcpsvr);
00126
00127 int consock(tcpcli_t *tcpcli, char *msg);
00128
00129 tcpcli_t *opentcpcli(const char *path, char *msg);
00130
00131 void closetcpcli(tcpcli_t *tcpcli);
00132
00133 int waittcpcli(tcpcli_t *tcpcli, char *msg);
00134
00135 int readtcpcli(tcpcli_t *tcpcli, unsigned char *buff, int n, char *msg);
00136
00137 int writetcpcli(tcpcli_t *tcpcli, unsigned char *buff, int n, char *msg);
00138
00139 int statetcpcli(tcpcli_t *tcpcli);
00140
00141 int encbase64(char *str, const unsigned char *byte, int n);
00142
00143 int reqntrip_s(ntrip_t *ntrip, char *msg);
00144
00145 int reqntrip_c(ntrip_t *ntrip, char *msg);
00146
00147 int rspntrip_s(ntrip_t *ntrip, char *msg);
00148
00149 int rspntrip_c(ntrip_t *ntrip, char *msg);
00150
00151 int waitntrip(ntrip_t *ntrip, char *msg);
00152
00153 ntrip_t *openntrip(const char *path, int type, char *msg);
00154
00155 void closentrip(ntrip_t *ntrip);
00156
00157 int readntrip(ntrip_t *ntrip, unsigned char *buff, int n, char *msg);
00158
00159 int writentrip(ntrip_t *ntrip, unsigned char *buff, int n, char *msg);
00160
00161 int statentrip(ntrip_t *ntrip);
00162
00163 void decodeftppath(const char *path, char *addr, char *file, char *user,
00164     char *passwd, int *topts);
00165
00166 gtime_t nextdltime(const int *topts, int stat);
00167
00168 void *ftpthread(void *arg);
00169
00170 ftp_t *openftp(const char *path, int type, char *msg);
```

```

00171
00172 void closeftp(ftp_t *ftp);
00173
00174 int readftp(ftp_t *ftp, unsigned char *buff, int n, char *msg);
00175
00176 int stateftp(ftp_t *ftp);
00177
00178 void strinitcom();
00179
00180 void strinit(stream_t *stream);
00181
00182 int stropen(stream_t *stream, int type, int mode, const char *path);
00183
00184 void strclose(stream_t *stream);
00185
00186 void strsync(stream_t *stream1, stream_t *stream2);
00187
00188 void strlock(stream_t *stream);
00189
00190 void strunlock(stream_t *stream);
00191
00192 int strread(stream_t *stream, unsigned char *buff, int n);
00193
00194 int strwrite(stream_t *stream, unsigned char *buff, int n);
00195
00196 int strstat(stream_t *stream, char *msg);
00197
00198 void strsum(stream_t *stream, int *inb, int *inr, int *outb, int *outr);
00199
00200 void strsetopt(const int *opt);
00201
00202 void strsettimeout(stream_t *stream, int inactive_timeout, int tirecon);
00203
00204 void strsetdir(const char *dir);
00205
00206 void strsetproxy(const char *addr);
00207
00208 gtime_t strgettime(stream_t *stream);
00209
00210 void strsendnmea(stream_t *stream, const double *pos);
00211
00212 int gen_hex(const char *msg, unsigned char *buff);
00213
00214 void strsendcmd(stream_t *str, const char *cmd);
00215
00216
00217 #endif

```

13.244 rtklib_tides.h File Reference

Tidal displacement corrections.

```
#include "rtklib.h"
```

Functions

- void **tide_pl** (const double *eu, const double *rp, double Gmp, const double *pos, double *dr)
- void **tide_solid** (const double *rsun, const double *rmoon, const double *pos, const double *E, double gmst, int opt, double *dr)
- void **tide_oload** (gtime_t tut, const double *odisp, double *denu)
- void **iers_mean_pole** (gtime_t tut, double *xp_bar, double *yp_bar)
- void **tide_pole** (gtime_t tut, const double *pos, const double *erpv, double *denu)
- void **tidedisp** (gtime_t tutc, const double *rr, int opt, const erp_t *erp, const double *odisp, double *dr)

Variables

- const double **GME** = 3.986004415E+14
- const double **GMS** = 1.327124E+20
- const double **GMM** = 4.902801E+12

13.244.1 Detailed Description

Tidal displacement corrections.

Authors

- 2015, T. Takasu
- 2017, Javier Arribas
- 2017, Carles Fernandez

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References: [1] D.D.McCarthy, IERS Technical Note 21, IERS Conventions 1996, July 1996 [2] D.D.McCarthy and G.Petit, IERS Technical Note 32, IERS Conventions 2003, November 2003 [3] D.A.Vallado, Fundamentals of Astrodynamics and Applications 2nd ed, Space Technology Library, 2004 [4] J.Kouba, A Guide to using International GNSS Service (IGS) products, May 2009 [5] G.Petit and B.Luzum (eds), IERS Technical Note No. 36, IERS

13.244.1.1 Conventions (2010), 2010

Definition in file [rtklib_tides.h](#).

13.244.2 Variable Documentation**13.244.2.1 GME**

```
const double GME = 3.986004415E+14
```

Definition at line 51 of file [rtklib_tides.h](#).

13.244.2.2 GMM

```
const double GMM = 4.902801E+12
```

Definition at line 53 of file [rtklib_tides.h](#).

13.244.2.3 GMS

```
const double GMS = 1.327124E+20
```

Definition at line 52 of file [rtklib_tides.h](#).

13.245 rtklib_tides.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib_tides.h
00003  * \brief Tidal displacement corrections
00004  * \authors <ul>
00005  *         <li> 2015, T. Takasu
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017, Carles Fernandez
00008  *         </ul>
00009  *
00010  * This is a derived work from RTKLIB http://www.rtklib.com/
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00018  *
00019  * Neither the executive binaries nor the shared libraries are required by, used
00020  * or included in GNSS-SDR.
00021  *
00022  * -----
```

```

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00026 * All rights reserved.
00027 *
00028 * SPDX-License-Identifier: BSD-2-Clause
00029 *
00030 * References:
00031 * [1] D.D.McCarthy, IERS Technical Note 21, IERS Conventions 1996, July 1996
00032 * [2] D.D.McCarthy and G.Petit, IERS Technical Note 32, IERS Conventions
00033 * 2003, November 2003
00034 * [3] D.A.Vallado, Fundamentals of Astrodynamics and Applications 2nd ed,
00035 * Space Technology Library, 2004
00036 * [4] J.Kouba, A Guide to using International GNSS Service (IGS) products,
00037 * May 2009
00038 * [5] G.Petit and B.Luzum (eds), IERS Technical Note No. 36, IERS
00039 * Conventions (2010), 2010
00040 * -----
00041 */
00042
00043
00044 #ifndef GNSS_SDR_RTKLIB_TIDES_H
00045 #define GNSS_SDR_RTKLIB_TIDES_H
00046
00047
00048 #include "rtklib.h"
00049
00050
00051 const double GME = 3.986004415E+14; /* earth gravitational constant */
00052 const double GMS = 1.327124E+20; /* sun gravitational constant */
00053 const double GMM = 4.902801E+12; /* moon gravitational constant */
00054
00055 void tide_pl(const double *eu, const double *rp, double GMp,
00056             const double *pos, double *dr);
00057
00058 void tide_solid(const double *rsun, const double *rmoon,
00059                const double *pos, const double *E, double gmst, int opt,
00060                double *dr);
00061
00062 void tide_oload(gtime_t tut, const double *odisp, double *denu);
00063
00064 void iers_mean_pole(gtime_t tut, double *xp_bar, double *yp_bar);
00065
00066
00067 void tide_pole(gtime_t tut, const double *pos, const double *erpv,
00068               double *denu);
00069
00070 void tidedisp(gtime_t tutc, const double *rr, int opt, const erp_t *erp,
00071              const double *odisp, double *dr);
00072 #endif

```

13.246 sensor_data_aggregator.h File Reference

Aggregates sensor samples from gnu radio stream tags into typed lists for easy access.

```

#include "sensor_data_source_configuration.h"
#include "sensor_identifier.h"
#include <gnuradio/tags.h>
#include <cstdint>
#include <gnss_block_interface.h>
#include <vector>

```

Classes

- struct [SensorDataSample< DataType >](#)
- class [SensorDataAggregator](#)

13.246.1 Detailed Description

Aggregates sensor samples from gnu radio stream tags into typed lists for easy access.

Author

Victor Castillo, 2024. victorcastilloaguero(at)gmail.com

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Copyright (C) 2024-2025 (see AUTHORS file for a list of contributors) SPDX-License-Identifier: GPL-3.0-or-later
Definition in file [sensor_data_aggregator.h](#).

13.247 sensor_data_aggregator.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file sensor_data_aggregator.h
00003  * \brief Aggregates sensor samples from gnu radio stream tags into typed lists for easy access
00004  * \author Victor Castillo, 2024. victorcastilloaguero(at)gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2024-2025 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_SENSOR_DATA_AGGREGATOR_H
00019 #define GNSS_SDR_SENSOR_DATA_AGGREGATOR_H
00020
00021 #include "sensor_data_source_configuration.h"
00022 #include "sensor_identifier.h"
00023 #include <gnuradio/tags.h>
00024 #include <stdint>
00025 #include <gnss_block_interface.h>
00026 #include <vector>
00027
00028 /** \addtogroup Algorithms_Library
00029  * \{ */
00030 /** \addtogroup Algorithm_libs algorithms_libs
00031  * \{ */
00032
00033
00034 template <typename DataType>
00035 struct SensorDataSample
00036 {
00037     uint64_t timestamp;
00038     DataType value;
00039     constexpr SensorDataSample() = default;
00040     constexpr SensorDataSample(uint64_t t, DataType v)
00041         : timestamp(t), value(v) {}
00042 };
00043
00044
00045 class SensorDataAggregator
00046 {
00047 public:
00048     const pmt::pmt_t SENSOR_DATA_TAG = pmt::mp("sensor_data");
00049
00050     explicit SensorDataAggregator(const SensorDataSourceConfiguration& configuration, const
std::vector<SensorIdentifier::value_type>& required_sensors);
00051
00052     void update(const std::vector<gr::tag_t>& tags);
00053
00054     const std::vector<SensorDataSample<float>>& get_f32(SensorIdentifier::value_type sensor_id) const;
00055     SensorDataSample<float> get_last_f32(SensorIdentifier::value_type sensor_id) const;
00056     SensorDataSample<float> get_average_f32(SensorIdentifier::value_type sensor_id) const;
00057
00058     const std::vector<SensorDataSample<double>>& get_f64(SensorIdentifier::value_type sensor_id) const;
00059     SensorDataSample<double> get_last_f64(SensorIdentifier::value_type sensor_id) const;
00060     SensorDataSample<double> get_average_f64(SensorIdentifier::value_type sensor_id) const;
00061
00062     // More getters to be added in the future for different types
00063 private:
00064     void append_data(const pmt::pmt_t& data_dict);
00065
00066     std::unordered_map<SensorIdentifier::value_type, std::vector<SensorDataSample<float>> f32_data_{};
00067     std::unordered_map<SensorIdentifier::value_type, std::vector<SensorDataSample<double>>
f64_data_{};
00068     // More maps to be added in the future for different types
00069 };
00070

```

```

00071
00072 /** \} */
00073 /** \} */
00074 #endif // GNSS_SDR_SENSOR_DATA_AGGREGATOR_H

```

13.248 sensor_data_file.h File Reference

Provides a simple abstraction for reading contiguous binary data from a file.

```

#include <cstdint>
#include <cstdint>
#include <fstream>
#include <gnss_block_interface.h>
#include <memory>
#include <string>
#include <vector>

```

Classes

- class [SensorDataFile](#)

13.248.1 Detailed Description

Provides a simple abstraction for reading contiguous binary data from a file.

Author

Victor Castillo, 2024. victorcastilloaguero(at)gmail.com

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 Definition in file [sensor_data_file.h](#).

13.249 sensor_data_file.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file sensor_data_file.h
00003  * \brief Provides a simple abstraction for reading contiguous binary data from a file
00004  * \author Victor Castillo, 2024. victorcastilloaguero(at)gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
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00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_SENSOR_DATA_FILE_H
00019 #define GNSS_SDR_SENSOR_DATA_FILE_H
00020
00021 #include <cstdint> // for size_t
00022 #include <cstdint>
00023 #include <fstream>
00024 #include <gnss_block_interface.h>
00025 #include <memory>
00026 #include <string>
00027 #include <vector>
00028
00029 /** \addtogroup Algorithms_Library
00030  * \{ */
00031 /** \addtogroup Algorithm_libs algorithms_libs
00032  * \{ */
00033
00034
00035 class SensorDataFile

```

```

00036 {
00037 public:
00038     using sptr = gnss_shared_ptr<SensorDataFile>;
00039     using id_type = std::size_t;
00040
00041     SensorDataFile(
00042         const std::string& path,
00043         const std::size_t& sample_delay,
00044         const std::size_t& sample_period,
00045         const std::size_t& offset_in_file,
00046         const std::size_t& item_size,
00047         const bool& repeat);
00048
00049     void reset();
00050
00051     bool read_until_sample(std::size_t end_sample, std::size_t& sample_stamp, std::vector<uint8_t>&
buffer);
00052
00053     std::size_t get_chunks_read() const;
00054
00055 private:
00056     bool read_item(std::vector<uint8_t>& buffer);
00057
00058     void read_into_io_buffer();
00059
00060     void read_into_item_buffer(std::vector<uint8_t>& item_buf);
00061
00062     std::string path_;
00063     std::ifstream file_;
00064     std::size_t sample_period_;
00065     std::size_t offset_in_file_;
00066     std::size_t item_size_;
00067
00068     std::size_t chunks_read_;
00069     std::size_t next_sample_stamp_;
00070     std::vector<uint8_t> io_buffer_;
00071     std::size_t io_buffer_size_;
00072     std::size_t offset_in_io_buffer_;
00073     bool repeat_;
00074     bool done_;
00075 };
00076
00077 /** \} */
00078 /** \} */
00079 #endif // GNSS_SDR_SENSOR_DATA_FILE_H

```

13.250 sensor_data_resampler.h File Reference

Updates timestamp within sensor data tags. To be used in resampler blocks.

```
#include <gnuradio/tags.h>
```

```
#include <vector>
```

Functions

- `std::vector< gr::tag_t > resample_sensor_data_tags` (const `std::vector< gr::tag_t >` &tags, double freq_in, double freq_out)

Updates timestamp within sensor data tags. To be used in resampler blocks.

13.250.1 Detailed Description

Updates timestamp within sensor data tags. To be used in resampler blocks.

Author

Victor Castillo, 2025. victorcastilloaguero(at)gmail.com

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Definition in file [sensor_data_resampler.h](#).

13.251 sensor_data_resampler.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file sensor_data_resampler.h
00003  * \brief Updates timestamp within sensor data tags. To be used in resampler blocks.
00004  * \author Victor Castillo, 2025. victorcastilloaguero(at)gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_SENSOR_DATA_RESAMPLER_H
00019 #define GNSS_SDR_SENSOR_DATA_RESAMPLER_H
00020
00021 #include <gnuradio/tags.h>
00022 #include <vector>
00023
00024 /** \addtogroup Algorithms_Library
00025  * \{ */
00026 /** \addtogroup Algorithm_libs algorithms_libs
00027  * \{ */
00028
00029
00030 /** \brief Updates timestamp within sensor data tags. To be used in resampler blocks.
00031  *
00032  * \param tags Stream tags as retrieved by `get_tags_in_window` or `get_tags_in_range`.
00033  * \param freq_in Input RF sample rate.
00034  * \param freq_out Output RF sample rate.
00035  * \return Stream tags to be added with `add_item_tag`.
00036  */
00037 std::vector<gr::tag_t> resample_sensor_data_tags(const std::vector<gr::tag_t>& tags, double freq_in,
double freq_out);
00038
00039
00040 /** \} */
00041 /** \} */
00042 #endif // GNSS_SDR_SENSOR_DATA_RESAMPLER_H

```

13.252 sensor_data_source.h File Reference

GNURadio block that adds extra data to the sample stream.

```

#include "gnss_block_interface.h"
#include "sensor_data/sensor_data_file.h"
#include "sensor_data/sensor_data_source_configuration.h"
#include <gnuradio/sync_block.h>
#include <gnuradio/types.h>
#include <cstdint>

```

Classes

- class [SensorDataSource](#)

13.252.1 Detailed Description

GNURadio block that adds extra data to the sample stream.

Author

Victor Castillo, 2024. victorcastilloaguero(at)gmail.com

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 Definition in file [sensor_data_source.h](#).

13.253 sensor_data_source.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file sensor_data_source.h
00003  * \brief GNURadio block that adds extra data to the sample stream.
00004  * \author Victor Castillo, 2024. victorcastilloaguero(at)gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2024-2025 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_SENSOR_DATA_SOURCE_H
00019 #define GNSS_SDR_SENSOR_DATA_SOURCE_H
00020
00021 #include "gnss_block_interface.h"
00022 #include "sensor_data/sensor_data_file.h"
00023 #include "sensor_data/sensor_data_source_configuration.h"
00024 #include <gnuradio/sync_block.h> // for sync_block
00025 #include <gnuradio/types.h> // for gr_vector_const_void_star
00026 #include <cstdint> // for size_t
00027
00028 /** \addtogroup Algorithms_Library
00029  * \{ */
00030 /** \addtogroup Algorithm_libs algorithms_libs
00031  * \{ */
00032
00033 class SensorDataSource : public gr::sync_block
00034 {
00035 public:
00036     using sptr = gnss_shared_ptr<SensorDataSource>;
00037
00038     SensorDataSource(
00039         const SensorDataSourceConfiguration& configuration,
00040         const gr::io_signature::sptr& io_signature);
00041
00042     int work(int noutput_items,
00043             gr_vector_const_void_star& input_items,
00044             gr_vector_void_star& output_items) override;
00045
00046 private:
00047     std::unordered_map<SensorDataFile::id_type, SensorDataFile::sptr> sensor_data_files_;
00048     std::unordered_map<SensorDataFile::id_type, std::vector<SensorDataConfiguration>
00049         sensor_config_map_;
00049     std::size_t item_size_;
00050     std::size_t items_per_sample_;
00051 };
00052
00053 /** \} */
00054 /** \} */
00055 #endif // GNSS_SDR_SENSOR_DATA_SOURCE_H

```

13.254 sensor_data_source_configuration.h File Reference

```

#include "configuration_interface.h"
#include "sensor_data_type.h"
#include "sensor_identifier.h"
#include <string>
#include <unordered_map>

```

Classes

- struct [SensorDataFileConfiguration](#)
- struct [SensorDataConfiguration](#)
- class [SensorDataSourceConfiguration](#)

13.254.1 Detailed Description

Author

Victor Castillo, 2024. victorcastilloaguero(at)gmail.com

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 Definition in file [sensor_data_source_configuration.h](#).

13.255 sensor_data_source_configuration.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file sensor_data_source_configuration.h
00003  * \brief
00004  * \author Victor Castillo, 2024. victorcastilloaguero(at)gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2024-2025 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_SENSOR_DATA_SOURCE_CONFIGURATION_H
00019 #define GNSS_SDR_SENSOR_DATA_SOURCE_CONFIGURATION_H
00020
00021 #include "configuration_interface.h"
00022 #include "sensor_data_type.h"
00023 #include "sensor_identifier.h"
00024 #include <string>
00025 #include <unordered_map>
00026
00027 /** \addtogroup Algorithms_Library
00028  * \{ */
00029 /** \addtogroup Algorithm_libs algorithms_libs
00030  * \{ */
00031
00032 class ConfigurationInterface;
00033
00034 struct SensorDataFileConfiguration
00035 {
00036     uint64_t id;
00037     uint64_t chunk_size;
00038     uint64_t file_offset;
00039     uint64_t sample_offset;
00040     uint64_t sample_period;
00041     std::string filename;
00042     bool repeat;
00043 };
00044
00045
00046 struct SensorDataConfiguration
00047 {
00048     uint64_t id;
00049     uint64_t file_id;
00050     uint64_t offset;
00051     SensorIdentifier::value_type identifier;
00052     SensorDataType::value_type type;
00053     pmt::pmt_t tag_key;
00054 };
00055
00056
00057 class SensorDataSourceConfiguration
00058 {
00059 public:
00060     explicit SensorDataSourceConfiguration(const ConfigurationInterface* configuration);
00061
00062     bool validate() const;
00063
00064     bool is_enabled() const;
00065
00066     bool is_sensor_provided(SensorIdentifier::value_type sensor_id) const;
00067
00068     const std::unordered_map<uint64_t, SensorDataFileConfiguration>& files() const;
00069

```



```

00070     const std::vector<SensorDataConfiguration>& sensors() const;
00071
00072     void set_items_per_sample(uint64_t items_per_sample);
00073
00074     uint64_t get_items_per_sample() const;
00075
00076 private:
00077     void configure_files(const ConfigurationInterface* configuration);
00078
00079     void configure_sensors(const ConfigurationInterface* configuration);
00080
00081     bool validate_files() const;
00082
00083     bool validate_sensors() const;
00084
00085     bool enabled_;
00086     std::unordered_map<uint64_t, SensorDataFileConfiguration> files_;
00087     std::vector<SensorDataConfiguration> sensors_;
00088     uint64_t items_per_sample_;
00089 };
00090
00091 /** @} */
00092 /** @} */
00093 #endif // GNSS_SDR_SENSOR_DATA_SOURCE_CONFIGURATION_H

```

13.256 sensor_data_type.h File Reference

```

#include <pmt/pmt.h>
#include <string>

```

Classes

- struct [SensorDataType](#)

13.256.1 Detailed Description

Author

Victor Castillo, 2025. victorcastilloaguero(at)gmail.com

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 Definition in file [sensor_data_type.h](#).

13.257 sensor_data_type.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file sensor_data_type.h
00003  * \brief
00004  * \author Victor Castillo, 2025. victorcastilloaguero(at)gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_SENSOR_DATA_TYPE_H
00019 #define GNSS_SDR_SENSOR_DATA_TYPE_H
00020
00021 #include <pmt/pmt.h>
00022 #include <string>
00023
00024 /** \addtogroup Algorithms_Library
00025  * \{ */
00026 /** \addtogroup Algorithm_libs algorithms_libs
00027  * \{ */

```

```

00028
00029 struct SensorDataType
00030 {
00031     SensorDataType() = delete;
00032     enum value_type
00033     {
00034         UINT64, // Used internally for SAMPLE_STAMP and CHUNK_COUNT
00035         F32,
00036         F64,
00037         I32,
00038         I64,
00039         // More types can be added here, don't forget to update the static functions
00040     };
00041
00042     static value_type from_string(const std::string& s);
00043
00044     static std::string to_string(const value_type& v);
00045
00046     static uint64_t get_size(const value_type& v);
00047
00048     static pmt::pmt_t make_value(const value_type& v, void* value);
00049 };
00050
00051
00052 /** \} */
00053 /** \} */
00054 #endif // GNSS_SDR_SENSOR_DATA_TYPE_H

```

13.258 sensor_identifier.h File Reference

```

#include "sensor_data_type.h"
#include <functional>
#include <string>

```

Classes

- struct [SensorIdentifier](#)
- struct [std::hash< SensorIdentifier::value_type >](#)

Namespaces

- namespace [std](#)
STL namespace.

13.258.1 Detailed Description

Author

Victor Castillo, 2025. victorcastilloaguero(at)gmail.com

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 Definition in file [sensor_identifier.h](#).

13.259 sensor_identifier.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file sensor_identifier.h
00003 * \brief
00004 * \author Victor Castillo, 2025. victorcastilloaguero(at)gmail.com
00005 *
00006 * -----
00007 *
00008 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009 * This file is part of GNSS-SDR.
00010 *
00011 * Copyright (C) 2024-2025 (see AUTHORS file for a list of contributors)
00012 * SPDX-License-Identifier: GPL-3.0-or-later
00013 *

```

```

00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_SENSOR_IDENTIFIER_H
00019 #define GNSS_SDR_SENSOR_IDENTIFIER_H
00020
00021 #include "sensor_data_type.h"
00022 #include <functional>
00023 #include <string>
00024
00025 /** \addtogroup Algorithms_Library
00026  * \{ */
00027 /** \addtogroup Algorithm_libs algorithms_libs
00028  * \{ */
00029
00030 struct SensorIdentifier
00031 {
00032     SensorIdentifier() = delete;
00033     enum value_type : unsigned short
00034     {
00035         SAMPLE_STAMP = 0,    // Used internally
00036         CHUNK_COUNT,        // Used internally
00037         IMU_VEL_X,
00038         IMU_VEL_Y,
00039         IMU_VEL_Z,
00040         IMU_ACC_X,
00041         IMU_ACC_Y,
00042         IMU_ACC_Z,
00043         IMU_ANG_VEL_X,
00044         IMU_ANG_VEL_Y,
00045         IMU_ANG_VEL_Z,
00046         IMU_ANG_ACC_X,
00047         IMU_ANG_ACC_Y,
00048         IMU_ANG_ACC_Z,
00049     };
00050
00051     static value_type from_string(const std::string& s);
00052
00053     static std::string to_string(value_type v);
00054
00055     static bool is_valid_type(value_type sensor_id, SensorDataType::value_type type);
00056
00057     static SensorDataType::value_type get_internal_type(value_type sensor_id);
00058
00059     static pmt::pmt_t convert_to_internal_type(value_type sensor_id, SensorDataType::value_type
original_type, const pmt::pmt_t& value);
00060 };
00061
00062
00063 // Fix for C++11
00064 namespace std
00065 {
00066     template <>
00067 struct hash<SensorIdentifier::value_type>
00068 {
00069     std::size_t operator()(const SensorIdentifier::value_type& key) const noexcept
00070     {
00071         return std::hash<unsigned short>()(static_cast<unsigned short>(key));
00072     }
00073 };
00074 } // namespace std
00075
00076
00077 /** \} */
00078 /** \} */
00079 #endif // GNSS_SDR_SENSOR_IDENTIFIER_H

```

13.260 short_x2_to_cshort.h File Reference

Adapts two short streams into a `std::complex<short>` stream.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_block.h>
#include <gnuradio/types.h>

```

Classes

- class [short_x2_to_cshort](#)

This class adapts two short streams into a `std::complex<short>` stream.

Typedefs

- using [short_x2_to_cshort_sptr](#) = gnss_shared_ptr<[short_x2_to_cshort](#)>

Functions

- [short_x2_to_cshort_sptr](#) [make_short_x2_to_cshort](#) ()

13.260.1 Detailed Description

Adapts two short streams into a `std::complex<short>` stream.

Author

Carles Fernandez Prades, [cfernandez\(at\)cttc.es](mailto:cfernandez(at)cttc.es)

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 Definition in file [short_x2_to_cshort.h](#).

13.261 short_x2_to_cshort.h

[Go to the documentation of this file.](#)

```
00001  /*!
00002  * \file short_x2_to_cshort.h
00003  * \brief Adapts two short streams into a std::complex<short> stream
00004  * \author Carles Fernandez Prades, cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_SHORT_X2_TO_CSHORT_H
00018 #define GNSS_SDR_SHORT_X2_TO_CSHORT_H
00019
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_block.h>
00023 #include <gnuradio/types.h> // for gr_vector_const_void_star
00024
00025 /** \addtogroup Algorithms_Library
00026  * \{ */
00027 /** \addtogroup Algorithm_libs algorithms_libs
00028  * \{ */
00029
00030
00031 class short_x2_to_cshort;
00032
00033 using short_x2_to_cshort_sptr = gnss_shared_ptr<short_x2_to_cshort>;
00034
00035 short_x2_to_cshort_sptr make_short_x2_to_cshort();
00036
00037 /*!
00038 * \brief This class adapts two short streams into a std::complex<short> stream
00039 */
00040 class short_x2_to_cshort : public gr::sync_block
00041 {
00042 public:
00043     int work(int noutput_items,
00044             gr_vector_const_void_star &input_items,
00045             gr_vector_void_star &output_items);
00046
00047 private:
00048     friend short_x2_to_cshort_sptr make_short_x2_to_cshort();
00049     short_x2_to_cshort();
00050 };
00051
00052
00053 /** \} */
00054 /** \} */
00055 #endif // GNSS_SDR_SHORT_X2_TO_CSHORT_H
```

13.262 trackingcmd.h File Reference

Class that stores information to update the GNSS signal tracking estimations.

```
#include <cstdint>
```

Classes

- class [TrackingCmd](#)

13.262.1 Detailed Description

Class that stores information to update the GNSS signal tracking estimations.

Author

Javier Arribas, 2021. jarribas(at)cttc.es

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Definition in file [trackingcmd.h](#).

13.263 trackingcmd.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file trackingcmd.h
00003  * \brief Class that stores information to update the GNSS signal tracking estimations
00004  * \author Javier Arribas, 2021. jarribas(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_TRACKINGCMD_H_
00019 #define GNSS_SDR_TRACKINGCMD_H_
00020
00021 #include <cstdint>
00022
00023 /** \addtogroup Algorithms_Library
00024  * \{ */
00025 /** \addtogroup Algorithm_libs algorithms_libs
00026  * \{ */
00027
00028 class TrackingCmd
00029 {
00030 public:
00031     TrackingCmd();
00032
00033     bool enable_carrier_nco_cmd = false;
00034     bool enable_code_nco_cmd = false;
00035     double code_freq_chips = 0.0;
00036     double carrier_freq_hz = 0.0;
00037     double carrier_freq_rate_hz_s = 0.0;
00038     uint64_t sample_counter = 0UL;
00039 };
00040
00041 /** \} */
00042 /** \} */
00043 #endif // GNSS_SDR_TRACKINGCMD_H_
```

13.264 hybrid_observables.h File Reference

Implementation of an adapter of an observables block accepting all kind of signals to a [ObservablesInterface](#).

```
#include "gnss_synchro.h"
#include "hybrid_observables_gs.h"
#include "observables_interface.h"
#include <gnuradio/gr_complex.h>
#include <gnuradio/runtime_types.h>
#include <cstdlib>
#include <string>
```

Classes

- class [HybridObservables](#)

This class implements an [ObservablesInterface](#) for observables of all kind of GNSS signals.

13.264.1 Detailed Description

Implementation of an adapter of an observables block accepting all kind of signals to a [ObservablesInterface](#).

Author

Mara Branzanti 2013. mara.branzanti(at)gmail.com

Javier Arribas 2013. jarribas(at)cttc.es

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 Definition in file [hybrid_observables.h](#).

13.265 hybrid_observables.h

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```
00001 /*!
00002  * \file hybrid_observables.h
00003  * \brief Implementation of an adapter of an observables block accepting all kind
00004  * of signals to a ObservablesInterface
00005  * \author Mara Branzanti 2013. mara.branzanti(at)gmail.com
00006  * \author Javier Arribas 2013. jarribas(at)cttc.es
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00012  *
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00015  *
00016  * -----
00017  */
00018
00019
00020 #ifndef GNSS_SDR_HYBRID_OBSERVABLES_H
00021 #define GNSS_SDR_HYBRID_OBSERVABLES_H
00022
00023 #include "gnss_synchro.h"
00024 #include "hybrid_observables_gs.h"
00025 #include "observables_interface.h"
00026 #include <gnuradio/gr_complex.h> // for gr_complex
00027 #include <gnuradio/runtime_types.h> // for basic_block_sptr, top_block_sptr
00028 #include <cstdlib>
00029 #include <string>
00030
00031 /** \addtogroup Observables
00032  * Classes for the computation of GNSS observables
00033  * \{ */
00034 /** \addtogroup Observables_adapters obs_adapters
00035  * Wrap GNU Radio observables blocks with an ObservablesInterface
00036  * \{ */
00037
00038 class ConfigurationInterface;
00039
00040 /*!
00041  * \brief This class implements an ObservablesInterface for observables of all kind of GNSS signals
00042  */
00043 class HybridObservables : public ObservablesInterface
```

```

00044 {
00045 public:
00046     HybridObservables(const ConfigurationInterface* configuration,
00047         const std::string& role,
00048         unsigned int in_streams,
00049         unsigned int out_streams);
00050
00051     ~HybridObservables() = default;
00052
00053     inline std::string role() override
00054     {
00055         return role_;
00056     }
00057
00058     /*! Returns "Hybrid_Observables"
00059     inline std::string implementation() override
00060     {
00061         return "Hybrid_Observables";
00062     }
00063
00064     void connect(gr::top_block_sptr top_block) override;
00065     void disconnect(gr::top_block_sptr top_block) override;
00066     gr::basic_block_sptr get_left_block() override;
00067     gr::basic_block_sptr get_right_block() override;
00068
00069     inline void reset() override
00070     {
00071         return;
00072     }
00073
00074     /*! All blocks must have an item_size() function implementation
00075     inline size_t item_size() override
00076     {
00077         return sizeof(Gnss_Synchro);
00078     }
00079
00080 private:
00081     hybrid_observables_gs_sptr observables_;
00082     std::string dump_filename_;
00083     std::string role_;
00084     unsigned int in_streams_;
00085     unsigned int out_streams_;
00086     bool dump_;
00087     bool dump_mat_;
00088 };
00089
00090 /** \} */
00091 /** \} */
00092 #endif

```

13.266 hybrid_observables_gs.h File Reference

Interface of the observables computation block.

```

#include "gnss_block_interface.h"
#include "gnss_time.h"
#include "obs_conf.h"
#include <boost/circular_buffer.hpp>
#include <gnuradio/block.h>
#include <gnuradio/types.h>
#include <cstdint>
#include <cstdint>
#include <fstream>
#include <memory>
#include <queue>
#include <string>
#include <typeinfo>
#include <vector>

```

Classes

- class [hybrid_observables_gs](#)

This class implements a block that computes observables.

Typedefs

- using [hybrid_observables_gs_sptr](#) = gnss_shared_ptr<[hybrid_observables_gs](#)>

Functions

- [hybrid_observables_gs_sptr](#) **hybrid_observables_gs_make** (const [Obs_Conf](#) &conf_)

13.266.1 Detailed Description

Interface of the observables computation block.

Author

Mara Branzanti 2013. mara.branzanti(at)gmail.com

Javier Arribas 2013. jarribas(at)cttc.es

Antonio Ramos 2018. antonio.ramos(at)cttc.es

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 Definition in file [hybrid_observables_gs.h](#).

13.267 hybrid_observables_gs.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file hybrid_observables_gs.h
00003  * \brief Interface of the observables computation block
00004  * \author Mara Branzanti 2013. mara.branzanti(at)gmail.com
00005  * \author Javier Arribas 2013. jarribas(at)cttc.es
00006  * \author Antonio Ramos 2018. antonio.ramos(at)cttc.es
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
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00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
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00015  *
00016  * -----
00017  */
00018
00019
00020 #ifndef GNSS_SDR_HYBRID_OBSERVABLES_GS_H
00021 #define GNSS_SDR_HYBRID_OBSERVABLES_GS_H
00022
00023 #include "gnss_block_interface.h"
00024 #include "gnss_time.h" // for timetags produced by Tracking
00025 #include "obs_conf.h"
00026 #include <boost/circular_buffer.hpp> // for boost::circular_buffer
00027 #include <gnuradio/block.h> // for block
00028 #include <gnuradio/types.h> // for gr_vector_int
00029 #include <cstdint> // for size_t
00030 #include <cstdlib> // for int32_t
00031 #include <fstream> // for std::ofstream
00032 #include <memory> // for std::shared, std::unique_ptr
00033 #include <queue> // for std::queue
00034 #include <string> // for std::string
00035 #include <typeinfo> // for typeid
00036 #include <vector> // for std::vector
00037
00038 /** \addtogroup Observables
00039  * \{ */
00040 /** \addtogroup Observables_gnuradio_blocks obs_gr_blocks
00041  * GNU Radio blocks for the computation of GNSS observables
00042  * \{ */
00043
00044
00045 class Gnss_Synchro;
00046 class hybrid_observables_gs;
00047
00048 template <class T>
00049 class Gnss_circular_deque;
00050
00051 using hybrid_observables_gs_sptr = gnss_shared_ptr<hybrid_observables_gs>;

```



```

00052
00053 hybrid_observables_gs_sptr hybrid_observables_gs_make(const Obs_Conf& conf_);
00054
00055 /*!
00056  * \brief This class implements a block that computes observables
00057  */
00058 class hybrid_observables_gs : public gr::block
00059 {
00060 public:
00061     ~hybrid_observables_gs();
00062     void forecast(int noutput_items, gr_vector_int& ninput_items_required);
00063     int general_work(int noutput_items, gr_vector_int& ninput_items,
00064                     gr_vector_const_void_star& input_items, gr_vector_void_star& output_items);
00065 private:
00066     friend hybrid_observables_gs_sptr hybrid_observables_gs_make(const Obs_Conf& conf_);
00067     explicit hybrid_observables_gs(const Obs_Conf& conf_);
00070
00071     const size_t d_double_type_hash_code = typeid(double).hash_code();
00072     const size_t d_int_type_hash_code = typeid(int).hash_code();
00073
00074     void msg_handler_pvt_to_observables(const pmt::pmt_t& msg);
00075     double compute_T_rx_s(const Gnss_Synchro& a) const;
00076     bool interp_trk_obs(Gnss_Synchro& interpolated_obs, uint32_t ch, uint64_t rx_clock) const;
00077     void update_TOW(const std::vector<Gnss_Synchro>& data);
00078     void compute_pranges(std::vector<Gnss_Synchro>& data) const;
00079     void smooth_pseudoranges(std::vector<Gnss_Synchro>& data);
00080     void detect_cycle_slips(std::vector<Gnss_Synchro>& data, uint64_t rx_clock);
00081
00082     void set_tag_timestamp_in_sdr_timeframe(const std::vector<Gnss_Synchro>& data, uint64_t rx_clock);
00083
00084     void propagate_sensor_data(const std::vector<Gnss_Synchro>& data);
00085
00086     int32_t save_matfile() const;
00087
00088     Obs_Conf d_conf;
00089
00090     std::unique_ptr<Gnss_circular_deque<Gnss_Synchro> d_gnss_synchro_history; // Tracking observable
history
00091
00092     boost::circular_buffer<uint64_t> d_Rx_clock_buffer; // time history
00093
00094     std::vector<std::queue<GnssTime> d_SourceTagTimestamps;
00095     std::queue<GnssTime> d_TimeChannelTagTimestamps;
00096
00097     std::queue<gr::tag_t> d_sensor_data_tags;
00098     std::uint64_t d_trq_last_sample{0};
00099
00100     std::vector<bool> d_channel_last_pll_lock;
00101     std::vector<double> d_channel_last_pseudorange_smooth;
00102     std::vector<double> d_channel_last_carrier_phase_rads;
00103     std::vector<bool> d_channel_last_rx_time_valid;
00104
00105     std::string d_dump_filename;
00106
00107     std::ofstream d_dump_file;
00108
00109     double d_smooth_filter_M;
00110     double d_T_rx_step_s;
00111     double d_last_rx_clock_round20ms_error;
00112
00113     uint32_t d_T_rx_TOW_ms;
00114     uint32_t d_T_rx_step_ms;
00115     uint32_t d_T_status_report_timer_ms;
00116     uint32_t d_nchannels_in;
00117     uint32_t d_nchannels_out;
00118
00119     bool d_T_rx_TOW_set; // rx time follow GPST
00120     bool d_always_output_gs;
00121     bool d_dump;
00122     bool d_dump_mat;
00123 };
00124
00125 /** \} */
00126 /** \} */
00127 #endif // GNSS_SDR_HYBRID_OBSERVABLES_GS_H

```

13.268 obs_conf.h File Reference

Class that contains all the configuration parameters for generic observables block.

```

#include <stdint>
#include <string>

```

Classes

- class [Obs_Conf](#)

13.268.1 Detailed Description

Class that contains all the configuration parameters for generic observables block.

Author

Javier Arribas, 2020. jarribas(at)cttc.es

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 Definition in file [obs_conf.h](#).

13.269 obs_conf.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file obs_conf.h
00003  * \brief Class that contains all the configuration parameters for generic
00004  * observables block
00005  * \author Javier Arribas, 2020. jarribas(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_OBS_CONF_H
00019 #define GNSS_SDR_OBS_CONF_H
00020
00021 #include <stdint>
00022 #include <string>
00023
00024 /** \addtogroup Observables
00025  * \{ */
00026 /** \addtogroup Observables_libs observables_libs
00027  * Utilities for GNSS observables configuration.
00028  * \{ */
00029
00030 class Obs_Conf
00031 {
00032 public:
00033     Obs_Conf();
00034
00035     std::string dump_filename{"obs_dump.dat"};
00036     int32_t smoothing_factor{0};
00037     uint32_t nchannels_in{0U};
00038     uint32_t nchannels_out{0U};
00039     uint32_t observable_interval_ms{20U};
00040     bool enable_carrier_smoothing{false};
00041     bool always_output_gs{false};
00042     bool dump{false};
00043     bool dump_mat{false};
00044     bool enable_E6{false};
00045 };
00046
00047 /** \} */
00048 /** \} */
00049 #endif // GNSS_SDR_OBS_CONF_H

```

13.270 rtklib_pvt.h File Reference

Interface of a Position Velocity and Time computation block.

```
#include "gnss_synchro.h"
#include "pvt_interface.h"
#include "rtklib.h"
#include "rtklib_pvt_gs.h"
#include <gnuradio/gr_complex.h>
#include <gnuradio/runtime_types.h>
#include <cstdlib>
#include <ctime>
#include <map>
#include <string>
```

Classes

- class [Rtklib_Pvt](#)

This class implements a [PvtInterface](#) for the RTKLIB PVT block.

13.270.1 Detailed Description

Interface of a Position Velocity and Time computation block.

Author

Javier Arribas, 2017. jarribas(at)cttc.es

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 Definition in file [rtklib_pvt.h](#).

13.271 rtklib_pvt.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtklib_pvt.h
00003  * \brief Interface of a Position Velocity and Time computation block
00004  * \author Javier Arribas, 2017. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_RTKLIB_PVT_H
00019 #define GNSS_SDR_RTKLIB_PVT_H
00020
00021 #include "gnss_synchro.h"
00022 #include "pvt_interface.h" // for PvtInterface
00023 #include "rtklib.h" // for rtk_t
00024 #include "rtklib_pvt_gs.h" // for rtklib_pvt_gs_sptr
00025 #include <gnuradio/gr_complex.h> // for gr_complex
00026 #include <gnuradio/runtime_types.h> // for basic_block_sptr, top_block_sptr
00027 #include <cstdlib> // for size_t
00028 #include <ctime> // for time_t
00029 #include <map> // for map
00030 #include <string> // for string
00031
00032 /** \addtogroup PVT
00033  * Computation of Position, Velocity and Time from GNSS observables.
00034  * \{ */
00035 /** \addtogroup PVT_adapters pvt_adapters
00036  * Wrap GNU Radio PVT solvers with a PvtInterface
00037  * \{ */
00038
00039 class ConfigurationInterface;
00040 class Galileo_Almanac;
```

```

00041 class Galileo_Ephemeris;
00042 class Gps_Almanac;
00043 class Gps_Ephemeris;
00044
00045 /*!
00046  * \brief This class implements a PvtInterface for the RTKLIB PVT block
00047  *
00048  * Global configuration options used:
00049  *
00050  * GNSS-SDR.pre_2009_file - flag indicating a file older than 2009 rollover should be processed
00051  * (false)
00052  * GNSS-SDR.observable_interval_ms - (20)
00053  * It supports the following configuration options:
00054  *
00055  * .dump - (false)
00056  * .dump_filename - (".pvt.dat")
00057  * .dump_mat - (true)
00058  * .rtk_trace_level - debug level for the RTKLIB methods (0)
00059  *
00060  * .output_rate_ms - (500)
00061  * Note that the actual rate is the least common multiple of this value and
00062  * GNSS-SDR.observable_interval_ms
00063  * .display_rate_ms - (500)
00064  *
00065  * .flag_nmea_tty_port - (false)
00066  * .nmea_dump_filename - (".nmea_pvt.nmea")
00067  * .nmea_dump_devname - ("/dev/tty1")
00068  *
00069  * .rinex_version - (3) overridden by -RINEX_version=n.nn command line argument
00070  * .rinexobs_rate_ms - rate at which RINEX observations are written (1000). Note that
00071  * the actual rate is the least common multiple of this value and
00072  * .output_rate_ms
00073  * .rinex_name - (-RINEX_name command-line argument)
00074  *
00075  * .flag_rtcmm_tty_port - (false)
00076  * .rtcmm_dump_devname - ("/dev/pts/1")
00077  * .flag_rtcmm_server - (false)
00078  * .rtcmm_tcp_port - (2101)
00079  * .rtcmm_station_id - (1234)
00080  * Output rates ... all values are LCM with the computed output rate (above)
00081  * .rtcmm_MT1019_rate_ms - (5000)
00082  * .rtcmm_MT1020_rate_ms - (5000)
00083  * .rtcmm_MT1045_rate_ms - (5000)
00084  * .rtcmm_MSM_rate_ms - (1000)
00085  * .rtcmm_MT1077_rate_ms - (.rtcmm_MSM_rate_ms)
00086  * .rtcmm_MT1087_rate_ms - (.rtcmm_MSM_rate_ms)
00087  * .rtcmm_MT1097_rate_ms - (.rtcmm_MSM_rate_ms)
00088  *
00089  * .kml_rate_ms - (1000)
00090  * .gpx_rate_ms - (1000)
00091  * .geojson_rate_ms - (1000)
00092  * .nmea_rate_ms - (1000)
00093  *
00094  * .positioning_mode - The RTKLIB positioning mode. ("Single") Supported values are "Single",
00095  * "Static", "Kinematic", "PPP_Static" and "PPP_Kinematic". Unsupported modes
00096  * include DGPS/DGNSS, Moving Baseline, Fixed, and PPP-fixed
00097  * .num_bands - number of frequencies to use, between 1 and 3. Default is based on the channels
00098  * configured
00099  * .elevation_mask - (15.0). Value must be in the range [0,90.0]
00100  * .dynamics_model - (0) 0:none, 1:velocity, 2:acceleration
00101  *
00102  * .iono_model - ("OFF"). Supported values are "OFF", "Broadcast", "SBAS", "Iono-Free-LC",
00103  * "Estimate_STEC", "IONEX". Unsupported values include QZSS broadcast, QZSS
00104  * LEX, and SLANT TEC.
00105  * .trop_model - ("OFF"). Supported values are "OFF", "Saastamoinen", "SBAS", "Estimate_ZTD", and
00106  * "Estimate_ZTD_Grad". Unsupported values include ZTD correction and ZTD+grad
00107  * correction
00108  * .phwindup - phase windup correction for PPP modes (0)
00109  * .reject_GPS_IIA - whether the GPS Block IIA satellites in eclipse are excluded (0). Only applies
00110  * in PPP-* modes
00111  * .raim_fde - whether RAIM (receiver autonomous integrity monitoring) FDE (fault detection and
00112  * exclusion) is enabled (0)
00113  * .earth_tide - (0)
00114  * .navigation_system - mask of navigation systems to use. Default based on configured channels
00115  * 0x01:GPS, 0x02:SBAS, 0x04:GLONASS, 0x08:Galileo, 0x10:QZSS, 0x20:BeiDou,
00116  * 0x40:IRNS, 0x80:LEO
00117  *
00118  * .AR_GPS - Ambiguity Resolution mode for GPS ("Continuous"). Supported values are "OFF",
00119  * "Continuous", "Instantaneous", "Fix-and-Hold", "PPP-AR". Unsupported values
00120  * include PPP-AR ILS, WLNL, and TCAR.
00121  * .AR_GLO - Ambiguity Resolution mode for GLONASS (1). Value must be in the range [0,3].
00122  * (0:off,1:on,2:auto cal,3:ext cal)
00123  * .AR_DBS - Ambiguity Resolution Mode for BeiDou (1). Value must be in the range [0,1]. (0:off,1:on)
00124  * .min_ratio_to_fix_ambiguity - (3.0)
00125  * .min_lock_to_fix_ambiguity - (0)
00126  * .min_elevation_to_fix_ambiguity - minimum elevation (deg) to fix integer ambiguity (0.0)

```

```

00122 * .outage_reset_ambiguity - (5)
00123 * .slip_threshold - (0.05)
00124 * .threshold_reject_gdop - if GDOP is over this value, the observable is excluded (30.0)
00125 * .threshold_reject_innovation - if innovation is over this value, the observable is excluded (30.0)
00126 * .number_filter_iter - number of iterations for the estimation filter (1)
00127 * .bias_0 - (30.0)
00128 * .iono_0 - (0.03)
00129 * .trop_0 - (0.3)
00130 * .sigma_bias - process noise stddev of carrier-phase bias(ambiguity) (cycle/sqrt(s)) (1e-4)
00131 * .sigma_iono - process noise stddev of vertical ionospheric delay per 10km baseline (m/sqrt(s))
(1e-3)
00132 * .sigma_trop - process noise stddev of zenith tropospheric delay (m/sqrt(s)) (1e-4)
00133 * .sigma_acch - process noise stddev of the receiver acceleration horizontal component
(m/s2/sqrt(s)) (1e-1)
00134 * .sigma_accv - process noise stddev of the receiver acceleration vertical component (m/s2/sqrt(s))
(1e-2)
00135 * .sigma_pos - (0.0)
00136 * .code_phase_error_ratio_l1 - (100.0)
00137 * .code_phase_error_ratio_l2 - (100.0)
00138 * .code_phase_error_ratio_l5 - (100.0)
00139 * .carrier_phase_error_factor_a - (0.003)
00140 * .carrier_phase_error_factor_b - (0.003)
00141 *
00142 * .output_enabled - (true)
00143 * .rinex_output_enabled - (.output_enabled)
00144 * .gpx_output_enabled - (.output_enabled)
00145 * .geojson_output_enabled - (.output_enabled)
00146 * .kml_output_enabled - (.output_enabled)
00147 * .xml_output_enabled - (.output_enabled)
00148 * .nmea_output_enabled - (.output_enabled)
00149 * .rtcm_output_enabled - (false)
00150
00151 * .output_path - directory to which output files are written (".")
00152 * .rinex_output_path - (.output_path)
00153 * .gpx_output_path - (.output_path)
00154 * .geojson_output_path - (.output_path)
00155 * .kml_output_path - (.output_path)
00156 * .xml_output_path - (.output_path)
00157 * .nmea_output_path - (.output_path)
00158 * .rtcm_output_path - (.output_path)
00159 *
00160 * .enable_monitor - enable the PVT monitor (false)
00161 * .monitor_client_addresses - ("127.0.0.1")
00162 * .monitor_udp_port - DO NOT USE THE DEFAULT (1234)
00163 * .enable_protobuf - serialize using protocol buffers (true). Monitor.enable_protobuf if true, sets
this to true
00164 *
00165 * .enable_monitor_ephemeris - enable the ephemeris monitor (false)
00166 * .monitor_ephemeris_client_addresses - ("127.0.0.1")
00167 * .monitor_ephemeris_udp_port - DO NOT USE THE DEFAULT (1234)
00168 *
00169 * .show_local_time_zone - (false)
00170 * .enable_rx_clock_correction - (false)
00171 * .max_clock_offset_ms - (40)
00172 */
00173 class Rtklib_Pvt : public PvtInterface
00174 {
00175 public:
00176     Rtklib_Pvt(const ConfigurationInterface* configuration,
00177               const std::string& role,
00178               unsigned int in_streams,
00179               unsigned int out_streams);
00180
00181     virtual ~Rtklib_Pvt();
00182
00183     inline std::string role() override
00184     {
00185         return role_;
00186     }
00187
00188     //! Returns "RTKLIB_PVT"
00189     inline std::string implementation() override
00190     {
00191         return "RTKLIB_PVT";
00192     }
00193
00194     void clear_ephemeris() override;
00195     std::map<int, Gps_Ephemeris> get_gps_ephemeris() const override;
00196     std::map<int, Galileo_Ephemeris> get_galileo_ephemeris() const override;
00197     std::map<int, Gps_Almanac> get_gps_almanac() const override;
00198     std::map<int, Galileo_Almanac> get_galileo_almanac() const override;
00199
00200     void connect(gr::top_block_sptr top_block) override;
00201     void disconnect(gr::top_block_sptr top_block) override;
00202     gr::basic_block_sptr get_left_block() override;
00203     gr::basic_block_sptr get_right_block() override;
00204

```

```

00205     inline void reset() override
00206     {
00207         return;
00208     }
00209
00210     //! All blocks must have an item_size() function implementation
00211     inline size_t item_size() override
00212     {
00213         return sizeof(Gnss_Synchro);
00214     }
00215
00216     bool get_latest_PVT(double* longitude_deg,
00217         double* latitude_deg,
00218         double* height_m,
00219         double* ground_speed_kmh,
00220         double* course_over_ground_deg,
00221         time_t* UTC_time) override;
00222
00223 private:
00224     rtklib_pvt_gs_sptr pvt_;
00225     rtk_t rtk{};
00226     std::string role_;
00227     unsigned int in_streams_;
00228     unsigned int out_streams_;
00229 };
00230
00231 /** \} */
00232 /** \} */
00233 #endif // GNSS_SDR_RTKLIB_PVT_H

```

13.272 rtklib_pvt_gs.h File Reference

Interface of a Position Velocity and Time computation block.

```

#include "gnss_block_interface.h"
#include "gnss_sdr_make_unique.h"
#include "gnss_synchro.h"
#include "gnss_time.h"
#include "osnma_data.h"
#include "rtklib.h"
#include "sensor_data/sensor_data_aggregator.h"
#include "sensor_data/sensor_data_source_configuration.h"
#include <boost/date_time/gregorian/gregorian.hpp>
#include <boost/date_time/posix_time/posix_time.hpp>
#include <boost/interprocess/ipc/message_queue.hpp>
#include <gnuradio/sync_block.h>
#include <gnuradio/types.h>
#include <pmt/pmt.h>
#include <chrono>
#include <cstdint>
#include <cstdint>
#include <ctime>
#include <fstream>
#include <map>
#include <memory>
#include <queue>
#include <set>
#include <string>
#include <vector>

```

Classes

- class [rtklib_pvt_gs](#)

This class implements a block that computes the PVT solution using the RTKLIB integrated library.

Typedefs

- using `rtklib_pvt_gs_sptr` = `gnss_shared_ptr<rtklib_pvt_gs>`

Functions

- `rtklib_pvt_gs_sptr rtklib_make_pvt_gs` (`uint32_t` nchannels, const `Pvt_Conf` &conf_, const `rtk_t` &rtk, const `SensorDataSourceConfiguration` &sensor_data_configuration)

13.272.1 Detailed Description

Interface of a Position Velocity and Time computation block.

Author

Javier Arribas, 2017. jarribas(at)cttc.es

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 Definition in file [rtklib_pvt_gs.h](#).

13.273 rtklib_pvt_gs.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file rtklib_pvt_gs.h
00003  * \brief Interface of a Position Velocity and Time computation block
00004  * \author Javier Arribas, 2017. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_RTKLIB_PVT_GS_H
00018 #define GNSS_SDR_RTKLIB_PVT_GS_H
00019
00020 #include "gnss_block_interface.h"
00021 #include "gnss_sdr_make_unique.h"
00022 #include "gnss_synchro.h"
00023 #include "gnss_time.h"
00024 #include "osnma_data.h"
00025 #include "rtklib.h"
00026 #include "sensor_data/sensor_data_aggregator.h"
00027 #include "sensor_data/sensor_data_source_configuration.h"
00028 #include <boost/date_time/gregorian/gregorian.hpp>
00029 #include <boost/date_time/posix_time/posix_time.hpp>
00030 #include <boost/interprocess/ipc/message_queue.hpp>
00031 #include <gnuradio/sync_block.h> // for sync_block
00032 #include <gnuradio/types.h> // for gr_vector_const_void_star
00033 #include <pmt/pmt.h> // for pmt_t
00034 #include <chrono> // for system_clock
00035 #include <cstdint> // for size_t
00036 #include <cstdint> // for int32_t
00037 #include <ctime> // for time_t
00038 #include <fstream> // for std::fstream
00039 #include <map> // for map
00040 #include <memory> // for shared_ptr, unique_ptr
00041 #include <queue> // for std::queue
00042 #include <set> // for std::set
00043 #include <string> // for string
00044 #include <vector> // for vector
00045
00046 /** \addtogroup PVT
00047  * \{ */
00048 /** \addtogroup PVT_gnuradio_blocks pvt_gr_blocks
00049  * GNU Radio blocks for the computation of PVT solutions.
00050  * \{ */
00051
00052
00053 class Beidou_Dnav_Almanac;
```

```

00054 class Beidou_Dnav_Ephemeris;
00055 class Galileo_Almanac;
00056 class Galileo_Ephemeris;
00057 class Galileo_HAS_data;
00058 class Geohash;
00059 class GeoJSON_Printer;
00060 class Gps_Almanac;
00061 class Gps_Ephemeris;
00062 class Gpx_Printer;
00063 class Kml_Printer;
00064 class Monitor_Pvt_Udp_Sink;
00065 class Monitor_Ephemeris_Udp_Sink;
00066 class Nmea_Printer;
00067 class Pvt_Conf;
00068 class Rinex_Printer;
00069 class Rtcn_Printer;
00070 class An_Packet_Printer;
00071 class Has_Simple_Printer;
00072 class Rtklib_Solver;
00073 class rtklib_pvt_gs;
00074
00075 using rtklib_pvt_gs_sptr = gnss_shared_ptr<rtklib_pvt_gs>;
00076
00077 rtklib_pvt_gs_sptr rtklib_make_pvt_gs(uint32_t nchannels,
00078     const Pvt_Conf& conf_,
00079     const rtk_t& rtk,
00080     const SensorDataSourceConfiguration& sensor_data_configuration);
00081
00082 /*!
00083  * \brief This class implements a block that computes the PVT solution using the RTKLIB integrated
00084  library
00085  */
00086 class rtklib_pvt_gs : public gr::sync_block
00087 {
00088 public:
00089     ~rtklib_pvt_gs(); ///< Default destructor
00090
00091     /*!
00092      * \brief Get latest set of GPS ephemeris from PVT block
00093      */
00094     std::map<int, Gps_Ephemeris> get_gps_ephemeris_map() const;
00095
00096     /*!
00097      * \brief Get latest set of GPS almanac from PVT block
00098      */
00099     std::map<int, Gps_Almanac> get_gps_almanac_map() const;
00100
00101     /*!
00102      * \brief Get latest set of Galileo ephemeris from PVT block
00103      */
00104     std::map<int, Galileo_Ephemeris> get_galileo_ephemeris_map() const;
00105
00106     /*!
00107      * \brief Get latest set of Galileo almanac from PVT block
00108      */
00109     std::map<int, Galileo_Almanac> get_galileo_almanac_map() const;
00110
00111     /*!
00112      * \brief Get latest set of BeiDou DNAV ephemeris from PVT block
00113      */
00114     std::map<int, Beidou_Dnav_Ephemeris> get_beidou_dnav_ephemeris_map() const;
00115
00116     /*!
00117      * \brief Get latest set of BeiDou DNAV almanac from PVT block
00118      */
00119     std::map<int, Beidou_Dnav_Almanac> get_beidou_dnav_almanac_map() const;
00120
00121     /*!
00122      * \brief Clear all ephemeris information and the almanacs for GPS and Galileo
00123      */
00124     void clear_ephemeris();
00125
00126     /*!
00127      * \brief Get the latest Position WGS84 [deg], Ground Velocity, Course over Ground, and UTC Time,
00128      if available
00129      */
00130     bool get_latest_PVT(double* longitude_deg,
00131         double* latitude_deg,
00132         double* height_m,
00133         double* ground_speed_kmh,
00134         double* course_over_ground_deg,
00135         time_t* UTC_time) const;
00136
00137     int work(int noutput_items, gr_vector_const_void_star& input_items,
00138         gr_vector_void_star& output_items); ///< PVT Signal Processing
00139 private:

```



```

00139     friend rtklib_pvt_gs_sptr rtklib_make_pvt_gs(uint32_t nchannels,
00140         const Pvt_Conf& conf_,
00141         const rtk_t& rtk,
00142         const SensorDataSourceConfiguration& sensor_data_configuration);
00143
00144     rtklib_pvt_gs(uint32_t nchannels,
00145         const Pvt_Conf& conf_,
00146         const rtk_t& rtk,
00147         const SensorDataSourceConfiguration& sensor_data_configuration);
00148
00149     void log_source_timetag_info(double RX_time_ns, double TAG_time_ns);
00150
00151     void msg_handler_telemetry(const pmt::pmt_t& msg);
00152
00153     void msg_handler_has_data(const pmt::pmt_t& msg);
00154
00155     void msg_handler_osnma(const pmt::pmt_t& msg);
00156
00157     void initialize_and_apply_carrier_phase_offset();
00158
00159     void apply_rx_clock_offset(std::map<int, Gnss_Synchro>& observables_map,
00160         double rx_clock_offset_s);
00161
00162     void update_HAS_corrections();
00163
00164     std::map<int, Gnss_Synchro> interpolate_observables(const std::map<int, Gnss_Synchro>&
observables_map_t0,
00165         const std::map<int, Gnss_Synchro>& observables_map_t1,
00166         double rx_time_s);
00167
00168     inline std::time_t convert_to_time_t(const boost::posix_time::ptime pt) const
00169     {
00170         return (pt - boost::posix_time::ptime(boost::gregorian::date(1970, 1, 1))).total_seconds();
00171     }
00172
00173     std::vector<std::string> split_string(const std::string& s, char delim) const;
00174
00175     bool send_ttf_msg(double ttf) const;
00176     bool save_gnss_synchro_map_xml(const std::string& file_name); // debug helper function
00177     bool load_gnss_synchro_map_xml(const std::string& file_name); // debug helper function
00178
00179     std::fstream d_log_timetag_file;
00180
00181     std::unique_ptr<SensorDataAggregator> d_sensor_data_aggregator;
00182
00183     std::shared_ptr<Rtklib_Solver> d_internal_pvt_solver;
00184     std::shared_ptr<Rtklib_Solver> d_user_pvt_solver;
00185
00186     std::unique_ptr<boost::interprocess::message_queue> d_mq;
00187
00188     std::unique_ptr<Rinex_Printer> d_rp;
00189     std::unique_ptr<Kml_Printer> d_kml_dump;
00190     std::unique_ptr<Gpx_Printer> d_gpx_dump;
00191     std::unique_ptr<Nmea_Printer> d_nmea_printer;
00192     std::unique_ptr<GeoJSON_Printer> d_geojson_printer;
00193     std::unique_ptr<Rtcm_Printer> d_rtcm_printer;
00194     std::unique_ptr<Monitor_Pvt_Udp_Sink> d_udp_sink_ptr;
00195     std::unique_ptr<Monitor_Ephemeris_Udp_Sink> d_eph_udp_sink_ptr;
00196     std::unique_ptr<Has_Simple_Printer> d_has_simple_printer;
00197     std::unique_ptr<An_Packet_Printer> d_an_printer;
00198
00199     std::chrono::time_point<std::chrono::system_clock> d_start;
00200     std::chrono::time_point<std::chrono::system_clock> d_end;
00201
00202     const std::string d_queue_name;
00203     std::string d_dump_filename;
00204     std::string d_xml_base_path;
00205     std::string d_local_time_str;
00206
00207     std::vector<bool> d_channel_initialized;
00208     std::vector<double> d_initial_carrier_phase_offset_estimation_rads;
00209
00210     std::map<int, Gnss_Synchro> d_gnss_observables_map;
00211     std::map<int, Gnss_Synchro> d_gnss_observables_map_t0;
00212     std::map<int, Gnss_Synchro> d_gnss_observables_map_t1;
00213     std::map<uint32_t, std::set<uint32_t>> d_auth_nav_data_map;
00214
00215     std::queue<GnssTime> d_TimeChannelTagTimestamps;
00216
00217     boost::posix_time::time_duration d_utc_diff_time;
00218     const std::unique_ptr<Geohash> d_geohash;
00219
00220     const size_t d_gps_ephemeris_sptr_type_hash_code;
00221     const size_t d_gps_iono_sptr_type_hash_code;
00222     const size_t d_gps_utc_model_sptr_type_hash_code;
00223     const size_t d_gps_cnav_ephemeris_sptr_type_hash_code;
00224     const size_t d_gps_cnav_iono_sptr_type_hash_code;

```

```

00225     const size_t d_gps_cnav_utc_model_spstr_type_hash_code;
00226     const size_t d_gps_almanac_spstr_type_hash_code;
00227     const size_t d_galileo_ephemeris_spstr_type_hash_code;
00228     const size_t d_galileo_iono_spstr_type_hash_code;
00229     const size_t d_galileo_utc_model_spstr_type_hash_code;
00230     const size_t d_galileo_almanac_helper_spstr_type_hash_code;
00231     const size_t d_galileo_almanac_spstr_type_hash_code;
00232     const size_t d_glonass_gnav_ephemeris_spstr_type_hash_code;
00233     const size_t d_glonass_gnav_utc_model_spstr_type_hash_code;
00234     const size_t d_glonass_gnav_almanac_spstr_type_hash_code;
00235     const size_t d_beidou_dnav_ephemeris_spstr_type_hash_code;
00236     const size_t d_beidou_dnav_iono_spstr_type_hash_code;
00237     const size_t d_beidou_dnav_utc_model_spstr_type_hash_code;
00238     const size_t d_beidou_dnav_almanac_spstr_type_hash_code;
00239     const size_t d_galileo_has_data_spstr_type_hash_code;
00240
00241     const double d_rinex_version;
00242     double d_rx_time;
00243     uint64_t d_local_counter_ms;
00244     uint64_t d_timestamp_rx_clock_offset_correction_msg_ms;
00245
00246     const int32_t d_rinexobs_rate_ms;
00247     int32_t d_rtcmt_M1045_rate_ms; // Galileo Broadcast Ephemeris
00248     int32_t d_rtcmt_M1019_rate_ms; // GPS Broadcast Ephemeris (orbits)
00249     int32_t d_rtcmt_M1020_rate_ms; // GLONASS Broadcast Ephemeris (orbits)
00250     int32_t d_rtcmt_M1077_rate_ms; // The type 7 Multiple Signal Message format for the USA's GPS
00251     system, popular
00252     int32_t d_rtcmt_M1087_rate_ms; // GLONASS MSM7. The type 7 Multiple Signal Message format for the
00253     Russian GLONASS system
00254     int32_t d_rtcmt_M1097_rate_ms; // Galileo MSM7. The type 7 Multiple Signal Message format for
00255     Europe's Galileo system
00256     int32_t d_rtcmt_MSM_rate_ms;
00257     const int32_t d_kml_rate_ms;
00258     const int32_t d_gpx_rate_ms;
00259     const int32_t d_geojson_rate_ms;
00260     const int32_t d_nmea_rate_ms;
00261     const int32_t d_an_rate_ms;
00262     const int32_t d_output_rate_ms;
00263     const int32_t d_display_rate_ms;
00264     const int32_t d_report_rate_ms;
00265     const int32_t d_max_obs_block_rx_clock_offset_ms;
00266
00267     const uint32_t d_nchannels;
00268     const uint32_t d_signal_enabled_flags;
00269     const uint32_t d_observable_interval_ms;
00270     uint32_t d_pvt_errors_counter;
00271
00272     bool d_dump;
00273     const bool d_dump_mat;
00274     const bool d_rinex_output_enabled;
00275     bool d_geojson_output_enabled;
00276     bool d_gpx_output_enabled;
00277     bool d_kml_output_enabled;
00278     bool d_nmea_output_file_enabled;
00279     bool d_rtcmt_enabled;
00280     bool d_first_fix;
00281     bool d_xml_storage;
00282     const bool d_flag_monitor_pvt_enabled;
00283     const bool d_flag_monitor_ephemeris_enabled;
00284     const bool d_show_local_time_zone;
00285     const bool d_enable_rx_clock_correction;
00286     bool d_enable_has_messages;
00287     const bool d_an_printer_enabled;
00288     bool d_log_timetag;
00289     const bool d_use_has_corrections;
00290     const bool d_use_unhealthy_sats;
00291     const bool d_osnma_strict;
00292 };
00293
00294 /** \} */
00295 /** \} */
00296 #endif // GNSS_SDR_RTKLIB_PVT_GS_H

```

13.274 an_packet_printer.h File Reference

Interface of a class that prints PVT solutions in a serial device following a custom version of the Advanced Navigation Packet Protocol.

```

#include "gnss_synchro.h"
#include <array>
#include <chrono>
#include <cstdint>

```

```
#include <stdint>
#include <map>
#include <string>
```

Classes

- struct [sdr_gnss_packet_t](#)
- struct [an_packet_t](#)
- class [An_Packet_Printer](#)

class that prints PVT solutions in a serial device following a custom version of the Advanced Navigation Packet Protocol.

13.274.1 Detailed Description

Interface of a class that prints PVT solutions in a serial device following a custom version of the Advanced Navigation Packet Protocol.

Author

Carles Fernandez-Prades, 2021. cfernandez@cttc.es

Miguel Angel Gomez Lopez, 2021. gomezlma@inta.es

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 Definition in file [an_packet_printer.h](#).

13.275 an_packet_printer.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file an_packet_printer.h
00003  * \brief Interface of a class that prints PVT solutions in a serial device
00004  * following a custom version of the Advanced Navigation Packet Protocol
00005  * \author Carles Fernandez-Prades, 2021. cfernandez@cttc.es
00006  * \author Miguel Angel Gomez Lopez, 2021. gomezlma@inta.es
00007  *
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020
00021 #ifndef GNSS_SDR_AN_PACKET_PRINTER_H
00022 #define GNSS_SDR_AN_PACKET_PRINTER_H
00023
00024 #include "gnss_synchro.h"
00025 #include <array>
00026 #include <chrono>
00027 #include <cstdint>
00028 #include <stdint>
00029 #include <map>
00030 #include <string>
00031
00032 /** \addtogroup PVT
00033  * \{ */
00034 /** \addtogroup PVT_libs
00035  * \{ */
00036
00037 class Rtklib_Solver;
00038
00039 struct sdr_gnss_packet_t
00040 {
00041     uint8_t nsvfix; // number of sats used in PVT fix
00042     uint8_t gps_satellites; // number of tracked GPS satellites
00043     uint8_t galileo_satellites; // number of tracked Galileo satellites
```

```

00044     uint32_t microseconds;           // from start of receiver operation
00045     double latitude;                 // in [rad]
00046     double longitude;                // in [rad]
00047     double height;                   // in [m]
00048     float velocity[3];               // North, East, Down, in [m/s]
00049
00050     struct
00051     {
00052         uint8_t prn;                 // PRN ID. Galileo sats expressed as PRN + 100
00053         uint8_t snr;                 // in [dB-Hz]
00054         int16_t doppler;             // in [Hz], saturates at +32767 / -32768 Hz
00055     } sats[16];
00056
00057     uint32_t reserved;
00058     uint16_t status;
00059 };
00060
00061
00062 struct an_packet_t
00063 {
00064     uint8_t header[4];
00065     uint8_t data[113]; // SDR_GNSS_PACKET_LENGTH
00066 };
00067
00068
00069 /*!
00070  * \brief class that prints PVT solutions in a serial device following a custom
00071  * version of the Advanced Navigation Packet Protocol.
00072  */
00073 class An_Packet_Printer
00074 {
00075 public:
00076     /*!
00077      * \brief Default constructor.
00078      */
00079     explicit An_Packet_Printer(const std::string& an_dump_devname);
00080
00081     /*!
00082      * \brief Default destructor.
00083      */
00084     ~An_Packet_Printer();
00085
00086     /*!
00087      * \brief Print AN packet to the initialized device.
00088      */
00089     bool print_packet(const Rtklib_Solver* const pvt_data, const std::map<int, Gnss_Synchro>&
gnss_observables_map);
00090
00091     /*!
00092      * \brief Close serial port. Also done in the destructor, this is only
00093      * for testing.
00094      */
00095     void close_serial() const;
00096
00097 private:
00098     const std::array<uint16_t, 256> d_crc16_table = {
00099         {0x0000, 0x1021, 0x2042, 0x3063, 0x4084, 0x50a5, 0x60c6, 0x70e7, 0x8108, 0x9129, 0xa14a,
0xb16b, 0xc18c, 0xd1ad, 0xe1ce, 0xf1ef, 0x1231, 0x0210, 0x3273,
0100         0x2252, 0x52b5, 0x4294, 0x72f7, 0x62d6, 0x9339, 0x8318, 0xb37b, 0xa35a, 0xd3bd, 0xc39c,
0xf3ff, 0xe3de, 0x2462, 0x3443, 0x0420, 0x1401, 0x64e6, 0x74c7, 0x44a4, 0x5485, 0xa56a, 0xb54b,
0x8528,
0101         0x9509, 0xe5ee, 0xf5cf, 0xc5ac, 0xd58d, 0x3653, 0x2672, 0x1611, 0x0630, 0x76d7, 0x66f6,
0x5695, 0x46b4, 0xb75b, 0xa77a, 0x9719, 0x8738, 0xf7df, 0xe7fe, 0xd79d, 0xc7bc, 0x48c4, 0x58e5,
0x6886,
0102         0x78a7, 0x0840, 0x1861, 0x2802, 0x3823, 0xc9cc, 0xd9ed, 0xe98e, 0xf9af, 0x8948, 0x9969,
0xa90a, 0xb92b, 0x5af5, 0x4ad4, 0x7ab7, 0x6a96, 0x1a71, 0x0a50, 0x3a33, 0x2a12, 0xdbfd, 0xcbbc,
0xfbbf,
0103         0xeb9e, 0x9b79, 0x8b58, 0xbb3b, 0xab1a, 0x6ca6, 0x7c87, 0x4ce4, 0x5cc5, 0x2c22, 0x3c03,
0x0c60, 0x1c41, 0xedae, 0xfd8f, 0xcdec, 0xddcd, 0xad2a, 0xbd0b, 0x8d68, 0x9d49, 0x7e97, 0x6eb6,
0x5ed5,
0104         0x4ef4, 0x3e13, 0x2e32, 0x1e51, 0x0e70, 0xff9f, 0xefbe, 0xdfdd, 0xcffc, 0xbflb, 0xaf3a,
0x9f59, 0x8f78, 0x9188, 0x81a9, 0xb1ca, 0xaleb, 0xd10c, 0xc12d, 0xf14e, 0xe16f, 0x1080, 0x00a1,
0x30c2,
0105         0x20e3, 0x5004, 0x4025, 0x7046, 0x6067, 0x83b9, 0x9398, 0xa3fb, 0xb3da, 0xc33d, 0xd31c,
0xe37f, 0xf35e, 0x02b1, 0x1290, 0x22f3, 0x32d2, 0x4235, 0x5214, 0x6277, 0x7256, 0xb5ea, 0xa5cb,
0x95a8,
0106         0x8589, 0xf56e, 0xe54f, 0xd52c, 0xc50d, 0x34e2, 0x24c3, 0x14a0, 0x0481, 0x7466, 0x6447,
0x5424, 0x4405, 0xa7db, 0xb7fa, 0x8799, 0x97b8, 0xe75f, 0xf77e, 0xc71d, 0xd73c, 0x26d3, 0x36f2,
0x0691,
0107         0x16b0, 0x6657, 0x7676, 0x4615, 0x5634, 0xd94c, 0xc96d, 0xf90e, 0xe92f, 0x99c8, 0x89e9,
0xb98a, 0xa9ab, 0x5844, 0x4865, 0x7806, 0x6827, 0x18c0, 0x08e1, 0x3882, 0x28a3, 0xcb7d, 0xdb5c,
0xeb3f,
0108         0xfb1e, 0x8bf9, 0x9bd8, 0xabbb, 0xbb9a, 0x4a75, 0x5a54, 0x6a37, 0x7a16, 0xaf11, 0x1ad0,
0x2ab3, 0x3a92, 0xfd2e, 0xed0f, 0xdd6c, 0xcd4d, 0xbdaa, 0xad8b, 0x9de8, 0x8dc9, 0x7c26, 0x6c07,
0x5c64,
0109         0x4c45, 0x3ca2, 0x2c83, 0x1ce0, 0x0cc1, 0xef1f, 0xff3e, 0xcf5d, 0xdf7c, 0xaf9b, 0xbfba,
0x8fd9, 0x9ff8, 0x6e17, 0x7e36, 0x4e55, 0x5e74, 0x2e93, 0x3eb2, 0x0ed1, 0x1ef0}};

```

```

00110
00111     const size_t SDR_GNSS_PACKET_LENGTH = 113;
00112     const uint8_t SDR_GNSS_PACKET_ID = 201;
00113
00114     int init_serial(const std::string& serial_device);
00115     void update_sdr_gnss_packet(sdr_gnss_packet_t* _packet, const Rtklib_Solver* const pvt, const
std::map<int, Gnss_Synchro>& gnss_observables_map) const;
00116     void encode_gnss_cttc_packet(sdr_gnss_packet_t* sdr_gnss_packet, an_packet_t* _packet) const;
00117     uint16_t calculate_crc16(const void* data, uint16_t length) const;
00118     uint8_t calculate_header_lrc(const uint8_t* data) const;
00119     void an_packet_encode(an_packet_t* an_packet) const;
00120     void encode_sdr_gnss_packet(sdr_gnss_packet_t* sdr_gnss_packet, an_packet_t* _packet) const;
00121     void LSB_bytes_to_array(void* _in, int offset, uint8_t* _out, uint8_t var_size) const;
00122
00123     std::chrono::time_point<std::chrono::system_clock> d_start;
00124     std::string d_an_devname;
00125     int d_an_dev_descriptor; // serial device descriptor (i.e. COM port)
00126 };
00127
00128 /** \} */
00129 /** \} */
00130 #endif // GNSS_SDR_AN_PACKET_PRINTER_H

```

13.276 geohash.h File Reference

Interface of a class that encodes / decodes geohashes.

```
#include <array>
#include <string>
```

Classes

- class [Geohash](#)

Class for geohash encoding / decoding See <https://en.wikipedia.org/wiki/Geohash>.

13.276.1 Detailed Description

Interface of a class that encodes / decodes geohashes.

Author

Carles Fernandez-Prades, 2023. cfernandez(at)cttc.es

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Definition in file [geohash.h](#).

13.277 geohash.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file geohash.h
00003  * \brief Interface of a class that encodes / decodes geohashes
00004  * \author Carles Fernandez-Prades, 2023. cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2023 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GEOHASH_H
00020 #define GNSS_SDR_GEOHASH_H
00021
00022 #include <array>
00023 #include <string>

```

```

00024
00025 /** \addtogroup PVT
00026 * \{ */
00027 /** \addtogroup PVT_libs
00028 * \{ */
00029
00030 /*!
00031 * \brief Class for geohash encoding / decoding
00032 * See https://en.wikipedia.org/wiki/Geohash
00033 */
00034 class Geohash
00035 {
00036 public:
00037     Geohash() = default;
00038
00039     /**
00040      * Encodes latitude/longitude to geohash, either to specified precision or
00041      * to automatically evaluated precision.
00042      *
00043      * @param {double} lat - Latitude in degrees.
00044      * @param {double} lon - Longitude in degrees.
00045      * @param {int} [precision] - Number of characters in resulting geohash.
00046      * @returns {string} Geohash of supplied latitude/longitude.
00047      * @throws Invalid geohash.
00048      */
00049     std::string encode(double lat, double lon, int precision = -1) const;
00050
00051     /**
00052      * Decode geohash to latitude/longitude (location is approximate centre of
00053      * geohash cell, to reasonable precision).
00054      *
00055      * @param {string} geohash - Geohash string to be converted to
00056      * latitude/longitude.
00057      * @returns {lat, lon} (Center of) geohashed location.
00058      * @throws Invalid geohash.
00059      */
00060     std::array<double, 2> decode(std::string geohash) const;
00061
00062     /**
00063      * Returns SW/NE latitude/longitude bounds of specified geohash.
00064      */
00065     std::array<double, 4> bounds(std::string geohash) const;
00066     std::string base32{"0123456789bcdefghjkmnpqrstuvwxyz"};
00067 };
00068
00069 /** \} */
00070 /** \} */
00071 #endif // GNSS_SDR_GEOHASH_H

```

13.278 geojson_printer.h File Reference

Interface of a class that prints PVT solutions in GeoJSON format.

```

#include <fstream>
#include <string>

```

Classes

- class [GeoJSON_Printer](#)

Prints PVT solutions in GeoJSON format file.

13.278.1 Detailed Description

Interface of a class that prints PVT solutions in GeoJSON format.

Author

Carles Fernandez-Prades, 2015. cfernandez(at)cttc.es

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 Definition in file [geojson_printer.h](#).

13.279 geojson_printer.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file geojson_printer.h
00003  * \brief Interface of a class that prints PVT solutions in GeoJSON format
00004  * \author Carles Fernandez-Prades, 2015. cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GEOJSON_PRINTER_H
00020 #define GNSS_SDR_GEOJSON_PRINTER_H
00021
00022
00023 #include <fstream>
00024 #include <string>
00025
00026 /** \addtogroup PVT
00027  * \{ */
00028 /** \addtogroup PVT_libs
00029  * \{ */
00030
00031
00032 class Pvt_Solution;
00033
00034 /*!
00035  * \brief Prints PVT solutions in GeoJSON format file
00036  *
00037  * See https://tools.ietf.org/html/rfc7946
00038  */
00039 class GeoJSON_Printer
00040 {
00041 public:
00042     explicit GeoJSON_Printer(const std::string& base_path = ".");
00043     ~GeoJSON_Printer();
00044     bool set_headers(const std::string& filename, bool time_tag_name = true);
00045     bool print_position(const Pvt_Solution* const position);
00046     bool close_file();
00047
00048 private:
00049     std::ofstream geojson_file;
00050     std::string filename_;
00051     std::string geojson_base_path;
00052     bool first_pos;
00053 };
00054
00055
00056 /** \} */
00057 /** \} */
00058 #endif // GNSS_SDR_GEOJSON_PRINTER_H

```

13.280 gpx_printer.h File Reference

Interface of a class that prints PVT information to a gpx file.

```

#include <fstream>
#include <string>

```

Classes

- class [Gpx_Printer](#)
Prints PVT information to GPX format file.

13.280.1 Detailed Description

Interface of a class that prints PVT information to a gpx file.

Author

Álvaro Cebrián Juan, 2018. [acebrianjuan\(at\)gmail.com](mailto:acebrianjuan(at)gmail.com)

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 Definition in file [gpx_printer.h](#).

13.281 gpx_printer.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gpx_printer.h
00003  * \brief Interface of a class that prints PVT information to a gpx file
00004  * \author Álvaro Cebrián Juan, 2018. acebrianjuan\(at\)gmail.com
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GPX_PRINTER_H
00020 #define GNSS_SDR_GPX_PRINTER_H
00021
00022
00023 #include <fstream>
00024 #include <string>
00025
00026 /** \addtogroup PVT
00027  * \{ */
00028 /** \addtogroup PVT_libs
00029  * \{ */
00030
00031
00032 class Pvt_Solution;
00033
00034 /*!
00035  * \brief Prints PVT information to GPX format file
00036  *
00037  * See https://www.topografix.com/gpx.asp
00038  */
00039 class Gpx_Printer
00040 {
00041 public:
00042     explicit Gpx_Printer(const std::string& base_path = ".");
00043     ~Gpx_Printer();
00044     bool set_headers(const std::string& filename, bool time_tag_name = true);
00045     bool print_position(const Pvt_Solution* const position);
00046     bool close_file();
00047
00048 private:
00049     std::ofstream gpx_file;
00050     std::string gpx_filename;
00051     std::string indent;
00052     std::string gpx_base_path;
00053     bool positions_printed;
00054 };
00055
00056
00057 /** \} */
00058 /** \} */
00059 #endif // GNSS_SDR_GPX_PRINTER_H

```

13.282 has_simple_printer.h File Reference

Interface of a class that prints HAS messages content in a txt file.

```

#include <cstdint>
#include <fstream>
#include <mutex>
#include <string>

```



```
#include <vector>
```

Classes

- class [Has_Simple_Printer](#)

Prints HAS messages content in a txt file. See HAS-SIS-ICD for a message description.

13.282.1 Detailed Description

Interface of a class that prints HAS messages content in a txt file.

Author

Carles Fernandez-Prades, 2021. cfernandez(at)cttc.es

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 Definition in file [has_simple_printer.h](#).

13.283 has_simple_printer.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file has_simple_printer.h
00003  * \brief Interface of a class that prints HAS messages content in a txt file.
00004  * \author Carles Fernandez-Prades, 2021. cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_HAS_SIMPLE_PRINTER_H
00018 #define GNSS_SDR_HAS_SIMPLE_PRINTER_H
00019
00020 #include <cstdint> // for size_t
00021 #include <fstream> // for std::ofstream
00022 #include <mutex> // for std::mutex
00023 #include <string> // for std::string
00024 #include <vector> // for std::vector
00025
00026 /** \addtogroup PVT
00027  * \{ */
00028 /** \addtogroup PVT_libs
00029  * \{ */
00030
00031 class Galileo_HAS_data;
00032
00033 /*!
00034  * \brief Prints HAS messages content in a txt file. See HAS-SIS-ICD for a
00035  * message description.
00036  */
00037 class Has_Simple_Printer
00038 {
00039 public:
00040     explicit Has_Simple_Printer(const std::string& base_path = std::string("."), const std::string&
        filename = std::string("HAS_Messages"), bool time_tag_name = true);
00041     ~Has_Simple_Printer();
00042     bool print_message(const Galileo_HAS_data* const has_data);
00043
00044 private:
00045     template <class T>
00046         std::string print_vector(const std::vector<T>& vec, float scale_factor = 1) const;
00047
00048     template <class T>
00049         std::string print_vector_binary(const std::vector<T>& vec, size_t bit_length) const;
00050
00051     template <class T>
00052         std::string print_matrix(const std::vector<std::vector<T>>& mat, const std::string& filler, float
            scale_factor = 1) const;
```

```

00053
00054     std::string print_vector_string(const std::vector<std::string>& vec) const;
00055
00056     bool close_file();
00057
00058     std::mutex d_mutex;
00059     std::ofstream d_has_file;
00060     std::string d_has_filename;
00061     std::string d_has_base_path;
00062     bool d_data_printed;
00063 };
00064
00065 /** \} */
00066 /** \} */
00067 #endif // GNSS_SDR_HAS_SIMPLE_PRINTER_H

```

13.284 kml_printer.h File Reference

Interface of a class that prints PVT information to a kml file.

```

#include <fstream>
#include <string>

```

Classes

- class [Kml_Printer](#)

Prints PVT information to OGC KML format file (can be viewed with Google Earth)

13.284.1 Detailed Description

Interface of a class that prints PVT information to a kml file.

Author

Javier Arribas, 2011. jarribas(at)cttc.es Álvaro Cebrián Juan, 2018. acebrianjuan(at)gmail.com

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 Definition in file [kml_printer.h](#).

13.285 kml_printer.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file kml_printer.h
00003  * \brief Interface of a class that prints PVT information to a kml file
00004  * \author Javier Arribas, 2011. jarribas(at)cttc.es
00005  *         Álvaro Cebrián Juan, 2018. acebrianjuan(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_KML_PRINTER_H
00020 #define GNSS_SDR_KML_PRINTER_H
00021
00022 #include <fstream> // for ofstream
00023 #include <string>
00024
00025 /** \addtogroup PVT
00026  * \{ */
00027 /** \addtogroup PVT_libs
00028  * \{ */
00029
00030

```

```

00031 class Pvt_Solution;
00032
00033 /*!
00034  * \brief Prints PVT information to OGC KML format file (can be viewed with Google Earth)
00035  *
00036  * See https://www.opengeospatial.org/standards/kml
00037  */
00038 class Kml_Printer
00039 {
00040 public:
00041     explicit Kml_Printer(const std::string& base_path = std::string("."));
00042     ~Kml_Printer();
00043     bool set_headers(const std::string& filename, bool time_tag_name = true);
00044     bool print_position(const Pvt_Solution* const position);
00045     bool close_file();
00046
00047 private:
00048     std::ofstream kml_file;
00049     std::ofstream tmp_file;
00050     std::string kml_filename;
00051     std::string kml_base_path;
00052     std::string tmp_file_str;
00053     std::string indent;
00054     unsigned int point_id;
00055     bool positions_printed;
00056 };
00057
00058
00059 /** \} */
00060 /** \} */
00061 #endif // GNSS_SDR_KML_PRINTER_H

```

13.286 monitor_ephemeris_udp_sink.h File Reference

Interface of a class that sends serialized [Gps_Ephemeris](#) and [Galileo_Ephemeris](#) objects over udp to one or multiple endpoints.

```

#include "galileo_ephemeris.h"
#include "gps_ephemeris.h"
#include "serdes_galileo_eph.h"
#include "serdes_gps_eph.h"
#include <boost/asio.hpp>
#include <memory>
#include <string>
#include <vector>

```

Classes

- class [Monitor_Ephemeris_Udp_Sink](#)

Typedefs

- using [b_io_context](#) = boost::asio::io_service

13.286.1 Detailed Description

Interface of a class that sends serialized [Gps_Ephemeris](#) and [Galileo_Ephemeris](#) objects over udp to one or multiple endpoints.

Author

Javier Arribas, 2021. jarribas(at)cttc.es

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Definition in file [monitor_ephemeris_udp_sink.h](#).

13.287 monitor_ephemeris_udp_sink.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file monitor_ephemeris_udp_sink.h
00003  * \brief Interface of a class that sends serialized Gps_Ephemeris and
00004  * Galileo_Ephemeris objects over udp to one or multiple endpoints.
00005  * \author Javier Arribas, 2021. jarribas(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_MONITOR_EPHEMERIS_UDP_SINK_H
00019 #define GNSS_SDR_MONITOR_EPHEMERIS_UDP_SINK_H
00020
00021 #include "galileo_ephemeris.h"
00022 #include "gps_ephemeris.h"
00023 #include "serdes_galileo_eph.h"
00024 #include "serdes_gps_eph.h"
00025 #include <boost/asio.hpp>
00026 #include <memory>
00027 #include <string>
00028 #include <vector>
00029
00030 /** \addtogroup PVT
00031  * \{ */
00032 /** \addtogroup PVT_libs
00033  * \{ */
00034
00035
00036 #if USE_BOOST_ASIO_IO_CONTEXT
00037 using b_io_context = boost::asio::io_context;
00038 #else
00039 using b_io_context = boost::asio::io_service;
00040 #endif
00041
00042 class Monitor_Ephemeris_Udp_Sink
00043 {
00044 public:
00045     Monitor_Ephemeris_Udp_Sink(const std::vector<std::string>& addresses, const uint16_t& port, bool
    protobuf_enabled);
00046     bool write_gps_ephemeris(const std::shared_ptr<Gps_Ephemeris>& monitor_gps_eph);
00047     bool write_galileo_ephemeris(const std::shared_ptr<Galileo_Ephemeris>& monitor_gal_eph);
00048
00049 private:
00050     Serdes_Galileo_Eph serdes_gal;
00051     Serdes_Gps_Eph serdes_gps;
00052     b_io_context io_context;
00053     boost::asio::ip::udp::socket socket;
00054     std::vector<boost::asio::ip::udp::endpoint> endpoints;
00055     boost::system::error_code error;
00056     bool use_protobuf;
00057 };
00058
00059
00060 /** \} */
00061 /** \} */
00062 #endif // GNSS_SDR_MONITOR_EPHEMERIS_UDP_SINK_H

```

13.288 monitor_pvt.h File Reference

Interface of the [Monitor_Pvt](#) class.

```

#include <boost/serialization/nvp.hpp>
#include <cstdint>
#include <string>

```

Classes

- class [Monitor_Pvt](#)

This class contains parameters and outputs of the PVT block.

13.288.1 Detailed Description

Interface of the [Monitor_Pvt](#) class.

Author

13.288.1.1 Álvaro Cebrián Juan, 2019. [acebrianjuan\(at\)gmail.com](mailto:acebrianjuan(at)gmail.com)

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Definition in file [monitor_pvt.h](#).

13.289 monitor_pvt.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file monitor_pvt.h
00003  * \brief Interface of the Monitor_Pvt class
00004  * \author
00005  * Álvaro Cebrián Juan, 2019. acebrianjuan\(at\)gmail.com
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_MONITOR_PVT_H
00018 #define GNSS_SDR_MONITOR_PVT_H
00019
00020 #include <boost/serialization/nvp.hpp>
00021 #include <stdint>
00022 #include <string>
00023
00024 /** \addtogroup PVT
00025  * \{ */
00026 /** \addtogroup PVT_libs
00027  * \{ */
00028
00029
00030 /*!
00031  * \brief This class contains parameters and outputs of the PVT block
00032  */
00033 class Monitor_Pvt
00034 {
00035 public:
00036     // TOW
00037     uint32_t TOW_at_current_symbol_ms;
00038     // WEEK
00039     uint32_t week;
00040     // PVT GPS time
00041     double RX_time;
00042     // User clock offset [s]
00043     double user_clk_offset;
00044
00045     // ECEF POS X,Y,X [m] + ECEF VEL X,Y,X [m/s] (6 x double)
00046     double pos_x;
00047     double pos_y;
00048     double pos_z;
00049     double vel_x;
00050     double vel_y;
00051     double vel_z;
00052
00053     // position variance/covariance (m^2) {c_xx,c_yy,c_zz,c_xy,c_yz,c_zx} (6 x double)
00054     double cov_xx;
00055     double cov_yy;
00056     double cov_zz;
00057     double cov_xy;
00058     double cov_yz;
00059     double cov_zx;
00060
00061     // GEO user position Latitude [deg]
00062     double latitude;
00063     // GEO user position Longitude [deg]

```

```

00064     double longitude;
00065     // GEO user position Height [m]
00066     double height;
00067     // East, Nord, Up (ENU) Velocity [m/s]
00068     double vel_e;
00069     double vel_n;
00070     double vel_u;
00071
00072     // Course Over Ground (COG) [deg]
00073     double cog;
00074
00075     // Galileo HAS status: 1- HAS messages decoded and applied, 0 - HAS not available
00076     uint32_t galhas_status;
00077
00078     // NUMBER OF VALID SATS
00079     uint8_t valid_sats;
00080     // RTKLIB solution status
00081     uint8_t solution_status;
00082     // RTKLIB solution type (0:xyz-ecef,1:enu-baseline)
00083     uint8_t solution_type;
00084     // AR ratio factor for validation
00085     float AR_ratio_factor;
00086     // AR ratio threshold for validation
00087     float AR_ratio_threshold;
00088
00089     // GDOP / PDOP/ HDOP/ VDOP
00090     double gdop;
00091     double pdop;
00092     double hdop;
00093     double vdop;
00094
00095     // User clock drift [ppm]
00096     double user_clk_drift_ppm;
00097
00098     // PVT UTC Time (rfc 3339 datetime string)
00099     std::string utc_time;
00100
00101     std::string geohash; // See https://en.wikipedia.org/wiki/Geohash
00102
00103     /*!
00104     * \brief This member function serializes and restores
00105     * Monitor_Pvt objects from a byte stream.
00106     */
00107     template <class Archive>
00108
00109     void serialize(Archive& ar, const unsigned int version)
00110     {
00111         if (version)
00112         {
00113         };
00114
00115         ar& BOOST_SERIALIZATION_NVP(TOW_at_current_symbol_ms);
00116         ar& BOOST_SERIALIZATION_NVP(week);
00117         ar& BOOST_SERIALIZATION_NVP(RX_time);
00118         ar& BOOST_SERIALIZATION_NVP(user_clk_offset);
00119
00120         ar& BOOST_SERIALIZATION_NVP(pos_x);
00121         ar& BOOST_SERIALIZATION_NVP(pos_y);
00122         ar& BOOST_SERIALIZATION_NVP(pos_z);
00123         ar& BOOST_SERIALIZATION_NVP(vel_x);
00124         ar& BOOST_SERIALIZATION_NVP(vel_y);
00125         ar& BOOST_SERIALIZATION_NVP(vel_z);
00126
00127         ar& BOOST_SERIALIZATION_NVP(cov_xx);
00128         ar& BOOST_SERIALIZATION_NVP(cov_yy);
00129         ar& BOOST_SERIALIZATION_NVP(cov_zz);
00130         ar& BOOST_SERIALIZATION_NVP(cov_xy);
00131         ar& BOOST_SERIALIZATION_NVP(cov_yz);
00132         ar& BOOST_SERIALIZATION_NVP(cov_zx);
00133
00134         ar& BOOST_SERIALIZATION_NVP(latitude);
00135         ar& BOOST_SERIALIZATION_NVP(longitude);
00136         ar& BOOST_SERIALIZATION_NVP(height);
00137
00138         ar& BOOST_SERIALIZATION_NVP(valid_sats);
00139         ar& BOOST_SERIALIZATION_NVP(solution_status);
00140         ar& BOOST_SERIALIZATION_NVP(solution_type);
00141         ar& BOOST_SERIALIZATION_NVP(AR_ratio_factor);
00142         ar& BOOST_SERIALIZATION_NVP(AR_ratio_threshold);
00143
00144         ar& BOOST_SERIALIZATION_NVP(gdop);
00145         ar& BOOST_SERIALIZATION_NVP(pdop);
00146         ar& BOOST_SERIALIZATION_NVP(hdop);
00147         ar& BOOST_SERIALIZATION_NVP(vdop);
00148
00149         ar& BOOST_SERIALIZATION_NVP(user_clk_drift_ppm);
00150         ar& BOOST_SERIALIZATION_NVP(utc_time);

```

```

00151
00152         ar& BOOST_SERIALIZATION_NVP (vel_e);
00153         ar& BOOST_SERIALIZATION_NVP (vel_n);
00154         ar& BOOST_SERIALIZATION_NVP (vel_u);
00155
00156         ar& BOOST_SERIALIZATION_NVP (cog);
00157         ar& BOOST_SERIALIZATION_NVP (geohash);
00158     }
00159 };
00160
00161
00162 /** \} */
00163 /** \} */
00164 #endif // GNSS_SDR_MONITOR_PVT_H

```

13.290 monitor_pvt_udp_sink.h File Reference

Interface of a class that sends serialized [Monitor_Pvt](#) objects over udp to one or multiple endpoints.

```

#include "monitor_pvt.h"
#include "serdes_monitor_pvt.h"
#include <boost/asio.hpp>
#include <memory>
#include <string>
#include <vector>

```

Classes

- class [Monitor_Pvt_Udp_Sink](#)

Typedefs

- using [b_io_context](#) = boost::asio::io_service

13.290.1 Detailed Description

Interface of a class that sends serialized [Monitor_Pvt](#) objects over udp to one or multiple endpoints.

Author

Álvaro Cebrián Juan, 2019. [acebrianjuan\(at\)gmail.com](mailto:acebrianjuan(at)gmail.com)

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 Definition in file [monitor_pvt_udp_sink.h](#).

13.291 monitor_pvt_udp_sink.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file monitor_pvt_udp_sink.h
00003  * \brief Interface of a class that sends serialized Monitor_Pvt objects
00004  * over udp to one or multiple endpoints
00005  * \author Álvaro Cebrián Juan, 2019. acebrianjuan(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_MONITOR_PVT_UDP_SINK_H
00019 #define GNSS_SDR_MONITOR_PVT_UDP_SINK_H
00020
00021 #include "monitor_pvt.h"

```

```

00022 #include "serdes_monitor_pvt.h"
00023 #include <boost/asio.hpp>
00024 #include <memory>
00025 #include <string>
00026 #include <vector>
00027
00028 /** \addtogroup PVT
00029  * \{ */
00030 /** \addtogroup PVT_libs
00031  * \{ */
00032
00033
00034 #if USE_BOOST_ASIO_IO_CONTEXT
00035 using b_io_context = boost::asio::io_context;
00036 #else
00037 using b_io_context = boost::asio::io_service;
00038 #endif
00039
00040 class Monitor_Pvt_Udp_Sink
00041 {
00042 public:
00043     Monitor_Pvt_Udp_Sink(
00044         const std::vector<std::string>& addresses,
00045         const std::vector<std::string>& ports,
00046         bool protobuf_enabled);
00047     bool write_monitor_pvt(const Monitor_Pvt* const monitor_pvt);
00048
00049 private:
00050     Serdes_Monitor_Pvt serdes;
00051     b_io_context io_context;
00052     boost::asio::ip::udp::socket socket;
00053     std::vector<boost::asio::ip::udp::endpoint> endpoints;
00054     boost::system::error_code error;
00055     bool use_protobuf;
00056 };
00057
00058
00059 /** \} */
00060 /** \} */
00061 #endif // GNSS_SDR_MONITOR_PVT_UDP_SINK_H

```

13.292 nmea_printer.h File Reference

Interface of a NMEA 2.1 printer for GNSS-SDR This class provides a implementation of a subset of the NMEA-0183 standard for interfacing marine electronic devices as defined by the National Marine Electronics Association (NMEA). See <https://www.nmea.org/> for the NMEA 183 standard.

```

#include <boost/date_time/posix_time/ptime.hpp>
#include <fstream>
#include <memory>
#include <string>

```

Classes

- class [Nmea_Printer](#)

This class provides a implementation of a subset of the NMEA-0183 standard for interfacing marine electronic devices as defined by the National Marine Electronics Association (NMEA).

13.292.1 Detailed Description

Interface of a NMEA 2.1 printer for GNSS-SDR This class provides a implementation of a subset of the NMEA-0183 standard for interfacing marine electronic devices as defined by the National Marine Electronics Association (NMEA). See <https://www.nmea.org/> for the NMEA 183 standard.

Author

Javier Arribas, 2012. jarribas(at)cttc.es

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 Definition in file [nmea_printer.h](#).

13.293 nmea_printer.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file nmea_printer.h
00003  * \brief Interface of a NMEA 2.1 printer for GNSS-SDR
00004  * This class provides a implementation of a subset of the NMEA-0183 standard for interfacing
00005  * marine electronic devices as defined by the National Marine Electronics Association (NMEA).
00006  * See https://www.nmea.org/ for the NMEA 183 standard
00007  *
00008  * \author Javier Arribas, 2012. jarribas(at)cttc.es
00009  *
00010  *
00011  * -----
00012  *
00013  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014  * This file is part of GNSS-SDR.
00015  *
00016  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022 #ifndef GNSS_SDR_NMEA_PRINTER_H
00023 #define GNSS_SDR_NMEA_PRINTER_H
00024
00025 #include <boost/date_time/posix_time/ptime.hpp> // for ptime
00026 #include <fstream> // for ofstream
00027 #include <memory> // for shared_ptr
00028 #include <string> // for string
00029
00030 /** \addtogroup PVT
00031  * \{ */
00032 /** \addtogroup PVT_libs
00033  * \{ */
00034
00035
00036 class Rtklib_Solver;
00037
00038 /*!
00039 * \brief This class provides a implementation of a subset of the NMEA-0183 standard for interfacing
00040 * marine electronic devices as defined by the National Marine Electronics Association (NMEA).
00041 *
00042 * See https://en.wikipedia.org/wiki/NMEA_0183
00043 */
00044 class Nmea_Printer
00045 {
00046 public:
00047     /*!
00048     * \brief Default constructor.
00049     */
00050     Nmea_Printer(const std::string& filename, bool flag_nmea_output_file, bool flag_nmea_tty_port,
00051                 std::string nmea_dump_devname, const std::string& base_path = ".");
00052
00053     /*!
00054     * \brief Default destructor.
00055     */
00056     ~Nmea_Printer();
00057
00058     /*!
00059     * \brief Print NMEA PVT and satellite info to the initialized device
00060     */
00061     bool Print_Nmea_Line(const Rtklib_Solver* const pvt_data);
00062
00063     /*!
00064     * \brief Returns GPGGA message (fix data)
00065     */
00066     std::string get_GPGGA(const Rtklib_Solver* const pvt_data) const;
00067
00068     /*!
00069     * \brief Returns GPGSA message (overall satellite reception data)
00070     */
00071     std::string get_GPGSA(const Rtklib_Solver* const pvt_data) const;
00072 private:
00073     int init_serial(const std::string& serial_device); // serial port control
00074     void close_serial() const;
00075     std::string get_GPGGA() const; // fix data
00076     std::string get_GPGSV() const; // satellite data
00077     std::string get_GPGSA() const; // overall satellite reception data
00078     std::string get_GPRMC() const; // minimum recommended data
00079     std::string get_UTC_NMEA_time(const boost::posix_time::ptime d_position_UTC_time) const;
00080     std::string longitude_to_hm(double longitude) const;
00081     std::string latitude_to_hm(double lat) const;
00082     char checksum(const std::string& sentence) const;

```

```

00083
00084     const Rtklib_Solver* d_PVT_data;
00085
00086     std::ofstream nmea_file_descriptor; // Output file stream for NMEA log file
00087
00088     std::string nmea_filename; // String with the NMEA log filename
00089     std::string nmea_base_path;
00090     std::string nmea_devname;
00091
00092     int nmea_dev_descriptor; // NMEA serial device descriptor (i.e. COM port)
00093     bool d_flag_nmea_output_file;
00094 };
00095
00096
00097 /** \} */
00098 /** \} */
00099 #endif // GNSS_SDR_NMEA_PRINTER_H

```

13.294 pvt_conf.h File Reference

Class that contains all the configuration parameters for the PVT block.

```

#include <cstdint>
#include <map>
#include <string>

```

Classes

- class [Pvt_Conf](#)

13.294.1 Detailed Description

Class that contains all the configuration parameters for the PVT block.

Author

Carles Fernandez, 2018. cfernandez(at)cttc.es

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 Definition in file [pvt_conf.h](#).

13.295 pvt_conf.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file pvt_conf.h
00003  * \brief Class that contains all the configuration parameters for the PVT block
00004  * \author Carles Fernandez, 2018. cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_PVT_CONF_H
00018 #define GNSS_SDR_PVT_CONF_H
00019
00020 #include <cstdint>
00021 #include <map>
00022 #include <string>
00023
00024 /** \addtogroup PVT
00025  * \{ */
00026 /** \addtogroup PVT_libs
00027  * \{ */
00028

```

```

00029
00030 class Pvt_Conf
00031 {
00032 public:
00033     std::map<int, int> rtcm_msg_rate_ms;
00034
00035     std::string rinex_name = std::string("-");
00036     std::string dump_filename;
00037     std::string nmea_dump_filename;
00038     std::string nmea_dump_devname;
00039     std::string rtcm_dump_devname;
00040     std::string an_dump_devname;
00041     std::string output_path = std::string(".");
00042     std::string rinex_output_path = std::string(".");
00043     std::string gpx_output_path = std::string(".");
00044     std::string geojson_output_path = std::string(".");
00045     std::string nmea_output_file_path = std::string(".");
00046     std::string kml_output_path = std::string(".");
00047     std::string xml_output_path = std::string(".");
00048     std::string rtcm_output_file_path = std::string(".");
00049     std::string has_output_file_path = std::string(".");
00050     std::string udp_addresses;
00051     std::string udp_ports;
00052     std::string udp_eph_addresses;
00053     std::string log_source_timetag_file;
00054
00055     uint32_t signal_enabled_flags = 0;
00056     uint32_t observable_interval_ms = 20;
00057
00058     int32_t output_rate_ms = 0;
00059     int32_t display_rate_ms = 0;
00060     int32_t kml_rate_ms = 20;
00061     int32_t gpx_rate_ms = 20;
00062     int32_t geojson_rate_ms = 20;
00063     int32_t nmea_rate_ms = 20;
00064     int32_t rinex_version = 0;
00065     int32_t rinexobs_rate_ms = 0;
00066     int32_t an_rate_ms = 20;
00067     int32_t max_obs_block_rx_clock_offset_ms = 40;
00068     int udp_eph_port = 0;
00069     int rtk_trace_level = 0;
00070
00071     uint16_t rtcm_tcp_port = 0;
00072     uint16_t rtcm_station_id = 0;
00073
00074     bool flag_nmea_tty_port = false;
00075     bool flag_rtcm_server = false;
00076     bool flag_rtcm_tty_port = false;
00077     bool output_enabled = true;
00078     bool rinex_output_enabled = true;
00079     bool gpx_output_enabled = true;
00080     bool geojson_output_enabled = true;
00081     bool nmea_output_file_enabled = true;
00082     bool an_output_enabled = false;
00083     bool kml_output_enabled = true;
00084     bool xml_output_enabled = true;
00085     bool rtcm_output_file_enabled = true;
00086     bool monitor_enabled = false;
00087     bool monitor_ephemeris_enabled = false;
00088     bool protobuf_enabled = true;
00089     bool enable_rx_clock_correction = true;
00090     bool show_local_time_zone = false;
00091     bool pre_2009_file = false;
00092     bool dump = false;
00093     bool dump_mat = true;
00094     bool log_source_timetag = false;
00095     bool use_e6_for_pvt = true;
00096     bool use_has_corrections = true;
00097     bool use_unhealthy_sats = false;
00098     bool osnma_strict = false;
00099
00100     // PVT KF parameters
00101     bool enable_pvt_kf = false;
00102     double measures_ecef_pos_sd_m = 1.0;
00103     double measures_ecef_vel_sd_ms = 0.1;
00104     double system_ecef_pos_sd_m = 0.01;
00105     double system_ecef_vel_sd_ms = 0.001;
00106
00107     // Sensor Data parameters
00108     bool kf_use_imu_vel = false;
00109 };
00110
00111
00112 /** \} */
00113 /** \} */
00114 #endif // GNSS_SDR_PVT_CONF_H

```

13.296 pvt_kf.h File Reference

Kalman Filter for Position and Velocity.

```
#include <armadillo>
```

Classes

- class [Pvt_Kf](#)
Kalman Filter for Position and Velocity.

13.296.1 Detailed Description

Kalman Filter for Position and Velocity.

Author

Javier Arribas, 2023. jarribas(at)cttc.es

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Definition in file [pvt_kf.h](#).

13.297 pvt_kf.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file pvt_kf.h
00003  * \brief Kalman Filter for Position and Velocity
00004  * \author Javier Arribas, 2023. jarribas(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2023 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_PVT_KF_H
00019 #define GNSS_SDR_PVT_KF_H
00020
00021 #include <armadillo>
00022
00023 /** \addtogroup PVT
00024  * \{ */
00025 /** \addtogroup PVT_libs
00026  * \{ */
00027
00028
00029 /*!
00030  * \brief Kalman Filter for Position and Velocity
00031  *
00032  */
00033 class Pvt_Kf
00034 {
00035 public:
00036     Pvt_Kf() = default;
00037     virtual ~Pvt_Kf() = default;
00038     void init_Kf(const arma::vec& p,
00039                 const arma::vec& v,
00040                 double update_interval_s,
00041                 double measures_ecef_pos_sd_m,
00042                 double measures_ecef_vel_sd_ms,
00043                 double system_ecef_pos_sd_m,
00044                 double system_ecef_vel_sd_ms);
00045     bool is_initialized() const;
00046     void run_Kf(const arma::vec& p, const arma::vec& v);
00047     void get_pv_Kf(arma::vec& p, arma::vec& v) const;
00048     void reset_Kf();
00049
00050 private:
```

```

00051 // Kalman Filter class variables
00052 arma::mat d_F;
00053 arma::mat d_H;
00054 arma::mat d_R;
00055 arma::mat d_Q;
00056 arma::mat d_P_old_old;
00057 arma::mat d_P_new_old;
00058 arma::mat d_P_new_new;
00059 arma::vec d_x_old_old;
00060 arma::vec d_x_new_old;
00061 arma::vec d_x_new_new;
00062 bool d_initialized{false};
00063 };
00064
00065
00066 /** \} */
00067 /** \} */
00068 #endif // GNSS_SDR_Pvt_Kf_H

```

13.298 pvt_solution.h File Reference

Interface of a base class for a PVT solution.

```

#include <boost/date_time/posix_time/posix_time.hpp>
#include <array>

```

Classes

- class [Pvt_Solution](#)

Base class for a PVT solution.

13.298.1 Detailed Description

Interface of a base class for a PVT solution.

Author

Carles Fernandez-Prades, 2015. cfernandez(at)cttc.es

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 Definition in file [pvt_solution.h](#).

13.299 pvt_solution.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file pvt_solution.h
00003 * \brief Interface of a base class for a PVT solution
00004 * \author Carles Fernandez-Prades, 2015. cfernandez(at)cttc.es
00005 *
00006 *
00007 * -----
00008 *
00009 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013 * SPDX-License-Identifier: GPL-3.0-or-later
00014 *
00015 * -----
00016 */
00017
00018 #ifndef GNSS_SDR_PVT_SOLUTION_H
00019 #define GNSS_SDR_PVT_SOLUTION_H
00020
00021 #include <boost/date_time/posix_time/posix_time.hpp>
00022 #include <array>
00023
00024 /** \addtogroup PVT
00025 * \{ */
00026 /** \addtogroup PVT_libs
00027 * \{ */

```

```

00028
00029
00030 /*!
00031  * \brief Base class for a PVT solution
00032  *
00033  */
00034 class Pvt_Solution
00035 {
00036 public:
00037     Pvt_Solution() = default;
00038     virtual ~Pvt_Solution() = default;
00039
00040     virtual double get_hdop() const = 0;
00041     virtual double get_vdop() const = 0;
00042     virtual double get_pdop() const = 0;
00043     virtual double get_gdop() const = 0;
00044
00045     std::array<double, 3> get_rx_pos() const;
00046     std::array<double, 3> get_rx_vel() const;
00047     boost::posix_time::ptime get_position_UTC_time() const;
00048     double get_latitude() const;          ///< Get RX position Latitude WGS84 [deg]
00049     double get_longitude() const;         ///< Get RX position Longitude WGS84 [deg]
00050     double get_height() const;            ///< Get RX position height WGS84 [m]
00051     double get_time_offset_s() const;     ///< Get RX time offset [s]
00052     double get_clock_drift_ppm() const;   ///< Get the Rx clock drift [ppm]
00053     double get_speed_over_ground() const; ///< Get RX speed over ground [m/s]
00054     double get_course_over_ground() const; ///< Get RX course over ground [deg]
00055     int get_num_valid_observations() const; ///< Get the number of valid pseudorange observations
00056     (valid satellites)
00057     bool is_pre_2009() const;
00058     bool is_valid_position() const;
00059     void set_rx_pos(const std::array<double, 3> &pos); ///< Set position: X, Y, Z in Cartesian ECEF
00060     void set_rx_vel(const std::array<double, 3> &vel); ///< Set velocity: East [m/s], North [m/s], Up
00061     void set_position_UTC_time(const boost::posix_time::ptime &pt);
00062     void set_time_offset_s(double offset);          ///< Set RX time offset [s]
00063     void set_clock_drift_ppm(double clock_drift_ppm); ///< Set the Rx clock drift [ppm]
00064     void set_speed_over_ground(double speed_m_s);   ///< Set RX speed over ground [m/s]
00065     void set_course_over_ground(double cog_deg);    ///< Set RX course over ground [deg]
00066     void set_valid_position(bool is_valid);
00067     void set_num_valid_observations(int num);        ///< Set the number of valid pseudorange observations
00068     (valid satellites)
00069     void set_pre_2009_file(bool pre_2009_file);    ///< Flag for the week rollover computation in post
00070     processing mode for signals older than 2009
00071 private:
00072     /*
00073      * Conversion of Cartesian coordinates (X,Y,Z) to geographical
00074      * coordinates (d_latitude_d, d_longitude_d, d_height_m) on a selected reference ellipsoid.
00075      *
00076      * \param[in] X [m] Cartesian coordinate
00077      * \param[in] Y [m] Cartesian coordinate
00078      * \param[in] Z [m] Cartesian coordinate
00079      * \param[in] ellipsoid_selection. Choices of Reference Ellipsoid for Geographical Coordinates:
00080      * 0 - International Ellipsoid 1924.
00081      * 1 - International Ellipsoid 1967.
00082      * 2 - World Geodetic System 1972.
00083      * 3 - Geodetic Reference System 1980.
00084      * 4 - World Geodetic System 1984.
00085      */
00086     int cart2geo(double X, double Y, double Z, int ellipsoid_selection);
00087
00088     std::array<double, 3> d_rx_pos{};
00089     std::array<double, 3> d_rx_vel{};
00090     boost::posix_time::ptime d_position_UTC_time;
00091
00092     double d_latitude_d{0.0};          // RX position Latitude WGS84 [deg]
00093     double d_longitude_d{0.0};         // RX position Longitude WGS84 [deg]
00094     double d_height_m{0.0};            // RX position height WGS84 [m]
00095     double d_rx_dt_s{0.0};            // RX time offset [s]
00096     double d_rx_clock_drift_ppm{0.0};  // RX clock drift [ppm]
00097     double d_speed_over_ground_m_s{0.0}; // RX speed over ground [m/s]
00098     double d_course_over_ground_d{0.0}; // RX course over ground [deg]
00099
00100     int d_valid_observations{0}; // Number of valid observations in this epoch
00101
00102     bool d_pre_2009_file{false}; // Flag to correct week rollover in post processing mode for signals
00103     older than 2009
00104     bool d_valid_position{false};
00105 };
00106
00107 /** \} */
00108 /** \} */

```

```
00109 #endif // GNSS_SDR_PVT_SOLUTION_H
```

13.300 rinex_printer.h File Reference

Interface of a RINEX 2.11 / 3.01 printer See <ftp://igs.org/pub/data/format/rinex301.pdf>.

```
#include "signal_enabled_flags.h"
#include <boost/date_time/posix_time/posix_time.hpp>
#include <cstdint>
#include <cstdlib>
#include <fstream>
#include <map>
#include <string>
#include <vector>
```

Classes

- class [Rinex_Printer](#)

Class that handles the generation of Receiver INdependent EXchange format (RINEX) files.

13.300.1 Detailed Description

Interface of a RINEX 2.11 / 3.01 printer See <ftp://igs.org/pub/data/format/rinex301.pdf>.

Receiver Independent EXchange Format (RINEX): The first proposal for the Receiver Independent Exchange Format RINEX was developed by the Astronomical Institute of the University of Berne for the easy exchange of the GPS data to be collected during the large European GPS campaign EUREF 89, which involved more than 60 GPS receivers of 4 different manufacturers. The governing aspect during the development was the fact that most geodetic processing software for GPS data use a well-defined set of observables: 1) The carrier-phase measurement at one or both carriers (actually being a measurement on the beat frequency between the received carrier of the satellite signal and a receiver-generated reference frequency). 2) The pseudorange (code) measurement, equivalent to the difference of the time of reception (expressed in the time frame of the receiver) and the time of transmission (expressed in the time frame of the satellite) of a distinct satellite signal. 3) The observation time being the reading of the receiver clock at the instant of validity of the carrier-phase and/or the code measurements. Note: A collection of the formats currently used by the IGS can be found here: <https://igs.org/formats-and-standards/>

Author

Carles Fernandez Prades, 2011-2026. [cfernandez\(at\)cttc.es](mailto:cfernandez(at)cttc.es)

Mathieu Favreau, 2025-2026. [favreau.mathieu\(at\)hotmail.com](mailto:favreau.mathieu(at)hotmail.com)

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 Definition in file [rinex_printer.h](#).

13.301 rinex_printer.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rinex_printer.h
00003  * \brief Interface of a RINEX 2.11 / 3.01 printer
00004  * See ftp://igs.org/pub/data/format/rinex301.pdf
00005  *
00006  * Receiver Independent EXchange Format (RINEX):
00007  * The first proposal for the Receiver Independent Exchange Format RINEX
00008  * was developed by the Astronomical Institute of the University of Berne
00009  * for the easy exchange of the GPS data to be collected during the large
00010  * European GPS campaign EUREF 89, which involved more than 60 GPS receivers
00011  * of 4 different manufacturers.
00012  * The governing aspect during the development was the fact that most geodetic
00013  * processing software for GPS data use a well-defined set of observables:
00014  * 1) The carrier-phase measurement at one or both carriers (actually being a
00015  * measurement on the beat frequency between the received carrier of the
00016  * satellite signal and a receiver-generated reference frequency).
```

```

00017 * 2) The pseudorange (code) measurement , equivalent to the difference
00018 * of the time of reception (expressed in the time frame of the receiver)
00019 * and the time of transmission (expressed in the time frame of the satellite)
00020 * of a distinct satellite signal.
00021 * 3) The observation time being the reading of the receiver clock at the
00022 * instant of validity of the carrier-phase and/or the code measurements.
00023 * Note: A collection of the formats currently used by the IGS can be found
00024 * here: https://igs.org/formats-and-standards/
00025 * \author Carles Fernandez Prades, 2011-2026. cfernandez(at)cttc.es
00026 * \author Mathieu Favreau, 2025-2026. favreau.mathieu(at)hotmail.com
00027 *
00028 * -----
00029 *
00030 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00031 * This file is part of GNSS-SDR.
00032 *
00033 * Copyright (C) 2010-2026 (see AUTHORS file for a list of contributors)
00034 * SPDX-License-Identifier: GPL-3.0-or-later
00035 *
00036 * -----
00037 */
00038
00039 #ifndef GNSS_SDR_RINEX_PRINTER_H
00040 #define GNSS_SDR_RINEX_PRINTER_H
00041
00042 #include "signal_enabled_flags.h"
00043 #include <boost/date_time/posix_time/posix_time.hpp>
00044 #include <cstdint> // for int32_t
00045 #include <cstdlib> // for strtol, strtod
00046 #include <fstream> // for fstream
00047 #include <map> // for map
00048 #include <string> // for string
00049 #include <vector> // for vector
00050
00051
00052 /** \addtogroup PVT
00053 * \{ */
00054 /** \addtogroup PVT_libs
00055 * \{ */
00056
00057
00058 class Beidou_Dnav_Ephemeris;
00059 class Beidou_Dnav_Iono;
00060 class Beidou_Dnav_Utc_Model;
00061 class Galileo_Ephemeris;
00062 class Galileo_Iono;
00063 class Galileo_Utc_Model;
00064 class Glonass_Gnav_Almanac;
00065 class Glonass_Gnav_Ephemeris;
00066 class Glonass_Gnav_Utc_Model;
00067 class Gnss_Synchro;
00068 class Gps_CNAV_Ephemeris;
00069 class Gps_CNAV_Iono;
00070 class Gps_CNAV_Utc_Model;
00071 class Gps_Ephemeris;
00072 class Gps_Iono;
00073 class Gps_Navigation_Message;
00074 class Gps_Utc_Model;
00075 class Rtklib_Solver;
00076
00077
00078 /*!
00079 * \brief Class that handles the generation of Receiver
00080 * INdependent EXchange format (RINEX) files
00081 */
00082 class Rinex_Printer
00083 {
00084 public:
00085     /*!
00086     * \brief Constructor. Creates GNSS Navigation and Observables RINEX files.
00087     */
00088     explicit Rinex_Printer(uint32_t signal_enabled_flags,
00089         int version = 3,
00090         const std::string& base_path = ".",
00091         const std::string& base_name = "-",
00092         bool pre_2009_file = false);
00093
00094     /*!
00095     * \brief Destructor. Removes created files if empty.
00096     */
00097     ~Rinex_Printer();
00098
00099     /*!
00100     * \brief Print RINEX annotation. If it is the first annotation, it also
00101     * prints the RINEX headers for navigation and observation files. If it is
00102     * not the first annotation, it only annotates the observation, and updates
00103     * the navigation header if UTC data was not available when writing it for

```



```

00104     * the first time.
00105     *
00106     */
00107 void print_rinex_annotation(const Rtklib_Solver* pvt_solver,
00108     const std::map<int, Gnss_Synchro>& gnss_observables_map,
00109     double rx_time,
00110     bool flag_write_RINEX_obs_output);
00111
00112     /*!
00113     * \brief Print RINEX annotation for GPS NAV message
00114     */
00115 void log_rinex_nav_gps_nav(const std::map<int32_t, Gps_Ephemeris>& new_eph);
00116
00117     /*!
00118     * \brief Print RINEX annotation for GPS CNAV message
00119     */
00120 void log_rinex_nav_gps_cnav(const std::map<int32_t, Gps_CNAV_Ephemeris>& new_cnav_eph);
00121
00122     /*!
00123     * \brief Print RINEX annotation for Galileo NAV message
00124     */
00125 void log_rinex_nav_gal_nav(const std::map<int32_t, Galileo_Ephemeris>& new_gal_eph);
00126
00127     /*!
00128     * \brief Print RINEX annotation for Glonass GNAV message
00129     */
00130 void log_rinex_nav_glo_gnav(const std::map<int32_t, Glonass_Gnav_Ephemeris>& new_glo_eph);
00131
00132     /*!
00133     * \brief Print RINEX annotation for BeiDou DNAV message
00134     */
00135 void log_rinex_nav_bds_dnav(const std::map<int32_t, Beidou_Dnav_Ephemeris>& new_bds_eph);
00136
00137     /*!
00138     * \brief Returns true is the RINEX file headers are already written
00139     */
00140 inline bool is_rinex_header_written() const
00141 {
00142     return d_rinex_header_written;
00143 }
00144
00145     /*!
00146     * \brief Returns name of RINEX navigation file(s)
00147     */
00148 inline std::vector<std::string> get_navfilename() const
00149 {
00150     return output_navfilename;
00151 }
00152
00153     /*!
00154     * \brief Returns name of RINEX observation file
00155     */
00156 inline std::string get_obsfilename() const
00157 {
00158     return obsfilename;
00159 }
00160
00161 private:
00162 // Not the best, but reorder params to select the correct constructor
00163 explicit Rinex_Printer(uint32_t signal_enabled_flags,
00164     const std::string& base_name,
00165     const std::string& base_rinex_path,
00166     int version,
00167     bool pre_2009_file);
00168
00169     /*
00170     * Generates the GPS Observation data header
00171     */
00172 void rinex_obs_header(std::fstream& out,
00173     const std::string& time_constellation,
00174     const boost::posix_time::ptime& system_time,
00175     double seconds);
00176
00177     /*
00178     * Generates the Navigation Data header
00179     */
00180 void rinex_nav_header(std::fstream& out,
00181     const std::vector<std::string>& iono_lines,
00182     const std::vector<std::string>& time_corr_lines,
00183     const std::string& leap_second_line) const;
00184
00185     /*
00186     * Computes the BDS Time and returns a boost::posix_time::ptime object
00187     * \details Function used to convert the observation time into BDT time which is used
00188     * as the default time for RINEX files
00189     * \param eph BeiDou DNAV Ephemeris object
00190

```

```

00191     * \param obs_time Observation time in BDT seconds of week
00192     */
00193     boost::posix_time::ptime compute_BDS_time(const Beidou_Dnav_Ephemeris& eph, double obs_time)
const;
00194
00195     /*
00196     * Computes the UTC time and returns a boost::posix_time::ptime object
00197     */
00198     boost::posix_time::ptime compute_UTC_time(const Gps_Navigation_Message& nav_msg) const;
00199
00200     /*
00201     * Computes the GPS time and returns a boost::posix_time::ptime object
00202     */
00203     boost::posix_time::ptime compute_GPS_time(const Gps_Ephemeris& eph, double obs_time) const;
00204
00205     /*
00206     * Computes the GPS time and returns a boost::posix_time::ptime object
00207     */
00208     boost::posix_time::ptime compute_GPS_time(const Gps_CNAV_Ephemeris& eph, double obs_time) const;
00209
00210     /*
00211     * Computes the Galileo time and returns a boost::posix_time::ptime object
00212     */
00213     boost::posix_time::ptime compute_Galileo_time(const Galileo_Ephemeris& eph, double obs_time)
const;
00214
00215     /*
00216     * Computes the UTC Time and returns a boost::posix_time::ptime object
00217     * \details Function used as a method to convert the observation time into UTC time which is used
00218     * as the default time for RINEX files
00219     * \param eph GLONASS GNAV Ephemeris object
00220     * \param obs_time Observation time in GPS seconds of week
00221     */
00222     boost::posix_time::ptime compute_UTC_time(const Glonass_Gnav_Ephemeris& eph, double obs_time)
const;
00223
00224     /*
00225     * Represents GPS time in the date time format. Leap years are considered, but leap seconds are
not.
00226     */
00227     void to_date_time(int gps_week,
00228         int gps_tow,
00229         int& year,
00230         int& month,
00231         int& day,
00232         int& hour,
00233         int& minute,
00234         int& second) const;
00235
00236     void update_obs_header(std::fstream& out, const std::string& leap_second_line) const;
00237
00238     const std::map<std::string, std::string> observationType; // PSEUDORANGE, CARRIER_PHASE, DOPPLER,
SIGNAL_STRENGTH
00239     const std::map<std::string, std::string> observationCode; // GNSS observation descriptors
00240
00241     const Signal_Enabled_Flags d_flags;
00242
00243     const int d_version; // RINEX version (2 for 2.10/2.11 and 3 for 3.01)
00244     const std::string d_stringVersion; // RINEX version (2.10/2.11 or 3.01/3.02)
00245
00246     double d_fake_cnav_iode;
00247     bool d_rinex_header_updated;
00248     bool d_rinex_header_gps_updated;
00249     bool d_rinex_header_galileo_updated;
00250     bool d_rinex_header_glonass_updated;
00251     bool d_rinex_header_beidou_updated;
00252     bool d_rinex_header_written;
00253     const bool d_pre_2009_file;
00254
00255     const std::string navfilename; // Name of RINEX navigation file
00256     const std::string obsfilename; // Name of RINEX observation file
00257     const std::string navGlofilename; // Name of RINEX navigation file for Glonass
00258     std::vector<std::string> output_navfilename; // Name of output RINEX navigation file(s)
00259
00260     std::fstream obsFile; // Output file stream for RINEX observation file
00261     std::fstream navFile; // Output file stream for RINEX navigation data file
00262     std::fstream navGloFile; // Output file stream for RINEX GLONASS navigation data file
00263 };
00264
00265
00266 /** \} */
00267 /** \} */
00268 #endif // GNSS_SDR_RINEX_PRINTER_H

```

13.302 rtcm.h File Reference

Interface for the RTCM 3.2 Standard.

```
#include "concurrent_queue.h"
#include "galileo_ephemeris.h"
#include "galileo_has_data.h"
#include "glonass_gnav_ephemeris.h"
#include "glonass_gnav_utc_model.h"
#include "gnss_synchro.h"
#include "gps_cnav_ephemeris.h"
#include "gps_ephemeris.h"
#include <boost/asio.hpp>
#include <boost/date_time/posix_time/posix_time.hpp>
#include <algorithm>
#include <array>
#include <bitset>
#include <cstdint>
#include <cstdint>
#include <deque>
#include <iomanip>
#include <list>
#include <map>
#include <memory>
#include <set>
#include <sstream>
#include <string>
#include <thread>
#include <utility>
#include <vector>
#include <absl/log/log.h>
```

Classes

- class [Rtcm](#)

This class implements the generation and reading of some Message Types defined in the RTCM 3.2 Standard, plus some utilities to handle messages.

Typedefs

- using [b_io_context](#) = boost::asio::io_service

13.302.1 Detailed Description

Interface for the RTCM 3.2 Standard.

Author

Carles Fernandez-Prades, 2015. cfernandez(at)cttc.es

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Definition in file [rtcm.h](#).

13.303 rtcm.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtcm.h
00003  * \brief Interface for the RTCM 3.2 Standard
00004  * \author Carles Fernandez-Prades, 2015. cfernandez(at)cttc.es
```

```

00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_RTCM_H
00019 #define GNSS_SDR_RTCM_H
00020
00021
00022 #include "concurrent_queue.h"
00023 #include "galileo_ephemeris.h"
00024 #include "galileo_has_data.h"
00025 #include "glonass_gnav_ephemeris.h"
00026 #include "glonass_gnav_utc_model.h"
00027 #include "gnss_synchro.h"
00028 #include "gps_cnav_ephemeris.h"
00029 #include "gps_ephemeris.h"
00030 #include <boost/asio.hpp>
00031 #include <boost/date_time/posix_time/posix_time.hpp>
00032 #include <algorithm> // for std::max, std::min, std::copy_n
00033 #include <array>
00034 #include <bitset>
00035 #include <cstdint> // for size_t
00036 #include <cstdint>
00037 #include <deque>
00038 #include <iomanip> // for std::setw
00039 #include <list>
00040 #include <map>
00041 #include <memory>
00042 #include <set>
00043 #include <sstream> // for std::stringstream
00044 #include <string>
00045 #include <thread>
00046 #include <utility>
00047 #include <vector>
00048
00049 #if USE_GLOG_AND_GFLAGS
00050 #include <glog/logging.h>
00051 #else
00052 #include <absl/log/log.h>
00053 #endif
00054
00055 /** \addtogroup PVT
00056  * \{ */
00057 /** \addtogroup PVT_libs
00058  * \{ */
00059
00060
00061 #if USE_BOOST_ASIO_IO_CONTEXT
00062 using b_io_context = boost::asio::io_context;
00063 #else
00064 using b_io_context = boost::asio::io_service;
00065 #endif
00066
00067
00068 /*!
00069  * \brief This class implements the generation and reading of some Message Types
00070  * defined in the RTCM 3.2 Standard, plus some utilities to handle messages.
00071  *
00072  * Generation of the following Message Types:
00073  * 1001, 1002, 1003, 1004, 1005, 1006, 1008, 1019, 1020, 1029, 1045
00074  *
00075  * Decoding of the following Message Types:
00076  * 1019, 1045
00077  *
00078  * Generation of the following Multiple Signal Messages:
00079  * MSM1 (message types 1071, 1091)
00080  * MSM2 (message types 1072, 1092)
00081  * MSM3 (message types 1073, 1093)
00082  * MSM4 (message types 1074, 1094)
00083  * MSM5 (message types 1075, 1095)
00084  * MSM6 (message types 1076, 1096)
00085  * MSM7 (message types 1077, 1097)
00086  *
00087  * RTCM 3 message format (size in bits):
00088  * +-----+-----+-----+-----+-----+-----+
00089  * | preamble | 000000 | length | data message | parity |
00090  * +-----+-----+-----+-----+-----+-----+
00091  * |<-- 8 --->|<-- 6 --->|<-- 10 --->|<-- length x 8 --->|<-- 24 --->|

```

```

00092 * +-----+-----+-----+-----+-----+
00093 *
00094 *
00095 * (C) Carles Fernandez-Prades, 2015. cfernandez(at)cttc.es
00096 */
00097 class RtcM
00098 {
00099 public:
00100     explicit RtcM(uint16_t port = 2101); //!< Default constructor that sets TCP port of the RTCM
message server and RTCM Station ID. 2101 is the standard RTCM port according to the Internet Assigned
Numbers Authority (IANA). See
https://www.iana.org/assignments/service-names-port-numbers/service-names-port-numbers.xml
00101     ~RtcM();
00102
00103     /*!
00104      * \brief Prints message type 1001 (L1-Only GPS RTK Observables)
00105      */
00106     std::string print_MT1001(const Gps_Ephemeris& gps_eph, double obs_time, const std::map<int32_t,
Gnss_Synchro>& observables, uint16_t station_id);
00107
00108     /*!
00109      * \brief Prints message type 1002 (Extended L1-Only GPS RTK Observables)
00110      */
00111     std::string print_MT1002(const Gps_Ephemeris& gps_eph, double obs_time, const std::map<int32_t,
Gnss_Synchro>& observables, uint16_t station_id);
00112
00113     /*!
00114      * \brief Prints message type 1003 (L1 & L2 GPS RTK Observables)
00115      */
00116     std::string print_MT1003(const Gps_Ephemeris& ephL1, const Gps_CNAV_Ephemeris& ephL2, double
obs_time, const std::map<int32_t, Gnss_Synchro>& observables, uint16_t station_id);
00117
00118     /*!
00119      * \brief Prints message type 1004 (Extended L1 & L2 GPS RTK Observables)
00120      */
00121     std::string print_MT1004(const Gps_Ephemeris& ephL1, const Gps_CNAV_Ephemeris& ephL2, double
obs_time, const std::map<int32_t, Gnss_Synchro>& observables, uint16_t station_id);
00122
00123     /*!
00124      * \brief Prints message type 1005 (Stationary Antenna Reference Point)
00125      */
00126     std::string print_MT1005(uint32_t ref_id, double ecef_x, double ecef_y, double ecef_z, bool gps,
bool glonass, bool galileo, bool non_physical, bool single_oscillator, uint32_t
quarter_cycle_indicator);
00127
00128     /*!
00129      * \brief Verifies and reads messages of type 1005 (Stationary Antenna Reference Point). Returns 1
if anything goes wrong, 0 otherwise.
00130      */
00131     int32_t read_MT1005(const std::string& message, uint32_t& ref_id, double& ecef_x, double& ecef_y,
double& ecef_z, bool& gps, bool& glonass, bool& galileo);
00132
00133     /*!
00134      * \brief Prints message type 1006 (Stationary Antenna Reference Point, with Height Information)
00135      */
00136     std::string print_MT1006(uint32_t ref_id, double ecef_x, double ecef_y, double ecef_z, bool gps,
bool glonass, bool galileo, bool non_physical, bool single_oscillator, uint32_t
quarter_cycle_indicator, double height);
00137
00138     std::string print_MT1005_test(); //!< For testing purposes
00139
00140     /*!
00141      * \brief Prints message type 1008 (Antenna Descriptor & Serial Number)
00142      */
00143     std::string print_MT1008(uint32_t ref_id, const std::string& antenna_descriptor, uint32_t
antenna_setup_id, const std::string& antenna_serial_number);
00144
00145     /*!
00146      * \brief Prints L1-Only GLONASS RTK Observables
00147      * \details This GLONASS message type is not generally used or supported; type 1012 is to be
preferred.
00148      * \note Code added as part of GSoC 2017 program
00149      * \param glonass_gnav_eph GLONASS GNAV Broadcast Ephemeris
00150      * \param obs_time Time of observation at the moment of printing
00151      * \param observables Set of observables as defined by the platform
00152      * \return string with message contents
00153      */
00154     std::string print_MT1009(const Glonass_Gnav_Ephemeris& glonass_gnav_eph, double obs_time, const
std::map<int32_t, Gnss_Synchro>& observables, uint16_t station_id);
00155
00156     /*!
00157      * \brief Prints Extended L1-Only GLONASS RTK Observables
00158      * \details This GLONASS message type is used when only L1 data is present and bandwidth is very
tight, often 1012 is used in such cases.
00159      * \note Code added as part of GSoC 2017 program
00160      * \param glonass_gnav_eph GLONASS GNAV Broadcast Ephemeris
00161      * \param obs_time Time of observation at the moment of printing

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00162     * \param observables Set of observables as defined by the platform
00163     * \return string with message contents
00164     */
00165     std::string print_MT1010(const Glonass_Gnav_Ephemeris& glonass_gnav_eph, double obs_time, const
std::map<int32_t, Gnss_Synchro>& observables, uint16_t station_id);
00166
00167     /*!
00168     * \brief Prints L1&L2 GLONASS RTK Observables
00169     * \details This GLONASS message type is not generally used or supported; type 1012 is to be
preferred
00170     * \note Code added as part of GSoC 2017 program
00171     * \param glonass_gnav_eph GLONASS GNAV Broadcast Ephemeris
00172     * \param obs_time Time of observation at the moment of printing
00173     * \param observables Set of observables as defined by the platform
00174     * \return string with message contents
00175     */
00176     std::string print_MT1011(const Glonass_Gnav_Ephemeris& glonass_gnav_ephL1, const
Glonass_Gnav_Ephemeris& glonass_gnav_ephL2, double obs_time, const std::map<int32_t, Gnss_Synchro>&
observables, uint16_t station_id);
00177
00178     /*!
00179     * \brief Prints Extended L1&L2 GLONASS RTK Observables
00180     * \details This GLONASS message type is the most common observational message type, with
L1/L2/SNR content. This is one of the most common messages found.
00181     * \note Code added as part of GSoC 2017 program
00182     * \param glonass_gnav_eph GLONASS GNAV Broadcast Ephemeris
00183     * \param obs_time Time of observation at the moment of printing
00184     * \param observables Set of observables as defined by the platform
00185     * \return string with message contents
00186     */
00187     std::string print_MT1012(const Glonass_Gnav_Ephemeris& glonass_gnav_ephL1, const
Glonass_Gnav_Ephemeris& glonass_gnav_ephL2, double obs_time, const std::map<int32_t, Gnss_Synchro>&
observables, uint16_t station_id);
00188
00189     /*!
00190     * \brief Prints message type 1019 (GPS Ephemeris), should be broadcast in the event that
the IODC does not match the IODE, and every 2 minutes.
00191     */
00192     std::string print_MT1019(const Gps_Ephemeris& gps_eph);
00193
00194     /*!
00195     * \brief Verifies and reads messages of type 1019 (GPS Ephemeris). Returns 1 if anything goes
wrong, 0 otherwise.
00196     */
00197     int32_t read_MT1019(const std::string& message, Gps_Ephemeris& gps_eph) const;
00198
00199     /*!
00200     * \brief Prints message type 1020 (GLONASS Ephemeris).
00201     * \note Code added as part of GSoC 2017 program
00202     * \param glonass_gnav_eph GLONASS GNAV Broadcast Ephemeris
00203     * \param glonass_gnav_utc_model GLONASS GNAV Clock Information
00204     * \return Returns message type as a string type
00205     */
00206     std::string print_MT1020(const Glonass_Gnav_Ephemeris& glonass_gnav_eph, const
Glonass_Gnav_Utc_Model& glonass_gnav_utc_model);
00207
00208     /*!
00209     * \brief Verifies and reads messages of type 1020 (GLONASS Ephemeris).
00210     * \note Code added as part of GSoC 2017 program
00211     * \param message Message to read as a string type
00212     * \param glonass_gnav_eph GLONASS GNAV Broadcast Ephemeris
00213     * \param glonass_gnav_utc_model GLONASS GNAV Clock Information
00214     * \return Returns 1 if anything goes wrong, 0 otherwise.
00215     */
00216     int32_t read_MT1020(const std::string& message, Glonass_Gnav_Ephemeris& glonass_gnav_eph,
Glonass_Gnav_Utc_Model& glonass_gnav_utc_model) const;
00217
00218     /*!
00219     * \brief Prints message type 1029 (Unicode Text String)
00220     */
00221     std::string print_MT1029(uint32_t ref_id, const Gps_Ephemeris& gps_eph, double obs_time, const
std::string& message);
00222
00223     /*!
00224     * \brief Prints message type 1045 (Galileo Ephemeris), should be broadcast every 2 minutes
00225     */
00226     std::string print_MT1045(const Galileo_Ephemeris& gal_eph);
00227
00228     /*!
00229     * \brief Verifies and reads messages of type 1045 (Galileo Ephemeris). Returns 1 if anything goes
wrong, 0 otherwise.
00230     */
00231     int32_t read_MT1045(const std::string& message, Galileo_Ephemeris& gal_eph) const;
00232
00233     /*!
00234     * \brief Prints messages of type MSM1 (Compact GNSS observables)
00235     */
00236

```

```

00237     std::string print_MSM_1(const Gps_Ephemeris& gps_eph,
00238         const Gps_CNAV_Ephemeris& gps_cnav_eph,
00239         const Galileo_Ephemeris& gal_eph,
00240         const Glonass_Gnav_Ephemeris& glo_gnav_eph,
00241         double obs_time,
00242         const std::map<int32_t, Gnss_Synchro>& observables,
00243         uint32_t ref_id,
00244         uint32_t clock_steering_indicator,
00245         uint32_t external_clock_indicator,
00246         int32_t smooth_int,
00247         bool divergence_free,
00248         bool more_messages);
00249
00250     /*!
00251     * \brief Prints messages of type MSM2 (Compact GNSS phaseranges)
00252     */
00253     std::string print_MSM_2(const Gps_Ephemeris& gps_eph,
00254         const Gps_CNAV_Ephemeris& gps_cnav_eph,
00255         const Galileo_Ephemeris& gal_eph,
00256         const Glonass_Gnav_Ephemeris& glo_gnav_eph,
00257         double obs_time,
00258         const std::map<int32_t, Gnss_Synchro>& observables,
00259         uint32_t ref_id,
00260         uint32_t clock_steering_indicator,
00261         uint32_t external_clock_indicator,
00262         int32_t smooth_int,
00263         bool divergence_free,
00264         bool more_messages);
00265
00266     /*!
00267     * \brief Prints messages of type MSM3 (Compact GNSS pseudoranges and phaseranges)
00268     */
00269     std::string print_MSM_3(const Gps_Ephemeris& gps_eph,
00270         const Gps_CNAV_Ephemeris& gps_cnav_eph,
00271         const Galileo_Ephemeris& gal_eph,
00272         const Glonass_Gnav_Ephemeris& glo_gnav_eph,
00273         double obs_time,
00274         const std::map<int32_t, Gnss_Synchro>& observables,
00275         uint32_t ref_id,
00276         uint32_t clock_steering_indicator,
00277         uint32_t external_clock_indicator,
00278         int32_t smooth_int,
00279         bool divergence_free,
00280         bool more_messages);
00281
00282     /*!
00283     * \brief Prints messages of type MSM4 (Full GNSS pseudoranges and phaseranges plus CNR)
00284     */
00285     std::string print_MSM_4(const Gps_Ephemeris& gps_eph,
00286         const Gps_CNAV_Ephemeris& gps_cnav_eph,
00287         const Galileo_Ephemeris& gal_eph,
00288         const Glonass_Gnav_Ephemeris& glo_gnav_eph,
00289         double obs_time,
00290         const std::map<int32_t, Gnss_Synchro>& observables,
00291         uint32_t ref_id,
00292         uint32_t clock_steering_indicator,
00293         uint32_t external_clock_indicator,
00294         int32_t smooth_int,
00295         bool divergence_free,
00296         bool more_messages);
00297
00298     /*!
00299     * \brief Prints messages of type MSM5 (Full GNSS pseudoranges, phaseranges, phaserange rate and
00300     CNR)
00301     */
00301     std::string print_MSM_5(const Gps_Ephemeris& gps_eph,
00302         const Gps_CNAV_Ephemeris& gps_cnav_eph,
00303         const Galileo_Ephemeris& gal_eph,
00304         const Glonass_Gnav_Ephemeris& glo_gnav_eph,
00305         double obs_time,
00306         const std::map<int32_t, Gnss_Synchro>& observables,
00307         uint32_t ref_id,
00308         uint32_t clock_steering_indicator,
00309         uint32_t external_clock_indicator,
00310         int32_t smooth_int,
00311         bool divergence_free,
00312         bool more_messages);
00313
00314     /*!
00315     * \brief Prints messages of type MSM6 (Full GNSS pseudoranges and phaseranges plus CNR, high
00316     resolution)
00317     */
00317     std::string print_MSM_6(const Gps_Ephemeris& gps_eph,
00318         const Gps_CNAV_Ephemeris& gps_cnav_eph,
00319         const Galileo_Ephemeris& gal_eph,
00320         const Glonass_Gnav_Ephemeris& glo_gnav_eph,
00321         double obs_time,

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00395     void run_server();    ///< Starts running the server
00396     void stop_server();   ///< Stops the server
00397
00398     void send_message(const std::string& msg);    ///< Sends a message through the server to all
connected clients
00399     bool is_server_running() const;              ///< Returns true if the server is running, false
otherwise
00400
00401 private:
00402     //
00403     // Generation of messages content
00404     //
00405     std::bitset<64> get_MT1001_4_header(uint32_t msg_number,
00406         double obs_time,
00407         const std::map<int32_t, Gnss_Synchro>& observables,
00408         uint32_t ref_id,
00409         uint32_t smooth_int,
00410         bool sync_flag,
00411         bool divergence_free);
00412
00413     std::bitset<58> get_MT1001_sat_content(const Gps_Ephemeris& eph, double obs_time, const
Gnss_Synchro& gnss_synchro);
00414     std::bitset<74> get_MT1002_sat_content(const Gps_Ephemeris& eph, double obs_time, const
Gnss_Synchro& gnss_synchro);
00415     std::bitset<101> get_MT1003_sat_content(const Gps_Ephemeris& ephL1, const Gps_CNAV_Ephemeris&
ephL2, double obs_time, const Gnss_Synchro& gnss_synchroL1, const Gnss_Synchro& gnss_synchroL2);
00416     std::bitset<125> get_MT1004_sat_content(const Gps_Ephemeris& ephL1, const Gps_CNAV_Ephemeris&
ephL2, double obs_time, const Gnss_Synchro& gnss_synchroL1, const Gnss_Synchro& gnss_synchroL2);
00417
00418     std::bitset<152> get_MT1005_test();
00419
00420     /*!
00421     * \brief Generates contents of message header for types 1009, 1010, 1011 and 1012. GLONASS RTK
Message
00422     * \note Code added as part of GSoC 2017 program
00423     * \param msg_number Message type number, acceptable options include 1009 to 1012
00424     * \param obs_time Time of observation at the moment of printing
00425     * \param observables Set of observables as defined by the platform
00426     * \param ref_id
00427     * \param smooth_int
00428     * \param divergence_free
00429     * \return Returns the message header content as set of bits
00430     */
00431     std::bitset<61> get_MT1009_12_header(uint32_t msg_number,
00432         double obs_time,
00433         const std::map<int32_t, Gnss_Synchro>& observables,
00434         uint32_t ref_id,
00435         uint32_t smooth_int,
00436         bool sync_flag,
00437         bool divergence_free);
00438
00439     /*!
00440     * \brief Get the contents of the satellite specific portion of a type 1009 Message (GLONASS Basic
RTK, L1 Only)
00441     * \details Contents generated for each satellite. See table 3.5-11
00442     * \note Code added as part of GSoC 2017 program
00443     * \param ephGNAV Ephemeris for GLONASS GNAV in L1 satellites
00444     * \param obs_time Time of observation at the moment of printing
00445     * \param gnss_synchro Information generated by channels while processing the satellite
00446     * \return Returns the message content as set of bits
00447     */
00448     std::bitset<64> get_MT1009_sat_content(const Glonass_Gnav_Ephemeris& ephGNAV, double obs_time,
const Gnss_Synchro& gnss_synchro);
00449     /*!
00450     * \brief Get the contents of the satellite specific portion of a type 1010 Message (GLONASS
Extended RTK, L1 Only)
00451     * \details Contents generated for each satellite. See table 3.5-12
00452     * \note Code added as part of GSoC 2017 program
00453     * \param ephGNAV Ephemeris for GLONASS GNAV in L1 satellites
00454     * \param obs_time Time of observation at the moment of printing
00455     * \param gnss_synchro Information generated by channels while processing the satellite
00456     * \return Returns the message content as set of bits
00457     */
00458     std::bitset<79> get_MT1010_sat_content(const Glonass_Gnav_Ephemeris& ephGNAV, double obs_time,
const Gnss_Synchro& gnss_synchro);
00459     /*!
00460     * \brief Get the contents of the satellite specific portion of a type 1011 Message (GLONASS Basic
RTK, L1 & L2)
00461     * \details Contents generated for each satellite. See table 3.5-13
00462     * \note Code added as part of GSoC 2017 program
00463     * \param ephGNAVL1 Ephemeris for GLONASS GNAV in L1 satellites
00464     * \param ephGNAVL2 Ephemeris for GLONASS GNAV in L2 satellites
00465     * \param obs_time Time of observation at the moment of printing
00466     * \param gnss_synchroL1 Information generated by channels while processing the GLONASS GNAV L1
satellite
00467     * \param gnss_synchroL2 Information generated by channels while processing the GLONASS GNAV L2
satellite

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00468     * \return Returns the message content as set of bits
00469     */
00470     std::bitset<107> get_MT1011_sat_content(const Glonass_Gnav_Ephemeris& ephL1, const
Glonass_Gnav_Ephemeris& ephL2, double obs_time, const Gnss_Synchro& gnss_synchroL1, const
Gnss_Synchro& gnss_synchroL2);
00471     /*!
00472     * \brief Get the contents of the satellite specific portion of a type 1012 Message (GLONASS
Extended RTK, L1 & L2)
00473     * \details Contents generated for each satellite. See table 3.5-14
00474     * \note Code added as part of GSOC 2017 program
00475     * \param ephGNAV1 Ephemeris for GLONASS GNAV in L1 satellites
00476     * \param ephGNAV2 Ephemeris for GLONASS GNAV in L2 satellites
00477     * \param obs_time Time of observation at the moment of printing
00478     * \param gnss_synchroL1 Information generated by channels while processing the GLONASS GNAV L1
satellite
00479     * \param gnss_synchroL2 Information generated by channels while processing the GLONASS GNAV L2
satellite
00480     * \return Returns the message content as set of bits
00481     */
00482     std::bitset<130> get_MT1012_sat_content(const Glonass_Gnav_Ephemeris& ephL1, const
Glonass_Gnav_Ephemeris& ephL2, double obs_time, const Gnss_Synchro& gnss_synchroL1, const
Gnss_Synchro& gnss_synchroL2);
00483
00484     std::string get_MSM_header(uint32_t msg_number,
00485         double obs_time,
00486         const std::map<int32_t, Gnss_Synchro>& observables,
00487         uint32_t ref_id,
00488         uint32_t clock_steering_indicator,
00489         uint32_t external_clock_indicator,
00490         int32_t smooth_int,
00491         bool divergence_free,
00492         bool more_messages);
00493
00494     std::string get_MSM_1_content_sat_data(const std::map<int32_t, Gnss_Synchro>& observables);
00495     std::string get_MSM_4_content_sat_data(const std::map<int32_t, Gnss_Synchro>& observables);
00496     std::string get_MSM_5_content_sat_data(const std::map<int32_t, Gnss_Synchro>& observables);
00497
00498     std::string get_MSM_1_content_signal_data(const std::map<int32_t, Gnss_Synchro>& observables);
00499     std::string get_MSM_2_content_signal_data(const Gps_Ephemeris& ephNAV, const Gps_CNAV_Ephemeris&
ephCNAV, const Galileo_Ephemeris& ephFNAV, const Glonass_Gnav_Ephemeris& ephGNAV, double obs_time,
const std::map<int32_t, Gnss_Synchro>& observables);
00500     std::string get_MSM_3_content_signal_data(const Gps_Ephemeris& ephNAV, const Gps_CNAV_Ephemeris&
ephCNAV, const Galileo_Ephemeris& ephFNAV, const Glonass_Gnav_Ephemeris& ephGNAV, double obs_time,
const std::map<int32_t, Gnss_Synchro>& observables);
00501     std::string get_MSM_4_content_signal_data(const Gps_Ephemeris& ephNAV, const Gps_CNAV_Ephemeris&
ephCNAV, const Galileo_Ephemeris& ephFNAV, const Glonass_Gnav_Ephemeris& ephGNAV, double obs_time,
const std::map<int32_t, Gnss_Synchro>& observables);
00502     std::string get_MSM_5_content_signal_data(const Gps_Ephemeris& ephNAV, const Gps_CNAV_Ephemeris&
ephCNAV, const Galileo_Ephemeris& ephFNAV, const Glonass_Gnav_Ephemeris& ephGNAV, double obs_time,
const std::map<int32_t, Gnss_Synchro>& observables);
00503     std::string get_MSM_6_content_signal_data(const Gps_Ephemeris& ephNAV, const Gps_CNAV_Ephemeris&
ephCNAV, const Galileo_Ephemeris& ephFNAV, const Glonass_Gnav_Ephemeris& ephGNAV, double obs_time,
const std::map<int32_t, Gnss_Synchro>& observables);
00504     std::string get_MSM_7_content_signal_data(const Gps_Ephemeris& ephNAV, const Gps_CNAV_Ephemeris&
ephCNAV, const Galileo_Ephemeris& ephFNAV, const Glonass_Gnav_Ephemeris& ephGNAV, double obs_time,
const std::map<int32_t, Gnss_Synchro>& observables);
00505
00506     std::string get_IGM01_header(const Galileo_HAS_data& has_data, uint8_t nsys, bool
ssr_multiple_msg_indicator);
00507     std::string get_IGM01_content_sat(const Galileo_HAS_data& has_data, uint8_t nsys_index);
00508     std::string get_IGM02_header(const Galileo_HAS_data& has_data, uint8_t nsys, bool
ssr_multiple_msg_indicator);
00509     std::string get_IGM02_content_sat(const Galileo_HAS_data& has_data, uint8_t nsys_index);
00510     std::string get_IGM03_header(const Galileo_HAS_data& has_data, uint8_t nsys, bool
ssr_multiple_msg_indicator);
00511     std::string get_IGM03_content_sat(const Galileo_HAS_data& has_data, uint8_t nsys_index);
00512     std::string get_IGM05_header(const Galileo_HAS_data& has_data, uint8_t nsys, bool
ssr_multiple_msg_indicator);
00513     std::string get_IGM05_content_sat(const Galileo_HAS_data& has_data, uint8_t nsys_index);
00514
00515     //
00516     // Utilities
00517     //
00518     static std::map<std::string, int> galileo_signal_map;
00519     static std::map<std::string, int> gps_signal_map;
00520     std::vector<std::pair<int32_t, Gnss_Synchro>> sort_by_signal(const std::vector<std::pair<int32_t,
Gnss_Synchro>& synchro_map) const;
00521     std::vector<std::pair<int32_t, Gnss_Synchro>> sort_by_PRN_mask(const std::vector<std::pair<int32_t,
Gnss_Synchro>& synchro_map) const;
00522     boost::posix_time::ptime compute_GPS_time(const Gps_Ephemeris& eph, double obs_time) const;
00523     boost::posix_time::ptime compute_GPS_time(const Gps_CNAV_Ephemeris& eph, double obs_time) const;
00524     boost::posix_time::ptime compute_Galileo_time(const Galileo_Ephemeris& eph, double obs_time)
const;
00525     boost::posix_time::ptime compute_GLONASS_time(const Glonass_Gnav_Ephemeris& eph, double obs_time)
const;
00526     boost::posix_time::ptime gps_L1_last_lock_time[64];
00527     boost::posix_time::ptime gps_L2_last_lock_time[64];

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00528     boost::posix_time::ptime gal_E1_last_lock_time[64];
00529     boost::posix_time::ptime gal_E5_last_lock_time[64];
00530     boost::posix_time::ptime glo_L1_last_lock_time[64];
00531     boost::posix_time::ptime glo_L2_last_lock_time[64];
00532     uint32_t lock_time_indicator(uint32_t lock_time_period_s);
00533     uint32_t msm_lock_time_indicator(uint32_t lock_time_period_s);
00534     uint32_t msm_extended_lock_time_indicator(uint32_t lock_time_period_s);
00535     // SSR utilities
00536     uint8_t ssr_update_interval(uint16_t validity_seconds) const;
00537
00538     //
00539     // Classes for TCP communication
00540     //
00541     uint16_t RTCM_port;
00542     // uint16_t RTCM_Station_ID;
00543     class RtcM_Message
00544     {
00545     public:
00546         static const std::size_t header_length = 6;
00547         static const std::size_t max_body_length = 1029;
00548
00549         RtcM_Message()
00550             : body_length_(0)
00551         {
00552         }
00553
00554         const char* data() const
00555         {
00556             return data_.data();
00557         }
00558
00559         char* data()
00560         {
00561             return data_.data();
00562         }
00563
00564         inline std::size_t length() const
00565         {
00566             return header_length + body_length_;
00567         }
00568
00569         const char* body() const
00570         {
00571             return data_.data() + header_length;
00572         }
00573
00574         char* body()
00575         {
00576             return data_.data() + header_length;
00577         }
00578
00579         std::size_t body_length() const
00580         {
00581             return body_length_;
00582         }
00583
00584         void body_length(std::size_t new_length)
00585         {
00586             body_length_ = new_length;
00587             if (body_length_ > max_body_length)
00588             {
00589                 body_length_ = max_body_length;
00590             }
00591         }
00592
00593         inline bool decode_header()
00594         {
00595             std::string header(data_.data(), header_length);
00596             if (header[0] != 'G' || header[1] != 'S')
00597             {
00598                 return false;
00599             }
00600
00601             auto header2 = header.substr(2);
00602             try
00603             {
00604                 body_length_ = std::stoi(header2);
00605             }
00606             catch (const std::exception& e)
00607             {
00608                 // invalid stoi conversion
00609                 body_length_ = 0;
00610                 return false;
00611             }
00612
00613             if (body_length_ == 0)
00614             {

```

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```

00700     }
00701
00702     inline void deliver(const Rtcmm_Message& msg)
00703     {
00704         bool write_in_progress = !write_msgs_.empty();
00705         write_msgs_.push_back(msg);
00706         if (!write_in_progress)
00707         {
00708             do_write();
00709         }
00710     }
00711
00712 private:
00713     inline void do_read_message_header()
00714     {
00715         auto self(shared_from_this());
00716         boost::asio::async_read(socket_,
00717             boost::asio::buffer(read_msg_.data(), Rtcmm_Message::header_length()),
00718             [this, self](boost::system::error_code ec, std::size_t /*length*/) {
00719                 if (!ec and read_msg_.decode_header())
00720                 {
00721                     do_read_message_body();
00722                 }
00723                 else if (!ec and !read_msg_.decode_header())
00724                 {
00725                     client_says += read_msg_.data();
00726                     bool first = true;
00727                     while (client_says.length() >= 80)
00728                     {
00729                         if (first == true)
00730                         {
00731                             DLOG(INFO) << "Client says:";
00732                             first = false;
00733                         }
00734                         DLOG(INFO) << client_says;
00735                         client_says = client_says.substr(80, client_says.length() - 80);
00736                     }
00737                     do_read_message_header();
00738                 }
00739                 else
00740                 {
00741                     std::cout << "Closing connection with RTCM client\n";
00742                     room_.leave(shared_from_this());
00743                 }
00744             });
00745     }
00746
00747     inline void do_read_message_body()
00748     {
00749         auto self(shared_from_this());
00750         boost::asio::async_read(socket_,
00751             boost::asio::buffer(read_msg_.body(), read_msg_.body_length()),
00752             [this, self](boost::system::error_code ec, std::size_t /*length*/) {
00753                 if (!ec)
00754                 {
00755                     room_.deliver(read_msg_);
00756                     // std::cout << "Delivered message (session): ";
00757                     // std::cout.write(read_msg_.body(), read_msg_.body_length());
00758                     // std::cout << '\n';
00759                     do_read_message_header();
00760                 }
00761                 else
00762                 {
00763                     std::cout << "Closing connection with RTCM client\n";
00764                     room_.leave(shared_from_this());
00765                 }
00766             });
00767     }
00768
00769     inline void do_write()
00770     {
00771         auto self(shared_from_this());
00772         boost::asio::async_write(socket_,
00773             boost::asio::buffer(write_msgs_.front().body(), write_msgs_.front().body_length()),
00774             [this, self](boost::system::error_code ec, std::size_t /*length*/) {
00775                 if (!ec)
00776                 {
00777                     write_msgs_.pop_front();
00778                     if (!write_msgs_.empty())
00779                     {
00780                         do_write();
00781                     }
00782                 }
00783                 else
00784                 {
00785                     std::cout << "Closing connection with RTCM client\n";
00786                     room_.leave(shared_from_this());

```

```

00787         }
00788         });
00789     }
00790
00791     boost::asio::ip::tcp::socket socket_;
00792     RtcM_Listener_Room& room_;
00793     RtcM_Message read_msg_;
00794     std::deque<RtcM_Message> write_msgs_;
00795     std::string client_says;
00796 };
00797
00798
00799     class Tcp_Internal_Client
00800     : public std::enable_shared_from_this<Tcp_Internal_Client>
00801     {
00802     public:
00803         Tcp_Internal_Client(b_io_context& io_context,
00804 #if BOOST_ASIO_USE_RESOLVER_ITERATOR
00805             boost::asio::ip::tcp::resolver::iterator endpoint_iterator)
00806             : io_context_(io_context), socket_(io_context)
00807             {
00808                 do_connect(std::move(endpoint_iterator));
00809             }
00810 #else
00811             boost::asio::ip::tcp::resolver::results_type endpoints)
00812             : io_context_(io_context), socket_(io_context)
00813             {
00814                 do_connect(std::move(endpoints));
00815             }
00816 #endif
00817
00818         inline void close()
00819         {
00820 #if BOOST_ASIO_USE_IOCONTEXT_POST
00821             io_context_.post([this]() { socket_.close(); });
00822 #else
00823             boost::asio::post(io_context_, [this]() { socket_.close(); });
00824 #endif
00825         }
00826
00827         inline void write(const RtcM_Message& msg)
00828         {
00829 #if BOOST_ASIO_USE_IOCONTEXT_POST
00830             io_context_.post(
00831                 [this, &msg]() {
00832 #else
00833             boost::asio::post(io_context_,
00834                 [this, &msg]() {
00835 #endif
00836                 bool write_in_progress = !write_msgs_.empty();
00837                 write_msgs_.push_back(msg);
00838                 if (!write_in_progress)
00839                 {
00840                     do_write();
00841                 }
00842             });
00843         }
00844
00845     private:
00846 #if BOOST_ASIO_USE_RESOLVER_ITERATOR
00847         inline void do_connect(boost::asio::ip::tcp::resolver::iterator endpoint_iterator)
00848         {
00849             boost::asio::async_connect(socket_, std::move(endpoint_iterator),
00850                 [this](boost::system::error_code ec, boost::asio::ip::tcp::resolver::iterator) {
00851 #else
00852         inline void do_connect(boost::asio::ip::tcp::resolver::results_type endpoints)
00853         {
00854             boost::asio::async_connect(socket_, std::move(endpoints),
00855                 [this](boost::system::error_code ec, boost::asio::ip::tcp::endpoint) {
00856 #endif
00857                 if (!ec)
00858                 {
00859                     do_read_message();
00860                 }
00861                 else
00862                 {
00863                     std::cout << "Server is down.\n";
00864                 }
00865             });
00866         }
00867
00868         inline void do_read_message()
00869         {
00870             boost::asio::async_read(socket_,
00871                 boost::asio::buffer(read_msg_.data(), 1029),
00872                 [this](boost::system::error_code ec, std::size_t /*length*/) {
00873                 if (!ec)

```

```

00874         {
00875             do_read_message();
00876         }
00877         else
00878         {
00879             std::cout << "Error in client\n";
00880             socket_.close();
00881         }
00882     });
00883 }
00884
00885 inline void do_write()
00886 {
00887     boost::asio::async_write(socket_,
00888         boost::asio::buffer(write_msgs_.front().data(), write_msgs_.front().length()),
00889         [this](boost::system::error_code ec, std::size_t /*length*/) {
00890             if (!ec)
00891             {
00892                 write_msgs_.pop_front();
00893                 if (!write_msgs_.empty())
00894                 {
00895                     do_write();
00896                 }
00897             }
00898             else
00899             {
00900                 socket_.close();
00901             }
00902         });
00903 }
00904
00905 b_io_context& io_context_;
00906 boost::asio::ip::tcp::socket socket_;
00907 Rtcmm_Message read_msg_;
00908 std::deque<Rtcmm_Message> write_msgs_;
00909 };
00910
00911
00912 class Queue_Reader
00913 {
00914 public:
00915     Queue_Reader(b_io_context& io_context, std::shared_ptr<Concurrent_Queue<std::string>& queue,
00916 int32_t port) : queue_(queue)
00917     {
00918         boost::asio::ip::tcp::resolver resolver(io_context);
00919         std::string host("localhost");
00920         std::string port_str = std::to_string(port);
00921 #if BOOST_ASIO_USE_RESOLVER_ITERATOR
00922         auto queue_endpoint_iterator = resolver.resolve({host.c_str(), port_str.c_str()});
00923         c = std::make_shared<Tcp_Internal_Client>(io_context, queue_endpoint_iterator);
00924 #else
00925         auto endpoints = resolver.resolve(host, port_str);
00926         c = std::make_shared<Tcp_Internal_Client>(io_context, endpoints);
00927 #endif
00928     }
00929
00930     inline void do_read_queue()
00931     {
00932         for (;;)
00933         {
00934             std::string message;
00935             Rtcmm_Message msg;
00936             queue_>wait_and_pop(message); // message += '\n';
00937             if (message == "Goodbye")
00938             {
00939                 break;
00940             }
00941
00942             const char* char_msg = message.c_str();
00943             msg.body_length(message.length());
00944             std::copy_n(char_msg, msg.body_length(), msg.body());
00945             msg.encode_header();
00946             c->write(msg);
00947         }
00948     }
00949 private:
00950     std::shared_ptr<Tcp_Internal_Client> c;
00951     std::shared_ptr<Concurrent_Queue<std::string>& queue_;
00952 };
00953
00954
00955 class Tcp_Server
00956 {
00957 public:
00958     Tcp_Server(b_io_context& io_context, const boost::asio::ip::tcp::endpoint& endpoint)
00959         : acceptor_(io_context), socket_(io_context)

```

```

00960     {
00961         acceptor_.open(endpoint.protocol());
00962         acceptor_.set_option(boost::asio::ip::tcp::acceptor::reuse_address(true));
00963         acceptor_.bind(endpoint);
00964         acceptor_.listen();
00965         do_accept();
00966     }
00967
00968     inline void close_server()
00969     {
00970         socket_.close();
00971         acceptor_.close();
00972     }
00973
00974     private:
00975         inline void do_accept()
00976         {
00977             acceptor_.async_accept(socket_, [this](boost::system::error_code ec) {
00978                 if (!ec)
00979                 {
00980                     if (first_client)
00981                     {
00982                         std::cout << "The TCP/IP server of RTCM messages is up and running.
Accepting connections ...\n";
00983                         first_client = false;
00984                     }
00985                     else
00986                     {
00987                         std::cout << "Starting RTCM TCP/IP server session...\n";
00988                         boost::system::error_code ec2;
00989                         boost::asio::ip::tcp::endpoint endpoint =
socket_.remote_endpoint(ec2);
00990                         if (ec2)
00991                         {
00992                             // Error creating remote_endpoint
00993                             std::cout << "Error getting remote IP address, closing
session.\n";
00994                             LOG(INFO) << "Error getting remote IP address";
00995                             start_session = false;
00996                         }
00997                         else
00998                         {
00999                             std::string remote_addr = endpoint.address().to_string();
01000                             std::cout << "Serving client from " << remote_addr << '\n';
01001                             LOG(INFO) << "Serving client from " << remote_addr;
01002                         }
01003                     }
01004                     if (start_session)
01005                     {
01006                         std::make_shared<Rtcm_Session>(std::move(socket_), room_)->start();
01007                     }
01008                 }
01009                 else
01010                 {
01011                     std::cout << "Error when invoking a RTCM session. " << ec << '\n';
01012                 }
01013                 start_session = true;
01014                 do_accept();
01015             });
01016         }
01017
01018         boost::asio::ip::tcp::acceptor acceptor_;
01019         boost::asio::ip::tcp::socket socket_;
01020         Rtcm_Listener_Room room_;
01021         bool first_client = true;
01022         bool start_session = true;
01023     };
01024
01025     b_io_context io_context;
01026     std::shared_ptr<Concurrent_Queue<std::string>> rtcm_message_queue;
01027     std::thread t;
01028     std::thread tq;
01029     std::list<Rtcm::Tcp_Server> servers;
01030     bool server_is_running;
01031     void stop_service();
01032
01033     //
01034     // Transport Layer
01035     //
01036     std::bitset<8> preamble;
01037     std::bitset<6> reserved_field;
01038     std::string add_CRC(const std::string& m) const;
01039     std::string build_message(const std::string& data) const; // adds 0s to complete a byte and adds
the CRC
01040
01041     //
01042     // Data Fields

```



```

01043 //
01044 std::bitset<12> DF002;
01045 int32_t set_DF002(uint32_t message_number);
01046
01047 std::bitset<12> DF003;
01048 int32_t set_DF003(uint32_t ref_station_ID);
01049
01050 std::bitset<30> DF004;
01051 int32_t set_DF004(double obs_time);
01052
01053 std::bitset<1> DF005;
01054 int32_t set_DF005(bool sync_flag);
01055
01056 std::bitset<5> DF006;
01057 int32_t set_DF006(const std::map<int32_t, Gnss_Synchro>& observables);
01058
01059 std::bitset<1> DF007;
01060 int32_t set_DF007(bool divergence_free_smoothing_indicator); // 0 - Divergence-free smoothing not
used 1 - Divergence-free smoothing used
01061
01062 std::bitset<3> DF008;
01063 int32_t set_DF008(int16_t smoothing_interval);
01064
01065 std::bitset<6> DF009;
01066 int32_t set_DF009(const Gnss_Synchro& gnss_synchro);
01067 int32_t set_DF009(const Gps_Ephemeris& gps_eph);
01068
01069 std::bitset<1> DF010;
01070 int32_t set_DF010(bool code_indicator);
01071
01072 std::bitset<24> DF011;
01073 int32_t set_DF011(const Gnss_Synchro& gnss_synchro);
01074
01075 std::bitset<20> DF012;
01076 int32_t set_DF012(const Gnss_Synchro& gnss_synchro);
01077
01078 std::bitset<7> DF013;
01079 int32_t set_DF013(const Gps_Ephemeris& eph, double obs_time, const Gnss_Synchro& gnss_synchro);
01080
01081 std::bitset<8> DF014;
01082 int32_t set_DF014(const Gnss_Synchro& gnss_synchro);
01083
01084 std::bitset<8> DF015;
01085 int32_t set_DF015(const Gnss_Synchro& gnss_synchro);
01086
01087 std::bitset<14> DF017;
01088 int32_t set_DF017(const Gnss_Synchro& gnss_synchroL1, const Gnss_Synchro& gnss_synchroL2);
01089
01090 std::bitset<20> DF018;
01091 int32_t set_DF018(const Gnss_Synchro& gnss_synchroL1, const Gnss_Synchro& gnss_synchroL2);
01092
01093 std::bitset<7> DF019;
01094 int32_t set_DF019(const Gps_CNAV_Ephemeris& eph, double obs_time, const Gnss_Synchro&
gnss_synchro);
01095
01096 std::bitset<8> DF020;
01097 int32_t set_DF020(const Gnss_Synchro& gnss_synchro);
01098
01099 std::bitset<6> DF021;
01100 int32_t set_DF021();
01101
01102 std::bitset<1> DF022;
01103 int32_t set_DF022(bool gps_indicator);
01104
01105 std::bitset<1> DF023;
01106 int32_t set_DF023(bool glonass_indicator);
01107
01108 std::bitset<1> DF024;
01109 int32_t set_DF024(bool galileo_indicator);
01110
01111 std::bitset<38> DF025;
01112 int32_t set_DF025(double antenna_ECEF_X_m);
01113
01114 std::bitset<38> DF026;
01115 int32_t set_DF026(double antenna_ECEF_Y_m);
01116
01117 std::bitset<38> DF027;
01118 int32_t set_DF027(double antenna_ECEF_Z_m);
01119
01120 std::bitset<16> DF028;
01121 int32_t set_DF028(double height);
01122
01123 std::bitset<8> DF029;
01124
01125 std::bitset<8> DF031;
01126 int32_t set_DF031(uint32_t antenna_setup_id);
01127

```

```

01128     std::bitset<8> DF032;
01129
01130     /*!
01131     * \brief Sets the Data Field value
01132     * \note Code added as part of GSoC 2017 program
01133     * \param obs_time Time of observation at the moment of printing
01134     * \return returns 0 upon success
01135     */
01136     int32_t set_DF034(double obs_time);
01137     std::bitset<27> DF034; //!< GLONASS Epoch Time (tk)
01138
01139     std::bitset<5> DF035; //!< No. of GLONASS Satellite Signals Processed
01140     int32_t set_DF035(const std::map<int32_t, Gnss_Synchro>& observables);
01141
01142     std::bitset<1> DF036; //!< GLONASS Divergence-free Smoothing Indicator
01143     int32_t set_DF036(bool divergence_free_smoothing_indicator);
01144
01145     std::bitset<3> DF037; //!< GLONASS Smoothing Interval
01146     int32_t set_DF037(int16_t smoothing_interval);
01147
01148     std::bitset<6> DF038; //!< GLONASS Satellite ID (Satellite Slot Number)
01149     int32_t set_DF038(const Gnss_Synchro& gnss_synchro);
01150     int32_t set_DF038(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01151
01152     std::bitset<1> DF039; //!< GLONASS L1 Code Indicator
01153     int32_t set_DF039(bool code_indicator);
01154
01155     std::bitset<5> DF040; //!< GLONASS Satellite Frequency Number
01156     int32_t set_DF040(int32_t frequency_channel_number);
01157     int32_t set_DF040(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01158
01159     std::bitset<25> DF041; //!< GLONASS L1 Pseudorange
01160     int32_t set_DF041(const Gnss_Synchro& gnss_synchro);
01161
01162     std::bitset<20> DF042; //!< GLONASS L1 PhaseRange - L1 Pseudorange
01163     int32_t set_DF042(const Gnss_Synchro& gnss_synchro);
01164
01165     std::bitset<7> DF043; //!< GLONASS L1 Lock Time Indicator
01166     int32_t set_DF043(const Glonass_Gnav_Ephemeris& eph, double obs_time, const Gnss_Synchro&
gnss_synchro);
01167
01168     std::bitset<7> DF044; //!< GLONASS Integer L1 Pseudorange Modulus Ambiguity
01169     int32_t set_DF044(const Gnss_Synchro& gnss_synchro);
01170
01171     std::bitset<8> DF045; //!< GLONASS L1 CNR
01172     int32_t set_DF045(const Gnss_Synchro& gnss_synchro);
01173
01174     std::bitset<2> DF046; //!< GLONASS L2 code indicator
01175     int32_t set_DF046(uint16_t code_indicator);
01176
01177     std::bitset<14> DF047; //!< GLONASS L2 - L1 Pseudorange Difference
01178     int32_t set_DF047(const Gnss_Synchro& gnss_synchroL1, const Gnss_Synchro& gnss_synchroL2);
01179
01180     std::bitset<20> DF048; //!< GLONASS L2 PhaseRange - L1 Pseudorange
01181     int32_t set_DF048(const Gnss_Synchro& gnss_synchroL1, const Gnss_Synchro& gnss_synchroL2);
01182
01183     std::bitset<7> DF049; //!< GLONASS L2 Lock Time Indicator
01184     int32_t set_DF049(const Glonass_Gnav_Ephemeris& eph, double obs_time, const Gnss_Synchro&
gnss_synchro);
01185
01186     std::bitset<8> DF050; //!< GLONASS L2 CNR
01187     int32_t set_DF050(const Gnss_Synchro& gnss_synchro);
01188
01189     std::bitset<16> DF051;
01190     int32_t set_DF051(const Gps_Ephemeris& gps_eph, double obs_time);
01191
01192     std::bitset<17> DF052;
01193     int32_t set_DF052(const Gps_Ephemeris& gps_eph, double obs_time);
01194
01195     // Contents of GPS Satellite Ephemeris Data, Message Type 1019
01196     std::bitset<8> DF071;
01197     int32_t set_DF071(const Gps_Ephemeris& gps_eph);
01198
01199     std::bitset<10> DF076;
01200     int32_t set_DF076(const Gps_Ephemeris& gps_eph);
01201
01202     std::bitset<4> DF077;
01203     int32_t set_DF077(const Gps_Ephemeris& gps_eph);
01204
01205     std::bitset<2> DF078;
01206     int32_t set_DF078(const Gps_Ephemeris& gps_eph);
01207
01208     std::bitset<14> DF079;
01209     int32_t set_DF079(const Gps_Ephemeris& gps_eph);
01210
01211     std::bitset<8> DF080;
01212     int32_t set_DF080(const Gps_Ephemeris& gps_eph);

```

```
01213
01214     std::bitset<16> DF081;
01215     int32_t set_DF081(const Gps_Ephemeris& gps_eph);
01216
01217     std::bitset<8> DF082;
01218     int32_t set_DF082(const Gps_Ephemeris& gps_eph);
01219
01220     std::bitset<16> DF083;
01221     int32_t set_DF083(const Gps_Ephemeris& gps_eph);
01222
01223     std::bitset<22> DF084;
01224     int32_t set_DF084(const Gps_Ephemeris& gps_eph);
01225
01226     std::bitset<10> DF085;
01227     int32_t set_DF085(const Gps_Ephemeris& gps_eph);
01228
01229     std::bitset<16> DF086;
01230     int32_t set_DF086(const Gps_Ephemeris& gps_eph);
01231
01232     std::bitset<16> DF087;
01233     int32_t set_DF087(const Gps_Ephemeris& gps_eph);
01234
01235     std::bitset<32> DF088;
01236     int32_t set_DF088(const Gps_Ephemeris& gps_eph);
01237
01238     std::bitset<16> DF089;
01239     int32_t set_DF089(const Gps_Ephemeris& gps_eph);
01240
01241     std::bitset<32> DF090;
01242     int32_t set_DF090(const Gps_Ephemeris& gps_eph);
01243
01244     std::bitset<16> DF091;
01245     int32_t set_DF091(const Gps_Ephemeris& gps_eph);
01246
01247     std::bitset<32> DF092;
01248     int32_t set_DF092(const Gps_Ephemeris& gps_eph);
01249
01250     std::bitset<16> DF093;
01251     int32_t set_DF093(const Gps_Ephemeris& gps_eph);
01252
01253     std::bitset<16> DF094;
01254     int32_t set_DF094(const Gps_Ephemeris& gps_eph);
01255
01256     std::bitset<32> DF095;
01257     int32_t set_DF095(const Gps_Ephemeris& gps_eph);
01258
01259     std::bitset<16> DF096;
01260     int32_t set_DF096(const Gps_Ephemeris& gps_eph);
01261
01262     std::bitset<32> DF097;
01263     int32_t set_DF097(const Gps_Ephemeris& gps_eph);
01264
01265     std::bitset<16> DF098;
01266     int32_t set_DF098(const Gps_Ephemeris& gps_eph);
01267
01268     std::bitset<32> DF099;
01269     int32_t set_DF099(const Gps_Ephemeris& gps_eph);
01270
01271     std::bitset<24> DF100;
01272     int32_t set_DF100(const Gps_Ephemeris& gps_eph);
01273
01274     std::bitset<8> DF101;
01275     int32_t set_DF101(const Gps_Ephemeris& gps_eph);
01276
01277     std::bitset<6> DF102;
01278     int32_t set_DF102(const Gps_Ephemeris& gps_eph);
01279
01280     std::bitset<1> DF103;
01281     int32_t set_DF103(const Gps_Ephemeris& gps_eph);
01282
01283     std::bitset<1> DF104; //!< GLONASS Almanac Health
01284     int32_t set_DF104(uint32_t glonass_gnav_alm_health);
01285
01286     std::bitset<1> DF105; //!< GLONASS Almanac Health Availability Indicator
01287     int32_t set_DF105(uint32_t glonass_gnav_alm_health_ind);
01288
01289     std::bitset<2> DF106; //!< GLONASS P1 Word
01290     int32_t set_DF106(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01291
01292     std::bitset<12> DF107; //!< GLONASS Epoch (tk)
01293     int32_t set_DF107(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01294
01295     std::bitset<1> DF108; //!< GLONASS MSB of Bn Word
01296     int32_t set_DF108(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01297
01298     std::bitset<1> DF109; //!< GLONASS P2 Word
01299     int32_t set_DF109(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
```

```

01300
01301     std::bitset<7> DF110;    //!< GLONASS Ephemeris Epoch (tb)
01302     int32_t set_DF110(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01303
01304     std::bitset<24> DF111;    //!< GLONASS Xn first derivative
01305     int32_t set_DF111(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01306
01307     std::bitset<27> DF112;    //!< GLONASS Xn
01308     int32_t set_DF112(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01309
01310     std::bitset<5> DF113;    //!< GLONASS Xn second derivative
01311     int32_t set_DF113(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01312
01313     std::bitset<24> DF114;    //!< GLONASS Yn first derivative
01314     int32_t set_DF114(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01315
01316     std::bitset<27> DF115;    //!< GLONASS Yn
01317     int32_t set_DF115(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01318
01319     std::bitset<5> DF116;    //!< GLONASS Yn second derivative
01320     int32_t set_DF116(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01321
01322     std::bitset<24> DF117;    //!< GLONASS Zn first derivative
01323     int32_t set_DF117(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01324
01325     std::bitset<27> DF118;    //!< GLONASS Zn
01326     int32_t set_DF118(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01327
01328     std::bitset<5> DF119;    //!< GLONASS Zn second derivative
01329     int32_t set_DF119(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01330
01331     std::bitset<1> DF120;    //!< GLONASS P3
01332     int32_t set_DF120(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01333
01334     std::bitset<11> DF121;    //!< GLONASS GAMMA_N
01335     int32_t set_DF121(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01336
01337     std::bitset<2> DF122;    //!< GLONASS P
01338     int32_t set_DF122(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01339
01340     std::bitset<1> DF123;    //!< GLONASS ln (third string)
01341     int32_t set_DF123(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01342
01343     std::bitset<22> DF124;    //!< GLONASS TAU_N
01344     int32_t set_DF124(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01345
01346     std::bitset<5> DF125;    //!< GLONASS DELTA_TAU_N
01347     int32_t set_DF125(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01348
01349     std::bitset<5> DF126;    //!< GLONASS Eccentricity
01350     int32_t set_DF126(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01351
01352     std::bitset<1> DF127;    //!< GLONASS P4
01353     int32_t set_DF127(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01354
01355     std::bitset<4> DF128;    //!< GLONASS F_T
01356     int32_t set_DF128(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01357
01358     std::bitset<11> DF129;    //!< GLONASS N_T
01359     int32_t set_DF129(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01360
01361     std::bitset<2> DF130;    //!< GLONASS M
01362     int32_t set_DF130(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01363
01364     std::bitset<1> DF131;    //!< GLONASS Availability of additional data
01365     int32_t set_DF131(uint32_t fifth_str_additional_data_ind);
01366
01367     std::bitset<11> DF132;    //!< GLONASS N_A
01368     int32_t set_DF132(const Glonass_Gnav_Utc_Model& glonass_gnav_utc_model);
01369
01370     std::bitset<32> DF133;    //!< GLONASS TAU_C
01371     int32_t set_DF133(const Glonass_Gnav_Utc_Model& glonass_gnav_utc_model);
01372
01373     std::bitset<5> DF134;    //!< GLONASS N_4
01374     int32_t set_DF134(const Glonass_Gnav_Utc_Model& glonass_gnav_utc_model);
01375
01376     std::bitset<22> DF135;    //!< GLONASS TAU_GPS
01377     int32_t set_DF135(const Glonass_Gnav_Utc_Model& glonass_gnav_utc_model);
01378
01379     std::bitset<1> DF136;    //!< GLONASS L_N (FIFTH STRING)
01380     int32_t set_DF136(const Glonass_Gnav_Ephemeris& glonass_gnav_eph);
01381
01382     std::bitset<1> DF137;
01383     int32_t set_DF137(const Gps_Ephemeris& gps_eph);
01384
01385
01386     std::bitset<1> DF141;

```

```
01387     int32_t set_DF141(const Gps_Ephemeris& gps_eph);
01388
01389     std::bitset<1> DF142;
01390     int32_t set_DF142(const Gps_Ephemeris& gps_eph);
01391
01392     std::bitset<30> DF248;
01393     int32_t set_DF248(double obs_time);
01394
01395     // Contents of Galileo F/NAV Satellite Ephemeris Data, Message Type 1045
01396     std::bitset<6> DF252;
01397     int32_t set_DF252(const Galileo_Ephemeris& gal_eph);
01398
01399     std::bitset<12> DF289;
01400     int32_t set_DF289(const Galileo_Ephemeris& gal_eph);
01401
01402     std::bitset<10> DF290;
01403     int32_t set_DF290(const Galileo_Ephemeris& gal_eph);
01404
01405     std::bitset<8> DF291;
01406     int32_t set_DF291(const Galileo_Ephemeris& gal_eph);
01407
01408     std::bitset<14> DF292;
01409     int32_t set_DF292(const Galileo_Ephemeris& gal_eph);
01410
01411     std::bitset<14> DF293;
01412     int32_t set_DF293(const Galileo_Ephemeris& gal_eph);
01413
01414     std::bitset<6> DF294;
01415     int32_t set_DF294(const Galileo_Ephemeris& gal_eph);
01416
01417     std::bitset<21> DF295;
01418     int32_t set_DF295(const Galileo_Ephemeris& gal_eph);
01419
01420     std::bitset<31> DF296;
01421     int32_t set_DF296(const Galileo_Ephemeris& gal_eph);
01422
01423     std::bitset<16> DF297;
01424     int32_t set_DF297(const Galileo_Ephemeris& gal_eph);
01425
01426     std::bitset<16> DF298;
01427     int32_t set_DF298(const Galileo_Ephemeris& gal_eph);
01428
01429     std::bitset<32> DF299;
01430     int32_t set_DF299(const Galileo_Ephemeris& gal_eph);
01431
01432     std::bitset<16> DF300;
01433     int32_t set_DF300(const Galileo_Ephemeris& gal_eph);
01434
01435     std::bitset<32> DF301;
01436     int32_t set_DF301(const Galileo_Ephemeris& gal_eph);
01437
01438     std::bitset<16> DF302;
01439     int32_t set_DF302(const Galileo_Ephemeris& gal_eph);
01440
01441     std::bitset<32> DF303;
01442     int32_t set_DF303(const Galileo_Ephemeris& gal_eph);
01443
01444     std::bitset<14> DF304;
01445     int32_t set_DF304(const Galileo_Ephemeris& gal_eph);
01446
01447     std::bitset<16> DF305;
01448     int32_t set_DF305(const Galileo_Ephemeris& gal_eph);
01449
01450     std::bitset<32> DF306;
01451     int32_t set_DF306(const Galileo_Ephemeris& gal_eph);
01452
01453     std::bitset<16> DF307;
01454     int32_t set_DF307(const Galileo_Ephemeris& gal_eph);
01455
01456     std::bitset<32> DF308;
01457     int32_t set_DF308(const Galileo_Ephemeris& gal_eph);
01458
01459     std::bitset<16> DF309;
01460     int32_t set_DF309(const Galileo_Ephemeris& gal_eph);
01461
01462     std::bitset<32> DF310;
01463     int32_t set_DF310(const Galileo_Ephemeris& gal_eph);
01464
01465     std::bitset<24> DF311;
01466     int32_t set_DF311(const Galileo_Ephemeris& gal_eph);
01467
01468     std::bitset<10> DF312;
01469     int32_t set_DF312(const Galileo_Ephemeris& gal_eph);
01470
01471     std::bitset<10> DF313;
01472     int32_t set_DF313(const Galileo_Ephemeris& gal_eph);
01473
```

```

01474     std::bitset<2> DF314;
01475     int32_t set_DF314(const Galileo_Ephemeris& gal_eph);
01476
01477     std::bitset<1> DF315;
01478     int32_t set_DF315(const Galileo_Ephemeris& gal_eph);
01479
01480     std::bitset<2> DF364;
01481
01482     // Content of message header for MSM1, MSM2, MSM3, MSM4, MSM5, MSM6 and MSM7
01483     std::bitset<1> DF393;
01484     int32_t set_DF393(bool more_messages); // 1 indicates that more MSMs follow for given physical
time and reference station ID
01485
01486     std::bitset<64> DF394;
01487     int32_t set_DF394(const std::map<int32_t, Gnss_Synchro>& gnss_synchro);
01488
01489     std::bitset<32> DF395;
01490     int32_t set_DF395(const std::map<int32_t, Gnss_Synchro>& gnss_synchro);
01491
01492     std::string set_DF396(const std::map<int32_t, Gnss_Synchro>& observables);
01493
01494     std::bitset<8> DF397;
01495     int32_t set_DF397(const Gnss_Synchro& gnss_synchro);
01496
01497     std::bitset<10> DF398;
01498     int32_t set_DF398(const Gnss_Synchro& gnss_synchro);
01499
01500     std::bitset<14> DF399;
01501     int32_t set_DF399(const Gnss_Synchro& gnss_synchro);
01502
01503     std::bitset<15> DF400;
01504     int32_t set_DF400(const Gnss_Synchro& gnss_synchro);
01505
01506     std::bitset<22> DF401;
01507     int32_t set_DF401(const Gnss_Synchro& gnss_synchro);
01508
01509     std::bitset<4> DF402;
01510     int32_t set_DF402(const Gps_Ephemeris& ephNAV, const Gps_CNAV_Ephemeris& ephCNAV, const
Galileo_Ephemeris& ephFNAV, const Glonass_Gnav_Ephemeris& ephGNAV, double obs_time, const
Gnss_Synchro& gnss_synchro);
01511
01512     std::bitset<6> DF403;
01513     int32_t set_DF403(const Gnss_Synchro& gnss_synchro);
01514
01515     std::bitset<15> DF404;
01516     int32_t set_DF404(const Gnss_Synchro& gnss_synchro);
01517
01518     std::bitset<20> DF405;
01519     int32_t set_DF405(const Gnss_Synchro& gnss_synchro);
01520
01521     std::bitset<24> DF406;
01522     int32_t set_DF406(const Gnss_Synchro& gnss_synchro);
01523
01524     std::bitset<10> DF407;
01525     int32_t set_DF407(const Gps_Ephemeris& ephNAV, const Gps_CNAV_Ephemeris& ephCNAV, const
Galileo_Ephemeris& ephFNAV, const Glonass_Gnav_Ephemeris& ephGNAV, double obs_time, const
Gnss_Synchro& gnss_synchro);
01526
01527     std::bitset<10> DF408;
01528     int32_t set_DF408(const Gnss_Synchro& gnss_synchro);
01529
01530     std::bitset<3> DF409;
01531     int32_t set_DF409(uint32_t iods);
01532
01533     std::bitset<2> DF411;
01534     int32_t set_DF411(uint32_t clock_steering_indicator);
01535
01536     std::bitset<2> DF412;
01537     int32_t set_DF412(uint32_t external_clock_indicator);
01538
01539     std::bitset<1> DF417;
01540     int32_t set_DF417(bool using_divergence_free_smoothing);
01541
01542     std::bitset<3> DF418;
01543     int32_t set_DF418(int32_t carrier_smoothing_interval_s);
01544
01545     std::bitset<1> DF420;
01546     int32_t set_DF420(const Gnss_Synchro& gnss_synchro);
01547
01548     // IGS State Space Representation (SSR) data fields
01549     // see https://files.igs.org/pub/data/format/igs_ssr_v1.pdf
01550     std::bitset<3> IDF001;
01551     void set_IDF001(uint8_t version);
01552
01553     std::bitset<8> IDF002;
01554     void set_IDF002(uint8_t igs_message_number);
01555

```

```

01556     std::bitset<20> IDF003;
01557     void set_IDF003(uint32_t tow);
01558
01559     std::bitset<4> IDF004;
01560     void set_IDF004(uint8_t ssr_update_interval);
01561
01562     std::bitset<1> IDF005;
01563     void set_IDF005(bool ssr_multiple_message_indicator);
01564
01565     std::bitset<1> IDF006;
01566     void set_IDF006(bool regional_indicator);
01567
01568     std::bitset<4> IDF007;
01569     void set_IDF007(uint8_t ssr_iod);
01570
01571     std::bitset<16> IDF008;
01572     void set_IDF008(uint16_t ssr_provider_id);
01573
01574     std::bitset<4> IDF009;
01575     void set_IDF009(uint8_t ssr_solution_id);
01576
01577     std::bitset<6> IDF010;
01578     void set_IDF010(uint8_t num_satellites);
01579
01580     std::bitset<6> IDF011;
01581     void set_IDF011(uint8_t gnss_satellite_id);
01582
01583     std::bitset<8> IDF012;
01584     void set_IDF012(uint8_t gnss_iod);
01585
01586     std::bitset<22> IDF013;
01587     void set_IDF013(float delta_orbit_radial_m);
01588
01589     std::bitset<20> IDF014;
01590     void set_IDF014(float delta_orbit_in_track_m);
01591
01592     std::bitset<20> IDF015;
01593     void set_IDF015(float delta_orbit_cross_track_m);
01594
01595     std::bitset<21> IDF016;
01596     void set_IDF016(float dot_orbit_delta_track_m_s);
01597
01598     std::bitset<19> IDF017;
01599     void set_IDF017(float dot_orbit_delta_in_track_m_s);
01600
01601     std::bitset<19> IDF018;
01602     void set_IDF018(float dot_orbit_delta_cross_track_m_s);
01603
01604     std::bitset<22> IDF019;
01605     void set_IDF019(float delta_clock_c0_m);
01606
01607     std::bitset<21> IDF020;
01608     void set_IDF020(float delta_clock_c1_m_s);
01609
01610     std::bitset<27> IDF021;
01611     void set_IDF021(float delta_clock_c2_m_s2);
01612
01613     std::bitset<5> IDF023;
01614     void set_IDF023(uint8_t num_bias_processed);
01615
01616     std::bitset<5> IDF024;
01617     void set_IDF024(uint8_t gnss_signal_tracking_mode_id);
01618
01619     std::bitset<14> IDF025;
01620     void set_IDF025(float code_bias_m);
01621 };
01622
01623
01624 /** \} */
01625 /** \} */
01626 #endif // GNSS_SDR_RTCM_H

```

13.304 rtcm_printer.h File Reference

Interface of a RTCM 3.2 printer for GNSS-SDR This class provides a implementation of a subset of the RTCM Standard 10403.2 for Differential GNSS Services.

```

#include "signal_enabled_flags.h"
#include <stdint>
#include <fstream>
#include <map>
#include <memory>

```

```
#include <string>
```

Classes

- class [Rtcm_Printer](#)

This class provides a implementation of a subset of the RTCM Standard 10403.2 messages.

13.304.1 Detailed Description

Interface of a RTCM 3.2 printer for GNSS-SDR This class provides a implementation of a subset of the RTCM Standard 10403.2 for Differential GNSS Services.

Author

Carles Fernandez-Prades, 2014. cfernandez(at)cttc.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.
 Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors) SPDX-License-Identifier: GPL-3.0-or-later
 Definition in file [rtcm_printer.h](#).

13.305 rtcm_printer.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtcm_printer.h
00003  * \brief Interface of a RTCM 3.2 printer for GNSS-SDR
00004  * This class provides a implementation of a subset of the RTCM Standard 10403.2
00005  * for Differential GNSS Services
00006  *
00007  * \author Carles Fernandez-Prades, 2014. cfernandez(at)cttc.es
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_RTCM_PRINTER_H
00021 #define GNSS_SDR_RTCM_PRINTER_H
00022
00023 #include "signal_enabled_flags.h"
00024 #include <stdint> // for int32_t
00025 #include <fstream> // for std::ofstream
00026 #include <map> // for std::map
00027 #include <memory> // std::shared_ptr
00028 #include <string>
00029
00030 /** \addtogroup PVT
00031  * \{ */
00032 /** \addtogroup PVT_libs
00033  * \{ */
00034
00035
00036 class Galileo_Ephemeris;
00037 class Glonass_Gnav_Ephemeris;
00038 class Glonass_Gnav_Utc_Model;
00039 class Gnss_Synchro;
00040 class Gps_CNAV_Ephemeris;
00041 class Gps_Ephemeris;
00042 class Rtcm;
00043 class Rtklib_Solver;
00044 class Galileo_HAS_data;
00045
00046 /*!
00047  * \brief This class provides a implementation of a subset of the RTCM Standard 10403.2 messages
00048  */
00049 class Rtcm_Printer
00050 {
00051 public:
00052     /*!
00053     * \brief Default constructor.
```



```

00054     */
00055     RtcM_Printer(const std::string& filename,
00056                 bool flag_rtcm_file_dump,
00057                 bool flag_rtcm_server,
00058                 bool flag_rtcm_tty_port,
00059                 uint16_t rtcm_tcp_port,
00060                 uint16_t rtcm_station_id,
00061                 const std::string& rtcm_dump_devname,
00062                 uint32_t signal_enabled_flags,
00063                 bool time_tag_name = true,
00064                 const std::string& base_path = ".");
00065
00066     /*!
00067     * \brief Default destructor.
00068     */
00069     ~RtcM_Printer();
00070
00071     /*!
00072     * \brief Print RTCM messages.
00073     */
00074     void Print_RtcM_Messages(const Rtklib_Solver* pvt_solver,
00075                             const std::map<int, Gnss_Synchro>& gnss_observables_map,
00076                             double rx_time,
00077                             bool rtcm_MSM_enabled,
00078                             bool rtcm_MT1019_enabled,
00079                             bool rtcm_MT1020_enabled,
00080                             bool rtcm_MT1045_enabled,
00081                             bool rtcm_MT1077_enabled,
00082                             bool rtcm_MT1087_enabled,
00083                             bool rtcm_MT1097_enabled,
00084                             bool flag_write_RTCM_MSM_output,
00085                             bool flag_write_RTCM_1019_output,
00086                             bool flag_write_RTCM_1020_output,
00087                             bool flag_write_RTCM_1045_output,
00088                             bool enable_rx_clock_correction);
00089
00090     uint32_t lock_time(const Gps_Ephemeris& eph, double obs_time, const Gnss_Synchro& gnss_synchro);
00091     uint32_t lock_time(const Gps_CNAV_Ephemeris& eph, double obs_time, const Gnss_Synchro& gnss_synchro);
00092     uint32_t lock_time(const Galileo_Ephemeris& eph, double obs_time, const Gnss_Synchro& gnss_synchro);
00093
00094     /*!
00095     * \brief Locks time for logging given GLONASS GNAV Broadcast Ephemeris
00096     * \note Code added as part of GSoC 2017 program
00097     * \params glonass_gnav_eph GLONASS GNAV Broadcast Ephemeris
00098     * \params obs_time Time of observation at the moment of printing
00099     * \params observables Set of observables as defined by the platform
00100     * \return locked time during logging process
00101     */
00102     uint32_t lock_time(const Glonass_Gnav_Ephemeris& eph, double obs_time, const Gnss_Synchro& gnss_synchro);
00103
00104     void Print_IGM_Messages(const Galileo_HAS_data& has_data);
00105
00106     std::string print_MT1005_test(); ///< For testing purposes
00107
00108 private:
00109     bool Print_RtcM_MT1001(const Gps_Ephemeris& gps_eph, double obs_time, const std::map<int32_t, Gnss_Synchro>& observables);
00110     bool Print_RtcM_MT1002(const Gps_Ephemeris& gps_eph, double obs_time, const std::map<int32_t, Gnss_Synchro>& observables);
00111     bool Print_RtcM_MT1003(const Gps_Ephemeris& gps_eph, const Gps_CNAV_Ephemeris& cnav_eph, double obs_time, const std::map<int32_t, Gnss_Synchro>& observables);
00112     bool Print_RtcM_MT1004(const Gps_Ephemeris& gps_eph, const Gps_CNAV_Ephemeris& cnav_eph, double obs_time, const std::map<int32_t, Gnss_Synchro>& observables);
00113
00114     /*
00115     * \brief Prints L1-Only GLONASS RTK Observables
00116     * \details This GLONASS message type is not generally used or supported; type 1012 is to be preferred.
00117     * \note Code added as part of GSoC 2017 program
00118     * \param glonass_gnav_eph GLONASS GNAV Broadcast Ephemeris
00119     * \param obs_time Time of observation at the moment of printing
00120     * \param observables Set of observables as defined by the platform
00121     * \return true or false upon operation success
00122     */
00123     bool Print_RtcM_MT1009(const Glonass_Gnav_Ephemeris& glonass_gnav_eph, double obs_time, const std::map<int32_t, Gnss_Synchro>& observables);
00124
00125     /*
00126     * \brief Prints Extended L1-Only GLONASS RTK Observables
00127     * \details This GLONASS message type is used when only L1 data is present and bandwidth is very tight, often 1012 is used in such cases.
00128     * \note Code added as part of GSoC 2017 program
00129     * \param glonass_gnav_eph GLONASS GNAV Broadcast Ephemeris
00130     * \param obs_time Time of observation at the moment of printing

```

```

00131     * \param observables Set of observables as defined by the platform
00132     * \return true or false upon operation success
00133     */
00134     bool Print_Rtcm_MT1010(const Glonass_Gnav_Ephemeris& glonass_gnav_eph, double obs_time, const
std::map<int32_t, Gnss_Synchro>& observables);
00135
00136     /*
00137     * \brief Prints L1&L2 GLONASS RTK Observables
00138     * \details This GLONASS message type is not generally used or supported; type 1012 is to be
preferred
00139     * \note Code added as part of GSoC 2017 program
00140     * \param glonass_gnav_ephL1 GLONASS L1 GNAV Broadcast Ephemeris for satellite
00141     * \param glonass_gnav_ephL2 GLONASS L2 GNAV Broadcast Ephemeris for satellite
00142     * \param obs_time Time of observation at the moment of printing
00143     * \param observables Set of observables as defined by the platform
00144     * \return true or false upon operation success
00145     */
00146     bool Print_Rtcm_MT1011(const Glonass_Gnav_Ephemeris& glonass_gnav_ephL1, const
Glonass_Gnav_Ephemeris& glonass_gnav_ephL2, double obs_time, const std::map<int32_t, Gnss_Synchro>&
observables);
00147
00148     /*
00149     * \brief Prints Extended L1&L2 GLONASS RTK Observables
00150     * \details This GLONASS message type is the most common observational message type, with
L1/L2/SNR content. This is one of the most common messages found.
00151     * \note Code added as part of GSoC 2017 program
00152     * \param glonass_gnav_ephL1 GLONASS L1 GNAV Broadcast Ephemeris for satellite
00153     * \param glonass_gnav_ephL2 GLONASS L2 GNAV Broadcast Ephemeris for satellite
00154     * \param obs_time Time of observation at the moment of printing
00155     * \param observables Set of observables as defined by the platform
00156     * \return true or false upon operation success
00157     */
00158     bool Print_Rtcm_MT1012(const Glonass_Gnav_Ephemeris& glonass_gnav_ephL1, const
Glonass_Gnav_Ephemeris& glonass_gnav_ephL2, double obs_time, const std::map<int32_t, Gnss_Synchro>&
observables);
00159
00160     bool Print_Rtcm_MT1019(const Gps_Ephemeris& gps_eph); // GPS Ephemeris, should be broadcast
in the event that the IODC does not match the IODE, and every 2 minutes.
00161     bool Print_Rtcm_MT1045(const Galileo_Ephemeris& gal_eph); // Galileo Ephemeris, should be
broadcast every 2 minutes
00162
00163     /*
00164     * \brief Prints GLONASS GNAV Ephemeris
00165     * \details This GLONASS message should be broadcast every 2 minutes
00166     * \note Code added as part of GSoC 2017 program
00167     * \param glonass_gnav_eph GLONASS GNAV Broadcast Ephemeris
00168     * \param utc_model GLONASS GNAV Clock Information broadcast in string 5
00169     * \return true or false upon operation success
00170     */
00171     bool Print_Rtcm_MT1020(const Glonass_Gnav_Ephemeris& glonass_gnav_eph, const
Glonass_Gnav_Utc_Model& utc_model);
00172
00173     bool Print_Rtcm_MSM(uint32_t msm_number,
00174         const Gps_Ephemeris& gps_eph,
00175         const Gps_CNAV_Ephemeris& gps_cnav_eph,
00176         const Galileo_Ephemeris& gal_eph,
00177         const Glonass_Gnav_Ephemeris& glo_gnav_eph,
00178         double obs_time,
00179         const std::map<int32_t, Gnss_Synchro>& observables,
00180         uint32_t clock_steering_indicator,
00181         uint32_t external_clock_indicator,
00182         int32_t smooth_int,
00183         bool divergence_free,
00184         bool more_messages);
00185
00186     bool Print_IGM01(const Galileo_HAS_data& has_data); // SSR Orbit Corrections
00187     bool Print_IGM02(const Galileo_HAS_data& has_data); // SSR Clock Corrections
00188     bool Print_IGM03(const Galileo_HAS_data& has_data); // SSR Combined Orbit & Clock Corrections
00189     bool Print_IGM05(const Galileo_HAS_data& has_data); // SSR Bias Corrections
00190
00191     int32_t init_serial(const std::string& serial_device); // serial port control
00192     void close_serial() const;
00193     bool Print_Message(const std::string& message);
00194
00195     std::unique_ptr<Rtcm> rtcm;
00196     std::ofstream rtcm_file_descriptor; // Output file stream for RTCM log file
00197     std::string rtcm_filename; // String with the RTCM log filename
00198     std::string rtcm_base_path;
00199     std::string rtcm_devname;
00200     int32_t rtcm_dev_descriptor; // RTCM serial device descriptor (i.e. COM port)
00201     uint16_t port;
00202     uint16_t station_id;
00203     bool d_rtcml_has_written_once;
00204     bool d_rtcml_file_dump;
00205     const Signal_Enabled_Flags d_flags;
00206 };
00207

```

```

00208
00209 /** \} */
00210 /** \} */
00211 #endif // GNSS_SDR_RTCM_PRINTER_H

```

13.306 rtklib_solver.h File Reference

PVT solver based on rtklib library functions adapted to the GNSS-SDR data flow and structures.

```

#include "beidou_dnav_almanac.h"
#include "beidou_dnav_ephemeris.h"
#include "beidou_dnav_iono.h"
#include "beidou_dnav_utc_model.h"
#include "galileo_almanac.h"
#include "galileo_ephemeris.h"
#include "galileo_has_data.h"
#include "galileo_iono.h"
#include "galileo_utc_model.h"
#include "glonass_gnav_almanac.h"
#include "glonass_gnav_ephemeris.h"
#include "glonass_gnav_utc_model.h"
#include "gnss_synchro.h"
#include "gps_almanac.h"
#include "gps_cnav_ephemeris.h"
#include "gps_cnav_iono.h"
#include "gps_cnav_utc_model.h"
#include "gps_ephemeris.h"
#include "gps_iono.h"
#include "gps_utc_model.h"
#include "monitor_pvt.h"
#include "pvt_conf.h"
#include "pvt_kf.h"
#include "pvt_solution.h"
#include "rtklib.h"
#include "rtklib_conversions.h"
#include "sensor_data/sensor_data_aggregator.h"
#include <array>
#include <stdint>
#include <fstream>
#include <map>
#include <string>
#include <utility>

```

Classes

- class [Rtklib_Solver](#)

This class implements a PVT solution based on RTKLIB.

13.306.1 Detailed Description

PVT solver based on rtklib library functions adapted to the GNSS-SDR data flow and structures.

Authors

- 2017, Javier Arribas
- 2017-2023, Carles Fernandez
- 2007-2013, T. Takasu

This is a derived work from RTKLIB <http://www.rtklib.com/> The original source code at <https://github.com/tomojitakasu/RTKLIB> is released under the BSD 2-clause license with an additional exclusive clause that does not apply here. This additional clause is reproduced below:

" The software package includes some companion executive binaries or shared libraries necessary to execute APs on Windows. These licenses succeed to the original ones of these software. "

Neither the executive binaries nor the shared libraries are required by, used or included in GNSS-SDR.

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Definition in file [rtklib_solver.h](#).

13.307 rtklib_solver.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file rtklib_solver.h
00003  * \brief PVT solver based on rtklib library functions adapted to the GNSS-SDR
00004  * data flow and structures
00005  * \authors <ul>
00006  *         <li> 2017, Javier Arribas
00007  *         <li> 2017-2023, Carles Fernandez
00008  *         <li> 2007-2013, T. Takasu
00009  *     </ul>
00010  *
00011  * This is a derived work from RTKLIB http://www.rtklib.com/
00012  * The original source code at https://github.com/tomojitakasu/RTKLIB is
00013  * released under the BSD 2-clause license with an additional exclusive clause
00014  * that does not apply here. This additional clause is reproduced below:
00015  *
00016  * " The software package includes some companion executive binaries or shared
00017  * libraries necessary to execute APs on Windows. These licenses succeed to the
00018  * original ones of these software. "
00019  *
00020  * Neither the executive binaries nor the shared libraries are required by, used
00021  * or included in GNSS-SDR.
00022  *
00023  * -----
00024  * Copyright (C) 2007-2013, T. Takasu
00025  * Copyright (C) 2017-2019, Javier Arribas
00026  * Copyright (C) 2017-2023, Carles Fernandez
00027  * All rights reserved.
00028  *
00029  * SPDX-License-Identifier: BSD-2-Clause
00030  *
00031  * -----
00032  */
00033
00034 #ifndef GNSS_SDR_RTKLIB_SOLVER_H
00035 #define GNSS_SDR_RTKLIB_SOLVER_H
00036
00037
00038 #include "beidou_dnav_almanac.h"
00039 #include "beidou_dnav_ephemeris.h"
00040 #include "beidou_dnav_iono.h"
00041 #include "beidou_dnav_utc_model.h"
00042 #include "galileo_almanac.h"
00043 #include "galileo_ephemeris.h"
00044 #include "galileo_has_data.h"
00045 #include "galileo_iono.h"
00046 #include "galileo_utc_model.h"
00047 #include "glonass_gnav_almanac.h"
00048 #include "glonass_gnav_ephemeris.h"
00049 #include "glonass_gnav_utc_model.h"
00050 #include "gnss_synchro.h"
00051 #include "gps_almanac.h"
00052 #include "gps_cnav_ephemeris.h"
00053 #include "gps_cnav_iono.h"
00054 #include "gps_cnav_utc_model.h"
00055 #include "gps_ephemeris.h"
00056 #include "gps_iono.h"
00057 #include "gps_utc_model.h"
00058 #include "monitor_pvt.h"
00059 #include "pvt_conf.h"
00060 #include "pvt_kf.h"
00061 #include "pvt_solution.h"
00062 #include "rtklib.h"
00063 #include "rtklib_conversions.h"
00064 #include "sensor_data/sensor_data_aggregator.h"
00065 #include <array>
00066 #include <stdint>

```

```

00067 #include <fstream>
00068 #include <map>
00069 #include <string>
00070 #include <utility>
00071
00072 /** \addtogroup PVT
00073  * \{ */
00074 /** \addtogroup PVT_libs pvt_libs
00075  * Library for the computation of PVT solutions.
00076  * \{ */
00077
00078
00079 /*!
00080  * \brief This class implements a PVT solution based on RTKLIB
00081  */
00082 class Rtklib_Solver : public Pvt_Solution
00083 {
00084 public:
00085     Rtklib_Solver(const rtk_t& rtk,
00086                  const Pvt_Conf& conf,
00087                  const std::string& dump_filename,
00088                  uint32_t signal_enabled_flags,
00089                  bool flag_dump_to_file,
00090                  bool flag_dump_to_mat);
00091
00092     ~Rtklib_Solver();
00093
00094     bool get_PVT(const std::map<int, Gnss_Synchro>& gnss_observables_map, double kf_update_interval_s,
00095                 const SensorDataAggregator& sensor_data_aggregator);
00096
00097     double get_hdop() const override;
00098     double get_vdop() const override;
00099     double get_pdop() const override;
00100     double get_gdop() const override;
00101     Monitor_Pvt get_monitor_pvt() const;
00102     void store_has_data(const Galileo_HAS_data& new_has_data);
00103     void update_has_corrections(const std::map<int, Gnss_Synchro>& obs_map);
00104
00105     sol_t pvt_sol{};
00106     std::array<ssat_t, MAXSAT> pvt_ssat{};
00107     std::map<int, Galileo_Ephemeris> galileo_ephemeris_map;           //!< Map storing new
00108     Galileo_Ephemeris std::map<int, Gps_Ephemeris> gps_ephemeris_map;           //!< Map storing new
00109     GPS_Ephemeris std::map<int, Gps_CNAV_Ephemeris> gps_cnav_ephemeris_map;           //!< Map storing new
00110     GPS_CNAV_Ephemeris std::map<int, Glonass_Gnav_Ephemeris> glonass_gnav_ephemeris_map;           //!< Map storing new GLONASS
00111     GNAV_Ephemeris std::map<int, Beidou_Dnav_Ephemeris> beidou_dnav_ephemeris_map;           //!< Map storing new BeiDou
00112     DNAV_Ephemeris
00113     Galileo_Utc_Model galileo_utc_model;
00114     Galileo_Iono galileo_iono;
00115     std::map<int, Galileo_Almanac> galileo_almanac_map;
00116
00117     Gps_Utc_Model gps_utc_model;
00118     Gps_Iono gps_iono;
00119     std::map<int, Gps_Almanac> gps_almanac_map;
00120
00121     Gps_CNAV_Iono gps_cnav_iono;
00122     Gps_CNAV_Utc_Model gps_cnav_utc_model;
00123
00124     Glonass_Gnav_Utc_Model glonass_gnav_utc_model;           //!< Map storing GLONASS GNAV UTC Model
00125     Glonass_Gnav_Almanac glonass_gnav_almanac;           //!< Map storing GLONASS GNAV Almanac Model
00126
00127     Beidou_Dnav_Utc_Model beidou_dnav_utc_model;
00128     Beidou_Dnav_Iono beidou_dnav_iono;
00129     std::map<int, Beidou_Dnav_Almanac> beidou_dnav_almanac_map;
00130
00131 private:
00132     bool save_matfile() const;
00133
00134     void check_has_orbit_clock_validity(const std::map<int, Gnss_Synchro>& obs_map);
00135     void get_has_biases(const std::map<int, Gnss_Synchro>& obs_map);
00136     void get_current_has_obs_correction(const std::string& signal, uint32_t tow_obs, int prn);
00137
00138     std::array<obsd_t, MAXOBS> d_obs_data{};
00139     std::array<double, 4> d_dop{};
00140     std::map<int, int> d_rtklib_freq_index;
00141     std::map<std::string, int> d_rtklib_band_index;
00142
00143     std::map<std::string, std::map<int, HAS_orbit_corrections>> d_has_orbit_corrections_store_map;           //
00144     first key is system, second key is PRN
00145     std::map<std::string, std::map<int, HAS_clock_corrections>> d_has_clock_corrections_store_map;           //
00146     first key is system, second key is PRN
00147
00148

```

```

00146     std::map<std::string, std::map<int, std::pair<float, uint32_t>> d_has_code_bias_store_map; //
        first key is signal, second key is PRN
00147     std::map<std::string, std::map<int, std::pair<float, uint32_t>> d_has_phase_bias_store_map; //
        first key is signal, second key is PRN
00148
00149     std::map<std::string, std::map<int, HAS_obs_corrections> d_has_obs_corr_map; // first key is
        signal, second key is PRN
00150
00151     std::string d_dump_filename;
00152     std::ofstream d_dump_file;
00153     rtk_t d_rtk{};
00154     nav_t d_nav_data{};
00155     Monitor_Pvt d_monitor_pvt{};
00156     Pvt_Conf d_conf;
00157     Pvt_Kf d_pvt_kf;
00158     uint32_t d_signal_enabled_flags;
00159     bool d_flag_dump_enabled;
00160     bool d_flag_dump_mat_enabled;
00161 };
00162
00163
00164 /** \} */
00165 /** \} */
00166 #endif // GNSS_SDR_RTKLIB_SOLVER_H

```

13.308 serdes_galileo_eph.h File Reference

Serialization / Deserialization of [Galileo_Ephemeris](#) objects using Protocol Buffers.

```

#include "galileo_ephemeris.h"
#include "galileo_ephemeris.pb.h"
#include <memory>
#include <string>
#include <utility>

```

Classes

- class [Serdes_Galileo_Eph](#)

This class implements serialization and deserialization of [Galileo_Ephemeris](#) using Protocol Buffers.

13.308.1 Detailed Description

Serialization / Deserialization of [Galileo_Ephemeris](#) objects using Protocol Buffers.

Author

Javier Arribas, 2021. jarribas(at)cttc.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [serdes_galileo_eph.h](#).

13.309 serdes_galileo_eph.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file serdes_galileo_eph.h
00003  * \brief Serialization / Deserialization of Galileo_Ephemeris objects using
00004  * Protocol Buffers
00005  * \author Javier Arribas, 2021. jarribas(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */

```

```

00017
00018 #ifndef GNSS_SDR_SERDES_GALILEO_EPH_H
00019 #define GNSS_SDR_SERDES_GALILEO_EPH_H
00020
00021 #include "galileo_ephemeris.h"
00022 #include "galileo_ephemeris.pb.h" // file created by Protocol Buffers at compile time
00023 #include <memory>
00024 #include <string>
00025 #include <utility>
00026
00027 /** \addtogroup PVT
00028 * \{ */
00029 /** \addtogroup PVT_libs
00030 * \{ */
00031
00032
00033 /*!
00034 * \brief This class implements serialization and deserialization of
00035 * Galileo_Ephemeris using Protocol Buffers.
00036 */
00037 class Serdes_Galileo_Eph
00038 {
00039 public:
00040     Serdes_Galileo_Eph()
00041     {
00042         // Verify that the version of the library that we linked against is
00043         // compatible with the version of the headers we compiled against.
00044         GOOGLE_PROTOBUF_VERIFY_VERSION;
00045     }
00046
00047     ~Serdes_Galileo_Eph()
00048     {
00049         // google::protobuf::ShutdownProtobufLibrary();
00050     }
00051
00052     inline Serdes_Galileo_Eph(const Serdes_Galileo_Eph& other) noexcept : monitor_(other.monitor_)
00053     /*!< Copy constructor
00054     {
00055     }
00056
00057     inline Serdes_Galileo_Eph& operator=(const Serdes_Galileo_Eph& rhs) noexcept /*!< Copy assignment
00058     operator
00059     {
00060         Serdes_Galileo_Eph temp(rhs);
00061         std::swap(this->monitor_, temp.monitor_);
00062         return *this;
00063     }
00064
00065     inline Serdes_Galileo_Eph(Serdes_Galileo_Eph&& other) noexcept :
00066     monitor_(std::move(other.monitor_)) /*!< Move constructor
00067     {
00068     }
00069
00070     inline Serdes_Galileo_Eph& operator=(Serdes_Galileo_Eph&& other) noexcept /*!< Move assignment
00071     operator
00072     {
00073         std::swap(this->monitor_, other.monitor_);
00074         return *this;
00075     }
00076
00077     inline std::string createProtobuffer(const std::shared_ptr<Galileo_Ephemeris> monitor) /*!<
00078     Serialization into a string
00079     {
00080         monitor_.Clear();
00081
00082         std::string data;
00083
00084         monitor_.set_prn(monitor->PRN);
00085         monitor_.set_m_0(monitor->M_0);
00086         monitor_.set_delta_n(monitor->delta_n);
00087         monitor_.set_ecc(monitor->ecc);
00088         monitor_.set_sqrtA(monitor->sqrtA);
00089         monitor_.set_omega_0(monitor->OMEGA_0);
00090         monitor_.set_i_0(monitor->i_0);
00091         monitor_.set_omega(monitor->omega);
00092         monitor_.set_omegadot(monitor->OMEGAdot);
00093         monitor_.set_idot(monitor->idot);
00094         monitor_.set_cuc(monitor->Cuc);
00095         monitor_.set_cus(monitor->Cus);
00096         monitor_.set_crc(monitor->Crc);
00097         monitor_.set_crs(monitor->Crs);
00098         monitor_.set_cic(monitor->Cic);
00099         monitor_.set_cis(monitor->Cis);
00100         monitor_.set_toe(monitor->toe);
00101         monitor_.set_toc(monitor->toc);
00102         monitor_.set_af0(monitor->af0);
00103         monitor_.set_af1(monitor->af1);

```

```

00099     monitor_.set_af2(monitor->af2);
00100     monitor_.set_satclkdrift(monitor->satClkDrift);
00101     monitor_.set_dtr(monitor->dtr);
00102     monitor_.set_wn(monitor->WN);
00103     monitor_.set_tow(monitor->tow);
00104
00105     // Galileo-specific parameters
00106     monitor_.set_iod_ephemeris(monitor->IOD_ephemeris);
00107     monitor_.set_iod_nav(monitor->IOD_nav);
00108     monitor_.set_sisa(monitor->SISA);
00109     monitor_.set_e5a_hs(monitor->E5a_HS);
00110     monitor_.set_e5b_hs(monitor->E5b_HS);
00111     monitor_.set_e1b_hs(monitor->E1B_HS);
00112     monitor_.set_e5a_dvs(monitor->E5a_DVS);
00113     monitor_.set_e5b_dvs(monitor->E5b_DVS);
00114     monitor_.set_e1b_dvs(monitor->E1B_DVS);
00115     monitor_.set_bgd_ele5a(monitor->BGD_E1E5a);
00116     monitor_.set_bgd_ele5b(monitor->BGD_E1E5b);
00117
00118     monitor_.SerializeToString(&data);
00119     return data;
00120 }
00121
00122 inline Galileo_Ephemeris readProtobuffer(const gnss_sdr::GalileoEphemeris& mon) const //!<
Deserialization
00123 {
00124     Galileo_Ephemeris monitor;
00125
00126     monitor.PRN = mon.prn();
00127     monitor.M_0 = mon.m_0();
00128     monitor.delta_n = mon.delta_n();
00129     monitor.ecc = mon.ecc();
00130     monitor.sqrta = mon.sqrta();
00131     monitor.OMEGA_0 = mon.omega_0();
00132     monitor.i_0 = mon.i_0();
00133     monitor.omega = mon.omega();
00134     monitor.OMEGAdot = mon.omegadot();
00135     monitor.idot = mon.idot();
00136     monitor.Cuc = mon.cuc();
00137     monitor.Cus = mon.cus();
00138     monitor.Crc = mon.crc();
00139     monitor.Crs = mon.crs();
00140     monitor.Cic = mon.cic();
00141     monitor.Cis = mon.cis();
00142     monitor.toe = mon.toe();
00143     monitor.toc = mon.toc();
00144     monitor.af0 = mon.af0();
00145     monitor.af1 = mon.af1();
00146     monitor.af2 = mon.af2();
00147     monitor.satClkDrift = mon.satclkdrift();
00148     monitor.dtr = mon.dtr();
00149     monitor.WN = mon.wn();
00150     monitor.tow = mon.tow();
00151
00152     // Galileo-specific parameters
00153     monitor.IOD_ephemeris = mon.iod_ephemeris();
00154     monitor.IOD_nav = mon.iod_nav();
00155     monitor.SISA = mon.sisa();
00156     monitor.E5a_HS = mon.e5a_hs();
00157     monitor.E5b_HS = mon.e5b_hs();
00158     monitor.E1B_HS = mon.e1b_hs();
00159     monitor.E5a_DVS = mon.e5a_dvs();
00160     monitor.E5b_DVS = mon.e5b_dvs();
00161     monitor.E1B_DVS = mon.e1b_dvs();
00162     monitor.BGD_E1E5a = mon.bgd_ele5a();
00163     monitor.BGD_E1E5b = mon.bgd_ele5b();
00164
00165     return monitor;
00166 }
00167
00168 private:
00169     gnss_sdr::GalileoEphemeris monitor_{};
00170 };
00171
00172
00173 /** \} */
00174 /** \} */
00175 #endif // GGNSS_SDR_SERDES_GALILEO_EPH_H

```

13.310 serdes_gps_eph.h File Reference

Serialization / Deserialization of [Gps_Ephemeris](#) objects using Protocol Buffers.


```
#include "gps_ephemeris.h"
#include "gps_ephemeris.pb.h"
#include <memory>
#include <string>
#include <utility>
```

Classes

- class [Serdes_Gps_Eph](#)

This class implements serialization and deserialization of [Gps_Ephemeris](#) objects using Protocol Buffers.

13.310.1 Detailed Description

Serialization / Deserialization of [Gps_Ephemeris](#) objects using Protocol Buffers.

Author

Javier Arribas, 2021. jarribas(at)cttc.es

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 Definition in file [serdes_gps_eph.h](#).

13.311 serdes_gps_eph.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file serdes_gps_eph.h
00003  * \brief Serialization / Deserialization of Gps_Ephemeris objects using
00004  * Protocol Buffers
00005  * \author Javier Arribas, 2021. jarribas(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_SERDES_GPS_EPH_H
00019 #define GNSS_SDR_SERDES_GPS_EPH_H
00020
00021 #include "gps_ephemeris.h"
00022 #include "gps_ephemeris.pb.h" // file created by Protocol Buffers at compile time
00023 #include <memory>
00024 #include <string>
00025 #include <utility>
00026
00027 /** \addtogroup PVT
00028  * \{ */
00029 /** \addtogroup PVT_libs
00030  * \{ */
00031
00032 /*!
00033  * \brief This class implements serialization and deserialization of
00034  * Gps_Ephemeris objects using Protocol Buffers.
00035  */
00036 class Serdes_Gps_Eph
00037 {
00038 public:
00039     Serdes_Gps_Eph()
00040     {
00041         // Verify that the version of the library that we linked against is
00042         // compatible with the version of the headers we compiled against.
00043         GOOGLE_PROTOBUF_VERIFY_VERSION;
00044     }
00045
00046     ~Serdes_Gps_Eph()
00047     {
00048         // google::protobuf::ShutdownProtobufLibrary();
00049     }
00050 }
```

```

00049     }
00050
00051     inline Serdes_Gps_Eph(const Serdes_Gps_Eph& other) noexcept : monitor_(other.monitor_) //!< Copy
    constructor
00052     {
00053     }
00054
00055     inline Serdes_Gps_Eph& operator=(const Serdes_Gps_Eph& rhs) noexcept //!< Copy assignment
    operator
00056     {
00057         Serdes_Gps_Eph temp(rhs);
00058         std::swap(this->monitor_, temp.monitor_);
00059         return *this;
00060     }
00061
00062     inline Serdes_Gps_Eph(Serdes_Gps_Eph&& other) noexcept : monitor_(std::move(other.monitor_)) //!<
    Move constructor
00063     {
00064     }
00065
00066     inline Serdes_Gps_Eph& operator=(Serdes_Gps_Eph&& other) noexcept //!< Move assignment operator
00067     {
00068         std::swap(this->monitor_, other.monitor_);
00069         return *this;
00070     }
00071
00072     inline std::string createProtobuffer(const std::shared_ptr<Gps_Ephemeris> monitor) //!<
    Serialization into a string
00073     {
00074         monitor_.Clear();
00075         std::string data;
00076
00077         monitor_.set_prn(monitor->PRN);
00078         monitor_.set_m_0(monitor->M_0);
00079         monitor_.set_delta_n(monitor->delta_n);
00080         monitor_.set_ecc(monitor->ecc);
00081         monitor_.set_sqrt_a(monitor->sqrtA);
00082         monitor_.set_omega_0(monitor->OMEGA_0);
00083         monitor_.set_i_0(monitor->i_0);
00084         monitor_.set_omega(monitor->omega);
00085         monitor_.set_omegadot(monitor->OMEGAdot);
00086         monitor_.set_idot(monitor->idot);
00087         monitor_.set_cuc(monitor->Cuc);
00088         monitor_.set_cus(monitor->Cus);
00089         monitor_.set_crc(monitor->Crc);
00090         monitor_.set_crs(monitor->Crs);
00091         monitor_.set_cic(monitor->Cic);
00092         monitor_.set_cis(monitor->Cis);
00093         monitor_.set_toe(monitor->toe);
00094         monitor_.set_toc(monitor->toc);
00095         monitor_.set_af0(monitor->af0);
00096         monitor_.set_af1(monitor->af1);
00097         monitor_.set_af2(monitor->af2);
00098         monitor_.set_satclkdrift(monitor->satClkDrift);
00099         monitor_.set_dtr(monitor->dtr);
00100         monitor_.set_wn(monitor->WN);
00101         monitor_.set_tow(monitor->tow);
00102
00103         // GPS-specific parameters
00104         monitor_.set_code_on_l2(monitor->code_on_L2);
00105         monitor_.set_l2_p_data_flag(monitor->L2_P_data_flag);
00106         monitor_.set_sv_accuracy(monitor->SV_accuracy);
00107         monitor_.set_sv_health(monitor->SV_health);
00108         monitor_.set_tgd(monitor->TGD);
00109         monitor_.set_iode(monitor->IODC);
00110         monitor_.set_iode_sf2(monitor->IODE_SF2);
00111         monitor_.set_iode_sf3(monitor->IODE_SF3);
00112         monitor_.set_aodo(monitor->AODO);
00113         monitor_.set_fit_interval_flag(monitor->fit_interval_flag);
00114         monitor_.set_spare1(monitor->spare1);
00115         monitor_.set_spare2(monitor->spare2);
00116         monitor_.set_integrity_status_flag(monitor->integrity_status_flag);
00117         monitor_.set_alert_flag(monitor->alert_flag);
00118         monitor_.set_antispoofing_flag(monitor->antispoofing_flag);
00119
00120         monitor_.SerializeToString(&data);
00121         return data;
00122     }
00123
00124     inline Gps_Ephemeris readProtobuffer(const gnss_sdr::GpsEphemeris& mon) const //!<
    Deserialization
00125     {
00126         Gps_Ephemeris monitor;
00127
00128         monitor.PRN = mon.prn();
00129         monitor.M_0 = mon.m_0();
00130         monitor.delta_n = mon.delta_n();

```

```

00131     monitor.ecc = mon.ecc();
00132     monitor.sqrta = mon.sqrta();
00133     monitor.OMEGA_0 = mon.omega_0();
00134     monitor.i_0 = mon.i_0();
00135     monitor.omega = mon.omega();
00136     monitor.OMEGAdot = mon.omegadot();
00137     monitor.idot = mon.idot();
00138     monitor.Cuc = mon.cuc();
00139     monitor.Cus = mon.cus();
00140     monitor.Crc = mon.crc();
00141     monitor.Crs = mon.crs();
00142     monitor.Cic = mon.cic();
00143     monitor.Cis = mon.cis();
00144     monitor.toe = mon.toe();
00145     monitor.toc = mon.toc();
00146     monitor.af0 = mon.af0();
00147     monitor.af1 = mon.af1();
00148     monitor.af2 = mon.af2();
00149     monitor.satClkDrift = mon.satclkdrift();
00150     monitor.dtr = mon.dtr();
00151     monitor.WN = mon.wn();
00152     monitor.tow = mon.tow();
00153
00154     // GPS-specific parameters
00155     monitor.code_on_L2 = mon.code_on_l2();
00156     monitor.L2_P_data_flag = mon.l2_p_data_flag();
00157     monitor.SV_accuracy = mon.sv_accuracy();
00158     monitor.SV_health = mon.sv_health();
00159     monitor.TGD = mon.tgd();
00160     monitor.IODC = mon.iodec();
00161     monitor.IODE_SF2 = mon.iode_sf2();
00162     monitor.IODE_SF3 = mon.iode_sf3();
00163     monitor.AODO = mon.aodo();
00164     monitor.fit_interval_flag = mon.fit_interval_flag();
00165     monitor.spare1 = mon.spare1();
00166     monitor.spare2 = mon.spare2();
00167     monitor.integrity_status_flag = mon.integrity_status_flag();
00168     monitor.alert_flag = mon.alert_flag();
00169     monitor.antispoofing_flag = mon.antispoofing_flag();
00170
00171     return monitor;
00172 }
00173
00174 private:
00175     gnss_sdr::GpsEphemeris monitor_{};
00176 };
00177
00178
00179 /** \} */
00180 /** \} */
00181 #endif // GNSS_SDR_SERDES_GPS_EPH_H

```

13.312 serdes_monitor_pvt.h File Reference

Serialization / Deserialization of [Monitor_Pvt](#) objects using Protocol Buffers.

```

#include "monitor_pvt.h"
#include "monitor_pvt.pb.h"
#include <memory>
#include <string>
#include <utility>

```

Classes

- class [Serdes_Monitor_Pvt](#)

This class implements serialization and deserialization of [Monitor_Pvt](#) objects using Protocol Buffers.

13.312.1 Detailed Description

Serialization / Deserialization of [Monitor_Pvt](#) objects using Protocol Buffers.

Author

Carles Fernandez-Prades, 2019. cfernandez(at)cttc.es

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 Definition in file [serdes_monitor_pvt.h](#).

13.313 serdes_monitor_pvt.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file serdes_monitor_pvt.h
00003  * \brief Serialization / Deserialization of Monitor_Pvt objects using
00004  * Protocol Buffers
00005  * \author Carles Fernandez-Prades, 2019. cfernandez(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_SERDES_MONITOR_PVT_H
00019 #define GNSS_SDR_SERDES_MONITOR_PVT_H
00020
00021 #include "monitor_pvt.h"
00022 #include "monitor_pvt.pb.h" // file created by Protocol Buffers at compile time
00023 #include <memory>
00024 #include <string>
00025 #include <utility>
00026
00027 /** \addtogroup PVT
00028  * \{ */
00029 /** \addtogroup PVT_libs
00030  * \{ */
00031
00032
00033 /*!
00034  * \brief This class implements serialization and deserialization of
00035  * Monitor_Pvt objects using Protocol Buffers.
00036  */
00037 class Serdes_Monitor_Pvt
00038 {
00039 public:
00040     Serdes_Monitor_Pvt()
00041     {
00042         // Verify that the version of the library that we linked against is
00043         // compatible with the version of the headers we compiled against.
00044         GOOGLE_PROTOBUF_VERIFY_VERSION;
00045     }
00046
00047     ~Serdes_Monitor_Pvt()
00048     {
00049         // google::protobuf::ShutdownProtobufLibrary();
00050     }
00051
00052     inline Serdes_Monitor_Pvt(const Serdes_Monitor_Pvt& other) noexcept : monitor_(other.monitor_)
00053     /**< Copy constructor
00054     {
00055
00056     inline Serdes_Monitor_Pvt& operator=(const Serdes_Monitor_Pvt& rhs) noexcept /**< Copy assignment
00057     operator
00058     {
00059         if (this != &rhs)
00060         {
00061             this->monitor_.CopyFrom(rhs.monitor_);
00062         }
00063         return *this;
00064     }
00065
00066     inline Serdes_Monitor_Pvt(Serdes_Monitor_Pvt&& other) noexcept :
00067     monitor_(std::move(other.monitor_)) /**< Move constructor
00068     {
00069         // Set the other object's monitor_ to a default-constructed state
00070         other.monitor_ = gnss_sdr::MonitorPvt{};
00071     }

```

```

00070
00071     inline Serdes_Monitor_Pvt& operator=(Serdes_Monitor_Pvt&& other) noexcept //!< Move assignment
operator
00072     {
00073         if (this != &other)
00074         {
00075             this->monitor_ = std::move(other.monitor_);
00076         }
00077         return *this;
00078     }
00079
00080     inline std::string createProtobuffer(const Monitor_Pvt* const monitor) //!< Serialization into a
string
00081     {
00082         monitor_.Clear();
00083
00084         std::string data;
00085
00086         monitor_.set_tow_at_current_symbol_ms(monitor->TOW_at_current_symbol_ms);
00087         monitor_.set_week(monitor->week);
00088         monitor_.set_rx_time(monitor->RX_time);
00089         monitor_.set_user_clk_offset(monitor->user_clk_offset);
00090         monitor_.set_pos_x(monitor->pos_x);
00091         monitor_.set_pos_y(monitor->pos_y);
00092         monitor_.set_pos_z(monitor->pos_z);
00093         monitor_.set_vel_x(monitor->vel_x);
00094         monitor_.set_vel_y(monitor->vel_y);
00095         monitor_.set_vel_z(monitor->vel_z);
00096         monitor_.set_cov_xx(monitor->cov_xx);
00097         monitor_.set_cov_yy(monitor->cov_yy);
00098         monitor_.set_cov_zz(monitor->cov_zz);
00099         monitor_.set_cov_xy(monitor->cov_xy);
00100         monitor_.set_cov_yz(monitor->cov_yz);
00101         monitor_.set_cov_zx(monitor->cov_zx);
00102         monitor_.set_latitude(monitor->latitude);
00103         monitor_.set_longitude(monitor->longitude);
00104         monitor_.set_height(monitor->height);
00105         monitor_.set_valid_sats(monitor->valid_sats);
00106         monitor_.set_solution_status(monitor->solution_status);
00107         monitor_.set_solution_type(monitor->solution_type);
00108         monitor_.set_ar_ratio_factor(monitor->AR_ratio_factor);
00109         monitor_.set_ar_ratio_threshold(monitor->AR_ratio_threshold);
00110         monitor_.set_gdop(monitor->gdop);
00111         monitor_.set_pdop(monitor->pdop);
00112         monitor_.set_hdop(monitor->hdop);
00113         monitor_.set_vdop(monitor->vdop);
00114         monitor_.set_user_clk_drift_ppm(monitor->user_clk_drift_ppm);
00115         monitor_.set_utc_time(monitor->utc_time);
00116         monitor_.set_vel_e(monitor->vel_e);
00117         monitor_.set_vel_n(monitor->vel_n);
00118         monitor_.set_vel_u(monitor->vel_u);
00119         monitor_.set_cog(monitor->cog);
00120         monitor_.set_galhas_status(monitor->galhas_status);
00121         monitor_.set_geohash(monitor->geohash);
00122
00123         monitor_.SerializeToString(&data);
00124         return data;
00125     }
00126
00127     inline Monitor_Pvt readProtobuffer(const gnss_sdr::MonitorPvt& mon) const //!< Deserialization
00128     {
00129         Monitor_Pvt monitor;
00130
00131         monitor.TOW_at_current_symbol_ms = mon.tow_at_current_symbol_ms();
00132         monitor.week = mon.week();
00133         monitor.RX_time = mon.rx_time();
00134         monitor.user_clk_offset = mon.user_clk_offset();
00135         monitor.pos_x = mon.pos_x();
00136         monitor.pos_y = mon.pos_y();
00137         monitor.pos_z = mon.pos_z();
00138         monitor.vel_x = mon.vel_x();
00139         monitor.vel_y = mon.vel_y();
00140         monitor.vel_z = mon.vel_z();
00141         monitor.cov_xx = mon.cov_xx();
00142         monitor.cov_yy = mon.cov_yy();
00143         monitor.cov_zz = mon.cov_zz();
00144         monitor.cov_xy = mon.cov_xy();
00145         monitor.cov_yz = mon.cov_yz();
00146         monitor.cov_zx = mon.cov_zx();
00147         monitor.latitude = mon.latitude();
00148         monitor.longitude = mon.longitude();
00149         monitor.height = mon.height();
00150         monitor.valid_sats = static_cast<uint8_t>(mon.valid_sats());
00151         monitor.solution_status = static_cast<uint8_t>(mon.solution_status());
00152         monitor.solution_type = static_cast<uint8_t>(mon.solution_type());
00153         monitor.AR_ratio_factor = mon.ar_ratio_factor();
00154         monitor.AR_ratio_threshold = mon.ar_ratio_threshold();

```

```

00155     monitor.gdop = mon.gdop();
00156     monitor.pdop = mon.pdop();
00157     monitor.hdop = mon.hdop();
00158     monitor.vdop = mon.vdop();
00159     monitor.user_clk_drift_ppm = mon.user_clk_drift_ppm();
00160     monitor.utc_time = mon.utc_time();
00161     monitor.vel_e = mon.vel_e();
00162     monitor.vel_n = mon.vel_n();
00163     monitor.vel_u = mon.vel_u();
00164     monitor.cog = mon.cog();
00165     monitor.galhas_status = mon.galhas_status();
00166     monitor.geohash = mon.geohash();
00167
00168     return monitor;
00169 }
00170
00171 private:
00172     gnss_sdr::MonitorPvt monitor_{};
00173 };
00174
00175
00176 /** \} */
00177 /** \} */
00178 #endif // GNSS_SDR_SERDES_MONITOR_PVT_H

```

13.314 signal_enabled_flags.h File Reference

Class to check the enabled signals.

```
#include <stdint>
```

Classes

- class [Signal_Enabled_Flags](#)

Enumerations

- enum **signal_flag** : uint32_t {
GPS_1C = 0x1 << 0 , **GPS_2S** = 0x1 << 1 , **GPS_L5** = 0x1 << 2 , **GAL_1B** = 0x1 << 3 ,
GAL_E5a = 0x1 << 4 , **GAL_E5b** = 0x1 << 5 , **GAL_E6** = 0x1 << 6 , **GLO_1G** = 0x1 << 7 ,
GLO_2G = 0x1 << 8 , **BDS_B1** = 0x1 << 9 , **BDS_B3** = 0x1 << 10 , **QZS_J1** = 0x1 << 11 ,
QZS_J5 = 0x1 << 12 }

13.314.1 Detailed Description

Class to check the enabled signals.

Author

Mathieu Favreau, 2025. favreau.mathieu(at)hotmail.com

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Definition in file [signal_enabled_flags.h](#).

13.314.2 Enumeration Type Documentation

13.314.2.1 signal_flag

```
enum signal_flag : uint32_t
```

Definition at line 24 of file [signal_enabled_flags.h](#).

13.315 signal_enabled_flags.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file signal_enabled_flags.h

```

```

00003  * \brief Class to check the enabled signals
00004  * \author Mathieu Favreau, 2025. favreau.mathieu(at)hotmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2025 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_SIGNAL_ENABLED_FLAGS_H
00018 #define GNSS_SDR_SIGNAL_ENABLED_FLAGS_H
00019
00020 #include <cstdint>
00021
00022 class ConfigurationInterface;
00023
00024 enum signal_flag : uint32_t
00025 {
00026     GPS_1C = 0x1 << 0,
00027     GPS_2S = 0x1 << 1,
00028     GPS_L5 = 0x1 << 2,
00029     GAL_1B = 0x1 << 3,
00030     GAL_E5a = 0x1 << 4,
00031     GAL_E5b = 0x1 << 5,
00032     GAL_E6 = 0x1 << 6,
00033     GLO_1G = 0x1 << 7,
00034     GLO_2G = 0x1 << 8,
00035     BDS_B1 = 0x1 << 9,
00036     BDS_B3 = 0x1 << 10,
00037     QZS_J1 = 0x1 << 11,
00038     QZS_J5 = 0x1 << 12
00039 };
00040
00041 class Signal_Enabled_Flags
00042 {
00043 public:
00044     explicit Signal_Enabled_Flags(const ConfigurationInterface* configuration);
00045     explicit Signal_Enabled_Flags(uint32_t flags_);
00046
00047     template <typename T>
00048     uint32_t or_all(const T& value) const
00049     {
00050         return value;
00051     }
00052
00053     template <typename T, typename... Args>
00054     uint32_t or_all(const T& first, const Args&... rest) const
00055     {
00056         return first | or_all(rest...);
00057     }
00058
00059     template <typename... Args>
00060     bool check_only_enabled(const Args&... args) const
00061     {
00062         return (flags ^ or_all(args...)) == 0;
00063     }
00064
00065     template <typename... Args>
00066     bool check_any_enabled(const Args&... args) const
00067     {
00068         return (flags & or_all(args...)) > 0;
00069     }
00070
00071     const uint32_t flags;
00072
00073     const bool has_gps;
00074     const bool has_galileo;
00075     const bool has_glonass;
00076     const bool has_beidou;
00077     const bool has_qzss;
00078
00079     const bool only_gps;
00080     const bool only_galileo;
00081     const bool only_glonass;
00082     const bool only_beidou;
00083     const bool only_qzss;
00084 };
00085
00086 #endif // GNSS_SDR_SIGNAL_ENABLED_FLAGS_H

```

13.316 direct_resampler_conditioner.h File Reference

Interface of an adapter of a direct resampler conditioner block to a SignalConditionerInterface.

```
#include "gnss_block_interface.h"
#include <gnuradio/hier_block2.h>
#include <string>
```

Classes

- class [DirectResamplerConditioner](#)

Interface of an adapter of a direct resampler conditioner block to a SignalConditionerInterface.

13.316.1 Detailed Description

Interface of an adapter of a direct resampler conditioner block to a SignalConditionerInterface.

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com

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 Definition in file [direct_resampler_conditioner.h](#).

13.317 direct_resampler_conditioner.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file direct_resampler_conditioner.h
00003  * \brief Interface of an adapter of a direct resampler conditioner block
00004  * to a SignalConditionerInterface
00005  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_DIRECT_RESAMPLER_CONDITIONER_H
00020 #define GNSS_SDR_DIRECT_RESAMPLER_CONDITIONER_H
00021
00022 #include "gnss_block_interface.h"
00023 #include <gnuradio/hier_block2.h>
00024 #include <string>
00025
00026 /** \addtogroup Resampler
00027  * \{ */
00028 /** \addtogroup Resampler_adapters
00029  * \{ */
00030
00031
00032 class ConfigurationInterface;
00033
00034 /*!
00035  * \brief Interface of an adapter of a direct resampler conditioner block
00036  * to a SignalConditionerInterface
00037  */
00038 class DirectResamplerConditioner : public GNSSBlockInterface
00039 {
00040 public:
00041     DirectResamplerConditioner(const ConfigurationInterface* configuration,
00042                               const std::string& role, unsigned int in_stream,
00043                               unsigned int out_stream);
00044
00045     ~DirectResamplerConditioner() = default;
00046
00047     inline std::string role() override
```



```

00048     {
00049         return role_;
00050     }
00051
00052     /*! Returns "Direct_Resampler"
00053     inline std::string implementation() override
00054     {
00055         return "Direct_Resampler";
00056     }
00057
00058     inline size_t item_size() override
00059     {
00060         return item_size_;
00061     }
00062
00063     void connect(gr::top_block_sptr top_block) override;
00064     void disconnect(gr::top_block_sptr top_block) override;
00065     gr::basic_block_sptr get_left_block() override;
00066     gr::basic_block_sptr get_right_block() override;
00067 private:
00068     gr::block_sptr resampler_;
00069     gr::block_sptr file_sink_;
00070     std::string role_;
00071     std::string item_type_;
00072     std::string dump_filename_;
00073     double sample_freq_in_;
00074     double sample_freq_out_;
00075     size_t item_size_;
00076     unsigned int in_stream_;
00077     unsigned int out_stream_;
00078     bool dump_;
00079 };
00080
00081
00082
00083 /** \} */
00084 /** \} */
00085 #endif // GNSS_SDR_DIRECT_RESAMPLER_CONDITIONER_H

```

13.318 mmse_resampler_conditioner.h File Reference

Interface of an adapter of a mmse resampler conditioner block to a SignalConditionerInterface.

```

#include "gnss_block_interface.h"
#include <gnuradio/filter/fir_filter_ccf.h>
#include <gnuradio/filter/fractional_resampler_cc.h>
#include <gnuradio/filter/firdes.h>
#include <string>

```

Classes

- class [MmseResamplerConditioner](#)
Interface of a MMSE resampler block adapter to a SignalConditionerInterface.

13.318.1 Detailed Description

Interface of an adapter of a mmse resampler conditioner block to a SignalConditionerInterface.

Author

Antonio Ramos, 2018. antonio.ramos(at)cttc.es

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 Definition in file [mmse_resampler_conditioner.h](#).

13.319 mmse_resampler_conditioner.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file mmse_resampler_conditioner.h

```

```

00003  * \brief Interface of an adapter of a mmse resampler conditioner block
00004  * to a SignalConditionerInterface
00005  * \author Antonio Ramos, 2018. antonio.ramos(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_MMSE_RESAMPLER_CONDITIONER_H
00020 #define GNSS_SDR_MMSE_RESAMPLER_CONDITIONER_H
00021
00022 #include "gnss_block_interface.h"
00023 #ifdef GR_GREATER_38
00024 #include <gnuradio/filter/fir_filter_blk.h>
00025 #include <gnuradio/filter/mmse_resampler_cc.h>
00026 #else
00027 #include <gnuradio/filter/fir_filter_ccf.h>
00028 #include <gnuradio/filter/fractional_resampler_cc.h>
00029 #endif
00030
00031 #include <gnuradio/filter/firdes.h>
00032 #include <string>
00033
00034 /** \addtogroup Resampler
00035  * Classes for input signal resampling
00036  * \{ */
00037 /** \addtogroup Resampler_adapters resampler_adapters
00038  * Classes that wrap GNU Radio resampler blocks with a GNSSBlockInterface
00039  * \{ */
00040
00041
00042 class ConfigurationInterface;
00043
00044 /*!
00045  * \brief Interface of a MMSE resampler block adapter
00046  * to a SignalConditionerInterface
00047  */
00048 class MmseResamplerConditioner : public GNSSBlockInterface
00049 {
00050 public:
00051     MmseResamplerConditioner(const ConfigurationInterface* configuration,
00052                             const std::string& role, unsigned int in_stream,
00053                             unsigned int out_stream);
00054
00055     ~MmseResamplerConditioner() = default;
00056
00057     inline std::string role() override
00058     {
00059         return role_;
00060     }
00061
00062     inline std::string implementation() override
00063     {
00064         return "Mmse_Resampler";
00065     }
00066
00067     inline size_t item_size() override
00068     {
00069         return item_size_;
00070     }
00071
00072     void connect(gr::top_block_sptr top_block) override;
00073     void disconnect(gr::top_block_sptr top_block) override;
00074     gr::basic_block_sptr get_left_block() override;
00075     gr::basic_block_sptr get_right_block() override;
00076
00077 private:
00078     #ifdef GR_GREATER_38
00079         gr::filter::mmse_resampler_cc::sptr resampler_;
00080     #else
00081         gr::filter::fractional_resampler_cc::sptr resampler_;
00082     #endif
00083     gr::filter::fir_filter_ccf::sptr fir_filter_ccf_;
00084     gr::block_sptr file_sink_;
00085     std::string role_;
00086     std::string item_type_;
00087     std::string dump_filename_;
00088     size_t item_size_;
00089     double sample_freq_in_;

```

```

00090     double sample_freq_out_;
00091     unsigned int in_stream_;
00092     unsigned int out_stream_;
00093     bool dump_;
00094 };
00095
00096
00097 /** @} */
00098 /** @} */
00099 #endif // GNSS_SDR_FRACTIONAL_RESAMPLER_CONDITIONER_H

```

13.320 direct_resampler_conditioner_cb.h File Reference

Nearest neighborhood resampler with `std::complex<signed char>` input and `std::complex<signed char>` output.

```

#include "gnss_block_interface.h"
#include <gnuradio/block.h>
#include <cstdint>

```

Classes

- class [direct_resampler_conditioner_cb](#)
This class implements a direct resampler conditioner for `std::complex<signed char>`

Typedefs

- using [direct_resampler_conditioner_cb_sptr](#) = `gnss_shared_ptr<direct_resampler_conditioner_cb>`

Functions

- `direct_resampler_conditioner_cb_sptr` **direct_resampler_make_conditioner_cb** (`double sample_freq_in`, `double sample_freq_out`)

13.320.1 Detailed Description

Nearest neighborhood resampler with `std::complex<signed char>` input and `std::complex<signed char>` output.

Author

Luis Esteve, 2011. [luis\(at\)epsilon-formacion.com](mailto:luis(at)epsilon-formacion.com)

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Definition in file [direct_resampler_conditioner_cb.h](#).

13.321 direct_resampler_conditioner_cb.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file direct_resampler_conditioner_cb.h
00003  * \brief Nearest neighborhood resampler with
00004  *         std::complex<signed char> input and std::complex<signed char> output
00005  * \author Luis Esteve, 2011. luis(at)epsilon-formacion.com
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_DIRECT_RESAMPLER_CONDITIONER_CB_H
00020 #define GNSS_SDR_DIRECT_RESAMPLER_CONDITIONER_CB_H

```

```

00021
00022 #include "gnss_block_interface.h"
00023 #include <gnuradio/block.h>
00024 #include <stdint>
00025
00026 /** \addtogroup Resampler
00027 * \{ */
00028 /** \addtogroup Resampler_gnuradio_blocks
00029 * GNU Radio blocks for input signal resampling
00030 * \{ */
00031
00032
00033 class direct_resampler_conditioner_cb;
00034
00035 using direct_resampler_conditioner_cb_sptr = gnss_shared_ptr<direct_resampler_conditioner_cb>;
00036
00037 direct_resampler_conditioner_cb_sptr direct_resampler_make_conditioner_cb(
00038     double sample_freq_in,
00039     double sample_freq_out);
00040
00041 /*!
00042 * \brief This class implements a direct resampler conditioner for std::complex<signed char>
00043 *
00044 * Direct resampling without interpolation
00045 */
00046 class direct_resampler_conditioner_cb : public gr::block
00047 {
00048 public:
00049     ~direct_resampler_conditioner_cb() = default;
00050
00051     inline unsigned int sample_freq_in() const
00052     {
00053         return d_sample_freq_in;
00054     }
00055
00056     inline unsigned int sample_freq_out() const
00057     {
00058         return d_sample_freq_out;
00059     }
00060
00061     void forecast(int noutput_items, gr_vector_int &ninput_items_required);
00062
00063     int general_work(int noutput_items, gr_vector_int &ninput_items,
00064         gr_vector_const_void_star &input_items,
00065         gr_vector_void_star &output_items);
00066
00067 private:
00068     friend direct_resampler_conditioner_cb_sptr direct_resampler_make_conditioner_cb(
00069         double sample_freq_in,
00070         double sample_freq_out);
00071
00072     direct_resampler_conditioner_cb(
00073         double sample_freq_in,
00074         double sample_freq_out);
00075
00076     double d_sample_freq_in;
00077     double d_sample_freq_out;
00078     uint32_t d_phase;
00079     uint32_t d_lphase;
00080     uint32_t d_phase_step;
00081 };
00082
00083
00084 /** \} */
00085 /** \} */
00086 #endif // GNSS_SDR_DIRECT_RESAMPLER_CONDITIONER_CB_H

```

13.322 direct_resampler_conditioner_cc.h File Reference

Nearest neighborhood resampler with gr_complex input and gr_complex output.

```

#include "gnss_block_interface.h"
#include <gnuradio/block.h>
#include <stdint>

```

Classes

- class [direct_resampler_conditioner_cc](#)

This class implements a direct resampler conditioner for complex data.

Typedefs

- using `direct_resampler_conditioner_cc_sptr` = `gnss_shared_ptr<direct_resampler_conditioner_cc>`

Functions

- `direct_resampler_conditioner_cc_sptr` **direct_resampler_make_conditioner_cc** (double `sample_freq_in`, double `sample_freq_out`)

13.322.1 Detailed Description

Nearest neighborhood resampler with `gr_complex` input and `gr_complex` output.

Author

Luis Esteve, 2011. [luis\(at\)epsilon-formacion.com](mailto:luis(at)epsilon-formacion.com)

This block takes in a signal stream and performs direct resampling. The theory behind this block can be found in Chapter 7.5 of the following book: R. Lyons, Understanding Digital Signal Processing, 3rd ed., Pearson Education, 2010.

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Definition in file [direct_resampler_conditioner_cc.h](#).

13.323 direct_resampler_conditioner_cc.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file direct_resampler_conditioner_cc.h
00003  *
00004  * \brief Nearest neighborhood resampler with
00005  *        gr_complex input and gr_complex output
00006  * \author Luis Esteve, 2011. luis(at)epsilon-formacion.com
00007  *
00008  * This block takes in a signal stream and performs direct resampling.
00009  * The theory behind this block can be found in Chapter 7.5 of the following
00010  * book:
00011  * R. Lyons, Understanding Digital Signal Processing, 3rd ed., Pearson Education,
00012  * 2010.
00013  *
00014  * -----
00015  *
00016  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00017  * This file is part of GNSS-SDR.
00018  *
00019  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00020  * SPDX-License-Identifier: GPL-3.0-or-later
00021  *
00022  * -----
00023  */
00024
00025 #ifndef GNSS_SDR_DIRECT_RESAMPLER_CONDITIONER_CC_H
00026 #define GNSS_SDR_DIRECT_RESAMPLER_CONDITIONER_CC_H
00027
00028 #include "gnss_block_interface.h"
00029 #include <gnuradio/block.h>
00030 #include <cstdint>
00031
00032 /** \addtogroup Resampler
00033  *  \{ */
00034 /** \addtogroup Resampler_gnuradio_blocks resampler_gr_blocks
00035  *  \{ */
00036
00037
00038 class direct_resampler_conditioner_cc;
00039
00040 using direct_resampler_conditioner_cc_sptr = gnss_shared_ptr<direct_resampler_conditioner_cc>;
00041
00042 direct_resampler_conditioner_cc_sptr direct_resampler_make_conditioner_cc(
00043     double sample_freq_in,
00044     double sample_freq_out);
00045
00046 /*!
00047  * \brief This class implements a direct resampler conditioner for complex data
00048  *
00049  * Direct resampling without interpolation

```

```

00050  */
00051  class direct_resampler_conditioner_cc : public gr::block
00052  {
00053  public:
00054      ~direct_resampler_conditioner_cc() = default;
00055      inline unsigned int sample_freq_in() const
00056      {
00057          return d_sample_freq_in;
00058      }
00059      inline unsigned int sample_freq_out() const
00060      {
00061          return d_sample_freq_out;
00062      }
00063  }
00064
00065      void forecast(int noutput_items, gr_vector_int &ninput_items_required);
00066
00067      int general_work(int noutput_items, gr_vector_int &ninput_items,
00068                      gr_vector_const_void_star &input_items,
00069                      gr_vector_void_star &output_items);
00070
00071  private:
00072      friend direct_resampler_conditioner_cc_sptr direct_resampler_make_conditioner_cc(
00073          double sample_freq_in,
00074          double sample_freq_out);
00075
00076      direct_resampler_conditioner_cc(
00077          double sample_freq_in,
00078          double sample_freq_out);
00079
00080      double d_sample_freq_in; // Sampling frequency of the input signal
00081      double d_sample_freq_out; // Sampling frequency of the output signal
00082      uint32_t d_phase;
00083      uint32_t d_lphase;
00084      uint32_t d_phase_step;
00085  };
00086
00087
00088  /** \} */
00089  /** \} */
00090  #endif // GNSS_SDR_DIRECT_RESAMPLER_CONDITIONER_CC_H

```

13.324 direct_resampler_conditioner_cs.h File Reference

Nearest neighborhood resampler with `std::complex<short>` input and `std::complex<short>` output.

```

#include "gnss_block_interface.h"
#include <gnuradio/block.h>
#include <cstdint>

```

Classes

- class [direct_resampler_conditioner_cs](#)
This class implements a direct resampler conditioner for `std::complex<short>`

Typedefs

- using [direct_resampler_conditioner_cs_sptr](#) = `gnss_shared_ptr<direct_resampler_conditioner_cs>`

Functions

- `direct_resampler_conditioner_cs_sptr` **direct_resampler_make_conditioner_cs** (double sample_freq_in, double sample_freq_out)

13.324.1 Detailed Description

Nearest neighborhood resampler with `std::complex<short>` input and `std::complex<short>` output.

Author

Luis Esteve, 2011. luis(at)epsilon-formacion.com

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Definition in file [direct_resampler_conditioner_cs.h](#).

13.325 direct_resampler_conditioner_cs.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file direct_resampler_conditioner_cs.h
00003  * \brief Nearest neighborhood resampler with
00004  *        std::complex<short> input and std::complex<short> output
00005  * \author Luis Esteve, 2011. luis(at)epsilon-formacion.com
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_DIRECT_RESAMPLER_CONDITIONER_CS_H
00020 #define GNSS_SDR_DIRECT_RESAMPLER_CONDITIONER_CS_H
00021
00022 #include "gnss_block_interface.h"
00023 #include <gnuradio/block.h>
00024 #include <cstdint>
00025
00026 /** \addtogroup Resampler
00027  * \{ */
00028 /** \addtogroup Resampler_gnuradio_blocks
00029  * \{ */
00030
00031
00032 class direct_resampler_conditioner_cs;
00033
00034 using direct_resampler_conditioner_cs_sptr = gnss_shared_ptr<direct_resampler_conditioner_cs>;
00035
00036 direct_resampler_conditioner_cs_sptr direct_resampler_make_conditioner_cs(
00037     double sample_freq_in,
00038     double sample_freq_out);
00039
00040 /*!
00041 * \brief This class implements a direct resampler conditioner for std::complex<short>
00042 *
00043 * Direct resampling without interpolation
00044 */
00045 class direct_resampler_conditioner_cs : public gr::block
00046 {
00047 public:
00048     ~direct_resampler_conditioner_cs() = default;
00049
00050     inline unsigned int sample_freq_in() const
00051     {
00052         return d_sample_freq_in;
00053     }
00054
00055     inline unsigned int sample_freq_out() const
00056     {
00057         return d_sample_freq_out;
00058     }
00059
00060     void forecast(int noutput_items, gr_vector_int &ninput_items_required);
00061
00062     int general_work(int noutput_items, gr_vector_int &ninput_items,
00063                     gr_vector_const_void_star &input_items,
00064                     gr_vector_void_star &output_items);
00065
00066 private:
00067     friend direct_resampler_conditioner_cs_sptr direct_resampler_make_conditioner_cs(
00068         double sample_freq_in,
00069         double sample_freq_out);
00070
00071     direct_resampler_conditioner_cs(
00072         double sample_freq_in,

```

```

00073         double sample_freq_out);
00074
00075     double d_sample_freq_in;
00076     double d_sample_freq_out;
00077     uint32_t d_phase;
00078     uint32_t d_lphase;
00079     uint32_t d_phase_step;
00080 };
00081
00082
00083 /** \} */
00084 /** \} */
00085 #endif // GNSS_SDR_DIRECT_RESAMPLER_CONDITIONER_CS_H

```

13.326 signal_generator.h File Reference

Adapter of a class that generates synthesized GNSS signal.

```

#include "concurrent_queue.h"
#include "gnss_block_interface.h"
#include "signal_generator_c.h"
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/vector_to_stream.h>
#include <gnuradio/hier_block2.h>
#include <pmt/pmt.h>
#include <memory>
#include <string>
#include <vector>

```

Classes

- class [SignalGenerator](#)

This class generates synthesized GNSS signal.

13.326.1 Detailed Description

Adapter of a class that generates synthesized GNSS signal.

Author

Marc Molina, 2013. marc.molina.pena@gmail.com

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Definition in file [signal_generator.h](#).

13.327 signal_generator.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file signal_generator.h
00003  * \brief Adapter of a class that generates synthesized GNSS signal.
00004  * \author Marc Molina, 2013. marc.molina.pena@gmail.com
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_SIGNAL_GENERATOR_H
00020 #define GNSS_SDR_SIGNAL_GENERATOR_H

```



```

00021
00022 #include "concurrent_queue.h"
00023 #include "gnss_block_interface.h"
00024 #include "signal_generator_c.h"
00025 #include <gnuradio/blocks/file_sink.h>
00026 #include <gnuradio/blocks/vector_to_stream.h>
00027 #include <gnuradio/hier_block2.h>
00028 #include <pmt/pmt.h>
00029 #include <memory>
00030 #include <string>
00031 #include <vector>
00032
00033 class ConfigurationInterface;
00034
00035 /*!
00036  * \brief This class generates synthesized GNSS signal.
00037  *
00038  */
00039 class SignalGenerator : public GNSSBlockInterface
00040 {
00041 public:
00042     SignalGenerator(const ConfigurationInterface* configuration,
00043                     const std::string& role, unsigned int in_stream,
00044                     unsigned int out_stream, Concurrent_Queue<pmt::pmt_t>* queue);
00045
00046     ~SignalGenerator() = default;
00047
00048     inline std::string role() override
00049     {
00050         return role_;
00051     }
00052
00053     /*!
00054     * \brief Returns "GNSSSignalGenerator".
00055     */
00056     inline std::string implementation() override
00057     {
00058         return "GNSSSignalGenerator";
00059     }
00060
00061     inline size_t item_size() override
00062     {
00063         return item_size_;
00064     }
00065
00066     void connect(gr::top_block_sptr top_block) override;
00067     void disconnect(gr::top_block_sptr top_block) override;
00068     gr::basic_block_sptr get_left_block() override;
00069     gr::basic_block_sptr get_right_block() override;
00070
00071 private:
00072     gnss_shared_ptr<gr::block> gen_source_;
00073     gr::blocks::vector_to_stream::sptr vector_to_stream_;
00074     gr::blocks::file_sink::sptr file_sink_;
00075     std::string role_;
00076     std::string item_type_;
00077     std::string dump_filename_;
00078     size_t item_size_;
00079     unsigned int in_stream_;
00080     unsigned int out_stream_;
00081     bool dump_;
00082 };
00083
00084 #endif // GNSS_SDR_SIGNAL_GENERATOR_H

```

13.328 signal_generator_c.h File Reference

GNU Radio source block that generates synthesized GNSS signal.

```

#include "gnss_block_interface.h"
#include <gnuradio/block.h>
#include <random>
#include <string>
#include <vector>

```

Classes

- class [signal_generator_c](#)
This class generates synthesized GNSS signal.

Typedefs

- using [signal_generator_c_sptr](#) = gnss_shared_ptr<[signal_generator_c](#)>

Functions

- [signal_generator_c_sptr](#) [signal_make_generator_c](#) (const std::vector< std::string > &signal1, const std::vector< std::string > &system, const std::vector< unsigned int > &PRN, const std::vector< float > &CN0_dB, const std::vector< float > &doppler_Hz, const std::vector< unsigned int > &delay_chips, const std::vector< unsigned int > &delay_sec, bool data_flag, bool noise_flag, unsigned int fs_in, unsigned int vector_length, float BW_BB)

Return a shared_ptr to a new instance of gen_source.

13.328.1 Detailed Description

GNU Radio source block that generates synthesized GNSS signal.

Author

Marc Molina, 2013. marc.molina.pena@gmail.com

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 Definition in file [signal_generator_c.h](#).

13.328.2 Typedef Documentation

13.328.2.1 [signal_generator_c_sptr](#)

using [signal_generator_c_sptr](#) = gnss_shared_ptr<[signal_generator_c](#)>

Definition at line 29 of file [signal_generator_c.h](#).

13.328.3 Function Documentation

13.328.3.1 [signal_make_generator_c\(\)](#)

```
signal_generator_c_sptr signal_make_generator_c (
    const std::vector< std::string > & signal1,
    const std::vector< std::string > & system,
    const std::vector< unsigned int > & PRN,
    const std::vector< float > & CN0_dB,
    const std::vector< float > & doppler_Hz,
    const std::vector< unsigned int > & delay_chips,
    const std::vector< unsigned int > & delay_sec,
    bool data_flag,
    bool noise_flag,
    unsigned int fs_in,
    unsigned int vector_length,
    float BW_BB)
```

Return a shared_ptr to a new instance of gen_source.

To avoid accidental use of raw pointers, gen_source's constructor is private. signal_make_generator_c is the public interface for creating new instances.

13.329 [signal_generator_c.h](#)

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file signal_generator_c.h
00003  * \brief GNU Radio source block that generates synthesized GNSS signal.
00004  * \author Marc Molina, 2013. marc.molina.pena@gmail.com
00005  *
00006  * -----
```

```

00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_SIGNAL_GENERATOR_C_H
00018 #define GNSS_SDR_SIGNAL_GENERATOR_C_H
00019
00020 #include "gnss_block_interface.h"
00021 #include <gnuradio/block.h>
00022 #include <random>
00023 #include <string>
00024 #include <vector>
00025
00026
00027 class signal_generator_c;
00028
00029 using signal_generator_c_sptr = gnss_shared_ptr<signal_generator_c>;
00030
00031 /*!
00032  * \brief Return a shared_ptr to a new instance of gen_source.
00033  *
00034  * To avoid accidental use of raw pointers, gen_source's
00035  * constructor is private. signal_make_generator_c is the public
00036  * interface for creating new instances.
00037  */
00038 signal_generator_c_sptr signal_make_generator_c(
00039     const std::vector<std::string> &signall,
00040     const std::vector<std::string> &system,
00041     const std::vector<unsigned int> &PRN,
00042     const std::vector<float> &CNO_dB,
00043     const std::vector<float> &doppler_Hz,
00044     const std::vector<unsigned int> &delay_chips,
00045     const std::vector<unsigned int> &delay_sec,
00046     bool data_flag,
00047     bool noise_flag,
00048     unsigned int fs_in,
00049     unsigned int vector_length,
00050     float BW_BB);
00051
00052 /*!
00053  * \brief This class generates synthesized GNSS signal.
00054  * \ingroup block
00055  *
00056  * \sa gen_source for a version that subclasses gr_block.
00057  */
00058 class signal_generator_c : public gr::block
00059 {
00060 public:
00061     ~signal_generator_c() = default; // public destructor
00062
00063     // Where all the action really happens
00064     int general_work(int noutput_items,
00065                     gr_vector_int &ninput_items,
00066                     gr_vector_const_void_star &input_items,
00067                     gr_vector_void_star &output_items);
00068 private:
00069     friend signal_generator_c_sptr signal_make_generator_c(
00070         const std::vector<std::string> &signall,
00071         const std::vector<std::string> &system,
00072         const std::vector<unsigned int> &PRN,
00073         const std::vector<float> &CNO_dB,
00074         const std::vector<float> &doppler_Hz,
00075         const std::vector<unsigned int> &delay_chips,
00076         const std::vector<unsigned int> &delay_sec,
00077         bool data_flag,
00078         bool noise_flag,
00079         unsigned int fs_in,
00080         unsigned int vector_length,
00081         float BW_BB);
00082
00083     signal_generator_c(
00084         std::vector<std::string> signall,
00085         std::vector<std::string> system,
00086         const std::vector<unsigned int> &PRN,
00087         std::vector<float> CNO_dB,
00088         std::vector<float> doppler_Hz,
00089         std::vector<unsigned int> delay_chips,
00090         std::vector<unsigned int> delay_sec,
00091         bool data_flag,
00092         bool noise_flag,
00093

```

```

00094         unsigned int fs_in,
00095         unsigned int vector_length,
00096         float BW_BB);
00097
00098     void init();
00099
00100     void generate_codes();
00101
00102     std::random_device r;
00103     std::uniform_int_distribution<int> uniform_dist;
00104     std::normal_distribution<float> normal_dist;
00105     std::vector<std::string> signal_;
00106     std::vector<std::string> system_;
00107     std::vector<std::vector<gr_complex>> sampled_code_data_;
00108     std::vector<std::vector<gr_complex>> sampled_code_pilot_;
00109     std::vector<gr_complex> current_data_bits_;
00110     std::vector<gr_complex> complex_phase_;
00111     std::vector<float> CN0_dB_;
00112     std::vector<float> doppler_Hz_;
00113     std::vector<float> start_phase_rad_;
00114     std::vector<unsigned int> PRN_;
00115     std::vector<unsigned int> delay_chips_;
00116     std::vector<unsigned int> delay_sec_;
00117     std::vector<unsigned int> samples_per_code_;
00118     std::vector<unsigned int> num_of_codes_per_vector_;
00119     std::vector<unsigned int> data_bit_duration_ms_;
00120     std::vector<unsigned int> ms_counter_;
00121     std::vector<signed int> current_data_bit_int_;
00122     std::vector<signed int> data_modulation_;
00123     std::vector<signed int> pilot_modulation_;
00124     float BW_BB_;
00125     unsigned int work_counter_{};
00126     unsigned int fs_in_;
00127     unsigned int num_sats_;
00128     unsigned int vector_length_;
00129     bool data_flag_;
00130     bool noise_flag_;
00131 };
00132
00133 #endif // GNSS_SDR_SIGNAL_GENERATOR_C_H

```

13.330 ad936x_custom_signal_source.h File Reference

A direct IIO custom front-end gnss-sdr signal source for the AD936x AD front-end family with special FPGA custom functionalities.

```

#include "ad936x_iio_source.h"
#include "concurrent_queue.h"
#include "conjugate_cc.h"
#include "signal_source_base.h"
#include "unpack_byte_2bit_cpx_samples.h"
#include "unpack_byte_4bit_samples.h"
#include "unpack_short_byte_samples.h"
#include <gnuradio/blocks/char_to_short.h>
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/delay.h>
#include <gnuradio/blocks/interleaved_short_to_complex.h>
#include <pmt/pmt.h>
#include <cstdint>
#include <memory>
#include <stdexcept>
#include <string>
#include <vector>

```

Classes

- class [Ad936xCustomSignalSource](#)

This class instantiates the Ad936xCustom gnuradio signal source. It has support also for a customized Ad936x↔ Custom firmware and signal source to support PPS samplestamp reading.

13.330.1 Detailed Description

A direct IIO custom front-end gnss-sdr signal source for the AD936x AD front-end family with special FPGA custom functionalities.

Author

Javier Arribas, jarribas(at)cttc.es

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 Definition in file [ad936x_custom_signal_source.h](#).

13.331 ad936x_custom_signal_source.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file ad936x_custom_signal_source.h
00003  * \brief A direct IIO custom front-end gnss-sdr signal source for the AD936x AD front-end family with
00004  *        special FPGA custom functionalities.
00005  * \author Javier Arribas, jarribas(at)cttc.es
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  * -----
00014  */
00015
00016
00017 #ifndef GNSS_SDR_Ad936xCUSTOM_SIGNAL_SOURCE_H
00018 #define GNSS_SDR_Ad936xCUSTOM_SIGNAL_SOURCE_H
00019
00020 #include "ad936x_iio_source.h"
00021 #include "concurrent_queue.h"
00022 #include "conjugate_cc.h"
00023 #include "signal_source_base.h"
00024 #include "unpack_byte_2bit_cpx_samples.h"
00025 #include "unpack_byte_4bit_samples.h"
00026 #include "unpack_short_byte_samples.h"
00027 #include <gnuradio/blocks/char_to_short.h>
00028 #include <gnuradio/blocks/file_sink.h>
00029 // #include <gnuradio/blocks/interleaved_char_to_complex.h>
00030 #include <gnuradio/blocks/delay.h>
00031 #include <gnuradio/blocks/interleaved_short_to_complex.h>
00032 #include <pmt/pmt.h>
00033 #include <stdint>
00034 #include <memory>
00035 #include <stdexcept>
00036 #include <string>
00037 #include <vector>
00038
00039 /** \addtogroup Signal_Source
00040  *  \{ */
00041 /** \addtogroup Signal_Source_adapters
00042  *  \{ */
00043
00044
00045 class ConfigurationInterface;
00046
00047 /*!
00048 * \brief This class instantiates the Ad936xCUSTOM gnuradio signal source.
00049 * It has support also for a customized Ad936xCUSTOM firmware and signal source to support PPS
00050 * stamp reading.
00051 */
00051 class Ad936xCUSTOMSignalSource : public SignalSourceBase
00052 {
00053 public:
00054     Ad936xCUSTOMSignalSource(const ConfigurationInterface* configuration,
00055                             const std::string& role, unsigned int in_stream,
00056                             unsigned int out_stream, Concurrent_Queue<pmt::pmt_t>* queue);
00057
00058     ~Ad936xCUSTOMSignalSource() = default;
00059
00060     inline size_t item_size() override
00061     {
00062         return item_size_;
00063     }
00064

```

```

00065     void connect(gr::top_block_sptr top_block) override;
00066     void disconnect(gr::top_block_sptr top_block) override;
00067     gr::basic_block_sptr get_left_block() override;
00068     gr::basic_block_sptr get_right_block() override;
00069     gr::basic_block_sptr get_right_block(int RF_channel) override;
00070
00071 private:
00072     unsigned int in_stream_;
00073     unsigned int out_stream_;
00074     gr::block_sptr ad936x_iio_source;
00075     std::vector<gr::blocks::file_sink::sptr> sink_;
00076     std::vector<std::string> filename_vec_;
00077
00078     gr::blocks::delay::sptr gr_delay;
00079     std::vector<gr::blocks::char_to_short::sptr> gr_char_to_short_;
00080     std::vector<gr::blocks::interleaved_short_to_complex::sptr> gr_interleaved_short_to_complex_;
00081     // std::vector<gr::blocks::interleaved_char_to_complex::sptr> gr_interleaved_char_to_complex_;
00082     std::vector<unpack_short_byte_samples_sptr> unpack_short_byte;
00083     std::vector<unpack_byte_4bit_samples_sptr> unpack_byte_fourbits;
00084     std::vector<unpack_byte_2bit_cpx_samples_sptr> unpack_byte_twobits;
00085
00086     std::string item_type_;
00087     size_t item_size_;
00088     int64_t samples_;
00089     bool dump_;
00090     std::string dump_filename_;
00091
00092     // Front-end settings
00093     std::string pluto_uri_;
00094     std::string board_type_;
00095     long long sample_rate_;
00096     long long bandwidth_;
00097     long long freq_;
00098     long long freq_2ch;
00099     std::string rf_port_select_;
00100     std::string rf_filter;
00101     std::string gain_mode_rx0_;
00102     std::string gain_mode_rx1_;
00103     double rf_gain_rx0_;
00104     double rf_gain_rx1_;
00105     bool enable_ch0;
00106     bool enable_ch1;
00107     bool PPS_mode_;
00108     std::string fe_ip_;
00109     int fe_ctlport_;
00110     int ssize_;
00111     int bshift_;
00112     bool spattern_;
00113     bool inverted_spectrum_ch0_;
00114     bool inverted_spectrum_ch1_;
00115     double lo_attenuation_db_;
00116     bool high_side_lo_;
00117     int tx_lo_channel_;
00118     double rx0_to_rx1_delay_ns_;
00119     bool delay_enabled;
00120     bool apply_delay_on_rx0;
00121
00122     std::vector<bool> inverted_spectrum_vec;
00123     int n_channels;
00124 };
00125
00126
00127 /** \} */
00128 /** \} */
00129 #endif // GNSS_SDR_Ad936xCustom_SIGNAL_SOURCE_H

```

13.332 adrv9361_z7035_signal_source_fpga.h File Reference

Signal source for the Analog Devices ADRV9361-Z7035 evaluation board directly connected to the FPGA accelerators. This source implements only the AD9361 control. It is NOT compatible with conventional SDR acquisition and tracking blocks. Please use the fmcomms2 source if conventional SDR acquisition and tracking is selected in the configuration file.

```

#include "concurrent_queue.h"
#include "fpga_buffer_monitor.h"
#include "fpga_dynamic_bit_selection.h"
#include "fpga_switch.h"
#include "gnss_block_interface.h"
#include "signal_source_base.h"
#include <pmt/pmt.h>

```

```
#include <stdint>
#include <memory>
#include <mutex>
#include <string>
#include <thread>
```

Classes

- class [Adrv9361z7035SignalSourceFPGA](#)

13.332.1 Detailed Description

Signal source for the Analog Devices ADRV9361-Z7035 evaluation board directly connected to the FPGA accelerators. This source implements only the AD9361 control. It is NOT compatible with conventional SDR acquisition and tracking blocks. Please use the fmcomms2 source if conventional SDR acquisition and tracking is selected in the configuration file.

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 Definition in file [adrv9361_z7035_signal_source_fpga.h](#).

13.333 adrv9361_z7035_signal_source_fpga.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file adrv9361_z7035_signal_source_fpga.h
00003  * \brief Signal source for the Analog Devices ADRV9361-Z7035 evaluation board
00004  * directly connected to the FPGA accelerators.
00005  * This source implements only the AD9361 control. It is NOT compatible with
00006  * conventional SDR acquisition and tracking blocks.
00007  * Please use the fmcomms2 source if conventional SDR acquisition and tracking
00008  * is selected in the configuration file.
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_ADRV9361_Z7035_SIGNAL_SOURCE_FPGA_H
00022 #define GNSS_SDR_ADRV9361_Z7035_SIGNAL_SOURCE_FPGA_H
00023
00024 #include "concurrent_queue.h"
00025 #include "fpga_buffer_monitor.h"
00026 #include "fpga_dynamic_bit_selection.h"
00027 #include "fpga_switch.h"
00028 #include "gnss_block_interface.h"
00029 #include "signal_source_base.h"
00030 #include <pmt/pmt.h>
00031 #include <stdint>
00032 #include <memory>
00033 #include <mutex>
00034 #include <string>
00035 #include <thread>
00036
00037
00038 /** \addtogroup Signal_Source
00039  * \{ */
00040 /** \addtogroup Signal_Source_adapters
00041  * \{ */
00042
00043
00044 class ConfigurationInterface;
00045
00046 class Adrv9361z7035SignalSourceFPGA : public SignalSourceBase
00047 {
00048 public:
00049     Adrv9361z7035SignalSourceFPGA(const ConfigurationInterface *configuration,
00050     const std::string &role, unsigned int in_stream,
00051     unsigned int out_stream, Concurrent_Queue<pmt::pmt_t> *queue);
```

```

00052
00053 ~Adrv9361z7035SignalSourceFPGA();
00054
00055 inline size_t item_size() override
00056 {
00057     return item_size_;
00058 }
00059
00060 void connect(gr::top_block_sptr top_block) override;
00061 void disconnect(gr::top_block_sptr top_block) override;
00062 gr::basic_block_sptr get_left_block() override;
00063 gr::basic_block_sptr get_right_block() override;
00064
00065 private:
00066     const std::string default_dump_filename = std::string("FPGA_buffer_monitor_dump.dat");
00067     const std::string default_rf_port_select = std::string("A_BALANCED");
00068     const std::string default_gain_mode = std::string("slow_attack");
00069     const double default_tx_attenuation_db = -10.0;
00070     const double default_manual_gain_rx1 = 64.0;
00071     const double default_manual_gain_rx2 = 64.0;
00072     const uint64_t default_bandwidth = 12500000;
00073
00074     // perform dynamic bit selection every 500 ms by default
00075     const uint32_t Gain_control_period_ms = 500;
00076     // check buffer overflow and perform buffer monitoring every 1s by default
00077     const uint32_t buffer_monitor_period_ms = 1000;
00078     // buffer overflow and buffer monitoring initial delay
00079     const uint32_t buffer_monitoring_initial_delay_ms = 2000;
00080     const int32_t switch_to_real_time_mode = 2;
00081
00082     void run_dynamic_bit_selection_process();
00083     void run_buffer_monitor_process();
00084
00085     mutable std::mutex dynamic_bit_selection_mutex;
00086     mutable std::mutex buffer_monitor_mutex;
00087
00088     std::thread thread_dynamic_bit_selection;
00089     std::thread thread_buffer_monitor;
00090
00091     std::shared_ptr<Fpga_Switch> switch_fpga;
00092     std::shared_ptr<Fpga_dynamic_bit_selection> dynamic_bit_selection_fpga;
00093     std::shared_ptr<Fpga_buffer_monitor> buffer_monitor_fpga;
00094
00095     std::string gain_mode_rx1_;
00096     std::string gain_mode_rx2_;
00097     std::string rf_port_select_;
00098     std::string filter_file_;
00099     std::string filter_source_;
00100     std::string filter_filename_;
00101
00102     double rf_gain_rx1_;
00103     double rf_gain_rx2_;
00104     double scale_dds_dbfs_;
00105     double phase_dds_deg_;
00106     double tx_attenuation_db_;
00107
00108     uint64_t freq0_; // frequency of local oscillator for ADRV9361-A 0
00109     uint64_t sample_rate_;
00110     uint64_t bandwidth_;
00111     uint64_t freq_dds_tx_hz_;
00112     uint64_t freq_rf_tx_hz_;
00113     uint64_t tx_bandwidth_;
00114
00115     float Fpass_;
00116     float Fstop_;
00117     uint32_t in_stream_;
00118     uint32_t out_stream_;
00119
00120     size_t item_size_;
00121
00122     bool enable_dds_lo_;
00123     bool quadrature_;
00124     bool rf_dc_;
00125     bool bb_dc_;
00126     bool rx1_enable_;
00127     bool rx2_enable_;
00128     bool enable_dynamic_bit_selection_;
00129     bool enable_ovf_check_buffer_monitor_active_;
00130     bool dump_;
00131     bool rf_shutdown_;
00132 };
00133
00134
00135 /** \} */
00136 /** \} */
00137 #endif // GNSS_SDR_ADRV9361_Z7035_SIGNAL_SOURCE_FPGA_H

```


13.334 custom_udp_signal_source.h File Reference

Receives ip frames containing samples in UDP frame encapsulation using a high performance packet capture library (libpcap)

```
#include "concurrent_queue.h"
#include "gr_complex_ip_packet_source.h"
#include "signal_source_base.h"
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/null_sink.h>
#include <pmt/pmt.h>
#include <stdexcept>
#include <string>
#include <vector>
```

Classes

- class [CustomUDPSignalSource](#)

This class reads from UDP packets, which streams interleaved I/Q samples over a network.

13.334.1 Detailed Description

Receives ip frames containing samples in UDP frame encapsulation using a high performance packet capture library (libpcap)

13.334.1.1 autotoc_md331

Author

Javier Arribas jarribas (at) cttc.es

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Definition in file [custom_udp_signal_source.h](#).

13.335 custom_udp_signal_source.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file custom_udp_signal_source.h
00003  * \brief Receives ip frames containing samples in UDP frame encapsulation
00004  * using a high performance packet capture library (libpcap)
00005  * \author Javier Arribas jarribas (at) cttc.es
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_CUSTOM_UDP_SIGNAL_SOURCE_H
00019 #define GNSS_SDR_CUSTOM_UDP_SIGNAL_SOURCE_H
00020
00021 #include "concurrent_queue.h"
00022 #include "gr_complex_ip_packet_source.h"
00023 #include "signal_source_base.h"
00024 #include <gnuradio/blocks/file_sink.h>
00025 #include <gnuradio/blocks/null_sink.h>
00026 #include <pmt/pmt.h>
00027 #include <stdexcept>
00028 #include <string>
00029 #include <vector>
00030
00031 /** \addtogroup Signal_Source
```

```

00032 * \{ */
00033 /** \addtogroup Signal_Source_adapters
00034 * \{ */
00035
00036
00037 class ConfigurationInterface;
00038
00039 /*!
00040 * \brief This class reads from UDP packets, which streams interleaved
00041 * I/Q samples over a network.
00042 */
00043 class CustomUDPSignalSource : public SignalSourceBase
00044 {
00045 public:
00046     CustomUDPSignalSource(const ConfigurationInterface* configuration,
00047         const std::string& role, unsigned int in_stream,
00048         unsigned int out_stream, Concurrent_Queue<pmt::pmt_t>* queue);
00049
00050     ~CustomUDPSignalSource() = default;
00051
00052     inline size_t item_size() override
00053     {
00054         return item_size_;
00055     }
00056
00057     void connect(gr::top_block_sptr top_block) override;
00058     void disconnect(gr::top_block_sptr top_block) override;
00059     gr::basic_block_sptr get_left_block() override;
00060     gr::basic_block_sptr get_right_block() override;
00061     gr::basic_block_sptr get_right_block(int RF_channel) override;
00062
00063 private:
00064     Gr_Complex_Ip_Packet_Source::sptr udp_gnss_rx_source_;
00065     std::vector<gnss_shared_ptr<gr::block>> null_sinks_;
00066     std::vector<gnss_shared_ptr<gr::block>> file_sink_;
00067
00068     std::string item_type_;
00069     std::string dump_filename_;
00070
00071     size_t item_size_;
00072
00073     int RF_channels_;
00074     int channels_in_udp_;
00075     unsigned int in_stream_;
00076     unsigned int out_stream_;
00077     bool IQ_swap_;
00078     bool dump_;
00079 };
00080
00081
00082 /** \} */
00083 /** \} */
00084 #endif // GNSS_SDR_CUSTOM_UDP_SIGNAL_SOURCE_H

```

13.336 dma_signal_source_fpga.h File Reference

signal source for a DMA connected directly to FPGA accelerators. This source implements only the DMA control. It is NOT compatible with conventional SDR acquisition and tracking blocks.

```

#include "concurrent_queue.h"
#include "fpga_dma-proxy.h"
#include "fpga_dynamic_bit_selection.h"
#include "fpga_switch.h"
#include "gnss_block_interface.h"
#include "signal_source_base.h"
#include <pmt/pmt.h>
#include <stdint>
#include <memory>
#include <mutex>
#include <string>
#include <thread>

```

Classes

- class [DMASignalSourceFPGA](#)

13.336.1 Detailed Description

signal source for a DMA connected directly to FPGA accelerators. This source implements only the DMA control. It is NOT compatible with conventional SDR acquisition and tracking blocks.

Author

Marc Majoral, mmajoral(at)cttc.es

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Definition in file [dma_signal_source_fpga.h](#).

13.337 dma_signal_source_fpga.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file dma_signal_source_fpga.h
00003  * \brief signal source for a DMA connected directly to FPGA accelerators.
00004  * This source implements only the DMA control. It is NOT compatible with
00005  * conventional SDR acquisition and tracking blocks.
00006  * \author Marc Majoral, mmajoral(at)cttc.es
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_DMA_SIGNAL_SOURCE_FPGA_H
00020 #define GNSS_SDR_DMA_SIGNAL_SOURCE_FPGA_H
00021
00022 #include "concurrent_queue.h"
00023 #include "fpga_dma-proxy.h"
00024 #include "fpga_dynamic_bit_selection.h"
00025 #include "fpga_switch.h"
00026 #include "gnss_block_interface.h"
00027 #include "signal_source_base.h"
00028 #include <pmt/pmt.h>
00029 #include <cstdint>
00030 #include <memory>
00031 #include <mutex>
00032 #include <string>
00033 #include <thread>
00034
00035
00036 /** \addtogroup Signal_Source
00037  * \{ */
00038 /** \addtogroup Signal_Source_adapters
00039  * \{ */
00040
00041
00042 class ConfigurationInterface;
00043
00044 class DMASignalSourceFPGA : public SignalSourceBase
00045 {
00046 public:
00047     DMASignalSourceFPGA(const ConfigurationInterface *configuration,
00048         const std::string &role, unsigned int in_stream,
00049         unsigned int out_stream, Concurrent_Queue<pmt::pmt_t> *queue);
00050
00051     ~DMASignalSourceFPGA();
00052
00053     void start() override;
00054
00055     inline size_t item_size() override
00056     {
00057         return item_size_;
00058     }
00059
00060     void connect(gr::top_block_sptr top_block) override;
00061     void disconnect(gr::top_block_sptr top_block) override;
00062     gr::basic_block_sptr get_left_block() override;
00063     gr::basic_block_sptr get_right_block() override;
00064
00065 private:

```

```

00066     const std::string dyn_bit_sel_device_name = std::string("dynamic_bits_selector"); // Switch
dynamic bit selector device name
00067     const std::string empty_string;
00068     const uint64_t default_bandwidth = 12500000;
00069     // perform dynamic bit selection every 500 ms by default
00070     const uint32_t Gain_control_period_ms = 500;
00071     // sample block size when running in post-processing mode
00072     const int sample_block_size = 16384;
00073     const int32_t switch_to_DMA = 0;
00074
00075     void run_DMA_process(const std::string &filename0,
00076         const std::string &filename1,
00077         uint64_t &samples_to_skip,
00078         size_t &item_size,
00079         int64_t &samples,
00080         bool &repeat,
00081         uint32_t &dma_buff_offset_pos,
00082         Concurrent_Queue<pmt::pmt_t> *queue);
00083
00084     void run_dynamic_bit_selection_process();
00085
00086     std::thread thread_file_to_dma;
00087     std::thread thread_dynamic_bit_selection;
00088
00089     std::shared_ptr<Fpga_Switch> switch_fpga;
00090     std::shared_ptr<Fpga_dynamic_bit_selection> dynamic_bit_selection_fpga;
00091     std::shared_ptr<Fpga_DMA> dma_fpga;
00092
00093     std::mutex dma_mutex;
00094     std::mutex dynamic_bit_selection_mutex;
00095
00096     Concurrent_Queue<pmt::pmt_t> *queue_;
00097
00098     std::string filename0_;
00099     std::string filename1_;
00100
00101     uint64_t sample_rate_;
00102     uint64_t samples_to_skip_;
00103     int64_t samples_;
00104     uint32_t num_input_files_;
00105     uint32_t dma_buff_offset_pos_;
00106     uint32_t in_stream_;
00107     uint32_t out_stream_;
00108     size_t item_size_;
00109
00110     bool enable_DMA_;
00111     bool enable_dynamic_bit_selection_;
00112     bool repeat_;
00113 };
00114
00115
00116 /** \} */
00117 /** \} */
00118 #endif // GNSS_SDR_DMA_SIGNAL_SOURCE_FPGA_H

```

13.338 fifo_signal_source.h File Reference

Header file of the class for retrieving samples through a Unix FIFO.

```

#include "concurrent_queue.h"
#include "signal_source_base.h"
#include <pmt/pmt.h>
#include <cstdint>
#include <string>

```

Classes

- class [FifoSignalSource](#)

Class that reads a sample stream from a Unix FIFO.

13.338.1 Detailed Description

Header file of the class for retrieving samples through a Unix FIFO.

Author

Malte Lenhart, 2021. malte.lenhart(at)mailbox.org

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Definition in file [fifo_signal_source.h](#).

13.339 fifo_signal_source.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file fifo_signal_source.h
00003  *
00004  * \brief Header file of the class for retrieving samples through a Unix FIFO
00005  * \author Malte Lenhart, 2021. malte.lenhart(at)mailbox.org
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_FIFO_SIGNAL_SOURCE_H
00020 #define GNSS_SDR_FIFO_SIGNAL_SOURCE_H
00021
00022 #include "concurrent_queue.h"
00023 #include "signal_source_base.h"
00024 #include <pmt/pmt.h>
00025 #include <cstdint>
00026 #include <string>
00027
00028 /** \addtogroup Signal_Source
00029  * \{ */
00030 /** \addtogroup Signal_Source_adapters
00031  * \{ */
00032
00033 // forward declaration to avoid include in header
00034 class ConfigurationInterface;
00035
00036 /*! \brief Class that reads a sample stream from a Unix FIFO.
00037  */
00038 /*! This class supports the following properties:
00039  */
00040 /*! .filename - the path to the input file
00041  *      - may be overridden by the -signal_source or -s command-line arguments
00042  */
00043 /*! .sample_type - data type read out from the FIFO. default is short ;
00044  *      - note: not output format. that is always gr_complex
00045  */
00046 /*! .dump - whether to archive input data
00047  */
00048 /*! .dump_filename - if dumping, path to file for output
00049  */
00050 class FifoSignalSource : public SignalSourceBase
00051 {
00052 public:
00053     FifoSignalSource(const ConfigurationInterface* configuration, const std::string& role,
00054                     unsigned int in_streams, unsigned int out_streams,
00055                     Concurrent_Queue<pmt::pmt_t>* queue);
00056
00057     ~FifoSignalSource() = default;
00058
00059     /*! override methods from GNSSBlockInterface
00060     void connect(gr::top_block_sptr top_block) override;
00061     void disconnect(gr::top_block_sptr top_block) override;
00062     size_t item_size() override;
00063     gr::basic_block_sptr get_left_block() override;
00064     gr::basic_block_sptr get_right_block() override;
00065
00066 protected:
00067 private:
00068     /*! output size - always gr_complex
00069     const size_t item_size_;
00070     /*! internal fifo_reader_ class acts as signal source
00071     const gnss_shared_ptr<gr::block> fifo_reader_;
00072

```

```

00073     gnss_shared_ptr<gr::block> file_sink_;
00074     const bool dump_;
00075     const std::string dump_filename_;
00076 };
00077
00078 /** \} */
00079 /** \} */
00080 #endif // GNSS_SDR_FIFO_SIGNAL_SOURCE_H

```

13.340 file_signal_source.h File Reference

Interface of a class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

```

#include "file_source_base.h"
#include <string>

```

Classes

- class [FileSignalSource](#)

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

13.340.1 Detailed Description

Interface of a class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com

This class represents a file signal source. Internally it uses a GNU Radio's `gr_file_source` as a connector to the data.

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Definition in file [file_signal_source.h](#).

13.341 file_signal_source.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file file_signal_source.h
00003  * \brief Interface of a class that reads signals samples from a file
00004  * and adapts it to a SignalSourceInterface
00005  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00006  *
00007  * This class represents a file signal source. Internally it uses a GNU Radio's
00008  * gr_file_source as a connector to the data.
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_FILE_SIGNAL_SOURCE_H
00022 #define GNSS_SDR_FILE_SIGNAL_SOURCE_H
00023
00024 #include "file_source_base.h"
00025 #include <string>
00026
00027 /** \addtogroup Signal_Source Signal Source
00028  * Classes for Signal Source management.
00029  * \{ */
00030 /** \addtogroup Signal_Source_adapters signal_source_adapters
00031  * Classes that wrap GNU Radio signal sources with a GNSSBlockInterface
00032  * \{ */
00033
00034

```

```

00035 class ConfigurationInterface;
00036
00037 /*!
00038  * \brief Class that reads signals samples from a file
00039  * and adapts it to a SignalSourceInterface
00040  */
00041 class FileSignalSource : public FileSourceBase
00042 {
00043 public:
00044     FileSignalSource(ConfigurationInterface const* configuration, std::string const& role,
00045                     unsigned int in_streams, unsigned int out_streams,
00046                     Concurrent_Queue<pmt::pmt_t>* queue);
00047
00048     ~FileSignalSource() = default;
00049
00050 private:
00051 };
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_FILE_SIGNAL_SOURCE_H

```

13.342 file_source_base.h File Reference

Header file of the base class to file-oriented signal_source GNSS blocks.

```

#include "concurrent_queue.h"
#include "sensor_data/sensor_data_source.h"
#include "signal_source_base.h"
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/file_source.h>
#include <gnuradio/blocks/throttle.h>
#include <pmt/pmt.h>
#include <cstdint>
#include <string>
#include <tuple>

```

Classes

- class [FileSourceBase](#)
Base class to file-oriented [SignalSourceBase](#) GNSS blocks.

13.342.1 Detailed Description

Header file of the base class to file-oriented signal_source GNSS blocks.

Author

Jim Melton, 2021. [jim.melton\(at\)sncorp.com](mailto:jim.melton(at)sncorp.com)

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 Definition in file [file_source_base.h](#).

13.343 file_source_base.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file file_source_base.h
00003  * \brief Header file of the base class to file-oriented signal_source GNSS blocks.
00004  * \author Jim Melton, 2021. jim.melton\(at\)sncorp.com
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *

```

```

00012  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_FILE_SOURCE_BASE_H
00019 #define GNSS_SDR_FILE_SOURCE_BASE_H
00020
00021 #include "concurrent_queue.h"
00022 #include "sensor_data/sensor_data_source.h"
00023 #include "signal_source_base.h"
00024 #include <gnuradio/blocks/file_sink.h> // for dump
00025 #include <gnuradio/blocks/file_source.h>
00026 #include <gnuradio/blocks/throttle.h>
00027 #include <pmt/pmt.h>
00028 #include <cstring>
00029 #include <string>
00030 #include <tuple>
00031
00032
00033 /** \addtogroup Signal_Source
00034  * \{ */
00035 /** \addtogroup Signal_Source_adapters
00036  * \{ */
00037
00038 class ConfigurationInterface;
00039
00040
00041 /// \brief Base class to file-oriented SignalSourceBase GNSS blocks.
00042 ///
00043 /// This class supports the following properties:
00044 ///
00045 /// .filename - the path to the input file
00046 ///           - may be overridden by the -signal_source or -s command-line arguments
00047 ///
00048 /// .samples - number of samples to process (default 0)
00049 ///           - if not specified or 0, read the entire file; otherwise stop after that many samples
00050 ///
00051 /// .sampling_frequency - the frequency of the sampled data (samples/second)
00052 ///
00053 /// .item_type - data type of the samples (default "short")
00054 ///
00055 /// .header_size - the size of a prefixed header to skip in "samples" (default 0)
00056 ///
00057 /// .seconds_to_skip - number of seconds of lead-in data to skip over (default 0)
00058 ///
00059 /// .enable_throttle_control - whether to stop reading if the upstream buffer is full (default
00060 ///                             false)
00061 ///
00062 /// .repeat - whether to rewind and continue at end of file (default false)
00063 /// (probably abstracted to the base class)
00064 ///
00065 /// .dump - whether to archive input data
00066 ///
00067 /// .dump_filename - if dumping, path to file for output
00068 class FileSourceBase : public SignalSourceBase
00069 {
00070 public:
00071     // Virtual overrides
00072     void connect(gr::top_block_sptr top_block) override;
00073     void disconnect(gr::top_block_sptr top_block) override;
00074     gr::basic_block_sptr get_left_block() override;
00075     gr::basic_block_sptr get_right_block() override;
00076
00077     /// The file to read
00078     std::string filename() const;
00079
00080     /// The item type
00081     std::string item_type() const;
00082
00083     /// The configured size of each item
00084     size_t item_size() override;
00085     virtual size_t item_size() const; // what the interface **should** have declared
00086
00087     /// Whether to repeat reading after end-of-file
00088     bool repeat() const;
00089
00090     /// The sampling frequency of the source file
00091     int64_t sampling_frequency() const;
00092
00093     /// The number of samples in the file
00094     uint64_t samples() const;
00095
00096 protected:
00097     /// \brief Constructor

```



```

00098     ///
00099     /// Subclasses may want to assert default item types that are appropriate to the specific file
00100     /// type supported. Rather than require the item type to be specified in the config file, allow
00101     /// sub-classes to impose their will
00102     FileSourceBase(ConfigurationInterface const& configuration, std::string const& role, std::string
impl,
00103         Concurrent_Queue<pmt::pmt_t>* queue,
00104         std::string default_item_type = "short");
00105
00106     /// Perform post-construction initialization
00107     void init();
00108
00109     /// Compute the item size, from the item_type(). Subclasses may constrain types that don't make
00110     /// sense. The return of this method is a tuple of item_size and is_complex
00111     virtual std::tuple<size_t, bool> itemTypeToSize();
00112
00113     /// The number of (possibly unpacked) samples in a (raw) file sample (default=1)
00114     virtual double packetsPerSample() const;
00115
00116     /// Compute the number of samples to skip
00117     virtual uint64_t samplesToSkip() const;
00118
00119     /// Compute the number of samples in the file
00120     uint64_t computeSamplesInFile() const;
00121
00122     /// Abstracted front-end source. Sub-classes may override if they create specialized chains to
00123     /// decode source files into a usable format
00124     virtual gnss_shared_ptr<gr::block> source() const;
00125
00126     /// For complex source chains, the size of the file item may not be the same as the size of the
00127     /// "source" (decoded) item. This method allows subclasses to handle these differences
00128     virtual size_t source_item_size() const;
00129     bool is_complex() const;
00130
00131     // Generic access to created objects
00132     gnss_shared_ptr<gr::block> file_source() const;
00133     gnss_shared_ptr<gr::block> valve() const;
00134     gnss_shared_ptr<gr::block> throttle() const;
00135     gnss_shared_ptr<gr::block> sink() const;
00136     SensorDataSource::sptr sensor_data_source() const;
00137
00138     // The methods create the various blocks, if enabled, and return access to them. The created
00139     // object is also held in this class
00140     gr::blocks::file_source::sptr create_file_source();
00141     gr::blocks::throttle::sptr create_throttle();
00142     gnss_shared_ptr<gr::block> create_valve();
00143     gr::blocks::file_sink::sptr create_sink();
00144     SensorDataSource::sptr create_sensor_data_source();
00145
00146     // Subclass hooks to augment created objects, as required
00147     virtual void create_file_source_hook();
00148     virtual void create_throttle_hook();
00149     virtual void create_valve_hook();
00150     virtual void create_sink_hook();
00151
00152     // Subclass hooks for connection/disconnection
00153     virtual void pre_connect_hook(gr::top_block_sptr top_block);
00154     virtual void post_connect_hook(gr::top_block_sptr top_block);
00155     virtual void pre_disconnect_hook(gr::top_block_sptr top_block);
00156     virtual void post_disconnect_hook(gr::top_block_sptr top_block);
00157
00158 private:
00159     gr::blocks::file_source::sptr file_source_;
00160     gr::blocks::throttle::sptr throttle_;
00161     gr::blocks::file_sink::sptr sink_;
00162     SensorDataSource::sptr sensor_data_source_;
00163
00164     // The valve allows only the configured number of samples through, then it closes.
00165
00166     // The framework passes the queue as a naked pointer, rather than a shared pointer, so this
00167     // class has two choices: construct the valve in the ctor, or hold onto the pointer, possibly
00168     // beyond its lifetime. Fortunately, the queue is only used to create the valve, so the
00169     // likelihood of holding a stale pointer is mitigated
00170     gnss_shared_ptr<gr::block> valve_;
00171     Concurrent_Queue<pmt::pmt_t>* queue_;
00172
00173     std::string role_;
00174     std::string filename_;
00175     std::string dump_filename_;
00176     std::string item_type_;
00177     size_t item_size_;
00178     size_t header_size_; // length (in samples) of the header (if any)
00179     uint64_t samples_;
00180     int64_t sampling_frequency_; // why is this signed
00181     double minimum_tail_s_;
00182     double seconds_to_skip_;
00183     bool is_complex_; // a misnomer; if I/Q are interleaved as integer values

```

```

00184     bool repeat_;
00185     bool enable_throttle_control_;
00186     bool dump_;
00187
00188     // Configuration for Extra Data source
00189     SensorDataSourceConfiguration sensor_data_source_configuration_;
00190 };
00191
00192 /** @} */
00193 /** @} */
00194 #endif // GNSS_SDR_FILE_SOURCE_BASE_H

```

13.344 file_timestamp_signal_source.h File Reference

This class reads samples stored in a file and generate stream tags with its timestamp information stored in separated file.

```

#include "configuration_interface.h"
#include "file_source_base.h"
#include "gnss_sdr_timestamp.h"
#include <string>

```

Classes

- class [FileTimestampSignalSource](#)

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

13.344.1 Detailed Description

This class reads samples stored in a file and generate stream tags with its timestamp information stored in separated file.

Author

Javier Arribas, jarribas(at)cttc.es

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Definition in file [file_timestamp_signal_source.h](#).

13.345 file_timestamp_signal_source.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file file_timestamp_signal_source.h
00003  * \brief This class reads samples stored in a file and generate stream tags
00004  * with its timestamp information stored in separated file
00005  * \author Javier Arribas, jarribas(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_FILE_TIMESTAMP_SIGNAL_SOURCE_H
00020 #define GNSS_SDR_FILE_TIMESTAMP_SIGNAL_SOURCE_H
00021
00022 #include "configuration_interface.h"
00023 #include "file_source_base.h"
00024 #include "gnss_sdr_timestamp.h"
00025 #include <string>
00026
00027 /** \addtogroup Signal_Source
00028  * \{ */

```

```

00029 /** \addtogroup Signal_Source_adapters
00030 * \{ */
00031
00032
00033 /**
00034 * \brief Class that reads signals samples from a file
00035 * and adapts it to a SignalSourceInterface
00036 */
00037 class FileTimestampSignalSource : public FileSourceBase
00038 {
00039 public:
00040     FileTimestampSignalSource(const ConfigurationInterface* configuration, const std::string& role,
00041         unsigned int in_streams, unsigned int out_streams,
00042         Concurrent_Queue<pmt::pmt_t*> queue);
00043
00044     ~FileTimestampSignalSource() = default;
00045
00046 protected:
00047     // std::tuple<size_t, bool> itemTypeToSize() override;
00048     // double packetsPerSample() const override;
00049     gnss_shared_ptr<gr::block> source() const override;
00050     void create_file_source_hook() override;
00051     void pre_connect_hook(gr::top_block_sptr top_block) override;
00052     void pre_disconnect_hook(gr::top_block_sptr top_block) override;
00053
00054 private:
00055     gnss_shared_ptr<Gnss_Sdr_Timestamp> timestamp_block_;
00056     std::string timestamp_file_;
00057     double timestamp_clock_offset_ms_;
00058 };
00059
00060
00061 /** \} */
00062 /** \} */
00063 #endif // GNSS_SDR_FILE_TIMESTAMP_SIGNAL_SOURCE_H

```

13.346 flexiband_signal_source.h File Reference

Signal Source adapter for the Teleorbit Flexiband front-end device. This adapter requires a Flexiband GNU Radio driver installed (not included with GNSS-SDR)

```

#include "concurrent_queue.h"
#include "signal_source_base.h"
#include <gnuradio/blocks/char_to_float.h>
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/float_to_complex.h>
#include <gnuradio/blocks/null_sink.h>
#include <gnuradio/hier_block2.h>
#include <pmt/pmt.h>
#include <memory>
#include <string>
#include <vector>

```

Classes

- class [FlexibandSignalSource](#)

This class configures and reads samples from Teleorbit Flexiband front-end. This software requires a Flexiband GNU Radio driver installed (not included with GNSS-SDR).

13.346.1 Detailed Description

Signal Source adapter for the Teleorbit Flexiband front-end device. This adapter requires a Flexiband GNU Radio driver installed (not included with GNSS-SDR)

Author

Javier Arribas, jarribas(at)cttc.es

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 Definition in file [flexiband_signal_source.h](#).

13.347 flexiband_signal_source.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file flexiband_signal_source.h
00003  * \brief signal Source adapter for the Teleorbit Flexiband front-end device.
00004  * This adapter requires a Flexiband GNU Radio Driver
00005  * installed (not included with GNSS-SDR)
00006  * \author Javier Arribas, jarribas(at)cttc.es
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019
00020 #ifndef GNSS_SDR_FLEXIBAND_SIGNAL_SOURCE_H
00021 #define GNSS_SDR_FLEXIBAND_SIGNAL_SOURCE_H
00022
00023 #include "concurrent_queue.h"
00024 #include "signal_source_base.h"
00025 #include <gnuradio/blocks/char_to_float.h>
00026 #include <gnuradio/blocks/file_sink.h>
00027 #include <gnuradio/blocks/float_to_complex.h>
00028 #include <gnuradio/blocks/null_sink.h>
00029 #include <gnuradio/hier_block2.h>
00030 #include <pmt/pmt.h>
00031 #include <memory>
00032 #include <string>
00033 #include <vector>
00034
00035
00036 /** \addtogroup Signal_Source
00037  * \{ */
00038 /** \addtogroup Signal_Source_adapters
00039  * \{ */
00040
00041
00042 class ConfigurationInterface;
00043
00044 /*!
00045 * \brief This class configures and reads samples from Teleorbit Flexiband front-end.
00046 * This software requires a Flexiband GNU Radio driver installed (not included with GNSS-SDR).
00047 */
00048 class FlexibandSignalSource : public SignalSourceBase
00049 {
00050 public:
00051     FlexibandSignalSource(const ConfigurationInterface* configuration,
00052                          const std::string& role, unsigned int in_stream,
00053                          unsigned int out_stream, Concurrent_Queue<pmt::pmt_t>* queue);
00054
00055     ~FlexibandSignalSource() = default;
00056
00057     inline size_t item_size() override
00058     {
00059         return item_size_;
00060     }
00061
00062     void connect(gr::top_block_sptr top_block) override;
00063     void disconnect(gr::top_block_sptr top_block) override;
00064     gr::basic_block_sptr get_left_block() override;
00065     gr::basic_block_sptr get_right_block() override;
00066     gr::basic_block_sptr get_right_block(int RF_channel) override;
00067
00068 private:
00069     gnss_shared_ptr<gr::block> flexiband_source_;
00070
00071     std::vector<gnss_shared_ptr<gr::block>> char_to_float;
00072     std::vector<gnss_shared_ptr<gr::block>> float_to_complex_;
00073     std::vector<gr::blocks::null_sink::sptr> null_sinks_;
00074
00075     std::string item_type_;
00076     std::string firmware_filename_;
00077     std::string signal_file;
00078
00079     size_t item_size_;
00080     unsigned int in_stream;
00081     unsigned int out_stream;
00082
00083     int gain1;

```

```

00084     int gain2_;
00085     int gain3_;
00086     int usb_packet_buffer_size_;
00087     int n_channels_;
00088     int sel_ch_;
00089
00090     bool AGC_;
00091     bool flag_read_file;
00092 };
00093
00094
00095 /** \} */
00096 /** \} */
00097 #endif // GNSS_SDR_FLEXIBAND_SIGNAL_SOURCE_H

```

13.348 fmcomms2_signal_source.h File Reference

Interface to use SDR hardware based in FCOMMS2 driver from analog devices, for example FCOMMS4 and ADALM-PLUTO (PlutoSdr)

```

#include "signal_source_base.h"
#include <gnuradio/blocks/file_sink.h>
#include <iio/fmcomms2_source.h>
#include "concurrent_queue.h"
#include <pmt/pmt.h>
#include <stdint>
#include <string>

```

Classes

- class [Fmcomms2SignalSource](#)

13.348.1 Detailed Description

Interface to use SDR hardware based in FCOMMS2 driver from analog devices, for example FCOMMS4 and ADALM-PLUTO (PlutoSdr)

Author

Rodrigo Muñoz, 2017. rmunozl@inacap.cl, rodrigo.munoz@proteinlab.cl

13.348.1.1 This class represent a fmcomms2 signal source. It use the gr_iio block

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Definition in file [fmcomms2_signal_source.h](#).

13.349 fmcomms2_signal_source.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file fmcomms2_signal_source.h
00003  * \brief Interface to use SDR hardware based in FCOMMS2 driver from analog
00004  * devices, for example FCOMMS4 and ADALM-PLUTO (PlutoSdr)
00005  * \author Rodrigo Muñoz, 2017. rmunozl@inacap.cl, rodrigo.munoz@proteinlab.cl
00006  *
00007  *
00008  * This class represent a fmcomms2 signal source. It use the gr_iio block
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019

```

```

00020 #ifndef GNSS_SDR_FMCOMMS2_SIGNAL_SOURCE_H
00021 #define GNSS_SDR_FMCOMMS2_SIGNAL_SOURCE_H
00022
00023 #include "signal_source_base.h"
00024 #include <gnuradio/blocks/file_sink.h>
00025 #if GRIIO_INCLUDE_HAS_GNURADIO
00026 #include <gnuradio/iio/fmcomms2_source.h>
00027 #else
00028 #include <iio/fmcomms2_source.h>
00029 #endif
00030 #include "concurrent_queue.h"
00031 #include <pmt/pmt.h>
00032 #include <cstdint>
00033 #include <string>
00034
00035
00036 /** \addtogroup Signal_Source
00037  * \{ */
00038 /** \addtogroup Signal_Source_adapters
00039  * \{ */
00040
00041
00042 class ConfigurationInterface;
00043
00044 class Fmcomms2SignalSource : public SignalSourceBase
00045 {
00046 public:
00047     Fmcomms2SignalSource(const ConfigurationInterface* configuration,
00048         const std::string& role, unsigned int in_stream,
00049         unsigned int out_stream, Concurrent_Queue<pmt::pmt_t>* queue);
00050
00051     ~Fmcomms2SignalSource();
00052
00053     inline size_t item_size() override
00054     {
00055         return item_size_;
00056     }
00057
00058     void connect(gr::top_block_sptr top_block) override;
00059     void disconnect(gr::top_block_sptr top_block) override;
00060     gr::basic_block_sptr get_left_block() override;
00061     gr::basic_block_sptr get_right_block() override;
00062
00063 private:
00064     const std::string default_gain_mode = std::string("slow_attack");
00065     const double default_tx_attenuation_db = -10.0;
00066
00067     #if GNURADIO_API_IIO
00068     #if GR_IIO_TEMPLATIZED_API
00069         gr::iio::fmcomms2_source<gr_complex>::sptr fmcomms2_source_f32c_;
00070     #else
00071         gr::iio::fmcomms2_source::sptr fmcomms2_source_f32c_;
00072     #endif
00073     #else
00074         gr::iio::fmcomms2_source_f32c::sptr fmcomms2_source_f32c_;
00075     #endif
00076     gnss_shared_ptr<gr::block> valve_;
00077     gr::blocks::file_sink::sptr file_sink_;
00078
00079     std::string item_type_;
00080     std::string dump_filename_;
00081
00082     // Front-end settings
00083     std::string uri_; // device direction
00084     std::string gain_mode_rx1_;
00085     std::string gain_mode_rx2_;
00086     std::string rf_port_select_;
00087     std::string filter_file_;
00088     std::string filter_source_;
00089     std::string filter_filename_;
00090
00091     int64_t samples_;
00092     size_t item_size_;
00093
00094     double rf_gain_rx1_;
00095     double rf_gain_rx2_;
00096     uint64_t freq_; // frequency of local oscillator
00097     uint64_t sample_rate_;
00098     uint64_t bandwidth_;
00099     uint64_t buffer_size_; // reception buffer
00100     float Fpass_;
00101     float Fstop_;
00102     unsigned int in_stream_;
00103     unsigned int out_stream_;
00104     int RF_channels_;
00105
00106     // DDS configuration for LO generation for external mixer

```

```

00107     double scale_dds_dbfs_;
00108     double phase_dds_deg_;
00109     double tx_attenuation_db_;
00110     uint64_t freq_dds_tx_hz_;
00111     uint64_t freq_rf_tx_hz_;
00112     uint64_t tx_bandwidth_;
00113     bool enable_dds_lo_;
00114
00115     bool rx1_en_;
00116     bool rx2_en_;
00117     bool quadrature_;
00118     bool rf_dc_;
00119     bool bb_dc_;
00120     bool filter_auto_;
00121     bool rf_shutdown_;
00122     bool dump_;
00123 };
00124
00125
00126 /** \} */
00127 /** \} */
00128 #endif // GNSS_SDR_FCOMMS2_SIGNAL_SOURCE_H

```

13.350 fmcomms5_signal_source_fpga.h File Reference

Signal source for the Analog Devices FCOMMS5 directly connected to the FPGA accelerators. This source implements only the AD9361 control. It is NOT compatible with conventional SDR acquisition and tracking blocks. Please use the fmcomms2 source if conventional SDR acquisition and tracking is selected in the configuration file.

```

#include "concurrent_queue.h"
#include "fpga_buffer_monitor.h"
#include "fpga_dynamic_bit_selection.h"
#include "fpga_switch.h"
#include "gnss_block_interface.h"
#include "signal_source_base.h"
#include <pmt/pmt.h>
#include <cstdint>
#include <memory>
#include <mutex>
#include <string>
#include <thread>

```

Classes

- class [Fmcomms5SignalSourceFPGA](#)

13.350.1 Detailed Description

Signal source for the Analog Devices FCOMMS5 directly connected to the FPGA accelerators. This source implements only the AD9361 control. It is NOT compatible with conventional SDR acquisition and tracking blocks. Please use the fmcomms2 source if conventional SDR acquisition and tracking is selected in the configuration file. GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [fmcomms5_signal_source_fpga.h](#).

13.351 fmcomms5_signal_source_fpga.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file fmcomms5_signal_source_fpga.h
00003 * \brief Signal source for the Analog Devices FCOMMS5 directly connected
00004 * to the FPGA accelerators.
00005 * This source implements only the AD9361 control. It is NOT compatible with
00006 * conventional SDR acquisition and tracking blocks.
00007 * Please use the fmcomms2 source if conventional SDR acquisition and tracking
00008 * is selected in the configuration file.
00009 *

```

```

00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_FCOMMS5_SIGNAL_SOURCE_FPGA_H
00022 #define GNSS_SDR_FCOMMS5_SIGNAL_SOURCE_FPGA_H
00023
00024 #include "concurrent_queue.h"
00025 #include "fpga_buffer_monitor.h"
00026 #include "fpga_dynamic_bit_selection.h"
00027 #include "fpga_switch.h"
00028 #include "gnss_block_interface.h"
00029 #include "signal_source_base.h"
00030 #include <pmt/pmt.h>
00031 #include <stdint>
00032 #include <memory>
00033 #include <mutex>
00034 #include <string>
00035 #include <thread>
00036
00037
00038 /** \addtogroup Signal_Source
00039  * \{ */
00040 /** \addtogroup Signal_Source_adapters
00041  * \{ */
00042
00043
00044 class ConfigurationInterface;
00045
00046 class Fmcomms5SignalSourceFPGA : public SignalSourceBase
00047 {
00048 public:
00049     Fmcomms5SignalSourceFPGA(const ConfigurationInterface *configuration,
00050                             const std::string &role, unsigned int in_stream,
00051                             unsigned int out_stream, Concurrent_Queue<pmt::pmt_t> *queue);
00052
00053     ~Fmcomms5SignalSourceFPGA();
00054
00055     inline size_t item_size() override
00056     {
00057         return item_size_;
00058     }
00059
00060     void connect(gr::top_block_sptr top_block) override;
00061     void disconnect(gr::top_block_sptr top_block) override;
00062     gr::basic_block_sptr get_left_block() override;
00063     gr::basic_block_sptr get_right_block() override;
00064
00065 private:
00066     const std::string default_dump_filename = std::string("FPGA_buffer_monitor_dump.dat");
00067     const std::string default_rf_port_select = std::string("A_BALANCED");
00068     const std::string default_gain_mode = std::string("slow_attack");
00069     const double default_manual_gain_rx1 = 64.0;
00070     const double default_manual_gain_rx2 = 64.0;
00071     const uint64_t default_bandwidth = 12500000;
00072
00073     // perform dynamic bit selection every 500 ms by default
00074     const uint32_t Gain_control_period_ms = 500;
00075     // check buffer overflow and perform buffer monitoring every 1s by default
00076     const uint32_t buffer_monitor_period_ms = 1000;
00077     // buffer overflow and buffer monitoring initial delay
00078     const uint32_t buffer_monitoring_initial_delay_ms = 2000;
00079     const int32_t switch_to_real_time_mode = 2;
00080
00081     void run_dynamic_bit_selection_process();
00082     void run_buffer_monitor_process();
00083
00084     mutable std::mutex dynamic_bit_selection_mutex;
00085     mutable std::mutex buffer_monitor_mutex;
00086
00087     std::thread thread_dynamic_bit_selection;
00088     std::thread thread_buffer_monitor;
00089
00090     std::shared_ptr<Fpga_Switch> switch_fpga;
00091     std::shared_ptr<Fpga_dynamic_bit_selection> dynamic_bit_selection_fpga;
00092     std::shared_ptr<Fpga_buffer_monitor> buffer_monitor_fpga;
00093
00094     std::string gain_mode_rx1_;
00095     std::string gain_mode_rx2_;
00096     std::string rf_port_select_;

```



```

00097     std::string filter_file_;
00098     std::string filter_source_;
00099     std::string filter_filename_;
00100
00101     double rf_gain_rx1_;
00102     double rf_gain_rx2_;
00103
00104     uint64_t freq0_; // frequency of local oscillator for ADRV9361-A
00105     uint64_t freq1_; // frequency of local oscillator for ADRV9361-B
00106     uint64_t sample_rate_;
00107     uint64_t bandwidth_;
00108
00109     float Fpass_;
00110     float Fstop_;
00111     uint32_t in_stream_;
00112     uint32_t out_stream_;
00113
00114     size_t item_size_;
00115
00116     bool quadrature_;
00117     bool rf_dc_;
00118     bool bb_dc_;
00119     bool rx1_enable_;
00120     bool rx2_enable_;
00121     bool enable_dynamic_bit_selection_;
00122     bool enable_ovf_check_buffer_monitor_active_;
00123     bool dump_;
00124     bool rf_shutdown_;
00125 };
00126
00127
00128 /** @} */
00129 /** @} */
00130 #endif // GNSS_SDR_FCOMMS5_SIGNAL_SOURCE_FPGA_H

```

13.352 four_bit_cpx_file_signal_source.h File Reference

Interface of a class that reads signals samples from a 2 bit complex sampler front-end file and adapts it to a [SignalSourceInterface](#).

```

#include "file_source_base.h"
#include "gnss_sdr_timestamp.h"
#include "unpack_byte_4bit_samples.h"
#include <gnuradio/blocks/interleaved_short_to_complex.h>
#include <cstring>
#include <string>
#include <tuple>

```

Classes

- class [FourBitCpxFileSignalSource](#)

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

13.352.1 Detailed Description

Interface of a class that reads signals samples from a 2 bit complex sampler front-end file and adapts it to a [SignalSourceInterface](#).

Author

Javier Arribas, 2015 jarribas(at)cttc.es

This class represents a file signal source.

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Definition in file [four_bit_cpx_file_signal_source.h](#).

13.353 four_bit_cpx_file_signal_source.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file four_bit_cpx_file_signal_source.h
00003  * \brief Interface of a class that reads signals samples from a 2 bit complex sampler front-end file
00004  * and adapts it to a SignalSourceInterface.
00005  * \author Javier Arribas, 2015 jarribas(at)cttc.es
00006  *
00007  * This class represents a file signal source.
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_FOUR_BIT_CPX_FILE_SIGNAL_SOURCE_H
00021 #define GNSS_SDR_FOUR_BIT_CPX_FILE_SIGNAL_SOURCE_H
00022
00023 #include "file_source_base.h"
00024 #include "gnss_sdr_timestamp.h"
00025 #include "unpack_byte_4bit_samples.h"
00026 #include <gnuradio/blocks/interleaved_short_to_complex.h>
00027 #include <csddef>
00028 #include <string>
00029 #include <tuple>
00030
00031 /** \addtogroup Signal_Source
00032  * \{ */
00033 /** \addtogroup Signal_Source_adapters
00034  * \{ */
00035
00036
00037 class ConfigurationInterface;
00038
00039 /*!
00040 * \brief Class that reads signals samples from a file
00041 * and adapts it to a SignalSourceInterface
00042 */
00043 class FourBitCpxFileSignalSource : public FileSourceBase
00044 {
00045 public:
00046     FourBitCpxFileSignalSource(const ConfigurationInterface* configuration,
00047                               const std::string& role,
00048                               unsigned int in_streams,
00049                               unsigned int out_streams,
00050                               Concurrent_Queue<pmt::pmt_t>* queue);
00051
00052     ~FourBitCpxFileSignalSource() = default;
00053
00054 protected:
00055     std::tuple<size_t, bool> itemTypeToSize() override;
00056     double packetsPerSample() const override;
00057     gnss_shared_ptr<gr::block> source() const override;
00058     void create_file_source_hook() override;
00059     void pre_connect_hook(gr::top_block_sptr top_block) override;
00060     void pre_disconnect_hook(gr::top_block_sptr top_block) override;
00061
00062 private:
00063     unpack_byte_4bit_samples_sptr unpack_byte_;
00064     gr::blocks::interleaved_short_to_complex::sptr inter_shorts_to_cpx_;
00065     gnss_shared_ptr<Gnss_Sdr_Timestamp> timestamp_block_;
00066     std::string sample_type_;
00067     std::string timestamp_file_;
00068     double timestamp_clock_offset_ms_;
00069     bool reverse_interleaving_;
00070 };
00071
00072
00073 /** \} */
00074 /** \} */
00075 #endif // GNSS_SDR_FOUR_BIT_CPX_FILE_SIGNAL_SOURCE_H

```

13.354 gen_signal_source.h File Reference

It wraps blocks that generates synthesized GNSS signal and filters it.

```

#include "concurrent_queue.h"
#include "gnss_block_interface.h"
#include "signal_source_interface.h"

```

```
#include <pmt/pmt.h>
#include <memory>
#include <string>
```

Classes

- class [GenSignalSource](#)

This class wraps blocks that generates synthesized GNSS signal and filters the signal.

13.354.1 Detailed Description

It wraps blocks that generates synthesized GNSS signal and filters it.

Author

Marc Molina, 2013. marc.molina.pena@gmail.com

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 Definition in file [gen_signal_source.h](#).

13.355 gen_signal_source.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gen_signal_source.h
00003  * \brief It wraps blocks that generates synthesized GNSS signal and filters
00004  * it.
00005  * \author Marc Molina, 2013. marc.molina.pena@gmail.com
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GEN_SIGNAL_SOURCE_H
00020 #define GNSS_SDR_GEN_SIGNAL_SOURCE_H
00021
00022
00023 #include "concurrent_queue.h"
00024 #include "gnss_block_interface.h"
00025 #include "signal_source_interface.h"
00026 #include <pmt/pmt.h>
00027 #include <memory>
00028 #include <string>
00029
00030
00031 /** \addtogroup Signal_Source
00032  * \{ */
00033 /** \addtogroup Signal_Source_adapters
00034  * \{ */
00035
00036
00037 /*!
00038  * \brief This class wraps blocks that generates synthesized GNSS signal and
00039  * filters the signal.
00040  */
00041 class GenSignalSource : public SignalSourceInterface
00042 {
00043 public:
00044     /** Constructor
00045     GenSignalSource(std::shared_ptr<GNSSBlockInterface> signal_generator,
00046                     std::shared_ptr<GNSSBlockInterface> filter,
00047                     std::string role, Concurrent_Queue<pmt::pmt_t> *queue);
00048
00049     void connect(gr::top_block_sptr top_block) override;
00050     void disconnect(gr::top_block_sptr top_block) override;
00051     gr::basic_block_sptr get_left_block() override;
```

```

00051     gr::basic_block_sptr get_right_block() override;
00052
00053     inline std::string role() override { return role_; }
00054     //! Returns "Signal Source"
00055     inline std::string implementation() override { return "Signal Source"; }
00056     inline size_t item_size() override { return 0; }
00057     inline size_t getRFChannels() const final { return 0; }
00058
00059     inline std::shared_ptr<GNSSBlockInterface> signal_generator() const { return signal_generator_; }
00060
00061 private:
00062     std::shared_ptr<GNSSBlockInterface> signal_generator_;
00063     std::shared_ptr<GNSSBlockInterface> filter_;
00064     std::string role_;
00065     std::string implementation_;
00066     bool connected_;
00067 };
00068
00069
00070 /** \} */
00071 /** \} */
00072 #endif // GNSS_SDR_GEN_SIGNAL_SOURCE_H

```

13.356 gnmax_signal_source.h File Reference

gnMAX2769 USB dongle GPS RF front-end signal sampler driver

```

#include "concurrent_queue.h"
#include "signal_source_base.h"
#include <gnuradio/blocks/file_sink.h>
#include <pmt/pmt.h>
#include <cstdint>
#include <memory>
#include <stdexcept>
#include <string>

```

Classes

- class [GnMaxSignalSource](#)

This class reads samples from a gnMAX2769 USB dongle, a RF front-end signal sampler.

13.356.1 Detailed Description

gnMAX2769 USB dongle GPS RF front-end signal sampler driver

Author

Wojciech Kazubski, wk(at)ire.pw.edu.pl

Javier Arribas, jarribas(at)cttc.es

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GNSS-SDR is a software defined Global Navigation Satellite Systems receiver

This file is part of GNSS-SDR.

SPDX-License-Identifier: GPL-3.0-or-later

Definition in file [gnmax_signal_source.h](#).

13.357 gnmax_signal_source.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gnmax_signal_source.h
00003  * \brief gnMAX2769 USB dongle GPS RF front-end signal sampler driver
00004  * \author Wojciech Kazubski, wk(at)ire.pw.edu.pl
00005  * \author Javier Arribas, jarribas(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)

```

```

00010  *
00011  * GNSS-SDR is a software defined Global Navigation
00012  *       Satellite Systems receiver
00013  *
00014  * This file is part of GNSS-SDR.
00015  *
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_GNMAX_SIGNAL_SOURCE_H_
00022 #define GNSS_SDR_GNMAX_SIGNAL_SOURCE_H_
00023
00024 #include "concurrent_queue.h"
00025 #include "signal_source_base.h"
00026 #include <gnuradio/blocks/file_sink.h>
00027 #include <pmt/pmt.h>
00028 #include <cstdint>
00029 #include <memory>
00030 #include <stdexcept>
00031 #include <string>
00032
00033 /** \addtogroup Signal_Source
00034  *  \{ */
00035 /** \addtogroup Signal_Source_adapters
00036  *  \{ */
00037
00038
00039 class ConfigurationInterface;
00040
00041 /*!
00042  * \brief This class reads samples from a gnMAX2769 USB dongle, a RF front-end signal sampler
00043  */
00044 class GnMaxSignalSource : public SignalSourceBase
00045 {
00046 public:
00047     GnMaxSignalSource(const ConfigurationInterface* configuration,
00048                       const std::string& role, unsigned int in_stream,
00049                       unsigned int out_stream, Concurrent_Queue<pmt::pmt_t*> queue);
00050
00051     virtual ~GnMaxSignalSource();
00052
00053     inline size_t item_size() override
00054     {
00055         return item_size_;
00056     }
00057
00058     void connect(gr::top_block_sptr top_block) override;
00059     void disconnect(gr::top_block_sptr top_block) override;
00060     gr::basic_block_sptr get_left_block() override;
00061     gr::basic_block_sptr get_right_block() override;
00062
00063 private:
00064     gr::block_sptr gnmax_source_;
00065     gnss_shared_ptr<gr::block> valve_;
00066     gr::blocks::file_sink::sptr file_sink_;
00067
00068     std::string item_type_;
00069     std::string dump_filename_;
00070
00071     // Front-end settings
00072     bool bias_;
00073     int bias__;
00074     int ant_;
00075     unsigned long freq_; // frequency of local oscillator
00076     float freq__;
00077     unsigned long bw_;
00078     int bw__;
00079     bool zeroif_;
00080     int zeroif__;
00081
00082     size_t item_size_;
00083     int64_t samples_;
00084
00085     unsigned int in_stream_;
00086     unsigned int out_stream_;
00087
00088     bool dump_;
00089 };
00090
00091
00092 /** \} */
00093 /** \} */
00094 #endif /*GNSS_SDR_GNMAX_SIGNAL_SOURCE_H_*/

```

13.358 ion_gsms_signal_source.h File Reference

GNSS-SDR Signal Source that reads sample streams following ION's GNSS-SDR metadata standard.

```
#include "configuration_interface.h"
#include "file_source_base.h"
#include "gnss_sdr_timestamp.h"
#include "ion_gsms.h"
#include <GnssMetadata.h>
#include <cstdint>
#include <memory>
#include <string>
#include <vector>
```

Classes

- class [IONGSMSSignalSource](#)

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

13.358.1 Detailed Description

GNSS-SDR Signal Source that reads sample streams following ION's GNSS-SDR metadata standard.

Author

Víctor Castillo Agüero, 2024. victorcastilloaguero(at)gmail.com

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 Definition in file [ion_gsms_signal_source.h](#).

13.359 ion_gsms_signal_source.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file ion_gsms_signal_source.h
00003  * \brief GNSS-SDR Signal Source that reads sample streams following ION's GNSS-SDR metadata standard
00004  * \author Víctor Castillo Agüero, 2024. victorcastilloaguero(at)gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_ION_GSMS_SIGNAL_SOURCE_H
00019 #define GNSS_SDR_ION_GSMS_SIGNAL_SOURCE_H
00020
00021 #include "configuration_interface.h"
00022 #include "file_source_base.h"
00023 #include "gnss_sdr_timestamp.h"
00024 #include "ion_gsms.h"
00025 #include <GnssMetadata.h>
00026 #include <cstdint>
00027 #include <memory>
00028 #include <string>
00029 #include <vector>
00030
00031 /** \addtogroup Signal_Source
00032  * \{ */
00033 /** \addtogroup Signal_Source_adapters
00034  * \{ */
00035
00036 /*!
00037  * \brief Class that reads signals samples from a file
00038  * and adapts it to a SignalSourceInterface
```

```

00039  */
00040  class IONGSMSSignalSource : public SignalSourceBase
00041  {
00042  public:
00043      IONGSMSSignalSource(const ConfigurationInterface* configuration, const std::string& role,
00044                          unsigned int in_streams, unsigned int out_streams,
00045                          Concurrent_Queue<pmt::pmt_t*> queue);
00046
00047      ~IONGSMSSignalSource() override = default;
00048
00049  protected:
00050      void connect(gr::top_block_sptr top_block) override;
00051      void disconnect(gr::top_block_sptr top_block) override;
00052
00053      gr::basic_block_sptr get_left_block() override;
00054      gr::basic_block_sptr get_right_block() override;
00055      gr::basic_block_sptr get_right_block(int RF_channel) override;
00056
00057      inline size_t item_size() override
00058      {
00059          return (*sources_.begin())->output_stream_item_size(0);
00060      }
00061
00062  private:
00063      std::vector<IONGSMSSignalSource::sptr> make_stream_sources(const std::vector<std::string>&
00064                                                                stream_ids) const;
00065
00066      void load_metadata();
00067
00068      std::vector<std::string> stream_ids_;
00069      std::vector<IONGSMSSignalSource::sptr> sources_;
00070      std::vector<gnss_shared_ptr<gr::block>> copy_blocks_;
00071      std::vector<gnss_shared_ptr<gr::block>> valves_;
00072
00073      std::string metadata_filepath_;
00074      std::shared_ptr<GnssMetadata::Metadata> metadata_;
00075
00076      gnss_shared_ptr<Gnss_Sdr_Timestamp> timestamp_block_;
00077      std::string timestamp_file_;
00078
00079      uint32_t in_streams_;
00080      uint32_t out_streams_;
00081  };
00082
00083  /** \} */
00084  /** \} */
00085  #endif // GNSS_SDR_ION_GSMS_SIGNAL_SOURCE_H

```

13.360 labsat_signal_source.h File Reference

LabSat version 2, 3, and 3 Wideband format reader.

```

#include "concurrent_queue.h"
#include "gnss_block_interface.h"
#include "signal_source_base.h"
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/throttle.h>
#include <gnuradio/hier_block2.h>
#include <pmt/pmt.h>
#include <memory>
#include <string>
#include <vector>

```

Classes

- class [LabsatSignalSource](#)

This class reads samples stored in LabSat version 2, 3, and 3 Wideband format.

13.360.1 Detailed Description

LabSat version 2, 3, and 3 Wideband format reader.

Author

Javier Arribas, jarribas(at)cttc.es

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 Definition in file [labsat_signal_source.h](#).

13.361 labsat_signal_source.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002   * \file labsat_signal_source.h
00003   * \brief LabSat version 2, 3, and 3 Wideband format reader
00004   * \author Javier Arribas, jarribas(at)cttc.es
00005   *
00006   * -----
00007   *
00008   * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009   * This file is part of GNSS-SDR.
00010   *
00011   * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00012   * SPDX-License-Identifier: GPL-3.0-or-later
00013   *
00014   * -----
00015   */
00016
00017
00018 #ifndef GNSS_SDR_LABSAT_SIGNAL_SOURCE_H
00019 #define GNSS_SDR_LABSAT_SIGNAL_SOURCE_H
00020
00021 #include "concurrent_queue.h"
00022 #include "gnss_block_interface.h"
00023 #include "signal_source_base.h"
00024 #include <gnuradio/blocks/file_sink.h>
00025 #include <gnuradio/blocks/throttle.h>
00026 #include <gnuradio/hier_block2.h>
00027 #include <pmt/pmt.h>
00028 #include <memory>
00029 #include <string>
00030 #include <vector>
00031
00032 /** \addtogroup Signal_Source
00033  * \{ */
00034 /** \addtogroup Signal_Source_adapters
00035  * \{ */
00036
00037
00038 class ConfigurationInterface;
00039
00040 /*!
00041  * \brief This class reads samples stored in LabSat version 2, 3, and 3 Wideband
00042  * format.
00043  */
00044 class LabsatSignalSource : public SignalSourceBase
00045 {
00046 public:
00047     LabsatSignalSource(const ConfigurationInterface* configuration,
00048                       const std::string& role, unsigned int in_stream,
00049                       unsigned int out_stream, Concurrent_Queue<pmt::pmt_t>* queue);
00050
00051     ~LabsatSignalSource() = default;
00052
00053     inline size_t item_size() override
00054     {
00055         return item_size_;
00056     }
00057
00058     size_t getRfChannels() const override;
00059     void connect(gr::top_block_sptr top_block) override;
00060     void disconnect(gr::top_block_sptr top_block) override;
00061     gr::basic_block_sptr get_left_block() override;
00062     gr::basic_block_sptr get_right_block() override;
00063     gr::basic_block_sptr get_right_block(int i) override;
00064
00065 private:
00066     gr::block_sptr labsat23_source_;
00067     std::vector<gr::blocks::file_sink::sptr> file_sink_;
00068     std::vector<gr::blocks::throttle::sptr> throttle_;
00069     std::vector<int> channels_selector_vec_;
00070
00071     std::string item_type_;
00072     std::string filename_;

```



```

00073     std::string dump_filename_;
00074
00075     size_t item_size_;
00076
00077     unsigned int in_stream_;
00078     unsigned int out_stream_;
00079
00080     bool enable_throttle_control_;
00081     bool dump_;
00082 };
00083
00084 /** \} */
00085 /** \} */
00086 #endif // GNSS_SDR_LABSAT_SIGNAL_SOURCE_H

```

13.362 limesdr_signal_source.h

```

00001 /*!
00002  * \file limesdr_signal_source.cc
00003  * \brief Signal source for LimeSDR front-end
00004  * \author Javier Arribas, 2021. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_LIMESDR_SIGNAL_SOURCE_H
00018 #define GNSS_SDR_LIMESDR_SIGNAL_SOURCE_H
00019
00020 #include "concurrent_queue.h"
00021 #include "signal_source_base.h"
00022 #include <gnuradio/blocks/file_sink.h>
00023 #include <pmt/pmt.h>
00024 #include <cstdint>
00025 #include <limesdr/source.h>
00026 #include <memory>
00027 #include <stdexcept>
00028 #include <string>
00029
00030 /** \addtogroup Signal_Source
00031  * \{ */
00032 /** \addtogroup Signal_Source_adapters
00033  * \{ */
00034
00035
00036 class ConfigurationInterface;
00037
00038 /*!
00039  * \brief This class instantiates the LimeSDR gnuradio signal source.
00040  * It has support also for a customized LimeSDR firmware and signal source to support PPS samplestamp
00041  * reading.
00042  */
00042 class LimesdrSignalSource : public SignalSourceBase
00043 {
00044 public:
00045     LimesdrSignalSource(const ConfigurationInterface* configuration,
00046         const std::string& role, unsigned int in_stream,
00047         unsigned int out_stream, Concurrent_Queue<pmt::pmt_t>* queue);
00048
00049     ~LimesdrSignalSource() = default;
00050
00051     inline size_t item_size() override
00052     {
00053         return item_size_;
00054     }
00055
00056     void connect(gr::top_block_sptr top_block) override;
00057     void disconnect(gr::top_block_sptr top_block) override;
00058     gr::basic_block_sptr get_left_block() override;
00059     gr::basic_block_sptr get_right_block() override;
00060
00061 private:
00062     gr::limesdr::source::sptr limesdr_source_;
00063     gnss_shared_ptr<gr::block> valve_;
00064     gr::blocks::file_sink::sptr file_sink_;
00065
00066     std::string item_type_;

```

```

00067     std::string dump_filename_;
00068     std::string limesdr_serial_;
00069     std::string limesdr_file_;
00070
00071     // Front-end settings
00072     double sample_rate_;
00073     double freq_;
00074     double gain_;
00075     double analog_bw_hz_;
00076     double digital_bw_hz_;
00077     double ext_clock_MHz_;
00078     size_t item_size_;
00079     int64_t samples_;
00080
00081     unsigned int in_stream_;
00082     unsigned int out_stream_;
00083
00084     int limechannel_mode_;
00085     int antenna_;
00086     int channel_;
00087
00088     bool PPS_mode_;
00089     bool dump_;
00090 };
00091
00092
00093 /** \} */
00094 /** \} */
00095 #endif // GNSS_SDR_LIMESDR_SIGNAL_SOURCE_H

```

13.363 max2771_evkit_signal_source_fpga.h File Reference

Signal source for the MAX2771EVKIT evaluation board connected directly to FPGA accelerators. This source implements only the MAX2771 control. It is NOT compatible with conventional SDR acquisition and tracking blocks.

```

#include "command_event.h"
#include "concurrent_queue.h"
#include "fpga_buffer_monitor.h"
#include "fpga_spidev.h"
#include "gnss_block_interface.h"
#include "signal_source_base.h"
#include <pmt/pmt.h>
#include <cstdint>
#include <memory>
#include <mutex>
#include <string>
#include <thread>
#include <vector>

```

Classes

- class [MAX2771EVKITSignalSourceFPGA](#)

13.363.1 Detailed Description

Signal source for the MAX2771EVKIT evaluation board connected directly to FPGA accelerators. This source implements only the MAX2771 control. It is NOT compatible with conventional SDR acquisition and tracking blocks. GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [max2771_evkit_signal_source_fpga.h](#).

13.364 max2771_evkit_signal_source_fpga.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file max2771_evkit_signal_source_fpga.h
00003 * \brief Signal source for the MAX2771EVKIT evaluation board connected directly
00004 * to FPGA accelerators.

```

```

00005  * This source implements only the MAX2771 control. It is NOT compatible with
00006  * conventional SDR acquisition and tracking blocks.
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_MAX2771_EVKIT_SIGNAL_SOURCE_FPGA_H
00020 #define GNSS_SDR_MAX2771_EVKIT_SIGNAL_SOURCE_FPGA_H
00021
00022 #include "command_event.h"
00023 #include "concurrent_queue.h"
00024 #include "fpga_buffer_monitor.h"
00025 #include "fpga_spidev.h"
00026 #include "gnss_block_interface.h"
00027 #include "signal_source_base.h"
00028 #include <pmt/pmt.h> // for pmt::pmt_t
00029 #include <stdint> // for fixed-width integer types
00030 #include <memory> // for smart pointers
00031 #include <mutex> // for mutex
00032 #include <string> // for strings
00033 #include <thread> // for threads
00034 #include <vector> // for std::vector
00035
00036
00037 /** \addtogroup Signal_Source
00038  * \{ */
00039 /** \addtogroup Signal_Source_adapters
00040  * \{ */
00041
00042
00043 class ConfigurationInterface;
00044
00045 class MAX2771EVKITSignalSourceFPGA : public SignalSourceBase
00046 {
00047 public:
00048     MAX2771EVKITSignalSourceFPGA(const ConfigurationInterface *configuration,
00049                                 const std::string &role, unsigned int in_stream,
00050                                 unsigned int out_stream, Concurrent_Queue<pmt::pmt_t> *queue);
00051
00052     ~MAX2771EVKITSignalSourceFPGA();
00053
00054     std::vector<uint32_t> setup_regs(uint64_t freq);
00055
00056     inline size_t item_size() override
00057     {
00058         return item_size_;
00059     }
00060
00061     void connect(gr::top_block_sptr top_block) override;
00062     void disconnect(gr::top_block_sptr top_block) override;
00063     gr::basic_block_sptr get_left_block() override;
00064     gr::basic_block_sptr get_right_block() override;
00065
00066 private:
00067     const std::string DEFAULT_BUFF_MON_FILENAME = std::string("FPGA_buffer_monitor_dump.dat"); //
00068     Default buffer monitor output file
00069     const std::string FREQ_BAND_0_SPI_DEVICE_NAME = std::string("/dev/spidev2.0"); // SPI
00070     0 device name
00071     const std::string FREQ_BAND_1_SPI_DEVICE_NAME = std::string("/dev/spidev1.0"); // SPI
00072     1 device name
00073     const uint32_t MAX_NUM_FREQ_BANDS = 2; //
00074     Maximum number of frequency bands
00075     const uint32_t DEFAULT_NUM_FREQ_BANDS = 1; //
00076     Default number of frequency bands used
00077     const uint64_t DEFAULT_BANDWIDTH = 16400000; //
00078     Default bandwidth
00079     const uint32_t DEFAULT_FILTER_ORDER = 5; //
00080     Default filter order
00081     const uint64_t DEFAULT_SAMPLING_RATE = 16368000; //
00082     Default sampling rate
00083     const uint32_t DEFAULT_PGA_GAIN_VALUE = 0x3A; //
00084     default PGA gain when AGC is off
00085     // max PGA gain value
00086     const uint32_t MAX_PGA_GAIN_VALUE = 0x3F;
00087     // check buffer overflow and perform buffer monitoring every 1s by default
00088     const uint32_t BUFFER_MONITOR_PERIOD_MS = 1000;
00089     // buffer overflow and buffer monitoring initial delay
00090     const uint32_t BUFFER_MONITOR_INITIAL_DELAY_MS = 2000;
00091     // MAX2771 number of configuration registers

```

```

00083     const uint32_t MAX2771_NUM_REGS = 11;
00084     // MAX2771 configuration register fields
00085     const uint32_t IDLE = 0x0;           // Idle mode disabled
00086     const uint32_t MIXPOLE = 0x0;        // set the passive filter pole at mixer output at 13
MHz.
00087     const uint32_t MIXERMODE_HIGH_BAND = 0x0; // L1 band enabled
00088     const uint32_t MIXERMODE_LOW_BAND = 0x1; // L2/L5 band enabled
00089     const uint32_t FCEN = 0x58;          // Center frequency not used when in low-pass filter
mode. Set to default value.
00090     const uint32_t FCENX = 0x0;          // Polyphase filter selection set to Lowpass filter
00091     const uint32_t ANAIMON = 0x0;        // analog monitor disabled
00092     const uint32_t IQEN = 0x1;          // I and Q channels enable
00093     const uint32_t GAINREF = 0xAA;       // AGC Gain ref
00094     const uint32_t SPI_SDIO_CONFIG = 0x0; // SPI SDIO config when tri-stated: nothing applied
00095     const uint32_t FORMAT = 0x1;        // sign and magnitude
00096     const uint32_t BITS = 0x2;          // number of bits in the ADC = 2
00097     const uint32_t DRVCFG = 0x0;        // output driver configuration = CMOS Logic
00098     const uint32_t DIEID = 0x0;         // identifies version of IC
00099     const uint32_t HILOADEN = 0x0;       // disable output driver for high loads
00100     const uint32_t FHIPEN = 0x1;        // enable highpass coupling between filter and PGA.
00101     const uint32_t PGAEN = 0x1;         // I-Channel PGA Enable
00102     const uint32_t PGAQEN = 0x1;        // Q-Channel PGA Enable
00103     const uint32_t STRMEN = 0x0;        // disable DSP interface for serial streaming of data
00104     const uint32_t STRMSTART = 0x0;      // the rising edge of this bit enables data streaming
to the output, clock, data, sync and frame sync outputs.
00105     const uint32_t STRMSTOP = 0x0;      // the rising edge of this bit disables data streaming
to the output, clock, data sync and frame sync outputs.
00106     const uint32_t STRMBITS = 0x1;      // number of bits to be streamed: I MSB, I LSB
00107     const uint32_t STAMPEN = 0x1;       // enable frame number insertion
00108     const uint32_t TIMESYNCEN = 0x1;    // enable the output of the time sync pulses at all
times when streaming is enabled.
00109     const uint32_t DATASYNCEN = 0x0;    // disable the sync pulses at the DATASYNC output
00110     const uint32_t STRMRST = 0x0;       // counter reset not active
00111     const uint32_t LOBAND_L1 = 0x0;     // L1 band
00112     const uint32_t LOBAND_L5 = 0x1;     // L5 band
00113     const uint32_t REFOUTEN = 0x1;      // Output clock buffer enable
00114     const uint32_t IXTAL = 0x1;         // XTAL oscillator/buffer set to normal current
00115     const uint32_t ICP = 0x0;           // charge pump current selection set to 0.5 mA
00116     const uint32_t INT_PLL = 0x1;       // PLL mode set to integer-N PLL
00117     const uint32_t PWRSV = 0x0;         // PLL power save mode disabled
00118     const uint32_t RDIV = 0x10;         // Set the PLL reference division ratio
00119     const uint32_t FDIV = 0x80000;      // PLL fractional division ratio not used. Set to
default value
00120     const uint32_t EXTADCCLK = 0x0;     // use internally generated clock
00121     const uint32_t REFCLK_L_CNT = 0x100; // set the L counter of the reference clock
configuration to its default value
00122     const uint32_t REFCLK_M_CNT = 0x61B; // set the M counter of the reference clock
configuration to its default value
00123     const uint32_t FCLKIN = 0x0;        // fractional clock divider set to default value
00124     const uint32_t ADCCLK = 0x0;        // ADC clock selection set to reference clock
divider/multiplier
00125     const uint32_t MODE = 0x0;          // DSP interface mode selection
00126     const uint32_t ADCCLK_L_CNT = 0x100; // set the L counter of the ADC clock configuration to
its default value
00127     const uint32_t ADCCLK_M_CNT = 0x61B; // set the M counter of the ADC clock configuration to
its default value
00128     const uint32_t PRE_FRACDIV_SEL = 0x0; // bypass fractional clock divider
00129     const uint32_t CLKOUT_SEL = 0x1;     // CLKOUT selection set to ADC clock
00130     // MAX2771 configuration register registers
00131     const uint32_t TEST_MODE_1_REG_VAL = 0x01E0F401; // reserved
00132     const uint32_t TEST_MODE_2_REG_VAL = 0x00000002;
00133
00134     bool configure(std::vector<uint32_t> register_values);
00135     void run_buffer_monitor_process();
00136
00137     mutable std::mutex buffer_monitor_mutex;
00138
00139     std::thread thread_buffer_monitor;
00140
00141     std::shared_ptr<Fpga_buffer_monitor> buffer_monitor_fpga;
00142     std::shared_ptr<Fpga_spidev> spidev_fpga;
00143
00144     uint64_t freq_; // Tuning frequency in single-band mode
00145     uint64_t freq0_; // Tuning frequency for band 0 when dual-band mode is enabled
00146     uint64_t freq1_; // Tuning frequency for band 1 when dual-band mode is enabled
00147     uint64_t sample_rate_;
00148
00149     uint32_t RF_channels_;
00150     uint32_t in_stream_;
00151     uint32_t out_stream_;
00152     uint32_t bandwidth_; // 2500000, 4200000, 8700000, 16400000, 23400000, 36000000
00153     uint32_t filter_order_; // 3, 5
00154     uint32_t gain_in_; // 0 to 0x3F
00155
00156     size_t item_size_; // 1
00157
00158     bool chipen_; // chip enable

```

```

00159     bool if_filter_gain_; // true, false
00160     bool LNA_active_;     // true, false
00161     bool enable_agc_;     // true, false
00162     bool enable_ovf_check_buffer_monitor_active_;
00163     bool dump_;
00164     bool rf_shutdown_;
00165 };
00166
00167
00168 /** @} */
00169 /** @} */
00170 #endif // GNSS_SDR_MAX2771_EVKIT_SIGNAL_SOURCE_FPGA_H

```

13.365 multichannel_file_signal_source.h File Reference

Implementation of a class that reads signals samples from files at different frequency band and adapts it to a [SignalSourceInterface](#).

```

#include "concurrent_queue.h"
#include "gnss_block_interface.h"
#include "signal_source_base.h"
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/file_source.h>
#include <gnuradio/blocks/throttle.h>
#include <gnuradio/hier_block2.h>
#include <pmt/pmt.h>
#include <stdint>
#include <string>
#include <vector>

```

Classes

- class [MultichannelFileSignalSource](#)

Class that reads signals samples from files at different frequency bands and adapts it to a [SignalSourceInterface](#).

13.365.1 Detailed Description

Implementation of a class that reads signals samples from files at different frequency band and adapts it to a [SignalSourceInterface](#).

Author

Javier Arribas, 2019 jarribas(at)cttc.es

This class represents a file signal source. Internally it uses a GNU Radio's `gr_file_source` as a connector to the data.

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [multichannel_file_signal_source.h](#).

13.366 multichannel_file_signal_source.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file multichannel_file_signal_source.h
00003  * \brief Implementation of a class that reads signals samples from files at
00004  * different frequency band and adapts it to a SignalSourceInterface
00005  * \author Javier Arribas, 2019 jarribas(at)cttc.es
00006  *
00007  * This class represents a file signal source. Internally it uses a GNU Radio's
00008  * gr_file_source as a connector to the data.
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.

```

```

00014  *
00015  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_MULTICHANNEL_FILE_SIGNAL_SOURCE_H
00022 #define GNSS_SDR_MULTICHANNEL_FILE_SIGNAL_SOURCE_H
00023
00024 #include "concurrent_queue.h"
00025 #include "gnss_block_interface.h"
00026 #include "signal_source_base.h"
00027 #include <gnuradio/blocks/file_sink.h>
00028 #include <gnuradio/blocks/file_source.h>
00029 #include <gnuradio/blocks/throttle.h>
00030 #include <gnuradio/hier_block2.h>
00031 #include <pmt/pmt.h>
00032 #include <stdint>
00033 #include <string>
00034 #include <vector>
00035
00036
00037 /** \addtogroup Signal_Source
00038  * \{ */
00039 /** \addtogroup Signal_Source_adapters
00040  * \{ */
00041
00042
00043 class ConfigurationInterface;
00044
00045 /*!
00046  * \brief Class that reads signals samples from files at different frequency bands
00047  * and adapts it to a SignalSourceInterface
00048  */
00049 class MultichannelFileSignalSource : public SignalSourceBase
00050 {
00051 public:
00052     MultichannelFileSignalSource(const ConfigurationInterface* configuration, const std::string& role,
00053     unsigned int in_streams, unsigned int out_streams,
00054     Concurrent_Queue<pmt::pmt_t>* queue);
00055
00056     ~MultichannelFileSignalSource() = default;
00057
00058     inline size_t item_size() override
00059     {
00060         return item_size_;
00061     }
00062
00063     void connect(gr::top_block_sptr top_block) override;
00064     void disconnect(gr::top_block_sptr top_block) override;
00065     gr::basic_block_sptr get_left_block() override;
00066     gr::basic_block_sptr get_right_block() override;
00067
00068     inline std::string filename() const
00069     {
00070         return filename_vec_.at(0);
00071     }
00072
00073     inline std::string item_type() const
00074     {
00075         return item_type_;
00076     }
00077
00078     inline bool repeat() const
00079     {
00080         return repeat_;
00081     }
00082
00083     inline int64_t sampling_frequency() const
00084     {
00085         return sampling_frequency_;
00086     }
00087
00088     inline uint64_t samples() const
00089     {
00090         return samples_;
00091     }
00092
00093 private:
00094     std::vector<gr::blocks::file_source::sptr> file_source_vec_;
00095     gnss_shared_ptr<gr::block> valve_;
00096     gr::blocks::file_sink::sptr sink_;
00097     std::vector<gr::blocks::throttle::sptr> throttle_vec_;
00098     std::vector<std::string> filename_vec_;
00099     std::string item_type_;
00100     uint64_t samples_;

```

```

00101     int64_t sampling_frequency_;
00102     size_t item_size_;
00103     int32_t n_channels_;
00104     uint32_t in_streams_;
00105     uint32_t out_streams_;
00106     bool repeat_;
00107     // Throttle control
00108     bool enable_throttle_control_;
00109 };
00110
00111
00112 /** \} */
00113 /** \} */
00114 #endif // GNSS_SDR_MULTICHANNEL_FILE_SIGNAL_SOURCE_H

```

13.367 nsr_file_signal_source.h File Reference

Implementation of a class that reads signals samples from a NSR 2 bits sampler front-end file and adapts it to a [SignalSourceInterface](#). More information about the front-end here <http://www.ifen.com/products/sx-scientific-gnss-solutions/nsr-software-receiver.html>.

```

#include "file_source_base.h"
#include "unpack_byte_2bit_samples.h"
#include <stdintdef>
#include <string>
#include <tuple>

```

Classes

- class [NsrFileSignalSource](#)

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

13.367.1 Detailed Description

Implementation of a class that reads signals samples from a NSR 2 bits sampler front-end file and adapts it to a [SignalSourceInterface](#). More information about the front-end here <http://www.ifen.com/products/sx-scientific-gnss-solutions/nsr-software-receiver.html>.

Author

Javier Arribas, 2013 jarribas(at)cttc.es

This class represents a file signal source.

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [nsr_file_signal_source.h](#).

13.368 nsr_file_signal_source.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file nsr_file_signal_source.h
00003  * \brief Implementation of a class that reads signals samples from a NSR 2 bits sampler front-end
00004  * file
00005  * and adapts it to a SignalSourceInterface. More information about the front-end here
00006  * http://www.ifen.com/products/sx-scientific-gnss-solutions/nsr-software-receiver.html
00007  * \author Javier Arribas, 2013 jarribas(at)cttc.es
00008  *
00009  * This class represents a file signal source.
00010  *
00011  * -----
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----

```

```

00019  */
00020
00021 #ifndef GNSS_SDR_NSR_FILE_SIGNAL_SOURCE_H
00022 #define GNSS_SDR_NSR_FILE_SIGNAL_SOURCE_H
00023
00024 #include "file_source_base.h"
00025 #include "unpack_byte_2bit_samples.h"
00026 #include <cstdint>
00027 #include <string>
00028 #include <tuple>
00029
00030 /** \addtogroup Signal_Source
00031  * \{ */
00032 /** \addtogroup Signal_Source_adapters
00033  * \{ */
00034
00035 class ConfigurationInterface;
00036
00037 /*!
00038  * \brief Class that reads signals samples from a file
00039  * and adapts it to a SignalSourceInterface
00040  */
00041 class NsrFileSignalSource : public FileSourceBase
00042 {
00043 public:
00044     NsrFileSignalSource(const ConfigurationInterface* configuration, const std::string& role,
00045         unsigned int in_streams, unsigned int out_streams,
00046         Concurrent_Queue<pmt::pmt_t>* queue);
00047
00048     ~NsrFileSignalSource() = default;
00049
00050 protected:
00051     std::tuple<size_t, bool> itemTypeToSize() override;
00052     double packetsPerSample() const override;
00053     gnss_shared_ptr<gr::block> source() const override;
00054     void create_file_source_hook() override;
00055     void pre_connect_hook(gr::top_block_sptr top_block) override;
00056     void pre_disconnect_hook(gr::top_block_sptr top_block) override;
00057
00058 private:
00059     unpack_byte_2bit_samples_sptr unpack_byte_;
00060 };
00061
00062 /** \} */
00063 /** \} */
00064 #endif // GNSS_SDR_NSR_FILE_SIGNAL_SOURCE_H

```

13.369 ntlab_file_signal_source.h File Reference

Interface of a class that reads signal samples from a file. Each sample is two bits from multiple channels.

```

#include "file_source_base.h"
#include "unpack_ntlab_2bit_samples.h"
#include <cstdint>
#include <string>
#include <tuple>

```

Classes

- class [NTLabFileSignalSource](#)

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

13.369.1 Detailed Description

Interface of a class that reads signal samples from a file. Each sample is two bits from multiple channels.

Author

Pedro Pereira, 2025 pereirapedrocp (at) gmail.com

This class represents a file signal source.

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [ntlab_file_signal_source.h](#).

13.370 ntlab_file_signal_source.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file ntlab_file_signal_source.h
00003  * \brief Interface of a class that reads signal samples from a file. Each
00004  * sample is two bits from multiple channels.
00005  *
00006  * \author Pedro Pereira, 2025 pereirapedrocp (at) gmail.com
00007  *
00008  * This class represents a file signal source.
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_NTLAB_FILE_SIGNAL_SOURCE_H
00022 #define GNSS_SDR_NTLAB_FILE_SIGNAL_SOURCE_H
00023
00024 #include "file_source_base.h"
00025 #include "unpack_ntlab_2bit_samples.h"
00026 #include <stdint>
00027 #include <string>
00028 #include <tuple>
00029
00030
00031 /** \addtogroup Signal_Source
00032  * \{ */
00033 /** \addtogroup Signal_Source_adapters
00034  * \{ */
00035
00036
00037 class ConfigurationInterface;
00038
00039 /*!
00040  * \brief Class that reads signals samples from a file
00041  * and adapts it to a SignalSourceInterface
00042  */
00043 class NTLabFileSignalSource : public FileSourceBase
00044 {
00045 public:
00046     NTLabFileSignalSource(const ConfigurationInterface* configuration,
00047         const std::string& role, unsigned int in_streams,
00048         unsigned int out_streams, Concurrent_Queue<pmt::pmt_t>* queue);
00049
00050     ~NTLabFileSignalSource() = default;
00051
00052     gr::basic_block_sptr get_left_block() override;
00053     gr::basic_block_sptr get_right_block() override;
00054
00055 protected:
00056     std::tuple<size_t, bool> itemTypeToSize() override;
00057     double packetsPerSample() const override;
00058     gnss_shared_ptr<gr::block> source() const override;
00059     void create_file_source_hook() override;
00060     void pre_connect_hook(gr::top_block_sptr top_block) override;
00061     void pre_disconnect_hook(gr::top_block_sptr top_block) override;
00062
00063 private:
00064     std::string sample_type_;
00065     unpack_ntlab_2bit_samples_sptr unpack_samples_;
00066     int n_channels_;
00067 };
00068
00069
00070 /** \} */
00071 /** \} */
00072 #endif // GNSS_SDR_NTLAB_FILE_SIGNAL_SOURCE_H

```

13.371 osmosdr_signal_source.h File Reference

Signal source wrapper for OsmoSDR-compatible front-ends, such as HackRF or Realtek's RTL2832U-based USB dongle DVB-T receivers (see <https://osmocom.org/projects/rtl-sdr/wiki> for more information)

```
#include "concurrent_queue.h"
#include "signal_source_base.h"
#include <gnuradio/blocks/file_sink.h>
#include <pmt/pmt.h>
#include <cstdint>
#include <memory>
#include <osmosdr/source.h>
#include <stdexcept>
#include <string>
```

Classes

- class [OsmosdrSignalSource](#)

This class reads samples OmoSDR-compatible front-ends, such as HackRF or Realtek's RTL2832U-based USB dongle DVB-T receivers (see <https://osmocom.org/projects/rtl-sdr/wiki>)

13.371.1 Detailed Description

Signal source wrapper for OmoSDR-compatible front-ends, such as HackRF or Realtek's RTL2832U-based USB dongle DVB-T receivers (see <https://osmocom.org/projects/rtl-sdr/wiki> for more information)

Author

Javier Arribas, 2012. jarribas(at)cttc.es

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 Definition in file [osmosdr_signal_source.h](#).

13.372 osmosdr_signal_source.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file osmosdr_signal_source.h
00003  * \brief Signal source wrapper for OmoSDR-compatible front-ends, such as
00004  * \ HackRF or Realtek's RTL2832U-based USB dongle DVB-T receivers
00005  * (see https://osmocom.org/projects/rtl-sdr/wiki for more information)
00006  * \author Javier Arribas, 2012. jarribas(at)cttc.es
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_OSMOSDR_SIGNAL_SOURCE_H
00020 #define GNSS_SDR_OSMOSDR_SIGNAL_SOURCE_H
00021
00022 #include "concurrent_queue.h"
00023 #include "signal_source_base.h"
00024 #include <gnuradio/blocks/file_sink.h>
00025 #include <pmt/pmt.h>
00026 #include <cstdint>
00027 #include <memory>
00028 #include <osmosdr/source.h>
00029 #include <stdexcept>
00030 #include <string>
00031
00032 /** \addtogroup Signal_Source
00033  * \{ */
00034 /** \addtogroup Signal_Source_adapters
00035  * \{ */
00036
00037
00038 class ConfigurationInterface;
00039
```

```

00040  /*!
00041  * \brief This class reads samples OsmoSDR-compatible front-ends, such as
00042  * HackRF or Realtek's RTL2832U-based USB dongle DVB-T receivers
00043  * (see https://osmocom.org/projects/rtl-sdr/wiki)
00044  */
00045  class OsmosdrSignalSource : public SignalSourceBase
00046  {
00047  public:
00048      OsmosdrSignalSource(const ConfigurationInterface* configuration,
00049                          const std::string& role, unsigned int in_stream,
00050                          unsigned int out_stream, Concurrent_Queue<pmt::pmt_t*> queue);
00051
00052      ~OsmosdrSignalSource() = default;
00053
00054      inline size_t item_size() override
00055      {
00056          return item_size_;
00057      }
00058
00059      void connect(gr::top_block_sptr top_block) override;
00060      void disconnect(gr::top_block_sptr top_block) override;
00061      gr::basic_block_sptr get_left_block() override;
00062      gr::basic_block_sptr get_right_block() override;
00063
00064  private:
00065      void driver_instance();
00066
00067      osmosdr::source::sptr osmosdr_source_;
00068      gnss_shared_ptr<gr::block> valve_;
00069      gr::blocks::file_sink::sptr file_sink_;
00070
00071      std::string item_type_;
00072      std::string dump_filename_;
00073      std::string osmosdr_args_;
00074      std::string antenna_;
00075
00076      // Front-end settings
00077      double sample_rate_;
00078      double freq_;
00079      double gain_;
00080      double if_gain_;
00081      double rf_gain_;
00082      double if_bw_;
00083
00084      size_t item_size_;
00085      int64_t samples_;
00086
00087      unsigned int in_stream_;
00088      unsigned int out_stream_;
00089
00090      bool AGC_enabled_;
00091      bool dump_;
00092  };
00093
00094
00095  /** \} */
00096  /** \} */
00097  #endif // GNSS_SDR_OSMOSDR_SIGNAL_SOURCE_H

```

13.373 plutosdr_signal_source.h File Reference

Signal source for PlutoSDR.

```

#include "signal_source_base.h"
#include <gnuradio/blocks/file_sink.h>
#include <iio/pluto_source.h>
#include "concurrent_queue.h"
#include <pmt/pmt.h>
#include <cstdint>
#include <string>

```

Classes

- class [PlutosdrSignalSource](#)

13.373.1 Detailed Description

Signal source for PlutoSDR.

Author

Rodrigo Muñoz, 2017, [rmunozl\(at\)inacap.cl](mailto:rmunozl@inacap.cl), [rodrigo.munoz\(at\)proteinlab.cl](mailto:rodrigo.munoz(at)proteinlab.cl)

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Definition in file [plutosdr_signal_source.h](#).

13.374 plutosdr_signal_source.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file plutosdr_signal_source.h
00003  * \brief Signal source for PlutoSDR
00004  * \author Rodrigo Muñoz, 2017, rmunozl\(at\)inacap.cl, rodrigo.munoz\(at\)proteinlab.cl
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_PLUTOSDR_SIGNAL_SOURCE_H
00020 #define GNSS_SDR_PLUTOSDR_SIGNAL_SOURCE_H
00021
00022 #include "signal_source_base.h"
00023 #include <gnuradio/blocks/file_sink.h>
00024 #if GRIIO_INCLUDE_HAS_GNURADIO
00025 #if GR_IIO_TEMPLATIZED_API
00026 #include <gnuradio/iio/fmcomms2_source.h>
00027 #else
00028 #include <gnuradio/iio/pluto_source.h>
00029 #endif
00030 #else
00031 #include <iio/pluto_source.h>
00032 #endif
00033 #include "concurrent_queue.h"
00034 #include <pmt/pmt.h>
00035 #include <stdint>
00036 #include <string>
00037
00038
00039 /** \addtogroup Signal_Source
00040  * \{ */
00041 /** \addtogroup Signal_Source_adapters
00042  * \{ */
00043
00044
00045 class ConfigurationInterface;
00046
00047 /*!
00048 */
00049 class PlutosdrSignalSource : public SignalSourceBase
00050 {
00051 public:
00052     PlutosdrSignalSource(const ConfigurationInterface* configuration,
00053                         const std::string& role, unsigned int in_stream,
00054                         unsigned int out_stream, Concurrent_Queue<pmt::pmt_t>* queue);
00055
00056     ~PlutosdrSignalSource() = default;
00057
00058     size_t item_size() override
00059     {
00060         return item_size_;
00061     }
00062
00063     void connect(gr::top_block_sptr top_block) override;
00064     void disconnect(gr::top_block_sptr top_block) override;
00065     gr::basic_block_sptr get_left_block() override;
00066     gr::basic_block_sptr get_right_block() override;
00067

```

```

00068 private:
00069     const std::string default_gain_mode = std::string("slow_attack");
00070     #if GR_IIO_TEMPLATIZED_API
00071         gr::iio::fmcomms2_source<gr_complex>::sptr plutosdr_source_;
00072     #else
00073         gr::iio::pluto_source::sptr plutosdr_source_;
00074     #endif
00075
00076     gnss_shared_ptr<gr::block> valve_;
00077     gr::blocks::file_sink::sptr file_sink_;
00078
00079     std::string dump_filename_;
00080
00081     // Front-end settings
00082     std::string uri_; // device direction
00083     std::string gain_mode_;
00084     std::string filter_file_;
00085     std::string filter_source_;
00086     std::string filter_filename_;
00087     std::string item_type_;
00088     double rf_gain_;
00089     int64_t samples_;
00090     uint64_t freq_; // frequency of local oscillator
00091     uint64_t sample_rate_;
00092     uint64_t bandwidth_;
00093     uint64_t buffer_size_; // reception buffer
00094     size_t item_size_;
00095     float Fpass_;
00096     float Fstop_;
00097     unsigned int in_stream_;
00098     unsigned int out_stream_;
00099
00100     bool quadrature_;
00101     bool rf_dc_;
00102     bool bb_dc_;
00103     bool filter_auto_;
00104     bool dump_;
00105 };
00106
00107
00108 /** \} */
00109 /** \} */
00110 #endif // GNSS_SDR_PLUTOSDR_SIGNAL_SOURCE_H

```

13.375 raw_array_signal_source.h File Reference

CTTC Experimental GNSS 8 channels array signal source.

```

#include "concurrent_queue.h"
#include "signal_source_base.h"
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/hier_block2.h>
#include <pmt/pmt.h>
#include <cstdint>
#include <memory>
#include <string>

```

Classes

- class [RawArraySignalSource](#)

This class reads samples from an antenna array RF front-end signal sampler.

13.375.1 Detailed Description

CTTC Experimental GNSS 8 channels array signal source.

Author

Javier Arribas, jarribas(at)cttc.es

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 Definition in file [raw_array_signal_source.h](#).

13.376 raw_array_signal_source.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file raw_array_signal_source.h
00003  * \brief CTTC Experimental GNSS 8 channels array signal source
00004  * \author Javier Arribas, jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_RAW_ARRAY_SIGNAL_SOURCE_H
00019 #define GNSS_SDR_RAW_ARRAY_SIGNAL_SOURCE_H
00020
00021 #include "concurrent_queue.h"
00022 #include "signal_source_base.h"
00023 #include <gnuradio/blocks/file_sink.h>
00024 #include <gnuradio/hier_block2.h>
00025 #include <pmt/pmt.h>
00026 #include <stdint>
00027 #include <memory>
00028 #include <string>
00029
00030
00031 /** \addtogroup Signal_Source
00032  * \{ */
00033 /** \addtogroup Signal_Source_adapters
00034  * \{ */
00035
00036
00037 class ConfigurationInterface;
00038
00039 /*!
00040 * \brief This class reads samples from an antenna array RF front-end signal sampler
00041 */
00042 class RawArraySignalSource : public SignalSourceBase
00043 {
00044 public:
00045     RawArraySignalSource(const ConfigurationInterface* configuration,
00046                         std::string role, unsigned int in_stream,
00047                         unsigned int out_stream, Concurrent_Queue<pmt::pmt_t>* queue);
00048
00049     ~RawArraySignalSource() = default;
00050
00051     inline size_t item_size() override
00052     {
00053         return item_size_;
00054     }
00055
00056     void connect(gr::top_block_sptr top_block) override;
00057     void disconnect(gr::top_block_sptr top_block) override;
00058     gr::basic_block_sptr get_left_block() override;
00059     gr::basic_block_sptr get_right_block() override;
00060
00061 private:
00062     gr::block_sptr raw_array_source_;
00063     gr::blocks::file_sink::sptr file_sink_;
00064     std::string item_type_;
00065     std::string dump_filename_;
00066     std::string eth_device_;
00067     size_t item_size_;
00068     [[maybe_unused]] int64_t samples_;
00069     unsigned int in_stream_;
00070     unsigned int out_stream_;
00071     bool dump_;
00072 };
00073
00074
00075 /** \} */
00076 /** \} */
00077 #endif // GNSS_SDR_RAW_ARRAY_SIGNAL_SOURCE_H

```

13.377 rtl_tcp_signal_source.h File Reference

Signal source which reads from rtl_tcp. (see <https://osmocom.org/projects/rtl-sdr/wiki> for more information)

```
#include "concurrent_queue.h"
#include "rtl_tcp_signal_source_c.h"
#include "signal_source_base.h"
#include <gnuradio/blocks/deinterleave.h>
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/float_to_complex.h>
#include <pmt/pmt.h>
#include <stdexcept>
#include <string>
```

Classes

- class [RtlTcpSignalSource](#)

This class reads from rtl_tcp, which streams interleaved I/Q samples over TCP. (see <https://osmocom.org/projects/rtl-sdr/wiki>)

13.377.1 Detailed Description

Signal source which reads from rtl_tcp. (see <https://osmocom.org/projects/rtl-sdr/wiki> for more information)

Author

Anthony Arnold, 2015. anthony.arnold@uqconnect.edu.au

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Definition in file [rtl_tcp_signal_source.h](#).

13.378 rtl_tcp_signal_source.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtl_tcp_signal_source.h
00003  * \brief Signal source which reads from rtl_tcp.
00004  * (see https://osmocom.org/projects/rtl-sdr/wiki for more information)
00005  * \author Anthony Arnold, 2015. anthony.arnold@uqconnect.edu.au
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_RTL_TCP_SIGNAL_SOURCE_H
00019 #define GNSS_SDR_RTL_TCP_SIGNAL_SOURCE_H
00020
00021 #include "concurrent_queue.h"
00022 #include "rtl_tcp_signal_source_c.h"
00023 #include "signal_source_base.h"
00024 #include <gnuradio/blocks/deinterleave.h>
00025 #include <gnuradio/blocks/file_sink.h>
00026 #include <gnuradio/blocks/float_to_complex.h>
00027 #include <pmt/pmt.h>
00028 #include <stdexcept>
00029 #include <string>
00030
00031
00032 /** \addtogroup Signal_Source
00033  * \{ */
```

```

00034 /** \addtogroup Signal_Source_adapters
00035  * \{ */
00036
00037
00038 class ConfigurationInterface;
00039
00040 /*!
00041  * \brief This class reads from rtl_tcp, which streams interleaved
00042  * I/Q samples over TCP.
00043  * (see https://osmocom.org/projects/rtl-sdr/wiki)
00044  */
00045 class RtlTcpSignalSource : public SignalSourceBase
00046 {
00047 public:
00048     RtlTcpSignalSource(const ConfigurationInterface* configuration,
00049         const std::string& role,
00050         unsigned int in_stream,
00051         unsigned int out_stream,
00052         Concurrent_Queue<pmt::pmt_t*> queue);
00053
00054     ~RtlTcpSignalSource() = default;
00055
00056     inline size_t item_size() override
00057     {
00058         return item_size_;
00059     }
00060
00061     void connect(gr::top_block_sptr top_block) override;
00062     void disconnect(gr::top_block_sptr top_block) override;
00063     gr::basic_block_sptr get_left_block() override;
00064     gr::basic_block_sptr get_right_block() override;
00065
00066 private:
00067     void MakeBlock();
00068
00069     rtl_tcp_signal_source_c_sptr signal_source_;
00070
00071     gnss_shared_ptr<gr::block> valve_;
00072     gr::blocks::file_sink::sptr file_sink_;
00073
00074     std::string item_type_;
00075     std::string dump_filename_;
00076
00077     // rtl_tcp settings
00078     std::string address_;
00079     size_t item_size_;
00080     uint64_t samples_;
00081     double rf_gain_;
00082     int sample_rate_;
00083     int freq_;
00084     int gain_;
00085     int if_gain_;
00086     unsigned int in_stream_;
00087     unsigned int out_stream_;
00088     int16_t port_;
00089     bool AGC_enabled_;
00090     bool flip_iq_;
00091     bool dump_;
00092 };
00093
00094
00095 /** \} */
00096 /** \} */
00097 #endif // GNSS_SDR_RTL_TCP_SIGNAL_SOURCE_H

```

13.379 signal_source_base.h File Reference

Header file of the base class to signal_source GNSS blocks.

```

#include "signal_source_interface.h"
#include <cstdint>
#include <string>

```

Classes

- class [SignalSourceBase](#)

13.379.1 Detailed Description

Header file of the base class to signal_source GNSS blocks.

Author

Jim Melton, 2020. jim.melton(at)sncorp.com

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Definition in file [signal_source_base.h](#).

13.380 signal_source_base.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file signal_source_base.h
00003  * \brief Header file of the base class to signal_source GNSS blocks.
00004  * \author Jim Melton, 2020. jim.melton(at)sncorp.com
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
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00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_SIGNAL_SOURCE_BASE_H
00019 #define GNSS_SDR_SIGNAL_SOURCE_BASE_H
00020
00021 #include "signal_source_interface.h"
00022 #include <cstdlib>
00023 #include <string>
00024
00025
00026 class ConfigurationInterface;
00027
00028 class SignalSourceBase : public SignalSourceInterface
00029 {
00030 public:
00031     std::string role() final;
00032     std::string implementation() final;
00033
00034     size_t getRfChannels() const override;
00035     gr::basic_block_sptr get_left_block() override; // non-sensical; implement once
00036
00037 protected:
00038     /// Constructor
00039     SignalSourceBase(ConfigurationInterface const* configuration, std::string role, std::string impl);
00040
00041     /// utility for decoding passed ".item_type" values
00042     /// @param[in] item_type - user provided string, should be one of the known types
00043     /// @param[out] is_interleaved - if non-null, the pointed to memory is updated with
00044     ///                               whether the data is interleaved I/Q (e.g., ishort)
00045     /// @param[in] throw_on_error - if true, throw an exception if the string does not
00046     ///                               represent a known type
00047     /// @return the size in bytes of the passed type
00048     size_t decode_item_type(std::string const& item_type, bool* is_interleaved = nullptr, bool
00049                             throw_on_error = false);
00049
00050 private:
00051     std::string const role_;
00052     std::string const implementation_;
00053     size_t rfChannels_;
00054 };
00055
00056
00057 #endif
```

13.381 spir_file_signal_source.h File Reference

Implementation of a class that reads signals samples from a SPIR file and adapts it to a [SignalSourceInterface](#).

```
#include "file_source_base.h"
#include "unpack_intspir_lbit_samples.h"
#include <cstdlib>
#include <string>
#include <tuple>
```

Classes

- class [SpirFileSignalSource](#)

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

13.381.1 Detailed Description

Implementation of a class that reads signals samples from a SPIR file and adapts it to a [SignalSourceInterface](#).

Author

Fran Fabra, 2014 fabra(at)ice.csic.es

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 Definition in file [spir_file_signal_source.h](#).

13.382 spir_file_signal_source.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file spir_file_signal_source.h
00003  * \brief Implementation of a class that reads signals samples from a SPIR file
00004  * and adapts it to a SignalSourceInterface.
00005  * \author Fran Fabra, 2014 fabra(at)ice.csic.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_SPIR_FILE_SIGNAL_SOURCE_H
00019 #define GNSS_SDR_SPIR_FILE_SIGNAL_SOURCE_H
00020
00021 #include "file_source_base.h"
00022 #include "unpack_intspir_lbit_samples.h"
00023 #include <cstdlib>
00024 #include <string>
00025 #include <tuple>
00026
00027 /** \addtogroup Signal_Source
00028  * \{ */
00030 /** \addtogroup Signal_Source_adapters
00031  * \{ */
00032
00033
00034 class ConfigurationInterface;
00035
00036 /*!
00037  * \brief Class that reads signals samples from a file
00038  * and adapts it to a SignalSourceInterface
00039  */
00040 class SpirFileSignalSource : public FileSourceBase
00041 {
00042 public:
00043     SpirFileSignalSource(const ConfigurationInterface* configuration, const std::string& role,
00044         unsigned int in_streams, unsigned int out_streams,
00045         Concurrent_Queue<pmt::pmt_t>* queue);
00046
00047     ~SpirFileSignalSource() = default;
00048 }
```

```

00049 protected:
00050     std::tuple<size_t, bool> itemTypeToSize() override;
00051     gnss_shared_ptr<gr::block> source() const override;
00052     void create_file_source_hook() override;
00053     void pre_connect_hook(gr::top_block_sptr top_block) override;
00054     void post_disconnect_hook(gr::top_block_sptr top_block) override;
00055
00056
00057 private:
00058     unpack_intspir_lbit_samples_sptr unpack_intspir_;
00059 };
00060
00061
00062 /** \} */
00063 /** \} */
00064 #endif // GNSS_SDR_SPIR_FILE_SIGNAL_SOURCE_H

```

13.383 spir_gss6450_file_signal_source.h File Reference

Implementation of a class that reads signals samples from a SPIR file and adapts it to a [SignalSourceInterface](#).

```

#include "concurrent_queue.h"
#include "gnss_sdr_valve.h"
#include "signal_source_base.h"
#include "unpack_spir_gss6450_samples.h"
#include <gnuradio/blocks/deinterleave.h>
#include <gnuradio/blocks/endian_swap.h>
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/file_source.h>
#include <gnuradio/blocks/null_sink.h>
#include <gnuradio/blocks/throttle.h>
#include <gnuradio/hier_block2.h>
#include <pmt/pmt.h>
#include <cstdint>
#include <string>
#include <vector>

```

Classes

- class [SpirGSS6450FileSignalSource](#)

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

13.383.1 Detailed Description

Implementation of a class that reads signals samples from a SPIR file and adapts it to a [SignalSourceInterface](#).

Author

Antonio Ramos, 2017 antonio.ramos(at)cttc.es

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Definition in file [spir_gss6450_file_signal_source.h](#).

13.384 spir_gss6450_file_signal_source.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file spir_gss6450_file_signal_source.h
00003  * \brief Implementation of a class that reads signals samples from a SPIR file
00004  * and adapts it to a SignalSourceInterface.
00005  * \author Antonio Ramos, 2017 antonio.ramos(at)cttc.es
00006  *

```

```

00007  * -----
00008  *
00009  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00010  *
00011  * GNSS-SDR is a software defined Global Navigation
00012  *      Satellite Systems receiver
00013  *
00014  * This file is not part of GNSS-SDR.
00015  *
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_SPIR_GSS6450_FILE_SIGNAL_SOURCE_H
00022 #define GNSS_SDR_SPIR_GSS6450_FILE_SIGNAL_SOURCE_H
00023
00024 #include "concurrent_queue.h"
00025 #include "gnss_sdr_valve.h"
00026 #include "signal_source_base.h"
00027 #include "unpack_spir_gss6450_samples.h"
00028 #include <gnuradio/blocks/deinterleave.h>
00029 #include <gnuradio/blocks/endian_swap.h>
00030 #include <gnuradio/blocks/file_sink.h>
00031 #include <gnuradio/blocks/file_source.h>
00032 #include <gnuradio/blocks/null_sink.h>
00033 #include <gnuradio/blocks/throttle.h>
00034 #include <gnuradio/hier_block2.h>
00035 #include <pmt/pmt.h>
00036 #include <cstdint>
00037 #include <string>
00038 #include <vector>
00039
00040
00041 /** \addtogroup Signal_Source
00042  * \{ */
00043 /** \addtogroup Signal_Source_adapters
00044  * \{ */
00045
00046
00047 class ConfigurationInterface;
00048
00049 /*!
00050  * \brief Class that reads signals samples from a file
00051  * and adapts it to a SignalSourceInterface
00052  */
00053 class SpirGSS6450FileSignalSource : public SignalSourceBase
00054 {
00055 public:
00056     SpirGSS6450FileSignalSource(const ConfigurationInterface* configuration, const std::string& role,
00057         uint32_t in_streams, uint32_t out_streams, Concurrent_Queue<pmt::pmt_t>* queue);
00058
00059     inline size_t item_size() override
00060     {
00061         return item_size_;
00062     }
00063
00064     void connect(gr::top_block_sptr top_block) override;
00065     void disconnect(gr::top_block_sptr top_block) override;
00066     gr::basic_block_sptr get_left_block() override;
00067     gr::basic_block_sptr get_right_block(int RF_channel) override;
00068     gr::basic_block_sptr get_right_block() override;
00069
00070     inline std::string filename() const
00071     {
00072         return filename_;
00073     }
00074
00075     inline std::string item_type() const
00076     {
00077         return item_type_;
00078     }
00079
00080     inline bool repeat() const
00081     {
00082         return repeat_;
00083     }
00084
00085     inline int64_t sampling_frequency() const
00086     {
00087         return sampling_frequency_;
00088     }
00089
00090     inline uint64_t samples() const
00091     {
00092         return samples_;
00093     }

```

```

00094
00095 private:
00096     gr::blocks::file_source::sptr file_source_;
00097     gr::blocks::deinterleave::sptr deint_;
00098     std::vector<gnss_shared_ptr<gr::block> valve_vec_;
00099     std::vector<gr::blocks::endian_swap::sptr> endian_vec_;
00100     std::vector<gr::blocks::null_sink::sptr> null_sinks_;
00101     std::vector<unpack_spir_gss6450_samples_sptr> unpack_spir_vec_;
00102     std::vector<gr::blocks::file_sink::sptr> sink_vec_;
00103     std::vector<gr::blocks::throttle::sptr> throttle_vec_;
00104     std::string filename_;
00105     std::string dump_filename_;
00106     std::string item_type_;
00107     uint64_t samples_;
00108     int64_t sampling_frequency_;
00109     size_t item_size_;
00110     uint32_t in_streams_;
00111     uint32_t out_streams_;
00112     uint32_t adc_bits_;
00113     int32_t n_channels_;
00114     int32_t sel_ch_;
00115     bool repeat_;
00116     bool dump_; // Enables dumping the gr_complex sample output
00117     bool enable_throttle_control_;
00118     bool endian_swap_;
00119 };
00120
00121
00122 /** \} */
00123 /** \} */
00124 #endif // GNSS_SDR_SPIR_GSS6450_FILE_SIGNAL_SOURCE_H

```

13.385 two_bit_cpx_file_signal_source.h File Reference

Interface of a class that reads signals samples from a 2 bit complex sampler front-end file and adapts it to a [SignalSourceInterface](#).

```

#include "file_source_base.h"
#include "unpack_byte_2bit_cpx_samples.h"
#include <gnuradio/blocks/interleaved_short_to_complex.h>
#include <cstdint>
#include <string>
#include <tuple>

```

Classes

- class [TwoBitCpxFileSignalSource](#)

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

13.385.1 Detailed Description

Interface of a class that reads signals samples from a 2 bit complex sampler front-end file and adapts it to a [SignalSourceInterface](#).

Author

Javier Arribas, 2015 jarribas(at)cttc.es

This class represents a file signal source.

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Definition in file [two_bit_cpx_file_signal_source.h](#).

13.386 two_bit_cpx_file_signal_source.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file two_bit_cpx_file_signal_source.h
00003  * \brief Interface of a class that reads signals samples from a 2 bit complex sampler front-end file

```

```

00004  * and adapts it to a SignalSourceInterface.
00005  * \author Javier Arribas, 2015 jarribas(at)cttc.es
00006  *
00007  * This class represents a file signal source.
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_TWO_BIT_CPX_FILE_SIGNAL_SOURCE_H
00021 #define GNSS_SDR_TWO_BIT_CPX_FILE_SIGNAL_SOURCE_H
00022
00023 #include "file_source_base.h"
00024 #include "unpack_byte_2bit_cpx_samples.h"
00025 #include <gnuradio/blocks/interleaved_short_to_complex.h>
00026 #include <cstdint>
00027 #include <string>
00028 #include <tuple>
00029
00030 /** \addtogroup Signal_Source
00031  * \{ */
00032 /** \addtogroup Signal_Source_adapters
00033  * \{ */
00034
00035
00036 class ConfigurationInterface;
00037
00038 /*!
00039  * \brief Class that reads signals samples from a file
00040  * and adapts it to a SignalSourceInterface
00041  */
00042 class TwoBitCpxFileSignalSource : public FileSourceBase
00043 {
00044 public:
00045     TwoBitCpxFileSignalSource(const ConfigurationInterface* configuration,
00046                             const std::string& role,
00047                             unsigned int in_streams,
00048                             unsigned int out_streams,
00049                             Concurrent_Queue<pmt::pmt_t>* queue);
00050
00051     ~TwoBitCpxFileSignalSource() = default;
00052
00053 protected:
00054     std::tuple<size_t, bool> itemTypeToSize() override;
00055     double packetsPerSample() const override;
00056     gnss_shared_ptr<gr::block> source() const override;
00057     void create_file_source_hook() override;
00058     void pre_connect_hook(gr::top_block_sptr top_block) override;
00059     void pre_disconnect_hook(gr::top_block_sptr top_block) override;
00060
00061 private:
00062     unpack_byte_2bit_cpx_samples_sptr unpack_byte_;
00063     gr::blocks::interleaved_short_to_complex::sptr inter_shorts_to_cpx_;
00064 };
00065
00066
00067 /** \} */
00068 /** \} */
00069 #endif // GNSS_SDR_TWO_BIT_CPX_FILE_SIGNAL_SOURCE_H

```

13.387 two_bit_packed_file_signal_source.h File Reference

Interface of a class that reads signals samples from a file. Each sample is two bits, which are packed into bytes or shorts.

```

#include "file_source_base.h"
#include "unpack_2bit_samples.h"
#include <gnuradio/blocks/interleaved_char_to_complex.h>
#include <cstdint>
#include <string>
#include <tuple>

```

Classes

- class [TwoBitPackedFileSignalSource](#)

Class that reads signals samples from a file and adapts it to a [SignalSourceInterface](#).

13.387.1 Detailed Description

Interface of a class that reads signals samples from a file. Each sample is two bits, which are packed into bytes or shorts.

Author

Cillian O'Driscoll, 2015 cillian.odriscoll (at) gmail.com

This class represents a file signal source.

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Definition in file [two_bit_packed_file_signal_source.h](#).

13.388 two_bit_packed_file_signal_source.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file two_bit_packed_file_signal_source.h
00003  * \brief Interface of a class that reads signals samples from a file. Each
00004  * sample is two bits, which are packed into bytes or shorts.
00005  *
00006  * \author Cillian O'Driscoll, 2015 cillian.odriscoll (at) gmail.com
00007  *
00008  * This class represents a file signal source.
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_TWO_BIT_PACKED_FILE_SIGNAL_SOURCE_H
00022 #define GNSS_SDR_TWO_BIT_PACKED_FILE_SIGNAL_SOURCE_H
00023
00024 #include "file_source_base.h"
00025 #include "unpack_2bit_samples.h"
00026 #include <gnuradio/blocks/interleaved_char_to_complex.h>
00027 #include <cstdint>
00028 #include <string>
00029 #include <tuple>
00030
00031
00032 /** \addtogroup Signal_Source
00033  * \{ */
00034 /** \addtogroup Signal_Source_adapters
00035  * \{ */
00036
00037
00038 class ConfigurationInterface;
00039
00040 /*!
00041  * \brief Class that reads signals samples from a file
00042  * and adapts it to a SignalSourceInterface
00043  */
00044 class TwoBitPackedFileSignalSource : public FileSourceBase
00045 {
00046 public:
00047     TwoBitPackedFileSignalSource(const ConfigurationInterface* configuration, const std::string& role,
00048         unsigned int in_streams, unsigned int out_streams,
00049         Concurrent_Queue<pmt::pmt_t>* queue);
00050
00051     ~TwoBitPackedFileSignalSource() = default;
00052
00053 private:
00054     inline bool big_endian_items() const
00055     {
00056         return big_endian_items_;
00057     }
00058 }
```

```

00057     }
00058
00059     inline bool big_endian_bytes() const
00060     {
00061         return big_endian_bytes_;
00062     }
00063
00064
00065     inline bool reverse_interleaving() const
00066     {
00067         return reverse_interleaving_;
00068     }
00069
00070 protected:
00071     std::tuple<size_t, bool> itemTypeToSize() override;
00072     double packetsPerSample() const override;
00073     gnss_shared_ptr<gr::block> source() const override;
00074     void create_file_source_hook() override;
00075     void pre_connect_hook(gr::top_block_sptr top_block) override;
00076     void pre_disconnect_hook(gr::top_block_sptr top_block) override;
00077
00078 private:
00079     std::string sample_type_;
00080     bool big_endian_items_;
00081     bool big_endian_bytes_;
00082     bool reverse_interleaving_;
00083     unpack_2bit_samples_sptr unpack_samples_;
00084     gnss_shared_ptr<gr::block> char_to_float_;
00085 };
00086
00087
00088 /** \} */
00089 /** \} */
00090 #endif // GNSS_SDR_TWO_BIT_CPX_FILE_SIGNAL_SOURCE_H

```

13.389 uhd_signal_source.h File Reference

Interface for the Universal Hardware Driver signal source.

```

#include "concurrent_queue.h"
#include "signal_source_base.h"
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/hier_block2.h>
#include <gnuradio/uhd/usrp_source.h>
#include <pmt/pmt.h>
#include <cstdint>
#include <string>
#include <vector>

```

Classes

- class [UhdSignalSource](#)

This class reads samples from a UHD device (see <http://code.ettus.com/redmine/ettus/projects/uhd/wiki>)

13.389.1 Detailed Description

Interface for the Universal Hardware Driver signal source.

Author

Javier Arribas, 2012. jarribas(at)cttc.es

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Definition in file [uhd_signal_source.h](#).

13.390 uhd_signal_source.h

[Go to the documentation of this file.](#)


```

00001  /*!
00002  * \file uhd_signal_source.h
00003  * \brief Interface for the Universal Hardware Driver signal source
00004  * \author Javier Arribas, 2012. jarribas(at)ettc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_UHD_SIGNAL_SOURCE_H
00018 #define GNSS_SDR_UHD_SIGNAL_SOURCE_H
00019
00020 #include "concurrent_queue.h"
00021 #include "signal_source_base.h"
00022 #include <gnuradio/blocks/file_sink.h>
00023 #include <gnuradio/hier_block2.h>
00024 #include <gnuradio/uhd/usrp_source.h>
00025 #include <pmt/pmt.h>
00026 #include <stdint>
00027 #include <string>
00028 #include <vector>
00029
00030
00031 /** \addtogroup Signal_Source
00032  * \{ */
00033 /** \addtogroup Signal_Source_adapters
00034  * \{ */
00035
00036 class ConfigurationInterface;
00037
00038 /*!
00039 * \brief This class reads samples from a UHD device (see
00040 * http://code.ettus.com/redmine/ettus/projects/uhd/wiki)
00041 */
00041 class UhdSignalSource : public SignalSourceBase
00042 {
00043 public:
00044     UhdSignalSource(const ConfigurationInterface* configuration,
00045                     const std::string& role, unsigned int in_stream,
00046                     unsigned int out_stream, Concurrent_Queue<pmt::pmt_t*> queue);
00047
00048     ~UhdSignalSource() = default;
00049
00050     inline size_t item_size() override
00051     {
00052         return item_size_;
00053     }
00054
00055     void connect(gr::top_block_sptr top_block) override;
00056     void disconnect(gr::top_block_sptr top_block) override;
00057     gr::basic_block_sptr get_left_block() override;
00058     gr::basic_block_sptr get_right_block() override;
00059     gr::basic_block_sptr get_right_block(int RF_channel) override;
00060
00061 private:
00062     gr::uhd::usrp_source::sptr uhd_source_;
00063
00064     std::vector<gnss_shared_ptr<gr::block>> valve_;
00065     std::vector<gr::blocks::file_sink::sptr> file_sink_;
00066     std::vector<double> freq_;
00067     std::vector<double> gain_;
00068     std::vector<double> IF_bandwidth_hz_;
00069     std::vector<uint64_t> samples_;
00070     std::vector<std::string> dump_filename_;
00071     std::vector<bool> dump_;
00072
00073     uhd::stream_args_t uhd_stream_args_; // UHD SETTINGS
00074
00075     std::string device_address_;
00076     std::string item_type_;
00077     std::string subdevice_;
00078     std::string clock_source_;
00079
00080     // * The OTW format is a string that describes the format over-the-wire.
00081     // * The following over-the-wire formats have been implemented:
00082     // * - sc16 - Q16 I16
00083     // * - sc8 - Q8_1 I8_1 Q8_0 I8_0
00084     // * - sc12 (Only some devices)
00085     std::string otw_format_;
00086

```

```

00087     double sample_rate_;
00088     size_t item_size_;
00089     int RF_channels_;
00090     unsigned int in_stream_;
00091     unsigned int out_stream_;
00092 };
00093
00094
00095 /** \} */
00096 /** \} */
00097 #endif // GNSS_SDR_UHD_SIGNAL_SOURCE_H

```

13.391 zmq_signal_source.h File Reference

Signal source which reads from ZeroMQ.

```

#include "signal_source_base.h"
#include "concurrent_queue.h"
#include <gnuradio/blocks/file_sink.h>
#include <gnuradio/blocks/vector_to_stream.h>
#include <gnuradio/zeromq/sub_source.h>
#include <pmt/pmt.h>
#include <string>

```

Classes

- class [ZmqSignalSource](#)

This class supports the following properties:

13.391.1 Detailed Description

Signal source which reads from ZeroMQ.

Author

Jim Melton, 2022. [jim.melton\(at\)snrcorp.com](mailto:jim.melton@snrcorp.com)

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Definition in file [zmq_signal_source.h](#).

13.392 zmq_signal_source.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file zmq_signal_source.h
00003  * \brief Signal source which reads from ZeroMQ.
00004  * \author Jim Melton, 2022. jim.melton\(at\)snrcorp.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_ZMQ_SIGNAL_SOURCE_H
00018 #define GNSS_SDR_ZMQ_SIGNAL_SOURCE_H
00019
00020 #include "signal_source_base.h"
00021 //
00022 #include "concurrent_queue.h"
00023 #include <gnuradio/blocks/file_sink.h> // for dump
00024 #include <gnuradio/blocks/vector_to_stream.h>
00025 #include <gnuradio/zeromq/sub_source.h>
00026 #include <pmt/pmt.h>

```

```

00027 #include <string>
00028
00029 /** \addtogroup Signal_Source
00030 * \{ */
00031 /** \addtogroup Signal_Source_adapters
00032 * \{ */
00033
00034 //! This class supports the following properties:
00035 //!
00036 //! .endpoint - the ZMQ endpoint to be connected to
00037 //! .vlen - vector length of the input items (default 1, one item)
00038 //! this must match the size of the publisher!
00039 //! .pass_tags - boolean flag if tags should be propagated (default false)
00040 //! .timeout_ms - receive timeout, in milliseconds (default 100)
00041 //! .hwm - ZMQ high water mark (default -1, ZMQ default)
00042 //!
00043 //! .item_type - data type of the samples (default "gr_complex")
00044 //!
00045 //! (probably should be abstracted to the base class)
00046 //!
00047 //! .dump - whether to archive input data
00048 //! .dump_filename - if dumping, path to file for output
00049 //!
00050
00051 class ZmqSignalSource : public SignalSourceBase
00052 {
00053 public:
00054     ZmqSignalSource(const ConfigurationInterface* configuration,
00055                     const std::string& role,
00056                     unsigned int in_stream,
00057                     unsigned int out_stream,
00058                     Concurrent_Queue<pmt::pmt_t>* queue);
00059
00060     ~ZmqSignalSource() = default;
00061
00062     size_t item_size() override;
00063
00064     auto connect(gr::top_block_sptr top_block) -> void override;
00065     auto disconnect(gr::top_block_sptr top_block) -> void override;
00066     auto get_right_block() -> gr::basic_block_sptr override;
00067
00068 private:
00069     gr::zeromq::sub_source::sptr d_source_block;
00070     gr::blocks::vector_to_stream::sptr d_vec_block;
00071     gr::blocks::file_sink::sptr d_dump_sink;
00072
00073     size_t d_item_size;
00074     std::string d_dump_filename;
00075     bool d_dump;
00076 };
00077
00078 /** \} */
00079 /** \} */
00080 #endif

```

13.393 ad936x_iio_source.h File Reference

A direct IIO custom front-end gnss-sdr signal gnuradio block for the AD936x AD front-end family with special FPGA custom functionalities.

```

#include "ad936x_iio_custom.h"
#include "concurrent_queue.h"
#include "gnss_block_interface.h"
#include "ppstcprx.h"
#include <gnuradio/block.h>
#include <pmt/pmt.h>
#include <cstdint>
#include <fstream>
#include <iostream>
#include <memory>
#include <string>
#include <thread>
#include <vector>

```

Classes

- class [ad936x_iio_source](#)

This class implements conversion between Labsat 2, 3 and 3 Wideband formats to gr_complex.

Typedefs

- using [ad936x_iio_source_sptr](#) = gnss_shared_ptr<[ad936x_iio_source](#)>

Functions

- [ad936x_iio_source_sptr](#) **ad936x_iio_make_source_sptr** (const std::string &pluto_uri_, const std::string &board_type_, int64_t bandwidth_, int64_t sample_rate_, int64_t freq_, const std::string &rf_port_select_, const std::string &rf_filter, const std::string &gain_mode_rx0_, const std::string &gain_mode_rx1_, double rf_gain_rx0_, double rf_gain_rx1_, bool enable_ch0, bool enable_ch1, int64_t freq_2ch, bool ppsmode_, bool customsamplesize_, const std::string &fe_ip_, int fe_ctlport_, int ssize_, int bshift_, bool spattern_, double lo_attenuation_db_, bool high_side_lo_, int tx_lo_channel_)

13.393.1 Detailed Description

A direct IIO custom front-end gnss-sdr signal gnuradio block for the AD936x AD front-end family with special FPGA custom functionalities.

Author

Javier Arribas, jarribas(at)cttc.es

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Definition in file [ad936x_iio_source.h](#).

13.394 ad936x_iio_source.h

[Go to the documentation of this file.](#)

```
00001  /*!
00002  * \file ad936x_iio_source.h
00003  * \brief A direct IIO custom front-end gnss-sdr signal gnuradio block for the
00004  * AD936x AD front-end family with special FPGA custom functionalities.
00005  * \author Javier Arribas, jarribas(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_AD936X_IIO_SOURCE_H
00020 #define GNSS_SDR_AD936X_IIO_SOURCE_H
00021
00022 #include "ad936x_iio_custom.h"
00023 #include "concurrent_queue.h"
00024 #include "gnss_block_interface.h"
00025 #include "ppstcprx.h"
00026 #include <gnuradio/block.h>
00027 #include <pmt/pmt.h>
00028 #include <cstdint>
00029 #include <cstring>
00030 #include <fstream>
00031 #include <iostream>
00032 #include <memory>
00033 #include <string>
00034 #include <thread>
00035 #include <vector>
00036
00037 /** \addtogroup Signal_Source
00038  * \{ */
```

```

00039 /** \addtogroup Signal_Source_gnuradio_blocks
00040 * \{ */
00041
00042
00043 class ad936x_iio_source;
00044
00045 using ad936x_iio_source_sptr = gnss_shared_ptr<ad936x_iio_source>;
00046
00047 ad936x_iio_source_sptr ad936x_iio_make_source_sptr(
00048     const std::string &pluto_uri_,
00049     const std::string &board_type_,
00050     int64_t bandwidth_,
00051     int64_t sample_rate_,
00052     int64_t freq_,
00053     const std::string &rf_port_select_,
00054     const std::string &rf_filter_,
00055     const std::string &gain_mode_rx0_,
00056     const std::string &gain_mode_rx1_,
00057     double rf_gain_rx0_,
00058     double rf_gain_rx1_,
00059     bool enable_ch0,
00060     bool enable_ch1,
00061     int64_t freq_2ch,
00062     bool ppsmode_,
00063     bool customsamplesize_,
00064     const std::string &fe_ip_,
00065     int fe_ctlport_,
00066     int ssize_,
00067     int bshift_,
00068     bool spattern_,
00069     double lo_attenuation_db_,
00070     bool high_side_lo_,
00071     int tx_lo_channel_);
00072
00073 /*!
00074 * \brief This class implements conversion between Labsat 2, 3 and 3 Wideband
00075 * formats to gr_complex
00076 */
00077 class ad936x_iio_source : public gr::block
00078 {
00079 public:
00080     ~ad936x_iio_source();
00081
00082     ///! start the sample transmission
00083     bool start();
00084     ///! stop the sample transmission
00085     bool stop();
00086
00087     int general_work(int noutput_items,
00088         gr_vector_int &ninput_items,
00089         gr_vector_const_void_star &input_items,
00090         gr_vector_void_star &output_items);
00091
00092 private:
00093     friend ad936x_iio_source_sptr ad936x_iio_make_source_sptr(
00094         const std::string &pluto_uri_,
00095         const std::string &board_type_,
00096         int64_t bandwidth_,
00097         int64_t sample_rate_,
00098         int64_t freq_,
00099         const std::string &rf_port_select_,
00100         const std::string &rf_filter_,
00101         const std::string &gain_mode_rx0_,
00102         const std::string &gain_mode_rx1_,
00103         double rf_gain_rx0_,
00104         double rf_gain_rx1_,
00105         bool enable_ch0,
00106         bool enable_ch1,
00107         int64_t freq_2ch,
00108         bool ppsmode_,
00109         bool customsamplesize_,
00110         const std::string &fe_ip_,
00111         int fe_ctlport_,
00112         int ssize_,
00113         int bshift_,
00114         bool spattern_,
00115         double lo_attenuation_db_,
00116         bool high_side_lo_,
00117         int tx_lo_channel_);
00118
00119     ad936x_iio_source(
00120         const std::string &pluto_uri_,
00121         const std::string &board_type_,
00122         int64_t bandwidth_,
00123         int64_t sample_rate_,
00124         int64_t freq_,
00125         const std::string &rf_port_select_,

```

```

00126         const std::string &rf_filter,
00127         const std::string &gain_mode_rx0_,
00128         const std::string &gain_mode_rx1_,
00129         double rf_gain_rx0_,
00130         double rf_gain_rx1_,
00131         bool enable_ch0,
00132         bool enable_ch1,
00133         int64_t freq_2ch,
00134         bool ppsmode_,
00135         bool customsamplesize_,
00136         const std::string &fe_ip_,
00137         int fe_ctlport_,
00138         int ssize_,
00139         int bshift_,
00140         bool spattern_,
00141         double lo_attenuation_db_,
00142         bool high_side_lo_,
00143         int tx_lo_channel_);
00144
00145     void ad9361_channel_demux_to_buffer(ad936x_iio_samples *samples_in, int nchannels,
gr_vector_void_star &output_items);
00146     void ad9361_channel_demux_and_record(ad936x_iio_samples *samples_in, int nchannels,
std::vector<std::fstream> *files_out);
00147
00148     std::thread pps_rx_thread;
00149     std::unique_ptr<ad936x_iio_custom> ad936x_custom;
00150     std::shared_ptr<pps_tcp_rx> pps_rx;
00151     std::shared_ptr<Concurrent_Queue<PpsSamplestamp>> ppsqueue;
00152
00153     std::vector<std::fstream> samplesfile;
00154 };
00155
00156
00157 /** \} */
00158 /** \} */
00159 #endif // GNSS_SDR_AD936X_IIO_SOURCE_H

```

13.395 fifo_reader.h File Reference

Header file to retrieve samples from an existing Unix FIFO.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_block.h>
#include <array>
#include <fstream>
#include <string>

```

Classes

- class [FifoReader](#)

13.395.1 Detailed Description

Header file to retrieve samples from an existing Unix FIFO.

Author

Malte Lenhart, 2021. [malte.lenhart\(at\)mailbox.org](mailto:malte.lenhart(at)mailbox.org)

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Definition in file [fifo_reader.h](#).

13.396 fifo_reader.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file fifo_reader.h
00003  *
00004  * \brief Header file to retrieve samples from an existing Unix FIFO
00005  * \author Malte Lenhart, 2021. malte.lenhart\(at\)mailbox.org
00006  *

```

```

00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_FIFO_READER_H_
00019 #define GNSS_SDR_FIFO_READER_H_
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_block.h>
00023 #include <array>
00024 #include <fstream> // std::ifstream
00025 #include <string>
00026
00027 /** \addtogroup Signal_Source
00028  * \{ */
00029 /** \addtogroup Signal_Source_gnuradio_blocks
00030  * \{ */
00031 class FifoReader : virtual public gr::sync_block
00032 {
00033 public:
00034     /// \brief static function to create a class instance
00035     using sptr = gnss_shared_ptr<FifoReader>;
00036     static sptr make(const std::string &file_name, const std::string &sample_type);
00037
00038     ~FifoReader() = default;
00039
00040     /// initialize istream resource for FIFO
00041     bool start();
00042
00043     /// gnu radio work cycle function
00044     int work(int noutput_items,
00045             gr_vector_const_void_star &input_items,
00046             gr_vector_void_star &output_items);
00047 private:
00048     /// \brief Constructor
00049     /// private constructor called by function make
00050     /// (gr handles this with public and private header pair)
00051     FifoReader(const std::string &file_name, const std::string &sample_type);
00052
00053     size_t read_gr_complex(int noutput_items, gr_vector_void_star &output_items);
00054
00055     /// function to read data out of FIFO which is stored as interleaved I/Q stream.
00056     /// template argument determines sample_type
00057     /// Note: template definition necessary in header file
00058     /// See also:
00059     https://stackoverflow.com/questions/495021/why-can-templates-only-be-implemented-in-the-header-file
00060     template <typename Type>
00061     size_t read_interleaved(int noutput_items, gr_vector_void_star &output_items)
00062     {
00063         size_t items_retrieved = 0;
00064         for (int n = 0; n < noutput_items; n++)
00065         {
00066             // TODO: try if performance increases if we copy larger chunks to vector.
00067             // how to read from stream: https://en.cppreference.com/w/cpp/io/basic\_ifstream
00068             std::array<char, 2 * sizeof(Type)> buffer;
00069             fifo_.read(reinterpret_cast<char *>(buffer.data()), buffer.size());
00070             if (fifo_.good())
00071             {
00072                 auto real = reinterpret_cast<Type const *>(&buffer[0]);
00073                 auto imag = reinterpret_cast<Type const *>(&buffer[sizeof(Type)]);
00074                 static_cast<gr_complex *>(output_items[0])[n] = gr_complex(*real, *imag);
00075                 items_retrieved++;
00076             }
00077             else if (fifo_.eof())
00078             {
00079                 fifo_.clear();
00080                 break;
00081             }
00082             else
00083             {
00084                 fifo_error_output();
00085                 break;
00086             }
00087         }
00088         return items_retrieved;
00089     }
00090
00091     /// this function moves logging output from this header into the source file
00092     /// thereby eliminating the need to include glog/logging.h in this header

```

```

00093     void fifo_error_output() const;
00094
00095     const std::string file_name_;
00096     const std::string sample_type_;
00097     std::ifstream fifo_;
00098 };
00099
00100 /** \} */
00101 /** \} */
00102 #endif /* GNSS_SDR_FIFO_READER_H_ */

```

13.397 gr_complex_ip_packet_source.h File Reference

Receives ip frames containing samples in UDP frame encapsulation using a high performance packet capture library (libpcap)

```

#include "gnss_block_interface.h"
#include <boost/thread.hpp>
#include <gnuradio/sync_block.h>
#include <arpa/inet.h>
#include <net/ethernet.h>
#include <net/if.h>
#include <netinet/if_ether.h>
#include <pcap.h>
#include <string>
#include <sys/ioctl.h>

```

Classes

- class [Gr_Complex_Ip_Packet_Source](#)

13.397.1 Detailed Description

Receives ip frames containing samples in UDP frame encapsulation using a high performance packet capture library (libpcap)

Author

Javier Arribas jarribas (at) cttc.es

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 Definition in file [gr_complex_ip_packet_source.h](#).

13.398 gr_complex_ip_packet_source.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gr_complex_ip_packet_source.h
00003  *
00004  * \brief Receives ip frames containing samples in UDP frame encapsulation
00005  * using a high performance packet capture library (libpcap)
00006  * \author Javier Arribas jarribas (at) cttc.es
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019
00020 #ifndef GNSS_SDR_GR_COMPLEX_IP_PACKET_SOURCE_H
00021 #define GNSS_SDR_GR_COMPLEX_IP_PACKET_SOURCE_H
00022

```



```

00023 #include "gnss_block_interface.h"
00024 #include <boost/thread.hpp>
00025 #include <gnuradio/sync_block.h>
00026 #include <arpa/inet.h>
00027 #include <net/ethernet.h>
00028 #include <net/if.h>
00029 #include <netinet/if_ether.h>
00030 #include <pcap.h>
00031 #include <string>
00032 #include <sys/ioctl.h>
00033
00034 /** \addtogroup Signal_Source
00035  * \{ */
00036 /** \addtogroup Signal_Source_gnuradio_blocks signal_source_gr_blocks
00037  * GNU Radio blocks for signal sources.
00038  * \{ */
00039
00040
00041 class Gr_Complex_Ip_Packet_Source : virtual public gr::sync_block
00042 {
00043 public:
00044     using sptr = gnss_shared_ptr<Gr_Complex_Ip_Packet_Source>;
00045     static sptr make(std::string src_device,
00046                     const std::string &origin_address,
00047                     int udp_port,
00048                     int udp_packet_size,
00049                     int n_baseband_channels,
00050                     const std::string &wire_sample_type,
00051                     size_t item_size,
00052                     bool IQ_swap_);
00053     Gr_Complex_Ip_Packet_Source(std::string src_device,
00054                                 const std::string &origin_address,
00055                                 int udp_port,
00056                                 int udp_packet_size,
00057                                 int n_baseband_channels,
00058                                 const std::string &wire_sample_type,
00059                                 size_t item_size,
00060                                 bool IQ_swap_);
00061     ~Gr_Complex_Ip_Packet_Source();
00062
00063     // Called by gnuradio to enable drivers, etc for i/o devices.
00064     bool start();
00065
00066     // Called by gnuradio to disable drivers, etc for i/o devices.
00067     bool stop();
00068
00069     // Where all the action really happens
00070     int work(int noutput_items,
00071             gr_vector_const_void_star &input_items,
00072             gr_vector_void_star &output_items);
00073
00074 private:
00075     void demux_samples(const gr_vector_void_star &output_items, int num_samples_readed);
00076     void my_pcap_loop_thread(pcap_t *pcap_handle);
00077     void pcap_callback(u_char *args, const struct pcap_pkthdr *pkthdr, const u_char *packet);
00078     static void static_pcap_callback(u_char *args, const struct pcap_pkthdr *pkthdr, const u_char
00079 *packet);
00080     /*
00081      * Opens the ethernet device using libpcap raw capture mode
00082      * If any of these fail, the function returns the error and exits.
00083      */
00084     bool open();
00085
00086     boost::thread *d_pcap_thread;
00087     // boost::mutex d_mutex;
00088     struct sockaddr_in si_me{};
00089     std::string d_src_device;
00090     std::string d_origin_address;
00091     pcap_t *descr; // ethernet pcap device descriptor
00092     char *fifo_buff;
00093     int fifo_read_ptr;
00094     int fifo_write_ptr;
00095     int fifo_items;
00096     int d_sock_raw;
00097     int d_udp_port;
00098     int d_n_baseband_channels;
00099     int d_wire_sample_type;
00100     float d_bytes_per_sample;
00101     bool d_IQ_swap;
00102 };
00103
00104 /** \} */
00105 /** \} */
00106 #endif // GNSS_SDR_GR_COMPLEX_IP_PACKET_SOURCE_H

```

13.399 ion_gsms.h File Reference

GNU Radio block that reads a Block from a file following ION's GNSS-SDR metadata standard.

```
#include "gnss_block_interface.h"
#include "gnss_sdr_filesystem.h"
#include "ion_gsms_chunk_data.h"
#include <gnuradio/block.h>
#include <gnuradio/sync_block.h>
#include <cstdint>
#include <fstream>
#include <memory>
#include <string>
#include <vector>
```

Classes

- class [IONGSMSFileSource](#)

13.399.1 Detailed Description

GNU Radio block that reads a Block from a file following ION's GNSS-SDR metadata standard.

Author

Víctor Castillo Agüero, 2024. victorcastilloaguero(at)gmail.com

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 Definition in file [ion_gsms.h](#).

13.400 ion_gsms.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file ion_gsms.h
00003  * \brief GNU Radio block that reads a Block from a file following ION's GNSS-SDR metadata standard
00004  * \author Víctor Castillo Agüero, 2024. victorcastilloaguero(at)gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_ION_GSMS_H
00018 #define GNSS_SDR_ION_GSMS_H
00019
00020 #include "gnss_block_interface.h"
00021 #include "gnss_sdr_filesystem.h"
00022 #include "ion_gsms_chunk_data.h"
00023 #include <gnuradio/block.h>
00024 #include <gnuradio/sync_block.h>
00025 #include <cstdint>
00026 #include <fstream>
00027 #include <memory>
00028 #include <string>
00029 #include <vector>
00030
00031 /** \addtogroup Signal_Source
00032  * \{ */
00033 /** \addtogroup Signal_Source_gnuradio_blocks
00034  * \{ */
00035
00036 class IONGSMSFileSource : public gr::sync_block
00037 {
00038 public:
```

```

00039     using sptr = gnss_shared_ptr<IONGSMSFileSource>;
00040
00041     IONGSMSFileSource(
00042         const fs::path& metadata_filepath,
00043         const GnssMetadata::File& file,
00044         const GnssMetadata::Block& block,
00045         const std::vector<std::string>& stream_ids);
00046
00047     int work(
00048         int noutput_items,
00049         gr_vector_const_void_star& input_items,
00050         gr_vector_void_star& output_items) override;
00051
00052     std::size_t output_stream_count() const;
00053     std::size_t output_stream_item_size(std::size_t stream_index) const;
00054     std::size_t output_stream_total_sample_count(std::size_t stream_index) const;
00055
00056 private:
00057     static gr::io_signature::sptr make_output_signature(const GnssMetadata::Block& block, const
std::vector<std::string>& stream_ids);
00058
00059     std::ifstream file_stream_;
00060     std::vector<char> io_buffer_;
00061     std::size_t io_buffer_offset_;
00062     std::vector<int> items_produced_;
00063     std::size_t output_stream_count_;
00064     std::vector<std::size_t> output_stream_item_sizes_;
00065     std::vector<std::size_t> output_stream_item_rates_;
00066     std::vector<std::size_t> output_stream_total_sample_counts_;
00067     std::size_t maximum_item_rate_;
00068     std::vector<std::shared_ptr<IONGSMSChunkData>> chunk_data_;
00069     std::size_t chunk_cycle_length_;
00070 };
00071
00072 /** \} */
00073 /** \} */
00074 #endif // GNSS_SDR_ION_GSMS_H

```

13.401 labsat23_source.h File Reference

Unpacks capture files in the LabSat 2 (ls2), LabSat 3 (ls3), LabSat 3 Wideband (LS3W), and Labsat 4 (ls4) formats.

```

#include "concurrent_queue.h"
#include "gnss_block_interface.h"
#include <gnuradio/block.h>
#include <pmt/pmt.h>
#include <cstring>
#include <stdint>
#include <fstream>
#include <map>
#include <string>
#include <utility>
#include <vector>

```

Classes

- class [labsat23_source](#)

This class implements conversion between Labsat 2, 3 and 3 Wideband formats to gr_complex.

Typedefs

- using [labsat23_source_sptr](#) = gnss_shared_ptr<[labsat23_source](#)>

Functions

- labsat23_source_sptr [labsat23_make_source_sptr](#) (const char *signal_file_basename, const std::vector<int> &channel_selector, [Concurrent_Queue](#)<pmt::pmt_t> *queue, bool digital_io_enabled, double seconds_to_skip)

13.401.1 Detailed Description

Unpacks capture files in the LabSat 2 (ls2), LabSat 3 (ls3), LabSat 3 Wideband (LS3W), and Labsat 4 (ls4) formats.

Author

Javier Arribas jarribas (at) cttc.es Mathieu Favreau favreau.mathieu (at) hotmail.com

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Definition in file [labsat23_source.h](#).

13.402 labsat23_source.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file labsat23_source.h
00003  *
00004  * \brief Unpacks capture files in the LabSat 2 (ls2), LabSat 3 (ls3), LabSat 3
00005  * Wideband (LS3W), and Labsat 4 (ls4) formats.
00006  * \author Javier Arribas jarribas (at) cttc.es
00007  *          Mathieu Favreau favreau.mathieu (at) hotmail.com
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2025 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_LABSAT23_SOURCE_H
00021 #define GNSS_SDR_LABSAT23_SOURCE_H
00022
00023 #include "concurrent_queue.h"
00024 #include "gnss_block_interface.h"
00025 #include <gnuradio/block.h>
00026 #include <pmt/pmt.h>
00027 #include <cstdint>
00028 #include <cstdint>
00029 #include <fstream>
00030 #include <map>
00031 #include <string>
00032 #include <utility>
00033 #include <vector>
00034
00035 /** \addtogroup Signal_Source
00036  * \{ */
00037 /** \addtogroup Signal_Source_gnuradio_blocks
00038  * \{ */
00039
00040
00041 class labsat23_source;
00042
00043 using labsat23_source_sptr = gnss_shared_ptr<labsat23_source>;
00044
00045 labsat23_source_sptr labsat23_make_source_sptr(
00046     const char *signal_file_basename,
00047     const std::vector<int> &channel_selector,
00048     Concurrent_Queue<pmt::pmt_t> *queue,
00049     bool digital_io_enabled,
00050     double seconds_to_skip);
00051
00052 /*!
00053  * \brief This class implements conversion between Labsat 2, 3 and 3 Wideband
00054  * formats to gr_complex
00055  */
00056 class labsat23_source : public gr::block
00057 {
00058 public:
00059     ~labsat23_source();
00060
00061     int general_work(int noutput_items,
00062         gr_vector_int &ninput_items,
00063         gr_vector_const_void_star &input_items,
00064         gr_vector_void_star &output_items);
00065
00066 private:
00067     friend labsat23_source_sptr labsat23_make_source_sptr(
```

```

00068     const char *signal_file_basename,
00069     const std::vector<int> &channel_selector,
00070     Concurrent_Queue<pmt::pmt_t> *queue,
00071     bool digital_io_enabled,
00072     double seconds_to_skip);
00073
00074     labsat23_source(const char *signal_file_basename,
00075     const std::vector<int> &channel_selector,
00076     Concurrent_Queue<pmt::pmt_t> *queue,
00077     bool digital_io_enabled,
00078     double seconds_to_skip);
00079
00080     std::string generate_filename();
00081
00082     int parse_header();
00083     int read_ls3w_ini(const std::string &filename);
00084     int number_of_samples_per_ls3w_register() const;
00085
00086     void decode_samples_one_channel(int16_t input_short, gr_complex *out, int type);
00087     void decode_ls3w_register(uint64_t input, std::vector<gr_complex *> &out, std::size_t
00088     output_pointer) const;
00089     int parse_ls23_data(int noutput_items, std::vector<gr_complex *> out);
00090     int parse_ls3w_data(int noutput_items, std::vector<gr_complex *> out);
00091     int parse_ls4_data(int noutput_items, std::vector<gr_complex *> out);
00092     bool read_ls4_data();
00093
00094     std::ifstream binary_input_file;
00095     std::string d_signal_file_basename;
00096     Concurrent_Queue<pmt::pmt_t> *d_queue;
00097     std::vector<int> d_channel_selector_config;
00098     int d_current_file_number;
00099     uint8_t d_labsat_version;
00100     uint8_t d_channel_selector;
00101     uint8_t d_ref_clock;
00102     uint8_t d_bits_per_sample;
00103     bool d_header_parsed;
00104
00105     // Data members for Labsat 3 Wideband
00106     std::string d_ls3w_OSC;
00107     std::vector<int> d_ls3w_selected_channel_offset;
00108     int64_t d_ls3w_SMP{};
00109     int32_t d_ls3w_QUA{};
00110     int32_t d_ls3w_CHN{};
00111     int32_t d_ls3w_SFT{};
00112     int d_ls3w_spare_bits{};
00113     int d_ls3w_samples_per_register{};
00114     bool d_is_ls3w = false;
00115     bool d_is_ls4 = false;
00116     bool d_ls3w_digital_io_enabled = false;
00117
00118     // Data members for Labsat 4
00119     int32_t d_ls4_BW_MAX{0};
00120     int32_t d_number_sample_per_output{0};
00121     int32_t d_number_register_per_output{0};
00122     uint64_t d_read_index{0};
00123
00124     struct ChannelState
00125     {
00126         std::string identifier;
00127         int32_t center_freq{0};
00128         int32_t bandwidth{0};
00129         int32_t bw_div{0};
00130         int32_t buff_size{0};
00131         int32_t number_sample_per_output{0};
00132         uint64_t data_index{0};
00133         std::vector<uint64_t> data{};
00134
00135         ChannelState(const std::string &id) : identifier(id) {}
00136     };
00137
00138     std::map<int32_t, ChannelState> d_channel_map{
00139         std::make_pair(1, ChannelState{"A"}), std::make_pair(2, ChannelState{"B"}), std::make_pair(3,
00140         ChannelState{"C"})};
00141
00142     /** \} */
00143     /** \} */
00144 #endif // GNSS_SDR_LABSAT23_SOURCE_H

```

13.403 rtl_tcp_signal_source_c.h File Reference

Interface of an rtl_tcp signal source reader.

```
#include "gnss_block_interface.h"
#include "rtl_tcp_dongle_info.h"
#include <boost/array.hpp>
#include <boost/asio.hpp>
#include <boost/circular_buffer.hpp>
#include <boost/thread/condition.hpp>
#include <boost/thread/mutex.hpp>
#include <gnuradio/sync_block.h>
#include <stdint>
#include <string>
#include <vector>
```

Classes

- class [rtl_tcp_signal_source_c](#)

This class reads interleaved I/Q samples from an rtl_tcp server and outputs complex types.

Typedefs

- using [rtl_tcp_signal_source_c_sptr](#) = `gnss_shared_ptr<rtl_tcp_signal_source_c>`
- using [b_io_context](#) = `boost::asio::io_service`

Functions

- `rtl_tcp_signal_source_c_sptr rtl_tcp_make_signal_source_c (const std::string &address, int16_t port, bool flip_iq=false)`

13.403.1 Detailed Description

Interface of an rtl_tcp signal source reader.

Author

Anthony Arnold, 2015. anthony.arnold@uqconnect.edu.au

The implementation of this block is a combination of various helpful sources. The data format and command structure is taken from the original Osmocom `rtl_tcp_source_f` (<https://git.osmocom.org/gr-osmosdr>). The asynchronous reading code comes from the examples provides by Boost.Asio and the bounded buffer producer-consumer solution is taken from the Boost.CircularBuffer examples (<https://www.boost.org/>).

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Definition in file [rtl_tcp_signal_source_c.h](#).

13.404 rtl_tcp_signal_source_c.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtl_tcp_signal_source_c.h
00003  * \brief Interface of an rtl_tcp signal source reader.
00004  * \author Anthony Arnold, 2015. anthony.arnold@uqconnect.edu.au
00005  *
00006  * The implementation of this block is a combination of various helpful
00007  * sources. The data format and command structure is taken from the
00008  * original Osmocom rtl_tcp_source_f (https://git.osmocom.org/gr-osmosdr).
00009  * The asynchronous reading code comes from the examples provides
00010  * by Boost.Asio and the bounded buffer producer-consumer solution is
00011  * taken from the Boost.CircularBuffer examples (https://www.boost.org/).
00012  *
00013  * -----
00014  *
00015  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00016  * This file is part of GNSS-SDR.
00017  *
00018  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
```

```

00019  * SPDX-License-Identifier: GPL-3.0-or-later
00020  *
00021  * -----
00022  */
00023
00024 #ifndef GNSS_SDR_RTL_TCP_SIGNAL_SOURCE_C_H
00025 #define GNSS_SDR_RTL_TCP_SIGNAL_SOURCE_C_H
00026
00027 #include "gnss_block_interface.h"
00028 #include "rtl_tcp_dongle_info.h"
00029 #include <boost/array.hpp>
00030 #include <boost/asio.hpp>
00031 #include <boost/circular_buffer.hpp>
00032 #include <boost/thread/condition.hpp>
00033 #include <boost/thread/mutex.hpp>
00034 #include <gnuradio/sync_block.h>
00035 #include <stdint>
00036 #include <string>
00037 #include <vector>
00038
00039
00040 /** \addtogroup Signal_Source
00041  * \{ */
00042 /** \addtogroup Signal_Source_gnuradio_blocks
00043  * \{ */
00044
00045
00046 class rtl_tcp_signal_source_c;
00047
00048 using rtl_tcp_signal_source_c_sptr = gnss_shared_ptr<rtl_tcp_signal_source_c>;
00049
00050 #if USE_BOOST_ASIO_IO_CONTEXT
00051 using b_io_context = boost::asio::io_context;
00052 #else
00053 using b_io_context = boost::asio::io_service;
00054 #endif
00055
00056 rtl_tcp_signal_source_c_sptr
00057 rtl_tcp_make_signal_source_c(const std::string &address,
00058     int16_t port,
00059     bool flip_iq = false);
00060
00061 /*!
00062  * \brief This class reads interleaved I/Q samples
00063  * from an rtl_tcp server and outputs complex types.
00064  */
00065 class rtl_tcp_signal_source_c : public gr::sync_block
00066 {
00067 public:
00068     ~rtl_tcp_signal_source_c();
00069
00070     int work(int noutput_items,
00071         gr_vector_const_void_star &input_items,
00072         gr_vector_void_star &output_items);
00073
00074     void set_frequency(int frequency);
00075     void set_sample_rate(int sample_rate);
00076     void set_agc_mode(bool agc);
00077     void set_gain(int gain);
00078     void set_if_gain(int gain);
00079
00080 private:
00081     friend rtl_tcp_signal_source_c_sptr
00082     rtl_tcp_make_signal_source_c(const std::string &address,
00083         int16_t port,
00084         bool flip_iq);
00085
00086     rtl_tcp_signal_source_c(const std::string &address,
00087         int16_t port,
00088         bool flip_iq);
00089
00090     // async read callback
00091     void handle_read(const boost::system::error_code &ec,
00092         size_t bytes_transferred);
00093
00094     inline bool not_full() const
00095     {
00096         return unread_ < buffer_.capacity();
00097     }
00098
00099     inline bool not_empty() const
00100     {
00101         return unread_ > 0 || io_context_.stopped();
00102     }
00103
00104     boost::circular_buffer_space_optimized<float> buffer_;
00105     // producer-consumer helpers

```

```

00106     boost::mutex mutex_;
00107     boost::condition not_full_;
00108     boost::condition not_empty_;
00109
00110     // lookup for scaling data
00111     boost::array<float, 0xff> lookup_{};
00112
00113     // IO members
00114     b_io_context io_context_;
00115     boost::asio::ip::tcp::socket socket_;
00116     std::vector<unsigned char> data_;
00117
00118     Rtl_Tcp_Dongle_Info info_;
00119     size_t unread_;
00120     bool flip_iq_;
00121 };
00122
00123
00124 /** \} */
00125 /** \} */
00126 #endif // GNSS_SDR_RTL_TCP_SIGNAL_SOURCE_C_H

```

13.405 unpack_2bit_samples.h File Reference

Unpacks 2 bit samples samples may be packed in any of the following ways: 1) Into bytes [item == byte] 1a) Big endian ordering within the byte 1b) Little endian ordering within the byte 2) Into shorts [item == short] 2a) Big endian ordering of bytes, big endian within the byte 2b) Big endian ordering of bytes, little endian within the byte 2c) Little endian ordering of bytes, big endian within the byte 2d) Little endian ordering of bytes, little endian within the byte.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_interpolator.h>
#include <stdint>
#include <vector>

```

Classes

- class [unpack_2bit_samples](#)

This class takes 2 bit samples that have been packed into bytes or shorts as input and generates a byte for each sample. It generates eight times as much data as is input (every two bits become 16 bits)

Typedefs

- using [unpack_2bit_samples_sptr](#) = `gnss_shared_ptr<unpack_2bit_samples>`

Functions

- `unpack_2bit_samples_sptr make_unpack_2bit_samples (bool big_endian_bytes, size_t item_size, bool big_endian_items, bool reverse_interleaving=false)`

13.405.1 Detailed Description

Unpacks 2 bit samples samples may be packed in any of the following ways: 1) Into bytes [item == byte] 1a) Big endian ordering within the byte 1b) Little endian ordering within the byte 2) Into shorts [item == short] 2a) Big endian ordering of bytes, big endian within the byte 2b) Big endian ordering of bytes, little endian within the byte 2c) Little endian ordering of bytes, big endian within the byte 2d) Little endian ordering of bytes, little endian within the byte.

Within a byte the two possibilities look like this: 7 6 5 4 3 2 1 0 : Bit number $x_{n,1}$ $x_{n,0}$ $x_{n+1,1}$ $x_{n+1,0}$ $x_{n+2,1}$ $x_{n+2,0}$ $x_{n+3,1}$ $x_{n+3,0}$: Little endian $x_{n+3,1}$ $x_{n+3,0}$ $x_{n+2,1}$ $x_{n+2,0}$ $x_{n+1,1}$ $x_{n+1,0}$ $x_{n,1}$ $x_{n,0}$: Big Endian

For a short (`uint16_t`) the bytes are either transmitted as follows:

1 0 : Byte number Byte_n Byte_{n+1} : Little endian Byte_{n+1} Byte_n : Bit endian

The two bit values are assumed to have the following mapping:

x_1 x_0 Value 0 0 +1 0 1 +3 1 0 -3 1 1 -1

Letting x denote the two's complement interpretation of x_1 x_0 , then:

Value = 2*x + 1

We want to output the data in the order:

Value_0, Value_1, Value_2, ..., Value_n, Value_n+1, Value_n+2, ...

Author

Cillian O'Driscoll cillian.odriscoll (at) gmail . com

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Definition in file [unpack_2bit_samples.h](#).

13.406 unpack_2bit_samples.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file unpack_2bit_samples.h
00003  *
00004  * \brief Unpacks 2 bit samples
00005  * samples may be packed in any of the following ways:
00006  * 1) Into bytes [ item == byte ]
00007  *     1a) Big endian ordering within the byte
00008  *     1b) Little endian ordering within the byte
00009  * 2) Into shorts [ item == short ]
00010  *     2a) Big endian ordering of bytes, big endian within the byte
00011  *     2b) Big endian ordering of bytes, little endian within the byte
00012  *     2c) Little endian ordering of bytes, big endian within the byte
00013  *     2d) Little endian ordering of bytes, little endian within the byte
00014  *
00015  * Within a byte the two possibilities look like this:
00016  *   7       6       5       4       3       2       1       0       : Bit number
00017  * x_n,1   x_n,0   x_n+1,1 x_n+1,0 x_n+2,1 x_n+2,0 x_n+3,1 x_n+3,0 : Little endian
00018  * x_n+3,1 x_n+3,0 x_n+2,1 x_n+2,0 x_n+1,1 x_n+1,0 x_n,1   x_n,0   : Big Endian
00019  *
00020  * For a short (uint16_t) the bytes are either transmitted as follows:
00021  *
00022  *   1       0       : Byte number
00023  * Byte_n   Byte_n+1 : Little endian
00024  * Byte_n+1 Byte_n   : Bit endian
00025  *
00026  * The two bit values are assumed to have the following mapping:
00027  *
00028  * x_1   x_0   Value
00029  * 0     0     +1
00030  * 0     1     +3
00031  * 1     0     -3
00032  * 1     1     -1
00033  *
00034  * Letting x denote the two's complement interpretation of x_1 x_0, then:
00035  *
00036  * Value = 2*x + 1
00037  *
00038  * We want to output the data in the order:
00039  *
00040  * Value_0, Value_1, Value_2, ..., Value_n, Value_n+1, Value_n+2, ...
00041  *
00042  * \author Cillian O'Driscoll cillian.odriscoll (at) gmail . com
00043  *
00044  * -----
00045  *
00046  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00047  * This file is part of GNSS-SDR.
00048  *
00049  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00050  * SPDX-License-Identifier: GPL-3.0-or-later
00051  *
00052  * -----
00053  */
00054
00055 #ifndef GNSS_SDR_UNPACK_2BIT_SAMPLES_H
00056 #define GNSS_SDR_UNPACK_2BIT_SAMPLES_H
00057
00058 #include "gnss_block_interface.h"
00059 #include <gnuradio/sync_interpolator.h>
00060 #include <stdint>
00061 #include <vector>
00062
00063 /** \addtogroup Signal_Source
00064  * \{ */
00065 /** \addtogroup Signal_Source_gnuradio_blocks
00066  * \{ */

```

```

00067
00068
00069 class unpack_2bit_samples;
00070
00071 using unpack_2bit_samples_sptr = gnss_shared_ptr<unpack_2bit_samples>;
00072
00073 unpack_2bit_samples_sptr make_unpack_2bit_samples(
00074     bool big_endian_bytes,
00075     size_t item_size,
00076     bool big_endian_items,
00077     bool reverse_interleaving = false);
00078
00079 /*!
00080 * \brief This class takes 2 bit samples that have been packed into bytes or
00081 * shorts as input and generates a byte for each sample. It generates eight
00082 * times as much data as is input (every two bits become 16 bits)
00083 */
00084 class unpack_2bit_samples : public gr::sync_interpolator
00085 {
00086 public:
00087     ~unpack_2bit_samples() = default;
00088
00089     unpack_2bit_samples(bool big_endian_bytes,
00090         size_t item_size,
00091         bool big_endian_items,
00092         bool reverse_interleaving);
00093
00094     int work(int noutput_items,
00095         gr_vector_const_void_star &input_items,
00096         gr_vector_void_star &output_items);
00097
00098 private:
00099     friend unpack_2bit_samples_sptr make_unpack_2bit_samples_sptr(
00100         bool big_endian_bytes,
00101         size_t item_size,
00102         bool big_endian_items,
00103         bool reverse_interleaving);
00104
00105     std::vector<int8_t> work_buffer_;
00106     size_t item_size_;
00107     bool big_endian_bytes_;
00108     bool big_endian_items_;
00109     bool swap_endian_items_;
00110     bool swap_endian_bytes_;
00111     bool reverse_interleaving_;
00112 };
00113
00114
00115 /** \} */
00116 /** \} */
00117 #endif // GNSS_SDR_UNPACK_2BIT_SAMPLES_H

```

13.407 unpack_byte_2bit_cpx_samples.h File Reference

Unpacks byte samples to 2 bits complex samples. Packing Order Most Significant Nibble - Sample n Least Significant Nibble - Sample n+1 Packing order in Nibble Q1 Q0 I1 I0.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_interpolator.h>

```

Classes

- class [unpack_byte_2bit_cpx_samples](#)

This class implements conversion between byte packet samples to 2bit_cpx samples 1 byte = 2 x complex 2bit I, + 2bit Q samples.

Typedefs

- using [unpack_byte_2bit_cpx_samples_sptr](#) = gnss_shared_ptr<[unpack_byte_2bit_cpx_samples](#)>

Functions

- [unpack_byte_2bit_cpx_samples_sptr make_unpack_byte_2bit_cpx_samples\(\)](#)

13.407.1 Detailed Description

Unpacks byte samples to 2 bits complex samples. Packing Order Most Significant Nibble - Sample n Least Significant Nibble - Sample n+1 Packing order in Nibble Q1 Q0 I1 I0.

Author

Javier Arribas jarribas (at) cttc.es

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 Definition in file [unpack_byte_2bit_cpx_samples.h](#).

13.408 unpack_byte_2bit_cpx_samples.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file unpack_byte_2bit_cpx_samples.h
00003  *
00004  * \brief Unpacks byte samples to 2 bits complex samples.
00005  *      Packing Order
00006  *      Most Significant Nibble - Sample n
00007  *      Least Significant Nibble - Sample n+1
00008  *      Packing order in Nibble Q1 Q0 I1 I0
00009  * \author Javier Arribas jarribas (at) cttc.es
00010  *
00011  * -----
00012  *
00013  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014  * This file is part of GNSS-SDR.
00015  *
00016  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022 #ifndef GNSS_SDR_UNPACK_BYTE_2BIT_CPX_SAMPLES_H
00023 #define GNSS_SDR_UNPACK_BYTE_2BIT_CPX_SAMPLES_H
00024
00025 #include "gnss_block_interface.h"
00026 #include <gnuradio/sync_interpolator.h>
00027
00028 /** \addtogroup Signal_Source
00029  * \{ */
00030 /** \addtogroup Signal_Source_gnuradio_blocks
00031  * \{ */
00032
00033
00034 class unpack_byte_2bit_cpx_samples;
00035
00036 using unpack_byte_2bit_cpx_samples_sptr = gnss_shared_ptr<unpack_byte_2bit_cpx_samples>;
00037
00038 unpack_byte_2bit_cpx_samples_sptr make_unpack_byte_2bit_cpx_samples();
00039
00040 /*!
00041  * \brief This class implements conversion between byte packet samples to 2bit_cpx samples
00042  *      1 byte = 2 x complex 2bit I, + 2bit Q samples
00043  */
00044 class unpack_byte_2bit_cpx_samples : public gr::sync_interpolator
00045 {
00046 public:
00047     unpack_byte_2bit_cpx_samples();
00048     ~unpack_byte_2bit_cpx_samples() = default;
00049     int work(int noutput_items,
00050             gr_vector_const_void_star &input_items,
00051             gr_vector_void_star &output_items);
00052
00053 private:
00054     friend unpack_byte_2bit_cpx_samples_sptr make_unpack_byte_2bit_cpx_samples_sptr();
00055 };
00056
00057
00058 /** \} */
00059 /** \} */
00060 #endif // GNSS_SDR_UNPACK_BYTE_2BIT_CPX_SAMPLES_H
```

13.409 unpack_byte_2bit_samples.h File Reference

Unpacks byte samples to NSR 2 bits samples.

```
#include "gnss_block_interface.h"
#include <gnuradio/sync_interpolator.h>
```

Classes

- class [unpack_byte_2bit_samples](#)

This class implements conversion between byte packet samples to 2bit samples 1 byte = 4 2bit samples.

Typedefs

- using [unpack_byte_2bit_samples_sptr](#) = gnss_shared_ptr<[unpack_byte_2bit_samples](#)>

Functions

- [unpack_byte_2bit_samples_sptr](#) [make_unpack_byte_2bit_samples](#) ()

13.409.1 Detailed Description

Unpacks byte samples to NSR 2 bits samples.

Author

Javier Arribas jarribas (at) ctte.es

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Definition in file [unpack_byte_2bit_samples.h](#).

13.410 unpack_byte_2bit_samples.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file unpack_byte_2bit_samples.h
00003  *
00004  * \brief Unpacks byte samples to NSR 2 bits samples
00005  * \author Javier Arribas jarribas (at) ctte.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_UNPACK_BYTE_2BIT_SAMPLES_H
00019 #define GNSS_SDR_UNPACK_BYTE_2BIT_SAMPLES_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_interpolator.h>
00023
00024
00025 /** \addtogroup Signal_Source
00026  * \{ */
00027 /** \addtogroup Signal_Source_gnuradio_blocks
00028  * \{ */
00029
00030 class unpack_byte_2bit_samples;
00031
00032 using unpack_byte_2bit_samples_sptr = gnss_shared_ptr<unpack_byte_2bit_samples>;
00033
00034 unpack_byte_2bit_samples_sptr make_unpack_byte_2bit_samples();
00035
00036 /*!
```

```

00037  * \brief This class implements conversion between byte packet samples to 2bit samples
00038  * 1 byte = 4 2bit samples
00039  */
00040  class unpack_byte_2bit_samples : public gr::sync_interpolator
00041  {
00042  public:
00043      unpack_byte_2bit_samples();
00044      ~unpack_byte_2bit_samples() = default;
00045      int work(int noutput_items,
00046              gr_vector_const_void_star &input_items,
00047              gr_vector_void_star &output_items);
00048
00049  private:
00050      friend unpack_byte_2bit_samples_sptr make_unpack_byte_2bit_samples_sptr();
00051  };
00052
00053
00054  /** \} */
00055  /** \} */
00056  #endif // GNSS_SDR_UNPACK_BYTE_2BIT_SAMPLES_H

```

13.411 unpack_byte_4bit_samples.h File Reference

Unpacks byte samples to 4 bits samples. Packing Order Packing order in Nibble I0 I1 I2 I3 I0 I1 I2 I3.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_interpolator.h>

```

Classes

- class [unpack_byte_4bit_samples](#)

This class implements conversion between byte packet samples to 4bit_cpx samples 1 byte = 1 x complex 4bit I, + 4bit Q samples.

Typedefs

- using [unpack_byte_4bit_samples_sptr](#) = [gnss_shared_ptr](#)<[unpack_byte_4bit_samples](#)>

Functions

- [unpack_byte_4bit_samples_sptr](#) **make_unpack_byte_4bit_samples** ()

13.411.1 Detailed Description

Unpacks byte samples to 4 bits samples. Packing Order Packing order in Nibble I0 I1 I2 I3 I0 I1 I2 I3.

Author

Javier Arribas jarribas (at) cttc.es

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 Definition in file [unpack_byte_4bit_samples.h](#).

13.412 unpack_byte_4bit_samples.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file unpack_byte_4bit_samples.h
00003  *
00004  * \brief Unpacks byte samples to 4 bits samples.
00005  *      Packing Order
00006  *      Packing order in Nibble I0 I1 I2 I3 I0 I1 I2 I3
00007  * \author Javier Arribas jarribas (at) cttc.es
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.

```

```

00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_UNPACK_BYTE_4BIT_SAMPLES_H
00021 #define GNSS_SDR_UNPACK_BYTE_4BIT_SAMPLES_H
00022
00023 #include "gnss_block_interface.h"
00024 #include <gnuradio/sync_interpolator.h>
00025
00026 /** \addtogroup Signal_Source
00027  * \{ */
00028 /** \addtogroup Signal_Source_gnuradio_blocks
00029  * \{ */
00030
00031
00032 class unpack_byte_4bit_samples;
00033
00034 using unpack_byte_4bit_samples_sptr = gnss_shared_ptr<unpack_byte_4bit_samples>;
00035
00036 unpack_byte_4bit_samples_sptr make_unpack_byte_4bit_samples();
00037
00038 /*!
00039  * \brief This class implements conversion between byte packet samples to 4bit_cpx samples
00040  * 1 byte = 1 x complex 4bit I, + 4bit Q samples
00041  */
00042 class unpack_byte_4bit_samples : public gr::sync_interpolator
00043 {
00044 public:
00045     unpack_byte_4bit_samples();
00046     ~unpack_byte_4bit_samples() = default;
00047     int work(int noutput_items,
00048             gr_vector_const_void_star &input_items,
00049             gr_vector_void_star &output_items);
00050
00051 private:
00052     friend unpack_byte_4bit_samples_sptr make_unpack_byte_4bit_samples_sptr();
00053 };
00054
00055
00056 /** \} */
00057 /** \} */
00058 #endif // GNSS_SDR_UNPACK_BYTE_4BIT_SAMPLES_H

```

13.413 unpack_intspir_1bit_samples.h File Reference

Unpacks SPIR int samples to NSR 1 bit samples.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_interpolator.h>

```

Classes

- class [unpack_intspir_1bit_samples](#)

This class implements conversion between byte packet samples to 2bit samples 1 byte = 4 2bit samples.

Typedefs

- using [unpack_intspir_1bit_samples_sptr](#) = [gnss_shared_ptr](#)<[unpack_intspir_1bit_samples](#)>

Functions

- [unpack_intspir_1bit_samples_sptr](#) [make_unpack_intspir_1bit_samples](#) ()

13.413.1 Detailed Description

Unpacks SPIR int samples to NSR 1 bit samples.

Author

Fran Fabra fabra (at) ice.csic.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is not part of GNSS-SDR. Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors) SPDX-License-Identifier: GPL-3.0-or-later Definition in file [unpack_intspir_1bit_samples.h](#).

13.414 unpack_intspir_1bit_samples.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file unpack_intspir_1bit_samples.h
00003  *
00004  * \brief Unpacks SPIR int samples to NSR 1 bit samples
00005  * \author Fran Fabra fabra (at) ice.csic.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is not part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_UNPACK_INTSPIR_1BIT_SAMPLES_H
00019 #define GNSS_SDR_UNPACK_INTSPIR_1BIT_SAMPLES_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_interpolator.h>
00023
00024
00025 /** \addtogroup Signal_Source
00026  * \{ */
00027 /** \addtogroup Signal_Source_gnuradio_blocks
00028  * \{ */
00029
00030
00031 class unpack_intspir_1bit_samples;
00032
00033 using unpack_intspir_1bit_samples_sptr = gnss_shared_ptr<unpack_intspir_1bit_samples>;
00034
00035 unpack_intspir_1bit_samples_sptr make_unpack_intspir_1bit_samples();
00036
00037 /*!
00038  * \brief This class implements conversion between byte packet samples to 2bit samples
00039  * 1 byte = 4 2bit samples
00040  */
00041 class unpack_intspir_1bit_samples : public gr::sync_interpolator
00042 {
00043 public:
00044     unpack_intspir_1bit_samples();
00045     ~unpack_intspir_1bit_samples() = default;
00046     int work(int noutput_items,
00047             gr_vector_const_void_star &input_items,
00048             gr_vector_void_star &output_items);
00049 private:
00050     friend unpack_intspir_1bit_samples_sptr make_unpack_intspir_1bit_samples_sptr();
00051 };
00052
00053
00054
00055 /** \} */
00056 /** \} */
00057 #endif // GNSS_SDR_UNPACK_INTSPIR_1BIT_SAMPLES_H
```

13.415 unpack_ntlab_2bit_samples.h File Reference

Unpacks multichannel 2-bit samples into 4 real-valued floats per input byte.

```
#include "gnss_block_interface.h"
#include <gnuradio/sync_interpolator.h>
#include <stdint>
#include <vector>
```

Classes

- class [unpack_ntlab_2bit_samples](#)

This class implements conversion between byte packet multichannel samples to 2bit samples 1 byte = 4 2bit samples.

Typedefs

- using [unpack_ntlab_2bit_samples_sptr](#) = gnss_shared_ptr<[unpack_ntlab_2bit_samples](#)>

Functions

- [unpack_ntlab_2bit_samples_sptr](#) **make_unpack_ntlab_2bit_samples** (size_t item_size, int nchannels=4)

13.415.1 Detailed Description

Unpacks multichannel 2-bit samples into 4 real-valued floats per input byte.

Author

Pedro Pereira pereirapedrocp (at) gmail.com

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Definition in file [unpack_ntlab_2bit_samples.h](#).

13.416 unpack_ntlab_2bit_samples.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file unpack_ntlab_2bit_samples.h
00003  *
00004  * \brief Unpacks multichannel 2-bit samples into 4 real-valued floats
00005  *        per input byte.
00006  * \author Pedro Pereira pereirapedrocp (at) gmail.com
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_UNPACK_NTLAB_2BIT_SAMPLES_H
00020 #define GNSS_SDR_UNPACK_NTLAB_2BIT_SAMPLES_H
00021
00022 #include "gnss_block_interface.h"
00023 #include <gnuradio/sync_interpolator.h>
00024 #include <stdint>
00025 #include <vector>
00026
00027 /** \addtogroup Signal_Source
00028  *  \{ */
00029 /** \addtogroup Signal_Source_gnuradio_blocks
00030  *  \{ */
00031
00032
00033 class unpack_ntlab_2bit_samples;
00034
00035 using unpack_ntlab_2bit_samples_sptr = gnss_shared_ptr<unpack_ntlab_2bit_samples>;
00036
00037 unpack_ntlab_2bit_samples_sptr make_unpack_ntlab_2bit_samples(
00038     size_t item_size,
00039     int nchannels = 4);
00040
00041  /*!
00042  * \brief This class implements conversion between byte packet multichannel samples
00043  *        to 2bit samples 1 byte = 4 2bit samples
00044  *
00045  * Unpack each of the four 2-bit samples in the byte 'b' into four real-valued outputs.
00046  *
00047  * The NTLAB format encodes samples as sign+magnitude pairs in each byte:

```



```

00048 * bits 7-6 = [M0 S0] -> sample 0
00049 * bits 5-4 = [M1 S1] -> sample 1
00050 * bits 3-2 = [M2 S2] -> sample 2
00051 * bits 1-0 = [M3 S3] -> sample 3
00052 *
00053 * M = magnitude bit (1->|sample|=3, 0->|sample|=1)
00054 * S = sign      bit (1->positive, 0->negative)
00055 */
00056 class unpack_ntlab_2bit_samples : public gr::sync_interpolator
00057 {
00058 public:
00059     ~unpack_ntlab_2bit_samples() = default;
00060
00061     unpack_ntlab_2bit_samples(size_t item_size,
00062                             int nchannels);
00063
00064     int work(int noutput_items,
00065             gr_vector_const_void_star &input_items,
00066             gr_vector_void_star &output_items);
00067 private:
00068     static constexpr int SAMPLES_PER_BYTE = 4;
00069
00070     friend unpack_ntlab_2bit_samples_sptr make_unpack_ntlab_2bit_samples_sptr(
00071         size_t item_size,
00072         int nchannels);
00073
00074     int nchannels_;
00075 };
00076
00077
00078
00079 /** @} */
00080 /** @} */
00081 #endif // GNSS_SDR_UNPACK_NTLAB_2BIT_SAMPLES_H

```

13.417 unpack_short_byte_samples.h

```

00001 /*!
00002 * \file unpack_short_byte_samples.cc
00003 *
00004 * \brief Unpacks shorts samples to byte samples (1 short = 2 byte samples).
00005 *      Packing Order
00006 *      Packing order in Nibble IO I1
00007 * \author Javier Arribas jarribas (at) cttc.es
00008 * -----
00009 *
00010 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011 * This file is part of GNSS-SDR.
00012 *
00013 * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00014 * SPDX-License-Identifier: GPL-3.0-or-later
00015 *
00016 * -----
00017 */
00018
00019 #ifndef GNSS_SDR_UNPACK_SHORT_BYTE_SAMPLES_H
00020 #define GNSS_SDR_UNPACK_SHORT_BYTE_SAMPLES_H
00021
00022 #include "gnss_block_interface.h"
00023 #include <gnuradio/sync_interpolator.h>
00024
00025 /** \addtogroup Signal_Source
00026 * \{ */
00027 /** \addtogroup Signal_Source_gnuradio_blocks
00028 * \{ */
00029
00030
00031 class unpack_short_byte_samples;
00032
00033 using unpack_short_byte_samples_sptr = gnss_shared_ptr<unpack_short_byte_samples>;
00034
00035 unpack_short_byte_samples_sptr make_unpack_short_byte_samples();
00036
00037 /*!
00038 * \brief This class implements conversion between short packet samples to byte samples
00039 *      1 short = 2 byte samples
00040 */
00041 class unpack_short_byte_samples : public gr::sync_interpolator
00042 {
00043 public:
00044     unpack_short_byte_samples();
00045     void forecast(int noutput_items, gr_vector_int &ninput_items_required);
00046     ~unpack_short_byte_samples() = default;
00047     int work(int noutput_items,

```

```

00048         gr_vector_const_void_star &input_items,
00049         gr_vector_void_star &output_items);
00050
00051 private:
00052     friend unpack_short_byte_samples_sptr make_unpack_short_byte_samples_sptr();
00053 };
00054
00055
00056 /** \} */
00057 /** \} */
00058 #endif // GNSS_SDR_UNPACK_SHORT_BYTE_SAMPLES_H

```

13.418 unpack_spir_gss6450_samples.h File Reference

Unpacks SPIR int samples.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_interpolator.h>

```

Classes

- class [unpack_spir_gss6450_samples](#)

Typedefs

- using [unpack_spir_gss6450_samples_sptr](#) = `gnss_shared_ptr<unpack_spir_gss6450_samples>`

Functions

- `unpack_spir_gss6450_samples_sptr` **make_unpack_spir_gss6450_samples** (int adc_nbit_)

13.418.1 Detailed Description

Unpacks SPIR int samples.

Author

Antonio Ramos, antonio.ramos(at)cttc.es

Javier Arribas jarribas (at) cttc.es

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 Definition in file [unpack_spir_gss6450_samples.h](#).

13.419 unpack_spir_gss6450_samples.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file unpack_spir_gss6450_samples.h
00003  * \brief Unpacks SPIR int samples
00004  * \author Antonio Ramos, antonio.ramos(at)cttc.es
00005  * \author Javier Arribas jarribas (at) cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is not part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_UNPACK_SPIR_GSS6450_SAMPLES_H
00019 #define GNSS_SDR_UNPACK_SPIR_GSS6450_SAMPLES_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_interpolator.h>

```

```

00023
00024 /** \addtogroup Signal_Source
00025 * \{ */
00026 /** \addtogroup Signal_Source_gnuradio_blocks
00027 * \{ */
00028
00029
00030 class unpack_spir_gss6450_samples;
00031
00032 using unpack_spir_gss6450_samples_sptr = gnss_shared_ptr<unpack_spir_gss6450_samples>;
00033
00034 unpack_spir_gss6450_samples_sptr make_unpack_spir_gss6450_samples(int adc_nbit_);
00035
00036
00037 class unpack_spir_gss6450_samples : public gr::sync_interpolator
00038 {
00039 public:
00040     explicit unpack_spir_gss6450_samples(int adc_nbit);
00041     ~unpack_spir_gss6450_samples() = default;
00042     void decode_4bits_word(uint32_t input_uint32, gr_complex *out, int adc_bits_);
00043     int work(int noutput_items,
00044             gr_vector_const_void_star &input_items, gr_vector_void_star &output_items);
00045
00046 private:
00047     friend unpack_spir_gss6450_samples_sptr make_unpack_spir_gss6450_samples_sptr(int adc_nbit);
00048     int adc_bits;
00049     int samples_per_int;
00050 };
00051
00052
00053 /** \} */
00054 /** \} */
00055 #endif // GNSS_SDR_UNPACK_SPIR_GSS6450_SAMPLES_H

```

13.420 ad9361_manager.h File Reference

An Analog Devices AD9361 front-end configuration library wrapper for configure some functions via iiod link.

```

#include <iio.h>
#include <stdint>
#include <string>

```

Classes

- struct [stream_cfg](#)

Macros

- #define [FIR_BUF_SIZE](#) 8192

Enumerations

- enum [iodev](#) { [RX](#) , [TX](#) }

Functions

- void [errchk](#) (int v, const char *what)
- void [wr_ch_lll](#) (struct iio_channel *chn, const char *what, int64_t val)
- void [wr_ch_str](#) (struct iio_channel *chn, const char *what, const char *str)
- struct iio_device * [get_ad9361_phy](#) (struct iio_context *ctx)
- bool [get_ad9361_stream_dev](#) (struct iio_context *ctx, enum iodev d, struct iio_device **dev)
- bool [get_ad9361_stream_ch](#) (struct iio_context *ctx, enum iodev d, struct iio_device *dev, int chid, struct iio_channel **chn)
- bool [get_phy_chan](#) (struct iio_context *ctx, enum iodev d, int chid, struct iio_channel **chn)
- bool [get_lo_chan](#) (struct iio_context *ctx, enum iodev d, struct iio_channel **chn)
- bool [cfg_ad9361_streaming_ch](#) (struct iio_context *ctx, struct [stream_cfg](#) *cfg, enum iodev type, int chid)

- `bool config_ad9361_rx_local` (uint64_t bandwidth_, uint64_t sample_rate_, uint64_t freq0_, uint64_t freq1_↵_, const std::string &rf_port_select_, bool rx1_enable_, bool rx2_enable_, const std::string &gain_mode_↵_rx1_, const std::string &gain_mode_rx2_, double rf_gain_rx1_, double rf_gain_rx2_, bool quadrature_, bool rfdc_, bool bbdc_, std::string filter_source_, std::string filter_filename_, float Fpass_, float Fstop_)
- `bool config_ad9361_rx_remote` (const std::string &remote_host, uint64_t bandwidth_, uint64_t sample_↵_rate_, uint64_t freq_, const std::string &rf_port_select_, bool rx1_enable_, bool rx2_enable_, const std_↵_::string &gain_mode_rx1_, const std::string &gain_mode_rx2_, double rf_gain_rx1_, double rf_gain_rx2_, bool quadrature_, bool rfdc_, bool bbdc_, std::string filter_source_, std::string filter_filename_, float Fpass_, float Fstop_)
- `bool config_ad9361_lo_local` (uint64_t bandwidth_, uint64_t sample_rate_, uint64_t freq_rf_tx_hz_, double tx_attenuation_db_, int64_t freq_dds_tx_hz_, double scale_dds_dbfs_, double phase_dds_deg_)
- `bool config_ad9361_lo_remote` (const std::string &remote_host, uint64_t bandwidth_, uint64_t sample_↵_rate_, uint64_t freq_rf_tx_hz_, double tx_attenuation_db_, int64_t freq_dds_tx_hz_, double scale_dds_↵_dbfs_, double phase_dds_deg_)
- `bool ad9361_disable_lo_remote` (const std::string &remote_host)
- `bool ad9361_disable_lo_local` ()
- `bool load_fir_filter` (std::string &filter, struct iio_device *phy)
- `bool disable_ad9361_rx_local` ()
- `bool disable_ad9361_rx_remote` (const std::string &remote_host)

13.420.1 Detailed Description

An Analog Devices AD9361 front-end configuration library wrapper for configure some functions via iio link.

Author

Javier Arribas, jarribas(at)cttc.es

This file contains information taken from librtlsdr: <https://git.osmocom.org/rtl-sdr>
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 Definition in file [ad9361_manager.h](#).

13.421 ad9361_manager.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file ad9361_manager.h
00003  * \brief An Analog Devices AD9361 front-end configuration library wrapper for configure some
00004  *        functions via iio link.
00005  * \author Javier Arribas, jarribas(at)cttc.es
00006  *
00007  * This file contains information taken from librtlsdr:
00008  *   https://git.osmocom.org/rtl-sdr
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_AD9361_MANAGER_H
00021 #define GNSS_SDR_AD9361_MANAGER_H
00022
00023 #include <iio.h>
00024 #include <stdint>
00025 #include <string>
00026
00027 /** \addtogroup Signal_Source
00028  * \{ */
00029 /** \addtogroup Signal_Source_libs signal_source_libs
00030  * Library with utilities for signal sources.
00031  * \{ */
00032
00033 #define FIR_BUF_SIZE 8192

```

```

00034
00035 static const std::string RX_DEV_A = "ad9361-phy";           // one or two AD9361s are present
00036 static const std::string RX_DEV_B = "ad9361-phy-B";        // one or two AD9361s are present
00037 static const std::string RX_STREAM_DEV = "cf-ad9361-lpc";   // one AD9361 is present
00038 static const std::string RX_STREAM_DEV_A = "cf-ad9361-A";   // two AD9361s are present
00039 static const std::string RX_STREAM_DEV_B = "cf-ad9361-B";   // two AD9361s are present
00040 static const std::string TX_STREAM_DEV = "cf-ad9361-dds-core-lpc";
00041
00042 /* RX is input, TX is output */
00043 enum iodev
00044 {
00045     RX,
00046     TX
00047 };
00048
00049 /* common RX and TX streaming params */
00050 struct stream_cfg
00051 {
00052     int64_t bw_hz;           // Analog bandwidth in Hz
00053     int64_t fs_hz;          // Baseband sample rate in Hz
00054     int64_t lo_hz;          // Local oscillator frequency in Hz
00055     const char *rfport;     // Port name
00056 };
00057
00058 /* check return value of attr_write function */
00059 void errchk(int v, const char *what);
00060
00061 /* write attribute: int64_t int */
00062 void wr_ch_lli(struct iio_channel *chn, const char *what, int64_t val);
00063
00064 /* write attribute: string */
00065 void wr_ch_str(struct iio_channel *chn, const char *what, const char *str);
00066
00067 /* returns ad9361 phy device */
00068 struct iio_device *get_ad9361_phy(struct iio_context *ctx);
00069
00070 /* finds AD9361 streaming IIO devices */
00071 bool get_ad9361_stream_dev(struct iio_context *ctx, enum iodev d, struct iio_device **dev);
00072
00073 /* finds AD9361 streaming IIO channels */
00074 bool get_ad9361_stream_ch(struct iio_context *ctx, enum iodev d, struct iio_device *dev, int chid,
    struct iio_channel **chn);
00075
00076 /* finds AD9361 phy IIO configuration channel with id chid */
00077 bool get_phy_chan(struct iio_context *ctx, enum iodev d, int chid, struct iio_channel **chn);
00078
00079 /* finds AD9361 local oscillator IIO configuration channels */
00080 bool get_lo_chan(struct iio_context *ctx, enum iodev d, struct iio_channel **chn);
00081
00082 /* applies streaming configuration through IIO */
00083 bool cfg_ad9361_streaming_ch(struct iio_context *ctx, struct stream_cfg *cfg, enum iodev type, int
    chid);
00084
00085 bool config_ad9361_rx_local(uint64_t bandwidth_,
00086     uint64_t sample_rate_,
00087     uint64_t freq0_,
00088     uint64_t freq1_,
00089     const std::string &rf_port_select_,
00090     bool rx1_enable_,
00091     bool rx2_enable_,
00092     const std::string &gain_mode_rx1_,
00093     const std::string &gain_mode_rx2_,
00094     double rf_gain_rx1_,
00095     double rf_gain_rx2_,
00096     bool quadrature_,
00097     bool rfdc_,
00098     bool bbdc_,
00099     std::string filter_source_,
00100     std::string filter_filename_,
00101     float Fpass_,
00102     float Fstop_);
00103
00104 bool config_ad9361_rx_remote(const std::string &remote_host,
00105     uint64_t bandwidth_,
00106     uint64_t sample_rate_,
00107     uint64_t freq_,
00108     const std::string &rf_port_select_,
00109     bool rx1_enable_,
00110     bool rx2_enable_,
00111     const std::string &gain_mode_rx1_,
00112     const std::string &gain_mode_rx2_,
00113     double rf_gain_rx1_,
00114     double rf_gain_rx2_,
00115     bool quadrature_,
00116     bool rfdc_,
00117     bool bbdc_,
00118     std::string filter_source_,

```

```

00119     std::string filter_filename_,
00120     float Fpass_,
00121     float Fstop_);
00122
00123 bool config_ad9361_lo_local(uint64_t bandwidth_,
00124     uint64_t sample_rate_,
00125     uint64_t freq_rf_tx_hz_,
00126     double tx_attenuation_db_,
00127     int64_t freq_dds_tx_hz_,
00128     double scale_dds_dbfs_,
00129     double phase_dds_deg_);
00130
00131 bool config_ad9361_lo_remote(const std::string &remote_host,
00132     uint64_t bandwidth_,
00133     uint64_t sample_rate_,
00134     uint64_t freq_rf_tx_hz_,
00135     double tx_attenuation_db_,
00136     int64_t freq_dds_tx_hz_,
00137     double scale_dds_dbfs_,
00138     double phase_dds_deg_);
00139
00140 bool ad9361_disable_lo_remote(const std::string &remote_host);
00141
00142 bool ad9361_disable_lo_local();
00143
00144 bool load_fir_filter(std::string &filter, struct iio_device *phy);
00145
00146 bool disable_ad9361_rx_local();
00147
00148 bool disable_ad9361_rx_remote(const std::string &remote_host);
00149
00150
00151 /** \} */
00152 /** \} */
00153 #endif // GNSS_SDR_AD9361_MANAGER_H

```

13.422 ad936x_iio_custom.h File Reference

A direct IIO custom front-end driver for the AD936x AD front-end family with special FPGA custom functionalities.

```

#include "ad936x_iio_samples.h"
#include "concurrent_queue.h"
#include "gnss_time.h"
#include "pps_samplestamp.h"
#include <boost/atomic.hpp>
#include <iio.h>
#include <ad9361.h>
#include <memory>
#include <string>
#include <thread>
#include <vector>

```

Classes

- class [ad936x_iio_custom](#)

13.422.1 Detailed Description

A direct IIO custom front-end driver for the AD936x AD front-end family with special FPGA custom functionalities.

13.422.1.1 autotoc_md421

Author

Javier Arribas, jarribas(at)cttc.es

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Definition in file [ad936x_iio_custom.h](#).

13.423 ad936x_iio_custom.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file ad936x_iio_custom.h
00003  * \brief A direct IIO custom front-end driver for the AD936x AD front-end
00004  * family with special FPGA custom functionalities.
00005  * \author Javier Arribas, jarribas(at)cttc.es
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_AD936X_IIO_CUSTOM_H
00019 #define GNSS_SDR_AD936X_IIO_CUSTOM_H
00020
00021 #include "ad936x_iio_samples.h"
00022 #include "concurrent_queue.h"
00023 #include "gnss_time.h"
00024 #include "pps_samplestamp.h"
00025 #include <boost/atomic.hpp>
00026 #include <iio.h>
00027 #include <ad9361.h> // multichip sync and high level functions
00028 #include <memory>
00029 #include <string>
00030 #include <thread>
00031 #include <vector>
00032
00033 /** \addtogroup Signal_Source
00034  * \{ */
00035 /** \addtogroup Signal_Source_libs
00036  * \{ */
00037
00038
00039 class ad936x_iio_custom
00040 {
00041 public:
00042     ad936x_iio_custom(int debug_level_, int log_level_);
00043     virtual ~ad936x_iio_custom();
00044     bool initialize_device(const std::string &pluto_device_uri, const std::string &board_type);
00045
00046     bool init_config_ad9361_rx(long long bandwidth_,
00047                               long long sample_rate_,
00048                               long long freq_,
00049                               const std::string &rf_port_select_,
00050                               const std::string &rf_filter,
00051                               const std::string &gain_mode_rx0_,
00052                               const std::string &gain_mode_rx1_,
00053                               double rf_gain_rx0_,
00054                               double rf_gain_rx1_,
00055                               bool enable_ch0,
00056                               bool enable_ch1,
00057                               long long freq_2ch,
00058                               double lo_attenuation_db_,
00059                               bool high_side_lo_,
00060                               int tx_lo_channel_);
00061
00062     bool calibrate(int ch, double bw_hz);
00063
00064     double get_rx_gain(int ch_num);
00065     bool setRXGain(int ch_num, const std::string &gain_mode, double gain_db);
00066
00067     bool set_antenna_port(int ch, int antenna_idx);
00068     double get_frequency(int ch);
00069     bool set_frequency(int ch, double freq_hz);
00070
00071     bool start_sample_rx(bool ppsmode);
00072     void stop_record();
00073
00074     void set_gnss_time_queue(std::shared_ptr<Concurrent_Queue<GnssTime>> queue);
00075     void set_pps_samplestamp_queue(std::shared_ptr<Concurrent_Queue<PpsSamplestamp>> queue);
00076
00077     bool get_rx_frequency(long long &freq_hz);
00078     bool set_rx_frequency(long long freq_hz);
00079     bool read_die_temp(double &temp_c);
00080
00081     void pop_sample_buffer(std::shared_ptr<ad936x_iio_samples> &current_buffer);
00082
00083     void push_sample_buffer(std::shared_ptr<ad936x_iio_samples> &current_buffer);

```

```

00084     int n_channels;
00085
00086 private:
00087     std::shared_ptr<Concurrent_Queue<GnssTime>> GnssTime_queue;
00088     std::shared_ptr<Concurrent_Queue<PpsSamplestamp>> Pps_queue;
00089     bool check_device();
00090     bool get_iio_param(iio_device *dev, const std::string &param, std::string &value);
00091     void configure_params(struct iio_device *phy,
00092         const std::vector<std::string> &params);
00093     void set_params_rx(struct iio_device *phy_device,
00094         unsigned long long frequency,
00095         unsigned long samplerate, unsigned long bandwidth,
00096         bool quadrature, bool rf_dc, bool bddc,
00097         const std::string &gain1, double gain1_value,
00098         const std::string &gain2, double gain2_value,
00099         const std::string &port_select);
00100
00101     bool config_ad9361_dds(uint64_t freq_rf_tx_hz_,
00102         double tx_attenuation_db_,
00103         int64_t freq_dds_tx_hz_,
00104         double scale_dds_,
00105         double phase_dds_deg_,
00106         int channel);
00107
00108     void get_PPS_timestamp();
00109     void capture(const std::vector<std::string> &channels);
00110
00111     bool select_rf_filter(const std::string &rf_filter);
00112
00113     void monitor_thread_fn();
00114
00115     void PlutoTxEnable(bool txon);
00116     void setPlutoGpo(int p);
00117
00118     // Device structure
00119     struct iio_context *ctx;
00120     struct iio_device *phy;
00121     struct iio_device *stream_dev;
00122     struct iio_device *dds_dev;
00123
00124     std::mutex mtx;
00125     std::condition_variable cv;
00126
00127     boost::atomic<bool> receive_samples;
00128
00129     boost::atomic<bool> fpga_overflow;
00130     // using queues of smart pointers to preallocated buffers
00131     Concurrent_Queue<std::shared_ptr<ad936x_iio_samples>> free_buffers;
00132     Concurrent_Queue<std::shared_ptr<ad936x_iio_samples>> used_buffers;
00133
00134     std::thread capture_samples_thread;
00135     std::thread overflow_monitor_thread;
00136     std::thread capture_time_thread;
00137
00138     // stream
00139     uint64_t sample_rate_sps;
00140     int debug_level;
00141     int log_level;
00142     bool PPS_mode;
00143 };
00144
00145 /** \} */
00146 /** \} */
00147 #endif // GNSS_SDR_AD936X_IIO_CUSTOM_H

```

13.424 ad936x_iio_samples.h File Reference

A class that holds a custom sample buffer for Analog Devices AD936x family front-ends.

```

#include <stdint>
#include <memory>
#include <vector>

```

Classes

- class [ad936x_iio_samples](#)

Macros

- `#define IIO_DEFAULTAD936XAPIFIFOSIZE_SAMPLES 32768 * 4`
- `#define IIO_INPUTRAMFIFOSIZE 256`

13.424.1 Detailed Description

A class that holds a custom sample buffer for Analog Devices AD936x family front-ends.

Author

Javier Arribas, jarribas(at)cttc.es

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 Definition in file [ad936x_iio_samples.h](#).

13.424.2 Macro Definition Documentation**13.424.2.1 IIO_DEFAULTAD936XAPIFIFOSIZE_SAMPLES**

```
#define IIO_DEFAULTAD936XAPIFIFOSIZE_SAMPLES 32768 * 4
```

Definition at line 21 of file [ad936x_iio_samples.h](#).

13.424.2.2 IIO_INPUTRAMFIFOSIZE

```
#define IIO_INPUTRAMFIFOSIZE 256
```

Definition at line 22 of file [ad936x_iio_samples.h](#).

13.425 ad936x_iio_samples.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file ad936x_iio_samples.h
00003  * \brief A class that holds a custom sample buffer for Analog Devices AD936x family front-ends.
00004  * \author Javier Arribas, jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_AD936X_IIO_SAMPLES_H
00019 #define GNSS_SDR_AD936X_IIO_SAMPLES_H
00020
00021 #define IIO_DEFAULTAD936XAPIFIFOSIZE_SAMPLES 32768 * 4
00022 #define IIO_INPUTRAMFIFOSIZE 256
00023
00024 #include <stdint>
00025 #include <memory>
00026 #include <vector>
00027
00028 /** \addtogroup Signal_Source
00029  * \{ */
00030 /** \addtogroup Signal_Source_libs
00031  * \{ */
00032
00033 class ad936x_iio_samples
00034 {
00035 public:
00036     ad936x_iio_samples() = default;
00037     uint32_t n_bytes{0};
00038     uint32_t n_interleaved_iq_samples{0};
00039     uint16_t n_channels{0};
00040     uint16_t step_bytes{0};
00041     char buffer[IIO_DEFAULTAD936XAPIFIFOSIZE_SAMPLES * 4 * 4]; // max 16 bits samples per buffer (4
                           channels, 2-bytes per I + 2-bytes per Q)
```

```

00042 };
00043
00044 /** \} */
00045 /** \} */
00046 #endif

```

13.426 fpga_buffer_monitor.h File Reference

Check receiver buffer overflow and monitor the status of the receiver buffers.

```

#include <stdint>
#include <fstream>
#include <string>

```

Classes

- class [Fpga_buffer_monitor](#)

Class that checks the receiver buffer overflow flags and monitors the status of the receiver buffers.

13.426.1 Detailed Description

Check receiver buffer overflow and monitor the status of the receiver buffers.

Authors

- Marc Majoral, 2021. mmajoral(at)cttc.es

Class that checks the receiver buffer overflow flags and monitors the status of the receiver buffers.

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Definition in file [fpga_buffer_monitor.h](#).

13.427 fpga_buffer_monitor.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file fpga_buffer_monitor.h
00003  * \brief Check receiver buffer overflow and monitor the status of the receiver
00004  * buffers.
00005  * \authors
00006  * <ul>
00007  * <li> Marc Majoral, 2021. mmajoral(at)cttc.es
00008  * </li>
00009  *
00010  * Class that checks the receiver buffer overflow flags and monitors the status
00011  * of the receiver buffers.
00012  *
00013  *
00014  * -----
00015  *
00016  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00017  * This file is part of GNSS-SDR.
00018  *
00019  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00020  * SPDX-License-Identifier: GPL-3.0-or-later
00021  *
00022  * -----
00023  */
00024
00025 #ifndef GNSS_SDR_FPGA_BUFFER_MONITOR_H
00026 #define GNSS_SDR_FPGA_BUFFER_MONITOR_H
00027
00028 #include <stdint> // for int32_t
00029 #include <fstream> // for std::ofstream
00030 #include <string> // for std::string
00031
00032 /** \addtogroup Signal_Source
00033  * \{ */
00034 /** \addtogroup Signal_Source_libs
00035  * \{ */
00036
00037

```

```

00038  /*!
00039  * \brief Class that checks the receiver buffer overflow flags and monitors the
00040  * status of the receiver buffers.
00041  */
00042  class Fpga_buffer_monitor
00043  {
00044  public:
00045      /*!
00046       * \brief Constructor
00047       */
00048      explicit Fpga_buffer_monitor(uint32_t num_freq_bands,
00049                                   bool dump,
00050                                   std::string dump_filename);
00051      // explicit Fpga_buffer_monitor(const std::string& device_name,
00052      //                               uint32_t num_freq_bands,
00053      //                               bool dump,
00054      //                               std::string dump_filename);
00055
00056      /*!
00057       * \brief Destructor
00058       */
00059      ~Fpga_buffer_monitor();
00060
00061      /*!
00062       * \brief This function checks buffer overflow and monitors the FPGA buffer status
00063       */
00064      bool check_buffer_overflow_and_monitor_buffer_status();
00065
00066  private:
00067      const std::string BUFFER_MONITOR_DEVICE_NAME = std::string("buffer_monitor"); // buffer monitor
00068      device name
00069      static const size_t FPGA_PAGE_SIZE = 0x1000;
00070      static const uint32_t test_register_writeval = 0x55AA;
00071      static const uint32_t num_samples_per_buffer_element = 2;
00072      // write addresses
00073      static const uint32_t reset_overflow_flags_and_max_buff_size_reg_addr = 0;
00074      // read-write addresses
00075      static const uint32_t test_reg_addr = 7;
00076      // read addresses
00077      static const uint32_t current_buff_occ_freq_band_0_reg_addr = 0;
00078      static const uint32_t current_buff_occ_freq_band_1_reg_addr = 1;
00079      static const uint32_t max_buff_occ_freq_band_0_reg_addr = 2;
00080      static const uint32_t max_buff_occ_freq_band_1_reg_addr = 3;
00081      static const uint32_t overflow_flags_reg_addr = 4;
00082      // FPGA-related constants
00083      static const uint32_t overflow_freq_band_0_bit_pos = 1;
00084      static const uint32_t overflow_freq_band_1_bit_pos = 2;
00085
00086      int32_t buffer_monitor_test_register();
00087      void close_device();
00088
00089      std::string d_dump_filename;
00090      std::ofstream d_dump_file;
00091
00092      volatile unsigned* d_map_base; // driver memory map corresponding to the FPGA buffer monitor
00093      int d_device_descriptor; // driver descriptor corresponding to the FPGA buffer monitor
00094
00095      uint32_t d_num_freq_bands;
00096
00097      uint32_t d_max_buff_occ_freq_band_0;
00098      uint32_t d_max_buff_occ_freq_band_1;
00099
00100      bool d_dump;
00101  };
00102
00103  /** \} */
00104  /** \} */
00105  #endif // GNSS_SDR_FPGA_BUFFER_MONITOR_H

```

13.428 fpga_dma-proxy.h File Reference

FPGA DMA control. This code is based in the Xilinx DMA proxy test application: <https://github.com/Xilinx-Wiki-Projects/software-prototypes/tree/master/linux-user-space-dma/Software>.

```
#include <cstdint>
```

Classes

- class [Fpga_DMA](#)

Class that controls the switch DMA in the FPGA.

Enumerations

- enum **proxy_status** { **PROXY_NO_ERROR** = 0 , **PROXY_BUSY** = 1 , **PROXY_TIMEOUT** = 2 , **PROXY_ERROR** = 3 }

Variables

- int8_t [buffer](#) [DMA_MAX_BUFFER_SIZE]
- enum proxy_status **status**
- unsigned int [length](#)

13.428.1 Detailed Description

FPGA DMA control. This code is based in the Xilinx DMA proxy test application: <https://github.com/Xilinx-Wiki-Projects/software-prototypes/tree/master/linux-user-space-dma/Software>.

Author

Marc Majoral, mmajoral(at)cttc.es

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Definition in file [fpga_dma-proxy.h](#).

13.428.2 Enumeration Type Documentation

13.428.2.1 proxy_status

enum proxy_status

Definition at line 1 of file [fpga_dma-proxy.h](#).

13.428.3 Variable Documentation

13.428.3.1 buffer

int8_t buffer [DMA_MAX_BUFFER_SIZE]

Definition at line 0 of file [fpga_dma-proxy.h](#).

13.428.3.2 length

unsigned int length

Definition at line 8 of file [fpga_dma-proxy.h](#).

13.429 fpga_dma-proxy.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file fpga_dma-proxy.h
00003  * \brief FPGA DMA control. This code is based in the Xilinx DMA proxy test application:
00004  * \a https://github.com/Xilinx-Wiki-Projects/software-prototypes/tree/master/linux-user-space-dma/Software
00005  * \author Marc Majoral, mmajoral(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
```

```

00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_FPGA_DMA_PROXY_H
00019 #define GNSS_SDR_FPGA_DMA_PROXY_H
00020
00021 #include <cstdint> // for std::int8_t
00022
00023 /*!
00024  * \brief Class that controls the switch DMA in the FPGA
00025  */
00026 class Fpga_DMA
00027 {
00028 public:
00029     /*!
00030      * \brief Default constructor.
00031      */
00032     Fpga_DMA() = default;
00033
00034     /*!
00035      * \brief Default destructor.
00036      */
00037     ~Fpga_DMA() = default;
00038
00039     /*!
00040      * \brief Open the DMA device driver.
00041      */
00042     int DMA_open(void);
00043
00044     /*!
00045      * \brief Obtain DMA buffer address.
00046      */
00047     int8_t *get_buffer_address(void); // NOLINT(readability-make-member-function-const)
00048
00049     /*!
00050      * \brief Transfer DMA data
00051      */
00052     int DMA_write(int nbytes) const;
00053
00054     /*!
00055      * \brief Close the DMA device driver
00056      */
00057     int DMA_close(void) const;
00058
00059 private:
00060     static const uint32_t DMA_MAX_BUFFER_SIZE = (128 * 1024); /* must match driver exactly */
00061     static const uint32_t TX_BUFFER_COUNT = 1;
00062
00063     // channel buffer structure
00064     struct channel_buffer
00065     {
00066         int8_t buffer[DMA_MAX_BUFFER_SIZE];
00067         enum proxy_status
00068         {
00069             PROXY_NO_ERROR = 0,
00070             PROXY_BUSY = 1,
00071             PROXY_TIMEOUT = 2,
00072             PROXY_ERROR = 3
00073         } status;
00074         unsigned int length;
00075     } __attribute__((aligned(1024))); /* 64 byte alignment required for DMA, but 1024 handy for
00076 viewing memory */
00077
00078     // internal DMA channel data structure
00079     struct channel
00080     {
00081         struct channel_buffer *buf_ptr;
00082         int fd;
00083     };
00084     channel tx_channel;
00085 };
00086 #endif // GNSS_SDR_FPGA_DMA_PROXY_H

```

13.430 fpga_dynamic_bit_selection.h File Reference

Dynamic bit selection in the received signal.

```

#include <cstddef>
#include <cstdint>
#include <string>

```

```
#include <vector>
```

Classes

- class [Fpga_dynamic_bit_selection](#)

Class that controls the switch in the FPGA, which connects the FPGA acquisition and multicorrelator modules to either the DMA or the Analog Front-End.

13.430.1 Detailed Description

Dynamic bit selection in the received signal.

Authors

- Marc Majoral, 2020. mmajoral(at)cttc.es

Class that controls the Dynamic Bit Selection in the FPGA.

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Definition in file [fpga_dynamic_bit_selection.h](#).

13.431 fpga_dynamic_bit_selection.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file fpga_dynamic_bit_selection.h
00003  * \brief Dynamic bit selection in the received signal.
00004  * \authors <ul>
00005  *         <li> Marc Majoral, 2020. mmajoral(at)cttc.es
00006  *         </li>
00007  *         </ul>
00008  * Class that controls the Dynamic Bit Selection in the FPGA.
00009  *
00010  *
00011  * -----
00012  *
00013  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014  * This file is part of GNSS-SDR.
00015  *
00016  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022 #ifndef GNSS_SDR_FPGA_DYNAMIC_BIT_SELECTION_H
00023 #define GNSS_SDR_FPGA_DYNAMIC_BIT_SELECTION_H
00024
00025 #include <cstdlib>
00026 #include <stdint>
00027 #include <string>
00028 #include <vector>
00029
00030 /** \addtogroup Signal_Source
00031  * \{ */
00032 /** \addtogroup Signal_Source_libs
00033  * \{ */
00034
00035
00036 /*!
00037  * \brief Class that controls the switch in the FPGA, which connects the FPGA acquisition and
00038  *        multicorrelator modules to
00039  *        either the DMA or the Analog Front-End.
00040  */
00041 class Fpga_dynamic_bit_selection
00042 {
00043 public:
00044     /*!
00045      * \brief Constructor
00046      */
00047     explicit Fpga_dynamic_bit_selection(bool enable_rx1_band, bool enable_rx2_band);
00048
00049     /*!
00050      * \brief Destructor
00051      */
00052 }
```

```

00051 ~Fpga_dynamic_bit_selection();
00052
00053 /*!
00054  * \brief This function configures the switch in the eFPGA
00055  */
00056 void bit_selection(void);
00057
00058 private:
00059     const std::string dyn_bit_sel_device_name = std::string("dynamic_bits_selector"); // Switch
00060     dynamic bit selector device name
00061     static const size_t FPGA_PAGE_SIZE = 0x1000;
00062     static const uint32_t Num_bits_ADC = 12; // Number of bits in
the ADC
00063     static const uint32_t Num_bits_FPGA = 4; // Number of bits
after the bit selection
00064     static const uint32_t shift_out_bits_default = Num_bits_ADC - Num_bits_FPGA; // take the most
significant bits by default
00065     static const uint32_t shift_out_bits_min = 0; // minimum possible
value for the bit selection
00066     static const uint32_t shift_out_bit_max = Num_bits_ADC - Num_bits_FPGA; // maximum possible
value for the bit selection
00067     // received signal power thresholds for the bit selection
00068     // the received signal power is estimated as the averaged squared absolute value of the received
signal samples
00069     static const uint32_t Power_Threshold_High = 9000;
00070     static const uint32_t Power_Threshold_Low = 3000;
00071
00072 void open_device(volatile unsigned **d_map_base, int &d_dev_descr, int freq_band);
00073 void bit_selection_per_rf_band(volatile unsigned *d_map_base, uint32_t &shift_out_bits);
00074 void close_device(volatile unsigned *d_map_base, int &d_dev_descr);
00075
00076 volatile unsigned *d_map_base_freq_band_1;
00077 volatile unsigned *d_map_base_freq_band_2;
00078 int d_dev_descr_freq_band_1;
00079 int d_dev_descr_freq_band_2;
00080 uint32_t d_shift_out_bits_freq_band_1;
00081 uint32_t d_shift_out_bits_freq_band_2;
00082 bool d_enable_rx1_band;
00083 bool d_enable_rx2_band;
00084 };
00085
00086 /** \} */
00087 /** \} */
00088 #endif // GNSS_SDR_FPGA_DYNAMIC_BIT_SELECTION_H

```

13.432 fpga_spidev.h File Reference

FPGA SPI control.

```
#include <stdint>
#include <string>
```

Classes

- class [Fpga_spidev](#)

13.432.1 Detailed Description

FPGA SPI control.

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Definition in file [fpga_spidev.h](#).

13.433 fpga_spidev.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file fpga_spidev.h
00003  * \brief FPGA SPI control.
00004  *
00005  * -----
00006  *
00007  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00008  * This file is part of GNSS-SDR.

```

```

00009  *
00010  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00011  * SPDX-License-Identifier: GPL-3.0-or-later
00012  *
00013  * -----
00014  */
00015
00016 #ifndef GNSS_SDR_FPGA_SPIDEV_H
00017 #define GNSS_SDR_FPGA_SPIDEV_H
00018
00019 #include <stdint>
00020 #include <string>
00021
00022 class Fpga_spidev
00023 {
00024 public:
00025     /*!
00026      * \brief Default constructor.
00027      */
00028     Fpga_spidev() = default;
00029
00030     /*!
00031      * \brief Default destructor.
00032      */
00033     ~Fpga_spidev() = default;
00034
00035     /*!
00036      * \brief write a register through the SPI.
00037      */
00038     int write_reg32(char addr, uint32_t data);
00039
00040     /*!
00041      * \brief read a register through the SPI.
00042      */
00043     int read_reg32(uint8_t addr, uint32_t* copy_to);
00044     /*!
00045      * \brief Open the SPI device driver.
00046      */
00047     int SPI_open(std::string spi_device_name);
00048
00049     /*!
00050      * \brief Close the SPI device driver
00051      */
00052     int SPI_close(void) const;
00053
00054 private:
00055     static const uint32_t SPI_SPEED = 250000;
00056     // const std::string SPI_DEVICE_NAME = std::string("/dev/spidev2.0"); // Switch UIO device name
00057
00058     int d_fd;
00059 };
00060
00061
00062 #endif // GNSS_SDR_FPGA_SPIDEV_H

```

13.434 fpga_switch.h File Reference

Switch that connects the HW accelerator queues to the analog front end or the DMA.

```

#include <stdint>
#include <string>

```

Classes

- class [Fpga_Switch](#)

Class that controls the switch in the FPGA, which connects the FPGA acquisition and multicorrelator modules to either the DMA or the Analog Front-End.

13.434.1 Detailed Description

Switch that connects the HW accelerator queues to the analog front end or the DMA.

Authors

- Marc Majoral, 2019. mmajoral(at)cttc.cat
- Javier Arribas, 2016. jarribas(at)cttc.es

Class that controls a switch in the FPGA

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Definition in file [fpga_switch.h](#).

13.435 fpga_switch.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file fpga_switch.h
00003  * \brief Switch that connects the HW accelerator queues to the analog front end or the DMA.
00004  * \authors <ul>
00005  *     <li> Marc Majoral, 2019. mmajoral(at)cttc.cat
00006  *     <li> Javier Arribas, 2016. jarribas(at)cttc.es
00007  * </ul>
00008  *
00009  * Class that controls a switch in the FPGA
00010  *
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.
00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_FPGA_SWITCH_H
00024 #define GNSS_SDR_FPGA_SWITCH_H
00025
00026 #include <cstdint>
00027 #include <string>
00028
00029 /** \addtogroup Signal_Source
00030 * \{ */
00031 /** \addtogroup Signal_Source_libs
00032 * \{ */
00033
00034
00035  /*!
00036  * \brief Class that controls the switch in the FPGA, which connects the FPGA acquisition and
00037  *        multicorrelator modules to
00038  *        either the DMA or the Analog Front-End.
00039  */
00039  class Fpga_Switch
00040  {
00041  public:
00042      /*!
00043       * \brief Constructor
00044       */
00045      Fpga_Switch(void);
00046      /*!
00047       * \brief Destructor
00048       */
00049      ~Fpga_Switch();
00050
00051      /*!
00052       * \brief This function configures the switch in the FPGA
00053       */
00054      void set_switch_position(int32_t switch_position);
00055
00056  private:
00057      const std::string SWITCH_DEVICE_NAME = std::string("AXIS_Switch_v1_0_0"); // Switch UIO device
00058      name
00059      static const size_t FPGA_PAGE_SIZE = 0x1000;
00059      static const uint32_t TEST_REGISTER_TRACK_WRITEVAL = 0x55AA;
00060      static const uint32_t MAX_LENGTH_DEVICEIO_NAME = 50;
00061
00062      // private functions
00063      unsigned fpga_switch_test_register(unsigned writeval);
00064      void close_device(void);
00065
00066      volatile unsigned* d_map_base; // driver memory map
00067      int d_device_descriptor; // driver descriptor
00068  };
00069
00070
00071 /** \} */
00072 /** \} */
00073 #endif // GNSS_SDR_FPGA_SWITCH_H

```

13.436 gnss_sdr_timestamp.h File Reference

GNURadio block that adds to sample stream timestamp metadata information stored on a separated file.

```
#include "gnss_block_interface.h"
#include "gnss_time.h"
#include <gnuradio/sync_block.h>
#include <gnuradio/types.h>
#include <pmt/pmt.h>
#include <cstdint>
#include <cstdint>
#include <fstream>
#include <string>
```

Classes

- class [Gnss_Sdr_Timestamp](#)

Functions

- `gnss_shared_ptr< Gnss_Sdr_Timestamp > gnss_sdr_make_Timestamp` (size_t sizeof_stream_item, std::string timestamp_file, double clock_offset_ms, int items_to_samples)

13.436.1 Detailed Description

GNURadio block that adds to sample stream timestamp metadata information stored on a separated file.

Author

Javier Arribas, 2021. jarribas(at)cttc.es

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 Definition in file [gnss_sdr_timestamp.h](#).

13.437 gnss_sdr_timestamp.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gnss_sdr_timestamp.h
00003  * \brief GNURadio block that adds to sample stream timestamp metadata information stored on a
00004  *        separated file
00005  * \author Javier Arribas, 2021. jarribas(at)cttc.es
00006  *
00007  * -----
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GNSS_SDR_TIMESTAMP_H
00019 #define GNSS_SDR_GNSS_SDR_TIMESTAMP_H
00020
00021 #include "gnss_block_interface.h"
00022 #include "gnss_time.h"
00023 #include <gnuradio/sync_block.h> // for sync_block
00024 #include <gnuradio/types.h> // for gr_vector_const_void_star
00025 #include <pmt/pmt.h>
00026 #include <cstdint> // for size_t
00027 #include <cstdint>
00028 #include <fstream>
00029 #include <string>
00030
00031 /** \addtogroup Signal_Source
```

```

00032  * \{ */
00033  /** \addtogroup Signal_Source_libs
00034  * \{ */
00035
00036
00037  class Gnss_Sdr_Timestamp;
00038
00039  gnss_shared_ptr<Gnss_Sdr_Timestamp> gnss_sdr_make_Timestamp(
00040      size_t sizeof_stream_item,
00041      std::string timestamp_file,
00042      double clock_offset_ms,
00043      int items_to_samples);
00044
00045
00046  class Gnss_Sdr_Timestamp : public gr::sync_block
00047  {
00048  public:
00049      int work(int noutput_items,
00050              gr_vector_const_void_star& input_items,
00051              gr_vector_void_star& output_items);
00052      bool start();
00053
00054  private:
00055      friend gnss_shared_ptr<Gnss_Sdr_Timestamp> gnss_sdr_make_Timestamp(
00056          size_t sizeof_stream_item,
00057          std::string timestamp_file,
00058          double clock_offset_ms,
00059          int items_to_samples);
00060
00061      Gnss_Sdr_Timestamp(size_t sizeof_stream_item,
00062                          std::string timestamp_file,
00063                          double clock_offset_ms,
00064                          int items_to_samples);
00065
00066      int64_t uint64diff(uint64_t first, uint64_t second);
00067      bool read_next_timetag();
00068      std::string d_timefile;
00069      std::fstream d_timefilestream;
00070      GnssTime next_timetag();
00071      double d_clock_offset_ms;
00072      double d_fraction_ms_offset;
00073      double d_integer_ms_offset;
00074      int d_items_to_samples;
00075      uint64_t d_next_timetag_samplecount;
00076      bool d_get_next_timetag;
00077  };
00078
00079
00080  /** \} */
00081  /** \} */
00082  #endif // GNSS_SDR_GNSS_SDR_TIMESTAMP_H

```

13.438 gnss_sdr_valve.h File Reference

Interface of a GNU Radio block that sends a STOP message to the control queue right after a specific number of samples have passed through it.

```

#include "concurrent_queue.h"
#include "gnss_block_interface.h"
#include <gnuradio/sync_block.h>
#include <gnuradio/types.h>
#include <pmt/pmt.h>
#include <cstdint>
#include <cstdint>

```

Classes

- class [Gnss_Sdr_Valve](#)

Implementation of a GNU Radio block that sends a STOP message to the control queue right after a specific number of samples have passed through it.

Functions

- [gnss_shared_ptr< Gnss_Sdr_Valve > gnss_sdr_make_valve](#) (size_t sizeof_stream_item, uint64_t nitems, [Concurrent_Queue< pmt::pmt_t > *queue](#))

- `gnss_shared_ptr< Gnss_Sdr_Valve > gnss_sdr_make_valve (size_t sizeof_stream_item, uint64_t nitems, Concurrent_Queue< pmt::pmt_t > *queue, bool stop_flowgraph)`

13.438.1 Detailed Description

Interface of a GNU Radio block that sends a STOP message to the control queue right after a specific number of samples have passed through it.

Author

Javier Arribas, 2018. jarribas(at)cttc.es

Carlos Aviles, 2010. carlos.avilesr(at)googlemail.com

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Definition in file [gnss_sdr_valve.h](#).

13.439 gnss_sdr_valve.h

[Go to the documentation of this file.](#)

```
00001  /*!
00002  * \file gnss_sdr_valve.h
00003  * \brief Interface of a GNU Radio block that sends a STOP message to the
00004  * control queue right after a specific number of samples have passed through it.
00005  * \author Javier Arribas, 2018. jarribas(at)cttc.es
00006  * \author Carlos Aviles, 2010. carlos.avilesr(at)googlemail.com
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019
00020 #ifndef GNSS_SDR_GNSS_SDR_VALVE_H
00021 #define GNSS_SDR_GNSS_SDR_VALVE_H
00022
00023 #include "concurrent_queue.h"
00024 #include "gnss_block_interface.h"
00025 #include <gnuradio/sync_block.h> // for sync_block
00026 #include <gnuradio/types.h> // for gr_vector_const_void_star
00027 #include <pmt/pmt.h>
00028 #include <cstdint> // for size_t
00029 #include <cstdint>
00030
00031 /** \addtogroup Signal_Source
00032  * \{ */
00033 /** \addtogroup Signal_Source_libs
00034  * \{ */
00035
00036
00037 class Gnss_Sdr_Valve;
00038
00039 gnss_shared_ptr<Gnss_Sdr_Valve> gnss_sdr_make_valve(
00040     size_t sizeof_stream_item,
00041     uint64_t nitems,
00042     Concurrent_Queue<pmt::pmt_t>* queue);
00043
00044 gnss_shared_ptr<Gnss_Sdr_Valve> gnss_sdr_make_valve(
00045     size_t sizeof_stream_item,
00046     uint64_t nitems,
00047     Concurrent_Queue<pmt::pmt_t>* queue,
00048     bool stop_flowgraph);
00049
00050 /*!
00051 * \brief Implementation of a GNU Radio block that sends a STOP message to the
00052 * control queue right after a specific number of samples have passed through it.
00053 */
00054 class Gnss_Sdr_Valve : public gr::sync_block
00055 {
00056 public:
00057     void open_valve();
00058 }
```

```

00059     int work(int noutput_items,
00060             gr_vector_const_void_star& input_items,
00061             gr_vector_void_star& output_items);
00062
00063 private:
00064     friend gnss_shared_ptr<Gnss_Sdr_Valve> gnss_sdr_make_valve(
00065         size_t sizeof_stream_item,
00066         uint64_t nitems,
00067         Concurrent_Queue<pmt::pmt_t>* queue);
00068
00069     friend gnss_shared_ptr<Gnss_Sdr_Valve> gnss_sdr_make_valve(
00070         size_t sizeof_stream_item,
00071         uint64_t nitems,
00072         Concurrent_Queue<pmt::pmt_t>* queue,
00073         bool stop_flowgraph);
00074
00075     Gnss_Sdr_Valve(size_t sizeof_stream_item,
00076                   uint64_t nitems,
00077                   Concurrent_Queue<pmt::pmt_t>* queue, bool stop_flowgraph);
00078
00079     uint64_t d_nitems;
00080     uint64_t d_ncopied_items;
00081     Concurrent_Queue<pmt::pmt_t>* d_queue;
00082     bool d_stop_flowgraph;
00083     bool d_open_valve;
00084 };
00085
00086
00087 /** \} */
00088 /** \} */
00089 #endif // GNSS_SDR_GNSS_SDR_VALVE_H

```

13.440 ion_gsms_chunk_data.h File Reference

Holds logic for reading and decoding samples from a chunk.

```

#include "ion_gsms_chunk_unpacking_ctx.h"
#include "ion_gsms_stream_encodings.h"
#include <gnuradio/block.h>
#include <GnssMetadata.h>
#include <cstdint>
#include <stdint>
#include <iostream>
#include <string>
#include <vector>

```

Classes

- struct [Allocator](#)
- struct [Deleter](#)
- class [IONGSMSChunkData](#)

Functions

- std::size_t [bits_to_item_size](#) (std::size_t bit_count)
- template<typename Callback>
void [with_word_type](#) (uint8_t word_size, Callback callback)

13.440.1 Detailed Description

Holds logic for reading and decoding samples from a chunk.

Author

Víctor Castillo Agüero, 2024. victorcastilloaguero(at)gmail.com

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 Definition in file [ion_gsms_chunk_data.h](#).

13.440.2 Function Documentation

13.440.2.1 bits_to_item_size()

```
std::size_t bits_to_item_size (
    std::size_t bit_count) [inline]
```

Definition at line 31 of file [ion_gsms_chunk_data.h](#).

13.440.2.2 with_word_type()

```
template<typename Callback>
void with_word_type (
    uint8_t word_size,
    Callback callback)
```

Definition at line 90 of file [ion_gsms_chunk_data.h](#).

13.441 ion_gsms_chunk_data.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file ion_gsms_chunk_data.h
00003  * \brief Holds logic for reading and decoding samples from a chunk
00004  * \author Victor Castillo Agüero, 2024. victorcastilloaguero(at)gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_ION_GSMS_CHUNK_DATA_H
00018 #define GNSS_SDR_ION_GSMS_CHUNK_DATA_H
00019
00020 #include "ion_gsms_chunk_unpacking_ctx.h"
00021 #include "ion_gsms_stream_encodings.h"
00022 #include <gnuradio/block.h>
00023 #include <GnssMetadata.h>
00024 #include <cstdint>
00025 #include <cstdint>
00026 #include <iostream>
00027 #include <string>
00028 #include <vector>
00029
00030
00031 inline std::size_t bits_to_item_size(std::size_t bit_count)
00032 {
00033     if (bit_count <= 8)
00034     {
00035         return 1;
00036     }
00037     if (bit_count <= 16)
00038     {
00039         return 2;
00040     }
00041     if (bit_count <= 32)
00042     {
00043         return 4;
00044     }
00045     if (bit_count <= 64)
00046     {
00047         return 8;
00048     }
00049
00050     // You are asking too much of this humble processor
00051     std::cerr << "Item size too large (" << std::to_string(bit_count) << "), returning nonsense.\n";
00052     return 1;
00053 }
00054
00055
00056 // Define a functor that has a templated operator()
00057 struct Allocator
00058 {
00059     size_t countwords_;
```

```

00060     void*& buffer_; // Using void* to hold any type of pointer
00061
00062     Allocator(size_t countwords, void*& buffer)
00063         : countwords_(countwords), buffer_(buffer) {}
00064
00065     template <typename WordType>
00066     void operator()() const
00067     {
00068         buffer_ = new WordType[countwords_];
00069     }
00070 };
00071
00072
00073 // Define a functor to delete the allocated memory
00074 struct Deleter
00075 {
00076     void* buffer_;
00077
00078     explicit Deleter(void* buffer)
00079         : buffer_(buffer) {}
00080
00081     template <typename WordType>
00082     void operator()() const
00083     {
00084         delete[] static_cast<WordType*>(buffer_);
00085     }
00086 };
00087
00088
00089 template <typename Callback>
00090 void with_word_type(uint8_t word_size, Callback callback)
00091 {
00092     switch (word_size)
00093     {
00094     case 1:
00095         callback.template operator()<int8_t>();
00096         break;
00097     case 2:
00098         callback.template operator()<int16_t>();
00099         break;
00100     case 4:
00101         callback.template operator()<int32_t>();
00102         break;
00103     case 8:
00104         callback.template operator()<int64_t>();
00105         break;
00106     default:
00107         std::cerr << "Unknown word size (" << std::to_string(word_size) << ")", returning
nonsense.\n";
00108         break;
00109     }
00110 }
00111
00112 class IONGSMSChunkData
00113 {
00114 public:
00115     IONGSMSChunkData(const GnssMetadata::Chunk& chunk, const std::vector<std::string>& stream_ids,
std::size_t output_stream_offset);
00116
00117     ~IONGSMSChunkData();
00118
00119     IONGSMSChunkData(const IONGSMSChunkData& rhl) = delete;
00120     IONGSMSChunkData& operator=(const IONGSMSChunkData& rhl) = delete;
00121
00122     IONGSMSChunkData(IONGSMSChunkData&& rhl) = delete;
00123     IONGSMSChunkData& operator=(IONGSMSChunkData&& rhl) = delete;
00124
00125     std::size_t read_from_buffer(uint8_t* buffer, std::size_t offset);
00126
00127     void write_to_output(gr_vector_void_star& outputs, std::vector<int>& output_items);
00128
00129     std::size_t output_stream_count() const;
00130     std::size_t output_stream_item_size(std::size_t stream_index) const;
00131     std::size_t output_stream_item_rate(std::size_t stream_index) const;
00132 private:
00133     template <typename WT>
00134     void unpack_words(gr_vector_void_star& outputs, std::vector<int>& output_items);
00135
00136     template <typename WT>
00137     std::size_t write_stream_samples(
IONGSMSChunkUnpackingCtx<WT>& ctx,
const GnssMetadata::Lump& lump,
const GnssMetadata::IonStream& stream,
GnssMetadata::StreamEncoding stream_encoding,
void** out);
00143
00144

```

```

00145     template <typename WT, typename OT>
00146     void write_n_samples(
00147         IONGSMSChunkUnpackingCtx<WT>& ctx,
00148         GnssMetadata::Lump::LumpShift lump_shift,
00149         uint8_t sample_bitsize,
00150         std::size_t sample_count,
00151         GnssMetadata::StreamEncoding stream_encoding,
00152         OT** out);
00153
00154     template <typename Sample>
00155     static void decode_sample(uint8_t sample_bitsize, Sample* sample, GnssMetadata::StreamEncoding
encoding);
00156
00157     const GnssMetadata::Chunk& chunk_;
00158     uint8_t sizeword_;
00159     uint8_t countwords_;
00160     uint8_t padding_bitsize_;
00161     std::size_t output_stream_count_;
00162     std::vector<std::size_t> output_stream_item_size_;
00163     std::vector<std::size_t> output_stream_item_rate_;
00164
00165     struct stream_metadata_t
00166     {
00167         const GnssMetadata::Lump& lump_;
00168         const GnssMetadata::IonStream& stream_;
00169         GnssMetadata::StreamEncoding stream_encoding_;
00170         int output_index = -1;
00171
00172         stream_metadata_t(
00173             const GnssMetadata::Lump& lump_,
00174             const GnssMetadata::IonStream& stream_,
00175             GnssMetadata::StreamEncoding stream_encoding_,
00176             int output_index_ = -1) : lump(lump_),
00177                                     stream(stream_),
00178                                     stream_encoding(stream_encoding_),
00179                                     output_index(output_index_)
00180         {
00181         }
00182     };
00183     std::vector<stream_metadata_t> streams_;
00184
00185     void* buffer_;
00186 };
00187
00188 #endif // GNSS_SDR_ION_GSMS_CHUNK_DATA_H

```

13.442 ion_gsms_chunk_unpacking_ctx.h File Reference

Holds state and provides utilities for unpacking samples from a chunk.

```

#include <gnuradio/block.h>
#include <GnssMetadata.h>
#include <cstdint>

```

Classes

- struct [IONGSMSChunkUnpackingCtx< WT >](#)

13.442.1 Detailed Description

Holds state and provides utilities for unpacking samples from a chunk.

Author

Víctor Castillo Agüero, 2024. victorcastilloagüero(at)gmail.com

This is a template class, and thus, its member functions must be defined in the header file.

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Definition in file [ion_gsms_chunk_unpacking_ctx.h](#).

13.443 ion_gsms_chunk_unpacking_ctx.h

[Go to the documentation of this file.](#)


```

00001  /*!
00002  * \file ion_gsms_chunk_unpacking_ctx.h
00003  * \brief Holds state and provides utilities for unpacking samples from a chunk
00004  * \author Victor Castillo Agüero, 2024. victorcastilloaguero(at)gmail.com
00005  *
00006  * This is a template class, and thus, its member functions must be defined in the header file.
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_ION_GSMS_CHUNK_UNPACKING_CTX_H
00020 #define GNSS_SDR_ION_GSMS_CHUNK_UNPACKING_CTX_H
00021
00022 #include <gnuradio/block.h>
00023 #include <GnssMetadata.h>
00024 #include <cstdint>
00025
00026 /** \addtogroup Signal_Source
00027  * \{ */
00028 /** \addtogroup Signal_Source_libs
00029  * \{ */
00030
00031 template <typename WT>
00032 struct IONGSMSChunkUnpackingCtx
00033 {
00034     static constexpr uint8_t word_bitsize_ = sizeof(WT) * 8;
00035
00036     const GnssMetadata::Chunk::WordShift word_shift_direction_;
00037     WT* iterator_ = nullptr; // Not owned by this class, MUST NOT destroy
00038     WT current_word_{};
00039     uint8_t bitshift_ = 0;
00040
00041     IONGSMSChunkUnpackingCtx(
00042         const GnssMetadata::Chunk::WordShift word_shift,
00043         WT* data_buffer,
00044         uint8_t data_buffer_word_count) : word_shift_direction_(word_shift)
00045     {
00046         if (word_shift_direction_ == GnssMetadata::Chunk::Left)
00047         {
00048             iterator_ = data_buffer;
00049         }
00050         else if (word_shift_direction_ == GnssMetadata::Chunk::Right)
00051         {
00052             iterator_ = &data_buffer[data_buffer_word_count];
00053         }
00054         if (iterator_)
00055         {
00056             advance_word(); // Initializes current_word_
00057         }
00058     }
00059
00060     void advance_word()
00061     {
00062         WT word = *iterator_;
00063         if (word_shift_direction_ == GnssMetadata::Chunk::Left)
00064         {
00065             ++iterator_;
00066         }
00067         else if (word_shift_direction_ == GnssMetadata::Chunk::Right)
00068         {
00069             --iterator_;
00070         }
00071         current_word_ = word;
00072     }
00073
00074     void shift_current_word(uint8_t n)
00075     {
00076         if ((n % word_bitsize_) == 0)
00077         {
00078             for (uint8_t i = 0; i < (n / word_bitsize_); ++i)
00079             {
00080                 advance_word();
00081             }
00082             return;
00083         }
00084         if (word_shift_direction_ == GnssMetadata::Chunk::Left)
00085         {
00086             {

```

```

00088         current_word_ <= n;
00089     }
00090     else if (word_shift_direction_ == GnssMetadata::Chunk::Right)
00091     {
00092         current_word_ >= n;
00093     }
00094
00095     bitshift_ += n;
00096     if (bitshift_ >= word_bitsize_)
00097     {
00098         advance_word();
00099         bitshift_ -= word_bitsize_;
00100     }
00101 }
00102
00103 void shift_padding(uint8_t n_bits)
00104 {
00105     if (n_bits == 0)
00106     {
00107         return;
00108     }
00109
00110     if ((n_bits + (bitshift_ % word_bitsize_)) >= word_bitsize_)
00111     {
00112         const uint8_t bits_shifted = word_bitsize_ - (bitshift_ % word_bitsize_);
00113
00114         shift_current_word(bits_shifted);
00115         shift_padding(n_bits - bits_shifted);
00116     }
00117     else
00118     {
00119         shift_current_word(n_bits);
00120     }
00121 }
00122
00123 template <typename OT>
00124 void shift_sample(uint8_t sample_bitsize, OT* output, uint8_t output_bit_offset = 0)
00125 {
00126     if (sample_bitsize % word_bitsize_ == 0)
00127     {
00128         const uint8_t words_per_sample = sample_bitsize / word_bitsize_;
00129         for (uint8_t i = 0; i < words_per_sample; ++i)
00130         {
00131             if (word_shift_direction_ == GnssMetadata::Chunk::Left)
00132             {
00133                 *output |= (current_word_ < ((words_per_sample - 1 - i) *
word_bitsize_));
00134             }
00135             else if (word_shift_direction_ == GnssMetadata::Chunk::Right)
00136             {
00137                 *output |= (current_word_ < (i * word_bitsize_));
00138                 // TODO - reverse bit order of sample? maybe?
00139             }
00140             advance_word();
00141         }
00142     }
00143     else if ((sample_bitsize + (bitshift_ % word_bitsize_)) > word_bitsize_)
00144     {
00145         const uint8_t bits_shifted = word_bitsize_ - (bitshift_ % word_bitsize_);
00146
00147         if (word_shift_direction_ == GnssMetadata::Chunk::Left)
00148         {
00149             WT mask = ~(1 < (word_bitsize_ - bits_shifted)) - 1;
00150             *output |= ((current_word_ & mask) > output_bit_offset);
00151         }
00152         else if (word_shift_direction_ == GnssMetadata::Chunk::Right)
00153         {
00154             WT mask = (1 < (bits_shifted)) - 1;
00155             *output |= (current_word_ & mask) < output_bit_offset;
00156             // TODO - reverse bit order of sample? maybe?
00157         }
00158
00159         shift_current_word(bits_shifted);
00160         shift_sample(sample_bitsize - bits_shifted, output, bits_shifted);
00161     }
00162     else
00163     {
00164         if (word_shift_direction_ == GnssMetadata::Chunk::Left)
00165         {
00166             WT mask = ~(1 < (word_bitsize_ - sample_bitsize)) - 1;
00167             OT sample = (current_word_ & mask) > (word_bitsize_ - sample_bitsize);
00168             *output |= (sample) > output_bit_offset;
00169         }
00170         else if (word_shift_direction_ == GnssMetadata::Chunk::Right)
00171         {
00172             WT mask = (1 < (sample_bitsize)) - 1;
00173             *output |= (current_word_ & mask) < output_bit_offset;

```

```

00174             // TODO - reverse bit order of sample? maybe?
00175         }
00176     }
00177     shift_current_word(sample_bitsize);
00178 }
00179 }
00180 };
00181
00182 /** \} */
00183 /** \} */
00184 #endif // GNSS_SDR_ION_GSMS_CHUNK_UNPACKING_CTX_H

```

13.444 ion_gsms_stream_encodings.h File Reference

Implements look up tables for all encodings in the standard.

```
#include <string>
```

Typedefs

- using [GnssMetadata::StreamEncoding](#) = unsigned char

Functions

- StreamEncoding [GnssMetadata::encoding_from_string](#) (const std::string &str)

Variables

- constexpr unsigned char [GnssMetadata::StreamEncodings::SIGN](#) = 0
- constexpr unsigned char [GnssMetadata::StreamEncodings::OB](#) = 1
- constexpr unsigned char [GnssMetadata::StreamEncodings::SM](#) = 2
- constexpr unsigned char [GnssMetadata::StreamEncodings::MS](#) = 3
- constexpr unsigned char [GnssMetadata::StreamEncodings::TC](#) = 4
- constexpr unsigned char [GnssMetadata::StreamEncodings::OG](#) = 5
- constexpr unsigned char [GnssMetadata::StreamEncodings::OBA](#) = 6
- constexpr unsigned char [GnssMetadata::StreamEncodings::SMA](#) = 7
- constexpr unsigned char [GnssMetadata::StreamEncodings::MSA](#) = 8
- constexpr unsigned char [GnssMetadata::StreamEncodings::TCA](#) = 9
- constexpr unsigned char [GnssMetadata::StreamEncodings::OGA](#) = 10
- constexpr unsigned char [GnssMetadata::StreamEncodings::FP](#) = 11
- template<typename T>
T [GnssMetadata::two_bit_look_up](#) [11][4]
- template<typename T>
T [GnssMetadata::three_bit_look_up](#) [11][8]
- template<typename T>
T [GnssMetadata::four_bit_look_up](#) [11][16]
- template<typename T>
T [GnssMetadata::five_bit_look_up](#) [11][32]

13.444.1 Detailed Description

Implements look up tables for all encodings in the standard.

Author

Víctor Castillo Agüero, 2024. victorcastilloaguero(at)gmail.com

These tables are taken from the standard's official document.

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [ion_gsms_stream_encodings.h](#).

13.444.2 Typedef Documentation

13.444.2.1 StreamEncoding

using GnssMetadata::StreamEncoding = unsigned char

Definition at line 32 of file [ion_gsms_stream_encodings.h](#).

13.444.3 Function Documentation

13.444.3.1 encoding_from_string()

```
StreamEncoding GnssMetadata::encoding_from_string (
    const std::string & str) [inline]
```

Definition at line 52 of file [ion_gsms_stream_encodings.h](#).

13.444.4 Variable Documentation

13.444.4.1 five_bit_look_up

```
template<typename T>
T GnssMetadata::five_bit_look_up[11][32] [inline]
```

Initial value:

```
{
    {},
    {-16, -15, -14, -13, -12, -11, -10, -9, -8, -7, -6, -5, -4, -3, -2, -1, 0, 1, 2, 3, 4, 5, 6, 7, 8, 9,
     10, 11, 12, 13, 14, 15},
    {0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 0, -1, -2, -3, -4, -5, -6, -7, -8, -9, -10, -11,
     -12, -13, -14, -15},
    {0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1,
     -1},
    {0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, -16, -15, -14, -13, -12, -11, -10, -9, -8, -7,
     -6, -5, -4, -3, -2, -1},
    {-16, -15, -13, -14, -9, -10, -12, -11, -1, -2, -4, -3, -8, -7, -5, -6, 15, 14, 12, 13, 8, 9, 11, 10, 0,
     1, 3, 2, 7, 6, 4, 5},
    {-31, -29, -27, -25, -23, -21, -19, -17, -15, -13, -11, -9, -7, -5, -3, -1, 1, 3, 5, 7, 9, 11, 13, 15,
     17, 19, 21, 23, 25, 27, 29, 31},
    {1, 3, 5, 7, 9, 11, 13, 15, 17, 19, 21, 23, 25, 27, 29, 31, -1, -3, -5, -7, -9, -11, -13, -15, -17, -19,
     -21, -23, -25, -27, -29, -31},
    {1, -1, 3, -3, 5, -5, 7, -7, 9, -9, 11, -11, 13, -13, 15, -15, 17, -17, 19, -19, 21, -21, 23, -23, 25,
     -25, 27, -27, 29, -29, 31, -31},
    {1, 3, 5, 7, 9, 11, 13, 15, 17, 19, 21, 23, 25, 27, 29, 31, -31, -29, -27, -25, -23, -21, -19, -17, -15,
     -13, -11, -9, -7, -5, -3, -1},
    {-31, -29, -25, -27, -17, -19, -23, -21, -1, -3, -7, -5, -15, -13, -9, -11, 31, 29, 25, 27, 17, 19, 23,
     21, 1, 3, 7, 5, 15, 13, 9, 11},
}
```

Definition at line 151 of file [ion_gsms_stream_encodings.h](#).

13.444.4.2 four_bit_look_up

```
template<typename T>
T GnssMetadata::four_bit_look_up[11][16] [inline]
```

Initial value:

```
{
    {},
    {-8, -7, -6, -5, -4, -3, -2, -1, 0, 1, 2, 3, 4, 5, 6, 7},
    {0, 1, 2, 3, 4, 5, 6, 7, 0, -1, -2, -3, -4, -5, -6, -7},
    {0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1},
    {0, 1, 2, 3, 4, 5, 6, 7, -8, -7, -6, -5, -4, -3, -2, -1},
    {-8, -7, -5, -6, -1, -2, -4, -3, 7, 6, 4, 5, 0, 1, 3, 2},
    {-15, -13, -11, -9, -7, -5, -3, -1, 1, 3, 5, 7, 9, 11, 13, 15},
    {1, 3, 5, 7, 9, 11, 13, 15, -1, -3, -5, -7, -9, -11, -13, -15},
    {1, -1, 3, -3, 5, -5, 7, -7, 9, -9, 11, -11, 13, -13, 15, -15},
    {1, 3, 5, 7, 9, 11, 13, 15, -15, -13, -11, -9, -7, -5, -3, -1},
    {-15, -13, -9, -11, -1, -3, -7, -5, 15, 13, 9, 11, 1, 3, 7, 5},
}
```

Definition at line 136 of file [ion_gsms_stream_encodings.h](#).

13.444.4.3 FP

```
unsigned char GnssMetadata::StreamEncodings::FP = 11 [constexpr]
```

Definition at line 48 of file [ion_gsms_stream_encodings.h](#).

13.444.4.4 MS

`unsigned char GnssMetadata::StreamEncodings::MS = 3 [constexpr]`
Definition at line 40 of file [ion_gsms_stream_encodings.h](#).

13.444.4.5 MSA

`unsigned char GnssMetadata::StreamEncodings::MSA = 8 [constexpr]`
Definition at line 45 of file [ion_gsms_stream_encodings.h](#).

13.444.4.6 OB

`unsigned char GnssMetadata::StreamEncodings::OB = 1 [constexpr]`
Definition at line 38 of file [ion_gsms_stream_encodings.h](#).

13.444.4.7 OBA

`unsigned char GnssMetadata::StreamEncodings::OBA = 6 [constexpr]`
Definition at line 43 of file [ion_gsms_stream_encodings.h](#).

13.444.4.8 OG

`unsigned char GnssMetadata::StreamEncodings::OG = 5 [constexpr]`
Definition at line 42 of file [ion_gsms_stream_encodings.h](#).

13.444.4.9 OGA

`unsigned char GnssMetadata::StreamEncodings::OGA = 10 [constexpr]`
Definition at line 47 of file [ion_gsms_stream_encodings.h](#).

13.444.4.10 SIGN

`unsigned char GnssMetadata::StreamEncodings::SIGN = 0 [constexpr]`
Definition at line 37 of file [ion_gsms_stream_encodings.h](#).

13.444.4.11 SM

`unsigned char GnssMetadata::StreamEncodings::SM = 2 [constexpr]`
Definition at line 39 of file [ion_gsms_stream_encodings.h](#).

13.444.4.12 SMA

`unsigned char GnssMetadata::StreamEncodings::SMA = 7 [constexpr]`
Definition at line 44 of file [ion_gsms_stream_encodings.h](#).

13.444.4.13 TC

`unsigned char GnssMetadata::StreamEncodings::TC = 4 [constexpr]`
Definition at line 41 of file [ion_gsms_stream_encodings.h](#).

13.444.4.14 TCA

`unsigned char GnssMetadata::StreamEncodings::TCA = 9 [constexpr]`
Definition at line 46 of file [ion_gsms_stream_encodings.h](#).

13.444.4.15 three_bit_look_up

```
template<typename T>
T GnssMetadata::three_bit_look_up[11][8]  [inline]
```

Initial value:

```
{
    {},
    {-4, -3, -2, -1, 0, 1, 2, 3},
    {0, 1, 2, 3, 0, -1, -2, -3},
    {0, 0, 1, -1, 0, 0, 1, -1},
    {0, 1, 2, 3, -4, -3, -2, -1},
    {-4, -3, -1, -2, 3, 2, 0, 1},
    {-7, -5, -3, -1, 1, 3, 5, 7},
    {1, 3, 5, 7, -1, -3, -5, -7},
    {1, -1, 3, -3, 5, -5, 7, -7},
    {1, 3, 5, 7, -7, -5, -3, -1},
    {-7, -5, -1, -3, 7, 5, 1, 3},
}
```

Definition at line 121 of file [ion_gsms_stream_encodings.h](#).**13.444.4.16 two_bit_look_up**

```
template<typename T>
T GnssMetadata::two_bit_look_up[11][4]  [inline]
```

Initial value:

```
{
    {},
    {-2, -1, 0, 1},
    {0, 1, 0, -1},
    {0, 0, 1, -1},
    {0, 1, -2, -1},
    {-2, -1, 1, 0},
    {-3, -1, 1, 3},
    {1, 3, -1, -3},
    {1, -1, 3, -3},
    {1, 3, -3, -1},
    {-3, -1, 3, 1},
}
```

Definition at line 106 of file [ion_gsms_stream_encodings.h](#).**13.445 ion_gsms_stream_encodings.h**[Go to the documentation of this file.](#)

```
00001  /*!
00002  * \file ion_gsms_stream_encodings.h
00003  * \brief Implements look up tables for all encodings in the standard
00004  * \author Víctor Castillo Agüero, 2024. victorcastilloaguero(at)gmail.com
00005  *
00006  * These tables are taken from the standard's official document.
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_ION_GSMS_STREAM_ENCODINGS_H
00020 #define GNSS_SDR_ION_GSMS_STREAM_ENCODINGS_H
00021
00022 #include <string>
00023
00024 /** \addtogroup Signal_Source
00025  * \{ */
00026 /** \addtogroup Signal_Source_libs
00027  * \{ */
00028
00029 namespace GnssMetadata
00030 {
00031
00032 using StreamEncoding = unsigned char;
00033
00034 namespace StreamEncodings
```

```

00035 {
00036
00037 constexpr unsigned char SIGN = 0;
00038 constexpr unsigned char OB = 1;
00039 constexpr unsigned char SM = 2;
00040 constexpr unsigned char MS = 3;
00041 constexpr unsigned char TC = 4;
00042 constexpr unsigned char OG = 5;
00043 constexpr unsigned char OBA = 6;
00044 constexpr unsigned char SMA = 7;
00045 constexpr unsigned char MSA = 8;
00046 constexpr unsigned char TCA = 9;
00047 constexpr unsigned char OGA = 10;
00048 constexpr unsigned char FP = 11;
00049
00050 } // namespace StreamEncodings
00051
00052 inline StreamEncoding encoding_from_string(const std::string& str)
00053 {
00054     if (str == "SIGN")
00055     {
00056         return StreamEncodings::SIGN;
00057     }
00058     if (str == "OB")
00059     {
00060         return StreamEncodings::OB;
00061     }
00062     if (str == "SM")
00063     {
00064         return StreamEncodings::SM;
00065     }
00066     if (str == "MS")
00067     {
00068         return StreamEncodings::MS;
00069     }
00070     if (str == "TC")
00071     {
00072         return StreamEncodings::TC;
00073     }
00074     if (str == "OG")
00075     {
00076         return StreamEncodings::OG;
00077     }
00078     if (str == "OBA")
00079     {
00080         return StreamEncodings::OBA;
00081     }
00082     if (str == "SMA")
00083     {
00084         return StreamEncodings::SMA;
00085     }
00086     if (str == "MSA")
00087     {
00088         return StreamEncodings::MSA;
00089     }
00090     if (str == "TCA")
00091     {
00092         return StreamEncodings::TCA;
00093     }
00094     if (str == "OGA")
00095     {
00096         return StreamEncodings::OGA;
00097     }
00098     if (str == "FP")
00099     {
00100         return StreamEncodings::FP;
00101     }
00102     return 0;
00103 }
00104
00105 template <typename T>
00106 inline T two_bit_look_up[11][4]{
00107     {}, // [0]
00108     {-2, -1, 0, 1}, // [1 /*OB*/]
00109     {0, 1, 0, -1}, // [2 /*SM*/]
00110     {0, 0, 1, -1}, // [3 /*MS*/]
00111     {0, 1, -2, -1}, // [4 /*TC*/]
00112     {-2, -1, 1, 0}, // [5 /*OG*/]
00113     {-3, -1, 1, 3}, // [6 /*OBA*/]
00114     {1, 3, -1, -3}, // [7 /*SMA*/]
00115     {1, -1, 3, -3}, // [8 /*MSA*/]
00116     {1, 3, -3, -1}, // [9 /*TCA*/]
00117     {-3, -1, 3, 1}, // [10 /*OGA*/]
00118 };
00119
00120 template <typename T>
00121 inline T three_bit_look_up[11][8]{

```

```

00122     {}, // [0]
00123     {-4, -3, -2, -1, 0, 1, 2, 3}, // [1 /*OB*/]
00124     {0, 1, 2, 3, 0, -1, -2, -3}, // [2 /*SM*/]
00125     {0, 0, 1, -1, 0, 0, 1, -1}, // [3 /*MS*/]
00126     {0, 1, 2, 3, -4, -3, -2, -1}, // [4 /*TC*/]
00127     {-4, -3, -1, -2, 3, 2, 0, 1}, // [5 /*OG*/]
00128     {-7, -5, -3, -1, 1, 3, 5, 7}, // [6 /*OBA*/]
00129     {1, 3, 5, 7, -1, -3, -5, -7}, // [7 /*SMA*/]
00130     {1, -1, 3, -3, 5, -5, 7, -7}, // [8 /*MSA*/]
00131     {1, 3, 5, 7, -7, -5, -3, -1}, // [9 /*TCA*/]
00132     {-7, -5, -1, -3, 7, 5, 1, 3}, // [10 /*OGA*/]
00133 };
00134
00135 template <typename T>
00136 inline T four_bit_look_up[11][16]{
00137     {}, // [0]
00138     {-8, -7, -6, -5, -4, -3, -2, -1, 0, 1, 2, 3, 4, 5, 6, 7}, // [1 /*OB*/]
00139     {0, 1, 2, 3, 4, 5, 6, 7, 0, -1, -2, -3, -4, -5, -6, -7}, // [2 /*SM*/]
00140     {0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1}, // [3 /*MS*/]
00141     {0, 1, 2, 3, 4, 5, 6, 7, -8, -7, -6, -5, -4, -3, -2, -1}, // [4 /*TC*/]
00142     {-8, -7, -5, -6, -1, -2, -4, -3, 7, 6, 4, 5, 0, 1, 3, 2}, // [5 /*OG*/]
00143     {-15, -13, -11, -9, -7, -5, -3, -1, 1, 3, 5, 7, 9, 11, 13, 15}, // [6 /*OBA*/]
00144     {1, 3, 5, 7, 9, 11, 13, 15, -1, -3, -5, -7, -9, -11, -13, -15}, // [7 /*SMA*/]
00145     {1, -1, 3, -3, 5, -5, 7, -7, 9, -9, 11, -11, 13, -13, 15, -15}, // [8 /*MSA*/]
00146     {1, 3, 5, 7, 9, 11, 13, 15, -15, -13, -11, -9, -7, -5, -3, -1}, // [9 /*TCA*/]
00147     {-15, -13, -9, -11, -1, -3, -7, -5, 15, 13, 9, 11, 1, 3, 7, 5}, // [10 /*OGA*/]
00148 };
00149
00150 template <typename T>
00151 inline T five_bit_look_up[11][32]{
00152     {}, // [0]
00153     {-16, -15, -14, -13, -12, -11, -10, -9, -8, -7, -6, -5, -4, -3, -2, -1, 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15}, // [1 /*OB*/]
00154     {0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 0, -1, -2, -3, -4, -5, -6, -7, -8, -9, -10, -11, -12, -13, -14, -15}, // [2 /*SM*/]
00155     {0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1, 0, 0, 1, -1}, // [3 /*MS*/]
00156     {0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, -16, -15, -14, -13, -12, -11, -10, -9, -8, -7, -6, -5, -4, -3, -2, -1}, // [4 /*TC*/]
00157     {-16, -15, -13, -14, -9, -10, -12, -11, -1, -2, -4, -3, -8, -7, -5, -6, 15, 14, 12, 13, 8, 9, 11, 10, 0, 1, 3, 2, 7, 6, 4, 5}, // [5 /*OG*/]
00158     {-31, -29, -27, -25, -23, -21, -19, -17, -15, -13, -11, -9, -7, -5, -3, -1, 1, 3, 5, 7, 9, 11, 13, 15, 17, 19, 21, 23, 25, 27, 29, 31}, // [6 /*OBA*/]
00159     {1, 3, 5, 7, 9, 11, 13, 15, 17, 19, 21, 23, 25, 27, 29, 31, -1, -3, -5, -7, -9, -11, -13, -15, -17, -19, -21, -23, -25, -27, -29, -31}, // [7 /*SMA*/]
00160     {1, -1, 3, -3, 5, -5, 7, -7, 9, -9, 11, -11, 13, -13, 15, -15, 17, -17, 19, -19, 21, -21, 23, -23, 25, -25, 27, -27, 29, -29, 31, -31}, // [8 /*MSA*/]
00161     {1, 3, 5, 7, 9, 11, 13, 15, 17, 19, 21, 23, 25, 27, 29, 31, -31, -29, -27, -25, -23, -21, -19, -17, -15, -13, -11, -9, -7, -5, -3, -1}, // [9 /*TCA*/]
00162     {-31, -29, -25, -27, -17, -19, -23, -21, -1, -3, -7, -5, -15, -13, -9, -11, 31, 29, 25, 27, 17, 19, 23, 21, 1, 3, 7, 5, 15, 13, 9, 11}, // [10 /*OGA*/]
00163 };
00164
00165 } // namespace GnssMetadata
00166
00167
00168 /** \} */
00169 /** \} */
00170 #endif // GNSS_SDR_ION_GSMS_STREAM_ENCODINGS_H

```

13.446 pps_samplestamp.h File Reference

A simple container for the sample count associated to PPS rising edge.

```
#include <cstdint>
```

Classes

- class [PpsSamplestamp](#)

13.446.1 Detailed Description

A simple container for the sample count associated to PPS rising edge.

13.446.1.1 autotoc_md445

Author

Javier Arribas, jarribas(at)cttc.es

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 Definition in file [pps_samplestamp.h](#).

13.447 pps_samplestamp.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file pps_samplestamp.h
00003  * \brief A simple container for the sample count associated to PPS rising edge
00004  * \author Javier Arribas, jarribas(at)cttc.es
00005  * -----
00006  *
00007  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00011  * SPDX-License-Identifier: GPL-3.0-or-later
00012  *
00013  * -----
00014  */
00015
00016 #ifndef IOPPS_PPS_SAMPLESTAMP_H
00017 #define IOPPS_PPS_SAMPLESTAMP_H
00018
00019 #include <cstdint>
00020
00021 class PpsSamplestamp
00022 {
00023 public:
00024     uint64_t samplestamp = 0; // PPS rising edge samples counter from the beginning of rx stream
00025     uint32_t overflow_reg = 0; // >0 indicates overflow situation in the FPGA RX buffer
00026 };
00027
00028 #endif

```

13.448 ppstcprx.h File Reference

TCP client class for front-end PPS samplestamp information reception.

```

#include "concurrent_queue.h"
#include "pps_samplestamp.h"
#include <arpa/inet.h>
#include <memory>
#include <netinet/in.h>
#include <string>
#include <sys/socket.h>
#include <sys/types.h>

```

Classes

- class [pps_tcp_rx](#)

13.448.1 Detailed Description

TCP client class for front-end PPS samplestamp information reception.

13.448.1.1 autotoc_md447

Author

Javier Arribas, jarribas(at)cttc.es

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 Definition in file [ppstcprx.h](#).

13.449 ppstcprx.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file ppstcprx.h
00003  * \brief TCP client class for front-end PPS samplestamp information reception
00004  * \author Javier Arribas, jarribas(at)cttc.es
00005  * -----
00006  *
00007  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00009  *
00010  * Copyright (C) 2010-2023 (see AUTHORS file for a list of contributors)
00011  * SPDX-License-Identifier: GPL-3.0-or-later
00012  *
00013  * -----
00014  */
00015
00016 #ifndef SRC_LIBS_PPSTCPRX_H_
00017 #define SRC_LIBS_PPSTCPRX_H_
00018 #include "concurrent_queue.h"
00019 #include "pps_samplestamp.h"
00020 #include <arpa/inet.h>
00021 #include <memory>
00022 #include <netinet/in.h>
00023 #include <string>
00024 #include <sys/socket.h>
00025 #include <sys/types.h>
00026
00027 class pps_tcp_rx
00028 {
00029 private:
00030     std::shared_ptr<Concurrent_Queue<PpsSamplestamp>> Pps_queue;
00031     int clientSd{-1};
00032
00033 public:
00034     volatile bool is_connected{false};
00035     pps_tcp_rx() = default;
00036     virtual ~pps_tcp_rx() = default;
00037
00038     void receive_pps(const std::string& ip_address, int port);
00039     bool send_cmd(std::string cmd) const;
00040
00041     void set_pps_samplestamp_queue(std::shared_ptr<Concurrent_Queue<PpsSamplestamp>> queue);
00042 };
00043
00044 #endif /* SRC_LIBS_PPSTCPRX_H_ */

```

13.450 rtl_tcp_commands.h File Reference

Defines structures and constants for communicating with rtl_tcp.

```

#include <boost/asio/ip/tcp.hpp>
#include <boost/system/error_code.hpp>

```

Enumerations

- enum [RTL_TCP_COMMAND](#) {
 RTL_TCP_SET_FREQUENCY = 1 , RTL_TCP_SET_SAMPLE_RATE = 2 , RTL_TCP_SET_GAIN_MODE
 = 3 , RTL_TCP_SET_GAIN = 4 ,
 RTL_TCP_SET_IF_GAIN = 6 , RTL_TCP_SET_AGC_MODE = 8 }

Command IDs for configuration rtl_tcp.

Functions

- boost::system::error_code [rtl_tcp_command](#) (RTL_TCP_COMMAND id, unsigned param, boost::asio::ip::tcp::socket &socket)

Send a command to rtl_tcp over the given socket.

13.450.1 Detailed Description

Defines structures and constants for communicating with rtl_tcp.

Author

Anthony Arnold, 2015. anthony.arnold@uqconnect.edu.au

This file contains information taken from librtlsdr:

13.450.1.1 <https://git.osmocom.org/rtl-sdr>

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Definition in file [rtl_tcp_commands.h](#).

13.451 rtl_tcp_commands.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtl_tcp_commands.h
00003  * \brief Defines structures and constants for communicating with rtl_tcp
00004  * \author Anthony Arnold, 2015. anthony.arnold@uqconnect.edu.au
00005  *
00006  * This file contains information taken from librtlsdr:
00007  * https://git.osmocom.org/rtl-sdr
00008  * -----
00009  *
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00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_RTL_TCP_COMMANDS_H
00020 #define GNSS_SDR_RTL_TCP_COMMANDS_H
00021
00022 #include <boost/asio/ip/tcp.hpp> // for tcp, tcp::socket
00023 #include <boost/system/error_code.hpp> // for error_code
00024
00025 /** \addtogroup Signal_Source
00026  * \{ */
00027 /** \addtogroup Signal_Source_libs
00028  * \{ */
00029
00030
00031 /// Command IDs for configuration rtl_tcp
00032 enum RTL_TCP_COMMAND
00033 {
00034     RTL_TCP_SET_FREQUENCY = 1,
00035     RTL_TCP_SET_SAMPLE_RATE = 2,
00036     RTL_TCP_SET_GAIN_MODE = 3,
00037     RTL_TCP_SET_GAIN = 4,
00038     RTL_TCP_SET_IF_GAIN = 6,
00039     RTL_TCP_SET_AGC_MODE = 8
00040 };
00041
00042
00043 /*!
00044  * \brief Send a command to rtl_tcp over the given socket.
00045  */
00046 boost::system::error_code rtl_tcp_command(RTL_TCP_COMMAND id, unsigned param,
00047     boost::asio::ip::tcp::socket &socket);
00048
00049
00050 /** \} */
00051 /** \} */
00052 #endif // GNSS_SDR_RTL_TCP_COMMANDS_H
```

13.452 rtl_tcp_dongle_info.h File Reference

Interface for a structure sent by rtl_tcp defining the hardware.

```
#include <boost/asio/ip/tcp.hpp>
```

Classes

- class [Rtl_Tcp_Dongle_Info](#)

This class represents the dongle information which is sent by rtl_tcp.

13.452.1 Detailed Description

Interface for a structure sent by rtl_tcp defining the hardware.

Author

Anthony Arnold, 2015. [anthony.arnold\(at\)uqconnect.edu.au](mailto:anthony.arnold(at)uqconnect.edu.au)

This file contains information taken from librtlsdr:

13.452.1.1 <https://git.osmocom.org/rtl-sdr>

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Definition in file [rtl_tcp_dongle_info.h](#).

13.453 rtl_tcp_dongle_info.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file rtl_tcp_dongle_info.h
00003  * \brief Interface for a structure sent by rtl_tcp defining the hardware.
00004  * \author Anthony Arnold, 2015. anthony.arnold\(at\)uqconnect.edu.au
00005  *
00006  * This file contains information taken from librtlsdr:
00007  * https://git.osmocom.org/rtl-sdr
00008  * -----
00009  *
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00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_RTL_TCP_DONGLE_INFO_H
00020 #define GNSS_SDR_RTL_TCP_DONGLE_INFO_H
00021
00022 #include <boost/asio/ip/tcp.hpp>
00023
00024
00025 /** \addtogroup Signal_Source
00026  * \{ */
00027 /** \addtogroup Signal_Source_libs
00028  * \{ */
00029
00030
00031 /*!
00032  * \brief This class represents the dongle information
00033  * which is sent by rtl_tcp.
00034  */
00035 class Rtl_Tcp_Dongle_Info
00036 {
00037 public:
00038     enum
00039     {
00040         TUNER_UNKNOWN = 0,
00041         TUNER_E4000,
00042         TUNER_FC0012,
00043         TUNER_FC0013,
```

```

00044         TUNER_FC2580,
00045         TUNER_R820T,
00046         TUNER_R828D
00047     };
00048
00049     Rtl_Tcp_Dongle_Info();
00050
00051     boost::system::error_code read(boost::asio::ip::tcp::socket &socket);
00052
00053     bool is_valid() const;
00054
00055     const char *get_type_name() const;
00056
00057     double clip_gain(int gain) const;
00058
00059     inline uint32_t get_tuner_type() const
00060     {
00061         return tuner_type_;
00062     }
00063
00064     inline uint32_t get_tuner_gain_count() const
00065     {
00066         return tuner_gain_count_;
00067     }
00068
00069 private:
00070     char magic_[4]{};
00071     uint32_t tuner_type_;
00072     uint32_t tuner_gain_count_;
00073 };
00074
00075
00076 /** \} */
00077 /** \} */
00078 #endif // GNSS_SDR_RTL_TCP_DONGLE_INFO_H

```

13.454 beidou_b1i_telemetry_decoder.h File Reference

Interface of an adapter of a Beidou B1I NAV data decoder block to a [TelemetryDecoderInterface](#).

```

#include "telemetry_decoder_adapter_base.h"
#include <string>

```

Classes

- class [BeidouB1iTelemetryDecoder](#)

This class implements a NAV data decoder for BEIDOU B1I.

13.454.1 Detailed Description

Interface of an adapter of a Beidou B1I NAV data decoder block to a [TelemetryDecoderInterface](#).

Author

Damian Miralles, 2018. dmiralles2009@gmail.com

Sergi Segura, 2018. [sergi.segura.munoz\(at\)gmail.com](mailto:sergi.segura.munoz(at)gmail.com)

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 Definition in file [beidou_b1i_telemetry_decoder.h](#).

13.455 beidou_b1i_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file beidou_b1i_telemetry_decoder.h
00003  * \brief Interface of an adapter of a Beidou B1I NAV data decoder block
00004  * to a TelemetryDecoderInterface
00005  * \author Damian Miralles, 2018. dmiralles2009@gmail.com
00006  * \author Sergi Segura, 2018. sergi.segura.munoz\(at\)gmail.com
00007  *
00008  * -----

```

```

00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00015  *
00016  * -----
00017  */
00018
00019
00020 #ifndef GNSS_SDR_BEIDOU_B1I_TELEMETRY_DECODER_H
00021 #define GNSS_SDR_BEIDOU_B1I_TELEMETRY_DECODER_H
00022
00023
00024 #include "telemetry_decoder_adapter_base.h"
00025 #include <string>
00026
00027 /** \addtogroup Telemetry_Decoder
00028  * \{ */
00029 /** \addtogroup Telemetry_Decoder_adapters
00030  * \{ */
00031
00032
00033 /*!
00034  * \brief This class implements a NAV data decoder for BEIDOU B1I
00035  */
00036 class BeidouB1iTelemetryDecoder : public TelemetryDecoderAdapterBase
00037 {
00038 public:
00039     BeidouB1iTelemetryDecoder(
00040         const ConfigurationInterface* configuration,
00041         const std::string& role,
00042         unsigned int in_streams,
00043         unsigned int out_streams);
00044
00045     //! Returns "BEIDOU_B1I_Telemetry_Decoder"
00046     inline std::string implementation() override
00047     {
00048         return "BEIDOU_B1I_Telemetry_Decoder";
00049     }
00050 };
00051
00052
00053 /** \} */
00054 /** \} */
00055 #endif

```

13.456 beidou_b3i_telemetry_decoder.h File Reference

Interface of an adapter of a Beidou B3I NAV data decoder block to a [TelemetryDecoderInterface](#).

```

#include "telemetry_decoder_adapter_base.h"
#include <string>

```

Classes

- class [BeidouB3iTelemetryDecoder](#)
This class implements a NAV data decoder for BEIDOU B1I.

13.456.1 Detailed Description

Interface of an adapter of a Beidou B3I NAV data decoder block to a [TelemetryDecoderInterface](#).

Author

Damian Miralles, 2019. dmiralles2009@gmail.com

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 Definition in file [beidou_b3i_telemetry_decoder.h](#).

13.457 beidou_b3i_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file beidou_b3i_telemetry_decoder.h
00003  * \brief Interface of an adapter of a Beidou B3I NAV data decoder block
00004  * to a TelemetryDecoderInterface
00005  * \author Damian Miralles, 2019. dmiralles2009@gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_BEIDOU_B3I_TELEMETRY_DECODER_H
00019 #define GNSS_SDR_BEIDOU_B3I_TELEMETRY_DECODER_H
00020
00021
00022 #include "telemetry_decoder_adapter_base.h"
00023 #include <string>
00024
00025
00026 /** \addtogroup Telemetry_Decoder
00027  * \{ */
00028 /** \addtogroup Telemetry_Decoder_adapters
00029  * \{ */
00030
00031
00032 /*!
00033  * \brief This class implements a NAV data decoder for BEIDOU B1I
00034  */
00035 class BeidouB3iTelemetryDecoder : public TelemetryDecoderAdapterBase
00036 {
00037 public:
00038     BeidouB3iTelemetryDecoder(
00039         const ConfigurationInterface *configuration,
00040         const std::string &role, unsigned int in_streams,
00041         unsigned int out_streams);
00042
00043     //! Returns "BEIDOU_B3I_Telemetry_Decoder"
00044     inline std::string implementation() override
00045     {
00046         return "BEIDOU_B3I_Telemetry_Decoder";
00047     }
00048 };
00049
00050 /** \} */
00051 /** \} */
00052 #endif

```

13.458 galileo_e1b_telemetry_decoder.h File Reference

Interface of an adapter of a GALILEO E1B NAV data decoder block to a [TelemetryDecoderInterface](#).

```

#include "telemetry_decoder_adapter_base.h"
#include <string>

```

Classes

- class [GalileoE1BTelemetryDecoder](#)

This class implements a NAV data decoder for Galileo INAV frames in E1B radio link.

13.458.1 Detailed Description

Interface of an adapter of a GALILEO E1B NAV data decoder block to a [TelemetryDecoderInterface](#).

Author

Javier Arribas 2013 jarribas(at)cttc.es, Mara Branzanti 2013. mara.branzanti(at)gmail.com

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 Definition in file [galileo_e1b_telemetry_decoder.h](#).

13.459 galileo_e1b_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_e1b_telemetry_decoder.h
00003  * \brief Interface of an adapter of a GALILEO E1B NAV data decoder block
00004  * to a TelemetryDecoderInterface
00005  * \author Javier Arribas 2013 jarribas(at)cttc.es,
00006  * Mara Branzanti 2013. mara.branzanti(at)gmail.com
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019
00020 #ifndef GNSS_SDR_GALILEO_E1B_TELEMETRY_DECODER_H
00021 #define GNSS_SDR_GALILEO_E1B_TELEMETRY_DECODER_H
00022
00023
00024 #include "telemetry_decoder_adapter_base.h"
00025 #include <string>
00026
00027 /** \addtogroup Telemetry_Decoder
00028  * \{ */
00029 /** \addtogroup Telemetry_Decoder_adapters
00030  * \{ */
00031
00032
00033 /*!
00034 * \brief This class implements a NAV data decoder for Galileo INAV frames in E1B radio link
00035 */
00036 class GalileoE1BTelemetryDecoder : public TelemetryDecoderAdapterBase
00037 {
00038 public:
00039     GalileoE1BTelemetryDecoder(
00040         const ConfigurationInterface* configuration,
00041         const std::string& role,
00042         unsigned int in_streams,
00043         unsigned int out_streams);
00044
00045     /*!
00046     * \brief Returns "Galileo_E1B_Telemetry_Decoder"
00047     */
00048     inline std::string implementation() override
00049     {
00050         return "Galileo_E1B_Telemetry_Decoder";
00051     }
00052 };
00053
00054
00055 /** \} */
00056 /** \} */
00057 #endif // GNSS_SDR_GALILEO_E1B_TELEMETRY_DECODER_H

```

13.460 galileo_e5a_telemetry_decoder.h File Reference

Interface of an adapter of a GALILEO E5a FNAV data decoder block to a [TelemetryDecoderInterface](#).

```

#include "telemetry_decoder_adapter_base.h"
#include <string>

```

Classes

- class [GalileoE5aTelemetryDecoder](#)

This class implements a NAV data decoder for Galileo INAV frames in E1B radio link.

13.460.1 Detailed Description

Interface of an adapter of a GALILEO E5a FNAV data decoder block to a [TelemetryDecoderInterface](#).

Author

Marc Sales, 2014. marcsales92(at)gmail.com \based on work from:

- Javier Arribas, 2011. jarribas(at)cttc.es

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Definition in file [galileo_e5a_telemetry_decoder.h](#).

13.461 galileo_e5a_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_e5a_telemetry_decoder.h
00003  * \brief Interface of an adapter of a GALILEO E5a FNAV data decoder block
00004  * to a TelemetryDecoderInterface
00005  * \author Marc Sales, 2014. marcsales92(at)gmail.com
00006  * \based on work from:
00007  *      <ul>
00008  *          <li> Javier Arribas, 2011. jarribas(at)cttc.es
00009  *      </ul>
00010  *
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.
00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_GALILEO_E5A_TELEMETRY_DECODER_H
00024 #define GNSS_SDR_GALILEO_E5A_TELEMETRY_DECODER_H
00025
00026
00027 #include "telemetry_decoder_adapter_base.h"
00028 #include <string>
00029
00030 /** \addtogroup Telemetry_Decoder
00031  * \{ */
00032 /** \addtogroup Telemetry_Decoder_adapters
00033  * \{ */
00034
00035  /*!
00036  * \brief This class implements a NAV data decoder for Galileo INAV frames in E1B radio link
00037  */
00038  class GalileoE5aTelemetryDecoder : public TelemetryDecoderAdapterBase
00039  {
00040  public:
00041      GalileoE5aTelemetryDecoder(
00042          const ConfigurationInterface* configuration,
00043          const std::string& role,
00044          unsigned int in_streams,
00045          unsigned int out_streams);
00046
00047      /*!
00048      * \brief Returns "Galileo_E5a_Telemetry_Decoder"
00049      */
00050      inline std::string implementation() override
00051      {
00052          return "Galileo_E5A_Telemetry_Decoder";
00053      }
00054  };
00055
00056
00057 /** \} */
00058 /** \} */
00059 #endif // GNSS_SDR_GALILEO_E5A_TELEMETRY_DECODER_H

```

13.462 galileo_e5b_telemetry_decoder.h File Reference

Interface of an adapter of a GALILEO E5B NAV data decoder block to a [TelemetryDecoderInterface](#).

```

#include "telemetry_decoder_adapter_base.h"
#include <string>

```

Classes

- class [GalileoE5bTelemetryDecoder](#)

This class implements a NAV data decoder for Galileo INAV frames in E5b radio link.

13.462.1 Detailed Description

Interface of an adapter of a GALILEO E5B NAV data decoder block to a [TelemetryDecoderInterface](#).

Author

Piyush Gupta 2020 piyush04111999@gmail.com.

Note

Code added as part of GSoC 2020 Program.

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 Definition in file [galileo_e5b_telemetry_decoder.h](#).

13.463 galileo_e5b_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_e5b_telemetry_decoder.h
00003  * \brief Interface of an adapter of a GALILEO E5B NAV data decoder block
00004  * to a TelemetryDecoderInterface
00005  * \author Piyush Gupta 2020 piyush04111999@gmail.com.
00006  * \note Code added as part of GSoC 2020 Program.
00007  *
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020
00021 #ifndef GNSS_SDR_GALILEO_E5B_TELEMETRY_DECODER_H
00022 #define GNSS_SDR_GALILEO_E5B_TELEMETRY_DECODER_H
00023
00024 #include "telemetry_decoder_adapter_base.h"
00025 #include <string>
00026
00027 /** \addtogroup Telemetry_Decoder
00028  * \{ */
00029 /** \addtogroup Telemetry_Decoder_adapters
00030  * \{ */
00031
00032
00033  /*!
00034  * \brief This class implements a NAV data decoder for Galileo INAV frames in E5b radio link
00035  */
00036  class GalileoE5bTelemetryDecoder : public TelemetryDecoderAdapterBase
00037  {
00038  public:
00039      GalileoE5bTelemetryDecoder(
00040          const ConfigurationInterface* configuration,
00041          const std::string& role,
00042          unsigned int in_streams,
00043          unsigned int out_streams);
00044
00045      /*!
00046      * \brief Returns "Galileo_E5b_Telemetry_Decoder"
00047      */
00048      inline std::string implementation() override
00049      {
00050          return "Galileo_E5b_Telemetry_Decoder";
00051      }
00052  };
00053

```

```

00054
00055 /** \} */
00056 /** \} */
00057 #endif // GNSS_SDR_GALILEO_E5B_TELEMETRY_DECODER_H

```

13.464 galileo_e6_telemetry_decoder.h File Reference

Interface of an adapter of a GALILEO E6 CNAV data decoder block to a [TelemetryDecoderInterface](#).

```

#include "telemetry_decoder_adapter_base.h"
#include <string>

```

Classes

- class [GalileoE6TelemetryDecoder](#)

This class implements a NAV data decoder for Galileo CNAV frames in E6 radio link.

13.464.1 Detailed Description

Interface of an adapter of a GALILEO E6 CNAV data decoder block to a [TelemetryDecoderInterface](#).

Author

Carles Fernandez-Prades, 2020 cfernandez@cttc.es

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Definition in file [galileo_e6_telemetry_decoder.h](#).

13.465 galileo_e6_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_e6_telemetry_decoder.h
00003  * \brief Interface of an adapter of a GALILEO E6 CNAV data decoder block
00004  * to a TelemetryDecoderInterface
00005  * \author Carles Fernandez-Prades, 2020 cfernandez@cttc.es
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019
00020 #ifndef GNSS_SDR_GALILEO_E6_TELEMETRY_DECODER_H
00021 #define GNSS_SDR_GALILEO_E6_TELEMETRY_DECODER_H
00022
00023 #include "telemetry_decoder_adapter_base.h"
00024 #include <string>
00025
00026 /** \addtogroup Telemetry_Decoder
00027  * \{ */
00028 /** \addtogroup Telemetry_Decoder_adapters
00029  * \{ */
00030
00031
00032 /*!
00033  * \brief This class implements a NAV data decoder for Galileo CNAV frames in E6 radio link
00034  */
00035 class GalileoE6TelemetryDecoder : public TelemetryDecoderAdapterBase
00036 {
00037 public:
00038     GalileoE6TelemetryDecoder(
00039         const ConfigurationInterface* configuration,
00040         const std::string& role,
00041         unsigned int in_streams,

```

```

00042         unsigned int out_streams);
00043
00044     /*!
00045     * \brief Returns "Galileo_E6_Telemetry_Decoder"
00046     */
00047     inline std::string implementation() override
00048     {
00049         return "Galileo_E6_Telemetry_Decoder";
00050     }
00051 };
00052
00053
00054 /** @} */
00055 /** @} */
00056 #endif // GNSS_SDR_GALILEO_E6_TELEMETRY_DECODER_H

```

13.466 glonass_l1_ca_telemetry_decoder.h File Reference

Interface of an adapter of a GLONASS L1 C/A NAV data decoder block to a [TelemetryDecoderInterface](#).

```
#include "telemetry_decoder_adapter_base.h"
```

```
#include <string>
```

Classes

- class [GlonassL1CaTelemetryDecoder](#)

This class implements a NAV data decoder for GLONASS L1 C/A.

13.466.1 Detailed Description

Interface of an adapter of a GLONASS L1 C/A NAV data decoder block to a [TelemetryDecoderInterface](#).

Note

Code added as part of GSoC 2017 program

Author

Damian Miralles, 2017. dmiralles2009(at)gmail.com

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Definition in file [glonass_l1_ca_telemetry_decoder.h](#).

13.467 glonass_l1_ca_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file glonass_l1_ca_telemetry_decoder.h
00003 * \brief Interface of an adapter of a GLONASS L1 C/A NAV data decoder block
00004 * to a TelemetryDecoderInterface
00005 * \note Code added as part of GSoC 2017 program
00006 * \author Damian Miralles, 2017. dmiralles2009(at)gmail.com
00007 *
00008 * -----
00009 *
00010 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011 * This file is part of GNSS-SDR.
00012 *
00013 * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014 * SPDX-License-Identifier: GPL-3.0-or-later
00015 *
00016 * -----
00017 */
00018
00019
00020 #ifndef GNSS_SDR_GLOASS_L1_CA_TELEMETRY_DECODER_H
00021 #define GNSS_SDR_GLOASS_L1_CA_TELEMETRY_DECODER_H
00022
00023 #include "telemetry_decoder_adapter_base.h"
00024 #include <string>

```

```

00025
00026 /** \addtogroup Telemetry_Decoder
00027 * \{ */
00028 /** \addtogroup Telemetry_Decoder_adapters
00029 * \{ */
00030
00031
00032 /**
00033 * \brief This class implements a NAV data decoder for GLONASS L1 C/A
00034 */
00035 class GlonassL1CaTelemetryDecoder : public TelemetryDecoderAdapterBase
00036 {
00037 public:
00038     GlonassL1CaTelemetryDecoder(
00039         const ConfigurationInterface* configuration,
00040         const std::string& role,
00041         unsigned int in_streams,
00042         unsigned int out_streams);
00043
00044     //! Returns "GLONASS_L1_CA_Telemetry_Decoder"
00045     inline std::string implementation() override
00046     {
00047         return "GLONASS_L1_CA_Telemetry_Decoder";
00048     }
00049 };
00050
00051
00052 /** \} */
00053 /** \} */
00054 #endif

```

13.468 glonass_l2_ca_telemetry_decoder.h File Reference

Interface of an adapter of a GLONASS L2 C/A NAV data decoder block to a [TelemetryDecoderInterface](#).

```

#include "telemetry_decoder_adapter_base.h"
#include <string>

```

Classes

- class [GlonassL2CaTelemetryDecoder](#)

This class implements a NAV data decoder for GLONASS L2 C/A.

13.468.1 Detailed Description

Interface of an adapter of a GLONASS L2 C/A NAV data decoder block to a [TelemetryDecoderInterface](#).

Author

Damian Miralles, 2018. [dmiralles2009\(at\)gmail.com](mailto:dmiralles2009(at)gmail.com)

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 Definition in file [glonass_l2_ca_telemetry_decoder.h](#).

13.469 glonass_l2_ca_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001 /**
00002 * \file glonass_l2_ca_telemetry_decoder.h
00003 * \brief Interface of an adapter of a GLONASS L2 C/A NAV data decoder block
00004 * to a TelemetryDecoderInterface
00005 * \author Damian Miralles, 2018. dmiralles2009(at)gmail.com
00006 *
00007 * -----
00008 *
00009 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010 * This file is part of GNSS-SDR.
00011 *
00012 * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013 * SPDX-License-Identifier: GPL-3.0-or-later
00014 *
00015 * -----

```

```

00016 */
00017
00018
00019 #ifndef GNSS_SDR_GLONASS_L2_CA_TELEMETRY_DECODER_H
00020 #define GNSS_SDR_GLONASS_L2_CA_TELEMETRY_DECODER_H
00021
00022 #include "telemetry_decoder_adapter_base.h"
00023 #include <string>
00024
00025 /** \addtogroup Telemetry_Decoder
00026 * \{ */
00027 /** \addtogroup Telemetry_Decoder_adapters
00028 * \{ */
00029
00030
00031 /*!
00032 * \brief This class implements a NAV data decoder for GLONASS L2 C/A
00033 */
00034 class GlonassL2CaTelemetryDecoder : public TelemetryDecoderAdapterBase
00035 {
00036 public:
00037     GlonassL2CaTelemetryDecoder(
00038         const ConfigurationInterface* configuration,
00039         const std::string& role,
00040         unsigned int in_streams,
00041         unsigned int out_streams);
00042
00043     //! Returns "GLONASS_L2_CA_Telemetry_Decoder"
00044     inline std::string implementation() override
00045     {
00046         return "GLONASS_L2_CA_Telemetry_Decoder";
00047     }
00048 };
00049
00050
00051 /** \} */
00052 /** \} */
00053 #endif // GNSS_SDR_GLONASS_L2_CA_TELEMETRY_DECODER_H

```

13.470 gps_l1_ca_telemetry_decoder.h File Reference

Interface of an adapter of a GPS L1 C/A NAV data decoder block to a [TelemetryDecoderInterface](#).

```

#include "telemetry_decoder_adapter_base.h"
#include <string>

```

Classes

- class [GpsL1CaTelemetryDecoder](#)

This class implements a NAV data decoder for GPS L1 C/A.

13.470.1 Detailed Description

Interface of an adapter of a GPS L1 C/A NAV data decoder block to a [TelemetryDecoderInterface](#).

Author

Javier Arribas, 2011. jarribas(at)cttc.es

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 Definition in file [gps_l1_ca_telemetry_decoder.h](#).

13.471 gps_l1_ca_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file gps_l1_ca_telemetry_decoder.h
00003 * \brief Interface of an adapter of a GPS L1 C/A NAV data decoder block
00004 * to a TelemetryDecoderInterface
00005 * \author Javier Arribas, 2011. jarribas(at)cttc.es
00006 *
00007 * -----

```

```

00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GPS_L1_CA_TELEMETRY_DECODER_H
00020 #define GNSS_SDR_GPS_L1_CA_TELEMETRY_DECODER_H
00021
00022 #include "telemetry_decoder_adapter_base.h"
00023 #include <string>
00024
00025 /** \addtogroup Telemetry_Decoder Telemetry Decoder
00026  * Classes for the decoding of GNSS Navigation messages.
00027  * \{ */
00028 /** \addtogroup Telemetry_Decoder_adapters telemetry_decoder_adapters
00029  * Wrap GNU Radio blocks for the decoding of GNSS Navigation messages with a
00030  * TelemetryDecoderInterface
00031  * \{ */
00032
00033
00034 /*!
00035  * \brief This class implements a NAV data decoder for GPS L1 C/A
00036  */
00037 class GpsL1CaTelemetryDecoder : public TelemetryDecoderAdapterBase
00038 {
00039 public:
00040     GpsL1CaTelemetryDecoder(
00041         const ConfigurationInterface* configuration,
00042         const std::string& role,
00043         unsigned int in_streams,
00044         unsigned int out_streams);
00045
00046     /*! Returns "GPS_L1_CA_Telemetry_Decoder"
00047     inline std::string implementation() override
00048     {
00049         return "GPS_L1_CA_Telemetry_Decoder";
00050     }
00051 };
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_GPS_L1_CA_TELEMETRY_DECODER_H

```

13.472 gps_l2c_telemetry_decoder.h File Reference

Interface of an adapter of a GPS L2C (CNAV) data decoder block to a [TelemetryDecoderInterface](#).

```

#include "telemetry_decoder_adapter_base.h"
#include <string>

```

Classes

- class [GpsL2CTelemetryDecoder](#)
This class implements a NAV data decoder for GPS L2 M.

13.472.1 Detailed Description

Interface of an adapter of a GPS L2C (CNAV) data decoder block to a [TelemetryDecoderInterface](#).

Author

Javier Arribas, 2015. jarribas(at)cttc.es

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 Definition in file [gps_l2c_telemetry_decoder.h](#).

13.473 gps_l2c_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gps_l2c_telemetry_decoder.h
00003  * \brief Interface of an adapter of a GPS L2C (CNAV) data decoder block
00004  * to a TelemetryDecoderInterface
00005  * \author Javier Arribas, 2015. jarribas(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GPS_L2C_TELEMETRY_DECODER_H
00020 #define GNSS_SDR_GPS_L2C_TELEMETRY_DECODER_H
00021
00022 #include "telemetry_decoder_adapter_base.h"
00023 #include <string>
00024
00025
00026 /** \addtogroup Telemetry_Decoder
00027  * \{ */
00028 /** \addtogroup Telemetry_Decoder_adapters
00029  * \{ */
00030
00031
00032 /*!
00033  * \brief This class implements a NAV data decoder for GPS L2 M
00034  */
00035 class GpsL2CTelemetryDecoder : public TelemetryDecoderAdapterBase
00036 {
00037 public:
00038     GpsL2CTelemetryDecoder(
00039         const ConfigurationInterface* configuration,
00040         const std::string& role,
00041         unsigned int in_streams,
00042         unsigned int out_streams);
00043
00044     /*! Returns "GPS_L2C_Telemetry_Decoder"
00045     inline std::string implementation() override
00046     {
00047         return "GPS_L2C_Telemetry_Decoder";
00048     }
00049     */;
00050
00051
00052 /** \} */
00053 /** \} */
00054 #endif // GNSS_SDR_GPS_L2C_TELEMETRY_DECODER_H

```

13.474 gps_l5_telemetry_decoder.h File Reference

Interface of an adapter of a GPS L5 (CNAV) data decoder block to a [TelemetryDecoderInterface](#).

```

#include "telemetry_decoder_adapter_base.h"
#include <string>

```

Classes

- class [GpsL5TelemetryDecoder](#)

This class implements a NAV data decoder for GPS L5.

13.474.1 Detailed Description

Interface of an adapter of a GPS L5 (CNAV) data decoder block to a [TelemetryDecoderInterface](#).

Author

Antonio Ramos, 2017. antonio.ramos(at)cttc.es

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Definition in file [gps_l5_telemetry_decoder.h](#).

13.475 gps_l5_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002   * \file gps_l5_telemetry_decoder.h
00003   * \brief Interface of an adapter of a GPS L5 (CNAV) data decoder block
00004   * to a TelemetryDecoderInterface
00005   * \author Antonio Ramos, 2017. antonio.ramos(at)cttc.es
00006   *
00007   * -----
00008   *
00009   * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010   * This file is part of GNSS-SDR.
00011   *
00012   * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013   * SPDX-License-Identifier: GPL-3.0-or-later
00014   *
00015   * -----
00016   */
00017
00018
00019 #ifndef GNSS_SDR_GPS_L5_TELEMETRY_DECODER_H
00020 #define GNSS_SDR_GPS_L5_TELEMETRY_DECODER_H
00021
00022
00023 #include "telemetry_decoder_adapter_base.h"
00024 #include <string>
00025
00026 /** \addtogroup Telemetry_Decoder
00027  * \{ */
00028 /** \addtogroup Telemetry_Decoder_adapters
00029  * \{ */
00030
00031 /*!
00032  * \brief This class implements a NAV data decoder for GPS L5
00033  */
00034 class GpsL5TelemetryDecoder : public TelemetryDecoderAdapterBase
00035 {
00036 public:
00037     GpsL5TelemetryDecoder(
00038         const ConfigurationInterface* configuration,
00039         const std::string& role,
00040         unsigned int in_streams,
00041         unsigned int out_streams);
00042
00043     //! Returns "GPS_L5_Telemetry_Decoder"
00044     inline std::string implementation() override
00045     {
00046         return "GPS_L5_Telemetry_Decoder";
00047     }
00048 };
00049
00050
00051 /** \} */
00052 /** \} */
00053 #endif // GNSS_SDR_GPS_L5_TELEMETRY_DECODER_H

```

13.476 qzss_l1_telemetry_decoder.h File Reference

Interface of an adapter of a QZSS L1 NAV data decoder block to a [TelemetryDecoderInterface](#).

```

#include "telemetry_decoder_adapter_base.h"
#include <string>

```

Classes

- class [QzssL1TelemetryDecoder](#)

This class implements a NAV data decoder for QZSS L1.

13.476.1 Detailed Description

Interface of an adapter of a QZSS L1 NAV data decoder block to a [TelemetryDecoderInterface](#).

Author

Carles Fernandez-Prades, 2026. cfernandez(at)cttc.es

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Definition in file [qzss_l1_telemetry_decoder.h](#).

13.477 qzss_l1_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file qzss_l1_telemetry_decoder.h
00003  * \brief Interface of an adapter of a QZSS L1 NAV data decoder block
00004  * to a TelemetryDecoderInterface
00005  * \author Carles Fernandez-Prades, 2026. cfernandez(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2026 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_QZSS_L1_TELEMETRY_DECODER_H
00020 #define GNSS_SDR_QZSS_L1_TELEMETRY_DECODER_H
00021
00022 #include "telemetry_decoder_adapter_base.h"
00023 #include <string>
00024
00025 /** \addtogroup Telemetry_Decoder Telemetry Decoder
00026  * Classes for the decoding of GNSS Navigation messages.
00027  * \{ */
00028 /** \addtogroup Telemetry_Decoder_adapters telemetry_decoder_adapters
00029  * Wrap GNU Radio blocks for the decoding of GNSS Navigation messages with a
00030  * TelemetryDecoderInterface
00031  * \{ */
00032
00033
00034 /*!
00035  * \brief This class implements a NAV data decoder for QZSS L1
00036  */
00037 class QzssL1TelemetryDecoder : public TelemetryDecoderAdapterBase
00038 {
00039 public:
00040     QzssL1TelemetryDecoder(
00041         const ConfigurationInterface* configuration,
00042         const std::string& role,
00043         unsigned int in_streams,
00044         unsigned int out_streams);
00045
00046     /*! Returns "QZSS_L1_Telemetry_Decoder"
00047     inline std::string implementation() override
00048     {
00049         return "QZSS_L1_Telemetry_Decoder";
00050     }
00051 };
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_QZSS_L1_TELEMETRY_DECODER_H

```

13.478 qzss_l5_telemetry_decoder.h File Reference

Interface of an adapter of a QZSS L5 NAV data decoder block to a [TelemetryDecoderInterface](#).

```
#include "telemetry_decoder_adapter_base.h"
```

```
#include <string>
```

Classes

- class [QzssL5TelemetryDecoder](#)

This class implements a NAV data decoder for QZSS L5.

13.478.1 Detailed Description

Interface of an adapter of a QZSS L5 NAV data decoder block to a [TelemetryDecoderInterface](#).

Author

Carles Fernandez-Prades, 2026. cfernandez(at)cttc.es

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Definition in file [qzss_l5_telemetry_decoder.h](#).

13.479 qzss_l5_telemetry_decoder.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002   * \file qzss_l5_telemetry_decoder.h
00003   * \brief Interface of an adapter of a QZSS L5 NAV data decoder block
00004   * to a TelemetryDecoderInterface
00005   * \author Carles Fernandez-Prades, 2026. cfernandez(at)cttc.es
00006   *
00007   * -----
00008   *
00009   * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014   *
00015   * -----
00016   */
00017
00018
00019 #ifndef GNSS_SDR_QZSS_L5_TELEMETRY_DECODER_H
00020 #define GNSS_SDR_QZSS_L5_TELEMETRY_DECODER_H
00021
00022 #include "telemetry_decoder_adapter_base.h"
00023 #include <string>
00024
00025 /** \addtogroup Telemetry_Decoder Telemetry Decoder
00026  * Classes for the decoding of GNSS Navigation messages.
00027  * \{ */
00028 /** \addtogroup Telemetry_Decoder_adapters telemetry_decoder_adapters
00029  * Wrap GNU Radio blocks for the decoding of GNSS Navigation messages with a
00030  * TelemetryDecoderInterface
00031  * \{ */
00032
00033
00034 /*!
00035  * \brief This class implements a NAV data decoder for QZSS L5
00036  */
00037 class QzssL5TelemetryDecoder : public TelemetryDecoderAdapterBase
00038 {
00039 public:
00040     QzssL5TelemetryDecoder(
00041         const ConfigurationInterface* configuration,
00042         const std::string& role,
00043         unsigned int in_streams,
00044         unsigned int out_streams);
00045
00046     //! Returns "QZSS_L5_Telemetry_Decoder"
00047     inline std::string implementation() override
00048     {
00049         return "QZSS_L5_Telemetry_Decoder";
00050     }
00051 };
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_QZSS_L5_TELEMETRY_DECODER_H

```

13.480 sbas_l1_telemetry_decoder.h File Reference

Interface of an adapter of a SBAS telemetry data decoder block to a [TelemetryDecoderInterface](#).

```
#include "telemetry_decoder_adapter_base.h"
#include <string>
```

Classes

- class [SbasL1TelemetryDecoder](#)

This class implements a NAV data decoder for SBAS frames in L1 radio link.

13.480.1 Detailed Description

Interface of an adapter of a SBAS telemetry data decoder block to a [TelemetryDecoderInterface](#).

Author

Daniel Fehr 2013. daniel.co(at)bluewin.ch

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 Definition in file [sbas_l1_telemetry_decoder.h](#).

13.481 sbas_l1_telemetry_decoder.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file sbas_l1_telemetry_decoder.h
00003  * \brief Interface of an adapter of a SBAS telemetry data decoder block
00004  * to a TelemetryDecoderInterface
00005  * \author Daniel Fehr 2013. daniel.co(at)bluewin.ch
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_SBAS_L1_TELEMETRY_DECODER_H
00020 #define GNSS_SDR_SBAS_L1_TELEMETRY_DECODER_H
00021
00022
00023 #include "telemetry_decoder_adapter_base.h"
00024 #include <string>
00025
00026 /** \addtogroup Telemetry_Decoder
00027  * \{ */
00028 /** \addtogroup Telemetry_Decoder_adapters
00029  * \{ */
00030
00031
00032 /*!
00033  * \brief This class implements a NAV data decoder for SBAS frames in L1 radio link
00034  */
00035 class SbasL1TelemetryDecoder : public TelemetryDecoderAdapterBase
00036 {
00037 public:
00038     SbasL1TelemetryDecoder(
00039         const ConfigurationInterface* configuration,
00040         const std::string& role,
00041         unsigned int in_streams,
00042         unsigned int out_streams);
00043
00044     /*!
00045     * \brief Returns "SBAS_L1_Telemetry_Decoder"
00046     */
00047     inline std::string implementation() override
00048     {
```

```

00049         return "SBAS_L1_Telemetry_Decoder";
00050     }
00051
00052 private:
00053     std::string dump_filename_;
00054     bool dump_;
00055 };
00056
00057
00058 /** \} */
00059 /** \} */
00060 #endif // GNSS_SDR_SBAS_L1_TELEMETRY_DECODER_H

```

13.482 telemetry_decoder_adapter_base.h File Reference

Common functionality for telemetry decoder adapters.

```

#include "configuration_interface.h"
#include "gnss_satellite.h"
#include "gnss_synchro.h"
#include "telemetry_decoder_interface.h"
#include "telemetry_impl_interface.h"
#include "tlm_conf.h"
#include <gnuradio/runtime_types.h>
#include <cstdio>
#include <string>

```

Classes

- class [TelemetryDecoderAdapterBase](#)
Base class for Telemetry Decoder adapters.

13.482.1 Detailed Description

Common functionality for telemetry decoder adapters.

Author

Carles Fernandez-Prades, 2025 cfernandez@cttc.es

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 Definition in file [telemetry_decoder_adapter_base.h](#).

13.483 telemetry_decoder_adapter_base.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file telemetry_decoder_adapter_base.h
00003  * \brief Common functionality for telemetry decoder adapters
00004  * \author Carles Fernandez-Prades, 2025 cfernandez@cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2025 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_TELEMETRY_DECODER_ADAPTER_BASE_H
00018 #define GNSS_SDR_TELEMETRY_DECODER_ADAPTER_BASE_H
00019
00020 #include "configuration_interface.h"
00021 #include "gnss_satellite.h"
00022 #include "gnss_synchro.h"

```

```

00023 #include "telemetry_decoder_interface.h"
00024 #include "telemetry_impl_interface.h"
00025 #include "tlm_conf.h"
00026 #include <gnuradio/runtime_types.h>
00027 #include <cstdint>
00028 #include <string>
00029
00030 class ConfigurationInterface;
00031
00032 /** \addtogroup Telemetry_Decoder
00033  * \{
00034  */
00035 /** \addtogroup Telemetry_Decoder_adapters
00036  * \{
00037  */
00038
00039 /**
00040  * \brief Base class for Telemetry Decoder adapters
00041  */
00042 class TelemetryDecoderAdapterBase : public TelemetryDecoderInterface
00043 {
00044 public:
00045     TelemetryDecoderAdapterBase(const ConfigurationInterface* configuration,
00046                                const std::string& role,
00047                                unsigned int in_streams,
00048                                unsigned int out_streams);
00049
00050     ~TelemetryDecoderAdapterBase() override = default;
00051
00052     void connect(gr::top_block_sptr top_block) override;
00053
00054     void disconnect(gr::top_block_sptr top_block) override;
00055
00056     gr::basic_block_sptr get_left_block() override;
00057
00058     gr::basic_block_sptr get_right_block() override;
00059
00060     void set_satellite(const Gnss_Satellite& satellite) override;
00061
00062     std::string role() override;
00063
00064     void set_channel(int channel) override;
00065
00066     void reset() override;
00067
00068     size_t item_size() override;
00069
00070 protected:
00071     void InitializeDecoder(telemetry_impl_interface_sptr decoder);
00072
00073     const Gnss_Satellite& satellite() const;
00074
00075     Tlm_Conf tlm_parameters_;
00076
00077 private:
00078     telemetry_impl_interface_sptr telemetry_decoder_;
00079     Gnss_Satellite satellite_;
00080     std::string role_;
00081     unsigned int in_streams_ = 0;
00082     unsigned int out_streams_ = 0;
00083 };
00084
00085 /** \} */
00086 /** \} */
00087
00088 #endif // GNSS_SDR_TELEMETRY_DECODER_ADAPTER_BASE_H

```

13.484 beidou_b1i_telemetry_decoder_gs.h File Reference

Implementation of a BEIDOU B1I DNAV data decoder block.

```

#include "beidou_dnav_navigation_message.h"
#include "nav_message_packet.h"
#include "telemetry_impl_interface.h"
#include "tlm_conf.h"
#include <boost/circular_buffer.hpp>
#include <gnuradio/types.h>
#include <array>

```

Classes

- class [beidou_b1i_telemetry_decoder_gs](#)

This class implements a block that decodes the BeiDou DNAV data.

Typedefs

- using [beidou_b1i_telemetry_decoder_gs_sptr](#) = gnss_shared_ptr<[beidou_b1i_telemetry_decoder_gs](#)>

Functions

- [beidou_b1i_telemetry_decoder_gs_sptr](#) **beidou_b1i_make_telemetry_decoder_gs** (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf)

13.484.1 Detailed Description

Implementation of a BEIDOU B1I DNAV data decoder block.
Code added as part of GSoC 2018 program.

Author

Damian Miralles, 2018. dmiralles2009(at)gmail.com

Sergi Segura, 2018. sergi.segura.munoz(at)gmail.es

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Definition in file [beidou_b1i_telemetry_decoder_gs.h](#).

13.485 beidou_b1i_telemetry_decoder_gs.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file beidou_b1i_telemetry_decoder_gs.h
00003  * \brief Implementation of a BEIDOU B1I DNAV data decoder block
00004  * \details Code added as part of GSoC 2018 program.
00005  * \author Damian Miralles, 2018. dmiralles2009(at)gmail.com
00006  * \author Sergi Segura, 2018. sergi.segura.munoz(at)gmail.es
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_BEIDOU_B1I_TELEMETRY_DECODER_GS_H
00020 #define GNSS_SDR_BEIDOU_B1I_TELEMETRY_DECODER_GS_H
00021
00022
00023 #include "beidou_dnav_navigation_message.h"
00024 #include "nav_message_packet.h"
00025 #include "telemetry_impl_interface.h"
00026 #include "tlm_conf.h"
00027 #include <boost/circular_buffer.hpp>
00028 #include <gnuradio/types.h> // for gr_vector_const_void_star
00029 #include <array>
00030
00031
00032 /** \addtogroup Telemetry_Decoder
00033  * \{ */
00034 /** \addtogroup Telemetry_Decoder_gnuradio_blocks
00035  * \{ */
00036
00037
00038 class beidou_b1i_telemetry_decoder_gs;
00039
00040 using beidou_b1i_telemetry_decoder_gs_sptr = gnss_shared_ptr<beidou_b1i_telemetry_decoder_gs>;
00041
00042 beidou_b1i_telemetry_decoder_gs_sptr beidou_b1i_make_telemetry_decoder_gs(
```

```

00043     const Gnss_Satellite &satellite,
00044     const Tlm_Conf &conf);
00045
00046
00047  /*!
00048   * \brief This class implements a block that decodes the BeiDou DNAV data.
00049   * \note Code added as part of GSOC 2018 program
00050   */
00051  class beidou_bli_telemetry_decoder_gs : public telemetry_impl_interface
00052  {
00053  public:
00054      ~beidou_bli_telemetry_decoder_gs() override;           //!< Class destructor
00055      void set_satellite(const Gnss_Satellite &satellite) override; //!< Set satellite PRN
00056      void set_channel(int channel) override;                 //!< Set receiver's channel
00057      void reset() override;
00058
00059      /*!
00060       * \brief This is where all signal processing takes place
00061       */
00062      int general_work(int noutput_items, gr_vector_int &ninput_items,
00063                      gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override;
00064
00065  private:
00066      friend beidou_bli_telemetry_decoder_gs_sptr beidou_bli_make_telemetry_decoder_gs(
00067          const Gnss_Satellite &satellite,
00068          const Tlm_Conf &conf);
00069
00070      beidou_bli_telemetry_decoder_gs(const Gnss_Satellite &satellite, const Tlm_Conf &conf);
00071
00072      void decode_subframe(float *symbols, double cn0);
00073      void decode_word(int32_t word_counter, const float *enc_word_symbols, int32_t *dec_word_symbols);
00074      void decode_bch15_11_01(const int32_t *bits, std::array<int32_t, 15> &decbits);
00075
00076      // Preamble decoding
00077      std::array<int32_t, BEIDOU_DNAV_PREAMBLE_LENGTH_SYMBOLS> d_preamble_samples{};
00078
00079      std::array<float, BEIDOU_DNAV_PREAMBLE_PERIOD_SYMBOLS> d_subframe_symbols{};
00080
00081      // Storage for incoming data
00082      boost::circular_buffer<float> d_symbol_history;
00083
00084      // Navigation Message variable
00085      Beidou_Dnav_Navigation_Message d_nav;
00086
00087      Nav_Message_Packet d_nav_msg_packet;
00088      std::unique_ptr<Tlm_CRC_Stats> d_Tlm_CRC_Stats;
00089
00090      // Satellite Information and logging capacity
00091      Gnss_Satellite d_satellite;
00092      std::string d_dump_filename;
00093      std::ofstream d_dump_file;
00094
00095      uint64_t d_sample_counter; // Sample counter as an index (1,2,3,..etc) indicating number of
samples processed
00096      uint64_t d_preamble_index; // Index of sample number where preamble was found
00097
00098      int32_t d_channel;
00099      int32_t d_symbols_per_preamble;
00100      int32_t d_samples_per_preamble;
00101      int32_t d_preamble_period_samples;
00102      int32_t d_CRC_error_counter; // Number of failed CRC operations
00103      uint32_t d_required_symbols;
00104      uint32_t d_stat; // Status of decoder
00105
00106      // Values to populate gnss synchronization structure
00107      uint64_t d_last_valid_preamble;
00108      uint32_t d_symbol_duration_ms;
00109      uint32_t d_TOW_at_Preamble_ms;
00110      uint32_t d_TOW_at_current_symbol_ms;
00111
00112      bool d_flag_SOW_set; // Indicates when time of week is set
00113      bool d_flag_frame_sync; // Indicate when a frame sync is achieved
00114      bool d_flag_preamble; // Flag indicating when preamble was found
00115
00116      bool d_flag_valid_word;
00117      bool d_sent_tlm_failed_msg;
00118      bool d_dump;
00119      bool d_dump_mat;
00120      bool d_remove_dat;
00121      bool d_enable_navdata_monitor;
00122      bool d_dump_crc_stats;
00123      bool d_tow_to_trk;
00124  };
00125
00126
00127  /** \} */
00128  /** \} */

```



```
00129 #endif // GNSS_SDR_BEIDOU_B3I_TELEMETRY_DECODER_GS_H
```

13.486 beidou_b3i_telemetry_decoder_gs.h File Reference

Implementation of a BEIDOU B3I DNAV data decoder block.

```
#include "beidou_dnav_navigation_message.h"
#include "nav_message_packet.h"
#include "telemetry_impl_interface.h"
#include "tlm_conf.h"
#include <boost/circular_buffer.hpp>
#include <gnuradio/types.h>
#include <array>
```

Classes

- class [beidou_b3i_telemetry_decoder_gs](#)
This class implements a block that decodes the BeiDou DNAV data.

Typedefs

- using [beidou_b3i_telemetry_decoder_gs_sptr](#)

Functions

- [beidou_b3i_telemetry_decoder_gs_sptr](#) [beidou_b3i_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf)

13.486.1 Detailed Description

Implementation of a BEIDOU B3I DNAV data decoder block.

Author

Damian Miralles, 2019. [dmiralles2009\(at\)gmail.com](mailto:dmiralles2009(at)gmail.com)

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 Definition in file [beidou_b3i_telemetry_decoder_gs.h](#).

13.487 beidou_b3i_telemetry_decoder_gs.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file beidou_b3i_telemetry_decoder_gs.h
00003  * \brief Implementation of a BEIDOU B3I DNAV data decoder block
00004  * \author Damian Miralles, 2019. dmiralles2009(at)gmail.com
00005  *
00006  * -----
00007  *
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00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_BEIDOU_B3I_TELEMETRY_DECODER_GS_H
00018 #define GNSS_SDR_BEIDOU_B3I_TELEMETRY_DECODER_GS_H
00019
00020 #include "beidou_dnav_navigation_message.h"
00021 #include "nav_message_packet.h"
00022 #include "telemetry_impl_interface.h"
00023 #include "tlm_conf.h"
```

```

00024 #include <boost/circular_buffer.hpp>
00025 #include <gnuradio/types.h> // for gr_vector_const_void_star
00026 #include <array>
00027
00028
00029 /** \addtogroup Telemetry_Decoder
00030 * \{ */
00031 /** \addtogroup Telemetry_Decoder_gnuradio_blocks
00032 * \{ */
00033
00034
00035 class beidou_b3i_telemetry_decoder_gs;
00036
00037 using beidou_b3i_telemetry_decoder_gs_sptr =
00038     gnss_shared_ptr<beidou_b3i_telemetry_decoder_gs>;
00039
00040 beidou_b3i_telemetry_decoder_gs_sptr beidou_b3i_make_telemetry_decoder_gs(
00041     const Gnss_Satellite &satellite,
00042     const Tlm_Conf &conf);
00043
00044 /*!
00045 * \brief This class implements a block that decodes the BeiDou DNAV data.
00046 */
00047 class beidou_b3i_telemetry_decoder_gs : public telemetry_impl_interface
00048 {
00049 public:
00050     ~beidou_b3i_telemetry_decoder_gs() override;           //!< Class destructor
00051     void set_satellite(const Gnss_Satellite &satellite) override; //!< Set satellite PRN
00052     void set_channel(int channel) override;                 //!< Set receiver's channel
00053     void reset() override;
00054
00055     /*!
00056     * \brief This is where all signal processing takes place
00057     */
00058     int general_work(int noutput_items, gr_vector_int &ninput_items,
00059         gr_vector_const_void_star &input_items,
00060         gr_vector_void_star &output_items) override;
00061 private:
00062     friend beidou_b3i_telemetry_decoder_gs_sptr beidou_b3i_make_telemetry_decoder_gs(
00063         const Gnss_Satellite &satellite,
00064         const Tlm_Conf &conf);
00065
00066     beidou_b3i_telemetry_decoder_gs(const Gnss_Satellite &satellite, const Tlm_Conf &conf);
00067
00068     void decode_subframe(float *symbols, double cn0);
00069     void decode_word(int32_t word_counter, const float *enc_word_symbols,
00070         int32_t *dec_word_symbols);
00071     void decode_bch15_11_01(const int32_t *bits, std::array<int32_t, 15> &decbits);
00072
00073     // Preamble decoding
00074     std::array<int32_t, BEIDOU_DNAV_PREAMBLE_LENGTH_SYMBOLS> d_preamble_samples{};
00075     std::array<float, BEIDOU_DNAV_PREAMBLE_PERIOD_SYMBOLS> d_subframe_symbols{};
00076
00077     // Storage for incoming data
00078     boost::circular_buffer<float> d_symbol_history;
00079
00080     // Navigation Message variable
00081     Beidou_Dnav_Navigation_Message d_nav;
00082     Gnss_Satellite d_satellite;
00083
00084     Nav_Message_Packet d_nav_msg_packet;
00085     std::unique_ptr<Tlm_CRC_Stats> d_Tlm_CRC_Stats;
00086
00087     std::string d_dump_filename;
00088     std::ofstream d_dump_file;
00089
00090     uint64_t d_sample_counter; // Sample counter as an index (1,2,3,..etc) indicating number of
00091     samples processed
00092     uint64_t d_preamble_index; // Index of sample number where preamble was found
00093     uint32_t d_required_symbols;
00094     uint32_t d_stat; // Status of decoder
00095
00096     int32_t d_channel;
00097     int32_t d_CRC_error_counter; // Number of failed CRC operations
00098     int32_t d_symbols_per_preamble;
00099     int32_t d_samples_per_preamble;
00100     int32_t d_preamble_period_samples;
00101
00102     // Values to populate gnss synchronization structure
00103     uint64_t d_last_valid_preamble;
00104     uint32_t d_symbol_duration_ms;
00105     uint32_t d_TOW_at_Preamble_ms;
00106     uint32_t d_TOW_at_current_symbol_ms;
00107
00108     bool d_flag_SOW_set; // Indicates when time of week is set
00109     bool d_flag_frame_sync; // Indicate when a frame sync is achieved

```

```

00110     bool d_flag_preamble;    // Flag indicating when preamble was found
00111     bool d_flag_valid_word;
00112     bool d_sent_tlm_failed_msg;
00113     bool d_dump;
00114     bool d_dump_mat;
00115     bool d_remove_dat;
00116     bool d_enable_navdata_monitor;
00117     bool d_dump_crc_stats;
00118     bool d_tow_to_trk;
00119 };
00120
00121
00122 /** \} */
00123 /** \} */
00124 #endif // GNSS_SDR_BEIDOU_B3I_TELEMETRY_DECODER_GS_H

```

13.488 galileo_telemetry_decoder_gs.h File Reference

Implementation of a Galileo unified INAV and FNAV message demodulator block.

```

#include "galileo_cnav_message.h"
#include "galileo_fnav_message.h"
#include "galileo_inav_message.h"
#include "gnss_time.h"
#include "nav_message_packet.h"
#include "telemetry_impl_interface.h"
#include "tlm_conf.h"
#include <boost/circular_buffer.hpp>
#include <gnuradio/types.h>
#include <pmt/pmt.h>
#include <vector>

```

Classes

- class [galileo_telemetry_decoder_gs](#)

This class implements a block that decodes the INAV and FNAV data defined in Galileo ICD.

Typedefs

- using [galileo_telemetry_decoder_gs_sptr](#) = `gnss_shared_ptr<galileo_telemetry_decoder_gs>`

Functions

- `galileo_telemetry_decoder_gs_sptr galileo_make_telemetry_decoder_gs (const Gnss_Satellite &satellite, const Tlm_Conf &conf, int frame_type)`

13.488.1 Detailed Description

Implementation of a Galileo unified INAV and FNAV message demodulator block.

Author

Javier Arribas 2018. jarribas(at)cttc.es

Carles Fernandez, 2021-2022. cfernandez(at)cttc.es

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 Definition in file [galileo_telemetry_decoder_gs.h](#).

13.489 galileo_telemetry_decoder_gs.h

[Go to the documentation of this file.](#)

```
00001 /*!
```

```

00002 * \file galileo_telemetry_decoder_gs.h
00003 * \brief Implementation of a Galileo unified INAV and FNAV message demodulator
00004 * block
00005 * \author Javier Arribas 2018. jarribas(at)cttc.es
00006 * \author Carles Fernandez, 2021-2022. cfernandez(at)cttc.es
00007 *
00008 *
00009 * -----
00010 *
00011 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012 * This file is part of GNSS-SDR.
00013 *
00014 * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00015 * SPDX-License-Identifier: GPL-3.0-or-later
00016 *
00017 * -----
00018 */
00019
00020
00021 #ifndef GNSS_SDR_GALILEO_TELEMETRY_DECODER_GS_H
00022 #define GNSS_SDR_GALILEO_TELEMETRY_DECODER_GS_H
00023
00024 #include "galileo_cnav_message.h" // for Galileo_Cnav_Message
00025 #include "galileo_fnav_message.h" // for Galileo_Fnav_Message
00026 #include "galileo_inav_message.h" // for Galileo_Inav_Message
00027 #include "gnss_time.h" // for GnssTime
00028 #include "nav_message_packet.h" // for Nav_Message_Packet
00029 #include "telemetry_impl_interface.h" // for telemetry_impl_interface
00030 #include "tlm_conf.h" // for Tlm_Conf
00031 #include <boost/circular_buffer.hpp> // for boost::circular_buffer
00032 #include <gnuradio/types.h> // for gr_vector_const_void_star
00033 #include <pmt/pmt.h> // for pmt::pmt_t
00034 #include <vector> // for std::vector
00035
00036 /** \addtogroup Telemetry_Decoder
00037 * \{ */
00038 /** \addtogroup Telemetry_Decoder_gnuradio_blocks
00039 * \{ */
00040
00041 class Viterbi_Decoder; // forward declaration
00042 class galileo_telemetry_decoder_gs; // forward declaration
00043
00044 using galileo_telemetry_decoder_gs_sptr = gnss_shared_ptr<galileo_telemetry_decoder_gs>;
00045
00046 galileo_telemetry_decoder_gs_sptr galileo_make_telemetry_decoder_gs(
00047     const Gnss_Satellite &satellite,
00048     const Tlm_Conf &conf,
00049     int frame_type);
00050
00051 /*!
00052 * \brief This class implements a block that decodes the INAV and FNAV data defined in Galileo ICD
00053 */
00054 class galileo_telemetry_decoder_gs : public telemetry_impl_interface
00055 {
00056 public:
00057     ~galileo_telemetry_decoder_gs() override;
00058     void set_satellite(const Gnss_Satellite &satellite) override; //!< Set satellite PRN
00059     void set_channel(int32_t channel) override; //!< Set receiver's channel
00060     void reset() override;
00061
00062     /*!
00063     * \brief This is where all signal processing takes place
00064     */
00065     int general_work(int noutput_items, gr_vector_int &ninput_items,
00066         gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override;
00067 private:
00068     friend galileo_telemetry_decoder_gs_sptr galileo_make_telemetry_decoder_gs(
00069         const Gnss_Satellite &satellite,
00070         const Tlm_Conf &conf,
00071         int frame_type);
00072
00073     galileo_telemetry_decoder_gs(const Gnss_Satellite &satellite, const Tlm_Conf &conf, int
frame_type);
00074
00075     void check_tlm_separation();
00076     void msg_handler_read_galileo_tow_map(const pmt::pmt_t &msg);
00077     void deinterleaver(int32_t rows, int32_t cols, const float *in, float *out);
00078     void decode_INAV_word(float *page_part_symbols, int32_t frame_length, double cn0);
00079     void decode_FNAV_word(float *page_symbols, int32_t frame_length, double cn0);
00080     void decode_CNAV_word(uint64_t time_stamp, float *page_symbols, int32_t page_length, double cn0);
00081
00082     std::unique_ptr<Viterbi_Decoder> d_viterbi;
00083     std::vector<int32_t> d_preamble_samples;
00084     std::vector<float> d_page_part_symbols;
00085
00086     std::string d_dump_filename;

```

```

00088     std::ofstream d_dump_file;
00089
00090     boost::circular_buffer<float> d_symbol_history;
00091
00092     Gnss_Satellite d_satellite;
00093
00094     // navigation message vars
00095     Galileo_Cnav_Message d_cnav_nav;
00096     Galileo_Inav_Message d_inav_nav;
00097     Galileo_Fnav_Message d_fnav_nav;
00098
00099     Nav_Message_Packet d_nav_msg_packet;
00100     GnssTime d_current_timetag{};
00101
00102     std::unique_ptr<Tlm_CRC_Stats> d_Tlm_CRC_Stats;
00103
00104     double d_delta_t; // GPS-GALILEO time offset
00105
00106     uint64_t d_symbol_counter;
00107     uint64_t d_preamble_index;
00108     uint64_t d_last_valid_preamble;
00109     uint64_t d_received_sample_counter;
00110
00111     int32_t d_mm;
00112     int32_t d_codelength;
00113     int32_t d_datalength;
00114     int32_t d_frame_type;
00115     int32_t d_bits_per_preamble;
00116     int32_t d_samples_per_preamble;
00117     int32_t d_preamble_period_symbols;
00118     int32_t d_CRC_error_counter;
00119     int32_t d_channel;
00120     int32_t d_flag_even_word_arrived;
00121
00122     uint32_t d_PRN_code_period_ms;
00123     uint32_t d_required_symbols;
00124     uint32_t d_frame_length_symbols;
00125     uint32_t d_stat;
00126     uint32_t d_TOW_at_Preamble_ms;
00127     uint32_t d_TOW_at_current_symbol_ms;
00128     uint32_t d_max_symbols_without_valid_frame;
00129     uint32_t d_received_tow_ms;
00130
00131     char d_band; // This variable will store which band we are dealing with (Galileo E1 or E5b)
00132
00133     bool d_sent_tlm_failed_msg;
00134     bool d_flag_frame_sync;
00135     bool d_flag_PLL_180_deg_phase_locked;
00136     bool d_flag_preamble;
00137     bool d_dump;
00138     bool d_dump_mat;
00139     bool d_remove_dat;
00140     bool d_first_eph_sent;
00141     bool d_cnav_dummy_page;
00142     bool d_print_cnav_page;
00143     bool d_enable_navdata_monitor;
00144     bool d_dump_crc_stats;
00145     bool d_enable_reed_solomon_inav;
00146     bool d_valid_timetag;
00147     bool d_E6_TOW_set;
00148     bool d_there_are_e1_channels;
00149     bool d_there_are_e6_channels;
00150     bool d_use_ced;
00151     bool d_tow_to_trk;
00152 };
00153
00154
00155 /** \} */
00156 /** \} */
00157 #endif // GNSS_SDR_GALILEO_TELEMETRY_DECODER_GS_H

```

13.490 glonass_l1_ca_telemetry_decoder_gs.h File Reference

Implementation of a GLONASS L1 C/A NAV data decoder block.

```

#include "GLONASS_L1_L2_CA.h"
#include "glonass_gnav_navigation_message.h"
#include "gnss_synchro.h"
#include "nav_message_packet.h"
#include "telemetry_impl_interface.h"
#include "tlm_conf.h"
#include <boost/circular_buffer.hpp>

```

```
#include <gnuradio/types.h>
#include <array>
```

Classes

- class [glonass_l1_ca_telemetry_decoder_gs](#)

This class implements a block that decodes the GNAV data defined in GLONASS ICD v5.1.

Typedefs

- using [glonass_l1_ca_telemetry_decoder_gs_sptr](#) = [gnss_shared_ptr](#)<[glonass_l1_ca_telemetry_decoder_gs](#)>

Functions

- [glonass_l1_ca_telemetry_decoder_gs_sptr glonass_l1_ca_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf)

13.490.1 Detailed Description

Implementation of a GLONASS L1 C/A NAV data decoder block.

Note

Code added as part of GSoC 2017 program

Author

Damian Miralles, 2017. dmiralles2009(at)gmail.comK

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 Definition in file [glonass_l1_ca_telemetry_decoder_gs.h](#).

13.491 glonass_l1_ca_telemetry_decoder_gs.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file glonass_l1_ca_telemetry_decoder_gs.h
00003  * \brief Implementation of a GLONASS L1 C/A NAV data decoder block
00004  * \note Code added as part of GSoC 2017 program
00005  * \author Damian Miralles, 2017. dmiralles2009(at)gmail.comK
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GLOMSS_L1_CA_TELEMETRY_DECODER_GS_H
00019 #define GNSS_SDR_GLOMSS_L1_CA_TELEMETRY_DECODER_GS_H
00020
00021
00022 #include "GLONASS_L1_L2_CA.h"
00023 #include "glonass_gnav_navigation_message.h"
00024 #include "gnss_synchro.h"
00025 #include "nav_message_packet.h"
00026 #include "telemetry_impl_interface.h"
00027 #include "tlm_conf.h"
00028 #include <boost/circular_buffer.hpp>
00029 #include <gnuradio/types.h> // for gr_vector_const_void_star
00030 #include <array>
00031
00032 /** \addtogroup Telemetry_Decoder
00033  * \{ */
00034 /** \addtogroup Telemetry_Decoder_gnuradio_blocks
```

```

00035  * \{ */
00036
00037
00038 class glonass_l1_ca_telemetry_decoder_gs;
00039
00040 using glonass_l1_ca_telemetry_decoder_gs_sptr = gnss_shared_ptr<glonass_l1_ca_telemetry_decoder_gs>;
00041
00042 glonass_l1_ca_telemetry_decoder_gs_sptr glonass_l1_ca_make_telemetry_decoder_gs(
00043     const Gnss_Satellite &satellite,
00044     const Tlm_Conf &conf);
00045
00046 /*!
00047  * \brief This class implements a block that decodes the GNAV data defined in GLONASS ICD v5.1
00048  * \note Code added as part of GSoC 2017 program
00049  * \see <a
00050       href="http://russianspacesystems.ru/wp-content/uploads/2016/08/ICD_GLONASS_eng_v5.1.pdf">GLONASS
00051       ICD</a>
00052  */
00053 class glonass_l1_ca_telemetry_decoder_gs : public telemetry_impl_interface
00054 {
00055 public:
00056     ~glonass_l1_ca_telemetry_decoder_gs() override;           //!< Class destructor
00057     void set_satellite(const Gnss_Satellite &satellite) override; //!< Set satellite PRN
00058     void set_channel(int32_t channel) override;               //!< Set receiver's channel
00059     inline void reset() override {};
00060
00061 /*!
00062  * \brief This is where all signal processing takes place
00063  */
00064     int general_work(int noutput_items, gr_vector_int &ninput_items,
00065                     gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override;
00066 private:
00067     friend glonass_l1_ca_telemetry_decoder_gs_sptr glonass_l1_ca_make_telemetry_decoder_gs(
00068         const Gnss_Satellite &satellite,
00069         const Tlm_Conf &conf);
00070
00071     glonass_l1_ca_telemetry_decoder_gs(const Gnss_Satellite &satellite, const Tlm_Conf &conf);
00072
00073     const std::array<int16_t, GLONASS_GNAV_PREAMBLE_LENGTH_BITS>
00074     d_preambles_bits{GLONASS_GNAV_PREAMBLE_SAMPLES};
00075
00076     void decode_string(const double *symbols, double cn0);
00077
00078     // Storage for incoming data
00079     boost::circular_buffer<Gnss_Synchro> d_symbol_history;
00080
00081     // Navigation Message variable
00082     Glonass_Gnav_Navigation_Message d_nav;
00083
00084     Gnss_Satellite d_satellite;
00085
00086     Nav_Message_Packet d_nav_msg_packet;
00087     std::unique_ptr<Tlm_CRC_Stats> d_Tlm_CRC_Stats;
00088
00089     std::string d_dump_filename;
00090     std::ofstream d_dump_file;
00091
00092     double d_preamble_time_samples;
00093     double d_TOW_at_current_symbol;
00094
00095     // Variables for internal functionality
00096     uint64_t d_sample_counter; // Sample counter as an index (1,2,3,..etc) indicating number of
00097     samples processed
00098     uint64_t d_preamble_index; // Index of sample number where preamble was found
00099
00100     uint32_t d_stat; // Status of decoder
00101     int32_t d_CRC_error_counter; // Number of failed CRC operations
00102     int32_t d_channel;
00103
00104     bool d_flag_frame_sync; // Indicate when a frame sync is achieved
00105     bool d_flag_preamble; // Flag indicating when preamble was found
00106     bool d_dump;
00107     bool d_dump_mat;
00108     bool d_remove_dat;
00109     bool d_enable_navdata_monitor;
00110     bool d_dump_crc_stats;
00111     bool d_tow_to_trk;
00112 };
00113
00114 /** \} */
00115 /** \} */
00116 #endif // GNSS_SDR_GLONASS_L1_CA_TELEMETRY_DECODER_GS_H

```

13.492 glonass_l2_ca_telemetry_decoder_gs.h File Reference

Implementation of a GLONASS L2 C/A NAV data decoder block.

```
#include "GLONASS_L1_L2_CA.h"
#include "glonass_gnav_navigation_message.h"
#include "gnss_synchro.h"
#include "nav_message_packet.h"
#include "telemetry_impl_interface.h"
#include "tlm_conf.h"
#include <boost/circular_buffer.hpp>
#include <gnuradio/types.h>
#include <array>
```

Classes

- class [glonass_l2_ca_telemetry_decoder_gs](#)

This class implements a block that decodes the GNAV data defined in GLONASS ICD v5.1.

Typedefs

- using [glonass_l2_ca_telemetry_decoder_gs_sptr](#) = gnss_shared_ptr<[glonass_l2_ca_telemetry_decoder_gs](#)>

Functions

- [glonass_l2_ca_telemetry_decoder_gs_sptr glonass_l2_ca_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf)

13.492.1 Detailed Description

Implementation of a GLONASS L2 C/A NAV data decoder block.

Author

Damian Miralles, 2018. dmiralles2009(at)gmail.com

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Definition in file [glonass_l2_ca_telemetry_decoder_gs.h](#).

13.493 glonass_l2_ca_telemetry_decoder_gs.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file glonass_l2_ca_telemetry_decoder_gs.h
00003  * \brief Implementation of a GLONASS L2 C/A NAV data decoder block
00004  * \author Damian Miralles, 2018. dmiralles2009(at)gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_GLOMSS_L2_CA_TELEMETRY_DECODER_GS_H
00018 #define GNSS_SDR_GLOMSS_L2_CA_TELEMETRY_DECODER_GS_H
00019
00020
00021 #include "GLONASS_L1_L2_CA.h"
00022 #include "glonass_gnav_navigation_message.h"
00023 #include "gnss_synchro.h"
00024 #include "nav_message_packet.h"
```



```

00025 #include "telemetry_impl_interface.h"
00026 #include "tlm_conf.h"
00027 #include <boost/circular_buffer.hpp>
00028 #include <gnuradio/types.h> // for gr_vector_const_void_star
00029 #include <array>
00030
00031 /** \addtogroup Telemetry_Decoder
00032 * \{ */
00033 /** \addtogroup Telemetry_Decoder_gnuradio_blocks
00034 * \{ */
00035
00036
00037 class glonass_l2_ca_telemetry_decoder_gs;
00038
00039 using glonass_l2_ca_telemetry_decoder_gs_sptr = gnss_shared_ptr<glonass_l2_ca_telemetry_decoder_gs>;
00040
00041 glonass_l2_ca_telemetry_decoder_gs_sptr glonass_l2_ca_make_telemetry_decoder_gs(
00042     const Gnss_Satellite &satellite,
00043     const Tlm_Conf &conf);
00044
00045 /*!
00046 * \brief This class implements a block that decodes the GNAV data defined in GLONASS ICD v5.1
00047 * \see <a
00048     href="http://russianspacesystems.ru/wp-content/uploads/2016/08/ICD_GLONASS_eng_v5.1.pdf">GLONASS
00049     ICD</a>
00050 *
00051 */
00052 class glonass_l2_ca_telemetry_decoder_gs : public telemetry_impl_interface
00053 {
00054 public:
00055     ~glonass_l2_ca_telemetry_decoder_gs() override; //!< Class destructor
00056     void set_satellite(const Gnss_Satellite &satellite) override; //!< Set satellite PRN
00057     void set_channel(int32_t channel) override; //!< Set receiver's channel
00058     inline void reset() override {};
00059
00060     /*!
00061     * \brief This is where all signal processing takes place
00062     */
00063     int general_work(int noutput_items, gr_vector_int &ninput_items,
00064         gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override;
00065 private:
00066     friend glonass_l2_ca_telemetry_decoder_gs_sptr glonass_l2_ca_make_telemetry_decoder_gs(
00067         const Gnss_Satellite &satellite,
00068         const Tlm_Conf &conf);
00069
00070     glonass_l2_ca_telemetry_decoder_gs(const Gnss_Satellite &satellite, const Tlm_Conf &conf);
00071
00072     const std::array<int16_t, GLONASS_GNAV_PREAMBLE_LENGTH_BITS>
00073     d_preambles_bits{GLONASS_GNAV_PREAMBLE_SAMPLES};
00074     void decode_string(const double *symbols, double cn0);
00075
00076     // Storage for incoming data
00077     boost::circular_buffer<Gnss_Synchro> d_symbol_history;
00078
00079     // Navigation Message variable
00080     Glonass_Gnav_Navigation_Message d_nav;
00081     Gnss_Satellite d_satellite;
00082
00083     Nav_Message_Packet d_nav_msg_packet;
00084     std::unique_ptr<Tlm_CRC_Stats> d_Tlm_CRC_Stats;
00085
00086     std::string d_dump_filename;
00087     std::ofstream d_dump_file;
00088
00089     double d_preamble_time_samples;
00090     double d_TOW_at_current_symbol;
00091
00092     uint64_t d_sample_counter; // Sample counter as an index (1,2,3,..etc) indicating number of
00093     samples processed
00094     uint64_t d_preamble_index; // Index of sample number where preamble was found
00095     uint32_t d_stat; // Status of decoder
00096
00097     int32_t d_CRC_error_counter; // Number of failed CRC operations
00098     int32_t d_channel;
00099
00100     bool d_flag_frame_sync; // Indicate when a frame sync is achieved
00101     bool d_flag_preamble; // Flag indicating when preamble was found
00102     bool d_dump;
00103     bool d_dump_mat;
00104     bool d_remove_dat;
00105     bool d_enable_navdata_monitor;
00106     bool d_dump_crc_stats;
00107     bool d_tow_to_trk;
00108 };
00109
00110
00111

```

```

00108 /** \} */
00109 /** \} */
00110 #endif // GNSS_SDR_GLOMSS_L2_CA_TELEMETRY_DECODER_GS_H

```

13.494 gps_l1_ca_telemetry_decoder_gs.h File Reference

Interface of a NAV message demodulator block based on Kay Borre book MATLAB-based GPS receiver.

```

#include "GPS_L1_CA.h"
#include "gnss_synchro.h"
#include "gnss_time.h"
#include "gps_navigation_message.h"
#include "nav_message_packet.h"
#include "telemetry_impl_interface.h"
#include "tlm_conf.h"
#include <boost/circular_buffer.hpp>
#include <gnuradio/types.h>
#include <array>

```

Classes

- class [gps_l1_ca_telemetry_decoder_gs](#)

This class implements a block that decodes the NAV data defined in IS-GPS-200M.

Typedefs

- using [gps_l1_ca_telemetry_decoder_gs_sptr](#) = [gnss_shared_ptr](#)<[gps_l1_ca_telemetry_decoder_gs](#)>

Enumerations

- enum class [L1LnavSystem](#) { [GPS](#) , [QZSS](#) }

Functions

- [gps_l1_ca_telemetry_decoder_gs_sptr](#) [gps_l1_ca_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf, [L1LnavSystem](#) system=[L1LnavSystem::GPS](#))

13.494.1 Detailed Description

Interface of a NAV message demodulator block based on Kay Borre book MATLAB-based GPS receiver.

Author

Javier Arribas, 2011. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)

Carles Fernandez Prades, 2011-2026. [cfernandez\(at\)cttc.es](mailto:cfernandez(at)cttc.es)

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Definition in file [gps_l1_ca_telemetry_decoder_gs.h](#).

13.495 gps_l1_ca_telemetry_decoder_gs.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gps_l1_ca_telemetry_decoder_gs.h
00003  * \brief Interface of a NAV message demodulator block based on
00004  * Kay Borre book MATLAB-based GPS receiver
00005  * \author Javier Arribas, 2011. jarribas\(at\)cttc.es
00006  * \author Carles Fernandez Prades, 2011-2026. cfernandez\(at\)cttc.es
00007  *
00008  * -----
00009  *

```

```

00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2026 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GPS_L1_CA_TELEMETRY_DECODER_GS_H
00020 #define GNSS_SDR_GPS_L1_CA_TELEMETRY_DECODER_GS_H
00021
00022 #include "GPS_L1_CA.h"
00023 #include "gnss_synchro.h"
00024 #include "gnss_time.h" // for timetags produced by Tracking
00025 #include "gps_navigation_message.h"
00026 #include "nav_message_packet.h"
00027 #include "telemetry_impl_interface.h"
00028 #include "tlm_conf.h"
00029 #include <boost/circular_buffer.hpp>
00030 #include <gnuradio/types.h> // for gr_vector_const_void_star
00031 #include <array> // for array
00032
00033
00034 /** \addtogroup Telemetry_Decoder
00035  * \{ */
00036 /** \addtogroup Telemetry_Decoder_gnuradio_blocks telemetry_decoder_gr_blocks
00037  * GNU Radio blocks for the demodulation of GNSS navigation messages.
00038  * \{ */
00039
00040 enum class L1LnavSystem
00041 {
00042     GPS,
00043     QZSS
00044 };
00045
00046 class gps_l1_ca_telemetry_decoder_gs;
00047
00048 using gps_l1_ca_telemetry_decoder_gs_sptr = gnss_shared_ptr<gps_l1_ca_telemetry_decoder_gs>;
00049
00050 gps_l1_ca_telemetry_decoder_gs_sptr gps_l1_ca_make_telemetry_decoder_gs(
00051     const Gnss_Satellite &satellite,
00052     const Tlm_Conf &conf,
00053     L1LnavSystem system = L1LnavSystem::GPS);
00054
00055 /*!
00056  * \brief This class implements a block that decodes the NAV data defined in IS-GPS-200M
00057  */
00058 class gps_l1_ca_telemetry_decoder_gs : public telemetry_impl_interface
00059 {
00060 public:
00061     ~gps_l1_ca_telemetry_decoder_gs() override;
00062     void set_satellite(const Gnss_Satellite &satellite) override; //!< Set satellite PRN
00063     void set_channel(int channel) override; //!< Set receiver's channel
00064     void reset() override;
00065
00066     /*!
00067     * \brief This is where all signal processing takes place
00068     */
00069     int general_work(int noutput_items, gr_vector_int &ninput_items,
00070         gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override;
00071
00072 private:
00073     friend gps_l1_ca_telemetry_decoder_gs_sptr gps_l1_ca_make_telemetry_decoder_gs(
00074         const Gnss_Satellite &satellite,
00075         const Tlm_Conf &conf,
00076         L1LnavSystem system);
00077
00078     gps_l1_ca_telemetry_decoder_gs(const Gnss_Satellite &satellite, const Tlm_Conf &conf, L1LnavSystem
system);
00079
00080     void check_tlm_separation();
00081     void frame_synchronization(const Gnss_Synchro &current_gs);
00082     bool is_PLL_180_deg_phase_locked();
00083     bool gps_word_parityCheck(uint32_t gpsword);
00084     bool decode_subframe(double cn0, bool flag_invert);
00085     bool is_tow_consistent(uint32_t decoded_tow_s);
00086
00087     L1LnavSystem d_system;
00088     std::unique_ptr<Gps_Navigation_Message> d_nav;
00089     Gnss_Satellite d_satellite;
00090     Nav_Message_Packet d_nav_msg_packet;
00091     std::unique_ptr<Tlm_CRC_Stats> d_Tlm_CRC_Stats;
00092
00093     std::array<int32_t, GPS_CA_PREAMBLE_LENGTH_BITS> d_preamble_samples{};
00094
00095     std::string d_dump_filename;

```

```

00096     std::ofstream d_dump_file;
00097
00098     boost::circular_buffer<float> d_symbol_history;
00099
00100     uint64_t d_sample_counter;
00101     uint64_t d_preamble_index;
00102     uint64_t d_last_valid_preamble;
00103
00104     int32_t d_bits_per_preamble;
00105     int32_t d_samples_per_preamble;
00106     int32_t d_preamble_period_symbols;
00107     int32_t d_CRC_error_counter;
00108     int32_t d_channel;
00109
00110     uint32_t d_required_symbols;
00111     uint32_t d_prev_GPS_frame_4bytes;
00112     uint32_t d_max_symbols_without_valid_frame;
00113     uint32_t d_stat;
00114     uint32_t d_TOW_at_Preamble_ms;
00115     uint32_t d_TOW_at_current_symbol_ms;
00116     uint32_t d_last_decoded_tow_s;
00117     uint64_t d_last_decoded_tow_sample_counter;
00118
00119     bool d_flag_frame_sync;
00120     bool d_flag_preamble;
00121     bool d_sent_tlm_failed_msg;
00122     bool d_flag_PLL_180_deg_phase_locked;
00123     bool d_flag_TOW_set;
00124     bool d_dump;
00125     bool d_dump_mat;
00126     bool d_remove_dat;
00127     bool d_enable_navdata_monitor;
00128     bool d_dump_crc_stats;
00129     bool d_tow_to_trk;
00130     bool d_have_last_decoded_tow;
00131 };
00132
00133
00134 /** \} */
00135 /** \} */
00136 #endif // GNSS_SDR_GPS_L1_CA_TELEMETRY_DECODER_GS_H

```

13.496 gps_l2c_telemetry_decoder_gs.h File Reference

Interface of a CNAV message demodulator block.

```

#include "gps_cnav_navigation_message.h"
#include "nav_message_packet.h"
#include "telemetry_impl_interface.h"
#include "tlm_conf.h"
#include <gnuradio/types.h>
#include "cnav_msg.h"

```

Classes

- class [gps_l2c_telemetry_decoder_gs](#)

This class implements a block that decodes CNAV data defined in IS-GPS-200M.

Typedefs

- using [gps_l2c_telemetry_decoder_gs_sptr](#) = gnss_shared_ptr<[gps_l2c_telemetry_decoder_gs](#)>

Functions

- [gps_l2c_telemetry_decoder_gs_sptr](#) [gps_l2c_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf)

13.496.1 Detailed Description

Interface of a CNAV message demodulator block.

Author

Javier Arribas, 2015. jarribas(at)cttc.es

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Definition in file [gps_l2c_telemetry_decoder_gs.h](#).

13.497 gps_l2c_telemetry_decoder_gs.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gps_l2c_telemetry_decoder_gs.h
00003  * \brief Interface of a CNAV message demodulator block
00004  * \author Javier Arribas, 2015. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00010  *
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00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_GPS_L2C_TELEMETRY_DECODER_GS_H
00018 #define GNSS_SDR_GPS_L2C_TELEMETRY_DECODER_GS_H
00019
00020
00021 #include "gps_cnav_navigation_message.h"
00022 #include "nav_message_packet.h"
00023 #include "telemetry_impl_interface.h"
00024 #include "tlm_conf.h"
00025 #include <gnuradio/types.h> // for gr_vector_const_void_star
00026
00027 extern "C"
00028 {
00029 #include "cnav_msg.h"
00030 }
00031
00032 /** \addtogroup Telemetry_Decoder
00033  * \{ */
00034 /** \addtogroup Telemetry_Decoder_gnuradio_blocks
00035  * \{ */
00036
00037
00038 class gps_l2c_telemetry_decoder_gs;
00039
00040 using gps_l2c_telemetry_decoder_gs_sptr = gnss_shared_ptr<gps_l2c_telemetry_decoder_gs>;
00041
00042 gps_l2c_telemetry_decoder_gs_sptr gps_l2c_make_telemetry_decoder_gs(
00043     const Gnss_Satellite &satellite,
00044     const Tlm_Conf &conf);
00045
00046 /*!
00047  * \brief This class implements a block that decodes CNAV data defined in IS-GPS-200M
00048  */
00049 class gps_l2c_telemetry_decoder_gs : public telemetry_impl_interface
00050 {
00051 public:
00052     ~gps_l2c_telemetry_decoder_gs() override;
00053     void set_satellite(const Gnss_Satellite &satellite) override; //!< Set satellite PRN
00054     void set_channel(int32_t channel) override; //!< Set receiver's channel
00055     void reset() override;
00056
00057     /*!
00058     * \brief This is where all signal processing takes place
00059     */
00060     int general_work(int noutput_items, gr_vector_int &ninput_items,
00061         gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override;
00062
00063 private:
00064     friend gps_l2c_telemetry_decoder_gs_sptr gps_l2c_make_telemetry_decoder_gs(
00065         const Gnss_Satellite &satellite,
00066         const Tlm_Conf &conf);
00067
00068     gps_l2c_telemetry_decoder_gs(const Gnss_Satellite &satellite, const Tlm_Conf &conf);
00069
00070     Gnss_Satellite d_satellite;
00071
00072     cnav_msg_decoder_t d_cnav_decoder{};

```

```

00073
00074     Gps_CNAV_Navigation_Message d_CNAV_Message;
00075
00076     Nav_Message_Packet d_nav_msg_packet;
00077     std::unique_ptr<Tlm_CRC_Stats> d_Tlm_CRC_Stats;
00078
00079     std::string d_dump_filename;
00080     std::ofstream d_dump_file;
00081
00082     double d_TOW_at_current_symbol;
00083     double d_TOW_at_Preamble;
00084
00085     uint64_t d_sample_counter;
00086     uint64_t d_last_valid_preamble;
00087
00088     int32_t d_channel;
00089
00090     uint32_t d_max_symbols_without_valid_frame;
00091
00092     bool d_dump;
00093     bool d_sent_tlm_failed_msg;
00094     bool d_flag_PLL_180_deg_phase_locked;
00095     bool d_flag_valid_word;
00096     bool d_dump_mat;
00097     bool d_remove_dat;
00098     bool d_enable_navdata_monitor;
00099     bool d_dump_crc_stats;
00100     bool d_tow_to_trk;
00101 };
00102
00103
00104 /** \} */
00105 /** \} */
00106 #endif // GNSS_SDR_GPS_L2C_TELEMETRY_DECODER_GS_H

```

13.498 gps_l5_telemetry_decoder_gs.h File Reference

Interface of a CNAV message demodulator block.

```

#include "GPS_L5.h"
#include "gps_cnav_navigation_message.h"
#include "nav_message_packet.h"
#include "telemetry_impl_interface.h"
#include "tlm_conf.h"
#include <boost/circular_buffer.hpp>
#include <gnuradio/types.h>
#include "cnav_msg.h"

```

Classes

- class [gps_l5_telemetry_decoder_gs](#)
This class implements a GPS L5 Telemetry decoder.

Typedefs

- using [gps_l5_telemetry_decoder_gs_sptr](#) = [gnss_shared_ptr](#)<[gps_l5_telemetry_decoder_gs](#)>

Functions

- [gps_l5_telemetry_decoder_gs_sptr](#) [gps_l5_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, const [Tlm_Conf](#) &conf, CnavSystem system=CnavSystem::GPS)

13.498.1 Detailed Description

Interface of a CNAV message demodulator block.

Author

Antonio Ramos, 2017. antonio.ramos(at)cttc.es

13.498.1.1 autotoc_md497

Author

Carles Fernandez Prades, 2017-2026. cfernandez(at)cttc.es

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Definition in file [gps_l5_telemetry_decoder_gs.h](#).

13.499 gps_l5_telemetry_decoder_gs.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gps_l5_telemetry_decoder_gs.h
00003  * \brief Interface of a CNAV message demodulator block
00004  * \author Antonio Ramos, 2017. antonio.ramos(at)cttc.es
00005  * \author Carles Fernandez Prades, 2017-2026. cfernandez(at)cttc.es
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_GPS_L5_TELEMETRY_DECODER_GS_H
00018 #define GNSS_SDR_GPS_L5_TELEMETRY_DECODER_GS_H
00019
00020
00021 #include "GPS_L5.h" // for GPS_L5I_NH_CODE_LENGTH
00022 #include "gps_cnav_navigation_message.h" // for Gps_CNAV_Navigation_Message
00023 #include "nav_message_packet.h"
00024 #include "telemetry_impl_interface.h"
00025 #include "tlm_conf.h"
00026 #include <boost/circular_buffer.hpp>
00027 #include <gnuradio/types.h> // for gr_vector_const_void_star
00028
00029 extern "C"
00030 {
00031     #include "cnav_msg.h"
00032 }
00033
00034 /** \addtogroup Telemetry_Decoder
00035  * \{ */
00036 /** \addtogroup Telemetry_Decoder_gnuradio_blocks
00037  * \{ */
00038
00039
00040 class gps_l5_telemetry_decoder_gs;
00041
00042 using gps_l5_telemetry_decoder_gs_sptr = gnss_shared_ptr<gps_l5_telemetry_decoder_gs>;
00043
00044 gps_l5_telemetry_decoder_gs_sptr gps_l5_make_telemetry_decoder_gs(
00045     const Gnss_Satellite &satellite,
00046     const Tlm_Conf &conf,
00047     CnavSystem system = CnavSystem::GPS);
00048
00049 /*!
00050 * \brief This class implements a GPS L5 Telemetry decoder
00051 *
00052 */
00053 class gps_l5_telemetry_decoder_gs : public telemetry_impl_interface
00054 {
00055 public:
00056     ~gps_l5_telemetry_decoder_gs() override;
00057     void set_satellite(const Gnss_Satellite &satellite) override; //!< Set satellite PRN
00058     void set_channel(int32_t channel) override; //!< Set receiver's channel
00059     void reset() override;
00060     int general_work(int noutput_items, gr_vector_int &ninput_items,
00061         gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override;
00062
00063 private:
00064     friend gps_l5_telemetry_decoder_gs_sptr gps_l5_make_telemetry_decoder_gs(
00065         const Gnss_Satellite &satellite,
00066         const Tlm_Conf &conf,
00067         CnavSystem system);
00068
00069     gps_l5_telemetry_decoder_gs(const Gnss_Satellite &satellite, const Tlm_Conf &conf, CnavSystem
00070         system);

```

```

00070
00071     cnav\_msg\_decoder\_t d_cnav_decoder{};
00072
00073     Gnss\_Satellite d_satellite;
00074     CnavSystem d_system;
00075
00076     std::unique_ptr<Gps_CNAV_Navigation_Message> d_CNAV_Message;
00077
00078     Nav\_Message\_Packet d_nav_msg_packet;
00079     std::unique_ptr<Tlm_CRC_Stats> d_Tlm_CRC_Stats;
00080
00081     std::string d_dump_filename;
00082     std::ofstream d_dump_file;
00083
00084     uint64_t d_sample_counter;
00085     uint64_t d_last_valid_preamble;
00086
00087     int32_t d_channel;
00088
00089     uint32_t d_TOW_at_current_symbol_ms;
00090     uint32_t d_TOW_at_Preamble_ms;
00091     uint32_t d_max_symbols_without_valid_frame;
00092
00093     bool d_flag_PLL_180_deg_phase_locked;
00094     bool d_flag_valid_word;
00095     bool d_sent_tlm_failed_msg;
00096     bool d_dump;
00097     bool d_dump_mat;
00098     bool d_remove_dat;
00099     bool d_enable_navdata_monitor;
00100     bool d_dump_crc_stats;
00101     bool d_tow_to_trk;
00102 };
00103
00104
00105 /** \} */
00106 /** \} */
00107 #endif // GNSS_SDR_GPS_L5_TELEMETRY_DECODER_GS_H

```

13.500 sbas_l1_telemetry_decoder_gs.h File Reference

Interface of a SBAS telemetry data decoder block.

```

#include "telemetry_impl_interface.h"
#include <boost/crc.hpp>
#include <gnuradio/types.h>
#include <cstdint>
#include <deque>
#include <vector>

```

Classes

- class [sbas_l1_telemetry_decoder_gs](#)

This class implements a block that decodes the SBAS integrity and corrections data defined in RTCA MOPS DO-229.

Typedefs

- using [sbas_l1_telemetry_decoder_gs_sptr](#) = gnss_shared_ptr<[sbas_l1_telemetry_decoder_gs](#)>

Functions

- [sbas_l1_telemetry_decoder_gs_sptr sbas_l1_make_telemetry_decoder_gs](#) (const [Gnss_Satellite](#) &satellite, bool dump)

13.500.1 Detailed Description

Interface of a SBAS telemetry data decoder block.

Author

Daniel Fehr 2013. daniel.co(at)bluewin.ch

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Definition in file [sbas_l1_telemetry_decoder_gs.h](#).

13.501 sbas_l1_telemetry_decoder_gs.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file sbas_l1_telemetry_decoder_gs.h
00003  * \brief Interface of a SBAS telemetry data decoder block
00004  * \author Daniel Fehr 2013. daniel.co(at)bluewin.ch
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_SBAS_L1_TELEMETRY_DECODER_GS_H
00018 #define GNSS_SDR_SBAS_L1_TELEMETRY_DECODER_GS_H
00019
00020 #include "telemetry_impl_interface.h"
00021 #include <boost/crc.hpp> // for crc_optimal
00022 #include <gnuradio/types.h> // for gr_vector_const_void_star
00023 #include <cstdint> // for size_t
00024 #include <deque>
00025 #include <vector>
00026
00027 /** \addtogroup Telemetry_Decoder
00028  * \{ */
00029 /** \addtogroup Telemetry_Decoder_gnuradio_blocks
00030  * \{ */
00031
00032
00033 class Viterbi_Decoder_Sbas;
00034
00035 class sbas_l1_telemetry_decoder_gs;
00036
00037 using sbas_l1_telemetry_decoder_gs_sptr = gnss_shared_ptr<sbas_l1_telemetry_decoder_gs>;
00038
00039 sbas_l1_telemetry_decoder_gs_sptr sbas_l1_make_telemetry_decoder_gs(
00040     const Gnss_Satellite &satellite,
00041     bool dump);
00042
00043 /*!
00044  * \brief This class implements a block that decodes the SBAS integrity and
00045  * corrections data defined in RTCA MOPS DO-229
00046  */
00047 class sbas_l1_telemetry_decoder_gs : public telemetry_impl_interface
00048 {
00049 public:
00050     ~sbas_l1_telemetry_decoder_gs() override;
00051     void set_satellite(const Gnss_Satellite &satellite) override; //!< Set satellite PRN
00052     void set_channel(int32_t channel) override; //!< Set receiver's channel
00053     inline void reset() override {};
00054
00055     /*!
00056     * \brief This is where all signal processing takes place
00057     */
00058     int general_work(int noutput_items, gr_vector_int &ninput_items,
00059         gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override;
00060
00061 private:
00062     friend sbas_l1_telemetry_decoder_gs_sptr sbas_l1_make_telemetry_decoder_gs(
00063         const Gnss_Satellite &satellite,
00064         bool dump);
00065
00066     sbas_l1_telemetry_decoder_gs(const Gnss_Satellite &satellite, bool dump);
00067
00068     void viterbi_decoder(double *page_part_symbols, int32_t *page_part_bits);
00069     void align_samples();
00070
00071     static const int32_t D_SAMPLES_PER_SYMBOL = 2;
00072     static const int32_t D_SYMBOLS_PER_BIT = 2;

```

```

00073     static const int32_t D_BLOCK_SIZE_IN_BITS = 30;
00074
00075     bool d_dump;
00076     Gnss_Satellite d_satellite;
00077     int32_t d_channel;
00078
00079     std::string d_dump_filename;
00080     std::ofstream d_dump_file;
00081
00082     size_t d_block_size;           //!< number of samples which are processed during one
    invocation of the algorithms
00083     std::vector<double> d_sample_buf;  //!< input buffer holding the samples to be processed in one
    block
00084
00085     typedef std::pair<int32_t, std::vector<int32_t> > msg_candidate_int_t;
00086     typedef std::pair<int32_t, std::vector<uint8_t> > msg_candidate_char_t;
00087
00088     // helper class for sample alignment
00089     class Sample_Aligner
00090     {
00091     public:
00092         Sample_Aligner();
00093         void reset();
00094         /*
00095          * samples length must be a multiple of two
00096          * for block operation
00097          */
00098         bool get_symbols(const std::vector<double> &samples, std::vector<double> &symbols);
00099
00100     private:
00101         int32_t d_n_smpls_in_history{3};
00102         double d_iir_par{0.05};
00103         double d_corr_paired{};
00104         double d_corr_shifted{};
00105         bool d_aligned{};
00106         double d_past_sample{};
00107     } d_sample_aligner;
00108
00109     // helper class for symbol alignment and Viterbi decoding
00110     class Symbol_Aligner_And_Decoder
00111     {
00112     public:
00113         Symbol_Aligner_And_Decoder();
00114         void reset();
00115         bool get_bits(const std::vector<double> &symbols, std::vector<int32_t> &bits);
00116
00117     private:
00118         int32_t d_KK{7};
00119         std::shared_ptr<Viterbi_Decoder_Sbas> d_vd1;
00120         std::shared_ptr<Viterbi_Decoder_Sbas> d_vd2;
00121         double d_past_symbol{0};
00122     } d_symbol_aligner_and_decoder;
00123
00124
00125     // helper class for detecting the preamble and collect the corresponding message candidates
00126     class Frame_Detector
00127     {
00128     public:
00129         void reset();
00130         void get_frame_candidates(const std::vector<int32_t> &bits, std::vector<std::pair<int32_t,
    std::vector<int32_t>> &msg_candidates);
00131
00132     private:
00133         std::deque<int32_t> d_buffer;
00134     } d_frame_detector;
00135
00136
00137     // helper class for checking the CRC of the message candidates
00138     class Crc_Verifier
00139     {
00140     public:
00141         void reset();
00142         void get_valid_frames(const std::vector<msg_candidate_int_t> &msg_candidates,
    std::vector<msg_candidate_char_t> &valid_msgs);
00143
00144     private:
00145         typedef boost::crc_optimal<24, 0x1864CFBU, 0x0, 0x0, false, false> crc_24_q_type;
00146         crc_24_q_type d_checksum_agent;
00147         void zerropad_front_and_convert_to_bytes(const std::vector<int32_t> &msg_candidate,
    std::vector<uint8_t> &bytes);
00148         void zerropad_back_and_convert_to_bytes(const std::vector<int32_t> &msg_candidate,
    std::vector<uint8_t> &bytes);
00149     } d_crc_verifier;
00150 };
00151
00152
00153 /** \} */

```

```
00154 /** \} */
00155 #endif // GNSS_SDR_SBAS_L1_TELEMETRY_DECODER_GS_H
```

13.502 telemetry_impl_interface.h File Reference

Base class for telemetry decoder GNU Radio blocks.

```
#include "gnss_block_interface.h"
#include "gnss_satellite.h"
#include <gnuradio/block.h>
#include <gnuradio/io_signature.h>
#include <stdint>
#include <fstream>
#include <memory>
#include <string>
#include <utility>
```

Classes

- class [telemetry_impl_interface](#)

Common base class for telemetry decoder GNU Radio implementations.

Typedefs

- using [telemetry_impl_interface_sptr](#) = `gnss_shared_ptr<telemetry_impl_interface>`

13.502.1 Detailed Description

Base class for telemetry decoder GNU Radio blocks.

Author

Carles Fernandez-Prades, 2025 cfernandez@cttc.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.
 Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors) SPDX-License-Identifier: GPL-3.0-or-later
 Definition in file [telemetry_impl_interface.h](#).

13.503 telemetry_impl_interface.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file telemetry_impl_interface.h
00003  * \brief Base class for telemetry decoder GNU Radio blocks.
00004  * \author Carles Fernandez-Prades, 2025 cfernandez@cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_TELEMETRY_IMPL_INTERFACE_H
00018 #define GNSS_SDR_TELEMETRY_IMPL_INTERFACE_H
00019
00020 #include "gnss_block_interface.h"
00021 #include "gnss_satellite.h"
00022 #include <gnuradio/block.h>
00023 #include <gnuradio/io_signature.h>
00024 #include <stdint>
00025 #include <fstream>
00026 #include <memory>
00027 #include <string>
```

```

00028 #include <utility>
00029
00030 class Tlm_CRC_Stats;
00031
00032 /** \addtogroup Telemetry_Decoder
00033 * \{
00034 */
00035 /** \addtogroup Telemetry_Decoder_gnuradio_blocks telemetry_decoder_gr_blocks
00036 * \{
00037 */
00038
00039 class telemetry_impl_interface;
00040 using telemetry_impl_interface_sp_ptr = gnss_shared_ptr<telemetry_impl_interface>;
00041
00042 /*!
00043 * \brief Common base class for telemetry decoder GNU Radio implementations.
00044 */
00045 class telemetry_impl_interface : public gr::block
00046 {
00047 public:
00048     telemetry_impl_interface(const std::string& name,
00049         gr::io_signature::sp_ptr input_signature,
00050         gr::io_signature::sp_ptr output_signature)
00051         : gr::block(name,
00052             std::move(input_signature),
00053             std::move(output_signature)) {}
00054
00055     ~telemetry_impl_interface() override = default;
00056
00057     virtual void set_satellite(const Gnss_Satellite& satellite) = 0;
00058     virtual void set_channel(int channel) = 0;
00059     virtual void reset() = 0;
00060
00061 protected:
00062     void configure_basic_outputs();
00063
00064     void configure_dump_file(int32_t channel,
00065         bool enable_dump,
00066         std::string& dump_filename,
00067         std::ofstream& dump_file) const;
00068
00069     void configure_crc_stats_channel(int32_t channel,
00070         bool& dump_crc_stats,
00071         std::unique_ptr<Tlm_CRC_Stats>& crc_stats) const;
00072 };
00073
00074 /** \} */
00075 /** \} */
00076
00077 #endif // GNSS_SDR_TELEMETRY_IMPL_INTERFACE_H

```

13.504 bits.h File Reference

Utilities for bit manipulation of the libswiftnav library.

```
#include "swift_common.h"
```

Functions

- uint8_t **parity** (uint32_t x)
- uint32_t **getbitu** (const uint8_t *buff, uint32_t pos, uint8_t len)
- int32_t **getbits** (const uint8_t *buff, uint32_t pos, uint8_t len)
- void **setbitu** (uint8_t *buff, uint32_t pos, uint32_t len, uint32_t data)
- void **setbits** (uint8_t *buff, uint32_t pos, uint32_t len, int32_t data)
- void **bitcopy** (void *dst, uint32_t dst_index, const void *src, uint32_t src_index, uint32_t count)
- void **bitshl** (void *buf, uint32_t size, uint32_t shift)
- uint8_t **count_bits_u64** (uint64_t v, uint8_t bv)
- uint8_t **count_bits_u32** (uint32_t v, uint8_t bv)
- uint8_t **count_bits_u16** (uint16_t v, uint8_t bv)
- uint8_t **count_bits_u8** (uint8_t v, uint8_t bv)

13.504.1 Detailed Description

Utilities for bit manipulation of the libswiftnav library.

Author

Fergus Noble fergus@swift-nav.com

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

This file was originally borrowed from libswiftnav <https://github.com/swift-nav/libswiftnav>, a portable C library implementing GNSS related functions and algorithms, and then modified by J. Arribas and C. Fernandez

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Definition in file [bits.h](#).

13.505 bits.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file bits.h
00003  * \brief Utilities for bit manipulation of the libswiftnav library
00004  * \author Fergus Noble <fergus@swift-nav.com>
00005  *
00006  * -----
00007  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00008  * This file is part of GNSS-SDR.
00009  *
00010  * This file was originally borrowed from libswiftnav
00011  * <https://github.com/swift-nav/libswiftnav>,
00012  * a portable C library implementing GNSS related functions and algorithms,
00013  * and then modified by J. Arribas and C. Fernandez
00014  *
00015  * Copyright (C) 2013, 2016 Swift Navigation Inc.
00016  * Contact: Fergus Noble <fergus@swift-nav.com>
00017  *
00018  * SPDX-License-Identifier: LGPL-3.0-only
00019  *
00020  */
00021
00022 #ifndef GNSS_SDR_BITS_H
00023 #define GNSS_SDR_BITS_H
00024
00025 #include "swift_common.h"
00026
00027 /** \addtogroup Telemetry_Decoder
00028  * \{ */
00029 /** \addtogroup Telemetry_Decoder_libswiftcnv telemetry_decoder_libswiftcnv
00030  * Utilities for CNAV message decoding by Swift Navigation Inc.
00031  * \{ */
00032
00033
00034 uint8_t parity(uint32_t x);
00035 uint32_t getbitu(const uint8_t *buff, uint32_t pos, uint8_t len);
00036 int32_t getbits(const uint8_t *buff, uint32_t pos, uint8_t len);
00037 void setbitu(uint8_t *buff, uint32_t pos, uint32_t len, uint32_t data);
00038 void setbits(uint8_t *buff, uint32_t pos, uint32_t len, int32_t data);
00039 void bitcopy(void *dst, uint32_t dst_index,
00040             const void *src, uint32_t src_index, uint32_t count);
00041 void bitshl(void *buf, uint32_t size, uint32_t shift);
00042 uint8_t count_bits_u64(uint64_t v, uint8_t bv);
00043 uint8_t count_bits_u32(uint32_t v, uint8_t bv);
00044 uint8_t count_bits_u16(uint16_t v, uint8_t bv);
00045 uint8_t count_bits_u8(uint8_t v, uint8_t bv);
00046
00047
00048 /** \} */
00049 /** \} */
00050 #endif /* GNSS_SDR_BITS_H */

```

13.506 cnav_msg.h File Reference

Utilities for CNAV message manipulation of the libswiftnav library.

```

#include "fec.h"
#include "swift_common.h"
#include <limits.h>
#include <stdbool.h>
#include <stdint.h>

```

```
#include <stdlib.h>
```

Classes

- struct [cnav_msg_t](#)
- struct [cnav_v27_part_t](#)
- struct [cnav_msg_decoder_t](#)

Macros

- #define [GPS_L2_V27_HISTORY_LENGTH_BITS](#) 64
- #define [GPS_L2C_V27_INIT_BITS](#) (32)
- #define [GPS_L2C_V27_DECODE_BITS](#) (32)
- #define [GPS_L2C_V27_DELAY_BITS](#) (32)

Functions

- const [v27_poly_t](#) * [cnav_msg_decoder_get_poly](#) (void)
- void [cnav_msg_decoder_init](#) ([cnav_msg_decoder_t](#) *dec)
- bool [cnav_msg_decoder_add_symbol](#) ([cnav_msg_decoder_t](#) *dec, unsigned char symbol, [cnav_msg_t](#) *msg, uint32_t *delay)

13.506.1 Detailed Description

Utilities for CNAV message manipulation of the libswiftnav library.

Author

Valeri Atamaniouk valeri@swift-nav.com

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR. This file was originally borrowed from libswiftnav <https://github.com/swift-nav/libswiftnav>, a portable C library implementing GNSS related functions and algorithms, and then modified by J. Arribas and C. Fernandez

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SPDX-License-Identifier: LGPL-3.0-only

Definition in file [cnav_msg.h](#).

13.507 cnav_msg.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file cnav_msg.h
00003  * \brief Utilities for CNAV message manipulation of the libswiftnav library
00004  * \author Valeri Atamaniouk <valeri@swift-nav.com>
00005  *
00006  * -----
00007  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00008  * This file is part of GNSS-SDR.
00009  *
00010  * This file was originally borrowed from libswiftnav
00011  * <https://github.com/swift-nav/libswiftnav>,
00012  * a portable C library implementing GNSS related functions and algorithms,
00013  * and then modified by J. Arribas and C. Fernandez
00014  *
00015  * Copyright (C) 2016 Swift Navigation Inc.
00016  * Contact: Valeri Atamaniouk <valeri@swift-nav.com>
00017  *
00018  * SPDX-License-Identifier: LGPL-3.0-only
00019  *
00020  */
00021
00022
00023 #ifndef GNSS_SDR_CNAV_MSG_H
00024 #define GNSS_SDR_CNAV_MSG_H
00025
```

```

00026 #include "fec.h"
00027 #include "swift_common.h"
00028 #include <limits.h>
00029 #include <stdbool.h>
00030 #include <stdint.h>
00031 #include <stdlib.h>
00032
00033 /** \addtogroup Telemetry_Decoder
00034 * \{ */
00035 /** \addtogroup Telemetry_Decoder_libswiftcnv
00036 * \{ */
00037
00038
00039 /** Size of the Viterbi decoder history. */
00040 #define GPS_L2_V27_HISTORY_LENGTH_BITS 64
00041 /** Bits to accumulate before decoding starts. */
00042 #define GPS_L2C_V27_INIT_BITS (32)
00043 /** Bits to decode at a time. */
00044 #define GPS_L2C_V27_DECODE_BITS (32)
00045 /** Bits in decoder tail. We ignore them. */
00046 #define GPS_L2C_V27_DELAY_BITS (32)
00047 /**
00048 * GPS CNAV message container.
00049 *
00050 * @sa cnav_msg_decoder_add_symbol
00051 */
00052 typedef struct
00053 {
00054     uint8_t prn; /**< SV PRN. 0..31 */
00055     uint8_t msg_id; /**< Message id. 0..31 */
00056     uint32_t tow; /**< GPS ToW in 6-second units.
00057     Multiply to 6 to get seconds. */
00058     bool alert; /**< CNAV message alert flag */
00059     uint8_t raw_msg[GPS_L2C_V27_DECODE_BITS + GPS_L2C_V27_DELAY_BITS]; /**< RAW MSG for GNSS-SDR */
00060 } cnav_msg_t;
00061
00062 /**
00063 * GPS CNAV decoder component.
00064 * This component controls symbol decoding string.
00065 *
00066 * @sa cnav_msg_decoder_t
00067 */
00068 typedef struct
00069 {
00070     v27_t dec; /**< Viterbi block decoder object */
00071     v27_decision_t decisions[GPS_L2_V27_HISTORY_LENGTH_BITS];
00072     /**< Decision graph */
00073     unsigned char symbols[(GPS_L2C_V27_INIT_BITS + GPS_L2C_V27_DECODE_BITS) * 2];
00074     /**< Symbol buffer */
00075     size_t n_symbols; /**< Count of symbols in the symbol buffer */
00076     unsigned char decoded[GPS_L2C_V27_DECODE_BITS + GPS_L2C_V27_DELAY_BITS];
00077     /**< Decode buffer */
00078     size_t n_decoded; /**< Number of bits in the decode buffer */
00079     bool preamble_seen; /**< When true, the decode buffer is aligned on
00080     * preamble. */
00081     bool invert; /**< When true, indicates the bits are inverted */
00082     bool message_lock; /**< When true, indicates the message boundary
00083     * is found. */
00084     bool crc_ok; /**< Flag that the last message had good CRC */
00085     size_t n_crc_fail; /**< Counter for CRC failures */
00086     bool init; /**< Initial state flag. When true, initial bits
00087     * do not produce output. */
00088 } cnav_v27_part_t;
00089
00090 /**
00091 * GPS CNAV message lock and decoder object.
00092 * Decoder uses two Viterbi decoder objects to ensure the lock is acquired when
00093 * the input symbol phase is not known.
00094 */
00095 typedef struct
00096 {
00097     cnav_v27_part_t part1; /**< Decoder for odd symbol pairs */
00098     cnav_v27_part_t part2; /**< Decoder for even symbol pairs */
00099 } cnav_msg_decoder_t;
00100
00101 const v27_poly_t *cnav_msg_decoder_get_poly(void);
00102 void cnav_msg_decoder_init(cnav_msg_decoder_t *dec);
00103 bool cnav_msg_decoder_add_symbol(cnav_msg_decoder_t *dec,
00104     unsigned char symbol,
00105     cnav_msg_t *msg,
00106     uint32_t *delay);
00107
00108 /** \} */
00109 /** \} */
00110 #endif /* GNSS_SDR_CNAV_MSG_H_ */

```

13.508 edc.h File Reference

Utilities for CRC computation of the libswiftnav library.

```
#include "swift_common.h"
```

Functions

- uint32_t **crc24q** (const uint8_t *buf, uint32_t len, uint32_t crc)
- uint32_t **crc24q_bits** (uint32_t crc, const uint8_t *buf, uint32_t n_bits, bool invert)

13.508.1 Detailed Description

Utilities for CRC computation of the libswiftnav library.

Author

Fergus Noble fergus@swift-nav.com

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

This file was originally borrowed from libswiftnav <https://github.com/swift-nav/libswiftnav>, a portable C library implementing GNSS related functions and algorithms, and then modified by J. Arribas and C. Fernandez

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Definition in file [edc.h](#).

13.509 edc.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file edc.h
00003  * \brief Utilities for CRC computation of the libswiftnav library
00004  * \author Fergus Noble <fergus@swift-nav.com>
00005  *
00006  * -----
00007  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00008  * This file is part of GNSS-SDR.
00009  *
00010  * This file was originally borrowed from libswiftnav
00011  * <https://github.com/swift-nav/libswiftnav>,
00012  * a portable C library implementing GNSS related functions and algorithms,
00013  * and then modified by J. Arribas and C. Fernandez
00014  *
00015  * Copyright (C) 2010 Swift Navigation Inc.
00016  * Contact: Fergus Noble <fergus@swift-nav.com>
00017  *
00018  * SPDX-License-Identifier: LGPL-3.0-only
00019  *
00020  */
00021
00022
00023 #ifndef GNSS_SDR_EDC_H
00024 #define GNSS_SDR_EDC_H
00025
00026 #include "swift_common.h"
00027
00028 /** \addtogroup Telemetry_Decoder
00029  * \{ */
00030 /** \addtogroup Telemetry_Decoder_libswiftcnv
00031  * \{ */
00032
00033
00034 uint32_t crc24q(const uint8_t *buf, uint32_t len, uint32_t crc);
00035 uint32_t crc24q_bits(uint32_t crc, const uint8_t *buf, uint32_t n_bits, bool invert);
00036
00037
00038 /** \} */
00039 /** \} */
00040 #endif /* GNSS_SDR_EDC_H */
```


13.510 fec.h File Reference

Utilities for the convolutional encoder of the libswiftnav library.

Classes

- struct [v27_poly_t](#)
- struct [v27_decision_t](#)
- struct [v27_t](#)

Macros

- `#define V27POLYA 0x4f`
- `#define V27POLYB 0x6d`

Functions

- void [v27_poly_init](#) ([v27_poly_t](#) *poly, const signed char polynomial[2])
- void [v27_init](#) ([v27_t](#) *v, [v27_decision_t](#) *decisions, unsigned int decisions_count, const [v27_poly_t](#) *poly, unsigned char initial_state)
- void [v27_update](#) ([v27_t](#) *v, const unsigned char *syms, int nbits)
- void [v27_chainback_fixed](#) ([v27_t](#) *v, unsigned char *data, unsigned int nbits, unsigned char final_state)
- void [v27_chainback_likely](#) ([v27_t](#) *v, unsigned char *data, unsigned int nbits)

13.510.1 Detailed Description

Utilities for the convolutional encoder of the libswiftnav library.

Author

Phil Karn, KA9Q

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

This file was originally borrowed from libswiftnav <https://github.com/swift-nav/libswiftnav>, a portable C library implementing GNSS related functions and algorithms, and then modified by J. Arribas and C. Fernandez

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Definition in file [fec.h](#).

13.510.2 Macro Definition Documentation

13.510.2.1 V27POLYA

```
#define V27POLYA 0x4f
```

Definition at line 29 of file [fec.h](#).

13.510.2.2 V27POLYB

```
#define V27POLYB 0x6d
```

Definition at line 30 of file [fec.h](#).

13.511 fec.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file fec.h
00003  * \brief Utilities for the convolutional encoder of the libswiftnav library
00004  * \author Phil Karn, KA9Q
00005  *
00006  * -----
00007  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
```

```

00008  * This file is part of GNSS-SDR.
00009  *
00010  * This file was originally borrowed from libswiftnav
00011  * <https://github.com/swift-nav/libswiftnav>,
00012  * a portable C library implementing GNSS related functions and algorithms,
00013  * and then modified by J. Arribas and C. Fernandez
00014  *
00015  * Copyright (C) 2004, Phil Karn, KA9Q
00016  *
00017  * SPDX-License-Identifier: LGPL-3.0-only
00018  *
00019  */
00020
00021
00022 #ifndef GNSS_SDR_FEC_H
00023 #define GNSS_SDR_FEC_H
00024
00025 /* r=1/2 k=7 convolutional encoder polynomials
00026  * The NASA-DSN convention is to use V27POLYA inverted, then V27POLYB
00027  * The CCSDS/NASA-GSFC convention is to use V27POLYB, then V27POLYA inverted
00028  */
00029 #define V27POLYA 0x4f
00030 #define V27POLYB 0x6d
00031
00032 typedef struct
00033 {
00034     unsigned char c0[32];
00035     unsigned char c1[32];
00036 } v27_poly_t;
00037
00038 typedef struct
00039 {
00040     unsigned int w[2];
00041 } v27_decision_t;
00042
00043 /* State info for instance of r=1/2 k=7 Viterbi decoder
00044  */
00045 typedef struct
00046 {
00047     unsigned int metrics1[64]; /* Path metric buffer 1 */
00048     unsigned int metrics2[64]; /* Path metric buffer 2 */
00049     /* Pointers to path metrics, swapped on every bit */
00050     unsigned int *old_metrics, *new_metrics;
00051     const v27_poly_t *poly; /* Polynomial to use */
00052     v27_decision_t *decisions; /* Beginning of decisions for block */
00053     unsigned int decisions_index; /* Index of current decision */
00054     unsigned int decisions_count; /* Number of decisions in history */
00055 } v27_t;
00056
00057 void v27_poly_init(v27_poly_t *poly, const signed char polynomial[2]);
00058
00059 void v27_init(v27_t *v, v27_decision_t *decisions, unsigned int decisions_count,
00060              const v27_poly_t *poly, unsigned char initial_state);
00061 void v27_update(v27_t *v, const unsigned char *syms, int nbits);
00062 void v27_chainback_fixed(v27_t *v, unsigned char *data, unsigned int nbits,
00063                          unsigned char final_state);
00064 void v27_chainback_likely(v27_t *v, unsigned char *data, unsigned int nbits);
00065
00066 #endif

```

13.512 swift_common.h File Reference

Common definitions used throughout the libswiftnav library.

```

#include <inttypes.h>
#include <stdbool.h>
#include <stdint.h>

```

Macros

- #define ABS(x)
- #define MIN(x, y)
- #define MAX(x, y)
- #define CLAMP_DIFF(a, b)

13.512.1 Detailed Description

Common definitions used throughout the libswiftnav library.

Author

Henry Hallam henry@swift-nav.com Fergus Noble fergus@swift-nav.com

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

This file was originally borrowed from libswiftnav <https://github.com/swift-nav/libswiftnav>, a portable C library implementing GNSS related functions and algorithms, and then modified by J. Arribas and C. Fernandez

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Definition in file [swift_common.h](#).

13.513 swift_common.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file swift_common.h
00003  * \brief Common definitions used throughout the libswiftnav library
00004  * \author Henry Hallam <henry@swift-nav.com>
00005  *         Fergus Noble <fergus@swift-nav.com>
00006  *
00007  * -----
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * This file was originally borrowed from libswiftnav
00012  * <https://github.com/swift-nav/libswiftnav>,
00013  * a portable C library implementing GNSS related functions and algorithms,
00014  * and then modified by J. Arribas and C. Fernandez
00015  *
00016  * Copyright (C) 2012 Swift Navigation Inc.
00017  * Contact: Henry Hallam <henry@swift-nav.com>
00018  *         Fergus Noble <fergus@swift-nav.com>
00019  *
00020  * SPDX-License-Identifier: LGPL-3.0-only
00021  *
00022  */
00023
00024
00025 #ifndef GNSS_SDR_SWIFT_COMMON_H
00026 #define GNSS_SDR_SWIFT_COMMON_H
00027
00028 /** \addtogroup Telemetry_Decoder
00029  * \{ */
00030 /** \addtogroup Telemetry_Decoder_libswiftnav
00031  * \{ */
00032
00033
00034 #define ABS(x) ((x) < 0 ? -(x) : (x))
00035 #define MIN(x, y) (((x) < (y)) ? (x) : (y))
00036 #define MAX(x, y) (((x) > (y)) ? (x) : (y))
00037 #define CLAMP_DIFF(a, b) (MAX((a), (b)) - (b))
00038
00039 #include <inttypes.h>
00040 #include <stdbool.h>
00041 #include <stdint.h>
00042
00043
00044 /** \} */
00045 /** \} */
00046 #endif /* GNSS_SDR_SWIFT_COMMON_H */
```

13.514 tlm_conf.h File Reference

Class that contains all the configuration parameters for generic telemetry decoder block.

```
#include "configuration_interface.h"
#include <string>
```

Classes

- class [Tlm_Conf](#)

13.514.1 Detailed Description

Class that contains all the configuration parameters for generic telemetry decoder block.

Author

Carles Fernandez, 2020. cfernandez(at)cttc.es

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 Definition in file [tlm_conf.h](#).

13.515 tlm_conf.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file tlm_conf.h
00003  * \brief Class that contains all the configuration parameters for generic
00004  * telemetry decoder block.
00005  * \author Carles Fernandez, 2020. cfernandez(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_TLM_CONF_H
00019 #define GNSS_SDR_TLM_CONF_H
00020
00021 #include "configuration_interface.h"
00022 #include <string>
00023
00024 /** \addtogroup Telemetry_Decoder
00025  * \{ */
00026 /** \addtogroup Telemetry_Decoder_libs
00027  * \{ */
00028
00029
00030 class Tlm_Conf
00031 {
00032 public:
00033     Tlm_Conf() = default;
00034
00035     void SetFromConfiguration(const ConfigurationInterface *configuration, const std::string &role);
00036
00037     std::string dump_filename;
00038     std::string dump_crc_stats_filename;
00039     bool dump{false};
00040     bool dump_mat{false};
00041     bool remove_dat{false};
00042     bool enable_reed_solomon{false}; // for INAV message in Galileo E1B
00043     bool dump_crc_stats{false}; // telemetry CRC statistics
00044     bool enable_navdata_monitor{false};
00045     bool there_are_e1_channels{false};
00046     bool there_are_e6_channels{false};
00047     bool use_ced{false};
00048     bool tow_to_trk{false};
00049 };
00050
00051
00052 /** \} */
00053 /** \} */
00054 #endif // GNSS_SDR_TLM_CONF_H

```

13.516 tlm_crc_stats.h File Reference

Class that computes the telemetry CRC statistics.

```
#include <stdint>
#include <fstream>
#include <string>
```

Classes

- class [Tlm_CRC_Stats](#)

Class that computes the telemetry CRC statistics.

13.516.1 Detailed Description

Class that computes the telemetry CRC statistics.

Author

Marc Majoral, 2021. mmajoral(at)cttc.es

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 Definition in file [tlm_crc_stats.h](#).

13.517 tlm_crc_stats.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file tlm_crc_stats.h
00003  * \brief Class that computes the telemetry CRC statistics
00004  * \author Marc Majoral, 2021. mmajoral(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_CRC_STATS_H
00018 #define GNSS_SDR_CRC_STATS_H
00019
00020 #include <stdint>
00021 #include <fstream> // for std::ofstream
00022 #include <string> // for std::string
00023
00024 /** \addtogroup Telemetry_Decoder
00025  * \{ */
00026 /** \addtogroup Telemetry_Decoder_libs telemetry_decoder_libs
00027  * \{ */
00028
00029 /*!
00030  * \brief Class that computes the telemetry CRC statistics
00031  */
00032 class Tlm_CRC_Stats
00033 {
00034 public:
00035     Tlm_CRC_Stats() = default;
00036
00037     ~Tlm_CRC_Stats();
00038
00039     /*!
00040     * \brief Initialize the telemetry CRC statistics
00041     */
00042     void initialize(std::string dump_crc_stats_filename);
00043
00044     /*!
00045     * \brief Initialize the channel number and output file
00046     */
00047     bool set_channel(int32_t channel);
00048
00049     /*!
00050     * \brief Update the CRC statistics
00051     */
```

```

00052     void update_CRC_stats(bool CRC);
00053
00054 private:
00055     std::ofstream d_dump_file;
00056     std::string d_dump_crc_stats_filename;
00057     uint32_t d_num_crc_ok{0};
00058     uint32_t d_num_crc_not_ok{0};
00059     int32_t d_channel{0};
00060     bool d_enable_crc_stats{false};
00061 };
00062
00063
00064 /** \} */
00065 /** \} */
00066 #endif // GNSS_SDR_CRC_STATS_H

```

13.518 tlm_utils.h File Reference

Utilities for the telemetry decoder blocks.

```
#include <string>
```

Functions

- int **save_tlm_matfile** (const std::string &dumpfile)
- bool **tlm_remove_file** (const std::string &file_to_remove)

13.518.1 Detailed Description

Utilities for the telemetry decoder blocks.

Author

Carles Fernandez, 2020. cfernandez(at)cttc.es

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Definition in file [tlm_utils.h](#).

13.519 tlm_utils.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file tlm_utils.h
00003  * \brief Utilities for the telemetry decoder blocks.
00004  * \author Carles Fernandez, 2020. cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_TLM_UTILS_H
00018 #define GNSS_SDR_TLM_UTILS_H
00019
00020 #include <string>
00021
00022 /** \addtogroup Telemetry_Decoder
00023  * \{ */
00024 /** \addtogroup Telemetry_Decoder_libs
00025  * \{ */
00026
00027 int save_tlm_matfile(const std::string &dumpfile);
00028
00029 bool tlm_remove_file(const std::string &file_to_remove);
00030
00031 /** \} */
00032 /** \} */
00033 #endif // GNSS_SDR_TLM_UTILS_H

```

13.520 viterbi_decoder.h File Reference

Class that implements a Viterbi decoder.

```
#include <array>
#include <cstdint>
#include <vector>
```

Classes

- class [Viterbi_Decoder](#)

Class that implements a Viterbi decoder.

13.520.1 Detailed Description

Class that implements a Viterbi decoder.

Author

Carles Fernandez, 2021. cfernandez(at)cttc.es

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Definition in file [viterbi_decoder.h](#).

13.521 viterbi_decoder.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file viterbi_decoder.h
00003  * \brief Class that implements a Viterbi decoder
00004  * \author Carles Fernandez, 2021. cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_VITERBI_DECODER_H
00018 #define GNSS_SDR_VITERBI_DECODER_H
00019
00020 #include <array>
00021 #include <cstdint>
00022 #include <vector>
00023
00024 /** \addtogroup Telemetry_Decoder
00025  * \{ */
00026 /** \addtogroup Telemetry_Decoder_libs
00027  * Utilities for the decoding of GNSS navigation messages.
00028  * \{ */
00029
00030
00031 /*!
00032  * \brief Class that implements a Viterbi decoder
00033  */
00034 class Viterbi_Decoder
00035 {
00036 public:
00037     /*!
00038      * \brief Constructor of a Viterbi decoder
00039      * \param[in] KK Constraint length
00040      * \param[in] nn Coding rate 1/n
00041      * \param[in] LL Data length
00042      * \param[in] g Polynomial G1 and G2
00043      */
00044     Viterbi_Decoder(int32_t KK, int32_t nn, int32_t LL, const std::array<int32_t, 2>& g);
00045
00046     /*!
00047      * \brief Uses the Viterbi algorithm to perform hard-decision decoding of a convolutional code.
```

```

00048     * \param[out] output_u_int    Hard decisions on the data bits
00049     * \param[in] input_c The received signal in LLR-form. For BPSK, must be in form  $r =$ 
00050     *  $2*a*y/(sigma^2)$ .
00051     */
00052     void decode(std::vector<int32_t>& output_u_int, const std::vector<float>& input_c);
00053
00054     /*!
00055     * \brief Reset internal status
00056     */
00057     void reset();
00058
00059 private:
00060     /*
00061     * Function that creates the transit and output vectors
00062     */
00063     void nsc_transit(std::vector<int32_t>& output_p,
00064                     std::vector<int32_t>& trans_p,
00065                     int32_t input) const;
00066
00067     /*
00068     * Computes the branch metric used for decoding.
00069     * \return (returned float) The metric between the hypothetical symbol and the received vector
00070     * \param[in] symbol      The hypothetical symbol
00071     */
00072     float Gamma(int32_t symbol) const;
00073
00074     /*
00075     * Determines if a symbol has odd (1) or even (0) parity
00076     * Output parameters:
00077     * \return (returned int): The symbol's parity = 1 for odd and 0 for even
00078     * \param[in] symbol      The integer-valued symbol
00079     * \param[in] length      The highest bit position in the symbol
00080     * This function is used by nsc_enc_bit()
00081     */
00082     int32_t parity_counter(int32_t symbol, int32_t length) const;
00083
00084     /*
00085     * Convolutionally encodes a single bit using a rate 1/n encoder.
00086     * Takes in one input bit at a time, and produces a n-bit output.
00087     * \return (returned int): Computed output
00088     * \param[in] input      The input data bit (i.e. a 0 or 1).
00089     * \param[in] state_in   The starting state of the encoder (an int from 0 to  $2^m-1$ ).
00090     * \param[out] state_out_p[] An integer containing the final state of the encoder
00091     *                          (i.e. the state after encoding this bit)
00092     * This function is used by nsc_transit()
00093     */
00094     int32_t nsc_enc_bit(int32_t* state_out_p,
00095                       int32_t input,
00096                       int32_t state_in) const;
00097
00098     std::vector<float> d_prev_section{};
00099     std::vector<float> d_next_section{};
00100
00101     std::vector<float> d_rec_array{};
00102     std::vector<float> d_metric_c{};
00103     std::vector<int32_t> d_prev_bit{};
00104     std::vector<int32_t> d_prev_state{};
00105     std::array<int32_t, 2> d_g{};
00106
00107     std::vector<int32_t> d_out0;
00108     std::vector<int32_t> d_out1;
00109     std::vector<int32_t> d_state0;
00110     std::vector<int32_t> d_state1;
00111
00112     float d_MAXLOG = 1e7; // Define infinity
00113     int32_t d_KK{};
00114     int32_t d_nn{};
00115     int32_t d_LL{};
00116
00117     int32_t d_mm{};
00118     int32_t d_states{};
00119     int32_t d_number_symbols{};
00120 };
00121
00122 /** \} */
00123 /** \} */
00124 #endif // GNSS_SDR_VITERBI_DECODER_H

```


13.522 viterbi_decoder_sbass.h File Reference

Interface of a Viterbi decoder class based on the Iterative Solutions Coded Modulation Library by Matthew C. Valenti.

```
#include <cstdint>
#include <deque>
#include <vector>
```

Classes

- class [Viterbi_Decoder_Sbas](#)

Class that implements a Viterbi decoder.

13.522.1 Detailed Description

Interface of a Viterbi decoder class based on the Iterative Solutions Coded Modulation Library by Matthew C. Valenti.

Author

Daniel Fehr 2013. daniel.co(at)bluewin.ch

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Definition in file [viterbi_decoder_sbass.h](#).

13.523 viterbi_decoder_sbass.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file viterbi_decoder_sbass.h
00003  * \brief Interface of a Viterbi decoder class based on the Iterative Solutions
00004  * Coded Modulation Library by Matthew C. Valenti
00005  * \author Daniel Fehr 2013. daniel.co(at)bluewin.ch
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_VITERBI_DECODER_SBASS_H
00019 #define GNSS_SDR_VITERBI_DECODER_SBASS_H
00020
00021 #include <cstdint> // for size_t
00022 #include <deque>
00023 #include <vector>
00024
00025 /** \addtogroup Telemetry_Decoder
00026  * \{ */
00027 /** \addtogroup Telemetry_Decoder_libs telemetry_decoder_libs
00028  * \{ */
00029
00030
00031 /*!
00032  * \brief Class that implements a Viterbi decoder
00033  */
00034 class Viterbi_Decoder_Sbas
00035 {
00036 public:
00037     Viterbi_Decoder_Sbas(const int g_encoder[], int KK, int nn);
00038
00039     void reset();
00040
00041     /*!
00042     * \brief Uses the Viterbi algorithm to perform hard-decision decoding of a convolutional code.
00043     *
00044     * \param[in] input_c[] The received signal in LLR-form. For BPSK, must be in form r =
00045     * 2*a*y/(sigma^2).
00046     * \param[in] LL The number of data bits to be decoded (does not include the mm
00047     * zero-tail-bits)
```

```

00046      *
00047      * \return output_u_int[] Hard decisions on the data bits (without the mm zero-tail-bits)
00048      */
00049      float decode_block(const double input_c[], int* output_u_int, int LL);
00050
00051      float decode_continuous(const double sym[], int traceback_depth, int bits[],
00052                             int nbits_requested, int& nbits_decoded);
00053
00054      private:
00055      class Prev
00056      {
00057      public:
00058          int num_states;
00059          Prev(int states, int tt);
00060          Prev(const Prev& prev);
00061          Prev& operator=(const Prev& other);
00062          ~Prev();
00063
00064          int get_ancestor_state_of_current_state(int current_state) const;
00065          int get_bit_of_current_state(int current_state) const;
00066          float get_metric_of_current_state(int current_state) const;
00067          int get_t() const;
00068          void set_current_state_as_ancestor_of_next_state(int next_state, int current_state);
00069          void set_decoded_bit_for_next_state(int next_state, int bit);
00070          void set_survivor_branch_metric_of_next_state(int next_state, float metric);
00071
00072      private:
00073          std::vector<float> v_metric;
00074          std::vector<int> state;
00075          std::vector<int> v_bit;
00076          int t;
00077          int refcount;
00078      };
00079
00080      // operations on the trellis (change decoder state)
00081      void init_trellis_state();
00082      int do_acs(const double sym[], int nbits);
00083      int do_traceback(std::size_t traceback_length);
00084      int do_tb_and_decode(int traceback_length, int requested_decoding_length, int state, int
00085                          output_u_int[], float& indicator_metric);
00086
00087      // branch metric function
00088      float gamma(const float rec_array[], int symbol, int nn);
00089
00090      // trellis generation
00091      void nsc_transit(int output_p[], int trans_p[], int input, const int g[], int KK, int nn);
00092      int nsc_enc_bit(int state_out_p[], int input, int state_in, const int g[], int KK, int nn);
00093      int parity_counter(int symbol, int length);
00094
00095      // trellis state
00096      std::deque<Prev> d_trellis_paths;
00097      std::vector<float> d_pm_t;
00098      std::vector<float> d_metric_c; /* Set of all possible branch metrics */
00099      std::vector<float> d_rec_array; /* Received values for one trellis section */
00100
00101      // trellis definition
00102      std::vector<int> d_out0;
00103      std::vector<int> d_state0;
00104      std::vector<int> d_out1;
00105      std::vector<int> d_state1;
00106
00107      // measures
00108      float d_indicator_metric;
00109
00110      // code properties
00111      int d_KK;
00112      int d_nn;
00113
00114      // derived code properties
00115      int d_mm;
00116      int d_states;
00117      int d_number_symbols;
00118      bool d_trellis_state_is_initialised;
00119
00120      };
00121
00122      /** \} */
00123      /** \} */
00124      #endif // GNSS_SDR_VITERBI_DECODER_SBAS_H

```

13.524 base_dll_pll_tracking.h File Reference

Base class providing shared logic for DLL+PLL VEML tracking adapters.

```
#include "dll_pll_conf.h"
#include "dll_pll_veml_tracking.h"
#include "tracking_interface.h"
#include <cstdint>
#include <string>
```

Classes

- class [BaseDllPllTracking](#)

Base class providing shared logic for DLL+PLL tracking loop adapters for GNSS signals.

13.524.1 Detailed Description

Base class providing shared logic for DLL+PLL VEML tracking adapters.

Authors

Carles Fernandez, 2025. carles.fernandez(at)cttc.cat

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 Definition in file [base_dll_pll_tracking.h](#).

13.525 base_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file base_dll_pll_tracking.h
00003  * \brief Base class providing shared logic for DLL+PLL VEML tracking adapters.
00004  * \authors Carles Fernandez, 2025. carles.fernandez(at)cttc.cat
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2025 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_BASE_DLL_PLL_TRACKING_H
00018 #define GNSS_SDR_BASE_DLL_PLL_TRACKING_H
00019
00020 #include "dll_pll_conf.h"
00021 #include "dll_pll_veml_tracking.h"
00022 #include "tracking_interface.h"
00023 #include <cstdint>
00024 #include <string>
00025
00026 /** \addtogroup Tracking
00027  * Classes for GNSS signal tracking.
00028  * \{ */
00029 /** \addtogroup Tracking_adapters tracking_adapters
00030  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00031  * \{ */
00032
00033 class ConfigurationInterface;
00034
00035 /*!
00036  * \brief Base class providing shared logic for DLL+PLL tracking loop adapters
00037  * for GNSS signals.
00038  */
00039 class BaseDllPllTracking : public TrackingInterface
00040 {
00041 public:
00042     /*!
00043      * \brief Base constructor of a Tracking block adapter
00044      */
00045     explicit BaseDllPllTracking(const ConfigurationInterface* configuration,
00046                                 std::string role,
00047                                 unsigned int in_streams,
00048                                 unsigned int out_streams);
```

```

00049
00050     /*!
00051      * \brief Default destructor of the Tracking block adapter
00052      */
00053     ~BaseDllPllTracking() override = default;
00054
00055     /*!
00056      * \brief Get role from the Tracking block adapter
00057      */
00058     inline std::string role() override final { return role_; }
00059
00060     /*!
00061      * \brief Get item_size from the Tracking block adapter
00062      */
00063     inline size_t item_size() override final { return item_size_; }
00064
00065     /*!
00066      * \brief Connect the Tracking block adapter
00067      */
00068     void connect(gr::top_block_sptr top_block) override final;
00069
00070     /*!
00071      * \brief Disconnect the sTracking block adapter
00072      */
00073     void disconnect(gr::top_block_sptr top_block) override final;
00074
00075     /*!
00076      * \brief Get left block from the Tracking block adapter
00077      */
00078     gr::basic_block_sptr get_left_block() override final;
00079
00080     /*!
00081      * \brief Get right block from the Tracking block adapter
00082      */
00083     gr::basic_block_sptr get_right_block() override final;
00084
00085     /*!
00086      * \brief Set tracking channel unique ID
00087      */
00088     void set_channel(unsigned int channel) override final;
00089
00090     /*!
00091      * \brief Set acquisition Gnss_Synchro object pointer
00092      * to exchange synchronization data between acquisition and tracking blocks
00093      */
00094     void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override final;
00095
00096     /*!
00097      * \brief Start the Tracking block
00098      */
00099     void start_tracking() override final;
00100
00101     /*!
00102      * \brief Stop the Tracking block
00103      */
00104     void stop_tracking() override final;
00105
00106 protected:
00107     // Can be used by each derived class
00108     inline Dll_Pll_Conf& config_params() { return trk_params_; }
00109     inline const Dll_Pll_Conf& config_params() const { return trk_params_; }
00110     inline void set_item_size(size_t item_size) { item_size_ = item_size; }
00111
00112     // Must be implemented / filled by each derived class
00113     virtual void configure_tracking_parameters(const ConfigurationInterface* configuration) = 0;
00114     virtual void create_tracking_block() = 0;
00115     dll_pll_veml_tracking_sptr tracking_sptr_;
00116
00117 private:
00118     // Managed by the base class
00119     Dll_Pll_Conf trk_params_;
00120     const std::string role_;
00121     size_t item_size_;
00122 };
00123
00124 /** @} */
00125 /** @} */
00126 #endif // GNSS_SDR_BASE_DLL_PLL_TRACKING_H

```

13.526 base_dll_pll_tracking_fpga.h File Reference

Base class providing shared logic for DLL+PLL VEML tracking adapters for FPGA-based devices.

```
#include "dll_pll_conf_fpga.h"
#include "dll_pll_veml_tracking_fpga.h"
#include "tracking_interface.h"
#include <cstddef>
#include <stdint>
#include <map>
#include <mutex>
#include <string>
```

Classes

- class [BaseDllPllTrackingFpga](#)

13.526.1 Detailed Description

Base class providing shared logic for DLL+PLL VEML tracking adapters for FPGA-based devices.

Authors

Carles Fernandez, 2025. carles.fernandez(at)cttc.cat

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 Definition in file [base_dll_pll_tracking_fpga.h](#).

13.527 base_dll_pll_tracking_fpga.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file base_dll_pll_tracking_fpga.h
00003  * \brief Base class providing shared logic for DLL+PLL VEML tracking adapters
00004  * for FPGA-based devices
00005  * \authors Carles Fernandez, 2025. carles.fernandez(at)cttc.cat
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2025 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_BASE_DLL_PLL_TRACKING_FPGA_H
00019 #define GNSS_SDR_BASE_DLL_PLL_TRACKING_FPGA_H
00020
00021 #include "dll_pll_conf_fpga.h"
00022 #include "dll_pll_veml_tracking_fpga.h"
00023 #include "tracking_interface.h"
00024 #include <cstddef>
00025 #include <stdint>
00026 #include <map>
00027 #include <mutex>
00028 #include <string>
00029
00030 // /** \addtogroup Tracking
00031 //  * \{ */
00032 // /** \addtogroup Tracking_adapters
00033 //  * \{ */
00034
00035 class ConfigurationInterface;
00036
00037 class BaseDllPllTrackingFpga : public TrackingInterface
00038 {
00039 public:
00040     /*!
00041     * \brief Base constructor of FPGA-based Tracking block adapters
00042     */
00043     BaseDllPllTrackingFpga(const ConfigurationInterface* configuration,
00044         const std::string& role,
00045         unsigned int in_streams,
```

```

00046         unsigned int out_streams);
00047     /*!
00048      * \brief Base destructor of FPGA-based Tracking block adapters
00049      */
00050     virtual ~BaseDllPllTrackingFpga() = default;
00051
00052     // Common TrackingInterface overrides
00053
00054     /*!
00055      * \brief Get role from the Tracking block adapter
00056      */
00057     std::string role() override { return role_; }
00058
00059     /*!
00060      * \brief Get item_size from the Tracking block adapter
00061      */
00062     size_t item_size() override { return sizeof(int16_t); }
00063
00064     /*!
00065      * \brief Connect the Tracking block adapter
00066      */
00067     void connect(gr::top_block_sptr top_block) override;
00068
00069     /*!
00070      * \brief Disconnect the Tracking block adapter
00071      */
00072     void disconnect(gr::top_block_sptr top_block) override;
00073
00074     /*!
00075      * \brief Get left block from the Tracking block adapter
00076      */
00077     gr::basic_block_sptr get_left_block() override;
00078
00079     /*!
00080      * \brief Get right block from the Tracking block adapter
00081      */
00082     gr::basic_block_sptr get_right_block() override;
00083
00084     /*!
00085      * \brief Start the tracking process in the FPGA
00086      */
00087     void start_tracking() override;
00088
00089     /*!
00090      * \brief Stop the tracking process in the FPGA
00091      */
00092     void stop_tracking() override;
00093
00094     /*!
00095      * \brief configure FPGA tracking channel mapping
00096      */
00097     void configure_fpga_tracking_channel_mapping(std::string signal);
00098
00099     /*!
00100      * \brief Set tracking channel unique ID
00101      */
00102     void set_channel(unsigned int channel) override;
00103
00104     /*!
00105      * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00106      * to efficiently exchange synchronization data between acquisition and tracking blocks
00107      */
00108     void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override;
00109
00110 protected:
00111     // Can be used by each derived class
00112     static const int32_t LOCAL_CODE_FPGA_ENABLE_WRITE_MEMORY = 0x0C000000; // flag that enables
00113     WE (Write Enable) of the local code FPGA
00114     static const int32_t LOCAL_CODE_FPGA_CORRELATOR_SELECT_COUNT = 0x20000000; // flag that selects
00115     the writing of the pilot code in the FPGA (as opposed to the data code)
00116
00117     inline Dll_Pll_Conf_Fpga& config_params_fpga() { return trk_params_; }
00118     inline const Dll_Pll_Conf_Fpga& config_params_fpga() const { return trk_params_; }
00119
00120     // Must be set by each derived class
00121     dll_pll_veml_tracking_fpga_sptr tracking_fpga_sc_sptr;
00122 private:
00123     // Mapping of GNSS signals to FPGA hardware multicorrelator names
00124     inline static const std::map<std::string, std::string> signal_to_device_ = {
00125         {"1C", "multicorrelator_resampler_S00_AXI"},
00126         {"2S", "multicorrelator_resampler_S00_AXI"},
00127         {"L5", "multicorrelator_resampler_3_1_AXI"},
00128         {"1B", "multicorrelator_resampler_5_1_AXI"},
00129         {"5X", "multicorrelator_resampler_3_1_AXI"},
00130     };
00131     // Mapping of GNSS signals to alternative FPGA multicorrelator tracking names

```

```

00131     inline static const std::map<std::string, std::string> signal_to_alternative_device_ = {
00132         {"1C", "multicorrelator_resampler_5_1_AXI"}};
00133
00134     // Number of channels per signal supported by the FPGA
00135     inline static std::map<std::string, int> channel_counts_;
00136
00137     void set_signal_channel_base_index_locked(); // Compute the base channel index for
    signal_ based on the channel initialization order in the receiver and the number of channels assigned
    to each signal. Requires: channel_counts_mtx_ is held by the caller.
00138     uint32_t get_num_alternative_devices_locked() const; // Return the number of FPGA tracking
    multicorrelator devices mapped to signal_ that are also assigned as alternative for other signals.
    Requires: channel_counts_mtx_ is held by the caller.
00139
00140     Dll_Pll_Conf_Fpga trk_params_;
00141     const std::string role_;
00142     std::string signal_; // GNSS signal type (1C, 2S, L5, 1B, 5X ...)
00143     std::string device_name_; // FPGA multicorrelator name
00144
00145     inline static std::mutex channel_counts_mtx_; // Protects access to channel_counts_
00146
00147     uint32_t channel_;
00148     uint32_t signal_base_channel_index_; // Channel index within the signal type (GPS L1 C/A, GPS L2,
    GPS L5, Galileo E1, Galileo E5a ...)
00149 };
00150
00151 /** @} */
00152 /** @} */
00153 #endif // GNSS_SDR_BASE_DLL_PLL_TRACKING_FPGA_H

```

13.528 beidou_b1i_dll_pll_tracking.h File Reference

Interface of an adapter of a DLL+PLL tracking loop block for Beidou B1I to a [TrackingInterface](#).

```
#include "base_dll_pll_tracking.h"
```

Classes

- class [BeidouB1IDllPllTracking](#)

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for BeiDou B1I signals.

13.528.1 Detailed Description

Interface of an adapter of a DLL+PLL tracking loop block for Beidou B1I to a [TrackingInterface](#).

Author

Sergi Segura, 2018. [sergi.segura.munoz\(at\)gmail.com](mailto:sergi.segura.munoz(at)gmail.com)

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [beidou_b1i_dll_pll_tracking.h](#).

13.529 beidou_b1i_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file beidou_b1i_dll_pll_tracking.h
00003  * \brief Interface of an adapter of a DLL+PLL tracking loop block
00004  * for Beidou B1I to a TrackingInterface
00005  * \author Sergi Segura, 2018. sergi.segura.munoz\(at\)gmail.com
00006  *
00007  * Code DLL + carrier PLL according to the algorithms described in:
00008  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00009  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00010  * Approach, Birkhauser, 2007
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.

```

```

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00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_BEIDOU_B1I_DLL_PLL_TRACKING_H
00024 #define GNSS_SDR_BEIDOU_B1I_DLL_PLL_TRACKING_H
00025
00026 #include "base_dll_pll_tracking.h"
00027
00028 /** \addtogroup Tracking
00029  * Classes for GNSS signal tracking.
00030  * \{ */
00031 /** \addtogroup Tracking_adapters tracking_adapters
00032  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00033  * \{ */
00034
00035 class ConfigurationInterface;
00036
00037 /*!
00038  * \brief This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking
00039  * loop block to a TrackingInterface for BeiDou B1I signals
00040  */
00041 class BeidouB1iDllPllTracking : public BaseDllPllTracking
00042 {
00043 public:
00044     /** Constructor
00045      * BeidouB1iDllPllTracking(const ConfigurationInterface* configuration,
00046      * const std::string& role,
00047      * unsigned int in_streams,
00048      * unsigned int out_streams);
00049
00050      * \returns "BEIDOU_B1I_DLL_PLL_Tracking"
00051      * inline std::string implementation() override
00052      * {
00053      *     return "BEIDOU_B1I_DLL_PLL_Tracking";
00054      * }
00055
00056 private:
00057     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00058     void create_tracking_block() override;
00059 };
00060
00061
00062 /** \} */
00063 /** \} */
00064 #endif // GNSS_SDR_BEIDOU_B1I_DLL_PLL_TRACKING_H

```

13.530 beidou_b3i_dll_pll_tracking.h File Reference

Interface of an adapter of a DLL+PLL tracking loop block for BeiDou B3I to a [TrackingInterface](#).

```
#include "base_dll_pll_tracking.h"
```

Classes

- class [BeidouB3iDllPllTracking](#)

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for BeiDou B3I signals.

13.530.1 Detailed Description

Interface of an adapter of a DLL+PLL tracking loop block for BeiDou B3I to a [TrackingInterface](#).

Author

Damian Miralles, 2019. dmiralles2009(at)gmail.com

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [beidou_b3i_dll_pll_tracking.h](#).

13.531 beidou_b3i_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file beidou_b3i_dll_pll_tracking.h
00003  * \brief Interface of an adapter of a DLL+PLL tracking loop block
00004  * for Beidou B3I to a TrackingInterface
00005  * \author Damian Miralles, 2019. dmiralles2009(at)gmail.com
00006  *
00007  * Code DLL + carrier PLL according to the algorithms described in:
00008  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00009  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00010  * Approach, Birkhauser, 2007
00011  *
00012  * -----
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00016  *
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00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_BEIDOU_B3I_DLL_PLL_TRACKING_H
00024 #define GNSS_SDR_BEIDOU_B3I_DLL_PLL_TRACKING_H
00025
00026 #include "base_dll_pll_tracking.h"
00027
00028 /** \addtogroup Tracking
00029  * Classes for GNSS signal tracking.
00030  * \{ */
00031 /** \addtogroup Tracking_adapters tracking_adapters
00032  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00033  * \{ */
00034
00035 class ConfigurationInterface;
00036
00037 /*!
00038 * \brief This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking
00039 * loop block to a TrackingInterface for Beidou B3I signals
00040 */
00041 class BeidouB3iDllPllTracking : public BaseDllPllTracking
00042 {
00043 public:
00044     /** Constructor
00045     BeidouB3iDllPllTracking(const ConfigurationInterface* configuration,
00046         const std::string& role,
00047         unsigned int in_streams,
00048         unsigned int out_streams);
00049
00050     /** Returns "BEIDOU_B3I_DLL_PLL_Tracking"
00051     inline std::string implementation() override
00052     {
00053         return "BEIDOU_B3I_DLL_PLL_Tracking";
00054     }
00055
00056 private:
00057     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00058     void create_tracking_block() override;
00059 };
00060
00061
00062 /** \} */
00063 /** \} */
00064 #endif // GNSS_SDR_BEIDOU_B3I_DLL_PLL_TRACKING_H

```

13.532 galileo_e1_dll_pll_veml_tracking.h File Reference

Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E1 signals.
#include "base_dll_pll_tracking.h"

Classes

- class [GalileoE1DllPllVemlTracking](#)

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E1 signals.

13.532.1 Detailed Description

Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E1 signals.

Author

Luis Esteve, 2012. luis(at)epsilon-formacion.com

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [galileo_e1_dll_pll_veml_tracking.h](#).

13.533 galileo_e1_dll_pll_veml_tracking.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file galileo_e1_dll_pll_veml_tracking.h
00003  * \brief Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block
00004  *        to a TrackingInterface for Galileo E1 signals
00005  * \author Luis Esteve, 2012. luis(at)epsilon-formacion.com
00006  *
00007  * Code DLL + carrier PLL according to the algorithms described in:
00008  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00009  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00010  * Approach, Birkhauser, 2007
00011  *
00012  * -----
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00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_GALILEO_E1_DLL_PLL_VEML_TRACKING_H
00024 #define GNSS_SDR_GALILEO_E1_DLL_PLL_VEML_TRACKING_H
00025
00026 #include "base_dll_pll_tracking.h"
00027
00028 /** \addtogroup Tracking
00029  * Classes for GNSS signal tracking.
00030  * \{ */
00031 /** \addtogroup Tracking_adapters tracking_adapters
00032  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00033  * \{ */
00034
00035 class ConfigurationInterface;
00036
00037 /*!
00038  * \brief This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking
00039  *        loop block to a TrackingInterface for Galileo E1 signals
00040  */
00041 class GalileoE1DllPllVemlTracking : public BaseDllPllTracking
00042 {
00043 public:
00044     /** Constructor
00045      * GalileoE1DllPllVemlTracking(const ConfigurationInterface* configuration,
00046      * const std::string& role,
00047      * unsigned int in_streams,
00048      * unsigned int out_streams);
00049
00050      * Returns "Galileo_E1_DLL_PLL_VEML_Tracking"
00051      * inline std::string implementation() override
00052      {
00053          return "Galileo_E1_DLL_PLL_VEML_Tracking";
00054      }
00055
00056 private:
00057     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00058     void create_tracking_block() override;
00059 };
00060
00061
00062 /** \} */
00063 /** \} */
00064 #endif // GNSS_SDR_GALILEO_E1_DLL_PLL_VEML_TRACKING_H
```

13.534 galileo_e1_dll_pll_veml_tracking_fpga.h File Reference

Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E1 signals for the FPGA.

```
#include "base_dll_pll_tracking_fpga.h"
```

Classes

- class [GalileoE1DllPllVemlTrackingFpga](#)

Adapter for a Galileo E1 DLL+PLL VEML tracking loop block in FPGA.

13.534.1 Detailed Description

Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E1 signals for the FPGA.

Author

Marc Majoral, 2019. mmajoral(at)cttc.cat

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [galileo_e1_dll_pll_veml_tracking_fpga.h](#).

13.535 galileo_e1_dll_pll_veml_tracking_fpga.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file galileo_e1_dll_pll_veml_tracking_fpga.h
00003  * \brief Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block
00004  * to a TrackingInterface for Galileo E1 signals for the FPGA
00005  * \author Marc Majoral, 2019. mmajoral(at)cttc.cat
00006  *
00007  * Code DLL + carrier PLL according to the algorithms described in:
00008  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00009  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00010  * Approach, Birkhauser, 2007
00011  *
00012  * -----
00013  *
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00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_GALILEO_E1_DLL_PLL_VEML_TRACKING_FPGA_H
00024 #define GNSS_SDR_GALILEO_E1_DLL_PLL_VEML_TRACKING_FPGA_H
00025
00026 #include "base_dll_pll_tracking_fpga.h"
00027
00028 /** \addtogroup Tracking
00029  * \{ */
00030 /** \addtogroup Tracking_adapters
00031  * \{ */
00032
00033 /*!
00034  * \brief Adapter for a Galileo E1 DLL+PLL VEML tracking loop block in FPGA
00035  */
00036 class GalileoE1DllPllVemlTrackingFpga : public BaseDllPllTrackingFpga
00037 {
00038 public:
00039     GalileoE1DllPllVemlTrackingFpga(const ConfigurationInterface* configuration,
00040         const std::string& role,
00041         unsigned int in_streams,
00042         unsigned int out_streams);
00043
00044     ~GalileoE1DllPllVemlTrackingFpga() override;
```

```

00045
00046     std::string implementation() override
00047     {
00048         return "Galileo_E1_DLL_PLL_VEML_Tracking_FPGA";
00049     }
00050
00051 private:
00052     int32_t* prn_codes_ptr_;
00053     int32_t* data_codes_ptr_;
00054     bool track_pilot_;
00055 };
00056
00057 // /** \} */
00058 // /** \} */
00059 #endif // GNSS_SDR_GALILEO_E1_DLL_PLL_VEML_TRACKING_FPGA_H

```

13.536 galileo_e1_tcp_connector_tracking.h File Reference

Interface of an adapter of a TCP connector block based on code DLL + carrier PLL for Galileo E1 to a [TrackingInterface](#).

```

#include "galileo_e1_tcp_connector_tracking_cc.h"
#include "tracking_interface.h"
#include <string>

```

Classes

- class [GalileoE1TcpConnectorTracking](#)

This class implements a code DLL + carrier PLL tracking loop.

13.536.1 Detailed Description

Interface of an adapter of a TCP connector block based on code DLL + carrier PLL for Galileo E1 to a [TrackingInterface](#).

Author

David Pubill, 2012. [dpubill\(at\)cttc.es](mailto:dpubill(at)cttc.es) Luis Esteve, 2012. [luis\(at\)epsilon-formacion.com](mailto:luis(at)epsilon-formacion.com) Javier Arribas, 2011. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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 Definition in file [galileo_e1_tcp_connector_tracking.h](#).

13.537 galileo_e1_tcp_connector_tracking.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_e1_tcp_connector_tracking.h
00003  * \brief Interface of an adapter of a TCP connector block based on code DLL + carrier PLL
00004  * for Galileo E1 to a TrackingInterface
00005  * \author David Pubill, 2012. dpubill\(at\)cttc.es
00006  * Luis Esteve, 2012. luis\(at\)epsilon-formacion.com
00007  * Javier Arribas, 2011. jarribas\(at\)cttc.es
00008  *
00009  * Code DLL + carrier PLL according to the algorithms described in:
00010  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00011  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00012  * Approach, Birkhauser, 2007
00013  *
00014  * -----
00015  *
00016  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00018  *
00019  * Copyright (C) 2012-2020 (see AUTHORS file for a list of contributors)
00020  * SPDX-License-Identifier: GPL-3.0-or-later
00021  *

```

```

00022  * -----
00023  */
00024
00025 #ifndef GNSS_SDR_GALILEO_E1_TCP_CONNECTOR_TRACKING_H
00026 #define GNSS_SDR_GALILEO_E1_TCP_CONNECTOR_TRACKING_H
00027
00028 #include "galileo_e1_tcp_connector_tracking_cc.h"
00029 #include "tracking_interface.h"
00030 #include <string>
00031
00032 /** \addtogroup Tracking
00033  * \{ */
00034 /** \addtogroup Tracking_adapters
00035  * \{ */
00036
00037
00038 class ConfigurationInterface;
00039
00040 /*!
00041  * \brief This class implements a code DLL + carrier PLL tracking loop
00042  */
00043 class GalileoE1TcpConnectorTracking : public TrackingInterface
00044 {
00045 public:
00046     GalileoE1TcpConnectorTracking(
00047         const ConfigurationInterface* configuration,
00048         const std::string& role,
00049         unsigned int in_streams,
00050         unsigned int out_streams);
00051
00052     ~GalileoE1TcpConnectorTracking() = default;
00053
00054     inline std::string role() override
00055     {
00056         return role_;
00057     }
00058
00059     /*! Returns "Galileo_E1_TCP_CONNECTOR_Tracking"
00060     inline std::string implementation() override
00061     {
00062         return "Galileo_E1_TCP_CONNECTOR_Tracking";
00063     }
00064
00065     inline size_t item_size() override
00066     {
00067         return item_size_;
00068     }
00069
00070     void connect(gr::top_block_sptr top_block) override;
00071     void disconnect(gr::top_block_sptr top_block) override;
00072     gr::basic_block_sptr get_left_block() override;
00073     gr::basic_block_sptr get_right_block() override;
00074
00075     /*!
00076     * \brief Set tracking channel unique ID
00077     */
00078     void set_channel(unsigned int channel) override;
00079
00080     /*!
00081     * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00082     * to efficiently exchange synchronization data between acquisition and
00083     * tracking blocks
00084     */
00085     void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override;
00086
00087     void start_tracking() override;
00088     /*!
00089     * \brief Stop running tracking
00090     */
00091     void stop_tracking() override;
00092
00093 private:
00094     galileo_e1_tcp_connector_tracking_cc_sptr tracking_sptr_;
00095     std::string role_;
00096     size_t item_size_;
00097     unsigned int channel_;
00098     unsigned int in_streams_;
00099     unsigned int out_streams_;
00100 };
00101
00102
00103 /** \} */
00104 /** \} */
00105 #endif // GNSS_SDR_GALILEO_E1_TCP_CONNECTOR_TRACKING_H

```

13.538 galileo_e5a_dll_pll_tracking.h File Reference

Adapts a code DLL + carrier PLL tracking block to a [TrackingInterface](#) for Galileo E5a signals.

```
#include "base_dll_pll_tracking.h"
```

Classes

- class [GalileoE5aDllPllTracking](#)

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E5a signals.

13.538.1 Detailed Description

Adapts a code DLL + carrier PLL tracking block to a [TrackingInterface](#) for Galileo E5a signals.

Author

Marc Sales, 2014. marcsales92(at)gmail.com \based on work from:

- Javier Arribas, 2011. jarribas(at)cttc.es
- Luis Esteve, 2012. luis(at)epsilon-formacion.com

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Definition in file [galileo_e5a_dll_pll_tracking.h](#).

13.539 galileo_e5a_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file galileo_e5a_dll_pll_tracking.h
00003  * \brief Adapts a code DLL + carrier PLL
00004  * tracking block to a TrackingInterface for Galileo E5a signals
00005  * \author Marc Sales, 2014. marcsales92(at)gmail.com
00006  * \based on work from:
00007  *      <ul>
00008  *          <li> Javier Arribas, 2011. jarribas(at)cttc.es
00009  *          <li> Luis Esteve, 2012. luis(at)epsilon-formacion.com
00010  *      </ul>
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.
00016  *
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00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_GALILEO_E5A_DLL_PLL_TRACKING_H
00024 #define GNSS_SDR_GALILEO_E5A_DLL_PLL_TRACKING_H
00025
00026 #include "base_dll_pll_tracking.h"
00027
00028 /** \addtogroup Tracking
00029  * Classes for GNSS signal tracking.
00030  * \{ */
00031 /** \addtogroup Tracking_adapters tracking_adapters
00032  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00033  * \{ */
00034
00035 class ConfigurationInterface;
00036
00037 /*!
00038  * \brief This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking
00039  * loop block to a TrackingInterface for Galileo E5a signals
00040  */
00041 class GalileoE5aDllPllTracking : public BaseDllPllTracking
00042 {
00043 public:
00044     /*! Constructor
```

```

00045     GalileoE5aDllPllTracking(const ConfigurationInterface* configuration,
00046         const std::string& role,
00047         unsigned int in_streams,
00048         unsigned int out_streams);
00049
00050     //!< Returns "Galileo_E5a_DLL_PLL_Tracking"
00051     inline std::string implementation() override
00052     {
00053         return "Galileo_E5a_DLL_PLL_Tracking";
00054     }
00055
00056 private:
00057     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00058     void create_tracking_block() override;
00059 };
00060
00061
00062 /** @} */
00063 /** @} */
00064 #endif // GNSS_SDR_GALILEO_E5A_DLL_PLL_TRACKING_H

```

13.540 galileo_e5a_dll_pll_tracking_fpga.h File Reference

Adapts a code DLL + carrier PLL tracking block to a [TrackingInterface](#) for Galileo E5a signals for the FPGA.

```
#include "base_dll_pll_tracking_fpga.h"
```

Classes

- class [GalileoE5aDllPllTrackingFpga](#)
Adapter for a Galileo E5a DLL+PLL tracking loop implemented in FPGA.

13.540.1 Detailed Description

Adapts a code DLL + carrier PLL tracking block to a [TrackingInterface](#) for Galileo E5a signals for the FPGA.

Author

Marc Majoral, 2019. mmajoral(at)cttc.cat

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 Definition in file [galileo_e5a_dll_pll_tracking_fpga.h](#).

13.541 galileo_e5a_dll_pll_tracking_fpga.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_e5a_dll_pll_tracking_fpga.h
00003  * \brief Adapts a code DLL + carrier PLL
00004  * \brief tracking block to a TrackingInterface for Galileo E5a signals for the FPGA
00005  * \author Marc Majoral, 2019. mmajoral(at)cttc.cat
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GALILEO_E5A_DLL_PLL_TRACKING_FPGA_H
00019 #define GNSS_SDR_GALILEO_E5A_DLL_PLL_TRACKING_FPGA_H
00020
00021 #include "base_dll_pll_tracking_fpga.h"
00022
00023 /** \addtogroup Tracking
00024  * \{ */
00025 /** \addtogroup Tracking_adapters
00026  * \{ */

```

```

00027
00028 /*!
00029  * \brief Adapter for a Galileo E5a DLL+PLL tracking loop implemented in FPGA
00030  */
00031 class GalileoE5aDllPllTrackingFpga : public BaseDllPllTrackingFpga
00032 {
00033 public:
00034 /*!
00035  * \brief Constructor
00036  */
00037 GalileoE5aDllPllTrackingFpga(const ConfigurationInterface* configuration,
00038                               const std::string& role,
00039                               unsigned int in_streams,
00040                               unsigned int out_streams);
00041
00042 /*!
00043  * \brief Destructor
00044  */
00045 ~GalileoE5aDllPllTrackingFpga() override;
00046
00047 /*!
00048  * \brief Returns "Galileo_E5a_DLL_PLL_Tracking_FPGA"
00049  */
00050 std::string implementation() override
00051 {
00052     return "Galileo_E5a_DLL_PLL_Tracking_FPGA";
00053 }
00054
00055 private:
00056  // Pointer to local PRN codes (pilot/data)
00057  int32_t* prn_codes_ptr_;
00058  int32_t* data_codes_ptr_;
00059
00060  // Pilot tracking flag
00061  bool track_pilot_;
00062 };
00063
00064
00065  // /** \} */
00066  // /** \} */
00067 #endif  // GNSS_SDR_GALILEO_E5a_DLL_PLL_TRACKING_FPGA_H

```

13.542 galileo_e5b_dll_pll_tracking.h File Reference

Adapts a code DLL + carrier PLL tracking block to a [TrackingInterface](#) for Galileo E5b signals.

```
#include "base_dll_pll_tracking.h"
```

Classes

- class [GalileoE5bDllPllTracking](#)

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E5b signals.

13.542.1 Detailed Description

Adapts a code DLL + carrier PLL tracking block to a [TrackingInterface](#) for Galileo E5b signals.

Author

Piyush Gupta, 2020. piyush04111999@gmail.com \based on work from:

- Javier Arribas, 2011. jarribas@cttc.es
- Luis Esteve, 2012. luis@epsilon-formacion.com
- Marc Sales, 2014. marcsales92@gmail.com

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Definition in file [galileo_e5b_dll_pll_tracking.h](#).

13.543 galileo_e5b_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_e5b_dll_pll_tracking.h
00003  * \brief Adapts a code DLL + carrier PLL
00004  * tracking block to a TrackingInterface for Galileo E5b signals
00005  * \author Piyush Gupta, 2020. piyush04111999@gmail.com
00006  * \based on work from:
00007  *      <ul>
00008  *          <li> Javier Arribas, 2011. jarribas@cttc.es
00009  *          <li> Luis Esteve, 2012. luis@epsilon-formacion.com
00010  *          <li> Marc Sales, 2014. marcsales92@gmail.com
00011  *      </ul>
00012  *
00013  * -----
00014  *
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00019  * SPDX-License-Identifier: GPL-3.0-or-later
00020  *
00021  * -----
00022  */
00023
00024 #ifndef GNSS_SDR_GALILEO_E5B_DLL_PLL_TRACKING_H
00025 #define GNSS_SDR_GALILEO_E5B_DLL_PLL_TRACKING_H
00026
00027 #include "base_dll_pll_tracking.h"
00028
00029 /** \addtogroup Tracking
00030  * Classes for GNSS signal tracking.
00031  * \{ */
00032 /** \addtogroup Tracking_adapters tracking_adapters
00033  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00034  * \{ */
00035
00036 class ConfigurationInterface;
00037
00038 /*!
00039 * \brief This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking
00040 * loop block to a TrackingInterface for Galileo E5b signals
00041 */
00042 class GalileoE5bDllPllTracking : public BaseDllPllTracking
00043 {
00044 public:
00045     /** Constructor
00046     GalileoE5bDllPllTracking(const ConfigurationInterface* configuration,
00047         const std::string& role,
00048         unsigned int in_streams,
00049         unsigned int out_streams);
00050
00051     /** Returns "Galileo_E5b_DLL_PLL_Tracking"
00052     inline std::string implementation() override
00053     {
00054         return "Galileo_E5b_DLL_PLL_Tracking";
00055     }
00056
00057 private:
00058     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00059     void create_tracking_block() override;
00060 };
00061
00062
00063 /** \} */
00064 /** \} */
00065 #endif // GNSS_SDR_GALILEO_E5B_DLL_PLL_TRACKING_H

```

13.544 galileo_e6_dll_pll_tracking.h File Reference

Adapts a code DLL + carrier PLL tracking block to a [TrackingInterface](#) for Galileo E6 signals.

```
#include "base_dll_pll_tracking.h"
```

Classes

- class [GalileoE6DllPllTracking](#)

This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking loop block to a [TrackingInterface](#) for Galileo E5a signals.

13.544.1 Detailed Description

Adapts a code DLL + carrier PLL tracking block to a [TrackingInterface](#) for Galileo E6 signals.

Author

Carles Fernandez-Prades, 2020. cfernandez(at)cttc.es

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Definition in file [galileo_e6_dll_pll_tracking.h](#).

13.545 galileo_e6_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_e6_dll_pll_tracking.h
00003  * \brief Adapts a code DLL + carrier PLL
00004  * tracking block to a TrackingInterface for Galileo E6 signals
00005  * \author Carles Fernandez-Prades, 2020. cfernandez(at)cttc.es
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
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00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GALILEO_E6_DLL_PLL_TRACKING_H
00020 #define GNSS_SDR_GALILEO_E6_DLL_PLL_TRACKING_H
00021
00022 #include "base_dll_pll_tracking.h"
00023
00024 /** \addtogroup Tracking
00025  * Classes for GNSS signal tracking.
00026  * \{ */
00027 /** \addtogroup Tracking_adapters tracking_adapters
00028  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00029  * \{ */
00030
00031 class ConfigurationInterface;
00032
00033 /*!
00034 * \brief This class Adapts a DLL+PLL VEML (Very Early Minus Late) tracking
00035 * loop block to a TrackingInterface for Galileo E5a signals
00036 */
00037 class GalileoE6DllPllTracking : public BaseDllPllTracking
00038 {
00039 public:
00040     /** Constructor
00041      * GalileoE6DllPllTracking(const ConfigurationInterface* configuration,
00042      * const std::string& role,
00043      * unsigned int in_streams,
00044      * unsigned int out_streams);
00045
00046      * Returns "Galileo_E6_DLL_PLL_Tracking"
00047      * inline std::string implementation() override
00048      {
00049          return "Galileo_E6_DLL_PLL_Tracking";
00050      }
00051
00052 private:
00053     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00054     void create_tracking_block() override;
00055 };
00056
00057
00058 /** \} */
00059 /** \} */
00060 #endif // GNSS_SDR_GALILEO_E6_DLL_PLL_TRACKING_H
00061
00062 // //

```

```
00063 // src/algorithms/tracking/adapters/galileo_e5a_dll_pll_tracking.h
00064
00065 // src/algorithms/tracking/adapters/galileo_e5a_dll_pll_tracking.h
00066 // #include "dll_pll_veml_tracking.h"
00067 // #include "tracking_interface.h"
00068 // #include <string>
00069
00070 // /** \addtogroup Tracking
00071 // * \{ */
00072 // /** \addtogroup Tracking_adapters
00073 // * \{ */
00074
00075
00076 // class ConfigurationInterface;
00077
00078 // /*!
00079 // * \brief This class implements a code DLL + carrier PLL tracking loop
00080 // */
00081 // class GalileoE6DllPllTracking : public TrackingInterface
00082 // {
00083 // public:
00084 //     GalileoE6DllPllTracking(
00085 //         const ConfigurationInterface* configuration,
00086 //         const std::string& role,
00087 //         unsigned int in_streams,
00088 //         unsigned int out_streams);
00089
00090 //     ~GalileoE6DllPllTracking() = default;
00091
00092 //     inline std::string role() override
00093 //     {
00094 //         return role_;
00095 //     }
00096
00097 //     //! Returns "Galileo_E6_DLL_PLL_Tracking"
00098 //     inline std::string implementation() override
00099 //     {
00100 //         return "Galileo_E6_DLL_PLL_Tracking";
00101 //     }
00102
00103 //     inline size_t item_size() override
00104 //     {
00105 //         return item_size_;
00106 //     }
00107
00108 //     /*!
00109 //     * \brief Connect
00110 //     */
00111 //     void connect(gr::top_block_sptr top_block) override;
00112
00113 //     /*!
00114 //     * \brief Disconnect
00115 //     */
00116 //     void disconnect(gr::top_block_sptr top_block) override;
00117
00118 //     /*!
00119 //     * \brief Get left block
00120 //     */
00121 //     gr::basic_block_sptr get_left_block() override;
00122
00123 //     /*!
00124 //     * \brief Get right block
00125 //     */
00126 //     gr::basic_block_sptr get_right_block() override;
00127
00128 //     /*!
00129 //     * \brief Set tracking channel unique ID
00130 //     */
00131 //     void set_channel(unsigned int channel) override;
00132
00133 //     /*!
00134 //     * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00135 //     * to efficiently exchange synchronization data between acquisition and tracking blocks
00136 //     */
00137 //     void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override;
00138
00139 //     void start_tracking() override;
00140
00141 //     /*!
00142 //     * \brief Stop running tracking
00143 //     */
00144 //     void stop_tracking() override;
00145
00146 // private:
00147 //     dll_pll_veml_tracking_sptr tracking_sptr_;
00148 //     std::string role_;
00149 //     size_t item_size_;
```

```

00150 //      unsigned int channel_;
00151 //      unsigned int in_streams_;
00152 //      unsigned int out_streams_;
00153 // };
00154
00155
00156 // /** \} */
00157 // /** \} */
00158 // #endif // GNSS_SDR_GALILEO_E6_DLL_PLL_TRACKING_H

```

13.546 glonass_l1_ca_dll_pll_tracking.h File Reference

Interface of an adapter of a DLL+PLL tracking loop block for Glonass L1 C/A to a [TrackingInterface](#).

```
#include "base_dll_pll_tracking.h"
```

Classes

- class [GlonassL1CaDllPlTracking](#)

This class implements a code DLL + carrier PLL tracking loop block adapter for GLONASS L1 signals.

13.546.1 Detailed Description

Interface of an adapter of a DLL+PLL tracking loop block for Glonass L1 C/A to a [TrackingInterface](#).

Author

Gabriel Araujo, 2017. gabriel.araujo.5000(at)gmail.com

Luis Esteve, 2017. luis(at)epsilon-formacion.com

Javier Arribas, 2025 javier.arribas(at)cttc.es

Carles Fernandez-Prades, 2025 carles.fernandez(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [glonass_l1_ca_dll_pll_tracking.h](#).

13.547 glonass_l1_ca_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file glonass_l1_ca_dll_pll_tracking.h
00003  * \brief Interface of an adapter of a DLL+PLL tracking loop block
00004  * for Glonass L1 C/A to a TrackingInterface
00005  * \author Gabriel Araujo, 2017. gabriel.araujo.5000(at)gmail.com
00006  * \author Luis Esteve, 2017. luis(at)epsilon-formacion.com
00007  * \author Javier Arribas, 2025 javier.arribas(at)cttc.es
00008  * \author Carles Fernandez-Prades, 2025 carles.fernandez(at)cttc.es
00009  *
00010  *
00011  * Code DLL + carrier PLL according to the algorithms described in:
00012  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00013  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00014  * Approach, Birkhauser, 2007
00015  *
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00022  * SPDX-License-Identifier: GPL-3.0-or-later
00023  *
00024  * -----
00025  */
00026
00027 #ifndef GNSS_SDR_GLOPASS_L1_CA_DLL_PLL_TRACKING_H
00028 #define GNSS_SDR_GLOPASS_L1_CA_DLL_PLL_TRACKING_H

```

```

00029
00030 #include "base_dll_pll_tracking.h"
00031
00032 /** \addtogroup Tracking
00033  * Classes for GNSS signal tracking.
00034  * \{ */
00035 /** \addtogroup Tracking_adapters tracking_adapters
00036  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00037  * \{ */
00038
00039
00040 /*!
00041  * \brief This class implements a code DLL + carrier PLL tracking loop
00042  * block adapter for GLONASS L1 signals
00043  */
00044 class GlonassL1CaDllPllTracking : public BaseDllPllTracking
00045 {
00046 public:
00047     ///! Constructor
00048     GlonassL1CaDllPllTracking(const ConfigurationInterface* configuration,
00049                             const std::string& role,
00050                             unsigned int in_streams,
00051                             unsigned int out_streams);
00052
00053     ///! Returns "GLONASS_L1_CA_DLL_PLL_Tracking"
00054     inline std::string implementation() override
00055     {
00056         return "GLONASS_L1_CA_DLL_PLL_Tracking";
00057     }
00058
00059 private:
00060     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00061     void create_tracking_block() override;
00062 };
00063
00064 /** \} */
00065 /** \} */
00066 #endif // GNSS_SDR_GLO_NASS_L1_DLL_PLL_TRACKING_H

```

13.548 glonass_l2_ca_dll_pll_tracking.h File Reference

Interface of an adapter of a DLL+PLL tracking loop block for Glonass L2 C/A to a [TrackingInterface](#).

```
#include "base_dll_pll_tracking.h"
```

Classes

- class [GlonassL2CaDllPllTracking](#)

This class implements a code DLL + carrier PLL tracking loop block adapter for GLONASS L2 signals.

13.548.1 Detailed Description

Interface of an adapter of a DLL+PLL tracking loop block for Glonass L2 C/A to a [TrackingInterface](#).

Author

Damian Miralles, 2018, dmiralles2009(at)gmail.com

Javier Arribas, 2025 javier.arribas(at)cttc.es

Carles Fernandez-Prades, 2025 carles.fernandez(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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 Definition in file [glonass_l2_ca_dll_pll_tracking.h](#).

13.549 glonass_l2_ca_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```
00001 /*!
```

```

00002 * \file glonass_l2_ca_dll_pll_tracking.h
00003 * \brief Interface of an adapter of a DLL+PLL tracking loop block
00004 * for Glonass L2 C/A to a TrackingInterface
00005 * \author Damian Miralles, 2018, dmiralles2009(at)gmail.com
00006 * \author Javier Arribas, 2025 javier.arribas(at)cttc.es
00007 * \author Carles Fernandez-Prades, 2025 carles.fernandez(at)cttc.es
00008 *
00009 *
00010 * Code DLL + carrier PLL according to the algorithms described in:
00011 * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00012 * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00013 * Approach, Birkhauser, 2007
00014 *
00015 * -----
00016 *
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00019 *
00020 * Copyright (C) 2010-2025 (see AUTHORS file for a list of contributors)
00021 * SPDX-License-Identifier: GPL-3.0-or-later
00022 *
00023 * -----
00024 */
00025
00026 #ifndef GNSS_SDR_GLOMSS_L2_CA_DLL_PLL_TRACKING_H
00027 #define GNSS_SDR_GLOMSS_L2_CA_DLL_PLL_TRACKING_H
00028
00029 #include "base_dll_pll_tracking.h"
00030
00031 /** \addtogroup Tracking
00032  * Classes for GNSS signal tracking.
00033  * \{ */
00034 /** \addtogroup Tracking_adapters tracking_adapters
00035  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00036  * \{ */
00037
00038
00039 /*!
00040 * \brief This class implements a code DLL + carrier PLL tracking loop
00041 * block adapter for GLONASS L2 signals
00042 */
00043 class GlonassL2CaDllPllTracking : public BaseDllPllTracking
00044 {
00045 public:
00046     /** Constructor
00047      * GlonassL2CaDllPllTracking(const ConfigurationInterface* configuration,
00048      * const std::string& role,
00049      * unsigned int in_streams,
00050      * unsigned int out_streams);
00051
00052      * Returns "GLONASS_L2_CA_DLL_PLL_Tracking"
00053      * inline std::string implementation() override
00054      * {
00055      *     return "GLONASS_L2_CA_DLL_PLL_Tracking";
00056      * }
00057
00058 private:
00059     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00060     void create_tracking_block() override;
00061 };
00062
00063 /** \} */
00064 /** \} */
00065 #endif // GNSS_SDR_GLOMSS_L2_CA_DLL_PLL_TRACKING_H

```

13.550 gps_l1_ca_dll_pll_tracking.h File Reference

Interface of an adapter of a DLL+PLL tracking loop block for GPS L1 C/A to a [TrackingInterface](#).

```
#include "base_dll_pll_tracking.h"
```

Classes

- class [GpsL1CaDllPllTracking](#)

This class implements a code DLL + carrier PLL tracking loop block adapter for GPS L1 C/A signals.

13.550.1 Detailed Description

Interface of an adapter of a DLL+PLL tracking loop block for GPS L1 C/A to a [TrackingInterface](#).

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com Javier Arribas, 2011. jarribas(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [gps_l1_ca_dll_pll_tracking.h](#).

13.551 gps_l1_ca_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gps_l1_ca_dll_pll_tracking.h
00003  * \brief Interface of an adapter of a DLL+PLL tracking loop block
00004  * for GPS L1 C/A to a TrackingInterface
00005  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00006  *         Javier Arribas, 2011. jarribas(at)cttc.es
00007  *
00008  * Code DLL + carrier PLL according to the algorithms described in:
00009  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00010  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00011  * Approach, Birkhauser, 2007
00012  *
00013  * -----
00014  *
00015  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00020  *
00021  * -----
00022  */
00023
00024 #ifndef GNSS_SDR_GPS_L1_CA_DLL_PLL_TRACKING_H
00025 #define GNSS_SDR_GPS_L1_CA_DLL_PLL_TRACKING_H
00026
00027 #include "base_dll_pll_tracking.h"
00028
00029 /** \addtogroup Tracking
00030  * Classes for GNSS signal tracking.
00031  * \{ */
00032 /** \addtogroup Tracking_adapters tracking_adapters
00033  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00034  * \{ */
00035
00036
00037 /*!
00038  * \brief This class implements a code DLL + carrier PLL tracking loop
00039  * block adapter for GPS L1 C/A signals
00040  */
00041 class GpsL1CaDllPllTracking : public BaseDllPllTracking
00042 {
00043 public:
00044     /** Constructor
00045      * \param configuration ConfigurationInterface* configuration,
00046      * \param role const std::string& role,
00047      * \param in_streams unsigned int in_streams,
00048      * \param out_streams unsigned int out_streams);
00049
00050     /** Returns "GPS_L1_CA_DLL_PLL_Tracking"
00051     inline std::string implementation() override
00052     {
00053         return "GPS_L1_CA_DLL_PLL_Tracking";
00054     }
00055 private:
00056     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00057     void create_tracking_block() override;
00058 };
00059
00060
00061 /** \} */
00062 /** \} */
00063 #endif // GNSS_SDR_GPS_L1_CA_DLL_PLL_TRACKING_H
```

13.552 gps_l1_ca_dll_pll_tracking_fpga.h File Reference

Interface of an adapter of a DLL+PLL tracking loop block for GPS L1 C/A to a [TrackingInterface](#) for the FPGA.

```
#include "base_dll_pll_tracking_fpga.h"
```

Classes

- class [GpsL1CaDllPllTrackingFpga](#)

Adapter for a GPS L1 C/A DLL+PLL tracking loop for FPGA.

13.552.1 Detailed Description

Interface of an adapter of a DLL+PLL tracking loop block for GPS L1 C/A to a [TrackingInterface](#) for the FPGA.

Author

Marc Majoral, 2019, mmajoral(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [gps_l1_ca_dll_pll_tracking_fpga.h](#).

13.553 gps_l1_ca_dll_pll_tracking_fpga.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gps_l1_ca_dll_pll_tracking_fpga.h
00003  * \brief Interface of an adapter of a DLL+PLL tracking loop block
00004  * for GPS L1 C/A to a TrackingInterface for the FPGA
00005  * \author Marc Majoral, 2019, mmajoral(at)cttc.es
00006  *
00007  * Code DLL + carrier PLL according to the algorithms described in:
00008  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00009  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00010  * Approach, Birkhauser, 2007
00011  *
00012  * -----
00013  *
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00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_GPS_L1_CA_DLL_PLL_TRACKING_FPGA_H
00024 #define GNSS_SDR_GPS_L1_CA_DLL_PLL_TRACKING_FPGA_H
00025
00026
00027 #include "base_dll_pll_tracking_fpga.h"
00028
00029 // /** \addtogroup Tracking
00030 //  * \{ */
00031 // /** \addtogroup Tracking_adapters
00032 //  * \{ */
00033
00034 class ConfigurationInterface;
00035
00036 /*!
00037  * \brief Adapter for a GPS L1 C/A DLL+PLL tracking loop for FPGA
00038  */
00039 class GpsL1CaDllPllTrackingFpga : public BaseDllPllTrackingFpga
00040 {
00041 public:
00042     GpsL1CaDllPllTrackingFpga(const ConfigurationInterface* configuration,
00043                               const std::string& role,
00044                               unsigned int in_streams,
00045                               unsigned int out_streams);
00046
00047     ~GpsL1CaDllPllTrackingFpga() override;
```



```

00048
00049  /*!
00050   * \brief Returns "GPS_L1_CA_DLL_PLL_Tracking_FPGA"
00051   */
00052  std::string implementation() override
00053  {
00054      return "GPS_L1_CA_DLL_PLL_Tracking_FPGA";
00055  }
00056
00057 private:
00058     int32_t* ca_codes_ptr_;
00059 };
00060
00061
00062 /** \} */
00063 /** \} */
00064 #endif // GNSS_SDR_GPS_L1_CA_DLL_PLL_TRACKING_FPGA_H

```

13.554 gps_l1_ca_dll_pll_tracking_gpu.h File Reference

Implementation of an adapter of a DLL+PLL tracking loop block using GPU accelerated functions for GPS L1 C/A to a [TrackingInterface](#).

```

#include "gps_l1_ca_dll_pll_tracking_gpu_cc.h"
#include "tracking_interface.h"
#include <string>

```

Classes

- class [GpsL1CaDllPllTrackingGPU](#)

This class implements a code DLL + carrier PLL tracking loop using GPU accelerated functions.

13.554.1 Detailed Description

Implementation of an adapter of a DLL+PLL tracking loop block using GPU accelerated functions for GPS L1 C/A to a [TrackingInterface](#).

Author

Javier Arribas, 2015. jarribas(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [gps_l1_ca_dll_pll_tracking_gpu.h](#).

13.555 gps_l1_ca_dll_pll_tracking_gpu.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002   * \file gps_l1_ca_dll_pll_tracking_gpu.h
00003   * \brief Implementation of an adapter of a DLL+PLL tracking loop block using GPU accelerated
00004   *        functions
00005   * for GPS L1 C/A to a TrackingInterface
00006   * \author Javier Arribas, 2015. jarribas(at)cttc.es
00007   *
00008   * Code DLL + carrier PLL according to the algorithms described in:
00009   * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00010   * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00011   * Approach, Birkhauser, 2007
00012   * -----
00013   *
00014   * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00019   *

```

```

00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_GPS_L1_CA_DLL_PLL_TRACKING_GPU_H
00024 #define GNSS_SDR_GPS_L1_CA_DLL_PLL_TRACKING_GPU_H
00025
00026 #include "gps_l1_ca_dll_pll_tracking_gpu_cc.h"
00027 #include "tracking_interface.h"
00028 #include <string>
00029
00030 /** \addtogroup Tracking
00031  * \{ */
00032 /** \addtogroup Tracking_adapters
00033  * \{ */
00034
00035
00036 class ConfigurationInterface;
00037
00038 /*!
00039  * \brief This class implements a code DLL + carrier PLL tracking loop using GPU accelerated functions
00040  */
00041 class GpsL1CaDllPllTrackingGPU : public TrackingInterface
00042 {
00043 public:
00044     GpsL1CaDllPllTrackingGPU(
00045         const ConfigurationInterface* configuration,
00046         std::string role,
00047         unsigned int in_streams,
00048         unsigned int out_streams);
00049
00050     virtual ~GpsL1CaDllPllTrackingGPU();
00051
00052     inline std::string role() override
00053     {
00054         return role_;
00055     }
00056
00057     /*! Returns "GPS_L1_CA_DLL_PLL_Tracking_GPU"
00058     inline std::string implementation() override
00059     {
00060         return "GPS_L1_CA_DLL_PLL_Tracking_GPU";
00061     }
00062
00063     inline size_t item_size() override
00064     {
00065         return item_size_;
00066     }
00067
00068     void connect(gr::top_block_sptr top_block) override;
00069     void disconnect(gr::top_block_sptr top_block) override;
00070     gr::basic_block_sptr get_left_block() override;
00071     gr::basic_block_sptr get_right_block() override;
00072
00073     /*!
00074     * \brief Set tracking channel unique ID
00075     */
00076     void set_channel(unsigned int channel) override;
00077
00078     /*!
00079     * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00080     * to efficiently exchange synchronization data between acquisition and tracking blocks
00081     */
00082     void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override;
00083
00084     void start_tracking() override;
00085
00086     /*!
00087     * \brief Stop running tracking
00088     */
00089     void stop_tracking() override;
00090
00091 private:
00092     gps_l1_ca_dll_pll_tracking_gpu_cc_sptr tracking_;
00093     size_t item_size_;
00094     unsigned int channel_;
00095     std::string role_;
00096     unsigned int in_streams_;
00097     unsigned int out_streams_;
00098 };
00099
00100
00101 /** \} */
00102 /** \} */
00103 #endif // GNSS_SDR_GPS_L1_CA_DLL_PLL_TRACKING_GPU_H

```

13.556 gps_l1_ca_gaussian_tracking.h File Reference

Interface of an adapter of a DLL + Kalman carrier tracking loop block for GPS L1 C/A signals.

```
#include "gps_l1_ca_gaussian_tracking_cc.h"
#include "tracking_interface.h"
#include <string>
```

Classes

- class [GpsL1CaGaussianTracking](#)
This class implements a code DLL + carrier PLL tracking loop.

13.556.1 Detailed Description

Interface of an adapter of a DLL + Kalman carrier tracking loop block for GPS L1 C/A signals.

Author

Javier Arribas, 2018. jarribas(at)cttc.es

Jordi Vila-Valls 2018. jvila(at)cttc.es

Carles Fernandez-Prades 2018. cfernandez(at)cttc.es

Reference: J. Vila-Valls, P. Closas, M. Navarro and C. Fernandez-Prades, "Are PLLs Dead? A Tutorial on Kalman Filter-based Techniques for Digital Carrier Synchronization", IEEE Aerospace and Electronic Systems Magazine, Vol. 32, No. 7, pp. 28–45, July 2017. DOI: 10.1109/MAES.2017.150260

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Definition in file [gps_l1_ca_gaussian_tracking.h](#).

13.557 gps_l1_ca_gaussian_tracking.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gps_l1_ca_gaussian_tracking.h
00003  * \brief Interface of an adapter of a DLL + Kalman carrier
00004  * tracking loop block for GPS L1 C/A signals
00005  * \author Javier Arribas, 2018. jarribas(at)cttc.es
00006  * \author Jordi Vila-Valls 2018. jvila(at)cttc.es
00007  * \author Carles Fernandez-Prades 2018. cfernandez(at)cttc.es
00008  *
00009  * Reference:
00010  * J. Vila-Valls, P. Closas, M. Navarro and C. Fernandez-Prades,
00011  * "Are PLLs Dead? A Tutorial on Kalman Filter-based Techniques for Digital
00012  * Carrier Synchronization", IEEE Aerospace and Electronic Systems Magazine,
00013  * Vol. 32, No. 7, pp. 28-45, July 2017. DOI: 10.1109/MAES.2017.150260
00014  *
00015  * -----
00016  *
00017  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00019  *
00020  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00021  * SPDX-License-Identifier: GPL-3.0-or-later
00022  *
00023  * -----
00024  */
00025
00026 #ifndef GNSS_SDR_GPS_L1_CA_GAUSSIAN_TRACKING_H
00027 #define GNSS_SDR_GPS_L1_CA_GAUSSIAN_TRACKING_H
00028
00029 #include "gps_l1_ca_gaussian_tracking_cc.h"
00030 #include "tracking_interface.h"
00031 #include <string>
00032
00033 /** \addtogroup Tracking
00034  * \{ */
00035 /** \addtogroup Tracking_adapters
00036  * \{ */
00037
00038
```

```

00039 class ConfigurationInterface;
00040
00041 /*!
00042  * \brief This class implements a code DLL + carrier PLL tracking loop
00043  */
00044 class GpsL1CaGaussianTracking : public TrackingInterface
00045 {
00046 public:
00047     GpsL1CaGaussianTracking(
00048         const ConfigurationInterface* configuration,
00049         const std::string& role,
00050         unsigned int in_streams,
00051         unsigned int out_streams);
00052
00053     ~GpsL1CaGaussianTracking() = default;
00054
00055     inline std::string role() override
00056     {
00057         return role_;
00058     }
00059
00060     ///! Returns "GPS_L1_CA_Gaussian_Tracking"
00061     inline std::string implementation() override
00062     {
00063         return "GPS_L1_CA_Gaussian_Tracking";
00064     }
00065
00066     inline size_t item_size() override
00067     {
00068         return item_size_;
00069     }
00070
00071     void connect(gr::top_block_sptr top_block) override;
00072     void disconnect(gr::top_block_sptr top_block) override;
00073     gr::basic_block_sptr get_left_block() override;
00074     gr::basic_block_sptr get_right_block() override;
00075
00076     /*!
00077     * \brief Set tracking channel unique ID
00078     */
00079     void set_channel(unsigned int channel) override;
00080
00081     /*!
00082     * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00083     * to efficiently exchange synchronization data between acquisition and tracking blocks
00084     */
00085     void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override;
00086
00087     void start_tracking() override;
00088
00089     /*!
00090     * \brief Stop running tracking
00091     */
00092     void stop_tracking() override;
00093
00094 private:
00095     gps_ll_ca_gaussian_tracking_cc_sptr tracking_sptr_;
00096     std::string role_;
00097     size_t item_size_;
00098     unsigned int channel_;
00099     unsigned int in_streams_;
00100     unsigned int out_streams_;
00101 };
00102
00103
00104 /** \} */
00105 /** \} */
00106 #endif // GNSS_SDR_GPS_L1_CA_GAUSSIAN_TRACKING_H

```

13.558 gps_l1_ca_kf_tracking.h File Reference

Interface of an adapter of a code + carrier Kalman Filter tracking loop with VTL capabilities block for GPS L1 C/A to a [TrackingInterface](#).

```

#include "kf_tracking.h"
#include "tracking_interface.h"
#include <string>

```

Classes

- class [GpsL1CaKfTracking](#)

This class implements a code + carrier Kalman Filter tracking loop with VTL capabilities.

13.558.1 Detailed Description

Interface of an adapter of a code + carrier Kalman Filter tracking loop with VTL capabilities block for GPS L1 C/A to a [TrackingInterface](#).

Author

Javier Arribas, 2020. jarribas(at)cttc.es

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Definition in file [gps_l1_ca_kf_tracking.h](#).

13.559 gps_l1_ca_kf_tracking.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002   * \file gps_l1_ca_kf_tracking.h
00003   * \brief Interface of an adapter of a code + carrier Kalman Filter tracking
00004   * loop with VTL capabilities block
00005   * for GPS L1 C/A to a TrackingInterface
00006   * \author Javier Arribas, 2020. jarribas(at)cttc.es
00007   *
00008   *
00009   * -----
00010   *
00011   * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012   *
00013   * GNSS-SDR is a software defined Global Navigation
00014   * Satellite Systems receiver
00015   *
00016   * This file is part of GNSS-SDR.
00017   *
00018   * SPDX-License-Identifier: GPL-3.0-or-later
00019   *
00020   * -----
00021   */
00022
00023 #ifndef GNSS_SDR_GPS_L1_CA_KF_TRACKING_H
00024 #define GNSS_SDR_GPS_L1_CA_KF_TRACKING_H
00025
00026 #include "kf_tracking.h"
00027 #include "tracking_interface.h"
00028 #include <string>
00029
00030 class ConfigurationInterface;
00031
00032 /*!
00033   * \brief This class implements a code + carrier Kalman Filter tracking loop
00034   * with VTL capabilities
00035   */
00036 class GpsL1CaKfTracking : public TrackingInterface
00037 {
00038 public:
00039     GpsL1CaKfTracking(
00040         const ConfigurationInterface* configuration,
00041         const std::string& role,
00042         unsigned int in_streams,
00043         unsigned int out_streams);
00044
00045     ~GpsL1CaKfTracking() = default;
00046
00047     inline std::string role() override
00048     {
00049         return role_;
00050     }
00051
00052     /*! Returns "GPS_L1_CA_KF_Tracking"
00053     inline std::string implementation() override
00054     {
00055         return "GPS_L1_CA_KF_Tracking";

```

```

00056     }
00057
00058     inline size_t item_size() override
00059     {
00060         return item_size_;
00061     }
00062
00063     void connect(gr::top_block_sptr top_block) override;
00064     void disconnect(gr::top_block_sptr top_block) override;
00065     gr::basic_block_sptr get_left_block() override;
00066     gr::basic_block_sptr get_right_block() override;
00067
00068     /*!
00069     * \brief Set tracking channel unique ID
00070     */
00071     void set_channel(unsigned int channel) override;
00072
00073     /*!
00074     * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00075     * to efficiently exchange synchronization data between acquisition
00076     * and tracking blocks
00077     */
00078     void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override;
00079
00080     void start_tracking() override;
00081
00082     /*!
00083     * \brief Stop running tracking
00084     */
00085     void stop_tracking() override;
00086
00087 private:
00088     kf_tracking_sptr tracking_sptr_;
00089     std::string role_;
00090     size_t item_size_;
00091     unsigned int channel_;
00092     unsigned int in_streams_;
00093     unsigned int out_streams_;
00094 };
00095
00096 #endif // GNSS_SDR_GPS_L1_CA_KF_TRACKING_H

```

13.560 gps_l1_ca_tcp_connector_tracking.h File Reference

Interface of an adapter of a TCP connector block based on code DLL + carrier PLL for GPS L1 C/A to a [TrackingInterface](#).

```

#include "gps_l1_ca_tcp_connector_tracking_cc.h"
#include "tracking_interface.h"
#include <string>

```

Classes

- class [GpsL1CaTcpConnectorTracking](#)

This class implements a code DLL + carrier PLL tracking loop.

13.560.1 Detailed Description

Interface of an adapter of a TCP connector block based on code DLL + carrier PLL for GPS L1 C/A to a [TrackingInterface](#).

Author

David Pubill, 2012. dpubill(at)cttc.es Javier Arribas, 2011. jarribas(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [gps_l1_ca_tcp_connector_tracking.h](#).

13.561 gps_l1_ca_tcp_connector_tracking.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gps_l1_ca_tcp_connector_tracking.h
00003  * \brief Interface of an adapter of a TCP connector block based on code DLL + carrier PLL
00004  * for GPS L1 C/A to a TrackingInterface
00005  * \author David Pubill, 2012. dpubill(at)cttc.es
00006  *         Javier Arribas, 2011. jarribas(at)cttc.es
00007  *
00008  * Code DLL + carrier PLL according to the algorithms described in:
00009  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00010  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00011  * Approach, Birkhauser, 2007
00012  *
00013  * -----
00014  *
00015  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00016  * This file is part of GNSS-SDR.
00017  *
00018  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00019  * SPDX-License-Identifier: GPL-3.0-or-later
00020  *
00021  * -----
00022  */
00023
00024 #ifndef GNSS_SDR_GPS_L1_CA_TCP_CONNECTOR_TRACKING_H
00025 #define GNSS_SDR_GPS_L1_CA_TCP_CONNECTOR_TRACKING_H
00026
00027 #include "gps_l1_ca_tcp_connector_tracking_cc.h"
00028 #include "tracking_interface.h"
00029 #include <string>
00030
00031 /** \addtogroup Tracking
00032  * \{ */
00033 /** \addtogroup Tracking_adapters
00034  * \{ */
00035
00036
00037 class ConfigurationInterface;
00038
00039 /*!
00040 * \brief This class implements a code DLL + carrier PLL tracking loop
00041 */
00042 class GpsL1CaTcpConnectorTracking : public TrackingInterface
00043 {
00044 public:
00045     GpsL1CaTcpConnectorTracking(
00046         const ConfigurationInterface* configuration,
00047         const std::string& role,
00048         unsigned int in_streams,
00049         unsigned int out_streams);
00050
00051     ~GpsL1CaTcpConnectorTracking() = default;
00052
00053     inline std::string role() override
00054     {
00055         return role_;
00056     }
00057
00058     /*! Returns "GPS_L1_CA_TCP_CONNECTOR_Tracking"
00059     inline std::string implementation() override
00060     {
00061         return "GPS_L1_CA_TCP_CONNECTOR_Tracking";
00062     }
00063
00064     inline size_t item_size() override
00065     {
00066         return item_size_;
00067     }
00068
00069     void connect(gr::top_block_sptr top_block) override;
00070     void disconnect(gr::top_block_sptr top_block) override;
00071     gr::basic_block_sptr get_left_block() override;
00072     gr::basic_block_sptr get_right_block() override;
00073
00074     /*!
00075     * \brief Set tracking channel unique ID
00076     */
00077     void set_channel(unsigned int channel) override;
00078
00079     /*!
00080     * \brief Set acquisition/tracking common Gnss_Synchro object pointer
00081     * to efficiently exchange synchronization data between acquisition and tracking blocks
00082     */
00083     void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro) override;

```

```

00084
00085     void start_tracking() override;
00086
00087     /*!
00088      * \brief Stop running tracking
00089      */
00090     void stop_tracking() override;
00091
00092 private:
00093     gps_ll_ca_tcp_connector_tracking_cc_sptr tracking_sptr_;
00094     std::string role_;
00095     size_t item_size_;
00096     unsigned int channel_;
00097     unsigned int in_streams_;
00098     unsigned int out_streams_;
00099 };
00100
00101
00102 /** \} */
00103 /** \} */
00104 #endif // GNSS_SDR_GPS_L1_CA_TCP_CONNECTOR_TRACKING_H

```

13.562 gps_l2_m_dll_pll_tracking.h File Reference

Interface of an adapter of a DLL+PLL tracking loop block for GPS L2C(M) to a [TrackingInterface](#).

```
#include "base_dll_pll_tracking.h"
```

Classes

- class [GpsL2MDIIPITracking](#)

This class implements a code DLL + carrier PLL tracking loop block adapter for GPS L2C(M) signals.

13.562.1 Detailed Description

Interface of an adapter of a DLL+PLL tracking loop block for GPS L2C(M) to a [TrackingInterface](#).

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com Javier Arribas, 2011. jarribas(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [gps_l2_m_dll_pll_tracking.h](#).

13.563 gps_l2_m_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gps_l2_m_dll_pll_tracking.h
00003  * \brief Interface of an adapter of a DLL+PLL tracking loop block
00004  * for GPS L2C(M) to a TrackingInterface
00005  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00006  *         Javier Arribas, 2011. jarribas(at)cttc.es
00007  *
00008  * Code DLL + carrier PLL according to the algorithms described in:
00009  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00010  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00011  * Approach, Birkhauser, 2007
00012  *
00013  * -----
00014  *
00015  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00016  * This file is part of GNSS-SDR.
00017  *
00018  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00019  * SPDX-License-Identifier: GPL-3.0-or-later
00020  *
00021  * -----
00022  */

```



```

00023
00024 #ifndef GNSS_SDR_GPS_L2_M_DLL_PLL_TRACKING_H
00025 #define GNSS_SDR_GPS_L2_M_DLL_PLL_TRACKING_H
00026
00027 #include "base_dll_pll_tracking.h"
00028
00029 /** \addtogroup Tracking
00030 * Classes for GNSS signal tracking.
00031 * \{ */
00032 /** \addtogroup Tracking_adapters tracking_adapters
00033 * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00034 * \{ */
00035
00036 /*!
00037 * \brief This class implements a code DLL + carrier PLL tracking loop
00038 * block adapter for GPS L2C(M) signals
00039 */
00040 class GpsL2MDllPllTracking : public BaseDllPllTracking
00041 {
00042 public:
00043     /*! Constructor
00044     GpsL2MDllPllTracking(const ConfigurationInterface* configuration,
00045         const std::string& role,
00046         unsigned int in_streams,
00047         unsigned int out_streams);
00048
00049     /*! Returns "GPS_L2_M_DLL_PLL_Tracking"
00050     inline std::string implementation() override
00051     {
00052         return "GPS_L2_M_DLL_PLL_Tracking";
00053     }
00054
00055 private:
00056     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00057     void create_tracking_block() override;
00058 };
00059
00060
00061 /** \} */
00062 /** \} */
00063 #endif // GNSS_SDR_GPS_L2_M_DLL_PLL_TRACKING_H

```

13.564 gps_l2_m_dll_pll_tracking_fpga.h File Reference

Interface of an adapter of a DLL+PLL tracking loop block for GPS L2C to a [TrackingInterface](#) for the FPGA.

```
#include "base_dll_pll_tracking_fpga.h"
```

Classes

- class [GpsL2MDllPllTrackingFpga](#)
Adapter for a GPS L2M DLL+PLL tracking loop implemented in FPGA.

13.564.1 Detailed Description

Interface of an adapter of a DLL+PLL tracking loop block for GPS L2C to a [TrackingInterface](#) for the FPGA.

Author

Marc Majoral, 2019, mmajoral(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [gps_l2_m_dll_pll_tracking_fpga.h](#).

13.565 gps_l2_m_dll_pll_tracking_fpga.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file gps_l2_m_dll_pll_tracking_fpga.h

```

```

00003  * \brief Interface of an adapter of a DLL+PLL tracking loop block
00004  * for GPS L2C to a TrackingInterface for the FPGA
00005  * \author Marc Majoral, 2019, mmajoral(at)cttc.es
00006  *
00007  * Code DLL + carrier PLL according to the algorithms described in:
00008  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00009  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00010  * Approach, Birkhauser, 2007
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.
00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_GPS_L2_M_DLL_PLL_TRACKING_FPGA_H
00024 #define GNSS_SDR_GPS_L2_M_DLL_PLL_TRACKING_FPGA_H
00025
00026 #include "base_dll_pll_tracking_fpga.h"
00027
00028 /** \addtogroup Tracking
00029  * \{ */
00030 /** \addtogroup Tracking_adapters
00031  * \{ */
00032
00033 /*!
00034  * \brief Adapter for a GPS L2M DLL+PLL tracking loop implemented in FPGA
00035  */
00036 class GpsL2MD11P11TrackingFpga : public BaseD11P11TrackingFpga
00037 {
00038 public:
00039     /*!
00040     * \brief Constructor
00041     */
00042     GpsL2MD11P11TrackingFpga(const ConfigurationInterface* configuration,
00043         const std::string& role,
00044         unsigned int in_streams,
00045         unsigned int out_streams);
00046
00047     /*!
00048     * \brief Destructor
00049     */
00050     ~GpsL2MD11P11TrackingFpga() override;
00051
00052     /*!
00053     * \brief Returns "GPS_L2_M_DLL_PLL_Tracking_FPGA"
00054     */
00055     std::string implementation() override
00056     {
00057         return "GPS_L2_M_DLL_PLL_Tracking_FPGA";
00058     }
00059 private:
00060     int32_t* prn_codes_ptr_; // Pointer to local PRN codes
00061 };
00062
00063 /** \} */
00064 /** \} */
00065 /** \} */
00066 #endif // GNSS_SDR_GPS_L2_M_DLL_PLL_TRACKING_FPGA_H

```

13.566 gps_l5_dll_pll_tracking.h File Reference

Interface of an adapter of a DLL+PLL tracking loop block for GPS L5 to a [TrackingInterface](#).

```
#include "base_dll_pll_tracking.h"
```

Classes

- class [GpsL5DI1P11Tracking](#)

This class implements a code DLL + carrier PLL tracking loop block adapter for GPS L5 signals.

13.566.1 Detailed Description

Interface of an adapter of a DLL+PLL tracking loop block for GPS L5 to a [TrackingInterface](#).

Author

Javier Arribas, 2017. jarribas(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [gps_l5_dll_pll_tracking.h](#).

13.567 gps_l5_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gps_l5_dll_pll_tracking.h
00003  * \brief Interface of an adapter of a DLL+PLL tracking loop block
00004  * for GPS L5 to a TrackingInterface
00005  * \author Javier Arribas, 2017. jarribas(at)cttc.es
00006  *
00007  * Code DLL + carrier PLL according to the algorithms described in:
00008  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00009  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00010  * Approach, Birkhauser, 2007
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.
00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_GPS_L5_DLL_PLL_TRACKING_H
00024 #define GNSS_SDR_GPS_L5_DLL_PLL_TRACKING_H
00025
00026 #include "base_dll_pll_tracking.h"
00027
00028 /** \addtogroup Tracking
00029  * Classes for GNSS signal tracking.
00030  * \{ */
00031 /** \addtogroup Tracking_adapters tracking_adapters
00032  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00033  * \{ */
00034
00035
00036 /*!
00037  * \brief This class implements a code DLL + carrier PLL tracking loop
00038  * block adapter for GPS L5 signals
00039  */
00040 class GpsL5DllPllTracking : public BaseDllPllTracking
00041 {
00042 public:
00043     /** Constructor
00044     GpsL5DllPllTracking(const ConfigurationInterface* configuration,
00045         const std::string& role,
00046         unsigned int in_streams,
00047         unsigned int out_streams);
00048
00049     /** Returns "GPS_L5_DLL_PLL_Tracking"
00050     inline std::string implementation() override
00051     {
00052         return "GPS_L5_DLL_PLL_Tracking";
00053     }
00054
00055 private:
00056     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00057     void create_tracking_block() override;
00058 };
00059
00060 /** \} */
00061 /** \} */
00062 #endif // GNSS_SDR_GPS_L5_DLL_PLL_TRACKING_H

```

13.568 gps_l5_dll_pll_tracking_fpga.h File Reference

Interface of an adapter of a DLL+PLL tracking loop block for GPS L5 to a [TrackingInterface](#) for the FPGA.

```
#include "base_dll_pll_tracking_fpga.h"
```

Classes

- class [GpsL5DllPllTrackingFpga](#)

Adapter for a GPS L5 DLL+PLL tracking loop for FPGA devices.

13.568.1 Detailed Description

Interface of an adapter of a DLL+PLL tracking loop block for GPS L5 to a [TrackingInterface](#) for the FPGA.

Author

Marc Majoral, 2019. mmajoral(at)cttc.cat Javier Arribas, 2019. jarribas(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [gps_l5_dll_pll_tracking_fpga.h](#).

13.569 gps_l5_dll_pll_tracking_fpga.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gps_l5_dll_pll_tracking_fpga.h
00003  * \brief Interface of an adapter of a DLL+PLL tracking loop block
00004  * for GPS L5 to a TrackingInterface for the FPGA
00005  * \author Marc Majoral, 2019. mmajoral(at)cttc.cat
00006  *         Javier Arribas, 2019. jarribas(at)cttc.es
00007  *
00008  * Code DLL + carrier PLL according to the algorithms described in:
00009  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00010  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00011  * Approach, Birkhauser, 2007
00012  *
00013  * -----
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00015  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00016  * This file is part of GNSS-SDR.
00017  *
00018  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00019  * SPDX-License-Identifier: GPL-3.0-or-later
00020  *
00021  * -----
00022  */
00023
00024 #ifndef GNSS_SDR_GPS_L5_DLL_PLL_TRACKING_FPGA_H
00025 #define GNSS_SDR_GPS_L5_DLL_PLL_TRACKING_FPGA_H
00026
00027 #include "base_dll_pll_tracking_fpga.h"
00028
00029 // /** \addtogroup Tracking
00030 //  * \{ */
00031 // /** \addtogroup Tracking_adapters
00032 //  * \{ */
00033
00034 /*!
00035  * \brief Adapter for a GPS L5 DLL+PLL tracking loop for FPGA devices
00036  */
00037 class GpsL5DllPllTrackingFpga : public BaseDllPllTrackingFpga
00038 {
00039 public:
00040     /*!
00041      * \brief Constructor
00042      */
00043     GpsL5DllPllTrackingFpga(const ConfigurationInterface* configuration,
00044                             const std::string& role,
00045                             unsigned int in_streams,
00046                             unsigned int out_streams);
00047
00048     /*!
00049      * \brief Destructor
00050      */
00051     ~GpsL5DllPllTrackingFpga() override;
```

```

00052
00053     /*!
00054     * \brief Returns "GPS_L5_DLL_PLL_Tracking_FPGA"
00055     */
00056     std::string implementation() override
00057     {
00058         return "GPS_L5_DLL_PLL_Tracking_FPGA";
00059     }
00060
00061 private:
00062     // Pointer to local PRN codes (pilot/data)
00063     int32_t* prn_codes_ptr_;
00064     int32_t* data_codes_ptr_;
00065
00066     // Pilot tracking flag
00067     bool track_pilot_;
00068 };
00069
00070 // /** \} */
00071 // /** \} */
00072 #endif // GNSS_SDR_GPS_L5_DLL_PLL_TRACKING_FPGA_H

```

13.570 qzss_l1_dll_pll_tracking.h File Reference

Interface of an adapter of a DLL+PLL tracking loop block for QZSS L1 signals to a [TrackingInterface](#).

```
#include "base_dll_pll_tracking.h"
```

Classes

- class [QzssL1DllPllTracking](#)

This class implements a code DLL + carrier PLL tracking loop block adapter for QZSS L1 signals.

13.570.1 Detailed Description

Interface of an adapter of a DLL+PLL tracking loop block for QZSS L1 signals to a [TrackingInterface](#).

Author

Carles Fernandez, 2026. cfernandez(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [qzss_l1_dll_pll_tracking.h](#).

13.571 qzss_l1_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file qzss_l1_dll_pll_tracking.h
00003 * \brief Interface of an adapter of a DLL+PLL tracking loop block
00004 * for QZSS L1 signals to a TrackingInterface
00005 * \author Carles Fernandez, 2026. cfernandez(at)cttc.es
00006 *
00007 * Code DLL + carrier PLL according to the algorithms described in:
00008 * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00009 * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00010 * Approach, Birkhauser, 2007
00011 *
00012 * -----
00013 *
00014 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015 * This file is part of GNSS-SDR.
00016 *
00017 * Copyright (C) 2010-2026 (see AUTHORS file for a list of contributors)
00018 * SPDX-License-Identifier: GPL-3.0-or-later
00019 *
00020 * -----
00021 */
00022

```

```

00023 #ifndef GNSS_SDR_QZSS_L1_DLL_PLL_TRACKING_H
00024 #define GNSS_SDR_QZSS_L1_DLL_PLL_TRACKING_H
00025
00026 #include "base_dll_pll_tracking.h"
00027
00028 /** \addtogroup Tracking
00029  * Classes for GNSS signal tracking.
00030  * \{ */
00031 /** \addtogroup Tracking_adapters tracking_adapters
00032  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00033  * \{ */
00034
00035
00036 /*!
00037  * \brief This class implements a code DLL + carrier PLL tracking loop
00038  * block adapter for QZSS L1 signals
00039  */
00040 class QzssL1DllPllTracking : public BaseDllPllTracking
00041 {
00042 public:
00043     /** Constructor
00044     QzssL1DllPllTracking(const ConfigurationInterface* configuration,
00045         const std::string& role,
00046         unsigned int in_streams,
00047         unsigned int out_streams);
00048
00049     /** Returns "QZSS_L1_CA_DLL_PLL_Tracking"
00050     inline std::string implementation() override
00051     {
00052         return "QZSS_L1_CA_DLL_PLL_Tracking";
00053     }
00054 private:
00055     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00056     void create_tracking_block() override;
00057 };
00058
00059
00060 /** \} */
00061 /** \} */
00062 #endif // GNSS_SDR_QZSS_L1_CA_DLL_PLL_TRACKING_H

```

13.572 qzss_l5_dll_pll_tracking.h File Reference

Interface of an adapter of a DLL+PLL tracking loop block for QZSS L5 signals to a [TrackingInterface](#).

```
#include "base_dll_pll_tracking.h"
```

Classes

- class [QzssL5DllPllTracking](#)

This class implements a code DLL + carrier PLL tracking loop block adapter for QZSS L5 signals.

13.572.1 Detailed Description

Interface of an adapter of a DLL+PLL tracking loop block for QZSS L5 signals to a [TrackingInterface](#).

Author

Carles Fernandez, 2026. cfernandez(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [qzss_l5_dll_pll_tracking.h](#).

13.573 qzss_l5_dll_pll_tracking.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file qzss_l5_dll_pll_tracking.h
00003  * \brief Interface of an adapter of a DLL+PLL tracking loop block

```

```

00004  * for QZSS L5 signals to a TrackingInterface
00005  * \author Carles Fernandez, 2026. cfernandez(at)cttc.es
00006  *
00007  * Code DLL + carrier PLL according to the algorithms described in:
00008  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00009  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency
00010  * Approach, Birkhauser, 2007
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.
00016  *
00017  * Copyright (C) 2010-2026 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_QZSS_L5_DLL_PLL_TRACKING_H
00024 #define GNSS_SDR_QZSS_L5_DLL_PLL_TRACKING_H
00025
00026 #include "base_dll_pll_tracking.h"
00027
00028 /** \addtogroup Tracking
00029  * Classes for GNSS signal tracking.
00030  * \{ */
00031 /** \addtogroup Tracking_adapters tracking_adapters
00032  * Wrap GNU Radio blocks for GNSS signal tracking with a TrackingInterface
00033  * \{ */
00034
00035
00036 /*!
00037  * \brief This class implements a code DLL + carrier PLL tracking loop
00038  * block adapter for QZSS L5 signals
00039  */
00040 class QzssL5DllPllTracking : public BaseDllPllTracking
00041 {
00042 public:
00043     /** Constructor
00044      * QzssL5DllPllTracking(const ConfigurationInterface* configuration,
00045      * const std::string& role,
00046      * unsigned int in_streams,
00047      * unsigned int out_streams);
00048
00049      * Returns "QZSS_L5_DLL_PLL_Tracking"
00050      * inline std::string implementation() override
00051      {
00052          return "QZSS_L5_DLL_PLL_Tracking";
00053      }
00054
00055 private:
00056     void configure_tracking_parameters(const ConfigurationInterface* configuration) override;
00057     void create_tracking_block() override;
00058 };
00059
00060 /** \} */
00061 /** \} */
00062 #endif // GNSS_SDR_QZSS_L5_DLL_PLL_TRACKING_H

```

13.574 dll_pll_veml_tracking.h File Reference

Implementation of a code DLL + carrier PLL tracking block.

```

#include "bit_synchronizer.h"
#include "cpu_multicorrelator_real_codes.h"
#include "dll_pll_conf.h"
#include "exponential_smoother.h"
#include "gnss_block_interface.h"
#include "gnss_time.h"
#include "tow_to_trk.h"
#include "tracking_FLL_PLL_filter.h"
#include "tracking_loop_filter.h"
#include <boost/circular_buffer.hpp>
#include <gnuradio/block.h>
#include <gnuradio/gr_complex.h>
#include <gnuradio/types.h>
#include <pmt/pmt.h>

```

```
#include <volk_gnssdr/volk_gnssdr_alloc.h>
#include <cstdlib>
#include <stdint>
#include <fstream>
#include <string>
#include <typeinfo>
#include <utility>
```

Classes

- class [dll_pll_veml_tracking](#)

This class implements a code DLL + carrier PLL tracking block.

Typedefs

- using [dll_pll_veml_tracking_sptr](#) = gnss_shared_ptr<[dll_pll_veml_tracking](#)>

Functions

- [dll_pll_veml_tracking_sptr](#) [dll_pll_veml_make_tracking](#) (const [Dll_Pll_Conf](#) &conf_)

13.574.1 Detailed Description

Implementation of a code DLL + carrier PLL tracking block.

Author

Javier Arribas, 2018-2025. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)

Carles Fernandez-Prades, 2018-2025 [carles.fernandez\(at\)cttc.es](mailto:carles.fernandez(at)cttc.es)

Antonio Ramos, 2018 [antonio.ramosdet\(at\)gmail.com](mailto:antonio.ramosdet(at)gmail.com)

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 Definition in file [dll_pll_veml_tracking.h](#).

13.575 [dll_pll_veml_tracking.h](#)

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file dll_pll_veml_tracking.h
00003  * \brief Implementation of a code DLL + carrier PLL tracking block.
00004  * \author Javier Arribas, 2018-2025. jarribas\(at\)cttc.es
00005  * \author Carles Fernandez-Prades, 2018-2025 carles.fernandez\(at\)cttc.es
00006  * \author Antonio Ramos, 2018 antonio.ramosdet\(at\)gmail.com
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2025 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_DLL_PLL_VEML_TRACKING_H
00020 #define GNSS_SDR_DLL_PLL_VEML_TRACKING_H
00021
00022 #include "bit_synchronizer.h"
00023 #include "cpu_multicorrelator_real_codes.h"
00024 #include "dll_pll_conf.h"
00025 #include "exponential_smoother.h"
00026 #include "gnss_block_interface.h"
00027 #include "gnss_time.h" // for timetags produced by File_Timestamp_Signal_Source
00028 #include "tow_to_trk.h"
00029 #include "tracking_FLL_PLL_filter.h" // for PLL/FLL filter
```



```

00030 #include "tracking_loop_filter.h" // for DLL filter
00031 #include <boost/circular_buffer.hpp>
00032 #include <gnuradio/block.h> // for block
00033 #include <gnuradio/gr_complex.h> // for gr_complex
00034 #include <gnuradio/types.h> // for gr_vector_int, gr_vector...
00035 #include <pmt/pmt.h> // for pmt_t
00036 #include <volk_gnssssdr/volk_gnssssdr_alloc.h> // for volk_gnssssdr::vector
00037 #include <stddef> // for size_t
00038 #include <stdint> // for int32_t
00039 #include <fstream> // for ofstream
00040 #include <string> // for string
00041 #include <typeinfo> // for typeid
00042 #include <utility> // for pair
00043
00044 /** \addtogroup Tracking
00045  * \{ */
00046 /** \addtogroup Tracking_gnuradio_blocks tracking_gr_blocks
00047  * GNU Radio blocks for GNSS signal tracking.
00048  * \{ */
00049
00050
00051 class Gnss_Synchro;
00052 class dll_pll_veml_tracking;
00053
00054 using dll_pll_veml_tracking_sptr = gnss_shared_ptr<dll_pll_veml_tracking>;
00055
00056 dll_pll_veml_tracking_sptr dll_pll_veml_make_tracking(const Dll_Pll_Conf &conf_);
00057
00058 /*!
00059  * \brief This class implements a code DLL + carrier PLL tracking block.
00060  */
00061 class dll_pll_veml_tracking : public gr::block
00062 {
00063 public:
00064     ~dll_pll_veml_tracking() override;
00065
00066     void set_channel(uint32_t channel);
00067     void set_gnss_synchro(Gnss_Synchro *p_gnss_synchro);
00068     void start_tracking();
00069     void stop_tracking();
00070
00071     int general_work(int noutput_items, gr_vector_int &ninput_items,
00072         gr_vector_const_void_star &input_items, gr_vector_void_star &output_items) override;
00073
00074     void forecast(int noutput_items, gr_vector_int &ninput_items_required) override;
00075
00076 private:
00077     friend dll_pll_veml_tracking_sptr dll_pll_veml_make_tracking(const Dll_Pll_Conf &conf_);
00078     explicit dll_pll_veml_tracking(const Dll_Pll_Conf &conf_);
00079
00080     void msg_handler_telemetry_to_trk(const pmt::pmt_t &msg);
00081     void do_correlation_step(const gr_complex *input_samples);
00082     void run_dll_pll();
00083     void check_carrier_phase_coherent_initialization();
00084     void update_tracking_vars();
00085     void clear_tracking_vars();
00086     void save_correlation_results();
00087     void log_data();
00088     void configure_bit_synchronizer();
00089     bool cn0_and_tracking_lock_status(double coh_integration_time_s);
00090     bool acquire_secondary();
00091     int64_t uint64diff(uint64_t first, uint64_t second);
00092     int32_t save_matfile() const;
00093
00094     Cpu_Multicorrelator_Real_Codes d_multicorrelator_cpu;
00095     Cpu_Multicorrelator_Real_Codes d_correlator_data_cpu; // for data channel
00096
00097     Dll_Pll_Conf d_trk_parameters;
00098
00099     Exponential_Smoother d_cn0_smoother;
00100     Exponential_Smoother d_carrier_lock_test_smoother;
00101
00102     Tracking_loop_filter d_code_loop_filter;
00103     Tracking_FLL_PLL_filter d_carrier_loop_filter;
00104
00105     HistogramBitSynchronizer d_bit_sync;
00106
00107     Gnss_Synchro *d_acquisition_gnss_synchro;
00108
00109     volk_gnssssdr::vector<float> d_tracking_code;
00110     volk_gnssssdr::vector<float> d_data_code;
00111     volk_gnssssdr::vector<float> d_local_code_shift_chips;
00112     volk_gnssssdr::vector<gr_complex> d_correlator_outs;
00113     volk_gnssssdr::vector<gr_complex> d_Prompt_Data;
00114     volk_gnssssdr::vector<gr_complex> d_Prompt_buffer;
00115
00116     boost::circular_buffer<float> d_dll_filt_history;

```

```

00117     boost::circular_buffer<std::pair<double, double> d_code_ph_history;
00118     boost::circular_buffer<std::pair<double, double> d_carr_ph_history;
00119     boost::circular_buffer<gr_complex> d_Prompt_circular_buffer;
00120
00121     const size_t d_int_type_hash_code = typeid(int).hash_code();
00122     const size_t d_tow_to_trk_type_hash_code = typeid(std::shared_ptr<TOW_to_trk>).hash_code();
00123
00124     double d_signal_carrier_freq;
00125     double d_code_period;
00126     double d_code_chip_rate;
00127     double d_acq_code_phase_samples;
00128     double d_acq_carrier_doppler_hz;
00129     double d_current_correlation_time_s;
00130     double d_carr_phase_error_hz;
00131     double d_carr_freq_error_hz;
00132     double d_carr_error_filt_hz;
00133     double d_code_error_chips;
00134     double d_code_error_filt_chips;
00135     double d_code_freq_chips;
00136     double d_cfo_frequency_hz;
00137     double d_carrier_doppler_hz;
00138     double d_acc_carrier_phase_rad;
00139     double d_rem_code_phase_chips;
00140     double d_T_chip_seconds;
00141     double d_T_prn_seconds;
00142     double d_T_prn_samples;
00143     double d_K_blk_samples;
00144     double d_carrier_lock_test;
00145     double d_CNO_SNV_dB_Hz;
00146     double d_carrier_lock_threshold;
00147     double d_carrier_phase_step_rad;
00148     double d_carrier_phase_rate_step_rad;
00149     double d_code_phase_step_chips;
00150     double d_code_phase_rate_step_chips;
00151     double d_rem_code_phase_samples;
00152
00153     gr_complex *d_Very_Early;
00154     gr_complex *d_Early;
00155     gr_complex *d_Prompt;
00156     gr_complex *d_Late;
00157     gr_complex *d_Very_Late;
00158
00159     gr_complex d_VE_accu;
00160     gr_complex d_E_accu;
00161     gr_complex d_P_accu;
00162     gr_complex d_P_accu_old;
00163     gr_complex d_L_accu;
00164     gr_complex d_VL_accu;
00165     gr_complex d_P_data_accu;
00166
00167     std::string d_secondary_code_string;
00168     std::string d_data_secondary_code_string;
00169     std::string d_systemName;
00170     std::string d_signal_type;
00171     std::string d_signal_pretty_name;
00172     std::string d_dump_filename;
00173
00174     std::ofstream d_dump_file;
00175
00176     // uint64_t d_sample_counter;
00177     uint64_t d_acq_sample_stamp;
00178     GnssTime d_last_timetag{};
00179     std::shared_ptr<TOW_to_trk> d_last_tow_received;
00180     uint64_t d_last_timetag_samplecounter;
00181     bool d_timetag_waiting;
00182
00183     float *d_prompt_data_shift;
00184     float d_rem_carr_phase_rad;
00185
00186     uint64_t d_tow_from_telemetry_ms{};
00187     int64_t d_bit_sync_target_epoch{};
00188     int32_t d_wn_from_telemetry{};
00189
00190     int32_t d_symbols_per_bit;
00191     int32_t d_state;
00192     int32_t d_correlation_length_ms;
00193     int32_t d_n_correlator_taps;
00194     int32_t d_current_prn_length_samples;
00195     int32_t d_extend_correlation_symbols_count;
00196     int32_t d_extend_correlation_symbols;
00197     int32_t d_current_symbol;
00198     int32_t d_current_data_symbol;
00199     int32_t d_cn0_estimation_counter;
00200     int32_t d_carrier_lock_fail_counter;
00201     int32_t d_code_lock_fail_counter;
00202     int32_t d_code_samples_per_chip; // All signals have 1 sample per chip code except Gal. E1 which
                                     has 2 (CBOC disabled) or 12 (CBOC enabled)

```

```

00203     int32_t d_code_length_chips;
00204
00205     uint32_t d_channel;
00206     uint32_t d_secondary_code_length;
00207     uint32_t d_data_secondary_code_length;
00208
00209     bool d_pull_in_transitory;
00210     bool d_corrected_doppler;
00211     bool d_interchange_iq;
00212     bool d_veml;
00213     bool d_cloop;
00214     bool d_secondary;
00215     bool d_dump;
00216     bool d_dump_mat;
00217     bool d_acc_carrier_phase_initialized;
00218     bool d_enable_extended_integration;
00219     bool d_Flag_PLL_180_deg_phase_locked;
00220     bool d_use_histogram_bit_sync;
00221     bool d_wait_for_bit_edge{false};
00222 };
00223
00224
00225 /** \} */
00226 /** \} */
00227 #endif // GNSS_SDR_DLL_PLL_VEML_TRACKING_H

```

13.576 dll_pll_veml_tracking_fpga.h File Reference

Implementation of a code DLL + carrier PLL tracking block using an FPGA.

```

#include "bit_synchronizer.h"
#include "dll_pll_conf_fpga.h"
#include "exponential_smoother.h"
#include "gnss_block_interface.h"
#include "tracking_FLL_PLL_filter.h"
#include "tracking_loop_filter.h"
#include <boost/circular_buffer.hpp>
#include <gnuradio/block.h>
#include <gnuradio/gr_complex.h>
#include <gnuradio/types.h>
#include <pmt/pmt.h>
#include <volk_gnssssdr/volk_gnssssdr_alloc.h>
#include <cstdint>
#include <cstdint>
#include <fstream>
#include <memory>
#include <string>
#include <typeinfo>
#include <utility>

```

Classes

- class [dll_pll_veml_tracking_fpga](#)
This class implements a code DLL + carrier PLL tracking block.

Typedefs

- using [dll_pll_veml_tracking_fpga_sptr](#) = [gnss_shared_ptr](#)<[dll_pll_veml_tracking_fpga](#)>

Functions

- [dll_pll_veml_tracking_fpga_sptr](#) [dll_pll_veml_make_tracking_fpga](#) (const [Dll_Pll_Conf_Fpga](#) &conf_)

13.576.1 Detailed Description

Implementation of a code DLL + carrier PLL tracking block using an FPGA.

Author

Marc Majoral, 2019. marc.majoral(at)cttc.es

Javier Arribas, 2019. jarribas(at)cttc.es

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Definition in file [dll_pll_veml_tracking_fpga.h](#).

13.577 dll_pll_veml_tracking_fpga.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file dll_pll_veml_tracking_fpga.h
00003  * \brief Implementation of a code DLL + carrier PLL tracking block using an FPGA.
00004  * \author Marc Majoral, 2019. marc.majoral(at)cttc.es
00005  * \author Javier Arribas, 2019. jarribas(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_DLL_PLL_VEML_TRACKING_FPGA_H
00019 #define GNSS_SDR_DLL_PLL_VEML_TRACKING_FPGA_H
00020
00021 #include "bit_synchronizer.h"
00022 #include "dll_pll_conf_fpga.h"
00023 #include "exponential_smoother.h"
00024 #include "gnss_block_interface.h"
00025 #include "tracking_FLL_PLL_filter.h" // for PLL/FLL filter
00026 #include "tracking_loop_filter.h" // for DLL filter
00027 #include <boost/circular_buffer.hpp>
00028 #include <gnuradio/block.h> // for block
00029 #include <gnuradio/gr_complex.h> // for gr_complex
00030 #include <gnuradio/types.h> // for gr_vector_int, gr_vector...
00031 #include <pmt/pmt.h> // for pmt_t
00032 #include <volk_gnssssdr/volk_gnssssdr_alloc.h> // for volk_gnssssdr::vector
00033 #include <cstdint> // for size_t
00034 #include <cstdint> // for int32_t
00035 #include <fstream> // for string, ofstream
00036 #include <memory> // for std::shared_ptr
00037 #include <string> // for string
00038 #include <typeinfo> // for typeid
00039 #include <utility> // for pair
00040
00041 /** \addtogroup Tracking
00042  * \{ */
00043 /** \addtogroup Tracking_gnuradio_blocks
00044  * \{ */
00045
00046
00047 class Fpga_Multicorrelator_8sc;
00048 class Gnss_Synchro;
00049 class dll_pll_veml_tracking_fpga;
00050
00051 using dll_pll_veml_tracking_fpga_sptr = gnss_shared_ptr<dll_pll_veml_tracking_fpga>;
00052
00053 dll_pll_veml_tracking_fpga_sptr dll_pll_veml_make_tracking_fpga(const Dll_Pll_Conf_Fpga &conf_);
00054
00055
00056 /*!
00057  * \brief This class implements a code DLL + carrier PLL tracking block.
00058  */
00059 class dll_pll_veml_tracking_fpga : public gr::block
00060 {
00061 public:
00062     /*!
00063      * \brief Destructor
00064      */
00065     ~dll_pll_veml_tracking_fpga();
00066
00067     /*!
00068      * \brief Set the channel number and configure some multicorrelator parameters
00069      */
00070     void set_channel(uint32_t channel, const std::string &device_io_name);

```

```

00071
00072     /*!
00073      * \brief This function is used with two purposes:
00074      * 1 -> To set the gnss_synchro
00075      * 2 -> A set_gnss_synchro command with a valid PRN is received when the system is going to run
00076      * acquisition with that PRN. We can use this command to pre-initialize tracking parameters and
00077      * variables before the actual acquisition process takes place. In this way we minimize the
00078      * latency between acquisition and tracking once the acquisition has been made.
00079      */
00080     void set_gnss_synchro(Gnss_Synchro *p_gnss_synchro);
00081
00082     /*!
00083      * \brief This function starts the tracking process
00084      */
00085     void start_tracking();
00086
00087     /*!
00088      * \brief This function sets a flag that makes general_work to stop in order to finish the
00089      * tracking process.
00090      */
00091     void stop_tracking();
00092
00093     /*!
00094      * \brief General Work
00095      */
00096     int general_work(int noutput_items, gr_vector_int &ninput_items,
00097                     gr_vector_const_void_star &input_items, gr_vector_void_star &output_items);
00098
00099     /*!
00100      * \brief This function disables the HW multicorrelator in the FPGA in order to stop the tracking
00101      * process
00102      */
00103     void reset();
00104
00105     private:
00106     friend dll_pll_veml_tracking_fpga_sptr dll_pll_veml_make_tracking_fpga(const Dll_Pll_Conf_Fpga
00107     &conf_);
00108     explicit dll_pll_veml_tracking_fpga(const Dll_Pll_Conf_Fpga &conf_);
00109
00110     void msg_handler_telemetry_to_trk(const pmt::pmt_t &msg);
00111     bool cn0_and_tracking_lock_status(double coh_integration_time_s);
00112     bool acquire_secondary();
00113     void do_correlation_step();
00114     void run_dll_pll();
00115     void check_carrier_phase_coherent_initialization();
00116     void update_tracking_vars();
00117     void clear_tracking_vars();
00118     void save_correlation_results();
00119     void log_data();
00120     void configure_bit_synchronizer();
00121     int32_t save_matfile() const;
00122
00123     Dll_Pll_Conf_Fpga d_trk_parameters;
00124     HistogramBitSynchronizer d_bit_sync;
00125     Exponential_Smoother d_cn0_smoother;
00126     Exponential_Smoother d_carrier_lock_test_smoother;
00127
00128     Gnss_Synchro *d_acquisition_gnss_synchro;
00129
00130     Tracking_loop_filter d_code_loop_filter;
00131
00132     Tracking_FLL_PLL_filter d_carrier_loop_filter;
00133
00134     volk_gnssssdr::vector<float> d_local_code_shift_chips;
00135     volk_gnssssdr::vector<gr_complex> d_correlator_outs;
00136     volk_gnssssdr::vector<gr_complex> d_Prompt_Data;
00137     volk_gnssssdr::vector<gr_complex> d_Prompt_buffer;
00138
00139     boost::circular_buffer<float> d_dll_filt_history;
00140     boost::circular_buffer<std::pair<double, double>> d_code_ph_history;
00141     boost::circular_buffer<std::pair<double, double>> d_carr_ph_history;
00142     boost::circular_buffer<gr_complex> d_Prompt_circular_buffer;
00143
00144     std::string d_systemName;
00145     std::string d_signal_type;
00146     std::string d_secondary_code_string;
00147     std::string d_data_secondary_code_string;
00148     std::string d_signal_pretty_name;
00149     std::string d_dump_filename;
00150
00151     std::ofstream d_dump_file;
00152
00153     std::shared_ptr<Fpga_Multicorrelator_8sc> d_multicorrelator_fpga;
00154
00155     boost::condition_variable d_m_condition;
00156
00157     boost::mutex d_mutex;

```

```

00155
00156     const size_t int_type_hash_code = typeid(int).hash_code();
00157
00158     double d_signal_carrier_freq;
00159     double d_code_period;
00160     double d_code_chip_rate;
00161     double d_code_phase_step_chips;
00162     double d_code_phase_rate_step_chips;
00163     double d_carrier_phase_step_rad;
00164     double d_carrier_phase_rate_step_rad;
00165     double d_acq_code_phase_samples;
00166     double d_acq_carrier_doppler_hz;
00167     double d_rem_code_phase_samples;
00168     double d_rem_code_phase_samples_prev;
00169     double d_current_correlation_time_s;
00170     double d_carr_phase_error_hz;
00171     double d_carr_freq_error_hz;
00172     double d_carr_error_filt_hz;
00173     double d_code_error_chips;
00174     double d_code_error_filt_chips;
00175     double d_code_freq_chips;
00176     double d_carrier_doppler_hz;
00177     double d_acc_carrier_phase_rad;
00178     double d_rem_code_phase_chips;
00179     double d_T_chip_seconds;
00180     double d_T_prn_seconds;
00181     double d_T_prn_samples;
00182     double d_K_blk_samples;
00183     double d_carrier_lock_test;
00184     double d_CNO_SNV_dB_Hz;
00185     double d_carrier_lock_threshold;
00186
00187     gr_complex *d_Very_Early;
00188     gr_complex *d_Early;
00189     gr_complex *d_Prompt;
00190     gr_complex *d_Late;
00191     gr_complex *d_Very_Late;
00192
00193     gr_complex d_VE_accu;
00194     gr_complex d_E_accu;
00195     gr_complex d_P_accu;
00196     gr_complex d_P_accu_old;
00197     gr_complex d_L_accu;
00198     gr_complex d_VL_accu;
00199     gr_complex d_P_data_accu;
00200
00201     uint64_t d_sample_counter;
00202     uint64_t d_acq_sample_stamp;
00203     uint64_t d_sample_counter_next;
00204     int64_t d_bit_sync_target_epoch{};
00205
00206     float *d_prompt_data_shift;
00207     float d_rem_carr_phase_rad;
00208
00209     int32_t d_symbols_per_bit;
00210     int32_t d_state;
00211     int32_t d_extend_correlation_symbols_count;
00212     int32_t d_current_symbol;
00213     int32_t d_current_data_symbol;
00214     int32_t d_current_integration_length_samples;
00215     int32_t d_cn0_estimation_counter;
00216     int32_t d_carrier_lock_fail_counter;
00217     int32_t d_code_lock_fail_counter;
00218     int32_t d_correlation_length_ms;
00219     int32_t d_n_correlator_taps;
00220     int32_t d_next_integration_length_samples;
00221     int32_t d_extend_fpga_integration_periods;
00222
00223     uint32_t d_channel;
00224     uint32_t d_secondary_code_length;
00225     uint32_t d_data_secondary_code_length;
00226     uint32_t d_code_length_chips;
00227     uint32_t d_code_samples_per_chip; // All signals have 1 sample per chip code except Gal. E1 which
has 2 (CBOC disabled) or 12 (CBOC enabled)
00228     uint32_t d_fpga_integration_period;
00229     uint32_t d_current_fpga_integration_period;
00230
00231     bool d_veml;
00232     bool d_cloop;
00233     bool d_secondary;
00234     bool d_enable_extended_integration;
00235     bool d_dump;
00236     bool d_dump_mat;
00237     bool d_pull_in_transitory;
00238     bool d_corrected_doppler;
00239     bool d_interchange_iq;
00240     bool d_acc_carrier_phase_initialized;

```

```

00241     bool d_worker_is_done;
00242     bool d_extended_correlation_in_fpga;
00243     bool d_current_extended_correlation_in_fpga;
00244     bool d_stop_tracking;
00245     bool d_sc_demodulate_enabled;
00246     bool d_Flag_PLL_180_deg_phase_locked;
00247     bool d_use_histogram_bit_sync;
00248     bool d_wait_for_bit_edge{false};
00249 };
00250
00251
00252 /** \} */
00253 /** \} */
00254 #endif // GNSS_SDR_DLL_PLL_VEML_TRACKING_FPGA_H

```

13.578 galileo_e1_tcp_connector_tracking_cc.h File Reference

Interface of a TCP connector block based on code DLL + carrier PLL VEML (Very Early Minus Late) tracking block for Galileo E1 signals.

```

#include "cpu_multicorrelator.h"
#include "gnss_block_interface.h"
#include "gnss_synchro.h"
#include "tcp_communication.h"
#include <gnuradio/block.h>
#include <volk_gnssssdr/volk_gnssssdr_alloc.h>
#include <fstream>
#include <map>
#include <string>

```

Classes

- class [Galileo_E1_Tcp_Connector_Tracking_cc](#)

This class implements a code DLL + carrier PLL VEML (Very Early Minus Late) tracking block for Galileo E1 signals.

Typedefs

- using [galileo_e1_tcp_connector_tracking_cc_sptr](#) = gnss_shared_ptr<[Galileo_E1_Tcp_Connector_Tracking_cc](#)>

Functions

- [galileo_e1_tcp_connector_tracking_cc_sptr](#) **galileo_e1_tcp_connector_make_tracking_cc** (int64_t fs_in, uint32_t vector_length, bool dump, const std::string &dump_filename, float pll_bw_hz, float dll_bw_hz, float early_late_space_chips, float very_early_late_space_chips, size_t port_ch0)

13.578.1 Detailed Description

Interface of a TCP connector block based on code DLL + carrier PLL VEML (Very Early Minus Late) tracking block for Galileo E1 signals.

Author

David Pubill, 2012. [dpubill\(at\)cttc.es](mailto:dpubill@cttc.es) Luis Esteve, 2012. [luis\(at\)epsilon-formacion.com](mailto:luis(at)epsilon-formacion.com) Javier Arribas, 2011. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [galileo_e1_tcp_connector_tracking_cc.h](#).

13.579 galileo_e1_tcp_connector_tracking_cc.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_e1_tcp_connector_tracking_cc.h
00003  * \brief Interface of a TCP connector block based on code DLL + carrier PLL VEML (Very Early
00004  * Minus Late) tracking block for Galileo E1 signals
00005  * \author David Pubill, 2012. dpubill(at)cttc.es
00006  *         Luis Esteve, 2012. luis(at)epsilon-formacion.com
00007  *         Javier Arribas, 2011. jarribas(at)cttc.es
00008  *
00009  * Code DLL + carrier PLL according to the algorithms described in:
00010  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00011  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach,
00012  * Birkhauser, 2007
00013  *
00014  * -----
00015  *
00016  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00017  * This file is part of GNSS-SDR.
00018  *
00019  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00020  * SPDX-License-Identifier: GPL-3.0-or-later
00021  *
00022  * -----
00023  */
00024
00025 #ifndef GNSS_SDR_GALILEO_E1_TCP_CONNECTOR_TRACKING_CC_H
00026 #define GNSS_SDR_GALILEO_E1_TCP_CONNECTOR_TRACKING_CC_H
00027
00028 #include "cpu_multicorrelator.h"
00029 #include "gnss_block_interface.h"
00030 #include "gnss_synchro.h"
00031 #include "tcp_communication.h"
00032 #include <gnuradio/block.h>
00033 #include <volk_gnssssdr/volk_gnssssdr_alloc.h> // for volk_gnssssdr::vector
00034 #include <fstream>
00035 #include <map>
00036 #include <string>
00037
00038 /** \addtogroup Tracking
00039  * \{ */
00040 /** \addtogroup Tracking_gnuradio_blocks
00041  * \{ */
00042
00043
00044 class Galileo_E1_Tcp_Connector_Tracking_cc;
00045
00046 using galileo_e1_tcp_connector_tracking_cc_sptr =
00047     gnss_shared_ptr<Galileo_E1_Tcp_Connector_Tracking_cc>;
00048
00049 galileo_e1_tcp_connector_tracking_cc_sptr
00050 galileo_e1_tcp_connector_make_tracking_cc(
00051     int64_t fs_in, uint32_t vector_length,
00052     bool dump,
00053     const std::string &dump_filename,
00054     float pll_bw_hz,
00055     float dll_bw_hz,
00056     float early_late_space_chips,
00057     float very_early_late_space_chips,
00058     size_t port_ch0);
00059
00060 /*!
00061  * \brief This class implements a code DLL + carrier PLL VEML (Very Early
00062  * Minus Late) tracking block for Galileo E1 signals
00063  */
00064 class Galileo_E1_Tcp_Connector_Tracking_cc : public gr::block
00065 {
00066 public:
00067     ~Galileo_E1_Tcp_Connector_Tracking_cc();
00068
00069     void set_channel(uint32_t channel);
00070     void set_gnss_synchro(Gnss_Synchro *p_gnss_synchro);
00071     void start_tracking();
00072
00073     int general_work(int noutput_items, gr_vector_int &ninput_items,
00074         gr_vector_const_void_star &input_items, gr_vector_void_star &output_items);
00075
00076     void forecast(int noutput_items, gr_vector_int &ninput_items_required);
00077 private:
00078     friend galileo_e1_tcp_connector_tracking_cc_sptr
00079     galileo_e1_tcp_connector_make_tracking_cc(
00080         int64_t fs_in, uint32_t vector_length,
00081         bool dump,
00082         const std::string &dump_filename,

```



```

00083         float pll_bw_hz,
00084         float dll_bw_hz,
00085         float early_late_space_chips,
00086         float very_early_late_space_chips,
00087         size_t port_ch0);
00088
00089     Galileo_E1_Tcp_Connector_Tracking_cc(
00090         int64_t fs_in, uint32_t vector_length,
00091         bool dump,
00092         const std::string &dump_filename,
00093         float pll_bw_hz,
00094         float dll_bw_hz,
00095         float early_late_space_chips,
00096         float very_early_late_space_chips,
00097         size_t port_ch0);
00098
00099     void update_local_code();
00100
00101     void update_local_carrier();
00102
00103     // tracking configuration vars
00104     uint32_t d_vector_length;
00105     bool d_dump;
00106
00107     Gnss_Synchro *d_acquisition_gnss_synchro;
00108     uint32_t d_channel;
00109
00110     int64_t d_fs_in;
00111
00112     int32_t d_correlation_length_samples;
00113     int32_t d_n_correlator_taps;
00114     float d_early_late_spc_chips;
00115     float d_very_early_late_spc_chips;
00116
00117     volk_gnssssdr::vector<gr_complex> d_ca_code;
00118
00119     gr_complex *d_Very_Early;
00120     gr_complex *d_Early;
00121     gr_complex *d_Prompt;
00122     gr_complex *d_Late;
00123     gr_complex *d_Very_Late;
00124
00125     // remaining code phase and carrier phase between tracking loops
00126     double d_rem_code_phase_samples;
00127     float d_next_rem_code_phase_samples;
00128     float d_rem_carr_phase_rad;
00129
00130     // acquisition
00131     float d_acq_code_phase_samples;
00132     float d_acq_carrier_doppler_hz;
00133
00134     // correlator
00135     volk_gnssssdr::vector<float> d_local_code_shift_chips;
00136     volk_gnssssdr::vector<gr_complex> d_correlator_outs;
00137     Cpu_Multicorrelator multicorrelator_cpu;
00138
00139     // tracking vars
00140     double d_code_freq_chips;
00141     float d_carrier_doppler_hz;
00142     float d_acc_carrier_phase_rad;
00143     float d_acc_code_phase_secs;
00144     float d_code_phase_samples;
00145     size_t d_port_ch0;
00146     size_t d_port;
00147     int32_t d_listen_connection;
00148     float d_control_id;
00149     Tcp_Communication d_tcp_com;
00150
00151     // PRN period in samples
00152     int32_t d_current_prn_length_samples;
00153     int32_t d_next_prn_length_samples;
00154
00155     // processing samples counters
00156     uint64_t d_sample_counter;
00157     uint64_t d_acq_sample_stamp;
00158
00159     // CN0 estimation and lock detector
00160     int32_t d_cn0_estimation_counter;
00161     volk_gnssssdr::vector<gr_complex> d_Prompt_buffer;
00162     float d_carrier_lock_test;
00163     float d_CN0_SNV_dB_Hz;
00164     float d_carrier_lock_threshold;
00165     int32_t d_carrier_lock_fail_counter;
00166
00167     // control vars
00168     bool d_enable_tracking;
00169     bool d_pull_in;

```

```

00170
00171 // file dump
00172 std::string d_dump_filename;
00173 std::ofstream d_dump_file;
00174
00175 std::map<std::string, std::string> systemName;
00176 std::string sys;
00177 };
00178
00179
00180 /** \} */
00181 /** \} */
00182 #endif // GNSS_SDR_GALILEO_E1_TCP_CONNECTOR_TRACKING_CC_H

```

13.580 gps_l1_ca_dll_pll_tracking_gpu_cc.h File Reference

Implementation of a code DLL + carrier PLL tracking block, GPU ACCELERATED.

```

#include "cuda_multicorrelator.h"
#include "gnss_block_interface.h"
#include "gnss_synchro.h"
#include "tracking_2nd_DLL_filter.h"
#include "tracking_FLL_PLL_filter.h"
#include <gnuradio/block.h>
#include <fstream>
#include <map>
#include <string>
#include <vector>

```

Classes

- class [Gps_L1_Ca_Dll_Pll_Tracking_GPU_cc](#)
This class implements a DLL + PLL tracking loop block.

Typedefs

- using [gps_l1_ca_dll_pll_tracking_gpu_cc_sptr](#) = gnss_shared_ptr<[Gps_L1_Ca_Dll_Pll_Tracking_GPU_cc](#)>

Functions

- [gps_l1_ca_dll_pll_tracking_gpu_cc_sptr](#) [gps_l1_ca_dll_pll_make_tracking_gpu_cc](#) (int64_t fs_in, uint32_t vector_length, bool dump, std::string dump_filename, float pll_bw_hz, float dll_bw_hz, float early_↵late_space_chips)

13.580.1 Detailed Description

Implementation of a code DLL + carrier PLL tracking block, GPU ACCELERATED.

Author

Javier Arribas, 2015. jarribas(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [gps_l1_ca_dll_pll_tracking_gpu_cc.h](#).

13.581 gps_l1_ca_dll_pll_tracking_gpu_cc.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file gps_l1_ca_dll_pll_tracking_gpu_cc.h

```

```

00003  * \brief Implementation of a code DLL + carrier PLL tracking block, GPU ACCELERATED
00004  * \author Javier Arribas, 2015. jarribas(at)cttc.es
00005  *
00006  * Code DLL + carrier PLL according to the algorithms described in:
00007  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00008  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach,
00009  * Birkhauser, 2007
00010  *
00011  * -----
00012  *
00013  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014  * This file is part of GNSS-SDR.
00015  *
00016  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022 #ifndef GNSS_SDR_GPS_L1_CA_DLL_PLL_TRACKING_GPU_CC_H
00023 #define GNSS_SDR_GPS_L1_CA_DLL_PLL_TRACKING_GPU_CC_H
00024
00025 #include "cuda_multicorrelator.h"
00026 #include "gnss_block_interface.h"
00027 #include "gnss_synchro.h"
00028 #include "tracking_2nd_DLL_filter.h"
00029 #include "tracking_FLL_PLL_filter.h"
00030 #include <gnuradio/block.h>
00031 #include <fstream>
00032 #include <map>
00033 #include <string>
00034 #include <vector>
00035
00036 /** \addtogroup Tracking
00037  * \{ */
00038 /** \addtogroup Tracking_gnuradio_blocks
00039  * \{ */
00040
00041
00042 class Gps_L1_Ca_Dll_Pll_Tracking_GPU_cc;
00043
00044 using gps_l1_ca_dll_pll_tracking_gpu_cc_sptr = gnss_shared_ptr<Gps_L1_Ca_Dll_Pll_Tracking_GPU_cc>;
00045
00046 gps_l1_ca_dll_pll_tracking_gpu_cc_sptr
00047 gps_l1_ca_dll_pll_make_tracking_gpu_cc(
00048     int64_t fs_in,
00049     uint32_t vector_length,
00050     bool dump,
00051     std::string dump_filename,
00052     float pll_bw_hz,
00053     float dll_bw_hz,
00054     float early_late_space_chips);
00055
00056
00057 /*!
00058  * \brief This class implements a DLL + PLL tracking loop block
00059  */
00060 class Gps_L1_Ca_Dll_Pll_Tracking_GPU_cc : public gr::block
00061 {
00062 public:
00063     ~Gps_L1_Ca_Dll_Pll_Tracking_GPU_cc();
00064
00065     void set_channel(uint32_t channel);
00066     void set_gnss_synchro(Gnss_Synchro *p_gnss_synchro);
00067     void start_tracking();
00068
00069     int general_work(int noutput_items, gr_vector_int &ninput_items,
00070         gr_vector_const_void_star &input_items, gr_vector_void_star &output_items);
00071
00072     void forecast(int noutput_items, gr_vector_int &ninput_items_required);
00073
00074 private:
00075     friend gps_l1_ca_dll_pll_tracking_gpu_cc_sptr
00076     gps_l1_ca_dll_pll_make_tracking_gpu_cc(
00077         int64_t fs_in,
00078         uint32_t vector_length,
00079         bool dump,
00080         std::string dump_filename,
00081         float pll_bw_hz,
00082         float dll_bw_hz,
00083         float early_late_space_chips);
00084
00085     Gps_L1_Ca_Dll_Pll_Tracking_GPU_cc(
00086         int64_t fs_in,
00087         uint32_t vector_length,
00088         bool dump,
00089         std::string dump_filename,

```

```

00090         float pll_bw_hz,
00091         float dll_bw_hz,
00092         float early_late_space_chips);
00093 void update_local_code();
00094 void update_local_carrier();
00095 void check_carrier_phase_coherent_initialization();
00096
00097 // PLL and DLL filter library
00098 Tracking_2nd_DLL_filter d_code_loop_filter;
00099 Tracking_FLL_PLL_filter d_carrier_loop_filter;
00100
00101 Gnss_Synchro *d_acquisition_gnss_synchro;
00102
00103 std::vector<gr_complex> d_Prompt_buffer;
00104
00105 // file dump
00106 std::string d_dump_filename;
00107 std::ofstream d_dump_file;
00108
00109 std::map<std::string, std::string> systemName;
00110 std::string sys;
00111
00112 // tracking configuration vars
00113 int64_t d_if_freq;
00114 int64_t d_fs_in;
00115 double d_early_late_spc_chips;
00116 uint32_t d_vector_length;
00117 uint32_t d_channel;
00118 int32_t d_n_correlator_taps;
00119
00120 // GPU HOST PINNED MEMORY IN/OUT VECTORS
00121 cuda_multicorrelator *multicorrelator_gpu;
00122 gr_complex *in_gpu;
00123 gr_complex *d_correlator_outs;
00124 gr_complex *d_ca_code;
00125 float *d_local_code_shift_chips;
00126
00127 gr_complex *d_Early;
00128 gr_complex *d_Prompt;
00129 gr_complex *d_Late;
00130
00131 // remaining code phase and carrier phase between tracking loops
00132 double d_rem_code_phase_samples;
00133 double d_rem_code_phase_chips;
00134 double d_rem_carrier_phase_rad;
00135
00136 // acquisition
00137 double d_acq_code_phase_samples;
00138 double d_acq_carrier_doppler_hz;
00139
00140 // tracking vars
00141 double d_code_freq_chips;
00142 double d_code_phase_step_chips;
00143 double d_carrier_doppler_hz;
00144 double d_carrier_phase_step_rad;
00145 double d_acc_carrier_phase_cycles;
00146 double d_code_phase_samples;
00147 double d_pll_to_dll_assist_secs_Ti;
00148
00149 // Integration period in samples
00150 int32_t d_correlation_length_samples;
00151
00152 // processing samples counters
00153 uint64_t d_sample_counter;
00154 uint64_t d_acq_sample_stamp;
00155
00156 // CN0 estimation and lock detector
00157 double d_carrier_lock_test;
00158 double d_CN0_SNV_dB_Hz;
00159 double d_carrier_lock_threshold;
00160 int32_t d_carrier_lock_fail_counter;
00161 int32_t d_cn0_estimation_counter;
00162
00163 // control vars
00164 bool d_acc_carrier_phase_initialized;
00165 bool d_enable_tracking;
00166 bool d_pull_in;
00167 bool d_dump;
00168 };
00169
00170
00171 /** \} */
00172 /** \} */
00173 #endif // GNSS_SDR_GPS_L1_CA_DLL_PLL_TRACKING_GPU_CC_H

```

13.582 gps_l1_ca_gaussian_tracking_cc.h File Reference

Interface of a processing block of a DLL + Kalman carrier tracking loop for GPS L1 C/A signals.

```
#include "bayesian_estimation.h"
#include "cpu_multicorrelator_real_codes.h"
#include "gnss_block_interface.h"
#include "gnss_synchro.h"
#include "tracking_2nd_DLL_filter.h"
#include "tracking_2nd_PLL_filter.h"
#include <armadillo>
#include <gnuradio/block.h>
#include <volk_gnssssdr/volk_gnssssdr_alloc.h>
#include <fstream>
#include <map>
#include <string>
```

Classes

- class [Gps_L1_Ca_Gaussian_Tracking_cc](#)
This class implements a DLL + PLL tracking loop block.

Typedefs

- using [gps_l1_ca_gaussian_tracking_cc_sptr](#) = gnss_shared_ptr<[Gps_L1_Ca_Gaussian_Tracking_cc](#)>

Functions

- [gps_l1_ca_gaussian_tracking_cc_sptr](#) [gps_l1_ca_gaussian_make_tracking_cc](#) (uint32_t order, int64_t fs_in, uint32_t vector_length, bool dump, const std::string &dump_filename, float dll_bw_hz, float early_late_space_chips, bool bce_run, uint32_t bce_ptrans, uint32_t bce_strans, int32_t bce_nu, int32_t bce_kappa)

13.582.1 Detailed Description

Interface of a processing block of a DLL + Kalman carrier tracking loop for GPS L1 C/A signals.

Author

Javier Arribas, 2018. jarribas(at)cttc.es

Jordi Vila-Valls 2018. jvila(at)cttc.es

Carles Fernandez-Prades 2018. cfernandez(at)cttc.es

Reference: J. Vila-Valls, P. Closas, M. Navarro and C. Fernandez-Prades, "Are PLLs Dead? A Tutorial on Kalman Filter-based Techniques for Digital Carrier Synchronization", IEEE Aerospace and Electronic Systems Magazine, Vol. 32, No. 7, pp. 28–45, July 2017. DOI: 10.1109/MAES.2017.150260

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Definition in file [gps_l1_ca_gaussian_tracking_cc.h](#).

13.583 gps_l1_ca_gaussian_tracking_cc.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gps_l1_ca_gaussian_tracking_cc.h
00003  * \brief Interface of a processing block of a DLL + Kalman carrier
00004  * tracking loop for GPS L1 C/A signals
00005  * \author Javier Arribas, 2018. jarribas(at)cttc.es
00006  * \author Jordi Vila-Valls 2018. jvila(at)cttc.es
00007  * \author Carles Fernandez-Prades 2018. cfernandez(at)cttc.es
00008  *
```

```

00009  * Reference:
00010  * J. Vila-Valls, P. Closas, M. Navarro and C. Fernandez-Prades,
00011  * "Are PLLs Dead? A Tutorial on Kalman Filter-based Techniques for Digital
00012  * Carrier Synchronization", IEEE Aerospace and Electronic Systems Magazine,
00013  * Vol. 32, No. 7, pp. 28-45, July 2017. DOI: 10.1109/MAES.2017.150260
00014  *
00015  * -----
00016  *
00017  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00018  * This file is part of GNSS-SDR.
00019  *
00020  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00021  * SPDX-License-Identifier: GPL-3.0-or-later
00022  *
00023  * -----
00024  */
00025
00026 #ifndef GNSS_SDR_GPS_L1_CA_GAUSSIAN_TRACKING_CC_H
00027 #define GNSS_SDR_GPS_L1_CA_GAUSSIAN_TRACKING_CC_H
00028
00029 #if ARMA_NO_BOUND_CHECKING
00030 #define ARMA_NO_DEBUG 1
00031 #endif
00032
00033 #include "bayesian_estimation.h"
00034 #include "cpu_multicorrelator_real_codes.h"
00035 #include "gnss_block_interface.h"
00036 #include "gnss_synchro.h"
00037 #include "tracking_2nd_DLL_filter.h"
00038 #include "tracking_2nd_PLL_filter.h"
00039 #include <armadillo>
00040 #include <gnuradio/block.h>
00041 #include <volk_gnssssdr/volk_gnssssdr_alloc.h> // for volk_gnssssdr::vector
00042 #include <fstream>
00043 #include <map>
00044 #include <string>
00045
00046 /** \addtogroup Tracking
00047  * \{ */
00048 /** \addtogroup Tracking_gnuradio_blocks
00049  * \{ */
00050
00051
00052 class Gps_L1_Ca_Gaussian_Tracking_cc;
00053
00054 using gps_l1_ca_gaussian_tracking_cc_sptr = gnss_shared_ptr<Gps_L1_Ca_Gaussian_Tracking_cc>;
00055
00056 gps_l1_ca_gaussian_tracking_cc_sptr
00057 gps_l1_ca_gaussian_make_tracking_cc(uint32_t order,
00058     int64_t fs_in,
00059     uint32_t vector_length,
00060     bool dump,
00061     const std::string& dump_filename,
00062     float dll_bw_hz,
00063     float early_late_space_chips,
00064     bool bce_run,
00065     uint32_t bce_ptrans,
00066     uint32_t bce_strans,
00067     int32_t bce_nu,
00068     int32_t bce_kappa);
00069
00070
00071 /*!
00072  * \brief This class implements a DLL + PLL tracking loop block
00073  */
00074 class Gps_L1_Ca_Gaussian_Tracking_cc : public gr::block
00075 {
00076 public:
00077     ~Gps_L1_Ca_Gaussian_Tracking_cc();
00078
00079     void set_channel(uint32_t channel);
00080     void set_gnss_synchro(Gnss_Synchro* p_gnss_synchro);
00081     void start_tracking();
00082
00083     int general_work(int noutput_items, gr_vector_int& ninput_items,
00084         gr_vector_const_void_star& input_items, gr_vector_void_star& output_items);
00085
00086     void forecast(int noutput_items, gr_vector_int& ninput_items_required);
00087 private:
00088     friend gps_l1_ca_gaussian_tracking_cc_sptr
00089     gps_l1_ca_gaussian_make_tracking_cc(uint32_t order,
00090         int64_t fs_in,
00091         uint32_t vector_length,
00092         bool dump,
00093         const std::string& dump_filename,
00094         float dll_bw_hz,

```

```

00096         float early_late_space_chips,
00097         bool bce_run,
00098         uint32_t bce_ptrans,
00099         uint32_t bce_strans,
00100         int32_t bce_nu,
00101         int32_t bce_kappa);
00102
00103     Gps_L1_Ca_Gaussian_Tracking_cc(uint32_t order,
00104         int64_t fs_in,
00105         uint32_t vector_length,
00106         bool dump,
00107         const std::string& dump_filename,
00108         float dll_bw_hz,
00109         float early_late_space_chips,
00110         bool bce_run,
00111         uint32_t bce_ptrans,
00112         uint32_t bce_strans,
00113         int32_t bce_nu,
00114         int32_t bce_kappa);
00115
00116     int32_t save_matfile();
00117
00118     // tracking configuration vars
00119     uint32_t d_order;
00120     uint32_t d_vector_length;
00121     bool d_dump;
00122
00123     Gnss_Synchro* d_acquisition_gnss_synchro;
00124     uint32_t d_channel;
00125
00126     int64_t d_fs_in;
00127
00128     double d_early_late_spc_chips;
00129
00130     // remaining code phase and carrier phase between tracking loops
00131     double d_rem_code_phase_samples;
00132     double d_rem_code_phase_chips;
00133     float d_rem_carr_phase_rad;
00134
00135     // Kalman filter variables
00136     arma::mat kf_P_x_ini; // initial state error covariance matrix
00137     arma::mat kf_P_x; // state error covariance matrix
00138     arma::mat kf_P_x_pre; // Predicted state error covariance matrix
00139     arma::mat kf_P_y; // innovation covariance matrix
00140
00141     arma::mat kf_F; // state transition matrix
00142     arma::mat kf_H; // system matrix
00143     arma::mat kf_R; // measurement error covariance matrix
00144     arma::mat kf_Q; // system error covariance matrix
00145
00146     arma::colvec kf_x; // state vector
00147     arma::colvec kf_x_pre; // predicted state vector
00148     arma::colvec kf_y; // measurement vector
00149     arma::mat kf_K; // Kalman gain matrix
00150
00151     // Gaussian estimator
00152     Bayesian_estimator bayes_estimator;
00153     arma::mat kf_R_est; // measurement error covariance
00154     uint32_t bayes_ptrans;
00155     uint32_t bayes_strans;
00156     int32_t bayes_nu;
00157     int32_t bayes_kappa;
00158
00159     bool bayes_run;
00160     uint32_t kf_iter;
00161
00162     // PLL and DLL filter library
00163     Tracking_2nd_DLL_filter d_code_loop_filter;
00164     Tracking_2nd_PLL_filter d_carrier_loop_filter;
00165
00166     // acquisition
00167     double d_acq_carrier_doppler_step_hz{};
00168     double d_acq_code_phase_samples;
00169     double d_acq_carrier_doppler_hz;
00170     // correlator
00171     int32_t d_n_correlator_taps;
00172     volk_gnssdr::vector<float> d_ca_code;
00173     volk_gnssdr::vector<float> d_local_code_shift_chips;
00174     volk_gnssdr::vector<gr_complex> d_correlator_outs;
00175     Cpu_Multicorrelator_Real_Codes multicorrelator_cpu;
00176
00177     // tracking vars
00178     double d_code_freq_chips;
00179     double d_code_phase_step_chips;
00180     double d_code_phase_rate_step_chips;
00181     double d_carrier_doppler_hz;
00182     double d_carrier_dopplerrate_hz2;

```

```

00183     double d_carrier_phase_step_rad;
00184     double d_acc_carrier_phase_rad;
00185     double d_carr_phase_error_rad{};
00186     double d_carr_phase_sigma2;
00187     double d_code_phase_samples;
00188     double code_error_chips;
00189     double code_error_filt_chips;
00190
00191     // PRN period in samples
00192     int32_t d_current_prn_length_samples;
00193
00194     // processing samples counters
00195     uint64_t d_sample_counter;
00196     uint64_t d_acq_sample_stamp;
00197
00198     // CN0 estimation and lock detector
00199     int32_t d_cn0_estimation_counter;
00200     volk_gnssdr::vector<gr_complex> d_Prompt_buffer;
00201     double d_carrier_lock_test;
00202     double d_CN0_SNV_dB_Hz;
00203     double d_carrier_lock_threshold;
00204     int32_t d_carrier_lock_fail_counter;
00205
00206     // control vars
00207     bool d_enable_tracking;
00208     bool d_pull_in;
00209
00210     // file dump
00211     std::string d_dump_filename;
00212     std::ofstream d_dump_file;
00213
00214     std::map<std::string, std::string> systemName;
00215     std::string sys;
00216 };
00217
00218
00219 /** \} */
00220 /** \} */
00221 #endif // GNSS_SDR_GPS_L1_CA_GAUSSIAN_TRACKING_CC_H

```

13.584 gps_l1_ca_tcp_connector_tracking_cc.h File Reference

Interface of a TCP connector block based on code DLL + carrier PLL.

```

#include "cpu_multicorrelator.h"
#include "gnss_block_interface.h"
#include "gnss_synchro.h"
#include "tcp_communication.h"
#include <gnuradio/block.h>
#include <volk_gnssdr/volk_gnssdr_alloc.h>
#include <fstream>
#include <map>
#include <string>

```

Classes

- class [Gps_L1_Ca_Tcp_Connector_Tracking_cc](#)
This class implements a DLL + PLL tracking loop block.

Typedefs

- using [gps_l1_ca_tcp_connector_tracking_cc_sptr](#) = gnss_shared_ptr<[Gps_L1_Ca_Tcp_Connector_Tracking_cc](#)>

Functions

- gps_l1_ca_tcp_connector_tracking_cc_sptr [gps_l1_ca_tcp_connector_make_tracking_cc](#) (int64_t fs_in, uint32_t vector_length, bool dump, const std::string &dump_filename, float early_late_space_chips, size_t port_ch0)

13.584.1 Detailed Description

Interface of a TCP connector block based on code DLL + carrier PLL.

Author

David Pubill, 2012. dpubill(at)cttc.es Javier Arribas, 2011. jarribas(at)cttc.es

Code DLL + carrier PLL according to the algorithms described in: K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007
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Definition in file [gps_l1_ca_tcp_connector_tracking_cc.h](#).

13.585 gps_l1_ca_tcp_connector_tracking_cc.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gps_l1_ca_tcp_connector_tracking_cc.h
00003  * \brief Interface of a TCP connector block based on code DLL + carrier PLL
00004  * \author David Pubill, 2012. dpubill(at)cttc.es
00005  *          Javier Arribas, 2011. jarribas(at)cttc.es
00006  *
00007  * Code DLL + carrier PLL according to the algorithms described in:
00008  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H.Jensen,
00009  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach,
00010  * Birkhauser, 2007
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.
00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_GPS_L1_CA_TCP_CONNECTOR_TRACKING_CC_H
00024 #define GNSS_SDR_GPS_L1_CA_TCP_CONNECTOR_TRACKING_CC_H
00025
00026 #include "cpu_multicorrelator.h"
00027 #include "gnss_block_interface.h"
00028 #include "gnss_synchro.h"
00029 #include "tcp_communication.h"
00030 #include <gnuradio/block.h>
00031 #include <volk_gnssssdr/volk_gnssssdr_alloc.h> // for volk_gnssssdr::vector
00032 #include <fstream>
00033 #include <map>
00034 #include <string>
00035
00036 /** \addtogroup Tracking
00037  * \{ */
00038 /** \addtogroup Tracking_gnuradio_blocks
00039  * \{ */
00040
00041
00042 class Gps_L1_Ca_Tcp_Connector_Tracking_cc;
00043
00044 using gps_l1_ca_tcp_connector_tracking_cc_sptr = gnss_shared_ptr<Gps_L1_Ca_Tcp_Connector_Tracking_cc>;
00045
00046 gps_l1_ca_tcp_connector_tracking_cc_sptr
00047 gps_l1_ca_tcp_connector_make_tracking_cc(
00048     int64_t fs_in, uint32_t vector_length,
00049     bool dump,
00050     const std::string &dump_filename,
00051     float early_late_space_chips,
00052     size_t port_ch0);
00053
00054
00055 /*!
00056  * \brief This class implements a DLL + PLL tracking loop block
00057  */
00058 class Gps_L1_Ca_Tcp_Connector_Tracking_cc : public gr::block
00059 {
00060 public:
00061     ~Gps_L1_Ca_Tcp_Connector_Tracking_cc();
00062
00063     void set_channel(uint32_t channel);
00064     void set_gnss_synchro(Gnss_Synchro *p_gnss_synchro);
```

```

00065     void start_tracking();
00066
00067     /*
00068     * \brief just like gr_block::general_work, only this arranges to call consume_each for you
00069     *
00070     * The user must override work to define the signal processing code
00071     */
00072     int general_work(int noutput_items, gr_vector_int &ninput_items,
00073                     gr_vector_const_void_star &input_items, gr_vector_void_star &output_items);
00074
00075     void forecast(int noutput_items, gr_vector_int &ninput_items_required);
00076
00077 private:
00078     friend gps_ll_ca_tcp_connector_tracking_cc_sptr
00079     gps_ll_ca_tcp_connector_make_tracking_cc(
00080         int64_t fs_in, uint32_t vector_length,
00081         bool dump,
00082         const std::string &dump_filename,
00083         float early_late_space_chips,
00084         size_t port_ch0);
00085
00086     Gps_Ll_Ca_Tcp_Connector_Tracking_cc(
00087         int64_t fs_in, uint32_t vector_length,
00088         bool dump,
00089         const std::string &dump_filename,
00090         float early_late_space_chips,
00091         size_t port_ch0);
00092
00093     volk_gnssssdr::vector<gr_complex> d_ca_code;
00094     // correlator
00095     volk_gnssssdr::vector<float> d_local_code_shift_chips;
00096     volk_gnssssdr::vector<gr_complex> d_correlator_outs;
00097     volk_gnssssdr::vector<gr_complex> d_Prompt_buffer;
00098     Cpu_Multicorrelator multicorrelator_cpu;
00099     Tcp_Communication d_tcp_com;
00100     Gnss_Synchro *d_acquisition_gnss_synchro;
00101     // tracking configuration vars
00102
00103     gr_complex *d_Early;
00104     gr_complex *d_Prompt;
00105     gr_complex *d_Late;
00106
00107     // file dump
00108     std::string d_dump_filename;
00109     std::ofstream d_dump_file;
00110
00111     std::map<std::string, std::string> systemName;
00112     std::string sys;
00113
00114     double d_early_late_spc_chips;
00115     double d_code_phase_step_chips;
00116     double d_rem_code_phase_samples;
00117     double d_next_rem_code_phase_samples;
00118     double d_code_freq_hz;
00119     double d_carrier_doppler_hz;
00120     double d_acc_carrier_phase_rad;
00121     double d_code_phase_samples;
00122     double d_sample_counter_seconds;
00123
00124     int64_t d_fs_in;
00125     uint64_t d_sample_counter;
00126     uint64_t d_acq_sample_stamp;
00127
00128     size_t d_port_ch0;
00129     size_t d_port;
00130
00131     uint32_t d_vector_length;
00132     uint32_t d_channel;
00133
00134     int32_t d_correlation_length_samples;
00135     int32_t d_n_correlator_taps;
00136     int32_t d_listen_connection;
00137     int32_t d_current_prn_length_samples;
00138     int32_t d_next_prn_length_samples;
00139     int32_t d_cn0_estimation_counter;
00140     int32_t d_carrier_lock_fail_counter;
00141
00142     float d_rem_carr_phase_rad;
00143     float d_acq_code_phase_samples;
00144     float d_acq_carrier_doppler_hz;
00145     float d_carrier_lock_test;
00146     float d_CN0_SNV_dB_Hz;
00147     float d_carrier_lock_threshold;
00148     float d_control_id;
00149
00150     bool d_enable_tracking;
00151     bool d_pull_in;

```

```

00152     bool d_dump;
00153 };
00154
00155
00156 /** \} */
00157 /** \} */
00158 #endif // GNSS_SDR_GPS_L1_CA_TCP_CONNECTOR_TRACKING_CC_H

```

13.586 kf_tracking.h

```

00001 /*!
00002  * \file kf_tracking.cc
00003  * \brief Implementation of a Kalman filter based tracking with optional Vector
00004  * Tracking Loop message receiver block.
00005  * \author Javier Arribas, 2020. jarribas(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00010  *
00011  * GNSS-SDR is a software defined Global Navigation
00012  * Satellite Systems receiver
00013  *
00014  * This file is part of GNSS-SDR.
00015  *
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_KF_TRACKING_H
00022 #define GNSS_SDR_KF_TRACKING_H
00023
00024 #if ARMA_NO_BOUND_CHECKING
00025 #define ARMA_NO_DEBUG 1
00026 #endif
00027
00028 #include "cpu_multicorrelator_real_codes.h"
00029 #include "exponential_smoother.h"
00030 #include "gnss_block_interface.h"
00031 #include "gnss_time.h" // for timetags produced by File_Timestamp_Signal_Source
00032 #include "kf_conf.h"
00033 #include "tracking_FLL_PLL_filter.h" // for PLL/FLL filter
00034 #include "tracking_loop_filter.h" // for DLL filter
00035 #include <armadillo>
00036 #include <boost/circular_buffer.hpp>
00037 #include <gnuradio/block.h> // for block
00038 #include <gnuradio/gr_complex.h> // for gr_complex
00039 #include <gnuradio/types.h> // for gr_vector_int, gr_vector...
00040 #include <pmt/pmt.h> // for pmt_t
00041 #include <volk_gnssssdr/volk_gnssssdr_alloc.h> // for volk_gnssssdr::vector
00042 #include <cstring> // for size_t
00043 #include <stdint.h> // for int32_t
00044 #include <fstream> // for ofstream
00045 #include <memory>
00046 #include <string> // for string
00047 #include <typeinfo> // for typeid
00048 #include <utility> // for pair
00049
00050 class Gnss_Synchro;
00051 class kf_tracking;
00052
00053 using kf_tracking_sptr = gnss_shared_ptr<kf_tracking>;
00054
00055 kf_tracking_sptr kf_make_tracking(const Kf_Conf &conf_);
00056
00057 /*!
00058  * \brief This class implements a code DLL + carrier PLL tracking block.
00059  */
00060 class kf_tracking : public gr::block
00061 {
00062 public:
00063     ~kf_tracking();
00064
00065     void set_channel(uint32_t channel);
00066     void set_gnss_synchro(Gnss_Synchro *p_gnss_synchro);
00067     void start_tracking();
00068     void stop_tracking();
00069
00070     int general_work(int noutput_items, gr_vector_int &ninput_items,
00071         gr_vector_const_void_star &input_items, gr_vector_void_star &output_items);
00072
00073     void forecast(int noutput_items, gr_vector_int &ninput_items_required);
00074

```

```

00075 private:
00076     friend kf_tracking_sptr kf_make_tracking(const Kf_Conf &conf_);
00077     explicit kf_tracking(const Kf_Conf &conf_);
00078
00079     void init_kf(double acq_code_phase_chips, double acq_doppler_hz);
00080     void update_kf_narrow_integration_time();
00081     void update_kf_cn0(double current_cn0_dbhz);
00082     void run_Kf();
00083
00084     void msg_handler_telemetry_to_trk(const pmt::pmt_t &msg);
00085     void msg_handler_pvt_to_trk(const pmt::pmt_t &msg);
00086     void do_correlation_step(const gr_complex *input_samples);
00087
00088     void check_carrier_phase_coherent_initialization();
00089     void update_tracking_vars();
00090     void clear_tracking_vars();
00091     void save_correlation_results();
00092     void log_data();
00093     bool cn0_and_tracking_lock_status(double coh_integration_time_s);
00094     bool acquire_secondary();
00095     int32_t save_matfile() const;
00096
00097     Cpu_Multicorrelator_Real_Codes d_multicorrelator_cpu;
00098     Cpu_Multicorrelator_Real_Codes d_correlator_data_cpu; // for data channel
00099
00100     Kf_Conf d_trk_parameters;
00101
00102     Exponential_Smoother d_cn0_smoother;
00103     Exponential_Smoother d_carrier_lock_test_smoother;
00104
00105     Gnss_Synchro *d_acquisition_gnss_synchro;
00106
00107     volk_gnssssdr::vector<float> d_tracking_code;
00108     volk_gnssssdr::vector<float> d_data_code;
00109     volk_gnssssdr::vector<float> d_local_code_shift_chips;
00110     volk_gnssssdr::vector<gr_complex> d_correlator_outs;
00111     volk_gnssssdr::vector<gr_complex> d_Prompt_Data;
00112     volk_gnssssdr::vector<gr_complex> d_Prompt_buffer;
00113
00114     boost::circular_buffer<gr_complex> d_Prompt_circular_buffer;
00115     boost::circular_buffer<std::pair<double, double> d_code_ph_history;
00116     boost::circular_buffer<std::pair<double, double> d_carr_ph_history;
00117
00118     const size_t d_int_type_hash_code = typeid(int).hash_code();
00119
00120     // Kalman Filter class variables
00121     arma::mat d_F;
00122     arma::mat d_H;
00123     arma::mat d_R;
00124     arma::mat d_Q;
00125     arma::mat d_P_old_old;
00126     arma::mat d_P_new_old;
00127     arma::mat d_P_new_new;
00128     arma::vec d_x_old_old;
00129     arma::vec d_x_new_old;
00130     arma::vec d_x_new_new;
00131
00132     std::string d_secondary_code_string;
00133     std::string d_data_secondary_code_string;
00134     std::string d_systemName;
00135     std::string d_signal_type;
00136     std::string d_signal_pretty_name;
00137     std::string d_dump_filename;
00138
00139     std::ofstream d_dump_file;
00140
00141     gr_complex *d_Very_Early;
00142     gr_complex *d_Early;
00143     gr_complex *d_Prompt;
00144     gr_complex *d_Late;
00145     gr_complex *d_Very_Late;
00146
00147     gr_complex d_VE_accu;
00148     gr_complex d_E_accu;
00149     gr_complex d_P_accu;
00150     gr_complex d_P_accu_old;
00151     gr_complex d_L_accu;
00152     gr_complex d_VL_accu;
00153     gr_complex d_P_data_accu;
00154
00155     // nominal signal parameters
00156     double d_signal_carrier_freq;
00157     double d_code_period;
00158     double d_code_chip_rate;
00159
00160     // acquisition
00161     double d_acq_code_phase_samples;

```

```

00162     double d_acq_carrier_doppler_hz;
00163     double d_current_correlation_time_s;
00164
00165     // carrier and code discriminators output
00166     double d_carr_phase_error_disc_hz;
00167     double d_code_error_disc_chips;
00168
00169     // estimated parameters
00170     // code
00171     double d_code_error_kf_chips;
00172     double d_code_freq_kf_chips_s;
00173     // carrier
00174     double d_carrier_phase_kf_rad;
00175     double d_carrier_doppler_kf_hz;
00176     double d_carrier_doppler_rate_kf_hz_s;
00177
00178     double d_acc_carrier_phase_rad;
00179
00180     double d_T_chip_seconds;
00181     double d_T_prn_seconds;
00182     double d_T_prn_samples;
00183     double d_K_blk_samples;
00184     double d_carrier_lock_test;
00185     double d_CNO_SNV_dB_Hz;
00186     double d_carrier_lock_threshold;
00187
00188     // carrier NCO
00189     double d_carrier_phase_step_rad;
00190     double d_carrier_phase_rate_step_rad;
00191
00192     // code NCO
00193     double d_code_phase_step_chips;
00194     double d_code_phase_rate_step_chips;
00195     double d_rem_code_phase_chips;
00196     double d_rem_code_phase_samples;
00197
00198     double d_beta;
00199
00200     uint64_t d_sample_counter;
00201     uint64_t d_acq_sample_stamp;
00202
00203     float *d_prompt_data_shift;
00204     float d_rem_carr_phase_rad;
00205
00206     uint32_t d_channel;
00207     uint32_t d_secondary_code_length;
00208     uint32_t d_data_secondary_code_length;
00209
00210     int32_t d_symbols_per_bit;
00211     int32_t d_state;
00212     int32_t d_correlation_length_ms;
00213     int32_t d_n_correlator_taps;
00214     int32_t d_current_prn_length_samples;
00215     int32_t d_extend_correlation_symbols_count;
00216     int32_t d_current_symbol;
00217     int32_t d_current_data_symbol;
00218     int32_t d_cn0_estimation_counter;
00219     int32_t d_carrier_lock_fail_counter;
00220     int32_t d_code_lock_fail_counter;
00221     int32_t d_code_samples_per_chip; // All signals have 1 sample per chip code except Gal. E1 which
has 2 (CBOC disabled) or 12 (CBOC enabled)
00222     int32_t d_code_length_chips;
00223
00224     bool d_pull_in_transitory;
00225     bool d_corrected_doppler;
00226     bool d_interchange_iq;
00227     bool d_veml;
00228     bool d_cloop;
00229     bool d_secondary;
00230     bool d_dump;
00231     bool d_dump_mat;
00232     bool d_acc_carrier_phase_initialized;
00233     bool d_enable_extended_integration;
00234 };
00235
00236 #endif // GNSS_SDR_KF_TRACKING_H

```

13.587 bayesian_estimation.h File Reference

Interface of a library with Bayesian noise statistic estimation.

```

#include <armadillo>
#include <gnuradio/gr_complex.h>

```

Classes

- class [Bayesian_estimator](#)
[Bayesian_estimator](#) is an estimator of noise characteristics (i.e. mean, covariance)

13.587.1 Detailed Description

Interface of a library with Bayesian noise statistic estimation.

[Bayesian_estimator](#) is a Bayesian estimator which attempts to estimate the properties of a stochastic process based on a sequence of discrete samples of the sequence.

[1]: LaMountain, Gerald, Vilà-Valls, Jordi, Closas, Pau, "Bayesian Covariance Estimation for Kalman Filter based Digital Carrier Synchronization," Proceedings of the 31st International Technical Meeting of the Satellite Division of The Institute of Navigation (ION GNSS+ 2018), Miami, Florida, September 2018, pp. 3575-3586. <https://doi.org/10.33012/2018.15911>

Authors

- Gerald LaMountain, 2018. gerald(at)ece.neu.edu
- Jordi Vila-Valls 2018. jvila(at)cttc.es

13.587.1.1

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Definition in file [bayesian_estimation.h](#).

13.588 bayesian_estimation.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file bayesian_estimation.h
00003  * \brief Interface of a library with Bayesian noise statistic estimation
00004  *
00005  * Bayesian_estimator is a Bayesian estimator which attempts to estimate
00006  * the properties of a stochastic process based on a sequence of
00007  * discrete samples of the sequence.
00008  *
00009  * [1]: LaMountain, Gerald, Vilà-Valls, Jordi, Closas, Pau, "Bayesian
00010  * Covariance Estimation for Kalman Filter based Digital Carrier
00011  * Synchronization," Proceedings of the 31st International Technical Meeting
00012  * of the Satellite Division of The Institute of Navigation
00013  * (ION GNSS+ 2018), Miami, Florida, September 2018, pp. 3575-3586.
00014  * https://doi.org/10.33012/2018.15911
00015  *
00016  * \authors <ul>
00017  *      <li> Gerald LaMountain, 2018. gerald(at)ece.neu.edu
00018  *      <li> Jordi Vila-Valls 2018. jvila(at)cttc.es
00019  *      </ul>
00020  * -----
00021  *
00022  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00023  * This file is part of GNSS-SDR.
00024  *
00025  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00026  * SPDX-License-Identifier: GPL-3.0-or-later
00027  *
00028  * -----
00029  */
00030
00031 #ifndef GNSS_SDR_BAYESIAN_ESTIMATION_H
00032 #define GNSS_SDR_BAYESIAN_ESTIMATION_H
00033
00034 #if ARMA_NO_BOUND_CHECKING
00035 #define ARMA_NO_DEBUG 1
00036 #endif
00037
00038 #include <armadillo>
00039 #include <gnuradio/gr_complex.h>
00040
00041 /** \addtogroup Tracking
00042  * \{ */
00043 /** \addtogroup Tracking_libs
00044  * \{ */
```

```

00045
00046
00047 /*! \brief Bayesian_estimator is an estimator of noise characteristics (i.e. mean, covariance)
00048 *
00049 * Bayesian_estimator is an estimator which performs estimation of noise characteristics from
00050 * a sequence of identically and independently distributed (IID) samples of a stationary
00051 * stochastic process by way of Bayesian inference using conjugate priors. The posterior
00052 * distribution is assumed to be Gaussian with mean  $\mathbf{\mu}$  and covariance  $\hat{\mathbf{C}}$ ,
00053 * which has a conjugate prior given by a normal-inverse-Wishart distribution with parameters
00054 *  $\mathbf{\mu}_0$ ,  $\mathbf{\kappa}_0$ ,  $\mathbf{\nu}_0$ , and  $\mathbf{\Psi}$ .
00055 *
00056 * [1] TODO: Ref1
00057 *
00058 */
00059
00060 class Bayesian_estimator
00061 {
00062 public:
00063     Bayesian_estimator();
00064     explicit Bayesian_estimator(int ny);
00065     Bayesian_estimator(const arma::vec& mu_prior_0, int kappa_prior_0, int nu_prior_0, const
arma::mat& Psi_prior_0);
00066     ~Bayesian_estimator() = default;
00067
00068     void init(const arma::mat& mu_prior_0, int kappa_prior_0, int nu_prior_0, const arma::mat&
Psi_prior_0);
00069
00070     void update_sequential(const arma::vec& data);
00071     void update_sequential(const arma::vec& data, const arma::vec& mu_prior_0, int kappa_prior_0, int
nu_prior_0, const arma::mat& Psi_prior_0);
00072
00073     arma::mat get_mu_est() const;
00074     arma::mat get_Psi_est() const;
00075
00076 private:
00077     arma::vec mu_est;
00078     arma::mat Psi_est;
00079     arma::vec mu_prior;
00080     arma::mat Psi_prior;
00081     int kappa_prior;
00082     int nu_prior;
00083 };
00084
00085
00086 /** \} */
00087 /** \} */
00088 #endif // GNSS_SDR_BAYESIAN_ESTIMATION_H

```

13.589 bit_synchronizer.h File Reference

Histogram-based bit-edge synchronizer for GNSS prompt correlator outputs.

```

#include <cmath>
#include <complex>
#include <cstdint>
#include <vector>

```

Classes

- class [HistogramBitSynchronizer](#)
Histogram-based navigation data bit synchronizer.
- struct [HistogramBitSynchronizer::Config](#)
Configuration parameters for [HistogramBitSynchronizer](#).

13.589.1 Detailed Description

Histogram-based bit-edge synchronizer for GNSS prompt correlator outputs.

Author

Carles Fernandez-Prades, 2026 cfernandez(at)cttc.es

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Definition in file [bit_synchronizer.h](#).

13.590 bit_synchronizer.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file bit_synchronizer.h
00003  * \brief Histogram-based bit-edge synchronizer for GNSS prompt correlator outputs.
00004  * \author Carles Fernandez-Prades, 2026 cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2026 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_BIT_SYNCHRONIZER_H
00018 #define GNSS_SDR_BIT_SYNCHRONIZER_H
00019
00020 #include <cmath>
00021 #include <complex>
00022 #include <cstdint>
00023 #include <vector>
00024
00025 /** \addtogroup Tracking
00026  * \{ */
00027 /** \addtogroup Tracking_libs
00028  * \{ */
00029
00030
00031 /**
00032  * @brief Histogram-based navigation data bit synchronizer.
00033  */
00034 class HistogramBitSynchronizer
00035 {
00036 public:
00037     /**
00038      * @brief Configuration parameters for HistogramBitSynchronizer.
00039      *
00040      * These parameters define the bit period, the update cadence, the lock criteria,
00041      * and the transition detection method.
00042      */
00043     struct Config
00044     {
00045         /**
00046          * @brief Navigation data bit period in milliseconds.
00047          *
00048          * This is the nominal duration of one navigation data bit.
00049          */
00050         int bit_period_ms;
00051
00052         /**
00053          * @brief Time interval between successive calls to update(), in milliseconds.
00054          *
00055          * This should match the minimum integration interval (epoch) produced by the
00056          * tracking loop and used to generate the provided prompt correlator output.
00057          */
00058         int epoch_ms;
00059
00060         /**
00061          * @brief Minimum number of detected transition events required before lock evaluation.
00062          *
00063          * The histogram is built from detected candidate transitions. Lock decisions are
00064          * not attempted until at least this many events have been accumulated.
00065          *
00066          * Trade-offs:
00067          * - Larger values increase robustness against false locks but increase time-to-lock.
00068          * - Smaller values reduce time-to-lock but increase sensitivity to noise/spurious
00069          * transitions.
00070          */
00070         int min_events_for_lock;
00071
00072         /**
00073          * @brief Required dominance ratio of the winning histogram bin.
00074          *
00075          * Lock requires the most frequent histogram bin to be sufficiently dominant:
00076          * @f[
00077          * \text{dominance\_ratio} = \frac{\text{best\_bin\_count}}{\text{total\_detected\_events}}
00078          * @f]
00079          *
00080          * Guidance:
00081          * - Values near 0.5 may lock faster but increase false-lock probability.
00082          * - Values closer to 1.0 are conservative and require a clearly dominant phase.

```



```

00083     */
00084     double dominance_ratio;
00085
00086     /**
00087      * @brief Required stability of the dominant histogram bin (consecutive evaluations).
00088      *
00089      * Even if the dominance ratio is met, the algorithm requires that the same histogram
00090      * bin remains dominant for this many consecutive lock evaluations before declaring lock.
00091      *
00092      * This helps prevent locking on transient peaks caused by noise or short-lived disturbances.
00093      */
00094     int stable_best_required;
00095
00096     /**
00097      * @brief Minimum magnitude of the prompt correlator output.
00098      *
00099      * Candidate transition detection is suppressed when  $|P| < \min\{\text{prompt\_mag}\}$ ,
00100      * where  $P$  is the prompt correlator output.
00101      *
00102      * Use this to avoid counting unreliable transitions when tracking quality is poor or
00103      * the prompt output is dominated by noise.
00104      */
00105     float min_prompt_mag;
00106
00107     /**
00108      * @brief Select the transition detection method.
00109      *
00110      * If true (recommended), uses a "phase-dot" detector:
00111      * - A candidate transition is detected when:
00112      *    $\text{Re}\{P_k \cdot P^{*}_{k-1}\} < 0$ 
00113      *   where  $P_k$  is the current prompt and  $P^{*}_{k-1}$  the conjugate of the
00114      *   previous.
00115      *
00116      * This method is largely insensitive to constant carrier phase rotations and is often
00117      * more robust during early tracking / imperfect carrier phase alignment.
00118      *
00119      * If false, uses a simpler sign-change detector on the real part:
00120      * - A candidate transition is detected when  $\text{sign}(\text{Re}(P_k)) \neq \text{sign}(\text{Re}(P_{k-1}))$ .
00121      *
00122      * This assumes the prompt output is already aligned with the data bit polarity
00123      * (i.e., stable PLL lock and correct navigation bit polarity mapping).
00124      */
00125     bool use_phase_dot_detector;
00126
00127     Config()
00128     : bit_period_ms(20),
00129       epoch_ms(1),
00130       min_events_for_lock(10),
00131       dominance_ratio(0.6),
00132       stable_best_required(5),
00133       min_prompt_mag(0.0f),
00134       use_phase_dot_detector(true)
00135     {
00136     }
00137 };
00138
00139 /**
00140  * @brief Construct a histogram bit synchronizer with the provided configuration.
00141  *
00142  * Initializes internal counters and allocates the histogram with bins() entries,
00143  * all set to zero.
00144  *
00145  * @param cfg Configuration parameters.
00146  */
00147 explicit HistogramBitSynchronizer(const Config& cfg)
00148 : cfg_(cfg),
00149   hist_(),
00150   total_events_(0),
00151   epoch_count_(0),
00152   last_prompt_(0.0f, 0.0f),
00153   edge_phase_(-1),
00154   last_sign_(+1),
00155   last_best_bin_(0),
00156   stable_best_count_(0),
00157   locked_(false),
00158   has_last_prompt_(false),
00159   has_last_sign_(false),
00160   has_last_best_bin_(false)
00161 {
00162     hist_.assign(bins(), 0);
00163 }
00164
00165 /**
00166  * @brief Reset the synchronizer state.
00167  */

```

```

00169     * Clears the histogram and all internal counters/flags, returning the instance to the
00170     * pre-lock state:
00171     *   - locked() becomes false
00172     *   - edge_phase() becomes -1
00173     *   - total_events and epoch_count are reset to zero
00174     */
00175 void reset();
00176
00177 /**
00178  * @brief Update the synchronizer once per epoch.
00179  *
00180  * This method should be called at a fixed cadence defined by Config::epoch_ms
00181  *
00182  * The method:
00183  *   - Advances the internal epoch counter,
00184  *   - Optionally performs candidate transition detection if tracking quality is acceptable,
00185  *   - Updates the phase histogram on detected transitions,
00186  *   - Evaluates lock once enough events have been gathered.
00187  *
00188  * @param prompt Prompt correlator output for the current epoch.
00189  * @param tracking_quality_ok Indicates whether tracking quality is sufficient to trust
00190  *       the prompt sample for transition detection (e.g., code/carrier lock metrics).
00191  *
00192  * @return True only on the epoch when lock is first declared; false otherwise
00193  *       (including subsequent epochs after lock has been achieved).
00194  */
00195 bool update(const std::complex<float>& prompt, bool tracking_quality_ok);
00196
00197 /**
00198  * @brief Query whether the synchronizer has achieved lock.
00199  *
00200  * @return True if lock has been declared, false otherwise.
00201  */
00202 bool locked() const { return locked_; }
00203
00204 /**
00205  * @brief Get the estimated bit edge phase bin.
00206  *
00207  * The edge phase is expressed as an integer histogram bin index in the range
00208  * [0, bins()-1] when locked. The interpretation is "which epoch phase within the
00209  * bit period is most likely to contain a navigation bit transition."
00210  *
00211  * @return Estimated edge phase bin index, or -1 if not locked.
00212  */
00213 int edge_phase() const { return edge_phase_; }
00214
00215 /**
00216  * @brief Predict whether a given epoch index corresponds to a bit edge.
00217  *
00218  * For a given epoch index @p k (0-based), this function returns true when @p k is
00219  * aligned with the currently estimated edge phase (i.e., the predicted transition epoch),
00220  * and false otherwise.
00221  *
00222  * If not locked, this always returns false.
00223  *
00224  * @param k Epoch index (0-based, consistent with the caller's epoch counting).
00225  * @return True if @p k is the predicted edge epoch; false otherwise.
00226  */
00227 bool is_edge_epoch(std::int64_t k) const;
00228
00229 /**
00230  * @brief Return the number of histogram bins.
00231  *
00232  * Derived from the bit period and epoch duration, e.g.:
00233  *   bins = bit_period_ms / epoch_ms
00234  *
00235  * @return Number of histogram bins.
00236  */
00237 int bins() const;
00238
00239 /**
00240  * @brief Access the internal histogram (read-only).
00241  *
00242  * Each entry counts how many detected candidate transitions occurred at the
00243  * corresponding phase bin within the bit period.
00244  *
00245  * @return Reference to the histogram vector.
00246  */
00247 const std::vector<int>& get_histogram() const { return hist_; }
00248
00249 /**
00250  * @brief Total number of detected transition events accumulated into the histogram.
00251  *
00252  * @return Total detected events.
00253  */
00254 std::int64_t get_total_events() const { return total_events_; }
00255

```

```

00256  /**
00257   * @brief Total number of epochs processed by update().
00258   *
00259   * This counter increments once per call to update(), regardless of whether a transition
00260   * is detected or whether tracking_quality_ok is true.
00261   *
00262   * @return Total processed epochs.
00263   */
00264  std::int64_t get_epoch_count() const { return epoch_count_; }
00265
00266  /**
00267   * @brief Return the number of epochs until the next predicted navigation bit edge.
00268   *
00269   * When the synchronizer is locked, this function computes the forward distance
00270   * (in epochs) from the most recently processed epoch to the next epoch that is
00271   * aligned with the estimated bit-edge phase.
00272   *
00273   * The result is expressed modulo the bit period and has the following meaning:
00274   * - 0 : the current epoch corresponds to the predicted start of a new navigation bit
00275   * - >0 : number of epochs remaining until the next bit boundary
00276   *
00277   * The computation is based on the internal epoch counter advanced by update(),
00278   * assuming that update() is called once per epoch with a constant cadence
00279   * equal to Config::epoch_ms.
00280   *
00281   * If the synchronizer is not locked, or if the configuration yields an invalid
00282   * number of bins, this function returns -1.
00283   *
00284   * @return Number of epochs until the next predicted bit edge, or -1 if not locked
00285   *         or if the bit period configuration is invalid.
00286   */
00287  int epochs_until_next_edge() const;
00288
00289 private:
00290  void best_bin_and_count(int& best_bin, int& best_count) const;
00291
00292  Config cfg_;
00293  std::vector<int> hist_;
00294
00295  std::int64_t total_events_;
00296  std::int64_t epoch_count_;
00297
00298  std::complex<float> last_prompt_; // Sign history (for simple detector)
00299
00300  int edge_phase_;
00301  int last_sign_; // Sign history (for simple detector)
00302  int last_best_bin_; // Stability tracking for best bin
00303  int stable_best_count_; // Stability tracking for best bin
00304
00305  bool locked_;
00306  bool has_last_prompt_; // Prompt history (for dot detector)
00307  bool has_last_sign_; // Sign history (for simple detector)
00308  bool has_last_best_bin_; // Stability tracking for best bin
00309 };
00310
00311 /** @} */
00312 /** @} */
00313 #endif // GNSS_SDR_BIT_SYNCHRONIZER_H

```

13.591 cpu_multicorrelator.h File Reference

High optimized CPU vector multiTAP correlator class.

#include <complex>

Classes

- class [Cpu_Multicorrelator](#)

Class that implements carrier wipe-off and correlators.

13.591.1 Detailed Description

High optimized CPU vector multiTAP correlator class.

Authors

- Javier Arribas, 2015. jarribas(at)cttc.es

Class that implements a high optimized vector multiTAP correlator class for CPUs

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Definition in file [cpu_multicorrelator.h](#).

13.592 cpu_multicorrelator.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file cpu_multicorrelator.h
00003  * \brief High optimized CPU vector multiTAP correlator class
00004  * \authors <ul>
00005  *         <li> Javier Arribas, 2015. jarribas(at)cttc.es
00006  *         </ul>
00007  *
00008  * Class that implements a high optimized vector multiTAP correlator class for CPUs
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_CPU_MULTICORRELATOR_H
00022 #define GNSS_SDR_CPU_MULTICORRELATOR_H
00023
00024
00025 #include <complex>
00026
00027 /** \addtogroup Tracking
00028  * \{ */
00029 /** \addtogroup Tracking_libs tracking_libs
00030  * Utilities for GNSS signal tracking.
00031  * \{ */
00032
00033
00034 /*!
00035  * \brief Class that implements carrier wipe-off and correlators.
00036  */
00037 class Cpu_Multicorrelator
00038 {
00039 public:
00040     Cpu_Multicorrelator() = default;
00041     ~Cpu_Multicorrelator();
00042     bool init(int max_signal_length_samples, int n_correlators);
00043     bool set_local_code_and_taps(int code_length_chips, const std::complex<float> *local_code_in,
00044     float *shifts_chips);
00044     bool set_input_output_vectors(std::complex<float> *corr_out, const std::complex<float> *sig_in);
00045     void update_local_code(int correlator_length_samples, float rem_code_phase_chips, float
00046     code_phase_step_chips);
00046     bool Carrier_wipeoff_multicorrelator_resampler(float rem_carrier_phase_in_rad, float
00047     phase_step_rad, float rem_code_phase_chips, float code_phase_step_chips, int signal_length_samples);
00047     bool free();
00048
00049 private:
00050     // Allocate the device input vectors
00051     const std::complex<float> *d_sig_in{nullptr};
00052     const std::complex<float> *d_local_code_in{nullptr};
00053     std::complex<float> **d_local_codes_resampled{nullptr};
00054     std::complex<float> *d_corr_out{nullptr};
00055     float *d_shifts_chips{nullptr};
00056     int d_code_length_chips{0};
00057     int d_n_correlators{0};
00058 };
00059
00060
00061 /** \} */
00062 /** \} */
00063 #endif // GNSS_SDR_CPU_MULTICORRELATOR_H

```

13.593 cpu_multicorrelator_16sc.h File Reference

Highly optimized CPU vector multiTAP correlator class for lv_16sc_t (short int complex)

```
#include <volk_gnssdr/volk_gnssdr.h>
```

Classes

- class [Cpu_Multicorrelator_16sc](#)

Class that implements carrier wipe-off and correlators.

13.593.1 Detailed Description

Highly optimized CPU vector multiTAP correlator class for lv_16sc_t (short int complex)

Authors

- Javier Arribas, 2016. jarribas(at)cttc.es

Class that implements a highly optimized vector multiTAP correlator class for CPUs

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Definition in file [cpu_multicorrelator_16sc.h](#).

13.594 cpu_multicorrelator_16sc.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file cpu_multicorrelator_16sc.h
00003  * \brief Highly optimized CPU vector multiTAP correlator class for lv_16sc_t (short int complex)
00004  * \authors <ul>
00005  *         <li> Javier Arribas, 2016. jarribas(at)cttc.es
00006  *         </li>
00007  *         </ul>
00008  * Class that implements a highly optimized vector multiTAP correlator class for CPUs
00009  * -----
00010  * -----
00011  * -----
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  * -----
00015  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  * -----
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_CPU_MULTICORRELATOR_16SC_H
00022 #define GNSS_SDR_CPU_MULTICORRELATOR_16SC_H
00023
00024 #include <volk_gnssdr/volk_gnssdr.h>
00025
00026 ** \addtogroup Tracking
00027  * \{ */
00028 ** \addtogroup Tracking_libs
00029  * \{ */
00030
00031
00032 /*!
00033  * \brief Class that implements carrier wipe-off and correlators.
00034  */
00035 class Cpu_Multicorrelator_16sc
00036 {
00037 public:
00038     Cpu_Multicorrelator_16sc() = default;
00039     ~Cpu_Multicorrelator_16sc();
00040     bool init(int max_signal_length_samples, int n_correlators);
00041     bool set_local_code_and_taps(int code_length_chips, const lv_16sc_t *local_code_in, float
00042  *shifts_chips);
00043     bool set_input_output_vectors(lv_16sc_t *corr_out, const lv_16sc_t *sig_in);
00044     void update_local_code(int correlator_length_samples, float rem_code_phase_chips, float
00045  code_phase_step_chips);
00046     bool Carrier_wipeoff_multicorrelator_resampler(float rem_carrier_phase_in_rad, float
00047  phase_step_rad, float rem_code_phase_chips, float code_phase_step_chips, int signal_length_samples);
00048     bool free();
```

```

00046
00047 private:
00048     // Allocate the device input vectors
00049     const lv_16sc_t *d_sig_in{nullptr};
00050     const lv_16sc_t *d_local_code_in{nullptr};
00051     lv_16sc_t **d_local_codes_resampled{nullptr};
00052     lv_16sc_t *d_corr_out{nullptr};
00053     float *d_shifts_chips{nullptr};
00054     int d_code_length_chips{0};
00055     int d_n_correlators{0};
00056 };
00057
00058
00059 /** \} */
00060 /** \} */
00061 #endif // GNSS_SDR_CPU_MULTICORRELATOR_H

```

13.595 cpu_multicorrelator_real_codes.h File Reference

Highly optimized CPU vector multiTAP correlator class using real-valued local codes.

```
#include <complex>
```

Classes

- class [Cpu_Multicorrelator_Real_Codes](#)
Class that implements carrier wipe-off and correlators.

13.595.1 Detailed Description

Highly optimized CPU vector multiTAP correlator class using real-valued local codes.

Authors

- Javier Arribas, 2015. jarribas(at)cttc.es
- Cillian O'Driscoll, 2017, cillian.odriscoll(at)gmail.com

Class that implements a highly optimized vector multiTAP correlator class for CPUs

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Definition in file [cpu_multicorrelator_real_codes.h](#).

13.596 cpu_multicorrelator_real_codes.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file cpu_multicorrelator_real_codes.h
00003 * \brief Highly optimized CPU vector multiTAP correlator class using real-valued local codes
00004 * \authors <ul>
00005 *     <li> Javier Arribas, 2015. jarribas(at)cttc.es
00006 *     <li> Cillian O'Driscoll, 2017, cillian.odriscoll(at)gmail.com
00007 * </ul>
00008 *
00009 * Class that implements a highly optimized vector multiTAP correlator class for CPUs
00010 *
00011 * -----
00012 *
00013 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014 * This file is part of GNSS-SDR.
00015 *
00016 * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00017 * SPDX-License-Identifier: GPL-3.0-or-later
00018 *
00019 * -----
00020 */
00021
00022 #ifndef GNSS_SDR_CPU_MULTICORRELATOR_REAL_CODES_H
00023 #define GNSS_SDR_CPU_MULTICORRELATOR_REAL_CODES_H
00024
00025
00026 #include <complex>
00027

```

```

00028 /** \addtogroup Tracking
00029 * \{ */
00030 /** \addtogroup Tracking_libs
00031 * \{ */
00032
00033
00034 /*!
00035 * \brief Class that implements carrier wipe-off and correlators.
00036 */
00037 class Cpu_Multicorrelator_Real_Codes
00038 {
00039 public:
00040     Cpu_Multicorrelator_Real_Codes() = default;
00041     void set_high_dynamics_resampler(bool use_high_dynamics_resampler);
00042     ~Cpu_Multicorrelator_Real_Codes();
00043     bool init(int max_signal_length_samples, int n_correlators);
00044     bool set_local_code_and_taps(int code_length_chips, const float *local_code_in, float
*shifts_chips);
00045     bool set_input_output_vectors(std::complex<float> *corr_out, const std::complex<float> *sig_in);
00046     void update_local_code(int correlator_length_samples, float rem_code_phase_chips, float
code_phase_step_chips, float code_phase_rate_step_chips = 0.0);
00047     bool Carrier_wipeoff_multicorrelator_resampler(float rem_carrier_phase_in_rad, float
phase_step_rad, float phase_rate_step_rad, float rem_code_phase_chips, float code_phase_step_chips,
float code_phase_rate_step_chips, int signal_length_samples);
00048     bool Carrier_wipeoff_multicorrelator_resampler(float rem_carrier_phase_in_rad, float
phase_step_rad, float rem_code_phase_chips, float code_phase_step_chips, float
code_phase_rate_step_chips, int signal_length_samples);
00049     bool free();
00050
00051 private:
00052     // Allocate the device input vectors
00053     const std::complex<float> *d_sig_in{nullptr};
00054     const float *d_local_code_in{nullptr};
00055     std::complex<float> *d_corr_out{nullptr};
00056     float **d_local_codes_resampled{nullptr};
00057     float *d_shifts_chips{nullptr};
00058     int d_code_length_chips{0};
00059     int d_n_correlators{0};
00060     bool d_use_high_dynamics_resampler{true};
00061 };
00062
00063
00064 /** \} */
00065 /** \} */
00066 #endif // GNSS_SDR_CPU_MULTICORRELATOR_REAL_CODES_H

```

13.597 cuda_multicorrelator.h File Reference

Highly optimized CUDA GPU vector multiTAP correlator class.

```

#include <complex>
#include <cuda.h>
#include <cuda_runtime.h>

```

Classes

- struct [GPU_Complex](#)
- struct [GPU_Complex_Short](#)
- class [cuda_multicorrelator](#)

Class that implements carrier wipe-off and correlators using NVIDIA CUDA GPU accelerators.

13.597.1 Detailed Description

Highly optimized CUDA GPU vector multiTAP correlator class.

Authors

- Javier Arribas, 2015. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)

Class that implements a highly optimized vector multiTAP correlator class for NVIDIA CUDA GPUs

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Definition in file [cuda_multicorrelator.h](#).

13.597.2 Macro Definition Documentation

13.597.2.1 CUDA_CALLABLE_MEMBER_DEVICE

#define CUDA_CALLABLE_MEMBER_DEVICE

Definition at line 30 of file [cuda_multicorrelator.h](#).

13.597.2.2 CUDA_CALLABLE_MEMBER_GLOBAL

#define CUDA_CALLABLE_MEMBER_GLOBAL

Definition at line 29 of file [cuda_multicorrelator.h](#).

13.598 cuda_multicorrelator.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002   * \file cuda_multicorrelator.h
00003   * \brief Highly optimized CUDA GPU vector multiTAP correlator class
00004   * \authors <ul>
00005   *         <li> Javier Arribas, 2015. jarribas(at)cttc.es
00006   *         </li>
00007   *
00008   * Class that implements a highly optimized vector multiTAP correlator class for NVIDIA CUDA GPUs
00009   *
00010   * -----
00011   *
00012   * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013   * This file is part of GNSS-SDR.
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00017   *
00018   * -----
00019   */
00020
00021 #ifndef GNSS_SDR_CUDA_MULTICORRELATOR_H
00022 #define GNSS_SDR_CUDA_MULTICORRELATOR_H
00023
00024
00025 #ifdef __CUDACC__
00026 #define CUDA_CALLABLE_MEMBER_GLOBAL __global__
00027 #define CUDA_CALLABLE_MEMBER_DEVICE __device__
00028 #else
00029 #define CUDA_CALLABLE_MEMBER_GLOBAL
00030 #define CUDA_CALLABLE_MEMBER_DEVICE
00031 #endif
00032
00033 #include <complex>
00034 #include <cuda.h>
00035 #include <cuda_runtime.h>
00036
00037 /** \addtogroup Tracking
00038  * \{ */
00039 /** \addtogroup Tracking_libs
00040  * \{ */
00041
00042
00043 // GPU new internal data types for complex numbers
00044
00045 struct GPU_Complex
00046 {
00047     float r;
00048     float i;
00049     CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex() {};
00050     CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex(float a, float b) : r(a), i(b) {}
00051     CUDA_CALLABLE_MEMBER_DEVICE float magnitude2(void) { return r * r + i * i; }
00052     CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex operator*(const GPU_Complex& a)
00053     {
00054 #ifdef __CUDACC__
00055         return GPU_Complex(__fmul_rn(r, a.r) - __fmul_rn(i, a.i), __fmul_rn(i, a.r) + __fmul_rn(r,
00056         a.i));
00057 #else
00057         return GPU_Complex(r * a.r - i * a.i, i * a.r + r * a.i);
00058 #endif
00059     }
00060     CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex operator+(const GPU_Complex& a)
00061     {
00062         return GPU_Complex(r + a.r, i + a.i);
00063     }
00064     CUDA_CALLABLE_MEMBER_DEVICE void operator+=(const GPU_Complex& a)

```



```

00065     {
00066         r += a.r;
00067         i += a.i;
00068     }
00069     CUDA_CALLABLE_MEMBER_DEVICE void multiply_acc(const GPU_Complex& a, const GPU_Complex& b)
00070     {
00071         // c=a*b+c
00072         // real part
00073         // c.r=(a.r*b.r - a.i*b.i)+c.r
00074 #ifdef __CUDACC__
00075         r = __fmaf_rn(a.r, b.r, r);
00076         r = __fmaf_rn(-a.i, b.i, r);
00077         // imag part
00078         i = __fmaf_rn(a.i, b.r, i);
00079         i = __fmaf_rn(a.r, b.i, i);
00080 #else
00081         r = (a.r * b.r - a.i * b.i) + r;
00082         i = (a.i * b.r - a.r * b.i) + i;
00083 #endif
00084     }
00085 };
00086
00087
00088 struct GPU_Complex_Short
00089 {
00090     float r;
00091     float i;
00092     CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex_Short(short int a, short int b) : r(a), i(b) {}
00093     CUDA_CALLABLE_MEMBER_DEVICE float magnitude2(void)
00094     {
00095         return r * r + i * i;
00096     }
00097     CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex_Short operator*(const GPU_Complex_Short& a)
00098     {
00099         return GPU_Complex_Short(r * a.r - i * a.i, i * a.r + r * a.i);
00100     }
00101     CUDA_CALLABLE_MEMBER_DEVICE GPU_Complex_Short operator+(const GPU_Complex_Short& a)
00102     {
00103         return GPU_Complex_Short(r + a.r, i + a.i);
00104     }
00105 };
00106
00107
00108 /*!
00109 * \brief Class that implements carrier wipe-off and correlators using NVIDIA CUDA GPU accelerators.
00110 */
00111 class cuda_multicorrelator
00112 {
00113 public:
00114     cuda_multicorrelator();
00115     bool init_cuda_integrated_resampler(
00116         int signal_length_samples,
00117         int code_length_chips,
00118         int n_correlators);
00119     bool set_local_code_and_taps(
00120         int code_length_chips,
00121         const std::complex<float>* local_codes_in,
00122         float* shifts_chips,
00123         int n_correlators);
00124     bool set_input_output_vectors(
00125         std::complex<float>* corr_out,
00126         std::complex<float>* sig_in);
00127
00128     bool free_cuda();
00129     bool Carrier_wipeoff_multicorrelator_resampler_cuda(
00130         float rem_carrier_phase_in_rad,
00131         float phase_step_rad,
00132         float code_phase_step_chips,
00133         float rem_code_phase_chips,
00134         int signal_length_samples,
00135         int n_correlators);
00136 private:
00137     cudaStream_t stream1;
00138     // cudaStream_t stream2;
00139
00140     // Allocate the device input vectors
00141     GPU_Complex* d_sig_in;
00142     GPU_Complex* d_nco_in;
00143     GPU_Complex* d_sig_doppler_wiped;
00144     GPU_Complex* d_local_codes_in;
00145     GPU_Complex* d_corr_out;
00146
00147     std::complex<float>* d_sig_in_cpu;
00148     std::complex<float>* d_corr_out_cpu;
00149
00150     float* d_shifts_chips;

```

```

00152     int* d_shifts_samples;
00153     int d_code_length_chips;
00154
00155     int selected_gps_device;
00156     int threadsPerBlock;
00157     int blocksPerGrid;
00158
00159     int num_gpu_devices;
00160     int selected_device;
00161 };
00162
00163
00164 /** \} */
00165 /** \} */
00166 #endif // GNSS_SDR_CUDA_MULTICORRELATOR_H

```

13.599 dll_pll_conf.h File Reference

Class that contains all the configuration parameters for generic tracking block based on a DLL and a PLL.

```

#include "configuration_interface.h"
#include <stdint>
#include <string>

```

Classes

- class [Dll_Pll_Conf](#)

13.599.1 Detailed Description

Class that contains all the configuration parameters for generic tracking block based on a DLL and a PLL.

Author

Javier Arribas, 2018. jarribas(at)cttc.es

Class that contains all the configuration parameters for generic tracking block based on a DLL and a PLL.
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Definition in file [dll_pll_conf.h](#).

13.600 dll_pll_conf.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file dll_pll_conf.h
00003  * \brief Class that contains all the configuration parameters for generic tracking block based on a
00004  *        DLL and a PLL.
00005  * \author Javier Arribas, 2018. jarribas(at)cttc.es
00006  *
00007  * Class that contains all the configuration parameters for generic tracking block based on a DLL and
00008  * a PLL.
00009  *
00010  * -----
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_DLL_PLL_CONF_H
00020 #define GNSS_SDR_DLL_PLL_CONF_H
00021
00022 #include "configuration_interface.h"
00023 #include <stdint>
00024 #include <string>
00025
00026 /** \addtogroup Tracking
00027  * \{ */

```

```

00028 /** \addtogroup Tracking_libs
00029 * \{ */
00030
00031
00032 class Dll_Pll_Conf
00033 {
00034 public:
00035     Dll_Pll_Conf();
00036     void SetFromConfiguration(const ConfigurationInterface *configuration, const std::string &role);
00037
00038     /* DLL/PLL tracking configuration */
00039     std::string item_type{"gr_complex"};
00040     std::string dump_filename{"./dll_pll_dump.dat"};
00041     double fs_in{2000000.0};
00042     double carrier_lock_th{0.0};
00043     double bs_dominance_ratio{0.6};
00044     float pll_pull_in_bw_hz{50.0};
00045     float dll_pull_in_bw_hz{3.0};
00046     float fll_bw_hz{35.0};
00047     float pll_bw_hz{35.0};
00048     float dll_bw_hz{2.0};
00049     float pll_bw_narrow_hz{5.0};
00050     float dll_bw_narrow_hz{0.75};
00051     float early_late_space_chips{0.25};
00052     float very_early_late_space_chips{0.5};
00053     float early_late_space_narrow_chips{0.15};
00054     float very_early_late_space_narrow_chips{0.5};
00055     float slope{1.0};
00056     float spc{0.5};
00057     float y_intercept{1.0};
00058     float cn0_smoother_alpha{0.002};
00059     float carrier_lock_test_smoother_alpha{0.002};
00060     float bs_min_prompt_mag{0.0};
00061     uint32_t pull_in_time_s{5U};
00062     uint32_t bit_synchronization_time_limit_s{20U};
00063     uint32_t vector_length{0U};
00064     uint32_t smoother_length{10U};
00065     int32_t fll_filter_order{1};
00066     int32_t pll_filter_order{3};
00067     int32_t dll_filter_order{2};
00068     int32_t extend_correlation_symbols{1};
00069     int32_t cn0_samples{0};
00070     int32_t cn0_smoother_samples{200};
00071     int32_t carrier_lock_test_smoother_samples{25};
00072     int32_t cn0_min{0};
00073     int32_t max_code_lock_fail{0};
00074     int32_t max_carrier_lock_fail{0};
00075     int32_t bs_stable_best_required{3};
00076     int32_t bs_min_events_for_lock{10};
00077     char signal[3]{};
00078     char system{'G'};
00079     bool enable_fll_pull_in{false};
00080     bool enable_fll_steady_state{false};
00081     bool track_pilot{true};
00082     bool enable_doppler_correction{false};
00083     bool carrier_aiding{true};
00084     bool high_dyn{false};
00085     bool dump{false};
00086     bool dump_mat{true};
00087     bool tow_to_trk{false};
00088     bool bs_use_phase_dot_detector{true};
00089 };
00090
00091
00092 /** \} */
00093 /** \} */
00094 #endif // GNSS_SDR_DLL_PLL_CONF_H

```

13.601 dll_pll_conf_fpga.h File Reference

Class that contains all the configuration parameters for generic tracking block based on a DLL and a PLL for the FPGA.

```

#include "configuration_interface.h"
#include <stdint>
#include <string>

```

Classes

- class [Dll_Pll_Conf_Fpga](#)


```

00062     float cn0_smoother_alpha{0.002};
00063     float carrier_lock_test_smoother_alpha{0.002};
00064     float bs_min_prompt_mag{0.0};
00065
00066     uint32_t pull_in_time_s{50}; // signed integer, when pull in time is not yet reached it has to be
    compared against a negative number
00067     uint32_t bit_synchronization_time_limit_s{700};
00068     uint32_t vector_length{00};
00069     uint32_t smoother_length{100};
00070     uint32_t code_length_chips{00};
00071     uint32_t code_samples_per_chip{00};
00072     uint32_t extend_fpga_integration_periods{1};
00073     uint32_t fpga_integration_period{0};
00074
00075     int32_t fll_filter_order{1};
00076     int32_t pll_filter_order{3};
00077     int32_t dll_filter_order{2};
00078     int32_t extend_correlation_symbols{1};
00079     int32_t cn0_samples{0};
00080     int32_t cn0_min{0};
00081     int32_t max_code_lock_fail{0};
00082     int32_t max_carrier_lock_fail{0};
00083     int32_t cn0_smoother_samples{200};
00084     int32_t carrier_lock_test_smoother_samples{25};
00085     // int32_t max_lock_fail;
00086     int32_t bs_stable_best_required{3};
00087     int32_t bs_min_events_for_lock{10};
00088
00089     int32_t* ca_codes{nullptr};
00090     int32_t* data_codes{nullptr};
00091
00092     char signal[3]{};
00093     char system{'G'};
00094
00095     bool extended_correlation_in_fpga{false};
00096     bool track_pilot{true};
00097     bool enable_doppler_correction{false};
00098     bool enable_fll_pull_in{false};
00099     bool enable_fll_steady_state{false};
00100     bool carrier_aiding{true};
00101     bool high_dyn{false};
00102     bool dump{false};
00103     bool dump_mat{true};
00104     bool bs_use_phase_dot_detector{true};
00105 };
00106
00107
00108 /** \} */
00109 /** \} */
00110 #endif // GNSS_SDR_DLL_PLL_CONF_FPGA_H

```

13.603 exponential_smoother.h File Reference

Class that implements an exponential smoother.

```
#include <vector>
```

Classes

- class [Exponential_Smoother](#)
Class that implements a first-order exponential smoother.

13.603.1 Detailed Description

Class that implements an exponential smoother.

Authors

Carles Fernandez, 2019 cfernandez@cttc.es

Class that implements a first-order exponential smoother.

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Definition in file [exponential_smoother.h](#).

13.604 exponential_smoother.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file exponential_smoother.h
00003  * \brief Class that implements an exponential smoother
00004  * \authors Carles Fernandez, 2019 cfernandez@cttc.es
00005  *
00006  * Class that implements a first-order exponential smoother.
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019
00020 #ifndef GNSS_SDR_EXPONENTIAL_SMOOTHER_H
00021 #define GNSS_SDR_EXPONENTIAL_SMOOTHER_H
00022
00023 #include <vector>
00024
00025 /** \addtogroup Tracking
00026  * \{ */
00027 /** \addtogroup Tracking_libs
00028  * \{ */
00029
00030
00031 /*! \brief
00032  * Class that implements a first-order exponential smoother.
00033  *
00034  * smoothed_value[k] = alpha * raw + (1-alpha) * smoothed_value[k-1]
00035  *
00036  * The length of the initialization can be controlled with
00037  * set_samples_for_initialization(int num_samples)
00038  */
00039 class Exponential_Smoother
00040 {
00041 public:
00042     Exponential_Smoother();           //!< Constructor
00043     ~Exponential_Smoother() = default; //!< Destructor
00044
00045     Exponential_Smoother(Exponential_Smoother&&) = default;           //!< Move operator
00046     Exponential_Smoother& operator=(Exponential_Smoother&& /*other*/) = default; //!< Move assignment
00047
00048     void set_alpha(float alpha);           //!< 0 < alpha < 1. The higher, the most
00049     void set_samples_for_initialization(int num_samples); //!< Number of samples averaged for
00050     void reset();
00051     void set_min_value(float value);
00052     void set_offset(float offset);
00053     float smooth(float raw);
00054     double smooth(double raw);
00055
00056 private:
00057     std::vector<float> init_buffer_;
00058     float alpha_{0.001};
00059     float one_minus_alpha_{0.999};
00060     float old_value_{0.0};
00061     float min_value_{25.0};
00062     float offset_{12.0};
00063     int samples_for_initialization_{200};
00064     int init_counter_{0};
00065     bool initializing_{true};
00066 };
00067
00068
00069 /** \} */
00070 /** \} */
00071 #endif // GNSS_SDR_EXPONENTIAL_SMOOTHER_H

```

13.605 fpga_multicorrelator.h File Reference

FPGA vector correlator class.

```
#include <gnuradio/block.h>
#include <volk_gnssssdr/volk_gnssssdr_alloc.h>
#include <stdint>
#include <string>
```

Classes

- class [Fpga_Multicorrelator_8sc](#)
Class that implements carrier wipe-off and correlators.

13.605.1 Detailed Description

FPGA vector correlator class.

Authors

- Marc Majoral, 2019. mmajoral(at)cttc.cat
- Javier Arribas, 2019. jarribas(at)cttc.es

Class that controls and executes a highly optimized vector correlator class in the FPGA
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Definition in file [fpga_multicorrelator.h](#).

13.606 fpga_multicorrelator.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file fpga_multicorrelator.h
00003  * \brief FPGA vector correlator class
00004  * \authors <ul>
00005  *         <li> Marc Majoral, 2019. mmajoral(at)cttc.cat
00006  *         <li> Javier Arribas, 2019. jarribas(at)cttc.es
00007  *         </ul>
00008  *
00009  * Class that controls and executes a highly optimized vector correlator
00010  * class in the FPGA
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.
00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_FPGA_MULTICORRELATOR_H
00024 #define GNSS_SDR_FPGA_MULTICORRELATOR_H
00025
00026 #include <gnuradio/block.h>
00027 #include <volk_gnssssdr/volk_gnssssdr_alloc.h>
00028 #include <stdint>
00029 #include <string>
00030
00031 /** \addtogroup Tracking
00032  * \{ */
00033 /** \addtogroup Tracking_libs
00034  * \{ */
00035
00036
00037 /*!
00038  * \brief Class that implements carrier wipe-off and correlators.
00039  */
00040 class Fpga_Multicorrelator_8sc
00041 {
00042 public:
00043     /*!
00044      * \brief Constructor
00045      */
00046     Fpga_Multicorrelator_8sc(int32_t n_correlators,
```

```

00047         int32_t *ca_codes,
00048         int32_t *data_codes,
00049         uint32_t code_length_chips,
00050         bool track_pilot,
00051         uint32_t code_samples_per_chip);
00052
00053     /*!
00054     * \brief Destructor
00055     */
00056     ~Fpga_Multicorrelator_8sc();
00057
00058     /*!
00059     * \brief Configure pointers to the FPGA multicorrelator results
00060     */
00061     void set_output_vectors(gr_complex *corr_out, gr_complex *Prompt_Data);
00062
00063     /*!
00064     * \brief Configure the local code in the FPGA multicorrelator
00065     */
00066     void set_local_code_and_taps(
00067         float *shifts_chips, float *prompt_data_shift, int32_t PRN);
00068
00069     /*!
00070     * \brief Configure code phase and code rate parameters in the FPGA
00071     */
00072     void update_local_code();
00073
00074     /*!
00075     * \brief Perform a multicorrelation
00076     */
00077     void Carrier_wipeoff_multicorrelator_resampler(
00078         float rem_carrier_phase_in_rad,
00079         float phase_step_rad,
00080         float carrier_phase_rate_step_rad,
00081         float rem_code_phase_chips,
00082         float code_phase_step_chips,
00083         float code_phase_rate_step_chips,
00084         int32_t signal_length_samples);
00085
00086     /*!
00087     * \brief Stop the correlation process in the FPGA and free code phase and code rate parameters
00088     */
00089     bool free();
00090
00091     /*!
00092     * \brief Open the FPGA device driver
00093     */
00094     void open_channel(const std::string &device_io_name, uint32_t channel);
00095
00096     /*!
00097     * \brief Set the initial sample number where the tracking process begins
00098     */
00099     void set_initial_sample(uint64_t samples_offset);
00100
00101     /*!
00102     * \brief Read the sample counter in the FPGA
00103     */
00104     uint64_t read_sample_counter();
00105
00106     /*!
00107     * \brief Start the tracking process in the FPGA
00108     */
00109     void lock_channel();
00110
00111     /*!
00112     * \brief finish the tracking process in the FPGA
00113     */
00114     void unlock_channel();
00115
00116     /*!
00117     * \brief Set the secondary code length in the FPGA. This is only used when extended coherent
    integration
00118     * is enabled in the FPGA. If tracking the pilot is enabled then secondary_code_0_length is the
    length of the pilot
00119     * secondary code and secondary_code_1_length is the length of the data secondary code. If
    tracking the pilot is disabled
00120     * then secondary_code_0_length is the length of the data secondary code, and
    secondary_code_1_length must be set to zero.
00121     */
00122     void set_secondary_code_lengths(uint32_t secondary_code_0_length, uint32_t
    secondary_code_1_length);
00123
00124     /*!
00125     * \brief Initialize the secondary code in the FPGA. If tracking the pilot is enabled then the
    pilot secondary code is
00126     * configured when secondary_code = 0 and the data secondary code is configured when
    secondary_code = 1. If tracking the

```



```

00127     * pilot is disabled then the data secondary code is configured when secondary code = 0.
00128     */
00129     void initialize_secondary_code(uint32_t secondary_code, std::string *secondary_code_string);
00130
00131     /*!
00132     * \brief Set the PRN length in the FPGA in number of samples. This function is only used then
    extended coherent integration is enabled in the
00133     * FPGA. The FPGA allows for the configuration of two PRN lengths. When the length of the extended
    coherent integration is bigger than the
00134     * length of the PRN code, the FPGA uses the first_length_secondary_code as the length of the PRN
    code immediately following the beginning
00135     * of the extended coherent integration, and the next_length_secondary_code as the length of the
    remaining PRN codes.
00136     * The purpose of this is to have the option to allow the FPGA to compensate for a possible
    deviation between the nominal value of the PRN
00137     * code length and the measured PRN code length in the PRN immediately following the start of the
    coherent integration only.
00138     * If this option is not used then write the same value to first_length_secondary_code and
    next_length_secondary_code.
00139     */
00140     void update_prn_code_length(uint32_t first_prn_length, uint32_t next_prn_length);
00141
00142     /*!
00143     * \brief Enable the use of secondary codes in the FPGA
00144     */
00145     void enable_secondary_codes();
00146
00147     /*!
00148     * \brief Disable the use of secondary codes in the FPGA
00149     */
00150     void disable_secondary_codes();
00151
00152 private:
00153     // FPGA register addresses
00154     // write addresses
00155     static const uint32_t code_phase_step_chips_num_reg_addr = 0;
00156     static const uint32_t initial_index_reg_base_addr = 1;
00157     static const uint32_t initial_interp_counter_reg_base_addr = 7;
00158     static const uint32_t nsamples_minus_1_reg_addr = 13;
00159     static const uint32_t code_length_minus_1_reg_addr = 14;
00160     static const uint32_t rem_carr_phase_rad_reg_addr = 15;
00161     static const uint32_t phase_step_rad_reg_addr = 16;
00162     static const uint32_t prog_mems_addr = 17;
00163     static const uint32_t drop_samples_reg_addr = 18;
00164     static const uint32_t initial_counter_value_reg_addr_lsw = 19;
00165     static const uint32_t initial_counter_value_reg_addr_msw = 20;
00166     static const uint32_t code_phase_step_chips_rate_reg_addr = 21;
00167     static const uint32_t phase_step_rate_reg_addr = 22;
00168     static const uint32_t stop_tracking_reg_addr = 23;
00169     static const uint32_t secondary_code_lengths_reg_addr = 25;
00170     static const uint32_t prog_secondary_code_0_data_reg_addr = 26;
00171     static const uint32_t prog_secondary_code_1_data_reg_addr = 27;
00172     static const uint32_t first_prn_length_minus_1_reg_addr = 28;
00173     static const uint32_t next_prn_length_minus_1_reg_addr = 29;
00174     static const uint32_t start_flag_addr = 30;
00175     // read-write addresses
00176     static const uint32_t test_reg_addr = 31;
00177     // read addresses
00178     static const uint32_t result_reg_real_base_addr = 1;
00179     static const uint32_t result_reg_imag_base_addr = 7;
00180     static const uint32_t sample_counter_reg_addr_lsw = 13;
00181     static const uint32_t sample_counter_reg_addr_msw = 14;
00182     // FPGA-related constants
00183     static const uint32_t secondary_code_word_size = 20; // the secondary codes are written in
    to the FPGA in words of secondary_code_word_size bits
00184     static const uint32_t secondary_code_wr_strobe = 0x800000; // write strobe position in the
    secondary code write register
00185     static const uint32_t secondary_code_addr_bits = 0x100000; // memory address position in the
    secondary code write register
00186     static const uint32_t drop_samples = 1; // bit 0 of drop_samples_reg_addr
00187     static const uint32_t enable_secondary_code = 2; // bit 1 of drop_samples_reg_addr
00188     static const uint32_t init_secondary_code_addresses = 4; // bit 2 of drop_samples_reg_addr
00189     static const uint32_t FPGA_PAGE_SIZE = 0x1000;
00190     static const uint32_t max_code_resampler_counter = 1 << 31; // 2^(number of bits of precision of
    the code resampler)
00191     static const uint32_t local_code_fpga_clear_address_counter = 0x10000000;
00192     static const uint32_t test_register_track_writeval = 0x55AA;
00193
00194     // private functions
00195     uint32_t fpga_acquisition_test_register(uint32_t writeval);
00196     void fpga_configure_tracking_gps_local_code(int32_t PRN);
00197     void fpga_compute_code_shift_parameters();
00198     void fpga_configure_code_parameters_in_fpga();
00199     void fpga_compute_signal_parameters_in_fpga();
00200     void fpga_configure_signal_parameters_in_fpga();
00201     void fpga_launch_multicorrelator_fpga();
00202     void read_tracking_gps_results();

```

```

00203     void close_device(void);
00204     void write_secondary_code(uint32_t secondary_code_length, std::string *secondary_code_string,
uint32_t reg_addr);
00205
00206     volk_gnssssdr::vector<uint32_t> d_initial_index;
00207     volk_gnssssdr::vector<uint32_t> d_initial_interp_counter;
00208
00209     uint64_t d_initial_sample_counter;
00210
00211     gr_complex *d_corr_out;
00212     gr_complex *d_Prompt_Data;
00213
00214     float *d_shifts_chips;
00215     float *d_prompt_data_shift;
00216
00217     float d_rem_code_phase_chips;
00218     float d_code_phase_step_chips;
00219     float d_code_phase_rate_step_chips;
00220     float d_rem_carrier_phase_in_rad;
00221     float d_phase_step_rad;
00222     float d_carrier_phase_rate_step_rad;
00223
00224     uint32_t d_code_length_samples;
00225     uint32_t d_n_correlators; // number of correlators
00226
00227     // data related to the hardware module and the driver
00228     int32_t d_device_descriptor; // driver descriptor
00229     volatile uint32_t *d_map_base; // driver memory map
00230
00231     // configuration data received from the interface
00232     uint32_t d_correlator_length_samples;
00233
00234     uint32_t d_code_phase_step_chips_num;
00235     uint32_t d_code_phase_rate_step_chips_num;
00236     int32_t d_rem_carr_phase_rad_int;
00237     int32_t d_phase_step_rad_int;
00238     int32_t d_carrier_phase_rate_step_rad_int;
00239
00240     // PRN codes
00241     int32_t *d_ca_codes;
00242     int32_t *d_data_codes;
00243
00244     // secondary code configuration
00245     uint32_t d_secondary_code_0_length;
00246     uint32_t d_secondary_code_1_length;
00247
00248     bool d_track_pilot;
00249     bool d_secondary_code_enabled;
00250 };
00251
00252
00253 /** @} */
00254 /** @} */
00255 #endif // GNSS_SDR_FPGA_MULTICORRELATOR_H

```

13.607 kf_conf.h

```

00001 /*!
00002  * \file Kf_conf.h
00003  * \brief Class that contains all the configuration parameters for generic tracking block based on a
Kalman Filter.
00004  * \author Javier Arribas, 2020. jarribas(at)cttc.es
00005  *
00006  * Class that contains all the configuration parameters for generic tracking block based on a DLL and
a PLL.
00007  *
00008  * -----
00009  *
00010  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00011  *
00012  * GNSS-SDR is a software defined Global Navigation
00013  * Satellite Systems receiver
00014  *
00015  * This file is part of GNSS-SDR.
00016  *
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022 #ifndef GNSS_SDR_Kf_CONF_H
00023 #define GNSS_SDR_Kf_CONF_H
00024
00025 #include "configuration_interface.h"

```

```

00026 #include <cstdint>
00027 #include <string>
00028
00029 class Kf_Conf
00030 {
00031 public:
00032     Kf_Conf();
00033     void SetFromConfiguration(const ConfigurationInterface *configuration, const std::string &role);
00034
00035     std::string item_type;
00036     std::string dump_filename;
00037     double fs_in;
00038     double carrier_lock_th;
00039
00040     // KF statistics
00041     // Measurement covariances (R)
00042     double code_disc_sd_chips;
00043     double carrier_disc_sd_rads;
00044
00045     // System covariances (Q)
00046     double code_phase_sd_chips;
00047     double carrier_phase_sd_rad;
00048     double carrier_freq_sd_hz;
00049     double carrier_freq_rate_sd_hz_s;
00050
00051     // initial Kalman covariance matrix (P)
00052     double init_code_phase_sd_chips;
00053     double init_carrier_phase_sd_rad;
00054     double init_carrier_freq_sd_hz;
00055     double init_carrier_freq_rate_sd_hz_s;
00056
00057     float early_late_space_chips;
00058     float very_early_late_space_chips;
00059     float early_late_space_narrow_chips;
00060     float very_early_late_space_narrow_chips;
00061     float slope;
00062     float spc;
00063     float y_intercept;
00064     float cn0_smoother_alpha;
00065     float carrier_lock_test_smoother_alpha;
00066     uint32_t pull_in_time_s;
00067     uint32_t bit_synchronization_time_limit_s;
00068     uint32_t vector_length;
00069     uint32_t smoother_length;
00070     int32_t extend_correlation_symbols;
00071     int32_t cn0_samples;
00072     int32_t cn0_smoother_samples;
00073     int32_t carrier_lock_test_smoother_samples;
00074     int32_t cn0_min;
00075     int32_t max_code_lock_fail;
00076     int32_t max_carrier_lock_fail;
00077     char signal[3]{};
00078     char system;
00079     bool track_pilot;
00080     bool enable_doppler_correction;
00081     bool high_dyn;
00082     bool dump;
00083     bool dump_mat;
00084 };
00085
00086 #endif

```

13.608 lock_detectors.h File Reference

Interface of a library with a set of code and carrier phase lock detectors.

```
#include <gnuradio/gr_complex.h>
```

Functions

- float [cn0_svn_estimator](#) (const gr_complex *Prompt_buffer, int length, float coh_integration_time_s)
cn0_svn_estimator is a Carrier-to-Noise (CN0) estimator based on the Signal-to-Noise Variance (SNV) estimator
- float [cn0_m2m4_estimator](#) (const gr_complex *Prompt_buffer, int length, float coh_integration_time_s)
cn0_m2m4_estimator is a Carrier-to-Noise (CN0) estimator based on the Second- and Fourth-Order Moments Method (M2M4)
- float [carrier_lock_detector](#) (const gr_complex *Prompt_buffer, int length)
A carrier lock detector.

13.608.1 Detailed Description

Interface of a library with a set of code and carrier phase lock detectors.

SNV_CN0 is a Carrier-to-Noise (CN0) estimator based on the Signal-to-Noise Variance (SNV) estimator [1]. Carrier lock detector using normalised estimate of the cosine of twice the carrier phase error [2].

[1] Marco Pini, Emanuela Falletti and Maurizio Fantino, "Performance Evaluation of C/N0 Estimators using a Real Time GNSS Software Receiver," IEEE 10th International Symposium on Spread Spectrum Techniques and Applications, pp.28-30, August 2008.

[2] Van Dierendonck, A.J. (1996), Global Positioning System: Theory and Applications, Volume I, Chapter 8: GPS Receivers, AJ Systems, Los Altos, CA 94024. Inc.: 329-407.

Authors

- Javier Arribas, 2011. jarribas(at)cttc.es
- Luis Esteve, 2012. luis(at)epsilon-formacion.com

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 Definition in file [lock_detectors.h](#).

13.609 lock_detectors.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file lock_detectors.h
00003  * \brief Interface of a library with a set of code and carrier phase lock detectors.
00004  *
00005  * SNV_CN0 is a Carrier-to-Noise (CN0) estimator
00006  * based on the Signal-to-Noise Variance (SNV) estimator [1].
00007  * Carrier lock detector using normalised estimate of the cosine
00008  * of twice the carrier phase error [2].
00009  *
00010  * [1] Marco Pini, Emanuela Falletti and Maurizio Fantino, "Performance
00011  * Evaluation of C/N0 Estimators using a Real Time GNSS Software Receiver,"
00012  * IEEE 10th International Symposium on Spread Spectrum Techniques and
00013  * Applications, pp.28-30, August 2008.
00014  *
00015  * [2] Van Dierendonck, A.J. (1996), Global Positioning System: Theory and
00016  * Applications,
00017  * Volume I, Chapter 8: GPS Receivers, AJ Systems, Los Altos, CA 94024.
00018  * Inc.: 329-407.
00019  * \authors <ul>
00020  * <li> Javier Arribas, 2011. jarribas(at)cttc.es
00021  * <li> Luis Esteve, 2012. luis(at)epsilon-formacion.com
00022  * </ul>
00023  *
00024  * -----
00025  *
00026  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00027  * This file is part of GNSS-SDR.
00028  *
00029  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00030  * SPDX-License-Identifier: GPL-3.0-or-later
00031  *
00032  * -----
00033  */
00034
00035 #ifndef GNSS_SDR_LOCK_DETECTORS_H
00036 #define GNSS_SDR_LOCK_DETECTORS_H
00037
00038 #include <gnuradio/gr_complex.h>
00039
00040 /** \addtogroup Tracking
00041  * \{ */
00042 /** \addtogroup Tracking_libs
00043  * \{ */
00044
00045
00046 /*! \brief cn0_svn_estimator is a Carrier-to-Noise (CN0) estimator
00047  * based on the Signal-to-Noise Variance (SNV) estimator
00048  *
00049  * Signal-to-Noise (SNR) ( $\rho$ ) estimator using the Signal-to-Noise Variance (SNV) estimator:
00050  * 
$$\hat{\rho} = \frac{\hat{P}_s}{\hat{P}_n} = \frac{\hat{P}_s}{\hat{P}_{tot} - \hat{P}_s},$$

00051  * where  $\hat{P}_s = \left( \frac{1}{N} \sum_{i=0}^{N-1} |\text{Re}(P(i))|^2 \right)$  is the estimation of
00052  * the signal power,
```

```

00054 * \f$ \hat{P}_{tot}=\frac{1}{N}\sum_{i=0}^{N-1}|Pc(i)|^2 \f$ is the estimator of the total power, \f$
|\cdot| \f$ is the absolute value,
00055 * \f$ Re(\cdot) \f$ stands for the real part of the value, and \f$ Pc(i) \f$ is the prompt correlator
output for the sample index i.
00056 *
00057 * The SNR value is converted to CN0 [dB-Hz], taking into account the coherent integration time, using
the following formula:
00058 * \f{equation}
00059 * CN0_{dB}=10*\log(\hat{\rho})-10*\log(T_{int}),
00060 * \f{
00061 * where \f$ T_{int} \f$ is the coherent integration time, in seconds.
00062 *
00063 * Ref: Marco Pini, Emanuela Falletti and Maurizio Fantino, "Performance
00064 * Evaluation of C/N0 Estimators using a Real Time GNSS Software Receiver,"
00065 * IEEE 10th International Symposium on Spread Spectrum Techniques and
00066 * Applications, pp.28-30, August 2008.
00067 */
00068 float cn0_svn_estimator(const gr_complex* Prompt_buffer, int length, float coh_integration_time_s);
00069
00070
00071 /*! \brief cn0_m2m4_estimator is a Carrier-to-Noise (CN0) estimator
00072 * based on the Second- and Fourth-Order Moments Method (M2M4)
00073 *
00074 * Signal-to-Noise (SNR) (\f$ \rho \f$) estimator using the Moments Method:
00075 * \f{equation}
00076 * \hat{\rho}=\frac{\sqrt{2} \hat{M}_2^2 - \hat{M}_4}{\hat{M}_2-\sqrt{2} \hat{M}_2^2 - \hat{M}_4}},
00077 * \f{
00078 * where
00079 * \f$ \hat{M}_2=\frac{1}{N}\sum_{k=0}^{K-1}|P[k]|^2 \f$, \f$ \hat{M}_4 =
\frac{1}{K}\sum_{k=0}^{K-1}|P[k]|^4 \f$, \f$ |\cdot| \f$ is the absolute value,
00080 * and \f$ P[k] \f$ is the prompt correlator output for the sample index k.
00081 *
00082 * The SNR value is converted to CN0 [dB-Hz] taking into account the coherent integration time, using
the following formula:
00083 * \f{equation}
00084 * CN0_{dB}=10*\log(\hat{\rho})-10*\log(T_{int}),
00085 * \f{
00086 * where \f$ T_{int} \f$ is the coherent integration time, in seconds.
00087 *
00088 * Ref: D. R. Pauluzzi, N. C. Beaulieu, "A comparison of SNR estimation
00089 * techniques for the AWGN channel," IEEE Trans. on Comm., vol. 48,
00090 * no. 10, pp. 1681-1691, Oct. 2000.
00091 */
00092 float cn0_m2m4_estimator(const gr_complex* Prompt_buffer, int length, float coh_integration_time_s);
00093
00094
00095 /*! \brief A carrier lock detector
00096 *
00097 * The Carrier Phase Lock Detector block uses the estimate of the cosine of twice the carrier phase
error is given by
00098 * \f{equation}
00099 * C2\phi=\frac{NBD}{NBP},
00100 * \f{
00101 * where \f$ NBD=(\sum_{i=0}^{N-1}|Im(Pc(i))|^2+(\sum_{i=0}^{N-1}|Re(Pc(i))|^2) \f$,
00102 * \f$ NBP=\sum_{i=0}^{N-1}|Im(Pc(i))|^2-\sum_{i=0}^{N-1}|Re(Pc(i))|^2 \f$, and
00103 * \f$ Pc(i) \f$ is the prompt correlator output for the sample index i.
00104 * Ref: Van Dierendonck, A.J. (1996), Global Positioning System: Theory and
00105 * Applications,
00106 * Volume I, Chapter 8: GPS Receivers, AJ Systems, Los Altos, CA 94024.
00107 * Inc.: 329-407.
00108 */
00109 float carrier_lock_detector(const gr_complex* Prompt_buffer, int length);
00110
00111
00112 /** \} */
00113 /** \} */
00114 #endif // GNSS_SDR_LOCK_DETECTORS_H

```

13.610 nonlinear_tracking.h File Reference

Interface of a library for nonlinear tracking algorithms.

```
#include <armadillo>
```

```
#include <gnuradio/gr_complex.h>
```

Classes

- class [ModelFunction](#)
- class [CubatureFilter](#)
- class [UnscentedFilter](#)

13.610.1 Detailed Description

Interface of a library for nonlinear tracking algorithms.

[CubatureFilter](#) implements the functionality of the Cubature Kalman Filter, which uses multidimensional cubature rules to estimate the time evolution of a nonlinear system. [UnscentedFilter](#) implements an Unscented Kalman Filter which uses Unscented Transform rules to perform a similar estimation.

[1] I Arasaratnam and S Haykin. Cubature kalman filters. IEEE Transactions on Automatic Control, 54(6):1254–1269,2009.

Authors

- Gerald LaMountain, 2019. gerald(at)ece.neu.edu
- Jordi Vila-Valls 2019. jvila(at)cttc.es

13.610.1.1

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Definition in file [nonlinear_tracking.h](#).

13.611 nonlinear_tracking.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file nonlinear_tracking.h
00003  * \brief Interface of a library for nonlinear tracking algorithms
00004  *
00005  * CubatureFilter implements the functionality of the Cubature Kalman
00006  * Filter, which uses multidimensional cubature rules to estimate the
00007  * time evolution of a nonlinear system. UnscentedFilter implements
00008  * an Unscented Kalman Filter which uses Unscented Transform rules to
00009  * perform a similar estimation.
00010  *
00011  * [1] I Arasaratnam and S Haykin. Cubature kalman filters. IEEE
00012  * Transactions on Automatic Control, 54(6):1254-1269,2009.
00013  *
00014  * \authors <ul>
00015  *     <li> Gerald LaMountain, 2019. gerald(at)ece.neu.edu
00016  *     <li> Jordi Vila-Valls 2019. jvila(at)cttc.es
00017  * </ul>
00018  * -----
00019  *
00020  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00022  *
00023  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
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00025  *
00026  * -----
00027  */
00028
00029 #ifndef GNSS_SDR_NONLINEAR_TRACKING_H
00030 #define GNSS_SDR_NONLINEAR_TRACKING_H
00031
00032 #if ARMA_NO_BOUND_CHECKING
00033 #define ARMA_NO_DEBUG 1
00034 #endif
00035
00036 #include <armadillo>
00037 #include <gnuradio/gr_complex.h>
00038
00039 /** \addtogroup Tracking
00040  * \{ */
00041 /** \addtogroup Tracking_libs
00042  * \{ */
00043
00044
00045 // Abstract model function
00046 class ModelFunction
00047 {
00048 public:
00049     ModelFunction() {};
00050     virtual arma::vec operator()(const arma::vec& input) = 0;
00051     virtual ~ModelFunction() = default;
00052 };
00053
00054 class CubatureFilter
```

```

00055 {
00056 public:
00057     // Constructors and destructors
00058     CubatureFilter();
00059     explicit CubatureFilter(int nx);
00060     CubatureFilter(const arma::vec& x_pred_0, const arma::mat& P_x_pred_0);
00061     ~CubatureFilter() = default;
00062
00063     // Reinitialization function
00064     void initialize(const arma::mat& x_pred_0, const arma::mat& P_x_pred_0);
00065
00066     // Prediction and estimation
00067     void predict_sequential(const arma::vec& x_post, const arma::mat& P_x_post, ModelFunction*
transition_fcn, const arma::mat& noise_covariance);
00068     void update_sequential(const arma::vec& z_upd, const arma::vec& x_pred, const arma::mat& P_x_pred,
ModelFunction* measurement_fcn, const arma::mat& noise_covariance);
00069
00070     // Getters
00071     arma::mat get_x_pred() const;
00072     arma::mat get_P_x_pred() const;
00073     arma::mat get_x_est() const;
00074     arma::mat get_P_x_est() const;
00075 private:
00076     arma::vec x_pred_out;
00077     arma::mat P_x_pred_out;
00078     arma::vec x_est;
00079     arma::mat P_x_est;
00080 };
00081
00082
00083 class UnscentedFilter
00084 {
00085 public:
00086     // Constructors and destructors
00087     UnscentedFilter();
00088     explicit UnscentedFilter(int nx);
00089     UnscentedFilter(const arma::vec& x_pred_0, const arma::mat& P_x_pred_0);
00090     ~UnscentedFilter() = default;
00091
00092     // Reinitialization function
00093     void initialize(const arma::mat& x_pred_0, const arma::mat& P_x_pred_0);
00094
00095     // Prediction and estimation
00096     void predict_sequential(const arma::vec& x_post, const arma::mat& P_x_post, ModelFunction*
transition_fcn, const arma::mat& noise_covariance);
00097     void update_sequential(const arma::vec& z_upd, const arma::vec& x_pred, const arma::mat& P_x_pred,
ModelFunction* measurement_fcn, const arma::mat& noise_covariance);
00098
00099     // Getters
00100     arma::mat get_x_pred() const;
00101     arma::mat get_P_x_pred() const;
00102     arma::mat get_x_est() const;
00103     arma::mat get_P_x_est() const;
00104 private:
00105     arma::vec x_pred_out;
00106     arma::mat P_x_pred_out;
00107     arma::vec x_est;
00108     arma::mat P_x_est;
00109 };
00110
00111
00112 /** \} */
00113 /** \} */
00114 #endif // GNSS_SDR_NONLINEAR_TRACKING_H

```

13.612 tcp_communication.h File Reference

Interface of the TCP communication class.

```

#include "tcp_packet_data.h"
#include <boost/array.hpp>
#include <boost/asio.hpp>

```

Classes

- class [Tcp_Communication](#)

TCP communication class.

Macros

- `#define NUM_TX_VARIABLES_GALILEO_E1` 13
- `#define NUM_TX_VARIABLES_GPS_L1_CA` 9
- `#define NUM_RX_VARIABLES` 4

Typedefs

- using `b_io_context` = `boost::asio::io_service`

13.612.1 Detailed Description

Interface of the TCP communication class.

Author

David Pubill, 2011. [dpubill\(at\)cttc.es](mailto:dpubill(at)cttc.es)

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 Definition in file [tcp_communication.h](#).

13.613 tcp_communication.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002   * \file tcp_communication.h
00003   * \brief Interface of the TCP communication class
00004   * \author David Pubill, 2011. dpubill(at)cttc.es
00005   *
00006   *
00007   * -----
00008   *
00009   * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014   *
00015   * -----
00016   */
00017
00018 #ifndef GNSS_SDR_TCP_COMMUNICATION_H
00019 #define GNSS_SDR_TCP_COMMUNICATION_H
00020
00021 #include "tcp_packet_data.h"
00022 #include <boost/array.hpp>
00023 #include <boost/asio.hpp>
00024
00025 /** \addtogroup Tracking
00026  * \{ */
00027 /** \addtogroup Tracking_libs
00028  * \{ */
00029
00030
00031 #if USE_BOOST_ASIO_IO_CONTEXT
00032 using b_io_context = boost::asio::io_context;
00033 #else
00034 using b_io_context = boost::asio::io_service;
00035 #endif
00036
00037 #define NUM_TX_VARIABLES_GALILEO_E1 13
00038 #define NUM_TX_VARIABLES_GPS_L1_CA 9
00039 #define NUM_RX_VARIABLES 4
00040
00041 /*!
00042  * \brief TCP communication class
00043  */
00044 class Tcp_Communication
00045 {
00046 public:
00047     Tcp_Communication();
00048     ~Tcp_Communication() = default;
00049
00050     int listen_tcp_connection(size_t d_port_, size_t d_port_ch0_);
00051     void send_receive_tcp_packet_galileo_e1(boost::array<float, NUM_TX_VARIABLES_GALILEO_E1> buf,
        Tcp_Packet_Data *tcp_data_);

```



```

00052     void send_receive_tcp_packet_gps_ll_ca(boost::array<float, NUM_TX_VARIABLES_GPS_L1_CA> buf,
    Tcp_Packet_Data *tcp_data_);
00053     void close_tcp_connection(size_t d_port_);
00054
00055 private:
00056     b_io_context io_context_;
00057     boost::asio::ip::tcp::socket tcp_socket_;
00058 };
00059
00060
00061 /** \} */
00062 /** \} */
00063 #endif

```

13.614 tcp_packet_data.h File Reference

Interface of the TCP data packet class.

Classes

- class [Tcp_Packet_Data](#)
Class that implements a TCP data packet.

13.614.1 Detailed Description

Interface of the TCP data packet class.

Author

David Pubill, 2011. dpubill(at)cttc.es

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 Definition in file [tcp_packet_data.h](#).

13.615 tcp_packet_data.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file tcp_packet_data.h
00003  * \brief Interface of the TCP data packet class
00004  * \author David Pubill, 2011. dpubill(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_TCP_PACKET_DATA_H
00019 #define GNSS_SDR_TCP_PACKET_DATA_H
00020
00021 /** \addtogroup Tracking
00022  * \{ */
00023 /** \addtogroup Tracking_libs
00024  * \{ */
00025
00026
00027 /*!
00028  * \brief Class that implements a TCP data packet
00029  */
00030 class Tcp_Packet_Data
00031 {
00032 public:
00033     Tcp_Packet_Data() = default;
00034     ~Tcp_Packet_Data() = default;
00035     float proc_pack_code_error = 0.0;
00036     float proc_pack_carr_error = 0.0;

```

```

00037     float proc_pack_carrier_doppler_hz = 0.0;
00038 };
00039
00040
00041 /** \} */
00042 /** \} */
00043 #endif

```

13.616 tracking_2nd_DLL_filter.h File Reference

Interface of a 2nd order DLL filter for code tracking loop.

Classes

- class [Tracking_2nd_DLL_filter](#)

This class implements a 2nd order DLL filter for code tracking loop.

13.616.1 Detailed Description

Interface of a 2nd order DLL filter for code tracking loop.

Author

Javier Arribas, 2011. jarribas(at)cttc.es

Class that implements a 2nd order PLL filter for code tracking loop. The algorithm is described in: K.Borre, D.M. Akos, N.Bertelsen, P.Rinder, and S. H. Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007, Applied and Numerical Harmonic Analysis.

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Definition in file [tracking_2nd_DLL_filter.h](#).

13.617 tracking_2nd_DLL_filter.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file tracking_2nd_DLL_filter.h
00003  * \brief Interface of a 2nd order DLL filter for code tracking loop.
00004  * \author Javier Arribas, 2011. jarribas(at)cttc.es
00005  *
00006  * Class that implements a 2nd order PLL filter for code tracking loop.
00007  * The algorithm is described in:
00008  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S. H. Jensen,
00009  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach,
00010  * Birkhauser, 2007, Applied and Numerical Harmonic Analysis.
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.
00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_TRACKING_2ND_DLL_FILTER_H
00024 #define GNSS_SDR_TRACKING_2ND_DLL_FILTER_H
00025
00026 /** \addtogroup Tracking
00027  * \{ */
00028 /** \addtogroup Tracking_libs
00029  * \{ */
00030
00031
00032 /*!
00033  * \brief This class implements a 2nd order DLL filter for code tracking loop.
00034  *
00035  * The algorithm is described in:
00036  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S. H. Jensen, A Software-Defined GPS
00037  * and Galileo Receiver. A Single-Frequency Approach,
00038  * Birkhauser, 2007, Applied and Numerical Harmonic Analysis.

```

```

00039  */
00040  class Tracking_2nd_DLL_filter
00041  {
00042  public:
00043      Tracking_2nd_DLL_filter();
00044      ~Tracking_2nd_DLL_filter() = default;
00045      explicit Tracking_2nd_DLL_filter(float pdi_code);
00046
00047      void set_DLL_BW(float dll_bw_hz);          //!< Set DLL filter bandwidth [Hz]
00048      void set_pdi(float pdi_code);              //!< Set Summation interval for code [s]
00049      void initialize();                          //!< Start tracking with acquisition information
00050      float get_code_nco(float DLL_discriminator); //!< Numerically controlled oscillator
00051
00052  private:
00053      void calculate_lopp_coef(float* tau1, float* tau2, float lbw, float zeta, float k);
00054
00055      // PLL filter parameters
00056      float d_tau1_code = 0.0;
00057      float d_tau2_code = 0.0;
00058      float d_pdi_code = 0.0;
00059      float d_dllnoisebandwidth = 0.0;
00060      float d_dlldampingratio = 0.0;
00061      float d_old_code_error = 0.0;
00062      float d_old_code_nco = 0.0;
00063  };
00064
00065
00066  /** \} */
00067  /** \} */
00068  #endif

```

13.618 tracking_2nd_PLL_filter.h File Reference

Interface of a 2nd order PLL filter for carrier tracking loop.

Classes

- class [Tracking_2nd_PLL_filter](#)

This class implements a 2nd order PLL filter for carrier tracking loop.

13.618.1 Detailed Description

Interface of a 2nd order PLL filter for carrier tracking loop.

Author

Javier Arribas, 2011. jarribas(at)cttc.es

Class that implements 2 order PLL filter for tracking carrier loop. The algorithm is described in K.Borre, D.M. Akos, N.Bertelsen, P.Rinder, and S.H. Jensen, A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach, Birkhauser, 2007, Applied and Numerical Harmonic Analysis.

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Definition in file [tracking_2nd_PLL_filter.h](#).

13.619 tracking_2nd_PLL_filter.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file tracking_2nd_PLL_filter.h
00003  * \brief Interface of a 2nd order PLL filter for carrier tracking loop
00004  * \author Javier Arribas, 2011. jarribas(at)cttc.es
00005  *
00006  * Class that implements 2 order PLL filter for tracking carrier loop.
00007  * The algorithm is described in
00008  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S.H. Jensen,
00009  * A Software-Defined GPS and Galileo Receiver. A Single-Frequency Approach,
00010  * Birkhauser, 2007, Applied and Numerical Harmonic Analysis.
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.

```

```

00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_TRACKING_2ND_PLL_FILTER_H
00024 #define GNSS_SDR_TRACKING_2ND_PLL_FILTER_H
00025
00026 /** \addtogroup Tracking
00027  * \{ */
00028 /** \addtogroup Tracking_libs
00029  * \{ */
00030
00031
00032 /*!
00033  * \brief This class implements a 2nd order PLL filter for carrier tracking loop.
00034  *
00035  * The algorithm is described in:
00036  * K.Borre, D.M.Akos, N.Bertelsen, P.Rinder, and S. H. Jensen, A Software-Defined GPS and Galileo
00037  * Receiver. A Single-Frequency Approach,
00038  * Birkhauser, 2007, Applied and Numerical Harmonic Analysis.
00039  */
00039 class Tracking_2nd_PLL_filter
00040 {
00041 public:
00042     Tracking_2nd_PLL_filter();
00043     ~Tracking_2nd_PLL_filter() = default;
00044     explicit Tracking_2nd_PLL_filter(float pdi_carr);
00045
00046     void set_PLL_BW(float pll_bw_hz); //!< Set PLL loop bandwidth [Hz]
00047     void set_pdi(float pdi_carr);      //!< Set Summation interval for code [s]
00048     void initialize();
00049     float get_carrier_nco(float PLL_discriminator);
00050
00051 private:
00052     void calculate_lopp_coef(float* tau1, float* tau2, float lbw, float zeta, float k);
00053     // PLL filter parameters
00054     float d_tau1_carr = 0.0;
00055     float d_tau2_carr = 0.0;
00056     float d_pdi_carr = 0.0;
00057     float d_pllnoisebandwidth = 0.0;
00058     float d_plldampingratio = 0.0;
00059     float d_old_carr_error = 0.0;
00060     float d_old_carr_nco = 0.0;
00061 };
00062
00063
00064 /** \} */
00065 /** \} */
00066 #endif

```

13.620 tracking_discriminators.h File Reference

Interface of a library with a set of code tracking and carrier tracking discriminators.

```

#include <gnuradio/gr_complex.h>
#include <cmath>

```

Functions

- double [fll_four_quadrant_atan](#) (gr_complex prompt_s1, gr_complex prompt_s2, double t1, double t2)
- double [fll_diff_atan](#) (gr_complex prompt_s1, gr_complex prompt_s2, double t1, double t2)
- double [phase_unwrap](#) (double phase_rad)

Phase unwrapping function, input is [rad].
- double [pll_four_quadrant_atan](#) (gr_complex prompt_s1)

PLL four quadrant arctan discriminator.
- double [pll_cloop_two_quadrant_atan](#) (gr_complex prompt_s1)

PLL Costas loop two quadrant arctan discriminator.
- double [dll_nc_e_minus_l_normalized](#) (gr_complex early_s1, gr_complex late_s1, float spc=0.5, float slope=1.0, float y_intercept=1.0)

DLL Noncoherent Early minus Late envelope normalized discriminator.

- double [dll_nc_vemlp_normalized](#) (gr_complex very_early_s1, gr_complex early_s1, gr_complex late_s1, gr_complex very_late_s1)
DLL Noncoherent Very Early Minus Late Power (VEMLP) normalized discriminator.
- template<typename Fun>
double [CalculateSlope](#) (Fun &&f, double x)
- template<typename Fun>
double [CalculateSlopeAbs](#) (Fun &&f, double x)
- template<typename Fun>
double [GetYIntercept](#) (Fun &&f, double x)
- template<typename Fun>
double [GetYInterceptAbs](#) (Fun &&f, double x)
- template<int M = 1, int N = M>
double [SinBocCorrelationFunction](#) (double offset_in_chips)
- template<int M = 1, int N = M>
double [CosBocCorrelationFunction](#) (double offset_in_chips)

13.620.1 Detailed Description

Interface of a library with a set of code tracking and carrier tracking discriminators.

Authors

- Javier Arribas, 2011. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)
- Luis Esteve, 2012. [luis\(at\)epsilon-formacion.com](mailto:luis(at)epsilon-formacion.com)

Library with a set of code tracking and carrier tracking discriminators that is used by the tracking algorithms. GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR. Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors) SPDX-License-Identifier: GPL-3.0-or-later Definition in file [tracking_discriminators.h](#).

13.621 tracking_discriminators.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file tracking_discriminators.h
00003  * \brief Interface of a library with a set of code tracking and carrier
00004  * tracking discriminators.
00005  * \authors <ul>
00006  *      <li> Javier Arribas, 2011. jarribas\(at\)cttc.es
00007  *      <li> Luis Esteve, 2012. luis\(at\)epsilon-formacion.com
00008  *      </ul>
00009  *
00010  * Library with a set of code tracking and carrier tracking discriminators
00011  * that is used by the tracking algorithms.
00012  *
00013  * -----
00014  *
00015  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00016  * This file is part of GNSS-SDR.
00017  *
00018  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00019  * SPDX-License-Identifier: GPL-3.0-or-later
00020  *
00021  * -----
00022  */
00023
00024 #ifndef GNSS_SDR_TRACKING_DISCRIMINATORS_H
00025 #define GNSS_SDR_TRACKING_DISCRIMINATORS_H
00026
00027 #include <gnuradio/gr_complex.h>
00028 #include <cmath>
00029
00030 /** \addtogroup Tracking
00031  * \{ */
00032 /** \addtogroup Tracking_libs
00033  * \{ */
00034
00035
00036 /*! brief FLL four quadrant arctan discriminator
00037  *
00038  * FLL four quadrant arctan discriminator:
```

```

00039 * \f{equation}
00040 * \frac{\phi_2-\phi_1}{t_2-t_1}=\frac{\text{ATAN2}(\text{cross},\text{dot})}{t_1-t_2},
00041 * \f{
00042 * where \f{cross}=I_{PS1}Q_{PS2}-I_{PS2}Q_{PS1}\f{ and \f{dot}=I_{PS1}I_{PS2}+Q_{PS1}Q_{PS2}\f{,
00043 * \f{I_{PS1},Q_{PS1}\f{ are the inphase and quadrature prompt correlator outputs respectively at
sample time \f{t_1}\f{, and
00044 * \f{I_{PS2},Q_{PS2}\f{ are the inphase and quadrature prompt correlator outputs respectively at
sample time \f{t_2}\f{. The output is in [radians/second]}.
00045 */
00046 double fll_four_quadrant_atan(gr_complex prompt_s1, gr_complex prompt_s2, double t1, double t2);
00047
00048
00049 /*
00050 * FLL differential arctan discriminator:
00051 * \f{equation}
00052 *
e_{atan}(k)=\frac{1}{t_1-t_2}\text{phase\_unwrap}(\tan^{-1}(\frac{Q(k)}{I(k)})-\tan^{-1}(\frac{Q(k-1)}{I(k-1)}))
00053 * \f{
00054 * The output is in [radians/second].
00055 */
00056 double fll_diff_atan(gr_complex prompt_s1, gr_complex prompt_s2, double t1, double t2);
00057
00058
00059 /*! \brief Phase unwrapping function, input is [rad]
00060 */
00061 double phase_unwrap(double phase_rad);
00062
00063
00064 /*! \brief PLL four quadrant arctan discriminator
00065 *
00066 * PLL four quadrant arctan discriminator:
00067 * \f{equation}
00068 * \phi=\text{ATAN2}(Q_{PS},I_{PS}),
00069 * \f{
00070 * where \f{I_{PS1},Q_{PS1}\f{ are the inphase and quadrature prompt correlator outputs respectively.
The output is in [radians]}.
00071 */
00072 double pll_four_quadrant_atan(gr_complex prompt_s1);
00073
00074
00075 /*! \brief PLL Costas loop two quadrant arctan discriminator
00076 *
00077 * PLL Costas loop two quadrant arctan discriminator:
00078 * \f{equation}
00079 * \phi=\text{ATAN}\left(\frac{Q_{PS}}{I_{PS}}\right),
00080 * \f{
00081 * where \f{I_{PS1},Q_{PS1}\f{ are the inphase and quadrature prompt correlator outputs respectively.
The output is in [radians]}.
00082 */
00083 double pll_cloop_two_quadrant_atan(gr_complex prompt_s1);
00084
00085
00086 /*! \brief DLL Noncoherent Early minus Late envelope normalized discriminator
00087 *
00088 * DLL Noncoherent Early minus Late envelope normalized discriminator:
00089 * \f{equation}
00090 * error = \frac{y_{\text{intercept}} - \text{slope} * \epsilon}{\text{slope}} \frac{E-L}{E+L},
00091 * \f{
00092 * where \f{E}=\sqrt{I_{ES}^2+Q_{ES}^2}\f{ is the Early correlator output absolute value and
00093 * \f{L}=\sqrt{I_{LS}^2+Q_{LS}^2}\f{ is the Late correlator output absolute value. The output is in
[chips]}.
00094 */
00095 double dll_nc_e_minus_l_normalized(gr_complex early_s1, gr_complex late_s1, float spc = 0.5, float
slope = 1.0, float y_intercept = 1.0);
00096
00097
00098 /*! \brief DLL Noncoherent Very Early Minus Late Power (VEMLP) normalized discriminator
00099 *
00100 * DLL Noncoherent Very Early Minus Late Power (VEMLP) normalized discriminator, using the outputs
00101 * of four correlators, Very Early (VE), Early (E), Late (L) and Very Late (VL):
00102 * \f{equation}
00103 * error=\frac{E-L}{E+L},
00104 * \f{
00105 * where \f{E}=\sqrt{I_{VE}^2+Q_{VE}^2+I_{E}^2+Q_{E}^2}\f{ and
00106 * \f{L}=\sqrt{I_{VL}^2+Q_{VL}^2+I_{L}^2+Q_{L}^2}\f{. The output is in [chips]}.
00107 */
00108 double dll_nc_vemlp_normalized(gr_complex very_early_s1, gr_complex early_s1, gr_complex late_s1,
gr_complex very_late_s1);
00109
00110
00111 template <typename Fun>
00112 double CalculateSlope(Fun &&f, double x)
00113 {
00114     static constexpr double dx = 1e-6;
00115     return (f(x + dx / 2.0) - f(x - dx / 2.0)) / dx;
00116 }
00117

```

```

00118
00119 template <typename Fun>
00120 double CalculateSlopeAbs(Fun &&f, double x)
00121 {
00122     static constexpr double dx = 1e-6;
00123
00124     return (std::abs(f(x + dx / 2.0)) - std::abs(f(x - dx / 2.0))) / dx;
00125 }
00126
00127 template <typename Fun>
00128 double GetYIntercept(Fun &&f, double x)
00129 {
00130     double slope = CalculateSlope(f, x);
00131     double y1 = f(x);
00132
00133     return y1 - slope * x;
00134 }
00135
00136 template <typename Fun>
00137 double GetYInterceptAbs(Fun &&f, double x)
00138 {
00139     double slope = CalculateSlopeAbs(f, x);
00140     double y1 = std::abs(f(x));
00141     return y1 - slope * x;
00142 }
00143
00144 // SinBocCorrelationFunction and CosBocCorrelationFunction from
00145 // Sousa, F. and Nunes, F., "New Expressions for the Autocorrelation
00146 // Function of BOC GNSS Signals", NAVIGATION - Journal of the Institute
00147 // of Navigation, March 2013.
00148 //
00149 template <int M = 1, int N = M>
00150 double SinBocCorrelationFunction(double offset_in_chips)
00151 {
00152     static constexpr int TWO_P = 2 * M / N;
00153
00154     double abs_tau = std::abs(offset_in_chips);
00155
00156     if (abs_tau > 1.0)
00157     {
00158         return 0.0;
00159     }
00160
00161     int k = static_cast<int>(std::ceil(TWO_P * abs_tau));
00162
00163     double sgn = ((k & 0x01) == 0 ? 1.0 : -1.0); // (-1)^k
00164
00165     return sgn * (2.0 * (k * k - k * TWO_P - k) / TWO_P + 1.0 +
00166                 (2 * TWO_P - 2 * k + 1) * abs_tau);
00167 }
00168
00169
00170 template <int M = 1, int N = M>
00171 double CosBocCorrelationFunction(double offset_in_chips)
00172 {
00173     static constexpr int TWO_P = 2 * M / N;
00174
00175     double abs_tau = std::abs(offset_in_chips);
00176
00177     if (abs_tau > 1.0)
00178     {
00179         return 0.0;
00180     }
00181
00182     int k = static_cast<int>(std::floor(2.0 * TWO_P * abs_tau));
00183
00184     if ((k & 0x01) == 0) // k is even
00185     {
00186         double sgn = ((k >> 1) & 0x01 ? -1.0 : 1.0); // (-1)^(k/2)
00187
00188         return sgn * ((2 * k * TWO_P + 2 * TWO_P - k * k) / (2.0 * TWO_P) + (-2 * TWO_P + k - 1) *
00189             abs_tau);
00190     }
00191     else
00192     {
00193         double sgn = (((k + 1) >> 1) & 0x01 ? -1.0 : 1.0); // (-1)^((k+1)/2)
00194
00195         return sgn * ((k * k + 2 * k - 2 * k * TWO_P + 1) / (2.0 * TWO_P) + (2 * TWO_P - k - 2) *
00196             abs_tau);
00197     }
00198 }
00199 /** \} */
00200 /** \} */
00201 #endif // GNSS_SDR_TRACKING_DISCRIMINATORS_H

```

13.622 tracking_FLL_PLL_filter.h File Reference

Interface of a hybrid FLL and PLL filter for tracking carrier loop.

Classes

- class [Tracking_FLL_PLL_filter](#)

This class implements a hybrid FLL and PLL filter for tracking carrier loop.

13.622.1 Detailed Description

Interface of a hybrid FLL and PLL filter for tracking carrier loop.

Author

Javier Arribas, 2011. jarribas(at)cttc.es

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Definition in file [tracking_FLL_PLL_filter.h](#).

13.623 tracking_FLL_PLL_filter.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file tracking_FLL_PLL_filter.h
00003  * \brief Interface of a hybrid FLL and PLL filter for tracking carrier loop
00004  * \author Javier Arribas, 2011. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_TRACKING_FLL_PLL_FILTER_H
00018 #define GNSS_SDR_TRACKING_FLL_PLL_FILTER_H
00019
00020 /** \addtogroup Tracking
00021  * \{ */
00022 /** \addtogroup Tracking_libs
00023  * \{ */
00024
00025
00026  /*!
00027  * \brief This class implements a hybrid FLL and PLL filter for tracking carrier loop
00028  */
00029  class Tracking_FLL_PLL_filter
00030  {
00031  public:
00032      Tracking_FLL_PLL_filter() = default;
00033      ~Tracking_FLL_PLL_filter() = default;
00034      void set_params(float fll_bw_hz, float pll_bw_hz, int order);
00035      void initialize(float d_acq_carrier_doppler_hz);
00036      float get_carrier_error(float FLL_discriminator, float PLL_discriminator, float
correlation_time_s);
00037
00038  private:
00039      // FLL + PLL filter parameters
00040      float d_pll_w{0.0};
00041      float d_pll_w0p3{0.0};
00042      float d_pll_w0f2{0.0};
00043      float d_pll_x{0.0};
00044      float d_pll_a2{0.0};
00045      float d_pll_w0f{0.0};
00046      float d_pll_a3{0.0};
00047      float d_pll_w0p2{0.0};
00048      float d_pll_b3{0.0};
00049      float d_pll_w0p{0.0};
00050      int d_order{0};
00051  };
00052

```



```

00053
00054 /** \} */
00055 /** \} */
00056 #endif

```

13.624 tracking_loop_filter.h File Reference

Generic 1st to 3rd order loop filter implementation.

#include <vector>

Classes

- class [Tracking_loop_filter](#)

This class implements a generic 1st, 2nd or 3rd order loop filter.

13.624.1 Detailed Description

Generic 1st to 3rd order loop filter implementation.

Author

Cillian O'Driscoll, 2015. [cillian.odriscoll\(at\)gmail.com](mailto:cillian.odriscoll(at)gmail.com)

Class implementing a generic 1st, 2nd or 3rd order loop filter. Based on the bilinear transform of the standard Wiener filter.

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Definition in file [tracking_loop_filter.h](#).

13.625 tracking_loop_filter.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file tracking_loop_filter.h
00003  * \brief Generic 1st to 3rd order loop filter implementation
00004  * \author Cillian O'Driscoll, 2015. cillian.odriscoll\(at\)gmail.com
00005  *
00006  * Class implementing a generic 1st, 2nd or 3rd order loop filter. Based
00007  * on the bilinear transform of the standard Wiener filter.
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_TRACKING_LOOP_FILTER_H
00021 #define GNSS_SDR_TRACKING_LOOP_FILTER_H
00022
00023 #include <vector>
00024
00025 /** \addtogroup Tracking
00026  * \{ */
00027 /** \addtogroup Tracking_libs
00028  * \{ */
00029
00030
00031 /*!
00032  * \brief This class implements a generic 1st, 2nd or 3rd order loop filter
00033  *
00034  */
00035 class Tracking_loop_filter
00036 {
00037 public:
00038     Tracking_loop_filter();
00039     ~Tracking_loop_filter() = default;

```

```

00040
00041     Tracking_loop_filter(float update_interval, float noise_bandwidth,
00042         int loop_order = 2,
00043         bool include_last_integrator = false);
00044
00045     Tracking_loop_filter(Tracking_loop_filter&&) = default;          //!< Move operator
00046     Tracking_loop_filter& operator=(Tracking_loop_filter&& /*other*/) = default;  //!< Move assignment
operator
00047
00048     float get_noise_bandwidth() const;
00049     float get_update_interval() const;
00050     bool get_include_last_integrator() const;
00051     int get_order() const;
00052
00053     void set_noise_bandwidth(float noise_bandwidth);
00054     void set_update_interval(float update_interval);
00055     void set_include_last_integrator(bool include_last_integrator);
00056     void set_order(int loop_order);
00057
00058     void initialize(float initial_output = 0.0);
00059     float apply(float current_input);
00060
00061 private:
00062     // Compute the filter coefficients:
00063     void update_coefficients();
00064
00065     // Store the last inputs and outputs:
00066     std::vector<float> d_inputs;
00067     std::vector<float> d_outputs;
00068
00069     // Store the filter coefficients:
00070     std::vector<float> d_input_coefficients;
00071     std::vector<float> d_output_coefficients;
00072
00073     // The noise bandwidth (in Hz)
00074     // Note this is an approximation only valid when the product of this
00075     // number and the update interval (T) is small.
00076     float d_noise_bandwidth;
00077
00078     // Loop update interval
00079     float d_update_interval;
00080
00081     // The loop order:
00082     int d_loop_order;
00083
00084     // The current index in the i/o arrays:
00085     int d_current_index;
00086
00087     // Should the last integrator be included?
00088     bool d_include_last_integrator;
00089 };
00090
00091
00092 /** \} */
00093 /** \} */
00094 #endif // GNSS_SDR_TRACKING_LOOP_FILTER_H

```

13.626 acquisition_interface.h File Reference

Header file of the interface to an acquisition GNSS block.

```

#include "gnss_block_interface.h"
#include "gnss_synchro.h"
#include <memory>

```

Classes

- class [AcquisitionInterface](#)

This abstract class represents an interface to an acquisition GNSS block.

13.626.1 Detailed Description

Header file of the interface to an acquisition GNSS block.

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com Luis Esteve, 2011. luis(at)epsilon-formacion.com

This header file contains the interface to an abstract class for acquisition algorithms. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

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Definition in file [acquisition_interface.h](#).

13.627 acquisition_interface.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file acquisition_interface.h
00003  * \brief Header file of the interface to an acquisition GNSS block.
00004  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00005  *         Luis Esteve, 2011. luis(at)epsilon-formacion.com
00006  *
00007  * This header file contains the interface to an abstract class
00008  * for acquisition algorithms. Since all its methods are virtual,
00009  * this class cannot be instantiated directly, and a subclass can only be
00010  * instantiated directly if all inherited pure virtual methods have been
00011  * implemented by that class or a parent class.
00012  *
00013  * -----
00014  *
00015  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00016  * This file is part of GNSS-SDR.
00017  *
00018  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00019  * SPDX-License-Identifier: GPL-3.0-or-later
00020  *
00021  * -----
00022  */
00023
00024 #ifndef GNSS_SDR_ACQUISITION_INTERFACE_H
00025 #define GNSS_SDR_ACQUISITION_INTERFACE_H
00026
00027 #include "gnss_block_interface.h"
00028 #include "gnss_synchro.h"
00029 #include <memory>
00030
00031 /** \addtogroup Core
00032  * \{ */
00033 /** \addtogroup GNSS_Block_Interfaces GNSS block interfaces
00034  * GNSS block interfaces.
00035  * \{ */
00036
00037
00038 template <typename Data>
00039 class Concurrent_Queue;
00040
00041 class ChannelFsm;
00042
00043 /*! \brief This abstract class represents an interface to an acquisition GNSS block.
00044  *
00045  * Abstract class for acquisition algorithms. Since all its methods are virtual,
00046  * this class cannot be instantiated directly, and a subclass can only be
00047  * instantiated directly if all inherited pure virtual methods have been
00048  * implemented by that class or a parent class.
00049  */
00050 class AcquisitionInterface : public GNSSBlockInterface
00051 {
00052 public:
00053     virtual void set_gnss_synchro(Gnss_Synchro* gnss_synchro) = 0;
00054     virtual void set_channel(unsigned int channel_id) = 0;
00055     virtual void set_channel_fsm(std::weak_ptr<ChannelFsm> channel_fsm) = 0;
00056     virtual void set_doppler_center(int /*doppler_center*/) {}
00057     virtual void set_local_code() = 0;
00058     virtual signed int mag() = 0;
00059     virtual void reset() = 0;
00060     virtual void stop_acquisition() = 0;
00061     virtual void set_resampler_latency(uint32_t latency_samples) = 0;
00062 };
00063
00064
00065 /** \} */
00066 /** \} */
00067 #endif // GNSS_SDR_ACQUISITION_INTERFACE */

```

13.628 channel_interface.h File Reference

This class represents an interface to a channel GNSS block.

```
#include "gnss_block_interface.h"
#include "gnss_signal.h"
```

Classes

- class [ChannelInterface](#)

This abstract class represents an interface to a channel GNSS block.

13.628.1 Detailed Description

This class represents an interface to a channel GNSS block.

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com Luis Esteve, 2011. luis(at)epsilon-formacion.com

Abstract class for channel blocks. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

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Definition in file [channel_interface.h](#).

13.629 channel_interface.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file channel_interface.h
00003  * \brief This class represents an interface to a channel GNSS block.
00004  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00005  *         Luis Esteve, 2011. luis(at)epsilon-formacion.com
00006  *
00007  * Abstract class for channel blocks. Since all its methods are virtual,
00008  * this class cannot be instantiated directly, and a subclass can only be
00009  * instantiated directly if all inherited pure virtual methods have been
00010  * implemented by that class or a parent class.
00011  *
00012  * -----
00013  *
00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.
00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_CHANNEL_INTERFACE_H
00024 #define GNSS_SDR_CHANNEL_INTERFACE_H
00025
00026 #include "gnss_block_interface.h"
00027 #include "gnss_signal.h"
00028
00029 /** \addtogroup Core
00030  *  \{ */
00031 /** \addtogroup GNSS_Block_Interfaces
00032  *  \{ */
00033
00034
00035 /*!
00036  * \brief This abstract class represents an interface to a channel GNSS block.
00037  *
00038  * Abstract class for channel blocks. Since all its methods are pure virtual,
00039  * this class cannot be instantiated directly, and a subclass can only be
00040  * instantiated directly if all inherited pure virtual methods have been
00041  * implemented by that class or a parent class.
00042  */
00043 class ChannelInterface : public GNSSBlockInterface
00044 {
```

```

00045 public:
00046     virtual gr::basic_block_sptr get_left_block_trk() = 0;
00047     virtual gr::basic_block_sptr get_right_block_trk() = 0;
00048     virtual gr::basic_block_sptr get_left_block_acq() = 0;
00049     virtual gr::basic_block_sptr get_right_block_acq() = 0;
00050     virtual gr::basic_block_sptr get_left_block() = 0;
00051     virtual gr::basic_block_sptr get_right_block() = 0;
00052     virtual Gnss_Signal get_signal() = 0;
00053     virtual void start_acquisition() = 0;
00054     virtual void assist_acquisition_doppler(double Carrier_Doppler_hz) = 0;
00055     virtual void stop_channel() = 0;
00056     virtual void set_signal(const Gnss_Signal&) = 0;
00057 };
00058
00059
00060 /** \} */
00061 /** \} */
00062 #endif // GNSS_SDR_CHANNEL_INTERFACE_H

```

13.630 configuration_interface.h File Reference

This class represents an interface to configuration parameters.

```

#include <stdint>
#include <string>

```

Classes

- class [ConfigurationInterface](#)

This abstract class represents an interface to configuration parameters.

13.630.1 Detailed Description

This class represents an interface to configuration parameters.

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com

The interface defines an accessor method that gets a parameter name as input and returns the value of this parameter, a string, as output. Property names are defined here. This is an abstract class for interfaces.

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Definition in file [configuration_interface.h](#).

13.631 configuration_interface.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file configuration_interface.h
00003  * \brief This class represents an interface to configuration parameters.
00004  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00005  *
00006  * The interface defines an accessor method that gets a parameter name as input
00007  * and returns the value of this parameter, a string, as output.
00008  * Property names are defined here. This is an abstract class for interfaces.
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_CONFIGURATION_INTERFACE_H
00022 #define GNSS_SDR_CONFIGURATION_INTERFACE_H
00023
00024 #include <stdint>

```

```

00025 #include <string>
00026
00027 /** \addtogroup Core
00028  * \{ */
00029 /** \addtogroup GNSS_Block_Interfaces
00030  * \{ */
00031
00032
00033 /*!
00034  * \brief This abstract class represents an interface to configuration parameters.
00035  *
00036  * The interface defines an accessor method that gets a parameter name as input
00037  * and returns the value of this parameter, a string, as output.
00038  * Property names are defined here. This is an abstract class for interfaces.
00039  * Since all its methods are virtual,
00040  * this class cannot be instantiated directly, and a subclass can only be
00041  * instantiated directly if all inherited pure virtual methods have been
00042  * implemented by that class or a parent class.
00043  */
00044 class ConfigurationInterface
00045 {
00046 public:
00047     virtual ~ConfigurationInterface() = default;
00048     virtual std::string property(std::string property_name, std::string default_value) const = 0;
00049     virtual bool property(std::string property_name, bool default_value) const = 0;
00050     virtual int64_t property(std::string property_name, int64_t default_value) const = 0;
00051     virtual uint64_t property(std::string property_name, uint64_t default_value) const = 0;
00052     virtual int32_t property(std::string property_name, int32_t default_value) const = 0;
00053     virtual uint32_t property(std::string property_name, uint32_t default_value) const = 0;
00054     virtual int16_t property(std::string property_name, int16_t default_value) const = 0;
00055     virtual uint16_t property(std::string property_name, uint16_t default_value) const = 0;
00056     virtual float property(std::string property_name, float default_value) const = 0;
00057     virtual double property(std::string property_name, double default_value) const = 0;
00058     virtual void set_property(std::string property_name, std::string value) = 0;
00059     virtual bool is_present(const std::string& property_name) const = 0;
00060 };
00061
00062
00063 /** \} */
00064 /** \} */
00065 #endif // GNSS_SDR_CONFIGURATION_INTERFACE_H

```

13.632 gnss_block_interface.h File Reference

This interface represents a GNSS block.

```

#include <gnuradio/top_block.h>
#include <cassert>
#include <string>
#include <utility>
#include <boost/make_shared.hpp>
#include <boost/shared_ptr.hpp>

```

Classes

- class [GNSSBlockInterface](#)
This abstract class represents an interface to GNSS blocks.

Typedefs

- template<typename T>
using [gnss_shared_ptr](#) = boost::shared_ptr<T>

Functions

- template<typename C, typename... Args>
[gnss_shared_ptr](#)< C > [gnss_make_shared](#) (Args &&... args)

13.632.1 Detailed Description

This interface represents a GNSS block.

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com

Abstract class for GNSS block interfaces. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

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Definition in file [gnss_block_interface.h](#).

13.633 gnss_block_interface.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gnss_block_interface.h
00003  * \brief This interface represents a GNSS block.
00004  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00005  *
00006  * Abstract class for GNSS block interfaces. Since all its methods are virtual,
00007  * this class cannot be instantiated directly, and a subclass can only be
00008  * instantiated directly if all inherited pure virtual methods have been
00009  * implemented by that class or a parent class.
00010  *
00011  * -----
00012  *
00013  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014  * This file is part of GNSS-SDR.
00015  *
00016  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022
00023 #ifndef GNSS_SDR_GNSS_BLOCK_INTERFACE_H
00024 #define GNSS_SDR_GNSS_BLOCK_INTERFACE_H
00025
00026 #include <gnuradio/top_block.h>
00027 #include <cassert>
00028 #include <string>
00029 #include <utility> // for std::forward
00030
00031 /** \addtogroup Core
00032  * \{ */
00033 /** \addtogroup GNSS_Block_Interfaces
00034  * \{ */
00035
00036 // clang-format off
00037 #if GNURADIO_USES_STD_POINTERS
00038 #include <memory>
00039 template <typename T>
00040 using gnss_shared_ptr = std::shared_ptr<T>;
00041 template <typename C, typename... Args>
00042 gnss_shared_ptr<C> gnss_make_shared(Args &&... args)
00043 {
00044     return std::make_shared<C>(std::forward<Args>(args)...);
00045 }
00046 #else
00047 #include <boost/make_shared.hpp>
00048 #include <boost/shared_ptr.hpp>
00049 template <typename T>
00050 using gnss_shared_ptr = boost::shared_ptr<T>;
00051 template <typename C, typename... Args>
00052 gnss_shared_ptr<C> gnss_make_shared(Args &&... args)
00053 {
00054     return boost::make_shared<C>(std::forward<Args>(args)...);
00055 }
00056 #endif
00057 // clang-format on
00058
00059
00060 /*!
00061 * \brief This abstract class represents an interface to GNSS blocks.
00062 *
00063 * Abstract class for GNSS block interfaces. Since all its methods are virtual,
00064 * this class cannot be instantiated directly, and a subclass can only be
00065 * instantiated directly if all inherited pure virtual methods have been
00066 * implemented by that class or a parent class.
00067 */
00068 class GNSSBlockInterface

```

```

00069 {
00070 public:
00071     virtual ~GNSSBlockInterface() = default;
00072     virtual std::string role() = 0;
00073     virtual std::string implementation() = 0;
00074     virtual size_t item_size() = 0;
00075     virtual void connect(gr::top_block_sptr top_block) = 0;
00076     virtual void disconnect(gr::top_block_sptr top_block) = 0;
00077
00078     virtual gr::basic_block_sptr get_left_block() = 0;
00079     virtual gr::basic_block_sptr get_right_block() = 0;
00080
00081     virtual gr::basic_block_sptr get_left_block(int RF_channel)
00082     {
00083         assert(RF_channel >= 0);
00084         if (RF_channel == 0)
00085         {
00086             }; // avoid unused param warning
00087         return nullptr; // added to support raw array access (non pure virtual to allow left
00088             unimplemented)= 0;
00089     }
00089     virtual gr::basic_block_sptr get_right_block(int RF_channel)
00090     {
00091         assert(RF_channel >= 0);
00092         if (RF_channel == 0)
00093         {
00094             }; // avoid unused param warning
00095         return nullptr; // added to support raw array access (non pure virtual to allow left
00096             unimplemented)= 0;
00097     }
00097
00098     /*!
00099     * \brief Start the flow of samples if needed.
00100     */
00101     virtual void start() {};
00102 };
00103
00104
00105 /** @} */
00106 /** @} */
00107 #endif // GNSS_SDR_GNSS_BLOCK_INTERFACE_H

```

13.634 observables_interface.h File Reference

This class represents an interface to an Observables block.

```
#include "gnss_block_interface.h"
```

Classes

- class [ObservablesInterface](#)

This abstract class represents an interface to an observables block.

13.634.1 Detailed Description

This class represents an interface to an Observables block.

Author

Javier Arribas, 2011. jarribas(at)cttc.es

Abstract class for Observables modules. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

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Definition in file [observables_interface.h](#).

13.635 observables_interface.h

[Go to the documentation of this file.](#)

```
00001 /*!
```



```

00002  * \file observables_interface.h
00003  * \brief This class represents an interface to an Observables block.
00004  * \author Javier Arribas, 2011. jarribas(at)cttc.es
00005  *
00006  * Abstract class for Observables modules. Since all its methods are virtual,
00007  * this class cannot be instantiated directly, and a subclass can only be
00008  * instantiated directly if all inherited pure virtual methods have been
00009  * implemented by that class or a parent class.
00010  *
00011  * -----
00012  *
00013  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014  * This file is part of GNSS-SDR.
00015  *
00016  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022
00023 #ifndef GNSS_SDR_OBSERVABLES_INTERFACE_H
00024 #define GNSS_SDR_OBSERVABLES_INTERFACE_H
00025
00026 #include "gnss_block_interface.h"
00027
00028 /** \addtogroup Core
00029  * \{ */
00030 /** \addtogroup GNSS_Block_Interfaces
00031  * \{ */
00032
00033
00034 /**
00035  * \brief This abstract class represents an interface to an observables block.
00036  *
00037  * Abstract class for pseudorange_interfaces, derived from GNSSBlockInterface.
00038  * Since all its methods are virtual,
00039  * this class cannot be instantiated directly, and a subclass can only be
00040  * instantiated directly if all inherited pure virtual methods have been
00041  * implemented by that class or a parent class.
00042  */
00043 class ObservablesInterface : public GNSSBlockInterface
00044 {
00045 public:
00046     virtual void reset() = 0;
00047 };
00048
00049
00050 /** \} */
00051 /** \} */
00052 #endif // GNSS_SDR_OBSERVABLES_INTERFACE_H

```

13.636 pvt_interface.h File Reference

This class represents an interface to a PVT block.

```

#include "galileo_almanac.h"
#include "galileo_ephemeris.h"
#include "gnss_block_interface.h"
#include "gps_almanac.h"
#include "gps_ephemeris.h"
#include <map>

```

Classes

- class [PvtInterface](#)

This class represents an interface to a PVT block.

13.636.1 Detailed Description

This class represents an interface to a PVT block.

Author

Javier Arribas, 2011. jarribas(at)cttc.es

Abstract class for PVT solvers. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

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Definition in file [pvt_interface.h](#).

13.637 pvt_interface.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file pvt_interface.h
00003  * \brief This class represents an interface to a PVT block.
00004  * \author Javier Arribas, 2011. jarribas(at)cttc.es
00005  *
00006  * Abstract class for PVT solvers. Since all its methods are virtual,
00007  * this class cannot be instantiated directly, and a subclass can only be
00008  * instantiated directly if all inherited pure virtual methods have been
00009  * implemented by that class or a parent class.
00010  *
00011  * -----
00012  *
00013  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014  * This file is part of GNSS-SDR.
00015  *
00016  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022
00023 #ifndef GNSS_SDR_PVT_INTERFACE_H
00024 #define GNSS_SDR_PVT_INTERFACE_H
00025
00026 #include "galileo_almanac.h"
00027 #include "galileo_ephemeris.h"
00028 #include "gnss_block_interface.h"
00029 #include "gps_almanac.h"
00030 #include "gps_ephemeris.h"
00031 #include <map>
00032
00033 /** \addtogroup Core
00034  * \{ */
00035 /** \addtogroup GNSS_Block_Interfaces
00036  * \{ */
00037
00038
00039 /*!
00040 * \brief This class represents an interface to a PVT block.
00041 *
00042 * Abstract class for PVT interfaces, derived from GNSSBlockInterface.
00043 * Since all its methods are virtual,
00044 * this class cannot be instantiated directly, and a subclass can only be
00045 * instantiated directly if all inherited pure virtual methods have been
00046 * implemented by that class or a parent class.
00047 */
00048 class PvtInterface : public GNSSBlockInterface
00049 {
00050 public:
00051     virtual void reset() = 0;
00052     virtual void clear_ephemeris() = 0;
00053     virtual std::map<int, Gps_Ephemeris> get_gps_ephemeris() const = 0;
00054     virtual std::map<int, Galileo_Ephemeris> get_galileo_ephemeris() const = 0;
00055     virtual std::map<int, Gps_Almanac> get_gps_almanac() const = 0;
00056     virtual std::map<int, Galileo_Almanac> get_galileo_almanac() const = 0;
00057
00058     virtual bool get_latest_PVT(double* longitude_deg,
00059                                double* latitude_deg,
00060                                double* height_m,
00061                                double* ground_speed_kmh,
00062                                double* course_over_ground_deg,
00063                                time_t* UTC_time) = 0;
00064 };
00065
00066
00067 /** \} */
00068 /** \} */

```

```
00069 #endif // GNSS_SDR_PVT_INTERFACE_H
```

13.638 signal_source_interface.h

```
00001 /*!
00002  * \signal_source_interface.h
00003  * \brief Header file of the interface to a signal_source GNSS block.
00004  * \author Jim Melton, 2020. jim.melton(at)sncorp.com
00005  *
00006  * This header file contains the interface to an abstract class for
00007  * signal sources. Since all its methods are virtual, this class
00008  * cannot be instantiated directly, and a subclass can only be
00009  * instantiated directly if all inherited pure virtual methods have
00010  * been implemented by that class or a parent class.
00011  *
00012  * -----
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  *
00016  * GNSS-SDR is a software defined Global Navigation
00017  * Satellite Systems receiver
00018  *
00019  * This file is part of GNSS-SDR.
00020  *
00021  * SPDX-License-Identifier: GPL-3.0-or-later
00022  *
00023  * -----
00024  */
00025
00026 #ifndef GNSS_SDR_SIGNAL_SOURCE_INTERFACE_H
00027 #define GNSS_SDR_SIGNAL_SOURCE_INTERFACE_H
00028
00029 #include "gnss_block_interface.h"
00030
00031 #if USE_GLOG_AND_GFLAGS
00032 #include <glog/logging.h>
00033 #else
00034 #include <absl/log/log.h>
00035 #endif
00036
00037 /** \addtogroup Core
00038  * \{ */
00039 /** \addtogroup GNSS_Block_Interfaces GNSS block interfaces
00040  * GNSS block interfaces.
00041  * \{ */
00042
00043 /*! \brief This abstract class represents an interface to signal_source GNSS block.
00044  *
00045  * Abstract class for signal sources. Since all its methods are virtual,
00046  * this class cannot be instantiated directly, and a subclass can only be
00047  * instantiated directly if all inherited pure virtual methods have been
00048  * implemented by that class or a parent class.
00049  */
00050
00051 class SignalSourceInterface : public GNSSBlockInterface
00052 {
00053 public:
00054     virtual size_t getRfChannels() const = 0;
00055
00056 protected:
00057     SignalSourceInterface()
00058     {
00059         VLOG(1) << "SignalSourceInterface: " << this << " ctor";
00060     }
00061
00062 public: // required for polymorphic destruction
00063     ~SignalSourceInterface()
00064     {
00065         VLOG(1) << "SignalSourceInterface: " << this << " dtor";
00066     }
00067 };
00068
00069 #endif
```

13.639 telemetry_decoder_interface.h File Reference

This class represents an interface to a telemetry decoder block.

```
#include "gnss_block_interface.h"
#include "gnss_satellite.h"
```

Classes

- class [TelemetryDecoderInterface](#)

This abstract class represents an interface to a navigation GNSS block.

13.639.1 Detailed Description

This class represents an interface to a telemetry decoder block.

Author

Javier Arribas, 2011. jarribas(at)cttc.es

Abstract class for telemetry decoders. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

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Definition in file [telemetry_decoder_interface.h](#).

13.640 telemetry_decoder_interface.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file telemetry_decoder_interface.h
00003  * \brief This class represents an interface to a telemetry decoder block.
00004  * \author Javier Arribas, 2011. jarribas(at)cttc.es
00005  *
00006  * Abstract class for telemetry decoders. Since all its methods are virtual,
00007  * this class cannot be instantiated directly, and a subclass can only be
00008  * instantiated directly if all inherited pure virtual methods have been
00009  * implemented by that class or a parent class.
00010  *
00011  * -----
00012  *
00013  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014  * This file is part of GNSS-SDR.
00015  *
00016  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022
00023 #ifndef GNSS_SDR_TELEMETRY_DECODER_INTERFACE_H
00024 #define GNSS_SDR_TELEMETRY_DECODER_INTERFACE_H
00025
00026 #include "gnss_block_interface.h"
00027 #include "gnss_satellite.h"
00028
00029 /** \addtogroup Core
00030  * \{ */
00031 /** \addtogroup GNSS_Block_Interfaces
00032  * \{ */
00033
00034
00035 /*!
00036  * \brief This abstract class represents an interface to a navigation GNSS block.
00037  *
00038  * Abstract class for navigation interfaces. Since all its methods are virtual,
00039  * this class cannot be instantiated directly, and a subclass can only be
00040  * instantiated directly if all inherited pure virtual methods have been
00041  * implemented by that class or a parent class.
00042  */
00043 class TelemetryDecoderInterface : public GNSSBlockInterface
00044 {
00045 public:
00046     virtual void reset() = 0;
00047     virtual void set_satellite(const Gnss_Satellite& sat) = 0;
00048     virtual void set_channel(int channel) = 0;
00049 };
00050
00051

```

```

00052 /** \} */
00053 /** \} */
00054 #endif // GNSS_SDR_TELEMETRY_DECODER_INTERFACE_H

```

13.641 tracking_interface.h File Reference

This class represents an interface to a tracking block.

```

#include "gnss_block_interface.h"
#include "gnss_synchro.h"

```

Classes

- class [TrackingInterface](#)

This abstract class represents an interface to a tracking block.

13.641.1 Detailed Description

This class represents an interface to a tracking block.

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com

Abstract class for tracking interfaces. Since all its methods are virtual, this class cannot be instantiated directly, and a subclass can only be instantiated directly if all inherited pure virtual methods have been implemented by that class or a parent class.

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Definition in file [tracking_interface.h](#).

13.642 tracking_interface.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file tracking_interface.h
00003  * \brief This class represents an interface to a tracking block.
00004  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00005  *
00006  * Abstract class for tracking interfaces. Since all its methods are virtual,
00007  * this class cannot be instantiated directly, and a subclass can only be
00008  * instantiated directly if all inherited pure virtual methods have been
00009  * implemented by that class or a parent class.
00010  *
00011  * -----
00012  *
00013  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00014  * This file is part of GNSS-SDR.
00015  *
00016  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00017  * SPDX-License-Identifier: GPL-3.0-or-later
00018  *
00019  * -----
00020  */
00021
00022
00023 #ifndef GNSS_SDR_TRACKING_INTERFACE_H
00024 #define GNSS_SDR_TRACKING_INTERFACE_H
00025
00026 #include "gnss_block_interface.h"
00027 #include "gnss_synchro.h"
00028
00029 /** \addtogroup Core
00030  * \{ */
00031 /** \addtogroup GNSS_Block_Interfaces
00032  * \{ */
00033
00034
00035 template <typename Data>
00036 class Concurrent_Queue;
00037

```

```

00038  /*!
00039  * \brief This abstract class represents an interface to a tracking block.
00040  *
00041  * Abstract class for tracking interfaces. Since all its methods are virtual,
00042  * this class cannot be instantiated directly, and a subclass can only be
00043  * instantiated directly if all inherited pure virtual methods have been
00044  * implemented by that class or a parent class.
00045  *
00046  */
00047  class TrackingInterface : public GNSSBlockInterface
00048  {
00049  public:
00050      virtual void start_tracking() = 0;
00051      virtual void stop_tracking() = 0;
00052      virtual void set_gnss_synchro(Gnss_Synchro* gnss_synchro) = 0;
00053      virtual void set_channel(unsigned int channel) = 0;
00054  };
00055
00056
00057  /** \} */
00058  /** \} */
00059  #endif // GNSS_SDR_TRACKING_INTERFACE_H

```

13.643 channel_event.h File Reference

Class that defines a channel event.

```
#include <memory>
```

Classes

- class [Channel_Event](#)

Typedefs

- using [channel_event_sptr](#) = std::shared_ptr<[Channel_Event](#)>

Functions

- [channel_event_sptr channel_event_make](#) (int channel_id, int event_type)

13.643.1 Detailed Description

Class that defines a channel event.

Author

Javier Arribas, 2019. jarribas(at)cttc.es

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 Definition in file [channel_event.h](#).

13.644 channel_event.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file channel_event.h
00003  * \brief Class that defines a channel event
00004  * \author Javier Arribas, 2019. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */

```

```

00016
00017 #ifndef GNSS_SDR_CHANNEL_EVENT_H
00018 #define GNSS_SDR_CHANNEL_EVENT_H
00019
00020 #include <memory>
00021
00022 /** \addtogroup Core
00023  * \{ */
00024 /** \addtogroup Core_Receiver_Library core_libs
00025  * \{ */
00026
00027
00028 class Channel_Event;
00029
00030 using channel_event_sptr = std::shared_ptr<Channel_Event>;
00031
00032 channel_event_sptr channel_event_make(int channel_id, int event_type);
00033
00034 class Channel_Event
00035 {
00036 public:
00037     int channel_id;
00038     int event_type;
00039
00040 private:
00041     friend channel_event_sptr channel_event_make(int channel_id, int event_type);
00042     Channel_Event(int channel_id_, int event_type_);
00043 };
00044
00045
00046 /** \} */
00047 /** \} */
00048 #endif // GNSS_SDR_CHANNEL_EVENT_H

```

13.645 channel_status_msg_receiver.h File Reference

GNU Radio block that receives asynchronous channel messages from acquisition and tracking blocks.

```

#include "gnss_block_interface.h"
#include "gnss_synchro.h"
#include "monitor_pvt.h"
#include <gnuradio/block.h>
#include <pmt/pmt.h>
#include <map>
#include <memory>

```

Classes

- class [channel_status_msg_receiver](#)

GNU Radio block that receives asynchronous channel messages from tlm blocks.

Typedefs

- using [channel_status_msg_receiver_sptr](#) = [gnss_shared_ptr](#)<[channel_status_msg_receiver](#)>

Functions

- [channel_status_msg_receiver_sptr channel_status_msg_receiver_make](#) ()

13.645.1 Detailed Description

GNU Radio block that receives asynchronous channel messages from acquisition and tracking blocks.

Author

Javier Arribas, 2019. jarribas@cttc.es

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 Definition in file [channel_status_msg_receiver.h](#).

13.646 channel_status_msg_receiver.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file channel_status_msg_receiver.h
00003  * \brief GNU Radio block that receives asynchronous channel messages from
00004  * acquisition and tracking blocks
00005  * \author Javier Arribas, 2019. jarribas(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
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00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_CHANNEL_STATUS_MSG_RECEIVER_CC_H
00019 #define GNSS_SDR_CHANNEL_STATUS_MSG_RECEIVER_CC_H
00020
00021 #include "gnss_block_interface.h"
00022 #include "gnss_synchro.h"
00023 #include "monitor_pvt.h"
00024 #include <gnuradio/block.h>
00025 #include <pmt/pmt.h>
00026 #include <map>
00027 #include <memory>
00028
00029 /** \addtogroup Core
00030  * \{ */
00031 /** \addtogroup Core_Receiver_Library
00032  * \{ */
00033
00034
00035 class channel_status_msg_receiver;
00036
00037 using channel_status_msg_receiver_sptr = gnss_shared_ptr<channel_status_msg_receiver>;
00038
00039 channel_status_msg_receiver_sptr channel_status_msg_receiver_make();
00040
00041 /*!
00042  * \brief GNU Radio block that receives asynchronous channel messages from tlm blocks
00043  */
00044 class channel_status_msg_receiver : public gr::block
00045 {
00046 public:
00047     ~channel_status_msg_receiver() = default; //!< Default destructor
00048
00049     /*!
00050     * \brief return the current status map of all channels with valid telemetry
00051     */
00052     std::map<int, std::shared_ptr<Gnss_Synchro> get_current_status_map();
00053
00054     /*!
00055     * \brief return the current receiver PVT
00056     */
00057     Monitor_Pvt get_current_status_pvt();
00058
00059 private:
00060     friend channel_status_msg_receiver_sptr channel_status_msg_receiver_make();
00061     channel_status_msg_receiver();
00062     void msg_handler_channel_status(const pmt::pmt_t& msg);
00063     Monitor_Pvt d_pvt_status{};
00064     std::map<int, std::shared_ptr<Gnss_Synchro> d_channel_status_map;
00065 };
00066
00067
00068 /** \} */
00069 /** \} */
00070 #endif // GNSS_SDR_CHANNEL_STATUS_MSG_RECEIVER_CC_H

```

13.647 command_event.h File Reference

Class that defines a receiver command event.

```
#include <memory>
```


Classes

- class [Command_Event](#)

Typedefs

- using [command_event_sptr](#) = std::shared_ptr<[Command_Event](#)>

Functions

- [command_event_sptr](#) **command_event_make** (int command_id, int event_type)

13.647.1 Detailed Description

Class that defines a receiver command event.

Author

Javier Arribas, 2019. jarribas(at)cttc.es

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 Definition in file [command_event.h](#).

13.648 command_event.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002   * \file command_event.h
00003   * \brief Class that defines a receiver command event
00004   * \author Javier Arribas, 2019. jarribas(at)cttc.es
00005   *
00006   * -----
00007   *
00008   * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009   * This file is part of GNSS-SDR.
00010   *
00011   * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012   * SPDX-License-Identifier: GPL-3.0-or-later
00013   *
00014   * -----
00015   */
00016
00017 #ifndef GNSS_SDR_COMMAND_EVENT_H
00018 #define GNSS_SDR_COMMAND_EVENT_H
00019
00020 #include <memory>
00021
00022 /** \addtogroup Core
00023  * \{ */
00024 /** \addtogroup Core_Receiver_Library
00025  * \{ */
00026
00027 class Command_Event;
00028
00029 using command_event_sptr = std::shared_ptr<Command_Event>;
00030
00031 command_event_sptr command_event_make(int command_id, int event_type);
00032
00033 class Command_Event
00034 {
00035 public:
00036     int command_id;
00037     int event_type;
00038
00039 private:
00040     friend command_event_sptr command_event_make(int command_id, int event_type);
00041     Command_Event(int command_id_, int event_type_);
00042 };
00043
00044
00045 /** \} */
00046 /** \} */
00047 #endif // GNSS_SDR_COMMAND_EVENT_H

```

13.649 galileo_e6_has_msg_receiver.h File Reference

GNU Radio block that processes Galileo HAS message pages received from Galileo E6B telemetry blocks. After successful decoding, sends the content to the PVT block.

```
#include "Galileo_CNAV.h"
#include "galileo_has_data.h"
#include "gnss_block_interface.h"
#include "nav_message_packet.h"
#include <gnuradio/block.h>
#include <pmt/pmt.h>
#include <bitset>
#include <cstdint>
#include <map>
#include <memory>
#include <string>
#include <utility>
#include <vector>
```

Classes

- class [galileo_e6_has_msg_receiver](#)

GNU Radio block that receives asynchronous Galileo HAS message pages from the telemetry blocks, stores them in memory, and decodes HAS messages when enough data have been received. The decoded HAS message is sent to the PVT block.

Typedefs

- using [galileo_e6_has_msg_receiver_sptr](#) = `gnss_shared_ptr<galileo_e6_has_msg_receiver>`

Functions

- `galileo_e6_has_msg_receiver_sptr galileo_e6_has_msg_receiver_make ()`

13.649.1 Detailed Description

GNU Radio block that processes Galileo HAS message pages received from Galileo E6B telemetry blocks. After successful decoding, sends the content to the PVT block.

Author

Carles Fernandez-Prades, 2021. [cfernandez\(at\)cttc.es](mailto:cfernandez@cttc.es)

Javier Arribas, 2021. [jarribas\(at\)cttc.es](mailto:jarribas@cttc.es)

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 Definition in file [galileo_e6_has_msg_receiver.h](#).

13.650 galileo_e6_has_msg_receiver.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file galileo_e6_has_msg_receiver.h
00003  * \brief GNU Radio block that processes Galileo HAS message pages received from
00004  * Galileo E6B telemetry blocks. After successful decoding, sends the content to
00005  * the PVT block.
00006  * \author Carles Fernandez-Prades, 2021. cfernandez(at)cttc.es
00007  * \author Javier Arribas, 2021. jarribas(at)cttc.es
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
```

```

00013  *
00014  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_GALILEO_E6_HAS_MSG_RECEIVER_H
00021 #define GNSS_SDR_GALILEO_E6_HAS_MSG_RECEIVER_H
00022
00023 #include "Galileo_CNAV.h" // for GALILEO_CNAV_* constants
00024 #include "galileo_has_data.h" // for Galileo_HAS_data
00025 #include "gnss_block_interface.h" // for gnss_shared_ptr
00026 #include "nav_message_packet.h" // for Nav_Message_Packet
00027 #include <gnuradio/block.h> // for gr::block
00028 #include <pmt/pmt.h> // for pmt::pmt_t
00029 #include <bitset>
00030 #include <cstdint>
00031 #include <map>
00032 #include <memory> // for std::unique_ptr
00033 #include <string>
00034 #include <utility> // std::pair
00035 #include <vector>
00036
00037 /** \addtogroup Core
00038  * \{ */
00039 /** \addtogroup Core_Receiver_Library
00040  * \{ */
00041
00042 class Galileo_HAS_page;
00043 class ReedSolomon;
00044 class galileo_e6_has_msg_receiver;
00045
00046 using galileo_e6_has_msg_receiver_sp_ptr = gnss_shared_ptr<galileo_e6_has_msg_receiver>;
00047
00048 galileo_e6_has_msg_receiver_sp_ptr galileo_e6_has_msg_receiver_make();
00049
00050 /*!
00051  * \brief GNU Radio block that receives asynchronous Galileo HAS message pages
00052  * from the telemetry blocks, stores them in memory, and decodes HAS messages
00053  * when enough data have been received.
00054  * The decoded HAS message is sent to the PVT block.
00055  */
00056 class galileo_e6_has_msg_receiver : public gr::block
00057 {
00058 public:
00059     ~galileo_e6_has_msg_receiver() = default; //!< Default destructor
00060     void set_enable_navdata_monitor(bool enable);
00061     std::shared_ptr<Galileo_HAS_data> process_test_page(const pmt::pmt_t& msg); //!< For testing
00062     purposes only
00063 private:
00064     friend galileo_e6_has_msg_receiver_sp_ptr galileo_e6_has_msg_receiver_make();
00065     galileo_e6_has_msg_receiver();
00066
00067     void msg_handler_galileo_e6_has(const pmt::pmt_t& msg);
00068     void process_HAS_page(const Galileo_HAS_page& has_page);
00069     void read_MT1_header(const std::string& message_header);
00070     void read_MT1_body(const std::string& message_body);
00071     void delete_outdated_data(const Galileo_HAS_page& has_page);
00072
00073     int decode_message_type1(uint8_t message_id, uint8_t message_size);
00074
00075     uint16_t read_has_message_header_parameter_uint16(const std::bitset<GALILEO_CNAV_MT1_HEADER_BITS>&
00076 bits, const std::pair<int32_t, int32_t>& parameter) const;
00077     uint8_t read_has_message_header_parameter_uint8(const std::bitset<GALILEO_CNAV_MT1_HEADER_BITS>&
00078 bits, const std::pair<int32_t, int32_t>& parameter) const;
00079     bool read_has_message_header_parameter_bool(const std::bitset<GALILEO_CNAV_MT1_HEADER_BITS>& bits,
00080 const std::pair<int32_t, int32_t>& parameter) const;
00081
00082     uint64_t read_has_message_body_uint64(const std::string& bits) const;
00083     uint16_t read_has_message_body_uint16(const std::string& bits) const;
00084     int16_t read_has_message_body_int16(const std::string& bits) const;
00085     uint8_t read_has_message_body_uint8(const std::string& bits) const;
00086
00087     template <class T>
00088     std::string debug_print_vector(const std::string& title, const std::vector<T>& vec) const; //
00089     only for debug purposes
00090
00091     template <class T>
00092     std::string debug_print_matrix(const std::string& title, const std::vector<std::vector<T>& mat)
00093     const; // only for debug purposes
00094
00095     std::unique_ptr<ReedSolomon> d_rs;
00096     Galileo_HAS_data d_HAS_data{};
00097     Nav_Message_Packet d_nav_msg_packet;
00098
00099

```

```

00094 // Store decoding matrices and received PIDs
00095 std::vector<std::vector<uint64_t> d_received_timestamps;
00096 std::vector<std::vector<std::vector<uint8_t>> d_C_matrix;
00097 std::vector<std::vector<uint8_t> d_M_matrix;
00098 std::vector<std::vector<uint8_t> d_received_pids;
00099 std::vector<uint64_t> d_printed_timestamps;
00100 std::vector<bool> d_printed_mids;
00101
00102 // Store masks
00103 std::vector<int> d_nsats_in_mask_id;
00104 std::vector<std::vector<uint8_t> d_gnss_id_in_mask;
00105 std::vector<std::vector<uint64_t> d_satellite_mask;
00106 std::vector<std::vector<uint16_t> d_signal_mask;
00107 std::vector<std::vector<bool> d_cell_mask_availability_flag;
00108 std::vector<std::vector<std::vector<std::vector<bool>>> d_cell_mask;
00109 std::vector<uint8_t> d_nsys_in_mask;
00110 std::vector<std::vector<uint8_t> d_nav_message_mask;
00111
00112 std::map<std::pair<uint8_t, uint8_t>, std::vector<uint16_t> d_ioid_ref_map;
00113
00114 uint8_t d_current_has_status{};
00115 uint8_t d_current_message_id{};
00116 bool d_new_message{};
00117 bool d_enable_navdata_monitor{};
00118 };
00119
00120
00121 /** \} */
00122 /** \} */
00123 #endif // GNSS_SDR_GALILEO_E6_HAS_MSG_RECEIVER_H

```

13.651 galileo_tow_map.h File Reference

GNU Radio block that stores TOW for Galileo channels.

```

#include "gnss_block_interface.h"
#include <gnuradio/block.h>
#include <pmt/pmt.h>
#include <stdint>
#include <map>
#include <utility>

```

Classes

- class [galileo_tow_map](#)

Typedefs

- using [galileo_tow_map_sptr](#) = [gnss_shared_ptr](#)<[galileo_tow_map](#)>

Functions

- [galileo_tow_map_sptr](#) [galileo_tow_map_make](#) ()

13.651.1 Detailed Description

GNU Radio block that stores TOW for Galileo channels.

Author

Carles Fernandez-Prades, 2022. cfernandez(at)cttc.es

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 Definition in file [galileo_tow_map.h](#).

13.652 galileo_tow_map.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_tow_map.h
00003  * \brief GNU Radio block that stores TOW for Galileo channels
00004  * \author Carles Fernandez-Prades, 2022. cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_GALILEO_TOW_MAP_H
00018 #define GNSS_SDR_GALILEO_TOW_MAP_H
00019
00020 #include "gnss_block_interface.h" // for gnss_shared_ptr
00021 #include <gnuradio/block.h>       // for gr::block
00022 #include <pmt/pmt.h>               // for pmt::pmt_t
00023 #include <cstdint>
00024 #include <map>
00025 #include <utility>
00026
00027 /** \addtogroup Core
00028  * \{ */
00029 /** \addtogroup Core_Receiver_Library
00030  * \{ */
00031
00032 class galileo_tow_map;
00033
00034 using galileo_tow_map_sp_ptr = gnss_shared_ptr<galileo_tow_map>;
00035
00036 galileo_tow_map_sp_ptr galileo_tow_map_make();
00037
00038 class galileo_tow_map : public gr::block
00039 {
00040 public:
00041     ~galileo_tow_map() = default; //!< Default destructor
00042
00043 private:
00044     friend galileo_tow_map_sp_ptr galileo_tow_map_make();
00045     galileo_tow_map();
00046
00047     void msg_handler_galileo_tow_map(const pmt::pmt_t& msg);
00048
00049     std::map<uint32_t, std::pair<uint32_t, uint64_t>> d_galileo_tow;
00050 };
00051
00052 /** \} */
00053 /** \} */
00054 #endif // GNSS_SDR_GALILEO_TOW_MAP_H

```

13.653 gnss_crypto.h File Reference

Class for computing cryptographic functions.

```

#include <cstdint>
#include <string>
#include <vector>
#include <openssl/ec.h>

```

Classes

- class [Gnss_Crypto](#)

Class implementing cryptographic functions for Navigation Message Authentication.

13.653.1 Detailed Description

Class for computing cryptographic functions.

Author

Carles Fernandez, 2023-2024. cfernandez(at)cttc.es Cesare Ghionoiu Martinez, 2023-2024. c.ghionoiu-martinez@tu-braunschweig.de

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 Definition in file [gnss_crypto.h](#).

13.654 gnss_crypto.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gnss_crypto.h
00003  * \brief Class for computing cryptographic functions
00004  * \author Carles Fernandez, 2023-2024. cfernandez(at)cttc.es
00005  *         Cesare Ghionoiu Martinez, 2023-2024. c.ghionoiu-martinez@tu-braunschweig.de
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GNSS_CRYPTO_H
00020 #define GNSS_SDR_GNSS_CRYPTO_H
00021
00022 #include <stdint>
00023 #include <string>
00024 #include <vector>
00025 #if USE_GNUTLS_FALLBACK
00026 #include <gnutls/abstract.h>
00027 #include <gnutls/gnutls.h>
00028 #else // OpenSSL
00029 #include <openssl/ec.h>
00030 #endif
00031
00032 /** \addtogroup Core
00033  * \{ */
00034 /** \addtogroup Core_Receiver_Library
00035  * \{ */
00036
00037 /*!
00038  * \brief Class implementing cryptographic functions
00039  * for Navigation Message Authentication
00040  */
00041 class Gnss_Crypto
00042 {
00043 public:
00044     Gnss_Crypto(); //!< Default constructor
00045
00046     /*!
00047      * Constructor with a .crt or .pem file for the ECDSA Public Key
00048      * and a XML file for the Merkle Tree root.
00049      * Files can be downloaded by registering at https://www.gsc-europa.eu/
00050      */
00051     Gnss_Crypto(const std::string& certFilePath, const std::string& merkleTreePath);
00052     ~Gnss_Crypto(); //!< Default destructor
00053
00054     bool have_public_key() const; //!< Returns true if the ECDSA Public Key is already loaded
00055
00056     /*!
00057      * Stores the ECDSA Public Key in a .pem file, which is read in a following run if the .crt file
00058      * is not found
00059      */
00059     bool store_public_key(const std::string& pubKeyFilePath) const;
00060
00061     bool verify_signature_ecdsa_p256(const std::vector<uint8_t>& message, const std::vector<uint8_t>&
signature) const; //!< Verify ECDSA-P256 signature (message in plain hex, signature in raw format)
00062     bool verify_signature_ecdsa_p521(const std::vector<uint8_t>& message, const std::vector<uint8_t>&
signature) const; //!< Verify ECDSA-P521 signature (message in plain hex, signature in raw format)
00063
00064     std::vector<uint8_t> compute_SHA_256(const std::vector<uint8_t>& input) const;
00065     //!< Computes SHA-256 hash
00066     std::vector<uint8_t> compute_SHA3_256(const std::vector<uint8_t>& input) const;
00067     //!< Computes SHA3-256 hash

```

```

00066     std::vector<uint8_t> compute_HMAC_SHA_256(const std::vector<uint8_t>& key, const
std::vector<uint8_t>& input) const; //!< Computes HMAC-SHA-256 message authentication code
00067     std::vector<uint8_t> compute_CMAC_AES(const std::vector<uint8_t>& key, const std::vector<uint8_t>&
input) const; //!< Computes CMAC-AES message authentication code
00068
00069     std::vector<uint8_t> get_merkle_root() const; //!< Gets the Merkle Tree root node (\f$ x_{4,0}
\f$)
00070     std::string get_public_key_type() const; //!< Gets the ECDSA Public Key type (ECDSA P-256 /
ECDSA P-521 / Unknown)
00071
00072     void set_public_key(const std::vector<uint8_t>& publickey); //!< Sets the ECDSA Public Key
(publickey compressed format)
00073     void set_public_key_type(const std::string& public_key_type); //!< Sets the ECDSA Public Key type
(ECDSA P-256 / ECDSA P-521)
00074     void set_merkle_root(const std::vector<uint8_t>& v); //!< Sets the Merkle Tree root node
x(\f$ x_{4,0} \f$)
00075     void read_merkle_xml(const std::string& merkleFilePath); //!< Reads the XML file provided
from the GSC OSNMA server
00076
00077 private:
00078     void readPublicKeyFromPEM(const std::string& pemFilePath);
00079     bool readPublicKeyFromCRT(const std::string& crtFilePath);
00080     bool convert_raw_to_der_ecdsa(const std::vector<uint8_t>& raw_signature, std::vector<uint8_t>&
der_signature) const;
00081     std::vector<uint8_t> convert_from_hex_str(const std::string& input) const; // TODO - deprecate if
OSNMA helper is to do this operation
00082 #if USE_GNUTLS_FALLBACK
00083     void decompress_public_key_secp256r1(const std::vector<uint8_t>& compressed_key,
std::vector<uint8_t>& x, std::vector<uint8_t>& y) const;
00084     void decompress_public_key_secp521r1(const std::vector<uint8_t>& compressed_key,
std::vector<uint8_t>& x, std::vector<uint8_t>& y) const;
00085     bool pubkey_copy(gnutls_pubkey_t src, gnutls_pubkey_t* dest);
00086     gnutls_pubkey_t d_PublicKey{};
00087 #else // OpenSSL
00088 #if USE_OPENSSL_3
00089     bool pubkey_copy(EVP_PKEY* src, EVP_PKEY** dest);
00090     EVP_PKEY* d_PublicKey{};
00091 #else // OpenSSL 1.x
00092     bool pubkey_copy(EC_KEY* src, EC_KEY** dest);
00093     EC_KEY* d_PublicKey = nullptr;
00094 #endif
00095 #endif
00096     std::vector<uint8_t> d_x_4_0;
00097     std::string d_PublicKeyType;
00098 };
00099
00100 /** \} */
00101 /** \} */
00102
00103 #endif // GNSS_SDR_GNSS_CRYPTOH

```

13.655 gnss_sdr_fpga_sample_counter.h File Reference

Simple block to report the current receiver time based on the output of the tracking or telemetry blocks.

```

#include "gnss_block_interface.h"
#include <gnuradio/block.h>
#include <gnuradio/types.h>
#include <stdint>
#include <string>

```

Classes

- class [gnss_sdr_fpga_sample_counter](#)

Typedefs

- using [gnss_sdr_fpga_sample_counter_sptr](#) = [gnss_shared_ptr<gnss_sdr_fpga_sample_counter>](#)

Functions

- [gnss_sdr_fpga_sample_counter_sptr gnss_sdr_make_fpga_sample_counter](#) (double _fs, int32_t _↵ interval_ms)

13.655.1 Detailed Description

Simple block to report the current receiver time based on the output of the tracking or telemetry blocks.

Author

Javier Arribas 2018. jarribas(at)cttc.es

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 Definition in file [gnss_sdr_fpga_sample_counter.h](#).

13.656 gnss_sdr_fpga_sample_counter.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gnss_sdr_fpga_sample_counter.h
00003  * \brief Simple block to report the current receiver time based on the output
00004  * of the tracking or telemetry blocks
00005  * \author Javier Arribas 2018. jarribas(at)cttc.es
00006  *
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GNSS_SDR_FPGA_SAMPLE_COUNTER_H
00020 #define GNSS_SDR_GNSS_SDR_FPGA_SAMPLE_COUNTER_H
00021
00022 #include "gnss_block_interface.h"
00023 #include <gnuradio/block.h>
00024 #include <gnuradio/types.h> // for gr_vector_const_void_star
00025 #include <stdint>
00026 #include <string>
00027
00028 /** \addtogroup Core
00029  * \{ */
00030 /** \addtogroup Core_Receiver_Library
00031  * \{ */
00032
00033
00034 class gnss_sdr_fpga_sample_counter;
00035
00036 using gnss_sdr_fpga_sample_counter_sptr = gnss_shared_ptr<gnss_sdr_fpga_sample_counter>;
00037
00038 gnss_sdr_fpga_sample_counter_sptr gnss_sdr_make_fpga_sample_counter(double fs, int32_t interval_ms);
00039
00040 class gnss_sdr_fpga_sample_counter : public gr::block
00041 {
00042 public:
00043     ~gnss_sdr_fpga_sample_counter();
00044     int general_work(int noutput_items,
00045                     gr_vector_int &ninput_items,
00046                     gr_vector_const_void_star &input_items,
00047                     gr_vector_void_star &output_items);
00048
00049 private:
00050     const std::string device_name = "counter"; // UIO device name
00051
00052     static const uint32_t FPGA_PAGE_SIZE = 0x1000; // default page size for the
00053     static const uint32_t test_reg_sanity_check = 0x55AA; // value to check the presence of the test
00054     static const uint32_t register (to detect the hw)
00055     friend gnss_sdr_fpga_sample_counter_sptr gnss_sdr_make_fpga_sample_counter(double fs, int32_t
00056     _interval_ms);
00057     gnss_sdr_fpga_sample_counter(double fs, int32_t _interval_ms);
00058     uint32_t test_register(uint32_t writeval);
00059     void configure_samples_per_output(uint32_t interval);
00060     void close_device(void);
00061     void open_device(void);
00062     bool start();
00063     bool stop();
00064     void wait_for_interrupt(void) const;

```



```

00065     volatile uint32_t *map_base; // driver memory map
00066
00067     double fs;
00068     uint64_t sample_counter;
00069     uint64_t last_sample_counter;
00070     uint64_t current_T_rx_ms; // Receiver time in ms since the beginning of the run
00071
00072     uint32_t samples_per_output;
00073     uint32_t samples_per_report;
00074     uint32_t interval_ms;
00075     uint32_t current_s; // Receiver time in seconds, modulo 60
00076     uint32_t current_m; // Receiver time in minutes, modulo 60
00077     uint32_t current_h; // Receiver time in hours, modulo 24
00078     uint32_t current_days; // Receiver time in days since the beginning of the run
00079     int32_t report_interval_ms;
00080     int32_t fd; // driver descriptor
00081
00082     bool flag_enable_send_msg;
00083     bool flag_m; // True if the receiver has been running for at least 1 minute
00084     bool flag_h; // True if the receiver has been running for at least 1 hour
00085     bool flag_days; // True if the receiver has been running for at least 1 day
00086     bool is_open;
00087 };
00088
00089
00090 /** @} */
00091 /** @} */
00092 #endif // GNSS_SDR_GNSS_SDR_FPGA_SAMPLE_COUNTER_H

```

13.657 gnss_sdr_sample_counter.h File Reference

Simple block to report the current receiver time based on the output of the tracking or telemetry blocks.

```

#include "gnss_block_interface.h"
#include <gnuradio/sync_decimator.h>
#include <gnuradio/types.h>
#include <cstdint>
#include <cstdint>

```

Classes

- class [gnss_sdr_sample_counter](#)

Typedefs

- using [gnss_sdr_sample_counter_sptr](#) = [gnss_shared_ptr](#)<[gnss_sdr_sample_counter](#)>

Functions

- [gnss_sdr_sample_counter_sptr](#) [gnss_sdr_make_sample_counter](#) (double _fs, int32_t _interval_ms, size_t _t_size)

13.657.1 Detailed Description

Simple block to report the current receiver time based on the output of the tracking or telemetry blocks.

Author

Javier Arribas 2018. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)

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 Definition in file [gnss_sdr_sample_counter.h](#).

13.658 gnss_sdr_sample_counter.h

[Go to the documentation of this file.](#)

```
00001 /*!
```

```

00002  * \file gnss_sdr_sample_counter.h
00003  * \brief Simple block to report the current receiver time based on the output of the tracking or
        telemetry blocks
00004  * \author Javier Arribas 2018. jarribas(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GNSS_SDR_SAMPLE_COUNTER_H
00019 #define GNSS_SDR_GNSS_SDR_SAMPLE_COUNTER_H
00020
00021 #include "gnss_block_interface.h"
00022 #include <gnuradio/sync_decimator.h>
00023 #include <gnuradio/types.h> // for gr_vector_const_void_star
00024 #include <cstdlib> // for size_t
00025 #include <stdint>
00026
00027 /** \addtogroup Core
00028  * \{ */
00029 /** \addtogroup Core_Receiver_Library
00030  * Utilities for the core GNSS receiver.
00031  * \{ */
00032
00033
00034 class gnss_sdr_sample_counter;
00035
00036 using gnss_sdr_sample_counter_sptr = gnss_shared_ptr<gnss_sdr_sample_counter>;
00037
00038 gnss_sdr_sample_counter_sptr gnss_sdr_make_sample_counter(
00039     double _fs,
00040     int32_t _interval_ms,
00041     size_t _size);
00042
00043 class gnss_sdr_sample_counter : public gr::sync_decimator
00044 {
00045 public:
00046     ~gnss_sdr_sample_counter() = default;
00047     int work(int noutput_items,
00048             gr_vector_const_void_star &input_items,
00049             gr_vector_void_star &output_items);
00050 private:
00051     friend gnss_sdr_sample_counter_sptr gnss_sdr_make_sample_counter(
00052         double _fs,
00053         int32_t _interval_ms,
00054         size_t _size);
00055
00056     gnss_sdr_sample_counter(double _fs,
00057                             int32_t _interval_ms,
00058                             size_t _size);
00060
00061     int64_t uint64diff(uint64_t first, uint64_t second);
00062
00063     double fs;
00064     int64_t current_T_rx_ms; // Receiver time in ms since the beginning of the run
00065     uint64_t sample_counter;
00066     int32_t interval_ms;
00067     int32_t report_interval_ms;
00068     uint32_t samples_per_output;
00069     uint32_t current_s; // Receiver time in seconds, modulo 60
00070     uint32_t current_m; // Receiver time in minutes, modulo 60
00071     uint32_t current_h; // Receiver time in hours, modulo 24
00072     uint32_t current_days; // Receiver time in days since the beginning of the run
00073     bool flag_m; // True if the receiver has been running for at least 1 minute
00074     bool flag_h; // True if the receiver has been running for at least 1 hour
00075     bool flag_days; // True if the receiver has been running for at least 1 day
00076     bool flag_enable_send_msg;
00077 };
00078
00079
00080 /** \} */
00081 /** \} */
00082 #endif // GNSS_SDR_GNSS_SDR_SAMPLE_COUNTER_H

```

13.659 gnss_sdr_supl_client.h File Reference

class that implements a C++ interface to external Secure User Location Protocol (SUPL) client library.

```
#include "supl.h"
#include "agnss_ref_location.h"
#include "agnss_ref_time.h"
#include "galileo_almanac.h"
#include "galileo_ephemeris.h"
#include "galileo_iono.h"
#include "galileo_utc_model.h"
#include "glonass_gnav_ephemeris.h"
#include "glonass_gnav_utc_model.h"
#include "gps_acq_assist.h"
#include "gps_almanac.h"
#include "gps_cnav_ephemeris.h"
#include "gps_cnav_utc_model.h"
#include "gps_ephemeris.h"
#include "gps_iono.h"
#include "gps_utc_model.h"
#include <fstream>
#include <map>
#include <string>
```

Classes

- class [Gnss_Sdr_Supl_Client](#)

class that implements a C++ interface to external Secure User Location Protocol (SUPL) client library..

13.659.1 Detailed Description

class that implements a C++ interface to external Secure User Location Protocol (SUPL) client library.

Author

Javier Arribas, 2013. jarribas(at)cttc.es

TODO: put here supl.c author info class that implements a C++ interface to external Secure User Location Protocol (SUPL) client library.

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Definition in file [gnss_sdr_supl_client.h](#).

13.660 gnss_sdr_supl_client.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gnss_sdr_supl_client.h
00003  * \brief class that implements a C++ interface to external Secure User Location Protocol (SUPL)
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00005  *
00006  * TODO: put here supl.c author info
00007  * class that implements a C++ interface to external Secure User Location Protocol (SUPL) client
00008  * library.
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
```

```

00019
00020 #ifndef GNSS_SDR_SUPL_CLIENT_H
00021 #define GNSS_SDR_SUPL_CLIENT_H
00022
00023 extern "C"
00024 {
00025 #include "supl.h"
00026 }
00027 #include "agnss_ref_location.h"
00028 #include "agnss_ref_time.h"
00029 #include "galileo_almanac.h"
00030 #include "galileo_ephemeris.h"
00031 #include "galileo_iono.h"
00032 #include "galileo_utc_model.h"
00033 #include "glonass_gnav_ephemeris.h"
00034 #include "glonass_gnav_utc_model.h"
00035 #include "gps_acq_assist.h"
00036 #include "gps_almanac.h"
00037 #include "gps_cnav_ephemeris.h"
00038 #include "gps_cnav_utc_model.h"
00039 #include "gps_ephemeris.h"
00040 #include "gps_iono.h"
00041 #include "gps_utc_model.h"
00042 #include <fstream>
00043 #include <map>
00044 #include <string>
00045
00046 /** \addtogroup Core
00047  * \{ */
00048 /** \addtogroup Core_Receiver_Library
00049  * \{ */
00050
00051
00052 /*!
00053  * \brief class that implements a C++ interface to external Secure User Location Protocol (SUPL)
00054  * client library..
00055  */
00056 class Gnss_Sdr_Supl_Client
00057 {
00058 public:
00059     Gnss_Sdr_Supl_Client();
00060     ~Gnss_Sdr_Supl_Client() = default;
00061
00062     // SUPL SERVER INFO
00063     std::string server_name;
00064     int server_port;
00065     int request;
00066     // ephemeris map
00067     std::map<int, Gps_Ephemeris> gps_ephemeris_map;
00068     std::map<int, Galileo_Ephemeris> gal_ephemeris_map;
00069     std::map<int, Gps_CNAV_Ephemeris> gps_cnav_ephemeris_map;
00070     std::map<int, Glonass_Gnav_Ephemeris> glonass_gnav_ephemeris_map;
00071
00072     // almanac map
00073     std::map<int, Gps_Almanac> gps_almanac_map;
00074     std::map<int, Galileo_Almanac> gal_almanac_map;
00075
00076     // ionospheric model
00077     Gps_Iono gps_iono;
00078     Galileo_Iono gal_iono;
00079     // reference time
00080     Agnss_Ref_Time gps_time;
00081     // UTC model
00082     Gps_Utc_Model gps_utc;
00083     Galileo_Utc_Model gal_utc;
00084     Gps_CNAV_Utc_Model gps_cnav_utc;
00085     Glonass_Gnav_Utc_Model glo_gnav_utc;
00086     // reference location
00087     Agnss_Ref_Location gps_ref_loc;
00088     // Acquisition Assistance map
00089     std::map<int, Gps_Acq_Assist> gps_acq_map;
00090
00091     /*
00092     * \brief Initiates the TCP SSL SUPL connection to the SUPL server and request assistance data
00093     * using the provided GSM Base station parameters
00094     * \param i_mcc Current network MCC (Mobile country code), 3 digits.
00095     * \param i_mns Current network MNC (Mobile Network code), 2 or 3 digits.
00096     * \param i_lac Current network LAC (Location area code), 16 bits, 1-65520 are valid values.
00097     * \param i_ci Cell Identity (16 bits, 0-65535 are valid values).
00098     * \return Error code -> 0 no errors.
00099     */
00100     int get_assistance(int i_mcc, int i_mns, int i_lac, int i_ci);
00101
00102     /*
00103     * \brief Read the received SUPL data and stores it into the corresponding class members
00104     * (gps_ephemeris_map, gps_almanac_map, gps_iono, gps_time, gps_utc, gps_acq_map, and gps_ref_loc)
00105     */

```

```
00103     */
00104 void read_supl_data();
00105
00106     /*!
00107     * \brief Read GPS NAV ephemeris map from XML file
00108     */
00109 bool load_ephemeris_xml(const std::string& file_name);
00110
00111     /*!
00112     * \brief Save ephemeris map to XML file.
00113     */
00114 bool save_ephemeris_map_xml(const std::string& file_name,
00115     std::map<int, Gps_Ephemeris> eph_map);
00116
00117     /*!
00118     * \brief Read GPS CNAV ephemeris map from XML file
00119     */
00120 bool load_cnav_ephemeris_xml(const std::string& file_name);
00121
00122     /*!
00123     * \brief Save GPS CNAV ephemeris map to XML file.
00124     */
00125 bool save_cnav_ephemeris_map_xml(const std::string& file_name,
00126     std::map<int, Gps_CNAV_Ephemeris> eph_map);
00127
00128     /*!
00129     * \brief Read Galileo ephemeris map from XML file
00130     */
00131 bool load_gal_ephemeris_xml(const std::string& file_name);
00132
00133     /*!
00134     * \brief Save Galileo ephemeris map to XML file.
00135     */
00136 bool save_gal_ephemeris_map_xml(const std::string& file_name,
00137     std::map<int, Galileo_Ephemeris> eph_map);
00138
00139     /*!
00140     * \brief Read GLONASS GNAV ephemeris map from XML file
00141     */
00142 bool load_gnav_ephemeris_xml(const std::string& file_name);
00143
00144     /*!
00145     * \brief Save GLONASS GNAV ephemeris map to XML file.
00146     */
00147 bool save_gnav_ephemeris_map_xml(const std::string& file_name,
00148     std::map<int, Glonass_Gnav_Ephemeris> eph_map);
00149
00150     /*!
00151     * \brief Read GPS utc model from XML file
00152     */
00153 bool load_utc_xml(const std::string& file_name);
00154
00155     /*!
00156     * \brief Save UTC model map to XML file
00157     */
00158 bool save_utc_xml(const std::string& file_name, Gps_Utc_Model& utc);
00159
00160     /*!
00161     * \brief Read CNAV GPS utc model from XML file
00162     */
00163 bool load_cnav_utc_xml(const std::string& file_name);
00164
00165     /*!
00166     * \brief Save CNAV UTC model map to XML file
00167     */
00168 bool save_cnav_utc_xml(const std::string& file_name, Gps_CNAV_Utc_Model& utc);
00169
00170     /*!
00171     * \brief Read Galileo utc model from XML file
00172     */
00173 bool load_gal_utc_xml(const std::string& file_name);
00174
00175     /*!
00176     * \brief Save Galileo UTC model map to XML file
00177     */
00178 bool save_gal_utc_xml(const std::string& file_name, Galileo_Utc_Model& utc);
00179
00180     /*!
00181     * \brief Read Galileo almanac map from XML file
00182     */
00183 bool load_gal_almanac_xml(const std::string& file_name);
00184
00185     /*!
00186     * \brief Save Galileo almanac map to XML file
00187     */
00188 bool save_gal_almanac_xml(const std::string& file_name, std::map<int, Galileo_Almanac>
galileo_almanac_map_to_save);
```

```

00189
00190     /*!
00191     * \brief Read GPS almanac map from XML file
00192     */
00193     bool load_gps_almanac_xml(const std::string& file_name);
00194
00195     /*!
00196     * \brief Save GPS almanac map to XML file
00197     */
00198     bool save_gps_almanac_xml(const std::string& file_name, std::map<int, Gps_Almanac>
gps_almanac_map_to_save);
00199
00200     /*!
00201     * \brief Read iono from XML file
00202     */
00203     bool load_iono_xml(const std::string& file_name);
00204
00205     /*!
00206     * \brief Save iono map to XML file
00207     */
00208     bool save_iono_xml(const std::string& file_name, Gps_Iono& iono);
00209
00210     /*!
00211     * \brief Read Galileo iono from XML file
00212     */
00213     bool load_gal_iono_xml(const std::string& file_name);
00214
00215     /*!
00216     * \brief Save Galileo iono map to XML file
00217     */
00218     bool save_gal_iono_xml(const std::string& file_name, Galileo_Iono& iono);
00219
00220     /*!
00221     * \brief Read Glonass utc model from XML file
00222     */
00223     bool load_glo_utc_xml(const std::string& file_name);
00224
00225     /*!
00226     * \brief Save Glonass UTC model map to XML file
00227     */
00228     bool save_glo_utc_xml(const std::string& file_name, Glonass_Gnav_Utc_Model& utc);
00229
00230     /*!
00231     * \brief Read ref time from XML file
00232     */
00233     bool load_ref_time_xml(const std::string& file_name);
00234
00235     /*!
00236     * \brief Save ref time map to XML file
00237     */
00238     bool save_ref_time_xml(const std::string& file_name,
00239         Agnss_Ref_Time& ref_time_map);
00240
00241     /*!
00242     * \brief Read ref location from XML file
00243     */
00244     bool load_ref_location_xml(const std::string& file_name);
00245
00246     /*!
00247     * \brief Save ref location map to XML file
00248     */
00249     bool save_ref_location_xml(const std::string& file_name,
00250         Agnss_Ref_Location& ref_location);
00251
00252     /*
00253     * Prints SUPL data to std::cout. Use it for debug purposes only.
00254     */
00255     void print_assistance();
00256
00257 private:
00258     bool read_gal_almanac_from_gsa(const std::string& file_name);
00259     // assistance protocol structure
00260     supl_ctx_t ctx{};
00261     // assistance data
00262     supl_assist_t assist{};
00263     // GSM CELL INFO
00264     int mcc;
00265     int mns;
00266     int lac;
00267     int ci;
00268 };
00269
00270
00271 /** \} */
00272 /** \} */
00273 #endif // GNSS_SDR_SUPL_CLIENT_H

```

13.661 gnss_sdr_time_counter.h File Reference

Simple block to report the current receiver time based on the output of the tracking or telemetry blocks.

```
#include <gnuradio/block.h>
#include <gnuradio/types.h>
#include <cstdint>
#include <memory>
```

Classes

- class [gnss_sdr_time_counter](#)

Typedefs

- using [gnss_sdr_time_counter_sptr](#) = std::shared_ptr<[gnss_sdr_time_counter](#)>

Functions

- [gnss_sdr_time_counter_sptr gnss_sdr_make_time_counter](#) ()

13.661.1 Detailed Description

Simple block to report the current receiver time based on the output of the tracking or telemetry blocks.

Author

Antonio Ramos 2018. antonio.ramosdet(at)gmail.com

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 Definition in file [gnss_sdr_time_counter.h](#).

13.662 gnss_sdr_time_counter.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gnss_sdr_time_counter.h
00003  * \brief Simple block to report the current receiver time based on the output of the tracking or
00004  * \author Antonio Ramos 2018. antonio.ramosdet(at)gmail.com
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GNSS_SDR_TIME_COUNTER_H
00019 #define GNSS_SDR_GNSS_SDR_TIME_COUNTER_H
00020
00021 #include <gnuradio/block.h>
00022 #include <gnuradio/types.h> // for gr_vector_const_void_star
00023 #include <cstdint>
00024 #include <memory>
00025
00026 /** \addtogroup Core
00027  * \{ */
00028 /** \addtogroup Core_Receiver_Library
00029  * \{ */
00030
00031
00032 class gnss_sdr_time_counter;
00033
00034 using gnss_sdr_time_counter_sptr = std::shared_ptr<gnss_sdr_time_counter>;
```

```

00035
00036 gnss_sdr_time_counter_sptr gnss_sdr_make_time_counter();
00037
00038 class gnss_sdr_time_counter : public gr::block
00039 {
00040 public:
00041     ~gnss_sdr_time_counter() = default;
00042     int general_work(int noutput_items __attribute__((unused)),
00043                     gr_vector_int &ninput_items __attribute__((unused)),
00044                     gr_vector_const_void_star &input_items __attribute__((unused)),
00045                     gr_vector_void_star &output_items);
00046
00047 private:
00048     gnss_sdr_time_counter();
00049     friend gnss_sdr_time_counter_sptr gnss_sdr_make_time_counter();
00050
00051     int64_t current_T_rx_ms; // Receiver time in ms since the beginning of the run
00052     int32_t report_interval_ms;
00053     uint32_t current_s; // Receiver time in seconds, modulo 60
00054     uint32_t current_m; // Receiver time in minutes, modulo 60
00055     uint32_t current_h; // Receiver time in hours, modulo 24
00056     uint32_t current_days; // Receiver time in days since the beginning of the run
00057     bool flag_m; // True if the receiver has been running for at least 1 minute
00058     bool flag_h; // True if the receiver has been running for at least 1 hour
00059     bool flag_days; // True if the receiver has been running for at least 1 day
00060 };
00061
00062
00063 /** \} */
00064 /** \} */
00065 #endif // GNSS_SDR_GNSS_SDR_SAMPLE_COUNTER_H

```

13.663 ini.h File Reference

This function parses an INI file into easy-to-access name/value pairs.

Macros

- #define `INI_ALLOW_MULTILINE` 1

Functions

- int `ini_parse` (const char *filename, int(*handler)(void *user, const char *section, const char *name, const char *value), void *user)

Parse given INI-style file. May have [section]s, name=value pairs (whitespace stripped), and comments starting with ';' (semicolon). Section is "" if name=value pair parsed before any section heading.

13.663.1 Detailed Description

This function parses an INI file into easy-to-access name/value pairs.

Author

Brush Technologies, 2009.

inih (INI Not Invented Here) is a simple .INI file parser written in C++. It's only a couple of pages of code, and it was designed to be small and simple, so it's good for embedded systems. To use it, just give `ini_parse()` an INI file, and it will call a callback for every name=value pair parsed, giving you strings for the section, name, and value. It's done this way because it works well on low-memory embedded systems, but also because it makes for a KISS implementation. Parse given INI-style file. May have [section]s, name=value pairs (whitespace stripped), and comments starting with ';' (semicolon). Section is "" if name=value pair parsed before any section heading. For each name=value pair parsed, call handler function with given user pointer as well as section, name, and value (data only valid for duration of handler call). Handler should return nonzero on success, zero on error. Returns 0 on success, line number of first error on parse error, on -1 on file open error

inih and INIReaden are released under the New BSD license:

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SPDX-License-Identifier: BSD-3-Clause

Go to the project home page for more info:

13.663.1.1 <https://github.com/benhoyt/inih>

Definition in file [ini.h](#).

13.664 ini.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file ini.h
00003  * \brief This function parses an INI file into easy-to-access name/value pairs.
00004  * \author Brush Technologies, 2009.
00005  *
00006  * inih (INI Not Invented Here) is a simple .INI file parser written in C++.
00007  * It's only a couple of pages of code, and it was designed to be small
00008  * and simple, so it's good for embedded systems. To use it, just give
00009  * ini_parse() an INI file, and it will call a callback for every
00010  * name=value pair parsed, giving you strings for the section, name,
00011  * and value. It's done this way because it works well on low-memory
00012  * embedded systems, but also because it makes for a KISS implementation.
00013  * Parse given INI-style file. May have [section]s, name=value pairs
00014  * (whitespace stripped), and comments starting with ';' (semicolon).
00015  * Section is "" if name=value pair parsed before any section heading.
00016  * For each name=value pair parsed, call handler function with given user
00017  * pointer as well as section, name, and value (data only valid for duration
00018  * of handler call). Handler should return nonzero on success, zero on error.
00019  * Returns 0 on success, line number of first error on parse error, on -1 on
00020  * file open error
00021  *
00022  * -----
00023  * inih and INIReaden are released under the New BSD license:
00024  *
00025  * Copyright (c) 2009, Brush Technology
00026  * All rights reserved.
00027  *
00028  * SPDX-License-Identifier: BSD-3-Clause
00029  *
00030  * Go to the project home page for more info:
00031  *
00032  * https://github.com/benhoyt/inih
00033  * -----
00034  */
00035
00036 #ifndef GNSS_SDR_INI_H
00037 #define GNSS_SDR_INI_H
00038
00039 /** \addtogroup Core
00040  * \{ */
00041 /** \addtogroup Core_Receiver_Library
00042  * \{ */
00043
00044
00045 /*! \brief Parse given INI-style file. May have [section]s, name=value pairs
00046  * (whitespace stripped), and comments starting with ';' (semicolon). Section
00047  * is "" if name=value pair parsed before any section heading.
00048
00049  * For each name=value pair parsed, call handler function with given user
00050  * pointer as well as section, name, and value (data only valid for duration
00051  * of handler call). Handler should return nonzero on success, zero on error.
00052
00053  * Returns 0 on success, line number of first error on parse error, on -1 on
00054  * file open error.
00055  */
00056 int ini_parse(const char* filename,
00057              int (*handler)(void* user, const char* section,
00058                             const char* name, const char* value),
00059              void* user);
00060
00061 /* Nonzero to allow multi-line value parsing, in the style of Python's
00062  * ConfigParser. If allowed, ini_parse() will call the handler with the same
00063  * name for each subsequent line parsed. */
00064 #ifndef INI_ALLOW_MULTILINE
00065 #define INI_ALLOW_MULTILINE 1
00066 #endif
00067
00068
00069 /** \} */
00070 /** \} */
00071 #endif // GNSS_SDR_INI_H

```

13.665 INIReader.h File Reference

This class reads an INI file into easy-to-access name/value pairs.

```
#include <stdint>
#include <map>
#include <string>
```

Classes

- class [INIReader](#)

Read an INI file into easy-to-access name/value pairs. (Note that I've gone for simplicity here rather than speed, but it should be pretty decent.)

13.665.1 Detailed Description

This class reads an INI file into easy-to-access name/value pairs.

Author

Brush Technologies, 2009.

inih (INI Not Invented Here) is a simple .INI file parser written in C++. It's only a couple of pages of code, and it was designed to be small and simple, so it's good for embedded systems. To use it, just give [ini_parse\(\)](#) an INI file, and it will call a callback for every name=value pair parsed, giving you strings for the section, name, and value. It's done this way because it works well on low-memory embedded systems, but also because it makes for a KISS implementation.

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Go to the project home page for more info:

13.665.1.1 <https://github.com/benhoyt/inih>

Definition in file [INIReader.h](#).

13.666 INIReader.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file INIReader.h
00003  * \brief This class reads an INI file into easy-to-access name/value pairs.
00004  * \author Brush Technologies, 2009.
00005  *
00006  * inih (INI Not Invented Here) is a simple .INI file parser written in C++.
00007  * It's only a couple of pages of code, and it was designed to be small
00008  * and simple, so it's good for embedded systems. To use it, just give
00009  * ini_parse() an INI file, and it will call a callback for every
00010  * name=value pair parsed, giving you strings for the section, name,
00011  * and value. It's done this way because it works well on low-memory
00012  * embedded systems, but also because it makes for a KISS implementation.
00013  *
00014  * -----
00015  * inih and INIReader are released under the New BSD license:
00016  *
00017  * Copyright (c) 2009, Brush Technology
00018  * All rights reserved.
00019  *
00020  * SPDX-License-Identifier: BSD-3-Clause
00021  *
00022  * Go to the project home page for more info:
00023  *
00024  * https://github.com/benhoyt/inih
00025  * -----
00026  */
00027
00028 #ifndef GNSS_SDR_INIREADER_H
00029 #define GNSS_SDR_INIREADER_H
00030
```

```

00031 #include <stdint>
00032 #include <map>
00033 #include <string>
00034
00035 /** \addtogroup Core
00036 * \{ */
00037 /** \addtogroup Core_Receiver_Library
00038 * \{ */
00039
00040
00041 /*!
00042 * \brief Read an INI file into easy-to-access name/value pairs. (Note that I've gone
00043 * for simplicity here rather than speed, but it should be pretty decent.)
00044 */
00045 class INIReader
00046 {
00047 public:
00048     /** Construct INIReader and parse given filename. See ini.h for more info about the parsing.
00049     explicit INIReader(const std::string& filename);
00050
00051     /** Return the result of ini_parse(), i.e., 0 on success, line number of first error on parse
    error, or -1 on file open error.
00052     int ParseError() const;
00053
00054     /** Get a string value from INI file, returning default_value if not found.
00055     std::string Get(const std::string& section, const std::string& name,
00056                     const std::string& default_value);
00057
00058     /** Get an integer (long) value from INI file, returning default_value if not found.
00059     int64_t GetInteger(const std::string& section, const std::string& name, int64_t default_value);
00060
00061     /** Return true if the given section exists (section must contain at least one name=value pair).
00062     bool HasSection(const std::string& section) const;
00063
00064     /** Return true if a value exists with the given section and field names.
00065     bool HasValue(const std::string& section, const std::string& name) const;
00066
00067 private:
00068     static std::string MakeKey(const std::string& section, const std::string& name);
00069     static int ValueHandler(void* user, const char* section, const char* name,
00070                             const char* value);
00071
00072     std::map<std::string, std::string> _values;
00073     int _error;
00074 };
00075
00076
00077 /** \} */
00078 /** \} */
00079 #endif // GNSS_SDR_INIREADER_H

```

13.667 nav_message_monitor.h File Reference

GNU Radio block that processes [Nav_Message_Packet](#) received from telemetry blocks and sends them via UDP.

```

#include "gnss_block_interface.h"
#include "nav_message_udp_sink.h"
#include <gnuradio/block.h>
#include <pmt/pmt.h>
#include <stdint>
#include <memory>
#include <string>
#include <vector>

```

Classes

- class [nav_message_monitor](#)

GNU Radio block that receives asynchronous [Nav_Message_Packet](#) objects from the telemetry blocks and sends them via UDP.

Typedefs

- using [nav_message_monitor_sptr](#) = [gnss_shared_ptr](#)<[nav_message_monitor](#)>

Functions

- `nav_message_monitor_sptr nav_message_monitor_make (const std::vector< std::string > &addresses, uint16_t port)`

13.667.1 Detailed Description

GNU Radio block that processes [Nav_Message_Packet](#) received from telemetry blocks and sends them via UDP.

Author

Carles Fernandez-Prades, 2021. [cfernandez\(at\)cttc.es](mailto:cfernandez(at)cttc.es)

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Definition in file [nav_message_monitor.h](#).

13.668 nav_message_monitor.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file nav_message_monitor.h
00003  * \brief GNU Radio block that processes Nav_Message_Packet received from
00004  * telemetry blocks and sends them via UDP.
00005  * \author Carles Fernandez-Prades, 2021. cfernandez(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_NAV_MESSAGE_MONITOR_H
00019 #define GNSS_SDR_NAV_MESSAGE_MONITOR_H
00020
00021 #include "gnss_block_interface.h"
00022 #include "nav_message_udp_sink.h"
00023 #include <gnuradio/block.h>
00024 #include <pmt/pmt.h>
00025 #include <stdint>
00026 #include <memory>
00027 #include <string>
00028 #include <vector>
00029
00030 /** \addtogroup Core
00031  * \{ */
00032 /** \addtogroup Core_Receiver_Library
00033  * \{ */
00034
00035 class nav_message_monitor;
00036
00037 using nav_message_monitor_sptr = gnss_shared_ptr<nav_message_monitor>;
00038
00039 nav_message_monitor_sptr nav_message_monitor_make(const std::vector<std::string>& addresses, uint16_t
port);
00040
00041 /*!
00042  * \brief GNU Radio block that receives asynchronous Nav_Message_Packet objects
00043  * from the telemetry blocks and sends them via UDP
00044  */
00045 class nav_message_monitor : public gr::block
00046 {
00047 public:
00048     ~nav_message_monitor() = default;    //!< Default destructor
00049
00050 private:
00051     friend nav_message_monitor_sptr nav_message_monitor_make(const std::vector<std::string>&
addresses, uint16_t port);
00052     nav_message_monitor(const std::vector<std::string>& addresses, uint16_t port);
00053     void msg_handler_nav_message(const pmt::pmt_t& msg);
00054     std::unique_ptr<Nav_Message_Udp_Sink> nav_message_udp_sink_;
00055 };
00056
00057

```

```

00058 /** \} */
00059 /** \} */
00060 #endif // GNSS_SDR_NAV_MESSAGE_MONITOR_H

```

13.669 nav_message_packet.h File Reference

Class for storage of decoded navigation messages.

```

#include <stdint>
#include <string>
#include <utility>

```

Classes

- class [Nav_Message_Packet](#)

13.669.1 Detailed Description

Class for storage of decoded navigation messages.

Author

Carles Fernandez-Prades, 2021. cfernandez(at)cttc.es

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 Definition in file [nav_message_packet.h](#).

13.670 nav_message_packet.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file nav_message_packet.h
00003  * \brief Class for storage of decoded navigation messages
00004  * \author Carles Fernandez-Prades, 2021. cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_NAV_MESSAGE_PACKET_H
00018 #define GNSS_SDR_NAV_MESSAGE_PACKET_H
00019
00020 #include <stdint>
00021 #include <string>
00022 #include <utility>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup Core_Receiver_Library
00027  * \{ */
00028
00029 class Nav_Message_Packet
00030 {
00031 public:
00032     Nav_Message_Packet() = default; //!< Default constructor
00033
00034     ~Nav_Message_Packet() = default; //!< Default destructor
00035
00036     std::string system; //!< GNSS constellation: "G" for GPS, "R" for Glonass, "S" for
00037     SBAS, "E" for Galileo and "C" for Beidou.
00038     std::string signal; //!< GNSS signal: "1C" for GPS L1 C/A, "1B" for Galileo E1b/c,
00039     "1G" for Glonass L1 C/A, "2S" for GPS L2 L2C(M), "2G" for Glonass L2 C/A, "L5" for GPS L5 and "5X" for
00040     Galileo E5a
00041     int32_t prn; //!< SV ID
00042     int32_t tow_at_current_symbol_ms; //!< Time of week of the current symbol, in ms

```

```

00040     std::string nav_message;           //!< Content of the navigation page
00041
00042     /// Copy constructor
00043     Nav_Message_Packet(const Nav_Message_Packet& other) noexcept
00044     {
00045         *this = other;
00046     };
00047
00048     /// Copy assignment operator
00049     Nav_Message_Packet& operator=(const Nav_Message_Packet& rhs) noexcept
00050     {
00051         // Only do assignment if RHS is a different object from this.
00052         if (this != &rhs)
00053         {
00054             this->system = rhs.system;
00055             this->signal = rhs.signal;
00056             this->prn = rhs.prn;
00057             this->tow_at_current_symbol_ms = rhs.tow_at_current_symbol_ms;
00058             this->nav_message = rhs.nav_message;
00059         }
00060         return *this;
00061     };
00062
00063     /// Move constructor
00064     Nav_Message_Packet(Nav_Message_Packet&& other) noexcept
00065     {
00066         *this = std::move(other);
00067     };
00068
00069     /// Move assignment operator
00070     Nav_Message_Packet& operator=(Nav_Message_Packet&& other) noexcept
00071     {
00072         if (this != &other)
00073         {
00074             this->system = other.system;
00075             this->signal = other.signal;
00076             this->prn = other.prn;
00077             this->tow_at_current_symbol_ms = other.tow_at_current_symbol_ms;
00078             this->nav_message = other.nav_message;
00079         }
00080         return *this;
00081     };
00082 };
00083
00084 /** @} */
00085 /** @} */
00086 #endif // GNSS_SDR_NAV_MESSAGE_PACKET_H

```

13.671 nav_message_udp_sink.h File Reference

Interface of a class that sends serialized [Nav_Message_Packet](#) objects over UDP to one or multiple endpoints.

```

#include "nav_message_packet.h"
#include "serdes_nav_message.h"
#include <boost/asio.hpp>
#include <memory>
#include <string>
#include <vector>

```

Classes

- class [Nav_Message_Udp_Sink](#)

Typedefs

- using [b_io_context](#) = boost::asio::io_service

13.671.1 Detailed Description

Interface of a class that sends serialized [Nav_Message_Packet](#) objects over UDP to one or multiple endpoints.

Author

Carles Fernandez-Prades, 2021. cfernandez(at)cttc.es

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 Definition in file [nav_message_udp_sink.h](#).

13.672 nav_message_udp_sink.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002   * \file nav_message_udp_sink.h
00003   * \brief Interface of a class that sends serialized Nav_Message_Packet objects
00004   * over UDP to one or multiple endpoints.
00005   * \author Carles Fernandez-Prades, 2021. cfernandez(at)cttc.es
00006   *
00007   * -----
00008   *
00009   * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010   * This file is part of GNSS-SDR.
00011   *
00012   * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00013   * SPDX-License-Identifier: GPL-3.0-or-later
00014   *
00015   * -----
00016   */
00017
00018 #ifndef GNSS_SDR_NAV_MESSAGE_UDP_SINK_H
00019 #define GNSS_SDR_NAV_MESSAGE_UDP_SINK_H
00020
00021 #include "nav_message_packet.h"
00022 #include "serdes_nav_message.h"
00023 #include <boost/asio.hpp>
00024 #include <memory>
00025 #include <string>
00026 #include <vector>
00027
00028 /** \addtogroup Core
00029  * \{ */
00030 /** \addtogroup Core_Receiver_Library
00031  * \{ */
00032
00033 #if USE_BOOST_ASIO_IO_CONTEXT
00034 using b_io_context = boost::asio::io_context;
00035 #else
00036 using b_io_context = boost::asio::io_service;
00037 #endif
00038
00039 class Nav_Message_Udp_Sink
00040 {
00041 public:
00042     Nav_Message_Udp_Sink(const std::vector<std::string>& addresses, const uint16_t& port);
00043     bool write_nav_message(const std::shared_ptr<Nav_Message_Packet>& nav_meg_packet);
00044
00045 private:
00046     Serdes_Nav_Message serdes_nav;
00047     b_io_context io_context;
00048     boost::asio::ip::udp::socket socket;
00049     std::vector<boost::asio::ip::udp::endpoint> endpoints;
00050     boost::system::error_code error;
00051 };
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_NAV_MESSAGE_UDP_SINK_H

```

13.673 osnma_helper.h File Reference

Class for auxiliary osnma functions.

```

#include <stdint>
#include <ctime>
#include <string>
#include <vector>

```

Classes

- class [Osnma_Helper](#)

13.673.1 Detailed Description

Class for auxiliary osnma functions.

Author

Carles Fernandez-Prades, 2024 cfernandez(at)cttc.es

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Definition in file [osnma_helper.h](#).

13.674 osnma_helper.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file osnma_helper.h
00003  * \brief Class for auxiliary osnma functions
00004  * \author Carles Fernandez-Prades, 2024 cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2023 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_OSNMA_HELPER_H
00018 #define GNSS_SDR_OSNMA_HELPER_H
00019
00020
00021 #include <cstdint>
00022 #include <ctime>
00023 #include <string>
00024 #include <vector>
00025
00026 /** \addtogroup Core
00027  * \{ */
00028 /** \addtogroup Core_Receiver_Library
00029  * \{ */
00030
00031 class Osnma_Helper
00032 {
00033 public:
00034     Osnma_Helper();
00035     ~Osnma_Helper() = default;
00036     uint32_t compute_gst(uint32_t WN, uint32_t TOW) const;
00037     uint32_t compute_gst(std::tm& input);
00038     uint32_t compute_gst_now();
00039     uint32_t get_WN(uint32_t GST) const;
00040     uint32_t get_TOW(uint32_t GST) const;
00041     std::vector<uint8_t> gst_to_uint8(uint32_t GST) const;
00042     std::vector<uint8_t> bytes(const std::string& binaryString) const;
00043     std::string verification_status_str(int status) const;
00044     std::string convert_to_hex_string(const std::vector<uint8_t>& vector) const;
00045     std::vector<uint8_t> convert_from_hex_string(const std::string& hex_string) const; // TODO remove
00046     similar function in gnss_crypto
00047     std::tm GST_START_EPOCH{};
00048 };
00049 /** \} */
00050 /** \} */
00051 #endif // GNSS_SDR_OSNMA_HELPER_H

```

13.675 osnma_msg_receiver.h File Reference

GNU Radio block that processes Galileo OSNMA data received from Galileo E1B telemetry blocks. After successful decoding, sends the content to the PVT block.


```
#include "galileo_inav_message.h"
#include "gnss_block_interface.h"
#include "osnma_data.h"
#include "osnma_nav_data_manager.h"
#include <gnuradio/block.h>
#include <pmt/pmt.h>
#include <array>
#include <stdint>
#include <ctime>
#include <map>
#include <memory>
#include <string>
#include <utility>
#include <vector>
```

Classes

- class [osnma_msg_receiver](#)

GNU Radio block that receives asynchronous OSNMA messages from the telemetry blocks, stores them in memory, and decodes OSNMA info when enough data have been received. The decoded OSNMA data is sent to the PVT block.

Macros

- #define [FRIEND_TEST](#)(test_case_name, test_name)

Typedefs

- using [osnma_msg_receiver_sptr](#) = gnss_shared_ptr<[osnma_msg_receiver](#)>

Functions

- [osnma_msg_receiver_sptr osnma_msg_receiver_make](#) (const std::string &pemFilePath, const std::string &merkleFilePath, bool strict_mode=false)

13.675.1 Detailed Description

GNU Radio block that processes Galileo OSNMA data received from Galileo E1B telemetry blocks. After successful decoding, sends the content to the PVT block.

Author

Carles Fernandez-Prades, 2023-2024. [cfernandez\(at\)cttc.es](mailto:cfernandez@cttc.es) Cesare Ghionoiu Martinez, 2023-2024. [c, ↩ ghionoiu-martinez@tu-braunschweig.de](mailto:ghionoiu-martinez@tu-braunschweig.de)

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR. Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors) SPDX-License-Identifier: GPL-3.0-or-later Definition in file [osnma_msg_receiver.h](#).

13.675.2 Macro Definition Documentation

13.675.2.1 FRIEND_TEST

```
#define FRIEND_TEST(
    test_case_name,
    test_name)
```

Value:

```
friend class test_case_name##_Test
```

Definition at line 23 of file [osnma_msg_receiver.h](#).

13.676 osnma_msg_receiver.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file osnma_msg_receiver.h
00003  * \brief GNU Radio block that processes Galileo OSNMA data received from
00004  * Galileo E1B telemetry blocks. After successful decoding, sends the content to
00005  * the PVT block.
00006  * \author Carles Fernandez-Prades, 2023-2024. cfernandez(at)cttc.es
00007  * Cesare Ghionoiu Martinez, 2023-2024. c.ghionoiu-martinez@tu-braunschweig.de
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_OSNMA_MSG_RECEIVER_H
00021 #define GNSS_SDR_OSNMA_MSG_RECEIVER_H
00022
00023 #define FRIEND_TEST(test_case_name, test_name) \
00024     friend class test_case_name##_Test
00025
00026 #include "galileo_inav_message.h" // for OSNMA_msg
00027 #include "gnss_block_interface.h" // for gnss_shared_ptr
00028 #include "osnma_data.h" // for OSNMA_data structures
00029 #include "osnma_nav_data_manager.h" // for OSNMA_NavDataManager
00030 #include <gnuradio/block.h> // for gr::block
00031 #include <pmt/pmt.h> // for pmt::pmt_t
00032 #include <array> // for std::array
00033 #include <cstdint> // for uint8_t
00034 #include <ctime> // for std::time_t
00035 #include <map> // for std::map, std::multimap
00036 #include <memory> // for std::shared_ptr
00037 #include <string> // for std::string
00038 #include <utility> // for std::pair
00039 #include <vector> // for std::vector
00040
00041 /** \addtogroup Core
00042  * \{ */
00043 /** \addtogroup Core_Receiver_Library
00044  * \{ */
00045
00046 class OSNMA_DSM_Reader;
00047 class Gnss_Crypto;
00048 class Osnma_Helper;
00049 class osnma_msg_receiver;
00050
00051 using osnma_msg_receiver_sptr = gnss_shared_ptr<osnma_msg_receiver>;
00052
00053 osnma_msg_receiver_sptr osnma_msg_receiver_make(const std::string& pemFilePath, const std::string&
00054 merkleFilePath, bool strict_mode = false);
00055
00056 /*!
00057 * \brief GNU Radio block that receives asynchronous OSNMA messages
00058 * from the telemetry blocks, stores them in memory, and decodes OSNMA info
00059 * when enough data have been received.
00060 * The decoded OSNMA data is sent to the PVT block.
00061 */
00062 class osnma_msg_receiver : public gr::block
00063 {
00064 public:
00065     ~osnma_msg_receiver() = default; //!< Default destructor
00066     bool verify_dsm_pkr(const DSM_PKR_message& message) const; //!< Public for benchmarking purposes
00067     void msg_handler_osnma(const pmt::pmt_t& msg); //!< For testing purposes
00068     void read_merkle_xml(const std::string& merklepath); //!< Public for testing purposes
00069     void set_merkle_root(const std::vector<uint8_t>& v); //!< Public for benchmarking purposes
00070 private:
00071     friend osnma_msg_receiver_sptr osnma_msg_receiver_make(const std::string& pemFilePath, const
00072 std::string& merkleFilePath, bool strict_mode);
00073     osnma_msg_receiver(const std::string& crtFilePath, const std::string& merkleFilePath, bool
00074 strict_mode);
00075
00076     void process_osnma_message(const std::shared_ptr<OSNMA_msg>& osnma_msg);
00077     void read_nma_header(uint8_t nma_header);
00078     void read_dsm_header(uint8_t dsm_header);
00079     void read_dsm_block(const std::shared_ptr<OSNMA_msg>& osnma_msg);
00080     void process_dsm_block(const std::shared_ptr<OSNMA_msg>& osnma_msg);
00081     void process_dsm_message(const std::vector<uint8_t>& dsm_msg, const uint8_t& nma_header);
00082     void read_and_process_mack_block(const std::shared_ptr<OSNMA_msg>& osnma_msg);

```

```

00081     void read_mack_header();
00082     void read_mack_body();
00083     void process_mack_message();
00084     void remove_verified_tags();
00085     void control_tags_awaiting_verify_size();
00086     void send_data_to_pvt(const std::vector<OSNMA_NavData>& data);
00087
00088     bool verify_tesla_key(std::vector<uint8_t>& key, uint32_t TOW);
00089     bool verify_tag(Tag& tag) const;
00090     bool tag_has_nav_data_available(const Tag& t) const;
00091     bool tag_has_key_available(const Tag& t) const;
00092     bool store_dsm_kroot(const std::vector<uint8_t>& dsm, const uint8_t nma_header) const;
00093
00094     std::pair<std::vector<uint8_t>, uint8_t> parse_dsm_kroot() const;
00095     std::vector<uint8_t> get_merkle_tree_leaves(const DSM_PKR_message& dsm_pkr_message) const;
00096     std::vector<uint8_t> compute_merkle_root(const DSM_PKR_message& dsm_pkr_message, const
std::vector<uint8_t>& m_i) const;
00097     std::vector<uint8_t> build_message(Tag& tag) const;
00098     std::vector<uint8_t> hash_chain(uint32_t num_of_hashes_needed, const std::vector<uint8_t>& key,
uint32_t GST_Sf, const uint8_t lk_bytes) const;
00099     std::vector<MACK_tag_and_info> verify_macseq(const MACK_message& mack);
00100
00101     std::map<uint32_t, std::map<uint32_t, OSNMA_NavData> d_satellite_nav_data; // map holding
OSNMA_NavData sorted by SVID (first key) and TOW (second key).
00102     std::map<uint32_t, std::vector<uint8_t> d_tesla_keys; // tesla keys over
time, sorted by TOW
00103     std::multimap<uint32_t, Tag> d_tags_awaiting_verify; // container with
tags to verify from arbitrary SVIDs, sorted by TOW
00104
00105     std::vector<uint8_t> d_new_public_key;
00106     std::vector<uint8_t> d_tags_to_verify{0, 4, 12};
00107     std::vector<MACK_message> d_macks_awaiting_MACSEQ_verification;
00108
00109     std::array<std::array<uint8_t, 256>, 16> d_dsm_message{}; // structure for recording DSM blocks,
when filled it sends them to parse and resets itself.
00110     std::array<std::array<uint8_t, 16>, 16> d_dsm_id_received{};
00111     std::array<uint16_t, 16> d_number_of_blocks{};
00112     std::array<uint8_t, 60> d_mack_message{}; // C: 480 b
00113
00114     std::unique_ptr<Gnss_Crypto> d_crypto; // class for cryptographic functions
00115     std::unique_ptr<OSNMA_DSM_Reader> d_dsm_reader; // osnma parameters parser
00116     std::unique_ptr<Osnma_Helper> d_helper; // helper class with auxiliary
functions
00117     std::unique_ptr<OSNMA_NavDataManager> d_nav_data_manager; // refactor for holding and processing
navigation data
00118
00119     OSNMA_data d_osnma_data{};
00120
00121     uint32_t d_last_received_GST{0}; // latest GST received
00122     uint32_t d_GST_Sf{}; // Scaled GST time for cryptographic computations
00123     uint32_t d_GST_Rx{0}; // local GST receiver time
00124     uint32_t d_last_verified_key_GST{0}; // GST for the latest verified TESLA key
00125     uint32_t d_GST_0{}; // Time of applicability GST (KROOT + 30 s)
00126     uint32_t d_GST_SIS{}; // GST coming from W6 and W5 of SIS
00127     uint32_t d_GST_PKR_PKREV_start{};
00128     uint32_t d_GST_PKR_AM_start{};
00129     uint32_t d_GST_chain_renewal_start{};
00130     uint32_t d_GST_chain_revocation_start{};
00131
00132     uint32_t d_count_successful_tags{0};
00133     uint32_t d_count_failed_tags{0};
00134     uint32_t d_count_failed_Kroot{0};
00135     uint32_t d_count_failed_pubKey{0}; // failed public key verifications against Merkle root
00136     uint32_t d_count_failed_macseq{0};
00137
00138     uint8_t const d_T_L{30}; // s RG Section 2.1
00139     uint8_t d_new_public_key_id{};
00140
00141     bool d_new_data{false};
00142     bool d_public_key_verified{false};
00143     bool d_kroot_verified{false};
00144     bool d_tesla_key_verified{false};
00145     bool d_strict_mode{false};
00146     bool d_flag_hot_start{false};
00147     bool d_flag_PKR_renewal{false};
00148     bool d_flag_PKR_revocation{false};
00149     bool d_flag_NPK_set{false};
00150     bool d_flag_alert_message{false};
00151     bool d_flag_chain_renewal{false};
00152     bool d_flag_chain_revocation{false};
00153
00154     // Provide access to inner functions to Gtest
00155     FRIEND_TEST(OsnmaMsgReceiverTest, TeslaKeyVerification);
00156     FRIEND_TEST(OsnmaMsgReceiverTest, TagVerification);
00157     FRIEND_TEST(OsnmaMsgReceiverTest, BuildTagMessageM0);
00158     FRIEND_TEST(OsnmaMsgReceiverTest, VerifyPublicKey);
00159     FRIEND_TEST(OsnmaMsgReceiverTest, ComputeBaseLeaf);

```

```

00160     FRIEND_TEST(OsnmaMsgReceiverTest, ComputeMerkleRoot);
00161     FRIEND_TEST(OsnmaTestVectors, NominalTestConf1);
00162     FRIEND_TEST(OsnmaTestVectors, NominalTestConf2);
00163     FRIEND_TEST(OsnmaTestVectors, PublicKeyRenewal);
00164     FRIEND_TEST(OsnmaTestVectors, PublicKeyRevocation);
00165     FRIEND_TEST(OsnmaTestVectors, ChainRenewal);
00166     FRIEND_TEST(OsnmaTestVectors, ChainRevocation);
00167     FRIEND_TEST(OsnmaTestVectors, AlertMessage);
00168 };
00169
00170
00171 /** \} */
00172 /** \} */
00173 #endif // GNSS_SDR_OSNMA_MSG_RECEIVER_H

```

13.677 osnma_nav_data_manager.h File Reference

Class for Galileo OSNMA navigation data management.

```

#include "osnma_data.h"
#include <stdint>
#include <map>
#include <string>
#include <vector>

```

Classes

- class [OSNMA_NavDataManager](#)
Class for managing OSNMA navigation data.

13.677.1 Detailed Description

Class for Galileo OSNMA navigation data management.

Author

Cesare Ghionoiu-Martinez, 2020-2023 [cesare.martinez\(at\)proton.me](mailto:cesare.martinez(at)proton.me)

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Definition in file [osnma_nav_data_manager.h](#).

13.678 osnma_nav_data_manager.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file osnma_nav_data_manager.h
00003  * \brief Class for Galileo OSNMA navigation data management
00004  * \author Cesare Ghionoiu-Martinez, 2020-2023 cesare.martinez\(at\)proton.me
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2023 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_OSNMA_NAV_DATA_MANAGER_H
00018 #define GNSS_SDR_OSNMA_NAV_DATA_MANAGER_H
00019
00020 #include "osnma_data.h" // for OSNMA_NavData, Tag
00021 #include <stdint>        // for uint32_t
00022 #include <map>
00023 #include <string>
00024 #include <vector>
00025
00026 /** \addtogroup Core

```

```

00027  * \{ */
00028  /** \addtogroup Core_Receiver_Library
00029  * \{ */
00030
00031  /**
00032  * @class OSNMA_NavDataManager
00033  * @brief Class for managing OSNMA navigation data
00034  */
00035  class OSNMA_NavDataManager
00036  {
00037  public:
00038      OSNMA_NavDataManager() = default;
00039
00040      void log_status() const;
00041      bool have_nav_data(const Tag& t) const;
00042      bool have_nav_data(uint32_t PRNd, uint32_t TOW, uint8_t ADKD) const;
00043      std::string get_navigation_data(const Tag& t) const;
00044
00045      void add_navigation_data(const std::string& nav_bits, uint32_t PRNd, uint32_t TOW);
00046      void update_nav_data(const std::multimap<uint32_t, Tag>& tags_verified, uint8_t tag_size);
00047      bool have_nav_data(const std::string& nav_bits, uint32_t PRNd, uint32_t TOW);
00048      std::vector<OSNMA_NavData> get_verified_data();
00049
00050  private:
00051      std::map<uint32_t, std::map<uint32_t, OSNMA_NavData> d_satellite_nav_data{}; // NavData sorted by
00052      [PRNd][TOW_start]
00053      const uint32_t L_t_min{40};
00054      const uint16_t EPH_SIZE{549};
00055      const uint16_t UTC_SIZE{141};
00056  };
00057  /** \} */
00058  /** \} */
00059  #endif // GNSS_SDR_OSNMA_NAV_DATA_MANAGER_H

```

13.679 serdes_nav_message.h File Reference

Serialization / Deserialization of [Nav_Message_Packet](#) objects using Protocol Buffers.

```

#include "nav_message.pb.h"
#include "nav_message_packet.h"
#include <stdint>
#include <memory>
#include <string>
#include <utility>

```

Classes

- class [Serdes_Nav_Message](#)

This class implements serialization and deserialization of [Nav_Message_Packet](#) objects using Protocol Buffers.

13.679.1 Detailed Description

Serialization / Deserialization of [Nav_Message_Packet](#) objects using Protocol Buffers.

Author

Carles Fernandez-Prades, 2021. cfernandez(at)cttc.es

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Definition in file [serdes_nav_message.h](#).

13.680 serdes_nav_message.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file serdes_nav_message.h
00003  * \brief Serialization / Deserialization of Nav_Message_Packet objects using
00004  * Protocol Buffers
00005  * \author Carles Fernandez-Prades, 2021. cfernandez(at)cttc.es

```

```

00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_SERDES_NAV_MESSAGE_H
00019 #define GNSS_SDR_SERDES_NAV_MESSAGE_H
00020
00021 #include "nav_message.pb.h" // file created by Protocol Buffers at compile time
00022 #include "nav_message_packet.h"
00023 #include <stdint>
00024 #include <memory>
00025 #include <string>
00026 #include <utility>
00027
00028 /** \addtogroup Telemetry_Decoder
00029  * \{ */
00030 /** \addtogroup Telemetry_Decoder_libs
00031  * \{ */
00032
00033
00034 /*!
00035  * \brief This class implements serialization and deserialization of
00036  * Nav_Message_Packet objects using Protocol Buffers.
00037  */
00038 class Serdes_Nav_Message
00039 {
00040 public:
00041     Serdes_Nav_Message()
00042     {
00043         // Verify that the version of the library that we linked against is
00044         // compatible with the version of the headers we compiled against.
00045         GOOGLE_PROTOBUF_VERIFY_VERSION;
00046     }
00047
00048     ~Serdes_Nav_Message()
00049     {
00050         // google::protobuf::ShutdownProtobufLibrary();
00051     }
00052
00053     inline Serdes_Nav_Message(const Serdes_Nav_Message& other) noexcept : navmsg_(other.navmsg_) //!<
Copy constructor
00054     {
00055     }
00056
00057     inline Serdes_Nav_Message& operator=(const Serdes_Nav_Message& rhs) noexcept //!< Copy assignment
operator
00058     {
00059         if (this != &rhs)
00060         {
00061             this->navmsg_.CopyFrom(rhs.navmsg_);
00062         }
00063         return *this;
00064     }
00065
00066     inline Serdes_Nav_Message(Serdes_Nav_Message&& other) noexcept : navmsg_(std::move(other.navmsg_))
//!< Move constructor
00067     {
00068         // Set the other object's navmsg_ to a default-constructed state
00069         other.navmsg_ = gnss_sdr::navMsg{};
00070     }
00071
00072     inline Serdes_Nav_Message& operator=(Serdes_Nav_Message&& other) noexcept //!< Move assignment
operator
00073     {
00074         if (this != &other)
00075         {
00076             navmsg_ = std::move(other.navmsg_);
00077             other.navmsg_ = gnss_sdr::navMsg{};
00078         }
00079         return *this;
00080     }
00081
00082     inline std::string createProtobuffer(const std::shared_ptr<Nav_Message_Packet> nav_msg_packet)
//!< Serialization into a string
00083     {
00084         navmsg_.Clear();
00085         std::string data;
00086
00087         navmsg_.set_system(nav_msg_packet->system);

```

```

00088     navmsg_.set_signal(nav_msg_packet->signal);
00089     navmsg_.set_prn(nav_msg_packet->prn);
00090     navmsg_.set_tow_at_current_symbol_ms(nav_msg_packet->tow_at_current_symbol_ms);
00091     navmsg_.set_nav_message(nav_msg_packet->nav_message);
00092
00093     navmsg_.SerializeToString(&data);
00094
00095     return data;
00096 }
00097
00098 inline Nav_Message_Packet readProtobuffer(const gnss_sdr::navMsg& msg) const //!< Deserialization
00099 {
00100     Nav_Message_Packet navmsg;
00101
00102     navmsg.system = msg.system();
00103     navmsg.signal = msg.prn();
00104     navmsg.prn = msg.prn();
00105     navmsg.tow_at_current_symbol_ms = msg.tow_at_current_symbol_ms();
00106     navmsg.nav_message = msg.nav_message();
00107
00108     return navmsg;
00109 }
00110
00111 private:
00112     gnss_sdr::navMsg navmsg_{};
00113 };
00114
00115
00116 /** @} */
00117 /** @} */
00118 #endif // GNSS_SDR_SERDES_NAV_MESSAGE_H

```

13.681 string_converter.h File Reference

Interface of a class that interprets the contents of a string and converts it into different types.

```
#include <cstdint>
```

```
#include <string>
```

Classes

- class [StringConverter](#)

Class that interprets the contents of a string and converts it into different types.

13.681.1 Detailed Description

Interface of a class that interprets the contents of a string and converts it into different types.

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com

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Definition in file [string_converter.h](#).

13.682 string_converter.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file string_converter.h
00003  * \brief Interface of a class that interprets the contents of a string
00004  * and converts it into different types.
00005  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  *

```

```

00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_STRING_CONVERTER_H
00020 #define GNSS_SDR_STRING_CONVERTER_H
00021
00022 #include <stdint>
00023 #include <string>
00024
00025 /** \addtogroup Core
00026  * \{ */
00027 /** \addtogroup Core_Receiver_Library
00028  * \{ */
00029
00030
00031 /*!
00032 * \brief Class that interprets the contents of a string
00033 * and converts it into different types.
00034 */
00035 class StringConverter
00036 {
00037 public:
00038     StringConverter() = default;
00039     ~StringConverter() = default;
00040
00041     bool convert(const std::string& value, bool default_value);
00042     int64_t convert(const std::string& value, int64_t default_value);
00043     uint64_t convert(const std::string& value, uint64_t default_value);
00044     int32_t convert(const std::string& value, int32_t default_value);
00045     uint32_t convert(const std::string& value, uint32_t default_value);
00046     int16_t convert(const std::string& value, int16_t default_value);
00047     uint16_t convert(const std::string& value, uint16_t default_value);
00048     float convert(const std::string& value, float default_value);
00049     double convert(const std::string& value, double default_value);
00050 };
00051
00052
00053 /** \} */
00054 /** \} */
00055 #endif // GNSS_SDR_STRING_CONVERTER_H

```

13.683 uio_fpga.h File Reference

This library contains functions to determine the uio device driver file that corresponds to a hardware accelerator device name in the FPGA.

```

#include <stdint>
#include <string>

```

Functions

- `const std::string uio_dir` ("/sys/class/uio/")
- `const std::string uio_filename` ("uio")
- `const std::string uio_subdir_name` ("/name")
- `int32_t find_uio_dev_file_name` (std::string &device_file_name, const std::string &device_name, uint32_t device_num)

This function finds the uio device driver device file name out of the device name and the device number.

- `uint32_t get_num_devices` (const std::string &device_name)

Returns the number of devices (tracking multicorrelators) of type device_name available in the FPGA.

13.683.1 Detailed Description

This library contains functions to determine the uio device driver file that corresponds to a hardware accelerator device name in the FPGA.

Author

Marc Majoral, 2020. mmajoral(at)cttc.es

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Definition in file [uio_fpga.h](#).

13.684 uio_fpga.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file uio_fpga.h
00003  * \brief This library contains functions to determine the uio device driver
00004  * file that corresponds to a hardware accelerator device name in the FPGA.
00005  * \author Marc Majoral, 2020. mmajoral(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00011  *
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00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_UIO_FPGA_H
00019 #define GNSS_SDR_UIO_FPGA_H
00020
00021 #include <stdint>
00022 #include <string>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup Core_Receiver_Library
00027  * \{ */
00028
00029 const std::string uio_dir("/sys/class/uio/");
00030 const std::string uio_filename("uio");
00031 const std::string uio_subdir_name("/name");
00032
00033 /*!
00034 * \brief This function finds the uio device driver device file name out of the
00035 * device name and the device number.
00036 */
00037 int32_t find_uio_dev_file_name(std::string &device_file_name,
00038                               const std::string &device_name,
00039                               uint32_t device_num);
00040
00041 /*!
00042 * \brief Returns the number of devices (tracking multicorrelators) of type device_name available in
00043 * the FPGA
00044 */
00044 uint32_t get_num_devices(const std::string &device_name);
00045
00046 /** \} */
00047 /** \} */
00048 #endif // GNSS_SDR_UIO_FPGA_H

```

13.685 gnss_synchro_monitor.h File Reference

Interface of a receiver monitoring block which allows sending a data stream with the receiver internal parameters ([Gnss_Synchro](#) objects) to local or remote clients over UDP.

```

#include "gnss_block_interface.h"
#include "gnss_synchro_udp_sink.h"
#include <gnuradio/block.h>
#include <gnuradio/runtime_types.h>
#include <memory>
#include <string>
#include <vector>

```

Classes

- class [gnss_synchro_monitor](#)

This class implements a monitoring block which allows sending a data stream with the receiver internal parameters ([Gnss_Synchro](#) objects) to local or remote clients over UDP.

Typedefs

- using `gnss_synchro_monitor_sptr` = `gnss_shared_ptr<gnss_synchro_monitor>`

Functions

- `gnss_synchro_monitor_sptr gnss_synchro_make_monitor` (int n_channels, int decimation_factor, const std::vector< std::string > &udp_ports, const std::vector< std::string > &udp_addresses, bool enable_protobuf)

13.685.1 Detailed Description

Interface of a receiver monitoring block which allows sending a data stream with the receiver internal parameters (`Gnss_Synchro` objects) to local or remote clients over UDP.

Author

Álvaro Cebrián Juan, 2018. [acebrianjuan\(at\)gmail.com](mailto:acebrianjuan(at)gmail.com)

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 Definition in file [gnss_synchro_monitor.h](#).

13.686 gnss_synchro_monitor.h

[Go to the documentation of this file.](#)

```
00001  /*!
00002  * \file gnss_synchro_monitor.h
00003  * \brief Interface of a receiver monitoring block which allows sending
00004  * a data stream with the receiver internal parameters (Gnss_Synchro objects)
00005  * to local or remote clients over UDP.
00006  *
00007  * \author Álvaro Cebrián Juan, 2018. acebrianjuan\(at\)gmail.com
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
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00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_GNSS_SYNCHRO_MONITOR_H
00021 #define GNSS_SDR_GNSS_SYNCHRO_MONITOR_H
00022
00023 #include "gnss_block_interface.h"
00024 #include "gnss_synchro_udp_sink.h"
00025 #include <gnuradio/block.h>
00026 #include <gnuradio/runtime_types.h> // for gr_vector_void_star
00027 #include <memory>
00028 #include <string>
00029 #include <vector>
00030
00031 /** \addtogroup Core
00032  * \{ */
00033 /** \addtogroup Gnss_Synchro_Monitor core_monitor
00034  * Classes for the Gnss_Synchro monitor.
00035  * \{ */
00036
00037
00038 class gnss_synchro_monitor;
00039
00040 using gnss_synchro_monitor_sptr = gnss_shared_ptr<gnss_synchro_monitor>;
00041
00042 gnss_synchro_monitor_sptr gnss_synchro_make_monitor(int n_channels,
00043     int decimation_factor,
00044     const std::vector<std::string>& udp_ports,
00045     const std::vector<std::string>& udp_addresses,
00046     bool enable_protobuf);
00047
00048 /*!
00049 * \brief This class implements a monitoring block which allows sending
00050 * a data stream with the receiver internal parameters (Gnss_Synchro objects)
```

```

00051  * to local or remote clients over UDP.
00052  */
00053  class gnss_synchro_monitor : public gr::block
00054  {
00055  public:
00056      ~gnss_synchro_monitor() = default; //!< Default destructor
00057      void forecast(int noutput_items, gr_vector_int& ninput_items_required);
00058      int general_work(int noutput_items, gr_vector_int& ninput_items,
00059                      gr_vector_const_void_star& input_items, gr_vector_void_star& output_items);
00060  private:
00061      friend gnss_synchro_monitor_sptr gnss_synchro_make_monitor(int n_channels,
00062                      int decimation_factor,
00063                      const std::vector<std::string>& udp_ports,
00064                      const std::vector<std::string>& udp_addresses,
00065                      bool enable_protobuf);
00066      gnss_synchro_monitor(int n_channels,
00067                      int decimation_factor,
00068                      const std::vector<std::string>& udp_ports,
00069                      const std::vector<std::string>& udp_addresses,
00070                      bool enable_protobuf);
00071      std::unique_ptr<Gnss_Synchro_Udp_Sink> udp_sink_ptr;
00072      int count;
00073      int d_nchannels;
00074      int d_decimation_factor;
00075  };
00076  #endif // GNSS_SDR_GNSS_SYNCHRO_MONITOR_H

```

13.687 gnss_synchro_udp_sink.h File Reference

Interface of a class that sends serialized [Gnss_Synchro](#) objects over udp to one or multiple endpoints.

```

#include "gnss_synchro.h"
#include "serdes_gnss_synchro.h"
#include <boost/asio.hpp>
#include <boost/system/error_code.hpp>
#include <stdint>
#include <string>
#include <vector>

```

Classes

- class [Gnss_Synchro_Udp_Sink](#)

This class sends serialized [Gnss_Synchro](#) objects over UDP to one or multiple endpoints.

Typedefs

- using [b_io_context](#) = boost::asio::io_service

13.687.1 Detailed Description

Interface of a class that sends serialized [Gnss_Synchro](#) objects over udp to one or multiple endpoints.

Author

Álvaro Cebrián Juan, 2018. [acebrianjuan\(at\)gmail.com](mailto:acebrianjuan(at)gmail.com)

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 Definition in file [gnss_synchro_udp_sink.h](#).

13.688 gnss_synchro_udp_sink.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gnss_synchro_udp_sink.h
00003  * \brief Interface of a class that sends serialized Gnss_Synchro objects
00004  * over udp to one or multiple endpoints
00005  * \author Álvaro Cebrián Juan, 2018. acebrianjuan(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GNSS_SYNCHRO_UDP_SINK_H
00019 #define GNSS_SDR_GNSS_SYNCHRO_UDP_SINK_H
00020
00021 #include "gnss_synchro.h"
00022 #include "serdes_gnss_synchro.h"
00023 #include <boost/asio.hpp>
00024 #include <boost/system/error_code.hpp>
00025 #include <cstdint>
00026 #include <string>
00027 #include <vector>
00028
00029 /** \addtogroup Core
00030  * \{ */
00031 /** \addtogroup Gnss_Synchro_Monitor
00032  * \{ */
00033
00034
00035 #if USE_BOOST_ASIO_IO_CONTEXT
00036 using b_io_context = boost::asio::io_context;
00037 #else
00038 using b_io_context = boost::asio::io_service;
00039 #endif
00040
00041 /*!
00042 * \brief This class sends serialized Gnss_Synchro objects
00043 * over UDP to one or multiple endpoints.
00044 */
00045 class Gnss_Synchro_Udp_Sink
00046 {
00047 public:
00048     Gnss_Synchro_Udp_Sink(const std::vector<std::string>& addresses, const std::vector<std::string>&
        ports, bool enable_protobuf);
00049     bool write_gnss_synchro(const std::vector<Gnss_Synchro>& stocks);
00050
00051 private:
00052     b_io_context io_context;
00053     boost::asio::ip::udp::socket socket;
00054     boost::system::error_code error;
00055     std::vector<boost::asio::ip::udp::endpoint> endpoints;
00056     Serdes_Gnss_Synchro serdes;
00057     bool use_protobuf;
00058 };
00059
00060
00061 /** \} */
00062 /** \} */
00063 #endif // GNSS_SDR_GNSS_SYNCHRO_UDP_SINK_H

```

13.689 serdes_gnss_synchro.h File Reference

Serialization / Deserialization of [Gnss_Synchro](#) objects using Protocol Buffers.

```

#include "gnss_synchro.h"
#include "gnss_synchro.pb.h"
#include <array>
#include <string>
#include <utility>
#include <vector>

```

Classes

- class [Serdes_Gnss_Synchro](#)

This class implements serialization and deserialization of [Gnss_Synchro](#) objects using Protocol Buffers.

13.689.1 Detailed Description

Serialization / Deserialization of [Gnss_Synchro](#) objects using Protocol Buffers.

Author

Carles Fernandez-Prades, 2019. cfernandez(at)cttc.es

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 Definition in file [serdes_gnss_synchro.h](#).

13.690 serdes_gnss_synchro.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002   * \file serdes_gnss_synchro.h
00003   * \brief Serialization / Deserialization of Gnss_Synchro objects using
00004   * Protocol Buffers
00005   * \author Carles Fernandez-Prades, 2019. cfernandez(at)cttc.es
00006   *
00007   * -----
00008   *
00009   * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00011   *
00012   * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013   * SPDX-License-Identifier: GPL-3.0-or-later
00014   *
00015   * -----
00016   */
00017
00018 #ifndef GNSS_SDR_SERDES_GNSS_SYNCHRO_H
00019 #define GNSS_SDR_SERDES_GNSS_SYNCHRO_H
00020
00021 #include "gnss_synchro.h"
00022 #include "gnss_synchro.pb.h" // file created by Protocol Buffers at compile time
00023 #include <array>
00024 #include <string>
00025 #include <utility>
00026 #include <vector>
00027
00028 /*!
00029   * \brief This class implements serialization and deserialization of
00030   * Gnss_Synchro objects using Protocol Buffers.
00031   */
00032 class Serdes_Gnss_Synchro
00033 {
00034 public:
00035     Serdes_Gnss_Synchro()
00036     {
00037         // Verify that the version of the library that we linked against is
00038         // compatible with the version of the headers we compiled against.
00039         GOOGLE_PROTOBUF_VERIFY_VERSION;
00040     }
00041
00042     ~Serdes_Gnss_Synchro()
00043     {
00044         google::protobuf::ShutdownProtobufLibrary();
00045     }
00046
00047     inline Serdes_Gnss_Synchro(const Serdes_Gnss_Synchro& other) noexcept //!< Copy constructor
00048     {
00049         this->observables = other.observables;
00050     }
00051
00052     inline Serdes_Gnss_Synchro& operator=(const Serdes_Gnss_Synchro& rhs) noexcept //!< Copy
00053     assignment operator
00054     {
00055         this->observables = rhs.observables;
00056         return *this;
00057     }
00058
00059     inline Serdes_Gnss_Synchro(Serdes_Gnss_Synchro&& other) noexcept //!< Move constructor
00060     {
00061         this->observables = std::move(other.observables);
00062     }

```

```

00063     inline Serdes_Gnss_Synchro& operator=(Serdes_Gnss_Synchro&& other) noexcept //!< Move assignment
operator
00064     {
00065         if (this != &other)
00066         {
00067             this->observables = std::move(other.observables);
00068         }
00069         return *this;
00070     }
00071
00072     inline std::string createProtobuffer(const std::vector<Gnss_Synchro>& vgs) //!< Serialization
into a string
00073     {
00074         observables.Clear();
00075         std::string data;
00076         for (const auto& gs : vgs)
00077         {
00078             gnss_sdr::GnssSynchro* obs = observables.add_observable();
00079             char c = gs.System;
00080             const std::string sys(1, c);
00081
00082             std::array<char, 2> cc;
00083             cc[0] = gs.Signal[0];
00084             cc[1] = gs.Signal[1];
00085             const std::string sig(cc.cbegin(), cc.cend());
00086
00087             obs->set_system(sys);
00088             obs->set_signal(sig);
00089             obs->set_prn(gs.PRN);
00090             obs->set_channel_id(gs.Channel_ID);
00091
00092             obs->set_acq_delay_samples(gs.Acq_delay_samples);
00093             obs->set_acq_doppler_hz(gs.Acq_doppler_hz);
00094             obs->set_acq_samplestamp_samples(gs.Acq_samplestamp_samples);
00095             obs->set_acq_doppler_step(gs.Acq_doppler_step);
00096             obs->set_flag_valid_acquisition(gs.Flag_valid_acquisition);
00097
00098             obs->set_fs(gs.fs);
00099             obs->set_prompt_i(gs.Prompt_I);
00100             obs->set_prompt_q(gs.Prompt_Q);
00101             obs->set_cn0_db_hz(gs.CN0_dB_hz);
00102             obs->set_carrier_doppler_hz(gs.Carrier_Doppler_hz);
00103             obs->set_carrier_phase_rads(gs.Carrier_phase_rads);
00104             obs->set_code_phase_samples(gs.Code_phase_samples);
00105             obs->set_tracking_sample_counter(gs.Tracking_sample_counter);
00106             obs->set_flag_valid_symbol_output(gs.Flag_valid_symbol_output);
00107             obs->set_correlation_length_ms(gs.correlation_length_ms);
00108
00109             obs->set_flag_valid_word(gs.Flag_valid_word);
00110             obs->set_tow_at_current_symbol_ms(gs.TOW_at_current_symbol_ms);
00111
00112             obs->set_pseudorange_m(gs.Pseudorange_m);
00113             obs->set_rx_time(gs.RX_time);
00114             obs->set_flag_valid_pseudorange(gs.Flag_valid_pseudorange);
00115             obs->set_flag_pll_180_deg_phase_locked(gs.Flag_PLL_180_deg_phase_locked);
00116             obs->set_flag_cycle_slip(gs.Flag_cycle_slip);
00117             obs->set_interp_tow_ms(gs.interp_TOW_ms);
00118         }
00119         observables.SerializeToString(&data);
00120         return data;
00121     }
00122
00123     inline std::vector<Gnss_Synchro> readProtobuffer(const gnss_sdr::Observables& obs) const //!<
Deserialization
00124     {
00125         std::vector<Gnss_Synchro> vgs;
00126         vgs.reserve(obs.observable_size());
00127         for (int i = 0; i < obs.observable_size(); ++i)
00128         {
00129             const gnss_sdr::GnssSynchro& gs_read = obs.observable(i);
00130             Gnss_Synchro gs = Gnss_Synchro();
00131             gs.System = gs_read.system()[0];
00132             gs.Signal[0] = gs_read.signal()[0];
00133             gs.Signal[1] = gs_read.signal()[1];
00134             gs.Signal[2] = '\0';
00135             gs.PRN = gs_read.prn();
00136             gs.Channel_ID = gs_read.channel_id();
00137
00138             gs.Acq_delay_samples = gs_read.acq_delay_samples();
00139             gs.Acq_doppler_hz = gs_read.acq_doppler_hz();
00140             gs.Acq_samplestamp_samples = gs_read.acq_samplestamp_samples();
00141             gs.Acq_doppler_step = gs_read.acq_doppler_step();
00142             gs.Flag_valid_acquisition = gs_read.flag_valid_acquisition();
00143
00144             gs.fs = gs_read.fs();
00145             gs.Prompt_I = gs_read.prompt_i();
00146             gs.Prompt_Q = gs_read.prompt_q();

```

```

00147         gs.CN0_db_hz = gs_read.cn0_db_hz();
00148         gs.Carrier_Doppler_hz = gs_read.carrier_doppler_hz();
00149         gs.Carrier_phase_rads = gs_read.carrier_phase_rads();
00150         gs.Code_phase_samples = gs_read.code_phase_samples();
00151         gs.Tracking_sample_counter = gs_read.tracking_sample_counter();
00152         gs.Flag_valid_symbol_output = gs_read.flag_valid_symbol_output();
00153         gs.correlation_length_ms = gs_read.correlation_length_ms();
00154
00155         gs.Flag_valid_word = gs_read.flag_valid_word();
00156         gs.TOW_at_current_symbol_ms = gs_read.tow_at_current_symbol_ms();
00157
00158         gs.Pseudorange_m = gs_read.pseudorange_m();
00159         gs.RX_time = gs_read.rx_time();
00160         gs.Flag_valid_pseudorange = gs_read.flag_valid_pseudorange();
00161         gs.Flag_PLL_180_deg_phase_locked = gs_read.flag_pll_180_deg_phase_locked();
00162         gs.Flag_cycle_slip = gs_read.flag_cycle_slip();
00163         gs.interp_TOW_ms = gs_read.interp_tow_ms();
00164
00165         vgs.push_back(gs);
00166     }
00167     return vgs;
00168 }
00169
00170 private:
00171     gnss_sdr::Observables observables{};
00172 };
00173
00174 #endif // GNSS_SDR_SERDES_GNSS_SYNCRO_H

```

13.691 concurrent_map.h File Reference

Interface of a thread-safe std::map.

```

#include <map>
#include <mutex>
#include <utility>

```

Classes

- class [Concurrent_Map< Data >](#)

This class implements a thread-safe std::map.

13.691.1 Detailed Description

Interface of a thread-safe std::map.

Author

Javier Arribas, 2011. jarribas(at)cttc.es

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Definition in file [concurrent_map.h](#).

13.692 concurrent_map.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file concurrent_map.h
00003  * \brief Interface of a thread-safe std::map
00004  * \author Javier Arribas, 2011. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */

```

```

00016
00017 #ifndef GNSS_SDR_CONCURRENT_MAP_H
00018 #define GNSS_SDR_CONCURRENT_MAP_H
00019
00020 #include <map>
00021 #include <mutex>
00022 #include <utility>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup Core_Receiver core_receiver
00027  * \{ */
00028
00029
00030 template <typename Data>
00031
00032
00033 /*!
00034  * \brief This class implements a thread-safe std::map
00035  *
00036  */
00037 class Concurrent_Map
00038 {
00039 public:
00040     void write(int key, Data const& data)
00041     {
00042         std::lock_guard<std::mutex> lock(the_mutex);
00043         auto data_iter = the_map.find(key);
00044         if (data_iter != the_map.end())
00045         {
00046             data_iter->second = data; // update
00047         }
00048         else
00049         {
00050             the_map.insert(std::pair<int, Data>(key, data)); // insert does not overwrite if the
item already exists in the map!
00051         }
00052     }
00053
00054     std::map<int, Data> get_map_copy() const&
00055     {
00056         std::lock_guard<std::mutex> lock(the_mutex);
00057         return the_map; // This implicitly creates a copy
00058     }
00059
00060     std::map<int, Data> get_map_copy() &&
00061     {
00062         std::lock_guard<std::mutex> lock(the_mutex);
00063         return std::move(the_map);
00064     }
00065
00066     size_t size() const
00067     {
00068         std::lock_guard<std::mutex> lock(the_mutex);
00069         return the_map.size();
00070     }
00071
00072     bool read(int key, Data& p_data) const
00073     {
00074         std::lock_guard<std::mutex> lock(the_mutex);
00075         auto data_iter = the_map.find(key);
00076         if (data_iter != the_map.end())
00077         {
00078             p_data = data_iter->second;
00079             return true;
00080         }
00081         return false;
00082     }
00083
00084 private:
00085     std::map<int, Data> the_map;
00086     mutable std::mutex the_mutex;
00087 };
00088
00089
00090 /** \} */
00091 /** \} */
00092 #endif // GNSS_SDR_CONCURRENT_MAP_H

```

13.693 concurrent_queue.h File Reference

Interface of a thread-safe std::queue.


```
#include <chrono>
#include <condition_variable>
#include <cstdint>
#include <mutex>
#include <queue>
#include <utility>
```

Classes

- class [Concurrent_Queue< Data >](#)

This class implements a thread-safe std::queue.

13.693.1 Detailed Description

Interface of a thread-safe std::queue.

Author

Javier Arribas, 2011. jarribas(at)cttc.es

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 Definition in file [concurrent_queue.h](#).

13.694 concurrent_queue.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file concurrent_queue.h
00003  * \brief Interface of a thread-safe std::queue
00004  * \author Javier Arribas, 2011. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_CONCURRENT_QUEUE_H
00018 #define GNSS_SDR_CONCURRENT_QUEUE_H
00019
00020 #include <chrono>
00021 #include <condition_variable>
00022 #include <cstdint>
00023 #include <mutex>
00024 #include <queue>
00025 #include <utility>
00026
00027 /** \addtogroup Core
00028  * \{ */
00029 /** \addtogroup Core_Receiver
00030  * \{ */
00031
00032
00033 template <typename Data>
00034
00035 /*!
00036  * \brief This class implements a thread-safe std::queue
00037  */
00038 class Concurrent_Queue
00039 {
00040 public:
00041     void push(const Data& data)
00042     {
00043         {
00044             std::lock_guard<std::mutex> lock(the_mutex);
00045             the_queue.push(data);
00046         }
00047     }
00048 }
```

```

00047         the_condition_variable.notify_one();
00048     }
00049
00050     void push(Data&& data)
00051     {
00052     {
00053         std::lock_guard<std::mutex> lock(the_mutex);
00054         the_queue.push(std::move(data));
00055     }
00056     the_condition_variable.notify_one();
00057     }
00058
00059     bool empty() const noexcept
00060     {
00061         return size() == 0;
00062     }
00063
00064     size_t size() const noexcept
00065     {
00066         std::lock_guard<std::mutex> lock(the_mutex);
00067         return the_queue.size();
00068     }
00069
00070     void clear()
00071     {
00072         std::lock_guard<std::mutex> lock(the_mutex);
00073         std::queue<Data>().swap(the_queue);
00074     }
00075
00076     bool try_pop(Data& popped_value)
00077     {
00078         std::lock_guard<std::mutex> lock(the_mutex);
00079         if (the_queue.empty())
00080         {
00081             return false;
00082         }
00083         popped_value = std::move(the_queue.front());
00084         the_queue.pop();
00085         return true;
00086     }
00087
00088     void wait_and_pop(Data& popped_value)
00089     {
00090         std::unique_lock<std::mutex> lock(the_mutex);
00091         the_condition_variable.wait(lock, [this] { return !the_queue.empty(); });
00092         popped_value = std::move(the_queue.front());
00093         the_queue.pop();
00094     }
00095
00096     bool timed_wait_and_pop(Data& popped_value, int wait_ms)
00097     {
00098         std::unique_lock<std::mutex> lock(the_mutex);
00099         if (!the_condition_variable.wait_for(lock,
00100             std::chrono::milliseconds(wait_ms),
00101             [this] { return !the_queue.empty(); }))
00102         {
00103             return false;
00104         }
00105         popped_value = std::move(the_queue.front());
00106         the_queue.pop();
00107         return true;
00108     }
00109
00110 private:
00111     std::queue<Data> the_queue;
00112     mutable std::mutex the_mutex;
00113     std::condition_variable the_condition_variable;
00114 };
00115
00116
00117 /** \} */
00118 /** \} */
00119 #endif // GNSS_SDR_CONCURRENT_QUEUE_H

```

13.695 control_thread.h File Reference

Interface of the receiver control plane.

```

#include "agnss_ref_location.h"
#include "agnss_ref_time.h"
#include "channel_event.h"
#include "command_event.h"
#include "concurrent_queue.h"

```

```
#include "gnss_sdr_supl_client.h"
#include "tcp_cmd_interface.h"
#include <pmt/pmt.h>
#include <array>
#include <cstdint>
#include <memory>
#include <string>
#include <thread>
#include <typeinfo>
#include <utility>
#include <vector>
```

Classes

- class [ControlThread](#)

This class represents the main thread of the application, so the name is [ControlThread](#). This is the GNSS Receiver Control Plane: it connects the flowgraph, starts running it, and while it does not stop, reads the control messages generated by the blocks, processes them, and applies the corresponding actions.

13.695.1 Detailed Description

Interface of the receiver control plane.

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com

GNSS Receiver Control Plane: connects the flowgraph, starts running it, and while it does not stop, reads the control messages generated by the blocks, processes them, and applies the corresponding actions.

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Definition in file [control_thread.h](#).

13.696 control_thread.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file control_thread.h
00003  * \brief Interface of the receiver control plane
00004  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00005  *
00006  * GNSS Receiver Control Plane: connects the flowgraph, starts running it,
00007  * and while it does not stop, reads the control messages generated by the blocks,
00008  * processes them, and applies the corresponding actions.
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021 #ifndef GNSS_SDR_CONTROL_THREAD_H
00022 #define GNSS_SDR_CONTROL_THREAD_H
00023
00024 #include "agnss_ref_location.h" // for Agnss_Ref_Location
00025 #include "agnss_ref_time.h" // for Agnss_Ref_Time
00026 #include "channel_event.h" // for channel_event_sptr
00027 #include "command_event.h" // for command_event_sptr
00028 #include "concurrent_queue.h" // for Concurrent_Queue
00029 #include "gnss_sdr_supl_client.h" // for Gnss_Sdr_Supl_Client
00030 #include "tcp_cmd_interface.h" // for TcpCmdInterface
00031 #include <pmt/pmt.h>
00032 #include <array> // for array
00033 #include <cstdint> // for size_t
```

```

00034 #include <memory>      // for shared_ptr
00035 #include <string>        // for string
00036 #include <thread>        // for std::thread
00037 #include <typeinfo>      // for std::type_info, typeid
00038 #include <utility>        // for pair
00039 #include <vector>         // for vector
00040
00041 #ifndef ENABLE_FPGA
00042 #include <boost/thread.hpp> // for boost::thread
00043 #endif
00044
00045 /** \addtogroup Core Core GNSS Receiver
00046  * Core GNSS Receiver.
00047  * \{ */
00048 /** \addtogroup Core_Receiver
00049  * Classes for the core GNSS receiver.
00050  * \{ */
00051
00052
00053 class ConfigurationInterface;
00054 class GNSSFlowgraph;
00055 class Gnss_Satellite;
00056
00057
00058 /*!
00059  * \brief This class represents the main thread of the application, so the name is ControlThread.
00060  * This is the GNSS Receiver Control Plane: it connects the flowgraph, starts running it,
00061  * and while it does not stop, reads the control messages generated by the blocks,
00062  * processes them, and applies the corresponding actions.
00063  */
00064 class ControlThread
00065 {
00066 public:
00067     static ControlThread *me;
00068     /*!
00069      * \brief Default constructor
00070      */
00071     ControlThread();
00072
00073     /*!
00074      * \brief Constructor that initializes the class with parameters
00075      *
00076      * \param[in] configuration Pointer to a ConfigurationInterface
00077      */
00078     explicit ControlThread(std::shared_ptr<ConfigurationInterface> configuration);
00079
00080     /*!
00081      * \brief Destructor
00082      */
00083     ~ControlThread();
00084
00085     /*! \brief Runs the control thread
00086      *
00087      * This is the main loop that reads and process the control messages:
00088      *
00089      * - Connect the GNSS receiver flowgraph;
00090      *
00091      * - Start the GNSS receiver flowgraph;
00092      *
00093      * while (flowgraph_>running() && !stop_){
00094      *
00095      * - Read control messages and process them; }
00096      */
00097     int run();
00098
00099     /*!
00100      * \brief Sets the control_queue
00101      *
00102      * \param[in] std::shared_ptr<Concurrent_Queue<pmt::pmt_t> control_queue
00103      */
00104     void set_control_queue(std::shared_ptr<Concurrent_Queue<pmt::pmt_t> control_queue);
00105
00106     unsigned int processed_control_messages() const
00107     {
00108         return processed_control_messages_;
00109     }
00110
00111     unsigned int applied_actions() const
00112     {
00113         return applied_actions_;
00114     }
00115
00116     /*!
00117      * \brief Instantiates a flowgraph
00118      *
00119      * \return Returns a smart pointer to a flowgraph object
00120      */

```

```

00121     std::shared_ptr<GNSSFlowgraph> flowgraph()
00122     {
00123         return flowgraph_;
00124     }
00125
00126 private:
00127     /*
00128      * Callback function for handling signals.
00129      * sig identifier of signal
00130      */
00131     static void handle_signal(int sig);
00132
00133     void init();
00134
00135     void apply_action(unsigned int what);
00136
00137     /*
00138      * New receiver event dispatcher
00139      */
00140     void event_dispatcher(bool &valid_event, pmt::pmt_t &msg);
00141
00142     // Read {ephemeris, iono, utc, ref loc, ref time} assistance from a local XML file previously
00143     // recorded
00144     bool read_assistance_from_XML();
00145
00146     /*
00147      * Blocking function that reads the GPS assistance queue
00148      */
00149     void gps_acq_assist_data_collector() const;
00150
00151     /*
00152      * Compute elevations for the specified time and position for all the available satellites in
00153      * ephemeris and almanac queues
00154      * returns a vector filled with the available satellites ordered from high elevation to low
00155      * elevation angle.
00156      */
00157     std::vector<std::pair<int, Gnss_Satellite>> get_visible_sats(time_t rx_utc_time, const
00158     std::array<float, 3> &LLH);
00159
00160     /*
00161      * Read initial GNSS assistance from SUPL server or local XML files
00162      */
00163     void assist_GNSS();
00164
00165     void telecommand_listener();
00166     void keyboard_listener();
00167     void message_queue_listener();
00168     void print_help_at_exit() const;
00169
00170     // default filename for assistance data
00171     const std::string eph_default_xml_filename_ = "./gps_ephemeris.xml";
00172     const std::string utc_default_xml_filename_ = "./gps_utc_model.xml";
00173     const std::string iono_default_xml_filename_ = "./gps_iono.xml";
00174     const std::string ref_time_default_xml_filename_ = "./gps_ref_time.xml";
00175     const std::string ref_location_default_xml_filename_ = "./gps_ref_location.xml";
00176     const std::string eph_gal_default_xml_filename_ = "./gal_ephemeris.xml";
00177     const std::string eph_cnav_default_xml_filename_ = "./gps_cnav_ephemeris.xml";
00178     const std::string gal_iono_default_xml_filename_ = "./gal_iono.xml";
00179     const std::string gal_utc_default_xml_filename_ = "./gal_utc_model.xml";
00180     const std::string cnav_utc_default_xml_filename_ = "./gps_cnav_utc_model.xml";
00181     const std::string eph_glo_gnav_default_xml_filename_ = "./glo_gnav_ephemeris.xml";
00182     const std::string glo_utc_default_xml_filename_ = "./glo_utc_model.xml";
00183     const std::string gal_almanac_default_xml_filename_ = "./gal_almanac.xml";
00184     const std::string gps_almanac_default_xml_filename_ = "./gps_almanac.xml";
00185
00186     const std::string control_message_queue_name_ = "receiver_control_queue";
00187
00188     const size_t channel_event_type_hash_code_ = typeid(channel_event_sptr).hash_code();
00189     const size_t command_event_type_hash_code_ = typeid(command_event_sptr).hash_code();
00190
00191     std::shared_ptr<ConfigurationInterface> configuration_;
00192     std::shared_ptr<Concurrent_Queue<pmt::pmt_t>> control_queue_;
00193     std::shared_ptr<GNSSFlowgraph> flowgraph_;
00194
00195     std::thread cmd_interface_thread_;
00196     std::thread keyboard_thread_;
00197     std::thread message_queue_thread_;
00198     std::thread gps_acq_assist_data_collector_thread_;
00199
00200 #ifdef ENABLE_FPGA
00201     boost::thread fpga_helper_thread_;
00202 #endif
00203
00204     TcpCmdInterface cmd_interface_;
00205
00206     // SUPL assistance classes
00207     Gnss_Sdr_Supl_Client supl_client_acquisition_;

```

```

00204     Gnss_Sdr_Supl_Client supl_client_ephemeris_;
00205     int supl_mcc_; // Current network MCC (Mobile country code), 3 digits.
00206     int supl_mns_; // Current network MNC (Mobile Network code), 2 or 3 digits.
00207     int supl_lac_; // Current network LAC (Location area code), 16 bits, 1-65520 are valid values.
00208     int supl_ci_; // Cell Identity (16 bits, 0-65535 are valid values).
00209
00210     Agnss_Ref_Location agnss_ref_location_;
00211     Agnss_Ref_Time agnss_ref_time_;
00212
00213     unsigned int processed_control_messages_;
00214     unsigned int applied_actions_;
00215
00216     bool well_formatted_configuration_;
00217     bool conf_file_has_section_;
00218     bool conf_file_has_mandatory_globals_;
00219     bool conf_has_signal_sources_;
00220     bool conf_has_observables_;
00221     bool conf_has_pvt_;
00222     bool receiver_on_standby_;
00223     bool stop_;
00224     bool restart_;
00225     bool telecommand_enabled_;
00226     bool pre_2009_file_; // to override the system time to postprocess old gnss records and avoid
                          // wrong week rollover
00227 };
00228
00229
00230 /** \} */
00231 /** \} */
00232 #endif // GNSS_SDR_CONTROL_THREAD_H

```

13.697 file_configuration.h File Reference

A [ConfigurationInterface](#) that reads the configuration from a file.

```

#include "INIReader.h"
#include "configuration_interface.h"
#include "in_memory_configuration.h"
#include "string_converter.h"
#include <stdint>
#include <memory>
#include <string>

```

Classes

- class [FileConfiguration](#)

This class is an implementation of the interface [ConfigurationInterface](#).

13.697.1 Detailed Description

A [ConfigurationInterface](#) that reads the configuration from a file.

Author

Carlos Aviles, 2010. carlos.avilesr(at)googlemail.com

This implementation has a text file as the source for the values of the parameters. The file is in the INI format, containing sections and pairs of names and values. For more information about the INI format, see https://en.wikipedia.org/wiki/INI_file

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 Definition in file [file_configuration.h](#).

13.698 file_configuration.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file file_configuration.h
00003  * \brief A ConfigurationInterface that reads the configuration from a file.

```

```

00004  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00005  *
00006  * This implementation has a text file as the source for the values of the parameters.
00007  * The file is in the INI format, containing sections and pairs of names and values.
00008  * For more information about the INI format, see https://en.wikipedia.org/wiki/INI\_file
00009  *
00010  * -----
00011  *
00012  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00013  * This file is part of GNSS-SDR.
00014  *
00015  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00016  * SPDX-License-Identifier: GPL-3.0-or-later
00017  *
00018  * -----
00019  */
00020
00021
00022 #ifndef GNSS_SDR_FILE_CONFIGURATION_H
00023 #define GNSS_SDR_FILE_CONFIGURATION_H
00024
00025 #include "INIReader.h"
00026 #include "configuration_interface.h"
00027 #include "in_memory_configuration.h"
00028 #include "string_converter.h"
00029 #include <stdint>
00030 #include <memory>
00031 #include <string>
00032
00033 /** \addtogroup Core
00034  * \{ */
00035 /** \addtogroup Core_Receiver
00036  * \{ */
00037
00038
00039 /**
00040  * \brief This class is an implementation of the interface ConfigurationInterface
00041  *
00042  * Derived from ConfigurationInterface, this class implements an interface
00043  * to a configuration file. This implementation has a text file as the source
00044  * for the values of the parameters.
00045  * The file is in the INI format, containing sections and pairs of names and values.
00046  * For more information about the INI format, see https://en.wikipedia.org/wiki/INI\_file
00047  */
00048 class FileConfiguration : public ConfigurationInterface
00049 {
00050 public:
00051     explicit FileConfiguration(std::string filename);
00052     FileConfiguration();
00053     ~FileConfiguration() = default;
00054     std::string property(std::string property_name, std::string default_value) const override;
00055     bool property(std::string property_name, bool default_value) const override;
00056     int64_t property(std::string property_name, int64_t default_value) const override;
00057     uint64_t property(std::string property_name, uint64_t default_value) const override;
00058     int32_t property(std::string property_name, int32_t default_value) const override;
00059     uint32_t property(std::string property_name, uint32_t default_value) const override;
00060     int16_t property(std::string property_name, int16_t default_value) const override;
00061     uint16_t property(std::string property_name, uint16_t default_value) const override;
00062     float property(std::string property_name, float default_value) const override;
00063     double property(std::string property_name, double default_value) const override;
00064     void set_property(std::string property_name, std::string value) override;
00065     bool is_present(const std::string& property_name) const override;
00066     bool has_section() const;
00067
00068 private:
00069     void init();
00070     std::string filename_;
00071     std::unique_ptr<INIReader> ini_reader_;
00072     std::unique_ptr<InMemoryConfiguration> overrided_;
00073     std::unique_ptr<StringConverter> converter_;
00074     int error_{};
00075 };
00076
00077
00078 /** \} */
00079 /** \} */
00080 #endif // GNSS_SDR_FILE_CONFIGURATION_H

```

13.699 gnss_block_factory.h File Reference

Interface of a factory that returns smart pointers to GNSS blocks.

```

#include "concurrent_queue.h"
#include <pmt/pmt.h>

```

```
#include <memory>
#include <string>
#include <vector>
```

Classes

- class [GNSSBlockFactory](#)

Class that produces all kinds of GNSS blocks.

13.699.1 Detailed Description

Interface of a factory that returns smart pointers to GNSS blocks.

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com Luis Esteve, 2011. luis(at)epsilon-formacion.com Javier Arribas, 2011. jarribas(at)cttc.es Carles Fernandez-Prades, 2014-2020. cfernandez(at)cttc.es

This class encapsulates the complexity behind the instantiation of GNSS blocks.

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [gnss_block_factory.h](#).

13.700 gnss_block_factory.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gnss_block_factory.h
00003  * \brief Interface of a factory that returns smart pointers to GNSS blocks.
00004  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00005  *         Luis Esteve, 2011. luis(at)epsilon-formacion.com
00006  *         Javier Arribas, 2011. jarribas(at)cttc.es
00007  *         Carles Fernandez-Prades, 2014-2020. cfernandez(at)cttc.es
00008  *
00009  * This class encapsulates the complexity behind the instantiation
00010  * of GNSS blocks.
00011  *
00012  *
00013  * -----
00014  *
00015  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00016  * This file is part of GNSS-SDR.
00017  *
00018  * Copyright (C) 2010-2026 (see AUTHORS file for a list of contributors)
00019  * SPDX-License-Identifier: GPL-3.0-or-later
00020  *
00021  * -----
00022  */
00023
00024 #ifndef GNSS_SDR_BLOCK_FACTORY_H
00025 #define GNSS_SDR_BLOCK_FACTORY_H
00026
00027 #include "concurrent_queue.h"
00028 #include <pmt/pmt.h>
00029 #include <memory> // for unique_ptr
00030 #include <string> // for string
00031 #include <vector> // for vector
00032
00033 /** \addtogroup Core
00034  * \{ */
00035 /** \addtogroup Core_Receiver
00036  * \{ */
00037
00038
00039 class ConfigurationInterface;
00040 class GNSSBlockInterface;
00041 class SignalSourceInterface;
00042 class AcquisitionInterface;
00043 class TrackingInterface;
00044 class TelemetryDecoderInterface;
00045
00046 /*!
00047  * \brief Class that produces all kinds of GNSS blocks
00048  */
```



```

00049 class GNSSBlockFactory
00050 {
00051 public:
00052     GNSSBlockFactory() = default;
00053     ~GNSSBlockFactory() = default;
00054
00055     std::unique_ptr<SignalSourceInterface> GetSignalSource(const ConfigurationInterface*
configuration,
00056         Concurrent_Queue<pmt::pmt_t>* queue, int ID = -1) const;
00057
00058     std::unique_ptr<GNSSBlockInterface> GetSignalConditioner(const ConfigurationInterface*
configuration, int ID = -1) const;
00059
00060     std::vector<std::unique_ptr<GNSSBlockInterface>> GetChannels(const ConfigurationInterface*
configuration,
00061         Concurrent_Queue<pmt::pmt_t>* queue) const;
00062
00063     std::unique_ptr<GNSSBlockInterface> GetObservables(const ConfigurationInterface* configuration)
const;
00064
00065     std::unique_ptr<GNSSBlockInterface> GetPVT(const ConfigurationInterface* configuration) const;
00066
00067     /*
00068     * \brief Returns the block with the required role implementation and its configuration parameters
00069     */
00070     std::unique_ptr<GNSSBlockInterface> GetBlock(const ConfigurationInterface* configuration,
00071         const std::string& role,
00072         unsigned int in_streams,
00073         unsigned int out_streams,
00074         Concurrent_Queue<pmt::pmt_t>* queue = nullptr) const;
00075
00076 private:
00077     std::unique_ptr<GNSSBlockInterface> GetChannel(
00078         const ConfigurationInterface* configuration,
00079         const std::string& signal,
00080         int channel,
00081         Concurrent_Queue<pmt::pmt_t>* queue) const;
00082
00083     std::unique_ptr<AcquisitionInterface> GetAcqBlock(
00084         const ConfigurationInterface* configuration,
00085         const std::string& role,
00086         unsigned int in_streams,
00087         unsigned int out_streams) const;
00088
00089     std::unique_ptr<TrackingInterface> GetTrkBlock(
00090         const ConfigurationInterface* configuration,
00091         const std::string& role,
00092         unsigned int in_streams,
00093         unsigned int out_streams) const;
00094
00095     std::unique_ptr<TelemetryDecoderInterface> GetTlmBlock(
00096         const ConfigurationInterface* configuration,
00097         const std::string& role,
00098         unsigned int in_streams,
00099         unsigned int out_streams) const;
00100 };
00101
00102 /** \} */
00103 /** \} */
00104 /** \} */
00105 #endif // GNSS_SDR_BLOCK_FACTORY_H

```

13.701 gnss_flowgraph.h File Reference

Interface of a GNSS receiver flow graph.

```

#include "channel_status_msg_receiver.h"
#include "concurrent_queue.h"
#include "galileo_e6_has_msg_receiver.h"
#include "galileo_tow_map.h"
#include "gnss_sdr_sample_counter.h"
#include "gnss_signal.h"
#include "osnma_msg_receiver.h"
#include "pvt_interface.h"
#include <gnuradio/blocks/null_sink.h>
#include <gnuradio/runtime_types.h>
#include <pmt/pmt.h>
#include <list>
#include <map>

```

```
#include <memory>
#include <mutex>
#include <string>
#include <unordered_map>
#include <utility>
#include <vector>
```

Classes

- class [GNSSFlowgraph](#)

This class represents a GNSS flow graph.

13.701.1 Detailed Description

Interface of a GNSS receiver flow graph.

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com Luis Esteve, 2011. luis(at)epsilon-formacion.com Carles Fernandez-Prades, 2014-2020. cfernandez(at)cttc.es Álvaro Cebrián Juan, 2018. acebrianjuan(at)gmail.com

It contains a signal source, a signal conditioner, a set of channels, an observables block and a pvt.
GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [gnss_flowgraph.h](#).

13.702 gnss_flowgraph.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gnss_flowgraph.h
00003  * \brief Interface of a GNSS receiver flow graph.
00004  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00005  *         Luis Esteve, 2011. luis(at)epsilon-formacion.com
00006  *         Carles Fernandez-Prades, 2014-2020. cfernandez(at)cttc.es
00007  *         Álvaro Cebrián Juan, 2018. acebrianjuan(at)gmail.com
00008  *
00009  * It contains a signal source,
00010  * a signal conditioner, a set of channels, an observables block and a pvt.
00011  *
00012  *
00013  * -----
00014  *
00015  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00016  * This file is part of GNSS-SDR.
00017  *
00018  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00019  * SPDX-License-Identifier: GPL-3.0-or-later
00020  *
00021  * -----
00022  */
00023
00024 #ifndef GNSS_SDR_GNSS_FLOWGRAPH_H
00025 #define GNSS_SDR_GNSS_FLOWGRAPH_H
00026
00027 #include "channel_status_msg_receiver.h"
00028 #include "concurrent_queue.h"
00029 #include "galileo_e6_has_msg_receiver.h"
00030 #include "galileo_tow_map.h"
00031 #include "gnss_sdr_sample_counter.h"
00032 #include "gnss_signal.h"
00033 #include "osnma_msg_receiver.h"
00034 #include "pvt_interface.h"
00035 #include <gnuradio/blocks/null_sink.h> // for null_sink
00036 #include <gnuradio/runtime_types.h> // for basic_block_sptr, top_block_sptr
00037 #include <pmt/pmt.h> // for pmt_t
00038 #include <list> // for list
00039 #include <map> // for map
00040 #include <memory> // for for shared_ptr, dynamic_pointer_cast
00041 #include <mutex> // for mutex
00042 #include <string> // for string
```

```

00043 #include <unordered_map>                // for unordered_map
00044 #include <utility>                        // for pair
00045 #include <vector>                        // for vector
00046 #if ENABLE_FPGA
00047 #include "gnss_sdr_fpga_sample_counter.h"
00048 #endif
00049
00050 /** \addtogroup Core
00051 * \{ */
00052 /** \addtogroup Core_Receiver
00053 * \{ */
00054
00055
00056 class ChannelInterface;
00057 class ConfigurationInterface;
00058 class GNSSBlockInterface;
00059 class Gnss_Satellite;
00060 class SignalSourceInterface;
00061
00062 /*! \brief This class represents a GNSS flow graph.
00063 *
00064 * It contains a signal source,
00065 * a signal conditioner, a set of channels, a PVT and an output filter.
00066 */
00067 class GNSSFlowgraph
00068 {
00069 public:
00070     /*!
00071      * \brief Constructor that initializes the receiver flow graph
00072      */
00073     GNSSFlowgraph(std::shared_ptr<ConfigurationInterface> configuration,
00074                   std::shared_ptr<Concurrent_Queue<pmt::pmt_t>> queue);
00075
00076     /*!
00077      * \brief Destructor
00078      */
00079     ~GNSSFlowgraph();
00080
00081     /*!
00082      * \brief Start the flow graph
00083      */
00084     void start();
00085
00086     /*!
00087      * \brief Stop the flow graph
00088      */
00089     void stop();
00090
00091     /*!
00092      * \brief Connects the defined blocks in the flow graph
00093      *
00094      * Signal Source > Signal conditioner > Channels » Observables » PVT > Output filter
00095      */
00096     void connect();
00097
00098     /*!
00099      * \brief Disconnect the blocks in the flow graph
00100      */
00101     void disconnect();
00102
00103     /*!
00104      * \brief Wait for a flowgraph to complete.
00105      *
00106      * Flowgraphs complete when either
00107      * (1) all blocks indicate that they are done, or
00108      * (2) after stop() has been called to request shutdown.
00109      */
00110     void wait();
00111
00112     /*!
00113      * \brief Manage satellite acquisition
00114      *
00115      * \param[in] who Channel ID
00116      */
00117     void acquisition_manager(unsigned int who);
00118
00119     /*!
00120      * \brief Applies an action to the flow graph
00121      *
00122      * \param[in] who Who generated the action
00123      * \param[in] what What is the action. 0: acquisition failed; 1: acquisition success; 2: tracking
00124      * lost
00125      */
00126     void apply_action(unsigned int who, unsigned int what);
00127
00128     /*!
00129      * \brief Set flow graph configuratiob

```

```

00128     */
00129 void set_configuration(const std::shared_ptr<ConfigurationInterface>& configuration);
00130
00131 bool connected() const
00132 {
00133     return connected_;
00134 }
00135
00136 bool running() const
00137 {
00138     return running_;
00139 }
00140
00141 /*!
00142  * \brief Sends a GNU Radio asynchronous message from telemetry to PVT
00143  *
00144  * It is used to assist the receiver with external ephemeris data
00145  */
00146 bool send_telemetry_msg(const pmt::pmt_t& msg);
00147
00148 /*!
00149  * \brief Returns a smart pointer to the PVT object
00150  */
00151 std::shared_ptr<PvtInterface> get_pvt()
00152 {
00153     return std::dynamic_pointer_cast<PvtInterface>(pvt_);
00154 }
00155
00156 /*!
00157  * \brief Prioritize visible satellites in the specified vector
00158  */
00159 void prioritize_satellites(const std::vector<std::pair<int, Gnss_Satellite>& visible_satellites);
00160
00161 #if ENABLE_FPGA
00162 void start_acquisition_helper();
00163
00164 void perform_hw_reset();
00165 #endif
00166
00167 private:
00168 void init(); // Populates the SV PRN list available for acquisition and tracking
00169 int connect_desktop_flowgraph();
00170
00171 int connect_signal_sources();
00172 int connect_signal_conditioners();
00173 int connect_channels();
00174 int connect_observables();
00175 int connect_pvt();
00176 int connect_sample_counter();
00177 int connect_galileo_tow_map();
00178
00179 int connect_signal_sources_to_signal_conditioners();
00180 int connect_signal_conditioners_to_channels();
00181 int connect_channels_to_observables();
00182 int connect_observables_to_pvt();
00183 int connect_monitors();
00184 int connect_osnma();
00185 int connect_gal_e6_has();
00186 int connect_gnss_synchro_monitor();
00187 int connect_acquisition_monitor();
00188 int connect_tracking_monitor();
00189 int connect_navdata_monitor();
00190
00191 #if ENABLE_FPGA
00192 int connect_fpga_flowgraph();
00193 int connect_fpga_sample_counter();
00194 #endif
00195
00196 int assign_channels();
00197 void check_signal_conditioners();
00198
00199 void set_signals_list();
00200 void set_channels_state(); // Initializes the channels state (start acquisition or keep standby)
00201 // using the configuration parameters (number of channels and max
channels in acquisition)
00202 Gnss_Signal search_next_signal(const std::string& searched_signal,
00203 bool& is_primary_frequency,
00204 bool& assistance_available,
00205 float& estimated_doppler,
00206 double& RX_time);
00207
00208 void push_back_signal(const Gnss_Signal& gs);
00209 void remove_signal(const Gnss_Signal& gs);
00210 void print_help();
00211 void check_desktop_conf_in_fpga_env();
00212
00213 double project_doppler(const std::string& searched_signal, double primary_freq_doppler_hz);

```

```

00214     bool is_multiband() const;
00215
00216     std::vector<std::string> split_string(const std::string& s, char delim);
00217     std::vector<bool> signal_conditioner_connected_;
00218
00219     gr::top_block_sptr top_block_;
00220
00221     std::shared_ptr<ConfigurationInterface> configuration_;
00222     std::shared_ptr<Concurrent_Queue<pmt::pmt_t>> queue_;
00223
00224     std::vector<std::shared_ptr<SignalSourceInterface>> sig_source_;
00225     std::vector<std::shared_ptr<GNSSBlockInterface>> sig_conditioner_;
00226     std::vector<std::shared_ptr<ChannelInterface>> channels_;
00227     std::shared_ptr<GNSSBlockInterface> observables_;
00228     std::shared_ptr<GNSSBlockInterface> pvt_;
00229
00230     std::map<std::string, gr::basic_block_sptr> acq_resamplers_;
00231     std::vector<gr::blocks::null_sink::sptr> null_sinks_;
00232
00233     gr::basic_block_sptr GnssSynchroMonitor_;
00234     gr::basic_block_sptr GnssSynchroAcquisitionMonitor_;
00235     gr::basic_block_sptr GnssSynchroTrackingMonitor_;
00236     gr::basic_block_sptr NavDataMonitor_;
00237     channel_status_msg_receiver_sptr channels_status_; // class that receives and stores the current
status of the receiver channels
00238     galileo_e6_has_msg_receiver_sptr gal_e6_has_rx_;
00239     galileo_tow_map_sptr galileo_tow_map_;
00240     osnma_msg_receiver_sptr osnma_rx_;
00241
00242     gnss_sdr_sample_counter_sptr ch_out_sample_counter_;
00243 #if ENABLE_FPGA
00244     gnss_sdr_fpga_sample_counter_sptr ch_out_fpga_sample_counter_;
00245 #endif
00246
00247     std::vector<unsigned int> channels_state_; // 0 - Idle, 1 - Assigned, 2 - Acquisition, 3 -
Tracking
00248
00249     std::unordered_map<std::string, std::list<Gnss_Signal>> available_signals_map_;
00250
00251     enum StringValue
00252     {
00253         evGPS_1C,
00254         evGPS_2S,
00255         evGPS_L5,
00256         evSBAS_1C,
00257         evGAL_1B,
00258         evGAL_5X,
00259         evGAL_7X,
00260         evGAL_E6,
00261         evGLO_1G,
00262         evGLO_2G,
00263         evBDS_B1,
00264         evBDS_B3,
00265         evQZS_J1,
00266         evQZS_J5
00267     };
00268     std::map<std::string, StringValue> mapStringValue_;
00269
00270     std::string config_file_;
00271     std::string help_hint_;
00272
00273     std::mutex signal_list_mutex_;
00274
00275     int sources_count_;
00276     int channels_count_;
00277     int acq_channels_count_;
00278     int max_acq_channels_;
00279
00280     bool connected_;
00281     bool running_;
00282     bool multiband_;
00283     bool enable_monitor_;
00284     bool enable_acquisition_monitor_;
00285     bool enable_tracking_monitor_;
00286     bool enable_navdata_monitor_;
00287     bool enable_fpga_offloading_;
00288     bool enable_osnma_rx_;
00289     bool enable_e6_has_rx_;
00290 };
00291
00292
00293 /** \} */
00294 /** \} */
00295 #endif // GNSS_SDR_GNSS_FLOWGRAPH_H

```

13.703 in_memory_configuration.h File Reference

A [ConfigurationInterface](#) for testing purposes.

```
#include "configuration_interface.h"
#include "string_converter.h"
#include <stdint>
#include <map>
#include <memory>
#include <string>
```

Classes

- class [InMemoryConfiguration](#)

This class is an implementation of the interface [ConfigurationInterface](#).

13.703.1 Detailed Description

A [ConfigurationInterface](#) for testing purposes.

Author

Carlos Aviles, 2010. carlos.avilesr(at)gmail.com

This implementation accepts configuration parameters upon instantiation and it is intended to be used in unit testing. GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [in_memory_configuration.h](#).

13.704 in_memory_configuration.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file in_memory_configuration.h
00003  * \brief A ConfigurationInterface for testing purposes.
00004  * \author Carlos Aviles, 2010. carlos.avilesr(at)gmail.com
00005  *
00006  * This implementation accepts configuration parameters upon instantiation and
00007  * it is intended to be used in unit testing.
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020
00021 #ifndef GNSS_SDR_IN_MEMORY_CONFIGURATION_H
00022 #define GNSS_SDR_IN_MEMORY_CONFIGURATION_H
00023
00024 #include "configuration_interface.h"
00025 #include "string_converter.h"
00026 #include <stdint>
00027 #include <map>
00028 #include <memory>
00029 #include <string>
00030
00031 /** \addtogroup Core
00032  * \{ */
00033 /** \addtogroup Core_Receiver
00034  * \{ */
00035
00036
00037 /*!
00038  * \brief This class is an implementation of the interface ConfigurationInterface.
00039  *
00040  * This implementation accepts configuration parameters upon instantiation and
00041  * it is intended to be used in unit testing.
```

```

00042  */
00043  class InMemoryConfiguration : public ConfigurationInterface
00044  {
00045  public:
00046      InMemoryConfiguration();
00047      ~InMemoryConfiguration();
00048      std::string property(std::string property_name, std::string default_value) const override;
00049      bool property(std::string property_name, bool default_value) const override;
00050      int64_t property(std::string property_name, int64_t default_value) const override;
00051      uint64_t property(std::string property_name, uint64_t default_value) const override;
00052      int32_t property(std::string property_name, int32_t default_value) const override;
00053      uint32_t property(std::string property_name, uint32_t default_value) const override;
00054      int16_t property(std::string property_name, int16_t default_value) const override;
00055      uint16_t property(std::string property_name, uint16_t default_value) const override;
00056      float property(std::string property_name, float default_value) const override;
00057      double property(std::string property_name, double default_value) const override;
00058      void set_property(std::string property_name, std::string value) override;
00059      void supersede_property(const std::string& property_name, const std::string& value);
00060      bool is_present(const std::string& property_name) const override;
00061
00062  private:
00063      std::map<std::string, std::string> properties_;
00064      std::unique_ptr<StringConverter> converter_;
00065  };
00066
00067
00068  /** \} */
00069  /** \} */
00070  #endif // GNSS_SDR_IN_MEMORY_CONFIGURATION_H

```

13.705 tcp_cmd_interface.h File Reference

Class that implements a TCP/IP telecommand command line interface for GNSS-SDR.

```

#include "concurrent_queue.h"
#include <pmt/pmt.h>
#include <array>
#include <cstdlib>
#include <ctime>
#include <functional>
#include <memory>
#include <string>
#include <unordered_map>
#include <vector>

```

Classes

- class [TcpCmdInterface](#)

13.705.1 Detailed Description

Class that implements a TCP/IP telecommand command line interface for GNSS-SDR.

Author

Javier Arribas jarribas (at) cttc.es

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 Definition in file [tcp_cmd_interface.h](#).

13.706 tcp_cmd_interface.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file tcp_cmd_interface.h
00003  *
00004  * \brief Class that implements a TCP/IP telecommand command line interface
00005  * for GNSS-SDR
00006  * \author Javier Arribas jarribas (at) cttc.es

```

```

00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018 #ifndef GNSS_SDR_TCP_CMD_INTERFACE_H
00019 #define GNSS_SDR_TCP_CMD_INTERFACE_H
00020
00021
00022 #include "concurrent_queue.h"
00023 #include <pmt/pmt.h>
00024 #include <array>
00025 #include <cstdint>
00026 #include <ctime>
00027 #include <functional>
00028 #include <memory>
00029 #include <string>
00030 #include <unordered_map>
00031 #include <vector>
00032
00033 /** \addtogroup Core
00034  * \{ */
00035 /** \addtogroup Core_Receiver
00036  * \{ */
00037
00038
00039 class PvtInterface;
00040
00041 class TcpCmdInterface
00042 {
00043 public:
00044     TcpCmdInterface();
00045     ~TcpCmdInterface() = default;
00046     void run_cmd_server(int tcp_port);
00047     void set_msg_queue(std::shared_ptr<Concurrent_Queue<pmt::pmt_t>> control_queue);
00048
00049     /*!
00050      * \brief gets the UTC time parsed from the last TC command issued
00051      */
00052     time_t get_utc_time() const;
00053
00054     /*!
00055      * \brief gets the Latitude, Longitude and Altitude vector from the last TC command issued
00056      */
00057     std::array<float, 3> get_LLH() const;
00058
00059     void set_pvt(std::shared_ptr<PvtInterface> PVT_sptr);
00060
00061 private:
00062     std::unordered_map<std::string, std::function<std::string(const std::vector<std::string> &)>>
00063         functions_;
00064     std::string status(const std::vector<std::string> &commandLine);
00065     std::string reset(const std::vector<std::string> &commandLine);
00066     std::string standby(const std::vector<std::string> &commandLine);
00067     std::string hotstart(const std::vector<std::string> &commandLine);
00068     std::string warmstart(const std::vector<std::string> &commandLine);
00069     std::string coldstart(const std::vector<std::string> &commandLine);
00070     std::string set_ch_satellite(const std::vector<std::string> &commandLine);
00071
00072     void register_functions();
00073
00074     std::shared_ptr<Concurrent_Queue<pmt::pmt_t>> control_queue_;
00075     std::shared_ptr<PvtInterface> PVT_sptr_;
00076
00077     float rx_latitude_;
00078     float rx_longitude_;
00079     float rx_altitude_;
00080
00081     time_t receiver_utc_time_;
00082
00083     bool keep_running_;
00084 };
00085
00086
00087 /** \} */
00088 /** \} */
00089 #endif // GNSS_SDR_TCP_CMD_INTERFACE_H

```


13.707 agnss_ref_location.h File Reference

Interface of an Assisted GNSS REFERENCE LOCATION storage.

```
#include <boost/serialization/nvp.hpp>
```

Classes

- class [Agnss_Ref_Location](#)

Interface of an Assisted GNSS REFERENCE LOCATION storage.

13.707.1 Detailed Description

Interface of an Assisted GNSS REFERENCE LOCATION storage.

Author

Javier Arribas, 2013. jarribas(at)cttc.es

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Definition in file [agnss_ref_location.h](#).

13.708 agnss_ref_location.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file agnss_ref_location.h
00003  * \brief Interface of an Assisted GNSS REFERENCE LOCATION storage
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_AGNSS_REF_LOCATION_H
00019 #define GNSS_SDR_AGNSS_REF_LOCATION_H
00020
00021 #include <boost/serialization/nvp.hpp>
00022
00023 /** \addtogroup Core
00024  * \{ */
00025 /** \addtogroup System_Parameters
00026  * Classes containing info about system parameters for the different GNSS.
00027  * \{ */
00028
00029 /*!
00030  * \brief Interface of an Assisted GNSS REFERENCE LOCATION storage
00031  *
00032  */
00033 class Agnss_Ref_Location
00034 {
00035 public:
00036     /*!
00037      * Default constructor
00038      */
00039     Agnss_Ref_Location() = default;
00040
00041     double lat{};
00042     double lon{};
00043     double uncertainty{};
00044     bool valid{};
00045
00046     template <class Archive>
00047
00048     /*!
00049      * \brief Serialize is a boost standard method to be called by the boost XML
00050      * serialization. Here is used to save the Ref location on disk file.
```

```

00051     */
00052     inline void serialize(Archive& archive, const unsigned int version)
00053     {
00054         using boost::serialization::make_nvp;
00055         if (version)
00056         {
00057             };
00058             archive& BOOST_SERIALIZATION_NVP(lat);
00059             archive& BOOST_SERIALIZATION_NVP(lon);
00060             archive& BOOST_SERIALIZATION_NVP(uncertainty);
00061             archive& BOOST_SERIALIZATION_NVP(valid);
00062         }
00063     };
00064
00065
00066 /** \} */
00067 /** \} */
00068 #endif // GNSS_SDR_AGNSS_REF_LOCATION_H

```

13.709 agnss_ref_time.h File Reference

Interface of an Assisted GNSS REFERENCE TIME storage.

#include <boost/serialization/nvp.hpp>

Classes

- class [Agnss_Ref_Time](#)

Interface of an Assisted GNSS REFERENCE TIME storage.

13.709.1 Detailed Description

Interface of an Assisted GNSS REFERENCE TIME storage.

Author

Javier Arribas, 2013. jarribas(at)cttc.es

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Definition in file [agnss_ref_time.h](#).

13.710 agnss_ref_time.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file agnss_ref_time.h
00003  * \brief Interface of an Assisted GNSS REFERENCE TIME storage
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_AGNSS_REF_TIME_H
00019 #define GNSS_SDR_AGNSS_REF_TIME_H
00020
00021 #include <boost/serialization/nvp.hpp>
00022
00023 /** \addtogroup Core
00024  * \{ */
00025 /** \addtogroup System_Parameters
00026  * \{ */
00027
00028

```

```

00029  /*!
00030  * \brief Interface of an Assisted GNSS REFERENCE TIME storage
00031  *
00032  */
00033  class Agnss_Ref_Time
00034  {
00035  public:
00036      /*!
00037       * Default constructor
00038       */
00039      Agnss_Ref_Time() = default;
00040
00041      double tow{};
00042      double week{};
00043      double seconds{};
00044      double microseconds{};
00045      bool valid{};
00046
00047      template <class Archive>
00048
00049      /*!
00050       * \brief Serialize is a boost standard method to be called by the boost XML
00051       * serialization. Here is used to save the ref time data on disk file.
00052       */
00053      inline void serialize(Archive& archive, const unsigned int version)
00054      {
00055          if (version)
00056          {
00057              archive& BOOST_SERIALIZATION_NVP(tow);
00058              archive& BOOST_SERIALIZATION_NVP(week);
00059              archive& BOOST_SERIALIZATION_NVP(seconds);
00060              archive& BOOST_SERIALIZATION_NVP(microseconds);
00061              archive& BOOST_SERIALIZATION_NVP(valid);
00062          }
00063      };
00064  };
00065
00066  /** \} */
00067  /** \} */
00068  /** \} */
00069  #endif // GNSS_SDR_AGNSS_REF_TIME_H

```

13.711 Beidou_B1I.h File Reference

Defines system parameters for BeiDou B1I signal and DNAV data.

```

#include "gnss_frequencies.h"
#include <cstdint>

```

Variables

- constexpr double [BEIDOU_B1I_FREQ_HZ](#) = [FREQ1_BDS](#)
B1I [Hz].
- constexpr double [BEIDOU_B1I_CODE_RATE_CPS](#) = 2.046e6
Beidou B1I code rate [chips/s].
- constexpr double [BEIDOU_B1I_CODE_LENGTH_CHIPS](#) = 2046.0
Beidou B1I code length [chips].
- constexpr double [BEIDOU_B1I_CODE_PERIOD_S](#) = 0.001
Beidou B1I code period [seconds].
- constexpr double [BEIDOU_B1I_PREAMBLE_DURATION_S](#) = 0.220
- constexpr double [BEIDOU_B1I_OPT_ACQ_FS_SPS](#) = 10e6
- constexpr uint32_t [BEIDOU_B1I_CODE_PERIOD_MS](#) = 1
Beidou B1I code period [ms].
- constexpr uint32_t [BEIDOU_B1I_PREAMBLE_LENGTH_BITS](#) = 11
- constexpr uint32_t [BEIDOU_B1I_PREAMBLE_LENGTH_SYMBOLS](#) = 220
- constexpr int32_t [BEIDOU_B1I_SECONDARY_CODE_LENGTH](#) = 20
- constexpr int32_t [BEIDOU_B1I_GEO_PREAMBLE_LENGTH_SYMBOLS](#) = 22
- constexpr int32_t [BEIDOU_B1I_PREAMBLE_DURATION_MS](#) = 220
- constexpr int32_t [BEIDOU_B1I_TELEMETRY_RATE_BITS_SECOND](#) = 50

- `constexpr int32_t BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT = 20`
- `constexpr int32_t BEIDOU_B1I_GEO_TELEMETRY_SYMBOLS_PER_BIT = 2`
- `constexpr int32_t BEIDOU_B1I_TELEMETRY_SYMBOL_PERIOD_MS = static_cast<int32_t>(static_cast<uint32_t>(BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT) * BEIDOU_B1I_CODE_PERIOD_MS)`
- `constexpr int32_t BEIDOU_B1I_TELEMETRY_RATE_SYMBOLS_SECOND = BEIDOU_B1I_TELEMETRY_RATE_BITS_SECOND * BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT`
- `constexpr char BEIDOU_B1I_SECONDARY_CODE_STR [21] = "00000100110101001110"`
- `constexpr char BEIDOU_B1I_GEO_PREAMBLE_SYMBOLS_STR [23] = "1111110000001100001100"`
- `constexpr char BEIDOU_B1I_D2_SECONDARY_CODE_STR [3] = "00"`

13.711.1 Detailed Description

Defines system parameters for BeiDou B1I signal and DNAV data.

Author

Sergi Segura, 2018. [sergi.segura.munoz\(at\)gmail.com](mailto:sergi.segura.munoz(at)gmail.com)

Damian Miralles, 2018. dmiralles2009@gmail.com

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 Definition in file [Beidou_B1I.h](#).

13.712 Beidou_B1I.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file Beidou_B1I.h
00003  * \brief Defines system parameters for BeiDou B1I signal and DNAV data
00004  * \author Sergi Segura, 2018. sergi.segura.munoz\(at\)gmail.com
00005  * \author Damian Miralles, 2018. dmiralles2009@gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
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00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_BEIDOU_B1I_H
00020 #define GNSS_SDR_BEIDOU_B1I_H
00021
00022 #include "gnss_frequencies.h"
00023 #include <cstdint>
00024
00025 /** \addtogroup Core
00026  * \{ */
00027 /** \addtogroup System_Parameters
00028  * \{ */
00029
00030
00031 // carrier and code frequencies
00032 constexpr double BEIDOU_B1I_FREQ_HZ = FREQ1_BDS;          //!< B1I [Hz]
00033 constexpr double BEIDOU_B1I_CODE_RATE_CPS = 2.046e6;      //!< Beidou B1I code rate [chips/s]
00034 constexpr double BEIDOU_B1I_CODE_LENGTH_CHIPS = 2046.0;    //!< Beidou B1I code length [chips]
00035 constexpr double BEIDOU_B1I_CODE_PERIOD_S = 0.001;         //!< Beidou B1I code period [seconds]
00036 constexpr double BEIDOU_B1I_PREAMBLE_DURATION_S = 0.220;
00037 constexpr double BEIDOU_B1I_OPT_ACQ_FS_SPS = 10e6;
00038 constexpr uint32_t BEIDOU_B1I_CODE_PERIOD_MS = 1;          //!< Beidou B1I code period [ms]
00039 constexpr uint32_t BEIDOU_B1I_PREAMBLE_LENGTH_BITS = 11;
00040 constexpr uint32_t BEIDOU_B1I_PREAMBLE_LENGTH_SYMBOLS = 220;
00041 constexpr int32_t BEIDOU_B1I_SECONDARY_CODE_LENGTH = 20;
00042 constexpr int32_t BEIDOU_B1I_GEO_PREAMBLE_LENGTH_SYMBOLS = 22;
00043 constexpr int32_t BEIDOU_B1I_PREAMBLE_DURATION_MS = 220;
00044 constexpr int32_t BEIDOU_B1I_TELEMETRY_RATE_BITS_SECOND = 50;
00045 constexpr int32_t BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT = 20;
00046 constexpr int32_t BEIDOU_B1I_GEO_TELEMETRY_SYMBOLS_PER_BIT = 2;
00047 constexpr int32_t BEIDOU_B1I_TELEMETRY_SYMBOL_PERIOD_MS =
    static_cast<int32_t>(static_cast<uint32_t>(BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT) *
    BEIDOU_B1I_CODE_PERIOD_MS);
```

```

00048 constexpr int32_t BEIDOU_B1I_TELEMETRY_RATE_SYMBOLS_SECOND = BEIDOU_B1I_TELEMETRY_RATE_BITS_SECOND *
    BEIDOU_B1I_TELEMETRY_SYMBOLS_PER_BIT;
00049 constexpr char BEIDOU_B1I_SECONDARY_CODE_STR[21] = "00000100110101001110";
00050 constexpr char BEIDOU_B1I_GEO_PREAMBLE_SYMBOLS_STR[23] = "1111110000001100001100";
00051 constexpr char BEIDOU_B1I_D2_SECONDARY_CODE_STR[3] = "00";
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_BEIDOU_B1I_H

```

13.713 Beidou_B3I.h File Reference

Defines system parameters for BeiDou B3I signal and DNAV data.

```

#include "gnss_frequencies.h"
#include <cstdint>

```

Variables

- constexpr double [BEIDOU_B3I_FREQ_HZ](#) = [FREQ3_BDS](#)
BeiDou B3I [Hz].
- constexpr double [BEIDOU_B3I_CODE_RATE_CPS](#) = 10.23e6
BeiDou B3I code rate [chips/s].
- constexpr double [BEIDOU_B3I_CODE_LENGTH_CHIPS](#) = 10230.0
BeiDou B3I code length [chips].
- constexpr double [BEIDOU_B3I_CODE_PERIOD_S](#) = 0.001
BeiDou B3I code period [seconds].
- constexpr double [BEIDOU_B3I_PREAMBLE_DURATION_S](#) = 0.220
- constexpr double [BEIDOU_B3I_OPT_ACQ_FS_SPS](#) = 10e6
- constexpr uint32_t [BEIDOU_B3I_CODE_PERIOD_MS](#) = 1
BeiDou B3I code period [ms].
- constexpr uint32_t [BEIDOU_B3I_PREAMBLE_LENGTH_BITS](#) = 11
- constexpr uint32_t [BEIDOU_B3I_PREAMBLE_LENGTH_SYMBOLS](#) = 220
- constexpr int32_t [BEIDOU_B3I_SECONDARY_CODE_LENGTH](#) = 20
- constexpr int32_t [BEIDOU_B3I_GEO_PREAMBLE_LENGTH_SYMBOLS](#) = 22
- constexpr int32_t [BEIDOU_B3I_PREAMBLE_DURATION_MS](#) = 220
- constexpr int32_t [BEIDOU_B3I_TELEMETRY_RATE_BITS_SECOND](#) = 50
D1 NAV message bit rate [bits/s].
- constexpr int32_t [BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT](#) = 20
- constexpr int32_t [BEIDOU_B3I_GEO_TELEMETRY_SYMBOLS_PER_BIT](#) = 2
- constexpr int32_t [BEIDOU_B3I_TELEMETRY_SYMBOL_PERIOD_MS](#) = static_cast<int32_t>(static_cast<uint32_t>(BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT) * [BEIDOU_B3I_CODE_PERIOD_MS](#))
- constexpr int32_t [BEIDOU_B3I_TELEMETRY_RATE_SYMBOLS_SECOND](#) = [BEIDOU_B3I_TELEMETRY_RATE_BITS_SECOND](#) * [BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT](#)
- constexpr char [BEIDOU_B3I_SECONDARY_CODE_STR](#) [21] = "00000100110101001110"
- constexpr char [BEIDOU_B3I_GEO_PREAMBLE_SYMBOLS_STR](#) [23] = "1111110000001100001100"
- constexpr char [BEIDOU_B3I_D2_SECONDARY_CODE_STR](#) [3] = "00"

13.713.1 Detailed Description

Defines system parameters for BeiDou B3I signal and DNAV data.

Author

Damian Miralles, 2019. dmiralles2009@gmail.com

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 Definition in file [Beidou_B3I.h](#).

13.714 Beidou_B3I.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file Beidou_B3I.h
00003  * \brief Defines system parameters for BeiDou B3I signal and DNAV data
00004  * \author Damian Miralles, 2019. dmiralles2009@gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_BEIDOU_B3I_H
00019 #define GNSS_SDR_BEIDOU_B3I_H
00020
00021 #include "gnss_frequencies.h"
00022 #include <cstdint>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup System_Parameters
00027  * \{ */
00028
00029
00030 // carrier and code frequencies
00031 constexpr double BEIDOU_B3I_FREQ_HZ = FREQ3_BDS;          //!< BeiDou B3I [Hz]
00032 constexpr double BEIDOU_B3I_CODE_RATE_CPS = 10.23e6;      //!< BeiDou B3I code rate [chips/s]
00033 constexpr double BEIDOU_B3I_CODE_LENGTH_CHIPS = 10230.0;  //!< BeiDou B3I code length [chips]
00034 constexpr double BEIDOU_B3I_CODE_PERIOD_S = 0.001;        //!< BeiDou B3I code period [seconds]
00035 constexpr double BEIDOU_B3I_PREAMBLE_DURATION_S = 0.220;
00036 constexpr double BEIDOU_B3I_OPT_ACQ_FS_SPS = 10e6;
00037 constexpr uint32_t BEIDOU_B3I_CODE_PERIOD_MS = 1;          //!< BeiDou B3I code period [ms]
00038 constexpr uint32_t BEIDOU_B3I_PREAMBLE_LENGTH_BITS = 11;
00039 constexpr uint32_t BEIDOU_B3I_PREAMBLE_LENGTH_SYMBOLS = 220; // *****
00040 constexpr int32_t BEIDOU_B3I_SECONDARY_CODE_LENGTH = 20;
00041 constexpr int32_t BEIDOU_B3I_GEO_PREAMBLE_LENGTH_SYMBOLS = 22;
00042 constexpr int32_t BEIDOU_B3I_PREAMBLE_DURATION_MS = 220;
00043 constexpr int32_t BEIDOU_B3I_TELEMETRY_RATE_BITS_SECOND = 50; //!< D1 NAV message bit rate [bits/s]
00044 constexpr int32_t BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT = 20;
00045 constexpr int32_t BEIDOU_B3I_GEO_TELEMETRY_SYMBOLS_PER_BIT = 2; // *****
00046 constexpr int32_t BEIDOU_B3I_TELEMETRY_SYMBOL_PERIOD_MS =
    static_cast<int32_t>(static_cast<uint32_t>(BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT) *
    BEIDOU_B3I_CODE_PERIOD_MS);
00047 constexpr int32_t BEIDOU_B3I_TELEMETRY_RATE_SYMBOLS_SECOND = BEIDOU_B3I_TELEMETRY_RATE_BITS_SECOND *
    BEIDOU_B3I_TELEMETRY_SYMBOLS_PER_BIT;
00048 constexpr char BEIDOU_B3I_SECONDARY_CODE_STR[21] = "00000100110101001110";
00049 constexpr char BEIDOU_B3I_GEO_PREAMBLE_SYMBOLS_STR[23] = "1111110000001100001100";
00050 constexpr char BEIDOU_B3I_D2_SECONDARY_CODE_STR[3] = "00";
00051
00052
00053 /** \} */
00054 /** \} */
00055 #endif // GNSS_SDR_BEIDOU_B3I_H

```

13.715 Beidou_DNAV.h File Reference

Defines system parameters for BeiDou DNAV data processing.

```

#include "MATH_CONSTANTS.h"
#include <cstdint>
#include <utility>
#include <vector>

```

Functions

- `const std::vector< std::pair< int32_t, int32_t > > D1_PRE {{{1, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_FRAID {{{16, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_SOW {{{19, 8}, {31, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_PNUM {{{44, 7}}}`

- `const std::vector< std::pair< int32_t, int32_t > > D1_SAT_H1 {{{43, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_AODC {{{44, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_URAI {{{49, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_WN {{{61, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TOC {{{74, 9}, {91, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TGD1 {{{99, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TGD2 {{{109, 4}, {121, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_ALPHA0 {{{127, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_ALPHA1 {{{135, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_ALPHA2 {{{151, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_ALPHA3 {{{159, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_BETA0 {{{167, 6}, {181, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_BETA1 {{{183, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_BETA2 {{{191, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_BETA3 {{{199, 4}, {211, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A2 {{{215, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A0 {{{226, 7}, {241, 17}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A1 {{{258, 5}, {271, 17}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_AODE {{{288, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_DELTA_N {{{43, 10}, {61, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_CUC {{{67, 16}, {91, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_M0 {{{93, 20}, {121, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_E {{{133, 10}, {151, 22}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_CUS {{{181, 18}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_CRC {{{199, 4}, {211, 14}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_CRS {{{225, 8}, {241, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_SQRT_A {{{251, 12}, {271, 20}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TOE_SF2 {{{291, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TOE_SF3 {{{43, 10}, {61, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_I0 {{{66, 17}, {91, 15}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_CIC {{{106, 7}, {121, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_OMEGA_DOT {{{132, 11}, {151, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_CIS {{{164, 9}, {181, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_IDOT {{{190, 13}, {211, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_OMEGA0 {{{212, 21}, {241, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_OMEGA {{{252, 11}, {271, 21}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_SQRT_A_ALMANAC {{{51, 2}, {61, 22}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A1_ALMANAC {{{91, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A0_ALMANAC {{{102, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_OMEGA0_ALMANAC {{{121, 22}, {151, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_E_ALMANAC {{{153, 17}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_DELTA_I {{{170, 3}, {181, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TOA {{{194, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_OMEGA_DOT_ALMANAC {{{202, 1}, {211, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_OMEGA_ALMANAC {{{227, 6}, {241, 18}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_M0_ALMANAC {{{259, 4}, {271, 20}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA1 {{{51, 2}, {61, 7}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA2 {{{68, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA3 {{{77, 6}, {91, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA4 {{{94, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA5 {{{103, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA6 {{{112, 1}, {121, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA7 {{{129, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA8 {{{138, 5}, {151, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA9 {{{155, 9}}}`

- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA10 {{{164, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA11 {{{181, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA12 {{{190, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA13 {{{199, 4}, {211, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA14 {{{216, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA15 {{{225, 8}, {241, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA16 {{{242, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA17 {{{251, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA18 {{{260, 3}, {271, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA19 {{{277, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA20 {{{51, 2}, {61, 7}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA21 {{{68, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA22 {{{77, 6}, {91, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA23 {{{94, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA24 {{{103, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA25 {{{112, 1}, {121, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA26 {{{129, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA27 {{{138, 5}, {151, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA28 {{{155, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA29 {{{164, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_HEA30 {{{181, 9}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_WNA {{{190, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_TOA2 {{{198, 5}, {211, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A0GPS {{{97, 14}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A1GPS {{{111, 2}, {121, 14}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A0GAL {{{135, 8}, {151, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A1GAL {{{157, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A0GLO {{{181, 14}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A1GLO {{{195, 8}, {211, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_DELTA_T_LS {{{51, 2}, {61, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_DELTA_T_LSF {{{67, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_WN_LSF {{{75, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A0UTC {{{91, 22}, {121, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_A1UTC {{{131, 12}, {151, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D1_DN {{{163, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_PRE {{{1, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_FRAID {{{16, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_SOW {{{19, 8}, {31, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_PNUM {{{43, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_SAT_H1 {{{47, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_AODC {{{48, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_URAI {{{61, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_WN {{{65, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_TOC {{{78, 5}, {91, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_TGD1 {{{103, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_TGD2 {{{121, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_ALPHA0 {{{47, 6}, {61, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_ALPHA1 {{{63, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_ALPHA2 {{{71, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_ALPHA3 {{{79, 4}, {91, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_BETA0 {{{95, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_BETA1 {{{103, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_BETA2 {{{111, 2}, {121, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_BETA3 {{{127, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > D2_A0 {{{101, 12}, {121, 12}}}`

- `const std::vector< std::pair< int32_t, int32_t > > D2_A1_MSB` ({133, 4}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_A1_LSB` ({47, 6}, {61, 12}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_A1` ({279, 22}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_A2` ({73, 10}, {91, 1}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_AODE` ({92, 5}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_DELTA_N` ({97, 16}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_CUC_MSB` ({121, 14}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_CUC_LSB` ({47, 4}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_CUC` ({283, 18}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_M0` ({51, 2}, {61, 22}, {91, 8}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_CUS` ({99, 14}, {121, 4}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_E_MSB` ({125, 10}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_E_LSB` ({47, 6}, {61, 16}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_SQRT_A` ({77, 6}, {91, 22}, {121, 4}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_CIC_MSB` ({125, 10}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_CIC_LSB` ({47, 6}, {61, 2}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_CIC` ({283, 18}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_CIS` ({63, 18}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_TOE` ({81, 2}, {91, 15}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_I0_MSB` ({106, 7}, {121, 14}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_I0_LSB` ({47, 6}, {61, 5}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_I0` ({269, 32}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_CRC` ({66, 17}, {91, 1}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_CRS` ({92, 18}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA_DOT_MSB` ({110, 3}, {121, 16}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA_DOT_LSB` ({47, 5}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA_DOT` ({277, 24}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA0` ({52, 1}, {61, 22}, {91, 9}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA_MSB` ({100, 13}, {121, 14}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA_LSB` ({47, 5}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_OMEGA` ({269, 32}}
- `const std::vector< std::pair< int32_t, int32_t > > D2_IDOT` ({52, 1}, {61, 13}}

Variables

- `constexpr double D1_TOC_LSB` = TWO_P3
- `constexpr double D1_TGD1_LSB` = 0.1e-9
- `constexpr double D1_TGD2_LSB` = 0.1e-9
- `constexpr double D1_ALPHA0_LSB` = TWO_N30
- `constexpr double D1_ALPHA1_LSB` = TWO_N27
- `constexpr double D1_ALPHA2_LSB` = TWO_N24
- `constexpr double D1_ALPHA3_LSB` = TWO_N24
- `constexpr double D1_BETA0_LSB` = TWO_P11
- `constexpr double D1_BETA1_LSB` = TWO_P14
- `constexpr double D1_BETA2_LSB` = TWO_P16
- `constexpr double D1_BETA3_LSB` = TWO_P16
- `constexpr double D1_A2_LSB` = TWO_N66
- `constexpr double D1_A0_LSB` = TWO_N33
- `constexpr double D1_A1_LSB` = TWO_N50
- `constexpr double D1_DELTA_N_LSB` = PI_TWO_N43
- `constexpr double D1_CUC_LSB` = TWO_N31
- `constexpr double D1_M0_LSB` = PI_TWO_N31
- `constexpr double D1_E_LSB` = TWO_N33
- `constexpr double D1_CUS_LSB` = TWO_N31
- `constexpr double D1_CRC_LSB` = TWO_N6

- constexpr double `D1_CRS_LSB` = `TWO_N6`
 - constexpr double `D1_SQRT_A_LSB` = `TWO_N19`
 - constexpr double `D1_TOE_LSB` = `TWO_P3`
 - constexpr double `D1_I0_LSB` = `PI_TWO_N31`
 - constexpr double `D1_CIC_LSB` = `TWO_N31`
 - constexpr double `D1_OMEGA_DOT_LSB` = `PI_TWO_N43`
 - constexpr double `D1_CIS_LSB` = `TWO_N31`
 - constexpr double `D1_IDOT_LSB` = `PI_TWO_N43`
 - constexpr double `D1_OMEGA0_LSB` = `PI_TWO_N31`
 - constexpr double `D1_OMEGA_LSB` = `PI_TWO_N31`
 - constexpr double `D1_SQRT_A_ALMANAC_LSB` = `TWO_N11`
 - constexpr double `D1_A1_ALMANAC_LSB` = `TWO_N38`
 - constexpr double `D1_A0_ALMANAC_LSB` = `TWO_N20`
 - constexpr double `D1_OMEGA0_ALMANAC_LSB` = `PI_TWO_N23`
 - constexpr double `D1_E_ALMANAC_LSB` = `TWO_N21`
 - constexpr double `D1_DELTA_I_LSB` = `PI_TWO_N19`
 - constexpr double `D1_TOA_LSB` = `TWO_P12`
 - constexpr double `D1_OMEGA_DOT_ALMANAC_LSB` = `PI_TWO_N38`
 - constexpr double `D1_OMEGA_ALMANAC_LSB` = `PI_TWO_N23`
 - constexpr double `D1_M0_ALMANAC_LSB` = `PI_TWO_N23`
 - constexpr double `D1_A0GPS_LSB` = `0.1e-9`
 - constexpr double `D1_A1GPS_LSB` = `0.1e-9`
 - constexpr double `D1_A0GAL_LSB` = `0.1e-9`
 - constexpr double `D1_A1GAL_LSB` = `0.1e-9`
 - constexpr double `D1_A0GLO_LSB` = `0.1e-9`
 - constexpr double `D1_A1GLO_LSB` = `0.1e-9`
 - constexpr double `D1_A0UTC_LSB` = `TWO_N30`
 - constexpr double `D1_A1UTC_LSB` = `TWO_N50`
 - constexpr int32_t `BEIDOU_DNAV_PREAMBLE_LENGTH_BITS` = 11
 - constexpr int32_t `BEIDOU_DNAV_PREAMBLE_LENGTH_SYMBOLS` = 11
 - constexpr int32_t `BEIDOU_DNAV_PREAMBLE_PERIOD_SYMBOLS` = 300
 - constexpr int32_t `BEIDOU_DNAV_SUBFRAME_DATA_BITS` = 300
- Number of bits per subframe in the NAV message [bits].*
- constexpr int32_t `BEIDOU_DNAV_BDT2GPST_LEAP_SEC_OFFSET` = 14
 - constexpr int32_t `BEIDOU_DNAV_BDT2GPST_WEEK_NUM_OFFSET` = 1356
 - constexpr uint32_t `BEIDOU_DNAV_SUBFRAME_SYMBOLS` = 300
 - constexpr uint32_t `BEIDOU_DNAV_WORDS_SUBFRAME` = 10
 - constexpr uint32_t `BEIDOU_DNAV_WORD_LENGTH_BITS` = 30
 - constexpr char `BEIDOU_DNAV_PREAMBLE` [12] = "11100010010"

13.715.1 Detailed Description

Defines system parameters for BeiDou DNAV data processing.

Author

Damian Miralles, 2018. dmiralles2009@gmail.com

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 Definition in file [Beidou_DNAV.h](#).

13.716 Beidou_DNAV.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file Beidou_DNAV.h
00003  * \brief Defines system parameters for BeiDou DNAV data processing
00004  * \author Damian Miralles, 2018. dmiralles2009@gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_BEIDOU_DNAV_H
00019 #define GNSS_SDR_BEIDOU_DNAV_H
00020
00021 #include "MATH_CONSTANTS.h"
00022 #include <stdint>
00023 #include <utility>
00024 #include <vector>
00025
00026 /** \addtogroup Core
00027  * \{ */
00028 /** \addtogroup System_Parameters
00029  * \{ */
00030
00031
00032 // DNAV SCALE FACTORS
00033 // EPH
00034 constexpr double D1_TOC_LSB = TWO_P3;
00035 constexpr double D1_TGD1_LSB = 0.1e-9;
00036 constexpr double D1_TGD2_LSB = 0.1e-9;
00037 constexpr double D1_ALPHA0_LSB = TWO_N30;
00038 constexpr double D1_ALPHA1_LSB = TWO_N27;
00039 constexpr double D1_ALPHA2_LSB = TWO_N24;
00040 constexpr double D1_ALPHA3_LSB = TWO_N24;
00041 constexpr double D1_BETA0_LSB = TWO_P11;
00042 constexpr double D1_BETA1_LSB = TWO_P14;
00043 constexpr double D1_BETA2_LSB = TWO_P16;
00044 constexpr double D1_BETA3_LSB = TWO_P16;
00045 constexpr double D1_A2_LSB = TWO_N66;
00046 constexpr double D1_A0_LSB = TWO_N33;
00047 constexpr double D1_A1_LSB = TWO_N50;
00048 constexpr double D1_DELTA_N_LSB = PI_TWO_N43;
00049 constexpr double D1_CUC_LSB = TWO_N31;
00050 constexpr double D1_M0_LSB = PI_TWO_N31;
00051 constexpr double D1_E_LSB = TWO_N33;
00052 constexpr double D1_CUS_LSB = TWO_N31;
00053 constexpr double D1_CRC_LSB = TWO_N6;
00054 constexpr double D1_CRS_LSB = TWO_N6;
00055 constexpr double D1_SQRT_A_LSB = TWO_N19;
00056 constexpr double D1_TOE_LSB = TWO_P3;
00057 constexpr double D1_I0_LSB = PI_TWO_N31;
00058 constexpr double D1_CIC_LSB = TWO_N31;
00059 constexpr double D1_OMEGA_DOT_LSB = PI_TWO_N43;
00060 constexpr double D1_CIS_LSB = TWO_N31;
00061 constexpr double D1_IDOT_LSB = PI_TWO_N43;
00062 constexpr double D1_OMEGA0_LSB = PI_TWO_N31;
00063 constexpr double D1_OMEGA_LSB = PI_TWO_N31;
00064 // ALM
00065 constexpr double D1_SQRT_A_ALMANAC_LSB = TWO_N11;
00066 constexpr double D1_A1_ALMANAC_LSB = TWO_N38;
00067 constexpr double D1_A0_ALMANAC_LSB = TWO_N20;
00068 constexpr double D1_OMEGA0_ALMANAC_LSB = PI_TWO_N23;
00069 constexpr double D1_E_ALMANAC_LSB = TWO_N21;
00070 constexpr double D1_DELTA_I_LSB = PI_TWO_N19;
00071 constexpr double D1_TOA_LSB = TWO_P12;
00072 constexpr double D1_OMEGA_DOT_ALMANAC_LSB = PI_TWO_N38;
00073 constexpr double D1_OMEGA_ALMANAC_LSB = PI_TWO_N23;
00074 constexpr double D1_M0_ALMANAC_LSB = PI_TWO_N23;
00075 constexpr double D1_A0GPS_LSB = 0.1e-9;
00076 constexpr double D1_A1GPS_LSB = 0.1e-9;
00077 constexpr double D1_A0GAL_LSB = 0.1e-9;
00078 constexpr double D1_A1GAL_LSB = 0.1e-9;
00079 constexpr double D1_A0GLO_LSB = 0.1e-9;
00080 constexpr double D1_A1GLO_LSB = 0.1e-9;
00081 constexpr double D1_A0UTC_LSB = TWO_N30;
00082 constexpr double D1_A1UTC_LSB = TWO_N50;
00083

```

```

00084 constexpr int32_t BEIDOU_DNAV_PREAMBLE_LENGTH_BITS = 11;
00085 constexpr int32_t BEIDOU_DNAV_PREAMBLE_LENGTH_SYMBOLS = 11; // *****
00086 constexpr int32_t BEIDOU_DNAV_PREAMBLE_PERIOD_SYMBOLS = 300;
00087 constexpr int32_t BEIDOU_DNAV_SUBFRAME_DATA_BITS = 300; //!< Number of bits per subframe in the NAV
    message [bits]
00088 // Number of leap seconds passed from the start of the GPS epoch up to the start of BeiDou epoch
00089 constexpr int32_t BEIDOU_DNAV_BDT2GPST_LEAP_SEC_OFFSET = 14;
00090 // Number of weeks passed from the start of the GPS epoch up to the start of BeiDou epoch
00091 constexpr int32_t BEIDOU_DNAV_BDT2GPST_WEEK_NUM_OFFSET = 1356;
00092
00093 constexpr uint32_t BEIDOU_DNAV_SUBFRAME_SYMBOLS = 300;
00094 constexpr uint32_t BEIDOU_DNAV_WORDS_SUBFRAME = 10;
00095 constexpr uint32_t BEIDOU_DNAV_WORD_LENGTH_BITS = 30;
00096 constexpr char BEIDOU_DNAV_PREAMBLE[12] = "11100010010";
00097
00098
00099 // BEIDOU D1 NAVIGATION MESSAGE STRUCTURE
00100 // GENERAL
00101 const std::vector<std::pair<int32_t, int32_t> > D1_PRE({{1, 11}});
00102 const std::vector<std::pair<int32_t, int32_t> > D1_FRAID({{16, 3}});
00103 const std::vector<std::pair<int32_t, int32_t> > D1_SOW({{19, 8}, {31, 12}});
00104 const std::vector<std::pair<int32_t, int32_t> > D1_PNUM({{44, 7}});
00105
00106 // SUBFRAME 1
00107 const std::vector<std::pair<int32_t, int32_t> > D1_SAT_H1({{43, 1}});
00108 const std::vector<std::pair<int32_t, int32_t> > D1_AODC({{44, 5}});
00109 const std::vector<std::pair<int32_t, int32_t> > D1_URAI({{49, 4}});
00110 const std::vector<std::pair<int32_t, int32_t> > D1_WN({{61, 13}});
00111 const std::vector<std::pair<int32_t, int32_t> > D1_TOC({{74, 9}, {91, 8}});
00112 const std::vector<std::pair<int32_t, int32_t> > D1_TGD1({{99, 10}});
00113 const std::vector<std::pair<int32_t, int32_t> > D1_TGD2({{109, 4}, {121, 6}});
00114 const std::vector<std::pair<int32_t, int32_t> > D1_ALPHA0({{127, 8}});
00115 const std::vector<std::pair<int32_t, int32_t> > D1_ALPHA1({{135, 8}});
00116 const std::vector<std::pair<int32_t, int32_t> > D1_ALPHA2({{151, 8}});
00117 const std::vector<std::pair<int32_t, int32_t> > D1_ALPHA3({{159, 8}});
00118 const std::vector<std::pair<int32_t, int32_t> > D1_BETA0({{167, 6}, {181, 2}});
00119 const std::vector<std::pair<int32_t, int32_t> > D1_BETA1({{183, 8}});
00120 const std::vector<std::pair<int32_t, int32_t> > D1_BETA2({{191, 8}});
00121 const std::vector<std::pair<int32_t, int32_t> > D1_BETA3({{199, 4}, {211, 4}});
00122 const std::vector<std::pair<int32_t, int32_t> > D1_A2({{215, 11}});
00123 const std::vector<std::pair<int32_t, int32_t> > D1_A0({{226, 7}, {241, 17}});
00124 const std::vector<std::pair<int32_t, int32_t> > D1_A1({{258, 5}, {271, 17}});
00125 const std::vector<std::pair<int32_t, int32_t> > D1_AODE({{288, 5}});
00126
00127 // SUBFRAME 2
00128 const std::vector<std::pair<int32_t, int32_t> > D1_DELTA_N({{43, 10}, {61, 6}});
00129 const std::vector<std::pair<int32_t, int32_t> > D1_CUC({{67, 16}, {91, 2}});
00130 const std::vector<std::pair<int32_t, int32_t> > D1_MO({{93, 20}, {121, 12}});
00131 const std::vector<std::pair<int32_t, int32_t> > D1_E({{133, 10}, {151, 22}});
00132 const std::vector<std::pair<int32_t, int32_t> > D1_CUS({{181, 18}});
00133 const std::vector<std::pair<int32_t, int32_t> > D1_CRC({{199, 4}, {211, 14}});
00134 const std::vector<std::pair<int32_t, int32_t> > D1_CRS({{225, 8}, {241, 10}});
00135 const std::vector<std::pair<int32_t, int32_t> > D1_SQRT_A({{251, 12}, {271, 20}});
00136 const std::vector<std::pair<int32_t, int32_t> > D1_TOE_SF2({{291, 2}});
00137
00138 // SUBFRAME 3
00139 const std::vector<std::pair<int32_t, int32_t> > D1_TOE_SF3({{43, 10}, {61, 5}});
00140 const std::vector<std::pair<int32_t, int32_t> > D1_IO({{66, 17}, {91, 15}});
00141 const std::vector<std::pair<int32_t, int32_t> > D1_CIC({{106, 7}, {121, 11}});
00142 const std::vector<std::pair<int32_t, int32_t> > D1_OMEGA_DOT({{132, 11}, {151, 13}});
00143 const std::vector<std::pair<int32_t, int32_t> > D1_CIS({{164, 9}, {181, 9}});
00144 const std::vector<std::pair<int32_t, int32_t> > D1_IDOT({{190, 13}, {211, 11}});
00145 const std::vector<std::pair<int32_t, int32_t> > D1_OMEGA0({{212, 21}, {241, 11}});
00146 const std::vector<std::pair<int32_t, int32_t> > D1_OMEGA({{252, 11}, {271, 21}});
00147
00148 // SUBFRAME 4 AND PAGES 1 THROUGH 6 IN SUBFRAME 5
00149 const std::vector<std::pair<int32_t, int32_t> > D1_SQRT_A_ALMANAC({{51, 2}, {61, 22}});
00150 const std::vector<std::pair<int32_t, int32_t> > D1_A1_ALMANAC({{91, 11}});
00151 const std::vector<std::pair<int32_t, int32_t> > D1_A0_ALMANAC({{102, 11}});
00152 const std::vector<std::pair<int32_t, int32_t> > D1_OMEGA0_ALMANAC({{121, 22}, {151, 2}});
00153 const std::vector<std::pair<int32_t, int32_t> > D1_E_ALMANAC({{153, 17}});
00154 const std::vector<std::pair<int32_t, int32_t> > D1_DELTA_I({{170, 3}, {181, 13}});
00155 const std::vector<std::pair<int32_t, int32_t> > D1_TOA({{194, 8}});
00156 const std::vector<std::pair<int32_t, int32_t> > D1_OMEGA_DOT_ALMANAC({{202, 1}, {211, 16}});
00157 const std::vector<std::pair<int32_t, int32_t> > D1_OMEGA_ALMANAC({{227, 6}, {241, 18}});
00158 const std::vector<std::pair<int32_t, int32_t> > D1_MO_ALMANAC({{259, 4}, {271, 20}});
00159
00160 // SUBFRAME 5 PAGE 7
00161 const std::vector<std::pair<int32_t, int32_t> > D1_HEA1({{51, 2}, {61, 7}});
00162 const std::vector<std::pair<int32_t, int32_t> > D1_HEA2({{68, 9}});
00163 const std::vector<std::pair<int32_t, int32_t> > D1_HEA3({{77, 6}, {91, 3}});
00164 const std::vector<std::pair<int32_t, int32_t> > D1_HEA4({{94, 9}});
00165 const std::vector<std::pair<int32_t, int32_t> > D1_HEA5({{103, 9}});
00166 const std::vector<std::pair<int32_t, int32_t> > D1_HEA6({{112, 1}, {121, 8}});
00167 const std::vector<std::pair<int32_t, int32_t> > D1_HEA7({{129, 9}});
00168 const std::vector<std::pair<int32_t, int32_t> > D1_HEA8({{138, 5}, {151, 4}});
00169 const std::vector<std::pair<int32_t, int32_t> > D1_HEA9({{155, 9}});

```

```

00170 const std::vector<std::pair<int32_t, int32_t> > D1_HEA10({{164, 9}});
00171 const std::vector<std::pair<int32_t, int32_t> > D1_HEA11({{181, 9}});
00172 const std::vector<std::pair<int32_t, int32_t> > D1_HEA12({{190, 9}});
00173 const std::vector<std::pair<int32_t, int32_t> > D1_HEA13({{199, 4}, {211, 5}});
00174 const std::vector<std::pair<int32_t, int32_t> > D1_HEA14({{216, 9}});
00175 const std::vector<std::pair<int32_t, int32_t> > D1_HEA15({{225, 8}, {241, 1}});
00176 const std::vector<std::pair<int32_t, int32_t> > D1_HEA16({{242, 9}});
00177 const std::vector<std::pair<int32_t, int32_t> > D1_HEA17({{251, 9}});
00178 const std::vector<std::pair<int32_t, int32_t> > D1_HEA18({{260, 3}, {271, 6}});
00179 const std::vector<std::pair<int32_t, int32_t> > D1_HEA19({{277, 9}});
00180
00181 // SUBFRAME 5 PAGE 8
00182 const std::vector<std::pair<int32_t, int32_t> > D1_HEA20({{51, 2}, {61, 7}});
00183 const std::vector<std::pair<int32_t, int32_t> > D1_HEA21({{68, 9}});
00184 const std::vector<std::pair<int32_t, int32_t> > D1_HEA22({{77, 6}, {91, 3}});
00185 const std::vector<std::pair<int32_t, int32_t> > D1_HEA23({{94, 9}});
00186 const std::vector<std::pair<int32_t, int32_t> > D1_HEA24({{103, 9}});
00187 const std::vector<std::pair<int32_t, int32_t> > D1_HEA25({{112, 1}, {121, 8}});
00188 const std::vector<std::pair<int32_t, int32_t> > D1_HEA26({{129, 9}});
00189 const std::vector<std::pair<int32_t, int32_t> > D1_HEA27({{138, 5}, {151, 4}});
00190 const std::vector<std::pair<int32_t, int32_t> > D1_HEA28({{155, 9}});
00191 const std::vector<std::pair<int32_t, int32_t> > D1_HEA29({{164, 9}});
00192 const std::vector<std::pair<int32_t, int32_t> > D1_HEA30({{181, 9}});
00193 const std::vector<std::pair<int32_t, int32_t> > D1_WNA({{190, 8}});
00194 const std::vector<std::pair<int32_t, int32_t> > D1_TOA2({{198, 5}, {211, 3}});
00195
00196 // SUBFRAME 5 PAGE 9
00197 const std::vector<std::pair<int32_t, int32_t> > D1_AOGPS({{97, 14}});
00198 const std::vector<std::pair<int32_t, int32_t> > D1_AIGPS({{111, 2}, {121, 14}});
00199 const std::vector<std::pair<int32_t, int32_t> > D1_AOGAL({{135, 8}, {151, 6}});
00200 const std::vector<std::pair<int32_t, int32_t> > D1_AIGAL({{157, 16}});
00201 const std::vector<std::pair<int32_t, int32_t> > D1_AOGLO({{181, 14}});
00202 const std::vector<std::pair<int32_t, int32_t> > D1_AIGLO({{195, 8}, {211, 8}});
00203
00204 // SUBFRAME 5 PAGE 10
00205 const std::vector<std::pair<int32_t, int32_t> > D1_DELTA_T_LS({{51, 2}, {61, 6}});
00206 const std::vector<std::pair<int32_t, int32_t> > D1_DELTA_T_LSF({{67, 8}});
00207 const std::vector<std::pair<int32_t, int32_t> > D1_WN_LSF({{75, 8}});
00208 const std::vector<std::pair<int32_t, int32_t> > D1_AOUTC({{91, 22}, {121, 10}});
00209 const std::vector<std::pair<int32_t, int32_t> > D1_ALUTC({{131, 12}, {151, 12}});
00210 const std::vector<std::pair<int32_t, int32_t> > D1_DN({{163, 8}});
00211
00212 // D2 NAV Message Decoding Information
00213 const std::vector<std::pair<int32_t, int32_t> > D2_PRE({{1, 11}});
00214 const std::vector<std::pair<int32_t, int32_t> > D2_FRAID({{16, 3}});
00215 const std::vector<std::pair<int32_t, int32_t> > D2_SOW({{19, 8}, {31, 12}});
00216 const std::vector<std::pair<int32_t, int32_t> > D2_PNUM({{43, 4}});
00217
00218 // D2 NAV, SUBFRAME 1, PAGE 1
00219 const std::vector<std::pair<int32_t, int32_t> > D2_SAT_H1({{47, 1}});
00220 const std::vector<std::pair<int32_t, int32_t> > D2_AODC({{48, 5}});
00221 const std::vector<std::pair<int32_t, int32_t> > D2_URAI({{61, 4}});
00222 const std::vector<std::pair<int32_t, int32_t> > D2_WN({{65, 13}});
00223 const std::vector<std::pair<int32_t, int32_t> > D2_TOC({{78, 5}, {91, 12}});
00224 const std::vector<std::pair<int32_t, int32_t> > D2_TGD1({{103, 10}});
00225 const std::vector<std::pair<int32_t, int32_t> > D2_TGD2({{121, 10}});
00226
00227 // D2 NAV, SUBFRAME 1, PAGE 2
00228 const std::vector<std::pair<int32_t, int32_t> > D2_ALPHA0({{47, 6}, {61, 2}});
00229 const std::vector<std::pair<int32_t, int32_t> > D2_ALPHA1({{63, 8}});
00230 const std::vector<std::pair<int32_t, int32_t> > D2_ALPHA2({{71, 8}});
00231 const std::vector<std::pair<int32_t, int32_t> > D2_ALPHA3({{79, 4}, {91, 4}});
00232 const std::vector<std::pair<int32_t, int32_t> > D2_BETA0({{95, 8}});
00233 const std::vector<std::pair<int32_t, int32_t> > D2_BETA1({{103, 8}});
00234 const std::vector<std::pair<int32_t, int32_t> > D2_BETA2({{111, 2}, {121, 6}});
00235 const std::vector<std::pair<int32_t, int32_t> > D2_BETA3({{127, 8}});
00236
00237 // D2 NAV, SUBFRAME 1, PAGE 3
00238 const std::vector<std::pair<int32_t, int32_t> > D2_A0({{101, 12}, {121, 12}});
00239 const std::vector<std::pair<int32_t, int32_t> > D2_A1_MSB({{133, 4}});
00240 const std::vector<std::pair<int32_t, int32_t> > D2_A1_LSB({{47, 6}, {61, 12}});
00241 const std::vector<std::pair<int32_t, int32_t> > D2_A1({{279, 22}});
00242
00243 // D2 NAV, SUBFRAME 1, PAGE 4
00244 const std::vector<std::pair<int32_t, int32_t> > D2_A2({{73, 10}, {91, 1}});
00245 const std::vector<std::pair<int32_t, int32_t> > D2_AODE({{92, 5}});
00246 const std::vector<std::pair<int32_t, int32_t> > D2_DELTA_N({{97, 16}});
00247 const std::vector<std::pair<int32_t, int32_t> > D2_CUC_MSB({{121, 14}});
00248 const std::vector<std::pair<int32_t, int32_t> > D2_CUC_LSB({{47, 4}});
00249 const std::vector<std::pair<int32_t, int32_t> > D2_CUC({{283, 18}});
00250
00251 // D2 NAV, SUBFRAME 1, PAGE 5
00252 const std::vector<std::pair<int32_t, int32_t> > D2_M0({{51, 2}, {61, 22}, {91, 8}});
00253 const std::vector<std::pair<int32_t, int32_t> > D2_CUS({{99, 14}, {121, 4}});
00254 const std::vector<std::pair<int32_t, int32_t> > D2_E_MSB({{125, 10}});
00255
00256 // D2 NAV, SUBFRAME 1, PAGE 6

```

```

00257 const std::vector<std::pair<int32_t, int32_t> > D2_E_LSB({{47, 6}, {61, 16}});
00258 const std::vector<std::pair<int32_t, int32_t> > D2_SQRT_A({{77, 6}, {91, 22}, {121, 4}});
00259 const std::vector<std::pair<int32_t, int32_t> > D2_CIC_MSB({{125, 10}});
00260 const std::vector<std::pair<int32_t, int32_t> > D2_CIC_LSB({{47, 6}, {61, 2}});
00261 const std::vector<std::pair<int32_t, int32_t> > D2_CIC({{283, 18}});
00262
00263 // D2 NAV, SUBFRAME 1, PAGE 7
00264 const std::vector<std::pair<int32_t, int32_t> > D2_CIS({{63, 18}});
00265 const std::vector<std::pair<int32_t, int32_t> > D2_TOE({{81, 2}, {91, 15}});
00266 const std::vector<std::pair<int32_t, int32_t> > D2_I0_MSB({{106, 7}, {121, 14}});
00267 const std::vector<std::pair<int32_t, int32_t> > D2_I0_LSB({{47, 6}, {61, 5}});
00268 const std::vector<std::pair<int32_t, int32_t> > D2_I0({{269, 32}});
00269
00270 // D2 NAV, SUBFRAME 1, PAGE 8
00271 const std::vector<std::pair<int32_t, int32_t> > D2_CRC({{66, 17}, {91, 1}});
00272 const std::vector<std::pair<int32_t, int32_t> > D2_CRS({{92, 18}});
00273 const std::vector<std::pair<int32_t, int32_t> > D2_OMEGA_DOT_MSB({{110, 3}, {121, 16}});
00274 const std::vector<std::pair<int32_t, int32_t> > D2_OMEGA_DOT_LSB({{47, 5}});
00275 const std::vector<std::pair<int32_t, int32_t> > D2_OMEGA_DOT({{277, 24}});
00276
00277 // D2 NAV, SUBFRAME 1, PAGE 9
00278 const std::vector<std::pair<int32_t, int32_t> > D2_OMEGA0({{52, 1}, {61, 22}, {91, 9}});
00279 const std::vector<std::pair<int32_t, int32_t> > D2_OMEGA_MSB({{100, 13}, {121, 14}});
00280 const std::vector<std::pair<int32_t, int32_t> > D2_OMEGA_LSB({{47, 5}});
00281 const std::vector<std::pair<int32_t, int32_t> > D2_OMEGA({{269, 32}});
00282
00283 // D2 NAV, SUBFRAME 1, PAGE 10
00284 const std::vector<std::pair<int32_t, int32_t> > D2_IDOT({{52, 1}, {61, 13}});
00285
00286
00287 /** \} */
00288 /** \} */
00289 #endif // GNSS_SDR_BEIDOU_DNAV_H

```

13.717 beidou_dnav_almanac.h File Reference

Interface of a Beidou DNAV Almanac storage.

```
#include "gnss_almanac.h"
```

```
#include <boost/serialization/nvp.hpp>
```

Classes

- class [Beidou_Dnav_Almanac](#)

This class is a storage for the BeiDou D1 almanac.

13.717.1 Detailed Description

Interface of a Beidou DNAV Almanac storage.

Author

Sergi Segura, 2018. sergi.segura.munoz@gmail.com

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [beidou_dnav_almanac.h](#).

13.718 beidou_dnav_almanac.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file beidou_dnav_almanac.h
00003  * \brief Interface of a Beidou DNAV Almanac storage
00004  * \author Sergi Segura, 2018. sergi.segura.munoz@gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later

```

```

00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_BEIDOU_DNAV_ALMANAC_H
00019 #define GNSS_SDR_BEIDOU_DNAV_ALMANAC_H
00020
00021 #include "gnss_almanac.h"
00022 #include <boost/serialization/nvp.hpp>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup System_Parameters
00027  * \{ */
00028
00029
00030 /*!
00031 * \brief This class is a storage for the BeiDou D1 almanac
00032 */
00033 class Beidou_Dnav_Almanac : public Gnss_Almanac
00034 {
00035 public:
00036     /*!
00037      * Default constructor
00038      */
00039     Beidou_Dnav_Almanac()
00040     {
00041         this->System = 'C';
00042     };
00043
00044     int SV_health{};    //!< SV Health
00045
00046     template <class Archive>
00047
00048     void serialize(Archive& ar, const unsigned int version)
00049     {
00050         if (version)
00051         {
00052             ar& BOOST_SERIALIZATION_NVP (PRN);
00053             ar& BOOST_SERIALIZATION_NVP (delta_i);
00054             ar& BOOST_SERIALIZATION_NVP (toa);
00055             ar& BOOST_SERIALIZATION_NVP (WNa);
00056             ar& BOOST_SERIALIZATION_NVP (M_0);
00057             ar& BOOST_SERIALIZATION_NVP (ecc);
00058             ar& BOOST_SERIALIZATION_NVP (sqrtA);
00059             ar& BOOST_SERIALIZATION_NVP (OMEGA_0);
00060             ar& BOOST_SERIALIZATION_NVP (omega);
00061             ar& BOOST_SERIALIZATION_NVP (OMEGAdot);
00062             ar& BOOST_SERIALIZATION_NVP (af0);
00063             ar& BOOST_SERIALIZATION_NVP (af1);
00064             ar& BOOST_SERIALIZATION_NVP (SV_health);
00065         }
00066     };
00067 };
00068
00069
00070 /** \} */
00071 /** \} */
00072 #endif // GNSS_SDR_BEIDOU_DNAV_ALMANAC_H

```

13.719 beidou_dnav_ephemeris.h File Reference

Interface of a BEIDOU EPHEMERIS storage.

```

#include "gnss_ephemeris.h"
#include <boost/serialization/nvp.hpp>
#include <map>
#include <string>

```

Classes

- class [Beidou_Dnav_Ephemeris](#)

This is a storage class for the BeiDou SV ephemeris data as described in BeiDou Navigation Satellite System Signal In Space Interface Control Document Open Service Signal B1I (Version 3.0)

13.719.1 Detailed Description

Interface of a BEIDOU EPHEMERIS storage.

Author

Sergi Segura, 2018. [sergi.segura.munoz\(at\)gmail.com](mailto:sergi.segura.munoz(at)gmail.com)

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 Definition in file [beidou_dnav_ephemeris.h](#).

13.720 beidou_dnav_ephemeris.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file beidou_dnav_ephemeris.h
00003  * \brief Interface of a BEIDOU EPHEMERIS storage
00004  * \author Sergi Segura, 2018. sergi.segura.munoz\(at\)gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_BEIDOU_DNAV_EPHEMERIS_H
00019 #define GNSS_SDR_BEIDOU_DNAV_EPHEMERIS_H
00020
00021 #include "gnss_ephemeris.h"
00022 #include <boost/serialization/nvp.hpp>
00023 #include <map>
00024 #include <string>
00025
00026 /** \addtogroup Core
00027  * \{ */
00028 /** \addtogroup System_Parameters
00029  * \{ */
00030
00031
00032 /*!
00033  * \brief This is a storage class for the Beidou SV ephemeris data as described in
00034  * BeiDou Navigation Satellite System Signal In Space Interface Control Document
00035  * Open Service Signal B1I (Version 3.0)
00036  *
00037  * See http://en.beidou.gov.cn/SYSTEMS/Officialdocument/201902/P020190227601370045731.pdf
00038  */
00039 class Beidou_Dnav_Ephemeris : public Gnss_Ephemeris
00040 {
00041 public:
00042     /*!
00043      * Default constructor
00044      */
00045     Beidou_Dnav_Ephemeris();
00046
00047     int SV_accuracy{}; //!< User Range Accuracy (URA) index of the SV (reference paragraph 5.2.4.5)
00048     for the standard positioning service user
00049     int SV_health{};
00050     double TGD1{}; //!< Estimated Group Delay Differential on B1I [s]
00051     double TGD2{}; //!< Estimated Group Delay Differential on B2I [s]
00052     double AODC{}; //!< Age of Data, Clock
00053     double AODE{}; //!< Age of Data, Ephemeris
00054     int AODO{}; //!< Age of Data Offset (AODO) term for the navigation message correction table
00055     (NMCT) contained in subframe 4 (reference paragraph 20.3.3.5.1.9) [s]
00056
00057     int sig_type{}; //!< BDS: data source (0:unknown,1:B1I,2:B1Q,3:B2I,4:B2Q,5:B3I,6:B3Q) */
00058     int nav_type{}; //!< BDS: nav type (0:unknown,1:IGSO/MEO,2:GEO) */
00059
00060     bool fit_interval_flag{}; //!< Curve-fit interval used by the CS (Block II/IIA/IIR/IIR-M/IIF) and
00061     SS (Block IIIA) in determining the ephemeris parameters, as follows: 0 = 4 hours, 1 = greater than 4
00062     hours.
00063     double spare1{};
00064     double spare2{};
00065
00066     /*! \brief If true, enhanced level of integrity assurance.
00067      *

```



```

00064      * If false, indicates that the conveying signal is provided with the
00065      * legacy level of integrity assurance. That is, the probability that the
00066      * instantaneous URE of the conveying signal exceeds 4.42 times the upper
00067      * bound value of the current broadcast URA index, for more than 5.2
00068      * seconds, without an accompanying alert, is less than 1E-5 per hour. If
00069      * true, indicates that the conveying signal is provided with an enhanced
00070      * level of integrity assurance. That is, the probability that the
00071      * instantaneous URE of the conveying signal exceeds 5.73 times the upper
00072      * bound value of the current broadcast URA index, for more than 5.2
00073      * seconds, without an accompanying alert, is less than 1E-8 per hour.
00074      */
00075      bool integrity_status_flag{};
00076      bool alert_flag{}; //!< If true, indicates that the SV URA may be worse than indicated in
d_SV_accuracy, use that SV at our own risk.
00077      bool antispoofing_flag{}; //!< If true, the AntiSpoofing mode is ON in that SV
00078
00079      std::map<int, std::string> satelliteBlock; //!< Map that stores to which block the PRN belongs
00080
00081      template <class Archive>
00082
00083      /*!
00084      * \brief Serialize is a boost standard method to be called by the boost XML
00085      * serialization. Here is used to save the ephemeris data on disk file.
00086      */
00087      void serialize(Archive& archive, const unsigned int version)
00088      {
00089          using boost::serialization::make_nvp;
00090          if (version)
00091          {
00092              };
00093
00094          archive& BOOST_SERIALIZATION_NVP (PRN);
00095          archive& BOOST_SERIALIZATION_NVP (M_0);
00096          archive& BOOST_SERIALIZATION_NVP (delta_n);
00097          archive& BOOST_SERIALIZATION_NVP (ecc);
00098          archive& BOOST_SERIALIZATION_NVP (sqrtA);
00099          archive& BOOST_SERIALIZATION_NVP (OMEGA_0);
00100          archive& BOOST_SERIALIZATION_NVP (i_0);
00101          archive& BOOST_SERIALIZATION_NVP (omega);
00102          archive& BOOST_SERIALIZATION_NVP (OMEGAdot);
00103          archive& BOOST_SERIALIZATION_NVP (idot);
00104          archive& BOOST_SERIALIZATION_NVP (Cuc);
00105          archive& BOOST_SERIALIZATION_NVP (Cus);
00106          archive& BOOST_SERIALIZATION_NVP (Crc);
00107          archive& BOOST_SERIALIZATION_NVP (Crs);
00108          archive& BOOST_SERIALIZATION_NVP (Cic);
00109          archive& BOOST_SERIALIZATION_NVP (Cis);
00110          archive& BOOST_SERIALIZATION_NVP (toe);
00111          archive& BOOST_SERIALIZATION_NVP (toc);
00112          archive& BOOST_SERIALIZATION_NVP (af0);
00113          archive& BOOST_SERIALIZATION_NVP (af1);
00114          archive& BOOST_SERIALIZATION_NVP (af2);
00115          archive& BOOST_SERIALIZATION_NVP (WN);
00116          archive& BOOST_SERIALIZATION_NVP (tow);
00117          archive& BOOST_SERIALIZATION_NVP (satClkDrift);
00118          archive& BOOST_SERIALIZATION_NVP (dtr);
00119
00120          archive& BOOST_SERIALIZATION_NVP (AODE);
00121          archive& BOOST_SERIALIZATION_NVP (SV_accuracy);
00122          archive& BOOST_SERIALIZATION_NVP (SV_health);
00123          archive& BOOST_SERIALIZATION_NVP (AODC);
00124          archive& BOOST_SERIALIZATION_NVP (TGD1);
00125          archive& BOOST_SERIALIZATION_NVP (TGD2);
00126          archive& BOOST_SERIALIZATION_NVP (sig_type);
00127          archive& BOOST_SERIALIZATION_NVP (nav_type);
00128          archive& BOOST_SERIALIZATION_NVP (AODO);
00129          archive& BOOST_SERIALIZATION_NVP (fit_interval_flag);
00130          archive& BOOST_SERIALIZATION_NVP (spare1);
00131          archive& BOOST_SERIALIZATION_NVP (spare2);
00132          archive& BOOST_SERIALIZATION_NVP (integrity_status_flag);
00133          archive& BOOST_SERIALIZATION_NVP (alert_flag);
00134          archive& BOOST_SERIALIZATION_NVP (antispoofing_flag);
00135      }
00136  };
00137
00138
00139  /** \} */
00140  /** \} */
00141  #endif // GNSS_SDR_BEIDOU_DNAV_EPHEMERIS_H

```

13.721 beidou_dnav_iono.h File Reference

Interface of a BEIDOU IONOSPHERIC MODEL storage.

```
#include "gps_iono.h"
```

Classes

- class [Beidou_Dnav_Iono](#)

This class is a storage for the BEIDOU IONOSPHERIC data as described in ICD v2.1.

13.721.1 Detailed Description

Interface of a BEIDOU IONOSPHERIC MODEL storage.

Author

Sergi Segura, 2018. [sergi.segura.munoz\(at\)gmail.com](mailto:sergi.segura.munoz(at)gmail.com)

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 Definition in file [beidou_dnav_iono.h](#).

13.722 beidou_dnav_iono.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file beidou_dnav_iono.h
00003  * \brief Interface of a BEIDOU IONOSPHERIC MODEL storage
00004  * \author Sergi Segura, 2018. sergi.segura.munoz\(at\)gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_BEIDOU_DNAV_IONO_H
00019 #define GNSS_SDR_BEIDOU_DNAV_IONO_H
00020
00021 #include "gps_iono.h"
00022
00023 /** \addtogroup Core
00024  * \{ */
00025 /** \addtogroup System_Parameters
00026  * \{ */
00027
00028
00029 /*!
00030  * \brief This class is a storage for the BEIDOU IONOSPHERIC data as described
00031  * in ICD v2.1
00032  */
00033 class Beidou_Dnav_Iono : public Gps_Iono
00034 {
00035 public:
00036     Beidou_Dnav_Iono() = default; //!< Default constructor
00037 };
00038
00039
00040 /** \} */
00041 /** \} */
00042 #endif // GNSS_SDR_BEIDOU_DNAV_IONO_H
```

13.723 beidou_dnav_navigation_message.h File Reference

Interface of a BeiDou DNAV Data message decoder.

```
#include "Beidou_B1I.h"
#include "Beidou_B3I.h"
#include "Beidou_DNAV.h"
```

```
#include "beidou_dnav_almanac.h"
#include "beidou_dnav_ephemeris.h"
#include "beidou_dnav_iono.h"
#include "beidou_dnav_utc_model.h"
#include <bitset>
#include <stdint>
#include <map>
#include <string>
#include <utility>
#include <vector>
```

Classes

- class [Beidou_Dnav_Navigation_Message](#)

This class decodes a BeiDou D1 NAV Data message.

13.723.1 Detailed Description

Interface of a BeiDou DNAV Data message decoder.

Author

Sergi Segura, 2018. [sergi.segura.munoz\(at\)gmail.com](mailto:sergi.segura.munoz(at)gmail.com)

Damian Miralles, 2018. dmiralles2009@gmail.com

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Definition in file [beidou_dnav_navigation_message.h](#).

13.724 beidou_dnav_navigation_message.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file beidou_dnav_navigation_message.h
00003  * \brief Interface of a BeiDou DNAV Data message decoder
00004  * \author Sergi Segura, 2018. sergi.segura.munoz(at)gmail.com
00005  * \author Damian Miralles, 2018. dmiralles2009@gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_BEIDOU_DNAV_NAVIGATION_MESSAGE_H
00020 #define GNSS_SDR_BEIDOU_DNAV_NAVIGATION_MESSAGE_H
00021
00022
00023 #include "Beidou_B1I.h"
00024 #include "Beidou_B3I.h"
00025 #include "Beidou_DNAV.h"
00026 #include "beidou_dnav_almanac.h"
00027 #include "beidou_dnav_ephemeris.h"
00028 #include "beidou_dnav_iono.h"
00029 #include "beidou_dnav_utc_model.h"
00030 #include <bitset>
00031 #include <stdint>
00032 #include <map>
00033 #include <string>
00034 #include <utility>
00035 #include <vector>
00036
00037 /** \addtogroup Core
00038  * \{ */
00039 /** \addtogroup System_Parameters
```

```

00040  * \{ */
00041
00042
00043  /*!
00044  * \brief This class decodes a BeiDou D1 NAV Data message
00045  */
00046  class Beidou_Dnav_Navigation_Message
00047  {
00048  public:
00049      /*!
00050       * Default constructor
00051       */
00052      Beidou_Dnav_Navigation_Message();
00053
00054      /*!
00055       * \brief Obtain a BDS SV Ephemeris class filled with current SV data
00056       */
00057      Beidou_Dnav_Ephemeris get_ephemeris() const;
00058
00059      /*!
00060       * \brief Obtain a BDS ionospheric correction parameters class filled with current SV data
00061       */
00062      Beidou_Dnav_Iono get_iono();
00063
00064      /*!
00065       * \brief Obtain a BDS UTC model parameters class filled with current SV data
00066       */
00067      Beidou_Dnav_Utc_Model get_utc_model();
00068
00069      /*!
00070       * \brief Decodes the BDS D1 NAV message
00071       */
00072      int32_t d1_subframe_decoder(std::string const& subframe);
00073
00074      /*!
00075       * \brief Decodes the BDS D2 NAV message
00076       */
00077      int32_t d2_subframe_decoder(std::string const& subframe);
00078
00079      /*!
00080       * \brief Computes the Coordinated Universal Time (UTC) and
00081       * returns it in [s]
00082       */
00083      double utc_time(double beidou_time_corrected) const;
00084
00085      bool satellite_validation();
00086
00087      /*!
00088       * \brief Returns true if new Ephemeris has arrived. The flag is set to false when the function is
00089       * executed
00090       */
00091      bool have_new_ephemeris();
00092
00093      /*!
00094       * \brief Returns true if new Iono model has arrived. The flag is set to false when the function
00095       * is executed
00096       */
00097      bool have_new_iono() const;
00098
00099      /*!
00100       * \brief Returns true if new UTC model has arrived. The flag is set to false when the function is
00101       * executed
00102       */
00103      bool have_new_utc_model();
00104
00105      /*!
00106       * \brief Sets satellite PRN number
00107       */
00108      inline void set_satellite_PRN(uint32_t prn)
00109      {
00110          i_satellite_PRN = prn;
00111      }
00112
00113      inline void set_signal_type(int32_t signal_type)
00114      {
00115          i_signal_type = signal_type;
00116      }
00117
00118      inline bool get_flag_CRC_test() const
00119      {
00120          return flag_crc_test;
00121      }
00122

```

```

00123     }
00124
00125     inline bool get_flag_new_SOW_available() const
00126     {
00127         return flag_new_SOW_available;
00128     }
00129
00130     inline void set_flag_new_SOW_available(bool new_SOW_available)
00131     {
00132         flag_new_SOW_available = new_SOW_available;
00133     }
00134
00135     inline double get_SOW() const
00136     {
00137         return d_SOW;
00138     }
00139
00140 private:
00141     uint64_t read_navigation_unsigned(const std::bitset<BEIDOU_DNAV_SUBFRAME_DATA_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00142     int64_t read_navigation_signed(const std::bitset<BEIDOU_DNAV_SUBFRAME_DATA_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00143     bool read_navigation_bool(const std::bitset<BEIDOU_DNAV_SUBFRAME_DATA_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00144     void print_beidou_word_bytes(uint32_t BEIDOU_word) const;
00145
00146     // broadcast orbit 1
00147     double d_SOW{}; // Time of BeiDou Week of the ephemeris set (taken from subframes SOW) [s]
00148     double d_SOW_SF1{}; // Time of BeiDou Week from HOW word of Subframe 1 [s]
00149     double d_SOW_SF2{}; // Time of BeiDou Week from HOW word of Subframe 2 [s]
00150     double d_SOW_SF3{}; // Time of BeiDou Week from HOW word of Subframe 3 [s]
00151     double d_SOW_SF4{}; // Time of BeiDou Week from HOW word of Subframe 4 [s]
00152     double d_SOW_SF5{}; // Time of BeiDou Week from HOW word of Subframe 5 [s]
00153
00154     double d_AODE{};
00155     double d_Crs{}; // Amplitude of the Sine Harmonic Correction Term to the Orbit Radius [m]
00156     double d_Delta_n{}; // Mean Motion Difference From Computed Value [semi-circles/s]
00157     double d_M_0{}; // Mean Anomaly at Reference Time [semi-circles]
00158
00159     // broadcast orbit 2
00160     double d_Cuc{}; // Amplitude of the Cosine Harmonic Correction Term to the Argument of
Latitude [rad]
00161     double d_eccentricity{}; // Eccentricity [dimensionless]
00162     double d_Cus{}; // Amplitude of the Sine Harmonic Correction Term to the Argument of
Latitude [rad]
00163     double d_sqrt_A{}; // Square Root of the Semi-Major Axis [sqrt(m)]
00164
00165     // broadcast orbit 3
00166     double d_Toe_sf2{}; // Ephemeris data reference time of week in subframe 2, D1 Message
00167     double d_Toe_sf3{}; // Ephemeris data reference time of week in subframe 3, D1 Message
00168     double d_Toe{}; // Ephemeris data reference time of week in subframe 1, D2 Message
00169     double d_Toc{}; // clock data reference time [s]
00170     double d_Cic{}; // Amplitude of the Cosine Harmonic Correction Term to the Angle of
Inclination [rad]
00171     double d_OMEGA0{}; // Longitude of Ascending Node of Orbit Plane at Weekly Epoch [semi-circles]
00172     double d_Cis{}; // Amplitude of the Sine Harmonic Correction Term to the Angle of Inclination
[rad]
00173
00174     // broadcast orbit 4
00175     double d_i_0{}; // Inclination Angle at Reference Time [semi-circles]
00176     double d_Crc{}; // Amplitude of the Cosine Harmonic Correction Term to the Orbit Radius [m]
00177     double d_OMEGA{}; // Argument of Perigee [semi-circles]
00178     double d_OMEGA_DOT{}; // Rate of Right Ascension [semi-circles/s]
00179
00180     // broadcast orbit 5
00181     double d_IDOT{}; // Rate of Inclination Angle [semi-circles/s]
00182     int32_t i_BEIDOU_week{}; // BeiDou week number, aka WN [week]
00183
00184     // broadcast orbit 6
00185     int32_t i_SV_accuracy{}; // User Range Accuracy (URA) index of the SV
00186     int32_t i_SV_health{};
00187     double d_TGD1{}; // Estimated Group Delay Differential in B1 [s]
00188     double d_TGD2{}; // Estimated Group Delay Differential in B2 [s]
00189     double d_AODC{}; // Age of Data, Clock
00190
00191     // broadcast orbit 7
00192     // int32_t i_AODO{}; // Age of Data Offset (AODO) term for the navigation message
correction table (NMCT) contained in subframe 4 (reference paragraph 20.3.3.5.1.9) [s]
00193
00194     // bool b_fit_interval_flag{}; // indicates the curve-fit interval used by the CS (Block
II/IIA/IIR/IIR-M/IIF) and SS (Block IIIA) in determining the ephemeris parameters, as follows: 0 = 4
hours, 1 = greater than 4 hours.
00195     // double d_spare1{};
00196     // double d_spare2{};
00197
00198     double d_A_f0{}; // Clock correction parameters. Coefficient 0 of code phase offset model [s]
00199     double d_A_f1{}; // Clock correction parameters. Coefficient 1 of code phase offset model [s/s]

```

```

00200     double d_A_f2{}; // Clock correction parameters. Coefficient 2 of code phase offset model [s/s^2]
00201
00202     // D2 NAV Message Decoding
00203     uint64_t d_A_f1_msb_bits{}; // Clock correction parameters, D2 NAV MSB
00204     uint64_t d_A_f1_lsb_bits{}; // Clock correction parameters, D2 NAV LSB
00205     uint64_t d_Cuc_msb_bits{}; // Amplitude of the Cosine Harmonic Correction Term to the
Argument of Latitude [rad]
00206     uint64_t d_Cuc_lsb_bits{}; // Amplitude of the Cosine Harmonic Correction Term to the
Argument of Latitude [rad]
00207     uint64_t d_eccentricity_msb{}; // Eccentricity [dimensionless]
00208     uint64_t d_eccentricity_lsb{}; // Eccentricity [dimensionless]
00209     uint64_t d_Cic_msb_bits{}; // Amplitude of the Cosine Harmonic Correction Term to the
Argument of Latitude [rad]
00210     uint64_t d_Cic_lsb_bits{}; // Amplitude of the Cosine Harmonic Correction Term to the
Argument of Latitude [rad]
00211     uint64_t d_eccentricity_msb_bits{}; // Eccentricity [dimensionless]
00212     uint64_t d_eccentricity_lsb_bits{};
00213     uint64_t d_i_0_msb_bits{}; // Inclination Angle at Reference Time [semi-circles]
00214     uint64_t d_i_0_lsb_bits{}; // Inclination Angle at Reference Time [semi-circles]
00215     uint64_t d_OMEGA_msb_bits{}; // Argument of Perigee [semi-circles]
00216     uint64_t d_OMEGA_lsb_bits{}; // Argument of Perigee [semi-circles]
00217     uint64_t d_OMEGA_DOT_msb_bits{}; // Rate of Right Ascension [semi-circles/s]
00218     uint64_t d_OMEGA_DOT_lsb_bits{}; // Rate of Right Ascension [semi-circles/s]
00219
00220     // Almanac
00221     // double d_Toa{}; // Almanac reference time [s]
00222     // int32_t i_WN_A{}; // Modulo 256 of the GPS week number to which the
almanac reference time (d_Toa) is referenced
00223     std::map<int32_t, int32_t> almanacHealth; // Map that stores the health information stored in the
almanac
00224
00225     std::map<int32_t, std::string> satelliteBlock; // Map that stores to which block the PRN belongs
00226
00227     // satellite identification info
00228     int32_t i_signal_type{}; // BDS: data source (0:unknown,1:B1I,2:B1Q,3:B2I,4:B2Q,5:B3I,6:B3Q)
00229     uint32_t i_satellite_PRN{};
00230
00231     // Ionospheric parameters
00232     double d_alpha0{}; // Coefficient 0 of a cubic equation representing the amplitude of the
vertical delay [s]
00233     double d_alphal{}; // Coefficient 1 of a cubic equation representing the amplitude of the
vertical delay [s/semi-circle]
00234     double d_alpha2{}; // Coefficient 2 of a cubic equation representing the amplitude of the
vertical delay [s(semi-circle)^2]
00235     double d_alpha3{}; // Coefficient 3 of a cubic equation representing the amplitude of the
vertical delay [s(semi-circle)^3]
00236     double d_beta0{}; // Coefficient 0 of a cubic equation representing the period of the model [s]
00237     double d_beta1{}; // Coefficient 1 of a cubic equation representing the period of the model
[s/semi-circle]
00238     double d_beta2{}; // Coefficient 2 of a cubic equation representing the period of the model
[s(semi-circle)^2]
00239     double d_beta3{}; // Coefficient 3 of a cubic equation representing the period of the model
[s(semi-circle)^3]
00240
00241     // UTC parameters
00242     double d_A1UTC{}; // 1st order term of a model that relates GPS and UTC time [s/s]
00243     double d_A0UTC{}; // Constant of a model that relates GPS and UTC time [s]
00244     int32_t i_DeltaT_LS{}; // delta time due to leap seconds [s]. Number of leap seconds since
6-Jan-1980 as transmitted by the GPS almanac.
00245     int32_t i_WN_LSF{}; // Week number at the end of which the leap second becomes effective
[weeks]
00246     int32_t i_DN{}; // Day number (DN) at the end of which the leap second becomes effective
[days]
00247     double d_DeltaT_LSF{}; // Scheduled future or recent past (relative to NAV message upload) value
of the delta time due to leap seconds [s]
00248     double d_A1GPS{};
00249     double d_A0GPS{};
00250     double d_A1GAL{};
00251     double d_A0GAL{};
00252     double d_A1GLO{};
00253     double d_A0GLO{};
00254
00255     double d_SQRT_A_ALMANAC{};
00256     double d_A1_ALMANAC{};
00257     double d_A0_ALMANAC{};
00258     double d_OMEGA0_ALMANAC{};
00259     double d_E_ALMANAC{};
00260     double d_DELTA_I{};
00261     double d_TOA{};
00262     double d_OMEGA_DOT_ALMANAC{};
00263     double d_OMEGA_ALMANAC{};
00264     double d_M0_ALMANAC{};
00265     int32_t almanac_WN{};
00266     double d_toa2{};
00267
00268     // System flags for data processing
00269     bool flag_eph_valid{};

```

```

00270     bool flag_utc_model_valid{};
00271     bool flag_iono_valid{};
00272     bool flag_dl_sf1{};
00273     bool flag_dl_sf2{};
00274     bool flag_dl_sf3{};
00275     bool flag_dl_sf4{};
00276     bool flag_dl_sf5{};
00277     bool flag_new_SOW_available{};
00278     bool flag_crc_test{};
00279     double d_previous_aode{};
00280
00281     // bool flag_dl_sf5_p7{}; // D1 NAV Message, Subframe 5, Page 09 decoded indicator
00282     // bool flag_dl_sf5_p8{}; // D1 NAV Message, Subframe 5, Page 09 decoded indicator
00283     bool flag_dl_sf5_p9{}; // D1 NAV Message, Subframe 5, Page 09 decoded indicator
00284     bool flag_dl_sf5_p10{}; // D1 NAV Message, Subframe 5, Page 10 decoded indicator
00285
00286     bool flag_sf1_p1{}; // D2 NAV Message, Subframe 1, Page 1 decoded indicator
00287     bool flag_sf1_p2{}; // D2 NAV Message, Subframe 1, Page 2 decoded indicator
00288     bool flag_sf1_p3{}; // D2 NAV Message, Subframe 1, Page 3 decoded indicator
00289     bool flag_sf1_p4{}; // D2 NAV Message, Subframe 1, Page 4 decoded indicator
00290     bool flag_sf1_p5{}; // D2 NAV Message, Subframe 1, Page 5 decoded indicator
00291     bool flag_sf1_p6{}; // D2 NAV Message, Subframe 1, Page 6 decoded indicator
00292     bool flag_sf1_p7{}; // D2 NAV Message, Subframe 1, Page 7 decoded indicator
00293     bool flag_sf1_p8{}; // D2 NAV Message, Subframe 1, Page 8 decoded indicator
00294     bool flag_sf1_p9{}; // D2 NAV Message, Subframe 1, Page 9 decoded indicator
00295     bool flag_sf1_p10{}; // D2 NAV Message, Subframe 1, Page 10 decoded indicator
00296 };
00297
00298
00299 /** \} */
00300 /** \} */
00301 #endif // GNSS_SDR_BEIDOU_DNAV_NAVIGATION_MESSAGE_H

```

13.725 beidou_dnav_utc_model.h File Reference

Interface of a BeiDou UTC MODEL storage.

```
#include <boost/serialization/nvp.hpp>
```

Classes

- class [Beidou_Dnav_Utc_Model](#)

This class is a storage for the BeiDou DNAV UTC Model.

13.725.1 Detailed Description

Interface of a BeiDou UTC MODEL storage.

Author

Damian Miralles, 2018. dmiralles2009@gmail.com

Sergi Segura, 2018. [sergi.segura.munoz\(at\)gmail.com](mailto:sergi.segura.munoz(at)gmail.com)

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Definition in file [beidou_dnav_utc_model.h](#).

13.726 beidou_dnav_utc_model.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file beidou_dnav_utc_model.h
00003  * \brief Interface of a BeiDou UTC MODEL storage
00004  * \author Damian Miralles, 2018. dmiralles2009@gmail.com
00005  * \author Sergi Segura, 2018. sergi.segura.munoz(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)

```

```

00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_BEIDOU_DNAV_UTC_MODEL_H
00020 #define GNSS_SDR_BEIDOU_DNAV_UTC_MODEL_H
00021
00022 #include <boost/serialization/nvp.hpp>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup System_Parameters
00027  * \{ */
00028
00029
00030 /*!
00031  * \brief This class is a storage for the BeiDou DNAV UTC Model.
00032  * \details Implementation follows the interface described in the Open Service Signal (Version 2.1)
00033  *
00034  */
00035 class Beidou_Dnav_Utc_Model
00036 {
00037 public:
00038     Beidou_Dnav_Utc_Model() = default;
00039
00040     // BeiDou UTC parameters
00041     double AO_UTC{};    //!< BDT clock bias relative to UTC [s]
00042     double AI_UTC{};    //!< BDT clock rate relative to UTC [s/s]
00043     int DeltaT_LS{};    //!< Delta time due to leap seconds before the new leap second effective
00044     int WN_LSF{};       //!< Week number of the new leap second
00045     int DN{};           //!< Day number of week of the new leap second
00046     double DeltaT_LSF{}; //!< Delta time due to leap seconds after the new leap second effective [s]
00047
00048     // BeiDou to GPS time corrections
00049     double AO_GPS{};    //!< BDT clock bias relative to GPS time [s]
00050     double AI_GPS{};    //!< BDT clock rate relative to GPS time [s/s]
00051
00052     // BeiDou to Galileo time corrections
00053     double AO_GAL{};    //!< BDT clock bias relative to GAL time [s]
00054     double AI_GAL{};    //!< BDT clock rate relative to GAL time [s/s]
00055
00056     // BeiDou to GLONASS time corrections
00057     double AO_GLO{};    //!< BDT clock bias relative to GLO time [s]
00058     double AI_GLO{};    //!< BDT clock rate relative to GLO time [s/s]
00059
00060     bool valid{};
00061
00062     template <class Archive>
00063     /*
00064      * \brief Serialize is a boost standard method to be called by the boost XML
00065      * serialization. Here is used to save the ephemeris data on disk file.
00066      */
00067     inline void serialize(Archive& archive, const unsigned int version)
00068     {
00069         if (version)
00070         {
00071             archive& BOOST_SERIALIZATION_NVP(AI_UTC);
00072             archive& BOOST_SERIALIZATION_NVP(AO_UTC);
00073             archive& BOOST_SERIALIZATION_NVP(DeltaT_LS);
00074             archive& BOOST_SERIALIZATION_NVP(WN_LSF);
00075             archive& BOOST_SERIALIZATION_NVP(DN);
00076             archive& BOOST_SERIALIZATION_NVP(DeltaT_LSF);
00077             archive& BOOST_SERIALIZATION_NVP(AO_GPS);
00078             archive& BOOST_SERIALIZATION_NVP(AI_GPS);
00079             archive& BOOST_SERIALIZATION_NVP(AO_GAL);
00080             archive& BOOST_SERIALIZATION_NVP(AI_GAL);
00081             archive& BOOST_SERIALIZATION_NVP(AO_GLO);
00082             archive& BOOST_SERIALIZATION_NVP(AI_GLO);
00083             archive& BOOST_SERIALIZATION_NVP(valid);
00084         }
00085     }
00086 };
00087
00088
00089 /** \} */
00090 /** \} */
00091 #endif // GNSS_SDR_BEIDOU_DNAV_UTC_MODEL_H

```

13.727 display.h File Reference

Defines useful display constants.


```
#include <string>
```

Macros

- `#define DISPLAY_COLORS 1`

Variables

- `const std::string TEXT_RESET = "\033[0m"`
- `const std::string TEXT_BLACK = "\033[30m"`
- `const std::string TEXT_RED = "\033[31m"`
- `const std::string TEXT_GREEN = "\033[32m"`
- `const std::string TEXT_YELLOW = "\033[33m"`
- `const std::string TEXT_BLUE = "\033[34m"`
- `const std::string TEXT_MAGENTA = "\033[35m"`
- `const std::string TEXT_CYAN = "\033[36m"`
- `const std::string TEXT_WHITE = "\033[37m"`
- `const std::string TEXT_BOLD_BLACK = "\033[1m\033[30m"`
- `const std::string TEXT_BOLD_RED = "\033[1m\033[31m"`
- `const std::string TEXT_BOLD_GREEN = "\033[1m\033[32m"`
- `const std::string TEXT_BOLD_YELLOW = "\033[1m\033[33m"`
- `const std::string TEXT_BOLD_BLUE = "\033[1m\033[34m"`
- `const std::string TEXT_BOLD_MAGENTA = "\033[1m\033[35m"`
- `const std::string TEXT_BOLD_CYAN = "\033[1m\033[36m"`
- `const std::string TEXT_BOLD_WHITE = "\033[1m\033[37m"`

13.727.1 Detailed Description

Defines useful display constants.

Author

Antonio Ramos, 2018. antonio.amos(at)cttc.es

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 Definition in file [display.h](#).

13.728 display.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file display.h
00003  * \brief Defines useful display constants
00004  * \author Antonio Ramos, 2018. antonio.amos(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_DISPLAY_H
00018 #define GNSS_SDR_DISPLAY_H
00019
00020 #include <string>
00021
00022 /** \addtogroup Core
00023  * \{ */
00024 /** \addtogroup System_Parameters
```

```

00025  * \{ */
00026
00027
00028 #ifndef NO_DISPLAY_COLORS
00029 #define DISPLAY_COLORS 1
00030 #endif
00031
00032
00033 #ifdef DISPLAY_COLORS
00034
00035 const std::string TEXT_RESET = "\033[0m";
00036 const std::string TEXT_BLACK = "\033[30m";
00037 const std::string TEXT_RED = "\033[31m";
00038 const std::string TEXT_GREEN = "\033[32m";
00039 const std::string TEXT_YELLOW = "\033[33m";
00040 const std::string TEXT_BLUE = "\033[34m";
00041 const std::string TEXT_MAGENTA = "\033[35m";
00042 const std::string TEXT_CYAN = "\033[36m";
00043 const std::string TEXT_WHITE = "\033[37m";
00044 const std::string TEXT_BOLD_BLACK = "\033[1m\033[30m";
00045 const std::string TEXT_BOLD_RED = "\033[1m\033[31m";
00046 const std::string TEXT_BOLD_GREEN = "\033[1m\033[32m";
00047 const std::string TEXT_BOLD_YELLOW = "\033[1m\033[33m";
00048 const std::string TEXT_BOLD_BLUE = "\033[1m\033[34m";
00049 const std::string TEXT_BOLD_MAGENTA = "\033[1m\033[35m";
00050 const std::string TEXT_BOLD_CYAN = "\033[1m\033[36m";
00051 const std::string TEXT_BOLD_WHITE = "\033[1m\033[37m";
00052
00053 #else
00054
00055 const std::string TEXT_RESET = "";
00056 const std::string TEXT_BLACK = "";
00057 const std::string TEXT_RED = "";
00058 const std::string TEXT_GREEN = "";
00059 const std::string TEXT_YELLOW = "";
00060 const std::string TEXT_BLUE = "";
00061 const std::string TEXT_MAGENTA = "";
00062 const std::string TEXT_CYAN = "";
00063 const std::string TEXT_WHITE = "";
00064 const std::string TEXT_BOLD_BLACK = "";
00065 const std::string TEXT_BOLD_RED = "";
00066 const std::string TEXT_BOLD_GREEN = "";
00067 const std::string TEXT_BOLD_YELLOW = "";
00068 const std::string TEXT_BOLD_BLUE = "";
00069 const std::string TEXT_BOLD_MAGENTA = "";
00070 const std::string TEXT_BOLD_CYAN = "";
00071 const std::string TEXT_BOLD_WHITE = "";
00072
00073 #endif // DISPLAY_COLORS
00074
00075
00076 /** \} */
00077 /** \} */
00078 #endif // GNSS_SDR_DISPLAY_H

```

13.729 galileo_almanac.h File Reference

Interface of a Galileo ALMANAC storage.

```
#include "gnss_almanac.h"
```

```
#include <boost/serialization/nvp.hpp>
```

Classes

- class [Galileo_Almanac](#)

This class is a storage for the Galileo SV ALMANAC data.

13.729.1 Detailed Description

Interface of a Galileo ALMANAC storage.

Author

Carles Fernandez, 2018. cfernandez(at)cttc.cat

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Definition in file [galileo_almanac.h](#).

13.730 galileo_almanac.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_almanac.h
00003  * \brief Interface of a Galileo ALMANAC storage
00004  * \author Carles Fernandez, 2018. cfernandez(at)cttc.cat
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GALILEO_ALMANAC_H
00019 #define GNSS_SDR_GALILEO_ALMANAC_H
00020
00021 #include "gnss_almanac.h"
00022 #include <boost/serialization/nvp.hpp>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup System_Parameters
00027  * \{ */
00028
00029
00030 /*!
00031 * \brief This class is a storage for the Galileo SV ALMANAC data
00032 */
00033 class Galileo_Almanac : public Gnss_Almanac
00034 {
00035 public:
00036     /*!
00037     * Default constructor
00038     */
00039     Galileo_Almanac()
00040     {
00041         this->System = 'E';
00042     };
00043
00044     int32_t IODa{};
00045     int32_t E5b_HS{};
00046     int32_t E1B_HS{};
00047     int32_t E5a_HS{};
00048
00049     template <class Archive>
00050
00051     void serialize(Archive& ar, const unsigned int version)
00052     {
00053         if (version)
00054         {
00055             ar& BOOST_SERIALIZATION_NVP (PRN);
00056             ar& BOOST_SERIALIZATION_NVP (delta_i);
00057             ar& BOOST_SERIALIZATION_NVP (toa);
00058             ar& BOOST_SERIALIZATION_NVP (WNa);
00059             ar& BOOST_SERIALIZATION_NVP (M_0);
00060             ar& BOOST_SERIALIZATION_NVP (ecc);
00061             ar& BOOST_SERIALIZATION_NVP (sqrtA);
00062             ar& BOOST_SERIALIZATION_NVP (OMEGA_0);
00063             ar& BOOST_SERIALIZATION_NVP (omega);
00064             ar& BOOST_SERIALIZATION_NVP (OMEGAdot);
00065             ar& BOOST_SERIALIZATION_NVP (af0);
00066             ar& BOOST_SERIALIZATION_NVP (af1);
00067             ar& BOOST_SERIALIZATION_NVP (IODa);
00068             ar& BOOST_SERIALIZATION_NVP (E5b_HS);
00069             ar& BOOST_SERIALIZATION_NVP (E1B_HS);
00070             ar& BOOST_SERIALIZATION_NVP (E5a_HS);
00071         }
00072     };
00073 };
00074
00075
00076 /** \} */
00077 /** \} */
00078 #endif // GNSS_SDR_GALILEO_ALMANAC_H

```

13.731 galileo_almanac_helper.h File Reference

Interface of a Galileo ALMANAC storage helper.

```
#include "galileo_almanac.h"
#include <cstdint>
```

Classes

- class [Galileo_Almanac_Helper](#)

This class is a storage for the GALILEO ALMANAC data as described in GALILEO ICD.

13.731.1 Detailed Description

Interface of a Galileo ALMANAC storage helper.

Author

Javier Arribas, 2013. jarribas(at)cttc.es

13.731.1.1 autotoc_md728

Author

Mara Branzanti 2013. mara.branzanti(at)gmail.com

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Definition in file [galileo_almanac_helper.h](#).

13.732 galileo_almanac_helper.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file galileo_almanac_helper.h
00003  * \brief Interface of a Galileo ALMANAC storage helper
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00005  * \author Mara Branzanti 2013. mara.branzanti(at)gmail.com
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_GALILEO_ALMANAC_HELPER_H
00018 #define GNSS_SDR_GALILEO_ALMANAC_HELPER_H
00019
00020 #include "galileo_almanac.h"
00021 #include <cstdint>
00022
00023 /** \addtogroup Core
00024  * \{ */
00025 /** \addtogroup System_Parameters
00026  * \{ */
00027
00028
00029 /*!
00030  * \brief This class is a storage for the GALILEO ALMANAC data as described in GALILEO ICD
00031  *
00032  * See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf
00033  * paragraph 5.1.10
00034  */
00035 class Galileo_Almanac_Helper
00036 {
00037 public:
00038     Galileo_Almanac_Helper() = default; //!< Default constructor
00039     Galileo_Almanac get_almanac(int i) const;
```

```

00040
00041 // Word type 7: Almanac for SVID1 (1/2), almanac reference time and almanac reference week number
00042 int32_t IOD_a_7{};
00043 int32_t WN_a_7{};
00044 int32_t t0a_7{};
00045 int32_t SVID1_7{};
00046 double DELTA_A_7{};
00047 double e_7{};
00048 double omega_7{};
00049 double delta_i_7{};
00050 double Omega0_7{};
00051 double Omega_dot_7{};
00052 double M0_7{};
00053
00054 // Word type 8: Almanac for SVID1 (2/2) and SVID2 (1/2)
00055 int32_t IOD_a_8{};
00056 double af0_8{};
00057 double af1_8{};
00058 int32_t E5b_HS_8{};
00059 int32_t E1B_HS_8{};
00060 int32_t E5a_HS_8{};
00061 int32_t SVID2_8{};
00062 double DELTA_A_8{};
00063 double e_8{};
00064 double omega_8{};
00065 double delta_i_8{};
00066 double Omega0_8{};
00067 double Omega_dot_8{};
00068
00069 // Word type 9: Almanac for SVID2 (2/2) and SVID3 (1/2)
00070 int32_t IOD_a_9{};
00071 int32_t WN_a_9{};
00072 int32_t t0a_9{};
00073 double M0_9{};
00074 double af0_9{};
00075 double af1_9{};
00076 int32_t E5b_HS_9{};
00077 int32_t E1B_HS_9{};
00078 int32_t E5a_HS_9{};
00079 int32_t SVID3_9{};
00080 double DELTA_A_9{};
00081 double e_9{};
00082 double omega_9{};
00083 double delta_i_9{};
00084
00085 // Word type 10: Almanac for SVID3 (2/2)
00086 int32_t IOD_a_10{};
00087 double Omega0_10{};
00088 double Omega_dot_10{};
00089 double M0_10{};
00090 double af0_10{};
00091 double af1_10{};
00092 int32_t E5b_HS_10{};
00093 int32_t E1B_HS_10{};
00094 int32_t E5a_HS_10{};
00095 };
00096
00097
00098 /** \} */
00099 /** \} */
00100 #endif // GNSS_SDR_GALILEO_ALMANAC_HELPER_H

```

13.733 Galileo_CNAV.h File Reference

Galileo CNAV message constants. Data from: Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022.

```

#include <cstdint>
#include <string>
#include <unordered_map>
#include <utility>

```

Functions

- const std::pair< int32_t, int32_t > **GALILEO_HAS_STATUS** ({1, 2})
- const std::pair< int32_t, int32_t > **GALILEO_HAS_RESERVED** ({3, 2})
- const std::pair< int32_t, int32_t > **GALILEO_HAS_MESSAGE_TYPE** ({5, 2})

- `const std::pair< int32_t, int32_t > GALILEO_HAS_MESSAGE_ID` ({7, 5})
- `const std::pair< int32_t, int32_t > GALILEO_HAS_MESSAGE_SIZE` ({12, 5})
- `const std::pair< int32_t, int32_t > GALILEO_HAS_MESSAGE_PAGE_ID` ({17, 8})
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_TOH` ({1, 12})
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_MASK_FLAG` ({13, 1})
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_ORBIT_CORRECTION_FLAG` ({14, 1})
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_CLOCK_FULLSET_FLAG` ({15, 1})
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_CLOCK_SUBSET_FLAG` ({16, 1})
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_CODE_BIAS_FLAG` ({17, 1})
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_PHASE_BIAS_FLAG` ({18, 1})
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_RESERVED` ({19, 4})
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_MASK_ID` ({23, 5})
- `const std::pair< int32_t, int32_t > GALILEO_MT1_HEADER_IOD_SET_ID` ({28, 5})

Variables

- `constexpr size_t HAS_MSG_NSYS_LENGTH` = 4
- `constexpr size_t HAS_MSG_ID_MASK_LENGTH` = 4
- `constexpr size_t HAS_MSG_SATELLITE_MASK_LENGTH` = 40
- `constexpr size_t HAS_MSG_SIGNAL_MASK_LENGTH` = 16
- `constexpr size_t HAS_MSG_NAV_MESSAGE_LENGTH` = 3
- `constexpr size_t HAS_MSG_MASK_RESERVED_LENGTH` = 6
- `constexpr size_t HAS_MSG_VALIDITY_INDEX_LENGTH` = 4
- `constexpr size_t HAS_MSG_IOD_GPS_LENGTH` = 8
- `constexpr size_t HAS_MSG_IOD_GAL_LENGTH` = 10
- `constexpr size_t HAS_MSG_DELTA_RADIAL_LENGTH` = 13
- `constexpr size_t HAS_MSG_DELTA_IN_TRACK_LENGTH` = 12
- `constexpr size_t HAS_MSG_DELTA_CROSS_TRACK_LENGTH` = 12
- `constexpr size_t HAS_MSG_DELTA_CLOCK_MULTIPLIER_LENGTH` = 2
- `constexpr size_t HAS_MSG_DELTA_CLOCK_CORRECTION_LENGTH` = 13
- `constexpr size_t HAS_MSG_NSYS_SUB_LENGTH` = 4
- `constexpr size_t HAS_MSG_ID_CLOCK_SUBSET_LENGTH` = 4
- `constexpr size_t HAS_MSG_DELTA_CLOCK_MULTIPLIER_SUBSET_LENGTH` = 2
- `constexpr size_t HAS_MSG_DELTA_CLOCK_CORRECTION_SUBSET_LENGTH` = 13
- `constexpr size_t HAS_MSG_CODE_BIAS_LENGTH` = 11
- `constexpr size_t HAS_MSG_PHASE_BIAS_LENGTH` = 11
- `constexpr size_t HAS_MSG_PHASE_DISCONTINUITY_INDICATOR_LENGTH` = 2
- `constexpr uint64_t MAX_SECONDS_REMEMBERING_MID` = 150
- `constexpr int32_t GALILEO_CNAV_SYMBOLS_PER_PAGE` = 1000
- `constexpr int32_t GALILEO_CNAV_PREAMBLE_PERIOD_SYMBOLS` = 1000
- `constexpr int32_t GALILEO_CNAV_PAGE_MS` = 1
- `constexpr int32_t GALILEO_CNAV_INTERLEAVER_ROWS` = 8
- `constexpr int32_t GALILEO_CNAV_INTERLEAVER_COLS` = 123
- `constexpr int32_t GALILEO_CNAV_TELEMETRY_RATE_BITS_SECOND` = 1000
- `constexpr int32_t GALILEO_CNAV_HAS_PAGE_DATA_BITS` = 448
- `constexpr int32_t GALILEO_CNAV_PAGE_RESERVED_BITS` = 14
- `constexpr int32_t GALILEO_CNAV_BYTES_FOR_CRC` = 58
- `constexpr int32_t GALILEO_CNAV_CRC_LENGTH` = 24
- `constexpr int32_t GALILEO_CNAV_MESSAGE_BITS_PER_PAGE` = 424
- `constexpr int32_t GALILEO_CNAV_PAGE_HEADER_BITS` = 24
- `constexpr int32_t GALILEO_CNAV_PREAMBLE_LENGTH_BITS` = 16
- `constexpr int32_t GALILEO_CNAV_MAX_NUMBER_SYMBOLS_ENCODED_BLOCK` = 255
- `constexpr int32_t GALILEO_CNAV_MT1_HEADER_BITS` = 32
- `constexpr int32_t GALILEO_CNAV_OCTETS_IN_SUBPAGE` = 53
- `constexpr int32_t GALILEO_CNAV_INFORMATION_VECTOR_LENGTH` = 32

- constexpr int32_t [GALILEO_CNAV_BITS_FOR_CRC](#) = GALILEO_CNAV_HAS_PAGE_DATA_BITS + GALILEO_CNAV_PAGE_RESERVED_BITS
- constexpr int32_t [HAS_MSG_NUMBER_MASK_IDS](#) = 32
- constexpr int32_t [HAS_MSG_NUMBER_GNSS_IDS](#) = 16
- constexpr int32_t [HAS_MSG_NUMBER_MESSAGE_IDS](#) = 32
- constexpr int32_t [HAS_MSG_NUMBER_SATELLITE_IDS](#) = 40
- constexpr int32_t [HAS_MSG_NUMBER_SIGNAL_MASKS](#) = 16
- constexpr float [HAS_MSG_DELTA_RADIAL_SCALE_FACTOR](#) = 0.0025
- constexpr float [HAS_MSG_DELTA_IN_TRACK_SCALE_FACTOR](#) = 0.008
- constexpr float [HAS_MSG_DELTA_CROSS_TRACK_SCALE_FACTOR](#) = 0.008
- constexpr float [HAS_MSG_DELTA_CLOCK_SCALE_FACTOR](#) = 0.0025
- constexpr float [HAS_MSG_CODE_BIAS_SCALE_FACTOR](#) = 0.02
- constexpr float [HAS_MSG_PHASE_BIAS_SCALE_FACTOR](#) = 0.01
- constexpr uint16_t [HAS_MSG_NUMBER_MAX_TOH](#) = 3599
- constexpr uint8_t [HAS_MSG_GPS_SYSTEM](#) = 0
- constexpr uint8_t [HAS_MSG_GALILEO_SYSTEM](#) = 2
- constexpr uint8_t [HAS_MSG_WRONG_SYSTEM](#) = 255
- constexpr char [GALILEO_CNAV_PREAMBLE](#) [17] = "1011011101110000"
- const std::unordered_map< uint8_t, std::unordered_map< uint8_t, std::string > > [HAS_SIGNAL_INDEX_TABLE](#)
- const std::unordered_map< uint8_t, uint16_t > [HAS_VALIDITY_INTERVALS](#)

13.733.1 Detailed Description

Galileo CNAV message constants. Data from: Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022.

Author

Carles Fernandez-Prades, 2020-2022. cfernandez(at)cttc.es

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 Definition in file [Galileo_CNAV.h](#).

13.734 Galileo_CNAV.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file Galileo_CNAV.h
00003  * \brief Galileo CNAV message constants. Data from:
00004  * Galileo High Accuracy Service Signal-In-Space Interface Control Document
00005  * (HAS SIS ICD) Issue 1.0, May 2022
00006  * \author Carles Fernandez-Prades, 2020-2022. cfernandez(at)cttc.es
00007  *
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_GALILEO_CNAV_H
00021 #define GNSS_SDR_GALILEO_CNAV_H
00022
00023 #include <cstdint>
00024 #include <string>
00025 #include <unordered_map>
00026 #include <utility>
00027
00028
00029 /** \addtogroup Core
00030  * \{
00031  /** \addtogroup System_Parameters

```

```

00032 * \{ */
00033
00034 // Galileo HAS message field lengths
00035 constexpr size_t HAS_MSG_NSYS_LENGTH = 4; // HAS SIS ICD 1.0 Table 15
00036 constexpr size_t HAS_MSG_ID_MASK_LENGTH = 4; // HAS SIS ICD 1.0 Table 16
00037 constexpr size_t HAS_MSG_SATELLITE_MASK_LENGTH = 40; // HAS SIS ICD 1.0 Table 16
00038 constexpr size_t HAS_MSG_SIGNAL_MASK_LENGTH = 16; // HAS SIS ICD 1.0 Table 16
00039 constexpr size_t HAS_MSG_NAV_MESSAGE_LENGTH = 3; // HAS SIS ICD 1.0 Table 16
00040 constexpr size_t HAS_MSG_MASK_RESERVED_LENGTH = 6; // HAS SIS ICD 1.0 Table 15
00041 constexpr size_t HAS_MSG_VALIDITY_INDEX_LENGTH = 4; // HAS SIS ICD 1.0 Table 22
00042 constexpr size_t HAS_MSG_IOD_GPS_LENGTH = 8; // HAS SIS ICD 1.0 Table 26
00043 constexpr size_t HAS_MSG_IOD_GAL_LENGTH = 10; // HAS SIS ICD 1.0 Table 26
00044 constexpr size_t HAS_MSG_DELTA_RADIAL_LENGTH = 13; // HAS SIS ICD 1.0 Table 25
00045 constexpr size_t HAS_MSG_DELTA_IN_TRACK_LENGTH = 12; // HAS SIS ICD 1.0 Table 25
00046 constexpr size_t HAS_MSG_DELTA_CROSS_TRACK_LENGTH = 12; // HAS SIS ICD 1.0 Table 25
00047 constexpr size_t HAS_MSG_DELTA_CLOCK_MULTIPLIER_LENGTH = 2; // HAS SIS ICD 1.0 Table 28
00048 constexpr size_t HAS_MSG_DELTA_CLOCK_CORRECTION_LENGTH = 13; // HAS SIS ICD 1.0 Table 31
00049 constexpr size_t HAS_MSG_NSYS_SUB_LENGTH = 4; // HAS SIS ICD 1.0 Table 32
00050 constexpr size_t HAS_MSG_ID_CLOCK_SUBSET_LENGTH = 4; // HAS SIS ICD 1.0 Table 32
00051 constexpr size_t HAS_MSG_DELTA_CLOCK_MULTIPLIER_SUBSET_LENGTH = 2; // HAS SIS ICD 1.0 Table 33
00052 constexpr size_t HAS_MSG_DELTA_CLOCK_CORRECTION_SUBSET_LENGTH = 13; // HAS SIS ICD 1.0 Table 34
00053 constexpr size_t HAS_MSG_CODE_BIAS_LENGTH = 11; // HAS SIS ICD 1.0 Table 37
00054 constexpr size_t HAS_MSG_PHASE_BIAS_LENGTH = 11; // HAS SIS ICD 1.0 Table 40
00055 constexpr size_t HAS_MSG_PHASE_DISCONTINUITY_INDICATOR_LENGTH = 2; // HAS SIS ICD 1.0 Table 40
00056
00057 constexpr uint64_t MAX_SECONDS_REMEMBERING_MID = 150; // HAS SIS ICD 1.0 Section 6.4.1 HAS Message
Completion Time-out
00058
00059 // Galileo CNAV message structure
00060 constexpr int32_t GALILEO_CNAV_SYMBOLS_PER_PAGE = 1000; // Total number of symbols per HAS page
including the sync pattern
00061 constexpr int32_t GALILEO_CNAV_PREAMBLE_PERIOD_SYMBOLS = 1000;
00062 constexpr int32_t GALILEO_CNAV_PAGE_MS = 1; // Duration in ms of a CNAV
page
00063 constexpr int32_t GALILEO_CNAV_INTERLEAVER_ROWS = 8; // HAS SIS ICD 1.0 Table 4
00064 constexpr int32_t GALILEO_CNAV_INTERLEAVER_COLS = 123; // HAS SIS ICD 1.0 Table 4
00065 constexpr int32_t GALILEO_CNAV_TELEMETRY_RATE_BITS_SECOND = 1000; // bps
00066 constexpr int32_t GALILEO_CNAV_HAS_PAGE_DATA_BITS = 448; // HAS SIS ICD 1.0 Table 5
00067 constexpr int32_t GALILEO_CNAV_PAGE_RESERVED_BITS = 14; // HAS SIS ICD 1.0 Table 5
00068 constexpr int32_t GALILEO_CNAV_BYTES_FOR_CRC = 58; // ceil(462 / 8)
00069 constexpr int32_t GALILEO_CNAV_CRC_LENGTH = 24; // HAS SIS ICD 1.0 Table 5
00070 constexpr int32_t GALILEO_CNAV_MESSAGE_BITS_PER_PAGE = 424; // HAS SIS ICD 1.0 Table 6
00071 constexpr int32_t GALILEO_CNAV_PAGE_HEADER_BITS = 24; // HAS SIS ICD 1.0 Table 6
00072 constexpr int32_t GALILEO_CNAV_PREAMBLE_LENGTH_BITS = 16; // HAS SIS ICD 1.0 Table 5
00073 constexpr int32_t GALILEO_CNAV_MAX_NUMBER_SYMBOLS_ENCODED_BLOCK = 255; // HAS SIS ICD 1.0 Section 6.2
Reed-Solomon Code
00074 constexpr int32_t GALILEO_CNAV_MT1_HEADER_BITS = 32; // HAS SIS ICD 1.0 Table 11
00075 constexpr int32_t GALILEO_CNAV_OCTETS_IN_SUBPAGE = 53; // HAS SIS ICD 1.0 Section 6.3
HAS Encoding and Transmission
00076 constexpr int32_t GALILEO_CNAV_INFORMATION_VECTOR_LENGTH = 32; // HAS SIS ICD 1.0 Section 6.2
Reed-Solomon Code
00077
00078 constexpr int32_t GALILEO_CNAV_BITS_FOR_CRC = GALILEO_CNAV_HAS_PAGE_DATA_BITS +
GALILEO_CNAV_PAGE_RESERVED_BITS; // 462
00079
00080 constexpr int32_t HAS_MSG_NUMBER_MASK_IDS = 32; // HAS SIS ICD 1.0 Table 13
00081 constexpr int32_t HAS_MSG_NUMBER_GNSS_IDS = 16; // HAS SIS ICD 1.0 Table 18
00082 constexpr int32_t HAS_MSG_NUMBER_MESSAGE_IDS = 32; // HAS SIS ICD 1.0 Table 8
00083 constexpr int32_t HAS_MSG_NUMBER_SATELLITE_IDS = 40; // HAS SIS ICD 1.0 Table 19
00084 constexpr int32_t HAS_MSG_NUMBER_SIGNAL_MASKS = 16; // HAS SIS ICD 1.0 Table 20
00085
00086 constexpr float HAS_MSG_DELTA_RADIAL_SCALE_FACTOR = 0.0025; // HAS SIS ICD 1.0 Table 25
00087 constexpr float HAS_MSG_DELTA_IN_TRACK_SCALE_FACTOR = 0.008; // HAS SIS ICD 1.0 Table 25
00088 constexpr float HAS_MSG_DELTA_CROSS_TRACK_SCALE_FACTOR = 0.008; // HAS SIS ICD 1.0 Table 25
00089 constexpr float HAS_MSG_DELTA_CLOCK_SCALE_FACTOR = 0.0025; // HAS SIS ICD 1.0 Table 31
00090 constexpr float HAS_MSG_CODE_BIAS_SCALE_FACTOR = 0.02; // HAS SIS ICD 1.0 Table 37
00091 constexpr float HAS_MSG_PHASE_BIAS_SCALE_FACTOR = 0.01; // HAS SIS ICD 1.0 Table 40
00092
00093 constexpr uint16_t HAS_MSG_NUMBER_MAX_TOH = 3599; // HAS SIS ICD 1.0 Table 13
00094
00095 constexpr uint8_t HAS_MSG_GPS_SYSTEM = 0; // HAS SIS ICD 1.0 Table 18
00096 constexpr uint8_t HAS_MSG_GALILEO_SYSTEM = 2; // HAS SIS ICD 1.0 Table 18
00097 constexpr uint8_t HAS_MSG_WRONG_SYSTEM = 255;
00098
00099 constexpr char GALILEO_CNAV_PREAMBLE[17] = "1011011101110000"; // HAS SIS ICD 1.0 Section 2.3.1
00100
00101 // HAS SIS ICD 1.0 Table 7
00102 const std::pair<int32_t, int32_t> GALILEO_HAS_STATUS({1, 2});
00103 const std::pair<int32_t, int32_t> GALILEO_HAS_RESERVED({3, 2});
00104 const std::pair<int32_t, int32_t> GALILEO_HAS_MESSAGE_TYPE({5, 2});
00105 const std::pair<int32_t, int32_t> GALILEO_HAS_MESSAGE_ID({7, 5});
00106 const std::pair<int32_t, int32_t> GALILEO_HAS_MESSAGE_SIZE({12, 5});
00107 const std::pair<int32_t, int32_t> GALILEO_HAS_MESSAGE_PAGE_ID({17, 8});
00108
00109 // HAS SIS ICD 1.0 Table 12
00110 const std::pair<int32_t, int32_t> GALILEO_MT1_HEADER_TOH({1, 12});
00111 const std::pair<int32_t, int32_t> GALILEO_MT1_HEADER_MASK_FLAG({13, 1});

```



```

00112 const std::pair<int32_t, int32_t> GALILEO_MT1_HEADER_ORBIT_CORRECTION_FLAG({14, 1});
00113 const std::pair<int32_t, int32_t> GALILEO_MT1_HEADER_CLOCK_FULLSET_FLAG({15, 1});
00114 const std::pair<int32_t, int32_t> GALILEO_MT1_HEADER_CLOCK_SUBSET_FLAG({16, 1});
00115 const std::pair<int32_t, int32_t> GALILEO_MT1_HEADER_CODE_BIAS_FLAG({17, 1});
00116 const std::pair<int32_t, int32_t> GALILEO_MT1_HEADER_PHASE_BIAS_FLAG({18, 1});
00117 const std::pair<int32_t, int32_t> GALILEO_MT1_HEADER_RESERVED({19, 4});
00118 const std::pair<int32_t, int32_t> GALILEO_MT1_HEADER_MASK_ID({23, 5});
00119 const std::pair<int32_t, int32_t> GALILEO_MT1_HEADER_IOD_SET_ID({28, 5});
00120
00121 // HAS SIS ICD v1.0 Table 20
00122 const std::unordered_map<uint8_t, std::unordered_map<uint8_t, std::string> HAS_SIGNAL_INDEX_TABLE = {
00123     {0, {
00124         {0, "L1 C/A"},
00125         {1, "Reserved"},
00126         {2, "Reserved"},
00127         {3, "L1C(D)"},
00128         {4, "L1C(P)"},
00129         {5, "L1C(D+P)"},
00130         {6, "L2 CM"},
00131         {7, "L2 CL"},
00132         {8, "L2 CM+CL"},
00133         {9, "L2 P"},
00134         {10, "Reserved"},
00135         {11, "L5 I"},
00136         {12, "L5 Q"},
00137         {13, "L5 I + L5 Q"},
00138         {14, "Reserved"},
00139         {15, "Reserved"},
00140     }},
00141     {2, {
00142         {0, "E1-B I/NAV OS"},
00143         {1, "E1-C"},
00144         {2, "E1-B + E1-C"},
00145         {3, "E5a-I F/NAV OS"},
00146         {4, "E5a-Q"},
00147         {5, "E5a-I+E5a-Q"},
00148         {6, "E5b-I I/NAV OS"},
00149         {7, "E5b-Q"},
00150         {8, "E5b-I+E5b-Q"},
00151         {9, "E5-I"},
00152         {10, "E5-Q"},
00153         {11, "E5-I + E5-Q"},
00154         {12, "E6-B C/NAV HAS"},
00155         {13, "E6-C"},
00156         {14, "E6-B + E6-C"},
00157         {15, "Reserved"},
00158     }}}};
00159
00160 // HAS SIS ICD v1.0 Table 23
00161 const std::unordered_map<uint8_t, uint16_t> HAS_VALIDITY_INTERVALS = {
00162     {0, 5},
00163     {1, 10},
00164     {2, 15},
00165     {3, 20},
00166     {4, 30},
00167     {5, 60},
00168     {6, 90},
00169     {7, 120},
00170     {8, 180},
00171     {9, 240},
00172     {10, 300},
00173     {11, 600},
00174     {12, 900},
00175     {13, 1800},
00176     {14, 3600}};
00177
00178
00179 /** \} */
00180 /** \} */
00181 #endif // GNSS_SDR_GALILEO_CNAV_H

```

13.735 galileo_cnav_message.h File Reference

Implementation of a Galileo CNAV Data message as described in Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022.

```

#include "Galileo_CNAV.h"
#include "galileo_has_page.h"
#include <bitset>
#include <stdint>
#include <string>
#include <utility>

```

Classes

- class [Galileo_Cnav_Message](#)

This class handles the Galileo CNAV Data message, as described in the Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022.

13.735.1 Detailed Description

Implementation of a Galileo CNAV Data message as described in Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022.

Author

Carles Fernandez-Prades, 2020-2022 cfernandez(at)cttc.es

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Definition in file [galileo_cnav_message.h](#).

13.736 galileo_cnav_message.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file galileo_cnav_message.h
00003  * \brief Implementation of a Galileo CNAV Data message as described in
00004  * Galileo High Accuracy Service Signal-In-Space Interface Control Document
00005  * (HAS SIS ICD) Issue 1.0, May 2022
00006  * \author Carles Fernandez-Prades, 2020-2022 cfernandez(at)cttc.es
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GALILEO_CNAV_MESSAGE_H
00020 #define GNSS_SDR_GALILEO_CNAV_MESSAGE_H
00021
00022 #include "Galileo_CNAV.h"
00023 #include "galileo_has_page.h"
00024 #include <bitset>
00025 #include <cstdint>
00026 #include <string>
00027 #include <utility>
00028
00029 /** \addtogroup Core
00030  * \{ */
00031 /** \addtogroup System_Parameters
00032  * \{ */
00033
00034
00035 /*!
00036  * \brief This class handles the Galileo CNAV Data message, as described in the
00037  * Galileo High Accuracy Service Signal-In-Space Interface Control Document
00038  * (HAS SIS ICD) Issue 1.0, May 2022
00039  */
00040 class Galileo_Cnav_Message
00041 {
00042 public:
00043     Galileo_Cnav_Message() = default;
00044
00045     void read_HAS_page(const std::string& page_string);
00046
00047     inline bool is_HAS_in_test_mode() const
00048     {
00049         return d_test_mode;
00050     }
00051
00052     inline bool is_HAS_page_dummy() const
00053     {
```

```

00054         return d_page_dummy;
00055     }
00056
00057     inline bool have_new_HAS_page() const
00058     {
00059         return d_new_HAS_page;
00060     }
00061
00062     inline Galileo_HAS_page get_HAS_encoded_page() const
00063     {
00064         return has_page;
00065     }
00066
00067     inline bool get_flag_CRC_test() const
00068     {
00069         return d_flag_CRC_test;
00070     }
00071
00072     inline void set_time_stamp(uint64_t time_stamp)
00073     {
00074         has_page.time_stamp = time_stamp;
00075     }
00076
00077     inline void set_tow(uint32_t tow)
00078     {
00079         has_page.tow = tow;
00080     }
00081
00082 private:
00083     uint8_t read_has_page_header_parameter(const std::bitset<GALILEO_CNAV_PAGE_HEADER_BITS>& bits,
00084     const std::pair<int32_t, int32_t>& parameter) const;
00085     bool CRC_test(const std::bitset<GALILEO_CNAV_BITS_FOR_CRC>& bits, uint32_t checksum) const;
00086     void read_HAS_page_header(const std::string& page_string);
00087
00088     Galileo_HAS_page has_page{};
00089
00089     uint8_t d_has_page_status{};
00090     uint8_t d_has_reserved{};
00091     uint8_t d_received_message_page_id{};
00092     uint8_t d_received_message_type{};
00093     uint8_t d_received_message_id{};
00094     uint8_t d_received_message_size{};
00095
00096     bool d_test_mode{};
00097     bool d_flag_CRC_test{};
00098     bool d_page_dummy{};
00099     bool d_new_HAS_page{};
00100 };
00101
00102
00103 /** \} */
00104 /** \} */
00105 #endif // GNSS_SDR_GALILEO_CNAV_MESSAGE_H

```

13.737 Galileo_E1.h File Reference

Defines system parameters for Galileo E1 signal and NAV data.

```

#include "MATH_CONSTANTS.h"
#include "gnss_frequencies.h"
#include <cstdint>
#include <cstdint>

```

Variables

- constexpr double [GALILEO_E1_FREQ_HZ](#) = [FREQ1](#)
Galileo E1 carrier frequency [Hz].
- constexpr double [GALILEO_E1_CODE_CHIP_RATE_CPS](#) = 1.023e6
Galileo E1 code rate [chips/s].
- constexpr double [GALILEO_E1_CODE_PERIOD_S](#) = 0.004
Galileo E1 code period [s].
- constexpr double [GALILEO_E1_SUB_CARRIER_A_RATE_HZ](#) = 1.023e6
Galileo E1 sub-carrier 'a' rate [Hz].
- constexpr double [GALILEO_E1_SUB_CARRIER_B_RATE_HZ](#) = 6.138e6

- Galileo E1 sub-carrier 'b' rate [Hz].*
- constexpr double `GALILEO_E1_B_CODE_LENGTH_CHIPS` = 4092.0
- Galileo E1-B code length [chips].*
- constexpr double `GALILEO_E1_B_SYMBOL_RATE_BPS` = 250.0
- Galileo E1-B symbol rate [bits/second].*
- constexpr uint32_t `GALILEO_E1_CODE_PERIOD_MS` = 4
- Galileo E1 code period [ms].*
- constexpr int32_t `GALILEO_E1_B_SAMPLES_PER_SYMBOL` = 1
- (Galileo_E1_CODE_CHIP_RATE_HZ / Galileo_E1_B_CODE_LENGTH_CHIPS) / Galileo_E1_B_SYMBOL_RATE_BPS*
- constexpr int32_t `GALILEO_E1_C_SECONDARY_CODE_LENGTH` = 25
- Galileo E1-C secondary code length [chips].*
- constexpr int32_t `GALILEO_E1_NUMBER_OF_CODES` = 50
- constexpr uint32_t `GALILEO_E1_OPT_ACQ_FS_SPS` = 2000000
- Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.*
- constexpr int32_t `GALILEO_E1_HISTORY_DEEP` = 100
- Observable history length for interpolation.*
- constexpr char `GALILEO_E1_C_SECONDARY_CODE` [26] = "0011100000001010110110010"
- constexpr size_t `GALILEO_E1_B_PRIMARY_CODE_STR_LENGTH` = 1023
- constexpr char `GALILEO_E1_B_PRIMARY_CODE` [GALILEO_E1_NUMBER_OF_CODES][1024]
- constexpr size_t `GALILEO_E1_C_PRIMARY_CODE_STR_LENGTH` = 1023
- constexpr char `GALILEO_E1_C_PRIMARY_CODE` [GALILEO_E1_NUMBER_OF_CODES][1024]

13.737.1 Detailed Description

Defines system parameters for Galileo E1 signal and NAV data.

Author

Luis Esteve, 2012. luis(at)epsilon-formacion.com

Mara Branzanti 2013. mara.branzanti(at)gmail.com

Javier Arribas 2013. jarribas(at)cttc.es

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 Definition in file [Galileo_E1.h](#).

13.738 Galileo_E1.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file Galileo_E1.h
00003  * \brief Defines system parameters for Galileo E1 signal and NAV data
00004  * \author Luis Esteve, 2012. luis(at)epsilon-formacion.com
00005  * \author Mara Branzanti 2013. mara.branzanti(at)gmail.com
00006  * \author Javier Arribas 2013. jarribas(at)cttc.es
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GALILEO_E1_H
00020 #define GNSS_SDR_GALILEO_E1_H
00021
00022 #include "MATH_CONSTANTS.h"
00023 #include "gnss_frequencies.h"
00024 #include <cstdint> // for size_t

```

```
00025 #include <stdint>
00026
00027 /** \addtogroup Core
00028 * \{ */
00029 /** \addtogroup System_Parameters
00030 * \{ */
00031
00032
00033 // carrier and code frequencies
00034 constexpr double GALILEO_E1_FREQ_HZ = FREQ1;          //!< Galileo E1 carrier frequency [Hz]
00035 constexpr double GALILEO_E1_CODE_CHIP_RATE_CPS = 1.023e6;  //!< Galileo E1 code rate [chips/s]
00036 constexpr double GALILEO_E1_CODE_PERIOD_S = 0.004;        //!< Galileo E1 code period [s]
00037 constexpr double GALILEO_E1_SUB_CARRIER_A_RATE_HZ = 1.023e6;  //!< Galileo E1 sub-carrier 'a' rate
00038                                     [Hz]
00039                                     [Hz]
00039 constexpr double GALILEO_E1_SUB_CARRIER_B_RATE_HZ = 6.138e6;  //!< Galileo E1 sub-carrier 'b' rate
00040                                     [Hz]
00040 constexpr double GALILEO_E1_B_CODE_LENGTH_CHIPS = 4092.0;      //!< Galileo E1-B code length [chips]
00041 constexpr double GALILEO_E1_B_SYMBOL_RATE_BPS = 250.0;        //!< Galileo E1-B symbol rate
00042                                     [bits/second]
00041 constexpr uint32_t GALILEO_E1_CODE_PERIOD_MS = 4;            //!< Galileo E1 code period [ms]
00042 constexpr int32_t GALILEO_E1_B_SAMPLES_PER_SYMBOL = 1;        //!< (Galileo_E1_CODE_CHIP_RATE_HZ /
00043                                     Galileo_E1_B_CODE_LENGTH_CHIPS) / Galileo_E1_B_SYMBOL_RATE_BPS
00043 constexpr int32_t GALILEO_E1_C_SECONDARY_CODE_LENGTH = 25;    //!< Galileo E1-C secondary code length
00044                                     [chips]
00044 constexpr int32_t GALILEO_E1_NUMBER_OF_CODES = 50;
00045
00046
00047 // optimum parameters
00048 constexpr uint32_t GALILEO_E1_OPT_ACQ_FS_SPS = 2000000;      //!< Sampling frequency that maximizes the
00049                                     acquisition SNR while using a non-multiple of chip rate
00050
00050 constexpr int32_t GALILEO_E1_HISTORY_DEEP = 100;             //!< Observable history length for interpolatlon
00051
00052 constexpr char GALILEO_E1_C_SECONDARY_CODE[26] = "0011100000001010110110010";
00053
00054 // Galileo E1 primary codes
00055 constexpr size_t GALILEO_E1_B_PRIMARY_CODE_STR_LENGTH = 1023;
00056 constexpr char GALILEO_E1_B_PRIMARY_CODE[GALILEO_E1_NUMBER_OF_CODES][1024] = {
00057     "F5D710130573541B9DBD4FD9E9B20A0D59D144C54BC7935539D2E75810FB51E494093A0A19"
00058     "DD79C70C5A98E5657AA578097777E86BCC4651CC72F2F974DC766E07AEA3D0B557EF42FF57"
00059     "E6A58E805358CE9257669133B18F08FDBDFB38C5524C7FB1DE079842482990DF58F72321D9"
00060     "201F8979EAB159B2679C9E95AA6D53456C0DF75C2B4316D1E2309216882854253A1FA60CA2"
00061     "C94ECE013E2A8C943341E7D9E5A8464B3AD407E0AE465C3E3DD1BE60A8C3D50F831536401E"
00062     "776BE02A6042FC4A27AF653F0FCFC4D4013F115310788D68CAEAD3ECCCC5330587EB3C22A1"
00063     "459FC8E6FCC9DE849A5205E70C6D66D125814D698DD0EEBFEEAE52CC65C5C84EEDF207379"
00064     "000E169D318426516AC5D1C31F2E18A65E07AE6E33FDD724B13098B3A444688389EFBBB5EE"
00065     "AB588742B083B679D42FB26FF77919EAB21DE0389D9997498F967AE05AF0F4C7E177416E1"
00066     "8C4D5E6987ED3590690AD127D872F14A8F4903A12329732A9768F82F295BEE391879293E3A"
00067     "97D51435A7F03ED7FBE275F102A83202DC3DE94AF4C712E9D006D182693E9632933E6EB773"
00068     "880CF147B922E74539E4582F79E39723B4C80E42EDCE4C08A8D02221BAE6D17734817D5B53"
00069     "1C0D3C1AE723911F3FFF6AAC02E97FEA69E376AF4761E6451CA61FDB2F9187642EFC63A09"
00070     "AAB680770C1593EEDD4FF4293BFFD6DD2C3367E85B14A654C834B6699421A", // PRN 01
00071     "96B856A629F581D1344FEF597835FE60434625D077ECF0D95FBE1155EA0431979E5AFF544A"
00072     "F591A332FDAEF98AB1EDD847A73F3AF15AAEE7E9A05C9D82C59EC325EF4CF264B8ADF2A8E8"
00073     "BA459354CB4B415C50BF239ADBC31B3A9C87B0843CF3B9E6D646BA43F866276B053826F3A"
00074     "2334CC5E2EFB9F8F195B382E75EEA63F58A06B3F82A3B5C77C1800FD9498F803E524435B32"
00075     "1210BB84690BED0BBE16D363B3A90656A73720E27008852FB7DACC8284411B177728D9527"
00076     "C560859084A395A6F11A96AD9DB6B43E00642B000ED12BFD967868EAB1108552CD4FC89FBC"
00077     "408ACE7678C381EC91DD000319124EB5D5EF52C4CAC9AADEE2FA045C16CE492D7F43743CA7"
00078     "7924C78696FCBF2F9F7F36D8E623752200C6FCBBD71ABBB6877F3C5D6E6740AB0389458A6B"
00079     "66440858B2D38244E853646FE2714211DEA9E6196252815BB704A20BFE556AC474F899894"
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00081     "8B478F3BB5D33AD2A9FA24AD7B8FA895FDBC04964192F7BA3FF74E0E3A435B5DFE042E3115"
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00083     "2C960E5ACE418D43770DF3B681F2B318F6F8E1CB17C2857350FB6009AED665E13B2780D792"
00084     "17F73FAC7A8A4B048DB0FB8A8A5007CDDC9A7B2DA8257C99F1CB605A18204", // PRN 02
00085     "E57DE19A3EA4A8C122FCB1DD6584B3D2DAE364D800F9C5A9E957B38F624CBD3ACC58FA3ED07"
00086     "0B5E44857CCB813FBC0BB83B5D157C6C562422E5963CC4DD753C45B0264F8E136A0F1774D7"
00087     "7A543E44D51EF8C6B9408B6E3B5CEE1347A94F13ECD94DC764976E5A50B4CB0AE7557553B"
00088     "7EDFE03EC2CD32EA8D125A341E1EDFC77E75330D6E7B23DC838EBCE7E5567F5B8C80C3D15"
00089     "E7404B4E10F0BEB0C69626A814AF91334199864FC77E0FF548DC2A6FA6A71C3C0561F2B085"
00090     "CC05E8512E27B9DBA60B93D114B87935776C8E9A67905C429D48BF3AB1B0A56FAFBFD5D9C8"
00091     "D8C8A9E5918BFF273CF5E8664FF2B90314BDBFDAD5AB8C22A0E45C104ECE75EA43FE9BDC3"
00092     "06A5A28AE464628163D249D8056005F1A900951808CC8620F81768153436F741667A8E271D"
00093     "D986C7A1E5046FCC74C7CEBBF9A1296D6CF0B2FF85BE412D87214BB368DFF462AD649D7324"
00094     "A117252311C664D33E4DAFBD830FBCEB6E6FDD7391D4BADA7A775FD1949D981F619655DB3C"
00095     "22BAC34E5AE4122905C0C7E80D6EA28471EC0468756531C09A471EDBE200472E78F1701FE"
00096     "E96E5769A9893C0F11E7906B064442E06E21ED8B0D70AF288690C532A2D03B373E1E0085F6"
00097     "2F7AAA658B569C5184E3DDC40ECAA88B887118601691892F9F55E2DE79E49DF11D434C2A6"
00098     "3AA6447522A7C99DC215CAD2ED0114ED62CBDAE9D315E48AE14D2014B7F8E", // PRN 03
00099     "C0FC4C72A12023BA7093C86775DF3D2F42C7CEDE616876340BE4301361B9DC9DFF4F1DEC6A"
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00101     "10E386FA7DB9FCFCDAF2B6AFBA46A8A299153B4E11582FBA7F28F0A9F9DE41830AB333506"
00102     "2C57D81DC361EDFE491939100FC827F36273760043D1C35B74E36C6C4DBE1D307847D55AC0"
00103     "7D8B212C2DBA632A86AB15BD0FAFFA43070644C7E50623195A3796AA8E8D6E4E964FA0E448"
00104     "8A500B9063FBBFB1204A0E33C6CF2879AC2BA7C86CAB57E3E8A497836194E65C5C39B950F1"
00105     "AFC3B58E850A5EC39F4190D55351D16529CD52B36DF4A2DC68EE202BB758CF19C54B0E1461"
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00106 "D547B5D06C2F9DC09C2B15458C3140860E4C6F3FE4F417FDFCCEDE00F71212EE137E6669E56"
00107 "9A7845470CA564F85CB4772808D65D2B48D409B709BD7AC5F7E28AA804CE9DAC3ABB5A5B76"
00108 "8C6A184B5A974E933F2C1772FF64AB26BA2D5A165744E314EFB2238AC4858A8B82723DAE88"
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00110 "3935670BCFF71C2EC04CCB98943786173C309E75A02BB78A788A5E6F8A8F407E57B8403841A"
00111 "9E1FCB3A7A880D1F6529770E52C173E2C47EDED4400D5E665E325ED845C9E8D0E66FDA16B1"
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00113 "EA9596357B343DFC31D5875CC0E94117A33651472E476D3892D8112EB6CB6E0151D409C5A5"
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00115 "B066F7B2DBB7307FB44F726DD2F368A5FDBE75BA7248762E1EC7E4589DF1A353A16D6B3CAC"
00116 "1C9ACDB89890ED2C4F44AFEFC763DB51D102230C37E1ED0943CD6F4176B2F5C19119588911"
00117 "ACF81A7A29320AD579C1BFAED1A70DEE1B87037138ADE411E0BB92F5B3148DFA11F2F84CA6"
00118 "C019124B922837503AA9823A97E443A66378D5CB3130A7EC9B05670E85D095D5E6F603092C"
00119 "632E51FD9013FE7FB9F08448FD09F1219A4744CDAF82BF9C60039C8185C7E9559FCE301C6D"
00120 "3F46A2E514AAD44D3889C8CB4ED747019194F2644363770F8BBD0AE92B6F5F43CBB5"
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00122 "3B4A9E301CEEEB978050AD9A9E410091AD29E389829E2F24BE1E3B24F4540C4A6533EBA72E"
00123 "8AD5408AAEA43ACB82F971F3A51DD77FE9E1956E2EE7553E050A1D10B99552DD5B68F2E28"
00124 "59712835BD2AD6B08881753B4833FB04740E3364D2CD4921B939393E7EA91B854FA1E5A8EE"
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00127 "90E92279CD4F60D98F6E8FCB3E9263DB60FAB146A835AAC2E96B3BE3FF07119032DEE0521C"
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00129 "F6207BE9F6CFC971D5EA11781AC2DA25DBEEB6B903EF8BB0AC0CD2E29F94B8CB67874A7B74"
00130 "41045758E09EA061181A50E0AB7BCCF801554E0644780BC137436E3FB7784C182856A790D6"
00131 "943BB53DB40D13D6A2F7B83A5C521073883B90FB8DB1C0F954D132943C09156A09984B8220"
00132 "79FB8F09AEB4307C1D6336C7CEAE8CC3162760B9838CA6A38FD0044FDF099E416D57BF9F33A5"
00133 "51043F34EBF9BAA90901E62D2D981065F977852072F692535DDE24EE8946387B4E5B0FEFEB"
00134 "D75552C1FC325A608A78079A9AC864F2F30010A3304CB16A26AF98D9BFD3B8D128541190B2"
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00140 "D2BCDCFCCEA46301E7D99A5AF7199155772E92BAD85F35EDB656F0999EE828", // PRN 06
00141 "A91F570102961D62CA6CB55144AFCCEAF3910F3336DCB029CDCBA164ADA72732771B6ECD1C"
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00144 "E27BC8D6768FEC5D268119EB9E965260FE1F5C56AEF60A8622CDA8C42F24CBA7F5B07A7416"
00145 "917277323314AFD3ECD10F74BEE7B22DC760EFA7F935FC9963411353782547FAEED32E69A4"
00146 "FB5756C1A73CCDFFEDE50F4B2D9B5D2ED5C59C9A52D80CD27B989B8DAA14C569E763C08FD4"
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00154 "D4E61750C13E8A3AD48FE1F89F201C288A8F443867C2BAC23C706EE7A2D2C", // PRN 07
00155 "C6E00978E351164532EEA256ECBE0D4F8FCE02A276BD19666DE93936F7A242FC4C7E879791"
00156 "3148043ABF1D5F9B0036ED22AA92028C800C4D62BD6640431170EA77311865074D670AF284"
00157 "7AA47CB94584A793FA82F51574BD7C62BF14386F14A3D7DBD129FDE64EAD67EB35D5E13FF2"
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00169 "821BBB3FB91E50253A9E71AC379ED57AEF394C2CC59587B2D0337CE74002EEAD17AB5D504B"
00170 "CA68BD4E9061C3DBAE2985EBE292B9BEC9D3542015225F44ED3C2C3FFB036A515BF33DA169"
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00195 "F633C7DB1C826AA9E1C1309E5B14A0DDDB79714DFDCB52221CEAD7E8A140DF7806F1271564"
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00197 "AFA7FBAC93326D0C36A388831B99DF4D527BCE7C9070F7B46B5FFCDEB07384801AE5F86A89"
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00199 "CEA42A5E9EA1BE3497C0A5BA9121DB97F64159AAC78E62D7DEFF3BF4CF73F8CFBE045C9D39"
00200 "E41D5D208DCC4B47CA27E900C3CD8FD1408DC5E0F5114F2FE65817D37CD1452C4967ACAA21"
00201 "19FB8D60E5E2FD8A820D0AADD88B94D40435C095568AE6394D3B97C835BA868A83083316C4"
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00384 "3BC3E9A86DC39AFA1818B9533EDE72FDAF021E2C9B7D6C74E49B849F372B1A131F4C532DBE"
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00535 "4E5C569A1E09C38A062B601F920EF4D957F4BCA8E329123BD6FDC3B731361864CC139EBE3"
00536 "C68FEDF040FB127D9D1DC071DFA1552ABC670349A632AA1314984A2D4B7A8BB32C555B79D"
00537 "EE013A66745AE15E8E5E4E129E44A119203425F2ABF1F03CE9CB33C0BDC3285ADFAAF4D7B5"
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00625 "FF71868F50855054085AA1B7CA3309581532D658C7D2D6069C3B44E0E3CDE45222DD9EB40C"
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00696 "8ADD1009A5126362B0B4F1FFDDAB4A00AD8290EB84F76AA345DD73FFFF7733035026E3CC1D9"
00697 "9428BC68ADE8B8CBE98E4A630F99F4F33E8AB66895AE7435D2E84EAC95CF19E9B440373EC0B"
00698 "4D4B2CFA6D72C7FE1FE8CE5F34F55B016F8B115FAD6CC7B53DA7555E67672FBF6BDE324AA0"
00699 "9FA18F13D9FF1041A12B04F30304774B07659F397554E66CA589D9D9F1F262CF659F718CA7"
00700 "F443B8331BDEA8C3980045562D909EA44E917FF5D47812A0390139B2A87D0", // PRN 46
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00703 "4DD8E7943ECDDA318C4B92B57B14EB0F8EB250686CE129BBB2B18EBE7FF53C9DA9C0B664C"
00704 "527A3C69D905CC6FAE8BEB7A7D83294C1656DA4B8308968EE49DDDC2D0C71A17B02053027D"
00705 "7DB8F4E77E3AD1C80FFDBD37938876B671D80E99F5F1C7BAEF50B7E05CC0CAB8979A3A2A85"
00706 "2A7018673292CDBCECAAB74B839FD3C08468235A75A14E431C1F25E34850FBC779285854F"
00707 "C6AFDCFB7B7749E0DFFF5F93A8AC146C873B407F2CD6CCB461312AE35DEE8D6D51347B0824"
00708 "156DDD60762807A5C132C0667FBBCA7489058C47A156B2A50CA5C24B894C1EE7C44B871791"
00709 "76905B7657A8E95AF7F2EA6C6D2A12384CAC9E6D14253DC5C31BB8FDD2462581C109D2DAF7"
00710 "2238E46B3F436DFD7D5571548D2206BCB8B837D8CE8C9C3B3066E46A1655E3D84AF42E10"
00711 "51DDDEF438821E0F0C1EDBFE148356D707036B269C19C4CEF4C4BB4048364E2A3886E38B42"
00712 "EFA15F22CC8F92D802EAF3FFAF9BF45247DB76C03E99F662884DC2A29EE488023BF0EBD465"
00713 "39DAC307410846B2580349106CBAADF658A066C3664E35C4C696726140275AF7611D2369"
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00717 "22DC10C47E11E934BEB7E1DCE8B6A2BAECD384D810BC3AE587E7EDE57CDEA908DDDB0208856"
00718 "24BE042DE0ACCD1511CE38AFB6C9DD812FEC339B8137D88108F07035A3869CDCFCB9402CF"
00719 "96B9E331297B644DB13DFA88F60605E067B9F35607D2D75573E0913F8080EF603AC4B7133D"
00720 "836B884F32F48534237CC559ACABA53A96885D297CBB572BAB1C3275F7CC7A3AAD10F29E727"
00721 "B28BC29B038F4003F8C93FEDC88C63D72609A5330F36F4986CD9536812676A89305C6CE58D"
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00726 "56E88068A777ACCE3C4B6E78C62AC1E8EAEBEED0AF3153983214D7459AA8E254633B52E5C0"
00727 "ABF4647B906AC50A62543710EE92B335A7162B540AC70F2B2F49FEA892BD72DBFC5F7A35C3"
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00735 "DBE63209C8231455012EB3E830B5B2A79ACD8FEA8016243EBC85BF5D6F46A48FE013D2B3B7"
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00743 "97051FC67ACA30E8AEE73D3A8CF38BB13524D4E0EBD9BE68398C7C16227CABB1D0B0A0ABE7"
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00745 "C85A757382270DAD15BA3CE36A76EF55F81A1E80BF366B37FE3A88EC722028C25E234E6240"
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00747 "36C79C30F36281495C76699CD48404673FA334F042F9E067DD7F3853BF71ABEAF6A9A546"
00748 "855E840CE42B224D8F6490C6CE5FC02EBAF4FFC390107058F54CD635D4A7F2878099C1EF49"
00749 "5750E6921BE2F39AD808C4210F287319F811A254CEF8CF153FC50AB2F3D694A530949E5F57"
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00755 "2B07DCB02D156CA96EEFAC69E556CFCE0AAB617C7FBB8C34871C1D35E74B7BD307D3F2E424"
00756 "C7A9AD676A1A69E0FE735EA50887A1DFAE6CA2FE4460FC7EF323ADE493020" // PRN 50
00757 };
00758
00759 constexpr size_t GALILEO_E1_C_PRIMARY_CODE_STR_LENGTH = 1023;
00760 constexpr char GALILEO_E1_C_PRIMARY_CODE[GALILEO_E1_NUMBER_OF_CODES][1024] = {
00761 "B39340CA1C817D81EF4FAE4E95BF3504A7709089FB48560E9E3EF802180E85EB2194E05902"
00762 "C6C4C52021FEB7EC64FD416BCEBC8E39D64A4B5EE345291911AB8204A888C25B1CD3D9342A"
00763 "56C538636D3EAB957037D09E879AE5F3A39834FBB84A3D8D5090D7814246B62E9CA68533D2"
00764 "EC403B4FB9488467FF9758B0D15A8CEF89187A1D5897880040B6C3C5244E85A2AD14BCF2F5"
00765 "ABC44A7B1D4A87E8BDA0576621873ED47F0F8D1D07CBB1E8CA6298E64EE6DC5886D37495B"
00766 "A2EDB3E0B0B68AD9F300310B88898DDEEFD484538C31A9BCAA76ECAD0C16607D32189058B0"
00767 "862EE9D70CEA9D304755CE8037BA4C46C2573181748A21E4B2BDD04F9BC240518273DC17C"
00768 "BAFF21A03E9120FA7DCA18D56DD1D9A7E510C90CF219104385F531F2EFAFD185ECB6B911F9"
00769 "B7809D98D86F15516FFDDBE9BD1CF8662EB777C3F94EA3F962D7B7949FAAD39935429E92C"
00770 "AE5637E9BCF4E94D413D27934952409AB536BE4055AFBC4330CD1E4B5509EFE5F8EFC9ECBE"
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00772 "GACF8990EBA907E43AD320F8019CB6355A2BA8670EE5A4F463E8E56F8F1D3E7F4922510FB6"
00773 "68E32C4FC23AD8496399638B095B47833E0CBB34977EB3E4242EAF870D86660D6A73F8E45"
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00775 "A64F94BB47BD4033C76D4924305907EC1F618B43C7535F3CFC093E5AF5DD5C4339F3BB6D8"
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00779 "D43721905D720EB85D8D229D7D87662121F0BEEB1E895ED9589ACF5833408A04197AC902"
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00787 "F5BE2974A2848FD917C3BCD346A431922246EC852E4AAD467E60C15D61DD3BF4A207BB57DB"
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00804 "6618CD376C4C184965F7D9D73400824E88A5C7B5866BA88C3E0065F9628A9AC6B91A188219"
00805 "2FC553E3140349934D20698C9F291B5370948AF6CC90C837B9F3607F13CAFD492CEF172337"
00806 "E66A5B813A56301B88A8799519CB7646F33F91C44CDBE7F768D7DD9B323A5002D2F784C410"
00807 "1AF90D6E4C5ADE7D085C79E827D43E10DF63AC70BCDF13DCE0471B487C5ECB752B9C3E20F7"
00808 "5DBD243790C91355ADFD7199081BFEA03D80E82445EC2831FB5014B85EFC2A52748A8ABFAC"
00809 "1BA3904E178DFBAB26C1750228C9A031104F58BB3B91905EDB9EADF7B0F6DF22ACEB0DE944"
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00832 "9EEDDA1565ECB0FA1EEDB424414120AAE8CFD0BE88D4D248899A0BCE31F9BEE7A4DC4DB3C3"
00833 "B10444FAD6ADCC2E28F0EDF7B808536ACF5EB05AADAEE92693EE02C9512B3EEF000844BA35E2"
00834 "4620A2E8935354B8432C07C8FD615534BCFD0D8E3B572BF2CF06AD343997590F8EB244A32B"
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00837 "D66A311AE03CCT9FF6861E715C9DA9AEE751F1220661581C75DCEC0515A1C9259B9CF8944"
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00842 "EBEEB9D5C888112589EA5C9CBDF49E675965223416D6DA02D233BFD4614706BF13373973"
00843 "207C849A0DB41EBA137FDF79A1EB25D74E30CF60B577C2787DF04740BA8CADE3F9DA55D3F0"
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00847 "A4A1EE07B4F3C03BF566558484F19A3BB674B6795F0D8537BC31BC8D7A38B2FF1B2EC8B785"
00848 "39B2251D0E385DE484B05A411477681A3AE7527AC98BC2943AF1CF7F09ACF2DDE4530AE896"
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01183 "E6C689F1E8DF0AD8AB289D5C33023DF90B21A26320CE8C1CEB2C099FC1DB58737665855DCD"
01184 "20D587E176483E33EF14C80AA760F751EE5B28460811E5110FEC3D689AE2A6E91D0A3F1E2"
01185 "2623E88571F4DAC895AA428D42634EC142E56D0D57CE68D7949BE13AF234229E546E9D6D5"
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01190 "2999D2D05B23B2C3067E6CE4A472FED3B8BE1C15C24DFBF4956A5B670FFCF128E5A230397"
01191 "64BB3CEAB55636B83674060B3CCF5EF9A7B7EAB0813ADEE82E271C422FB78A9820007753B1"
01192 "E62BF4CCC0774F7796D5B2008FE6542DC0C77ECA3810120ABE9F90BE5934E8EAE365D02B3D2"
01193 "DF4EA4A827E033263B113EEE5823DD3912FB31E3C4B46B274D7115F34CDA793DB6AD2CD8BC"
01194 "AF4B13B832AB605B642B2877EE2E66B411668EA29A7DBA5BD969B9F152638", // PRN 31
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01196 "13ED4B647013B3EC31C9EA6217DE55D016A1977A0B285224129CDC59A9E54F3E5094258F11"
01197 "C0C995F60785614E560764312CD86C6969B3274236EE602EFAE392C015E4C3972D6FA2A47A"
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01206 "0D60D523216FB233CBDEDE7FDFBA827450E595AB51237F9E77058E40F862D3A5A96E4AA3DA"
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01240 "CB5B8FEB23D289FA235BB4959F8845B25405A75A30E7D05D7BDEB721BFD4A998DAA6F1A547"
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01243 "F15E629473D61FFA29BA18A468D8D4B1F72DDFF99608AC9E6A6D6A9231F24388991E80FBE6"
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01268 "7A04D7449A489BD02704CA65BCD8B753B689CB90C87C73FB4A45219DCD817E9AB584E0FF049"
01269 "EA711CD3E24CE41423FE6F258A65CA8EC3A00D45371EC5B846CF1549CB5CA4FF14B696140"
01270 "D3483DDC7801BFE6CFEFB9189B5C7AC3DB9C0709F630D80F361442BBD2263B00530EEF21D"
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01276 "A51EA2A9A2AA15A0A4F29C2FFD8B2CB4ADEE99B59553BB2398273C04329A5C884989D417C1"
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01342 "F570CF88303377092B5B6BFF3B01D38A53E8A68B0D81FC2D1D375EB27C7AEEDD70679E8DDB"
01343 "A6DE656442ED951478FB96A979B4A9091F344EF39AF23DAA886C6FBAA8611C61686332C630"
01344 "690109E2869D91EEEA2C21B22921B9E3DE40BF063E370FF64E7AFE160B7EBFC4AF6AED0A3"
01345 "042552F5F36C2CABD339FE1442242EAD931D1B83968D1A31A7E32A0838401DBB9C1034D56A"
01346 "DCAF5942462EF63440FD70F1520137A50372DD0D125A6285F7D7175FD9225D03A109E1FC5EB"
01347 "547303CD7708F8FEED2814607171930436B249924714E8D8E024C24B3C0C9E40127DEC61"
01348 "D966C3F9DF01793864615F291B73F73D27B624ACBEAD3D371B8D4FDA823C0", // PRN 42
01349 "A1B9E8AB6C44A3610768CC17E3B899CEDDB44B746319EC50BA7E006EA0F3C09E9D67EF8A20"
01350 "15482BF93EC2658800503BC72831800CE0CF9FB6CCADC8327A840F69DDF29BE212BEFE4AB181"
01351 "0026FFF786D9D3A88B29745EB61131FB47B385F83CA211B4A2BC0449F7ECE43B2DDAC94C109"
01352 "55FF2E078CAF5973FFA7349907571AF501FA6A2FCF24E4B5676F8213475351C0398748FB6D0A"
01353 "SEEA11E28C0998E57D076A201453EA7C70B1F171E7D084F444311C9829CAD03E0C2330D768"
01354 "D39DB6B7901C30787FF123CFBAD4E974A5F6412FB1BC927FD65CAD1F3AA4ED52E2D84AF625"
01355 "7EF311222467DE179E89438524116D8E0A4A94C19A4D66D0AE0FC535D69C4953C2E43136AC"
01356 "07D6A5774D59DEF1471B4097146C2124DF83D36678FBD7BEA6E258D826645DD88AC9A7E5A"
01357 "05FB49F2CB29EA9081323FFB2A00F3915D1F36675BA1C9AAA3B166D9FB2529150D3573E502"
01358 "668E33DFA5BE95AA6C2F1F106D69218839BA590406B4FE4A03C4B16E29E6BC31335234BCA5"
01359 "5D34955880B702F82023198EB7BAE381B231FAFE513F24C8BA9E58798F35465C2679DD5A8"
01360 "B16EEDAFB04E5A807B9BE6EE4B3AD77609D2B9E0985BB23397BBDE08F4D0B21494A3129857"
01361 "E37D13862C1FFF77A57AC663C206A92F8358E6C05FDE1A9D68131BC04B76F6865E8DF5C48F9"
01362 "424CD9AB6FEFFB3BA98AD32C923CDB8602C5367AA9ECAE48AE6A276CF25C", // PRN 43
01363 "ED1196222AA470CB4FC8A0B7D2C785EB45D232E06453B77DB76F60E5F7BAA0FAE80467EC8C"
01364 "656FC277FDE8BFAADD2368B41AFF69460495923942ACF85C09EF01BCED0076960E5CDB1D36"
01365 "061933C1B6037548D27932CDF969FD5A910D5564F3A6BAF896A2A69F40EDA76E813AA26153"
01366 "0F686042235A39A76081F58D952662894E6E648BA72098D840235EC4A2B963F8E74B52F2D0"
01367 "088DACA7EDF48115618DBBABC698C04AAAC0632475BEE65BB26A4EAA08F0209B75EB259B82"
01368 "6724F580209F899E1808411F823819CC5F42A9FC1F0CEDBDC54C046EB1D1658FFF7252908B"
01369 "09F8C1D82E5F6D605F0B17B25506FAF91D4B3D4EBCB7A705E5BCB2A6FB409ABE4B1B0B4763"
01370 "0F1AB0B40A3455181678573F82A7C139F072659D80671961D614D9F7DA72914BD5D6F417EB"
01371 "C152595972PDDFAE876176923819CC5F42A9FC1F0CEDBDC54C046EB1D1658FFF7252908B"
01372 "4717D2086D91765D83AB76605050B810C542819BBB7CD87EA2305AB4A567B2C500D9913B7C"
01373 "6046F748DEECFE3C3AF829EF97E03799EA50F7C9EB38990F0D466498C091C3ABAA18453B17"
01374 "3FOAA3A486DAFEFE68E7998EA30E5C1349F2A54AE753963CEF58332A114F964B83B4E46A"
01375 "44147B11FFC60DA25B5FA705F34725B1388B17E99018236BD646DC714F8B7CD3BF2648063B"
01376 "2D3FB713AB94D82ED81D571D5BB4D3E5F2F067E2F2C90E8B6857E6A651B8E", // PRN 44
01377 "EBE597534C0A6FEE9CE6AD10A80D2DFD160D7DE7A20154F62AFD7C3187D51D09DA39A95843"
01378 "2CDCCB83FCE19131E65A30DE99DB796D93D0944223D960BA233798323D368DDBD407D51B8"
01379 "0350976951AE0E50CF409279301939624C741D20D5CDBF4BC3ABC8723E267BE75707024F63"
01380 "98CC6D32A7BCD098555E0EE49C1A2354D1E961CA9910A5169ADFA71D56745181E0CF13469"
01381 "D8F3C6020637B8118ED8421A680FD4D515DF6B31C39ACFA36B601027AFBC861493D3ACEAC"
01382 "FB501DF9A311B7EB9D38D7107E6B5ECBE74FD35CC8BC8319DF9F1948653C94C868DC24AB8D"
01383 "7E650DBF70A3D1D878558AC9BFA50D425604037F3DA323192654F1296C8320AF934AF60DAC"
01384 "AD7F9630EA4ED0A635678213F6D09D73A2544C779596990DA42079C23581E22F541E6A3B6D"
01385 "3FA383597A8BDD7CA42930816D74FE8B12F92CBB9303CA5FA12BF5FE954FA7B53E0D88B79B"
01386 "E263BA85B842A7672F5C4F7E6B2DB4C02AFD6034B7371E01215CED3F73AB8E3419D7447781"
01387 "AE5DEB4F4547C5549E9B0AD59940C162790650344E5ACAB33A187A58E29C9032963F088C04"
01388 "4ABE73A855F1FC93AB8DC258E41977311B7997EA95D32CF1F0140CAB9E6707E73E4FE575"
01389 "E0752816122C39B8D12F34ED6771EAE192D830797DBE97A0BFD00E39CA382D44F080BB4F8"
01390 "FF6FAAFF2A82744C6E14D3036E00EC2ED5C9D184ECCA300030D7BD77B27DA", // PRN 45
01391 "A56990B45E9AA5F9523D563D53E854A47629A4183E85CA1995BB374EE5601BDBCE5C740799"
01392 "9D28B7F0F1B3EC7A463D3C941C5B7EB71E6626DA3A7136627814EA6D28C8D16E91680B0D96"
01393 "1AAFACE2CA4099F986CD45A2AB387E39497B13678447480514B4008F0FA3B95AD7D2B4751F"
01394 "680F0C7D73651F9621E1355CEC76F10468ED33DE4C7D7D68B786B7F0006C604BCF893739FE"
01395 "6AE56AD5AAD07D5BE76DE1CD581B10EDFEC9DF65AF925C4C1289837BE1854A62FCCECCCE4E"
01396 "2AB47B846C467F5E4C276047501EABE444E051DEA933863E0FCB2356CC0C3817BA59B2E0A"
01397 "D78BBFF4C3E4C3543331CD81C7F4C428B0418DFA4D66F655BC50AFA49C9A5E8A67BC265A3"
01398 "F30800B93E42C0E66F117E6C59C85BA5E273234EC7212C7B7AC3D87FC0E0EC5FBAE6654461"
01399 "F24BBDFA9A063FD0E3F98741C5622ACC8BC008EB0E3F3D57680F12E52F894CD957EFD49BF5"
01400 "12D9131757161A73DD9650E3561FB31509A908D3EA8DBD1C3AA95AC32E6960E0D17A218A25"
01401 "784332A88E85303DEBE117BEFEDF46882995AEBD704AEAE032668AEC6B8E5BD28D3F110C9F"
01402 "8C1DCA8FACFDC1188A073037796555DC4FAA26ACB9F51B545D32C22442BAC3DAB20D3C08D"
01403 "784E9FEDB47547C25671C269A62163742B55AB4CF9406D2C5047F92C76356F0B90221E019B"
01404 "31890C0B8FCFCD04E6B5D06114B967D1358797238D5B14D824C8F0BD7B8BD0", // PRN 46
01405 "D85AAA53F2DE2946EB0CA09DEBB6CB61D91D27C8907B90C89E20C01F681D33BF0DC70B6C79"
01406 "F19E4DB64793505A0E055C33D1E07B7F5AE09F7EFF0C8CEBE80C84373804A48A945CA406D3"
01407 "A1B17CA787DA265C1D8FC735CB098C1AB37A0452F1A287B8E19E3A57E59EF8F2E6CCE2F0AA"
01408 "7772955977982B1F6880AE8717520753636591BA36E351310E98ABB77E2E62CA5BF267935F"
01409 "C38DE173CA20C3A64B5692A45E82A9E36D005EDE6680D543C021C7A9F53DB69BFA3201880"
01410 "B7797E90D31011AFA17BAE836505F5B337C23A07D6AF167258C314C3001291DD9FC565F6B7"


```

01411    "FB74D99C1B42B496422B3D3E1A564769C2306E40264641EC14724301795B4D54F5FF8D6C4A"
01412    "B3645B56C1D0FFE9B977FC5017E2A53392E7458BAA308C343AAFF5B46B808BDA1FE5C28429"
01413    "9A9EEFFC755132F9D3B475E2FCD6BA84917C601B5E8340B5A68148A33563E40AC5A1E49BD8"
01414    "D5FA77BEB6B99E6F4F68A10ECA112475531E7C1942AB9504B8F76EA7BCCAE4A19EF859FD6B"
01415    "6753F07BDD9A19421A2A0B8F27643B2311FAD7978F4366C41BD9F609486FC6EC7CE833A00D"
01416    "7A48AD816412BD201F40C93D136ABB8E329DDB816D1F59A1F3124D6314C64C9B640E4D5BB2"
01417    "01CDB4490A65C73228E78055AD6632D81709AA443EBF29A4607A504DD5CBC0D271FE595677"
01418    "B8E6A5E29E23D171D50B878D0D3F9416657E3997D077677B87399A6D1936E", // PRN 47
01419    "A0E629454DE594F7693888C9ADB907F83EC6818D6FC0019B70077BF1B0E3C2CB16A263BE14"
01420    "5EA8129FED6BD98F3D9120BAD28379EC8E36DEC69C59B37BD6C2B65D172C70C69C23E29A61"
01421    "43121ABE9E6A9AB46C3DB8C3979BC876F4357F6BAA5A0CB33C3AFF1654FE547D5D760E8CE09"
01422    "5A9B324E15CEC1596BB7E0D56433D8908EA69925A5CCDCF01702811AD1103F237D36C5F12A"
01423    "3CD938A61EF76A3387340499E4EF1855F892F57AC39AB419F1A397CD43FE7F4C5E609ADF3A"
01424    "2A8E401FFAC870985826CA0DE211996A3549A203B798A5162E98FFC8B5CC2CFA68D618AE80"
01425    "D399D8DFE0FE4A81ED9B586EA89F646D5C0AA8B107506CF786879419D0F717E8F70C5A9DC"
01426    "2C3F122CB52F3B691087EF5971C27086512F1890494ABA38B1619969F8846B8876B95C5614"
01427    "2F5B171502FA44ACD0299E82FC94EBCD4CDDBE1F5DF978871128F79C1758BB512D5C3BDE59"
01428    "A89786CF4E4716F0515F45A1CA31B06B23E4883F99EE0488848E0A60FA14AABBD41EC5421"
01429    "D0C162590FEFFEBB4DD0300221471DE8DC0C87DB3F1D54DB11744F8A7115DCA0595F6CD99B"
01430    "74AF6B10C0D14E430F8B40E3E7105C89B2C8F12B37A8879AD9BEAD49AFA1BD56569713CCDA"
01431    "3FB634C3011D51A8DCF84437251A7B19EB61FCE5DF6E2278784722BABB384BA5424646A23"
01432    "F6D10CE23DC5E0D8D512E7C5C094B1627D6285B57EDF38A7DB1BD57B72044", // PRN 48
01433    "CD7AAC98501F29507EA4E0183E8A40D2E5117E47BB5D18D01A3732DE4C821DFE86521CBEA7"
01434    "DB29BE1148BD544ECC681689BCD1B41EAF755310B7659342F8EE11CB41550CC30E566E1927"
01435    "96B66C1A83C0B28BACCF6A6C393043A0A2CB89712BC1CCB174DE58E66896AF39C1CEED1E05B"
01436    "0435F8CF6FD920D100F51584FE24879987399481DBF27DDB6286B6353919E552E669290CE0"
01437    "2AB4CD5113D7F484229F379C7332767EC69E4336439B05DE1C1E3563DD303A4F580BFF20A4"
01438    "0E49CB822F715ED0221EBCDB5DBAD751124B1715E82F37488265135B6C8BBCF4F801ECC4D"
01439    "3525FFF189493AD4EFF0C042B070C4CA8FB1FDF43D79F06A6E4E3D35D7B07D4B728D5DC54EE"
01440    "DACBBBA1EDDCDC07ADF7DFCFEF835E44DF1FF66DAF2A7BAEBE218AC3B15E183044D6A8A89B"
01441    "3C101B40BED97ED5DF93BBC1B84931D56B8C822A6D058AC74CFA4C85D8B456698E82D5B757"
01442    "4C17B041E5F4BEED09F75012355CBC322B822C63F10C18A8F279E9A0E18E1FEF183D23E138"
01443    "94E31F6D046956FE8A647558228F6D4D6910151EC03937876BED7A078D33DAEB3F2239353"
01444    "BB8181E62B286BBC41588DE10F478A5CE5B508F205A41820356767B0A0ED4B8DB9EFE34836"
01445    "2E9A90D6C30218B295B338B51C9239D02FC8A1E7DAAAB60AC37F5E67CFC88EEF69567B5C8"
01446    "1A03B449F4ED38B9D295A36AA3503173F6F6F66D93CE72D753076040FACDE", // PRN 49
01447    "ADDCEBDB50E907D20E826E6E8A0D30C20C74B2DF204EA784BAE9F618CAE33A3C937729DF9CB"
01448    "10BA2A4C33E0182A37200C0CC509729D828B8A2A20F283AC4F9306596684EA3FB5492A4C9F"
01449    "2DB459E7531C9F9C0950E7D9E93B3EE5912AE7E39AC8F4EC14B18F24E325003F477E347C5A"
01450    "C1B67CDB11AF3BBBCD0AC3703024B5767AA67A208254F798684BFD1D3EACD757EEC772549"
01451    "50A146620400DB95E694574F739A991EBA771EBBDF1056BB39A77DBE0636A032E17141332"
01452    "F951C57C6C90F348F165E3ABDD60D429D5D6BEC7E3E3463806F819EB2D212B3528A5EDE51F"
01453    "235AD100A35E890955F8A1DC51FDCB53EABCA2540997DD054C1F5B29462995B876B44D0859"
01454    "04E55E1B838BEF600A992EB49CE078DF75AF3D0F137685AC0D07F0BE1EB87B63A41E74DDE8"
01455    "69C8A683BDBE60AF5D77FF18F7137495BCEFD0ED28F62F9C3E25D332B5F861D999FCDC0B485"
01456    "1A984A4DBB53401FD40351ADA4335C702BCC8D900C737507B990BDDBE91D201E3A0946DC96"
01457    "8D43FD10D04B0B76667FF5B4291C2124B0124C6B710A6D1BCFAEB016B9DEEB0F7A4FE044CA"
01458    "4EA0CCD84B7682617C3A545071EC295B0663B3F577D562DE1D9DD80DE6A1EFD6D5991EB524"
01459    "6F1597B86D0E9A90CF6DB0EB2B8E7BAE9431E567F01AA98502C773742246467ABF911A91A5"
01460    "1F6C1B9E0C3233DC1A37D17DB91A5F0F661B0EB5886964456C7818601BD0C" // PRN 50
01461 };
01462
01463
01464 /** \} */
01465 /** \} */
01466 #endif // GNSS_SDR_GALILEO_E1_H

```

13.739 Galileo_E5a.h File Reference

Defines system parameters for Galileo E5a signal and NAV data.

```

#include "MATH_CONSTANTS.h"
#include "gnss_frequencies.h"
#include <stdint.h>
#include <stdint.h>

```

Variables

- constexpr double `GALILEO_E5A_FREQ_HZ` = `FREQ5`
Galileo E5a carrier frequency [Hz].
- constexpr double `GALILEO_E5A_CODE_CHIP_RATE_CPS` = 1.023e7
Galileo E5a code rate [chips/s].
- constexpr double `GALILEO_E5A_I_TIERED_CODE_PERIOD_S` = 0.020
Galileo E5a-I tiered code period [s].
- constexpr double `GALILEO_E5A_Q_TIERED_CODE_PERIOD_S` = 0.100

- Galileo E5a-Q tiered code period [s].*
- `constexpr double GALILEO_E5A_CODE_PERIOD_S = 0.001`
- Galileo E5a primary code period [s].*
- `constexpr int32_t GALILEO_E5A_CODE_LENGTH_CHIPS = 10230`
- Galileo E5a primary code length [chips].*
- `constexpr int32_t GALILEO_E5A_I_SECONDARY_CODE_LENGTH = 20`
- Galileo E5a-I secondary code length [chips].*
- `constexpr int32_t GALILEO_E5A_Q_SECONDARY_CODE_LENGTH = 100`
- Galileo E5a-Q secondary code length [chips].*
- `constexpr int32_t GALILEO_E5A_CODE_PERIOD_MS = 1`
- Galileo E5a primary code period [ms].*
- `constexpr int32_t GALILEO_E5A_SYMBOL_RATE_BPS = 50`
- Galileo E5a symbol rate [bits/second].*
- `constexpr int32_t GALILEO_E5A_NUMBER_OF_CODES = 50`
- `constexpr int32_t GALILEO_E5A_HISTORY_DEEP = 20`
- `constexpr int32_t GALILEO_E5A_CRC_ERROR_LIMIT = 6`
- `constexpr uint32_t GALILEO_E5A_OPT_ACQ_FS_SPS = 10000000`
- Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.*
- `constexpr int32_t GALILEO_FNAV_PREAMBLE_LENGTH_BITS = 12`
- `constexpr int32_t GALILEO_FNAV_CODES_PER_SYMBOL = 20`
- `constexpr int32_t GALILEO_FNAV_CODES_PER_PREAMBLE = 240`
- `constexpr int32_t GALILEO_FNAV_SYMBOLS_PER_PAGE = 500`
- `constexpr int32_t GALILEO_FNAV_SECONDS_PER_PAGE = 10`
- `constexpr int32_t GALILEO_FNAV_CODES_PER_PAGE = 10000`
- `constexpr int32_t GALILEO_FNAV_INTERLEAVER_ROWS = 8`
- `constexpr int32_t GALILEO_FNAV_INTERLEAVER_COLS = 61`
- `constexpr int32_t GALILEO_FNAV_PAGE_TYPE_BITS = 6`
- `constexpr int32_t GALILEO_FNAV_DATA_FRAME_BITS = 214`
- `constexpr int32_t GALILEO_FNAV_DATA_FRAME_BYTES = 27`
- `constexpr char GALILEO_FNAV_PREAMBLE [13] = "101101110000"`
- `constexpr size_t GALILEO_E5A_I_PRIMARY_CODE_STR_LENGTH = 2558`
- `constexpr char GALILEO_E5A_I_PRIMARY_CODE [GALILEO_E5A_NUMBER_OF_CODES][2559]`
- `constexpr size_t GALILEO_E5A_Q_PRIMARY_CODE_STR_LENGTH = 2558`
- `constexpr char GALILEO_E5A_Q_PRIMARY_CODE [GALILEO_E5A_NUMBER_OF_CODES][2559]`
- `constexpr char GALILEO_E5A_I_SECONDARY_CODE [] = "10000100001011101001"`
- `constexpr size_t GALILEO_E5A_Q_SECONDARY_CODE_STR_LENGTH = 100`
- `constexpr char GALILEO_E5A_Q_SECONDARY_CODE [GALILEO_E5A_NUMBER_OF_CODES][101]`

13.739.1 Detailed Description

Defines system parameters for Galileo E5a signal and NAV data.

Author

Marc Sales, 2014. marcsales92@gmail.com

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 Definition in file [Galileo_E5a.h](#).

13.740 Galileo_E5a.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file Galileo_E5a.h
00003  * \brief Defines system parameters for Galileo E5a signal and NAV data
00004  * \author Marc Sales, 2014. marcsales92@gmail.com
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_GALILEO_E5A_H
00018 #define GNSS_SDR_GALILEO_E5A_H
00019
00020 #include "MATH_CONSTANTS.h"
00021 #include "gnss_frequencies.h"
00022 #include <stdint> // for size_t
00023 #include <stdint>
00024
00025 /** \addtogroup Core
00026  * \{ */
00027 /** \addtogroup System_Parameters
00028  * \{ */
00029
00030
00031 // Carrier and code frequencies
00032 constexpr double GALILEO_E5A_FREQ_HZ = FREQ5; //!< Galileo E5a carrier frequency [Hz]
00033 constexpr double GALILEO_E5A_CODE_CHIP_RATE_CPS = 1.023e7; //!< Galileo E5a code rate [chips/s]
00034 constexpr double GALILEO_E5A_I_TIERED_CODE_PERIOD_S = 0.020; //!< Galileo E5a-I tiered code period
00035 [s]
00036 constexpr double GALILEO_E5A_Q_TIERED_CODE_PERIOD_S = 0.100; //!< Galileo E5a-Q tiered code period
00037 [s]
00038 constexpr double GALILEO_E5A_CODE_PERIOD_S = 0.001; //!< Galileo E5a primary code period [s]
00039 constexpr int32_t GALILEO_E5A_CODE_LENGTH_CHIPS = 10230; //!< Galileo E5a primary code length
00040 [chips]
00041 constexpr int32_t GALILEO_E5A_I_SECONDARY_CODE_LENGTH = 20; //!< Galileo E5a-I secondary code length
00042 [chips]
00043 constexpr int32_t GALILEO_E5A_Q_SECONDARY_CODE_LENGTH = 100; //!< Galileo E5a-Q secondary code length
00044 [chips]
00045 constexpr int32_t GALILEO_E5A_CODE_PERIOD_MS = 1; //!< Galileo E5a primary code period
00046 [ms]
00047 constexpr int32_t GALILEO_E5A_SYMBOL_RATE_BPS = 50; //!< Galileo E5a symbol rate
00048 [bits/second]
00049 constexpr int32_t GALILEO_E5A_NUMBER_OF_CODES = 50;
00050
00051 // OBSERVABLE HISTORY DEEP FOR INTERPOLATION AND CRC ERROR LIMIT
00052 constexpr int32_t GALILEO_E5A_HISTORY_DEEP = 20;
00053 constexpr int32_t GALILEO_E5A_CRC_ERROR_LIMIT = 6;
00054
00055 // optimum parameters
00056 constexpr uint32_t GALILEO_E5A_OPT_ACQ_FS_SPS = 10000000; //!< Sampling frequency that maximizes the
00057 acquisition SNR while using a non-multiple of chip rate
00058
00059 // F/NAV message structure
00060
00061 constexpr int32_t GALILEO_FNAV_PREAMBLE_LENGTH_BITS = 12;
00062 constexpr int32_t GALILEO_FNAV_CODES_PER_SYMBOL = 20; // (chip rate/ code length)/telemetry bps
00063 constexpr int32_t GALILEO_FNAV_CODES_PER_PREAMBLE = 240; // bits preamble * codes/symbol
00064 constexpr int32_t GALILEO_FNAV_SYMBOLS_PER_PAGE = 500; // Total symbols per page including
00065 preamble. See Galileo ICD 4.2.2
00066 constexpr int32_t GALILEO_FNAV_SECONDS_PER_PAGE = 10;
00067 constexpr int32_t GALILEO_FNAV_CODES_PER_PAGE = 10000; // symbols * codes/symbol, where code stands
00068 for primary code
00069
00070 constexpr int32_t GALILEO_FNAV_INTERLEAVER_ROWS = 8;
00071 constexpr int32_t GALILEO_FNAV_INTERLEAVER_COLS = 61;
00072 constexpr int32_t GALILEO_FNAV_PAGE_TYPE_BITS = 6;
00073
00074 constexpr int32_t GALILEO_FNAV_DATA_FRAME_BITS = 214;
00075 constexpr int32_t GALILEO_FNAV_DATA_FRAME_BYTES = 27;
00076
00077 constexpr char GALILEO_FNAV_PREAMBLE[13] = "101101110000";
00078
00079 // Galileo E5a-I primary codes
00080 constexpr size_t GALILEO_E5A_I_PRIMARY_CODE_STR_LENGTH = 2558;
00081 constexpr char GALILEO_E5A_I_PRIMARY_CODE[GALILEO_E5A_NUMBER_OF_CODES][2559] = {
00082     "3CEA9DA7B07B13A6CC0AE53DAD1EE2A0FCC70009338C08AC0EE457F76A1690815C3C940AB7"
00083 }

```

00074 "22487CC8F3D1F4C428828E7FD2A21230E42A3BBDFF1E792165F644D0E0335F95EBDC93D6005"
00075 "CC0C680DB780E1B8C4946B7974319F9816141DB9E01011E4F20DA8F1B8E15A6F618CF599C3"
00076 "F5C1A1B276D51318ED4119BCE0ACD0332F3DD8F88EC5215AB311C51FF4987DA93B09A4BA8"
00077 "4CF08032F6CB28F43043C54586811D870AD6FA27AA63785345C8BCDD3DA26A0134738BC7E0"
00078 "8461D5409F0B791D8574CE797FC5EF7821055028CB4AF92AE1088F8806CD55F0E5FDFCD8D"
00079 "74ED801B2644AD5D79D1924D41DDC6AB2070B5360CB64CCF487FE517420348CC39BF50BD7"
00080 "8BE7DA91542FEAB689457B3EE69E43C75FADC303F31032FD96B7DC70A88C3B7BAC7322B285"
00081 "D9CFB3A93AC8B890165F23848FAD8477DBDD3D0AA4CB3CD73A48000B6D134DA2DA70B56E59"
00082 "0A101AAE78864DA0C64A7BCC6B37CD6F31E9AFF10CA4D47630752D253944632DF6EC60AEC"
00083 "CD223F29399CDA3B74D1DFA5471277EE6C814464A8C55D3C0B83B36B6AC9FA90CE876ACDF6"
00084 "5E3EA3FD61D309EB71ED29A3D510B2F4C0B6D6C5B57EC9060CFBE48389DCB17CBB2284E7F5"
00085 "78565B91503B06F49CF3E8534870AEB6AD9707265A9A1E6E2E5E6DF6DAA367239A96EF5B02"
00086 "C19A4543D537EB4D9D73966C09E9B52B4706F57B3E0987885EB84DEA26F7823D895F620151"
00087 "88ED38C04CC6714F797FDB0BC713E3D0208462F9A68E3872A167BF1BF9791AAE8BB73CF527"
00088 "C50975B52C4E52CF2E95B677F833ECC878D1764839608CC1108A75EE9E58FFCFE4CB52884E"
00089 "7AF15EE0632E0729DA1CF5B7A227028CFE1E08F8B881E1A743D52DD27BED33DE0EE75DC031"
00090 "B4864CF192DFEAF64F726D73321363A233F81C57232432D2B0A5A4C44F4320847A9C143F37"
00091 "F20421C85D2B571482FE45D6BCA152E6EA7223BFC6DCE06CEF90CE9114623EAB9B1EC789B2"
00092 "51B4AB711DABF5B16FCD970F437B8860313B4F1F14D384EE3976B7E55D2FDCB7E1BD9BE18B"
00093 "722E37C853ADC7E1CC2870A02881F95B78487780E1D1C296415109CF07AB63D0782A9F451C"
00094 "EBE3E5B91503B06F49CF3E8534870AEB6AD9707265A9A1E6E2E5E6DF6DAA367239A96EF5B02"
00095 "C56431159556B8BCE077A51469A87737D3D6F06D97DD479FCC35129F4499C19EF98BDCEA9D"
00096 "4941B3756CDE1997C3AFCAE62B6D9E23341E11CD05A7FFF52F5814011A84D737E126410900"
00097 "6BEF5F19E3C6A9C7521B44741A8282755A8F0DC2FA0E1F6CA4FB34D8CD5FAA27E188088687"
00098 "25B9634376137C1BBC46934F83958112D03082DD6148F353BD1DD24B9F8FD7AD89C40DA0A"
00099 "92ABDBE36708038CD56FFC4ACA35241D76FAC4AE1211AAD9D73D51C81C59BCE05F71C34573"
00100 "DD3A2C670F8F533A950EF24B00EFE6A3F1354694ABCC6FD9EC4E74DDE1F287AD4F847A297E"
00101 "CCCC39AF029EFCDDDB19932D906B9CEDFCBE0D422CEE305DD05E407340F28EEEA866664D60"
00102 "AF293A45D5D6D5C0000B05F79463DB513ED488DE7BD4EC9EACFEF973B23CE4E9539EFCB797"
00103 "456CF5D91EC54FDEEE80B39063C48B91A5C2D2BEB8C1B9B46D0AD6503BE5AACED2BA5EBE81"
00104 "F630B4E07510356E8229F7FC5EA532B8729CDB819E066A15379AC6942CD4BC5E97C6791E09"
00105 "8105C323A3A3DA3880D5EE5562ABBA2BDC9906F4486B51ACF8AA4405E9D7A63DB9E3058782"
00106 "DD9AF3995FFB3D34AEF98234A0B3DC62C339325B60706C068F0198BD8FA658396D06931B06"
00107 "9155217690C7F88FD230CDB38E3E48530BD47722FC", // PRN 01
00108 "9D8CF144C4B667345D44F765622A956CAC4E097AB1CAB05CFBCC6BB68C709503AD9DB09C09"
00109 "C983D46A0A0586F7EB26DB4D46F868C10E112828B1AEDB3C0074BE0DE3C9B7821BABBAF8B"
00110 "8E24F69869CCD981B09A783BF6A95F39ECFAF25DED6B16F89EA09D3A8413CCEBB545651B36"
00111 "3DD385D12BB72420440C40E804FA27DE029A1E08629BAAB598C035DC58FDD309844F3BEBDE"
00112 "40FCC231F38605DEDD06572ADD85DC51D3D8B89B4480143D0B75283522354330E5CCF4DE1A6"
00113 "E68047D5B8D45D83A5891F2D40C9DB8A76CEB1D18FE2BC38D080A8D97064CC87D692DF2118"
00114 "4ABFDDA7642D0BD6F3209D06B4AE7600F7DDDB71DA751120599117ECCE645FD109CCA2EC7D"
00115 "B98F4177F14DB854FEB314B5D7CD3385AD203464EADAEAF4AD08DFEF3D21240BFBBEFCAC"
00116 "1356C72A0F5C61BE03CD2A21A7D756FA9003D562FC4A49A6BE788EC8D80054ACA881DFFF72"
00117 "C2966EECD09F185EDD11218C6696DB14E05FFF3644D11E508F4F1E9C5AB3074FB1C3FB2109"
00118 "2A1C8D5AE05688FA4A9226C3C3D0BC3981933DC8648240F8CB67085F53AC5295428DC8447"
00119 "A1E5A46C2BA86796982C4C6CC647FD8079BC4024BB69E2B226E6F3D0FA90B4D36DA2AED4C"
00120 "6BB60D318AA7479FDC2031143C67CB4381C27072E12935001524C7BECEDAA9954BCC2AA128"
00121 "E9EC2C95498FD8DF655C015896D9ED42CE7F91CBBA2CC4A7920038EBB5F5CE638F969F8B17"
00122 "9E72AE252B7E826E5CB53CE85AAF1E1F1AD8D534F78A681928818AC3154651FFC583DEB0"
00123 "A6A1F40B98771ACC528AAF80D210ADAF83597869968D499ADE9A19BAF341E8CBA20F0E1473"
00124 "BDD898C24C7A546679924EC7EE992A2086AF295BEE1F6D0F8843D91180BF2C981C11FD978B"
00125 "23B6BAF7786BD526B458B76A87C31D7C52DFA43F3D362C8EEFFFB3FE5FB3F6E5F34B1FEC7E"
00126 "F1031146F36F09B32677F148F7DEBCF3526BB45582436A3092408193D6312626E46ECFA96F"
00127 "EAD12A234ACE10FAF9DE75EE2D238088146328E10E9ECDDB0B018ECDFF2725415CF5A06AAB"
00128 "857403BBF6CBFC350903A982864827988BC805A3484A31FECF7A40D4FE251BC7E487613B9D"
00129 "3A48D3C7DAEFDCA9C4B7E625F868DB53A798515A61050978552699EF2A5BF2F13BDD444EAD"
00130 "C9B60B479FDD64633EB4C1062AA78BEF06692DED203819D3160310FD7F2343732156A9CBCB0"
00131 "B50BA9A8F93E339B702670E54BFA6DB2E2E773202C690FB71EB03671AB0B1B02B2F189BD99"
00132 "061ADD23F75F4914067AE638C9A29DD3661C28AE272CE692CBDE6AE880FBCF272E54834237"
00133 "2CBAF6370CF3BAE9648341CE7310BEAC534B5702B0611AF65868F840B6B7613FDAEA21DEFB"
00134 "4F2024487023B02BB858C9E9F27AA787EE775249EFC40913CBB69C38538F239B203815F00"
00135 "F7B9CB30DC79E6A0C3E069D109E4A1BAEEE36D354C3D0121F1342F1F4AC504A68D69DEC158"
00136 "D54B04BE8164B48F31BC0827A0379C5237070B6F963741AD9ED4F3865698FB823D7F49ED4"
00137 "E0EEF3AD927CBAF4FAE183252BC56AE4CDE3E329B1D9C87C6C11429B15B8EE589213CFAC20"
00138 "8A12AA601F7FC735CD0AEAE217471B3DAC1C279F353DC61994FC45FEDBBE0005D8EC7293"
00139 "85645846EF98A3A417E62F1EACA7E60D4E773BB2E4024D62830F103A7988733DD7BBCF3AB0"
00140 "CD0049006FE27FB3821724BEC37EAE44681A9699A025D212724CD98CA3415FE2BD09FADC0"
00141 "2F1501FA38A6083427B662DDCBD0460E12A09072698EC8966C47B8A640AC79C1B7722E78A6"
00142 "C28680F4BB77BBA477BE0A6FAB959B9753217C5708", // PRN 02
00143 "45D1C8FF162EE106CC87C3EBF6A837930F8CC797EC7A446E8A213ABD239582350636B19B5B"
00144 "E428A9C13F980B7AF5CD7F32630AFE8693CDF0EC0BC2C84F2472F5B86576E8C43136C14717"
00145 "A24705953D392BAC96C1055B782C7941D82FEA357E5FDEFF772FB9F3DF248455CADEAC4CBA"
00146 "2EBA9C91184006D1680E00D59E4BC8FBE2C2F7CC2E78BFA5B60EB292F244E6CF497D5A287"
00147 "432F2520B31B9D9FEC1210923299EDFF043CE077195509E92372F5959AAB4666AE486DEFA4"
00148 "00D81463C388CD05C677BFD4953D2627105B0A776960FEE916C75D53981D30DC689581B7E8"
00149 "E0723D56949662ECFAA6FCC9F0CE8892E367721718F906207663F9AD450AE98D75DF040080"
00150 "FC15DC2CD7A1DC0E13A0E547ADD2C29A397ECB9E7FA02035327AC40240E2091098708D42456"
00151 "3AB7C5867F3F2D78EE3EF5B658FDDBD49435060CA2EA3D559CDE957B7E48B98DB41CF875F7"
00152 "B3D9EBDF6547B4EDD98DF4B747B0793152FA8CC07C6D9EE5A2002464566D86466C2EDE54A2"
00153 "BF4BBE823049E57364C127A14BFE1B88ECF70EFB81EB831BBF50F6AE124E5F6A775F3F2620"
00154 "E91D489CCF24811C0890EF905E9E2ACD399E13DC81333A54BDD295B872EB74E412E2FB654A"
00155 "9874854FBC3A68C73434C5FC5CED27534B2B13C316205FF4E432FAFC13A7B5B7A7FFA9FEED"
00156 "B5AE6903678F2955DA124CE5856E8C53F24E609F7D3386DC5212B2E78B5AA23B59D45FE98A"
00157 "A08E9CFAA9D52ED260A36AF07522C047ED43808A39D7019E444EDF84D885A9AC84092A0F6B"
00158 "FED562F3E0D79FB5CF62F98E67EF219FA3F5AEB7D4E344642D3D4B1A7EEA18464F6CE8D4CB"
00159 "3181D9EBF684122751B54D0D7F3FC470A91B547148AAB1CA0DF59872120190640555A7561B"
00160 "0F2C11280768F74B1A56674FD5480B0F510491431810D99CECBC6DB85888BACBE2B020FB8B"

00161 "3D78039773229714156494EAEC3A2D0A59E718F72205747D69C05DDF1C678E2E154A1F84EF"
00162 "0CA2E24DC4A6A996F0850A396D2432596EAE84AEC0935B8C25D5C65B52A3272F01D281C4F"
00163 "753EE03EB10020E9FA02462CA303DA39560669637532D381EB78AE5EC0F6DBF6273EC97944"
00164 "2E6243F65FC51F26C6C9554C6C0E3EFF33BC4EAB6A27CAB9383BE7DDDE4218C4998033B479"
00165 "19503E1C9A789711EBEAAAD6C0298B3DC563F54D28675260F6D896F1B8D4FD0001C42921039"
00166 "8E9544B3DA12C31F7EE82EF4D2234E26F873610B76756DDACD24B6132BCFFE735FE75513E"
00167 "D527DD04D7DC6D24059F85706679DCD1474A9DB9571426BE17E6DEBA58B33B708567697F47"
00168 "1CAB8B78E8FA73B0E18CB6F88BF9E4F442F0FC21FAB89305484828F18B65F9D373A6A2B380D"
00169 "73F5924F80DA234C1DD87416D025E4E663C96F287B0C83DC92C2164D81830781B715209FD1"
00170 "1A65E64962D805389BAAA91DFBB990D3511E506A8EC101131C5B7284252F861D047DB2C202"
00171 "7DBAAD487ABFE429CA21CBEA7671350618E441F4D62F2D579CAE29D97023A8873869B55329"
00172 "3D9F54DA929E252AF132325A6E3BCBF7B36D0DAFA1E56A39A5D801FD0D5A4111017BF62A"
00173 "AF8346C7D424FE007C32B437ADE60AAA9540AA5078FE6C3C3CCEA53EE863086646C976FE6C"
00174 "794340AAAF453B2E9E2C3B4FC9C9C4015391E27CDFF5C1FCCC00BBF5B99715A1265F591E2"
00175 "94D530BD14DFD485AD34BBCEA32E5B5D0EED15F88BF5D96D058E6D70BB1A232597E35A625E"
00176 "5E8C2EF5E7031A71F70309019A0591BA0A50E87C839498255A3602C0FAE53166BE5E49E29D"
00177 "24AEC47002B698F80FC49E718B66A8959259ACC540", // PRN 03
00178 "7A0133D5CC3754D6B259A2CC4EC0298111D098CDFB40549E5C40B36A2846CB4B256672BA18"
00179 "9CD3A05293BB36B167508A7BECA3110BFF339BA06340585DE8EDA03AD244A77F54B7931610"
00180 "B6F9C5C54D688A0526A9B52605BD7D7BB01A63F3D1565CF78ED904BBE4AFA4A290EADFF9DC"
00181 "15659BAC162A818B6CDF38D2BC715144D44A1578BFC727423777784D15ACFE80FACAB61F9"
00182 "E58B5D3FFDB065A00C5D49DF0237EA6C488D7758F1A689DC59DBFF78261016A7C723FE52F"
00183 "FE571F5876FE0ED50FB00A90BB82B27BCAF5A67374284844E06BB1B2D84B1D20228F5C2208"
00184 "CA78BEEC2E95027B09372A309223A15C132543FF3A89B7AFBA56AA7A8DBE70E0805D3A5419"
00185 "1CC6884D75ED0FC00C06D9D488B0F4816E12D6C2A4324EF742AC8FF885E42100849DA05E3B"
00186 "7C451D43ADBEDDFFDD13076CD8D22BDA101F665B5878E321A009B970D1F4C48503CE3536554"
00187 "3B3F367868023E5C3FFDD756C95784E4F130904044660784ECD9C9161477F5BCEFC9898754"
00188 "0AD1E86CABD3EC7823D83877605FFC79820F1381DA29282C3C5B3443B6A67973F0622EA5DA"
00189 "A14FA239542EB140082F242958B39014486E5D5632C62C3EC8BE0E09E038C0ABD52B1322E0"
00190 "F7407FA3A8ED716858136CB371AED5E6FC9D32CADC8F870EE833B7120BC0278D9A05554D9"
00191 "0DBEB24ED6F5A8861698D48B4BF7AFE7763C1401572643E246DC65853996B0480D38DB7302"
00192 "3644093571737DCD0B416561B9511BA43CA34341FEF7954C28B2D9FF96EA110E0818309C32A"
00193 "D306DA077CC911299FAD6396C872F3F6AF7871395D7E67879EFED929E4C05AB4C09E8BB396"
00194 "048150A4161D7944CBD99C94DD16CD8E0D8BB73768B17EC02C0D4206AF623037D6F4257DAB"
00195 "4C07B4A6C0B4D2E0C9923FBAD3DFF7FDAB45F4E6BC5A895FAE4F5BB9EA247F2D4446E260F"
00196 "7988C452203EEA1DFA64DEC2DCC090BB3ABE13F6A8718F8DA2BE551407B59B8EF1806A6552"
00197 "6B6B872CB8922BB929F09341554A71E69B41B60987FE3A5E7E3424D947455083A827FFE27F"
00198 "B5BC5365C80998DE01CCDB66213575FB61B3E6F877D0E2E4EFDE4467D9F07B6A28148FE2FD"
00199 "GEDC9202F55FC8E55D0DF8C49E244C40CC3D95FC06C6778D397461BD157F4A0FFD91579980"
00200 "D55F52C96AEC0CC5A3E7A2151A845EECEE78B82ED9A217E326CF6C49F7D31C4D8ACAFD827E"
00201 "6ABB760150203448C000819E7E0B6E424C43A5500164CF128D686B4810D9838480604A8917"
00202 "92987FDC549D87F95BCA120AB84FCDD8C9F93F988C87E79599F3C1952BC0F7773BDFFC50B1"
00203 "9BDF8E3D8F52D887E45B643297650044E80124BEA0ED60FEC4449BB3BBE394CDF7CC7AA39B"
00204 "C1A5023044F6A843186C01EE1BF5834EB5401AF7905FC04447AE00DAC50B051B432F831FE5"
00205 "AA7506160CFDD7D4639C489ECA447F4F993AF0503CE5EF68A837FCF858B5993ECC55A9A367"
00206 "3F8F2C5CB8D3DD4C60E8421E3417EA958EF87E0764B061A39C32ABD5E0E3A712B54B0A3E2D"
00207 "351A0E00F4E901521C63C1F4ED829F6E259A1F720FDE96EA9CBB8F7BD7485531A81A49CDEF"
00208 "CE725493A04B5EAAAF7411DEACDE5A95AB6C2AA7BE3269F6AE4D166D8A5FD5264B135FF8361"
00209 "FF75B2FF22A61905A349C6B2C1DB2BD7B385B8FBD8C2768C7926F138D5F8107111563CE527"
00210 "322AC42E6BD42485668106B8CE91F157E0C94448869F7AABA255821DF981CD5298D40378FB"
00211 "E0E33AFDC78A0321F0AE268E69F7CF61E7E117BB463EDE3C7D2FE95987C66AC3E5C7D79C4"
00212 "4A7590BFCE998683701DAD7B98731DBCBA455E61428", // PRN 04
00213 "64D4236F326627BC08E9B2B96C1A9E5BA2631DCCA3F7A5B63736E4EA8074056DCD6BF0E5D6"
00214 "DB8845D9271C0D706F972AF22E652E3B2A7CC482B125EF8BE005F25D5109F6F9DD84DF966E"
00215 "2E088950FE1C01E2DF15205EC48BECEFB32511DCC39678F9DB08ED0EFF64C7B5DAED1DFD20"
00216 "2F63B6EDBCFB7E4FBB431718BBFA2B65594D78D3983B0457DDDB350AF2C1B9743AB9EFC260"
00217 "A78C31493A04B5EAAAF7411DEACDE5A95AB6C2AA7BE3269F6AE4D166D8A5FD5264B135FF8361"
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00868 "42746F14B8FA489DFAA9540B4D0470CB31F99B10C335F672C2E06E8A2378B9DD28E8F56BC7"
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01029 "5A70B5CC9855A39188FBBA8E6BA0F5B6538ACCAF394A809C68F81041BB81CE71F7DBB2A11"
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01033 "E7120D3AC2F24729A08B2B4C8D44EF807987C156DD3ED871B0A6217E9783A78BFE56C819F"
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01188 "511DE926AA24E776CB9C798058A7576E1F76ABFD2C86B8C741230D6D95ADE980ADEA22547B"
01189 "88E607AAA8C3462FA34114DFA46046848CB10482314D1240516AA7EC7160215A54F69EBC39"
01190 "FE4CC97EF710BB7EB855F9AC158B7F9C87B738FD993D2F0E35E4E9969FE5FC4B301BFCBA8A"
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01202 "64DE83CDCC023FD45860E09552303B8535B63E37FF038F2AAFDBBEFAC8BBBCF04EEB41BF1"
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01669 "2DDCA8C120538E1C0FD9922B33DC73C780C1149C4B294AFC5CD23CA8EFF423A3FEFD0EE1A5B0"
01670 "CB28964B8E80C42AB660665C4B5E06E44557689AC22196CE641644959BC7F80D1AA828DE7"
01671 "5CC21E0A8FD211BCF6185A7DA81222CAE0B632A7F98484ADD6E83A220CD49D5942B7D16309"
01672 "AB1DFB705852A2AD51EDD96DB3E318CAD7E96D5531193DB24B50D3EBF55DF8214093ED04"
01673 "91B037E1B38FBCEBD71199A063ED101C227A10313051F0B4BF4142057A73C491AEDBBE916CE"
01674 "4BC05D1A44FE7A2E7DD76CBD24C13F3758BF7E3BB8139690E33631F180ABA7425DE3E512B5"
01675 "3663CF9A8D1B2C08B86C655AD3A03FA8698A5F5AB5484E3CE53CDE1F3A466FCBD734D15BE"
01676 "B727B0FDFDF68BAE40299C73A8F455ED471C82F6DCE240B3BA4EF6364A56828FE2D6BD8DFF"
01677 "03F35FC6BCBDF0C907F7473F24938016615835D801598409F1004C478BB1B2283AEAB437BE"
01678 "EA2F5FC5D1D8E43F78C0092ED4D0B08FFBDF1CD60454D3BFE6EA1F41EDC5EEC06357DB4F73"
01679 "CAB23556634416369365D13FC8FF9E20EDD8FDEC673F0BD6C8A1EF60E394B596B70F751EF0"
01680 "D9D7E8D573E3526D2D90325B52A08D25F18DB0E6757EBB6002251809ED47C85D4FA37C5890"
01681 "D60B40BAE3AD2258BBEC4CEAA1B6B585EEF32615F7254268DB82532BACBD9C553624AFEAA6"
01682 "BE2AE9E1401F9BE05D68A881AC8D9E0CD437F60C00", // PRN 46
01683 "7831C1BA1031B6B0E0ECE28BC7E6A8ED1E3068E8F0006DA96B8740114397B19AA19370B1E"
01684 "1F061AEBC8953C0D0B7099668BE752BCD8B1CCBC497E06BB0F75AF47A36EF8925A59E07011"
01685 "5D3ED63C6D7FF554D037B4A818703F6D78BB37725D7F0AECF6CAF120A80C938FF44BFF1654"
01686 "4C7847B1A980598F1602A220392CAAC2EBC390FD53D15CFD3372426CA41DCF816E29C731FD"
01687 "CA2E84CF1A01039FB1AED0DB9630BC28D54201D5606906091A3F867D257C3A0F8193DCAB"
01688 "2625D40DE5EDE651C20F2DBC83FD551EF46C4E724D2C516560749AA89D35C7283385E98AB3"
01689 "4BB88F8ACF50A0EDCB70888DCBCCF0B792A5D1F2F6977FA081B4EB08BBDA076A43BF1EFCF1"
01690 "C387D5B92DEB5000B4139938CB0A3B6DFF47B729BB5826C7E188A177CF6DB1B88F051B537"
01691 "DA014B396645218DF4EFDB0DA597B3A78E9884DE4A7B3D06C259C10B78DEA1DB711CBA8FAA"
01692 "2CDF37EF0378091E408960B011F4E4FE24771D0FF3B8DD01DB0527087AC5C0F64EB693D38E"
01693 "A0128FBCB8053E811602A05F3DADF2166CE49EBA13F382E90EF4A143B2CF4FC12DD4873A40"
01694 "FF7354C6E648A56623457665402632C41942D23001C08470AAAF13FF0A474AC6586C76915F"
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01697 "B9F82B546462DB93D67E0C6748F943F39B8FD6791847C50A5A834A78C2FBE5D21448A035D"
01698 "83D45F9ECF44C21C4DE726AE8111CF277049331D78B06E9D7D3D0D8915C7C32CD6954D3704"
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01704 "DC886B4B83AEF5F34AF1A78DDF6B11C201760175D57823DEE0FA5C6A9C1A91638561B857E9"
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01711 "DBE78D851F89AFACAEA3A2A068C59654EF5E5BE2F6727136908D993434E5EB1B84331119DB"
01712 "1C02547EAEF7C9DD479C5B326CEA6224B1A2E108E76CDF0C54D16E472D0CBC80DAE7980713"
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01714 "8F82AE583A2EA454EE7548882C1A192F11345A3F5A3F2CF64B85DF6306F7FD396C4E773FA6"
01715 "6CC098DB3CF8E5599C2EA13A6F726161BB0C0D6673F02E3DB24FF75A5698E91C1522424D4"
01716 "43165B52C90FEFFCFCE6C42656138BD85409C45D8AC453D6742B42A43A762E70C212B7318"
01717 "834B7D29CAD0C29F22E6AC3A59359B1A75F727E1DC", // PRN 47
01718 "30B93A783620E3E094D47590AA38B10FF12C3E421887E9081F9A9C5BA1D753F341C33B7322"
01719 "187317C6610EFBD0382DBDC2D863C48F15AC3FA86B3C5A5B9EDB937AE961E8EBC3D880CC79"
01720 "141B79869F95D6E90C5C5E7D9448CDACCBDE184F6FB545324995184770CD2838B61376B148"
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01723 "81D1C98EE6FD6690914467048A50AF09435A68FF9A70B59DF8FA7A543BBA24EF8E13AA509C"
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01725 "83BCF8140629DA13D1289B7130F3714B8318518770EE1399CECF1D3074A65F8913596F92B"
01726 "269529B5FC63D824AC7B6390580C516BDA78BB1F158B2C69AD2FC1BC610AC24DA696F44B58"

01727 "DF813D9DA52529D325BF2B3575768DB43AC3BE5D0402C717FB587B6976E6701B0A70D04F32"
01728 "50B6C5AE999832B1057DFD9EB7B621504A1004E7E67B33B138628EC7C43A199D00D9FAB8B"
01729 "1990A5FF2964399051D1C62AD0D8B651E9DD94D27DD6A7B09AFBF1EC737B161A4A398F7F4"
01730 "24889C0BE6FBF8EBAE9F1A835FCF4AFD45FB36919D362CF73F0786D93552A7B4E421EFF9D6"
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01732 "08866DDE79F8AE34136B04787F6A5918F5AAEE705CFDD5071ACF8FF54A232FE39E1D79D82EF"
01733 "FCB6CE1B68A17B4585817CC9AC33FD6CA21A00929F1EE5B9E3518B27060867624D8262EA18"
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01735 "E519B3757092239BFC633C4A7099290FF7B99FEBF81DF5AC41366D3DAC3384C65AD0EC84F0"
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01740 "ECE83BOA3BB846FC37C7D4D2A37B2B841CFF9820DB444FB090B430D9714FE2ED731F097FD3"
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01744 "C593D15E1A56DCB03ACA1A5DBDB6E6FA9DD3D7D152E8FC1741BD876760F99CE780EA5BD0"
01745 "18022397587357614ED37266C69AFE4644D7D5259770B85B70E7E395D2ABCA3FAEDD5AB32C"
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01748 "049B37225742345E065720A81098B5785AF12927167ADD2F72F766292F421C290C2648E270"
01749 "C34443ABE5B9587E635B4CBEFF74478F65C77899418C8ABEA6A4C3FE217D784823CB448A7E"
01750 "C0739C7166F4AF733BE758B6D5011EAA9B05ED995DC70E3D5A2D2298801C25049661FC4CB"
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01753 "84D5B404488AFCC35CFC6EF1CF7A848EE5EE527B7D2D2081EBD8FA8432414FCCB271A43FD6"
01754 "18EF95CAF1CEF445B50F02AFDC6B41D5C1F1FF4B6B8F2AB94F90F259383F44246B2D400C30"
01755 "12FD76E2980827C9B5476C4651293CBE9FAA77EFC53E369B94F51BE480EEAA389D88AE421E"
01756 "75EC67C76E30A6FA7EF02500372E4C9AB875EBA1C357C003938B979859B0A914D58F21B3BF"
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01758 "260A26B3A46688E79E733E1E2F0010846937689E2998BC769186E0B977AE0A1689245D255A"
01759 "E7D5F34715AD526E824838B62546D9569009A191BA5192535E23142236F4035C90D1405C85"
01760 "30A57B402118FDED2A5DA4B40635D2F95AC7CEAA370686F0AB23AB31DED369BEFB066909B7"
01761 "6F2C04039E49FF0CFD323628D03C26F0BD4054C127F21355C33B49F86895D5354C3BBD2C0D"
01762 "38ECD169289F7D8403AA1753B93AC06C887F98315324DBD78F9BFD1AD8880D41D4EA98956"
01763 "EC89BBAD08F7CFEBF26988EB5AB01D4E49AA8273CAB6AFDFA1CC1C95EDF85284E6570332A"
01764 "0B8242FBA495D87A01A945E61CD36E865CD4F430F04A3B3EE74CE0486B5676F7A938B1E1D"
01765 "B2DAE2D67C04B3D65892C7394D0B07C5A2F7698D196711DC83FFF6ABDD4E8131E1106EBA23"
01766 "245FB0E2A696EA40FB6B0B1CB4DD22C9720AC76F09863711647A7E369FDE5D6911A5FCF987"
01767 "470B8C06CAF7063B08A8320B4371866789147E9D7C5D477A662A501627F91E95C6E2CB681"
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01770 "BFC53CD8F629FDB82186CB52EBE7136F105D3CFF9CCCC2610BF2C8F943DF5BD03877ED7AFA"
01771 "25CA81C4063E1B97452A937FCF77F1AA068FE2A26F6ECD662ACDF18391AF7D627C2AA07CF"
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01773 "EDC8C59DB0A91DA79C248D6894CAF9CB411F302635BEEF1A1C7916C7545B8BE7C577692245"
01774 "E285D32B4F18B1478F88F8373E22A5CEC6D22EACAD2A41612F05AB2C54A1C03C0512359B0"
01775 "F9C5F91615EF2EA80DE97230480F489FEDA38D52FC84E2F1258CB20FF0E850639B31C2958B"
01776 "A6C064D0D0F4AAEFF313E43C65EFFFB74CF09F2A122D15F76E8B704DA8F2B8C71449AA497"
01777 "74EBB7B2CDF97CF6004D2FF6D37B9C689261189B85CFD50C20C96122A644F5149737742655"
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01782 "E6270E27D46A25621F86A2BC4259DE6C04CCAA657FE65C640833B290F00A1660329A3F09F"
01783 "FE6015A23925D4DBB0933AC016B5802CA863F66F8CEB5C8383B1180A515AE6C51B5F56597"
01784 "C3A004F8D25F8A6235C97B4DE38468B63E3B859A487AFC4320598EB6D143E5C914409D25F6"
01785 "DFF6E957D575C71D3ECBC6743CCCC03E5F34791744637A994F3ADF86966B4FE911C06F7BA1"
01786 "A6C20A2971D82B64E49721A530D9D5A2319D5BE0F47B8119C5A835CABEC735A935E23CB439"
01787 "970437C6F4CCDE2525EF0D7B1555CBE70280D5E760", // PRN 49
01788 "A5029C9EB4623226D321FF78D3C4EAB1F672A8B2B24A09CAEF21F561A851323C05A3C5E136"
01789 "A2DA7104ED19FBFFCAC3FC49B6D598F3060E93552EA6C700B837F7CE04721919B9C96A57B4"
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01791 "9B20CA7F83DA0FDC2F171FDB72455B7ED0D43206992520CDD86B29C48BCC687573AAC4217D"
01792 "0B7DCF852811ADC3ECADD8B2B34B4572675CCAEFDAAA01F83561E6E240878F229698185A80E"
01793 "6FEECE89455A72A377C24CE3FECAEC2A34B9CA98D288596D1C769CDEAB06871316CA7D1DDC"
01794 "5862E682DECE33F362C64A73E57AB266715068932ECC31E62AD2ECFF7C6FBFE213384DA08"
01795 "6ADF49E30D7432EE2C715D9AC4DEF53A7B09BD722CAC560FE8CF0059B80428458282F7E817"
01796 "17647D72E321A3E4BEF16FAEF76009BD98B8D9822B771EB62F1D0748E462FB7F3BEE9B12AA"
01797 "86D9629085AEDF8A43E1252EE59970CF6F66A6F865C7651EF83F8FE10EB0E2615BF8F5C7F12"
01798 "FC601B0CF795C0D8B7057F54408BEFF86747C0F6F23EF212A9086EADD464A25341AB71FBA4"
01799 "ADED8F599C38FC15E790A5B86E64977C5AC718DD0B47C1A476AC9D7369396144F6288E84F7"
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01803 "32DA0E2610430461876FF6F77FF3CCAFA1BB2424B8B347588667B48480476D40BD9E487468C"
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01805 "4893B3F084291D964403F0350B7E1B06DFB73362C38318B762A972972BFB76CC5C08B5D47D"
01806 "BA0F3A2473D7749DE9F49F50C4C1620A9EE9FE56296124D72906497411DB87D4D8EC4E1F79"
01807 "BEF27232008A2299F5317FC1A6F455F1B827F1712BC01814F0B9D0CC162B25B804278B9C7B"
01808 "C5FC5616B317F2050234A7AF92FE35A59E22C959C7163DFA5F142022BE5CC4D5EF16D21821"
01809 "6C57C2E29D826436C00DCB82E68E16CA5A07158DB8864D38A765D14E82175114A28CD97D"
01810 "11D564C8C7B87411589A4FBD49F9900D08939B7A73B5E6466B6F607F8AD22120A559A02BFC"
01811 "EF6456E7AE8C89B7C9D2B322D2197124C053632CBFA58B74CD88877F22A5E5C202FC2C33"
01812 "531125F1518E40F38FA788E5E6B3307A75EC73E545391CEA200243DD6D25A5B8654A00B82"
01813 "BA57437BF0ACC0ED37ED2FED221E54EC12B93AFA6E3939223596075F4C74340355D722A8"

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01814 "234A1F65EDDA42FFF5D19F7FACBF09AA77E7962F4CFBF61A0F26FB18E31A504B3717140488"
01815 "74BBE286A9F71B43E4739A17E8AC25FA77121ABBE6E99754AF42F1D0021EA1E3FF088D0734"
01816 "BB191F91A520C96E22B4A28F9A2BD7DF81E8079EE5D0DDCDB517046F12098FAF6920E0EBA1"
01817 "0DE8CFB391C63C60D62C1F4BB26BF8B6E421A830575731F67D306CEB5D6FF04637144790EC"
01818 "4AA2F435906320114CB81EB40C22B271FBB065474687AA5880F1DBAAA1744AB3E9B831A932"
01819 "A9208BA9F5D526C52F5FDA56320E123CFB553E2B71A595DDED2ECBBD6E890B0421D765D2E"
01820 "9FD0D3995DF2A9523A65FE2040710DF16F2A83F510DCA08493DC138541E5681B51EE87D84C"
01821 "9AC11612EB5C06F5A63E22BD6275E35216766D79B215DBD087E9CADA0CEB09BFE435DF9B78"
01822 "09A76DE323B373682B8C58CB4F08D9C708EB050DEC", // PRN 50
01823 };
01824
01825 // Galileo E5a-Q primary codes
01826 constexpr size_t GALILEO_E5A_Q_PRIMARY_CODE_STR_LENGTH = 2558;
01827 constexpr char GALILEO_E5A_Q_PRIMARY_CODE[GALILEO_E5A_NUMBER_OF_CODES][2559] = {
01828     "515537AD5E5F4216C16046FB0AC50DCBBE5CEE7E3CBB51B6ABB4E87A407B90E0EFD49D1DE"
01829     "5ED29184E7FF0DC31F75FBB94F46FF6586B36C7771E5A68D060A965ACCF8D640C6B6E4530F"
01830     "DF19DD2491BCAB69ACBCFD3EC7281CCC31253A471B652E21C4CB0B43613EC542266460FA06"
01831     "1998436BEF95572DEBEE920A915FD854D17FFD0DF8C74E23B21B28493A0927709709B07C6"
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02798 "71968009ED5364774644E995DCB33A41D53B3C9C1BE952449CA8E671E15EA888789CCDFCDC"
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02800 "BC92C0D17868986BF2BA8127BF95E159776570E273393FEFE203FB079780E675BD62F475"
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02804 "F4F1CC30E75B6A1B67FDA687E672E7136AED3E02F8CC346F520E5929526B6E9126450E708D"
02805 "30168D1A60B41D19949AA4BA5CB7A691DB90A7B5040B01518FDDB6035454280BEF79E019FB"
02806 "96D899DF7BBA47D0A7EBB39A11A84036659598294B0B9A905CE2E0CBA0E3BAC855FEF2CD34"
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02811 "E7FCB458BA2F9C44E14589D2805A904AF02FD3693DE69D0CAC00E058B26277018C3339EDA8"
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02814 "8E4D2EF96E5FAD8BD3EDF830FF2B12829E97C5C57927E69A438737B1920553F2B921E62A3E"
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02962 "82E75BC2CB2DCA0E9A43717B6A157070C77A8A3B5DD1E30AAB09F5368F46F66575599C042"
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02964 "DB8A2D820BF372E795957D59ADE6A72C265D19C852312BFDACCA65431B9AF4DA6AD56B97E"
02965 "9FDA9AE465C9165037F353D9BE92322B4383C30404706D102F15D8D39B21D22E0B23FFB0A"
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03018 "E0DAFB980D888AA2580DB37930D1942D6D088FDC706871A90D887B5F2CA6B21911BBB8BFEE"
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03122 "B5466B266562E2186FE01D028CD4AB5B6AC9F048D8", // PRN 37
03123 "D50CD8EB871C5F371648DC07E20BE84263CD676282D56EA5374E21B52752DBE416DB787BCE"
03124 "232226568621ED792A9135A59849451A4A4D8A1DCFC3804AF966881FE5156FB761B3736F42"
03125 "82240FC0BBE72F51F0122D96B3755109E7CDFC70F9DD04C58B4A51C00B4FC0EF252B05ED76"
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03127 "9919621E8C4E920E08061D228038F73F8E5DD66BAB806D2DD953C6FA5360487957912249DE"
03128 "009655658BE8CACF00E6E0621739648A7A75EA06E93946987E62EDC270B266BBBCEF61D7CC"
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03130 "901A3DDFF16EF1E1685EA1F92B1F32DFED2F9076EF9CB1ADD8B04953E5509B24C48977FFEE"
03131 "6044B8C5B80F9DED6FA7110C3A2EA42EEE8A83F4A28FE78B27E84AAE7B3FABA56C1A4D2414"
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03133 "F1B9C8288105489624C03DECE74976228B119974BC546F823A597C7486DD594F1FEB2B6D03"
03134 "30918936DCBC12E3752A7072C5FD7B145571DC4A22C770E00F24B8C91E27F2C727FB049D04"
03135 "BCA813948D2F7B531C906F2018F51C9EF8B7642C0F1CC06AD338BEDE17683E0BD2A90D4D47"
03136 "46189F7925037E4918D2D6E61C1C8A8B6C437075ABC38913C250BBEEDDA5CD24B630AB8"
03137 "FE9123B08D5E8FB8B71BC95BDA4AF1A71D5E54BE98B16D7D3083AB1649CBBBF44B3D5DC33B"
03138 "77DC1171A66F6F40E75EB86801EAA36E02D138093F28ECC6DA4CE4B128DAFB8D49A17C683F"
03139 "FAA8E6910B8BB7B832B3A3D0765DE2ECDAD97BFF0A822F5FD389A04B660F832687CD677E1"
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03159 "FE4225F576026F79010AED56CE915AD9AC001447CDCB7CC3846B0E291DE0E9E443984E0ABF"
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03161 "32612870B0EA23CDA21E3B6E851B063BC76FBF7BC394A7D3805D45616C6A313C887D2FDC51"
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03190 "98AD0CDD61D2FCDC360C66DFDE0AFF0E8A7B26359606CD4F47D28DE115261E6F98F323FBDF"
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03196 "E9EFF6DA22EF3DBE0FAA6DDFFB5D8C265D1A1855CF7019D8659062AD7A705362D1510ED501"
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03198 "8C2B531F06805D92FE53D45B9A6FA530E3D6A2F467AECA07D29E1E9123247C69220E2B9D4"
03199 "501EE42E5BDAD07F0D092B33A938B8FC0EB7E435713E3E428E87DB24AC570E4EF64840A1B4"
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03225 "344584AA8522B63FB34BAD2122F9FEE1245E6DC837DB032387EFF5036A021C8112CDF03BEE"
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03286 "61D7F4C6755D4DB0F288341D5E525B15F2BDA314DA38D2B2C7CD7D64F6DE35EE782A076333"
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03289 "EB6EBF5F5FFEAC8441BD1103D2151689BFCF8D4E29B9C39B1BE4972186B099C2C35572DB1B"
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03294 "4704DA5A9237F1AA52E12C821BB0F54C0820AF8124AE6D0F4BFECDA6500995B2B61ECB062"
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03446 "CF5C9E178A8FFA032A454908BBE41E13D829FA98C066A7736577CDEFC6D5441656D0AC95C8"
03447 "72861BCE0A282ED6E9420D4D167F37F96087F9E761F38B882CD41521DE8E2C40564C0E001"
03448 "EDBC0482669B82F05CD0411A6BADD8CB704B545FCB19A286BFFAF0FB6DC889BCE75C5763BE"
03449 "1D70DCAD1D39F395A75E637E0663F3D5A855F53F700AF5F82124E72CC2A4E41A4B43FCBA41"
03450 "E55298A1B799368BD5F9B507FB11E8BD2D80FE517A5FA935006064278CDDC5EED43B7C2D30"
03451 "9BECCCB2C0AE3B8D09509315933E2DF91304B1DD3777EC9FA2415F7D18A96CD08095A30F7"
03452 "EB9BC12F8739E409EE7DC062703CB3EA591531F47F5D1C0431E9F1883C3BA249492EE61971"
03453 "9C8B3BDFC1DEC7E3C4CE4CE032FB2882247D1D54566E3819464837C248D35647D273A87F8"
03454 "BE667760D26A7EA1FFA682A931A4D35F7407FBBBAD725BEA62449623AADE97A2789F2F8642"
03455 "F1EC12A06C93861DE9D27C5ACE0E4ECE40B58664176113ED6437B8AC8A0459653EA30F71A0"
03456 "23544BFFA685343E278129DA12EEAADBDD5AB0E2CCA0B840E87AFA0D0E859449893276B9B58"
03457 "94EB0C57C3222E01E7538FF7E91807C10CDB465A12CCD358151D96856C6143C9F8D25AF8E8"
03458 "086C83D4CAE37BD660D15C0C0707691E8366C4AFE6DC0AE1BFCECF9BEF46CFEA3356A3155E"
03459 "027D1C921E8852BA4B8FE8E0C8C00829CEE4049A21A1C3424D2BE532B735232D12B81C3C9"
03460 "E5B02294701E6BCBC86072AFCFB2DD9B1142B4D261418C1B239B0B22451D7D3AC64636B0C"
03461 "7F96B41D7E775C1CFA2E277C957F0D59BD1FB02226A462533850E99E917E310A684E81634F"
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03463 "6916EF35C5D4871E94B1671493FDBC497BFA30328DD24D340A07A960828A855FA95EE33FE4"
03464 "FCD15B14B7929D338611239AC34FDA6503E4DD9570EC339CFDC8D1C3D3536F5176901D012"
03465 "BABB133EBB4560484344E044F86A77C21183C82BB2B6632CF69F5A661C98EFD5529F8B96"
03466 "5DCC6AF185CA8CDB4D01C5E8902966B063B8D1724AD18DAE495AD47416B61321DEEBF782EF"

03467 "7A6ADE3CD0D5B9ECA84DB5D50C2E5C7D8B8DB9E0F398376CDE3D7E8DC46F0D77D38D6CF605"
03468 "5D6D074CBA92A27C6F9018CAE87C97F1B3ACCEE495ED9DCE46DF4FA5255DB2C7F2669F5201"
03469 "058E90F7567672162E17D5B6D028C6AD23F2AEB3A32061E6B33EA86915FAFA2344CC58162C0"
03470 "32CE837D5C32F5993013314BD261DE6EBB35B94B8F690C5624A8CF5509BF50D3AF5FDAD773"
03471 "11B6D6F9398213AC1A267CAA0F52A262DA4F85F5ADC79947D2C5128B8E0B0C41B9FDEEF6AE"
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03473 "4B7593A9ED7897766CACD515D3A55959FF99C1CE28A745DEC1D8F2565F24F4A1E14E9083AF"
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03478 "2D3941F802DD2C731403ACD856A3AEE6ED7F23023BAD7BF138C702B6449E2601042D7990AD"
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03480 "21E18FEED2F93C268A2D3EA012F3D7F68DB0B18A5CDEBE13CE4A05683947DD985D4AED1E19"
03481 "2FBDE719755846C9B758FC8FF28B9999D07E634645064C2C9DB4CFE50BB8A030B60F43AFBD"
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03512 "075A165EDE0A58F6CF6D215D306A7840CBECD0E87E3AD186F7A67A967373551E13D2956E5C"
03513 "578A7F5BD50E2D570F9B914848D46A640913EBED2E2ABFB86916BC34EEB3E8A671AD771F6D"
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03515 "A1B0E5F2DF7E1E45DB6D4BE2B76535A817F94594A4541C01BB62AA83A690B6D84FC13B632"
03516 "972C61D940F2C9D32837413AF8E42045ECA3072CD044B2183400CE63C418879D13FD281A8D"
03517 "08352568DD2BC3C9750C1D44CF1037FD7264B7716398FCF1D31CFDFD0B7C52C6370E4CE6FC1"
03518 "63B40436490A757465B20B8890C3B5C0AFB971ABFD01796569E3BC73C13D1E4B1FBC1CDE5"
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03529 "68B7BBB0A974C69A8F79ECF8D379DC13685D2A8F6F19CE102C3DE34B11422AFB42E894C8"
03530 "D00F606296DABA7123FCE039ED27324D60E853BA94DC638454088281335D437A954333FF1A"
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03532 "B00C8900AD4E0532C5ECBC94513DD9F50BE511CFE4D3DDBB3F112AE148DB062B2EADDB901C"
03533 "DA6AB6BF59D37F356AB34AF97D3ADAAA417642E87C9B95AA546C682ED641214605F82A4F48"
03534 "6C9C72576106F76D7152615EC8E77187D4485071CFC6B0AE44880442790696E057A3AE20C8"
03535 "60691353B3F6BEC5F1C2DA07563B423BC01E0334099571158A432441256D7C409B7B6EF264"
03536 "42075ED17E2BE37F8EBC049CFBE0FA89CDA7A58DD32C417B34E899FBE86E2FAB8D30846DA1"
03537 "7144A6A6AAE1C24FCFABDA5B573FD26337226B5E49BB031B4D2B455B6DB871076F67AC03"
03538 "C3A73CEC01BD0B1EC42ABD177127E62A66FE8E475B982B4490F0877466EEFC7317A703C5C0"
03539 "7937340ED4B53E5DE5325197FA31B8C8E05AA2222064EE5D7C06D4A1EB53151F75C94A2E25"
03540 "9688C60716548465C5C255D81FF10BACC2C13098ED8CF7F5B15193EE14FB5D258E95EDCC93"
03541 "E9796FA823892C705A5771D561787C12592D269D657FBB71F021F365B7453D50C35F748FB2"
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03543 "53DA0E7B84741AA9E225483630169ACBCC03EB8CDA28B7BDA685C756D66B14488A2D0AEF7E"
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03545 "F85456B37F32FC8CDE50882EF0F09BE4ED4AB9A425806A49E8347A42A50B38FA8D1DA2FD2C"
03546 "9438618B6701DEE159060C186D50170F24F38E07B185E3272EAEA4A0A7CA41A69C6E9D95E"
03547 "271287D3AB8284146A58440EA131A7F47D73CB2BCF40FE3A58E1B998C2E5EF9CEEC8EA2F84"
03548 "67BB7757C0A99FC8F014EE933A7080CD46625A2A7A251B7A37E4208956A8C9BD35E6B8674"
03549 "BC06FCAA5DD04A2558C9665C7985014D3AD95ED256FAFA358962EF5BB26AE2FCE899392DF8"
03550 "58F99303E2417BCA7672E991FEB891F5DFCA2D461148367C5C0DE1460BF557194533DAF01A"
03551 "5E8E0E43D57B825AF7EEFF163DA23B9F95C063A26B3D213459D885AA96023715CD21DFA2A"
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03556      "84D6722499A6310FA449D979030B2A21206D44225800BE2228FA00AE6D92C8DA652E1B003B"  
03557      "D2734D30557B735CC2A591E090394DB791245C22B4D29E706476593B6F90C694C5B87BBB0F"  
03558      "A2C479E292A768A9687A713336A21D1199186F852C41F586E9BBC64004D8BB6814BFE73983"  
03559      "4C99923177AAF87B926D56A7AFC0879C027332A60951C84E9314380A5A78E1196D094F15D8"  
03560      "56AA36742825D2B397156BCAD8ABE7291FB41DB4365AAE49CA82CA066D3B4366D3122ABBC0"  
03561      "0F05559DAFEBA9F98361DDAEF068D60B18265E7184C4D6BC9C3619CFF5C758090FF6398CCC"  
03562      "EB78176D2A8A2A4B9854C4ACF5CB614DC1CA0E15E7E85442241D48FD3D6E851A5D3947FA76"  
03563      "9560928948FA26FA16EFBD2159994BD92B3D6B0C62818C91D4724413A7F40B2A2D67F4FC97"  
03564      "B5DF6A7E3CEC03158E201D6643F402D3DD6995A42900D46C2881198CAD28A27489F5116ECE"  
03565      "C3E38D999B2020E0C381DB3B8230811270D75950D9BB61548802DBBCB68ED8C7BCCB50D606"  
03566      "BE400BECF873498621E66ABD2AA179B3E90E055C3719CE2FE047F815B95B065BA086B467AF"  
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03569      "4892278688B3ECA612452B590AF38DBDD9A7070C5610E7A3CA6C91D24438E7F45E7A2A330F"  
03570      "164AEDFFF1789D5E875EEF121298DB79C77278ABFEC3FE3DF843C46F40E847272EB2669BAB"  
03571      "A808C38E31F13516B5066AF4DFCE6EDB2FF0B0A4CE9FA9B4101F6F144B02384868617CD39"  
03572      "175852E065473D6F566CD18D7403FFD24DD33ADDB52C7CC22167E49102C46DC369A92CE2D2"  
03573      "FCB81B4D1F14B7CD2F80A65D8FBD20FDA23219873ACB8CF934E68D6F8FED6B41193CFAB1F"  
03574      "44CE4BFC7C67DE1E8804B47DFD7E8AE281E19846AEB6FF94AE7E7CF6FFAB46242843811E6C"  
03575      "5BDB78157C76DF4F92FD3653D7FA5978316EB055059C6A2B6306C957418860A88F63355E76"  
03576      "D96F4727128D9B3EB98501AF5B093F2C314F98EA2CDB89468E1BD51138CBF25E8B911C26B9"  
03577      "7DCCA47F1A1D6C1CD415A5079A756B8A8715DD3164", // PRN 50  
03578  };  
03579  
03580  // Galileo E5a-I secondary code  
03581  constexpr char GALILEO_E5A_I_SECONDARY_CODE[] = "10000100001011101001";  
03582  
03583  // Galileo E5a-Q secondary codes  
03584  constexpr size_t GALILEO_E5A_Q_SECONDARY_CODE_STR_LENGTH = 100;  
03585  constexpr char GALILEO_E5A_Q_SECONDARY_CODE[GALILEO_E5A_NUMBER_OF_CODES][101] = {  
03586  
03587      "10000011111101101111011010011101100011101101110000101010100000100011111011100011001001101100011100",  
03588      "0110011001010101100010111101001111001110000011000111011110010010111010000011001101010000010100100101",  
03589      "010110011010000000100101101010011100000110101111000001100101000110110111011100110101000001110000001",  
03590      "110100111010001100100110010000000111000001011101111011000110001110010011011110110101010010110111",  
03591      "10111001000111111100101011010111011101100000110000100001100011111010010110010011001000101010010011",  
03592      "1011101011000111011111101001001100111010011101111001000101000000111000010010100111101111110011000",  
03593      "010100110111011110000101110111100010100000001001001001111000110101101011000101110100110011101110110",  
03594      "11101111110010101011010010110110010111100111000010100110001110110010100010001000100101111100010",  
03595      "011110011111100011001010111010000011000010001110101111010100101011000010010111101111110010011011",  
03596      "11001010010100010111000011111101010001110101000000100001101100011000000110101101100110010010100",  
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03598      "11111110000010101001110101111101101011000100010011100100001011001011100101011101001001100001",  
03599      "1011000000110000011000101101110000101011011100011001100101011101010110110110001011011111011011110",  
03600      "1111011011000011100110001001100100111111010110011000111000101101111010000100011010111010101",  
03601      "000110111011001011110111000101101011111100100100001110010101110001011100111100010110100001",  
03602      "00101111100100100000011010000111110100100011100011001100011100000100011011101110101011111001001",  
03603      "00110100000101100011100010000110111110001001101101011111100101010010010010110111110110111000",  
03604      "0110011010101000011100101100111001000111000001100111111011001011011111101010101100010010110101101",  
03605      "1001100111010101101001110000000101100010110010010010000001000100101110111001110011100001110010101000",  
03606      "100000011101011100011011110101011100000010100110100111101011001100101111010111000110011011001010",  
03607      "101001100101010001010010010000000111010010100111100110011100000001101101110011101001111011000110",  
03608      "1100001100111001011010100001000000011011110110110101111011000100011110011111000101011101100110111",  
03609      "1100001111010100101010110010000100011101111001101101111001000010001000111100100001010000111001101",  
03610      "0011110111111110010010111101010111001101100001011100110010011001011010111100010100010111000001",  
03611      "100110010100100100001001111000000110101011111010111000011001101111000111000100100000001010110101",  
03612      "101110010011100001010011010101010010001011010001000110011111010000001100001001011111101101011101100",  
03613      "11000111000110101011010101001001110000000100100100010101001101110000001001100111001100100001010111",
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03614 "000011001101101110001100100111100111101101010011111010101011111010110110000101000000101100101111011",
03615 "01100001110001011111101000100101001011110001101011111000000100010100010001110110011001001001001111",
03616 "0110001001100000001001110111011110001111101001111000110101110110100101110101001111010010110011101",
03617 "11100111010001010100000100101111111010100111101111010111101000000111110001110010011010011000110011",
03618 "0011010110010010101011000000100000011111001100010111010111111010011100100100011000111001000010011000",
03619 "010100100010100001001101100101000001110000111101110010101111001001110010000111011101101100011111101",
03620 "011100111011001111011000111100001010110101010101110111110100111111010000001010011101101100010010000",
03621 "1001010010111111000101101100100000011011110101110100011000101111011001001001100011100000001010000010",
03622 "10101000110000111101111000011010110001100110100000001000100110110000101101000101101100110101111001",
03623 "001000101101011011100010101001110110100011100101111100110101111111111001000111000000001011110010110",
03624 "0010010100110001000010100000011001100111010111101011001001110001111100101010000010011110101000011101",
03625 "10011111011110011001001111000110001000011101010010111110110010000001101000000101001101011100000011",
03626 "11010110001010011001100111101010110011110001110010011001000010000001111000000101101001010010000010111",
03627 "1111011001100101101001111110101001000100000110111010101001001110101000001101000000010000011110001100",
03628 "0100011011110011110100110000010000111111001001001100110111010101111010110111101111001010101000011",
03629 "111000101110001111101000001001010100011000010110101111011001011011001110111110010100110010100011010",
03630 "1110010101001000001000110001101010000010111110011010000000011010000110011101101011110000110110010",
03631 "0010011001011100011111110010000101000010110111101001001111011011110001010101001110000011011001000",
03632 "001101100100101000111010100111101011000011110000010010000001110110100000000110011001110101111101010",
03633 "100110000001000010100111101010001001100010010110000100100110001110100000111101110100100111110101010",
03634 };
03635
03636 /** \} */
03637 /** \} */
03638 #endif // GNSS_SDR_GALILEO_E5A_H

```

13.741 Galileo_E5b.h File Reference

Defines system parameters for Galileo E5b signal and NAV data.

```

#include "MATH_CONSTANTS.h"
#include "gnss_frequencies.h"
#include <stddef>
#include <stdint>

```

Variables

- constexpr double [GALILEO_E5B_FREQ_HZ](#) = [FREQ7](#)
Galileo E5b carrier frequency [Hz].
- constexpr double [GALILEO_E5B_CODE_CHIP_RATE_CPS](#) = [1.023e7](#)
Galileo E5b code rate [chips/s].
- constexpr double [GALILEO_E5B_I_TIERED_CODE_PERIOD_S](#) = [0.004](#)
Galileo E5b-I tiered code period [s].
- constexpr double [GALILEO_E5B_Q_TIERED_CODE_PERIOD_S](#) = [0.100](#)
Galileo E5b-Q tiered code period [s].
- constexpr double [GALILEO_E5B_CODE_PERIOD_S](#) = [0.001](#)
Galileo E5b primary code period [s].
- constexpr int32_t [GALILEO_E5B_CODE_PERIOD_MS](#) = [1](#)
Galileo E5b primary code period [ms].
- constexpr int32_t [GALILEO_E5B_CODE_LENGTH_CHIPS](#) = [10230](#)

- Galileo E5b primary code length [chips].*
- constexpr int32_t `GALILEO_E5B_I_SECONDARY_CODE_LENGTH` = 4
- Galileo E5b-I secondary code length [chips].*
- constexpr int32_t `GALILEO_E5B_Q_SECONDARY_CODE_LENGTH` = 100
- Galileo E5b-Q secondary code length [chips].*
- constexpr int32_t `GALILEO_E5B_SYMBOL_RATE_BPS` = 250
- Galileo E5b symbol rate [bits/second].*
- constexpr int32_t `GALILEO_E5B_NUMBER_OF_CODES` = 50
- constexpr int32_t `GALILEO_E5B_HISTORY_DEEP` = 100
- constexpr uint32_t `GALILEO_E5B_OPT_ACQ_FS_SPS` = 10000000
- Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.*
- constexpr char `GALILEO_E5B_I_SECONDARY_CODE` [5] = "1110"
- constexpr size_t `GALILEO_E5B_I_PRIMARY_CODE_STR_LENGTH` = 2558
- constexpr char `GALILEO_E5B_I_PRIMARY_CODE` [`GALILEO_E5B_NUMBER_OF_CODES`][2559]
- constexpr size_t `GALILEO_E5B_Q_PRIMARY_CODE_STR_LENGTH` = 2558
- constexpr char `GALILEO_E5B_Q_PRIMARY_CODE` [`GALILEO_E5B_NUMBER_OF_CODES`][2559]
- constexpr size_t `GALILEO_E5B_Q_SECONDARY_CODE_STR_LENGTH` = 100
- constexpr char `GALILEO_E5B_Q_SECONDARY_CODE` [`GALILEO_E5B_NUMBER_OF_CODES`][101]

13.741.1 Detailed Description

Defines system parameters for Galileo E5b signal and NAV data.

Author

Piyush Gupta, 2020. piyush04111999@gmail.com

Note

Code added as part of GSoC 2020 program.

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.
 Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors) SPDX-License-Identifier: GPL-3.0-or-later
 Definition in file [Galileo_E5b.h](#).

13.742 Galileo_E5b.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file Galileo_E5b.h
00003  * \brief Defines system parameters for Galileo E5b signal and NAV data
00004  * \author Piyush Gupta, 2020. piyush04111999@gmail.com
00005  * \note Code added as part of GSoC 2020 program.
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GALILEO_E5B_H
00019 #define GNSS_SDR_GALILEO_E5B_H
00020
00021 #include "MATH_CONSTANTS.h"
00022 #include "gnss_frequencies.h"
00023 #include <stdint>
00024 #include <stdint>
00025
00026 /** \addtogroup Core
00027  * \{ */
00028 /** \addtogroup System_Parameters
00029  * \{ */

```

```
00030
00031
00032 // Carrier and code frequencies
00033 constexpr double GALILEO_E5B_FREQ_HZ = FREQ7;          //!< Galileo E5b carrier frequency [Hz]
00034 constexpr double GALILEO_E5B_CODE_CHIP_RATE_CPS = 1.023e7;  //!< Galileo E5b code rate [chips/s]
00035 constexpr double GALILEO_E5B_I_TIERED_CODE_PERIOD_S = 0.004;  //!< Galileo E5b-I tiered code period
    [s]
00036 constexpr double GALILEO_E5B_Q_TIERED_CODE_PERIOD_S = 0.100;  //!< Galileo E5b-Q tiered code period
    [s]
00037 constexpr double GALILEO_E5B_CODE_PERIOD_S = 0.001;          //!< Galileo E5b primary code period [s]
00038 constexpr int32_t GALILEO_E5B_CODE_PERIOD_MS = 1;            //!< Galileo E5b primary code period
    [ms]
00039 constexpr int32_t GALILEO_E5B_CODE_LENGTH_CHIPS = 10230;      //!< Galileo E5b primary code length
    [chips]
00040 constexpr int32_t GALILEO_E5B_I_SECONDARY_CODE_LENGTH = 4;     //!< Galileo E5b-I secondary code length
    [chips]
00041 constexpr int32_t GALILEO_E5B_Q_SECONDARY_CODE_LENGTH = 100;   //!< Galileo E5b-Q secondary code length
    [chips]
00042 constexpr int32_t GALILEO_E5B_SYMBOL_RATE_BPS = 250;          //!< Galileo E5b symbol rate
    [bits/second]
00043 constexpr int32_t GALILEO_E5B_NUMBER_OF_CODES = 50;
00044
00045
00046 // OBSERVABLE HISTORY DEEP FOR INTERPOLATION
00047 constexpr int32_t GALILEO_E5B_HISTORY_DEEP = 100;
00048
00049 // optimum parameters
00050 constexpr uint32_t GALILEO_E5B_OPT_ACQ_FS_SPS = 10000000;      //!< Sampling frequency that maximizes the
    acquisition SNR while using a non-multiple of chip rate
00051
00052 // Galileo E5b-I secondary code
00053 constexpr char GALILEO_E5B_I_SECONDARY_CODE[5] = "1110";
00054
00055 // Galileo E5b-I primary codes
00056 constexpr size_t GALILEO_E5B_I_PRIMARY_CODE_STR_LENGTH = 2558;
00057 constexpr char GALILEO_E5B_I_PRIMARY_CODE[GALILEO_E5B_NUMBER_OF_CODES][2559] = {
00058     "C5BEA11BADD79BC7A91DC8DBED9A215B8FFFE4978A981C98CDEECE756A364B33FF851B7B3A"
00059     "FDEA0564CF9DA207C784E13542404E3BDE45C1DD70B4D6B51C88E3ED42A1C524E0BA5441A9"
00060     "C8766013E712313070BDFAD3699A226B719410EF18EDC843818877FEF748A0D7C6AA366163"
00061     "30A087CB91058D7F1A245311AC571864DF734F99E3E643AB7627B4CB57DADC23E4D22C5F2E"
00062     "3D2FBD4F04DF616E8110A001565B030C993141FE038670F574DCC4DF46C8DC18C84B449106"
00063     "9D1CAB4BB923AE6CD41BB9528ED40F7D139CD425416EB2D6342AB8808009A40C042F153DF2"
00064     "3C8B14F3F7235FAEBC9AFE0C845AD41F40E2FF7A7FB82971E014C9269C60AFE05F694AEFE3"
00065     "2B3194956253AC39AD42E0B7575F96CF2A094011C91A2FD3A10C02CB42D3425A3D6D85B404"
00066     "CDE1171ADC81B5EE752F5783DFA14A7E26507C231FA5541FD06330ED44E37DDA40008A91BA"
00067     "74EFACBBB617C7EDFA3DDE592EA284381EF17477038A8B7ABF3C5BD673D658D11A22B97DA9"
00068     "F247FECF2143D69468CF8A112A69FD3E9488F14AB1506DB1240F26C52D2F19AE7A81A39E9B"
00069     "9304F65CB7FB39B4404679701216BDEF9F9E576EB36F7C9D77847A8FC40A7D7C4C65C8D78"
00070     "BD82FC7E5F90C6BE1CF19A2B7576DB1547A26C24E5F9BE97D2AED0A71BDEF74B26F92B0CAA"
00071     "A683DD3412BC52C7BD443F32EB3E39B2C9B1CD6B274C825AC7618CADE08D9991E5150281E2"
00072     "D9076EA58B2A99C54236A1E93F4D467692766080113C58FC53093C739FA8B0CB85DD0B6683"
00073     "CCDFC0907EB124E79C33C3EAC7CDF8E9F679B87B4FA71688BADC1DEE44FCE4952CAFEB0D3D"
00074     "6432F0775E3B6F34D18A24233A39C0B59A1F458B9F28B958539193A054DA2AC02B60D1146A"
00075     "1C6D5B86DE1BC424C2C7C703CAF92997E09A345AC0243EEB72468B161E5CE268DFE2A76B10"
00076     "F84DEC801F5F20419D9C326E7AB0BA22BD4225CDD990DE4A0C7E8C60E24A385DEC7F342E8E"
00077     "5BDA079ECA357DEE07A2E1690CBB8C28247B6E13AB795D6DE97FA074596DEE8B5846E8D904"
00078     "39B61BD71C228D10C7BC45886288F33654F787B4D336950EE6CB2989EF35D14200B9082C08"
00079     "5C6EFCAD497A12A053543DEE352E4AAEC83858967441F7023B90E263E8476D53E23FCA4805"
00080     "99FF7FA69C006271E1353CC546E04FDA1D6E2EE8DDA422F25216522B9657FD3D02CBA10247"
00081     "98C00CC2396154E2DEEEEF4EE6E25C8C980C2B78991C545C09AAD403A0D3D16FFB8C485C15"
00082     "D93A160AB2DF82968811A25030688196C7208D66269EAC5C17CC4F00BB35CF85BC73DEDFE1"
00083     "CE66547D6C7873135A351E4C4335C257694D766CFE21440BE04432BE32583A166569FA7C5"
00084     "ECA0DF8D74BEC43F44D914A707902234E9A9E5C68FC472C8DE48C5E96071A1999108DF98"
00085     "00F8D1141E18F376C9A422A73C21535D055080845586C931FE8600366FBE3C80522D32EAC"
00086     "06E9005B545F5937C64AA152226F66E100B183690347C53698ADC5B8FEDAAB5D36823A1"
00087     "3F775B295EA8FD2EB09C23B80A3E96AC1580124E027004CB0A488FB2DDCD739E8BAF4B47B7"
00088     "539D2D7E3E79FB67255F5CEDBA801026A6DF3389A205DCDE967AE8F0BC766A53465E46AB20"
00089     "A67B379B11546D66E385B963CEC31C4B832C62F417122CEB158DCB5D042A7290371BA41E"
00090     "9B59FE6379BDEE02FE476C9194F27E67B6953CDF9FE738A7B8256B2F8789D5679A5A172C46"
00091     "97117695E598BE1FAEABEF94D2B7E08ACDD9D9FA341A47D211123C6DFB12330142B8171DDF"
00092     "404225E20A90CD94DC00B1627B704BFBF6264A74C", // PRN 01
00093     "4F62483A58B2AA45A7F0B344DFA1C95568646AE79869337332CF0FB02D7A9A91633F160EC7"
00094     "D50EB74D2FBD3050B16E2E264EFC804070A7845AB5903A986183DF0F7146DE5BC923841446"
00095     "46BDB346E3A6E436FEB19E16C324B001C4CA6D4B223874D15032F743481B2E4D8B0D77B23"
00096     "BBEDCD2ADC458C23180C1632887694F12949B95584ADF4040F21E2F47F1F1F5E4E7FC3AD65"
00097     "21FD18CAD7FEC9EB2BC1CF3C04AB70E54E55A31F654634A1D29005CDF05797D3E7FD5B2B94"
00098     "398BCE5A56D2B0BA49C79066A5866FABFF8D59582FA407E795189B3AFC33B798F672FD41E"
00099     "6806D877ED31A4614627F6D46011FC6153A9F3143018BCEE9A0F98FF48194AE7C51539C175"
00100     "B66C5AFE7C9BCCF8D6B4926122EFEE9AE07CECAAF783BD40AD8376A95A0345A3EF7DC8F8"
00101     "8237E25BDF6F509AFF85DE7C7101CF51766E6B4419424A10F15BF4343BBE845E5F6279FF54"
00102     "4577F26DAAE7522580AC9EC833D3021AF903BAEA8CC53B5F0A630639789CDA3CA6FC72F96E"
00103     "F17EE975366610DBE3DA5063955CA0DB7FD3318E14AFAA514CBDC864F40261D54EC284F510"
00104     "6A1F385409CF82CDB91D535B470A883B08D2167435E2533D123A7B71FFC8914A370923B121"
00105     "4F5341C2D65BC868570185F2472E93E77FAE64BBB112A2E7B63F2117214B9BD0B2D9029AEA"
00106     "EA8F6E6A70F18D178B0B4D26AF7F5FDC8CF149B6744EF28F77B7D87DCC92D0E2CEF3977D38"
00107     "E8920F71D89846CA5DE3F4FD76D51A0B5B69A6589774EC227CEC64B16217EB5B37EFF5CA"
00108     "78B5DFBAAD361DE5E606627EBA04F5FADBA5224A6C38F63289E9874A56180B5C57DC188A62"
```

00109 "E1BC314488F06E728399066FB9EBDEBFCB2F20466CB0C6EE1B2B8B158B769C40409838D95E"
00110 "C5EB52E169DDFDF0946700852FA1F10436E2C093E257DC969C5D3195CC4DA6E376CB1A915"
00111 "A92519EE1EB2034CE3C55AF3C242D7D74832D46D532F9797268C3B0DAABD705945F4EC5514"
00112 "19E94E84A13E75AC428B2559C2076333DED3A6E9CB604751E2FDF379B9A1BD6099274E90B5"
00113 "23A19010477B0958A5C53A2E9A18CEC53589AFCFB075387425FB3A24C2F66B40E55DC3F52F"
00114 "C4048AC77730953DE72BE2E662AB41EEAAC4A661A6E43C65AD368FC2AEBB7F658C2D8A646C9"
00115 "8234071009ABB81C7E33A75B86D89BB3484391D210582A9407637D82A9DEA9E2BEC0B4CF9"
00116 "CFDFA6E0B7D377E2EF3E91212D212B2F9515E6B541046EE2E5744887EDC1A0B149F848E7D4"
00117 "EF9CD5AAE0010132C6C5A8A5E1082CDD46EF100C82AB553EBE5490184971B1F08D110156E"
00118 "0BCD083B81F94D47F19C0F41C815333C34384F16E9B34D659E6A65CB9B274725F9C535420A"
00119 "A73CF0B1497C96EF000D5227834F7C8124B114F9711A0AB19D7A563679092093D5B8DF349A"
00120 "F5AC30E87FC773DFFDACB3E95981837F7C48F97F3E34BF278616C5A14180D81B3BAA654206"
00121 "42B74606D764F6897BCB2A12EA2A07F0DAD3DD1DEC00E265C0D965EA6CFBBD5E3721F4CEAC"
00122 "C09B3B04E423873AC76E64B17C071CE9A6E336676835E854D1E0E2B2618D918E41808FF0D"
00123 "B2296CE151A2883AA314FBBF2E9A300A75C841AFCB3EC4DB34F392DF4DD970F5ECBEF9E81D"
00124 "9DCBA9EF78AF41CDFBD9D77B6EDC92795175D805137996CAB4F91FC8935EFCDD788AE1F5F"
00125 "C650D4840EF222A78401DDD313EA4B4943A89DCE637F1F81636D06C6E1CC1062162320AA07"
00126 "D01F679F57384820286F29CBE9881FBECC3E1AE4D7FAC3A143046E29D9D4A19B95BA2508C7"
00127 "030C0E846E358D52284A921ECA6F2C7890696F6008", // PRN 02
00128 "FD5488290C9EFF7CC7C4E4F2A6900C2F9CB24239B239645B27D990BA8878505E1987F8DF3A7"
00129 "1105499EED4410AED6FDF8434EAEF0C2C0FBC1C2508170CE37EBF740B273BDFE45F4B28625"
00130 "9021B2182D6185078F0C7A6580B1371F023F07236F1655C9BE30F35F2485C9EEDBF030068C"
00131 "660A9E754C0B6F949CF5556C133AD512C65DD3E4AF6A01AC9F4B111F107FAD356E7C4E0E8"
00132 "814527E486226D9A6FDD2D9D0F1B7B1A0F840F99C83F8483E3DBA2F1B576634BD5ECC49640A"
00133 "EC7338185D72D629A03F12CF53EB3DE8FA86112F5D0E666DE0DC3CC772693897690EA2986B"
00134 "2B9F02C2213FD46ABA0A2BA2A2D90CE15BF1E6069347D5A1E78BC55D13E2BE2D173003FF68"
00135 "317BFFC96A9BFF858A07A4D2EC5CAD1D4FB21CDE30D67B1DE383096987B93F8C709E3033772"
00136 "32EE2692324D8C585E35B3E9978B13B8579B0E759B4CA76B6E69CFDC350C1FD02F7088D0BF"
00137 "BA5633A8EDAB83871C1693BDCFE6A8D0E39A78DBB3D190196FBAF7033238792139561543"
00138 "8C75D59705810BA4CA380367AD26B08B85A19D167B0ECB27EB8600D9F6FB96375684ABA1E"
00139 "FE9460DECA0690FEA707B2410781C571ECCF567569E07B78311E5AFD6A3EABBCFB6E68068E"
00140 "365517FDFE9E1A15FDAC6A000C324D82FA7D451334B873888B6DD164C89CFF3253BFC2DEBE"
00141 "4CC3AF78C66EC6DCA4BD529C3DDBCB8B932120733133E754F235354144B3EB4E37E3003BF90"
00142 "73F211C432431B192E9605A63B39DC6C31AC889E468DF3CAFF2A8D63683235B935784F6055"
00143 "02AE8E63794FF8E27C7A11502C99A834B0BBEA2AAD4300405F9C373203DC05D28CBFF5260C"
00144 "001DB0F963792F6D1D1BFE1345A4084A8A0EFAE3183A6C67E4852B90A426A257279EDFC751"
00145 "E4D3963816D5044B16248366BCCB874E9572DC9CF65FEC89F8D8A29F7E2328A0AAE3FE1930"
00146 "1C7A440115F881A3808B64B8E3C17EC0F225F1AB1CA4824D54330E504F562B9981511392F4"
00147 "715BA02578130DD776C8023249FE78FDD66D92569D9D5E652EBBD89A5C55C6939BF99A3441"
00148 "E6E3ACC944033FC5560A4512C3EA1F78890064C1663EC86BFCC9626C30CE67487A0928E95F"
00149 "A0957B774DA5F9A6730BCB7022E74D5DF4A6EBBE76D27317B972CEA4C0FE3FE1517E88361C"
00150 "32E253C025B4F16F55D532A75C3F15D1AD532CFB9BFC20AA18B5D9577F969185B55405AC7"
00151 "BB185CD83E5AB99C31D475B264954130BFC6318C437E5B437109818AFEEC7C2B78DBD7076E"
00152 "DCA94F0EF2E5EEFBBD65B22BE8DA21CE7B83A018E78A671A7669B1F8EC62B7AC522886AD8"
00153 "4377108E5E5FBC79A64E68CFCCB535538F892F0278CCD295F266FD1C84B33DAA3B340128"
00154 "BCBFA8EE0BE4AE9E88344E5861E14747AB0F9DA7EBBC32CCF2424CB8CFC50627532607D47"
00155 "DF5E878537307FDB54276B92C3C3B0366623F2777C7196E3B6D8794E5A7A70D3C1CA7C583A"
00156 "495E150B378A562BAA8C5B5B30107B1D887499A4629B1A6621F5D79F9AC3764C42B763D6"
00157 "03AB28A9C921827149922D9230581BB8F05079E1EB37215A45498B20667A25E613CAAD346A"
00158 "248F0140175E9A0CCD06BBFC25B8CDBFEA11B126DE738240AA33AA0B248C5D4AD67305E07B"
00159 "C8BE86464726151247DF7D35D08B8DD373FB6A26134846B4DB32DCBF3053E5001A50B625E1"
00160 "2A8E480043E053793675DD68D2CED8AE3FA434DC701CB8B96BC666BAADF5E1E70CD94B308"
00161 "2C36619E689A9CBA9CCDE701664DBED3B069242EA13EFCFFE6084846C096D03E59C7451E2"
00162 "23622864163749D6B7D938FB0524B057AC679D3BA4", // PRN 03
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01132 "C4B291B666F41713923194E643E2F60EFA566D4924D0398B4D6EC9EA8D275D0AAB536898CB"
01133 "CF3A877ED1CDBA31B552086FE54958549C86D5A8AB6CC5C342EA04D363A85AE55EC0365A7D"
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01456 "0787F4E8A335DBFCAD7E399272194F9FFB6ADA78E296F634770F69FB851E583EEA8C9CEB54"
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01466 "DF79781CBE2EEBE5781D1A0B0F1D1444FB1C5E600C6EA92814E2DF764F123E015A1DE147A3"
01467 "F472C5D5B47D0C2DC631765EDF13769ECA5489AA0747338031401D56431AF6F8F0CE2411C"
01468 "C12AF4F8C1D265E4FACFFC71F432388A39D622264964B14725C9858F8442E0781561E0AC30"
01469 "3A79BFA0F5D0C07B71561265B9DC3ACA8C68FD7765B504B78963FAB0948EC9B90407897A1E"
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01531 "03109C3EA9D49422968FE54CD66D29E94187D73B446C21F369D506D6178C91ABDDDFC6736C"
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01533 "1480A517E39B78BD85668C2E0B6B1E30AA9C1614B07089577A20BEB06FD51F5D73FA78FA64"
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01538 "FCDCE5E848BD8A37D18768990C4424D4AD0A7A269BE56A7C58F6191B797AB4E019C77EECF9"
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01559 "96845B0A656506D9BAE8B9B43F1086223020703B789E5F34465BB2A2E04CA2644998AE6B2"
01560 "99DFBA547F0DF087CE376140888FA6D1444D6639C3D7EB8FBB6518B3B6C2E8C70BBF46D53"
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01566 "451F6E87B6369615F39F0716719BCB7E4799C8AA568DBE32B3B279C1CE3B48B205D23CEF04"
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01569 "5F8E0929001D38D96C87313B98BAF1FD1F350139FC32A7E84351F052868B5B1960D192FA2"
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01780 "5B45B54EF72F8787A82DC82585A82D2A0CF368286AF117B399766A8A4DFDEA87072F18FC0A"
01781 "847B8D485FD28AC3C0F58B3DFEDE3E076D56F27DFD19D244C7564688EAB0197A61CEDDFCF15"
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01785 "A05BE5A3626A5AD6905AF5C7EAE5866085F64A35EA9A8ED52E382DF5E42D0576008BD378A5F"
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01789 "9F726B8A3EFF64CA0248DD03C45E5363FF1F17FB1D98E51DCB74848A028C42E864A3E477CF"
01790 "90BA6D14BDCD58250E849CE88E19DEF46476B726DF3A4D4A859BBEC49AF7D1B4F4F2A3101A"
01791 "FB0D0BDCB082C712C20CF7C8CD344361E3D9698C3A7FCA20BD554B954ADA52AE0710549CE5"
01792 "7B5200D34795C91129F33DCD7DFF9F3EC8E72D2EECF48376A991E08C682C4A18EE1D97A6A"
01793 "8087099882F775E62ABB5A75408C505D9DCE34EFC173EBCA5C14DDAFFCAC5CF77464A22FE6"
01794 "BA0771E13C398B7AE6AAF10CFFC8CFE238FA9066F449AF172933BD0AA73AE90E406431BCCF"
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01805 "FC5F197D769CD6C62738646810ED1C94D87B0D47C13124572DED11BEC718C8161C78F0DE88"
01806 "A09E39257B2DE14241A0A5163F0B3E41491EDAC323A050F7D75DB7821608C341F5DFC461F"
01807 "84E7DA25EAF86E7A7DD99C1A004408DC9DADB36F08" // PRN 50
01808 };
01809
01810 // Galileo E5b-Q primary codes
01811 constexpr size_t GALILEO_E5B_Q_PRIMARY_CODE_STR_LENGTH = 2558;
01812 constexpr char GALILEO_E5B_Q_PRIMARY_CODE[GALILEO_E5B_NUMBER_OF_CODES][2559] = {
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01814 "D0E4101A8846F50D25B0ABAF49171E3A0C8384465B39458FEC7D8644CD6ADDA0DE47617495"
01815 "DD1886FDD3A960A25D58DAF9333F73AE833D840ABD6DD1D749C20B8EECC0C29E63661B0E0"
01816 "BC50E9EBF44ACDD0FB5B48E141C16E196ADF48314E2E8E7986FA609DC9F11307B68EEDFE07"
01817 "7AD6A5F8E7A333DBDF74C126FDEE4E13E4C879CB19A381067DF74A075176104A3C60FA17C"
01818 "934F01CD20986A3844CC3395C2F14DBF38B4932660051732A813D7D224D6A9A46347702B34"
01819 "2A8A1F214550A3E30DE0D007029BF701A32DE08148C67E341C95FDAB5D31FC4AC790DEF152"
01820 "1BED12156D1E68349B60431261D99176797A9CD9F855D3746D03C575D6CED7E62C401E24A"
01821 "A20A43571AD6316A9F288E02E99C4B29AF9FCAAAEDBE83306694FF697B2A894E350A3C2DA4"
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01825 "AD7668AF00CEBB7AAD8A47F144377BB81D9831DFA53DA0AC1D6C1B909FF9708B05A248EDFF"
01826 "820A84B0F94DEC6B1308C2DC6A44473CAA01A4CD4124CD99130899FC85F7D2C7FB1A12E5A"
01827 "93F75DC4061F0029627EF320E3228338FAC94318B0D767956BA42A38B58571BEFDADD77921"
01828 "326E5C98F8983BFC70B0CDDFBD8C628A1A5CD6BD015767691E85A3D6FC1702C5FE9ED26DAB"
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01830 "6420CF3BFEAE100F555C633F91FED3C382E7359ACC381A1E1044148A2BFAFC132833E74811"
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01848 "CE701F7B81A1EE81DEF8354D759C27FF6E4C6EBED2153250472ACB70A82E3BE39DF9DF9BEF"
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01851 "673C72580640146C7A4F640F6524D3CD827342BFB29E5A211FC373C94E11F16771D58D008E"
01852 "DF116230ABD8F165797E8B0CFC589FEA57788516502A664C04AB9F15310C55758CADCD63FB"
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01863 "7024DC10FF6430FE2B4C9BE4EA2CDC2357AC71529F4362D9A792D4472E14682EE124892B8F"
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02106 "262D49D727E83928DFA27EB2FCBED2392901CF09C7E3B14EB8795A2E152063058BD213964A"
02107 "A5DD8EF99865255AC7CD5379017B96A6A379A736CB1A5D041B1F2CC43D27F7C234DF3FC5A7"
02108 "E4596E02111268781A30BD9B3A10A15716E7753BFE3EC8013D4ACAFDF6F2918D901CACA5A"
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02754 "73A38B6DCB7432273F9421EAA6D6A833D4DBB32B19DCC3FE505FE9B9494B2CB18474BFC7F2"
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02756 "CEEC6B7DFD14E75C4FC65F4C331DE1B7FBCF6BF314E5DFFD974861202784CD4D9054C71434"
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02922 "DF74A0AA947ED016CFF3DA2815C87750969D869249CC1E017F4E952448FB7809CBE4703586"
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03077 "20B95CE62698733522093BC64EA57CA48F05161C0FCB369B57F16C449D3F094C0351F8717E"
03078 "FEE5A576454D3023DA435C8C553F4F786C505A16B9DABFF43DE50091F27D338C78AA5ACE5F"
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03096 "BDB88AD3481209D9FFC08CBF3C2807CF6BEE56B4B91D3B1980BEC5F52D6C56B4FD36EB83A"
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03143 "978D4E016D006EBED30E25C1E0C5843FFD41A9B72D83E97C511FFF9C43E6EE09C7D3EFD6E"
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03147 "093E9ADEEC149E08892127E97F9CA9A3AD97C59B8446A880D6766C2FF2C1D596E4AF1ABB47"
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03236 "844F9540DC9DF30548BB942BA09216E2203F7B723F37351D86A49B2EE870CFDDE82614627"
03237 "1B7C532E9ECE3C7E985B22AD3DFAC4E7813CC8BDF3133AE30081A1364E4203D3BF3617B4A4"
03238 "639FAFEF78C4351A50E5643AC44B3C51ECB9EF1B1073A6AEABD7ACAF57DEC2781868F535CF"
03239 "0BE6318933659FD643D8EA8D0189AE66A0D8EC34E84E04331A8481367FAE12F1CC68494F"
03240 "48CAB82097A50E238008433AED289C5B948D7B1A42B8074913EB531DF7196C40B499034D15"

03241 "C81396B41A5E5C2AE85F775DB18E090BE56FCCE74C733933749C07CF695013FC804A1FFC06"
03242 "D4DDFEFFDD23586EE9E0C9D0BA161E83DFD786EE54E424B8272D1E167F53F9043E23B5934"
03243 "600C0F063BA7717FF53ACB74149DC1211FF1AEDE82F261ABF6B1C58259416F3DB7DED56F11"
03244 "D1C148BF43F828DDD892805B080C3C68BC6316EB1C0F533B9ED6C81C48DF418FCE514DB7C5"
03245 "8783B5F4C27AE0C3BD31E069A22CE0A95AE1C49099C839C64575D897A6AE55691B71B406B7"
03246 "C6EFB460CDAE1126304B5A3D1BB438A9C2B7508A28DD58C42EE2A6B290E88FA5A8B0D77F27"
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03249 "DFAE322AE3AD6917A37610C5187ABCD89B839308182E7FAB6AE980157993F5371787BDFCCF"
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03251 "C0242B002D4D33E4EE9FEA4625B98BF9873BB8D352CE0ED298B0BD2CC251F097F722A28383"
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03253 "BB5CAACBA0317575D8C6390BB21F3463893C931870DBF2C2C9AFECB410815C65EA33AA0A99"
03254 "6D3217DD1B2DD826715DC57E103FF6166ECE2A3BF309552E755E7E41F7FE28D1CE1022913F"
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03256 "19BFEFDCDD3F65A0CA9E79A90857F6D3DBB5EE50580519645CC41E6CD359EA97E2E4D6DD90"
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03259 "FFC6C1DA8CEC6FC9C35FD109D571B800BBC4F43BC552BF5B05867B65C458244A139BAE9BB"
03260 "825F9B0EA9AA1540B0DE16CE5BEE092C80A32C0854DF3FEA26479A93FD5443549CF03447A4"
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03285 "A47E9C6D8F985DC388B8DCDCD4A67B90D989852E4E8F073D0AE845F3A6F86534BA2172CAF8"
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03319 "E2A0604107B5442819D5159AAC554BB2EBF6807D877F0AC3FCD0C63EDE4A3DD19205710F0A"
03320 "5A7B1D4071B3406868E7887A2CF58C5DF238B5D72C534CFD40B5D307C7BD5C626ABD64A07B5"
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03322 "5CA1338EFF1566C8526B66F0C6CE2D4A8D3A0183513A69B412AF28ED9D7AFA34F1FF5682B4"
03323 "387D796BFF783D6FC813CB34D2426304F67704624FEAA4CBEFFAF09D4E5A8A4E0E7ADABAB"
03324 "633503193A2A61DE0BF49786D8A29032B5632036AF6267E9A5D8712D0F64088C0F5F05EE6C"
03325 "276D6A17C6EBE74A1D8412FC4677FE2C37F50CB86C79CD5FB402B3195C4AB474F42C3FE54"
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03332 "911E95A686849242E2B4C5BFC6307A00E1584840103CB1F8A22943E4782CCC4B0DB04AFF8C"
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03334 "A59D0B7E5171CDADF402FDB3B5C2E1E455A44FA8ADD4791BACDE5466F8BCBD584D09E0041"
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03337 "262ECE3F874DD219CE98D4CA01EBDE53EABD1B19062959DA6CA380E4DDCB7B7B0E1FE8168A"
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03393 "A312BCA33B2CD9679C4E21FFD66F97AF011A77A2E5885FF6D42D6276B6EDE10CB29CC5EB4D"
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03556 "BE9DCF78DFCDEC0711B6712ADFDD6A2A71FAB1D6FE40CFF4BB1267D169FAEDBCF21F1379B5"
03557 "8CC76731093BF233951FEDCA86A2BD505F9E10ACF169943F20846A341D85297DB02288BC9E"
03558 "FAA7B436D1D53CBFC170B4FD7D3E11FF76C30B922C8AA205A376F94D61066749C2C7387CE"
03559 "7EC5C6952AB7C9F12E7C11489AD879F8ED43015D1C63FEDE9EB223D52D79BE1E2242F9B92A"
03560 "5C64C8B6D5C36498A9A8F862473C081A58004ADE1B4EBD4C4C0AA5978074FF22AD2CE1A70E"
03561 "2E1945F9B14E3D537E07C930864EB4C09DDA24B74264FA45903008E42059DEFE5CA0C04D45"
03562 "A44B716EE0BE551C47CE7D23182370FB896B9AB080" // PRN 50
03563 };
03564
03565
03566 // Galileo E5b-Q secondary codes
03567 constexpr size_t GALILEO_E5B_Q_SECONDARY_CODE_STR_LENGTH = 100;
03568 constexpr char GALILEO_E5B_Q_SECONDARY_CODE[GALILEO_E5B_NUMBER_OF_CODES][101] = {
03569
03570 "1100111111110010001010011101110001111000110000100100110101001001001111110101011100101110010010100",
03571
03572 "11111100001100010111110010011010100110111110001100011000000011100010110101110010101101010110011",
03573
03574 "10100010111010101101011101001011010111100110000110011011100100000101000011100100111111001000111001",
03575
03576 "01110010111100101011000100011000000011110100110101110000000001011001011100001001101111100110010111",
03577
03578 "000100111110001110101110100100110111100010100100011100100011101000010011010000100110000010",
03579
03580 "01110111110000000100001000000010101100100011010010001011000110110100110100011010011010110001110",
03581
03582 "11111101011110001011001001010111010111100011010011010101100010000001110100001011011001010011100",
03583
03584 "00001011010010010100000001110111110011110001100110111101101101100010100011001101001110111",
03585
03586 "1101110100001110001100100001100000110111010001110101010010000101101001101110110101101111100",
03587
03588 "0100001110111101010100100001110101001101100010010000011111001110011001000011000011001000100011111",
```

```
03579 "0000001101100110101010110011001111110000000101100111101101101111010100101110011101101011000011000",
03580 "100110011100110010111011111101010100010010010000101100101111100011000111000010111101010100101101",
03581 "10100011010001100110100100100011110011101111101111101000101000111101100000011111001110110100100010",
03582 "000110100101001001110001111100100010101001101111100110101000110101110110111001111001101101111110000",
03583 "0011001000000100101001101110111001000110110100100111010001101000101101001110000101011100101100000",
03584 "001100101111100000111010110111010100001110110101100110011100101111110111000011000101000111001011011",
03585 "0011100001110001111101100001101100010011101101101110111010101001111101011011000010011110011000001",
03586 "011010100011110010111011111110010110101100100110100010111110000000100111011100111100011001000101",
03587 "00101011110011010000100110001000100110100001110101111111100001000011001111001011101101111000111011",
03588 "00111110010010010100011001111111010011010100001010000000101110011001010000101100110101111100011100",
03589 "01100101100011100011001101101101110011111011001100000001001111100001101101010101001010010100000001",
03590 "11101101010000101000010011110011010001010001011100001100111101110111001001101000110010000100",
03591 "0010100111101100110011101001000100001101100000110010110010101111000101011110001111011111010111010001",
03592 "01000101011011001100111101111111110100100110101001111010101000011101000111101001110000100011111010",
03593 "111110110111010101111100110010011110000110001100101111000000001010111110001101110000100101110011010",
03594 "01010110100001100010001010011010100011011001100000100010010011110001000010011010111100011111111100",
03595 "0111000000001010001011010011001001011110101000010100110001001011011110110111010101000001100111000",
03596 "000100100001000010100011001100001011010011010011101101010000011111011000010101001100101110100011111",
03597 "01000011100011101110010000010000101111010010111011110110111001101110110000101010110010110111010",
03598 "01001011100101110110010011001100010001010101101011100001111101100001111011110110100100001100101011",
03599 "101111110001111101000101111110111011011000110101100101001010110011110011110001001100100000000110",
03600 "110110100100001001010100010000001111111010001110110111000101100000100011011100011101100000110100100",
03601 "11101110001011001000000001010111101001111100000101101001100110101111101000110011111111011010001",
03602 "0010110010001011111010111110110000011100101011100011000011101111101010010110001001000011010010010001",
03603 "0011100100011110010010111011011010111100010000111110100110000001010100001100110111011100101011010",
03604 "0011100110011111011100101010011110101011011101101000010110010010000110000111110110011101111110000",
03605 "100100110000001100011111101111010100101100010001111100010001110100000111001010100010010011100001100",
03606 "1011101010000000011000010100011000101101100001110011011100000101111010010101110101011100101100110111",
03607 "1101001001000001100010001111100010000101010001001110101100010010000111101001011000111111110100110100",
03608 "1101010111110110101010001011101100001000000111011000111100111000001110000010010110100100110111001010",
03609 "0000111110100100101000100000010111110000110101110110000010001000110100001000111010101111001001100111",
03610 "001001110010111010010000100111110101110101111000110010100100001010111100010011000111110001001011000",
03611 "001100110111000011110011010110011001111010010010001010000010100001000110010111111100100000010110",
03612 "010101001110111110010110000100010110110101001010000011001000110110110000111000000111000100000011111",
03613 "110111100011010001111100011110110010011111110101101110001001000111011110001100000100110101000101011",
03614 "0000000110110001011011101100100110111110000110100001110101110000010001100010110111000100101000100",
03615 "0001100001010100110110111010000110101000000001110111010010100110110001111110001110110100011101101",
03616 "00101000111001000000110001101000010011001000011100110111000011001101000000110010111111101010110100",
03617 "01011110010000101100000110010111000101110000100100110011010100111011110010101011110100000000110011",
03618 "011001000011000100001011101011011000111010110110110011011110001110000110010001101010111100000001"};
03619
03620
03621 /** \} */
03622 /** \} */
03623 #endif // GNSS_SDR_GALILEO_E5B_H
```

13.743 Galileo_E6.h File Reference

Defines system parameters for Galileo E6 B/C signal, as published at: European Union, E6-B/C Codes Technical Note, Issue 1, January 2019.

```
#include "gnss_frequencies.h"
#include <stddef>
#include <stdint>
```

Variables

- constexpr double [GALILEO_E6_FREQ_HZ](#) = [FREQ6](#)
Galileo E6 carrier frequency [Hz].
- constexpr double [GALILEO_E6_B_CODE_CHIP_RATE_CPS](#) = 5.115e6
Galileo E6 B code rate [chips/s].
- constexpr double [GALILEO_E6_C_CODE_CHIP_RATE_CPS](#) = 5.115e6
Galileo E6 C code rate [chips/s].
- constexpr double [GALILEO_E6_CODE_PERIOD_S](#) = 0.001
Galileo E6 code period [s].
- constexpr double [GALILEO_E6_B_CODE_LENGTH_CHIPS](#) = 5115.0
Galileo E6 B code length [chips].
- constexpr double [GALILEO_E6_C_CODE_LENGTH_CHIPS](#) = 5115.0
Galileo E6 C code length [chips].
- constexpr double [GALILEO_E6_C_SECONDARY_CODE_LENGTH_CHIPS](#) = 100.0
Galileo E6 C secondary code length [chips].
- constexpr uint32_t [GALILEO_E6_CODE_PERIOD_MS](#) = 1
Galileo E& B/C code period [ms].
- constexpr int32_t [GALILEO_E6_NUMBER_OF_CODES](#) = 50
- constexpr uint32_t [GALILEO_E6_OPT_ACQ_FS_SPS](#) = 10000000
- constexpr size_t [GALILEO_E6_B_PRIMARY_CODE_STR_LENGTH](#) = 1279
- constexpr char [GALILEO_E6_B_PRIMARY_CODE](#) [[GALILEO_E6_NUMBER_OF_CODES](#)][1280]
- constexpr size_t [GALILEO_E6_C_PRIMARY_CODE_STR_LENGTH](#) = 1279
- constexpr char [GALILEO_E6_C_PRIMARY_CODE](#) [[GALILEO_E6_NUMBER_OF_CODES](#)][1280]
- constexpr size_t [GALILEO_E6_C_SECONDARY_CODE_STR_LENGTH](#) = 25
- constexpr char [GALILEO_E6_C_SECONDARY_CODE](#) [[GALILEO_E6_NUMBER_OF_CODES](#)][26]

13.743.1 Detailed Description

Defines system parameters for Galileo E6 B/C signal, as published at: European Union, E6-B/C Codes Technical Note, Issue 1, January 2019.

Author

Carles Fernandez-Prades, 2020. cfernandez@cttc.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.
Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors) SPDX-License-Identifier: GPL-3.0-or-later
Definition in file [Galileo_E6.h](#).

13.744 Galileo_E6.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file Galileo_E6.h
00003  * \brief Defines system parameters for Galileo E6 B/C signal, as published at:
00004  * \brief European Union, E6-B/C Codes Technical Note, Issue 1, January 2019.
00005  * \author Carles Fernandez-Prades, 2020. cfernandez@cttc.es
00006  *
00007  * -----
```



```
00008 *
00009 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010 * This file is part of GNSS-SDR.
00011 *
00012 * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013 * SPDX-License-Identifier: GPL-3.0-or-later
00014 *
00015 * -----
00016 */
00017
00018 #ifndef GNSS_SDR_GALILEO_E6_H
00019 #define GNSS_SDR_GALILEO_E6_H
00020
00021 #include "gnss_frequencies.h"
00022 #include <stdint> // for size_t
00023 #include <stdint>
00024
00025 /** \addtogroup Core
00026 * \{ */
00027 /** \addtogroup System_Parameters
00028 * \{ */
00029
00030 constexpr double GALILEO_E6_FREQ_HZ = FREQ6; //!< Galileo E6 carrier frequency [Hz]
00031 constexpr double GALILEO_E6_B_CODE_CHIP_RATE_CPS = 5.115e6; //!< Galileo E6 B code rate [chips/s]
00032 constexpr double GALILEO_E6_C_CODE_CHIP_RATE_CPS = 5.115e6; //!< Galileo E6 C code rate [chips/s]
00033 constexpr double GALILEO_E6_CODE_PERIOD_S = 0.001; //!< Galileo E6 code period [s]
00034
00035 constexpr double GALILEO_E6_B_CODE_LENGTH_CHIPS = 5115.0; //!< Galileo E6 B code length
00036 [chips]
00037 constexpr double GALILEO_E6_C_CODE_LENGTH_CHIPS = 5115.0; //!< Galileo E6 C code length
00038 [chips]
00039 constexpr double GALILEO_E6_C_SECONDARY_CODE_LENGTH_CHIPS = 100.0; //!< Galileo E6 C secondary code
00040 length [chips]
00041 constexpr uint32_t GALILEO_E6_CODE_PERIOD_MS = 1; //!< Galileo E6 B/C code period
00042 [ms]
00043
00044 constexpr int32_t GALILEO_E6_NUMBER_OF_CODES = 50;
00045
00046 constexpr uint32_t GALILEO_E6_OPT_ACQ_FS_SPS = 10000000;
00047
00048 constexpr size_t GALILEO_E6_B_PRIMARY_CODE_STR_LENGTH = 1279;
00049 constexpr char GALILEO_E6_B_PRIMARY_CODE[GALILEO_E6_NUMBER_OF_CODES][1280] = {
00050     "E6648AA5EFF0907A170377FB20CEDEE1E8D253DAC2496831010336B44276BAAB17E599548"
00051     "B1A79C67379F98DF0CB81AE8D914EE4947093ADC94FF4B3916EE562A4CAFD4A5A04972160"
00052     "E655FFFE26C949D7C8B0AB7AD2F7DDBBF88A9B091510D209AAA3F6C83ECFB8DE21B77E793"
00053     "A9E759E73A7ED6330395FD9380E8E86F0A511E0FEC8E0B6501983FA7C693FFFFF719EFE42"
00054     "49EF295B578E514817D9E86EBC10917B3B7656BEF6C9AAB8200B20DEE54BFD18728A33934"
00055     "50F20B08A7AC84A9F945398E13434BD3076087F32CA165AFB94FEA9686924E831BA4BD76AC"
00056     "F62D7B216BAC53F71FAF1A13580BDFBB56DD555855A9E2541FFDED2ADF6A6125D73F116006A"
00057     "715596001D1538B0D91C8D445D0342B910219EA64B77A7A245E470AD547590C3D59DF32CF"
00058     "8ACCB6D2F17ABDA7F89DB09C96A2E811599A39191CEE8F8D42A0BC2A5D00D8D7C318E8996"
00059     "470280F551D25DFAF153766F6D237236B23FBE1E74484CA9485848CD5C1966705EA03A0220"
00060     "E84B1AFC9F08F8BDC110D9597973C0F347F5259591EEEF00C399D9A6EF140B759465E07F48"
00061     "7ACE9B8CE34EB219AC63C01127520C8E2D2FA7090AC754976B8DAE5C51F18001ED095518DC"
00062     "659B5746B390226013A6DEF1C54DF4BE1E60CBAAFD10D163E937BC753184791966B930990F"
00063     "9DF0A98D2F9060233858CD699613088876272B23C6FC27288BE7D258CE3E83A0F2D5C3A9BC"
00064     "FC0E7C9F02AA0A97AFC31A286E9CF85BE5885FFA22E51827EFB1066452B27335C01FCAE645"
00065     "B56819B9D7C7014B4B8C050E647B1B215A45F8B939624433F0319C840DEA265D8631A1EE9A"
00066     "66439DA99563DB168E9C1574E2730F6AAF709AA145B75DB885B14FB7E838A05948ABC6206C"
00067     "793C33CE9189BFF19338C", // PRN 01
00068     "A2AB1DB576F2061D6993AC3832FF041C388E44240AAEAB61ABB450D961ED6C8088C05313E"
00069     "8A31B322CC757C389FF8B033792BFDACA5D3D4926321497DDBD7C40F833AA87EC0D27B11E"
00070     "215E491528C0919B2E0D3106DBBA384EF22B1133538C78C76C4ABAC8493E18A30E842CD005"
00071     "01EE9A737F8AD7E7D78EF22EA826E8973BD19945A5A30A4101295D4D9010CFB232E2187A98"
00072     "AB9876E1C9B33B2A8328028E9111A3AD612D7583B0E6A502AA3AAD7E90680013A3C2E83C"
00073     "475C6827307B9B4B71B668EE7B2573756F1AB9FC7DF4DBB0577C87FEA7031A1A3B55D054731"
00074     "C1FD7849296D03F66BEC0D4DC25C99BFEBD810622970C160248356A15A18C3F6907E39C4BE"
00075     "82EAC8AD3874D3EC67E77FBAF6AB25DE3FE764BD22B3EC24C944E4BC060675369DE7642972"
00076     "DCA19A687F6680CF598EEF1B29BA7A4C15D43A6FE33AA867B929F158E7CDECC08E11B6E352"
00077     "52AD148ADE7DAED8B17648FF1E98094E560B89B75F72084BCDA4B93D237555F3FA2272253"
00078     "7F4A7AE9BEC228D7BA9DD7189B1165C35D9BCF7791E4823FD81A05131D9DDF0F696458C93"
00079     "FF255DEADB2C4B55B64F5FF621B8A4773C1A95C0B47D84E2F410A79D8F959C76AEA247846A"
00080     "1666845653BA47CFEE762C6846EDFB5DFAE144FA31501FC18D8CB77160B8B3FA5500C30D5F"
00081     "B1CB0B8F5060182F278BD748E3B64D8DA7FA85A48E0179CA3A2441B2205FBC5E335BC49D0"
00082     "B1FE60B2D7F94484C2921780B31B9968747EE4D19F1AEBD314F8018F47649B8EFE6D8F7230"
00083     "E4E810FA22301B620674202651D73A3C3AF84CC259F26AB775F46FD947EA5818B055224667A"
00084     "94C29D0BE44E925053CB0A35FC670A1FEBF39EB00D7D64AD23AF036915DB36FAB654AD9D5F"
00085     "39B3F97F16DB0B9522718", // PRN 02
00086     "D7C50CAAB17471A735C51D4759644BE4A788FEA8ECD5F17E00B373DBD24917481DA7418208"
00087     "04EA5CB366885ADFFC988EE21A0875EE7A36981726B7106EE3C7E4C1435890E415A2F74667"
00088     "633E1DC7D259FF2C3A1D408FEC4D1792326E7691253F6DC3E7B9B43EB546AE28E6152984FF"
00089     "677E4585B1637B8A38C7042138050888F88EA0479E974833EA5DA1B445350D4322DB625F56"
00090     "7F6DCC3F1A8F4096BE5333BF0B9C7F5545C5D7430A9935A2001FD1742AA34E572F886892AC"
00091     "061B4A1D306B91928F2A8C159E237D23A4BF9D08F6780F9936FA6A63684500CDC51ED6AD2B"
00092     "23574C459B83BA0504CEB21980F324F91A37A48E8402155CB97798F2618DC292FFABD99B80"
00093     "00500C3D4B85F4D6249B4033D098C08316E570B10E5C939DE08C1DDE918B749332B5E6AA4"
00094     "88A5AF937F609414E885C77A953D8CA93FD382CA84752F54BD2779F460F0EDEE48C99AEA83"
```

00091 "7877EF01AFA9687F334218F8EDB23EBA3FC0AC8CF8BB5794562E6D5B0A356CDB6BCFC0CAC2"
00092 "ACCE6CEEAF102CA980B23A36F89C35470D0BB41C8BEB2BE0E6CD0C9689DF2D1907AFE689B4"
00093 "9C19D4539AA1A48412B6F15227839629DA976249FF057261940C6E88719EE8672E8A772E7"
00094 "CD10DF669B1E966A8D93C4B3E9B9D4D0148BB53F272208F192B370B17291D33573D8BA7698"
00095 "4B2980343928DE4F7AD5E335FBCCFDBBD31C8E9FA63015327D0517EA2F161EF5A08BCC0856"
00096 "B6D5BD210FA3DFAE918EDD7C4E44956FFF2455A4C3C71EAB715A12FB9DF145C7FB4F46A17"
00097 "C877797EE158737A730F8937BC6DF8325815464EED4F48ADE718C01CC7BFE5979D71D1FC87"
00098 "994524F89CA789788BA057F9D499EDC7E1DC6BFF41920FC1B5C3DE263D5768B31237BBE750"
00099 "617E5802094537DC8E62C", // PRN 03
00100 "AA696973C3A5E818309F73264D9EE219FC69692F106F7FCB8ADCC3FCE9816C691C07B996C0"
00101 "E5DEDF63501B63A6F9E5F219FCF8ACB811E980346BA432CCC6E2A0FA95B9E30ED03468AC7D"
00102 "1C0A59035359666F1A04C7673F7EB7C5576F6B2C6548979F480754D4C7C31A4A4E125514DB"
00103 "FB61BD199830855A928BA58531257E01F5D69D222C56C0472C3354DEA19D563EFF9E25150"
00104 "256FD27E76A0F719B63AD6917BA13C69D49B228FDE7D4181B843AE23F4D8740D942F27BB70"
00105 "3199D70A0EB5D3C0DF04F0BABA9AE21408C6070345FA82A69792BB88F1194C6C205008A729"
00106 "3C077169BBB58281CF57DF1846C976AFBE5BAFBF05C4948AEC474CE85B0DDA450441DAC1E"
00107 "778BC63D1B75D867532FA3534CEEC0B796EADA76B8EFCF1FBB70F4902086E7C7926FF19EDB"
00108 "75FA9848525068D591D1F0E83995BC10CA25DD8E22245AB72558D27F620E785E5132062F3"
00109 "AF642EB9C83944714CBF5A98EA18402500380FAA6EAA7823E00ADD6B70DD1C879E486C6C3"
00110 "9FCDASDD734798AA70ABC07AD7867F03EC3C1D478227DCC91701AEA7E509085AB319858790"
00111 "D692AC9B1A85537E7A16D4682D90E0EF5FAE63B342D86C6B610DB41022FE46A8013A756A31"
00112 "31C0731A213C3BB07981ABD53C22103C5094636CD630BAAEC9400E574DFED45FAC5E1AF832"
00113 "06E62D1486A80ADCEAC8A89D3B8F9BC8C88ED5F1EC4A31CB16487510A054CACA7725E3FFC4"
00114 "AF4C65A7DDBE4D0861F4593F84CE36C5275C543B573BADC1659257DE53396F667E8A3C437"
00115 "5DA4AB23EB622546547C1E51EB436DB27BC3F321B15C373DE2755F3F860A8A2CE62C90E728"
00116 "717E5E8DF09AEC67DAC2CD84FF8CE9180B4DA29D32F52FF849F64BC65278EEAD25BB54F1B"
00117 "33A2735EE9AC5766F2E30", // PRN 04
00118 "AA48B0CC726F7B85B9ACE4D423964A1E548D6CB7F8F886DE941E49360E53EAA7AD303BCF4DD"
00119 "F3E8E640DB733727082AED108C3C497644800E14AE78DF95D3214D948BEDCB3D52FEAA68FE"
00120 "F9F0A98662B390CA0E98E663EBF8B7459A8526E06F639630B3790B5195F9330FFA0BCA9C14"
00121 "120136CF11560956B598A3A656A045E254BFAB4F4C9907F82C1D2BDDFF35958980D49CD3E9D"
00122 "1DE1CD86D72A35385371CDA6C3BDF42256B13EE6CB959F1CBBFE6CA7493835123141089509"
00123 "B9D8741BE692FD6980C1F72F328C670FA91882AF369D8D75F640A4AEB20923738DEODE2FF8"
00124 "C29CA505575C59B779D32F790D7AF8DB5C5E13810EB316844D1CFAD297A041D3B9BE524836"
00125 "180E5039AEE79444CA1ED352AD4DD61F7101AE2D556CECAA7E7DF1F7BF2E88BAE57F60906C"
00126 "27C12AF03780EA2CF10F4A2222988313326898728E5CE8E09267363575F9B2EA976495E739"
00127 "52C05E69F955C5F66937A4BE157D5BA63F529A28846FC25D800C8858F8BE4988681FDB6294"
00128 "DAD76E501C40D8A49B816AE8990D4EEE2A029DC9BA1717EB7C013ED8D6F57DEDA4784960FC"
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00944 "5A134BB226BBE1E508F0A7CE3A60BD85CD528CDC8D2D86E27A27477C83F6E1A9CAC0AB73AB"
00945 "D25D2CA84D26BAFE257E4" // PRN 50
00946 };
00947
00948
00949 constexpr size_t GALILEO_E6_C_PRIMARY_CODE_STR_LENGTH = 1279;
00950 constexpr char GALILEO_E6_C_PRIMARY_CODE[GALILEO_E6_NUMBER_OF_CODES][1280] = {
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00953 "009D6C30036FC1C0DA770D6C598CBC95CC2710DD627B5E10CF9764825427FE0387DF7EC6F8"
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01781 "E455313FF915A3AD9466F11B651CF210143D6FB06BA6E5BF4083671FB3DC9454E4EA38ED98"
01782 "OC0C52EB65224FAD970316D5BBF490B2403BFDC348A7DB1B4AFD9A91B6898381CEEBA5F6E"
01783 "A1419C19D21E1A64DA2063D824AADF7C0E5A546D608F7FF19B89BDD9E8808A7A236E98DF0728"
01784 "BA39498DC6BCFE82C534DDB6FE02B303B2DB401DF41C53F4F5321CC28861D22010DF2D1457"
01785 "F9C594F3A3DE00753CAF0CB6EE6B34DA2364EDDC2619930C7DCE4C976F50BE69444BB2759"
01786 "44D17D07061A87D1CFE0DED63400B514C6457F4119845A19072678017FD6A498CE3D3932CA"
01787 "C6B63335D87426F1C16FCE0F5861FF0953CA13E9C911A947A2C82231E61012DB7E782BB839"
01788 "764EE42A94FC7BCE4BED84D891EE959D9430B963CDD38EC2F63884AA493BE7FEAF47B6252"
01789 "F2F042531A5FF5347AE9C322C374AEF6A7F4529BCBD085696178D1D2C12C9AB91A2B66E3F0"
01790 "5A45A1950BBFA797134B4430DC09289B09EB1BD88D05B03D2EC269500532FCEBF7EC7A652E"
01791 "9F96AFB6522E6D71E568756C2D1700D55238AD36D86A6D92C62C4522F4EB2F2AA0F9FAB8E5"
01792 "6D4052B1389F0DA9BC17376E248EC86AE21EA8430B110A8A2AA835D7317095CCF2FC00ABD"
01793 "132A1D2CB7CCB105871E4FCE7F5D8B7CB3E9FE24303DAF57EE80581725B9ADCD9CE09F7CA"
01794 "50DB4B61AFB3C8AFC7C39958F4A963E92E3E29F4349275C772F68D135AE05CA99019C14166E"
01795 "D34E0C3598A67C9CD8CA68832D7D7EEECA0BE86B4355B8439002D2F7CC7933F07E6A8F0908"
01796 "CF0F3903996C390142728", // PRN 47
01797 "9F4DE194AFEB87B4D4934D86F08C2F3506BFC8F0F0AE05E9AB45A17B36AA9C7D5534127B3C"
01798 "98E60885AC2D00006A8CBA4EAF711CE0C9497B04B539553ED80B24EAC9496BE53725F8EAE"
01799 "5DB5BDB71664C45D01CD17BE31D039CE8CA16FD9D9D60E9294C8ECFF4975392793C879BB2E"
01800 "375AC7EFA4731C3D6D895E6A3F929E78BE82EFC896E89304FC3F3F0751E22D523D3117AF239"
01801 "B897B12841429AFDBE8F8D303D50D2A56275CEADAC04CC32A95E9DD45F4D4C83EA7CA29EF"
01802 "5E8F7D172D18134E5FE9BC9E442F6D2DD3B01807B994C80697A28CAC0927FE31E62985F629"
01803 "A965FD14083E72D65835BF6230A660F10D91A04EA9809FF8817129E6503F28596FE9A486D4"
01804 "86A3B789580E36C0F9C6B75BB6548742676F50FDA64602EE6986EF10824C90E66585A118F5"
01805 "C3BD1FF67BBCAD408CF0762D59216884525FCB32863B6A1502302C4F09B3BCB27A9EBA72EA"
01806 "BE68DB6A15CA6FDCC8E89CD4F20055C322161F1B1F9CFAD8B93A68C42AB19565DABC486B0C"
01807 "A93215DDC8E128806B4ED06FAA0987A49EFCFC1C23E1BACC6ACB332D720311B8FED658024"
01808 "F0CA12EAC658494DA79F9CB56D59F17C927650575562095A99F5A11D13CD1267BE89FBE761"
01809 "DF5CF0E9DC8C67A9DE21E8BEA108BC3E2E3AA68C7742103B6F975DC232443C34F17D9EAA193"
01810 "9C25134BFF908757849AC3EC6E954FB4991373DF8E7DC6011D16F9C19E4C7021A788C0834D"
01811 "6BC09A560908AF50F71D0496A3DE1EA1DF8F485A3C96B9F4B65A279083F8390966C034829"
01812 "6D05BCFA81D2EF8A2714C4A886D35DF870BA4DCF73BFD8E3EA1DFD4D9E37A0ED8E9032E350"
01813 "947D61B0CA2FE10FC20B8A5AD0E3FD70AE3C8BB91F2E04619ADB3C684E10B9127E5B768BCD"
01814 "0E9BAD2FD100131E6FCB8", // PRN 48
01815 "953E31E5F9C45E57DB6C54DBEBE650C07F8C14D832BC39D5D860912A7B4EE9F726C0D3FF84"
01816 "2DA45AE9286321AEB6A45FAB260E1FB3AFB7A4DCBFF3D65491BC61AE83207E1CC56858D13"
01817 "046191A5CBA51C59F3BB37E281847EE624A8E54DA17273262E790246A54C8873BE252E9FB"
01818 "D7A7ECCD476D62124FD1F28AFE207545525B325DC6F73F25D09E3589BC848E0A803EB10FF5"
01819 "0E81732E5F317CD3AADAF6C123807677B273B6B56955065869078BBE27AA04CEB7ECCA493"
01820 "DC2E9499188C51B16309F014624554EB96E3A69E3E067FA946977379B4BD23A9DD57D5E175"
01821 "FAA891F5FCD72431A3C857A582B233403B0D13C48C502F9E5324DB127DA83F019272A29ACD"
01822 "F325E6AB2908ABA54CD56D1D91188B320A1941720BDC2CF00991C932FC5D7025B69F242F7"
01823 "75A06DD6B8BF7615246AC4B7495A350C4BBE9F657F449969DECE013BF3F7367647316C2A"
01824 "A55F882BB42C7BD7C43618F78A6409A8659919E3FA20DAA9BC384CC6BEA776A438080DA6DF"
01825 "11AB8A853F06DAAE429883F3C153FEDFDF9D968FF806D9B7CA193F3A72D316E0297A01CF1"
01826 "AB6350D2E807F93EC27E7BD91CEB6CDC4001E092EADF5523BF0D67EFDCC8D98E5A2F7CEAF"
01827 "0B126F4D2AA32A484B5272AD7CE9E9F26CF418E6642927124483043E3C15B7833655C6388A"
01828 "26A10152857221718FB9AFE36331E071C04E98DA3181B5F5BC701CC5C30BB963183F6AC5F"
01829 "26A5CAB32ECB7C8A88FDFCE73823FA6FBD965B2772067CC2B81BE5A35660ACD3F5658ED28"
01830 "A0D225B54392F0D0398148ED738FF3A80E5DEB5D2DF3092C1AAF81272E751903979F9FA66A"

```
01831 "D3C101F259496F9EA011082D7BE7E1E10F80ECC4C42AF40E0AB498081404E5593A71147038"
01832 "3D8149ACE622AA769A900", // PRN 49
01833 "CE11D9F5C85027678446809BB43074F041568F30717E5B784BD0B64FAAE0610A144496CF4A"
01834 "AC1BEE53CF98AAB2BA75239D228BF946D99CD0899C250CF1850D17ADD418E389F4ACE5A942"
01835 "6A1251074E28C13A818477875BC0FF732517A6CFB18A23F633E9D0F876582907AC8C3403A5"
01836 "7BBAC9706D7BFAABEDF132A3990E6C4089BAD9939F1F8CE910779BE5CF96EAE87716BDC45CB"
01837 "5C7BCB5D14123D03BE2E50909C523D10096335770D849D509811EC426D80E1115B3AF367D9"
01838 "41C74D8025D7C7F5B2AEC5E5E7AD5F38538CFE33387B5D19AB846A7CFA6C6CC4E0AFC054DF"
01839 "EDCDBD0A8B489A082B3B2A064EBE0902AF6BDA5B64310641F2D717D06E1064D2C2C0ABB19C"
01840 "66DFBA807E36ACE0F6BB487C9868C2F354909960BDF7A8B4C42CC935EDFB10C1975F051D40"
01841 "29A76D255A1CBAD199393A8A7BBCF80C25649C22B475244323D5323675D74886B30A90B9B9"
01842 "1939521DE115DD5AD0509363C6057B9DB321C0871D45B9269B048A98148BD91E3976DDB740"
01843 "5F0AA990A8C7987767F76AD1CBAA8B442DF151E28FFE3D4A985BFF6C263108D8873CE28F62"
01844 "DEDF610ECB1A6C35FE5D66F437B227F184D856EF994099763510425B16234A31B14FC8BD6B"
01845 "C37264F9BAEBF838AC2D03BEA98EA7F9FA0160A21BC211EBFB82A5CC2A70F72FFBED8170AE"
01846 "C8209A6B7ED8CFA7A6FFB9E956239C9A50249D14E365EA7166033BC83D1FB6F336A8BC85E0"
01847 "EB6EE26EFD4B8A5028CA26F9CE872C7A3CFD21CACF29E42DE0309211CCC8143C7CB336A450"
01848 "A2B786D526F53265B60339ABC9ECA67FAAFBD3CE1DE3C3867A9D11D758AE3162BC3D464EDD"
01849 "1C77EA1A4B4A3A0BDB80D05E566F97DF2555E427C8466AE006876402B89FBF37CA38ADDBC2"
01850 "083D30D7F27DAEAEF334" // PRN 50
01851 };
01852
01853
01854 constexpr size_t GALILEO_E6_C_SECONDARY_CODE_STR_LENGTH = 25;
01855 constexpr char GALILEO_E6_C_SECONDARY_CODE[GALILEO_E6_NUMBER_OF_CODES][26] = {
01856 "83F6F69D8F6E15411FB8C9B1C", // PRN 01
01857 "66558BD3CE0C7792E83350525", // PRN 02
01858 "59A025A9C1AF0651B779A8381", // PRN 03
01859 "D3A32640782F7B18E4DF754B7", // PRN 04
01860 "B91FCAD7760C218FA59348A93", // PRN 05
01861 "BAC77E933A779140F094FBF98", // PRN 06
01862 "537785DE280927C6B58BA6776", // PRN 07
01863 "EFCAB4B65F38531ECA22257E2", // PRN 08
01864 "79F8CAE838475EA5584BEFC9B", // PRN 09
01865 "CA5170FEA3A810EC606B66494", // PRN 10
01866 "1FC32410652A2C49BD845E567", // PRN 11
01867 "FE0A9A7AFDAC44E42CB95D261", // PRN 12
01868 "B03062DC2B71995D5AD8B7DBE", // PRN 13
01869 "F6C398993F598E2DF4235D3D5", // PRN 14
01870 "1BB2FB8B5BF24395C2EF3C5A1", // PRN 15
01871 "2F920687D238CC7046EF6AFC9", // PRN 16
01872 "34163886FC4ED7F2A92EFDDB8", // PRN 17
01873 "66A872CE47833FB2DFD5625AD", // PRN 18
01874 "99D5A70162C920A4BB9DE1CA8", // PRN 19
01875 "81D71BD6E069A7ACCBEDC66CA", // PRN 20
01876 "A654524074A9E6780DB9D3EC6", // PRN 21
01877 "C3396A101BEDAF623CFC5BB37", // PRN 22
01878 "C3D4AB211DF36F2111F2141CD", // PRN 23
01879 "3DFF25EAE761739265AF145C1", // PRN 24
01880 "994909E0757D70CDE389102B5", // PRN 25
01881 "B938535522D119F40C25FDAEC", // PRN 26
01882 "C71AB549C0491537026B390B7", // PRN 27
01883 "0CDB8C9E7B53F55F5B0A0597B", // PRN 28
01884 "61C5FA252F1AF81144766494F", // PRN 29
01885 "626027778FD3C6BB4BAA7A59D", // PRN 30
01886 "E745412FF53DEBD03F1C9A633", // PRN 31
01887 "3592AC083F3175FA724639098", // PRN 32
01888 "52284D941C3DCAF2721DDB1FD", // PRN 33
01889 "73B3D8F0AD55DF4FE814ED890", // PRN 34
01890 "94BF16C83BD7462F6498E0282", // PRN 35
01891 "A8C3DE1AC668089B0B45B3579", // PRN 36
01892 "E23FFC2DD2C14388AD8D6BEC8", // PRN 37
01893 "F2AC871CDF89DDC06B5960D2B", // PRN 38
01894 "06191EC1F622A77A526868BA1", // PRN 39
01895 "22D6E2A768E5F35FFC8E01796", // PRN 40
01896 "25310A06675EB271F2A09EA1D", // PRN 41
01897 "9F7993C621D4BEC81A0535703", // PRN 42
01898 "D62999EACF1C99083C0B4A417", // PRN 43
01899 "F665A7EA441BAA4EA0D01078C", // PRN 44
01900 "46F3D3043F24CDEABD6F79543", // PRN 45
01901 "E2E3E8254616BD96CEFC6A651A", // PRN 46
01902 "E548231A82F9A01A19DB5E1B2", // PRN 47
01903 "265C7F90A16F49EDE2AA706C8", // PRN 48
01904 "364A3A9EB0F0481DA0199D7EA", // PRN 49
01905 "9810A7A898961263A0F749F56" // PRN 50
01906 };
01907
01908
01909 /** \} */
01910 /** \} */
01911 #endif // GNSS_SDR_GALILEO_E6_H
```

13.745 galileo_ephemeris.h File Reference

Interface of a Galileo EPHEMERIS storage.

```
#include "gnss_ephemeris.h"
#include <boost/serialization/nvp.hpp>
#include <cstdint>
```

Classes

- class [Galileo_Ephemeris](#)

This class is a storage and orbital model functions for the Galileo SV ephemeris data as described in Galileo ICD paragraph 5.1.1.

13.745.1 Detailed Description

Interface of a Galileo EPHEMERIS storage.

Author

Javier Arribas, 2013. jarribas(at)cttc.es,

Mara Branzanti 2013. mara.branzanti(at)gmail.com

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [galileo_ephemeris.h](#).

13.746 galileo_ephemeris.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file galileo_ephemeris.h
00003  * \brief Interface of a Galileo EPHEMERIS storage
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es,
00005  * \author Mara Branzanti 2013. mara.branzanti(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GALILEO_EPHEMERIS_H
00020 #define GNSS_SDR_GALILEO_EPHEMERIS_H
00021
00022 #include "gnss_ephemeris.h"
00023 #include <boost/serialization/nvp.hpp>
00024 #include <cstdint>
00025
00026 /** \addtogroup Core
00027  * \{ */
00028 /** \addtogroup System_Parameters
00029  * \{ */
00030
00031
00032 /*!
00033  * \brief This class is a storage and orbital model functions for the Galileo SV
00034  * ephemeris data as described in Galileo ICD paragraph 5.1.1
00035  *
00036  * (See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf )
00037  *
00038  */
00039 class Galileo_Ephemeris : public Gnss_Ephemeris
00040 {
00041 public:
00042     Galileo_Ephemeris()
00043     {
```

```

00044         this->System = 'E';
00045     }
00046
00047     double Galileo_System_Time(double week_number, double TOW);    //!< Galileo System Time (GST), ICD
                                paragraph 5.1.2
00048
00049     int32_t IOD_ephemeris{};
00050     int32_t IOD_nav{};
00051
00052     // SV status
00053     int32_t SISA{};    //!< Signal in space accuracy index
00054     int32_t E5a_HS{};    //!< E5a Signal Health Status
00055     int32_t E5b_HS{};    //!< E5b Signal Health Status
00056     int32_t E1B_HS{};    //!< E1B Signal Health Status
00057     bool E5a_DVS{};    //!< E5a Data Validity Status
00058     bool E5b_DVS{};    //!< E5b Data Validity Status
00059     bool E1B_DVS{};    //!< E1B Data Validity Status
00060     double BGD_E1E5a{};    //!< E1-E5a Broadcast Group Delay [s]
00061     double BGD_E1E5b{};    //!< E1-E5b Broadcast Group Delay [s]
00062
00063     bool flag_all_ephemeris{};
00064
00065     template <class Archive>
00066
00067     /*!
00068     * \brief Serialize is a boost standard method to be called by the boost XML
00069     * serialization. Here is used to save the ephemeris data on disk file.
00070     */
00071     inline void serialize(Archive& archive, const uint32_t version)
00072     {
00073         if (version)
00074         {
00075             };
00076
00077         archive& BOOST_SERIALIZATION_NVP(PRN);
00078         archive& BOOST_SERIALIZATION_NVP(M_0);
00079         archive& BOOST_SERIALIZATION_NVP(delta_n);
00080         archive& BOOST_SERIALIZATION_NVP(ecc);
00081         archive& BOOST_SERIALIZATION_NVP(sqrtA);
00082         archive& BOOST_SERIALIZATION_NVP(OMEGA_0);
00083         archive& BOOST_SERIALIZATION_NVP(i_0);
00084         archive& BOOST_SERIALIZATION_NVP(omega);
00085         archive& BOOST_SERIALIZATION_NVP(OMEGAdot);
00086         archive& BOOST_SERIALIZATION_NVP(idot);
00087         archive& BOOST_SERIALIZATION_NVP(Cuc);
00088         archive& BOOST_SERIALIZATION_NVP(Cus);
00089         archive& BOOST_SERIALIZATION_NVP(Crc);
00090         archive& BOOST_SERIALIZATION_NVP(Crs);
00091         archive& BOOST_SERIALIZATION_NVP(Cic);
00092         archive& BOOST_SERIALIZATION_NVP(Cis);
00093         archive& BOOST_SERIALIZATION_NVP(toe);
00094         archive& BOOST_SERIALIZATION_NVP(toc);
00095         archive& BOOST_SERIALIZATION_NVP(af0);
00096         archive& BOOST_SERIALIZATION_NVP(af1);
00097         archive& BOOST_SERIALIZATION_NVP(af2);
00098         archive& BOOST_SERIALIZATION_NVP(WN);
00099         archive& BOOST_SERIALIZATION_NVP(tow);
00100         archive& BOOST_SERIALIZATION_NVP(satClkDrift);
00101         archive& BOOST_SERIALIZATION_NVP(dtr);
00102
00103         archive& BOOST_SERIALIZATION_NVP(IOD_ephemeris);
00104         archive& BOOST_SERIALIZATION_NVP(IOD_nav);
00105         archive& BOOST_SERIALIZATION_NVP(SISA);
00106         archive& BOOST_SERIALIZATION_NVP(E5a_HS);
00107         archive& BOOST_SERIALIZATION_NVP(E5b_HS);
00108         archive& BOOST_SERIALIZATION_NVP(E1B_HS);
00109         archive& BOOST_SERIALIZATION_NVP(E5a_DVS);
00110         archive& BOOST_SERIALIZATION_NVP(E5b_DVS);
00111         archive& BOOST_SERIALIZATION_NVP(E1B_DVS);
00112         archive& BOOST_SERIALIZATION_NVP(BGD_E1E5a);
00113         archive& BOOST_SERIALIZATION_NVP(BGD_E1E5b);
00114         archive& BOOST_SERIALIZATION_NVP(flag_all_ephemeris);
00115     }
00116 };
00117
00118
00119 /** \} */
00120 /** \} */
00121 #endif    // GNSS_SDR_GALILEO_EPHEMERIS_H

```

13.747 Galileo_FNAV.h File Reference

Galileo FNAV message constants.

```
#include "MATH_CONSTANTS.h"
#include <stdint>
#include <utility>
#include <vector>
```

Functions

- `const std::vector< std::pair< int32_t, int32_t > > FNAV_PAGE_TYPE_BIT ({1, 6})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_SV_ID_PRN_1_BIT ({7, 6})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IO_DNAV_1_BIT ({13, 10})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_T0C_1_BIT ({23, 14})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF0_1_BIT ({37, 31})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF1_1_BIT ({68, 21})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF2_1_BIT ({89, 6})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_SISA_1_BIT ({95, 8})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AI0_1_BIT ({103, 11})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AI1_1_BIT ({114, 11})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AI2_1_BIT ({125, 14})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_REGION1_1_BIT ({139, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_REGION2_1_BIT ({140, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_REGION3_1_BIT ({141, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_REGION4_1_BIT ({142, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_REGION5_1_BIT ({143, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_BGD_1_BIT ({144, 10})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E5AHS_1_BIT ({154, 2})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_WN_1_BIT ({156, 12})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_TOW_1_BIT ({168, 20})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E5ADVS_1_BIT ({188, 1})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IO_DNAV_2_BIT ({7, 10})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_M0_2_BIT ({17, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGADOT_2_BIT ({49, 24})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E_2_BIT ({73, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_A12_2_BIT ({105, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGA0_2_BIT ({137, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IDOT_2_BIT ({169, 14})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_WN_2_BIT ({183, 12})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_TOW_2_BIT ({195, 20})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IO_DNAV_3_BIT ({7, 10})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_I0_3_BIT ({17, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_3_BIT ({49, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTAN_3_BIT ({81, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_CUC_3_BIT ({97, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_CUS_3_BIT ({113, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_CRC_3_BIT ({129, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_CRS_3_BIT ({145, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_T0E_3_BIT ({161, 14})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_WN_3_BIT ({175, 12})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_TOW_3_BIT ({187, 20})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IO_DNAV_4_BIT ({7, 10})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_CIC_4_BIT ({17, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_CIS_4_BIT ({33, 16})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_A0_4_BIT ({49, 32})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_A1_4_BIT ({81, 24})`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTATLS_4_BIT ({105, 8})`

- `const std::vector< std::pair< int32_t, int32_t > > FNAV_T0T_4_BIT {{{113, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_NOT_4_BIT {{{121, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_NLSF_4_BIT {{{129, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DN_4_BIT {{{137, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTATLSF_4_BIT {{{140, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_T0G_4_BIT {{{148, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_A0G_4_BIT {{{156, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_A1G_4_BIT {{{172, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_N0G_4_BIT {{{184, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_TOW_4_BIT {{{190, 20}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IO_DA_5_BIT {{{7, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_NA_5_BIT {{{11, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_T0A_5_BIT {{{13, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_SVI_D1_5_BIT {{{23, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTA12_1_5_BIT {{{29, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E_1_5_BIT {{{42, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_1_5_BIT {{{53, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTAI_1_5_BIT {{{69, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGA0_1_5_BIT {{{80, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGADOT_1_5_BIT {{{96, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_M0_1_5_BIT {{{107, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF0_1_5_BIT {{{123, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF1_1_5_BIT {{{139, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E5AHS_1_5_BIT {{{152, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_SVI_D2_5_BIT {{{154, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTA12_2_5_BIT {{{160, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E_2_5_BIT {{{173, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_2_5_BIT {{{184, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTAI_2_5_BIT {{{200, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_IO_DA_6_BIT {{{7, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGADOT_2_6_BIT {{{23, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_M0_2_6_BIT {{{34, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF0_2_6_BIT {{{50, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF1_2_6_BIT {{{66, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E5AHS_2_6_BIT {{{79, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_SVI_D3_6_BIT {{{81, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTA12_3_6_BIT {{{87, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E_3_6_BIT {{{100, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_W_3_6_BIT {{{111, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_DELTAI_3_6_BIT {{{127, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGA0_3_6_BIT {{{138, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_OMEGADOT_3_6_BIT {{{154, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_M0_3_6_BIT {{{165, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF0_3_6_BIT {{{181, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_AF1_3_6_BIT {{{197, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > FNAV_E5AHS_3_6_BIT {{{210, 2}}}`

Variables

- `constexpr int32_t FNAV_T0C_1_LSB = 60`
- `constexpr double FNAV_AF0_1_LSB = TWO_N34`
- `constexpr double FNAV_AF1_1_LSB = TWO_N46`
- `constexpr double FNAV_AF2_1_LSB = TWO_N59`
- `constexpr double FNAV_AI0_1_LSB = TWO_N2`
- `constexpr double FNAV_AI1_1_LSB = TWO_N8`
- `constexpr double FNAV_AI2_1_LSB = TWO_N15`
- `constexpr double FNAV_BGD_1_LSB = TWO_N32`
- `constexpr double FNAV_M0_2_LSB = PI_TWO_N31`
- `constexpr double FNAV_OMEGADOT_2_LSB = PI_TWO_N43`
- `constexpr double FNAV_E_2_LSB = TWO_N33`
- `constexpr double FNAV_A12_2_LSB = TWO_N19`
- `constexpr double FNAV_OMEGA0_2_LSB = PI_TWO_N31`
- `constexpr double FNAV_IDOT_2_LSB = PI_TWO_N43`
- `constexpr double FNAV_I0_3_LSB = PI_TWO_N31`
- `constexpr double FNAV_W_3_LSB = PI_TWO_N31`
- `constexpr double FNAV_DELTAN_3_LSB = PI_TWO_N43`
- `constexpr double FNAV_CUC_3_LSB = TWO_N29`
- `constexpr double FNAV_CUS_3_LSB = TWO_N29`
- `constexpr double FNAV_CRC_3_LSB = TWO_N5`
- `constexpr double FNAV_CRS_3_LSB = TWO_N5`
- `constexpr int32_t FNAV_T0E_3_LSB = 60`
- `constexpr double FNAV_CIC_4_LSB = TWO_N29`
- `constexpr double FNAV_CIS_4_LSB = TWO_N29`
- `constexpr double FNAV_A0_4_LSB = TWO_N30`
- `constexpr double FNAV_A1_4_LSB = TWO_N50`
- `constexpr int32_t FNAV_T0T_4_LSB = 3600`
- `constexpr int32_t FNAV_T0G_4_LSB = 3600`
- `constexpr double FNAV_A0G_4_LSB = TWO_N35`
- `constexpr double FNAV_A1G_4_LSB = TWO_N51`
- `constexpr int32_t FNAV_T0A_5_LSB = 600`
- `constexpr double FNAV_DELTAA12_5_LSB = TWO_N9`
- `constexpr double FNAV_E_5_LSB = TWO_N16`
- `constexpr double FNAV_W_5_LSB = TWO_N15`
- `constexpr double FNAV_DELTAI_5_LSB = TWO_N14`
- `constexpr double FNAV_OMEGA0_5_LSB = TWO_N15`
- `constexpr double FNAV_OMEGADOT_5_LSB = TWO_N33`
- `constexpr double FNAV_M0_5_LSB = TWO_N15`
- `constexpr double FNAV_AF0_5_LSB = TWO_N19`
- `constexpr double FNAV_AF1_5_LSB = TWO_N38`

13.747.1 Detailed Description

Galileo FNAV message constants.

Author

Carles Fernandez, 2020. cfernandez(at)cttc.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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 Definition in file [Galileo_FNAV.h](#).

13.748 Galileo_FNAV.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file Galileo_FNAV.h
00003  * \brief Galileo FNAV message constants
00004  * \author Carles Fernandez, 2020. cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GALILEO_FNAV_H
00019 #define GNSS_SDR_GALILEO_FNAV_H
00020
00021 #include "MATH_CONSTANTS.h"
00022 #include <stdint>
00023 #include <utility>
00024 #include <vector>
00025
00026 /** \addtogroup Core
00027  * \{ */
00028 /** \addtogroup System_Parameters
00029  * \{ */
00030
00031
00032 const std::vector<std::pair<int32_t, int32_t> FNAV_PAGE_TYPE_BIT({{1, 6}});
00033
00034 /* WORD 1 iono corrections. FNAV (Galileo E5a message)*/
00035 const std::vector<std::pair<int32_t, int32_t> FNAV_SV_ID_PRN_1_BIT({{7, 6}});
00036 const std::vector<std::pair<int32_t, int32_t> FNAV_IO_DNAV_1_BIT({{13, 10}});
00037 const std::vector<std::pair<int32_t, int32_t> FNAV_TOC_1_BIT({{23, 14}});
00038 constexpr int32_t FNAV_TOC_1_LSB = 60;
00039 const std::vector<std::pair<int32_t, int32_t> FNAV_AF0_1_BIT({{37, 31}});
00040 constexpr double FNAV_AF0_1_LSB = TWO_N34;
00041 const std::vector<std::pair<int32_t, int32_t> FNAV_AF1_1_BIT({{68, 21}});
00042 constexpr double FNAV_AF1_1_LSB = TWO_N46;
00043 const std::vector<std::pair<int32_t, int32_t> FNAV_AF2_1_BIT({{89, 6}});
00044 constexpr double FNAV_AF2_1_LSB = TWO_N59;
00045 const std::vector<std::pair<int32_t, int32_t> FNAV_SISA_1_BIT({{95, 8}});
00046 const std::vector<std::pair<int32_t, int32_t> FNAV_AI0_1_BIT({{103, 11}});
00047 constexpr double FNAV_AI0_1_LSB = TWO_N2;
00048 const std::vector<std::pair<int32_t, int32_t> FNAV_AI1_1_BIT({{114, 11}});
00049 constexpr double FNAV_AI1_1_LSB = TWO_N8;
00050 const std::vector<std::pair<int32_t, int32_t> FNAV_AI2_1_BIT({{125, 14}});
00051 constexpr double FNAV_AI2_1_LSB = TWO_N15;
00052 const std::vector<std::pair<int32_t, int32_t> FNAV_REGION1_1_BIT({{139, 1}});
00053 const std::vector<std::pair<int32_t, int32_t> FNAV_REGION2_1_BIT({{140, 1}});
00054 const std::vector<std::pair<int32_t, int32_t> FNAV_REGION3_1_BIT({{141, 1}});
00055 const std::vector<std::pair<int32_t, int32_t> FNAV_REGION4_1_BIT({{142, 1}});
00056 const std::vector<std::pair<int32_t, int32_t> FNAV_REGION5_1_BIT({{143, 1}});
00057 const std::vector<std::pair<int32_t, int32_t> FNAV_BGD_1_BIT({{144, 10}});
00058 constexpr double FNAV_BGD_1_LSB = TWO_N32;
00059 const std::vector<std::pair<int32_t, int32_t> FNAV_E5AHS_1_BIT({{154, 2}});
00060 const std::vector<std::pair<int32_t, int32_t> FNAV_WN_1_BIT({{156, 12}});
00061 const std::vector<std::pair<int32_t, int32_t> FNAV_TOW_1_BIT({{168, 20}});
00062 const std::vector<std::pair<int32_t, int32_t> FNAV_E5ADVS_1_BIT({{188, 1}});
00063
00064 // WORD 2 Ephemeris (1/3)
00065 const std::vector<std::pair<int32_t, int32_t> FNAV_IO_DNAV_2_BIT({{7, 10}});
00066 const std::vector<std::pair<int32_t, int32_t> FNAV_M0_2_BIT({{17, 32}});
00067 constexpr double FNAV_M0_2_LSB = PI_TWO_N31;
00068 const std::vector<std::pair<int32_t, int32_t> FNAV_OMEGADOT_2_BIT({{49, 24}});
00069 constexpr double FNAV_OMEGADOT_2_LSB = PI_TWO_N43;
00070 const std::vector<std::pair<int32_t, int32_t> FNAV_E_2_BIT({{73, 32}});
00071 constexpr double FNAV_E_2_LSB = TWO_N33;
00072 const std::vector<std::pair<int32_t, int32_t> FNAV_A12_2_BIT({{105, 32}});
00073 constexpr double FNAV_A12_2_LSB = TWO_N19;
00074 const std::vector<std::pair<int32_t, int32_t> FNAV_OMEGA0_2_BIT({{137, 32}});
00075 constexpr double FNAV_OMEGA0_2_LSB = PI_TWO_N31;
00076 const std::vector<std::pair<int32_t, int32_t> FNAV_IDOT_2_BIT({{169, 14}});
00077 constexpr double FNAV_IDOT_2_LSB = PI_TWO_N43;
00078 const std::vector<std::pair<int32_t, int32_t> FNAV_WN_2_BIT({{183, 12}});
00079 const std::vector<std::pair<int32_t, int32_t> FNAV_TOW_2_BIT({{195, 20}});
00080
00081 // WORD 3 Ephemeris (2/3)
00082 const std::vector<std::pair<int32_t, int32_t> FNAV_IO_DNAV_3_BIT({{7, 10}});
00083 const std::vector<std::pair<int32_t, int32_t> FNAV_IO_3_BIT({{17, 32}});

```

```

00084 constexpr double FNAV_I0_3_LSB = PI_TWO_N31;
00085 const std::vector<std::pair<int32_t, int32_t> FNAV_W_3_BIT({{49, 32}});
00086 constexpr double FNAV_W_3_LSB = PI_TWO_N31;
00087 const std::vector<std::pair<int32_t, int32_t> FNAV_DELTAN_3_BIT({{81, 16}});
00088 constexpr double FNAV_DELTAN_3_LSB = PI_TWO_N43;
00089 const std::vector<std::pair<int32_t, int32_t> FNAV_CUC_3_BIT({{97, 16}});
00090 constexpr double FNAV_CUC_3_LSB = TWO_N29;
00091 const std::vector<std::pair<int32_t, int32_t> FNAV_CUS_3_BIT({{113, 16}});
00092 constexpr double FNAV_CUS_3_LSB = TWO_N29;
00093 const std::vector<std::pair<int32_t, int32_t> FNAV_CRC_3_BIT({{129, 16}});
00094 constexpr double FNAV_CRC_3_LSB = TWO_N5;
00095 const std::vector<std::pair<int32_t, int32_t> FNAV_CRS_3_BIT({{145, 16}});
00096 constexpr double FNAV_CRS_3_LSB = TWO_N5;
00097 const std::vector<std::pair<int32_t, int32_t> FNAV_T0E_3_BIT({{161, 14}});
00098 constexpr int32_t FNAV_T0E_3_LSB = 60;
00099 const std::vector<std::pair<int32_t, int32_t> FNAV_WN_3_BIT({{175, 12}});
00100 const std::vector<std::pair<int32_t, int32_t> FNAV_TOW_3_BIT({{187, 20}});
00101
00102 // WORD 4 Ephemeris (3/3)
00103 const std::vector<std::pair<int32_t, int32_t> FNAV_IO_DNAV_4_BIT({{7, 10}});
00104 const std::vector<std::pair<int32_t, int32_t> FNAV_CIC_4_BIT({{17, 16}});
00105 constexpr double FNAV_CIC_4_LSB = TWO_N29;
00106 const std::vector<std::pair<int32_t, int32_t> FNAV_CIS_4_BIT({{33, 16}});
00107 constexpr double FNAV_CIS_4_LSB = TWO_N29;
00108 const std::vector<std::pair<int32_t, int32_t> FNAV_A0_4_BIT({{49, 32}});
00109 constexpr double FNAV_A0_4_LSB = TWO_N30;
00110 const std::vector<std::pair<int32_t, int32_t> FNAV_A1_4_BIT({{81, 24}});
00111 constexpr double FNAV_A1_4_LSB = TWO_N50;
00112 const std::vector<std::pair<int32_t, int32_t> FNAV_DELTATLS_4_BIT({{105, 8}});
00113 const std::vector<std::pair<int32_t, int32_t> FNAV_T0T_4_BIT({{113, 8}});
00114 constexpr int32_t FNAV_T0T_4_LSB = 3600;
00115 const std::vector<std::pair<int32_t, int32_t> FNAV_W_NOT_4_BIT({{121, 8}});
00116 const std::vector<std::pair<int32_t, int32_t> FNAV_W_NLSF_4_BIT({{129, 8}});
00117 const std::vector<std::pair<int32_t, int32_t> FNAV_DN_4_BIT({{137, 3}});
00118 const std::vector<std::pair<int32_t, int32_t> FNAV_DELTATLSF_4_BIT({{140, 8}});
00119 const std::vector<std::pair<int32_t, int32_t> FNAV_T0G_4_BIT({{148, 8}});
00120 constexpr int32_t FNAV_T0G_4_LSB = 3600;
00121 const std::vector<std::pair<int32_t, int32_t> FNAV_A0G_4_BIT({{156, 16}});
00122 constexpr double FNAV_A0G_4_LSB = TWO_N35;
00123 const std::vector<std::pair<int32_t, int32_t> FNAV_A1G_4_BIT({{172, 12}});
00124 constexpr double FNAV_A1G_4_LSB = TWO_N51;
00125 const std::vector<std::pair<int32_t, int32_t> FNAV_W_N0G_4_BIT({{184, 6}});
00126 const std::vector<std::pair<int32_t, int32_t> FNAV_TOW_4_BIT({{190, 20}});
00127
00128 // WORD 5 Almanac SVID1 SVID2(1/2)
00129 const std::vector<std::pair<int32_t, int32_t> FNAV_IO_DA_5_BIT({{7, 4}});
00130 const std::vector<std::pair<int32_t, int32_t> FNAV_W_NA_5_BIT({{11, 2}});
00131 const std::vector<std::pair<int32_t, int32_t> FNAV_TOA_5_BIT({{13, 10}});
00132 constexpr int32_t FNAV_TOA_5_LSB = 600;
00133 const std::vector<std::pair<int32_t, int32_t> FNAV_SVI_D1_5_BIT({{23, 6}});
00134 const std::vector<std::pair<int32_t, int32_t> FNAV_DELTA12_1_5_BIT({{29, 13}});
00135 constexpr double FNAV_DELTA12_1_5_LSB = TWO_N9;
00136 const std::vector<std::pair<int32_t, int32_t> FNAV_E_1_5_BIT({{42, 11}});
00137 constexpr double FNAV_E_5_LSB = TWO_N16;
00138 const std::vector<std::pair<int32_t, int32_t> FNAV_W_1_5_BIT({{53, 16}});
00139 constexpr double FNAV_W_5_LSB = TWO_N15;
00140 const std::vector<std::pair<int32_t, int32_t> FNAV_DELTAI_1_5_BIT({{69, 11}});
00141 constexpr double FNAV_DELTAI_5_LSB = TWO_N14;
00142 const std::vector<std::pair<int32_t, int32_t> FNAV_OMEGA0_1_5_BIT({{80, 16}});
00143 constexpr double FNAV_OMEGA0_5_LSB = TWO_N15;
00144 const std::vector<std::pair<int32_t, int32_t> FNAV_OMEGADOT_1_5_BIT({{96, 11}});
00145 constexpr double FNAV_OMEGADOT_5_LSB = TWO_N33;
00146 const std::vector<std::pair<int32_t, int32_t> FNAV_M0_1_5_BIT({{107, 16}});
00147 constexpr double FNAV_M0_5_LSB = TWO_N15;
00148 const std::vector<std::pair<int32_t, int32_t> FNAV_AF0_1_5_BIT({{123, 16}});
00149 constexpr double FNAV_AF0_5_LSB = TWO_N19;
00150 const std::vector<std::pair<int32_t, int32_t> FNAV_AF1_1_5_BIT({{139, 13}});
00151 constexpr double FNAV_AF1_5_LSB = TWO_N38;
00152 const std::vector<std::pair<int32_t, int32_t> FNAV_E5AHS_1_5_BIT({{152, 2}});
00153 const std::vector<std::pair<int32_t, int32_t> FNAV_SVI_D2_5_BIT({{154, 6}});
00154 const std::vector<std::pair<int32_t, int32_t> FNAV_DELTA12_2_5_BIT({{160, 13}});
00155 const std::vector<std::pair<int32_t, int32_t> FNAV_E_2_5_BIT({{173, 11}});
00156 const std::vector<std::pair<int32_t, int32_t> FNAV_W_2_5_BIT({{184, 16}});
00157 const std::vector<std::pair<int32_t, int32_t> FNAV_DELTAI_2_5_BIT({{200, 11}});
00158 // const std::vector<std::pair<int,int> FNAV_Omega012_2_5_bit({{210,4}});
00159
00160 // WORD 6 Almanac SVID2(1/2) SVID3
00161 const std::vector<std::pair<int32_t, int32_t> FNAV_IO_DA_6_BIT({{7, 4}});
00162 // const std::vector<std::pair<int,int> FNAV_Omega022_2_6_bit({{10,12}});
00163 const std::vector<std::pair<int32_t, int32_t> FNAV_OMEGADOT_2_6_BIT({{23, 11}});
00164 const std::vector<std::pair<int32_t, int32_t> FNAV_M0_2_6_BIT({{34, 16}});
00165 const std::vector<std::pair<int32_t, int32_t> FNAV_AF0_2_6_BIT({{50, 16}});
00166 const std::vector<std::pair<int32_t, int32_t> FNAV_AF1_2_6_BIT({{66, 13}});
00167 const std::vector<std::pair<int32_t, int32_t> FNAV_E5AHS_2_6_BIT({{79, 2}});
00168 const std::vector<std::pair<int32_t, int32_t> FNAV_SVI_D3_6_BIT({{81, 6}});
00169 const std::vector<std::pair<int32_t, int32_t> FNAV_DELTA12_3_6_BIT({{87, 13}});
00170 const std::vector<std::pair<int32_t, int32_t> FNAV_E_3_6_BIT({{100, 11}});

```

```

00171 const std::vector<std::pair<int32_t, int32_t>> FNAV_W_3_6_BIT({{111, 16}});
00172 const std::vector<std::pair<int32_t, int32_t>> FNAV_DELTAI_3_6_BIT({{127, 11}});
00173 const std::vector<std::pair<int32_t, int32_t>> FNAV_OMEGA0_3_6_BIT({{138, 16}});
00174 const std::vector<std::pair<int32_t, int32_t>> FNAV_OMEGADOT_3_6_BIT({{154, 11}});
00175 const std::vector<std::pair<int32_t, int32_t>> FNAV_M0_3_6_BIT({{165, 16}});
00176 const std::vector<std::pair<int32_t, int32_t>> FNAV_AF0_3_6_BIT({{181, 16}});
00177 const std::vector<std::pair<int32_t, int32_t>> FNAV_AF1_3_6_BIT({{197, 13}});
00178 const std::vector<std::pair<int32_t, int32_t>> FNAV_E5AHS_3_6_BIT({{210, 2}});
00179
00180
00181 /** \} */
00182 /** \} */
00183 #endif // GNSS_SDR_GALILEO_FNAV_H

```

13.749 galileo_fnav_message.h File Reference

Implementation of a Galileo F/NAV Data message as described in Galileo OS SIS ICD Issue 1.2 (Nov. 2015)

```

#include "Galileo_E5a.h"
#include "Galileo_FNAV.h"
#include "galileo_almanac_helper.h"
#include "galileo_ephemeris.h"
#include "galileo_iono.h"
#include "galileo_utc_model.h"
#include <bitset>
#include <cstdint>
#include <string>
#include <utility>
#include <vector>

```

Classes

- class [Galileo_Fnav_Message](#)

This class handles the Galileo F/NAV Data message, as described in the Galileo Open Service Signal in Space Interface Control Document (OS SIS ICD), Issue 2.0 (Jan. 2021). See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf.

13.749.1 Detailed Description

Implementation of a Galileo F/NAV Data message as described in Galileo OS SIS ICD Issue 1.2 (Nov. 2015)

Author

Marc Sales, 2014. marcsales92(at)gmail.com \based on work from:

- Javier Arribas, 2011. jarribas(at)cttc.es

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 Definition in file [galileo_fnav_message.h](#).

13.750 galileo_fnav_message.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_fnav_message.h
00003  * \brief Implementation of a Galileo F/NAV Data message
00004  *       as described in Galileo OS SIS ICD Issue 1.2 (Nov. 2015)
00005  * \author Marc Sales, 2014. marcsales92(at)gmail.com
00006  * \based on work from:
00007  * <ul>
00008  * <li> Javier Arribas, 2011. jarribas(at)cttc.es
00009  * </li>
00010  *
00011  *
00012  * -----
00013  *

```

```

00014  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00015  * This file is part of GNSS-SDR.
00016  *
00017  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00018  * SPDX-License-Identifier: GPL-3.0-or-later
00019  *
00020  * -----
00021  */
00022
00023 #ifndef GNSS_SDR_GALILEO_FNAV_MESSAGE_H
00024 #define GNSS_SDR_GALILEO_FNAV_MESSAGE_H
00025
00026
00027 #include "Galileo_E5a.h"
00028 #include "Galileo_FNAV.h"
00029 #include "galileo_almanac_helper.h"
00030 #include "galileo_ephemeris.h"
00031 #include "galileo_iono.h"
00032 #include "galileo_utc_model.h"
00033 #include <bitset>
00034 #include <stdint>
00035 #include <string>
00036 #include <utility>
00037 #include <vector>
00038
00039 /** \addtogroup Core
00040  * \{ */
00041 /** \addtogroup System_Parameters
00042  * \{ */
00043
00044
00045 /*!
00046  * \brief This class handles the Galileo F/NAV Data message, as described in the
00047  * Galileo Open Service Signal in Space Interface Control Document (OS SIS ICD), Issue 2.0 (Jan.
00048  * 2021).
00049  * See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo\_OS\_SIS\_ICD\_v2.0.pdf
00050  */
00051 class Galileo_Fnav_Message
00052 {
00053 public:
00054     Galileo_Fnav_Message() = default;
00055
00056     void split_page(const std::string& page_string);
00057     bool have_new_ephemeris();
00058     bool have_new_iono_and_GST();
00059     bool have_new_utc_model();
00060     bool have_new_almanac();
00061     Galileo_Ephemeris get_ephemeris() const;
00062     Galileo_Iono get_iono() const;
00063     Galileo_Utc_Model get_utc_model() const;
00064     Galileo_Almanac_Helper get_almanac() const;
00065
00066     inline int32_t get_TOW1() const
00067     {
00068         return FNAV_TOW_1;
00069     }
00070
00071     inline int32_t get_TOW2() const
00072     {
00073         return FNAV_TOW_2;
00074     }
00075
00076     inline int32_t get_TOW3() const
00077     {
00078         return FNAV_TOW_3;
00079     }
00080
00081     inline int32_t get_TOW4() const
00082     {
00083         return FNAV_TOW_4;
00084     }
00085
00086     inline bool get_flag_CRC_test() const
00087     {
00088         return flag_CRC_test;
00089     }
00090
00091     inline bool get_flag_TOW_set() const
00092     {
00093         return flag_TOW_set;
00094     }
00095
00096     inline void set_flag_TOW_set(bool flag_tow)
00097     {
00098         flag_TOW_set = flag_tow;
00099     }
00100

```

```

00100     inline bool is_TOW1_set() const
00101     {
00102         return flag_TOW_1;
00103     }
00104
00105     inline void set_TOW1_flag(bool flag_tow1)
00106     {
00107         flag_TOW_1 = flag_tow1;
00108     }
00109
00110     inline bool is_TOW2_set() const
00111     {
00112         return flag_TOW_2;
00113     }
00114
00115     inline void set_TOW2_flag(bool flag_tow2)
00116     {
00117         flag_TOW_2 = flag_tow2;
00118     }
00119
00120     inline bool is_TOW3_set() const
00121     {
00122         return flag_TOW_3;
00123     }
00124
00125     inline void set_TOW3_flag(bool flag_tow3)
00126     {
00127         flag_TOW_3 = flag_tow3;
00128     }
00129
00130     inline bool is_TOW4_set() const
00131     {
00132         return flag_TOW_4;
00133     }
00134
00135     inline void set_TOW4_flag(bool flag_tow4)
00136     {
00137         flag_TOW_4 = flag_tow4;
00138     }
00139
00140 private:
00141     bool CRC_test(const std::bitset<GALILEO_FNAV_DATA_FRAME_BITS>& bits, uint32_t checksum) const;
00142     void decode_page(const std::string& data);
00143     uint64_t read_navigation_unsigned(const std::bitset<GALILEO_FNAV_DATA_FRAME_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00144     int64_t read_navigation_signed(const std::bitset<GALILEO_FNAV_DATA_FRAME_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00145
00146     std::string omega0_1{};
00147     // std::string omega0_2{};
00148     // bool omega_flag{};
00149
00150     int32_t IOD_ephemeris{};
00151
00152     int32_t page_type{};
00153     // WORD 1 SVID, Clock correction, SISA, Ionospheric correction, BGD, GST, Signal
00154     // health and Data validity status
00155     int32_t FNAV_SV_ID_PRN_1{};
00156     int32_t FNAV_IODnav_1{};
00157     int32_t FNAV_t0c_1{};
00158     double FNAV_af0_1{};
00159     double FNAV_af1_1{};
00160     double FNAV_af2_1{};
00161     int32_t FNAV_SISA_1{};
00162     double FNAV_ai0_1{};
00163     double FNAV_ai1_1{};
00164     double FNAV_ai2_1{};
00165     double FNAV_BGD_1{};
00166     int32_t FNAV_E5ahs_1{};
00167     int32_t FNAV_WN_1{};
00168     int32_t FNAV_TOW_1{};
00169     bool FNAV_region1_1{};
00170     bool FNAV_region2_1{};
00171     bool FNAV_region3_1{};
00172     bool FNAV_region4_1{};
00173     bool FNAV_region5_1{};
00174     bool FNAV_E5advs_1{};
00175
00176     // WORD 2 Ephemeris (1/3) and GST
00177     int32_t FNAV_IODnav_2{};
00178     double FNAV_M0_2{};
00179     double FNAV_omegadot_2{};
00180     double FNAV_e_2{};
00181     double FNAV_a12_2{};
00182     double FNAV_omega0_2{};
00183     double FNAV_idot_2{};
00184     int32_t FNAV_WN_2{};

```

```

00185     int32_t FNAV_TOW_2{};
00186
00187     // WORD 3 Ephemeris (2/3) and GST
00188     int32_t FNAV_IODnav_3{};
00189     double FNAV_i0_3{};
00190     double FNAV_w_3{};
00191     double FNAV_deltan_3{};
00192     double FNAV_Cuc_3{};
00193     double FNAV_Cus_3{};
00194     double FNAV_Crc_3{};
00195     double FNAV_Crs_3{};
00196     int32_t FNAV_t0e_3{};
00197     int32_t FNAV_WN_3{};
00198     int32_t FNAV_TOW_3{};
00199
00200     // WORD 4 Ephemeris (3/3), GST-UTC conversion, GST-GPS conversion and TOW.
00201     // Note that the clock is repeated in this page type
00202     int32_t FNAV_IODnav_4{};
00203     double FNAV_Cic_4{};
00204     double FNAV_Cis_4{};
00205     double FNAV_A0_4{};
00206     double FNAV_A1_4{};
00207     int32_t FNAV_deltatls_4{};
00208     int32_t FNAV_t0t_4{};
00209     int32_t FNAV_WN0t_4{};
00210     int32_t FNAV_WN1sf_4{};
00211     int32_t FNAV_DN_4{};
00212     int32_t FNAV_deltatlsf_4{};
00213     int32_t FNAV_t0g_4{};
00214     double FNAV_A0g_4{};
00215     double FNAV_A1g_4{};
00216     int32_t FNAV_WN0g_4{};
00217     int32_t FNAV_TOW_4{};
00218
00219     // WORD 5 Almanac (SVID1 and SVID2(1/2)), Week Number and almanac reference time
00220     int32_t FNAV_IODa_5{};
00221     int32_t FNAV_WNa_5{};
00222     int32_t FNAV_t0a_5{};
00223     int32_t FNAV_SVID1_5{};
00224     double FNAV_Deltaa12_1_5{};
00225     double FNAV_e_1_5{};
00226     double FNAV_w_1_5{};
00227     double FNAV_deltai_1_5{};
00228     double FNAV_Omega0_1_5{};
00229     double FNAV_Omegadot_1_5{};
00230     double FNAV_M0_1_5{};
00231     double FNAV_af0_1_5{};
00232     double FNAV_af1_1_5{};
00233     uint32_t FNAV_E5ahs_1_5{};
00234     int32_t FNAV_SVID2_5{};
00235     double FNAV_Deltaa12_2_5{};
00236     double FNAV_e_2_5{};
00237     double FNAV_w_2_5{};
00238     double FNAV_deltai_2_5{};
00239
00240     // WORD 6 Almanac (SVID2(2/2) and SVID3)
00241     int32_t FNAV_IODa_6{};
00242     double FNAV_Omega0_2_6{};
00243     double FNAV_Omegadot_2_6{};
00244     double FNAV_M0_2_6{};
00245     double FNAV_af0_2_6{};
00246     double FNAV_af1_2_6{};
00247     int32_t FNAV_E5ahs_2_6{};
00248     int32_t FNAV_SVID3_6{};
00249     double FNAV_Deltaa12_3_6{};
00250     double FNAV_e_3_6{};
00251     double FNAV_w_3_6{};
00252     double FNAV_deltai_3_6{};
00253     double FNAV_Omega0_3_6{};
00254     double FNAV_Omegadot_3_6{};
00255     double FNAV_M0_3_6{};
00256     double FNAV_af0_3_6{};
00257     double FNAV_af1_3_6{};
00258     int32_t FNAV_E5ahs_3_6{};
00259
00260     bool flag_CRC_test{};
00261     bool flag_all_ephemeris{}; // Flag indicating that all words containing ephemeris have been
received
00262     bool flag_ephemeris_1{}; // Flag indicating that ephemeris 1/3 (word 2) have been received
00263     bool flag_ephemeris_2{}; // Flag indicating that ephemeris 2/3 (word 3) have been received
00264     bool flag_ephemeris_3{}; // Flag indicating that ephemeris 3/3 (word 4) have been received
00265
00266     bool flag_iono_and_GST{}; // Flag indicating that ionospheric and GST parameters (word 1) have
been received
00267     bool flag_TOW_1{};
00268     bool flag_TOW_2{};
00269     bool flag_TOW_3{};

```

```

00270     bool flag_TOW_4{};
00271     bool flag_TOW_set{};    // it is true when page 1,2,3 or 4 arrives
00272     bool flag_utc_model{};  // Flag indicating that utc model parameters (word 4) have been received
00273
00274     bool flag_all_almanac{}; // Flag indicating that all Almanac data have been received
00275     bool flag_almanac_1{};   // Flag indicating that almanac 1/2 (word 5) have been received
00276     bool flag_almanac_2{};   // Flag indicating that almanac 2/2 (word 6) have been received
00277 };
00278
00279
00280 /** \} */
00281 /** \} */
00282 #endif // GNSS_SDR_GALILEO_FNAV_MESSAGE_H

```

13.751 galileo_has_data.h File Reference

Class for Galileo HAS message type 1 data storage.

```

#include <cstdint>
#include <string>
#include <vector>

```

Classes

- struct [mt1_header](#)
- class [Galileo_HAS_data](#)

This class is a storage for Galileo HAS message type 1, as defined in Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022. See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_HAS_SIS_ICD_v1.0.pdf.

13.751.1 Detailed Description

Class for Galileo HAS message type 1 data storage.

Author

Carles Fernandez-Prades, 2020-2022 cfernandez(at)cttc.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [galileo_has_data.h](#).

13.752 galileo_has_data.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_has_data.h
00003  * \brief Class for Galileo HAS message type 1 data storage
00004  * \author Carles Fernandez-Prades, 2020-2022 cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GALILEO_HAS_DATA_H
00019 #define GNSS_SDR_GALILEO_HAS_DATA_H
00020
00021 #include <cstdint>
00022 #include <string>
00023 #include <vector>
00024
00025 /** \addtogroup Core
00026  * \{ */

```



```

00027 /** \addtogroup System_Parameters
00028 * \{ */
00029
00030 struct mt1_header
00031 {
00032     uint16_t toh;
00033     uint8_t mask_id;
00034     uint8_t iod_set_id;
00035     uint8_t reserved;
00036     bool mask_flag;
00037     bool orbit_correction_flag;
00038     bool clock_fullset_flag;
00039     bool clock_subset_flag;
00040     bool code_bias_flag;
00041     bool phase_bias_flag;
00042 };
00043
00044 /*!
00045 * \brief This class is a storage for Galileo HAS message type 1, as defined in
00046 * Galileo High Accuracy Service Signal-In-Space Interface Control Document
00047 * (HAS SIS ICD) Issue 1.0, May 2022.
00048 * See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_HAS_SIS_ICD_v1.0.pdf
00049 */
00050 class Galileo_HAS_data
00051 {
00052 public:
00053     Galileo_HAS_data() = default;
00054
00055     std::vector<std::string> get_signals_in_mask(uint8_t nsys) const;           //!< Get a
vector of Nsys std::string with signals in mask for system nsys, with 0 <= nsys < Nsys
00056     std::vector<std::string> get_signals_in_mask(const std::string& system) const; //!< Get a
vector of Nsys std::string with signals in mask for system ("GPS"/"Galileo")
00057     std::vector<std::string> get_systems_string() const;                       //!< Get Nsys
system name strings
00058     std::vector<std::string> get_systems_subset_string() const;               //!< Get Nsat
system name strings present in clock corrections subset
00059     std::vector<std::vector<float>> get_code_bias_m() const;                  //!< Get Nsat
x Ncodes code biases in [m]
00060     std::vector<std::vector<float>> get_phase_bias_cycle() const;             //!< Get Nsat
x Nphases phase biases in [cycles]
00061     std::vector<std::vector<float>> get_delta_clock_subset_correction_m() const; //!< Get
Nsys_sub vectors with Nsat_sub delta clock C0 corrections in [m]
00062     std::vector<float> get_delta_radial_m() const;                           //!< Get Nsat
delta radial corrections in [m]
00063     std::vector<float> get_delta_radial_m(uint8_t nsys) const;               //!< Get
delta radial corrections in [m] for system nsys, with 0 <= nsys < Nsys
00064     std::vector<float> get_delta_in_track_m() const;                         //!< Get Nsat
delta in-track corrections in [m]
00065     std::vector<float> get_delta_in_track_m(uint8_t nsys) const;             //!< Get
delta in-track corrections in [m] for system nsys, with 0 <= nsys < Nsys
00066     std::vector<float> get_delta_cross_track_m() const;                      //!< Get Nsat
delta cross-track corrections in [m]
00067     std::vector<float> get_delta_cross_track_m(uint8_t nsys) const;          //!< Get
delta cross-track corrections in [m] for system nsys, with 0 <= nsys < Nsys
00068     std::vector<float> get_delta_clock_correction_m() const;                 //!< Get Nsat
delta clock C0 corrections in [m]
00069     std::vector<float> get_delta_clock_correction_m(uint8_t nsys) const;      //!< Get
delta clock C0 corrections in [m] for system nsys, with 0 <= nsys < Nsys
00070     std::vector<float> get_delta_clock_subset_correction_m(uint8_t nsys) const; //!< Get
delta clock C0 subset corrections in [m] for system nsys, with 0 <= nsys < Nsys
00071     std::vector<int> get_PRNs_in_mask(uint8_t nsys) const;                   //!< Get PRNs
in mask for system nsys, with 0 <= nsys < Nsys
00072     std::vector<int> get_PRNs_in_mask(const std::string& system) const;      //!< Get PRNs
in mask for system ("GPS"/"Galileo")
00073     std::vector<int> get_PRNs_in_submask(uint8_t nsys) const;                //!< Get PRNs
in submask for system nsys, with 0 <= nsys < Nsys
00074     std::vector<uint16_t> get_gnss_iod(uint8_t nsys) const;                  //!< Get GNSS
IODs for for system nsys, with 0 <= nsys < Nsys
00075     std::vector<uint8_t> get_num_satellites() const;                         //!< Get Nsys
number of satellites
00076     std::vector<uint8_t> get_num_subset_satellites() const;                  //!< Get
Nsys_sub number of satellites
00077     float get_code_bias_m(const std::string& signal, int PRN) const;          //!< Get code
bias in [m] for a given signal and PRN satellite
00078     float get_phase_bias_cycle(const std::string& signal, int PRN) const;     //!< Get
phase bias in [cycles] for a given signal and PRN satellite
00079     float get_delta_radial_m(const std::string& system, int prn) const;        //!< Get
orbital radial correction in [m] for a given system ("GPS"/"Galileo") and PRN
00080     float get_delta_in_track_m(const std::string& system, int prn) const;      //!< Get
orbital in-track correction in [m] for a given system ("GPS"/"Galileo") and PRN
00081     float get_delta_cross_track_m(const std::string& system, int prn) const;   //!< Get
orbital cross-track correction in [m] for a given system ("GPS"/"Galileo") and PRN
00082     float get_clock_correction_mult_m(const std::string& system, int prn) const; //!< Get
clock correction in [m], already multiplied by its Delta Clock Multiplier, for a given system
("GPS"/"Galileo") and PRN
00083     float get_clock_subset_correction_mult_m(const std::string& system, int prn) const; //!< Get
clock correction subset in [m], already multiplied by its Delta Clock Multiplier

```



```

00084     uint16_t get_nsat() const;                                     //!< Get
total number of satellites with corrections
00085     uint16_t get_nsat_sub() const;                                 //!< Get
number of satellites in clock subset corrections
00086     uint16_t get_validity_interval_s(uint8_t validity_interval_index) const; //!< Get
validity interval in [s] from the validity_interval_index
00087     uint16_t get_gnss_iod(const std::string& system, int prn) const;    //!< Get GNSS
IOD from a given system ("GPS"/"Galileo") and PRN
00088     uint8_t get_gnss_id(int nsat) const;                             //!< Get GNSS
ID from the nsat satellite
00089
00090     // Mask
00091     std::vector<uint8_t> gnss_id_mask;                               //!< GNSS ID. See HAS SIS ICD 1.0 Section
5.2.1.1
00092     std::vector<uint64_t> satellite_mask;                           //!< SatM - Satellite Mask. See HAS SIS
ICD 1.0 Section 5.2.1.2
00093     std::vector<uint16_t> signal_mask;                               //!< SigM - Signal Mask. See HAS SIS ICD
1.0 Section 5.2.1.3
00094     std::vector<bool> cell_mask_availability_flag;                 //!< CMAF - Cell Mask Availability Flag.
See HAS SIS ICD 1.0 Section 5.2.1.4
00095     std::vector<std::vector<std::vector<bool>>> cell_mask;          //!< CM - Cell Mask. See HAS SIS ICD 1.0
Section 5.2.1.5
00096     std::vector<uint8_t> nav_message;                               //!< NM - Navigation Message Index. See
HAS SIS ICD 1.0 Section 5.2.1.6
00097
00098     // Orbit corrections
00099     std::vector<uint16_t> gnss_iod;                                  //!< IODref - Reference Issue of Data. See HAS SIS ICD
1.0 Table 26
00100     std::vector<int16_t> delta_radial;                               //!< DR - Delta Radial Correction. See HAS SIS ICD 1.0
Table 25
00101     std::vector<int16_t> delta_in_track;                             //!< DIT - Delta In-Track Correction. See HAS SIS ICD 1.0
Table 25
00102     std::vector<int16_t> delta_cross_track;                         //!< DCT - Delta Cross Correction. See HAS SIS ICD 1.0
Table 25
00103
00104     // Clock full-set corrections
00105     std::vector<uint8_t> delta_clock_multiplier;                   //!< DCM - Delta Clock Multipliers. See HAS SIS ICD
1.0 Section 5.2.3.1
00106     std::vector<int16_t> delta_clock_correction;                   //!< DCC - Delta Clock Corrections. See HAS SIS ICD
1.0 Section 5.2.3.2
00107
00108     // Clock subset corrections
00109     std::vector<uint8_t> gnss_id_clock_subset;                     //!< GNSS ID. Specific
GNSS to which the corrections refer. See HAS SIS ICD 1.0 Section 5.2.1.1
00110     std::vector<uint8_t> delta_clock_multiplier_clock_subset;      //!< DCM. Multiplier for
all Delta Clock corrections. See HAS SIS ICD 1.0 Section 5.2.3.1
00111     std::vector<uint64_t> satellite_submask;                       //!< SatMsub - Satellite
Subset Mask. See HAS SIS ICD 1.0 Section 5.2.4.1
00112     std::vector<std::vector<int16_t>> delta_clock_correction_clock_subset; //!< DCCsub - Delta Clock
Subset Corrections. See HAS SIS ICD 1.0 Section 5.2.4.1
00113
00114     // Code bias
00115     std::vector<std::vector<int16_t>> code_bias;                   //!< CB - Code bias for the m-th signal of the n-th
SV. See HAS SIS ICD 1.0 Section 5.2.5
00116
00117     // Phase bias
00118     std::vector<std::vector<int16_t>> phase_bias;                   //!< PB - Phase bias for the m-th
signal of the n-th SV. See HAS SIS ICD 1.0 Section 5.2.6
00119     std::vector<std::vector<uint8_t>> phase_discontinuity_indicator; //!< PDI - Phase Discontinuity
Indicator. See HAS SIS ICD 1.0 Section 5.2.6.
00120
00121     uint32_t tow;           //!< Time of Week
00122
00123     mt1_header header;      //!< MT1 Header parameters. See HAS SIS ICD 1.0 Section 5.1.1
00124     uint8_t has_status;     //!< HASS - HAS Status (from HAS page header). See HAS SIS ICD 1.0 Section
3.1.1
00125     uint8_t message_id;     //!< MID - Message ID (from HAS page header). See HAS SIS ICD 1.0 Section 3.1
00126
00127     uint8_t Nsys;           //!< Number of GNSS for which corrections are provided. See HAS SIS ICD 1.0
Section 5.2.1
00128     uint8_t Nsys_sub;       //!< Number of GNSS for which corrections are provided in clock subset
corrections. See HAS SIS ICD 1.0 Section 5.2.2.1
00129
00130     uint8_t validity_interval_index_orbit_corrections;             //!< VI - Validity Interval Index for
Orbit corrections. See HAS SIS ICD 1.0 Section 5.2.2.1
00131     uint8_t validity_interval_index_clock_fullset_corrections;     //!< VI - Validity Interval Index for
Clock full-set corrections. See HAS SIS ICD 1.0 Section 5.2.2.1
00132     uint8_t validity_interval_index_clock_subset_corrections;     //!< VI - Validity Interval Index for
Clock subset corrections. See HAS SIS ICD 1.0 Section 5.2.2.1
00133     uint8_t validity_interval_index_code_bias_corrections;        //!< VI - Validity Interval Index for
Code bias. See HAS SIS ICD 1.0 Section 5.2.2.1
00134     uint8_t validity_interval_index_phase_bias_corrections;       //!< VI - Validity Interval Index for
Phase bias. See HAS SIS ICD 1.0 Section 5.2.2.1
00135 };
00136
00137
00138 /** \} */

```

```
00139 /** \} */
00140 #endif // GNSS_SDR_GALILEO_HAS_DATA_H
```

13.753 galileo_has_page.h File Reference

Class for Galileo HAS message page storage.

```
#include <cstdint>
#include <string>
```

Classes

- class [Galileo_HAS_page](#)

This class is a storage for Galileo HAS message page, as defined in Galileo High Accuracy Service Signal-In-Space Interface Control Document (HAS SIS ICD) Issue 1.0, May 2022.

13.753.1 Detailed Description

Class for Galileo HAS message page storage.

Author

Carles Fernandez-Prades, 2021 cfernandez(at)cttc.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors) SPDX-License-Identifier: GPL-3.0-or-later
 Definition in file [galileo_has_page.h](#).

13.754 galileo_has_page.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002 * \file galileo_has_page.h
00003 * \brief Class for Galileo HAS message page storage
00004 * \author Carles Fernandez-Prades, 2021 cfernandez(at)cttc.es
00005 *
00006 * -----
00007 *
00008 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009 * This file is part of GNSS-SDR.
00010 *
00011 * Copyright (C) 2010-2022 (see AUTHORS file for a list of contributors)
00012 * SPDX-License-Identifier: GPL-3.0-or-later
00013 *
00014 * -----
00015 */
00016
00017
00018 #ifndef GNSS_SDR_GALILEO_HAS_PAGE_H
00019 #define GNSS_SDR_GALILEO_HAS_PAGE_H
00020
00021 #include <cstdint>
00022 #include <string>
00023
00024 /** \addtogroup Core
00025 * \{ */
00026 /** \addtogroup System_Parameters
00027 * \{ */
00028
00029
00030 /*!
00031 * \brief This class is a storage for Galileo HAS message page, as defined in
00032 * Galileo High Accuracy Service Signal-In-Space Interface Control Document
00033 * (HAS SIS ICD) Issue 1.0, May 2022
00034 */
00035 class Galileo_HAS_page
00036 {
00037 public:
00038     Galileo_HAS_page() = default;
00039
00040     std::string has_message_string; //!< HAS message content
00041     uint64_t time_stamp{}; //!< HAS page time stamp, in [s]
```

```

00042     uint32_t tow{};                                //!< HAS page time of week, in [s]
00043
00044     // HAS page header
00045     uint8_t has_status{};                            //!< HAS status
00046     uint8_t reserved{};                             //!< HAS reserved field
00047     uint8_t message_type{};                         //!< HAS message type (MT)
00048     uint8_t message_id{};                           //!< HAS message ID (MID)
00049     uint8_t message_size{};                         //!< HAS message size (MS)
00050     uint8_t message_page_id{};                      //!< HAS message page ID (PID)
00051 };
00052
00053
00054 /** \} */
00055 /** \} */
00056 #endif // GNSS_SDR_GALILEO_HAS_PAGE_H

```

13.755 Galileo_INAV.h File Reference

Galileo INAV message constants.

```

#include "MATH_CONSTANTS.h"
#include <stddef>
#include <stdint>
#include <utility>
#include <vector>

```

Functions

- const std::vector< std::pair< int32_t, int32_t > > **TYPE** ({{1, 6}})
- const std::vector< std::pair< int32_t, int32_t > > **PAGE_TYPE_BIT** ({{1, 6}})
- const std::vector< std::pair< int32_t, int32_t > > **IOD_NAV_1_BIT** ({{7, 10}})
- const std::vector< std::pair< int32_t, int32_t > > **T0_E_1_BIT** ({{17, 14}})
- const std::vector< std::pair< int32_t, int32_t > > **M0_1_BIT** ({{31, 32}})
- const std::vector< std::pair< int32_t, int32_t > > **E_1_BIT** ({{63, 32}})
- const std::vector< std::pair< int32_t, int32_t > > **A_1_BIT** ({{95, 32}})
- const std::vector< std::pair< int32_t, int32_t > > **IOD_NAV_2_BIT** ({{7, 10}})
- const std::vector< std::pair< int32_t, int32_t > > **OMEGA_0_2_BIT** ({{17, 32}})
- const std::vector< std::pair< int32_t, int32_t > > **I_0_2_BIT** ({{49, 32}})
- const std::vector< std::pair< int32_t, int32_t > > **OMEGA_2_BIT** ({{81, 32}})
- const std::vector< std::pair< int32_t, int32_t > > **I_DOT_2_BIT** ({{113, 14}})
- const std::vector< std::pair< int32_t, int32_t > > **IOD_NAV_3_BIT** ({{7, 10}})
- const std::vector< std::pair< int32_t, int32_t > > **OMEGA_DOT_3_BIT** ({{17, 24}})
- const std::vector< std::pair< int32_t, int32_t > > **DELTA_N_3_BIT** ({{41, 16}})
- const std::vector< std::pair< int32_t, int32_t > > **C_UC_3_BIT** ({{57, 16}})
- const std::vector< std::pair< int32_t, int32_t > > **C_US_3_BIT** ({{73, 16}})
- const std::vector< std::pair< int32_t, int32_t > > **C_RC_3_BIT** ({{89, 16}})
- const std::vector< std::pair< int32_t, int32_t > > **C_RS_3_BIT** ({{105, 16}})
- const std::vector< std::pair< int32_t, int32_t > > **SISA_3_BIT** ({{121, 8}})
- const std::vector< std::pair< int32_t, int32_t > > **IOD_NAV_4_BIT** ({{7, 10}})
- const std::vector< std::pair< int32_t, int32_t > > **SV_ID_PRN_4_BIT** ({{17, 6}})
- const std::vector< std::pair< int32_t, int32_t > > **C_IC_4_BIT** ({{23, 16}})
- const std::vector< std::pair< int32_t, int32_t > > **C_IS_4_BIT** ({{39, 16}})
- const std::vector< std::pair< int32_t, int32_t > > **T0C_4_BIT** ({{55, 14}})
- const std::vector< std::pair< int32_t, int32_t > > **AF0_4_BIT** ({{69, 31}})
- const std::vector< std::pair< int32_t, int32_t > > **AF1_4_BIT** ({{100, 21}})
- const std::vector< std::pair< int32_t, int32_t > > **AF2_4_BIT** ({{121, 6}})
- const std::vector< std::pair< int32_t, int32_t > > **SPARE_4_BIT** ({{127, 2}})
- const std::vector< std::pair< int32_t, int32_t > > **AI0_5_BIT** ({{7, 11}})
- const std::vector< std::pair< int32_t, int32_t > > **AI1_5_BIT** ({{18, 11}})
- const std::vector< std::pair< int32_t, int32_t > > **AI2_5_BIT** ({{29, 14}})

- `const std::vector< std::pair< int32_t, int32_t > > REGION1_5_BIT {{{43, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > REGION2_5_BIT {{{44, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > REGION3_5_BIT {{{45, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > REGION4_5_BIT {{{46, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > REGION5_5_BIT {{{47, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > BGD_E1_E5A_5_BIT {{{48, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > BGD_E1_E5B_5_BIT {{{58, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E5B_HS_5_BIT {{{68, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E1_B_HS_5_BIT {{{70, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E5B_DVS_5_BIT {{{72, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E1_B_DVS_5_BIT {{{73, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > WN_5_BIT {{{74, 12}}}`
- `const std::vector< std::pair< int32_t, int32_t > > TOW_5_BIT {{{86, 20}}}`
- `const std::vector< std::pair< int32_t, int32_t > > SPARE_5_BIT {{{106, 23}}}`
- `const std::vector< std::pair< int32_t, int32_t > > A0_6_BIT {{{7, 32}}}`
- `const std::vector< std::pair< int32_t, int32_t > > A1_6_BIT {{{39, 24}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_T_LS_6_BIT {{{63, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > T0T_6_BIT {{{71, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > W_NOT_6_BIT {{{79, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > WN_LSF_6_BIT {{{87, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DN_6_BIT {{{95, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_T_LSF_6_BIT {{{98, 8}}}`
- `const std::vector< std::pair< int32_t, int32_t > > TOW_6_BIT {{{106, 20}}}`
- `const std::vector< std::pair< int32_t, int32_t > > IOD_A_7_BIT {{{7, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > WN_A_7_BIT {{{11, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > T0A_7_BIT {{{13, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > SVI_D1_7_BIT {{{23, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_A_7_BIT {{{29, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E_7_BIT {{{42, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_7_BIT {{{53, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_I_7_BIT {{{69, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA0_7_BIT {{{80, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_DOT_7_BIT {{{96, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > M0_7_BIT {{{107, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > IOD_A_8_BIT {{{7, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF0_8_BIT {{{11, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF1_8_BIT {{{27, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E5B_HS_8_BIT {{{40, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E1_B_HS_8_BIT {{{42, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > SVI_D2_8_BIT {{{44, 6}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_A_8_BIT {{{50, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E_8_BIT {{{63, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_8_BIT {{{74, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_I_8_BIT {{{90, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA0_8_BIT {{{101, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_DOT_8_BIT {{{117, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > IOD_A_9_BIT {{{7, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > WN_A_9_BIT {{{11, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > T0A_9_BIT {{{13, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > M0_9_BIT {{{23, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF0_9_BIT {{{39, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > AF1_9_BIT {{{55, 13}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E5B_HS_9_BIT {{{68, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E1_B_HS_9_BIT {{{70, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > SVI_D3_9_BIT {{{72, 6}}}`

- `const std::vector< std::pair< int32_t, int32_t > > DELTA_A_9_BIT` ({78, 13}}
- `const std::vector< std::pair< int32_t, int32_t > > E_9_BIT` ({91, 11}}
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_9_BIT` ({102, 16}}
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_I_9_BIT` ({118, 11}}
- `const std::vector< std::pair< int32_t, int32_t > > IOD_A_10_BIT` ({7, 4}}
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA0_10_BIT` ({11, 16}}
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_DOT_10_BIT` ({27, 11}}
- `const std::vector< std::pair< int32_t, int32_t > > M0_10_BIT` ({38, 16}}
- `const std::vector< std::pair< int32_t, int32_t > > AF0_10_BIT` ({54, 16}}
- `const std::vector< std::pair< int32_t, int32_t > > AF1_10_BIT` ({70, 13}}
- `const std::vector< std::pair< int32_t, int32_t > > E5B_HS_10_BIT` ({83, 2}}
- `const std::vector< std::pair< int32_t, int32_t > > E1_B_HS_10_BIT` ({85, 2}}
- `const std::vector< std::pair< int32_t, int32_t > > A_0_G_10_BIT` ({87, 16}}
- `const std::vector< std::pair< int32_t, int32_t > > A_1_G_10_BIT` ({103, 12}}
- `const std::vector< std::pair< int32_t, int32_t > > T_0_G_10_BIT` ({115, 8}}
- `const std::vector< std::pair< int32_t, int32_t > > WN_0_G_10_BIT` ({123, 6}}
- `const std::vector< std::pair< int32_t, int32_t > > CED_DeltaAred_BIT` ({7, 5}}
- `const std::vector< std::pair< int32_t, int32_t > > CED_exred_BIT` ({12, 13}}
- `const std::vector< std::pair< int32_t, int32_t > > CED_eyred_BIT` ({25, 13}}
- `const std::vector< std::pair< int32_t, int32_t > > CED_DeltaIored_BIT` ({38, 17}}
- `const std::vector< std::pair< int32_t, int32_t > > CED_Omega0red_BIT` ({55, 23}}
- `const std::vector< std::pair< int32_t, int32_t > > CED_lambda0red_BIT` ({78, 23}}
- `const std::vector< std::pair< int32_t, int32_t > > CED_af0red_BIT` ({101, 22}}
- `const std::vector< std::pair< int32_t, int32_t > > CED_af1red_BIT` ({123, 6}}
- `const std::vector< std::pair< int32_t, int32_t > > RS_IODNAV_LSBS` ({15, 2}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_CONSTELLATION_ID_BIT` ({7, 3}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_SERVICE_LEVEL_ID_BIT` ({10, 3}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_WN_BIT` ({13, 12}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_T0_BIT` ({25, 9}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_MASK_MSB_BIT` ({34, 1}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_MASK_BIT` ({35, 32}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_PCONST_BIT` ({67, 4}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_PSAT_BIT` ({71, 4}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_URA_BIT` ({75, 4}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_URE_BIT` ({79, 4}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_BNOM_BIT` ({83, 4}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_TVALIDITY_BIT` ({87, 4}}
- `const std::vector< std::pair< int32_t, int32_t > > ISM_CRC_BIT` ({97, 32}}
- `const std::vector< std::pair< int32_t, int32_t > > TIME_0_BIT` ({7, 2}}
- `const std::vector< std::pair< int32_t, int32_t > > WN_0_BIT` ({97, 12}}
- `const std::vector< std::pair< int32_t, int32_t > > TOW_0_BIT` ({109, 20}}

Variables

- `constexpr double GALILEO_INAV_PAGE_PART_WITH_PREABLE_SECONDS` = 2.04
Page Duration + (Galileo I/NAV Preamble bits)(Galileo E5b-I tiered Code Period(seconds))*
- `constexpr uint32_t GALILEO_INAV_PAGE_SYMBOLS` = 500
The complete Galileo INAV page length.
- `constexpr int32_t GALILEO_INAV_PREAMBLE_LENGTH_BITS` = 10
- `constexpr int32_t GALILEO_INAV_PREAMBLE_PERIOD_SYMBOLS` = 250
- `constexpr int32_t GALILEO_INAV_PAGE_PART_SYMBOLS` = 250
Each Galileo INAV pages are composed of two parts (even and odd) each of 250 symbols, including preamble. See Galileo ICD 4.3.2.
- `constexpr int32_t GALILEO_INAV_PAGE_PART_SECONDS` = 1
- `constexpr int32_t GALILEO_INAV_PAGE_PART_MS` = 1000

- `constexpr int32_t GALILEO_INAV_PAGE_SECONDS = 2`
- `constexpr int32_t GALILEO_INAV_INTERLEAVER_ROWS = 8`
- `constexpr int32_t GALILEO_INAV_INTERLEAVER_COLS = 30`
- `constexpr int32_t GALILEO_TELEMETRY_RATE_BITS_SECOND = 250`
- `constexpr int32_t GALILEO_PAGE_TYPE_BITS = 6`
- `constexpr int32_t GALILEO_DATA_JK_BITS = 128`
- `constexpr int32_t GALILEO_DATA_FRAME_BITS = 196`
- `constexpr int32_t GALILEO_DATA_FRAME_BYTES = 25`
- `constexpr char GALILEO_INAV_PREAMBLE [11] = "0101100000"`
- `constexpr int32_t T0E_1_LSB = 60`
- `constexpr double M0_1_LSB = PI_TWO_N31`
- `constexpr double E_1_LSB = TWO_N33`
- `constexpr double A_1_LSB_GAL = TWO_N19`
- `constexpr double OMEGA_0_2_LSB = PI_TWO_N31`
- `constexpr double I_0_2_LSB = PI_TWO_N31`
- `constexpr double OMEGA_2_LSB = PI_TWO_N31`
- `constexpr double I_DOT_2_LSB = PI_TWO_N43`
- `constexpr double OMEGA_DOT_3_LSB = PI_TWO_N43`
- `constexpr double DELTA_N_3_LSB = PI_TWO_N43`
- `constexpr double C_UC_3_LSB = TWO_N29`
- `constexpr double C_US_3_LSB = TWO_N29`
- `constexpr double C_RC_3_LSB = TWO_N5`
- `constexpr double C_RS_3_LSB = TWO_N5`
- `constexpr double C_IC_4_LSB = TWO_N29`
- `constexpr double C_IS_4_LSB = TWO_N29`
- `constexpr int32_t T0C_4_LSB = 60`
- `constexpr double AF0_4_LSB = TWO_N34`
- `constexpr double AF1_4_LSB = TWO_N46`
- `constexpr double AF2_4_LSB = TWO_N59`
- `constexpr double AI0_5_LSB = TWO_N2`
- `constexpr double AI1_5_LSB = TWO_N8`
- `constexpr double AI2_5_LSB = TWO_N15`
- `constexpr double BGD_E1_E5A_5_LSB = TWO_N32`
- `constexpr double BGD_E1_E5B_5_LSB = TWO_N32`
- `constexpr double A0_6_LSB = TWO_N30`
- `constexpr double A1_6_LSB = TWO_N50`
- `constexpr int32_t T0T_6_LSB = 3600`
- `constexpr int32_t T0A_7_LSB = 600`
- `constexpr double DELTA_A_7_LSB = TWO_N9`
- `constexpr double E_7_LSB = TWO_N16`
- `constexpr double OMEGA_7_LSB = TWO_N15`
- `constexpr double DELTA_I_7_LSB = TWO_N14`
- `constexpr double OMEGA0_7_LSB = TWO_N15`
- `constexpr double OMEGA_DOT_7_LSB = TWO_N33`
- `constexpr double M0_7_LSB = TWO_N15`
- `constexpr double AF0_8_LSB = TWO_N19`
- `constexpr double AF1_8_LSB = TWO_N38`
- `constexpr double DELTA_A_8_LSB = TWO_N9`
- `constexpr double E_8_LSB = TWO_N16`
- `constexpr double OMEGA_8_LSB = TWO_N15`
- `constexpr double DELTA_I_8_LSB = TWO_N14`
- `constexpr double OMEGA0_8_LSB = TWO_N15`
- `constexpr double OMEGA_DOT_8_LSB = TWO_N33`
- `constexpr int32_t T0A_9_LSB = 600`
- `constexpr double M0_9_LSB = TWO_N15`

- constexpr double [AF0_9_LSB](#) = TWO_N19
- constexpr double [AF1_9_LSB](#) = TWO_N38
- constexpr double [DELTA_A_9_LSB](#) = TWO_N9
- constexpr double [E_9_LSB](#) = TWO_N16
- constexpr double [OMEGA_9_LSB](#) = TWO_N15
- constexpr double [DELTA_I_9_LSB](#) = TWO_N14
- constexpr double [OMEGA0_10_LSB](#) = TWO_N15
- constexpr double [OMEGA_DOT_10_LSB](#) = TWO_N33
- constexpr double [M0_10_LSB](#) = TWO_N15
- constexpr double [AF0_10_LSB](#) = TWO_N19
- constexpr double [AF1_10_LSB](#) = TWO_N38
- constexpr double [A_0G_10_LSB](#) = TWO_N35
- constexpr double [A_1G_10_LSB](#) = TWO_N51
- constexpr int32_t [T_0_G_10_LSB](#) = 3600
- constexpr double [CED_DeltaAred_LSB](#) = TWO_P8
- constexpr double [CED_exred_LSB](#) = TWO_N22
- constexpr double [CED_eyred_LSB](#) = TWO_N22
- constexpr double [CED_DeltaI0red_LSB](#) = TWO_N22
- constexpr double [CED_Omega0red_LSB](#) = TWO_N22
- constexpr double [CED_lambda0red_LSB](#) = TWO_N22
- constexpr double [CED_af0red_LSB](#) = TWO_N26
- constexpr double [CED_af1red_LSB](#) = TWO_N35
- constexpr size_t [INAV_RS_SUBVECTOR_LENGTH](#) = 15
- constexpr size_t [INAV_RS_PARITY_VECTOR_LENGTH](#) = 60
- constexpr size_t [INAV_RS_INFO_VECTOR_LENGTH](#) = 58
- constexpr size_t [INAV_RS_BUFFER_LENGTH](#) = 118
- constexpr int32_t [BITS_IN_OCTET](#) = 8
- constexpr int32_t [FIRST_RS_BIT](#) = 7
- constexpr int32_t [FIRST_RS_BIT_AFTER_IODNAV](#) = 17
- constexpr int32_t [GALILEO_ISM_CRC_DATA_BITS](#) = 96
- constexpr int32_t [GALILEO_ISM_CRC_DATA_BYTES](#) = 12
- constexpr char [GALILEO_INAV_PLAIN_SSP1](#) [9] = "00000100"
- constexpr char [GALILEO_INAV_PLAIN_SSP2](#) [9] = "00101011"
- constexpr char [GALILEO_INAV_PLAIN_SSP3](#) [9] = "00101111"
- constexpr char [GALILEO_INAV_ENCODED_SSP1](#) [17] = "1110100100100101"
- constexpr char [GALILEO_INAV_ENCODED_SSP2](#) [17] = "0110110001001110"
- constexpr char [GALILEO_INAV_ENCODED_SSP3](#) [17] = "1101000000111110"

13.755.1 Detailed Description

Galileo INAV message constants.

Author

Carles Fernandez, 2020. cfernandez(at)cttc.es

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 Definition in file [Galileo_INAV.h](#).

13.756 Galileo_INAV.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file Galileo_INAV.h
00003  * \brief Galileo INAV message constants
00004  * \author Carles Fernandez, 2020. cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GALILEO_INAV_H
00019 #define GNSS_SDR_GALILEO_INAV_H
00020
00021 #include "MATH_CONSTANTS.h"
00022 #include <cstdint>
00023 #include <stdint>
00024 #include <utility>
00025 #include <vector>
00026
00027 /** \addtogroup Core
00028  * \{ */
00029 /** \addtogroup System_Parameters
00030  * \{ */
00031
00032
00033 // Galileo INAV message structure
00034 constexpr double GALILEO_INAV_PAGE_PART_WITH_PREAMBLE_SECONDS = 2.04; //!< Page Duration + (Galileo
00035 I/NAV Preamble bits)*(Galileo E5b-I tiered Code Period(seconds))
00036 constexpr uint32_t GALILEO_INAV_PAGE_SYMBOLS = 500; //!<< The complete Galileo INAV
00037 page length
00038 constexpr int32_t GALILEO_INAV_PREAMBLE_LENGTH_BITS = 10;
00039 constexpr int32_t GALILEO_INAV_PREAMBLE_PERIOD_SYMBOLS = 250;
00040 constexpr int32_t GALILEO_INAV_PAGE_PART_SYMBOLS = 250; //!<< Each Galileo INAV pages are composed of
00041 two parts (even and odd) each of 250 symbols, including preamble. See Galileo ICD 4.3.2
00042 constexpr int32_t GALILEO_INAV_PAGE_PART_SECONDS = 1; // a page part last 1 sec
00043 constexpr int32_t GALILEO_INAV_PAGE_PART_MS = 1000; // a page part last 1 sec
00044 constexpr int32_t GALILEO_INAV_PAGE_SECONDS = 2; // a full page last 2 sec
00045 constexpr int32_t GALILEO_INAV_INTERLEAVER_ROWS = 8;
00046 constexpr int32_t GALILEO_INAV_INTERLEAVER_COLS = 30;
00047 constexpr int32_t GALILEO_TELEMETRY_RATE_BITS_SECOND = 250; // bps
00048 constexpr int32_t GALILEO_PAGE_TYPE_BITS = 6;
00049 constexpr int32_t GALILEO_DATA_JK_BITS = 128;
00050 constexpr int32_t GALILEO_DATA_FRAME_BITS = 196;
00051 constexpr int32_t GALILEO_DATA_FRAME_BYTES = 25;
00052 constexpr char GALILEO_INAV_PREAMBLE[11] = "0101100000";
00053
00054 const std::vector<std::pair<int32_t, int32_t>> TYPE({{1, 6}});
00055 const std::vector<std::pair<int32_t, int32_t>> PAGE_TYPE_BIT({{1, 6}});
00056
00057 /* Page 1 - Word type 1: Ephemeris (1/4) */
00058 const std::vector<std::pair<int32_t, int32_t>> IOD_NAV_1_BIT({{7, 10}});
00059 const std::vector<std::pair<int32_t, int32_t>> T0_E_1_BIT({{17, 14}});
00060 constexpr int32_t T0_E_1_LSB = 60;
00061 const std::vector<std::pair<int32_t, int32_t>> M0_1_BIT({{31, 32}});
00062 constexpr double M0_1_LSB = PI_TWO_N31;
00063 const std::vector<std::pair<int32_t, int32_t>> E_1_BIT({{63, 32}});
00064 constexpr double E_1_LSB = TWO_N33;
00065 const std::vector<std::pair<int32_t, int32_t>> A_1_BIT({{95, 32}});
00066 constexpr double A_1_LSB_GAL = TWO_N19;
00067 // last two bits are reserved
00068
00069 /* Page 2 - Word type 2: Ephemeris (2/4) */
00070 const std::vector<std::pair<int32_t, int32_t>> IOD_NAV_2_BIT({{7, 10}});
00071 const std::vector<std::pair<int32_t, int32_t>> OMEGA_0_2_BIT({{17, 32}});
00072 constexpr double OMEGA_0_2_LSB = PI_TWO_N31;
00073 const std::vector<std::pair<int32_t, int32_t>> I_0_2_BIT({{49, 32}});
00074 constexpr double I_0_2_LSB = PI_TWO_N31;
00075 const std::vector<std::pair<int32_t, int32_t>> OMEGA_2_BIT({{81, 32}});
00076 constexpr double OMEGA_2_LSB = PI_TWO_N31;
00077 const std::vector<std::pair<int32_t, int32_t>> I_DOT_2_BIT({{113, 14}});
00078 constexpr double I_DOT_2_LSB = PI_TWO_N43;
00079 // last two bits are reserved
00080
00081 /* Word type 3: Ephemeris (3/4) and SISA */
00082 const std::vector<std::pair<int32_t, int32_t>> IOD_NAV_3_BIT({{7, 10}});

```



```

00081 const std::vector<std::pair<int32_t, int32_t>> OMEGA_DOT_3_BIT({{17, 24}});
00082 constexpr double OMEGA_DOT_3_LSB = PI_TWO_N43;
00083 const std::vector<std::pair<int32_t, int32_t>> DELTA_N_3_BIT({{41, 16}});
00084 constexpr double DELTA_N_3_LSB = PI_TWO_N43;
00085 const std::vector<std::pair<int32_t, int32_t>> C_UC_3_BIT({{57, 16}});
00086 constexpr double C_UC_3_LSB = TWO_N29;
00087 const std::vector<std::pair<int32_t, int32_t>> C_US_3_BIT({{73, 16}});
00088 constexpr double C_US_3_LSB = TWO_N29;
00089 const std::vector<std::pair<int32_t, int32_t>> C_RC_3_BIT({{89, 16}});
00090 constexpr double C_RC_3_LSB = TWO_N5;
00091 const std::vector<std::pair<int32_t, int32_t>> C_RS_3_BIT({{105, 16}});
00092 constexpr double C_RS_3_LSB = TWO_N5;
00093 const std::vector<std::pair<int32_t, int32_t>> SISA_3_BIT({{121, 8}});
00094
00095
00096 /* Word type 4: Ephemeris (4/4) and Clock correction parameters */
00097 const std::vector<std::pair<int32_t, int32_t>> IOD_NAV_4_BIT({{7, 10}});
00098 const std::vector<std::pair<int32_t, int32_t>> SV_ID_PRN_4_BIT({{17, 6}});
00099 const std::vector<std::pair<int32_t, int32_t>> C_IC_4_BIT({{23, 16}});
00100 constexpr double C_IC_4_LSB = TWO_N29;
00101 const std::vector<std::pair<int32_t, int32_t>> C_IS_4_BIT({{39, 16}});
00102 constexpr double C_IS_4_LSB = TWO_N29;
00103 const std::vector<std::pair<int32_t, int32_t>> T0C_4_BIT({{55, 14}}); //
00104 constexpr int32_t T0C_4_LSB = 60;
00105 const std::vector<std::pair<int32_t, int32_t>> AF0_4_BIT({{69, 31}}); //
00106 constexpr double AF0_4_LSB = TWO_N34;
00107 const std::vector<std::pair<int32_t, int32_t>> AF1_4_BIT({{100, 21}}); //
00108 constexpr double AF1_4_LSB = TWO_N46;
00109 const std::vector<std::pair<int32_t, int32_t>> AF2_4_BIT({{121, 6}});
00110 constexpr double AF2_4_LSB = TWO_N59;
00111 const std::vector<std::pair<int32_t, int32_t>> SPARE_4_BIT({{127, 2}});
00112 // last two bits are reserved
00113
00114 /* Word type 5: Ionospheric correction, BGD, signal health and data validity status and GST */
00115 /* Ionospheric correction */
00116 /* Az */
00117 const std::vector<std::pair<int32_t, int32_t>> AI0_5_BIT({{7, 11}}); //
00118 constexpr double AI0_5_LSB = TWO_N2;
00119 const std::vector<std::pair<int32_t, int32_t>> AI1_5_BIT({{18, 11}}); //
00120 constexpr double AI1_5_LSB = TWO_N8;
00121 const std::vector<std::pair<int32_t, int32_t>> AI2_5_BIT({{29, 14}}); //
00122 constexpr double AI2_5_LSB = TWO_N15;
00123 /* Ionospheric disturbance flag */
00124 const std::vector<std::pair<int32_t, int32_t>> REGION1_5_BIT({{43, 1}}); //
00125 const std::vector<std::pair<int32_t, int32_t>> REGION2_5_BIT({{44, 1}}); //
00126 const std::vector<std::pair<int32_t, int32_t>> REGION3_5_BIT({{45, 1}}); //
00127 const std::vector<std::pair<int32_t, int32_t>> REGION4_5_BIT({{46, 1}}); //
00128 const std::vector<std::pair<int32_t, int32_t>> REGION5_5_BIT({{47, 1}}); //
00129 const std::vector<std::pair<int32_t, int32_t>> BGD_E1_E5A_5_BIT({{48, 10}}); //
00130 constexpr double BGD_E1_E5A_5_LSB = TWO_N32;
00131 const std::vector<std::pair<int32_t, int32_t>> BGD_E1_E5B_5_BIT({{58, 10}}); //
00132 constexpr double BGD_E1_E5B_5_LSB = TWO_N32;
00133 const std::vector<std::pair<int32_t, int32_t>> E5B_HS_5_BIT({{68, 2}}); //
00134 const std::vector<std::pair<int32_t, int32_t>> E1_B_HS_5_BIT({{70, 2}}); //
00135 const std::vector<std::pair<int32_t, int32_t>> E5B_DVS_5_BIT({{72, 1}}); //
00136 const std::vector<std::pair<int32_t, int32_t>> E1_B_DVS_5_BIT({{73, 1}}); //
00137 /* GST */
00138 const std::vector<std::pair<int32_t, int32_t>> WN_5_BIT({{74, 12}});
00139 const std::vector<std::pair<int32_t, int32_t>> TOW_5_BIT({{86, 20}});
00140 const std::vector<std::pair<int32_t, int32_t>> SPARE_5_BIT({{106, 23}});
00141
00142
00143 /* Page 6 */
00144 const std::vector<std::pair<int32_t, int32_t>> A0_6_BIT({{7, 32}});
00145 constexpr double A0_6_LSB = TWO_N30;
00146 const std::vector<std::pair<int32_t, int32_t>> A1_6_BIT({{39, 24}});
00147 constexpr double A1_6_LSB = TWO_N50;
00148 const std::vector<std::pair<int32_t, int32_t>> DELTA_T_LS_6_BIT({{63, 8}});
00149 const std::vector<std::pair<int32_t, int32_t>> T0T_6_BIT({{71, 8}});
00150 constexpr int32_t T0T_6_LSB = 3600;
00151 const std::vector<std::pair<int32_t, int32_t>> W_NOT_6_BIT({{79, 8}});
00152 const std::vector<std::pair<int32_t, int32_t>> WN_LSF_6_BIT({{87, 8}});
00153 const std::vector<std::pair<int32_t, int32_t>> DN_6_BIT({{95, 3}});
00154 const std::vector<std::pair<int32_t, int32_t>> DELTA_T_LSF_6_BIT({{98, 8}});
00155 const std::vector<std::pair<int32_t, int32_t>> TOW_6_BIT({{106, 20}});
00156
00157
00158 /* Page 7 */
00159 const std::vector<std::pair<int32_t, int32_t>> IOD_A_7_BIT({{7, 4}});
00160 const std::vector<std::pair<int32_t, int32_t>> WN_A_7_BIT({{11, 2}});
00161 const std::vector<std::pair<int32_t, int32_t>> T0A_7_BIT({{13, 10}});
00162 constexpr int32_t T0A_7_LSB = 600;
00163 const std::vector<std::pair<int32_t, int32_t>> SVI_D1_7_BIT({{23, 6}});
00164 const std::vector<std::pair<int32_t, int32_t>> DELTA_A_7_BIT({{29, 13}});
00165 constexpr double DELTA_A_7_LSB = TWO_N9;
00166 const std::vector<std::pair<int32_t, int32_t>> E_7_BIT({{42, 11}});
00167 constexpr double E_7_LSB = TWO_N16;

```

```

00168 const std::vector<std::pair<int32_t, int32_t>> OMEGA_7_BIT({{53, 16}});
00169 constexpr double OMEGA_7_LSB = TWO_N15;
00170 const std::vector<std::pair<int32_t, int32_t>> DELTA_I_7_BIT({{69, 11}});
00171 constexpr double DELTA_I_7_LSB = TWO_N14;
00172 const std::vector<std::pair<int32_t, int32_t>> OMEGA0_7_BIT({{80, 16}});
00173 constexpr double OMEGA0_7_LSB = TWO_N15;
00174 const std::vector<std::pair<int32_t, int32_t>> OMEGA_DOT_7_BIT({{96, 11}});
00175 constexpr double OMEGA_DOT_7_LSB = TWO_N33;
00176 const std::vector<std::pair<int32_t, int32_t>> M0_7_BIT({{107, 16}});
00177 constexpr double M0_7_LSB = TWO_N15;
00178
00179
00180 /* Page 8 */
00181 const std::vector<std::pair<int32_t, int32_t>> IOD_A_8_BIT({{7, 4}});
00182 const std::vector<std::pair<int32_t, int32_t>> AF0_8_BIT({{11, 16}});
00183 constexpr double AF0_8_LSB = TWO_N19;
00184 const std::vector<std::pair<int32_t, int32_t>> AF1_8_BIT({{27, 13}});
00185 constexpr double AF1_8_LSB = TWO_N38;
00186 const std::vector<std::pair<int32_t, int32_t>> E5B_HS_8_BIT({{40, 2}});
00187 const std::vector<std::pair<int32_t, int32_t>> E1_B_HS_8_BIT({{42, 2}});
00188 const std::vector<std::pair<int32_t, int32_t>> SVI_D2_8_BIT({{44, 6}});
00189 const std::vector<std::pair<int32_t, int32_t>> DELTA_A_8_BIT({{50, 13}});
00190 constexpr double DELTA_A_8_LSB = TWO_N9;
00191 const std::vector<std::pair<int32_t, int32_t>> E_8_BIT({{63, 11}});
00192 constexpr double E_8_LSB = TWO_N16;
00193 const std::vector<std::pair<int32_t, int32_t>> OMEGA_8_BIT({{74, 16}});
00194 constexpr double OMEGA_8_LSB = TWO_N15;
00195 const std::vector<std::pair<int32_t, int32_t>> DELTA_I_8_BIT({{90, 11}});
00196 constexpr double DELTA_I_8_LSB = TWO_N14;
00197 const std::vector<std::pair<int32_t, int32_t>> OMEGA0_8_BIT({{101, 16}});
00198 constexpr double OMEGA0_8_LSB = TWO_N15;
00199 const std::vector<std::pair<int32_t, int32_t>> OMEGA_DOT_8_BIT({{117, 11}});
00200 constexpr double OMEGA_DOT_8_LSB = TWO_N33;
00201
00202
00203 /* Page 9 */
00204 const std::vector<std::pair<int32_t, int32_t>> IOD_A_9_BIT({{7, 4}});
00205 const std::vector<std::pair<int32_t, int32_t>> WN_A_9_BIT({{11, 2}});
00206 const std::vector<std::pair<int32_t, int32_t>> T0A_9_BIT({{13, 10}});
00207 constexpr int32_t T0A_9_LSB = 600;
00208 const std::vector<std::pair<int32_t, int32_t>> M0_9_BIT({{23, 16}});
00209 constexpr double M0_9_LSB = TWO_N15;
00210 const std::vector<std::pair<int32_t, int32_t>> AF0_9_BIT({{39, 16}});
00211 constexpr double AF0_9_LSB = TWO_N19;
00212 const std::vector<std::pair<int32_t, int32_t>> AF1_9_BIT({{55, 13}});
00213 constexpr double AF1_9_LSB = TWO_N38;
00214 const std::vector<std::pair<int32_t, int32_t>> E5B_HS_9_BIT({{68, 2}});
00215 const std::vector<std::pair<int32_t, int32_t>> E1_B_HS_9_BIT({{70, 2}});
00216 const std::vector<std::pair<int32_t, int32_t>> SVI_D3_9_BIT({{72, 6}});
00217 const std::vector<std::pair<int32_t, int32_t>> DELTA_A_9_BIT({{78, 13}});
00218 constexpr double DELTA_A_9_LSB = TWO_N9;
00219 const std::vector<std::pair<int32_t, int32_t>> E_9_BIT({{91, 11}});
00220 constexpr double E_9_LSB = TWO_N16;
00221 const std::vector<std::pair<int32_t, int32_t>> OMEGA_9_BIT({{102, 16}});
00222 constexpr double OMEGA_9_LSB = TWO_N15;
00223 const std::vector<std::pair<int32_t, int32_t>> DELTA_I_9_BIT({{118, 11}});
00224 constexpr double DELTA_I_9_LSB = TWO_N14;
00225
00226
00227 /* Page 10 */
00228 const std::vector<std::pair<int32_t, int32_t>> IOD_A_10_BIT({{7, 4}});
00229 const std::vector<std::pair<int32_t, int32_t>> OMEGA0_10_BIT({{11, 16}});
00230 constexpr double OMEGA0_10_LSB = TWO_N15;
00231 const std::vector<std::pair<int32_t, int32_t>> OMEGA_DOT_10_BIT({{27, 11}});
00232 constexpr double OMEGA_DOT_10_LSB = TWO_N33;
00233 const std::vector<std::pair<int32_t, int32_t>> M0_10_BIT({{38, 16}});
00234 constexpr double M0_10_LSB = TWO_N15;
00235 const std::vector<std::pair<int32_t, int32_t>> AF0_10_BIT({{54, 16}});
00236 constexpr double AF0_10_LSB = TWO_N19;
00237 const std::vector<std::pair<int32_t, int32_t>> AF1_10_BIT({{70, 13}});
00238 constexpr double AF1_10_LSB = TWO_N38;
00239 const std::vector<std::pair<int32_t, int32_t>> E5B_HS_10_BIT({{83, 2}});
00240 const std::vector<std::pair<int32_t, int32_t>> E1_B_HS_10_BIT({{85, 2}});
00241 const std::vector<std::pair<int32_t, int32_t>> A_0_G_10_BIT({{87, 16}});
00242 constexpr double A_0G_10_LSB = TWO_N35;
00243 const std::vector<std::pair<int32_t, int32_t>> A_1_G_10_BIT({{103, 12}});
00244 constexpr double A_1G_10_LSB = TWO_N51;
00245 const std::vector<std::pair<int32_t, int32_t>> T_0_G_10_BIT({{115, 8}});
00246 constexpr int32_t T_0_G_10_LSB = 3600;
00247 const std::vector<std::pair<int32_t, int32_t>> WN_0_G_10_BIT({{123, 6}});
00248
00249 /* Page 16 */
00250 constexpr double CED_DeltaAred_LSB = TWO_P8;
00251 const std::vector<std::pair<int32_t, int32_t>> CED_DeltaAred_BIT({{7, 5}});
00252 constexpr double CED_exred_LSB = TWO_N22;
00253 const std::vector<std::pair<int32_t, int32_t>> CED_exred_BIT({{12, 13}});
00254 constexpr double CED_eyred_LSB = TWO_N22;

```

```

00255 const std::vector<std::pair<int32_t, int32_t>> CED_eyred_BIT({{25, 13}});
00256 constexpr double CED_DeltaI0red_LSB = TWO_N22;
00257 const std::vector<std::pair<int32_t, int32_t>> CED_DeltaI0red_BIT({{38, 17}});
00258 constexpr double CED_Omega0red_LSB = TWO_N22;
00259 const std::vector<std::pair<int32_t, int32_t>> CED_Omega0red_BIT({{55, 23}});
00260 constexpr double CED_lambda0red_LSB = TWO_N22;
00261 const std::vector<std::pair<int32_t, int32_t>> CED_lambda0red_BIT({{78, 23}});
00262 constexpr double CED_af0red_LSB = TWO_N26;
00263 const std::vector<std::pair<int32_t, int32_t>> CED_af0red_BIT({{101, 22}});
00264 constexpr double CED_aflred_LSB = TWO_N35;
00265 const std::vector<std::pair<int32_t, int32_t>> CED_aflred_BIT({{123, 6}});
00266
00267 /* Pages 17, 18, 19, 20 */
00268 const std::vector<std::pair<int32_t, int32_t>> RS_IODNAV_LSBS({{15, 2}});
00269 constexpr size_t INAV_RS_SUBVECTOR_LENGTH = 15;
00270 constexpr size_t INAV_RS_PARITY_VECTOR_LENGTH = 60;
00271 constexpr size_t INAV_RS_INFO_VECTOR_LENGTH = 58;
00272 constexpr size_t INAV_RS_BUFFER_LENGTH = 118;
00273 constexpr int32_t BITS_IN_OCTET = 8;
00274 constexpr int32_t FIRST_RS_BIT = 7;
00275 constexpr int32_t FIRST_RS_BIT_AFTER_IODNAV = 17;
00276
00277 /* Page 22 */
00278 const std::vector<std::pair<int32_t, int32_t>> ISM_CONSTELLATION_ID_BIT({{7, 3}});
00279 const std::vector<std::pair<int32_t, int32_t>> ISM_SERVICE_LEVEL_ID_BIT({{10, 3}});
00280 const std::vector<std::pair<int32_t, int32_t>> ISM_WN_BIT({{13, 12}});
00281 const std::vector<std::pair<int32_t, int32_t>> ISM_TO_BIT({{25, 9}});
00282 const std::vector<std::pair<int32_t, int32_t>> ISM_MASK_MSB_BIT({{34, 1}});
00283 const std::vector<std::pair<int32_t, int32_t>> ISM_MASK_BIT({{35, 32}});
00284 const std::vector<std::pair<int32_t, int32_t>> ISM_PCONST_BIT({{67, 4}});
00285 const std::vector<std::pair<int32_t, int32_t>> ISM_PSAT_BIT({{71, 4}});
00286 const std::vector<std::pair<int32_t, int32_t>> ISM_URA_BIT({{75, 4}});
00287 const std::vector<std::pair<int32_t, int32_t>> ISM_URE_BIT({{79, 4}});
00288 const std::vector<std::pair<int32_t, int32_t>> ISM_BNOM_BIT({{83, 4}});
00289 const std::vector<std::pair<int32_t, int32_t>> ISM_TVALIDITY_BIT({{87, 4}});
00290 const std::vector<std::pair<int32_t, int32_t>> ISM_CRC_BIT({{97, 32}});
00291 constexpr int32_t GALILEO_ISM_CRC_DATA_BITS = 96;
00292 constexpr int32_t GALILEO_ISM_CRC_DATA_BYTES = 12;
00293
00294 /* Page 0 */
00295 const std::vector<std::pair<int32_t, int32_t>> TIME_0_BIT({{7, 2}});
00296 const std::vector<std::pair<int32_t, int32_t>> WN_0_BIT({{97, 12}});
00297 const std::vector<std::pair<int32_t, int32_t>> TOW_0_BIT({{109, 20}});
00298
00299 /* Secondary Synchronization Patterns */
00300 constexpr char GALILEO_INAV_PLAIN_SSP1[9] = "00000100";
00301 constexpr char GALILEO_INAV_PLAIN_SSP2[9] = "00101011";
00302 constexpr char GALILEO_INAV_PLAIN_SSP3[9] = "00101111";
00303 constexpr char GALILEO_INAV_ENCODED_SSP1[17] = "1110100100100101";
00304 constexpr char GALILEO_INAV_ENCODED_SSP2[17] = "0110110001001110";
00305 constexpr char GALILEO_INAV_ENCODED_SSP3[17] = "1101000000111110";
00306
00307 /** \} */
00308 /** \} */
00309 #endif // GNSS_SDR_GALILEO_INAV_H

```

13.757 galileo_inav_message.h File Reference

Implementation of a Galileo I/NAV Data message as described in Galileo OS SIS ICD Issue 2.0 (Jan. 2021)

```

#include "Galileo_INAV.h"
#include "galileo_almanac_helper.h"
#include "galileo_ephemeris.h"
#include "galileo_iono.h"
#include "galileo_ism.h"
#include "galileo_utc_model.h"
#include "gnss_sdr_make_unique.h"
#include <array>
#include <bitset>
#include <cstdint>
#include <memory>
#include <string>
#include <utility>
#include <vector>

```

Classes

- class [OSNMA_msg](#)
This class fills the [OSNMA_msg](#) structure with the data received from the telemetry blocks.
- class [Galileo_Inav_Message](#)
This class handles the Galileo I/NAV Data message, as described in the Galileo Open Service Signal in Space Interface Control Document (OS SIS ICD), Issue 2.0 (Jan. 2021). See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf.

13.757.1 Detailed Description

Implementation of a Galileo I/NAV Data message as described in Galileo OS SIS ICD Issue 2.0 (Jan. 2021)

Author

Mara Branzanti 2013. mara.branzanti(at)gmail.com

Javier Arribas, 2013. jarribas(at)cttc.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.
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Definition in file [galileo_inav_message.h](#).

13.758 galileo_inav_message.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file galileo_inav_message.h
00003  * \brief Implementation of a Galileo I/NAV Data message
00004  *         as described in Galileo OS SIS ICD Issue 2.0 (Jan. 2021)
00005  * \author Mara Branzanti 2013. mara.branzanti(at)gmail.com
00006  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GALILEO_INAV_MESSAGE_H
00020 #define GNSS_SDR_GALILEO_INAV_MESSAGE_H
00021
00022 #include "Galileo_INAV.h"
00023 #include "galileo_almanac_helper.h"
00024 #include "galileo_ephemeris.h"
00025 #include "galileo_iono.h"
00026 #include "galileo_ism.h"
00027 #include "galileo_utc_model.h"
00028 #include "gnss_sdr_make_unique.h" // for std::unique_ptr in C++11
00029 #include <array>
00030 #include <bitset>
00031 #include <stdint>
00032 #include <memory>
00033 #include <string>
00034 #include <utility>
00035 #include <vector>
00036
00037 class ReedSolomon; // Forward declaration of the ReedSolomon class
00038
00039 /** \addtogroup Core
00040  *  \{ */
00041 /** \addtogroup System_Parameters
00042  *  \{ */
00043 /*!
00044  * \brief This class fills the OSNMA_msg structure with the data received from the telemetry blocks.
00045  */
00046 class OSNMA_msg
00047 {
00048 public:
00049     OSNMA_msg() = default;
00050     std::array<uint32_t, 15> mack{};
00051     std::array<uint8_t, 15> hkroot{};
```

```
00052     uint32_t PRN{};          // PRN_a authentication data PRN
00053     uint32_t WN_sf0{};       // Week number at the start of OSNMA subframe
00054     uint32_t TOW_sf0{};      // TOW at the start of OSNMA subframe
00055 };
00056
00057 /*!
00058  * \brief This class handles the Galileo I/NAV Data message, as described in the
00059  * Galileo Open Service Signal in Space Interface Control Document (OS SIS ICD), Issue 2.0 (Jan.
00060  * 2021).
00061  * See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo\_OS\_SIS\_ICD\_v2.0.pdf
00062  */
00062 class Galileo_Inav_Message
00063 {
00064 public:
00065     Galileo_Inav_Message();
00066     ~Galileo_Inav_Message();
00067
00068     /*
00069     * \brief Takes in input a page (Odd or Even) of 120 bit, split it according ICD 4.3.2.3 and join
00070     Data_k with Data_j
00071     */
00072     void split_page(std::string page_string, int32_t flag_even_word);
00073
00074     /*
00075     * \brief Returns true if new Ephemeris has arrived. The flag is set to false when the function is
00076     executed
00077     */
00077     bool have_new_ephemeris();
00078
00079     /*
00080     * \brief Returns true if new Iono model has arrived. The flag is set to false when the function
00081     is executed
00082     */
00082     bool have_new_iono_and_GST();
00083
00084     /*
00085     * \brief Returns true if new UTC model has arrived. The flag is set to false when the function is
00086     executed
00087     */
00087     bool have_new_utc_model();
00088
00089     /*
00090     * \brief Returns true if new UTC model has arrived. The flag is set to false when the function is
00091     executed
00092     */
00092     bool have_new_almanac();
00093
00094     /*
00095     * \brief Returns true if new Reduced CED parameters have arrived. The flag is set to false when
00096     the function is executed
00097     */
00097     bool have_new_reduced_ced();
00098
00099     /*
00100     * \brief Returns true if new ISM data have arrived. The flag is set to false when the function is
00101     executed
00102     */
00102     bool have_new_ism();
00103
00104     /*
00105     * \brief Returns true if new NMA data have arrived. The flag is set to false when the function is
00106     executed
00107     */
00107     bool have_new_nma();
00108
00109     /*
00110     * \brief Returns a Galileo_Ephemeris object filled with the latest navigation data received
00111     */
00111     Galileo_Ephemeris get_ephemeris() const;
00112
00113     /*
00114     * \brief Returns a Galileo_Iono object filled with the latest navigation data received
00115     */
00115     Galileo_Iono get_iono() const;
00116
00117     /*
00118     * \brief Returns a Galileo_Utc_Model object filled with the latest navigation data received
00119     */
00119     Galileo_Utc_Model get_utc_model() const;
00120
00121     /*
00122     * \brief Returns a Galileo_Almanac_Helper object filled with the latest navigation data received
00123     */
00123     Galileo_Almanac_Helper get_almanac() const;
00124
00125     /*
00126     */
00126
00127
00128
00129     /*
```

```

00130      * \brief Returns a Galileo_Ephemeris object filled with the latest reduced CED received
00131      */
00132      Galileo_Ephemeris get_reduced_ced() const;
00133
00134      /*
00135      * \brief Returns a Galileo_ISMs object filled with the latest ISM data received
00136      */
00137      Galileo_ISM get_galileo_ism() const;
00138
00139      /*
00140      * \brief Returns an OSNMA_msg object filled with the latest NMA message received. Resets msg
00141      buffer.
00142      */
00143      OSNMA_msg get_osnma_msg();
00144
00145      /*
00146      * @brief Retrieves the OSNMA ADKD 4 NAV bits. Resets the string.
00147      */
00148      std::string get_osnma_adkd_4_nav_bits();
00149
00150      /*
00151      * @brief Resets the OSNMA ADKD 4 NAV bits.
00152      */
00153      void reset_osnma_nav_bits_adkd4();
00154
00155      /*
00156      * @brief Retrieves the OSNMA ADKD 0/12 NAV bits. Resets the string.
00157      */
00158      std::string get_osnma_adkd_0_12_nav_bits();
00159
00160      /*
00161      * @brief Resets the OSNMA ADKD 0/12 NAV bits.
00162      */
00163      void reset_osnma_nav_bits_adkd0_12();
00164
00165      inline bool get_flag_CRC_test() const
00166      {
00167          return flag_CRC_test;
00168      }
00169
00170      inline bool get_flag_TOW_set() const
00171      {
00172          return flag_TOW_set;
00173      }
00174
00175      inline void set_flag_TOW_set(bool flag_tow)
00176      {
00177          flag_TOW_set = flag_tow;
00178      }
00179
00180      inline int32_t get_Galileo_week() const
00181      {
00182          return WN_0;
00183      }
00184
00185      inline int32_t get_TOW5() const
00186      {
00187          return TOW_5;
00188      }
00189
00190      inline int32_t get_TOW6() const
00191      {
00192          return TOW_6;
00193      }
00194
00195      inline bool is_TOW5_set() const
00196      {
00197          return flag_TOW_5;
00198      }
00199
00200      inline void set_TOW5_flag(bool flag_tow5)
00201      {
00202          flag_TOW_5 = flag_tow5;
00203      }
00204
00205      inline bool is_TOW6_set() const
00206      {
00207          return flag_TOW_6;
00208      }
00209
00210      inline void set_TOW6_flag(bool flag_tow6)
00211      {
00212          flag_TOW_6 = flag_tow6;
00213      }
00214
00215      inline int32_t get_TOW0() const
00216      {

```

```

00216         return TOW_0;
00217     }
00218
00219     inline bool is_TOW0_set() const
00220     {
00221         return flag_TOW_0;
00222     }
00223
00224     inline void set_TOW0_flag(bool flag_tow0)
00225     {
00226         flag_TOW_0 = flag_tow0;
00227     }
00228
00229     inline bool get_flag_GGTO() const
00230     {
00231         return (flag_GGTO_1 == true and flag_GGTO_2 == true and flag_GGTO_3 == true and flag_GGTO_4 ==
00232 true);
00233     }
00234
00235     inline double get_A0G() const
00236     {
00237         return A_0G_10;
00238     }
00239
00240     inline double get_A1G() const
00241     {
00242         return A_1G_10;
00243     }
00244
00245     inline double get_t0G() const
00246     {
00247         return t_0G_10;
00248     }
00249
00250     inline double get_WN0G() const
00251     {
00252         return WN_0G_10;
00253     }
00254
00255     /*
00256     * \brief Initialize PRN field so we do not need to wait for page 4.
00257     */
00258     inline void init_PRN(uint32_t prn)
00259     {
00260         SV_ID_PRN_4 = prn;
00261         nma_msg.PRN = prn;
00262         nma_msg.mack = std::array<uint32_t, 15>{};
00263         nma_msg.hkroot = std::array<uint8_t, 15>{};
00264         page_position_in_inav_subframe = 255;
00265         nma_position_filled = std::array<int8_t, 15>{};
00266     }
00267
00268     /*
00269     * \brief Enable Reed-Solomon in Galileo E1B
00270     */
00271     inline void enable_reed_solomon()
00272     {
00273         enable_rs = true;
00274     }
00275 private:
00276     bool CRC_test(const std::bitset<GALILEO_DATA_FRAME_BITS>& bits, uint32_t checksum) const;
00277     bool read_navigation_bool(const std::bitset<GALILEO_DATA_JK_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00278     uint64_t read_navigation_unsigned(const std::bitset<GALILEO_DATA_JK_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00279     uint64_t read_page_type_unsigned(const std::bitset<GALILEO_PAGE_TYPE_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00280     int64_t read_navigation_signed(const std::bitset<GALILEO_DATA_JK_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00281     uint8_t read_octet_unsigned(const std::bitset<GALILEO_DATA_JK_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00282     void read_page_1(const std::bitset<GALILEO_DATA_JK_BITS>& data_bits);
00283     void read_page_2(const std::bitset<GALILEO_DATA_JK_BITS>& data_bits);
00284     void read_page_3(const std::bitset<GALILEO_DATA_JK_BITS>& data_bits);
00285     void read_page_4(const std::bitset<GALILEO_DATA_JK_BITS>& data_bits);
00286     std::bitset<GALILEO_DATA_JK_BITS> regenerate_page_1(const std::vector<uint8_t>& decoded) const;
00287     std::bitset<GALILEO_DATA_JK_BITS> regenerate_page_2(const std::vector<uint8_t>& decoded) const;
00288     std::bitset<GALILEO_DATA_JK_BITS> regenerate_page_3(const std::vector<uint8_t>& decoded) const;
00289     std::bitset<GALILEO_DATA_JK_BITS> regenerate_page_4(const std::vector<uint8_t>& decoded) const;
00290
00291     Galileo_ISM gal_ism{};
00292     std::string page_Even{};
00293
00294     std::vector<uint8_t> rs_buffer; // Reed-Solomon buffer
00295     std::unique_ptr<ReedSolomon> rs; // The Reed-Solomon decoder
00296     std::vector<int> inav_rs_pages; // Pages 1,2,3,4,17,18,19,20. Holds 1 if the page has arrived, 0

```



```

        otherwise.
00297
00298     int32_t page_jk_decoder(const char* data_jk);
00299     int32_t IOD_ephemeris{};
00300
00301     // Word type 1: Ephemeris (1/4)
00302     int32_t IOD_nav_1{}; // IOD_nav page 1
00303     int32_t t0e_1{};    // Ephemeris reference time [s]
00304     double M0_1{};      // Mean anomaly at reference time [rad]
00305     double e_1{};       // Eccentricity
00306     double A_1{};       // Square root of the semi-major axis [meters^1/2]
00307
00308     // Word type 2: Ephemeris (2/4)
00309     int32_t IOD_nav_2{}; // IOD_nav page 2
00310     double OMEGA_0_2{};  // Longitude of ascending node of orbital plane at weekly epoch [rad]
00311     double i_0_2{};      // Inclination angle at reference time [rad]
00312     double omega_2{};    // Argument of perigee [rad]
00313     double iDot_2{};     // Rate of inclination angle [rad/sec]
00314
00315     // Word type 3: Ephemeris (3/4) and SISA
00316     int32_t IOD_nav_3{};
00317     int32_t SISA_3{};
00318     double OMEGA_dot_3{}; // Rate of right ascension [rad/sec]
00319     double delta_n_3{};   // Mean motion difference from computed value [rad/sec]
00320     double C_uc_3{};      // Amplitude of the cosine harmonic correction term to the argument of
latitude [radians]
00321     double C_us_3{};      // Amplitude of the sine harmonic correction term to the argument of
latitude [radians]
00322     double C_rc_3{};      // Amplitude of the cosine harmonic correction term to the orbit radius
[meters]
00323     double C_rs_3{};      // Amplitude of the sine harmonic correction term to the orbit radius
[meters]
00324
00325     // Word type 4: Ephemeris (4/4) and Clock correction parameters*/
00326     int32_t IOD_nav_4{}; //
00327     int32_t SV_ID_PRN_4{}; //
00328     double C_ic_4{};      // Amplitude of the cosine harmonic correction term to the angle of
inclination [radians]
00329     double C_is_4{};      // Amplitude of the sine harmonic correction term to the angle of
inclination [radians]
00330
00331     // Clock correction parameters
00332     int32_t t0c_4{};      // Clock correction data reference Time of Week [sec]
00333     double af0_4{};       // SV clock bias correction coefficient [s]
00334     double af1_4{};       // SV clock drift correction coefficient [s/s]
00335     double af2_4{};       // clock drift rate correction coefficient [s/s^2]
00336     double spare_4{};
00337
00338     // Word type 5: Ionospheric correction, BGD, signal health and data validity status and GST*/
00339     // Ionospheric correction
00340     double ai0_5{};        // Effective Ionisation Level 1st order parameter [sfu]
00341     double ai1_5{};        // Effective Ionisation Level 2st order parameter [sfu/degree]
00342     double ai2_5{};        // Effective Ionisation Level 3st order parameter [sfu/degree]
00343     double BGD_E1E5a_5{};  // E1-E5a Broadcast Group Delay [s]
00344     double BGD_E1E5b_5{};  // E1-E5b Broadcast Group Delay [s]
00345     int32_t E5b_HS_5{};    // E5b Signal Health Status
00346     int32_t E1B_HS_5{};    // E1B Signal Health Status
00347
00348     // Ionospheric disturbance flag
00349     bool Region1_flag_5{}; // Ionospheric Disturbance Flag for region 1
00350     bool Region2_flag_5{}; // Ionospheric Disturbance Flag for region 2
00351     bool Region3_flag_5{}; // Ionospheric Disturbance Flag for region 3
00352     bool Region4_flag_5{}; // Ionospheric Disturbance Flag for region 4
00353     bool Region5_flag_5{}; // Ionospheric Disturbance Flag for region 5
00354     bool E5b_DVS_5{};      // E5b Data Validity Status
00355     bool E1B_DVS_5{};      // E1B Data Validity Status
00356
00357     // GST
00358     int32_t WN_5{};
00359     int32_t TOW_5{};
00360     double spare_5{};
00361
00362     // Word type 6: GST-UTC conversion parameters
00363     double A0_6{};
00364     double A1_6{};
00365     int32_t Delta_tLS_6{};
00366     int32_t t0t_6{};
00367     int32_t WN_LSF_6{};
00368     int32_t DN_6{};
00369     int32_t Delta_tLSF_6{};
00370     int32_t TOW_6{};
00371
00372
00373     // Word type 7: Almanac for SVID1 (1/2), almanac reference time and almanac reference week number
00374     int32_t IOD_a_7{};
00375     int32_t WN_a_7{};
00376     int32_t t0a_7{};

```



```
00377     int32_t SVID1_7{};
00378     double DELTA_A_7{};
00379     double e_7{};
00380     double omega_7{};
00381     double delta_i_7{};
00382     double Omega0_7{};
00383     double Omega_dot_7{};
00384     double M0_7{};
00385
00386     // Word type 8: Almanac for SVID1 (2/2) and SVID2 (1/2)
00387     int32_t IOD_a_8{};
00388     int32_t E5b_HS_8{};
00389     int32_t E1B_HS_8{};
00390     int32_t SVID2_8{};
00391     double af0_8{};
00392     double af1_8{};
00393     double DELTA_A_8{};
00394     double e_8{};
00395     double omega_8{};
00396     double delta_i_8{};
00397     double Omega0_8{};
00398     double Omega_dot_8{};
00399
00400     // Word type 9: Almanac for SVID2 (2/2) and SVID3 (1/2)
00401     int32_t IOD_a_9{};
00402     int32_t WN_a_9{};
00403     int32_t t0a_9{};
00404     double M0_9{};
00405     double af0_9{};
00406     double af1_9{};
00407     int32_t E5b_HS_9{};
00408     int32_t E1B_HS_9{};
00409     int32_t SVID3_9{};
00410     double DELTA_A_9{};
00411     double e_9{};
00412     double omega_9{};
00413     double delta_i_9{};
00414
00415     // Word type 10: Almanac for SVID3 (2/2) and GST-GPS conversion parameters
00416     int32_t IOD_a_10{};
00417     double Omega0_10{};
00418     double Omega_dot_10{};
00419     double M0_10{};
00420     double af0_10{};
00421     double af1_10{};
00422     int32_t E5b_HS_10{};
00423     int32_t E1B_HS_10{};
00424
00425     // GST-GPS conversion
00426     double A_0G_10{}; // Constant term of the offset Delta t systems
00427     double A_1G_10{}; // Rate of change of the offset Delta t systems
00428     int32_t t_0G_10{}; // Reference time for Galileo/GPS Time Offset (GGTO) data
00429     int32_t WN_0G_10{}; // Week Number of Galileo/GPS Time Offset (GGTO) reference
00430
00431     // Word type 0: I/NAV Spare Word
00432     int32_t Time_0{};
00433     int32_t WN_0{};
00434     int32_t TOW_0{};
00435
00436     // Word type 16: Reduced Clock and Ephemeris Data (CED) parameters
00437     double ced_DeltaAred{};
00438     double ced_exred{};
00439     double ced_eyred{};
00440     double ced_DeltaI0red{};
00441     double ced_Omega0red{};
00442     double ced_lambda0red{};
00443     double ced_af0red{};
00444     double ced_af1red{};
00445
00446     double Galileo_satClkDrift{};
00447
00448     int32_t current_IODnav{};
00449
00450     // OSNMA
00451     uint32_t mack_sis{};
00452     uint8_t hkroot_sis{};
00453     uint8_t page_position_in_inav_subframe{255};
00454     std::array<int8_t, 15> nma_position_filled{};
00455     OSNMA_msg nma_msg{};
00456     std::string nav_bits_adkd_4{};
00457     std::string nav_bits_word_6{};
00458     std::string nav_bits_word_10{};
00459     std::string nav_bits_adkd_0_12{};
00460     std::string nav_bits_word_1{};
00461     std::string nav_bits_word_2{};
00462     std::string nav_bits_word_3{};
00463     std::string nav_bits_word_4{};
```

```

00464     std::string nav_bits_word_5{};
00465
00466     uint8_t IODnav_LSB17{};
00467     uint8_t IODnav_LSB18{};
00468     uint8_t IODnav_LSB19{};
00469     uint8_t IODnav_LSB20{};
00470
00471     uint8_t ism_constellation_id{};
00472     uint8_t ism_service_level_id{};
00473
00474     bool flag_CRC_test{};
00475     bool flag_all_ephemeris{}; // Flag indicating that all words containing ephemeris have been
received
00476     bool flag_ephemeris_1{}; // Flag indicating that ephemeris 1/4 (word 1) have been received
00477     bool flag_ephemeris_2{}; // Flag indicating that ephemeris 2/4 (word 2) have been received
00478     bool flag_ephemeris_3{}; // Flag indicating that ephemeris 3/4 (word 3) have been received
00479     bool flag_ephemeris_4{}; // Flag indicating that ephemeris 4/4 (word 4) have been received
00480
00481     bool flag_iono_and_GST{}; // Flag indicating that ionospheric and GST parameters (word 5) have
been received
00482     bool flag_TOW_5{};
00483     bool flag_TOW_6{};
00484     bool flag_TOW_0{};
00485     bool flag_TOW_set{}; // it is true when page 5 or page 6 arrives
00486     bool flag_utc_model{}; // Flag indicating that utc model parameters (word 6) have been received
00487
00488     bool flag_all_almanac{}; // Flag indicating that all Almanac data have been received
00489     bool flag_almanac_1{}; // Flag indicating that almanac 1/4 (word 7) have been received
00490     bool flag_almanac_2{}; // Flag indicating that almanac 2/4 (word 8) have been received
00491     bool flag_almanac_3{}; // Flag indicating that almanac 3/4 (word 9) have been received
00492     bool flag_almanac_4{}; // Flag indicating that almanac 4/4 (word 10) have been received
00493
00494     bool flag_GGTO_1{};
00495     bool flag_GGTO_2{};
00496     bool flag_GGTO_3{};
00497     bool flag_GGTO_4{};
00498
00499     bool flag_CED{};
00500     bool enable_rs{};
00501     bool have_ISM{};
00502 };
00503
00504
00505 /** \} */
00506 /** \} */
00507 #endif // GNSS_SDR_GALILEO_INAV_MESSAGE_H

```

13.759 galileo_iono.h File Reference

Interface of a Galileo Ionospheric Model storage.

```
#include <boost/serialization/nvp.hpp>
#include <cstdint>
```

Classes

- class [Galileo_Iono](#)

This class is a storage for the GALILEO IONOSPHERIC data as described in Galileo ICD paragraph 5.1.6.

13.759.1 Detailed Description

Interface of a Galileo Ionospheric Model storage.

Author

Javier Arribas, 2013. jarribas(at)cttc.es

Mara Branzanti 2013. mara.branzanti(at)gmail.com

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 Definition in file [galileo_iono.h](#).

13.760 galileo_iono.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_iono.h
00003  * \brief Interface of a Galileo Ionospheric Model storage
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00005  * \author Mara Branzanti 2013. mara.branzanti(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GALILEO_IONO_H
00020 #define GNSS_SDR_GALILEO_IONO_H
00021
00022 #include <boost/serialization/nvp.hpp>
00023 #include <cstdint>
00024
00025 /** \addtogroup Core
00026  * \{ */
00027 /** \addtogroup System_Parameters
00028  * \{ */
00029
00030
00031  /*!
00032  * \brief This class is a storage for the GALILEO IONOSPHERIC data as described
00033  * in Galileo ICD paragraph 5.1.6
00034  *
00035  * See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf
00036  */
00037  class Galileo_Iono
00038  {
00039  public:
00040      /*!
00041       * Default constructor
00042       */
00043      Galileo_Iono() = default;
00044
00045      // Ionospheric correction
00046      double ai0{}; //!< Effective Ionisation Level 1st order parameter [sfu]
00047      double ai1{}; //!< Effective Ionisation Level 2st order parameter [sfu/degree]
00048      double ai2{}; //!< Effective Ionisation Level 3st order parameter [sfu/degree]
00049
00050      // from page 5 (UTC) to have a timestamp
00051      int32_t tow{}; //!< UTC data reference Time of Week [s]
00052      int32_t WN{}; //!< UTC data reference Week number [week]
00053
00054      // Ionospheric disturbance flag
00055      bool Region1_flag{}; //!< Ionospheric Disturbance Flag for region 1
00056      bool Region2_flag{}; //!< Ionospheric Disturbance Flag for region 2
00057      bool Region3_flag{}; //!< Ionospheric Disturbance Flag for region 3
00058      bool Region4_flag{}; //!< Ionospheric Disturbance Flag for region 4
00059      bool Region5_flag{}; //!< Ionospheric Disturbance Flag for region 5
00060
00061      template <class Archive>
00062
00063      /*!
00064       * \brief Serialize is a boost standard method to be called by the boost XML serialization.
00065       * Here is used to save the iono data on disk file.
00066       */
00067      inline void serialize(Archive& archive, const unsigned int version)
00068      {
00069          if (version)
00070          {
00071          };
00072          archive& BOOST_SERIALIZATION_NVP(ai0);
00073          archive& BOOST_SERIALIZATION_NVP(ai1);
00074          archive& BOOST_SERIALIZATION_NVP(ai2);
00075          archive& BOOST_SERIALIZATION_NVP(tow);
00076          archive& BOOST_SERIALIZATION_NVP(WN);
00077          archive& BOOST_SERIALIZATION_NVP(Region1_flag);
00078          archive& BOOST_SERIALIZATION_NVP(Region2_flag);
00079          archive& BOOST_SERIALIZATION_NVP(Region3_flag);
00080          archive& BOOST_SERIALIZATION_NVP(Region4_flag);
00081          archive& BOOST_SERIALIZATION_NVP(Region5_flag);
00082      }
00083  };

```

```

00084
00085
00086 /** \} */
00087 /** \} */
00088 #endif // GNSS_SDR_GALILEO_IONO_H

```

13.761 galileo_ism.h File Reference

Interface of a Galileo Integrity Support Message.

```

#include "Galileo_INAV.h"
#include <boost/crc.hpp>
#include <bitset>
#include <cstdint>
#include <unordered_map>
#include <vector>

```

Classes

- class [Galileo_ISM](#)

This class is a storage for the GALILEO Integrity Support Message as described in Galileo ICD paragraph 5.2.

13.761.1 Detailed Description

Interface of a Galileo Integrity Support Message.

Author

Carles Fernandez, 2024. cfernandez(at)cttc.es

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Definition in file [galileo_ism.h](#).

13.762 galileo_ism.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_ism.h
00003  * \brief Interface of a Galileo Integrity Support Message
00004  * \author Carles Fernandez, 2024. cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2024 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GALILEO_ISM_H
00019 #define GNSS_SDR_GALILEO_ISM_H
00020
00021 #include "Galileo_INAV.h"
00022 #include <boost/crc.hpp>
00023 #include <bitset>
00024 #include <cstdint>
00025 #include <unordered_map>
00026 #include <vector>
00027
00028 /** \addtogroup Core
00029  * \{ */
00030 /** \addtogroup System_Parameters
00031  * \{ */
00032
00033
00034 /*!

```

```

00035 * \brief This class is a storage for the GALILEO Integrity Support Message as described
00036 * in Galileo ICD paragraph 5.2
00037 *
00038 * See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo\_OS\_SIS\_ICD\_v2.1.pdf
00039 */
00040 class Galileo_ISM
00041 {
00042 public:
00043     /*!
00044      * Default constructor
00045      */
00046     Galileo_ISM() = default;
00047
00048     void set_ism_constellation_id(uint8_t const_id);
00049     void set_ism_service_level_id(uint8_t sl_id);
00050     void set_ism_wn(uint16_t wn_ism);
00051     void set_ism_t0(uint16_t t0);
00052     void set_ism_mask_msb(bool mask_msb);
00053     void set_ism_mask(uint32_t mask);
00054     void set_ism_pconst(uint8_t pconst);
00055     void set_ism_psat(uint8_t psat);
00056     void set_ism_ura(uint8_t ura);
00057     void set_ism_ure(uint8_t ure);
00058     void set_ism_bnom(uint8_t bnom);
00059     void set_ism_Tvalidity(uint8_t tvalidity);
00060
00061     bool check_ism_crc(const std::bitset<GALILEO_DATA_JK_BITS>& bits);
00062
00063     double get_pconst_value() const;
00064     double get_psat_value() const;
00065     float get_ura_m() const;
00066     float get_ure_m() const;
00067     float get_bnom_m() const;
00068     uint32_t get_mask_ISM() const;
00069     uint16_t get_WN_ISM() const;
00070     uint16_t get_t0_ISM() const;
00071     uint16_t get_Tvalidity_hours() const;
00072     bool get_ism_mask_msb() const;
00073     bool ism_parameters_apply(uint32_t prn) const;
00074
00075 private:
00076     uint32_t compute_crc(const std::vector<uint8_t>& data);
00077     boost::crc_optimal<32, 0x814141AB, 0, 0, false, false> d_crc32_ism;
00078
00079     // ICD 2.1 Table 97
00080     std::unordered_map<uint8_t, double> d_ISM_PCONST_MAP = {
00081         {0, 1.0e-8},
00082         {1, 1.0e-7},
00083         {2, 1.0e-6},
00084         {3, 3.0e-6},
00085         {4, 6.0e-6},
00086         {5, 8.0e-6},
00087         {6, 1.0e-5},
00088         {7, 2.0e-5},
00089         {8, 4.0e-5},
00090         {9, 6.0e-5},
00091         {10, 8.0e-5},
00092         {11, 1.0e-4},
00093         {12, 1.25e-4},
00094         {13, 1.5e-4},
00095         {14, 1.75e-4},
00096         {15, 2.0e-4}};
00097
00098     // ICD 2.1 Table 98
00099     std::unordered_map<uint8_t, double> d_ISM_PSAT_MAP = {
00100         {0, 1.0e-7},
00101         {1, 3.0e-7},
00102         {2, 6.0e-7},
00103         {3, 1.0e-6},
00104         {4, 2.0e-6},
00105         {5, 3.0e-6},
00106         {6, 5.0e-6},
00107         {7, 7.0e-6},
00108         {8, 1.0e-5},
00109         {9, 1.2e-5},
00110         {10, 1.4e-5},
00111         {11, 1.7e-5},
00112         {12, 2.05e-5},
00113         {13, 2.4e-5},
00114         {14, 2.8e-5},
00115         {15, 3.0e-5}};
00116
00117     // ICD 2.1 Table 99
00118     std::unordered_map<uint8_t, float> d_ISM_URA_MAP = {
00119         {0, 0.75},
00120         {1, 1.0},
00121         {2, 1.5},

```

```
00122         {3, 2.0},
00123         {4, 2.25},
00124         {5, 2.50},
00125         {6, 2.75},
00126         {7, 3.0},
00127         {8, 3.25},
00128         {9, 3.50},
00129         {10, 3.75},
00130         {11, 4.0},
00131         {12, 4.50},
00132         {13, 5.0},
00133         {14, 5.50},
00134         {15, 6.0}};
00135
00136 // ICD 2.1 Table 100
00137 std::unordered_map<uint8_t, float> d_ISM_URE_MAP = {
00138     {0, 0.25},
00139     {1, 0.50},
00140     {2, 0.75},
00141     {3, 1.00},
00142     {4, 1.25},
00143     {5, 1.50},
00144     {6, 1.75},
00145     {7, 2.0},
00146     {8, 2.25},
00147     {9, 2.50},
00148     {10, 2.75},
00149     {11, 3.0},
00150     {12, 3.25},
00151     {13, 3.50},
00152     {14, 3.75},
00153     {15, 4.00}};
00154
00155 // ICD 2.1 Table 101
00156 std::unordered_map<uint8_t, float> d_ISM_BNOM_MAP = {
00157     {0, 0.0},
00158     {1, 0.10},
00159     {2, 0.20},
00160     {3, 0.30},
00161     {4, 0.40},
00162     {5, 0.50},
00163     {6, 0.60},
00164     {7, 0.75},
00165     {8, 0.85},
00166     {9, 1.0},
00167     {10, 1.20},
00168     {11, 1.40},
00169     {12, 1.60},
00170     {13, 1.80},
00171     {14, 2.0},
00172     {15, 2.4}};
00173
00174 // ICD 2.1 Table 102
00175 std::unordered_map<uint8_t, uint16_t> d_ISM_TVALIDITY_MAP = {
00176     {0, 1},
00177     {1, 2},
00178     {2, 3},
00179     {3, 4},
00180     {4, 6},
00181     {5, 8},
00182     {6, 12},
00183     {7, 18},
00184     {8, 24},
00185     {9, 36},
00186     {10, 48},
00187     {11, 72},
00188     {12, 120},
00189     {13, 168},
00190     {14, 720},
00191     {15, 1440}};
00192
00193 uint32_t d_ism_crc{};
00194 uint32_t d_ism_mask{};
00195 uint16_t d_ism_wn{};
00196 uint16_t d_ism_t0{};
00197 uint8_t d_ism_constellation_id{};
00198 uint8_t d_ism_service_level_id{};
00199 uint8_t d_ism_pconst{};
00200 uint8_t d_ism_psat{};
00201 uint8_t d_ism_ura{};
00202 uint8_t d_ism_ure{};
00203 uint8_t d_ism_bnom{};
00204 uint8_t d_ism_tvalidity{};
00205 bool d_ism_mask_msb{};
00206 };
00207
00208 /** \}
```

```
00209 /** \} */
00210 #endif // GNSS_SDR_GALILEO_ISM_H
```

13.763 Galileo_OSNMA.h File Reference

Galileo OSNMA message constants.

```
#include <cstdint>
#include <cstdint>
#include <string>
#include <unordered_map>
#include <utility>
#include <vector>
```

Classes

- class [Mack_lookup](#)

Functions

- const std::string **PEMFILE_DEFAULT** (".OSNMA_PublicKey.pem")
- const std::string **CRTFILE_DEFAULT** (".OSNMA_PublicKey_20240115100000_newPKID_1.crt")
- const std::string **MERKLEFILE_DEFAULT** (".OSNMA_MerkleTree_20240115100000_newPKID_1.xml")
- const std::string **KROOTFILE_DEFAULT** (".OSNMA_DSM_KROOT_NMAHeader.bin")

Variables

- constexpr size_t **SIZE_DSM_BLOCKS_BYTES** = 13
- const std::unordered_map< uint8_t, std::string > **OSNMA_TABLE_1**
- const std::unordered_map< uint8_t, std::string > **OSNMA_TABLE_2**
- const std::unordered_map< uint8_t, std::pair< uint16_t, uint16_t > > **OSNMA_TABLE_3**
- const std::unordered_map< uint8_t, std::string > **OSNMA_TABLE_5**
- const std::unordered_map< std::string, uint16_t > **OSNMA_TABLE_6**
- const std::unordered_map< uint8_t, std::pair< uint16_t, uint16_t > > **OSNMA_TABLE_7**
- const std::unordered_map< uint8_t, std::string > **OSNMA_TABLE_8**
- const std::unordered_map< uint8_t, uint16_t > **OSNMA_TABLE_10**
- const std::unordered_map< uint8_t, uint8_t > **OSNMA_TABLE_11**
- const std::unordered_map< std::string, uint16_t > **OSNMA_TABLE_15**
- const std::unordered_map< uint8_t, [Mack_lookup](#) > **OSNMA_TABLE_16**

13.763.1 Detailed Description

Galileo OSNMA message constants.

Author

Carles Fernandez, 2023. cfernandez(at)cttc.es

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 Definition in file [Galileo_OSNMA.h](#).

13.764 Galileo_OSNMA.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002 * \file Galileo_OSNMA.h
00003 * \brief Galileo OSNMA message constants
00004 * \author Carles Fernandez, 2023. cfernandez(at)cttc.es
00005 *
```

```

00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
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00012  * Copyright (C) 2010-2023 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018 #ifndef GNSS_SDR_GALILEO_OSNMA_H
00019 #define GNSS_SDR_GALILEO_OSNMA_H
00020
00021 #include <stddef>
00022 #include <stdint>
00023 #include <string>
00024 #include <unordered_map>
00025 #include <utility>
00026 #include <vector>
00027
00028 /** \addtogroup Core
00029  * \{ */
00030 /** \addtogroup System_Parameters
00031  * \{ */
00032
00033 constexpr size_t SIZE_DSM_BLOCKS_BYTES = 13;
00034
00035 // OSNMA User ICD, Issue 1.1, Table 1
00036 const std::unordered_map<uint8_t, std::string> OSNMA_TABLE_1 = {
00037     {0, std::string("Reserved")},
00038     {1, std::string("Test")},
00039     {2, std::string("Operational")},
00040     {3, std::string("Don't use")}; // key: nmas, value: nmas status
00041
00042 // OSNMA User ICD, Issue 1.1, Table 2
00043 const std::unordered_map<uint8_t, std::string> OSNMA_TABLE_2 = {
00044     {0, std::string("Reserved")},
00045     {1, std::string("Nominal")},
00046     {2, std::string("End of Chain (EOC)")},
00047     {3, std::string("Chain Revoked (CREV)")},
00048     {4, std::string("New Public Key (NPK)")},
00049     {5, std::string("Public Key Revoked (PKREV)")},
00050     {6, std::string("New Merkle Tree (NMT)")},
00051     {7, std::string("Alert Message (AM)"); // key: cpks, value: cpks status
00052
00053 // OSNMA User ICD for the Test Phase, Issue 1.0, Table 3
00054 const std::unordered_map<uint8_t, std::pair<uint16_t, uint16_t> OSNMA_TABLE_3 = {
00055     {0, {0, 0}},
00056     {1, {0, 0}},
00057     {2, {0, 0}},
00058     {3, {0, 0}},
00059     {4, {0, 0}},
00060     {5, {0, 0}},
00061     {6, {0, 0}},
00062     {7, {13, 1352}},
00063     {8, {14, 1456}},
00064     {9, {15, 1560}},
00065     {10, {16, 1664}},
00066     {11, {0, 0}},
00067     {12, {0, 0}},
00068     {13, {0, 0}},
00069     {14, {0, 0}},
00070     {15, {0, 0}}; // key: nb_dp, value: {num_blocks, l_dp_bits}
00071
00072 const std::unordered_map<uint8_t, std::string> OSNMA_TABLE_5 = {
00073     {0, std::string("Reserved")},
00074     {1, std::string("ECDSA P-256")},
00075     {2, std::string("Reserved")},
00076     {3, std::string("ECDSA P-521")},
00077     {4, std::string("OAM")},
00078     {5, std::string("Reserved")},
00079     {6, std::string("Reserved")},
00080     {7, std::string("Reserved")},
00081     {8, std::string("Reserved")},
00082     {9, std::string("Reserved")},
00083     {10, std::string("Reserved")},
00084     {11, std::string("Reserved")},
00085     {12, std::string("Reserved")},
00086     {13, std::string("Reserved")},
00087     {14, std::string("Reserved")},
00088     {15, std::string("Reserved")}; // key: nptk, value: message
00089
00090 const std::unordered_map<std::string, uint16_t> OSNMA_TABLE_6 = {
00091     {std::string("ECDSA P-256"), 264},

```



```

00093     {std::string("ECDSA P-521"), 536}};
00094
00095 // OSNMA User ICD, Issue 1.1, Table 7
00096 const std::unordered_map<uint8_t, std::pair<uint16_t, uint16_t> OSNMA_TABLE_7 = {
00097     {0, {0, 0}},
00098     {1, {7, 728}},
00099     {2, {8, 832}},
00100     {3, {9, 936}},
00101     {4, {10, 1040}},
00102     {5, {11, 1144}},
00103     {6, {12, 1248}},
00104     {7, {13, 1352}},
00105     {8, {14, 1456}},
00106     {9, {0, 0}},
00107     {10, {0, 0}},
00108     {11, {0, 0}},
00109     {12, {0, 0}},
00110     {13, {0, 0}},
00111     {14, {0, 0}},
00112     {15, {0, 0}}}; // key: nb_dk, value: {num_blocks, l_dk_bits}
00113
00114 const std::unordered_map<uint8_t, std::string> OSNMA_TABLE_8 = {
00115     {0, std::string("SHA-256")},
00116     {1, std::string("Reserved")},
00117     {2, std::string("SHA3-256")},
00118     {3, std::string("Reserved")}; // key: hs, value: hash_function
00119
00120 const std::unordered_map<uint8_t, uint16_t> OSNMA_TABLE_10 = {
00121     {0, 96},
00122     {1, 104},
00123     {2, 112},
00124     {3, 120},
00125     {4, 128},
00126     {5, 160},
00127     {6, 192},
00128     {7, 224},
00129     {8, 256},
00130     {9, 0},
00131     {10, 0},
00132     {11, 0},
00133     {12, 0},
00134     {13, 0},
00135     {15, 0},
00136     {15, 0}}; // key: ks, value: lk_bits
00137
00138 const std::unordered_map<uint8_t, uint8_t> OSNMA_TABLE_11 = {
00139     {0, 0},
00140     {1, 0},
00141     {2, 0},
00142     {3, 0},
00143     {4, 0},
00144     {5, 20},
00145     {6, 24},
00146     {7, 28},
00147     {8, 32},
00148     {9, 40},
00149     {10, 0},
00150     {11, 0},
00151     {12, 0},
00152     {13, 0},
00153     {14, 0},
00154     {15, 0},
00155 };
00156
00157 const std::unordered_map<std::string, uint16_t> OSNMA_TABLE_15 = {
00158     {std::string("ECDSA P-256"), 512},
00159     {std::string("ECDSA P-521"), 1056}}; // key: ECDSA Curve and hash function, value: {l_ds_bits}
00160
00161 const std::string PEMFILE_DEFAULT("./OSNMA_PublicKey.pem");
00162 const std::string CRTFILE_DEFAULT("./OSNMA_PublicKey_20240115100000_newPKID_1.crt");
00163 const std::string MERKLEFILE_DEFAULT("./OSNMA_MerkleTree_20240115100000_newPKID_1.xml");
00164 const std::string KROOTFILE_DEFAULT("./OSNMA_DSM_KROOT_NMAHeader.bin");
00165
00166 class Mack_lookup
00167 {
00168 public:
00169     Mack_lookup() = default;
00170     Mack_lookup(uint8_t msg_,
00171                 uint8_t nt_,
00172                 const std::vector<std::string>& s1_,
00173                 const std::vector<std::string>& s2_) : msg(msg_),
00174                                                         nt(nt_),
00175                                                         sequence1(s1_),
00176                                                         sequence2(s2_) {};
00177     uint8_t msg{};
00178     uint8_t nt{};
00179     std::vector<std::string> sequence1;

```

```

00180     std::vector<std::string> sequence2;
00181 };
00182
00183 const std::unordered_map<uint8_t, Mack_lookup> OSNMA_TABLE_16 = {
00184     {27, {2, 6, {"00S", "00E", "00E", "00E", "12S", "00E"}, {"00S ", "00E", "00E", "04S", "12S",
00185         "00E"}}},
00186     {28, {2, 10, {"00S", "00E", "00E", "00E", "00S", "00E", "00E", "12S", "00E", "00E"}, {"00S",
00187         "00E", "00E", "00S", "00E", "00E", "04S", "12S", "00E", "00E"}}},
00188     {31, {2, 5, {"00S", "00E", "00E", "12S", "00E"}, {"00S", "00E", "00E", "12S", "04S"}}},
00189     {33, {2, 6, {"00S", "00E", "04S", "00E", "12S", "00E"}, {"00S", "00E", "00E", "12S", "00E",
00190         "12E"}}},
00191     {34, {2, 6, {"00S", "FLX", "04S", "FLX", "12S", "00E"}, {"00S", "FLX", "00E", "12S", "00E",
00192         "12E"}}},
00193     {35, {2, 6, {"00S", "FLX", "04S", "FLX", "12S", "FLX"}, {"00S", "FLX", "FLX", "12S", "FLX",
00194         "FLX"}}},
00195     {36, {2, 5, {"00S", "FLX", "04S", "FLX", "12S"}, {"00S", "FLX", "00E", "12S", "12E"}}},
00196     {37, {2, 5, {"00S", "00E", "04S", "00E", "12S"}, {"00S", "00E", "00E", "12S", "12E"}}},
00197     {38, {2, 5, {"00S", "FLX", "04S", "FLX", "12S"}, {"00S", "FLX", "FLX", "12S", "FLX"}}},
00198     {39, {2, 4, {"00S", "FLX", "04S", "FLX"}, {"00S", "FLX", "00E", "12S"}}},
00199     {40, {2, 4, {"00S", "00E", "04S", "12S"}, {"00S", "00E", "00E", "12E"}}},
00200     {41, {2, 4, {"00S", "FLX", "04S", "FLX"}, {"00S", "FLX", "FLX", "12S"}}};
00201
00202 /** \} */
00203 /** \} */
00204 #endif // GNSS_SDR_GALILEO_OSNMA_H

```

13.765 galileo_reduced_ced.h File Reference

Galileo Reduced Clock and Ephemeris Data storage class.

```
#include "galileo_ephemeris.h"
```

```
#include <cstdint>
```

Classes

- class [Galileo_Reduced_CED](#)

This class manages the Galileo Reduced Clock and Ephemeris Data.

13.765.1 Detailed Description

Galileo Reduced Clock and Ephemeris Data storage class.

Author

Carles Fernandez, 2021. cfernandez(at)cttc.cat

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Definition in file [galileo_reduced_ced.h](#).

13.766 galileo_reduced_ced.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file galileo_reduced_ced.h
00003  * \brief Galileo Reduced Clock and Ephemeris Data storage class
00004  * \author Carles Fernandez, 2021. cfernandez(at)cttc.cat
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GALILEO_REDUCED_CED_H
00019 #define GNSS_SDR_GALILEO_REDUCED_CED_H
00020

```

```

00021 #include "galileo_ephemeris.h"
00022 #include <cstdint>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup System_Parameters
00027  * \{ */
00028
00029
00030 /*!
00031  * \brief This class manages the Galileo Reduced Clock and Ephemeris Data
00032  */
00033 class Galileo_Reduced_CED
00034 {
00035 public:
00036     /*!
00037      * Default constructor
00038      */
00039     Galileo_Reduced_CED() = default;
00040
00041     /*!
00042      * Convert to Galileo_Ephemeris
00043      */
00044     Galileo_Ephemeris compute_eph() const;
00045
00046     uint32_t PRN{};          //!< Satellite ID
00047     int32_t TOTRedCED{};     //!< Start time of transmission of the Reduced CED word in GST
00048     int32_t IODnav{};        //!< Issue of Data
00049     double DeltaAred{};      //!< Difference between the Reduced CED semi-major axis and the nominal
                                semi-major axis [meters]
00050     double exred{};          //!< Reduced CED eccentricity vector component x
00051     double eyred{};          //!< Reduced CED eccentricity vector component y
00052     double Deltai0red{};     //!< Difference between the Reduced CED inclination angle at reference time
                                and the nominal inclination [rad]
00053     double Omega0red{};      //!< Reduced CED longitude of ascending node at weekly epoch [rad]
00054     double lambda0red{};     //!< Reduced CED mean argument of latitude [rad]
00055     double af0red{};         //!< Reduced CED satellite clock bias correction coefficient [seconds]
00056     double aflred{};         //!< Reduced CED satellite clock drift correction coefficient
                                [seconds/seconds]
00057 };
00058
00059
00060 /** \} */
00061 /** \} */
00062 #endif // GNSS_SDR_GALILEO_REDUCED_CED_H

```

13.767 galileo_utc_model.h File Reference

Interface of a Galileo UTC MODEL storage.

```

#include <boost/serialization/nvp.hpp>
#include <cstdint>

```

Classes

- class [Galileo_Utc_Model](#)

This class is a storage for the GALILEO UTC MODEL data as described in Galileo ICD https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf paragraph 5.1.7.

13.767.1 Detailed Description

Interface of a Galileo UTC MODEL storage.

Author

Javier Arribas, 2013. jarribas(at)cttc.es

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Definition in file [galileo_utc_model.h](#).

13.768 galileo_utc_model.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file galileo_utc_model.h
00003  * \brief Interface of a Galileo UTC MODEL storage
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GALILEO_UTC_MODEL_H
00020 #define GNSS_SDR_GALILEO_UTC_MODEL_H
00021
00022 #include <boost/serialization/nvp.hpp>
00023 #include <cstdint>
00024
00025 /** \addtogroup Core
00026  * \{ */
00027 /** \addtogroup System_Parameters
00028  * \{ */
00029
00030
00031  /*!
00032  * \brief This class is a storage for the GALILEO UTC MODEL data as described in Galileo ICD
00033  * \a https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OS_SIS_ICD_v2.0.pdf
00034  * \a paragraph 5.1.7
00035  */
00036  class Galileo_Utc_Model
00037  {
00038  public:
00039      /*!
00040       * Default constructor
00041       */
00042      Galileo_Utc_Model() = default;
00043
00044      // double TOW;
00045      double GST_to_UTC_time(double t_e, int32_t WN) const; //!< GST-UTC Conversion Algorithm and
Parameters
00046
00047      // Word type 6: GST-UTC conversion parameters
00048      double A0{};
00049      double A1{};
00050      int32_t Delta_tLS{};
00051      int32_t tot{}; //!< UTC data reference Time of Week [s]
00052      int32_t WNot{}; //!< UTC data reference Week number [week]
00053      int32_t WN_LSF{};
00054      int32_t DN{};
00055      int32_t Delta_tLSF{};
00056
00057      // GPS to Galileo GST conversion parameters
00058      double A_0G{};
00059      double A_1G{};
00060      int32_t t_0G{};
00061      int32_t WN_0G{};
00062
00063      bool flag_utc_model{};
00064
00065      template <class Archive>
00066
00067      /*!
00068       * \brief Serialize is a boost standard method to be called by the boost XML serialization.
00069       * Here is used to save the UTC data on disk file.
00070       */
00071      inline void serialize(Archive& archive, const unsigned int version)
00072      {
00073          if (version)
00074          {
00075              ;
00076              archive& BOOST_SERIALIZATION_NVP(A0);
00077              archive& BOOST_SERIALIZATION_NVP(A1);
00078              archive& BOOST_SERIALIZATION_NVP(Delta_tLS);
00079              archive& BOOST_SERIALIZATION_NVP(tot);
00080              archive& BOOST_SERIALIZATION_NVP(WNot);
00081              archive& BOOST_SERIALIZATION_NVP(WN_LSF);
00082              archive& BOOST_SERIALIZATION_NVP(DN);

```

```

00083         archive& BOOST_SERIALIZATION_NVP(Delta_tLSF);
00084         archive& BOOST_SERIALIZATION_NVP(flag_utc_model);
00085     }
00086 };
00087
00088
00089 /** \} */
00090 /** \} */
00091 #endif // GNSS_SDR_GALILEO_UTC_MODEL_H

```

13.769 glonass_gnav_almanac.h File Reference

Interface of a GLONASS GNAV ALMANAC storage.

```

#include <boost/serialization/nvp.hpp>
#include <cstdint>

```

Classes

- class [Glonass_Gnav_Almanac](#)

This class is a storage for the GLONASS SV ALMANAC data as described GLONASS ICD (Edition 5.1)

13.769.1 Detailed Description

Interface of a GLONASS GNAV ALMANAC storage.

Note

Code added as part of GSoC 2017 program

Author

Damian Miralles, 2017. dmiralles2009(at)gmail.com

See also

[GLONASS ICD](#)

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 Definition in file [glonass_gnav_almanac.h](#).

13.770 glonass_gnav_almanac.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file glonass_gnav_almanac.h
00003  * \brief Interface of a GLONASS GNAV ALMANAC storage
00004  * \note Code added as part of GSoC 2017 program
00005  * \author Damian Miralles, 2017. dmiralles2009(at)gmail.com
00006  * \see <a
00007         href="http://russianspacesystems.ru/wp-content/uploads/2016/08/ICD_GLONASS_eng_v5.1.pdf">GLONASS
00008         ICD</a>
00009  *
00010  * -----
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019
00020 #ifndef GNSS_SDR_GLONASS_ALMANAC_H
00021 #define GNSS_SDR_GLONASS_ALMANAC_H
00022

```

```

00023 #include <boost/serialization/nvp.hpp>
00024 #include <cstdint>
00025
00026 /** \addtogroup Core
00027  * \{ */
00028 /** \addtogroup System_Parameters
00029  * \{ */
00030
00031
00032 /*!
00033  * \brief This class is a storage for the GLONASS SV ALMANAC data as described GLONASS ICD (Edition
00034 5.1)
00035  * \note Code added as part of GSoC 2017 program
00036  * \see <a
00037 href="http://russianspacesystems.ru/wp-content/uploads/2016/08/ICD_GLONASS_eng_v5.1.pdf">GLONASS
00038 ICD</a>
00039 */
00040 class Glonass_Gnav_Almanac
00041 {
00042 public:
00043     /*!
00044     * Default constructor
00045     */
00046     Glonass_Gnav_Almanac() = default;
00047
00048     double d_n_A{};                //!< Conventional number of satellite within GLONASS space segment
00049     [dimensionless]
00050     double d_H_n_A{};              //!< Carrier frequency number of navigation RF signal transmitted by
00051     d_n_A satellite as table 4.10 (0-31) [dimensionless]
00052     double d_lambda_n_A{};         //!< Longitude of the first (within the d_n_A day) ascending node of
00053     d_n_A [radians]
00054     double d_t_lambda_n_A{};       //!< Time of first ascending node passage [s]
00055     double d_Delta_i_n_A{};        //!< Correction of the mean value of inclination of d_n_A satellite
00056     at instant t_lambda_n_A [radians]
00057     double d_Delta_T_n_A{};        //!< Correction to the mean value of Draconian period of d_n_A
00058     satellite at instant t_lambda_n_A [s / orbital period]
00059     double d_Delta_T_n_A_dot{};    //!< Rate of change of Draconian period of d_n_A satellite at instant
00060     t_lambda_n_A [s / orbital period^2]
00061     double d_epsilon_n_A{};        //!< Eccentricity of d_n_A satellite at instant t_lambda_n_A
00062     [dimensionless]
00063     double d_omega_n_A{};          //!< Argument of perigee of d_n_A satellite at instant t_lambda_n_A
00064     [radians]
00065     double d_M_n_A{};              //!< Type of satellite n_A [dimensionless]
00066     double d_KP{};                 //!< Notification on forthcoming leap second correction of UTC
00067     [dimensionless]
00068     double d_tau_n_A{};            //!< Coarse value of d_n_A satellite time correction to GLONASS time
00069     at instant t_lambda_n_A[s]
00070     bool d_C_n{};                  //!< Generalized "unhealthy flag" of n_A satellite at instant of
00071     almanac upload [dimensionless]
00072     bool d_l_n{};                  //!< Health flag for nth satellite; ln = 0 indicates the n-th
00073     satellite is healthy, ln = 1 indicates malfunction of this nth satellite [dimensionless]
00074
00075     // Satellite Identification Information
00076     int32_t i_satellite_freq_channel{}; //!< SV Frequency Channel Number
00077     uint32_t PRN{};                   //!< SV PRN Number, equivalent to slot number for
00078     compatibility with GPS
00079     uint32_t i_satellite_slot_number{}; //!< SV Slot Number
00080
00081     template <class Archive>
00082     /*!
00083     * \brief Serialize is a boost standard method to be called by the boost XML
00084     * serialization. Here is used to save the almanac data on disk file.
00085     */
00086     void serialize(Archive& archive, const uint32_t version)
00087     {
00088         if (version)
00089         {
00090
00091             archive& BOOST_SERIALIZATION_NVP(i_satellite_freq_channel);
00092             archive& BOOST_SERIALIZATION_NVP(PRN);
00093             archive& BOOST_SERIALIZATION_NVP(i_satellite_slot_number);
00094             archive& BOOST_SERIALIZATION_NVP(d_n_A);
00095             archive& BOOST_SERIALIZATION_NVP(d_H_n_A);
00096             archive& BOOST_SERIALIZATION_NVP(d_lambda_n_A);
00097             archive& BOOST_SERIALIZATION_NVP(d_t_lambda_n_A);
00098             archive& BOOST_SERIALIZATION_NVP(d_Delta_i_n_A);
00099             archive& BOOST_SERIALIZATION_NVP(d_Delta_T_n_A);
00100             archive& BOOST_SERIALIZATION_NVP(d_Delta_T_n_A_dot);
00101             archive& BOOST_SERIALIZATION_NVP(d_epsilon_n_A);
00102             archive& BOOST_SERIALIZATION_NVP(d_omega_n_A);
00103             archive& BOOST_SERIALIZATION_NVP(d_M_n_A);
00104             archive& BOOST_SERIALIZATION_NVP(d_KP);
00105             archive& BOOST_SERIALIZATION_NVP(d_tau_n_A);
00106             archive& BOOST_SERIALIZATION_NVP(d_C_n);
00107             archive& BOOST_SERIALIZATION_NVP(d_l_n);
00108         }
00109     }

```

```

00094 };
00095
00096
00097 /** \} */
00098 /** \} */
00099 #endif // GNSS_SDR_GLOMSS_ALMANAC_H

```

13.771 glonass_gnav_ephemeris.h File Reference

Interface of a GLONASS EPHEMERIS storage.

```

#include "glonass_gnav_utc_model.h"
#include <boost/date_time/posix_time/ptime.hpp>
#include <boost/serialization/nvp.hpp>
#include <cstdint>

```

Classes

- class [Glonass_Gnav_Ephemeris](#)

This class is a storage and orbital model functions for the GLONASS SV ephemeris data as described in GLONASS ICD (Edition 5.1)

13.771.1 Detailed Description

Interface of a GLONASS EPHEMERIS storage.

Note

Code added as part of GSoC 2017 program

Author

Damian Miralles, 2017. dmiralles2009(at)gmail.com

See also

[GLONASS ICD](#)

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 Definition in file [glonass_gnav_ephemeris.h](#).

13.772 glonass_gnav_ephemeris.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file glonass_gnav_ephemeris.h
00003  * \brief Interface of a GLONASS EPHEMERIS storage
00004  * \note Code added as part of GSoC 2017 program
00005  * \author Damian Miralles, 2017. dmiralles2009(at)gmail.com
00006  * \see <a
00007  * href="http://russianspacesystems.ru/wp-content/uploads/2016/08/ICD_GLONASS_eng_v5.1.pdf">GLONASS
00008  * ICD</a>
00009  * -----
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  * -----
00016  *
00017  */
00018
00019
00020 #ifndef GNSS_SDR_GLOMSS_GNAV_EPHEMERIS_H
00021 #define GNSS_SDR_GLOMSS_GNAV_EPHEMERIS_H

```

```

00022
00023
00024 #include "glonass_gnav_utc_model.h"
00025 #include <boost/date_time/posix_time/ptime.hpp> // for ptime
00026 #include <boost/serialization/nvp.hpp>
00027 #include <cstdint>
00028
00029 /** \addtogroup Core
00030 * \{ */
00031 /** \addtogroup System_Parameters
00032 * \{ */
00033
00034
00035 /*!
00036 * \brief This class is a storage and orbital model functions for the GLONASS SV ephemeris data as
described in GLONASS ICD (Edition 5.1)
00037 * \note Code added as part of GSoC 2017 program
00038 * \see <a
href="http://russianspacesystems.ru/wp-content/uploads/2016/08/ICD_GLONASS_eng_v5.1.pdf">GLONASS
ICD</a>
00039 */
00040 class Glonass_Gnav_Ephemeris
00041 {
00042 public:
00043     /*!
00044     * Default constructor
00045     */
00046     Glonass_Gnav_Ephemeris() = default;
00047
00048     double d_m{}; //!< String number within frame [dimensionless]
00049     double d_t_k{}; //!< GLONASS Time (UTC(SU) + 3 h) referenced to the beginning of the
frame within the current day [s]
00050     double d_t_b{}; //!< Reference ephemeris relative time in GLONASS Time (UTC(SU) + 3 h).
Index of a time interval within current day according to UTC(SU) + 03 hours 00 min. [s]
00051     double d_M{}; //!< Type of satellite transmitting navigation signal [dimensionless]
00052     double d_gamma_n{}; //!< Relative deviation of predicted carrier frequency value of n-
satellite from nominal value at the instant tb [dimensionless]
00053     double d_tau_n{}; //!< Correction to the nth satellite time (tn) relative to GLONASS time
(te),
00054     double d_Xn{}; //!< Earth-fixed coordinate x of the satellite in PZ-90.02 coordinate
system [km].
00055     double d_Yn{}; //!< Earth-fixed coordinate y of the satellite in PZ-90.02 coordinate
system [km]
00056     double d_Zn{}; //!< Earth-fixed coordinate z of the satellite in PZ-90.02 coordinate
system [km]
00057     double d_VXn{}; //!< Earth-fixed velocity coordinate x of the satellite in PZ-90.02
coordinate system [km/s]
00058     double d_VYn{}; //!< Earth-fixed velocity coordinate y of the satellite in PZ-90.02
coordinate system [km/s]
00059     double d_VZn{}; //!< Earth-fixed velocity coordinate z of the satellite in PZ-90.02
coordinate system [km/s]
00060     double d_AXn{}; //!< Earth-fixed acceleration coordinate x of the satellite in PZ-90.02
coordinate system [km/s^2]
00061     double d_AYn{}; //!< Earth-fixed acceleration coordinate y of the satellite in PZ-90.02
coordinate system [km/s^2]
00062     double d_AZn{}; //!< Earth-fixed acceleration coordinate z of the satellite in PZ-90.02
coordinate system [km/s^2]
00063     double d_B_n{}; //!< Health flag [dimensionless]
00064     double d_P{}; //!< Technological parameter of control segment, indication the satellite
operation mode in respect of
time parameters [dimensionless]
00065     double d_N_T{}; //!< Current date, calendar number of day within four-year interval
starting from the 1-st of January in a leap year [days]
00066     double d_F_T{}; //!< Parameter that provides the predicted satellite user range accuracy
at time tb [dimensionless]
00067     double d_n{}; //!< Index of the satellite transmitting given navigation signal. It
corresponds to a slot number within GLONASS constellation
00068     double d_Delta_tau_n{}; //!< Time difference between navigation RF signal transmitted in L2 sub-
band and aviation RF signal transmitted in L1 sub-band by nth satellite. [dimensionless]
00069     double d_E_n{}; //!< Characterises "age" of a current information [days]
00070     double d_P_1{}; //!< Flag of the immediate data updating [minutes]
00071     bool d_P_2{}; //!< Flag of oddness ("1") or evenness ("0") of the value of (tb)
[dimensionless]
00072     bool d_P_3{}; //!< Flag indicating a number of satellites for which almanac is
transmitted within given frame: "1" corresponds to 5 satellites and "0" corresponds to 4 satellites
[dimensionless]
00073     bool d_P_4{}; //!< Flag to show that ephemeris parameters are present. "1" indicates
that updated ephemeris or frequency/time parameters have been uploaded by the control segment
[dimensionless]
00074     bool d_l3rd_n{}; //!< Health flag for nth satellite; ln = 0 indicates the n-th satellite
is healthy, ln = 1 indicates malfunction of this nth satellite [dimensionless]
00075     bool d_l5th_n{}; //!< Health flag for nth satellite; ln = 0 indicates the n-th satellite
is healthy, ln = 1 indicates malfunction of this nth satellite [dimensionless]
00076
00077     // Immediate deliverables of ephemeris information
00078     // Satellite Identification Information
00079     int32_t i_satellite_freq_channel{}; //!< SV Frequency Channel Number
00080     uint32_t PRN{}; //!< SV PRN Number, equivalent to slot number for

```



```

compatibility with GPS
00081  uint32_t i_satellite_slot_number{};    //!< SV Slot Number
00082  double d_yr = 1972.0;                 //!< Current year
00083  double d_satClkDrift{};               //!< GLONASS clock error
00084  double d_dtr{};                       //!< relativistic clock correction term
00085  double d_diode{};                     //!< Issue of data, ephemeris (Bit 0-6 of tb)
00086  double d_tau_c{};                     //!< GLONASST 2 UTC correction (todo) may be eliminated
00087  double d_TOW{};                       //!< GLONASST IN GPST seconds of week
00088  int32_t d_WN{};                       //!< GLONASST IN GPST week number of the start of frame
00089  double d_tod{};                       //!< Time of Day since ephemeris where decoded
00090
00091  /*!
00092   * \brief Sets (\a d_satClkDrift) and returns the clock drift in seconds according to the User
Algorithm for SV Clock Correction
00093   */
00094   double sv_clock_drift(double transmitTime, double timeCorrUTC);
00095
00096  /*!
00097   * \brief Computes the GLONASS System Time and returns a boost::posix_time::ptime object
00098   * \param offset_time Is the start of day offset to compute the time
00099   */
00100   boost::posix_time::ptime compute_GLONASS_time(double offset_time) const;
00101
00102  /*!
00103   * \brief Converts from GLONASST to UTC
00104   * \details The function simply adjust for the 6 hrs offset between GLONASST and UTC
00105   * \param[in] offset_time Is the start of day offset
00106   * \param[in] glot2utc_corr Correction from GLONASST to UTC
00107   * \returns UTC time as a boost::posix_time::ptime object
00108   */
00109   boost::posix_time::ptime glot_to_utc(double offset_time, double glot2utc_corr) const;
00110
00111  /*!
00112   * \brief Converts from GLONASST to GPST
00113   * \details Converts from GLONASST to GPST in time of week (TOW) and week number (WN) format
00114   * \param[in] tod_offset Is the start of day offset
00115   * \param[in] glot2utc_corr Correction from GLONASST to UTC
00116   * \param[in] glot2gpst_corr Correction from GLONASST to GPST
00117   * \param[out] WN Week Number, not in mod(1024) format
00118   * \param[out] TOW Time of Week in seconds of week
00119   */
00120   void glot_to_gpst(double tod_offset, double glot2utc_corr, double glot2gpst_corr, int32_t* WN,
double* TOW) const;
00121
00122   template <class Archive>
00123
00124   /*!
00125   * \brief Serialize is a boost standard method to be called by the boost XML
00126   * serialization. Here is used to save the ephemeris data on disk file.
00127   */
00128   void serialize(Archive& archive, const uint32_t version)
00129   {
00130       if (version)
00131       {
00132       };
00133
00134       archive< BOOST_SERIALIZATION_NVP(i_satellite_freq_channel);    //!< SV PRN frequency channel
number
00135       archive< BOOST_SERIALIZATION_NVP(PRN);
00136       archive< BOOST_SERIALIZATION_NVP(i_satellite_slot_number);
00137       archive< BOOST_SERIALIZATION_NVP(d_m);                        //!< String number within frame
[dimensionless]
00138       archive< BOOST_SERIALIZATION_NVP(d_t_k);                    //!< Time referenced to the beginning of the
frame within the current day [hours, minutes, seconds]
00139       archive< BOOST_SERIALIZATION_NVP(d_t_b);                    //!< Index of a time interval within current
day according to UTC(SU) + 03 hours 00 min. [minutes]
00140       archive< BOOST_SERIALIZATION_NVP(d_M);                      //!< Type of satellite transmitting
navigation signal [dimensionless]
00141       archive< BOOST_SERIALIZATION_NVP(d_gamma_n);                //!< Relative deviation of predicted carrier
frequency value of n- satellite from nominal value at the instant tb [dimensionless]
00142       archive< BOOST_SERIALIZATION_NVP(d_tau_n);                  //!< Correction to the nth satellite time
(tn) relative to GLONASS time (te)
00143       archive< BOOST_SERIALIZATION_NVP(d_Xn);                      //!< Earth-fixed coordinate x of the
satellite in PZ-90.02 coordinate system [km].
00144       archive< BOOST_SERIALIZATION_NVP(d_Yn);                      //!< Earth-fixed coordinate y of the
satellite in PZ-90.02 coordinate system [km]
00145       archive< BOOST_SERIALIZATION_NVP(d_Zn);                      //!< Earth-fixed coordinate z of the
satellite in PZ-90.02 coordinate system [km]
00146       archive< BOOST_SERIALIZATION_NVP(d_VXn);                    //!< Earth-fixed velocity coordinate x of
the satellite in PZ-90.02 coordinate system [km/s]
00147       archive< BOOST_SERIALIZATION_NVP(d_VYn);                    //!< Earth-fixed velocity coordinate y of
the satellite in PZ-90.02 coordinate system [km/s]
00148       archive< BOOST_SERIALIZATION_NVP(d_VZn);                    //!< Earth-fixed velocity coordinate z of
the satellite in PZ-90.02 coordinate system [km/s]
00149       archive< BOOST_SERIALIZATION_NVP(d_AXn);                    //!< Earth-fixed acceleration coordinate x
of the satellite in PZ-90.02 coordinate system [km/s^2]
00150       archive< BOOST_SERIALIZATION_NVP(d_AYn);                    //!< Earth-fixed acceleration coordinate y

```

```

    of the satellite in PZ-90.02 coordinate system [km/s^2]
00151     archive& BOOST_SERIALIZATION_NVP(d_Azn);          //!< Earth-fixed acceleration coordinate z
    of the satellite in PZ-90.02 coordinate system [km/s^2]
00152     archive& BOOST_SERIALIZATION_NVP(d_B_n);          //!< Health flag [dimensionless]
00153     archive& BOOST_SERIALIZATION_NVP(d_P);          //!< Technological parameter of control
    segment, indication the satellite operation mode in respect of time parameters [dimensionless]
00154     archive& BOOST_SERIALIZATION_NVP(d_N_T);          //!< Current date, calendar number of day
    within four-year interval starting from the 1-st of January in a leap year [days]
00155     archive& BOOST_SERIALIZATION_NVP(d_F_T);          //!< Parameter that provides the predicted
    satellite user range accuracy at time tb [dimensionless]
00156     archive& BOOST_SERIALIZATION_NVP(d_n);          //!< Index of the satellite transmitting
    given navigation signal. It corresponds to a slot number within GLONASS constellation
00157     archive& BOOST_SERIALIZATION_NVP(d_Delta_tau_n);  //!< Time difference between navigation RF
    signal transmitted in L2 sub- band and aviation RF signal transmitted in L1 sub-band by nth satellite.
    [dimensionless]
00158     archive& BOOST_SERIALIZATION_NVP(d_E_n);          //!< Characterises "age" of a current
    information [days]
00159     archive& BOOST_SERIALIZATION_NVP(d_P_1);          //!< Flag of the immediate data updating.
00160     archive& BOOST_SERIALIZATION_NVP(d_P_2);          //!< Flag of oddness ("1") or evenness ("0")
    of the value of (tb) [dimensionless]
00161     archive& BOOST_SERIALIZATION_NVP(d_P_3);          //!< Flag indicating a number of satellites
    for which almanac is transmitted within given frame: "1" corresponds to 5 satellites and "0"
    corresponds to 4 satellites [dimensionless]
00162     archive& BOOST_SERIALIZATION_NVP(d_P_4);          //!< Flag to show that ephemeris parameters
    are present. "1" indicates that updated ephemeris or frequency/time parameters have been uploaded by
    the control segment [dimensionless]
00163     archive& BOOST_SERIALIZATION_NVP(d_l3rd_n);        //!< Health flag for nth satellite; ln = 0
    indicates the n-th satellite is helthy, ln = 1 indicates malfunction of this nth satellite
    [dimensionless]
00164     archive& BOOST_SERIALIZATION_NVP(d_l5th_n);        //!< Health flag for nth satellite; ln = 0
    indicates the n-th satellite is helthy, ln = 1 indicates malfunction of this nth satellite
    [dimensionless]
00165 }
00166
00167 private:
00168     /*
00169     * Accounts for the beginning or end of week crossover
00170     *
00171     * \param[in] - time in seconds
00172     * \param[out] - corrected time, in seconds
00173     */
00174     double check_t(double time);
00175 };
00176
00177
00178 /** \} */
00179 /** \} */
00180 #endif // GNSS_SDR_GLO_NASS_GNAV_EPHEMERIS_H

```

13.773 glonass_gnav_navigation_message.h File Reference

Interface of a GLONASS GNAV Data message decoder as described in GLONASS ICD (Edition 5.1)

```

#include "GLONASS_L1_L2_CA.h"
#include "glonass_gnav_almanac.h"
#include "glonass_gnav_ephemeris.h"
#include "glonass_gnav_utc_model.h"
#include <bitset>
#include <stdint>
#include <string>
#include <utility>
#include <vector>

```

Classes

- class [Glonass_Gnav_Navigation_Message](#)

This class decodes a GLONASS GNAV Data message as described in GLONASS ICD (Edition 5.1)

13.773.1 Detailed Description

Interface of a GLONASS GNAV Data message decoder as described in GLONASS ICD (Edition 5.1)

Note

Code added as part of GSoC 2017 program

Author

Damian Miralles, 2017. dmiralles2009(at)gmail.com

See also

[GLONASS ICD](#)

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 Definition in file [glonass_gnav_navigation_message.h](#).

13.774 glonass_gnav_navigation_message.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file glonass_gnav_navigation_message.h
00003  * \brief Interface of a GLONASS GNAV Data message decoder as described in GLONASS ICD (Edition 5.1)
00004  * \note Code added as part of GSoC 2017 program
00005  * \author Damian Miralles, 2017. dmiralles2009(at)gmail.com
00006  * \see <a
00007  href="http://russianspacesystems.ru/wp-content/uploads/2016/08/ICD_GLONASS_eng_v5.1.pdf">GLONASS
00008  ICD</a>
00009  *
00010  * -----
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019
00020 #ifndef GNSS_SDR_GLONASS_GNAV_NAVIGATION_MESSAGE_H
00021 #define GNSS_SDR_GLONASS_GNAV_NAVIGATION_MESSAGE_H
00022
00023
00024 #include "GLONASS_L1_L2_CA.h"
00025 #include "glonass_gnav_almanac.h"
00026 #include "glonass_gnav_ephemeris.h"
00027 #include "glonass_gnav_utc_model.h"
00028 #include <bitset>
00029 #include <stdint>
00030 #include <string>
00031 #include <utility> // for pair
00032 #include <vector> // for vector
00033
00034 /** \addtogroup Core
00035  * \{ */
00036 /** \addtogroup System_Parameters
00037  * \{ */
00038
00039
00040 /*!
00041 * \brief This class decodes a GLONASS GNAV Data message as described in GLONASS ICD (Edition 5.1)
00042 * \note Code added as part of GSoC 2017 program
00043 * \see <a
00044 href="http://russianspacesystems.ru/wp-content/uploads/2016/08/ICD_GLONASS_eng_v5.1.pdf">GLONASS
00045 ICD</a>
00046 */
00047 class Glonass_Gnav_Navigation_Message
00048 {
00049 public:
00050     /*!
00051     * Default constructor
00052     */
00053     Glonass_Gnav_Navigation_Message() = default;
00054
00055     /*!
00056     * \brief Compute CRC for GLONASS GNAV strings
00057     * \param bits Bits of the string message where to compute CRC
00058     */
00059     bool CRC_test(std::bitset<GLONASS_GNAV_STRING_BITS>& bits) const;

```

```

00058
00059     /*!
00060     * \brief Computes the frame number being decoded given the satellite slot number
00061     * \param satellite_slot_number [in] Satellite slot number identifier
00062     * \returns Frame number being decoded, 0 if operation was not successful.
00063     */
00064     uint32_t get_frame_number(uint32_t satellite_slot_number);
00065
00066     /*!
00067     * \brief Obtain a GLONASS GNAV SV Ephemeris class filled with current SV data
00068     */
00069     Glonass_Gnav_Ephemeris get_ephemeris() const
00070     {
00071         return gnav_ephemeris;
00072     }
00073
00074     /*!
00075     * \brief Obtain a GLONASS GNAV UTC model parameters class filled with current SV data
00076     */
00077     inline Glonass_Gnav_Utc_Model get_utc_model() const
00078     {
00079         return gnav_utc_model;
00080     }
00081
00082     /*!
00083     * \brief Returns a Glonass_Gnav_Almanac object filled with the latest navigation data received
00084     * \param satellite_slot_number Slot number identifier for the satellite
00085     * \returns Returns the Glonass_Gnav_Almanac object for the input slot number
00086     */
00087     Glonass_Gnav_Almanac get_almanac(uint32_t satellite_slot_number) const;
00088
00089     /*!
00090     * \brief Returns true if a new Glonass_Gnav_Ephemeris object has arrived.
00091     */
00092     bool have_new_ephemeris();
00093
00094     /*!
00095     * \brief Returns true if new Glonass_Gnav_Utc_Model object has arrived
00096     */
00097     bool have_new_utc_model();
00098
00099     /*!
00100     * \brief Returns true if new Glonass_Gnav_Almanac object has arrived.
00101     */
00102     bool have_new_almanac();
00103
00104     /*!
00105     * \brief Decodes the GLONASS GNAV string
00106     * \param frame_string [in] is the string message within the parsed frame
00107     * \returns Returns the ID of the decoded string
00108     */
00109     int32_t string_decoder(const std::string& frame_string);
00110
00111     inline bool get_flag_CRC_test() const
00112     {
00113         return flag_CRC_test;
00114     }
00115
00116     inline void set_rf_link(int32_t rf_link)
00117     {
00118         gnav_ephemeris.i_satellite_freq_channel = rf_link;
00119     }
00120
00121     inline uint32_t get_alm_satellite_slot_number() const
00122     {
00123         return i_alm_satellite_slot_number;
00124     }
00125
00126     inline bool get_flag_update_slot_number() const
00127     {
00128         return flag_update_slot_number;
00129     }
00130
00131     inline void set_flag_update_slot_number(bool flag_slot)
00132     {
00133         flag_update_slot_number = flag_slot;
00134     }
00135
00136     inline bool get_flag_TOW_new() const
00137     {
00138         return flag_TOW_new;
00139     }
00140
00141     inline void set_flag_TOW_new(bool tow_new)
00142     {
00143         flag_TOW_new = tow_new;
00144     }

```

```

00145
00146     inline bool is_flag_TOW_set() const
00147     {
00148         return flag_TOW_set;
00149     }
00150
00151     inline void set_flag_ephemeris_str_1(bool ephemeris_str_1)
00152     {
00153         flag_ephemeris_str_1 = ephemeris_str_1;
00154     }
00155
00156     inline void set_flag_ephemeris_str_2(bool ephemeris_str_2)
00157     {
00158         flag_ephemeris_str_2 = ephemeris_str_2;
00159     }
00160
00161     inline void set_flag_ephemeris_str_3(bool ephemeris_str_3)
00162     {
00163         flag_ephemeris_str_3 = ephemeris_str_3;
00164     }
00165
00166     inline void set_flag_ephemeris_str_4(bool ephemeris_str_4)
00167     {
00168         flag_ephemeris_str_4 = ephemeris_str_4;
00169     }
00170
00171 private:
00172     uint64_t read_navigation_unsigned(const std::bitset<GLONASS_GNAV_STRING_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter> const;
00173     int64_t read_navigation_signed(const std::bitset<GLONASS_GNAV_STRING_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter> const;
00174     bool read_navigation_bool(const std::bitset<GLONASS_GNAV_STRING_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter> const;
00175
00176     Glonass_Gnav_Ephemeris gnav_ephemeris{}; // Ephemeris information decoded
00177     Glonass_Gnav_Utc_Model gnav_utc_model{}; // UTC model information
00178     Glonass_Gnav_Almanac gnav_almanac[GLONASS_CA_NBR_SATS]{}; // Almanac information for all 24
satellites
00179
00180     double d_previous_tb{}; // Previous iode for the Glonass_Gnav_Ephemeris
object. Used to determine when new data arrives
00181     double d_previous_Na[GLONASS_CA_NBR_SATS]{}; // Previous time for almanac of the
Glonass_Gnav_Almanac object
00182
00183     uint32_t d_frame_ID{};
00184     uint32_t d_string_ID{};
00185     uint32_t i_alm_satellite_slot_number{}; // SV Orbit Slot Number
00186
00187     bool flag_CRC_test{};
00188     bool flag_update_slot_number{};
00189
00190     // Ephemeris Flags and control variables
00191     bool flag_all_ephemeris{}; // Flag indicating that all strings containing ephemeris have been
received
00192     bool flag_ephemeris_str_1{}; // Flag indicating that ephemeris 1/4 (string 1) have been received
00193     bool flag_ephemeris_str_2{}; // Flag indicating that ephemeris 2/4 (string 2) have been received
00194     bool flag_ephemeris_str_3{}; // Flag indicating that ephemeris 3/4 (string 3) have been received
00195     bool flag_ephemeris_str_4{}; // Flag indicating that ephemeris 4/4 (string 4) have been received
00196
00197     // Almanac Flags
00198     bool flag_almanac_str_6{}; // Flag indicating that almanac of string 6 have been received
00199     bool flag_almanac_str_7{}; // Flag indicating that almanac of string 7 have been received
00200     bool flag_almanac_str_8{}; // Flag indicating that almanac of string 8 have been received
00201     bool flag_almanac_str_9{}; // Flag indicating that almanac of string 9 have been received
00202     bool flag_almanac_str_10{}; // Flag indicating that almanac of string 10 have been received
00203     bool flag_almanac_str_11{}; // Flag indicating that almanac of string 11 have been received
00204     bool flag_almanac_str_12{}; // Flag indicating that almanac of string 12 have been received
00205     bool flag_almanac_str_13{}; // Flag indicating that almanac of string 13 have been received
00206     bool flag_almanac_str_14{}; // Flag indicating that almanac of string 14 have been received
00207     bool flag_almanac_str_15{}; // Flag indicating that almanac of string 15 have been received
00208
00209     // UTC and System Clocks Flags
00210     bool flag_utc_model_str_5{}; // Clock info send in string 5 of navigation data
00211
00212     bool flag_TOW_set{}; // Flag indicating when the TOW has been set
00213     bool flag_TOW_new{}; // Flag indicating when a new TOW has been computed
00214 };
00215
00216
00217 /** \} */
00218 /** \} */
00219 #endif // GNSS_SDR_GLOASS_GNAV_NAVIGATION_MESSAGE_H

```

13.775 glonass_gnav_utc_model.h File Reference

Interface of a GLONASS GNAV UTC MODEL storage.

```
#include <boost/serialization/nvp.hpp>
#include <cstdint>
```

Classes

- class [Glonass_Gnav_Utc_Model](#)

This class is a storage for the GLONASS GNAV UTC MODEL data as described in GLONASS ICD (Edition 5.1)

13.775.1 Detailed Description

Interface of a GLONASS GNAV UTC MODEL storage.

Note

Code added as part of GSoC 2017 program

Author

Damian Miralles, 2017. dmiralles2009(at)gmail.com

See also

[GLONASS ICD](#)

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Definition in file [glonass_gnav_utc_model.h](#).

13.776 glonass_gnav_utc_model.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file glonass_gnav_utc_model.h
00003  * \brief Interface of a GLONASS GNAV UTC MODEL storage
00004  * \note Code added as part of GSoC 2017 program
00005  * \author Damian Miralles, 2017. dmiralles2009(at)gmail.com
00006  * \see <a
00007         href="http://russianspacesystems.ru/wp-content/uploads/2016/08/ICD_GLONASS_eng_v5.1.pdf">GLONASS
00008         ICD</a>
00009  *
00010  * -----
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  * -----
00017  */
00018
00019
00020 #ifndef GNSS_SDR_GLONASS_GNAV_UTC_MODEL_H
00021 #define GNSS_SDR_GLONASS_GNAV_UTC_MODEL_H
00022
00023 #include <boost/serialization/nvp.hpp>
00024 #include <cstdint>
00025
00026 /** \addtogroup Core
00027  * \{ */
00028 /** \addtogroup System_Parameters
00029  * \{ */
00030
00031
00032 /*!
00033  * \brief This class is a storage for the GLONASS GNAV UTC MODEL data as described in GLONASS ICD
00034         (Edition 5.1)
00035  * \note Code added as part of GSoC 2017 program
```

```

00035  * \see <a
        href="http://russianspacesystems.ru/wp-content/uploads/2016/08/ICD_GLONASS_eng_v5.1.pdf">GLONASS
        ICD</a>
00036  */
00037  class Glonass_Gnav_Utc_Model
00038  {
00039  public:
00040      /*!
00041       * Default constructor
00042       */
00043      Glonass_Gnav_Utc_Model() = default;
00044
00045      bool valid{};
00046      // Clock Parameters
00047      double d_tau_c{};    //!< GLONASS time scale correction to UTC(SU) time. [s]
00048      double d_tau_gps{};  //!< Correction to GPS time to GLONASS time [day]
00049      double d_N_4{};      //!< Four year interval number starting from 1996 [4 year interval]
00050      double d_N_A{};      //!< Calendar day number within the four-year period beginning since the leap
        year for Almanac data [days]
00051      double d_B1{};       //!< Coefficient to determine DeltaUT1 [s]
00052      double d_B2{};       //!< Coefficient to determine DeltaUT1 [s/msd]
00053
00054      /*!
00055       * \brief Computes the Coordinated Universal Time (UTC) and
00056       * returns it in [s] (GLONASS ICD (Edition 5.1) Section 3.3.3 GLONASS Time)
00057       */
00058      double utc_time(double glonass_time_corrected) const;
00059
00060      template <class Archive>
00061      /*!
00062       * \brief Serialize is a boost standard method to be called by the boost XML
00063       * serialization. Here is used to save the almanac data on disk file.
00064       */
00065      void serialize(Archive& archive, const uint32_t version)
00066      {
00067          if (version)
00068          {
00069              archive& BOOST_SERIALIZATION_NVP(valid);
00070              archive& BOOST_SERIALIZATION_NVP(d_tau_c);
00071              archive& BOOST_SERIALIZATION_NVP(d_tau_gps);
00072              archive& BOOST_SERIALIZATION_NVP(d_N_4);
00073              archive& BOOST_SERIALIZATION_NVP(d_N_A);
00074              archive& BOOST_SERIALIZATION_NVP(d_B1);
00075              archive& BOOST_SERIALIZATION_NVP(d_B2);
00076          }
00077      };
00078  };
00079
00080
00081  /** \} */
00082  /** \} */
00083  #endif // GNSS_SDR_GLONASS_GNAV_UTC_MODEL_H

```

13.777 GLONASS_L1_L2_CA.h File Reference

Defines system parameters for GLONASS L1 C/A signal and NAV data.

```

#include "gnss_frequencies.h"
#include <stdint>
#include <map>
#include <utility>
#include <vector>

```

Macros

- #define [GLONASS_GNAV_PREAMBLE](#)
- #define [GLONASS_GNAV_PREAMBLE_SAMPLES](#)

Functions

- const std::vector< std::pair< int32_t, int32_t > > [STRING_ID](#) ({{2, 4}})
- const std::vector< std::pair< int32_t, int32_t > > [KX](#) ({{78, 8}})
- const std::vector< std::pair< int32_t, int32_t > > [P1](#) ({{8, 2}})
- const std::vector< std::pair< int32_t, int32_t > > [T_K_HR](#) ({{10, 5}})
- const std::vector< std::pair< int32_t, int32_t > > [T_K_MIN](#) ({{15, 6}})

- `const std::vector< std::pair< int32_t, int32_t > > T_K_SEC {{{21, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > X_N_DOT {{{22, 24}}}`
- `const std::vector< std::pair< int32_t, int32_t > > X_N_DOT_DOT {{{46, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > X_N {{{51, 27}}}`
- `const std::vector< std::pair< int32_t, int32_t > > B_N {{{6, 3}}}`
- `const std::vector< std::pair< int32_t, int32_t > > P2 {{{9, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > T_B {{{10, 7}}}`
- `const std::vector< std::pair< int32_t, int32_t > > Y_N_DOT {{{22, 24}}}`
- `const std::vector< std::pair< int32_t, int32_t > > Y_N_DOT_DOT {{{46, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > Y_N {{{51, 27}}}`
- `const std::vector< std::pair< int32_t, int32_t > > P3 {{{6, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > GAMMA_N {{{7, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > P {{{19, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > EPH_L_N {{{21, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > Z_N_DOT {{{22, 24}}}`
- `const std::vector< std::pair< int32_t, int32_t > > Z_N_DOT_DOT {{{46, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > Z_N {{{51, 27}}}`
- `const std::vector< std::pair< int32_t, int32_t > > TAU_N {{{6, 22}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_TAU_N {{{28, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > E_N {{{33, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > P4 {{{52, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > F_T {{{53, 4}}}`
- `const std::vector< std::pair< int32_t, int32_t > > N_T {{{60, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > N {{{71, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > M {{{76, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DAY_NUMBER_A {{{6, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > TAU_C {{{17, 32}}}`
- `const std::vector< std::pair< int32_t, int32_t > > N_4 {{{50, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > TAU_GPS {{{55, 22}}}`
- `const std::vector< std::pair< int32_t, int32_t > > ALM_L_N {{{77, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > C_N {{{6, 1}}}`
- `const std::vector< std::pair< int32_t, int32_t > > M_N_A {{{7, 2}}}`
- `const std::vector< std::pair< int32_t, int32_t > > N_A {{{9, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > TAU_N_A {{{14, 10}}}`
- `const std::vector< std::pair< int32_t, int32_t > > LAMBDA_N_A {{{24, 21}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_I_N_A {{{45, 18}}}`
- `const std::vector< std::pair< int32_t, int32_t > > EPSILON_N_A {{{63, 15}}}`
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_N_A {{{6, 16}}}`
- `const std::vector< std::pair< int32_t, int32_t > > T_LAMBDA_N_A {{{22, 21}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_T_N_A {{{43, 22}}}`
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_T_DOT_N_A {{{65, 7}}}`
- `const std::vector< std::pair< int32_t, int32_t > > H_N_A {{{72, 5}}}`
- `const std::vector< std::pair< int32_t, int32_t > > B1 {{{6, 11}}}`
- `const std::vector< std::pair< int32_t, int32_t > > B2 {{{17, 10}}}`

Variables

- `constexpr double GLONASS_F_M_A = 0.35e9`
Gravitational constant of atmosphere [m^3/s^2].
- `constexpr double GLONASS_SEMI_MAJOR_AXIS = 6378136`
Semi-major axis of Earth [m].
- `constexpr double GLONASS_FLATTENING = 1.0 / 29825784.0`
Flattening parameter.
- `constexpr double GLONASS_GRAVITY = 97803284.0`

- Equatorial acceleration of gravity [mGal].*
- constexpr double `GLONASS_GRAVITY_CORRECTION` = 0.87
- Correction to acceleration of gravity at sea-level due to Atmosphere[uGal].*
- constexpr double `GLONASS_J2` = 1082625.75e-9
- Second zonal harmonic of the geopotential.*
- constexpr double `GLONASS_J4` = -2370.89e-9
- Fourth zonal harmonic of the geopotential.*
- constexpr double `GLONASS_J6` = 6.08e-9
- Sixth zonal harmonic of the geopotential.*
- constexpr double `GLONASS_J8` = 1.40e-11
- Eighth zonal harmonic of the geopotential.*
- constexpr double `GLONASS_U0` = 62636861.4
- Normal potential at surface of common terrestrial ellipsoid [m^2/s^2].*
- constexpr double `GLONASS_C20` = -1082.63e-6
- Second zonal coefficient of spherical harmonic expansion.*
- constexpr double `GLONASS_EARTH_RADIUS` = 6378.136
- Equatorial radius of Earth [km].*
- constexpr double `GLONASS_EARTH_INCLINATION` = 0.000409148809899e3
- Mean inclination of ecliptic to equator (23 deg 26 min 33 sec) [rad].*
- constexpr double `GLONASS_TAU_0` = -0.005835151531174e3
- (-334 deg 19 min 46.40 sec) [rad];*
- constexpr double `GLONASS_TAU_1` = 0.071018041257371e3
- (4069 deg 02 min 02.52 sec) [rad];*
- constexpr double `GLONASS_MOON_Q0` = -0.001115184961435e3
- (-63 deg 53 min 43.41 sec) [rad]*
- constexpr double `GLONASS_MOON_Q1` = 8.328691103668023e3
- (477198 deg 50 min 56.79 sec) [rad]*
- constexpr double `GLONASS_MOON_OMEGA_0` = 0.004523601514852e3
- (259 deg 10 min 59.79 sec) [rad]*
- constexpr double `GLONASS_MOON_OMEGA_1` = -0.033757146246552e3
- (-1934 deg 08 min 31.23 sec) [rad]*
- constexpr double `GLONASS_MOON_GM` = 4902.835
- Lunar gravitational constant [km^3/s^2].*
- constexpr double `GLONASS_MOON_SEMI_MAJOR_AXIS` = 3.84385243e5
- Semi-major axis of lunar orbit [km].;*
- constexpr double `GLONASS_MOON_ECCENTRICITY` = 0.054900489
- Eccentricity of lunar orbit.*
- constexpr double `GLONASS_MOON_INCLINATION` = 0.000089803977407e3
- Inclination of lunar orbit to ecliptic plane (5 deg 08 min 43.4 sec) [rad].*
- constexpr double `GLONASS_SUN_OMEGA` = 0.004908229466869e3
- TODO What is this operation in the seconds with T?(281 deg 13 min 15.0 + 6189.03 x T sec) [rad].*
- constexpr double `GLONASS_SUN_Q0` = 0.006256583774423e3
- (358 deg 28 min 33.04 sec) [rad]*
- constexpr double `GLONASS_SUN_Q1` = 0e3
- TODO Why is the value greater than 60?(129596579.10 sec) [rad].*
- constexpr double `GLONASS_SUN_GM` = 0.1325263e12
- Solar gravitational constant [km^3/s^2].*
- constexpr double `GLONASS_SUN_SEMI_MAJOR_AXIS` = 1.49598e8
- Semi-major axis of solar orbit [km].;*
- constexpr double `GLONASS_SUN_ECCENTRICITY` = 0.016719
- Eccentricity of solar orbit.*

- constexpr int32_t [GLONASS_GNAV_HAMMING_CODE_BITS](#) = 8
Number of bits in hamming code sequence of GNAV message.
- constexpr int32_t [GLONASS_GNAV_DATA_SYMBOLS](#) = 1700
- constexpr double [GLONASS_LEAP_SECONDS](#) [19][7]
Record of leap seconds definition for GLOT to GPST conversion and vice versa.
- const std::map< uint32_t, int32_t > [GLONASS_PRN](#)
- const std::vector< int32_t > [GLONASS_GNAV_CRC_I_INDEX](#) {9, 10, 12, 13, 15, 17, 19, 20, 22, 24, 26, 28, 30, 32, 34, 35, 37, 39, 41, 43, 45, 47, 49, 51, 53, 55, 57, 59, 61, 63, 65, 66, 68, 70, 72, 74, 76, 78, 80, 82, 84}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_J_INDEX](#) {9, 11, 12, 14, 15, 18, 19, 21, 22, 25, 26, 29, 30, 33, 34, 36, 37, 40, 41, 44, 45, 48, 49, 52, 53, 56, 57, 60, 61, 64, 65, 67, 68, 71, 72, 75, 76, 79, 80, 83, 84}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_K_INDEX](#) {10, 11, 12, 16, 17, 18, 19, 23, 24, 25, 26, 31, 32, 33, 34, 38, 39, 40, 41, 46, 47, 48, 49, 54, 55, 56, 57, 62, 63, 64, 65, 69, 70, 71, 72, 77, 78, 79, 80, 85}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_L_INDEX](#) {13, 14, 15, 16, 17, 18, 19, 27, 28, 29, 30, 31, 32, 33, 34, 42, 43, 44, 45, 46, 47, 48, 49, 58, 59, 60, 61, 62, 63, 64, 65, 73, 74, 75, 76, 77, 78, 79, 80}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_M_INDEX](#) {20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 81, 82, 83, 84, 85}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_N_INDEX](#) {35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_P_INDEX](#) {66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85}
- const std::vector< int32_t > [GLONASS_GNAV_CRC_Q_INDEX](#) {9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85}
- const std::vector< int32_t > [GLONASS_GNAV_ECC_LOCATOR](#) {0, 0, 1, 8, 2, 9, 10, 11, 3, 12, 13, 14, 15, 16, 17, 18, 4, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 5, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 6, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84}

13.777.1 Detailed Description

Defines system parameters for GLONASS L1 C/A signal and NAV data.

Note

File renamed from GLONASS_L1_CA.h to [GLONASS_L1_L2_CA.h](#) to accommodate GLO L2 addition

Author

Damian Miralles, 2017. dmiralles2009(at)gmail.com

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 Definition in file [GLONASS_L1_L2_CA.h](#).

13.778 GLONASS_L1_L2_CA.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file GLONASS_L1_L2_CA.h
00003  * \brief Defines system parameters for GLONASS L1 C/A signal and NAV data
00004  * \note File renamed from GLONASS_L1_CA.h to GLONASS_L1_L2_CA.h to accommodate GLO L2 addition
00005  * \author Damian Miralles, 2017. dmiralles2009(at)gmail.com
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
```

```

00016 */
00017
00018
00019 #ifndef GNSS_SDR_GLO_NASS_L1_L2_CA_H
00020 #define GNSS_SDR_GLO_NASS_L1_L2_CA_H
00021
00022 #include "gnss_frequencies.h"
00023 #include <stdint>
00024 #include <map>
00025 #include <utility> // std::pair
00026 #include <vector>
00027
00028 /** \addtogroup Core
00029 * \{ */
00030 /** \addtogroup System_Parameters
00031 * \{ */
00032
00033
00034 // Physical constants
00035 constexpr double GLONASS_F_M_A = 0.35e9; //!< Gravitational constant of
    atmosphere [m^3/s^2]
00036 constexpr double GLONASS_SEMI_MAJOR_AXIS = 6378136; //!< Semi-major axis of Earth [m]
00037 constexpr double GLONASS_FLATTENING = 1.0 / 29825784.0; //!< Flattening parameter
00038 constexpr double GLONASS_GRAVITY = 97803284.0; //!< Equatorial acceleration of
    gravity [mGal]
00039 constexpr double GLONASS_GRAVITY_CORRECTION = 0.87; //!< Correction to acceleration of
    gravity at sea-level due to Atmosphere[uGal]
00040 constexpr double GLONASS_J2 = 1082625.75e-9; //!< Second zonal harmonic of the
    geopotential
00041 constexpr double GLONASS_J4 = -2370.89e-9; //!< Fourth zonal harmonic of the
    geopotential
00042 constexpr double GLONASS_J6 = 6.08e-9; //!< Sixth zonal harmonic of the
    geopotential
00043 constexpr double GLONASS_J8 = 1.40e-11; //!< Eighth zonal harmonic of the
    geopotential
00044 constexpr double GLONASS_U0 = 62636861.4; //!< Normal potential at surface of
    common terrestrial ellipsoid [m^2/s^2]
00045 constexpr double GLONASS_C20 = -1082.63e-6; //!< Second zonal coefficient of
    spherical harmonic expansion
00046 constexpr double GLONASS_EARTH_RADIUS = 6378.136; //!< Equatorial radius of Earth
    [km]
00047 constexpr double GLONASS_EARTH_INCLINATION = 0.000409148809899e3; //!< Mean inclination of ecliptic
    to equator (23 deg 26 min 33 sec) [rad]
00048
00049 constexpr double GLONASS_TAU_0 = -0.005835151531174e3; //!< (-334 deg 19 min 46.40 sec) [rad];
00050 constexpr double GLONASS_TAU_1 = 0.071018041257371e3; //!< (4069 deg 02 min 02.52 sec) [rad];
00051
00052 constexpr double GLONASS_MOON_Q0 = -0.001115184961435e3; //!< (-63 deg 53 min 43.41 sec)
    [rad]
00053 constexpr double GLONASS_MOON_Q1 = 8.328691103668023e3; //!< (477198 deg 50 min 56.79 sec)
    [rad]
00054 constexpr double GLONASS_MOON_OMEGA_0 = 0.004523601514852e3; //!< (259 deg 10 min 59.79 sec)
    [rad]
00055 constexpr double GLONASS_MOON_OMEGA_1 = -0.033757146246552e3; //!< (-1934 deg 08 min 31.23 sec)
    [rad]
00056 constexpr double GLONASS_MOON_GM = 4902.835; //!< Lunar gravitational constant
    [km^3/s^2]
00057 constexpr double GLONASS_MOON_SEMI_MAJOR_AXIS = 3.84385243e5; //!< Semi-major axis of lunar orbit
    [km];
00058 constexpr double GLONASS_MOON_ECCENTRICITY = 0.054900489; //!< Eccentricity of lunar orbit
00059 constexpr double GLONASS_MOON_INCLINATION = 0.000089803977407e3; //!< Inclination of lunar orbit to
    ecliptic plane (5 deg 08 min 43.4 sec) [rad]
00060
00061 constexpr double GLONASS_SUN_OMEGA = 0.004908229466869e3; //!< TODO What is this operation in the
    seconds with T?(281 deg 13 min 15.0 + 6189.03 x T sec) [rad]
00062 constexpr double GLONASS_SUN_Q0 = 0.006256583774423e3; //!< (358 deg 28 min 33.04 sec) [rad]
00063 constexpr double GLONASS_SUN_Q1 = 0e3; //!< TODO Why is the value greater than
    60?(129596579.10 sec) [rad]
00064 constexpr double GLONASS_SUN_GM = 0.1325263e12; //!< Solar gravitational constant
    [km^3/s^2]
00065 constexpr double GLONASS_SUN_SEMI_MAJOR_AXIS = 1.49598e8; //!< Semi-major axis of solar orbit [km];
00066 constexpr double GLONASS_SUN_ECCENTRICITY = 0.016719; //!< Eccentricity of solar orbit
00067
00068 constexpr double GLONASS_L2_CA_FREQ_HZ = FREQ2_GLO; //!< L2 [Hz]
00069 constexpr double GLONASS_L2_CA_DFREQ_HZ = DFRQ2_GLO; //!< Freq Bias for GLONASS L1 [Hz]
00070 constexpr double GLONASS_L2_CA_CODE_RATE_CPS = 0.511e6; //!< GLONASS L1 C/A code rate [chips/s]
00071 constexpr double GLONASS_L2_CA_CODE_LENGTH_CHIPS = 511.0; //!< GLONASS L1 C/A code length [chips]
00072 constexpr double GLONASS_L2_CA_CODE_PERIOD_S = 0.001; //!< GLONASS L1 C/A code period [seconds]
00073 constexpr double GLONASS_L2_CA_SYMBOL_PERIOD_S = 0.01; //!< GLONASS L1 C/A symbol period
    [seconds]
00074 constexpr double GLONASS_L2_CA_CHIP_PERIOD_S = 1.9569e-06; //!< GLONASS L1 C/A chip period [seconds]
00075 constexpr double GLONASS_L2_CA_SYMBOL_RATE_BPS = 1000.0;
00076
00077 constexpr double GLONASS_L1_CA_FREQ_HZ = FREQ1_GLO; //!< L1 [Hz]
00078 constexpr double GLONASS_L1_CA_DFREQ_HZ = DFRQ1_GLO; //!< Freq Bias for GLONASS L1 [Hz]
00079 constexpr double GLONASS_L1_CA_CODE_RATE_CPS = 0.511e6; //!< GLONASS L1 C/A code rate [chips/s]
00080 constexpr double GLONASS_L1_CA_CODE_LENGTH_CHIPS = 511.0; //!< GLONASS L1 C/A code length [chips]

```

Generated by Doxygen

```
00160         5,
00161     }, // Plane 1
00162     {
00163         4,
00164         6,
00165     }, // Plane 1
00166     {
00167         5,
00168         1,
00169     }, // Plane 1
00170     {
00171         6,
00172         -4,
00173     }, // Plane 1
00174     {
00175         7,
00176         5,
00177     }, // Plane 1
00178     {
00179         8,
00180         6,
00181     }, // Plane 1
00182     {
00183         9,
00184         -2,
00185     }, // Plane 2
00186     {
00187         10,
00188         -7,
00189     }, // Plane 2
00190     {
00191         11,
00192         0,
00193     }, // Plane 2
00194     {
00195         12,
00196         -1,
00197     }, // Plane 2
00198     {
00199         13,
00200         -2,
00201     }, // Plane 2
00202     {
00203         14,
00204         -7,
00205     }, // Plane 2
00206     {
00207         15,
00208         0,
00209     }, // Plane 2
00210     {
00211         16,
00212         -1,
00213     }, // Plane 2
00214     {
00215         17,
00216         4,
00217     }, // Plane 3
00218     {
00219         18,
00220         -3,
00221     }, // Plane 3
00222     {
00223         19,
00224         3,
00225     }, // Plane 3
00226     {
00227         20,
00228         -5,
00229     }, // Plane 3
00230     {
00231         21,
00232         4,
00233     }, // Plane 3
00234     {
00235         22,
00236         -3,
00237     }, // Plane 3
00238     {
00239         23,
00240         3,
00241     }, // Plane 3
00242     {24, 2}}; // Plane 3
00243
00244 const std::vector<int32_t> GLONASS_GNAV_CRC_I_INDEX{9, 10, 12, 13, 15, 17, 19, 20, 22, 24, 26, 28, 30,
32, 34, 35, 37, 39, 41, 43, 45, 47, 49, 51, 53, 55, 57, 59, 61, 63, 65, 66, 68, 70, 72, 74, 76, 78,
80, 82, 84};
```

```
00245 const std::vector<int32_t> GLONASS_GNAV_CRC_J_INDEX{9, 11, 12, 14, 15, 18, 19, 21, 22, 25, 26, 29, 30,
33, 34, 36, 37, 40, 41, 44, 45, 48, 49, 52, 53, 56, 57, 60, 61, 64, 65, 67, 68, 71, 72, 75, 76, 79,
80, 83, 84};
00246 const std::vector<int32_t> GLONASS_GNAV_CRC_K_INDEX{10, 11, 12, 16, 17, 18, 19, 23, 24, 25, 26, 31,
32, 33, 34, 38, 39, 40, 41, 46, 47, 48, 49, 54, 55, 56, 57, 62, 63, 64, 65, 69, 70, 71, 72, 77, 78,
79, 80, 85};
00247 const std::vector<int32_t> GLONASS_GNAV_CRC_L_INDEX{13, 14, 15, 16, 17, 18, 19, 27, 28, 29, 30, 31,
32, 33, 34, 42, 43, 44, 45, 46, 47, 48, 49, 58, 59, 60, 61, 62, 63, 64, 65, 73, 74, 75, 76, 77, 78,
79, 80};
00248 const std::vector<int32_t> GLONASS_GNAV_CRC_M_INDEX{20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31,
32, 33, 34, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 81, 82, 83, 84, 85};
00249 const std::vector<int32_t> GLONASS_GNAV_CRC_N_INDEX{35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46,
47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65};
00250 const std::vector<int32_t> GLONASS_GNAV_CRC_P_INDEX{66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77,
78, 79, 80, 81, 82, 83, 84, 85};
00251 const std::vector<int32_t> GLONASS_GNAV_CRC_Q_INDEX{9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21,
22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46,
47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71,
72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85};
00252 const std::vector<int32_t> GLONASS_GNAV_ECC_LOCATOR{0, 0, 1, 8, 2, 9, 10, 11, 3, 12, 13, 14, 15, 16,
17, 18, 4, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 5, 34, 35, 36, 37, 38, 39, 40,
41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 6, 65,
66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84};
00253
00254 // GLONASS GNAV NAVIGATION MESSAGE STRUCTURE
00255 // NAVIGATION MESSAGE FIELDS POSITIONS
00256
00257 // FRAME 1-4
00258 // COMMON FIELDS
00259 const std::vector<std::pair<int32_t, int32_t> STRING_ID>{{2, 4}};
00260 const std::vector<std::pair<int32_t, int32_t> KX>{{78, 8}};
00261 // STRING 1
00262 const std::vector<std::pair<int32_t, int32_t> P1>{{8, 2}};
00263 const std::vector<std::pair<int32_t, int32_t> T_K_HR>{{10, 5}};
00264 const std::vector<std::pair<int32_t, int32_t> T_K_MIN>{{15, 6}};
00265 const std::vector<std::pair<int32_t, int32_t> T_K_SEC>{{21, 1}};
00266 const std::vector<std::pair<int32_t, int32_t> X_N_DOT>{{22, 24}};
00267 const std::vector<std::pair<int32_t, int32_t> X_N_DOT_DOT>{{46, 5}};
00268 const std::vector<std::pair<int32_t, int32_t> X_N>{{51, 27}};
00269
00270 // STRING 2
00271 const std::vector<std::pair<int32_t, int32_t> B_N>{{6, 3}};
00272 const std::vector<std::pair<int32_t, int32_t> P2>{{9, 1}};
00273 const std::vector<std::pair<int32_t, int32_t> T_B>{{10, 7}};
00274 const std::vector<std::pair<int32_t, int32_t> Y_N_DOT>{{22, 24}};
00275 const std::vector<std::pair<int32_t, int32_t> Y_N_DOT_DOT>{{46, 5}};
00276 const std::vector<std::pair<int32_t, int32_t> Y_N>{{51, 27}};
00277
00278 // STRING 3
00279 const std::vector<std::pair<int32_t, int32_t> P3>{{6, 1}};
00280 const std::vector<std::pair<int32_t, int32_t> GAMMA_N>{{7, 11}};
00281 const std::vector<std::pair<int32_t, int32_t> P>{{19, 2}};
00282 const std::vector<std::pair<int32_t, int32_t> EPH_L_N>{{21, 1}};
00283 const std::vector<std::pair<int32_t, int32_t> Z_N_DOT>{{22, 24}};
00284 const std::vector<std::pair<int32_t, int32_t> Z_N_DOT_DOT>{{46, 5}};
00285 const std::vector<std::pair<int32_t, int32_t> Z_N>{{51, 27}};
00286
00287 // STRING 4
00288 const std::vector<std::pair<int32_t, int32_t> TAU_N>{{6, 22}};
00289 const std::vector<std::pair<int32_t, int32_t> DELTA_TAU_N>{{28, 5}};
00290 const std::vector<std::pair<int32_t, int32_t> E_N>{{33, 5}};
00291 const std::vector<std::pair<int32_t, int32_t> P4>{{52, 1}};
00292 const std::vector<std::pair<int32_t, int32_t> F_T>{{53, 4}};
00293 const std::vector<std::pair<int32_t, int32_t> N_T>{{60, 11}};
00294 const std::vector<std::pair<int32_t, int32_t> N>{{71, 5}};
00295 const std::vector<std::pair<int32_t, int32_t> M>{{76, 2}};
00296
00297 // STRING 5
00298 const std::vector<std::pair<int32_t, int32_t> DAY_NUMBER_A>{{6, 11}};
00299 const std::vector<std::pair<int32_t, int32_t> TAU_C>{{17, 32}};
00300 const std::vector<std::pair<int32_t, int32_t> N_4>{{50, 5}};
00301 const std::vector<std::pair<int32_t, int32_t> TAU_GPS>{{55, 22}};
00302 const std::vector<std::pair<int32_t, int32_t> ALM_L_N>{{77, 1}};
00303
00304 // STRING 6, 8, 10, 12, 14
00305 const std::vector<std::pair<int32_t, int32_t> C_N>{{6, 1}};
00306 const std::vector<std::pair<int32_t, int32_t> M_N_A>{{7, 2}};
00307 const std::vector<std::pair<int32_t, int32_t> N_A>{{9, 5}};
00308 const std::vector<std::pair<int32_t, int32_t> TAU_N_A>{{14, 10}};
00309 const std::vector<std::pair<int32_t, int32_t> LAMBDA_N_A>{{24, 21}};
00310 const std::vector<std::pair<int32_t, int32_t> DELTA_T_N_A>{{45, 18}};
00311 const std::vector<std::pair<int32_t, int32_t> EPSILON_N_A>{{63, 15}};
00312
00313 // STRING 7, 9, 11, 13, 15
00314 const std::vector<std::pair<int32_t, int32_t> OMEGA_N_A>{{6, 16}};
00315 const std::vector<std::pair<int32_t, int32_t> T_LAMBDA_N_A>{{22, 21}};
00316 const std::vector<std::pair<int32_t, int32_t> DELTA_T_N_A>{{43, 22}};
```



```

00317 const std::vector<std::pair<int32_t, int32_t>> DELTA_T_DOT_N_A({{65, 7}});
00318 const std::vector<std::pair<int32_t, int32_t>> H_N_A({{72, 5}});
00319
00320 // STRING 14 FRAME 5
00321 const std::vector<std::pair<int32_t, int32_t>> B1({{6, 11}});
00322 const std::vector<std::pair<int32_t, int32_t>> B2({{17, 10}});
00323
00324
00325 /** \} */
00326 /** \} */
00327 #endif // GNSS_SDR_GLO_NASS_L1_L2_CA_H

```

13.779 gnss_almanac.h File Reference

Base class for GNSS almanac storage.

```

#include <array>
#include <cstdint>

```

Classes

- class [Gnss_Almanac](#)

Base class for GNSS almanac storage.

13.779.1 Detailed Description

Base class for GNSS almanac storage.

Author

Carles Fernandez, 2021. cfernandez(at)cttc.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [gnss_almanac.h](#).

13.780 gnss_almanac.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002 * \file gnss_almanac.h
00003 * \brief Base class for GNSS almanac storage
00004 * \author Carles Fernandez, 2021. cfernandez(at)cttc.es
00005 *
00006 * -----
00007 *
00008 * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009 * This file is part of GNSS-SDR.
00010 *
00011 * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00012 * SPDX-License-Identifier: GPL-3.0-or-later
00013 *
00014 * -----
00015 */
00016
00017
00018 #ifndef GNSS_SDR_GNSS_ALMANAC_H
00019 #define GNSS_SDR_GNSS_ALMANAC_H
00020
00021 #include <array>
00022 #include <cstdint>
00023
00024 /** \addtogroup Core
00025 * \{ */
00026 /** \addtogroup System_Parameters
00027 * \{ */
00028
00029
00030 /*!
00031 * \brief Base class for GNSS almanac storage
00032 */
00033 class Gnss_Almanac
00034 {

```



```

00035 public:
00036     /*!
00037      * Default constructor
00038      */
00039     Gnss_Almanac() = default;
00040
00041     /*!
00042      * \brief Computes prediction of the Doppler shift for a given time and receiver's position and
00043      * velocity.
00044      * 
$$f_d = - \mathbf{v} \cdot \frac{\mathbf{x}^T}{\|\mathbf{x}\|} \frac{f_L}{c}$$

00045      * where:
00046      * 
$$\mathbf{v} = \mathbf{v}_{sat} - \mathbf{v}_{rx}$$

00047      * 
$$\mathbf{x} = \mathbf{x}_{sat} - \mathbf{x}_{rx}$$

00048      * 
$$\|\mathbf{x}\| = \sqrt{\mathbf{x} \cdot \mathbf{x}}$$

00049      * \param[in] rx_time_s Time of Week in seconds
00050      * \param[in] lat Receiver's latitude in degrees
00051      * \param[in] lon Receiver's longitude in degrees
00052      * \param[in] h Receiver's height in meters
00053      * \param[in] ve Receiver's velocity in the East direction [m/s]
00054      * \param[in] vn Receiver's velocity in the North direction [m/s]
00055      * \param[in] vu Receiver's velocity in the Up direction [m/s]
00056      * \param[in] band Signal band for which the Doppler will be computed
00057      * (1: L1 C/A, E1B, BI1; 2: L2C, BI2; 3: BI3; 5: L5/E5a; 6: E6B; 7: E5b; 8:
00058      * E5a+E5b)
00059      */
00060     double predicted_doppler(double rx_time_s,
00061                             double lat,
00062                             double lon,
00063                             double h,
00064                             double ve,
00065                             double vn,
00066                             double vu,
00067                             int band) const;
00068
00069     /*!
00070      * \brief Computes satellite Position and Velocity, in ECEF, for a given time (expressed in
00071      * seconds of week)
00072      */
00073     void satellitePosVelComputation(double transmitTime, std::array<double, 7>& pos_vel_dtr) const;
00074
00075     uint32_t PRN{}; //!< SV PRN NUMBER
00076     double delta_i{}; //!< Inclination Angle at Reference Time (relative to i_0 = 0.30 semi-circles)
00077     int32_t toa{}; //!< Almanac data reference time of week [s]
00078     int32_t WNa{}; //!< Almanac week number
00079     double M_0{}; //!< Mean Anomaly at Reference Time [semi-circles]
00080     double ecc{}; //!< Eccentricity [dimensionless]
00081     double sqrtA{}; //!< Square Root of the Semi-Major Axis [sqrt(m)]
00082     double OMEGA_0{}; //!< Longitude of Ascending Node of Orbit Plane at Weekly Epoch [semi-circles]
00083     double omega{}; //!< Argument of Perigee [semi-circles]
00084     double OMEGAdot{}; //!< Rate of Right Ascension [semi-circles/s]
00085     double af0{}; //!< Coefficient 0 of code phase offset model [s]
00086     double af1{}; //!< Coefficient 1 of code phase offset model [s/s]
00087
00088 protected:
00089     char System{}; //!< Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou
00090 private:
00091     double check_t(double time) const;
00092 };
00093
00094 /** \} */
00095 /** \} */
00096 #endif // GNSS_SDR_GNSS_ALMANAC_H

```

13.781 gnss_ephemeris.h File Reference

Base class for GNSS Ephemeris.

```
#include <array>
```

```
#include <cstdint>
```

Classes

- class [Gnss_Ephemeris](#)

Base class for GNSS ephemeris storage.

13.781.1 Detailed Description

Base class for GNSS Ephemeris.

Author

Carles Fernandez, 2021. cfernandez(at)cttc.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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Definition in file [gnss_ephemeris.h](#).

13.782 gnss_ephemeris.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gnss_ephemeris.h
00003  * \brief Base class for GNSS Ephemeris
00004  * \author Carles Fernandez, 2021. cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GNSS_EPHEMERIS_H
00020 #define GNSS_SDR_GNSS_EPHEMERIS_H
00021
00022 #include <array>
00023 #include <cstdint>
00024
00025 /*!
00026 * \brief Base class for GNSS ephemeris storage
00027 */
00028 class Gnss_Ephemeris
00029 {
00030 public:
00031     Gnss_Ephemeris() = default;
00032
00033     /*!
00034     * \brief Sets (\a satClkDrift) and (\a dtr), and returns the clock drift in
00035     * seconds according to the User Algorithm for SV Clock Correction
00036     * (IS-GPS-200M, 20.3.3.3.1, and Galileo OS SIS ICD, 5.1.4).
00037     */
00038     double sv_clock_drift(double transmitTime);
00039
00040     /*!
00041     * \brief Computes prediction of the Doppler shift for a given time and receiver's position and
00042     * velocity.
00043     * \f[
00044     * f_{d} = - \mathbf{v} \cdot \frac{\mathbf{x}^T}{|\mathbf{x}|} \frac{f_L}{c}
00045     * \f]
00046     * where:
00047     * \f[
00048     * \mathbf{v} = \mathbf{v}_{sat} - \mathbf{v}_{rx}
00049     * \f]
00050     * \f[
00051     * \mathbf{x} = \mathbf{x}_{sat} - \mathbf{x}_{rx}
00052     * \f]
00053     * \f[
00054     * |\mathbf{x}| = \sqrt{\mathbf{x} \cdot \mathbf{x}}
00055     * \f]
00056     * @param[in] rx_time_s Time of Week in seconds
00057     * @param[in] lat Receiver's latitude in degrees
00058     * @param[in] lon Receiver's longitude in degrees

```

```

00059      * @param[in] h Receiver's height in meters
00060      * @param[in] ve Receiver's velocity in the East direction [m/s]
00061      * @param[in] vn Receiver's velocity in the North direction [m/s]
00062      * @param[in] vu Receiver's velocity in the Up direction [m/s]
00063      * @param[in] band Signal band for which the Doppler will be computed
00064      * (1: L1 C/A, E1B, BI1; 2: L2C, BI2; 3: BI3; 5: L5/E5a; 6: E6B; 7: E5b; 8:
E5a+E5b)
00065      */
00066      double predicted_doppler(double rx_time_s, double lat, double lon, double h, double ve, double vn,
double vu, int band) const;
00067
00068      void satellitePosition(double transmitTime); //!< Computes the ECEF SV coordinates and ECEF
velocity
00069
00070      uint32_t PRN{}; //!< SV ID
00071      double M_0{}; //!< Mean anomaly at reference time [rad]
00072      double delta_n{}; //!< Mean motion difference from computed value [rad/sec]
00073      double ecc{}; //!< Eccentricity
00074      double sqrtA{}; //!< Square root of the semi-major axis [meters^1/2]
00075      double OMEGA_0{}; //!< Longitude of ascending node of orbital plane at weekly epoch [rad]
00076      double i_0{}; //!< Inclination angle at reference time [rad]
00077      double omega{}; //!< Argument of perigee [rad]
00078      double OMEGAdot{}; //!< Rate of right ascension [rad/sec]
00079      double idot{}; //!< Rate of inclination angle [rad/sec]
00080      double Cuc{}; //!< Amplitude of the cosine harmonic correction term to the argument of
latitude [rad]
00081      double Cus{}; //!< Amplitude of the sine harmonic correction term to the argument of
latitude [rad]
00082      double Crc{}; //!< Amplitude of the cosine harmonic correction term to the orbit radius
[meters]
00083      double Crs{}; //!< Amplitude of the sine harmonic correction term to the orbit radius
[meters]
00084      double Cic{}; //!< Amplitude of the cosine harmonic correction term to the angle of
inclination [rad]
00085      double Cis{}; //!< Amplitude of the sine harmonic correction term to the angle of
inclination [rad]
00086      int32_t toe{}; //!< Ephemeris reference time [s]
00087
00088      // Clock correction parameters
00089      int32_t toc{}; //!< Clock correction data reference Time of Week [sec]
00090      double af0{}; //!< SV clock bias correction coefficient [s]
00091      double af1{}; //!< SV clock drift correction coefficient [s/s]
00092      double af2{}; //!< SV clock drift rate correction coefficient [s/s^2]
00093
00094      double satClkDrift{}; //!< SV clock drift
00095      double dtr{}; //!< Relativistic clock correction term
00096
00097      // Time
00098      int32_t WN{}; //!< Week number
00099      int32_t tow{}; //!< Time of Week
00100
00101      // satellite positions
00102      double satpos_X{}; //!< Earth-fixed coordinate x of the satellite [m]. Intersection of the IERS
Reference Meridian (IRM) and the plane passing through the origin and normal to the Z-axis.
00103      double satpos_Y{}; //!< Earth-fixed coordinate y of the satellite [m]. Completes a right-handed,
Earth-Centered, Earth-Fixed orthogonal coordinate system.
00104      double satpos_Z{}; //!< Earth-fixed coordinate z of the satellite [m]. The direction of the IERS
(International Earth Rotation and Reference Systems Service) Reference Pole (IRP).
00105
00106      // Satellite velocity
00107      double satvel_X{}; //!< Earth-fixed velocity coordinate x of the satellite [m]
00108      double satvel_Y{}; //!< Earth-fixed velocity coordinate y of the satellite [m]
00109      double satvel_Z{}; //!< Earth-fixed velocity coordinate z of the satellite [m]
00110
00111      protected:
00112      char System{}; //!< Character ID of the GNSS system. 'G': GPS. 'E': Galileo. 'C': BeiDou
00113
00114      private:
00115      void satellitePosVelComputation(double transmitTime, std::array<double, 7>& pos_vel_dtr) const;
00116      double check_t(double time) const;
00117      double sv_clock_relativistic_term(double transmitTime) const;
00118  };
00119
00120 #endif // GNSS_SDR_GNSS_EPHEMERIS_H

```

13.783 gnss_frequencies.h File Reference

GNSS Frequencies.

```
#include <string>
#include <unordered_map>
```

Variables

- constexpr double [FREQ1](#) = 1.57542e9
L1/E1 frequency (Hz)
- constexpr double [FREQ2](#) = 1.22760e9
L2 frequency (Hz)
- constexpr double [FREQ5](#) = 1.17645e9
L5/E5a frequency (Hz)
- constexpr double [FREQ6](#) = 1.27875e9
E6/LEX frequency (Hz)
- constexpr double [FREQ7](#) = 1.20714e9
E5b frequency (Hz)
- constexpr double [FREQ8](#) = 1.191795e9
E5a+b frequency (Hz)
- constexpr double [FREQ9](#) = 2.492028e9
S frequency (Hz)
- constexpr double [FREQ1_GLO](#) = 1.60200e9
GLONASS G1 base frequency (Hz)
- constexpr double [DFRQ1_GLO](#) = 0.56250e6
GLONASS G1 bias frequency (Hz/n)
- constexpr double [FREQ2_GLO](#) = 1.24600e9
GLONASS G2 base frequency (Hz)
- constexpr double [DFRQ2_GLO](#) = 0.43750e6
GLONASS G2 bias frequency (Hz/n)
- constexpr double [FREQ3_GLO](#) = 1.202025e9
GLONASS G3 frequency (Hz)
- constexpr double [FREQ1_BDS](#) = 1.561098e9
BeiDou B1 frequency (Hz)
- constexpr double [FREQ2_BDS](#) = 1.20714e9
BeiDou B2 frequency (Hz)
- constexpr double [FREQ3_BDS](#) = 1.26852e9
BeiDou B3 frequency (Hz)
- const std::unordered_map< std::string, double > [SIGNAL_FREQ_MAP](#)

13.783.1 Detailed Description

GNSS Frequencies.

Author

Carles Fernandez, 2017. cfernandez(at)cttc.es

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Definition in file [gnss_frequencies.h](#).

13.784 gnss_frequencies.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gnss_frequencies.h
00003  * \brief GNSS Frequencies
00004  * \author Carles Fernandez, 2017. cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
```

```

00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GNSS_FREQUENCIES_H
00020 #define GNSS_SDR_GNSS_FREQUENCIES_H
00021
00022 #include <string>
00023 #include <unordered_map>
00024
00025 /** \addtogroup Core
00026  * \{ */
00027 /** \addtogroup System_Parameters
00028  * \{ */
00029
00030
00031 constexpr double FREQ1 = 1.57542e9;      //!< L1/E1 frequency (Hz)
00032 constexpr double FREQ2 = 1.22760e9;      //!< L2 frequency (Hz)
00033 constexpr double FREQ5 = 1.17645e9;      //!< L5/E5a frequency (Hz)
00034 constexpr double FREQ6 = 1.27875e9;      //!< E6/LEX frequency (Hz)
00035 constexpr double FREQ7 = 1.20714e9;      //!< E5b frequency (Hz)
00036 constexpr double FREQ8 = 1.191795e9;     //!< E5a+b frequency (Hz)
00037 constexpr double FREQ9 = 2.492028e9;     //!< S frequency (Hz)
00038 constexpr double FREQ1_GLO = 1.60200e9;  //!< GLONASS G1 base frequency (Hz)
00039 constexpr double DFRQ1_GLO = 0.56250e6;  //!< GLONASS G1 bias frequency (Hz/n)
00040 constexpr double FREQ2_GLO = 1.24600e9;  //!< GLONASS G2 base frequency (Hz)
00041 constexpr double DFRQ2_GLO = 0.43750e6;  //!< GLONASS G2 bias frequency (Hz/n)
00042 constexpr double FREQ3_GLO = 1.202025e9; //!< GLONASS G3 frequency (Hz)
00043 constexpr double FREQ1_BDS = 1.561098e9; //!< BeiDou B1 frequency (Hz)
00044 constexpr double FREQ2_BDS = 1.20714e9;  //!< BeiDou B2 frequency (Hz)
00045 constexpr double FREQ3_BDS = 1.26852e9;  //!< BeiDou B3 frequency (Hz)
00046
00047 const std::unordered_map<std::string, double> SIGNAL_FREQ_MAP = {
00048     {"1C", FREQ1},
00049     {"2S", FREQ2},
00050     {"L5", FREQ5},
00051     {"1B", FREQ1},
00052     {"5X", FREQ5},
00053     {"E6", FREQ6},
00054     {"7X", FREQ7},
00055     {"1G", FREQ1_GLO},
00056     {"2G", FREQ2_GLO},
00057     {"B1", FREQ1_BDS},
00058     {"B2", FREQ2_BDS},
00059     {"B3", FREQ3_BDS},
00060     {"J1", FREQ1},
00061     {"J5", FREQ5},
00062 };
00063
00064
00065 /** \} */
00066 /** \} */
00067 #endif // GNSS_SDR_GNSS_FREQUENCIES_H

```

13.785 gnss_obs_codes.h File Reference

GNSS Observable codes.

```
#include <cstdint>
```

Variables

- constexpr uint32_t **CODE_NONE** = 0
obs code: none or unknown
- constexpr uint32_t **CODE_L1C** = 1
obs code: L1C/A, G1C/A, E1C (GPS, GLO, GAL, QZS, SBS)
- constexpr uint32_t **CODE_L1P** = 2
obs code: L1P, G1P (GPS, GLO)
- constexpr uint32_t **CODE_L1W** = 3
obs code: L1 Z-track (GPS)
- constexpr uint32_t **CODE_L1Y** = 4

- obs code: L1Y (GPS)*
- constexpr uint32_t [CODE_L1M](#) = 5
 - obs code: L1M (GPS)*
- constexpr uint32_t [CODE_L1N](#) = 6
 - obs code: L1codeless (GPS)*
- constexpr uint32_t [CODE_L1S](#) = 7
 - obs code: L1C(D) (GPS,QZS)*
- constexpr uint32_t [CODE_L1L](#) = 8
 - obs code: L1C(P) (GPS,QZS)*
- constexpr uint32_t [CODE_L1E](#) = 9
 - (not used)*
- constexpr uint32_t [CODE_L1A](#) = 10
 - obs code: E1A (GAL)*
- constexpr uint32_t [CODE_L1B](#) = 11
 - obs code: E1B (GAL)*
- constexpr uint32_t [CODE_L1X](#) = 12
 - obs code: E1B+C,L1C(D+P) (GAL,QZS)*
- constexpr uint32_t [CODE_L1Z](#) = 13
 - obs code: E1A+B+C,L1SAIF (GAL,QZS)*
- constexpr uint32_t [CODE_L2C](#) = 14
 - obs code: L2C/A,G1C/A (GPS,GLO)*
- constexpr uint32_t [CODE_L2D](#) = 15
 - obs code: L2 L1C/A-(P2-P1) (GPS)*
- constexpr uint32_t [CODE_L2S](#) = 16
 - obs code: L2C(M) (GPS,QZS)*
- constexpr uint32_t [CODE_L2L](#) = 17
 - obs code: L2C(L) (GPS,QZS)*
- constexpr uint32_t [CODE_L2X](#) = 18
 - obs code: L2C(M+L),B1I+Q (GPS,QZS,BDS)*
- constexpr uint32_t [CODE_L2P](#) = 19
 - obs code: L2P,G2P (GPS,GLO)*
- constexpr uint32_t [CODE_L2W](#) = 20
 - obs code: L2 Z-track (GPS)*
- constexpr uint32_t [CODE_L2Y](#) = 21
 - obs code: L2Y (GPS)*
- constexpr uint32_t [CODE_L2M](#) = 22
 - obs code: L2M (GPS)*
- constexpr uint32_t [CODE_L2N](#) = 23
 - obs code: L2codeless (GPS)*
- constexpr uint32_t [CODE_L5I](#) = 24
 - obs code: L5/E5aI (GPS,GAL,QZS,SBS)*
- constexpr uint32_t [CODE_L5Q](#) = 25
 - obs code: L5/E5aQ (GPS,GAL,QZS,SBS)*
- constexpr uint32_t [CODE_L5X](#) = 26
 - obs code: L5/E5aI+Q/L5B+C (GPS,GAL,QZS,IRN,SBS)*
- constexpr uint32_t [CODE_L7I](#) = 27
 - obs code: E5bI,B2I (GAL,BDS)*
- constexpr uint32_t [CODE_L7Q](#) = 28
 - obs code: E5bQ,B2Q (GAL,BDS)*
- constexpr uint32_t [CODE_L7X](#) = 29
 - obs code: E5bI+Q,B2I+Q (GAL,BDS)*

- constexpr uint32_t [CODE_L6A](#) = 30
obs code: E6A (GAL)
- constexpr uint32_t [CODE_L6B](#) = 31
obs code: E6B (GAL)
- constexpr uint32_t [CODE_L6C](#) = 32
obs code: E6C (GAL)
- constexpr uint32_t [CODE_L6X](#) = 33
obs code: E6B+C, LEXS+L, B3I+Q (GAL, QZS, BDS)
- constexpr uint32_t [CODE_L6Z](#) = 34
obs code: E6A+B+C (GAL)
- constexpr uint32_t [CODE_L6S](#) = 35
obs code: LEXS (QZS)
- constexpr uint32_t [CODE_L6L](#) = 36
obs code: LEXL (QZS)
- constexpr uint32_t [CODE_L8I](#) = 37
obs code: E5(a+b)I (GAL)
- constexpr uint32_t [CODE_L8Q](#) = 38
obs code: E5(a+b)Q (GAL)
- constexpr uint32_t [CODE_L8X](#) = 39
obs code: E5(a+b)I+Q (GAL)
- constexpr uint32_t [CODE_L2I](#) = 40
obs code: B1I (BDS)
- constexpr uint32_t [CODE_L2Q](#) = 41
obs code: B1Q (BDS)
- constexpr uint32_t [CODE_L6I](#) = 42
obs code: B3I (BDS)
- constexpr uint32_t [CODE_L6Q](#) = 43
obs code: B3Q (BDS)
- constexpr uint32_t [CODE_L3I](#) = 44
obs code: G3I (GLO)
- constexpr uint32_t [CODE_L3Q](#) = 45
obs code: G3Q (GLO)
- constexpr uint32_t [CODE_L3X](#) = 46
obs code: G3I+Q (GLO)
- constexpr uint32_t [CODE_L1I](#) = 47
obs code: B1I (BDS)
- constexpr uint32_t [CODE_L1Q](#) = 48
obs code: B1Q (BDS)
- constexpr uint32_t [CODE_L5A](#) = 49
obs code: L5A SPS (IRN)
- constexpr uint32_t [CODE_L5B](#) = 50
obs code: L5B RS(D) (IRN)
- constexpr uint32_t [CODE_L5C](#) = 51
obs code: L5C RS(P) (IRN)
- constexpr uint32_t [CODE_L9A](#) = 52
obs code: SA SPS (IRN)
- constexpr uint32_t [CODE_L9B](#) = 53
obs code: SB RS(D) (IRN)
- constexpr uint32_t [CODE_L9C](#) = 54
obs code: SC RS(P) (IRN)
- constexpr uint32_t [CODE_L9X](#) = 55
obs code: SB+C (IRN)
- constexpr int32_t [MAXCODE](#) = 55
max number of obs code

13.785.1 Detailed Description

GNSS Observable codes.

Author

Carles Fernandez, 2017. cfernandez(at)cttc.es

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 Definition in file [gnss_obs_codes.h](#).

13.786 gnss_obs_codes.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gnss_obs_codes.h
00003  * \brief GNSS Observable codes
00004  * \author Carles Fernandez, 2017. cfernandez(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GNSS_OBS_CODES_H
00020 #define GNSS_SDR_GNSS_OBS_CODES_H
00021
00022 #include <stdint>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup System_Parameters
00027  * \{ */
00028
00029
00030 constexpr uint32_t CODE_NONE = 0; //!< obs code: none or unknown
00031 constexpr uint32_t CODE_L1C = 1; //!< obs code: L1C/A, G1C/A, E1C (GPS, GLO, GAL, QZS, SBS)
00032 constexpr uint32_t CODE_L1P = 2; //!< obs code: L1P, G1P (GPS, GLO)
00033 constexpr uint32_t CODE_L1W = 3; //!< obs code: L1 Z-track (GPS)
00034 constexpr uint32_t CODE_L1Y = 4; //!< obs code: L1Y (GPS)
00035 constexpr uint32_t CODE_L1M = 5; //!< obs code: L1M (GPS)
00036 constexpr uint32_t CODE_L1N = 6; //!< obs code: L1codeless (GPS)
00037 constexpr uint32_t CODE_L1S = 7; //!< obs code: L1C(D) (GPS, QZS)
00038 constexpr uint32_t CODE_L1L = 8; //!< obs code: L1C(P) (GPS, QZS)
00039 constexpr uint32_t CODE_L1E = 9; //!< (not used)
00040 constexpr uint32_t CODE_L1A = 10; //!< obs code: E1A (GAL)
00041 constexpr uint32_t CODE_L1B = 11; //!< obs code: E1B (GAL)
00042 constexpr uint32_t CODE_L1X = 12; //!< obs code: E1B+C, L1C(D+P) (GAL, QZS)
00043 constexpr uint32_t CODE_L1Z = 13; //!< obs code: E1A+B+C, L1SAIF (GAL, QZS)
00044 constexpr uint32_t CODE_L2C = 14; //!< obs code: L2C/A, G1C/A (GPS, GLO)
00045 constexpr uint32_t CODE_L2D = 15; //!< obs code: L2 L1C/A- (P2-P1) (GPS)
00046 constexpr uint32_t CODE_L2S = 16; //!< obs code: L2C(M) (GPS, QZS)
00047 constexpr uint32_t CODE_L2L = 17; //!< obs code: L2C(L) (GPS, QZS)
00048 constexpr uint32_t CODE_L2X = 18; //!< obs code: L2C(M+L), B1I+Q (GPS, QZS, BDS)
00049 constexpr uint32_t CODE_L2P = 19; //!< obs code: L2P, G2P (GPS, GLO)
00050 constexpr uint32_t CODE_L2W = 20; //!< obs code: L2 Z-track (GPS)
00051 constexpr uint32_t CODE_L2Y = 21; //!< obs code: L2Y (GPS)
00052 constexpr uint32_t CODE_L2M = 22; //!< obs code: L2M (GPS)
00053 constexpr uint32_t CODE_L2N = 23; //!< obs code: L2codeless (GPS)
00054 constexpr uint32_t CODE_L5I = 24; //!< obs code: L5/E5aI (GPS, GAL, QZS, SBS)
00055 constexpr uint32_t CODE_L5Q = 25; //!< obs code: L5/E5aQ (GPS, GAL, QZS, SBS)
00056 constexpr uint32_t CODE_L5X = 26; //!< obs code: L5/E5aI+Q/L5B+C (GPS, GAL, QZS, IRN, SBS)
00057 constexpr uint32_t CODE_L7I = 27; //!< obs code: E5bI, B2I (GAL, BDS)
00058 constexpr uint32_t CODE_L7Q = 28; //!< obs code: E5bQ, B2Q (GAL, BDS)
00059 constexpr uint32_t CODE_L7X = 29; //!< obs code: E5bI+Q, B2I+Q (GAL, BDS)
00060 constexpr uint32_t CODE_L6A = 30; //!< obs code: E6A (GAL)
00061 constexpr uint32_t CODE_L6B = 31; //!< obs code: E6B (GAL)
00062 constexpr uint32_t CODE_L6C = 32; //!< obs code: E6C (GAL)
00063 constexpr uint32_t CODE_L6X = 33; //!< obs code: E6B+C, LEXS+L, B3I+Q (GAL, QZS, BDS)
00064 constexpr uint32_t CODE_L6Z = 34; //!< obs code: E6A+B+C (GAL)
00065 constexpr uint32_t CODE_L6S = 35; //!< obs code: LEXS (QZS)
00066 constexpr uint32_t CODE_L6L = 36; //!< obs code: LEXL (QZS)
00067 constexpr uint32_t CODE_L8I = 37; //!< obs code: E5 (a+b) I (GAL)
```



```

00068 constexpr uint32_t CODE_L8Q = 38; //!< obs code: E5 (a+b)Q (GAL)
00069 constexpr uint32_t CODE_L8X = 39; //!< obs code: E5 (a+b) I+Q (GAL)
00070 constexpr uint32_t CODE_L2I = 40; //!< obs code: B1I (BDS)
00071 constexpr uint32_t CODE_L2Q = 41; //!< obs code: B1Q (BDS)
00072 constexpr uint32_t CODE_L6I = 42; //!< obs code: B3I (BDS)
00073 constexpr uint32_t CODE_L6Q = 43; //!< obs code: B3Q (BDS)
00074 constexpr uint32_t CODE_L3I = 44; //!< obs code: G3I (GLO)
00075 constexpr uint32_t CODE_L3Q = 45; //!< obs code: G3Q (GLO)
00076 constexpr uint32_t CODE_L3X = 46; //!< obs code: G3I+Q (GLO)
00077 constexpr uint32_t CODE_L1I = 47; //!< obs code: B1I (BDS)
00078 constexpr uint32_t CODE_L1Q = 48; //!< obs code: B1Q (BDS)
00079 constexpr uint32_t CODE_L5A = 49; //!< obs code: L5A SPS (IRN)
00080 constexpr uint32_t CODE_L5B = 50; //!< obs code: L5B RS(D) (IRN)
00081 constexpr uint32_t CODE_L5C = 51; //!< obs code: L5C RS(P) (IRN)
00082 constexpr uint32_t CODE_L9A = 52; //!< obs code: SA SPS (IRN)
00083 constexpr uint32_t CODE_L9B = 53; //!< obs code: SB RS(D) (IRN)
00084 constexpr uint32_t CODE_L9C = 54; //!< obs code: SC RS(P) (IRN)
00085 constexpr uint32_t CODE_L9X = 55; //!< obs code: SB+C (IRN)
00086 constexpr int32_t MAXCODE = 55; //!< max number of obs code
00087
00088
00089 /** \} */
00090 /** \} */
00091 #endif // GNSS_SDR_GNSS_OBS_CODES_H

```

13.787 gnss_satellite.h File Reference

Interface of the [Gnss_Satellite](#) class.

```

#include <stdint>
#include <map>
#include <ostream>
#include <set>
#include <string>

```

Classes

- class [Gnss_Satellite](#)

This class represents a GNSS satellite.

13.787.1 Detailed Description

Interface of the [Gnss_Satellite](#) class.

Author

Carles Fernandez-Prades, 2012. cfernandez(at)cttc.es

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Definition in file [gnss_satellite.h](#).

13.788 gnss_satellite.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gnss_satellite.h
00003  * \brief Interface of the Gnss_Satellite class
00004  * \author Carles Fernandez-Prades, 2012. cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016

```

```

00017
00018 #ifndef GNSS_SDR_GNSS_SATELLITE_H
00019 #define GNSS_SDR_GNSS_SATELLITE_H
00020
00021 #include <stdint>
00022 #include <map>
00023 #include <ostream>
00024 #include <set>
00025 #include <string>
00026
00027 /** \addtogroup Core
00028  * \{ */
00029 /** \addtogroup System_Parameters
00030  * \{ */
00031
00032
00033 /*!
00034  * \brief This class represents a GNSS satellite.
00035  *
00036  * It contains information about the space vehicles currently operational
00037  * of GPS, Glonass, SBAS and Galileo constellations.
00038  */
00039 class Gnss_Satellite
00040 {
00041 public:
00042     Gnss_Satellite() = default;                //!< Default Constructor.
00043     Gnss_Satellite(const std::string& system_, uint32_t PRN_);    //!< Concrete GNSS satellite
00044     Constructor.
00045     ~Gnss_Satellite() = default;                //!< Default Destructor.
00046
00047     Gnss_Satellite(const Gnss_Satellite& other) noexcept;    //!< Copy constructor
00048     Gnss_Satellite& operator=(const Gnss_Satellite&) noexcept;    //!< Copy assignment operator
00049     Gnss_Satellite(Gnss_Satellite& other) noexcept;    //!< Move constructor
00050     Gnss_Satellite& operator=(Gnss_Satellite& other) noexcept;    //!< Move assignment operator
00051
00052     friend bool operator==(const Gnss_Satellite& /*sat1*/, const Gnss_Satellite& /*sat2*/);    //!<
00053     operator== for comparison
00054     friend std::ostream& operator<<(std::ostream& /*out*/, const Gnss_Satellite& /*sat*/);    //!<
00055     operator<< for pretty printing
00056
00057     void update_PRN(uint32_t PRN);                //!< Updates the PRN Number
00058     when information is decoded, only applies to GLONASS GNAV messages
00059     uint32_t get_PRN() const;                //!< Gets satellite's PRN
00060     int32_t get_rf_link() const;                //!< Gets the satellite's rf
00061     link
00062     std::string get_system() const;                //!< Gets the satellite system
00063     {"GPS", "Glonass", "SBAS", "Galileo", "Beidou", "QZSS"}
00064     std::string get_system_short() const;                //!< Gets the satellite system
00065     {"G", "R", "SBAS", "E", "C", "J"}
00066     std::string get_block() const;                //!< Gets the satellite block.
00067     If GPS, returns {"IIA", "IIR", "IIR-M", "IIF"}
00068     std::string what_block(const std::string& system_, uint32_t PRN_);    //!< Gets the block of a given
00069     satellite
00070 private:
00071     const std::set<std::string> system_set = {"GPS", "Glonass", "SBAS", "Galileo", "Beidou", "QZSS"};
00072     const std::map<std::string, std::string> satelliteSystem = {{"GPS", "G"}, {"Glonass", "R"},
00073     {"SBAS", "S"}, {"Galileo", "E"}, {"Beidou", "C"}, {"QZSS", "J"}};
00074     void set_system(const std::string& system);    // Sets the satellite system {"GPS", "Glonass",
00075     "SBAS", "Galileo", "Beidou", "QZSS"}.
00076     void set_PRN(uint32_t PRN);                // Sets satellite's PRN
00077     void set_block(const std::string& system_, uint32_t PRN_);
00078     void reset();
00079     void set_rf_link(int32_t rf_link_);
00080     std::string system{};
00081     std::string block{};
00082     uint32_t PRN{};
00083     int32_t rf_link{};
00084 };
00085
00086 /** \} */
00087 /** \} */
00088 #endif // GNSS_SDR_GNSS_SATELLITE_H

```

13.789 gnss_signal.h File Reference

Implementation of the [Gnss_Signal](#) class.

```

#include "gnss_satellite.h"
#include <ostream>
#include <string>

```

Classes

- class [Gnss_Signal](#)

This class represents a GNSS signal.

13.789.1 Detailed Description

Implementation of the [Gnss_Signal](#) class.

Author

Luis Esteve, 2012. luis(at)epsilon-formacion.com Javier Arribas, 2012. jarribas(at)cttc.es

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Definition in file [gnss_signal.h](#).

13.790 gnss_signal.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gnss_signal.h
00003  * \brief Implementation of the Gnss_Signal class
00004  * \author
00005  * Luis Esteve, 2012. luis(at)epsilon-formacion.com
00006  * Javier Arribas, 2012. jarribas(at)cttc.es
00007  *
00008  * -----
00009  *
00010  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00011  * This file is part of GNSS-SDR.
00012  *
00013  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00014  * SPDX-License-Identifier: GPL-3.0-or-later
00015  *
00016  * -----
00017  */
00018
00019 #ifndef GNSS_SDR_GNSS_SIGNAL_H
00020 #define GNSS_SDR_GNSS_SIGNAL_H
00021
00022 #include "gnss_satellite.h"
00023 #include <ostream>
00024 #include <string>
00025
00026 /** \addtogroup Core
00027  * \{ */
00028 /** \addtogroup System_Parameters
00029  * \{ */
00030
00031
00032 /*!
00033  * \brief This class represents a GNSS signal.
00034  *
00035  * Encapsulates a specific GNSS signal (e.g., GPS L1 C/A, Galileo E1B) and its
00036  * associated satellite.
00037  */
00038 class Gnss_Signal
00039 {
00040 public:
00041     Gnss_Signal() = default;
00042     explicit Gnss_Signal(const std::string& signal_);
00043     Gnss_Signal(const Gnss_Satellite& satellite_, const std::string& signal_);
00044     ~Gnss_Signal() = default;
00045
00046     /*!
00047     * \brief Return the signal identifier string.
00048     *
00049     * - GPS: "1C" (L1 C/A), "2S" (L2C), "L5"
00050     * - GLONASS: "1G" (L1 C/A), "2G" (L2 C/A)
00051     * - Galileo: "1B" (E1B), "5X" (E5a), "7X" (E5b), "6C" (E6C)
00052     * - BeiDou: "B1" (B1I), "B3" (B3I)
00053     */
00054     std::string get_signal_str() const;
00055
00056     Gnss_Satellite get_satellite() const; //!< Get the Gnss_Satellite associated to the signal
00057
00058     friend bool operator==(const Gnss_Signal& /*sig1*/, const Gnss_Signal& /*sig2*/);    //!<
00059     operator== for comparison

```

```

00059     friend std::ostream& operator<<(std::ostream& /*out*/, const Gnss_Signal& /*sig*/); //!< operator<<
        for pretty printing
00060
00061 private:
00062     Gnss_Satellite satellite{};
00063     std::string signal{};
00064 };
00065
00066
00067 /** \} */
00068 /** \} */
00069 #endif // GNSS_SDR_GNSS_SIGNAL_H

```

13.791 gnss_synchro.h File Reference

Interface of the [Gnss_Synchro](#) class.

```

#include <boost/serialization/nvp.hpp>
#include <stdint>
#include <utility>

```

Classes

- class [Gnss_Synchro](#)

This is the class that contains the information that is shared by the processing blocks.

13.791.1 Detailed Description

Interface of the [Gnss_Synchro](#) class.

Author

Luis Esteve, 2012. [luis\(at\)epsilon-formacion.com](mailto:luis(at)epsilon-formacion.com) Javier Arribas, 2012. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es) Álvaro Cebrián Juan, 2018. [acebrianjuan\(at\)gmail.com](mailto:acebrianjuan(at)gmail.com)

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 Definition in file [gnss_synchro.h](#).

13.792 gnss_synchro.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gnss_synchro.h
00003  * \brief Interface of the Gnss_Synchro class
00004  * \author
00005  * Luis Esteve, 2012. luis\(at\)epsilon-formacion.com
00006  * Javier Arribas, 2012. jarribas\(at\)cttc.es
00007  * Álvaro Cebrián Juan, 2018. acebrianjuan\(at\)gmail.com
00008  *
00009  * -----
00010  *
00011  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00012  * This file is part of GNSS-SDR.
00013  *
00014  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00015  * SPDX-License-Identifier: GPL-3.0-or-later
00016  *
00017  * -----
00018  */
00019
00020 #ifndef GNSS_SDR_GNSS_SYNCHRO_H
00021 #define GNSS_SDR_GNSS_SYNCHRO_H
00022
00023 #include <boost/serialization/nvp.hpp>
00024 #include <stdint>
00025 #include <utility>
00026
00027 /** \addtogroup Core
00028  * \{ */
00029 /** \addtogroup System_Parameters core_system_parameters
00030  * GNSS parameters

```

```

00031  * \{ */
00032
00033
00034  /*!
00035  * \brief This is the class that contains the information that is shared
00036  * by the processing blocks.
00037  */
00038  class Gnss_Synchro
00039  {
00040  public:
00041      Gnss_Synchro() = default;    //!< Default constructor
00042
00043      ~Gnss_Synchro() = default;  //!< Default destructor
00044
00045      // Satellite and signal info
00046      char System{};               //!< Set by Channel::set_signal(Gnss_Signal gnss_signal)
00047      char Signal[3]{};           //!< Set by Channel::set_signal(Gnss_Signal gnss_signal)
00048      uint32_t PRN{};             //!< Set by Channel::set_signal(Gnss_Signal gnss_signal)
00049      int32_t Channel_ID{};       //!< Set by Channel constructor
00050
00051      // Acquisition
00052      double Acq_delay_samples{}; //!< Set by Acquisition processing block
00053      double Acq_doppler_hz{};    //!< Set by Acquisition processing block
00054      uint64_t Acq_samplestamp_samples{}; //!< Set by Acquisition processing block
00055      uint32_t Acq_doppler_step{}; //!< Set by Acquisition processing block
00056
00057      // Tracking
00058      int64_t fs{};               //!< Set by Tracking processing block
00059      double Prompt_I{};          //!< Set by Tracking processing block
00060      double Prompt_Q{};          //!< Set by Tracking processing block
00061      double CN0_dB_hz{};         //!< Set by Tracking processing block
00062      double Carrier_Doppler_hz{}; //!< Set by Tracking processing block
00063      double Carrier_phase_rads{}; //!< Set by Tracking processing block
00064      double Code_phase_samples{}; //!< Set by Tracking processing block
00065      uint64_t Tracking_sample_counter{}; //!< Set by Tracking processing block
00066      int32_t correlation_length_ms{}; //!< Set by Tracking processing block
00067
00068      // Telemetry Decoder
00069      uint32_t TOW_at_current_symbol_ms{}; //!< Set by Telemetry Decoder processing block
00070
00071      // Observables
00072      double Pseudorange_m{};     //!< Set by Observables processing block
00073      double RX_time{};           //!< Set by Observables processing block
00074      double interp_TOW_ms{};     //!< Set by Observables processing block
00075
00076      // Flags
00077      bool Flag_valid_acquisition{}; //!< Set by Acquisition processing block
00078      bool Flag_valid_symbol_output{}; //!< Set by Tracking processing block
00079      bool Flag_valid_word{};       //!< Set by Telemetry Decoder processing block
00080      bool Flag_valid_pseudorange{}; //!< Set by Observables processing block
00081      bool Flag_PLL_180_deg_phase_locked{}; //!< Set by Telemetry Decoder processing block
00082      bool Flag_cycle_slip{};      //!< Set by Observables processing block
00083
00084      /// Copy constructor
00085      Gnss_Synchro(const Gnss_Synchro& other) noexcept = default;
00086
00087      /// Copy assignment operator
00088      Gnss_Synchro& operator=(const Gnss_Synchro& rhs) noexcept
00089      {
00090          // Only do assignment if RHS is a different object from this.
00091          if (this != &rhs)
00092          {
00093              this->System = rhs.System;
00094              this->Signal[0] = rhs.Signal[0];
00095              this->Signal[1] = rhs.Signal[1];
00096              this->Signal[2] = rhs.Signal[2];
00097              this->PRN = rhs.PRN;
00098              this->Channel_ID = rhs.Channel_ID;
00099              this->Acq_delay_samples = rhs.Acq_delay_samples;
00100              this->Acq_doppler_hz = rhs.Acq_doppler_hz;
00101              this->Acq_samplestamp_samples = rhs.Acq_samplestamp_samples;
00102              this->Acq_doppler_step = rhs.Acq_doppler_step;
00103              this->fs = rhs.fs;
00104              this->Prompt_I = rhs.Prompt_I;
00105              this->Prompt_Q = rhs.Prompt_Q;
00106              this->CN0_dB_hz = rhs.CN0_dB_hz;
00107              this->Carrier_Doppler_hz = rhs.Carrier_Doppler_hz;
00108              this->Carrier_phase_rads = rhs.Carrier_phase_rads;
00109              this->Code_phase_samples = rhs.Code_phase_samples;
00110              this->Tracking_sample_counter = rhs.Tracking_sample_counter;
00111              this->correlation_length_ms = rhs.correlation_length_ms;
00112              this->TOW_at_current_symbol_ms = rhs.TOW_at_current_symbol_ms;
00113              this->Pseudorange_m = rhs.Pseudorange_m;
00114              this->RX_time = rhs.RX_time;
00115              this->interp_TOW_ms = rhs.interp_TOW_ms;
00116              this->Flag_valid_acquisition = rhs.Flag_valid_acquisition;
00117              this->Flag_valid_symbol_output = rhs.Flag_valid_symbol_output;

```

```

00118         this->Flag_valid_word = rhs.Flag_valid_word;
00119         this->Flag_valid_pseudorange = rhs.Flag_valid_pseudorange;
00120         this->Flag_PLL180_deg_phase_locked = rhs.Flag_PLL180_deg_phase_locked;
00121         this->Flag_cycle_slip = rhs.Flag_cycle_slip;
00122     }
00123     return *this;
00124 };
00125
00126 /// Move constructor
00127 Gnss_Synchro(Gnss_Synchro&& other) noexcept = default;
00128
00129 /// Move assignment operator
00130 Gnss_Synchro& operator=(Gnss_Synchro&& other) noexcept
00131 {
00132     if (this != &other)
00133     {
00134         this->System = other.System;
00135         this->Signal[0] = other.Signal[0];
00136         this->Signal[1] = other.Signal[1];
00137         this->Signal[2] = other.Signal[2];
00138         this->PRN = other.PRN;
00139         this->Channel_ID = other.Channel_ID;
00140         this->Acq_delay_samples = other.Acq_delay_samples;
00141         this->Acq_doppler_hz = other.Acq_doppler_hz;
00142         this->Acq_samplestamp_samples = other.Acq_samplestamp_samples;
00143         this->Acq_doppler_step = other.Acq_doppler_step;
00144         this->fs = other.fs;
00145         this->Prompt_I = other.Prompt_I;
00146         this->Prompt_Q = other.Prompt_Q;
00147         this->CN0_dB_hz = other.CN0_dB_hz;
00148         this->Carrier_Doppler_hz = other.Carrier_Doppler_hz;
00149         this->Carrier_phase_rads = other.Carrier_phase_rads;
00150         this->Code_phase_samples = other.Code_phase_samples;
00151         this->Tracking_sample_counter = other.Tracking_sample_counter;
00152         this->correlation_length_ms = other.correlation_length_ms;
00153         this->TOW_at_current_symbol_ms = other.TOW_at_current_symbol_ms;
00154         this->Pseudorange_m = other.Pseudorange_m;
00155         this->RX_time = other.RX_time;
00156         this->interp_TOW_ms = other.interp_TOW_ms;
00157         this->Flag_valid_acquisition = other.Flag_valid_acquisition;
00158         this->Flag_valid_symbol_output = other.Flag_valid_symbol_output;
00159         this->Flag_valid_word = other.Flag_valid_word;
00160         this->Flag_valid_pseudorange = other.Flag_valid_pseudorange;
00161         this->Flag_PLL180_deg_phase_locked = other.Flag_PLL180_deg_phase_locked;
00162
00163         // Leave the source object in a valid but unspecified state
00164         other.Signal[0] = '\0';
00165         other.Signal[1] = '\0';
00166         other.Signal[2] = '\0';
00167         other.System = 0;
00168         other.PRN = 0;
00169         other.Channel_ID = 0;
00170         other.Acq_delay_samples = 0.0;
00171         other.Acq_doppler_hz = 0.0;
00172         other.Acq_samplestamp_samples = 0;
00173         other.Acq_doppler_step = 0;
00174         other.fs = 0;
00175         other.Prompt_I = 0.0;
00176         other.Prompt_Q = 0.0;
00177         other.CN0_dB_hz = 0.0;
00178         other.Carrier_Doppler_hz = 0.0;
00179         other.Carrier_phase_rads = 0.0;
00180         other.Code_phase_samples = 0.0;
00181         other.Tracking_sample_counter = 0;
00182         other.correlation_length_ms = 0;
00183         other.TOW_at_current_symbol_ms = 0;
00184         other.Pseudorange_m = 0.0;
00185         other.RX_time = 0.0;
00186         other.interp_TOW_ms = 0.0;
00187         other.Flag_valid_acquisition = false;
00188         other.Flag_valid_symbol_output = false;
00189         other.Flag_valid_word = false;
00190         other.Flag_valid_pseudorange = false;
00191         other.Flag_PLL180_deg_phase_locked = false;
00192         other.Flag_cycle_slip = false;
00193     }
00194     return *this;
00195 };
00196
00197 /*!
00198  * \brief This member function serializes and restores
00199  * Gnss_Synchro objects from a byte stream.
00200  */
00201 template <class Archive>
00202
00203 void serialize(Archive& ar, const unsigned int version)
00204 {

```

```

00205         if (version)
00206         {
00207         };
00208         // Satellite and signal info
00209         ar& BOOST_SERIALIZATION_NVP(System);
00210         ar& BOOST_SERIALIZATION_NVP(Signal);
00211         ar& BOOST_SERIALIZATION_NVP(PRN);
00212         ar& BOOST_SERIALIZATION_NVP(Channel_ID);
00213         // Acquisition
00214         ar& BOOST_SERIALIZATION_NVP(Acq_delay_samples);
00215         ar& BOOST_SERIALIZATION_NVP(Acq_doppler_hz);
00216         ar& BOOST_SERIALIZATION_NVP(Acq_samplestamp_samples);
00217         ar& BOOST_SERIALIZATION_NVP(Acq_doppler_step);
00218         // Tracking
00219         ar& BOOST_SERIALIZATION_NVP(fs);
00220         ar& BOOST_SERIALIZATION_NVP(Prompt_I);
00221         ar& BOOST_SERIALIZATION_NVP(Prompt_Q);
00222         ar& BOOST_SERIALIZATION_NVP(CN0_dB_hz);
00223         ar& BOOST_SERIALIZATION_NVP(Carrier_Doppler_hz);
00224         ar& BOOST_SERIALIZATION_NVP(Carrier_phase_rads);
00225         ar& BOOST_SERIALIZATION_NVP(Code_phase_samples);
00226         ar& BOOST_SERIALIZATION_NVP(Tracking_sample_counter);
00227         ar& BOOST_SERIALIZATION_NVP(correlation_length_ms);
00228         // Telemetry Decoder
00229         ar& BOOST_SERIALIZATION_NVP(TOW_at_current_symbol_ms);
00230         // Observables
00231         ar& BOOST_SERIALIZATION_NVP(Pseudorange_m);
00232         ar& BOOST_SERIALIZATION_NVP(RX_time);
00233         ar& BOOST_SERIALIZATION_NVP(interp_TOW_ms);
00234         // Flags
00235         ar& BOOST_SERIALIZATION_NVP(Flag_valid_acquisition);
00236         ar& BOOST_SERIALIZATION_NVP(Flag_valid_symbol_output);
00237         ar& BOOST_SERIALIZATION_NVP(Flag_valid_word);
00238         ar& BOOST_SERIALIZATION_NVP(Flag_valid_pseudorange);
00239         ar& BOOST_SERIALIZATION_NVP(Flag_PLL_180_deg_phase_locked);
00240         ar& BOOST_SERIALIZATION_NVP(Flag_cycle_slip);
00241     }
00242 };
00243
00244
00245 /** \} */
00246 /** \} */
00247 #endif // GNSS_SDR_GNSS_SYNCHRO_H

```

13.793 gps_acq_assist.h File Reference

Interface of a GPS RRL ACQUISITION ASSISTANCE storage.

```
#include <cstdint>
```

Classes

- class [Gps_Acq_Assist](#)

This class is a storage for the GPS GSM RRL acquisition assistance data as described in Digital cellular telecommunications system (Phase 2+); Location Services (LCS); Mobile Station (MS) - Serving Mobile Location Centre (SMLC) Radio Resource LCS Protocol (RRLP) (3GPP TS 44.031 version 5.12.0 Release 5)

13.793.1 Detailed Description

Interface of a GPS RRL ACQUISITION ASSISTANCE storage.

Author

Javier Arribas, 2013. jarribas(at)cttc.es

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Definition in file [gps_acq_assist.h](#).

13.794 gps_acq_assist.h

[Go to the documentation of this file.](#)

```
00001 /*!
```

```

00002  * \file gps_acq_assist.h
00003  * \brief Interface of a GPS RRL ACQUISITION ASSISTACE storage
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GPS_ACQ_ASSIST_H
00019 #define GNSS_SDR_GPS_ACQ_ASSIST_H
00020
00021 #include <stdint>
00022
00023 /** \addtogroup Core
00024  * \{ */
00025 /** \addtogroup System_Parameters
00026  * \{ */
00027
00028
00029 /*!
00030  * \brief This class is a storage for the GPS GSM RRL ACQUISITION assistance data as described in
00031  * Digital cellular telecommunications system (Phase 2+);
00032  * Location Services (LCS);
00033  * Mobile Station (MS) - Serving Mobile Location Centre (SM-LC)
00034  * Radio Resource LCS Protocol (RRLP)
00035  * (3GPP TS 44.031 version 5.12.0 Release 5)
00036  */
00037 class Gps_Acq_Assist
00038 {
00039 public:
00040     /*!
00041      * Default constructor
00042      */
00043     Gps_Acq_Assist() = default;
00044
00045     uint32_t PRN{};           //!< SV PRN NUMBER
00046     double tow{};            //!< Time Of Week assigned to the acquisition data
00047     double Doppler0{};       //!< Doppler (0 order term) [Hz]
00048     double Doppler1{};       //!< Doppler (1 order term) [Hz]
00049     double dopplerUncertainty{}; //!< Doppler Uncertainty [Hz]
00050     double Code_Phase{};     //!< Code phase [chips]
00051     double Code_Phase_int{}; //!< Integer Code Phase [1 C/A code period]
00052     double GPS_Bit_Number{}; //!< GPS Bit Number
00053     double Code_Phase_window{}; //!< Code Phase search window [chips]
00054     double Azimuth{};        //!< Satellite Azimuth [deg]
00055     double Elevation{};      //!< Satellite Elevation [deg]
00056 };
00057
00058
00059 /** \} */
00060 /** \} */
00061 #endif // GNSS_SDR_GPS_ACQ_ASSIST_H

```

13.795 gps_almanac.h File Reference

Interface of a GPS ALMANAC storage.

```

#include "gnss_almanac.h"
#include <boost/serialization/nvp.hpp>

```

Classes

- class [Gps_Almanac](#)

This class is a storage for the GPS SV ALMANAC data as described in IS-GPS-200M.

13.795.1 Detailed Description

Interface of a GPS ALMANAC storage.

Author

Javier Arribas, 2013. jarribas(at)cttc.es

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Definition in file [gps_almanac.h](#).

13.796 gps_almanac.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gps_almanac.h
00003  * \brief Interface of a GPS ALMANAC storage
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GPS_ALMANAC_H
00019 #define GNSS_SDR_GPS_ALMANAC_H
00020
00021 #include "gnss_almanac.h"
00022 #include <boost/serialization/nvp.hpp>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup System_Parameters
00027  * \{ */
00028
00029
00030 /*!
00031 * \brief This class is a storage for the GPS SV ALMANAC data as described in IS-GPS-200M
00032 *
00033 * See https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf Appendix II
00034 */
00035 class Gps_Almanac : public Gnss_Almanac
00036 {
00037 public:
00038  /*!
00039   * Default constructor
00040   */
00041  Gps_Almanac()
00042  {
00043      this->System = 'G';
00044  };
00045
00046  int32_t SV_health{}; //!< SV Health
00047  int32_t AS_status{}; //!< Anti-Spoofing Flags and SV Configuration
00048
00049  template <class Archive>
00050
00051  void serialize(Archive& ar, const unsigned int version)
00052  {
00053      if (version)
00054      {
00055      };
00056      ar& BOOST_SERIALIZATION_NVP (PRN);
00057      ar& BOOST_SERIALIZATION_NVP (delta_i);
00058      ar& BOOST_SERIALIZATION_NVP (toa);
00059      ar& BOOST_SERIALIZATION_NVP (WNa);
00060      ar& BOOST_SERIALIZATION_NVP (M_0);
00061      ar& BOOST_SERIALIZATION_NVP (ecc);
00062      ar& BOOST_SERIALIZATION_NVP (sqrtA);
00063      ar& BOOST_SERIALIZATION_NVP (OMEGA_0);
00064      ar& BOOST_SERIALIZATION_NVP (omega);
00065      ar& BOOST_SERIALIZATION_NVP (OMEGAdot);
00066      ar& BOOST_SERIALIZATION_NVP (af0);
00067      ar& BOOST_SERIALIZATION_NVP (af1);
00068      ar& BOOST_SERIALIZATION_NVP (SV_health);
00069      ar& BOOST_SERIALIZATION_NVP (AS_status);
00070  }
00071  };
00072

```

```

00073
00074 /** \} */
00075 /** \} */
00076 #endif // GNSS_SDR_GPS_ALMANAC_H

```

13.797 GPS_CNAV.h File Reference

Defines parameters for GPS CNAV.

```

#include "MATH_CONSTANTS.h"
#include <cstdint>
#include <utility>
#include <vector>

```

Functions

- const std::vector< std::pair< int32_t, int32_t > > **CNAV_PRN** ({9, 6})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_MSG_TYPE** ({15, 6})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_TOW** ({21, 17})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_ALERT_FLAG** ({38, 1})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_WN** ({39, 13})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_HEALTH** ({52, 3})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_TOP1** ({55, 11})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_URA** ({66, 5})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_TOE1** ({71, 11})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_DELTA_A** ({82, 26})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_A_DOT** ({108, 25})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_DELTA_N0** ({133, 17})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_DELTA_N0_DOT** ({150, 23})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_M0** ({173, 33})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_E_ECCENTRICITY** ({206, 33})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_OMEGA** ({239, 33})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_INTEGRITY_FLAG** ({272, 1})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_L2_PHASING_FLAG** ({273, 1})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_TOE2** ({39, 11})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_OMEGA0** ({50, 33})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_I0** ({83, 33})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_DELTA_OMEGA_DOT** ({116, 17})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_I0_DOT** ({133, 15})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_CIS** ({148, 16})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_CIC** ({164, 16})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_CRS** ({180, 24})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_CRC** ({204, 24})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_CUS** ({228, 21})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_CUC** ({249, 21})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_TOP2** ({39, 11})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_URA_NED0** ({50, 5})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_URA_NED1** ({55, 3})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_URA_NED2** ({58, 3})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_TOC** ({61, 11})
- const std::vector< std::pair< int, int > > **CNAV_AF0** ({72, 26})
- const std::vector< std::pair< int, int > > **CNAV_AF1** ({98, 20})
- const std::vector< std::pair< int, int > > **CNAV_AF2** ({118, 10})
- const std::vector< std::pair< int, int > > **CNAV_TGD** ({128, 13})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_ISCL1** ({141, 13})
- const std::vector< std::pair< int32_t, int32_t > > **CNAV_ISCL2** ({154, 13})

- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ISCL5I` {{{167, 13}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ISCL5Q` {{{180, 13}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ALPHA0` {{{193, 8}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ALPHA1` {{{201, 8}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ALPHA2` {{{209, 8}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_ALPHA3` {{{217, 8}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_BETA0` {{{225, 8}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_BETA1` {{{233, 8}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_BETA2` {{{241, 8}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_BETA3` {{{249, 8}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_WNOP` {{{257, 8}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_A0` {{{128, 16}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_A1` {{{144, 13}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_A2` {{{157, 7}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_DELTA_TLS` {{{164, 8}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_TOT` {{{172, 16}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_WN_OT` {{{188, 13}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_WN_LSF` {{{201, 13}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_DN` {{{214, 4}}
- `const std::vector< std::pair< int32_t, int32_t > > CNAV_DELTA_TLSF` {{{218, 8}}

Variables

- `constexpr int32_t GPS_CNAV_DATA_PAGE_BITS = 300`
- `constexpr int32_t CNAV_TOW_LSB = 6`
- `constexpr int32_t CNAV_TOP1_LSB = 300`
- `constexpr int32_t CNAV_TOE1_LSB = 300`
- `constexpr double CNAV_DELTA_A_LSB = TWO_N9`
- `constexpr double CNAV_A_DOT_LSB = TWO_N21`
- `constexpr double CNAV_DELTA_N0_LSB = TWO_N44 * GNSS_PI`
- `constexpr double CNAV_DELTA_N0_DOT_LSB = TWO_N57 * GNSS_PI`
- `constexpr double CNAV_M0_LSB = TWO_N32 * GNSS_PI`
- `constexpr double CNAV_E_ECCENTRICITY_LSB = TWO_N34`
- `constexpr double CNAV_OMEGA_LSB = TWO_N32 * GNSS_PI`
- `constexpr int32_t CNAV_TOE2_LSB = 300`
- `constexpr double CNAV_OMEGA0_LSB = TWO_N32 * GNSS_PI`
- `constexpr double CNAV_I0_LSB = TWO_N32 * GNSS_PI`
- `constexpr double CNAV_DELTA_OMEGA_DOT_LSB = TWO_N44 * GNSS_PI`
- `constexpr double CNAV_I0_DOT_LSB = TWO_N44 * GNSS_PI`
- `constexpr double CNAV_CIS_LSB = TWO_N30`
- `constexpr double CNAV_CIC_LSB = TWO_N30`
- `constexpr double CNAV_CRS_LSB = TWO_N8`
- `constexpr double CNAV_CRC_LSB = TWO_N8`
- `constexpr double CNAV_CUS_LSB = TWO_N30`
- `constexpr double CNAV_CUC_LSB = TWO_N30`
- `constexpr int32_t CNAV_TOP2_LSB = 300`
- `constexpr int32_t CNAV_TOC_LSB = 300`
- `constexpr double CNAV_AF0_LSB = TWO_N35`
- `constexpr double CNAV_AF1_LSB = TWO_N48`
- `constexpr double CNAV_AF2_LSB = TWO_N60`
- `constexpr double CNAV_TGD_LSB = TWO_N35`
- `constexpr double CNAV_ISCL1_LSB = TWO_N35`
- `constexpr double CNAV_ISCL2_LSB = TWO_N35`
- `constexpr double CNAV_ISCL5I_LSB = TWO_N35`
- `constexpr double CNAV_ISCL5Q_LSB = TWO_N35`

- constexpr double [CNAV_ALPHA0_LSB](#) = TWO_N30
- constexpr double [CNAV_ALPHA1_LSB](#) = TWO_N27
- constexpr double [CNAV_ALPHA2_LSB](#) = TWO_N24
- constexpr double [CNAV_ALPHA3_LSB](#) = TWO_N24
- constexpr double [CNAV_BETA0_LSB](#) = TWO_P11
- constexpr double [CNAV_BETA1_LSB](#) = TWO_P14
- constexpr double [CNAV_BETA2_LSB](#) = TWO_P16
- constexpr double [CNAV_BETA3_LSB](#) = TWO_P16
- constexpr double [CNAV_A0_LSB](#) = TWO_N35
- constexpr double [CNAV_A1_LSB](#) = TWO_N51
- constexpr double [CNAV_A2_LSB](#) = TWO_N68
- constexpr int32_t [CNAV_DELTA_TLS_LSB](#) = 1
- constexpr int32_t [CNAV_TOT_LSB](#) = TWO_P4
- constexpr int32_t [CNAV_WN_OT_LSB](#) = 1
- constexpr int32_t [CNAV_WN_LSF_LSB](#) = 1
- constexpr int32_t [CNAV_DN_LSB](#) = 1
- constexpr int32_t [CNAV_DELTA_TLSF_LSB](#) = 1
- constexpr double [CNAV_A_REF](#) = 26559710.0
- constexpr double [CNAV_OMEGA_DOT_REF](#) = -2.6e-9
- constexpr double [CNAV_QZSS_A_REF](#) = 42164200.0

13.797.1 Detailed Description

Defines parameters for GPS CNAV.

Author

Antonio Ramos, 2017. [antonio.ramos\(at\)cttc.es](mailto:antonio.ramos(at)cttc.es)

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 Definition in file [GPS_CNAV.h](#).

13.798 GPS_CNAV.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file GPS_CNAV.h
00003  * \brief Defines parameters for GPS CNAV
00004  * \author Antonio Ramos, 2017. antonio.ramos\(at\)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GPS_CNAV_H
00019 #define GNSS_SDR_GPS_CNAV_H
00020
00021 #include "MATH_CONSTANTS.h"
00022 #include <stdint>
00023 #include <utility> // std::pair
00024 #include <vector>
00025
00026 /** \addtogroup Core
00027  * \{ */
00028 /** \addtogroup System_Parameters
00029  * \{ */
00030
00031
00032 // CNAV GPS NAVIGATION MESSAGE STRUCTURE
00033 // NAVIGATION MESSAGE FIELDS POSITIONS (from IS-GPS-200M Appendix III)

```

```

00034
00035 constexpr int32_t GPS_CNAV_DATA_PAGE_BITS = 300;
00036
00037 // common to all messages
00038 const std::vector<std::pair<int32_t, int32_t> > CNAV_PRN({{9, 6}});
00039 const std::vector<std::pair<int32_t, int32_t> > CNAV_MSG_TYPE({{15, 6}});
00040 const std::vector<std::pair<int32_t, int32_t> > CNAV_TOW({{21, 17}}); // GPS Time Of Week in seconds
00041 constexpr int32_t CNAV_TOW_LSB = 6;
00042 const std::vector<std::pair<int32_t, int32_t> > CNAV_ALERT_FLAG({{38, 1}});
00043
00044 // MESSAGE TYPE 10 (Ephemeris 1)
00045 const std::vector<std::pair<int32_t, int32_t> > CNAV_WN({{39, 13}});
00046 const std::vector<std::pair<int32_t, int32_t> > CNAV_HEALTH({{52, 3}});
00047 const std::vector<std::pair<int32_t, int32_t> > CNAV_TOP1({{55, 11}});
00048 constexpr int32_t CNAV_TOP1_LSB = 300;
00049 const std::vector<std::pair<int32_t, int32_t> > CNAV_URA({{66, 5}});
00050
00051 const std::vector<std::pair<int32_t, int32_t> > CNAV_TOE1({{71, 11}});
00052 constexpr int32_t CNAV_TOE1_LSB = 300;
00053
00054 const std::vector<std::pair<int32_t, int32_t> > CNAV_DELTA_A({{82, 26}}); // Relative to AREF =
26,559,710 meters
00055 constexpr double CNAV_DELTA_A_LSB = TWO_N9;
00056
00057 const std::vector<std::pair<int32_t, int32_t> > CNAV_A_DOT({{108, 25}});
00058 constexpr double CNAV_A_DOT_LSB = TWO_N21;
00059
00060 const std::vector<std::pair<int32_t, int32_t> > CNAV_DELTA_N0({{133, 17}});
00061 constexpr double CNAV_DELTA_N0_LSB = TWO_N44 * GNSS_PI; // semi-circles to radians
00062 const std::vector<std::pair<int32_t, int32_t> > CNAV_DELTA_N0_DOT({{150, 23}});
00063 constexpr double CNAV_DELTA_N0_DOT_LSB = TWO_N57 * GNSS_PI; // semi-circles to radians
00064 const std::vector<std::pair<int32_t, int32_t> > CNAV_M0({{173, 33}});
00065 constexpr double CNAV_M0_LSB = TWO_N32 * GNSS_PI; // semi-circles to radians
00066 const std::vector<std::pair<int32_t, int32_t> > CNAV_E_ECCENTRICITY({{206, 33}});
00067 constexpr double CNAV_E_ECCENTRICITY_LSB = TWO_N34;
00068 const std::vector<std::pair<int32_t, int32_t> > CNAV_OMEGA({{239, 33}});
00069 constexpr double CNAV_OMEGA_LSB = TWO_N32 * GNSS_PI; // semi-circles to radians
00070 const std::vector<std::pair<int32_t, int32_t> > CNAV_INTEGRITY_FLAG({{272, 1}});
00071 const std::vector<std::pair<int32_t, int32_t> > CNAV_L2_PHASING_FLAG({{273, 1}});
00072
00073 // MESSAGE TYPE 11 (Ephemeris 2)
00074 const std::vector<std::pair<int32_t, int32_t> > CNAV_TOE2({{39, 11}});
00075 constexpr int32_t CNAV_TOE2_LSB = 300;
00076 const std::vector<std::pair<int32_t, int32_t> > CNAV_OMEGA0({{50, 33}});
00077 constexpr double CNAV_OMEGA0_LSB = TWO_N32 * GNSS_PI; // semi-circles to radians
00078 const std::vector<std::pair<int32_t, int32_t> > CNAV_I0({{83, 33}});
00079 constexpr double CNAV_I0_LSB = TWO_N32 * GNSS_PI; // semi-circles to
radians
00080 const std::vector<std::pair<int32_t, int32_t> > CNAV_DELTA_OMEGA_DOT({{116, 17}}); // Relative to REF
= -2.6 x 10^-9 semi-circles/second.
00081 constexpr double CNAV_DELTA_OMEGA_DOT_LSB = TWO_N44 * GNSS_PI; // semi-circles to
radians
00082 const std::vector<std::pair<int32_t, int32_t> > CNAV_I0_DOT({{133, 15}});
00083 constexpr double CNAV_I0_DOT_LSB = TWO_N44 * GNSS_PI; // semi-circles to radians
00084 const std::vector<std::pair<int32_t, int32_t> > CNAV_CIS({{148, 16}});
00085 constexpr double CNAV_CIS_LSB = TWO_N30;
00086 const std::vector<std::pair<int32_t, int32_t> > CNAV_CIC({{164, 16}});
00087 constexpr double CNAV_CIC_LSB = TWO_N30;
00088 const std::vector<std::pair<int32_t, int32_t> > CNAV_CRS({{180, 24}});
00089 constexpr double CNAV_CRS_LSB = TWO_N8;
00090 const std::vector<std::pair<int32_t, int32_t> > CNAV_CRC({{204, 24}});
00091 constexpr double CNAV_CRC_LSB = TWO_N8;
00092 const std::vector<std::pair<int32_t, int32_t> > CNAV_CUS({{228, 21}});
00093 constexpr double CNAV_CUS_LSB = TWO_N30;
00094 const std::vector<std::pair<int32_t, int32_t> > CNAV_CUC({{249, 21}});
00095 constexpr double CNAV_CUC_LSB = TWO_N30;
00096
00097
00098 // MESSAGE TYPE 30 (CLOCK, IONO, GROUP DELAY)
00099 const std::vector<std::pair<int32_t, int32_t> > CNAV_TOP2({{39, 11}});
00100 constexpr int32_t CNAV_TOP2_LSB = 300;
00101 const std::vector<std::pair<int32_t, int32_t> > CNAV_URA_NED0({{50, 5}});
00102 const std::vector<std::pair<int32_t, int32_t> > CNAV_URA_NED1({{55, 3}});
00103 const std::vector<std::pair<int32_t, int32_t> > CNAV_URA_NED2({{58, 3}});
00104 const std::vector<std::pair<int32_t, int32_t> > CNAV_TOC({{61, 11}});
00105 constexpr int32_t CNAV_TOC_LSB = 300;
00106 const std::vector<std::pair<int, int> > CNAV_AF0({{72, 26}});
00107 constexpr double CNAV_AF0_LSB = TWO_N35;
00108 const std::vector<std::pair<int, int> > CNAV_AF1({{98, 20}});
00109 constexpr double CNAV_AF1_LSB = TWO_N48;
00110 const std::vector<std::pair<int, int> > CNAV_AF2({{118, 10}});
00111 constexpr double CNAV_AF2_LSB = TWO_N60;
00112 const std::vector<std::pair<int, int> > CNAV_TGD({{128, 13}});
00113 constexpr double CNAV_TGD_LSB = TWO_N35;
00114 const std::vector<std::pair<int32_t, int32_t> > CNAV_ISCL1({{141, 13}});
00115 constexpr double CNAV_ISCL1_LSB = TWO_N35;
00116 const std::vector<std::pair<int32_t, int32_t> > CNAV_ISCL2({{154, 13}});

```

```

00117 constexpr double CNAV_ISCL2_LSB = TWO_N35;
00118 const std::vector<std::pair<int32_t, int32_t> > CNAV_ISCL5I({{167, 13}});
00119 constexpr double CNAV_ISCL5I_LSB = TWO_N35;
00120 const std::vector<std::pair<int32_t, int32_t> > CNAV_ISCL5Q({{180, 13}});
00121 constexpr double CNAV_ISCL5Q_LSB = TWO_N35;
00122 // Ionospheric parameters
00123 const std::vector<std::pair<int32_t, int32_t> > CNAV_ALPHA0({{193, 8}});
00124 constexpr double CNAV_ALPHA0_LSB = TWO_N30;
00125 const std::vector<std::pair<int32_t, int32_t> > CNAV_ALPHA1({{201, 8}});
00126 constexpr double CNAV_ALPHA1_LSB = TWO_N27;
00127 const std::vector<std::pair<int32_t, int32_t> > CNAV_ALPHA2({{209, 8}});
00128 constexpr double CNAV_ALPHA2_LSB = TWO_N24;
00129 const std::vector<std::pair<int32_t, int32_t> > CNAV_ALPHA3({{217, 8}});
00130 constexpr double CNAV_ALPHA3_LSB = TWO_N24;
00131 const std::vector<std::pair<int32_t, int32_t> > CNAV_BETA0({{225, 8}});
00132 constexpr double CNAV_BETA0_LSB = TWO_P11;
00133 const std::vector<std::pair<int32_t, int32_t> > CNAV_BETA1({{233, 8}});
00134 constexpr double CNAV_BETA1_LSB = TWO_P14;
00135 const std::vector<std::pair<int32_t, int32_t> > CNAV_BETA2({{241, 8}});
00136 constexpr double CNAV_BETA2_LSB = TWO_P16;
00137 const std::vector<std::pair<int32_t, int32_t> > CNAV_BETA3({{249, 8}});
00138 constexpr double CNAV_BETA3_LSB = TWO_P16;
00139 const std::vector<std::pair<int32_t, int32_t> > CNAV_WNOP({{257, 8}});
00140
00141
00142 // MESSAGE TYPE 33 (CLOCK and UTC)
00143 const std::vector<std::pair<int32_t, int32_t> > CNAV_A0({{128, 16}});
00144 constexpr double CNAV_A0_LSB = TWO_N35;
00145 const std::vector<std::pair<int32_t, int32_t> > CNAV_A1({{144, 13}});
00146 constexpr double CNAV_A1_LSB = TWO_N51;
00147 const std::vector<std::pair<int32_t, int32_t> > CNAV_A2({{157, 7}});
00148 constexpr double CNAV_A2_LSB = TWO_N68;
00149 const std::vector<std::pair<int32_t, int32_t> > CNAV_DELTA_TLS({{164, 8}});
00150 constexpr int32_t CNAV_DELTA_TLS_LSB = 1;
00151 const std::vector<std::pair<int32_t, int32_t> > CNAV_TOT({{172, 16}});
00152 constexpr int32_t CNAV_TOT_LSB = TWO_P4;
00153 const std::vector<std::pair<int32_t, int32_t> > CNAV_WN_OT({{188, 13}});
00154 constexpr int32_t CNAV_WN_OT_LSB = 1;
00155 const std::vector<std::pair<int32_t, int32_t> > CNAV_WN_LSF({{201, 13}});
00156 constexpr int32_t CNAV_WN_LSF_LSB = 1;
00157 const std::vector<std::pair<int32_t, int32_t> > CNAV_DN({{214, 4}});
00158 constexpr int32_t CNAV_DN_LSB = 1;
00159 const std::vector<std::pair<int32_t, int32_t> > CNAV_DELTA_TLSF({{218, 8}});
00160 constexpr int32_t CNAV_DELTA_TLSF_LSB = 1;
00161
00162 constexpr double CNAV_A_REF = 26559710.0; // [m] See IS-GPS-200M, Table 30-I.
00163 constexpr double CNAV_OMEGA_DOT_REF = -2.6e-9; // [semicircles / s], see IS-GPS-200M, Table 30-I.
00164 constexpr double CNAV_QZSS_A_REF = 42164200.0;
00165
00166 // TODO: Add more frames (Almanac, etc...)
00167
00168
00169 /** \} */
00170 /** \} */
00171 #endif // GNSS_SDR_GPS_CNAV_H

```

13.799 gps_cnav_ephemeris.h File Reference

Interface of a GPS CNAV EPHEMERIS storage.

```

#include "gnss_ephemeris.h"
#include <boost/serialization/nvp.hpp>
#include <cstdint>

```

Classes

- class [Gps_CNAV_Ephemeris](#)

This is a storage class for the GPS CNAV ephemeris data as described in IS-GPS-200M.

13.799.1 Detailed Description

Interface of a GPS CNAV EPHEMERIS storage.

Author

Javier Arribas, 2015. jarribas(at)cttc.es

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Definition in file [gps_cnav_ephemeris.h](#).

13.800 gps_cnav_ephemeris.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gps_cnav_ephemeris.h
00003  * \brief Interface of a GPS CNAV EPHEMERIS storage
00004  * \author Javier Arribas, 2015. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GPS_CNAV_EPHEMERIS_H
00019 #define GNSS_SDR_GPS_CNAV_EPHEMERIS_H
00020
00021 #include "gnss_ephemeris.h"
00022 #include <boost/serialization/nvp.hpp>
00023 #include <cstdint>
00024
00025 /** \addtogroup Core
00026  * \{ */
00027 /** \addtogroup System_Parameters
00028  * \{ */
00029
00030
00031  /*!
00032  * \brief This is a storage class for the GPS CNAV ephemeris data as described
00033  * in IS-GPS-200M
00034  *
00035  * See https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf Appendix III
00036  */
00037  class Gps_CNAV_Ephemeris : public Gnss_Ephemeris
00038  {
00039  public:
00040      /*!
00041       * Constructor
00042       */
00043      Gps_CNAV_Ephemeris()
00044      {
00045          this->System = 'G';
00046      }
00047
00048      double delta_A{};          //!< Semi-major axis difference at reference time
00049      double Adot{};             //!< Change rate in semi-major axis
00050      double delta_ndot{};        //!< Rate of mean motion difference from computed value
00051      double delta_OMEGAAdot{};   //!< Rate of Right Ascension difference [semi-circles/s]
00052      int32_t toe1{};            //!< Ephemeris data reference time of week (Ref. 20.3.3.4.3 IS-GPS-200M)
00053      [s] int32_t toe2{};        //!< Ephemeris data reference time of week (Ref. 20.3.3.4.3 IS-GPS-200M)
00054      [s] int32_t signal_health{}; //!< Signal health (L1/L2/L5)
00055      int32_t top{};             //!< Data predict time of week
00056      int32_t URA{};             //!< ED Accuracy Index
00057
00058      double URA0{};             //!< NED Accuracy Index
00059      double URA1{};             //!< NED Accuracy Change Index
00060      double URA2{};             //!< NED Accuracy Change Rate Index
00061
00062      // Group Delay Differential Parameters
00063      double TGD{};             //!< Estimated Group Delay Differential: L1-L2 correction term only for the benefit
00064      of "L1 P(Y)" or "L2 P(Y)" s users [s]
00065      double ISCL1{};
00066      double ISCL2{};
00067      double ISCL5I{};
00068      double ISCL5Q{};
00069      /*! \brief If true, enhanced level of integrity assurance.

```



```

00070      *
00071      * If false, indicates that the conveying signal is provided with the
00072      * legacy level of integrity assurance. That is, the probability that the
00073      * instantaneous URE of the conveying signal exceeds 4.42 times the upper
00074      * bound value of the current broadcast URA index, for more than 5.2
00075      * seconds, without an accompanying alert, is less than 1E-5 per hour. If
00076      * true, indicates that the conveying signal is provided with an enhanced
00077      * level of integrity assurance. That is, the probability that the
00078      * instantaneous URE of the conveying signal exceeds 5.73 times the upper
00079      * bound value of the current broadcast URA index, for more than 5.2
00080      * seconds, without an accompanying alert, is less than 1E-8 per hour.
00081      */
00082      bool integrity_status_flag{};
00083      bool l2c_phasing_flag{};
00084      bool alert_flag{};      //!< If true, indicates that the SV URA may be worse than indicated in
                                d_SV_accuracy, use that SV at our own risk.
00085      bool antispoofing_flag{}; //!< If true, the AntiSpoofing mode is ON in that SV
00086
00087      template <class Archive>
00088
00089      /*!
00090      * \brief Serialize is a boost standard method to be called by the boost XML
00091      * serialization. Here is used to save the ephemeris data on disk file.
00092      */
00093      inline void serialize(Archive& archive, const uint32_t version)
00094      {
00095          using boost::serialization::make_nvp;
00096          if (version)
00097          {
00098              };
00099
00100          archive& BOOST_SERIALIZATION_NVP(PRN);
00101          archive& BOOST_SERIALIZATION_NVP(M_0);
00102          archive& BOOST_SERIALIZATION_NVP(delta_n);
00103          archive& BOOST_SERIALIZATION_NVP(ecc);
00104          archive& BOOST_SERIALIZATION_NVP(sqrtA);
00105          archive& BOOST_SERIALIZATION_NVP(OMEGA_0);
00106          archive& BOOST_SERIALIZATION_NVP(i_0);
00107          archive& BOOST_SERIALIZATION_NVP(omega);
00108          archive& BOOST_SERIALIZATION_NVP(OMEGAdot);
00109          archive& BOOST_SERIALIZATION_NVP(idot);
00110          archive& BOOST_SERIALIZATION_NVP(Cuc);
00111          archive& BOOST_SERIALIZATION_NVP(Cus);
00112          archive& BOOST_SERIALIZATION_NVP(Crc);
00113          archive& BOOST_SERIALIZATION_NVP(Crs);
00114          archive& BOOST_SERIALIZATION_NVP(Cic);
00115          archive& BOOST_SERIALIZATION_NVP(Cis);
00116          archive& BOOST_SERIALIZATION_NVP(toe);
00117          archive& BOOST_SERIALIZATION_NVP(toc);
00118          archive& BOOST_SERIALIZATION_NVP(af0);
00119          archive& BOOST_SERIALIZATION_NVP(af1);
00120          archive& BOOST_SERIALIZATION_NVP(af2);
00121          archive& BOOST_SERIALIZATION_NVP(WN);
00122          archive& BOOST_SERIALIZATION_NVP(tow);
00123          archive& BOOST_SERIALIZATION_NVP(satClkDrift);
00124          archive& BOOST_SERIALIZATION_NVP(dtr);
00125
00126          archive& BOOST_SERIALIZATION_NVP(toe1);
00127          archive& BOOST_SERIALIZATION_NVP(toe2);
00128          archive& BOOST_SERIALIZATION_NVP(TGD);
00129          archive& BOOST_SERIALIZATION_NVP(ISCL1);
00130          archive& BOOST_SERIALIZATION_NVP(ISCL2);
00131          archive& BOOST_SERIALIZATION_NVP(ISCL5I);
00132          archive& BOOST_SERIALIZATION_NVP(ISCL5Q);
00133          archive& BOOST_SERIALIZATION_NVP(delta_A);
00134          archive& BOOST_SERIALIZATION_NVP(Adot);
00135          archive& BOOST_SERIALIZATION_NVP(delta_OMEGAdot);
00136          archive& BOOST_SERIALIZATION_NVP(integrity_status_flag);
00137          archive& BOOST_SERIALIZATION_NVP(l2c_phasing_flag);
00138          archive& BOOST_SERIALIZATION_NVP(alert_flag);
00139          archive& BOOST_SERIALIZATION_NVP(antispoofing_flag);
00140      }
00141  };
00142
00143
00144  /** \} */
00145  /** \} */
00146  #endif // GNSS_SDR_GPS_CNAV_EPHEMERIS_H

```

13.801 gps_cnav_iono.h File Reference

Interface of a GPS CNAV IONOSPHERIC MODEL storage.


```
#include "gps_iono.h"
```

Classes

- class [Gps_CNAV_Iono](#)

This class is a storage for the GPS IONOSPHERIC data as described in IS-GPS-200M.

13.801.1 Detailed Description

Interface of a GPS CNAV IONOSPHERIC MODEL storage.

Author

Javier Arribas, 2015. jarribas(at)cttc.es

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 Definition in file [gps_cnav_iono.h](#).

13.802 gps_cnav_iono.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gps_cnav_iono.h
00003  * \brief Interface of a GPS CNAV IONOSPHERIC MODEL storage
00004  * \author Javier Arribas, 2015. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GPS_CNAV_IONO_H
00019 #define GNSS_SDR_GPS_CNAV_IONO_H
00020
00021 #include "gps_iono.h"
00022
00023 /** \addtogroup Core
00024  * \{ */
00025 /** \addtogroup System_Parameters
00026  * \{ */
00027
00028
00029 /*!
00030  * \brief This class is a storage for the GPS IONOSPHERIC data as described in IS-GPS-200M
00031  *
00032  * See https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf Appendix III
00033  */
00034 class Gps_CNAV_Iono : public Gps_Iono
00035 {
00036 public:
00037     Gps_CNAV_Iono() = default; //!< Default constructor
00038 };
00039
00040
00041 /** \} */
00042 /** \} */
00043 #endif // GNSS_SDR_GPS_CNAV_IONO_H
```

13.803 gps_cnav_navigation_message.h File Reference

Interface of a GPS CNAV Data message decoder.

```
#include "GPS_CNAV.h"
#include "gps_cnav_ephemeris.h"
```

```
#include "gps_cnav_iono.h"
#include "gps_cnav_utc_model.h"
#include <bitset>
#include <stdint>
#include <map>
#include <string>
#include <utility>
#include <vector>
```

Classes

- class [Gps_CNAV_Navigation_Message](#)

This class decodes a GPS CNAV Data message as described in IS-GPS-200M.

Enumerations

- enum class **CnavSystem** { **GPS** , **QZSS** }

13.803.1 Detailed Description

Interface of a GPS CNAV Data message decoder.

Author

Javier Arribas, 2015. jarribas(at)cttc.es

Carles Fernandez Prades, 2015-2026. cfernandez(at)cttc.es

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 Definition in file [gps_cnav_navigation_message.h](#).

13.804 gps_cnav_navigation_message.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gps_cnav_navigation_message.h
00003  * \brief Interface of a GPS CNAV Data message decoder
00004  * \author Javier Arribas, 2015. jarribas(at)cttc.es
00005  * \author Carles Fernandez Prades, 2015-2026. cfernandez(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2026 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GPS_CNAV_NAVIGATION_MESSAGE_H
00020 #define GNSS_SDR_GPS_CNAV_NAVIGATION_MESSAGE_H
00021
00022
00023 #include "GPS_CNAV.h"
00024 #include "gps_cnav_ephemeris.h"
00025 #include "gps_cnav_iono.h"
00026 #include "gps_cnav_utc_model.h"
00027 #include <bitset>
00028 #include <stdint>
00029 #include <map>
00030 #include <string>
00031 #include <utility>
00032 #include <vector>
00033
00034 /** \addtogroup Core
00035  * \{ */
00036 /** \addtogroup System_Parameters
```

```

00037  * \{ */
00038
00039  enum class CnavSystem
00040  {
00041      GPS,
00042      QZSS
00043  };
00044
00045  /*!
00046  * \brief This class decodes a GPS CNAV Data message as described in IS-GPS-200M
00047  *
00048  * See https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf Appendix III
00049  */
00050  class Gps_CNAV_Navigation_Message
00051  {
00052  public:
00053      /*!
00054       * Default constructor
00055       */
00056      explicit Gps_CNAV_Navigation_Message(CnavSystem system = CnavSystem::GPS);
00057
00058      void decode_page(const std::bitset<GPS_CNAV_DATA_PAGE_BITS>& data_bits);
00059
00060      /*!
00061       * \brief Obtain a GPS SV Ephemeris class filled with current SV data
00062       */
00063      Gps_CNAV_Ephemeris get_ephemeris() const;
00064
00065      /*!
00066       * \brief Check if we have a new iono record stored in the GPS ephemeris class
00067       */
00068      bool have_new_iono();
00069
00070      /*!
00071       * \brief Obtain a GPS ionospheric correction parameters class filled with current SV data
00072       */
00073      Gps_CNAV_Iono get_iono() const;
00074
00075      /*!
00076       * \brief Obtain a GPS UTC model parameters class filled with current SV data
00077       */
00078      Gps_CNAV_Utc_Model get_utc_model();
00079
00080      /*!
00081       * \brief Check if we have a new GPS UTC model record stored in the GPS ephemeris class
00082       */
00083      bool have_new_utc_model();
00084
00085      /*!
00086       * \brief Check if we have a new ephemeris stored in the GPS ephemeris class
00087       */
00088      bool have_new_ephemeris();
00089
00090  private:
00091      uint64_t read_navigation_unsigned(const std::bitset<GPS_CNAV_DATA_PAGE_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00092      int64_t read_navigation_signed(const std::bitset<GPS_CNAV_DATA_PAGE_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00093      bool read_navigation_bool(const std::bitset<GPS_CNAV_DATA_PAGE_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00094
00095      Gps_CNAV_Ephemeris ephemeris_record{};
00096      Gps_CNAV_Iono iono_record{};
00097      Gps_CNAV_Utc_Model utc_model_record{};
00098
00099      std::map<int32_t, std::string> satelliteBlock; //!< Map that stores to which block the PRN
belongs https://www.navcen.uscg.gov/?Do=constellationStatus
00100
00101      CnavSystem d_system;
00102      int32_t d_TOW{};
00103
00104      bool b_flag_ephemeris_1{};
00105      bool b_flag_ephemeris_2{};
00106      bool b_flag_iono_valid{}; //!< If set, it indicates that the ionospheric parameters are filled
and are not yet read by the get_iono
00107      bool b_flag_utc_valid{}; //!< If set, it indicates that the utc parameters are filled and are
not yet read by the get_utc_model
00108  };
00109
00110
00111  /** \} */
00112  /** \} */
00113  #endif // GNSS_SDR_GPS_CNAV_NAVIGATION_MESSAGE_H

```

13.805 gps_cnav_utc_model.h File Reference

Interface of a GPS CNAV UTC MODEL storage.

```
#include "gps_utc_model.h"
```

Classes

- class [Gps_CNAV_Utc_Model](#)

This class is a storage for the GPS UTC MODEL data as described in in IS-GPS-200M.

13.805.1 Detailed Description

Interface of a GPS CNAV UTC MODEL storage.

Author

Javier Arribas, 2013. jarribas(at)cttc.es

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Definition in file [gps_cnav_utc_model.h](#).

13.806 gps_cnav_utc_model.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gps_cnav_utc_model.h
00003  * \brief Interface of a GPS CNAV UTC MODEL storage
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GPS_CNAV_UTC_MODEL_H
00019 #define GNSS_SDR_GPS_CNAV_UTC_MODEL_H
00020
00021 #include "gps_utc_model.h"
00022
00023 /** \addtogroup Core
00024  * \{ */
00025 /** \addtogroup System_Parameters
00026  * \{ */
00027
00028
00029 /*!
00030  * \brief This class is a storage for the GPS UTC MODEL data as described in in IS-GPS-200M
00031  *
00032  * See https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf Appendix III
00033  */
00034 class Gps_CNAV_Utc_Model : public Gps_Utc_Model
00035 {
00036 public:
00037     Gps_CNAV_Utc_Model() = default; //!< Default constructor
00038 };
00039
00040
00041 /** \} */
00042 /** \} */
00043 #endif // GNSS_SDR_GPS_CNAV_UTC_MODEL_H
```

13.807 gps_ephemeris.h File Reference

Interface of a GPS EPHEMERIS storage.

```
#include "gnss_ephemeris.h"
#include <boost/serialization/nvp.hpp>
#include <stdint>
#include <map>
#include <string>
```

Classes

- class [Gps_Ephemeris](#)

This class is a storage and orbital model functions for the GPS SV ephemeris data as described in IS-GPS-200M.

13.807.1 Detailed Description

Interface of a GPS EPHEMERIS storage.

Author

Javier Arribas, 2013. jarribas(at)cttc.es

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 Definition in file [gps_ephemeris.h](#).

13.808 gps_ephemeris.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file gps_ephemeris.h
00003  * \brief Interface of a GPS EPHEMERIS storage
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GPS_EPHEMERIS_H
00019 #define GNSS_SDR_GPS_EPHEMERIS_H
00020
00021
00022 #include "gnss_ephemeris.h"
00023 #include <boost/serialization/nvp.hpp>
00024 #include <stdint>
00025 #include <map>
00026 #include <string>
00027
00028 /** \addtogroup Core
00029  * \{ */
00030 /** \addtogroup System_Parameters
00031  * \{ */
00032
00033
00034 /*!
00035  * \brief This class is a storage and orbital model functions for the GPS SV
00036  * ephemeris data as described in IS-GPS-200M
00037  *
00038  * See https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf Appendix II
00039  */
00040 class Gps_Ephemeris : public Gnss_Ephemeris
00041 {
00042 public:
00043     /*!
00044      * Default constructor
00045      */
00046     Gps_Ephemeris();
00047
00048     int32_t code_on_L2{};    //!< If 1, P code ON in L2; if 2, C/A code ON in L2;
```

```

00049     bool L2_P_data_flag{}; //!< When true, indicates that the NAV data stream was commanded OFF on
the P-code of the L2 channel
00050     int32_t SV_accuracy{}; //!< User Range Accuracy (URA) index of the SV (reference paragraph 6.2.1)
for the standard positioning service user (Ref 20.3.3.3.1.3 IS-GPS-200M)
00051     int32_t SV_health{}; //!< Satellite health status
00052     double TGD{}; //!< Estimated Group Delay Differential: L1-L2 correction term only for
the benefit of "L1 P(Y)" or "L2 P(Y)" s users [s]
00053     int32_t IODC{}; //!< Issue of Data, Clock
00054     int32_t IODE_SF2{}; //!< Issue of Data, Ephemeris (IODE), subframe 2
00055     int32_t IODE_SF3{}; //!< Issue of Data, Ephemeris (IODE), subframe 3
00056     int32_t AODO{}; //!< Age of Data Offset (AODO) term for the navigation message correction
table (NMCT) contained in subframe 4 (reference paragraph 20.3.3.5.1.9) [s]
00057
00058     bool fit_interval_flag{}; //!< indicates the curve-fit interval used by the CS (Block
II/IIA/IIR/IIR-M/IIF) and SS (Block IIA) in determining the ephemeris parameters, as follows: 0 = 4
hours, 1 = greater than 4 hours.
00059     double spare1{};
00060     double spare2{};
00061
00062     // Flags
00063
00064     /*! \brief If true, enhanced level of integrity assurance.
00065     *
00066     * If false, indicates that the conveying signal is provided with the legacy level of integrity
assurance.
00067     * That is, the probability that the instantaneous URE of the conveying signal exceeds 4.42 times
the upper bound
00068     * value of the current broadcast URA index, for more than 5.2 seconds, without an accompanying
alert, is less
00069     * than 1E-5 per hour. If true, indicates that the conveying signal is provided with an enhanced
level of
00070     * integrity assurance. That is, the probability that the instantaneous URE of the conveying
signal exceeds 5.73
00071     * times the upper bound value of the current broadcast URA index, for more than 5.2 seconds,
without an
00072     * accompanying alert, is less than 1E-8 per hour.
00073     */
00074     bool integrity_status_flag{};
00075     bool alert_flag{}; //!< If true, indicates that the SV URA may be worse than indicated in
d_SV_accuracy, use that SV at our own risk.
00076     bool antispoofing_flag{}; //!< If true, the AntiSporofing mode is ON in that SV
00077
00078     std::map<int, std::string> satelliteBlock; //!< Map that stores to which block the PRN belongs
https://www.navcen.uscg.gov/?Do=constellationStatus
00079
00080     template <class Archive>
00081
00082     /*!
00083     * \brief Serialize is a boost standard method to be called by the boost XML
00084     * serialization. Here is used to save the ephemeris data on disk file.
00085     */
00086     inline void serialize(Archive& archive, const uint32_t version)
00087     {
00088         using boost::serialization::make_nvp;
00089         if (version)
00090         {
00091             };
00092
00093         archive& BOOST_SERIALIZATION_NVP (PRN);
00094         archive& BOOST_SERIALIZATION_NVP (M_0);
00095         archive& BOOST_SERIALIZATION_NVP (delta_n);
00096         archive& BOOST_SERIALIZATION_NVP (ecc);
00097         archive& BOOST_SERIALIZATION_NVP (sqrtA);
00098         archive& BOOST_SERIALIZATION_NVP (OMEGA_0);
00099         archive& BOOST_SERIALIZATION_NVP (i_0);
00100         archive& BOOST_SERIALIZATION_NVP (omega);
00101         archive& BOOST_SERIALIZATION_NVP (OMEGAdot);
00102         archive& BOOST_SERIALIZATION_NVP (idot);
00103         archive& BOOST_SERIALIZATION_NVP (Cuc);
00104         archive& BOOST_SERIALIZATION_NVP (Cus);
00105         archive& BOOST_SERIALIZATION_NVP (Crc);
00106         archive& BOOST_SERIALIZATION_NVP (Crs);
00107         archive& BOOST_SERIALIZATION_NVP (Cic);
00108         archive& BOOST_SERIALIZATION_NVP (Cis);
00109         archive& BOOST_SERIALIZATION_NVP (toe);
00110         archive& BOOST_SERIALIZATION_NVP (toc);
00111         archive& BOOST_SERIALIZATION_NVP (af0);
00112         archive& BOOST_SERIALIZATION_NVP (af1);
00113         archive& BOOST_SERIALIZATION_NVP (af2);
00114         archive& BOOST_SERIALIZATION_NVP (WN);
00115         archive& BOOST_SERIALIZATION_NVP (tow);
00116         archive& BOOST_SERIALIZATION_NVP (satClkDrift);
00117         archive& BOOST_SERIALIZATION_NVP (dtr);
00118
00119         archive& BOOST_SERIALIZATION_NVP (IODE_SF2);
00120         archive& BOOST_SERIALIZATION_NVP (IODE_SF3);
00121         archive& BOOST_SERIALIZATION_NVP (code_on_L2);

```

```

00122         archive& BOOST_SERIALIZATION_NVP (L2_P_data_flag);
00123         archive& BOOST_SERIALIZATION_NVP (SV_accuracy);
00124         archive& BOOST_SERIALIZATION_NVP (SV_health);
00125         archive& BOOST_SERIALIZATION_NVP (TGD);
00126         archive& BOOST_SERIALIZATION_NVP (IODC);
00127         archive& BOOST_SERIALIZATION_NVP (AODO);
00128         archive& BOOST_SERIALIZATION_NVP (fit_interval_flag);
00129         archive& BOOST_SERIALIZATION_NVP (spare1);
00130         archive& BOOST_SERIALIZATION_NVP (spare2);
00131         archive& BOOST_SERIALIZATION_NVP (integrity_status_flag);
00132         archive& BOOST_SERIALIZATION_NVP (alert_flag);
00133         archive& BOOST_SERIALIZATION_NVP (antispoofing_flag);
00134     }
00135 };
00136
00137
00138 /** @} */
00139 /** @} */
00140 #endif // GNSS_SDR_GPS_EPHEMERIS_H

```

13.809 gps_iono.h File Reference

Interface of a GPS IONOSPHERIC MODEL storage.

```
#include <boost/serialization/nvp.hpp>
```

Classes

- class [Gps_Iono](#)

This class is a storage for the GPS IONOSPHERIC data as described in IS-GPS-200M.

13.809.1 Detailed Description

Interface of a GPS IONOSPHERIC MODEL storage.

Author

Javier Arribas, 2013. jarribas(at)cttc.es

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Definition in file [gps_iono.h](#).

13.810 gps_iono.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file gps_iono.h
00003  * \brief Interface of a GPS IONOSPHERIC MODEL storage
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GPS_IONO_H
00019 #define GNSS_SDR_GPS_IONO_H
00020
00021
00022 #include <boost/serialization/nvp.hpp>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup System_Parameters
00027  * \{ */

```

```

00028
00029
00030 /*!
00031  * \brief This class is a storage for the GPS IONOSPHERIC data as described in IS-GPS-200M
00032  *
00033  * See https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf Appendix II
00034  */
00035 class Gps_Iono
00036 {
00037 public:
00038     Gps_Iono() = default;    //!< Default constructor
00039
00040     // Ionospheric parameters
00041     double alpha0{};    //!< Coefficient 0 of a cubic equation representing the amplitude of the
vertical delay [s]
00042     double alpha1{};    //!< Coefficient 1 of a cubic equation representing the amplitude of the
vertical delay [s/semi-circle]
00043     double alpha2{};    //!< Coefficient 2 of a cubic equation representing the amplitude of the
vertical delay [s(semi-circle)^2]
00044     double alpha3{};    //!< Coefficient 3 of a cubic equation representing the amplitude of the
vertical delay [s(semi-circle)^3]
00045     double beta0{};    //!< Coefficient 0 of a cubic equation representing the period of the model [s]
00046     double beta1{};    //!< Coefficient 1 of a cubic equation representing the period of the model
[s/semi-circle]
00047     double beta2{};    //!< Coefficient 2 of a cubic equation representing the period of the model
[s(semi-circle)^2]
00048     double beta3{};    //!< Coefficient 3 of a cubic equation representing the period of the model
[s(semi-circle)^3]
00049
00050     bool valid{};    //!< Valid flag
00051
00052     template <class Archive>
00053
00054     /*!
00055     * \brief Serialize is a boost standard method to be called by the boost XML
00056     * serialization. Here is used to save the ephemeris data on disk file.
00057     */
00058     inline void serialize(Archive& archive, const unsigned int version)
00059     {
00060         if (version)
00061         {
00062             archive& BOOST_SERIALIZATION_NVP(alpha0);
00063             archive& BOOST_SERIALIZATION_NVP(alpha1);
00064             archive& BOOST_SERIALIZATION_NVP(alpha2);
00065             archive& BOOST_SERIALIZATION_NVP(alpha3);
00066             archive& BOOST_SERIALIZATION_NVP(beta0);
00067             archive& BOOST_SERIALIZATION_NVP(beta1);
00068             archive& BOOST_SERIALIZATION_NVP(beta2);
00069             archive& BOOST_SERIALIZATION_NVP(beta3);
00070         }
00071     };
00072 };
00073
00074
00075 /** \} */
00076 /** \} */
00077 #endif // GNSS_SDR_GPS_IONO_H

```

13.811 GPS_L1_CA.h File Reference

Defines system parameters for GPS L1 C/A signal and NAV data.

```

#include "MATH_CONSTANTS.h"
#include "gnss_frequencies.h"
#include <cstdint>
#include <utility>
#include <vector>

```

Functions

- const std::vector< std::pair< int32_t, int32_t > > **TOW** ({{{31, 17}}})
- const std::vector< std::pair< int32_t, int32_t > > **INTEGRITY_STATUS_FLAG** ({{{23, 1}}})
- const std::vector< std::pair< int32_t, int32_t > > **ALERT_FLAG** ({{{48, 1}}})
- const std::vector< std::pair< int32_t, int32_t > > **ANTI_SPOOFING_FLAG** ({{{49, 1}}})
- const std::vector< std::pair< int32_t, int32_t > > **SUBFRAME_ID** ({{{50, 3}}})
- const std::vector< std::pair< int32_t, int32_t > > **GPS_WEEK** ({{{61, 10}}})

- `const std::vector< std::pair< int32_t, int32_t > > CA_OR_P_ON_L2` {{{71, 2}}}
- `const std::vector< std::pair< int32_t, int32_t > > SV_ACCURACY` {{{73, 4}}}
- `const std::vector< std::pair< int32_t, int32_t > > SV_HEALTH` {{{77, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > L2_P_DATA_FLAG` {{{91, 1}}}
- `const std::vector< std::pair< int32_t, int32_t > > T_GD` {{{197, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > IODC` {{{83, 2}, {211, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > T_OC` {{{219, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > A_F2` {{{241, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > A_F1` {{{249, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > A_F0` {{{271, 22}}}
- `const std::vector< std::pair< int32_t, int32_t > > IODE_SF2` {{{61, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > C_RS` {{{69, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > DELTA_N` {{{91, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > M_0` {{{107, 8}, {121, 24}}}
- `const std::vector< std::pair< int32_t, int32_t > > C_UC` {{{151, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > ECCENTRICITY` {{{167, 8}, {181, 24}}}
- `const std::vector< std::pair< int32_t, int32_t > > C_US` {{{211, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > SQRT_A` {{{227, 8}, {241, 24}}}
- `const std::vector< std::pair< int32_t, int32_t > > T_OE` {{{271, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > FIT_INTERVAL_FLAG` {{{271, 1}}}
- `const std::vector< std::pair< int32_t, int32_t > > AODO` {{{272, 5}}}
- `const std::vector< std::pair< int32_t, int32_t > > C_IC` {{{61, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_0` {{{77, 8}, {91, 24}}}
- `const std::vector< std::pair< int32_t, int32_t > > C_IS` {{{121, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > I_0` {{{137, 8}, {151, 24}}}
- `const std::vector< std::pair< int32_t, int32_t > > C_RC` {{{181, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA` {{{197, 8}, {211, 24}}}
- `const std::vector< std::pair< int32_t, int32_t > > OMEGA_DOT` {{{241, 24}}}
- `const std::vector< std::pair< int32_t, int32_t > > IODE_SF3` {{{271, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > I_DOT` {{{279, 14}}}
- `const std::vector< std::pair< int32_t, int32_t > > SV_DATA_ID` {{{61, 2}}}
- `const std::vector< std::pair< int32_t, int32_t > > SV_PAGE` {{{63, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALPHA_0` {{{69, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALPHA_1` {{{77, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALPHA_2` {{{91, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALPHA_3` {{{99, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > BETA_0` {{{107, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > BETA_1` {{{121, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > BETA_2` {{{129, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > BETA_3` {{{137, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > A_1` {{{151, 24}}}
- `const std::vector< std::pair< int32_t, int32_t > > A_0` {{{181, 24}, {211, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > T_OT` {{{219, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > WN_T` {{{227, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > DELTAT_LS` {{{241, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > WN_LSF` {{{249, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > DN` {{{257, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > DELTAT_LSF` {{{271, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV25` {{{229, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV26` {{{241, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV27` {{{247, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV28` {{{253, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV29` {{{259, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV30` {{{271, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV31` {{{277, 6}}}

- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV32` {{{283, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > T_OA` {{{69, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > WN_A` {{{77, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV1` {{{91, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV2` {{{97, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV3` {{{103, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV4` {{{109, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV5` {{{121, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV6` {{{127, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV7` {{{133, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV8` {{{139, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV9` {{{151, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV10` {{{157, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV11` {{{163, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV12` {{{169, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV13` {{{181, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV14` {{{187, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV15` {{{193, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV16` {{{199, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV17` {{{211, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV18` {{{217, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV19` {{{223, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV20` {{{229, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV21` {{{241, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV22` {{{247, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV23` {{{253, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > HEALTH_SV24` {{{259, 6}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALM_ECC` {{{69, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALM_TOA` {{{91, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALM_DELTAI` {{{99, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALM_OMEGADOT` {{{121, 16}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALM_SVHEALTH` {{{137, 8}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALM_SQUAREA` {{{151, 24}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALM_OMEGAZERO` {{{181, 24}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALM_OMEGA` {{{211, 24}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALM_MZERO` {{{241, 24}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALM_AF0` {{{271, 8}, {290, 3}}}
- `const std::vector< std::pair< int32_t, int32_t > > ALM_AF1` {{{279, 11}}}

Variables

- `constexpr double GPS_L1_FREQ_HZ = FREQ1`
L1 [Hz].
- `constexpr double GPS_L1_CA_CODE_RATE_CPS = 1.023e6`
GPS L1 C/A code rate [chips/s].
- `constexpr double GPS_L1_CA_CODE_LENGTH_CHIPS = 1023.0`
GPS L1 C/A code length [chips].
- `constexpr double GPS_L1_CA_CODE_PERIOD_S = 0.001`
GPS L1 C/A code period [seconds].
- `constexpr double GPS_L1_CA_CHIP_PERIOD_S = 9.7752e-07`
GPS L1 C/A chip period [seconds].
- `constexpr uint32_t GPS_L1_CA_CODE_PERIOD_MS = 1U`
GPS L1 C/A code period [ms].
- `constexpr uint32_t GPS_L1_CA_BIT_PERIOD_MS = 20U`

- constexpr double $\text{ALPHA} = \text{LSB} = \text{TWO}^{-N30}$

- constexpr double ALPHA_1_LSB = TWO_N27
- constexpr double ALPHA_2_LSB = TWO_N24
- constexpr double ALPHA_3_LSB = TWO_N24
- constexpr double BETA_0_LSB = TWO_P11
- constexpr double BETA_1_LSB = TWO_P14
- constexpr double BETA_2_LSB = TWO_P16
- constexpr double BETA_3_LSB = TWO_P16
- constexpr double A_1_LSB = TWO_N50
- constexpr double A_0_LSB = TWO_N30
- constexpr double T_OT_LSB = TWO_P12
- constexpr double WN_T_LSB = 1
- constexpr double DELTAT_LS_LSB = 1
- constexpr double WN_LSF_LSB = 1
- constexpr double DN_LSB = 1
- constexpr double DELTAT_LSF_LSB = 1
- constexpr int32_t T_OA_LSB = TWO_P12
- constexpr double ALM_ECC_LSB = TWO_N21
- constexpr int32_t ALM_TOA_LSB = static_cast<int32_t>(TWO_P12)
- constexpr double ALM_DELTAI_LSB = TWO_N19
- constexpr double ALM_OMEGADOT_LSB = TWO_N38
- constexpr double ALM_SQUAREA_LSB = TWO_N11
- constexpr double ALM_OMEGAZERO_LSB = TWO_N23
- constexpr double ALM_OMEGA_LSB = TWO_N23
- constexpr double ALM_MZERO_LSB = TWO_N23
- constexpr double ALM_AF0_LSB = TWO_N20
- constexpr double ALM_AF1_LSB = TWO_N38

13.811.1 Detailed Description

Defines system parameters for GPS L1 C/A signal and NAV data.

Author

Javier Arribas, 2011. jarribas(at)cttc.es

GNSS-SDR is a Global Navigation Satellite System software-defined receiver. This file is part of GNSS-SDR.

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 Definition in file [GPS_L1_CA.h](#).

13.812 GPS_L1_CA.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file GPS_L1_CA.h
00003  * \brief Defines system parameters for GPS L1 C/A signal and NAV data
00004  * \author Javier Arribas, 2011. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GPS_L1_CA_H
00019 #define GNSS_SDR_GPS_L1_CA_H
00020
00021 #include "MATH_CONSTANTS.h"
00022 #include "gnss_frequencies.h"
00023 #include <cstdint>

```

[illegible]

```

00099 const std::vector<std::pair<int32_t, int32_t>> A_F1({{249, 16}});
00100 constexpr double A_F1_LSB = TWO_N43;
00101 const std::vector<std::pair<int32_t, int32_t>> A_F0({{271, 22}});
00102 constexpr double A_F0_LSB = TWO_N31;
00103
00104 // SUBFRAME 2
00105 const std::vector<std::pair<int32_t, int32_t>> IODE_SF2({{61, 8}});
00106 const std::vector<std::pair<int32_t, int32_t>> C_RS({{69, 16}});
00107 constexpr double C_RS_LSB = TWO_N5;
00108 const std::vector<std::pair<int32_t, int32_t>> DELTA_N({{91, 16}});
00109 constexpr double DELTA_N_LSB = PI_TWO_N43;
00110 const std::vector<std::pair<int32_t, int32_t>> M_0({{107, 8}, {121, 24}});
00111 constexpr double M_0_LSB = PI_TWO_N31;
00112 const std::vector<std::pair<int32_t, int32_t>> C_UC({{151, 16}});
00113 constexpr double C_UC_LSB = TWO_N29;
00114 const std::vector<std::pair<int32_t, int32_t>> ECCENTRICITY({{167, 8}, {181, 24}});
00115 constexpr double ECCENTRICITY_LSB = TWO_N33;
00116 const std::vector<std::pair<int32_t, int32_t>> C_US({{211, 16}});
00117 constexpr double C_US_LSB = TWO_N29;
00118 const std::vector<std::pair<int32_t, int32_t>> SQRT_A({{227, 8}, {241, 24}});
00119 constexpr double SQRT_A_LSB = TWO_N19;
00120 const std::vector<std::pair<int32_t, int32_t>> T_OE({{271, 16}});
00121 constexpr int32_t T_OE_LSB = static_cast<int32_t>(TWO_P4);
00122 const std::vector<std::pair<int32_t, int32_t>> FIT_INTERVAL_FLAG({{271, 1}});
00123 const std::vector<std::pair<int32_t, int32_t>> AODO({{272, 5}});
00124 constexpr int32_t AODO_LSB = 900;
00125
00126 // SUBFRAME 3
00127 const std::vector<std::pair<int32_t, int32_t>> C_IC({{61, 16}});
00128 constexpr double C_IC_LSB = TWO_N29;
00129 const std::vector<std::pair<int32_t, int32_t>> OMEGA_0({{77, 8}, {91, 24}});
00130 constexpr double OMEGA_0_LSB = PI_TWO_N31;
00131 const std::vector<std::pair<int32_t, int32_t>> C_IS({{121, 16}});
00132 constexpr double C_IS_LSB = TWO_N29;
00133 const std::vector<std::pair<int32_t, int32_t>> I_0({{137, 8}, {151, 24}});
00134 constexpr double I_0_LSB = PI_TWO_N31;
00135 const std::vector<std::pair<int32_t, int32_t>> C_RC({{181, 16}});
00136 constexpr double C_RC_LSB = TWO_N5;
00137 const std::vector<std::pair<int32_t, int32_t>> OMEGA({{197, 8}, {211, 24}});
00138 constexpr double OMEGA_LSB = PI_TWO_N31;
00139 const std::vector<std::pair<int32_t, int32_t>> OMEGA_DOT({{241, 24}});
00140 constexpr double OMEGA_DOT_LSB = PI_TWO_N43;
00141 const std::vector<std::pair<int32_t, int32_t>> IODE_SF3({{271, 8}});
00142 const std::vector<std::pair<int32_t, int32_t>> I_DOT({{279, 14}});
00143 constexpr double I_DOT_LSB = PI_TWO_N43;
00144
00145 // SUBFRAME 4-5
00146 const std::vector<std::pair<int32_t, int32_t>> SV_DATA_ID({{61, 2}});
00147 const std::vector<std::pair<int32_t, int32_t>> SV_PAGE({{63, 6}});
00148
00149 // SUBFRAME 4
00150 //! \todo read all pages of subframe 4
00151 // Page 18 - Ionospheric and UTC data
00152 const std::vector<std::pair<int32_t, int32_t>> ALPHA_0({{69, 8}});
00153 constexpr double ALPHA_0_LSB = TWO_N30;
00154 const std::vector<std::pair<int32_t, int32_t>> ALPHA_1({{77, 8}});
00155 constexpr double ALPHA_1_LSB = TWO_N27;
00156 const std::vector<std::pair<int32_t, int32_t>> ALPHA_2({{91, 8}});
00157 constexpr double ALPHA_2_LSB = TWO_N24;
00158 const std::vector<std::pair<int32_t, int32_t>> ALPHA_3({{99, 8}});
00159 constexpr double ALPHA_3_LSB = TWO_N24;
00160 const std::vector<std::pair<int32_t, int32_t>> BETA_0({{107, 8}});
00161 constexpr double BETA_0_LSB = TWO_P11;
00162 const std::vector<std::pair<int32_t, int32_t>> BETA_1({{121, 8}});
00163 constexpr double BETA_1_LSB = TWO_P14;
00164 const std::vector<std::pair<int32_t, int32_t>> BETA_2({{129, 8}});
00165 constexpr double BETA_2_LSB = TWO_P16;
00166 const std::vector<std::pair<int32_t, int32_t>> BETA_3({{137, 8}});
00167 constexpr double BETA_3_LSB = TWO_P16;
00168 const std::vector<std::pair<int32_t, int32_t>> A_1({{151, 24}});
00169 constexpr double A_1_LSB = TWO_N50;
00170 const std::vector<std::pair<int32_t, int32_t>> A_0({{181, 24}, {211, 8}});
00171 constexpr double A_0_LSB = TWO_N30;
00172 const std::vector<std::pair<int32_t, int32_t>> T_OT({{219, 8}});
00173 constexpr double T_OT_LSB = TWO_P12;
00174 const std::vector<std::pair<int32_t, int32_t>> WN_T({{227, 8}});
00175 constexpr double WN_T_LSB = 1;
00176 const std::vector<std::pair<int32_t, int32_t>> DELTAT_LS({{241, 8}});
00177 constexpr double DELTAT_LS_LSB = 1;
00178 const std::vector<std::pair<int32_t, int32_t>> WN_LSF({{249, 8}});
00179 constexpr double WN_LSF_LSB = 1;
00180 const std::vector<std::pair<int32_t, int32_t>> DN({{257, 8}});
00181 constexpr double DN_LSB = 1;
00182 const std::vector<std::pair<int32_t, int32_t>> DELTAT_LSF({{271, 8}});
00183 constexpr double DELTAT_LSF_LSB = 1;
00184
00185 // Page 25 - Antispoofing, SV config and SV health (PRN 25 -32)

```



```

00186 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV25({{229, 6}});
00187 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV26({{241, 6}});
00188 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV27({{247, 6}});
00189 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV28({{253, 6}});
00190 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV29({{259, 6}});
00191 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV30({{271, 6}});
00192 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV31({{277, 6}});
00193 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV32({{283, 6}});
00194
00195
00196 // SUBFRAME 5
00197 //!< \todo read all pages of subframe 5
00198
00199 // page 25 - Health (PRN 1 - 24)
00200 const std::vector<std::pair<int32_t, int32_t>> T_OA({{69, 8}});
00201 constexpr int32_t T_OA_LSB = TWO_P12;
00202 const std::vector<std::pair<int32_t, int32_t>> WN_A({{77, 8}});
00203 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV1({{91, 6}});
00204 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV2({{97, 6}});
00205 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV3({{103, 6}});
00206 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV4({{109, 6}});
00207 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV5({{121, 6}});
00208 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV6({{127, 6}});
00209 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV7({{133, 6}});
00210 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV8({{139, 6}});
00211 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV9({{151, 6}});
00212 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV10({{157, 6}});
00213 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV11({{163, 6}});
00214 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV12({{169, 6}});
00215 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV13({{181, 6}});
00216 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV14({{187, 6}});
00217 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV15({{193, 6}});
00218 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV16({{199, 6}});
00219 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV17({{211, 6}});
00220 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV18({{217, 6}});
00221 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV19({{223, 6}});
00222 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV20({{229, 6}});
00223 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV21({{241, 6}});
00224 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV22({{247, 6}});
00225 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV23({{253, 6}});
00226 const std::vector<std::pair<int32_t, int32_t>> HEALTH_SV24({{259, 6}});
00227
00228
00229 // Almanac
00230 const std::vector<std::pair<int32_t, int32_t>> ALM_ECC({{69, 16}});
00231 constexpr double ALM_ECC_LSB = TWO_N21;
00232 const std::vector<std::pair<int32_t, int32_t>> ALM_TOA({{91, 8}});
00233 constexpr int32_t ALM_TOA_LSB = static_cast<int32_t>(TWO_P12);
00234 const std::vector<std::pair<int32_t, int32_t>> ALM_DELTAT({{99, 16}});
00235 constexpr double ALM_DELTAT_LSB = TWO_N19;
00236 const std::vector<std::pair<int32_t, int32_t>> ALM_OMEGADOT({{121, 16}});
00237 constexpr double ALM_OMEGADOT_LSB = TWO_N38;
00238 const std::vector<std::pair<int32_t, int32_t>> ALM_SVHEALTH({{137, 8}});
00239 const std::vector<std::pair<int32_t, int32_t>> ALM_SQUAREA({{151, 24}});
00240 constexpr double ALM_SQUAREA_LSB = TWO_N11;
00241 const std::vector<std::pair<int32_t, int32_t>> ALM_OMEGAZERO({{181, 24}});
00242 constexpr double ALM_OMEGAZERO_LSB = TWO_N23;
00243 const std::vector<std::pair<int32_t, int32_t>> ALM_OMEGA({{211, 24}});
00244 constexpr double ALM_OMEGA_LSB = TWO_N23;
00245 const std::vector<std::pair<int32_t, int32_t>> ALM_MZERO({{241, 24}});
00246 constexpr double ALM_MZERO_LSB = TWO_N23;
00247
00248 const std::vector<std::pair<int32_t, int32_t>> ALM_AF0({{271, 8}, {290, 3}});
00249 constexpr double ALM_AF0_LSB = TWO_N20;
00250 const std::vector<std::pair<int32_t, int32_t>> ALM_AF1({{279, 11}});
00251 constexpr double ALM_AF1_LSB = TWO_N38;
00252 /** \} */
00253 /** \} */
00254 #endif // GNSS_SDR_GPS_L1_CA_H

```

13.813 GPS_L2C.h File Reference

Defines system parameters for GPS L2C signal.

```

#include "GPS_CNAV.h"
#include "gnss_frequencies.h"
#include <stdint>
#include <utility>
#include <vector>

```

Variables

- constexpr double `GPS_L2_FREQ_HZ` = `FREQ2`
L2 [Hz].
- constexpr double `GPS_L2_L_PERIOD_S` = 1.5
GPS L2 L code period [seconds].
- constexpr double `GPS_L2_M_CODE_RATE_CPS` = 0.5115e6
GPS L2 M code rate [chips/s].
- constexpr double `GPS_L2_M_CODE_RATE_L_ZEROED_CPS` = 1.023e6
GPS L2 M code rate with L2 M Zeroed [chips/s].
- constexpr double `GPS_L2_M_PERIOD_S` = 0.02
GPS L2 M code period [seconds].
- constexpr double `GPS_L2_L_CODE_RATE_CPS` = 0.5115e6
GPS L2 L code rate [chips/s].
- constexpr uint32_t `GPS_L2_M_CODE_PERIOD_MS` = 20
GPS L2 L code period [ms].
- constexpr int32_t `GPS_L2_M_CODE_LENGTH_CHIPS` = 10230
GPS L2 M code length [chips].
- constexpr int32_t `GPS_L2_M_CODE_LENGTH_CHIPS_L_ZEROED` = 2 * `GPS_L2_M_CODE_LENGTH_CHIPS`
GPS L2 M code length with L2 CL zeroed [chips].
- constexpr int32_t `GPS_L2_L_CODE_LENGTH_CHIPS` = 767250
GPS L2 L code length [chips].
- constexpr int32_t `GPS_L2_CNAV_DATA_PAGE_BITS` = 300
GPS L2 CNAV page length, including preamble and CRC [bits].
- constexpr int32_t `GPS_L2_SYMBOLS_PER_BIT` = 2
- constexpr int32_t `GPS_L2_SAMPLES_PER_SYMBOL` = 1
- constexpr int32_t `GPS_L2_CNAV_DATA_PAGE_SYMBOLS` = 600
- constexpr int32_t `GPS_L2_CNAV_DATA_PAGE_DURATION_S` = 12
- constexpr int32_t `GPS_L2C_HISTORY_DEEP` = 5
- constexpr uint32_t `GPS_L2C_OPT_ACQ_FS_SPS` = 2000000
Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.
- constexpr int32_t `GPS_L2C_M_INIT_REG` [115]

13.813.1 Detailed Description

Defines system parameters for GPS L2C signal.

Author

Javier Arribas, 2015. jarribas(at)cttc.es

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Definition in file [GPS_L2C.h](#).

13.814 GPS_L2C.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file GPS_L2C.h
00003  * \brief Defines system parameters for GPS L2C signal
00004  * \author Javier Arribas, 2015. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
```



```

00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GPS_L2C_H
00019 #define GNSS_SDR_GPS_L2C_H
00020
00021
00022 #include "GPS_CNAV.h"
00023 #include "gnss_frequencies.h"
00024 #include <stdint>
00025 #include <utility> // std::pair
00026 #include <vector>
00027
00028 /** \addtogroup Core
00029  * \{ */
00030 /** \addtogroup System_Parameters
00031  * \{ */
00032
00033
00034 // carrier and code frequencies
00035 constexpr double GPS_L2_FREQ_HZ = FREQ2; //!< L2 [Hz]
00036 constexpr double GPS_L2_L_PERIOD_S = 1.5; //!< GPS L2 L
00037     code period [seconds]
00038     code rate [chips/s]
00037 constexpr double GPS_L2_M_CODE_RATE_CPS = 0.5115e6; //!< GPS L2 M
00038     code rate with L2 M Zeroed [chips/s]
00038 constexpr double GPS_L2_M_CODE_RATE_L_ZEROED_CPS = 1.023e6; //!< GPS L2 M
00039     code rate with L2 M Zeroed [chips/s]
00039 constexpr double GPS_L2_M_PERIOD_S = 0.02; //!< GPS L2 M
00040     code period [seconds]
00040 constexpr double GPS_L2_L_CODE_RATE_CPS = 0.5115e6; //!< GPS L2 L
00041     code rate [chips/s]
00041 constexpr uint32_t GPS_L2_M_CODE_PERIOD_MS = 20; //!< GPS L2
00042     L code period [ms]
00042 constexpr int32_t GPS_L2_M_CODE_LENGTH_CHIPS = 10230; //!< GPS L2 M
00043     code length [chips]
00043 constexpr int32_t GPS_L2_M_CODE_LENGTH_CHIPS_L_ZEROED = 2 * GPS_L2_M_CODE_LENGTH_CHIPS; //!< GPS L2 M
00044     code length with L2 CL zeroed [chips]
00044 constexpr int32_t GPS_L2_L_CODE_LENGTH_CHIPS = 767250; //!< GPS L2 L
00045     code length [chips]
00045 constexpr int32_t GPS_L2_CNAV_DATA_PAGE_BITS = 300; //!< GPS L2
00046     CNAV page length, including preamble and CRC [bits]
00046 constexpr int32_t GPS_L2_SYMBOLS_PER_BIT = 2;
00047 constexpr int32_t GPS_L2_SAMPLES_PER_SYMBOL = 1;
00048 constexpr int32_t GPS_L2_CNAV_DATA_PAGE_SYMBOLS = 600;
00049 constexpr int32_t GPS_L2_CNAV_DATA_PAGE_DURATION_S = 12;
00050
00051 constexpr int32_t GPS_L2C_HISTORY_DEEP = 5;
00052
00053 // optimum parameters
00054 constexpr uint32_t GPS_L2C_OPT_ACQ_FS_SPS = 2000000; //!< Sampling frequency that maximizes the
00055     acquisition SNR while using a non-multiple of chip rate
00055
00056 constexpr int32_t GPS_L2C_M_INIT_REG[115] =
00057     {0742417664, 0756014035, 0002747144, 0066265724, // 1:4
00058     0601403471, 0703232733, 0124510070, 0617316361, // 5:8
00059     0047541621, 0733031046, 0713512145, 0024437606,
00060     0021264003, 0230655351, 0001314400, 0222021506,
00061     0540264026, 0205521705, 0064022144, 0120161274,
00062     0044023533, 0724744327, 0045743577, 0741201660,
00063     0700274134, 0010247261, 0713433445, 0737324162,
00064     0311627434, 0710452007, 0722462133, 0050172213,
00065     0500653703, 0755077436, 0136717361, 0756675453,
00066     0435506112, 0771353753, 0226107701, 0022025110,
00067     0402466344, 0752566114, 0702011164, 0041216771,
00068     0047457275, 0266333164, 0713167356, 0060546335,
00069     0355173035, 0617201036, 0157465571, 0767360553,
00070     0023127030, 0431343777, 0747317317, 0045706125,
00071     0002744276, 0060036467, 0217744147, 0603340174, // 57:60
00072     0326616775, 0063240065, 0111460621, // 61:63
00073     0604055104, 0157065232, 0013305707, 0603552017, // 159:162
00074     0230461355, 0603653437, 0652346475, 0743107103,
00075     0401521277, 0167335110, 0014013575, 0362051132,
00076     0617753265, 0216363634, 0755561123, 0365304033,
00077     0625025543, 0054420334, 0415473671, 0662364360,
00078     0373446602, 0417564100, 0000526452, 0226631300,
00079     0113752074, 0706134401, 0041352546, 0664630154,
00080     0276524255, 0714720530, 0714051771, 0044526647,
00081     0207164322, 0262120161, 0204244652, 0202133131,
00082     0714351204, 0657127260, 0130567507, 0670517677,
00083     0607275514, 0045413633, 0212645405, 0613700455,
00084     0706202440, 0705056276, 0020373522, 0746013617,
00085     0132720621, 0434015513, 0566721727, 0140633660};
00086
00087

```

```

00088 /** \} */
00089 /** \} */
00090 #endif // GNSS_SDR_GPS_L2C_H

```

13.815 GPS_L5.h File Reference

Defines system parameters for GPS L5 signal.

```

#include "GPS_CNAV.h"
#include "gnss_frequencies.h"
#include <stdint>

```

Variables

- constexpr double [GPS_L5_FREQ_HZ](#) = [FREQ5](#)
L5 [Hz].
- constexpr double [GPS_L5I_CODE_RATE_CPS](#) = 10.23e6
GPS L5I code rate [chips/s].
- constexpr double [GPS_L5I_PERIOD_S](#) = 0.001
GPS L5I code period [seconds].
- constexpr double [GPS_L5I_SYMBOL_PERIOD_S](#) = 0.01
GPS L5I symbol period [seconds].
- constexpr double [GPS_L5Q_CODE_RATE_CPS](#) = 10.23e6
GPS L5Q code rate [chips/s].
- constexpr double [GPS_L5Q_PERIOD_S](#) = 0.001
GPS L5Q code period [seconds].
- constexpr int32_t [GPS_L5Q_CODE_LENGTH_CHIPS](#) = 10230
GPS L5Q code length [chips].
- constexpr int32_t [GPS_L5I_CODE_LENGTH_CHIPS](#) = 10230
GPS L5I code length [chips].
- constexpr int32_t [GPS_L5I_PERIOD_MS](#) = 1
GPS L5I code period [ms].
- constexpr int32_t [GPS_L5I_SYMBOL_PERIOD_MS](#) = 10
GPS L5I symbol period [ms].
- constexpr int32_t [GPS_L5_HISTORY_DEEP](#) = 5
- constexpr uint32_t [GPS_L5_OPT_ACQ_FS_SPS](#) = 10000000
Sampling frequency that maximizes the acquisition SNR while using a non-multiple of chip rate.
- constexpr int32_t [GPS_L5I_INIT_REG](#) [210]
- constexpr int32_t [GPS_L5Q_INIT_REG](#) [210]
- constexpr int32_t [GPS_L5_CNAV_DATA_PAGE_BITS](#) = 300
GPS L5 CNAV page length, including preamble and CRC [bits].
- constexpr int32_t [GPS_L5_SYMBOLS_PER_BIT](#) = 2
- constexpr int32_t [GPS_L5_SAMPLES_PER_SYMBOL](#) = 10
- constexpr int32_t [GPS_L5_CNAV_DATA_PAGE_SYMBOLS](#) = 600
- constexpr int32_t [GPS_L5_CNAV_DATA_PAGE_DURATION_S](#) = 6
- constexpr int32_t [GPS_L5I_NH_CODE_LENGTH](#) = 10
- constexpr int32_t [GPS_L5I_NH_CODE](#) [10] = {0, 0, 0, 0, 1, 1, 0, 1, 0, 1}
- constexpr int32_t [GPS_L5Q_NH_CODE_LENGTH](#) = 20
- constexpr int32_t [GPS_L5Q_NH_CODE](#) [20] = {0, 0, 0, 0, 0, 1, 0, 0, 1, 1, 0, 1, 0, 1, 0, 0, 1, 1, 1, 0}
- constexpr char [GPS_L5I_NH_CODE_STR](#) [11] = "0000110101"
- constexpr char [GPS_L5Q_NH_CODE_STR](#) [21] = "00000100110101001110"

13.815.1 Detailed Description

Defines system parameters for GPS L5 signal.

Author

Javier Arribas, 2017. jarribas(at)cttc.es

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 Definition in file [GPS_L5.h](#).

13.816 GPS_L5.h

[Go to the documentation of this file.](#)

```
00001 /*!
00002  * \file GPS_L5.h
00003  * \brief Defines system parameters for GPS L5 signal
00004  * \author Javier Arribas, 2017. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GPS_L5_H
00019 #define GNSS_SDR_GPS_L5_H
00020
00021 #include "GPS_CNAV.h"
00022 #include "gnss_frequencies.h"
00023 #include <cstdint>
00024
00025 /** \addtogroup Core
00026  * \{ */
00027 /** \addtogroup System_Parameters
00028  * \{ */
00029
00030
00031 // carrier and code frequencies
00032 constexpr double GPS_L5_FREQ_HZ = FREQ5;          //!< L5 [Hz]
00033 constexpr double GPS_L5I_CODE_RATE_CPS = 10.23e6;  //!< GPS L5I code rate [chips/s]
00034 constexpr double GPS_L5I_PERIOD_S = 0.001;         //!< GPS L5I code period [seconds]
00035 constexpr double GPS_L5I_SYMBOL_PERIOD_S = 0.01;   //!< GPS L5I symbol period [seconds]
00036 constexpr double GPS_L5Q_CODE_RATE_CPS = 10.23e6;  //!< GPS L5Q code rate [chips/s]
00037 constexpr double GPS_L5Q_PERIOD_S = 0.001;         //!< GPS L5Q code period [seconds]
00038 constexpr int32_t GPS_L5Q_CODE_LENGTH_CHIPS = 10230;  //!< GPS L5Q code length [chips]
00039 constexpr int32_t GPS_L5I_CODE_LENGTH_CHIPS = 10230;  //!< GPS L5I code length [chips]
00040 constexpr int32_t GPS_L5I_PERIOD_MS = 1;             //!< GPS L5I code period [ms]
00041 constexpr int32_t GPS_L5I_SYMBOL_PERIOD_MS = 10;     //!< GPS L5I symbol period [ms]
00042
00043 constexpr int32_t GPS_L5_HISTORY_DEEP = 5;
00044
00045 // optimum parameters
00046 constexpr uint32_t GPS_L5_OPT_ACQ_FS_SPS = 10000000;  //!< Sampling frequency that maximizes the
00047               acquisition SNR while using a non-multiple of chip rate
00048
00049 constexpr int32_t GPS_L5I_INIT_REG[210] =
00050     {266, 365, 804, 1138,
00051      1509, 1559, 1756, 2084,
00052      2170, 2303, 2527, 2687,
00053      2930, 3471, 3940, 4132,
00054      4332, 4924, 5343, 5443,
00055      5641, 5816, 5898, 5918,
00056      5955, 6243, 6345, 6477,
00057      6518, 6875, 7168, 7187,
00058      7329, 7577, 7720, 7777,
00059      8057, 5358, 3550, 3412,
00060      819,
00061      4608, 3698, 962, 3001,
00062      4441, 4937, 3717, 4730,
00063      7291, 2279, 7613, 5723,
00064      7030, 1475, 2593, 2904,
00065      2056, 2757, 3756, 6205,
00066      5053, 6437,
00067      7789, 2311, 7432, 5155,
```

```
00067      1593, 5841, 5014, 1545,
00068      3016, 4875, 2119, 229,
00069      7634, 1406, 4506, 1819,
00070      7580, 5446, 6053, 7958,
00071      5267, 2956, 3544, 1277,
00072      2996, 1758, 3360, 2718,
00073      3754, 7440, 2781, 6756,
00074      7314, 208, 5252, 696,
00075      527, 1399, 5879, 6868,
00076      217, 7681, 3788, 1337,
00077      2424, 4243, 5686, 1955,
00078      4791, 492, 1518, 6566,
00079      5349, 506, 113, 1953,
00080      2797, 934, 3023, 3632,
00081      1330, 4909, 4867, 1183,
00082      3990, 6217, 1224, 1733,
00083      2319, 3928, 2380, 841,
00084      5049, 7027, 1197, 7208,
00085      8000, 152, 6762, 3745,
00086      4723, 5502, 4796, 123,
00087      8142, 5091, 7875, 330,
00088      5272, 4912, 374, 2045,
00089      6616, 6321, 7605, 2570,
00090      2419, 1234, 1922, 4317,
00091      5110, 825, 958, 1089,
00092      7813, 6058, 7703, 6702,
00093      1714, 6371, 2281, 1986,
00094      6282, 3201, 3760, 1056,
00095      6233, 1150, 2823, 6250,
00096      645, 2401, 1639, 2946,
00097      7091, 923, 7045, 6493,
00098      1706, 5836, 926, 6086,
00099      950, 5905, 3240, 6675,
00100      3197, 1555, 3589, 4555,
00101      5671, 6948, 4664, 2086,
00102      5950, 5521, 1515};
00103
00104
00105  constexpr int32_t GPS_L5Q_INIT_REG[210] =
00106      {
00107          1701, 323, 5292, 2020,
00108          5429, 7136, 1041, 5947,
00109          4315, 148, 535, 1939,
00110          5206, 5910, 3595, 5135,
00111          6082, 6990, 3546, 1523,
00112          4548, 4484, 1893, 3961,
00113          7106, 5299, 4660, 276,
00114          4389, 3783, 1591, 1601,
00115          749, 1387, 1661, 3210,
00116          708,
00117          4226, 5604, 6375, 3056,
00118          1772, 3662, 4401, 5218,
00119          2838, 6913, 1685, 1194,
00120          6963, 5001, 6694, 991,
00121          7489, 2441, 639, 2097,
00122          2498, 6470, 2399, 242,
00123          3768, 1186,
00124          5246, 4259, 5907, 3870,
00125          3262, 7387, 3069, 2999,
00126          7993, 7849, 4157, 5031,
00127          5986, 4833, 5739, 7846,
00128          898, 2022, 7446, 6404,
00129          155, 7862, 7795, 6121,
00130          4840, 6585, 429, 6020,
00131          200, 1664, 1499, 7298,
00132          1305, 7323, 7544, 4438,
00133          2485, 3387, 7319, 1853,
00134          5781, 1874, 7555, 2132,
00135          6441, 6722, 1192, 2588,
00136          2188, 297, 1540, 4138,
00137          5231, 4789, 659, 871,
00138          6837, 1393, 7383, 611,
00139          4920, 5416, 1611, 2474,
00140          118, 1382, 1092, 7950,
00141          7223, 1769, 4721, 1252,
00142          5147, 2165, 7897, 4054,
00143          3498, 6571, 2858, 8126,
00144          7017, 1901, 181, 1114,
00145          5195, 7479, 4186, 3904,
00146          7128, 1396, 4513, 5967,
00147          2580, 2575, 7961, 2598,
00148          4508, 2090, 3685, 7748,
00149          684, 913, 5558, 2894,
00150          5858, 6432, 3813, 3573,
00151          7523, 5280, 3376, 7424,
00152          2918, 5793, 1747, 7079,
00153          2921, 2490, 4119, 3373,
```

```

00154         977, 681, 4273, 5419,
00155         5626, 1266, 5804, 2414,
00156         6444, 4757, 427, 5452,
00157         5182, 6606, 6531, 4268,
00158         3115, 6835, 862, 4856,
00159         2765, 37, 1943, 7977,
00160         2512, 4451, 4071};
00161
00162 constexpr int32_t GPS_L5_CNAV_DATA_PAGE_BITS = 300; //!< GPS L5 CNAV page length, including preamble
           and CRC [bits]
00163 constexpr int32_t GPS_L5_SYMBOLS_PER_BIT = 2;
00164 constexpr int32_t GPS_L5_SAMPLES_PER_SYMBOL = 10;
00165 constexpr int32_t GPS_L5_CNAV_DATA_PAGE_SYMBOLS = 600;
00166 constexpr int32_t GPS_L5_CNAV_DATA_PAGE_DURATION_S = 6;
00167 constexpr int32_t GPS_L5I_NH_CODE_LENGTH = 10;
00168 constexpr int32_t GPS_L5I_NH_CODE[10] = {0, 0, 0, 0, 1, 1, 0, 1, 0, 1};
00169 constexpr int32_t GPS_L5Q_NH_CODE_LENGTH = 20;
00170 constexpr int32_t GPS_L5Q_NH_CODE[20] = {0, 0, 0, 0, 0, 1, 0, 0, 1, 1, 0, 1, 0, 1, 0, 0, 1, 1, 1, 0};
00171 constexpr char GPS_L5I_NH_CODE_STR[11] = "0000110101";
00172 constexpr char GPS_L5Q_NH_CODE_STR[21] = "00000100110101001110";
00173
00174
00175 /** \} */
00176 /** \} */
00177 #endif // GNSS_SDR_GPS_L5_H

```

13.817 gps_navigation_message.h File Reference

Interface of a GPS NAV Data message decoder.

```

#include "GPS_L1_CA.h"
#include "gps_almanac.h"
#include "gps_ephemeris.h"
#include "gps_iono.h"
#include "gps_utc_model.h"
#include <bitset>
#include <cstdint>
#include <map>
#include <string>
#include <utility>
#include <vector>

```

Classes

- class [Gps_Navigation_Message](#)

This class decodes a GPS NAV Data message as described in IS-GPS-200M.

Enumerations

- enum class **LnavSystem** { **GPS**, **QZSS** }

13.817.1 Detailed Description

Interface of a GPS NAV Data message decoder.

Author

Javier Arribas, 2011. jarribas(at)cttc.es

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Definition in file [gps_navigation_message.h](#).

13.818 gps_navigation_message.h

[Go to the documentation of this file.](#)

```
00001 /*!
```

```

00002  * \file gps_navigation_message.h
00003  * \brief Interface of a GPS NAV Data message decoder
00004  * \author Javier Arribas, 2011. jarribas(at)cttc.es
00005  *
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_GPS_NAVIGATION_MESSAGE_H
00020 #define GNSS_SDR_GPS_NAVIGATION_MESSAGE_H
00021
00022
00023 #include "GPS_L1_CA.h"
00024 #include "gps_almanac.h"
00025 #include "gps_ephemeris.h"
00026 #include "gps_iono.h"
00027 #include "gps_utc_model.h"
00028 #include <bitset>
00029 #include <cstdint>
00030 #include <map>
00031 #include <string>
00032 #include <utility> // for pair
00033 #include <vector>
00034
00035 /** \addtogroup Core
00036  * \{ */
00037 /** \addtogroup System_Parameters
00038  * \{ */
00039
00040 enum class LnavSystem
00041 {
00042     GPS,
00043     QZSS
00044 };
00045
00046 /*!
00047  * \brief This class decodes a GPS NAV Data message as described in IS-GPS-200M
00048  *
00049  * See https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf Appendix II
00050  */
00051 class Gps_Navigation_Message
00052 {
00053 public:
00054     /*!
00055      * Default constructor
00056      */
00057     explicit Gps_Navigation_Message(LnavSystem system = LnavSystem::GPS);
00058
00059     /*!
00060      * \brief Obtain a GPS SV Ephemeris class filled with current SV data
00061      */
00062     Gps_Ephemeris get_ephemeris() const;
00063
00064     /*!
00065      * \brief Obtain a GPS ionospheric correction parameters class filled with current SV data
00066      */
00067     Gps_Iono get_iono();
00068
00069     /*!
00070      * \brief Obtain a GPS almanac class filled with current SV data
00071      */
00072     Gps_Almanac get_almanac();
00073
00074     /*!
00075      * \brief Obtain a GPS Almanac model parameters class filled with current SV data
00076      */
00077     Gps_Utc_Model get_utc_model();
00078
00079     /*!
00080      * \brief Decodes the GPS NAV message
00081      */
00082     int32_t subframe_decoder(const char* subframe);
00083
00084     /*!
00085      * \brief Computes the Coordinated Universal Time (UTC) and
00086      * returns it in [s] (IS-GPS-200M, 20.3.3.5.2.4)
00087      */
00088     double utc_time(double gpstime_corrected) const;

```

```

00089
00090     /*!
00091      * \brief Gets Time of Week, in seconds
00092      */
00093     inline int32_t get_TOW() const
00094     {
00095         return d_TOW;
00096     }
00097
00098     /*!
00099      * \brief Gets GPS Week Number
00100      */
00101     inline int32_t get_GPS_week() const
00102     {
00103         return i_GPS_week;
00104     }
00105
00106     /*!
00107      * \brief Sets satellite PRN number
00108      */
00109     inline void set_satellite_PRN(uint32_t prn)
00110     {
00111         i_satellite_PRN = prn;
00112     }
00113
00114     /*!
00115      * \brief Gets satellite PRN number
00116      */
00117     inline uint32_t get_satellite_PRN() const
00118     {
00119         return i_satellite_PRN;
00120     }
00121
00122     /*!
00123      * \brief Sets channel ID
00124      */
00125     inline void set_channel(int32_t channel_id)
00126     {
00127         i_channel_ID = channel_id;
00128     }
00129
00130     /*!
00131      * \brief Gets flag_iono_valid
00132      */
00133     inline bool get_flag_iono_valid() const
00134     {
00135         return flag_iono_valid;
00136     }
00137
00138     /*!
00139      * \brief Gets flag_utc_model_valid
00140      */
00141     inline bool get_flag_utc_model_valid() const
00142     {
00143         return flag_utc_model_valid;
00144     }
00145
00146     bool satellite_validation();
00147     bool almanac_validation() const;
00148
00149 private:
00150     uint64_t read_navigation_unsigned(const std::bitset<GPS_SUBFRAME_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00151     int64_t read_navigation_signed(const std::bitset<GPS_SUBFRAME_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00152     bool read_navigation_bool(const std::bitset<GPS_SUBFRAME_BITS>& bits, const
std::vector<std::pair<int32_t, int32_t>& parameter) const;
00153     void print_gps_word_bytes(uint32_t GPS_word) const;
00154
00155     std::map<int32_t, int32_t> almanacHealth; //!< Map that stores the health information stored in
the almanac
00156
00157     std::map<int32_t, std::string> satelliteBlock; //!< Map that stores to which block the PRN
belongs https://www.navcen.uscg.gov/?Do=constellationStatus
00158
00159     LnavSystem d_system;
00160
00161     // broadcast orbit 1
00162     int32_t d_TOW{}; // Time of GPS Week of the ephemeris set (taken from subframes TOW) [s]
00163     int32_t d_TOW_SF1{}; // Time of GPS Week from HOW word of Subframe 1 [s]
00164     int32_t d_TOW_SF2{}; // Time of GPS Week from HOW word of Subframe 2 [s]
00165     int32_t d_TOW_SF3{}; // Time of GPS Week from HOW word of Subframe 3 [s]
00166     int32_t d_TOW_SF4{}; // Time of GPS Week from HOW word of Subframe 4 [s]
00167     int32_t d_TOW_SF5{}; // Time of GPS Week from HOW word of Subframe 5 [s]
00168     int32_t d_IODE_SF2{};
00169     int32_t d_IODE_SF3{};
00170     double d_Crs{}; // Amplitude of the Sine Harmonic Correction Term to the Orbit Radius [m]

```

```

00171     double d_Delta_n{}; // Mean Motion Difference From Computed Value [semi-circles/s]
00172     double d_M_0{}; // Mean Anomaly at Reference Time [semi-circles]
00173     // broadcast orbit 2
00174     double d_Cuc{}; // Amplitude of the Cosine Harmonic Correction Term to the Argument of
Latitude [rad]
00175     double d_e_eccentricity{}; // Eccentricity [dimensionless]
00176     double d_Cus{}; // Amplitude of the Sine Harmonic Correction Term to the Argument of
Latitude [rad]
00177     double d_sqrt_A{}; // Square Root of the Semi-Major Axis [sqrt(m)]
00178     // broadcast orbit 3
00179     int32_t d_Toe{}; // Ephemeris data reference time of week (Ref. 20.3.3.4.3 IS-GPS-200M) [s]
00180     int32_t d_Toc{}; // clock data reference time (Ref. 20.3.3.3.1 IS-GPS-200M) [s]
00181     double d_Cic{}; // Amplitude of the Cosine Harmonic Correction Term to the Angle of
Inclination [rad]
00182     double d_OMEGA0{}; // Longitude of Ascending Node of Orbit Plane at Weekly Epoch [semi-circles]
00183     double d_Cis{}; // Amplitude of the Sine Harmonic Correction Term to the Angle of Inclination
[rad]
00184     // broadcast orbit 4
00185     double d_i_0{}; // Inclination Angle at Reference Time [semi-circles]
00186     double d_Crc{}; // Amplitude of the Cosine Harmonic Correction Term to the Orbit Radius [m]
00187     double d_OMEGA{}; // Argument of Perigee [semi-circles]
00188     double d_OMEGA_DOT{}; // Rate of Right Ascension [semi-circles/s]
00189     // broadcast orbit 5
00190     double d_IDOT{}; // Rate of Inclination Angle [semi-circles/s]
00191     int32_t i_code_on_L2{}; // If 1, P code ON in L2; if 2, C/A code ON in L2;
00192     int32_t i_GPS_week{}; // GPS week number, aka WN [week]
00193     bool b_L2_P_data_flag{}; // When true, indicates that the NAV data stream was commanded OFF on
the P-code of the L2 channel
00194     // broadcast orbit 6
00195     int32_t i_SV_accuracy{}; // User Range Accuracy (URA) index of the SV (reference paragraph 6.2.1)
for the standard positioning service user (Ref 20.3.3.3.1.3 IS-GPS-200M)
00196     int32_t i_SV_health{};
00197     double d_TGD{}; // Estimated Group Delay Differential: L1-L2 correction term only for the
benefit of "L1 P(Y)" or "L2 P(Y)" s users [s]
00198     int32_t d_IODC{}; // Issue of Data, Clock
00199     // broadcast orbit 7
00200     int32_t i_AODO{}; // Age of Data Offset (AODO) term for the navigation message
correction table (NMCT) contained in subframe 4 (reference paragraph 20.3.3.5.1.9) [s]
00201     bool b_fit_interval_flag{}; // indicates the curve-fit interval used by the CS (Block
II/IIA/IIR/IIR-M/IIF) and SS (Block IIIA) in determining the ephemeris parameters, as follows: 0 = 4
hours, 1 = greater than 4 hours.
00202     double d_spare1{};
00203     double d_spare2{};
00204     double d_A_f0{}; // Coefficient 0 of code phase offset model [s]
00205     double d_A_f1{}; // Coefficient 1 of code phase offset model [s/s]
00206     double d_A_f2{}; // Coefficient 2 of code phase offset model [s/s^2]
00207
00208     // Almanac
00209     int32_t i_ToA{}; // Almanac reference time [s]
00210     int32_t i_WN_A{}; // Modulo 256 of the GPS week number to which the almanac reference time
(i_ToA) is referenced
00211     int32_t SV_Health{}; // Almanac SV health
00212     uint32_t a_PRN{}; // Almanac PRN
00213     double a_delta_i{}; // Inclination Angle at Reference Time (relative to i_0 = 0.30 semi-circles)
00214     double a_M_0{}; // Mean Anomaly at Reference Time [semi-circles]
00215     double a_ecc{}; // Eccentricity [dimensionless]
00216     double a_sqrt_A{}; // Square Root of the Semi-Major Axis [sqrt(m)]
00217     double a_OMEGA_0{}; // Longitude of Ascending Node of Orbit Plane at Weekly Epoch [semi-circles]
00218     double a_omega{}; // Argument of Perigee [semi-circles]
00219     double a_OMEGA_dot{}; // Rate of Right Ascension [semi-circles/s]
00220     double a_af0{}; // Coefficient 0 of code phase offset model [s]
00221     double a_af1{}; // Coefficient 1 of code phase offset model [s/s]
00222
00223     // satellite identification info
00224     int32_t i_channel_ID{};
00225     uint32_t i_satellite_PRN{};
00226
00227     // Ionospheric parameters
00228     double d_alpha0{}; // Coefficient 0 of a cubic equation representing the amplitude of the
vertical delay [s]
00229     double d_alpha1{}; // Coefficient 1 of a cubic equation representing the amplitude of the
vertical delay [s/semi-circle]
00230     double d_alpha2{}; // Coefficient 2 of a cubic equation representing the amplitude of the
vertical delay [s(semi-circle)^2]
00231     double d_alpha3{}; // Coefficient 3 of a cubic equation representing the amplitude of the
vertical delay [s(semi-circle)^3]
00232     double d_beta0{}; // Coefficient 0 of a cubic equation representing the period of the model [s]
00233     double d_beta1{}; // Coefficient 1 of a cubic equation representing the period of the model
[s/semi-circle]
00234     double d_beta2{}; // Coefficient 2 of a cubic equation representing the period of the model
[s(semi-circle)^2]
00235     double d_beta3{}; // Coefficient 3 of a cubic equation representing the period of the model
[s(semi-circle)^3]
00236
00237     // UTC parameters
00238     double d_A0{}; // Constant of a model that relates GPS and UTC time (ref. 20.3.3.5.2.4
IS-GPS-200M) [s]

```



```

00239     double d_A1{}; // 1st order term of a model that relates GPS and UTC time (ref. 20.3.3.5.2.4
IS-GPS-200M) [s/s]
00240
00241     int32_t d_t_OT{}; // Reference time for UTC data (reference 20.3.4.5 and 20.3.3.5.2.4
IS-GPS-200M) [s]
00242     int32_t i_WN_T{}; // UTC reference week number [weeks]
00243     int32_t d_DeltaT_LS{}; // delta time due to leap seconds [s]. Number of leap seconds since
6-Jan-1980 as transmitted by the GPS almanac.
00244     int32_t i_WN_LSF{}; // Week number at the end of which the leap second becomes effective
[weeks]
00245     int32_t i_DN{}; // Day number (DN) at the end of which the leap second becomes effective
[days]
00246     int32_t d_DeltaT_LSF{}; // Scheduled future or recent past (relative to NAV message upload) value
of the delta time due to leap seconds [s]
00247
00248     // Flags
00249     bool b_valid_ephemeris_set_flag{}; // flag indicating that this ephemeris set have passed the
validation check
00250     bool flag_iono_valid{}; // If set, it indicates that the ionospheric parameters are
filled (page 18 has arrived and decoded)
00251     bool flag_utc_model_valid{}; // If set, it indicates that the UTC model parameters are
filled
00252     bool flag_almanac_valid{}; // If set, it indicates that the almanac is filled
00253     bool flag_almanac_week_valid{}; // If set, it indicates that the almanac week is valid
00254     /* If true, enhanced level of integrity assurance.
00255     *
00256     * If false, indicates that the conveying signal is provided with the legacy level of integrity
assurance.
00257     * That is, the probability that the instantaneous URE of the conveying signal exceeds 4.42 times
the upper bound
00258     * value of the current broadcast URA index, for more than 5.2 seconds, without an accompanying
alert, is less
00259     * than 1E-5 per hour. If true, indicates that the conveying signal is provided with an enhanced
level of
00260     * integrity assurance. That is, the probability that the instantaneous URE of the conveying
signal exceeds 5.73
00261     * times the upper bound value of the current broadcast URA index, for more than 5.2 seconds,
without an
00262     * accompanying alert, is less than 1E-8 per hour.
00263     */
00264     bool b_integrity_status_flag{};
00265     bool b_alert_flag{}; // If true, indicates that the SV URA may be worse than indicated in
d_SV_accuracy, use that SV at our own risk.
00266     bool b_antispoofing_flag{}; // If true, the AntiSpoofing mode is ON in that SV
00267 };
00268
00269
00270 /** \} */
00271 /** \} */
00272 #endif // GNSS_SDR_GPS_NAVIGATION_MESSAGE_H

```

13.819 gps_utc_model.h File Reference

Interface of a GPS UTC MODEL storage.

```
#include <boost/serialization/nvp.hpp>
```

```
#include <cstdint>
```

Classes

- class [Gps_Utc_Model](#)

This class is a storage for the GPS UTC MODEL data as described in IS-GPS-200M.

13.819.1 Detailed Description

Interface of a GPS UTC MODEL storage.

Author

Javier Arribas, 2013. jarribas(at)cttc.es

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Definition in file [gps_utc_model.h](#).

13.820 gps_utc_model.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file gps_utc_model.h
00003  * \brief Interface of a GPS UTC MODEL storage
00004  * \author Javier Arribas, 2013. jarribas(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_GPS_UTC_MODEL_H
00019 #define GNSS_SDR_GPS_UTC_MODEL_H
00020
00021 #include <boost/serialization/nvp.hpp>
00022 #include <cstdint>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup System_Parameters
00027  * \{ */
00028
00029
00030 /*!
00031 * \brief This class is a storage for the GPS UTC MODEL data as described in IS-GPS-200M
00032 *
00033 * See https://www.gps.gov/sites/default/files/2025-07/IS-GPS-200M.pdf Appendix II
00034 */
00035 class Gps_Utc_Model
00036 {
00037 public:
00038     /*!
00039     * Default constructor
00040     */
00041     Gps_Utc_Model() = default;
00042
00043     // UTC parameters
00044     double A0{}; //!< Constant of a model that relates GPS and UTC time (ref. 20.3.3.5.2.4
IS-GPS-200M) [s]
00045     double A1{}; //!< 1st order term of a model that relates GPS and UTC time (ref.
20.3.3.5.2.4 IS-GPS-200M) [s/s]
00046     double A2{}; //!< 2nd order term of a model that relates GPS and UTC time (ref.
20.3.3.5.2.4 IS-GPS-200M) [s/s]
00047     int32_t tot{}; //!< Reference time for UTC data (reference 20.3.4.5 and 20.3.3.5.2.4
IS-GPS-200M) [s]
00048     int32_t WN_T{}; //!< UTC reference week number [weeks]
00049     int32_t DeltaT_LS{}; //!< Delta time due to leap seconds [s]. Number of leap seconds since
6-Jan-1980 as transmitted by the GPS almanac.
00050     int32_t WN_LSF{}; //!< Week number at the end of which the leap second becomes effective
[weeks]
00051     int32_t DN{}; //!< Day number (DN) at the end of which the leap second becomes effective
[days]
00052     int32_t DeltaT_LSF{}; //!< Scheduled future or recent past (relative to NAV message upload) value
of the delta time due to leap seconds [s]
00053
00054     bool valid{};
00055
00056     template <class Archive>
00057     /*
00058     * \brief Serialize is a boost standard method to be called by the boost XML
00059     * serialization. Here is used to save the ephemeris data on disk file.
00060     */
00061     inline void serialize(Archive& archive, const uint32_t version)
00062     {
00063         if (version)
00064         {
00065             };
00066             archive& BOOST_SERIALIZATION_NVP(A0);
00067             archive& BOOST_SERIALIZATION_NVP(A1);
00068             archive& BOOST_SERIALIZATION_NVP(A2);
00069             archive& BOOST_SERIALIZATION_NVP(tot);
00070             archive& BOOST_SERIALIZATION_NVP(WN_T);
00071             archive& BOOST_SERIALIZATION_NVP(DeltaT_LS);
00072             archive& BOOST_SERIALIZATION_NVP(WN_LSF);
00073             archive& BOOST_SERIALIZATION_NVP(DN);
00074             archive& BOOST_SERIALIZATION_NVP(DeltaT_LSF);
00075             archive& BOOST_SERIALIZATION_NVP(valid);

```

```

00076     }
00077 };
00078
00079
00080 /** \} */
00081 /** \} */
00082 #endif // GNSS_SDR_GPS_UTC_MODEL_H

```

13.821 MATH_CONSTANTS.h File Reference

Defines useful mathematical constants and their scaled versions.

Variables

- constexpr double [GNSS_OMEGA_EARTH_DOT](#) = 7.2921151467e-5
Default Earth rotation rate, [rad/s].
- constexpr double [SPEED_OF_LIGHT_M_S](#) = 299792458.0
Speed of light in vacuum [m/s].
- constexpr double [SPEED_OF_LIGHT_M_MS](#) = 299792.4580
Speed of light in vacuum [m/ms].
- constexpr double [GPS_GM](#) = 3.986005e14
Universal gravitational constant times the mass of the Earth, [m^3/s^2] IS-GPS-200M, 20.3.3.3.3.1.
- constexpr double [GPS_F](#) = -4.442807633e-10
Constant, [$s/(m)^{1/2}$], IS-GPS-200M, 20.3.3.3.3.1.
- constexpr double [GALILEO_GM](#) = 3.986004418e14
Geocentric gravitational constant [m^3/s^2], OS SIS ICD v2.0, pag. 44.
- constexpr double [GALILEO_F](#) = -4.442807309e-10
Constant, [$s/(m)^{1/2}$], OS SIS ICD v2.0, pag. 47.
- constexpr double [GLONASS_OMEGA_EARTH_DOT](#) = 7.292115e-5
Earth rotation rate, [rad/s] ICD L1, L2 GLONASS Edition 5.1 2008 pag. 55.
- constexpr double [GLONASS_GM](#) = 398600.44e9
Universal gravitational constant times the mass of the Earth, [m^3/s^2].
- constexpr double [BEIDOU_OMEGA_EARTH_DOT](#) = 7.2921150e-5
Earth rotation rate, [rad/s] as defined in BDS-SIS-ICD-B11-3.0 2019-02, pag. 3.
- constexpr double [BEIDOU_GM](#) = 3.986004418e14
Universal gravitational constant times the mass of the Earth, [m^3/s^2] as defined in CGCS2000.
- constexpr double [BEIDOU_F](#) = -4.442807309e-10
Constant, [$s/(m)^{1/2}$] $F = -2(GM)^{.5}/C^2$.
- constexpr double [GNSS_PI](#) = 3.1415926535898
pi constant as defined for GNSS
- constexpr double [HALF_PI](#) = [GNSS_PI](#) / 2.0
pi/2
- constexpr double [TWO_PI](#) = 2.0 * [GNSS_PI](#)
*2 * pi*
- constexpr double [TWO_P3](#) = 8.0
2^3
- constexpr double [TWO_P4](#) = 16.0
2^4
- constexpr double [TWO_P8](#) = 256.0
2^8
- constexpr double [TWO_P11](#) = 2048.0
2^11
- constexpr double [TWO_P12](#) = 4096.0
2^12

- constexpr double [TWO_P14](#) = 16384.0
 2^{14}
- constexpr double [TWO_P16](#) = 65536.0
 2^{16}
- constexpr double [TWO_P19](#) = 524288.0
 2^{19}
- constexpr double [TWO_P31](#) = 2147483648.0
 2^{31}
- constexpr double [TWO_P32](#) = 4294967296.0
 2^{32}
- constexpr double [TWO_P56](#) = 7.205759403792794e+016
 2^{56}
- constexpr double [TWO_P57](#) = 1.441151880758559e+017
 2^{57}
- constexpr double [TWO_N2](#) = 0.25
 2^{-2}
- constexpr double [TWO_N5](#) = 0.03125
 2^{-5}
- constexpr double [TWO_N6](#) = 0.015625
 2^{-6}
- constexpr double [TWO_N8](#) = 0.00390625
 2^{-8}
- constexpr double [TWO_N9](#) = 0.001953125
 2^{-9}
- constexpr double [TWO_N10](#) = 0.0009765625
 2^{-10}
- constexpr double [TWO_N11](#) = 4.882812500000000e-004
 2^{-11}
- constexpr double [TWO_N14](#) = 0.00006103515625
 2^{-14}
- constexpr double [TWO_N15](#) = 3.051757812500000e-005
 2^{-15}
- constexpr double [TWO_N16](#) = 1.525878906250000e-005
 2^{-16}
- constexpr double [TWO_N17](#) = 7.629394531250000e-006
 2^{-17}
- constexpr double [TWO_N18](#) = 3.814697265625000e-006
 2^{-18}
- constexpr double [TWO_N19](#) = 1.907348632812500e-006
 2^{-19}
- constexpr double [TWO_N20](#) = 9.536743164062500e-007
 2^{-20}
- constexpr double [TWO_N21](#) = 4.768371582031250e-007
 2^{-21}
- constexpr double [TWO_N22](#) = 2.384185791015625e-007
 2^{-22}
- constexpr double [TWO_N23](#) = 1.192092895507810e-007
 2^{-23}
- constexpr double [TWO_N24](#) = 5.960464477539063e-008
 2^{-24}
- constexpr double [TWO_N25](#) = 2.980232238769531e-008

- 2^{-25}
- constexpr double [TWO_N26](#) = 1.490116119384765e-009
- 2^{-26}
- constexpr double [TWO_N27](#) = 7.450580596923828e-009
- 2^{-27}
- constexpr double [TWO_N29](#) = 1.862645149230957e-009
- 2^{-29}
- constexpr double [TWO_N30](#) = 9.313225746154785e-010
- 2^{-30}
- constexpr double [TWO_N31](#) = 4.656612873077393e-010
- 2^{-31}
- constexpr double [TWO_N32](#) = 2.328306436538696e-010
- 2^{-32}
- constexpr double [TWO_N33](#) = 1.164153218269348e-010
- 2^{-33}
- constexpr double [TWO_N34](#) = 5.82076609134674e-011
- 2^{-34}
- constexpr double [TWO_N35](#) = 2.91038304567337e-011
- 2^{-35}
- constexpr double [TWO_N38](#) = 3.637978807091713e-012
- 2^{-38}
- constexpr double [TWO_N39](#) = 1.818989403545856e-012
- 2^{-39}
- constexpr double [TWO_N40](#) = 9.094947017729280e-013
- 2^{-40}
- constexpr double [TWO_N43](#) = 1.136868377216160e-013
- 2^{-43}
- constexpr double [TWO_N44](#) = 5.684341886080802e-14
- 2^{-44}
- constexpr double [TWO_N46](#) = 1.4210854715202e-014
- 2^{-46}
- constexpr double [TWO_N48](#) = 3.552713678800501e-15
- 2^{-46}
- constexpr double [TWO_N50](#) = 8.881784197001252e-016
- 2^{-50}
- constexpr double [TWO_N51](#) = 4.44089209850063e-016
- 2^{-51}
- constexpr double [TWO_N55](#) = 2.775557561562891e-017
- 2^{-55}
- constexpr double [TWO_N57](#) = 6.938893903907228e-18
- 2^{-57}
- constexpr double [TWO_N59](#) = 1.73472347597681e-018
- 2^{-59}
- constexpr double [TWO_N60](#) = 8.673617379884036e-19
- 2^{-60}
- constexpr double [TWO_N66](#) = 1.3552527156068805425093160010874271392822265625e-20
- 2^{-66}
- constexpr double [TWO_N68](#) = 3.388131789017201e-21
- 2^{-68}
- constexpr double [PI_TWO_N19](#) = 5.992112452678286e-006
- $Pi * 2^{-19}$.

- constexpr double [PI_TWO_N43](#) = 3.571577341960839e-013
 $Pi \cdot 2^{-43}$.
- constexpr double [PI_TWO_N31](#) = 1.462918079267160e-009
 $Pi \cdot 2^{-31}$.
- constexpr double [PI_TWO_N38](#) = 1.142904749427469e-011
 $Pi \cdot 2^{-38}$.
- constexpr double [PI_TWO_N23](#) = 3.745070282923929e-007
 $Pi \cdot 2^{-23}$.
- constexpr double [D2R](#) = [GNSS_PI](#) / 180.0
deg to rad
- constexpr double [R2D](#) = 180.0 / [GNSS_PI](#)
rad to deg
- constexpr double [SC2RAD](#) = [GNSS_PI](#)
semi-circle to radian (IS-GPS)
- constexpr double [AS2R](#) = [D2R](#) / 3600.0
arc sec to radian
- constexpr double [AU](#) = 149597870691.0
1 Astronomical Unit AU (m) distance from Earth to the Sun.

13.821.1 Detailed Description

Defines useful mathematical constants and their scaled versions.

Author

Javier Arribas, 2013. [jarribas\(at\)cttc.es](mailto:jarribas(at)cttc.es)

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Definition in file [MATH_CONSTANTS.h](#).

13.822 MATH_CONSTANTS.h

[Go to the documentation of this file.](#)

```

00001  /*!
00002  * \file MATH_CONSTANTS.h
00003  * \brief Defines useful mathematical constants and their scaled versions
00004  * \author Javier Arribas, 2013. jarribas\(at\)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2020 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_MATH_CONSTANTS_H
00018 #define GNSS_SDR_MATH_CONSTANTS_H
00019
00020 /** \addtogroup Core
00021  * \{ */
00022 /** \addtogroup System_Parameters
00023  * \{ */
00024
00025
00026 constexpr double GNSS\_OMEGA\_EARTH\_DOT = 7.2921151467e-5; //!< Default Earth rotation rate, [rad/s]
00027 constexpr double SPEED\_OF\_LIGHT\_M\_S = 299792458.0; //!< Speed of light in vacuum [m/s]
00028 constexpr double SPEED\_OF\_LIGHT\_M\_MS = 299792.4580; //!< Speed of light in vacuum [m/ms]
00029
00030 // Physical constants for GPS
00031 constexpr double GPS\_GM = 3.986005e14; //!< Universal gravitational constant times the mass of
the Earth, [m^3/s^2] IS-GPS-200M, 20.3.3.3.3.1
00032 constexpr double GPS\_F = -4.442807633e-10; //!< Constant, [s/(m)^(1/2)], IS-GPS-200M, 20.3.3.3.3.1
00033

```

```
00034 // Physical constants for Galileo
00035 constexpr double GALILEO_GM = 3.986004418e14;    //!< Geocentric gravitational constant[m^3/s^2], OS
           SIS ICD v2.0, pag. 44
00036 constexpr double GALILEO_F = -4.442807309e-10;    //!< Constant, [s/(m)^(1/2)]. OS SIS ICD v2.0, pag. 47
00037
00038 // Physical constants for GLONASS
00039 constexpr double GLONASS_OMEGA_EARTH_DOT = 7.292115e-5;    //!< Earth rotation rate, [rad/s] ICD L1, L2
           GLONASS Edition 5.1 2008 pag. 55
00040 constexpr double GLONASS_GM = 3.986004418e9;        //!< Universal gravitational constant times
           the mass of the Earth, [m^3/s^2]
00041
00042 // Physical constants for Beidou
00043 constexpr double BEIDOU_OMEGA_EARTH_DOT = 7.2921150e-5;    //!< Earth rotation rate, [rad/s] as defined
           in BDS-SIS-ICD-B1I-3.0 2019-02, pag. 3
00044 constexpr double BEIDOU_GM = 3.986004418e14;        //!< Universal gravitational constant times
           the mass of the Earth, [m^3/s^2] as defined in CGCS2000
00045 constexpr double BEIDOU_F = -4.442807309e-10;        //!< Constant, [s/(m)^(1/2)] F=-2(GM)^.5/C^2
00046
00047 constexpr double GNSS_PI = 3.1415926535898;    //!< pi constant as defined for GNSS
00048 constexpr double HALF_PI = GNSS_PI / 2.0;    //!< pi/2
00049 constexpr double TWO_PI = 2.0 * GNSS_PI;    //!< 2 * pi
00050
00051
00052 // Constants for scaling the ephemeris found in the data message
00053 // the format is the following: TWO_N5 -> 2^-5, TWO_P4 -> 2^4, PI_TWO_N43 -> Pi*2^-43, etc etc
00054 // Additionally some of the PI*2^N terms are used in the tracking stuff
00055 // TWO_PX ==> 2^X
00056 // TWO_NX ==> 2^-X
00057 // PI_TWO_NX ==> Pi*2^-X
00058
00059 constexpr double TWO_P3 = 8.0;    //!< 2^3
00060 constexpr double TWO_P4 = 16.0;    //!< 2^4
00061 constexpr double TWO_P8 = 256.0;    //!< 2^8
00062 constexpr double TWO_P11 = 2048.0;    //!< 2^11
00063 constexpr double TWO_P12 = 4096.0;    //!< 2^12
00064 constexpr double TWO_P14 = 16384.0;    //!< 2^14
00065 constexpr double TWO_P16 = 65536.0;    //!< 2^16
00066 constexpr double TWO_P19 = 524288.0;    //!< 2^19
00067 constexpr double TWO_P31 = 2147483648.0;    //!< 2^31
00068 constexpr double TWO_P32 = 4294967296.0;    //!< 2^32
00069 constexpr double TWO_P56 = 7.205759403792794e+016;    //!< 2^56
00070 constexpr double TWO_P57 = 1.441151880758559e+017;    //!< 2^57
00071
00072 constexpr double TWO_N2 = 0.25;    //!< 2^-2
00073 constexpr double TWO_N5 = 0.03125;    //!< 2^-5
00074 constexpr double TWO_N6 = 0.015625;    //!< 2^-6
00075 constexpr double TWO_N8 = 0.00390625;    //!< 2^-8
00076 constexpr double TWO_N9 = 0.001953125;    //!< 2^-9
00077 constexpr double TWO_N10 = 0.0009765625;    //!< 2^-10
00078 constexpr double TWO_N11 = 4.882812500000000e-004;    //!< 2^-11
00079 constexpr double TWO_N14 = 0.00006103515625;    //!< 2^-14
00080 constexpr double TWO_N15 = 3.051757812500000e-005;    //!< 2^-15
00081 constexpr double TWO_N16 = 1.525878906250000e-005;    //!< 2^-16
00082 constexpr double TWO_N17 = 7.629394531250000e-006;    //!< 2^-17
00083 constexpr double TWO_N18 = 3.814697265625000e-006;    //!< 2^-18
00084 constexpr double TWO_N19 = 1.907348632812500e-006;    //!< 2^-19
00085 constexpr double TWO_N20 = 9.536743164062500e-007;    //!< 2^-20
00086 constexpr double TWO_N21 = 4.768371582031250e-007;    //!< 2^-21
00087 constexpr double TWO_N22 = 2.384185791015625e-007;    //!< 2^-22
00088 constexpr double TWO_N23 = 1.192092895507810e-007;    //!< 2^-23
00089 constexpr double TWO_N24 = 5.960464477539063e-008;    //!< 2^-24
00090 constexpr double TWO_N25 = 2.980232238769531e-008;    //!< 2^-25
00091 constexpr double TWO_N26 = 1.490116119384765e-009;    //!< 2^-26
00092 constexpr double TWO_N27 = 7.450580596923828e-009;    //!< 2^-27
00093 constexpr double TWO_N29 = 1.862645149230957e-009;    //!< 2^-29
00094 constexpr double TWO_N30 = 9.313225746154785e-010;    //!< 2^-30
00095 constexpr double TWO_N31 = 4.656612873077393e-010;    //!< 2^-31
00096 constexpr double TWO_N32 = 2.328306436538696e-010;    //!< 2^-32
00097 constexpr double TWO_N33 = 1.164153218269348e-010;    //!< 2^-33
00098 constexpr double TWO_N34 = 5.82076609134674e-011;    //!< 2^-34
00099 constexpr double TWO_N35 = 2.91038304567337e-011;    //!< 2^-35
00100 constexpr double TWO_N38 = 3.637978807091713e-012;    //!< 2^-38
00101 constexpr double TWO_N39 = 1.818989403545856e-012;    //!< 2^-39
00102 constexpr double TWO_N40 = 9.094947017729280e-013;    //!< 2^-40
00103 constexpr double TWO_N43 = 1.136868377216160e-013;    //!< 2^-43
00104 constexpr double TWO_N44 = 5.684341886080802e-014;    //!< 2^-44
00105 constexpr double TWO_N46 = 1.4210854715202e-014;    //!< 2^-46
00106 constexpr double TWO_N48 = 3.552713678800501e-015;    //!< 2^-46
00107
00108 constexpr double TWO_N50 = 8.881784197001252e-016;    //!< 2^-50
00109 constexpr double TWO_N51 = 4.44089209850063e-016;    //!< 2^-51
00110 constexpr double TWO_N55 = 2.775557561562891e-017;    //!< 2^-55
00111 constexpr double TWO_N57 = 6.938893903907228e-018;    //!< 2^-57
00112 constexpr double TWO_N59 = 1.73472347597681e-018;    //!< 2^-59
00113 constexpr double TWO_N60 = 8.673617379884036e-019;    //!< 2^-60
00114 constexpr double TWO_N66 = 1.3552527156068805425093160010874271392822265625e-20;    //!< 2^-66
00115 constexpr double TWO_N68 = 3.388131789017201e-21;    //!< 2^-68
```

```

00116
00117 constexpr double PI_TWO_N19 = 5.992112452678286e-006; //!< Pi*2^-19
00118 constexpr double PI_TWO_N43 = 3.571577341960839e-013; //!< Pi*2^-43
00119 constexpr double PI_TWO_N31 = 1.462918079267160e-009; //!< Pi*2^-31
00120 constexpr double PI_TWO_N38 = 1.142904749427469e-011; //!< Pi*2^-38
00121 constexpr double PI_TWO_N23 = 3.745070282923929e-007; //!< Pi*2^-23
00122
00123 constexpr double D2R = GNSS_PI / 180.0; //!< deg to rad
00124 constexpr double R2D = 180.0 / GNSS_PI; //!< rad to deg
00125 constexpr double SC2RAD = GNSS_PI; //!< semi-circle to radian (IS-GPS)
00126 constexpr double AS2R = D2R / 3600.0; //!< arc sec to radian
00127
00128 constexpr double AU = 149597870691.0; //!< 1 Astronomical Unit AU (m) distance from Earth to the Sun.
00129
00130
00131 /** \} */
00132 /** \} */
00133 #endif // GNSS_SDR_MATH_CONSTANTS_H

```

13.823 osnma_data.h File Reference

Class for Galileo OSNMA data storage.

```

#include "galileo_inav_message.h"
#include <array>
#include <stdint>
#include <memory>
#include <string>
#include <vector>

```

Classes

- class [DSM_nma_header](#)
- class [DSM_dsm_header](#)
- class [MACK_header](#)
- class [MACK_tag_info](#)
- class [MACK_tag_and_info](#)
- class [DSM_PKR_message](#)
- class [DSM_KROOT_message](#)
- class [MACK_message](#)
- class [OSNMA_NavData](#)
- class [OSNMA_data](#)

This class handles OSNMA data See https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo_OSNMA_User_ICD_for_Test_Phase_v1.0.pdf.

- class [Tag](#)

13.823.1 Detailed Description

Class for Galileo OSNMA data storage.

Author

Carles Fernandez-Prades, 2020-2023 cfernandez(at)cttc.es

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 Definition in file [osnma_data.h](#).

13.824 osnma_data.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file osnma_data.h
00003  * \brief Class for Galileo OSNMA data storage

```



```

00004  * \author Carles Fernandez-Prades, 2020-2023 cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2023 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_OSNMA_DATA_H
00019 #define GNSS_SDR_OSNMA_DATA_H
00020
00021 #include "galileo_inav_message.h" // for OSNMA_msg
00022 #include <array>
00023 #include <cstdint>
00024 #include <memory>
00025 #include <string>
00026 #include <vector>
00027
00028 /** \addtogroup Core
00029  * \{ */
00030 /** \addtogroup System_Parameters
00031  * \{ */
00032
00033 class DSM_nma_header
00034 {
00035 public:
00036     DSM_nma_header() = default;
00037     uint8_t nmas{};
00038     uint8_t cid{};
00039     uint8_t cpks{};
00040     bool reserved{};
00041 };
00042
00043
00044 class DSM_dsm_header
00045 {
00046 public:
00047     DSM_dsm_header() = default;
00048     uint8_t dsm_id{};
00049     uint8_t dsm_block_id{};
00050 };
00051
00052
00053 class MACK_header
00054 {
00055 public:
00056     MACK_header() = default;
00057     uint64_t tag0{};
00058     uint16_t macseq{};
00059     uint8_t cop{};
00060 };
00061
00062
00063 class MACK_tag_info
00064 {
00065 public:
00066     MACK_tag_info() = default;
00067     uint8_t PRN_d{};
00068     uint8_t ADKD{};
00069     uint8_t cop{};
00070 };
00071
00072
00073 class MACK_tag_and_info
00074 {
00075 public:
00076     MACK_tag_and_info() = default;
00077     uint64_t tag; // C: 20-40 bits
00078     MACK_tag_info tag_info;
00079     uint32_t counter; // CTR
00080 };
00081
00082
00083 class DSM_PKR_message
00084 {
00085 public:
00086     DSM_PKR_message() = default;
00087
00088     std::array<uint8_t, 128> itn{}; // bitset<1024>
00089     std::vector<uint8_t> npk;
00090     std::vector<uint8_t> p_dp;

```

```

00091     uint8_t nb_dp{};
00092     uint8_t mid{};
00093     uint8_t npkt{};
00094     uint8_t npktid{};
00095 };
00096
00097
00098 class DSM_KROOT_message
00099 {
00100 public:
00101     DSM_KROOT_message() = default;
00102
00103     std::vector<uint8_t> kroot;
00104     std::vector<uint8_t> ds;
00105     std::vector<uint8_t> p_dk;
00106     uint64_t alpha{};
00107     uint16_t wn_k{};
00108     uint8_t nb_dk{};
00109     uint8_t pkid{};
00110     uint8_t cidkr{};
00111     uint8_t reserved1{};
00112     uint8_t hf{};
00113     uint8_t mf{};
00114     uint8_t ks{}; // key size, in bits
00115     uint8_t ts{};
00116     uint8_t mac1t{};
00117     uint8_t reserved{};
00118     uint8_t towh_k{};
00119     bool verified{false};
00120 };
00121
00122
00123 class MACK_message
00124 {
00125 public:
00126     MACK_message() = default;
00127     MACK_header header;
00128     std::vector<MACK_tag_and_info> tag_and_info;
00129     std::vector<uint8_t> key;
00130     uint32_t TOW; // TODO duplicated variable, also in OSNMA_NavData
00131     uint32_t WN;
00132     uint32_t PRNA;
00133 };
00134
00135
00136 class OSNMA_NavData
00137 {
00138 public:
00139     OSNMA_NavData() : nav_data_id(id_counter++) {}
00140     const uint32_t nav_data_id;
00141     std::string get_utc_data() const;
00142     std::string get_ephemeris_data() const;
00143     uint32_t get_verified_bits() const { return verified_bits; }
00144     uint32_t get_prn_d() const { return PRNd; }
00145     uint32_t get_IOD_nav() const { return IOD_nav; }
00146     uint32_t get_last_received_TOW() const { return d_last_received_TOW; }
00147     uint32_t get_tow_sf0() const { return d_TOW_sf0; }
00148     bool have_this_bits(std::string nav_data);
00149     bool get_verified_status() const { return verified; }
00150     bool add_nav_data(const std::string& nav_data);
00151     void set_tow_sf0(int value) { d_TOW_sf0 = value; }
00152     void set_ephemeris_data(std::string value) { d_ephemeris_iono = value; }
00153     void set_utc_data(std::string value) { d_utc = value; }
00154     void update_last_received_timestamp(uint32_t TOW);
00155     void set_prn_d(uint32_t value) { PRNd = value; }
00156     void set_last_received_TOW(uint32_t TOW) { d_last_received_TOW = TOW; }
00157     void set_update_verified_bits(uint32_t morebits) { verified_bits += morebits; }
00158     void set_verified_status(bool value) { verified = value; }
00159     void set_IOD_nav(uint32_t value) { IOD_nav = value; }
00160
00161 private:
00162     static uint32_t id_counter;
00163     std::string d_ephemeris_iono{" "};
00164     std::string d_utc{" "};
00165     uint32_t d_TOW_sf0{0};
00166     uint32_t d_last_received_TOW{0};
00167     uint32_t PRNd{0};
00168     uint32_t verified_bits{0};
00169     uint32_t IOD_nav{0};
00170     bool verified{false};
00171 };
00172
00173
00174 /*!
00175  * \brief This class handles OSNMA data
00176  * See
00177     https://www.gsc-europa.eu/sites/default/files/sites/all/files/Galileo\_OSNMA\_User\_ICD\_for\_Test\_Phase\_v1.0.pdf

```

```

00177  */
00178  class OSNMA_data
00179  {
00180  public:
00181      OSNMA_data() = default;
00182      DSM_nma_header d_nma_header;
00183      DSM_dsm_header d_dsm_header;
00184      DSM_PKR_message d_dsm_pkr_message;
00185      DSM_KROOT_message d_dsm_kroot_message;
00186      DSM_KROOT_message d_dsm_kroot_new_message;
00187      MACK_message d_mack_message;
00188      OSNMA_NavData d_nav_data;
00189  };
00190
00191
00192  class Tag
00193  {
00194  public:
00195      enum e_verification_status
00196      {
00197          SUCCESS,
00198          FAIL,
00199          UNVERIFIED
00200      };
00201      Tag(const MACK_tag_and_info& MTI, uint32_t TOW, uint32_t WN, uint32_t PRNa, uint8_t CTR) //
standard tag constructor, for tags within Tag&Info field
00202          : tag_id(id_counter++),
00203            TOW(TOW), // TODO missing for build_message WN for GST computation, CTR, NMAS,
OSNMA_NavData missing
00204            WN(WN),
00205            PRNa(PRNa),
00206            CTR(CTR),
00207            status(UNVERIFIED),
00208            received_tag(MTI.tag),
00209            computed_tag(0),
00210            PRN_d(MTI.tag_info.PRN_d),
00211            ADKD(MTI.tag_info.ADKD),
00212            cop(MTI.tag_info.cop),
00213            skipped(0)
00214      {
00215      }
00216      explicit Tag(const MACK_message& mack) // constructor for Tag0
00217          : tag_id(id_counter++),
00218            TOW(mack.TOW), // TODO missing for build_message WN for GST computation, CTR, NMAS,
OSNMA_NavData missing
00219            WN(mack.WN),
00220            PRNa(mack.PRNa),
00221            CTR(1),
00222            status(UNVERIFIED),
00223            received_tag(mack.header.tag0),
00224            computed_tag(0),
00225            PRN_d(mack.PRNa), // Tag0 are self-authenticating
00226            ADKD(0),
00227            cop(mack.header.cop),
00228            skipped(0)
00229      {
00230      }
00231      const uint32_t tag_id;
00232      static uint32_t id_counter;
00233      uint32_t TOW;
00234      uint32_t WN;
00235      uint32_t PRNa;
00236      uint8_t CTR;
00237      e_verification_status status;
00238      uint64_t received_tag;
00239      uint64_t computed_tag;
00240      uint8_t PRN_d;
00241      uint8_t ADKD;
00242      uint8_t cop;
00243      uint32_t skipped;
00244      std::string nav_data;
00245  };
00246
00247  /** \} */
00248  /** \} */
00249
00250  #endif // GNSS_SDR_OSNMA_DATA_H

```

13.825 osnma_dsm_reader.h File Reference

Class for reading OSNMA DSM messages.

```

#include <cstdint>
#include <string>

```

```
#include <vector>
```

Classes

- class [OSNMA_DSM_Reader](#)

13.825.1 Detailed Description

Class for reading OSNMA DSM messages.

Author

Carles Fernandez-Prades, 2023 cfernandez(at)cttc.es

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 Definition in file [osnma_dsm_reader.h](#).

13.826 osnma_dsm_reader.h

[Go to the documentation of this file.](#)

```
00001  /*!
00002  * \file osnma_dsm_reader.h
00003  * \brief Class for reading OSNMA DSM messages
00004  * \author Carles Fernandez-Prades, 2023 cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2023 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_OSNMA_DSM_READER_H
00018 #define GNSS_SDR_OSNMA_DSM_READER_H
00019
00020 #include <stdint>
00021 #include <string>
00022 #include <vector>
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup System_Parameters
00027  * \{ */
00028
00029 class OSNMA_DSM_Reader
00030 {
00031 public:
00032     OSNMA_DSM_Reader() = default;
00033     uint8_t get_nmas(uint8_t nma_header) const;
00034     uint8_t get_cid(uint8_t nma_header) const;
00035     uint8_t get_cpks(uint8_t nma_header) const;
00036     bool get_nma_header_reserved(uint8_t nma_header) const;
00037
00038     uint8_t get_dsm_id(uint8_t dsm_header) const;
00039     uint8_t get_dsm_block_id(uint8_t dsm_header) const;
00040
00041     uint8_t get_number_blocks_index(uint8_t dsm_msg_0) const;
00042     uint8_t get_pkid(const std::vector<uint8_t>& dsm_msg) const;
00043     uint8_t get_cidkr(const std::vector<uint8_t>& dsm_msg) const;
00044     uint8_t get_dsm_reserved1(const std::vector<uint8_t>& dsm_msg) const;
00045     uint8_t get_hf(const std::vector<uint8_t>& dsm_msg) const;
00046     uint8_t get_mf(const std::vector<uint8_t>& dsm_msg) const;
00047     uint8_t get_ks(const std::vector<uint8_t>& dsm_msg) const;
00048     uint8_t get_ts(const std::vector<uint8_t>& dsm_msg) const;
00049     uint8_t get_mac1t(const std::vector<uint8_t>& dsm_msg) const;
00050     uint8_t get_dsm_reserved(const std::vector<uint8_t>& dsm_msg) const;
00051     uint16_t get_wn_k(const std::vector<uint8_t>& dsm_msg) const;
00052     uint8_t get_towh_k(const std::vector<uint8_t>& dsm_msg) const;
00053     uint64_t get_alpha(const std::vector<uint8_t>& dsm_msg) const;
00054     uint16_t get_l_dk_bits(uint8_t nb_dk) const;
00055     uint16_t get_lk_bits(uint8_t ks) const;
00056     std::vector<uint8_t> get_kroot(const std::vector<uint8_t>& dsm_msg, uint16_t bytes_lk) const;
```

```

00057 std::string get_hash_function(uint8_t hf) const;
00058 std::string get_nmas_status(uint8_t nmas) const;
00059 std::string get_cpks_status(uint8_t cpks) const;
00060
00061 uint8_t get_mid(const std::vector<uint8_t>& dsm_msg) const;
00062 uint8_t get_npkt(const std::vector<uint8_t>& dsm_msg) const;
00063 uint8_t get_npktid(const std::vector<uint8_t>& dsm_msg) const;
00064
00065 private:
00066     static constexpr std::uint8_t mask_nmas{0xC0};
00067     static constexpr std::uint8_t mask_cid{0x30};
00068     static constexpr std::uint8_t mask_cpks{0x0E};
00069     static constexpr std::uint8_t mask_nma_header_reserved{0x01};
00070     static constexpr std::uint8_t mask_dsm_id{0xF0};
00071     static constexpr std::uint8_t mask_dsm_block_id{0x0F};
00072     static constexpr std::uint8_t mask_dsm_number_blocks{0xF0};
00073     static constexpr std::uint8_t mask_dsm_pkid{0x0F};
00074     static constexpr std::uint8_t mask_dsm_cidkr{0xC0};
00075     static constexpr std::uint8_t mask_dsm_reserved1{0x30};
00076     static constexpr std::uint8_t mask_dsm_hf{0x0C};
00077     static constexpr std::uint8_t mask_dsm_mf{0x03};
00078     static constexpr std::uint8_t mask_dsm_ks{0xF0};
00079     static constexpr std::uint8_t mask_dsm_ts{0x0F};
00080     static constexpr std::uint8_t mask_dsm_reserved{0xF0};
00081     static constexpr std::uint8_t mask_dsm_wk_k_msbyte{0x0F};
00082     static constexpr std::uint8_t mask_dsm_mid{0x0F};
00083     static constexpr std::uint8_t mask_dsm_npkt{0x0F};
00084     static constexpr std::uint8_t mask_dsm_npktid{0x0F};
00085 };
00086
00087 /** \} */
00088 /** \} */
00089 #endif // GNSS_SDR_OSMA_DSM_READER_H

```

13.827 qzss.h File Reference

Defines system parameters for QZSS signals.

```
#include "gnss_frequencies.h"
```

```
#include <cstdint>
```

Variables

- constexpr const char QZSS_CA_PREAMBLE_SYMBOLS_STR[161] = "1111111111111111111000000000000000000000"
- constexpr const char QZSS_L5Q_NH_CODE_STR[21] = "00000100110101001110"
- constexpr const char QZSS_L5I_NH_CODE_STR[11] = "0000110101"

13.827.1 Detailed Description

Defines system parameters for QZSS signals.

Author

Carles Fernández-Prades, 2026. cfernandez (at) cttc.es

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Definition in file [qzss.h](#).

13.828 qzss.h

[Go to the documentation of this file.](#)

```
00001 /*!  
00002  * \file qzss.h  
00003  * \brief Defines system parameters for QZSS signals  
00004  * \author Carles Fernández-Prades, 2026. cfernandez (at) cttc.es  
00005  *  
00006  * -----  
00007  *  
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.  
00009  * This file is part of GNSS-SDR.  
00010  *
```


Author

Carles Fernandez, 2021. cfernandez(at)cttc.es

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 Definition in file [reed_solomon.h](#).

13.830 reed_solomon.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file reed_solomon.h
00003  * \brief Class implementing a Reed-Solomon encoder/decoder for blocks of 255
00004  * symbols and symbols of 8 bits.
00005  * \author Carles Fernandez, 2021. cfernandez(at)cttc.es
00006  *
00007  * -----
00008  *
00009  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00010  * This file is part of GNSS-SDR.
00011  *
00012  * Copyright (C) 2010-2021 (see AUTHORS file for a list of contributors)
00013  * SPDX-License-Identifier: GPL-3.0-or-later
00014  *
00015  * -----
00016  */
00017
00018
00019 #ifndef GNSS_SDR_REED_SOLOMON_H
00020 #define GNSS_SDR_REED_SOLOMON_H
00021
00022 #include <array>
00023 #include <cstdint>
00024 #include <string>
00025 #include <vector>
00026
00027
00028 /** \addtogroup Core
00029  * \{ */
00030 /** \addtogroup System_Parameters
00031  * \{ */
00032
00033 /*!
00034  * \brief
00035  * Class implementing a Reed-Solomon encoder and decoder RS(255,K,d) where
00036  * k=255-nroots is the information vector length and d=nroots+1 is the minimum
00037  * Hamming distance, with symbols of 8 bits. It allows shortened RS codes.
00038  */
00039
00040 class ReedSolomon
00041 {
00042 public:
00043     /*!
00044      * \brief Default constructor.
00045      * Constructs a Reed Solomon object. The encode_with_generator_poly
00046      * and encode_with_generator_matrix methods are available for testing
00047      * purposes.
00048      *
00049      * gnss_signal: empty or "E6B" sets the Galileo E6B RS parameters.
00050      * "E1B" sets the Galileo E1B (INAV) RS parameters.
00051      */
00052     explicit ReedSolomon(const std::string& gnss_signal = std::string());
00053
00054     /*!
00055      * \brief Custom constructor for RS(255, 255-nroots, nroots+1). Parameters:
00056      *
00057      * nroots - the number of roots in the RS code generator polynomial,
00058      * which is the same as the number of parity symbols in a block.
00059      *
00060      * minpoly - primitive polynomial.
00061      *
00062      * prim - the primitive root of the generator polynomial.
00063      *
00064      * for - first consecutive root of the Reed-Solomon generator polynomial.
00065      *
00066      * pad - the number of pad symbols in a block. If not defined, it defaults
00067      * to 0.
00068      *
00069      * shortening - value of the shortening parameter. Defaults to 0.
00070      * If different to 0, it defines a shortened RS encoder/decoder.
00071      *
00072      * genpoly_coeff - a vector of (nroots+1) elements containing the generator

```

```

00073     * polynomial coefficients. Only used for encoding. Defaults to empty.
00074     * If defined, the encode_with_generator_poly method can be used.
00075     *
00076     * gen_matrix - a (255-shortening)x(255-nroots-shortening) matrix containing
00077     * the elements of the generator matrix. Only used for encoding. Defaults
00078     * to empty. If defined, the encode_with_generator_matrix method can be
00079     * used.
00080     */
00081 ReedSolomon(int nroots,
00082             int minpoly,
00083             int prim,
00084             int fcr,
00085             int pad = 0,
00086             int shortening = 0,
00087             const std::vector<uint8_t>& genpoly_coeff = std::vector<uint8_t>{},
00088             const std::vector<std::vector<uint8_t>& gen_matrix = std::vector<std::vector<uint8_t>>{});
00089
00090     /*!
00091     * \brief Decode an encoded block.
00092     *
00093     * The decoded symbols are at the first 255-nroots-shortening elements
00094     * of the data_to_decode vector.
00095     *
00096     * The second parameter is optional, and contains a vector of erasure
00097     * positions to be passed to the decoding algorithm. Defaults to empty.
00098     *
00099     * Returns the number of corrected errors, or -1 if decoding failed.
00100     */
00101     int decode(std::vector<uint8_t>& data_to_decode,
00102              const std::vector<int>& erasure_positions = std::vector<int>{}) const;
00103
00104     /*!
00105     * \brief Encode data with the generator matrix (for testing purposes)
00106     *
00107     * Returns the encoded vector. It is set to all zeros if the generator
00108     * matrix is not defined.
00109     */
00110     std::vector<uint8_t> encode_with_generator_matrix(const std::vector<uint8_t>& data_to_encode)
00111     const;
00112
00113     /*!
00114     * \brief Encode data with the generator polynomial (for testing purposes)
00115     *
00116     * Returns the encoded vector. It is set to all zeros if the generator
00117     * polynomial is not defined.
00118     */
00118     std::vector<uint8_t> encode_with_generator_poly(const std::vector<uint8_t>& data_to_encode) const;
00119
00120 private:
00121     static const int d_symbols_per_block = 255; // the total number of symbols in a RS block.
00122     static const int d_symsize = 8;           // symbol size, in bits.
00123
00124     int mod255(int x) const;
00125     int rs_min(int a, int b) const;
00126     int decode_rs_8(uint8_t* data, const int* eras_pos, int no_eras) const;
00127
00128     uint8_t galois_mul(uint8_t a, uint8_t b) const;
00129     uint8_t galois_add(uint8_t a, uint8_t b) const;
00130     uint8_t galois_mul_table(uint8_t a, uint8_t b) const;
00131
00132     void encode_rs_8(const uint8_t* data, uint8_t* parity) const;
00133     void init_log_tables(); // initialize d_log_table and d_antilog
00134     void init_alpha_tables(); // initialize d_alpha_to, d_index_of
00135
00136     std::array<uint8_t, 256> d_alpha_to{}; // used for decoding
00137     std::array<uint8_t, 256> d_index_of{}; // used for decoding
00138     std::array<uint8_t, 256> d_log_table{}; // used for encoding
00139     std::array<uint8_t, 256> d_antilog{}; // used for encoding
00140
00141     std::vector<std::vector<uint8_t>> d_genmatrix; // used for encoding
00142     std::vector<uint8_t> d_genpoly_coeff; // used for encoding
00143     std::vector<uint8_t> d_genpoly_index; // used for encoding
00144
00145     size_t d_data_in_block{}; // number of information symbols in a block
00146     size_t d_rows_G{}; // number of rows of the generator matrix
00147     size_t d_columns_G{}; // number of rows of the generator matrix
00148     size_t d_info_symbols_shortened{}; // number of info symbols in the shortened code
00149     size_t d_data_symbols_shortened{}; // number of data symbols in the shortened code
00150
00151     int d_nroots{}; // number of parity symbols in a block
00152     int d_prim{}; // The primitive root of the generator poly
00153     int d_pad{}; // the number of pad symbols in a block
00154     int d_iprim{}; // prim-th root of 1, index form
00155     int d_fcr{}; // first consecutive root
00156     int d_shortening{}; // shortening parameter
00157
00158     uint8_t d_min_poly{}; // primitive polynomial

```



```

00159     uint8_t d_a0{};           // auxiliary variable
00160 };
00161
00162 /** \} */
00163 /** \} */
00164 #endif // GNSS_SDR_REED_SOLOMON_H

```

13.831 sbas_ephemeris.h File Reference

Interface of a SBAS REFERENCE LOCATION storage.

```
#include <ostream>
```

Classes

- class [Sbas_Ephemeris](#)

This class stores SBAS SV ephemeris data.

13.831.1 Detailed Description

Interface of a SBAS REFERENCE LOCATION storage.

Author

Daniel Fehr, 2013. [daniel.co\(at\)bluewin.ch](mailto:daniel.co(at)bluewin.ch)

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 Definition in file [sbas_ephemeris.h](#).

13.832 sbas_ephemeris.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file sbas_ephemeris.h
00003  * \brief Interface of a SBAS REFERENCE LOCATION storage
00004  * \author Daniel Fehr, 2013. daniel.co\(at\)bluewin.ch
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
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00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017
00018 #ifndef GNSS_SDR_SBAS_EPHEMERIS_H
00019 #define GNSS_SDR_SBAS_EPHEMERIS_H
00020
00021 #include <ostream>
00022
00023 /** \addtogroup Core
00024  * \{ */
00025 /** \addtogroup System_Parameters
00026  * \{ */
00027
00028
00029 /*!
00030  * \brief This class stores SBAS SV ephemeris data
00031  *
00032  */
00033 class Sbas_Ephemeris
00034 {
00035 public:
00036     Sbas_Ephemeris() = default;
00037
00038     int i_prn{};           //!< PRN number
00039     int i_t0{};           //!< Reference epoch time (GPST)
00040     double d_tof{};       //!< Time of message frame (GPST)

```

```

00041     int i_sv_ura{};           //!< SV accuracy (URA index), not standardized
00042     bool b_sv_do_not_use{};    //!< Health status (false:do not use / true:usable)
00043     double d_pos[3]{};        //!< Satellite position (m) (ECEF)
00044     double d_vel[3]{};        //!< Satellite velocity (m/s) (ECEF)
00045     double d_acc[3]{};        //!< Satellite acceleration (m/s^2) (ECEF)
00046     double d_af0{};           //!< Satellite clock-offset (s)
00047     double d_af1{};           //!< Satellite drift (s/s)
00048
00049     void print(std::ostream &out);
00050 };
00051
00052
00053 /** \} */
00054 /** \} */
00055 #endif // GNSS_SDR_SBAS_EPHEMERIS_H

```

13.833 tow_to_trk.h File Reference

Class to inform about TOW from Telemetry to Tracking blocks.

```

#include <stdint>
#include <string>

```

Classes

- class [TOW_to_trk](#)

13.833.1 Detailed Description

Class to inform about TOW from Telemetry to Tracking blocks.

Author

Carles Fernandez, 2025. cfernandez(at)cttc.es

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Definition in file [tow_to_trk.h](#).

13.834 tow_to_trk.h

[Go to the documentation of this file.](#)

```

00001 /*!
00002  * \file tow_to_trk.h
00003  * \brief Class to inform about TOW from Telemetry to Tracking blocks
00004  * \author Carles Fernandez, 2025. cfernandez(at)cttc.es
00005  *
00006  * -----
00007  *
00008  * GNSS-SDR is a Global Navigation Satellite System software-defined receiver.
00009  * This file is part of GNSS-SDR.
00010  *
00011  * Copyright (C) 2010-2025 (see AUTHORS file for a list of contributors)
00012  * SPDX-License-Identifier: GPL-3.0-or-later
00013  *
00014  * -----
00015  */
00016
00017 #ifndef GNSS_SDR_TOW_TO_TRK_H
00018 #define GNSS_SDR_TOW_TO_TRK_H
00019
00020 #include <stdint>
00021 #include <string>
00022
00023
00024 /** \addtogroup Core
00025  * \{ */
00026 /** \addtogroup System_Parameters
00027  * \{ */
00028
00029 class TOW_to_trk
00030 {
00031 public:
00032     TOW_to_trk() = default;

```

```
00033
00034     // Constructor with all parameters
00035     TOW_to_trk(const std::string& sig, int32_t ch, uint32_t t, uint64_t stamp, int32_t w, uint32_t p)
00036         : signal(sig), channel(ch), tow(t), sample_stamp(stamp), wn(w), prn(p) {}
00037
00038     std::string signal;
00039     int32_t channel{0};
00040     uint32_t tow{0};
00041     uint64_t sample_stamp{0};
00042     int32_t wn{0};
00043     uint32_t prn{0};
00044 };
00045
00046 /** \} */
00047 /** \} */
00048 #endif // GNSS_SDR_TOW_TO_TRK_H
```


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